

# USER GUIDE

## Resolution T<sup>®</sup> GPS Embedded Board

  
**The right one.**<sup>™</sup>

 **Trimble.**



# USER GUIDE

## **Resolution T<sup>®</sup> GPS Embedded Board**

Version 2.0  
Revision B  
Part Number 54655-05-ENG  
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Meerheide 45  
5521 DZ Eersel, NL



# Safety Information

## Warnings and Cautions

An absence of specific alerts does not mean that there are no safety risks involved. Always follow the instructions that accompany a Warning or Caution. The information they provide is intended to minimize the risk of personal injury and/or damage to the equipment. In particular, observe safety instructions that are presented in the following formats:



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**WARNING** – A Warning alerts you to a likely risk of serious injury to your person and/or damage to the equipment.

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**CAUTION** – A Caution alerts you to a possible risk of damage to the equipment and/or loss of data.

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## Operation and storage



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**WARNING** – The Resolution T GPS receiver is ready to accept TSIP commands approximately 2.1 seconds after power-up. If a command is sent to the receiver within this 2.1 second window, the receiver will ignore the command. The Resolution T GPS receiver will not respond to commands sent within the 2.1 second window and will discard any associated command data.

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**WARNING** – Operating or storing the Resolution T GPS timing receiver outside the specified temperature range can damage it. For more information, see the product specifications on the data sheet.

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## Routing any cable



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**CAUTION** – Be careful not to damage the cable. Take care to avoid sharp bends or kinks in the cable, hot surfaces (for example, exhaust manifolds or stacks), rotating or reciprocating equipment, sharp or abrasive surfaces, door and window jambs, and corrosive fluids or gases.

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## AC adaptor safety

An international adaptor kit is provided with the Resolution T Starter Kit.



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**WARNING** – Using an incorrect AC adaptor can damage your product and may void your warranty. To use AC adaptors safely:

- Use only the AC adaptor intended for the Resolution T GPS timing receiver. Using any other AC adaptor can damage your product and may void your warranty.
  - Do not use the AC adaptor with any other product.
  - Make certain that the input voltage on the adaptor matches the voltage and frequency in your location.
  - Make certain that the adaptor has prongs compatible with your outlets.
  - AC adaptors are designed for indoor use only. Avoid using the AC adaptor in wet outdoor areas.
  - Unplug the AC adaptor from power when not in use.
  - Do not short the output connector.
  - There are no user-serviceable parts in this product.
  - Should damage to the AC adaptor occur, replace it with a new Trimble AC adaptor.
-

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# Introduction

## In this chapter:

- Operation
- Timing features
- Starter kit
- Use and care
- Technical assistance
- Your comments

The *Resolution T GPS Embedded Board User Guide* describes how to integrate and operate the Resolution T® GPS timing receiver. The instructions in this manual assume that you know how to use the primary functions of a Microsoft® Windows® operating system.

The Trimble Resolution T embedded timing board, is a full featured, 12 channel, parallel tracking GPS receiver. The receiver is designed to operate on the L1 (1575.42 MHz) frequency, providing standard position service (SPS) using Coarse Acquisition (C/A) code.

The Trimble Resolution T is designed for 3.3 V prime power and provides a separate pin on the I/O connector for powering the antenna with a user supplied voltage from 3.0 V to 5.5 V (antenna dependent).

For more information on GPS, go to <http://www.trimble.com/gps/index.shtml>.

## Operation

The Resolution T automatically initiates a self-survey upon acquisition of GPS satellites. When the survey is completed, the receiver switches into the Overdetermined Timing Mode. In this mode, the reference position from the self survey is maintained in memory and the receiver solves only for clock error and clock bias. The receiver provides for both Position and Time Receiver Autonomous Integrity Monitoring which allows the receiver to self determine a position change or to remove a satellite providing incorrect information from the timing solution.

***Note** – To offset the delay inherent in the RF cable from the antenna to the receiver and further improve the accuracy, determine the length of the cable and enter the offset based on the specific cable type.*

## Timing features

The timing features of the Resolution T GPS timing receiver include the following:

- Automatic self survey
- Overdetermined timing mode
- Single satellite timing mode
- Timing Superpackets
- TRAIM (Timing Receiver Autonomous Integrity Monitoring)
- Position integrity
- Cable-delay compensation
- Accuracy <15 ns (1  $\sigma$ ).

## Starter kit

The starter kit makes it simple to evaluate the Resolution T receiver's performance. It can be used as a platform for configuring the receiver software or as a platform for troubleshooting your design.

For a complete description of the starter kit, see [Resolution T starter kit, page 15](#).

## Use and care

The Resolution T GPS timing receiver is a high-precision electronic instrument and should be treated with reasonable care.



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**CAUTION** – There are no user-serviceable parts inside the Resolution T and any modification to the unit by the user voids the warranty.

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## Technical assistance

If you have a problem and cannot find the information you need in the product documentation, contact the Trimble Technical Assistance Center at 800-767-4822 or email [trimble\\_support@trimble.com](mailto:trimble_support@trimble.com).

## Your comments

Your feedback about the supporting documentation helps us to improve it with each revision. Email your comment to [techpubs@trimble.co.nz](mailto:techpubs@trimble.co.nz).

# Setting up the Resolution T Starter Kit

## In this chapter:

- System requirements
- Timing receiver performance
- Interface protocols
- Resolution T starter kit
- Power
- Setting up the starter kit
- Setting up the software toolkit

This chapter describes the elements of the Resolution T starter kit and how to set it up.

The hardware integration is described in [Chapter 3, Hardware Integration](#).

## System requirements

### Hardware

- The Trimble Resolution T Starter Kit, see [page 15](#).
- User-provided connectors and extension cords to connect the Resolution T to the computer, antenna interface, and other devices as required.
- +24 VDC power supply
- User-provided equipment to analyze the 10 MHz output frequency and the 1 PPS accuracy, and a BNC connector to connect them to the Resolution T module.
- User-provided connectors and extension cords to connect the Resolution T to the computer, antenna interface, and other devices as required.

### Computer

- An office computer running a version of the Windows® operating system (Windows 2000 or later)
- The computer must have one of the following service packs installed:
  - Service Pack 2, for Windows Vista® or Windows XP
  - Service Pack 4, for Windows 2000

### System software

- Monitor software. The software is used to monitor the GPS performance of the Resolution T and to change its settings. The software is compatible with the Windows 95, 98, 2000, and XP operating systems and with the Windows Vista operating system.
- Trimble Standard Interface Protocol (TSIP). This consists of command packets and report packets. See [Appendix A, Trimble Standard Interface Protocol](#)

## Removing the Resolution T module from the motherboard

The Resolution T GPS receiver is secured to the motherboard standoffs with Phillips head screws, allowing for removal and integration with the user's application. Follow these steps to remove the receiver from the motherboard:

1. Disconnect power to the enclosure.
2. Remove base plate and unplug the RF cable from the receiver.
3. Use a small Phillips screwdriver to remove the securing hardware which holds the Resolution T GPS receiver to the motherboard.

4. Gently rock the board loose from the motherboard I/O connector.



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**WARNING** – Before opening the interface unit, disconnect the unit from any external power source and confirm that both you and your work surface are properly grounded for ESD protection.

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The Resolution T is designed for embedded applications. The digital I/O lines and power lines are not designed with additional ESD protection like a stand-alone receiver would be. Use standard CMOS ESD handling precautions when removing and installing the receiver module.

## Timing receiver performance

The Resolution T GPS timing receiver is a complete 12-channel, parallel tracking, GPS receiver, designed to operate with the L1 frequency, Standard Position Service, Coarse Acquisition code. The receiver is designed in a single board format, specially adapted for timing applications where reliability, performance, and ease of integration are desired. The receiver features Trimble's improved signal processing code, a high-gain RF section for compatibility with standard active gain GPS antennas, and a CMOS level pulse-per-second (PPS) output for timing and synchronization applications.

Timing applications are assumed to be static. The special timing software used with the Resolution T receiver configures the unit into an automatic self survey mode at start up. The receiver will average position fixes for a specified time (one per second) and at the end of this period will save this reference location. At this time the receiver will go into an Overdetermined Clock mode and no longer solve for position but only for clock error and clock bias using all of the available satellites. This provides an accuracy of less than 15ns (1 Sigma) for the 1PPS output.

User settings such as port parameters and NMEA settings can be stored in the receiver's non-volatile (flash) memory. These settings are retained without main power. The Resolution T receiver has a single configurable serial I/O communication port.

***Note** – When customizing port assignments or characteristics, confirm that your changes do not affect your ability to communicate with the receiver.*



## Interface protocols

The Resolution T receiver operates using one of two protocols: protocol selection and port characteristics are user configurable.

**Note** – *The factory default setting for the I/O port is TSIP bidirectional.*

- TSIP (Trimble Standard Interface Protocol) is a powerful binary packet protocol that allows the system designer maximum configuration control over the GPS receiver for optimum performance in timing applications. TSIP supports multiple commands and their associated response packets for use in configuring the Resolution T receiver to meet user requirements.
- NMEA 0183 (National Marine Electronics Association) is an industry standard protocol common to marine applications. NMEA provides direct compatibility with other NMEA-capable devices such as chart plotters, radar, etc. The Resolution T receiver supports the ZDA NMEA message for GPS timing. You can select other NMEA messages and output rates as required.

## Resolution T starter kit

The Resolution T GPS receiver is available in a Starter Kit or as an individual receiver and associated antenna. The Starter Kit includes all the components necessary to quickly test and integrate the receiver:



The starter kit includes the Resolution T timing module, mounted on an interface motherboard in a durable metal enclosure. The motherboard accepts 9 – 32 VDC power and provides regulated +3.3 V power to the Resolution T receiver. The motherboard also contains:

- Two antenna options:
  - Bullet™ III GPS antenna, 5 V, F connector
  - Miniature magnetic mount antenna
- 50 feet (20 m) RG-59 antenna cable, terminated with F connectors (F-F)
- Interface cable, USB
- AC/DC power supply adapter:
  - Input: 100 – 240 VAC
  - Output: 24 VDC
- SMB to F adapter cable (RG-316 antenna transition cable)

Software tools used to communicate with the receiver are available for download from [www.trimble.com/tmg\\_resolutiont\\_ts.asp](http://www.trimble.com/tmg_resolutiont_ts.asp), including the *Resolution T GPS Embedded Board User Guide* (this document), and the Monitor Program.

**Note** – *The Resolution T GPS receiver is also available as an individual receiver and associated antenna.*

### Starter kit interface unit

The starter kit interface unit consists of a Resolution T GPS receiver attached to an interface motherboard, housed in a sturdy metal enclosure. This packaging simplifies evaluation and software development with the receiver by providing a USB interface which is compatible with most PC communication ports. Power (9-32 VDC) is supplied through the power connector on the front of the interface unit. The motherboard features a switching power supply which converts this voltage input to the 3.3 V required by the receiver and the 5 V required by the antenna. The USB connector allows for an easy connection to an office computer using the USB interface cable provided in the starter kit. The metal enclosure protects the receiver and the motherboard for testing outside of the laboratory environment.

The Resolution T GPS receiver, installed in the Starter Kit interface unit, is a single port receiver. A straight-in, panel-mount RF SMB connector supports the GPS antenna connection. The center conductor of the SMB connector also supplies +5.5 VDC for the Low Noise Amplifier of the active antenna.

**Note** – *A 3.3 VDC antenna can also be supported on the Resolution T GPS receiver, an 8-pin (2x4), 2 mm header (J4) supports the interface (CMOS level), the pulse-per-second (PPS) signal (CMOS level), and the input power (+3.3 VDC).*

The following figure shows the receiver in the metal enclosure:



The interface motherboard includes a 9 to 32 VDC switching power supply which provides regulated +3.3 VDC power to the receiver, regulated +5 VDC power to the antenna, and contains circuitry which provides a USB interface to a computer. The CMOS level PPS is brought directly out to Pin 9 of the USB connector on the front of the interface unit.

The Starter Kit includes an AC/DC converter for powering the module from an AC wall socket.

The mounting plate is secured to the metal enclosure with four screws. The eight pin I/O header on the receiver module connects directly to the motherboard.

The following figure shows the starter kit interface unit:



### Pulse-per-second (PPS)

The receiver provides a 1.0 millisecond wide, CMOS compatible Pulse-Per-Second (PPS). The PPS is a positive pulse available on the connector of the interface unit. The rising edge of the pulse is synchronized to GPS. The timing accuracy is <15 nanoseconds ( $1\sigma$ ) when operating in the Overdetermined Timing Mode. The rising edge of the pulse is less than 20 nanoseconds. The PPS is capable of driving a load up to 5mA without damaging the receiver.

The PPS signal is defaulted to always output. This is a customer selectable feature under TSIP packet 8F-4E. Other options include PPS output when one or more satellites are usable or when three or more satellites are usable. Additionally, the PPS output can be programmed to provide an Even Second output using TSIP packet 8F-4E.

## Power

The Resolution T GPS receiver is designed for embedded applications and requires a regulated +3.3 VDC input (+3.0 to +3.6 VDC). The receiver provided in the Starter Kit is installed on a motherboard, which provides a DC power regulator which converts a 9 VDC to 32 VDC input to the regulated 3.3 VDC required by the receiver and the regulated 5 VDC required by the antenna. Power can be applied to the interface unit using the AC/DC power converter.

### AC/DC power converter

The AC/DC power converter may be used as an alternate power source for the interface unit. The AC/DC power converter converts 110 or 220 VAC to a regulated 24 VDC compatible with the interface unit. The AC/DC power converter output cable is terminated with a 3-pin connector compatible with the power connector on the metal enclosure. The AC power cable is not provided in the kit, since this cable can be country-specific. The input connector is a standard 3-prong connector used on many desktop PCs.





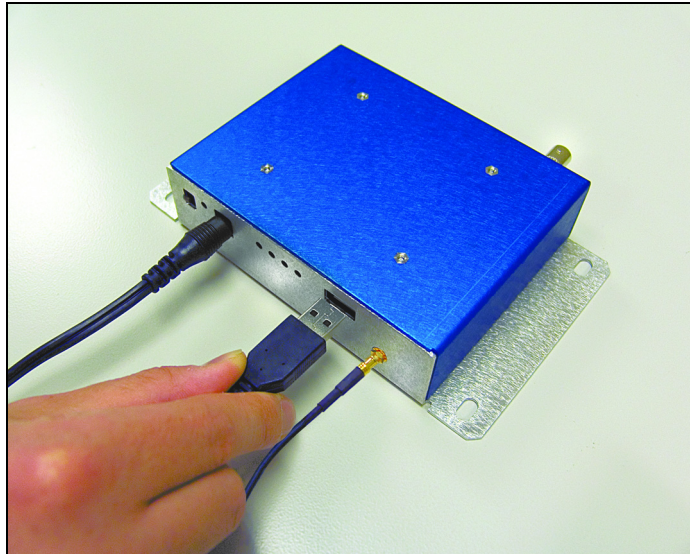
## Setting up the starter kit

**Note** – You can either set up the starter kit temporarily for testing or evaluation purposes, or embed it permanently into your system. The procedure is largely the same.

1. Start up your office computer that is running a suitable Windows operating system and service pack (see [page 13](#)) and that has a free USB port.
2. Download the required software from [www.trimble.com/support.shtml](http://www.trimble.com/support.shtml). Select and then save all the relevant files to a directory on the hard drive.
3. To use the Monitor software tool to communicate with the GPS receiver, you must install the FTDI driver on your computer. The starter kit uses a USB 2.0 dual serial port emulator interface chip from Future Technology Devices International Ltd. (FTDI).

To do this, click the CDM\_Setup.exe file that you downloaded earlier. If the installation is successful, a message **FTDI CDM Drivers have been successfully installed** appears.

4. Click **OK**.
5. Connect one end of the USB cable (supplied) to the USB connector on the interface unit:

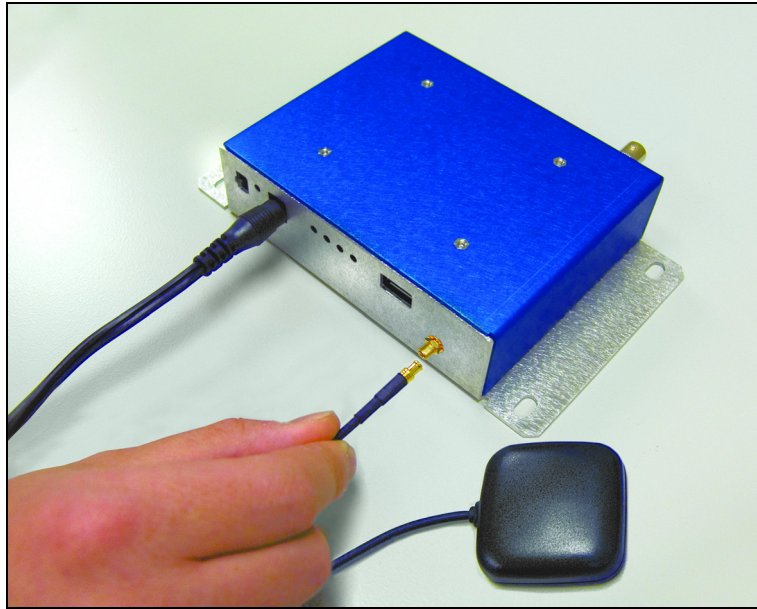


6. Connect the other end of the USB cable to your computer. The USB cable will now supply power to the unit.
7. Turn on the interface unit. The Power LED will light up (green).

**Note** – Two additional power adapters are supplied – an international AC / DC adapter and an automotive DC/DC adapter.

8. The FTDI driver automatically assigns two virtual COM ports to the USB port. When you need to assign the virtual COM ports, they appear on the monitor screen. To view the ports, select *System Properties / Device Manager / Ports*.

9. Connect the magnetic mount GPS antenna to the interface unit:



10. Place the antenna outside.
11. Start up the Monitor program and then select one of the USB virtual COM ports.  
Either the TSIP or NMEA data stream is visible on your monitor ( features including serial port baud rate are product dependent). To view the other protocol, restart the Monitor program and then select a different USB virtual COM port.

## Setting up the software toolkit

The DSP-Monitor program is used to monitor GPS performance and to assist system integrators in developing a software interface for the GPS module. It runs on the Windows 95/98/2000/XP and Windows Vista platforms.

To use the Monitor program to monitor the receiver's performance:

1. Connect one end of the serial interface cable to Port 1 of the interface unit. Connect the other end of the cable to the COM port of your computer.
2. Download the DSP-Monitor program, DSPMon.exe, onto your computer's hard drive.
3. Right-click in the bottom right of the DSP monitor screen to specify the communications port and protocol.

When the DSP-Monitor screen appears, the TX and RX indicators appear in the lower left corner of the status bar. A blinking TX indicates that the PC is transmitting commands to the receiver; a blinking RX indicates that the PC is

receiving reports from the receiver. If either of these indicators stop blinking, there is no activity. The PC COM port settings appear in the lower right corner of this same status bar.

4. Connect a GPS antenna to the receiver to complete the self-survey. Once the receiver has achieved a position fix, the following information appears:
  - position
  - time
  - satellites tracked
  - GPS receiver status

**Notes –**

*The receiver also sends a health report every few seconds, even if satellites are not being tracked.*

*If the DSP-Monitor program displays a question mark (?) in a data field, the receiver has not reported a status for this field. If a (?) remains in the data field, the GPS module may not be communicating with the computer. Recheck the interface cable connections and verify the serial port selection and settings. If the communication failure, please call the Trimble Technical Assistance Center (TAC) at 1 (800) 767-4822.*

# Hardware Integration

## In this chapter:

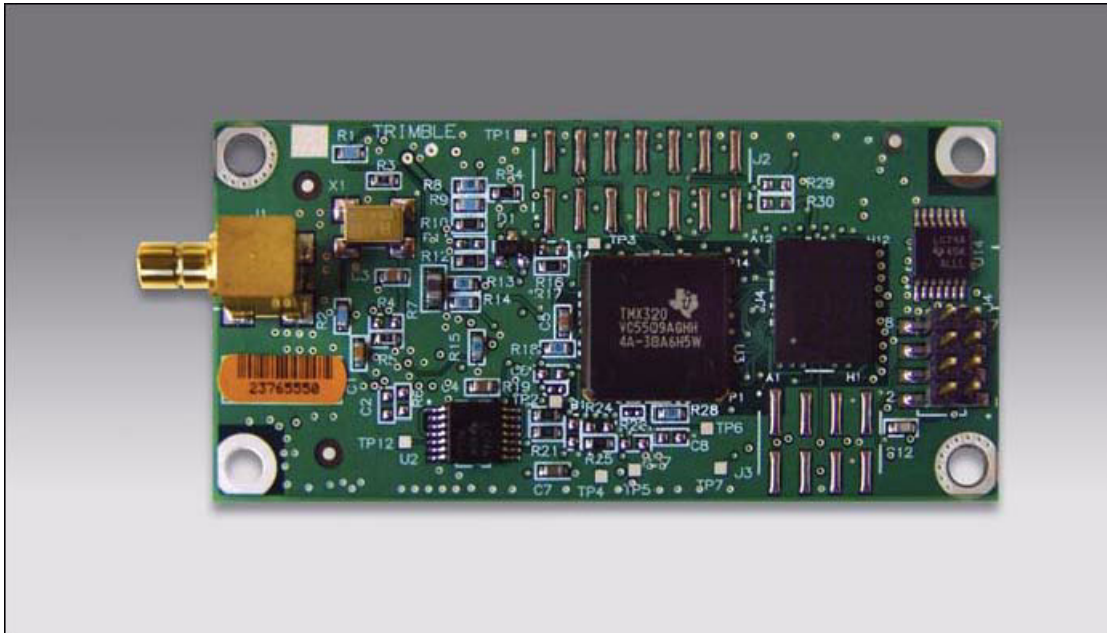
- Resolution T board
- Connectors
- Power requirements
- Serial interface
- Pulse-per-second (PPS)
- Mounting
- GPS antenna

The Trimble Resolution T GPS timing receiver delivers accurate timing solutions for use in all applications where precision timing is needed.

The Resolution T GPS timing receiver typically requires 350 mW of power (at 3.3 VDC). The receiver includes flash memory for field upgrades and for storing the user configuration.



## Resolution T board



## Connectors

### Digital IO/Power connector

The Resolution T GPS receiver uses a single 8-pin (2x4) male header connector for both power and data I/O. The power and I/O connector, J4, is a surface mount micro terminal strip. This connector uses 0.126 inch (3.2 mm) high pins on 0.079 inch (2 mm) spacing. The manufacturer of this connector is Samtec, part number TMM104-01-T-D-SM.

### Mating connectors

A surface mount mating connector from those specified by Samtec as compatible to Samtec TMM-104-01-T-D-SM is recommended.

### RF connector

The RF connector mounted on the Resolution T receiver is a right angle SMB.

## Antenna options

Trimble offers either a 3.3 VDC or a 5.0 VDC rooftop antenna and cable for use with the Resolution T GPS receiver.

## Digital IO/Power connector pin-out

The Digital IO/Power connector pin-out information is provided in the following table:

Pin Number	Function	Description
1	Antenna Power Input	3.0VDC to 5.5VDC, 55mA max
2	Prime Power Input	+3.3VDC $\pm$ 0.3VDC
3	TXD A	Port A transmit, CMOS
4	Reserved	Reserved
5	RXD A	Port A receive, CMOS
6	1 PPS	One Pulse-Per-Second, CMOS
7	No Connect	Not used
8	GND	Ground, Power and Signal

## Power requirements

The Resolution T GPS receiver requires +3.3 VDC  $\pm$ 0.3 VDC at 110 mA, typical excluding the antenna. The on-board capacitance is approximately 65  $\mu$ F. An important design consideration for power is the receiver's internal clock frequency at 12.504 MHz  $\pm$  3 KHz. Interference spurs on prime power in this narrow frequency band should be kept to less than 1mV.

The receiver does not require any special power up or down sequencing. The receiver power is supplied through pin 2 of the I/O connector. See Table 5 for the power specifications.



**WARNING** – The Resolution T GPS receiver is ready to accept TSIP commands approximately 2.1 seconds after power-up. If a command is sent to the receiver within this 2.1 second window, the receiver will ignore the command. The Resolution T GPS receiver will not respond to commands sent within the 2.1 second window and will discard any associated command data.

Signal	Voltage	Current	J4 Pin #
VCC	3.0 - 3.6	110 mA	2
Ground	0		8

## Serial interface

The Resolution T GPS receiver provides direct CMOS compatible serial I/O. The RX and TX signals on the J4 I/O connector are driven directly by the UART on the Resolution T GPS receiver. Interfacing these signals directly to a UART in your application circuitry provides direct serial communication without the complication of RS-232 or RS-422 line drivers.

## Pulse-per-second (PPS)

The Resolution T GPS timing receiver provides a one millisecond wide, CMOS compatible Pulse-Per-Second (PPS). The PPS is a positive pulse available on pin 6 of the power and I/O connector. The rising edge of the PPS pulse is synchronized with respect to UTC. The timing accuracy is within 15 nanoseconds ( $1\sigma$ ) to UTC when valid position fixes are being reported in the Overdetermined Mode.

The rising edge of the pulse is typically less than 20 nanoseconds. The distributed impedance of the attached signal line and input circuit can affect the pulse shape and rise time. The PPS can drive a load up to 5mA without damaging the receiver.

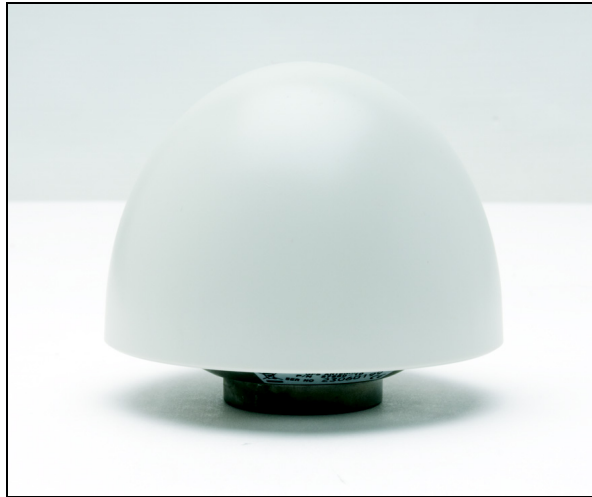
## Mounting

There are four mounting holes at the corners of the PCB that accept  $\frac{3}{16}$ " hex or round standoffs with a  $\frac{3}{8}$ " height, and #2-2-56 or M2 mounting screws. Space constrained environments may require a different standoff.

## GPS antenna

Trimble offers the following two antenna options for use with the Resolution T GPS receiver:

- A 3.3 VDC or 5.0 VDC Bullet™ III rooftop antenna:



- A compact magnetic mount antenna:



The antenna receives the GPS satellite signals and passes them to the receiver. The GPS signals are spread spectrum signals in the 1575 MHz range and do not penetrate conductive or opaque surfaces. Therefore, the antenna must be located outdoors with a clear view of the sky. The Resolution T GPS receiver requires an active antenna. The received GPS signals are very low power, approximately -130 dBm, at the surface of the earth. Trimble's active antenna includes a preamplifier that filters and amplifies the GPS signals before delivery to the receiver.

# Software Interface

## In this chapter:

- Start-up
- Communicating with the receiver
- Port protocol and data output options

This chapter describes the software interface and describes both communication with the receiver, port protocol, and data output options.

## Start-up

The Resolution T GPS timing receiver is a complete 12-channel parallel tracking GPS timing receiver designed to operate with the L1 frequency, standard position service, Coarse Acquisition code. When connected to an external GPS antenna, the receiver contains all the circuitry necessary to automatically acquire GPS satellite signals, track up to 12 GPS satellites, and compute location, speed, heading, and time. At power-up the receiver will begin a self-survey process. Upon completion, the receiver will provide an overdetermined timing solution.

The first time the receiver is powered-up, it is searching for satellites from a cold start (no almanac, time, ephemeris, or stored position). While the receiver will begin to compute position solutions within the first 46 seconds, the receiver must continuously track satellites for approximately 15 minutes to download a complete almanac and ephemeris. This initialization process should not be interrupted. The receiver will respond to commands almost immediately after power-up (see Warning below).




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**WARNING** – The Resolution T GPS receiver is ready to accept TSIP commands approximately 2.1 seconds after power-up. If a command is sent to the receiver within this 2.1 second window, the receiver will ignore the command. The Resolution T GPS receiver will not respond to commands sent within the 2.1 second window and will discard any associated command data.

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## Communicating with the receiver

The Resolution T GPS receiver supports two message protocols: TSIP and NMEA. Communication with the receiver is through a CMOS compatible serial port. The port characteristics can be modified to accommodate your application requirements. Port parameters are stored in non-volatile memory (flash) which does not require back-up power. Table 6 lists the default port characteristics.

### Software tools

The software tools provided on the Trimble website include a user-friendly Windows application to facilitate communication with the receiver, via the Trimble Standard Interface Protocol (TSIP).

### Port configuration

The Resolution T GPS receiver has a single I/O port. The following table shows the default protocol and port configuration for the receiver, as delivered from the factory. TSIP IN/OUT is the default protocol. The following table shows the default protocol and port configuration:

TSIP Input	TSIP Output
Baud Rate: 9600 Data Bits: 8 Parity: Odd Stop Bits: 1 No Flow Control	Baud Rate: 9600 Data Bits: 8 Parity: Odd Stop Bits: 1 No Flow Control

The Resolution T GPS receiver can also be configured to output NMEA messages. The industry standard port characteristics for NMEA are:

- Baud Rate: 4800
- Data Bits: 8
- Parity: None
- Stop Bits: 1
- No Flow Control

Any standard serial communications program, such as Windows Hyper-Terminal or PROCOMM, can be used to view the NMEA output messages. TSIP is a binary protocol and outputs raw binary serial data that cannot be read when using Windows Terminal or PROCOMM. To view the output of the TSIP protocol in text format, use the DSP Monitor program.




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**WARNING** – When using the TSIP protocol to change port assignments or settings, confirm that your changes do not affect the ability to communicate with the receiver (e.g., selecting the PC COM port settings that do not match the receiver's, or changing the output protocol to TSIP while not using TSIPCHAT).

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## Port protocol and data output options

### Protocol configuration and interface

The factory default protocol for the Resolution T GPS receiver is the Trimble Standard Interface Protocol (TSIP), for both input and output. The serial port setting is 9600 baud 8-odd-1. The receiver protocol can be re-configured using TSIP command packet 0xBC, DSP Monitor, or a user written serial interface program.

DSP Monitor (DSPMon.exe), a Windows-based GUI, provides a versatile graphical interface for monitoring TSIP data. This application allows the user to view complete receiver operations including data output, status and configuration. In this application, the entry of command packets is replaced by traditional point and click pull-down menus.

C-source code examples for TSIP commands are also provided in [Appendix A, Trimble Standard Interface Protocol](#). When used as software design templates, this source code can significantly speed-up code development.

The protocol settings and options are stored in Random-Access-Memory (RAM). They can be saved into the non-volatile memory (flash), if required, using command 0x8E-26.

## NMEA 0183 Protocol and Data Output Options

The National Marine Electronics Association (NMEA) protocol is an industry standard data protocol which was developed for the marine industry. Trimble has chosen to adhere stringently to the NMEA 0183 data specification as published by the NMEA. The Resolution T GPS receiver also adheres to the NMEA 0183, Version 3.0 specification.

NMEA data is output in standard ASCII sentence formats. Message identifiers are used to signify what data is contained in each sentence. Data fields are separated by commas within the NMEA sentence. In the Resolution T GPS receiver, NMEA is an output only protocol.

The receiver is shipped from the factory with the TSIP protocol configured on Port 1. The receiver can be reconfigured using TSIP command packet 0xBC, in conjunction with TSIPCHAT, DSP Monitor, or a user written serial interface program.

The NMEA output messages selection and message output rate can be set using TSIP command packet 0x7A. The default setting is to output the ZDA message at a 1 second interval, when the receiver output protocol is configured to NMEA, using packet 0xBC.

If NMEA is to be permanent for the application, the protocol configuration (0xBC) and NMEA message output setting (0x7A) can be stored in the non-volatile memory (on-board flash) using TSIP command 0x8E-26.



# System Operation

## In this chapter:

- Operation
- PPS quantization error
- Data communication
- Using Resolution T in mobile applications
- Customizing operations
- System architecture

This chapter describes the operating characteristics of the Resolution T GPS timing receiver including start-up, satellite acquisition, operating modes, serial data communication, and the timing pulse. The Resolution T GPS timing receiver acquires satellites and computes position and time solutions. It outputs data in the TSIP (or NMEA) protocol through its serial port.

## Operation

### Start-up

When the Resolution T is turned on, it automatically begins to acquire and track GPS satellite signals. It obtains its first fix in under one minute.

During the satellite acquisition process, the Resolution T GPS outputs periodic TSIP status messages. These status messages confirm that the receiver is working.

### Automatic operation

When the Resolution T has acquired and locked onto a set of satellites that pass the mask criteria listed below, and has obtained a valid ephemeris for each satellite, it performs a self-survey. After a number of position fixes (configurable), the self-survey is complete. At that time, the Resolution T automatically switches to a time-only mode.

### Satellite masks

The Resolution T continuously tracks and uses up to twelve satellites in an overdetermined clock solution. The satellites must pass the mask criteria to be included in the solution.

The following table lists the default satellite masks used by the Resolution T. These masks serve as the screening criteria for satellites used in fix computations and ensure that solutions meet a minimum level of accuracy. The satellite masks can be adjusted using the TSIP protocol described in [Appendix A, Trimble Standard Interface Protocol](#).

Mask	Setting	Notes
Elevation	10°	SV elevation above horizon
SNR (AMUs)	4	Signal strength
PDOP	12	Self-survey only

### Elevation mask

Satellites below 10° elevation are not used in the solution. Generally, signals from low-elevation satellites are of poorer quality than signals from higher elevation satellites. These signals travel farther through the ionospheric and tropospheric layers and undergo distortion due to these atmospheric conditions.

### SNR mask

Although the Resolution T is capable of tracking signals with SNRs as low as 2, the default SNR mask is set to 4 to eliminate poor quality signals from the fix computation. Low SNR values can result from low-elevation satellites, partially obscured signals (for example, dense foliage), or multi-reflected signals (multipath).

Multi-reflected signals, also known as multipath, can degrade the position and timing solution. Multipath is most commonly found in urban environments with many tall buildings and a preponderance of mirrored glass. Multi-reflected signals tend to be weak (low SNR value), since each reflection diminishes the signal. Setting the SNR mask to 4 or higher minimizes the impact of multi-reflected signals.

### PDOP mask

Position Dilution of Position (PDOP) is a measure of the error caused by the geometric relationship of the satellites used in the position solution. Satellite sets that are tightly clustered or aligned in the sky have a high PDOP and contribute to lower position accuracy. For timing applications, a PDOP mask of 12 offers a satisfactory trade-off between accuracy and GPS coverage. With worldwide GPS coverage, the PDOP mask can be lowered even more for many applications without sacrificing coverage.

*Note – PDOP is only applicable during self-survey or whenever the receiver is performing position fixes.*

## Tracking modes

The Resolution T operates in one of two main fix modes:

- Self-Survey (Position fix mode)
- Overdetermined Clock mode

After establishing a reference position in Self-Survey mode, the Resolution T automatically switches to Overdetermined (OD) Clock mode.

### Self-Survey mode

At power-on, the Resolution T performs a self-survey by averaging 2000 position fixes. The number of position fixes until survey completion is configurable using the 8E-A9 command.

The default mode during self-survey is 3-D manual, where the receiver must obtain a 3-D solution with a PDOP below the PDOP mask. The PDOP mask criteria can be set and queried using a TSIP packet. If fewer than four conforming satellites are visible, the Resolution T suspends the self survey.

The highest accuracy fix mode is 3-D manual, where altitude is always calculated along with the latitude, longitude, and time. Obtaining a position requires four satellites with a PDOP below the PDOP mask. Depending on how the PDOP mask is set, 3-D mode can be restrictive when the receiver is subjected to frequent obscuration or when the geometry is poor due to an incomplete constellation.

### Overdetermined Clock mode

Overdetermined Clock Mode is used only in stationary timing applications. This is the default mode for the Resolution T once a surveyed (or user input) position is determined. After the receiver self-surveys its static reference position, it automatically

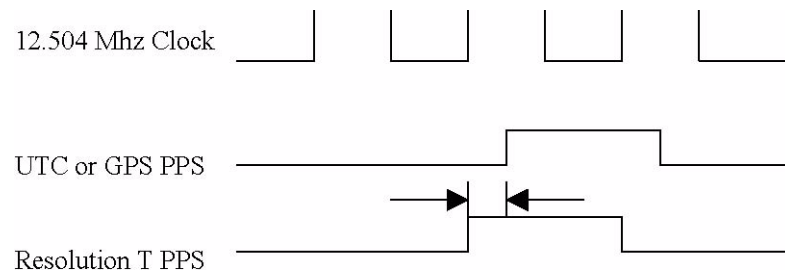
switches to Overdetermined Clock Mode and determines the clock solution. The timing solution is qualified by a TRAIM algorithm, which automatically detects and rejects faulty satellites from the solution.

In this mode, the Resolution T does not navigate or update positions and velocities, but maintains the PPS output, solving only for the receiver clock error (bias) and error rate (bias rate).

## PPS quantization error

The Resolution T uses a high-precision, fixed frequency oscillator as the timing source to down-convert and decode the GPS signal and to generate the PPS output signal. Since a fixed-frequency oscillator is used, the Resolution T must place the PPS output on the clock edge that it determines is closest to UTC or GPS. This situation results in a quantization error on the placement of the PPS whose magnitude is equal to one-half the period of the fixed frequency oscillator. The oscillator frequency is 12.504 MHz which is equivalent to a period just under 80 nanoseconds. Since both clock edges are used, the quantization error on the PPS output is between  $\pm 20\text{ns}$ .

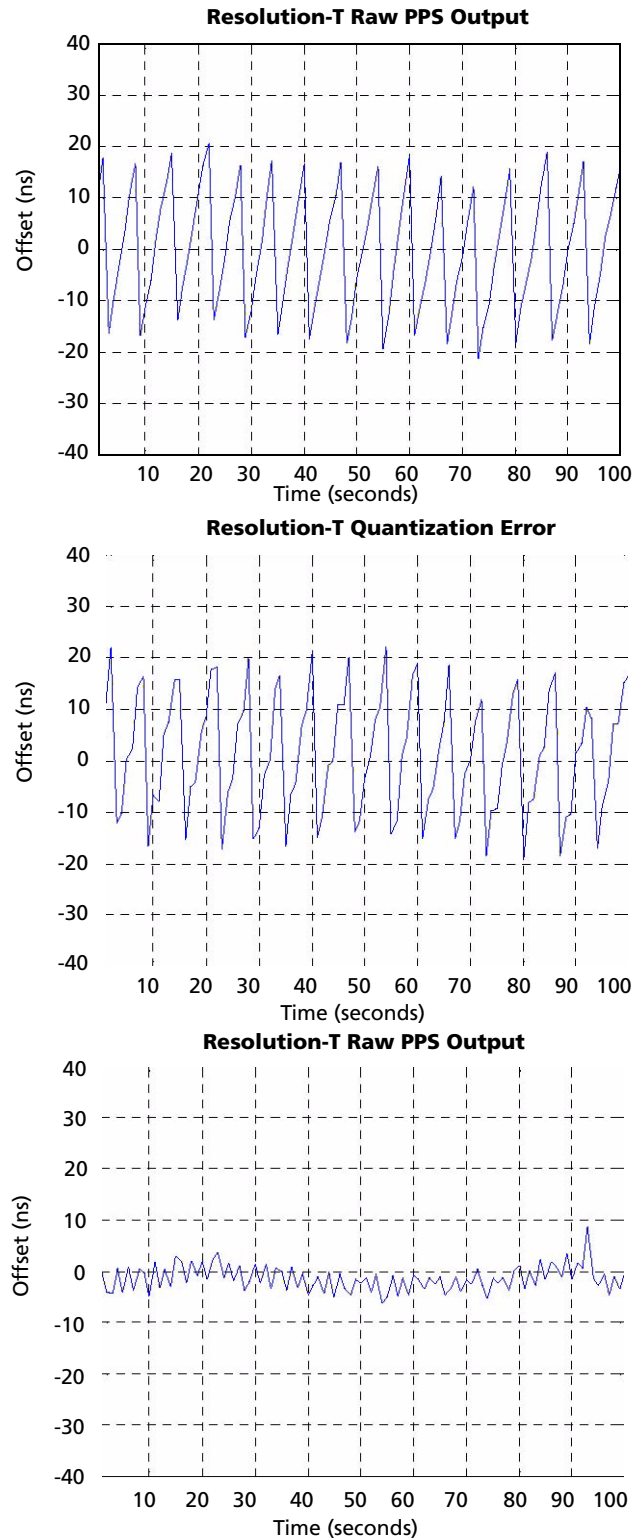
The quantization error is illustrated below. The top waveform represents the 12.504 MHz clock. The Resolution T output must be placed on one of the edges of this clock. The middle waveform represents the UTC/GPS on-time mark as determined by the receiver's electronics. The bottom waveform represents the Resolution T PPS output which is output on the clock edge closest to the actual UTC/GPS on-time mark.



The amount of quantization error present on each PPS output pulse is reported in packet 0x8F-AC. This quantization error information can be used to reduce the effective amount of jitter on the PPS pulse.

The figures below illustrate the result of removing the quantization error from the PPS output in a user system. The top slot shows the offset of the PPS output pulse relative to a stable standard such as a Cesium atomic clock. The quantization error is responsible for the jagged appearance of the waveform. The middle plot shows the

quantization error as reported by the Resolution T in packet 0x8FAC. The bottom plot is the result of subtracting the quantization error from the PPS offset.



## Data communication

The Resolution T outputs TSIP super packets or NMEA messages. Immediately following power-on, the Resolution T outputs packets 8F-AB, 8F-AC, and PPS. Use packet 8E-A5 to enable or disable timing packets and automatic output packets. These packets are described in [Appendix A, Trimble Standard Interface Protocol](#).

The factory default port setting is 9600 baud in/out, 8 data bits, odd parity, 1 stop bit. The serial port setting can be changed and stored in flash memory using a TSIP command. This port can be configured to transmit timing packets, using packet 8E-A5.

## GPS timing

For many timing applications, such as time/frequency standards, site synchronization systems, and wireless voice and data networks, the Resolution T can be used to steer a local reference oscillator. The steering algorithm combines the short-term stability of the oscillator with the long-term stability of the GPS PPS. An accurate GPS PPS allows the use of cost-effective crystal oscillators, which have less stability than expensive, high-quality oscillators, such as OCXOs (Oven Controlled Crystal Oscillators).

The GPS constellation consists of at least 24 orbiting satellites. Unlike most telecommunications satellites, GPS satellites are not geostationary, so satellites in view are constantly changing. Each GPS satellite contains four highly-stable atomic clocks, which are continuously monitored and corrected by the GPS control segment. Consequently, the GPS constellation can be considered a set of 24 orbiting "clocks" with worldwide 24-hour coverage.

A Trimble GPS receiver uses the signals from these GPS "clocks" to correct its internal clock, which is not as stable or accurate as the GPS atomic clocks. A GPS receiver like the Resolution T outputs a highly accurate timing pulse (PPS) generated by its internal clock, which is constantly corrected using the GPS clocks. In the case of the Resolution T, this timing pulse is synchronized to GPS/UTC time within 15 nanoseconds ( $1 \sigma$ ) after survey is complete.

In addition to serving as highly-accurate stand-alone time sources, GPS timing receivers are used to synchronize distant clocks in communication or data networks. This is possible because all GPS satellites are corrected to a common master clock. Therefore, the relative clock error is the same, regardless of which satellites are used. For synchronization applications requiring a common clock, GPS is the ideal solution.

Position and time errors are related by the speed of light. This is why an accurate reference position is critical. A position error of 100 meters corresponds to a time error of approximately 333 ns.

The GPS receiver's clocking rate and software affect PPS accuracy. The Resolution T has a clocking rate of 12.504 MHz which enables a steering resolution of 40 ns ( $\pm 20$  ns). Utilizing both the rising edge and falling edge of the pulse will enable a steering resolution of  $\pm 20$  ns. Using software algorithms like an overdetermined clock solution, the Resolution T mitigates the effects of clock error to achieve a PPS accuracy within 15 ns ( $1 \sigma$ ) to GPS/UTC after survey is complete.

## Timing operation

The Resolution T automatically outputs a PPS and time tag. With an accurate reference position, the receiver automatically switches to an overdetermined clock mode, activates its TRAIM algorithm and outputs a precise PPS. Using a simple voting scheme based on pseudo-range residuals, the Resolution T integrity algorithm automatically removes the worst satellite with the highest residual from the solution set if that satellite's residual is above a certain threshold.

The Resolution T's default configuration provides optimal timing accuracy. The only item under user or host control that can affect the receiver's absolute PPS accuracy is the delay introduced by the antenna cable. For long cable runs, this delay can be significant (1.25 ns per foot). TSIP packet 8Ex4A sets the cable delay parameter, which is stored in non-volatile memory. For the best absolute PPS accuracy, adjust the cable delay to match the installed cable length (check with your cable manufacturer for the delay for a specific cable type). Generally, the cable delay is about 1.25 nanoseconds per foot of cable. To compensate for the cable delay, use a negative offset to advance the PPS output.

***Note** – GPS time differs from UTC (Universal Coordinated Time) by a small, sub-microsecond offset and an integer-second offset. The small offset is the steering offset between the GPS DoD clock ensemble and the UTC (NIST) clock ensemble. The large offset is the cumulative number of leap seconds since 1 January 1970, which, on 31 December 2006, was increased from 14 to 16 seconds. Historically, the offset increases by one second approximately every 18 months, usually just before midnight on 30 June or 31 December. System designers should note whether the output time is UTC or GPS time.*

## Using Resolution T in mobile applications

Although it is intended primarily for use in static applications, the Resolution T can also be used in mobile applications. The factory default settings for the Resolution T assume that the antenna is going to be used in a static timing application. To use the Resolution T in mobile applications, you must disable the receiver's self-survey mechanism and ensure that a stored position does not exist in the flash ROM.

To prepare the Resolution T receiver for mobile applications, complete the following steps:

1. Confirm that there is no stored position in the flash ROM by using command packet 8E-A6 to delete the stored position (if one exists).
2. Disable the self-survey mechanism using command packet 8E-A9. If not disabled, the self-survey mechanism will automatically survey the antenna's position and then set the receiver to operate in a static, time-only mode.
3. Set the desired position fix mode using command packet BB.
4. Optionally, use packet 8E-A5 to enable the automatic output packets such as position and velocity.

5. Use packet 8E-26 to save this new configuration to Flash storage and to retain these settings during power cycles and resets.

After these steps are completed, the Resolution T receiver is ready to operate properly in mobile applications. While operating in a mobile application, the receiver can continue to output a PPS pulse as well as timing packets.

**Note** – *The accuracy of the PPS output pulse will be degraded by a factor of about 3 when the unit is operated in a mobile application.*

## Customizing operations

The Resolution T receiver provides a number of user configurable parameters that allow you to customize the operation of the unit. These parameters are stored in flash ROM chip to be retained during loss of power and through resets. At reset or power-up, the receiver configures itself based on the parameters stored in the flash ROM. You can change the values of these parameters to achieve the desired operations using a variety of TSIP packets. The Resolution T configures itself based on the new parameter immediately, but the new parameter value is not automatically saved to the flash ROM. You must direct the receiver to save the parameters to the flash ROM.

To change the parameter values stored in flash ROM, send packet 0x8E-26 to direct the Resolution T to save the current parameter values to the flash ROM. To save or delete the stored position, use command packet 0x8E-A6. You can also direct the receiver to set the parameter values to their factory default settings (and to erase the stored position) with packet 0x1E.

In brief, to customize the Resolution T GPS receiver operations for your application:

- Configure the receiver using TSIP command packets until the desired operation is achieved.
- Use TSIP packet 0x8E-26 to save the settings in nonvolatile memory ( flash ROM.)
- If the position was not automatically saved during the self survey or if it was manually entered, the position can be saved to flash memory using TSIP packet 8E-A6.

The new settings will control receiver operations whenever it is reset or power cycled.

## Configuration parameters

The following tables list the user configurable parameters. Each table lists the parameter name, its factory default value, and the TSIP packet that sets or reads the parameter value (typically, one TSIP packet sets or reads several related parameters.)



## System architecture

The Resolution T is a software GPS timing receiver. It is a complete all-in-view, 12 channel, parallel tracking GPS receiver designed to operate with the L1 frequency, standard position service, Coarse Acquisition code.

The Resolution T receives the amplified GPS satellite signals through the antenna feed line connector and passes them to the RF down converter. A highly stable crystal reference oscillator operating at 12.504 MHz is used by the down converter to produce the signals used by the DSP. The DSP tracks the GPS satellite signals and extracts the carrier code information as well as the navigation data at 50 bits per second.

Operation of the tracking channels is controlled by the navigation processor. The software tracking channels are used to track the highest twelve satellites above the horizon. The navigation processor will then use the optimum satellite combination to compute a position. The navigation processor also manages the ephemeris and almanac data for all of the satellites, and performs the data I/O.

# Trimble Standard Interface Protocol

## In this appendix:

- Introduction
- Customizing operations parameters
- Packets output at startup
- Report packets: Resolution T to User
- Command Packets: User to Resolution T
- Packet structure
- Packet descriptions
- TSIP Superpackets
- Unused or miscellaneous packets
- Legacy packets (unused)

The Trimble Standard Interface Protocol (TSIP) may be characterized as a set of data packets used to transmit information to and receive information from a Trimble GPS receiver. Trimble products commonly support a version of TSIP which is customized to the attributes of the product. This appendix describes the Resolution T customization.



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**WARNING** – The Resolution T GPS receiver is ready to accept TSIP commands approximately 2.1 seconds after power-up. If a command is sent to the receiver within this 2.1 second window, the receiver will ignore the command. The Resolution T GPS receiver will not respond to commands sent within the 2.1 second window and will discard any associated command data.

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*Note* – This appendix has been generated and reviewed with care, however, history has shown that it is surprisingly difficult to generate a TSIP appendix which is entirely free of errors. There is no reason to believe that this appendix will be an exception. Trimble is always grateful to receive reports of any errors in either products or documentation.

## Introduction

TSIP is a powerful and compact interface protocol which has been designed to allow the system developer a great deal of flexibility in interfacing to a Trimble product. Many TSIP data packets are common to all products which use TSIP. An example would be a single precision position output packet. Other packets may be unique to a product. Custom packets are only used in the products for which they have been created.

### Interface scope

The Resolution T GPS module has one configurable serial I/O communication port, which is a bi-directional control and data port utilizing a Trimble Standard Interface Protocol (TSIP). The data I/O port characteristics and other options are user programmable and stored in non-volatile memory (flash ROM.)

The TSIP protocol is based on the transmission of packets of information between the user equipment and the GPS receiver. Each packet includes an identification code that identifies the meaning and format of the data that follows. Each packet begins and ends with control characters.

### Automatic output packets

The Resolution T GPS embedded timing board is configured to automatically output the 0x8F-AB and 0x8F-AC packets. For most system implementations these output packets provide all of the information required for operation including time, position, GPS status, and health. The following packets can be broadcast if enabled with packet 0x8E-A5 and 0x35. By default, only packets 0x8F-AB and 0x8F-AC are enabled for output. This table shows the broadcast output packets:

Broadcast Packet ID	Description	Masking Packet ID	Request Packet ID	When Sent
0x42	Position XYZ (ECEF), single precision	0x35	0x37	When a position fix is computed
0x43	Velocity XYZ, single precision	0x35	0x37	When a position fix is computed
0x4A	Position LLA, single precision	0x35	0x37	When a position fix is computed
0x56	Velocity ENU, single precision	0x35	0x37	When a position fix is computed
0x58	Satellite system data	none	0x38	When new system data is received
0x6D	Satellite list, DOPS, mode	none	0x24	When the satellite selection list is updated
0x83	Position XYZ (ECEF), double precision	0x35	0x37	When a position fix is computed
0x84	Position LLA, double precision	0x35	0x37	When a position fix is computed
0x8F-AB	Primary timing packet	0x8E-A5	none	Once per second
0x8F-AC	Secondary timing packet	0x8E-A5	none	Once per second

## Customizing operations parameters

The Resolution T provides a number of user configurable parameters that allow the user to customize the operation of the Resolution T. These parameters are stored in flash memory to be retained during loss of power and through resets. At reset or power up, the Resolution T configures itself based on the parameters stored in the flash. The user can change the values of these parameters to achieve the desired operation using a variety of TSIP packets. The Resolution T configures itself based upon the new parameters immediately, but the new parameter is not automatically saved to flash. The user must direct the Resolution T to save the parameters to flash. To change the parameter values stored in flash, the user sends packet 0x8E-26 to direct the Resolution T to save the current parameters in the flash. Users can also direct the Resolution T to set the parameter values to their factory default with packet 0x1E.

**Note** – Whenever configuration data is saved to the flash ROM (using 0x8E-26 or other packets) the Resolution T automatically performs a reset.

To customize the Resolution T output for your application:

1. Set up the Resolution T using TSIP commands until the desired operation is achieved.
2. Use command 0x8E-26 to store the settings in nonvolatile memory.

These settings will control Resolution T operations whenever it is cold-started. The following tables illustrate how the user configurable data is mapped. The Trimble factory defaults are also provided. See packet 0x1E.

### Factory default settings

Parameter	Factory Default	Set	Request	Report
Receiver mode	4 (Full Position 3D)			
Dynamics code	1 (land)			
Elevation mask	0.175 radians (10 degrees)			
Signal level mask	4 (AMU)	0xBB	0xBB	0xBB
PDOP mask	12			
PDOP switch	6			
Foliage mode	1 (sometimes)			

## Packet I/O control

Parameter	Factory Default	Set	Request	Report
Packet broadcast mask				
mask 0	0x05	0x8E-A5	0x8E-A5	0x8F-A5
mask 1	0x00			
Packet 0x35				
data position (byte 0)	0x12			
velocity (byte 1)	0x02	0x35	0x35	0x35
timing (byte 2)	0x00			
auxiliary (byte 3)	0x00			
Datum	0 WGS-84	0x8E-15	0x8E-15	0x8F-15

## Serial port configuration

Parameter	Factory Default	Set	Request	Report
Input baud rate	7 (9600 baud)			
Output baud	7 (9600 baud)			
Data bits	8			
Parity	1 (odd)	0xBC	0xBC	0xBC
Stop bits	1			
Input protocol	2 (TSIP)			
Output protocol	2 (TSIP)			

## Timing outputs

Parameter	Factory Default	Set	Request	Report
PPS enable	1 (enabled)	0x8E-4A	0x8E-4A	0x8F-4A
PPS sense	1 (rising edge)			
PPS offset	0.0 (seconds)			
Bias Uncertainty Threshold	300.0 (meters)	0x8E-4A	0x8E-4A	0x8F-4A
PPS Output Qualifier	2 (always on)	0x8E-4E	0x8E-4E	0x8F-4E
UTC/GPS Date/Time	0 (GPS)	0x8E-A2	0x8E-A2	0x8F-A2
UTC/GPS PPS Alignment	0 (GPS)	0x8E-A2	0x8E-A2	0x8F-A2

## Accurate position

Parameter	Factory Default	Set	Request	Report
Position	No stored position	0x31 0x32 self-survey	0x8E-AC	0x8F-AC

## Self-survey

Self-Survey	Factory Default	Set	Request	Report
Self-survey enable	1 (enabled)			
Position save flag	1 (save)	0x8EA9	0x8E-A9	0x8F-A9
Self-survey count	2000 (fixes)			

## Packets output at startup

After completing its self-diagnostics, the Resolution T automatically outputs the following packets. The following table shows the packet power-up output messages:

Output ID	Description	Notes
0x45	Software version	

## Report packets: Resolution T to User

The table below summarizes the packets output by the Resolution T. The table includes the output packet ID, a short description of each packet, and the associated input packet. In some cases, the response packets depend on user-selected options.

Output ID	Packet Description	Input ID
0x1C	Firmware/Hardware versions	0x1C
0x42	single-precision XYZ position	0x37, auto
0x43	velocity fix (XYZ ECEF)	0x37, auto
0x45	software version information	0x1E 0x1F power-up
0x47	signal level for all satellites	0x27
0x4A	single-precision LLA position	0x37 auto
0x55	I/O options	0x35
0x56	velocity fix (ENU)	0x37 auto
0x57	information about last computed fix	0x37
0x58	GPS system data/acknowledge	0x38
0x59	sat enable/disable & health flag	0x39
0x5A	raw measurement data	0x3A
0x5C	satellite tracking status	0x3C
0x6D	all-in-view satellite selection	0x24 auto
0x83	double-precision XYZ	0x37 auto

<b>Output ID</b>	<b>Packet Description</b>	<b>Input ID</b>
0x84	double-precision LLA	0x37 auto
0xBB	primary configuration	0xBB
0xBC	port configuration	0xBC
0x8F-15	current datum values	0x8E-15
0x8F-41	stored manufacturing operating parameters	0x8E-41
0x8F-42	stored production parameters	0x8E-42
0x8F-4A	set PPS characteristics	0x8E-4A
0x8F-A2	UTC/GPS timing	0x8E-A2
0x8F-A4	test modes	0x8E-A4
0x8F-4E	PPS output option	0x8E-4E
0x8F-A5	packet broadcast mask	0x8E-A5
0x8F-A6	Self survey command	0x8E-A6
0x8F-A9	Self survey parameters	0x8E-A9
0x8F-AB	primary timing packet	auto
0x8F-AC	supplemental timing packet	auto

## Command Packets: User to Resolution T

The table below summarizes the packets that can be input by the user. The table includes the input packet ID, a short description of each packet, and the associated output packet.

<b>Input ID</b>	<b>Packet Description</b>	<b>Output ID</b>
0x1C	Firmware/Hardware versions	0x1C
0x1E	Initiate cold reset or factory reset	0x45
0x1F	software version	0x45
0x24	request GPS satellite selection	0x6D
0x25	initiate soft reset & self-test	0x45
0x27	request signal levels	0x47
0x31	set accurate initial position (XYZ ECEF)	
0x32	set accurate initial position (lat, long, Alt)	
0x34	satellite selection for one-satellite mode	
0x35	set/request I/O options	0x55
0x37	status and values of last position and velocity	0x57 (and other enabled packets)
0x38	load or request satellite system data	0x58
0x39	set/request satellite disable or ignore health	0x59
0x3A	request last raw measurement	0x5A
0x3C	request current satellite tracking status	0x5C
0x7A	NMEA Set/Request	
0x7B	NMEA Output Interval	

Input ID	Packet Description	Output ID
0xBB	set receiver configuration	0xBB
0xBC	set port configuration	0xBB
0x8E-4E	PPS output option	0x8F-4E
0x8E-15	set/request current datum	0x8F-15
0x8E-26	Save configuration	
0x8E-41	request manufacturing parameters	0x8F-41
0x8E-42	request production parameters	0x8F-42
0x8E-4A	set PPS characteristics	0x8F-4A
0x8E-A2	UTC/GPS timing	0x8F-A2
0x8E-A4	test modes	0x8F-A4
0x8E-A5	packet broadcast mask	0x8F-A5
0x8E-A6	self-survey commands	0x8F-A6
0x8E-A9	self-survey parameters	0x8F-A9

## Packet structure

TSIP packet structure is the same for both commands and reports. The packet format is:

<DLE> <id> <data string bytes> <DLE> <ETX>

Where:

<DLE>	is the byte 0x10
<ETX>	is the byte 0x03
<id>	is a packet identifier byte, which can have any value excepting
<ETX> and <DLE>	The bytes in the data string can have any value. To prevent confusion with the frame sequences <DLE> <id> and <DLE> <ETX>, every <DLE> byte in the data string is preceded by an extra <DLE> byte ('stuffing'). These extra <DLE> bytes must be added ('stuffed') before sending a packet and removed after receiving the packet.  <b>Note</b> – A simple <DLE> <ETX> sequence does not necessarily signify the end of the packet, as these can be bytes in the middle of a data string. The end of a packet is <ETX> preceded by an odd number of <DLE> bytes.

Multiple-byte numbers (integer, float, and double) follow the ANSI / IEEE Std. 754 IEEE Standard for binary Floating-Point Arithmetic. They are sent most-significant byte first. **You must switch the byte order on Intel-based machines.**

The data types used in the Resolution T TSIP are as follows:

Data type	Description
UINT8	An 8-bit unsigned number (0 to 255)
SINT8	An 8-bit signed number (-128 to 127)
INT16	A 16-bit unsigned number (0 to 65,535)



Data type	Description
SINT16	A 16-bit signed number (-32,768 to 32,767)
UINT32	A 32-bit unsigned number (0 to 4,294,967,295)
SINT32	A 32-bit signed number (-2,147,483,648 to 2,147,483,647): <ul style="list-style-type: none"> <li>• Single - Float (4 bytes) (3.4x10<sup>-38</sup> to 1.7x10<sup>38</sup>) (24 bit precision)</li> <li>• Double - Float (8 bytes) (1.7x10<sup>-308</sup> to 3.4x10<sup>308</sup>) (53 bit precision)</li> </ul>

*Note – Default settings are 9600-8-odd-1.*

## Packet descriptions

### Command Packet 0x1C: Firmware Version 01

The command packet 0x1C: 01 may be issued to obtain the firmware version. The product name is *Resolution T GPS Timing Receiver*. The packet format is defined in the following table:

Byte	Item	Type	Value	Meaning
0	Packet ID	UINT8	0x1C	Packet ID 0x1C
1	Sub-code	UINT8	0x01	Sub-code 0x01 for software component version information request

### Report Packet 0x1C: 81

Byte	Item	Type	Value	Meaning
0	Packet ID	UINT8	0x1C	Packet ID 0x1C
1	Sub-code	UINT8	0x81	Sub-code 0x81 for software component version information report
2	Reserved	UINT8	Any	Reserved
3	Major version	UINT8	Any	Firmware major version
4	Minor version	UINT8	Any	Firmware minor version
5	Build number	UINT8	Any	Firmware build number
6	Month	UINT8	1-12	Firmware build month
7	Day	UINT8	1-31	Firmware build day
8...9	Year	INT16	Any	Firmware build year
10	Length of first module name	UINT8	Any	The length of the product name (L1)
11... (10+L1)	Product name	UINT8	String	Product name in ASCII

### Command Packet 0x1C: 03 – hardware component version information

- The command packet 0x1C: 03 may be issued to obtain the hardware component version information.
- The report packet is of variable length, depending on the length of the hardware ID.
- The serial number, build date fields, and the hardware ID are programmed into the Resolution SMT at production.
- The hardware code for the Resolution T GPS Timing Receiver is 3002.
- ID for Resolution T receiver is **Resolution T GPS Timing Receiver**.

The packet format is defined in the following table:

Byte	Item	Type	Value	Meaning
0	Packet ID	UINT8	0x1C	Packet ID 0x1C
1	Sub-code	UINT8	0x03	Sub-code 0x03 for hardware component version information request

### Report Packet 0x1C: 83 – hardware component version information

Byte	Item	Type	Value	Meaning
0	Packet ID	UINT8	0x1C	Packet ID 0x1C
1	Sub-code	UINT8	0x83	Sub-code 0x83 for hardware component version information report
2 ... 5	Serial number	UINT32	Any	Board serial number
6	Build day	UINT8	1-31	Day of the board's build date
7	Build month	UINT8	1-12	Month of the board's build date
8...9	Build year	INT16	Any	Year of the board's build date
10	Build hour	UINT8	0-23	Hour of the board's build date
11...12	Hardware code	INT16	Any	Hardware code associated with Hardware ID
13	Length of Hardware ID	UINT8	Any	The length of the Hardware ID (L)
14... (13+L)	Hardware ID	UINT8	String	Hardware ID string in ASCII

### Command Packet 0x1E: Clear RAM then Reset

This packet commands the Resolution T to perform either a cold reset, warm reset, or a factory reset:

- A cold reset will clear the GPS data (almanac, ephemeris, etc.) stored in RAM and is equivalent to a power cycle.
- A factory reset will additionally restore the factory defaults of all configuration parameters stored in flash memory.

- A warm reset clears ephemeris and oscillator uncertainty but retains the last position, time and almanac. This packet contains one data byte.

The data format is shown below.

Byte	Item	Type	Value	Meaning
0	Reset	UINT8	0x4B	Cold reset
			0x0E	Warm reset
			0x46	Factory reset

*Note* – The factory reset command will delete the stored position and cause self survey to restart.

### Command Packet 0x1F: Request Software Version

This packet requests information about the version of software in the Resolution T. This packet contains no data. The GPS receiver returns packet 0x45.

### Command Packet 0x24: Request GPS Satellite Selection

This packet requests a list of satellites used for the current position/time fix. This packet contains no data. The GPS receiver returns packet 0x6D.

## Command Packet 0x25: Initiate Hot Reset & Self Test

This packet commands the GPS receiver to perform a software (hot) reset. This is not equivalent to cycling the power; RAM is not cleared. The GPS receiver performs a self-test as part of the reset operation. This packet contains no data. Following completion of the reset, the receiver will output the start-up messages. The GPS receiver sends packet 0x45 on power-up reset, and on request; thus, if packet 0x45 appears unrequested, then either the GPS receiver power was cycled or the GPS receiver was reset.

## Command Packet 0x27: Request Signal Levels

This packet requests signal levels for all satellites currently being tracked. This packet contains no data. The GPS receiver returns packet 0x47 hex.

## Command Packet 0x31: Accurate Initial Position (XYZ Cartesian ECEF)

This packet provides an accurate initial position to the GPS receiver in XYZ coordinates. Either the single precision or the double precision version of this packet may be used, however, we recommend using the double precision version for greatest accuracy. The GPS receiver uses this position for performing time-only fixes. If a survey is in progress when this command is sent, the survey is aborted, and this position data is used immediately. The Resolution T will automatically switch to the overdetermined timing mode. Note that this position is not automatically saved to flash memory. If you want to save this position, first set the position, wait at least 2 seconds and then use packet 8E-A6 to save the position.

### Single precision data format

Byte	Item	Type	Units
0-3	X-axis	Single	Meters
4-7	Y-axis	Single	Meters
8-11	Z-axis	Single	Meters

### Double precision data format

Byte	Item	Type	Units
0-7	X-axis	Double	Meters
8-15	Y-axis	Double	Meters
16-23	Z-axis	Double	Meters

## Command Packet 0x32: Accurate Initial Position (Latitude, Longitude, Altitude)

This packet provides an accurate initial position to the GPS receiver in latitude, longitude, and altitude coordinates. Either the single precision or the double precision version of this packet may be used, however, we recommend using the double precision version for greatest accuracy. The GPS receiver uses this position for performing time-only fixes. If a survey is in progress when this command is issued, the survey is aborted, and this position data is used immediately. The coordinates entered must be in the WGS-84 datum. The Resolution T will automatically switch to the overdetermined timing mode. Note that this position is not automatically saved to flash memory. If you want to save this position, first set the position, wait at least 2 seconds and then use packet 8E-A6 to save the position.

*Note* – When converting from degrees to radians use the following value for  $\pi$ :

3.1415926535898

### Single precision data format

Byte	Item	Type	Units
0-3	Latitude	Single	Radians, north
4-7	Longitude	Single	Radians, east
8-11	Altitude	Single	Meters

### Double precision data format

Byte	Item	Type	Units
0-7	Latitude	Double	Radians, north
8-15	Longitude	Double	Radians, east
16-23	Altitude	Double	Meters

## Command Packet 0x34: Satellite Select For One-Satellite Mode

This packet allows the user to control the choice of the satellite to be used for the one-satellite time-only fix mode. This packet contains one byte. If the byte value is 0, the GPS receiver automatically chooses the best. This automatic selection of the best satellite is the default action, and the GPS receiver does this unless it receives this packet. If the byte value is from 1 to 32, the packet specifies the PRN number of the satellite to be used.

## Command Packet 0x35: Set or Request I/O Options

This packet requests the current I/O option states and allows the I/O option states to be set as desired.

To request the option states without changing them, the user sends this packet with no data bytes. To change any option states, the user includes 4 data bytes with the values. The I/O options, their default states, and the byte values for all possible states are shown below. These options can be set into non-volatile memory ( flash ROM) with the 0x8E-26 command. The GPS receiver returns packet 0x55.

These abbreviations apply to the following table:

- ALT (Altitude)
- ECEF (Earth-centered, Earth-fixed)
- XYZ (Cartesian coordinates)
- LLA (latitude, longitude, altitude)
- HAE (height above ellipsoid)
- WGS-84 (Earth model (ellipsoid))
- MSL geoid (Earth (mean sea level) mode)
- UTC (coordinated universal time)

Byte	Data Type	Bit	Default	Value	Meaning	Associated Packet
0	Position	0	0	0	ECEF off	0x42 or 0x83
				1	ECEF on	
		1	1	0	LLA off	0x4A or 0x84
				1	LLA on	
		2	0	0	HAE (datum)	0x4A or 0x84
				1	MSL geoid (Note 1)	
		3	0	0	reserved	
				4	1	
		1	double-precision position			
		5:7	0		reserved	
1	velocity	0	0	0	ECEF off	0x43
				1	ECEF on	
		1	1	0	ENU off	0x56
				1	ENU on	
		2:7	0		reserved	
2	timing	0	0	0	GPS time reference	0x42, 0x43, 0x4A, 0x83, 0x84, 0x56,
				1	UTC time reference	
3	auxiliary	0	0	0	packet 5A off	0x5A
				1	packet 5A on	
		1	0	0	reserved	
				2	reserved	
		3	0	0	output AMU	0x5A, 0x5C, 0x47
				1	output dB/ Hz	
		4:7	reserved	0	0	

**Note** – When using the MSL altitude output, the current datum must be set to WGS-84.

## Command Packet 0x37: Request Status and Values of Last Position

This packet requests information regarding the last position fix (normally used when the GPS receiver is not automatically outputting fixes). The GPS receiver returns the position/velocity auto packets specified in the 0x35 message as well as message 0x57. This packet contains no data.

## Command Packet 0x38: Request Satellite System Data

This packet requests current satellite data. The GPS receiver returns packet 0x58.

Byte	Item	Type	Value	Meaning
0	Operation	UINT8	1	Must always be '1'
1	Type of data	UINT8	2	Almanac
			3	Health page, toa, WNa
			4	Ionosphere
			5	UTC
			6	Ephemeris
2	Sat PRN#	UINT8	0	Data not satellite ID specific
			1 - 32	Satellite PRN number

## Command Packet 0x39: Set or Request SV Disable and Health Use



**CAUTION** – Improperly ignoring health can cause the GPS receiver software to lock up, as an unhealthy satellite may contain defective data. Use extreme caution in ignoring satellite health.

Normally the GPS receiver selects only healthy satellites (based on transmitted values in the ephemeris and almanac) which satisfy all mask values. This packet allows overriding the internal logic and forces the receiver to either unconditionally disable a particular satellite or to ignore a bad health flag. The GPS receiver returns packet 0x59 if operation 3 or 6 is requested; otherwise there is no reply.

It should be noted that when viewing the satellite disables list, the satellites are not numbered but are in numerical order. The disabled satellites are signified by a "1" and enabled satellites are signified by a "0".

Byte	Item	Type	Value	Meaning
0	Operation	UINT8	1	Enable satellite (default)
			2	Disable satellite
			3	Request enable/disable status of all 32 satellites
			4	Heed health (default)
			5	Ignore health
			6	Request heed - or - ignore health on all 32 satellites

Byte	Item	Type	Value	Meaning
1	Satellite #	UINT8	0 1 - 32	All 32 satellites Any one satellite PRN number

*Note – At power-on and after a reset the default values are set for all satellites.*

### Command Packet 0x3A: Request last raw Measurement

This packet requests the most recent raw measurement data for one specified satellite. The GPS receiver returns packet 0x5A if data is available.

Byte	Item	Type	Value	Meaning
0	Satellite number	INT8	0 1-32	All satellites in current tracking set Specific desired satellite

### Command Packet 0x3C: Request Current Satellite Tracking Status

This packet requests the current satellite tracking status. The GPS receiver returns packet 0x5C if data is available.

Byte	Item	Type	Value	Meaning
0	Satellite number	INT8	0 1-32	All satellites in current tracking set Specific desired satellites

### Command Packet 0x7A: Set or Request NMEA Interval and Message Mask

The NMEA message determines whether or not a given NMEA message will be output. If the bit for a message is set, the message will be sent every "interval" seconds. To determine the NMEA interval and message mask, use the values shown below. While fixes are being generated the output order is: ZDA, GGA, GLL, VTG, GSA, GSV, RMC.

Byte	Bit	Item	Type	Value	Meaning
0		Subcode	UINT8	0	
1		Interval	UINT8	1-225	Fix interval in seconds
2		Reserved	UINT8	0	
3		Reserved	UINT8	0	
4	0	RMC	Bit	0 1	On Off
5	1-7	Reserved	Bit	0	
5	0	GGA	Bit	0 1	On Off
5	1	GGL	Bit	0 1	On Off
5	2	VTG	Bit	0 1	On Off



Byte	Bit	Item	Type	Value	Meaning
5	3	GSV	Bit	0	On
				1	Off
5	4	GSA	Bit	0	On
				1	Off
5	5	ZDA	Bit	0	On
				1	Off
5	6-7	Reserved	Bit	0	

### Report Packet 0x7B: Set NMEA Message Output

This packet is sent in response to command packet 7A and has the same data format as packet 7A.

### Report Packet 0x42: Single-precision Position Fix

This packet provides current GPS position fix in XYZ ECEF coordinates. If the I/O "position" option is set to "XYZ ECEF" and the I/O "Precision-of-Position output" is set to single-precision, then the GPS receiver sends this packet each time a fix is computed and at start-up. The data format is shown below.

Byte	Item	Type	Units
0-3	X	Single	meters
4-7	Y	Single	meters
8-11	Z	Single	meters
12-15	time-of-fix	Single	seconds

The time-of-fix is in GPS time or UTC as selected by the I/O "timing" option in command packet 0x35. Packet 0x83 provides a double-precision version of this information.

### Report Packet 0x43 Velocity Fix, XYZ ECEF

This packet provides current GPS velocity fix in XYZ ECEF coordinates. If the I/O "velocity" option (packet 0x35) is set to "XYZ ECEF", then the GPS receiver sends this packet each time a fix is computed or in response to packet 0x37. The data format is shown below. The time-of-fix is in GPS or UTC as selected by the I/O "timing" option.

Byte	Item	Type	Units
0-3	X velocity	Single	meters/second
4-7	Y velocity	Single	meters/second
8-11	Z velocity	Single	meters/second
12-15	bias rate	Single	meters/second
16-19	time-of-fix	Single	seconds

## Report Packet 0x45: Software Version Information

This packet provides information about the version of software in the Resolution T. The GPS receiver sends this packet after power-on and in response to packet 0x1F.

Byte	Item	Type
0	Major version number of application	UINT8
1	Minor version number	UINT8
2	Month	UINT8
3	Day	UINT8
4	Year number minus 1900	UINT8
5	Major revision number of GPS core	UINT8
6	Minor revision number	UINT8
7	Month	UINT8
8	Day	UINT8
9	Year number minus 1900	UINT8

*Note* – Bytes 0 through 4 are part of the application layer of the firmware, while bytes 5 through 9 are part of the GPS core layer of the firmware.

## Report Packet 0x47: Signal Level for All Satellites Tracked

This packet provides received signal levels for all satellites currently being tracked or on which tracking is being attempted (i.e., above the elevation mask and healthy according to the almanac). The receiver sends this packet only in response to packet 0x27. The data format is shown below. Up to 12 satellite number/signal level pairs may be sent, indicated by the count field. Signal level is normally positive. If it is zero then that satellite has not yet been acquired. If it is negative then that satellite is not currently in lock. The absolute value of signal level field is the last known signal level of that satellite.

Byte	Item	Type
0	count	UINT8
1	satellite number 1	UINT8
2- 5	signal level 1	Single
6	satellite number 2	UINT8
7-10	signal level 2	Single
(etc.)	(etc.)	(etc.)

*Note* – The signal level provided in this packet is a linear measure of the signal strength after correlation or de-spreading. Units, either AMU or dB/Hz, are controlled by packet 0x35.

## Report Packet 0x4A: Single Precision LLA Position Fix

The packet provides current GPS position fix in LLA (latitude, longitude, and altitude) coordinates. If the I/O position option is set to "LLA" and the I/O precision of position output is set to single precision, then the receiver sends this packet each time a fix is computed. The data format is shown below:

Byte	Item	Type	Units
0-3	latitude	Single	radians: + for north, - for south
4-7	longitude	Single	radians: + for east, - for west
8-11	altitude	Single	meters
12-15	clock Bias	Single	meters (always relative to GPS)
16-19	time of fix	Single	seconds

The LLA conversion is done according to the datum selected using packet 8E-15. The default is WGS-84. Altitude is referred to the datum or the MSL Geoid, depending on which I/O LLA altitude option is selected with packet 0x35. The time of fix is in GPS time or UTC, depending on which I/O timing option is selected.



**CAUTION** – When converting from radians to degrees, significant and readily visible errors will be introduced by use of an insufficiently precise approximation for the constant  $\pi$  (pi). The value of a constant  $\pi$  as specified in ICDGPS-200 is 3.1415926535898.



**CAUTION** – The MSL option is only valid with the WGS-84 datum. When using other datums, only the HAE option is valid.

## Report Packet 0x55 I/O Options

This packet provides the current I/O option states in response to packet 0x35 request. The data format is the same as for packet 0x35 and is repeated below for convenience.

These abbreviations apply to the following table:

ALT (Altitude)  
 ECEF (Earth-centered, Earth-fixed)  
 XYZ (Cartesian coordinates)  
 LLA (latitude, longitude, altitude)  
 HAE (height above ellipsoid)  
 WGS-84 (Earth model (ellipsoid))  
 MSL geoid (Earth (mean sea level) mode)  
 UTC (coordinated universal time)

Byte	Data Type	Bit	Default	Value	Meaning	Associated Packet
0	UINT8 Position	0	0	0	ECEF on	0x42 or 0x83
				1	ECEF off	
		1	1	0	LLA off	0x4A or 0x84
				1	LLA on	

Byte	Data Type	Bit	Default	Value	Meaning	Associated Packet
1	UINT8 velocity	2	0	0	HAE (datum)	0x4A or 0x84
				1	MSL geoid	
		3	0	0	reserved	
				4	1	0
				1	double-precision position	
		5:7	0		reserved	
		0	0	0	ECEF off	0x43
				1	ECEF on	
		1	1	0	ENU off	0x56
				1	ENU on	
2:7	0		reserved			
2	UINT8 timing	0	0	0	GPS time reference	0x42, 0x43, 0x4A, 0x83, 0x84, 0x56,
				1	UTC time reference	
3	UINT8 auxiliary	0	0	0	packet 5A off	0x5A
				1	packet 5A on	
		1	0	0	raw PR's in 5A	0x5A
				1	filtered PR's in 5A	
		2	reserved			
		3	0	0	output AMU	0x5A, 0x5C, 0x47
				1	output dB/Hz	
		4:7	reserved	0	0	

### Report Packet 0x56: Velocity Fix, East-North-Up (ENU)

If East-North-Up (ENU) coordinates have been selected for the I/O "velocity" option, the receiver sends this packet under the following conditions:

- Each time that a fix is computed
- In response to packet 0x37 (last known fix)

The data format is shown below.

Byte	Item	Type	Units
0-3	East Velocity	Single	m/s; + for east, - for west
4-7	North Velocity	Single	m/s; + for north, - for south
8-11	up velocity	Single	m/s; + for up, - for down
12-15	clock bias rate	Single	m/s
16-19	time-of-fix	Single	seconds

*Note* – The time-of-fix is in GPS or UTC time as selected by the I/O "timing" option.

## Report Packet 0x57: Information about Last Computed Fix

This packet provides information concerning the time and origin of the previous position fix. The receiver sends this packet, among others, in response to packet 0x37. The data format is shown below.

Byte	Item	Type	Value	Meaning
0	source of info	UINT8	0	none
			1	regular fix initialization
			2	diagnostic initialization
			4	diagnostic entered by 0x23 or 0x2B
			5	entered by 0x31 or 0x32
			6	default after BBRAM fail
			8	
			8	
1	Tracking mode	UINT8	0	No previous fix
			1	Time only -SV
			2	2D clock hold
			3	2D
			4	3D
			5	overdetermined clock
			6	DGPS reference
2-5	time of last fix	Single		seconds GPS time
6-7	week of last fix	UINT16		weeks

## Report Packet 0x58: GPS System Data/Acknowledge from Receiver

This packet provides GPS data (almanac, ephemeris, etc.). The receiver sends this packet in response to packet 0x38. The data format is shown below. The table and section numbers referred to in the "Meaning" column reference the *Global Positioning System Standard Positioning Service Signal Specification* document.

### Data Format

Byte	Item	Type	Value	Meaning
0	operation	UINT8	2	data out
			3	no data on SV
1	Type of data	UINT8	2	Almanac
			3	Health page, T_oa, WN_oa
			4	Ionosphere
			5	UTC
			6	Ephemeris
			6	
2	Sat PRN #	UINT8	0	Data that is not satellite ID-specific
			1 to 32	Satellite PRN number
3	Length (n)	UINT8		Byte count
4 to n+3	Data	UINT8		Table 2.8

*Note* – If data is not available, byte 3 is set to 0 and "no" data is sent.

**Almanac data type 2**

Byte	Item	Type	Value	Meaning
4	Toa (raw)	UINT8		Table 2.8
5	SV_HEALTH	Single		
6-9	e	Single		
10-13	t <sub>oa</sub>	Single		
14-17	i <sub>o</sub>	Single		
18-21	OMEGADOT	Single		
22-25	sqrt(A)	Single		
26-29	(OMEGA)0	Single		
30-33	(OMEGA)	Single		
34-37	M <sub>0</sub>	Single		
38-41	af <sub>0</sub>	Single		
42-45	af <sub>1</sub>	Single		
46-49	Axis	Single		
50-53	n	Single		
54-57	OMEGA_n	Single		Derived
58-61	ODOT_n	Single		Derived
62-65	t <sub>zc</sub>	UINT16		time of collection (set to -1.0 if there is no data available)
66-67	week number	UINT16		GPS week number
68-69	WN <sub>a</sub>	UINT16		Sec 2.4.5.2.3

*Note – All angles are in radians.*

**Almanac health data type 3**

Byte	Item	Type	Meaning
4	week number for health	UINT8	Sec 2.4.5.3
5-36	SV health	UINT8	Sec 2.4.5.3
37	t <sub>oa</sub> for health	UINT8	Sec 2.4.5.2.3
38	current t <sub>oa</sub>	UINT8	time of collection
39-40	current week number	UINT16	time of collection

**Ionosphere data type 4**

Byte	Item	Type	Meaning
4-11	not used		
12-15	$\alpha_0$	Single	Sec 2.4.5.6
16-19	$\alpha_1$	Single	
20-23	$\alpha_2$	Single	
24-27	$\alpha_3$	Single	
28-31	$\beta_0$	Single	

Byte	Item	Type	Meaning
32-35	$\beta_1$	Single	
36-39	$\beta_2$	Single	
40-43	$\beta_3$	Single	

### UTC data type 5

Byte	Item	Type	Meaning
4-16	not used		
17-24	$A_0$	Double	Sec 2.4.5.5
25-28	$A_1$	Single	
29-30	$\Delta t_{LS}$	SINT16	
31-34	$t_{ot}$	Single	
35-36	$WN_t$	UINT16	
37-38	$WN_{LSF}$	UINT16	
39-40	DN	UINT16	
41-42	$\Delta t_{LSf}$	SINT16	

### Ephemeris data type 5

Byte	Item	Type	Meaning
4	SV number	UINT8	SV PRN number
5-8	$t_{ephem}$	Single	time of collection (seconds)
9-10	week number	UINT16	GPS week number 0 thru 1023
11	retired		
12	retired		
13	SV accuracy raw	UINT8	URA index of SV (0 thru 15)
14	SV health	UINT8	6 bit health code
15-16	IODC	UINT16	Issue of data clock
17-20	$t_{GD}$	Single	L1-L2 correction term
21-24	$t_{oc}$	Single	Sec 20.4.3.5
25-28	$a_{f2}$	Single	Sec 2.4.3.6
29-32	$a_{f1}$	Single	
33-36	$a_{fo}$	Single	
37-40	SV accuracy	Single	URA of SV
41	IODE	UINT8	issue of data ephemeris

Byte	Item	Type	Meaning
42	retired		
43-46	$C_{rs}$	Single	
47-50	$\Delta n$	Single	
51-58	$M_0$	Double	
59-62	$C_{uc}$	Single	
63-70	e	Double	
71-74	CUS	Single	
75-82	sqrt(A)	Double	
83-86	$t_{oe}$	Single	Table 2-5
87-90	$C_{ic}$	Single	
91-98	(OMEGA) <sub>0</sub>	Double	
99-102	$C_{is}$	Single	
103-110	$i_o$	Double	
111-114	$C_{rc}$	Single	
115-122	(OMEGA)	Double	
123-126	OMEGADOT	Single	
127-130	IDOT	Single	
131-138	Axis	Double	
139-146	n	Double	
147-154	r1me2	Double	= sqrt (1.0-e <sub>2</sub> )
155-162	OMEGA_n	Double	derived from OMEGA_0, OMEGADOT
163-170	ODOT_n	Double	derived from OMEGADOT

*Note* – All angles are in radians. Reference numbers refer to "Global Positioning System Standard Positioning Service Signal Specification." As of this writing, it is available in Adobe Acrobat format at <http://www.navcen.uscg.gov/pubs/gps/sigspec/>.

### Report Packet 0x59: Status of Satellite Disable or Ignore Health

This packet is sent in response to command packet 0x39.

Byte	Item	Type	Value	Meaning
0	Operation	UINT8	3	The remaining bytes tell whether a receiver is allowed to select each satellite.
			6	The remaining bytes tell whether the receiver heeds or ignores each satellite's health as a criterion for selection.
1 to 32	Satellite #	UINT8 (1 per SV)	0	Enable satellite selection or heed satellite's health. Default value.
			1	Disable satellite selection or ignore satellite's health.



## Report Packet 0x5A: Raw Data Measurement Data

Packet 0x5A provides raw GPS measurement data. If the packet 0x35 auxiliary option byte bit 1 is set, this packet is sent automatically as measurements are taken.

Byte	Item	Type	Units
0	SV PRN number	UINT8	
1-4	sample length	single	milliseconds
5-8	signal level	single	AMU or dB/Hz
9-12	code phase	single	1/16th chip
13-16	doppler	single	Hertz @ L1
17-24	time of measurement	double	seconds

**Note** – The sample length is the number of milliseconds over which the sample was averaged.

**Note** – The code phase value is the average delay over the sample interval of the received C/A code, and is measured with respect to the receiver's millisecond timing reference.

## Report Packet 0x5C: Satellite Tracking Status

The receiver sends this packet in response to command packet 0x3C.

Byte	Bit	Item	Type	Value	Meaning
0		SV PRN number	UINT8	1-32	PRN
1	0:2	slot number	bit field	0 0 0	not used
1	3:7	channel number	bit field	0 0 0 0 0 0 0 1 0 0 1 0 0 0 1 1 0 1 0 0 0 1 0 1 0 1 1 0 0 1 1 1 1 0 0 0 1 0 0 1 1 0 1 0 1 0 1 1	channel 1 channel 2 channel 3 channel 4 channel 5 channel 6 channel 7 channel 8 channel 9 channel 10 channel 11 channel 12
2		acquisition flag	UNIT8	0 1 2	never acquired acquired re-opened search
3		ephemeris flag	UNIT8	0 >0	flag not set good ephemeris
4-7		signal level	Single		AMU or dBHz
8-11		time of last measurement	Single	secs	GPS time of week
1215					

Byte	Bit	Item	Type	Value	Meaning
		elevation angle	single		radians
1619		azimuth angle	single		radians
20		old measurement flag	UINT8	0 >0	flag not set measurement old
21		integer msec flag	UINT8	0 1 2 3 4	don't know msec known from subframe  verified by bit crossing verified by good fix
22		bad data flag	UINT8	0 1 2	flag not set bad parity bad ephemeris health
23		data collection flag	UINT8	0 >0	flag not set collection in progress

### Report Packet 0x6D: All-in-View Satellite Selection

This packet provides a list of satellites used for position or time only fixes by the GPS receiver. The packet also provides the PDOP, HDOP, and VDOP of that set and provides the current mode (automatic or manual, 3-D or 2-D, overdetermined, clock, etc.). This packet has variable length equal to 17+nsvs where "nsvs" is the number of satellites used in the solution. If an SV is rejected for use by the T-RAIM algorithm then the SV PRN value will be negative.

The GPS receiver sends this packet in response to packet 0x24 when the selection list is updated. If enabled with packet 8E-A5, the receiver will send this packet whenever the selection is updated. The data format is shown below.

Byte	Bit	Item	Type	Value	Meaning
0	0:2	fix dimension	bit field	1 3 4 5	1D clock fix 2D fix 3D fix OD clock fix
	3	fix mode	bit field	0 1	auto manual
	4:7	number of SVs in fix	bit field	0-12	count
1-4		PDOP	Single		PDOP
5-8		HDOP	Single		HDOP
9-12		VDOP	Single		VDOP
13-16		TDOP	Single		TDOP
17 - n		SV PRN	SINT8	±(1- 32)	PRN

## Report Packet 0x83: Double Precision XYZ

This packet provides current GPS position fix in XYZ ECEF coordinates. If the I/O "position" option is set to "XYZ ECEF" and the I/O double position option is selected, the receiver sends this packet each time a fix is computed. The data format is shown below.

Byte	Item	Type	Units
0-7	X	Double	meters
8-15	Y	Double	meters
16-23	Z	Double	meters
24-31	clock bias	Double	meters
32-35	time-of-fix	Single	seconds

*Note* – The time-of-fix is in GPS time or UTC, as selected by the I/O "timing" option. Packet 0x42 provides a single-precision version of this information.

## Report Packet 0x84: Double Precision LLA Position Fix and Bias Information

This packet provides current GPS position fix in LLA coordinates. If the I/O "position" option is set to "LLA" and the double position option is selected (see packet 0x35), the receiver sends this packet each time a fix is computed.

Byte	Item	Type	Units
0-7	latitude	Double	radians; + for north, - for south
8-15	longitude	Double	radians; + for east, - for west
16-23	altitude	Double	meters
24-31	clock bias	Double	meters (always relative to GPS)
32-35	time-of-fix	Single	seconds

*Note* – The time-of-fix is in GPS time or UTC time as selected by the I/O "timing" option.



**CAUTION** – When converting from radians to degrees, significant and readily visible errors will be introduced by use of an insufficiently precise approximation for the constant  $\pi$  (PI). The value of the constant PI as specified in ICDGPS-200 is 3.1415926535898.

## Command Packet 0xBB: Set Primary Configuration

In query mode, packet 0xBB is sent with a single data byte and returns report packet 0xBB in the format shown below:

### Data Format (Query Only)

Byte	Item	Type	Value	Meaning	Default
0	Subcode	UINT8	0	Query mode	

TSIP packet 0xBB is used to set GPS Processing options. The table below lists the individual fields within the 0xBB packet.

### Report Packet 0 x BB Data Format

Byte	Item	Type	Value	Meaning	Default
0	Subcode	UINT8	0xFF	Primary receiver configuration block	
1	receiver mode	UINT8	0 1 3 4 5 6 7	automatic single satellite (1 SV) Horizontal (2D) Full position (3D) DGPS reference 2D clock hold Over Determined Clock	#4 (3D)
2	reserved	UINT8	0xFF	do not alter	
3	Dynamics Code	UINT8	1 2 3 4	Land Sea Air Stationary	Land
4	reserved	UINT8	0xFF	do not alter	
5-8	Elevation Mask	Single	0- $\pi/2$	Lowest satellite elevation for fixes (radians)	10 degrees
9-12	AMU Mask	Single		Minimum signal level for fixes	4
13-16	PDOP Mask	Single		Maximum DOP for fixes	12
17-20	PDOP Switch	Single		Switches 2D/3D mode	6
21	reserved	UINT8	0xFF	do not alter	
22	Foliage Mode	UINT8	0 1 2	Never Sometimes Always	Sometimes
23	reserved	UINT8	0xFF	do not alter	
24	reserved	UINT8	0xFF	do not alter	
25	reserved	UINT8	0xFF	do not alter	
26	reserved	UINT8	0xFF	do not alter	
27-39	reserved	UINT8	0xFF	do not alter	



**CAUTION** – The operation of the Resolution T can be affected adversely if incorrect data is entered in the fields associated with packet 0xBB. Know what you are doing.

*Note* – When sending packet 0xBB, fields that are specified as "do not alter" or if you do not want to alter a specific field, send a value of 0xFF for UINT8 types and a value of -1.0 for floating point types. The Resolution T will ignore these values.

## Command Packet 0xBC: Set Port Configuration

TSIP packet 0xBC is used to set and query the port characteristics. In query mode, packet 0xBC is sent with a single data byte and returns report packet 0xBC:

*Note* – The input and output baud rates must be the same.

Byte	Item	Type	Value	Meaning
0	Port Number	UINT8	0	Port 1 (standard)
			1	Port 2 (not available)
			FF	Current port

### Field data format

The table below lists the individual fields within the packet 0xBC when used in the set mode and when read in the query mode:

Byte	Item	Type	Value	Meaning
0	Port to Change	UINT8	0	Port 1 (standard)
			1	Port 2 (factory only)
			0xFF	Current port
1	Input Baud Rate	UINT8	0	None
			1	None
			2	300 baud
			3	600 baud
			4	1200 baud
			5	2400 baud
			6	4800 baud
			7	9600 baud
			8	19200 baud
			9	38400 baud
			10	57600 baud
11	115200 baud			
2	Output Baud Rate	UINT8	As above	As above
3	# Data Bits	UINT8	2	7 bits
			3	8 bits
4	Parity	UINT8	0	None
			1	Odd
			2	Even

Byte	Item	Type	Value	Meaning
5	# Stop Bits	UINT8	0	1 bit
			1	2 bits
6	Flow Control	UINT8	0	none
7	Input Protocols	UINT8	0	none
			2	TSIP
8	Output Protocols	UINT8	0	none
			2	TSIP
			4	NMEA
9	Reserved	UINT8	0	

## TSIP Superpackets

Several packets have been added to the core TSIP protocol to provide additional capability for the receivers. In packets 0x8E and their 0x8F responses, the first data byte is a subcode which indicates the superpacket type. For example, in packet 0x8E-15, 15 is the subcode that indicates the superpacket type. Therefore the ID code for these packets is 2 bytes long followed by the data.

### Command Packet 0x8E-01: Configure Raw GPS Data Output

TSIP super-packet 0x8E-01 is used to configure raw GPS data output.

In the auto-send mode, a subframe is automatically sent out for each tracked satellite as soon as it is decoded (every 6 seconds of continuous tracking). Therefore, in the auto-send mode, at most 12 report packets 0x8F-01 will be sent out every 6 seconds for a 12-channel receiver.

In the request mode, a specific subframe can be queried for a particular satellite. The returned data reflects the last valid subframe collected for that satellite (it may not be current). If the satellite is not tracked, or the specified subframe has not been collected yet, a short report packet is returned with the *Status* field of the packet indicating the error code.

The data fields of this command packet following the packet ID 0x8E are as follows:

Byte	Item	Type	Value	Definition
0	Sub-code	U8	0x01	Packet 0x8E/8F sub-code
1	Operation	U8	0	Turn off auto-send mode
			1	Turn on auto-send mode
			2	Request data for specific SV
2	SV ID	U8	1...32	Satellite ID for which to request data. This field is ignored when Operation is 0 or 1.
3	Subframe ID	U8	0...5	Subframe ID for which to send data (0 to request all subframes for that SV). This field is ignored when Operation is 0 or 1.

## Command Packet 0x8E-15: Request Current Datum Values

This packet contains only the subpacket ID, 0x15. The response to this packet is 8F-15

## Command Packet 0x8E-26: Write Receiver Configuration to Flash ROM

This command packet causes the current configuration settings to be written to the flash ROM. This packet contains only a single byte: the sub-packet ID. Note that the unit will reset itself following the execution of this command.



**WARNING** – The Resolution T GPS receiver is ready to accept TSIP commands approximately 2.1 seconds after power -up. If a command is sent to the receiver within this 2.1 second window, the receiver will ignore the command. The Resolution T GPS receiver will not respond to commands sent within the 2.1 second window and will discard any associated command data.

## Command Packet 0x8E-41: Request Manufacturing Parameters

This packet is used to request the manufacturing parameters stored in nonvolatile memory. Send this packet with no data bytes (don't forget the subcode) to request packet 0x8F-41.

## Command Packet 0x8E-42: Stored Production Parameters

This packet is used to request the production parameters stored in nonvolatile memory. Send this packet with no data bytes (don't forget the subcode) to request packet 0x8F-42.

## Command Packet 0x8E-4A: Set PPS Characteristics

This packet allows the user to query (by sending the packet with no data bytes) or set the Resolution T PPS characteristics. The Resolution T responds to a query or set command with packet 8F-4A.

Byte	Item	Type	Value	Meaning
0	Subcode	UINT8	0x4A	
1	PPS driver switch	UINT8	0 1	off on
2	reserved	UINT8		
3	PPS polarity	UINT8	0 1	positive negative
4-11	PPS offset or cable delay (see note)	Double		seconds
12-15	Bias uncertainty threshold	Single		meters

*Note* – Negative offset values advance the PPS, and are normally used to compensate for cable delay.

### Command Packet 0x8E-4E: Set PPS output option

This command packet sets the PPS driver switch to one of the values listed in Table A-52. The current driver switch value can be requested by sending the packet with no data bytes except the subcode byte.

Driver switch values 3 and 4 only make sense in Overdetermined Timing mode. In any position fix mode the effective choices are always on or during fixes which you get if you set the driver switch to 3 or 4.

The Resolution T can also be configured to generate an Even Second pulse in place of the PPS pulse by setting the value as shown in the table below.

Byte	Item	Type	Value	Meaning
0	Subcode	UINT8	0x4E	
1	PPS driver switch	UINT8	2	PPS is always on. PPS is generated every second
			3	PPS is output when at least one satellite is tracking. PPS is generated every second
			4	PPS is output when at least three satellites are tracking. PPS is generated every second
			130	PPS is always on. PPS is generated every even second
			131	PPS is output when at least one satellite is tracking. PPS is generated every even second
			132	PPS is output when at least three satellites are tracking. PPS is generated every even second.

### Command Packet 0x8E-A2: UTC/GPS Timing

Command packet 8E-A2 sets the UTC/GPS timing mode (time and date fields) in packet 0x8F-AB, and the temporal location of the Resolution T output PPS. Send packet 8E-A2 with no data to request the current settings. The Resolution T replies with response packet 8F-A2.

Byte	Bit	Item	Type	Value	Meaning
0		Subcode	UINT8	0xA2	
1	0 1	UTC/GPS time	bit field	0	GPS time/date in packet 0x8F-AB
			bit field	1	UTC time/date in packet 0x8F-AB
				0	PPS referenced to GPS time
				1	PPS referenced to UTC time



## Command Packet 0x8E-A4: Test Modes

The Resolution T provides a test mode of operation that allows the user to set the time and UTC parameters. Packet 0x8F-AC provides a status bit (minor alarm bit 8) to warn the user that the Resolution T is operating in a test mode. There is no response to this packet.

Note that test mode 3 does not actually cause the Resolution T to enter a test mode, but instead provides a means for the user to send UTC parameters to the Resolution T that will be used in test mode 1.

### Test Mode 0 Data Fields

Field	Description
Test Mode	Set this field to 0 to exit test mode and return the Resolution T to normal operations. A reset or power cycle will also cause the Resolution T to exit test mode.

Test Mode 0 Data Format:

Byte	Item	Type	Description
0	Subcode	UINT8	0xA4
1	Test Mode	UINT8	0 = Exit test mode

### Test Mode 1 Data Fields

Field	Description
Test Mode	Setting this field to 1 tells the Resolution T to enter the user time test mode. The Resolution T will set the time to the week number and TOW sent with this packet. The Resolution T will then increment this time once per second. The time in packets 8F-AB and 8F-A7 will show the user test time, but all other packets that have time fields will be unaffected.
Week Number	This field contains the week number for the user time test mode
Time-of-Week	This field contains the TOW for the user time test mode

Test Mode 1 Data Format:

Byte	Item	Type	Description
0	Subcode	UINT8	0xA4
1	Test Mode	UINT8	1 = Set absolute time, ignore GPS time
2-3	Week Number	UINT16	Week number (0-1023)
4-7	Time of Week	UINT32	Seconds (0-604799)

## Test Mode 3 Data Fields

*Note* – For a more detailed description of UTC parameters see the GPS SPS Signal Specification.

Field	Description
Test Mode	Setting this field to 3 tells the Resolution T that the following fields contain the user UTC parameters that are to be used while in test mode 1.
A_0	This field is the fractional second offset of GPS from UTC at the reference time in seconds
A_1	This field is the rate of change of fractional second offset of GPS from UTC in seconds/second.
delta_t_LS	Current integer leap seconds
t_ot	This field is the reference time-of-week for the A_0/A_1 parameters.
WN_t	This field is the reference week number for the A_0/A_1 parameters.
WN_LSF	This field is the week number of a future leap second event.
DN	This field is the day number of a future leap second event.
delta_t_LSF	This field is the integer number of future leap seconds.

Test Mode 3 Data Format:

Byte	Item	Type	Description
0	Subcode	UINT8	0xA4
1	Test Mode	UINT8	3 = Send user UTC parameter
2-5	A_0	Single	Seconds
6-9	A_1	Single	Seconds/second
10-11	delta_t_LS	SINT16	Seconds
12-15	t_ot	UINT32	Seconds
16-17	WN_t	UINT16	Week number
18-19	WN_LSF	UINT16	Week number
20-21	DN	UINT16	Day number (1-7)
22-23	delta_t_LSF	SINT16	Seconds

## Command Packet 0x8E-A5: Packet Broadcast Mask

Use command packet 8E-A5 to set the packet broadcast masks or to request the current mask settings. The Resolution T replies to requests with response packet 8F-A5. The broadcast mask is bitwise encoded to allow the user to turn on and off the broadcast of certain packets. For those broadcast packets that have multiple format, the Resolution T will broadcast only one of the formats. If more than one of the formats is masked on for broadcast, then the format with the greatest precision of content masked on will be sent and the rest will not. For each bit in the mask that is used, the coding is as follows:

0: Turn off broadcast of this packet

1: Turn on broadcast of this packet

Byte	Bit	Item	Type	Description
0		Subcode	UINT8	0xA5
1-2	0	Mask 0	bit field	8F-AB, Primary Timing Information
	1			Reserved
	2			8F-AC, Supplemental Timing Information
	3			Reserved
	4			Reserved
	5			Reserved
	6			Automatic Output Packets
3-4		Mask 2	bit field	reserved

### Command Packet 0x8E-A6: Self-Survey Command

Use command packet 8E-A6 to issue a self-survey command, to save the current position in flash or to delete the position saved in flash. There is no response to this packet.

Byte	Item	Type	Value	Meaning
0	Subcode	UINT8	0xA6	
1	Self-survey command	UINT8	0	Restart self-survey
			1	Save position to Flash
			2	Delete position from Flash

### Command Packet 0x8E-A9: Self-Survey Parameters

Use command packet 8E-A9 to set the self-survey parameters or to request the current settings. The Resolution T replies to requests with response packet 8F-A9.

#### Data fields

- Self-Survey Enable: Use this field to enable or disable the self-survey mechanism.
  - 0: Disable the self-survey mechanism
  - 1: Enable the self-survey mechanism
- Position Save Flag: Use this field to tell the self-survey mechanism to automatically save (or to not save) the self-surveyed position at the end of the self-survey procedure.
  - 0: Don't automatically save the surveyed position when the self-survey is complete
  - 1: Automatically save the surveyed position when the self-survey is complete.

- Self-Survey Length: Use this field to specify the number of position fixes that are to be averaged together to form the self-surveyed position used for clock-only fixes.

Limits: 1 to  $(2^{32} - 1)$  fixes

Byte	Item	Type	Value	Description
0	Subcode	UINT8	0xA9	
1	Self-Survey Enable	UINT8	0 1	Disabled Enabled
2	Position Save Flag	UINT8	0 1	Don't save position Save self-surveyed position at the end of the survey
3-6	Self-Survey Length	UINT3 2	see above	Number of fixes
7-10	Reserved	UINT3 2	0	0

### Report Packet 0x8F-01: Report Raw GPS Subframes

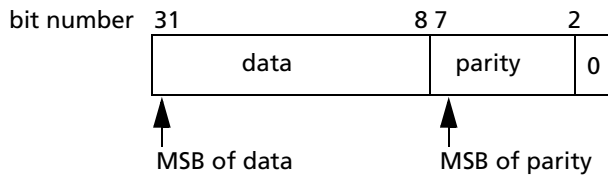
TSIP super-packet 0x8F-01 is used to report raw GPS subframes. A report is sent for a specific SV with a specific GPS subframe based on the Operation selected using the command packet 0x8E-01.

This packet may have different lengths depending on the value of the Status field. If Status is 0, the packet consists of 45 bytes including all 10 subframe data words. If Status is not 0, only the first 4 bytes are sent.

The data fields of this report packet following the packet ID 0x8F are as follows:

Byte	Item	Type	Value	Definition
0	Sub-code	U8	0x01	Packet 0x8E/8F sub-code
1	Status	U8	0 1 2	Request successful or auto-send mode. Requested SV is not being tracked. Requested Subframe not decoded yet.
2	SV ID	U8	1 ... 32	SV ID for which a subframe was requested and/or decoded.
3	Subframe ID	U8	1 ... 5	Subframe ID (requested and/or decoded).
4	Week number	U8	0 ... 255	Current 8-bit week number.
5-8	Word	U32	NOTE 1	Subframe Word 1 (TLM)
9-12	Word	U32	NOTE 1	Subframe Word 2 (HOW)
13-16	Word	U32	NOTE 1	Subframe Word 3
17-20	Word 4	U32	NOTE 1	Subframe Word 4
21-24	Word 5	U32	NOTE 1	Subframe Word 5
25-28	Word 6	U32	NOTE 1	Subframe Word 6
29-32	Word 7	U32	NOTE 1	Subframe Word 7
33-36	Word 8	U32	NOTE 1	Subframe Word 8
37-40	Word 9	U32	NOTE 1	Subframe Word 9
41-44	Word 10	U32	NOTE 1	Subframe Word 10

**Note** – Each 32-bit word of the subframe has the following bit format:



Where:

Bits 0, 1 – unused bits (0's)

Bits 2...7 – parity bits (most significant parity bit is at Bit 7)

Bits 8...31 – data bits (most significant data bit is at Bit 31)

## Report Packet 0x8F-15: Current Datum Values

This packet contains 43 data bytes with the values for the datum currently in use and is sent in response to packet 8E-15. If a built-in datum is being used, both the datum index and the five double-precision values for that index are returned. If the receiver is operating on a custom user-entered datum, the datum index is set to -1 and the five values are displayed. These five values describe an ellipsoid to convert ECEF XYZ coordinate system into LLA.

Byte	Type	Value	Description
0	Super Packet ID	14	
1-2	Datum index (-1 for custom)	Datum Index	
3-10	DOUBLE	DX	meters
11-18	DOUBLE	DY	meters
19-26	DOUBLE	DZ	meters
27-34	DOUBLE	A-axis	meters
35-42	DOUBLE	Eccentricity squared	none

## Report Packet 0x8F-41: Stored Manufacturing Operating Parameters

This packet is sent in response to a command 0x8E-41.

Byte	Item	Type	Units
0	Subcode	UINT8	0x41
1-2	board serial number prefix	SINT16	
3-6	Board serial number	UINT32	
7	Year of build	UINT8	
8	Month of build	UINT8	
9	Day of build	UINT8	
10	Hour of build	UINT8	
11-14	Oscillator offset	Single	

Byte	Item	Type	Units
15-16	Test code identification number	UINT16	

### Report Packet 0x8F-42: Stored Production Parameters

This packet is sent in response to 0x8E-42.

Byte	Item	Type	Units
0	Subcode	UINT8	0x42
1	Production options prefix	UINT8	
2	Production number extension	UINT8	
3-4	Case serial number prefix	UINT16	
5-8	Case serial number	UINT32	
9-12	Production number	UINT32	
13-14	Reserved	UINT16	
15-16	Machine identification number	UINT16	
17-18	Reserved	UINT16	

### Report Packet 0x8F-4A: Set PPS Characteristics

This is sent in response to a query by packet 0x8E-4A. See the corresponding command packet for information about the data format.

### Report Packet 0x8F-4E: PPS Output

This report packet is output after the command packet 8E-4E has been executed. See the corresponding command packet for information about the data format.

### Report Packet 0x8F-A2: UTC/GPS Timing

This packet is sent in response to command packet 0x8E-A2. See the corresponding command packet for information about the data format.

### Report Packet 0x8F-A5: Packet Broadcast Mask

This packet is sent in response to 0x8E-A5 command and describes which packets are currently automatically broadcast. A '0' in a bit field turns off broadcast, and a '1' in a bit field enables broadcast. See the corresponding command packet for information about the data format.

## Report Packet 0x8F-A9: Self-Survey Parameters

Packet 0x8F-A9 is sent in response to command packet 0x8E-A9 and describes the current self-survey parameters. See the corresponding command packet for information about the data format.

## Report Packet 0x8F-AB: Primary Timing Packet

This broadcast packet provides time information once per second. GPS week number, GPS time-of-week (TOW), UTC integer offset, time flags, date and time-of-day (TOD) information is provided. This packet cannot be requested. If enabled, this packet will begin transmission within 20 ms after the PPS pulse to which it refers.

### Data fields

- Time of Week: This field represents the number of seconds since Sunday at 00:00:00 GPS time for the current GPS week. Time of week is often abbreviated as TOW.
- Week Number: This field represents the current GPS week number. GPS week number 0 started on January 6, 1980.
- UTC Offset: This field represents the current integer leap second offset between GPS and UTC according to the relationship:  $\text{Time (UTC)} = \text{Time (GPS)} - \text{UTC Offset}$ . The UTC offset information is reported to Resolution T by the GPS system and can take up to 12.5 minutes to obtain. Before the Resolution T has received UTC information from the GPS system, it is only capable of representing time in the GPS time scale, and the UTC offset will be shown as 0.
- Timing Flags: This field is bitwise encoded to provide information about the timing outputs. Unused bits should be ignored.
  - Bit 0: When 0, the date and time fields broadcast in packet 8F-AB are in the GPS time scale. When 1, these fields are in the UTC time scale and are adjusted for leap seconds. Use command packet 8E-A2 to select either GPS or UTC time scales.
  - Bit 1: When 0, the PPS output is aligned to GPS. When 1, the PPS output is aligned to UTC. Use command packet 8E-A2 to select either GPS or UTC PPS alignment.
  - Bit 2: When 0, time has been set from GPS. When 1, time has not yet been set from GPS.
  - Bit 3: When 0, UTC offset information has been received. When 1, UTC offset information is not yet known.
  - Bit 4: When 0, time is coming from GPS. When 1, the Resolution T is in a test mode and time is being generated by the test mode selected by the user.

See packet 8E-A4, Test Modes.

- Time of Day: The time of day is sent in hours-minutes-seconds format and varies from 00:00:00 to 23:59:59, except when time is in UTC and a leap second insertion occurs. In this case the time will transition from 23:59:59 to 23:59:59 to 00:00:00. Use command packet 8E-A2 to select either the GPS or UTC time scale.
- Date: The date is sent in day-month-year format. Use command packet 8E-A2 to select either the GPS or UTC time scale.

### Broadcast Control: Packet 8F-AB, Mask 0, Bit 0

Byte	Bit	Item	Type	Value	Description	
0		Subcode	UINT8		0xAB	
1-4		Time of week	UINT32		GPS seconds of week	
5-6		Week number	UINT16		GPS week number (see above)	
7-8		UTC Offset	SINT16		UTC Offset (seconds)	
9	0	Timing flag	bit field	0	GPS time	
				1	UTC time	
				1	GPS PPS	
				1	UTC PPS	
				2	0	time is set
				2	1	time is not set
				3	0	have UTC info
				3	1	no UTC info
				4	0	time from GPS
4	1	time from user				
10		Seconds	UINT8	0-59	Seconds	
11		Minutes	UINT8	0-59	Minutes	
12		Hours	UINT8	0-23	Hours	
13		Day of Month	UINT8	1-31	Day of month	
14		Month	UINT8	1-12	Month of year	
15-16		Year	UINT16		Four digits of year (for example 1998)	

### Report Packet 0x8F-AC: Supplemental Timing Packet

This broadcast packet provides supplemental timing information once per second. Information regarding position, unit status and health, and the operational state of the unit is provided. This packet cannot be requested. When enabled, this packet is transmitted once per second shortly after packet 8F-AB.

The position sent in packet 8F-AC depends on the Receiver Operating Mode and on self-survey activity. When a self-survey is in progress, the position sent is the running average of all of the position fixes collected so far. When the self-survey ends or whenever the receiver is using a time-only operating mode, then the position sent is



the accurate position the receiver is using to perform time-only fixes. When the self-survey is disabled or otherwise inactive and the receiver is using a position fix operating mode, then the position sent is the position fix computed on the last second.

### Data fields

- **Receiver Mode:** This field shows the fix mode that the GPS receiver is currently configured for. The Resolution T spends most of its time in the Overdetermined Clock mode where it uses all available satellites to perform the best time-only fix possible. See packet BB for a description of all available receiver modes.
- **Self-Survey Progress:** When a self-survey procedure is in progress, this field shows the progress of the survey as a percentage of fixes collected so far. The self-survey will be complete when the self-survey progress reaches 100 percent.
- **Minor Alarms:** This field is bitwise encoded with several minor alarm indicators. A minor alarm indicates a condition that the user should be alerted to, but does not indicate an immediate (or necessarily any) impairment of functionality. For each bit, a value of 0 means that the condition is not indicated. Bits not described below should be ignored.
  - **Bit 1:** When 1, indicates that the antenna input connection is open. More precisely, this bit indicates that the antenna input is not drawing sufficient current. Normally, the Resolution T provides power to the antenna's LNA (Low Noise Amplifier) through the center conductor of the antenna cable. On-board circuitry senses this current draw, and if low, this condition will be indicated. However, when the antenna is powered elsewhere (e.g. when using a splitter) then an antenna open condition is expected and does not imply a fault nor does it impair the operation of the Resolution T.
  - **Bit 2:** When 1, indicates that the antenna input is shorted. More precisely, this bit indicates that the antenna input is drawing too much current. Onboard protection circuitry prevents any damage to the Resolution T when its antenna input is shorted to ground. This condition tends to indicate a fault in either the antenna cable or the antenna itself.
  - **Bit 3:** When 1, indicates that no satellites are yet usable. In order for a satellite to be usable, it must be tracked long enough to obtain ephemeris and health data.
  - **Bit 5:** When 1, indicates that a self-survey procedure is in progress.
  - **Bit 6:** When 1, indicates that there is no accurate position stored in flash ROM.
  - **Bit 7:** When 1, indicates that the GPS system has alerted the Resolution T that a leap second transition is pending.
  - **Bit 8:** When 1, indicates that the Resolution T is operating in one of its test modes.

- Bit 9: When 1, indicates that the accuracy of the position used for time only fixes is questionable. This alarm may indicate that the unit has been moved since the unit completed the last self-survey. If this alarm persists, resurvey the position of the unit.
- Bit 11: When 1, indicates that the Almanac is not current or complete.
- Bit 12: When 1, indicates that the PPS was not generated this second. This could mean that there wasn't enough usable satellites to generate an accurate PPS output. It could also mean that the unit is generating an Even Second output (see Packet 8E-4E) and the unit did not output a PPS on the odd second.
- GPS Decoding Status: This field indicates the decoding status of the GPS receiver.
- Local Clock Bias: This field contains the bias of the local clock. Note that this data cannot be used to increase the accuracy of the PPS output.
- Local Clock Bias Rate: This field contains the bias rate of the local clock. Note that this data cannot be used to increase the accuracy of the PPS output.
- Temperature: This field shows the temperature (in Celsius) as reported by the Resolution T's on-board temperature sensor.
- Latitude: This field carries the latitude of the position being shown. The units are in radians and vary from  $-\pi/2$  to  $+\pi/2$ . Negative values represent southern latitudes. Positive values represent northern latitudes.
- Longitude: This field carries the longitude of the position being shown. The units are in radians and vary from  $-\pi$  to  $+\pi$ . Negative values represent western longitudes. Positive values represent eastern longitudes.
- Altitude: This field carries the altitude of the position being shown. The units are in meters (WGS-84.)
- PPS Quantization Error: This field carries the PPS quantization error in units of seconds.

Byte	Item	Type	Value	Description
0	Subcode	UINT8	0xAC	
1	Receiver Mode	UINT8	0	Automatic (2D/3D)
			1	Single Satellite (Time)
			3	Horizontal (2D)
			4	Full Position (3D)
			5	DGPR Reference
			6	Clock Hold (2D)
			7	Overdetermined Clock

Byte	Item	Type	Value	Description
2	Reserved	UINT8	0	Reserved
			1	
			2	
			3	
			4	
			5	
3	Self-Survey Progress	UINT 8		0-100%
4-7	Reserved	UINT 32	0	Reserved
8-9	Reserved	UINT16	0	Reserved
10-11	Minor Alarms	UINT16	bit field	Bit 0: not used Bit 1: Antenna open Bit 2: Antenna shorted Bit 3: Not tracking satellites Bit 4: not used Bit 5: Survey-in progress Bit 6: no stored position Bit 7: Leap second pending Bit 8: In test mode Bit 9: Position is questionable Bit 10: not used Bit 11: Almanac not complete Bit 12: PPS was generated
12	GPS Decoding Status	UINT8	0	Doing fixes
			1	Don't have GPS time
			3	PDOP is too high
			8	No usable sats
			9	Only 1 usable sat
			0x0A	Only 2 usable sats
			0x0B	Only 3 usable sats
			0x0C	The chosen sat is unusable
			0x10	TRAIM rejected the fix
13	Reserved	UINT8	0	Reserved
14	Spare Status 1	UINT8	0	
15	Spare Status 2	UINT8	0	
16-19	Local clock bias	Single		ns
20-23	Local clock bias rate	Single		ppb
24-27	Reserved	UINT32		Reserved
28-31	Reserved	Single		Reserved
32-35	Temperature	Single		degrees C
36-43	Latitude	Double		radians
44-51	Longitude	Double		radians
52-59	Altitude	Double		meters
60-63	PPS Quantization Error	Single		seconds
64-67	Spare			Future expansion

## Unused or miscellaneous packets

### Report Packet 0x13: Unparsable Packet

This packet is sent in response to a received packet that was unparsable. A packet is unparsable if the packet ID is not recognized or if the length or content of the packet is not correct for the packet ID.

### Report Packet 0x13: Data Format

Byte	Type	Item
0	UINT8	Packet ID of unparsable packet
1-N	UINT8	Packet data bytes of unparsable packet

## Legacy packets (unused)

The four packets below will be sent, for historical reasons, when the Automatic Output Packets are enabled with packet 0x8E-A5, but the same information contained in these packets is contained in packets 0x8E-AB and 0x8E-AC and these old packets should be ignored.

### Report Packet 0x54: Bias and Bias Rate

Information contained in super packets 8F-AB or 8F-AC

### Report Packet 0x46: Health of Receiver

Information contained in super packets 8F-AB or 8F-AC

### Report Packet 0x41: GPS Time

Information contained in super packets 8F-AB or 8F-AC

### Report Packet 0x4B: Machine Code ID and Additional Status

Information contained in super packets 8F-AB or 8F-AC

# NMEA 0183 Protocol

## In this appendix:

- Introduction
- NMEA 0183 communication interface
- NMEA 0183 message structure
- Field definitions
- NMEA 0183 message options
- NMEA 0183 message formats
- Exception behavior

This appendix provides a brief overview of the NMEA 0183 protocol, and describes both the standard and optional messages offered by the Resolution T.

## Introduction

NMEA 0183 is a simple, yet comprehensive ASCII protocol which defines both the communication interface and the data format. The NMEA 0183 protocol was originally established to allow marine navigation equipment to share information. Since it is a well established industry standard, NMEA 0183 has also gained popularity for use in applications other than marine electronics. The latest release of NMEA 0183 is Version 3.0 (July 1, 2000). Trimble Navigation supports both version 2.1 and version 3.0. The primary change in release 3.0 is the addition of the mode indicators in the GLL, RMC, and VTG messages.

For those applications requiring output only from the GPS receiver, NMEA 0183 is a popular choice since, in many cases, an NMEA 0183 software application code already exists. The Resolution T is available with firmware that supports a subset of the NMEA 0183 messages: GGA, GLL, GSA, GSV, RMC, VTC, and ZDA. For a nominal fee, Trimble can offer custom firmware with a different selection of messages to meet your application requirements.

For a complete copy of the NMEA 0183 standard, contact:

NMEA National Office  
Seven Riggs Avenue, Severna Park, MD 21146  
Phone: +1-410-975-9425 or 800-808-6632 (NMEA)  
Fax: +1-410-975-9450

## NMEA 0183 communication interface

NMEA 0183 allows a single source (talker) to transmit serial data over a single twisted wire pair to one or more receivers (listeners). The table below lists the standard characteristics of the NMEA 0183 data transmissions.

Signal	NMEA standard
Baud rate	4800
Data bits	8
Parity	None (Disabled)
Stop bits	1

## NMEA 0183 message structure

The NMEA 0183 protocol covers a broad array of navigation data. This broad array of information is separated into discrete messages which convey a specific set of information. The entire protocol encompasses over 50 messages, but only a sub-set of these messages apply to a GPS receiver like the Resolution T. The NMEA message structure is described below.

```
$IDMSG, D1, D2, D3, D4, . . . . ., Dn*CS [CR] [LF]
```

Where:

\$	Signifies the start of a message
ID	The talker identification is a two letter mnemonic which describes the source of the navigation information. The GP identification signifies a GPS source.
MSG	The message identification is a three letter mnemonic which describes the message content and the number and order of the data fields.
,	Commas serve as delimiters for the data fields.
Dn	Each message contains multiple data fields (Dn) which are delimited by commas.
*	The asterisk serves as a checksum delimiter.
CS	The checksum field contains two ASCII characters which indicate the hexadecimal value of the checksum.
[CR] [LF]	The carriage return [CR] and line feed [LF] combination terminate the message.

NMEA 0183 messages vary in length, but each message is limited to 79 characters or less. This length limitation excludes the "\$" and the [CR][LF]. The data field block, including delimiters, is limited to 74 characters or less.

## Field definitions

Many of the NMEA data fields are of variable length, and the user should always use the comma delineators to parse the NMEA message data field. The following table specifies the definitions of all field types in the NMEA messages supported by Trimble:

Type	Symbol	Definition
Status	A	Single character field: A=Yes, data valid, warning flag clear V=No, data invalid, warning flag set
<b>Special Format Fields</b>		
Latitude	llll.lll	Fixed/variable length field: Degreesminutes.decimal-2 fixed digits of degrees, 2 fixed digits of minutes and a variable number of digits for decimal-fraction of minutes. Leading zeros always included for degrees and minutes to maintain fixed length. The decimal point and associated decimal-fraction are optional if full resolution is not required.

Type	Symbol	Definition
Longitude	yyyyy.yyy	Fixed/Variable length field: Degreesminutes.decimal-3 fixed digits of degrees, 2 fixed digits of minutes and a variable number of digits for decimal-fraction of minutes. Leading zeros always included for degrees and minutes to maintain fixed length. The decimal point and associated decimal-fraction are optional if full resolution is not required.
Time	hhmmss.ss	Fixed/Variable length field: hoursminutesseconds.decimal-2 fixed digits of minutes, 2 fixed digits of seconds and a variable number of digits for decimal-fraction of seconds. Leading zeros always included for hours, minutes, and seconds to maintain fixed length. The decimal point and associated decimal-fraction are optional if full resolution is not required.
Defined		Some fields are specified to contain pre-defined constants, most often alpha characters. Such a field is indicated in this standard by the presence of one or more valid characters. Excluded from the list of allowable characters are the following that are used to indicated field types within this standard: "A", "a", "c", "hh", "hhmmss.ss", "llll.ll", "x", "yyyy.yy"
<b>Numeric Value Fields</b>		
Variable	x.x	Variable length integer or floating numeric field. Optional leading and trailing zeros. The decimal point and associated decimal-fraction are optional if full resolution is not required (example: 73.10=73.1=073.1=73).
Fixed HEX	hh	Fixed length HEX numbers only, MSB on the left
<b>Information Fields</b>		
Fixed Alpha	aa	Fixed length field of upper-case or lower-case alpha characters.
Fixed Number	xx	Fixed length field of numeric characters

**Note –**

- Spaces are only be used in variable text fields.
- Units of measure fields are appropriate characters from the Symbol column unless a specified unit of measure is indicated.
- Fixed length field definitions show the actual number of characters. For example, a field defined to have a fixed length of 5 HEX characters is represented as hhhhh between delimiters in a sentence definition.

## NMEA 0183 message options

The Resolution T can output any or all of the messages listed in the table below. In its default configuration (as shipped from the factory), the Resolution T outputs only TSIP messages. Typically NMEA messages are output at a 1 second interval with the "GP" talker ID and checksums. These messages are output at all times during operation, with or without a fix. If a different set of messages has been selected (using Packet 0x7A), and this setting has been stored in flash memory (using Packet 0x8E-26), the default messages are permanently replaced until the receiver is returned to the factory default settings.



**Note** – The user can configure a custom mix of the messages listed in the table below. See Chapter 3, and TSIP command packets 0xBC, 0x7A, and 8E-26 in Appendix A for details on configuring NMEA output.



**WARNING** – If too many messages are specified for output, you may need to increase the unit's baud rate.

Message	Description
GGA	GPS fix data
GLL	Geographic position Latitude/Longitude
GSA	GPS DOP and active satellites
GSV	GPS satellites in view
RMC	Recommended minimum specific GPS/Transit data
VTG	Track made good and ground speed
ZDA	Time and date

## NMEA 0183 message formats

### GGA-GPS Fix Data

The GGA message includes time, position and fix related data for the GPS receiver.

```
$GPGGA, hhmmss.ss, llll.lll, a, nnnnn.nnn, b, t, uu,
v.v, w.w, M, x.x, M, y.y, zzzz*hh <CR><LF>
```

Field number	Description
1	UTC of Position
2, 3	Latitude, N (North) or S (South)
4, 5	Longitude, E (East) or W (West)
6	GPS Quality Indicator: 0 = No GPS, 1 = GPS, 2 = DGPS
7	Number of Satellites in Use
8	Horizontal Dilution of Precision (HDOP)
9, 10	Antenna Altitude in Meters, M = Meters
11, 12	Geoidal Separation in Meters, M=Meters. Geoidal separation is the difference between the WGS-84 earth ellipsoid and mean-sea-level.
13	Age of Differential GPS Data. Time in seconds since the last Type 1 or 9 Update
14	Differential Reference Station ID (0000 to 1023)
hh	Checksum

## GLL - Geographic Position - Latitude/Longitude

The GLL message contains the latitude and longitude of the present vessel position, the time of the position fix and the status.

```
$GPGLL,1111.111,a,yyyyy.yyy,a,hhmmss.ss,A,i*hh <CR> <LF>
```

Field number	Description
1	Latitude, N (North) or S (South)
2, 3	Longitude, E (East) or W (West)
5	UTC of position
6	Status: A = Valid V = Invalid
7	Mode Indicator: Mode A=Autonomous Mode D=Differential Mode E=Estimated (dead reckoning) Mode M=Manual Input Mode S=Simulated Mode N=Data Not Valid
hh	Checksum

## GSA - GPS DOP and Active Satellites

The GSA messages indicates the GPS receiver's operating mode and lists the satellites used for navigation and the DOP values of the position solution.

```
$GPGSA,a,x,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,xx,x.x,x.x,x.x*hh<CR><LF>
```

Field number	Description
1	Mode: M = Manual, A = Automatic. In manual mode, the receiver is forced to operate in either 2D or 3D mode. In automatic mode, the receiver is allowed to switch between 2D and 3D modes subject to the PDOP and satellite masks.
2	Current Mode: 1 = fix not available, 2 = 2D, 3 = 3D
3 - 14	PRN numbers of the satellites used in the position solution. When less than 12 satellites are used, the unused fields are null
15	Position dilution of precision (PDOP)
16	Horizontal dilution of precision (HDOP)
17	Vertical dilution of precision (VDOP)
hh	Checksum

## GSV - GPS Satellites in View

The GSV message identifies the GPS satellites in view, including their PRN number, elevation, azimuth and SNR value. Each message contains data for four satellites. Second and third messages are sent when more than 4 satellites are in view. Fields #1 and #2 indicate the total number of messages being sent and the number of each message respectively.

```
$GPGSV, x, x, xx, xx, xx, xxx, xx, xx, xx, xxx, xx, xx, xx,
xxx, xx, xx, xx, xxx, xx*hh<CR><LF>
```

Field number	Description
1	Total number of GSV messages
2	Message number: 1 to 3
3	Total number of satellites in view
4	Satellite PRN number
5	Satellite elevation in degrees (90° Maximum)
6	Satellite azimuth in degrees true (000 to 359)
7	Satellite SNR (C/No), null when not tracking
8, 9, 10, 11	PRN, elevation, azimuth and SNR for second satellite
12, 13, 14, 15	PRN, elevation, azimuth and SNR for third satellite
16, 17, 18, 19	PRN, elevation, azimuth and SNR for fourth satellite
hh	Checksum

## RMC - Recommended Minimum Specific GPS/Transit Data

The RMC message contains the time, date, position, course, and speed data provided by the GPS navigation receiver. A checksum is mandatory for this message and the transmission interval may not exceed 2 seconds. All data fields must be provided unless the data is temporarily unavailable. Null fields may be used when data is temporarily unavailable.

```
$GPRMC, hhmmss.ss, A, llll.ll, a, yyyyy.yy, a, x.x, x.
x, xxxxxx, x.x, a, i*hh<CR><LF>
```

Field number	Description
1	UTC of Position Fix.
2	Status: A = Valid, V = navigation receiver warning
3, 4	Latitude, N (North) or S (South).
5, 6	Longitude, E (East) or W (West).
7	Speed over the ground (SOG) in knots Track made good in degrees true. Date: dd/mm/yy Magnetic variation in degrees, E = East / W= West

Field number	Description
	Position System Mode Indicator: A=Autonomous D=Differential E=Estimated (Dead Reckoning) M=Manual Input S=Simulation Mode N=Data Not Valid
hh	Checksum (Mandatory for RMC)

### VTG - Track Made Good and Ground Speed

The VTG message conveys the actual track made good (COG) and the speed relative to the ground (SOG).

\$GPVTG, x.x, T, x.x, M, x.x, N, x.x, K, i\*hh<CR><LF>

Field number	Description
1	Track made good in degrees true.
2	Track made good in degrees magnetic.
3, 4	Speed over the ground (SOG) in knots.
5, 6	Speed over the ground (SOG) in kilometer per hour.
7	Mode Indicator: A=Autonomous Mode D=Differential Mode E=Estimated (dead reckoning) Mode M=Manual Input Mode S=Simulated Mode N=Data Not Valid
hh	Checksum

### ZDA - Time & Date

The ZDA message contains UTC time, the day, the month, the year and the local time zone.

\$GPZDA, hhmmss.ss, xx, xx, xxxx, , \*hh<CR><LF>

Field number	Description
1	UTC
2	Day (01 to 31)
3	Month (01 to 12)
4	Year
5	Unused
6	Unused
hh	Checksum

---

*Note* – Fields #5 and #6 are null fields in the Resolution T output. A GPS receiver cannot independently identify the local time zone offsets.



---

**CAUTION** – If UTC offset is not available, time output will be in GPS time until the UTC offset value is collected from the GPS satellites. When the offset becomes available, the time will jump to UTC time.

---

*Note* – GPS time can be used as a timetag for the 1PPS. The ZDA message comes out 100-500 msec after the PPS.

## Exception behavior

When no position fix is available, some of the data fields in the NMEA messages will be blank. A blank field has no characters between the commas.

### Interruption of GPS signal

If the GPS signal is interrupted temporarily, the NMEA will continue to be output according to the user-specified message list and output rate. Position and velocity fields will be blank until the next fix, but most other fields will be filled.

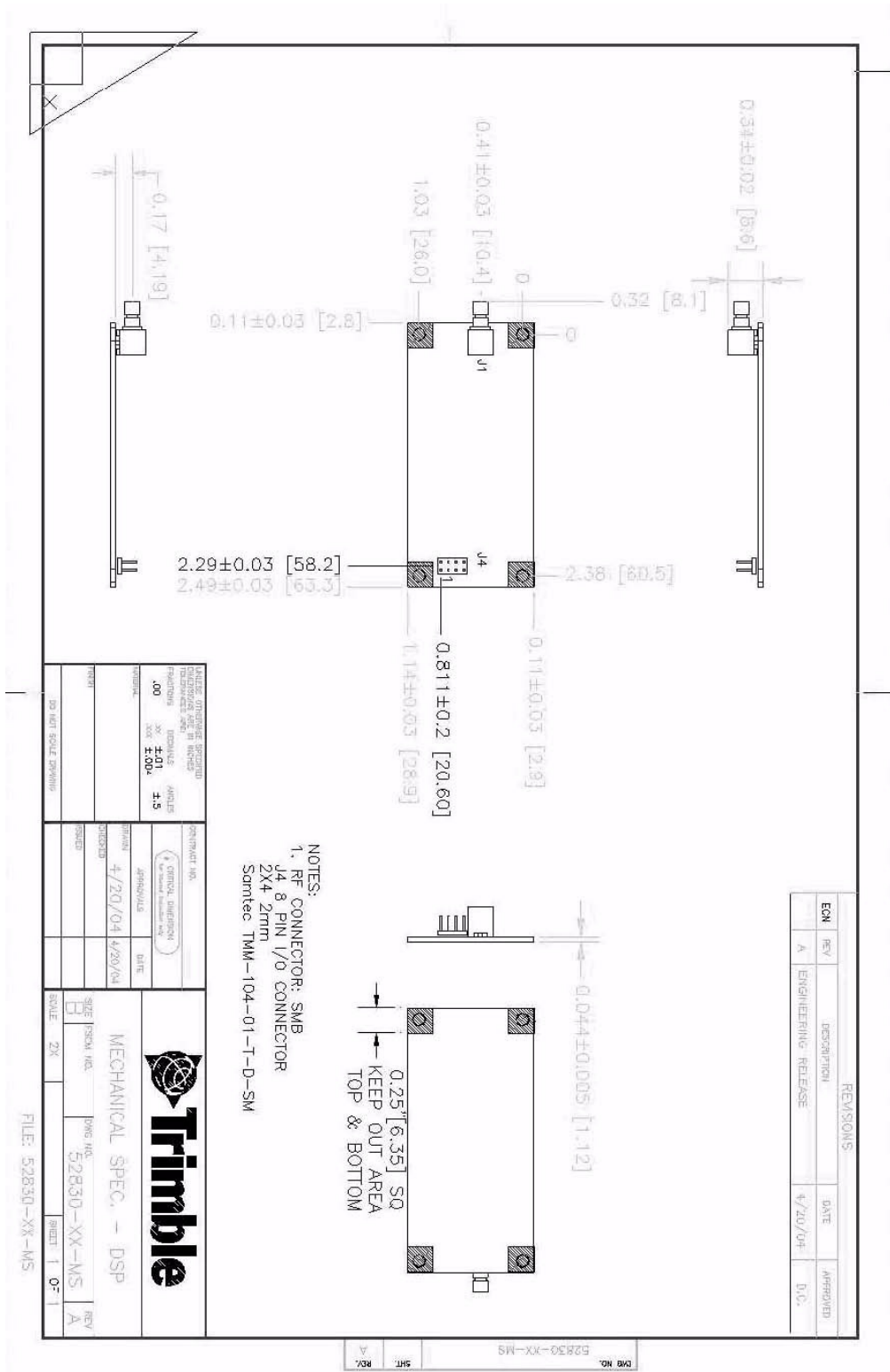
# Specifications

## In this chapter:

- [Mechanical specification](#)

The Resolution T is designed for a variety of embedded timing applications. This appendix includes the system specifications and mechanical drawings for the Resolution T and the available GPS antenna.

# Mechanical specification



REVISIONS			DATE	APPROVED
ECN	REV	DESCRIPTION		
	A	ENGINEERING RELEASE	4/20/04	D.O.

- NOTES:
- RF CONNECTOR: SMB
  - J4 8 PIN I/O CONNECTOR
  - J8 2mm
  - Samtec TMM-104-01-T-D-SM

THESE DIMENSIONS EXCEPT DIMENSIONS OF 16 MILS DIMENSIONS PER FINISH		DIMENSIONAL NO. 4/20/04	
TOLERANCE .00 .01 .004 .004	ANGLE 45	APPROVALS DATE	DATE
MECHANICAL SPEC. - DSP		SIZE B	REV A
TRIMBLE		P/N 52830-XX-MS	SHEET 1 OF 1

FILE: 52830-XX-MS









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