

User manual

GSP421 En



Engineered for life

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1 Introduction

This manual is general for the global standard family. Note! Some paragraphs are specific for special programs. These paragraphs have a program note after the headline or within the text. The pictures are only examples.

This is an ITT Flygt RTU (remote terminal unit) for the control and supervision of wastewater pumping stations equipped with one or more pumps. It incorporates

- powerful 32 bit processor
- data memory
- program memory
- alarm panel
- display, and
- level transmitter.

The RTU can be equipped with modems and a separate battery backup supply as options.

The RTU is equipped with

- parameter-controlled functions for pump control
- alarm functions
- operating statistics
- performance monitoring, and
- communications with the central system and/or Paging system.

1.1 Menus

The menus are grouped according to function. The first menu in each group also serves as a group header. There are three levels of menus:

1. User menu for reading the operating data. These menus are always visible.
2. Parameter menus for entering or changing the parameter values.
3. Service menus for the basic settings carried out by the service personnel.

1.2 Browse the Menus

Browse the menus according to this table.

What do you want to do?

Scroll backwards one menu at a time.

Press this button:



Advance one menu at a time.



Display the first menu in a submenu group.



Return to the last menu shown in the previous menu group.



1.3 Change a Parameter

Open parameter: Follow these steps to open any type of parameter for changing.

Step Action

1 Browse to the relevant menu according to the instruction above.

2



Press the OK button.

Result: A flashing cursor is shown in the display, telling that the change of parameter is allowed

Change: The numerical parameters can be changed position by position in the window menu. The parameters with text can only be changed by selection of alternatives.

Change the different parameters according to this table.

What do you want to do?

Press this button:

Back the cursor on the numerical parameter



Left arrow

Advance the cursor on the numerical parameter



Right arrow

Decrease one value on the numerical parameter, or advance among a set of alternative parameters with text



Down arrow

Back among a set of alternative parameters with text, or increase one value on the numerical parameter



Up arrow

Save or exit: Save or exit according to this table.

What do you want to do?

Save the changed value.

Exit the menu without saving the value.

Press this button:

Result: This table shows possible messages in the display after you have saved a value, and if you need to perform further action.

| Message | Description | Action |
|-----------------|---|-----------------------|
| Value stored | The value has been saved. | - - |
| Low value (xx) | The value is below the permissible range. | Enter a higher value. |
| High Value (yy) | The value is above the permissible range. | Enter a lower value. |

Reference: For more information about permissible range of value, see Appendix C- List of Menus.

1.4 Alarm panel

This section describes the standard function of the alarm panel. In some special programs the use of the alarm panel may be different.

Table: This table gives an overview of general led on the alarm panel, indicating the most common alarms.

| Led | Description |
|---|---|
|  | Overflow alarm. |
|  | Power failure. |
|  | High level sensor or float. |
|  | Low level sensor or float. |
|  | External pump alarms: Programs GSP2xx: Tripped motor protection. Programs GSP4xx: Tripped motor protection, water in oil, high temperature or pump switched off. Programs GSP2xx US: Tripped motor protection, high/low current, pump switched off or operation error. |
|  | Programs GSP4xx US: Tripped motor protection, water in oil, high temperature, pump switched off or operation error. |

| Led | Description |
|---|--|
|  | Water in oil. |
|  | High temperature. |
|  | Internal pump alarms: Programs GSPxxx: High/low current, high/low capacity, operation error, service and max starts. Programs CLCxxx: Operation error and service. |
|  | Programs GSPxxx US: High/low capacity. |
|  | Pump switched off. |
|  | Pump blocked or remote. |

Reference: For specific information about the led see 16.1 Alarm panel Led.

When an alarm is activated, the led flash until the alarm have been acknowledged.

Table: This table shows what the led signal.

| Signal from led | Alarm status | Description |
|--------------------|--------------|--|
| A steady beam | Active | The cause remains, acknowledgement has been performed. |
| Continues to flash | Passive | The cause is gone, acknowledgement has not been performed. |

Alarm Handling: Follow the instructions in this table when an alarm is activated on the alarm panel.

| What do you want to do? | Press this button: | Result/Comment |
|----------------------------------|---|---|
| Shift between remote local alarm |  | When remote is on, alarms will be transmitted to the central system, or a cell phone through SMS. |
| Acknowledge a new alarm |  | The alarm is not removed from the alarm log. |

Note! Acknowledgement with the button affects only the indication on the alarm panel, not the alarm in the alarm log or in the alarm buffer.

2 Start the RTU

Follow these steps to prepare for the start.

Step Action

- 1 Connect the RTU as described in the general installation instructions supplied with the unit. Reference: For description of signals, see 20 "Appendix F - Connection".
- 2 Complete the connection procedure by switching on the unit.

Result: A led on the front panel indicates the operational status of the unit.



Table: This table shows which light the led may have and what it means.

| Light | Meaning |
|--------------------|--|
| Steady red | The RTU is in service mode only. |
| Flashing red light | The pump control is not running. |
| Steady green light | Set points have been entered and the RTU is running. |

Operational status LED on front panel.

2.1 Personal safety



N.B.
Ensure that personnel cannot come in contact with live cabling or terminal blocks in the course of connection or service work. Maximum caution must be exercised when working on the digital outputs.

2.2 Configuring the RTU

The RTU requires certain parameters and set points to operate. It is supplied with a number of default settings, but some of the menus must be complemented or altered, beginning with the settings of a number of menus in the first menu group. Most of these can be entered from the central system. Reference: See 17 Appendix C - List of menus for a complete list.

Table: This table gives an overview of the menus that must be complemented or altered.

| Menu | Instruction/ Comment | See |
|---------------------------------|--|---|
| Display | Select "Service" to show all menus. | 3.1.1 Selecting visibility level |
| Language | Select the language to use in the RTU. | 3.1.2 Selecting language |
| Show functions | Step through this set point and select functions to use. Set all positions to "1" to show all menus. | 3.1.3 Selecting used functions |
| Inverse inputs | Select the digital inputs connected to the RTU that are "inverted" / active low. | 3.2.2 Inverting inputs |
| Select connected signals | Select signals connected to the RTU inputs and outputs. Note! These set-points are sensitive. Be careful to select the correct input and output or connected equipment may start unpredictable. | 3.2.3 Selecting input functions 3.2.4 Selecting output functions |
| Communication setup | Needed only if the station uses any type of communication, either to a central system or paging system. | |
| Station number | Must be unique to each RTU. Used by the central system to identify the unit. The number may vary from 1 to 899. | 3.3.2 Station number |
| Fixed line ID | Needed only if the communication uses a fixed line. | 3.3.3 Fixed ID number |
| Communication mode | The settings are necessary to get the RTU to communicate. Select the modem/method used to communicate with this station. Only change the setting for the used serial menu. | 3.3.4 Communication selections |
| DTE speed | Select the communication speed to the modem or other equipment. | 3.3.5 DTE speed selection |
| Protocol | Select protocol used. AquaCom, Comli, Modbus, CCom or GPRS AquaCom. Use AquaCom to the central system, AquaView. | 3.3.6 Protocol selection |

Other parameters for communication that may be required to be changed include various delays used in special communications like radio or GSM.

Table: This table gives an overview of the menus that must be complemented or altered for an RTU connected to GSP.

| Menu | Instruction/ Comment | See |
|--|---|------------------------------------|
| Starting up the pumps | This gets the pump control up and running, and sets up a rough control of the pumps. | |
| Level sensor | Select the range used by the level sensor. This is the only value needed to use the sensor if a normal level sensor is used. To get accurate flow and pump control, other set-points are needed. | 5.1.1 Level transmitter adjustment |
| Start and stop levels | Only these values need to be selected to start the pump control. | 7.1 Start and stop levels |
| Alarm distribution, precipitation measurement, pump operation, capacity measurement, etc. | It is optional to enter set-points for these functions and much more, depending on which RTU program is used. All these settings can also be entered from the central system. | Next chapter |
| Date and time | Note! Date and time is the most important setting. Enter time and date to start the RTU when all the other settings have been entered. | Next section |

2.3 Setting the time and date and commissioning the RTU control.

If the RTU is cold started

- it will not control and monitor the station
- the operating status led will be red and blinking and
- the menu showing date and time will only show question marks.

Instruction : Follow these steps to enter date and time.

Step Action

- 1 Press OK in the Date and time menu.
- 2 Edit the time and date.
- 3 Press OK to save the value, even if the original time and date is right.

Result: The operating status led changes to green and displays a steady light.

3 System functions

3.1 General

3.1.1 Selecting visibility level

In this menu you select if you want to see all menus or only the harmless read only menus. There are three levels of visibility.

| |
|------------------------------------|
| Display menu User |
|------------------------------------|

Showing only user menus.

The first is the user level and it is default. It will show only the result menus and some harmless menus.

| |
|---|
| Display menu Parameter |
|---|

Showing parameter menus.

The second is the parameter level. It will show all menus that you need to control the station including the user menus.

The third level is the service level.

| |
|---------------------------------------|
| Display menu Service |
|---------------------------------------|

Showing service menus.

Service mode allows you to change all setpoints in the unit. The service selection will return back to either parameter or user mode five minutes after the last use of the display.

3.1.2 Selecting language

It is possible to change the shown language in the RTU. This setting will also change the language used for alarm texts sent to the paging system.

| |
|-----------------------------------|
| Language English |
|-----------------------------------|

The language menu set to English.

3.1.3 Selecting used functions

This function shows and hides different menus in the application part of the RTU program. Here it is possible to hide menu functions that are not used in the current installation.

The menu is a binary menu showing the enabled functions.

```
Show functions
11111111100000
```

The menu to select showed functions.

Set the bit to zero to hide the menus for a special function.



N.B.

The functions will still work in the background. Remember to turn of a function before hiding the menus.

Available options depend on the program used.

| Option | Description | See |
|------------------|---|---------------|
| Person.+burglary | Personnel alarm and burglary alarm menus. | 4.3 and 4.4 |
| Currents+APF | Current analogue inputs and APF menus. | 5.2 and 7.4.2 |
| General analog | General analogue input menus. | 5.3 |
| Adv. Pump contr. | Advanced pump control menus. | 7.3 |
| Flush+vol. pulse | Flush valve and volume pulse menus. | 7.4.4 and 8.2 |
| Capacity | Capacity calculation menus. | 8.4 |
| Overflow | Overflow calculation menus. | 8.5 |
| Service larm | Service alarm menus. | 4.6 |
| Blocking in+out | Remote blocking, in and out, menus. | 9 |
| Energy | Energy calculation menus. | 10 |
| Counter | Counter menus. | 11 |
| Test alarm | Test alarm menus. | 4.5 |
| Timers | Timer menus. | 12 |
| Pump 2 Pump 4 | Pump 2, or 4, menus. This will make the RTU menus look like a one pump or three pump station. | |

3.1.4 Program information

3.1.4.1 System information

The system ID tells version number of the system program inside the RTU. Use this information to identify the program if you contact ITT Flygt service.

```
System: 3.51.00
ProgID: 12345
```

System and program identity menu.

3.1.4.2 Project number

The project number is used as information to identify the station and program when you contact ITT Flygt service. Do not change the number.

3.1.5 Program mode function

The program mode function is used when maintaining the RTU. It is possible to restart the RTU, start remote service and load/save set-points.

3.1.5.1 Run mode

| |
|--|
| Program mode Normal run |
|--|

Run mode changeable from AquaView.

It is possible change the run mode by sending the set-points from AquaView. This is sometimes very useful but it opens a security risk. To prevent the change of this menu set the run mode to Normal locked. This will prevent the possibility to cold start the RTU from remote but also prevent the possibility to use remote service. Other remote functions from AquaView are not affected by this menu.

| |
|---|
| Program mode Normal locked |
|---|

Run mode not changeable from AquaView.

It is still possible to activate remote service and cold/warm start the RTU if the menu is changed locally on the RTU.

3.1.5.2 Restarting the RTU

The program mode menu is used if a situation occurs in which the RTU must be cold or warm started. The command will not be done immediately when the menu is saved. It is possible to cancel the command by changing the menu again.

| |
|--|
| Program mode Warm start |
|--|

Warm starting the RTU.

Restarting will take 1 to 5 minutes depending on the program.

| |
|--|
| Program mode Cold start |
|--|

Cold starting the RTU.



| |
|---|
| <p>Remember that the set-points will be lost and must be re-entered following a cold start.</p> |
|---|

3.1.5.3 Remote service

Remote service of the RTU is possible if the RTU is called. This includes loading a new program over the telephone line.

```

Program mode
Remote load COM3

```

Remote load on COM3.

Select the COM port to be used in the program mode menu. Note! The RTU will not control the station during remote service.



The service must be done by qualified personnel.

3.1.5.4 Save/load set-points

It is possible to save and load set-points to a file in the RTU. Use this function to protect the set-points from being destroyed in a cold start. Once you saved the set-points they will be used to start-up the RTU in a cold start. The cold-start will lose alarm, trend and report data, but not control parameters and the RTU will continue to control the station.

Set-points will be saved automatically at midnight if changed.

Another way of using this function is if you experiment with set-points and you want to be able to return to the original set-points. It is also possible to use this option if you want to copy set-points from one RTU to another but only, and this is important, only if the two programs are identical. The two programs have to have the same program ID.

```

Program mode
Save setpoints

```

To save the set-points.

Remember that when loading the set-points the program will assume the same logical state as when they were saved. If the save was done after a cold start then this command will be equal to a cold start and all set-points will be lost.

```

Program mode
Load setpoints

```

Loading set-points.



The load set-points does not work if the program is changed in service. If the program is changed the command may destroy the set-points or even crash the program. Use it carefully.

3.1.5.5 Save default set-points

It is possible to change the default values used by the RTU at a cold start-up. This may be used to create a regional variant of the set-points to make the installation easier.

```

Program mode
Save defaults

```

To save the default values.

To create a regional file first set-up the RTU with desired values. Next select the command and the RTU will create a file "Abackup.IMG". This will contain all

set-point values. Download the file to your PC and use this file in the installation of future RTUs.



It is extremely important that the file is installed in the exact same program with the same program ID otherwise the RTU may crash.

3.1.6 Password

Two password menus are included in the RTU to prevent unauthorised personnel from altering settings in the RTU. The function is activated by entering the appropriate four-digit code in the New password menu. When an operator wishes to alter a setting in any menu using the buttons on the front panel, the code must first be entered before the data can be changed.

Enter password
0

This is the password menu that appears if the password is activated.

To turn off the password function, enter 0000 as a new password.

Remember that unauthorised personnel must also be prevented from changing settings from the central system to ensure full protection against unauthorised alterations.

3.2 Physical setup

The programs use flexible inputs and output digital signals which allow the user to select input polarity and function for most of the signals.

These settings are required to get the RTU to work with external equipment.

3.2.1 Viewing inputs

It is possible to view the status of the digital inputs connected to the RTU.

Status inputs
0100100000000000

Inputs 2 and 5 activated.

Switch the menu input to write mode to get a description of the individual inputs. Many of them may however be general inputs.

3.2.2 Inverting inputs

Closed contacts normally activate the digital input signals. The signal function can be inverted in the menu if input is to be activated by open contacts.

Inverse inputs
0000100010000000

This is the invert inputs menu with two inputs inverted.

The inversion of input signals is only possible on inputs directly connected to the RTU. Inputs connected to Siox units cannot be inverted. In this case use an intermediate relay.

3.2.3 Selecting input functions

Some inputs in the program are selectable. The possible options on an individual input depend on position and program. See 20 “Appendix F - Connection” for more information about your program.

The input functions and a short description of the function are included in the table below. See individual function descriptions for more information.

Available options depend on the program used.

| Input function | Description | See |
|-----------------------|---|-------------|
| Not used | The input is not used. Connected signal will be ignored. | |
| Spare alarm | A spare alarm is created on the input. The alarm code depends on connected input. | |
| Px Tripped motor | Pump tripped. This input will create an alarm and stop the pump. | |
| Px Off switch | Pump turned off. This will stop the pump and prevent the program from starting it. | |
| Px Leakage | Leakage alarm. This will normally not stop the pump. | |
| Px High temp. | High pump temperature alarm. This will stop the pump. | |
| High float | High level float. This function gives an alarm and may also start the pumps. | 7.2.1 |
| Low float | Low level float. This function stops the pumps and gives an alarm. | -“- |
| Overflow sensor | Overflow sensor input. This will start the overflow calculation. It is possible to use the level sensor to trigger the overflow but with lower accuracy. To do this make sure the overflow input is not used. | 8.5 |
| Power fail | Power fail sensor. This will stop the pumps. | 4.2 |
| Intruder sensor | Intruder sensor or switch. This input will cause the intruder alarm. | 4.4 |
| Personnel onsite | Personnel on site input. This will activate the personnel on site protection function. | 4.3 |
| Intruder + personnel. | Personnel on site combined with intruder sensor. It is possible to combine these two inputs to save one input. | 4.3 and 4.4 |
| Block remote | Signal to block a remote station using dialled or fixed line. | 9.1.1 |
| Energy pulse | Energy pulse counter input. | 10.2 |
| Counter pulse | General pulse counter. May be connected to a rain sensor. | 11 |
| Timer x | General timer input. Used to create various timer functions | 12 |

| Input function | Description | See |
|-----------------------|--------------------------|------------|
| | together with an output. | |

3.2.4 Selecting output functions

Some outputs in the program are selectable. The possible options on an individual output depend on position and program. See 20 “Appendix F - Connection” for more information.

The output functions and a short description of the function are included in the table below. See individual function descriptions for more information.

Available options depend on the program used.

| Output function | Description | See |
|------------------------|--|-------------|
| Not used | The output is not used. Connected signal will be low. | |
| High level | Activated by a high level alarm. | 5.1.3 |
| Extrem high lev. | Activated by an extremely high level alarm. | -- |
| Low level | Activated by a low level alarm. | -- |
| Extrem low lev. | Activated by an extremely low level alarm. | -- |
| Generic analog x | The output is controlled by the generic analogue signal. | 5.3.4 |
| Remote blocked | The output is activated when the RTU gets remote blocked by another RTU. | 9.2.2 |
| Alarm pulse | One pulse on every new alarm. | 3.5.3 |
| Alarm status | Shows the status of alarms. Low – no alarms, pulse – active not acknowledged alarms, high – active alarms. | -- |
| Alarm active | Shows if there are any active alarms. | -- |
| Flush valve | The output is activated by the flush valve function. | 7.4.4 |
| Timer x out | Activated by the Timer functions. | 12 |
| Watchdog | The output is high when the program has set-points and runs properly. | |
| Remote x | The output is controlled by the user from status. | |
| Buzzer | The output is used by intruder alarm and personnel functions. The buzzer is activated to inform the user when the alarms is turn on/off and when working time has expired. | 4.3 and 4.4 |
| Siren | Intruder alarm or personnel alarm. Connect to a siren. | -- |
| Buzzer+siren | Buzzer and siren combined. | -- |

| Output function | Description | See |
|-----------------|---|-----|
| Volume pulse | One pulse for each amount of outflow/inflow/overflow volume. | 8.2 |
| Modem reset | If a communication problem is detected, this output is used to switch the power on/off for the modem. | |

3.3 Communication setup

The RTU can communicate with the central station and paging systems in several different ways. Select communication function depending on connected equipment and desired function.

The programs are equipped with a very flexible communication set-up. It is possible to connect various modems and use several protocols.

These settings are only required if the RTU should communicate. A stand alone RTU does not require any changes in this section.

3.3.1 Communication status led

Underneath the display of the RTU there is a symbol of two telephone handsets with a communication status led.



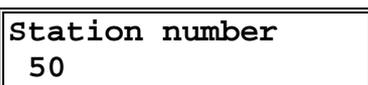
Communication status led.

Table: This table shows the different lights of the communication status led and what the colours mean.

| Colour | Description |
|--------|------------------------|
| Green | The RTU receives data |
| Red | The RTU sends out data |

3.3.2 Station number

To enable the central system to contact the station and get the status data for the picture you have to enter the correct station number. This number has to be the same as in the central system.



This is the station number menu.

Valid station numbers range from 1 to 899.

3.3.3 Fixed ID number

To connect the RTU on a fixed line the Fixed line ID need to be entered otherwise the communication will not work. This number needs to be the same in the AquaView system.

| |
|--|
| ID number fixed 0 (fixed) |
|--|

The fixed line ID.

3.3.4 Communication selections

In the communication menus the following selections are available.

| Serial menu | Alternative | Function and description | DTE speed |
|----------------|--|---|--------------------|
| COM1 | Not used | No equipment on COM1. | |
| | TD22 V22 | External TD-22 working in V.22 mode. | 1200-4800 |
| | TD22 V.22bisLAPM | External TD-22 working in V.22bis mode with compression and error correction. | 1200-4800 |
| | TD22 V23 dial. | External TD-22 working in V.23 mode. | 1200 |
| | (TD22 V23 fix.) | Not recommended*. External TD-22 working in V.23 fixed mode. | 1200 |
| | TD33 V.90 | External TD-33 working in V.34 mode. | 4800-38400 |
| | TD33 V.90 X1 | External TD-33 working in V.34 mode. No busy tone detection. | 4800-38400 |
| | TD33 V.90 LAPM | External TD-33 working in V.34 mode with compression and error correction. | 4800-57600 |
| | RS232 half dup. | RS232 half duplex. | 300-57600 |
| | RS232 full dup. | RS232 full duplex. | 300-57600 |
| | Siox RS232 | External Siox driver K32. | Only 4800 or 19200 |
| | Alarm printer | Alarm printer. ASCII protocol. | 1200-57600 |
| | User def. 0 | User configuration 0 defined in modem. (AT Z) | 300-57600 |
| | User def. HDX | User configuration 0 defined in modem working in multi-drop mode for V.23. (AT Z) | 300-57600 |
| Factory set. 0 | Modem factory configuration 0. (AT &F) | 300-57600 | |
| User def. 1 | User configuration 1 defined in modem. (AT Z1) | 300-57600 | |

| Serial menu | Alternative | Function and description | DTE speed |
|-------------|-----------------|--|--------------------|
| | Factory set. 1 | Modem factory configuration 1. (AT &F1) | 300-57600 |
| COM3 | Not used | No equipment on COM1. | |
| | RS232 half dup. | RS232 half duplex. | 300-57600 |
| | RS232 full dup. | RS232 full duplex. | 300-57600 |
| | Siox RS232 | External Siox driver K32. | Only 4800 or 19200 |
| | Alarm printer | Alarm printer. ASCII protocol. | 1200-57600 |
| | User def. 0 | User configuration 0 defined in modem. (AT Z) | 300-57600 |
| | User def. HDX | User configuration 0 defined in modem working in multi-drop mode for V.23. (AT Z) | 300-57600 |
| | Factory set. 0 | Modem factory configuration 0. (AT &F) | 300-57600 |
| | User def. 1 | User configuration 1 defined in modem. (AT Z1) | 300-57600 |
| | Factory set. 1 | Modem factory configuration 1. (AT &F1) | 300-57600 |

3.3.4.1 Modem TD-22

Use one of these settings if the RTU is delivered with the Westermo TD-22 modem. Select V.23 when the modem shall communicate with CCC0502/0503 modems. Select V.23 fixed when the modem shall communicate with CCD0502/0503 or other TD-22 modems on a fixed line. V.22 should be used to communicate with other Hayes modems.



Using TD-22 in V.23 mode is not recommended. The modem is initialized by the RTU and this fixed mode cause the possibility to initialize the modem again to be lost. If the modem loose power the communication is lost. It is therefore highly recommended to connect the TD-22 modem to the same power supply as the RTU if this communication mode is used. This will cause the modem to be initialized safely. A better method is to set the TD-22 modem to V.23 mode using the DIP switches inside the modem and use RS232 half duplex as communication mode.

3.3.4.2 Modem TD-33

Use one of these settings if the RTU is supplied with the TD-33 modem.

| |
|--|
| Communic. COM1 TD33 V.90 X1 |
|--|

Communication selected to TD-33 using option X1.

The option TD33 X1 is used when the modem has problems to detect the telephone system dial tone.

3.3.4.3 Modem TD-23

Use the option for RS232 half duplex if the modem TD-23 is used. Set speed to 1200 bit/s.

3.3.4.4 RS232 full duplex

Use this option for point to point communication on a fixed line cable together with Mtc-Com, AquaView or GPRS AquaCom. A null modem or a special null modem cable should be used in this communication.

This option is also used for modems emulating a RS232 line using control signals. This is the preferred option for using modem TD-22 in V.23 fixed mode.

3.3.4.5 RS232 half duplex

Use this option for multi-drop communication using TD-22 or TD-23 on a fixed line cable together with Mtc-Com or AquaView.

3.3.4.6 User defined modems

It is possible to connect other modems to the RTU. In this case the modem needs to be configured using a PC before installation. The configuration should be saved in the internal memory area 0 inside the modem using the command "AT E0 V0 &W0". The modem will then later on be initiated with the command "AT Z" to recall the saved configuration. See separate documentation for specific modems.

| |
|--|
| Communic. COM4 User def. multid |
|--|

Communication selected to a user defined multi-drop modem on COM4.

It is possible to run the user defined modem in either multi-drop mode or point-to-point mode. Multi-drop mode is used for fixed line modems.

3.3.4.7 Alarm printer

The alarm printer is connected to COM1 usually with 1200 bps. Use 8 bits 1 stop bit and no parity in the printer. Used character table is "MS-DOS 850".

3.3.4.8 Other information on modems and connections

The line speed depends on the initiation string, line quality and DTE speed. Changing the DTE speed will not always change the line speed.

All modems besides PC card modems are connected to COM1. See the modem documentation for cabling specifications.

When the communication mode is changed then the RTU will automatically restart after a few seconds.

3.3.5 DTE speed selection

Select the DTE speed for the used menus. The DTE speed is the speed on the serial menu connected to the RTU.

| |
|--|
| Speed COM1 9600 bit/s |
|--|

DTE speed on COM1 selected to 9600.

If a modem is used this is the speed between the modem and the RTU. This is not the same as the line speed between the two modems.



| |
|---|
| <p>It is highly recommended that the DTE speed is equal or higher compared to the line speed.</p> |
|---|

3.3.6 Protocol selection

Select protocol to use on the serial menus.

| |
|---|
| Protocol on COM1 AquaCom |
|---|

COM1 selected to use AquaCom.

Supported options are:

| Menu option | Comment |
|--------------|---|
| None | No protocol used. Use this if Siox or alarm printer is selected. |
| AquaCom | AquaCom dialled or AquaCom fixed. Dialled or fixed mode is selected automatically depending on connected modem. |
| Modbus | Modbus fixed. |
| Comli | Comli dialled or Comli fixed. |
| Ccom | Ccom fixed. |
| GPRS AquaCom | AquaCom using GPRS. |
| Other | Other option. This will make the menu change to enter a protocol code. See protocol code below. |



| |
|--|
| <p>It is not possible to select two dialled serial menus working with the AquaCom protocol at the same time.</p> |
|--|

| Code | Function | Comment |
|------|---------------|---|
| 0 | None | Selecting this if you don't use any function. |
| 1 | Alarm printer | Alarm printer is connected. It is not necessary to select this option if alarm printer is selected as communication mode. |
| 2 | Service | It is possible to service the RTU using other com ports than |

| Code | Function | Comment |
|------|---------------------|---|
| | | COM2 using this option. |
| 3 | AquaCom slave | Same as menu option. |
| 4 | Modbus slave | Same as menu option. |
| 5 | Comli slave | Same as menu option. |
| 6-7 | | Not normally used. Used for master communication and others. |
| 8 | Siox | Siox is connected. It is not necessary to select this option if Siox is selected as communication mode. |
| 9-12 | | Not normally used. Used for master communication and others. |
| 13 | Ccom slave | Same as menu option. |
| 14 | | Not normally used. Used for master communication and others. |
| 15 | MAS Modbus Slave | Old method for communication with MAS. Not used. |
| 16 | Unpolled Fixed-line | Used for Radio or GPRS iConnector over AquaCom Central communication. |
| 17 | Modbus multi slave | Makes it possible to connect more than one Modbus slave. |
| 18 | GPRS AquaCom | Select this for AquaView Central communication over GPRS. |
| 19 | DNP3 | Used together with another SCADA system. |
| 20 | IEC60870-5 | Used together with another SCADA system. |
| 21 | Modbus dialled | Modbus in dialled mode. |
| 22 | IEC60870-5 dialled | Dialled version of number 20. |

3.3.7 Communication time-outs and delays

Avoid changing these values unless absolutely necessary. The communication may be unstable or cease to work if any of these values is set to a faulty value.

3.3.7.1 RTS delay

This is the time required by the modem to stabilise the signal before it starts to transmit data. In certain cases, the RTS delay must be changed to permit communications to work satisfactorily.

| |
|--|
| RTS delay COM1 200 ms |
|--|

This shows RTS delay set to 200 ms on COM1.

The RTS delay is also used in dialled up communication as a general delay between telegrams. In dialled communication it rarely need to be used and is set to 0 ms.



Operation may be put at risk if this value is too high. A suitable value is between 100 and 300 ms.

3.3.7.2 Time-out telegram

This setting controls how long the program will wait for an answer. A timeout may occur if a long time elapses before a response is received from the central system or another remote terminal unit. The response time in the menu can be increased to prevent this; however, it is recommended that this value (8 seconds) should not be changed unless absolutely necessary.

3.3.7.3 Time-out character

This setting controls how long the program waits for a new character. In some applications where messages are sent in packages it can be gaps. This concern particularly radio communication where you can get time-outs. To avoid them increase the value in this menu.

3.3.7.4 Delay before sending OK

This is the time the program waits from starting a modem communication until sending the first OK message. In special situations where radio modems are used it may be necessary to increase this value if the communication line is not ready directly.

3.3.7.5 Modbus delay

Delay between telegrams in Modbus and Comli, master and slave.

3.3.7.6 Time-out Modbus

Delay after each telegram if an answer from slave is not detected from the RTU.

3.3.8 Max telegram size

It is sometimes necessary to reduce the size of the telegrams sent between the RTU and the CS, especially if radios are used. It is possible to set the size of some of the telegrams using this function.

**Max telegram
size 2000 byte**

Telegram size set to default value.

3.3.9 Trend sample

3.3.9.1 Sample time

The RTU continuously samples trend data like levels, flows and currents. The sample rate of this data may be changed in one minute intervals between 1 and 30 minutes. The default sample rate is 5 minutes.

**Trend sample
time 1 min**

Sample rate set to one minute.

If the sample rate is changed to one minute the same change has to be done in the set-up of this station in AquaView. A zero in this menu will work as the default value, five minutes.

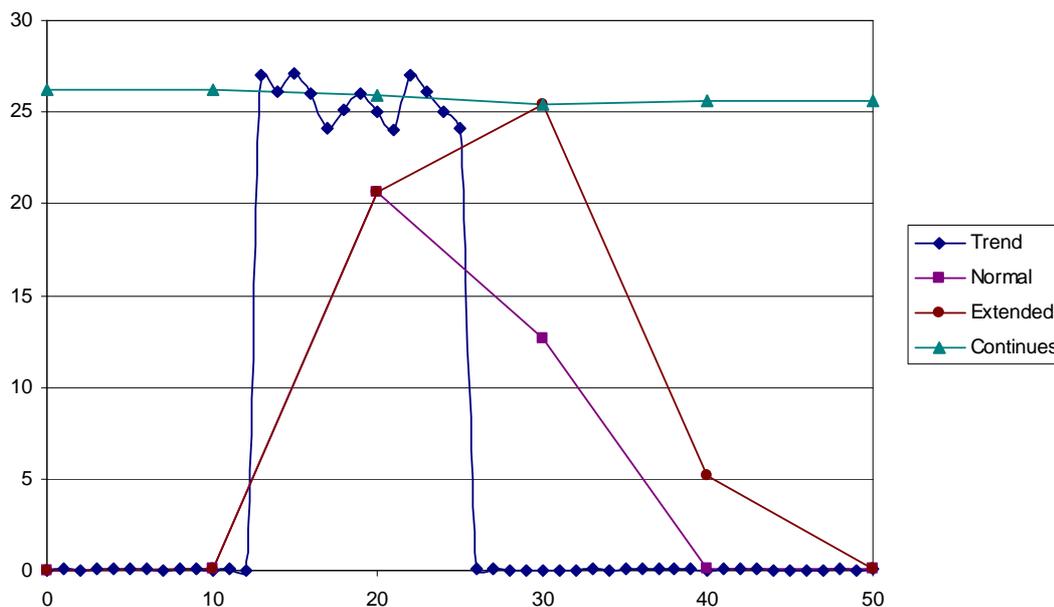
3.3.9.2 Sample method

The way trends are sampled in the RTU may be changed. In some stations with rapid pump-cycles even changing the trend sample rate to one minute may be too long. In this case it is possible to extend the sampled trend in two ways.

**Trend method
Extended**

Extending the trend.

This function changes the sampling of trend values that are dependent on pump operation. Affected trends are: Pump currents, pump flow, energy effect and specific energy.



Resulting trend curves in AquaView.

- Normal Trend is sampled 10 times during the selected time. The average is calculated and shown in the resulting trend.
- Extended The trend is sampled during the pump operation. The average value is used to extend the stored trend. The resulting trend will be guaranteed to show at least one sample with the true maximum value.
- Continues The trend is sampled during the pump operation. The average is used to store trend during non pump operation resulting in a continuous trend curve.

3.3.10 Remote control break delay

The pumps can be remote-controlled from the central system. The option of starting and stopping the pumps manually is available on the status picture. When remote control is selected, the RTU pump control function is inoperable. When a pump is started remotely, pump control returns to auto mode when the picture is closed. The remote control break delay prevents the RTU from setting the pump in auto mode after a closed picture. It is then possible to control the pumps remotely without the need of an open status picture.

| |
|------------------------------|
| Remote break 0 min |
|------------------------------|

The remote break delay default value.

A pump that is started with a remote command will always stop at the normal stop level or low level float. It will also stop on any pump failure. The pump will then return to automatic mode.

A pump that is stopped with remote command will stay stopped until the status picture is closed and the remote break delay is elapsed. The pump will then return to automatic mode and start as normal.



| |
|--|
| Care is always required when operating the pumps manually from the central system. |
|--|

See 19 "Appendix E - Central system" for information on all objects to be controlled remotely.

3.3.11 Response delay incoming call

This is the delay from the first ring signal to answer from the RTU.



| |
|---|
| Only set this time if the telephone line is also connected to a normal telephone. Setting this value in many stations will increase the data collection time in the CS. |
|---|

3.3.12 GPRS communication

GPRS communication works as follows:

1. RTU with GPRS modem establishes an Internet connection.
2. RTU connects to the AquaView Central server over Internet.
3. As long as the connection is kept alive, the RTU and AquaView Central server can communicate over Internet.

3.3.12.1 Keep the connection alive

To keep the connection alive, the RTU sends "I am alive" messages within a specified time frame. Try out different settings to find a suitable time frame. A value to start with is 210 s.

3.3.12.2 Configure GPRS communication

| |
|----------------------------|
| IP address ##### |
|----------------------------|

Enter the IP address for the AquaView Central Server.

Example:

If the address is “195 . 67 . 103 . 220”,
enter “195.67.103.220”.

| |
|--------------------------------|
| TCP Port number #### |
|--------------------------------|

Enter the TCP Port Number to the AquaView Central Server. Valid range is 0-65535.

| |
|-------------------------------------|
| Delay for Gprs msg #### s |
|-------------------------------------|

Enter the time frame for keeping the connection alive. Valid range is 0-86400.
Use 0 for default value (210 s).

3.4 General alarm information

The RTU may generate an alarm in different situations as part of pump station monitoring. The alarm may be due, for example, to the absence of an operating response, but may also be activated by internal monitoring functions. See 18 "Appendix D - List of alarms" for a list of the alarms in the RTU.

3.4.1 Active/passive alarm types

Two alarms are generated in most alarm situations; one when the condition is fulfilled i.e. when the alarm is activated, one when the alarm is passive. In a few alarm situations, the alarm is generated only when the condition is fulfilled. One example of this second type is the "Warm start" alarm.

3.4.2 Alarm priorities

An RTU alarm can be assigned one of four different priorities, A, B, C or D. In some special cases the alarm may also have priority E and H. In most cases, these are used as described below. The Alarm distribution menu described below determines the alarms that are to be transmitted.

| Priority | Shown in the RTU alarm log | Sent by RTU to central system or paging | Sent by central system to paging | Comment |
|----------|----------------------------|---|----------------------------------|---|
| A | Yes | Yes * | Yes | Is assigned to the most important alarms. |
| B | Yes | Yes * | No | Is assigned to those alarms which, although not as important, must be |

| Priority | Shown in the RTU alarm log | Sent by RTU to central system or paging | Sent by central system to paging | Comment |
|----------|----------------------------|---|----------------------------------|--|
| | | | | reported continuously to the alarm recipient. |
| C | Yes | No * | No | Usually assigned to those alarms that are only to be recorded locally in the RTU. |
| D | Yes | Yes * | Yes | Works as A alarms with the difference that they are transmitted to the pager only on work hours. |
| E | Yes | No | No | Is used by the RTU when the Local alarm mode has been selected. This priority is not selectable for individual alarms. |
| F | No | No | No | Used to hide alarms from showing up in the RTU. Usually used by programmers of the RTU but may be used locally on the RTU. |
| H | No | No | No | Is assigned to alarms working as events. This events is not transmitted automatically, they are instead collected as data. |

* The actual priorities transmitted to the central system or paging may be changed. See 3.6.3 "Alarm distribution, selecting alarms for transmission".

See 18 "Appendix D - List of alarms" regarding alarm priorities following a cold start.

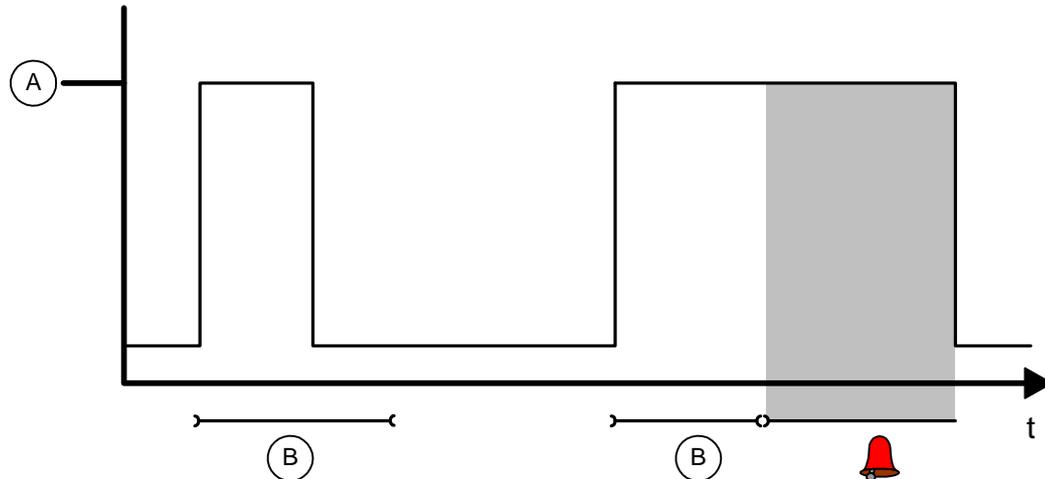
It is possible to change the alarm priority and alarm code locally on the RTU. See 3.6.6 "Changing alarm code and priority".

3.4.3 Alarm activation

Most alarms are in service directly when the RTU is commissioned. The monitoring of analogue values requires alarm limits to be entered for them. The various alarm limits and their respective functions are described in other parts of this document.

3.4.4 Alarm delay

Each alarm can be delayed for a period during which the alarm condition shall be fulfilled before the alarm is generated. A delay is used to 'filter out' disturbances of a temporary nature in the system. No general rule can be given regarding a suitable delay since the setting will be dependent on the plant configuration. However, approx. 10 seconds is a normal setting.



A = Alarm condition present B = Alarm delay

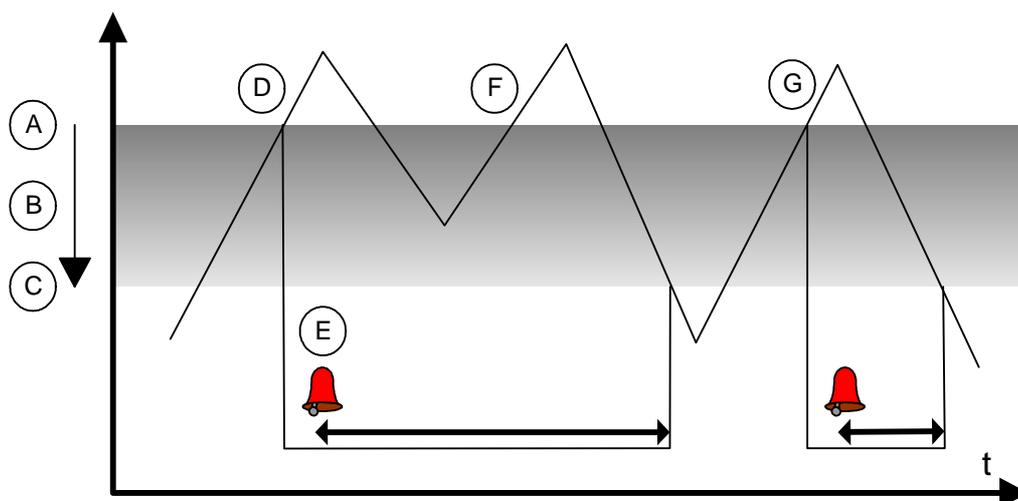
Typical alarm delay

In the above example, an alarm is not generated on the first occasion since the alarm condition is not present for long enough. However an alarm is generated in the second case since the alarm condition is still present when the delay period expires.

ITT Flygt RTU's can be set with different delays for general alarms, high level alarm, low level alarm as well as power failure alarms. If a central system is installed, alarm delays can also be set by means of the central system set point function.

3.4.5 Alarm hysteresis

Alarm hysteresis is another method of filtering out undesired, superfluous alarms. Hysteresis, which is applied to analogue alarm limits, specifies the amount by which the measured value must change for an alarm to be deactivated.



Example of high level alarm with hysteresis and alarm delay.

In the above example, the High level (A) alarm is subject to a limit. The shaded area (B) shows the hysteresis range. If an alarm occurs, the level must fall below the lower hysteresis limit (C) before it can be repeated. The alarm condition is

fulfilled at (D), although the alarm itself is generated a little later (E) since it is normally subject to a delay. The alarm remains active while the level remains in the shaded, hysteresis area. Thus, a new alarm is not generated at (F), even though the level has again risen above the high level limit, since it has not fallen below the lower hysteresis limit in the interim. However, at (G), the alarm condition is again fulfilled and an alarm is generated after the specified delay.

Hysteresis operates in similar manner for a Low level alarm. In this case, the level must exceed the upper hysteresis limit before the alarm can be repeated.

The alarm hysteresis is set via menus in the appropriate group menu and can also be set from a central system.

3.5 Local alarm functions

This chapter describes how alarms are used on the RTU locally.

3.5.1 Alarm logging

An alarm generated when the alarm condition is fulfilled is recorded in the alarm log, which accommodates at minimum 100 alarms. If a greater number of alarms are generated, the earliest alarm will be overwritten. You can view the alarm log by displaying the Alarm log menu.

| |
|---|
| ALARM LOG: 18 ACKNOWLEDGE: 0 (2) |
|---|

The alarm log menu.

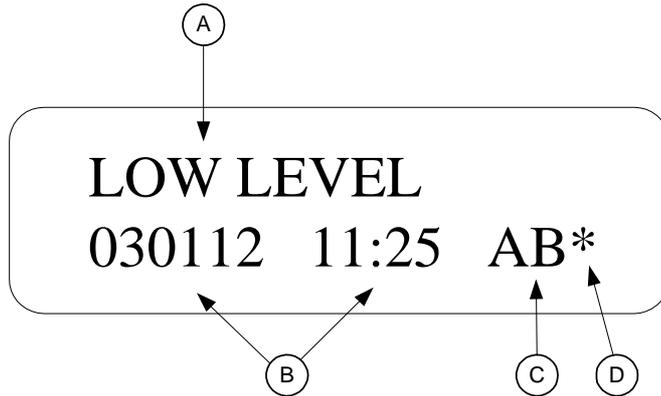
3.5.1.1 Browse the alarm log

Follow these steps to browse the alarm log:

- | Step | Action |
|------|--|
| 1 | Display the Alarm log menu, and press OK. Result: The first alarm is shown in the display. |
| 2 | Chose one of the following two steps: <ul style="list-style-type: none"> • To acknowledge all alarms without viewing, change the acknowledge value to 2 and press OK. • To read the latest alarms, press OK. |
| 3 | Browse the log with the Up and Down arrows. |
| 4 | To acknowledge present alarm, press OK. |

Result: The alarm text, consisting of a maximum of 20 characters, is shown in the display of the RTU and recorded in the alarm log.

Example: This is an example of the alarm text.



Alarm displayed on the RTU.

Table: This table gives an overview of alarm text.

| Field | Description | Comment/Reference |
|-------|---|--|
| A | Alarm text indicates that it is an activation alarm, generated when the alarm condition is fulfilled. | When the condition is no longer fulfilled, the alarm is not stored in the alarm log. |
| B | Date and time of alarm | - - |
| C | Type and priority (A, B, C or E) assigned to the alarm. | For explanation, see 3.4.2 Alarm priorities. |
| D | * indicates that the alarm has been transferred to the central or to the alarm system. | For further information, see 18 Appendix D - List of alarms. |

Note: Active alarms are not cleared from the log or the central system. Alarms are sent to the central system independent of the alarms in the alarm log.

There is no need to delete alarms to make space for new alarms. If the alarm buffer becomes full, the oldest alarm will be overwritten. The only reason to delete alarms is to make it easier to find new alarms.

3.5.1.2 General alarm

The lowermost led on the alarm panel is used as a general alarm led. This means that it will begin to flash as soon as a new alarm has been recorded in the alarm log. Always scroll through the alarm log to check for new alarms when this led flashes. When the alarm log is checked, the led is extinguished if the alarm has been acknowledged from the alarm panel.

3.5.1.3 Testing alarm panel Led

The RTU incorporates a function for testing the integrity of all of the led on the alarm panel. Press and hold the alarm acknowledgement button until the led begin to flash. The led will revert to normal operation when the button is released.

3.5.2 Printing out alarms from RTU

A printer can be connected directly to the unit and alarms printed out as they are generated. Note that this does not include alarms received before the printer is connected.

The printer, which must be of the serial type, is connected to COM1 or COM4. Select communication mode Alarm printer in the communications menus. See 3.3.4 "Communication selections".

3.5.3 Alarm output signal

The alarms in the RTU may be indicated with an output. There are three variants on the output with slightly different functions.

| Output option | Function |
|---------------------|---|
| Alarm pulse | One pulse on every new alarm. A short pulse on the output is generated on every new active flank on A, B or D alarms. The length of the pulse may be set in a menu. |
| Alarm status | Shows the status of alarms. The alarm output will work the same way as an alarm LED. Low - no alarms, pulse - active not acknowledged alarms, high - active alarms. Alarms are acknowledged on the RTU panel. |
| Alarm active | Shows if there are any active alarms. The output will be high as long as there is an A, B or D alarm active. |

Only A, B or D alarms are used with the output. If an alarm is set to C it will not affect the output.

Alarms with only an active flank and no passive flank like Warm start will not affect the output.

3.6 Remote alarm setup

3.6.1 Alarms to central system

Alarms are transmitted to the central system via a dedicated or dial-up connection. Alarms to be transmitted are stored in a buffer. If the buffer becomes full, the earliest alarm will be overwritten by the most recent but this will only happen if the connection to the central system is lost for several days.

A dial-up RTU can also be configured to call a pager directly. The selection to send to the pager is made in the telephone number by entering the special character "&" in the first position. See 3.6.4 "Telephone numbers to CS/Pager".

3.6.1.1 RTU with dedicated connection to central system (CS)

If an RTU is connected to the central system by a dedicated connection, the CS will transmit alarm queries to the RTU. Any alarms in the buffer will then be transmitted.

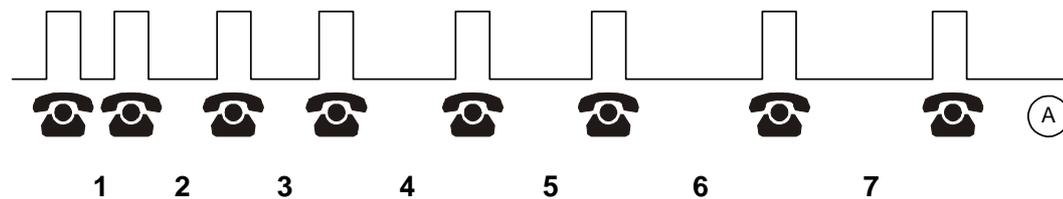
3.6.1.2 RTU with dial-up connection

In the case of a dial-up connection, the RTU will dial to the CS or pager as soon as an alarm is created. For this purpose, the alarm receiver's telephone number must be entered in the Telno:1 MTC/Page menu in the major menu group, which contains two telephone number menus.

3.6.1.3 How the RTU dials out alarms

The RTU contains two menus for telephone numbers. In the event of an alarm, the RTU rings the first number stored in the first menu. This number may go to the CS or pager. If this is unsuccessful, the unit will make further attempts to call the same number, with a pause between each attempt. The number of attempts is controlled by two menus Number of calls CS and Number of calls pager.

When the RTU rings and the call fail, the first pause will be 1 minute long. Thereafter, the pause duration will increase by one minute on each occasion.



A = Pause

RTU alarm dial-out sequence.

If the RTU fails to transmit the alarm to the telephone number in the first menu, further attempts will be made to call the number in the next menu. If this is also unsuccessful, dialling will be blocked (A). The blocking time is set in the Pager cycle menu.

After the blocking the RTU will recommence the sequence from the beginning i.e. making new attempts to call the number in each menu. The RTU will continue to attempt to report the alarm until it succeeds.

The CS will automatically acknowledge if the alarm is successfully transmitted to the CS the alarm.

If the alarm is transmitted to a pager then the RTU will wait for acknowledge from the user. The time the RTU will wait is set in the Pager acknowledge time menu.

If the user fails to acknowledge the alarm the RTU will try the next telephone number in the sequence.

3.6.2 Alarm sending mode

An alarm can be transmitted to the central or alarm system, or simply recorded in the RTU. The appropriate setting is made in the Transmit alarm menu in the main menu group.

| |
|---|
| Transmit alarm Local today |
|---|

Alarm is only recorded locally in RTU.

Local permanent Alarms are only recorded in the RTU. All alarms (*) get priority E and will not be transmitted to the central system.

Remote Alarms are transmitted to the central system. The particular alarms that are transmitted will depend on the setting in the Alarm distribution menu.

Clear May be used to prohibit alarms, which have not yet been transmitted to the central system, from being sent.

Local today Same as "Local permanent". The selection will return to remote at midnight.

Select the Local today mode to avoid false alarms, for example when carrying out service work in the pump station.

! The Cold start and Personnel alarms are transmitted to the central or alarm system on every occasion, regardless of the alarm mode selection.



Alarm mode indicating lamp.

Table: This table gives an overview of the alarm modes shown through the indication lamp.

| Indicating lamp | Alarm mode |
|-----------------|---|
| Steady light | Remote mode, alarms will be transmitted. |
| Flashes | Alarms waiting to be transmitted. |
| Extinguished | Local mode, alarms will not be transmitted. |

To toggle between Remote and Local today, press the local/remote button.

! It is not possible to toggle from the Local permanent alarm mode.

3.6.3 Alarm distribution, selecting alarms for transmission

Select the priorities to be transmitted to the central/pager in the Alarm distribution menu. The default setting is to transmit A and B alarms, as well as P alarms, which represent passive alarm. Enter '1' in the positions corresponding to the transmission priorities.

| |
|--|
| Alarmdistrib. 1101 (ABCP) |
|--|

Alarm distribution for transmission of A and B priority alarms, as well as passive alarms.

See 3.4.2 "Alarm priorities" for more information.

3.6.4 Telephone numbers to CS/Pager

A telephone number may contain up to 20 characters, including the type of dialling and "pause" characters.

The following characters are used to enter the telephone number correctly:

| Character | Explanation |
|--------------|--|
| & | Used in Paging systems numbers. The '&' character must always be first in the string if this telephone number is a paging number. Otherwise the system assumes that the alarm should be transmitted to a Mtc-Com or AquaView. |
| T | The RTU transmits digits using tones in what is known as DTMF tone dialling, which is the most common mode. The DTMF tone dialling character must be first in the string when calling the central system but in second position in paging numbers. If the paging system uses a telephone number to the paging central and this is a paging number then do NOT use this character. |
| P | The RTU transmits digits by sending mechanical pulses. This should be used only if DTMF tone dialling does not work due to older types of telephone exchanges. The pulse dialling character must be first in the string when calling the central system but in second position in paging numbers. If the paging system uses a telephone number to the paging central and this is a paging number then do NOT use this character. |
| , | The RTU pauses for 2 seconds, e.g. to dial 0 for an outside line. A pause can be inserted at any point in the telephone number. Several pauses may also be inserted in succession. If the paging system uses a telephone number to the paging central and this is a paging number then do NOT use this character. |

A telephone number to an MTC-COM may be of the following form:

| |
|---|
| Telno:1 MTC/Page T123456 |
|---|

Telephone number 123456 entered.

This means that the RTU will ring the number 123456 in the event of an alarm. The character 'T' at the start indicates tone dialling.

The number T0,234567 means that the MTC-COM first dials a zero, then pauses for 2 seconds before continuing with 234567.

The telephone numbers can also be entered in the menus using the set point adjustment function in the central system.

3.6.5 Number of calls to CS

The numbers of attempts to call central system are controlled by the menu:

```
Number of calls
CS 5
```

Number of calls to central system.

This is the number of calls the RTU will try to make to the same number before switching to the next number.

3.6.6 Changing alarm code and priority

It is possible to change the alarm priority and alarm code locally on the RTU. This is normally done by sending the "Alarm code filter" from AquaView. Three menus are used for this function. You enter the alarm code of the menu you want to change in the first menu and then you set the priority and code in the following two menus.

Example on how to change the spare alarm on input 6 to another code.

First select the alarm code to change.

```
Select alarm
code 86
```

Go to the next menu.

And change the priority to another code.

```
Alarm priority
A
```

Go to the next menu.

And change to another alarm code.

```
New alarm code
45
```

The input 6 will now send an A alarm with code 45 "Low pH".

If this alarm is sent to directly from RTU to pager the text will be the old text "Alarm digital input 6". It is however possible to change also the text but this must be done by updating the RTU with a special text file (RTU.CFG) using a PC.

3.7 Paging setup

3.7.1 Text paging system and SMS message

The RTU can handle alarm distribution directly to a paging system or to a GSM telephone. The first sign in the menu Telno: CS/PAGE must be "&", otherwise the program will handle the phone call as if calling to a CS.

3.7.1.1 Numerical paging

The message that is sent to a numerical pager consists of numerical code like "12580501". It starts with the station number, three digits "125". The next four digits are the alarm code "8050", and the last digit is the priority of the alarm "1". The only setting needed is the telephone number to the pager in the menu "Telno. 1 CS/PAGE" starting with a "&".

3.7.1.2 Alphanumerical paging

When using alphanumerical paging, the message on the pager consists of alarm text and station name. The following settings are needed:

- The telephone number to the pager in the menu Telno: CS/PAGE starting with a "&". Neither a "T" nor a comma should be used.
- The telephone number to the paging central. This is the telephone number that is dialled by the modem when an alarm should be transmitted. Information is given on the subscriber agreement and in that company's documentation. No "&" should be entered in this menu.
- The name of the station should be entered in the menu Station name. If no name is entered, the station number will be sent to the pager.
- If used, enter the password in the menu Password.

3.7.1.3 SMS

When using SMS, the message on the GSM telephone consists of alarm text and station name. The following settings are needed:

- The telephone number to the GSM telephone in the menu Telno: CS/PAGE starting with a "&". Neither a "T" nor a comma should be used.
- The telephone number to the paging central. This is the telephone number that is dialled by the modem when an alarm should be transmitted. Information is given on the subscriber agreement and in that company's documentation. No "&" should be entered in this menu.
- The name of the station should be entered in the menu Station name. If no name is entered, the station number will be sent to the pager.
- If used, enter the password in the menu Password.
- If used (SMS for Germany), an identification code should be entered in the menu Identity code.

3.7.2 Number of calls to pager

The numbers of attempts to call the pager central are controlled by the menu:

| |
|--|
| Number of calls pager 5 |
|--|

Number of calls to paging central.

This is the number of calls the RTU will try to make to the same number before switching to the next number.

3.7.3 Pager acknowledge time

If the alarm is transmitted to a pager then the RTU will wait for acknowledge from the user. The time the RTU will wait is set in the Pager acknowledge time menu.

| |
|---------------------------------|
| Pager Ack Time 10 min |
|---------------------------------|

The Pager acknowledge menu.

If the user fails to acknowledge the alarm the RTU will try the next telephone number in the sequence.

If you do not want to acknowledge any alarms then set this time to zero. The RTU will then send the alarm and then automatically acknowledge the alarm. Only use this if the paging system has a two way communication to the pager like in SMS.

3.7.4 Wait time pager cycle

If the RTU fails to transmit the alarm to the telephone number in the first menu, further attempts will be made to call the number in the next menu. If this is also unsuccessful, dialling will be blocked. The blocking time is set in the Pager cycle menu.

| |
|---------------------------------------|
| Wait time pager cycle: 180 min |
|---------------------------------------|

After the blocking the RTU will restart the sequence from the beginning i.e. making new attempts to call the number in each menu. The RTU will continue to attempt to report the alarm until it succeeds.

3.7.5 Selecting paging system

The RTU can also dial out an alarm directly to a paging system. The correct values must be entered in the parameter menus including Telephone number to PAD, Pager number and more depending on the selected paging system.

The RTU software may handle several paging systems. Countries normally have only one or two paging systems. The systems to use in different countries are listed below. Since this function is heavily dependent on the paging system supplier it might not be completely up to date.

| Number | Paging name | Parameters used. See following headlines. | Countries |
|--------|------------------|---|-------------------------|
| 0 | None | | |
| 3 | MiniCall numeric | | Sweden |
| 4 | Semadigit | | Holland |
| 7 | Numerik N/DK | Wt | Norway, Denmark, Sweden |
| 9 | Minicall text | Tx, Pw, Id, Pad, Stn | Sweden |

| Number | Paging name | Parameters used. See following headlines. | Countries |
|--------|----------------|---|--|
| 10 | Semascript | Pad | Holland |
| 11 | TAP text | Id, Pad, Stn | England, France, Canada |
| 12 | Cityruf DE | Wt | Germany |
| 13 | SMS Europ. | Pw, Id, Pad, Stn | Sweden |
| 14 | SMS UCP | Pad, Stn | Sweden, Norway, Denmark, Holland, Germany, Austria |
| 16 | SemaDigit B | Wt | Belgium |
| 17 | SemaDigit NL | Wt | Holland |
| 18 | TAP D1 SMS | Pad, Stn | Germany |
| 19 | GSM-SMS | Pad, Stn | Almost all countries |
| 20 | Numeric A | | Austria |
| 21 | SMS-SFR F | Pad, Stn | France |
| 22 | SMS-Itineris F | Pad, Stn | France |
| 23 | TAP F | Id, Pad, Stn | France |
| 24 | SMS-Bouygues | Pad, Stn | France |
| 25 | SMS-CDMA | Pad, Stn | Australia |
| | Other | | |

See the next chapter and also 17 "Appendix C - List of menus" for information about the parameters.

To select the paging system you select the name in the Paging system menu.

| |
|--|
| Paging system SMS UCP |
|--|

Selecting SMS UCP Paging.

Since the paging systems change all the time the internal system software of the RTU might be updated with newer paging systems. If this happen you can select the option "Other" in the paging menu.

| |
|--------------------------------------|
| Paging system Other |
|--------------------------------------|

Selecting another paging system.

This will immediately change the menu to enable entering the paging code instead.

| |
|---------------------------------|
| Paging system code 0 |
|---------------------------------|

Selecting paging system by code.

Now you are able to select any paging system supported by the newer system software. This number will be larger than the last number in the table above. Selecting number zero will change back the menu to the normal menu menu.

In the set points from AquaView you always have to select the paging number code. The menu menu is not available there.

3.7.6 Paging system parameters

Information on some of the menus is given on the subscriber agreement and in that company's documentation.

3.7.6.1 Tx = Paging transmitter number

| |
|----------------------------------|
| Transmitter no 123456 |
|----------------------------------|

Paging transmitter number

The transmitter number is normally only six characters. It is currently only used in "Minicall text" in Sweden.

3.7.6.2 Id = Paging identity code

| |
|-------------------------------|
| Identity code 1234 |
|-------------------------------|

Paging identity code

The identity code may be any text or number.

3.7.6.3 Pw = Paging password

| |
|-------------------------------|
| Pager password XYZ |
|-------------------------------|

Paging password

The password may also be any text or number.

3.7.6.4 Pad = Paging number to PAD/SMSC

| |
|--|
| Telno. PAD/SMSC T0123456789 |
|--|

Paging number to PAD/SMSC

The telephone number to the paging central follow the same rules as the normal telephone numbers with the exception that you can not use the "&" character.

3.7.6.5 Stn = Station name

The Station name is entered as specified in the central system.

| |
|---|
| Station name MYOWNNAME |
|---|

Station name

Try to select a name as close as the one in the CS to avoid confusion. Only capital letters and numbers are allowed.

3.7.6.6 Wt = Delay paging central

| |
|--|
| Delay paging central 15 s |
|--|

Wait time, delay paging central

The paging delay wait time is used in primitive text paging systems to wait out the voice so the message will be accepted. Some systems do not accept sending the message immediately. This might also be used in other ways in some paging systems.

4 Special alarms and alarm delays

4.1 Analogue and digital alarm delays

Most of the alarms are either delayed by the analogue alarm delay or the digital alarm delay. Set the delays depending on the situation at your station. A general guide is to set both the digital delay and the analogue delay to 10 s but this may need to be changed.

| |
|-------------------------------------|
| Digital delay 10 s |
|-------------------------------------|

Digital alarm delay set to 10 s

4.2 Power failure delay

A special delay is used for power failure.

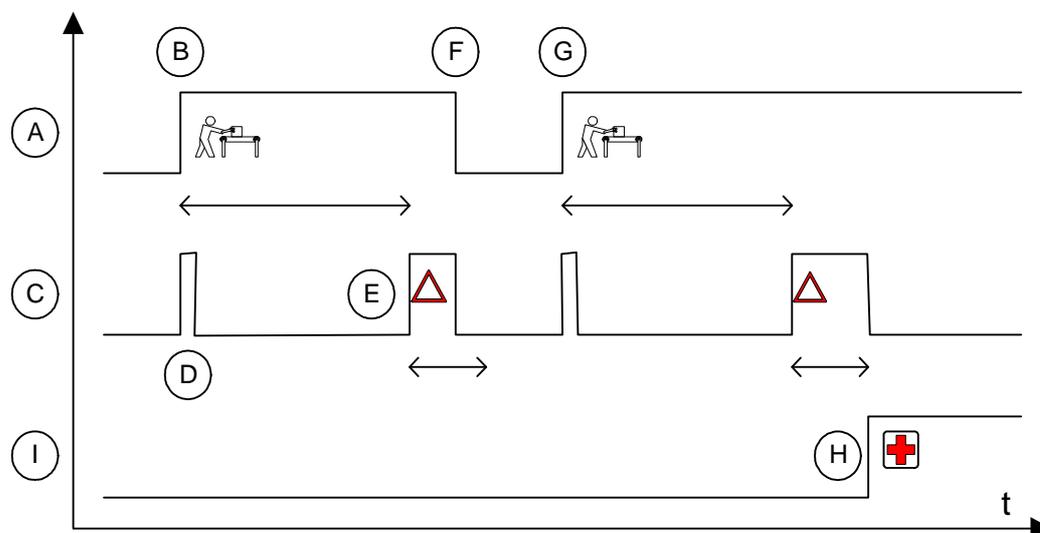
| |
|--|
| Power fail delay 10 s |
|--|

Power failure alarm delay.

The power failure will stop the pumps immediately. The alarm will however be delayed by the time in the menu. The pumps will start when the power failure signal goes low and after a short start delay.

4.3 Personnel alarm

The personnel alarm is one of the most important alarm functions. The alarm is used when work of any kind is being carried out in the pumping station.



Personnel alarm.

A switch (A) connected to the personnel alarm input, usually the station lighting switch, is operated when work begins (B) in the station, starting a countdown of the specified working period. The output buzzer (C) is activated shortly (D) when the period starts and then when the period has elapsed (E). Some type of warning signal should be connected to this output. The switch should be opened (F) when the warning is received and then closed again to begin a new working period (G). Failure to acknowledge the buzzer signal will start the output siren (I) and send an alarm to the central system (H).

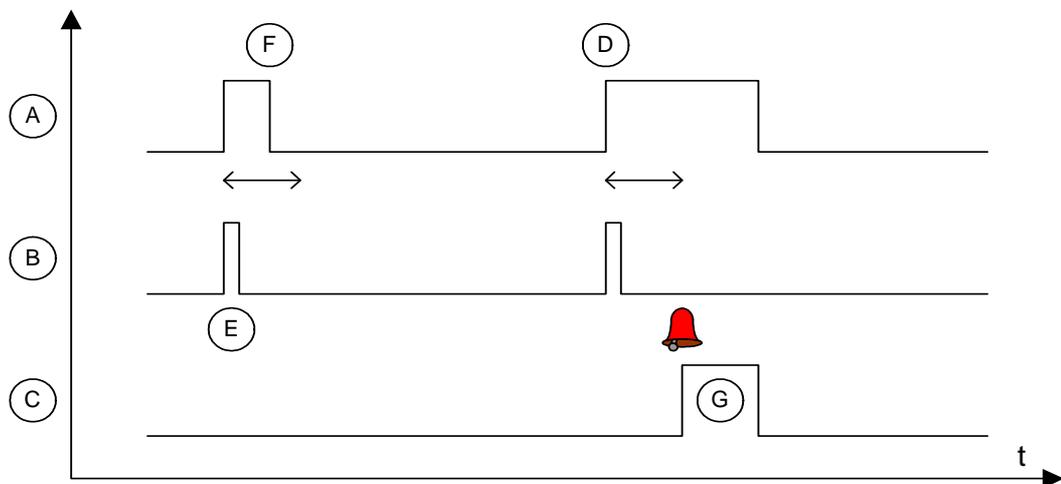
The working and warning periods are set in the Max. work time and Warning time menus, and can also be set from the central system. If the periods are changed while the switch is closed, the new settings will not apply until the switch has been opened.

The personnel alarm is dialled out to the central system or paging in all cases, regardless of the alarm mode selected.

4.4 Intruder alarm

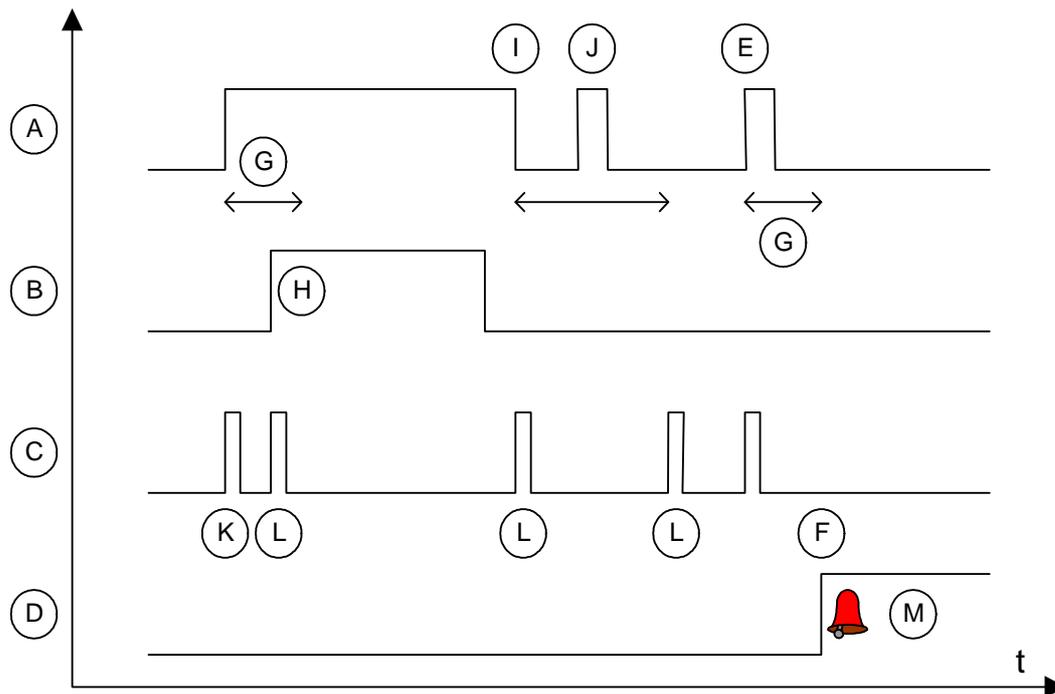
The intruder alarm simply sends an alarm if the input intruder sensor is activated and the alarm is not stopped in some way.

There are two basic ways to use the intruder alarm.



Intruder alarm using only intruder sensor.

The simple way is to use only use the intruder sensor (A) and not use the RTU password. The use of a buzzer output (B) and siren output (C) are optional. If the intruder sensor is high and stay high (D), for the period in the intruder delay menu, the alarm will be created. The intruder alarm is simply stopped by a low signal on intruder sensor (F). The output buzzer signal will be activated for a short beep (E) to indicate that the sensor is activated. When the alarm is created the siren output will be permanently high (G) until the alarm disappears. This solution is suitable when external intruder alarm systems are used.



Intruder alarm using intruder sensor and RTU password.

The other way to use the intruder alarm is to use both intruder sensor input (A) and RTU password (B). The use of the buzzer (C) and siren (D) outputs are optional. If the intruder sensor gets high (E) the alarm (F) will be created after the intruder delay (G). In this case it a low signal on the intruder alarm will not stop the alarm. Enter the password (H) in the RTU to stop the alarm. The RTU will show the password menu automatically. The alarm is deactivated as long as the sensor input is active or as long as the RTU display is active. The intruder alarm is activated again two minutes after the sensor input is low (I) and the display of the RTU is off. Sensor input will be ignored during this period (J). The output signal will be activated for a short beep when the sensor is activated (K) and also when the alarm is turned off by entering the password (L). When the alarm is created the siren output will be permanently high (M) until the alarm is deactivated by entering the password in the RTU.

It is possible to connect intruder sensor and personnel on site signals to the same input. It is also possible to connect buzzer and siren outputs to the same output. See 3.2.3 "Selecting input functions".

4.5 Test alarm

To verify that the alarm distribution is working properly, it is possible to configure the RTU to call out a test alarm. The test alarm has B-priority as default, and is transmitted in the same way as an ordinary alarm according to the settings regarding the alarm distribution.

You set the number of days between every alarm and the time you want the alarm to be transmitted.

| |
|---|
| Testalarm every 2 days |
|---|

| |
|---|
| Testalarm time 13:00 h:m |
|---|

These settings will send an alarm every other day at 13:00.

4.6 Pump service alarm

The RTU can be programmed with a service alarm, which is activated after the pumps have been in service for a number of hours. The length of the service interval is entered in the Service interval pumps menu in the SERVICE INTERVAL menu group. A service alarm will be generated if the pumps are in service for an extended period.

The Time after service menus show how long the pumps have been in service since the last service. The service interval can be set from the central system.

The Time after service menus must be reset on completion of service. Change from the Read to the Write mode in the menu and select Delete value? Yes. The value in the menu will then be zeroed.

provided with hysteresis in the Hyst. level alarm menu to avoid unnecessary alarms.

These alarms use individual alarm delays. The high level alarms are delayed use one delay and the low level alarms use one.

See 3.4.5 "Alarm hysteresis" for a description of the concept of hysteresis.

5.1.3 High and low level alarm outputs

The high level alarms and low level alarms activate digital output signals. The output goes high when the alarm is activated and low when the alarm goes passive.

The outputs are intended to be used to control external equipment. The outputs may also be connected to external alarm systems. See 20 "Appendix F - Connection" for more information.

5.1.4 Level calibration

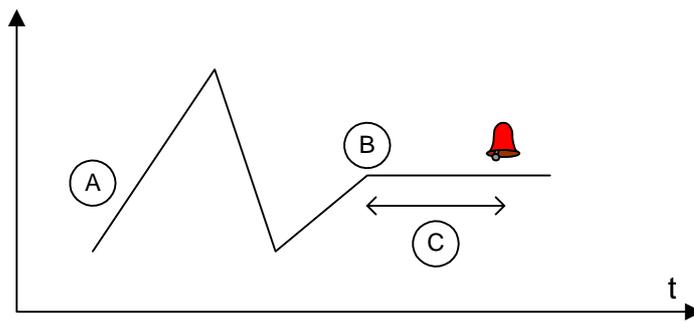
Level calibration of the transmitter is not required. The following instructions are useful only if the need would arise for any reason.

Follow these steps to calibrate the level of the transmitter.

- | Step | Action |
|------|---|
| 1 | Select the Level (calibrate) menu in the LEVEL menu group. |
| 2 | Enter maximum level for transmitter calibration range in the Specify max. level: menu, and press OK. |
| 3 | Enter the minimum level for the transmitter calibration range in the Specify min. level: menu, and press OK. |
| 4 | Lift the transmitter out of the water, and press OK. |
| 5 | Submerge the transmitter into the water, and press OK. |
| 6 | Enter the actual level of the transmitter below the water surface in the Specify actual level: menu, and press OK. Result: "Calibration complete" is shown in the display. |
| 7 | Press OK. |

5.1.5 Sensor control

The RTU can also monitor the transmitter. If the sensor fails an alarm is created. The duration for which the level in the sump may remain constant is entered in the Sensor control menu and an alarm will be generated if the transmitter value is not altered during that time.



The illustration above show what happens. The level (A) changes constantly but in one point in time (B) it ceases to work. The sensor control will wait and see if the level changes (C) for the time set and finally generate an alarm.

The change must exceed 1% of the sensor range within the time limit to count as a working sensor. If numerous false Sensor Fault alarms are generated, try to extend the sensor control time. The function can be disabled by entering zero.

5.2 Current sensors

5.2.1 Pump motor currents

An RTU can both measure and monitor motor currents. A motor current transmitter must supply a DC current signal in the 0/4-20 mA range.



The operating response digital inputs of the pumps must be connected in order for the measurement to be in operation.

5.2.2 Nominal current

The results of the measurement are displayed in the CURRENT P1 menu. The calculated nominal current is displayed in the next menu. The nominal current shows a calculated average of the current and this value is shown even when the pump does not run.

5.2.3 Current inputs on 2 pump stations

On a two pump station the currents for P1 and P2 are connected to analogue 2 and 3. The maximum value of the current measurements is set in the menus Current range P1 to Current range P4. See 20 "Appendix F - Connection".

5.2.4 Current input options on 4 pump stations without Siox S48

On a four pump station the current inputs for two pumps may share the same analogue input signal. The program use the response digital input to figure out which pump the current is from. If both pumps are running the currents are split using the power value of the pump.

The current inputs are selectable. The following options exist:

| Menu option | Analogue 2 | Analogue 3 | General analogue 4 |
|------------------|------------|------------|--------------------|
| A2=P1+3, A3=P2+4 | P1 and P3 | P2 and P4 | |
| A2=P1+2, A3=P3+4 | P1 and P2 | P3 and P4 | |
| A2=1,A3=2,A4=3+4 | P1 | P2 | P3 and P4 |
| A2=1+2,A3=3,A4=4 | P1 and P2 | P3 | P4 |

If general analogue 4 are to be used as current this analogue input has to be selected to current input. See 5.3 "General analogue

".

5.2.5 Input options on 4 pump stations with Siox S48

Four analogue signals for the current signals are provided through the Siox S48 unit. The maximum value of the current measurements is set in the menus Current range P1 to Current range P4. See 20 "Appendix F - Connection".

5.2.6 Current alarms

There are also the possibilities of getting alarms if the currents are too high or too low, the limits are entered in High current P1 to P4 and Low current P1 to P4 menus. In order to avoid repeated alarms if the current is varying around the alarm limit, the value in the menus Curr. Hyst. P1 to P4 can be used to avoid these unnecessary alarms. For a more comprehensive description of this function called hysteresis see 3.4.5 "Alarm hysteresis" for a description. Current alarms are generated only when the pumps are running.

5.3 General analogue

Many of the programs have the possibility to connect a general analogue signal. This could be used for example to measure different flows, pH, current, temperature or pressure. It is possible to use the input to replace internal calculations for inflow, outflow, overflow or current on one or two pumps.

5.3.1 Input options

The Maximum value and Minimum value menus must be adjusted to ensure that the transmitter reads the correct value.

It is possible to select different options on this analogue. The options are:

| Menu option | Comment |
|-------------|---|
| General | The analogue is used as a general input. No unit will be used when the value is presented. The volume calculation will be turned off. |
| Flow | The analogue is used to measure a flow. The volume of the flow will be calculated. |
| Pumpflow | The analogue is used to measure the station pump flow. This will replace the |

| Menu option | Comment |
|-------------|--|
| | pump flow calculated by the program using only the pump capacities. The flow will be used to monitor pump capacities and alarms and to calculate pumped volume. |
| Inflow | The analogue is used to measure the station inflow. This will replace the inflow calculated by the program using the level sensor. |
| Overflow | The analogue is used to measure the station overflow. This will replace the overflow calculation by the program using the level and overflow sensors. If the overflow sensor is used this will be used to start the overflow monitoring. If the overflow sensor is not used the overflow will start when the flow is larger than 1 l/s. This requires the analogue to be trimmed to be accurate on 4 mA or else it may register false overflow alarms. |
| Current | The analogue is used to measure a current. If this is used on a four pump station the current may be used to replace one or two currents for the pumps. See 5.2.4 "Current input options on 4 pump stations without Siox S48" for more information. |
| PH | The analogue is used to measure pH. |
| Temperature | The analogue is used to measure temperature in Celsius. |
| Pressure | The analogue is used to measure pressure in bar. |

5.3.2 Volume calculation

If a flow meter is connected and option Flow selected then the program will calculate the volume on this flow. The flow is integrated, and the total volume is showed in the menu total flow.

5.3.3 Alarms

Low and high alarm limits are required to enable the value to be monitored. These limits are entered in the High alarm and Low alarm menus. The alarm can also be provided with hysteresis in the Alarm Hyster. menu to avoid unnecessary alarms. See 3.4.5 "Alarm hysteresis" for a description of the concept of hysteresis.

5.3.4 Level control output

An object may be controlled by the analogue signal. Enter values in the Start value analogue and Stop value analogue to activate the digital output. This output may be used for example to control an external object or to block the pumps.

The output is active either by high level or low level. The function depends on the order of the start and stop levels. If the start level is higher than the stop level then the output will be activated when the analogue is higher than the start level and it will be de-activated when the analogue is lower than the stop level. If the start level is lower than the stop level the output will be reversed. The output will in this case be activated when the analogue signal is lower than the start level and deactivated when the analogue is higher than the stop level.

6 Operational data

The RTU continuously monitors, measures and stores pumping station data. See 19 "Appendix E - Central system" for the trend measurements and report values, which are recorded in the RTU and can be collected in the central system.

The values recorded in the RTU can be read in the appropriate menus. The values are recorded simultaneously in daily and continuous basis and presented as today's, yesterday's or continuous data. Daily recording means that the saved values are zeroed every midnight. Continuous recording means that each value is saved continuously until it is zeroed manually. Yesterday values are the full day value for the previous day.

It is possible to change mode anytime without losing any data. All three types of values are recorded and saved continuously.

6.1 Selecting report mode

Selects the manner in which recorded values are to be displayed in the menu. The reporting mode cannot be selected from the central system. Change the setting in the menu:

| |
|---|
| OPERATIONAL DATA Today's |
|---|

Report mode menu.

6.2 Restarting counters

It is possible to empty the counters for all local continuous data. Today's and yesterday's values are not possible to change.

To change any report value first change to continuous data.

| |
|--|
| OPERATIONAL DATA Continuous |
|--|

Report mode in continuous.

Then select the menu with the data to change, select the Write mode and change the value.

6.3 Runtimes and start data

Running times and number of starts are calculated on all pumps.

| |
|--|
| P1 no. of starts 23 day |
|--|

Daily value for pump 1 number of starts.

| |
|--|
| P1 runtime 2:10 h:m y-day |
|--|

Yesterday runtime for pump 1.

The program also calculates running time and starts for two simultaneously running pumps. The number of starts in this data is the number of times both pumps were forced to start.

| |
|---|
| Two pump starts 12 day |
|---|

Daily number of starts for two pumps.

| |
|---|
| Two pump runtime ##### h total |
|---|

Total run time for two pumps.

7 Pump control

The pump control function determines the manner in which the pumps operate, including starting and stopping, as well as the sequence of operation.

The pump control menus are grouped in the Start and stop levels, Pump control, Advanced pump control and Pump sump cleaning menu group.

7.1 Start and stop levels

There is one start and one stop level for each pump.

To control a pump set both the start and the stop level. The basic function is that the pump will start at the start level and stop at the stop level.

| |
|---------------------------------|
| Start level P1 1.30 m |
|---------------------------------|

Start level for pump 1.

| |
|--------------------------------|
| Stop level P1 0.40 m |
|--------------------------------|

Stop level for pump 1.

If alternation of the pumps is used some, but not all, of the start levels may be set to zero. See 7.3.3 "Maximum running pumps" for more information. If alternation is turned off both start and stop levels has to be used or else the pump will not start.



| |
|---|
| If stop level is set to zero the pump will be disabled and can not start. |
|---|

7.2 Basic pump control

7.2.1 Backup control

When the level activates the high level float, a backup function intervenes to start a pump. When the level switch signal disappears, a timer function is initiated to ensure that the pumps continue to run for at least the specified time. This time is specified in the high level run time menu.

| |
|---|
| High level run time 10 s |
|---|

The high level run time menu.

When the timer runs out the pumps will either continue to run or stop depending on the level signal. The main purpose of the function is to secure the pumping even if the level sensor fails to work. The most common fail on the sensor will make the level show zero. This will stop the pumps when the high level runtime timer runs out. If the level sensor works as normal the pumps will continue to run and stop at the normal stop level.

The pumps are not started if the time is set to zero. In this case only the alarm is created.

The number of pumps that start will depend on the setting in the maximum running pumps menu. It is possible to select exactly which pumps to start at the high level float. See 7.3.4 "Special control options" for possibilities on how to customize pump operation.

| |
|---|
| Low level block- time #### s |
|---|

Low level block time menu.

When the low level float is activated a similar function exists to protect the pumps to run if the level sensor fails. The pumps are blocked as long as the low level is active and continued to be blocked the time in the low level block time.

7.2.2 Response error delay

The response error delay controls the time it takes to switch to another pump if the response signal should fail to appear. At the same time the response alarm is created. The switching of pumps only occurs within alternating pumps. If the pump is not alternating the program will only create the alarm and try to run the pump without the response signal. The program will prefer pumps without response error when it starts alternating pumps but it will try to start them if more pumps need to be started. The alarm will disappear (be passive) when the response signal appears the next time. To manually disable the alarm start the pump by hand, the response signal must of course appear.

The delay is also used to remove the over current alarm that may otherwise be triggered when the pump starts.

7.2.3 Start/stop delays

The start delay and stop delay can be applied to filter out pump control disturbances. The delay is the interval between the occurrence of the starting condition and the instant of starting. Specifying a delay prevents the pumps from starting as the result of a disturbance.

Specifying a stopping delay will eliminate unnecessary stopping of the pumps. The stopping delay is specified in the Stopping delay menu.

7.2.4 Intermediate delays

Two delays are used to prevent pumps from simultaneously starting and stopping. These delays are also used to prevent a pump from starting immediately after a pump stop or vice versa.

| |
|-------------------------------------|
| Time between starts 10 s |
|-------------------------------------|

Delay time between two pump starts.

The delay between two starts is sometimes used to protect the pump power supply from the overload occurring when several pumps is starting at the same time. The

delay between two stops may be used to protect the pipes from water hammer that occur when a pump stops.

| |
|------------------------------------|
| Time between stops 10 s |
|------------------------------------|

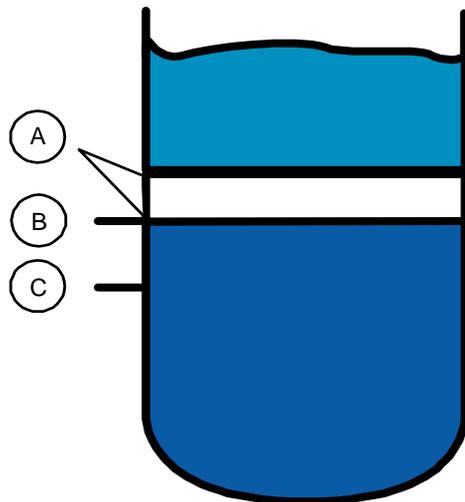
Delay time between two pump stops.

Delay between two starts is also used for to prevent a pump stop when a pump has started. This will in fact be the same as a minimum run time for a pump.

The delay between two stops is also used to prevent a pump from starting after a pump stop.

7.2.5 Random start level

Starting the pumps at the same levels in every instance creates a risk of fouling build-up in the sump. This is prevented by specifying a Random start span in the menu. This provides the pump, not with a single starting level, but with a range of random levels within which to start.



A = Random starting range. Pumps start at some point in this area.

B = Starting level

C = Stop level

Random starting range.

If alternation is not used then it is recommended to use a smaller random starting range than the distance between the used starting levels, otherwise pumps may start in an unpredicted order. If alternation is used it does not matter if the random start range overlap next pump start. The pumps will alternate correctly anyway.

7.2.6 Maximum start/hour alarm

It is possible to get an alarm if the pumps for some reason start too often. Set the number of starts in the menu to activate the alarm. If the pump starts this number of times within an hour an alarm is created. The alarm does not stop the pump.

This alarm is activated by default and set to 16. To disable the alarm set the value to zero.

7.2.7 Blocking pumps with low current

By entering a value in the Low current reset time menu, the pump will be switched off when a low current alarm is generated. The Pump is blocked during the time set in the menu. A zero in the menu Low current reset time turns this function off.

It is possible to disable the function for individual pumps if only some of the pumps should be blocked. This is done in the special control menu for the pump. See 7.3.4 "Special control options".

7.3 Advanced pump control

7.3.1 Action, starting control sequences locally

It is possible to start some automatic pump control sequences locally on the RTU display. The alternatives are to activate the APF or to start a pump down. These functions are the same as the corresponding remote command.

| |
|--|
| <p>Action Select action</p> |
|--|

The select action menu.

The command activate APF will not start the pumps. They will start as normal on the next start level. To activate APF and start pumping also select the pump down command.

The menu return to "Select action" after starting any of the commands.

See 7.4.2 "APF control" and 7.4.3 "Forced pump down" for information on these functions.

7.3.2 Alternation

The alternation used is not based on a fixed starting sequence. When alternation is active the exact alternating order will be based on the starting and stopping times. The pump selected to start will be the one that has been still the longest time within the current pump cycle. The pump selected to stop will be the one that has been running the longest time in this pump cycle. If the pump is started manually it will influence the order.

The alternation is also used when two or more pumps are running. The pumps alternate also on high inflow situations where many pumps are running for a longer time.

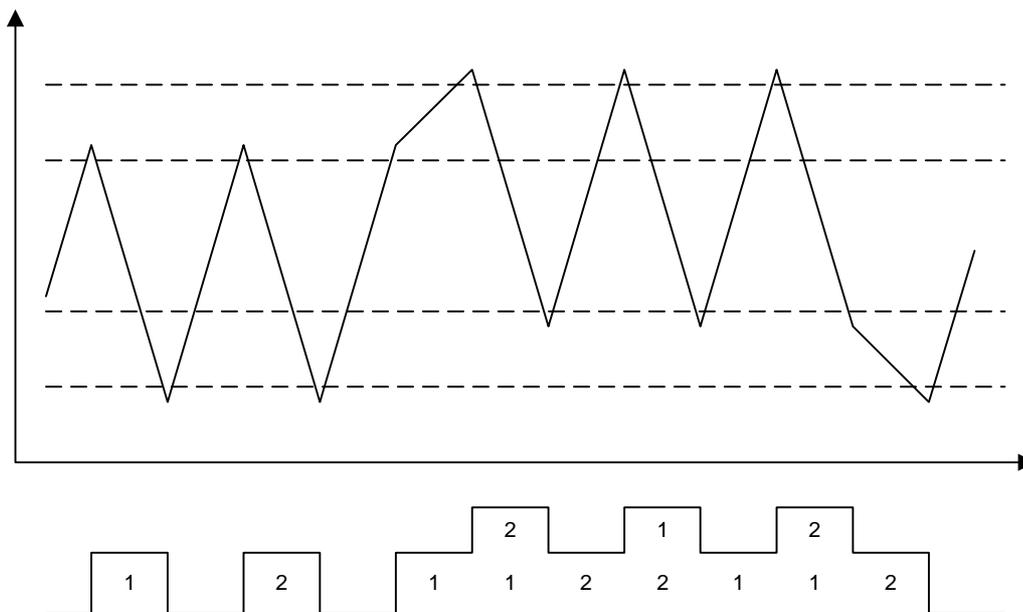
This method will cause the pumps to start the same amount of times, the running times may however be different if the pumps are not equal.

The first pump is started on the lowest stating level, the second pump on the second lowest level and so on. The pumps stopped in the same way, if all pumps are running the first pump is stopped on the highest stopping level and the last pump is stopped on the lowest stopping level. If only one pump is running it is stopped on the lowest stopping level. This is illustrated in the following pictures.

7.3.2.1 Two pump alternation

The Control option menu is used to specify the pump operating sequence. Three options are available: Alternation, which means that each pump starts every second time, as well as P1 always first and P2 always first, which means that either pumps P1 or P2, is started first.

The illustration below shows the starting and stopping sequence when two pump alternate.



Picture showing pumping sequence when two pumps are alternated.

The illustration shows two starting levels and two stopping levels and the changing level in the upper part of the picture. The lower part shows running pumps. Two numbers stacked here shows multiple running pumps.

7.3.2.2 Four pump alternation

The alternation groups menu is used to specify the pump operating sequence. It is possible to set the alternation on and off to any pump. It is also possible to alternate pumps in one or two groups.

```
Alternate groups
#-#-#-# P1-P4
```

The alternation groups menu for four pumps.

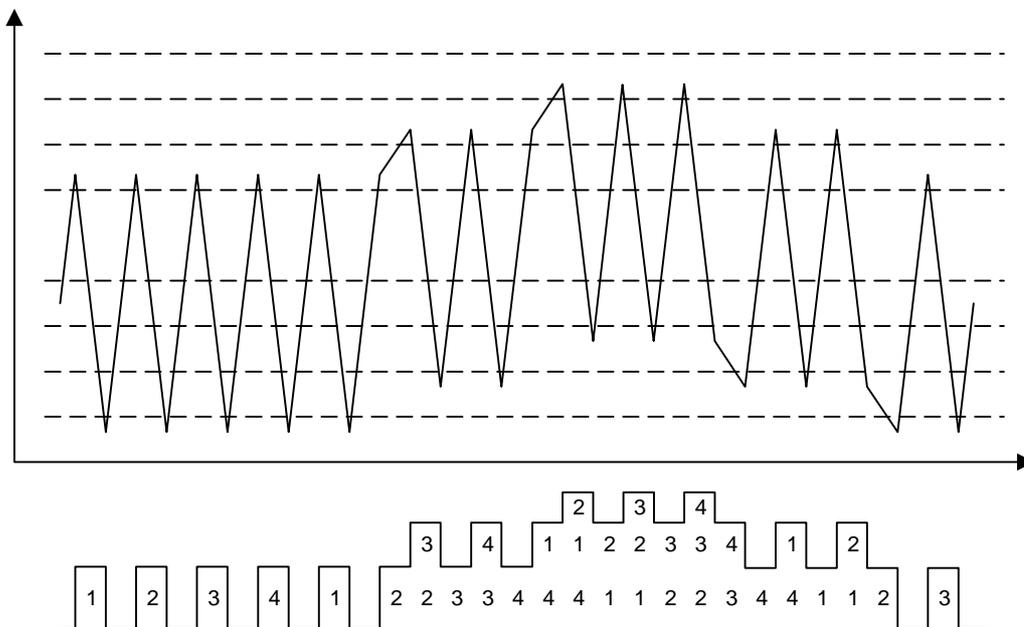
First number belongs to pump 1, second number to pump 2 and so on. If two pumps have the same group number they will alternate. Using a zero as group number will however turn the alternation off.

| Examples of alternation | Value in menu |
|-----------------------------|---------------|
| All four pumps alternate. | 1-1-1-1 |
| Alternate pumps 1, 2 and 3. | 1-1-1-0 |

| Examples of alternation | Value in menu |
|--|---------------|
| Alternate only pumps 2 and 3. | 0-1-1-0 |
| Alternate pumps 1 and 2 together and pumps 3 and 4 together. | 1-1-2-2 |
| Alternate pumps 1 and 4 together and pumps 2 and 3 together. | 1-2-2-1 |

The actual group number except zero is of no importance. Alternations 1-1-2-2 and 2-2-1-1 or even 7-7-3-3 are equal. 14 alternation combinations are possible for four pumps.

The illustration below shows the starting and stopping sequence when four pumps are alternated.



Starting sequence when four pumps are alternated.

The illustration shows four starting levels and four stopping levels and the changing level in the upper part of the picture. The lower part shows running pumps. Two or more numbers stacked here shows multiple running pumps.

7.3.3 Maximum running pumps

It is possible to reduce the number of simultaneously running pumps. Use this function if the hydraulic or electric system can not handle all running pumps. Reducing the number of pumps with this function has no effect on which pump is running, it only effects how many.

Max running pumps #

The menu for maximum running pumps.

Example: For a two pump station entering '1' eliminate the simultaneous running of both pumps.

Almost the same effect is achieved if one or more start level values are set to zero when the alternation is active. All stop levels are however always required on active pumps. The difference between using the maximum running pumps function and removing starting levels is what will happen when the level rise to the high level float. When using maximum running pumps then only the allowed amount of pumps will start. Pumps with no start level will start on the high level float.

7.3.4 Special control options

It is possible to set special options to control the pumps. All these options are normally set to off and they rarely need to be changed.

| Option | Default function. Off | Special function. On |
|------------------|---|---|
| Disconnected | Pump works as normal. | Pump is disconnected and the control of the pump is turned off completely. |
| Blocked by P2 | Pump is not stopped or blocked when pump 2 runs. | Pump is stopped before pump 2 is started. |
| Blocked by P3 | See above. Only found in four pump stations. | See above. Only found in four pump stations. |
| Blocked by P4 | See above. Only found in four pump stations. | See above. Only found in four pump stations. |
| No backup run | Pump start on backup run (High level float). | Pump does not start on backup run. |
| No long run blk. | Pump is stopped if running too long time. | Pump is not stopped if running too long time. |
| Leakage block | Leakage alarm does not stop and block the pump. | Leakage alarm stops the pump. |
| Not tele blocked | Pump is blocked when RTU is remote blocked. | Pump is not blocked when the RTU is remote blocked. |
| Use level E1 | If pump is blocked by another pump it will stay blocked until the other pump stops. | Pump will start and stop on extra start and stop levels 1 (E1) when it is blocked by another pump. |
| Use level E2 | See above. Only found in four pump stations. | Pump will start and stop on extra start and stop levels 2 when it is blocked by another pump. Only found in four pump stations. |
| APF high pres. | Normal undercurrent sensitivity. Pump will stop on APF on a | High undercurrent sensitivity. Pump will stop on APF on a current change |

| Option | Default function. | Special function. |
|------------------|--|---|
| | Off | On |
| | current change of 12 %. | of 6 %. |
| APF no use filt1 | Pump stops on APF at current transients. | Pump does not stop at current transients. |
| APF no use filt2 | Pump stops on APF at undercurrent. | Pump does not stop at undercurrent. |
| No low cur. blk. | Pump is blocked by a low current alarm. | Pump is not blocked by a low current alarm. |

7.3.4.1 Disconnect

Use this option if the pump needs to be removed from the pumping sequence temporary.

7.3.4.2 Blocked by other pump

Use this option if a pump shall stop when another pump runs. The pump is stopped before the other pump starts. If the other pump is started manually the pump is immediately stopped.

See 7.3.6 "Inter-blocking" for more information.

7.3.4.3 No backup run

This option will disable the pump from backup run. Backup run normally starts all pumps or as many as allowed by maximum running pumps set-point. If the station uses different sized pumps smaller pumps may start when the backup run is activated. Remove these pumps with this option if necessary.

See 7.2.1 "Backup control" for more information.

7.3.4.4 No long run block

The function long runtime block is common for all pumps. If some of the pumps are not suited for this function these pumps may be removed from the block by this option.

See 7.4.1 "Maximum pump time" for more information.

7.3.4.5 Leakage block

Some users want the pump to stop if the leakage sensor is activated. This option makes the pump stop on this alarm. Since the alarm is not removed automatically it is recommended to set the leakage alarm to A priority if the blocking is activated.

7.3.4.6 Not tele blocked

The pumps stopped if the station receives a remote blocking command. If this is not the desired behaviour set this bit to let the pump continue to run.

See 9.2.2 "Blocking actions" for more information.

7.3.4.7 Use extra levels E1 /E2

To start a blocked pump assign the pump an extra start and stop level using special option "Use level E1". This will make the pump start on start level E1 even when it is blocked.

See 7.3.6 "Inter-blocking" for more information.

7.3.4.8 APF options

There are two methods of stopping the pump when the APF function is active, current transients and undercurrent.

It is possible to only stop the pump on transients or undercurrent by using these options.

If the current difference between normal running and 'snoring' is small, the sensitivity may be raised by the "APF high pres." option.

See 7.4.2 "APF control" for more information.

7.3.4.9 No low current block

The function low current block is common for all pumps. If some of the pumps are not appropriate for this function it is possible to disable the function for these pumps using this option.

See 7.2.7 "Blocking pumps with low current" for more information.

7.3.5 Manual control

A pump cycle can be initiated by starting the pump manually from the control panel. If ON is chosen in the menu Manual control and the pump has been running for more than 5 seconds, the RTU pump control will take over. The pump stops when the stop level is reached.

7.3.6 Inter-blocking

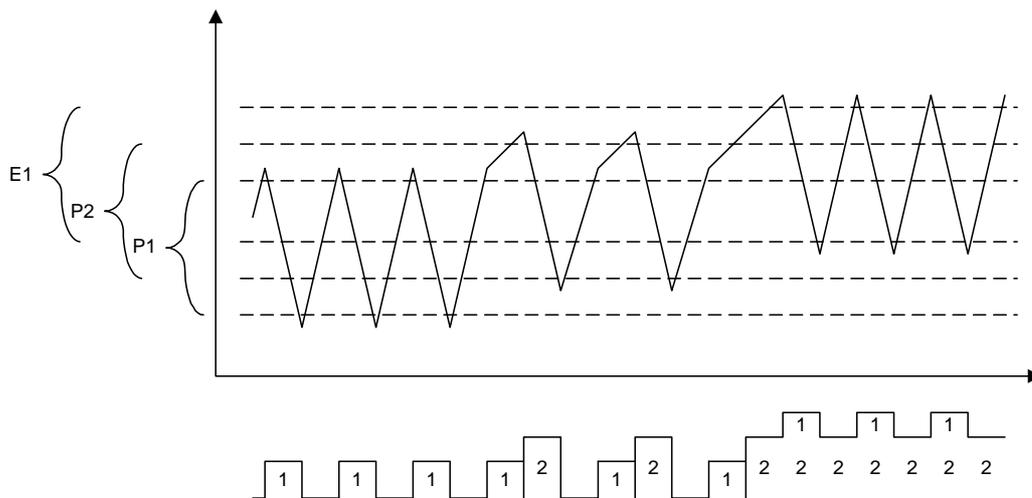
These options are useful if the station use different sized pumps. With these options it is possible to set up a station to use the small pump first and when the inflow gets higher use only the larger pump and finally use both pumps on high inflow.

In a four pump station it is possible to set up many combinations of small and big pumps.

An example:

A two pump station with a small pump P1 and a large pump P2. The small pump P1 runs most of the time and P2 takes over on higher flows. P1 is blocked by P2. On high inflows both pumps work together.

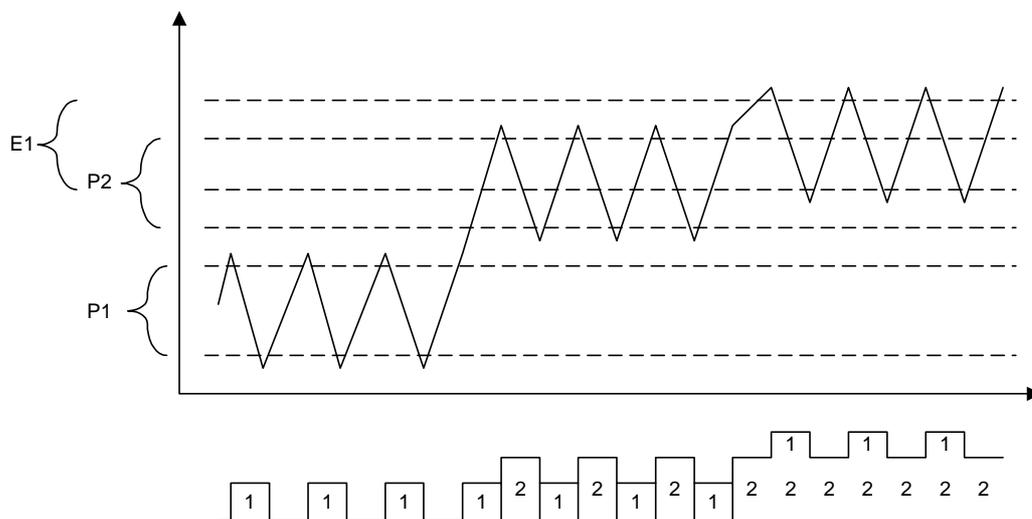
Setup will be, alternation: P1 start first, P1 blocked by P2 and P1 using extra levels E1.



The picture shows the result. The upper part of the picture shows the changing level and the start and stop levels for P1 and P2 together with the extra start and stop level assigned to P1. The lower part shows running pumps. Two stacked numbers means that the pumps are running in parallel.

The result is a station where P1 is pumping the most time to save energy. The cost of using P1 is lower than P2 because of the lower energy consumption on a smaller pump.

Changing the starting levels will result in a slightly different pump sequence.



See 7.3.4 "Special control options" for details about configuration options.

7.4 Sump cleaning

7.4.1 Maximum pump time

To prevent a pump from running continuously for a long time, it is possible to enter a time in the menu Maximum pump time. The pump that has exceeded the limit will be stopped. When the time between starts has elapsed, and the level

risers above a start level, the next pump according to the starting sequence will start. This will prevent clogging build up that lowers the capacity of the pump.

This function works with all pumps. If one or more of the pumps is not suitable for this the pump may be removed from the function by changing an option in the special control menu for this pump. See 7.3.4 "Special control options" for details about configuration options.

7.4.2 APF control

The APF cleaning function runs the pump to the absolute minimum water level in the sump - the point at which air is drawn into the impeller. The pump is then able to draw off the dirt and grease which normally settles on the surface of the water. By operating down to this minimum water level, the pump also creates turbulence in the water as the air is sucked into the pump, and this turbulence agitates any sludge layer which has formed on the sump floor, allowing this, too, to be drawn off.

The APF function requires that currents are monitored for the pumps.

Activate the APF by setting the number of cleanings a day in the menu.

| |
|--|
| APF clean cycles per day ## |
|--|

The APF cleaning menu.

7.4.2.1 Stop functions

When the water in the sump has dropped to such a level that the pump begins to draw air, the motor current will drop. The APF function detects this and stops the pump.

The APF function measures the normal operating current of each pump during routine pump cycles, by means of dedicated current transformers. These current values are shown in the nominal current menus and serve as reference values.

| |
|---|
| Nominal curr. P1 ###.# A |
|---|

Nominal current for pump 1.

The current is analysed by two different methods, each of which can lead to stopping of the pump. One of these detects a drop in the current in relation to the normal value, while the other detects high rates of change in the current.

Both stop functions are active by default but it is possible to deactivate each of them in the special control option menu for each pump. See 7.3.4 "Special control options" for details.

To switch off the APF function for one pump; deactivate both stop methods. This will block the APF on this pump.

If the difference between normal current and current at 'snoring' is little, the sensitivity can be raised with a special control option.

7.4.3 Forced pump down

If the inflow into the sump is long it may cause problems with sedimentation or gases. To avoid these types of problems it possible to start the pump sequence in advance before the starting level has been reached. Set the maximum time to store water in the menu Forced pump down delay.

| |
|--|
| Forced pump down delay #### min |
|--|

The maximum time between pump cycles.

It is possible to select a different stop level than normal in this case.

| |
|--|
| Forced pump down level @##.## m |
|--|

Level used when pumping down.

7.4.4 Flush valve

It is possible to connect a sprinkler valve to flush the walls of the sump regularly. Set the number of cleanings a day and cleaning duration to activate the function.

| |
|---------------------------------------|
| No of flushings per day ## |
|---------------------------------------|

Number of sprinkler flushings started each day.

Set any of the two values to zero to stop the function.

8 Flow calculations

The flow calculations are carried out independent of the pump control. It is not necessary to control the pumps to use the flow calculations. The flow calculations only use the level sensor, and optionally other analogue signals, look if the pumps are running using the response signals and then calculate flows and volumes.

8.1 Flows and volumes

The RTU calculates inflow, pumped flow and overflow and the volume for each flow. The volumes are displayed as continuous, daily and yesterday value. See 6.1 "Selecting report mode" for more information on how to change displayed data.

The menus which contain these data are located in the FLOWS AND VOLUMES menu group.

8.1.1 Inflow

The inflow menus show the calculated inflow and inflow volume to the station.

To calculate the inflow the pump sump form and nominal pump capacity must be defined.

| |
|-------------------------------|
| Inflow @#####.# l/s |
|-------------------------------|

The inflow menu

To get an accurate inflow calculation it is important that the level sensor show an accurate value and that the pump sump are correctly defined. This is especially important if the walls of the sump are sloping. The inflow is also dependant on the calculated capacity of the pumps.

It is possible to use an external flow meter to measure inflow and connect this to the generic analogue input. This sensor will replace the calculated inflow. See 5.3 "General analogue

" for information on how to activate this function.

8.1.2 Outflow / pumped flow

To calculate the outflow or pumped flow and volume the nominal pump capacity must be defined.

Calculation of the pumped flow is based on the calculated capacity and the response of the pump. In the case of multiple pump operation, pump factors must be stated to ensure the accuracy of the calculation. An expression of the proportion of the total pump capacity which represents the actual capacity, the pump factor is entered in the Capacity factor 2 pumps, (Capacity factor 3 pumps, Capacity factor 4 pumps) menus. See 8.4 "Capacity" for information on capacity calculation.

It is possible to use an external flow meter to measure pumped flow and connect this to the generic analogue input. This will replace the pump flow calculated by

the program. The flow will be used to monitor pump capacities and alarms and to calculate pumped volume. See 5.3 "General analogue

" for information on how to activate this function.

8.1.3 Outflow/pump flow calibration

The pump flow and volume need in some situations be adjusted. The calculation is based on the calculated capacity of the pump. The calculated pump capacity represents only one operating point for the pump and this may be different from the average pump capacity over a pump cycle. To adjust the difference and increase or decrease the calculated pump flow change the pump flow calibration menu.

| |
|---------------------------------|
| Outflow calib ###.# % |
|---------------------------------|

Pump flow calibration.

The formula used to calculate the pump flow is:

Pumped flow = Sum of calculated capacities for running pumps * Capacity factor for number of running pumps * Pump flow calibration.

8.1.4 Sump volume

The pump sump volume is calculated and presented in a menu.

| |
|----------------------------------|
| Volume sump #####.# m3 |
|----------------------------------|

Volume of pump sump.

This is done when the pump sump is defined. The volume is calculated using the areas and levels in the pump sump definition together with the level meter.

8.2 Volume pulse

It is possible to control external equipments like a water sampler or a chemical feeder based on different flows in the station. A digital output is used to start the equipment using a 3 second pulse. The pulse is created when the amount of water has passed.

| |
|---|
| Volume pulse #####.# m3/pulse |
|---|

Amount of water to make a pulse.

Select the water flow to use to create the pulse.

| |
|----------------------------------|
| Volume pulse src ##### |
|----------------------------------|

Menu to select pulse source.

The following options are possible.

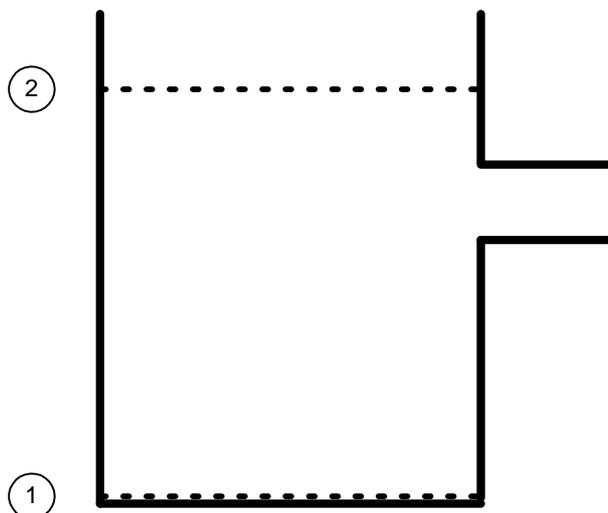
| | |
|------------------|--|
| Pumped flow | The pulse is created on the calculated pumped flow. |
| Inflow | The pulse is created using the calculated inflow. |
| Overflow | The pulse is created using the overflow. An extra pulse is created when the overflow starts. |
| Generic ana flow | The pulse is created using the generic analogue. |

8.3 Pump sump configuration

The shape and size of the sump must be defined to enable the RTU to calculate the pump flows and capacities. This is done by specifying the surface area at different levels. It is important to specify the surface areas at those levels at which the sump changes shape. The uppermost surface area should be located above the highest possible level in the sump. Up to five different levels can be specified. If the sump has straight walls, it may be sufficient to specify the surface area at two levels. The following are some examples of how the pump surface is defined for different sump shapes.

8.3.1 Sump with straight walls

The first example deals with a sump with straight walls. In this case, two surface areas are sufficient to define the configuration.



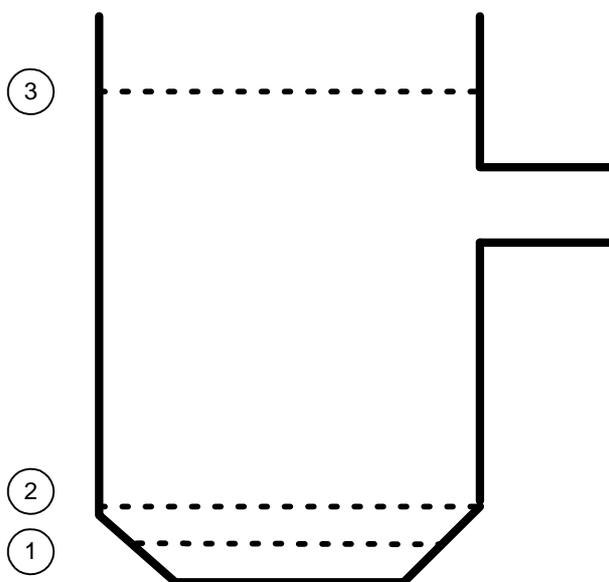
Pump sump with straight walls.

Assume that the calibration range is 0 - 3.50 m and that the surface area of the sump is 3.60 m². Select two levels at which to enter the area. For example, level (1) may be 0 m and level (2) 3.00 m. Specify 3.60 m² for both areas.

8.3.2 Sump with straight walls and tapered bottom section

section

The sump in this example has straight walls and a tapered bottom section. To define a sump of this shape, the surface area must be specified at three levels, at the bottom, at the transition point between the tapered and straight sections, and in the top section.

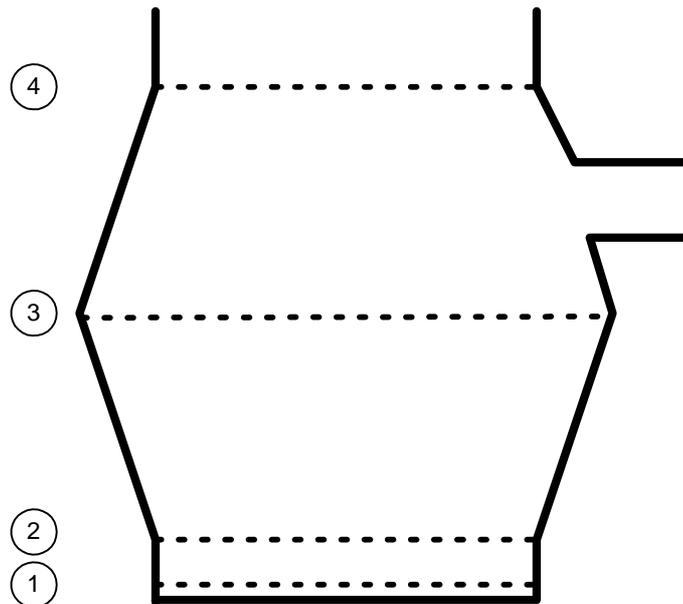


Pump sump with straight walls and tapered bottom section.

As before, assume that the calibration range is 0 - 3.50 m, also that the transition point between the tapered and straight sections is located at 0.45 m. Suitable levels at which to specify the surface area are thus (1) 0 m, (2) 0.45 m and (3) 3.00 m (see illustration).

8.3.3 Double-tapered sump with straight bottom section

In this case, the surface area must be specified at four levels for correct definition: at the bottom, at the transition from the straight to the tapered section, at the widest point and, finally, at the top edge.

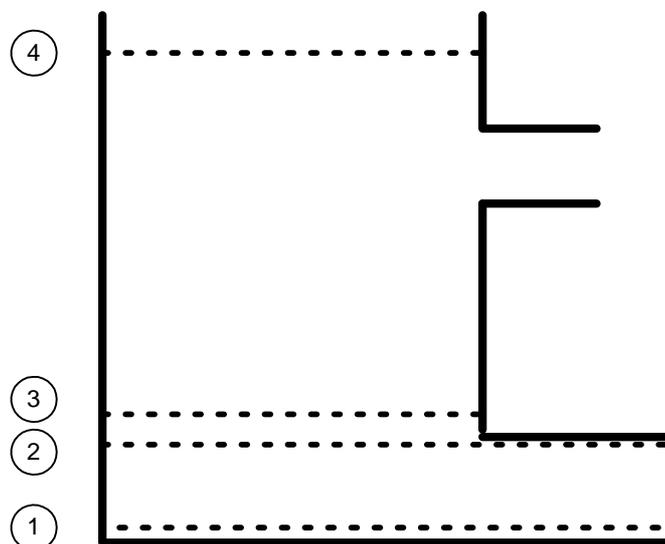


Double-tapered pump sump with straight bottom section.

The calibration range is 0 - 3.50 m. The surface area should be specified at levels of (1) 0, (2) 0.40, (3) 1.75 and (4) 3.00 m.

8.3.4 Pump sump with two areas

A sump of this shape must be defined in terms of four surface areas.



Pump sump with two areas.

This sump changes area once. To define it, the surface area must be specified at levels of (1) 0, (2) 1.70 (i.e. the highest level at which the sump has this area), (3) 1.71 and (4) 3.00 m. The calibration range is 0 - 3.50 m.

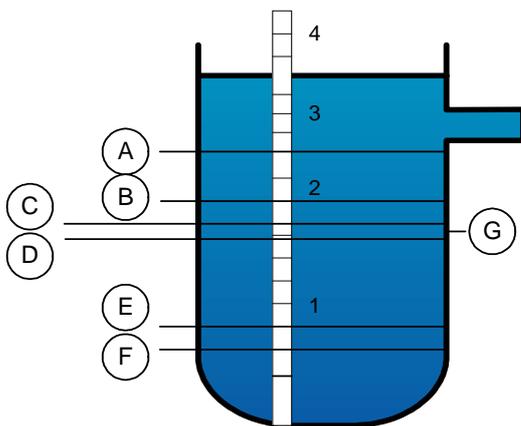
All menus for defining the pump sump are located in the CAPACITY... menu group and can be set from the central system.

8.4 Capacity

8.4.1 Capacity measurement

Capacity measurement is carried out when pumping lowers the level in the sump. For the purpose of calculation, the range in which it is to be carried out i.e. the levels at which measurement is to be started and stopped, must be specified. It is not possible to propose the exact location of the capacity measurement range since this is a function of many factors, which may be unique to each pumping station. To ensure accuracy, however, the measurement period must not be too short. Capacity measurement must take at least 30 seconds and should not be longer than 9 minutes.

As a guideline, the range should be approx. 15% of the pumped range. Capacity measurement should commence somewhat below the lowest starting level, or Starting level 1, while the distance between Starting level 1 and the start of capacity measurement is usually approx. 10% of the pumped range.



A = Start level 2
 B = Start level 1
 C = Upper level
 D = Lower level
 E = Stop level 2
 F = Stop level 1

G = Capacity measurement

Choice of range for capacity measurement.

In the illustration above, the measurement range is 0 - 3.50 m. The Starting level 1 is 2.00 m and the Stopping level 1 is 0.50 m. The pumped range is calculated as follows:

Pumped range = Starting level 1 - Stopping level 1.

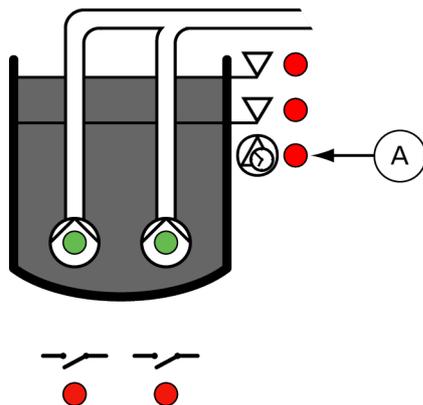
The pumped range in the example is 1.50 m. The upper level for capacity measurement should be somewhat below Starting level 1. In the normal case, the distance between Start level 1 and the upper capacity measurement level is 10% of the pumped range. Ten percent of 1.50 m is 0.15 m, making the upper level 1.85 m (2.00 m - 0.15 m). The distance between the upper and lower capacity measurement levels is usually 15% of the pumped range. Fifteen percent of 1.50 m is 0.22 m, making the lower level 1.63 m (1.85 m - 0.22 m).

The example above shows how the capacity measurement parameters can be set. It is important to ensure that measurement is carried out over a sufficiently long time, which should range from 30 seconds to 9 minutes. If the time taken to lower the level below the measurement range is shorter or longer, the range must be increased or decreased appropriately.

The capacity measurement limits are entered in the Upper Level cap. and Lower level cap menus.

The calculated capacity of the particular pump is based on a mean value calculated over a number of pumping cycles. The number of cycles is specified in the Number of calculations menu. In the normal case, calculation is based on 5 cycles; however, this may need to be increased if the inflow varies significantly. If the number of pumping cycles is zero, the RTU will use the nominal capacity as the calculated value.

An LED indicating that capacity measurement is in progress is mounted on the front panel of the RTU beside the pump operation Led.



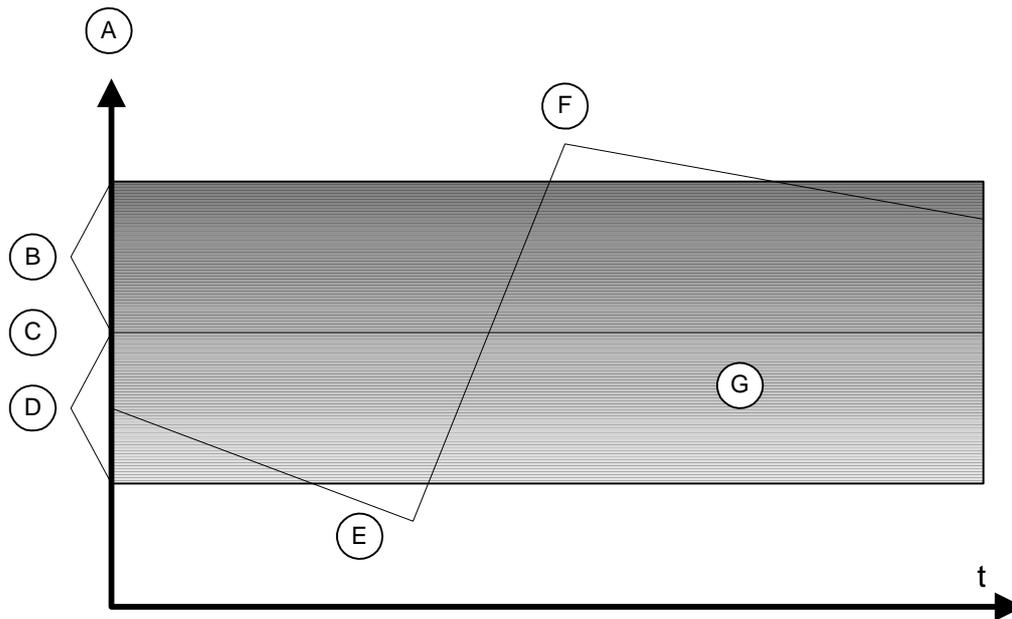
A = Capacity measurement is in progress when LED light and one or more pumps is running.

An LED on the front panel indicates capacity measurement in progress.

8.4.2 Monitoring of pump capacities

The calculated pump capacities are displayed in the Calc cap. P1 to Calc cap. P4 menus. The RTU can monitor the calculated pump capacities continuously to compare them with the nominal values. The nominal capacities should be entered in the Nom. cap. P1 to Nom. cap. P4 menus for this purpose. The nominal pump capacities are available, for example, from the pump curves. The amount by which the calculated capacity may deviate from the nominal before a capacity deviation alarm is generated should also be specified.

A capacity alarm will be generated if the calculated capacity deviates from the nominal value by more than the permissible amount.



- A = Capacity
 B = Capacity deviation
 C = Nominal capacity
 D = Capacity deviation
 G = Calculated capacity must vary within shaded area
 E = Low capacity alarm
 F = High capacity alarm

Calculated pump capacity.

The example above relates to a pump, which is in need of service. The pump capacity is falling steadily and an alarm is generated when the level falls below the low capacity alarm limit (nominal capacity - capacity deviation). The pump is serviced and the capacity rises dramatically. After a time, the level exceeds the high capacity alarm limit (nominal capacity + capacity deviation) before returning to the permissible level.

The capacity calculation and recording menus are located in the Calc. cap. P1 to Calc. cap. P4 of group menu CAPACITY. The settings can also be entered from the central system.

8.5 Overflow

The monitoring and recording of overflow conditions is an important element of pump station monitoring. The overflow flow, overflow time, number of overflows and overflow quantity are recorded in the RTU. An overflow alarm is generated and recorded in its own Overflow alarm log when overflow occurs. All menus which process overflow monitoring and recording are located in the OVERFLOW... menu group.

8.5.1 Overflow alarm log

In addition to the ordinary alarm log, overflow alarms are stored in a special log for overflow alarms only. The overflow alarm log is located in the FLOWS... group menu

**Overflow alarm
log**

Overflow alarm log menu

Follow these steps to browse the overflow alarm log:

- | Step | Action |
|-------------|--|
| 1 | Display the Overflow alarm log menu, and press OK. Result: The first alarm is shown in the display. |
| 2 | Browse the log with the Up and Down arrows. |

Alarms cannot be deleted from the overflow alarm log.

8.5.2 Setting of overflow monitoring

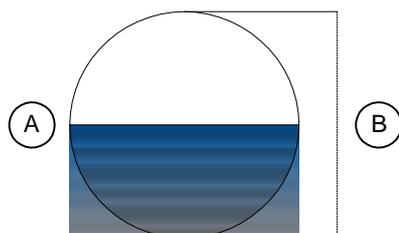
A conventional level switch or an overflow transmitter can be used to record overflow. If a switch is chosen, the RTU will record the overflow period and the number of overflows. There is a delay of 15 sec before the calculation starts to prevent faulty values. A transmitter should be installed if the overflow flow is also to be recorded since this device will provide more accurate values than a level switch.

When selecting a transmitter, it is important to specify a type, which has a very high accuracy and is insensitive to changes in atmospheric pressure, fouling, floating sludge and foaming. The transmitter must also be completely submersible.

To enable the RTU to calculate the overflow quantity, the height of the overflow range must be entered and the overflow curve defined. This is done by specifying the flow, which will occur at different overflow levels. Instead of entering the values for the different overflow segments this can be done by the program in order to ease your calculations in the case of rectangular or V-notch weir.

The type of weir that is used are entered in the Weir select menu, rectangular for rectangular weir, V-notch for the V-notch shaped weir and manual if the values are to be entered manually.

The overflow range is the height of the overflow outlet in the pump sump. The overflow level, which varies between 0 and the top of the overflow range, is the level in the overflow outlet under overflow conditions.



A = Overflow level
B = Overflow range

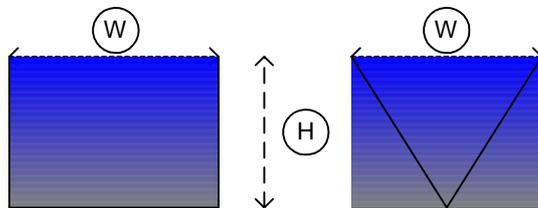
Overflow level and overflow range.

First enter the overflow range. This is entered in the Overflow range menu in the OVERFLOW... menu group.

8.5.3 Using a weir to specify overflow segments

If the Rectangular or V-notch are selected, the width of the weir have to be entered in the Weir width menu, and the discharge coefficient associated with the current weir have to be entered in the menu Discharge coeff.

The discharge coefficient is a value in the range of 0.00-1.00 that describes certain properties of the weir such as the shape of the edge, the dimensions of the menu and of the approach and more. The typical value for rectangular weir is $D_c \approx 0.62$, and for V-notch weir $D_c \approx 0.58$, but it may differ. The manufacturer of the weir should provide this coefficient. What is described in words above is also explained by the following figure except for the D_c .



W = Weir width.

H = Overflow range.

Left = Rectangular, right = V-notch.

8.5.4 Setting the overflow segments manually

The overflow curve parameters are then entered. Up to 20 overflow levels can be specified. Although the RTU can calculate the curve for only two levels, it will be more accurate if the values for several levels are entered.

Distribute the chosen levels evenly over the overflow range. If the flow is only specified at two overflow levels, the levels midway in the overflow range and the max. level should be chosen.

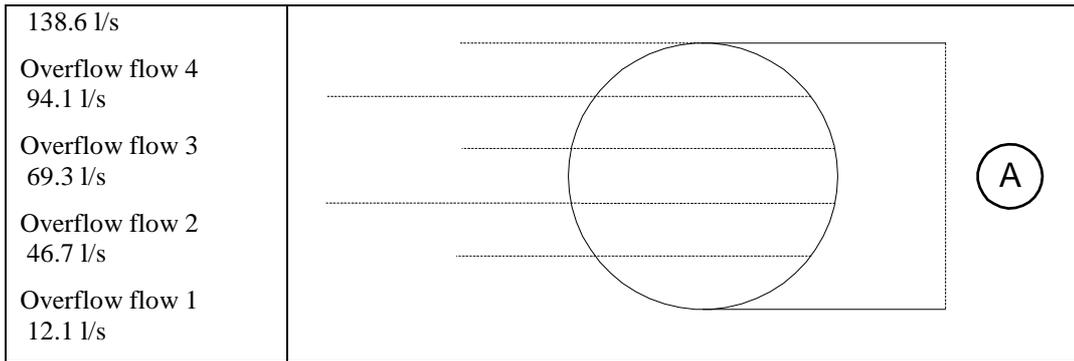
| | |
|---|--|
| Overflow flow 2 138.6 l/s Overflow flow 1 69.3 l/s | |
|---|--|

A = Overflow range

Flow curve defined by two levels.

In the example below, the flow is specified at 5 different levels.

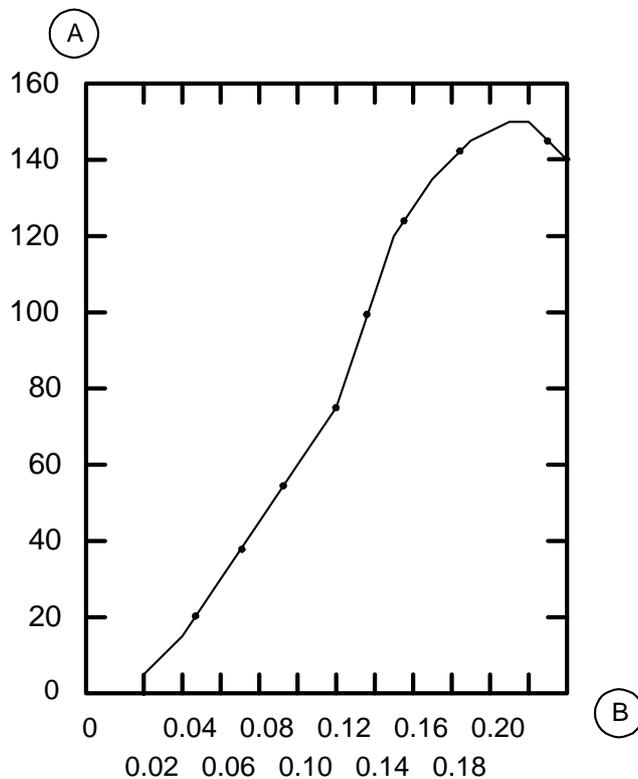
| | |
|-----------------|--|
| Overflow flow 5 | |
|-----------------|--|



A = Overflow range

Flow curve defined at five levels.

Finally, the figure below shows a typical overflow curve calculated on the basis of ten entered values.



A = Overflow flow l/s

B = Level, m

Typical overflow curve.

The overflow curve will not be correct if the overflow flow is obstructed or if there is not a free fall to the receiver.

The overflow range and flow can be set from the central system.

9 Blocking

The blocking functions in the RTU are used mainly to prevent overflows in unsuitable stations. When the flows from several stations converge and the station there is not dimensioned to handle the total flow this function may be used to improve the situation. It is also used to avoid overflows in especially sensitive receivers.

The blocking functions work in principle by sending messages between the RTU's to stop one or more of the stations from pumping. The messages may be sent by telephone calls or by fixed line. The condition that is used to generate and send the blocking message is highly configurable. The action carried out may be to stop one or more pumps or to set an output signal that does something else. The flexibility of the function makes it possible to use it in other ways than blocking.

9.1 Sending blocking commands

9.1.1 Blocking conditions

The blocking conditions are the rules the RTU use to decide when to send a blocking command, either dialled or fixed. There are two independent sets of conditions and it is possible to select which stations to send the blocking command to on each set.

The conditions inputs that are used to generate a blocking of another RTU is given in the menu Block condition. One or more conditions can be chosen.

```
Block1 condition
#####
```

Blocking conditions

Two block condition menus exist. The menu has the options below:

| Menu option | Blocking condition |
|------------------|---|
| Px failed | Blocking is activated if the pump is failed. Pump has a leak alarm, trip alarm, high temperature alarm or blocked by a low current alarm. |
| Px switched off | Blocking is activated when the pump is switched off manually. |
| Block levels | Blocking levels used. Blocking is activated when the sump level reaches the blocking level. |
| High level | Blocking is activated when the sump level reaches the high level alarm limit. |
| Extrem high lev. | Blocking is activated when the sump level reaches the extra high level alarm limit. |
| High level input | Blocking is activated when the sump level reaches the high level float. |

| Menu option | Blocking condition |
|------------------|--|
| Overflow input | Blocking is activated when the sump level reaches the overflow level float/sensor. |
| Power fail input | Blocking is activated when power fail is detected. |
| Block input | Blocking is activated when a special digital input is activated. |
| Gen ana level | General analogue levels used. Blocking is activated when the general analogue reaches the start level. |

In the menu Block logic it is possible to select if all conditions or only one condition need to be active to start the blocking. Select "or" if only one condition is needed. Select "and" if all conditions are needed.

```
Block 1 logic
#####
```

Select "and" or "or".

Two menus with block logic exist.

9.1.2 Selecting stations to block in dialled blocking

These menus are only used in dialled communication. Select the stations to send blocking commands to by entering the telephone numbers to the stations in the telephone menus.

```
Telephone #1
12345678
```

Telephone number one of six.

Select telephone number to use by the two blocking conditions by setting the menu:

```
Block1 tele# use
000101
```

Telephone numbers 1 and 3 used by blocking command 1.

Two menus that select telephone numbers exist.

9.1.3 Blocking using level sensor

If blocking levels are selected as conditions also set the level to start and stop the blocking using the level sensor.

```
Blocking level
@##.## m
```

Send blocking command on this level.

```
Unblocking level
@##.## m
```

Send unblocking command on this level.

9.1.4 Delaying the block messages

The blocking messages are delayed before sent by two menus, block delay and deblock delay. If for example a level float is used as condition the delays are needed to avoid too many telephone calls.

```
Block delay
#### s
```

Delay for sending a block command.

```
Deblock delay
#### s
```

Delay for sending a unblock command.

9.2 Receiving a blocking command

9.2.1 Blocking status

In normal state, the menu Block status displays the text Not Blocked. If the RTU has been blocked by another RTU the text will be changed to Blocked. When the RTU has been deblocked the text Not blocked is shown again.

```
Blocked status
Blocked
```

Station blocked.

To reset the blocking, change the value to "not blocked". This menu can also be used to block the station. This can be used for example to test the blocking functions.

9.2.2 Blocking actions

It is possible to choose activity when an RTU has received a blocking command from another RTU. The pumps are normally blocked when a remote block command is received. To disable blocking of a pump, set the "Not tele blocked" option in the special control menu for the pump. See 7.3.4 "Special control options" on how to do this.

The blocked output is activated by default. The output has to be selected on most programs. See 3.2.4 "Selecting output functions".

9.2.3 Blocking data

Blocking time and events are displayed in two menus. This data are also sent to report.

9.2.4 Selecting stations to block in fixed line blocking

These menus are only used in fixed line communication. Select the station to receive blocking commands from by entering the station fixed line ID. The ID to enter is found in the menu "ID fixed line" in the sending station.

| |
|----------------------------|
| Blocked by ID @# |
|----------------------------|

ID number of station blocking this station.

Also select if block 1 condition or block 2 condition in the sending station should block this station.

| |
|------------------------------|
| Blocked by func 01 |
|------------------------------|

Blocking function 1 selected to block this station.

Blocking commands in fixed line communication is using the AquaCom telegram TIO. In this telegram there are possibilities to get values from other RTUs connected to another fixed line network. See the Mtc-Com manual on how to use this function.

9.3 Blocking safety

If the transmission fails, the RTU attempts to reach the other RTU as long as the blocking conditions are fulfilled. To increase safety two menus are used. The first in the sending/blocking RTU is a repeat of the blocking command. The second in the receiving/blocked RTU is a timeout of the blocked command. Both or none of the menus has to be used.

| |
|----------------------------------|
| Repeat block. #### min |
|----------------------------------|

Menu to repeat the blocking command.

Set this menu and the RTU will send repeated blocking commands with this interval. Do not set this menu shorter than the time it takes to dial all blocked stations.

| |
|-----------------------------------|
| Timeout block. #### min |
|-----------------------------------|

Menu to remove the blocking command.

The timeout of the blocking will unblock (remove the blocking command) from the station. If the communication for some reason fails the RTU will resume normal pumping after this time. When the blocking command is repeated the time out will restart. The time out has to be longer than the repeat block time in the blocking RTU.

10 Energy

10.1 Calculated data

The energy calculations show used energy in kWh, current power in kW and specific energy in kWh/m³. The specific energy is the cost of pumping a specific amount of water. It is calculated by using the pumped flow and current power consumption.

| |
|--------------------------------|
| Energy ##### kWh tot |
|--------------------------------|

Used energy.

Energy is shown as total, daily and yesterdays values.

| |
|----------------------------|
| Power #####.# kW |
|----------------------------|

Current power.

| |
|---|
| Specific energy ##.### kwh/m3 |
|---|

Calculated specific energy.

The specific energy is the key cost of pumping. This value and the power are calculated momentarily and presented as historical trend.

10.2 Measuring methods

The energy calculation requires either a pulse input or current sensors or both. Select measuring method in the menu:

| |
|-------------------------------|
| Energy method ##### |
|-------------------------------|

Menu for selecting measuring method.

Options are:

| | |
|-----------------|--|
| Pulse only | Measured values are calculated using only a digital input pulse. |
| Current & pulse | Measured values are calculated using both a digital input pulse and the currents of the pumps. The pulse is used for calculation of the consumed energy and the pump currents are used for calculation of the used effect and specific energy. |
| Current only | Measured values are calculated using only the currents of the pumps. |

If currents are used as energy measuring method the power factor for the pumps and the voltage of the pumps is needed for the calculation. As the power factor of the pumps may differ from installation to installation there is a menu for each pump where the power factor of the pump may be entered. The power factor menus are Cos phi pumps. The value for different pumps is often printed on the

fact sheet belonging to the pump. The energy is calculated with the use of the value in menu Voltage and the measured currents of the pumps.

If a pulse input is used as energy measuring method the only value needed is the pulse scale. Enter the energy of each pulse in the menu:

| |
|--|
| Energy scale ##.### kWh/pulse |
|--|

Scaling of energy pulse.

11 Counter

A pulse with duration exceeding 10 ms can be connected to the RTU to count pulses. This could be used for example to measure precipitation (see 20 "Appendix F - Connection" for information on the terminal block to which the pulse must be connected). Start by entering the value per pulse in the Counter scale menu. See the supplier's documentation for information regarding this value.

When the amount per pulse value has been entered, the quantity will be recorded in the RTU. The recorded value will be displayed in the Counter menu, which is the first menu in the group menu of the same name. The form in which the value is reported (daily or continuous) will depend on how the RTU is configured. See the beginning of this chapter for instructions on how to select the reporting mode and how to delete recorded values.

An alarm limit can also be entered in the Max value 5 min or in the Max value 24h menu. The limit should be stated in quantity for a 5-minute or a 24-hour period. The COUNTER group menu contains menus for entering settings and reading out recorded values. All settings can be sent from the central system.

12 Function timers

The program is equipped with two timer functions. Each timer function is controlled by one digital input and controls one digital output. The two timer functions are equal.

There is one menu for each timer function to select operation for the timer. There are six functions to select and there are also two menus for each timer to select time delays.

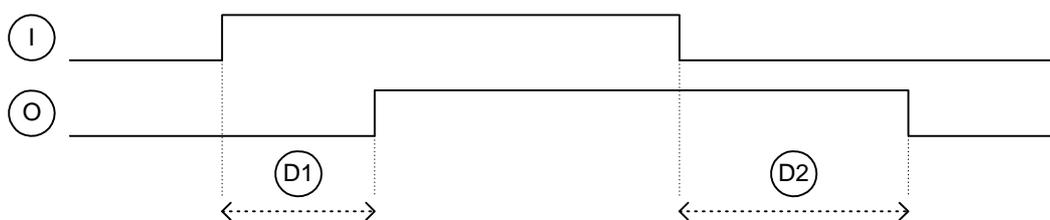
I = Timer input signal.

O = Timer output signal.

D1 = Pulse delay.

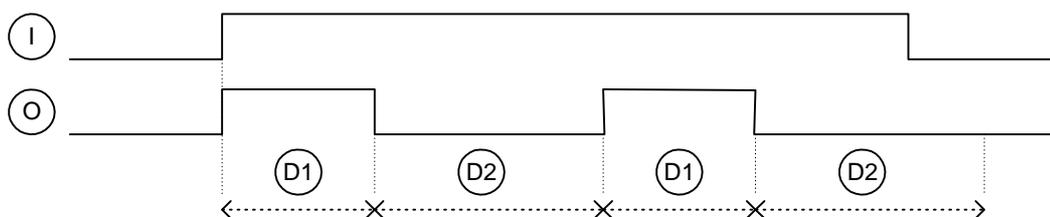
D2 = Pause delay.

Option: On/off delay



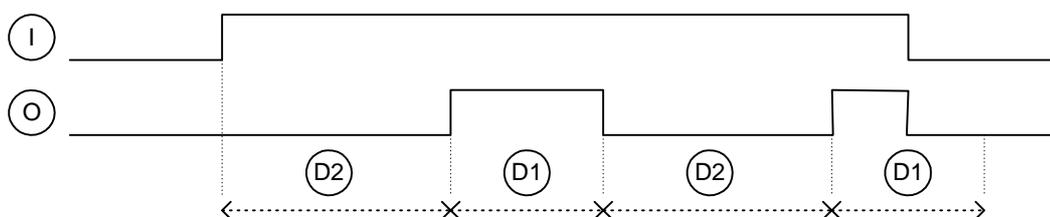
This option will delay the input to the output signal.

Option: Pulses



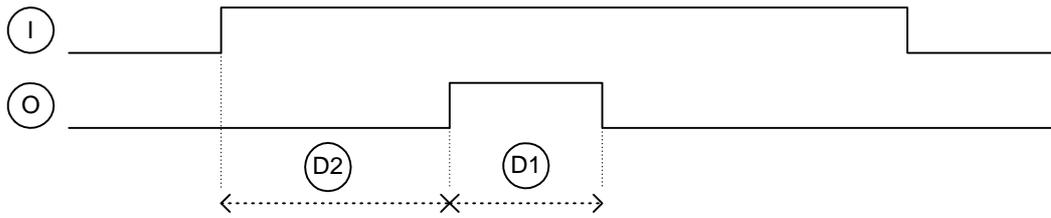
This option will create pulses on the output as long as the input is active.

Option: Pulses delayed



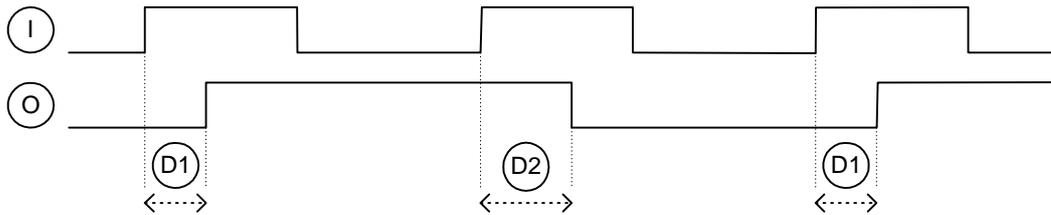
This option will also create pulses on the output but start with the delay.

Option: 1 pulse



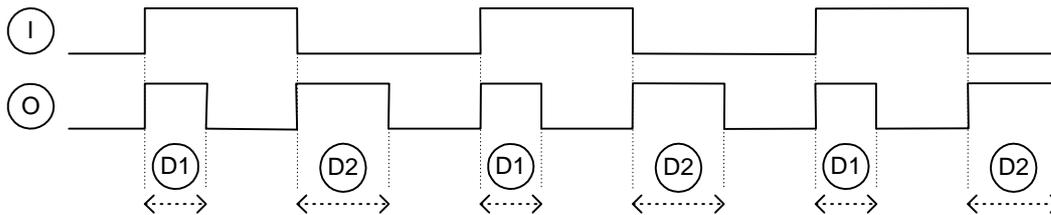
This option will create one single output pulse.

Option: Halve pulse



This option will create pulses on the output with half the frequency as the input.

Option: Double pulse



This option will create pulses on the output with double frequency as the input.

13 Safety

13.1 Personal safety



N.B.

Ensure that personnel cannot come in contact with live cabling or terminal blocks in the course of connection or service work. Maximum caution must be exercised when working on the digital outputs.

13.2 Password function

Two password menus are included in the first menu group to prevent unauthorised personnel from altering settings in the RTU. The function is activated by entering the appropriate four-digit code in the New password menu. When an operator wishes to alter a setting in any menu using the buttons on the front panel, the code must first be entered before the data can be changed.

Remember that unauthorised personnel must also be prevented from changing settings from the central system to ensure full protection against unauthorised alterations.

See 3.1.6 "Password" for a description of this function. **Personnel alarm**

The purpose of the personnel alarm function is to increase personnel safety when working in the pumping station. Always activate this alarm when connecting the RTU. See 4.3 "Personnel alarm" for a description of this function.

14 Service and maintenance



N.B.

Ensure that personnel cannot come in contact with live cabling or terminal blocks in the course of connection or service work. Maximum caution must be exercised when working on the digital outputs.

14.1 Contacting Support

Before contacting ITT Flygt, Technical Support, make sure to have the following information available.

Email: MonitoringControl.Support@ITT.com

| Information | Location |
|---|--|
| Product designation (type of hardware) Example: APP 721 | Lower right-hand corner of the front panel. |
| Serial number Example: 012345678-1234 | Label with bar code and serial number: <ul style="list-style-type: none"> • (Front mounted RTU) Label is placed on the back of the RTU. • (Wall mounted RTU) Label is placed together with the terminal blocks. |
| Program name | First menu |
| Project number | Project nr menu |
| System version | System information menu, see example below. |
| Program identity | System information menu, see example below. |
| Type of connection | Communication menu: <ul style="list-style-type: none"> • Station number • ID number fixed • Communic. COM1, COM3 • Speed COM1, COM3 • Protocol on COM1, COM3 • RTS delay COM1, Com3 • Telno. PAD/SMSC (Only needed if it is a dialled RTU). |
| Telephone number to the RTU | |

| | |
|---|---------------------------------------|
| Type, version and revision number of central system | Central system, for example AquaView. |
|---|---------------------------------------|

| | |
|----------------|----------------|
| System: | 3.07.00 |
| ProgID: | 7036 |

Example of System information menu.

14.2 Restarting the RTU

The RTU program mode channel is used if a situation occurs in which the RTU must be cold or warm started. Select the Cold start or Warm start option in the RTU program mode channel. Restarting will take 20 to 90 seconds depending on the program. Remember that the RTU set points must be re-entered following a cold start.

14.3 Remote programming

If the RTU is called, a new program can be downloaded over the telephone line. Select which the COM port use in the RTU program mode channel. The RTU must be started as described under 14.2 "Restarting the RTU" when the new software has been downloaded.

14.4 Battery life

An external uninterruptedly power source (UPS) can be connected to the RTU. This means that the RTU will continue to record data in the event of a power failure. The duration of the power available under these conditions will depend on the type of battery. The life of a battery normally ranges from two to five years (see battery manufacturer's specifications).

14.5 Replacement of components

Contact ITT Flygt, Technical Support, if hardware components need to be replaced.

14.6 Service in pumping station

A number of recommendations must be followed when carrying out service in the pumping station, for example when removing pumps for maintenance. Start by resetting the alarm mode from remote to Local, to avoid the possible transmission of false alarms to the alarm or central system. Personnel alarms will be sent out regardless of which alarm mode is selected (see under Alarms in the chapter headed Changing alarm mode. The Remote mode should be reselected on completion of service work.

In the case of a dial-up workstation with a spare telephone, an answering delay can be entered in the RTU to allow time for answering the phone. The delay is entered in the Response delay dialled menu.

Changes in settings, for example in pump control, which will apply only during the actual maintenance work, can be carried out most easily using the buttons on the RTU front panel. This makes it easy to restore all of the settings by re-entering the set points from the central system when work has been completed.

Before altering values in RTU, write down the original values. This is especially important in the absence of a Central system.

15 Appendix A – Troubleshooting



N.B.

Ensure that personnel cannot come in contact with live cabling or terminal blocks in the course of connection or service work. Maximum caution must be exercised when working on the digital outputs.

In the event of problems with the RTU, follow the checklists in this chapter. If the problem remains, contact ITT Flygt, Technical Support, see 14.1 "Contacting Support".

15.1 Common problems

The following are some of the most common problems dealt with by Technical Support.



Central system is receiving no data

First determine if the problem is in the central system or in the RTU. Check if data is being received from other RTUs. If so, the problem is probably in the RTU. Otherwise, see the central system documentation.

See Checking communication below if the problem appears to be with the RTU.



Only one pump starts regardless of the level in the sump

First check if any of the pump alarms is active, in which case the pump is blocked.

Next, check the pump control setting.

- Is a starting level value missing?
- Check that the stopping level values are correct.
- Check that the Max. number of pumps running menu is set to '1'.

If the pump control parameters are correct, check the connection of the unit as described in the general installation instructions and Appendix - Connection.



Pump does not start although starting delay has long elapsed

Check that the random starting range is not too big.

Check the connection of the unit as described in the general installation instructions and Appendix - Connection.



Pump currents are not recorded

Check the pump current settings. See under Pump currents in the chapter headed Monitoring and measurement.

Check that the pump operating responses are connected correctly. The currents are recorded only when pump is running.



No level signal from transmitter

Start by checking that level transmitter settings have been entered. See under Setting of transmitter in the chapter headed Starting the RTU.

Check that the transmitter is correctly installed, then carry out test measurement.

15.1.1 Checking communication

Start by checking the modem connections. Check that the cables are connected securely. Remember to check the supply voltage to an external modem.

Check the communication led on the front panel. These should flash when the unit is transmitting and receiving data. Reference: For further information, see 3.3.1 "Communication status led".

Modem with dedicated connection between RTU and central system:

Check the modem led to determine if the modem is transmitting and receiving data. See the modem manual for details.

Modem with dial-up connection between RTU and central system:

First check the telephone connection. Connect a telephone in parallel with the RTU. Test the connection by calling another number.

Next, call the RTU from an ordinary telephone to see if the RTU answers.

15.1.2 Checking level transmitter signal

Check for a voltage of at least 8 V d.c. across the terminals.

Lift the transmitter out of the water and check that it is delivering a 4 mA current signal. Check that the signal changes when the transmitter is again immersed in the water.

Note that transmitter does not require to be calibrated; only the Max. level and Min. level settings require to be set.

15.1.3 Testing digital inputs

To test a digital input, activate a signal, such as a motor protection. Check that the DI status in the DI status menu in the major menu group is changed and that the LED lights.

15.1.4 Testing status and alarm LEDs

To test the status and alarm LEDs on the front panel, press and hold the alarm acknowledgement button until the LEDs begin to flash. The LEDs will return to normal operation when the button is released.

15.1.5 Checking supply voltage

Check the power supply unit connections. Measure the supply voltage at the terminal block.

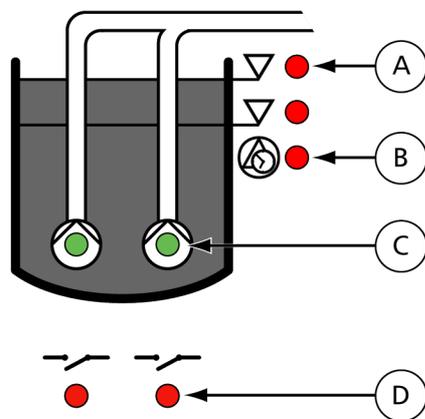
16 Appendix B – Front panel Led

16.1 Alarm panel Led

Led displays the alarms on the annunciation panel as follows:

16.2 Operation Led

The following Led indicates pump operation:



A = Indicates when the start level is reached for respective pump

B = Capacity measurement in progress

C = Pump running

D = Pump start output active

Operating indications.

Alarm LED

| Number | Description |
|--------|---|
| 1 | Overflow. |
| 2 | Power failure. |
| 3 | High level sensor or float. |
| 4 | Low level sensor or float. |
| 5 | External failue P1.1. Tripped pump, high temperature, leakage or pump switched off. |
| 6 | External failue P1.2. Tripped pump, high temperature, leakage or pump switched off. |
| 7 | External failue P2.1. Tripped pump, high temperature, leakage or pump switched off. |

| | |
|----|--|
| 8 | External failue P2.2. Tripped pump, high temperature, leakage or pump swiched off. |
| 9 | Internal failue P1.1. High/low capacity, high/low current, service, no response or maximum starts. |
| 10 | Internal failue P1.2. High/low capacity, high/low current, service, no response or maximum starts. |
| 11 | Internal failue P2.1. High/low capacity, high/low current, service, no response or maximum starts. |
| 12 | Internal failue P2.2. High/low capacity, high/low current, service, no response or maximum starts. |
| 15 | This station is remote blocked or station is controlled by remote command from status. |
| 16 | New alarms in alarm log. |

17 Appendix C – List of menus

The list is composed as follows: The left-hand column, Display, shows the appearance of the display in the particular menu. The # character indicates those positions which may/should indicate values. The next column shows the text displayed in the set point setting in the central system, and the range and options which the menu may afford.

Menus

GSP 421 2.05

| No | Menu Name | Specification | Description |
|----|---------------------------------|---------------|---|
| 1 | GSP 421 2.05 ####-##-## #:## | Writable | Shows program name and date/time. Date and time must be set in a cold started system before it activates the controlling. |

GENERAL SETUP

| No | Menu Name | Specification | Description |
|-----|----------------------------|--|---|
| 2 | GENERAL SETUP ... | Read only | Setup of general parameters. |
| 2_1 | Display channel ##### | Writable Alternative 0 = User 1 = Parameter 2 = Service | Selection of showed channels. User - Show only result channels. Parameter - Show all application set-up channels. Service - Show all channels including system channels. |
| 2_2 | ☒ Language ##### | Writable Alternative 0 = English 1 = Svenska 2 = Français 3 = Dutch 4 = Deutsch 5 = Italiano 6 = Magyar 7 = Español Central System Text Language | Select language to show and use in the display for this RTU. 0=English, 1=Svenska, 2=Français, 3=Dutch, 4=Deutsch, 5=Italiano, 6=Magyar, 7=Español. |
| 2_3 | Show functions ##### | Writable Alternative 1 = Person.+burglary 2 = Currents+APF 3 = Not used 4 = Adv. pump contr. 5 = Flush+vol. pulse 6 = Capacity 7 = Overflow 8 = Service larm 9 = Blocking in+out 10 = Energy 11 = Counter 12 = Test alarm 13 = Timers 14 = Not used Central System Text Show functions | Select the functions that shall be visible in the display. |
| 2_4 | System: Progid: | Read only | Identifies the RTU program unique ID. Quote this information together with the program name in channel 1 when you are calling ITT Flygt support regarding software questions. |
| 2_5 | Project number #####.## | Writable Interval 0.00 To 999999.99 Central System Text Project number | Enter the ITT Flygt project number. For example 97M123A will be 97123.01. |

| | | | |
|-----|------------------------|---|--|
| 2_6 | Program mode ##### | Writable Alternative 0 = Normal run 1 = Warm start 2 = Cold start 3 = Remote load COM3 4 = Remote load COM1 5 = Save setpoints 6 = Load setpoints 7 = Save defaults 8 = Normal locked Central System Text Program mode | Selections: 0 = Normal run. 1 = Warm start (no data loss). 2 = Cold start (remove data). 3 = Remote COM3. 4 = Remote COM1. 5 = Save setpoints (to file). 6 = Load setpoints (from file). |
| 2_7 | Enter password #### | Writable | Used to logging in to a RTU with activated password. If a new password is selected it protects all channels. |
| 2_8 | New password #### | Writable | Sets a new password. To change the password you need to enter the current password first. Password is disabled by entering a zero. |

PHYSICAL SETUP

| No | Menu Name | Specification | Description |
|-----|---------------------------------|--|---|
| 3 | PHYSICAL SETUP ... | Read only | Setup of digital and analogue signals. |
| 3_1 | Status inputs ##### | Read only Alternative 1 = Di 01 2 = Di 02 3 = Di 03 4 = Di 04 5 = Di 05 6 = Di 06 7 = Di 07 8 = Di 08 9 = Di 09 10 = Di 10 11 = Di 11 12 = Di 12 13 = Di 13 14 = Di 14 15 = Di 15 16 = Di 16 | System channel. This channel shows the status of the digital inputs. '0' = Input not active, '1' = input active. Change to write mode to see the function is of each input. |
| 3_2 | Inverse inputs ##### | Writable Alternative 1 = Di 01 2 = Di 02 3 = Di 03 4 = Di 04 5 = Di 05 6 = Di 06 7 = Di 07 8 = Di 08 9 = Di 09 10 = Di 10 11 = Di 11 12 = Di 12 13 = Di 13 14 = Di 14 15 = Di 15 16 = Di 16 Central System Text Inverse inputs 1-16 (0=NO, 1=NC) | System channel. Select which digital input signals to invert. '0' = NO, normal open contact and '1' = NC, normal closed contact, inverted. |
| 3_3 | Function inp. 11 ##### ## | Writable Alternative 0 = Not used 1 = Overflow sensor 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text | Function on input signal 11. Select function: 0=Not used, 1=Overflow sensor, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |

| | | | |
|-----|---------------------------------|---|--|
| | | Function on input 11 | |
| 3_4 | Function inp. 12 ##### ## | Writable Alternative 0 = Not used 1 = Counter pulse 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 12 | Function on input signal 12. Select function: 0=Not used, 1=Counter pulse, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_5 | Function inp. 13 ##### ## | Writable Alternative 0 = Not used 1 = P1.1 Off switch 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 13 | Function on input signal 13. Select function: 0=Not used, 1=P1.1 Off switch, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_6 | Function inp. 14 ##### ## | Writable Alternative 0 = Not used 1 = P1.2 Off switch 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 14 | Function on input signal 14. Select function: 0=Not used, 1=P1.2 Off switch, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_7 | Function inp. 15 ##### ## | Writable Alternative 0 = Not used 1 = P2.1 Off switch 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 15 | Function on input signal 15. Select function: 0=Not used, 1=P2.1 Off switch, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_8 | Function inp. 16 ##### ## | Writable Alternative 0 = Not used 1 = P2.2 Off switch 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse | Function on input signal 16. Select function: 0=Not used, 1=P2.2 Off switch, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |

| | | Central System Text Function on input 16 | |
|----------|---------------------------------|--|---|
| 3_9 | Function inp. 18 ##### ## | Writable Alternative 0 = Not used 1 = P1.1 Leakage 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote Central System Text Function on input 18 | Function on input signal 18. Select function: 0=Not used, 1=P1.1 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 3_1 0 | Function inp. 20 ##### ## | Writable Alternative 0 = Not used 1 = P1.2 Leakage 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote Central System Text Function on input 20 | Function on input signal 20. Select function: 0=Not used, 1=P1.2 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 3_1 1 | Function inp. 22 ##### ## | Writable Alternative 0 = Not used 1 = P2.1 Leakage 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote Central System Text Function on input 22 | Function on input signal 22. Select function: 0=Not used, 1=P2.1 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 3_1 2 | Function inp. 24 ##### ## | Writable Alternative 0 = Not used 1 = P2.2 Leakage 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote Central System Text Function on input 24 | Function on input signal 24. Select function: 0=Not used, 1=P2.2 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 3_1 3 | Function inp. 25 ##### ## | Writable Alternative 0 = Not used 1 = Low float sump 1 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote Central System Text Function on input 25 | Function on input signal 25. Select function: 0=Not used, 1=Low float sump 1, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| | Function inp. 27 | Writable | Function on input signal 27. Select function: |

| | | | |
|----------|---------------------------------|---|---|
| 3_1 4 | ##### ## | Alternative 0 = Not used 1 = Low float sump 2 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 27 | 0=Not used, 1=Low float sump 2, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_1 5 | Function inp. 28 ##### ## | Writable Alternative 0 = Not used 1 = Timer 1 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 28 | Function on input signal 28. Select function: 0=Not used, 1=Timer 1, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_1 6 | Function inp. 29 ##### ## | Writable Alternative 0 = Not used 1 = Timer 2 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 29 | Function on input signal 29. Select function: 0=Not used, 1=Timer 2, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_1 7 | Function inp. 30 ##### ## | Writable Alternative 0 = Not used 1 = Personnel onsite 2 = Spare alarm 3 = Intruder sensor 4 = Intr.sens+pers. 5 = Block remote 6 = Energy pulse Central System Text Function on input 30 | Function on input signal 30. Select function: 0=Not used, 1=Personnel onsite, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 3_1 8 | Function out. 05 ##### ## | Writable Alternative 0 = Not used 1 = Extr. high lev.1 2 = Extr. high lev.2 3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 1 8 = Timer 1 out 9 = Watchdog | Function on output signal 05. Select function: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |

| | | | |
|----------|--|--|--|
| | | <p>10 = Remote 1 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 1 15 = Generic analog 2 16 = Modem reset Central System Text Function on output 05</p> | |
| 3_1 9 | <p>Function out. 06 ##### ##</p> | <p>Writable Alternative 0 = Not used 1 = Extr. low lev. 1 2 = Extr. low lev. 2 3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 2 8 = Timer 2 out 9 = Watchdog 10 = Remote 2 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 2 15 = Generic analog 3 16 = Modem reset Central System Text Function on output 06</p> | <p>Function on output signal 06. Select function: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset.</p> |
| 3_2 0 | <p>Function out. 07 ##### ##</p> | <p>Writable Alternative 0 = Not used 1 = Extr. high lev.1 2 = Extr. high lev.2 3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 1 8 = Timer 1 out 9 = Watchdog 10 = Remote 1 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 1 15 = Generic analog 2 16 = Modem reset Central System Text Function on output 07</p> | <p>Function on output signal 07. Select function: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset.</p> |
| 3_2 1 | <p>Function out. 08 ##### ##</p> | <p>Writable Alternative 0 = Not used 1 = Extr. low lev. 1 2 = Extr. low lev. 2</p> | <p>Function on output signal 08. Select function: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out,</p> |

| | | | |
|----------|--|--|--|
| | | <p>3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 2 8 = Timer 2 out 9 = Watchdog 10 = Remote 2 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 2 15 = Generic analog 3 16 = Modem reset Central System Text Function on output 08</p> | <p>9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset.</p> |
| 3_2 2 | <p>Function out. 09 ##### ##</p> | <p>Writable Alternative 0 = Not used 1 = Extr. high lev.1 2 = Extr. high lev.2 3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 1 8 = Timer 1 out 9 = Watchdog 10 = Remote 1 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 1 15 = Generic analog 2 16 = Modem reset Central System Text Function on output 09</p> | <p>Function on output signal 09. Select function: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset.</p> |
| 3_2 3 | <p>Function out. 10 ##### ##</p> | <p>Writable Alternative 0 = Not used 1 = Extr. low lev. 1 2 = Extr. low lev. 2 3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 2 8 = Timer 2 out 9 = Watchdog 10 = Remote 2 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 2 15 = Generic analog 3 16 = Modem reset Central System Text</p> | <p>Function on output signal 10. Select function: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset.</p> |

| | | | |
|----------|---------------------------------|--|---|
| | | Function on output 10 | |
| 3_2 4 | Function out. 11 ##### ## | <p>Writable</p> <p>Alternative</p> <p>0 = Not used</p> <p>1 = Extr. high lev.1</p> <p>2 = Extr. high lev.2</p> <p>3 = Remote blocked</p> <p>4 = Alarm pulse</p> <p>5 = Alarm status</p> <p>6 = Alarm active</p> <p>7 = Sprinkler sump 1</p> <p>8 = Timer 1 out</p> <p>9 = Watchdog</p> <p>10 = Remote 1</p> <p>11 = Buzzer</p> <p>12 = Siren</p> <p>13 = Buzzer+siren</p> <p>14 = Vol.pulse sump 1</p> <p>15 = Generic analog 2</p> <p>16 = Modem reset</p> <p>Central System Text</p> <p>Function on output 11</p> | Function on output signal 11. Select function: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |
| 3_2 5 | Function out. 12 ##### ## | <p>Writable</p> <p>Alternative</p> <p>0 = Not used</p> <p>1 = Extr. low lev. 1</p> <p>2 = Extr. low lev. 2</p> <p>3 = Remote blocked</p> <p>4 = Alarm pulse</p> <p>5 = Alarm status</p> <p>6 = Alarm active</p> <p>7 = Sprinkler sump 2</p> <p>8 = Timer 2 out</p> <p>9 = Watchdog</p> <p>10 = Remote 2</p> <p>11 = Buzzer</p> <p>12 = Siren</p> <p>13 = Buzzer+siren</p> <p>14 = Vol.pulse sump 2</p> <p>15 = Generic analog 3</p> <p>16 = Modem reset</p> <p>Central System Text</p> <p>Function on output 12</p> | Function on output signal 12. Select function: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset. |
| 3_2 6 | Function out. 13 ##### ## | <p>Writable</p> <p>Alternative</p> <p>0 = Not used</p> <p>1 = Extr. high lev.1</p> <p>2 = Extr. high lev.2</p> <p>3 = Remote blocked</p> <p>4 = Alarm pulse</p> <p>5 = Alarm status</p> <p>6 = Alarm active</p> <p>7 = Sprinkler sump 1</p> <p>8 = Timer 1 out</p> <p>9 = Watchdog</p> <p>10 = Remote 1</p> | Function on output signal 13. Select function: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |

| | | | |
|----------|--|--|--|
| | | <p>11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 1 15 = Generic analog 2 16 = Modem reset Central System Text Function on output 13</p> | |
| 3_2 7 | <p>Function out. 14 ##### ##</p> | <p>Writable Alternative 0 = Not used 1 = Extr. low lev. 1 2 = Extr. low lev. 2 3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 2 8 = Timer 2 out 9 = Watchdog 10 = Remote 2 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 2 15 = Generic analog 3 16 = Modem reset Central System Text Function on output 14</p> | <p>Function on output signal 14. Select function: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset.</p> |
| 3_2 8 | <p>Function out. 15 ##### ##</p> | <p>Writable Alternative 0 = Not used 1 = Extr. high lev.1 2 = Extr. high lev.2 3 = Remote blocked 4 = Alarm pulse 5 = Alarm status 6 = Alarm active 7 = Sprinkler sump 1 8 = Timer 1 out 9 = Watchdog 10 = Remote 1 11 = Buzzer 12 = Siren 13 = Buzzer+siren 14 = Vol.pulse sump 1 15 = Generic analog 2 16 = Modem reset Central System Text Function on output 15</p> | <p>Function on output signal 15. Select function: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset.</p> |

COMMUNICATION

| No | Menu Name | Specification | Description |
|-----|--------------------------------|---|---|
| 4 | COMMUNICATION SETUP ... | Read only | Setup of communication. |
| 4_1 | Station number ### | Writable Interval 0 To 0 | The station number identifies the RTU. The station number is 999 in a cold started RTU. |
| 4_2 | ID number fixed ### (fixed) | Writable Interval 0 To 0 | Enter the ID number used to identify the station in fixed line communication. |
| 4_3 | Communic. COM1 ##### | Writable Alternative 0 = Not used 1 = TD22 V.22 2 = TD22 V.22bisLAPM 3 = TD22 V.23 dial. 4 = (TD22 V.23 fix.) 5 = TD33 V.90 6 = TD33 V.90 X1 7 = TD33 V.90 LAPM 8 = RS232 half dup. 9 = RS232 full dup. 10 = Siox RS232 11 = Alarm printer 12 = User def. 0 13 = User def. 0 HDX 14 = Factory set. 0 15 = User def. 1 16 = Factory set. 1 | Select communication function on serial channel 1. |
| 4_4 | Speed COM1 ###00 bit/s | Writable Alternative 0 = 3 1 = 6 2 = 12 3 = 24 4 = 48 5 = 96 6 = 192 7 = 384 8 = 576 | Select communication speed (DTE) on serial channel 1. |
| 4 | Protocol on COM1 ##### | Indirect Writable Alternative 0 = None 1 = AquaCom 2 = Modbus 3 = Comli 4 = CCom 5 = GPRS AquaCom 6 = Other | Selection of protocol on COM1. |

| | | | |
|----------|-----------------------------|---|--|
| 4 | Protocol on COM1 code ## | Indirect Writable Interval 0 To 0 | Selection of protocol code for COM1. 3=AquaCom, 4=Modbus, 5=Comli, 13=CCom. |
| 4_6 | RTS delay COM1 #### ms | Writable Interval 0 To 2000 Central System Text General and RTS delay COM1 (ms) | The time the modem needs to stabilise the signal before it begins to send data. Recommended value is 100-300 ms for fixed line and 0 ms for dialled line. |
| 4_7 | Communic. COM3 ##### | Writable Alternative 0 = Not used 1 = RS232 half dup. 2 = RS232 full dup. 3 = Siox RS232 4 = Alarm printer 5 = User def. 0 6 = User def. 0 HDX 7 = Factory set. 0 8 = User def. 1 9 = Factory set. 1 | Select communication function on serial channel 3. |
| 4_8 | Speed COM3 ###00 bit/s | Writable Alternative 0 = 3 1 = 6 2 = 12 3 = 24 4 = 48 5 = 96 6 = 192 7 = 384 8 = 576 | Select communication speed (DTE) on serial channel 3. |
| 4 | Protocol on COM3 ##### | Indirect Writable Alternative 0 = None 1 = AquaCom 2 = Modbus 3 = Comli 4 = CCom 5 = GPRS AquaCom 6 = Other | Selection of protocol on COM3. |
| 4 | Protocol on COM3 code ## | Indirect Writable Interval 0 To 0 | Selection of protocol code for COM3. 3=AquaCom, 4=Modbus, 5=Comli, 13=CCom. |
| 4_1 0 | RTS delay COM3 #### ms | Writable Interval 0 To 2000 Central System Text General and RTS delay COM3 | The time the modem needs to stabilise the signal before it begins to send data. Recommended value is 100-300 ms for fixed line and 0 ms for dialled line. |

| | | (ms) | |
|----------|--------------------------------|--|--|
| 4_1 1 | Time-out teleg. ## s | Writable Interval 0 To 30 Central System Text Time-out telegram (s) | This setting controls how long the program will wait for an answer. When it takes long time to receive an answer from an RTU the program will timeout. To avoid this you may increase this value. Only change the default value 8 s if it is absolutely necessary. |
| 4_1 2 | Time-out char #### ms | Writable Interval 0 To 9999 Central System Text Time-out character (ms) | This setting controls how long the program wait for a new character in a telegram. |
| 4_1 3 | Send OK delay ##### ms | Writable Interval 0 To 15000 Central System Text Delay before sending OK (ms) | The time the program wait from starting a modem communication until sending the first OK message. |
| 4_1 4 | Max telegram size #### byte | Writable Interval 0 To 9999 Central System Text Max telegram size (byte) | The maximum telegram size that is used in AquaCom. Longer telegrams is splitted up in smaler ones. |
| 4_1 5 | Trend sample time ## min | Writable Interval 0 To 60 Central System Text Trend sample time (min) | Trend sample time. A zero will give 5 minutes. |
| 4_1 6 | Trend method ##### | Writable Alternative 0 = Normal 1 = Extended 2 = Continuous Central System Text Trend sample method | Sample method for trend. 0=Normal, 1=Extended, 2=Continuous |
| 4_1 7 | Remote break #### min | Writable Interval 0 To 1440 Central System Text Remote ctrl break delay (min) | A pump can be switched on or off via the central system 'installation status'. After leaving the status picture the pump will keep this mode during the time set in this channel. |
| 4_1 8 | Response delay dialled ## s | Writable Interval 0 To 30 Central System Text Response delay incoming call (s) | Enter the delay time before answering incoming calls. |
| 4_1 9 | Delay for GPRS msg ##### s | Writable Interval 0 To 68400 Central System Text | Set the time between 'I am alive' messages. This is to keep the GPRS connection to AquaView Central Server going. |

| | | | |
|----------|--------------------------|---|---|
| | | Delay between GPRS messages. | |
| 4_2 0 | IP address ##### | Writable Central System Text IP address GPRS | IP address of AquaView Central Server when using a GPRS solution. Example: If the address is '195 . 67 . 103 . 110', enter '195.67.103.110'. |
| 4_2 1 | TCP Port number ##### | Writable Central System Text TCP Port number GPRS | TCP Port Number to the AquaView Central Server when using a GPRS solution. Can be any valid number from 0 to 65535. |

ALARM LOG

| No | Menu Name | Specification | Description |
|-----------|-------------------|----------------------|--|
| 5 | ALARM LOG #### | Writable | Shows locally unacknowledged alarms. There is room for about 400 alarms in the RTU. |

ALARM SETUP

| No | Menu Name | Specification | Description |
|-----|---------------------------------|--|---|
| 6 | ALARM SETUP ... | Read only | Setup for alarm parameters. |
| 6_1 | Transmit alarm ##### | Writable Alternative 0 = Local permanent 1 = Remote 2 = Clear 3 = Local today Central System Text Alarm status (0=Local, 1=Remote) | Select whether an alarm should be sent to CS/pager. 'Clear' will remove all alarm that is waiting to be sent. Alarm created when the state is in 'Local' or 'Local today' will not be sent to CS with the exception of 'Personal' and 'Cold start' alarms that is sent anyway. 'Local today' will return to remote at midnight. |
| 6_2 | Alarmdistrib. #### (ABCP) | Writable Alternative 1 = A-- Alarm 2 = -B-- Alarm 3 = --C- Alarm 4 = ---P Passive Central System Text Alarm distribution (ABCP) | Select the alarms priorities to send to CS/pager. A '1' means that this alarm with this priority should be sent. A '0' that it should not be sent. Default setup is '1101'. A=A Alarm up flank. B=B Alarm up flank, C=C Alarm up flank, P=all alarm down flank. |
| 6_3 | Telno. 1 CS/PAGE ##### | Writable Central System Text Telephone number 1 CS/Pager | First telephone number to CS or paging system. Use a '&' as the first character for numbers to paging systems. |
| 6_4 | Telno. 2 CS/PAGE ##### | Writable Central System Text Telephone number 2 CS/Pager | Second telephone number to CS or paging system. Use a '&' as the first character for numbers to paging systems. |
| 6_5 | Number of calls to CS ## | Writable Interval 0 To 99 Central System Text Number of calls to CS | Alarming to CS. Number of calls the RTU makes when the CS is not responding. |
| 6_6 | New alarm pulse length ### s | Writable Interval 0 To 999 Central System Text Pulse length on new alarm (s) | Enter the pulse length of the alarm output at a new alarm. This may be used to control an acoustic alarm. |
| 6_7 | Select alarm code #### | Writable Interval 0 To 0 | Select alarm code to show and change. |
| 6_8 | Alarm priority # | Writable Alternative 0 = - 1 = A 2 = B 3 = C 4 = D 5 = F | Select new alarm priority for the alarm selected in the previous channel. |

| | | | |
|----------|-----------------------------|---|---|
| | | 6 = H | |
| 6_9 | New alarm code #### | Writable Interval 0 To 0 | Select new alarm code for selected alarm. |
| 6_1 0 | Testalarm every ## days | Writable Interval 0 To 99 Central System Text Test alarm (every xx days) | Enter how often the RTU has to report himself with a testalarm. A zero in this channel turns off this function. |
| 6_1 1 | Testalarm time ##:## h:m | Writable Interval 00:00 To 23:59 Central System Text Test alarm time (h:m) | Enter the time of day the unit will send the test alarm. |

PAGING SETUP

| No | Menu Name | Specification | Description |
|-----|--------------------------------|---|--|
| 7 | PAGING SETUP ... | Read only | Setup for paging. |
| 7_1 | Station name ##### | Writable Central System Text Station name | Station name. This name is transmitted to some paging systems. If the name is missing the station number will be transmitted. |
| 7_2 | Number of calls to pager ## | Writable Interval 0 To 99 Central System Text Number of calls to pager | Alarming to pager. Number of calls the RTU makes when the service personnel is not responding. |
| 7_3 | Pager ack. time #### min | Writable Interval 0 To 9999 Central System Text Pager acknowledge time (min) | This is the time the user has to acknowledge an alarm that is sent to a pager. If no acknowledge is received the alarm will be sent again. If the time is set to zero no acknowledge is needed. In this case the unit only calls one time. |
| 7_4 | Wait time pager cycle #### min | Writable Interval 0 To 9999 Central System Text Wait time pager cycle (min) | Waiting time after a unsuccessful batch of alarm calls. |
| 7 | Paging system ##### | Indirect Writable Alternative 0 = None 1 = Minicall numeric 2 = Semadigit 3 = Numerik N/DK 4 = Minicall text 5 = Semascript 6 = TAP text 7 = Cityruf DE 8 = SMS Europ. 9 = SMS UCP 10 = SemaDigit B 11 = SemaDigit NL 12 = TAP D1 SMS 13 = GSM-SMS 14 = Numeric A 15 = SMS-SFR F 16 = SMS-Itineris F 17 = TAP F 18 = SMS-Bouygues 19 = Other | Selection of paging system. |
| 7 | Paging system code ## | Indirect Writable Interval | Selection of paging system. 0=None, 3=Minicall numeric, 4=Semadigit, 5=BellBoy, 7=Numerik N/DK, 9=Minicall |

| | | | |
|----------|---------------------------|---|---|
| | | 0 To 99 Central System Text Paging system selection code | text, 10=Semascript, 11=TAP text, 12=Cityruf DE, 13=SMS Europ., 14=SMS UCP, 16=SemaDigit B, 17=SemaDigit NL, 18=TAP D1 SMS, 19=GSM-SMS M20, 20=Numeric A, 21=SMS-SFR F, 22=SMS-Itineris F, 23=TAP F, 24=SMS-Bouygues. |
| 7_6 | Telno. PAD/SMSC ##### | Writable Central System Text Paging number to PAD/SMSC | Phone number to the paging central. This number must be used if larms is to be sent to SMS. |
| 7_7 | Delay paging central ## s | Writable Interval 0 To 99 Central System Text Delay paging central (s) | Delay between dialling and transmitting of the paging message. Only used in some paging systems. |
| 7_8 | Transmitter no ##### | Writable Central System Text Paging transmitter number | Transmit number for paging system. Only used in some paging systems. |
| 7_9 | Identity code ##### | Writable Central System Text Paging identity code | Identification code for paging system. Only used in some paging systems. |
| 7_1 0 | Paging password ##### | Writable Central System Text Paging password | Password for paging system. Only used in some paging systems. |

ALARM DELAYS

| No | Menu Name | Specification | Description |
|-----|-----------------------------|--|---|
| 8 | ALARM DELAYS ... | Read only | Setup for alarm delays. |
| 8_1 | Digital delay #### s | Writable Interval 0 To 9999 Central System Text Digital alarm delay (s) | Common alarm delay for digital alarms. |
| 8_2 | Analog delay #### s | Writable Interval 0 To 9999 Central System Text Analogue alarm delay (s) | Common alarm delay for analogue alarms. |
| 8_3 | Power fail delay #### s | Writable Interval 0 To 9999 Central System Text Power fail alarm delay (s) | Alarm delay for power fail alarm. |
| 8_4 | Worktim pers.al. ### min | Writable Interval 0 To 999 Central System Text Worktime before personnel alarm (min) | Enter the time that the work will last. After this time the output buzzer will start. |
| 8_5 | Pers. warning #### s | Writable Interval 0 To 9999 Central System Text Personnel alarm warning time (s) | The delay before the alarm is sent after the warning buzzer started. |
| 8_6 | Burglary delay #### s | Writable Interval 0 To 9999 Central System Text Burglary alarm delay (s) | Delay before the intruder alarm is sent to CS. |

LEVEL SUMP 1

| No | Menu Name | Specification | Description |
|-----|-----------------------------------|--|---|
| 9 | LEVEL SUMP 1 @##.## m | Read only | Shows the level of the water in the sump. |
| 9_1 | High lev. sump 1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text High level sump 1 (m) | Alarm limit for high level. The alarm will be generated when the sump level reach up to this value. Set the alarm level to zero to disable the alarm. |
| 9_2 | Ext. high lev. 1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Extremely high level sump 1 (m) | Alarm limit for extremely high level. The alarm will be generated when the sump level reach up to this value. Set the alarm level to zero to disable the alarm. |
| 9_3 | High level alarm delay ##### s | Writable Interval 0 To 99999 Central System Text High level alarm delay sump 1 (s) | Alarm delay for high level and extremely high level alarms. |
| 9_4 | Low level sump 1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Low level sump 1 (m) | Alarm limit for low level. The alarm will be generated when the sump level goes down below this value. Set the alarm level to zero to disable the alarm. |
| 9_5 | Ext. low lev. 1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Extremely low level sump 1 (m) | Alarm limit for extremely low level. The alarm will be generated when the sump level goes down below this value. Set the alarm level to zero to disable the alarm. |
| 9_6 | Low level alarm delay #### s | Writable Interval 0 To 9999 Central System Text Low level alarm delay sump 1 (s) | Alarm delay for low level and extremely low level alarms. |
| 9_7 | Level alarm hyst ##.## m | Writable Interval 0.00 To 10.00 Central System Text Level alarm hysteresis sump 1 (m) | Hysteresis for all level alarms. |
| 9_8 | Calibrate lev. 1 @##.## m | Writable | Calibration of the level sensor. |
| 9_9 | Maximum level 1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text | Maximum value for level sensor. Enter the level measured when the signal is equal to maximum signal (normally 20 mA). The value is normally equal to sensor range plus the next channel value. Changed by level |

| | | | |
|----------|-------------------------------|--|--|
| | | Maximum level sump 1 (m) | calibration. |
| 9_1 0 | Minimum level 1 @###.## m | Writable Interval -100.00 To 100.00 Central System Text Minimum level sump 1 (m) | Minimum value for level sensor. Enter the level measured when the signal is equal to minimum signal (normally 4 mA). The value is normally equal to the distance from the sump bottom to the sensor. Changed by level calibration. |
| 9_1 1 | Max sens.sign. 1 ##.### mA | Writable Interval 0.000 To 30.000 Central System Text Maximum sensor signal sump 1 (mA) | Maximum sensor signal. Normally 20 mA. Changed by level calibration. |
| 9_1 2 | Min sens.sign. 1 ##.### mA | Writable Interval 0.000 To 30.000 Central System Text Minimum sensor signal sump 1 (mA) | Minimum sensor signal. Normally 4 mA. Changed by level calibration. |
| 9_1 3 | Sensor control ##### min | Writable Interval 0 To 9999 Central System Text Sensor control sump 1 (min) | Sensor control time. If the value from the sensor do not move within this time an alarm is generated. |

LEVEL SUMP 2

| No | Menu Name | Specification | Description |
|----------|-----------------------------------|--|--|
| 10 | LEVEL SUMP 2 @##.## m | Read only | Shows the level of the water in the sump. |
| 10_ 1 | High lev. sump 2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text High level sump 2 (m) | Alarm limit for high level. The alarm will be generated when the sump level reach up to this value. Set the alarm level to zero to disable the alarm. |
| 10_ 2 | Ext. high lev. 2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Extremely high level sump 2 (m) | Alarm limit for extremely high level. The alarm will be generated when the sump level reach up to this value. Set the alarm level to zero to disable the alarm. |
| 10_ 3 | High level alarm delay ##### s | Writable Interval 0 To 99999 Central System Text High level alarm delay sump 2 (s) | Alarm delay for high level and extremely high level alarms. |
| 10_ 4 | Low level sump 2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Low level sump 2 (m) | Alarm limit for low level. The alarm will be generated when the sump level goes down below this value. Set the alarm level to zero to disable the alarm. |
| 10_ 5 | Ext. low lev. 2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Extremely low level sump 2 (m) | Alarm limit for extremely low level. The alarm will be generated when the sump level goes down below this value. Set the alarm level to zero to disable the alarm. |
| 10_ 6 | Low level alarm delay #### s | Writable Interval 0 To 9999 Central System Text Low level alarm delay sump 2 (s) | Alarm delay for low level and extremely low level alarms. |
| 10_ 7 | Level alarm hyst ##.## m | Writable Interval 0.00 To 10.00 Central System Text Level alarm hysteresis sump 2 (m) | Hysteresis for all level alarms. |
| 10_ 8 | Calibrate lev. 2 @##.## m | Writable | Calibration of the level sensor. |
| 10_ 9 | Maximum level 2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text | Maximum value for level sensor. Enter the level measured when the signal is equal to maximum signal (normally 20 mA). The value is normally equal to sensor range plus |

| | | | |
|-------|-------------------------------|--|--|
| | | Maximum level sump 2 (m) | the next channel value. Changed by level calibration. |
| 10_10 | Minimum level 2 @###.## m | Writable Interval -100.00 To 100.00 Central System Text Minimum level sump 2 (m) | Minimum value for level sensor. Enter the level measured when the signal is equal to minimum signal (normally 4 mA). The value is normally equal to the distance from the sump bottom to the sensor. Changed by level calibration. |
| 10_11 | Max sens.sign. 2 ##.### mA | Writable Interval 0.000 To 30.000 Central System Text Maximum sensor signal sump 2 (mA) | Maximum sensor signal. Normally 20 mA. Changed by level calibration. |
| 10_12 | Min sens.sign. 2 ##.### mA | Writable Interval 0.000 To 30.000 Central System Text Minimum sensor signal sump 2 (mA) | Minimum sensor signal. Normally 4 mA. Changed by level calibration. |
| 10_13 | Sensor control #### min | Writable Interval 0 To 9999 Central System Text Sensor control sump 2 (min) | Sensor control time. If the value from the sensor do not move within this time an alarm is generated. |

CURRENT P1.1

| No | Menu Name | Specification | Description |
|----------|------------------------------|---|--|
| 11 | CURRENT P1.1 ###.# A | Read only | Shows the current for pump 1.1. |
| 11_ 1 | Nom.current P1.1 ###.# A | Read only Interval 0.0 To 0.0 | Shows the calculated nominal current for pump 1.1. |
| 11_ 2 | High curr. P1.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text High current P1.1 (A) | Alarm limit for high current pump 1.1. Set the alarm level to zero to disable the alarm. |
| 11_ 3 | Low current P1.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Low current P1.1 (A) | Alarm limit for low current pump 1.1. Set the alarm level to zero to disable the alarm. It is a possible to switch off the pump on this alarm. |
| 11_ 4 | Curr. hyst. P1.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current hysteresis P1.1 (A) | Hysteresis for current alarms on pump 1.1. |
| 11_ 5 | Max current P1.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current range P1.1 (A) | Range of measurement for current transformer pump 1.1. |
| 11_ 6 | Current P1.1 signal ##### | Writable Alternative 0 = 0-20 mA 1 = 4-20 mA Central System Text Signal type current P1.1 (0=0, 1=4-20mA) | Type of current transformer for pump 1.1. Choose between: 0=0-20 mA, 1=4-20 mA. |

CURRENT P1.2

| No | Menu Name | Specification | Description |
|----------|------------------------------|---|--|
| 12 | CURRENT P1.2 ###.# A | Read only | Shows the current for pump 1.2. |
| 12_ 1 | Nom.current P1.2 ###.# A | Read only Interval 0.0 To 0.0 | Shows the calculated nominal current for pump 1.2. |
| 12_ 2 | High curr. P1.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text High current P1.2 (A) | Alarm limit for high current pump 1.2. Set the alarm level to zero to disable the alarm. |
| 12_ 3 | Low current P1.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Low current P1.2 (A) | Alarm limit for low current pump 1.2. Set the alarm level to zero to disable the alarm. It is a possible to switch off the pump on this alarm. |
| 12_ 4 | Curr. hyst. P1.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current hysteresis P1.2 (A) | Hysteresis for current alarms on pump 1.2. |
| 12_ 5 | Max current P1.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current range P1.2 (A) | Range of measurement for current transformer pump 1.2. |
| 12_ 6 | Current P1.2 signal ##### | Writable Alternative 0 = 0-20 mA 1 = 4-20 mA Central System Text Signal type current P1.2 (0=0, 1=4-20mA) | Type of current transformer for pump 1.2. Choose between: 0=0-20 mA, 1=4-20 mA. |

CURRENT P2.1

| No | Menu Name | Specification | Description |
|----------|------------------------------|---|--|
| 13 | CURRENT P2.1 ###.# A | Read only | Shows the current for pump 2.1. |
| 13_ 1 | Nom.current P2.1 ###.# A | Read only Interval 0.0 To 0.0 | Shows the calculated nominal current for pump 2.1. |
| 13_ 2 | High curr. P2.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text High current P2.1 (A) | Alarm limit for high current pump 2.1. Set the alarm level to zero to disable the alarm. |
| 13_ 3 | Low current P2.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Low current P2.1 (A) | Alarm limit for low current pump 2.1. Set the alarm level to zero to disable the alarm. It is a possible to switch off the pump on this alarm. |
| 13_ 4 | Curr. hyst. P2.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current hysteresis P2.1 (A) | Hysteresis for current alarms on pump 2.1. |
| 13_ 5 | Max current P2.1 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current range P2.1 (A) | Range of measurement for current transformer pump 2.1. |
| 13_ 6 | Current P2.1 signal ##### | Writable Alternative 0 = 0-20 mA 1 = 4-20 mA Central System Text Signal type current P2.1 (0=0, 1=4-20mA) | Type of current transformer for pump 2.1. Choose between: 0=0-20 mA, 1=4-20 mA. |

CURRENT P2.2

| No | Menu Name | Specification | Description |
|----------|------------------------------|---|--|
| 14 | CURRENT P2.2 ###.# A | Read only | Shows the current for pump 2.2. |
| 14_ 1 | Nom.current P2.2 ###.# A | Read only Interval 0.0 To 0.0 | Shows the calculated nominal current for pump 2.2. |
| 14_ 2 | High curr. P2.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text High current P2.2 (A) | Alarm limit for high current pump 2.2. Set the alarm level to zero to disable the alarm. |
| 14_ 3 | Low current P2.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Low current P2.2 (A) | Alarm limit for low current pump 2.2. Set the alarm level to zero to disable the alarm. It is a possible to switch off the pump on this alarm. |
| 14_ 4 | Curr. hyst. P2.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current hysteresis P2.2 (A) | Hysteresis for current alarms on pump 2.2. |
| 14_ 5 | Max current P2.2 ###.# A | Writable Interval 0.0 To 999.9 Central System Text Current range P2.2 (A) | Range of measurement for current transformer pump 2.2. |
| 14_ 6 | Current P2.2 signal ##### | Writable Alternative 0 = 0-20 mA 1 = 4-20 mA Central System Text Signal type current P2.2 (0=0, 1=4-20mA) | Type of current transformer for pump 2.2. Choose between: 0=0-20 mA, 1=4-20 mA. |

GENERAL ANALOG 2

| No | Menu Name | Specification | Description |
|----------|-----------------------------|--|---|
| 15 | GENERAL ANALOG 2 | Read only | Shows the general analogue 2 input. |
| 15 | Volume GA2 Not used | Indirect Read only | Shown when the volume in general analog 2 is not used. |
| 15 | Volume GA2 | Indirect Read only | Volume general analog 2. |
| 15 | Volume GA2 #####.# m3 | Indirect Writable | Volume for general analog 2. Enter a value manually and the counter will continue on this value. |
| 15_ 2 | High value GA2 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text High alarm general analog 2 | Alarm limit för high value general analogue 2. Set the alarm level to zero to disable the alarm. |
| 15_ 3 | Low value GA2 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Low alarm general analog 2 | Alarm limit för low value general analogue 2. Set the alarm level to zero to disable the alarm. |
| 15_ 4 | Alarm hyst. GA2 ####.## | Writable Interval 0.00 To 9999.99 Central System Text Alarm hysteresis general analog 2 | Hysteresis for general analogue 2 alarms. |
| 15_ 5 | Use of GA2 ##### | Writable Alternative 0 = General 1 = Flow 2 = Pumpflow 1 3 = Pumpflow 2 4 = Inflow 1 5 = Inflow 2 6 = Overflow 7 = Current 8 = PH 9 = Temperature 10 = Pressure Central System Text Use of general analog 2 | Select view of general analogue 2. 0=General, 1=Flow, 2=Pumpflow 1, 3=Pumpflow 2, 4=Inflow 1, 5=Inflow 2, 6=Overflow, 7=Current, 8=PH, 9=Temperature, 10=Pressure |
| 15_ 6 | Max value GA2 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text | Maximum value for general analogue 2. Enter the value measured by the sensor when the signal is 20 mA. |

| | | | |
|-------|------------------------------|---|---|
| | | Maximum value general analog 2 | |
| 15_7 | Min value GA2 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Minimum value general analog 2 | Minimum value for general analogue 2. Enter the value measured by the sensor when the signal is 0 or 4 mA. |
| 15_8 | Signal type GA2 ##### | Writable Alternative 0 = 0-20 mA 1 = 4-20 mA Central System Text Signal type general ana. (0=0, 1=4-20mA) | Type of sensor for general analogue 2. Choose between 0=0-20 mA, 1=4-20 mA. |
| 15_9 | Start value GA2 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Start value general analog 2 | Enter a start value. When general analogue 2 reach this value an output is activated. This output remains active until the stop value is reached. |
| 15_10 | Stop value GA2 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Stop value general analog 2 | Enter a stop value. When general analogue 2 reach the start value an output is activated. This output remains active until the stop value is reached. |

GENERAL ANALOG 3

| No | Menu Name | Specification | Description |
|----------|-----------------------------|--|---|
| 16 | GENERAL ANALOG 3 | Read only | Shows the general analogue 3 input. |
| 16 | Volume GA3 Not used | Indirect Read only | Shown when the volume in general analog 3 is not used. |
| 16 | Volume GA3 | Indirect Read only | Volume general analog 3. |
| 16 | Volume GA3 #####.# m3 | Indirect Writable | Volume for general analog 3. Enter a value manually and the counter will continue on this value. |
| 16_ 2 | High value GA3 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text High alarm general analog 3 | Alarm limit för high value general analogue 3. Set the alarm level to zero to disable the alarm. |
| 16_ 3 | Low value GA3 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Low alarm general analog 3 | Alarm limit för low value general analogue 3. Set the alarm level to zero to disable the alarm. |
| 16_ 4 | Alarm hyst. GA3 ####.## | Writable Interval 0.00 To 9999.99 Central System Text Alarm hysteresis general analog 3 | Hysteresis for general analogue 3 alarms. |
| 16_ 5 | Use of GA3 ##### | Writable Alternative 0 = General 1 = Flow 2 = Pumpflow 1 3 = Pumpflow 2 4 = Inflow 1 5 = Inflow 2 6 = Overflow 7 = Current 8 = PH 9 = Temperature 10 = Pressure Central System Text Use of general analog 3 | Select view of general analogue 3. 0=General, 1=Flow, 2=Pumpflow 1, 3=Pumpflow 2, 4=Inflow 1, 5=Inflow 2, 6=Overflow, 7=Current, 8=PH, 9=Temperature, 10=Pressure |
| 16_ 6 | Max value GA3 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text | Maximum value for general analogue 3. Enter the value measured by the sensor when the signal is 20 mA. |

| | | | |
|-------|------------------------------|---|---|
| | | Maximum value general analog 3 | |
| 16_7 | Min value GA3 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Minimum value general analog 3 | Minimum value for general analogue 3. Enter the value measured by the sensor when the signal is 0 or 4 mA. |
| 16_8 | Signal type GA3 ##### | Writable Alternative 0 = 0-20 mA 1 = 4-20 mA Central System Text Signal type general ana. (0=0, 1=4-20mA) | Type of sensor for general analogue 3. Choose between 0=0-20 mA, 1=4-20 mA. |
| 16_9 | Start value GA3 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Start value general analog 3 | Enter a start value. When general analogue 3 reach this value an output is activated. This output remains active until the stop value is reached. |
| 16_10 | Stop value GA3 @#####.## | Writable Interval -9999.99 To 9999.99 Central System Text Stop value general analog 3 | Enter a stop value. When general analogue 3 reach the start value an output is activated. This output remains active until the stop value is reached. |

REPORT SETUP

| No | Menu Name | Specification | Description |
|------|--------------------------------|---|--|
| 17 | REPORT SETUP ... | Read only | Setup for report parameters. |
| 17_1 | OPERATIONAL DATA ##### | Writable Alternative 0 = Today's 1 = Yesterday's 2 = Continuous | Selects if channels with report data should show today's, yesterday's or continuous values. Today's and yesterday's values can not be changed. Continuous values may be changed. This channel may be changed without influence on stored values. |
| 17 | P1.1 no. starts | Indirect Read only | Starts of pump 1.1. |
| 17 | P1.1 no. starts ##### total | Indirect Writable Interval 0 To 0 | Starts of pump 1.1. Enter a value manually and the counter will continue on this value. |
| 17 | P1.1 runtime | Indirect Read only | Runtime pump 1.1. |
| 17 | P1.1 runtime ##### h total | Indirect Writable Interval 0 To 0 | Runtime pump 1.1. Enter a value manually and the counter will continue on this value. |
| 17 | P1.2 no. starts | Indirect Read only | Starts of pump 1.2. |
| 17 | P1.2 no. starts ##### total | Indirect Writable Interval 0 To 0 | Starts of pump 1.2. Enter a value manually and the counter will continue on this value. |
| 17 | P1.2 runtime | Indirect Read only | Runtime pump 1.2. |
| 17 | P1.2 runtime ##### h total | Indirect Writable Interval 0 To 0 | Runtime pump 1.2. Enter a value manually and the counter will continue on this value. |
| 17 | Two pump starts | Indirect Read only | Starts two pumps running at the same time. |
| 17 | Two pump starts ##### total | Indirect Writable Interval 0 To 0 | Starts two pumps running at the same time. Enter a value manually and the counter will continue on this value. |
| 17 | Two pump runtime | Indirect Read only | Runtime two pumps running at the same time. |

| | | | |
|----|-----------------------------------|--|---|
| 17 | Two pump runtime ##### h total | Indirect Writable Interval 0 To 0 | Runtime two pumps running at the same time. Enter a value manually and the counter will continue on this value. |
| 17 | P2.1 no. starts | Indirect Read only | Starts of pump 2.1. |
| 17 | P2.1 no. starts ##### total | Indirect Writable Interval 0 To 0 | Starts of pump 2.1. Enter a value manually and the counter will continue on this value. |
| 17 | P2.1 runtime | Indirect Read only | Runtime pump 2.1. |
| 17 | P2.1 runtime ##### h total | Indirect Writable Interval 0 To 0 | Runtime pump 2.1. Enter a value manually and the counter will continue on this value. |
| 17 | P2.2 no. starts | Indirect Read only | Starts of pump 2.2. |
| 17 | P2.2 no. starts ##### total | Indirect Writable Interval 0 To 0 | Starts of pump 2.2. Enter a value manually and the counter will continue on this value. |
| 17 | P2.2 runtime | Indirect Read only | Runtime pump 2.2. |
| 17 | P2.2 runtime ##### h total | Indirect Writable Interval 0 To 0 | Runtime pump 2.2. Enter a value manually and the counter will continue on this value. |
| 17 | Two pump starts | Indirect Read only | Starts two pumps running at the same time. |
| 17 | Two pump starts ##### total | Indirect Writable Interval 0 To 0 | Starts two pumps running at the same time. Enter a value manually and the counter will continue on this value. |
| 17 | Two pump runtime | Indirect Read only | Runtime two pumps running at the same time. |
| 17 | Two pump runtime ##### h total | Indirect Writable Interval 0 To 0 | Runtime two pumps running at the same time. Enter a value manually and the counter will continue on this value. |

START AND STOP

| No | Menu Name | Specification | Description |
|----------|------------------------------|---|---|
| 18 | START AND STOP LEVELS ... | Read only | Start and stop levels of the pumps. |
| 18_ 1 | Start level P1.1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Start level P1.1 (m) | Start level for pump 1.1. When alternating is selected this start level is shared by all alternating pumps. |
| 18_ 2 | Stop level P1.1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Stop level P1.1 (m) | Stop level for pump 1.1. When alternating is selected this stop level is shared by all alternating pumps. |
| 18_ 3 | Start level P1.2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Start level P1.2 (m) | Start level for pump 1.2. When alternating is selected this start level is shared by all alternating pumps. |
| 18_ 4 | Stop level P1.2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Stop level P1.2 (m) | Stop level for pump 1.2. When alternating is selected this stop level is shared by all alternating pumps. |
| 18_ 5 | Start level E1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Start level E1 (m) | Extra start level 1. Used by pump selected in special control options. |
| 18_ 6 | Stop level E1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Stop level E1 (m) | Extra stop level 1. Used by pump selected in special control options. |
| 18_ 7 | Start level P2.1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Start level P2.1 (m) | Start level for pump 2.1. When alternating is selected this start level is shared by all alternating pumps. |
| 18_ 8 | Stop level P2.1 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Stop level P2.1 (m) | Stop level for pump 2.1. When alternating is selected this stop level is shared by all alternating pumps. |
| 18_ 9 | Start level P2.2 | Writable Interval | Start level for pump 2.2. When alternating is selected this start level is shared by all |

| | | | |
|-----------|-----------------------------|--|---|
| 9 | @##.## m | -100.00 To 100.00 Central System Text Start level P2.2 (m) | alternating pumps. |
| 18_ 10 | Stop level P2.2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Stop level P2.2 (m) | Stop level for pump 2.2. When alternating is selected this stop level is shared by all alternating pumps. |
| 18_ 11 | Start level E2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Start level E2 (m) | Extra start level 2. Used by pump selected in special control options. |
| 18_ 12 | Stop level E2 @##.## m | Writable Interval -100.00 To 100.00 Central System Text Stop level E2 (m) | Extra stop level 2. Used by pump selected in special control options. |

PUMP CONTROL

| No | Menu Name | Specification | Description |
|----------|----------------------------------|--|---|
| 19 | PUMP CONTROL SUMP 1 ... | Read only | Control of pumps in sump 1. |
| 19_ 1 | High level run time ##### s | Writable Interval 0 To 9999 Central System Text High level float minimum run time (s) | Runtime on high level float. When the high level float is activated the available pumps will start and continue to run at least this time after return of the float. A zero of will prevent the pump to start and only make an alarm. |
| 19_ 2 | Low level block- time ##### s | Writable Interval 0 To 9999 Central System Text Low level float minimum block time (s) | Blocktime on low level float. When the low level float is activated all pumps will stop and continue to be stopped this time after return of the float. Also a zero will stop the pumps. |
| 19_ 3 | Al. pump do not start ##### s | Writable Interval 3 To 9999 Central System Text Alarm pump does not start after (s) | Alarm delay for pump response. When there is no running signal within this time an operation alarm will be generated. Alternating pumps will switch on this alarm. |
| 19_ 4 | Start delay ##### s | Writable Interval 0 To 9999 Central System Text Start delay (s) | Delay between the start condition and starting the pump. |
| 19_ 5 | Stop delay ##### s | Writable Interval 0 To 9999 Central System Text Stop delay (s) | Delay between the stop condition and stopping the pump. |
| 19_ 6 | Time between starts ##### s | Writable Interval 0 To 9999 Central System Text Time between two starts (s) | Delay between two pump starts. Also delay between a pump start to a pump stop. |
| 19_ 7 | Time between stops ##### s | Writable Interval 0 To 9999 Central System Text Time between two stops (s) | Delay between two pump stops. Also delay between a pump stop to a pump start. |
| 19_ 8 | Random start span #.## m | Writable Interval 0.00 To 10.00 Central System Text Random start span (m) | Makes the start levels variate randomly between start level and start level+range. Used to avoid accumulation of dirt on sump-wall. |

| | | | |
|-----------|----------------------------------|---|--|
| 19_ 9 | Max starts per hour alarm ### | Writable Interval 0 To 999 Central System Text Maximum start/hour alarm | An alarm will be generated for the pump if it has more starts in an hour than this value. Default is 16. Enter zero to turn off this alarm. |
| 19_ 10 | Low curr. reset time #### min | Writable Interval 0 To 9999 Central System Text Low current reset time (min) | If a value is entered in this channel, a pump will be switched off when it is reaching a low current alarm, and blocked during the time set. |

ADVANCED PUMP

| No | Menu Name | Specification | Description |
|------|------------------------------|--|--|
| 20 | ADVANCED PUMP CONTROL SUMP 1 | Read only | Advanced control of pumps in sump 1. |
| 20_1 | Action ##### ## | Writable Alternative 0 = Select action 1 = Activate APF 2 = Pump down | Select remote action. Options: 0=Select action, 1=Activate APF, 2=Pump down. |
| 20_2 | Control option ##### | Writable Alternative 0 = Alternating 1 = P1.1 first 2 = P1.2 first Central System Text Control option (0=Alter, 1=P1.1, 2=P1.2) | Running mode. Selection between alternation and duty pump. 0=Alternating, 1=P1.1 first, 2=P1.2 first. |
| 20_3 | Max running pumps # | Writable Interval 0 To 4 Central System Text Max running pumps | Max running pumps. Used to limit the number of pumps running at the same time. |
| 20_4 | Spec. cont. P1.1 ##### | Writable Alternative 1 = Disconnected 2 = Blocked by P1.2 3 = No backup run 4 = No long run blk. 5 = Leakage block 6 = Not tele blocked 7 = Use level E1 8 = APF high sens. 9 = APF no transient 10 = APF no undercurr 11 = No low cur. blk. Central System Text Special control P1.1 | Special control of pump 1.1. Options: 1=Disconnected, 2=Blocked by P1.2, 3=No backup run, 4=No long run blk., 5=Leakage block, 6=Not tele blocked, 7=Use level E1, 8=APF high sens., 9=APF no transient, 10=APF no undercurr, 11=No low cur. blk. |
| 20_5 | Spec. cont. P1.2 ##### | Writable Alternative 1 = Disconnected 2 = Blocked by P1.1 3 = No backup run 4 = No long run blk. 5 = Leakage block 6 = Not tele blocked 7 = Use level E1 8 = APF high sens. 9 = APF no transient 10 = APF no undercurr 11 = No low cur. blk. | Special control of pump 1.2. Options: 1=Disconnected, 2=Blocked by P1.1, 3=No backup run, 4=No long run blk., 5=Leakage block, 6=Not tele blocked, 7=Use level E1, 8=APF high sens., 9=APF no transient, 10=APF no undercurr, 11=No low cur. blk. |

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|------|------------------------|--|--|
| | | Central System Text Special control P1.2 | |
| 20_6 | Manual control #### | Writable Alternative 0 = Off 1 = On Central System Text Manual pump start (1=On) | System channel. Controls if the RTU shall take over control of pump on manual run by local switch. If a pump is manually controlled for more than 5 seconds the RTU takes over the pump control until the stop level has been reached. |

SUMP 1 CLEANING

| No | Menu Name | Specification | Description |
|----------|------------------------------------|---|--|
| 21 | SUMP 1 CLEANING ... | Read only | Cleaning of pump sump 1. |
| 21_ 1 | Max. pump time #### min | Writable Interval 0 To 9999 Central System Text Maximum pump time (min) | Maximum continues runtime of the pumps. When the pump has run this time it is stopped temporary. This prevents garbage from building up on the impeller lowering the performance. |
| 21_ 2 | APF clean cycles per day ## | Writable Interval 0 To 99 Central System Text APF cleaning cycles per day | Number of cleaning cycles using the APF per day. |
| 21_ 3 | Forced pump down delay #### min | Writable Interval 0 To 9999 Central System Text Forced pump down delay (min) | Forces an extra pump cycle to empty the bassin to avoid stagnant water. The pump with the lowest startlevel will be started. |
| 21_ 4 | Forced pump down level @##.## m | Writable Interval -100.00 To 100.00 Central System Text Forced pump down level (m) | This is the level the pump will run to when it starts with the forced pump down function. This may be selected lower than the normal stop level but has to be higher than the low level float if used. A zero will use the normal pump stop level. |
| 21_ 5 | No of flushings per day ## | Writable Interval 0 To 99 Central System Text No of sprinkler flushings per day | Number of sprinkler flush starts each day. |
| 21_ 6 | Flushing time #### s | Writable Interval 0 To 9999 Central System Text Sprinkler flushing time (s) | Cleaning time for sprinkler flush valve. |

PUMP CONTROL

| No | Menu Name | Specification | Description |
|----------|----------------------------------|--|---|
| 22 | PUMP CONTROL SUMP 2 ... | Read only | Control of pumps in sump 2. |
| 22_ 1 | High level run time ##### s | Writable Interval 0 To 9999 Central System Text High level float minimum run time (s) | Runtime on high level float. When the high level float is activated the available pumps will start and continue to run at least this time after return of the float. A zero of will prevent the pump to start and only make an alarm. |
| 22_ 2 | Low level block- time ##### s | Writable Interval 0 To 9999 Central System Text Low level float minimum block time (s) | Blocktime on low level float. When the low level float is activated all pumps will stop and continue to be stopped this time after return of the float. Also a zero will stop the pumps. |
| 22_ 3 | Al. pump do not start ##### s | Writable Interval 3 To 9999 Central System Text Alarm pump does not start after (s) | Alarm delay for pump response. When there is no running signal within this time an operation alarm will be generated. Alternating pumps will switch on this alarm. |
| 22_ 4 | Start delay ##### s | Writable Interval 0 To 9999 Central System Text Start delay (s) | Delay between the start condition and starting the pump. |
| 22_ 5 | Stop delay ##### s | Writable Interval 0 To 9999 Central System Text Stop delay (s) | Delay between the stop condition and stopping the pump. |
| 22_ 6 | Time between starts ##### s | Writable Interval 0 To 9999 Central System Text Time between two starts (s) | Delay between two pump starts. Also delay between a pump start to a pump stop. |
| 22_ 7 | Time between stops ##### s | Writable Interval 0 To 9999 Central System Text Time between two stops (s) | Delay between two pump stops. Also delay between a pump stop to a pump start. |
| 22_ 8 | Random start span #.## m | Writable Interval 0.00 To 10.00 Central System Text Random start span (m) | Makes the start levels variate randomly between start level and start level+range. Used to avoid accumulation of dirt on sump-wall. |

| | | | |
|-------------------|---------------------------------------|---|---|
| <p>22_ 9</p> | <p>Max starts per hour alarm ###</p> | <p>Writable Interval 0 To 999 Central System Text Maximum start/hour alarm</p> | <p>An alarm will be generated for the pump if it has more starts in an hour than this value. Default is 16. Enter zero to turn off this alarm.</p> |
| <p>22_ 10</p> | <p>Low curr. reset time ##### min</p> | <p>Writable Interval 0 To 9999 Central System Text Low current reset time (min)</p> | <p>If a value is entered in this channel, a pump will be switched off when it is reaching a low current alarm, and blocked during the time set.</p> |

ADVANCED PUMP

| No | Menu Name | Specification | Description |
|------|------------------------------|--|--|
| 23 | ADVANCED PUMP CONTROL SUMP 2 | Read only | Advanced control of pumps in sump 2. |
| 23_1 | Action ##### ## | Writable Alternative 0 = Select action 1 = Activate APF 2 = Pump down | Select remote action. Options: 0=Select action, 1=Activate APF, 2=Pump down. |
| 23_2 | Control option ##### | Writable Alternative 0 = Alternating 1 = P2.1 first 2 = P2.2 first Central System Text Control option (0=Alter, 1=P2.1, 2=P2.2) | Running mode. Selection between alternation and duty pump. 0=Alternating, 1=P2.1 first, 2=P2.2 first. |
| 23_3 | Max running pumps # | Writable Interval 0 To 4 Central System Text Max running pumps | Max running pumps. Used to limit the number of pumps running at the same time. |
| 23_4 | Spec. cont. P2.1 ##### | Writable Alternative 1 = Disconnected 2 = Blocked by P2.2 3 = No backup run 4 = No long run blk. 5 = Leakage block 6 = Not tele blocked 7 = Use level E2 8 = APF high sens. 9 = APF no transient 10 = APF no undercurr 11 = No low cur. blk. Central System Text Special control P2.1 | Special control of pump 2.1. Options: 1=Disconnected, 2=Blocked by P2.2, 3=No backup run, 4=No long run blk., 5=Leakage block, 6=Not tele blocked, 7=Use level E2, 8=APF high sens., 9=APF no transient, 10=APF no undercurr, 11=No low cur. blk. |
| 23_5 | Spec. cont. P2.2 ##### | Writable Alternative 1 = Disconnected 2 = Blocked by P2.1 3 = No backup run 4 = No long run blk. 5 = Leakage block 6 = Not tele blocked 7 = Use level E2 8 = APF high sens. 9 = APF no transient 10 = APF no undercurr 11 = No low cur. blk. | Special control of pump 2.2. Options: 1=Disconnected, 2=Blocked by P2.1, 3=No backup run, 4=No long run blk., 5=Leakage block, 6=Not tele blocked, 7=Use level E2, 8=APF high sens., 9=APF no transient, 10=APF no undercurr, 11=No low cur. blk. |

| | | | |
|------|------------------------|--|--|
| | | Central System Text Special control P2.2 | |
| 23_6 | Manual control #### | Writable Alternative 0 = Off 1 = On Central System Text Manual pump start (1=On) | System channel. Controls if the RTU shall take over control of pump on manual run by local switch. If a pump is manually controlled for more than 5 seconds the RTU takes over the pump control until the stop level has been reached. |

SUMP 2 CLEANING

| No | Menu Name | Specification | Description |
|----------|-------------------------------------|---|--|
| 24 | SUMP 2 CLEANING ... | Read only | Cleaning of pump sump 2. |
| 24_ 1 | Max. pump time #### min | Writable Interval 0 To 9999 Central System Text Maximum pump time (min) | Maximum continues runtime of the pumps. When the pump has run this time it is stopped temporary. This prevents garbage from building up on the impeller lowering the performance. |
| 24_ 2 | APF clean cycles per day ## | Writable Interval 0 To 99 Central System Text APF cleaning cycles per day | Number of cleaning cycles using the APF per day. |
| 24_ 3 | Forced pump down delay ##### min | Writable Interval 0 To 9999 Central System Text Forced pump down delay (min) | Forces an extra pump cycle to empty the bassin to avoid stagnant water. The pump with the lowest startlevel will be started. |
| 24_ 4 | Forced pump down level @##.## m | Writable Interval -100.00 To 100.00 Central System Text Forced pump down level (m) | This is the level the pump will run to when it starts with the forced pump down function. This may be selected lower than the normal stop level but has to be higher than the low level float if used. A zero will use the normal pump stop level. |
| 24_ 5 | No of flushings per day ## | Writable Interval 0 To 99 Central System Text No of sprinkler flushings per day | Number of sprinkler flush starts each day. |
| 24_ 6 | Flushing time #### s | Writable Interval 0 To 9999 Central System Text Sprinkler flushing time (s) | Cleaning time for sprinkler flush valve. |

FLOWS AND

| No | Menu Name | Specification | Description |
|----------|----------------------------------|--|---|
| 25 | FLOWS AND VOLUMES SUMP 1 | Read only | Flows and volumes. |
| 25_ 1 | Inflow @#####.# l/s | Read only | The calculated inflow into the sump. |
| 25 | Inflow volume | Indirect Read only | Inflow volume. |
| 25 | Inflow volume #####.# m3 tot | Indirect Writable Interval 0 To 0 | Inflow volume. Enter a value manually and the counter will continue on this value. |
| 25_ 3 | Outflow #####.# l/s | Read only | The calculated pump flow out from the sump. |
| 25 | Pumped volume | Indirect Read only | Pumped volume. |
| 25 | Pumped volume #####.# m3 tot | Indirect Writable Interval 0 To 0 | Pumped volume. Enter a value manually and the counter will continue on this value. |
| 25_ 5 | Outflow calib ###.# % | Writable Interval 0.0 To 999.9 Central System Text Outflow calibration (%) | Calibration for pumped flow. Change this value to adjust the calculated pumped flow. |
| 25_ 6 | Volume sump #####.# m3 | Read only | Calculated volume in sump. |
| 25_ 7 | Volume pulse #####.# m3/pulse | Writable Interval 0.0 To 99999.9 Central System Text Volume output pulse (m3/pulse) | Flow pulses. Enter the volume that is needed to create a pulse. This can be used for sample taking. |
| 25_ 8 | Volume pulse src ##### | Writable Alternative 0 = Pumped flow 1 = Inflow 2 = Overflow Central System Text Volume output pulse source | Select source for flow pulse. 0=Pumped flow, 1=Inflow, 2=Overflow. This channel selects the type of flow to use to create pulses. If overflow is selected the program will make an extra pulse when the overflow starts. |

FLOWS AND

| No | Menu Name | Specification | Description |
|------|----------------------------------|--|--|
| 26 | FLOWS AND VOLUMES SUMP 2 | Read only | Flows and volumes. |
| 26_1 | Inflow @#####.# l/s | Read only | The calculated inflow into the sump. |
| 26 | Inflow volume | Indirect Read only | Inflow volume. |
| 26 | Inflow volume #####.# m3 tot | Indirect Writable Interval 0 To 0 | Inflow volume. Enter a value manually and the counter will continue on this value. |
| 26_3 | Outflow #####.# l/s | Read only | The calculated pump flow out from the sump. |
| 26 | Pumped volume | Indirect Read only | Pumped volume. |
| 26 | Pumped volume #####.# m3 tot | Indirect Writable Interval 0 To 0 | Pumped volume. Enter a value manually and the counter will continue on this value. |
| 26_5 | Outflow calib ###.# % | Writable Interval 0.0 To 999.9 Central System Text Outflow calibration (%) | Calibration for pumped flow. Change this value to adjust the calculated pumped flow. |
| 26_6 | Volume sump #####.# m3 | Read only | Calculated volume in sump. |
| 26_7 | Volume pulse #####.# m3/pulse | Writable Interval 0.0 To 99999.9 Central System Text Volume output pulse (m3/pulse) | Flow pulses. Enter the volume that is needed to create a pulse. This can be used for sample taking. |
| 26_8 | Volume pulse src ##### | Writable Alternative 0 = Pumped flow 1 = Inflow 2 = Overflow Central System Text Volume output pulse source | Select source for flow pulse. 0=Pumped flow, 1=Inflow, 2=Overflow. This channel selects the type of flow to use to create pulses. If overflow is selected the program will make an extra pulse when the overflow starts. |

SUMP 1 FORM

| No | Menu Name | Specification | Description |
|----------|---------------------|--|------------------------------------|
| 27 | SUMP 1 FORM ... | Read only | Definition of pumpsump. |
| 27_ 1 | Level 1 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 1 (m) | Level at area 1. May be zero. |
| 27_ 2 | Area 1 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 1 (m2) | Area at level 1. |
| 27_ 3 | Level 2 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 2 (m) | Level at area 2. May not be zero. |
| 27_ 4 | Area 2 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 2 (m2) | Area at level 2. |
| 27_ 5 | Level 3 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 3 (m) | Level at area 3. Zero if not used. |
| 27_ 6 | Area 3 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 3 (m2) | Area at level 3. Zero if not used. |
| 27_ 7 | Level 4 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 4 (m) | Level at area 4. Zero if not used. |
| 27_ 8 | Area 4 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 4 (m2) | Area at level 4. Zero if not used. |
| 27_ 9 | Level 5 | Writable Interval | Level at area 5. Zero if not used. |

| | | | |
|-----------|---------------------|---|------------------------------------|
| 9 | @###.## m | -99.99 To 99.99 Central System Text Level 5 (m) | |
| 27_ 10 | Area 5 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 5 (m2) | Area at level 5. Zero if not used. |

SUMP 2 FORM

| No | Menu Name | Specification | Description |
|----------|---------------------|--|------------------------------------|
| 28 | SUMP 2 FORM ... | Read only | Definition of pumpsump. |
| 28_ 1 | Level 1 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 1 (m) | Level at area 1. May be zero. |
| 28_ 2 | Area 1 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 1 (m2) | Area at level 1. |
| 28_ 3 | Level 2 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 2 (m) | Level at area 2. May not be zero. |
| 28_ 4 | Area 2 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 2 (m2) | Area at level 2. |
| 28_ 5 | Level 3 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 3 (m) | Level at area 3. Zero if not used. |
| 28_ 6 | Area 3 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 3 (m2) | Area at level 3. Zero if not used. |
| 28_ 7 | Level 4 @##.## m | Writable Interval -99.99 To 99.99 Central System Text Level 4 (m) | Level at area 4. Zero if not used. |
| 28_ 8 | Area 4 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 4 (m2) | Area at level 4. Zero if not used. |
| 28_ 9 | Level 5 | Writable Interval | Level at area 5. Zero if not used. |

| | | | |
|-----------|---------------------|---|------------------------------------|
| 9 | @###.## m | -99.99 To 99.99 Central System Text Level 5 (m) | |
| 28_ 10 | Area 5 ###.## m2 | Writable Interval 0.00 To 999.99 Central System Text Area 5 (m2) | Area at level 5. Zero if not used. |

CAPACITY CALC.

| No | Menu Name | Specification | Description |
|----------|---------------------------------|---|--|
| 29 | CAPACITY CALC. SUMP 1 ... | Read only | Pump capacity calculation in the sump. |
| 29_ 1 | Upper level cap. @##.## m | Writable Interval -100.00 To 100.00 Central System Text Upper level cap. calc. (m) | Upper level for capacity calculation. Has to be below the lowest start level. |
| 29_ 2 | Lower level cap. @##.## m | Writable Interval -100.00 To 100.00 Central System Text Lower level cap. calc. (m) | Lower level for capacity calculation. Has to be higher than the stop level. |
| 29_ 3 | No. calculations ## (0-20) | Writable Interval 0 To 20 Central System Text Number of calculations (0-20) | Number of average values in capacity calculations. Use 0 and the current pump flow uses nominal capacity. |
| 29_ 4 | Capacity factor #.## 2 pumps | Writable Interval 0.00 To 1.00 Central System Text Capacity factor 2 pumps (0.50-1.00) | Calibration factor for 2 pumps. Divide the real total capacity by the added individual capacities. Example: P1.1=10 l/s, P1.2=10 l/s, together 15 l/s the capacity factor is then 0,75. This figure will be used to calculate the pumped flow. |

CAPACITY CALC.

| No | Menu Name | Specification | Description |
|----------|---------------------------------|---|--|
| 30 | CAPACITY CALC. SUMP 2 ... | Read only | Pump capacity calculation in the sump. |
| 30_ 1 | Upper level cap. @##.## m | Writable Interval -100.00 To 100.00 Central System Text Upper level cap. calc. (m) | Upper level for capacity calculation. Has to be below the lowest start level. |
| 30_ 2 | Lower level cap. @##.## m | Writable Interval -100.00 To 100.00 Central System Text Lower level cap. calc. (m) | Lower level for capacity calculation. Has to be higher than the stop level. |
| 30_ 3 | No. calculations ## (0-20) | Writable Interval 0 To 20 Central System Text Number of calculations (0-20) | Number of average values in capacity calculations. Use 0 and the current pump flow uses nominal capacity. |
| 30_ 4 | Capacity factor #.## 2 pumps | Writable Interval 0.00 To 1.00 Central System Text Capacity factor 2 pumps (0.50-1.00) | Calibration factor for 2 pumps. Divide the real total capacity by the added individual capacities. Example: P2.1=10 l/s, P2.2=10 l/s, together 15 l/s the capacity factor is then 0,75. This figure will be used to calculate the pumped flow. |

CAPACITY

| No | Menu Name | Specification | Description |
|------|-------------------------------|---|---|
| 31 | CAPACITY ALARMS ... | Read only | Parameters for the capacity alarms. |
| 31_1 | Calc cap. P1.1 #####.# l/s | Read only | Shows the calculated pump capacity of P1.1. |
| 31_2 | Nom. cap. P1.1 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Nominal capacity P1.1 (l/s) | Enter the nominal capacity of P1.1. Used for capacity alarms. |
| 31_3 | Cap. div. P1.1 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Capacity divergation limit P1.1 (l/s) | Divergation limit for high and low capacity alarms. Uses nominal capacity +/- this channel. |
| 31_4 | Calc cap. P1.2 #####.# l/s | Read only | Shows the calculated pump capacity of P1.2. |
| 31_5 | Nom. cap. P1.2 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Nominal capacity P1.2 (l/s) | Enter the nominal capacity of P1.2. Used for capacity alarms. |
| 31_6 | Cap. div. P1.2 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Capacity divergation limit P1.2 (l/s) | Divergation limit for high and low capacity alarms. Uses nominal capacity +/- this channel. |
| 31_7 | Calc cap. P2.1 #####.# l/s | Read only | Shows the calculated pump capacity of P2.1. |
| 31_8 | Nom. cap. P2.1 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Nominal capacity P2.1 (l/s) | Enter the nominal capacity of P2.1. Used for capacity alarms. |
| 31_9 | Cap. div. P2.1 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Capacity divergation limit P2.1 | Divergation limit for high and low capacity alarms. Uses nominal capacity +/- this channel. |

| | | | |
|-----------|-------------------------------|--|---|
| | | (l/s) | |
| 31_ 10 | Calc cap. P2.2 #####.# l/s | Read only | Shows the calculated pump capacity of P2.2. |
| 31_ 11 | Nom. cap. P2.2 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Nominal capacity P2.2 (l/s) | Enter the nominal capacity of P2.2. Used for capacity alarms. |
| 31_ 12 | Cap. div. P2.2 #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Capacity divergence limit P2.2 (l/s) | Divergation limit for high and low capacity alarms. Uses nominal capacity +/- this channel. |

OVERFLOW

| No | Menu Name | Specification | Description |
|----------|---------------------------------|--|--|
| 32 | OVERFLOW #####.# l/s | Read only | Show calculated overflow. |
| 32 | Overflow volume | Indirect Read only | Overflow volume. |
| 32 | Overflow volume ##### m3 tot | Indirect Writable Interval 0 To 0 | Overflow volume. Enter a value manually and the counter will continue on this value. |
| 32 | Overflow time | Indirect Read only | Overflow time. |
| 32 | Overflow time ##### h total | Indirect Writable Interval 0 To 0 | Overflow time. Enter a value manually and the counter will continue on this value. |
| 32 | Num. overflow | Indirect Read only | Number of overflows. |
| 32 | Num. overflow ##### total | Indirect Writable Interval 0 To 0 | Number of overflows. Enter a value manually and the counter will continue on this value. |
| 32_ 4 | Num. gross over- flows ##### | Writable Interval 0 To 0 | Number of gross overflows. If the time span between two overflows is smaller than 24 hour this second overflow belongs to the first one. |
| 32_ 5 | Overflow alarm log | Writable | Overflow alarm log. Shows all overflow alarms. Press read/write twice to view the alarms. |

OVERFLOW

| No | Menu Name | Specification | Description |
|------|----------------------------------|---|--|
| 33 | OVERFLOW DEFINITION ... | Read only | Overflow calculation. |
| 33_1 | Overflow using sump # | Writable Alternative 0 = 1 1 = 2 Central System Text Overflow used on (0=sump 1, 1=sump 2) | Select where the overflow is used. 0=sump 1, 1=sump 2. |
| 33_2 | Overflow level @###.## m | Writable Interval -100.00 To 100.00 Central System Text Overflow level (m) | The level where overflow occurs. Set this level manually if no overflow sensor is used. |
| 33_3 | Discharge coeff. #.## | Writable Interval 0.00 To 1.00 Central System Text Discharge coeff.(0.00-1.00) | Enter the overflow coefficient for the overflow weir. This value is used only to automatically calculate the overflow table. This value will often be named as cd. |
| 33_4 | Overflow range #.### m | Writable Interval 0.000 To 99.999 Central System Text Overflow range (m) | Enter the height of the overflow weir. This height should correspond to the maximum flow in the overflow table. |
| 33_5 | Weir width ##.### m | Writable Interval 0.000 To 99.999 Central System Text Overflow weir width (m) | Enter the width of the overflow weir. This value is used only to automatically calculate the overflow table. |
| 33_6 | Weir select ##### | Writable Alternative 0 = Manual 1 = Rectangular 2 = V-notch Central System Text Weir select (0=Man, 1=Rect, 2=V-Notch) | Overflow table method. 0=Manual, 1=Rectangular, 2=V-notch. Select calculation method for overflow table. Select 'Manual' to define the overflow segment manually. Select 'Rectangular' or 'V-Notch' and the unit will calculate the overflow segments. |
| 33_7 | Overflow segment 01: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 01 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_ | Overflow segment 02: #####.# l/s | Writable Interval 0.0 To 99999.9 | The flow over the overflow weir when the level is in this segment. (see overflow |

| | | | |
|-------|----------------------------------|---|--|
| 8 | | Central System Text Overflow segment 02 (l/s) | description). |
| 33_9 | Overflow segment 03: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 03 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_10 | Overflow segment 04: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 04 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_11 | Overflow segment 05: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 05 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_12 | Overflow segment 06: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 06 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_13 | Overflow segment 07: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 07 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_14 | Overflow segment 08: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 08 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_15 | Overflow segment 09: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 09 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_16 | Overflow segment 10: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 10 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_17 | Overflow segment 11: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 11 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| | Overflow segment | Writable | The flow over the overflow weir when the |

| | | | |
|-------|-------------------------------------|---|--|
| 33_18 | 12: #####.# l/s | Interval 0.0 To 99999.9 Central System Text Overflow segment 12 (l/s) | level is in this segment. (see overflow description). |
| 33_19 | Overflow segment 13: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 13 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_20 | Overflow segment 14: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 14 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_21 | Overflow segment 15: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 15 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_22 | Overflow segment 16: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 16 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_23 | Overflow segment 17: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 17 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_24 | Overflow segment 18: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 18 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_25 | Overflow segment 19: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 19 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |
| 33_26 | Overflow segment 20: #####.# l/s | Writable Interval 0.0 To 99999.9 Central System Text Overflow segment 20 (l/s) | The flow over the overflow weir when the level is in this segment. (see overflow description). |

SERVICE

| No | Menu Name | Specification | Description |
|----------|------------------------------------|---|---|
| 34 | SERVICE ... | Read only | Service-alarms. |
| 34_ 1 | Service interval P1.1 ##### h | Writable Interval 0 To 99999 Central System Text Service interval P1.1 (h) | Service interval time. When the pump has run this time a service alarm is sent. |
| 34_ 2 | P1.1 time after service ##### h | Writable | This is the time since the last pump service on pump 1.1. Reset this channel after service. |
| 34_ 3 | Service interval P1.2 ##### h | Writable Interval 0 To 99999 Central System Text Service interval P1.2 (h) | Service interval time. When the pump has run this time a service alarm is sent. |
| 34_ 4 | P1.2 time after service ##### h | Writable | This is the time since the last pump service on pump 1.2. Reset this channel after service. |
| 34_ 5 | Service interval P2.1 ##### h | Writable Interval 0 To 99999 Central System Text Service interval P2.1 (h) | Service interval time. When the pump has run this time a service alarm is sent. |
| 34_ 6 | P2.1 time after service ##### h | Writable | This is the time since the last pump service on pump 2.1. Reset this channel after service. |
| 34_ 7 | Service interval P2.2 ##### h | Writable Interval 0 To 99999 Central System Text Service interval P2.2 (h) | Service interval time. When the pump has run this time a service alarm is sent. |
| 34_ 8 | P2.2 time after service ##### h | Writable | This is the time since the last pump service on pump 2.2. Reset this channel after service. |

RECEIVE BLOCKING

| No | Menu Name | Specification | Description |
|----------|-------------------------------|---|--|
| 35 | RECEIVE BLOCKING ... | Read only | Receive blocking. |
| 35_ 1 | Blocked status ##### | Writable Alternative 0 = Not blocked 1 = Blocked | Shows the block status. The status changes when the RTU receives remote blocking or unblocking commands. To override the remote command change the status in this channel. |
| 35 | Num. of blocks | Indirect Read only | Number of blockings. |
| 35 | Num. of blocks ##### total | Indirect Writable Interval 0 To 0 | Number of blockings. Enter a value manually and the counter will continue on this value. |
| 35 | Blocked time | Indirect Read only | Blocked time. |
| 35 | Blocked time ##### h total | Indirect Writable Interval 0 To 0 | Blocked time. Enter a value manually and the counter will continue on this value. |
| 35_ 4 | Timeout block. #### min | Writable Interval 0 To 9999 Central System Text Timeout blocking (min) | The blocked station will be unblocked after this time. This is a safety function to unblock the station if a unblocking command fail to come. Use the repeat blocking function in the sending RTU and set it to five minutes less than this value. |
| 35_ 5 | Blocked by ID @# | Writable Interval -1 To 9 Central System Text Fixed blocked by ID | Fixed line ID of remote station that blocks this station. Used only in fixed communication. |
| 35_ 6 | Blocked by func ## | Writable Alternative 1 = Blocked by fnc 2 2 = Blocked by fnc 1 Central System Text Fixed blocked by function (21) | Block logic function in the remote station that is used to block this station. Used only in fixed communication. Options: 1=Blocked by fnc 2, 2=Blocked by fnc 1 |

SEND BLOCKING

| No | Menu Name | Specification | Description |
|-----------|---------------------------|---|---|
| 36 | SEND BLOCKING ... | Read only | Send blocking. |
| 36_ 1 | Block delay #### s | Writable Interval 0 To 9999 Central System Text Block delay (s) | Enter the time to wait before the unit actually sends a blocking telegram when the blocking conditions are active. |
| 36_ 2 | Deblock delay #### s | Writable Interval 0 To 9999 Central System Text Deblock delay (s) | Enter the time to wait before the unit is actually sending deblocking when the blocking conditions is passive. |
| 36_ 3 | Repeat block. #### min | Writable Interval 0 To 9999 Central System Text Repeat blocking (min) | Repeating time for blocking command. A new blocking command is sent out after this time. Use the timeout blocking function in the receiving station and set it to five minutes more than this value. |
| 36_ 4 | Telephone #1 ##### | Writable Central System Text Telephone #1 | Blocking telephone number. Enter the telephone number of the unit you want to block. |
| 36_ 5 | Telephone #2 ##### | Writable Central System Text Telephone #2 | Blocking telephone number. Enter the telephone number of the unit you want to block. |
| 36_ 6 | Telephone #3 ##### | Writable Central System Text Telephone #3 | Blocking telephone number. Enter the telephone number of the unit you want to block. |
| 36_ 7 | Telephone #4 ##### | Writable Central System Text Telephone #4 | Blocking telephone number. Enter the telephone number of the unit you want to block. |
| 36_ 8 | Telephone #5 ##### | Writable Central System Text Telephone #5 | Blocking telephone number. Enter the telephone number of the unit you want to block. |
| 36_ 9 | Telephone #6 ##### | Writable Central System Text Telephone #6 | Blocking telephone number. Enter the telephone number of the unit you want to block. |
| 36_ 10 | Block1 condition ##### | Writable Alternative 1 = P1.1 failed 2 = P1.2 failed 3 = P2.1 failed 4 = P2.2 failed 5 = P1.1 switch off 6 = P1.2 switch off | Blocking logic set 1. Select the conditions that is required to send a blocking command. Options: 1=P1.1 failed, 2=P1.2 failed, 3=P2.1 failed, 4=P2.2 failed, 5=P1.1 switch off, 6=P1.2 switch off, 7=P2.1 switch off, 8=P2.2 switch off, 9=Block levels 1, 10=Block levels 2, 11=High level 1, 12=Extr.high lev. 1, 13=High float 1, |

| | | | |
|-------|--|---|---|
| | | <p>7 = P2.1 switch off 8 = P2.2 switch off 9 = Block levels 1 10 = Block levels 2 11 = High level 1 12 = Extr.high lev. 1 13 = High float 1 14 = Overflow input 15 = Power fail input 16 = Block input Central System Text Block 1 condition</p> | <p>14=Overflow input, 15=Power fail input, 16=Block input</p> |
| 36_11 | <p>Block1 tele# use #####</p> | <p>Writable Alternative 1 = Use number 6 2 = Use number 5 3 = Use number 4 4 = Use number 3 5 = Use number 2 6 = Use number 1 Central System Text Use tele# for block 1 (654321)</p> | <p>Blocking logic set 1. Select the telephone numbers to use for this blocking condition. Options: 1=Use number 6, 2=Use number 5, 3=Use number 4, 4=Use number 3, 5=Use number 2, 6=Use number 1</p> |
| 36_12 | <p>Block 1 logic #####</p> | <p>Writable Alternative 0 = Or 1 = And Central System Text Block 1 logic (0=Or, 1=And)</p> | <p>Blocking logic set 1. Select block logic for this function. 0=Or, 1=And. Select if one (or) or all (and) of the conditions are required to send block commands to other stations.</p> |
| 36_13 | <p>Block2 condition #####</p> | <p>Writable Alternative 1 = P1.1 failed 2 = P1.2 failed 3 = P2.1 failed 4 = P2.2 failed 5 = P1.1 switch off 6 = P1.2 switch off 7 = P2.1 switch off 8 = P2.2 switch off 9 = Block levels 1 10 = Block levels 2 11 = High level 2 12 = Extr.high lev. 2 13 = High float 2 14 = Overflow input 15 = Power fail input 16 = Block input Central System Text Block 2 condition</p> | <p>Blocking logic set 2. Select the conditions that is required to send a blocking command. Options: 1=P1.1 failed, 2=P1.2 failed, 3=P2.1 failed, 4=P2.2 failed, 5=P1.1 switch off, 6=P1.2 switch off, 7=P2.1 switch off, 8=P2.2 switch off, 9=Block levels 1, 10=Block levels 2, 11=High level 2, 12=Extr.high lev. 2, 13=High float 2, 14=Overflow input, 15=Power fail input, 16=Block input</p> |
| 36_14 | <p>Block2 tele# use #####</p> | <p>Writable Alternative 1 = Use number 6 2 = Use number 5 3 = Use number 4 4 = Use number 3 5 = Use number 2</p> | <p>Blocking logic set 2. Select the telephone numbers to use for this blocking condition. Options: 1=Use number 6, 2=Use number 5, 3=Use number 4, 4=Use number 3, 5=Use number 2, 6=Use number 1</p> |

| | | | |
|-----------|------------------------------|---|---|
| | | 6 = Use number 1 Central System Text Use tele# for block 2 (654321) | |
| 36_ 15 | Block 2 logic ##### | Writable Alternative 0 = Or 1 = And Central System Text Block 2 logic (0=Or, 1=And) | Blocking logic set 2. Select block logic for this function. 0=Or, 1=And. Select if one (or) or all (and) of the conditions are required to send block commands to other stations. |
| 36_ 16 | Blocking level 1 @##.## m | Writable Interval 0.00 To 100.00 Central System Text Blocking level 1 (m) | Blocking level 1. Other stations are blocked at this level. |
| 36_ 17 | Unblock level 1 @##.## m | Writable Interval 0.00 To 100.00 Central System Text Unblockering level 1 (m) | Deblocking level 1. Other stations are unblocked at this level. |
| 36_ 18 | Blocking level 2 @##.## m | Writable Interval 0.00 To 100.00 Central System Text Blocking level 2 (m) | Blocking level 2. Other stations are blocked at this level. |
| 36_ 19 | Unblock level 2 @##.## m | Writable Interval 0.00 To 100.00 Central System Text Unblockering level 2 (m) | Deblocking level 2. Other stations are unblocked at this level. |

ENERGY

| No | Menu Name | Specification | Description |
|----------|----------------------------------|--|--|
| 37 | ENERGY ... | Read only | Energy calculation. |
| 37 | Energy | Indirect Read only | Energy. |
| 37 | Energy ##### kWh tot | Indirect Writable Interval 0 To 0 | Energy. Enter a value manually and the counter will continue on this value. |
| 37_ 2 | Power #####.# kW | Read only | Shown used power. |
| 37_ 3 | Specific energy ##.### kWh/m3 | Read only | Shows specific energy. This is the cost of pumping the water. |
| 37_ 4 | Energy method ##### | Writable Alternative 0 = Pulse only 1 = Current & pulse 2 = Current only Central System Text Energy calculation method used | Select energy calculation source. 0=Pulse only, 1=Current & pulse, 2=Current only. |
| 37_ 5 | Cos phi P1.1 ### | Writable Interval 0.00 To 1.00 Central System Text Cos phi P1.1 | Enter the nominal cosine phi of pump 1.1. |
| 37_ 6 | Cos phi P1.2 ### | Writable Interval 0.00 To 1.00 Central System Text Cos phi P1.2 | Enter the nominal cosine phi of pump 1.2. |
| 37_ 7 | Cos phi P2.1 ### | Writable Interval 0.00 To 1.00 Central System Text Cos phi P2.1 | Enter the nominal cosine phi of pump 2.1. |
| 37_ 8 | Cos phi P2.2 ### | Writable Interval 0.00 To 1.00 Central System Text Cos phi P2.2 | Enter the nominal cosine phi of pump 2.2. |
| 37_ 8 | Voltage | Writable Interval | Enter the voltage measured between two |

| | | | |
|-----------|----------------------------------|---|---|
| 9 | ### V | 0 To 999 Central System Text Voltage | phases of a pump. |
| 37_ 10 | Energy scale ##.### kWh/pulse | Writable Interval 0.000 To 99.999 Central System Text Energy (kWh/pulse) | Scale value for the digital input signal. |

COUNTER

| No | Menu Name | Specification | Description |
|----------|----------------------------------|--|--|
| 38 | COUNTER ... | Read only | General counter. |
| 38_ 1 | Counter | Read only | Shows counter intensity in units/time. |
| 38 | Counter | Indirect Read only | Counter value. |
| 38 | Counter | Indirect Writable Interval 0.0 To 0.0 | Counted value. Enter a value manually and the counter will continue on this value. |
| 38 | Counter runtime | Indirect Read only | Counter time. |
| 38 | Counter runtime ##### h total | Indirect Writable Interval 0 To 0 | Counter time. Enter a value manually and the counter will continue on this value. |
| 38_ 4 | Max value 5 min #####.# | Writable Interval 0.0 To 99999999.9 Central System Text Maximum value per 5 min | Enter the value by which a high alarm counter will be generated. This will be measured on 5 min base. |
| 38_ 5 | Max value 24 h #####.# | Writable Interval 0.0 To 99999999.9 Central System Text Maximum value per 24 hour | Enter the value by which a high alarm counter will be generated. This will be measured on 24 h base. |
| 38_ 6 | Use of counter ##### | Writable Alternative 0 = General 1 = Rain 2 = Flow Central System Text Use of counter | Select use of counter. This selection changes the shown unit in the channels. 0=General, 1=Rain, 2=Flow. |
| 38_ 7 | Counter scale | Writable Interval 0.000 To 999.999 Central System Text Counter scale (x/pulse) | Enter here the counter scale for counter input. |

FUNCTION TIMERS

| No | Menu Name | Specification | Description |
|----------|---------------------------|--|--|
| 39 | FUNCTION TIMERS ... | Read only | Function timers. |
| 39_ 1 | Function timer 1 ##### | Writable Alternative 0 = No function 1 = On/off delay 2 = Pulses 3 = Pulses delayed 4 = One pulse 5 = Halve pulses 6 = Double pulses Central System Text Timer 1 function | Select function for timer 1. Options: 0=No function, 1=On/off delay, 2=Pulses, 3=Pulses delayed, 4=One pulse, 5=Halve pulses, 6=Double pulses. |
| 39_ 2 | T1 pulse time ##### s | Writable Interval 0 To 99999 Central System Text Timer 1 pulse time (s) | Enter the on/pulse time or active flank delay. |
| 39_ 3 | T1 pause time ##### s | Writable Interval 0 To 99999 Central System Text Timer 1 pause time (s) | Enter the off/pause time or the passive flank delay. |
| 39_ 4 | Function timer 2 ##### | Writable Alternative 0 = No function 1 = On/off delay 2 = Pulses 3 = Pulses delayed 4 = One pulse 5 = Halve pulses 6 = Double pulses Central System Text Timer 2 function | Select function for timer 2. Options: 0=No function, 1=On/off delay, 2=Pulses, 3=Pulses delayed, 4=One pulse, 5=Halve pulses, 6=Double pulses. |
| 39_ 5 | T2 pulse time ##### s | Writable Interval 0 To 99999 Central System Text Timer 2 pulse time (s) | Enter the on/pulse time or active flank delay. |
| 39_ 6 | T2 pause time ##### s | Writable Interval 0 To 99999 Central System Text Timer 2 pause time (s) | Enter the off/pause time or the passive flank delay. |

18 Appendix D – List of alarms

The following is a list of the alarms which can be generated and transmitted, together with the associated alarm codes and alarm texts, as well as an explanation of the alarm sources.

Only the alarm code is transmitted in the case of an alarm to a paging system that can only receive numbers. The list can be used to obtain an explanation of the alarm codes transmitted and received.

The priority shown is that assigned to the alarm after a cold start. **Alarms**

| Alarm Code | Default priority | Delay | Local text | Central System Text | Description |
|------------|------------------|-------|----------------|----------------------------|---|
| 3 | A | 300 | Mains error | Mains error | It has been a external net failure. The pumps are blocked. |
| 5 | A | 60 | Pers. alarm | Personal alarm | Personal alarm warning time has run out without reset. Personnel in danger ! |
| 6 | A | 0 | Intruder | Intruder | Burglary alarm reset time has run out before turned off. |
| 28 | B | | RTU no answer | Substation does not answer | There is no communication with the RTU. This alarm is not created in the RTU, it is created in CS when it fails to contact the RTU. |
| 72 | B | | High rainfall | High rainfall | The RTU has calculated a rainfall higher than the high alarm limit. |
| 91 | B | 10 | Alarm input 11 | Alarm digital input 11 | Spare alarm input 11. |
| 92 | B | 10 | Alarm input 12 | Alarm digital input 12 | Spare alarm input 12. |
| 93 | B | 10 | Alarm input 13 | Alarm digital input 13 | Spare alarm input 13. |
| 94 | B | 10 | Alarm input 14 | Alarm digital input 14 | Spare alarm input 14. |
| 95 | B | 10 | Alarm input 15 | Alarm digital input 15 | Spare alarm input 15. |
| 96 | B | 10 | Alarm input 16 | Alarm digital input 16 | Spare alarm input 16. |
| 8001 | C | | No teleline | No telephone line | The RTU has failed to detect a dial tone. The alarm is made passive the next time the RTU detects a dial tone. |

| | | | | | |
|------|---|--|------------------|---------------------------------------|---|
| 8002 | C | | No resp. paging | No response from Paging system | No answer from paging system central. |
| 8004 | B | | Serv. no resp. | Service personnel no response | Printed out if on-call personnel do not answer. |
| 8005 | B | | Serv. busy | Service personnel busy | Printed out if on-call personnel telephone is engaged. |
| 8019 | B | | Missing param. | Missing parameters | The RTU is cold started and has no set points. Some automatic control does not work. |
| 8033 | C | | Invalid tel.no. | Incorrect tel.no | One of the telephone numbers has invalid characters. Check all telephone numbers and correct. |
| 8035 | C | | Bad param. dist. | Bad parameters for alarm distribution | Incorrect parameters in paging set points. Check and retransmit. |
| 8050 | B | | Setpoint changed | Setpoint changed | At least one channel have been changed on the local display. The alarm reverts when new set points are sent to the RTU. |
| 8083 | B | | Station blocked | Station blocked | This RTU has received a blocking command from another RTU. |
| 8089 | C | | Unknown p-system | Unknown paging system | The selected paging system does not exist. The selected code is wrong or the system program needs to be updated to a newer version. |
| 8090 | A | | Cold start | Cold start | The RTU is cold started. The RTU needs new set points. Most automatic control do not work. |
| 8111 | C | | Telegram long | Telegram too long | The telegram received where to long. This may happen when there are communication problems. |
| 8114 | B | | Warm start | Warm start | The RTU is warm started. The reason is either power failure or manual restart. |
| 8117 | C | | Modem error | Modem error | The RTU has detected an error in the modem. If this alarm follows every warm start there is a failure in the modem. |
| 8123 | C | | Error Hayes com. | Error in Hayes command | The modem responds with an error code on initiation. This may be due to an error in the modem or if you select the wrong modem. |

| | | | | | |
|------|---|--|------------------|--------------------------------------|---|
| 8142 | C | | File error | File error | The RTU has detected a write or read error on the internal disk. |
| 8156 | H | | Call failed CS | Unsuccessful call to CS | Recorded as an event. The RTU has failed to dial to CS. |
| 8157 | H | | Call ok CS | Call ok to CS | Recorded as an event. The RTU has succeeded to dial to CS. |
| 8190 | B | | Fail ana.sig. Px | Contradicting analogue signals, Px | Both high and low float has been activated at the same time. Check the floats. |
| 8191 | B | | Fail dig.sig. Px | Contradicting digital signals, Px | Both start and stop level are active at the same time. Check setpoints for pumps. |
| 8193 | B | | Fail signals Px | Contradicting signals on pumps | High float and stop level or low float and start level are active at the same time. Check floats and setpoints. |
| 8194 | B | | Calib. complete | Calibration complete | Calibration of level sensor has been done. |
| 8199 | C | | Serial restarted | Serial task restarted | For some reason one of the serial channels (with or without modem) was halted and hence reinitiated by the system software. |
| 8200 | C | | P-Checksum error | Paging - Checksum error | Check sum error on transmitting a pager message. |
| 8201 | C | | P-Format error | Paging - Format error | Format error on transmitting a pager message. |
| 8202 | C | | P-Error pager no | Paging - Error in pager number | The number to the paging central is wrong on sending a paging message. |
| 8203 | C | | P-Error TX no | Paging - Error in transmitter number | Not a valid transmission number on sending a paging message. |
| 8204 | C | | P-Wrong password | Paging - Wrong password | Password not valid on sending a paging message. |
| 8205 | C | | P-ID code error | Paging - ID code error | Authorisation code not valid on sending a paging message. |
| 8209 | C | | P-Serv. blocked | Paging - Service blocked | Paging service blocked on sending a paging message. |
| 8210 | C | | P-Timeout | Paging - Timeout | Timeout on sending a paging message. |
| 8211 | C | | P-Busy/other err | Paging - Busy/other error | Paging central [number] engaged. |

| | | | | | |
|------|---|----|------------------|-----------------------------|--|
| 8212 | C | | P-Call failed | Paging - Call failed | SMS call failed. There are some communication problem with the SMS central. |
| 8213 | B | | Low 12V Supply | Low 12V internal supply | The internal 12 V power supply is low. May due to a fault in the internal power transformer. |
| 8214 | B | | Low 24V Supply | Low 24V external supply | The external 24 V power supply is low. May due to a discharged battery or bad external power. |
| 8215 | B | | Low int. battery | Low internal battery | The internal battery has low power. This may due to an old battery or that the RTU has been dead (no supply) for a long time. This is detected only at power-up. |
| 8300 | B | 60 | Hi level sump 1 | High level sump 1 | High level in the pump sump. Alarm from the analog level input. |
| 8301 | B | 60 | Very hi level S1 | Extremely high level sump 1 | Extremely high level in the sump. Alarm from the analog level input. |
| 8302 | B | 60 | Lo level sump 1 | Low level sump 1 | Low level in the pump sump. Alarm from the analog level input. |
| 8303 | B | 60 | Very lo level S1 | Extremely low level sump 1 | Extremely low level in the sump. Alarm from the analog level input. |
| 8304 | A | 10 | Hi lev float S1 | High level float sump 1 | High level float. Alarm from digital input. |
| 8305 | B | 10 | Lo lev float S1 | Low level float sump 1 | Low level float. Alarm from digital input. |
| 8306 | B | 60 | Hi level sump 2 | High level sump 2 | High level in the pump sump. Alarm from the analog level input. |
| 8307 | B | 60 | Very hi level S2 | Extremely high level sump 2 | Extremely high level in the sump. Alarm from the analog level input. |
| 8308 | B | 60 | Lo level sump 2 | Low level sump 2 | Low level in the pump sump. Alarm from the analog level input. |
| 8309 | B | 60 | Very lo level S2 | Extremely low level sump 2 | Extremely low level in the sump. Alarm from the analog level input. |
| 8310 | A | 10 | Hi lev float S2 | High level float sump 2 | High level float. Alarm from digital input. |
| 8311 | B | 10 | Lo lev float S2 | Low level float sump 2 | Low level float. Alarm from digital input. |
| 8313 | B | | No response P1.1 | No response P1.1 | The RTU has not received a response signal from pump 1.1. The pump has |

| | | | | | |
|------|---|----|------------------|------------------------------|--|
| | | | | | probably failed to start. |
| 8314 | B | 10 | Hi temp. P1.1 | High temperature P1.1 | High temperature pump 1.1. |
| 8315 | B | 10 | Trip. motor P1.1 | Tripped motor protector P1.1 | Pump 1.1 has a triggered motor. The pump is blocked by this alarm. |
| 8316 | B | 10 | P1.1 switch off | P1.1 switched off | The Auto-Manual-Off switch set to off. Pump 1.1 is stopped. |
| 8318 | B | 10 | Hi current P1.1 | High current P1.1 | High current P1.1. Alarm from the analog current input. |
| 8319 | B | 10 | Low current P1.1 | Low current P1.1 | Low current P1.1. Alarm from the analog current input. |
| 8321 | B | | No response P1.2 | No response P1.2 | The RTU has not received a response signal from pump 1.2. The pump has probably failed to start. |
| 8322 | B | 10 | Hi temp. P1.2 | High temperature P1.2 | High temperature pump 1.2. |
| 8323 | B | 10 | Trip. motor P1.2 | Tripped motor protector P1.2 | Pump 1.2 has a triggered motor. The pump is blocked by this alarm. |
| 8324 | B | 10 | P1.2 switch off | P1.2 switched off | The Auto-Manual-Off switch set to off. Pump 1.2 is stopped. |
| 8326 | B | 10 | Hi current P1.2 | High current P1.2 | High current P1.2. Alarm from the analog current input. |
| 8327 | B | 10 | Low current P1.2 | Low current P1.2 | Low current P1.2. Alarm from the analog current input. |
| 8353 | B | | No response P2.1 | No response P2.1 | The RTU has not received a response signal from pump 2.1. The pump has probably failed to start. |
| 8354 | B | 10 | Hi temp. P2.1 | High temperature P2.1 | High temperature pump 2.1. |
| 8355 | B | 10 | Trip. motor P2.1 | Tripped motor protector P2.1 | Pump 2.1 has a triggered motor. The pump is blocked by this alarm. |
| 8356 | B | 10 | P2.1 switch off | P2.1 switched off | The Auto-Manual-Off switch set to off. Pump 2.1 is stopped. |
| 8358 | B | 10 | Hi current P2.1 | High current P2.1 | High current P2.1. Alarm from the analog current input. |
| 8359 | B | 10 | Low current P2.1 | Low current P2.1 | Low current P2.1. Alarm from the analog current input. |
| 8361 | B | | No response P2.2 | No response P2.2 | The RTU has not received a response signal from pump 2.2. The pump has |

| | | | | | |
|------|---|----|------------------|------------------------------|---|
| | | | | | probably failed to start. |
| 8362 | B | 10 | Hi temp. P2.2 | High temperature P2.2 | High temperature pump 2.2. |
| 8363 | B | 10 | Trip. motor P2.2 | Tripped motor protector P2.2 | Pump 2.2 has a triggered motor. The pump is blocked by this alarm. |
| 8364 | B | 10 | P2.2 switch off | P2.2 switched off | The Auto-Manual-Off switch set to off. Pump 2.2 is stopped. |
| 8366 | B | 10 | Hi current P2.2 | High current P2.2 | High current P2.2. Alarm from the analog current input. |
| 8367 | B | 10 | Low current P2.2 | Low current P2.2 | Low current P2.2. Alarm from the analog current input. |
| 8410 | B | 10 | P1.1 High cap. | P1.1, High capacity | The RTU has calculated a capacity higher than the high capacity alarm level for pump 1.1. |
| 8411 | B | 10 | P1.1 Low cap. | P1.1, Low capacity | The RTU has calculated a capacity lower than the low capacity alarm level for pump 1.1. |
| 8412 | B | 10 | P1.2 High cap. | P1.2, High capacity | The RTU has calculated a capacity higher than the high capacity alarm level for pump 1.2. |
| 8413 | B | 10 | P1.2 Low cap. | P1.2, Low capacity | The RTU has calculated a capacity lower than the low capacity alarm level for pump 1.2. |
| 8420 | B | 10 | P2.1 High cap. | P2.1, High capacity | The RTU has calculated a capacity higher than the high capacity alarm level for pump 2.1. |
| 8421 | B | 10 | P2.1 Low cap. | P2.1, Low capacity | The RTU has calculated a capacity lower than the low capacity alarm level for pump 2.1. |
| 8422 | B | 10 | P2.2 High cap. | P2.2, High capacity | The RTU has calculated a capacity higher than the high capacity alarm level for pump 2.2. |
| 8423 | B | 10 | P2.2 Low cap. | P2.2, Low capacity | The RTU has calculated a capacity lower than the low capacity alarm level for pump 2.2. |
| 8430 | B | | Service P1.1 | Service P1.1 | P1.1 has run the set service time. The pump needs service. |
| 8431 | B | | Service P1.2 | Service P1.2 | P1.2 has run the set service time. The pump needs service. |
| 8435 | B | | Service P2.1 | Service P2.1 | P2.1 has run the set service time. The pump needs service. |

| | | | | | |
|------|---|-----|------------------|------------------------------|---|
| 8436 | B | | Service P2.2 | Service P2.2 | P2.2 has run the set service time. The pump needs service. |
| 8440 | B | 10 | Leakage P1.1 | Leakage P1.1 | Water in oil pump 1.1. |
| 8441 | B | 10 | Leakage P1.2 | Leakage P1.2 | Water in oil pump 1.2. |
| 8445 | B | 10 | Leakage P2.1 | Leakage P2.1 | Water in oil pump 2.1. |
| 8446 | B | 10 | Leakage P2.2 | Leakage P2.2 | Water in oil pump 2.2. |
| 8470 | B | | Max starts P1.1 | Max starts P1.1 | P1.1 starts to often. The value that is entered in the channel 'Max start per hour' has been reached. |
| 8471 | B | | Max starts P1.2 | Max starts P1.2 | P1.2 starts to often. The value that is entered in the channel 'Max start per hour' has been reached. |
| 8475 | B | | Max starts P2.1 | Max starts P2.1 | P2.1 starts to often. The value that is entered in the channel 'Max start per hour' has been reached. |
| 8476 | B | | Max starts P2.2 | Max starts P2.2 | P2.2 starts to often. The value that is entered in the channel 'Max start per hour' has been reached. |
| 8536 | H | | Intruder al. off | Intruder alarm deactivated | The intruder alarm is disconnected. |
| 8538 | A | 300 | I/O-mod not resp | I/O module(s) not responding | Communication problems with Sixx units. Communication errors or not responding units may be the reason. |
| 8539 | B | 300 | Wrong I/O module | Wrong type of I/O module | Communication problems with Sixx units. Wrong unit type. |
| 8540 | A | 10 | Pic comm error | Pic communication error | Error on communication between top and bottom card in the RTU. |
| 8541 | B | 120 | Ana.sig < 4 mA | Analogue signal < 4 mA | One of the 4-20 mA analogue inputs receives a signal < 3.5 mA. |
| 8542 | B | | Disk error/low | Disk error/low disk space | Low internal disk space or disk write/read error. |
| 8543 | B | 120 | Ana.sig > 20 mA | Analogue signal > 20 mA | One of the analogue inputs receives a signal > 20.5 mA. |
| 8561 | B | 0 | Sensfault sump 1 | Sensor fault sump 1 | Sensor error. If the value from the sensor not changes then the alarm is trigged. |
| 8562 | B | 0 | Sensfault sump 2 | Sensor fault sump 2 | Sensor error. If the value from the sensor not changes then the alarm is |

| | | | | | |
|------|---|----|------------------|--------------------------------|--|
| | | | | | triggered. |
| 8603 | B | | Blocking | Blocking other stations | The blocking function is activated. This RTU is sending blocking commands to other RTU's. |
| 8610 | B | 10 | High analogue 2 | High analogue 2 | High alarm value general analogue 2. |
| 8611 | B | 10 | Low analogue 2 | Low analogue 2 | Low alarm value general analogue 2. |
| 8628 | A | | Hi lev+pfail S1 | High level+pumpfailure. Sump 1 | There is a high level in the sump and at least one pump is on fail. |
| 8629 | A | | Hi lev+pfail S2 | High level+pumpfailure. Sump 2 | There is a high level in the sump and at least one pump is on fail. |
| 8630 | B | | Testcall ! | Testcall ! | The test alarm are sent to check that the station is alive. It is sent every n:th day at the time in the setpoint. |
| 8632 | B | 10 | High analogue 3 | High analogue 3 | High alarm value general analogue 3. |
| 8633 | B | 10 | Low analogue 3 | Low analogue 3 | Low alarm value general analogue 3. |
| 8650 | B | | High counter 24h | High alarm counter 24 h | The counter has reached the maximum value per 24 hours. |
| 8651 | B | | High count. 5min | High alarm counter 5 min | The counter has reached the maximum value per 5 minutes. |
| 8654 | A | | Fail 2 pumps S1 | Failure on two pumps. Sump 1 | There are two failed pumps. |
| 8655 | A | | Fail 2 pumps S2 | Failure on two pumps. Sump 2 | There are two failed pumps. |
| 8660 | A | 10 | Overflow sump 1 | Overflow sump 1 | Overflowing. The station is now overflowing. |
| 8661 | A | 10 | Overflow sump 2 | Overflow sump 2 | Overflowing. The station is now overflowing. |
| 8718 | B | 10 | Alarm input 18 | Alarm digital input 18 | Spare alarm input 18. |
| 8720 | B | 10 | Alarm input 20 | Alarm digital input 20 | Spare alarm input 20. |
| 8722 | B | 10 | Alarm input 22 | Alarm digital input 22 | Spare alarm input 22. |
| 8724 | B | 10 | Alarm input 24 | Alarm digital input 24 | Spare alarm input 24. |
| 8725 | B | 10 | Alarm input 25 | Alarm digital | Spare alarm input 25. |

| | | | | | |
|------|---|----|----------------|------------------------|-----------------------|
| | | | | input 25 | |
| 8727 | B | 10 | Alarm input 27 | Alarm digital input 27 | Spare alarm input 27. |
| 8728 | B | 10 | Alarm input 28 | Alarm digital input 28 | Spare alarm input 28. |
| 8729 | B | 10 | Alarm input 29 | Alarm digital input 29 | Spare alarm input 29. |
| 8730 | B | 10 | Alarm input 30 | Alarm digital input 30 | Spare alarm input 30. |

19 Appendix E – Central system

19.1 Periodic reporting

RTU stores the following operating data for the 30 previous days. The daily report is fetched automatically from the central system once per day. This function can be disconnected from the system.

The following information is summarized in the periodic report:

Report

| Text1 | Text2 | Text3 | Description |
|----------|------------|-------|---|
| Run time | P1.1 | h | Running time pump 1.1. |
| Run time | P1.2 | h | Running time pump 1.2. |
| Run time | P2.1 | h | Running time pump 2.1. |
| Run time | P2.2 | h | Running time pump 2.2. |
| Runtime | two pumps | h | Running time with two pumps. |
| Runtime | two pumps | h | Running time with two pumps. |
| Overflow | time | h | Overflow time. |
| Blocked | time | h | The time this station has been blocked from another RTU. |
| Runtime | counter | h | Running time counter input. |
| Starts | P1.1 | | Number of starts pump 1.1. |
| Starts | P1.2 | | Number of starts pump 1.2. |
| Starts | P2.1 | | Number of starts pump 2.1. |
| Starts | P2.2 | | Number of starts pump 2.2. |
| Starts | two pumps | | Number of starts with two pumps. |
| Starts | two pumps | | Number of starts with two pumps. |
| Runtime | P1.1 total | h | Running time pump 1.1 total. This is the continuously sum since start-up. |
| Runtime | P1.2 total | h | Running time pump 1.2 total. This is the continuously sum since start-up. |
| Runtime | P2.1 total | h | Running time pump 2.1 total. This is the continuously sum since start-up. |

| | | | |
|-----------|------------|-----------|---|
| Runtime | P2.2 total | h | Running time pump 2.2 total. This is the continuously sum since start-up. |
| Capacity | P1.1 | l/s | Calculated capacity pump 1.1. |
| Capacity | P1.2 | l/s | Calculated capacity pump 1.2. |
| Capacity | P2.1 | l/s | Calculated capacity pump 2.1. |
| Capacity | P2.2 | l/s | Calculated capacity pump 2.2. |
| Inflow | vol sump 1 | m3 | Inflow volume into sump 1. |
| Pumped | vol sump 1 | m3 | Pumped volume from sump 1. |
| Number of | overflows | | Number of overflow events. |
| Number of | gross | overflows | Number of gross overflow events. |
| Overflow | volume | m3 | Overflow volume. |
| Volume | analogue 2 | m3 | General analogue 2 volume. |
| Volume | analogue 3 | m3 | General analogue 3 volume. |
| Energy | | kWh | Energy. |
| Blocked | events | | Number of times this station has been blocked from another RTU. |
| Counter | value | | Counter. |
| Inflow | vol sump 2 | m3 | Inflow volume into sump 2. |
| Pumped | vol sump 2 | m3 | Pumped volume from sump 2. |

19.2 Historical trend

Measurements are stored in RTU at intervals of five minutes as default and are fetched from the central system one or more times every day. The information can then be displayed in graphical form. This function can be disconnected from the system.

The following figures can be presented in the form of a trend graph:

Trend

| Text1 | Text2 | Text3 | Description |
|-------|--------|-------|------------------|
| Level | sump 1 | m | Level in sump 1. |
| Level | sump 2 | m | Level in sump 2. |

| | | | |
|----------|------------|--------------------|-----------------------------|
| Current | P1.1 | A | Current for pump 1.1. |
| Current | P1.2 | A | Current for pump 1.2. |
| Current | P2.1 | A | Current for pump 2.1. |
| Current | P2.2 | A | Current for pump 2.2. |
| Value | analogue 2 | | General analogue 2. |
| Value | analogue 3 | | General analogue 3. |
| Capacity | P1.1 | l/s | Capacity for pump 1.1. |
| Capacity | P1.2 | l/s | Capacity for pump 1.2. |
| Capacity | P2.1 | l/s | Capacity for pump 2.1. |
| Capacity | P2.2 | l/s | Capacity for pump 2.2. |
| Inflow | sump 1 | l/s | Inflow in sump 1. |
| Pumped | fl. sump 1 | l/s | Pump flow from sump 1. |
| Pumped | vol sump 1 | m ³ | Pumped volume sump 1. |
| Overflow | | l/s | Overflow. |
| Power | | kW | Power consumption. |
| Specific | energy | kWh/m ³ | Specific energy. |
| Counter | | value/5min | Counter value per 5 minute. |
| Counter | 24 h | sum | Counter sum over 24 hours. |
| Inflow | sump 2 | l/s | Inflow in sump 2. |
| Pumped | fl. sump 2 | l/s | Pump flow from sump 2. |
| Pumped | vol sump 2 | m ³ | Pumped volume sump 2. |

19.3 Remote control

The pumps can be operated by remote control as required. In this case, the units are not controlled by level, but in response to commands from the workstation. Only when the connection is switched out does pump control revert automatically to RTU.



If pump related alarms are active the pump will not start remotely.

Remote Control

| Object | Description |
|--------|--|
| P1.1 | Pump 1.1. Start and stop of pump. Temporary control while active status picture. The function remote control break delay may extend the manual control of the pump. The pump will not start on remote commands if there is a fault active on the pump. |
| P1.2 | Pump 1.2. Start and stop of pump. Temporary control while active status picture. The function remote control break delay may extend the manual control of the pump. The pump will not start on remote commands if there is a fault active on the pump. |
| S1 | Control of cleaning function in pump sump. |
| P2.1 | Pump 2.1. Start and stop of pump. Temporary control while active status picture. The function remote control break delay may extend the manual control of the pump. The pump will not start on remote commands if there is a fault active on the pump. |
| P2.2 | Pump 2.2. Start and stop of pump. Temporary control while active status picture. The function remote control break delay may extend the manual control of the pump. The pump will not start on remote commands if there is a fault active on the pump. |
| S2 | Control of cleaning function in pump sump. |
| ALARMS | Acknowledge paging alarms. If alarms is sent from the RTU directly to the pager then it is possible to acknowledge the alarms here. |
| BLOCK | Control of blocking for this station. |
| RO1 | Control of output 1. |
| RO2 | Control of output 2. |
| AUTO | Return control to automatic. Releases all remote control commands. |

20 Appendix F – Connection



N.B.

Ensure that personnel cannot come in contact with live cabling or terminal blocks in the course of connection or service work. Maximum caution must be exercised when working on the digital outputs.

The following is a description of the terminal blocks in the RTU (see wiring diagram at rear of section).

Before connecting external electrical equipment, such as relays, coils etc., to outputs or inputs, check carefully that the electrical specifications comply with those of the RTU. If this is not the case, install the necessary protective equipment to avoid the occurrence of operating disturbances.

Digital input signals

1 - Std digital in - Digital in.

| Signal No | Terminal No | Description |
|-----------|-------------|---|
| 01:01 | 3 - 4 | Fixed input 01: P1.1 Response |
| 01:02 | 5 - 6 | Fixed input 02: P1.2 Response |
| 01:03 | 7 - 8 | Fixed input 03: P2.1 Response |
| 01:04 | 9 - 10 | Fixed input 04: P2.2 Response |
| 01:05 | 11 - 12 | Fixed input 05: P1.1 Tripped |
| 01:06 | 13 - 14 | Fixed input 06: P1.2 Tripped |
| 01:07 | 15 - 16 | Fixed input 07: P2.1 Tripped |
| 01:08 | 17 - 18 | Fixed input 08: P2.2 Tripped |
| 01:09 | 19 - 20 | Fixed input 09: Power fail |
| 01:10 | 21 - 22 | Fixed input 10: High float sump1 |
| 01:11 | 23 - 24 | Multi input 11: 0=Not used, 1=Overflow sensor, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 01:12 | 25 - 26 | Multi input 12: 0=Not used, 1=Counter pulse, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 01:13 | 27 - 28 | Multi input 13: 0=Not used, 1=P1.1 Off switch, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 01:14 | 29 - 30 | Multi input 14: 0=Not used, 1=P1.2 Off switch, 2=Spare alarm, 3=Intruder |

| | | |
|-------|---------|---|
| | | sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 01:15 | 31 - 32 | Multi input 15: 0=Not used, 1=P2.1 Off switch, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 01:16 | 33 - 34 | Multi input 16: 0=Not used, 1=P2.2 Off switch, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |

4 - RIO S45 - Address: 1 Extra digital in/out

| Signal No | Terminal No | Description |
|-----------|-------------|--|
| 04:08 | 10 | Fixed input 17: P1.1 High temp. |
| 04:09 | 11 | Multi input 18: 0=Not used, 1=P1.1 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 04:10 | 12 | Fixed input 19: P1.2 High temp. |
| 04:11 | 13 | Multi input 20: 0=Not used, 1=P1.2 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 04:12 | 14 | Fixed input 21: P2.1 High temp. |
| 04:13 | 15 | Multi input 22: 0=Not used, 1=P2.1 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 04:14 | 16 | Fixed input 23: P2.2 High temp. |
| 04:15 | 17 | Multi input 24: 0=Not used, 1=P2.2 Leakage, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 04:16 | 18 | Multi input 25: 0=Not used, 1=Low float sump 1, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote. |
| 04:17 | 19 | Fixed input 26: High float sump2 |
| 04:18 | 20 | Multi input 27: 0=Not used, 1=Low float sump 2, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 04:19 | 21 | Multi input 28: 0=Not used, 1=Timer 1, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 04:20 | 22 | Multi input 29: 0=Not used, 1=Timer 2, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |
| 04:21 | 23 | Multi input 30: 0=Not used, 1=Personnel onsite, 2=Spare alarm, 3=Intruder sensor, 4=Intr.sens+pers., 5=Block remote, 6=Energy pulse. |

Digital output signals

2 - Std digital out - Digital out.

| Signal No | Terminal No | Description |
|-----------|-------------|--|
| 02:01 | 53 - 54 | Fixed output 01: Run P1.1 |
| 02:02 | 55 - 56 | Fixed output 02: Run P1.2 |
| 02:03 | 57 - 58 | Fixed output 03: Run P2.1 |
| 02:04 | 59 - 60 | Fixed output 04: Run P2.2 |
| 02:05 | 61 - 62 | Multi output signal 05: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |
| 02:06 | 63 - 64 | Multi output signal 06: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset. |
| 02:07 | 65 - 66 | Multi output signal 07: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |
| 02:08 | 67 - 68 | Multi output signal 08: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset. |

4 - RIO S45 - Address: 1 Extra digital in/out

| Signal No | Terminal No | Description |
|-----------|-------------|--|
| 04:02 | 2 | Multi output signal 10: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset. |
| 04:01 | 1 | Multi output signal 09: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |

| | | |
|-------|---|--|
| 04:03 | 3 | Multi output signal 11: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |
| 04:04 | 4 | Multi output signal 12: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset. |
| 04:05 | 5 | Multi output signal 13: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |
| 04:06 | 5 | Multi output signal 14: 0=Not used, 1=Extr. low lev. 1, 2=Extr. low lev. 2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 2, 8=Timer 2 out, 9=Watchdog, 10=Remote 2, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 2, 15=Generic analog 3, 16=Modem reset. |
| 04:07 | 7 | Multi output signal 15: 0=Not used, 1=Extr. high lev.1, 2=Extr. high lev.2, 3=Remote blocked, 4=Alarm pulse, 5=Alarm status, 6=Alarm active, 7=Sprinkler sump 1, 8=Timer 1 out, 9=Watchdog, 10=Remote 1, 11=Buzzer, 12=Siren, 13=Buzzer+siren, 14=Vol.pulse sump 1, 15=Generic analog 2, 16=Modem reset. |

Analogue input signals

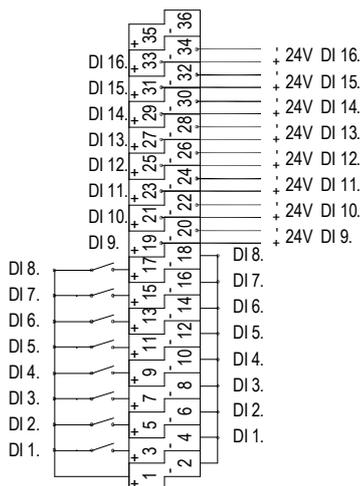
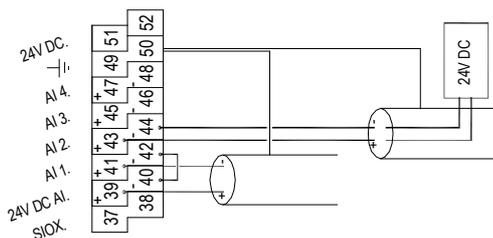
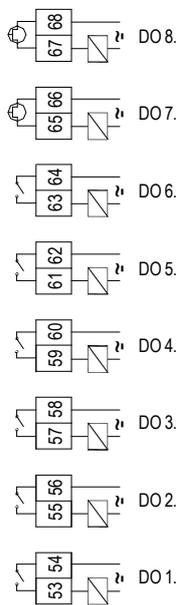
3 - Std analogue in - Analog in.

| Signal No | Terminal No | Description |
|-----------|-------------|---|
| 03:01 | 41 - 42 | Pump sump 1 level. Level signal for pump control and flow calculations. |
| 03:02 | 43 - 44 | Unscaled general analog 2. |
| 03:03 | 45 - 46 | Unscaled general analog 3. |
| 03:04 | 47 - 48 | Pump sump 2 level. Level signal for pump control and flow calculations. |

5 - RIO S48 - Address: 2 Extra analog in/out

| Signal No | Terminal No | Description |
|-----------|-------------|----------------------------|
| 05:03 | 2 - 3 | Unscaled current signal 1. |
| 05:04 | 4 - 5 | Unscaled current signal 2. |

| | | |
|-------|-------|----------------------------|
| 05:05 | 6 - 7 | Unscaled current signal 3. |
| 05:06 | 8 - 9 | Unscaled current signal 4. |



RTU

| | |
|------|---------------------------------|
| DO1 | Digital output signal 1 |
| DO2 | Digital output signal 2 |
| DO3 | Digital output signal 3 |
| DO4 | Digital output signal 4 |
| DO5 | Digital output signal 5 |
| DO6 | Digital output signal 6 |
| DO7 | Digital output signal 7 |
| DO8 | Digital output signal 8 |
| AI1 | 4-20 mA analogue input signal 1 |
| AI2 | 4-20 mA analogue input signal 2 |
| AI3 | 4-20 mA analogue input signal 3 |
| AI4 | 4-20 mA analogue input signal 4 |
| DI1 | Digital input signal 1 |
| DI2 | Digital input signal 2 |
| DI3 | Digital input signal 3 |
| DI4 | Digital input signal 4 |
| DI5 | Digital input signal 5 |
| DI6 | Digital input signal 6 |
| DI7 | Digital input signal 7 |
| DI8 | Digital input signal 8 |
| DI9 | Digital input signal 9 |
| DI10 | Digital input signal 10 |
| DI11 | Digital input signal 11 |
| DI12 | Digital input signal 12 |
| DI13 | Digital input signal 13 |
| DI14 | Digital input signal 14 |
| DI15 | Digital input signal 15 |
| DI16 | Digital input signal 16 |

Example 1

Connection of digital inputs signals for normally open contacts. In this example DI 1-8

Example 2

Connection for digital input signal if the equipment delivers a voltage. In this example DI9-16. Note: No jumpers on the negative side.

Example 3

Connection for analogue input signals when a two-wire sensor is supplied with power from the RTU. In this example AI1.

Example 4

Connection for analogue input signals if the sensor is supplied from an external power supply. In this example AI2.

