# CO<sub>2</sub>P<sub>3</sub>S Installation Guide and User Manual Version 1.1

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#### Abstract

This document is an installation guide and user manual for Version 1.0 of the  $CO_2P_3S$  parallel programming system.  $CO_2P_3S$  is a programming system for designing, coding, and executing parallel programs that execute in a shared memory environment.  $CO_2P_3S$  generates framework code from a design pattern description of the structure of a program. The framework code contains all of the necessary communication and synchronization for the selected program structure. Application code is inserted by implementing sequential hook methods that are called by the larger framework structure.

## **1** Introduction

CO<sub>2</sub>P<sub>3</sub>S (Correct Object–Oriented Pattern–based Parallel Programming System, pronounced "cops") combines design patterns and object-oriented frameworks into a process for writing highperformance object-oriented programs that execute on multiple processors. At the highest level of application development, you specify the parallel structure of your program using a set of supported design pattern templates. Much like the patterns they are based upon, pattern templates represent a family of solutions to a design problem. You specialize the pattern template to select the most appropriate member of this family by specifying values for design pattern template *parameters.* Once the best pattern structure is selected, the pattern template is used to generate object–oriented framework code implementing the specific structure that you've selected.  $CO_2P_3S$ currently generates multithreaded Java code targeted at shared memory multiprocessors. This framework code encapsulates all of the communication and synchronization code needed for the selected structure, and is hidden from you to reduce the possibility of errors. To complete a program, you need only implement sequential hook methods that are invoked from the generated structure. Lower layers gradually expose the generated code using high-level abstractions, and then the implementation of these abstractions. These layers provide performance tuning opportunities and flexibility in a controlled manner.

This document serves as an installation guide and user manual for the  $CO_2P_3S$  parallel programming system. Section 2 describes the steps in the installation process. This section describes the general process; this release of  $CO_2P_3S$  was assembled with some of these steps already completed to minimize your effort. Section 3 describes the execution environment and general programming model of  $CO_2P_3S$ . Section 4 shows the features of the user interface in detail. Note that this section does not describe the pattern templates in detail. Documentation for the templates is available through the interface. Section 6 and 5 give a description of the new features that  $CO_2P_3S$  has in the current release.

# 2 Installing $CO_2P_3S$

## 2.1 Operating System

We have successfully run  $CO_2P_3S$  using native-threaded Java virtual machines (VMs) on the following operating systems:

- Linux
- Solaris
- SGI Irix

Since  $CO_2P_3S$  is a Java tool generating Java code, it may run on other platforms. However, we did not develop the tool with portability in mind, so we cannot guarantee that either the tool or the generated framework code will run correctly on other platforms. You may experience problems with the  $CO_2P_3S$  user interface. Differences in thread scheduling policies on different operating systems may cause problems in the generated frameworks. If you successfully use  $CO_2P_3S$  on a different operating system, please let us know and we will add it to the above list.

## 2.2 Other System Requirements

You will need the following hardware configuration and software installed on your system for  $CO_2P_3S$  to work properly:

- A Java distribution, Version 1.2 or higher. This distribution must include both a compiler and a run–time environment. The run–time environment must support native threads to take advantage of multiple processors.
- A Perl distribution, Version 5 or higher. It must be possible to start the executable using the command:

/usr/bin/perl

This can be either the executable program or a link to the executable.

- Any version of GNU make. This is required to compile your  $CO_2P_3S$  distribution.
- A computer with an active network connection. CO<sub>2</sub>P<sub>3</sub>S uses XML documents to store relevant program and tool configuration information, and the document descriptions are accessed via the World Wide Web. It is possible to work around this requirement; see Section 4.7 for details. Also, the network connection is required to use the distributed CO<sub>2</sub>P<sub>3</sub>S environment [6].

• If you want parallel speedups, you will need a shared memory multiprocessor computer system. CO<sub>2</sub>P<sub>3</sub>S will work on uniprocessor machines, but you will not likely experience any performance improvements. In fact, you will most likely experience performance degradation. However, when testing for the correctness of a program, such a system may still be useful.

## 2.3 CO<sub>2</sub>P<sub>3</sub>S Installation Process

To compile and install CO<sub>2</sub>P<sub>3</sub>S on your computer, you will need to do the following:

1. Obtain a copy of the source code distribution. This comes as either a gzipped tar file or a zip file. This is available through the World Wide Web at:

```
http://www.cs.ualberta.ca/~systems/cops/index.html
```

through the Downloads link on the left-hand frame.

2. Select a directory for your CO<sub>2</sub>P<sub>3</sub>S installation, which we will refer to as COPSDIR for the rest of this document. Extract the contents of the distribution. The CO<sub>2</sub>P<sub>3</sub>S distribution will unarchive into a subdirectory "copsProj". For the gzipped tar file, use the command (where "%" is your shell prompt, and replacing copsDistribution.tar.gz with the name of the distribution file):

% tar xvfz copsDistribution.tar.gz

or

```
% zcat copsDistribution.tar.gz | tar x
```

For a zip file, use the command

% unzip copsDistribution.zip

- 3. Add the following directories and JAR files to your CLASSPATH variable, using the correct means for your operating system or shell:
  - .
  - COPS\_HOME
  - COPS\_HOME/libs/jdom.jar
  - COPS\_HOME/libs/xalan.jar
  - COPS\_HOME/libs/xerces.jar
  - JAVA\_HOME/lib/tools.jar
  - COPS\_HOME/jini1\_1/jini-core.jar
  - COPS\_HOME/jini1\_1/jini-ext.jar
  - COPS\_HOME/jini1\_1/jini-code.jar

• COPS\_HOME/jini1\_1/norm.jar

Make sure COPS\_HOME points to your cops installation dir (such as \$HOME/copsProj), JAVA\_HOME points to your jdk1.4.1 install, and JINI\_HOME points to COPS\_HOME/jini1\_1

(The last four items are used by the current release of  $CO_2P_3S$ , which supports distributed memory programs.) This step must be done before you compile or run  $CO_2P_3S$ .

- 4. Add the following directory to your PATH variable:
  - COPS\_HOME/binUtil

If you install a jdk in your local space, be sure to set  $JAVA\_HOME$  to your local jdk install and add  $JAVA\_HOME/bin$  to your PATH variable. This step must be done before you compile or run  $CO_2P_3S$ .

5. The current release has already been compiled, so you can skip this step. However, you still need to complete all of the earlier steps. If you have a source–only distribution, you will need to build CO<sub>2</sub>P<sub>3</sub>S. Change to the directory COPS\_HOME/. Build the distribution using the command (where "%" is your shell prompt):

% make

## 2.4 Configuring CO<sub>2</sub>P<sub>3</sub>S

If you are using a pre-compiled  $CO_2P_3Sdistribution$ , you can skip this step. The  $CO_2P_3Ssystem$  can be directly launched.

After compiling  $CO_2P_3S$ , you must configure it before you can execute it.  $CO_2P_3S$  configuration consists of two stages. The first stage is setting the properties for the user interface. The second stage is adding pattern templates to the user interface. Since the second stage requires you to run the  $CO_2P_3S$  user interface, this process is also described in this section.

This release of  $CO_2P_3S$  was assembled to minimize the amount of work you need to do before using the system. As a result, some of the steps below are not required. However, this information will be useful for future releases.

#### 2.4.1 CO<sub>2</sub>P<sub>3</sub>S Properties

First, copy the file COPS\_HOME/copsProj/copsrc.xml to \$HOME/.copsrc.xml (note the extra period). \$HOME is your home directory as defined by the Java system property user.home. If you are unsure about the value of this property, you can get it by printing the result of the Java method call:

```
System.getProperties().getProperty("user.home")
```

In a UNIX environment, this should correspond to your normal home directory.

Copy the file  $COPS_HOME/.copsrc.xml$  to HOME/.copsrc.xml. The default file is shown in Figure 1. This file contains configuration properties used by the  $CO_2P_3S$  graphical user

<?xml version="1.0"?> <!- - This is a sample RC file for the CO2P3S program. The location for this file on the user's system is \$HOME/.copsrc.xml - -> <!DOCTYPE CopsCfg:copsCfg SYSTEM "http://www.cs.ualberta.ca/~systems/DTD/1.0/CopsCfg.dtd"> <CopsCfg:copsCfg xmlns:CopsCfg="http://www/cs.ualberta.ca/~systems/cops/cfg/"> 10 <CopsCfg:copsInstallationDirectory> installation path of COPS </CopsCfg:copsInstallationDirectory> <CopsCfg:userProgramDirectory> path to user programs </CopsCfg:userProgramDirectory> <CopsCfg:defaultEditor> name of default Java code editor 20 </CopsCfg:defaultEditor> <CopsCfg:htmlBrowser> name of HTML browser </CopsCfg:htmlBrowser> <CopsCfg:patterns> <CopsCfg:patternName>Mesh</CopsCfg:patternName> <CopsCfg:patternName>Distributor</CopsCfg:patternName> <CopsCfg:patternName>Phases</CopsCfg:patternName> </CopsCfg:patterns> 30 <CopsCfg:jiniPolicyDirectory> install path of COPS/Distributed/JINI/policy/policy.all </CopsCfg:jiniPolicyDirectory> <CopsCfg:jiniLUSAddress> URL for lookup service </CopsCfg:jiniLUSAddress> </CopsCfg:copsCfg>

Figure 1: The default XML file that comes with a  $CO_2P_3S$  distribution.

interface. Some of these properties must be filled in before  $CO_2P_3S$  can be run. Some can be reset or must be set through the user interface.

The first part of the XML file consists of header and definition information. You should not find it necessary to change any part of the first 9 lines (with one possible exception). Lines 1 is header information regarding the XML file. Lines 2 and 3 are a comment indicating the purpose and location for this file. Line 4 and 5 indicate where the DTD (Document Type Definition) file for this document can be found. The DTD file indicates the format of the XML file, including all legal tags. Since this file is referenced through a URL, your machine must have an active network connection for  $CO_2P_3S$  to work properly. See Section 4.7 for a workaround if you plan to use  $CO_2P_3S$  on a machine that cannot access this URL. Lines 7 and 8 define a name space for the XML document.  $CO_2P_3S$  will work properly if you cannot access this URL.

The region of interest in the .copsrc.xml file starts at line 10 and ends at line 39. The format of the configuration fields is that of standard XML. Each field starts with the XML tag

<CopsCfg:fieldName>

where *fieldName* is the name of the configuration field. The field ends with the tag

</CopsCfg:fieldName>

where *fieldName* must match the starting tag. The value of the field is contained between these two tags. Tags can appear inside of other tags, but they must be properly nested.

The current  $CO_2P_3S$  configuration has the following fields:

- **copsInstallationDirectory** This is the path to the CO<sub>2</sub>P<sub>3</sub>S installation. This field has to be filled in manually, before CO<sub>2</sub>P<sub>3</sub>S is run the first time. The correct value for this field is \$HOME/copsProj. From this point onward, COPSINSTALL refers to this directory.
- **userProgramDirectory** This is the full path of default directory for your  $CO_2P_3S$  programs. If no value is entered or the supplied directory does not exist, your home directory (as defined earlier in this section) is used. This can be entered either here or through the user interface. However, because of interface limitations (described in Section 4.7), it should be filled in before you open or create a program in  $CO_2P_3S$  for the first time.
- **defaultEditor** This is the name of your favourite text editor. This editor is used to edit extra program files that you wish to incorporate into a  $CO_2P_3S$  program. This field can be entered now or entered later using the  $CO_2P_3S$  interface. Note that the selected editor must execute in its own window, as  $CO_2P_3S$  will not do this for you. For editors such as emacs and gvim, this is not a problem. On the other hand, vi does not start its own window. On X11 systems, this can be remedied by specifying

xterm -e vi

as the value of this attribute. You can replace vi with other console-based editors.

**htmlBrowser** This is the name of your favourite HTML browser. This browser will be used to display HTML documentation for the design pattern templates in  $CO_2P_3S$ . This field can be entered now or entered later using the  $CO_2P_3S$  interface. As with the editor, this browser

must execute in its own window, so browsers such as lynx must be started the same way that the vi editor is above. However, most of the documentation pages also include graphics, so a graphical browser is best.

- **patterns** This field contains a list of the current pattern templates that have been loaded into the  $CO_2P_3S$  interface. You should not change this field manually. It will be updated as you add and remove templates in the interface, as described in Section 2.4.3. This field already includes entries for the three pattern templates provided with this distribution of  $CO_2P_3S$ .
- **jiniPolicyDirectory** This field is for the distributed CO<sub>2</sub>P<sub>3</sub>S that includes distributed pattern templates.
- **jiniLUSAddress** This field is for the distributed  $CO_2P_3S$ . You can set the IP address of any workstation you want use to start up Jini infrastructure components.

Line 39 ends the configuration file.

#### 2.4.2 Running $CO_2P_3S$

To run  $CO_2P_3S$ , use the script supplied with the distribution. This script can be found at

COPS\_HOME/runCops

It can be executed from this location, or copied to a directory within your normal path for executables. When  $CO_2P_3S$  is run, a log file cops.log is created in the current directory. This file logs events and errors in the user interface. If you experience problems, you can view the log by selecting View Log from the File menu.

The initial screen for  $CO_2P_3S$  is shown in Figure 2. For the remainder of this section, the menus at the top of the window are the points of interest.

#### 2.4.3 Adding Pattern Templates to CO<sub>2</sub>P<sub>3</sub>S

When you first start  $CO_2P_3S$ , it will have twelve pattern templates already installed: the Abstract Factory, the Composite, the Decorator, the Observer, the Singleton, the Phases, the Distributor, the Distributed-mem version of Distributor, the Two–Dimensional Mesh, the Distributed-mem of Mesh, the Wavefront, and the Distributed-memory version of Wavefront. These twelve pattern template will appear when you create a new program or open an existing one. You can use these templates in your programs. However,  $CO_2P_3S$  is an extensible system that allows you to add new pattern templates as they are developed. Later distributions will include tools to help you create your own pattern templates, and we hope to create a repository for you to exchange your templates with other users.

The process of adding a new pattern template is best done from the initial  $CO_2P_3S$  screen (Figure 2), as follows:

1. Select the Environment menu from the menu bar on the top of the interface. Then select Import Pattern, shown in Figure 3(a).

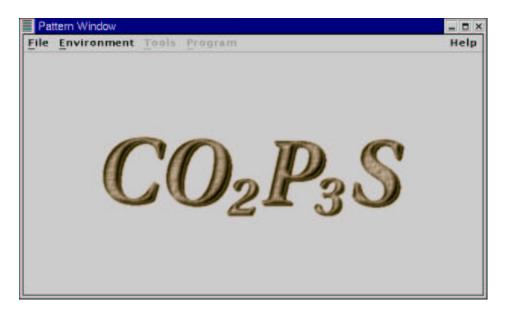


Figure 2: The initial screen of  $CO_2P_3S$ .

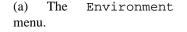
- 2. After you select Import Pattern, the dialog in Figure 3(b) will appear. You use this dialog to select a pattern template to import. By default, this dialog looks for pattern templates in the directory COPSINSTALL/patterns, which is where the templates bundled with your  $CO_2P_3S$  distribution can be found. If you have downloaded other patterns, navigate to the directory where you have installed them.
- 3. Once you have navigated to the appropriate directory, select the XML file for the pattern template you wish to add. Select it and click OK, and wait for the template to load. This process can take some time, as the contents of the XML file are used to generate Java source code which is then compiled.
- 4. You can repeat the last two steps for all pattern templates you wish to add.
- 5. As the interface instructs you, quit  $CO_2P_3S$  (by selecting Quit from the File menu). The new pattern templates will be available the next time you start  $CO_2P_3S$ . (This is why we recommend you add new templates from the initial screen, so you don't interrupt work on a current program.)

#### 2.4.4 Removing Pattern Templates from CO<sub>2</sub>P<sub>3</sub>S

If you decide that a pattern template is no longer useful, you can remove it from  $CO_2P_3S$ . As with adding a template, this can be done from the initial  $CO_2P_3S$  screen. However, if you do so, you will not be able to modify any programs that use that pattern template.

To remove a pattern template, select the Environment menu item from the menu bar at the top of the interface. From this menu, select Remove Pattern (Figure 3(a)). This is a cascaded menu item, where the items that appear are a list of the currently imported pattern templates. Select the pattern template that you wish to remove, as shown in Figure 4. After you confirm your

		Select Patt	em File		
		Look <u>i</u> n:	<b>patterns</b>	• 🖬 1	
		Phases			
		Wavefront			
		DDistribut	or.xml		
		DMesh.xm	1		
		Distributor	r. xml		
		Mesh.xml			
		Phases.xm	1		
ironment Taols Prot	gram	Wavefront.	xml		
nport Pattern	Ctrl-A	Contractor and			
emove Pattern		File <u>n</u> ame:	Mesh.xml		ОК
reate or Edit Pattern	Gtrl-I	Files of ty	pe: All Files (*.*)		- Cancel
references	GtrI-E				



(b) The pattern file selection dialog.

Figure 3: User interface elements for adding pattern templates in CO<sub>2</sub>P<sub>3</sub>S.

Import Pattern	Ctrl-A	
Remove Pattern		Phases
Create or Edit Pattern		Wavefront
Preferences	Ctrl-E	Mesh

Figure 4: Removing a pattern template from CO<sub>2</sub>P<sub>3</sub>S.

selection, the pattern template will be removed from  $CO_2P_3S$ . It can be added back into  $CO_2P_3S$  using the process in Section 2.4.3.

## 2.5 Setting Preferences with the Graphical User Interface

From the Environment menu (Figure 3(a)), you can set your  $CO_2P_3S$  preferences at any time by selecting Preferences. When you select this item, the dialog in Figure 5 appears. This dialog allows you to set the userProgramDirectory, defaultEditor, htmlBrowser, jiniPolicyDirectory, and jiniLUSAddress properties described in Section 2.4.1. The remaining properties cannot be set through this dialog. You have to set User program Directory to make it point to your local directory which contains all  $CO_2P_3$ Sprograms. Change the default value in the dialogue to the absolute address of your directory. The directory of your Jini Policy should be set to COPS\_HOME/Distributed/JINI/policy/policy.all. If you choose to use the  $CO_2P_3$ Sto support distributed-memory programming, you need to choose a machine in your LAN to setup Jini infrastracture components. Fill in the ip address of the chosen machine in Jini Lookup Service Address.

Default Editor emacs	
User Program Directory /home/stevem/phd	/software/program
Default HTML Browser netscape	
JINI Policy Directory	

Figure 5: The Preferences dialog.

# **3** About $CO_2P_3S$

This section describes some of the more general details of the  $CO_2P_3S$  parallel programming system. This includes information on the execution environment for your programs and the programming model supported by the tool.

### 3.1 Execution Environment

CO<sub>2</sub>P<sub>3</sub>S generates multithreaded as well as multiprocess Java code for the supported parallel design pattern templates. This code can be run on a uniprocessor or shared memory multiprocessor or networks of workstations or clusters. On a multiprocessor system, you can used native threads, which allows the Java Virtual Machine to map the threads to different processors. This will hopefully result in performance improvements, by using different processors to execute different parts of your program in parallel.

 $CO_2P_3S$  assumes that there is an active network connection. This connection is used to verify the validity of some of the XML files contained within the  $CO_2P_3S$  system. Section 4.7 contains instructions for removing this dependency if you need to.

For shared-memory programming,  $CO_2P_3S$  has no special requirements regarding file systems. Applications that use disk will need to make sure files are available to all threads that need them. On most shared memory machines, this should not be an issue. However, if  $CO_2P_3S$  used to support distributed-memory programming, we assume that a user's logins into different machines on the network have access to the same directory in the file system. This is to guareentee java classes can be loaded by using the same script on different machines.

### 3.2 Programming Model

The programming model for  $CO_2P_3S$  consists of three layers of user–accessible abstraction. Each layer provides distinct abstractions supporting different phases of program development. In addition, each layer gradually exposes more implementation details of the object–oriented framework code generated by  $CO_2P_3S$ , providing *openness* (which, in this sense, means that you can access low–level structures and run–time code to improve the performance of your application). More

information on programming in  $\mathrm{CO}_2 P_3 S$  can be found in our papers available through the <code>Publications</code> link at

http://www.cs.ualberta.ca/~systems/cops/index.html

The layers of  $CO_2P_3S$  are listed below. The current distribution only supports the topmost layer. The layers are:

**Patterns Layer** At this layer, you express the structure of your program by selecting the appropriate *parallel design pattern templates*. A design pattern template is a design construct that represents a family of related design pattern implementations. Each implementation has the same basic structure, but each is a slight structural variation that makes the pattern more applicable to your specific problem. To select the member of the family that best suits your problem, you provide values for *pattern template parameters* associated with each template.

After you have provided appropriate values for the pattern template parameters, you use the fully–specified template to create an object–oriented framework that implements the selected pattern structure. An object–oriented framework is a set of (usually) abstract classes that provide a design and partial implementation of the application–independent part of a specific kind of application, such as a graphical user interface. In our case, the application domain is the implementation of a parallel structural pattern. The structural part of the framework calls a set of *hook methods* at execution points where application–specific operations are required. You complete a program by providing implementations of these hook methods by subclassing the framework classes and overriding the required methods.

For our parallel frameworks, the structural code includes all of the error-prone communication and synchronization code required by a pattern implementation. The hook methods are sequential code. They do not require any parallel code for the framework to operate correctly. In many programs, the hook method code for a generated framework can be taken directly from an existing sequential program, possibly using the Adapter design pattern [1].

Documentation on the pattern template parameters and the generated framework code is provided with each template and is not part of this document.

To reduce the possibility of programmer error, the structural framework code is encapsulated away from you at this layer of development. Other errors are prevented through the user interface, which is illustrated in Section 4.

**Intermediate Code Layer** This layer provides a high–level explicitly parallel programming language based on a superset of an existing language, such as Java or C++. It provides high– level abstractions for expressing parallelism and synchronization.

At this layer, the structural framework code generated at the Patterns Layer is made available, implemented in the high–level language. You can optimize the code or implement a pattern variation that is not supported by the template parameters. Alternately, you can skip the Patterns Layer and write programs directly in this language.

**Native Code Layer** This layer provides a base object-oriented programming language together with any libraries used to implement the abstractions in higher layers. The libraries can be optimized for your particular execution environment.

## 4 The CO<sub>2</sub>P<sub>3</sub>S Graphical User Interface

### 4.1 **Program Organization**

A CO<sub>2</sub>P<sub>3</sub>S program is a directory with the following subdirectories:

src This subdirectory contains the complete source code for a CO<sub>2</sub>P<sub>3</sub>S program. This code includes both the generated source code and additional source file you add to your program (Section 4.4.3). You should use the CO<sub>2</sub>P<sub>3</sub>S user interface to work on all of these source files. Otherwise, any changes you make may be overwritten during source code generation.

classes This subdirectory contains the Java bytecode files for the program.

- **cops\_patterns** This subdirectory contains saved information on the pattern templates in your  $CO_2P_3S$  program. You should not change any of the contents of this directory.
- **cops\_html** This subdirectory contains HTML files for the classes with hook methods for a given framework. Again, the contents of this subdirectory should not be modified.
- **cops\_methods** This subdirectory contains the bodies of the application–specific hook methods that you have implemented. The contents should not be altered manually.

Other directories are also included in a  $CO_2P_3S$  program, and you can create others to manage additional data for your application. It is important that you not modify the contents of any of the above directories by hand. The user interface provides safe access to the files that you can modify.

### 4.2 Opening or Creating a CO<sub>2</sub>P<sub>3</sub>S Program

The first step in working with  $CO_2P_3S$  is to open an existing program or create a new one. These operations are available through the File menu (Figure 6). The dialog for opening a program is given in Figure 7.

This dialog starts looking for  $CO_2P_3S$  programs in the directory indicated by the userProgramDirectory attribute in your preferences. This is the standard file chooser in Java, and can be used to navigate your files. The items with the  $CO_2P_3S$  logo on the left are directories with a subdirectory structure matching that described in Section 4.1. You can select one of these directories and select Open to work on that program.

Creating a new program is almost identical. A similar file chooser appears, again starting in the directory indicated in your preferences. You navigate to where you would like your program to be kept and enter in the name of the program. The directory for the program, including all of its subdirectories, is created. The empty program is opened and you can begin work on it.

### 4.3 Saving a CO<sub>2</sub>P<sub>3</sub>S Program

Of course, you will want to save the state of your  $CO_2P_3S$  programs as you work on them. This is done by selecting Save from the File menu. It is important to note that this only saves the configuration information of a program, such as the current set of patterns and their values.



Figure 6: The File menu.

Open Progr	am				
Look <u>i</u> n:	🗖 pro	ograms	•	1	C 88 8=
backups	-				
$CO_2P_3S$	PSRS				
$CO_2P_3S$		no			
$CO_2P_3S$	-				
File <u>n</u> ame:	R	leactionDiffusion			<u>O</u> pen
	e:	Directories On			Cancel

Figure 7: The dialog for opening a  $CO_2P_3S$  program.

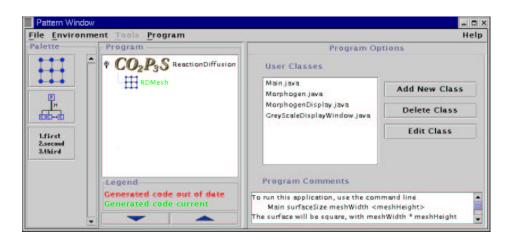


Figure 8: An open CO<sub>2</sub>P<sub>3</sub>S program.

Unfortunately, many other changes to a  $CO_2P_3S$  program take effect immediately and cannot be undone by simply not saving the program. You should save your program after making structural changes to it, or you will find that the program state and the state displayed in the user interface may not agree when the program is opened later.

For example, if you change a pattern template parameter and regenerate the framework code, you cannot undo the changes by not saving the program. The next time you load the program, the code will be that for the modified parameter value while the interface displays the old value. Similarly, application code is saved as you change it, and will persist regardless of whether or not you save your program.

### 4.4 Working With a CO<sub>2</sub>P<sub>3</sub>S Program

To make the presentation of this section more concrete, we have opened the reaction–diffusion example programs provided with your  $CO_2P_3S$  distribution. Initially it will appear as shown in Figure 8. This section describes each part of the user interface as well as the compilation and execution facilities.

#### 4.4.1 Pattern Palette

The first part of the interface we will examine is the Pattern Palette on the left of Figure 8. A closeup is shown in Figure 9(a).

The Pattern Palette allows you to select from the set of support design pattern templates, represented as buttons on the palette. In Figure 9(a), the templates (from top to bottom) are the Two–Dimensional Mesh, the Distributor, and the Phases. You can always get the name of the template by placing the cursor in the button and waiting for the tool tip.

Left-clicking on a button includes the pattern template into the current program. The pattern will appear in the Program Pane (Section 4.4.2) and in the Pattern Pane (Section 4.4.4). Right-clicking on a button brings up the background menu, shown in Figure 9(b). You can add the pattern to the program (Insert Pattern) or view the pattern template documentation (Pattern Help) using the HTML browser specified in your preferences.





(b) The background menu for the pattern templates.

(a) The Pattern Palette.

Figure 9: The Pattern Palette and background menu.

#### 4.4.2 Program Pane

The Program Pane is the middle section of Figure 8. An expanded picture is in Figure 10. This pane shows the set of pattern templates that are part of the current program.

The topmost item, with the  $CO_2P_3S$  logo followed by the program name, represents the entire program. Beneath it is a list of the pattern templates that are used in the current program. Each item in the list is a small graphical representation of the template followed by its name. The name of a pattern template is based on one of its parameter values, which allows you to distinguish between different instances of the same template. In our example, we are using an instance of the Mesh template with the name RDMesh.

The Program Pane also indicates the status of each pattern template using colours for the template name. The colours are:

**Red** This colour indicates that the framework code is out of date. This either means that you have not generated code for this template, or you have changed a pattern template parameter value and the generated code may not be consistent with the current parameters. You can generate code from the Pattern Pane (Section 4.4.4) or the Compile dialog (Section 4.4.5).

Green The framework code is consistent with the current parameter values.

The meaning of these colours is indicated by the legend that appears at the bottom of the Program Pane.

#### 4.4.3 **Program Options Pane**

When the topmost item in the Program Pane is selected, the Program Options Pane appears on the right side of the interface. This is the case in Figure 8, shown again in Figure 11.

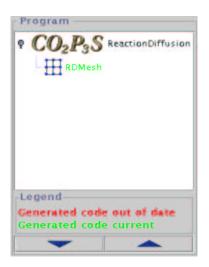


Figure 10: The Program Pane.

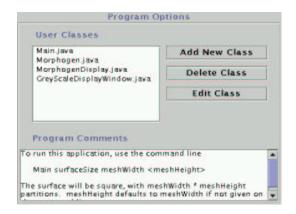


Figure 11: The Program Options Pane.

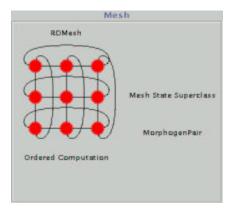


Figure 12: The Pattern Pane, showing an instance of the Mesh pattern template.

The Program Options Pane allows you to provide information for the entire program. This consists of two components: user classes and program comments.

User classes, the top part of the Program Options Pane, let you create additional classes for your application. In all  $CO_2P_3S$  programs, you will need to supply a mainline class, but other classes (perhaps from sequential versions of your program) can also be included. In addition to the mainline, the reaction-diffusion example uses three additional classes. You can add new classes using the Add New Class button, where you will be prompted for the name of the new class. This should be entered without the . java suffix. You can select a user class and delete it from the program. You can also select a class and edit it using the editor in your preferences.

The bottom part of the Program Options Pane provides space for program comments. In Figure 11, this space is used to provide information on the command line arguments for the program.

#### 4.4.4 Pattern Pane

If you select one of the pattern template instances in the Program Pane, the Program Options Pane is replaced by the Pattern Pane for the selected instance of a pattern template. The Pattern Pane on an instance of the Mesh is shown in Figure 12.

The Pattern Pane shows details on a specific instance of a pattern template, such as the current values of its parameters. This information is depicted using a combination of text and graphics. In Figure 12, we can see several class names (RDMesh and MorphogenPair) as well as other parameter values (a four-point mesh, a fully-toroidal topology, and an ordered computation).

The Pattern Pane is also used to work with the pattern template and generated framework code. The pane allows you to change parameter values to refine the template, generate code from a fully–specified template, and insert hook method bodies to complete the implementation of a program. Some aspects of this functionality are common to all pattern templates and are discussed here. Other aspects are necessarily specific to a particular pattern template and are covered in more detail in the template documentation.

The pattern template is refined using a background menu in the Pattern Pane, obtained by rightclicking anywhere in the pane. The menu for the Mesh pattern template is shown in Figure 13. The operations in this menu can be broken down into three categories: generic operations that apply to all pattern templates, pattern template class names, and pattern template parameters. The latter two

Generate First Code Layer Generate Next Code Layer View Pattern Template Delete Pattern	Generic Operations
Set Mesh Class Name Set Mesh State Class Set Mesh State Superclass	Pattern Template
Set Mesh Ordering Set Mesh Boundary Conditions Set Number of Neighbours	Pattern Template

Figure 13: The background menu in the Pattern Pane.

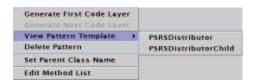


Figure 14: The background menu for the Pattern Pane with multiple viewable templates.

categories are specific to each pattern template and are discussed in the template documentation.

The first menu item in the generic operations, Generate First Layer Code, generates Patterns Layer code from the pattern template using the current template parameter values. If code is successfully generated, the label for the template in the Program Pane will turn green. The Generate Next Code Layer item is disabled since this release only supports the Patterns Layer. It will be enabled in the future when there is more support for the two lower layers in the  $CO_2P_3S$  programming model.

The last menu item in the generic operations, Delete Pattern, deletes the current pattern and associated files from your program. Note that this deletion takes place immediately and cannot be undone later.

The middle menu item is View Pattern Template. This item allows you to add hook method bodies to generated framework code, and so is only available when the generated framework code is up-to-date. Selecting this item brings up a Viewing Template window, shown in Figure 15, that allows you to view and edit hook method bodies for the current framework. If there are multiple classes in a framework that have hook methods, this item becomes a cascaded menu item (indicated by an arrow to the right) and you can select the class you wish to edit (Figure 14). Either a new viewer for the class will appear, or an existing viewer for the selected class will be brought to the foreground.

The Viewing Template window is a modified HTML viewer where the links represent places where you can add or edit code. The code in the viewer is generated with the framework code for a pattern template, and is run through a code beautifier before being displayed. If you select a link, a Code Editor dialog appears, shown in Figure 16.

The Code Editor dialog allows you to modify the code for particular method in the viewer. This editor is not the one in your preferences, but rather is a dialog that was created specifically to prevent errors involving hook method signatures. The combination of the Viewing Template and Code Editor dialogs do not allow you an opportunity to edit the signatures of the hook methods. Further, the code is generated for you, saving you from having to enter these signatures. This is

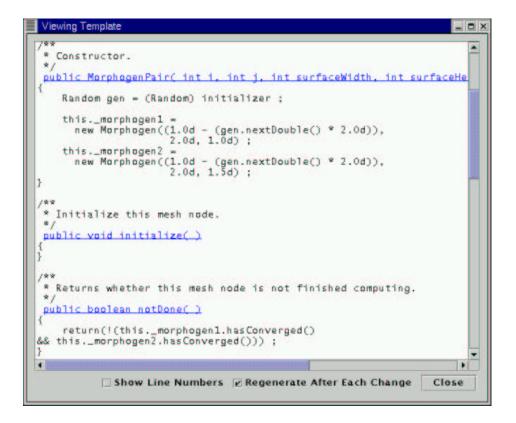


Figure 15: The Viewing Template for editing application code in the framework generated for a pattern template.

	phogen1.has orphogen2.h:	Converged() isConverged())) ;
}		

Figure 16: The Code Editor dialog.

important because the remaining framework code relies on the methods in the class in the viewer having specific signatures for the code to operate correctly. This tool support ensures that these signatures cannot be changed and prevents some potential compile and logic errors. As an example of the latter error, consider the first two arguments to the constructor at the top of the code in Figure 15. These two arguments represent the location in a two–dimensional data structure for the element being created. If you had to write this signature or were able to change it, you could accidently reverse the two parameters. This error cannot be caught by the compiler since the parameter types are correct, which is all the compiler checks. However, the framework code that uses this constructor is assuming the order in the figure. Reversing the parameters causes the data to be transposed, which may cause errors later.

In the Code Editor dialog, you can also restore the default implementation of a hook method by clicking the Restore Default button. This replaces the current value of the hook method with the default as generated with the framework code. An important note is that, because of a problem with the current implementation, the code editor does not display any code for those methods with the default implementation. The correct method body is still in the actual source code, but is not displayed in the code editor. However, if you click OK on a code editor with an empty body, you will overwrite the default with a blank body. This will cause compilation errors later. To preserve the default, either cancel the change or restore the default.

After restoring the default or accepting a new method body,  $CO_2P_3S$  will normally regenerate source code for the framework to incorporate this new code, and display the updated code in the viewer. This regeneration can incur an unwelcome time delay. You can disable this regeneration by unchecking the Regenerate After Each Change checkbox at the bottom of the Viewing Template. This speeds up the code editing process. Changes to method bodies are no longer reflected in the viewer. However, the changes are still visible in the code editors. If any methods are changed, the background of the viewer will turn grey and a label will appear at the bottom of the dialog, making it is clear that the displayed code is out-of-date. An out-of-date viewer can be refreshed by rechecking the Regenerate After Each Change. Closing an out-of-date viewer (by clicking the Close button) will force a code regeneration, so current code will appear if the template is brought up again later.

Checking the Show Line Numbers checkbox at the bottom of the Viewing Template window cause line numbers for the source code to appear on the left side of the viewer. This feature allows you to easily find compile errors in the code in this window.

Note that if you regenerate the framework code, using either the Generate First Layer Code menu item or the option in the Compile dialog (Section 4.4.5), all Viewing Template and associated Code Editor dialogs for that pattern template are closed. It is possible for you to change some of the class names in the generated code, which may mean that the class displayed in the viewer may no longer be part of your program. The best way to ensure that this window always displays a relevant class is to close it and have you open another viewer, which will always be on a class that is part of the current framework.

#### 4.4.5 Compile Dialog

Once you have entered all of your application code, you need to compile the code. This is done by selecting the Compile item from the Program menu, shown in Figure 17.

<u>P</u> rogram	
<u>C</u> ompile	Ctrl=C
<u>R</u> un	Ctr1-R

Figure 17: The Program menu.

Compile		_ <b>=</b> ×
Compilation Output:		
Compilation complete.		
Generate Debugging Information Optimize Show Deprecation Warnings Verbose Output Flags		
Compile Clean Regenerate All Layer One Source	Abort	Close

Figure 18: The Compile dialog.

The Compile dialog, shown in Figure 18, will appear. Selecting Compile will compile you program with the arguments supplied in the dialog. Clean will remove all of your .class files. Abort stops any currently executing compilation.

The Regenerate All Layer One Source button performs two functions. First, it removes all source files (except the user classes entered using the Program Options Pane (Section 4.4.3)), class files, and HTML files for the program. Second, it regenerates source code and HTML files for all patterns in the program using the current values of the pattern template parameters. The reason for this is that  $CO_2P_3S$  may keep source files that were generated based on old values of class names. We currently compile all source files in the src directory. However, these old files can interfere with compilation if the code they contain is out of date. This button lets you clean out these old source code files. It is also useful for quickly regenerating code for all of the pattern templates in a program rather than doing it template by template.

Arguments to the compiler can be specified in two ways. Common arguments, for including debugging information (-g on the command line), deprecation warnings, optimizations, and verbose output can be indicated with the check boxes. Additional arguments can be inserted into the Flags text field. The output of the compiler will appear in the text area at the top of the dialog.

The contents of this dialog are also saved when you save your program, so you won't have to enter this information each time.

#### 4.4.6 Run Dialog

To run your program, select Run from the Program menu (Figure 17). The Run dialog, shown in Figure 19, will appear.

The Run dialog is much like the Compile dialog. Common options are provided as check boxes or text areas. Other options can be entered into the Flags text area. The Run dialog has an additional text area for specifying the mainline class and command line parameters. The output of

urning: native threads are carting simulation at time mulation converged.	not supported in this release 1675
✓ Use Native Threads	Initial Heap Size (optional)
🗌 Verbose output	Maximum Heap Size (optional)
Flags	🛞 Shared Memory 🛛 Distributed Memor
Main Class and Command L	ine Parameters Main 64 2 2

Figure 19: The Run dialog.

the program is displayed in the text area.

The contents of this dialog are also saved when you save your program, so you won't have to enter this information each time. The Run dialog for Distributed  $CO_2P_3S$  slightly different than this one, it contains extra settings for the distributed-memory environment. This will be described in Section 5.

## 4.5 Example Programs Supplied with CO<sub>2</sub>P<sub>3</sub>S

This section briefly describes the example applications that are supplied with this distribution of  $CO_2P_3S$ : reaction–diffusion texture generation, parallel sorting by regular sampling, and matrix product chain. These programs can be found in the directory

```
COPSINSTALL/programs
```

More information on these two programs is provided in the docs subdirectory for the program.

#### 4.5.1 Reaction-diffusion Texture Generation

The reaction–diffusion texture generation problem is taken from computer graphics [4]. The program simulates two chemical, called *morphogens*, as they simultaneously react with one another and diffuse over a two–dimensional surface. This simulation repeatedly iterates over the surface, computing new values, until the values converge to their final solution. When the simulation is complete, one of the morphogens can be used to render a texture that resembles zebra stripes, as shown in Figure 20.

This texture is generated so that it can be tiled on a larger surface without any noticeable edges between tiles. This is accomplished by allowing the diffusion process to wrap around the edges, both horizontally and vertically, during the simulation.

This program uses the Mesh pattern template. This template parallelizes this computation by spatially decomposing the two-dimensional surface into distinct partitions. These partitions are then assigned to different processors for evaluation. However, the nature of a mesh computation is that each element (or pixel in the texture) requires data from adjacent elements. Thus, each partition needs data from adjacent partitions to compute new values for the elements on its boundary.

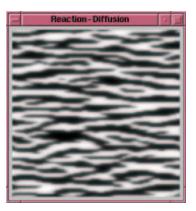


Figure 20: The output of the reaction-diffusion texture generation.

Further, for each iteration, the new values for the elements are computed using the values from the previous iteration, which requires barrier synchronization to ensure that no processor computes too far ahead.

The example program executes the simulation (based on a set of command line parameters that are explained in the Program Options Pane of the program). The initial, random conditions are displayed in a window. When complete, the final result is displayed. This window is the only output of the program. You can use image manipulation software to capture this image for later use.

To end the program, you will need to kill this window. Otherwise, the Run dialog will still believe the program is executing.

An interesting note on this program is the reuse of code from the sequential version. All of the classes in the Program Options Pane except the Main.java class were taken directly from a sequential implementation of this program. The hook method code is used as an Adapter pattern [1], essentially translating the interface in the generated framework code to the interface required by the reused code. In addition to reusing sequential code, this implementation strategy also keeps the hook method code simple.

### 4.5.2 Parallel Sorting by Regular Sampling

The second example program implements the Parallel Sorting by Regular Sampling (PSRS) algorithm [2]. This program sorts a specified number of uniformly distributed, random Integer objects and verifies the results. This is an explicitly parallel sorting algorithm that does not have a direct sequential counterpart. In addition, this program uses two instances of the Phases and Distributor pattern templates, providing an example of composing multiple frameworks into a complete application.

Composing frameworks in  $CO_2P_3S$  is simplified because each framework uses the Facade pattern [1] to provide a single, simple interface to the code. The constructor for this Facade creates all of the objects needed by the framework and assembles them into a complete program, simplifying the instantiation process. The Facade also provides a simple interface for launching the computation for the framework where applicable (seen in the Phases and Mesh frameworks).

### 4.5.3 Matrix Product Chain

The final example is matrix chain product, one of the Cowichan problems [3]. This program uses a dynamic programming matrix to find the least expensive way to multiply a set of matrices. The program uses a single instance of the Wavefront pattern template, computing the upper half of a matrix starting from the diagonal and working to the top right corner.

## 4.6 Disabled Interface Options

This version of  $CO_2P_3S$  does not have all options enabled. To minimize the number of changes for future versions of  $CO_2P_3S$ , most of these options are permanently grayed out in this distribution. These options are:

- The Create or Edit Pattern menu item in the Environment menu. This is provided for modifying and create pattern templates (Section 6).
- The Tools menu item on the user interface is disabled. These tools are for managing machines and resources in the forthcoming distributed memory version of  $CO_2P_3S$  (Section 5).
- The Shared Memory and Distributed Memory radio buttons in the Run dialog. Shared memory is always selected.
- The Generate Next Code Layer in the background menu in the Pattern Pane. This release of  $CO_2P_3S$  only supports the Pattern Layer, so this menu item is disabled.

## 4.7 Caveats

There are a number of issues with the  $CO_2P_3S$  user interface. These problems, and potential workarounds where possible, are:

- 1. When editing hook methods in the Viewing Template window, the code for the complete framework is regenerated after each method body is accepted. The time for this generation may be longer than you wish to wait. To prevent this regeneration, uncheck the Regener-ate After Each Change checkbox. The window will let you know if the code in the window is out of date. Note, though, that the most recent code will be displayed in the Code Editor dialog. It simply won't be shown in the viewer itself. If you recheck this checkbox or close the viewer with out-of-date code, the framework will be regenerated.
- 2. When you regenerate the complete framework, using either the Generate First Code Layer menu item in the Pattern Pane or the Regenerate All Layer One Source button on the Compile dialog (but not if you've changed a hook method body), all template viewers and code editors are closed. We cannot check to see if the class in the viewer is still relevant in the application, or if the correct code is being displayed. Closing the viewers and reopening them from the Pattern Pane menu ensures that the viewers always display the most recent version of a class, and that the class is still relevant to the application.

3. Using X11, the graphical user interface may not correctly display over a remote X connection. You will need to run  $CO_2P_3S$  on the local machine. As far as we can tell, this is a problem in the Swing library used for the interface.

This means that you will not be able to use the Run dialog to execute your  $CO_2P_3S$  program. Instead, you can run the program manually. In the classes directory for your program (Section 4.1) are the class files for your program. You can start the virtual machine using these files, or copy them to other machines as necessary.

- 4. Using X11, some window managers do not correctly display the user interface, even on the local machine. Once again, this appears to be a problem with Swing. In particular, we have experienced serious problems with the FVWM2 window manager, including the following:
  - The region around the edge of dialog boxes does not render properly, instead appearing as a blank grey region. This may obscure the buttons in the dialog. The buttons are still present and can be clicked, but you will not be able to see what you're clicking. Usually, resizing the dialog will correct this. Another option is to iconify and expand the window, but again this doesn't always work.
  - The size of a dialog window may change each time it is brought up. The dialog may grow slightly each time until it takes up the entire screen. It may shrink slightly until it is too small for all of its components.

The problems with FVWM2 are apparently known bugs, but fixes do not appear to be forthcoming. The screenshots for this document were all taken using the Enlightenment window manager running under the Gnome desktop on a Linux workstation. We have not experienced any problems with this environment. We cannot vouch for other desktop and window manager combinations.

- 5. The file list dialog hangs when working on directories with a large number of files. This is why we recommend that you set the userProgramDirectory attribute (Section 2.4.1), either by modifying the .copsrc.xml file manually or through the Edit Preferences menu item in the user interface.
- 6. There are a number of exceptions that are thrown by Swing components. Most of the time, these can be safely ignored. Unfortunately, this can make it hard to find the exceptions that are important.
- 7. Saving a CO<sub>2</sub>P<sub>3</sub>S program saves the configuration information for an individual program. However, changes within the program are performed immediately, regardless of whether you save the configuration or not. For example, deleting classes or changing hook method bodies take effect immediately and cannot be undone by not saving the program. This also means that it is possible for the configuration and program code to be out of step with one another. We should perhaps follow the emacs approach of creating a working copy and replacing the original when you save the program, but this has not been done.
- 8.  $CO_2P_3S$  requires an open network connection to start. The reason for this is that the format of the .copsrc.xml file is verified using a DTD (Document Type Definition) file that is

accessed through the World Wide Web. Line 5 of Figure 1 shows the URL of this file. If you will be using  $CO_2P_3S$  on a computer without a network connection, you should change this URL to point to the copy of the DTD file included in the  $CO_2P_3S$  distribution. Change the URL to the following:

file:COPSINSTALL/DTD/CopsCfg.dtd

where COPSINSTALL is the directory of your  $CO_2P_3S$  installation (the value of the copsInstallationDirectory configuration property from Section 2.4.1).

- 9. When editing code using the Viewing Template, the code for methods that still have their default bodies will not appear in the Code Editor. The proper code is still in the application classes, but simply doesn't appear in the Code Editor dialog. However, you must take care not to accept an empty window by clicking OK. This overwrites the default with an empty method body, which will result in compile errors. Either cancel the change or restore the default implementation.
- 10. There are a number of cases when the displayed HTML and the actual code do not match. The most common example is with the < and > operators. These are not displayed correctly since they are part of HTML tags. The HTML generator does not convert these for proper display. In other cases, we have seen extra newlines inserted into code. These problems only affect the HTML and not the underlying code. The code as it appears in the Code Editor dialog is properly inserted into the source.
- 11. If no constructors are explicitly added to a class, the code generator will always insert an explicit default constructor that is not editable by the user. This can be a problem for pattern designers, as it means that the user cannot augment the default constructor. (Trying to add the default constructor in user–added code will result in a compile error.) The workaround is to explicitly add the default constructor as part of the generated framework code and make it editable. Another option, which is best for constructors that pass arguments to a parent constructor, is to create a constructor that cannot be edited and that calls an initialize method that the user can implement.

## **5** Distributed CO<sub>2</sub>P<sub>3</sub>S

The current release of  $CO_2P_3S$  includes a  $DCO_2P_3S$  environment which supports distributed parallel programming.  $DCO_2P_3S$  is a distributed-memory runtime environment including a flexible architecture (built by Jini technology), a distributed-synchronization package, a communication mechanism, a performance monitor and a distributed process controller. All these components offer runtime support for distributed-parallel applications. Moreover, a set of new distributedmemroy parallel design pattern templates (DM\_Mesh, DM\_Distributor, DM\_Wavefront) are also created. These design pattern templates facilitate the design of distributed applications which can be executed under the  $DCO_2P_3S$  environment.

### 5.1 Working with the $DCO_2P_3S$ environment

This section will introduce the  $DCO_2P_3S$  environment. At the end of this section there will be checklists about using different functionalities of the environment. The DCO<sub>2</sub>P<sub>3</sub>S Tools menu in Figure 21 shows three options—Distributed Environment, Jini Start Up and Jini Shut Down—that control the DCO<sub>2</sub>P<sub>3</sub>S environment. The second option launches all Jini infrastructure components on one or more machines. As  $DCO_2P_3S$  is implemented as a Jini distributed system, all these Jini infrastructure components are necessary to help different components in DCO<sub>2</sub>P<sub>3</sub>S to interact and coordinate with each other [6]. The third option destroys all Jini components in order to shut down the  $DCO_2P_3S$  environment. The first option, launches a configuration window, as shown in Figure 22. The left list box in the window includes all machines that comprise the system. By clicking the Add, Delete and Delete All buttons, the user can add or remove the machines in the system. The Launch button triggers all listed machines to launch a series of daemon processes, which will be manipulated by the central control to provide execution support for distributed programs. The right list box in the window allows the user to choose one or more machines from the left as participants for a specific distributed-parallel application. This approach gives the user an option to apply static load balancing to the application. By monitoring the real-time performance of all machines in the environment (described later in Section 5.2), the user can choose the most idle ones to use.

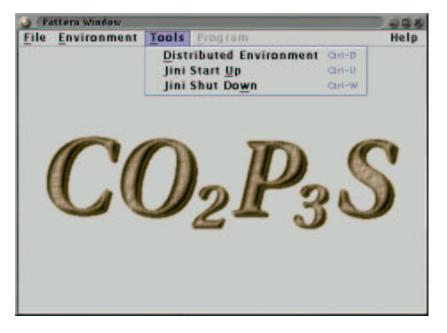


Figure 21: Menu options to start up the environment

After the environment is launched, all the underlying details about the distributed parallelism can be ignored by the programmer, who can use  $DCO_2P_3S$  the same as  $CO_2P_3S$ . Please refer to previous sections for descriptions on how to use distributed pattern templates.

In  $DCO_2P_3S$ , a generated application consists of a main program and a series of distributed slave processes. The main program is executed on a central control machine where all GUI stuff resides. Each process is implemented as a Jini service running on a ditributed machine in the environment.

Add Delete Launch St Close
Remove all
Add Delete Launch St., Close
Add Delete Launch St., Close
Delete all

Figure 22: The window to configure the  $DCO_2P_3S$  environment

### 5.2 The Performance Monitor and the Process Manager

In a distributed system, having central control over distributed processes and remote machines helps the user easily monitor and dynamically configure the system. We provided such a function in  $DCO_2P_3S$ .

#### 5.2.1 The performance monitor

A graphical display of the runtime information of distributed machines helps  $DCO_2$ -  $P_3S$  users monitor the environment to make full use of idle machines and avoid highly loaded ones. Dynamic load balancing is not supported in current version of  $DCO_2P_3S$  as this requires extensive modifications to the Java virtual machine. Rather, by the use of visual information, for most applications the user can easily improve performance using static load balancing.

The  $CO_2P_3S$  environment has to be launched before any system information can be viewed. As described in 5.1, the Jini infrastructure has to be started first; then certain machines have to be added to the environment; finally one daemon on each machine will be activated (by clicking the Launch buttern in 21). These daemons show the runtime performance information of the environment.

The "system information" menu item of Figure 23 is used to launch graphical displays <sup>1</sup> (Figure 24 and 25).

<sup>&</sup>lt;sup>1</sup>The graphical display stems from a memory monitor in a Java 2D demo canned in the JDK1.2.2 distribution.

9				
<u>\dd</u>	Ctrl-A			
Delete	Ctrl-D	1		
ystem in	fo Orl-s	1000	Insert	
Quit	QrI-Q			
brul	e-h e-d		Insert all	
			Remove	
			Remove all	
	dd	Delete	Launch St Close	
_	Delete		Launch St Close	

Figure 23: The Menu of the  $DCO_2P_3S$  configuration dialogue



Figure 24: The CPU usage of the machines in the environment

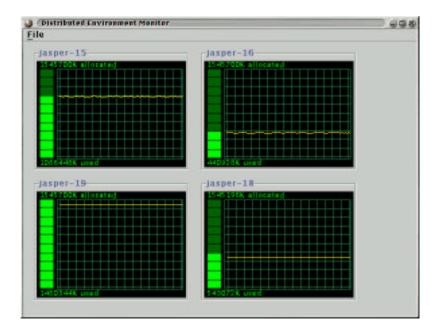


Figure 25: The memory usage of the machines in the environment

#### 5.2.2 The Process Manager

A daemon running at each participating machine is responsible for remote process management. The process manager also helps deliver remote display. Remote display is always a difficult problem in distributed systems because of a lack of low-level control over distributed processes. In our approach, each process manager gathers the output of all local processes and sends the output to the central manager.

Figure 26 shows the run dialog used to execute generated applications. The user must clarify whether an application is intended for a shared-memory environment or a distributed-memory environment. By clicking the radio box labeled "Distributed Memory", the  $DCO_2P_3S$  environment is chosen as the runtime. The user can also specify the maximum and minimum heap size of JVMs that will be launched on the central control and distributed machines. In the text field labeled "Main class and command line parameters", the user specifies the Java class that launches the instantiated framework and provides necessary command line parameters. After all necessary information has been specified, the user can click the Execute button to run the application. Application output, including the results from distributed machines, is displayed in the large text box at the center of the window.

### 5.3 Checklists

- 1. Launch the Jini environment
  - (a) Go to Environment→Preferences, set the Jini lookup Service Address to be the IP address of one machine on your LAN (Figure 5)

ecution Output:				
Use Native Threads	Initial Heap Size (optional)	Min Heap Size (Distribu	ted Process)	
🗌 Verbose output	Maximum Heap Size (optional)	Max Heap Size (Distribu	ited Process)	
Flags	⊖ Share	ed Memory 💿 Distribute	ad Memory	
Hain Class and Commany	Line Barameters			
Main Class and Command	Line Parameters			

Figure 26: The run dialog of DCO<sub>2</sub>P<sub>3</sub>S

- (b) Go to Tools→Start Jini, which launches the Jini infrastructure components at above address
- 2. Launch the  $DCO_2P_3S$  environment
  - (a) Start up the Jini environment first, refer to the first checklist
  - (b) Go to Tools→Distributed Environment, launch the Distributed environment configuration window (Figure 22)
  - (c) Add machines you want to include in the environment in the left list box
  - (d) click "Launch" botton to load the daemon class into each machine you add in the previous step
- 3. Launch the Performance Monitor
  - (a) Launch the  $DCO_2P_3S$  environment first, refer to above checklist
  - (b) Go to File→System Information in the Distributed environment configuration window (Figure 22)
  - (c) Choose the menu items under the File menu in the Performance Monito window (Figure 24) to see CPU or memory usage of each distributed machine
- 4. Execute a  $DCO_2P_3S$  application
  - (a) Launch the  $DCO_2P_3S$  environment first, refer to the second checklist

- (b) Open up a generated distributed application, the steps to generate a distributed application are the same as those taken to generate a shared memory or a sequential application. Refer to section 4.4 for more information on creating a CO<sub>2</sub>P<sub>3</sub>S application.
- (c) Go to the Distributed environment configuration window (Figure 22), choose several machines from the left list box and add them into the right list box.
- (d) Go to the Program Menu under the Main Gui (Figure 17), choose Compile to compile your program. Choose Run to launch the Run dialog (Figure 26).
- (e) In the run dialog, choose the execution environment to be distributed environment
- (f) change the Heap sizes of distributed processes if necessary
- (g) Fill in the Main Class and Command Line Parameters. Please note that for sharedmemory and distributed-memory applications, one of the command line parameters must indicate the number of threads/processes to be used in the application. For distributed applications, the number of processes you specify in the command line option must equal the number of machines you add in the right list box (Figure 22) in step 3.
- (h) Click Execute to run the application
- 5. Shutdown the  $DCO_2P_3S$  environment
  - (a) Shut down all daemons in the DCO<sub>2</sub>P<sub>3</sub>S environment coniguration window (Figure 22) first
  - (b) Go the Tools-Jini Shutdown (Figure 21) to destroy Jini components

### 5.4 Things to notice when using distributed pattern templates

• Static variable initializations When using a distributed pattern template to create one distributed application, special efforts should be put on static variable initializations. A regular approach in shared-memory applications to initialize static variables is to put initialization code in the Main program. For example, in the Main program of the shared-memory Reaction-diffussion application, the following code is used to create two instances of class SpecificMorphogenConstants.

These two SpecificMorphogenConstants instances will be set to two static variales in class MorphogenPairState, which is a user-template class. The MorphogenPairState

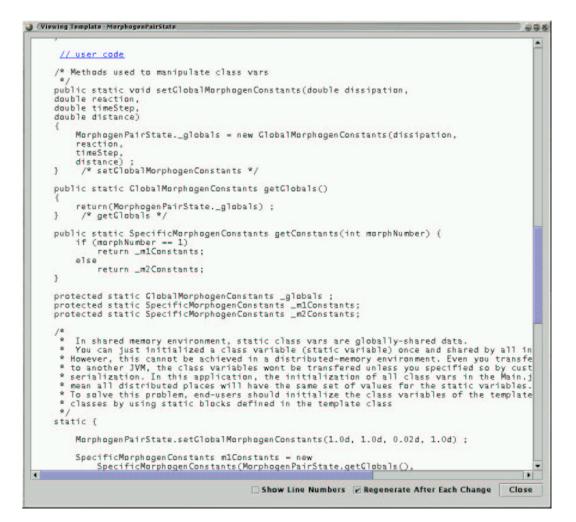


Figure 27: The code template of the Distributed Reaction-Diffusion Application

class models the node class of the two-dimensional mesh surface in the reaction-diffusion application. These two static variables are shared among all MorphogenPairState instaces to process the new states of all mesh nodes. This approach is not valid in distributedapplications. Therefore, the user should add the static variable initialization code in the user template as well as the Main program. Open up the NewDMesh application under \$COPS\_HOME/programs/DistMemApps/ to view its code template for more information. 27

- Manually launch and shutting down Jini infrastructure components There are two scripts launchScript and shutDnScript–under the \$COPS\_HOME/binUtil/jini\_startup. These two scripts help launch and shutdown Jini system components. The syntax of launchScript is "./launchScript ipaddress", the ipaddress represents the IP address of the machine you wish all Jini system components to run on. TO shut down these components manually, rsh the machine and run shutdnScript.
- **Runnaway processes** There is always a runnaway Jini process after shutting down all Jini system components. Rsh into the machine that Jini system components were running to kill that runnaway process.
- The Performance Monitor The Performance Monitor is implemented with JNI and LibGTop a C++ library for getting system runtime information. The Performance monitor is tested on Red Hat Linux 7.1 2.96-98. It may not work properly on other platforms. If there is any problem launching the DCO<sub>2</sub>P<sub>3</sub>S environment, please contact us.
- Problem with execution output for distributed applications Currently, DCO<sub>2</sub>P<sub>3</sub>S only supports a first-time display of the execution output for a distributed applications. A first-time display means the output from the distributed processes can only be collected for the first time after the DCO<sub>2</sub>P<sub>3</sub>S environment has been launched. Following executions will only have the output from the main program which runs from the main GUI. To have all output, the user has to shut down all DCO<sub>2</sub>P<sub>3</sub>S daemons and restart them. This problem will be solved in future releases.

## **6** MetaCO<sub>2</sub>P<sub>3</sub>S introduction

Although design patterns try to be generic to cover as many situations as possible, they are still not comprehensive enough to handle some requirements and ramifications which may appear in future applications. The limited capacity and extensibility of pattern libraries is one of the major reasons that pattern-based programming systems have not gained greater acceptance.

 $CO_2P_3S$  has addressed this problem by introducing a new tool—Meta $CO_2P_3S$ . Using Meta $CO_2P_3S$ , a pattern designer can identify and generate a new design pattern and add it into the  $CO_2P_3S$  pattern library.

 $MetaCO_2P_3S$  provides a means of constructing design pattern templates in a structured way. Each generative design pattern constructed using  $MetaCO_2P_3S$  contains two parts: the GUI part and the pattern template part. The GUI part allows the user to specify pattern parameters through a graphical user interface. The pattern template part contains all template code.

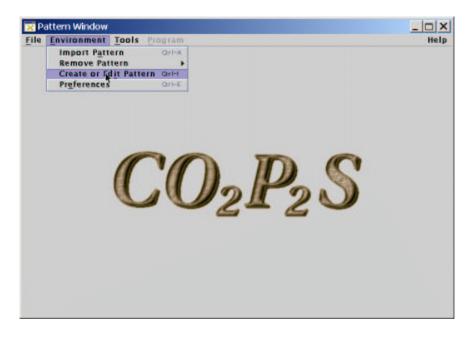


Figure 28: The pattern editor

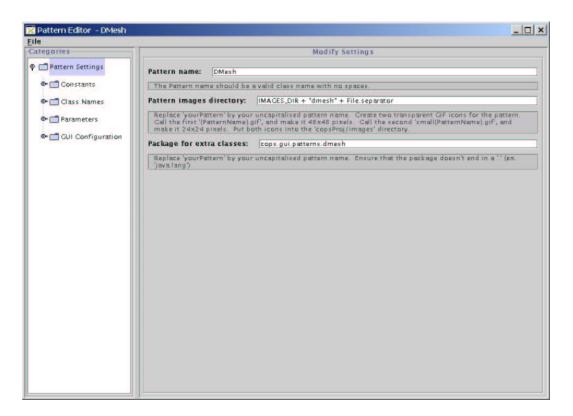


Figure 29: The MetaCO<sub>2</sub>P<sub>3</sub>S GUI

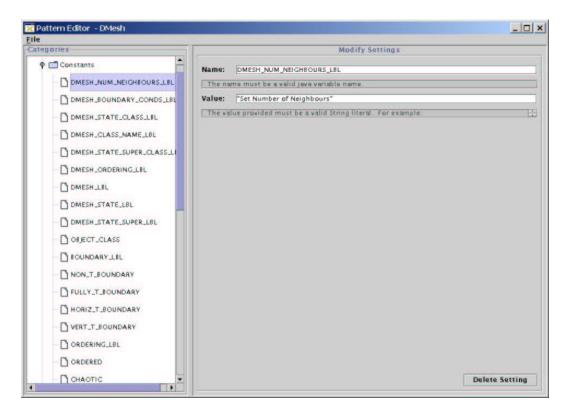


Figure 30: The constants of the DM\_Mesh pattern in  $MetaCO_2P_3S$ 

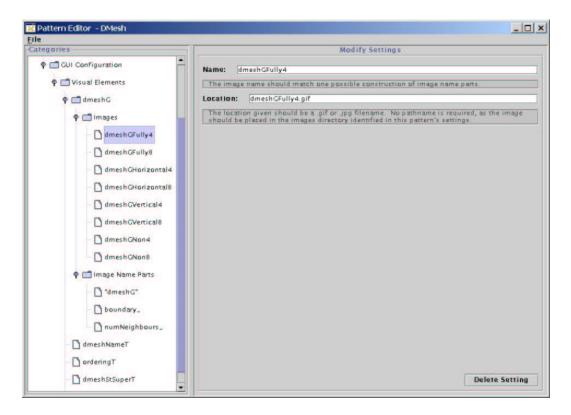


Figure 31: The GUI configuration of the DM\_Mesh pattern in  $MetaCO_2P_3S$ 

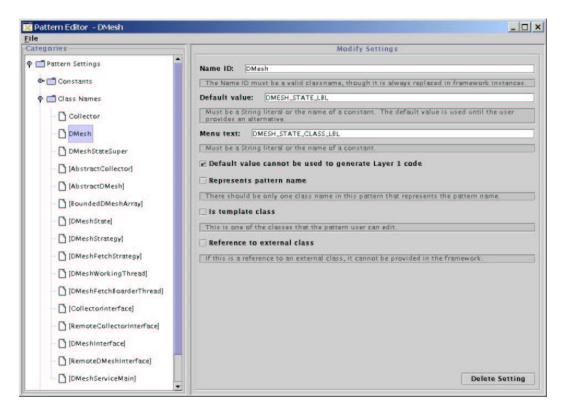


Figure 32: The structure of the DM\_Mesh pattern in MetaCO<sub>2</sub>P<sub>3</sub>S

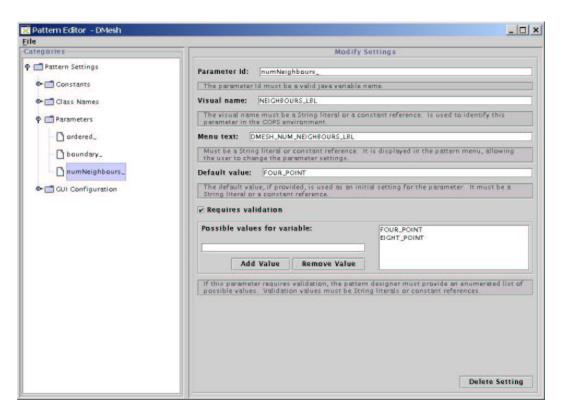


Figure 33: Pattern parameters in MetaCO<sub>2</sub>P<sub>3</sub>S

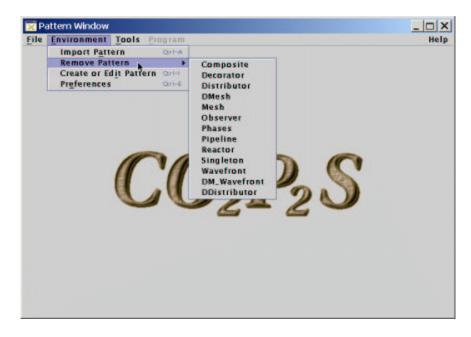


Figure 34: Importing and removing patterns

The menu item in figure 28 activates the pattern template editor. The pattern editor is opened with an empty template. The first step to create an empty template is to specify its name and other two properties. After specifying these three properties, a pattern designer can continue to create other components of the new pattern.

Figure 29 shows a graphical display of the DM\_Mesh template in Meta $CO_2P_3S$ . The left pane of this figure displays all required components in the template, including constants, classes, parameters and GUI configurations.

The constants and GUI configurations define the GUI part of the pattern template. The constants in Figure 30 describes the text labels that will be displayed on the template GUI as in Figure 12 and 13. The GUI configuration (Figure 31) sets up the graphical display, such as the picture which shows the pattern's object structure and the position of the constant labels in the window of the pattern template that will be used by a programmer. A good practice of using the pattern editor is to open an existing pattern template and modify it to create another new pattern.

The class names and parameters are the core of each template since they implement a design pattern using a code template.

The classes consists of all necessary components that contribute to the implementation of a design pattern. Different classes have different attributes, reflecting whether a class contributes to the private parallel structure or offers hook methods for the programmer to input application-specific details. The class named DM\_Mesh in Figure 32 describes the collector class in the DM\_Mesh pattern; the collector class is a framework class that encapsulates the structure information and cannot be accessed by the user.

An important step in creating a design pattern template is to generalize and quantify the descriptive properties of an ordinary design pattern to formal parameters with domain restrictions. Each pattern parameter has a direct effect on the code that is generated by a pattern template. After identifying all possible parameters, the pattern designer provides code fragments for each legal combination of parameters. A design pattern thus becomes a template for a group of frameworks. For example, Figure 33 lists a parameter of the DM\_Mesh pattern called "\_neighbors", which specifies how many neighbour nodes (4 or 8) are needed to compute the mesh node.

All design patterns created in Meta $CO_2P_3S$  are stored as XML and Java files, which are easy to store and share with other systems. Generated pattern templates can be easily imported into a  $CO_2P_3S$  distribution (Figure 34. Patterns can also be removed by choosing the "Remove Pattern" menu item.

MetaCO<sub>2</sub>P<sub>3</sub>S was a key tool in constructing DCO<sub>2</sub>P<sub>3</sub>S to support the generation of parallel design patterns for a distributed-memory environment. It allowed us to focus on designing efficient parallel structures, communication and synchronization mechanisms for new distributed-memory version of patterns.

## 7 Support for Sequential Design Patterns

 $CO_2P_3S$  was originally envisioned as a pattern–based parallel programming system. It has become clear that these same ideas and programming model are equally applicable to creating programs with sequential design patterns. By using Meta $CO_2P_3S$ , we successfully added four sequential patterns (Composite, Decorator, Observer and Singleton) into our pattern template repository. De-

tailed introductions of these patterns can be found in [1]. Sample applications using these patterns are also included in the distribution.

- Breakout: Uses 5 patters: Composite, Observer, Decorator, Singleton and Abstract Factory.
- CompositeParser: builds a parse tree as a composite for simple arithmetic expressions. The parsing and building of the tree was all done manually, but uses COPS generated code for three types of traversals: Unparsing the tree (prints out the original expression fully parenthesized). Printing the parse tree (each level in the tree is indented more). Evaluating the parse tree.
- ListObserver: replaces the ListData event model from Java's api with an instance of a COPS generated Observer pattern. It's a pretty complicated example because I had to take the source code of several classes from the api and make small changes to it.
- PowerPlant: another Observer pattern. It's just a toy application, but it's easier to see the pattern at work in this program than in the previous one.
- Monitor: replaces System.out with an instance of a COPS generated Sigleton pattern.
- PrefixParser: uses an abstract factory to generate parse nodes in a parser that evaluates arithmetic expressions in prefix notation.
- TableDecorator: decorates a TableModel to sort the elements in the selected column.

# 8 Feedback

We would appreciate any feedback that you have on the  $CO_2P_3S$  parallel programming system, or reports of any bugs that you find. Please send e-mail to systems@cs.ualberta.ca.

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