

### ROBONET Extension Unit

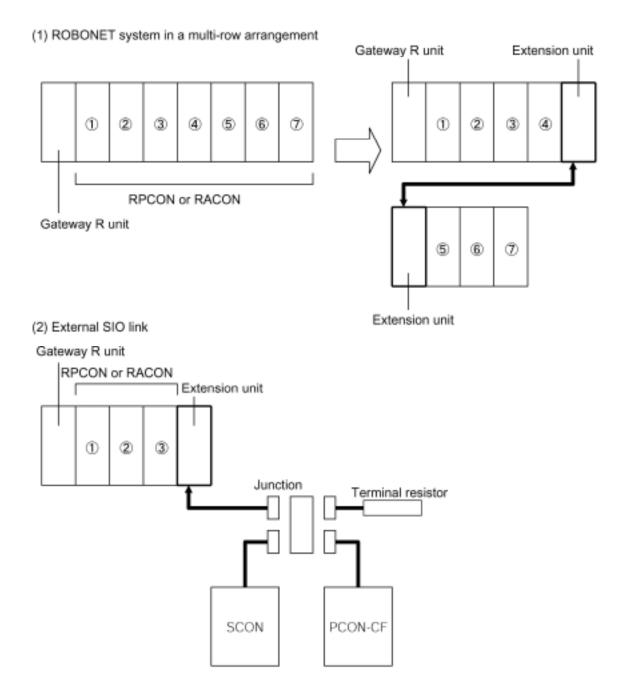
Addendum

User Manual First Edition

IAI America, Inc.

### 1. Overview

Under normal circumstances, the ROBONET system consists of a Gateway R unit in the leftmost slot and RPCON or RACON controller units installed side by side, adjacent to the Gateway R unit. However, due to the width of the control panel or other physical limitations, it may not be possible to arrange the modules in a single row. In that case, the (optional) Extension unit can be used to arrange the modules into several rows (multi-row arrangement). The controller units are normally RPCON or RACON units, but the Extension unit allows SCON (positioner mode) or PCON-CF units to be connected to the ROBONET system (via external SIO link).



### 2. Specifications

Туре	REXT (Main unit)				
Power supply	DC24V±10%				
Current consumption	Max. 200mA				
Environmental conditions	Ambient operating temperature	0~40°C			
	Ambient operating humidity	Max. 95% RH (non-condensing)			
	Operating ambience Free of corrosive gases and dust				
	Storage temperature 0~40°C				
	Storage humidity Max. 95% RH (non-condensing)				
	Vibration resistance XYZ directions: 10~57Hz half amplitude 0.035 mm				
		(continuous)			
		0.075 mm (intermittent)			
		57~150Hz 4.9m/s2 (continuous) 9.8m/s2 (intermittent)			
	Impact resistance	XYZ directions: 147 mm/s2 11 ms half sign-wave pulse			
Protection	IP20				
degree:					
Weight	140g (main unit only)				
External dimensions	34W×100H×73.3D mm				

### 3. Product configuration

Name	Туре	Contents	Application	Figure
ROBONET Extension unit	REXT	<ul> <li>Main unit x 1</li> <li>Power supply connection plate x 2</li> <li>Communication connection circuit board×1</li> </ul>	<ul> <li>ROBONET multi-row arrangement</li> <li>External SIO link</li> </ul>	Fig.1
ROBONET Extension set A	REXT-SIO	<ul> <li>Main unit x 2</li> <li>Power supply connection plate x 2</li> <li>Communication connection circuit board x 1</li> <li>ROBONET Extension A cable (standard 1 m)</li> </ul>	Multi-row arrangement set	Fig.2
ROBONET Extension set B	REXT-CTL	<ul> <li>Main unit x 1</li> <li>Power supply connection plate x 2</li> <li>Communication connection circuit board x 1</li> <li>ROBONET Extension B cable (standard 1 m)</li> </ul>	External SIO link set	Fig.3
ROBONET Extension A cable	CB-REXT- SIO□□□		Cable for interconnecting ROBONET Extension units	Fig.4
ROBONET Extension B cable	CB-REXT- CTLDDD		Cable to connect the external SIO link	Fig.5

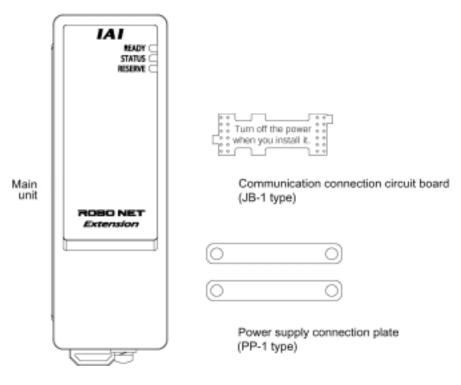
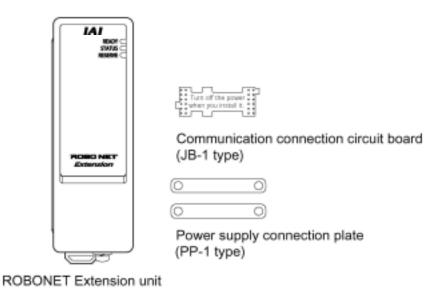


Fig.1 ROBONET Extension unit (REXT)

### IAI\_ IAI IAI STATUS MEACH STATUS furn off the pres Communication connection circuit board (JB-1 type) 0 0) (O Power supply connection plate (PP-1 type) ROBONET Extension unit ROBONET Extension A cable(

Fig.2 ROBONET Extension set A (REXT-SIO)



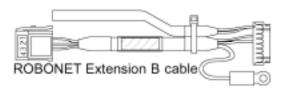
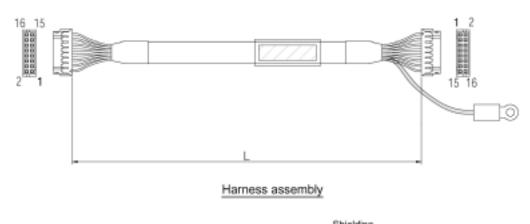


Fig.3 ROBONET Extension set B (REXT-CTL)



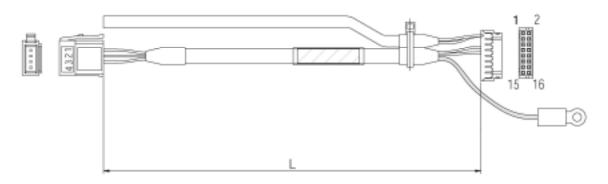
			Shielding		
DF11-16DS-2	C			DF11-	-16DS-2C
Signal No.	Black2/White	/	Black2/White	No.	Signal
/RSV1 16 RSV1 15	Red2/White	X	Red2/White	16	/RSV1 RSV1
ROUT 14	Black2/Gray	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~	Black2/Gray	14	ROUT
ROUT 13	Red2/Gray	XX	Red2/Gray	13	ROUT
/R5V0 12	Black2/Orange Red2/Orange	XX	Black2/Orange Red2/Orange	12	/RSV0
RSV0 11	Black1/Pink		Black1/Pink	11	RSV0
JENA 10 ENA 9	Red1/Pink	)//	Red1/Pink	10	(ENA. ENA
COM2 8	Black1/Yellow		Black1/Yellow	8	COM2
COM1 7	Red1/Yellow	X	Red1/Yellow Black1/White	7	COM1
SD- 6	Black1/White Red1/White	- W	Red1/White	6	SD-
SD+ 5	Black1/Gray		Black1/Gray	5	SD+
RD- 4 RD+ 3	Red1/Gray	X	Red1/Gray	3	RD-
EMG- 2	Black1/Orange		Black1/Orange	2	EMG-
EMG+ 1	Red1/Orange	X	Red1/Orange	1	EMG+
	U		Drain	RAV1	

Wring color explanation: dot color, number/insulation color Connection diagram

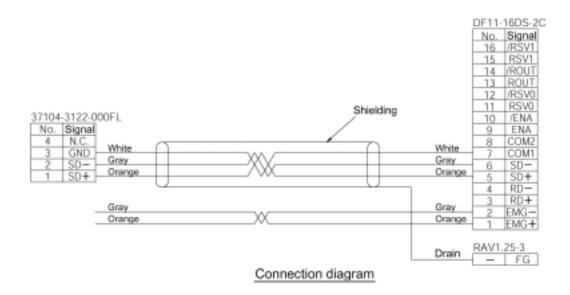
※□□□ is the cable length (L) Example: 010 = 1 m

IAI\_

Fig.4 ROBONET Extension A cable (CB-REXT-SIO



Harness assembly



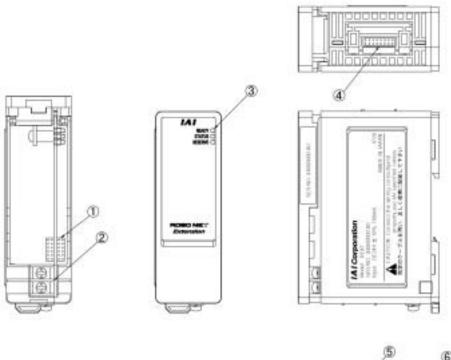
Is the cable length (L) Example: 010 = 1 m

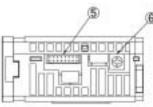
IAI\_

Fig.5 ROBONET Extension B cable (CB-REXT-CTLDD)

## 4. Part names and external dimensions

### 4.1 Part names





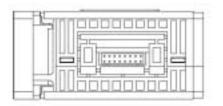
Number	Name	Description		
	ROBONET communication connector	Communication connector for connecting units in the same row. Connect with the ROBONET communication connection circuit board (JB-1).		
	Power supply terminal block Use this input terminal block to connect DC 24V to the un terminal is for the +24V, the bottom terminal is for the 0 connection. Use a maximum of 6 mm wide M3 round terminals to co power supply wires. Use the power supply connection plates (PP-1) for inter units in the same row.			
	Indicator LED READY	Displays the status of the internal power (5V) • Green light : Normal • No light : internal power failure		
	STATUS	<ul> <li>Displays the connection status of connectors and .</li> <li>Green light : Normal (only one of the connectors is connected)</li> <li>Red light : Error (both connectors are connected)</li> <li>No light : Error (none of the connectors are connected)</li> <li>If the external SIO link connection is used, this LED is not lit.</li> </ul>		
	RESERVE	Not used Normally not lit		

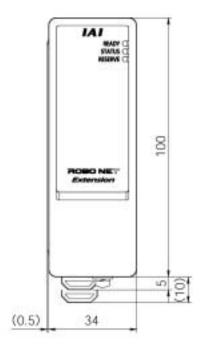


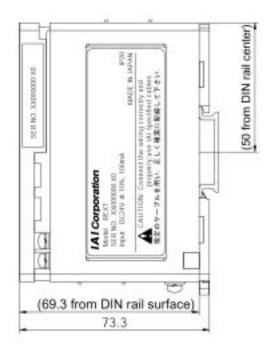
ROBONET

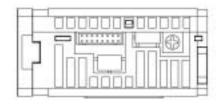
Number	Name	Description		
	Connector to upstream units	This connector is used to connect to the upstream (upper row) units via the ROBONET Extension A cable (CB-REXT-SIO).		
Connector to downstream units		This connector is used to connect to the downstream (lower row) units via the ROBONET Extension A cable (CB-REXT-SIO). If the external SIO link connection is used, then the ROBONET Extension B cable (CB-REXT-CTL) should be used.		
	FG terminal block	Use this terminal block to connect the ground wire (M3 round terminal). Use this terminal block to connect the shield wire of the ROBONET Extension A cable (CB-REXT-SIO) or the ROBONET Extension B cable (CB-REXT-CTL).		

#### 4.2 External dimensions









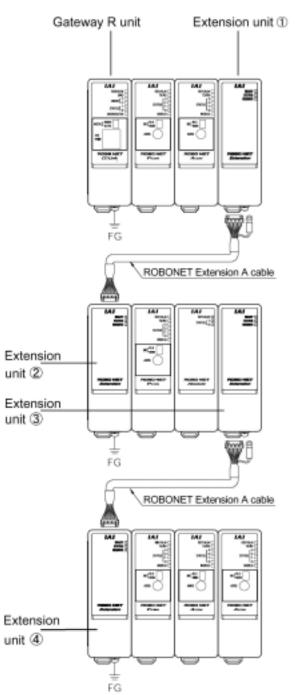
#### 5. Connection procedures 5.1 ROBONET system in a multi-row arrangement

The illustration on the right shows an example of a multi-row arrangement.

- (1) The units are connected to a DIN rail.
- (2) Install the Extension unit connecting downstream (to the lower row) in the rightmost position. (Extension units , )
- (3) Install the Extension unit connecting upstream (to the upper row) in the leftmost position.
   (Extension units , )
- (4) Connect the upstream (upper row) downstream and (lower row) units Extension usina the ROBONET Extension A cable (CB-REXT-SIO), and connect the grounding wire with an M3 round terminal to the FG terminal block of upstream Extension unit. the (Extension units , ) Connect the FG terminals of the

downstream Extension unit ( , ) to the ground terminal of the control panel, the same way as the Gateway R unit is connected.

- (5) The terminal resistor board that is enclosed with the Gateway R unit should be installed on the rightmost unit of the last downstream row (bottom row).
- (6) Connect the Extension unit to the adjacent unit using the enclosed power supply connection plate and the communication connection circuit board.
- (7) Connect the power supply (+24V, 0V) to the leftmost unit of each row. Make sure the power-up time is the same for all rows.



Warning:

1. The 0V of the supply power (+24V, 0V) to each row should be common.

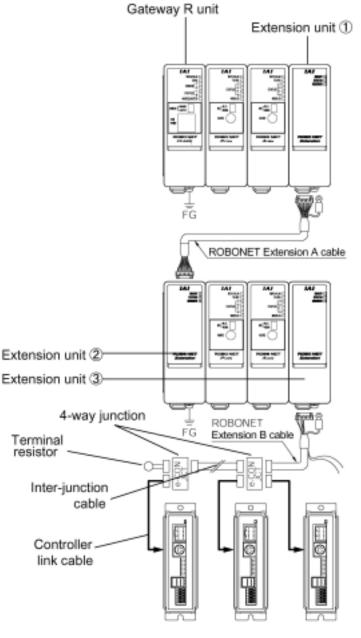
2. The RABU unit (Simple absolute R unit) paired with the RPCON or RACON unit must be installed in the same row.

#### 5.2 External SIO link

The illustration on the right shows an example of the external SIO link.

The first row and the second row are in a multi-row arrangement, where the SCON or the PCON-CF is connected to the last unit of the second row (Extension unit ) via SIO link.

- (1) The various units are connected to a DIN rail.
- (2) The first and second rows of the multi-row arrangement are the same as under 5.1, please refer to the explanation presented there.
- (3) Connect the Extension unit to the adjacent unit using the enclosed power supply connection plate and the communication connection circuit board.
- (4) Place the Extension unit that is used for the external SIO link (Extension unit ) in the last slot of the last downstream row (bottom row). Connect the ROBONET Extension B cable (CB-REXT-CTL) to the downstream connector of the Extension unit. Connect the grounding wire with an M3 round terminal to the FG terminal block.
- (5) Connect the e-CON side of the Extension B cable to the 4-way junction.
- (6) Use the optional controller link cable (CBRCB-CTL002) to connect the SCON or the PCON-CF to the 4-way



#### SCON or PCON-CF

junction. Use the following accessories that are supplied with the controller link cable (CBRCB-CTL002) to make the connections illustrated on the right.

- 4-way junction (AMP 5-1473574-4) x 1
- e-CON connector (AMP 4-1473562-4) x 1
- Terminal resistor 220Ω (with e-CON connector) x 1

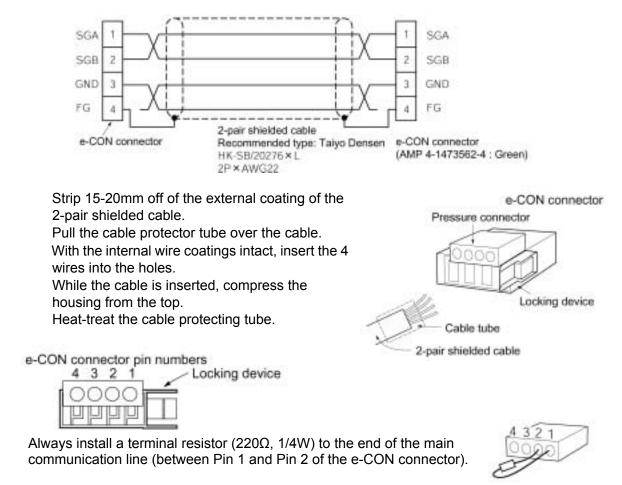
Create the inter-junction cable using the e-CON connector listed above.

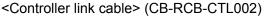
(7) There is no need to use the supplied terminal resistor with the Gateway R unit. (Do not install it on the ROBONET controller.)

Install the  $220\Omega$  terminal resistor supplied with the controller link cable to the last 4-way junction of the SIO link.

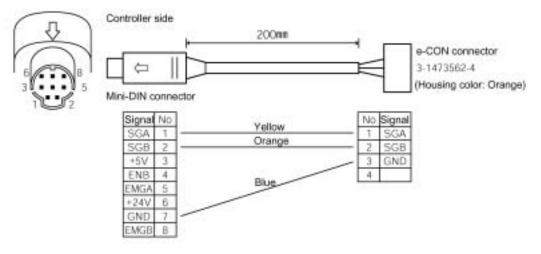
<Creating the intra-junction cable>

 $IAI_{-}$ 





This cable can be purchased separately as an optional accessory to the controller.

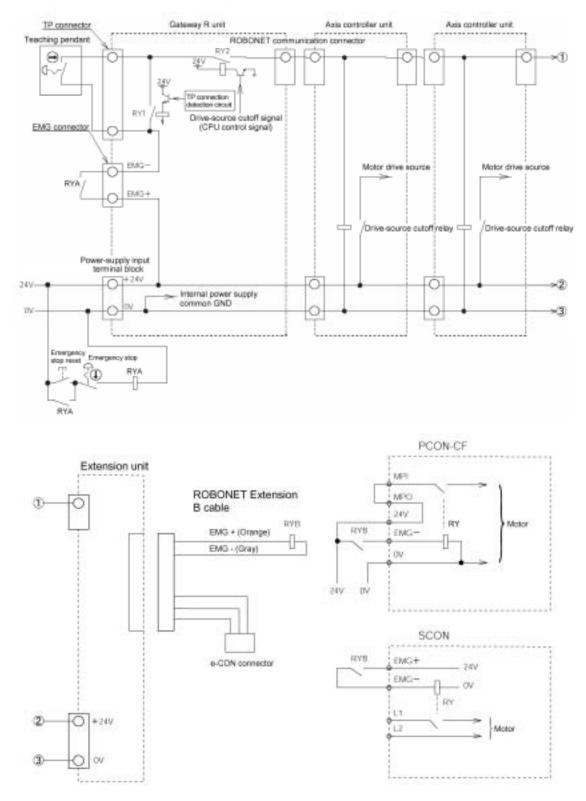


The following parts are supplied with the cable:

4-way junction	Type: 5-	1473574-4	Manufacturer: AMP	x 1			
e-CON connector	4-14735	62-4	Manufacturer: AMP	x 1			
	Compatible wire diameter including insulation: 1.35~1.6mm						
Terminal resistor	220Ω	1/4W	Supplied with the e-CON connector	x 1			

### 5.3 Emergency stop circuit

The diagram below shows the emergency stop circuit for the external SIO link.



Warning: 1. Select the RYA relay with a minimum rated contact capacity of 160mA.

- 2. Select the RYB relay so the coil current rated value satisfies the following formula:
- 10mA x No. of ROBONET controllers + RYB coil current rating ≤ 160mA.
   The 0V side of the 24V power supply of the ROBONET controller and the 0V side of the PCON-CF power supply should be common.

### 6. Other important points

IA

The followings must be noted regarding the status of the SW1 user setting switch of the Gateway R unit:

(1) If SW1 = OFF (TP enable switch signal disabled)

Regardless of the enable operation parameter of the Gateway parameter setting tool, the connected RPCON, RACON, PCON-CF, SCON does not respond to the TP enable switch signal.

(2) If SW1 = ON (TP enable switch signal enabled)

When the enable operation parameter setting is "Shutdown control": The TP enable switch becomes disabled, and the connected RPCON, RACON, PCON-CF, SCON units go into stop status (servo off → drive source cutoff).

When the enable operation parameter setting is "Servo control":

The TP enable switch becomes disabled, and the connected RPCON, RACON units go into stop status (servo off), but the PCON-CF, SCON units don't stop, they continue their operation.

## 7. SCON/PCON-CF settings and signal allocation when using the external SIO link

The SCON can only operate in positioner mode. It cannot be operated in pulse train input mode. The following settings are required for operation:

#### (1) User parameters

Number	Name	Setting (change) description	SCON	PCON-CF
16	SIO communication speed	38400bps (Default value) →change to 230400bps	Yes	Yes
17	Slave transmitter activation Minimum delay time	5msec (Default value) →change to 2msec	Yes	Yes
25	PIO pattern selection	Default value 0 (Standard type) →Set to 0~3 (*See Note)	Yes	Yes
74	PIO power monitor	Default value 0 (Enabled) →change to 1 (Disabled)	Yes	No

\*Note: The 4 and 5 solenoid valve mode settings cannot be used. The maximum number of positions that can be registered depends on the selected mode.

(2) Piano switch (SCON only)

Set the SCON to positioner mode by turning the first piano switch OFF on the front panel.

(3) Mode switch

Set the mode switch on the front panel of the SCON/PCON-CF to AUTO.

- (4) Signal allocation The signal allocation of the SCON/PCON-CF is the same as of the RPCON/RACON. Refer to the specifications in the ROBONET user manual.
- (5) Use the rotary switch for setting the axis number.

Catalog No.: MJ0189-1A (10/2007)



## IAI America, Inc.

Head Office: 2690 W. 237th Street, Torrance, CA 90505 TEL (310) 891-6015 FAX (310) 891-0815 Chicago Office: 1261 Hamilton Parkway, Itasca, IL 60143 TEL (630) 467-9900 FAX (630) 467-9912 Atlanta Office: 1220 E. Kenneston Circle, Marietta, GA 30066 TEL (678) 354-9470 FAX (678) 354-9471

Website: www.intelligentactuator.com

### IAI Industrieroboter GmbH

Ober der Röth 4, D-65824 Schwalbach am Taunus, Germany TEL 06196-88950 FAX 06196-889524

The information contained in this document is subject to change without notice for the purpose of product improvement. Copyright © Oct. 2007. IAI Corporation. All rights reserved.