



Product Manual

### Seagate® 600 SSD

Standard 2.5" 7mm Limited Warranty With Media Usage models

ST480HM000 ST240HM000 ST120HM000 Standard 2.5" 5mm Limited Warranty With Media Usage models

ST480HM001 ST240HM001 ST120HM001

100722309 Rev. B May 2013

### **Document Revision History**

| Revision | Date       | Description of changes |
|----------|------------|------------------------|
| Rev. A   | 04/11/2013 | Initial release.       |
| Rev. B   | 05/13/2013 | 1, 3, 4 and 13.        |

© 2013 Seagate Technology LLC. All rights reserved.

Publication number: 100722309, Rev. B May 2013

Seagate, Seagate Technology and the Wave logo are registered trademarks of Seagate Technology LLC in the United States and/or other countries. Seagate 600 SSD and SeaTools are either trademarks or registered trademarks of Seagate Technology LLC or one of its affiliated companies in the United States and/or other countries. The FIPS logo is a certification mark of NIST, which does not imply product endorsement by NIST, the U.S., or Canadian governments. All other trademarks or registered trademarks are the property of their respective owners.

No part of this publication may be reproduced in any form without written permission of Seagate Technology LLC. Call 877-PUB-TEK1 (877-782-8351) to request permission.

When referring to drive capacity, one gigabyte, or GB, equals one billion bytes and one terabyte, or TB, equals one trillion bytes. Your computer's operating system may use a different standard of measurement and report a lower capacity. In addition, some of the listed capacity is used for formatting and other functions, and thus will not be available for data storage. Actual quantities will vary based on various factors, including file size, file format, features and application software. Actual data rates may vary depending on operating environment and other factors. The export or re-export of hardware or software containing encryption may be regulated by the U.S. Department of Commerce, Bureau of Industry and Security (for more information, visit www.bis.doc.gov), and controlled for import and use outside of the U.S. Seagate reserves the right to change, without notice, product offerings or specifications.

# Contents

| 0 | Introc     | luction  |
|---|------------|--|
|   | 1.1        | About the Serial ATA interface 2   |
| ) | Drive      | specifications   |
|   | 2.1        | Specification summary tables   |
|   | 2.2        | Formatted capacity   |
|   |            | 2.2.1 LBA mode   |
|   | 2.3        | Default logical geometry for ATA based systems   |
|   | 2.4        | Performance, Recording and interface technology  |
|   | 2.4        | 2.4.1 Interface technology   |
|   |            | 2.4.1       Interface technology       3         2.4.2       Recording technology       5  |
|   |            | 2.4.2 Performance  |
|   | 2.5        | Physical characteristics   |
|   |            |  |
|   | 2.6        | Time to Ready  |
|   | 2.7        | Power specifications   |
|   |            | 2.7.1 Power consumption  |
|   |            | 2.7.2 DC power requirements  |
|   | 2.8        | Environmental specifications   |
|   |            | 2.8.1 Temperature  |
|   |            | 2.8.2 Temperature gradient   |
|   |            | 2.8.3 Humidity   |
|   |            | 2.8.4 Altitude   |
|   |            | 2.8.5 Shock  |
|   |            | 2.8.6 Vibration  |
|   | 2.9        | Electromagnetic immunity   |
|   | 2.10       | Reliability  |
|   |            | 2.10.1 Annualized Failure Rate (AFR) and Mean Time Between Failures (MTBF) 13              |
|   |            | 2.10.2 Reliability specifications  |
|   | 2.11       | Agency certification   |
|   |            | 2.11.1 Safety certification  |
|   |            | 2.11.2 Electromagnetic compatibility 14  |
|   |            | 2.11.3 FCC verification  |
|   | 2.12       | Environmental protection   |
|   |            | 2.12.1 European Union Restriction of Hazardous Substances (RoHS) Directive 15              |
|   |            | 2.12.2 China Restriction of Hazardous Substances (RoHS) Directive                          |
|   | 2.13       | Corrosive environment  |
|   | Confi      | guring and mounting the drive  |
|   | 3.1        | Handling and static-discharge precautions  |
|   | 3.2        | Configuring the drive  |
|   | 3.3        | Serial ATA cables and connectors   |
|   | 3.4        | Drive mounting   |
|   | 3.5        | Cooling  |
|   | Serial     | ATA (SATA) interface   |
|   | 4.1        | Hot-Plug compatibility   |
|   | 4.1        | Serial ATA device plug connector pin definitions   |
|   | 4.2<br>4.3 | Supported ATA commands   |
|   | 4.0        | 4.3.1 Identify Device command  |
|   |            | <b>,</b>   |
|   |            |  |
|   |            | 4.3.2       Set Features command       30         4.3.3       S.M.A.R.T. commands       31 |

# **FIGURES**

| Figure 1. | Typical 5V Startup and Operation Current Profile | 10 |
|-----------|--|----|
| Figure 2. | Attaching SATA cabling                           | 16 |
| Figure 3. | Mounting configuration dimensions (7mm models)   | 17 |
| Figure 4. | Mounting configuration dimensions (5mm models)   | 18 |
| Figure 5. | Air flow   | 19 |

# Seagate Technology Support Services

For information regarding online support and services, visit http://www.seagate.com/about/contact-us/technical-support/

Available services include:

- Presales & Technical support
- Global Support Services telephone numbers & business hours
- Authorized Service Centers

Warranty terms will vary based on type of warranty chosen: "Managed Life" or "Limited Warranty With Media Usage". Consult your Seagate sales representative for warranty terms and conditions.

For information regarding data recovery services, visit http://www.seagate.com/services-software/data-recovery-services/

For Seagate OEM and Distribution partner portal, visit: http://www.seagate.com/partners/

For Seagate reseller portal, visit: http://www.seagate.com/partners/my-spp-dashboard/

### **1.0** INTRODUCTION

This manual describes the functional, mechanical and interface specifications for the following Seagate<sup>®</sup> 600 SSD model drives:

| 2.5" Limited Warranty With<br>Media, 7mm Model | 2.5" Limited Warranty With<br>Media, 5mm Model |
|--|--|
| ST480HM000                                     | ST480HM001                                     |
| ST240HM000                                     | ST240HM001                                     |
| ST120HM000                                     | ST120HM001                                     |

These drives provide the following key features:

- Multi-Level Cell (19nm MLC) NAND Flash storage.
- Serial ATA 3.1 Host Interface (SATA 6Gb/s).
- High instantaneous (burst) data-transfer rates (up to 530MB/s).
- Parallel flash access channels.
- State-of-the-art on-the-fly error-correction algorithms.
- Native Command Queueing with command ordering to increase performance in demanding applications.
- · Highly integrated hardware functions.
- Data Set Management with Trim Support.
- · Silent operation.
- · SeaTools diagnostic software performs a drive self-test that eliminates unnecessary drive returns.
- Support for S.M.A.R.T. drive monitoring and reporting.
- Supports latching SATA cables and connectors.
- · Worldwide Name (WWN) capability uniquely identifies the drive.

#### 1.1 ABOUT THE SERIAL ATA INTERFACE

The Serial ATA interface provides several advantages:

- Easy installation and configuration with true plug-and-play connectivity. It is not necessary to set any jumpers or other configuration options.
- Thinner and more flexible cabling for improved enclosure airflow and ease of installation.
- Scalability to higher performance levels.

The Serial ATA interface connects each drive in a point-to-point configuration with the Serial ATA host adapter. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both "masters" on two separate ports.

**Note.** The host adapter may, optionally, emulate a master/slave environment to host software where two devices on separate Serial ATA ports are represented to host software as a Device 0 (master) and Device 1 (slave) accessed at the same set of host bus addresses. A host adapter that emulates a master/slave environment manages two sets of shadow registers. This is not a typical Serial ATA environment.

The Serial ATA host adapter and drive share the function of emulating parallel ATA device behavior to provide backward compatibility with existing host systems and software. The Command and Control Block registers, PIO and DMA data transfers, resets, and interrupts are all emulated.

The Serial ATA host adapter contains a set of registers that shadow the contents of the traditional device registers, referred to as the Shadow Register Block. All Serial ATA devices behave like Device 0 devices. For additional information about how Serial ATA emulates parallel ATA, refer to the "Serial ATA: High Speed Serialized AT Attachment" specification. The specification can be downloaded from <u>www.serialata.org</u>.

### 2.0 DRIVE SPECIFICATIONS

Unless otherwise noted, all specifications are measured under ambient conditions, at 25°C, and nominal power. For convenience, the phrases *the drive* and *this drive* are used throughout this manual to indicate the following drive models:

|                            | Capacity   |            |            |            |            |            |  |
|----------------------------|------------|------------|------------|------------|------------|------------|--|
| 2.5" Limited Warranty With | 480GB      |            | 240GB      |            | 120GB      |            |  |
| Media Usage                | ST480HM000 | ST480HM001 | ST240HM000 | ST240HM001 | ST120HM000 | ST120HM001 |  |

Product data communicated in this manual is specific only to the model numbers listed in this manual. The data listed in this manual may not be predictive of future generation specifications or requirements. If you are designing a system which will use one of the models listed or future generation products and need further assistance, please contact your Customer Technical Support Engineer or our global support services group as shown in See "Seagate Technology Support Services" on page 1.

#### 2.1 SPECIFICATION SUMMARY TABLES

The specifications listed in the following table is for quick reference. For details on specification measurement or definition, see the appropriate section of this manual.

#### Table 1 Drive specifications summary for 2.5" - 480, 240 and 120 GB models

| Drive specification   | ST480HM000   | ST480HM001          | ST240HM000          | ST240HM001          | ST120HM000          | ST120HM001          |  |
|---|--|---------------------|---------------------|---------------------|---------------------|---------------------|--|
| Formatted GB (512 bytes/sector)*                                    | 480  |                     | 240                 |                     | 120                 |                     |  |
| Guaranteed logical block addresses (LBAs)                           | 937,70   | 03,088              | 468,862,128         |                     | 234,441,648         |                     |  |
| Emulated Bytes per LBA  | 512  |                     |                     |                     |                     |                     |  |
| Sustained 128KB sequential read/write data transfer rate (MB/s max) |  |                     | 530/                | 440                 |                     |                     |  |
| Peak 4KB Random read/write command rate (KIOPs)                     |  | 80/70               |                     |                     |                     |                     |  |
| Flash Memory Type   |  |                     | NAND                | MLC                 |                     |                     |  |
| I/O data-transfer rate (MB/s max)                                   |  |                     | 60                  | 00                  |                     |                     |  |
| Height (mm max)   | 7.0mm<br>(0.276 in)  | 5.0mm<br>(0.197 in) | 7.0mm<br>(0.276 in) | 5.0mm<br>(0.197 in) | 7.0mm<br>(0.276 in) | 5.0mm<br>(0.197 in) |  |
| Width (mm max)  |  |                     | 70.10 mm            | (2.760 in)          | •                   |                     |  |
| Length (mm max)   |  |                     | 100.45 mm           | ı (3.955 in)        |                     |                     |  |
| Weight (max)  | 77 g<br>(0.170 lb)   | 67 g<br>(0.148lbs)  | 77 g<br>(0.170 lb)  | 67 g<br>(0.148 lbs) | 77 g<br>(0.170 lb)  | 67 g<br>(0.148 lbs) |  |
| Power-on to ready (typ)   |  |                     | <1 :                | sec                 | •                   |                     |  |
| Standby to ready (max)  |  |                     | 3 s                 | ec                  |                     |                     |  |
| Data Retention (typical minimum at 30°C)                            |  |                     | 12 m                | onths               |                     |                     |  |
| Startup current 5V (max)  |  |                     | 950                 | mA                  |                     |                     |  |
| Voltage tolerance (including noise)                                 |  |                     | 5V ±                | : 5%                |                     |                     |  |
| Temperature   | 0° to 70°C (operating as reported by SMART attribute 194)<br>-40° to 75°C (nonoperating) |                     |                     |                     |                     |                     |  |
| Temperature gradient (°C per hour max)                              | 20°C (operating)<br>20°C (nonoperating)  |                     |                     |                     |                     |                     |  |
| Relative humidity   | 5% to 95% (operating)<br>5% to 95% (nonoperating)  |                     |                     |                     |                     |                     |  |
| Relative humidity gradient  |  |                     | 20% per l           | nour max            |                     |                     |  |
| Wet bulb temperature (°C max)                                       |  |                     | 2                   | 9                   |                     |                     |  |
| Altitude, operating   | –61 m to 3048 m<br>(–200 ft. to 10,000+ ft.)   |                     |                     |                     |                     |                     |  |
| Altitude, nonoperating<br>(below mean sea level, max)               | -61 m to 12,192 m<br>(-200 ft to 40,000+ ft)   |                     |                     |                     |                     |                     |  |
| Operational Shock (max at 0.5ms)                                    | 1500 Gs  |                     |                     |                     |                     |                     |  |
| Non-Operational Shock (max at 0.5ms)                                | 1500 Gs  |                     |                     |                     |                     |                     |  |
| Vibration, random operating   | 20–2000 Hz: 11.08 Grms   |                     |                     |                     |                     |                     |  |

| Drive specification   | ST480HM000                               | ST480HM001 | ST240HM000 | ST240HM001 | ST120HM000 | ST120HM001 |  |
|---|--|------------|------------|------------|------------|------------|--|
| Vibration, random nonoperating  | 20–2000 Hz: 11.08 Grms                   |            |            |            |            |            |  |
| Nonrecoverable read errors, max   | 1 LBA per 10 <sup>16</sup> bits read     |            |            |            |            |            |  |
| Annualized Failure Rate (AFR)   | 0.58%                                    |            |            |            |            |            |  |
| Warranty  | 3-Year Limited Warranty With Media Usage |            |            |            |            |            |  |
| Lifetime Power cycles   | 25,000                                   |            |            |            |            |            |  |
| Supports Hotplug operation per<br>Serial ATA Revision 3.0 specification | Yes                                      |            |            |            |            |            |  |

\*One GB equals one billion bytes when referring to drive capacity. Accessible capacity may vary depending on operating environment and formatting.

\*\*Warranty terms are "Limited Warranty With Media Usage", see Warranty information in Section 2.10.2 or consult your Seagate sales representative for warranty terms and conditions.

#### 2.2 FORMATTED CAPACITY

| Formatted capacity* | Guaranteed LBAs | Emulated LBA Size (Bytes) |  |  |
|---------------------|-----------------|---------------------------|--|--|
| 480GB               | 937,703,088     |                           |  |  |
| 240GB               | 468,862,128     | 512                       |  |  |
| 120GB               | 234,441,648     |                           |  |  |

\*One GB equals one billion bytes when referring to drive capacity. Accessible capacity may vary depending on operating environment and formatting.

#### 2.2.1 LBA mode

When addressing these drives in LBA mode, all blocks (LBAs) are consecutively numbered from 0 to n-1, where n is the number of guaranteed LBAs as defined above.

See Section 4.3.1, "Identify Device command" (words 60-61 and 100-103) for additional information about 48-bit addressing support of drives with capacities over 137GB.

#### 2.3 DEFAULT LOGICAL GEOMETRY FOR ATA BASED SYSTEMS

| Cylinders | Read/write heads | Sectors per track |
|-----------|------------------|-------------------|
| 16,383    | 16               | 63                |

#### 2.4 PERFORMANCE, RECORDING AND INTERFACE TECHNOLOGY

#### 2.4.1 Interface technology

|                                | 480GB models       | 240GB models          | 120GB models |  |  |  |
|--------------------------------|--------------------|-----------------------|--------------|--|--|--|
| Interface                      | Serial ATA (SATA-I | Serial ATA (SATA-II)  |              |  |  |  |
| Interface Speeds Supported     | 6Gb/s, 3Gb/s, 1.5G | 6Gb/s, 3Gb/s, 1.5Gb/s |              |  |  |  |
| Maximum Burst Transfer Rate    | 600MB/s            | 600MB/s               |              |  |  |  |
| Hot Plug Support               | Yes                | Yes                   |              |  |  |  |
| Native Command Queuing Support | Yes                |                       |              |  |  |  |
| Trim Support                   | Yes                |                       |              |  |  |  |

#### 2.4.2 Recording technology

| Flash Memory Type                                   | NAND MLC  |
|---|-----------|
| Emulated LBA Size (Bytes)                           | 512       |
| Default transfer alignment offset                   | 0         |
| Typical Data Retention with Power removed (at 30°C) | 12 months |

#### 2.4.3 Performance

|   | Notes | 480GB | 240GB   | 120GB |
|---|-------|-------|---------|-------|
| Sustained sequential 128KB read/write data transfer rate (MB/s) | [1]   |       | 530/440 |       |
| Peak 4KB random read/write command rate (KIOPs)                 | [2]   |       | 80/70   |       |

[1] Testing performed at Queue Depth = 32, Sequentially Preconditioned drive, using IOMeter 2006.7.27.

[2] Testing performed at Queue Depth = 32, Randomly Preconditioned drive, using IOMeter 2006.7.27.

**Note.** IOMeter is available at http://www.iometer.org/ or http://sourceforge.net/projects/iometer/. IOMeter is licensed under the Intel Open Source License and the GNU General Public License. Intel does not endorse any IOMeter results.

Peak performance is defined as the typical best case performance that the product will be able to achieve when the product is preconditioned as mentioned and host commands are aligned on 4KB boundaries.

Sustained performance is defined as the typical worst case pe rformance that the product will be able to achieve when the product is preconditioned as mentioned and host commands are aligned on 4KB boundaries.

Due to the nature of Flash memory technologies there are many factors that can result in values different than those stated in this specification. Some discrepancies can be caused by bandwidth limitations in the host adapter, operating system, or driver limitations. It is not the intent of this manual to cover all possible causes of performance discrepancies.

When evaluating performance of SSD devices, it is recommended to measure performance of the device in a method that resembles the targeted application using real world data and workloads. Test time should also be adequately large to ensure that sustainable metrics and measures are obtained.

### 2.5 PHYSICAL CHARACTERISTICS

|                | ST480HM000, ST240HM000         ST480HM001, ST240HM001           & ST120HM000         & ST120HM001 |                 |  |  |
|----------------|---|-----------------|--|--|
| Maximum height | 7.00 mm (0.276 in) 5.00 mm (0.197 in)   |                 |  |  |
| Maximum width  | 70.10 mm (2.760 in)   |                 |  |  |
| Maximum length | 100.45 mm (3.955 in)  |                 |  |  |
| Max weight     | 77 g (0.170lb)  | 67 g (0.148 lb) |  |  |

### 2.6 TIME TO READY

|                         | 480GB | 240GB    | 120GB |
|-------------------------|-------|----------|-------|
| Power-on to Ready (sec) |       | <1 (typ) |       |

#### 2.7 POWER SPECIFICATIONS

The drive receives DC power (+5V) through a native SATA power connector. See 2 on page 16.

#### 2.7.1 Power consumption

Power requirements for the drives are listed in the table on page 9. Typical power measurements are based on an average of drives tested, under nominal conditions, at 35°C ambient temperature.

#### • Startup power

Startup power is measured from the time of power-on to the time that the drive reaches operating condition and can process media access commands.

#### Peak operating mode

During peak operating mode, the drive is tested in various read and write access patterns to simulate the worst-case power consumption.

#### Idle mode power

Idle mode power is measured with the drive powered up and ready for media access commands, with no media access commands having been received from the host.

#### • Standby mode

During Standby mode, the drive accepts commands, but not be able to immediately access the media because the drive electronics are in a partial power-down mode.

#### 2.7.2 DC power requirements

#### Table 2 480GB DC power requirements

| Parameter                                  | ST480HM000<br>ST480HM001 | ,<br>(6.0Gb) |
|--|--------------------------|--------------|
| Voltage                                    | +5V                      | Power        |
| Regulation                                 | +/- 5%                   | (watts)      |
| Average Idle Current                       | 0.22                     | 1.10         |
| Average Sleep Current                      | 0.10                     | 0.50         |
| Maximum Start Current                      | 0.95                     |              |
| DC (Peak DC)                               | 0.54                     |              |
| AC (Peak AC)                               | 0.40                     |              |
| Peak Operating Current (random read):      |                          |              |
| Typical DC                                 | 0.32                     | 1.59         |
| Maximum DC                                 | 0.33                     | 1.63         |
| Maximum DC (peak)                          | 0.90                     | 4.50         |
| Peak Operating Current (random write):     |                          |              |
| Typical DC                                 | 0.40                     | 2.02         |
| Maximum DC                                 | 0.46                     | 2.31         |
| Maximum DC (peak)                          | 1.44                     | 7.20         |
| Peak Operating Current (sequential read):  |                          |              |
| Typical DC                                 | 0.44                     | 2.18         |
| Maximum DC                                 | 0.45                     | 2.20         |
| Maximum DC (peak)                          | 1.02                     | 5.10         |
| Peak Operating Current (sequential write): |                          |              |
| Typical DC                                 | 0.52                     | 2.61         |
| Maximum DC                                 | 0.60                     | 2.99         |
| Maximum DC (peak)                          | 1.50                     | 7.50         |

\*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase power to operational levels.

#### Table 3 240GB DC power requirements

| Parameter                                  | ST240HM000<br>ST240HM001 | ),<br>(6.0Gb) |
|--|--------------------------|---------------|
| Voltage                                    | +5V                      | Power         |
| Regulation                                 | +/- 5%                   | (watts)       |
| Average Idle Current                       | 0.22                     | 1.10          |
| Average Sleep Current                      | 0.10                     | 0.50          |
| Maximum Start Current                      | 0.95                     |               |
| DC (Peak DC)                               | 0.52                     |               |
| AC (Peak AC)                               | 0.38                     |               |
| Peak Operating Current (random read):      |                          |               |
| Typical DC                                 | 0.32                     | 1.57          |
| Maximum DC                                 | 0.34                     | 1.68          |
| Maximum DC (peak)                          | 0.78                     | 3.90          |
| Peak Operating Current (random write):     |                          |               |
| Typical DC                                 | 0.41                     | 2.03          |
| Maximum DC                                 | 0.46                     | 2.27          |
| Maximum DC (peak)                          | 1.22                     | 6.10          |
| Peak Operating Current (sequential read):  |                          |               |
| Typical DC                                 | 0.43                     | 2.06          |
| Maximum DC                                 | 0.44                     | 2.309         |
| Maximum DC (peak)                          | 0.92                     | 4.20          |
| Peak Operating Current (sequential write): |                          |               |
| Typical DC                                 | 0.53                     | 2.64          |
| Maximum DC                                 | 0.56                     | 2.82          |
| Maximum DC (peak)                          | 1.28                     | 6.40          |

\*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase power to operational levels.

#### Table 4 120GB DC power requirements

| Parameter                                  | ST120HM000<br>ST120HM001 | ,<br>(6.0Gb) |
|--|--------------------------|--------------|
| Voltage                                    | +5V                      | Power        |
| Regulation                                 | +/- 5%                   | (watts)      |
| Average Idle Current                       | 0.22                     | 1.10         |
| Average Sleep Current                      | 0.10                     | 0.50         |
| Maximum Start Current                      | 0.95                     |              |
| DC (Peak DC)                               | 0.54                     |              |
| AC (Peak AC)                               | 0.70                     |              |
| Peak Operating Current (random read):      |                          |              |
| Typical DC                                 | 0.34                     | 1.67         |
| Maximum DC                                 | 0.35                     | 1.72         |
| Maximum DC (peak)                          | 0.82                     | 4.10         |
| Peak Operating Current (random write):     |                          |              |
| Typical DC                                 | 0.51                     | 2.54         |
| Maximum DC                                 | 0.56                     | 2.18         |
| Maximum DC (peak)                          | 1.42                     | 7.10         |
| Peak Operating Current (sequential read):  |                          |              |
| Typical DC                                 | 0.43                     | 2.30         |
| Maximum DC                                 | 0.44                     | 2.34         |
| Maximum DC (peak)                          | 0.92                     | 4.40         |
| Peak Operating Current (sequential write): |                          |              |
| Typical DC                                 | 0.53                     | 2.64         |
| Maximum DC                                 | 0.56                     | 2.90         |
| Maximum DC (peak)                          | 1.28                     | 6.40         |

\*During periods of drive idle, some offline activity may occur according to the S.M.A.R.T. specification, which may increase power to operational levels.



#### 2.7.2.1 Typical current profiles

Figure 1. Typical 5V Startup and Operation Current Profile

#### 2.8 ENVIRONMENTAL SPECIFICATIONS

#### 2.8.1 Temperature

Temperature is defined as the drive's internal temperature as reported by SMART attribute 194 for operation or the drive case temperature for non-operating.

Above 1000 feet (305 meters), the maximum temperature is derated linearly to 112°F (44°C) at 10,000 feet (3048 meters).

| Operating:    | 0° to 70°C (32° to 158°F)    |
|---------------|------------------------------|
| Nonoperating: | -40° to 75°C (-40° to 167°F) |

#### 2.8.2 Temperature gradient

| Operating:    | 20°C per hour (30°F per hour max), without condensation |
|---------------|---|
| Nonoperating: | 20°C per hour (30°F per hour max)                       |

#### 2.8.3 Humidity

#### 2.8.3.1 Relative humidity

| Operating:    | 5% to 95% noncondensing (20% per hour max) |
|---------------|--|
| Nonoperating: | 5% to 95% noncondensing (20% per hour max) |

#### 2.8.3.2 Wet bulb temperature

| Operating:    | 29°C (84°F max) |
|---------------|-----------------|
| Nonoperating: | 29°C (84°F max) |

#### 2.8.4 Altitude

| ** Operating:    | -61 m to 3048 m (-200 ft. to 10,000+ ft.)   |
|------------------|---|
| ** Nonoperating: | -61 m to 12,192 m (-200 ft. to 40,000+ ft.) |

\*\* Applies to atmospheric pressure only.

#### 2.8.5 Shock

All shock specifications assume that the drive is mounted securely with the input shock applied at the drive mounting screws. Shock may be applied in the X, Y or Z axis.

#### 2.8.5.1 Operating shock

These drives comply with the performance levels specified in this document when subjected to a maximum operating shock of 1500 Gs based on half-sine shock pulses of 0.5ms. This specification does not cover connection issues that may result from testing at this level.

#### 2.8.5.2 Nonoperating shock

The nonoperating shock level that the drive can experience without incurring physical damage or degradation in performance when subsequently put into operation is 1500 Gs based on a half-sine shock pulse of 0.5ms duration.

#### 2.8.6 Vibration

All vibration specifications assume that the drive is mounted securely with the input vibration applied at the drive mounting screws. Vibration may be applied in the X, Y or Z axis.

#### 2.8.6.1 Operating vibration

The maximum random vibration levels that the drive may experience while meeting the performance standards specified in this document are specified below. This specification does not cover connection issues that may result from testing at this level.

|--|

#### 2.8.6.2 Nonoperating vibration

The maximum random nonoperating vibration levels that the drive may experience without incurring physical damage or degradation in performance when subsequently put into operation are specified below.

| 20–2000 Hz | 11.08 Grms |
|------------|------------|
|            |            |

#### 2.9 ELECTROMAGNETIC IMMUNITY

When properly installed in a representative host system, the drive operates without errors or degradation in performance when subjected to the radio frequency (RF) environments defined in the following table:

 Table 5
 Radio frequency environments

| Теят                      | DESCRIPTION   | Performance<br>Level | REFERENCE<br>STANDARD             |
|---------------------------|---|----------------------|-----------------------------------|
| Electrostatic discharge   | Contact, HCP, VCP: ± 4 kV; Air: ± 8 kV  | В                    | EN 61000-4-2: 95                  |
| Radiated RF immunity      | 80 to 1000 MHz, 3 V/m,<br>80% AM with 1 kHz sine<br>900 MHz, 3 V/m, 50% pulse modulation @ 200 Hz | A                    | EN 61000-4-3: 96<br>ENV 50204: 95 |
| Electrical fast transient | ± 1 kV on AC mains, ± 0.5 kV on external I/O  | В                    | EN 61000-4-4: 95                  |
| Surge immunity            | ± 1 kV differential, ± 2 kV common, AC mains  | В                    | EN 61000-4-5: 95                  |
| Conducted RF immunity     | 150 kHz to 80 MHz, 3 Vrms, 80% AM with 1 kHz sine   | A                    | EN 61000-4-6: 97                  |
| Voltage dips, interrupts  | 0% open, 5 seconds<br>0% short, 5 seconds<br>40%, 0.10 seconds<br>70%, 0.01 seconds               | C<br>C<br>C<br>B     | EN 61000-4-11: 94                 |

#### 2.10 RELIABILITY

#### 2.10.1 Annualized Failure Rate (AFR) and Mean Time Between Failures (MTBF)

The product shall achieve an Annualized Failure Rate - AFR - of 0.58%. AFR and MTBF are population statistics that are not relevant to individual units.

AFR and MTBF specifications are based on the following assumptions:

- 8760 power-on-hours per year.
- 250 average power cycles per year.
- Operations at nominal voltages.
- Systems will provide adequate cooling to ensure the case temperatures do not exceed specification.

#### 2.10.2 Reliability specifications

| Unrecoverable read error rate during                | 1 LBA per 10 <sup>16</sup> bits read, max  |
|---|--|
| Annualized Failure Rate (AFR)                       | 0.58%  |
| Power cycles  | 25,000 cycles<br>(at nominal voltage and temperature, with 60 cycles per hour<br>and a 50% duty cycle)   |
| Warranty  | Warranty terms are "Limited Warranty With Media Usage" <sup>[2]</sup><br>Consult your Seagate sales representative for warranty terms<br>and conditions. |
| Preventive maintenance                              | None required.   |
| Typical Data Retention with Power removed (at 40°C) | 12 months <sup>[1]</sup>   |
| Endurance   | 40GBs (max capacity) host writes per day   |

- [1] As NAND Flash devices age with use, the capability of the media to retain a programmed value begins to deteriorate. This deterioration is affected by the number of times a particular memory cell is programmed and subsequently erased. When a device is new, it has a powered off data retention capability of up to ten years. With use the retention capability of the device is reduced. Temperature also has an effect on how long a Flash component can retain its programmed value with power removed. At high temperature the retention capabilities of the device are reduced. Data retention is not an issue with power applied to the SSD. The SSD drive contains firmware and hardware features that can monitor and refresh memory cells when power is applied.
- [2] Limited Warranty With Media Usage: This warranty is based on the shorter of term and endurance usage of the drive: 36 months or 73 (max capacity) TBW whichever comes first.

#### 2.11 AGENCY CERTIFICATION

#### 2.11.1 Safety certification

These products are certified to meet the requirements of UL60950-1, CSA60950-1 and EN60950 and so marked as to the certify agency.

#### 2.11.2 Electromagnetic compatibility

Drives that display the CE mark comply with the European Union (EU) requirements specified in the Electromagnetic Compatibility Directive (2004/108/EC) as put into place 20 July 2007. Testing is performed to the levels specified by the product standards for Information Technology Equipment (ITE). Emission levels are defined by EN 55022, Class B and the immunity levels are defined by EN 55024.

Seagate uses an independent laboratory to confirm compliance with the EC directives specified in the previous paragraph. Drives are tested in representative end-user systems. Although CE-marked Seagate drives comply with the directives when used in the test systems, we cannot guarantee that all systems will comply with the directives. The drive is designed for operation inside a properly designed enclosure, with properly shielded I/O cable (if necessary) and terminators on all unused I/O ports. Computer manufacturers and system integrators should confirm EMC compliance and provide CE marking for their products.

#### Korean KCC

If these drives have the Korean Communications Commission (KCC) logo, they comply with KN22 and KN61000.

#### Australian C-Tick (N176)

If these models have the C-Tick marking, they comply with the Australia/New Zealand Standard AS/NZ CISPR22 and meet the Electromagnetic Compatibility (EMC) Framework requirements of the Australian Communication Authority (ACA).

#### 2.11.3 FCC verification

These drives are intended to be contained solely within a personal computer or similar enclosure (not attached as an external device). As such, each drive is considered to be a subassembly even when it is individually marketed to the customer. As a subassembly, no Federal Communications Commission verification or certification of the device is required.

Seagate Technology LLC has tested this device in enclosures as described above to ensure that the total assembly (enclosure, drive, motherboard, power supply, etc.) does comply with the limits for a Class B computing device, pursuant to Subpart J, Part 15 of the FCC rules. Operation with noncertified assemblies is likely to result in interference to radio and television reception.

**Radio and television interference.** This equipment generates and uses radio frequency energy and if not installed and used in strict accordance with the manufacturer's instructions, may cause interference to radio and television reception.

This equipment is designed to provide reasonable protection against such interference in a residential installation. However, there is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television, which can be determined by turning the equipment on and off, you are encouraged to try one or more of the following corrective measures:

- Reorient the receiving antenna.
- Move the device to one side or the other of the radio or TV.
- Move the device farther away from the radio or TV.
- Plug the computer into a different outlet so that the receiver and computer are on different branch outlets.

If necessary, you should consult your dealer or an experienced radio/television technician for additional suggestions. You may find helpful the following booklet prepared by the Federal Communications Commission: *How to Identify and Resolve Radio-Television Interference Problems*. This booklet is available from the Superintendent of Documents, U.S. Government Printing Office, Washington, DC 20402. Refer to publication number 004-000-00345-4.

#### 2.12 ENVIRONMENTAL PROTECTION

Seagate designs its products to meet environmental protection requirements worldwide, including regulations restricting certain chemical substances.

#### 2.12.1 European Union Restriction of Hazardous Substances (RoHS) Directive

The European Union Restriction of Hazardous Substances (RoHS) Directive, restricts the presence of chemical substances, including Lead, Cadmium, Mercury, Hexavalent Chromium, PBB and PBDE, in electronic products, effective July 2006. This drive is manufactured with components and materials that comply with the RoHS Directive.

#### 2.12.2 China Restriction of Hazardous Substances (RoHS) Directive 中国限制危险物品的指令

This product has an Environmental Protection Use Period (EPUP) of 20 years. The following table contains information mandated by China's "Marking Requirements for Control of Pollution Caused by Electronic Information Products" Standard.



该产品具有20年的环境保护使用周期 (EPUP)。 下表包含了中国 "电子产品所导致的污染的控制的记号要求"所指定的信息。

| r                     |               | Toxic or Hazardous Substances or Elements<br>有毒有害物质或元素 |                   |                                      |   |  |
|-----------------------|---------------|--|-------------------|--------------------------------------|---|--|
| Name of Parts<br>部件名称 | Lead<br>铅(Pb) | Mercury<br>汞 (Hg)                                      | Cadmium<br>镐 (Cd) | Hexavalent<br>Chromium<br>六价铬 (Cr6+) | Polybrom in ated<br>Diphen yl<br>多溴联苯 (PBB) | Polybrominated<br>Diphenyl Ether<br>多溴二苯醚 (PBDE) |
| PCBA                  | Х             | 0  | 0                 | 0                                    | 0   | 0  |
| CHASSIS               | Х             | 0  | 0                 | 0                                    | 0   | 0  |

"O" indicates the hazardous and toxic substance content of the part (at the homogenous material level) is lower than the threshold defined by the China RoHS MCV Standard.

"O"表示该部件(于同类物品程度上)所含的危险和有毒物质低于中国RoHS MCV标准所定义的门槛值。

"X" indicates the hazardous and toxic substance content of the part (at the homogenous material level) is over the threshold defined by the China RoHS MCV Standard.

"X"表示该部件(于同类物品程度上)所含的危险和有毒物质超出中国RoHSMCV标准所定义的门槛值。

#### 2.13 CORROSIVE ENVIRONMENT

Seagate electronic drive components pass accelerated corrosion testing equivalent to 10 years exposure to light industrial environments containing sulfurous gases, chlorine and nitric oxide, classes G and H per ASTM B845. However, this accelerated testing cannot duplicate every potential application environment. Users should use caution exposing any electronic components to uncontrolled chemical pollutants and corrosive chemicals as electronic drive component reliability can be affected by the installation environment. The silver, copper, nickel and gold films used in Seagate products are especially sensitive to the presence of sulfide, chloride, and nitrate contaminants. Sulfur is found to be the most damaging.n addition, electronic components should never be exposed to condensing water on the surface of the printed circuit board assembly (PCBA) or exposed to an ambient relative humidity greater than 95%. Materials used in cabinet fabrication, such as vulcanized rubber, that can outgas corrosive compounds should be minimized or eliminated. The useful life of any electronic equipment may be extended by replacing materials near circuitry with sulfide-free alternatives.

### 3.0 CONFIGURING AND MOUNTING THE DRIVE

This section contains the specifications and instructions for configuring and mounting the drive.

#### 3.1 HANDLING AND STATIC-DISCHARGE PRECAUTIONS

After unpacking, and before installation, the drive may be exposed to potential handling and electrostatic discharge (ESD) hazards. Observe the following standard handling and static-discharge precautions:

#### Caution:

- Before handling the drive, put on a grounded wrist strap, or ground yourself frequently by touching the metal chassis of a computer that is plugged into a grounded outlet. Wear a grounded wrist strap throughout the entire installation procedure.
- The drive is fragile—handle it with care.
- Always rest the drive on an antistatic surface until you mount it in the computer.
- Do not touch the connector pins or the printed circuit board.
- Do not remove the factory-installed labels from the drive or cover them with additional labels. Removal voids the warranty. Some factory-installed labels contain information needed to service the drive.

#### 3.2 CONFIGURING THE DRIVE

Each drive on the Serial ATA interface connects point-to-point with the Serial ATA host adapter. There is no master/slave relationship because each drive is considered a master in a point-to-point relationship. If two drives are attached on one Serial ATA host adapter, the host operating system views the two devices as if they were both "masters" on two separate ports. Both drives behave as if they are Device 0 (master) devices.

Serial ATA drives are designed for easy inst allation. If you connect the drive and rec eive a "drive not detected" error, your SATA equipped motherboard or host adapter may use a chipset that does not support SATA 6.0Gb speed autonegotiation. You will need to install a SATA host adapter that supports autonegotiation.

#### 3.3 SERIAL ATA CABLES AND CONNECTORS

The Serial ATA interface cable consists of four conductors in two differential pairs, plus three ground connections. The cable size may be 30 to 26 AWG with a maximum length of one mete r (39.37 inches). See Table 6 for connector pin definitions. Either end of the SATA signal cable can be attached to the drive or host.

For direct backplane connection, the drive connectors are inserted directly into the host receptacle. The drive and the host receptacle incorporate features that enable the direct connection to be hot pluggable and blind mateable.

For installations which require cables, you can connect the drive as illustrated in 2.



Figure 2. Attaching SATA cabling

Each cable is keyed to ensure correct orientation. Seagate 600 SSD drives support latching SATA connectors.

#### 3.4 DRIVE MOUNTING

You can mount the drive in any orientation using four screws in the side-mounting holes or four screws in the bottommounting holes. Follow these important mounting precautions when mounting the drive:

- Allow a minimum clearance of 0.030 in (0.76 mm) around the entire perimeter of the drive for cooling as a guideline. Please refer to Section 3.5 for final cooling requirements.
- Use only M3 x 0.5 metric mounting screws.
- Four (4) threads (0.080 in) minimum screw engagement recommended. Also ensure maximum screw length does not bottom out in mounting holes.
- Do not overtighten the mounting screws (maximum torque: 4.5 in-lb, ± 0.45 in-lb).

Refer to 4 for detailed mounting configuration dimensions. See Section 3.4, "Drive mounting."

| Woight: | 7mm models | 0.170 pounds | 77 grams |
|---------|------------|--------------|----------|
| Weight: | 5mm models | 0.148 pounds | 67 grams |

**Note.** These dimensions conform to the Small Form Factor Standard documented in SFF-8201 and SFF-8223 found at <u>www.sffcommittee.org</u>.



Figure 3. Mounting configuration dimensions (7mm models)

**Note.** These dimensions conform to the Small Form Factor Standard documented in SFF-8120 and SFF-8146 found at <u>www.sffcommittee.org</u>.



Figure 4. Mounting configuration dimensions (5mm models)

### 3.5 COOLING

Cabinet cooling must be designed by the customer so that the ambient temperature immediately surrounding the drive will not exceed temperature conditions specified in Section 2.8.1, "Temperature."

The rack, cabinet, or drawer environment for the drive must provide heat removal. You should confirm that adequate heat removal is provided using the temperature measurement guidelines described in Section 2.8.1.

Forced air flow may be required to keep temperatures at or below the temperatures specified in Section 2.8.1 in which case the drive should be oriented, or air flow directed, so that the least amount of air flow resistance is created while providing air flow to the drive. Also, the shortest possible path between the air inlet and exit should be chosen to minimize the travel lenth of air heated by the drive and other heat sources within the rack, cabinet, or drawer environment.

If forced air is determined to be necessary, possible air-flow patterns are shown in figure 5. The air-flow patterns are created by one or more fans, either forcing or drawing air as shown in the illustrations. Conduction, convection, or other forced air-flow patterns are acceptable as long as the temperature measurement guidelines of Section 2.8.1 are met.





Image may not represent actual product, for reference only.

### 4.0 SERIAL ATA (SATA) INTERFACE

These drives use the industry-standard Serial ATA interface that supports FIS data transfers. It supports ATA programmed input/output (PIO) modes 0–4; multiword DMA modes 0–2, and Ultra DMA modes 0–6.

For detailed information about the Serial ATA interface, refer to the "Serial ATA: High Speed Serialized AT Attachment" specification.

#### 4.1 HOT-PLUG COMPATIBILITY

Seagate 600 SSD drives incorporate connectors which enable you to hot plug these drives in accordance with the Serial ATA II: Extension to Serial ATA 1.0a specification. This specification can be downloaded from www.serialata.org.

#### 4.2 SERIAL ATA DEVICE PLUG CONNECTOR PIN DEFINITIONS

Table 6 summarizes the 2.5" drive Signal and Power SATA Plug.

| Segment | Pin    | Function        | Definition                               |  |
|---------|--------|-----------------|--|--|
|         | S1     | GND             | Ground                                   |  |
|         | S2     | A+              | Differential Signal Pair (Host to Drive) |  |
|         | S3     | A-              |  |  |
| Signal  | S4     | GND             | Ground                                   |  |
|         | S5     | В-              | Differential Signal Pair (Drive to Host) |  |
|         | S6     | B+              |  |  |
|         | S7     | GND             | Ground                                   |  |
|         | Key an | d spacing sepa  | rate signal and power segments           |  |
|         | P1     | V <sub>33</sub> |  |  |
|         | P2     | V <sub>33</sub> | Unused <sup>[2]</sup>                    |  |
|         | P3     | V <sub>33</sub> |  |  |
|         | P4     | GND             | Ground <sup>[1]</sup>                    |  |
|         | P5     | GND             |  |  |
|         | P6     | GND             |  |  |
|         | P7     | V <sub>5</sub>  |  |  |
| Power   | P8     | V <sub>5</sub>  | 5V power to Drive                        |  |
|         | P9     | V <sub>5</sub>  |  |  |
|         | P10    | Ground          | Ground                                   |  |
|         | P11    | LED Signal      | Activity LED: Driven low to light        |  |
|         | P12    | Ground          | Ground <sup>[1]</sup>                    |  |
|         | P13    | V <sub>12</sub> |  |  |
|         | P14    | V <sub>12</sub> | Unused <sup>[3]</sup>                    |  |
|         | P15    | V <sub>12</sub> |  |  |

Table 6 2.5" SATA Connector Plug Pinout

#### Notes:

- [1] Ground pins 4 and 12 mate first on SATA backplane connectors.
- [2] The three  $V_{33}$  pins are unused but connected together on the drive. They can be used for a drive-in-place detection.
- [3] The three  $V_{12}$  pins are unused but connected together on the drive. They can be used for a drive-in-place detection.

| Segment                                     | Pin | Function        | Definition                               |  |  |
|---|-----|-----------------|--|--|--|
|   | S1  | GND             | Ground                                   |  |  |
|   | S2  | A+              | Differential Signal Dair (Heat to Drive) |  |  |
|   | S3  | A-              | Differential Signal Pair (Host to Drive) |  |  |
| Signal                                      | S4  | GND             | Ground                                   |  |  |
|   | S5  | B-              | Differential Signal Bair (Drive to Heat) |  |  |
|   | S6  | B+              | Differential Signal Pair (Drive to Host) |  |  |
|   | S7  | GND             | Ground                                   |  |  |
| Spacing separates signal and power segments |     |                 |  |  |  |
|   | P1  | V <sub>33</sub> | Unused <sup>[2]</sup>                    |  |  |
|   | P2  | V <sub>33</sub> |  |  |  |
|   | P3  | GND             | Ground <sup>[1]</sup>                    |  |  |
|   | P4  | GND             |  |  |  |
| Power                                       | P5  | V <sub>5</sub>  | EV power to Drive                        |  |  |
| Fower                                       | P6  | V <sub>5</sub>  | 5V power to Drive                        |  |  |
|   | P7  | LED Signal      | Activity LED: Driven low to light        |  |  |
|   | Key | Key             | Кеуway                                   |  |  |
|   | P8  | Optional        | Reserved for Seagate use.                |  |  |
|   | P9  | Optional        | Leave unconnected.                       |  |  |

#### Table 7 1.8" SATA Connector Plug Pinout

#### Notes:

- [1] Ground pins 3 and 4 mate first on micro SATA backplane connectors
- [2] The two  $V_{33}$  pins are unused but connected together on the drive. They can be used for a drive-in-place detection.

#### 4.3 SUPPORTED ATA COMMANDS

The following table lists Serial ATA standard commands that the drive supports. For a detailed description of the ATA commands, refer to the Serial ATA: High Speed Serialized AT Attachment specification. See "S.M.A.R.T. commands" on page 31 for details and subcommands used in the S.M.A.R.T. implementation.

#### Table 8 Supported ATA commands

|                                       | COMMAND CODE (IN HEX)              |
|---------------------------------------|------------------------------------|
| Check Power Mode                      | E5 <sub>H</sub>                    |
| Data Set Management with Trim Support | 06 <sub>H</sub>                    |
| Download Microcode                    | 92 <sub>H</sub>                    |
| Flush Cache                           | E7 <sub>H</sub>                    |
| Flush Cache Extended                  | EA <sub>H</sub>                    |
| Identify Device                       | EC <sub>H</sub>                    |
| Idle                                  | E3 <sub>H</sub>                    |
| Idle Immediate                        | E1 <sub>H</sub>                    |
| Initialize Device Parameters          | 91 <sub>H</sub>                    |
| NOP                                   | 00 <sub>H</sub>                    |
| Read Buffer                           | E4 <sub>H</sub>                    |
| Read DMA                              | C8 <sub>H</sub>                    |
| Read DMA Extended                     | 25 <sub>H</sub>                    |
| Read FPDMA Queued                     | 60 <sub>H</sub>                    |
| Read Log Ext                          | 2F <sub>H</sub>                    |
| Read Multiple                         | C4 <sub>H</sub>                    |
| Read Multiple Extended                | 29 <sub>H</sub>                    |
| Read Native Max Address               | F8 <sub>H</sub>                    |
| Read Native Max Address Extended      | 27 <sub>H</sub>                    |
| Read Sectors                          | 20 <sub>H</sub>                    |
| Read Sectors Extended                 | 24 <sub>H</sub>                    |
| Read Verify Sectors                   | 40 <sub>H</sub>                    |
| Read Verify Sectors Extended          | 42 <sub>H</sub>                    |
| Sanitize Block Erase                  | B4 <sub>H</sub> /0012 <sub>H</sub> |
| Sanitize Freeze Lock Ext              | B4 <sub>H</sub> /0020 <sub>H</sub> |
| Sanitize Status Ext                   | B4 <sub>H</sub> /0000 <sub>H</sub> |
| Security Disable Password             | F6 <sub>H</sub>                    |
| Security Erase Prepare                | F3 <sub>H</sub>                    |
| Security Erase Unit                   | F4 <sub>H</sub>                    |
| Security Freeze                       | F5 <sub>H</sub>                    |
| Security Set Password                 | F1 <sub>H</sub>                    |
| Security Unlock                       | F2 <sub>H</sub>                    |
| Set Features                          | EF <sub>H</sub>                    |
| Set Max Address                       | F9 <sub>H</sub>                    |
| Set Max Address Extended              | 37 <sub>H</sub>                    |
|                                       |                                    |

| COMMAND NAME                  | Command code (in hex)             |
|-------------------------------|-----------------------------------|
| Set Multiple Mode             | C6 <sub>H</sub>                   |
| Sleep                         | E6 <sub>H</sub>                   |
| S.M.A.R.T. Disable Operations | B0 <sub>H</sub> / D9 <sub>H</sub> |
| S.M.A.R.T. Enable Operations  | B0 <sub>H</sub> / D8 <sub>H</sub> |
| S.M.A.R.T. Execute Offline    | B0 <sub>H</sub> / D4 <sub>H</sub> |
| S.M.A.R.T. Read Data          | B0 <sub>H</sub> / D0 <sub>H</sub> |
| S.M.A.R.T. Read Log Sector    | B0 <sub>H</sub> / D5 <sub>H</sub> |
| S.M.A.R.T. Return Status      | B0 <sub>H</sub> / DA <sub>H</sub> |
| S.M.A.R.T. Write Log Sector   | B0 <sub>H</sub> / D6 <sub>H</sub> |
| Standby                       | E2 <sub>H</sub>                   |
| Standby Immediate             | E0 <sub>H</sub>                   |
| Write Buffer                  | E8 <sub>H</sub>                   |
| Write DMA                     | CA <sub>H</sub>                   |
| Write DMA Extended            | 35 <sub>H</sub>                   |
| Write DMA FUA Extended        | 3D <sub>H</sub>                   |
| Write FPDMA Queued            | 61 <sub>H</sub>                   |
| Write Log Extended            | 3F <sub>H</sub>                   |
| Write Multiple                | C5 <sub>H</sub>                   |
| Write Multiple Extended       | 39 <sub>H</sub>                   |
| Write Multiple FUA Extended   | CE <sub>H</sub>                   |
| Write Sectors                 | 30 <sub>H</sub>                   |
| Write Sectors Extended        | 34 <sub>H</sub>                   |
| Write Uncorrectable Extended  | 45 <sub>H</sub>                   |

#### 4.3.1 Identify Device command

The Identify Device command (command code  $EC_H$ ) transfers information about the drive to the host following power up. The data is organized as a single 512-byte block of data, whose contents are shown in Table 8 on page 22. All reserved bits or words should be set to zero. Parameters listed with an "x" are drive-specific or vary with the state of the drive. see Section 2.0 on page 3 for default parameter settings.

The following commands contain drive-specific features that may not be included in the Serial ATA specification.

| Word  | DESCRIPTION   | VALUE                               |
|-------|---|-------------------------------------|
| 0     | General configuration   | 0040 <sub>H</sub>                   |
| 1     | Number of logical cylinders (obsolete) 16,383   | 3FFF <sub>H</sub>                   |
| 2     | Specific configuration  | C837 <sub>H</sub>                   |
| 3     | Number of logical heads (obsolete) 16   | 0010 <sub>H</sub>                   |
| 4-5   | Retired   | 0000 <sub>H</sub>                   |
| 6     | Number of logical sectors per logical track (obsolete) 63   | 003F <sub>H</sub>                   |
| 7–8   | Reserved for CompactFlash Association   | 0000 <sub>H</sub>                   |
| 9     | Retired   | 0000 <sub>H</sub>                   |
| 10–19 | Serial number: (ATA ASCII string padded with spaces (20 <sub>H</sub> ))   | ASCII                               |
| 20-21 | Retired   | 0000 <sub>H</sub>                   |
| 22    | Obsolete  | 0000 <sub>H</sub>                   |
| 23–26 | Firmware revision (ATA ASCII string padded with spaces (20h))   | ASCII                               |
| 27–46 | Model number (ATA ASCII string padded with spaces (20h))  | ASCII                               |
| 47    | (Bits 7-0) Maximum number of logical sectors that shall be transferred per DRQ data block on READ/WRITE MULTIPLE commands. 16   | 8010 <sub>H</sub>                   |
| 48    | Reserved for Trusted Computing feature set options  | 4000 <sub>H</sub>                   |
| 49    | Capabilities – Standby Timer, IORDY Support, etc  | 2F00 <sub>H</sub>                   |
| 50    | Capabilities Continued  | 4000 <sub>H</sub>                   |
| 51    | PIO data transfer cycle timing option (Obsolete)  | 0000 <sub>H</sub>                   |
| 52    | Retired   | 0000 <sub>H</sub>                   |
| 53    | Words 54–58, 64–70 and 88 are valid   | 0006 <sub>H</sub>                   |
| 54    | Number of current logical cylinders (Obsolete)  | 3FFF <sub>H</sub>                   |
| 55    | Number of current logical heads (Obsolete)  | 0010 <sub>H</sub>                   |
| 56    | Number of current logical sectors per logical track (Obsolete)  | 003F <sub>H</sub>                   |
| 57–58 | Current capacity in sectors (Obsolete)  | FC10 <sub>H</sub> 00FB <sub>H</sub> |
| 59    | Number of LBAs transferred per Read Multiple or Write Multiple. Sanitize Command Support  | 9110 <sub>H</sub>                   |
| 60–61 | Total number of user addressable logical sectors for 28-bit commands Note: The maxi-<br>mum value allowed in this field is: 0FFFFFFh. If this field contains 0FFFFFFh and the<br>device has user addressable LBAs greater than or 137GB, then words 100103 contain<br>the total number of user addressable LBAs | XXXXXXXXH                           |
| 62    | Obsolete  | 0000 <sub>H</sub>                   |
| 63    | Multiword DMA active and modes supported (see note following this table)  | 0007 <sub>H</sub>                   |
| 64    | Advanced PIO modes supported. SATA = 0003h  | 0003 <sub>H</sub>                   |
| 65    | Minimum Multiword DMA transfer cycle time per word (120ns)  | 0078 <sub>H</sub>                   |
| 66    | Recommended Multiword DMA transfer cycle time (120ns)   | 0078 <sub>H</sub>                   |

| Word    | DESCRIPTION   | VALUE   |
|---------|---|---|
| 67      | Minimum PIO transfer cycle time without flow control (120ns)  | 0078 <sub>H</sub>   |
| 68      | Minimum PIO transfer cycle time with IORDY flow control (120ns)   | 0078 <sub>H</sub>   |
| 69      | Additional Features and Commands supported.<br>Trim Features supported, DMA commands supported  | 0100 <sub>H</sub>   |
| 70      | Reserved  | 0000 <sub>H</sub>   |
| 71–74   | Reserved for ATAPI  | 0000 <sub>H</sub>   |
| 75      | Queue depth   | 001F <sub>H</sub>   |
| 76      | Serial ATA Capabilities Supported   | 870E <sub>H</sub>   |
| 77      | Reserved for Serial ATA   | 0006 <sub>H</sub>   |
| 78      | Serial ATA features supported   | 0056 <sub>H</sub>   |
| 79      | Serial ATA features enabled   | 0040 <sub>H</sub>   |
| 80      | Major version number  | 01F0 <sub>H</sub>   |
| 81      | Minor version number  | 0029 <sub>H</sub>   |
| 82      | Commands and feature sets supported   | 746B <sub>H</sub>   |
| 83      | Commands and feature sets supported   | 7401 <sub>H</sub>   |
| 84      | Commands and feature sets supported   | 4163 <sub>H</sub>   |
| 85      | Commands and feature sets supported or enabled  | 7469 <sub>H</sub>   |
| 86      | Commands and feature sets supported or enabled  | B401 <sub>H</sub>   |
| 87      | Commands and feature sets supported or enabled  | 4163 <sub>H</sub>   |
| 88      | Ultra DMA support and current mode (see note following this table)  | 407F <sub>H</sub>   |
| 89      | Security erase time   | 0004 <sub>H</sub>   |
| 90      | Enhanced security erase time  | 0000 <sub>H</sub>   |
| 91      | Current APM level value   | 0000H   |
| 92      | Master password Identifier  | FFFE <sub>H</sub>   |
| 93      | Hardware reset result   | 0000 <sub>H</sub>   |
| 94      | Reserved  | 0000 <sub>H</sub>   |
| 95–99   | ATA-reserved  | 0000 <sub>H</sub>   |
| 100–103 | Total Number of User Addressable Logical Blocks for 48-bit commands. These words are required for drives that support the 48-bit addressing feature. Maximum value: 0000FFFFFFFFFFFFh | 480GB model = 937,703,088<br>240GB model = 468,862,128<br>120GB model = 234,441,648 |
| 104     | Reserved for Streaming Command Set  | 0000 <sub>H</sub>   |
| 105     | Maximum number of 512-byte blocks of LBA Range Entries<br>(see 4.18.3.2) per DATA SET MANAGEMENT command  | 0001 <sub>H</sub>   |
| 106     | Physical sector size / logical sector size  | 6003 <sub>H</sub>   |
| 107     | Inter-seek delay for ISO 7779 standard acoustic testing   | 0000 <sub>H</sub>   |
| 108–111 | World wide name   | XXXX <sub>H</sub>   |
| 112–115 | Reserved  | 0000 <sub>H</sub>   |
| 116     | Reserved for TLC  | 0000 <sub>H</sub>   |
| 117–118 | Logical sector size (DWord)   | 0000 <sub>H</sub>   |
| 119     | Commands and feature sets supported   | 4014 <sub>H</sub>   |
| 120     | Commands and feature sets supported or enabled  | 4014 <sub>H</sub>   |
| 121–126 | Reserved for expanded supported and enabled settings  | 0000 <sub>H</sub>   |

| Word    | DESCRIPTION   | VALUE             |
|---------|---|-------------------|
| 127     | Obsolete  | 0000 <sub>H</sub> |
| 128     | Security status   | 0001 <sub>H</sub> |
| 129–159 | Vendor specific   | xxxx <sub>H</sub> |
| 160–167 | Reserved for the CompactFlash Association   | 0000 <sub>H</sub> |
| 168     | Device Nominal Form Factor  | 0003 <sub>H</sub> |
| 169     | DATA SET MANAGEMENT features supported  | 0001 <sub>H</sub> |
| 170–173 | Additional Product Identifier (ATA String)  | 0000 <sub>H</sub> |
| 174–175 | Reserved  | 0000 <sub>H</sub> |
| 176–197 | Reserved  | 0000 <sub>H</sub> |
| 198–199 | Reserved  | 8000 <sub>H</sub> |
| 200–205 | Reserved  | 0000 <sub>H</sub> |
| 206     | SCT Command Transport   | 0000 <sub>H</sub> |
| 207–208 | Reserved for CE-ATA   | 0000 <sub>H</sub> |
| 209     | Alignment of logical blocks within a physical block                                   | 4000 <sub>H</sub> |
| 210–211 | Write-Read-Verify Sector Count Mode 3   | 0000 <sub>H</sub> |
| 212–213 | Write-Read-Verify Sector Count Mode 2 (DWord)   | 0000 <sub>H</sub> |
| 214     | NV Cache Capability   | 0000 <sub>H</sub> |
| 215-216 | NV Cache Size in Logical Blocks (DWord)   | 0000 <sub>H</sub> |
| 217     | Nominal media rotation rate   | 0001 <sub>H</sub> |
| 218     | Reserved  | 0000 <sub>H</sub> |
| 219     | NV Cache Options  | 0000 <sub>H</sub> |
| 220     | Write-Read-Verify feature set   | 0000 <sub>H</sub> |
| 221     | Reserved  | 0000 <sub>H</sub> |
| 222     | Transport major version number  | 1020 <sub>H</sub> |
| 223     | Transport minor version number  | 0000 <sub>H</sub> |
| 224-233 | Reserved  | 0000 <sub>H</sub> |
| 234     | Minimum number of 512-byte data blocks per<br>DOWNLOAD MICROCODE command for mode 03h | 0001 <sub>H</sub> |
| 235     | Maximum number of 512-byte data blocks per<br>DOWNLOAD MICROCODE command for mode 03h | 02A0 <sub>H</sub> |
| 236-254 | Reserved  | 0000 <sub>H</sub> |
| 255     | Integrity word (XXA5 <sub>H</sub> )   | xxA5 <sub>H</sub> |

Note. See the bit descriptions below for words 49, 69, 76, 78, 82-87 and 119-120 of the Identify Drive data.

| Descrip | Description (if bit is set to 1) |  |  |
|---------|----------------------------------|--|--|
| Bit     | Word 49                          |  |  |
| 8       | DMA Supported                    |  |  |
| 9       | Shall be set to 1                |  |  |
| 10      | IORDY May be disabled            |  |  |
| 11      | IORDY supported                  |  |  |
| 13      | Standby Timer Values supported   |  |  |
| Bit     | Word 50                          |  |  |
| 14      | Shall be set to 1                |  |  |

| Bit   | Word 69   |  |
|-------|---|--|
| 5     | Read zero after Trim is supported   |  |
| 6     | Optional ATA 28-bit commands supported  |  |
| 8     | Download Microcode DMA supported  |  |
| 9     | Set Max Password DMA and Set Max Unlock DMA supported                               |  |
| 10    | Write Buffer DMA Supported  |  |
| 11    | Read Buffer DMA Supported   |  |
| 12    | DEVICE CONFIGURATION IDENTIFY DMA and<br>DEVICE CONFIGURATION SET DMA are supported |  |
| 13    | Long Physical Sector Alignment Error Reporting Control is supported                 |  |
| 14    | Deterministic read after Trim is supported  |  |
| Bit   | Word 76   |  |
| 0     | Shall be cleared to zero  |  |
| 1     | Supports SATA Gen1 Signaling Speed (1.5Gb/s)  |  |
| 2     | Supports SATA Gen2 Signaling Speed (3.0Gb/s)  |  |
| 3     | Supports SATA Gen3 Signaling Speed (6.0Gb/s)  |  |
| 4-7   | Reserved for Serial ATA   |  |
| 8     | Supports the NCQ feature set  |  |
| 9     | Supports receipt of host initiated power management requests                        |  |
| 10    | Supports Phy Event Counters   |  |
| 11    | Supports Unload while NCQ commands are outstanding                                  |  |
| 12    | Supports NCQ priority information   |  |
| 13-15 | Reserved for Serial ATA   |  |
| Bit   | Word 78   |  |
| 0     | Shall be cleared to zero  |  |
| 1     | Device supports non-zero buffer offsets   |  |
| 2     | Device supports DMA Setup auto-activation   |  |
| 3     | Device supports initiating power management   |  |
| 4     | Device supports in-order data delivery  |  |
| 5     | Reserved for Serial ATA   |  |
| 6     | Device supports Software Settings Preservation                                      |  |
| 7-15  | Reserved for Serial ATA   |  |
| Bit   | Word 82   |  |
| 0     | The SMART feature set is supported  |  |
| 1     | The Security feature set is supported   |  |
| 2     | Obsolete  |  |
| 3     | Mandatory Power Management feature set is supported                                 |  |
| 4     | PACKET feature set is supported   |  |
| 5     | Volatile write cache is supported   |  |
| 6     | Read look-ahead is supported  |  |
| 7     | Release interrupt is supported  |  |
| 8     | SERVICE interrupt is supported  |  |
| 9     | DEVICE RESET command is supported   |  |
| 10    | HPA feature set is supported  |  |
| 11    |   |  |
| 12    | WRITE BUFFER command is supported   |  |
|       |   |  |
| 13    | READ BUFFER command is supported  |  |
|       |   |  |

| Bit   | Word 83   |  |
|-------|---|--|
| 0     | DOWNLOAD MICROCODE command is supported                             |  |
| 1     | Obsolete  |  |
| 2     | CFA feature set is supported  |  |
| 3     | APM feature set is supported  |  |
| 4     | Obsolete  |  |
| 5     | PUIS feature set is supported                                       |  |
| 6     | SET FEATURES subcommand is required to spin-up after power-up       |  |
| 7     | Reserved  |  |
| 8     | SET MAX security extension is supported                             |  |
| 9     | AAM feature set is supported  |  |
| 10    | 48-bit Address feature set is supported                             |  |
| 11    | DCO feature set is supported  |  |
| 12    | Mandatory FLUSH CACHE command is supported                          |  |
| 13    | FLUSH CACHE EXT command is supported                                |  |
| 14    | Shall be set to one   |  |
| 15    | Shall be cleared to zero  |  |
| Bit   | Word 84   |  |
| 0     | SMART error logging is supported                                    |  |
| 1     | SMART self-test is supported  |  |
| 2     | Media serial number is supported                                    |  |
| 3     | Media Card Pass Through Command feature set is supported            |  |
| 4     | Streaming feature set is supported                                  |  |
| 5     | GPL feature set is supported  |  |
| 6     | WRITE DMA FUA EXT and WRITE MULTIPLE FUA EXT commands are supported |  |
| 7     | Obsolete  |  |
| 8     | 64-bit World wide name is supported                                 |  |
| 9-10  | Obsolete  |  |
| 11-12 | Reserved for TLC  |  |
| 13    | IDLE IMMEDIATE command with UNLOAD feature is supported             |  |
| 14    | Shall be set to one   |  |
| 15    | Shall be cleared to zero  |  |
| Bit   | Word 85   |  |
| 9     | DEVICE RESET command is not supported                               |  |
| 10    | HPA feature set is supported  |  |
| 11    | Obsolete  |  |
| 12    | WRITE BUFFER command is supported                                   |  |
| 13    | READ BUFFER command is supported                                    |  |
| 14    | NOP command is supported  |  |
| 15    | Obsolete  |  |
| Bit   | Word 86   |  |
| 0     | DOWNLOAD MICROCODE command is supported                             |  |
| 1     | Obsolete  |  |
| 2     | CFA feature set is supported  |  |
| 6     | SET FEATURES subcommand is required to spin-up after power-up       |  |
| 10    | The 48-bit Address features set is supported                        |  |
| 11    | The DCO feature set is supported                                    |  |
| 12    | FLUSH CACHE command supported                                       |  |
| 13    | FLUSH CACHE EXT command supported                                   |  |
| 15    | Words 119 120 are valid   |  |
|       |   |  |

| Bit  | Word 87   |  |
|------|---|--|
| 0    | SMART error logging is supported                                    |  |
| 1    | SMART self-test supported   |  |
| 3    | The Media Card Pass Through Command feature set is supported        |  |
| 5    | The GPL feature set is supported                                    |  |
| 6    | WRITE DMA FUA EXT and WRITE MULTIPLE FUA EXT commands are supported |  |
| 8    | The 64-bit World wide name is supported                             |  |
| 13   | The IDLE IMMEDIATE command with UNLOAD FEATURE is supported         |  |
| 14   | Shall be set to one   |  |
| 15   | Shall be cleared to zero  |  |
| Bit  | Word 119  |  |
| 0    | Reserved  |  |
| 1    | Write-Read-Verify feature set is supported                          |  |
| 2    | WRITE UNCORRECTABLE EXT command is supported                        |  |
| 3    | READ LOG DMA EXT and WRITE LOG DMA EXT commands are supported       |  |
| 4    | DOWNLOAD MICROCODE command with mode 3 is supported                 |  |
| 5    | Free-fall Control feature set is supported                          |  |
| 6    | Extended Status Reporting feature set is supported                  |  |
| 7    | Extended Power Conditions feature set is supported                  |  |
| 8-13 | Reserved  |  |
| 14   | Shall be set to one   |  |
| 15   | Shall be cleared to zero  |  |
| Bit  | Word 120  |  |
| 2    | WRITE UNCORRECTABLE EXT command is supported                        |  |
| 3    | READ LOG DMA EXT and WRITE LOG DMA EXT commands are supported       |  |
| 4    | DOWNLOAD MICROCODE command with mode 3 is supported                 |  |
| 14   | Shall be set to one   |  |
| 15   | Shall be cleared to zero  |  |

#### 4.3.2 Set Features command

This command controls the implementation of various features that the drive supports. When the drive receives this command, it sets BSY, checks the contents of the Features regis ter, clears BSY and generates an interrupt. If the value in the register does not represent a feature that the drive supports, the command is aborted. Power-on default has the read look-ahead and write caching features enabled. The acceptable values for the Features register are defined as follows:

#### Table 9 Set Features command values

- 02<sub>H</sub> Enable write cache *(default)*.
- 03<sub>H</sub> Set transfer mode (based on value in Sector Count register).
  - Sector Count register values:
    - $\rm 00_{H}~Set~PIO$  mode to default (PIO mode 2).
    - 01<sub>H</sub> Set PIO mode to default and disable IORDY (PIO mode 2).
    - 08<sub>H</sub> PIO mode 0
    - 09<sub>H</sub> PIO mode 1
    - 0A<sub>H</sub> PIO mode 2
    - 0B<sub>H</sub> PIO mode 3
    - 0C<sub>H</sub> PIO mode 4 (default)
    - $20_H$  Multiword DMA mode 0
    - 21<sub>H</sub> Multiword DMA mode 1
    - 22<sub>H</sub> Multiword DMA mode 2
    - 40<sub>H</sub> Ultra DMA mode 0
    - 41<sub>H</sub> Ultra DMA mode 1
    - 42<sub>H</sub> Ultra DMA mode 2
    - 43<sub>H</sub> Ultra DMA mode 3
    - 44<sub>H</sub> Ultra DMA mode 4
    - 45<sub>H</sub> Ultra DMA mode 5
    - 46<sub>H</sub> Ultra DMA mode 6

#### 10<sub>H</sub> Enable use of SATA features

- 02<sub>H</sub> DMA Setup FIS Auto-Activate optimization
- 03<sub>H</sub> Device-initiated interface power state transitions
- 06<sub>H</sub> Software Settings Preservation
- 55<sub>H</sub> Disable read look-ahead (read cache) feature
- 66<sub>H</sub> Disable reverting to power-on defaults
- 82<sub>H</sub> Disable write cache
- 90<sub>H</sub> Disable use of SATA features
  - 02<sub>H</sub> DMA Setup FIS Auto-Activate optimization
  - 03<sub>H</sub> Device-initiated interface power state transitions
  - 06<sub>H</sub> Software Settings Preservation
- AA<sub>H</sub> Enable read look-ahead (read cache) feature (default).
- CC<sub>H</sub> Enable reverting to power-on defaults
- **Note.** At power-on, or after a hardware or software reset, the default values of the features are as indicated above.

#### 4.3.3 S.M.A.R.T. commands

S.M.A.R.T. provides near-term failure prediction for drives. When S.M.A.R.T. is enabled, the drive monitors predetermined drive attributes that are susceptible to degradation over time. If self-monitoring determines that a failure is likely, S.M.A.R.T. makes a status report available to the host. Not all failures are predictable. S.M.A.R.T. predictability is limited to the attibutes the drive can monitor. For more information on S.M.A.R.T. commands and implementation, see the *Draft ATA-8 Standard*.

SeaTools diagnostic software activates a built-in drive self-test (DST S.M.A.R.T. command for D4<sub>H</sub>) that eliminates unnecessary drive returns. The diagnostic software ships with all new drives and is also available at: <u>http://www.seagate.com/support/downloads/seatools/</u>.

This drive is shipped with S.M.A.R.T. features disabled. You must have a recent BIOS or software package that supports S.M.A.R.T. to enable this feature. The table below shows the S.M.A.R.T. command codes that the drive uses.

| CODE IN FEATURES<br>REGISTER | S.M.A.R.T. COMMAND                               |
|------------------------------|--|
| D0 <sub>H</sub>              | S.M.A.R.T. Read Data                             |
| D4 <sub>H</sub>              | S.M.A.R.T. Execute Off-line Immediate (runs DST) |
| D5 <sub>H</sub>              | S.M.A.R.T. Read Log Sector                       |
| D6 <sub>H</sub>              | S.M.A.R.T. Write Log Sector                      |
| D8 <sub>H</sub>              | S.M.A.R.T. Enable Operations                     |
| D9 <sub>H</sub>              | S.M.A.R.T. Disable Operations                    |
| DA <sub>H</sub>              | S.M.A.R.T. Return Status                         |

#### Table 10 S.M.A.R.T. commands

**Note.** If an appropriate code is not written to the Features Register, the command is aborted and 0x04 (abort) is written to the Error register.

#### 4.3.4 SSD Percentage Endurance Remaining Indicator

An application can interrogate the drive through the host to determine an estimate of the percentage of device life that is remaining. Seagate SeaTools diagnostic software has the capability to report the indicator value.

### Α

ACA 14 acceleration 12 Agency certification 14 air flow illustrated 19 altitude 11 ambient temperature 7 Annualized Failure Rate (AFR) 13 ATA commands 22 Australia/New Zealand Standard AS/NZ CISPR22 14 Australian Communication Authority (ACA) 14 Australian C-Tick 14

### С

cables and connectors 16 capacity 4 CE mark 14 certification 14 Check Power Mode 22 China RoHS directive 15 Class B computing device 14 compatibility 14 Conducted RF immunity 12 Configuring the drive 16 connectors 16 Corrosive environment 15 CSA60950-1 14 cycles 13 Cylinders 4

### D

Data Set Management with Trim Support 22 data-transfer rates 2 DC power 7 Default logical geometry 4 dimensions 17 Download Microcode 22 drive mounting 17

### Ε

Electrical fast transient 12 Electromagnetic compatibility 14 Electromagnetic Compatibility Directive (2004/108/EC) 14 Electromagnetic immunity 12 Electrostatic discharge 12 electrostatic discharge (ESD) 16 EN 55022, Class B 14 EN 55024 14 EN60950 14 Environmental specifications 11 ESD 16 EU 14 EU RoHS directive 15 European Union (EU) requirements 14

### F

FCC verification 14 features 2 Federal Communications Commission 14 Flush Cache 22 Flush Cache Extended 22 Formatted capacity 4

### G

geometry 4 guaranteed LBAs 4

### Η

Handling precautions 16 heads 4 height 6 humidity 11

### I

Identify Device 22 Identify Device command 24 Idle 22 Idle Immediate 22 Idle mode 7 Idle mode power 7 Information Technology Equipment (ITE) 14 Initialize Device Parameters 22 interface 5, 20 Interface technology 5 ITE 14

### Κ

KCC 14 Korean Communications Commission 14 Korean RRL 14

### L

LBA mode 4 length 6 Limited Warranty With Media Usage 13 logical geometry 4

### Μ

maintenance 13 master/slave 2 maximum temperature 11 mounting 17 mounting configuration 17 mounting configuration dimensions 17, 18 mounting screws 11 mounting the drive 16

SEAGATE 600 SSD PRODUCT MANUAL, REV. B

## **I**NDEX

### Ν

Nonoperating shock 11 Nonoperating vibration 12 NOP 22

### 0

Operating shock 11 Operating vibration 12

### Ρ

Peak operating mode 7 Performance 5 Physical characteristics 6 point-to-point 2, 16 Power consumption 7 Power specifications 7 precautions 16 printed circuit board 16

### Q

quick reference 3

### R

Radiated RF immunity 12 Radio and television interference 14 radio frequency (RF) 12 Read Buffer 22 Read DMA 22 Read DMA Extended 22 Read FPDMA queued 22 Read Log Ext 22 Read Multiple 22 Read Multiple Extended 22 Read Native Max Address 22 Read Native Max Address Extended 22 Read Sectors 22 Read Sectors Extended 22 Read Verify Sectors 22 Read Verify Sectors Extended 22 Read/write heads 4 Recording technology 5 relative humidity 11 Reliability 13 RF 12 RoHS 15

### S

S.M.A.R.T. Disable Operations 23 S.M.A.R.T. Enable Operations 23 S.M.A.R.T. Execute Offline 23 S.M.A.R.T. implementation 22 S.M.A.R.T. Read Data 23 S.M.A.R.T. Read Log Sector 23 S.M.A.R.T. Return Status 23 S.M.A.R.T. Write Log sector 23 Safety certification 14 Sanitize Block Erase 22 Sanitize Freeze Lock Ext 22 Sanitize Status Ext 22 SATA 20 screws 11 Seagate Technology Support Services 1 Sectors per track 4 Security Disable Password 22 Security Erase Prepare 22 Security Erase Unit 22 Security Freeze 22 Security Set Password 22 Security Unlock 22 Serial ATA (SATA) interface 20 serial ATA ports 2 Set Features 22 Set Max Address 22 Set Max Address Extended 22 Set Multiple Mode 23 Shock 11 Signal and Power SATA Plug and Nominal Mate Sequence 20, 21 Sleep 23 Specification summary table 3 SSD Percentage Endurance Remaining Indicator 31 Standby 23 Standby Immediate 23 Standby mode 7 Startup power 7 static-discharge 16 Surge immunity 12

### Т

temperature 11 temperature gradient 11 Time to Ready 6

### U

UL60950-1 14

### V

Vibration 11 Voltage dips, interrupts 12

### W

weight 6 wet bulb temperature 11 width 6 Write Buffer 23 Write DMA 23 Write DMA Extended 23 Write DMA FUA Extended 23 Write FPDMA queued 23 Write Log Extended 23 Write Multiple 23 Write Multiple Extended 23 Write Multiple FUA Extended 23 Write Sectors 23 Write Sectors Extended 23 write uncorrectable 23



#### Seagate Technology LLC

AMERICAS Seagate Technology LLC 10200 South De Anza Boulevard, Cupertino, California 95014, United States, 408-658-1000 ASIA/PACIFIC Seagate Singapore International Headquarters Pte. Ltd. 7000 Ang Mo Kio Avenue 5, Singapore 569877, 65-6485-3888 EUROPE, MIDDLE EAST AND AFRICA Seagate Technology SAS 16-18 rue du Dôme, 92100 Boulogne-Billancourt, France, 33 1-4186 10 00

Publication Number: 100722309, Rev. B May 2013