



AVID

## Installation and operating instructions for AVID XA+ Control Position Monitor for hazardous applications according product certification:



EPSILON 08 ATEX 2434X

Ex d IIB +H2 T\* Tamb -\*°C to +\*°C

Ex tD A21 IP6X T\*°C Tamb -\*°C to +\*°C

Beacon cover -30°C to +85°C (T4); -30°C to +75°C (T5); -30°C to +60°C (T6)

Environmental parameters: 80 kPa (0.8 bar) to 110 kPa (1.1 bar). Air with normal oxygen content, typically 21%.

### 1 Product description

The XA+ series valve control monitor has an integral solenoid coil that can be used with various solenoid configurations such a 3/2 and 5/2 way valves.

The XA+ also provides two methods of end of travel indication by the means of mechanical switches, inductive proximity sensors or proximity switches and an external visual indicator.

For applications that require position feed back, ancillary components such as a 4-20 mA current signal transmitter or a resistive signal feed back can be installed.

To allow this product to be used with network communication bus protocols, the XA+ series enclosure can house various network modules.

The XA+ series enclosure comprises of a two parts, a cover and housing. The housing can offer up to four of the following conduit entries; M20 x 1.5p, M25 x 1.5p, 1/2"-14 NPT or 3/4"-14 NPT cable entries for connection to an external power source via appropriate ATEX certified cable glands. The XA+ certification is compliant against the following standards:

EN 60079-0 : 2006	Electrical apparatus for explosive gas atmospheres – Part 0 - General requirements
EN 60079-1 : 2007	Electrical apparatus for explosive gas atmospheres – Part 1 - Flameproof enclosures 'd'
EN 61241-0 : 2006	Electrical apparatus for use in the presence of combustible dust – Part 0 - General requirements
EN 61241-1 : 2006	Electrical apparatus for use in the presence of combustible dust – Part 1 - Protection by enclosures 'tD'

**Note:** Before installation of this product, please ensure that the product and its certification is suitable for the intended application. If the equipment is likely to come into contact with aggressive substances, then it is the responsibility of the user to take suitable precautions that prevent it from being adversely affected, thus ensuring that the type of protection provided by the equipment is not compromised.

Installation of any cable entry devices, conduit entry devices or blanking devices shall not compromise the degree of ingress protection level IP6X for use in the presence of combustible dusts.

The unit has an ingress protection of IP66 / 67 and therefore any conduit device fitted must maintain this.

**Note:** These products have been certified with a cable entry temperature rise of 4°C. Ensure that this is taken into consideration when selecting suitable cabling for the ambient temperature in which the product is to be used.

**Note:** These products are not intended to be assembled directly to process pipe work etc that is heated or cooled to temperatures outside of the range as indicated above.



### Warning

Do not open when energised or when an explosive atmosphere is present.



### Warning

Electrostatic hazard, clean only with damp cloth.

## 2 Mounting instructions

- 2.1 The XA+ housing is assembled with the Pentair ModMount adapter (standard). To re-orientate the ModMount, if required, loosen and remove the four M8 socket head cap screws, position the bracket and replace the screws.
- 2.2 To ensure that the XA+ series drive coupler is orientated correctly, it may be necessary to stroke the actuator to the fully closed position.



### Warning

Before stroking the actuator to the fully closed position, please ensure that the process is safe to do so.

- 2.3 With the actuator in the correct position, attach the XA+ series bracket to the actuator using the hardware provided in the mounting kit.
- 2.4 To release the cover, loosen the cover retaining screws. Twist the cover approx 45° and lift up. See Fig 1.
- 2.5 To set the switches, stroke the actuator to its close position, lift the bottom cam and turn until the switch has activated and then release. The spring will push the cam back onto the splined shaft.



### Warning

Before stroking the actuator, please ensure that the process is safe to do so and that all hands are kept away from the moving shaft.

- 2.6 Stroke the actuator to the open position. Set the top cam by pushing down and turning the cam until the switch is activated.



### Warning

Before stroking the actuator, please ensure that the process is safe to do so and that all hands are kept away from the moving shaft.

- 2.7 Stroke the actuator from one end of stroke to the other several times to check the switch operation. If the switches require adjustment, repeat steps 2.5 to 2.7.
- 2.8 Replace the housing cover and secure the (4) captive screws. Confirm that you have noted the final position of the valve (full open or full closed).

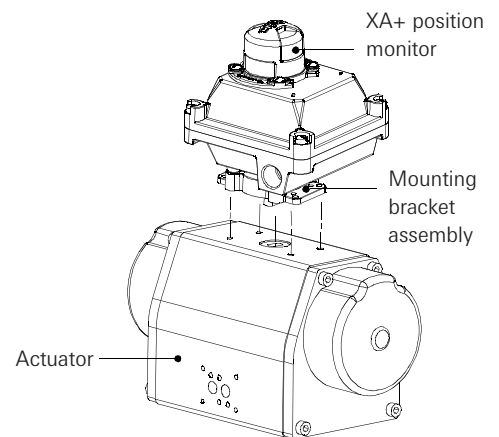


Figure 1

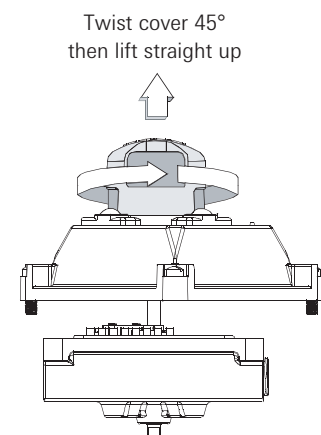


Figure 2

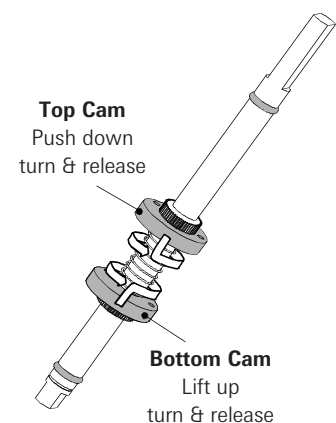


Figure 3

### 3 Field wiring & installation

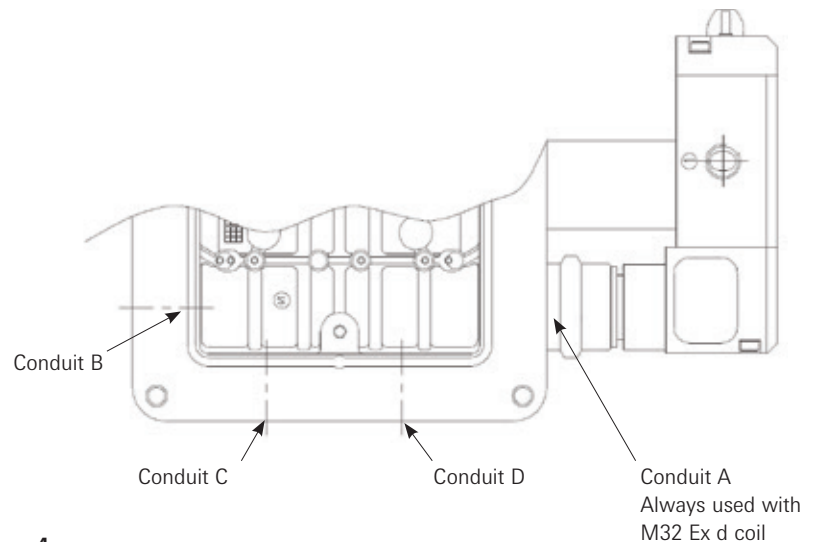


#### Warning

The XA+ series should always be handled with care when the cover is removed and wired to electrical power source.

**Note:** Before electrical installation, please read and follow the wiring diagram located inside the cover. The electrical ratings can be found on the product I.D label.

- 3.1 Field wiring must be carried out in accordance with site, local and national electrical codes / requirements. This includes special attention to earth bond to the aluminium enclosure using the internal and external earth points provided.
- 3.2 Installation of this product shall be carried out by competent personnel in accordance with the applicable code of practice such as EN60079-14.
- 3.3 The XA+ position monitor housing can offer up to three of the following conduit entries; M20 x 1.5p, M25 x 1.5p, 1/2"-14 NPT or 3/4"-14 NPT. These entries are detailed on the product I.D label found on the product cover. Please see Fig. 4 for conduit positions.



**Figure 4**

- 3.4 The certification applies to equipment without cable glands. When mounting the flameproof enclosure in the hazardous area, only suitably rated IP 66 / 67 ATEX certified flameproof glands must be used.
- 3.5 All unused cable entries must be plugged with a suitably rated IP 66 / 67 ATEX certified blanking devices.
- 3.6 The XA+ is available with a selection of switches and sensors.

Mechanical V3 SPDT switches	15 A - 125 or 250 V AC; 0.5 A - 125 V DC; 0.25 A - 250 V DC
Mechanical DPDT switches	10 A - 125 or 250 V AC; 10 A - 28 V DC; 0.2 A - 125 V DC
Proximity T-switch	1 A - 250 V AC; 2 A - 120 V AC or 1.5 A - 24 V DC
Inductive Proximity Sensors	Various inductive proximity sensors that can be assembled into the Ex d enclosure.
CS 4-20 mA Transmitter	Various switches / sensors option can be assembled with transmitter. The CS Transmitter electrical ratings are – current loop 4-20 mA at 18 to 24 V DC.
RS Transmitter	Various switches / sensors option can be assembled with transmitter. The RS Transmitter electrical ratings are – 1 K Ohms (standard).
Network Fieldbus Options	

### Netpak Fieldbus Option

### Electrical Parameters

AS-I Actuator Sensor Interface	24 V DC, 140 mA MAX
Device Net	24 V DC, 105 mA MAX
Foundation Fieldbus	9-32 V DC, 34 mA MAX
Modbus	24 V DC, 85 mA MAX
Profibus DP	24 V DC, 120 mA MAX

**Note:** The data signifies the maximum electrical rating of the product, suitable overloading protection must be provided to prevent these values being exceeded.

- 3.6 The XA+ is available with the following coil options:
- 24 V DC
  - 120 V AC
  - 240 V AC

- 3.7 The XA+ series enclosure. The table below details the applicable ambient ranges;

Cover Type	T Class	Ambient Range
Beacon	T6 (80°C)	-30°C - +60°C
Beacon	T5 (95°C)	-30°C - +75°C
Beacon	T4 (130°C)	-30°C - +85°C

- 3.8 Before replace the enclosure cover, ensure that both of the housing and cover flange surfaces are clean and undamaged. Tighten the cover screws hand tight using a standard 6 mm A/F Allen key ensuring there are no gaps.

## 4 Product repair & service

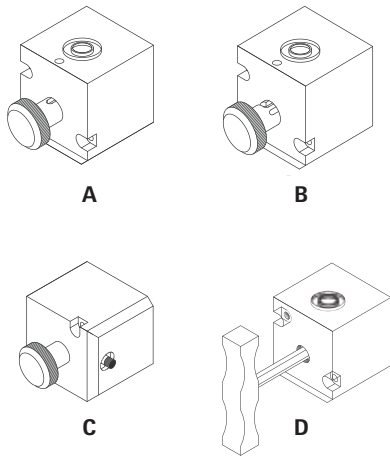
- 4.1 Inspection of this product shall be carried out by suitably trained personnel in accordance with the applicable code of practice such as EN60079-17.
- 4.2 In the event of any repairs that may be required such tasks must be carried out by suitably trained / competent personnel in accordance with the applicable code of practice such as EN60079-19.
- 4.3 The certification of this product has been approved based on the material of construction as per the drawings listed in the schedule within this certificate. Any replacement parts that are not made in accordance to the listed drawing will invalidate the approval / certification.
- 4.4 Replacement parts must be purchased through Pentair Valves & Controls or via an approved Pentair Valves & Controls distributor.

## 5 Operating and maintenance instructions for Falcon II solenoid valve

- 5.1 General description

- 5.1.1 The Falcon II solenoid valve incorporates elastomer static seals through which a shaped spool moves and are manufactured for 3 or 5 way operation. 3 way is normally used for pilot control of the other relay valves or for the operation of single acting cylinders. 5 way is normally used to control the action of double acting cylinders. 3 way operation is realised by blocking output 4 with a plug.
- The seal spacer assembly forms individual annular chambers opposite each valve port and the grooved spool either closes or allows flow between adjacent chambers, hence the position of the spool determines which ports are open or closed.

The spool is moved by way of a manually or mechanically operated mechanism normally against a return spring. Operation may be by application or removal of a pilot air supply acting as a pilot piston. This form of control is utilized for electrical actuation where integral solenoid valves control the pilot air supply.



**Figure 5**

## 5.1.2 Optional features - Falcon II

### 5.1.2.1 Momentary Override

Spring return momentary push type, must hold in to actuate. See Fig. 5A

### 5.1.2.2 Manual Locking Override

Manually depress palm button and rotate clockwise for maintained condition, must manually disengage to return to original position. See Fig. 5B

### 5.1.2.3 No-Voltage Release (Latching)

With the coil first energized, the palm button is then manually moved and latched. The inward movement of the palm button causes the valve to shift.

When the coil is de-energized, the palm button and latching mechanism are automatically tripped, allowing the valve to return to its original position. See Fig. 5C

### 5.1.2.4 Hex Drive Maintained Override

Insert Allen key in hex head screw and rotate clockwise (4-5 turns) to shift spool. Valve will stay put until hex head screw is rotated counter clockwise (4-5 turns) back to original position. See Fig. 5D

## 5.1.3 Specifications

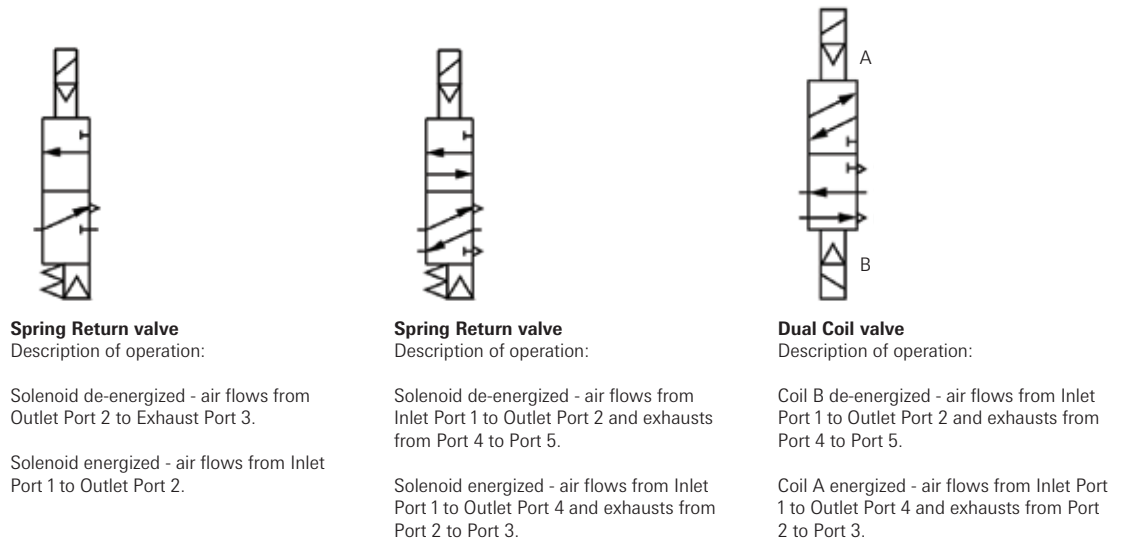
Operating pressure: 45 - 120 psig / 3.1 - 8.2 bar

Operating media: Non lubricated filtered air to 20 microns

## 5.1.4 Field wiring

Complete the electrical wiring in accordance with national and local electrical requirements.

The ground wire should be secure under the green screw. Check all screws for tightness.



**Figure 6** - Air Line Designation, 1/4" NPT or BSP air ports for inlet, outlet and exhaust

## 5.1.5 (Air line) Installation considerations

Air mains and lines should be large enough to avoid excessive pressure loss under conditions of maximum flow. Air lines should be installed with as few restrictions as possible if the cost of compressed air is to be kept to a minimum. Sharp turns in piping should be avoided for more efficient air flow and economical air power. It is advisable to pitch the mains in the direction of air flow so that both gravity and air flow will carry the water to traps or water legs located at frequent intervals.

To help in preventing condensed moisture from reaching the point of usage, down pipes should never be taken directly from the bottom of air pipes or mains. Connection should be made at the top of the main and a long radius return bend used.

### 5.1.6 Air flow

Pipe sizes are normally determined on semi empirical lines, basis for selection being an acceptable pressure drop e.g. not more than 10% of the applied pressure. In sizing pipes, consideration should be given to likely future demands, as a system will be inefficient if the demand outgrows the supply. It is always better to over size mains as this will reduce air velocity and make water separation more effective.

### 5.1.7 Air service equipment

The importance of proper filtration (20 micron) and lubrication of the air supply to pneumatic equipment can never be over-emphasized as a means of decreasing friction and preventing corrosion and wear due to moisture and abrasive solids being present in the air supply.

At higher pressures than recommended, pneumatic equipment can wear excessively with no significant increase in output and compressed air is consequently wasted.

There is much to be gained, therefore, from providing pneumatic equipment with serviced air by including suitable air line filters, pressure regulators and lubricants in the installation.

### 5.1.8 Tubes and fittings

The use of copper, stainless steel, nylon or polyethylene tube is recommended for piping up air circuits and equipment. As a general rule, pipe threaded fittings should not be assembled to a specific torque because the torque required for a reliable joint varies with thread quality, port and fitting materials, sealant used, and other factors. The suggested method of assembling pipe threaded connections is to assemble them finger tight and then wrench tighten further to a specified number of turns from finger tight.

The assembly procedure given below is for reference only, the fitting should not be over tightened for this will lead to distortion and most likely, complete valve failure.

1. Inspect port and connectors to ensure that the threads on both are free of dirt, burrs and excessive nicks.
2. Apply sealant/lubricant or Teflon tape to the male pipe threads. With any sealant tape, the first one or two threads should be left uncovered to avoid system contamination.
3. Screw the connector into the port to the finger tight position.
4. Wrench tighten the connector approximately 1 - 2 turns (to seal) from finger tight. again this is only reference – the fitting should NOT be over tightened.

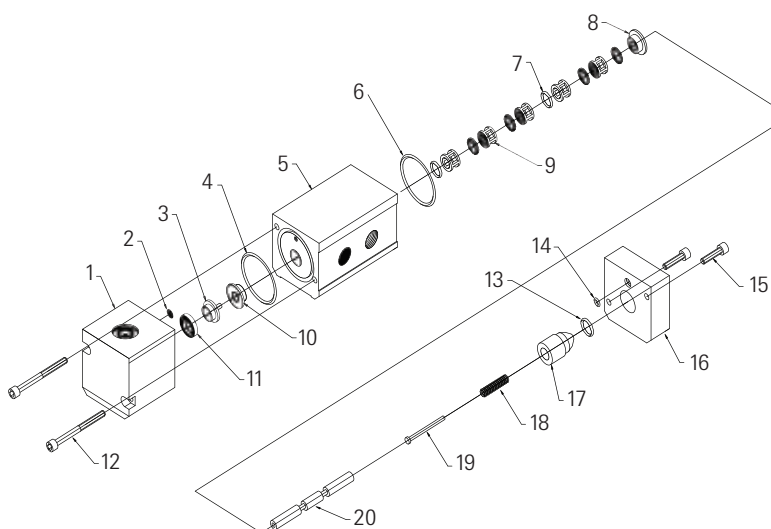


Figure 7

## Parts list

## No. Part Name

1. Pilot piston end cap	V5243
2. O-Ring	OZOIN070/00125
3. Pilot piston	V5119
4. O-Ring	OZOIN070/01062
5. Valve body	5/2 V5246 5/3 V5314
6. O-Ring	OZOIN0070/01062
7. O-ring	5/2 V5042 6 off 3/2 V5042 4 off
8. Bush	V5084
9. Spacer	5/2 V4734 5 off 3/2 V4734 3 off
10. Bush	V5084
11. Pilot piston seal	V4163
12. Cap screws	OSMO4KS40
13. O-ring	OZOIN010/0130
14. O-ring	OZOIN070/00125
15. Cap screws	OSMO4KS16
16. Spring end cap	V5244
17. Tell-tale cover	V5247
18. Spring	V4571
19. Tell-tale pin	V5026
20. Spool	5/2V5212 3/2 V5313