

TRANSDUCER of TEMPERATURE and STANDARD SIGNALS P20 type



USER'S MANUAL



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1. APPLICATION

The P20 programmable transducer is designed to convert temperature, resistance, voltage from a shunt and standard signals into a constant-current or constant-voltage standard signal.

The output signal is galvanicaly isolated from the input signal and supply.

The transducer compensates automatically the resistance of wires in case of resistance value measurements in a three-wire system and automatically compensates the temperature of terminals in case of measurements from thermocouples.

The transducer is fully configurable through the PD14 programmer. By means of this programmer, one can change the input type, the measurement averaging time and rescale the analog output acc. to the individual output characteristic, and also read out the measured value.

2. TRANSDUCER SET

The set of the P20 transducer is composed of:

- P20 transducer
- User's manual
- Guarantee card
- Plug with screw terminals
- Hole plug of the programmer socket
1 pc.
2 pcs.
1 pc

When unpacking the transducer, please check whether the type and execution code on the data plate correspond to the order.



3. OPERATIONAL SAFETY

In the safety service scope, the transducer meets to requirements of the EN 61010-1 standard.

Observations concerning the operational safety

- All operations concerning transport, installation, and commissioning as well as maintenance, must be carried out by qualified, skilled personnel, and national regulations for the prevention of accidents must be observed.
- Before switching transducer on, one must check the correctness of connections to the network.
- When connecting the supply, one must remember that a switch or a circuit-breaker should be installed in the building. This switch should be located near the device, easy accessible by the operator, and suitably marked as an element switching the transducer off.
- Do not connect the transducer to the network through an autotransformer.
- Before removing the transducer housing, one must switch the supply off and disconnect measuring circuits.
- The removal of the transducer housing during the guarantee contract period may cause its cancellation.
- The programmer socket is only use to connect the PD14 programmer. After the transducer programming, one must insert the hole plug.
- Non-authorized removal of the housing, inappropriate use, incorrect installation or operation, creates the risk of injury to personnel or a transducer damage.
 - For more detailed information, please study the User's Manual.

4. INSTALLATION

4.1. Fitting way

P20 transducers are designed to be mounted on a 35 mm rail according to EN 60715.

Housing dimensions are: 22.5 x 120 x 100 mm.

On the transducer outside, there are screw or self-locking terminal strips, which make possible the connection of external wires with a 2.5 mm² cross-section (supply and output) and up to 1.5 mm² (input).

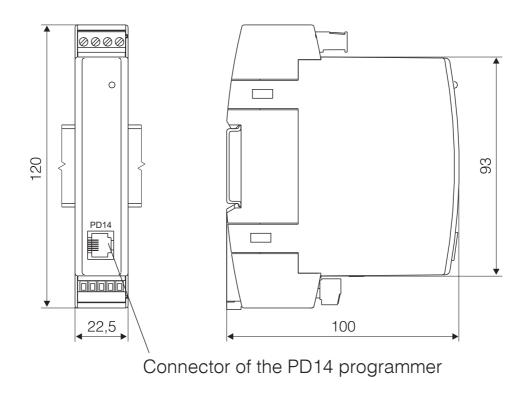


Fig. 1. Overall dimensions and fitting way of the transducer

Transdusers should be mounted on the rail in direct contact with another devices that emit heat (eg transducer P20). You must keep a minimum 5 mm distance between the devices to allow emit heat from the housings to the ambient. Otherwise, the in rated operating temperature of transducer which is in direct contact with the other transducer may exceed the rated operating temperature stated operating conditions.

4.2. External electrical connection diagrams

The transducer has two sockets of terminal strips, which two plugs with terminal screws are connected to. The way to connect external signals is shown on the fig.1

The electrical connection diagram is also situated on the transducer housing. In case of the transducer work in an environment with high interferences, one must apply shielded wires in the transducer input.

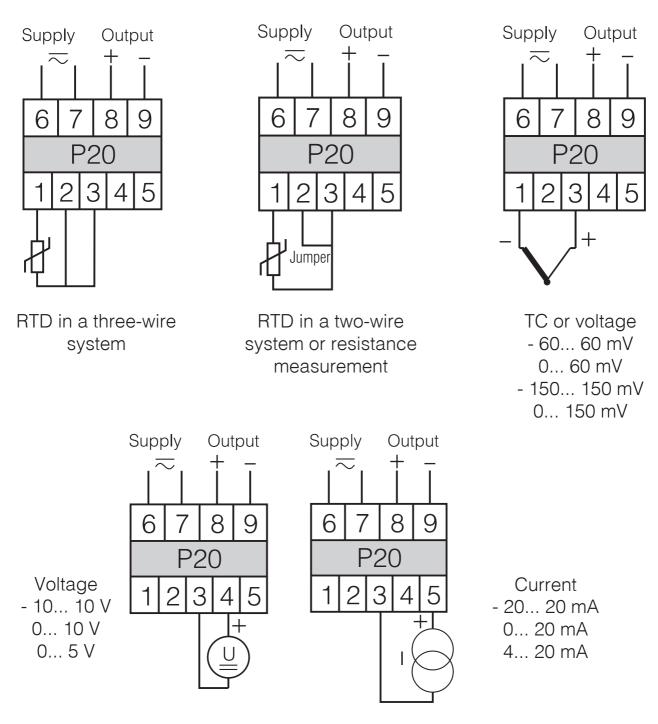
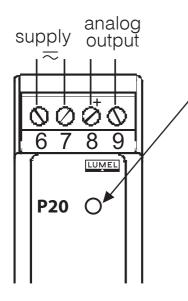


Fig. 2. Electrical connection diagrams of the P20 transducer.

5. SERVICE

After switching the transducer on, the work state diode should light in red for a moment, next it should light in green.



Diode of the transducer work state:

- the state diode lights in green normal work,
- the state diode lights in red improper work parameters; one must configure the transducer again,
- the state diode pulsates in red lack of calibration or the non-volatile memory is damaged; one must return the transducer to the manufacturer.

Fig. 3. View of the P20 transducer

Confirmation of the separator's communication with PD14 programmer is indicated by the status diode which turns off for short period of time.

5.1. Transducer configuration by means of the LPCon program

The LPCon program is destined for the P20 transducer configuration. One must connect the PC computer through the PD14 programmer and configure the connection choosing *Option -> Connection configuration* from the menu (for the P20 transducer, we choose the address 1, baud rate 9600 kb/s, the mode RTU 8N2 and the appropriate port COM under which the controller of the PD14 programmer has been installed).

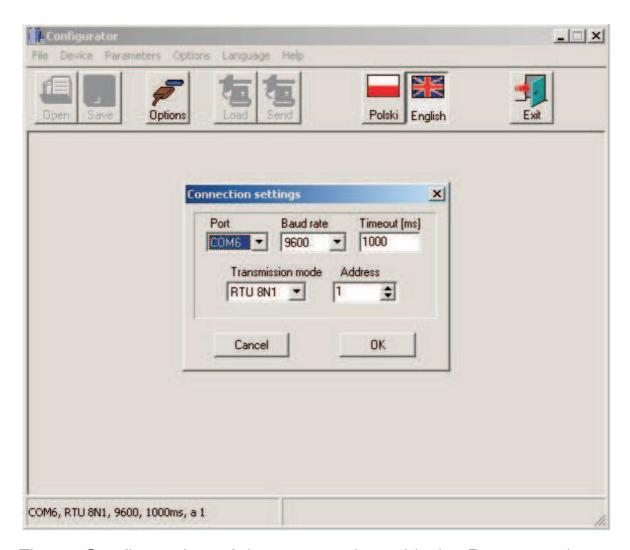


Fig. 3. Configuration of the connection with the P20 transducer.

After the connection configuration, one must choose **Device -> Trans-ducers P -> P20** from the menu, and next click the **Readout** icon in order to read out all parameters. One can also read out parameters individually in each group clicking the **Refresh** push-button.

5.1.1 Configuration of the transducer input type

Three developable lists are accessible in the parameter group "Input configuration", by means of which, one can choose the input type, the measuring range and the measurement averaging time. One must confirm changes, clicking the *Apply* push-button.

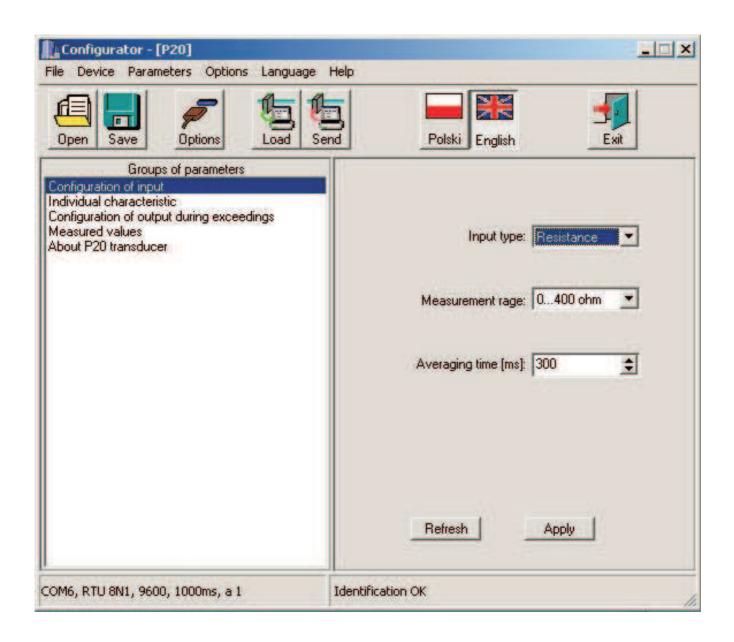


Fig. 4. View of the LPCon program window "Input configuration"

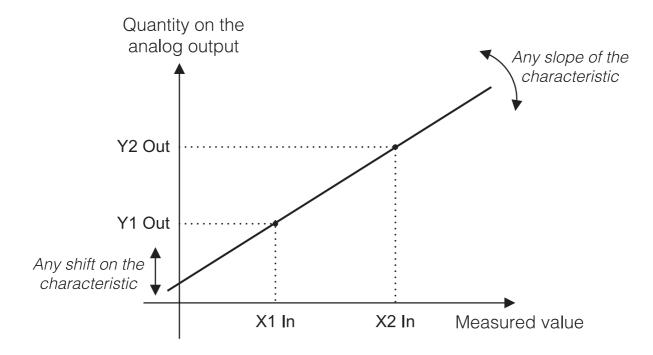
5.1.2. Configuration of the analog output characteristic

The P20 transducer enables the conversion of measured values into an output signal on the base of the individual linear characteristic of the analog output. On the base of given by the user coordinates of two points, the transducer determines (from the system of equations) coefficients **a** and **b** of the individual characteristic.

$$\begin{cases} Y1 Out = a \cdot X1 \ln + b \\ Y2 Out = a \cdot X2 \ln + b \end{cases}$$

where:

X1 In and X2 In – measured value Y1 Out and Y2 Out – expected value on the output



The X1 In value on the transducer input

=> Y1 Out value on the analog output

The X2 In value on the transducer input

=> Y2 Out value on the analog output

Other points of the characteristic are calculated

Fig. 5. Individual characteristic of analog outputs

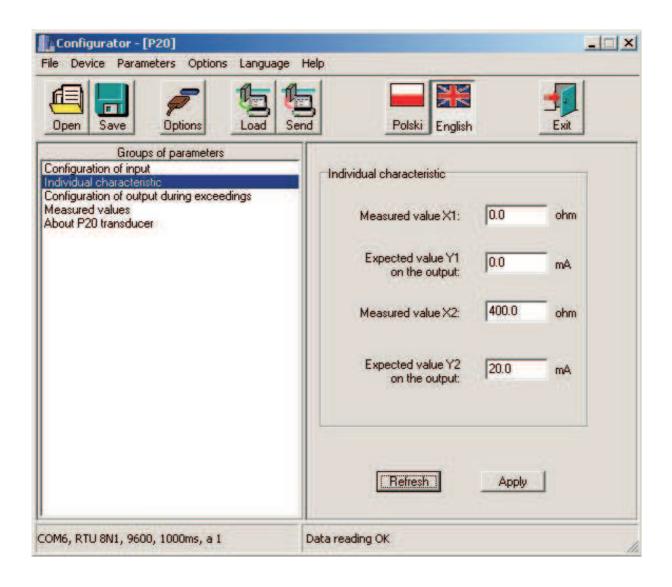


Fig. 6. View of the LPCon program window "Individual characteristic"

5.1.3. Configuration of the analog output at overflows

The user has the additional possibility in the P20 transducer to configure the preservation of the analog output after the signal overflow occurrence on the measuring input. By default, the service of overflows is switched out – then, after the signal overflow on the input, the output is still proportional to the steered up input beyond the basic output range. After switching the overflow service on, the user can define himself by

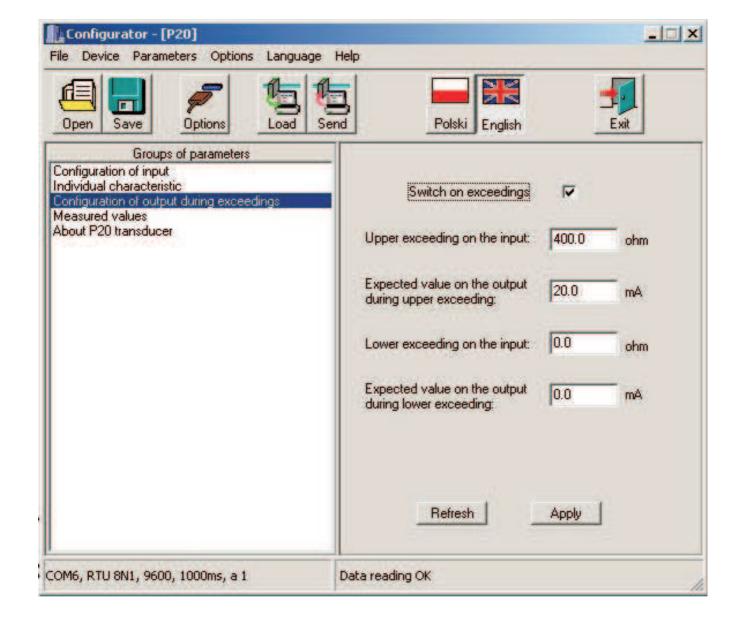


Fig. 7. View of the "Output configuration at overflows" window of the LPCon program.

5.1.4. Readout of the measured value

By means of the LPCon program, one can also read out the actually measured value, check the output type, read out the factory serial number and the programming version. These quantities are located in the *Measured values* window.

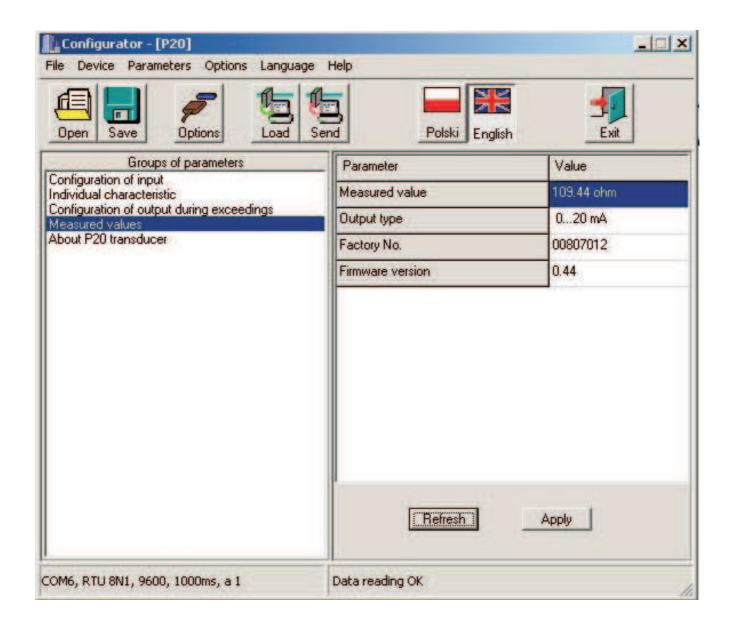


Fig. 8. View of the "measured values" window of the LPCon program

6. TECHNICAL DATA

Basic parameters:

		_ 1 _ 1		1 ' 1		the self-self-self-self-self-self-self-self-
-	analog	output	ga	ıvanıcaı	V	isolated:

- current	0/420 mA
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- voltage 0...10 V

- maximal load resistance of the

current output $\leq 500 \Omega$

 minimal load resistance of the voltage output

 $\geq 500 \ \Omega$

- accuracy class¹⁾ 0.2

- averaging time of the transducer:

- range: d.c. current [mA], d.c. voltage [V] ≥ 0.1 s

- other ranges $\geq 0.3 \text{ s}$

- consumption < 2 VA

- preheating time of the transducer 10 min

- transducer response time:

- range: d.c. current [mA], d.c. voltage [V] ≥ 0.2 s

- other ranges ≥ 0.4 s

- current flowing through RTD < 0.2 mA

- resistance of wires connecting

RTD with the transducer $\leq 10 \Omega$

Rated operating conditions:

- supply depending on the

execution code 85... 253 V a.c./d.c.

20...85 V d.c., 20...65 V a.c.

- frequency of the supply a.c. voltage 45... 65 Hz

- ambient temperature — 20...23...55°C

- storage temperature — 25...85°C

- related air humidity < 95% (condensation

inadmissible)

- working position any

Input parameters:

- resistance of voltage input [V] $> 1 \text{ M}\Omega$ - resistance of current input [mA] $12 \Omega \pm 1\%$

Sustained overload:

TC and RTD
 voltage, current and resistance
 1.1 X_n
 1.3 X_n

Short duration overload:

- voltage input- current input5 U_n10 I_n

Ensured protection level acc. to EN 60529:

housingfrom terminal sideIP 40

Dimensions: $22.5 \times 100 \times 120 \text{ mm}$

Weight: 0.125 kg

Fitting on a 35 mm DIN rail,

acc. to EN 60715

Electromagnetic compatibility:

- noise immunity EN 61000-6-2 - noise emission EN 61000-6-4

Safety requirements acc. to EN 61010-1:

- installation category III

- pollution degree 2

- phase-to-earth working voltage:

- supply 300 V²⁾
- input 50 V
- output 50 V

- altitude above sea level < 2000 m

¹⁾ A part of sub-ranges for thermocouples and RTD has a specified individual class – see table 3

²⁾ Execution for supply voltage 230 V.

7. EXECUTION CODES

Execution codes of the P20 transducer

Table 2.

TRANSDUCER	P20 -	X	X	XX	XX	X
Analog outputs:						
current 0 20 mA current 4 20 mA voltage 0 10 V		2				
Supply:			4			
85253 V a.c./d.c 20 85 V d.c., 206						
Kind of input see table 3				XX		
Execution:						
standard custom-made*						
Acceptance tests:						
without extra quality r	•					
with an extra quality i acc. to customer's re-	•					

^{*} after agreeing with the manufacturer

Type of sensor/input	Range [°C]	Kod
Pt100 RTD	-200850 0850 0600 0400 0200 -200200 -100100*	01 02 03 04 05 06 07
Pt 250 RTD	-200850 0850 0600 0400 0200 -200200 -100100	08 09 10 11 12 13 14
Pt 500 RTD	-200850 0850 0600 0400 0200 -200200 -100100	15 16 17 18 19 20 21
Pt1000 RTD	-200850 0850 0600 0400 0200 -200200 -100100	22 23 24 25 26 27 28
TC of J type	-2001200 01200 01000 0800 0600 0400* -200200*	29 30 31 32 33 34 35

TC of K type	-2001370 01200 01000 0800 0600 0400* -200200*	36 37 38 39 40 41 42		
TC of S type	01760 01600 01400* 01200* 01000*	43 44 45 46 47		
TC of N type	-2001200 01200 01000 0800 0600* 0400* -200200*	48 49 50 51 52 53 54		
d.c. voltage	010 V 05 V -1010 V -55 V 060 mV -6060 mV 0150 mV	55 56 57 58 59 60 61 62		
d.c. current	020 mA 420 mA 05 mA -2020 mA	63 64 65 66		
Resistance	0400 Ω 04000 Ω	67 68		
Custom-made execution				

^{*} accuracy class 0,5

Example of order:

When ordering, please respect successive code numbers.

The code: **P20-1.1.04.00.7** means:

P20 – transducer of temperature and standard signals

1 – with current analog output: 0...20 mA,

1 – voltage supply: 85...253 V a.c./d.c.,

04 – Pt100 input signal, 0...400°C range,

00 - standard execution

7 – with an extra quality inspection certificate

8. MAINTENANCE AND GUARANTEE

The P20 transducer does not require any periodical maintenance. In case of some incorrect operations:

After the dispatch date and in the period stated in the guarantee card:

One should return the transducer to the Manufacturer's Quality Inspection Dept.

If the instrument has been used in compliance with the instructions, we guarantee to repair it free of charge.

The disassembling of the housing causes the cancellation of the granted guarantee.

After the guarantee period:

One should turn over the instrument to repair it in a certified service workshop.

Spare parts are available for the period of five years from the date of purchase.

We reserves the right to make changes in design and specifications of any products as engineering advances or necessity requires.



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