

MARINE RADAR FR-2115-B/FR-2125-B

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* IME34830H00 *



SAFETY INSTRUCTIONS

WARNING

Radio Frequency Radiation Hazard

The radar antenna emits electromagnetic radio frequency (RF) energy which can be harmful, particularly to your eyes. Never look directly into the antenna aperture from a close distance while the radar is in operation or expose yourself to the transmitting antenna at a close distance.

Distances at which RF radiation levels of 100 and 10 W/m² exist are given in the table below.

Note: If the antenna unit is installed at a close distance in front of the wheel house, your administration may require halt of transmission within a certain sector of antenna revolution. This is possible - ask your FURUNO representative or dealer to provide this feature.

Model	Radiator type	Distance to 100 W/m ² point	Distance to 10 W/m ² point
FR-2115-B	XN12AF	0.1 m	3.5 m
	XN20AF	0.1 m	3.5 m
	XN24AF	0.1 m	3.5 m
FR-2125-B	XN12AF	1.1 m	1.4 m
	XN20AF	1.1 m	10.0 m
	XN24AF	1.1 m	10.0 m

⚠ WARNING



ELECTRICAL SHOCK HAZARD

Do not open the equipment unless totally familiar with electrical circuits and service manual.

Only qualified personnel should work inside the equipment.



Wear a safety belt and hard hat when working on the antenna unit.

Serious injury or death can result if someone falls from the radar antenna mast.

Construct a suitable service platform from which to install the antenna unit.

Serious injury or death can result if someone falls from the radar antenna mast.

Turn off the power at the mains switchboard before beginning the installation.

Fire, electrical shock or serious injury can result if the power is left on or is applied while the equipment is being installed.

Do not install the display unit where it may get wet from rain or water splash.

Water in the display unit can result in fire, electrical shock or equipment damage.

⚠ WARNING

Be sure that the power supply is compatible with the voltage rating of the equipment.

Connection of an incorrect power supply can cause fire or equipment damage. The voltage rating of the equipment appears on the label above the power connector.

Use only the specified power cable.

Fire or equipment damage can result if a different cable is used.

⚠ CAUTION



Ground the equipment to prevent electrical shock and mutual interference.

Observe the following compass safe distances to prevent interference to a magnetic compass:

	Standard compass	Steering compass
Processor unit	1.70 m	0.90 m
Antenna unit (FR-2115-B)	1.70 m	0.90 m
Antenna unit (FR-2125-B)	2.10 m	1.20 m

EQUIPMENT LISTS

Standard supply (System with monitor)

Name	Type	Code No.	Qty	Remarks	
Antenna Unit	XN12AF-RSB-0074-062	–	1	FR-2115-B, 24 rpm, 1200 mm	CP03-24201
	XN12AF-RSB-0075-062	–		FR-2115-B, 42 rpm, 1200 mm	
	XN20AF-RSB-0074-062	–		FR-2115-B, 24 rpm, 2000 mm	CP03-19101
	XN20AF-RSB-0075-062	–		FR-2115-B, 42 rpm, 2000 mm	
	XN24AF-RSB-0074-062	–		FR-2115-B, 24 rpm, 2400 mm	
	XN24AF-RSB-0075-062	–		FR-2115-B, 42 rpm, 2400 mm	
	XN12AF-RSB-0074-063	–		FR-2125-B, 24 rpm, 1200 mm	CP03-24201
	XN12AF-RSB-0075-063	–		FR-2125-B, 42 rpm, 1200 mm	
	XN20AF-RSB-0074-063	–		FR-2125-B, 24 rpm, 2000 mm	CP03-19101
	XN20AF-RSB-0075-063	–		FR-2125-B, 42 rpm, 2000 mm	
	XN24AF-RSB-0074-063	–		FR-2125-B, 24 rpm, 2400 mm	
	XN24AF-RSB-0075-063	–		FR-2125-B, 42 rpm, 2400 mm	
Monitor	RDP-124-M-ES	–	1		
Control Unit	RCU-011	–	1		
Processor Unit	RPU-011	–	1		
Spare Parts	SP03-12500 (DC mains)	000-089-390	1 set	SP03-12501, SP03-12505	
	SP03-12510 (AC mains)	000-089-391		SP03-12501, SP03-12506	
Accessories	FP03-07410	000-089-584	1 set	FP03-07401: Accessories FP03-06201: Handle FP03-06502: Accessories FP03-06503: Hood Dust cover 03-144-1338	
Installation Materials	CP03-20400	000-089-748	Select one	CP03-19105: Monitor CP03-19104: Antenna Unit Signal Cable: S03-75-15 (15 m) Cable Assy: UL1007/2C-2V (10 m), for monitor	
	CP03-20410	000-089-749		CP03-19105: Monitor CP03-19104: Antenna Unit Signal Cable: S03-75-20 (20 m) Cable Assy: UL1007/2C-2V (10 m), for monitor	
	CP03-20420	000-089-750		CP03-19105: Monitor CP03-19104: Antenna Unit Signal Cable: S03-75-30 (30 m) Cable Assy: UL1007/2C-2V (10 m), for monitor	

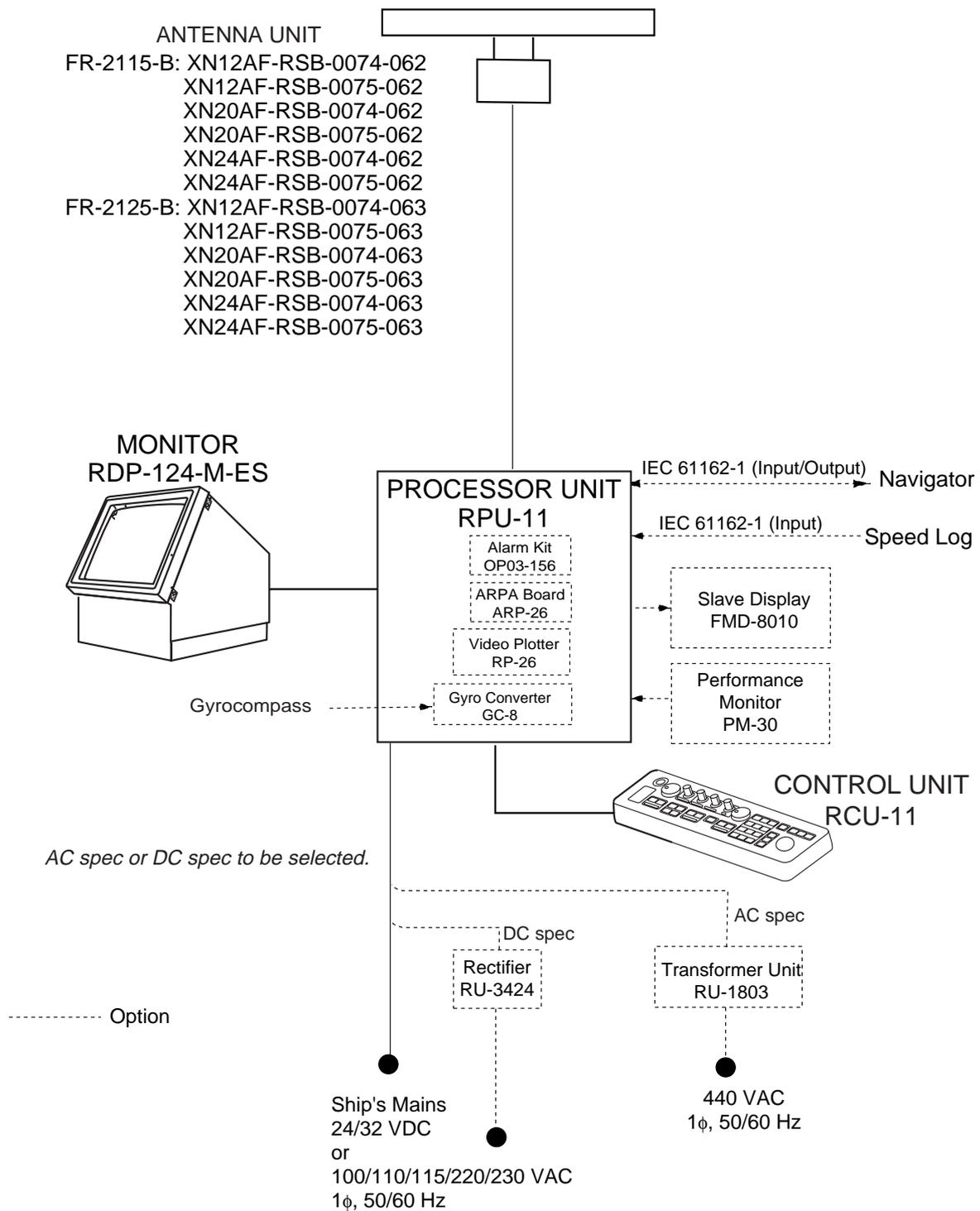
Standard supply (System without monitor)

Name	Type	Code No.	Qty	Remarks	
Antenna Unit	XN12AF-RSB-0074-062	–	1	FR-2115-B, 24 rpm, 1200 mm	CP03-24201
	XN12AF-RSB-0075-062	–		FR-2115-B, 42 rpm, 1200 mm	
	XN20AF-RSB-0074-062	–		FR-2115-B, 24 rpm, 2000 mm	CP03-19101
	XN20AF-RSB-0075-062	–		FR-2115-B, 42 rpm, 2000 mm	
	XN24AF-RSB-0074-062	–		FR-2115-B, 24 rpm, 2400 mm	
	XN24AF-RSB-0075-062	–		FR-2115-B, 42 rpm, 2400 mm	
	XN12AF-RSB-0074-063	–		FR-2125-B, 24 rpm, 1200 mm	CP03-24201
	XN12AF-RSB-0075-063	–		FR-2125-B, 42 rpm, 1200 mm	
	XN20AF-RSB-0074-063	–		FR-2125-B, 24 rpm, 2000 mm	CP03-19101
	XN20AF-RSB-0075-063	–		FR-2125-B, 42 rpm, 2000 mm	
	XN24AF-RSB-0074-063	–		FR-2125-B, 24 rpm, 2400 mm	
	XN24AF-RSB-0075-063	–		FR-2125-B, 42 rpm, 2400 mm	
Control Unit	RCU-011	–	1		
Processor Unit	RPU-011	–	1		
Spare Parts	SP03-12500 (DC mains)	000-089-390	1	SP03-12502, SP03-12505	
	SP03-12510 (AC mains)	000-089-391		SP03-12502, SP03-12506	
Accessories	FP03-07510	000-089-586	1	FP03-06502, FP03-07401	
Installation Materials	CP03-19100	000-089-393	Select one	CP03-19104: Antenna Unit CP03-19105: Monitor Signal Cable: S03-75-15 (15 m)	
	CP03-19110	000-089-394		CP03-19104: Antenna Unit CP03-19105: Monitor Signal Cable: S03-75-20 (20 m)	
	CP03-19120	000-089-395		CP03-19104: Antenna Unit CP03-19105: Monitor Signal Cable: S03-75-30 (30 m)	

Optional equipment

Name	Type	Code No	Qty	Remarks
Remote Display	FMD-8010	–	1	
Gyro Converter	GC-8-2	008-446-520	1 set	Separate order
	GC-8-1	008-446-270		Built in
Interswitch	RJ-7	–	1	
Interswitch	RJ-8	–	1	
Performance Monitor	PM-30	–	1	Mandatory for IMO radar
Transformer Unit	RU-1758	000-030-416	1	
	RU-1803	000-030-420	1	
Rectifier	RU-3424	000-030-497	1	
ARPA	ARP-26-1E	008-492-300	1	Built in
	ARP-26-2E	008-485-500	1	Separate order
Video Plotter	RP-26-Z-1E	008-492-520	1	Built in
Video Plotter	RP-26-Z-2E	008-485-520	1	Separate order
Alarm Kit	OP03-156	008-500-650	1	
Performance Monitor Inst. Kit	OP03-150	008-485-490	1	
Power Cable	CVV-S (8X2C)-15C	000-560-634	1	
AC-DC Conversion Kit	OP03-161-24	008-499-760	1	24 rpm antenna
	OP03-161-42	008-499-770	1	42 rpm antenna
Interface Unit	IF-2300	–	1	Mandatory for IMO radar

SYSTEM CONFIGURATION



I/O Data Sentences

Input: GGA, RMA, RMB, RMC, GLL, ZDA, VBW, VHW, VTG, MWV, VWT, VWR, VDR, DPT, DBT, DBS, MTW, BWR, BWC, WPT, RTE

Output: RAOSD, RARSD, RATTM

1. MOUNTING

1.1 Antenna Unit

1.1.1 Mounting considerations

- The antenna unit is generally installed either on top of the wheelhouse or on the radar mast, on a suitable platform. Locate the antenna unit where there is a good all-round view.
- No funnel, mast or derrick should be within the vertical beamwidth of the antenna in the bow direction, especially zero degrees $\pm 5^\circ$, to prevent blind sectors and false echoes on the radar picture.
- It is rarely possible to place the antenna unit where a completely clear view in all directions is available. Thus, you should determine the angular width and relative bearing of any shadow sectors for their influence on the radar at the first opportunity after fitting.
- Locate the antenna of a direction finder clear of the antenna unit to prevent interference to the direction finder. A separation of more than two meters is recommended.
- To lessen the chance of picking up electrical interference, avoid where possible routing the signal cable near other onboard electrical equipment. Also avoid running the cable in parallel with power cables.
- A magnetic compass will be affected if placed too close to the antenna unit. Observe the following compass safe distances to prevent deviation of a magnetic compass: Standard compass, 1.70 m (FR-2115-B), 2.10 m (FR-2125-B), Steering compass, 0.90 m (FR-2115-B), 1.20 m (FR-2125-B).
- Do not paint the radiator aperture, to ensure proper emission of the radar waves.
- The signal cable run between the antenna and the display is available in lengths of 15 m (standard), 20 m, and 30 m. Whatever length is used it must be unbroken; namely, no splicing allowed.
- The antenna base is made of cast aluminum. To prevent electrolytic corrosion of the antenna base, use the seal washers and corrosion-proof rubber mat.
- Deposits and fumes from a funnel or other exhaust vent can adversely affect the aerial performance and hot gases may distort the radiator portion. The antenna unit must not be mounted where the temperature is more than 70°C.
- Leave sufficient space around the unit for maintenance and servicing. See the antenna unit outline drawing for recommended maintenance space.

1.1.2 Assembling the antenna unit

The antenna unit consists of the antenna radiator and the antenna unit chassis, and they are packed separately. Fasten the antenna radiator to the antenna unit chassis as follows:

1. **For the XN20AF, XN24AF**, attach two guide pins to the underside of the antenna radiator.
2. Remove the waveguide cap from the radiator bracket. The cap may be discarded.
3. Coat the waveguide flange with anticorrosive sealant as shown in Figure 1-1.

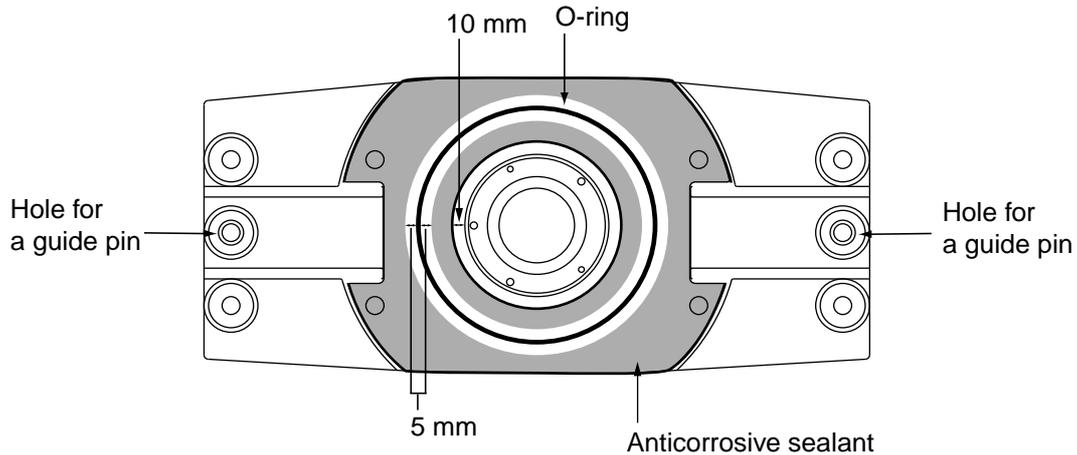
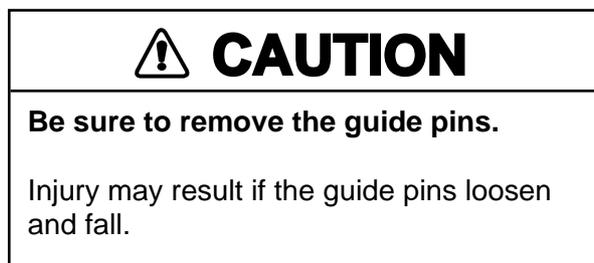


Figure 1-1 Coating the waveguide flange with anticorrosive sealant

4. Coat fixing holes for the antenna radiator with anticorrosive sealant.
5. Grease the O-ring and set it to the O-ring groove of the radiator flange.
6. Set the antenna radiator to the radiator bracket.
7. **For the XN20AF, XN24AF**, coat hex bolts (M8X40, slotted washer-head, 8 pcs.) with anticorrosive sealant and use them to loosely fasten the antenna radiator to the antenna unit chassis. For the XN12AF, coat hex bolts, flat washers and spring washers with anticorrosive sealant and use them to loosely fasten the antenna radiator to the antenna unit chassis.
8. **For the XN20AF, XN24AF**, remove two guide pins (inserted at step 1).
9. Tighten the bolts loosely fastened at step 7.



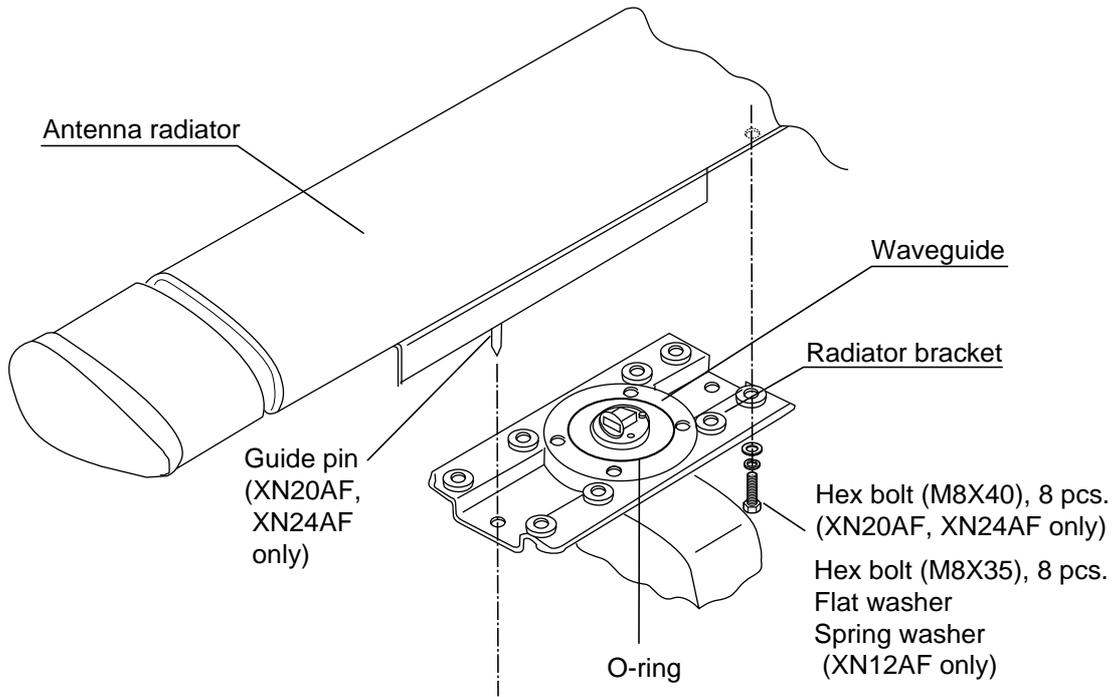
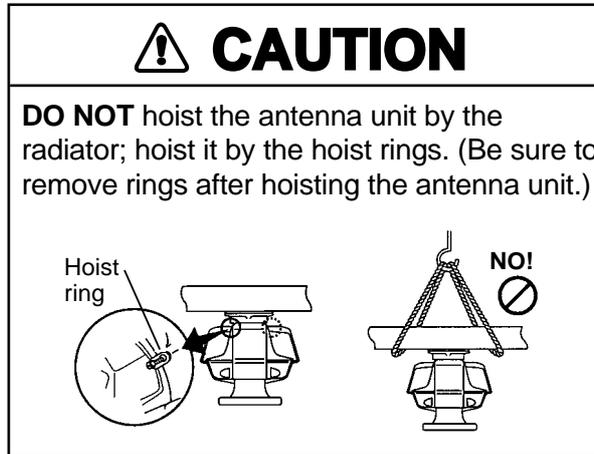


Figure 1-2 Fastening the radiator to the radiator bracket

1.1.3 Fastening the antenna unit to the mounting platform

The antenna unit may be assembled before hoisting it to the mounting platform. However, do not lift the antenna unit by the radiator. Always hold the unit by its housing. When using a crane or hoist, lift the unit by the hoist rings which should be fastened to the bolt fixing covers of the antenna housing.



1. Construct a suitable mounting platform referring to the outline drawing at the back of the manual.
2. Drill four mounting holes of 15 mm diameter and one cable entry hole of about 50 mm diameter in the mounting platform.
3. Lay the rubber mat (supplied) on the mounting platform.
4. Place the antenna unit on the rubber mat orienting the unit so the bow mark on its base is facing the ship's bow.

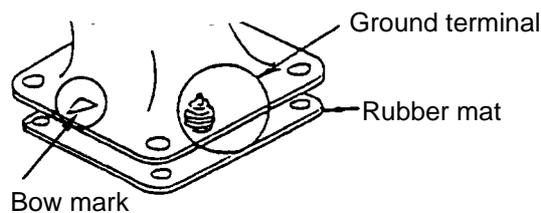
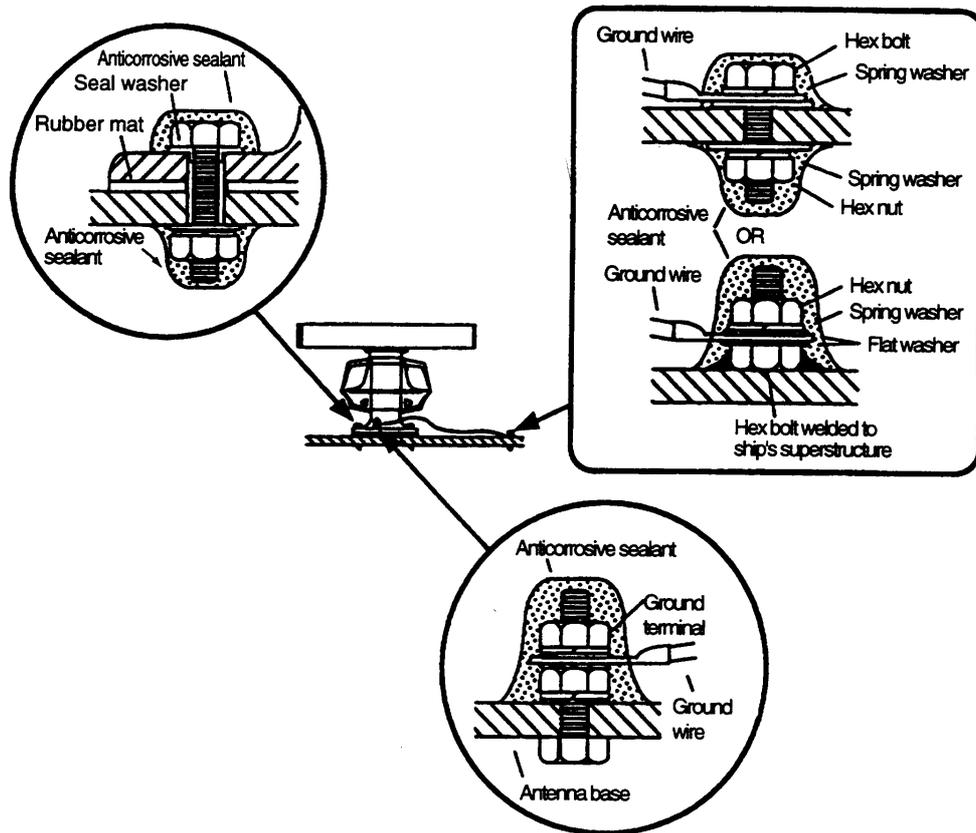


Figure 1-3 Antenna unit, front view

5. Fasten the antenna unit to the mounting platform with four sets of M12X60 hex bolts, nuts, flat washers and seal washers (supplied).
6. Using hex bolt (M6X25), nut (M6) and flat washer (M6), establish the ground system on the mounting platform as shown in Figure 1-4. The location should be within 370 mm of the ground terminal on the antenna unit. Connect the ground wire (RW-4747, 370 mm, supplied) between the grounding point and ground terminal on the antenna unit. Coat the entire ground system with silicone sealant (supplied).



	CAUTION
	Ground the equipment to prevent electrical shock and mutual interference.

Figure 1-4 How to mount the antenna unit

1.2 Processor Unit

1.2.1 Mounting considerations

When selecting a mounting location, keep in mind the following points:

- The processor unit must be mounted horizontally.
- DO NOT place any item on the top of the processor unit.
- Locate the unit out of direct sunlight and away from heat sources because of heat that can build up inside the cabinet.
- Locate the equipment away from places subject to water splash and rain.
- Be sure the mounting location is strong enough to support the weight of the unit under the continued vibration which is normally experienced on the ship. If necessary reinforce the mounting location.
- Determine the mounting location considering the length of the following cables:
 - a) Signal cable from the antenna unit
 - b) Power cable from the ship's mains
 - c) Monitor cable from the monitor
 - d) Control cable from the control unit
- Leave sufficient space on the sides and rear of the unit to facilitate maintenance. Also, leave a foot or so of "service loop" in cables behind the unit for servicing ease.
- A magnetic will be adversely affected if placed too close to the processor unit. Observe the following compass safety distances to prevent deviation of a magnetic compass: Standard compass, 1.70 m, Steering compass, 0.90 m.

1.2.2 Mounting the processor unit

1. Drill four holes of 12 mm in diameter in the mounting location.
2. Unfasten 15 binding screws (M4) to remove the processor unit cover.

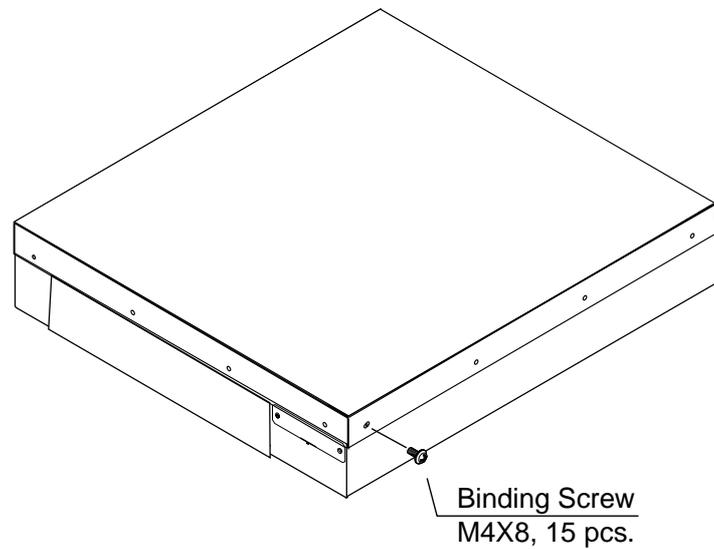


Figure 1-5 Processor unit

3. Fasten the processor unit to the mounting location with four each of M10 bolts, nuts and washers, using the pipe box spanner (supplied). See the figure on the next page for location of fixing holes.

How to access the rear-left fixing hole

The rear-left fixing hole is hidden under the PTU board cover. To access it do the following:

- a) Loosen five M3X8 screws at the top of the PTU board cover and two M4X8 screws at the front of the cover.
- b) Grasp the knob on the cover and slide the cover toward the front of the unit to release it.

How to access the front-right fixing hole

The front-right fixing hole is hidden beneath the RGB Board. To access it do the following:

- a) Unfasten the M4X8 pan-head screw from the RGB board mounting plate.
- b) Unfasten two pan-head screws (M3X10) fixing the M-card cover.

4. After mounting the unit, fasten the PTU board cover and RGB board mounting plate, and then close the processor unit.

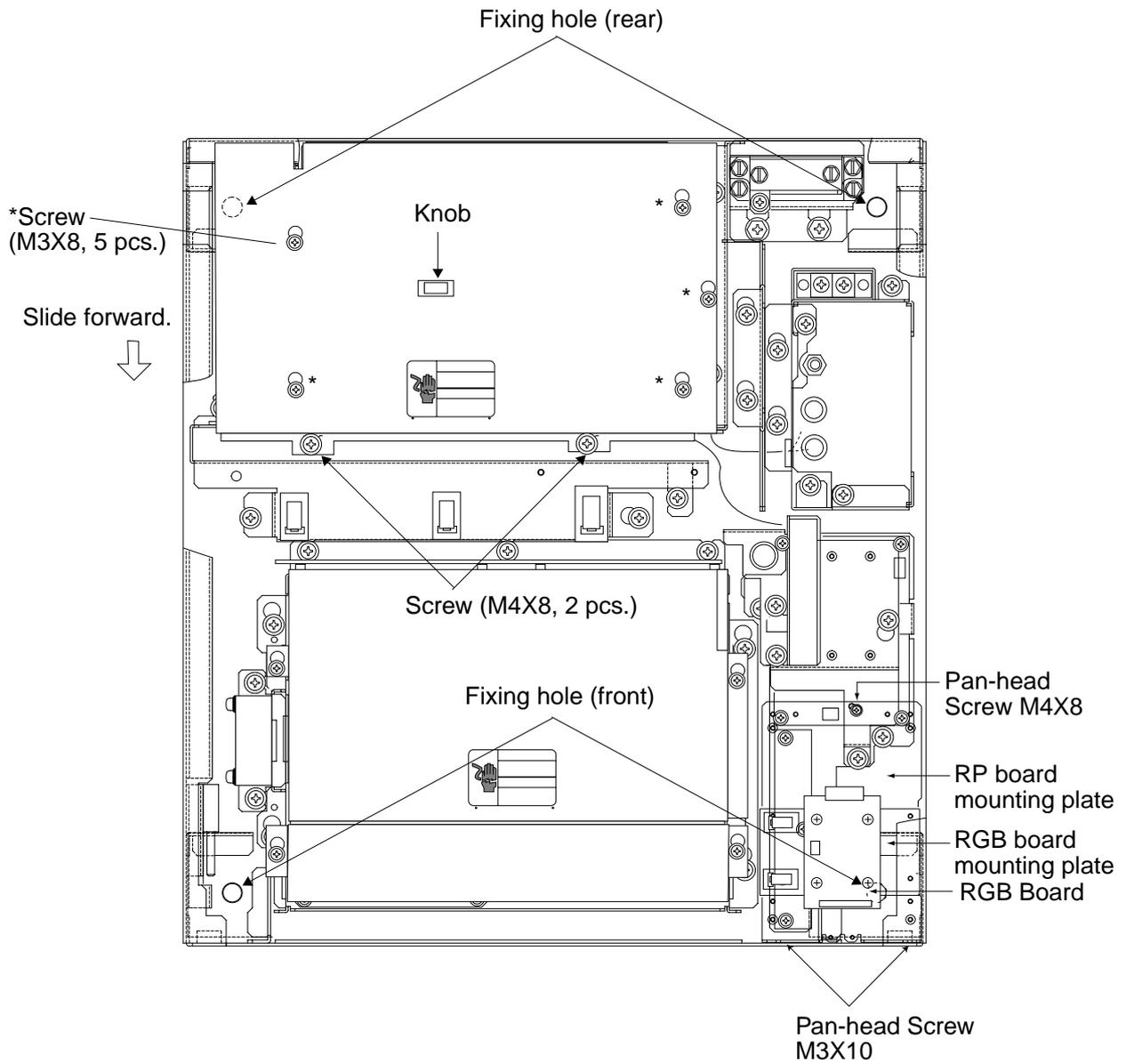


Figure 1-6 Processor unit, inside view

1.3 Monitor

The FR-2115-B/2125-B is available with or without a monitor. This section shows how to mount the monitor supplied.

Mounting considerations

- The monitor is designed to be mounted on a desktop.
- Locate the monitor where it can be easily operated while viewing the screen and operating the control unit.
- DO NOT place the monitor on the top of the processor unit.
- Locate the monitor out of direct sunlight and away from heat sources because of heat that can build up inside the cabinet.
- Locate the equipment away from places subject to water splash and rain.
- Be sure the mounting location is strong enough to support the weight of the unit under the continued vibration which is normally experienced on the ship. If necessary reinforce the mounting location.
- The length of the monitor cable which runs between the processor unit and the monitor is 10 m. Keep this distance in mind when selecting the mounting location for the monitor.
- Leave sufficient space on the sides and rear of the unit to facilitate maintenance.

1.3.2 Mounting the monitor

1. Drill four holes of 12 mm in diameter in the mounting location, referring to the outline drawing for mounting dimensions.
2. Unfasten two M4X10 screws to dismount the monitor cover.
3. Unfasten two sets of M10 bolts, plain washers and spring washers at the front of the monitor to separate the monitor from the mounting base.
4. Pull the monitor forward about 4 centimeters and then lift it from the mounting base.
5. Fasten the mounting base to the mounting location with M10 bolts, nuts and washers (local supply), using the pipe box wrench supplied. Make sure there is 3mm protrusion under the nut.
6. Lay the monitor on the top of the mounting base, making sure the rear pin on the monitor is mated with the slit in the mounting base. Fix the mounting base with the two sets of bolts, and washers unfastened at step 3.
7. Fasten the monitor cover.

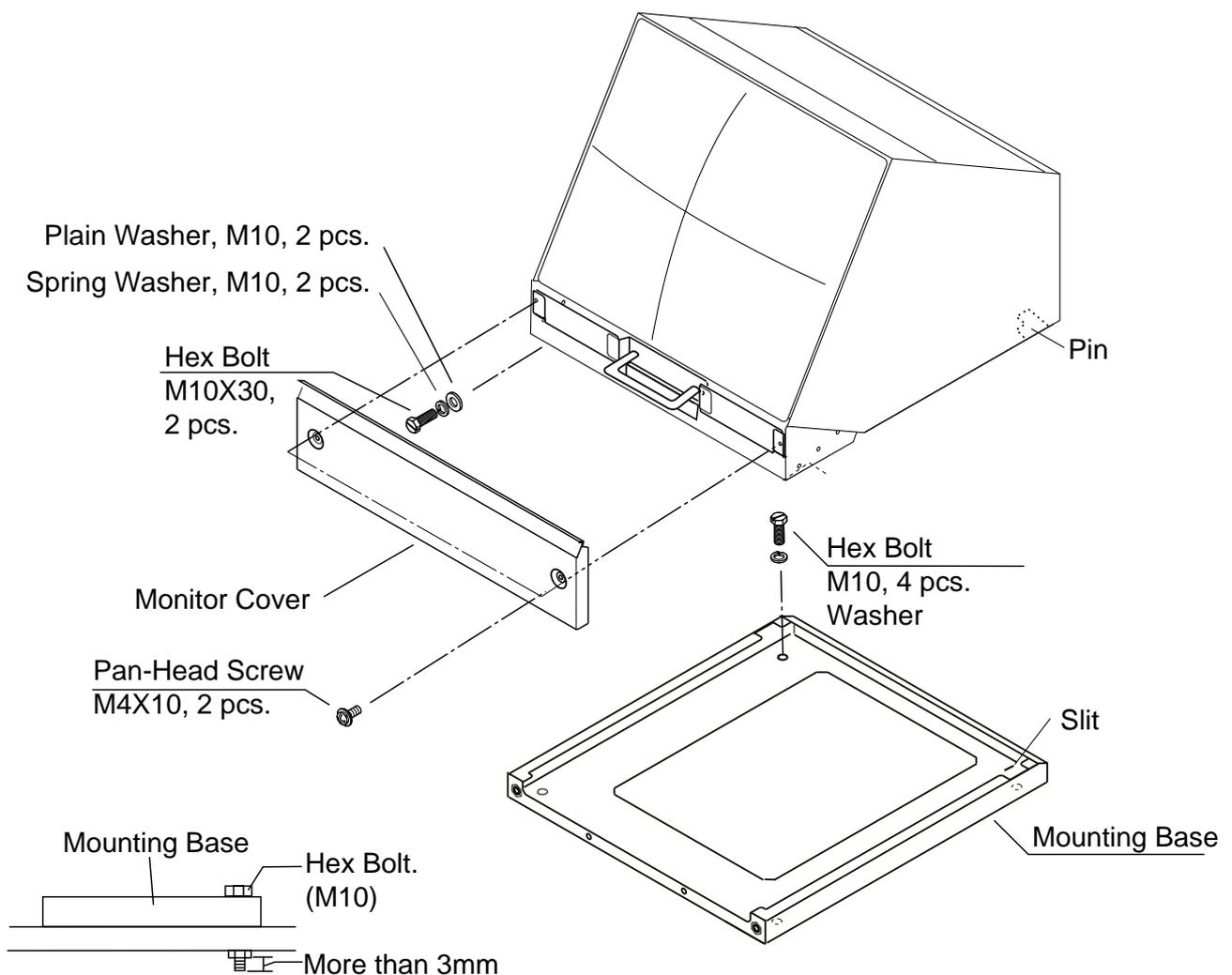


Figure 1-7 Monitor

1.4 Control Unit

1.4.1 Mounting procedure

1. Attach rubber to feet to the bottom of the keyboard if the keyboard is not going to be permanently fixed. To fix the keyboard to a desired location, fasten the KB fixing plate to the keyboard and desired location with two upset screws (M5X10, supplied) and two tapping screws ($\phi 6.5$, local supply) as below.

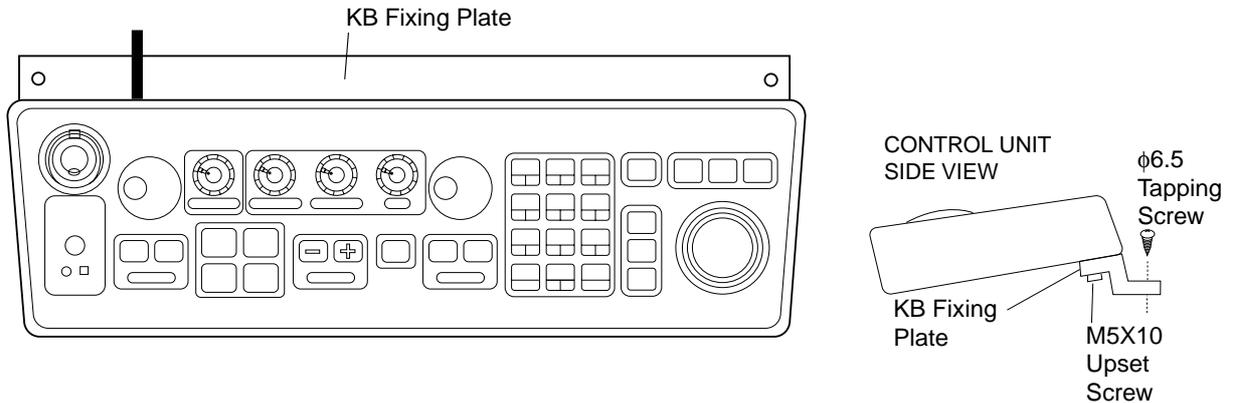
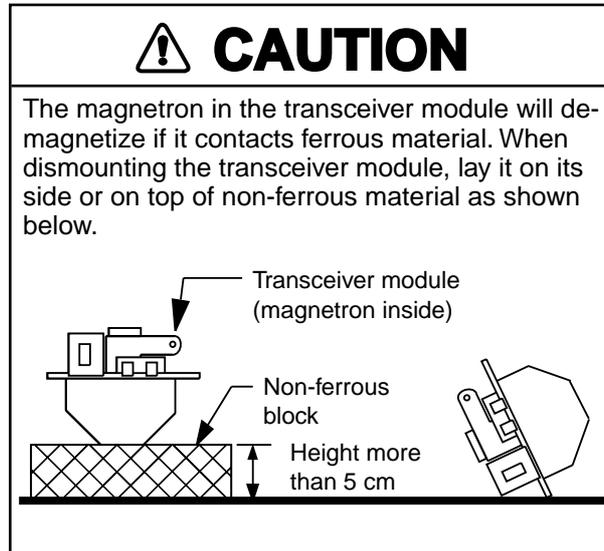


Figure 1-8 How to attach KB fixing plate

2. Set KB dust cover (supplied) to the control unit.

2. WIRING

2.1 Antenna Unit



2.1.1 Mounting the antenna chassis

1. Open the antenna unit cover.
2. Disconnect plugs P611, P801 and P821 from the antenna unit.
3. Unfasten two bolts to dismount the transceiver module.

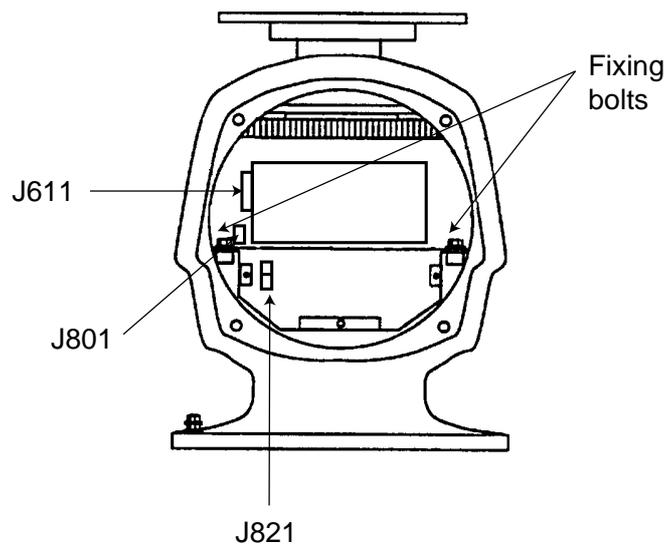


Figure 2-1 Antenna unit, front view

4. Unfasten the four fixing bolts on the cable gland at the base of the antenna unit. Remove clamping ring, rubber gasket and washers.

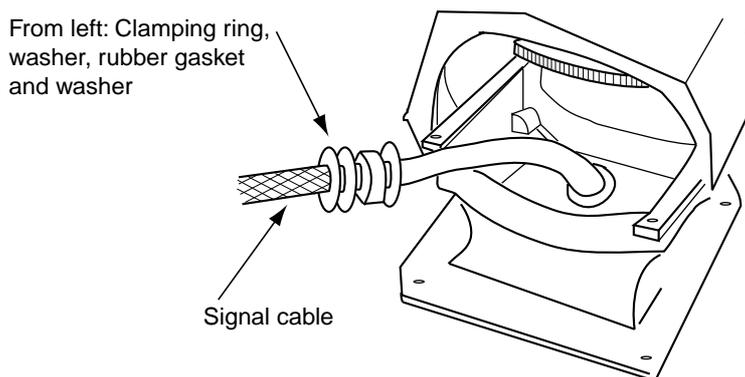


Figure 2-2 Antenna unit, front view, cover removed

5. Pass the signal cable through the cable entry hole in the antenna unit mounting platform. Trim the cable so about 80 cm of it protrudes past the cable gland.
6. Slide the clamping ring, washer, rubber gasket and washer onto the cable in that order.
7. Fabricate the signal cable as shown on page 2-4.
8. Referring to Figure 2-3, pass the outer and inner shields between the signal cable and the clamping ring. Fasten the cable gland.

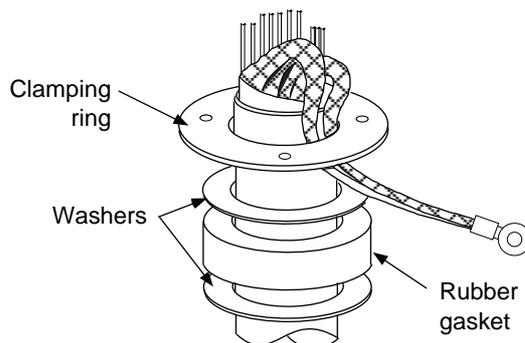


Figure 2-3 Passing cable shields between cable and clamping ring

9. Connect the signal cable to the terminal board RTB801 by referring to the interconnection diagram. Leave slack in the coaxial wire to prevent breakage.
10. Bind cores of cables with cable ties.
11. Mount the transceiver module. Connect plugs P611, P801 and P821. Fasten the shield to the ground terminal on the transceiver module.

12. If the antenna is mounted 2° or more left of ship's bow, adjust the position of S901 so it becomes "on" (contact between #1 and #2 on pcb MP-3795). To access S901, open the bow side cover; S901 is above the drive gear.

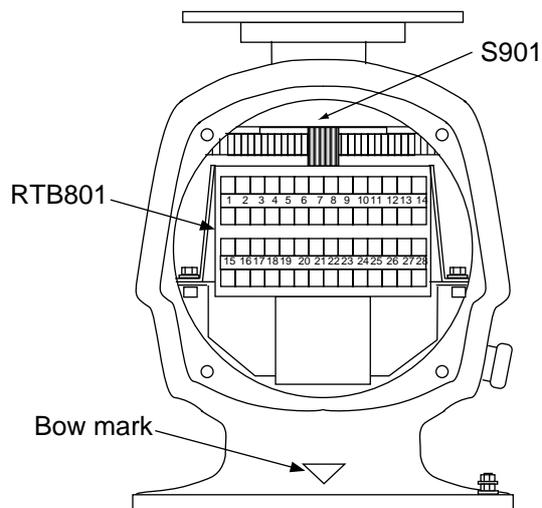


Figure 2-4 Antenna unit, front view

13. Confirm that all screws are tightened and all wiring is properly made. Coat waterproofing gasket, bolts and tapping holes of antenna unit with silicone grease. Check that the waterproofing gasket is seated as shown in Figure 2-5. Close the antenna unit cover.

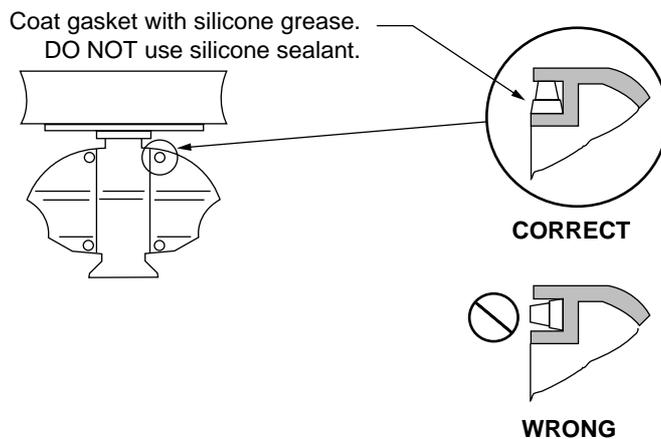


Figure 2-5 Correct seating of waterproofing gasket

2.1.2 Fabricating signal cable S03-75

1. Remove the vinyl sheath by 450 mm.
2. Slide the clamping ring, washer, rubber gasket and washer onto the signal cable in that order.
3. Unravel the outer shield to expose the cores in the outer layer. Then, unravel the inner shield to expose the cores in the inner layer. Label all inner cores to aid in identification.
4. Attach EMI cores to all inner cores and all outer cores, and bind them with cable ties, etc. Note that there are two types of the EMI cores, thick and thin.
5. Trim each core (except coaxial wire) considering its location on the terminal board in the antenna unit.
6. Trim the inner and outer shields leaving 500 mm each. Twist shields together and attach crimp-on lug FV5.5-4 (blue, $\phi 4$).
7. Remove insulation of each core by about 6 mm. Fix crimp-on lug FV1.25-3 (red, $\phi 3$) to each core.
8. Fabricate the coaxial cable. Make the length 10 mm longer than the shield to prevent wire strain. Attach crimp-on lug FVD1.25-3 (red, $\phi 3$) to coaxial cable.

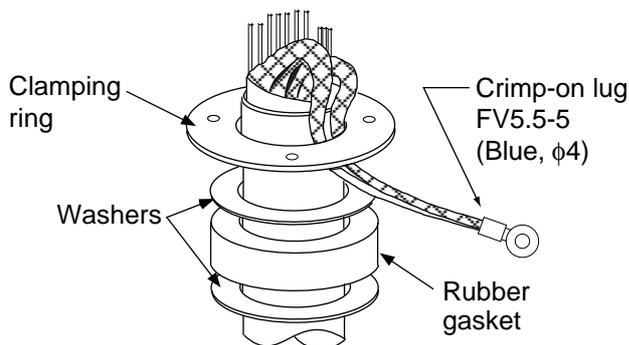
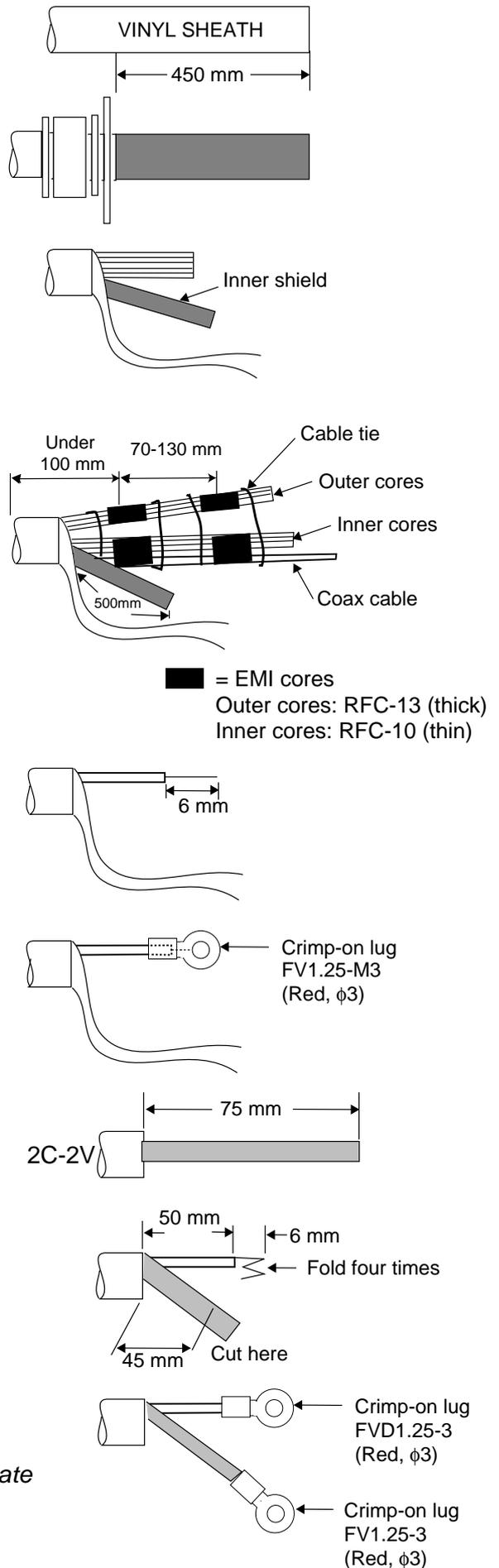


Figure 2-7 How to ground signal cable S03-75

Figure 2-6 How to fabricate signal cable S03-75



2.2 Processor Unit

Two cables are terminated at the processor unit: the signal cable S03-75 and the power cable. The signal cable comes with a connector preattached to it for connection to the processor unit. Fabricate the power cable as below.

2.2.1 Fabricating the AC power cable

1. Remove the vinyl sheath by 80 mm. Cut off jute tape wrapped around the armor. Unravel the armor to expose the cores by about 35 mm.
2. Remove insulation of cores by about 10 mm. Fix crimp-on lugs to the cores and armor.
3. Cover the armor with vinyl tape, leaving the portion which will lie inside the cable clamp untaped.

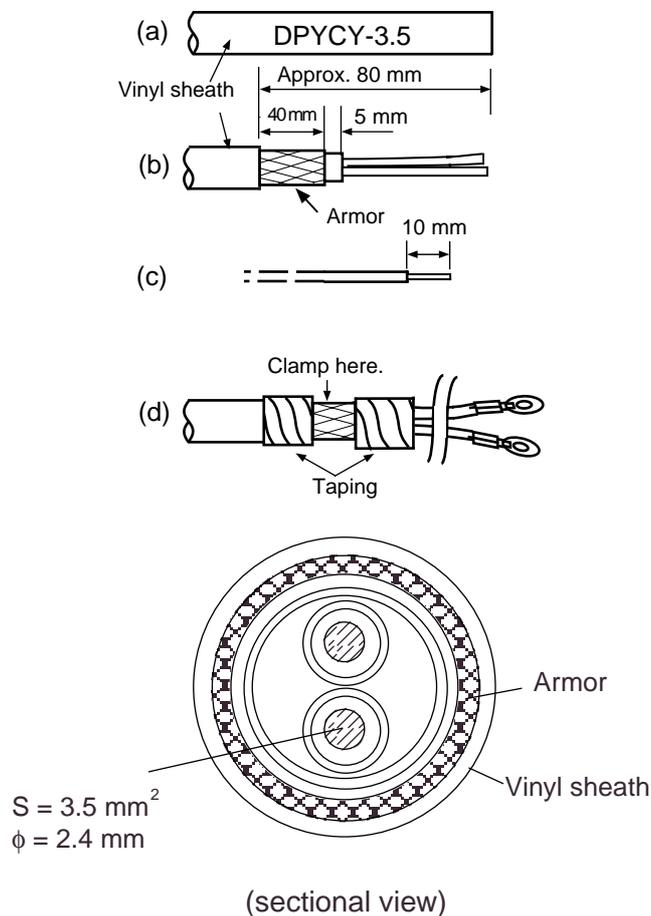


Figure 2-8 Fabricating power cable DPYCY-3.5

2.2.2 Fabricating the DC power cable (CVV-S 8X2C, option)

1. Remove the vinyl sheath by 100 mm.
2. Unravel the braided shield 60 mm from end of cable.
3. Remove the jute tape and inclusion from cable.
4. Expose the cores by 50 mm.
5. Expose the shield by 60 mm. Tape the shield, leaving 10 mm exposed.
6. Remove the sheath of cores by 10 mm. Attach crimp-on lug type 8NK4 to the cores and crimp-on lug type FV5.5-4 (yellow) to the shield.
7. Tape the cable as shown in the figure below. Fasten the shield to screw (M4) on the cable clamp.

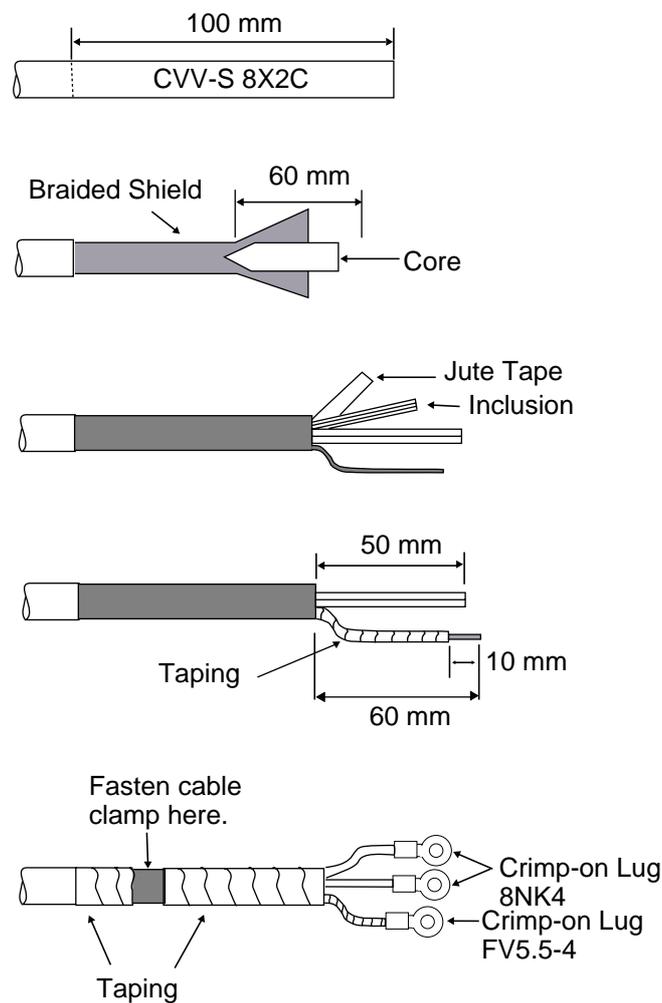


Figure 2-9 Fabricating power cable CVV-S 8X2C

2.2.3 Leading in cables to the processor unit

Cables are led in to the processor unit through the cable clamp at the rear of the unit. Use the shielding foam (supplied) as below to protect against noise radiation.

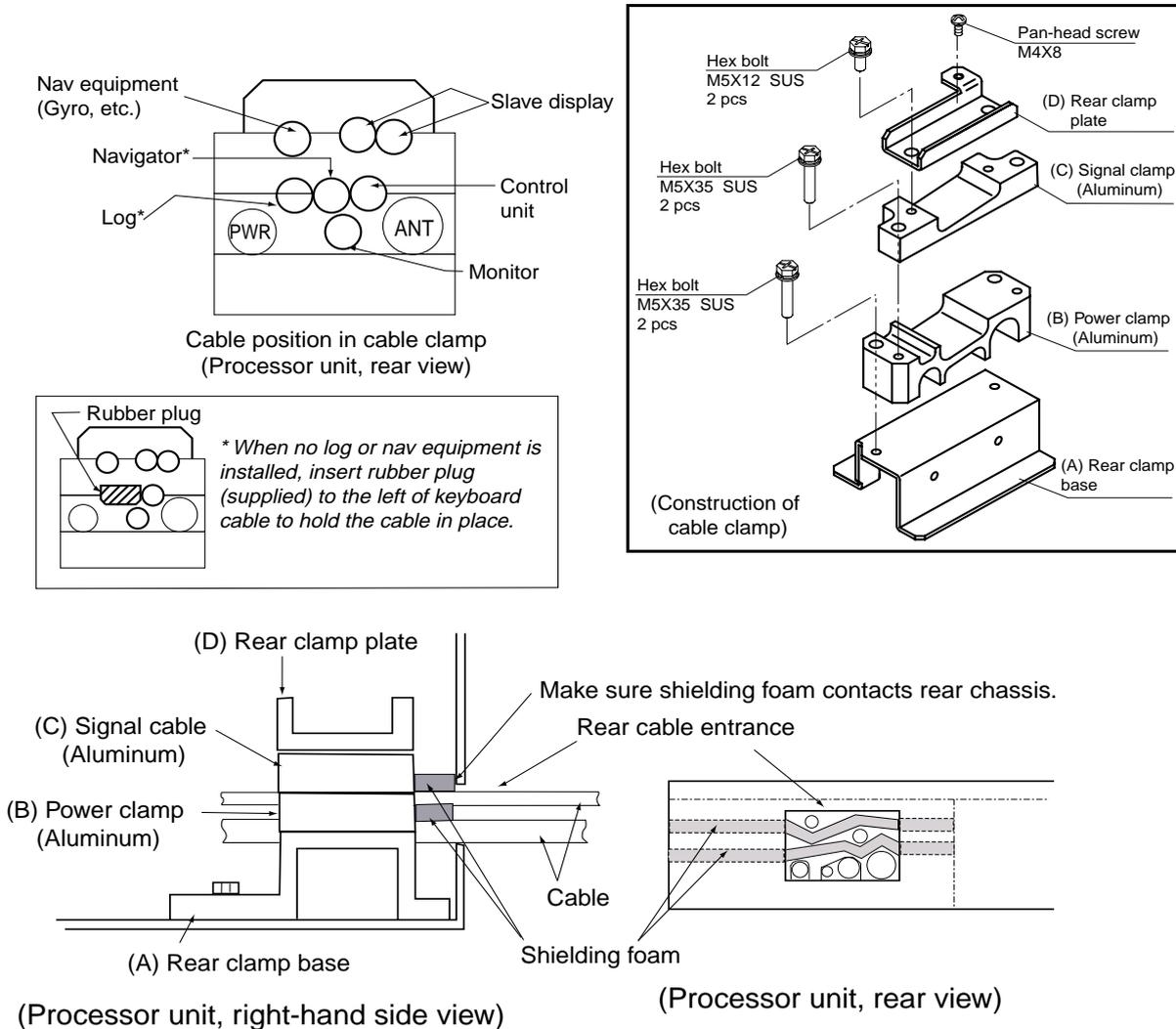
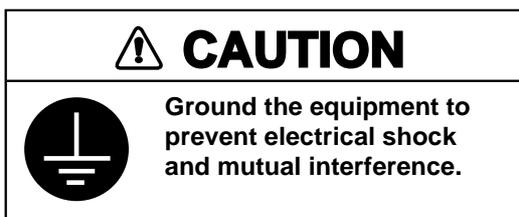


Figure 2-10 Cable clamp position

- Place shielding foam between cables, and then attach foam to aluminum clamps.
- Fill unused clamp holes with shielding foam.
- Connect a ground wire between the earth terminal on the processor unit and ship's superstructure.



2.3 Monitor

2.3.1 Connection of monitor cable inside processor unit

The monitor cable (a monitor cable comes with FURUNO-supplied monitor) runs between the RGB Board (inside the processor unit) and the monitor. Route it inside the processor unit as below. Connect the cable to J2 on the RGB Board. If a converter adaptor is used it may be necessary to route the cable differently than shown. In any case be sure the cable does not touch the TX-HV Board.

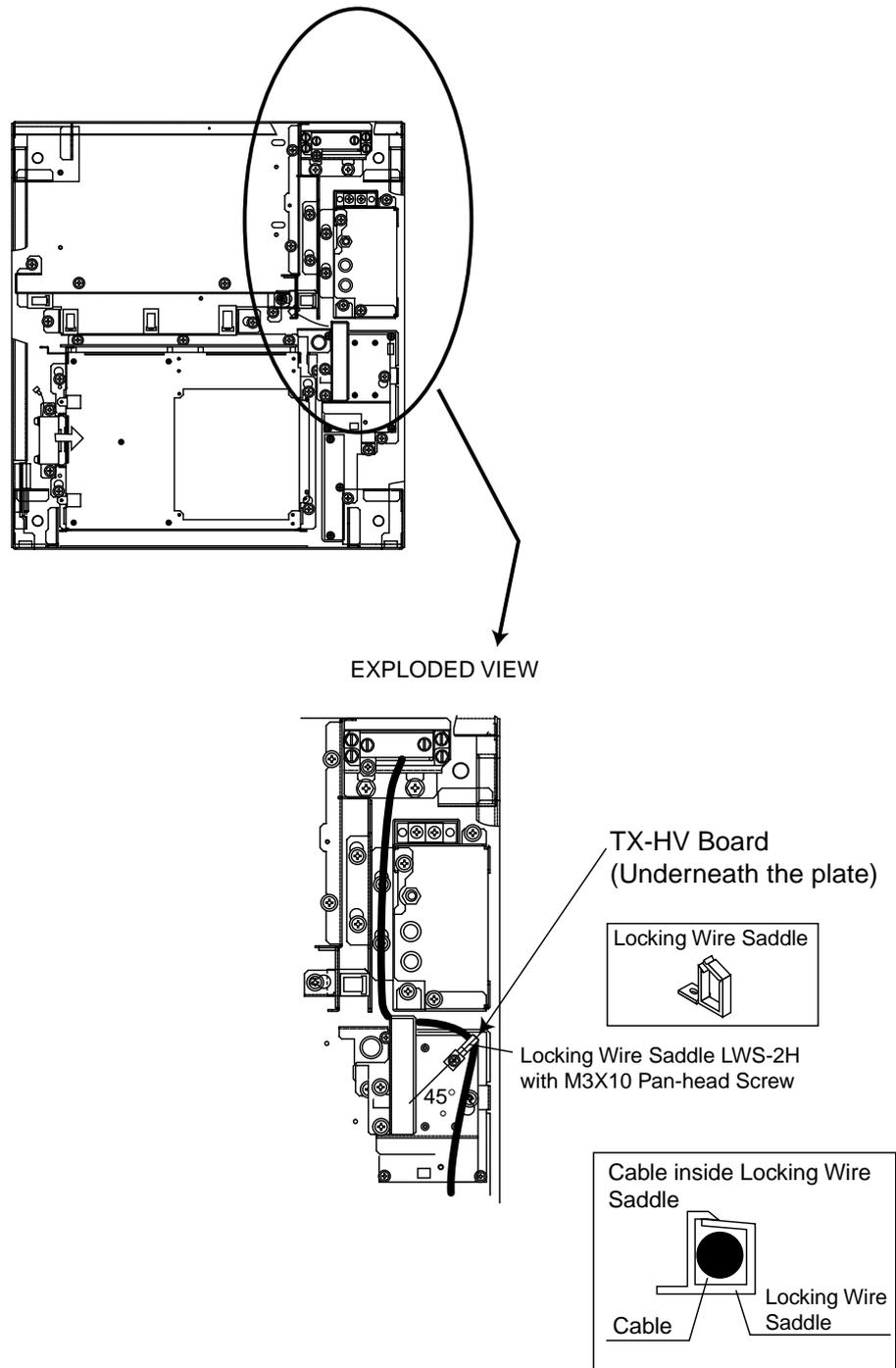


Figure 2-11 Processor unit, inside view

2.3.2 Connection of monitor cable inside the monitor

Connect the monitor cable inside the monitor as below.

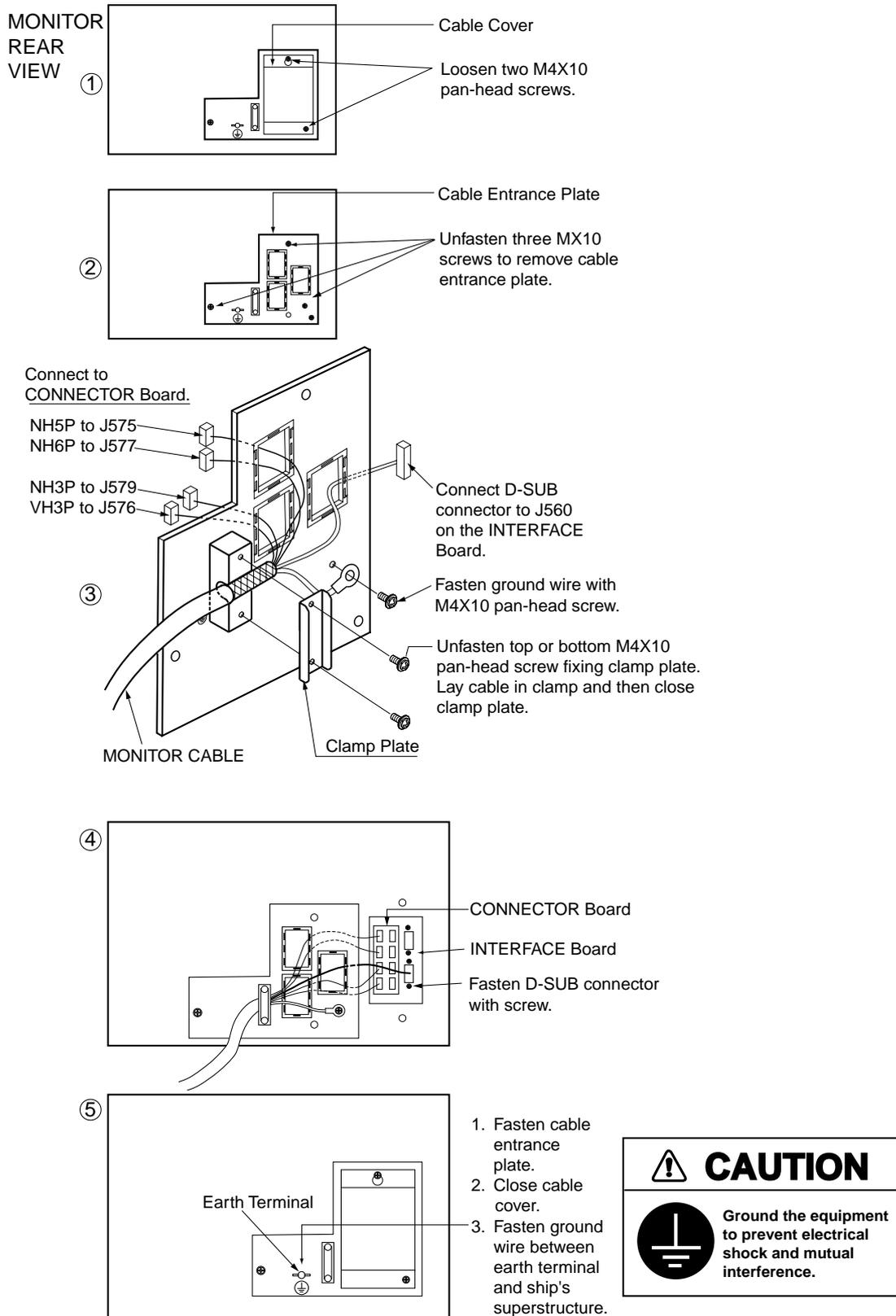


Figure 2-12 Connection of monitor

2.4 Control Unit

1. Open the processor unit.
2. Lead in the control unit cable assy. (option) from the rear entrance of the processor unit.
3. Inside the processor unit, fasten ground the wire of the cable assembly with an M4 screw on the chassis.
4. Plug in two connectors of control unit cable to P412 and J583.

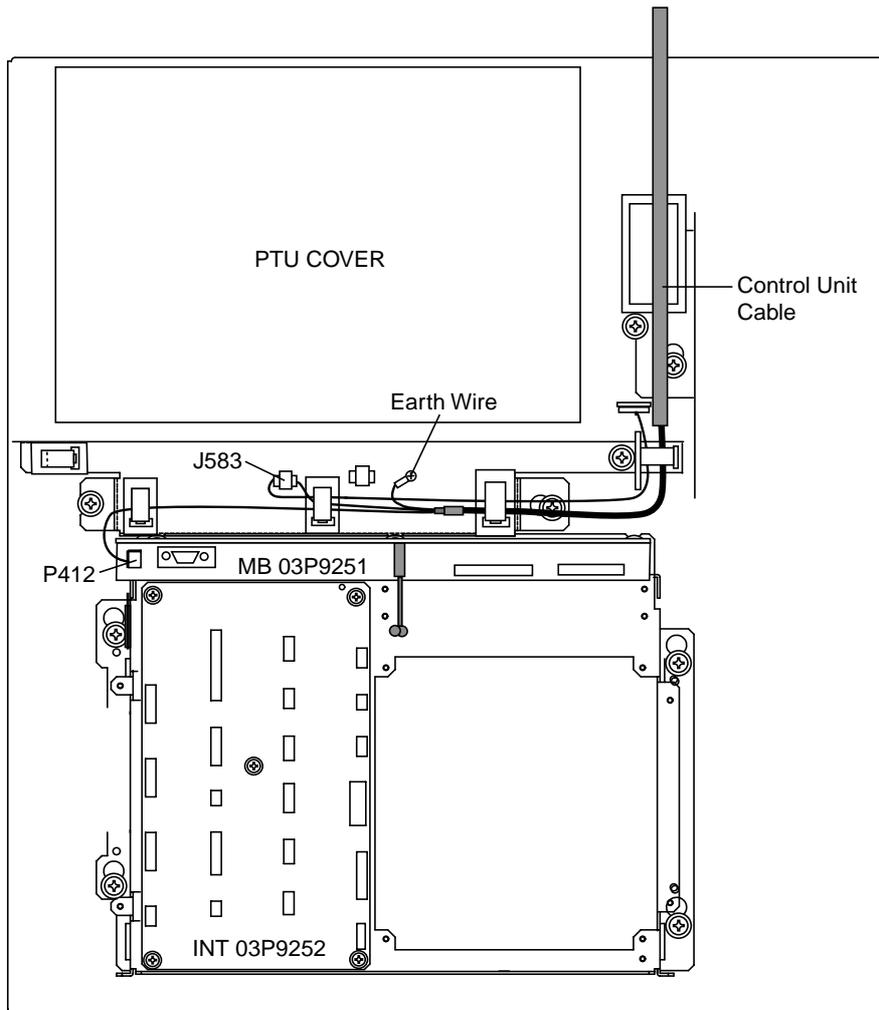


Figure 2-13 Processor unit, inside view

2.5 External Equipment

Open the processor unit. Remove the cover from the INT Board. Connect signal, power (ship's mains and power supply), gyro, log and monitor cables as below. Optional equipment are connected to the INT Board - see the next page for information.

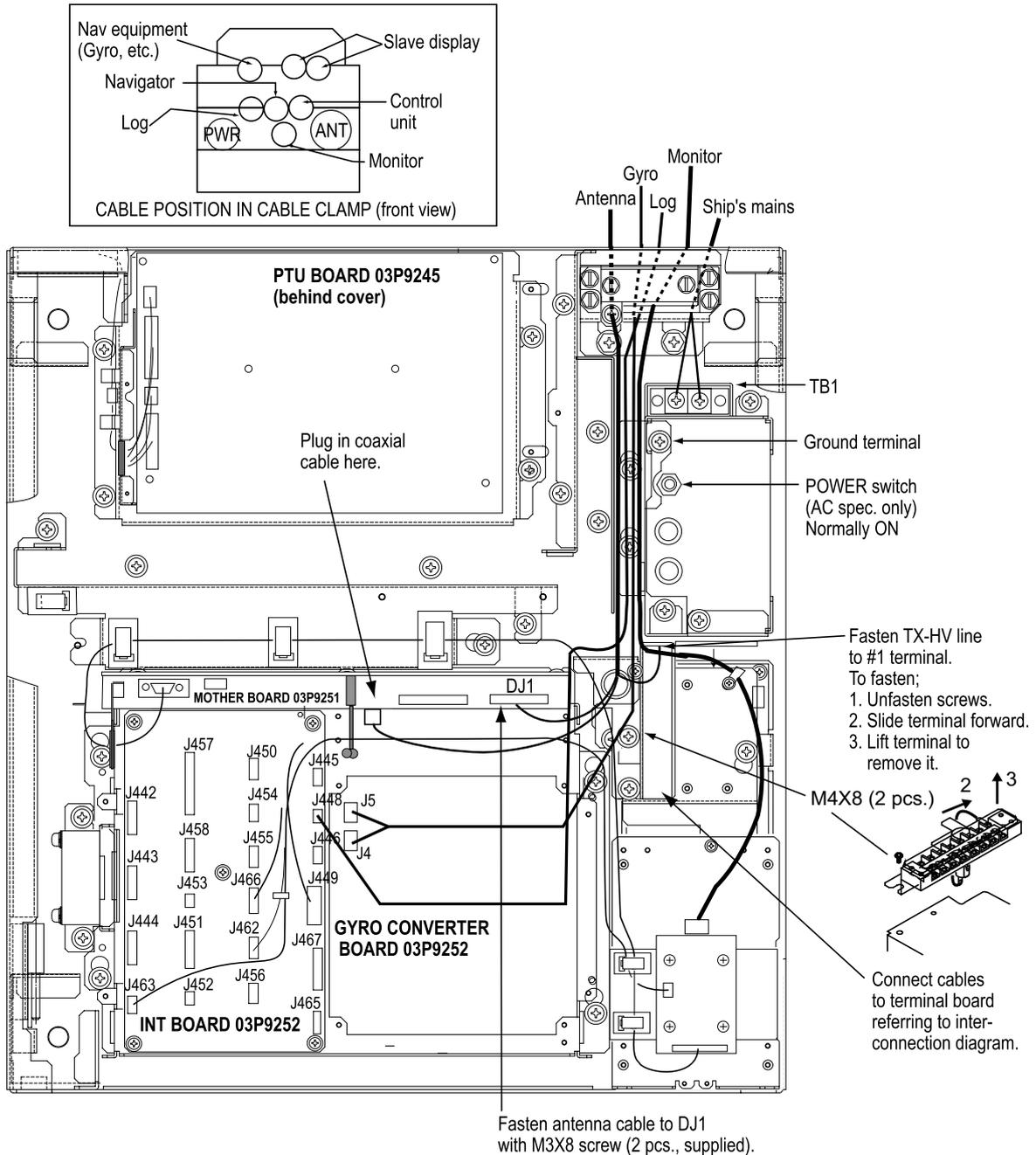


Figure 2-14 Processor unit, inside view

Connectors on the INT Board

Table 2-1 Connectors on the INT Board

Signal Name	Name on PCB	Connector No.	Connector Type	Applicable Equipment	Remarks
INPUT SIGNAL					
Gyro signal		J4	VH, 3 pin		On pcb A64P1106 (option)
		J5	VH, 5 pin		
Speed log signal	LOG	J448	NH, 3 pin		200 pulses/nm, etc.
Radar buoy signal	RADAR BUOY	J445	NH, 4 pin		
Remote display signal	EXT-RADAR or RJ-7	J458	NH, 8 pin		
OUTPUT SIGNAL					
External ARPA signal	EXT-ARPA	J444	NH, 8 pin		Heading, bearing, Tx trigger
Slave display signal	SLAVE	J442 J443	NH, 8 pin	CD-140, CD-141, GD-500, GD-500MK2, FMD-800, FMD-8010 *1	Heading, bearing, video, Tx trigger
Buzzer signal	EXT-BUZ	J451	NH, 9 pin	Speaker w/amp	Speaker signal
Monitor signal		J449	NH, 10 pin		VER synchronous, HOR synchronous, video
RS-232C	RS-232C	J456	XH, 4 pin		
Analog	ANALOG	J453	NH, 3 pin		
External buzzer	EXT ALARM (AC)	J452	NH, 3 pin		
INPUT/OUTPUT SIGNAL					
INS Data	INS. DATA	J455	NH, 5 pin		
RJ-7	RJ-7	J457	NH, 15 pin		
RJ-8	RJ-8	J416	NH, 4 pin		On Mother Board 03P9251
Nav data	NAV DATA	J450	NH, 5 pin		
ARPA data	ARPA DATA	J454	NH, 5 pin		
PM_ON_OFF	PM_PRINT	J411	XH, 3 pin		On Mother Board 03P9251

How to attach NH connector

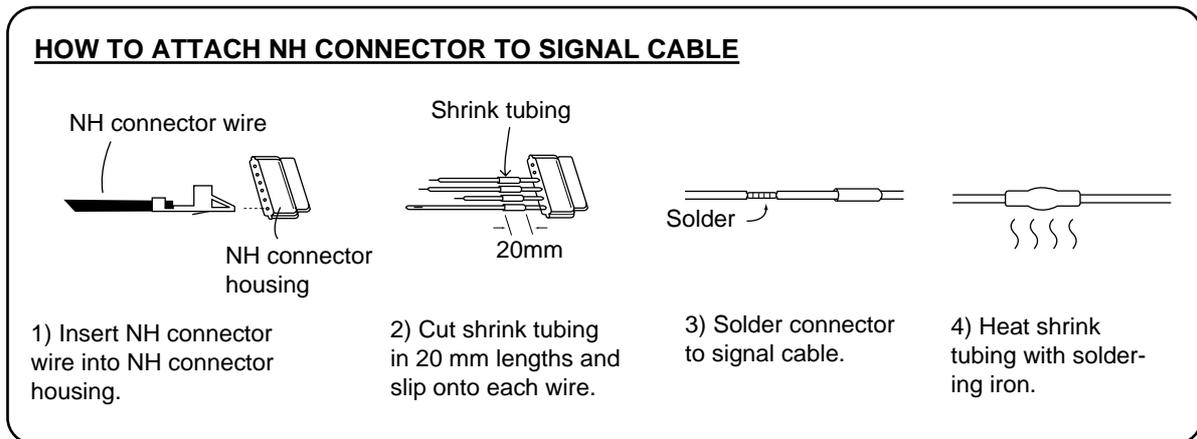


Figure 2-15 How to attach NH connector

2.6 AC Power Specification of Processor Unit

For 100 VAC or 220 VAC power, add or delete jumper wires on the PTU Board and change the power fuses inside the processor unit as shown in the table below according to ship's mains. The figure below shows the location of the power fuses and the jumper wires on the PTU Board.

Table 2-2 Jumper wire setting on the PTU board, fuse rating and power specification

PCB	Power Spec. (VAC)	Antenna rpm	JP1	JP2	JP3	JP4	JP91	JP92	Power Fuse
03P9245A	100/110/115	24 rpm	YES	YES	YES	NO	NO	NO	10A
03P9245D	220/230	24 rpm	NO	NO	NO	YES	NO	NO	5A

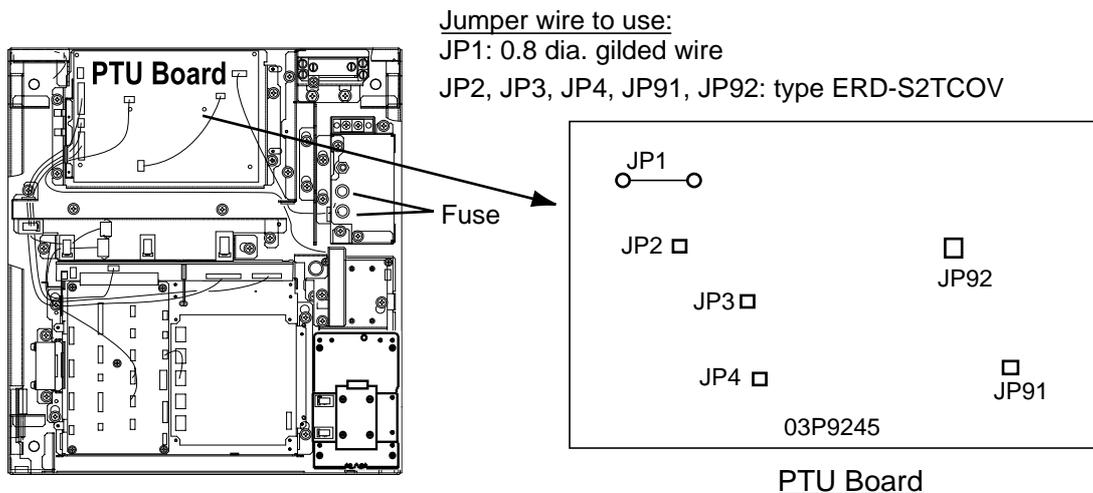


Figure 2-16 Processor unit, inside view

3. INITIALIZATION AND ADJUSTMENT

3.1 Tuning Initialization

Tune the radar as follows: Press [RADAR MENU] [0] [0] [2] [0] [0] [0] [0] (TUNE INITIALIZE on RADAR 3 menu) and press the [ENT] key. Also, confirm that "2.MODEL" is set to "FR-2115, 2125" on the INITIAL SETTING 4 menu, following paragraph 3.2 and then pressing [RADAR MENU], [0], [0], [0], [2], [0], [0], [0]. Trouble may result if the setting is wrong.

3.2 Accessing Menus for Initialization and Adjustment

1. Turn on the power.
2. Press the [RADAR MENU] key five times while pressing and holding down the [HL OFF] key.

3.2.1 Restoring default settings

1. Press [RADAR MENU] [0] [0] [0] [2] [0] [0] [0] to display the INITIAL SETTING 4 menu.
2. Press the [0] key to select FACTORY DEFAULT.
3. Press the [ENTER] key five times, and turn the power off and on again.
4. "Initializing" appears during restoring. It takes about 90 seconds to restore the default settings, after which the normal display appears. Confirm that "2.MODEL" is set to "FR-2115, 2125" on the INITIAL SETTING 4 menu.

3.3 Adjusting Video Signal Level

When the signal cable is very long, the video amplifier input level decreases, shrinking target echoes. To prevent this, confirm (and adjust if necessary) video amplifier input level.

1. Connect an oscilloscope to TP6 on the INT Board (03P9252) in the processor unit.
2. Transmit on the 12 nm range.
3. Adjust R21 on the INT Board so the value of TP6 is 4 Vpp. (For remote display, adjust R134 on the INT Board.)

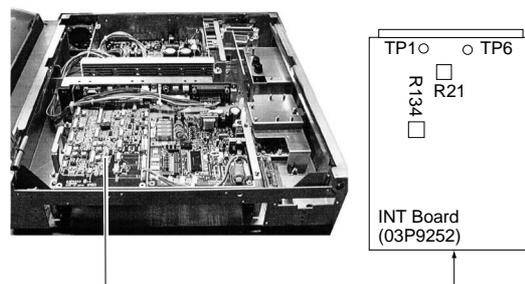


Figure 3-1 Processor unit, cover opened

3.4 Heading Alignment

You have mounted the antenna unit facing straight ahead in the direction of the bow. Therefore, a small but conspicuous target dead ahead visually should appear on the heading line (zero degrees).

In practice, you will probably observe some small bearing error on the display because of the difficulty in achieving accurate initial positioning of the antenna unit. The following adjustment will compensate for this error.

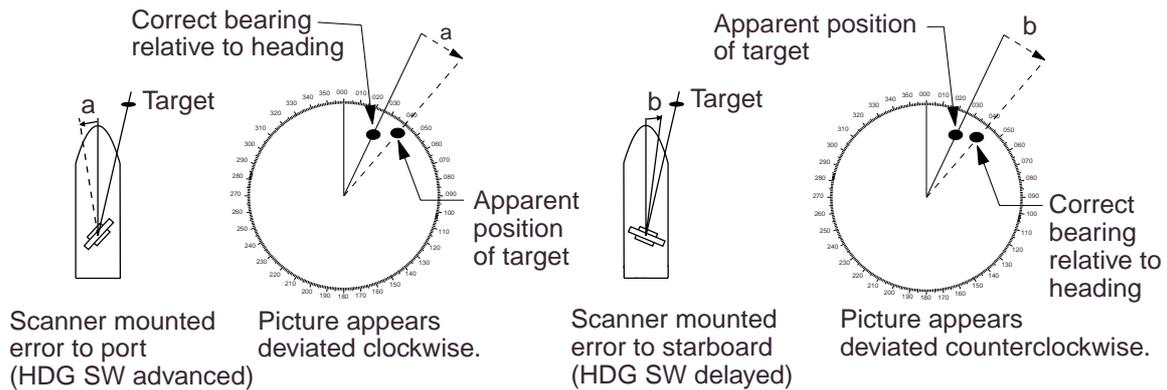


Figure 3-2 Heading alignment

1. Turn on the power. Press [RADAR MENU] [0] [0] [0] [2] [2] to select HL ALIGN on the INITIAL SETTING1 menu.
2. Select a target echo (by gyrocompass, for example) at a range between 0.125 and 0.25 nm, preferably near the heading line.
3. Operate the EBL control to bisect the target echo with the heading line. (The value shown on the display is scanner position in relation to ship's bow.)
4. Press [ENTER] to finish.

3.5 Adjusting Sweep Timing

Sweep timing differs with respect to the length of the signal cable between the antenna unit and the processor unit. Adjust sweep timing at installation to prevent the following symptoms:

- The echo of a "straight" target (for example, pier), on the 0.25 nm range, will appear on the display as being pulled inward or pushed outward. See Figure 3-3.
- The range of target echoes will also be incorrectly shown.

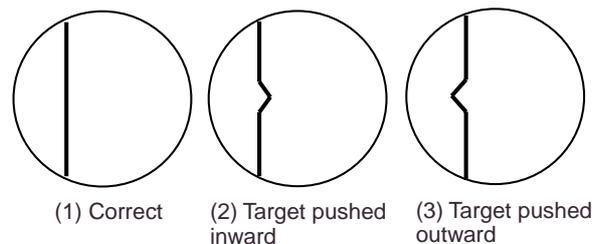


Figure 3-3 Examples of correct and incorrect sweep timings

1. Turn on the power. Press [RADAR MENU] [0] [0] [0] [2] [3] to select TIMING ADJ on the INITIAL SETTING1 menu.
2. Transmit on the 0.25 nm range.
3. Adjust radar picture controls to display picture properly.
4. Select a target echo which should be displayed straightly.
5. Adjust the VRM control to straighten the target echo.
6. Press [ENTER].

3.6 Suppressing Main Bang

If main bang appears at the screen center, suppress it as follows:

1. Turn on the power. Transmit on a long range and then wait ten minutes.
2. Adjust [GAIN] control to show a slight amount of noise on the display.
3. Select the 0.25 nm range. Adjust the [A/C SEA] control to suppress sea clutter.
4. Press [RADAR MENU] [0] [0] [0] [2] to open the INITIAL SETTING1 menu.
5. Press [7] to select 7. MBS.
6. Adjust the VRM control to adjust timing; the EBL control to adjust level.
7. Press [ENTER].

3.7 Confirming Magnetron Heater Voltage

Magnetron heater voltage is adjusted at the factory. However, confirm that it is within the prescribed rating.

Table 3-1 Magnetron heater voltage rating

Rating	FR-2115-B (12 kW)	FR-2125-B (25 kW)
ST-BY, 0.125 nm	7.4 to 7.6 V	8.2 to 8.4 V
TX, max range	7.4 to 7.6 V	6.5 to 7.5 V

1. Press [RADAR MENU] [0] [0] [0] [2] [0] to open the INITIAL SETTING2 menu.
2. Press [5] to select both the 5. SCANNER STOPPED field and the TX option and press [ENTER]. Disconnect connector P821 from the antenna unit.
3. Turn off screen brilliance.
4. Measure voltage between pins #12(+) and #5(-) on connector P801 on the RFC Board (03P9243) in the antenna unit.
5. If the voltage is not within the rating shown in Table 3-1, adjust potentiometer VR1 on the RFC Board.
6. Show the INITIAL SETTING 2 menu, press [5] to select ST-BY, and then press [ENTER].

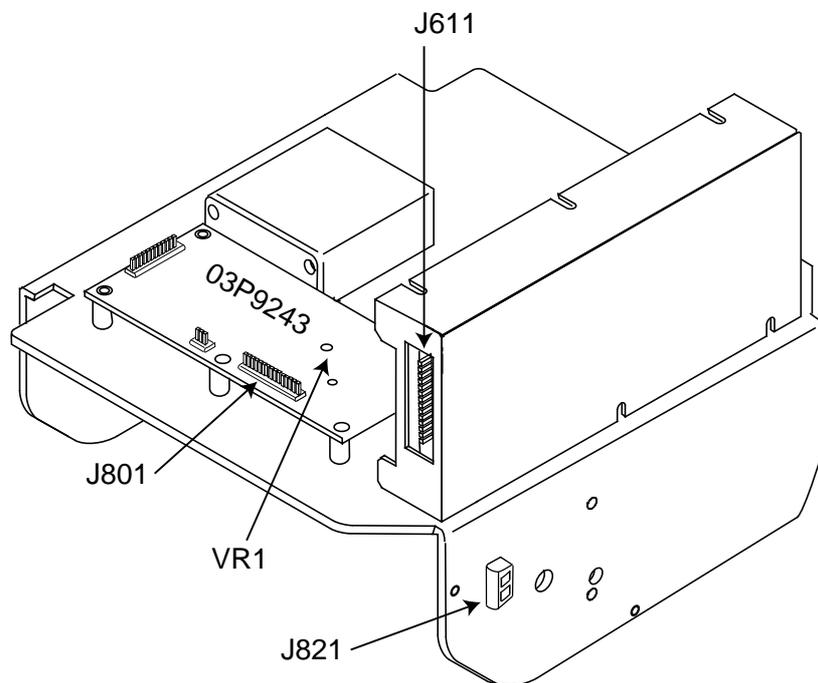
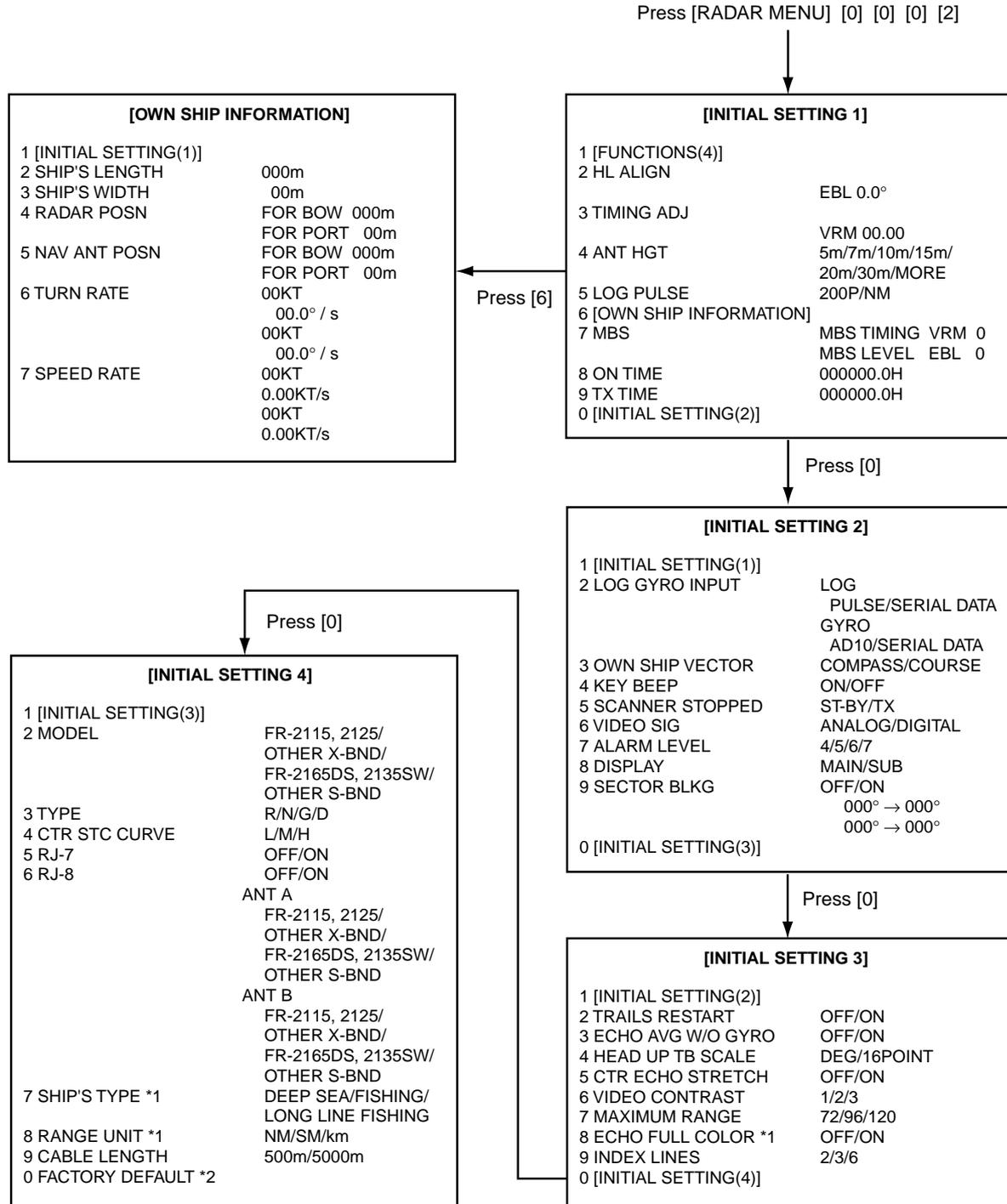


Figure 3-5 RFC Board

3.8 Initial Setting Menus

The INITIAL SETTING menus (four menus) and the OWN SHIP INFORMATION menu setup the radar according to expected usage, authorities specification, ship's characteristics, operator's preference, etc. Set items on each menu in accordance with regulations/operator's preference. After entering initial settings, reset the power.



*1: For merchant vessel the settings are DEEP SEA (SHIP'S TYPE), NM (RANGE UNIT), COLOR (ECHO FULL COLOR).

*2: For factory use.

INITIAL SETTING1 menu

Keying sequence: [RADAR MENU] [0] [0] [0] [2]

HL ALIGN: Aligns heading.

TIMING ADJ: Adjusts sweep timing.

ANT HGT: Enter height of scanner above water. Select from 5 m, 7 m, 10 m, 15 m, 20 m, or more than 30 m.

LOG PULSE: Enter speed log's pulse rate.

OWN SHIP INFORMATION: Enter ship's characteristics; length, width, radar scanner position, navigation antenna position, turn rate, and speed rate. See the description on the next page for further details.

MBS: Suppresses main bang.

ON TIME, TX TIME: Shows number of hours the radar has been turned on and transmitted, respectively. Value can be changed.

INITIAL SETTING2 menu

Keying sequence: [RADAR MENU] [0] [0] [0] [2] [0]

LOG GYRO INPUT: Select LOG or GYRO input type. LOG: Select pulse or serial data. GYRO: Digital from A/D converter or serial data.

OWN SHIP VECTOR: Select reference for own ship vector; compass or course.

KEY BEEP: Turns key response beep on or off.

SCANNER STOPPED: Set to ST-BY in normal use. TX enables transmission state without scanner rotation.

VIDEO SIG: Set to ANLG (analog) for normal use. Select DIGITAL to adjust QV (Quantized Video).

ALARM LEVEL: Sets echo strength which triggers guard alarm. "7" is strongest echo; "4" is medium strength echo.

DISPLAY: Select radar display function; main or sub (slave).

SECTOR BLKG: Sets area (up to 2) where no radar pulses will be transmitted. For example, set the area where an interfering object at the rear of the scanner would produce a dead sector (area where no echoes appear) on the display. To enter an area, select ON and enter relative bearing range of the area.

INITIAL SETTING3 menu

Keying sequence: [RADAR MENU] [0] [0] [0] [2] [0] [0]

TRAILS RESTART: Selects whether to restart or discontinue target trails when changing the range. ON restarts trailing on newly selected range; OFF discontinues trails.

ECHO AVG W/O GYRO: Echo averaging can be turned on without gyrocompass connection.

HEAD UP TB SCALE: Bearing scale may be shown in degrees or compass points in the head-up mode.

CTR ECHO STRETCH: Turn on to enlarge echoes in the range up to the first range ring.

VIDEO CONTRAST: For factory use. Do not change setting.

MAXIMUM RANGE: For factory use. Do not change setting.

ECHO FULL COLOR: Echoes may be displayed in one color or multi-color. Select ON for multi-color display.

INDEX LINES: Selects the number of index lines to display; 2, 3, or 6.

INITIAL SETTING4 menu

Keying sequence: [RADAR MENU] [0] [0] [0] [2] [0] [0] [0]

MODEL: Selects radar model.

TYPE: Selects specification of radar. R, Regular type; G, Germany; N, Netherlands, D, Denmark.

CTR STC CURVE: Selects level of STC affect; Low, Medium or High.

RJ-7, RJ-8: Selects which Interswitch unit to use.

SHIP'S TYPE: Select class of vessel; deep sea, fishing, long line fishing.

CABLE LENGTH: Set for "500."

FACTORY DEFAULT: Restores all menus' default settings.

OWN SHIP INFORMATION menu

Keying sequence: [RADAR MENU] [0] [0] [0] [2] [6]

SHIP'S LENGTH: Enter ship's length.

SHIP'S WIDTH: Enter ship's width.

RADAR POSN: Enter distance from both bow and port to the radar antenna location.

NAV ANT POSN: Enter distance from both bow and port to the navigation antenna location.

TURN RATE: Enter ship's turn rate.

SPEED RATE: Enter ship's speed rate.

1. OPTIONAL EQUIPMENT

4.1 Gyro Converter GC-8

The Gyro Converter GC-8, incorporated inside the processor unit, converts analog gyrocompass reading into digital coded bearing data for display on the monitor.

This section explains how to install and the GC-8 (mainly consisting of the GYRO CONVERTER Board) and set it up according to the gyrocompass connected.

4.1.1 Installation and connection of the GYRO CONVERTER Board

Necessary Parts: GC-8 (Code No. 008-446-520)

Name	Type	Qty	Code No.
Gyro Converter Board	64P1106	1	004-412-226
Washer-head Screw	M3X8, C2700W	5	000-881-404
Sticker	64-014-20211	1	100-132-701

1. Turn off the main POWER switch.
2. Open the processor unit. Turn off the internal power switch if so equipped. Unfasten four screws to remove the INT Board cover.
3. Fasten the GYRO CONVERTER Board inside the processor unit with four washer-head screws (supplied).

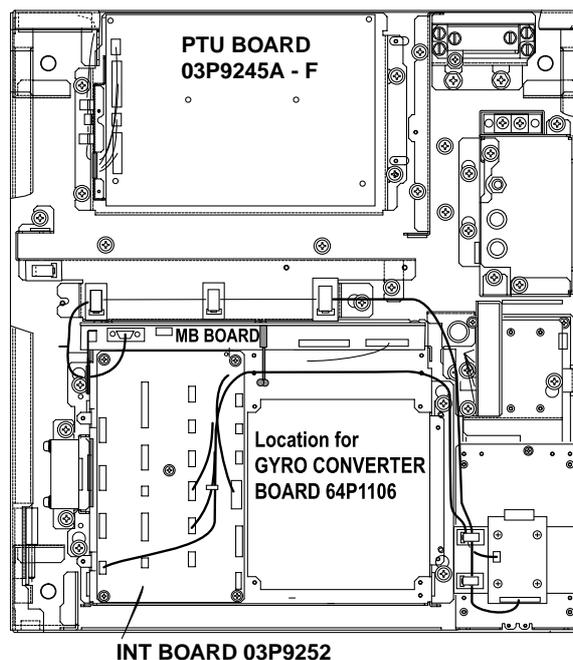


Figure 4-1 Processor unit, inside view, INT board cover removed

4. Connect the GYRO CONVERTER Board to the INT Board (cables supplied with GC-8) as shown below.

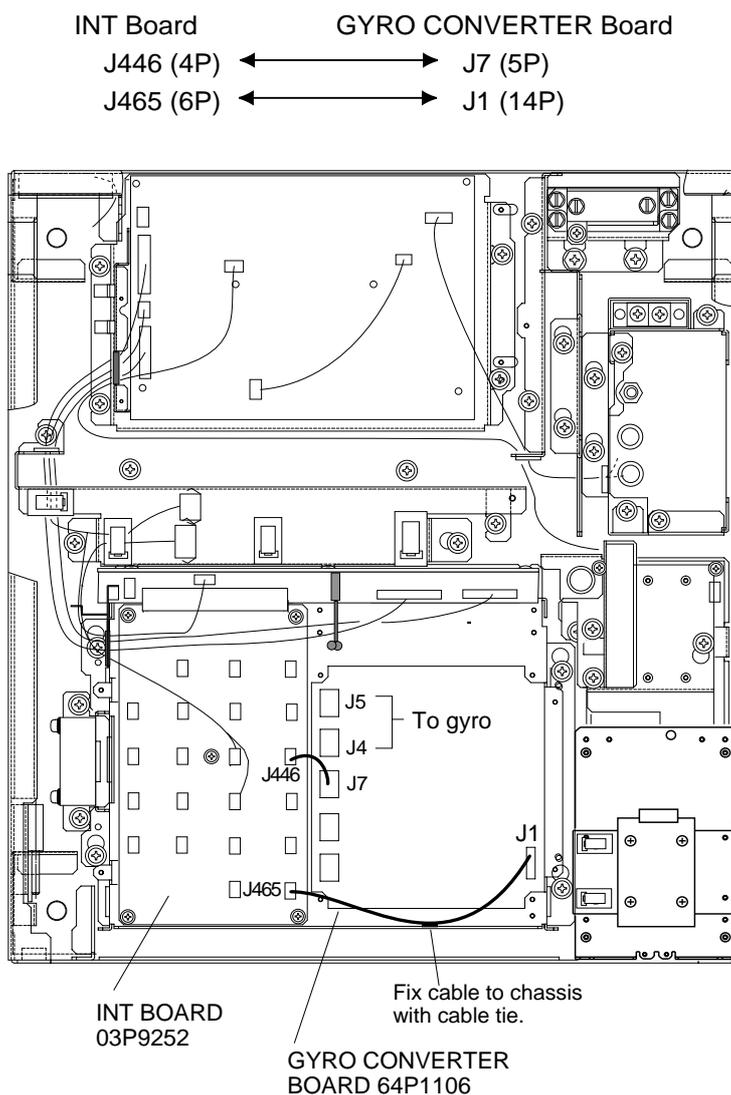


Figure 4-2 Processor unit, inside view

5. Confirm gyrocompass specifications and set the DIP switches and jumper wires on the GYRO CONVERTER Board according to the gyrocompass connected:
 Setting jumper wires and DIP switches by gyrocompass specifications: page 4-4
 Setting jumper wires and DIP switches by make and model of gyrocompass: page 4-5
 Location of jumper wires and DIP switches: page 4-6
6. Solder the gyrocompass cable to the VH connector assemblies (supplied).
7. Attach instruction label (supplied) to shield cover for the INT and GYRO CONVERTER boards.
8. Close both the INT Board cover and the processor unit cover.
9. Turn the power off and on again to reset the CPU.

4.1.2 Connection of external power supply

An external power supply is necessary when the repeater signal is step-by-step type and the step voltage is below 20 V or output voltage is less than 5 W.

1. Cut the jumper wire JP1 on the GYRO CONVERTER Board when an external power supply is used.
2. Connect the gyro cable and power cable as shown below.

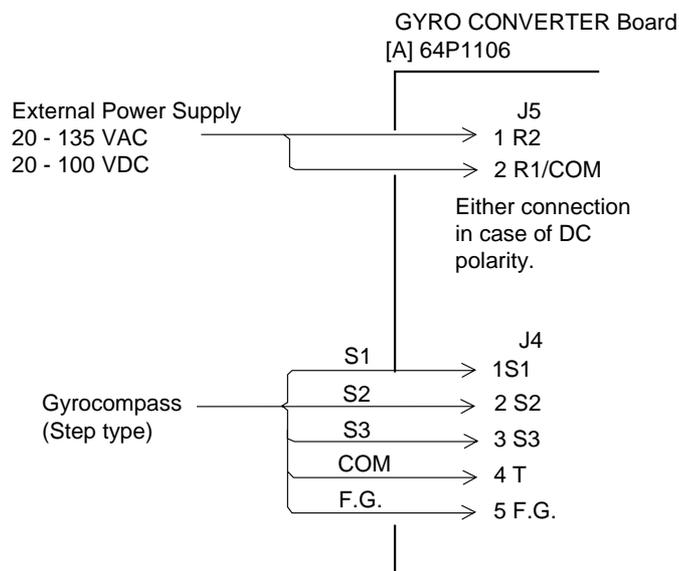


Figure 4-3 Connection of external power supply to GYRO CONVERTER Board

4.1.3 DIP switch, jumper wire settings

Default setting

The default setting of all DIP switches is off and all jumpers wire are set to "#1". (Note that the jumper wire JP1 is set at #1, #2, and #3.) In those settings the gyrocompass having the following characteristics can be directly connected; modification of the GYRO CONVERTER Board is not necessary.

AC synchronous signal: 50/60 Hz

Rotor voltage: 60 to 135 V AC

Stator voltage: 60 to 135 V AC

Gear ratio: 360X

Supply voltage: 30 to 135 V AC

If the specifications of the gyrocompass differ from those mentioned above, change jumper wire and DIP switch settings on the GYRO CONVERTER Board as appropriate. Settings may be changed according to gyrocompass specifications (page 4-4) or make and model of gyrocompass (page 4-5). For the location of DIP switches and jumper wires, see page 4-6.

Setting method 1: DIP switch settings and gyrocompass specifications

1) Gyrocompass type

Gyrocompass type	SW 1-4	SW 1-5	SW 1-6	JP1
AC synchronous	OFF	OFF	OFF	#1, #2, #3
DC synchronous	OFF	OFF	OFF	#2, #3, #4
DC step	ON	OFF	OFF	#4, #5, #6
Full-wave pulsating current	OFF	ON	OFF	#4, #5, #6
Half-wave pulsating current	ON,	ON	OFF	#4, #5, #6

2) Frequency

Frequency	SW 1-7	SW 1-8	Remarks
50/60 Hz	OFF	OFF	AC synchronous pulsating current
400 Hz	ON	OFF	AC synchronous pulsating current
500 Hz	OFF	ON	AC synchronous pulsating current
DC	ON	ON	DC synchronous DC step

3) Rotor Voltage (between R1 & R2)

Rotor Voltage	SW 2-1	JP3
20 to 45 VAC	ON	#2
30 to 70 VAC	OFF	#2
40 to 90 VAC	ON	#1
60 to 135 VAC	OFF	#1

4) Stator Voltage (between S1 & S2)

Stator Voltage	SW 2-2	SW 2-3	JP2
20 to 45 VAC, or 20 to 60 VDC	OFF	OFF	#2
30 to 70 VAC, or 40 to 100 VDC	ON	OFF	#2
40 to 90 VAC	OFF	ON	#1
60 to 135 VAC	ON	ON	#1

5) Ratio

Ratio	SW 1-1	SW 1-2	SW 1-3
360X	OFF	OFF	OFF
180X	ON	OFF	OFF
90X	OFF	ON	OFF
36X	OFF	ON	OFF

6) Supply Voltage

Stator Voltage	SW 2-2	SW 2-3	JP2
20 to 45 VAC, or 20 to 60 VDC	OFF	OFF	#2
30 to 70 VAC, or 40 to 100 VDC	ON	OFF	#2
40 to 90 VAC	OFF	ON	#1
60 to 135 VAC	ON	ON	#1

7) AD-10 format data Tx interval

Select data transmitting interval for ports 1 to 6 with jumper wires JP6 and JP7. The Tx interval is available in 25 ms or 200 ms. 25 ms is for radar; 200 ms is for all other equipment.

8) NMEA interval

Tx Interval	SW2-4
2 seconds	ON
1second	OFF

Setting method 2: DIP switch/jumper settings and make and model of gyrocompass

Maker	Models	Specification	SW 1-1	SW 1-2	SW 1-3	SW 1-4	SW 1-5	SW 1-6	SW 1-7	SW 1-8	SW 2-1	SW 2-2	SW 2-3	JP1	JP2	JP3	JP4	JP5	
FURUNO	GY-700	DC step 100V 180x 5-wire, open collector	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	OFF	OFF	#4, #5,#6	#2	-	#1	#1	
Anschutz	Standard 2,3	AC synchronous 50/60Hz Rotor voltage: 50/60V Stator voltage: 22V 360x	OFF	ON	OFF	#1, #2,#3	#2	#2	#1	#									
	Standard 4,6	AC synchronous 50/60Hz Rotor voltage: 50/60V Stator voltage: 90V 360x	OFF	#1, #2,#3	#2	#1	#1	#											
	Standard 20	DC step 35V 180x COM(-),3-wire(+)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	ON	OFF	#4, #5,#6	#2	-	#2	#	
Yokogawa Navtec (Plaitth type)	C-1/1A/2/3 A-55, B-55	AC synchronous 50/60Hz Rotor voltage: 50/60V Stator voltage: 22V 360x	OFF	ON	OFF	#1, #2,#3	#2	#2	#1	#									
	CMZ-700	DC step 24V 180x COM(+), 3-wire(-)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	ON	OFF	Remove	#2	-	*	*	
	CMZ-250X/ 300X/500	DC synchronous 360x	OFF	OFF	OFF	OFF	OFF	OFF	ON	ON	-	ON	OFF	Remove	#2	-	*	*	
		DC step 35V 180x COM(+),3-wire(-)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	ON	OFF	#4, #5,#6	#2	-	#2	#2	
	CMZ-100/200/ 300 C-1Jr,D-1Z/1/3 IPS-2/3	AC synchronous 50/60Hz Rotor voltage: 100V Stator voltage: 90V 360x	OFF	#1, #2,#3	#1	#1	#1	#1											
CMZ-50 Note	step 35V 180x COM(+),3-wire(-)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	ON	OFF	Remove	#2	-	*	*		
Plaitth	NAVGAT II/III	AC synchronous 50/60Hz Rotor voltage: 50/60V Stator voltage: 68V 360x	OFF	#1, #2,#3	#2	#2	#1	#1											
Tokimec (Sperry type)	ES-1/2/11 GLT-101/102/ 103/106K/107	AC synchronous 50/60Hz Rotor voltage: 100/110V Stator voltage: 90V 36x	ON	ON	OFF	#1, #2,#3	#1	#1	#1	#1									
	ES-11A/110 TG-200 PR222R/2000 PR237L/H GM 21	AC synchronous 50/60Hz Rotor voltage: 100/110V Stator voltage: 22V 90x	OFF	ON	OFF	#1, #2,#3	#1	#1	#1	#1									
	MK-14 MOD-1/2/T NK-EN,NK-EI	DC step 70V 180x COM(-), 3-wire(+)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	OFF	OFF	#4, #5,#6	#2	-	#1	#1	
	SR-130/140	DC step 70V 180x 5-wire, open collector	ON	OFF	OFF	OFF	ON	OFF	OFF	OFF	-	OFF	OFF	#4, #5,#6	#2	-	#1	#1	
	TG-100/5000 PR-357/130/ 140, ES-17 GLT-201/202 /203	DC step 70V 180x COM(+), 3-wire(-)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	OFF	OFF	#4, #5,#6	#2	-	#1	#1	
	TG-6000	DC step 24V 180x	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	ON	OFF	#4, #5,#6	#2	-	#2	#2	
	GM-11	AC synchronous 50/60Hz Rotor voltage: 100V Stator voltage: 90V 90x	OFF	ON	OFF	#1, #2,#3	#1	#1	#1	#1									
	SR-120,ES-16 MK-10/20/30	DC step 35V 180x	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	ON	OFF	#4, #5,#6	#2	-	#2	#2	
Kawasaki	GX-81	AC synchronous 50/60Hz Rotor voltage: 100/110V Stator voltage: 90V 90x	OFF	ON	OFF	#1, #2,#3	#1	#1	#1	#1									
Armabrown	MK-10,MKL-1 SERIES1351, MOD-4	DC step 50V 180x COM(+), 3-wire(-)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	OFF	OFF	#4, #5,#6	#2	-	#1	#1	
Robertson	SKR-80	DC step 35V 180x COM(-), 3-wire(+)	ON	OFF	OFF	ON	OFF	OFF	ON	ON	-	ON	OFF	#4, #5,#6	#2	-	#2	#2	

*: Set JP4 and JP5 according to the voltage of the external power supply.

Note: If CMZ-50 has 35VDC, set JP1 to #4, #5, #6.

Location of DIP switches, jumper wires on the GYRO CONVERTER Board

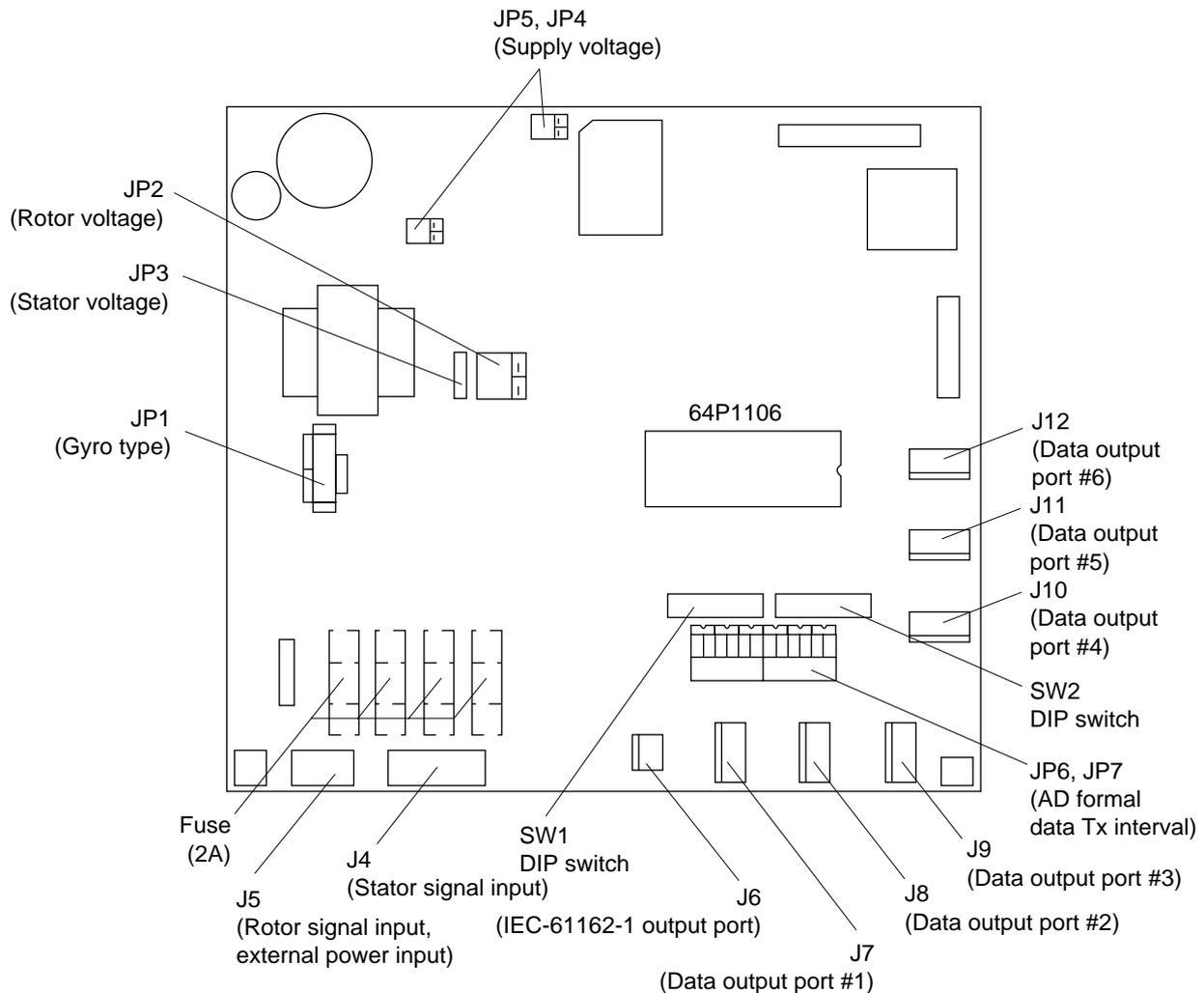


Figure 4-4 GYRO CONVERTER Board

4.1.3 Setting the heading readout on the radar display

Confirm that the gyrocompass is giving a reliable readout. Then, set the heading readout on the monitor as follows:

1. Press the [RADAR MENU] key to display the FUNCTIONS 1 menu.
2. Press the [0] key twice to display the FUNCTIONS 3 menu.
3. Press the [9] key to select the GYRO SETTING option.
4. Rotate the EBL control to align the radar's HDG readout with the gyrocompass heading.
5. Press the [ENTER] key to finish.

4.2 ARP Board ARP-26

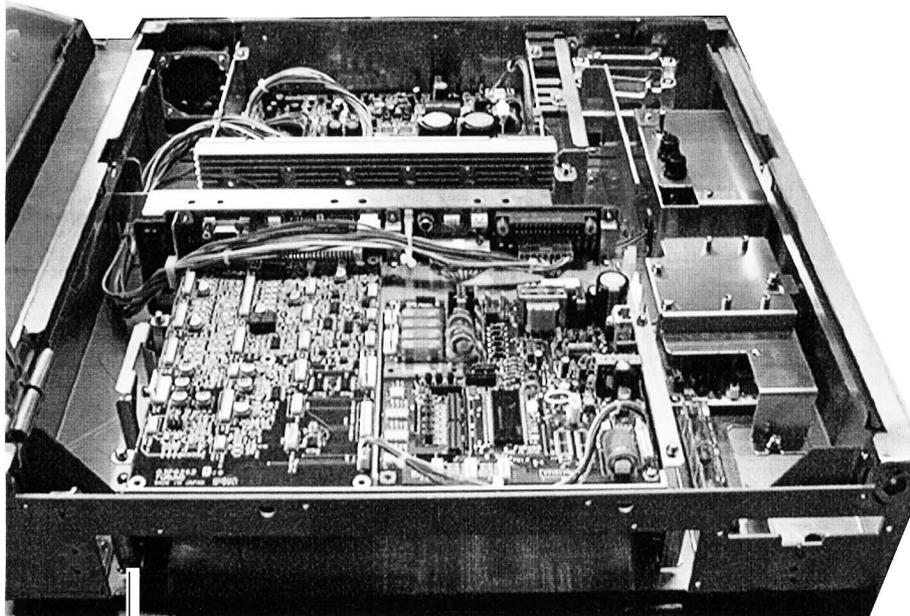
The ARP Board ARP-26, which provides ARPA functions, is an optional circuit board which is accommodated in the processor unit. Note that the ARP-26 is not available with the statute mile-type radar.

Necessary Parts: ARP-26-2E (008-485-500)

Name	Type	Qty	Code No.
ARP Board	18P9002B	1	008-473-650

4.2.1 Installation of the ARP board

1. Turn off the power. Unfasten the PCB card case cover at the left front of the processor unit by unfastening four screws.
2. Set the ARP Board in the center slot of the PCB card case.



Top: RP Board (Option)
Middle: ARP Board (Option)
Bottom: SPU Board

Figure 4-5 Processor unit, inside view

3. Adjust the ARP Board referring to the procedure on the next page.

4.2.2 ARP board adjustment

1. Turn the GAIN, A/C SEA and A/C RAIN controls fully counterclockwise (OFF). Transmit on the 12 nm range.
2. Connect a digital multimeter between TP7(+) and TP6(-) on the ARP Board.

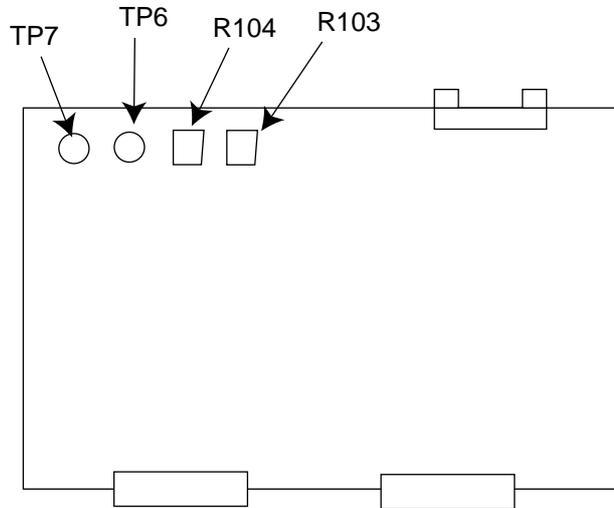


Figure 4-6 ARP Board (18P9002B)

3. Adjust R104 on the ARP Board so the multimeter reads between 0.09 and 0.14 VDC.
4. Set controls and switches as below.
 - 5. GAIN: fully clockwise (max.)
 - Interference rejector: OFF
 - Range: 24 nm
 - Echo stretch: OFF
6. Press [RADAR MENU] [0] [0] [0] [2] [0] to open the INITIAL SETTING2 menu.
7. Set the VIDEO SIG field to DIGITAL and press the [ENTER] key.
8. Adjust R103 on the ARP Board so noise just appears on the display.

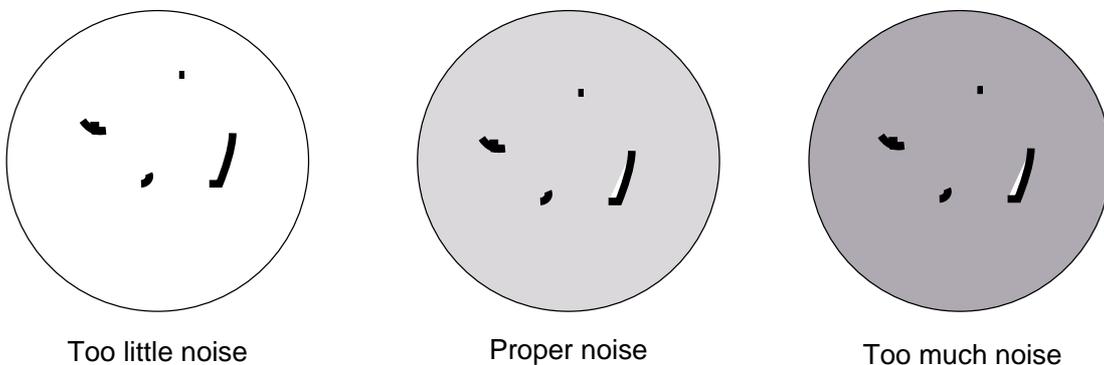


Figure 4-7 How to adjust noise

9. Set VIDEO SIG to ANALOG and press the [ENTER] key.

4.2.3 Final check of ARP board

Connect a gyrocompass and a log to the radar and place the radar under transmit state. Confirm that LEDs CR9, CR10, CR11, CR12, CR15 and CR16 on the ARP Board are off. If ship's speed is zero, or other signal is not being input, corresponding LED will light. Refasten the card case cover and close the processor unit.

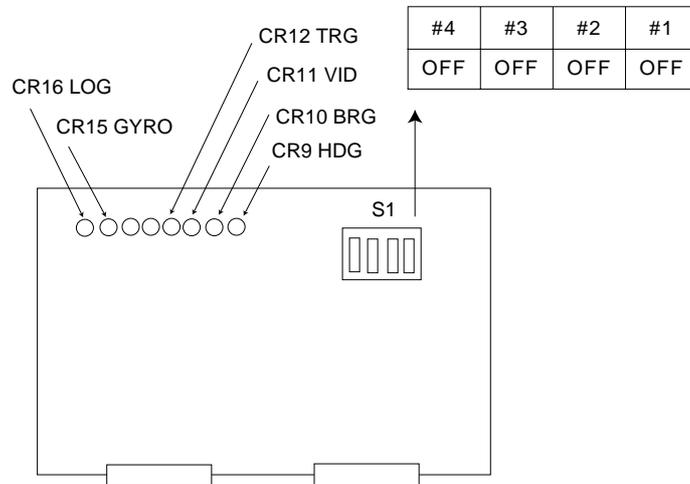


Figure 4-8 ARP Board (18P9002B)

4.3 RP Board RP-26

The RP Board RP-26, which provides video plotter functions, consists of a circuit board and a card drive, both of which are accommodated in the processor unit. Note that the RP-26 is not available with the statute mile-type radar.

Necessary parts: RP-26-Z-2E (Code no. 008-485-520)

Name	Type	Qty	Code No.	Remarks
M-card Base Assy.	-	1		IF Board, Cable assy., M-card base assy.
RP Board	14P0298	1	008-487-640	
Pan-head Screw B	M4X8 C2700W	4	000-881-445	
Pan-head Screw B	M3X8 C2700W	2	000-881-404	Not used
Pan-head Screw A	M2.6X5 C2700W	2	000-800-973	Not used
Pan-head Screw A	M3X8 C2700W	1	000-881-104	Not used
Teethed Lock Washer	M4 C5191W	1	000-864-506	
Teethed Lock Washer	M4 C5191W	1	000-864-504	Not used

1. Open the processor unit. Unfasten one M4X8 pan-head screw and two M3X10 pan-head screws to remove the RGB Board together with its mounting plate. Disconnect the monitor cable at the RGB Board. See the figure at the top of the next page for location.

2. Unfasten four M3X8 pan-head screws to remove the RP board mounting plate from the RGB board and its mounting plate.

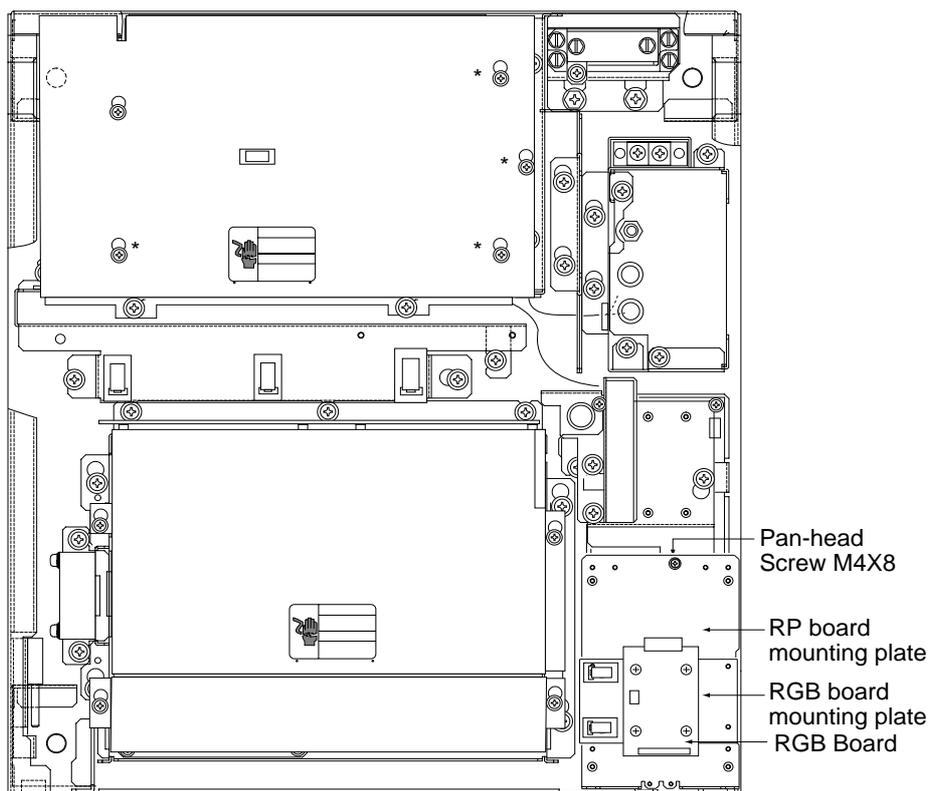


Figure 4-9 Processor unit, inside view

3. Disconnect RP connector from M-card base assy. Fasten the M-card base assy. and RGB board mounting plate with one M4X8 pan-head screw.

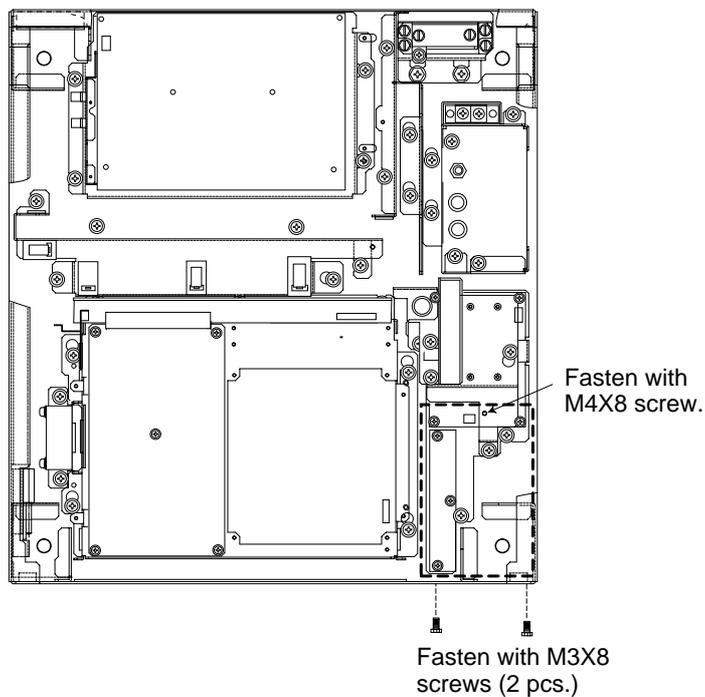


Figure 4-10 Processor unit, inside view

4. Fix the M-card base assy. with two M3X8 pan-head screws.
5. Set the M-card case cover to the hole in the front panel and fix with two M2.6X5 pan-head screws.

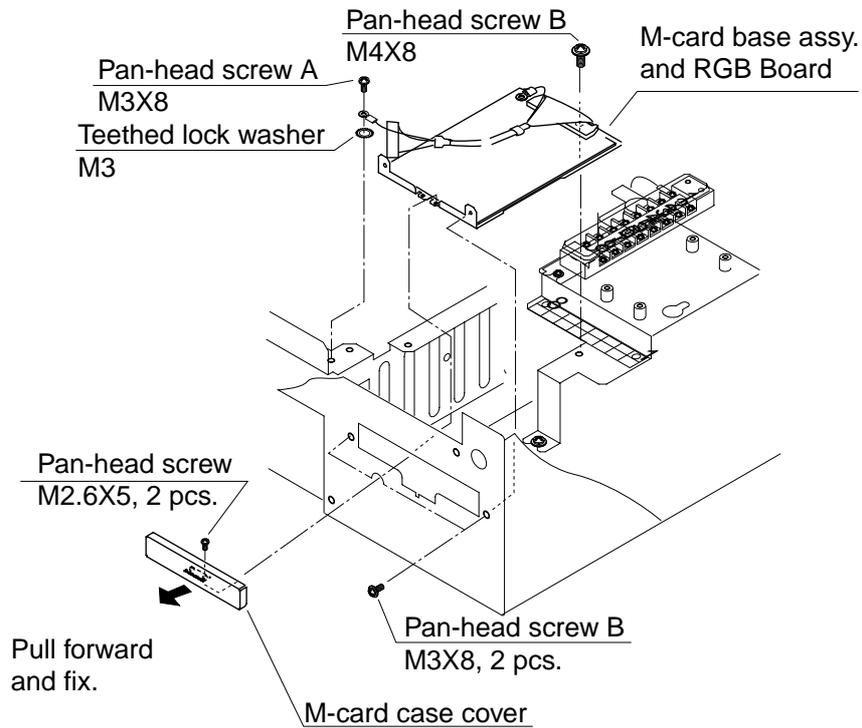


Figure 4-11 Processor unit, front view

6. Unfasten four M4X8 screws to remove the PCB card case cover at the front of the processor unit.
7. Set the RP Board (14P0298) in the top slot of the PCB card case.

8. Run the connector from the card case in front of the GYRO CONVERTER Board as shown in Figure 4-12.
9. Plug the connector from the M-card base assy. in J1 on the RP Board as shown in Figure 4-12.

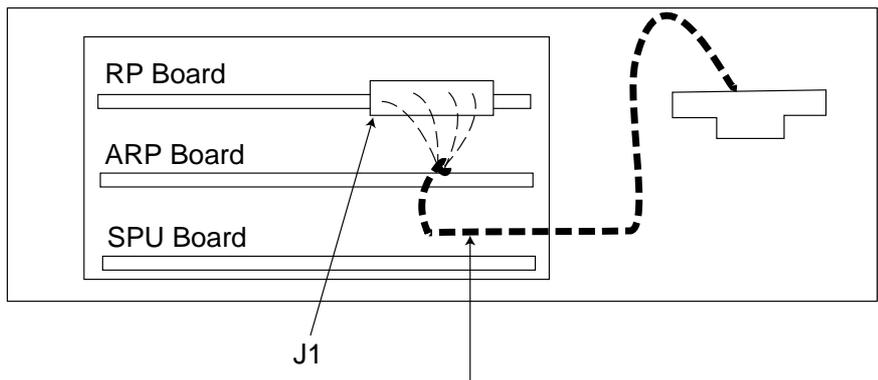
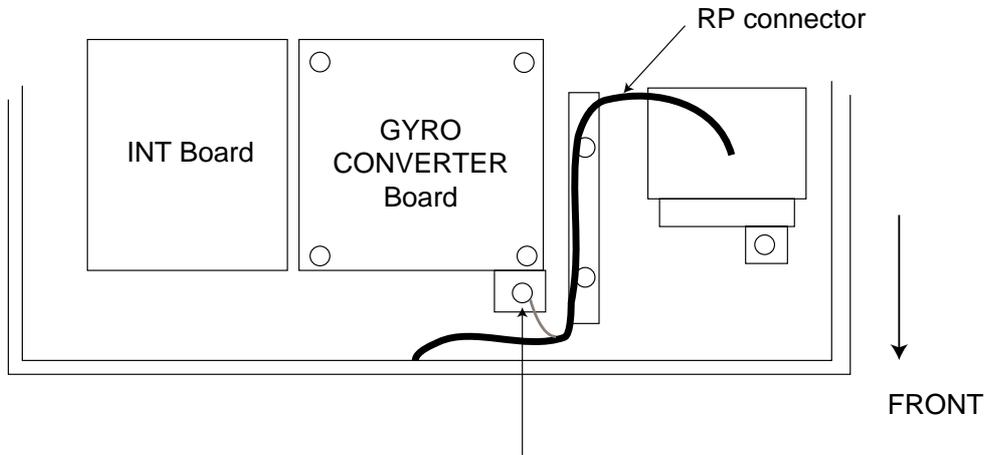


Figure 4-12 Processor, front and top views

10. Fasten the ground wire from the connector with M3X8 pan-head screw and teathed lock washer at the location shown in Figure 4-12.
11. Fasten the PCB card case cover to the processor unit.
12. Connect the monitor cable to the RGB Board. Close the processor unit.

4.4 Performance Monitor PM-30

Necessary parts: PM-30 and OP03-150 (Code no. 008-485-490)

Name	Type	Code No.	Qty
PM-IN Board	03P9225	008-487-620	1
Pan-head Screw B	M3X8 C2700W	000-881-404	3
Connector Assy.	VH3P-L300-AA	000-141-014	2

1. Open the processor unit. Unfasten three screws to remove the RGB Board together with its mounting plate. Unfasten the monitor cable at the RGB Board. (See Figure 4-9 on page 4-10 for location.)
2. Fasten the PM Board 03P9225 to the location shown below with three M3X8 pan-head screws.

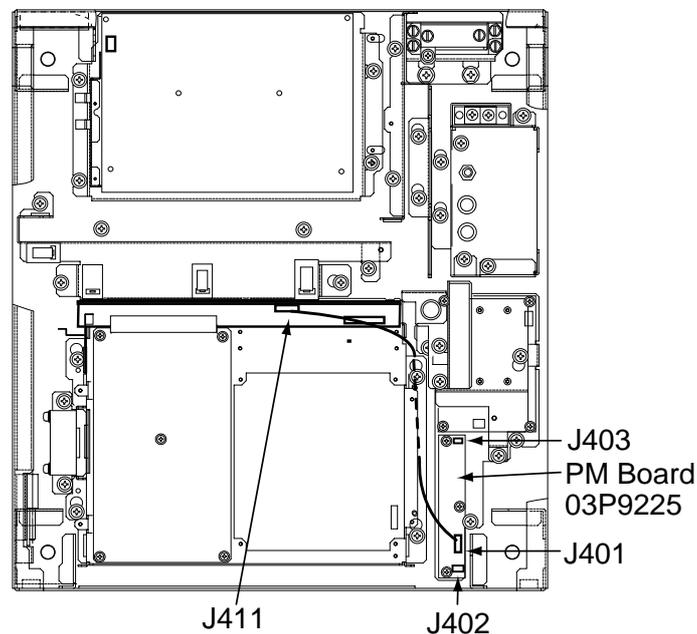


Figure 4-13 Processor unit, inside view

3. Connect J411 to J401 on the PM Board.
4. Connect two connector assemblies (VH3P-L300-AA) to J402 and J403.
5. Solder the other end of the connector assemblies with external cables, one from ship's mains and one from the PM-30.
6. Fasten the RGB board and its mounting plate and connect the monitor cable. Close the processor unit.

4.5 Alarm Kit

The alarm kit mainly consists of a circuit board and connection cables, and provides alarm output to ship's bridge alarm system.

Necessary parts: OP03-156 (Code no. 008-500-650)

Name	Type	Code No.	Qty
ALARM Board	03P9262	008-500-680	1
NH Connector Assy.	03-1990(9-9P)	008-500-700	1
NH Connector Assy.	03-1991(3P)	008-500-710	4
Cable Band	HP-3N	000-570-001	1
Cable Tie	CV-100	000-570-322	3
Pan-head Screw B	M3X8 C2700W	000-881-404	4
Pan-Head Screw B	M3X8 C2700W	000-881-447	1

Refer to the figure on the next page for parts location.

1. Open the processor unit.
2. Unfasten four screws to dismount the INT Board cover.
3. Fasten the ALARM Board to the processor unit with four M3X8 pan-head screws (supplied).
4. Connect the NH connector (9-9P, supplied) between J471 on the ALARM Board and J451 (EXT-BUZ) on the INT Board, passing it through the cable band and binding it with existing cable tie.
5. Fasten the cable band (supplied) with a pan-head screw (M4X12, supplied) and attach two cable ties (CV-100, supplied).
6. Connect a NH connector (3P, supplied) to each of J472, J473, J474 and J475 on the ALARM Board.
7. Route the NH connectors along the cable ties and pass them through the cable clamp.
8. Close the INT board cover.
9. Close the processor unit.

J472: ARPA guard zone; target alarm

J473: SYSTEM FAILURE (HP, BP, TRIG, VIDEO, GYRO, and AZI)

J474: ARPA CPA/TCPA

J475: Spare

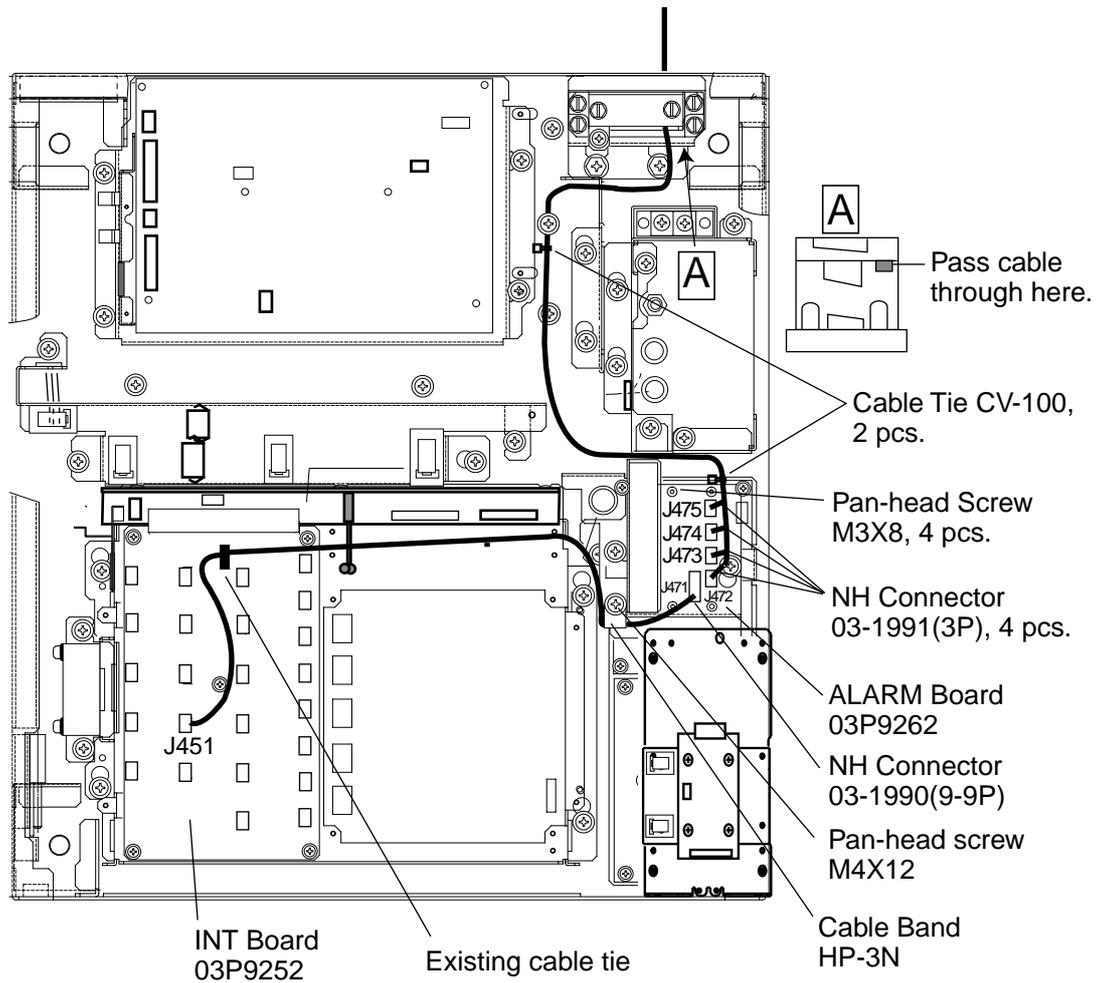


Figure 4-14 Processor unit, inside view

4.6 AC-DC Conversion Kit

The AC-DC Conversion Kit enables conversion from AC power to DC power, and mainly consists of a circuit board and filter.

AC-DC Conversion Kit (for 24 rpm antenna) Type: OP03-161-24, Code No. 008-499-760				AC-DC Conversion Kit (for 42 rpm antenna) Type: OP03-161-42, Code No. 008-499-770			
Name	Type	Code No.	Qty	Name	Type	Code No.	Qty
POWER Board	03P9246A	008-487-440	1	POWER Board	03P9246C	008-493-700	1
Filter	RDP-124 (DC)	008-492-460	1	Filter	RDP-124 (DC)	008-492-460	1

1. Open the processor unit.
2. Follow a) and b) of "how to access rear-left fixing hole" on page 7 to remove the PTU Board cover.
3. Unplug all connectors from the PTU Board.
4. Loosen the screws fixing the PTU Board, and then remove the PTU Board.
5. Fasten new PTU Board with screws removed in step 4.
6. Plug in six connectors to their proper locations on the PTU Board. Do not connect J101.
7. Loosen four screws fixing the AC filter.
8. Fasten new filter.
9. Connect cable from filter to J101 on the PTU Board.
10. Fasten the PTU board cover.
11. Connect power cable from ship's mains.
12. Close the processor unit.

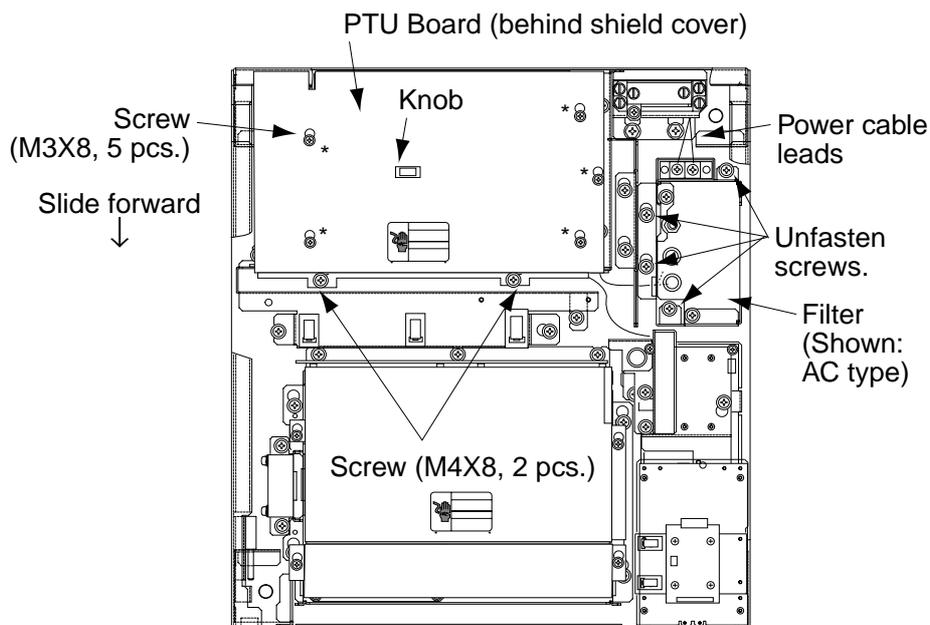
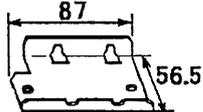
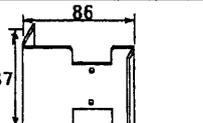
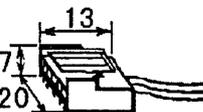
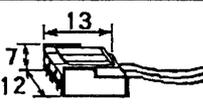
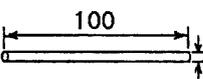
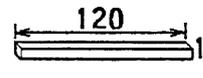
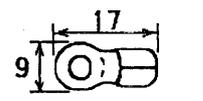
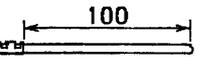
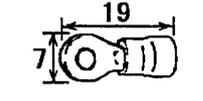
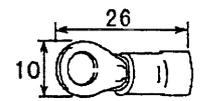


Figure 4-15 Processor unit, inside view

FURUNO

CODE NO.	008-503-450	03FS-X-9408-1
TYPE	CP03-19105	1/2

工事材料表 INSTALLATION MATERIALS		船舶用レーダー MARINE RADAR			
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	下クランプ 前板 LOWER CLAMP FRONT PLATE		03-144-1425-1	1	
			CODE NO. 100-263-601		
2	下クランプ 後板 LOWER CLAMP REAR PLATE		03-144-1426-0	1	
			CODE NO. 100-263-610		
3	VHコネクタ組品 VH CONNECTOR ASSY.		03-1737(5P)	1	
			CODE NO. 008-454-380		
4	VHコネクタ組品 VH CONNECTOR ASSY.		03-1738(3P)	1	
			CODE NO. 008-454-390		
5	スチューブ F(Z) HEAT-SHRINK TUBE		3X0.25 寸 * 0.10M*	2	
			CODE NO. 000-105-874		
6	シートフォーム SHIELD FOAM		71TS-10-10*0.12M*	4	
			CODE NO. 000-808-456		
7	圧着端子 CRIMP-ON LUG		BNK4	2	
			CODE NO. 000-538-180		
8	NHコネクタ *センガイ* NH CONNECTOR ASSY.		AWG24 *0.1M*	20	
			CODE NO. 000-132-342		
9	圧着端子 CRIMP-ON LUG		FV1.25-M3 7カ	5	
			CODE NO. 000-538-110		
10	圧着端子 CRIMP-ON LUG		FV5.5-4	2	
			CODE NO. 000-538-123		

DWG NO.

C3464-M07-B

FURUNO ELECTRIC CO., LTD.

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FURUNO

CODE NO.	008-503-450	03FS-X-9408-1 2/2
TYPE	CP03-19105	

工事材料表 INSTALLATION MATERIALS		FR-2115/2115-B FR-2125/2125V FR-2125W/2125-B FR-2135S/2135SW FR-2135S-B/2165DS FR-2155/2155-B FR-2135SW-MSA 船舶用レーダー MARINE RADAR			
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
11	コネクタ CONNECTOR		H3P-SHF-AA	2	
			CODE NO.		
12	コネクタ CONNECTOR		H5P-SHF-AA	2	
			CODE NO.		
13	ワッシャーヘッドネジ B WASHER HEAD SCREW		M3X8 C2700 MBN12	2	
			CODE NO.		
14	六角セットUIネジ B HEX. BOLT (WASHER HEAD)		M5X10 SUS304	2	
			CODE NO.		
15	パイプボックススパンナー PIPE BOX SPANNER		PS0017	1	
			CODE NO.		
16	コネクタ(クミヒン) CONNECTOR ASSY.		VH3P-L300-AA	2	
			CODE NO.		
17	特殊ラグ LUG		7ヶ44 ス	2	
			CODE NO.		

DWG NO.

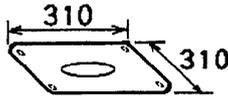
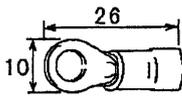
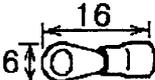
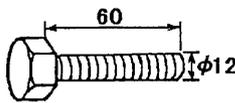
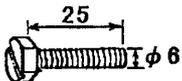
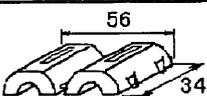
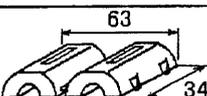
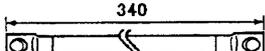
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FURUNO

CODE NO.	008-493-160	03FS-X-9404 -7
TYPE	CP03-19104	1/2

工事材料表 INSTALLATION MATERIALS					
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	防蝕ゴム.1. CORROSION-PROOF RUBBER MAT		03-001-3001-0	1	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
2	シーワッシャー SEAL WASHER		03-001-3002-0	4	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
3	圧着端子 CRIMP-ON LUG		FV1.25-M3 7カ	26	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
4	圧着端子 CRIMP-ON LUG		FV5.5-4	2	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
5	圧着端子 CRIMP-ON LUG		FVD1.25-3	1	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
6	六角ボルト (全紗) HEX. BOLT		M12X60 SUS304	4	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
7	六角ボルト HEX. BOLT		M6X25 SUS304	1	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
8	EMIコア EMI CORE		RFC-10	2	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
9	EMIコア EMI CORE		RFC-13	2	空中線部用 FOR ANTENNA UNIT
			CODE NO.		
10	7-入線 GROUNDING WIRE		RW-4747-1 03S4747	1	空中線部用 FOR ANTENNA UNIT
			CODE NO.		

DWG NO.

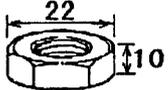
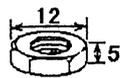
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FURUNO ELECTRIC CO., LTD.

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FURUNO

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TYPE	CP03-19104	

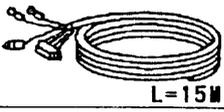
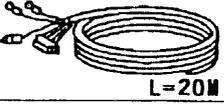
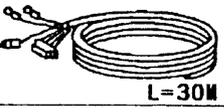
工事材料表 INSTALLATION MATERIALS					
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
11	六角ナット 1種 HEX. NUT		M12 SUS304	4	空中線部用 FOR ANTENNA UNIT
	CODE NO.		000-863-112		
12	ミガキ平座金 FLAT WASHER		M12 SUS304	4	空中線部用 FOR ANTENNA UNIT
	CODE NO.		000-864-132		
13	バネ座金 SPRING WASHER		M12 SUS304	4	空中線部用 FOR ANTENNA UNIT
	CODE NO.		000-864-263		
14	六角ナット 1種 HEX. NUT		M6 SUS304	1	空中線部用 FOR ANTENNA UNIT
	CODE NO.		000-863-109		
15	ミガキ平座金 FLAT WASHER		M6 SUS304	3	空中線部用 FOR ANTENNA UNIT
	CODE NO.		000-864-129		
16	バネ座金 SPRING WASHER		M6 SUS304	1	空中線部用 FOR ANTENNA UNIT
	CODE NO.		000-864-260		

DWG NO.
C3464-M06- G

FURUNO ELECTRIC CO., LTD.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

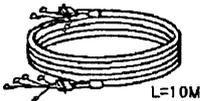
工事材料表 INSTALLATION MATERIALS		船舶用レーダ MARINE RADAR		CODE NO.	03FS-X-9405 -1
				TYPE	1/1
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	信号ケーブル組品 SIGNAL CABLE ASSY.	 L=15M	S03-75-15	1	選択 TO BE SELECTED
			CODE NO.		
2	信号ケーブル組品 SIGNAL CABLE ASSY.	 L=20M	S03-75-20	1	選択 TO BE SELECTED
			CODE NO.		
3	信号ケーブル組品 SIGNAL CABLE ASSY.	 L=30M	S03-75-30	1	選択 TO BE SELECTED
			CODE NO.		

DWG NO. C3471-M01- B

FURUNO ELECTRIC CO., LTD

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

工事材料表 INSTALLATION MATERIALS		FR-2115-B 船舶用レーダー FR-2125-B FR-2155-B FR-2135S-B MARINE RADAR		CODE NO.	03FS-X-9406 -1
				TYPE	1/1
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	ケーブル(クミヒン) CABLE ASSY.	 L=10M	UL1007/2C-2VSB CODE NO. 000-142-172	1	

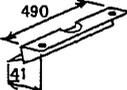
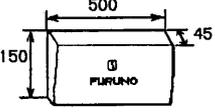
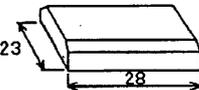
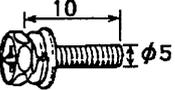
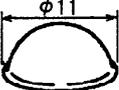
 DWG NO.
 C3483-M01- B

FURUNO ELECTRIC CO., LTD.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

CODE NO.	008-501-170	03FS-X-9509 -2 1/1
TYPE	FP03-07401	

付属品表 ACCESSORIES					
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	KB直付け金具 KB FIXNG PLATE		03-144-1691-1	1	
			CODE NO. 100-263-941		
2	ダストカバー-KB DUST COVER KB		03-144-1693-0	1	
			CODE NO. 100-271-760		
3	スリ止メゴム NONSLIP RUBBER		03-144-1694-0	1	
			CODE NO. 100-277-860		
4	+77° セットUIセムB +HEX. BOLT (WASHER HEAD)		M5X10 SUS304	2	
			CODE NO. 000-802-288		
5	ゴム足 RUBBER FEET		SJ-5003 ㊦	4	
			CODE NO. 000-801-787		

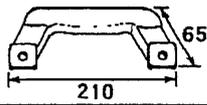
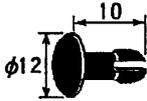
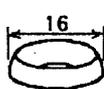
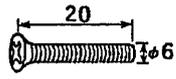
DWG NO. C3483-F01- C

FURUNO ELECTRIC CO., LTD.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

CODE NO.	008-478-830	03FS-X-9501-5 1/1
TYPE	FP03-06201	

付属品表					
ACCESSORIES					
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	取手 HANDLE		14-002-1125-2	2	
			CODE NO. 840-211-252		
2	スナップボタ PLASTIC RIVET		KB-133ヨ ボタンボ ボタ	4	
			CODE NO. 000-570-276		
3	ロゼット座金 ROSETTE WASHER		M6 C2700W ボリール 座 座	4	
			CODE NO. 000-864-910		
4	+丸皿小ネジ OVAL COUNTERSUNK HEAD SCREW		M6X20 C2700W ボリール 座	4	
			CODE NO. 000-861-475		
5	波座金 WAVE WASHER		WW-6 SUS	4	
			CODE NO. 000-864-350		

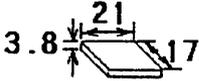
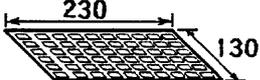
DWG NO.
C3464-F01- F

FURUNO ELECTRIC CO., LTD.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

CODE NO.	008-485-480	03FS-X-9504 -5 1/1
TYPE	FP03-06502	

付属品表 ACCESSORIES		FR-2115/2115-B 船舶用レーダ FR-2125/2125-B FR-2155/2155-B FR-2135S/2135S-B MARINE RADAR FR-2135SW/2125V FR-2165DS			
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	ユーザーキーキャップ USER KEYCAP		03-144-1613-1	4	
			CODE NO. 100-263-831		
2	ユーザーキーシート(E) USER KEYSHEET (E)		03-144-1655-1	1	
			CODE NO. 100-263-881		

DWG NO.

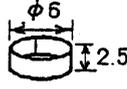
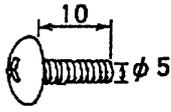
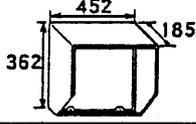
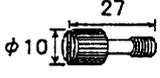
C3464-F04-E

FURUNO ELECTRIC CO., LTD

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

CODE NO.	008-490-970	03FS-X-9502 -4 1/1
TYPE	FP03-06503	

付属品表 ACCESSORIES		FR-2115/2115-B FR-2125/2125W FR-2125-B FR-2155/2155-B FR-2135S/2135SW FR-2135S-B/2165DS GD-680/GP-680		船舶用レーダ カラービデオプロッター カラーGPSプロッター MARINE RADAR COLOR VIDEO PLOTTER COLOR GPS PLOTTER		
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS		数量 Q'TY	用途/備考 REMARKS
1	マキスヘーサー SPACER		5X2.5		2	
			CODE NO.	000-808-429		
2	トラスネジ SCREW		M5X10 C2700W		2	
			CODE NO.	000-808-430		
3	フード HOOD		03-144-1335-1		1	
			CODE NO.	100-263-331		
4	フードヒス HOOD RETAINER		03-144-1336-1		2	
			CODE NO.	100-266-311		

DWG NO. C3464-F02- E

FURUNO ELECTRIC CO., LTD

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

付属品表 ACCESSORIES		FR-2115/2115-B, FR-2125/2125-B, FR-2125W, FR-2155/2155-B, FR-2135S/2135S-B, FR-2135SW/2165DS, FR-2135SW-MSA, GD-680/GP-680, FSV-24		CODE NO.	03FS-X-9506 -4
				TYPE	1/1
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	ダストカバー-CRT DUST COVER		03-144-1338 CODE NO. 100-271-750	1	

 DWG NO.
 C3464-F06- E

FURUNO ELECTRIC CO., LTD.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

FURUNO

CODE NO.	008-485-360	03FS-X-9301 -2
TYPE	SP03-12501	BOX NO. P

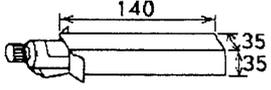
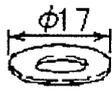
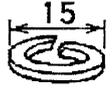
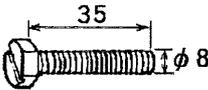
SHIP NO.		SPARE PARTS LIST FOR		U S E			SETS PER VESSEL
		FR-2115/2115-B 船舶用レーダ FR-2125/2125-B FR-2125V MARINE RADAR		空中線用 FOR ANTENNA UNIT			
ITEM NO.	NAME OF PART	OUTLINE	DWG. NO. OR TYPE NO.	QUANTITY			REMARKS/CODE NO.
				WORKING		SPARE	
				PER SET	PER VES		
1	カーボンブラシ CARBON BRUSH		MG120-5X6X11 D8G	1		1	1袋2個入り 2pcs in bag 000-631-716
MFR'S NAME		FURUNO ELECTRIC CO.,LTD		DWG NO.		C3464-P01- B 1/1	

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

A-15

FURUNO

CODE NO.	008-485-250	03FS-X-9409 -0 1/1
TYPE	CP03-24201	

工事材料表 INSTALLATION MATERIALS					
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	スリーボンド SEALANT		1211 50G	1	
			CODE NO.		
2	Oリング O-RING		JISB2401-P135	1	
			CODE NO.		
3	ミガキ平座金 FLAT WASHER		M8 SUS304	8	
			CODE NO.		
4	バネ座金 SPRING WASHER		M8 SUS304	8	
			CODE NO.		
5	六角ボルト スリ割り HEX. BOLT (SLOTTED HEAD)		M8X35 SUS304	8	
			CODE NO.		

DWG NO. C3453-M04-A

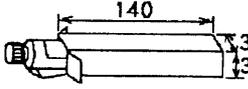
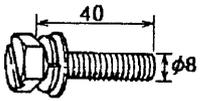
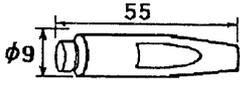
FURUNO ELECTRIC CO., LTD.

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)

A-16

FURUNO

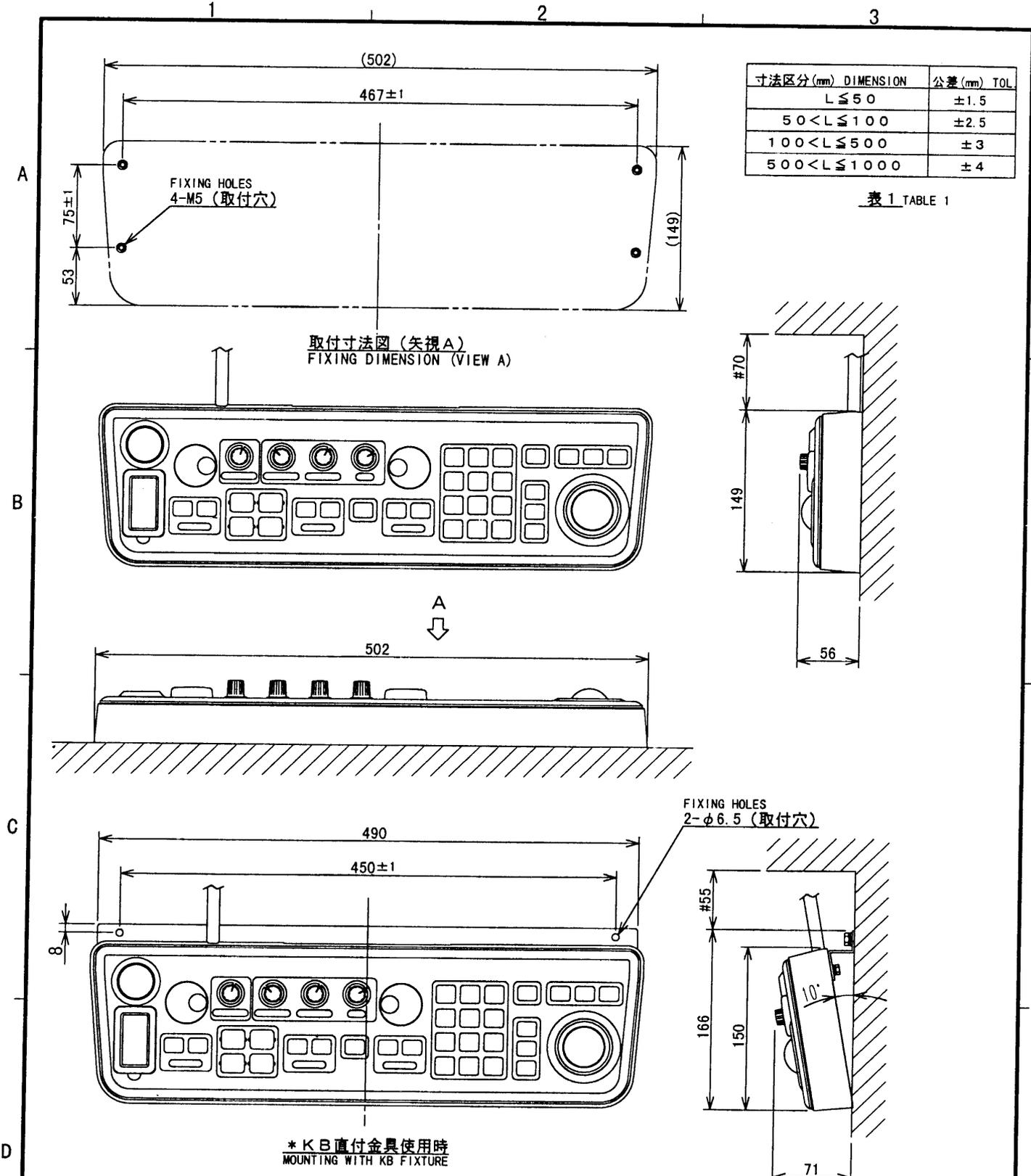
CODE NO.	008-487-130	03FS-X-9403 -2 1/1
TYPE	CP03-19101	

工事材料表 INSTALLATION MATERIALS		FR-2115/2125/2125W 船舶用レーダ MARINE RADAR			
番号 NO.	名称 NAME	略図 OUTLINE	型名/規格 DESCRIPTIONS	数量 Q'TY	用途/備考 REMARKS
1	Oリング O-RING		JISB2401-P135	1	
			CODE NO.		
2	スリーボンド ADHESIVE		1211 50G	1	
			CODE NO.		
3	六角ボルト スリッ HEX. BOLT (SLOTTED, WASHER HEAD)		M8X40 SUS304	8	
			CODE NO.		
4	ピン PIN		03-141-0301-2	2	
			CODE NO.		

DWG NO. C3464-M04-C

FURUNO ELECTRIC CO., LTD

(略図の寸法は、参考値です。 DIMENSIONS IN DRAWING FOR REFERENCE ONLY.)



注 記 1) #印寸法は最小サービス空間寸法とする。
 2) 指定外の寸法公差は、表 1 による。

NOTE 1. #: RECOMMENDED SERVICE CLEARANCE.
 2. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS.

DRAWN July 19 '99 T. YAMASAKI		TITLE RCU-011
CHECKED July 15 '99 K. Kusunoki		名称 操作部
APPROVED July 15 '99 K. Kusunoki	OTHERS FR-2115/2125-B	外寸図
SCALE 1/5 MASS 5.2 kg	MASS W/ CABLE AND FIXTURE. 質量はケーブル・取付金具を含む	NAME CONTROL UNIT
DWG. No. C3471-G03-B	03-144-1690-G2	OUTLINE DRAWING

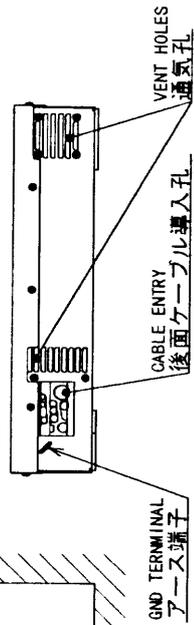
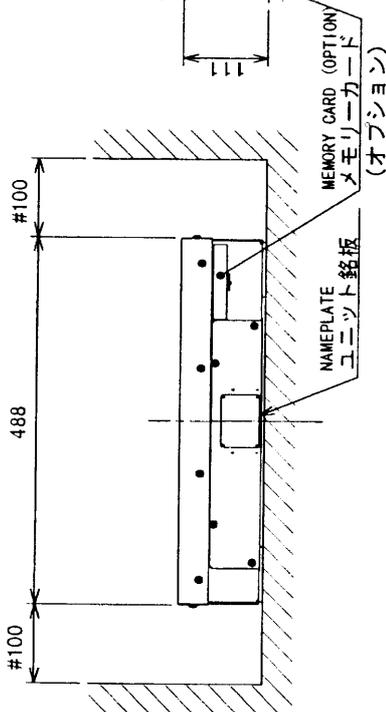
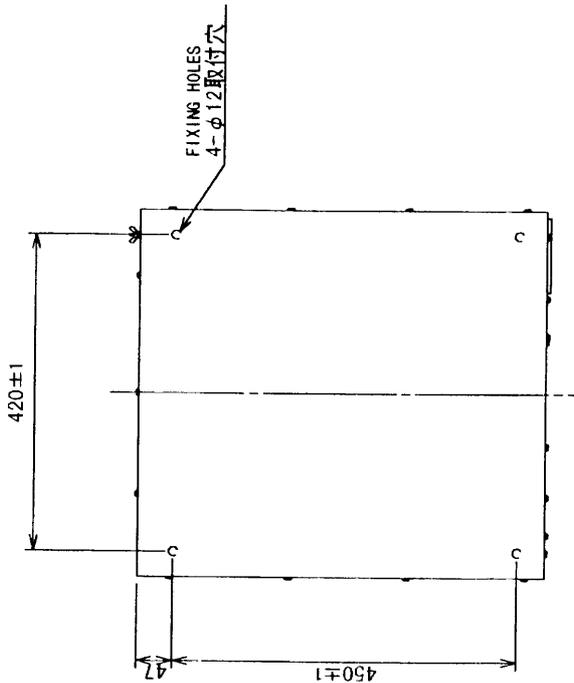
4

3

2

寸法区分 (mm)	DIMENSION	公差 (mm) TOL
L ≤ 50		±1.5
50 < L ≤ 100		±2.5
100 < L ≤ 500		±3
500 < L ≤ 1000		±4

表 1
TABLE 1



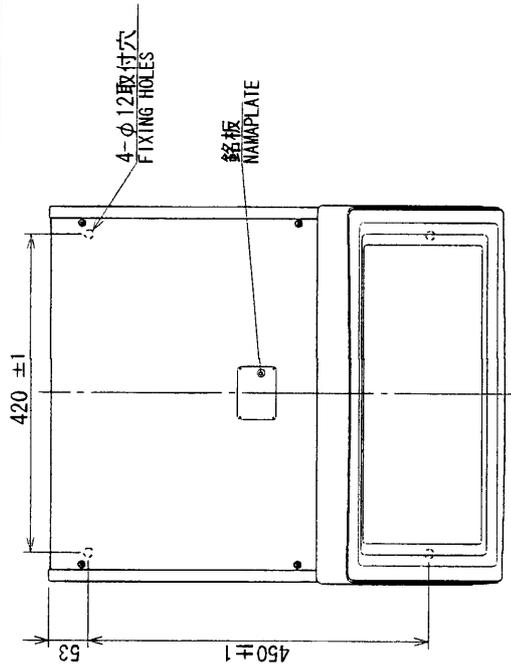
注記 1) #印寸法は最小サービス空間寸法とする。
2) 指定外の寸法公差は表 1 による。

NOTE 1. #: RECOMMENDED SERVICE CLEARANCE.

2. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS.

DRAWN Apr. 1977 T. Yamazaki	TITLE RPU-011
CHECKED Apr. 2'79 K. Kurawaki	名称 制御部
APPROVED Apr. 5'79 K. Kurawaki	外寸図
SCALE 1/10	NAME PROCESSOR UNIT
MASS 17 kg	OUTLINE DRAWING
DWG. No. C3471-G02-A	03-144-1410-G2

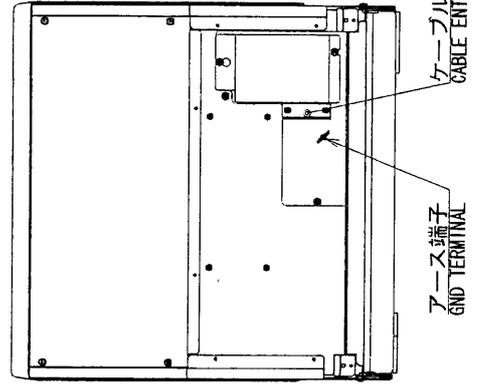
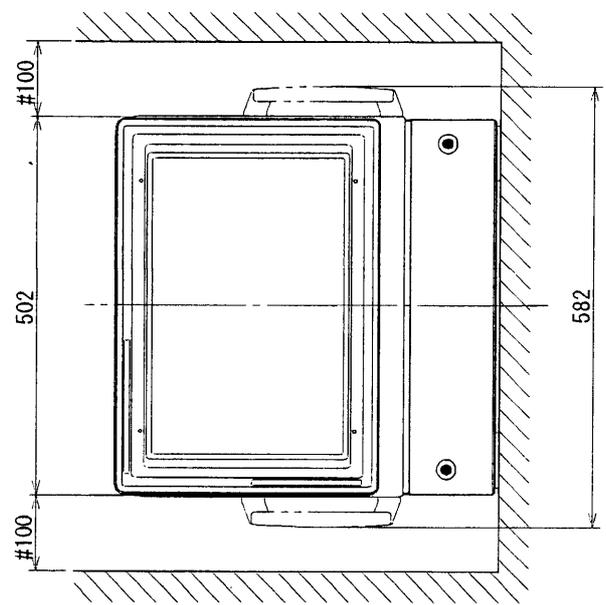
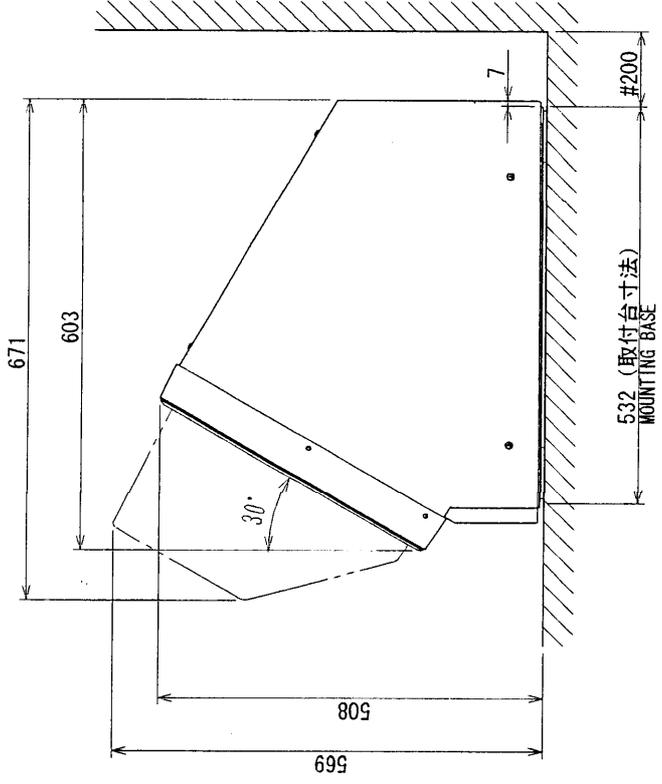
1 2 3 4



寸法区分 (mm) DIMENSION 公差 (mm) TOL

0 < L ≤ 50	±1.5
50 < L ≤ 100	±2.5
100 < L ≤ 500	±3
500 < L ≤ 1000	±4

表 1 TABLE 1



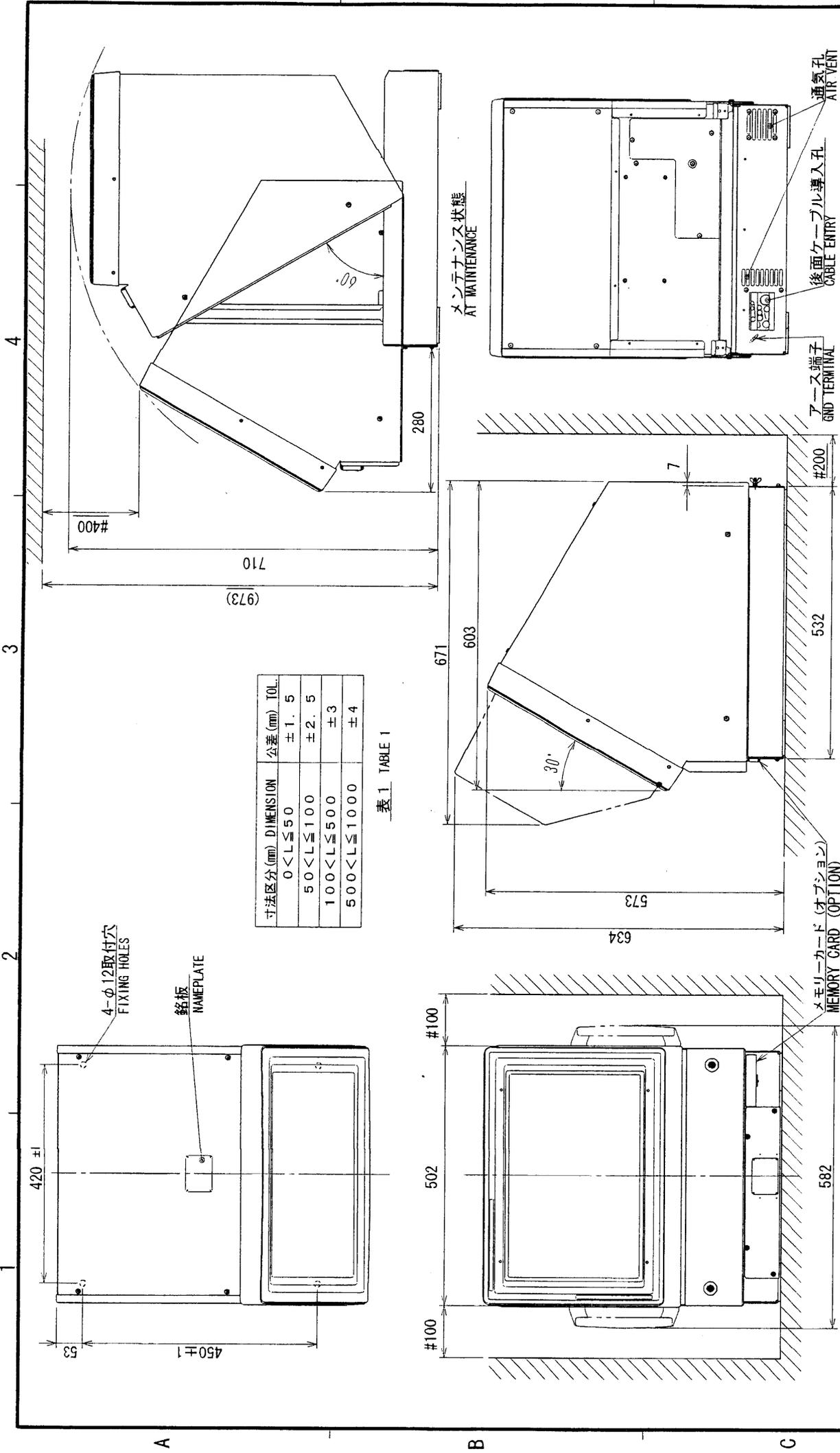
注記 1) #印寸法は最小サービス空間寸法とする。

2) 指定外の寸法公差は、表 1 による。

NOTE 1. #: RECOMMENDED SERVICE CLEARANCE.

2. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS.

DRAWN JAL 1970.10.27 Y. K.	CHECKED Y. K.	OTHERS FR-2125 FR-2115	TITLE RDP-124-M
APPROVED 1970.11.10 Y. K.	SCALE 1/10	NAME MONITOR UNIT (LESS PROCESSOR/CONTROL PANEL)	名称 モニタ一部 (制御部/パネル分離型)
MASS 47 kg	DWG. No. C3464-606-C	外寸図	外寸図
		OUTLINE DRAWING	OUTLINE DRAWING
		03-144-1030-63	



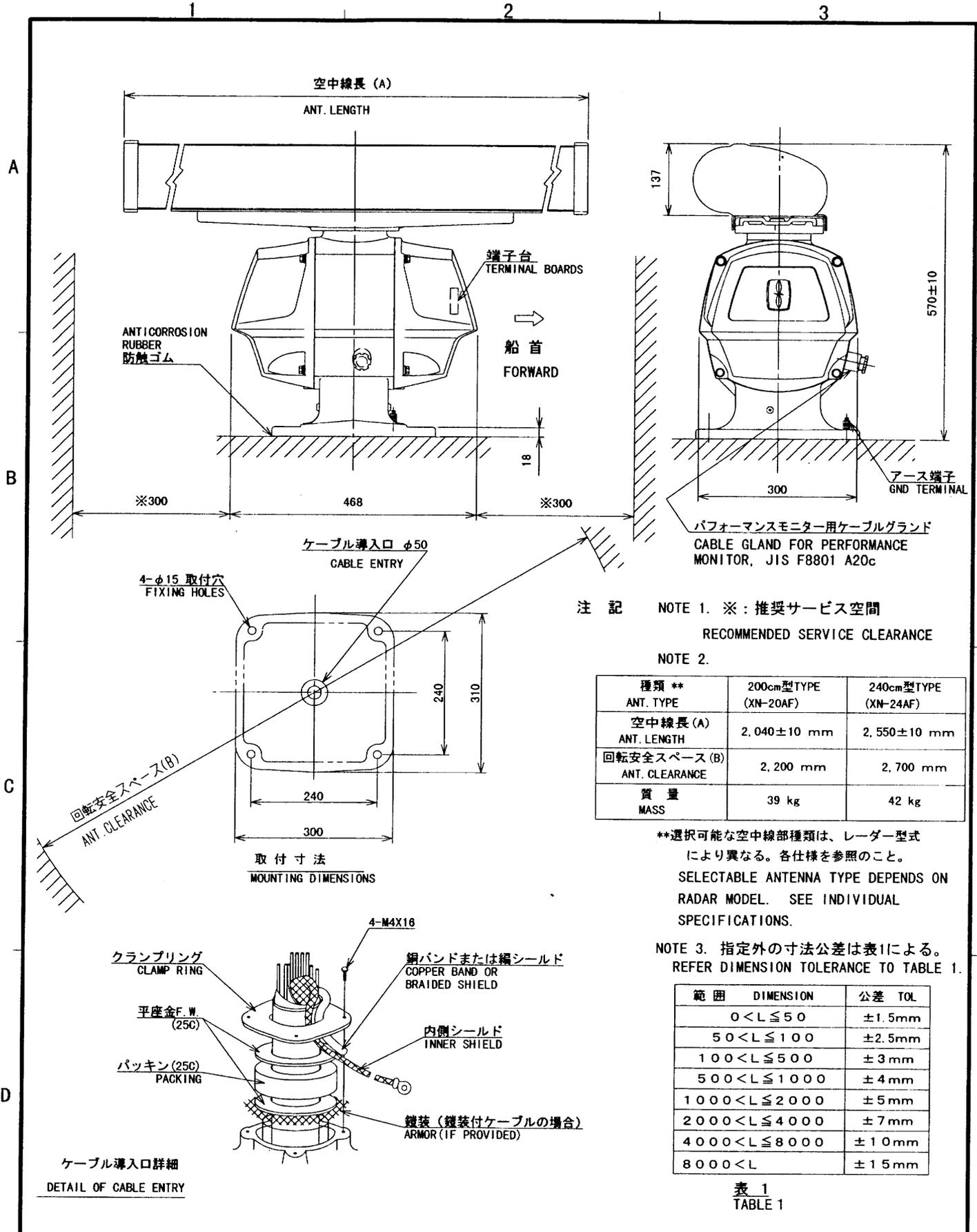
注記 1) #印寸法は最小サービス空間寸法とする。

2) 指定外の寸法公差は、表 1 による。

NOTE 1. #: RECOMMENDED SERVICE CLEARANCE.

2. TABLE 1 INDICATES TOLERANCE OF DIMENSIONS.

DRAWING 19 部 JYK/MS/K	TITLE RDP-124-M
CHECKED 19 部 Y.K.	名称 モニター部 (操作部分離型)
APPROVED 19 部 Y.K.	外寸図
SCALE 1/10 MASS ± 10%	NAME MONITOR UNIT (LESS CONTROL PANEL)
DWG. No. C3464-607-G	OUTLINE DRAWING



注記 NOTE 1. ※: 推奨サービス空間
RECOMMENDED SERVICE CLEARANCE
NOTE 2.

種類 ** ANT. TYPE	200cm型TYPE (XN-20AF)	240cm型TYPE (XN-24AF)
空中線長 (A) ANT. LENGTH	2,040 ± 10 mm	2,550 ± 10 mm
回転安全スペース (B) ANT. CLEARANCE	2,200 mm	2,700 mm
質量 MASS	39 kg	42 kg

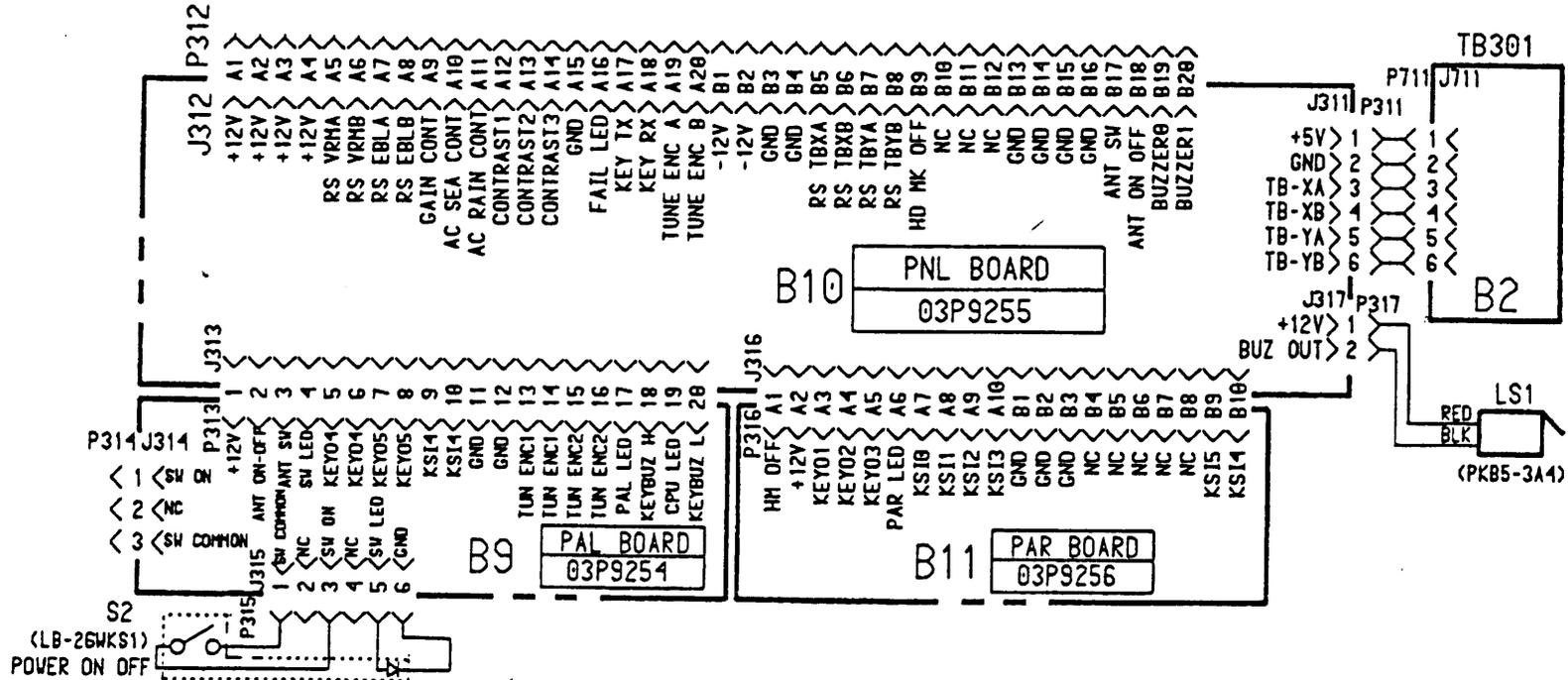
**選択可能な空中線部種類は、レーダー型式により異なる。各仕様を参照のこと。
SELECTABLE ANTENNA TYPE DEPENDS ON RADAR MODEL. SEE INDIVIDUAL SPECIFICATIONS.

NOTE 3. 指定外の寸法公差は表1による。
REFER DIMENSION TOLERANCE TO TABLE 1.

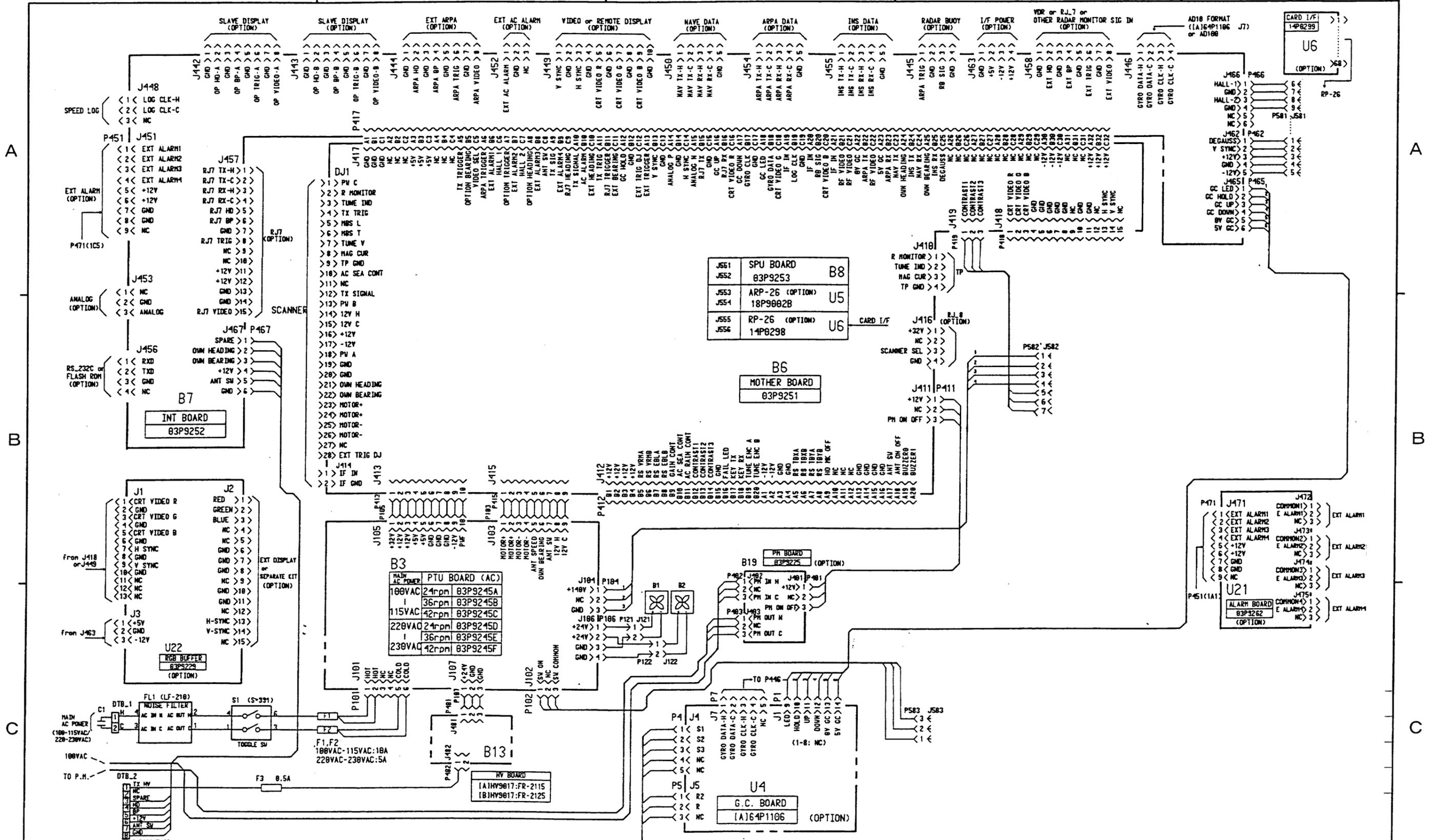
範囲	DIMENSION	公差 TOL
0 < L ≤ 50		±1.5mm
50 < L ≤ 100		±2.5mm
100 < L ≤ 500		±3mm
500 < L ≤ 1000		±4mm
1000 < L ≤ 2000		±5mm
2000 < L ≤ 4000		±7mm
4000 < L ≤ 8000		±10mm
8000 < L		±15mm

表 1
TABLE 1

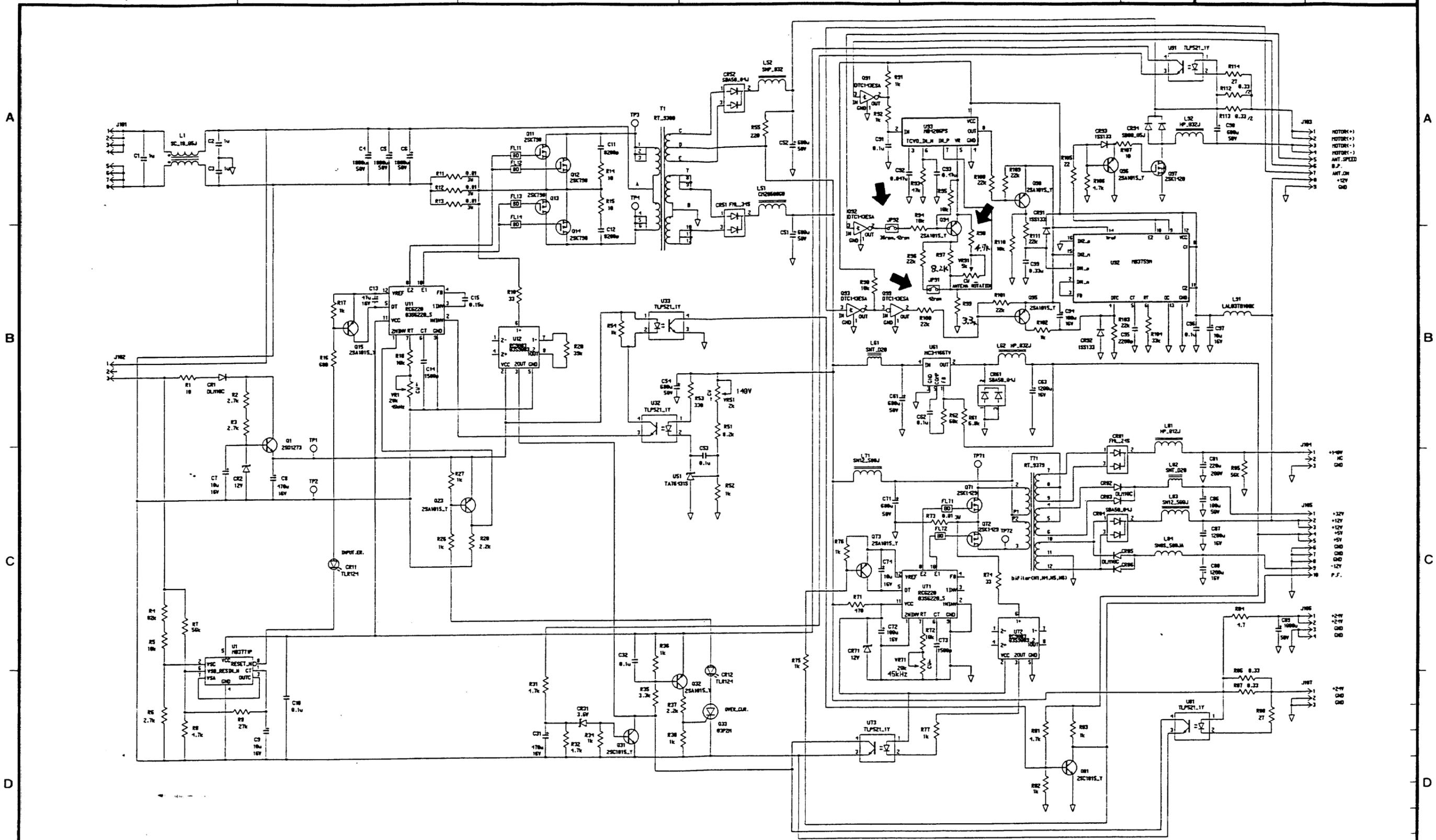
DRAWN Aug 20 '99 T.YAMASAKI		TITLE RSB-0074/0075-20/24AF
CHECKED Aug 20 '99 K.Kusumoki	OTHERS FR-1500 SER.	名称 空中線部
APPROVED Aug 20 '99 K.Kusumoki	FR-1700 SER. FR-2115/2125	外寸図
SCALE 1/10 MASS kg		NAME ANTENNA UNIT
DWG. No. C3464-G02-D	03-143-3000-G2	OUTLINE DRAWING



DRAWN Aug 26 '99 T. YAMASAKI			TYPE RCU-011
CHECKED Aug 26 '99 K. Kusuruki	FR-2135SB		名称 操作部 (総合)
APPROVED Aug 26 '99 K. Kusuruki	FR-2155-B		回路図
SCALE	MASS kg	APPLICABLE TO; (MODEL)	BLOCK NO.
DWG NO. C3483-K02- A			NAME CONTROL UNIT (GENERAL)
		03-144-6008- 10	SCHMATIC DIAGRAM

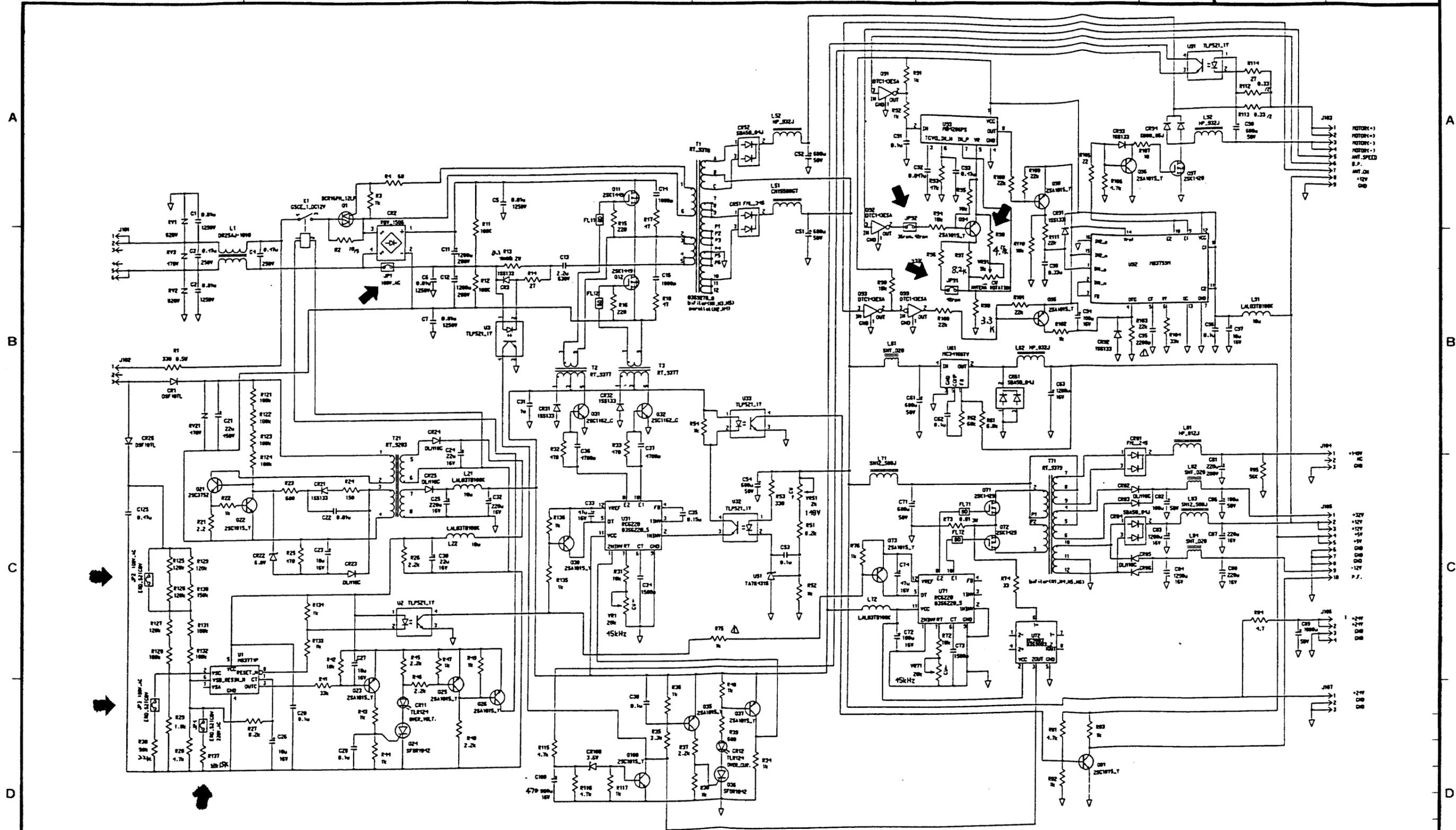


DRAWN Aug 26 '99 T. YAMASAKI	TYPE RPU-011
CHECKED Aug 26 '99 K. Kawanishi	名称 制御部 (総合)
APPROVED Aug 26 '99 K. Kawanishi	回路図
SCALE MASS kg	APPLICABLE TO; (MODEL)
DWG NO. C3483-K01-A	BLOCK NO. 03-144-6008-10
NAME PROCESSOR UNIT (GENERAL)	
SCHEMATIC DIAGRAM	



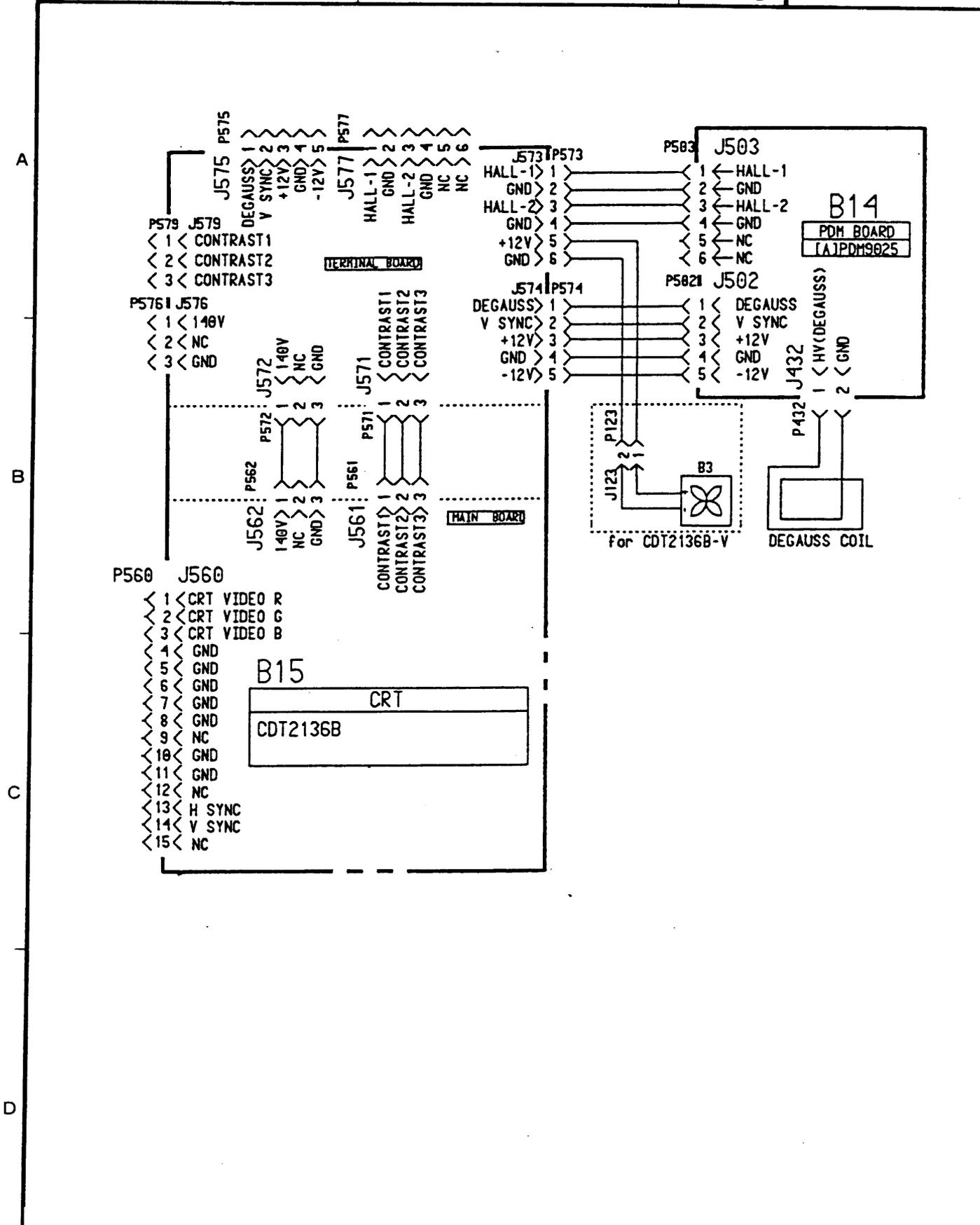
PWB	ANTENNA	JP91	JP92	R98
03P9246 A	24rpm	Cut	Cut	4.7 k
03P9246 C	42rpm	Cut	Short	1.2 k

DRAWN <i>Sep. 4 '98 E. Kusaka</i>	TYPE 03P9246
CHECKED <i>Sep 4 '98 K. Okamoto</i>	名称 DC電源基板
APPROVED <i>Sep 2 '98 M. Yamamoto</i>	FR-2125 FR-2115 回路図
SCALE MASS kg	APPLICABLE TO; (MODEL)
BLOCK NO.	NAME PTU BOARD(DC)
DWG NO. C3464-K18- B	03-144-6020- 5
SCHEMATIC DIAGRAM	

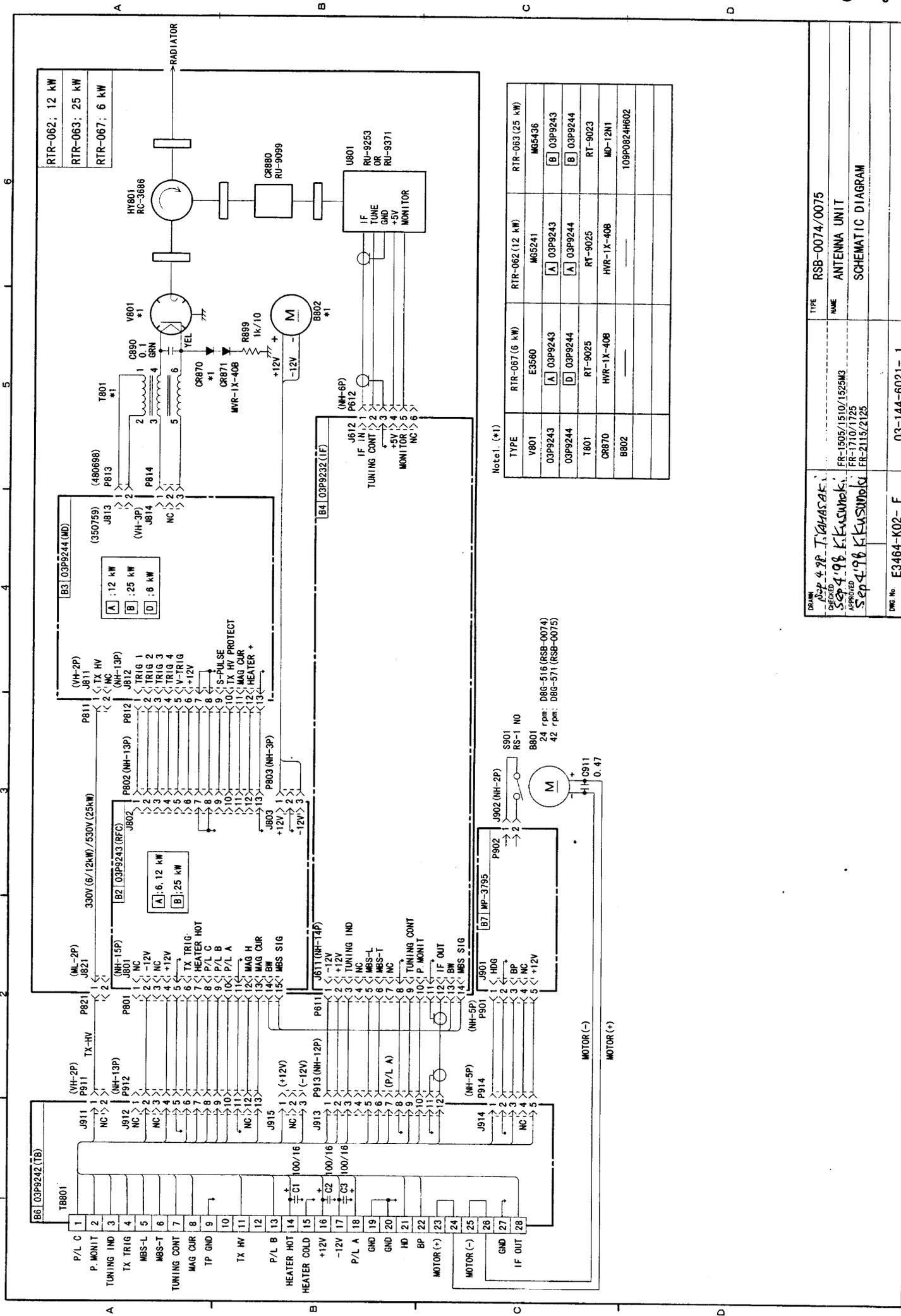


PWB	POWER	ANTENNA	JP1	JP2	JP3	JP4	JP91	JP92	R98
03P9245 A	100 VAC	24rpm	Short	Short	Short	Cut	Cut	Cut	4.7 k
03P9245 C	100 VAC	42rpm	Short	Short	Short	Cut	Cut	Short	1.2 k
03P9245 D	220 VAC	24rpm	Cut	Cut	Cut	Short	Cut	Cut	4.7 k
03P9245 F	220 VAC	42rpm	Cut	Cut	Cut	Short	Cut	Short	1.2 k

DRAWN <i>Sep 4 '99 E. Kishino</i> CHECKED <i>Sep 4 '99 K. Okamoto</i> APPROVED <i>Sep 6 '99 M. Yamamoto</i> SCALE / MASS kg	FR-2125 FR-2115 APPLICABLE TO; (MODEL)	TYPE 03P9245 名称 AC電源基板 回路図 NAME PTU BOARD (AC)
DWG NO. C3464-K03-C	BLOCK NO. 03-144-6019-6	NAME SCHEMATIC DIAGRAM



DRAWN <i>Aug 26 '99 T. YAMASAKI</i>	FR-2135SB FR-2155-B FR-2125-B FR-2115-B	TYPE RDP-124-M
CHECKED <i>Aug 26 '99 K. Kusunoki</i>	APPLICABLE TO; (MODEL)	名称 モニター部 (総合)
APPROVED <i>Aug 26 '99 K. Kusunoki</i>	BLOCK NO.	回路図
SCALE /	MASS kg	NAME MONITOR UNIT(GENERAL)
DWG NO. C3483-K03- A	03-144-6008- 10	SCHEMATIC DIAGRAM



TYPE	RTR-067 (6 kW)	RTR-062 (12 kW)	RTR-063 (25 kW)
V801	E3560	M65241	M65436
03P9243	A 03P9243	A 03P9243	B 03P9243
03P9244	D 03P9244	A 03P9244	B 03P9244
T801	RT-9025	RT-9025	RT-9023
CR870	HVR-1X-40B	HVR-1X-40B	MD-12N1
B802			109P0824H602

Note1. (*1)

DRAWN 2024.09.08 T. KAWASAKI CHECKED 2024.09.08 K. KAWASAKI APPROVED 2024.09.08 K. KAWASAKI	TYPE RSB-0074/0075 NAME ANTENNA UNIT SCHEMATIC DIAGRAM
FR-1505/1510/1525M3 FR-1710/1725 FR-2115/2125	DWG. No. E3464-K02-F 03-144-6021-1

A

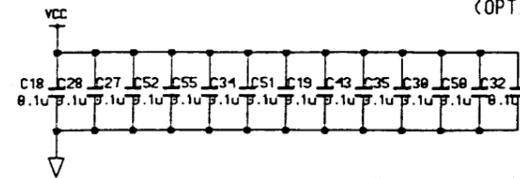
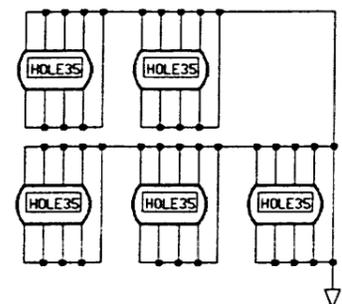
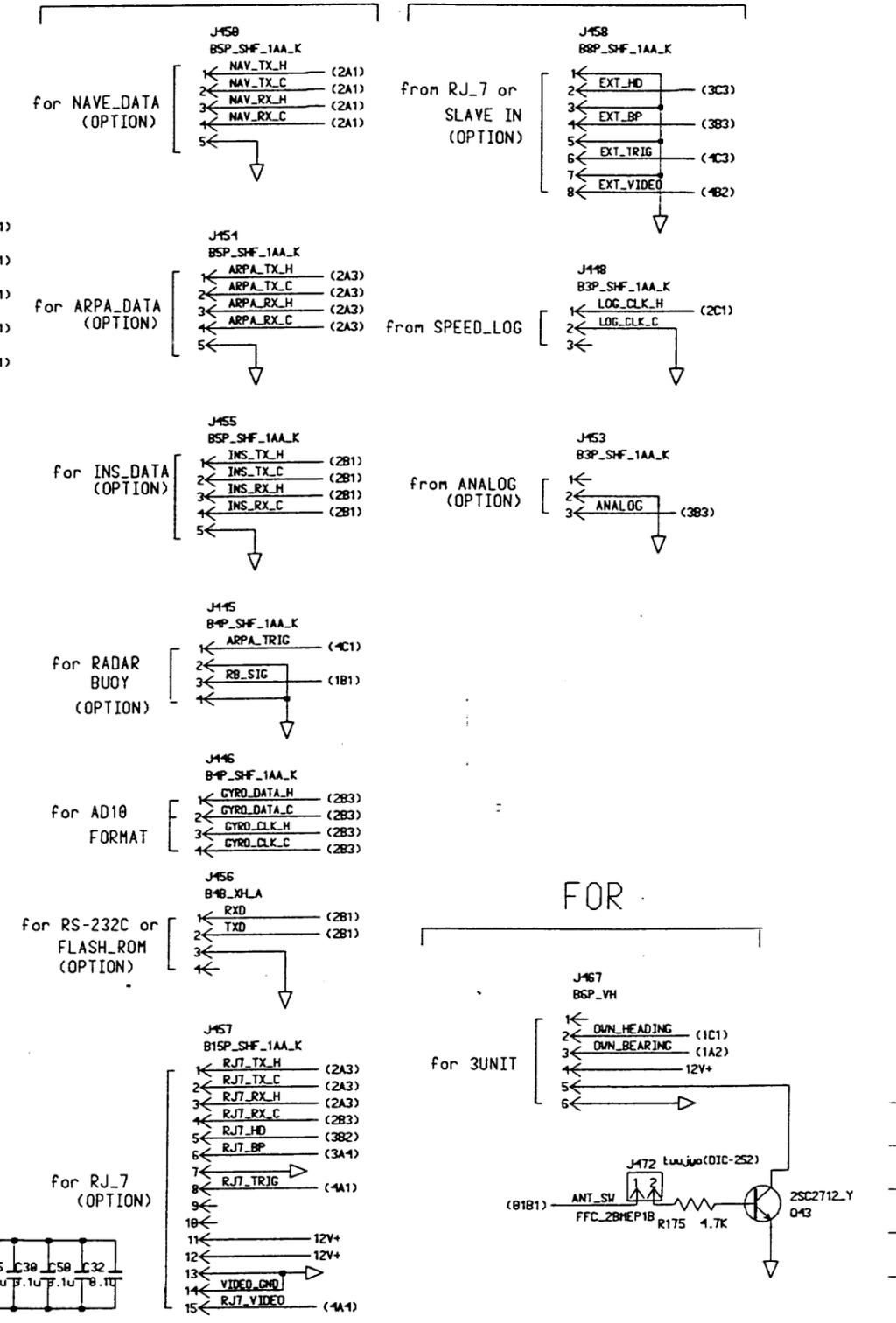
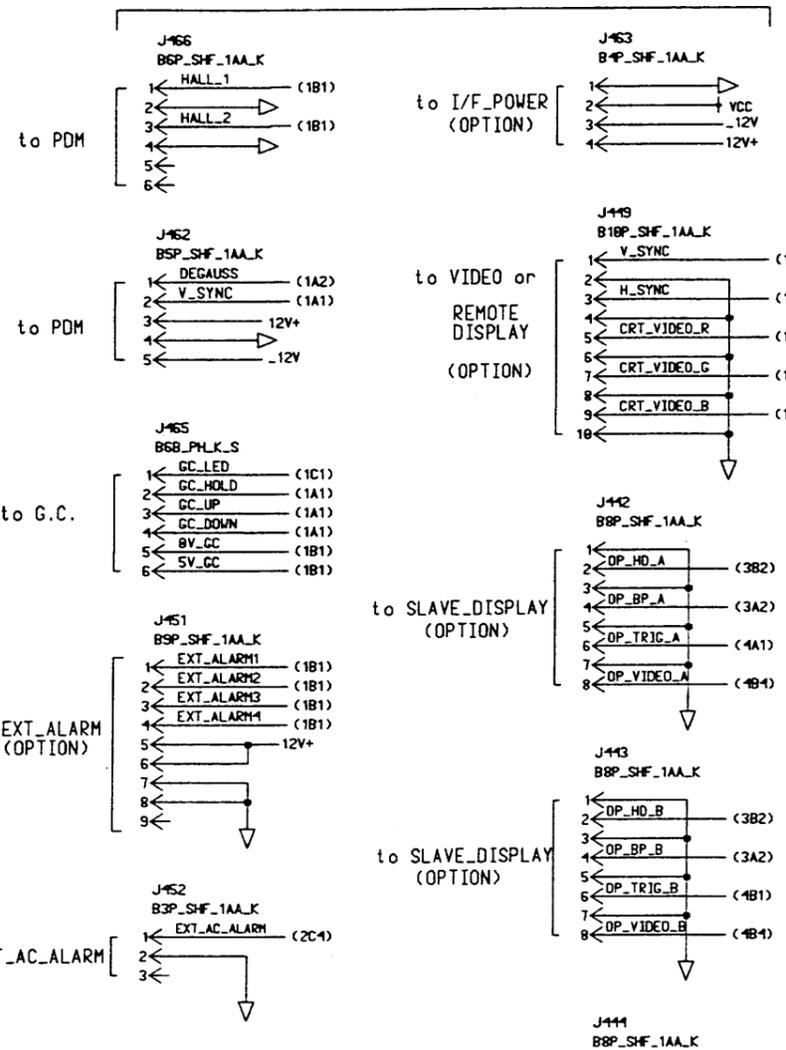
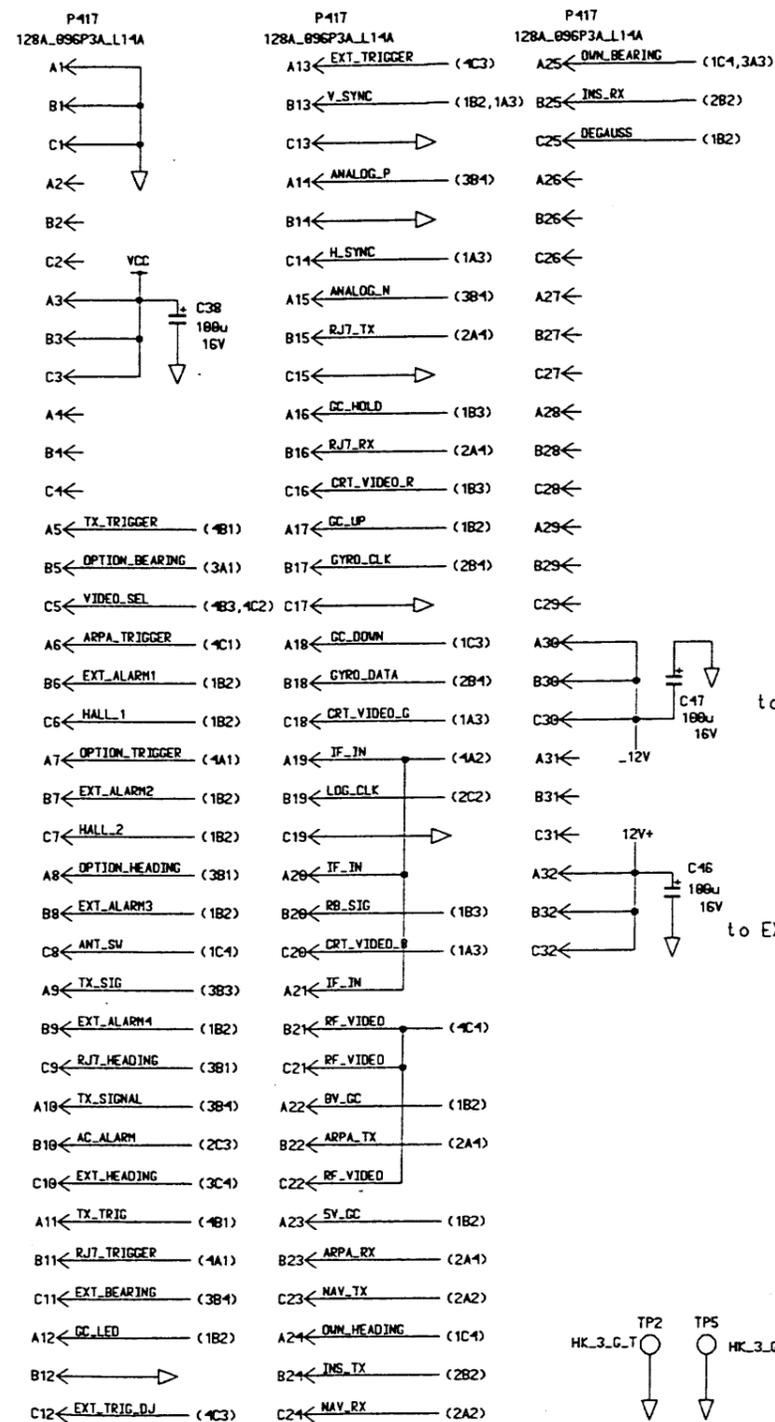
B

C

A

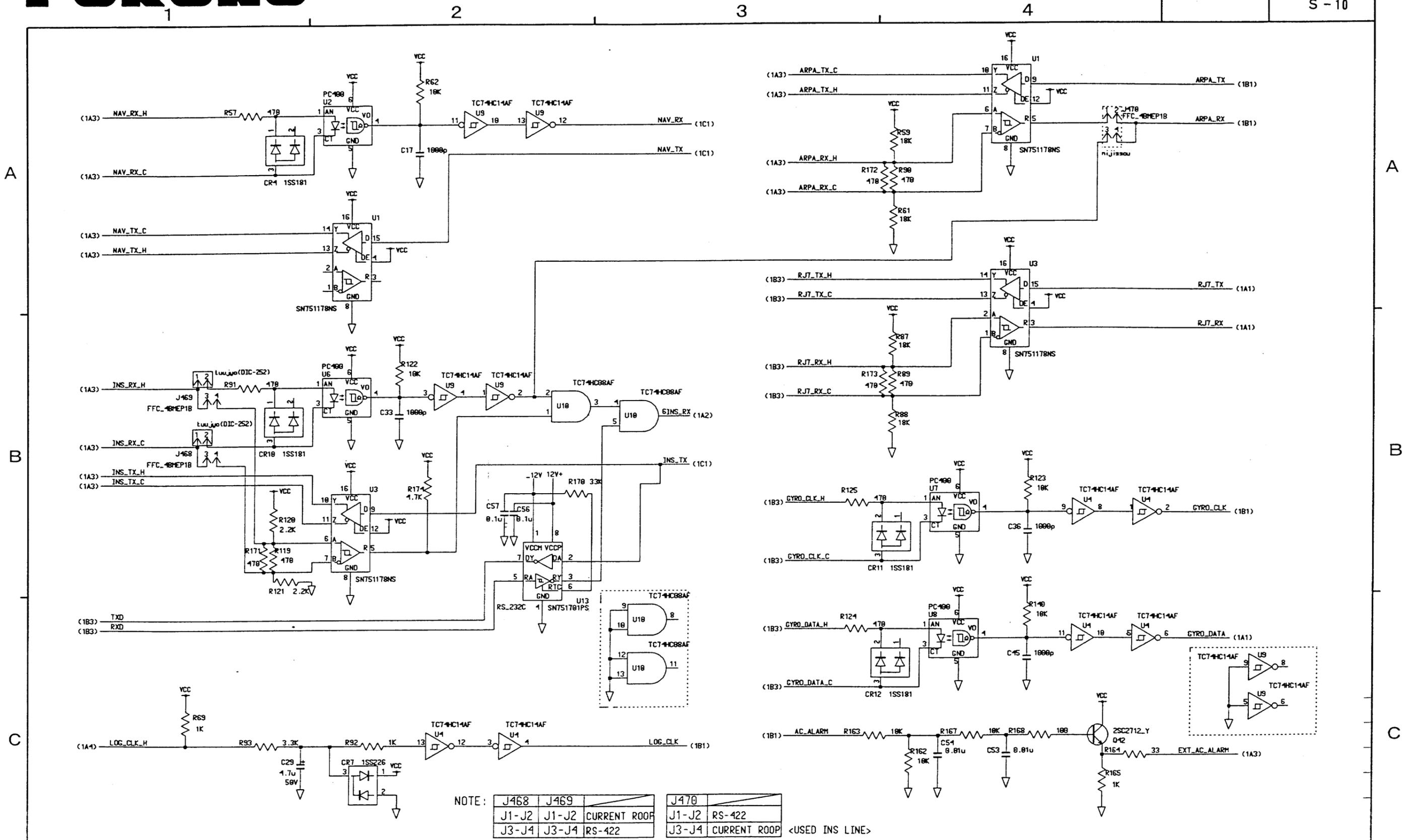
B

C

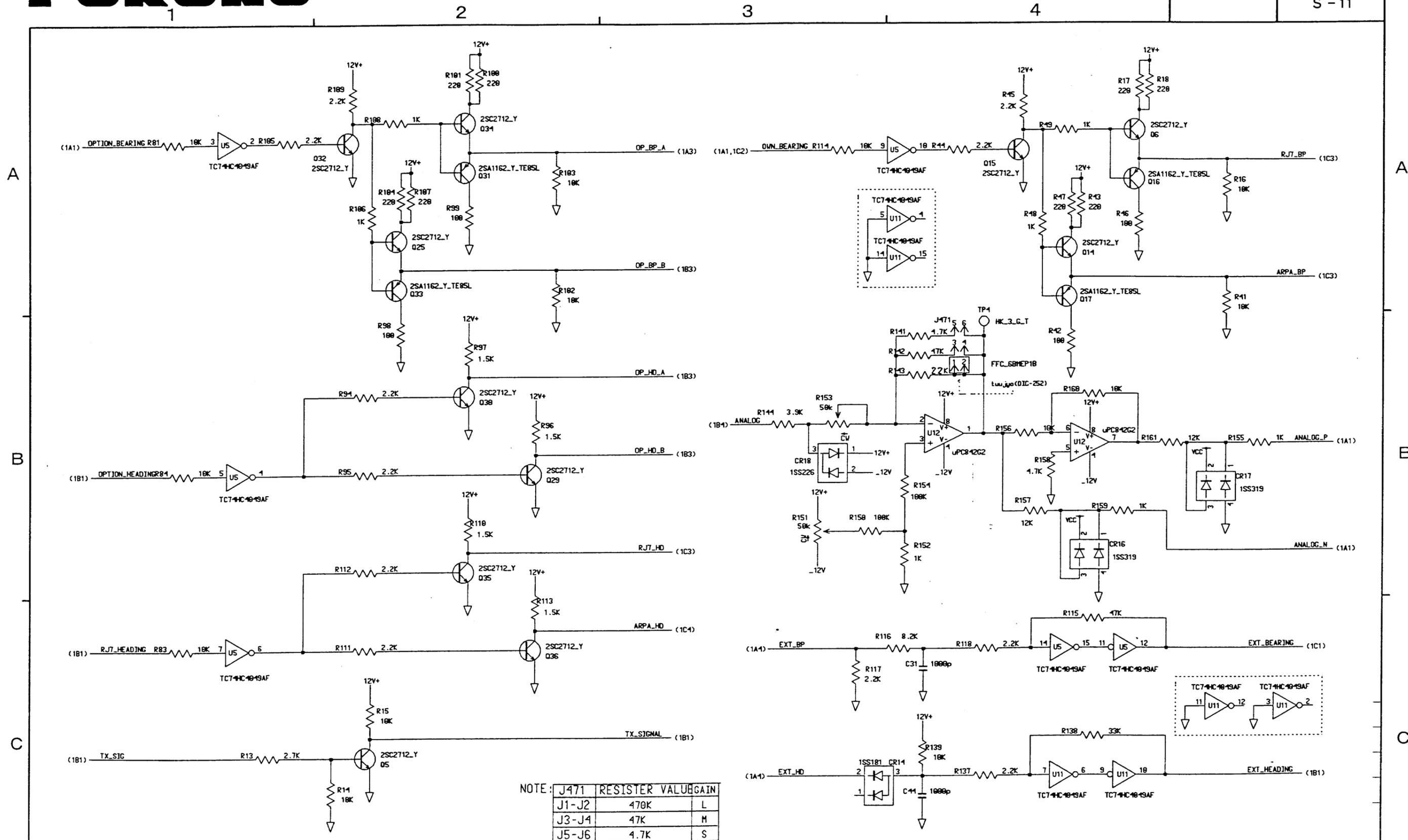


DRAWN Apr. 21 '99 T. YAMASAKI	CHECKED Apr. 21 '99 K. Kusumoki	APPROVED Apr. 21 '99 K. Kusumoki	SCALE /	MASS kg	OTHERS FR-2125 FR-2115	APPLICABLE TO; (MODEL)	BLOCK NO.	TYPE 03P9252	名称 INT基板 (1/4)
DWG NO. C3464-K08-B								NAME INT BOARD(1/4)	
03-144-6011-5								SCHEMATIC DIAGRAM	





DRAWN Apr. 21 '99 T.YAMASAKI CHECKED Apr. 21 '99 K.Kusuruki APPROVED Apr. 21 '99 K.Kusuruki SCALE / MASS kg	OTHERS FR-2125 FR-2115 APPLICABLE TO: (MODEL)	BLOCK NO. NAME INT BOARD(2/4)	TYPE 03P9252 名称 INT基板 (2/4) 回路図 NAME INT BOARD(2/4)
DWG NO. C3464-K09- B		BLOCK NO. 03-144-6011- 5	
SCHEMATIC DIAGRAM			



NOTE: J471 RESISTER VALUE GAIN

J1-J2	470K	L
J3-J4	47K	M
J5-J6	4.7K	S

DRAWN Apr. 21 '99 T. YAMASAKI CHECKED Apr. 21 '99 K. KUSUROKI APPROVED Apr. 21 '99 K. KUSUROKI	OTHERS FR-2125 FR-2115	TYPE 03P9252 名称 INT基板 (3/4) 回路図 NAME INT BOARD (3/4)
SCALE MASS kg	APPLICABLE TO: (MODEL)	BLOCK NO. NAME INT BOARD (3/4)
DWG NO. C3464-K10-B	03-144-6011-5	SCHEMATIC DIAGRAM

A

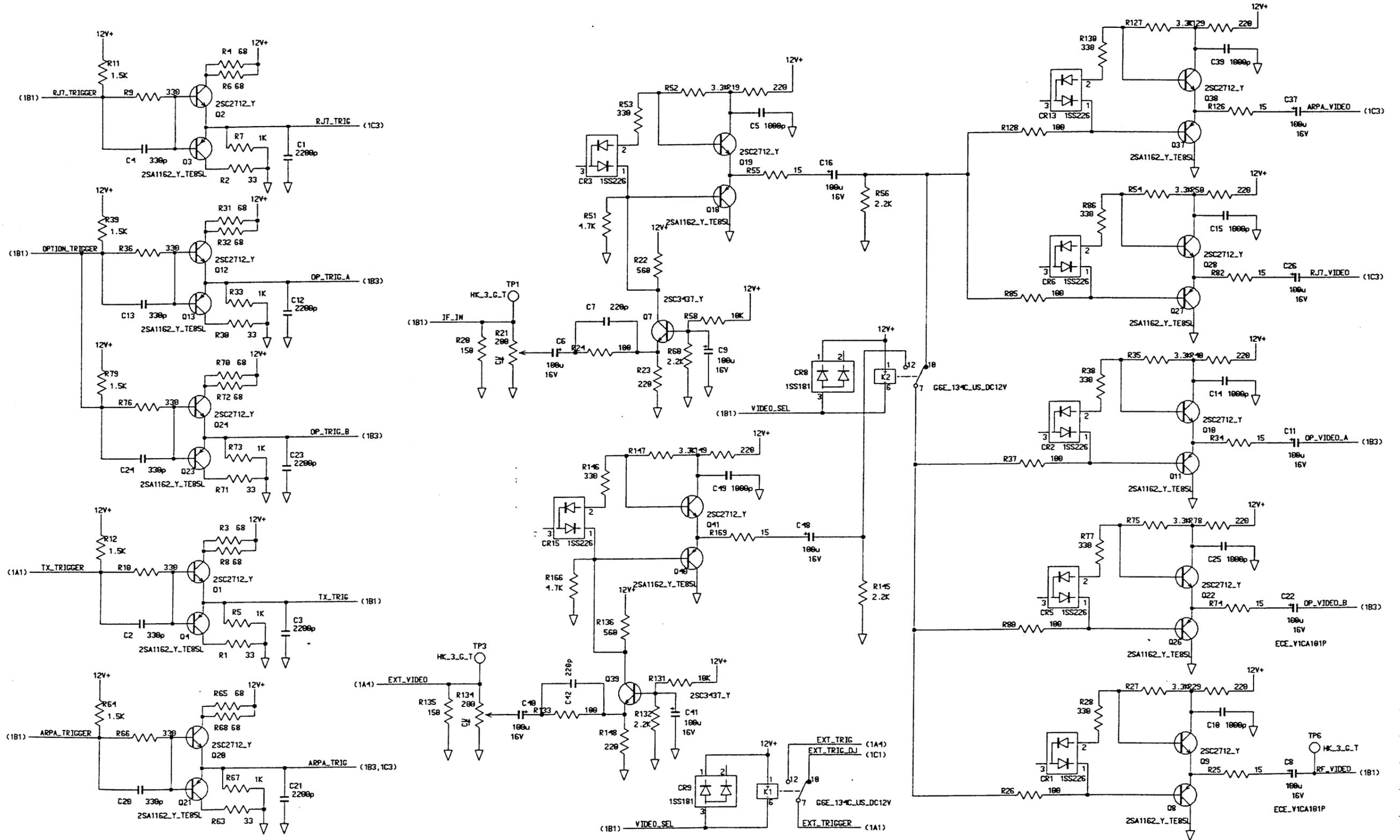
A

B

B

C

C



DRAWN Apr 21 '99 T.YAMASAKI CHECKED Apr 21 '99 K.Kusuwaki APPROVED Apr 21 '99 K.Kusuwaki SCALE / MASS kg DWG NO. C3464-K11-B	OTHERS FR-2125 FR-2115 APPLICABLE TO: (MODEL)	TYPE 03P9252 名称 INT基板(4/4) 回路図 NAME INT BOARD(4/4) BLOCK NO. 03-144-6011-5
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