

User's Manual



INDUSTRIAL RADIO CONTROLS

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1. Introduction

The **FLEX** radio remote control systems are designed for control of industrial equipment and machinery such as overhead traveling cranes, jib cranes, gantry cranes, tower cranes, electric hoists, winches, monorails, conveyor belts, mining equipment and other material handling equipment where wireless control is preferred.

Each **FLEX** system consists of a transmitter handset and receiver unit. Other standard-equipped accessories include transmitter waist belt, spare transmitter power key, clear vinyl pouch, "AA" alkaline batteries, compass direction decal sheet and user's manual.

List of notable features include:

- * 62 user-programmable channels Advanced synthesized RF controls with 62 built-in channels, no more fixed channel and fragile quartz crystals to break.
- * Automatic channel scanning receiver No more hassle of climbing up the crane to change receiver channels.
- * Over one million unique ID codes (20bit) Each and every Flex system has its own unique ID codes and serial number, never repeats.
- * Advanced controls The Flex system utilizes advanced microprocessor controls with 32bit CRC and Hamming Code, which provide ultra fast, safe, precise, and error-free encoding and decoding.
- * Unique I-CHIP design The I-CHIP functions in a way that is very similar to SIM card used on mobile phones, with the ability to transfer system information and settings from one transmitter to another without the hassle of resetting the spares.
- * Reliable push buttons The in-house designed push buttons with gold-plated contacts are rated for more than one million press cycles.
- * Low power consumption Requires only two "AA" Alkaline batteries for more than 80 hours of operating time between replacements.
- * Ultra-durable nylon and fiberglass composite enclosures Highly resistance to breakage and deformation even in the most abusive environments.
- * Full compliance All systems are fully complied with the FCC Part-15 Rules, European Directives (Safety, EMC, R&TTE, Machinery) and Industry Canada Specifications (IC).

2. Radio Controlled Safety

Flex radio remote control system should be operated by persons with sufficient amount of knowledge and skill in crane operation and safety. Persons being trained to operate a radio remote controlled crane should possess the knowledge of all hazards peculiar to radio remote controlled crane operation, ability to judge distance and moving objects, equipment capacity and radio remote controlled safety rules. Radio remote controlled cranes should not be operated by any person with insufficient eyesight, hearing, illness, and under influence of drugs and medications that may cause loss of crane control.

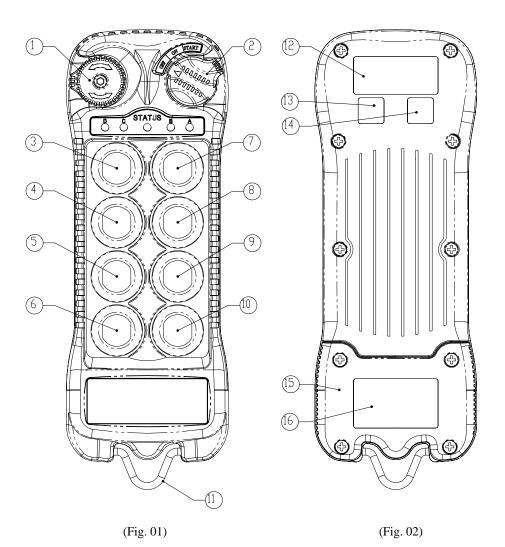
Below are some general operating safety tips that should be strictly followed when operating a radio remote controlled crane.

- Prior to crane operation always check the transmitter handset for any damage that might inhibit proper crane operation.
- 2. Always check if the red emergency stop button is working properly prior to crane operation.
- 3. Check the Status LED on the transmitter for any signs of low battery power (refer to page 31).
- 4. Check the Status LED on the transmitter for any signs of irregularities (refer to page 31).
- 5. The crane limit switches should be checked prior to crane operation or at the beginning of each shift.
 When checking limit switches the hoist should be centered over an area free of personnel and equipment.
- 6. If the power to the crane is removed, the operator should turn off the transmitter power immediately until the power to the crane is restored.
- 7. If the crane fails to respond properly to operator's command the operator should stop operation, turn the transmitter power off, and then report the condition to their supervisor.
- 8. The transmitter power should be turned off after each use. If the transmitter handset is not in use always turn the power off and stored it in a safe or designated location. Never leave the transmitter handset unattended in the working area.
- Make sure the system is not set to the same channel as any other Flex systems in use within a distance of 300 meters (900 feet).
- 10. Never operate a crane or equipment with two transmitter handsets at the same time unless they are programmed with "Pitch & Catch" function. For information on the "Pitch & Catch" feature, please refer to page 19 and page 30 of this manual.

3. General System Information

A. TRANSMITTER HANDSET

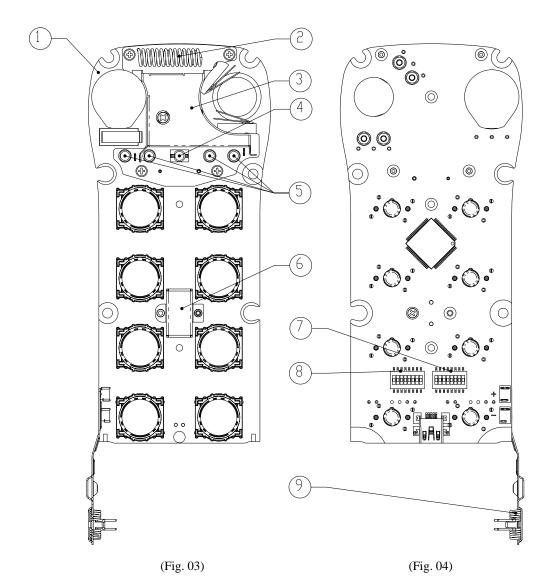
1. External Illustration (Standard Push Button Configuration)



- 1. Emergency Stop Button
- 2. Removable Power Key Switch
- 3. Push Button #2
- 4. Push Button #4
- 5. Push Button #6
- 6. Push Button #8
- 7. Push Button #1
- 8. Push Button #3

- 9. Push Button #5
- 10. Push Button #7
- 11. Strap Ring
- 12. System Information
- 13. System Channel
- 14. Crane Number
- 15. Battery Cover
- 16. FCC Information

2. Internal Illustration

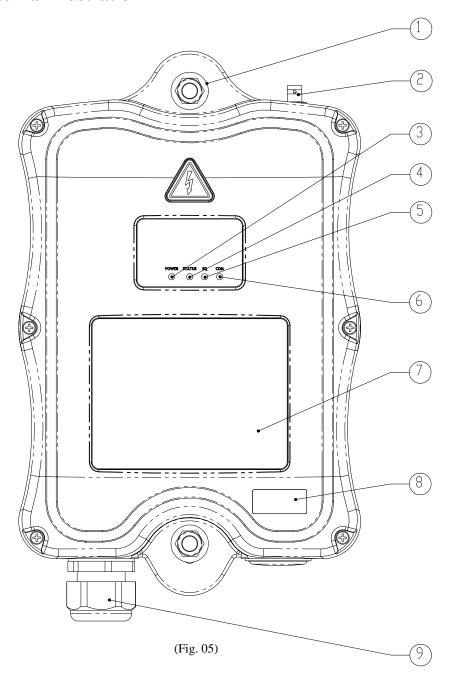


- 1. Encoder Board
- 2. Arial Antenna
- 3. Transmitting Module
- 4. Status LED Display
- 5. Function LED Displays

- 6. I-CHIP
- 7. Function Dip-Switch
- 8. Channel Dip-Switch
- 9. Battery Contact Mechanism

B. RECEIVER UNIT

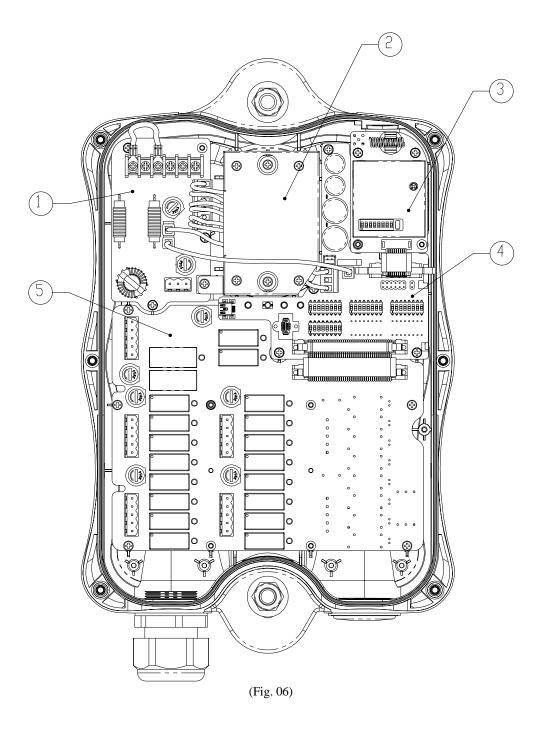
1. External Illustration



- 1. Shock Mount
- 2. Optional External Antenna (BNC) Jack
- 3. Power LED Display
- 4. Status LED Display
- 5. SQ LED Display

- 6. COM LED Display
- 7. Output Contact Diagram
- 8. System Information
- 9. Cord Grip

2. Internal Illustration

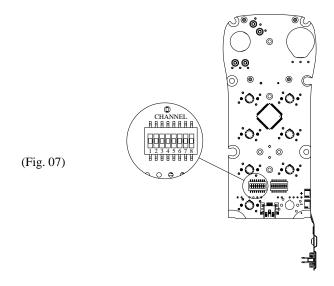


- 1. AC Line Filter
- 2. Power Transformer
- 3. Receiving Module
- 4. Decoder Module
- 5. Output Relay Board

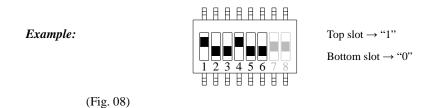
4. Function Settings

A. TRANSMITTER HANDSET

1. System Channel Settings



Set the transmitter channel by adjusting the channel dip-switch located on the backside of the transmitter encoder board (refer to Fig. 07 above). Only the first six (6) positions are used for channel programming (refer to Fig. 08 below). The system channels table located on page 24 illustrates which dip-switch setting corresponds to which channel. Once the transmitter channel is altered do make sure to change receiver channel as well. The channel on both transmitter and receiver must be identical in order for system to work. To change receiver channel please refer to page 15.

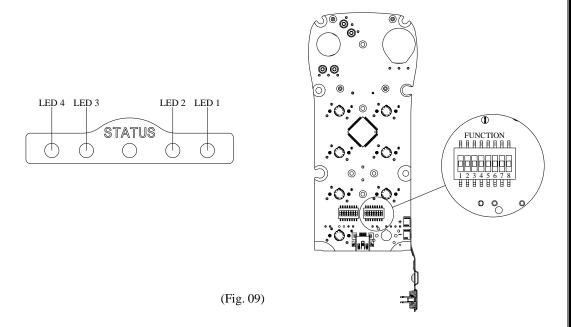


The above dip-switch setting "1 0 0 1 0 0" corresponds to "channel 36" in the system channels table on page 24.

2. Push Button Functions with LED Displays

A. Standard Push Button Configuration (Transmitter Toggle)

Set transmitter toggle (latching output relay) function by adjusting the 8-position function dip-switch located on the backside of the transmitter encoder board (refer to Fig. 09 below). The LED 1 through LED 4 shown inside the shaded box (see below) illustrates which LED on the transmitter will light up when the designated push button (PB-5 \sim PB-8) is pressed.



| | DIP | PB-5 | PB-6 | PB-7 | PB-8 |
|---|----------|--------|--------|--------|--------|
| 1 | 00000000 | Normal | Normal | Normal | Normal |
| 2 | 00000101 | Normal | Normal | Normal | LED 4 |
| 3 | 00000110 | Normal | Normal | LED 3 | LED 4 |
| 4 | 00000111 | Normal | LED 2 | LED 3 | LED 4 |
| 5 | 00001000 | LED 1 | LED 2 | LED 3 | LED 4 |

^{*} $PB-5...PB-8 \rightarrow Push\ button\ number$

^{*} $Normal \rightarrow Normal \ momentary \ contact$

^{*} LED 1...LED $4 \rightarrow$ Transmitter toggled with designated LED Display

B. Standard Push Button Configuration (A/B Selector)

There are four (4) different types of A/B selector sequence available on the Flex system.

Choose the one that is most suitable for your application.

Type-A selector sequence : $A+B \rightarrow A \rightarrow B \rightarrow A+B \dots$

 $\label{eq:continuous} \text{Type-B selector sequence} \quad : \quad \text{Off} \rightarrow A \rightarrow B \rightarrow \text{Off} \rightarrow A \rightarrow B \dots$

 $\label{eq:continuous} \text{Type-C selector sequence} \quad : \quad \quad A \to B \to A + B \to A \to B \to A + B \ \dots$

Type-D selector sequence : Off \rightarrow A \rightarrow B \rightarrow A+B \rightarrow Off \rightarrow A \rightarrow B \rightarrow A+B ...

| | DIP | PB-5 | PB-6 | PB-7 | PB-8 |
|----|----------|--------|--------|--------|--------|
| 6 | 00101111 | Normal | Normal | A/1&2 | Normal |
| 7 | 00110000 | Normal | Normal | B/1&2 | Normal |
| 8 | 00110001 | Normal | Normal | C/1&2 | Normal |
| 9 | 00110010 | Normal | Normal | D/1&2 | Normal |
| 10 | 00110011 | Normal | Normal | Normal | A/3&4 |
| 11 | 00110100 | Normal | Normal | Normal | B/3&4 |
| 12 | 00110101 | Normal | Normal | Normal | C/3&4 |
| 13 | 00110110 | Normal | Normal | Normal | D/3&4 |
| 14 | 00110111 | Normal | Normal | A/1&2 | A/3&4 |
| 15 | 00111000 | Normal | Normal | A/1&2 | B/3&4 |
| 16 | 00111001 | Normal | Normal | A/1&2 | C/3&4 |
| 17 | 00111010 | Normal | Normal | A/1&2 | D/3&4 |
| 18 | 00111011 | Normal | Normal | B/1&2 | B/3&4 |
| 19 | 00111100 | Normal | Normal | B/1&2 | C/3&4 |
| 20 | 00111101 | Normal | Normal | B/1&2 | D/3&4 |
| 21 | 00111110 | Normal | Normal | C/1&2 | C/3&4 |
| 22 | 00111111 | Normal | Normal | C/1&2 | D/3&4 |
| 23 | 01000000 | Normal | Normal | D/1&2 | D/3&4 |

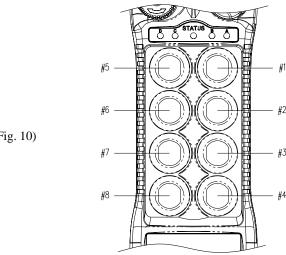
^{*} $PB-5...PB-8 \rightarrow Push\ button\ number$

^{*} $Normal \rightarrow Normal \ momentary \ contact$

^{*} $A/1 \& 2...D/3 \& 4 \rightarrow A/B$ Selector type with designated LED Display (LED 1 & 2 or LED 3 & 4)

C. Inline Push Button Configuration (Transmitter Toggle)

The push button arrangement for inline push button setup starts from top to bottom and then from right column to left column (refer to Fig. 10 below). To set inline push button configuration please refer to JP4 and JP5 jumpers setting on page 22. With inline push buttons configuration, push button #1 & #2 still corresponds to output relay K1~K4, push button #3 & #4 corresponds to relay K5~K8, etc...



| (Fig. 1 | 10) |
|---------|-----|
|---------|-----|

| | DIP | PB-5 | PB-6 | PB-7 | PB-8 |
|----|--------------------|--------|--------|--------|--------|
| 24 | 24 00000000 Normal | | Normal | Normal | Normal |
| 25 | 00000101 | Normal | Normal | Normal | LED 4 |
| 26 | 00010100 | Normal | Normal | LED 3 | LED 4 |
| 27 | 00010101 | Normal | LED 2 | LED 3 | LED 4 |
| 28 | 00010110 | LED 1 | LED 2 | LED 3 | LED 4 |

^{*} $PB-5...PB-8 \rightarrow Push\ button\ number$

^{*} $Normal \rightarrow Normal \ momentary \ contact$

^{*} LED 1...LED 4 \rightarrow Transmitter toggled with designated LED Display

D. Inline Push Button Configuration (A/B Selector)

There are four (4) different types of A/B selector sequence available on the Flex system.

Choose the one that is most suitable for your application.

Type-A selector sequence : $A+B \rightarrow A \rightarrow B \rightarrow A+B \dots$

 $\label{eq:continuous} \text{Type-B selector sequence} \quad : \quad \text{Off} \rightarrow A \rightarrow B \rightarrow \text{Off} \rightarrow A \rightarrow B \dots$

 $\label{eq:continuous} \text{Type-C selector sequence} \quad : \quad \quad A \to B \to A + B \to A \to B \to A + B \ \dots$

Type-D selector sequence : Off \rightarrow A \rightarrow B \rightarrow A+B \rightarrow Off \rightarrow A \rightarrow B \rightarrow A+B ...

| | DIP | PB-5 | PB-6 | PB-7 | PB-8 |
|----|----------|--------|--------|--------|--------|
| 29 | 01110011 | Normal | Normal | A/1&2 | Normal |
| 30 | 01110100 | Normal | Normal | B/1&2 | Normal |
| 31 | 01110101 | Normal | Normal | C/1&2 | Normal |
| 32 | 01110110 | Normal | Normal | D/1&2 | Normal |
| 33 | 00110011 | Normal | Normal | Normal | A/3&4 |
| 34 | 00110100 | Normal | Normal | Normal | B/3&4 |
| 35 | 00110101 | Normal | Normal | Normal | C/3&4 |
| 36 | 00110110 | Normal | Normal | Normal | D/3&4 |
| 37 | 01110111 | Normal | Normal | A/1&2 | A/3&4 |
| 38 | 01111000 | Normal | Normal | A/1&2 | B/3&4 |
| 39 | 01111001 | Normal | Normal | A/1&2 | C/3&4 |
| 40 | 01111010 | Normal | Normal | A/1&2 | D/3&4 |
| 41 | 01111011 | Normal | Normal | B/1&2 | B/3&4 |
| 42 | 01111100 | Normal | Normal | B/1&2 | C/3&4 |
| 43 | 01111101 | Normal | Normal | B/1&2 | D/3&4 |
| 44 | 01111110 | Normal | Normal | C/1&2 | C/3&4 |
| 45 | 01111111 | Normal | Normal | C/1&2 | D/3&4 |
| 46 | 10000000 | Normal | Normal | D/1&2 | D/3&4 |

^{*} $PB-5...PB-8 \rightarrow Push\ button\ number$

^{*} $Normal \rightarrow Normal \ momentary \ contact$

^{*} $A/1 \& 2...D/3 \& 4 \rightarrow A/B$ Selector type with designated LED Display (LED 1 & 2 or LED 3 & 4)

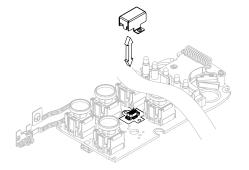
3. I-CHIP

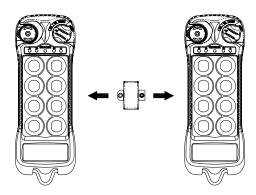
I-Chip functioned in a way that is very similar to a SIM card inside a mobile phone, which stores system information such as your phone number, account number, phone book and other settings.

I-CHIP works exactly the same way, as it stores information such as system serial number/ID code, channel and push button configurations.

When replacing a transmitter handset, just take the I-CHIP out of the old transmitter and install it into the new one (refer to Fig. 11 below). For complete information transfer, do make sure both the Channel and Function dip-switch is set to all "1". If both dip-switches are set to all "1", then the transmitter will operate according to the push button configurations and channel stored inside the I-CHIP. If both Channel and Function dip-switch is set to other values other than all "1", then the transmitter will operate according to the channel and push button configurations set on these two dip-switches, not the ones stored inside the I-CHIP. Every time when the settings on these two dip-switches have changed, the new settings will be stored into the I-CHIP automatically. In this case the previous channel and push button configurations stored inside the I-CHIP will be erased and be replaced by the new settings.

For safety purposes, system serial number/ID code stored inside the I-CHIP can not be changed directly on the transmitter encoder board. Only channels and push button configurations can be changed directly on the encoder board via Channel and Function dip-switches. There are only two ways that you can change transmitter serial number/ID code; 1) via I-CHIP programming port located on the decoder module inside the receiver unit, please refer to page 23 on how to program the I-CHIP (serial number/ID code) via receiver unit; 2) via an external I-CHIP programmer or duplicator unit available from the factory. Please ask your local dealers for assistance if your system requires serial number/ID code adjustments.

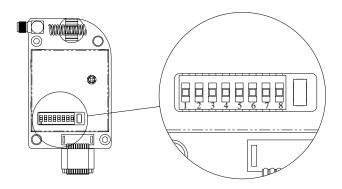




(Fig. 11)

B. RECEIVER UNIT

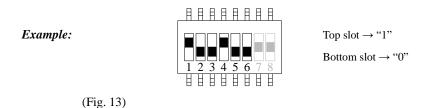
1. System Channel Settings



(Fig. 12)

Even though Flex system is equipped with automatic channel scanning receiver, the user can also set the receiver channel manually. Please refer to page 30 on how automatic channel scanning receiver works.

Set the receiver channel by adjusting the channel dip-switch located on the receiver module (refer to Fig. 12 above), only the first six (6) positions are used for channel programming (refer to Fig. 13 below). The system channels table located on page 24 illustrates which dip-switch setting corresponds to which channel. Once the receiver channel is altered do make sure to change transmitter channel as well. The channel on both transmitter and receiver must be identical in order for system to work. To change transmitter channel please refer to page 9.



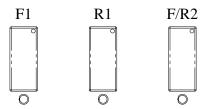
The above dip-switch setting "1 0 0 1 0 0" corresponds to "channel 36" in the system channels table on page 24.

2. Output Relay Configurations

- a. Output Relay Types
 - 1. Three (3) output relays per motion shared 2nd speed output relay

 Output relays with Forward 1st speed (F1), Reverse 1st speed (R1) and Forward/Reverse

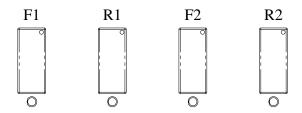
 2nd speed (F/R2). Forward and Reverse 2nd speed (F/R2) shared the same output relay.



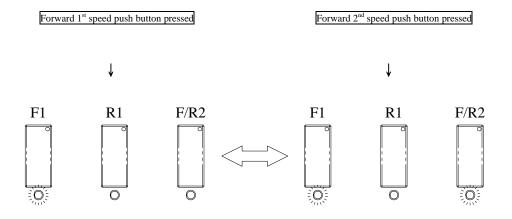
2. Four (4) output relays per motion – separate 1st and 2nd speed output relays

Output relays with Forward 1st speed (F1), Reverse 1st speed (R1), Forward 2nd speed (F2)

and Reverse 2nd speed (R2). Forward and Reverse 2nd speed with separate output relays.



- b. Output Relay Actions at 2nd Speed
 - 1. 3-output relays configuration with Closed/Closed contact at 2nd speed At 2nd speed, both 1st speed (F1 or R1) and 2nd speed (F/R2) output relays are closed (refer to page 20 on how to set to this function).

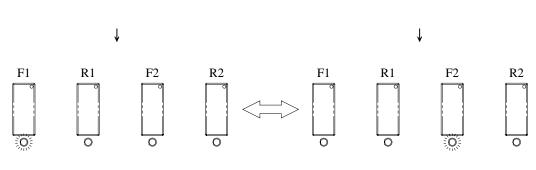


2. 4-output relays configuration with Opened/Closed contact at 2nd speed At 2nd speed, only the 2nd speed (F2 or R2) output relay is closed (refer to page 20 on how

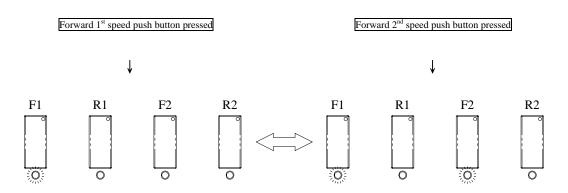
to set to this function).

Forward 1st speed push button pressed

Forward 2nd speed push button pressed



3. 4-output relays configuration with Closed/Closed contact at 2nd speed At 2nd speed, both 1st speed (F1 or R1) and 2nd speed (F2 or R2) output relays are closed (refer to page 20 on how to set to this function).



c. ON/OFF Push Button Function

The user can set any of the two adjacent push buttons on the transmitter to behave like a mechanical ON & OFF rocker switch (refer to page 20 on how to set to this function). When "On" output relay is closed ("On" push button pressed), the "Off" output relay will open automatically, or vise versa.

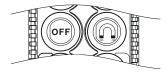


d. START/AUX Function

After initiating the START function the Start position will become an auxiliary function with momentary contact. For auxiliary application such as horn or buzzer, please connect it to the FUNC output relay (wire #6) located inside the receiver unit.

e. Magnet ON/OFF Push Button Function

The user can set any of the two adjacent push buttons on the transmitter to control a magnet. To activate the magnet just press the push button with the Magnet symbol. To deactivate the magnet, for safety purpose, you must first press and hold the Magnet push button and then press the OFF push button. Press the OFF push button by itself can not deactivate the magnet (refer to page 20 on how to set to this function).



f. Brake Function

When the transmitter push button is released from 2nd speed up to 1st speed, both 1st and 2nd speed output relays will open for up to 1.0 second and then with 1st speed output relay closed thereafter (refer to page 20 on how to set to this function).

g. Momentary Contact

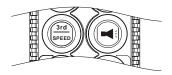
When push button is released the output relay corresponds to that push button will open (refer to page 21 on how to set to this function). This type of contact is usually applies to external application such as horns or buzzers.

h. Toggled Contact

When push button is released the output relay corresponds to that push button will remained closed (maintained contact) until next time the user presses the same push button again (refer to page 21 on how to set to this function). This type of contact is usually applies to external application such as lights.

i. 3rd Speed Push Button Function

This function allows the crane to travel an additional step beyond 2^{nd} speed. For example, if the operator is pressing the "UP" push button down to 2^{nd} speed, pressing the 3^{rd} speed push button (with "UP" push button still hold at 2^{nd} speed) will toggle between 2^{nd} speed and 3^{rd} speed (refer to page 21 on how to set to this function).



j. Auxiliary STOP Push Button Function

The auxiliary STOP function acts as a 2nd emergency stop button. Other than by emergency stop button and transmitter power key switch, the receiver MAIN is also deactivated when this auxiliary stop push button is pressed (refer to page 21 on how to set to this function).

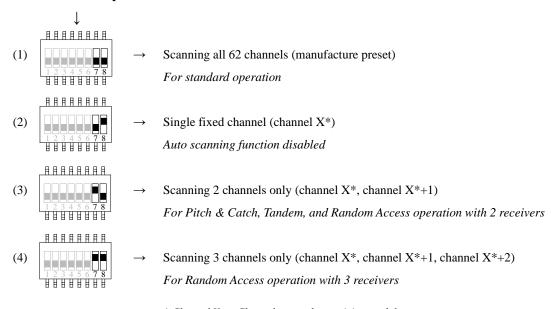


k. Pitch & Catch Function

This function allows two operators controlling one crane from opposite ends of a cross or long travel (refer to page 21 on how to set to this function). When set to "Pitch & Catch" make sure the 2^{nd} transmitter is set to the next upper channel (channel X^*+1). For example, if the system is preset at "Ch.01" then the channel of the 2^{nd} transmitter should be set to "Ch.02". Furthermore, the dip-switch position #7 and #8 on the receiving module should be set to "01", this will allow the receiver to scan only Ch.01 and Ch.02 (please refer to the illustration below). On the other hand, since there are only 62 available channels on the Flex system, the system preset at channel 62 is ineffective because the 2^{nd} transmitter can not be set to Ch.63. If your system is preset at Ch.62 do make sure to change it to another channel.

3. Receiver Auto-Scanning Settings

Receiver Channel Dip-switch



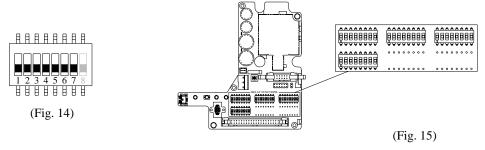
* Channel $X \rightarrow$ Channel set on the receiving module

Example: If the first 6 dip-switch positions on the receiving module is set to Ch.01 ("000000" or "000001"), when set to 2-channel scanning (type-2 above), then the receiver will only scan Ch.01 and Ch.02.

4. Dip-Switch Settings

a. Interlocked Functions

Interlocked means the two adjacent push buttons can not be activated simultaneously at the same time as it will cancel each other out. Interlocked settings are usually applied to crane's forward and reverse motions. Each dip-switch on the decoder module corresponds to one (1) motion or two (2) adjacent push buttons (refer to Fig. 14 & 15 below). Only the first 7 dip-switch positions are used (counting from left to right), the 8th dip-switch position (far right) is not used.



Manufacture preset

| Dip Settings | Function Descriptions | # of Relays Used |
|-----------------|---|---------------------|
| 0000000 | Normal (single speed only, F2 & R2 relays not used) | 2 |
| 0000001 | Closed/Closed Relay Action at 2 nd Speed (separate 2 nd speed relay) | 4 |
| 0000010 | Closed/Closed Relay Action at 2 nd Speed (shared 2 nd speed relay) | 3 |
| 0000011 | Opened/Closed Relay Action at 2 nd Speed (separate 2 nd speed relay) | 4 |
| 0000110 | On (right button) & Off (left button) | 2 |
| 0001000 | On & Off (affected by the E-stop command. When E-stop command is initiated, the Off relay is activated) | 2 |
| 0000111 | Safety Magnet On & Off | 2 |
| 0100001 | Closed/Closed + Brake | 4 |
| 0100010 | Closed/Closed Relay Action + Brake | 3 |
| 0100011 | Opened/Closed Relay Action + Brake | 4 |

b. Non-Interlocked Functions

Contrary to interlocked settings, non-interlocked settings allow the two adjacent push buttons be used simultaneously at the same time. Non-interlocked settings are usually applied to crane's auxiliary functions such as lights, horn, 3rd speed, auxiliary stop and Pitch & Catch. Each dip-switch on the decoder module corresponds to one (1) motion or two (2) adjacent push buttons (left & right push buttons).

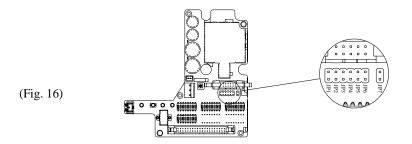
| Function Code | Dip Position Setting #1 | Dip Position Setting #2 ~ #4 (left button) & #5 ~ #7 (right button) | Function Description |
|------------------|----------------------------------|---|--|
| A | 1 | 000 | Normal (momentary) contact. |
| В | 1 | 001 | Toggled (latching) contact. |
| С | 1 | 010 | Acceleration (3 rd speed). |
| D | 1 | 011 | Toggled (latching) contact affected by the E-Stop command. When E-Stop command is initiated, all toggled (latching) relays are also deactivated. |
| E | 1 | 101 | Pitch & Catch Type-1. When Pitch (release) function is initiated, receiver MAIN will not be deactivated. |
| F | 1 | 110 | Pitch & Catch Type-2. When Pitch (release) function is initiated, receiver MAIN will be deactivated. |
| G | 1 | 111 | Auxiliary Stop. |

Example #1: Left button (set to function code A) / right button (set to function code A) \rightarrow 1 000 000 Example #2: Left button (set to function code B) / right button (set to function code B) \rightarrow 1 001 001 Example #3: Left button (set to function code A) / right button (set to function code C) \rightarrow 1 000 010 Example #4: Left button (set to function code F) / right button (set to function code A) \rightarrow 1 110 000

When set to Pitch & Catch function make sure the 2nd transmitter is set to the next upper channel. For example, if the system is preset at Ch.01 then the 2nd transmitter should be set to Ch.02. Furthermore, you must also set the dip-switch on the receiving module (position #7 & #8) to "01" position (2-channel scanning), please refer to page 19.

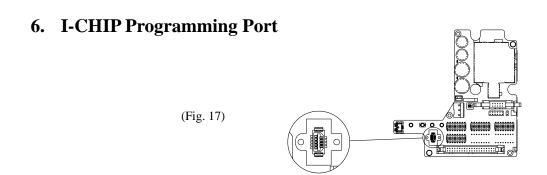
5. Jumper Settings

Jumper settings are applied to functions such as mainline-disconnect time, Start function, transmitter push button layout, system information (serial number/ID code and channel) programming and system testing. The jumpers $\#1 \sim \#7$ are located on the decoder module above the four (4) dip-switches (refer to Fig.16 below).



Manufacture preset

| ivialiulacture preser | | | | | | |
|-----------------------|-------------------|---|--|--|--|--|
| Jumper | Settings | Function | | | | |
| JP1 JP2 (Blank) | | Receiver MAIN remained closed unless the transmitter power is turned off or emergency stop command is initiated. | | | | |
| JP1 (Inserted) | JP2 (Blank) | Receiver MAIN opens after 5 minutes of inactivity. | | | | |
| JP1 (Blank) | JP2 (Inserted) | Receiver MAIN opens after 30 minutes of inactivity. | | | | |
| JP1 (Inserted) | JP2 (Inserted) | Receiver MAIN opens after 60 minutes of inactivity. | | | | |
| JI (Bla | og ank) | After turning on the transmitter power key switch or after resetting the emergency stop button, press any push button to activate the receiver MAIN. | | | | |
| JI (Inse | | After turning on the transmitter power key switch or after resetting the emergency stop button, rotate the power key to "START" position to activate the receiver MAIN. | | | | |
| JP4 (Blank) | JP5 (Blank) | Standard right-to-left push button configuration for all models. | | | | |
| JP4 (Inserted) | JP5 (Blank) | In-line push button configuration (top to bottom) for FLEX 8ES/EX. | | | | |
| JP4 (Blank) | JP5 (Inserted) | In-line push button configuration (top to bottom) for FLEX 12ES/EX. | | | | |
| JP4 (Inserted) | JP5 (Inserted) | In-line push button configuration (top to bottom) for FLEX 4ES/EX. | | | | |
| JI (Bla | P6 ank) | Program system serial number/ID code and channel from decoder module to I-CHIP. | | | | |
| | P6 erted) | Program system serial number/ID code and channel from I-CHIP to decoder module. | | | | |
| | P7 erted) | For system test only, receiver MAIN disabled. | | | | |



I-CHIP programming port located on the decoder module (refer to Fig. 17 above) inside the receiver is designed for the purpose of transferring system serial number/ID code either from I-CHIP to receiver or from receiver to I-CHIP. If you wish to transfer system information from receiver to I-CHIP, just insert the I-CHIP onto the programming port (JP6 jumper not inserted), wait until the Status LED on the decoder module turned constant green (within 2 seconds), and then take the I-CHIP out of the programming port (programming completed). At this time the I-CHIP should also possess the same serial number/ID code as the receiver. If the Status LED on the decoder module displayed a constant red light after inserting the I-CHIP (programming failed), then you must reinsert the I-CHIP one more time. On the other hand, if you wish to transfer system information from I-CHIP to receiver, then you must first insert JP6 jumper prior to inserting the I-CHIP, then wait for the green light to appear on the Status LED. At this time the receiver should also possess the same system information as the I-CHIP. Please note that the receiver unit must be powered in order to proceed with the programming.

7. Voltage Settings

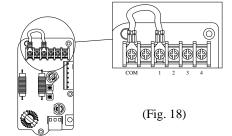
Prior to installation always check the voltage setting is correct for your application (refer to Fig. 18 below).

Position 1 \rightarrow 110~120VAC

Position 2 → 220~240VAC or 24VAC*

Position 3 \rightarrow 380~410VAC or 42VAC*

Position 4 \rightarrow 440~460VAC or 48VAC* or 12~24VDC**



F9 and F10 power fuse ratings:

| FUSE# | 110~120VAC | 220~240VAC | 380~410VAC | 440~460VAC | 24VAC | 42 & 48VAC | 12~24VDC |
|-------|------------|------------|------------|-------------|---------------|---------------|---------------|
| F9 | 1.0A (red) | 1.0A (red) | 1.0A (red) | 0.5A (blue) | 3.0A (yellow) | 2.0A (purple) | 2.0A (purple) |
| F10 | 1.0A (red) | 1.0A (red) | 1.0A (red) | 0.5A (blue) | 3.0A (yellow) | 2.0A (purple) | 2.0A (purple) |

^{*} Output relay fuse \rightarrow 5.0A (clear)

^{*} For system with 24/42/48VAC power supply.

^{**} For system with 12~24VDC power supply.

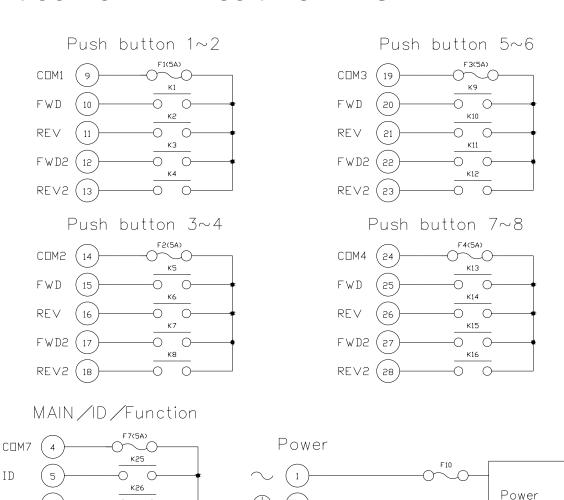
5. System Channels Table

| Channel | Frequency | Dip-switch Setting | Channel | Frequency | Dip-switch Setting |
|---------|------------|-----------------------|---------|------------|-----------------------|
| 01 | 433.000MHZ | 000000 | 32 | 433.775MHZ | 100000 |
| 01 | 433.000MHZ | 000001 | 33 | 433.800MHZ | 100001 |
| 02 | 433.025MHZ | 000010 | 34 | 433.825MHZ | 100010 |
| 03 | 433.050MHZ | 000011 | 35 | 433.850MHZ | 100011 |
| 04 | 433.075MHZ | 000100 | 36 | 433.875MHZ | 100100 |
| 05 | 433.100MHZ | 000101 | 37 | 433.900MHZ | 100101 |
| 06 | 433.125MHZ | 000110 | 38 | 433.925MHZ | 100110 |
| 07 | 433.150MHZ | 000111 | 39 | 433.950MHZ | 100111 |
| 08 | 433.175MHZ | 001000 | 40 | 433.975MHZ | 101000 |
| 09 | 433.200MHZ | 001001 | 41 | 434.000MHZ | 101001 |
| 10 | 433.225MHZ | 001010 | 42 | 434.025MHZ | 101010 |
| 11 | 433.250MHZ | 001011 | 43 | 434.050MHZ | 101011 |
| 12 | 433.275MHZ | 001100 | 44 | 434.075MHZ | 101100 |
| 13 | 433.300MHZ | 001101 | 45 | 434.100MHZ | 101101 |
| 14 | 433.325MHZ | 001110 | 46 | 434.125MHZ | 101110 |
| 15 | 433.350MHZ | 001111 | 47 | 434.150MHZ | 101111 |
| 16 | 433.375MHZ | 010000 | 48 | 434.175MHZ | 110000 |
| 17 | 433.400MHZ | 010001 | 49 | 434.200MHZ | 110001 |
| 18 | 433.425MHZ | 010010 | 50 | 434.225MHZ | 110010 |
| 19 | 433.450MHZ | 010011 | 51 | 434.250MHZ | 110011 |
| 20 | 433.475MHZ | 010100 | 52 | 434.275MHZ | 110100 |
| 21 | 433.500MHZ | 010101 | 53 | 434.300MHZ | 110101 |
| 22 | 433.525MHZ | 010110 | 54 | 434.325MHZ | 110110 |
| 23 | 433.550MHZ | 010111 | 55 | 434.350MHZ | 110111 |
| 24 | 433.575MHZ | 011000 | 56 | 434.375MHZ | 111000 |
| 25 | 433.600MHZ | 011001 | 57 | 434.400MHZ | 111001 |
| 26 | 433.625MHZ | 011010 | 58 | 434.425MHZ | 111010 |
| 27 | 433.650MHZ | 011011 | 59 | 434.450MHZ | 111011 |
| 28 | 433.675MHZ | 011100 | 60 | 434.475MHZ | 111100 |
| 29 | 433.700MHZ | 011101 | 61 | 434.500MHZ | 111101 |
| 30 | 433.725MHZ | 011110 | 62 | 434.525MHZ | 111110 |
| 31 | 433.750MHZ | 011111 | I-CHIP | _ | 1111111* |

^{*} When set to all "1" the priority goes to the channel assigned inside the I-CHIP.

6. Receiver Installation

A. OUTPUT RELAY CONTACT DIAGRAM



- * For 3-relay (shared 2nd speed) and 4-relay (separate 2nd speed) configuration please refer to page 16~20.
- * For 4-relay closed/closed and 4-relay opened/closed relay configuration please refer to page 16~20.

2

Transformer

* For different voltage settings please refer to page 23.

0

K27A

F8(5A)

-0

Func

CDM8

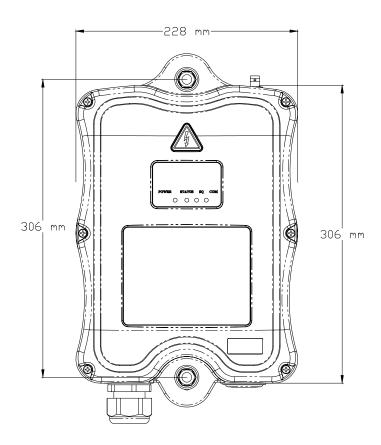
MAIN

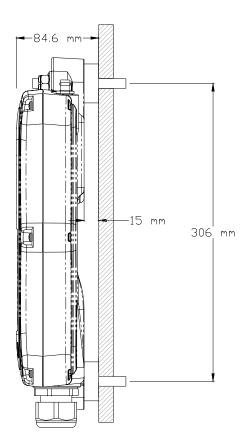
- * For F9 and F10 power fuse ratings please refer to page 23.
- * For 12~24VDC power supply, wire #1 corresponds to the negative charge (-) and wire #3 corresponds to the positive charge (+), wire #2 is for GROUND.

B. PRE-INSTALLATION PRECAUTIONS

- 1. Make sure the transmitter and receiver are with identical serial number/ID code and channel.
- 2. Make sure the receiver is not set to the same channel as any other systems in use in the surrounding area.
- 3. Make sure that the crane or equipment is working properly prior to installation.
- 4. Make sure the power source to the receiver is set correctly.
- 5. Switch off the main power source to the crane or equipment prior to installation.

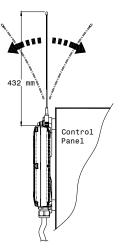
C. STEP-BY-STEP INSTALLATION

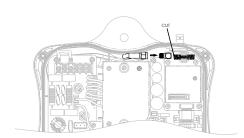




(Fig. 19)

- 1. For best reception the location of the receiver should be visible to the operator at all time.
- The location selected should not be exposed to high levels of electric noise. Mounting the receiver
 next to an unshielded variable frequency drive may cause minor interference. Always locate the
 receiver as far away from variable frequency drive as possible.
- 3. Ensure the selected location has adequate space to accommodate the receiver (refer to Fig. 19 on page 26). If an external antenna is used, to avoid the possibility of antenna damage always locate the receiver where the antenna is free from any obstacles from all directions (refer to diagram at right).
- 4. When installing an external antenna you must also connect the SMA jack located inside the receiver and as well as cut or unsolder the existing spring antenna out, as both can not be connected at the same time.





- 5. For better reception, make sure the receiver is in an upright position.
- 6. Drill two holes (10mm in diameter) on the control panel or location where the receiver is to be installed (refer to Fig. 19 on page 26).
- 7. Make sure the two bolts are tightened after installation.
- 8. For system wiring please refer to page 25.

D. SYSTEM TESTING

- Turn on the power source to the receiver and test the MAIN relay output by pressing the red
 emergency stop button and observe that it properly opens and closes the mainline disconnect
 contactor.
- 2. Test the operation of each function to ensure it corresponds to the transmitter direction labels or the pendent it is replacing.
- 3. Test the limit switches (if any) to see if they are working properly.
- 4. If your new remote control is replacing an existing pendant, make sure it is completely disconnected and placed in a safe location to prevent unwanted control command.

7. Operating Procedure

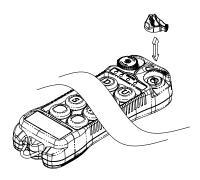
A. TRANSMITTER OPERATION

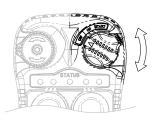
1. General Operating Procedure

 Reset the red emergency stop button located on the top left hand side of the transmitter handset by rotating it either clockwise or counter clockwise, the red button will pop up.



b. Turn on the transmitter power by inserting the black-colored key into the power key slot located on the top right hand side of the transmitter handset and rotate it clockwise to "On" position.





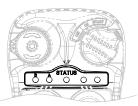
- c. After turning on the transmitter power, check the Status LED on the transmitter handset for any sign of system irregularities (refer to "Status Light Indicators & Warnings" on page 31). If the system is normal the Status LED will light up green for two (2) seconds.
- d. If there are no signs of any system irregularities, then rotate the power key further clockwise to "Start" position for up to 2 seconds, this will activate the receiver MAIN (depends on JP3 setting on page 22). Thereafter, the same "Start" position will become an auxiliary function with momentary contact (refer to page 18).

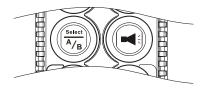


- Now press any push button on the transmitter handset to operate the crane or equipment.
- f. In case of an emergency, pressing down the red emergency stop button will immediately disconnect the receiver mainline (Status LED blinks red). To reset the emergency stop button just rotate the red button either clockwise or counter clockwise, it will pop up. When green light appears, rotate the power key to "Start" position to resume operation (depends on JP3 setting on page 22).
- g. After 5 minutes of inactivity (push button not pressed) the receiver MAIN will be disconnected temporarily (depends on JP1 & JP2 settings on page 22). To resume operation just press any push button on the transmitter, this will reconnect the receiver MAIN automatically.
- h. To turn off the transmitter handset just rotate the power key to "Off" position, it will disconnect the transmitter power and the receiver MAIN altogether.

2. A/B Selector Push Button Operating Procedure

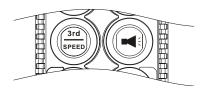
Pressing the "Select A/B" push button will toggle between output relay A, B, A+B respectively. There are 4 different types of Select A/B sequence available, please refer to page 11 for instructions on how to set Select A/B functions.





3. 3rd Speed Push Button Operating Procedure

When a push button is hold at 2^{nd} speed, pressing the 3^{rd} Speed push button one time will activate the 3^{rd} speed output relay (toggled). If the operator wants 2^{nd} speed again, just press the 3^{rd} Speed push button one more time.



4. Pitch & Catch Operating Procedure

To release control of the crane, press the "Pitch" push button. To take over control of the crane, rotate the power key switch to "Catch" position for up to 2 seconds. The 2nd operator "can not" take control of the crane unless the 1st operator presses the "Pitch" push button (2.0 seconds). If the operator unintentionally presses the "Pitch" push button during operation, just rotate the power key to "Catch" position for up to 2 seconds to regain control again.



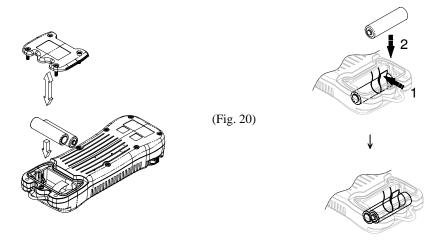
5. Automatic Channel Scanning Operating Procedure

After changing transmitter channel (refer to page 9), turn on the transmitter power and rotate the power key switch to "Start" position and hold it there for up to 1 minute. Within this 1-minute period the receiver will search (channel 01 ~ channel 62) and lock onto the newly selected transmitter channel automatically. Please note that in order for the receiver to switch to auto-scanning mode, prior to changing the transmitter channel, you must first deactivate the receiver MAIN by shutting off the transmitter power or press down the emergency stop button. Please refer to page 19 if you do not want the receiver to auto-scan all 62 channels.



6. Changing Transmitter Batteries

Changing transmitter batteries by unscrewing the battery cover located on the backside of the transmitter (refer to Fig. 20 below). During battery installations make sure that the blue ribbon is centered between the two batteries. After changing the batteries also make sure that all screws are tightened to avoid water, moisture, dirt, grease, or other liquid penetration.



B. STATUS LIGHT INDICATORS & WARNINGS

1. Transmitter STATUS Light Indication

| Туре | Display Type (Green & Red) | Indication |
|------|---|---|
| 1 | Constant red | Voltage below 1.9V at initial power on, transmitter power and receiver MAIN shuts off. Voltage below 1.8V during operation, transmitter power and receiver MAIN shuts off. |
| 2 | 1 red blinks followed by a 2-second pause | Voltage below 1.85V during operation, warning, change batteries suggested. |
| 3 | 2 red blinks followed by a 2-second pause | The pushbutton is defective after turning on the transmitter power. |
| 4 | No light displayed | When defective push button condition occurs (2 red blinks, type 3 above), find out which push button is defective by pressing all the push buttons on the transmitter one at a time. If the push button is in good working order, the LED will not light up when pressed. If the push button is defective the LED will continue to display 2 red blinks when pressed. |
| 5 | 3 red blinks followed by a 2-second pause | EEPROM error. |
| 6 | 4 red blinks followed by a 2-second pause | Transmitting error, system can not locked on to the designated channel. |
| 7 | Constant green for up to 2 seconds | Transmitter power on with no faults detected (prior to initiating the START function). |
| 8 | Blinking green | Pushbutton pressed, signal transmitted. |
| 9 | Slow red blinks | Stop command initiated with receiver MAIN deactivated. |

2. Receiver STATUS Light Indication

| Type | Display Type (Green & Red) | Indication |
|------|----------------------------|--|
| 1 | Fast green blinks | Decoding in process |
| 2 | Slow green blinks | Decoding on standby |
| 3 | Slow red blinks | Stop command initiated with receiver MAIN deactivated |
| 4 | Two red blinks | Receiver MAIN jammed or defective |
| 5 | Fast red blinks | Incorrect transmitter serial number/ID code |
| 6 | Constant red | Receiver under-voltage, LV output relay activated |
| 7 | No light displayed | Decoding microprocessor is defective |

3. Receiver SQ Light Indication

| Type | Display Type (Red) | Indication |
|------|-----------------------|--------------------------|
| 1 | On | Transmission received |
| 2 | Off | No transmission |
| 3 | Blinks intermittently | Other radio interference |

4. Receiver POWER Light Indication

| Type | Display Type (Red) | Indication |
|------|--------------------|----------------------|
| 1 | On | Power to receiver |
| 2 | Off | No power to receiver |

5. Receiver COM Light Indication

| Type | Display Type (Red) | Indication |
|------|--------------------|-------------------------|
| 1 | On | Power to relay Board |
| 2 | Off | No power to relay board |

C. TROUBLE SHOOTING TIPS

| Problems | Possible Reasons | Suggestions |
|---|--|--|
| | Transmitter low battery power | Check the transmitter battery level. |
| | Emergency stop button activated prior to startup | Prior to turning on the transmitter power switch make sure that the red emergency stop button is elevated. |
| No responds when transmitter push | Improper startup procedure | Redo the startup procedure by holding the power key at "START" position for up to 2.0 seconds and then release. |
| button is pressed (Improper startup & settings) | Incorrect system RF channel | Check and make sure that the transmitter handset and receiver unit both have the same channel. |
| settings) | Incorrect system serial number/ID code | Check and make sure that the transmitter handset and receiver unit both have the same serial number/ID code. |
| | System out of range | Make sure that the startup procedure is initiated within 100 meters (300 feet) from the receiver location. |
| No responds when transmitter push button is pressed (Damaged hardware) | Defective transmitting and receiving module | Check the SQ display on the face of the receiver unit. If it does not light up when push button is pressed then either the transmitting or receiving module is defective. First replace the transmitting module. If SQ display still not lid when push button is pressed then go ahead and replace the receiving module. |
| (Damageu naruware) | Defective encoder board or decoder module | If still no responds, then replace the transmitter encoder board. If still doesn't work then the decoder module is defective. |
| N. A.C. | Incorrect input voltage | Make sure the source voltage is set correctly. |
| No AC power to the receiver | Blown fuse | Check for any blown fuse. |
| | Incorrect wiring | Check input voltage connection. |
| Outputs do not correspond to transmitter | Incorrect output connection | Check the system wiring again. Please refer to the output contact diagram inside this manual or on the receiver cover. |

8. System Specifications

Frequency Range : $433 \sim 434 \text{ MHz}$ Number of Channels : 62 channelsChannel Spacing : 25 KHz

Modulation : Digital Frequency Modulation based on

Manchester Code, 20bit address, 32bit CRC

Parity Check and Hamming Code.

Encoder & Decoder : Microprocessor-controlled

Transmitting Range : 100 Meters / 300 Feet (indoors)

Hamming Distance : >6

Frequency Control : Synthesized PLL (Phase Lock Loop)

Receiver Type : Frequency Auto Scanning

Receiver Sensitivity : -113dBm Spurious Emission : -50dB Antenna Impedance : 50 ohms

Responding Time : 60 Milliseconds (average)

Transmitting Power : 0.3mW
Enclosure Type : NEMA-4X

Enclosure Rating : IP-66

Output Contact Rating : 250V @ 10 Amps

Transmitter Operating Voltage : DC 3.0V Receiver Power Consumption : 11.0 VA

Operating Temperature : $-25 \sim 75 / -13 \sim 167$

Transmitter Dimension

 4ES/4EX Models
 :
 138mm (L) x 69mm (W) x 34mm (H)

 8ES/8EX Models
 :
 184mm (L) x 69mm (W) x 34mm (H)

 12ES/12EX Models
 :
 230mm (L) x 69.0mm (W) x 35mm (H)

Receiver Dimension (All Models) : 363mm (L) x 228mm (W) x 70mm (H)

Transmitter Weight

 4ES/4EX Models
 :
 192g / 6.8oz

 8ES/8EX Models
 :
 242g / 8.5oz

 12ES/12EX Models
 :
 296g / 10.4oz

 Receiver Weight (All Models)
 :
 2.5kg / 5.5lb

9. Spare Parts

| 1. | Transmitting Module (433/434MHz) | TRB 01 |
|-----|--|--------|
| 2. | Encoder Board (complete with push buttons) | ENB 05 |
| 3. | I-CHIP (complete) | ICP 01 |
| 4. | Receiving Module | RVB 01 |
| 5. | Decoder Module | DEB 02 |
| 6. | Receiver Relay Board | RLB 05 |
| 7. | AC Line Filter Board | LFB 01 |
| 8. | Power Transformer | |
| | AC 110~120V/220~240V/380~410V/440~460V | PTF 01 |
| | AC 24V/42V/48V | PTF 02 |
| | DC 12V/24V | PTF 03 |
| 9. | Transmitter Top Casing | TTC 02 |
| 10. | Transmitter Bottom Casing | TBC 02 |
| 11. | Transmitter Battery Cover | TBC 04 |
| 12. | Receiver Top Casing | RTC 01 |
| 13. | Receiver Bottom Casing | RBC 01 |
| 14. | Cord Grip | CGR 01 |
| 15. | Shock Mount | SMT 01 |
| 16. | 2-Step Push Button | PBN 02 |
| 17. | 3-Stage Mechanical Selector Switch | SWT 01 |
| 18. | Push Button Rubber Boot | PRB 01 |
| 19. | Emergency Stop Button | EMS 01 |
| 20. | Transmitter Power Keys Switch | PWK 01 |
| 21. | Waist Belt | WBT 01 |
| 22. | Strap Ring | STR 01 |
| 23. | Safety MAIN relay | SMR 01 |
| 24. | Regular Output Relay | RLY 01 |
| 25. | Clear Vinyl Pouch | CVP 02 |
| 26. | External Receiver Antenna | ANT 01 |

