562200-000, Issue1.1, April 2013

PME 200

Rated Capacity Indicator, Machine Envelope Indicator
Rated Capacity Controller, Machine Envelope Controller

Operators Manual

Your safety, your profit, our commitment

This guide describes operation of the

PROLEC PME LIFTING AND MACHINE ENVELOPE SAFETY SYSTEM FOR CONSTRUCTION PLANT

Model covered :	PART No.	MODEL Ref
	0050X0-X00	PME200 - RCI + MEI SYSTEM
	0050X0-X00	PME200 - RCC + MEC SYSTEM

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DURING NORMAL OPERATION THE SAFE WORKING LOAD OF A CRANE SHOULD NOT BE EXCEEDED. THEREFORE THE WARNING OF OVERLOAD SHOULD NOT BE USED AS A NORMAL OPERATING FACILITY. IT SHOULD BE NOTED THAT CERTAIN STATUTORY REQUIREMENTS DO NOT PERMIT THE SAFE WORKING LOAD TO BE EXCEEDED EXCEPT FOR THE PURPOSE OF TESTING.

THIS RATED CAPACITY INDICATOR / CONTROLLER (RCI, RCC) IS NOT SUITABLE FOR USE IN EXPLOSIVE ATMOSPHERES. ADJUSTMENT BY UNAUTHORISED PERSONS WILL INVALIDATE ANY WARRANTY OR CERTIFICATION SUPPLIED. IF A PROBLEM ARISES WHICH CANNOT BE RECTIFIED USING THIS GUIDE, AUTHORISED SERVICE SHOULD BE SOUGHT.

THIS DEVICE IS CERTIFIED TO MEET CURRENT UK & EC SAFETY REGULATIONS FOR LIFTING OPERATIONS.

Any alterations or modifications to machine components which affect this system and any system component failure must be reported to Prolec Ltd or via the machine convertor/service agreement holder. This manual must be kept with the product and be passed on to any subsequent user of the product.
Whilst every effort has been made to ensure the accuracy of the information supplied in this manual, Prolec Ltd cannot be held responsible for any errors or omissions.

Manufacturers original instructions.

Table of contents

Table of contents (continued)

Table of contents (continued)

Continued

Table of contents (continued)

Continued

Table of contents (continued)

Table of contents - continued

Table of contents - continued

1 Use of this Document

This user guide is intended for persons familiar with the use of construction plant undertaking lifting operations.

WARNING denotes information about particular risks which may be generated by certain applications, by using certain fittings, and about additional protective measures which are necessary for such applications.

Caution, care, risk situation

HAZARD Actions that can lead to serious injury or death

2 Notices

Adjustment by unauthorised persons will invalidate any warranty or certification supplied. If an error condition is displayed which cannot be rectified using this guide, halt any operation, seek authorised service immediately and do not continue operation until the fault has been remedied.

3 System Identification

The PME system provides two primary safety functions

1. Lifting Stability
2. Machine Envelope Monitoring

Both safety functions are achieved through real time monitoring some or all of the machine's moving parts (booms, other articulations, turret etc) and its environment (ground pitch and inclination, load etc) and actively determining the safety of the current operation where appropriate limits have been set.

The Lifting Stability function falls into two sub classes

- Rated capacity indictors (RCI) warn of potential instability when the machine is involved in lifting operations. Any motion which reduces the safe working load will not be inhibited at any time.

- Rated capacity controllers (RCC) prevent instability when the machine is involved in lifting operations. This is achieved by hydraulically stopping unsafe movements of the machine which could cause the machine to tip.

The Machine Envelope Monitoring function also is divided into two sub classes

- Machine envelope indictors (MEI) warn of movements that would bring parts of the machine into hazardous areas, most notably height restrictions when working under overhead wires. Any motion which exceeds the set limit will not be inhibited at any time.

- Machine envelope controllers (MEC) prevent movements that would bring parts of the machine into hazardous areas, most notably height restrictions when working under overhead wires.

During operation the indicators on the left are displayed on the screen to clearly identify the function supported by your PME 200. Functions may not be available i.e. when in non-lifting mode or when envelope monitoring is switched off, if this is the case a cross will be painted over the relevant function icon.

Combinations of these functions may be present, it is essential that the functions of the system installed are identified and understood.

4 Operating and Hazard Situation Recommendations

Operating Recommendations

When operating the machine as a crane:

- Ensure Lift Mode is selected during lifting operations
- Operate the machine at a sensible speed
- Take extra care when travelling with a load attached
- Do not operate the machine in a reckless Manner

When using envelope monitoring:

- When setting a height limit, make sure any attached tool is in its least favourable position
- Check for correct operation once the limit or limits have been set
- Operate the machine at a sensible speed
- Reduce operating speed
- Do not raise the equipment quickly when close to a limit
- Do not operate the machine in a reckless manor
- Do not travel over rough terrain when at or near a limit

Hazard Situation Recommendations

In an Overload / Hydraulic hazard state:

- Release the control levers if a limit has been reached if appropriate
- Do operate the machine at a slow speed
- The lifting point must me moved in a direction that in creases the safe working load

In a limit hazard state:

- Release the control levers if a limit has been reached if appropriate
- Operate the machine at a slow speed

5 Operating Instructions

5.1 Power Up

The PME system automatically powers up when the machines ignition is switched on. The in-cab unit incorporates a 4.3” high resolution LCD display and is controlled with three buttons at each side. Three status LEDs and an internal alarm provide further information.

The system will perform a self check at start up:

1. All LEDs will flash, the internal display alarm and the external alarm will sound.
2. The RED LED will light indicating the system is starting and performing a self test.
3. Once the self test is complete, the GREEN LED will light and the system will become active. A safety warming message is displayed, please read and proceed only if you are fully familiar with your PME system. Lifting Mode is activated by pressing any key and any previous limits set will be enabled. The system is now ready for use.
4. The system can be configured to require a user login - if this is enabled, see section 5.5.

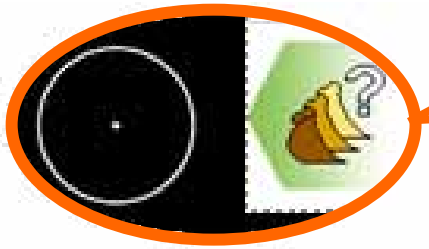
If the RED LED remains lit, a fault has been detected, halt any operation, seek authorised service immediately and do not continue operation until the fault has been remedied.

The display is secured to the machine using a flexible ball mounting allowing easy adjustment for personal viewing preference.

5.2 Using the Display

The display is operated by using the buttons adjacent to a function icon. The buttons can open a sub menu, turn a function ON or OFF, set a value, toggle through multiple screens, no one button has a single function. The button icon will turn black/purple when the button has been activated. Note that the image of the machine is fixed and does not follow the movement of the machine.

Multifunction buttons: The action of the button is indicated by the adjacent icon.



A secondary symbol can appear in the top left corner of an icon, these mean :

The plus symbol indicates a sub menu will be opened if selected.

The cycle symbol indicates that multiple features are available.

The on / off symbols indicate if a feature is ON or OFF. Red is ON and grey is OFF.

Help is available for each button. To access the help, push and hold the button for three seconds. The help message can be cleared by pressing any of the six buttons. PME is still active when displaying help messages, if the Lifting Mode is active and or a height limit is set, any alarm or warning condition will be indicated.

5.3 Editing Values using the Arrow Buttons

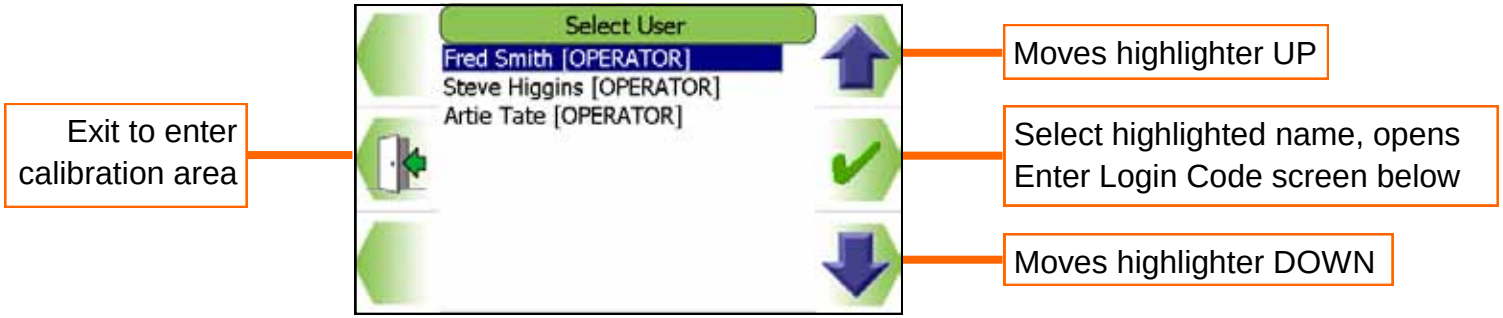
Editing values such as login codes or a height limit is easily achieved using the number editor screen. The digit highlighted in blue is increased or decreased between 0 and 9 by pressing the UP and DOWN buttons - use the LEFT and RIGHT buttons to move the high-lighter to the left and to the right. Press the tick button to apply the value displayed.

5.4 Selecting from a list using the Arrow Buttons

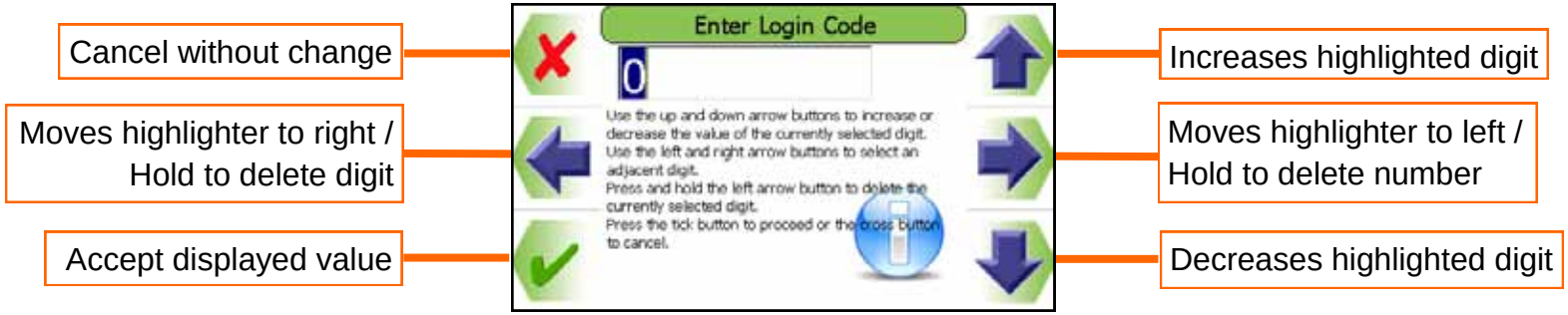
To make a selection from a list such as Users, Duties (shown here) or Lifting Points, use the UP and DOWN buttons to move the high-lighter up and down. Press the TICK button to select the highlighted entry. Press the CROSS button to exit without making a change.

5.5 User Login

If PME has been configured to work with the built-in user list, the system will prompt for a user login pass code. Select the user name required and the login code screen will appear.



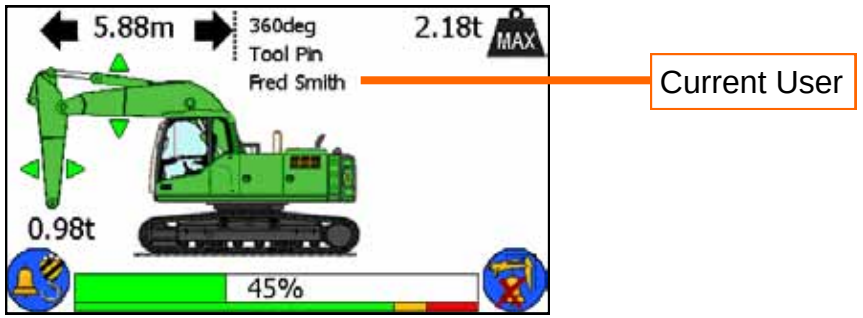
Using the arrow buttons to enter a valid pass code. The previous number will be replaced with a star as the code is entered. Press the TICK button to confirm the login pass code. If a valid pass code is entered the system will commence normal operation.



If an incorrect login code is entered, a failure screen will be displayed. Press the TICK button to return to the Select User screen.

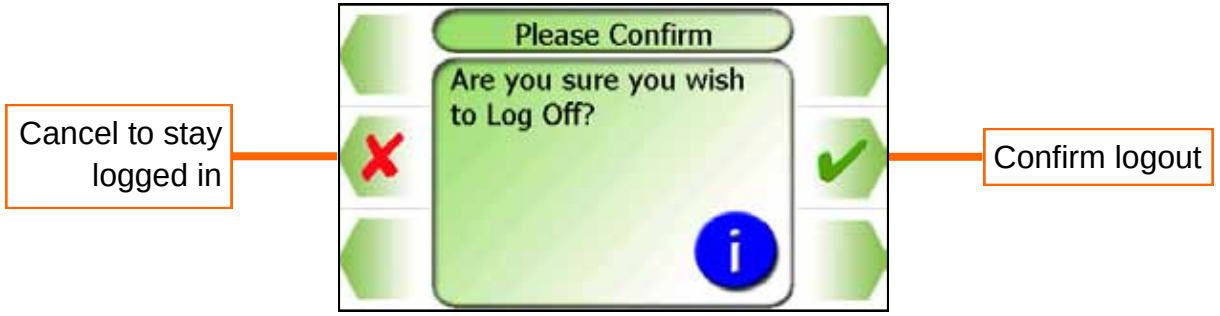
5.6 Current User

Once logged in, the current user details can be found below the duty and lifting point information.



5.7 User Logout

If a user is logged in as the current user, they can select the logout screen by holding an exit key down for three seconds.



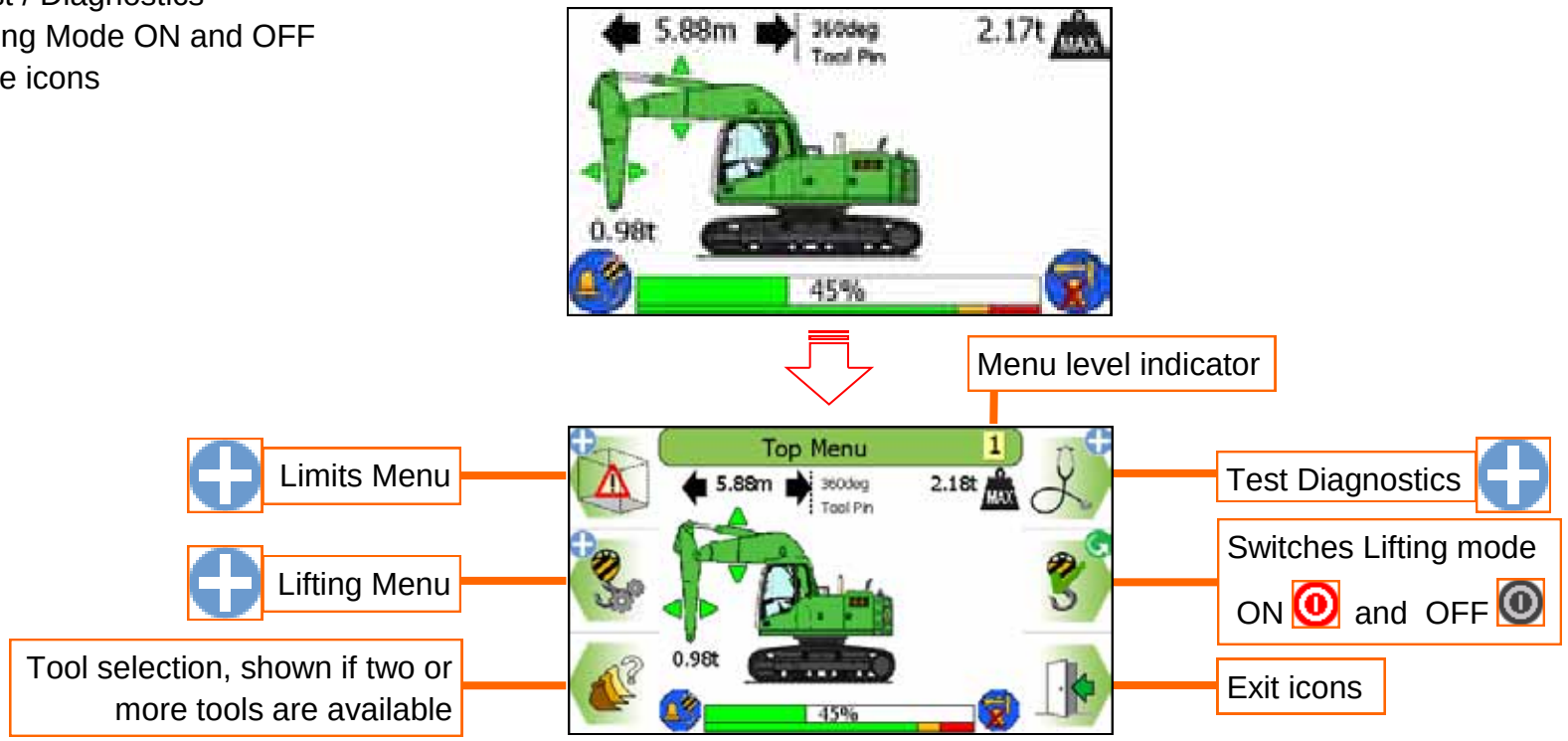
Once logout has been confirmed the login screen will be automatically displayed.
Press the CROSS button to stay logged in, the screen will return to that previously shown.

6 Top Menu

The Top Menu screen allows access to all the system functions. To reveal the icons, if hidden, press any button. To return to the Top Menu from a sub menu press the EXIT button until the Top Menu is displayed. To hide the icons when at the Top Menu, press the EXIT button once more.

Top Menu button functions:

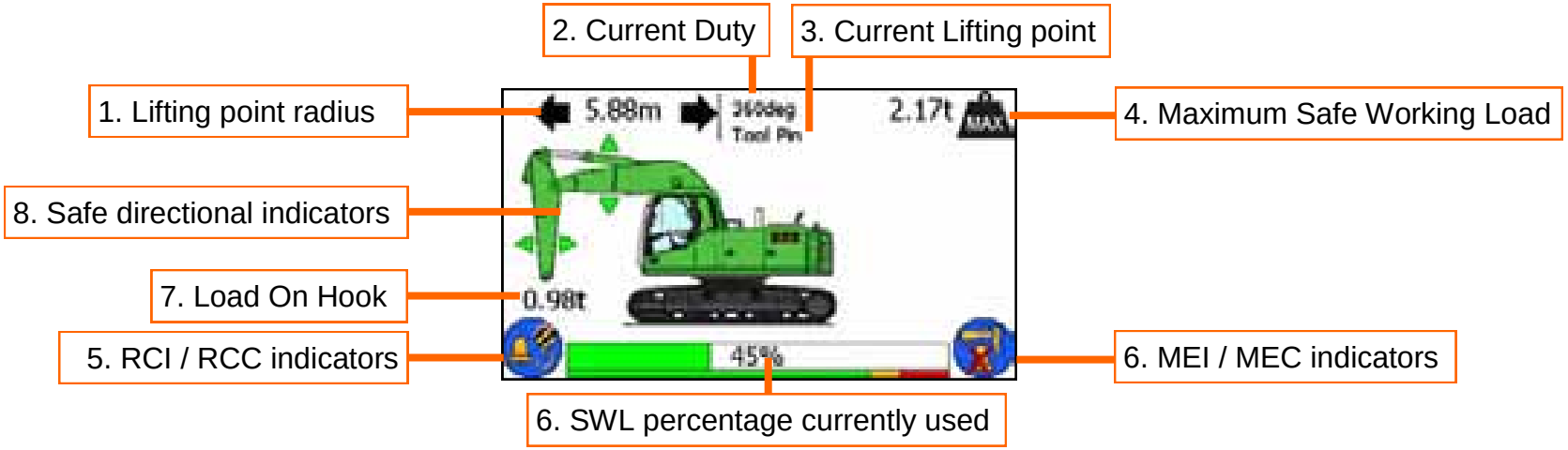
- Limits menu
- Lifting menu
- Tool selection
- Test / Diagnostics
- Lifting Mode ON and OFF
- Hide icons



7 Rated Capacity Indicator / Controller

7.1 Introduction

The PME RCI/RCC has been designed to meet European requirements for the provision of rated capacity indicators. PME ensures that the maximum lifting capacity over the range of a machine working envelope can be utilised. The system will always start up in Lifting Mode. See section 4 for operating advice when using an construction plant as a crane. The Lifting Mode feature can be used in conjunction with envelope monitoring, see section 7. In this mode, the beacon (if fitted) will indicate that the Lifting Mode functionality is active.

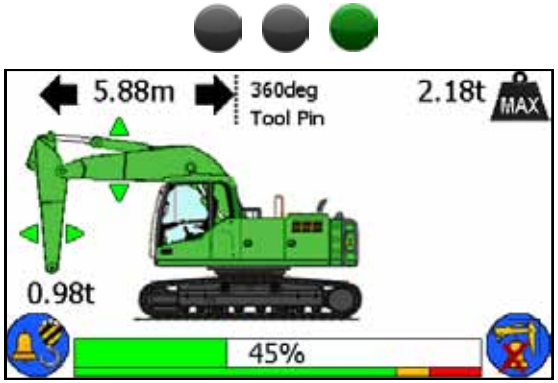


1. Lift point radius is the horizontal distance in metres from the slew centre line to the lifting point.
2. Current lifting duty in use is displayed.
3. Lift point description (Unless multiple lifting points are available, this value will be 'bucket pin').
4. Maximum Safe Working Load (SWL) for the current lifting point height and radius combination. The value is given in metric tonnes. A value shown in red indicates that the SWL is limited by hydraulic capacity and not by machine stability.
5. RCI / RCC - MEI / MEC indicators (see section 3)
6. SWL percentage bar graph indicating the percentage of the current load to the maximum available safe working load.
7. Load on Hook (LOH) shows the current load in tonnes suspended from the lifting point.
8. Safe Directional indicators. The triangles on both sides of each piece of equipment indicate if it is safe GREEN, or unsafe RED to move the relevant articulation in that direction under overload condition occurs. Triangles also indicate safe direction of movement when in breach of a height limit.

The SWL as displayed assumes that the load is suspended directly below the lifting point. The weight of the tool or tools, if fitted, (e.g. Bucket , quick hitch etc) are included in the SWL and LOH values if they were taken into consideration when the system was calibrated. The bucket cylinder and control linkage is assumed to be present.

7.2 Operation within the Safe Working Load

With the Lifting Mode active, the current lifting point radius and the maximum safe working load for that radius are shown.

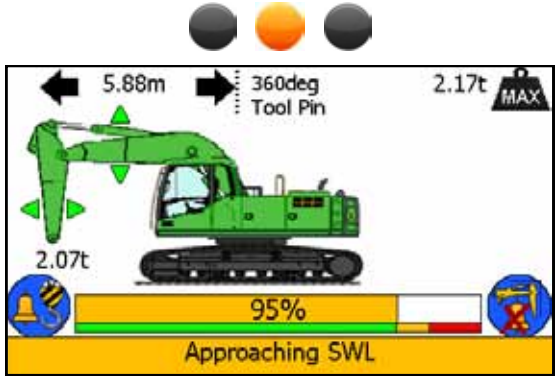


If the load is less than 95% of the maximum safe working load

- The load capacity indicator will be green
- The green LED will be lit

7.3 Approach to Overload

With the Lifting Mode active, if the load is greater than 95% of the maximum safe working load the system will warn the machine is approaching the lifting capacity at the current height and radius.



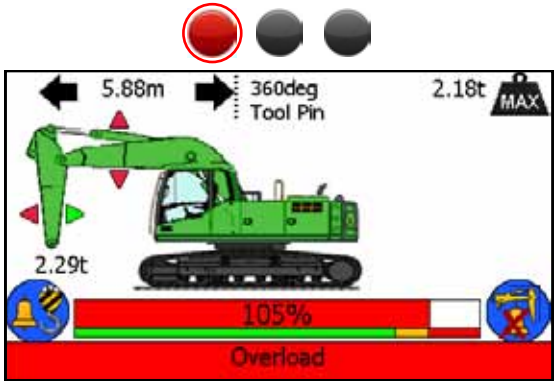
If the load is greater than 95% of the maximum safe working load.

- The load capacity indicator will be amber
- The amber LED will be lit
- The internal alarm will sound
- The message shown here will be displayed.

In the event of an approach to overload or an overload condition, the lifting point should only be moved in a direction that increases the safe working load. See section 4 for further information.

7.4 Stability Indication Overload

The system indicates an overload condition via internal and external alarms only - no motion is cut.

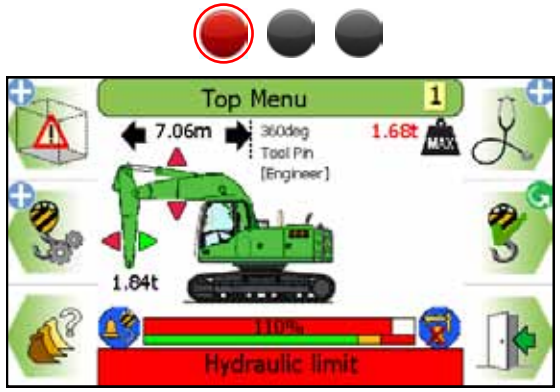


If the load is greater than 105% of the maximum safe working load

- The load capacity indicator will be red
- The red LED will flash
- The internal and external alarm will sound
- The message shown here will be displayed
- Unsafe motion is indicated by RED arrows, safe motion is indicated by GREEN arrows

7.4.1 Hydraulic Limit Indication

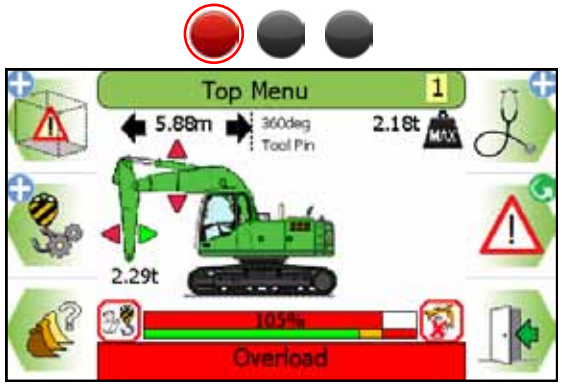
If a particular lift is limited by hydraulic capacity rather than stability, the maximum safe working load will be shown in **RED**. Hydraulic limitation is more likely to occur at short radii.



In the event of an approach to overload or an overload condition, the lifting point should only be moved in a direction that increases the safe working load. See section 4 for further information.

7.5 Stability Control Overload

Where an overload condition occurs the machine hydraulics will be locked to prevent any further dangerous movements. Only those movements that allow safer operation remain active. The radius cannot be increased and the load cannot be raised. The internal and external alarms will sound in conjunction with visual indicators on the display.



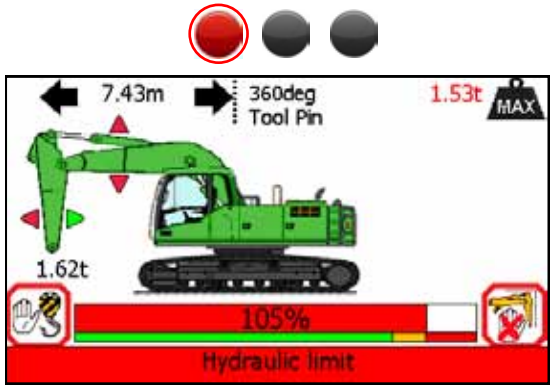
If the load is greater than 105% of the maximum safe working load

- The load capacity indicator will be red
- The red LED will flash
- The internal and external alarm will sound
- The message shown here will be displayed
- Motion control of the machine will operate, motion cut is indicated by RED arrows, safe motion is indicated by GREEN arrows

7.5.1 Hydraulic Limitation Control

The system will cut motion to the appropriate articulation in a hydraulic limit state via internal and external alarms in conjunction with visual indicators on the display.

*Where an overload condition occurs the machine hydraulics will be locked to prevent any further dangerous movements. Only those movements that allow safer operation remain active. The radius cannot be increased and the load cannot be raised.



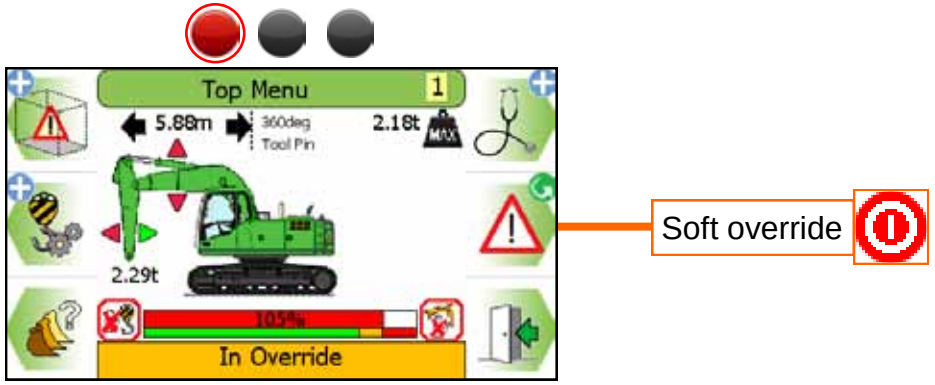
After three seconds a soft override will become available, see section 7.6.1

In the event of an approach to overload or an overload condition, the lifting point should only be moved in a direction that increases the safe working load. See section 4 for further information.

7.6 Overload / Hydraulic Limitation Control Override

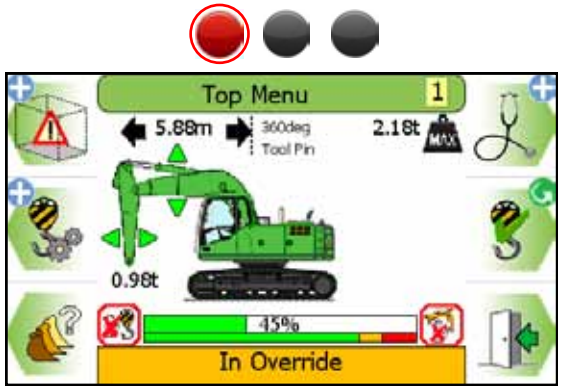
7.6.1 Soft Override

After three seconds a soft override button will replace the Lifting Mode button. If soft override is utilised, the machine hydraulics will be re-enabled. However, the external alarm will stay active, the red LED will flash, and the beacon (if fitted) will switch off. Once the alarm condition has been corrected the RCC will automatically clear the override request and revert to normal operation.



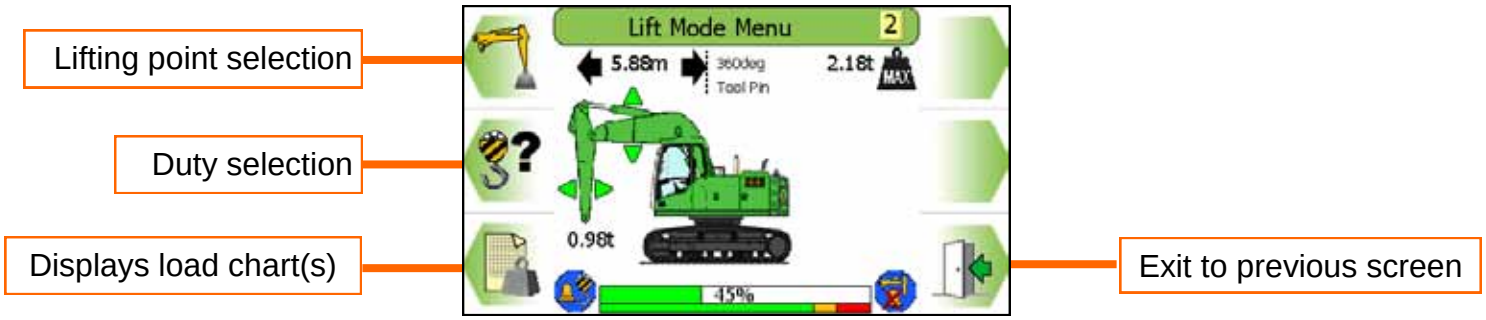
7.6.2 Master Override key Switch

The system can optionally be fitted with a key operated Master override switch. Turning the switch to the override position will allow normal operation of any of the hydraulic services regardless of safety status. When the unit is in override the external alarms will stay active, and the beacon (if fitted) will indicate that the machine is overridden, the red LED will flash and an In Override message will appear on the display. See section 4.1 for further details.



7.7 Lift Mode Menu

The Lifting Mode function has various features which may be available if configured at installation. The configuration will depend on the operating procedures of the machine owner. If only one duty, lifting point and or tool has been calibrated, the relevant icon will not be displayed. Each will affect the SWL,



7.8 Lifting Point Selection


The current lifting point is indicated on Lifting Mode screen. The system can be calibrated with just one lifting point for use in any duty. If more than one lifting point has been calibrated, it will be manually selected via the lifting point selection screen shown below. Use the arrow buttons to select the required lifting point and confirm using the TICK button. Example lifting points are shown in the listing.

Multiple lifting points allow different lifting capacities to be achieved, altering the lifting point will not affect the current duty selected (See section 7.8).

7.9 Duty Selection

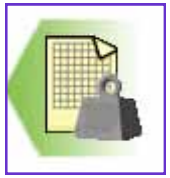
The current duty is indicated on the Lifting Mode screen. The system can be calibrated with just one duty for use throughout 360 degrees of slew, most machines will be calibrated in this way. If more than one duty has been calibrated, it will either be manually or automatically selected. Manual selection is via the duty selection screen shown below. Use the arrow buttons to select the required duty and confirm using the TICK button. Common duty types are shown in the listing.

Multiple duties on tracked machines may be used to allow both 360º and FRONT/REAR lifting arcs for increased lifting capacity. On wheeled machines extra duties could be used for any combination of arc, support blade and stabiliser usage. Altering the duty will not affect the current lifting point selected (See section 7.8).

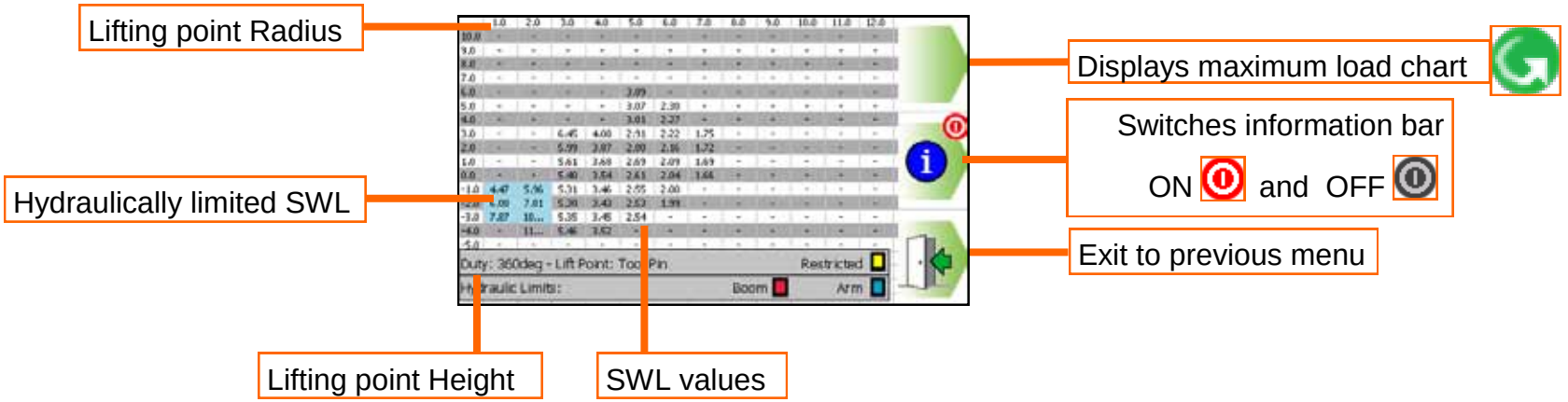
If automatic duty switching is available, manual duty selection will be disabled. Automatic duty selection can be based on a number of machine features such as slew position, stabiliser position, telescopic extension position, secondary equipment.

If only one duty has been calibrated this screen will not be accessible.

7.10 Load Chart Menu



PME can display the load chart for the currently selected lifting duty and lifting point. If the machine is equipped with a hydraulically adjustable boom, both maximum and minimum charts will be available. Hydraulically adjustable booms allow the machine to reach the same point in space (i.e. height and radius combination) with a variety of different equipment angles. The minimum loads shown refer to the least favourable angle combination. When load charts are being displayed, machine safety status is still monitored.

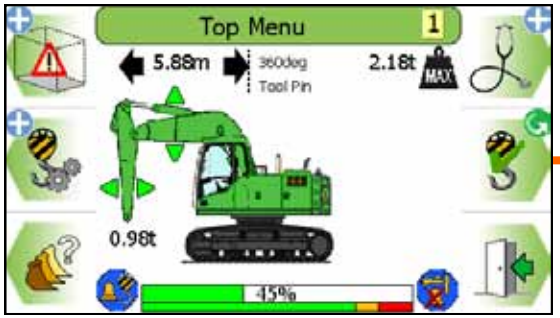


If a particular lift is limited by hydraulic capacity rather than stability, the maximum safe working load will be shown in **RED**. The maximum load for duties limited by stability is stated as a percentage of the 'tipping load' and in a standard installation will be 75%.

7.11 Lifting Mode - Non Lifting Mode

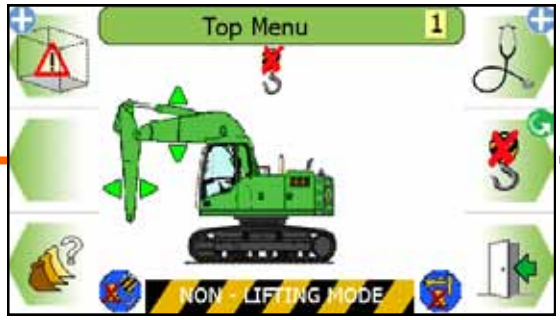


When the machine is not being used for lifting operations it can be put into 'Non Lifting Mode' from the Top Menu screen. This option allows the machine to be used for digging etc. When in Non Lifting Mode, the system still monitors all machine activity and safety status but will NOT warn of overload conditions. In this mode, the beacon (if fitted) will indicate that the Lifting Mode functionality is NOT active. Lifting mode cannot be activated if the LOH value exceeds a predefined weight. Envelope Limit monitoring will remain active if any limit has been set.



Lifting Mode ON

Note Lift Mode button is not accessible



Lifting Mode OFF

When in Non Lifting Mode, the screen states NON-LIFTING MODE on the hazard warning tape and a red cross appears in the RCI RCC indicator - lifting operations should not be attempted in this state. The beacon (if fitted) will be off.

7.12 Tool Selection Menu

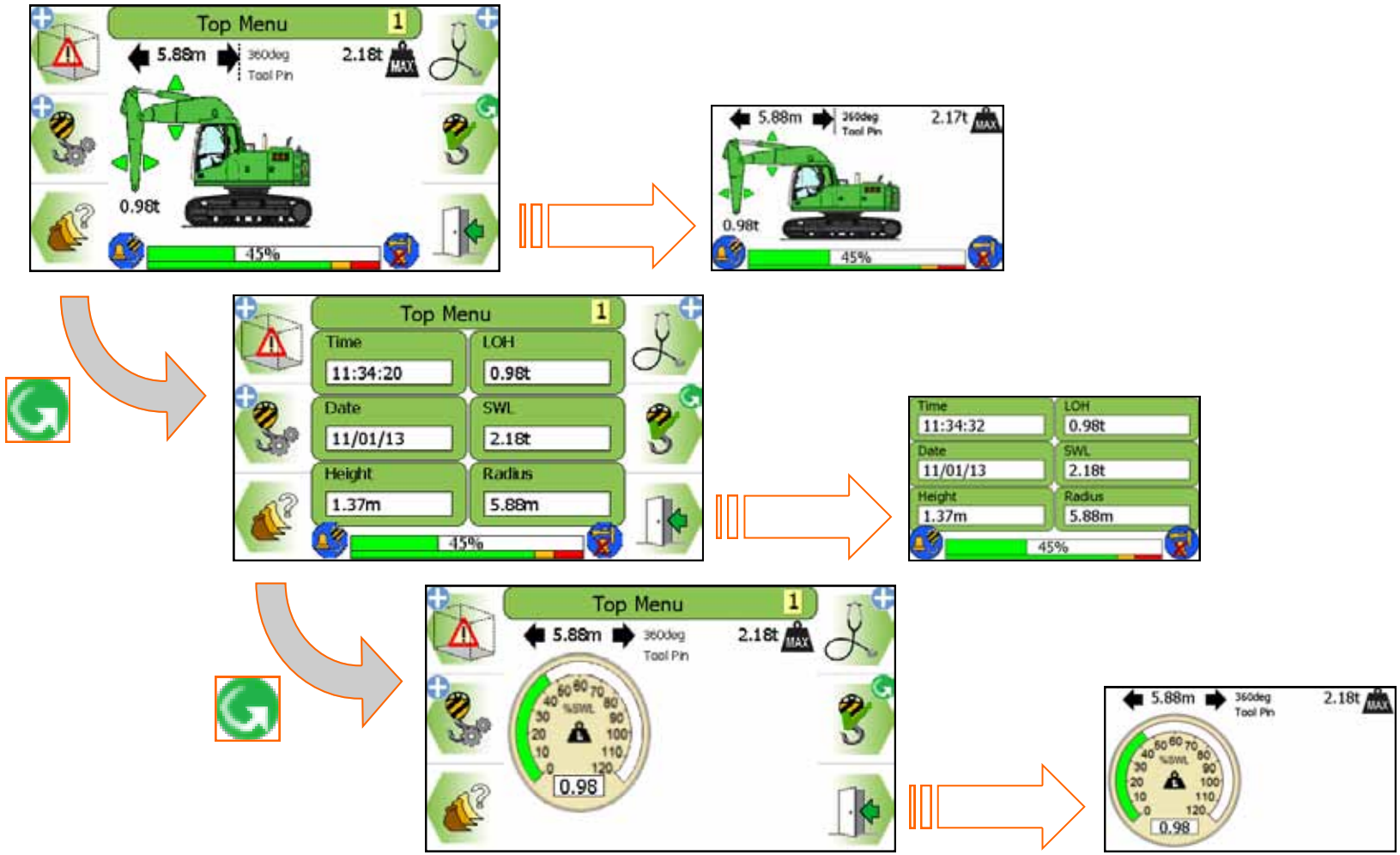
The system can be calibrated with no tools, one or multiple tools for use in any duty. If more than one tool has been calibrated, it will be manually selected via the Select tool selection screen shown below. Use the arrow buttons to select the required tool and confirm using the TICK button. Example tools are shown in the listing.

Different tools allow different lifting capacities to be achieved, altering the tool will not affect the current duty selected (See section 8.1).

If only one tool has been calibrated this screen will not be accessible.

7.13 Alternative Lifting Mode Screens

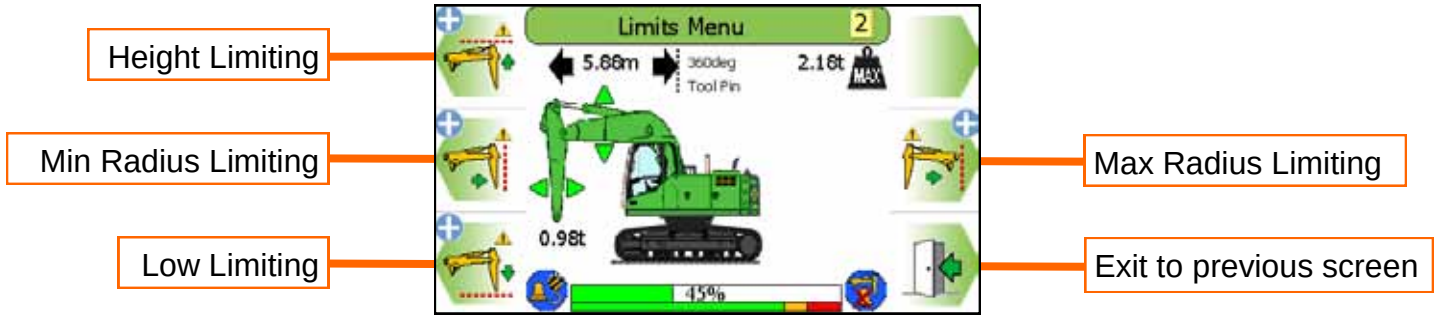
Alterative Lifting Mode screens can be selected from the Display Settings screen (See section 13). The three selectable screens show safe working load, load on hook, lifting point radius and bar graph or dial indicating the proximity of the current load to the maximum available safe working load. Pressing the EXIT button will hide the icons. Press any button to reveal the icons.



8 Envelope Monitoring

PME envelope monitoring can be configured to be either a Machine Envelope Indication (MEI) or Machine Envelope Control (MEC) system for Height, Max Radius, Min Radius and Low limits. A limit type may or may not be enabled at the point of installation, MEI will give a warning only, MEC will warn and prevent equipment motion (see section 3). MEC is achieved by interacting with the machines hydraulics, this allows motion to be cut to any section of equipment that has reached a limit but allow other sections to operate unhindered unless they too reach the set limit.

When setting a limit, either by entering a known value or by positioning the machine at the desired limit, make sure any implement attached is in its least favourable position as the system is unaware of any implement fitted even if it is selectable in Tools (see section 7.12).



MEC MEI


OFF: when operating with an inactive limit the indicator will have a cross painted on it.


ON: when operating with an active limit the indicator will not have a painted on cross on it.

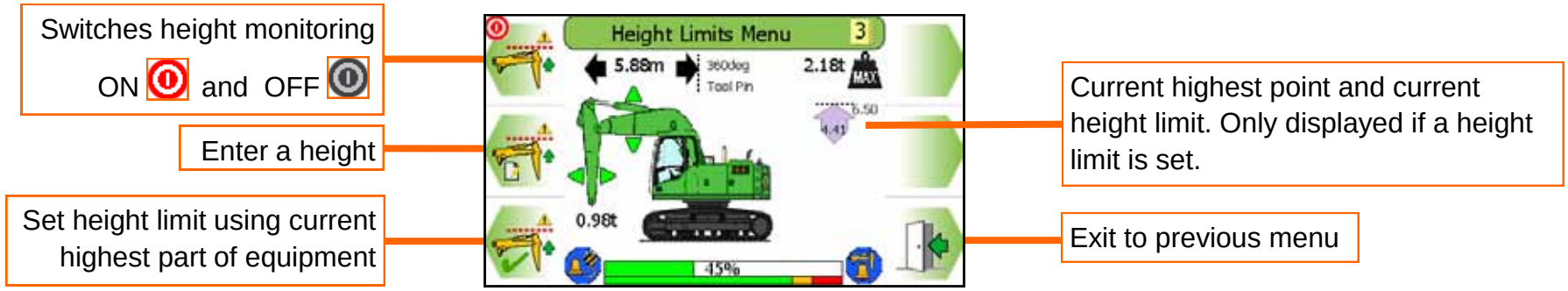
Care should be taken to test that the limit is set correctly.

Observe the operational limitations given in section 4.

8.1 Limits Menu

8.1.1 Height Limit Menu

A height limit can be set by entering a known height on the keypad or by manually moving the machine to the desired limit.



Using the height Limits Menu, the height limit can be switched ON and OFF, see sections 8.1.2 to enter a known height and section 8.1.3 for setting the limit by moving the machine.

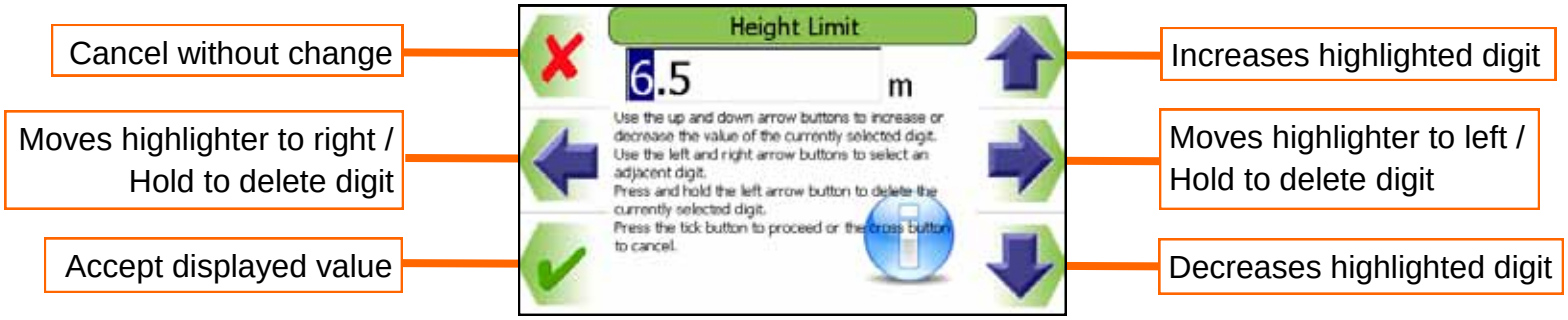
Once a height limit is set, the internal alarm will sound and the RED LED will light if the highest point of the equipment exceeds the current limit. Always check that the height limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.1.2 Height Limit Setting - Known Height

A known limit can be entered into the display:

Press the 'Enter a value' button

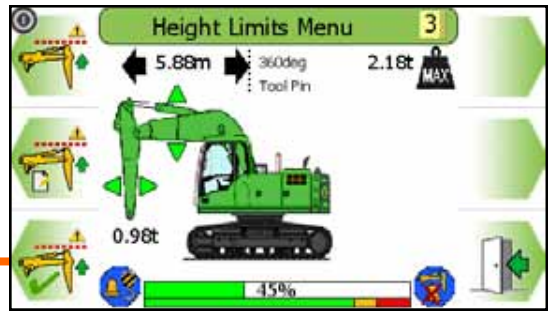
Use the UP and DOWN arrows to increase and decrease the highlighted number. Use the LEFT and RIGHT arrows to move the high-lighter to the left and to the right.

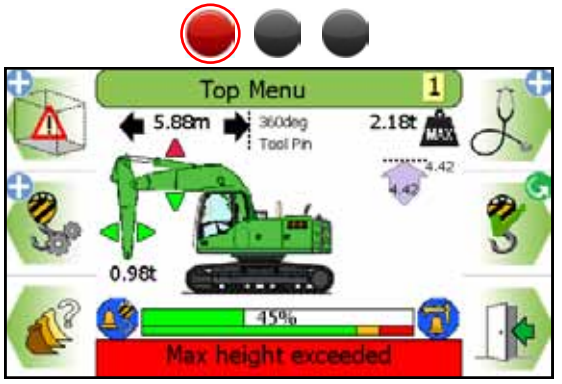


Once a limit is set, the internal alarm will sound and the RED LED will light if the equipment exceeds the current limit. Always check that the limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.1.3 Height Limit Setting - Using Current Highest Point

Move equipment to required height limit and press this button

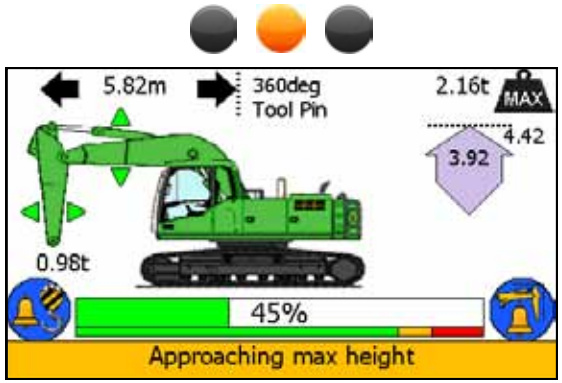


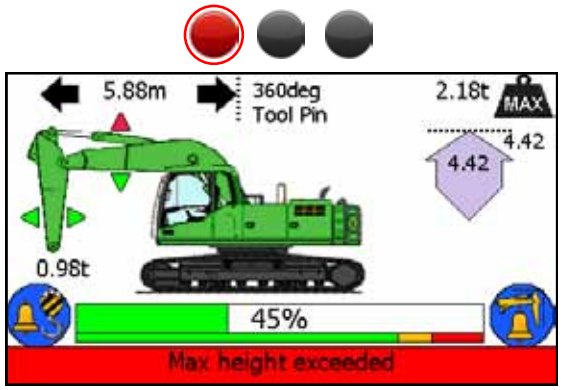


To set the height limit using the machine, move the equipment to the desired maximum height, and press the ‘current highest point’ button. A confirmation box will appear reporting the height set. Press the TICK button to continue.

8.1.4 Machine Envelope Indicator (MEI) - Height

If any of the equipment enters the approach limit* an ‘Approaching max height’ message will appear, the internal alarm will sound and the amber LED will be lit.





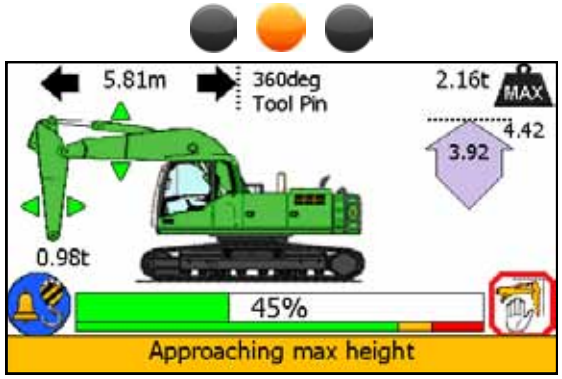
MEI systems will not cut motion to any section of equipment that has reached a limit. This can lead to the a breech of the set limit.

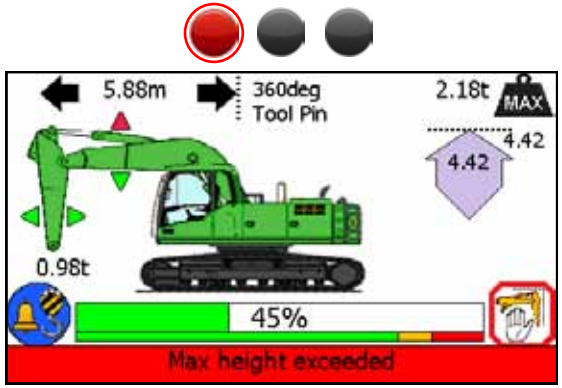
*The approach limit is configurable at point of calibration, check system operation before commencing work.

If any of the equipment exceeds the set limit a ‘Max height exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.1.5 Machine Envelope Controller (MEC) - Height

If any of the equipment enters the approach limit* an ‘Approaching max height’ message will appear, the internal alarm will beep and the amber LED will be lit. If any of the equipment reaches the height limit, the appropriate motions will be controlled.





MEI systems will cut motion to any section of equipment that has reached a limit but allow other sections to operate unhindered unless they too reach the set limit.

*The approach limit is configurable at point of calibration, check system operation before commencing work.
See sections 4.1 and 6.5.2 for hydraulic override details.

If any of the equipment exceeds the set limit a ‘Max height exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.2.1 Max Radius Limit

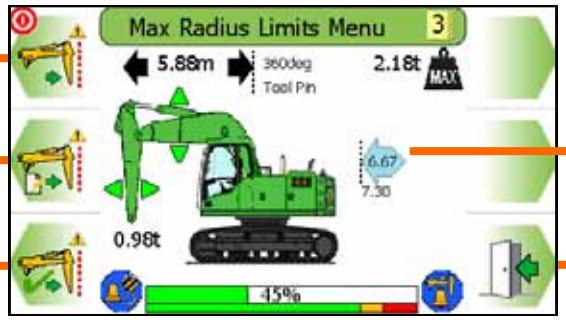
8.2.1 Max Radius Limit Menu

A max radius limit can be set by entering a known radius on the keypad or by manually moving the machine to the desired limit.

Switches height monitoring ON and OFF

Enter a value

Set limit using current far-thest part of equipment



Current max radius limit. Only displayed if a max radius limit is set.

Exit to previous menu

Using the Max Radius Limits Menu, the max radius limit can be switched ON and OFF, a max radius limit can be set to a known value, or the max radius limit can be set to the current farthest point.

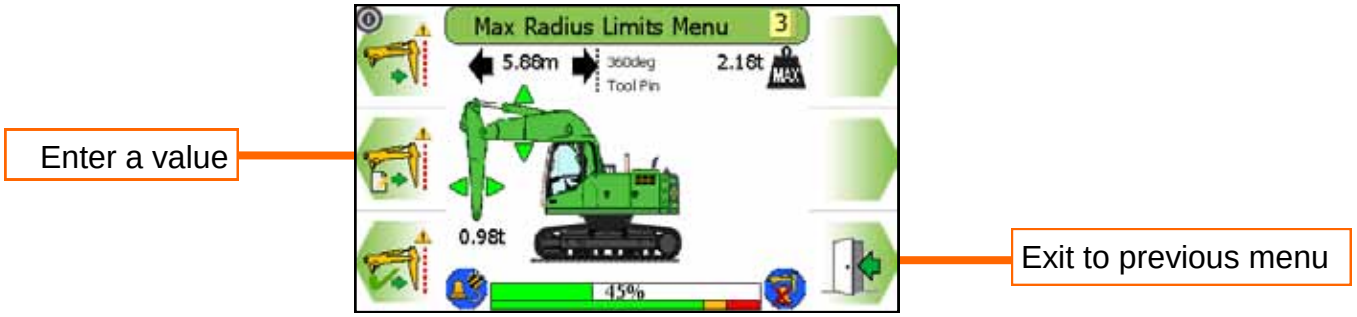
See sections 8.2.2 to enter a known max radius and section 8.2.3 for setting the limit by moving the machine.

Once a max radius limit is set, the internal alarm will sound and the RED LED will light if the farthest point of the equipment exceeds the current limit. Always check that the max radius limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

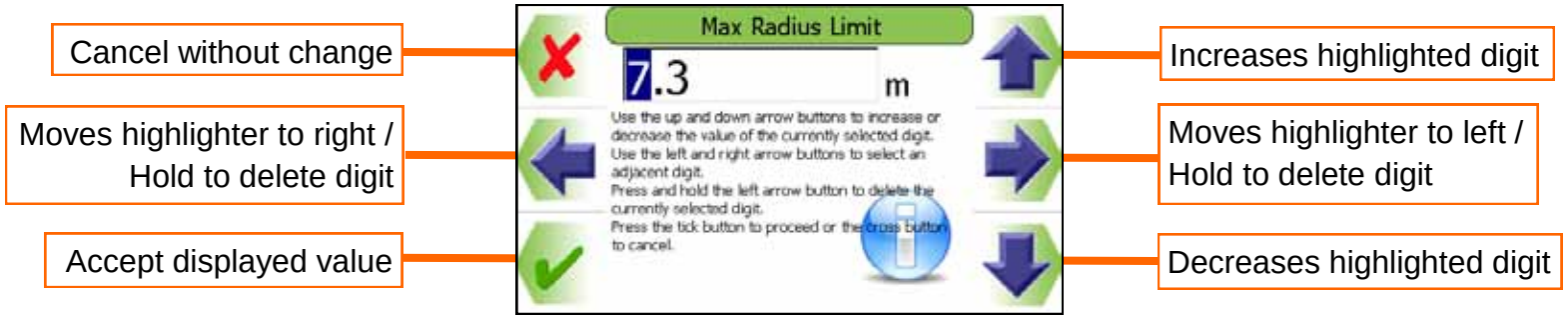
8.2.2 Max Radius Limit Setting - Known Radius

A known limit can be entered into the display:

Press the 'Enter a value' button



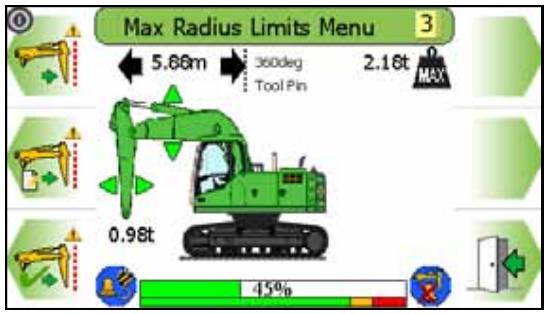
Use the UP and DOWN arrows to increase and decrease the highlighted number. Use the LEFT and RIGHT arrows to move the highlighter to the left and to the right.



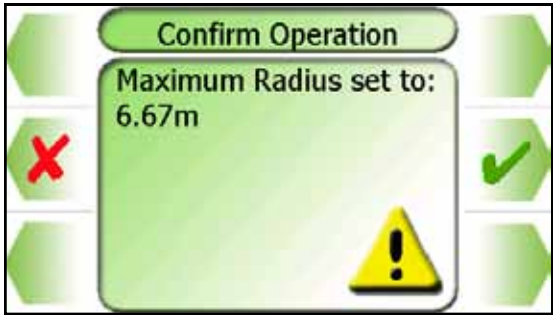
Once a max radius limit is set, the internal alarm will sound and the RED LED will light if the farthest point of the equipment exceeds the current limit. Always check that the max radius limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

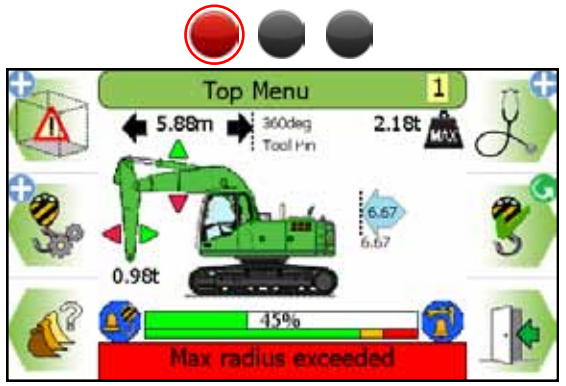
8.2.3 Max Radius Limit Setting - using Current Max Radius

Move equipment to required max radius limit and press this button



To set the max radius limit using the machine, move the equipment to the desired radius, and press the 'current farthest point' button. A confirmation box will appear reporting the radius set. Press the TICK button to continue.

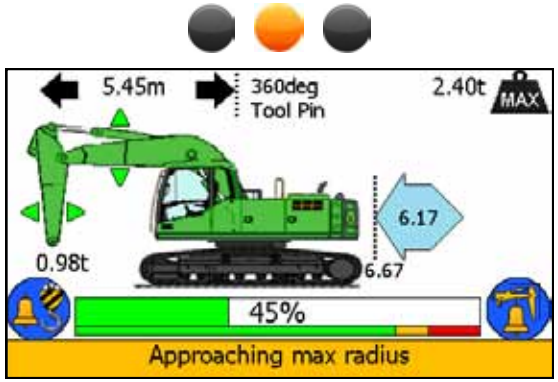


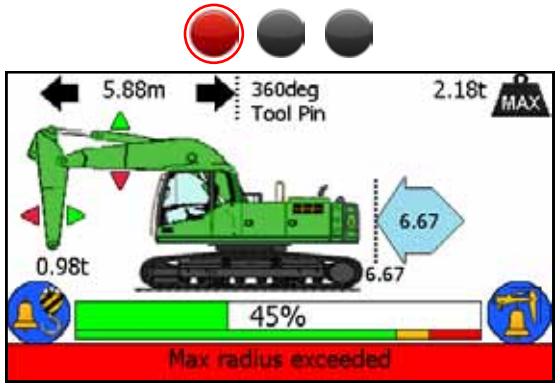


Once a max radius limit is set, the internal alarm will sound and the RED LED will light if the farthest point of the equipment exceeds the current limit. Always check that the max radius limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.2.4 Machine Envelope Indicator (MEI) - Max Radius

If any of the equipment enters the approach limit* an ‘Approaching max radius’ message will appear, the internal alarm will sound and the amber LED will be lit.





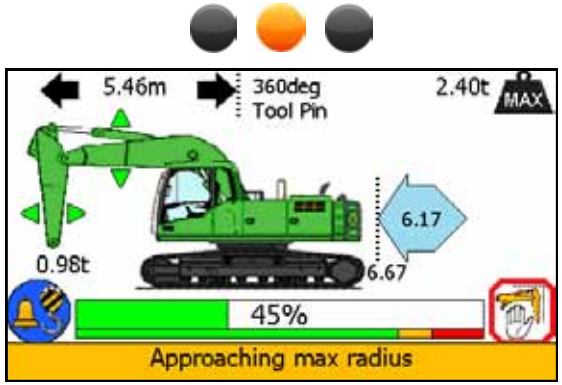
MEI systems will not cut motion to any section of equipment that has reached a limit. This can lead to the a breech of the set limit.

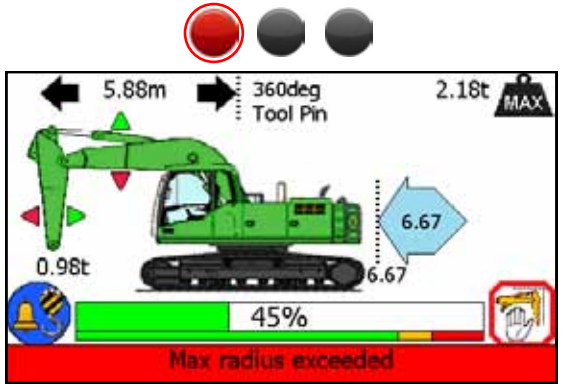
*The approach limit is configurable at point of calibration, check system operation before commencing work.

If any of the equipment exceeds the set limit a ‘Max radius exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.2.5 Machine Envelope Controller (MEC) - Max Radius

If any of the equipment enters the approach limit* an ‘Approaching max radius’ message will appear, the internal alarm will beep and the amber LED will be lit. If any of the equipment reaches the max radius limit, the appropriate motions will be controlled.





MEI systems will cut motion to any section of equipment that has reached a limit but allow other sections to operate unhindered unless they too reach the set limit.

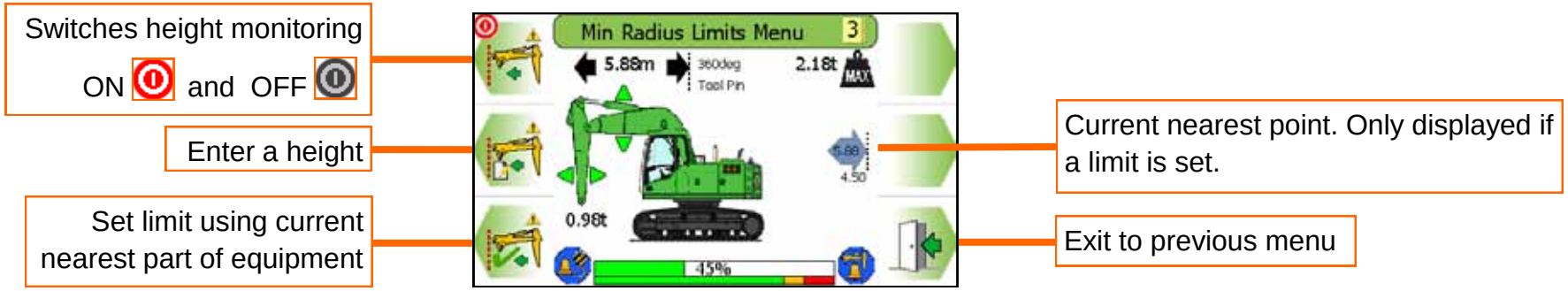
*The approach limit is configurable at point of calibration, check system operation before commencing work.

If any of the equipment exceeds the set limit a ‘Max radius exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.3 Min Radius

8.3.1 Min Radius Limit Menu

A min radius limit can be set by entering a known radius on the keypad or by manually moving the machine to the desired limit.



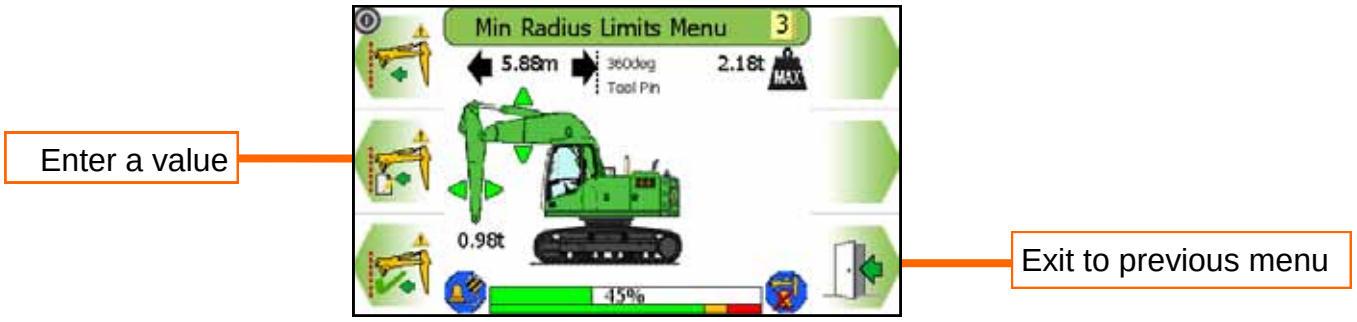
Using the Min Radius Limits Menu, the min radius limit can be switched ON and OFF, see sections 8.3.2 to enter a known min radius and section 8.3.3 for setting the min radius by moving the machine.

Once a min radius limit is set, the internal alarm will sound and the RED LED will light if the nearest point of the equipment exceeds the current limit. Always check that the min radius limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

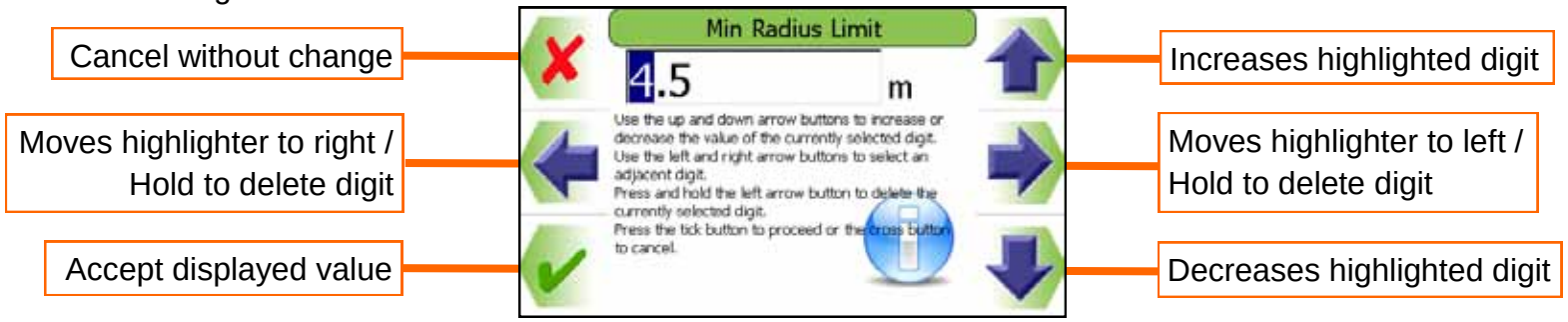
8.3.2 Min Radius Limit Setting - Known Min Radius

A known min radius can be entered into the display:

Press the 'Enter a value' button



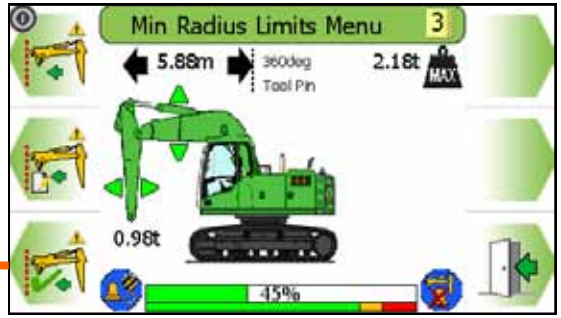
Use the UP and DOWN arrows to increase and decrease the highlighted number. Use the LEFT and RIGHT arrows to move the high-lighter to the left and to the right.



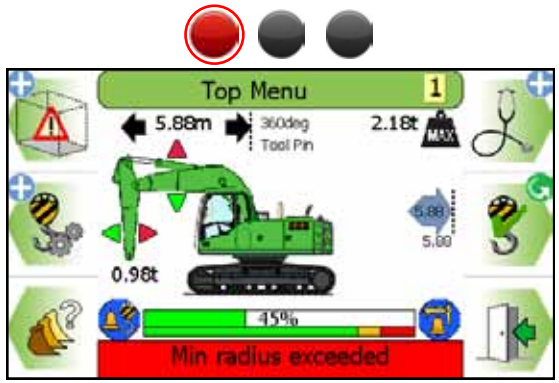
Once a height limit is set, the internal alarm will sound and the RED LED will light if the nearest point of the equipment exceeds the current limit. Always check that the min radius limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.3.3 Min Radius Limit Setting - using Current Min Radius

Move equipment to required min radius limit and press this button



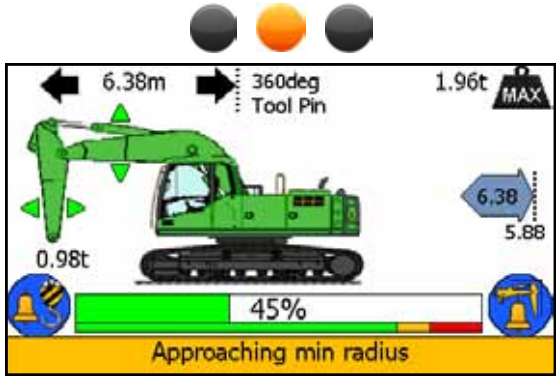
To set the min radius limit using the machine, move the equipment to the desired minimum radius, and press the 'current nearest point' button. A confirmation box will appear reporting the radius set. Press the TICK button to continue.

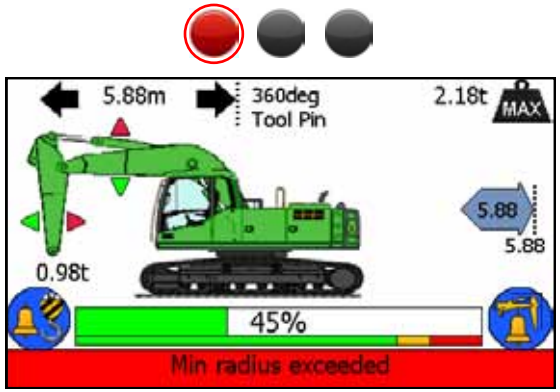


Once a height limit is set, the internal alarm will sound and the RED LED will light if the nearest point of the equipment exceeds the current limit. Always check that the min radius limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.3.4 Machine Envelope Indicator (MEI) - Min Radius

If any of the equipment enters the approach limit* an ‘Approaching min radius’ message will appear, the internal alarm will sound and the amber LED will be lit.





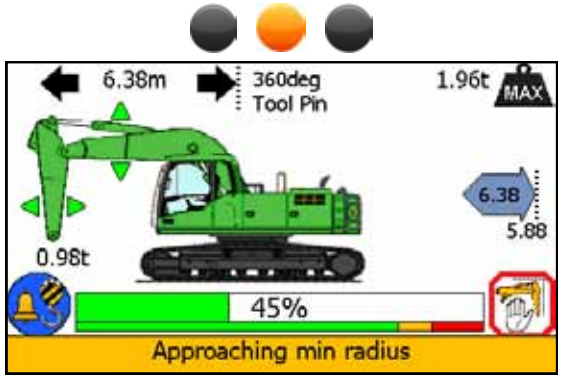
MEI systems will not cut motion to any section of equipment that has reached a limit. This can lead to the a breech of the set limit.

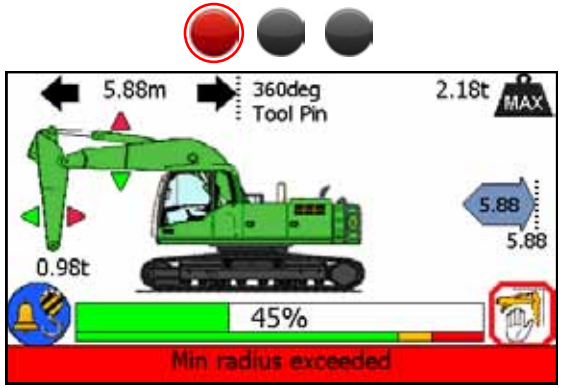
*The approach limit is configurable at point of calibration, check system operation before commencing work.

If any of the equipment exceeds the set limit a ‘Min radius exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.3.5 Machine Envelope Controller (MEC) - Min Radius

If any of the equipment enters the approach limit* an ‘Approaching min radius’ message will appear, the internal alarm will beep and the amber LED will be lit. If any of the equipment reaches the min radius limit, the appropriate motions will be controlled.





MEI systems will cut motion to any section of equipment that has reached a limit but allow other sections to operate unhindered unless they too reach the set limit.

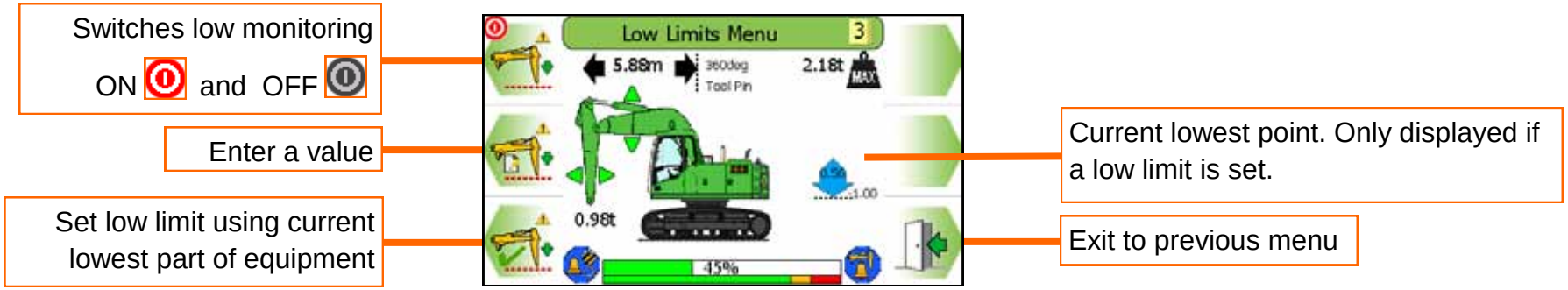
*The approach limit is configurable at point of calibration, check system operation before commencing work.
See sections 4.1 and 6.5.2 for hydraulic override details.

If any of the equipment exceeds the set limit a ‘Min radius exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.4 Low Limits

8.4.1 Low Limit Menu

A low limit can be set by entering a known height on the keypad or by manually moving the machine to the desired limit.



Using the Low Limits Menu, the low limit can be switched ON and OFF, a low limit can be set to a known value, or the low limit can be set to the current lowest point.

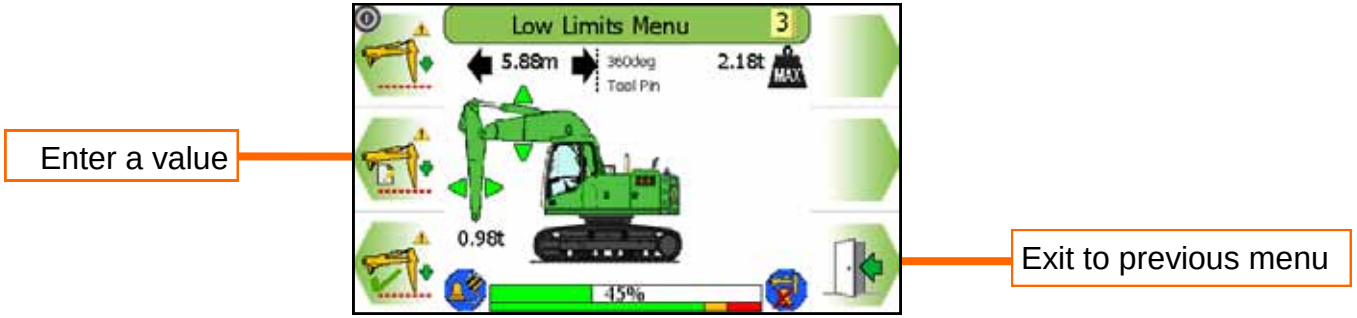
See sections 8.4.2 to enter a known low and section 8.4.3 for setting the limit by moving the machine.

Once a low limit is set, the internal alarm will sound and the RED LED will light if the lowest point of the equipment exceeds the current limit. Always check that the low limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

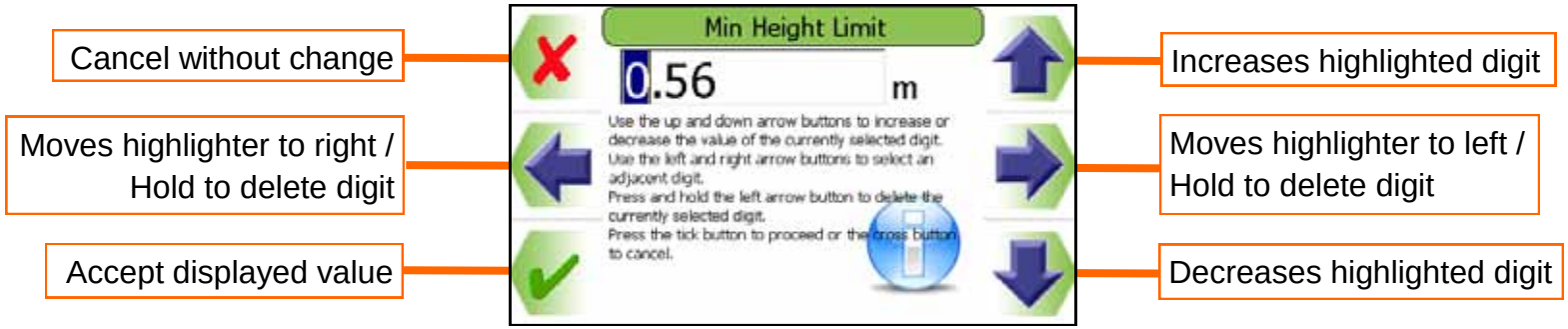
8.4.2 Low Limit Setting - Known Low

A known low limit can be entered into the display:

Press the 'Enter a value' button



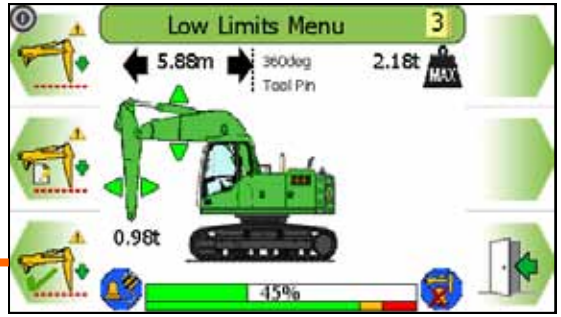
Use the UP and DOWN arrows to increase and decrease the highlighted number. Use the LEFT and RIGHT arrows to move the highlighter to the left and to the right.

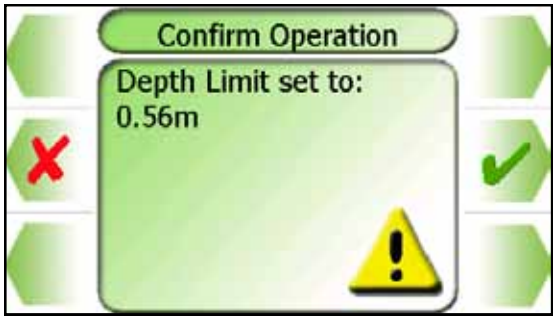


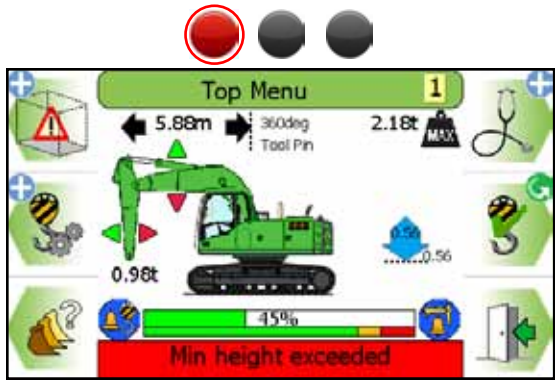
Once a low limit is set, the internal alarm will sound and the RED LED will light if the lowest point of the equipment exceeds the current limit. Always check that the low limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.4.3 Low Limit Setting - using Current Low

Move equipment to required low limit and press this button





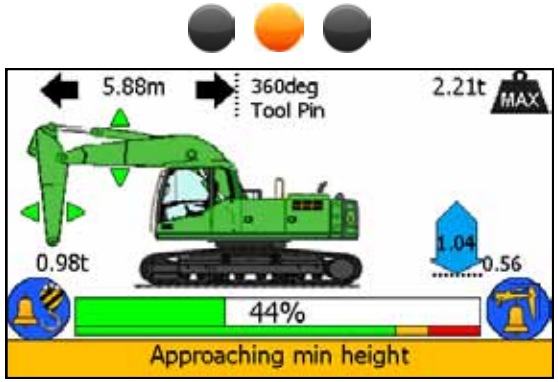


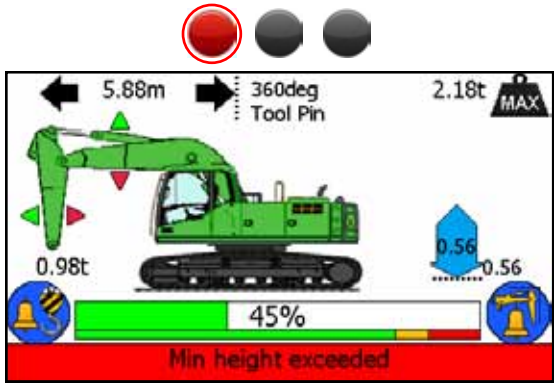
To set the low limit using the machine, move the equipment to the desired low height, and press the 'current lowest point' button. A confirmation box will appear reporting the height set. Press the TICK button to continue.

Once a low limit is set, the internal alarm will sound and the RED LED will light if the lowest point of the equipment exceeds the current limit. Always check that the low limit activates at the set point. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.4.4 Machine Envelope Indicator (MEI) - Low

If any of the equipment enters the approach limit* an ‘Approaching min height’ message will appear, the internal alarm will sound and the amber LED will be lit.





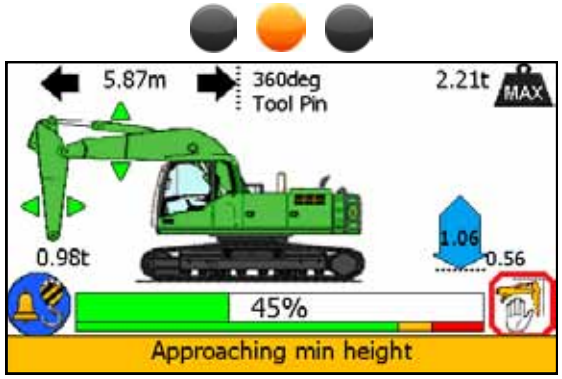
MEI systems will not cut motion to any section of equipment that has reached a limit. This can lead to the a breech of the set limit.

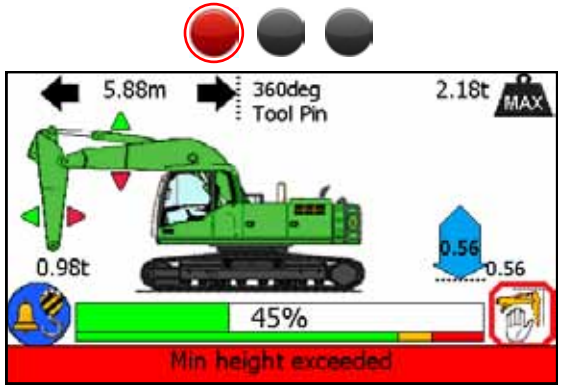
*The approach limit is configurable at point of calibration, check system operation before commencing work.

If any of the equipment exceeds the set limit a ‘Min height exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

8.4.5 Machine Envelope Controller (MEC) - Low

If any of the equipment enters the approach limit* an ‘Approaching min height’ message will appear, the internal alarm will beep and the amber LED will be lit. If any of the equipment reaches the low limit, the appropriate motions will be controlled.





MEI systems will cut motion to any section of equipment that has reached a limit but allow other sections to operate unhindered unless they too reach the set limit.

*The approach limit is configurable at point of calibration, check system operation before commencing work.
See sections 4.1 and 6.5.2 for hydraulic override details.

If any of the equipment exceeds the set limit a ‘Min height exceeded’ message will appear, the internal alarm will sound and the red LED will be lit. The limit cannot be deactivated if in the alarm state. Observe the operational limitations given in section 4.

9 Warning Messages

9.1 On Screen Messages

Approaching max height	Highest point of equipment within *0.5m of set limit
Maximum height exceeded	Highest point of equipment has reached/exceeded set limit
Approaching max radius	Furthest point of equipment within *0.5m of set limit
Maximum radius exceeded	Furthest point of equipment has reached/exceeded set limit
Approaching min radius	Nearest point of equipment within *0.5m of set limit
Minimumradius exceeded	Nearest point of equipment has reached/exceeded set limit
Approaching min height	Lowest point of equipment within *0.5m of set limit
Minimum height exceeded	Lowest point of equipment has reached/exceeded set limit
Approaching SWL	95 percent of the maximum safe working load
Overload	105 percent of the maximum safe working load
Hydraulic Limit	Pressure in the lift rams is in excess of 87% of main relief valve pressure

*The approach limit is configurable at point of calibration, check system operation before commencing work.

PME continuously monitors the presence and condition of the safety controller and sensors. If the safety controller or any sensor fails an error message box will appear at the bottom of the display. In the event of a failure, the cab mounted beacon (if fitted) will indicate that the system is NOT active, the display red LED will flash and the internal and external alarms will sound.

9.2 LED and Internal Alarm Warnings

The table below shows the state of the three LEDs on the display and the internal alarm with respect to system status.

LED and Internal Alarm status	System status
	Off
	Start up, Power Down
	Operational: System OK, no warnings, hazards, or errors
 1 Hz	Warning: Approach to overload or envelope limit
 Continuous	Hazard: Overload or breach of an envelope limit
	Maintenance: Engineering access active
 8 Hz	Error: PME hardware/software error, or sensor failure

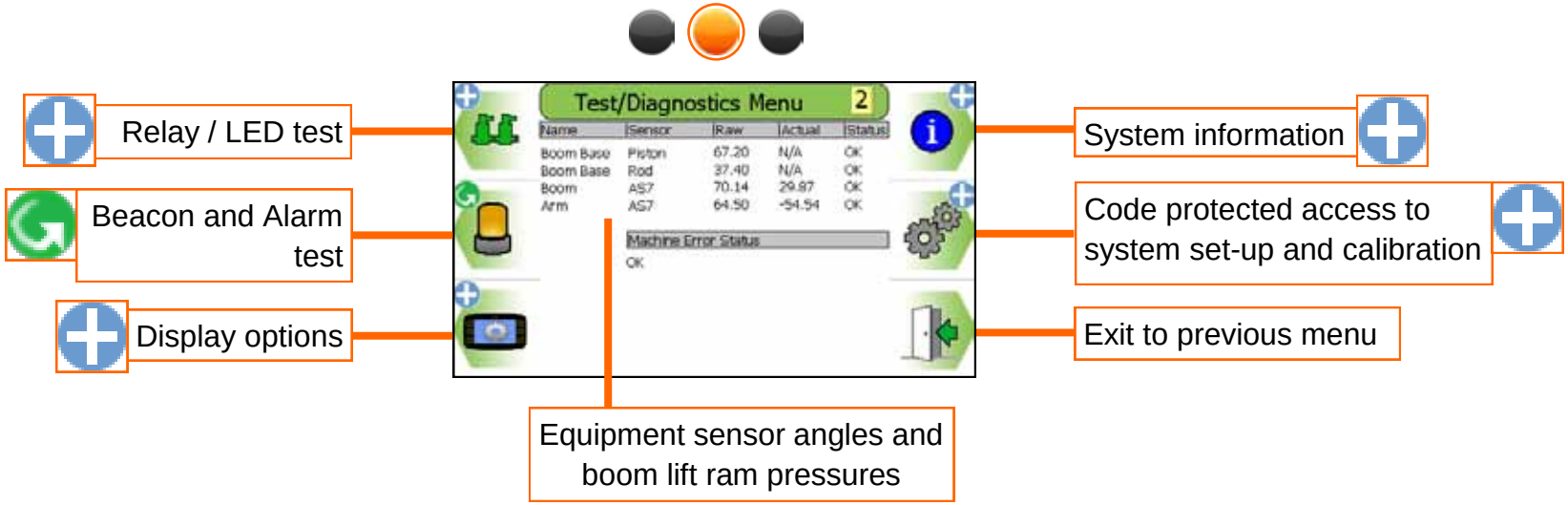
10 Daily Checks

- Display and Safety Controller - check for damage and correct operational
- Sensors and sensor cabling including connectors- check for damage
- Alarm / beacon / LED functionality
- Automatic duty selection

See section 11 for test / diagnosis features. If an issue is discovered which cannot be rectified using this guide, halt any operation, seek authorised service immediately and do not continue operation until the fault has been remedied.

11 Test / Diagnostics

The system test function is available from the main operating screen. This option allows the functionality of the system to be verified, and basic trouble-shooting to be performed. In this mode, the amber LED will flash to indicate that the system is in maintenance mode. The system will continue to monitor any limits that are active and the Lifting Mode (if active) will continue to monitor machine safety status. Alarm conditions and warnings / controls will be issued as normal.



The image shown is an example only. The exact contents of the sensor list will depend on machine type and PME specification.

11.1 Relay Function Test

Operate show status of feature

Exit to previous menu

11.2 Beacon, LED Alarm Function Test

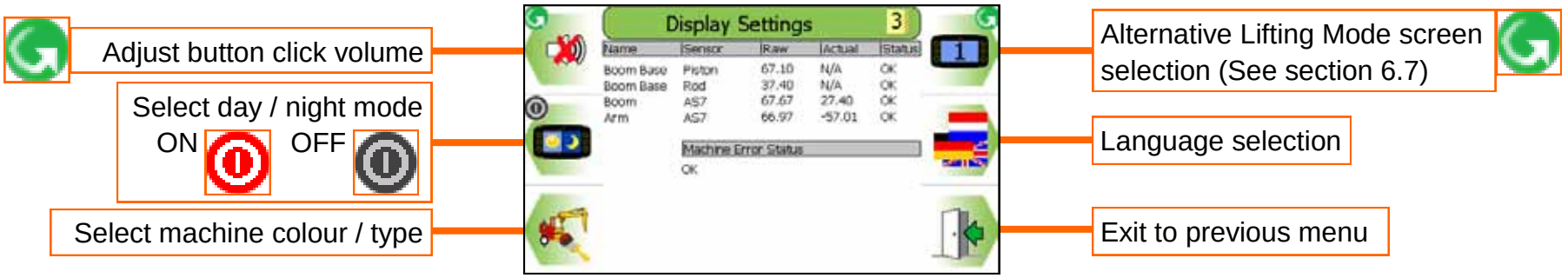
Press the Beacon button to activate the alarm 

Press the Alarm button to activate the LEDs 

Press the Alarm button to activate the beacon 

12 Display Settings

The display brightness, button click volume, and the displayed machine colour and type can be adjusted from this menu.



12.1 Day / Night Mode

To make viewing the display more comfortable at night, the display brightness can be switched to a preset ‘night mode’. The system will default to day mode on power up.

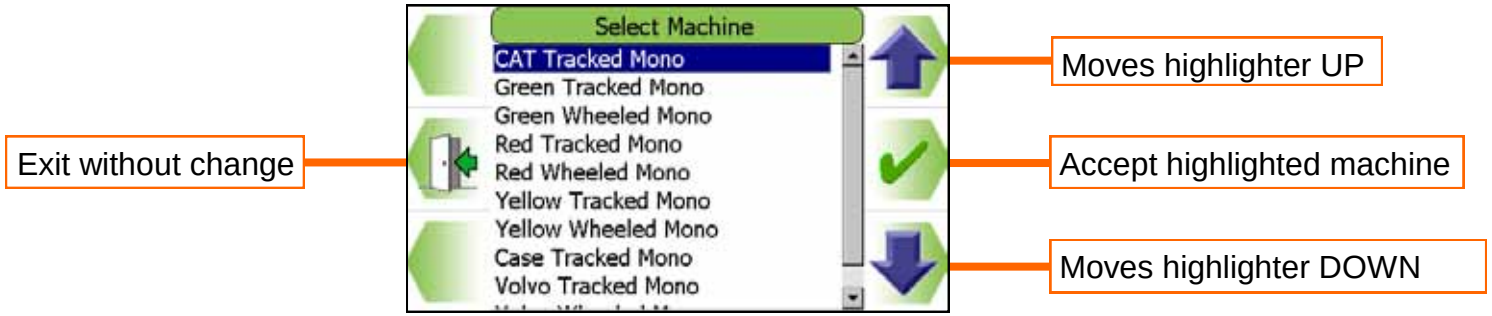
Select day / night mode:

Day mode ON
Full display brightness

Night mode ON
Reduced display brightness

12.2 Select Display Machine

An appropriate machine type for the display can be selected from this list.



12.3 Select Language

An appropriate language for the operator can be selected from this list.

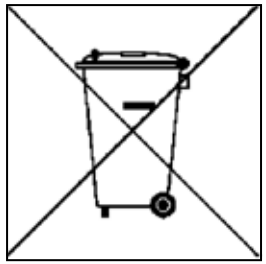
13 System Information

Information regarding the system can be found from this menu.

14 Taking Product out of Operation

Prolec Limited is committed to complying with the upcoming European Directive of RoHS (Restriction of Certain Hazardous Substances) and WEEE (Waste from Electrical and Electronic Equipment). PME is subject to the WEEE directive, therefore PME or any component must be returned to Prolec Ltd for correct disposal or recycling.

The display and safety controller are fitted with internal batteries and must not be disposed of in landfill.



15 Service and Repair

PME has very few user serviceable parts. The safety controller has internal fuses that, in the event of a blown fuse, can be replaced. The service section describes daily, monthly and yearly checks that must be carried out to ensure safe operation of the system.

15.1 Maintenance Review

Due to nature of the PME system operating environment, changes in usage can occur. Prolec Ltd must be notified of any changes in the pattern of use of the system for consideration.

Any alterations or modifications to machine components which affect the system must be reported to Prolec Ltd or via the service agreement holder.

To aid in the use of PME, all appropriate technical bulletins relating to PME are to be assessed and implemented as appropriate. This information is available from Prolec Ltd.

Prolec Ltd must be informed of any Prolec system component failure via the service agreement holder.

Technical consultation is available to the user, contact Prolec Ltd or the service agreement holder.

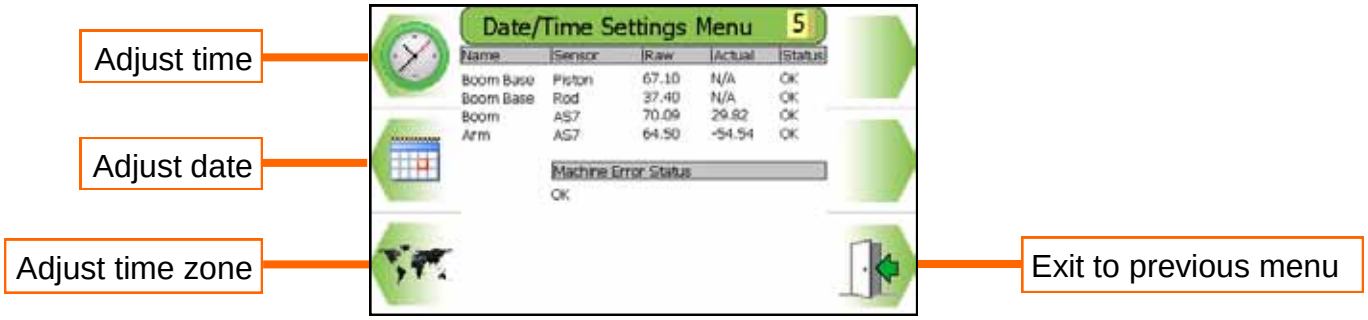
Prolec Ltd	Telephone	+44 (0) 1202 681190
25 Benson Road	Fax	+44 (0) 1202 677909
Nuffield Industrial Estate	Email	service@prolec.co.uk
Poole Dorset BH17 0GB		

15.2 Time / Date

The time and date can be checked in the alternative RCI screen number 2. Adjustment can be made, see sections 16.2.1

15.2.1 Time / Date Adjustment

Time / date adjustment requires supervisor access rights.



Continued...

15.2.1 Time / Date Adjustment continued

Cancel without change

Moves highlighter to right / Hold to delete digit

Accept displayed value

Increases highlighted digit

Moves highlighter to left / Hold to delete number

Decreases highlighted digit

Cancel without change

Moves highlighter to right / Hold to delete digit

Accept displayed value

Increases highlighted digit

Moves highlighter to left / Hold to delete number

Decreases highlighted digit

Cancel without change

Moves highlighter UP

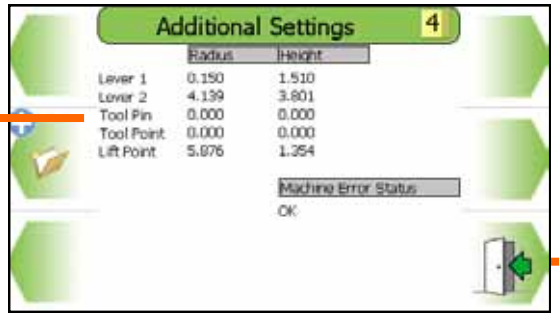
Accept highlighted time zone

Moves highlighter DOWN

15.3 Radius/ Height

Requires supervisor access rights.

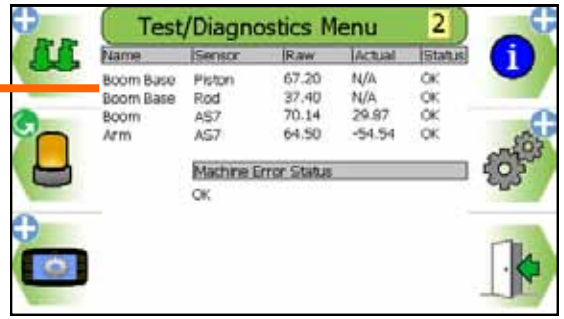
Lever 1 = Boom pivot pin
Lever 2 = Arm or hydraulically adjustable boom pivot pin
Lever 3 = Arm pivot pin
Tool Pin = Not used
Tool Point = Not used
Lift Point = Current lifting point



Exit to previous menu

15.4 Pressure Transducers

Boom Base PISTON - Full side
Boom Base ROD - Rod side



15.5 Safe Working Load

1) SWL Display Check.

Set the machine at a near maximum radius, match a point on the load chart and check that the displayed SWL matches the load stated on the load chart. This must be within+/- 5%. For triple articulated machines, the displayed SWL should be less than or equal to 5% of the SWL on the 'Max' load chart, and greater than or equal to 5% of the SWL on the 'Min' load chart.

2) Alarm Check.

With the machine on level ground pull on a fixed point via a load cell or use a known weight. Confirm that the alarm sounds at the correct points for SWL approach and Overload.

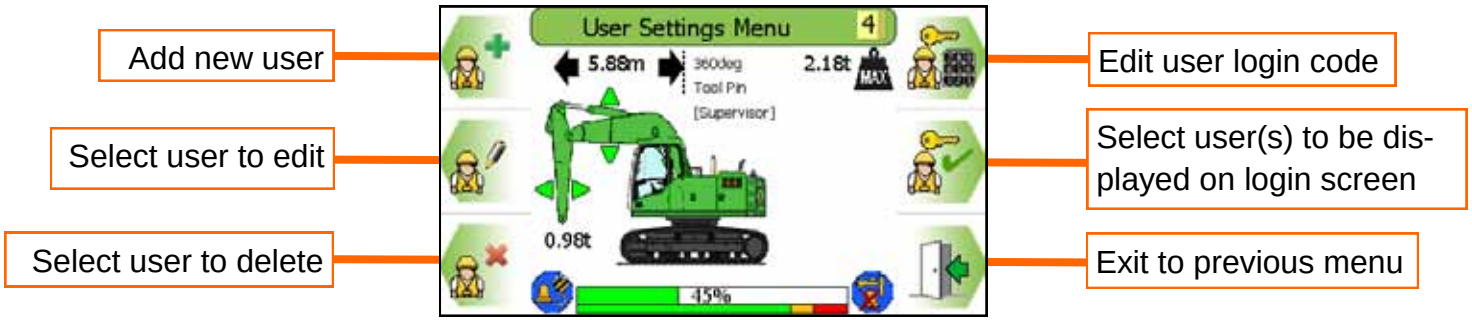
In this example for a SWL of 2.11t : SWL Approach = 2.11 x 0.95 = 2.00 T

Overload = 2.11 x 1.05 = 2.22 T

16 User Login

16.1 User Login Setup

Requires supervisor access rights.



16.2 Add New User

Requires supervisor access code

Toggle to / from keyboard

Moves highlighter to right

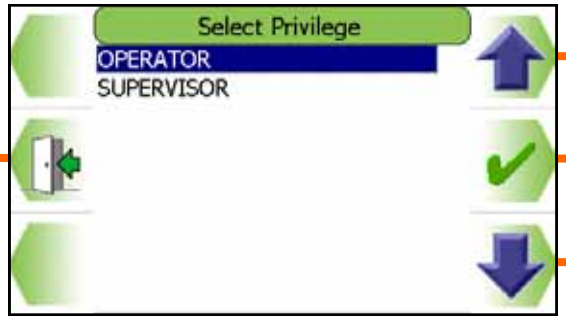
Accept displayed name

Highlight cross and press tick to cancel without

Increases highlighted number / Scroll up though digits/ letters

Moves highlighter to left

Decreases highlighted number / Scroll down though digits/ letters



Exit without change

Moves highlighter UP

Select highlighted Privilege

Moves highlighter DOWN

Cancel without change

Moves highlighter to right / Hold to delete digit

Accept displayed value

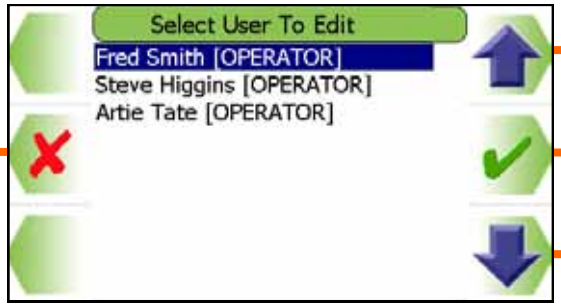
Increases highlighted digit

Moves highlighter to left / Hold to delete number

Decreases highlighted digit

16.3 Edit User Details

Requires supervisor access rights.

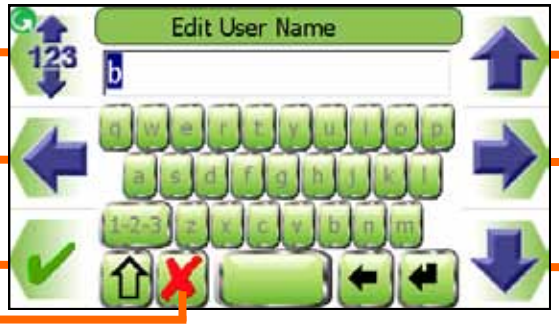


Cancel without change

Moves highlighter UP

Select highlighted user

Moves highlighter DOWN



Toggle to / from keyboard

Moves highlighter to right

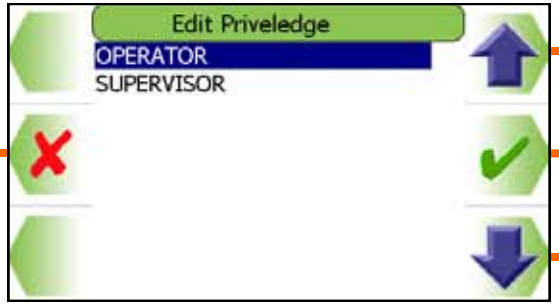
Accept displayed name

Highlight cross and press tick to exit without change

Increases highlighted number / Scroll up though digits/ letters

Moves highlighter to left

Decreases highlighted number / Scroll down though digits/ letters

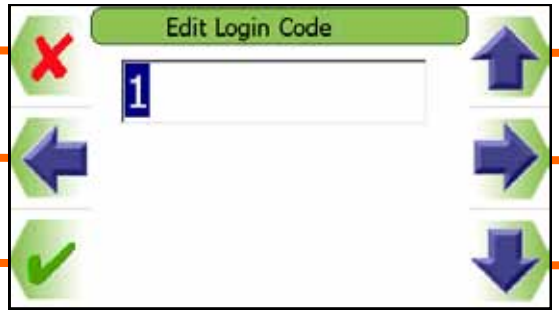


Return to previous screen

Moves highlighter UP

Select highlighted Privilege

Moves highlighter DOWN



Cancel without change

Moves highlighter to right / Hold to delete digit

Accept displayed value

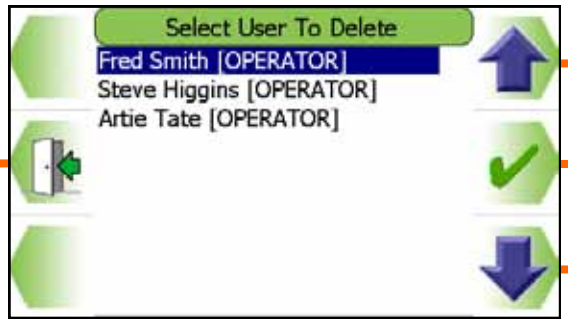
Increases highlighted digit

Moves highlighter to left / Hold to delete digit

Decreases highlighted digit

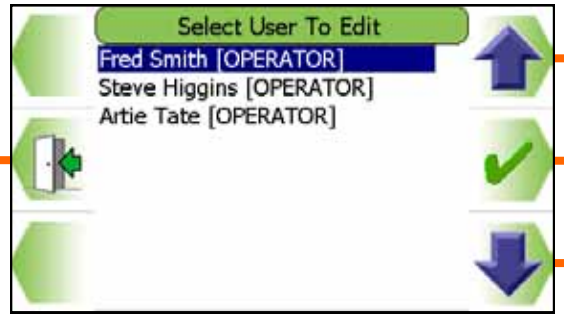
16.4 Select User to Delete

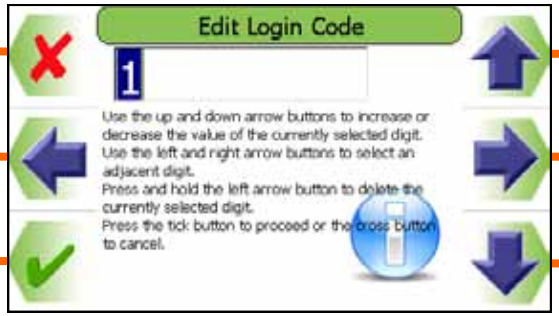
Requires supervisor access rights.



16.5 Edit User Access Code

Requires supervisor access rights.





16.6 Enable / Disable Users

Requires supervisor access rights

17 Repair

Once a repair has been carried out and tested, the following must be checked:

Required Checks	Section
Height and radius check	15.3
Pressure check	15.4
Duty Check	7.1
Relay Check	11.1
Alarm, LED and beacon Check	11.2
SWL check	15.5
Maintenance review	16.1

18 Definitions / Glossary continued

Definitions of words used to ensure understanding

SWL	Safe Working Load
LOH	Load on Hook
Duty	Lifting configuration
Tip	A tip is defined as: Idler rollers off the track (over the side), or rear idler rollers off the track when over the front on tracked machines and a tyre is clear of the ground on wheeled machines.
Hydraulic Limit	Maximum SWL limited by 87% of maximum hydraulic capacity rather than machine stability.
Pitch	Longitudinal base machine angle (fore / aft)
Roll	Lateral base machine angle (side to side)
Boom	First articulation connected to turret
Arm	Second articulation
Artic	Second articulation of a hydraulically adjustable boom (luffing boom, knuckle boom, two piece boom)
Turret	Section of machine above the undercarriage
Undercarriage	Section which the tracks/wheels attach too
Track	continuous band of treads, metal or rubber covered
Blade	heavy metal plate on the front of the machine, used for stability and moving material
Stabiliser	Hydraulically powered arms that can be lowered and raised to increase the Stability of the machine
Counterweight	Weight attached to the rear of an excavator to increase digging force and lifting capacity
Pivot pin	Point at which the articulations rotate about
Wheeled excavator	An excavator fitted with wheels
Tracked excavator	An excavator fitted with tracks, also known as
Bucket	Digging attachment
Attachment	Tool fixed to the dipper other than a bucket
Pressure transducer	Device to measure pressure within an hydraulic cylinder
Full side	Internal section below the cylinder rod face
Rod side	Internal section above the cylinder rod face

19 Definitions / Glossary

Relay	Electronic device to operate motion cut valve
SC	Safety Controller
MMI	Man Machine Interface (i.e. Display)
CAN cable	Cable connecting system components
Angle sensor	Sensor detecting current equipment angle
Motion Cut	Direct control of component hydraulic service
Power Supply	DC supply voltage
Ram	Hydraulic Cylinder
P/N	Part Number

562200-000, Issue1.1, April 2013

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