# Acti 9 Smartlink Ethernet Communication System User Manual

04/2014



The information provided in this documentation contains general descriptions and/or technical characteristics of the performance of the products contained herein. This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications. It is the duty of any such user or integrator to perform the appropriate and complete risk analysis, evaluation and testing of the products with respect to the relevant specific application or use thereof. Neither Schneider Electric nor any of its affiliates or subsidiaries shall be responsible or liable for misuse of the information contained herein. If you have any suggestions for improvements or amendments or have found errors in this publication, please notify us.

No part of this document may be reproduced in any form or by any means, electronic or mechanical, including photocopying, without express written permission of Schneider Electric.

All pertinent state, regional, and local safety regulations must be observed when installing and using this product. For reasons of safety and to help ensure compliance with documented system data, only the manufacturer should perform repairs to components.

When devices are used for applications with technical safety requirements, the relevant instructions must be followed.

Failure to use Schneider Electric software or approved software with our hardware products may result in injury, harm, or improper operating results.

Failure to observe this information can result in injury or equipment damage.

© 2014 Schneider Electric. All rights reserved.

# **Table of Contents**



	Safety Information
	About the Book
Chapter 1	Acti 9 Communication System
-	Overview
Chapter 2	Architecture of Acti 9 Communication System
•	Acti 9 Smartlink Ethernet
	Acti 9 Communication System Pre-assembled Cables
	Acti 9 Devices with Ti24 Interface
	Acti 9 Devices without Ti24 Interface
	Devices out of the Acti 9 Range
	Devices with Analog Output
Chapter 3	Technical Characteristics
Chapter C	Technical Characteristics of the Acti 9 Smartlink Ethernet
Chapter 4	Sizing the 24 Vdc Power Supply
onaptor 4	Definition of the 24 Vdc Power Supply
	Protection Against a 240 Vac Fault on the Acti 9 Smartlink Ethernet Channels
	Electromagnetic Compatibility (EMC) Recommendations
Chapter 5	Installation
Chapter 5	Mounting
	Connection
Chapter 6	Connection of Input/Output Channels
Chapter 6	Acti 9 Devices with Ti24 Interface
	Meters
	Volt-Free Low Level Indication Contact
	Volt-Free Standard Indication Contact
	Contactor and Relay (Not in the Acti 9 Range)
	Indirect Output Connection
	Generating Summary Data Using iOF+SD24 or OF+SD24
	Analog Input Characteristics and Connection (Recommendation)
01	Recommendation for Cabling
Chapter 7	Setting Up Ethernet Communication
	Ethernet Principle
	Set Up and Ethernet Addressing Mode
	Web Page Setting Menu
	Acti 9 Smartlink Ethernet Device Function
	Modbus TCP/IP Functions
	Modbus TCP/IP Exception Codes
	Description of Ethernet LEDs
	Other Protocol or Services
Chapter 8	Setting Up Modbus Communication (Gateway Function)       6         Modbus Master Principle       6
	Possible Architecture
	Setup
	Gateway Features
	Web Page Setting Menu
	Description of Modbus LEDs
Chapter 9	Test
2apto. 0	Acti 9 Smart Test Software

Chapter 10	Web Page
	Overview
	Global Content Description
	Quick View Page
	Monitoring and Control Page
	Maintenance Page
	Diagnostics Page
	Settings Page
Chapter 11	Tables of Modbus Registers
11.1	General Description of Modbus Tables
	Overview
	Modbus Table Format and Data Types
	Global Modbus Address Table
11.2	Summary and Detailed Modbus Tables
	System
	Summary of Digital Channels 1 to 7
	Details of Digital Channels 1 to 7
	Analog Input
11.3	Modbus Tables for Connected Products
	iOF+SD24 Indication Auxiliary
	OF+SD24 Indication Auxiliary
	iEM2000T, iEM3110, iEM3155, iEM3210, iEM3255 Meters, or Meter with Pulse Output
	(Standard CEI 62053-31)
	iACT24 Auxiliary for iCT Contactor
	iATL24 Auxiliary for iTL Impulse Relay
	Contactor and Relay (Not in the Acti 9 Range)
	Acti 9 RCA iC60 Remote Control with Ti24 Interface
	Acti 9 Reflex iC60 Integrated Control Circuit Breaker With Ti24 Interface
Appendices	
Appendix A	
	Function 8: Modbus Diagnostics
	Function 43-14: Read Acti 9 Smartlink ID
	Function 43–15: Read Date and Time
	Function 43-16: Write Date and Time
	Function 100–4: Read n Non-Adjacent Words
Appendix B	Reset of Smartlink Ethernet 1
	Description
Appendix C	Troubleshooting 1
	Common Problems

# **Safety Information**



# **Important Information**

#### **NOTICE**

Read these instructions carefully, and look at the equipment to become familiar with the device before trying to install, operate, or maintain it. The following special messages may appear throughout this documentation or on the equipment to warn of potential hazards or to call attention to information that clarifies or simplifies a procedure.



The addition of this symbol to a Danger safety label indicates that an electrical hazard exists, which will result in personal injury if the instructions are not followed.



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death

# A DANGER

**DANGER** indicates an imminently hazardous situation which, if not avoided, **will result in** death or serious injury.

# WARNING

**WARNING** indicates a potentially hazardous situation which, if not avoided, **can result in** death or serious injury.

# **A** CAUTION

**CAUTION** indicates a potentially hazardous situation which, if not avoided, **can result in** minor or moderate injury.

# NOTICE

**NOTICE** is used to address practices not related to physical injury.

#### **PLEASE NOTE**

Electrical equipment should be installed, operated, serviced, and maintained only by qualified personnel. No responsibility is assumed by Schneider Electric for any consequences arising out of the use of this material

A qualified person is one who has skills and knowledge related to the construction and operation of electrical equipment and its installation, and has received safety training to recognize and avoid the hazards involved.

# **About the Book**



#### At a Glance

#### **Document Scope**

The purpose of this manual is to provide users, installers, and maintenance personnel with the technical information necessary to install and use the Acti 9 Smartlink Ethernet communication system.

#### **Validity Note**

The Acti 9 Smartlink Ethernet communication system can be easily integrated into any building management architecture.

It combines command and control, metering and protection functions designed for energy efficiency solutions in any type of environment. Based on the Modbus protocol, the Acti 9 Smartlink Ethernet communication system allows switchboard data to be exchanged in real time with a supervision system or a PLC.

This system's pre-wired connectors can save time and prevent wiring errors during installation.

#### **Related Documents**

Title of Documentation	Reference Number
Instruction Sheet for the iACT24 Auxiliary on the iCT Contactor (English, Dutch, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1B33421
Instruction Sheet for the iATL24 Auxiliary on the iTL Remote Control Switch (English, Dutch, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1B33422
Instruction Sheet for the Acti 9 Smartlink Ethernet (English, Dutch, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	EAV14819
Instruction Sheet for the RCA iC60 Remote Control (English, Dutch, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1A4079001
Instruction Sheet for the Reflex iC60 Integrated Control Circuit Breaker (English, Dutch, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1B8674701
Instruction Sheet for the iEM2000T Meter (English, Dutch, French, Finnish, German, Hungarian, Italian, Norwegian, Polish, Portuguese, Spanish, Swedish, Chinese, Russian)	S1A89364
Instruction Sheet for the iEM3100, iEM3110, iEM3115 Meters (English, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1B46581
Instruction Sheet for the iEM3150, iEM3155 Meters (English, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1B46583
Instruction Sheet for the iEM3200, iEM3210, iEM3215 Meters (English, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1B46598
Instruction Sheet for the iEM3250, iEM3255 Meters (English, French, German, Italian, Portuguese, Spanish, Chinese, Russian)	S1B46602
Reference Manual for the RCA iC60 Remote Control for iC60 Circuit Breakers (English)	A9MA01EN

Title of Documentation	Reference Number
Reference Manual for the Reflex iC60 Integrated Control Circuit Breaker (English)	A9MA03EN
User Manual for the PowerLogic EGX300 Ethernet Gateway (English, French, German, Spanish)	63230-319-216
Technical Advice on the Acti 9 Smartlink Device (English)	CA908033EN
User Manual - Acti 9 Communication System Diagnostics (English)	DOCA0042EN
User Manual - Acti 9 Smart Test Software (English)	DOCA0029EN

You can download these technical publications and other technical information from our website at www.schneider-electric.com.

# **Chapter 1**

# **Acti 9 Communication System**

#### Overview

#### Introduction

The Acti 9 communication system is used to connect final distribution boards to any supervision system.

Modular equipment in the Acti 9 communication system is used to monitor, measure, and control electrical distribution boards via a Modbus serial line or Modbus TCP/IP communication network.

The Acti 9 communication system concentrates the data from electrical distribution boards in real time, thus contributing to achieve energy efficiency targets.

The Acti 9 communication system collects data from any meter (including kilowatt-hour, water, air, gas or steam meters).

This system consists of:

- · Acti 9 Smartlink Ethernet and the test kit
- iOF+SD24 and OF+SD24 indication auxiliaries
- iACT24 and iATL24 auxiliaries for contactors and impulse relays in the Acti 9 range
- The Acti 9 RCA iC60 remote control module with Ti24 interface
- The Reflex iC60 integrated control circuit breaker with Ti24 interface
- iEM2000T, iEM3110, iEM3155, iEM3210, and iEM3255 meters
- · Pre-wired connectors

This system offers the following advantages and services:

Calculation functions

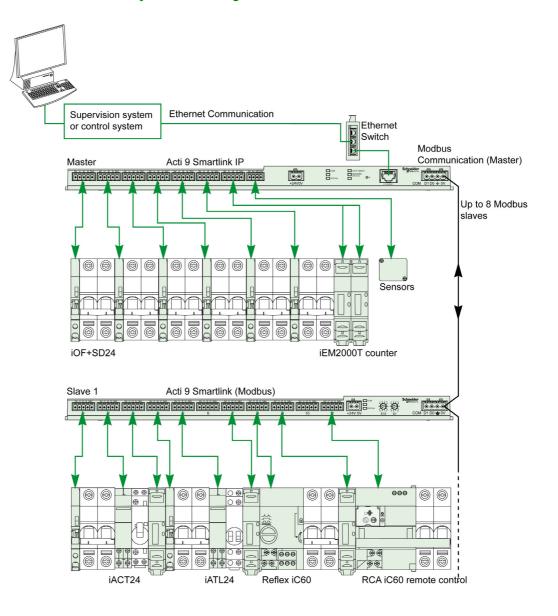
The Acti 9 communication system is an open system:

- Acti 9 Smartlink Ethernet can be used as a standard I/O distributed module.
- Acti 9 Smartlink Ethernet is equipped with seven digital channels. Each channel is represented by a Ti24 interface consisting of:
  - Two power supply terminals: 0 V and 24 Vdc
  - Two 24 Vdc logic inputs (I1 and I2)
  - One 24 Vdc logic output (Q)
- Each Ti24 interface is compatible with Miniconnect Phoenix standard connectors (at intervals of 3.81 mm) or equivalent.
- Acti 9 Smartlink Ethernet is equipped with one analog channel having:
  - Two power supply terminals: 0 V and 24 Vdc
  - Two analog inputs (4...20 mA or 0...10 V)
- Acti 9 Smartlink Ethernet is compatible with any type of counter (pulse output) compliant with standard IEC 62053-21 (minimum pulse width of 30 ms):
  - The pulse weight must be configured (written in a Modbus register).
  - Acti 9 Smartlink Ethernet calculates consumption and flow.
- Acti 9 Smartlink Ethernet is compatible with any type of device equipped with low level inputs and outputs (24 Vdc).

The Acti 9 communication system is simple and safe to use:

- The Acti 9 communication system pre-wired connectors reduce complexity and wiring time by allowing connection on an Acti 9 Smartlink Ethernet module of all the Acti 9 communication system components and 24 Vdc compatible products.
- All Acti 9 communication system functions can be created by sending messages (Modbus protocol) to Acti 9 Smartlink Ethernet devices (Modbus slave or Ethernet server) that act on devices via Ti24 interfaces.

# **Acti 9 Smartlink Ethernet Communication System Block Diagram**



Acti 9 Smartlink Ethernet can manage a gateway function (Modbus TCP/IP to Modbus RS485). It can support up to eight Modbus RS485 slave devices (address from 1 to 247).

Acti 9 Smartlink Ethernet also manages web page in order to configure settings or to monitor and control the Acti 9 devices.

# **Chapter 2**

# **Architecture of Acti 9 Communication System**

# What Is in This Chapter?

This chapter contains the following topics:

Торіс	Page
Acti 9 Smartlink Ethernet	
Acti 9 Communication System Pre-assembled Cables	
Acti 9 Devices with Ti24 Interface	14
Acti 9 Devices without Ti24 Interface	
Devices out of the Acti 9 Range	
Devices with Analog Output	

#### **Acti 9 Smartlink Ethernet**

#### Introduction

The Acti 9 Smartlink Ethernet device has seven digital channels (24 Vdc) and one analog channel (4...20 mA or 0...10 Vdc) and can be connected to the devices in the Acti 9 range equipped with a Ti24 interface. The data can be transmitted from the Acti 9 Smartlink Ethernet device to a PLC or a supervision system via a Modbus TCP/IP protocol.

The Acti 9 Smartlink Ethernet device channels can also be used to transmit standardized I/O. The Acti 9 Smartlink Ethernet device can also therefore communicate with devices (not in the Acti 9 range) with or without a Ti24 link.

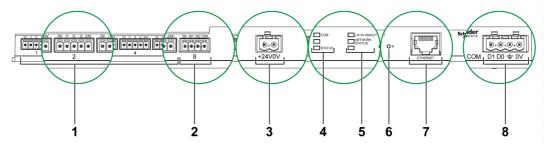
Devices which can be connected to the Acti 9 Smartlink Ethernet device include:

- Acti 9 products: control switch for iACT24 contactors and iATL24 impulse relays, iC60 iOF+SD24 indication auxiliary, C60 OF+SD24 indication auxiliary, RCA iC60 remote control with Ti24 interface, Reflex iC60 integrated control circuit breaker with Ti24 interface
- Meters: iEM2000T or other meters (Schneider Electric or other manufacturers) in compliance with IEC 62053-21 (minimum pulse 30 ms).
- Any product (not in the Acti 9 range) that has command and control information: 2 discrete 24 V outputs and 1 discrete 24 V input.
- Any product using analog output (4...20 mA or 0...10 V).

The Acti 9 Smartlink Ethernet device is an intermediary between the supervisor and various electrical appliances. It can therefore be used to retrieve and process data received from devices and also control them. The functions available depend on the type of connected devices.

The Acti 9 Smartlink Ethernet functions are described in Acti 9 Smartlink Ethernet functions (see page 59).

#### **Description**



- 7 digital input/output channels
- 2 1 analog channel with two inputs
- 3 1 x 24 V power connector
- 4 Status LEDs
- 5 Ethernet LEDs
- 6 Reset button
- 7 Ethernet communication port
- 8 1 Modbus connector: 4-way

# **Acti 9 Communication System Pre-assembled Cables**

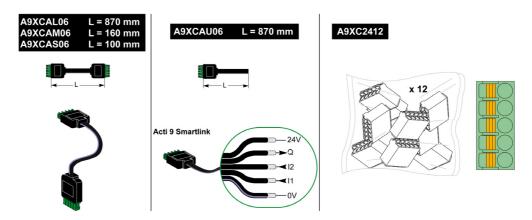
#### **Description**

Acti 9 communication pre-assembled cables are a quick way to connect all the Acti 9 communication system components and compatible products (24 Vdc) to the channels of the Acti 9 Smartlink Ethernet module.

The female connectors that can be connected to the Acti 9 Smartlink Ethernet I/O channels are:

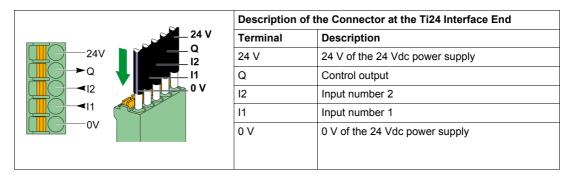
Product Referance	Description	Length (mm)
A9XCAS06	Set of 6 pre-assembled cables with 2 Ti24 connectors	100
A9XCAM06	Set of 6 pre-assembled cables with 2 Ti24 connectors	160
A9XCAL06	Set of 6 pre-assembled cables with 2 Ti24 connectors	870
A9XCAU06	Set of 6 pre-assembled cables with 1 Ti24 connector	870
A9XC2412	Set of 12 connectors with 5-pin spring	-

Each Ti24 interface (I/O channel) is compatible with Miniconnect Phoenix standard connectors (at intervals of 3.81 mm) or equivalent.



**NOTE:** The connectors in each pre-assembled cable have a flat surface where a self-adhesive label can be placed to identify the channel number used.

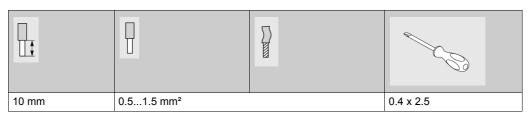
Self-adhesive labels are not supplied by Schneider Electric.



#### NOTE:

- Do not connect two wires in each of the Ti24 connector terminals (A9XC2412).
- Do not connect a wire with cable end in each of the Ti24 connector terminals.

The table below gives the characteristics of cables that can be used with the A9XC2412 connector:



# **Acti 9 Devices with Ti24 Interface**

# Description

Devices that can be connected to the Acti 9 Smartlink Ethernet are listed in the table below:

Device	Product Reference	Description	
iACT24 auxiliary for iCT contactor	A9C15924	The iACT24 auxiliary:  Can be used to control a contactor (iCT) via its Y1, Y2, and Y3 inputs. The Y3 (24 Vdc) input can be controlled by one of the Acti 9 Smartlink Ethernet device channels.  Is used to find out the contactor status (O/C status).	
iATL24 auxiliary for iTL contactor	A9C15424	The iATL24 auxiliary:  Can be used to control an (iTL) impulse relay via its Y1, Y2, and Y3 inputs. The Y3 (24 Vdc) input can be controlled by one of the Acti 9 Smartlink Ethernet device channels.  Is used to find out the impulse relay status (O/C status).	
iOF+SD24 indication auxiliary for iC60, iC65, and iDPN circuit breakers	A9A26897	The iOF+SD24 indication auxiliary is used to find out the status of a iC60, iC65 (OF and $\overline{SD}$ states) and iDPN circuit breaker (sold in China).	
OF+SD24 indication auxiliary for C60, C120, C60H-DC, and iDPN circuit breakers	A9N26899	The OF+SD24 indication auxiliary is used to find out the status of a C60, C120, C60H-DC (OF and $\overline{SD}$ ) and iDPN circuit breaker (sold in all the countries except China).	
Acti 9 RCA iC60 remote control with Ti24 interface	A9C7012•	The Acti 9 RCA iC60 remote control: Should have a Ti24 interface (with product references A9C70122 and A9C70124). Can be used to control an iC60 circuit breaker via input Y3 of its Ti24 interface. Input Y3 (24 Vdc) can be controlled by one of the device channels Acti 9 Smartlink Ethernet.  Can be used to find out the OF and SD status of the circuit breaker associated with the RCA iC60 remote control.	
Acti 9 Reflex iC60 integrated control circuit breaker with Ti24 interface	A9C6••••	The Acti 9 Reflex iC60 integrated control circuit breaker: Should have a Ti24 interface (with product references A9C6****). Can allow the device to be controlled via input Y3 of its Ti24 interface. The Y3 (24 Vdc) input can be controlled by one of the Acti 9 Smartlink Ethernet channels. Can be used to communicate its O/C and auto/OFF status.	

**NOTE:** All the devices in the above table can be connected to channel N ( $1 \le N \le 7$ ) of an Acti 9 Smartlink Ethernet module with A9XCAS06 pre-wired connector (or A9XCAM06 or A9XCAL06).

# **Acti 9 Devices without Ti24 Interface**

# **Description**

Devices that can be connected to the Acti 9 Smartlink Ethernet are listed in the table below:

Designation	Product Reference	Description
iEM2000T	A9MEM2000T	Single-phase energy meter without display
iEM3110	A9MEM3110	Three-phase energy meter with display
iEM3155	A9MEM3155	Three-phase energy meter with display
iEM3210	A9MEM3210	Three-phase energy meter with display
iEM3255	A9MEM3255	Three-phase energy meter with display

**NOTE:** The connection of these devices can be done with an A9XCAU06 pre-wired connector: molded connector (at Smartlink end), and with five wires (at device end).

The table below describes products that need a low level interface relay in order to be connected to Acti 9 Smartlink Ethernet:

Designation	Product Reference	Description
IH, IHP	see catalog	Timer switches with RBN type low level relays or equivalent
IC	see catalog	Light sensitive switches with RBN type low level relays or equivalent
TH, THP	see catalog	Thermostats with RBN type low level relays or equivalent

## **Devices out of the Acti 9 Range**

#### **Description**

Devices that can be connected to the Acti 9 Smartlink Ethernet are:

- Meter with a pulse output and compliant with standard IEC 62053-31
- Volt-Free Low Level Indication Contact
- Volt-Free Standard Indication Contact
- Contactor and Relay
- Indication device or PLC input can be directly connected to the output (Q) of Acti 9 Smartlink Ethernet channel.

The connected device should have the following characteristics:

- To be powered with 24 Vdc
- The consumption must be less than 100 mA
- Any device (for example: motor) that needs a command circuit of more than 100 mA can be controlled by the output (Q) of a channel of Acti 9 Smartlink Ethernet. The electrical diagram must be indirect between Acti 9 Smartlink Ethernet and this device: a low level relay must be installed between the command of this device and Acti 9 Smartlink Ethernet.

**NOTE:** The connection of these devices can be done with an A9XCAU06 pre-wired connector: molded connector (at Smartlink end), and with five wires (at device end).

All sensors (compliant with IEC 61000-6-2 and IEC61000-6-3 standards) using one output (compatible with 4...20 mA or 0...10 V) can be directly connected to analog inputs of Acti 9 Smartlink Ethernet (the connector for analog channel is delivered with the product).

# **Devices with Analog Output**

#### **Overview**

All sensors (compliant with IEC 61000-6-2 and IEC61000-6-3 standards) using 24 Vdc as power supply input and 0...10 V or 4...20 mA output can be connected to Acti 9 Smartlink Ethernet analog inputs (female analog connector is delivered with the product).

# **Chapter 3**

# **Technical Characteristics**

# **Technical Characteristics of the Acti 9 Smartlink Ethernet**

# **General Characteristics**

Characteristic		Value
Product marking		CE
Temperature	Operation (horizontal)	-25+60°C
	Operation (vertical)	-25+50°C
	Storage	-40+85°C
Tropicalization		Execution 2 (relative humidity of 93% at 40°C)
Resistance to voltage dips		10 ms, class 3 according to IEC 61000-4-29
Degree of protection		IP 20
Level of pollution		3
Overvoltage category		OVC II
Conforming to SELV specification	S	Yes
Altitude	Operation	02,000 m
	Storage	03,000 m
Immunity to vibration	IEC 60068-2-6	1 g/± 3.5 mm, 5300 Hz, 10 cycles
Immunity to mechanical shock		15 g/11 ms
Immunity to electrostatic	IEC 61000-4-2	Air: 8 kV
discharge		Contact: 4 kV
Immunity to radiated electromagnetic interference	IEC 61000-4-3	10 V/m – 80 MHz to 3 GHz
Immunity to fast transients	IEC 61000-4-4	1 kV for the I/O, Modbus and Ethernet communication. 2 kV for the 24 Vdc - 5 kHz - 100 kHz power supply
Surge	IEC 61000-4-5	Power supply: 0.5 kV Modbus and Ethernet: 1 KV
Immunity to conducted magnetic fields	IEC 61000-4-6	10 V from 150 kHz to 80 MHz
Immunity to magnetic fields at line frequency	IEC 61000-4-8	30 A/m continuous 100 A/m pulse
Conducted emissions	IEC 61131-2, CISPR	Class A (0.1530 MHz)
Radiated emissions	IEC 61131-2, CISPR	Class A (301000 MHz)
Resistance to corrosive atmospheres	IEC 60721-3-3	Level 3C2 on H <sup>2</sup> S/SO <sup>2</sup> /NO <sup>2</sup> /Cl <sup>2</sup>
Fire withstand	For live parts	30 s at 960°C. IEC 60695-2-10 and IEC 60695-2-11
	For other parts	30 s at 650°C. IEC 60695-2-10 and IEC 60695-2-11
Salt mist	IEC 60068-2-52	Severity 2
Environment		Conforms to RoHS directives
Installation position		Horizontal or vertical
Mean time between failures		More than 1 M hours

# **Integrated Functions**

Characteristic		Value
Counter	Number of counters	Up to 14 (14 inputs)
	Maximum frequency	16.667 Hz, IEC 62053-31
Period stored in backup memory		10 years

# **Mechanical Characteristics**

Characteristic		Value
Dimensions	Length	359 mm
	Height	22.5 mm
	Depth	42 mm
Weight		180 g

# **Communication Module**

Characteristic		Value
Type of interface module		Modbus RTU, RS485 serial connection Modbus TCP/IP Ethernet
Transmission	Modbus RS485	Transfer rate: 9,60019,200 Baud Medium: Double shielded twisted pair Impedance 120 $\Omega$
	Ethernet	Transfer rate: 10/100 Mbps Medium: STP, Cat5e, straight cable
Structure	Туре	Modbus, Ethernet
	Method	Master/Slave
Device type	Modbus	Master
	Ethernet	Server
Turnaround time	Modbus	10 ms
	Ethernet	1 ms
Maximum length of cable	Modbus	1000 m
	Ethernet	100 m
Type of bus connector	Modbus	4-pin connector
	Ethernet	RJ45 (Shielded)
Power supply	Nominal	Non-isolated 24 Vdc with protection against negative voltages up to -28.8 Vdc
	Voltage limits	19.2 28.8 Vdc with ripple
	Current consumption, no-load	110 mA
	Maximum input intensity	1.5 A
	Maximum current inrush	3 A
Isolation	Between the Modbus serial connection and 24 Vdc Ti24 I/O interfaces	1.9 kVdc for 1 minute
	Between the Ethernet serial connection and 24 Vdc Ti24 I/O interfaces	1.9 kVdc for 1 minute
Number of digital I/O channels		7
Number of analog input channel	els	1
Number of ethernet ports		1

# **Digital Inputs**

Characteristic	Value
Number of logic inputs	14 (2 per channel)
Rated input voltage	24 Vdc
Input type	Current sink, type 1 IEC 61131-2
Weight (0 V)	1 for 2 inputs (1 per channel)
Input voltage limits	19.228.8 Vdc

Characteristic	Value
Rated input current	2.5 mA
Maximum input current	5 mA
Filter time	2 ms
Acquisition time	10 ms
Isolation	No isolation between the Ti24 interfaces
Negative voltage protection	Yes
Maximum length of cables and cordsets	500 m (conductor c.s.a. of at least 0.5 mm <sup>2</sup> )

# **Digital Outputs**

Characteristic		Value
Number of logic outputs		7 (1 per channel)
Logic output		Current source, 24 Vdc 0.1 A IEC 61131-2
Weight (0 V)		1
Rated output voltage	Voltage	24 Vdc
	Maximum current	100 mA
Filter time		1 ms
Voltage drop (voltage at state 1)		1 V max.
Maximum current inrush		500 mA
Leakage current		0.1 mA
Overvoltage protection		33 Vdc
Short-circuit protection		Yes
Overload protection		Yes
Current limiting		Yes
Maximum length of cables and cordsets		500 m (conductor c.s.a. of at least 0.5 mm <sup>2</sup> )

# **Analog Inputs**

Characteristic		Value
Number of analog inputs		2
Type of each input		Voltage/Current: IEC 61131 - 2 compliant
Rated input voltage		010 V
Rated input current		420 mA
Input impedance	Current mode	140 Ω
	Voltage mode	50 ΚΩ
Resolution		12 bits
Accuracy		≤ ± 1% of the full scale
Refresh time		500 ms
Isolation		None
Type of cable		Twisted pair and screened
Cable length		< 30 m maximum <sup>(1)</sup>
Channel 8 (Analog inputs) maximum sourcing current at 24 V to power the sensors		200 mA for each analog sensor
Conversion time/Refresh time		100 ms
Connector type		Screw type (4-pin), 3.5 mm pitch

**NOTE:** (1) Wrong wiring or wrong configuration can cause the analog input damage.

Introduce analog isolators (with 0.5 to 1% accuracy) when the cables go outside the switchboard where Acti 9 Smartlink Ethernet is mounted.

# iACT24

Characteristic		Value
Control voltage (Ue)		230 Vac, +10 %, -15 % (Y2) 24 Vdc, ± 20 % (Y3)
Control voltage frequency		50/60 Hz
Insulation voltage (Ui)		250 Vac
Rated impulse withstand voltage	(Uimp)	8 kV (OVC IV)
Level of pollution		3
Degree of protection		IP20B device only IP40 device in modular enclosure
Width in 9 mm modules )		2
Auxiliary contact (O/C) Ti24		24 Vdc protected output, min. 2 mA, max. 100 mA
Contact		1 O/C operating category AC 14
Temperature	Operation	-25 60°C
	Storage	-40 +80°C
Consumption		< 1 W
Standard		IEC/EN 60947-5-1

# iATL24

Characteristic		Value
Control voltage (Ue)		230 Vac, +10 %, -15 % (Y2) 24 Vdc, ± 20 % (Y3)
Control voltage frequency		50/60 Hz
Insulation voltage (Ui)		250 Vac
Rated impulse withstand voltage (Uir	np)	8 kV (OVC IV)
Level of pollution		3
Degree of protection		IP20B device only IP40 device in modular enclosure
Width in 9 mm modules )		2
Auxiliary contact (O/C) Ti24		24 Vdc protected output, min. 2 mA, max. 100 mA
Contact		1 O/C operating category AC 14
Temperature	Operation	-25 60°C
	Storage	-40 +80°C
Consumption		< 1 W
Standard		IEC/EN 60947-5-1

# **Chapter 4**

# Sizing the 24 Vdc Power Supply

# What Is in This Chapter?

This chapter contains the following topics:

Topic	Page
Definition of the 24 Vdc Power Supply	24
Protection Against a 240 Vac Fault on the Acti 9 Smartlink Ethernet Channels	
Electromagnetic Compatibility (EMC) Recommendations	

## **Definition of the 24 Vdc Power Supply**

#### **Safety Information**

# **A** A DANGER

#### **RISK OF ELECTROCUTION**

Isolate the Acti 9 Smartlink Ethernet 24 V power terminals from the power terminals connected to the Modbus network line.

Failure to follow these instructions will result in death or serious injury.

**Example**: The 0 V and the 24 V of a 24 Vdc power supply connected to the TRV00210 ULP communication module must be isolated from the **0 V** or **+24 V** terminals of the 24 Vdc power supply for the Acti 9 Smartlink Ethernet device.

#### **General Characteristics**

Acti 9 Smartlink Ethernet device consumption:

Status	Consumption
Device with no load	110 mA
Device under load	1.5 A maximum

#### **Products in the Acti 9 Range**

If products connected to the channels (Ti24 interfaces) of an Acti 9 Smartlink Ethernet device are in the Acti 9 range, the consumption of a channel output is the same as the consumption of an input because the output is connected to the input. All that needs to be done is to add up the consumption of three input currents per channel.

**Example**: Assuming that the input current is less than 5 mA and two analog sensors connected to Acti 9 Smartlink Ethernet, the consumption of an Acti 9 Smartlink Ethernet device is as follows:

No-load consumption + (number of digital channels x 3 input currents) + (Analog sensor x 2) = 110 mA +  $(7 \times (3 \times 5 \text{ mA})) + (200 \text{ mA} \times 2) = 615 \text{ mA}$ 

#### Products that can be Controlled by a Channel

If products connected to the channels (Ti24 interfaces) of an Acti 9 Smartlink Ethernet device are in a different range, the maximum consumption of a device channel is 110 mA. The output for each channel supplies 100 mA, the digital inputs can consume up to 10 mA and the analog input can consume up to 200 mA.

**Example**: Assuming that the consumption of one channel is 110 mA, the consumption of one Acti 9 Smartlink Ethernet device is as follows:

No-load consumption + (number of digital channels x consumption per channel) + (Analog sensor x 2)

## Selection of the Acti 9 Smartlink Ethernet 24 Vdc Power Supply

The 24 Vdc power supply must correspond to the following criteria:

• It must be local to the electrical cabinet.

= 110 mA + (7 x 110 mA) + (200 mA x 2) = 1.3 A

- It must be different from the Modbus network 24 Vdc power supply so as to maintain galvanic isolation between the Modbus network (common to several electrical cabinets) and the 24 Vdc I/O.
- It must be Safety Extra Low Voltage (SELV) type.
- Galvanic isolation between the power supply input (AC voltage) and the power supply output (DC voltage) must be at least 3 kVac at 50 Hz.
- The rated AC voltage of the power supply input must be 240 Vac +15/-20%.
- This power supply can be used to supply other products inside the electrical cabinet provided that these
  products are double insulated or with reinforced insulation so as to preserve the power supply's SELV
  quality.

Phaseo ABL8MEM240xx (OVC II) or ABL7RM24025 (OVC II) modular power supplies and their accessories comply with the above recommendations. These accessories provide the redundancy and backup power supply functions and can eliminate micro-cuts on the line.

The upstream and downstream protection functions of the Phaseo power supply must be installed as indicated in their respective manuals.

**NOTE:** OVC indicates the overvoltage category.

If overvoltage category IV or III is needed in the installation, we recommend using:

- Either power supplies (limited to 1 A) in the ULP (Universal Logic Plug) system with product references 54440 to 54445. See the User's Manual, ULP Connection System, product reference TRV99100
- Or use the Phaseo power supply recommended above, protecting it with an isolating transformer from the Phaseo Optimum (ABL6TS) range or the Universal (ABT7PDU) range.

**NOTE:** For each of these solutions, you should refer to the respective manuals.

#### Protection Against a 240 Vac Fault on the Acti 9 Smartlink Ethernet Device 24 Vdc Input

A fuse protection is provided if a 240 Vac power supply is accidentally connected to the 24 Vdc input on the Acti 9 Smartlink Ethernet power supply.

## Protection Against a 240 Vac Fault on the Acti 9 Smartlink Ethernet Channels

#### Overview

In the event of a wiring error or electrical fault, the 240 Vac voltage may be present on the Acti 9 Smartlink Ethernet device channels: the neutral or phase (240 Vac) can be in contact with the Ti24 interfaces or the 24 Vdc power supply.

The insulation inside the Acti 9 Smartlink Ethernet device prevents propagation of this dangerous voltage (240 Vac) over the Modbus and Ethernet network.

The protection function inside the Acti 9 Smartlink Ethernet device eliminates the risk of fire inside the Acti 9 Smartlink Ethernet device.

These two protection functions (internal insulation and internal protection) cannot prevent wiring errors or electrical faults. A risk of dangerous voltage remains on the Acti 9 Smartlink Ethernet device channels.

# **A A** DANGER

# HAZARD OF ELECTRIC SHOCK, EXPLOSION, OR ARC FLASH

- Implement a TT or TN-S earthing system.
- Connect the SELV (Safety Extra Low Voltage) power supply 0 Vdc to the protective earth to make it a PELV (Protective Extra Low Voltage) power supply. The upstream residual current protection must be type A.

Failure to follow these instructions will result in death or serious injury.

**NOTE:** In the majority of cases, the presence of a PELV means an upstream residual current protection can trip, thus protecting people and property.

# **A A** DANGER

#### **ACCIDENTAL EQUIPMENT BEHAVIOR**

- Connect the 0 Vdc of the SELV power supply to the protective earth at a single point to avoid any stray currents (50 Hz, harmonics, or transient currents) circulating across the 0 Vdc.
- Check that products supplied by this power supply are not already connecting the 0 Vdc to the protective earth.

Failure to follow these instructions will result in death or serious injury.

# **NOTICE**

## RISK OF DAMAGING THE ACTI 9 SMARTLINK DEVICE

- Connect the 0 Vdc of the SELV power supply to the protective earth at a single point to avoid any stray currents (50 Hz, harmonics, or transient currents) circulating across the 0 Vdc.
- Check that products supplied by this power supply are not already connecting the 0 Vdc to the
  protective earth.

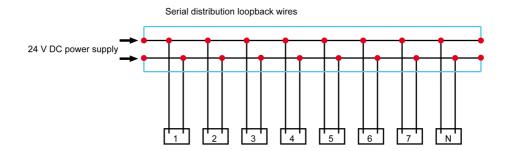
Failure to follow these instructions can result in equipment damage.

# **Electromagnetic Compatibility (EMC) Recommendations**

#### Overview

A star 24 Vdc distribution is preferable to a serial 24 Vdc distribution because star 24 Vdc distribution can minimize the wiring impedance.

If serial distribution is used, it is recommended to wire two serial loopback wires (see the two blue wires in the drawing below) in order to minimize impedance.



In a poor-quality electrical distribution network, it is recommended to use a Phaseo power supply from the Universal range (ABL8MEM240xx (OVC II) or ABL7RM24025 (OVC II)) which can withstand up to 500 Vac incoming and also offers galvanic insulation between the power supply AC input and the power supply DC output of 4 kVac at 50 Hz.

It is mandatory to comply with the segregation rules between low level signals (24 Vdc) and power conductors, see:

- <u>www.electrical-installation.org</u> see "ElectroMagnetic Compatibility (EMC)" part, "Wiring recommendations" section (information only available in English).
- Electrical Installation Guide in pdf format: Document No. EIGED306001EN.

# **Chapter 5**

# Installation

# What Is in This Chapter?

This chapter contains the following topics:

Topic	Page
Mounting	30
Connection	33

# **Mounting**

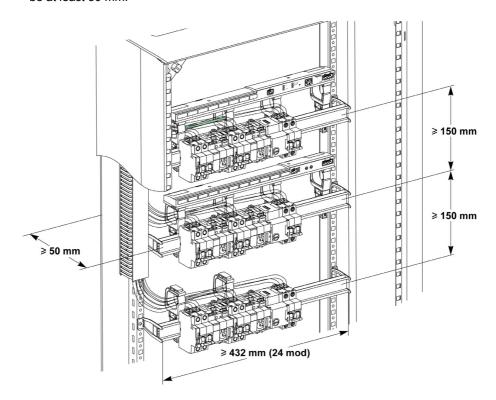
#### Introduction

The Acti 9 Smartlink Ethernet device can be mounted on:

- DIN rail
- Multiclip 80
- Multiclip 200

Acti 9 Smartlink Ethernet can be installed horizontally or vertically:

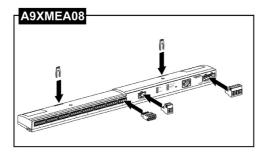
- In a horizontal mounting, Acti 9 Smartlink Ethernet is clipped onto DIN rails with fixing centers of 150 mm or more.
- Wall-mounted and floor-standing enclosures must be at least 24 modules wide (18 mm x 24 = 432 mm).
- The distance between the DIN rail and the back of the wall-mounted or floor-standing enclosure must be at least 50 mm.



The ambient operating temperature is:

- Horizontal mounting: -25°...+60°C
- Vertical mounting: -25°...+50°C

# **Mounting Components**



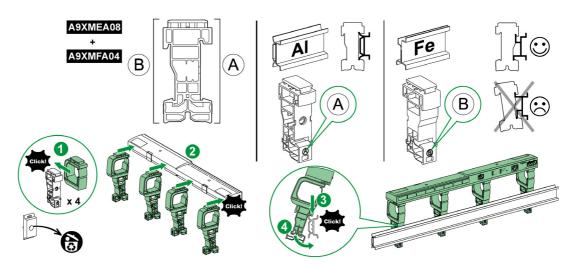




Product Reference	Description
A9XMEA08	Acti 9 Smartlink Ethernet
A9XMFA04	Set of bracelets, adaptors, and feet for DIN rail mounting
A9XM2B04	Spacers for Multiclip 200 mounting

#### **DIN Rail Mounting**

The side of the foot ( $\bf A$  or  $\bf B$  in the drawing below) used to mount the system on the DIN rail depends on the type of rail (aluminum or iron).

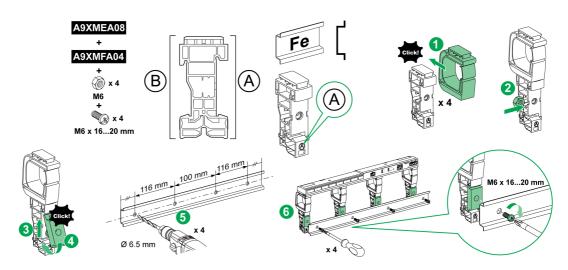


The table below describes the procedure for mounting the Acti 9 Smartlink Ethernet device on a DIN rail:

Step	Action
1	Clip one bracelet onto one foot according to the type of rail. Repeat this step three times.
2	Clip the Acti 9 Smartlink Ethernet device on top of the bracelets.
3	Place the top of the foot at an angle against the top lip of the rail.
4	Clip the bottom of the foot into place.
5	Repeat steps 3 and 4 for each of the other three feet.

# **Simple DIN Rail Mounting**

To mount the system on a simple DIN rail (iron), use side **A** of the foot.

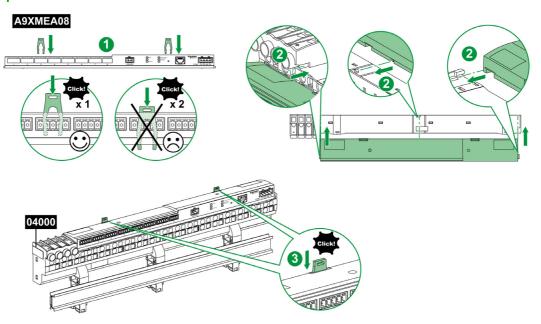


The table below describes the procedure for mounting the Acti 9 Smartlink Ethernet device on a simple DIN rail:

Step	Action	
1	Clip one bracelet onto side <b>A</b> of a foot. Repeat this step three times.	
2	Place one M6 nut inside a foot. Repeat this step three times.	
3	Position the top of an adaptor diagonally at the front of a foot.	
4	Clip the bottom of the adaptor into place. Repeat steps 3 and 4 three times.	

Step	Action	
5	Drill the rail making sure that the drill hole diameters and positioning dimensions are correct, as shown in the above graphic.	
6	Screw the feet onto the rail.	

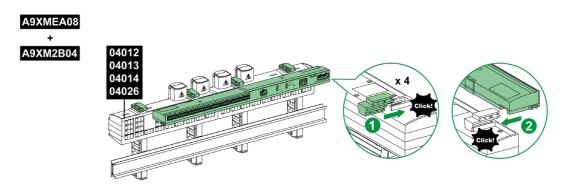
# **Mounting on Multiclip 80**



The table below describes the procedure for mounting the Acti 9 Smartlink Ethernet device on Multiclip 80.

Step	Action
1	Position the two clips in the notches on the Acti 9 Smartlink Ethernet device.
2	Slide the Acti 9 Smartlink Ethernet device front first onto the Multiclip 80 until fully inserted.
3	Push down the two clips until they click into place.

# **Mounting on Multiclip 200**



The table below describes the procedure for mounting the Acti 9 Smartlink Ethernet device on Multiclip 200.

Step	Action
1	Slide the four spacers from the back into the notches on top of the Multiclip 200.
2	Slide the Acti 9 Smartlink Ethernet device front first onto the spacers, until it clicks into place.

#### Connection

#### **Safety Instructions**

# **A** A DANGER

#### RISK OF ELECTRIC SHOCK, EXPLOSION, OR ARC FLASH

- Wear suitable personal protective equipment and follow the currently applicable electrical safety instructions.
- This equipment may only be installed by qualified electricians who have read all the relevant information.
- NEVER work alone.
- Before performing visual inspections, tests, or maintenance on this equipment, disconnect all sources
  of electric power. Assume that all circuits are live until they have been completely de-energized, tested
  and tagged. Pay particular attention to the design of the power system. Consider all power supply
  sources, particularly the potential for backfeed.
- Before closing protective covers and doors, carefully inspect the work area to ensure that no tools or
  objects have been left inside the equipment.
- Take care when removing or replacing panels. Take special care to ensure that they do not come into contact with live busbars. To minimize the risk of injuries, do not tamper with the panels.
- The successful operation of this equipment depends upon proper handling, installation, and operation.
   Failure to follow basic installation procedures can lead to personal injury as well as damage to electrical equipment or other property.
- NEVER shunt an external fuse/circuit breaker.
- This equipment must be installed inside a suitable electrical cabinet.

Failure to follow these instructions will result in death or serious injury.

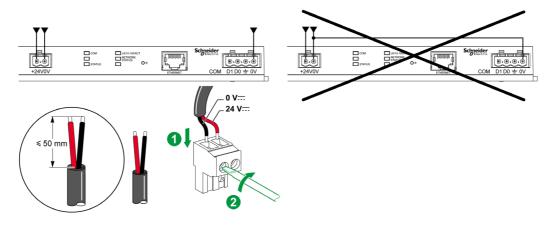
# A A DANGER

#### **RISK OF ELECTROCUTION**

Isolate the Acti 9 Smartlink Ethernet power terminals from the power terminals connected to the Modbus network line.

Failure to follow these instructions will result in death or serious injury.

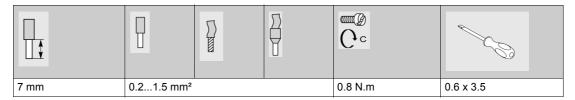
#### **Connecting the Power Supply Connector**



The table below describes the procedure for connecting the power supply connector:

Ste	ер	Action	
1		Insert both stripped power supply wires in the connector.	
2		Fix the wires in place using the connector tightening screws.	

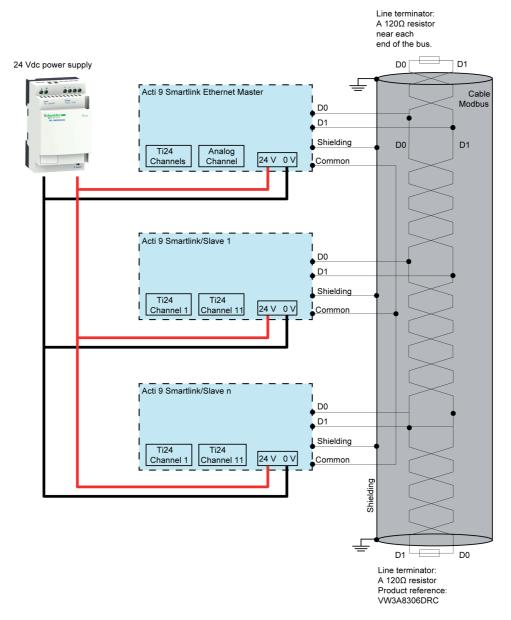
The table below gives the characteristics of cables that can be used to connect the 24 Vdc power supply:



#### **Connecting the Modbus Connector**

The Schneider Electric communication cables to be used are:

Product Reference	Description	Length (m)
50965	RS 485 double shielded twisted pair cable for Modbus serial link (supplied without connector)	60



## NOTE:

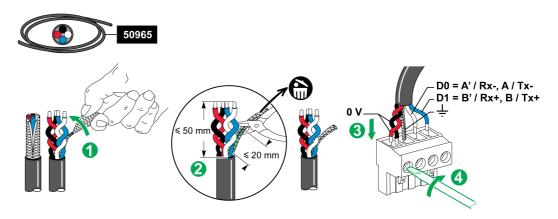
• It is possible to use a common 24 Vdc power-supply for several Acti 9 Smartlink devices if installed in the same switchboard.

# NOTICE

# HAZARD OF NON-OPERATION OF MODBUS NETWORK

Comply with the wiring and connection rules described below in order to create a working Modbus network.

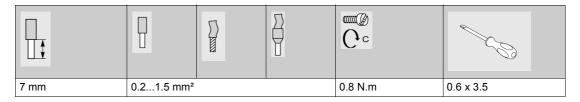
Failure to follow these instructions can result in equipment damage.



The table below describes the procedure for connecting the Modbus connector:

Step	Action
1	Coil up the Modbus communication cable shielding.
2	Cut the shielding 20 mm from the sheath.
3	Insert the stripped wires in the connector terminals as shown in the above graphic.
4	Fix the wires in place using the connector tightening screw.

The table below gives the characteristics of cables that can be used to connect the Modbus connector:



# **Checking the Modbus Serial Link**

The table below gives the characteristics of the RS 485 link that need to be checked during installation:

Designation	Description
Shielding connection	Each Modbus serial link must have shielding connected at one point to an earthed link.
Bus polarization	<ul> <li>Pull-up resistor connected to the 5 V: 450650 Ohm</li> <li>Pull-down resistor connected to ground (Modbus 0 V): 450650 Ohm</li> </ul>
	<b>NOTE</b> : This polarization is recommended for the master.
Line terminator	A 150 Ohm resistor ± 5%
Ground polarity	The ground circuit (0 V of an optional power supply) must be connected directly to a protected earth, preferably at a single point on the bus. This point is usually placed on the master or its slaves.
Trunk cable	A pair of shielded twisted cables and a third conductor at minimum.
Maximum length of bus	1000 m at 19,200 Baud with the Schneider Electric 50965 cable.

# **Chapter 6**

# **Connection of Input/Output Channels**

## What Is in This Chapter?

This chapter contains the following topics:

Торіс	Page
Acti 9 Devices with Ti24 Interface	38
Meters	39
Volt-Free Low Level Indication Contact	40
Volt-Free Standard Indication Contact	41
Contactor and Relay (Not in the Acti 9 Range)	42
Direct Output Connection	43
Indirect Output Connection	44
Generating Summary Data Using iOF+SD24 or OF+SD24	45
Analog Input Characteristics and Connection (Recommendation)	47
Recommendation for Cabling	48

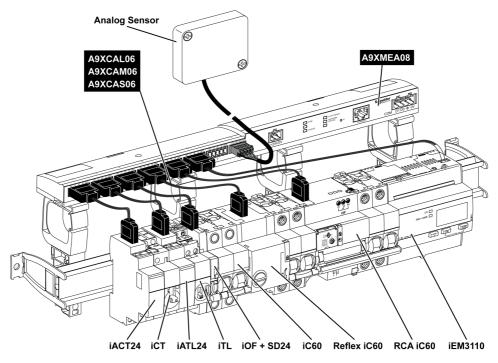
## Acti 9 Devices with Ti24 Interface

#### **Overview**

Auxiliary devices such as iACT24, iATL24, iOF+SD24, OF+SD24, RCA iC60, and Reflex iC60 can be connected to the Acti 9 Smartlink Ethernet with Acti 9 communication system pre-asssembled cables.

## Wiring

The figure below shows the connection of auxiliary devices to the Acti 9 Smartlink Ethernet using pre-assembled cables:



**NOTE:** A9XCAU06 cable could be used to link Acti 9 devices with Ti24 interface to Acti 9 Smartlink Ethernet.

In this case, for the connection of iACT24 and iATL24, input I2 must be connected on both ends of A9XCAU06 cable.

#### **Meters**

#### Overview

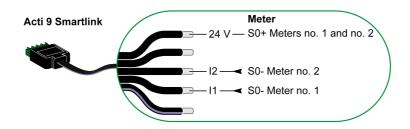
The iEM2000T, iEM3110, iEM3155, iEM3210, and iEM3255 products are kilowatt-hour meters from the Schneider Electric range.

Meters not in the Acti 9 range can be controlled by an Acti 9 Smartlink Ethernet channel. These meters must have the following characteristics:

- 1 pulse output
- Compatibility with standard IEC 62053-31

#### Wiring

iEM2000T, iEM3110, iEM3155, iEM3210, and iEM3255 kilowatt-hour meters can be connected to channel N ( $1 \le N \le 7$ ) of an Acti 9 Smartlink Ethernet module with an A9XCAU06 pre-wired connector: molded connector (at Acti 9 Smartlink Ethernet end), and with 5 wires (at iEM2000T end).

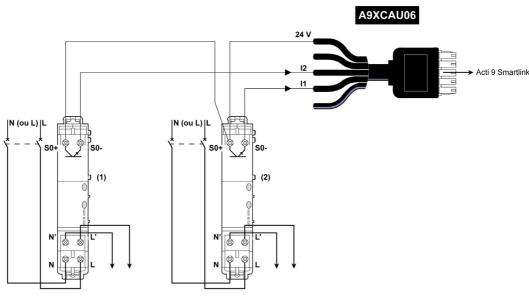


**NOTE:** A single Acti 9 Smartlink Ethernet channel can take account of 2 meters, 1 meter on input I1 and 1 meter on input I2.

## NOTE:

- Do not connect 2 wires in each of the Ti24 connector terminals (A9XC2412).
- Do not connect a wire with cable end in each of the Ti24 connector terminals.

## **Example of Connection of iEM2000T Meters**



- 1 iEM2000T meter
- 2 iEM2000T meter

## **Volt-Free Low Level Indication Contact**

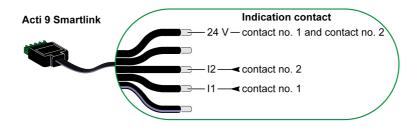
#### Overview

A low level type indication contact (NO or NC) can be connected to input I1 or I2 of an Acti 9 Smartlink Ethernet channel.

**NOTE:** A single Acti 9 Smartlink Ethernet channel can take account of two indication contacts, one contact on input I1, and one contact on input I2.

#### Wiring

An indication contact can be connected with an A9XCAU06 pre-wired connector: molded connector (at Acti 9 Smartlink Ethernet end, and with the five wires (indication contact end).

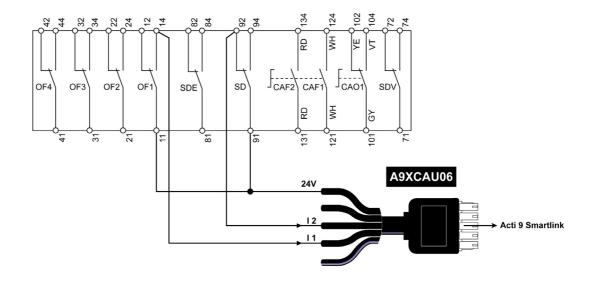


#### NOTE:

- Do not connect 2 wires in each of the Ti24 connector terminals (A9XC2412).
- Do not connect a wire with cable end in each of the Ti24 connector terminals.

#### **Example of Connection**

The OF and SD contacts of a NSX circuit breaker could be directly connected to Acti 9 Smartlink Ethernet.



## **Volt-Free Standard Indication Contact**

#### Overview

A standard indication contact (NO or NC) can be connected to input I1 or I2 of an Acti 9 Smartlink Ethernet channel.

**NOTE:** A single Acti 9 Smartlink Ethernetchannel can take account of two indication contacts, one contact on input I1 and one contact on input I2. The electrical diagram must be indirect between Acti 9 Smartlink Ethernet and this device: a low level relay must be installed between the contact of this device and Acti 9 Smartlink Ethernet.

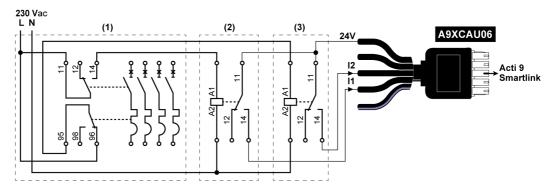
#### Wiring

An indication contact can be connected with an A9XCAU06 pre-wired connector: molded connector (at Acti 9 Smartlink Ethernet end, and with the five wires (indication contact end).

#### NOTE:

- Do not connect two wires in each of the Ti24 connector terminals (A9XC2412).
- Do not connect a wire with cable end in each of the Ti24 connector terminals.

## **Example of Connection**



- (1) NG125 circuit breaker: OF+SD auxiliary contacts with a minimum current of 100 mA
- (2) iRBN relay for OF signal
- (3) iRBN relay for SD signal

## Contactor and Relay (Not in the Acti 9 Range)

#### Overview

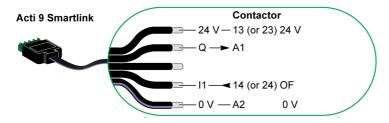
A contactor or relay powered with 24 Vdc can be connected to Acti 9 Smartlink Ethernet. This should have the following characteristics:

- The contactor or relay coil must not draw more than 100 mA
- The indication contact must be low level type

Only contactors in the Acti 9 range can be connected to Acti 9 Smartlink Ethernet using the iACT24 auxiliary.

## Wiring

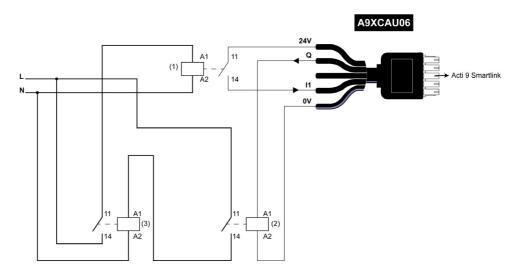
A contactor can be connected with an A9XCAU06 pre-wired connector: molded connector (at Acti 9 Smartlink Ethernet end), and with five wires (at contactor end).



#### NOTE:

- Do not connect 2 wires in each of the Ti24 connector terminals (A9XC2412).
- Do not connect a wire with cable end in each of the Ti24 connector terminals.

#### **Example of Connection**



- 1 Low level relay (for example, iRBN)
- 2 24 Vdc/230 Vac relay
- 3 Power contactor (for example, TeSys D, type LC1)

## **Direct Output Connection**

#### **Overview**

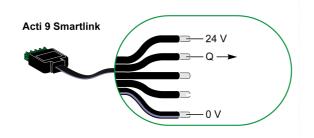
An indication device or a PLC input can be directly connected to the output (Q) of Acti 9 Smartlink Ethernet channel.

The connected device should have the following characteristics:

- To be powered with 24 Vdc
- The consumption must be less than 100 mA

## Wiring

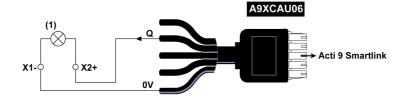
The wiring can be done with an A9XCAU06 pre-wired connector: molded connector (at Acti 9 Smartlink Ethernet end), and with five wires (at contactor end).



#### NOTE:

- Do not connect two wires in each of the Ti24 connector terminals (A9XC2412).
- Do not connect a wire with cable end in each of the Ti24 connector terminals.

## **Example of Connection**



(1) Indication light 12...48 Vdc/Vac

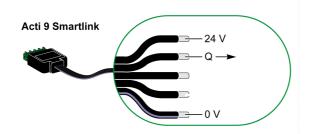
## **Indirect Output Connection**

#### Overview

Any device (for example: motor) that needs a command circuit of more than 100 mA can be controlled by the output (Q) of a channel of Acti 9 Smartlink Ethernet. The electrical connection between Acti 9 Smartlink Ethernet and the device must be indirect. A low level relay must be installed between the command of the connected device and Acti 9 Smartlink Ethernet.

#### Wiring

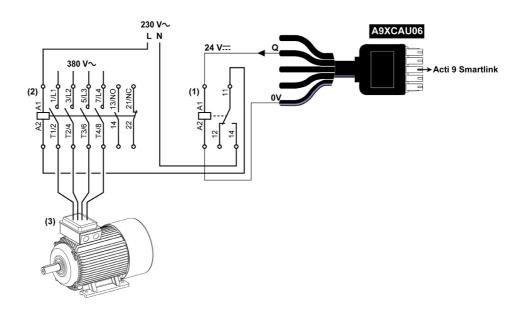
The wiring can be done with an A9XCAU06 pre-wired connector: molded connector (at Acti 9 Smartlink Ethernet end), and with five wires (at contactor end).



#### NOTE:

- Do not connect two wires in each of the Ti24 connector terminals (A9XC2412).
- Do not connect a wire with cable end in each of the Ti24 connector terminals.

## **Example of Connection**



- (1) Relay iRTBT
- (2) Contactor Tesys D LC1D•25 with an 230 Vac coil
- (3) Motor 10 kW with power supply 3-phases 380 Vac

## Generating Summary Data Using iOF+SD24 or OF+SD24

#### Overview

The electrical summary of the SD contacts or summary of the OF contacts can be generated with iOF+SD24 and/or OF+SD24 auxiliaries.

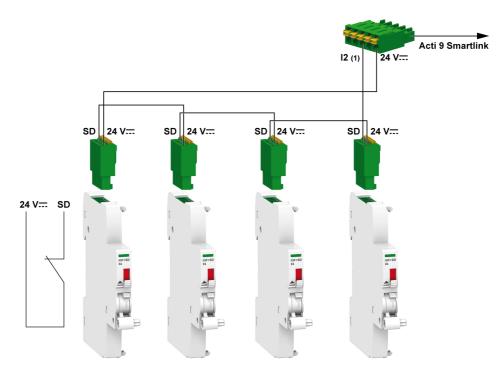
The electrical summary of the OF signals can be done by cabling in series of all OF signals and by connecting this circuit to the I1 input of a channel of Acti 9 Smartlink Ethernet.

The electrical summary of the SD signals can be done by cabling in series of all SD signals and by connecting this circuit to the I2 input of another channel of Acti 9 Smartlink Ethernet.

The OF connections (on I1 input) and the SD connections (on I2 input) cannot be connected to the same channel of Acti 9 Smartlink Ethernet, as the summary information dedicated to the OF signals cannot be separated from the summary information dedicated to the SD signals in Acti 9 Smartlink Ethernet.

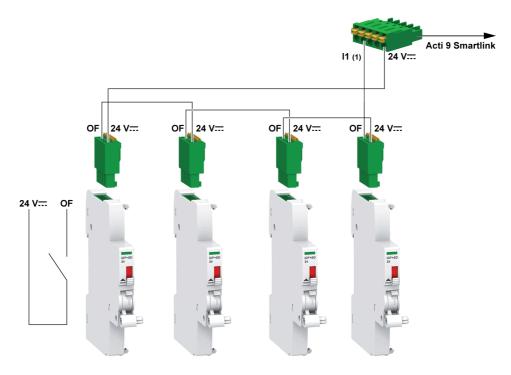
The summary of OF (or SD) signals can be wired in series using the A9XC2412 15-pin connector (spring cage). A maximum of 10 OF (or SD) signals can be wired in the same summary.

## Wiring SD Contacts on iOF+SD24 or OF+SD24 in Series



(1) Input I2 (of a channel) on Acti 9 Smartlink Ethernet or PLC input

## Wiring OF Contacts on iOF+SD24 or OF+SD24 in Series



(1) Input I1 (of a channel) on Acti 9 Smartlink Ethernet or PLC input

## **Analog Input Characteristics and Connection (Recommendation)**

## Overview

Analog Input Characteristics	Value
Number of analog inputs	2
Type of input	Voltage/Current: IEC 61131 - 2
Rated input voltage	010 V
Rated input current	420 mA
Input impedance for current mode	140 Ω
Input impedance for voltage mode	50 kΩ
Resolution	12 bits
Accuracy	≤ ±1% of the full scale
Refresh time	500 ms
Isolation	None
Type of cable	Twisted pair or screened cable
Cable length	< 30 m maximum <sup>(1)</sup>
Channel 8 (analog inputs) maximum sourcing current at 24 V to power the sensors	200 mA for each analog sensor
Conversion time/Refresh time	100 ms
Connector type	Screw type (4-pin), 3.5 mm pitch

**NOTE:** (1) The instruction for missed wiring or wrong configuration can result in input damage.

## **Recommendation for Cabling**

## **Connecting the Analog Input Connector**

The table below gives the details of the cable reference and specifications of the analog input connector:

Cable Reference		Specifications	Cable Stripping Length	
Manufacturer	Alpha wire	STP Cable (shielded twisted pair	≤ 50 mm	
Part reference	3303	Cable length < 30 m		7 mm
_		AWG between 26 - 16	_	

## NOTICE

## **RISK OF DAMAGING THE EQUIPMENT**

Ensure that the analog channel configuration and physical connection is accurate.

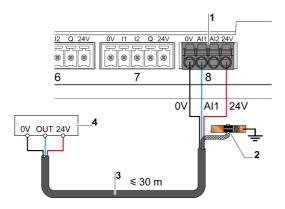
Failure to follow these instructions can result in equipment damage.

The reference of the analog input connector are:

- Manufacturer: Phoenix
- Commercial reference: 1916410
- Description: PTB PLUG 3.5 NA FMLE MCSCW 4 1x4 PA

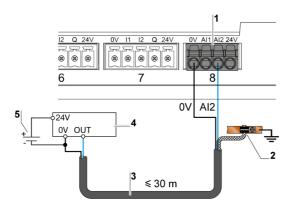
## Wiring

The following figure shows the sensor powered by Acti 9 Smartlink Ethernet:



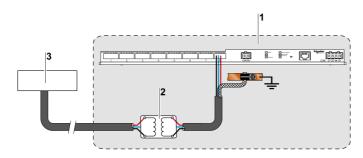
- 1 Consumption or each Al1 or Al2: 200 mA
- 2 The shield must be connected to ground near the Acti 9 Smartlink Ethernet with a clamp only
- 3 Twisted pair, shielded cable
- 4 Sensor (current/voltage) compliant with IEC 61000-6-2 and IEC 61000-6-3 standards

The following figure shows the sensor powered by external power supply:



- 1 Consumption or each Al1 or Al2: 200 mA
- 2 The shield must be connected to ground near the Acti 9 Smartlink Ethernet with a clamp only
- 3 Twisted pair, shielded cable
- 4 Sensor (current/voltage) compliant with IEC 61000-6-2 and IEC61000-6-3 standards
- 5 External power supply

If the analog sensor is placed outside the panel, then an analog isolator is recommended as per the system specifications.



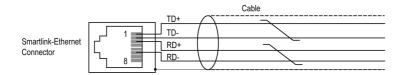
- 1 Acti 9 Smartlink Ethernet
- 2 Analog isolator
- 3 Sensor (current/voltage) compliant with IEC 61000-6-2 and IEC61000-6-3 standards

## **Connecting the Ethernet Connection**

The connection between Acti 9 Smartlink Ethernet and other Ethernet devices is done using a standard straight Ethernet cable (RJ45 shield twist pair).

If Acti 9 Smartlink Ethernet is mounted on Multiclip 200, the cable must be a right angle RJ45 Ethernet cable in order to install a cover in the panel.

## **RJ45 Connector and Signal Pin**



The table below gives the details of RJ45 connector and signal description:

RJ45 Female Pin Number	Signal	RJ45 Male Plug Pair	Signal Description
1	TX+	A	Transmit+
2	TX-	A	Transmit-
3	RX+	В	Receive+
4	Not connected	-	Not connected
5	Not connected	-	Not connected
6	RX-	В	Receive-
7	Not connected	-	Not connected
8	Not connected	-	Not connected

# **Chapter 7**

# **Setting Up Ethernet Communication**

## What Is in This Chapter?

This chapter contains the following topics:

Topic	Page
Ethernet Principle	52
Set Up and Ethernet Addressing Mode	53
Web Page Setting Menu	56
Acti 9 Smartlink Ethernet Device Function	59
Modbus TCP/IP Functions	60
Modbus TCP/IP Exception Codes	62
Description of Ethernet LEDs	63
Other Protocol or Services	64

## **Ethernet Principle**

#### Overview

Ethernet is a data link and physical layer protocol defined by IEEE 802 specification that connects computer or other Ethernet devices. Ethernet is an asynchronous Carrier Sense Multiple Access with Collision detection (referred as CSMA/CD) protocol. Carrier Sense means that the hosts can detect whether the medium (coaxial cable) is idle or busy. Multiple Access means that multiple hosts can be connected to the common medium. Collision Detection means a host detects whether its transmission has collided with the transmission of another host (or hosts).

Acti 9 Smarlink Ethernet can be connected to a PC or a laptop over Ethernet. Acti 9 Smarlink Ethernet provides a Modbus TCP/IP gateway over Ethernet to enable Modbus TCP communication from a Modbus TCP master to any Modbus slave devices connected to it.

The maximum active Modbus TCP client connection is eight.

Acti 9 Smarlink Ethernet has an embedded web server (web page).

## **Set Up and Ethernet Addressing Mode**

#### **Ethernet Connection**

The table below provides the steps recommended to connect a PC or a laptop for the first time to Acti 9 Smartlink Ethernet device:

Step	Action
1	Disconnect your PC from all networks.
2	Connect an Ethernet straight cable between your PC or a laptop and the Ethernet port on the Acti 9 Smartlink Ethernet.
3	Perform the actions described in the section below for accesing web page.

The following tables provides the steps to access web page of Acti 9 Smartlink Ethernet from Windows XP and Windows 7.

## Access Web Page of Acti 9 Smartlink Ethernet from Windows XP

The table below provides the steps to access web page of Acti 9 Smartlink Ethernet from Windows XP:

Use Case	Procedure	
Panel not connected to building network	<ol> <li>Launch the web browser (Google Chrome, Internet Explorer, Mozilla Firefox, or Safari)<sup>(1)</sup> on your PC.</li> <li>Type the IPv4 address<sup>(2)</sup> in the address field of the web browser.</li> <li>Press ENTER. This opens the home page of the web page.</li> </ol>	
Panel is already connected for the first time to building network with no DHCP server, using static addressing mode	Connect your PC or a laptop directly to Acti 9 Smartlink Ethernet (point to point) or if not connected to Acti 9 Smartlink Ethernet, connect your PC to	
Panel is already connected to building network with DHCP server, using dynamic addressing mode	<ol> <li>Connect your PC or a laptop to the building Ethernet network.</li> <li>Launch the web browser (Google Chrome, Internet Explorer, Mozilla Firefox, or Safari)<sup>(1)</sup> on your PC.</li> <li>Type the name<sup>(3)</sup> of the Acti 9 Smartlink Ethernet in the address field of the web browser.</li> <li>Press ENTER. This opens the home page of the web page.</li> </ol>	

- (1) The browsers compatible with Acti 9 Smartlink Ethernet are:
- Internet Explorer (Windows) version 8, 9, and 10
- Google Chrome (Windows) from 4.0.249 and for MAC from (17.0.963)
- Mozilla Firefox from 4.0
- Safari (Windows) from 5.1.7

 $^{(2)}$  IPv4 address is printed on Acti 9 Smartlink Ethernet with this format 169.254.xxx.yyy. The 2 last numbers (xxx, yyy) are unique per product.

 $^{(3)}$  By default the name of the product is SmartLinkIP-1234.

## Access Web Page of Acti 9 Smartlink Ethernet from Windows 7

The table below provides the steps to access web page of Acti 9 Smartlink Ethernet from Windows 7:

Use Case	Procedure		
Panel not connected to building network	<ol> <li>Connect your PC or a laptop directly to Acti 9 Smartlink Ethernet (point to point) or connect your PC or a laptop to the Ethernet switch of the panel.</li> <li>Launch the Windows explorer, then select Network to see the available devices.</li> <li>Double-click on the auto-discovered<sup>(3)</sup> Acti 9 Smartlink Ethernet product. This opens the home page of the web page.</li> </ol>		

Use Case	Procedure	
Panel is already connected for the first time to building network with no DHCP server, using static addressing mode	<ol> <li>Connect your PC or a laptop directly to Acti 9 Smartlink Ethernet (point to point) or connect your PC or a laptop to the Ethernet switch of the panel or if not connected to Acti 9 Smartlink Ethernet, connect your PC to the building Ethernet network.</li> <li>Launch the Windows explorer, then select Network to see the available devices.</li> <li>Double-click on the auto-discovered<sup>(3)</sup> Acti 9 Smartlink Ethernet product. This opens the home page of the web page.</li> <li>From the web page, click Settings menu - IPv4/v6 page, Manual IP Addressing parameter, type new IPv4 address, subnet mask, and gateway address.</li> <li>Put a sticker on the product with the new IPv4 address.</li> </ol>	
Panel is already connected to building network with DHCP server, using dynamic addressing mode	<ol> <li>From either different subnet or same subnet:         <ol> <li>Connect your PC or a laptop to the building Ethernet network.</li> <li>Launch the web browser (Google Chrome, Internet Explorer, Mozilla Firefox, or Safari)<sup>(1)</sup> on your PC.</li> <li>Type the name<sup>(3)</sup> of the Acti 9 Smartlink Ethernet in the address field of the web browser.</li> <li>Press ENTER. This opens the home page of the web page.</li> </ol> </li> <li>From same subnet:         <ol> <li>Connect your PC or a laptop to the building Ethernet network.</li> <li>Launch the Windows explorer, then select Network to see the available devices.</li> </ol> </li> <li>Double-click on the auto-discovered<sup>(3)</sup> Acti 9 Smartlink Ethernet product. This opens the home page of the web page.</li> </ol>	
Panel is already connected to the building network with DHCP server, using fixed addressing mode	<ol> <li>From either different subnet or same subnet:         <ol> <li>Connect your PC or a laptop to the building Ethernet network.</li> <li>Launch the web browser (Google Chrome, Internet Explorer, Mozilla Firefox, or Safari)<sup>(1)</sup> on your PC.</li> <li>Type the IPv4 address<sup>(2)</sup> of the Acti 9 Smartlink Ethernet in the address field of the web browser.</li> <li>Press ENTER. This opens the home page of the web page.</li> </ol> </li> <li>From same subnet:         <ol> <li>Connect your PC or a laptop to the building Ethernet network.</li> <li>Launch the Windows explorer, then select Network to see the available IP devices.</li> </ol> </li> <li>Double-click on the auto-discovered<sup>(3)</sup> Acti 9 Smartlink Ethernet product. This opens the home page of the web page.</li> </ol>	

<sup>&</sup>lt;sup>(1)</sup> The browsers compatible with Acti 9 Smartlink Ethernet are:

- Internet Explorer (Windows) version 8, 9, and 10
- Google Chrome (Windows) from 4.0.249 and for MAC from (17.0.963)
- Mozilla Firefox from 4.0
- Safari (Windows) from 5.1.7

## **Access Web Page using Tablet**

The table below describes the procedure to access web page using tablet:

Step	Action
1	Connect Acti 9 Smartlink Ethernet to the wireless router using Ethernet cable.
2	Search for the available networks in the tablet.
3	Connect the tablet to the same wireless router to which Acti 9 Smartlink Ethernet is connected.
4	Launch web browser in the tablet after a connection is established.
5	Type the IP address of the Acti 9 Smartlink Ethernet on the web browser if Acti 9 Smartlink Ethernet is in static IP address mode.  Type the product name (for example, https://SmartlinkIP-1234) on the web browser if Acti 9 Smartlink Ethernet is in DHCP mode and tablet is used along with wireless router (DHCP).
6	Type the username and the password in the login page to access the device.

 $<sup>^{(2)}</sup>$  IPv4 address is printed on Acti 9 Smartlink Ethernet with this format 169.254.xxx.yyy. The 2 last numbers (xxx, yyy) are unique per product.

 $<sup>^{(3)}</sup>$  By default the name of the product is SmartLinklP-1234.

## **Access Web Page using Smartphone**

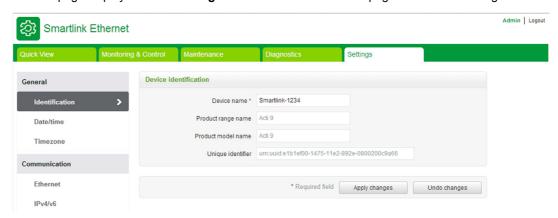
The table below describes the procedure to access web page using smartphone:

Step	Action		
1	Connect Acti 9 Smartlink Ethernet to the wireless router using Ethernet cable.		
2	Search for the available networks in the smartphone.		
3	Connect the smartphone to the same wireless router to which Acti 9 Smartlink Ethernet is connected.		
4	Launch web browser in the smartphone after a connection is established.		
5	Type the IP address of the Acti 9 Smartlink Ethernet on the web browser if Acti 9 Smartlink Ethernet is in static IP address mode.  Type the product name (for example, https://SmartlinkIP-1234) on the web browser if Acti 9 Smartlink Ethernet is in DHCP mode and smartphone is used along with wireless router (DHCP).		
6	Type the username and the password in the login page to access the device.		

## Web Page Setting Menu

#### **Description**

The first page displayed in the **Settings** menu is the **Identification** page as shown in the figure below:

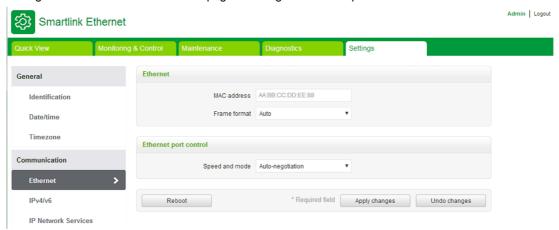


This page is used to read or modify the **Device name** that is used by the communication protocol to identify the device. For more details, refer the **Identification page** (see page 91) described in web page chapter.

#### **Ethernet Settings**

The Ethernet parameters can be set using the Acti 9 Smartlink Ethernet web page (access to web page is described in Web Page chapter (see page 77)).

The figure below shows the **Ethernet** page to configure Ethernet parameters:



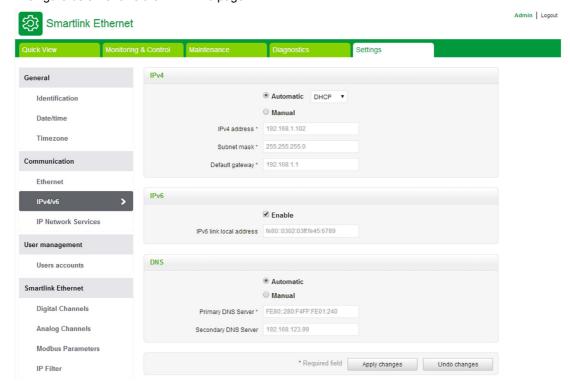
The user can modify the following parameters in **Communication** chapter, **Ethernet** page:

- Frame format (the default value is Auto)
- Speed and mode (the default value is Auto-negotiation)

This page also permits to read the **MAC address** of the product. The configuration of the Ethernet parameters is explained in detail in Ethernet page (see page 93).

## IPv4/IPv6 Settings

The user can configure the IPv4 parameters using the **IPv4/v6** page in the **Communication** chapter. The figure below shows the IPv4/IPv6 page:



The user must select either **Automatic** or **Manual** (the default is **Automatic**) mode to configure IPv4 parameters. The user can select DHCP or BOOTP (the default is DHCP) from the list to configure IPv4 parameters using **Automatic** mode (see page 94).

The user can enter the details of the following parameters to configure the IPv4 parameters in **Manual** mode:

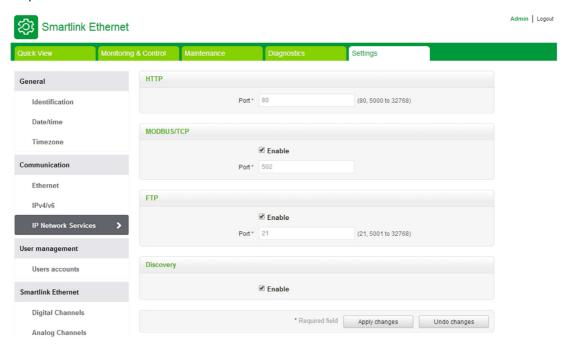
- IPv4 address
- Subnet mask
- Default gateway

The user can select the **Enable** check box to enable the IPv6 service. It is recommended to reboot the device for enable or disable action to take effect.

NOTE: It takes about a minute for the IP setting changes to take effect.

#### **IP Network Services**

The user can select the IP network services using **IP Network Services** page in the **Communication** chapter.



Acti 9 Smartlink Ethernet supports HTTP, FTP, Modbus TCP, and Discovery protocols and services. The user can select the **Enable** check box to enable the **Modbus/TCP** and **Discovery** services. If the discovery service is enabled, user can access Acti 9 Smartlink Ethernet from a laptop or a PC directly. The user cannot modify the HTTP and FTP parameters, as HTTP and FTP are read-only parameters The configuration of the network parameters is explained in detail in IP Network Services Page (see page 95).

#### **Acti 9 Smartlink Ethernet Device Function**

#### Modbus TCP/IP Server

Acti 9 Smartlink Ethernet provides a Modbus TCP server to give access to all its data and configuration parameters. Acti 9 Smartlink Ethernet has a fixed unit ID of 255. The Modbus data mapping and read or write accesses is identical to RS485 for same functions or data. In other words, the Modbus data mapping is a subset of RS485 data mapping (at least for digital channels related accesses).

## **Modbus TCP/IP Gateway**

Modbus TCP/IP gateway on Acti 9 Smartlink Ethernet enables communication between a Modbus TCP/IP client connected to the TCP/IP port on Acti 9 Smartlink Ethernet and any Modbus slave devices connected to Acti 9 Smartlink Ethernet. Acti 9 Smartlink Ethernet provides a simple and transparent interface between Ethernet based networks and field devices. This includes meters, monitors, protective relays, trip units, motor controls, and other devices that communicate using Modbus RS485 slave.

Acti 9 Smartlink Ethernet can manage up to eight Modbus RS485 slaves. Address of these slaves could be from 1 to 247 (the default address ranges from 1 through 8).

Modbus communication parameters are:

- Data rate (in Baud) 9,600 and 19,200 (19,200 is the default data rate)
- Parity
  - Even and one stop bit
  - Odd and one stop bit
  - No Parity (parity bit eliminated) two stop bits are needed

#### **Modbus TCP/IP Functions**

#### **General Description**

The Modbus messaging service provides a client/server communication between devices connected on an Ethernet TCP/IP network.

The client/server model is based on four type of messages:

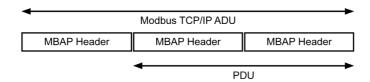
- Modbus Request, the message sent on the network by the client to initiate a transaction.
- Modbus Indication, the request message received on the server side.
- Modbus Response, the response message sent by the server.
- Modbus Confirmation, the response message received on the client side.



The Modbus messaging services (client/server model) are used for real time information exchange between:

- two device applications
- · device application and other device
- HMI/SCADA applications and devices
- a PC and a device program providing on line services

A dedicated header is used on TCP/IP to identify the Modbus Application Data Unit. It is called the MBAP header (Modbus Application Protocol header).



The MBAP header contains the following fields:

Fields	Length	Description	Client	Server
Transaction Identifier	2 bytes	Identification of a Modbus Request/Response transaction	Initialized by the client	Recopied by the server from the received request
Protocol Identifier	2 bytes	0 = Modbus protocol	Initialized by the client	Recopied by the server from the received request
Length	2 bytes	Number of following bytes	Initialized by the client (Request)	Initialized by the server (Response)
Unit Identifier	1 byte	Identification of a remote slave connected on a serial line or on other buses	Initialized by the client	Recopied by the server from the received request

#### **Table of Modbus Functions**

The following table describes in detail the functions supported by Acti 9 Smartlink Ethernet devices:

Function Code	Function Name
01	Read n output or internal bits
02	Read n input bits
03	Read n output or internal bits
05	Write 1 bit
06	Write 1 word
08 <sup>(1)</sup>	Modbus diagnostic data
15	Write n bits
16	Write n words

Function Code	Function Name
43-14 <sup>(2)</sup>	Read identification
43-15 <sup>(3)</sup>	Read the date and time
43-16 <sup>(4)</sup>	Write the date and time
100-4 <sup>(5)</sup>	Read non-adjacent words where n ≤ 100

<sup>&</sup>lt;sup>(1)</sup>For more details, see the appendix describing function 8 (see page 140)

<sup>(2)</sup>For more details, see the appendix describing function 43-14 (see page 142)

<sup>&</sup>lt;sup>(3)</sup>For more details, see the appendix describing function 43-15 (see page 144)

<sup>&</sup>lt;sup>(4)</sup>For more details, see the appendix describing function 43-16 (see page 145)

<sup>(5)</sup>For more details, see the appendix describing function 100-4 (see page 146)

## **Modbus TCP/IP Exception Codes**

#### **Exception Responses**

Exception responses issued by the master or a slave can be the result of data processing errors. One of the following events can occur after a request from the master:

- If the slave receives the request from the master without a communication error and manages the request correctly, it sends back a normal response.
- If the slave does not receive the request from the master due to a communication error, it does not send back a response. The master program ends by applying a time delay condition to the request.
- If the slave receives the request from the master but detects a communication error, it does not send back a response. The master program ends by applying a time delay condition to the request.
- If the slave receives the request from the master without a communication error but cannot manage it (for example, the request consists of reading a register that does not exist), the slave sends back an exception response to inform the master of the nature of the error.

## **Exception Frame**

The slave sends an exception frame to the master to indicate an exception response. An exception response consists of four fields:

Field	Definition	Size
1	Slave number 1 byte	
2	Exception function code 1 byte	
3 Exception code n bytes		n bytes
4	Check	2 byte

## **Managing Modbus Exceptions**

The exception response frame consists of two fields that distinguish it from a normal response frame:

- The exception response's exception function code is the same as the original request function code plus 128 (0x80).
- The exception code depends on the communication error detected by the slave.

The table below describes the exception codes managed by the Acti 9 Smartlink Ethernet device:

Exception Code	Name	Description
01	Illegal function	The function code received in the request is not a permitted action for the slave. It is possible that the slave is in an unsuitable state to process a specific request.
02	Illegal data address	The data address received by the slave is not a permitted address for the slave.
03	Illegal data value	The value of the request data field is not a permitted value for the slave.
04	Slave device failure	The slave is unable to perform a required action due to an unrecoverable error.
06	Slave device busy	The slave is busy processing another command. The master should send the request once the slave is free.

 $\begin{tabular}{ll} \textbf{NOTE:} For more information, a detailed description of the Modbus protocol is available on $\underline{www.modbus.org}$. \end{tabular}$ 

#### **Access to Variables**

A Modbus variable can have the following attributes:

- Read-only
- Read/write
- Write-only

**NOTE:** An attempt to write to a read-only variable generates an exception response.

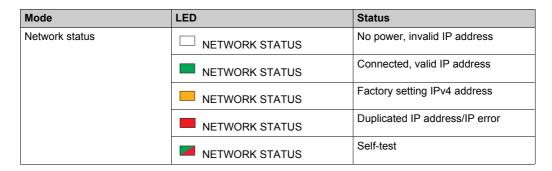
## **Description of Ethernet LEDs**

#### **Ethernet LED Status**



Mode	LED	Status
Ethernet communication	LK/10-100/ACT	10 Mb
	LK/10-100/ACT	100 Mb

## **LED Network Status**



#### Other Protocol or Services

#### Overview

Acti 9 Smartlink Ethernet supports Simple Network Time Protocol (SNTP) and Devices Profile for Web Services (DPWS) protocols.

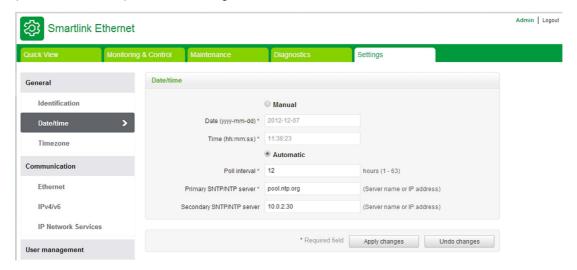
## **Simple Network Time Protocol**

Network Time Protocol (NTP) is a networking protocol for clock synchronization between computer systems over packet-switched, variable-latency data networks.

A less complex implementation of NTP, using the same protocol without the storage of state over extended periods of time is known as the Simple Network Time Protocol. It is used in embedded devices and in applications where high accuracy timing is not required.

When automatic time configuration is selected and NTP servers are configured, the Acti 9 Smartlink Ethernet can communicate with NTP and server to synchonizes its time.

Acti 9 Smartlink Ethernet supports time synchronization with remote server using SNTP. When SNTP is activated, time synchronization from one of the selected time servers can be achieved at every configured interval and also supports Modbus time services Get Date-Time (function code 43-15) and Set Date-Time (function code 43-16). The time is configured in 24-hour format.



NOTE: SNTP feature works only when the device is integrated with the remote server network.

## **Devices Profile for Web Services**

DPWS defines a minimal set of implementation constraints to enable secure Web Service messaging, discovery, description, and eventing on resource-constrained devices.

DPWS is supported on Acti 9 Smartlink Ethernet.

# **Chapter 8**

# **Setting Up Modbus Communication (Gateway Function)**

## What Is in This Chapter?

This chapter contains the following topics:

Торіс	Page
Modbus Master Principle	66
Possible Architecture	68
Setup	69
Gateway Features	70
Web Page Setting Menu	71
Description of Modbus LEDs	72

## **Modbus Master Principle**

#### Overview

The Modbus protocol exchanges data using a request/response mechanism between a master and a slave. The master/slave principle is a type of communication protocol in which a device (the master) controls one or more devices (the slaves). A standard Modbus network consists of one master and up to 31 slaves.

**NOTE:** For more information, a detailed description of the Modbus protocol is available on <a href="https://www.modbus.org">www.modbus.org</a>.

#### **Characteristics of the Master/Slave Principle**

The master/slave principle has the following characteristics:

- Only one master at a time is connected to the network.
- Only the master can launch communication and send requests to slaves.
- The master can address each slave individually using its dedicated address or all slaves simultaneously
  using address 0.
- The slaves can only send responses to the master.
- Slaves cannot launch communication with either the master, or the other slaves.

#### **Master/Slave Communication Modes**

The Modbus protocol can exchange data using 2 communication modes:

- Request/response mode
- Broadcast mode

Acti 9 Smartlink Ethernet support Modbus protocol as master and can support up to eight Modbus slave devices as Acti 9 Smartlink RS485. Each Acti 9 Smartlink RS485 has a Modbus address (1 to 99), and concentrates data from connected devices on its 11 channels (Ti24 interface).

The states and orders for each device connected to Acti 9 Smartlink Ethernet are accessible in registers whose address depends on the digital channels (1 to 7) on which the device is connected.

#### Request/Response Mode

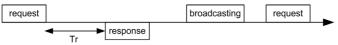
In request/response mode, the master addresses one slave using the slave's dedicated address. The slave processes the request, then responds to the master.

#### **Broadcast Mode**

In broadcast mode, the master addresses all the slaves using address 0. Slaves do not respond to broadcast messages.

#### **Turnaround Time**

The turnaround time Tr is the time between the end of receipt of a request and sending the response.



The typical value of the turnaround time Tr is less than 10 ms with the Modbus protocol.

#### **Data Exchange**

The Modbus protocol uses two data types:

- Bits
- · 16-bit words called registers

Each register has a register number. Each data type (bit or register) has a 16-bit address.

Messages exchanged with the Modbus protocol contain the address of the data to be processed.

#### **Frames**

All frames exchanged with the Modbus protocol are 256 bytes maximum and consist of 4 fields:

Field	Definition	Size	Description
1	Slave number	1 byte	Destination of the request  0: broadcast (all slaves are affected)  1247: unique destination
2	Function code	1 byte	Modbus TCP/IP Function (see page 60)
3	<ul><li>Data</li><li>Sub-function code</li></ul>	n bytes	<ul><li>Request or response data</li><li>Sub-function code</li></ul>
4	Check	2 bytes	CRC16 (to check transmission errors)

#### **Data Format**

The data format is configured as shown below according to Modbus RTU protocol:

Start	Data	Parity	Stop
1 bit	8 bits	1 bit	1 bit

NOTE: The Modbus RTU data format is composed of 11 bits.

Even parity is required, other modes (odd parity, no parity) may be also used.

If no parity is implemented in the Modbus Master, an additional stop bit must be transmitted by the Modbus Master to fill out the character frame to a full 11 bit asynchronous character.

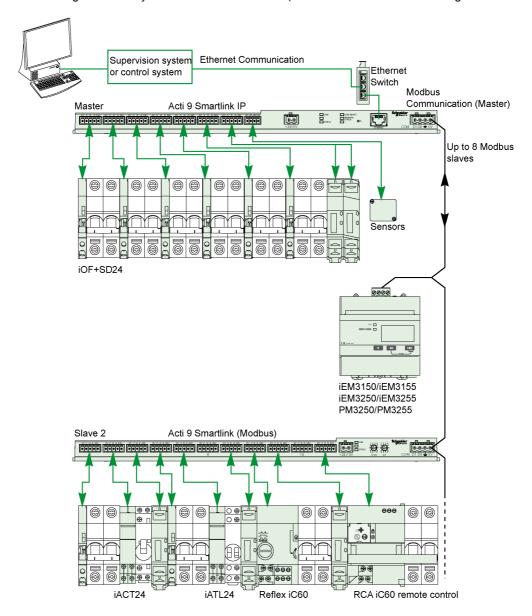
**NOTE:** For more information, a detailed description of the Modbus protocol is available on <a href="https://www.modbus.org">www.modbus.org</a>.

## **Possible Architecture**

## **Description**

Acti 9 Smartlink Ethernet acts as a Modbus master that can be connected to 8 slave devices. The default Modbus address of Acti 9 Smartlink Ethernet is 255.

Address 0 is used to broadcast and address from 248 to 254 is used as reserved address. Slave devices can be assigned from any address between 1 to 247 (the default slave addresses ranges from 1 through 8).



## **Setup**

#### **Overview**

The default gateway ID of Smartlink Ethernet is 255.

The table below provides the communication parameter values:

Settings	Authorized Values	Default Valued
Data rate (in Bauds)	9600 and 19,200	19,200
Parity	<ul> <li>Even and one stop bit</li> <li>Odd and one stop bit</li> <li>No parity (parity bit eliminated), 2 stop bits are needed.</li> </ul>	Even (with 1 stop bit)

**NOTE:** The Modbus network communication speed is same for all serial connections. It is imposed by the lowest communication speed of a slave device. If slave implements auto go, then it obtains Modbus parameters from the master (Acti 9 Smartlink Ethernet) automatically. If slave does not support auto go, then user has to manually configure Modbus parameters as that of the master.

## **Gateway Features**

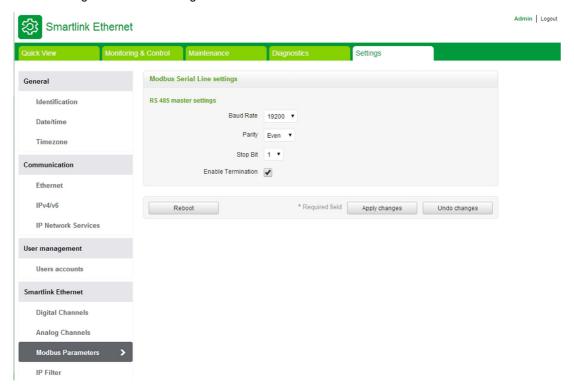
#### **Overview**

Acti 9 Smartlink Ethernet supports Modbus TCP/IP gateway. The gateway features enable Modbus TCP communication from a Modbus TCP master to any Modbus RS485 slave devices connected to it. Acti 9 Smartlink Ethernet provides a simple and transparent interface between Ethernet based networks and field devices. These devices are meters, monitors, protective relays, trip units, motor controls, and other devices that communicate using ModbusTCP/IP.

## Web Page Setting Menu

## **Modbus Settings**

The Modbus parameters can be configured using **Settings** menu. The user can configure Modbus RS485 master settings as shown in the figure below:



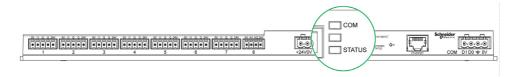
The user can configure the following parameters to set the RS485 master settings:

- Baud Rate
- Parity
- Enable Termination

The **Enable Termination** is selected by default and is embedded in Acti 9 Smartlink Ethernet.

## **Description of Modbus LEDs**

## **Modbus LED Status**



The table below lists the LED status according to the operating mode:

Mode	LEDs	Status
Initialization	COM	COM: Yellow light STATUS: Green light
Start-up	COM	COM: Yellow light during communication with the Modbus serial port; off if there is no Modbus communication STATUS: Alternate green and red light every second
Operation	COM	COM: Yellow light during communication with the Modbus serial port; off if there is no Modbus communication STATUS: Green light
Degraded	COM	COM: Yellow light during communication with the Modbus serial port STATUS: Flashing orange light. Peripheral device problem:  • Short-circuit or overload on the 24 Vdc I/O  • The power supply level is less than 19.2 Vdc
Failure	COM	COM: Yellow light during communication with the Modbus serial port STATUS: Red light (internal problem)

# **Chapter 9**

# **Test**

#### **Acti 9 Smart Test Software**

#### **Overview**

The main purpose of the Acti 9 Smart Test software is to check that all devices are correctly wired and function properly after installation.

The Acti 9 Smart Test software offers a quick test process based on a intuitive Graphical User Interface.

This software has the ability to deal with multiple Acti 9 Smartlink devices at the same time. They can be chained and multiple Acti 9 devices can be connected to the computer using Smartlink Modbus, EGX, and Smartlink Ethernet network. The maximum number of Acti 9 Smartlink devices that can be connected for Smartlink Modbus and EGX network is 10. The maximum number of Acti 9 Smartlink slave devices that can be connected for Smartlink Ethernet network is 8. The slave devices can include Acti 9 Smartlink RS485.

The Acti 9 Smart Test software is used to update the Acti 9 Smartlink firmware.

#### **Main Functions**

The Acti 9 Smart Test software has four main functions:

- Testing the installation
- Editing test reports
- · Generating test reports
- · Recovering a configuration already saved in a Smartlink Ethernet

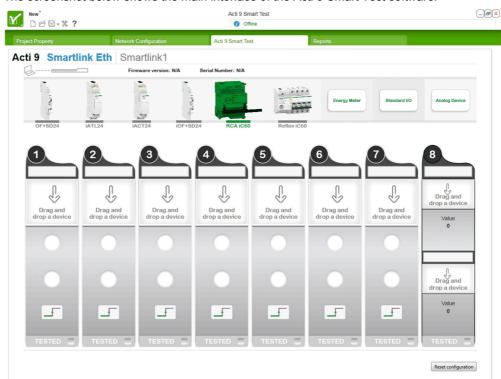
The Acti 9 Smart Test has one complementary function; updating the firmware on Acti 9 Smartlink.

In order to test the installation, the software:

- Tests the communication network (Modbus SL/Modbus TCP-IP).
- Tests the connection and the status of the electrical devices connected to Acti 9 Smartlink.

Also, the software provides the following reports:

- List of tested devices (.pdf file)
- Acti 9 Smartlink channels assignment (.dxf file)



The screenshot below shows the main interface of the Acti 9 Smart Test software.

# **Downloading and Installation**

Acti 9 Smart Test software can be downloaded from Schneider Electric website.

Acti 9 Smart Test software is available in two versions:

- Full version including Microsoft .NET Framework
- Light version without Microsoft .NET Framework

We recommend to install the full version unless Microsoft .NET Framework (3.5 or later) is already installed on the PC.

The table below describes the procedure for installing the Acti 9 Smart Test software:

Step	Description	
1	Go to the Schneider Electric website: <u>www.schneider-electric.com</u> or Schneider Electric country website.	
2	In the search field, enter <b>SmartTest</b> without space character.	
3	Select "Acti 9 Smart Test Software 2.0.0 ( with .NET Framework )" or "Acti 9 Smart Test Software 2.0.0 ( without .NET Framework )".	
4	Download the Acti 9 Smart Test software.	
5	Install the Acti 9 Smart Test software.	
6	Acti 9 Smart Test user guide can be downloaded from Schneider Electric web site.  In the search field, enter:  DOCA0029EN for English user guide,  DOCA0029ES for Spanish user guide,  DOCA0029FR for French user guide,  DOCA0029DE for German user guide,  DOCA0029IT for Italian user guide,  DOCA0029NL for Dutch user guide,  DOCA0029PT for Portuguese user guide,  DOCA0029RU for Russian user guide,  DOCA0029ZH for Chinese user guide,  Select the user manual.  Download the user guide.	

Acti 9 Smart Test software is also available in the Power Launcher library.

# Registration

Acti 9 Smart Test software requires a user registration.

The software can be started 10 times before online registration.

The software is always free of charge even after online registration.

# **Chapter 10**Web Page

# What Is in This Chapter?

This chapter contains the following topics:

Topic	Page
Overview	78
Global Content Description	79
Quick View Page	80
Monitoring and Control Page	82
Maintenance Page	85
Diagnostics Page	87
Settings Page	91

#### Overview

Acti 9 Smartlink Ethernet has an embedded web server and user can access to web pages with PC or mobile tool like laptop (see page 53).

The web pages can be used for multiple operations:

- Setting of Ethernet parameters to connect Acti 9 Smartlink Ethernet on the network.
- Diagnosis of exchanges on Ethernet network.
- Monitoring or control of the devices connected to Acti 9 Smartlink, Acti 9 Smartlink Modbus or energy meter IEM3000 and power meter PM3000.
- Configuration of the devices connected.
- Adding or removing Acti 9 Smartlink and devices connected to Acti 9 Smartlink.

The last features can be useful during installation or maintenance of the electrical panel and also during operation.

The monitoring and control operation are accessible only if Acti 9 Smartlink Ethernet and Acti 9 Smartlink Modbus have been configured by Smart Test tool or by **Configuration** menu in web page.

Web pages are accessible to the following three categories of user:

- Administrator, can access all information, control the connected devices, and modify the parameters in Settings menu
- User, can access only monitoring and control of connected devices
- Guest, can access only monitoring of connected devices

The scope of products supported in web page are:

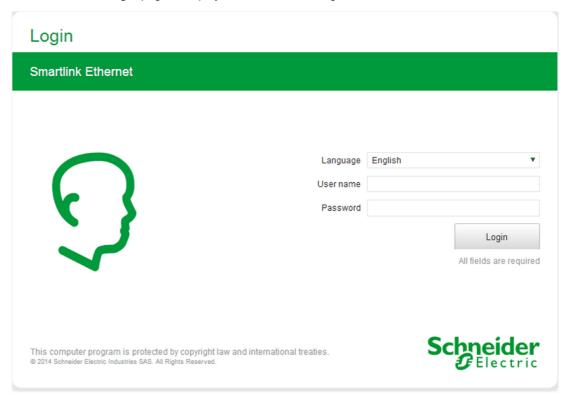
- Smartlink Ethernet
- Smartlink Modbus slave connected to Smartlink Ethernet
- Energy meter IEM3000, power meter PM3000, Modbus slave connected to Smartlink Ethernet

The web page can support one Acti 9 Smartlink Ethernet and up to eight Modbus slaves.

# **Global Content Description**

#### **Login Page**

The **Login** page is used to enter the user credentials and select the preferred language to access Acti 9 Smartlink Ethernet web pages. When the user connects to the Acti 9 Smartlink Ethernet through a web browser, the **Login** page is displayed as shown in the figure below.



Enter the following details in the Login page:

- Language
- User name
- Password

Enter the user name and password to access the web pages related to Acti 9 Smartlink Ethernet, connected slaves, and auxiliaries. The default user name and password is **admin** to access the web page for the first time. The user can modify the user name and passowrd in the **Settings** menu, **User Management** chapter. The user can select the language in the **Login** page, so that all the pages are displayed in the selected language.

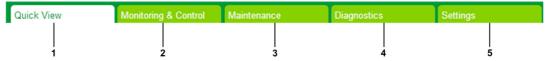
The top right corner of all the web pages displays the following information:

- User name
- Language
- Logout

The **Logout** link is used to logout of the Acti 9 Smartlink Ethernet web page.

# **Quick View Page**

# **Web Page Organization**



- 1 The alarm for trip on circuit breaker or the alarm for default on communication device is the default value. The complementary information can be selected from the **Settings** menu to display in the **Quick View** menu.
- 2 Information is classified based on function and product; digital channels, analog channels, and energy meter
- 3 Smartlink upgrade
- 4 Information is classified based on product and channel; Ethernet diagnosis
- 5 Configuration of Ethernet parameter, Modbus parameter, quick view page, communication product, and auxiliary devices

# **Description**

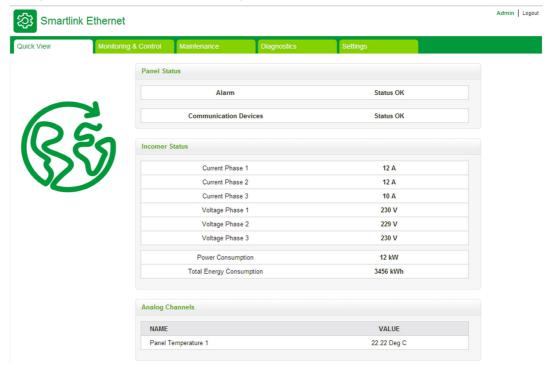
The user will be redirected to **Quick View** page after logging to the Acti 9 Smartlink Ethernet. This page gives an overview of the entire system.

The Quick View page displays the status of the alarms and the missing communication devices.

This also displays the following information if selected in the **Settings** menu:

- Value of the incomer meter
- Status of the digital channels
- Value of the analog channel
- Value of the connected pulse meter

The figure below shows the Quick View page:



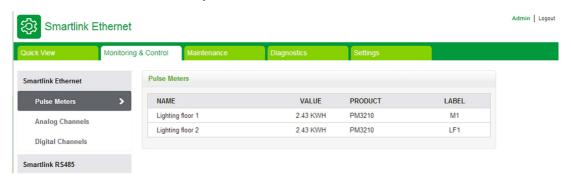
The table below gives the functional description of the main elements of **Quick View** page:

Function	Description	
Alarm Status	Displays name and number of the tripped breakers and the circuit breaker in default.	
<b>Communication Devices</b>	Displays the missing IEM3000 or PM3000 connected to communication devices.	
Incomer Status	Displays the value for the incoming meter (connected to Acti 9 Smartlink Ethernet through Modbus) if selected in the <b>Incomer Selection</b> page of the <b>Settings</b> menu. This provides the values of power, energy, voltage and current on each phase. If there is no data from the device, then incomer status displays the null (0) value for that device.	
Analog Channels	Displays the value of the analog channels if selected from <b>Analog Channels</b> page of the <b>Settings</b> menu.	
Digital Channels	Displays the status of the digital channels if selected from <b>Digital Channels</b> page of the <b>Settings</b> menu. The status of a digital channel can be open, closed, tripped, disconnected, or error.	
Pulse Meter	Displays the value of the pulse meter if selected in the <b>Settings</b> menu.	

# **Monitoring and Control Page**

# **Description**

The **Monitoring & Control** menu is used to monitor and control Acti 9 Smartlink Ethernet, Acti 9 Smartlink RS485, and auxiliary devices.

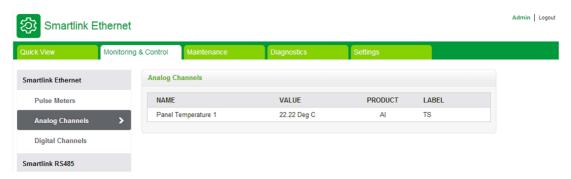


The **Monitoring & Control** menu, **Maintenance** menu, **Diagnostics** menu, and the **Settings** menu consists of two main areas:

- · Function list or device list
- Dashboard

Area	Description
Function list or device list	List of functions or lists the devices connected to Acti 9 Smartlink Ethernet, Acti 9 Smartlink RS485, energy meter IEM3000 or power meter PM3000 (Modbus slaves), and auxiliary devices.
Dashboard	Displays the general characteristics of the function depending on the selected device from the function list or device list area.

# **Smartlink Ethernet**

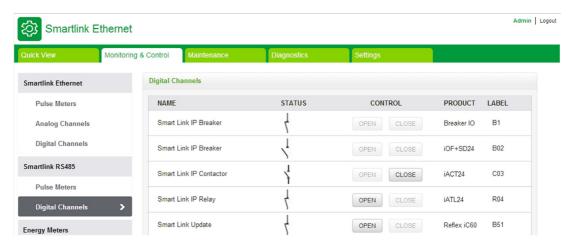


The **Smartlink Ethernet** lists the devices and the characteristics of the devices as described in the following table:

Device List	Description
Pulse Meters	Provides information about the energy measurements from the meters connected to Acti 9 Smartlink Ethernet (pulse output).
Analog Channels	Displays the sensors connected to Acti 9 Smartlink Ethernet. The following information is displayed for each device:  Name Value Product Label

Device List	Description
Digital Channels	Displays the information of devices like breakers, relays, and contactors connected to Acti 9 Smartlink Ethernet.  The following information is displayed for each device:  Name Status Control Product Label
	The status of the device can be one of the following:  Open Closed Disconnected Tripped The device can be opened or closed using the control buttons (control is only possible for Administrator and User accounts). Click <b>Open</b> to open the corresponding device and click <b>Close</b> to close the device.

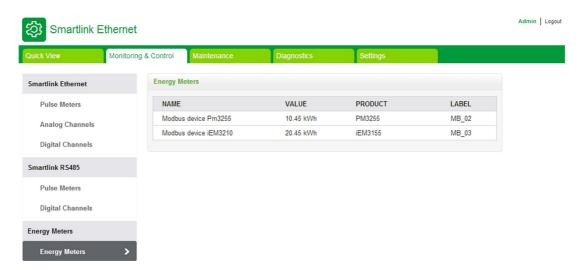
# **Smartlink RS485**



The Smartlink RS485 lists the devices and the characteristics of the devices as described in the following table:

Device List	Description
Pulse Meters	Provides information about the energy measurements from the meters connected to Acti 9 Smartlink RS485 (from 1 to 8 devices).
Digital Channels	Displays the information of devices like breakers, relays, and contactors connected to Acti 9 Smartlink RS485.  The following information is displayed for each device:  Name Status Control Product Label  The status of the device can be one of the following: Open Closed Disconnected Tripped  The device can be opened or closed using the control buttons (control is only possible for Administrator and User accounts). Click Open to open the contacts of the corresponding device and click Close to close the contacts of the corresponding device.

# **Energy Meters**



The **Energy Meters** lists the devices and the characteristics of the devices as described in the following table:

Device List	Description
Energy	Displays the energy meters (IEM3000 or PM3000 Modbus slaves) connected to Acti 9 Smartlink Ethernet through Modbus.  The following information is displayed for each device:  Name  Value  Product  Label

# **Maintenance Page**

# **Description**

The **Maintenance** page displays the firmware version and web page version of the device. This page is used to upgrade the firmware version of the application.



#### **Device Information**

The **Device Information** page displays the following firmware details:

<b>Device Information</b>	Description
Serial Number Displays the serial number of Acti 9 Smartlink Ethernet.	
Firmware Version	Displays the currently installed firmware version of Acti 9 Smartlink Ethernet.
Webpage Version	Displays the currently installed web page version of Acti 9 Smartlink Ethernet.

# **Upgrade**

# **NOTICE**

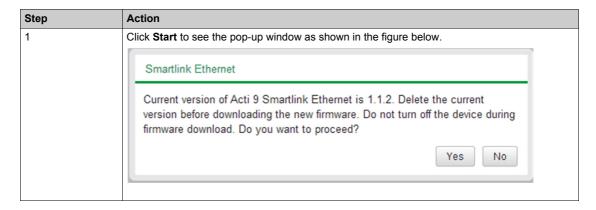
# **RISK OF DAMAGING THE EQUIPMENT**

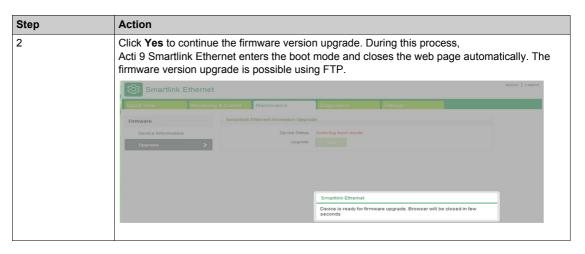
Ensure to operate the Acti 9 Smartlink Ethernet firmware upgrade only by a maintenance person.

Failure to follow these instructions can result in equipment damage.



The **Upgrade** page displays the device status of Acti 9 Smartlink Ethernet. This page is used to upgrade the firmware version of Acti 9 Smartlink Ethernet as described in the following table:



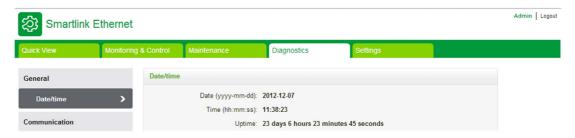


Only Administrator can access the Upgrade page.

# **Diagnostics Page**

# **Description**

The **Diagnostics** menu is used to perform self diagnostics of the system.



#### Date/Time

The **Date/Time** page displays the following information:

Parameters	Description	
Date	Displays the current date in the format YYYY-MM-DD.	
Time	Displays the current in the local time zone.	
Uptime	Displays the elapsed time since the last start of the device.	

#### **Ethernet Communication**

The **Ethernet** page displays the statistics information of Ethernet network.

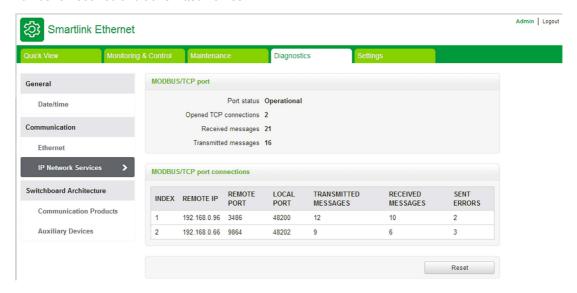


	Function Name	Description
Ethernet global statistics	Frames received	Displays the number of frames received from all the Ethernet ports.
	Frames transmitted	Displays the number of frames transmitted from all the Ethernet ports.
Ethernet port statistics	Link speed	Displays link speed on Ethernet port.
	Duplex mode	Displays the communication mode of the Ethernet port. It can be half duplex or full duplex.
	Frames received	Displays the number of frames received from the specific Ethernet port.
	Frames transmitted	Displays the number of frames transmitted from the specific Ethernet port.

Click Reset button to clear the Ethernet frames counter.

#### **IP Network Services**

The **IP Network Services** page displays Modbus/TCP port information, number of active connections, and number of recevied and transmitted frames.

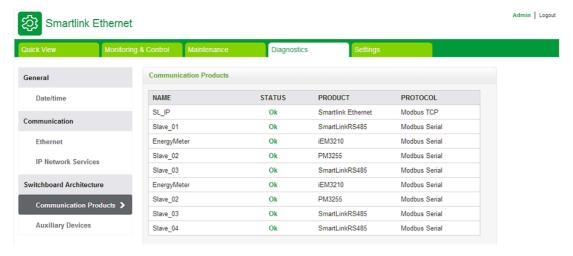


	Function Name	Description
Modbus/TCP port	Port status	Displays the current status of the Modbus/TCP port.
	Opened TCP connections	Displays the number of established Modbus/TCP connections.
	Received messages	Displays the counter of received Modbus/TCP messages.
	Transmitted messages	Displays the counter of transmitted Modbus/TCP messages.
Modbus/TCP port connections		Displays the statistics of open Modbus/TCP connections.

Click Reset button to clear the Modbus/TCP counter.

#### **Communication Products**

The **Communication Products** page displays the communication device status (Acti 9 Smartlink Ethernet and Acti 9 Smartlink RS485 connected through Modbus).



The communication device status displays the following information:

- Name
- Status
- Product
- Protocol

If the device is communicating properly, the status is displayed as **Ok**. If the device is not communicating properly, the status is displayed as **Communication Error**. If input/output channel do not have 24 V, then the status is displayed as **24 V Channel Error** and this status is displayed only for Acti 9 Smartlink Ethernet.

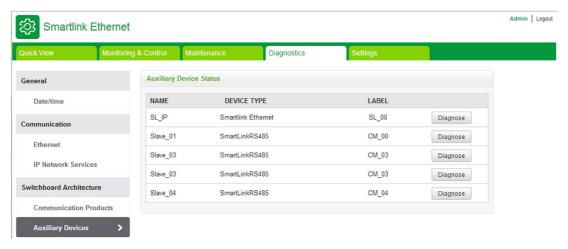
#### **Auxiliary Devices**

The **Auxiliary Devices** page displays the list of communication device.

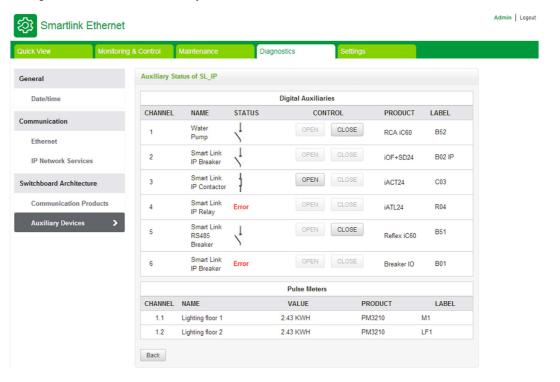
Click the **Diagnose** button to display the auxiliary devices connected on the selected communication device.

The auxiliary device status displays the following information for each connected device:

- Name
- Device Type
- Label
- Diagnose



The figure below shows the auxiliary devices connected to the communication device:



The diagnose page displays the following information for Digital Auxiliaries:

Parameter	Description	
Channel	Displays the channel number.	
Name	Displays the name of the auxiliary device.	
Status	Displays one of the following status for an auxiliary device:  Open Close Tripped Disconnected Error	
Control	Click the <b>Open</b> or <b>Close</b> button of an auxiliary device. A pop-up dialog with a message, success or failure, is opened to confirm the control operation.  Only Administrator account or user account can perform the <b>Open</b> or <b>Close</b> action.	
Product	Displays the product of the auxiliary device.	
Label	Displays the label of the auxiliary device.	

The diagnose page also displays the value of the pulse meters. Click **Back** button to go back to the auxiliary device page.

# **Settings Page**

#### **Description**

The **Settings** menu is used to configure or edit the following parameters:

- Configure device identification
- Set date, time, and timezone
- Configure Ethernet, IPv4/Ipv6, and IP network services
- · Configure the user profiles
- Configure digital channels and analog channels of Acti 9 Smartlink Ethernet
- Configure Modbus parameters
- Configure IP address to have write access
- Configure the Modbus slave devices connected to Acti 9 Smartlink Ethernet and associated auxiliary devices connected to digital channels
- · Configure incomer meter

The configuration of the parameters is accessible to only Administrator accounts.

#### **Identification Page**

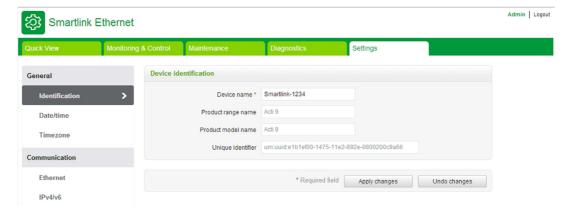
The **Identification** page is used to edit the device name and it displays the following parameters:

Parameters	Description	
Device name	Displays the name of the particular device used by communication services to identify the device.	
Product range name	Displays the product range name of the device.	
Product model name	Displays the product model name of the device.	
Unique identifier	Displays the identifier used by communication protocols.	

The user can edit only the **Device name**. The **Device name** is same as the name displayed in Windows 7 explorer. The other parameters in this page cannot be edited, as these are read-only parameters.

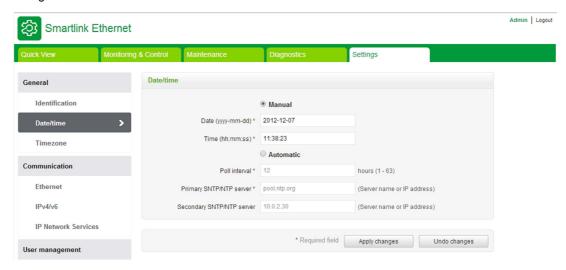
Click Apply Changes to save the changes. Click Undo Changes to revert the changes.

**NOTE:** Once you click apply changes, you cannot undo the changes. You can click undo changes only before saving the changes.



#### **Date/Time Page**

The **Date/time** page is used to set date and time either in manual mode or in automatic mode as shown in the figure below:



**NOTE:** After every power cycle, the device will reset to a default value of date and time. The default date and time value is 2000-1-1, 00:00:00.

Follow the procedure below to configure the date and time in Manual mode:

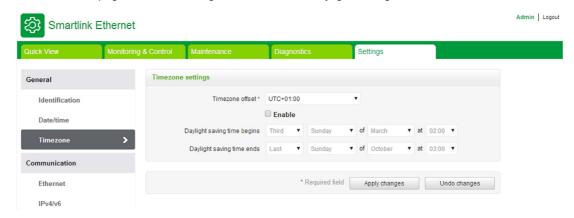
Step	Action	
1	Select Manual.	
2	Type the <b>Date</b> to be set in the format <b>yyyy-mm-dd</b> .	
3	Type the <b>Time</b> in the format <b>hh:mm:sec</b> .	
Click Apply Changes to save the settings. If you do not want to save the changes, click Undo Ch		

In automatic mode, the Acti 9 Smartlink Ethernet receives date and time from SNTP server after every poll interval time. Follow the procedure below to configure date and time in **Automatic** mode:

Step	Action	
1	Select Automatic.	
2	Type the value for <b>Poll interval</b> in hours that ranges from 1 through 63. The default value of poll interval is 1	
3	Type the primary server name or IP address for <b>Primary SNTP/NTP server</b> parameter. The primary server can be:  IPv4 address IPv6 address Domain name	
4	Type the secondary server name or IP address for <b>Secondary SNTP/NTP server</b> parameter. This is an optional parameter.	
5	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

#### **Timezone Page**

The **Timezone** page is used to configure the offset and daylight saving time for the selected timezone.

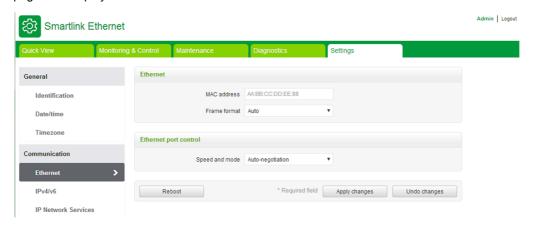


Follow the procedure below to configure timezone settings:

Step	Action	
1	Select the offset value used by the local time zone from the <b>Timezone offset</b> list.	
2	Select the <b>Enable</b> check box to configure the daylight time saving settings. The <b>Enable</b> check box is not selected by default.	
3 Select the day, month, and time to configure the start time of daylight saving time from the re <b>Daylight saving time begins</b> list.		
4	Select the day, month, and time to configure the end time of daylight saving time from the <b>Daylight savi time ends</b> list.	
5	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

# **Ethernet Page**

The Ethernet page is used to configure the frame format and speed and mode of the Ethernet port. This page also displays the MAC address of the Ethernet network.

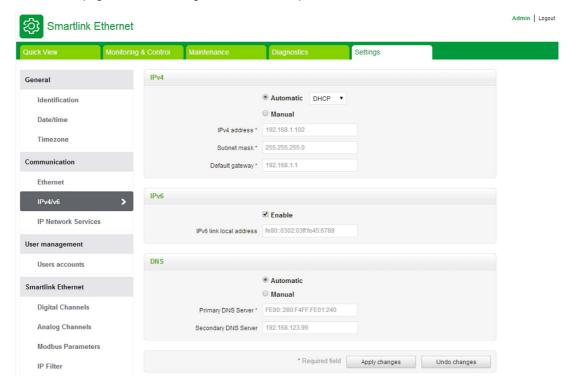


The following procedure describes to configure Ethernet parameters:

Step	Action
1	Select the Ethernet frame format from the <b>Frame format</b> list. It can be <b>Ethernet II</b> , <b>802.3</b> , or <b>Auto</b> . The default value of the frame format is <b>Auto</b> .
2	Select the value for speed and mode of the Ethernet port from the <b>Speed and mode</b> list.  The value of speed an dmode can be one of the following:  10 Mbps - Half duplex 10 Mbps - Full duplex 100 Mbps - Full duplex Auto-negotiation
	The default value is <b>Auto-negotiation</b> .
3	Click <b>Apply Changes</b> and then click <b>Reboot</b> to automatically restart the device to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .

#### IPv4/v6 Page

The IPv4/v6 page is used to configure IPv4 and IPv6 parameters.



IPv4 parameters can be set either in manual mode or in automatic mode. To configure IPv4 parameter in automatic mode, click **Automatic** and select the type of protocol (DHCP or BOOTP) from the list. The default type is **DHCP** protocol.

DHCP mode is used to acquire the IPv4 address from the DHCP server in the network to which Acti 9 Smartlink Ethernet is connected. BOOTP mode is used to acquire the IPv4 address if DHCP server is not present in the network. and a BOOTP server is configured in the network to assign the IPv4 address.

Follow the procedure below to configure IPv4 parameters in manual mode:

Step	Action	
1	Select Manual.	
2	Type the IPv4 Address of the device.	
3 Type the <b>Subnet Mask</b> of the device.		
4	Type the <b>Default Gateway</b> of the device.	
5	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

Follow the procedure below to configure IPv6 parameters:

Step	Action	
1	Select the <b>Enable</b> check box to enable the IPv6 service. The <b>Enable</b> check box is selected by default.	
2	Displays the value of the IPv6 link local address. The user cannot modify this parameter.	
3	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

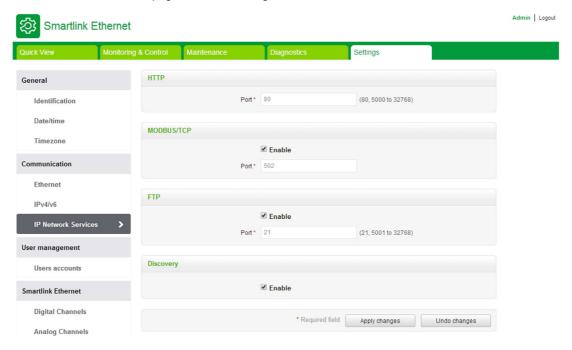
Acti 9 Smartlink Ethernet can acquire the domain name automatically or user can set the DNS server address manually. Click **Automatic** to acquire the DNS server automatically from the network.

Follow the procedure below to configure DNS parameters in manual mode:

Step	Action	
1	Click Manual.	
2	Type the <b>Primary DNS Server</b> of the device.	
3 Type the <b>Secondary DNS Server</b> of the device.		
4	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

# **IP Network Services Page**

The IP network Services page is used to configure the network services.



Acti 9 Smartlink Ethernet supports HTTP, Modbus/TCP, FTP, and discovery protocols and services.

Displays the value of the HTTP **Port**. The default value of the port number is 80.

Follow the procedure below to configure Modbus/TCP parameters:

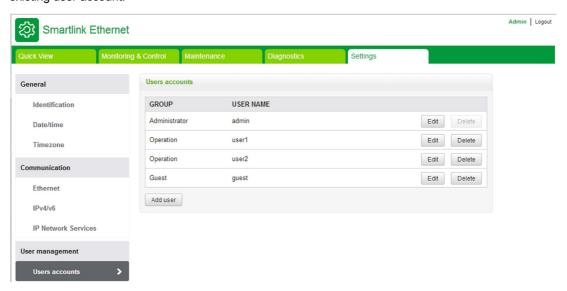
Step	Action		
1	Select the <b>Enable</b> check box to enable the Modbus/TCP service. The <b>Enable</b> check box is selected by default.		
2	Displays the port number of the Modbus/TCP network. The default value is 502.		
3	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .		

Follow the procedure below to configure discovery services:

	Step Action	
1 Select the <b>Enable</b> check box to enable the discovery service. The <b>Enable</b> check box is selected		Select the <b>Enable</b> check box to enable the discovery service. The <b>Enable</b> check box is selected by default.
	2	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .

#### **Users Accounts Page**

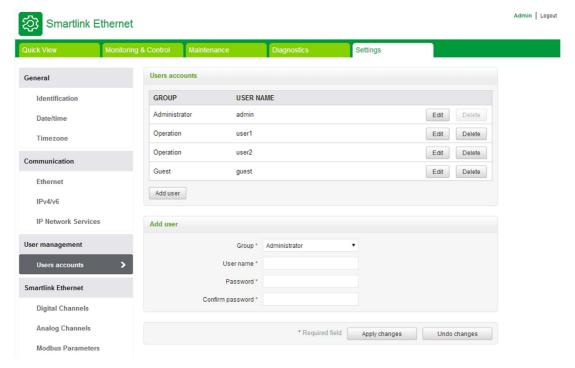
The **User Management** chapter is used to manage the user profiles. The **Users Accounts** page displays the existing user accounts. This page is used to add a new user account and edit the password of the existing user account.



The following table lists the three types of user account supported by Acti 9 Smartlink Ethernet and their access rights:

User Accounts	Access	Username	Password
Administrator	<ul> <li>Edit parameters in Settings menu</li> <li>Monitor and control of the devices</li> <li>View all menus</li> </ul>	admin	admin
User	<ul><li>Monitor and control of the devices</li><li>View all menus</li></ul>	user	user
Guest	View all menus	guest	guest

Administrator account is the first level of access to the web page by default. The number of user accounts at Administrator level is up to 1. The number of user accounts at User level is up to 10.



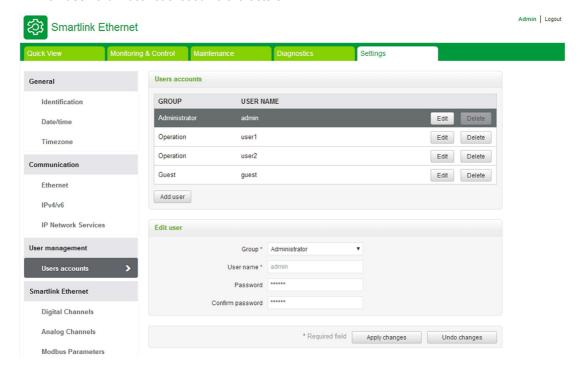
Follow the procedure below to add a new user profile:

	Step	Action	
	1	Click Add.	
2 Type <b>Username</b> and <b>Password</b> for a user.		Type <b>Username</b> and <b>Password</b> for a user.	
Ī	Click Apply Changes to save the settings. If you do not want to save the changes, click Undo Cha		

By default, only one Administrator account and one user account is available.

The **Username** and **Password** must meet the following criterias:

- The **Username** must have minimum of 4 characters.
- The **Username** must not exceed 16 characters.
- The Password must contain minimum of 8 characters with 1 special character, 1 number, and 1 alphabet in upper case.
- The Password must not exceed 16 characters.



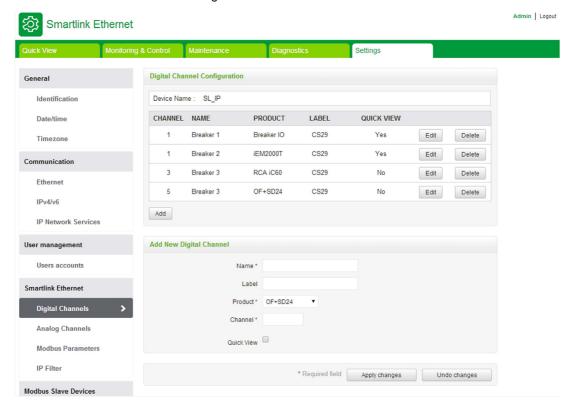
Follow the procedure below to edit the details of an existing user profile:

Step	Action	
1	Select the user account from the <b>Users</b> list and click <b>Edit</b> .	
2	Edit the password for the selected user account.	
3	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

Click **Delete** to delete the user profile from web page. The user profile with Admin account cannot be deleted.

# **Digital Channels Page**

The **Digital Channels** page displays the list of connected I/O devices. This page is used to add new I/O device and to edit or delete an existing I/O device on Acti 9 Smartlink Ethernet.



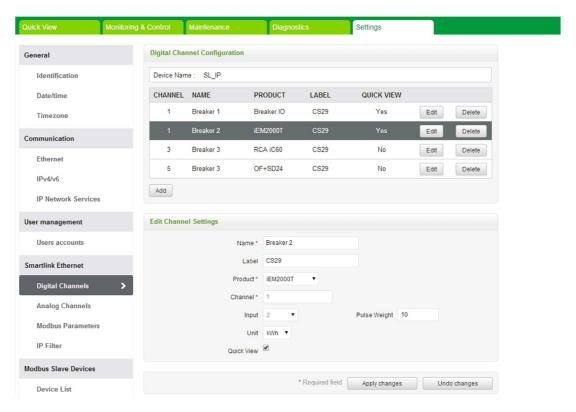
Follow the procedure below to configure the digital channels:

Step	Action	
1	Click <b>Add</b> to add a new digital channel.	
2	Type the <b>Name</b> of a digital channel.	
3	Type the <b>Label</b> of a digital channel. This is an optional parameter.	
4	Select the name of the product from the <b>Product</b> list.	
5	Type the <b>Channel</b> number of a digital channel.	
6	Select the Quick View check box to display the digital channel in the Quick View page.	
7	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

Follow the procedure below to configure the pulse meters:

Step	Action	
1	Click <b>Add</b> to add a new digital channel.	
2	Type the <b>Name</b> of a digital channel.	
3	Type the <b>Label</b> of a digital channel. This is an optional parameter.	
4	Select the pulse meter from the <b>Product</b> list.	
5	Type the <b>Channel</b> number of a digital channel.	
6	Select the value for the <b>Input</b> .	
7	Type the <b>Pulse Weight</b> of the pulse meter.	
	NOTE: The pulse weight is measured with respect to watt-hour (Wh).	
8	Select the <b>Unit</b> of the pulse weight for the type of consumption.	
9	Select the Quick View check box to display the digital channel in the Quick View page.	
10	Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo Changes</b> .	

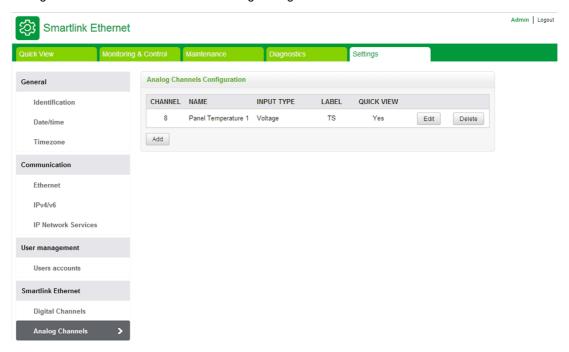
**NOTE:** The user has to configure the value of the pulse weight as Act 9 Smartlink Ethernet does not read the default pulse weight values (on web page, the value is always displayed as 10) from Smartlink devices.



Click **Edit** to modify the device details. Click **Delete** to remove the digital channel from web page.

# **Analog Channels Page**

The **Analog Channels** page displays the list of connected analog devices. This page is used to add new analog device and to edit or delete an existing analog device.



Follow the procedure below to configure the analog channels:

Step	Action
1	Click <b>Add</b> to add a new analog channel.
2	Select input 1 or 2 from the list.
3	Type the <b>Name</b> of a analog channel.
4	Type the <b>Label</b> of a analog channel. This is an optional parameter.

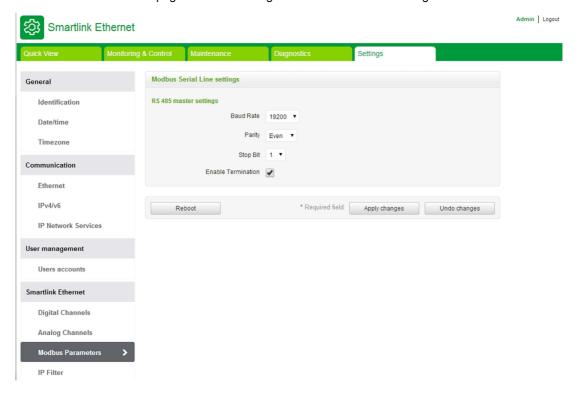
Step	Action	
5	Select the product from the <b>Input Type</b> list.	
6	Select either input 1 or 2 from the <b>Input</b> list. Specify the <b>Sensor Range Min</b> and <b>Sensor Range Max</b> values. Select the unit of temperature from the <b>Unit</b> list.	
7	Select the Quick View check box to display the analog channel in the QuickView page.	
8 Click <b>Apply Changes</b> to save the settings. If you do not want to save the changes, click <b>Undo</b>		

Click **Edit** to modify the device details. Click **Delete** to remove the digital channel from the web page.

**NOTE:** The device flags a conflict status in case the sensor type is wrongly configured.

# **Modbus Parameters Page**

The Modbus Parameters page is used to configure Modbus serial line settings.

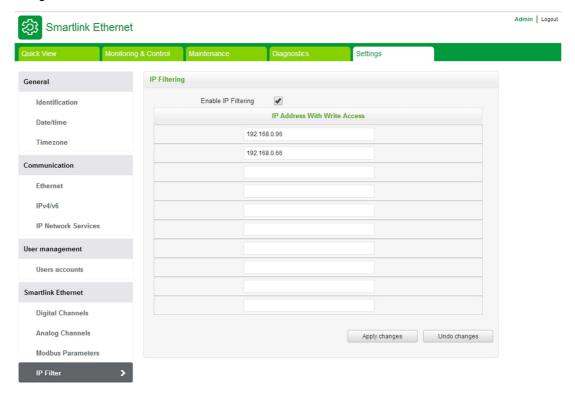


Follow the procedure below to configure the Modbus parameters:

Step	Action	
1	Select the baud rate from the <b>Baud Rate</b> list. The default value is 19,200.	
2	Select the type of parity from the <b>Parity</b> list. The default value is <b>Even</b> .	
3	Select the <b>Enable Termination</b> check box, if Acti 9 Smartlink Ethernet is at the beginning or end of RS485 network. The <b>Enable Termination</b> check box is enabled by default.	
4	Click <b>Apply Changes</b> and then click <b>Reboot</b> to save the settings. If you do not want to save the click <b>Undo Changes</b> .	

# **IP Filter Page**

IP filtering is a security feature that lists the IP addresses from which the communication can be accepted (Ethernet client). This function is used only with Ethernet static addressing mode. This page is used to configure the IP address in order to enable write access.



Follow the procedure below to configure the IP address to enable write access:

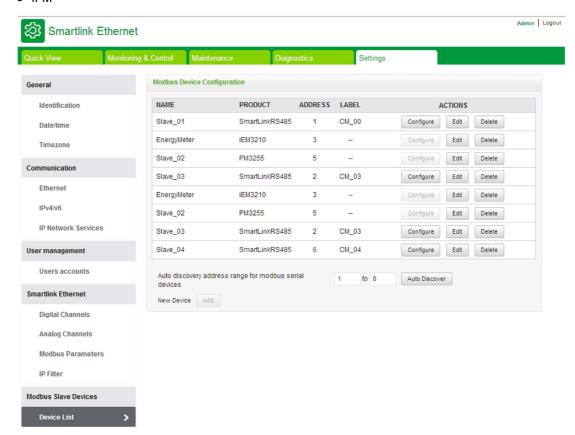
Step	Action	
1	Select the <b>Enable IP Filtering</b> check box to enable write access only for the listed IP address.	
2	Type the IP addresses in the <b>IP Address With Write Access</b> area. A maximum of 10 IP address can be added. The IP address added will have a write access.	
3 Click Apply Changes to save the settings. If you do not want to save the changes, click Undo Ch		

#### **Device List Page**

The **Device List** page is used to view and configure the **Modbus** slaves connected to Acti 9 Smartlink Ethernet. The devices can be discovered automatically with this page.

Web page supports the following devices:

- Smartlink RS485
- PM3250
- PM3255
- IEM3150
- IEM3155
- IEM3250
- IEM3255
- IFM



The user can add devices to Acti 9 Smartlink Ethernet either in manual mode or by using auto discover feature.

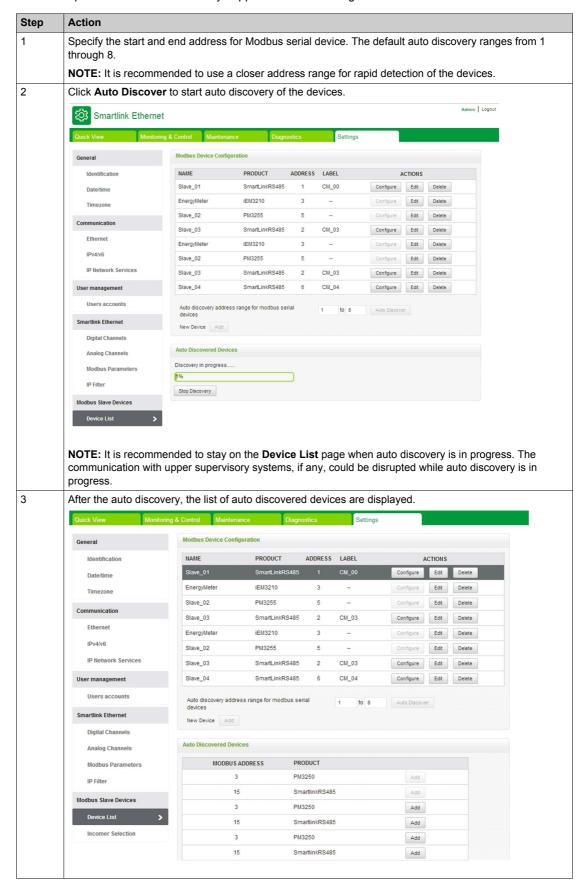
Follow the procedure below to add the devices in manual mode to Acti 9 Smartlink Ethernet:

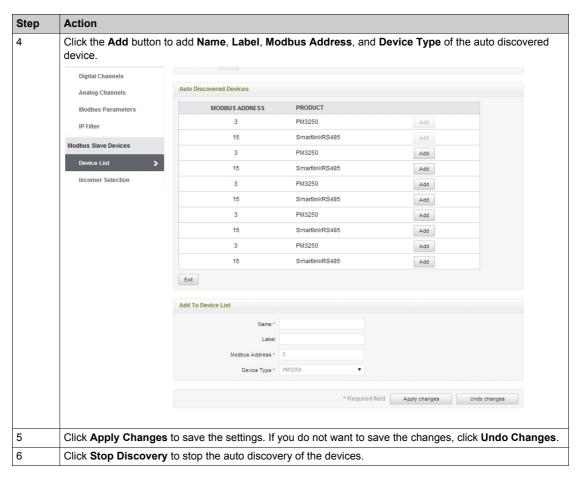
Step	Action
1	Click <b>Add</b> to add Modbus slaves to Acti 9 Smartlink Ethernet.
2	Type the <b>Name</b> of the device to be added.
3	Type the <b>Label</b> for the device.
4	Select the product type from the <b>Device Type</b> list.
5	Type the <b>Modbus Address</b> of the device to be added.
6	Click Apply Changes to save the settings. If you do not want to save the changes, click Undo Changes.

#### Auto Discovery Feature

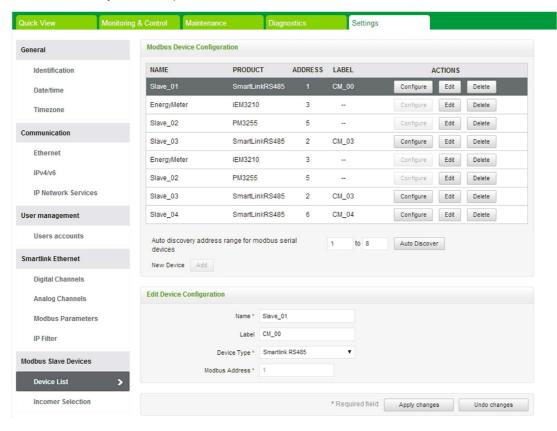
If you need to connect only Acti 9 Smartlink RS485, select the Modbus address between 1 and 8, and click the **Auto Discover** button to automatically detect the devices.

Follow the procedure below to add any supported devices using auto discover feature:



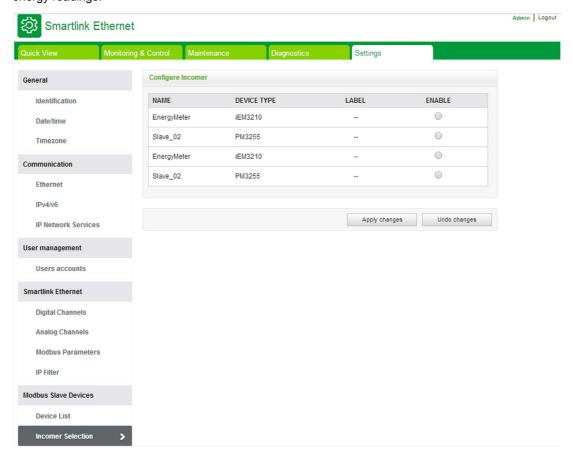


Click Edit to modify the device parameters. Click Delete to delete the selected device from the device list.



# **Incomer Selection Page**

The **Incomer Selection** page displays the list of energy meter or power meter and is used to select any one device as incomer. This incomer meter is displayed in the **Quick View** page with voltage, current & energy readings.



Click **Apply Changes** to save the settings. If you do not want to save the changes, click **Undo Changes**.

# **Chapter 11**

# **Tables of Modbus Registers**

# What Is in This Chapter?

This chapter contains the following sections:

Section	Topic	Page
11.1	General Description of Modbus Tables	108
11.2	Summary and Detailed Modbus Tables	114
11.3	Modbus Tables for Connected Products	127

# Section 11.1

# **General Description of Modbus Tables**

# What Is in This Section?

This section contains the following topics:

Topic	Page
Overview	109
Modbus Table Format and Data Types	110
Global Modbus Address Table	113

#### Overview

#### Overview

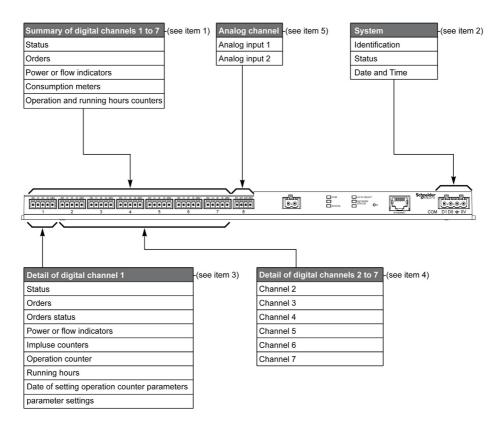
All the Modbus tables in the Acti 9 Smartlink Ethernet device have been designed to minimize the number of Modbus requests that the master system needs to send in order to collect the data prepared by Acti 9 Smartlink Ethernet.

The Modbus tables in the Acti 9 Smartlink Ethernet device are compact and summaries of all the data are collected on the seven digital channels and one analog channel of the Acti 9 Smartlink Ethernet device.

The Modbus tables in the Acti 9 Smartlink Ethernet device are described in:

- · The section presenting:
  - The overall list of Acti 9 Smartlink Ethernet device address zones (see page 113)
  - The summary of channel 1 to 7 address zones (see page 117)
  - The details of channel 1 to 7 address zones (see page 120)
  - Analog inputs (see page 125)
- The section presenting the address zones for each type of device that can be connected to
  Acti 9 Smartlink Ethernet: iOF+SD24, OF+SD24, iACT24, iATL24, RCA iC60, Reflex iC60, iEM2000T,
  analog sensor, meter, contactor, and impulse relay (see page 127)
- The section presenting the address zones for each type of data (status, orders, measurements, and parameter settings) with a description of the summary zones and a description of the detailed data zones for each channel (see page 114).

#### General Organization of Modbus Tables in Acti 9 Smartlink Ethernet Devices



Item	Description	Link	
1	Channel summary data	(see page 117)	
2	System data independent of the channel	(see page 115)	
3	Data for channel 1 Devices that can be connected to channel 1	(see page 120) (see page 127)	
4	Data for channel 2 to 7 Devices that can be connected to channel 2 to 7	(see page 120) (see page 127)	
5	Analog inputs 1 to 2	(see page 125)	

# **Modbus Table Format and Data Types**

#### **Table Formats**

Register tables have the following columns:

Address	No.	RW	X	Unit	Type	Range	Fault	Svd	Function	Description
									Code	

Designation	Description
Address	16-bit register address that allows the user to access the variable. The address is expressed in decimal notation.  Modbus Address: The list of Modbus addresses, defined by the Modbus protocol, starts at 0. The detailed tables in subsequent chapters of this manual give the Modbus addresses.  If the programmable controller (master) refers to the data model addresses, the addresses to be supplied to this controller must meet the following rule: Data model addresses, the addresses to be supplied to this controller (Modbus master) refers to the procotol addresses, the addresses to be supplied to this controller must be the Modbus addresses.
No.	Number of 16-bit registers that need to be read/written to access the complete information.
RW	Whether the register is read only (R) or read-write (RW).
X	<ul> <li>Scale factor:</li> <li>Scale "X1" means that the value of the register is the right one with the unit indicated.</li> <li>A scale of 10 means that the register contains the value multiplied by 10. The actual value is therefore the value of the register divided by 10.</li> <li>A scale of 0.1 means that the register contains the value multiplied by 0.1. The actual value is therefore the value of the register multiplied by 10.</li> </ul>
Unit	Information unit of measurement:  • "—": no unit corresponding to the value expressed.  • "h": hours  • "D": the unit depends on the connected device.
Туре	Coding data type (see "Data type" table below).
Range	Range of permitted values for the variable, usually a subset of what the format allows. For BITMAP type data, the content of this domain is "—".
Fault	Default value for the variable
Svd	Saving the value in the event of a power failure:  • "Y": the value of the register is saved in the event of a power failure.  • "N": the value is lost in the event of a power failure.
	NOTE: On start-up or reset, the available values are retrieved.
Function code	Code of functions that can be used in the register.
Description	Information about the register and the restrictions that apply.

# **Data Types**

The following data types appear in the tables of Modbus registers:

Name	Description	Range
UINT	16-bit unsigned integer (1 word)	065535
INT	16-bit signed integer (1 word)	-32768+32767
UINT32	32-bit unsigned integer (2 words)	04 294 967 295
INT32	32-bit signed integer (2 words)	-2 147 483 648+2 147 483 647
Float32	32-bit value (2 words)	-3.4028E+38 +3.4028E+38
ASCII	8-bit alphanumeric character	Table of ASCII Characters
BITMAP	16-bit field (1 word)	_
DATE	See below	_

### NOTE:

Float32 type data: Single precision float with sign bit, 8 bits exponent, 23 bits mantissa (positive and negative normalized real)

For ASCII type data, the order of transmission of characters in words (16-bit registers) is as follows:

- Character n as least significant
- Character n + 1 as most significant

All registers (16-bit or 2 bytes) are transmitted with Big Endian coding:

- The most significant byte is transmitted first
- The least significant byte is transmitted second

32-bit variables saved on two 16-bit words (e.g. consumption meters) are in Big Endian format:

• The most significant word is transmitted first, then the least significant.

64-bit variables saved on four 16-bit words (e.g. dates) are in Big Endian format:

• The most significant word is transmitted first, and so on.

#### **DATE**

DATE format in accordance with TI081 standard:

Word	Bits															
	15	15 14 13 12 11 10						8	7	6	5	4	3	2	1	0
1	Reserved (0)								R4 (0)	Yea	r (01	27)		•		•
2	0 Month						2)		WD (0)			Day	(13	1)		
3	SU (0) 0 Hour (023)							iV	0	Minute (059)						
4	Millisecond (059,999)															
R4: Year: Month: Day: Hour: Minute: Millisecond: WD (day of the week): SU (summertime):						4 bits 5 bits 5 bits 6 bits 16 bits Bit at Bit at	(year s 0 if thi 1 for s	startin s para umme	g at 2000 nmeter is r ertime, bit mation is	not us at 0 i	f this p					not

#### **Direct Bit Addressing**

Addressing is permitted for BITMAP type zones with functions 1, 2, 5, and 15.

The address of the first bit is constructed as follows: (register address x 16) + bit number.

This addressing mode is specific to Schneider Electric.

**Example:** For functions 1, 2, 5, and 15, bit 3 of register 0x0078 should be addressed; the bit address is therefore 0x0783.

**NOTE:** The register whose bit needs to be addressed should have an address  $\leq 0x0FFF$ .

#### **Example of Modbus Frames**

#### Request

Definition	Number of Bytes	Value	Comment					
Slave number	1 byte	0x05	Acti 9 Smartlink Ethernet Modbus Address					
Function code	1 byte	0x03	Reads n output or internal words					
Address	2 bytes	0x36E2	Address of a consumption meter whose address is 14050 in decimal notation.					
Number of words	2 bytes	0x002C	Reads 44 16-bit registers.					
CRC	2 bytes	xxxx	Value of CRC16.					

#### Response

Definition	Number of Bytes	Value	Comment
Slave number	1 byte	0x05	Acti 9 Smartlink Ethernet Modbus Address
Function code	1 byte	0x03	Reads n output or internal words
Number of Bytes	2 bytes	0x0058	Number of bytes read
Value of words read	88 bytes	-	Reads 44 16-bit registers
CRC	2 bytes	xxxx	Value of CRC16.

#### **Modbus Address**

The list of Modbus addresses, defined by the protocol, starts at 0. The detailed tables in subsequent chapters of this manual give the addresses.

If the programmable controller (Modbus master) refers to the data model addresses, the addresses to be supplied to this controller must meet the following rule: Data model address = address + 1.

If the programmable controller (Modbus master) refers to the procotol addresses, the addresses to be supplied to this controller must be the Modbus addresses.

#### **Global Modbus Address Table**

#### Overview

Description	Address	No. of Words	Туре	RW
System			<u> </u>	
Identification	100	11	ASCII	R
Status	112	1	BITMAP	R
Date and Time	115	4	DATE	RW
Summary of digital channels 1 to 7				
Status	120	2	BITMAP	R
Orders	130	4	BITMAP	RW
Power or flow indicators	14000	28	Float32	R
Consumption meters	14050	28	UINT32	R
Operation counters	14100	28	UINT32	RW
Running hour counters	14144	14	UINT32	RW
Detail of digital channel 1				
Status	14200	1	BITMAP	R
Orders	14201	2	BITMAP	RW
Output status	14203	1	BITMAP	R
Power or flow indicators	14204	4	Float32	R
Consumption meters	14208	4	UINT32	R
Operation counters	14212	4	UINT32	RW
Running hour counters	14216	2	UINT32	RW
Setting date of operation counters	14218	12	DATE	R
Pulse weight settings (meters)	14230	2	UNIT	RW
Detail of digital channels 2 to 7				
Channel 2 <sup>(1)</sup>	14240	40	_	_
Channel 3 <sup>(1)</sup>	14280	40	_	_
Channel 4 <sup>(1)</sup>	14320	40	-	_
Channel 5 <sup>(1)</sup>	14360	40	-	_
Channel 6 <sup>(1)</sup>	14400	40	-	-
Channel 7 <sup>(1)</sup>	14440	40	_	-
Analog inputs 1 to 2	<u>'</u>	1	1	
Analog input 1	200	2	Float32	R
Analog input 2	202	2	Float32	R

 $<sup>^{(1)}</sup>$ The detailed information for the digital channels 2 to 7 has the same structure as the detailed information for a digital channel 1. To address the digital channel N (1  $\leq$  N  $\leq$  7) registers, add 40  $\times$  (N - 1) to the digital channel 1 registers.

#### **Modbus Address**

The list of Modbus addresses, defined by the Modbus protocol, starts at 0. The detailed tables in subsequent chapters of this manual give the Modbus addresses.

If the programmable controller (Modbus master) refers to the data model addresses, the addresses to be supplied to this controller must meet the following rule: Data model address = Modbus address + 1.

If the programmable controller (Modbus master) refers to the procotol addresses, the addresses to be supplied to this controller must be the Modbus addresses.

# Section 11.2

# **Summary and Detailed Modbus Tables**

## What Is in This Section?

This section contains the following topics:

Topic	Page
System	115
Summary of Digital Channels 1 to 7	117
Details of Digital Channels 1 to 7	120
Analog Input	125

# **System**

#### Identification

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
100	6	R	_	-	ASCII	-	N/A	Y	03, 100–4	Serial number on 12 ASCII characters; 11 alphanumeric digits maximum [SN] or [S/N]: PP YY WW [D[nnnn]] PP: SAP Bridge plant number YY: Year in decimal notation [0599] WW: Week in decimal notation [153] D: Day of the week in decimal notation [17] nnnn: Sequence of numbers [000110.000-1]
106	3	R	_	_	ASCII	_	N/A	N	03, 100–4	Hardware version on 6 ASCII characters
109	3	R	_	_	ASCII	_	N/A	N	03, 100–4	Software version on 6 ASCII characters. <b>Example:</b> "V0.0.1"

#### **Status**

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
112	1	R	-	-	BITMAP	-	0x0000	N	01, 02, 03, 100–4	Acti 9 Smartlink Ethernet device status and diagnostic register Bit 0 = 1: start-up phase Bit 1 = 1: operating phase Bit 2 = 1: downgraded mode <sup>(1)</sup> Bit 3 = 1: failure mode Bit 4: not used Bit 5: not used Bit 6 = 1: invalid data Bit 7 = 1: 24 V channel error Bit 8: not used Bit 10: not used Bit 10: not used Bit 11: not used Bit 12: not used Bit 15: Fash error Bit 15: FLASH error NOTE: Bits 0 to 3 are exclusive: only one mode is used at any given time.

<sup>(1)</sup>Downgraded mode comes into effect:

- When the power supply is cut or less than 16 Vdc.
- In the event of overcurrent (overload or short-circuit) on the Ti24 I/O.

If a short-circuit on an output has caused a change to downgraded mode, at the end of the short-circuit, the output is reset to 0 by the electronics: the Modbus master system sends a Modbus message to reset the output to 1 if it was at 1, before the short-circuit.

Failure mode intervenes if there is an FLASH and/or RAM and/or E2PROM error.

The data is invalid in the start-up phase, downgraded, and failure modes. Invalid data include inputs 1 and 2, the power or flow indicator, the operation and running hours counter.

- The E2PROM error bit is activated during the operating phase when a checksum error is detected in an E2PROM page.
- The RAM error bit is activated during the product initialization phase when an error is detected during a test of the RAM.
- The FLASH error bit is activated during the start-up phase when a checksum error is detected on the FLASH memory.

#### **Date and Time**

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
115	4	RW	_	_	DATE	(1)	N/A	N	03, 16 100–4	Indicates the year, month, day, hour, minute and millisecond on the Acti 9 Smartlink Ethernet device.

<sup>(1)</sup> See description of the DATE type (see page 111).

# Summary of Digital Channels 1 to 7

#### **Status**

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
120	1	R	_	_	BITMAP	_	0x0000	N	01, 02, 03, 100–4	Electrical status on input 1 of all channels <sup>(1)</sup> .
121	1	R	_	-	BITMAP	_	0x0000	N	01, 02, 03, 100–4	Electrical status on input 2 of all channels <sup>(1)</sup> .

(1)

- Bit 0 to 6: channel 1 to 7
- Bits 7 to 15: reserved

Each bit gives the electrical level of input 1 and 2:

- 0 = no current
- 1 = input current

Reserved bits do not mean anything.

#### **Orders**

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
130	1	RW	_	_	BITMAP	-	0x0000	N	01, 02, 03, 05, 06, 15, 16, 100–4	Open order for Acti 9 product <sup>(1)</sup> .
131	1	RW	_	_	BITMAP	-	0x0000	N	01, 02, 03, 05, 06, 15, 16, 100–4	Close order for Acti 9 product <sup>(1)</sup> .
132	1	RW	_	_	BITMAP	-	0x0000	N	01, 02, 03, 05, 06, 15, 16, 100–4	Deactivation order for product not in the Acti 9 range <sup>(1)</sup> .
133	1	RW	_	_	BITMAP	_	0x0000	N	01, 02, 03, 05, 06, 15, 16, 100–4	Activation order for product not in the Acti 9 range <sup>(1)</sup> .

(1)

- Bit 0 to 6: channel 1 to 7
- Bits 7 to 15: reserved

#### NOTE

- Each bit corresponds to an open order (activated when the bit is at 1).
- The open order on several channels is possible.
- The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the open order is taken into account (unless no product is connected to the channel).
- If a reserved bit is at 1, the Acti 9 Smartlink Ethernet device resets it to 0.
- "No meaning" indicates that the bits are fixed at 0 or 1 and do not affect the system.
- If bits 0 and 1 are at 1, there is no effect on the system.
- The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the order is taken into account.

#### **Power or Flow Indicators**

	Channels								
	1	2	3	4	5	6	7		
Input I1	14000	14002	14004	14006	14008	14010	14012		
Input I2	14022	14024	14026	14028	14030	14032	14034		

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14000	2	R	X1	D	Float32	_	0	N	03, 100–4	Power or flow indicator for channel 1/input 1 <sup>(1)</sup> .

(1)

- When the impulse counter (the unit depends on the connected device: energy, gas, water, etc.) is connected to input 1 or 2 of channel 1, the register contains the flow value. This is calculated as follows:
  - (3600 x pulse weight)/t, t representing the time in seconds between 2 pulses. The result is expressed for one hour.
- The default value of pulse weight is 10 and it can be configured by the Modbus command.
   Example: This register indicates the active power between the last 2 pulses if an iEM2000T device is connected to the channel 1/input 1 (Pulse weight = 10 Wh).

#### NOTE:

This register is reset to 0:

- After a duration d = 3 x t (t being the time in seconds between the last 2 pulses), if 3 x t is less than 5 seconds, the duration d equals 5 seconds
- After 24 hours without a pulse
- After loss of the 24 Vdc input/output voltage

The accuracy of the power or flow indication is:

- 5% if the pulse frequency is 5 Hertz or less
- 17% if the pulse frequency equals the maximum frequency of 17 Hertz

#### **Consumption Meters**

The consumption meters in this Modbus table indicate the consumption from meters connected to each Acti 9 Smartlink Ethernet channel (1 to 7).

The consumption value (associated with a channel) is obtained by multiplying the number of pulses (received by inputs I1 and I2 of this channel) by the pulse weight.

	Channels									
	1	2	3	4	5	6	7			
Input I1	14050	14052	14054	14056	14058	14060	14062			
Input I2	14072	14074	14076	14078	14080	14082	14084			

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14050	2	R	X1	_	UINT32	_	0	Y	03, 100–4	Consumption meter on channel 1/input I1.

## NOTE:

- The number of pulses from inputs I1 and I2 of each channel (1 to 7) are available in registers 14212 (channel 1) to 14454 (channel 7). The number of pulses can be preset by writing to the impulse counter register. See the Operation Counters (see page 119) chapter.
- The pulse weights of inputs I1 and I2 of each channel (1 to 7) are available and can be set in registers 14230 (channel 1) to 14471 (channel 7). The pulse weight is 10 by default. See the Pulse Weight Settings (see page 124) chapter.

# **Operation Counters**

	Channels									
	1	2	3	4	5	6	7			
Input I1	14100	14102	14104	14106	14108	14110	14112			
Input I2	14122	14124	14126	14128	14130	14132	14134			

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14100	2	RW	X1	_	UINT32	_	0	Y	03, 16, 100–4	Operation counter for channel 1/input 1: changes from state 1 to state 0.

# **Running Hour Counters**

	Channels									
	1	2	3	4	5	6	7			
Input I1	14144	14146	14148	14150	14152	14154	14156			

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14144	2	RW	X1	h	UINT32	-	0	Y	03, 16, 100–4	Running hours counter for channel 1/input 1. Counting starts when the input is activated.

# **Details of Digital Channels 1 to 7**

#### **Channels 1 to 7 Overview**

	Channel	s					
	1	2	3	4	5	6	7
Status	1	1		11	- I	11	The state of the s
Input I1 (bit 0)	14200	14240	14280	14320	14360	14400	14440
Input I2 (bit 1)	14200	14240	14280	14320	14360	14400	14440
Orders							
Commands output Q (bit 0 and bit 1): Acti 9 product	14201	14241	14281	14321	14361	14401	14441
Commands output Q (bit 0 and bit 1): non-Acti 9 product	14202	14242	14282	14322	14362	14402	14442
State of output Q (bit 0)	14203	14243	14283	14323	14363	14403	14443
Counters					•		
Input I1 power or flow indicator <sup>(2)</sup>	14204	14244	14284	14324	14364	14404	14444
Input I2 power or flow indicator <sup>(2)</sup>	14206	14246	14286	14326	14366	14406	14446
Input I1 consumption meter <sup>(1)(2)</sup>	14208	14248	14288	14328	14368	14408	14448
Input I2 consumption meter (1)(2)	14210	14250	14290	14330	14370	14410	14450
Operation and Running Hours	Counters			"		"	
I1 operation counter <sup>(1)</sup>	14212	14252	14292	14332	14372	14412	14452
I2 operation counter <sup>(1)</sup>	14214	14254	14294	14334	14374	14414	14454
I1 input running hours <sup>(1)</sup>	14216	14256	14296	14336	14376	14416	14456
Setting Date of Operation Coun	iters						
Input I1 date	14218	14258	14298	14338	14378	14418	14458
Input I2 date	14222	14262	14302	14342	14382	14422	14462
Running hours parameter setting date on input I1	14226	14266	14306	14346	14386	14426	14466
Pulse Weight Settings (Meters)		'					'
Pulse weight for input I1 <sup>(2)</sup>	14230	14270	14310	14350	14390	14430	14470
Pulse weight for input I2 <sup>(2)</sup>	14231	14271	14311	14351	14391	14431	14471

<sup>(1)</sup> Data type: UINT32

#### **Modbus Address**

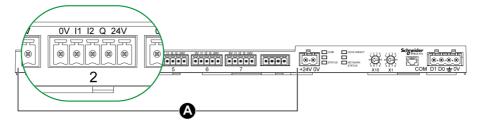
The list of Modbus addresses, defined by the Modbus protocol, starts at 0. The detailed tables in subsequent chapters of this manual give the Modbus addresses.

If the programmable controller (Modbus master) refers to the data model addresses, the addresses to be supplied to this controller must meet the following rule: Data model address = Modbus address + 1.

If the programmable controller (Modbus master) refers to the procotol addresses, the addresses to be supplied to this controller must be the Modbus addresses.

<sup>(2)</sup> Information specific to meter type devices

The figure below shows the terminals for each channel.



#### A Channels from 1 to 7

Description of terminals for each channel (Ti24 interface):

Terminal	Description
24 V	24 V of the 24 Vdc power supply
Q	Control output
12	Input number 2
I1	Input number 1
0 V	0 V of the 24 Vdc power supply

#### **Status**

	Channels									
	1	2	3	4	5	6	7			
Input I1 (bit 0)	14200	14240	14280	14320	14360	14400	14440			
Input I2 (bit 1)	14200	14240	14280	14320	14360	14400	14440			

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14200	1	R	_	_	BITMAP	_	0x0000	N	03, 100–4	Electrical status of inputs 1 and 2 of all connected devices <sup>(1)</sup> .

(1)

- Bit 0 = electrical level of input 1
- Bit 1 = electrical level of input 2
- Bits 2 to 15 = reserved

**NOTE:** "Reserved" means that the bits are fixed at 0 and do not mean anything.

Meaning of bits for inputs I1 and I2:

- 0 = no current
- 1 = input current

#### **Orders**

	Channels									
	1	2	3	4	5	6	7			
Output Q (bit 0 and bit 1): Acti 9 product	14201	14241	14281	14321	14361	14401	14441			

Address	No.	RW	Х	Unit	Туре	Range	Fault	Svd	Function Code	Description
14201	1	RW	_	_	BITMAP	_	0x0000	N	03, 06, 16, 100–4	Close and open order for products in the Acti 9 range <sup>(1)</sup> .

	Channels									
	1	2	3	4	5	6	7			
Output Q (bit 0 and bit 1): non- Acti 9 product	14202	14242	14282	14322	14362	14402	14442			

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14202	1	RW	_	_	BITMAP	_	0x0000	N	03, 06, 16, 100–4	Deactivation and activation order for product not in the Acti 9 range <sup>(2)</sup> .

(1)

- Bit 0 = open order
- Bit 1 = close order
- Bits 2 to 15 = no meaning

(2)

- Bit 0 = deactivation order
- Bit 1 = activation order
- Bits 2 to 15 = no meaning

#### NOTE:

- The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the open order is taken into account (unless no product is connected to the channel).
- If a reserved bit is at 1, the Acti 9 Smartlink Ethernet device resets it to 0.
- "No meaning" indicates that the bits are fixed at 0 or 1 and do not affect the system.
- If bits 0 and 1 are at 1, there is no effect on the system.
- The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the order is taken into account.

#### **Power or Flow Indicators**

	Channels									
	1	2	3	4	5	6	7			
Input I1 power or flow indicator <sup>(6)</sup>	14204	14244	14284	14324	14364	14404	14444			
Input I2 power or flow indicator <sup>(6)</sup>	14206	14246	14286	14326	14366	14406	14446			

Address	No.	RW	Х	Unit	Туре	Range	Fault	Svd	Function Code	Description
14204	2	R	X1	D	Float32	_	0	N	03, 100–4	Power or flow indicator for input 1 <sup>(1)</sup> .
14206	2	R	X1	D	Float32	_	0	N	03, 100–4	Power or flow indicator for input 2 <sup>(1)</sup> .

(1) The same channel (Ti24 interface) on the Acti 9 Smartlink Ethernet can take account of 2 counters:

- One counter connected to input I1
- One counter connected to input I2

## **Consumption Meters**

	Channels	Channels									
	1	2	3	4	5	6	7				
Input I1 consumption meter <sup>(1)</sup>	14208	14248	14288	14328	14368	14408	14448				
Input I2 consumption meter <sup>(1)</sup>	14210	14250	14290	14330	14370	14410	14450				

- $^{(1)}$  The same channel (Ti24 interface) on the Acti 9 Smartlink Ethernet can take account of 2 meters:
- One meter connected to input I1
- One meter connected to input I2

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14208	2	R	X1	_	UINT32	_	0	Y	03, 100–4	Consumption meter on input 1.
14210	2	R	X1	-	UINT32	_	0	Υ	03, 100–4	Consumption meter on input 2.

# **Operation Counters**

	Channels									
	1	2	3	4	5	6	7			
I1 operation counter	14212	14252	14292	14332	14372	14412	14452			
I2 operation counter	14214	14254	14294	14334	14374	14414	14454			

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14212	2	RW	X1	_	UINT32	-	0	Y	03, 16 100–4	Operation counter for channel 1/input 1. This register indicates the number of changes of state of input 1 from state 1 to state 0.

# **Running Hour Counters**

	Channels						
	1	2	3	4	5	6	7
I1 input running time	14216	14256	14296	14336	14376	14416	14456

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14216	2	RW	X1	h	UINT32	_	0	Y	03, 16 100–4	Running hours counter for a digital channel 1/input 1. Counting starts when the input is activated.

# **Setting Date of Operation Counters**

	Channels	Channels								
	1	2	3	4	5	6	7			
Input I1 date	14218	14258	14298	14338	14378	14418	14458			
Input I2 date	14222	14262	14302	14342	14382	14422	14462			
Running hours parameter setting date on input I1	14226	14266	14306	14346	14386	14426	14466			

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14218	4	R	-	-	DATE	(1)	(1)	Y	03, 100–4	Date when the operation counter parameter was last set. This register indicates the date and time when the operation counter parameter was last set on input 1.
14222	4	R	-	-	DATE	(1)	(1)	Y	03, 100–4	Date when the operation counter parameter was last set. This register indicates the date and time when the operation counter parameter was last set on input 2.
14226	4	R	-	_	DATE	(1)	(1)	Y	03, 100–4	Date when the running hours counter parameter was last set. This register indicates the date and time when the running hours counter parameter was last set on input 1.

 $<sup>^{(1)}</sup>$  See description of the DATE type (see page 111).

# **Pulse Weight Settings (Meters)**

	Channels	Channels									
	1	2	3	4	5	6	7				
Pulse weight I1	14230	14270	14310	14350	14390	14430	14470				
Pulse weight I2 <sup>(1)</sup>	14231	14271	14311	14351	14391	14431	14471				

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
14230	1	RW	X1	D	UINT	065,53 5	10	Y	03, 06, 16 100–4	Pulse weight: this register can be used to set the value of the pulse weight for the meter connected to input 1 of a digital channel 1.
14231	1	RW	X1	D	UINT	065,53 5	10	Y	03, 06, 16 100–4	Pulse weight: this register can be used to set the value of the pulse weight for the meter connected to input 2 of a digital channel 1.

 <sup>(1)</sup> The same channel (Ti24 interface) on the Acti 9 Smartlink Ethernet can take account of 2 meters:
 One meter connected to input I1

- One meter connected to input I2

# **Analog Input**

# **Analog Channel Synthesis Data Access**

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
200	2	R	_	V/A	Float32	_	0xFFC0 0	N	03, 06, 16, 100–4	Analog input 1 measurement value in Volt (010 V) or Ampere (420 mA).
202	2	R	_	V/A	Float32	_	0	N	03, 06, 16, 100–4	Analog input 2 measurement value in Volt (010 V) or Ampere (420 mA).

# **Analog Channel Detail Information Access**

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
Analog ch	anne	l 1 dat	а							
15000	2	R	_	V/A	Float32	_	0	N	03, 06, 16, 100–4	Analog channel 1 measurement value Value in Volt (010 V) or Ampere (420 mA)
15002	2	R	NA	User- defin ed	Float32	NA	0	N	03, 06, 16, 100–4	Analog input physical value after conversion by transfer function
15004	6	R	NA	_	_	_	0x8000	_	03, 06, 16, 100–4	_
Analog ch	anne	l 1 set	ting		1				1	
15010	1	R/W	-	_	BITMAP	_	0x0000	Y	03, 06, 16, 100–4	Input type of analog channel 1 Bit 0 0 : 010 V 1 : 420 mA Bit 1 0 : Channel is not customized 1 : Channel is customized
15011	2	R/W	Use r defi ned	User defin ed	Float32	_	0	_	03, 06, 16, 100–4	Minimum of scale for the transfer function of analog channel 1
15013	2	R/W	Use r defi ned	User defin ed	Float32	-	0	-	03, 06, 16, 100–4	Maximum of scale for transfer function of analog channel 1
Analog ch	nanne	l 2 dat	а							
15020	2	R	_	V/A	Float32	_	0	N	03, 06, 16, 100–4	Analog channel 2 measurement value Value in Volt (010 V) or Ampere (420 mA)]
15022	2	R	_	User defin ed	Float32	-	0	N	03, 06, 16, 100–4	Physical value after conversion by transfer function for analog channel 2
15024	6	R	-	-	_	_	0x8000	-	03, 06, 16, 100–4	_
Analog ch	anne	l 2 set	ting						•	

Address	No.	RW	X	Unit	Туре	Range	Fault	Svd	Function Code	Description
15030	1	R/W	_	_	BITMAP	_	0x0000	Y	03, 06, 16, 100–4	Input type of analog channel 2 Bit 0 0:010 V 1:420 mA Bit 1 0: Channel is not customized 1: Channel is customized
15031	2	R/W	Use r defi ned	User defin ed	Float32	_	NaN	_	03, 06, 16, 100–4	Minimum of scale for the transfer function of analog channel 2
15033	2	R/W	Use r defi ned	User defin ed	Float32	_	0	_	03, 06, 16, 100–4	Maximum of scale for transfer function of analog channel 2

# Section 11.3

# **Modbus Tables for Connected Products**

## What Is in This Section?

This section contains the following topics:

Topic	Page
iOF+SD24 Indication Auxiliary	128
OF+SD24 Indication Auxiliary	129
iEM2000T, iEM3110, iEM3155, iEM3210, iEM3255 Meters, or Meter with Pulse Output (Standard CEI 62053-31)	130
iACT24 Auxiliary for iCT Contactor	131
iATL24 Auxiliary for iTL Impulse Relay	132
Contactor and Relay (Not in the Acti 9 Range)	133
Acti 9 RCA iC60 Remote Control with Ti24 Interface	134
Acti 9 Reflex iC60 Integrated Control Circuit Breaker With Ti24 Interface	135

# iOF+SD24 Indication Auxiliary

#### Overview

The iOF+SD24 indication auxiliary is used to find out the status of the following devices:

- iC60 and iC65 circuit breaker (OF and SD states)
- $\bullet~$  iID residual current circuit breaker (OF and  $\overline{\mbox{SD}}$  states)
- iSW-NA switch (OF status)
- iDPN circuit breaker (sold in China)

The Modbus information in the table below is given for an iOF+SD24 auxiliary connected to channel 1.

Description	Address <sup>(1)</sup>	No. of Register(s)	Туре	Action	Values and Meanings
Status					
OF status	14200	1	BITMAP	R	bit 0 = 0: circuit breaker open bit 0 = 1: circuit breaker closed
status SD	14200	1	BITMAP	R	bit 1 = 0: device tripped (fault present) bit 1 = 1: device not tripped
Counters					
Number of circuit breaker opening/closing cycles	14212	2	UINT32	RW	_
Number of trippings	14214	2	UINT32	RW	-
Load running time	14216	2	UINT32	RW	in hours

 $<sup>^{(1)}</sup>$  To address the digital channel N (1  $\leq$  N  $\leq$  7) registers, add 40  $\times$  (N - 1) to the digital channel 1 registers.

# **OF+SD24 Indication Auxiliary**

#### **Overview**

The OF+SD24 indication auxiliary is used to find out the status of the following devices:

- C60 or C120 circuit breaker (OF and SD states)
- ullet DPN residual current circuit breaker (OF and  $\overline{\text{SD}}$  states)
- DPN switch (OF status)
- C60H-DC circuit breaker (OF and SD states)
- iDPN circuit breaker (sold in every country except China)

The Modbus information in the table below is given for an OF+SD24 auxiliary connected to channel 1.

Description	Address <sup>(1)</sup>	No. of Register(s)	Туре	Action	Values and Meanings
Status					
OF status	14200	1	BITMAP	R	bit 0 = 0: circuit breaker open bit 0 = 1: circuit breaker closed
Status SD	14200	1	BITMAP	R	bit 1 = 0: device tripped (fault present) bit 1 = 1: device not tripped
Counters					
Number of circuit breaker opening/closing cycles	14212	2	UINT32	RW	-
Number of trippings	14214	2	UINT32	RW	-
Load running time	14216	2	UINT32	RW	in hours

 $<sup>^{(1)}</sup>$  To address the digital channel N (1  $\leq$  N  $\leq$  7) registers, add 40  $\times$  (N - 1) to the digital channel 1 registers.

# iEM2000T, iEM3110, iEM3155, iEM3210, iEM3255 Meters, or Meter with Pulse Output (Standard CEI 62053-31)

#### **Overview**

The meter delivers a pulse output.

The Modbus information in the table below is given for a meter connected to a digital channel 1.

The same channel (Ti24 interface) on the Acti 9 Smartlink Ethernet can take account of 2 meters:

- One meter connected to input I1
- One meter connected to input I2

Description	Address <sup>(1)</sup>	No. of Register(s)	Туре	Action	Values and Meanings	
Status						
Pulse output (meter 1)	14200	1	BITMAP	R	bit 0	
Pulse output (meter 2)	14200	1	BITMAP	R	bit 1	
Counters	•					
Power or flow indicator (meter 1)	14204	2	Float32	R	(2)	
Power or flow indicator (meter 2)	14206	2	Float32	R	(2)	
Consumption meter (meter 1)	14208	2	UINT32	R	(3)	
Consumption meter (meter 2)	14210	2	UINT32	R	(3)	
Settings	!	!	*		•	
Pulse weight (meter 1)	14230	1	UINT	RW	(2)	
Pulse weight (meter 2)	14231	1	UINT	RW	(2)	

 $<sup>^{(1)}</sup>$  To address the digital channel N (1  $\leq$  N  $\leq$  7) registers, add 40  $\times$  (N - 1) to the digital channel 1 registers.

<sup>(2)</sup> The register contains the flow value.

<sup>•</sup> The flow is: (3600 x pulse weight)/t, with t representing the time in seconds between 2 pulses. The result is expressed for one hour.

<sup>•</sup> The pulse weight is 10 by default. The unit depends on the connected device: energy, gas, water, etc.

<sup>&</sup>lt;sup>(3)</sup> The consumption value (associated with a channel) is obtained by multiplying the number of pulses (received by inputs I1 and I2 of this channel) by the pulse weight.

# iACT24 Auxiliary for iCT Contactor

#### Overview

The iACT24 auxiliary:

- Can be used to control an iCT contactor rated 25 A or higher via its Y1, Y2 and Y3 inputs. The Y3 (24 Vdc) input can be controlled by one of the Acti 9 Smartlink Ethernet device channels.
- Is used to find out the contactor status (O/C status: open/closed status)

The Modbus information in the table below is given for an iACT24 auxiliary connected to a digital channel 1.

Description	Address <sup>(1)</sup>	No. of Register(s)	Туре	Action	Values and Meanings
Status	·				
O/C status: open/closed status	14200	1	BITMAP	R	bit 0 = 0: contactor open bit 0 = 1: contactor closed
Device present	14200	1	BITMAP	R	bit 1 = 0: connection fault or no connected device bit 1 = 1: connected device
Orders					
Deactivate contactor coil	14201	1	BITMAP	RW	bit 0 = 1: deactivate coil <sup>(2)</sup>
Activate contactor coil	14201	1	BITMAP	RW	bit 1 = 1: activate coil <sup>(2)</sup>
Counters	·				
Number of contactor open/close cycles	14212	2	UINT32	RW	-
Load running time for an NO contactor	14216	2	UINT32	RW	in hours

<sup>&</sup>lt;sup>(1)</sup> To address the digital channel N ( $1 \le N \le 7$ ) registers, add  $40 \times (N-1)$  to the digital channel 1 registers.

<sup>&</sup>lt;sup>(2)</sup> The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the order is taken into account (unless no product is connected to the channel). If bits 0 and 1 of address 14201 are activated simultaneously, the Acti 9 Smartlink Ethernet device does nothing.

# iATL24 Auxiliary for iTL Impulse Relay

#### Overview

The iATL24 auxiliary:

- Can be used to control an iTL impulse relay via its Y1, Y2, and Y3 inputs
  The Y3 (24 Vdc) input can be controlled by one of the Acti 9 Smartlink Ethernet device channels.
- Can be used to find out the impulse relay status (O/C status open/closed status).

The Modbus information in the table below is given for an iATL24 auxiliary connected to a digital channel 1.

Description	Address <sup>(1)</sup>	Address <sup>(1)</sup> No. of Register(s) Type A		Action	Values and Meanings
Status					
O/C status: open/closed status	14200	1	BITMAP	R	bit 0 = 0: impulse relay open bit 0 = 1: impulse relay closed
Device present	14200	1	BITMAP	R	bit 1 = 0: connection fault or no connected device bit 1 = 1: connected device
Orders					
Impulse relay contact opening	14201	1	BITMAP	RW	bit 0 = 1: Impulse relay contact opening <sup>(2)</sup>
Impulse relay contact closing	14201	1	BITMAP	RW	bit 1 = 1: Impulse relay contact closing <sup>(2)</sup>
Counters	<u> </u>				
Number of impulse relay opening/closing cycles	14212	2	UINT32	RW	_
Load running time	14216	2	UINT32	RW	in hours

 $<sup>^{(1)}</sup>$  To address the digital channel N (1  $\leq$  N  $\leq$  7) registers, add 40  $\times$  (N - 1) to the digital channel 1 registers.

<sup>&</sup>lt;sup>(2)</sup> The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the order is taken into account (unless no product is connected to the channel). If bits 0 and 1 of address 14201 are activated simultaneously, the Acti 9 Smartlink Ethernet device does nothing.

# **Contactor and Relay (Not in the Acti 9 Range)**

#### Overview

A contactor or relay powered with 24 Vdc can be connected to Acti 9 Smartlink Ethernet. This should have the following characteristics:

- The contactor or relay coil must not draw more than 100 mA
- The indication contact must be low level type

Only contactors in the Acti 9 range can be connected to Acti 9 Smartlink Ethernet using the iATL24 auxiliary.

The contactor can be controlled by one of the Acti 9 Smartlink Ethernet device channels.

The Modbus information in the table below is given for a contactor connected to a digital channel 1.

Description	Address <sup>(1)</sup>	No. of Register(s)	Туре	Action	Values and Meanings
Status				•	
OF status	14200	1	BITMAP	R	bit 0 = 0: contactor open bit 0 = 1: contactor closed
Orders					
Deactivate contactor coil	14202	1	BITMAP	RW	bit 0 = 1: deactivate coil <sup>(2)</sup>
Activate contactor coil	14202	1	BITMAP	RW	bit 1 = 1: activate coil <sup>(2)</sup>
Counters					
Number of contactor open/close cycles	14212	2	UINT32	RW	_
Load running time for an NO contactor	14216	2	UINT32	RW	in hours

 $<sup>^{(1)}</sup>$  To address the digital channel N (1  $\leq$  N  $\leq$  7) registers, add 40  $\times$  (N - 1) to the digital channel 1 registers.

<sup>&</sup>lt;sup>(2)</sup> The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the order is taken into account (unless no product is connected to the channel). If bits 0 and 1 of address 14202 are activated simultaneously, the Acti 9 Smartlink Ethernet device does nothing.

#### Acti 9 RCA iC60 Remote Control with Ti24 Interface

#### Overview

The Acti 9 RCA iC60 remote control:

- Should have a Ti24 interface (with product references A9C70122 and A9C70124)
- Can be used to control a iC60 circuit breaker via input Y3 of its Ti24 interface.
   The Y3 (24 Vdc) input can be controlled by one of the Acti 9 Smartlink Ethernet device channels
- Can be used to find out the OF and SD states of the circuit breaker associated with the Acti 9 RCA iC60 remote control

The Modbus information in the table below is given for an Acti 9 RCA iC60 remote control connected to a digital channel 1.

Description	Address <sup>(1)</sup>	No. of Register(s)	Туре	Action	Values and Meanings
Status					
OF status	14200	1	BITMAP	R	bit 0 = 0: circuit breaker open bit 0 = 1: circuit breaker closed
Status SD	14200	1	BITMAP	R	bit 1 = 0: device tripped (fault present) bit 1 = 1: device not tripped
Orders					
Activation of the open order	14201	1	BITMAP	RW	bit 0 = 1: activation of the open order <sup>(2)</sup>
Activation of the close order	14201	1	BITMAP	RW	bit 1 = 1: activation of the close order <sup>(2)</sup>
Counters		*	*		
Number of circuit breaker open/close cycles	14212	2	UINT32	RW	_
Number of trippings	14214	2	UINT32	RW	_
Load running time	14216	2	UINT32	RW	in hours

 $<sup>^{(1)}</sup>$  To address the digital channel N (1  $\leq$  N  $\leq$  7) registers, add 40  $\times$  (N - 1) to the digital channel 1 registers.

<sup>&</sup>lt;sup>(2)</sup> The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the order is taken into account (unless no product is connected to the channel). If bits 0 and 1 of address 14201 are activated simultaneously, the Acti 9 Smartlink Ethernet device does nothing.

# Acti 9 Reflex iC60 Integrated Control Circuit Breaker With Ti24 Interface

#### Overview

The Acti 9 Reflex iC60 integrated control circuit breaker:

- Should have a Ti24 interface (with product references A9C6 ••••).
- Can allow the device to be controlled via input Y3 of its Ti24 interface
  The Y3 (24 Vdc) input can be controlled by one of the Acti 9 Smartlink Ethernet device channels.
- Can be used to communicate its O/C and auto/OFF status

The Modbus information in the table below is given for an Acti 9 Reflex iC60 integrated control circuit breaker connected to a digital channel 1.

Description	Address <sup>(1)</sup>	No. of Register(s)	Туре	Action	Values and Meanings
Status					
O/C status: open/closed status	14200	1	BITMAP	R	bit 0 = 0: circuit breaker open bit 0 = 1: circuit breaker closed
auto/OFF status: handle position	14200	1	BITMAP	R	bit 1 = 0: handle in OFF position (device open) bit 1 = 1: handle in upper position: auto
Orders					
Activation of the open order	14201	1	BITMAP	RW	bit 0 = 1: activation of the open order <sup>(2)</sup>
Activation of the close order	14201	1	BITMAP	RW	bit 1 = 1: activation of the close order <sup>(2)</sup>
Counters					
Number of circuit breaker open/close cycles	14212	2	UINT32	RW	-
Number of trippings	14214	2	UINT32	RW	-
Load running time	14216	2	UINT32	RW	in hours

<sup>(1)</sup> To address the digital channel N ( $1 \le N \le 7$ ) registers, add  $40 \times (N-1)$  to the digital channel 1 registers.

<sup>&</sup>lt;sup>(2)</sup> The Acti 9 Smartlink Ethernet device resets the bit to state 0 when the order is taken into account (unless no product is connected to the channel). If bits 0 and 1 of address 14201 are activated simultaneously, the Acti 9 Smartlink Ethernet device does nothing.

# **Appendices**



# What Is in This Appendix?

The appendix contains the following chapters:

Chapter	Chapter Name	Page
Α	Details of Modbus Functions	139
В	Reset of Smartlink Ethernet	147
С	Troubleshooting	149

# **Appendix A**Details of Modbus Functions

# What Is in This Chapter?

This chapter contains the following topics:

Topic	Page
Function 8: Modbus Diagnostics	140
Function 43-14: Read Acti 9 Smartlink ID	142
Function 43–15: Read Date and Time	144
Function 43-16: Write Date and Time	145
Function 100-4: Read n Non-Adjacent Words	146

# **Function 8: Modbus Diagnostics**

## Structure of Modbus Messages Concerning Acti 9 Smartlink Ethernet Diagnostic Counter Management

#### Request

Definition	Number of Bytes	Value
Slave number	1 byte	0xFF
Function code	2 bytes	08 (0x08)
Sub-function code	2 bytes	22 (0x0016)
Operation code	2 bytes	1 ((0x0001) see below list for operation code)
Diagnostic control	2 bytes	0x0100 (see below list for diagnostic control)
Starting entry index	1 byte	0x00 (0 to 255)

The operation code field is used to select the diagnostic and the statistic data to be read from the device.

Most 9	Signific	nificant Byte					Least Significant Byte								
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Reserv	ved			Protoc	ol Vers	ion	•	Operation Code							

Bit assignments are included in the table below:

Bit	Field	Description
1512	Reserved	Must be zero
118	Protocol Version (PV)	Indicates version of the protocol of the client (requestor) Values are: 0x00 (initial version)
70	Operation Code	Indicates function to be performed by the command Values are:  • 0x01 = Read diagnostic data  • 0x02 = Clear diagnostic data  • 0x03 = Clear all diagnostic data  • 0x04 = List ports

The diagnostic control field provides the data selection information for this protocol as well as specifies the logical port from which, the data is to be retrieved (if applicable). The diagnostic control field is defined as shown in the table below:

Most 9	Signific	ant By	te					Least Significant Byte							
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Data S	Selection	n Code					•	Port Select							

Bit assignments are included in the table below:

Bit	Field	Description
158	Data Selection Code (DS)	Indicates the diagnostic data to retrieve or to clear from the logical port. See the table below for valid values.
70	Port Select (PS)	Indicates the logical port number to retrieve the selected data from  ■ 0x00 = the internal port of a device that supports an embedded switch or any single port not accessible externally  ■ 0x01 to 0xFE = logical number of the desired port  ■ 0xFF = the port the current request came in
		This value should be 0xFF if the requested data is not port specific. See the <b>Port Select Needed</b> column in the table below for which <b>Data Selection Code</b> requires a valid port select value.

#### Data selection code

Data Selection Code	Diagnostic Data Retrieved	Port Select Needed	Туре
0x00	Reserved		Public
0x01	Basic network diagnostics		Public
0x02	Ethernet port diagnostics	Yes	Public
0x03	Modbus TCP port 502 diagnostics		Public
0x04	Modbus TCP port 502 connection table		Public
0x05 to 0x7E	Reserved for other public codes		Public
0x7F	Data structure offsets		Public
0x80 to 0xFF	Reserved		Reserved

# Response

Definition	Number of Bytes	Value
Slave number	1 byte	0xFF
Function code	2 bytes	08 (0x08)
Sub-function code	2 bytes	22 (0x0016)
Operation code	2 bytes	1 ((0x0001) see the above list for operation code)
Diagnostic control	2 bytes	0x0100 (see the above list for diagnostic control)
Starting entry index	1 byte	0x00 (0 to 255)

# **Resetting Counters**

The counters are reset to 0:

- When they reach the maximum value 65535.
- When they are reset by a Modbus command (function code 8, sub-function code 10).
- When the power is cut off, or
- When the communication parameters are modified.

# Function 43-14: Read Acti 9 Smartlink ID

# Structure of Modbus Read Acti 9 Smartlink ID Messages

The ID consists of ASCII characters called objects.

Request for basic information

Definition	Number of Bytes	Value
Slave number	1 byte	0xFF
Function code	1 byte	0x2B
Sub-function code	1 byte	0x0E
Product ID	1 byte	0x01
Object identifier	1 byte	0x00

## Response with basic information

Definition		Number of Bytes	Value	
Slave number		1 byte	0xFF	
Function code		1 byte	0x2B	
Sub-function code		1 byte	0x0E	
Product ID		1 byte	0x01	
Conformity level		1 byte	0x01	
Reserved		1 byte	0x00	
Reserved		1 byte	0x00	
Number of objects		1 byte	0x03	
Object 0: manufacturer name	Object number	1 byte	0x00	
	Object length	1 byte	0x12	
	Object content	18 bytes	Schneider Electric	
Object 1: product code	Object number	1 byte	0x01	
	Object length	1 byte	0x08	
	Object content	8 bytes	A9XMEA08	
Object 2: version number	Object number	1 byte	0x02	
	Object length	1 byte	0x06 (minimum)	
	Object content	6 bytes minimum	Vx.y.z	

# Request for complete information

Definition	Number of Bytes	Value
Slave number	1 byte	0xFF
Function code	1 byte	0x2B
Sub-function code	1 byte	0x0E
Product ID	1 byte	0x02
Object identifier	1 byte	0x00

# Response with complete information

Definition	Number of Bytes	Value
Slave number	1 byte	0xFF
Function code	1 byte	0x2B
Sub-function code	1 byte	0x0E
Product ID	1 byte	0x02
Conformity level	1 byte	0x02
Reserved	1 byte	0x00

Definition		Number of Bytes	Value	
Reserved		1 byte	0x00	
Number of objects		1 byte	0x05	
Object 0: manufacturer name	Object number	1 byte	0x00	
	Object length	1 byte	0x12	
	Object content	18 bytes	Schneider Electric	
Object 1: product code	Object number	1 byte	0x01	
	Object length	1 byte	0x08	
	Object content	8 bytes	A9XMEA08	
Object 2: version number	Object number	1 byte	0x02	
	Object length	1 byte	0x06 (minimum)	
	Object content	6 bytes minimum	Vx.y.z	
Object 3: manufacturer URL	Object number	1 byte	0x03	
	Object length	1 byte	0x1A	
	Object content	26 bytes	www.schneider-electric.com	
Object 4: product name	Object number	1 byte	0x04	
	Object length	1 byte	0x12	
	Object content	18 byte	Acti 9 Smartlink Ethernet	

**NOTE:** The above table describes how to read the ID of a Acti 9 Smartlink Ethernet.

# Function 43-15: Read Date and Time

# **Structure of Modbus Read Date and Time Messages**

# Request

Definition	Number of Bytes	Value	Example
Slave number	1 byte	0x2F	47
Function code	1 byte	0x2B	43
Sub-function code	1 byte	0x0F	15
Reserved	1 byte	0x00	Reserved

# Response

			Number of Bytes	Value	Example
Slave number			1 byte	0x2F	47
Function code			1 byte	0x2B	43
Sub-function code			1 byte	0x0F	15
Reserved			1 byte	0x00	Reserved
Date and time <sup>(1)</sup>	byte 1	Not used	1 byte	0x00	Not used
	byte 2	Year	1 byte	0x0A	Year 2010
	byte 3	Month	1 byte	0x0B	Month of November
	byte 4	Day of the month	1 byte	0x02	Second day of the month
	byte 5	Hour	1 byte	0x0E	14 hours
	byte 6	Minute	1 byte	0x20	32 minutes
byte 7 and byte 8 Millisecond		2 bytes	0x0DAC	3.5 seconds	
(1) See description of the DATE type (see page 111).					

# Function 43-16: Write Date and Time

# **Structure of Modbus Write Date and Time Messages**

# Request

Definition			Number of Bytes	Value	Example
Slave number			1 byte	0x2F	47
Function code			1 byte	0x2B	43
Sub-function code			1 byte	0x10	16
Reserved			1 byte	0x00	Reserved
Date and time <sup>(1)</sup>	byte 1	not used	1 byte	0x00	Not used
	byte 2	Year	1 byte	0x0A	Year 2010
	byte 3	Month	1 byte	0x0B	Month of November
	byte 4	Day of the month	1 byte	0x02	Second day of the month
	byte 5	Hour	1 byte	0x0E	14 hours
	byte 6	Minute	1 byte	0x20	32 minutes
	byte 7 and byte 8	Millisecond	2 bytes	0x0DAC	3.5 seconds
(1) See description of the DATE type (see page 111).					

# Response

Definition			Number of Bytes	Value	Example
Slave number			1 byte	0x2F	47
Function code			1 byte	0x2B	43
Sub-function code			1 byte	0x10	15
Reserved			1 byte	0x00	Reserved
Date and time <sup>(1)</sup>	byte 1	Not used	1 byte	0x00	Not used
	byte 2	Year	1 byte	0x0A	Year 2010
	byte 3	Month	1 byte	0x0B	Month of November
	byte 4	Day of the month	1 byte	0x02	Second day of the month
	byte 5	Hour	1 byte	0x0E	14 hours
	byte 6	Minute	1 byte	0x20	32 minutes
	byte 7 and byte 8	Millisecond	2 bytes	0x0DAE	3.502 seconds
(1) See description of the DATE type (see page 111).					

# Function 100-4: Read n Non-Adjacent Words

# Structure of Modbus Read n Non-Adjacent Words Messages Where $n \leq 100\,$

#### Request

Definition	Number of Bytes	Value			
Modbus slave number	1 byte	0x2F			
Function code	1 byte	0x64			
Length of data in bytes	1 byte	0x06			
Sub-function code	1 byte	0x04			
Transmission number <sup>(1)</sup>	1 byte	0xXX			
Address of the first word to be read (MSB)	1 byte	0x00			
Address of the first word to be read (LSB)	1 byte	0x65			
Address of the second word to be read (MSB)	1 byte	0x00			
Address of the second word to be read (LSB)	1 byte	0x67			
(1) The master gives the transmission number in the request.					

**NOTE:** The above table describes how to read addresses 101 = 0x65 and 103 = 0x67 of a Modbus slave. The Modbus slave number is 47 = 0x2F.

## Response

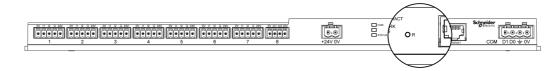
Definition	Number of Bytes	Value	
Modbus slave number	1 byte	0x2F	
Function code	1 byte	0x64	
Length of data in bytes	1 byte	0x06	
Sub-function code	1 byte	0x04	
Transmission number <sup>(1)</sup>	1 byte	0xXX	
First word read (MSB)	1 byte	0x12	
First word read (LSB)	1 byte	0x0A	
Second word read (MSB)	1 byte	0x74	
Second word read (LSB)	1 byte	0x0C	
(1) The slave sends back the sa	me number in the response.		

**NOTE:** The above table describes how to read addresses 101 = 0x65 and 103 = 0x67 of a Modbus slave. The Modbus slave number is 47 = 0x2F.

# Appendix B

# **Reset of Smartlink Ethernet**

# **Description**



Press and hold the **Reset** button for 5 seconds of Acti 9 Smartlink Ethernet to reset to the factory parameter settings.

The reset data is as follows:

- The mode of IP acquisition is set to DHCP.
- The password is set to the default value.
- Modbus serial setting is set to 19,200, 8 bits, 1 stop bit, and even parity.
- The panel information saved in Actii 9 Smartlink Ethernet is erased.
- The user accounts is erased (only default user accounts will be retained).
- The operation counters are set to 0.
- The running hours counters are set to 0.
- The counter modification values are set to the value "1 January 2000".
- The counter pulse weights are set to 10.

# **Appendix C Troubleshooting**

# **Common Problems**

# **Description**

The following table describe the abnormal behavior and diagnostics, and provide some corrective actions:

Problem	Diagnostics	Action	
Web page is displayed only with texts without graphics.	The text and graphics in the web page is loaded based on the traffic and disruptions on the IT network.	Refresh the browser.	
Analog sensor values on the web page does not appear appropriate.	Incorrect sensor settings	Check the settings in the <b>Settings</b> menu and ensure proper values are applied.	
	Wrong wiring between the sensor and Acti 9 Smartlink Ethernet	Check that the wiring between the sensor and Acti 9 Smartlink Ethernet is accurate.	
	Sensor is disconnected from Acti 9 Smartlink Ethernet	Check the wiring for loose connections or open terminals.	
IP setting changes are not effected.	IP settings not applied	Reboot the device if the changes do not take effect within two minutes.	



Schneider Electric Industries SAS

35, rue Joseph Monier CS30323 F - 92506 Rueil Malmaison Cedex As standards, specifications and designs change from time to time, please ask for confirmation of the information given in this publication.

www.schneider-electric.com 04/2014