User Manual for GNLab

Joshua W.K. Ho 1,3 and Michael A. Charleston 2,3*

¹School of Biological Sciences, and ²School of Information Technologies, University of Sydney, Sydney, Australia, ³Sydney University Biological Informatics and Technologies Centre, Sydney, Australia

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[∗]Correspondent author: M.A. Charleston(mcharleston@it.usyd.edu.au)

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1 Introduction

GNLab (stand for Gene Network virtual Laboratory) implements a computational pipeline for large-scale analysis of gene networks. The pipeline allows iterative experiments on GRNs to be designed and carried out in a simple and flexible manner. This framework consists of distinct functional components for network generation, simulation, analysis, visualization, inference and comparison. By piping different components together in different ways, many types of systems biology analyses can be carried out effectively. Although the development of such a computational pipeline was inspired to assess limitations of GRN inference methods, this pipeline is designed for the general analysis of GRN structures and dynamics.

Analogous to running various experiments in a laboratory using a range of equipments, GNLab provides a collection of computational tools that can be used for constructing various repeatable experiments. The design principle of GNLab is that each functional component is invoked and controlled separately in a coherent manner. Instead of generating, analyzing and simulating a gene network in a single run, GNLab is invoked several times and piped together by a simple user-defined script (e.g. using any scripting language such as Perl or Python). Simple tab-delimited text files are used for communication between each component. **GNLab** is implemented in ASCII C++, and has a command-line interface. Individual components of GNLab are invoked by command-line options. For example, the command GNLab -a net1 reads in a text file net1.gnl.txt and outputs a detailed summary of topological features in a file called net1.ana.txt. The command line option -a specifies the action, and any parameters following this option are the arguments of the call. A list of GNLab command options can be found in Table 1.

The first few sections of this manual explains the theoretical background of most of tools, and the detailed usage of each option is explained in section 9.

2 Network Generation

A number of procedures have been suggested to generate networks that are topologically similar to real GRNs. Current algorithms for generating GRNs are mostly mathematically motivated. Since most biological networks exhibit both small-world (Watts and Strogatz, 1998) and scale-free (Barabási and Albert, 1999; Albert and Barabasi, 2000) topology, a preferential attachment growth model has been used to generate artificial GRNs (Mendes $et al., 2003$. An alternative approach is to generate a GRN by sampling a subset of genes and interactions from experimentally validated gene networks (Van den Bulcke et al., 2006). Despite being able to generate GRNs of the desired topology, the success of this method depends on the validity of the source network. None of these can effectively produce network structures that are topologically consistent with real GRNs.

2.1 Modeling evolution of GRNs

To overcome the shortcomings of the existing approaches, a biologically motivated GRN evolution model, comprising horizontal gene transfer, gene duplication and gene mutation, is proposed. The model is referred to as the Charleston-Ho (CH) model (Ho and Charleston, in prep.). The CH model is probabilistic in nature. Starting with a small 'seed network', a network is grown by iteratively performing one of the evolutionary operators according to their respective probability. The growth process based on this CH model is governed by a set of ten parameters Table 2.

2.2 Generating Networks with GNLab

The two other commonly used network growth models are the Erdös-Rényi (ER) model (Erdös and Rényi, 1959), and the Scale-free (SF) model (Barabási and Albert, 1999). Networks generated by these two models have been used as benchmark datasets for evaluating performance of GRN inference methods (Mendes et al., 2003). Along with the CH model, these two growth models are also implemented in GNLab. To construct a ER network with n nodes, the model specifies that each of the e edges is randomly inserted between a pair of nodes. The generation of a SF network relies on two parameters – the number of nodes (n) and the probability of random edge addition (p_{Add}) . In the Scale-free model, either a node insertion or an edge addition event is performed in any one iteration. In

Table 1: Summary of command line options of GNLab.

Parameter	Description
$\,n$	number of genes
p_{trans}	probability of horizontal gene transfer
p_{dup}	probability of gene duplication
p_{iq}	probability of interaction gain
p_{il}	probability of interaction loss
p_{gl}	probability of gene loss
mts	maximum size of subgraph transferable
p_{dr}	probability of duplication of regulator
mc	maximum arc weight change
p_r	probability of retaining a duplicate interaction

Table 2: Description of parameters for the Charleston-Ho model.

a node insertion event, the new node is inserted and linked preferentially to a highly connected node. In an edge addition event, an edge is randomly added between a pair of nodes which are preferentially highly connected.

In GNLab, command-line options $-r$, $-f$ and $-g$ are used to invoke the generation of random networks using the ER, SF and CH model respectively. The randomly generated network is written into a simple text file with extension .gnl.txt. This text file contains information about nodes, edges and edge weights.

3 Simulation of Gene Expression Dynamics

The realistic simulation of the dynamic behaviour of an GRN is essential for simulation of microarray datasets. Since microarray technology measures gene expression by the amount of mRNA present, most modeling effect centred around the cellular mRNA level. The level of mRNA molecules of a gene depends on two processes, namely its synthesis from gene transcription and its natural breakdown. The level of mRNA synthesis is influenced by the mRNA level of other genes as described by the Hill's kinetics (Hill, 1910; Hofmeyr and Cornish-Bowden, 1997). Hill's kinetics is a non-linear model of gene-to-gene relationships. It assumes the effect of all regulator genes to the target gene to be multiplicative. Using the same model proposed by Mendes et al. (2003), the dynamics of the GRN is modeled by a set of ordinary differential equations (ODEs). Assume that $X(G_i)$ represents the level of mRNA of gene G_i , and it is activated by genes $G_{a_1}, G_{a_2}, ..., G_{a_m}$ and repressed by genes $G_{r_1}, G_{r_2}, ..., G_{r_n}$. Constants K_{a_i} and K_{r_j} represent the expression levels of G_{a_i} and G_{r_j} respectively at which the effect on the target gene is half of its saturating value. The Hill's constant n controls the sigmoidicity of the interaction curve. V_i represents the basal transcriptional rate of gene G_i . The rate law for mRNA synthesis can therefore be formulated as:

$$
syn(G_i) = V_i \cdot \prod_{i=1}^{m} \left(1 + \frac{X(G_{a_i})^n}{X(G_{a_i})^n + K_{a_i}^n} \right) \cdot \prod_{j=1}^{n} \frac{K_{r_j}^n}{X(G_{r_j})^n + K_{r_j}^n}
$$
(1)

The rate mRNA degradation is assumed to only depend linearly on the current expression level. Therefore, the rate law of mRNA breakdown can be formulated as:

$$
break(G_i) = b_i \cdot X(G_i)
$$
\n⁽²⁾

Overall, the change of gene expression level for a gene G_i can be modeled by the following ordinary differential equation:

$$
\frac{dG_i}{dt} = syn(G_i) - break(G_i) \tag{3}
$$

This is a deterministic approach to simulate a GRN. This ODE approach, however, ignores the inherent stochasticity in the a real gene network. Moreover, solving a large set of ODEs analytically is computationally intensive, which often requires the use of approximation methods. In this study, Euler's method is used to simulate the GRN due to its simplicity. With the use of a small time-step (e.g. 0.1), Euler's method is sufficient to simulate the gene system.

To incorporate stochasticity into the simulation, the deterministic model is extended into a stochastic model using an approach recently described by Tian and Burrage (2006). The key is to replace each state variable x in equation 3 by a Poisson random variate with mean x. The expression of a gene G_i (measured in mRNA molecular number) is simulated as:

$$
X(G_i, t + \tau) = X(Gi) + P(syn(G_i)) - P(break(G_i))
$$
\n
$$
(4)
$$

The variable $X(G_i, t)$ denotes the molecular number of mRNA of G_i , and τ denotes the time elapsed. $P(x)$ generates a Poisson random variate with mean x. Using this technique, the level of mRNA of a gene is affected by Poisson noise, which is consistent with the chance event in transcription and translation (Thattai and van Oudenaarden, 2001).

3.1 Microarray Dataset Synthesis

There are three main types of microarray datasets available, namely time-series, gene perturbation, and condition-specific datasets. A summary of how each type of dataset is generated is shown as follows:

3.1.1 Time-series Microarray Dataset

- 1. Initialize the gene system, and simulate $1000 \times \tau$ rounds to bring the system to a steady state
- 2. Knockout one gene (i.e. set concentration $= 0$, and $V = 0$)
- 3. Simulate the system, and repeatedly take the expression level at certain intervals

3.1.2 Gene Perturbation Microarray Dataset

- 1. Initialize the gene system, and simulate $1,000 \times \tau$ rounds
- 2. Knockout one gene (i.e. set concentration=0, and $V=0$)
- 3. Repeatedly, simulate the system for $1,000 \times \tau$ rounds
- 4. Obtain gene expression level after each iteration

3.1.3 Condition-specific Microarray Dataset

- 1. Initialize the gene system, and simulate $1,000 \times \tau$ rounds
- 2. randomly select a set of n genes, each gene is randomly assigned to undertake one of the following actions:
	- conc=0, $V=0$ (i.e. down regulate)
	- conc=conc^{*2} and $V=V*4$ (i.e. up regulate)
- 3. Repeatedly, simulate the system $1,000 \times \tau$ rounds
- 4. Obtain the gene expression level after each iteration

3.2 Experimental Noise Model

Microarray is an inherently noisy technology. Being able to incorporate a realistic amount of noise into the simulated microarray data is essential for a range of microarray analysis experiments. By studying the structure of microarray noise at the DNA hybridization and the preparation level, the noise in an oligonucleotide microarray has been shown to be signal intensity dependent (Tu et al., 2002). In general, the stronger the signal, the less the signal is affected by noise. In this work, a normal distribution of noise with standard deviation of $\beta e^{-|\theta|}$ is applied to each signal with log intensity θ . The term β is the noise coefficient, which can be varied. The higher the β , the more 'noisy' the data becomes.

3.3 Invoking Microarray Simulation in GNLab

In GNLab, network simulation can be carried out using option -t, which generates a time-series of gene expression. Simulation results are written into a .data file. Timeseries, gene perturbation, and condition-specific microarray datasets can be simulated from a network using the option -s. The number of technical and biological replicates can be specified as arguments. The resulting data resemble the microarray data generated by a one-channel oligonucleotide array. The microarray data can optionally be log-transformed and mean normalized per array. The microarray data is stored in a .ma.txt file.

4 Network Analysis

4.1 Topological Features

A set of 11 commonly used topological features are calculated to characterize a GRN in GNLab (see Table 3). These features are used to describe the global and local network properties. For global network statistics, one can extract the number of gene (n), number of interactions per genes (inter), proportion of genes with self-loops (loop), proportion of regulator genes (reg), number of disjoint network components (comp), proportion of the maximum component size (mcs), longest path length (lpl; longest directed path between a regulator and any other gene), proportion of activation amongst all interactions (act) and hub dominance (hubDom; defined as the proportion of arcs connected to the top 5% of most connected genes compared to the total number of arcs). For local properties, they can be characterized by the average clustering coefficient (cc) and the number of feed-forward loops per gene (ffl).

In particular, hub dominance is a new topological feature used in GNLab. Normally, the importance of hub genes is characterized by the slope of a power-law curve. However, fitting a power-law curve to the out-degree of a GRN may not be appropriate, thus a new method of measuring hub usage is needed. The idea of measuring the proportion of arcs connected to the top 5% of hub genes compared to the total number of arcs was used by Basso et al. (2005). This work formally adopts this measurement as a topological feature for network analysis.

Topological features can be calculated using option -a, which calculates a range of topological features such as degree distribution, clustering coefficient distribution, length of longest path. The results are stored into a file with an .ana.txt extension. The command-line option -n can be used to print a one-line summary of the 11 topological features onto the console display. The analysis results from the file can easily be parsed into statistical analysis packages such as R (Ihaka and Gentleman, 1996).

5 Robustness Score

The dynamic behaviour of a GRN can also be measured by a novel robustness score devised in this studied. The network robustness can be estimated by the ability of a network to tolerate random gene perturbation using an in silico simulation procedure. To calculate the robustness score, a set of k genes is initially labeled as essential genes. One thousand rounds of simulations are initially performed to bring the system to its steady state. Then, k mutant genomes are created by systematically knocking out one gene per mutant genome (i.e. set $X(G_i) = 0$) and $V(G_i) = 0$). Each mutant genome is further simulated for 1,000 iterations. If the expression of any essential gene in a mutant genome is dropped by more than 50%, the mutant is non-viable. The robustness score is the proportion of viable mutant genomes over all possible single gene mutants. In GNLab,

Table 3: Descriptions of the 11 topological features used in GNLab.

robustness scores can be calculated by -b. The robustness scores are then summarized in a file with an .rob.txt extension.

6 Network Visualization

Network visualization is not explicitly performed in GNLab. GNLab generates data files for other visual analysis programs. Using **GNLab** command option $-v$, a network can be converted into a .dot, .xwg, .sif and .net file, which can then be parsed into GraphViz (Gansner and North, 1999), GEOMI (Ahmed et al., 2005), Cytoscape (Shannon et al., 2003) and pajek Batagelj and Mrvar (1998) respectively.

7 Network Inference

Although GNLab does not contain network inference functionality, it provides utility (command option -d) to convert a .ma.txt file into an input file of other inference programs, currently only available for ARACNe (Margolin et al., 2006) and Banjo (http://www.cs.duke.edu/∼amink/software/banjo).

8 Network Comparison

A network comparison method is implemented in GNLab to measure GRN inference reliability. The objective of this network comparison step is to quantify how different two networks are (e.g. the original and the inferred network). The two networks are assumed to contain the same set of nodes (Sharan and Ideker, 2006). A set of machine learning performance metrics can be used to quantify how well a GRN is inferred from the data. Four quantities are essentials in these metrics: true positive count (TP; number of edges that are correctly inferred), true negative edges count (TN; number of non-interacting relationships inferred), false positive count (FP; number of inferred edges that are not present in the original network), and false negative count (FN; number of true edges that are not inferred). A combination of some machine learning metrics (sensitivity, specificity and precision) and the topological distance (the one similar to Trusina et al., 2005) is used to measure network similarity in GNLab. A brief description of the four similarity measures can be found at Table 4. Sensitivity, specificity and precision are the commonly used criteria for assessing network inference reliability. The topological distance is essentially a ratio of number of non-matching edges (false positive and false negative) over all possible edge positions. For example, let's assume we are comparing the original graph A with an inferred graph B , both having n nodes. If there are two false positive arcs (two arcs appeared in B , but not in A) and one false negative arc (one arc appeared in A , but not in B), the number of non-matching arcs is three. The total number of all possible arc is n^2 . Therefore, the topological distance is $\frac{3}{n^2}$. The total number of

arcs for an undirect graph is different from an directed graph. However, it is expected that two randomly generated networks would have a non-zero topological distance. Therefore the theoretical topological distance for any two random networks are calculated and used as a base-line for meaningful comparisons of network differences (detailed calculation omitted for simplicity). If a topological distance is larger than this expected distance, it implies that the existence of systematic bias in the inference algorithm. Two networks (in .gnl.txt format) can be compared through the command option -c in GNLab. A one-line summary of network difference are printed onto the standard output.

Table 4: Summary of reliability metrics of network inference methods. TP=true positive, TN=true negative, FP=false positive, FN=false negative, n=number of nodes.

9 GNLab Options Summary

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