

XEV22D Driver for Stepper Electronic Expansion Valves Installation and Operation Manual





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1 Introduction

1.1. General Warning

Please read the following safety precautions and warnings before using this manual:



CAUTION!

• *This manual is part of the product and should be kept near the controller for easy and quick reference.*

- *The controller should not be used for purposes different from those described in this manual. It cannot be used as a safety device.*
- *Check the application limits before proceeding.*



SAFETY PRECAUTIONS AND WARNINGS!

• *Check that the supply voltage is correct before connecting the controller.*

• *Do not expose to water or moisture: use the controller only within the operating limits and avoid sudden temperature changes with high atmospheric humidity to prevent condensation from forming.*

• *Warning! Disconnect all electrical connections before performing any kind of maintenance.*

• *Fit the probe where it is not accessible by the end user. The controller must not be opened.*

• *In case of failure or faulty operation, send the controller back to Retail Solutions (see address) with a detailed description of the fault.*

• *Verify the maximum current that can be applied to each relay (see Section 15, Specifications).*

• *Ensure that the wires for probes, loads, and the power supply are separated and far enough from each other, without crossing or intertwining.*

• *In case of applications in industrial environments, the use of main filters (our mod. FT1) in parallel with inductive loads could be useful.*

2 Overview

2.1. General Description

The XEV22D controller is capable of driving a wide variety of stepper electronic expansion valves. The controller regulates the superheat (SH) of the fluid that runs into the refrigeration unit to obtain optimized performance and functioning of the evaporator independent of climate or load conditions.

XEV22D controllers are equipped with two (2) probe inputs, one for a 4 to 20mA (or 0 to 5V) pressure transducer and another one for a Pt1000 or NTC temperature probe.

The LAN connection transmits the pressure signal to the other XEVs; this allows the use of only one pressure transducer in multiplexed cabinet applications. The controller can also have two (2) configurable digital inputs, the first one is free of voltage and the other one is at high voltage, to simplify connections with cooling request signal.

With the integrated display, it is possible to see the superheat (SH) value, the degree of valve opening, or the probe values; the local keyboard enables the controller to be programmed without any other devices.

An RS485 serial link connects the controller to other Emerson monitoring and supervising systems.

2.2. Ordering Code

Device Name	Dixell Code	Emerson Code
XEV22D	XEV22D-1C0F0B X0JFGAESG3NA-000	318-5001

Table 2-1 - Product Ordering Code

3 Wiring Connections

The superheat regulation is performed only when the cooling digital input is enabled. **Figure 3-1** shows how the device takes the request of cooling:

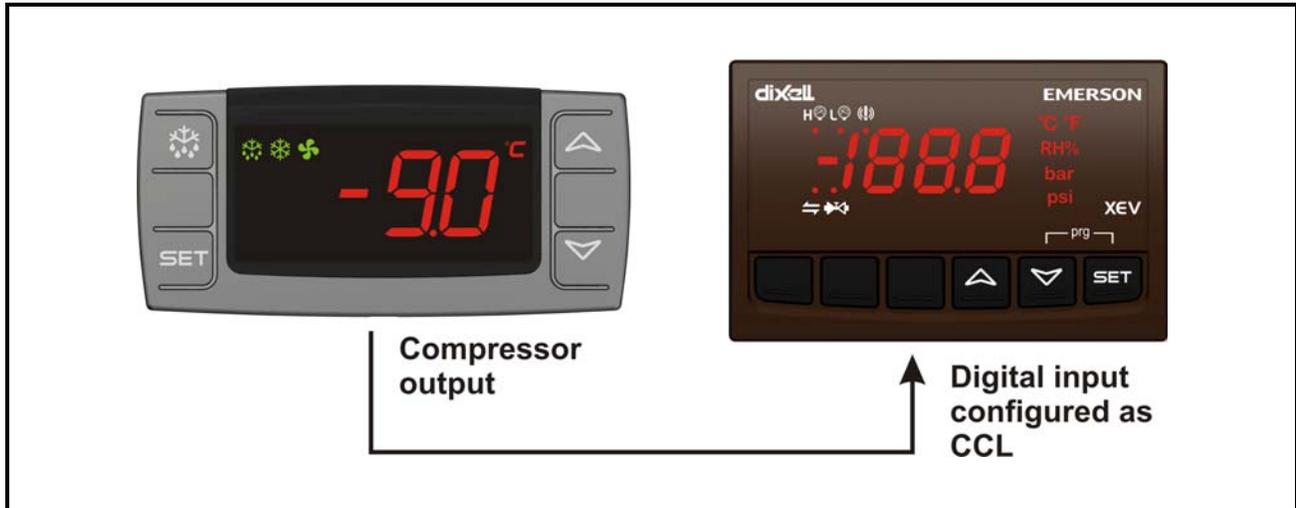


Figure 3-1 - How XEV22D Acts on Cooling Request

See **Figure 3-2** for wiring. The “First Level” indicates the connections on the floor of the 4-DIN module and “Second Level” indicates the connections on the first floor that are only for the stepper motor of the valve and for the Hot Key.

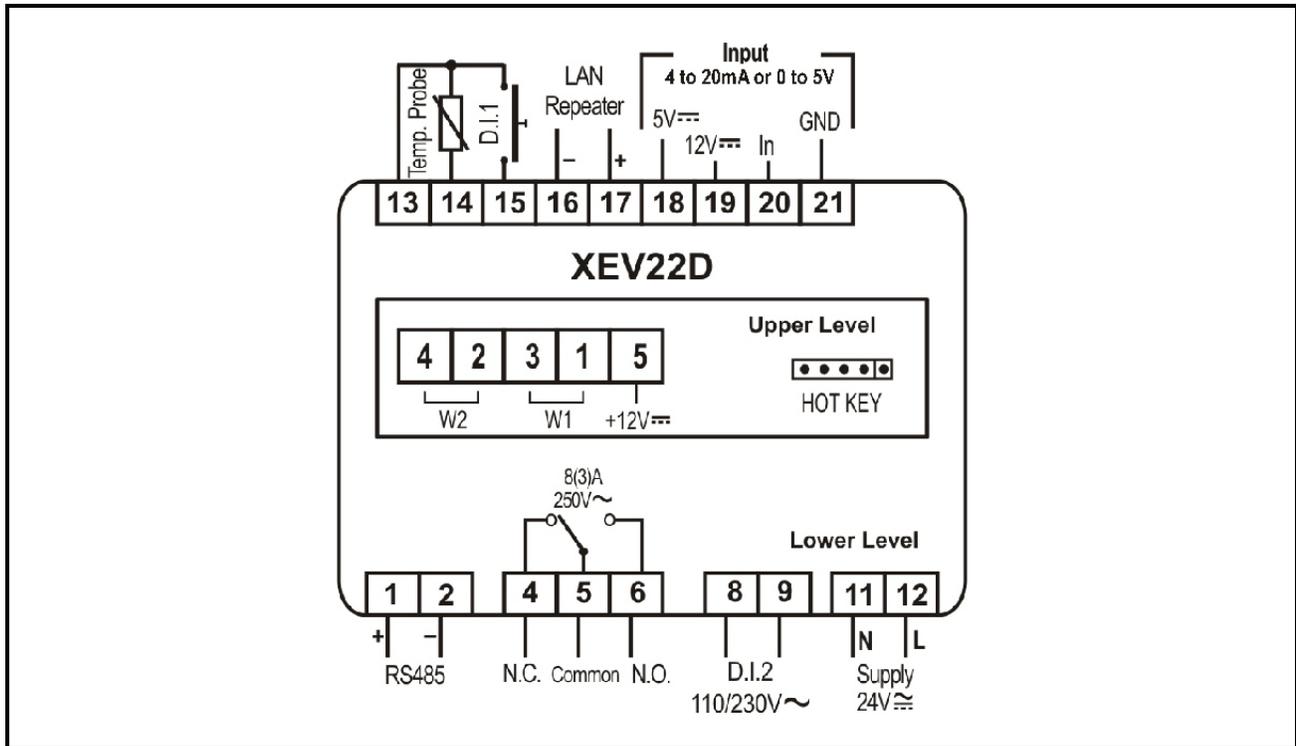


Figure 3-2 - XEV22D Wiring Connections

4 Valve Connections and Configuration



CAUTION! To avoid possible problems, before connecting the valve configure the driver by making the right changes on the parameters. Select the kind of motor (tEU parameter) and check if the valve is present in the tEP parameter table reported below:

tEP	Model	LSt (steps*10)	uSt (steps*10)	CPP (mA*10)	CHd (mA*10)	Sr (step/s)
0	Manual settings	Par	Par	Par	Par	Par
1	Sporlan SEI 0.5-20	10	159	20	5	200
2	Sporlan SEI 30	20	319	20	5	200
3	Sporlan SEH 50-250	40	638	20	5	200
4	Alco EX5-EX6	10	75	40	10	450
5	Alco EX7	25	160	75	25	330
6	Alco EX8 330 step/s	25	260	80	50	330
7	Alco EX8 500 step/s	25	260	80	50	500
8	Danfoss ETS-25/50	20	262	14	8	120
9	Danfoss ETS-100	30	353	14	8	120
10	Danfoss ETS-250/400	35	381	14	8	120

Table 4-1 - tEP Parameter Table

If you can locate your valve in the table, select the valve through the tEP parameter. This way, you can be sure of the correct configuration (refer to **Table 4-1**).

Regarding connections, use **Table 4-2** below for a quick reference on the connection mode for valves of different manufacturers. In any case, the unique and valid reference has to be considered the datasheet made by manufacturer of the valve:

Connection Numbering	ALCO EX*	ALCO EX 5/6	SPORLAN SEI-SHE	DANFOSS ETS
4	WHITE	BLUE	WHITE	BLACK
2	YELLOW	BROWN	BLACK	WHITE
3	BROWN	BLACK	RED	RED
1	GREEN	WHITE	GREEN	GREEN

Table 4-2 - 4-Wire Valves (Bipolar)

5 Absolute Maximum Power

Connection Numbering	SPORLAN	SAGINOMIYA
4	ORANGE	ORANGE
2	RED	RED
3	YELLOW	YELLOW
1	BLACK	BLACK
5- Common	GRAY	GRAY

Table 4-3 - 5 to 6 Wire Valves (Unipolar)



NOTE: After making the connection, switch the XEV controller OFF and ON to make sure that the valve is positioned properly.

The XEV22D controller is capable of driving a wide range of stepper valves; listed in *Table 5-1* are the maximum values of current that the actuator can supply to the stepper wiring. Use the TF20D transformer.



NOTE: The electrical power absorption of the valve can be unrelated to refrigeration power that the valve has. Before using the actuator, read the technical manual of the valve supplied by the manufacturer and check the maximum current used to drive the valve to verify that they are lower than indicated below in *Table 5-1*.

VALVE TYPE	Bipolar Valves (4 Wires)	Maximum Current 0.9A
	Uni-polar Valves (5 to 6 Wires)	Maximum Current 0.9A

Table 5-1 - Maximum Allowable Valve Current

6 Front Panel



Figure 6-1 - XEV22D Front Panel

6.1. Keys and Functions

Table 6-1 shows the keys found on the front panel of the XEV22D and their corresponding functions:

Key	Function
SET	To display and to modify the set point. In programming mode, it selects a parameter or confirms a value.

Table 6-1 - XEV22D Front Panel Keys and Functions

	By pressing and releasing this key, it is possible to see the values of the probes. In programming mode, it slides the codes of the parameters or increases their values.
	In programming mode, it slides the codes of parameters or decreases their values.
Key Combinations	
	To lock and unlock the keyboard.
SET +	To enter programming mode.

Table 6-1- XEV22D Front Panel Keys and Functions

6.2. XEV22D LEDs

Each LED function is described in Table 6-2:

LED	Mode	Function
	ON	Low pressure alarm
	ON	Maximum operating pressure alarm
	OFF	Valve is completely closed
	BLINKING	Valve is moving
	ON	Valve is completely opened
	BLINKING	Serial communication present
	OFF	Serial communication absent
	ON	Superheat alarm

Table 6-2 - XEV22D LEDs

7 User Interface

7.1. To See the Read-Only Values

1. Press and release the UP arrow key.
2. The first read-only label is displayed.
3. Slide labels using the UP or DOWN arrow keys.
4. Press the SET key to see the read-only value. To change and view the parameter, press SET.
5. To exit the fast access menu, press and release the SET + UP arrow keys or wait for the device time-out for 3 minutes.

7.2. To See the Setpoint

1. Press the SET key until the setpoint is displayed.
2. To return and view the temperature, wait for 5 seconds or press the SET key again.

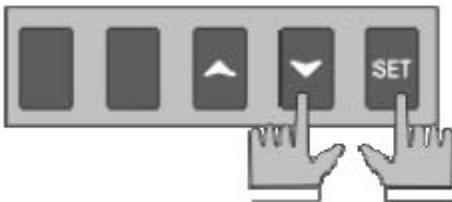
7.3. To Modify the Setpoint

To change the setpoint value, operate as follows:

1. Press the SET key until the set point is displayed.
2. Use the UP or DOWN arrow keys to change its value.
3. Press SET to store the new value.

7.4. To Enter Pr1 Parameters List

To enter in **Pr1** level menu:



1. Press the SET + DOWN arrow keys for about 3 seconds.

2. The device will display the first parameter in **Pr1** menu.

7.5. To Enter Pr2 Parameters List

To enter to **Pr2** parameters list:



1. Enter the **Pr1** level menu.
2. Select **Pr2** parameter and press SET.
3. The **PAS** label will be displayed followed by a blinking **0**.
4. Insert **321** password using the UP and DOWN arrow keys.

7.6. To Modify the Parameters Value

To change the parameter's value operate as follows:

1. Enter the programming mode by pressing the SET and DOWN arrow keys for about 3 seconds.
2. Select the required parameter.
3. Press the SET key to display its value.
4. Use the UP or DOWN arrow keys to change its value.
5. Press the SET key to store the new value and move to the next parameter.
6. To exit, press SET + UP or wait 30 seconds without pressing a key.



NOTE: The set value is stored even when the time-out expires and ends the procedure.

7.7. How to Assign a MODBUS Address

1. To enter the programming mode, press and hold the SET and DOWN arrow keys together for about three (3) seconds or until the dots at the top of the display start flashing.
2. Arrow down to **PR2** and press SET to select.
3. **PAS** for password will display and flash.
4. Use the arrow keys to set the **321** password. Press SET to save.



NOTE: If a time-out occurs while setting the password (PR2 flashes), press SET to resume entering the password.

5. Use the arrow keys to scroll through and locate **Nod**. Press SET. Use the arrow keys to scroll through and locate **Std**. Press SET.
6. Use the arrow keys to scroll through and locate **Adr**. Press SET. Use the arrow keys to choose the address number of the device. Press SET to save.
7. To exit, press the SET and UP arrow keys together or wait 15 seconds without pressing a key.

8 Parameters

NOTE: All pressure parameters are relatives or absolutes depending on the PrM parameter.

Code	Description	Function
REGULATION		
Fty	Kind of gas	(R22, 134, 404, 407, 410, 507, CO2) Type of gas used by plant. <i>Fundamental parameter for correct functioning of all systems.</i>
PEo	Probe error opening percentage	(0 to 100%) If a temporary probe error occurs, valve opening percentage is PEo until PEd time is elapsed. If PEo is different from 0 , it ensures cooling also with probe error, because even if the device cannot calculate superheat, the valve can work at PEo percentage.
PEd	Probe error delay before stopping regulation	(0 to 239 sec – 240 = On = unlimited) If the probe error duration is bigger than PEd , valve closes completely. The Pf message is displayed. If PEd = On , valve opening is PEo until probe error finishes.
tEU	Type of stepper motor	(uP - bP) Selects the kind of valve. uP = 5 to 6 wires unipolar valves bP = 4 wires bipolar valves CAUTION! <i>By changing this parameter, the valve has to be re-initialized.</i>
tEP	Predefined valve selection	(0 to 10) If tEP = 0 , the user has to configure all the parameters to use the valve. If tEP is different from 0 , the controller performs a fast configuration of the following parameters: LSt , Ust , Sr , CPP , and CHd . To select the correct value, refer to Table 4-1 . If tEP is different from 0 , previous configuration of LSt , Ust , Sr , CPP , and CHd <u>are overwritten</u> .
LSt	Minimum number of steps	(0 to Ust) Selects the minimum number of steps. At this number of steps, the valve should be closed. Read the manufacturer datasheet to set this parameter correctly. The number of steps should be set within the advised range of functioning. CAUTION! <i>When this parameter is changed, the valve must be re-initialized. The controller performs this procedure automatically and restarts its normal functioning when the programming mode ends.</i>
Ust	Maximum number of steps	(LSt to 800*10) Selects the maximum number of steps. At this number of steps, the valve should be opened completely. Read the datasheet provided by the valve manufacturer to set this parameter correctly. The maximum number of steps should be set within the advised range of functioning. CAUTION! <i>When this parameter is changed, the valve must be re-initialized. The controller performs this procedure automatically and restarts its normal functioning when the programming mode ends.</i>

Table 8-1 - List of Parameters

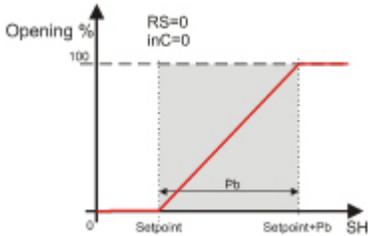
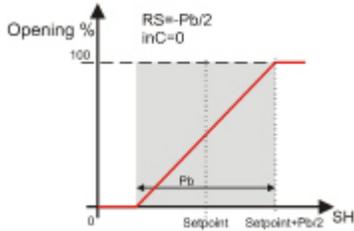
Code	Description	Function
Sr	Step rate	(10 to 600 step/sec) Maximum speed to change a step without losing precision (= losing steps). Set parameter under the maximum speed.
CPP	Current per phase (Only bipolar valves)	(0 to 100 * 10mA) Maximum current per phase used to drive valve.
CHd	Holding current per phase (Only bipolar valves)	(0 to 100 * 10mA) The current per phase when the valve is stopped for more than 4 minutes.
oPE	Start opening percentage	(0 to 100%) Opening valve percentage when the start function is active and during post defrost phase. This phase duration is SFd time.
SFd	Start function duration	(0.0 to 42.0 min: tens of seconds) It sets start function duration and post-defrost duration. <i>During this phase, the alarms are neglected.</i>
Sti	Stop regulation interval	(0.0 to 24.0 hours: tens of minutes) After regulating continuously for Sti time, the valve closes for Std time to prevent ice from forming.
Std	Stop duration	(0 to 60 min) Defines the stop regulation time after Sti . During this stop, display shows StP message.
MnF	Maximum opening percentage at normal functioning	(0 to 100%) During regulation, it sets the maximum valve opening percentage.
FOP	Forced opening percentage	(0 to 100 - not used) If FOP = not used , valve works with regulation algorithm. If FOP is different from not used , the valve stays at FOP opening percentage. This function could be useful during plant starting or during service operations.
PI PARAMETERS (For use of trained staff only)		
Pb	Proportional band (0.1 to 50.0 / 1 to 90°F) PI proportional band. A value bigger than 5°C is advised.	
rS	Band offset (-12.0 to 12.0°C / -21 to 21°F) PI band offset. It moves the proportional band of the PI . With rS = 0 , the band is between Set to Set + Pb .	
InC	Integration time	(0 to 255 sec) PI integration time
PROBE PARAMETERS		

Table 8-1 - List of Parameters

Code	Description	Function
tPP	Type of pressure transducer	(420 – 5V – LAN) Sets the type of pressure transducer to use: 420 = 4 to 20mA pressure transducer; 5V = 0 to 5V ratiometric transducer; LAN = the pressure signal comes from another XEV module.
LPP	Enable pressure probe sending in LAN	(n to Y) If LPP = Y , the value of pressure read by device is sent in LAN. Only one device of the LAN can have LPP = Y .
PA4	Probe value At 4mA or At 0V	(-1.0 to P20 bar/ -14 to PSI) Pressure value measured by probe at 4mA or at 0V (related to PrM parameter).
P20	Probe value 20mA or At 5V	(PA4 to 50.0 bar/ 725 psi) Pressure value measured by probe at 20mA or at 5V (related to PrM parameter).
OPr	Pressure probe calibration	(-12.0 to 12.0 bar/ -174 to 174 psi)
ttE	Type of temperature probe	(PtM to ntC) Sets the kind of probe used by the controller: PtM = Pt1000, ntC = NTC probe.
otE	Temperature probe calibration	(-12.0 to 12.0°C/ -21 to 21°F)
DIGITAL INPUTS		
i1P	Digital input 1 (free of voltage) digital input polarity	(CL, OP) CL = activated when closed; OP = activated when opened
i1F	Digital input 1 (free of voltage) digital input function	(CCL, rL) CCL = cooling call; rL = digital input activates relay
d1d	Digital input 1 (free of voltage) activation delay	(0 to 255 min) This activation delay is used only if digital input is configured as rL .
i2P	Digital input 2 (high voltage) digital input polarity	(CL,OP) CL = activated when closed; OP = activated when opened
i2F	Digital input 2 (high voltage) digital input function	(CCL, rL) CCL = cooling call; rL = digital input activates relay
d2d	Digital input 2 (high voltage) activation delay	(0 to 255 min) This activation delay is used only if digital input is configured as rL .
ALARM		
dAo	Alarm delay after restarting regulation	(0.0 to 42.0 min: tens of seconds) Time between digital input activation (configured as CCL) and alarm signaling. The LSH alarm is always signaled also during this time.
tdA	Type of alarm signaled by relay	(ALL, SH, PrE, di) ALL = all alarm; SH = superheat alarm; PrE = pressure alarm; di = activation only when digital input configured as rL is activated.
LPL	Lower pressure limit for superheat regulation	(PA4 to P20 bar/ psi) When the suction pressure comes down to LPL , the regulation is performed with a LPL fixed value for pressure; when the pressure comes back to LPL , the normal pressure value is used. (related to PrM parameter).
MOP	Maximum operating pressure threshold	(PA4 to P20 bar/ psi) If the suction pressure exceeds the maximum operating pressure value, the controller signals a condition with a High Pressure alarm LED (related to PrM parameter).

Table 8-1 - List of Parameters

Code	Description	Function
LOP	Lowest operating pressure	(PA4 to P20 bar/ psi) If the suction pressure comes down to this value, a low pressure alarm is signaled with Low Pressure alarm LED (related to PrM parameter).
PHY	Pressure alarm hysteresis	(0.1 to 5.0 bar/ 1 to 72 PSI) Alarm hysteresis to disable alarm signaling.
dML	delta MOP-LOP	(0 to 100%) When a MOP alarm occurs, the valve will close at the dML percentage every one second until the MOP alarm is active. When LOP occurs, the valve will open at the dML percentage every one second until LOP alarm is active.
MSH	Maximum superheat alarm	(LSH to 32.0°C/ LSH to 176°F) When the superheat exceeds this value, a high superheat alarm is signaled after interval SHd .
LSH	Lowest superheat alarm	(0.0 to MSH °C/ 32 to MSH °F) When the superheat goes down to this value, a low superheat alarm is signaled after interval SHd .
SHy	Superheat alarm hysteresis	(0.0 to 25.5°C/ 1 to 77°F) Hysteresis for superheat alarm deactivation.
SHd	Superheat alarm activation delay	(0 to 255 sec) When a superheat alarm occurs, the time SHd has to pass before signaling alarm.
FrC	Fast-recovery constant	(0 to 100 sec) Increases the integral time when SH is below the setpoint. If FrC = 0, fast-recovery function is disabled.
DISPLAY		
Lod	Local display	Display: (SH , PEr , P1 , P2) SH = superheat; PEr = valve opening percentage; P1 = value of temperature measured; P2 = pressure measured by P2 probe;
CF	Temperature measurement units	(°C to °F) °C = Celsius degree; °F = Fahrenheit degree <i>CAUTION! By changing the measurement unit, the regulation parameters have to be changed correctly.</i>
PMU	Pressure measurement units	(bAr , PSI) bAr = bar; PSI = psi <i>CAUTION! By changing the measurement unit, the regulation parameters have to be changed correctly.</i>
rES	Resolution (only °C)	(dE to in) Whether a whole number or decimal point is used in temperature reading
PrM	Pressure visualization mode	(rEL to AbS) rEL = relative pressure; AbS = absolute pressure All pressure parameters depend on this parameter.
CLP	Cooling percentage	(Read only) Displays the percentage of time during which the cooling call was active in the time interval defined by parameter CLt .
tP1	Temperature probe value	(Read only) Shows the temperature probe value from P1 .
PPr	Pressure probe value	(Read only) Shows the pressure probe value. The value depends on PrM .
tP2	Temperature from P2	Shows the temperature obtained from conversion of pressure value.

Table 8-1 - List of Parameters

Code	Description	Function
OPP	Opening percentage	Shows the actual opening percentage of the valve.
d1S	Free of voltage digital input state	(Read only) Shows the free of voltage digital input.
d2S	High voltage digital input state	(Read only) Shows the high voltage digital input state.
Adr	RS485 serial address	(1 to 247) Identifies the controller address when connected to a MODBUS compatible monitoring system.
Mod	MODBUS	(AdU to StD) AdU = (Only for XWEB systems) In this case, the XEV and the thermostat controller are considered standalone controller (it requires a custom library for XWEB); StD = to use XEV in standalone mode, in this case normal MODBUS-RTU protocol is used.
Ptb	Parameters map	(Read only) It identifies the parameters map written by factory.
rEL	Release firmware	(Read only) It shows the firmware release.
Pr2	Second level menu	

Table 8-1 - List of Parameters

9 Digital Inputs

The XEV22D comes with two (2) digital inputs: a voltage-free input and a high voltage input; both can be configured as cooling call. In this way the cooling signal can come from the controllers with direct load outputs or via the controllers with voltage-free outputs. One of these inputs must be configured as the cooling call.

10 Forced Opening

If necessary, change the **FOP** parameter to force the valve to open. For example, if **FOP** is set to **50** (**FOP = 50**), the valve will be opened at half of full scale. To disable this function, set the **FOP** to default value (**FOP = not used**). The valve opening is enabled only when **CCL** digital input is enabled.

11 Electrical Connections

The controller comes with a screw terminal block to connect cables with a cross section up to 2.5 mm². Heat-resistant cables have to be used. Before connecting the cables, verify that the power supply complies with the controller's requirements. Separate the probe cables from the power supply cables, from the outputs and the power connections. Do not exceed the maximum current allowed on each relay, in case of heavier loads, use a suitable external relay.

11.1. Probes

The recommended temperature probe placement is illustrated in *Figure 11-1*, between 0 and 180 degrees of inclination with respect to the horizontal pipe section. For suction pressure probes, there is no particular recommendation.

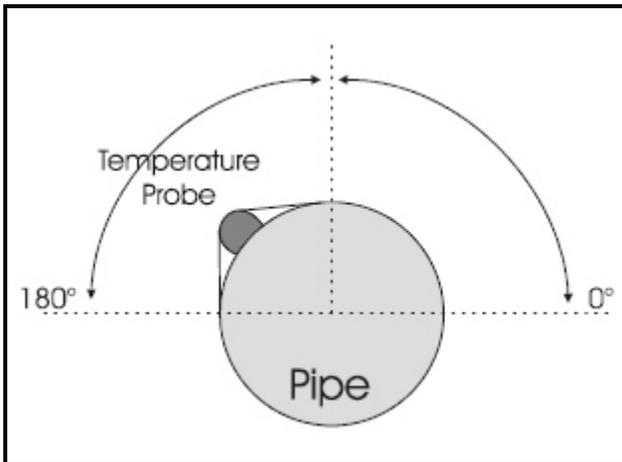


Figure 11-1 - Recommended Temperature Probe Placement

12 RS485 Serial Line

All models can be connected to the monitoring and supervising system XWEB3000. If **Mod = StD**, the standard MODBUS-RTU protocol is used; if **Mod = AdU**, the custom XWEB library is required. This last configuration makes it possible to use the same serial address of the thermostat that gives the cooling request to XEV. In this way, it is possible to reduce the number of addresses used.

13 How to Use the Hot Key



NOTE: The Err message is displayed in case an error or failure in programming occurs. In this case, turn the unit OFF and then ON if you want to restart the download or remove the Hot Key to abort the operation.

13.1. How to Program a Hot Key From the Controller (Upload)

1. Program one controller using the front keypad.
2. When the controller is ON, insert the Hot Key and press the UP arrow key; the **uPL** message will appear followed by a flashing **End** LED.
3. Push the SET key and the **End** LED will stop flashing.
4. Turn OFF the controller, remove the Hot Key, then turn it ON again.



NOTE: The Err message is displayed in case an error or failure in programming occurs. In this case, push the UP arrow key again if you want to restart the upload or remove the Hot Key to abort the operation.

13.2. How to Program the Controller Using a Hot Key (Download)

1. Turn OFF the controller.
2. Insert a programmed Hot Key into the 5-pin connector and then turn the controller ON.
3. Automatically the parameter list of the Hot Key is downloaded into the controller memory, the **doL** message will blink followed by a flashing **End** LED.
4. After 10 seconds, the controller will restart work with the new parameters.
5. Remove the Hot Key.

14 Display Messages

The controller is provided with an internal check to verify memory integrity. Alarm **EE** flashes when a failure in the internal memory is detected. In this case, call for service.

Message	Cause	Outputs
nA	None of the digital inputs configured as CCL are activated	Valve closed
Pf	The PEd time is elapsed and the regulation is stopped.	Valve closed after PEd . There is a probe error.
P1	Temperature probe fault	According to PEo and PEd
P2	Pressure transducer fault	According to PEo and PEd
HSH	High superheat alarm	By PI
LSH	Low superheat alarm	Valve closed
LPL	Low pressure limit	See LPL parameter
MOP	Maximum Operating Pressure	See dML parameter
LOP	Lowest Operating Pressure	See dML parameter
StF	Start Function enabled	See SFd parameter
StP	Regulation stop caused by Std and Sti	Valve closed
EE	Memory anomaly	

Table 14-1 - Alarm Signals

14.1. Alarm Recovery

Probe alarms **P1** and **P2** start a few seconds after the fault in the probe; they automatically stop few seconds after the probe restarts normal operation. Check the connections before replacing the probe. Maximum and minimum alarms **HSH**, **LSH**, **MOP**, and **LOP** automatically stop as soon as the variable returns to normal values.

15 Specifications

Housing	Self extinguishing ABS
Dimensions	Case: Front: 4 DIN modules, 70 mm x 135 mm with male and female connectors Depth: 60 mm
	Mounting: DIN RAIL mounted in a omega (3) din rail
Protection	IP20
Connections	Detachable screw terminal block $\leq 2.5 \text{ mm}^2$ wiring
Power Supply	24VAC/DC $\pm 10\%$
Power Absorption (depending on the valve)	20VA max
Display	Three (3) digits with icons, red LEDs, height 14.2 mm
Inputs	1 temperature probe Pt1000 or NTC
	1 pressure transducer 4 to 20mA or 0 to 5V
Digital Inputs	1 free of voltage
	1 at high voltage
Outputs for Valve	Bipolar or unipolar valves
Data Storage	On the non-volatile memory (EEPROM)
Kind of Action	1B
Pollution Grade	Normal
Software Class	A
Temperature	Operating: 0 to 60°C
	Storage: -25 to 60 °C
Relative Humidity	20 to 85% (no condensing)
Resolution	0.1°C or 1°F
Precision at 25°C	$\pm 0.7^\circ\text{C} \pm 1$ digit

Table 15-1 - XEV22D Specifications

16 E2 MODBUS Network Wiring

- Connect MODBUS Network to the RS485 Connector on the E2 PIB board (Belden 8641 recommended).
- Note to wire the RS485 +/- polarity at the E2 in the *reverse* of the XEV22D devices.
- Position the three termination jumpers to the UP (terminated) position to provide RS485 termination at the E2.
- Do not connect the shield of the MODBUS network to the E2 PIB center terminal. Instead, use a 100 ohm 1/2 watt resistor to connect the MODBUS cable shield to earth ground.
- At each XEV22D device, wire the MODBUS cable to the RS485 +/- terminals and connect the MODBUS shield to the pin **16** terminal.
- Terminate the end of the MODBUS network at the last XEV22D device on the daisy chain with the MODBUS termination block (P/N 535-2711), or by connecting a 150 ohm resistor between the MODBUS +/- terminals.

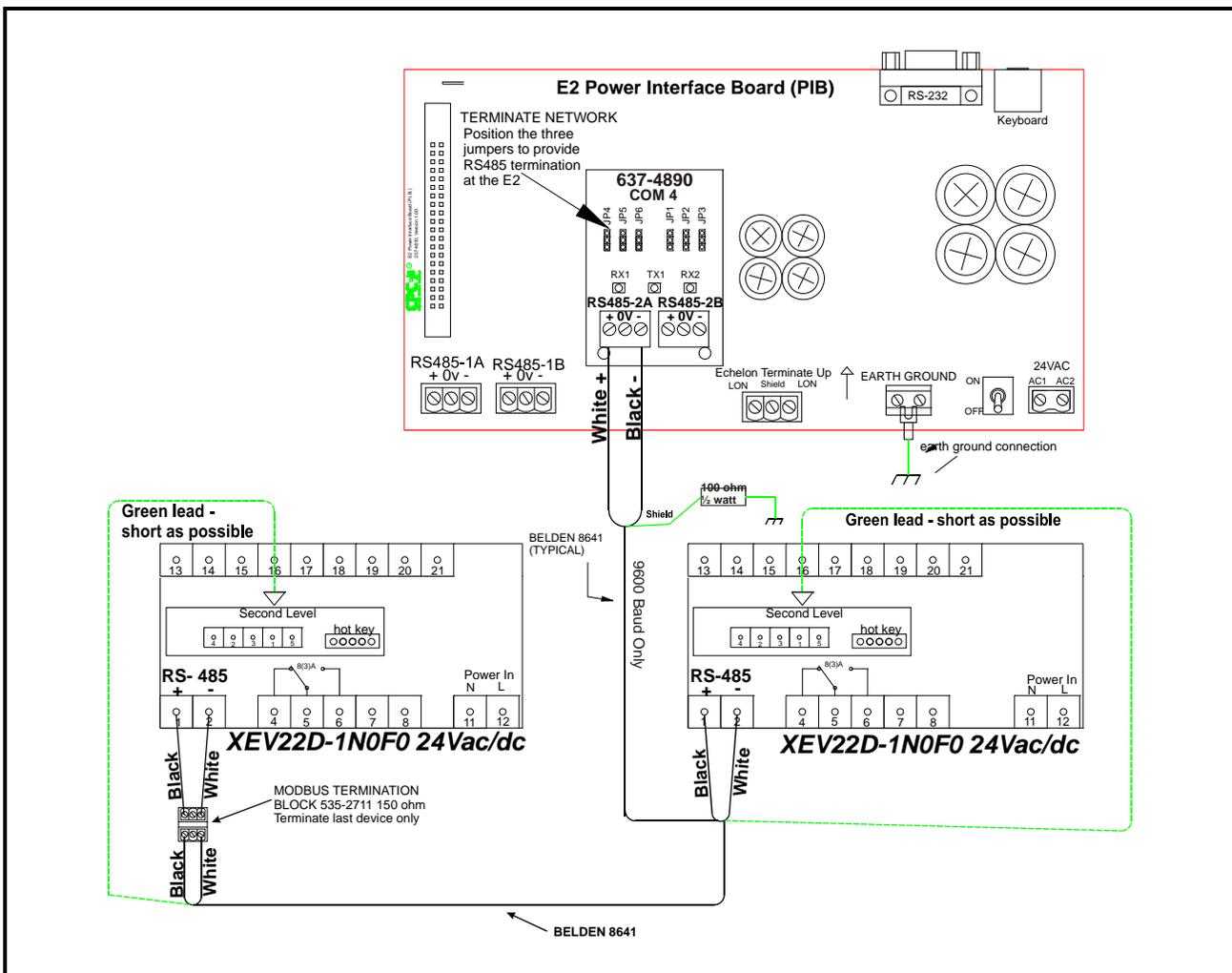


Figure 16-1 - XEV22D to E2 Wiring Diagram

17 ECT MODBUS Networking to E2s

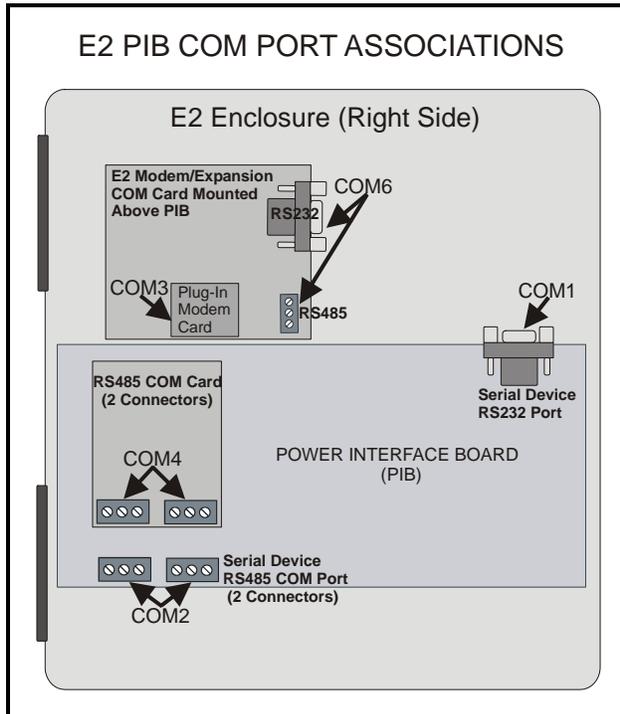


Figure 17-1 - Location of E2 COM Ports

Connecting an XEV22D controller to an E2 requires the E2 to be version 2.84 or above. Contact Retail Solutions for upgrade information if the controller is a version before 2.84.

An E2 has up to three COM ports that can be assigned for MODBUS communication: COM2, an RS485 port on the E2 power interface board, and COM4 and COM6, which are optional ports requiring expansion cards. COM4 is recommended for MODBUS connection of Emerson units.

COM ports can only be used for one function; in other words, if COM2 is set up as the I/O network, you cannot connect MODBUS devices to COM2. Ensure your E2 is equipped with an RS485 COM Card (P/N 637-4890) and configured in E2 General Services (Menu **& 7 # 3 1**, **Serial** tab) to enable COM4 or an E2 Expansion COM Card (P/N 637-4871) to enable COM6.

Connect the MODBUS network cable to the three-terminal connector on the COM port you wish to assign as MODBUS. Reverse polarity of +/- on RS485 cable from E2 to the device.

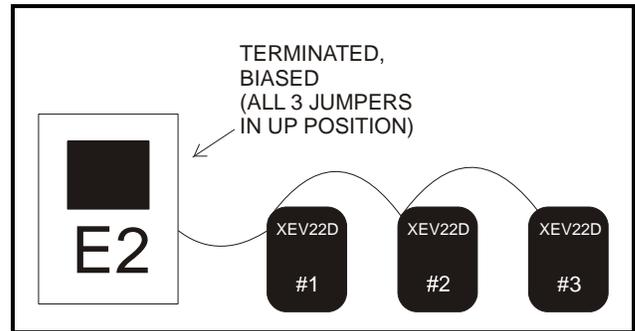


Figure 17-2 - MODBUS Networking

17.1. E2 Setup of Devices

17.1.1. Set Up Network Ports

Before setting up device, the port on the E2 that has the MODBUS cable connected must be set up as a MODBUS port.

1. Log in to the E2 with Level 4 access.
2. Press **Menu** followed by **& 7 # 3 1** - **General Controller Info**.
3. Press **Ctrl + 3** to open the **Serial** tab of the General Controller Info setup screens:

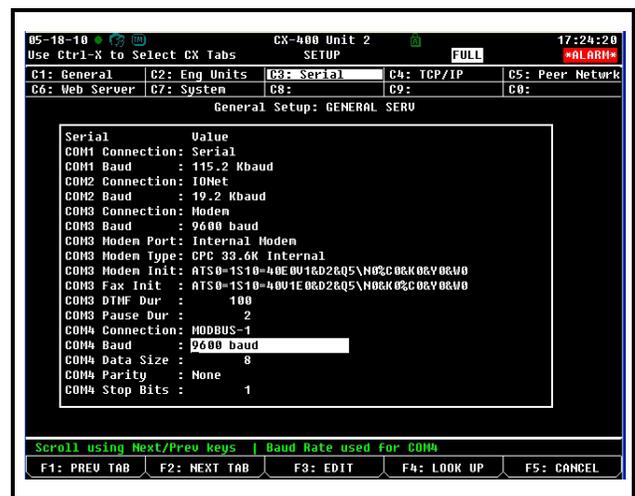


Figure 17-3 - Serial Communications Manager Screen

4. This screen will have a "Connection" field for all COM ports on the E2. Highlight the COM port connection field that will be used for the device, and press **F4** - **LOOK UP**. From the list of network types, select **MODBUS**.

- Four fields will become visible underneath the COM port connection field, which pertain to the way the device communicates:
 - Baud** - Default setting is **19.2k**. The baud rate setting should be set to match the baud rate of the device (**9600**). (All devices connected to the same COM port should be set to the same baud rate.)
 - Data Size** - Leave this field at the default value (**8**).
 - Parity** - Leave this field at the default value (**None**).
 - Stop Bits** - Leave this field at the default value (**1**).
- Press to save changes and exit.

17.1.2. Add and Connect the Device

To enable communications between E2 and the units, the devices must be added and addressed in E2.

- Log in to the E2 with Level 4 access.
- Press & **7** & **7** & **2** - **Connected I/O Boards and Controllers**.

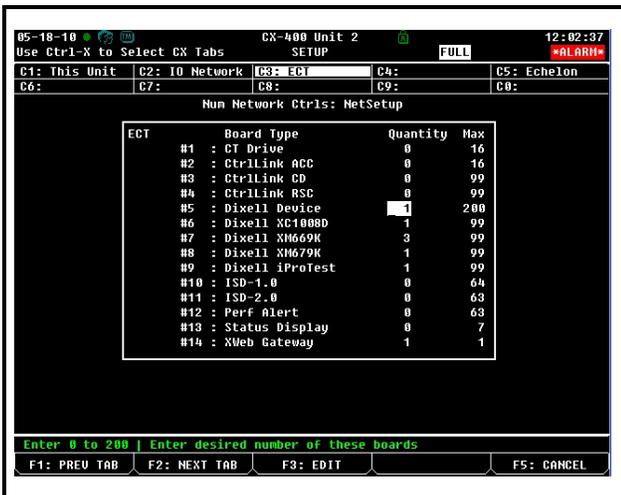


Figure 17-4 - Num Network Ctrl's: NetSetup Screen

- In the *Num Network Ctrl's: NetSetup* screen, under the **ECT** tab, enter the number of devices in the **Quantity** field. (**Max** shows the maximum number of devices allowed on the network.)
- Press to return to the *Network Setup* menu, then select **1** - **Network Summary**.
- Locate the units you added to the network list (press and to scroll through the list). If desired, en-

ter a new name for each device in the **Name** field.

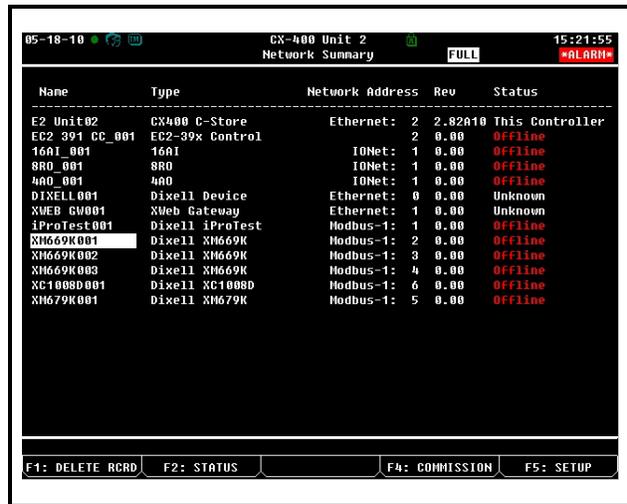


Figure 17-5 - Network Summary Screen

- By default, each device in the network list has a board number of 0. To set the address and begin communication, choose the device and press **F4**. In the list of MODBUS devices, choose the address number corresponding to the address set up through the front display, and press to select it. A window will open where you can specify the address of the controller. If a network ID has already been selected, its name will be shown next to the network ID in this list. If the network ID you are trying to assign has already been used, you must set the address on this device to a different number that is not being used.

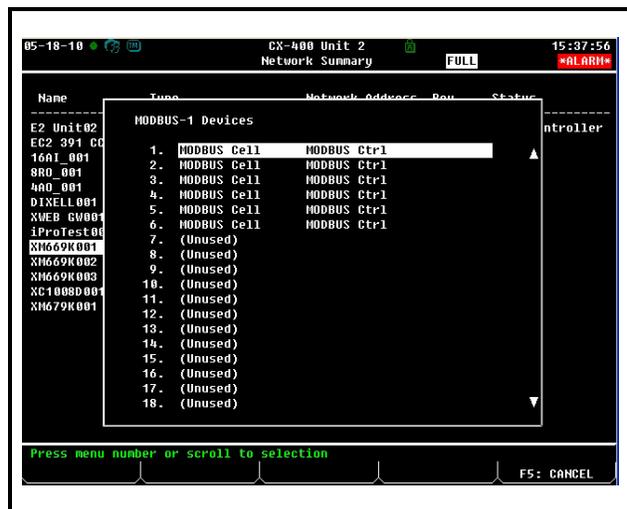


Figure 17-6 - List of MODBUS Devices

- Repeat **Steps 5** and **6** until each device has a name and address.
- When finished, press to return to the *Net-*

work Setup menu, then press **1** - **Network Summary** (Figure 17-7). Locate the devices you set up, and look at each device's status in the **Status** field. You will see one of the following messages:

- **Online** - The device is communicating normally.
- **Offline** - The device is not communicating, has not been commissioned, is not functional, or is not powered up. Verify the device is powered up, wired correctly, and has the proper network address, baud rate, and parity.
- **Unknown** - The device is not communicating or has not been commissioned. Verify the device is powered up, wired correctly, and has the proper network address, baud rate, and parity.
- **No Port** - No port is set up in the E2 Serial Configuration Manager to be a MODBUS port.
- **Wrong FW Rev** - This message is likely caused by the device having a firmware version older than the minimum revision required by E2 for communication. Replace the device with a new one or a device that has the latest version of firmware on it.

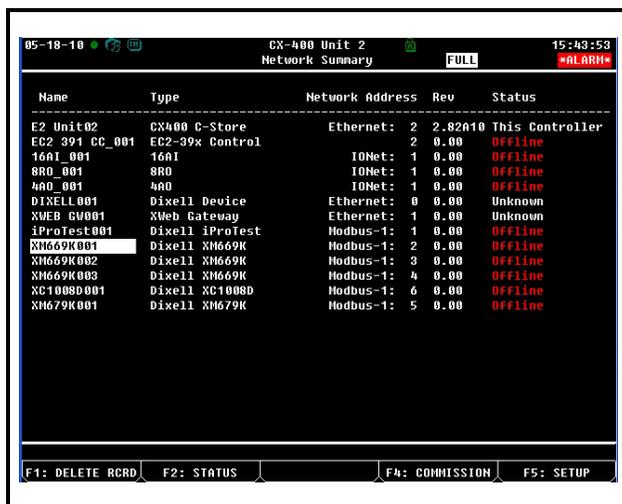


Figure 17-7 - Network Summary Screen

17.2. Wiring Types

Retail Solutions specifies Belden #8761 shielded twisted pair cables for use as MODBUS wiring (or Belden #82761 and Belden #88761 for plenum installations).

For MODBUS network wiring of XEV series of controllers to E2, Belden #8641 (CPC P/N 135-8641) is the recommended wire type to use.

If the recommended cable is not available in your area, be sure the wiring meets or exceeds the following specs:

Shielded?	Yes
Conductor Type	Twisted Pair
Gauge	18 - 24 AWG
Capacitance between signal wires	31 pF/ft or less (9.45 m) or less
Capacitance between signal and shield	59 pF/ft or less (17.98 m) or less
Maximum Length	4000 ft/18 to 22 AWG (1219.2 m) 2500 ft/24 AWG (762 m)
Nominal Impedance	120Ω±50Ω

17.3. MODBUS Termination Blocks

Because the XEV22D device has no on-board means of termination, use the MODBUS termination block (P/N 535-2711) for termination that can be wired to the end of the cable segment using the three-pin connector. Wire the two signal wires to the outside terminals, and connect the shield to pin 16, keeping the exposed shield wire length as short as possible (3 inches ideal maximum length).

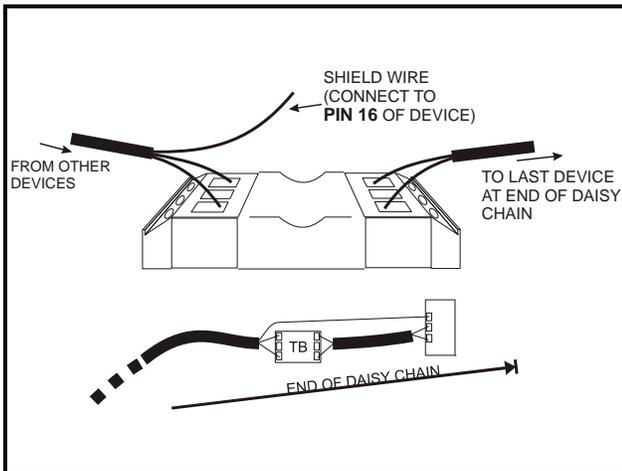


Figure 17-8 - MODBUS Termination Block (P/N 535-2711)

18 Standard Values

Label	Description	Range	Default	Level
Fty	Kind of gas	R22, 134, 404, 407, 410, 507, CO2	404	Pr2
PEo	Probe error opening percentage	0 to 100%	50	Pr2
PEd	Probe error delay before stopping regulation	0 to 239 sec - On	On	Pr2
tEU	Type of stepper motor	uP – bP	bP	Pr2
tEP	Automatic valve configuration	0 to 10	1	Pr2
LSt	Minimum number of steps	0 – Ust	See tEP	Pr2
Ust	Maximum number of steps	LSt – 800 * 10	See tEP	Pr2
Sr	Step rate	10 to 600 step/s	See tEP	Pr2
CPP	Current per phase (only bipolar valves)	0 to 100 * 10mA	See tEP	Pr2
CHd	Holding current per phase (only bipolar valves)	0 to 100 * 10mA	See tEP	Pr2
oPE	Start opening percentage	0 to 100%	85	Pr2
SFd	Start function duration	0.0 to 42.0 min: tens of seconds	1.3	Pr2
Sti	Stop regulation interval	0.0 to 24.0 hr: tens of minutes	0	Pr2
Std	Stop duration	0 to 60 min	0	Pr2
MnF	Maximum opening percentage	0 to 100%	100	Pr2
FOP	Forced opening time-out	0 to 100% - not used	not used	Pr2
PI PARAMETERS (For trained staff use only)				
Pb	Proportional band	0.1 to 50.0°C/ 1 to 90°F	10.0	Pr2
rS	Band offset	-12.0 to 12.0°C/ -21 to 21°F	0.0	Pr2
inC	Integration time	0 to 255 sec	120	Pr2
PROBE PARAMETERS				
tPP	Type of pressure transducer	420 - 5V- LAn	420	Pr2
LPP	Enable pressure probe sending in LAN	n to Y	n	Pr2
PA4	Probe value at 4mA or at 0V (related to PrM parameter)	-1.0 bar/ -14 PSI	-0.5	Pr2
P20	Probe value at 20mA or at 5V (related to PrM parameter)	PA4 to 50.0 bar/ 725 PSI	11.0	Pr2
OPr	Pressure probe calibration	-12.0 to 12.0 bar/ -174 to 174 psi	0	Pr2
ttE	Type of temperature probe	PtM to ntC	PtM	Pr2
otE	Temperature probe calibration	-12.0 to 12.0°C/ -21 to 21°F	0	Pr2
DIGITAL INPUTS				
iIP	Free of voltage digital input polarity	CL – OP	CL	Pr2
d1d	Digital input 1 (free of voltage) activation delay	0 to 255 min	0	Pr2

Table 18-1 - XEV22D Standard Parameter Values

Label	Description	Range	Default	Level
i2P	Main voltage digital input polarity	CL – OP	CL	Pr2
i2F	Main voltage digital input function	CCL, rL	CCL	Pr2
d2d	Digital input 2 (Main voltage) activation delay	0 to 255 min	0	Pr2
ALARMS				
dAo	Alarm delay after restarting regulation	0.0 to 42.0 min: tens of seconds	10.0	Pr2
tdA	Type of alarm signaled by relay	ALL, SH, PrE, di	ALL	Pr2
LPL	Lower pressure limit for superheat regulation (related to PrM parameter)	PA4 to P20 bar/ PSI	-0.5	Pr2
MOP	Maximum operating pressure threshold (related to PrM parameter)	PA4 to P20 bar/ PSI	11.0	Pr2
LOP	Minimum suction pressure limit (related to PrM parameter)	PA4 to P20 bar/ PSI	-0.5	Pr2
PHY	Pressure alarm hysteresis	0.1 to 5.0 bar/ 1 to 72 PSI	0.1	Pr2
dML	delta MOP-LOP	0 to 100%	30	Pr2
MSH	Maximum superheat alarm	LSH to 32.0 °C/ LSH to 176 °F	80.0	Pr1
LSH	Lowest superheat alarm	0.0 to MSH °C/ 32 to MSH °F	2.5	Pr1
SHy	Superheat hysteresis	0.1 to 25.5°C/ 1 to 77°F	0.1	Pr2
SHd	Superheat alarm activation delay	0 to 255 sec	120	Pr1
FrC	Fast-recovery constant	0 to 100 sec	50	Pr2
DISPLAY				
Lod	Local display	SH - PEr – P1 - P2	SH	Pr1
CF	Temperature measurement units	°C - °F	°C	Pr2
PMU	Pressure measurement unit	bAr – PSI	bAr	Pr2
rES	Resolution (only °C)	dE – in	dE	Pr2
PrM	Type of pressure (absolute/ relative)	rEL – AbS	rEL	Pr2
CLP	Cooling call percentage	Read only	---	Pr2
tP1	Temperature probe value	Read only	---	Pr1
PPr	Pressure probe value	Read only	---	Pr1
tP2	Temperature converted from pressure probe	Read only	---	Pr1
OPP	Actual opening percentage	Read only	---	Pr1
d1S	Free of voltage digital input state	Read only	---	Pr1
d2S	Main voltage digital input state	Read only	---	Pr1
Adr	Serial address	1 to 247	1	Pr2
Mod	MODBUS type	StD – AdU	StD	Pr2
Ptb	Parameters map	---	---	Pr2
rEL	Release software	---	---	Pr2
Pr2	Second level menu	---	---	Pr1

Table 18-1 - XEV22D Standard Parameter Values