

Features

- Actel A3P060 Low Power FPGA
- 50MHz Oscillator
- One User LED
- 1.5V LDO Regulator for FPGA Core Supply
- Single 3.3V Supply
- 30 User I/O's
- SMD or TH mountable

Design Support

Actel's free Libero 8.5 design environment can be used to create own configurations. If CoreABC is used then CoreConsole 1.4 needs to be installed also.

Programmer Support

STAMP60 can be re-programmed using a JTAG programmer/cable. Either Actel FlashPro3 or 3rd party cable can be used.

Please note that ProAsic3 FPGA's can be reprogrammed maximum 500 times as per datasheet. This doesn't mean they will stop working after 500 programming attempts, but the FPGA is not specified for a larger number of reprogramming cycles.

Open source project UrJTAG (hosted at SourceForge) can be used to play back SVF files and program the FPGA. UrJTAG supports many different JTAG Cables.

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Mount styles

The module can be mounted in different ways, either using pin headers or then as SMD component by direct solder.

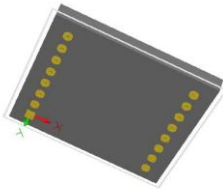
Name	Mount Type	Max User I/O
SIP	TH	6
DIP	TH	14
QIP	TH	26
SMD	SMD	30

SIP Mount

For this style of mounting only the left row (pins 1 to 8) can be used, number of useable I/O is 6. Pins 17-24 can be used as user configuration switches or header.

DIP Mount

For this style the left and right rows can be used. Total amount of useable I/O is 14.



CAD Component 3D view, 8 pins in 2 rows at 700mil distance

QIP Mount

For this style all TH rows can be used, total amount of useable I/O is 26.

SMD Mount

For this style all SMD pads can be used, total number of useable I/O is 30.

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On-Board Components

STAMP60 is mounted with the minimum set of components to make it easy to use while still keeping the cost low. For OEM orders there is a possibility of some custom assembly options.

FPGA

The main component on STAMP60 is Actel ProAsic3 family low power Flash FPGA A3P060-CN132.

Feature	
Number of Logic Cells	1536
Number of Block RAMs (512x9 bit)	4
Number of CCC (Clock Conditioning Circuit)	6
Number of PLL's (CCC's with PLL)	1

VCCIO for all banks and VJTAG/VPUMP are all tied to the single VCC pin that should normally be connected to 3.3V supply voltage.

Oscillator

A 50MHz Oscillator is mounted as default on the STAMP60. The oscillator is always enabled, it's output is connected to FPGA pin A26. Note that while A26 is Global clock input, it is not connected to CCC with integrated PLL. So when using a PLL the clock to PLL input must be routed using other global clock lines (not using the PLL own hardwired input pads).

User LED

One Red color LED is available on the board, it is "On" when FPGA Output is logic 1. Connection to FPGA pin A37 via 1K series resistor.

Note that the LED will be "dimmed On" while programming the FPGA, this due to the pull-ups that are normally enabled during the programming.

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FTDI Support

STAMP60 can be used in different ways with the FTDI USB devices.

Clock generator

STAMP60 can deliver 6MHz clock for the older FT232/FT245 devices and for FT2232. So the BOM is reduced by 2 Capacitors and a Crystal.

93C46 Emulation

Serial EEPROM can be emulated, including the resistor that is normally needed for the connection to FTDI devices. So the BOM is reduced by 2 components (1 resistor and 93C46 EEPROM).

User Logic

Different user logic can be implemented by the STAMP60.

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CAD Support

Libraries are available for several popular CAD tools.

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Demo Designs

List of available demo designs, supplied as Libero projects, with full source code and ready to download programming files.

LED blinker

A simple clock divider makes an human eye visible blink on the LED from the on-board 50MHz oscillator.

FPGA Oscillator Test

This is a simple design that demonstrates the use of an oscillator made from FPGA primitives. The CLKDLY primitive is used, also one global I/O pin. The frequency can be set by selecting the 5 bit delay parameter. Please note that the delay cannot be changed dynamically, it has to be fixed during bitstream generation.

The demo will blink the LED at rate $f_{osc}/2^{24}$, the output clock of the oscillator is available on pin 2. All other pins are not actively driven (configured as inputs). The oscillator is configured to lowest frequency (delay code 11111). The LED blinks at about 2 Hz rate.

In the demo design the clock output pin is the same pin used in the oscillator as part of the loopback, so the capacitive loading on this pin will change the frequency. For real designs some free unused pin should be used instead.

For best temperature stability the lowest frequency setting should be used, because then most of the delay is introduced by the CLKDLY primitive and the I/O pad parameters have less impact on the frequency.

For STAMP60 there is no reason to ever use this type of oscillator, as the module has on-board oscillator. This design is provided as demonstration only. In some ultra low cost designs this type of oscillator maybe sufficient if exact clock is not needed.

This demo is implemented as single VHDL file, the I/O constraints are entered in the Designer I/O Editor.

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Source code for the On-Chip Oscillator Demo

```
-----
-- Company: Trioflex OY http://www.trioflex.com
-- Engineer: Antti Lukats
-----

library IEEE;
use IEEE.STD_LOGIC_1164.ALL;
use IEEE.STD_LOGIC_ARITH.ALL;
use IEEE.STD_LOGIC_UNSIGNED.ALL;
-- we need ProAsic3 technology primitives
library proasic3;
use proasic3.all;

entity top is Port (
    en    : in STD_LOGIC;    -- must be connected to GND (or use pulldown)
    clkout : inout STD_LOGIC; -- must be global clock capable pin
    LED    : out STD_LOGIC );
end top;

architecture Behavioral of top is

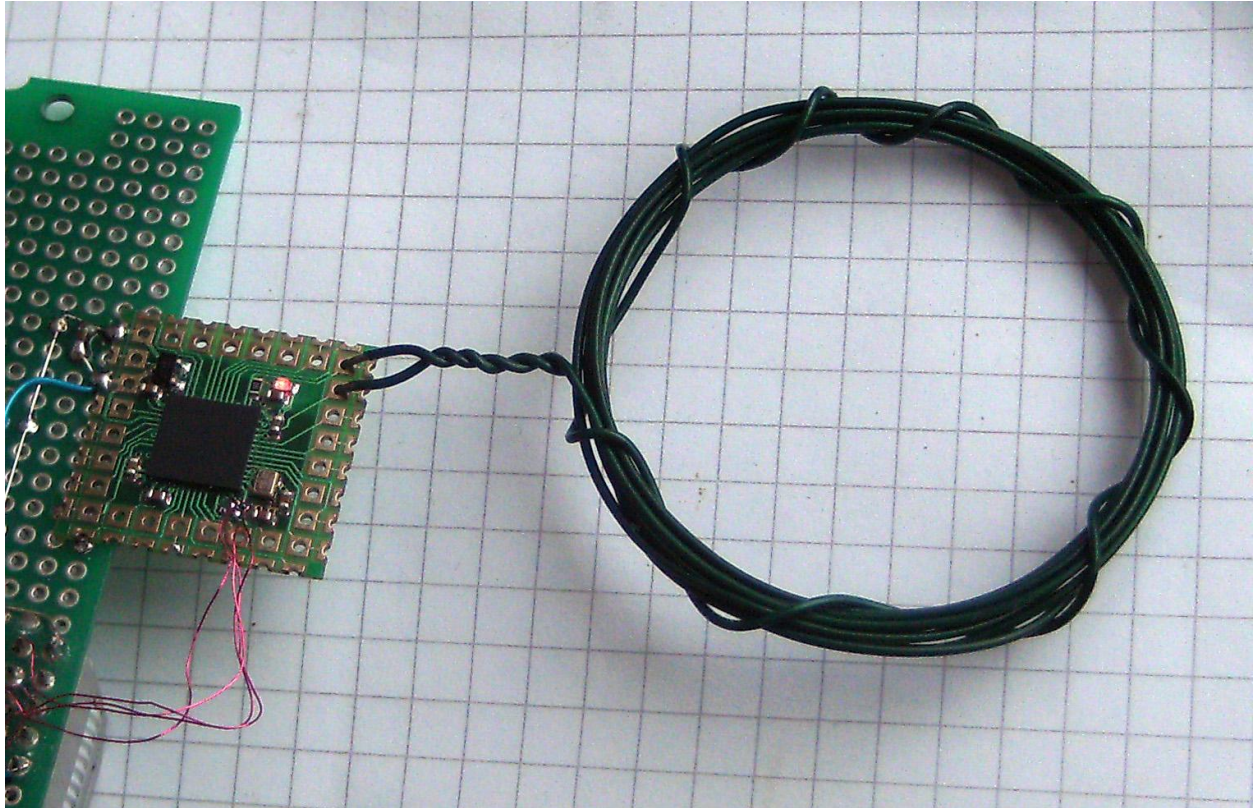
component CLKDLY port(
    CLK : in std_logic := 'U'; GL : out std_logic; DLYGL0, DLYGL1, DLYGL2, DLYGL3, DLYGL4 : in std_logic := 'U' );
end component;

signal prescaler: std_logic_vector (23 downto 0);
signal gl: std_logic;

begin
    -- Divide the clock for Eye visible blink rate
    process (gl) begin
        if (rising_edge(gl)) then
            prescaler <= prescaler + X"000001";
        end if;
    end process;
    -- drive the LED
    LED <= prescaler(23);
    -- en is a pin that is externally connected to GND so we use it as known const 0, but synthesis
    -- doesn't know this, so the bibuf will remain in the code (is not optimized away)
    clkout <= (not gl) when en='0' else 'Z'; -- we need an inverter to make it oscillate!
    -- the CLKDLY primitive
    InstCLKDLY : CLKDLY
        port map(
            CLK => clkout,
            GL => gl,
            DLYGL0 => '1', -- set the frequency
            DLYGL1 => '1', -- 1111 is the lowest setting
            DLYGL2 => '1',
            DLYGL3 => '1',
            DLYGL4 => '1'
        );
end Behavioral;
```


L(C) Oscillator Demo

L(LC) oscillators seem to be fully forgotten art, but they may have a new second life for some applications. Philips (now NXP) Application Note AN456 is a good description how to implement LC oscillator for MCU clocking. An logic can also be used to implement a LC oscillator, actually all we need is a single inverter connected to I/O Pins.



LC Oscillator test, STAMP60 rev A is used. There are no C added so only the pin capacitance is working as part of the LC circuit. For real designs some extra C should be added.

The L can be implemented as PCB spiral inductor so its cost is very low.

Another interesting application would be using PCB inductors for touchless inductive sensor. Microchip has lots of information how to implement inductive touch sensors using Microchip PIC microcontrollers. But an FPGA could do the same with almost no extra circuitry, it is sufficient to make the sensors to oscillate and measure the frequency change. Extra analog circuitry should not be necessary.

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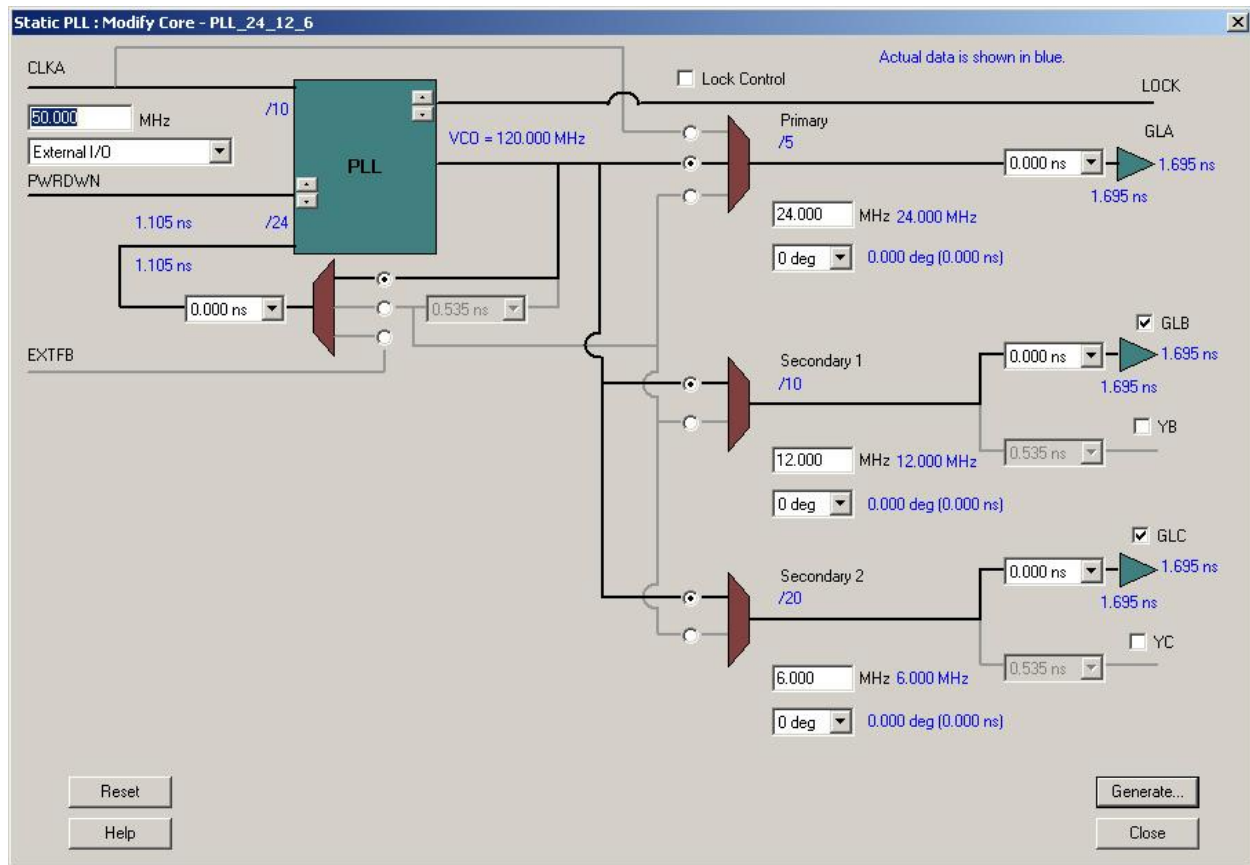
RISC 5X SoC Demo

In preparation

A RISC Core compatible to Microchip 5X family takes approximately 50% of the A3P060 FPGA logic resources.

Fixed PLL Demo

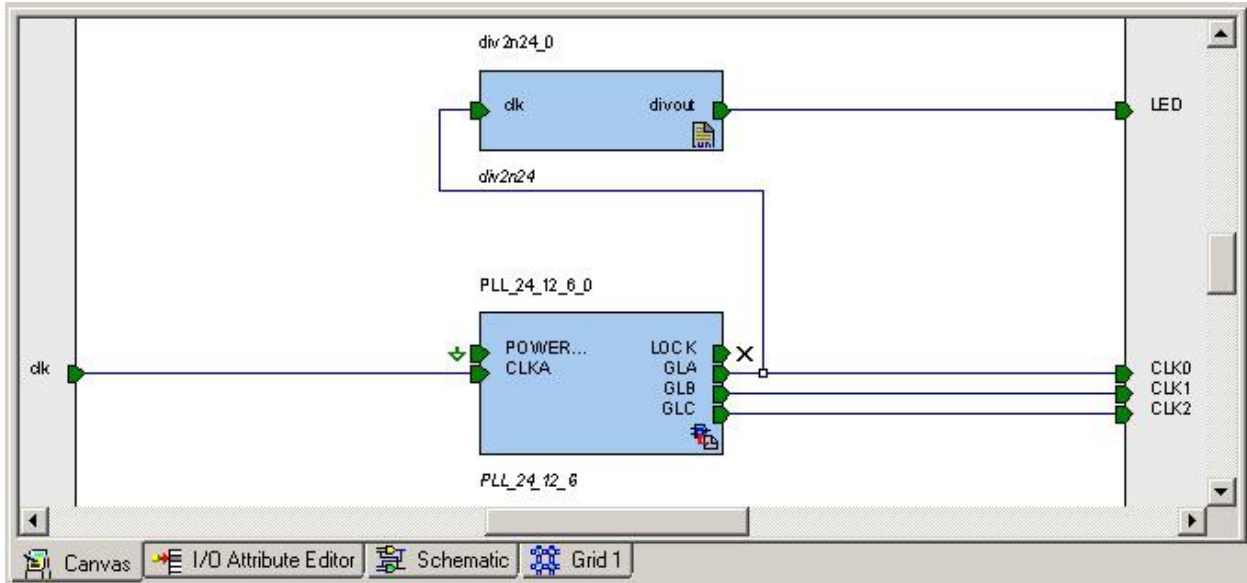
This demo uses a PLL to generate a fixed set of output frequencies.



This is the static PLL wizard screen that was used for the demo. Please note that clock input is not selected as "Hardwired I/O" as the 50MHz clock is coming from Global clock pin connected to CCC without integrated PLL.

This design is implemented using Actel Smart Design as top level. A LED (with divider) is connected to the GLA output.

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Canvas view of the Smart Design. This is auto generated view!

	Port Name▲	Group	Macro Cell	Direction	Pin Number	Locked	Bank Name	I/O Standard	Output Drive (mA)
1	clk			Input	A26	<input checked="" type="checkbox"/>	Bank0	LVTTL	--
2	CLK0			Output	A1	<input checked="" type="checkbox"/>	Bank1	LVTTL	12
3	CLK1			Output	A2	<input checked="" type="checkbox"/>	Bank1	LVTTL	12
4	CLK2			Output	A4	<input checked="" type="checkbox"/>	Bank1	LVTTL	12
5	LED			Output	A37	<input checked="" type="checkbox"/>	Bank0	LVTTL	12

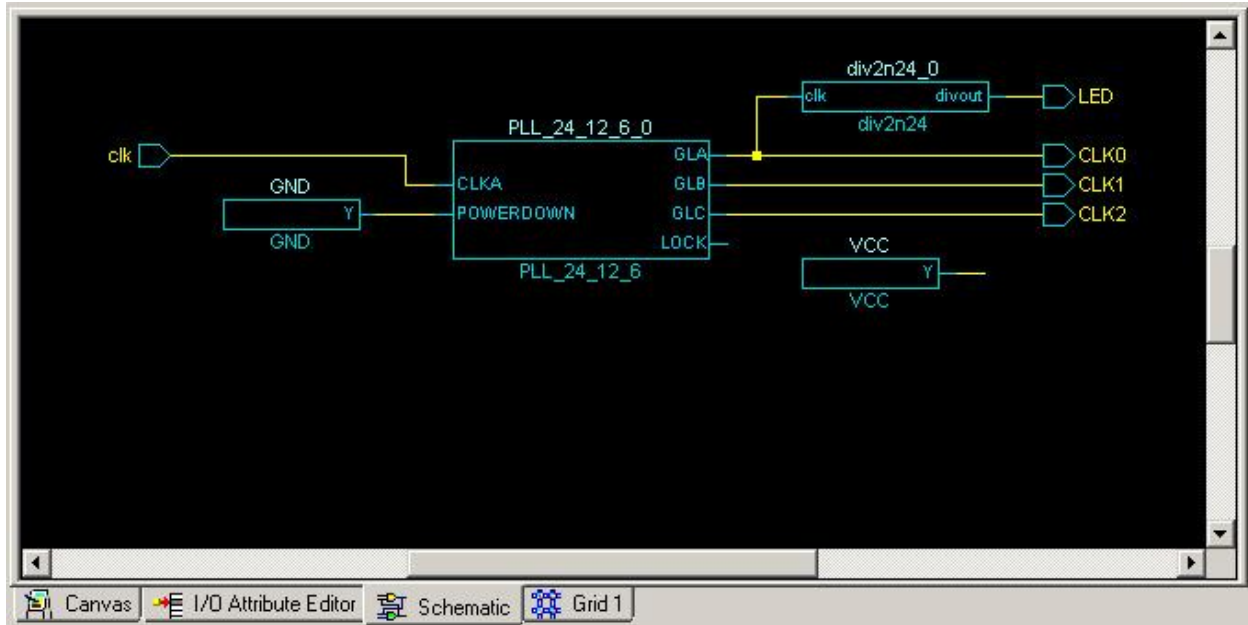
[Click here to add a port...](#)

Ports Package Pins

Canvas I/O Attribute Editor Schematic Grid 1

I/O view of the Smart Design. This is where the I/O pins are assigned to package pins and attributes like pull-up can be assigned.

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Schematic view of the Smart Design. This is auto generated view!

Instance-Instance View

			Attribute	myPLL	Instances	
Instance	Port Name	Slice			div2n24_0	PLL_24_12_6_0
myPLL	clk				CLKA	
	CLK0				GLA	
	CLK1				GLB	
	CLK2				GLC	
	LED			divout	GLA	
div2n24_0	clk					
	divout		LED			
PLL_24_12_6_0	CLKA					
	GLA		clk	clk		
	GLB					
	GLC					
	LOCK					
	POWERDOWN					

Grid view of the Smart Design. This is where the connections are made between components and top level ports.

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CoreABC/CorePWM Demo

This is a simple demo for Actel CoreABC (a soft Microcontroller core) and CorePWM IP's. A divider is added that creates a slow "flag" on CoreABC input port0. CorePWM is configured with Max period 255 so the settings 100 is about 40% of maximum.

Instance	myabc	CLKINT_0	CoreAPB3_0	corepwm_0	div2n24_0	mycore_0
myabc	A					
LED [0]				PwM[1]		
CLKINT_0	clk			PCLK	clk	PCLK
CoreAPB3_0	0	0	3	1	0	1
corepwm_0			APBmslave0			
div2n24_0	LED[0]	Y				PRESETN
mycore_0	0	1	1	2	2	IO_IN[0]

Notes(For Libero 8.5):

- Minimum number of APB slots is 2
- Minimum width of INPUT port is 2
- LED must be defined as bus with the width 1
- CLKINT must be instantiated manually

If any of the above settings is different the system will not build.

Source code of the demo program

```

DEF PWM0 0
// Enable PWM0
  APBWRT DAT8 PWM0 0x08 1
$MyLoop
  JUMP IF INPUT0 $Set1
  APBWRT DAT8 PWM0 0x14 50
  JUMP $MyLoop
$Set1
  APBWRT DAT8 PWM0 0x14 100
  JUMP $MyLoop

```

The above code will change the LED intensity from 20% to 40% at slow rate (controlled by INPUT0). This design uses 249 Logic Cells. As the program code ROM is implemented from logic resources so the resource utilization depend on the program used.