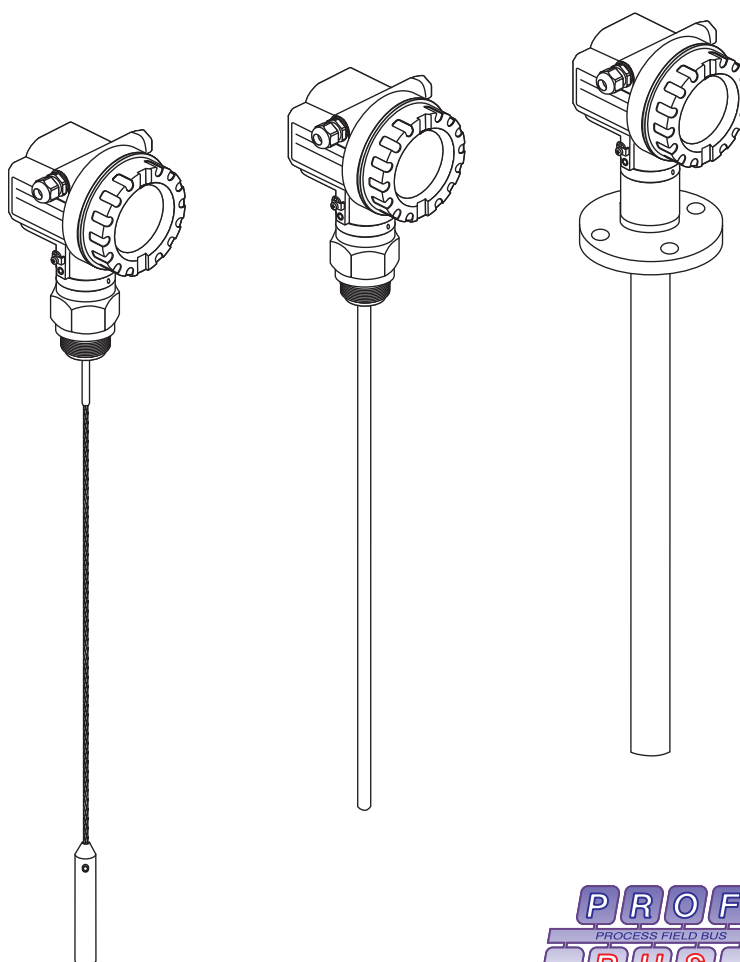
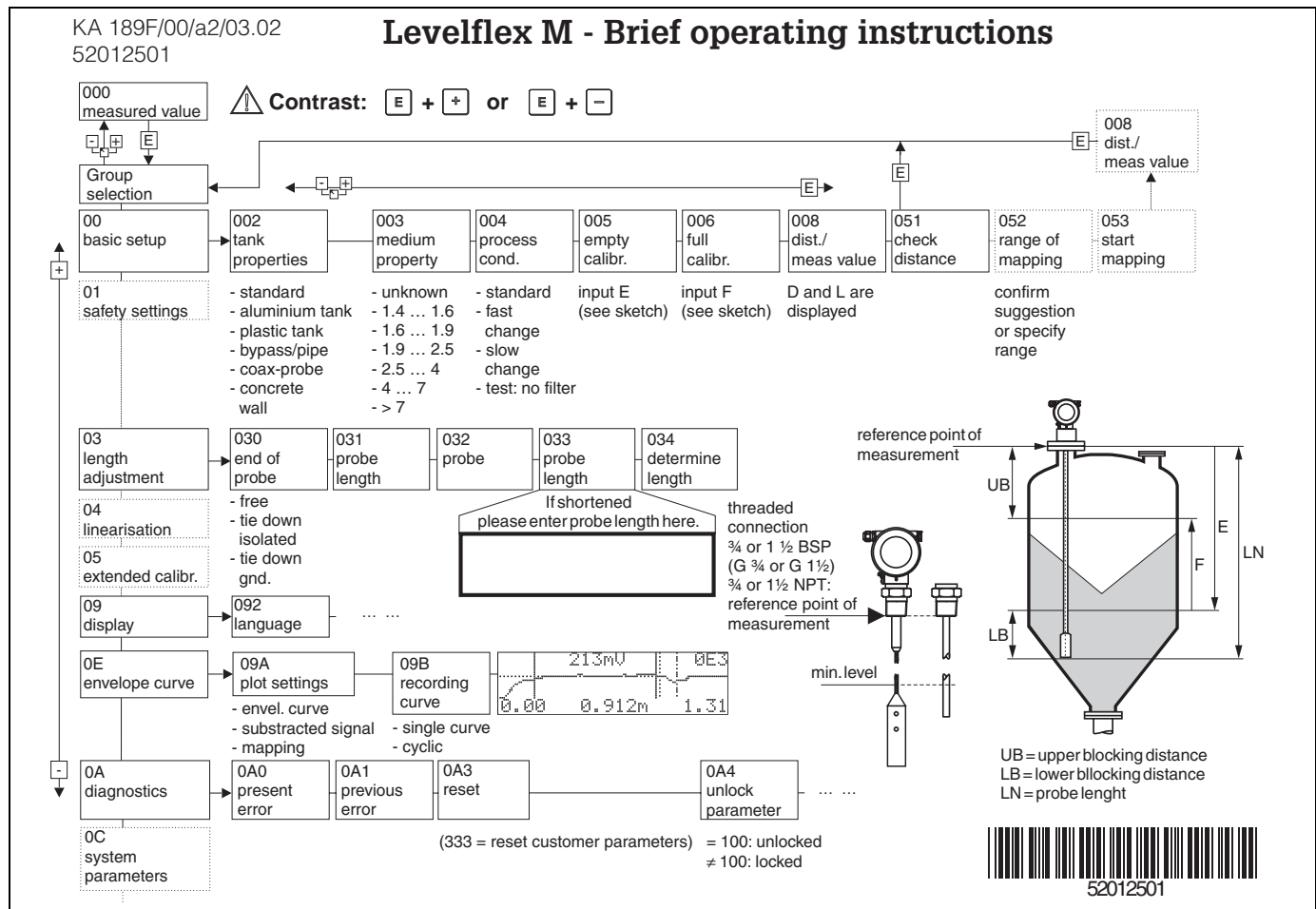


levelflex M FMP 40 with PROFIBUS-PA Guided Level-Radar

Operating Instructions



Brief operating instructions



Note!

This operating manual explains the installation and initial start-up for the level transmitter measuring device. All functions that are required for a typical measuring task are taken into account here.

In addition, the Levelflex M provides many other functions that are not included in this operating manual, such as optimising the measuring point and converting the measured values.

An **overview of all device functions** can be found on page 94.

The operating manual BA 245F/00/en provides an **extensive description of all device functions** – Description of the device functions for Levelflex M, which can also be found on the enclosed CD-ROM.

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1 Safety instructions

1.1 Designated use

The Levelflex M FMP 40 is a compact level transmitter for the continuous measurement of solids and liquids, measuring principle: Guided Level Radar / TDR: **T**ime **D**omain **R**eflectometry).

1.2 Installation, commissioning and operation

The Levelflex M has been designed to operate safely in accordance with current technical, safety and EU standards. If installed incorrectly or used for applications for which it is not intended, however, it is possible that application-related dangers may arise, e.g. product overflow due to incorrect installation or calibration. For this reason, the instrument must be installed, connected, operated and maintained according to the instructions in this manual: personnel must be authorised and suitably qualified. The manual must have been read and understood, and the instructions followed. Modifications and repairs to the device are permissible only when they are expressly approved in the manual.

1.3 Operational safety

Hazardous areas




Measuring systems for use in hazardous environments are accompanied by separate "Ex documentation", which is an *integral part* of this Operating Manual. Strict compliance with the installation instructions and ratings as stated in this supplementary documentation is mandatory.

- Ensure that all personnel are suitably qualified.
- Observe the specifications in the certificate as well as national and local regulations.




1.4 Notes on safety conventions and symbols

In order to highlight safety-relevant or alternative operating procedures in the manual, the following conventions have been used, each indicated by a corresponding symbol in the margin.






Safety conventions

Symbol	Meaning
	Warning! A warning highlights actions or procedures which, if not performed correctly, will lead to personal injury, a safety hazard or destruction of the instrument
	Caution! Caution highlights actions or procedures which, if not performed correctly, may lead to personal injury or incorrect functioning of the instrument
	Note! A note highlights actions or procedures which, if not performed correctly, may indirectly affect operation or may lead to an instrument response which is not planned

Explosion protection

	Device certified for use in explosion hazardous area If the Levelflex has this symbol embossed on its name plate it can be installed in an explosion hazardous area
	Explosion hazardous area Symbol used in drawings to indicate explosion hazardous areas. – Devices located in and wiring entering areas with the designation "explosion hazardous areas" must conform with the stated type of protection
	Safe area (non-explosion hazardous area) Symbol used in drawings to indicate, if necessary, non-explosion hazardous areas. – Devices located in safe areas still require a certificate if their outputs run into explosion hazardous areas.

Electrical symbols

	Direct voltage A terminal to which or from which a direct current or voltage may be applied or supplied
	Alternating voltage A terminal to which or from which an alternating (sine-wave) current or voltage may be applied or supplied
	Grounded terminal A grounded terminal, which as far as the operator is concerned, is already grounded by means of an earth grounding system
	Protective grounding (earth) terminal A terminal which must be connected to earth ground prior to making any other connection to the equipment
	Equipotential connection (earth bonding) A connection made to the plant grounding system which may be of type e.g. neutral star or equipotential line according to national or company practice

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Please enter probe length in mm or inch / 0.1 inch

 mm

probe length LN see page 12

2.2 Scope of delivery



Caution!

It is essential to follow the instructions concerning the unpacking, transport and storage of measuring instruments given in the chapter »Incoming acceptance, transport, storage« on page 11.

The scope of delivery consists of:

- Assembled instrument
- 2 ToF Tool CD-ROMs
 - CD 1: ToF Tool Program
 - CD 2: Device descriptions (device drivers) and documentation for all Endress+Hauser devices which are operable using ToF Tool
- Accessories (s. Chapter 8)

Accompanying documentation:

- Short manual (basic equalisation/troubleshooting): housed in the instrument
- Operating manual (this manual)
- Operating manual: Description of the instrument functions
- Approval documentation: if this is not included in the operating manual.

2.3 Certificates and approvals

CE mark, declaration of conformity

The instrument is designed to meet state-of-the-art safety requirements, has been tested and left the factory in a condition in which it is safe to operate. The instrument complies with the applicable standards and regulations in accordance with EN 61010 "Protection Measures for Electrical Equipment for Measurement, Control, Regulation and Laboratory Procedures". The instrument described in this manual thus complies with the statutory requirements of the EG directives. Endress+Hauser confirms the successful testing of the instrument by affixing to it the CE mark.

2.4 Registered trademarks

KALREZ[®], VITON[®], TEFLON[®]

Registered trademark of the company E.I. Du Pont de Nemours & Co., Wilmington, USA

TRI-CLAMP[®]

Registered trademark of the company Ladish & Co., Inc., Kenosha, USA

HART[®]

Registered trademark of HART Communication Foundation, Austin, USA

ToF[®]

Registered trademark of the company Endress+Hauser GmbH+Co. KG, Maulburg, Germany

PulseMaster[®]

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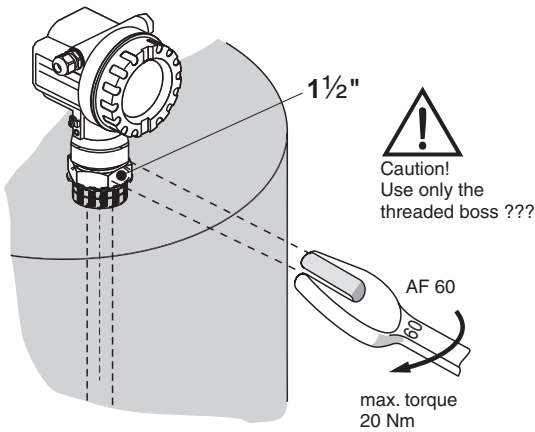
PROFIBUS[®]

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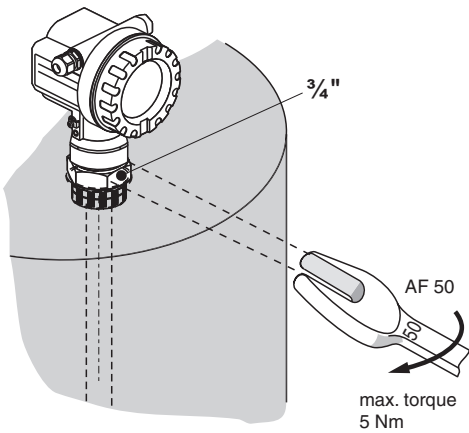
3 Mounting

3.1 Quick installation guide

F12 or T12 housing



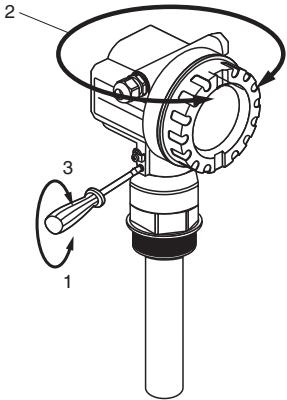
F12 or T12 housing



Turn housing

The housing can be turned 350° in order to simplify access to the display and the terminal compartment

F12 housing



3.2 Incoming acceptance, transport, storage

3.2.1 Incoming acceptance

Check the packing and contents for any signs of damage.

Check the shipment, make sure nothing is missing and that the scope of supply matches your order.

3.2.2 Transport



Caution!

Follow the safety instructions and transport conditions for instruments of more than 18 kg. Do not lift the measuring instrument by its probe rod in order to transport it.

3.2.3 Storage

Pack the measuring instrument so that is protected against impacts for storage and transport. The original packing material provides the optimum protection for this. The permissible storage temperature is -40 °C...+80 °C.

3.3 Installation Conditions

3.3.1 Dimensions

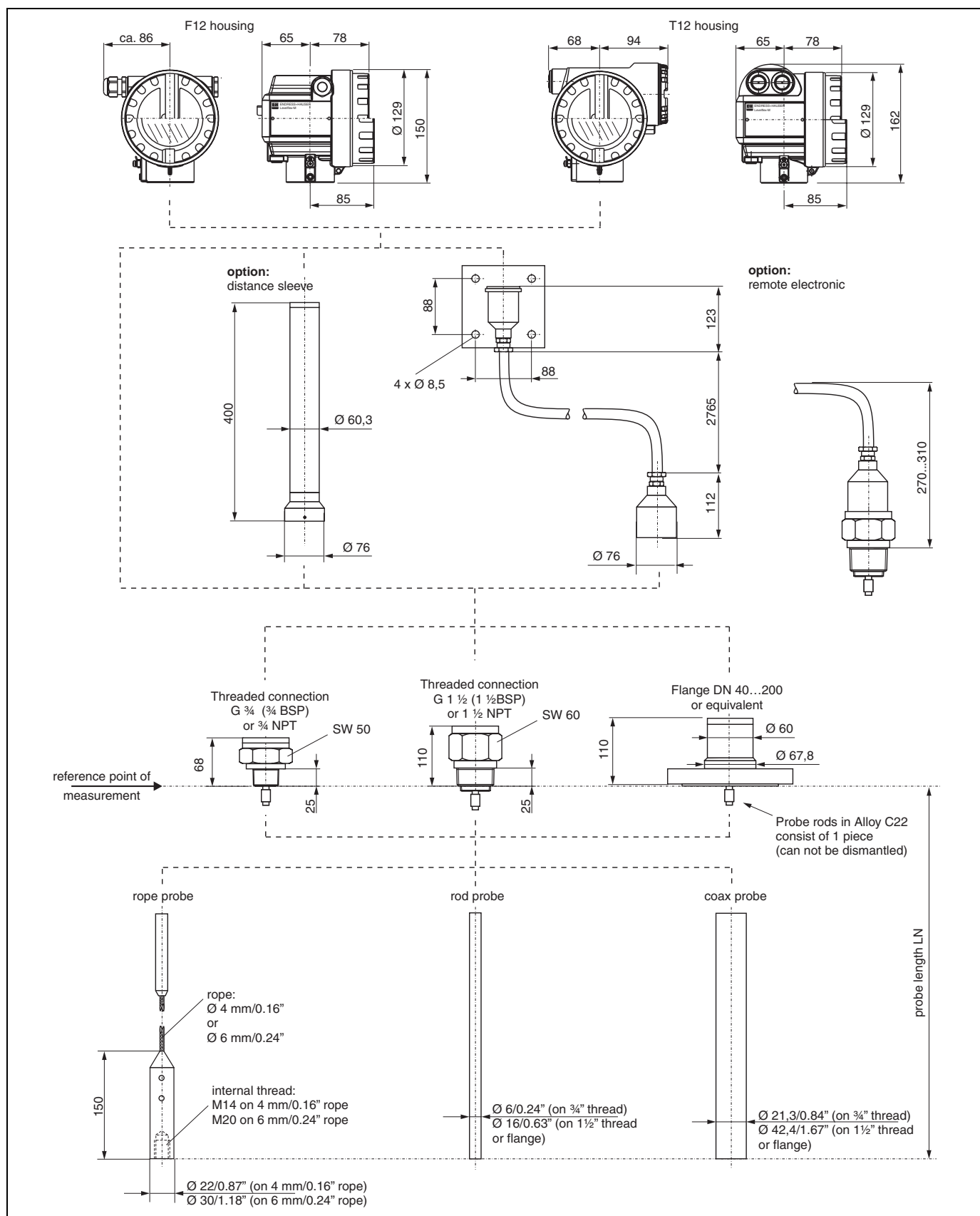


Fig. 2 Dimensions Levelflex M FMP 40

3.4 Installation

3.4.1 Mounting kit

In addition to the tool needed for flange mounting, you will require the following tool:

- 4 mm Allen wrench for turning the housing.

Shortening probes

Rod and rope probes can be easily shortened. This is necessary if the distance to the container floor or outlet cone is less than 150 mm in the case of a rope probe, or less than 100 mm in the case of a rod probe or less than 50 mm in the case of a coax probe.

Shortening rod probes

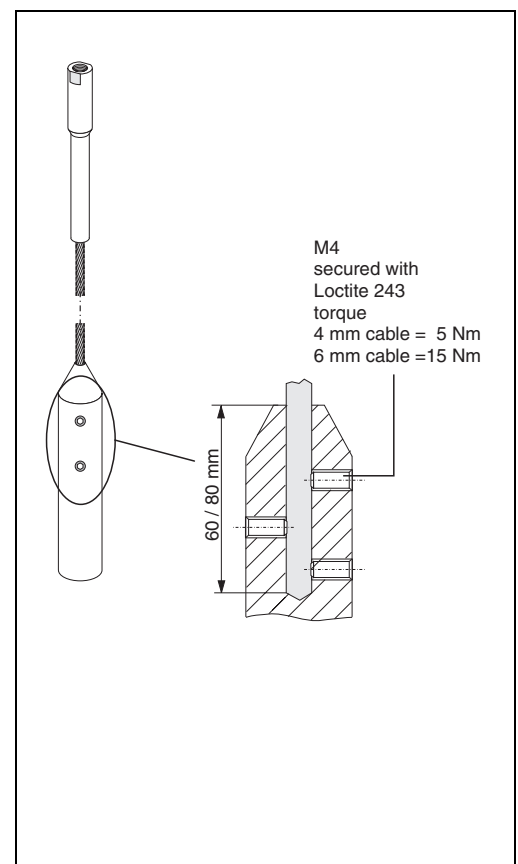
The rods of a rod probe are shortened by sawing or separating at the bottom end.

Shortening rope probes

- Remove ballast weight:
 - The weight is fixed to the probe rope with 3 Allen setscrews (M4, Allen key AF3). The screws are secured with Loctite. This may first have to be made plastic with a hot air apparatus.
- Remove released rope from the weight
- Measure off new rope length
- Wrap adhesive tape around the rope at the point to be shortened to prevent it from fanning out.
- Saw off the rope at a right angle or cut it off with a bolt cutter.
- Insert the rope completely into the weight,
 - thin rope (4 mm) 60 mm deep,
 - thick rope (6 mm) 80 mm deep

The weight is then refixed to the rope:

- Reapply screw locking fluid (we recommend Loctite type 243) to the setscrews and screw into place.
- When doing so, observe the following torques:
 - For 6 mm rope: 15 Nm
 - For 4 mm rope: 5 Nm



Shortening coax probes

Coax probes can be shortened max. 80 mm from the end. They have centering units inside which fix the rod centrally in the pipe. The centerings are held with borders on the rod. Shortening is possible up to approx. 10 mm below the centering.

3.4.2 Engineering hints for level measurement in bulk solids and fluids

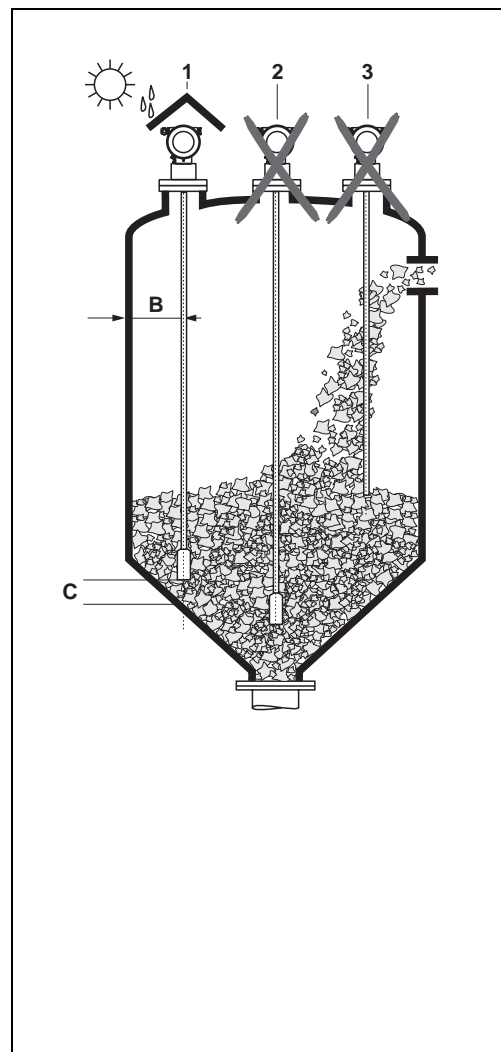
The following installation instructions apply for rope and rod probes for measurement in bulk solids and fluids.

Coax probes are suitable purely for measurement in fluids. They function practically independent of all installation conditions and can, therefore, be installed as desired.

- Temperature conditions must be met (see page 91).
- It is recommended that a protective cover (1) is used, in order to protect the transmitter against direct sunlight or rain (see »Accessories« on page 78.).

Mounting location

- Do not mount rod or rope probes in the filling curtain (3)
- Mount rod and rope probes away from the wall (B) at such a distance that, in the event of build-up on the wall, there is still a minimum distance of 100 mm between the probe and the build-up.
- Mount rod and rope probes as far away as possible from installed fittings. "Mapping " must be carried out during commissioning in the event of distances < 300 mm.
- When installing rod and rope probes in plastic containers, the minimum distance of 300 mm also applies to metallic parts outside the container.
- Rod and rope probes may not, at times, contact metallic container walls or floors.
- In metal containers, do not install rod and rope probes exactly in the centre (2).
- Minimum distance of probe end to the container floor (C):
 - Rope probe: 150 mm
 - Rod probe: 100 mm
 - Coax probe: 50 mm
- When installing outdoors, it is recommended that you use a protective cover (1) see »Accessories« on page 78..

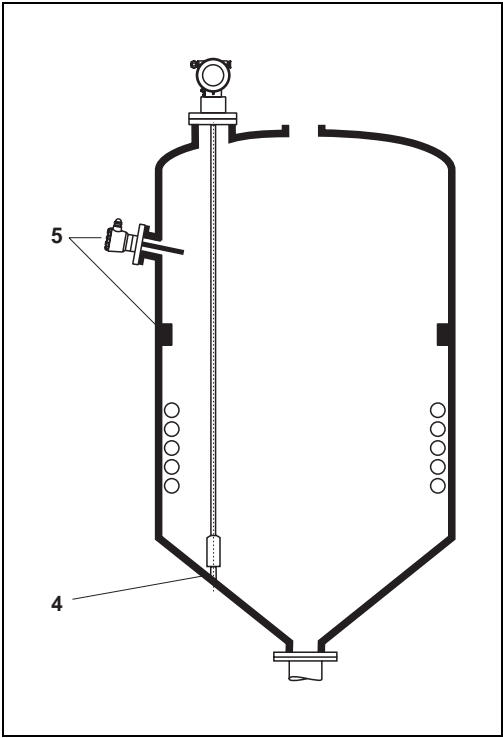


Other installations

- Select the mounting location such that the distance to internals (5) (e.g. limit switch, struts) > is 300 mm over the entire length of the probe, also during operation.
- Probe must within the measuring span not touch any internals during operation. If necessary: when using rope probes the probe end (4) may be fixed to ensure that (see page 23)!

Optimization options

- Interference echo suppression:
Measurement can be optimised by electronically tuning out interference echoes.



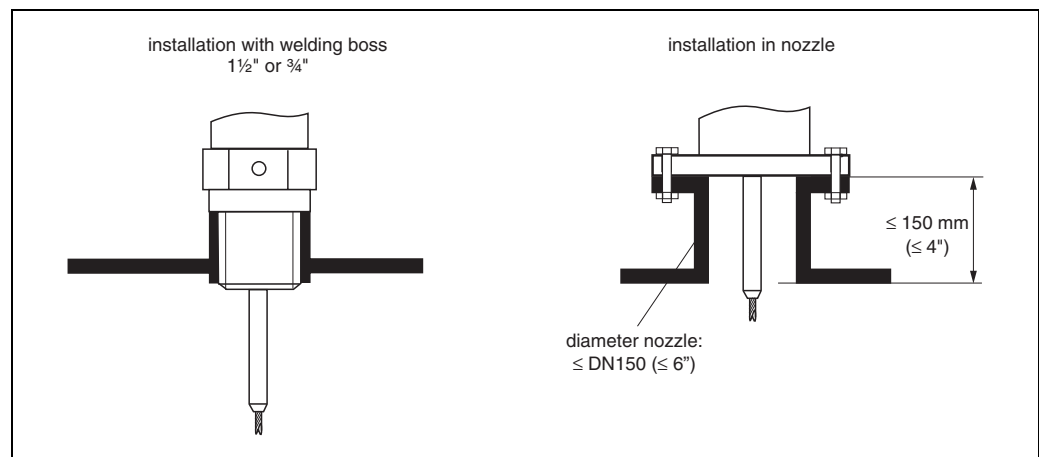
Minimum distance B of the probe to the container wall:

Wall	min. distance B
Metal	100 mm for smooth walls
Plastic	100 mm, min. 300 mm to metallic components outside of the tank
Concrete	0.5 m/20", otherwise the max. possible measuring range is reduced

Distance to protruding internals min. 300 mm.

Standard installation

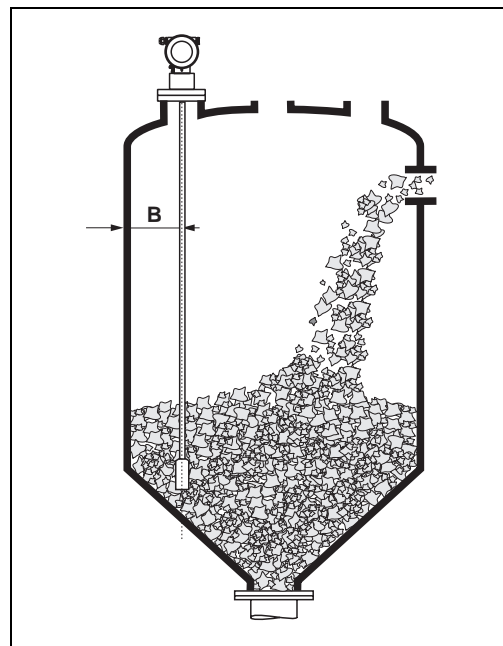
- Probes are mounted to the process connection with threaded connections or flanges and are usually also secured with these. If during this installation there is the danger that the probe end moves so much that it touches the tank floor or cone at times, the probe must, if necessary, be shortened and fixed down. The easiest way to fix the rope probes is to screw them to the internal thread on the lower end of the weight. Thread size, see page 23.
- The ideal installation is mounting in a screwed joint / screw-in sleeve which is internally flush with the container ceiling.
- If installation takes place in a nozzle, the nozzle should be 50 ... 150 mm in diameter and should not be more than 150 mm high. Installation adapters are available for other dimensions, see »Accessories« on page 78.

**Probe length**

- The measuring range is directly dependent on the probe length. If the probe is not fixed at the bottom end, the following distances to the container floor must be observed:
 - Rope probe: 150 mm
 - Rod probe: 100 mm
 - Coax probe: 30 mm
 It is better to order probes too long than too short since it is possible to shorten the probe if necessary.

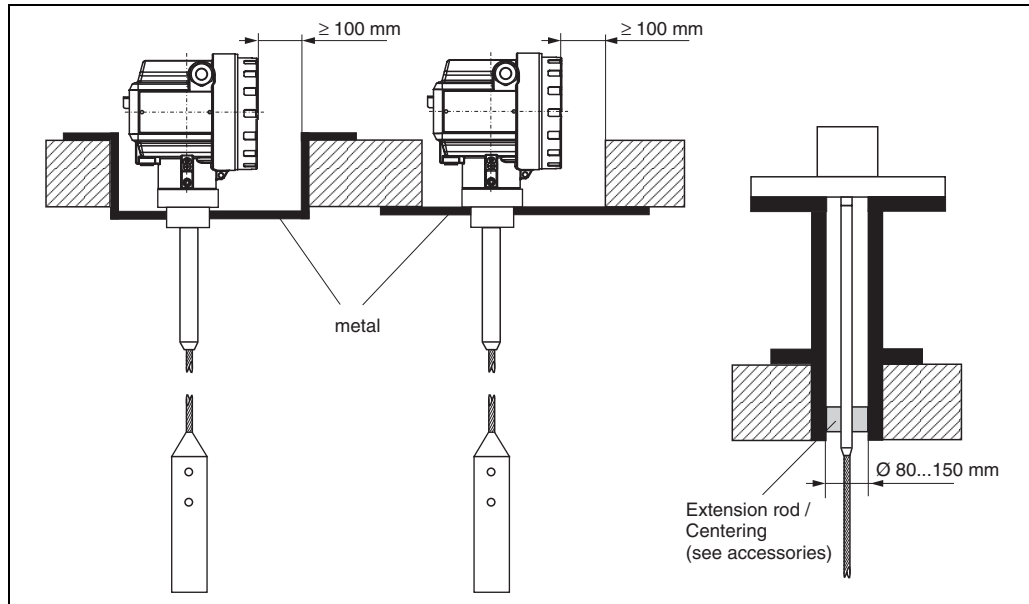
3.4.3 Special notes for bulk solids

- In the case of bulk solids, as great a distance as possible from the filling curtain is especially important to avoid wear.
- In concrete silos, a **large distance (B)** should be observed between the probe and the concrete wall, if possible $\geq 1\text{ m}$, but at least 0.5 m



Installation in concrete silos

Installation, for example, into a thick concrete ceiling should be made flush with the lower edge. Alternatively, the probe can also be installed into a pipe that must not protrude over the lower edge of the silo ceiling. Installation suggestions see diagram.



3.4.4 Installation in bulk solid silos

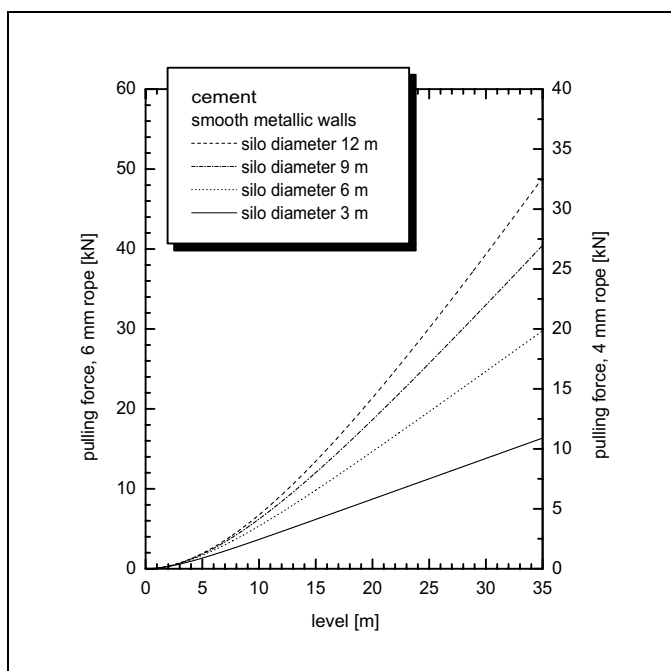
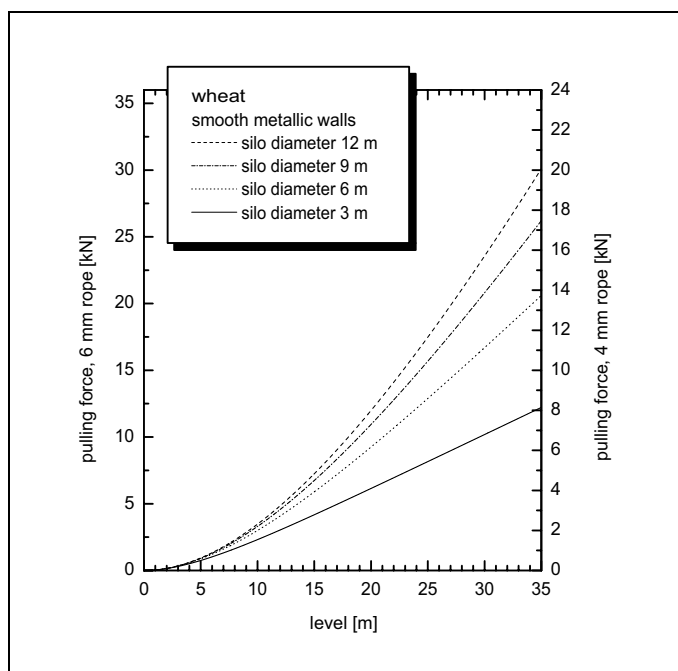
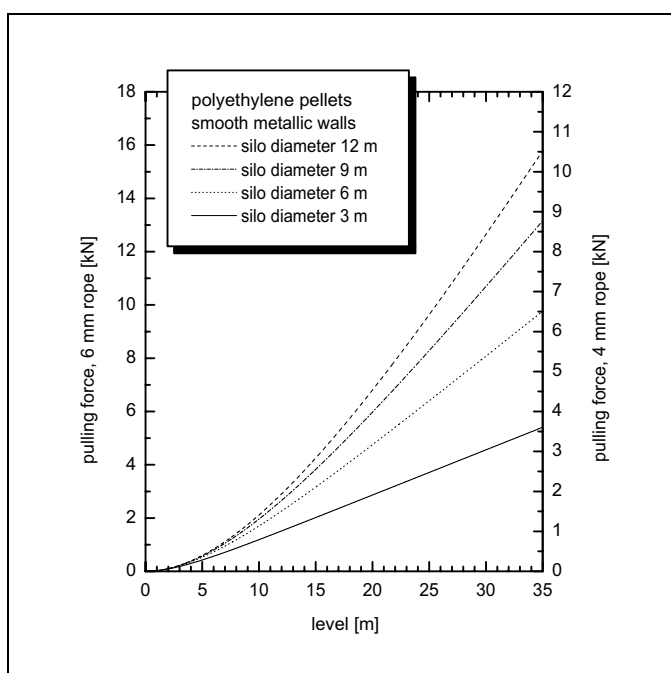
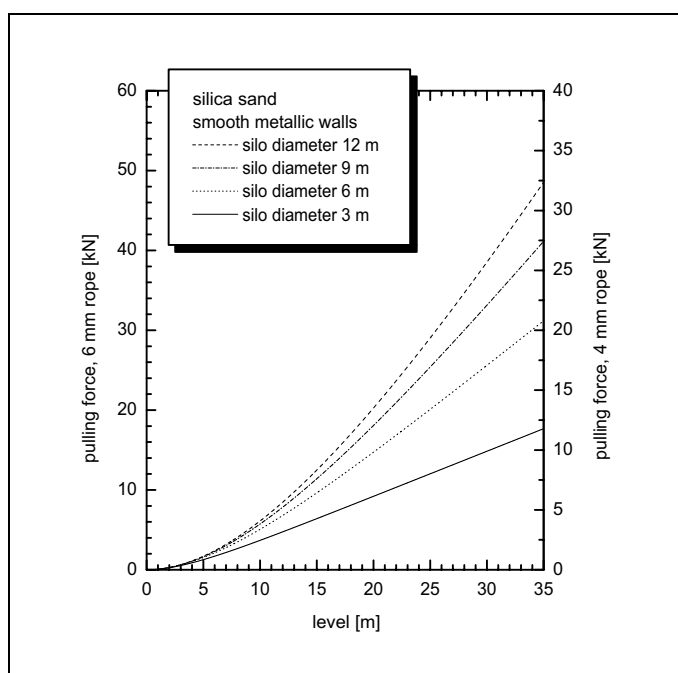
Tensile load

Bulk solids exert tensile forces on rope probes whose height increases with:

- the length of the probe, i.e. max. cover,
- the bulk density of the product,
- the silo diameter and
- the diameter of the probe rope

The following diagrams show typical loads for frequently occurring bulk solids as reference values. The calculation is performed for the following conditions:

- Suspended probe (probe end not fixed at the bottom)
- Free-flowing bulk solid, i.e. mass flow. A calculation for core flow is not possible. In the event of collapsing cornices, considerably higher loads can occur.
- The specification for tensile forces contains the safety factor 2, which compensates for the normal fluctuation range in pourable bulk solids.



Since the tensile forces are also heavily dependent on the viscosity of the product, a higher safety factor is necessary for highly viscous products and if there is a risk of cornice build-up.

In critical cases it is better to use a 6 mm rope instead of a 4 mm one.

The same forces also act on the silo cover.

On a fixed rope, the tensile forces are definitely greater, but this can not be calculated.

Observe the tensile strength of the probes or ensure that the tensile strength of the probes is not exceeded.

Options for reducing the tensile forces:

- Shorten the probe
- If the maximum tensile load is exceeded, check whether it would be possible to use a non-contact ultrasonic device.

3.4.5 Installation in liquids tanks

- When installing in agitation units, check whether a no-contact process (ultrasonic or radar) would be better suited, especially if the agitator generates large mechanical loads on the probe.
- If Levelflex is, nevertheless, installed in tanks with agitators, it is better to use coax probes which have a greater lateral loading capacity.

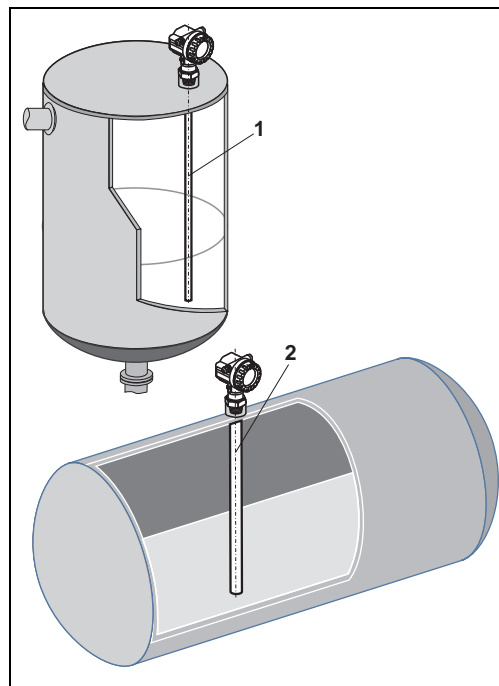
Standard installation

Using a coax probe offers great advantages when the viscosity of the product is ≤ 500 cst and it is certain that the product does not accumulate build-up:

- Greater reliability:
As of dielectric constant=1.4, measurement functions independently of all electrical properties in all liquids.
- Internals in the tank and nozzle dimensions do not have any influence on measurement.
- Higher lateral load-bearing capacity than rod probes.
- For higher viscosity a rod probe is recommended, or using a non-contact measuring principle.

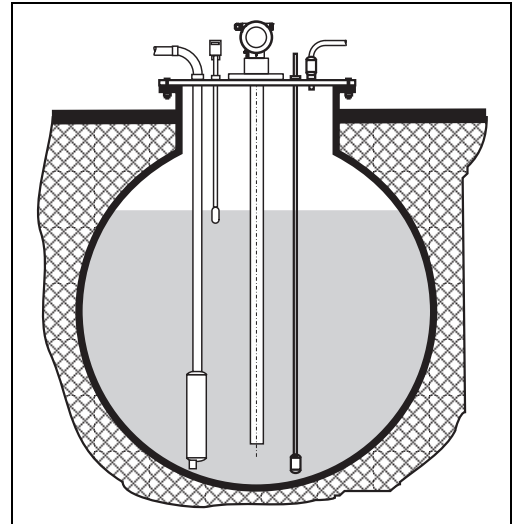
Installation in horizontal cylindrical and standing tanks

- Use a coax or rod probe for measuring ranges up to 4 m. For anything over this or if there is too free cover space use a 4 mm rope probe.
- Installation and possible fixing as with bulk solids.
- Any distance from wall, as long as occasional contact is prevented.
- Do not mount a rod or rope probe (1) exactly central when using metallic containers. Central mounting doesn't impair coax probe (2) performance.
- When installing in tanks with a lot of internals or internals situated close to the probe: Use a coax probe.



Installation in underground tanks

- Use coax probe for nozzles with large diameters in order to avoid reflections at the nozzle wall.

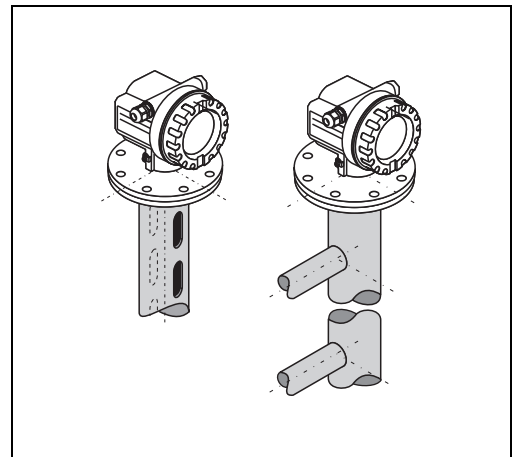


Measurement in corrosive fluids

For measurement in corrosive liquids, it is possible to install a rod probe in a closed plastic pipe with a diameter of up to approx. 50 mm. When using plastic tanks it is also possible to mount the probe on the outside of the tank (see Installation instructions on Page 24). Levelflex measures the level through the plastic in both cases.

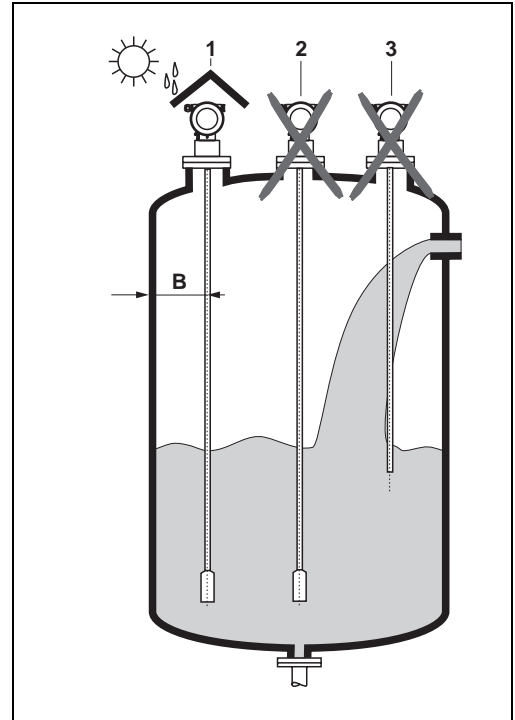
Installation in stilling well or bypass

- A rod probe can be used for pipe diameters up to 150 mm, for diameters above that the flange with horn adapter recommended.
- When installing a rod probe into a metallic pipe with internal diameter of up to 150 mm, you have all the advantages of a coax probe.
- Welded joints that protrude up to approx. 5 mm/0.2" inwards do not influence measurement.



Mounting Location

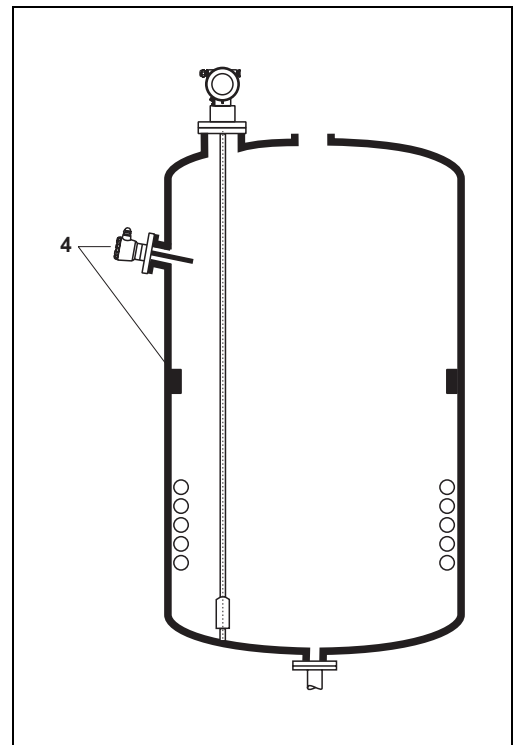
- Recommended distance B wall-mounted rope probe: $\sim 1/6 \dots 1/4$ of the container diameter (min. 100 mm/4", concrete silos: min. 500 mm).
- Not central (2) in metallic tanks.
- Not in the filling curtain (3).
- Please order the probe length such that it ends approx 30 mm above the floor of the tank.
- Temperature conditions must be met.
- It is recommended that a protective cover (1) be used, in order to protect the transmitter against direct sunlight or rain. Mounting and demounting are carried out simply with a clamp (see »Accessories« on page 78.).

**Tank installations**

- Select the mounting location such that the distance to internals (4) (e.g. limit switch, struts) is > 300 mm.

Optimization options

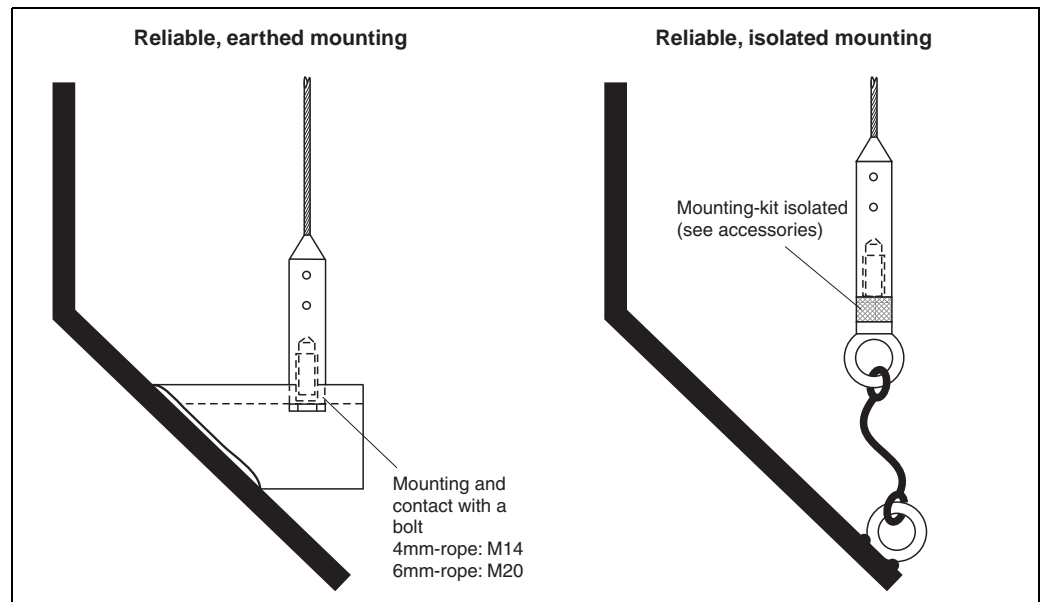
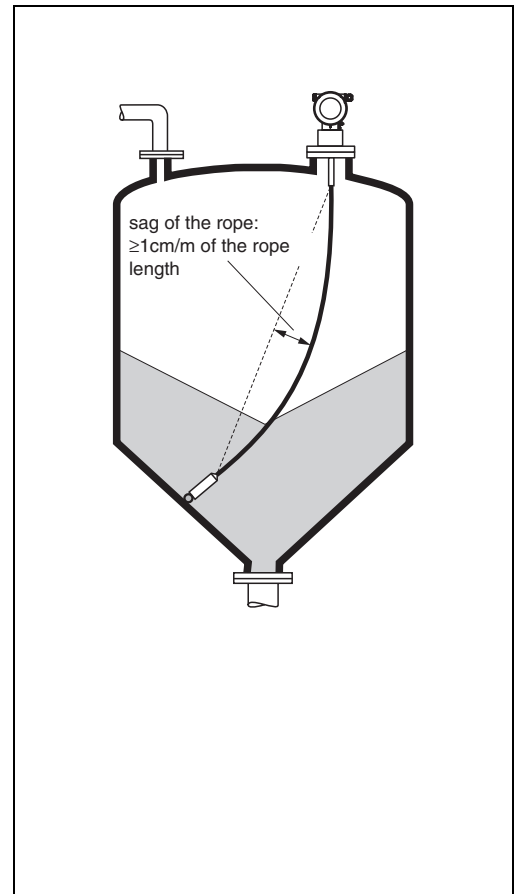
- Interference echo suppression: Measurement can be optimised by electronically tuning out interference echoes.
- Bypass pipe and stilling well (only for liquids): for viscosities of up to 500 cst, a bypass pipe, stilling well or a coax probe can be used to prevent interference.



3.4.6 Notes on special installation situations

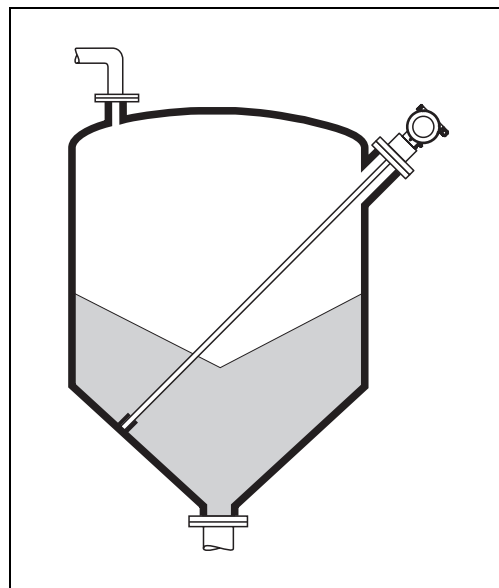
Fixing rope probe

- The end of the probe needs to be secured if the probe would otherwise touch the silo wall, the cone or another part, or the probe comes closer than 0.5 m to a concrete wall. This is what the internal thread in the probe weight is intended for:
 - for 4 mm rope: M14
 - for 6 mm rope: M20
- Preferably use the 6 mm rope probe due to the higher tensile strength when fixing a rope probe
- The fixing must be either reliably grounded or reliably insulated (see accessories). If it is not possible to mount the probe weight with a safe earthed connection, it can be secured using an isolated eyelet, which is available as an accessory (see page 80).
- In order to prevent an extremely high tensile load and the risk of rope crack, the rope has to be slack. Make the rope longer than the required measuring range such that there is a sag in the middle of the rope that is $\geq 1\text{ cm/m}$ ($1''/100''$) of the rope length.



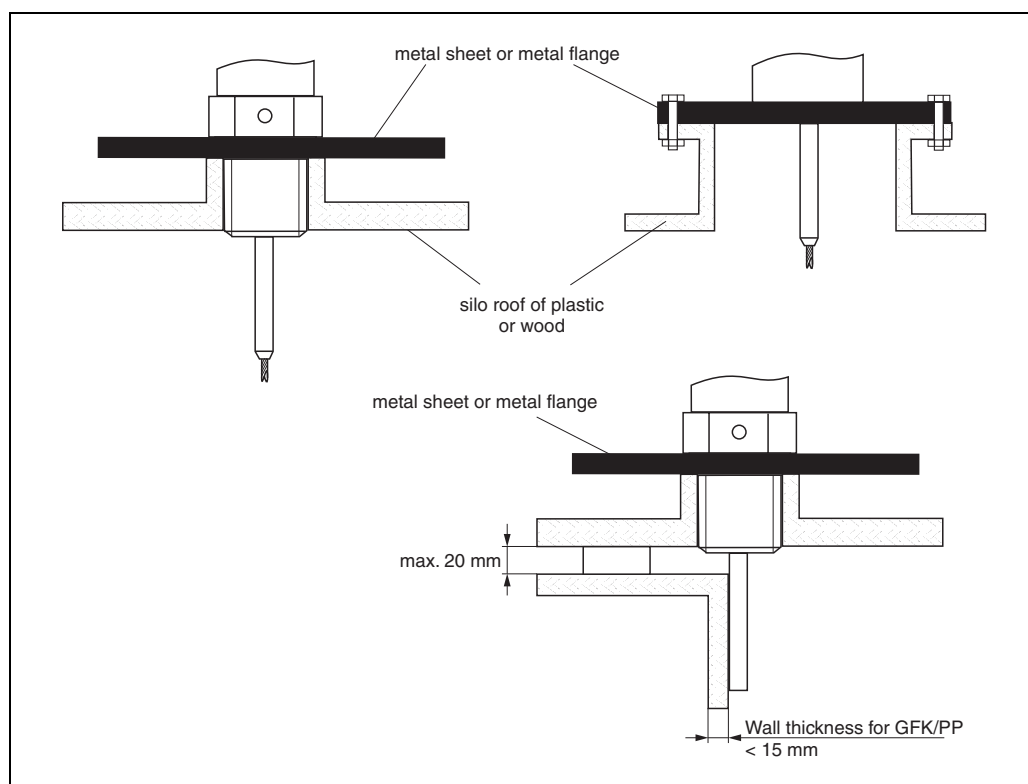
Installation from the side

- If installation from above is not possible, the Levelflex can also be mounted from the side.
- In this case, always fix the rope probe (see »Fixing rope probe«).
- Support coax probe if the lateral load-bearing capacity is exceeded. Only fix rod probes at the probe end.
- Connect rod probe metallicly with the container wall.

**Installation in plastic containers**

Please note that for rod and rope probes only with a metallic surface at the process connection an optimal performance can be guaranteed.

When installing the probe in plastic silos, whose silo cover is also made of plastic or silos with wood cover, the probes must either be mounted in a $\geq \text{DN50}$ / 2" metallic flange, or a metal sheet with diameter of ≥ 200 mm must be mounted under the screw-in piece.



- It is also possible to mount the probe externally on the tank wall for measuring in Aqueous solutions. Measurement then takes place through the tank wall without contacting the medium. If people are in the vicinity of the probe mounting location, a plastic half pipe with a diameter of approx. 200 mm, or some other protective unit, must be affixed externally to the probe to prevent any influences on the measurement.
- There must not be any metallic reinforcement rings secured to the tank.
- The wall thickness should be at Fibre-Glass Reinforced Plastic/PP < 15 mm.
- There must be no open space between the tank wall and the probe.

- If measuring externally, an automatic probe length determination and a two point linearisation must be performed in order to compensate for the time-of-flight change caused by the plastic wall.

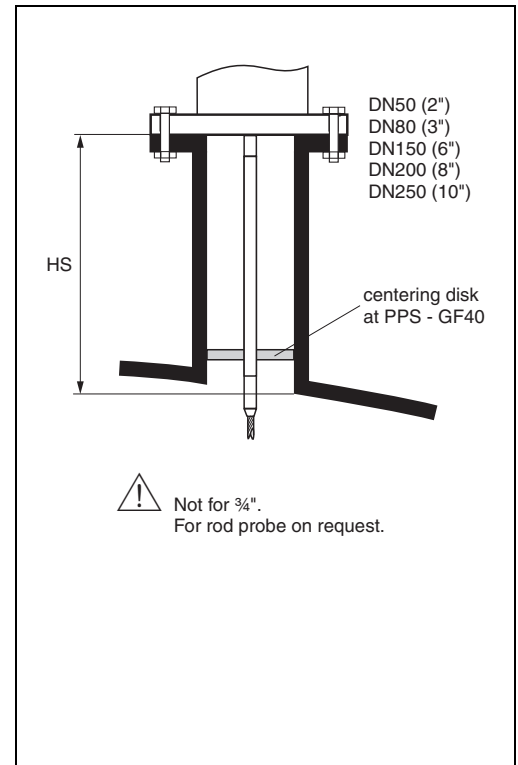
Installation in nozzles > 150 mm high

If, when installing probes in nozzles DN 40...250/1 1/2"...10" with nozzle height (HS) of > 150 mm/6", the probe could touch the lower edge of the nozzle due to moving materials in the container, we recommend using an extension rod with or without centering disk.

This accessory consists of the extension rod corresponding to the nozzle height, on which a centering disk is also mounted if the nozzles are narrow or when working in bulk solids. This component is delivered separately from the device. Please order the probe length correspondingly shorter. For the exact length of the rod see page 79.

Order codes for specific nozzle nominal diameters and heights can be found on Page 79.

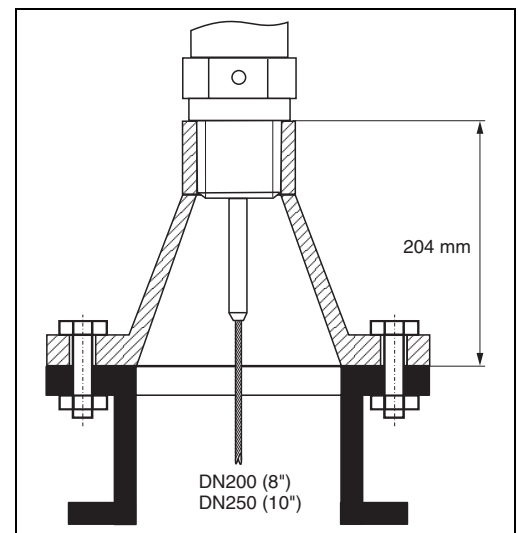
Only use centering disks with small diameters (DN 40 and DN 50) if there is no significant build-up in the nozzle above the disk.



Installation in DN 200/DN 8" and DN 250/DN 10"nozzles

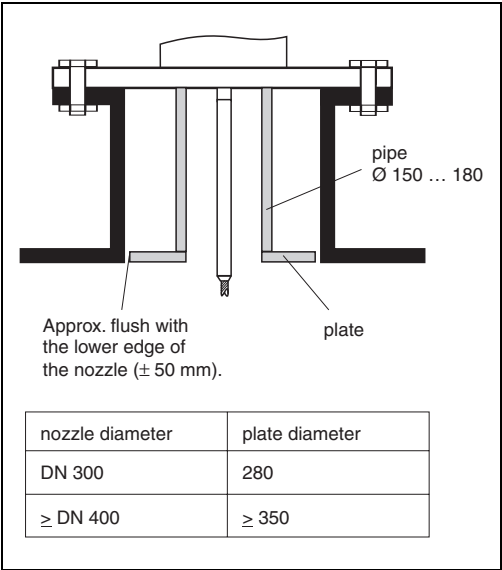
When installing the Levelflex in nozzles of ≥ 210 mm / 8", signals are generated by reflections on the nozzle wall, which can sometimes lead to faulty measurements in the case of products with small dielectric constants. With nozzle diameters of 200 mm / 8" or 250 mm / 10", therefore, a special flange with a "horn adaptor" must be fitted.

Nozzles with nominal diameters greater than DN 250 / 10" should be avoided.



Installation in \geq DN 300/DN 12" nozzles

If installation in $\geq 300\text{mm}/12''$ nozzles is unavoidable, installation must be carried out in accordance with the sketch on the right.

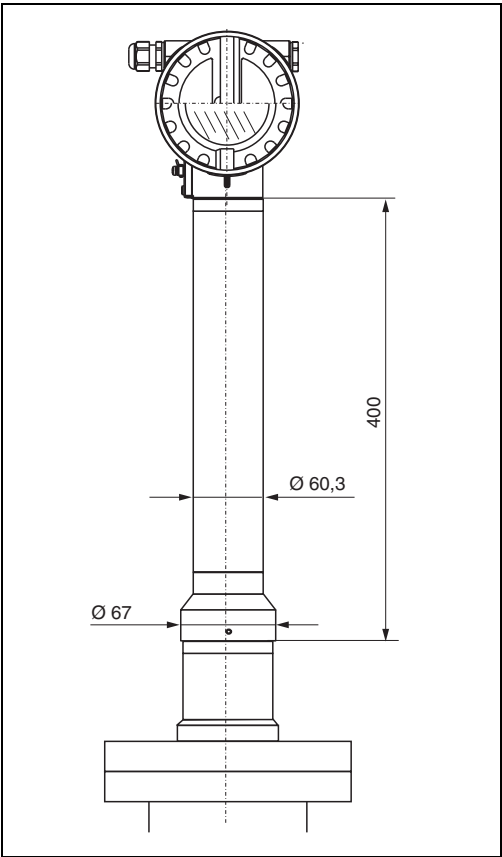


3.4.7 Installation for difficult to access process connections

For tight spaces or temperatures above that in the graphic, the electronics housing can be ordered with distance pipe or connecting cable (seperate housing).

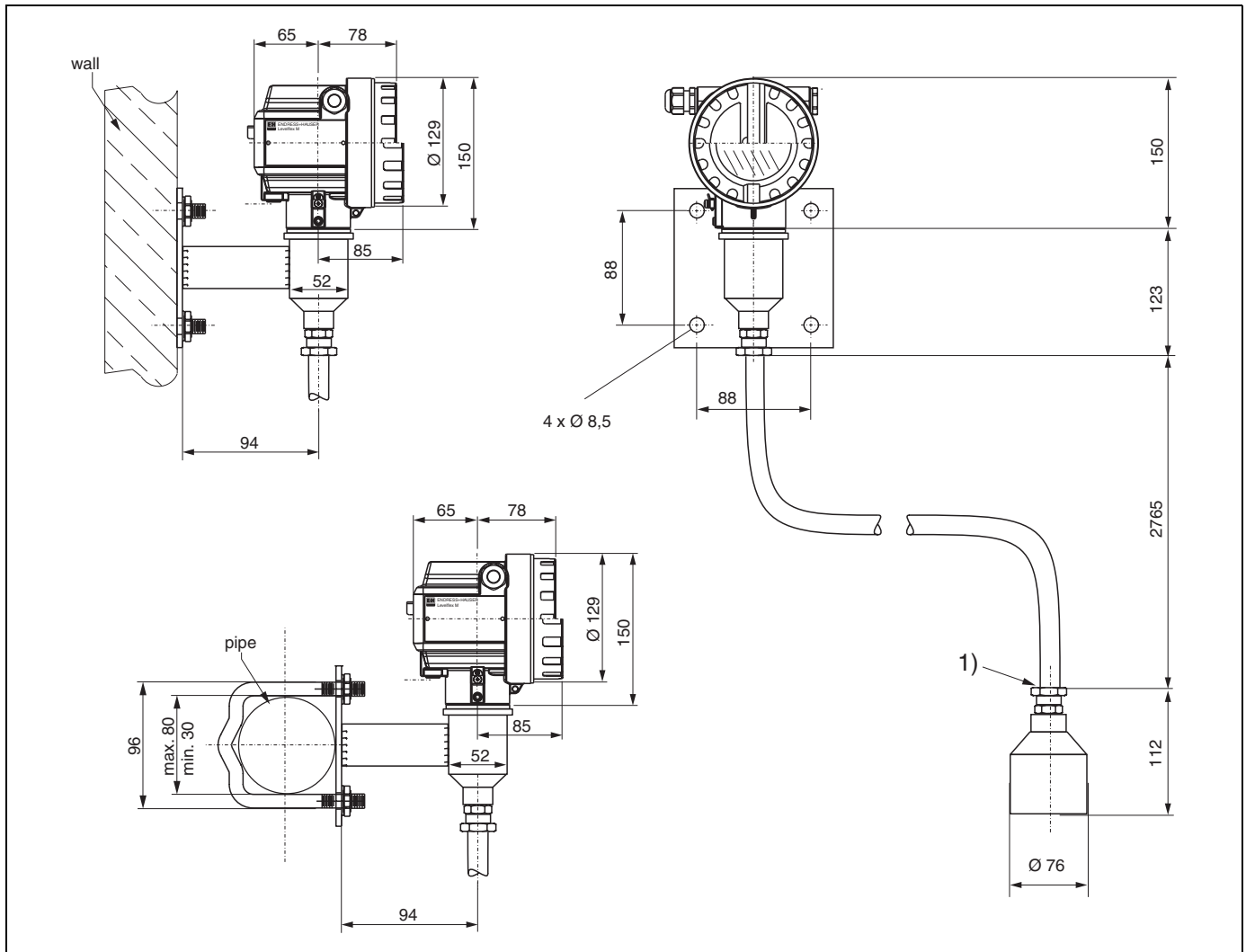
Installation with distance pipe

- Follow installation instructions on Page 14 ff..
- After mounting, the housing can be turned 350°, in order make access to the display and the connection compartment easier.
- The max. measuring range is reduced to 34 m/1338".



Installation with separate housing

- Follow installation instructions on Page 14 ff..
- Mount housing on a wall or pipe as shown in the diagram.



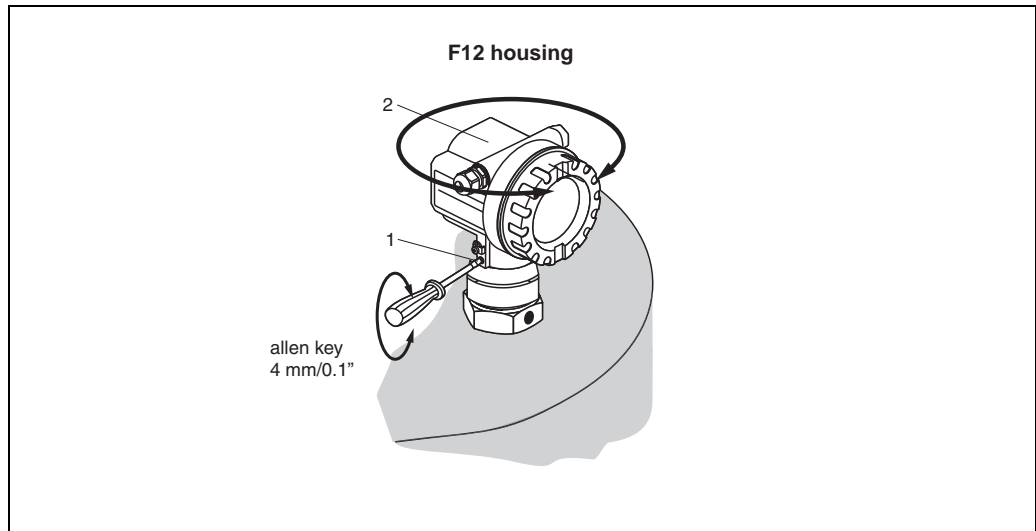
The separate housing is designed for use at high environmental temperatures at the mounting location of the sensor. The max. measuring range is reduced to 30 m/1181". The version with separate housing consists of the probe, a connecting cable and the housing. If they are ordered as a set, they are assembled on delivery.

1) The protective hose can not be dismantled at this point.

3.4.8 Turn housing

After mounting, the housing can be turned 350° in order to simplify access to the display and the terminal compartment. Proceed as follows to turn the housing to the required position:

- Undo the fixing screws (1)
- Turn the housing (2) in the required direction
- Tighten up the fixing screws (1).



3.5 Post-installation check

After the measuring instrument has been installed, perform the following checks:

- Is the measuring instrument damaged (visual check)?
- Does the measuring instrument correspond to the measuring point specifications such as process temperature/pressure, ambient temperature, measuring range, etc.?
- Are the measuring point number and labeling correct (visual check)?
- Is the measuring instrument adequately protected against rain and direct sunlight (see page 78 ff.)?

4 Wiring

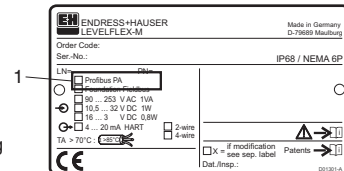
4.1 Quick wiring guide

Wiring in F12 housing



Before connection please note the following:

- PROFIBUS devices are marked on the nameplate (1). The voltage is determined by the PROFIBUS standard and the desired safety concept. (see chapter 4.3).
- Connect potential matching line to transmitter ground terminal (7) before connecting up the device.
- Tighten the locking screw (8):
It forms the connection between the antenna and the housing earth potential.



When you use the measuring system in hazardous areas, make sure you comply with national standards and the specifications in the safety instructions (XA's).
Make sure you use the specific cable gland.



On devices supplied with a certificate, the explosion protection is designed as follows:

- Housing F12 - EEx ia:
Power supply must be intrinsically safe.
- The electronics and the current output are galvanically separated from the probe circuit.

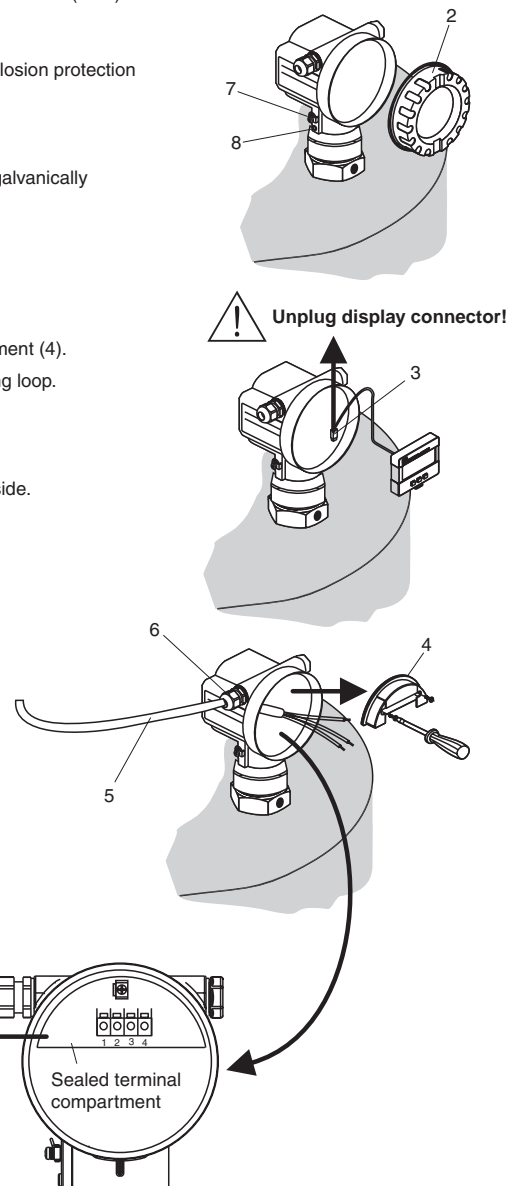
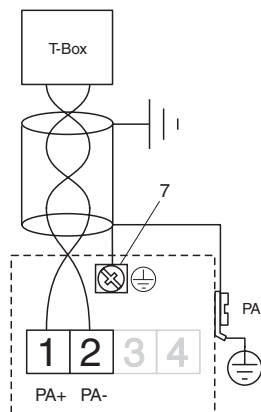
Connect up the Levelflex M as follows:

- Unscrew housing cover (2).
- Remove any display (3) if fitted.
- Remove cover plate from terminal compartment (4).
- Pull out terminal module slightly using pulling loop.
- Insert cable (5) through gland (6).
- Use screened, twisted wire pair.



Only ground screen conductor (7) on sensor side.

- Make connection (see pin assignment).
- Re-insert terminal module.
- Tighten cable gland (6).
- Tighten screws on cover plate (4).
- Insert display if fitted.
- Screw on housing cover (2).
(on dust-Ex torque = 40 Nm).



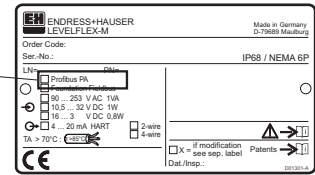
Wiring with M12 connector



Caution!

Before connection please note the following:

- PROFIBUS devices are marked on the nameplate (1). The voltage is determined by the PROFIBUS standard and the desired safety concept. (see chapter 4.3).
- Connect potential matching line to transmitter earth terminal before connecting up the device.
- Tighten the locking screw:
It forms the connection between the probe and the housing earth potential.



When you use the measuring system in hazardous areas, make sure you comply with national standards and the specifications in the safety instructions (XA's).
Make sure you use the specific cable gland.

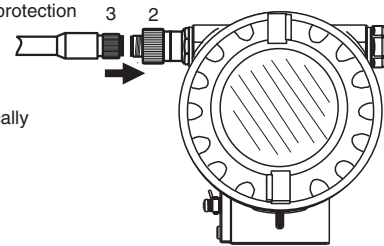


On devices supplied with a certificate, the explosion protection is designed as follows:

- Housing F12 - EEx ia:
Power supply must be intrinsically safe.
- The electronics and the current output are galvanically separated from the antenna circuit.

The Levelflex M is connected as follows:

- Insert plug (2) into bushing (3).
- Screw firmly
- Ground the device according to the desired safety concept.



4.2 Cable specifications PROFIBUS

Twisted, screened pairs must be used. The following specification must be met for explosion hazardous application (EN 50 020, FISCO model):

- Loop-resistance (DC): 15...150 Ω /km,
- Specific inductance: 0.4...1 mH/km,
- Specific capacitance: 80...200 nF/km

The following cable types can be used, for example

Non-Ex-area:

- Siemens 6XV1 830-5BH10 (black),
- Belden 3076F, Kerpen CEL-PE/OSCR/PVC/FRLA FB-02YS(ST)YFL (grey)

Ex-area:

- Siemens 6XV1 830-5AH10 (blue),
- Belden 3076F, Kerpen CEL-PE/OSCR/PVC/FRLA FB-02YS(ST)YFL (blue)

4.3 Connecting the measuring unit

Housing

Housing orientation regarding the wiring, see »Turn housing« on page 28.

Cable entry

Cable gland: M20x1.5 or Pg13.5

Cable entry: G ½ or ½" NPT

PROFIBUS-PA M12 plug

Supply voltage

The following values are the voltages across the terminals directly at the instrument:

Type	Terminal voltage	
	minimum	maximum
standard	9 V	32 V
EEx ia (FISCO model)	9V	17.5 V
EEx ia (Entity concept)	9 V	24 V

Current consumption

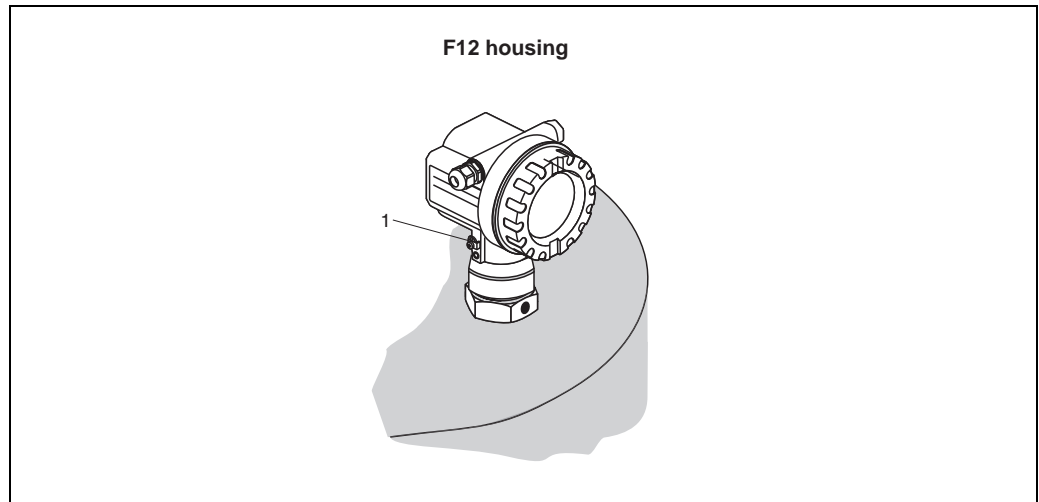
approx 11 mA for the range of voltages given above

Connection with M12 plug

The Levelflex M PROFIBUS-PA sensor version with M12 plug is supplied ready wired and need only be connected to the bus by means of a suitable cord set (see Page 30).

4.4 Equipotential bonding

For maximum protection against electromagnetic interference, e.g. when the bus is operating near frequency converters, it is recommended that high integrity potential bonding be provided between the housing and the cable screening. Transposed, screened two-wire cabling is recommended for the connecting cable. Max. wire diameter: 2.5 mm² ; permanently attached cable..



Please take account of the following points

- The external ground terminal (1) on the transmitter must be connected to ground.
- The continuity of the cable screening between tapping points must be ensured.
- The screening must be grounded at each end of the cable.
- If there are large differences in potential between grounding points, the grounding should run via a capacitor that is suitable for high frequency use (e.g. ceramic 10 nF/ 250 V~).
- Connect the equipotential bonding to the external ground terminal of the transmitter.



Caution!

Applications, which are subject to the explosion prevention, permit only under special conditions the repeated grounding of the protective screen , see to EN 60 079-14..

Further notes for the setting up and to the grounding of the network are in that the manual BA 198F "PROFIBUS-PA: Manual to project engineering and commissioning" to infer and the Profibus Pa specification EN 50 170.

4.5 Degree of protection

- housing: IP 68, NEMA 4X (open housing: IP20, NEMA 1)
- antenna: IP 68 (NEMA 6P)

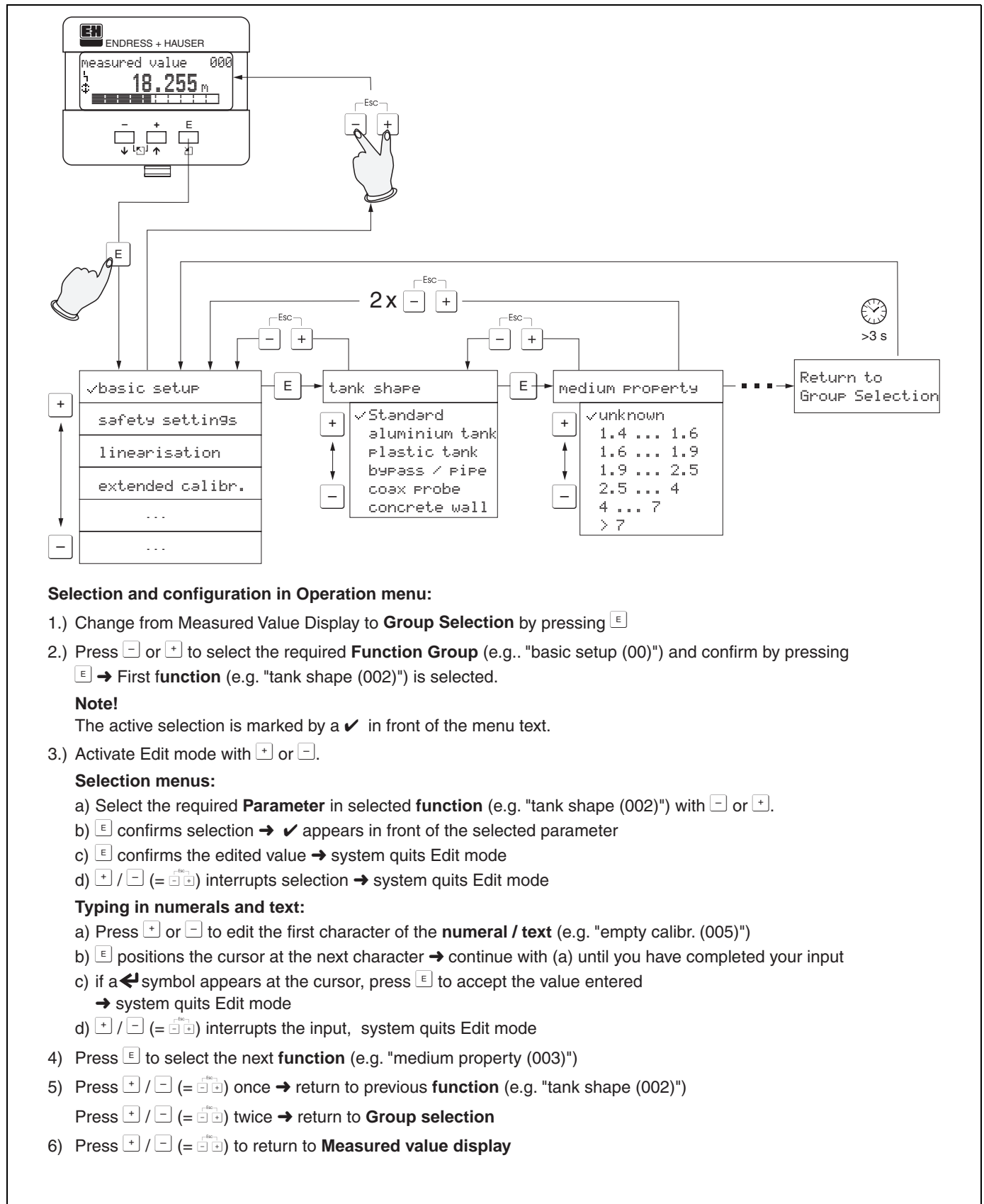
4.6 Post-connection check

After wiring the measuring instrument, perform the following checks:

- Is the terminal allocation correct (see page 29 ff. and page 30)?
- Is the cable gland tight?
- Is the M12 connector screwed tight?
- Is the housing cover screwed tight?
- If auxiliary power is available:
Is the instrument ready for operation and does the liquid crystal display show any value?

5 Operation

5.1 Quick operation guide



5.1.1 General structure of the operating menu

The operating menu is made up of two levels:

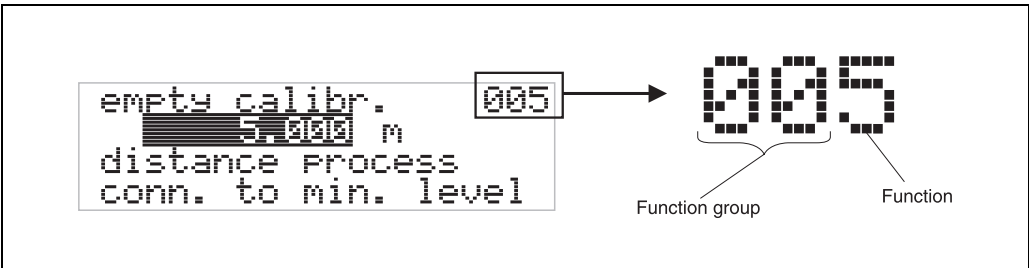
- **Function groups (00, 01, 03, ..., 0C, 0D):**
The individual operating options of the instrument are split up roughly into different function groups. The function groups that are available include, e.g.: **"basic setup"**, **"safety settings"**, **"profibus param."**, **"display"**, etc.
- **Functions (001, 002, 003, ..., 0D8, 0D9):**
Each function group consists of one or more functions. The functions perform the actual operation or parameterisation of the instrument. Numerical values can be entered here and parameters can be selected and saved. The available functions of the **"basic setup (00)"** function group include, e.g.: **"tank properties" (002)**, **"medium property (003)"**, **"process cond. (004)"**, **"empty calibr. (005)"**, etc.

If, for example, the application of the instrument is to be changed, carry out the following procedure:

1. Select the **"basic setup (00)"** function group.
2. Select the **"tank properties" (002)** function (where the existing tank shape is selected).

5.1.2 Identifying the functions

For simple orientation within the function menus, for each function a position is shown on the display.



The first two digits identify the function group:

- **basic setup** **00**
- **safety settings** **01**
- **length adjustment** **03**
- ...

The third digit numbers the individual functions within the function group:

- | | | | | |
|----------------------|-----------|---|--------------------------|------------|
| • basic setup | 00 | → | • tank properties | 002 |
| | | | • medium property | 003 |
| | | | • process cond. | 004 |
| | | | ... | |

- Here after the position is always given in brackets (e.g. **"tank properties" (002)**) after the described function.

5.2 Display and operating elements

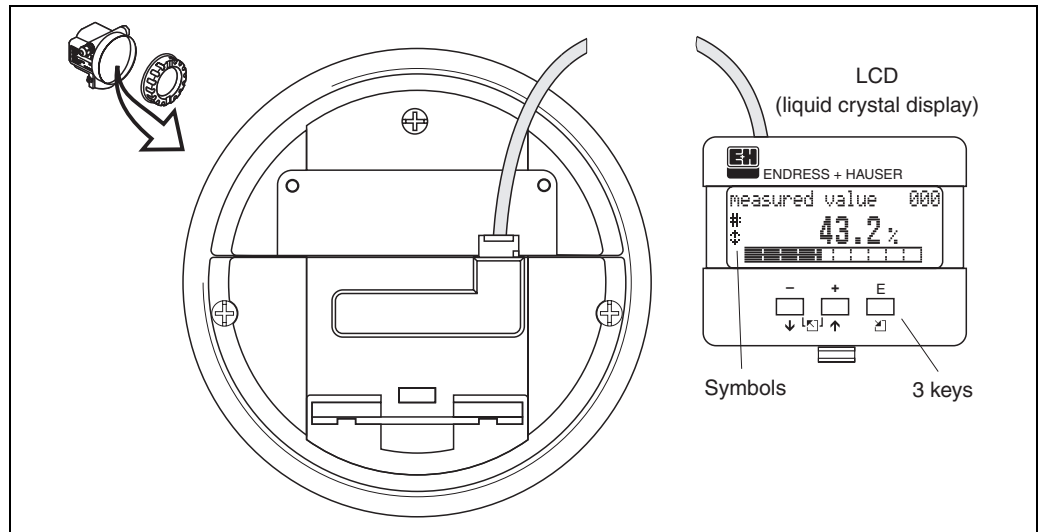


Fig. 3 Layout of the display and operating elements

5.2.1 Display

Liquid crystal display (LCD):

Four lines with 20 characters each. Display contrast adjustable through key combination.

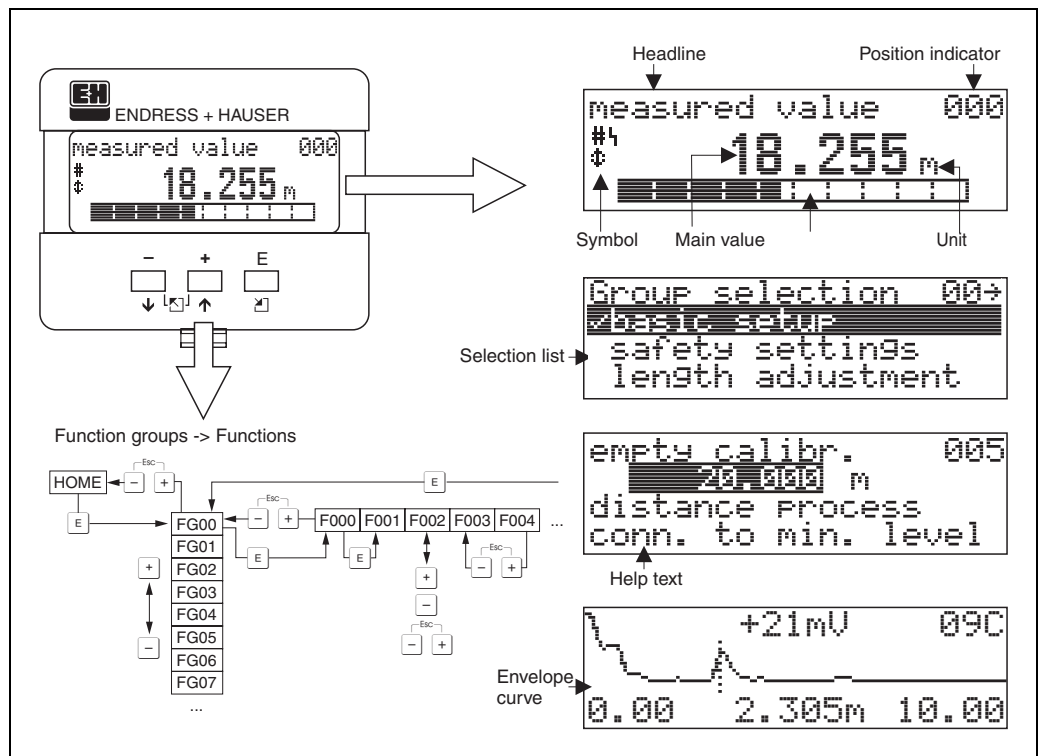





Fig. 4 Display

5.2.2 Display symbols

The following table describes the symbols that appear on the liquid crystal display:
















Symbols	Meaning
	ALARM_SYMBOL This alarm symbol appears when the instrument is in an alarm state. If the symbol flashes, this indicates a warning.
	LOCK_SYMBOL This lock symbol appears when the instrument is locked,i.e. if no input is possible.
	COM_SYMBOL This communication symbol appears when a data transmission via e.g. HART, PFOFIBUS-PA or Foundation Fieldbus is in progress.

Tab. 1 Meaning of Symbols

5.2.3 Key assignment

The operating elements are located inside the housing and are accessible for operation by opening the lid of the housing.

Function of the keys

Key(s)	Meaning
 or 	Navigate upwards in the selection list Edit numeric value within a function
 or 	Navigate downwards in the selection list Edit numeric value within a function
 or 	Navigate to the left within a function group
 or 	Navigate to the right within a function group, confirmation.
 and  or  and 	Contrast settings of the LCD
 and  and 	Hardware lock / unlock After a hardware lock, an operation of the instrument via display or communication is not possible! The hardware can only be unlocked via the display. An unlock parameter must be entered to do so.


Tab. 2 Function of the keys

5.3 Local operation








5.3.1 Locking of the configuration mode

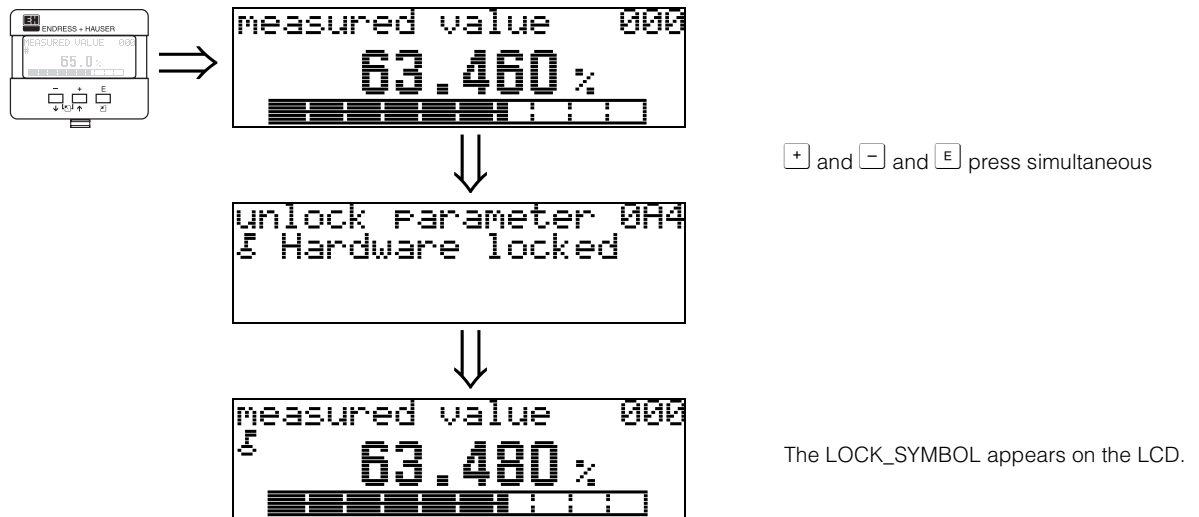
The Levelflex can be protected in two ways against unauthorised changing of instrument data, numerical values or factory settings:

"unlock parameter" (0A4):

A value \leftrightarrow 2457 (e.g. 2456) must be entered in "unlock parameter" (0A4) in the "diagnostics" (0A) function group. The lock is shown on the display by the  symbol and can be released again either via the display or by communication.

Hardware lock:

The instrument is locked by pressing the  and  and  keys at the same time. The lock is shown on the display by the  symbol and can **only** be unlocked again via the display by pressing the  and  and  keys at the same time again. It is **not** possible to unlock the hardware by communication. All parameters can be displayed even if the instrument is locked.



5.3.2 Unlocking of configuration mode

If an attempt is made to change parameters when the instrument is locked, the user is automatically requested to unlock the instrument:

"unlock parameter" (0A4):

By entering the unlock parameter (on the display or via communication)

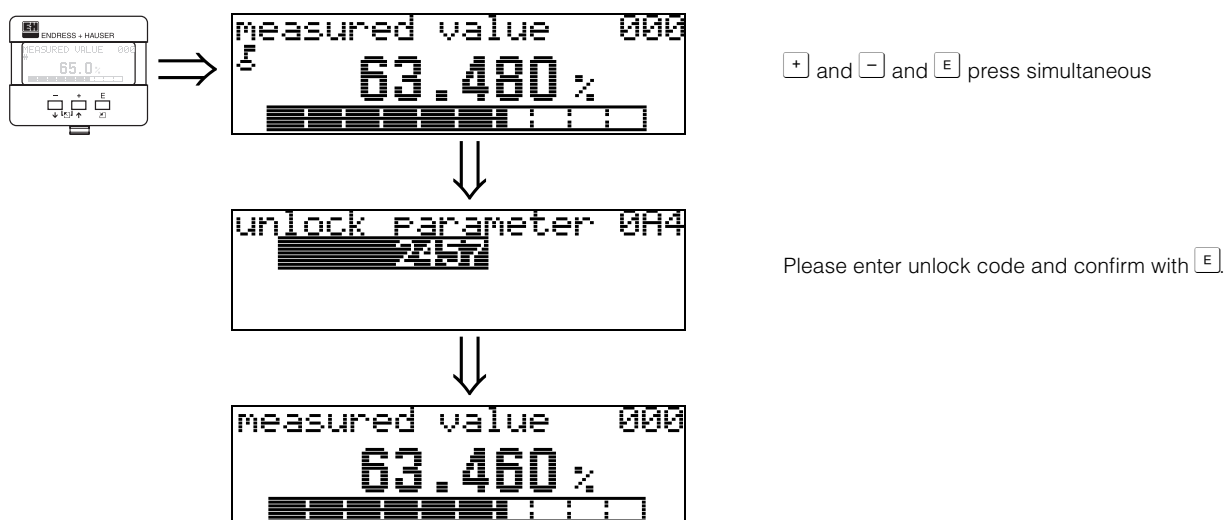
2457 = for PROFIBUS devices

the Levelflex is released for operation.

Hardware unlock:

After pressing the **+** and **-** and **E** keys at the same time, the user is asked to enter the unlock parameter

2457 = for PROFIBUS devices.



Caution!

Changing certain parameters such as all sensor characteristics, for example, influences numerous functions of the entire measuring system, particularly measuring accuracy. There is no need to change these parameters under normal circumstances and consequently, they are protected by a special code known only to the E+H service organization. Please contact Endress+Hauser if you have any questions.

5.3.3 Factory settings (Reset)



Caution!

A reset sets the instrument back to the factory settings. This can lead to an impairment of the measurement. Generally, you should perform a basic setup again following a reset.

A reset is only necessary:

- if the instrument no longer functions
- if the instrument must be moved from one measuring point to another
- if the instrument is being de-installed /put into storage/installed



User input ("reset" (0A3)):

- 33 333= reset of customer parameters

33 333 = reset customer parameters

This reset is recommended whenever an instrument with an unknown 'history' is to be used in an application:

- The Levelflex is reset to the default values.
- **The customer specific tank map is not deleted.**
- The mapping can also be deleted in the "**cust. tank map**" (055) function of the "**extended calibr.**" (05) function group.
- A linearisation is switched to "**linear**" although the table values are retained. The table can be reactivated in the "**linearisation**" (04) function group.

List of functions that are affected by a reset

- | | |
|------------------------------|--------------------------|
| • tank properties (002) | • max. scale (046) |
| • medium cond. (003) | • diameter vessel (047) |
| • process proper. (004) | • check distance (051) |
| • empty calibr. (005) | • range of mapping (052) |
| • full calibr. (006) | • start mapping (053) |
| • output on alarm (010) | • delete mapping (055) |
| • outp. echo loss (012) | • offset (057) |
| • ramp %span/min (013) | • output damping (058) |
| • delay time (014) | • language (092) |
| • safety distance (015) | • back to home (093) |
| • in safety dist. (016) | • format display (094) |
| • overspill protection (018) | • no of decimals (095) |
| • broken probe det (019) | • sep. character (096) |
| • end of probe (030) | • unlock parameter (0A4) |
| • level/ullage (040) | • application par (0A8) |
| • linearisation (041) | • tag no (0C0) |
| • customer unit (042) | |




A complete "**basic setup**" (00) must be activated.

5.4 Display and acknowledging error messages

Type of error



Errors that occur during commissioning or measuring are displayed immediately on the local display. If two or more system or process errors occur, the error with the highest priority is the one shown on the display.

The measuring system distinguishes between two types of error:

- **A (Alarm):**
Instrument goes into a defined state (e.g. MAX 22 mA)
Indicated by a constant  symbol.
(For a description of the codes, see table 9.2 on page 83)
- **W (Warning):**
Instrument continue measuring, error message is displayed.
Indicated by a flashing  symbol.
(For a description of the codes, see table 9.2 on page 83)
- **E (Alarm / Warning):**
Configurable (e.g. loss of echo, level within the safety distance)
Indicated by a constant/flashing  symbol.
(For a description of the codes, see table 9.2 on page 83)

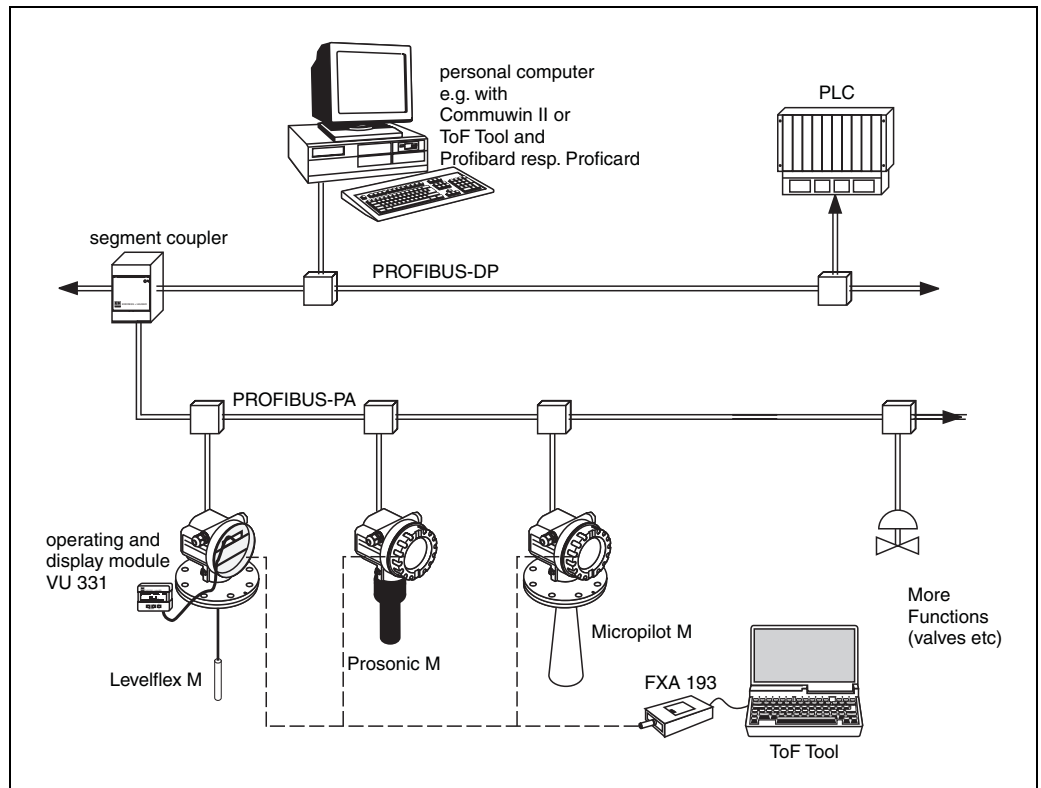


Error messages

- Error messages appear as four lines of plain text on the display. In addition, a unique error code is also output. A description of the error codes is given on page 83.
- The "**diagnostics (0A)**" function group can display current errors as well as the last errors that occurred.
- If several current errors occur, use  or  to page through the error messages.
- The last occurring error can be deleted in the "**diagnostics (0A)**" function group with the function "**clear last error**" (**0A2**).

5.5 PROFIBUS communication

5.5.1 Synopsis



A maximum of 32 transmitters can be connected to the bus (10 in explosion hazardous areas EEx ia IIC according to the FISCO model). The bus power is supplied by the segment coupler. On-site- as well as remote operation are possible. For detailed information on the PROFIBUS-PA standard refer to Operation Instructions BA 198F/00/de and the standards EN 50 170/DIN 19 245 (PROFIBUS-PA) and EN 50 020 (FISCO model).

5.5.2 Device address

Selecting the device address

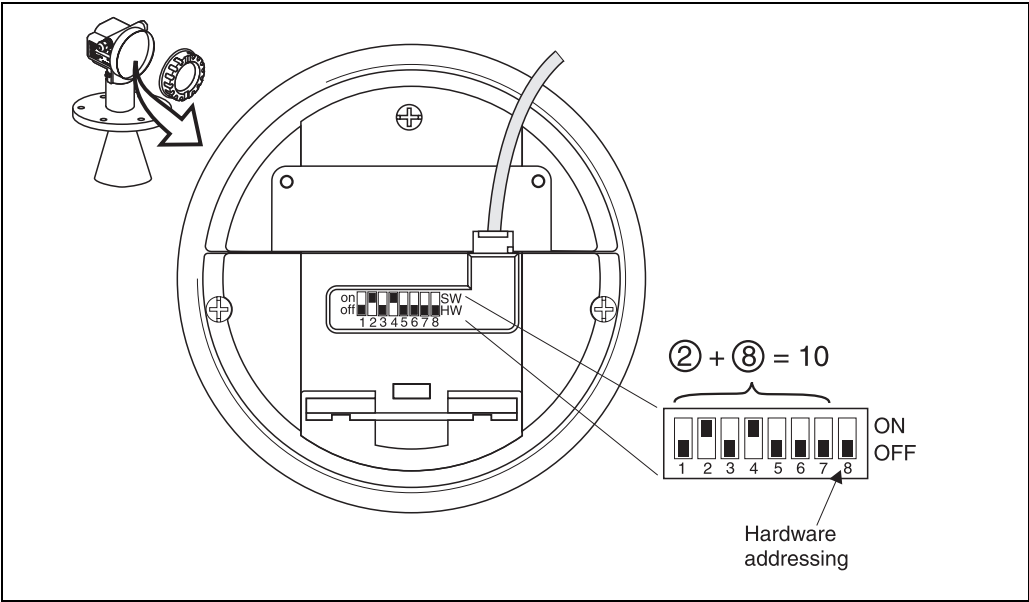
- Every PROFIBUS-PA device must be given an address. If the address is not set correctly, the device will not be recognised by the process control system.
- A device address may appear only once within a particular PROFIBUS-PA network, see BA 198F.
- Valid device addresses are in the range 1 and 126. All devices are delivered from the factory with the software address 126.
- The default address can be used to check the function of the device and connect it to an operating PROFIBUS-PA system. Afterwards the address must be changed to allow other devices to be connected to the network.

Software addressing

Software addressing comes into operation, when DIP-switch 8 is in the position "ON". BA 198F/00/en, chap. 5.7 describes, how to set the address in this case.

In ToF Tool, the address can be set via the **"Set address"** function in the **"Device"** menu.

Hardware addressing



Hardware addressing comes into operation, when DIP switch 8 is in the position "OFF". In this case the address is determined by the position of DIP-switches 1 to 7 according to the following table:

Switch No.	1	2	3	4	5	6	7
Value in position "OFF"	0	0	0	0	0	0	0
Value in Position "ON"	1	2	4	8	16	32	64

The new address becomes valid 10 seconds after switching.

5.5.3 Device database and type files (GSD)

A device database file (GSD) contains a description of the properties of the PROFIBUS-PA device, e.g. the supported transmission rates and the type and format of the digital information output to the PLC.

Additional bitmap files are required in order to represent the device by an icon in the network design software.

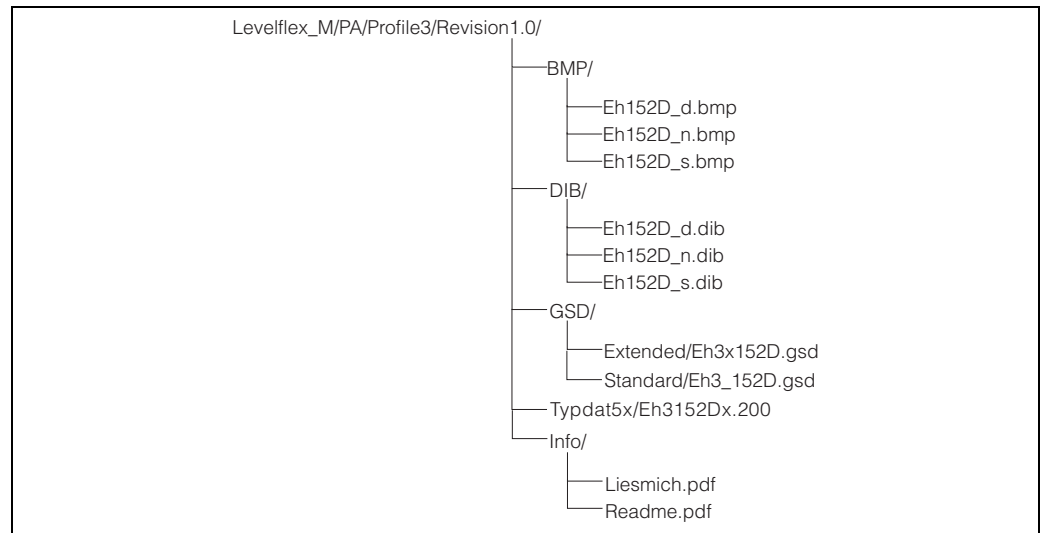
Every device is allocated an identity code by the PROFIBUS User Organisation (PNO). This appears in the device data base file name (.gsd). The Levelflex M has the ID number 0x152D (hex) = 5421 (dec).

Source of supply

- Internet (ftp-Server): ftp://194.196.152.203/pub/communic/gsd/Levellflex_m.EXE
- CD-ROM with GSD files for all E+H devices. Order-Code: 50097200
- GSD library of the PROFIBUS User Organisation (PNO): <http://www.PROFIBUS.com>

Directory structure

The files are organized in the following structure:



- The GSD files in the directory "Extended" are needed for the network design software STEP 7 of the S7-300/400 PLC family.
- The GSD files in the directory "Standard" are used for PLCs, which do not support an identifier format but only an identifier byte (e.g. PLC5 of Allen-Bradley)
- For the network design tool COM ET200 with Siemens S5 instead of an GSD file the Type file "EH_1522x.200" and instead of the BMP files the DIB files have to be used.

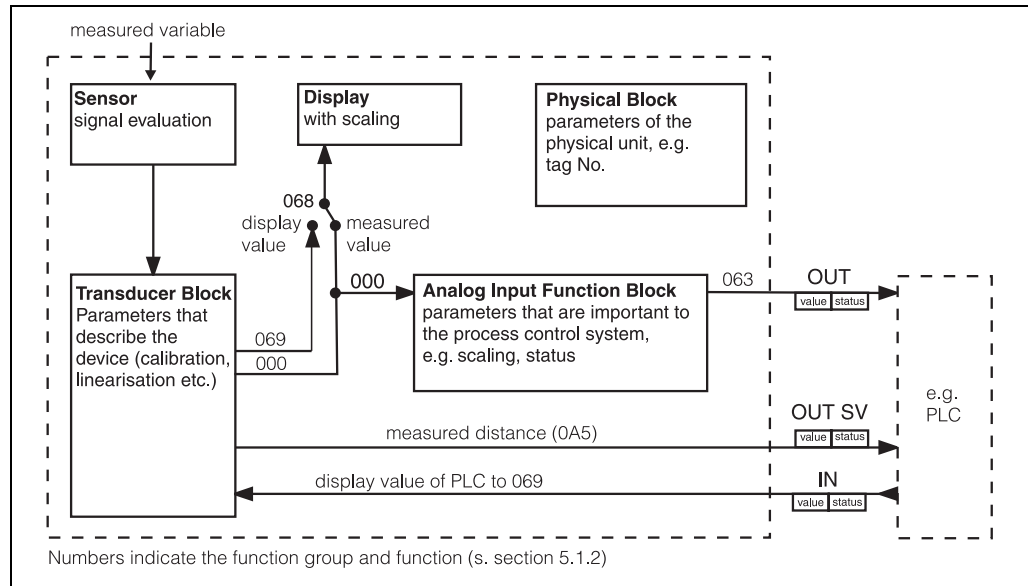
Universal Database File

The PNO also provides an universal database file with the designation PA139700.gsd for devices with one analogue input block. Should this be used instead of the Levelflex M file, then only the process value can be transmitted. The functions secondary and display value are not supported.

The universal profile must also be selected in the function "**Ident number**" (061).

5.5.4 Cyclic data exchange

Block model of the Levelflex M FMP 40



The block model shows, which data are exchanged continuously (i.e. by cyclic data transfer) between the Levelflex M and the PLC. The numbers refer to the function groups and functions (see page 94):

- After linearization and integration in the transducer block the **"measured value" (000)** is transmitted to the Analog-Input Block. There, it may be scaled and checked for limit transgression, and is written out over **"OUT value" (063)** to the PLC.
- The function **"select V0H0" (068)** determines whether at the display of the device in the field for the main measured value the **"measured value" (000)** or the value from the PLC **"display value" (069)** are displayed.

Modules for the cyclic data telegram

For the cyclic data telegram the Prosonic provides the following modules:

1. **Main Process Value**
This is the main measured value scaled by the Analog Input Block (063).
2. **2nd Cyclic Value**
This is the measured distance between the sensor membrane and the product surface (0A5) or the measured temperature (030).
3. **Display Value**
This is a value which can be transferred from the PLC to the Prosonic M in order to be shown on the display.
4. **FREE PLACE**
This module must be applied during configuration (see below), if the 2nd cyclic value or the display value are not to appear in the data telegram.

Configuration of the cyclic data telegram

Use the configuration software of your PLC in order to compose the data telegram from these modules in one of the following ways:

1. **Main value**
In order to transmit the main measured value, select the module **Main Process Value**.
2. **Main value and second cyclic value**
In order to transmit the main value and the second cyclic value (temperature or measured distance), select the modules in the following order: **"Main Process Value", "2nd Cyclic Value", "FREE PLACE"**.
3. **Main value and display value**
In order to transmit the main value and to receive a display value select the modules in the following order: **"Main Process Value", "FREE PLACE", "Display Value"**.
4. **Main value, second cyclic value and display value**
In order to transmit the main value and the second cyclic value and to receive a display value, select the modules in the following order: **"Main Process Value", "2nd Cyclic Value", "Display Value"**.

The exact way of performing the configuration depends on the configuration software of the PLC.

Structure of the input data (Leveflex M → PLC)

The input data are transmitted according to the following structure:

Index Input-Data	Data	Access	Format/Remarks
0, 1, 2, 3	Main value (level)	read	32 bit floating point number (IEEE-754)
4	Status code for main value	read	see "Status codes" (see page 47)
5, 6, 7, 8 (option)	Secondary value (measured distance)	read	32 bit floating point number (IEEE-754)
9 (option)	Status code for secondary value	read	see "Status codes" (see page 47)

Structure of the output data (PLC → Prosonic M)

The output data are transmitted according to the following structure:

Index Output-Data	Data	Access	Format/Remarks
0, 1, 2, 3	Display value	write	32 bit floating point number (IEEE-754)
4	Status code for Display value	write	see "Status codes" (see page 47)

IEEE-745 Floating Point Number

The measured value is transmitted as a IEEE 754 floating point number, whereby

Measured value = $(-1)^S \times 2^{(E-127)} \times (1+F)$

Byte 1								Byte 2							
Bit 7	Bit 6	Bit5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Sign (S)	2^7	2^6	2^5	2^4	2^3	2^2	2^1	2^0	2^{-1}	2^{-2}	2^{-3}	2^{-4}	2^{-5}	2^{-6}	2^{-7}
Exponent (E)								Mantissa (F)							

Byte 3								Byte 4							
Bit 7	Bit 6	Bit5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
2^{-8}	2^{-9}	2^{-10}	2^{-11}	2^{-12}	2^{-13}	2^{-14}	2^{-15}	2^{-16}	2^{-17}	2^{-18}	2^{-19}	2^{-20}	2^{-21}	2^{-22}	2^{-23}
Mantissa (F)															

Example

40 F0 00 00 (hex) = 0100 0000 1111 0000 0000 0000 0000 0000 (bin)
= $(-1)^0 \times 2^{(129 - 127)} \times (1 + 2^{-1} + 2^{-2} + 2^{-3})$
= $1 \times 2^2 \times (1 + 0.5 + 0.25 + 0.125)$
= $1 \times 4 \times 1.875$
= 7.5

Stauts codes

The status codes comprise one byte and have got the following meaning:

Status-Code	Device status	Significance	Primary value	Secondary value
0C Hex	BAD	device error		x
0F Hex	BAD	device error	x	
1F Hex	BAD	out-of-service (target mode)	x	
40 Hex	UNCERTAIN	non-specific (simulation)		x
47 Hex	UNCERTAIN	last usable value (Fail-safe-Mode aktiv)	x	
4B Hex	UNCERTAIN	Substitute set (fail-Safe mode active)	x	
4F Hex	UNCERTAIN	initial value (fail-Safe mode active)	x	
5C Hex	UNCERTAIN	Configuration error (limits not set correctly)	x	
80 Hex	GOOD	OK	x	x
84 Hex	GOOD	Active block alarm (static revision counter incremented)	x	
89 Hex	GOOD	LOW_LIM (alarm active)	x	
8A Hex	GOOD	HI_LIM (alarm active)	x	
8D Hex	GOOD	LOW_LOW_LIM (alarm active)	x	
8E Hex	GOOD	HI_HI_LIM (alarm active)	x	

If a status other than "GOOD" is sent to the device, the display indicates an error.

5.5.5 Acyclic data exchange

The device parameters in the physical block, transducer block and analog input block, as well as the device management can be accessed by a Class 2 PROFIBUS-DP master (e.g. Commuwin II) using the acyclic data services.

Slot/index tables

The device parameters are listed in the following tables. The parameters are accessed via the slot and index number.

The Analog-Input and physical blocks contain standard parameters, block parameters and manufacturer-specific parameters. The transducer block of the Levellflex M is E+H specific.

The parameters of the Analog-Input block are not available when operating via the display or via ToF Tool.

Device Management

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Directory object header		1	0	12	Array of UNSIGNED16	x		constant
Composite list directory entries		1	1	24	Array of UNSIGNED16	x		constant

Analog-Input-Block

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Standard parameters								
Block Data		1	16	20	DS-32*	x		constant
Static revision		1	17	2	UNSIGNED16	x		non-vol.
Device tag		1	18	32	OSTRING	x	x	static
Strategy		1	19	2	UNSIGNED16	x	x	static
Alert key		1	20	1	UNSIGNED8	x	x	static
Target Mode		1	21	1	UNSIGNED8	x	x	static
Mode		1	22	3	DS-37*	x		dynamic non-vol. constant
Alarm summary		1	23	8	DS-42*	x		dynamic
Batch		1	24	10	DS-67*	x	x	static
Gap		1	25					
Block parameters								
Out	V6H2 (Wert) V6H3 (Status)	1	26	5	DS-33*	x		dynamic
PV Scale		1	27	8	Array of FLOAT	x	x	static
Out Scale		1	28	11	DS-36*	x	x	static
Linearisation type		1	29	1	UNSIGNED8	x	x	static
Channel		1	30	2	UNSIGNED16	x	x	static
Gap		1	31					
PV fail safe time		1	32	4	FLOAT	x	x	non-vol.
Fail safe type		1	33	1	UNSIGNED8	x	x	static
Fail safe value		1	34	4	FLOAT	x	x	static
Alarm Hysteresis		1	35	4	FLOAT	x	x	static
Gap		1	36					
HI HI Limit		1	37	4	FLOAT	x	x	static
Gap		1	38					
HI Limit		1	39	4	FLOAT	x	x	static

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Gap		1	40					
LO Limit		1	41	4	FLOAT	x	x	static
Gap		1	42					
LO LO Limit		1	43	4	FLOAT	x	x	static
Gap		1	44-45					
HI HI Alarm		1	46	16	DS-39*	x		dynamic
HI Alarm		1	47	16	DS-39*	x		dynamic
LO Alarm		1	48	16	DS-39*	x		dynamic
LO LO Alarm		1	49	16	DS-39*	x		dynamic
Simulate		1	50	6	DS-51*	x	x	non-vol.
Out unit text		1	51	16	OSTRING	x	x	static

Physical Block

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Standard parameters								
Block Data		0	16	20	DS-32*	x		constant
Static revision		0	17	2	UNSIGNED16	x		non-vol.
Device tag		0	18	32	OSTRING	x	x	static
Strategy		0	19	2	UNSIGNED16	x	x	static
Alert key		0	20	1	UNSIGNED8	x	x	static
Target mode		0	21	1	UNSIGNED8	x	x	static
Mode		0	22	3	DS-37*	x		dynamic non-vol. constant
Alarm summary		0	23	8	DS-42*	x		dynamic
Block parameters								
Software revision		0	24	16	OSTRING	x		constant
Hardware revision		0	25	16	OSTRING	x		constant
Device manufacturer ID		0	26	2	UNSIGNED16	x		constant
Device ID		0	27	16	OSTRING	x		constant
Device serial number		0	28	16	OSTRING	x		constant
Diagnosis		0	29	4	OSTRING	x		dynamic
Diagnosis extension		0	30	6	OSTRING	x		dynamic
Diagnosis mask		0	31	4	OSTRING	x		constant
Diagnosis mask ext.		0	32	6	OSTRING	x		constant
Device certification		0	33	32	OSTRING	x	x	constant
Security locking		0	34	2	UNSIGNED16	x	x	non-vol.
Factory reset		0	35	2	UNSIGNED16		x	non-vol.
Descriptor		0	36	32	OSTRING	x	x	static
Device message		0	37	32	OSTRING	x	x	static
Device instal. date		0	38	8	OSTRING	x	x	static
Gap reserved		0	39					
Ident number select		0	40	1	UNSIGNED8	x	x	static
HW write protection		0	41	1	UNSIGNED8	x	x	dynamic
Gap		0	42-53					
E+H parameters								
error code		0	54	2	UNSIGNED16	x		dynamic
last error code		0	55	2	UNSIGNED16	x	x	dynamic

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Up Down features		0	56	1	OSTRING	x		constant
Up Down control		0	57	1	UNSIGNED8		x	dynamic
Up Down param		0	58	20	OSTRING	x	x	dynamic
Bus address		0	59	1	UNSIGNED8	x		dynamic
Device SW No.		0	60	2	UNSIGNED16	x		dynamic
set unit to bus		0	61	1	UNSIGNED8	x	x	static
input value		0	62	6	FLOAT+U8+U8	x		dynamic
Select Main value		0	63	1	UNSIGNED8	x	x	dynamic
PA profile revision		0	64	16	OSTRING	x		constant

E+H specific level transducer block

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Standard parameters								
Block data		1	130	20	DS-32*	x		constant
Static revision		1	131	2	UNSIGNED16	x		non-vol.
Device tag		1	132	32	OSTRING	x	x	static
Strategy		1	133	2	UNSIGNED16	x	x	static
Alert key		1	134	1	UNSIGNED8	x	x	static
Target mode		1	135	1	UNSIGNED8	x	x	static
Mode		1	136	3	DS-37*	x		dyna- mic/ non-vol./ static
Alarm summary		1	137	8	DS-42*	x		dynamic
E+H parameters								
Measured value	V0H0	1	138	4	FLOAT	x		dynamic
Gap			139					
Tank properties	V0H2	1	140	1	UNSIGNED8	x	x	static
Application parameter	V0H3	1	141	1	UNSIGNED8	x	x	static
Process properties	V0H4	1	142	1	UNSIGNED8	x	x	static
Empty calibration	V0H5	1	143	4	FLOAT	x	x	static
Full calibration	V0H6	1	144	4	FLOAT	x	x	static
Tube diameter	V0H7	1	145	4	FLOAT	x	x	static
Gap			146 - 147					
Output on alarm	V1H0	1	148	1	UNSIGNED8	x	x	static
Gap			149					
Outp. echo loss	V1H2	1	150	1	UNSIGNED8	x	x	static
Ramp %span/min	V1H3	1	151	4	FLOAT	x	x	static
Delay time	V1H4	1	152	2	UNSIGNED16	x	x	static
Safety distance	V1H5	1	153	4	FLOAT	x	x	static
In safety dist.	V1H6	1	154	1	UNSIGNED8	x	x	static
Reset self holding	V1H7	1	155	1	UNSIGNED8	x	x	static
Operating mode	V1H8	1	156	1	UNSIGNED8	x	x	static
Broken probe det.	V1H9	1	157	1	UNSIGNED8	x	x	static
End of probe	V2H0	1	158	1	UNSIGNED8	x	x	static
Probe shortened	V2H1	1	159	1	UNSIGNED8	x	x	static
Probe free	V2H2	1	160	1	UNSIGNED8	x	x	static
Probe length	V2H3	1	161	4	FLOAT	x	x	static
Probe length setup	V2H4	1	162	1	UNSIGNED8	x	x	static

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Gap		1	163-167					
Level/ullage	V3H0	1	168	1	UNSIGNED8	x	x	static
Linearisation mode	V3H1	1	169	1	UNSIGNED8	x	x	static
Customer unit	V3H2	1	170	1	UNSIGNED16	x	x	static
Table no.	V3H3	1	171	1	UNSIGNED8	x	x	static
Input level	V3H4	1	172	4	FLOAT	x	x	static
Input volume	V3H5	1	173	4	FLOAT	x	x	static
Max. volume	V3H6	1	174	4	FLOAT	x	x	static
Cylinder vessel	V3H7	1	175	4	FLOAT	x	x	static
Gap		1	176-177					
Selection	V4H0	1	178	1	UNSIGNED8	x	x	static
check distance	V4H1	1	179	1	UNSIGNED8	x	x	static
Range of mapping	V4H2	1	180	4	FLOAT	x	x	static
Mapping rec start	V4H3	1	181	1	UNSIGNED8	x	x	static
Pres. map. dist.	V4H4	1	182	4	FLOAT	x		dynamic
Delete mapping	V4H5	1	183	1	UNSIGNED8	x	x	static
Echo quality	V4H6	1	184	1	UNSIGNED8	x		dynamic
Offset meas dist	V4H7	1	185	4	FLOAT	x	x	static
Output damping	V4H8	1	186	4	FLOAT	x	x	static
High blocking dist.	V4H9	1	187	4	FLOAT	x	x	static
Bus address	V5H0	1	188	1	UNSIGNED8	x		dynamic
Ident nr sel	V5H1	1	189	1	UNSIGNED8	x	x	static
Set unit to bus	V5H2	1	190	1	UNSIGNED8	x	x	static
AI out value	V5H3	1	191	4	FLOAT	x		dynamic
AI out status	V5H4	1	192	1	UNSIGNED8	x		dynamic
Simulation type	V5H5	1	193	1	UNSIGNED8	x	x	static
Simulation value	V5H6	1	194	4	FLOAT	x	x	static
2nd cyclic value	V5H7	1	195	1	UNSIGNED8	x	x	static
Select Main Value	V5H8	1	196	1	UNSIGNED8	x	x	static
Input value	V5H9	1	197	4	FLOAT	x		dynamic
Gap		1	198					
Display contrast	V6H1	1	199	1	UNSIGNED8	x	x	static
Language	V6H2	1	200	1	UNSIGNED8	x	x	static
Back to home	V6H3	1	201	2	INT16	x	x	static
Format display	V6H4	1	202	1	UNSIGNED8	x	x	static
No. decimals	V6H5	1	203	1	UNSIGNED8	x	x	static
Sep. character	V6H6	1	204	1	UNSIGNED8	x	x	static
Display test	V6H7	1	205	1	UNSIGNED8	x	x	static
Gap		1	206 - 207					
Gap		1	218-227					
Actual alarm	V9H0	1	228		STRUCT	x		dynamic
Last alarm	V9H1	1	229		STRUCT	x		dynamic
Clear last alarm	V9H2	1	230	1	UNSIGNED8	x	x	static
Reset	V9H3	1	231	2	UNSIGNED16	x	x	static
Operating code	V9H4	1	232	2	UNSIGNED16	x	x	static
Measured distance	V9H5	1	233	4	FLOAT	x		dynamic
Measured level	V9H6	1	234	4	FLOAT	x		dynamic
Gap		1	235					
Application parameter	V9H8	1	236	1	UNSIGNED8	x		dynamic

Parameter	E+H Matrix (CW II)	Slot	Index	Size [bytes]	Type	Read	Write	Storage Class
Gap		1	237					
Tag no.	VAH0	1	238		STRING	x		const
Profile revision	VAH1	1	239		STRING	x	x	static
Version string	VAH2	1	240		STRING	x		const
Gap		1	241					
Serial no.	VAH4	1	242		STRING	x	x	static
Distance unit	VAH5	1	243	2	UNSIGNED16	x	x	static
Gap		1	244 - 245					
Download mode	VAH8	1	246	1	UNSIGNED8	x	x	static

Data strings

In der Slot/Index table some data types, e.g. DS-33 are marked by an asterisk. These are data strings according to the PROFIBUS-PA specifications part 1, Version 3.0. They contain several elements, which are addressed by an additional subindex. The following table gives an example.

Data type	Subindex	Typ	Size [bytes]
DS-33	1	FLOAT	4
	5	UNSIGNED8	1

5.5.6 Parameter access via Commuwin II

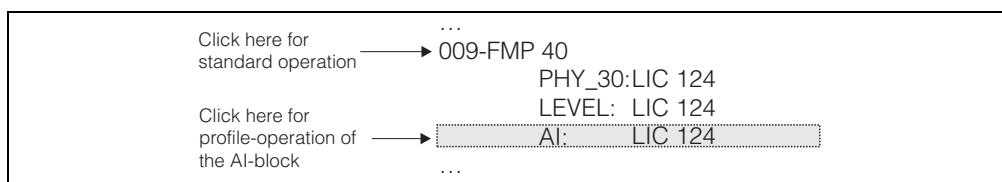
The block parameters can be accessed by a PROFIBUS-DP Class 2 master, for example, Commuwin II. Commuwin II runs on an IBM-compatible computer or laptop. The computer must be equipped with a PROFIBUS interface, i.e. PROFIBOARD for PCs and PROFICARD for laptops. During the system integration, the computer is registered as a Class 2 master.

Connection

- Profiboard for connection to a PC
- Proficard for connection to a Laptop

Generating the device list

- The PA-DPV1 server must be installed. The connection to Commuwin II is opened selecting the PA-DPV1 server in the "Open connection" function in the "Connect" menu. The empty device list appears.
- The function "Display with tags" in the "Connect" menu generates the live list with measuring point tags.
- Two operation modes are possible:



- The **E+H standard operation** is selected by clicking on the device name
- The **profile operation** is selected by clicking on the tag for the appropriate block (e.g. "AI: LIC 124" for the Analog-Input block of the Levelflex M).
- The settings are entered in the device menu.

Device menu

The device menu allows matrix or graphical operation to be selected.

- In the case of **matrix operation**, the device or profile parameters are displayed in a matrix. For the standard operation this is the E+H standard matrix. For the profile operation this is the matrix of the selected block. A parameter can be changed when the corresponding matrix field is selected.
- In the case of **graphical operation**, the operating sequence is shown in a series of templates with parameters. For profile operation, the pictures Diagnosis, Scaling, Simulation and Block are of interest.

The meaning and the parametrization of the parameters is described in Chapter 6.



Note!

The Levelflex M can also be operated locally using the keys (see page 36). If operation is prevented by the keys being locked locally, parameter entry via communication is not possible either.



Note!

Further information on Commuwin II is given in the Operating Manual BA 124F/00/a2.

5.5.7 Parameter access via ToF Tool

The ToF Tool is a graphical operating software for instruments from Endress+Hauser that operate based on the time-of-flight principle. It is used to support commissioning, securing of data, signal analysis and documentation of the instruments. It is compatible with the following operating systems: Win95, Win98, WinNT4.0, Win2000 and Windows XP.

The ToF Tool supports the following functions:

- Online configuration of transmitters
- Signal analysis via envelope curve
- Loading and saving of instrument data (Upload/Download)
- Documentation of measuring point



Note!

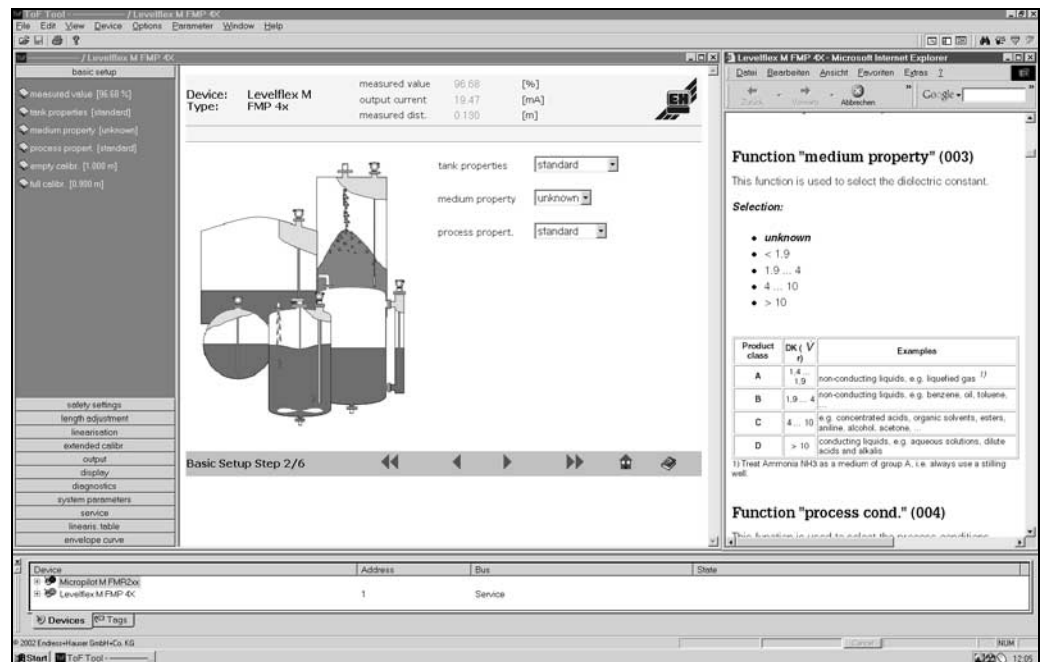
The parameters of the Analog-Input block are presently not accessible via ToF Tool.



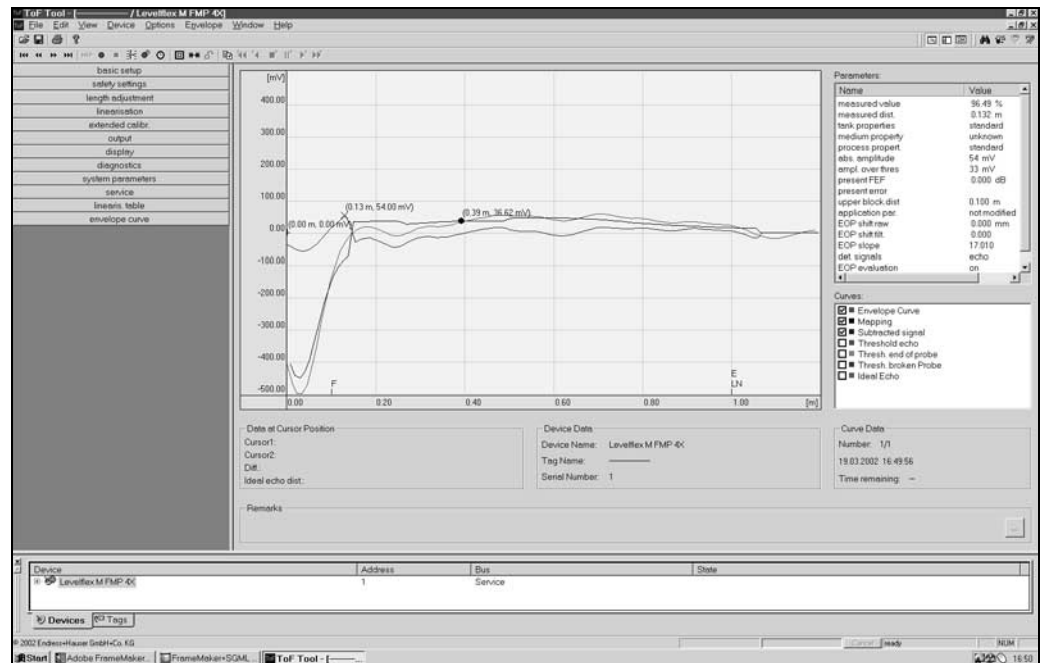
Note!

Further information you may find on the CD-ROM, which is enclosed to the instrument.

Menu-guided commissioning



Signal analysis via envelope curve:



Connection options:

- Service-interface with adapter FXA 193 (see page 41)
- Proficard for connection to a Laptop
- Proficard for connection to a PC



Note!

The Levelflex M can also be operated locally using the keys. If operation is prevented by the keys being locked locally, parameter entry via communication is not possible either.

5.5.8 Scaling of the output data

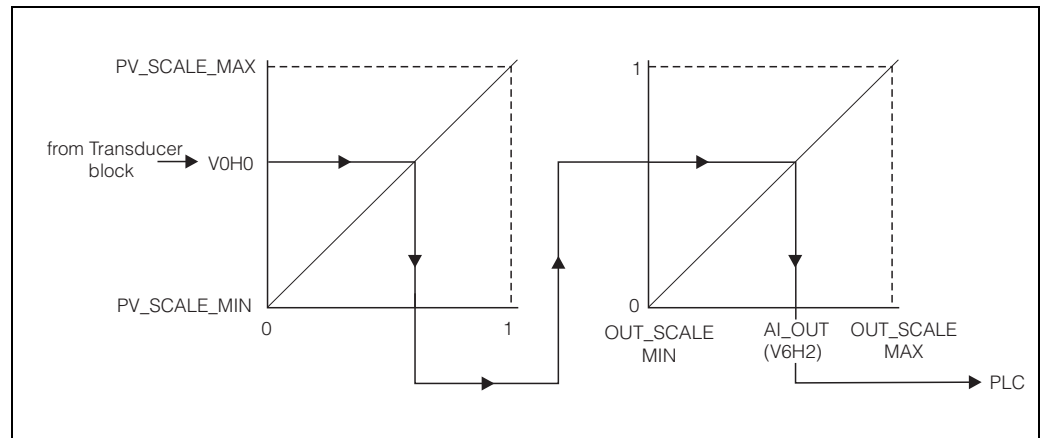
The on-site display and the digital output are working independently of each other.

On-site display

The on-site display always displays the main value V0H0 directly from the Transducer Block.

Digital output

For the digital output this value is rescaled in two steps:



1. In a first step, the main value is mapped to the interval [0;1]. PV_SCALE_MIN and PV_SCALE_MAX determine the limits of this mapping.
2. In a second step, the interval [0,1] is mapped to the interval [OUT_SCALE_MIN, OUT_SCALE_MAX]. The value resulting from this mapping is transferred via V6H2 to the PLC.



Note!

The scaling of the output value is required by the Profibus profiles. It prevents uncontrolled jumps of the output value when one changes the unit of the measuring value in the Transducer Block. If units are changed, PV_SCALE_MIN and PV_SCALE_MAX automatically adapt themselves in such a way that the output value remains unchanged. Only after confirming the change by the **"Set unit to bus" (062)** function, OUT_SCALE_MIN is set equal to PV_SCALE_MIN and OUT_SCALE_MAX equal to PV_SCALE_MAX. Thereby the new unit also becomes effective at the output.



Caution!

If a linearisation has been carried out, it must be confirmed by the **"Set unit to bus" (062)** function in order to become effective at the digital output.

6 Commissioning

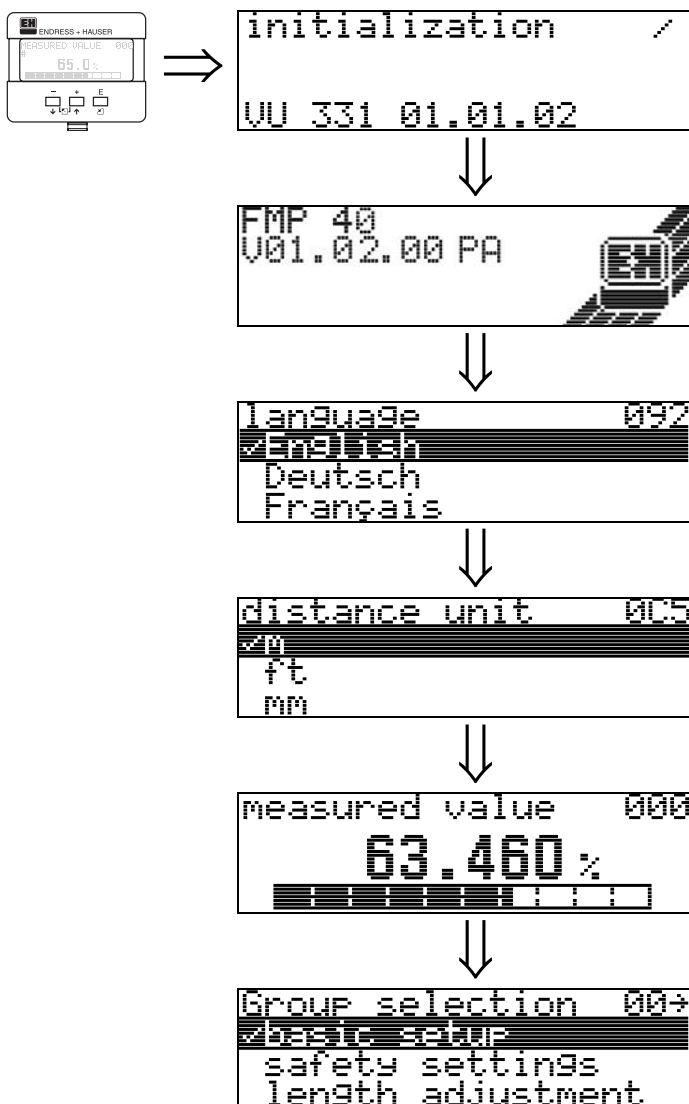
6.1 Function check

Make sure that all final checks have been completed before you start up your measuring point:

- Checklist “Post installation check” (see page 28 ff.).
- Checklist “Post connection check” (see page 32 ff.).

6.2 Switching on the measuring device

When the instrument is switched on for the first time, the following messages appear on the display:



After 5 s, the following message appears

After 5 s or after you have pressed **[E]** the following message appears

Select the language
(this message appears the first time the instrument is switched on)

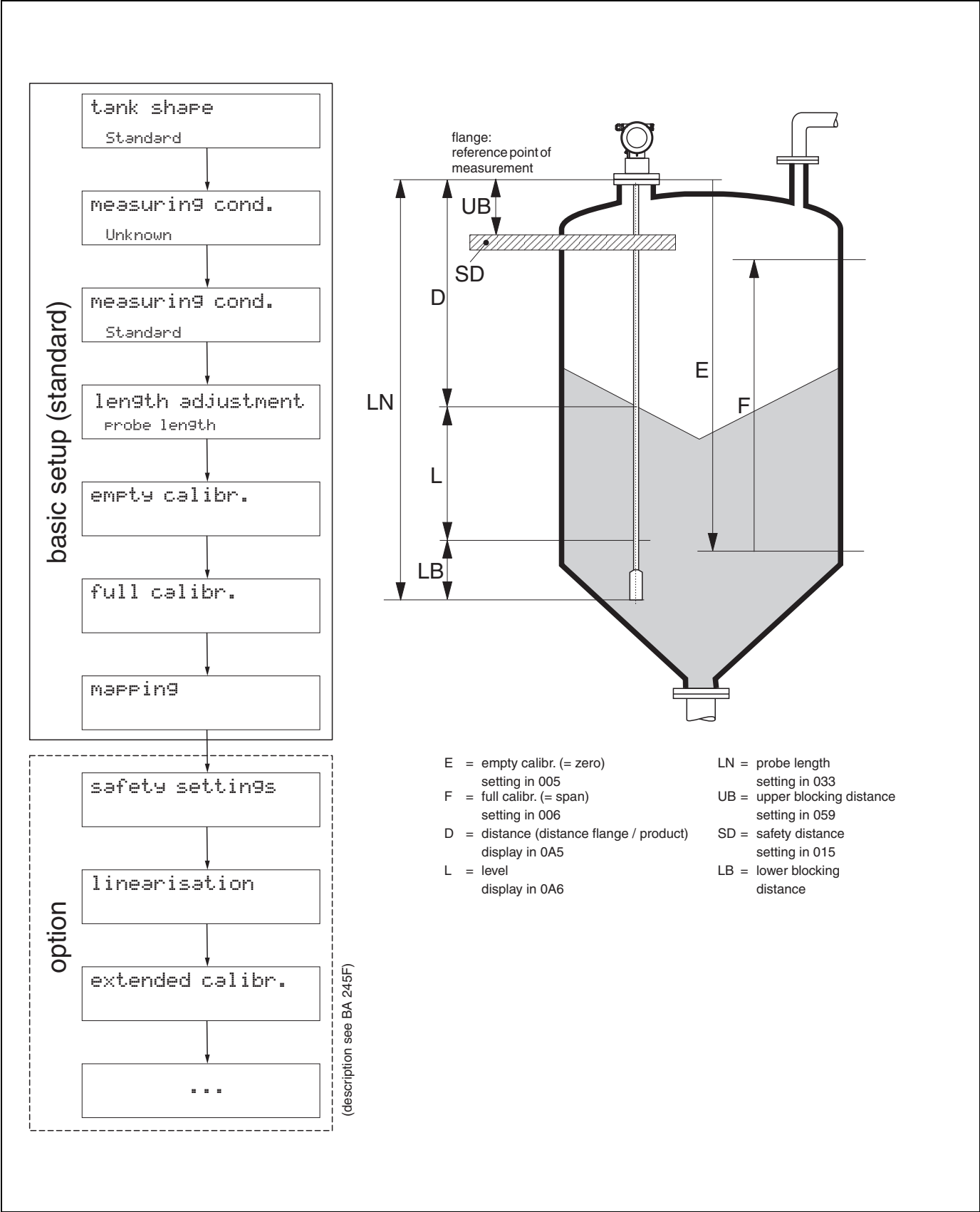
Select the basic unit
(this message appears the first time the instrument is switched on)

The current measured value is displayed

After **[E]** is pressed, you reach the group selection.

This selection enables you to perform the basic setup

6.3 Basic Setup






The basic setup is sufficient for successful commissioning in most applications.

**Note!**

The Levelflex M allows to check for broken probe. On delivery, this function is switched off, because otherwise shortening of the probe would be mistaken for a broken probe. If you want to check the probe for a crack select the **"broken probe det" (019)** function in the **"safety settings" (01)** function group.

Complex measuring operations necessitate additional functions that the user can use to customise the Levelflex as necessary to suit his specific requirements. The functions available to do this are described in detail in the BA 245F.

Comply with the following instructions when configuring the functions in the **"basic setup" (00)**:

- Select the functions as described on page 33.
- Certain functions (e.g. starting an interference echo mapping (053)) prompt you to confirm your data entries. Press  or  to select **"YES"** and press  to confirm. The function is now started.
- If you do not press a key during a configurable time period (→ function group "display (09)"), an automatic return is made to the home position (measured value display).

**Note!**

- The instrument continues to measure while data entry is in progress, i.e. the current measured values are output via the signal outputs in the normal way.
- If the envelope curve mode is active on the display, the measured values are updated in a slower cycle time. Thus, it is advisable to leave the envelope curve mode after the measuring point has been optimised.
- If the power supply fails, all preset and parameterised values remain safely stored in the EEPROM.

**Caution!**

All functions are described in detail, as is the overview of the operating menu itself, in the manual **"Description of the instrument functions – BA 245F"**, which is a separate part of this operating manual.

6.4 Basic Setup with the VU 331

Function "measured value" (000)

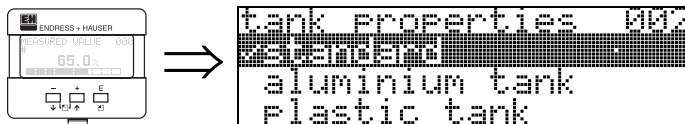


This function displays the current measured value in the selected unit (see "**customer unit**" (042) function). The number of digits after decimal point can be selected in the "**no.of decimals**" (095) function.

6.4.1 Function group "basic setup" (00)



Function "tank properties" (002)



This function is used to select the tank properties.

Selection:

- **standard**
- aluminium tank
- plastic tank
- bypass / pipe
- coax probe
- concrete wall

standard

The "**standard**" option is recommended for normal containers for rod and rope probes.

aluminium tank

The "**aluminium tank**" option is designed especially for high aluminium silos that cause an increased level of noise when empty. This option is only useful for probes longer than (> 4 m). For short probes (< 4 m) select the "**standard**" option.

Note!

If "**aluminium tank**" is selected, the device calibrates of its own accord when first filled, depending on the medium's properties. Slope errors can, therefore, occur when beginning the first filling procedure.

plastic tank

Select the "**plastic tank**" option when installing probes in wood or plastic containers **without** metallic surfaces at the process connection (see installation in plastic containers). When using a metallic surface at the process connection, the "**standard**" option is sufficient.

Note!

In principle the employment of a metallic surface area should be preferred at the process connection!

bypass / pipe

The **"bypass / pipe"** option is designed especially for the installation of probes in a bypass or a stilling well.

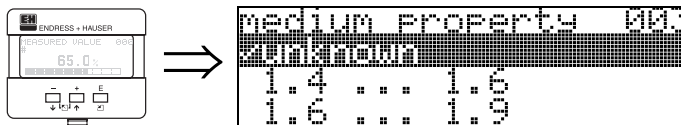
coax probe

Select the **"coax probe"** option when using a coaxial probe. When this setting is made, the evaluation is adapted to the high sensitivity of the coax probe. This option should, therefore, **not** be selected when using rope or rod probes.

concrete wall

The **"concrete wall"** option takes into account the signal-damping property of concrete walls when mounting with < 1 m distance to the wall.

Function "medium property" (003)



This function is used to select the dielectric constant.

Selection:

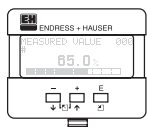
- **unknown**
- 1.4 ... 1.6 (for coaxial probe only)
- 1.6 ... 1.9
- 1.9 ... 2.5
- 2.5 ... 4.0
- 4.0 ... 7.0
- > 7.0

Media group	DK (εr)	Typical bulk solids	Typical liquids	Typical measuring range
0	unknown			
1	1,4 ... 1,6		– Liquefied gases, e.g. N ₂ , CO ₂	4 m, coax probe only
2	1,6 ... 1,9	– Plastic granules – White lime, special cement – Sugar	– Liquefied gas, e.g. propane – Solvents – Frigen / freon – Palm oil	25 m
3	1,9 ... 2,5	– Portland cement, plasters	– Mineral oils, fuels	30 m
4	2,5 ... 4	– Cereals, seeds – Ground stone – Sand	– Benzene, styrene, toluene – Furan – Naphthalene	35 m
5	4 ... 7	– Naturally-moist (ground) stone, ores – Salt	– Chlorobenzene, chloroform – Cellulose spray – Isocyanate, aniline	35 m
6	> 7	– Metal powder	– Aqueous solutions – Alcohols – Ammoniac	35 m

The lower group applies to very loose or loosened bulk solids.

Reduction of the max. possible measuring range by means of:

- extremely loose surfaces of bulk solids, e.g. bulk solids with low piled density when filled pneumatically.
- Build-up, primarily of moist products.



Function "process propert." (004)

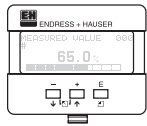


Use this function to adapt the device reaction to the filling speed in the tank. The setting impacts on an intelligent filter.

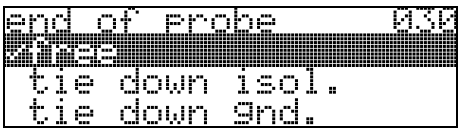
Selection:

- standard
- fast change
- slow change
- test:no filter

Selection:	standard	fast change	slow change	test:no filter
Application:	For all normal applications, bulk solids and fluids at low to medium filling speed and sufficiently large tanks.	Small tanks, primarily with fluids, at high filling speeds.	Applications with strong surface movement, e.g. caused by stirrer, primarily large tanks with slow to medium filling speed.	Shortest reaction time: <ul style="list-style-type: none">• For test purposes• Measurement in small tanks at high filling speeds, if "rapid change" setting is too slow.
2-wire electronics:	Dead time: 4 s Rise time: 18 s	Dead time: 2 s Rise time: 5 s	Dead time: 6 s Rise time: 40 s	Dead time: 1 s Rise time: 0 s
4-wire electronics:	Dead time: 2 s Rise time: 11 s	Dead time: 1 s Rise time: 3 s	Dead time: 3 s Rise time: 25 s	Dead time: 0,7 s Rise time: 0 s



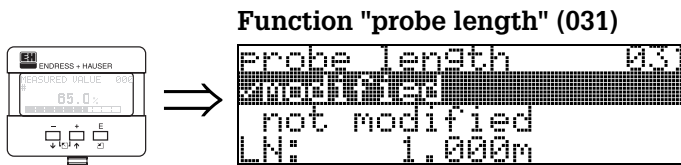
Function "end of probe" (030)



Use this function to select the polarity of the probe end signal. If the probe end is uncovered or in an insulated attachment, there is a negative probe end signal. The signal from the probe end is positive if the attachment is grounded.

Selection:

- free
- tie down isol.
- tie down gnd.



Use this function to select whether the probe length was changed after factory calibration. Only then is it necessary to enter or correct the probe length.

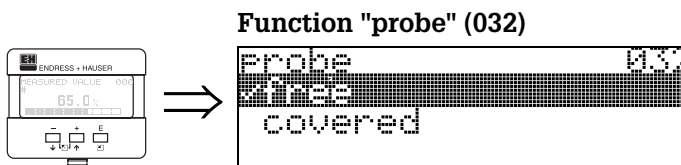
Selection:

- not modified
- modified



Note!

If "modified" was selected in the "probe length" (031) function, the probe length is defined in the next step.

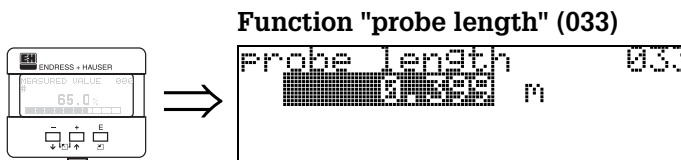


Use this function to select whether the probe is at the time of the commissioning uncovered or covered.

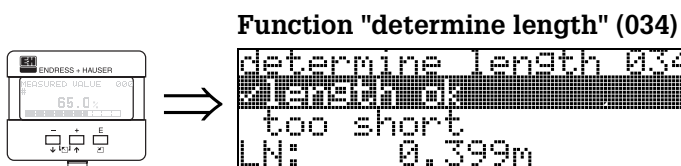
If the probe is uncovered, the Levelflex can determine the probe length automatically "determine length" (034). function. If the probe is covered, a correct entry is required in the "probe length" (033) function

Selection:

- free
- covered



Use this function, the probe length can be entered manually.

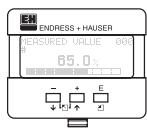


Use this function, the probe length can be determined automatically.

Selection:

- length ok
- too short
- too long

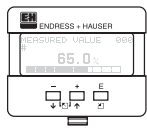
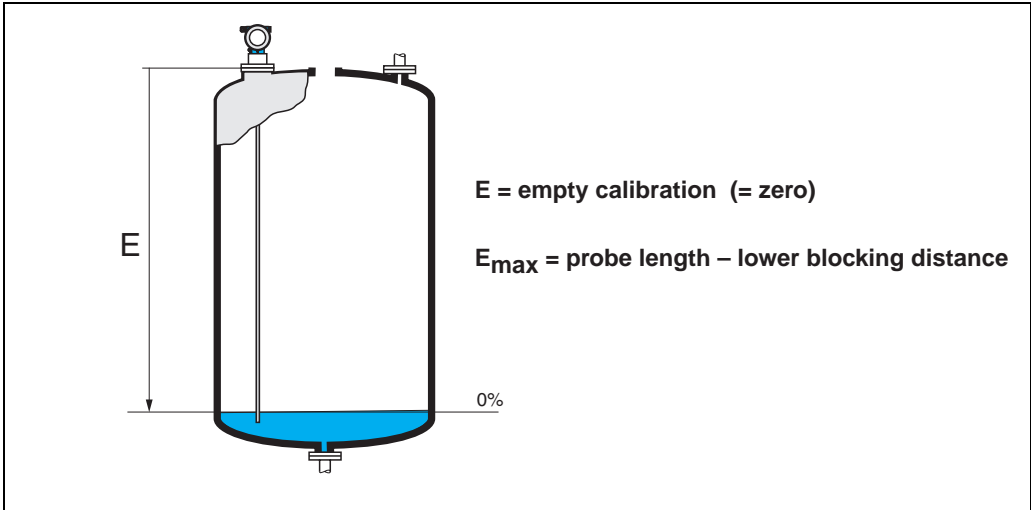
After selection "length too short" or "length too long", the calculation of the new value need approx. 10 s.



Function "empty calibr." (005)

empty calibr. 005
[REDACTED] m
distance Process
conn. to min. level

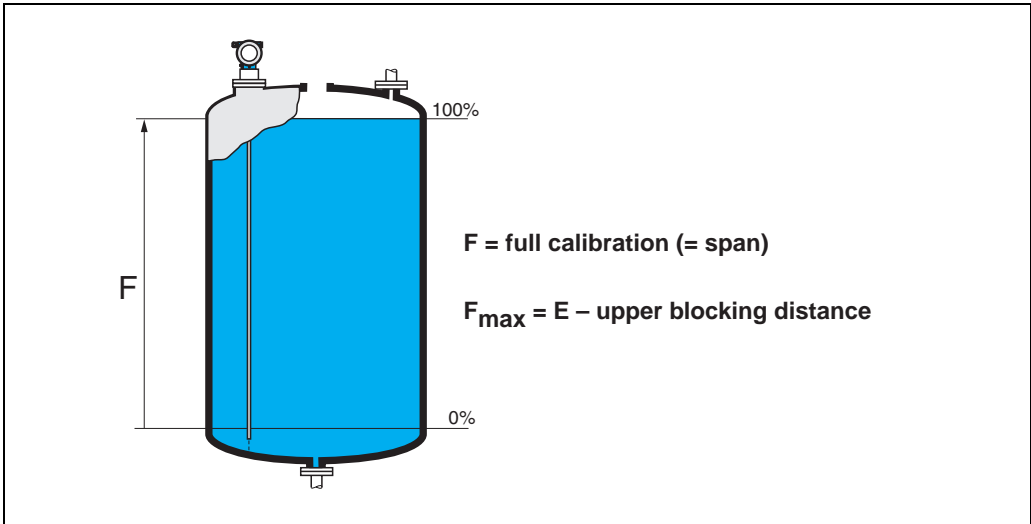
This function is used to enter the distance from the flange (reference point of the measurement) to the minimum level (=zero).



Function "full calibr." (006)

full calibr. 006
[REDACTED] m
span

This function is used to enter the distance from the minimum level to the maximum level (=span).




Note!

The usable measuring range lies between the lower and the upper blocking distance. The values for empty distance (E) and span (F) can be set independently of this.

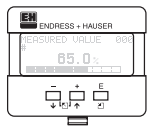
Blocking distance and measuring range for $D_k \geq 1.6$ (1.4 for coax probes):

FMP 40	LN [m]"/		UB [m]"/	LB [m]"/
	min	max	min	min
Rope probe	1/40	35/1378	0,2/8 ¹⁾	0,25/10
6 mm rod probe	0,3/12	2/80	0,2/8 ¹⁾	0,05/2
16 mm rod probe	0,3/12	4/178	0,2/8 ¹⁾	0,05/2
Coax probe	0,3/12	4/178	0/0	0,05/2

1) The indicated blocking distances are prearised. At media with $DK > 7$, the upper blocking distance UB can be reduced for rod- and rope probes on 0.1m. The upper blocking distance UB can be entered manually.


Note!

Within the upper and lower blocking distance, a reliable measurement can not be guaranteed.

**Display (008)**

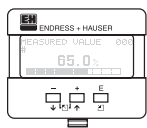
```

dist./meas.value 008
dist: 0.180 m
m.val 102.46 %

```

The **distance** measured from the reference point to the product surface and the **meas. value** calculated with the aid of the empty adjustment are displayed. Check whether the values correspond to the actual meas. value or the actual distance. The following cases can occur:

- Distance correct – meas. value correct -> continue with the next function, **"check distance" (051)**
- Distance correct – meas. value incorrect -> Check **"empty calibr." (005)**
- Distance incorrect – meas. value incorrect -> continue with the next function, **"check distance" (051)**

**Function "check distance" (051)**

```

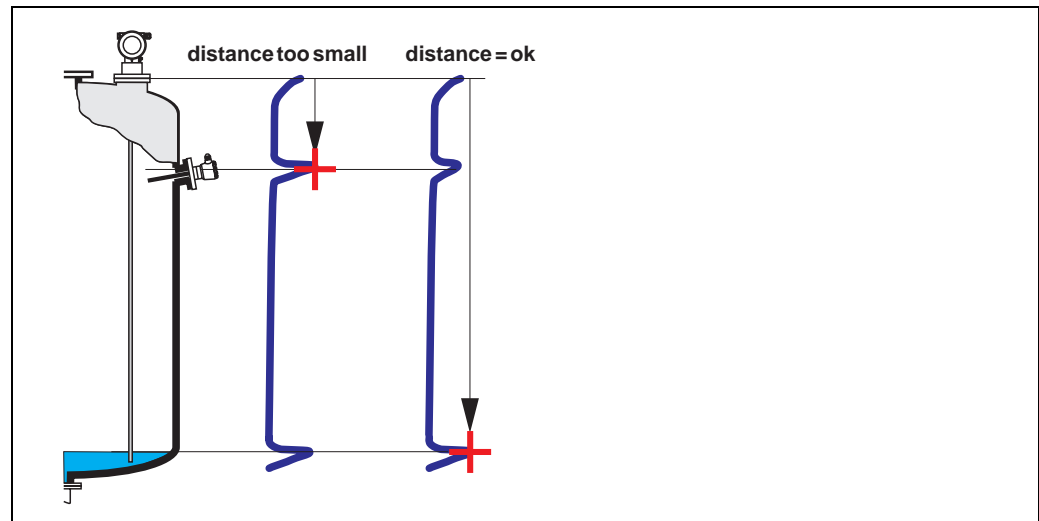
check distance 051
dist. unknown
manual
probe free

```

This function triggers the mapping of interference echoes. To do so, the measured distance must be compared with the actual distance to the product surface. The following options are available for selection:

Selection:

- distance = ok
- dist. too small
- dist. too big
- dist. unknown
- **manual**
- probe free

**distance = ok**

Use this function at part-covered probe. Choosing function **"manual"** or **"probe free"** at free probe.

- mapping is carried out up to the currently measured echo
- The range to be suppressed is suggested in the **"range of mapping (052)"** function. Anyway, it is wise to carry out a mapping even in this case.

**Note!**

At free probe, the mapping should be confirmed with the choice **"probe free"**.

dist. too small

- At the moment, an interference is being evaluated
- Therefore, a mapping is carried out including the presently measured echoes
- The range to be suppressed is suggested in the "**range of mapping (052)**" function.

dist. too big

- This error cannot be remedied by interference echo mapping
- Check the application parameters (002), (003), (004) and "**probe length.**" (031)

dist. unknown

If the actual distance is not known, no mapping can be carried out.

manual

A mapping is also possible by manual entry of the range to be suppressed. This entry is made in the "**range of mapping (052)**" function.



Caution!

The range of mapping must end 0.3 m (20") before the echo of the actual level. In case of empty vessel it is possible to make a map over the whole probe length.

probe free

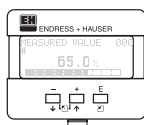
If the probe is uncovered, mapping is carried out along the whole probe length.



Caution!

Only begin mapping in this function if the probe is safely uncovered. Otherwise, the device will not make correct measurements.

Function "range of mapping" (052)

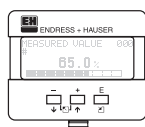


```
range of mapping 052
0.000 m
input of
mapping range
```

This function displays the suggested range of mapping. The reference point is always the reference point of the measurement (see page 58 ff.). This value can be edited by the operator.

For manual mapping, the default value is 0,3 m.

Function "start mapping" (053)

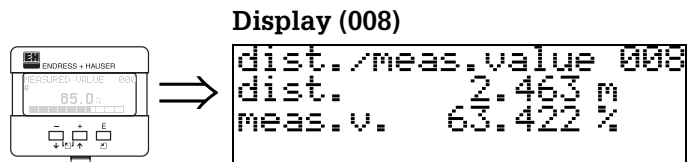


```
start mapping 053
off
on
```

This function is used to start the interference echo mapping up to the distance given in "**range of mapping**" (052).

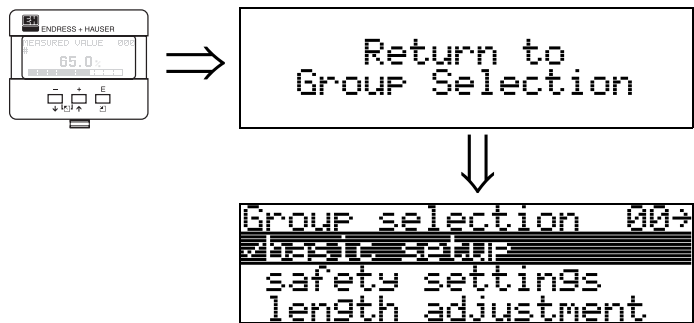
Selection:

- **off:** no mapping is carried out
- **on:** mapping is started



The distance measured from the reference point to the product surface and the meas. value calculated with the aid of the empty alignment are displayed again. Check whether the values correspond to the actual meas. value or the actual distance. The following cases can occur:

- Distance correct – meas. value correct -> basic setup completed
- Distance incorrect – meas. value incorrect -> a further interference echo mapping must be carried out "**check distance**" (051).
- Distance correct – meas. value incorrect -> check "**empty calibr.**" (005)



After 3 s, the following message appears

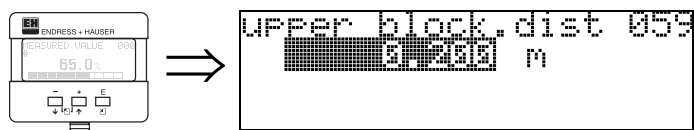


Note!
After the basic setup, an evaluation of the measurement with the aid of the envelope curve ("**envelope curve**" (0E) function group) is recommended.

6.5 Blocking distnace



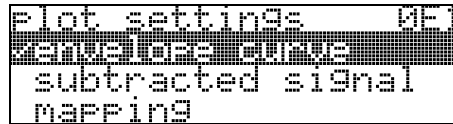
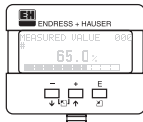
Note!
At installation in high nozzles, please the blocking distance in the function "**upper block.dist**" (059) newly enter!



6.6 Envelope curve with VU 331

After the basic setup, an evaluation of the measurement with the aid of the envelope curve ("envelope curve" (0E) function group) is recommended.).

6.6.1 Function "plot settings" (0E1)



Here you can select which information is shown on the display:

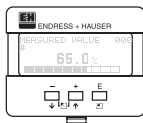
- **envelope curve**
- subtracted signal
- mapping

6.6.2 Function "recording curve" (0E2)

Function "recording curve" (09B)

This function determines whether the envelope curve is read as:

- **single curve**
- or
- cyclic.

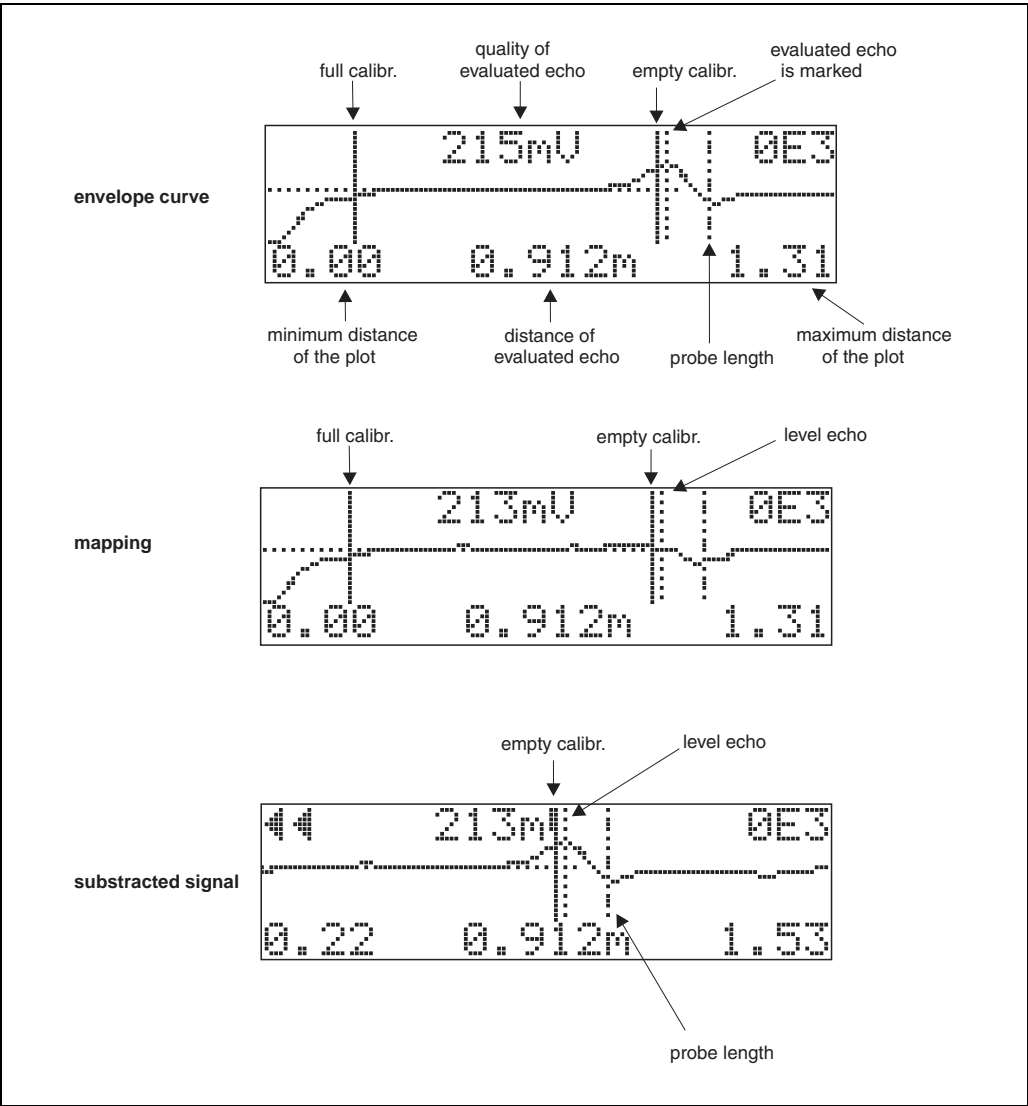


Note!

If the envelope curve mode is active on the display, the measured values are updated in a slower cycle time. Thus, it is advisable to leave the envelope curve mode after the measuring point has been optimised.

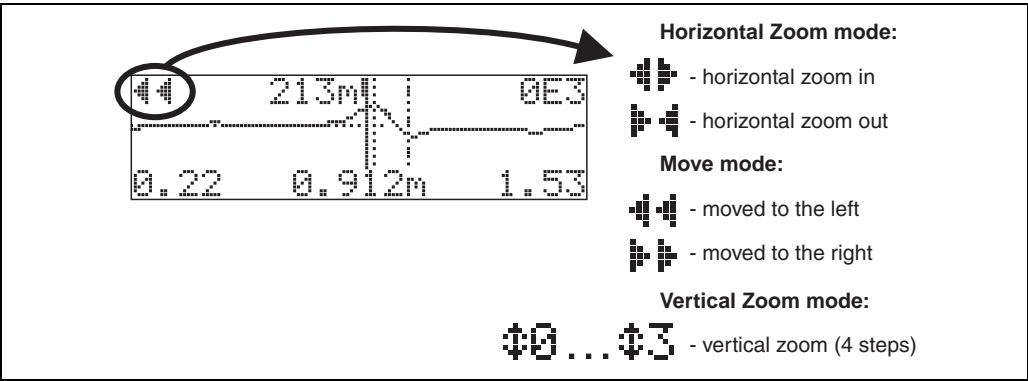
6.7 Function "envelope curve display" (0E3)

You can obtain the following information from the envelope curve display in this function:



Navigation in the envelope curve display

Using navigation, the envelope curve can be scaled horizontally and vertically and shifted to the left or the right. The active navigation mode is indicated by a symbol in the top left hand corner of the display.

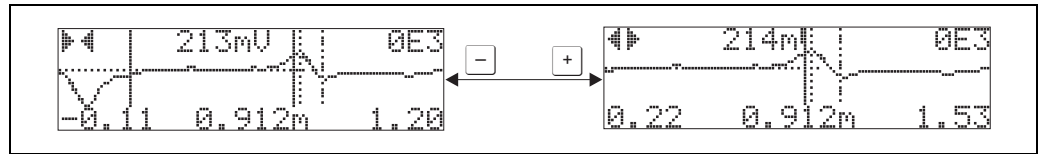


Horizontal-Zoom-Modus

Press \leftarrow or \rightarrow , to switch to the envelope curve navigation. You are then in Horizontal Zoom mode. Either \leftarrow or \rightarrow is displayed.

You now have the following options:

- \leftarrow increases the horizontal scale.
- \rightarrow decreases the horizontal scale.

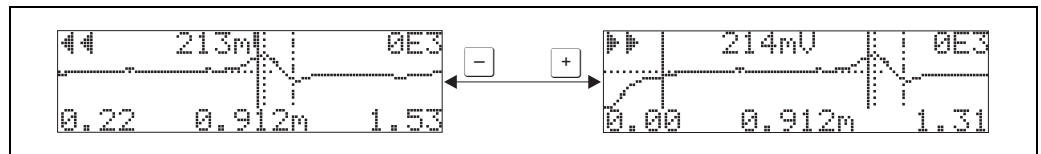


Move-Modus

Then press \leftarrow to switch to Move mode. Either \leftarrow or \rightarrow is displayed.

You now have the following options:

- \leftarrow shifts the curve to the right.
- \rightarrow shifts the curve to the left.



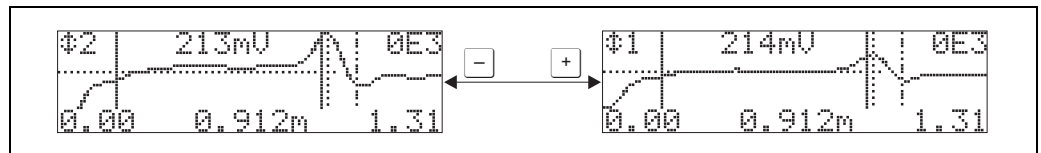
Vertical-Zoom-Modus

Press \leftarrow once more to switch to Vertical Zoom mode $\Phi 1$ is displayed.

You now have the following options:

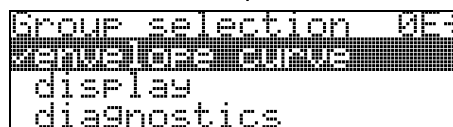
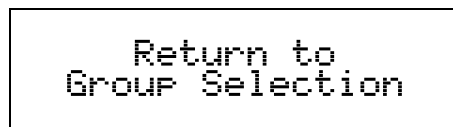
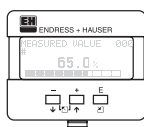
- \leftarrow increases the vertical scale.
- \rightarrow decreases the vertical scale.

The display icon shows the current zoom factor ($\Phi 0$ to $\Phi 3$).



Exiting the navigation

- Press \leftarrow again to run through the different modes of the envelope curve navigation.
- Press \leftarrow and \rightarrow to exit the navigation. The set increases and shifts are retained. Only when you reactivate the "recording curve" (0E2) function does the Levelflex use the standard display again.



After 3 s, the following message appears

6.8 Basic Setup with the ToF Tool

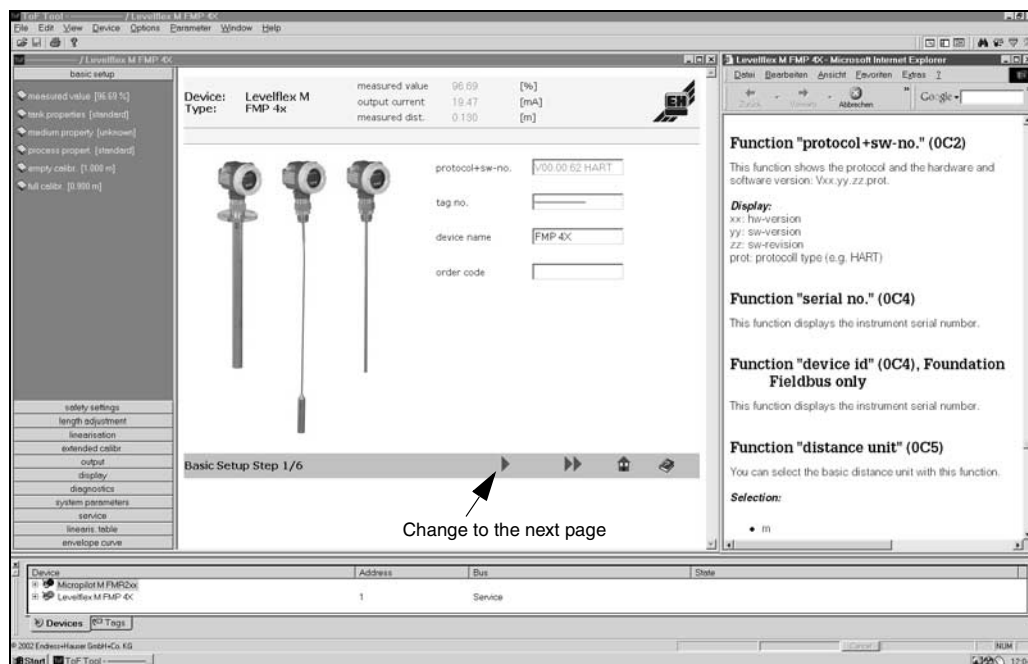
To carry out the basic setup with the ToF Tool operating program, proceed as follows:

- Start the ToF Tool operating program and establish a connection
- Select the "**basic setup**" function group in the navigation bar

The following display appears on the screen:

Basic Setup step 1/6:

- Status image
- Enter the measuring point description (TAG number).

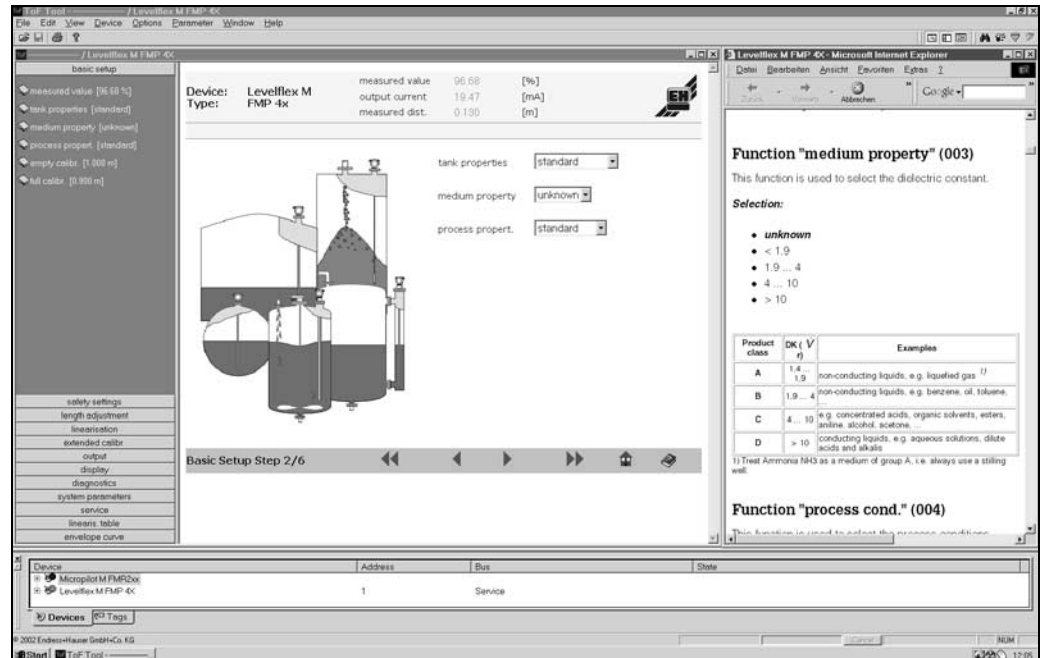


Note!

- Each parameter that is changed must be confirmed with the **RETURN** key!
- The "**Next**" button moves you to the next screen display:

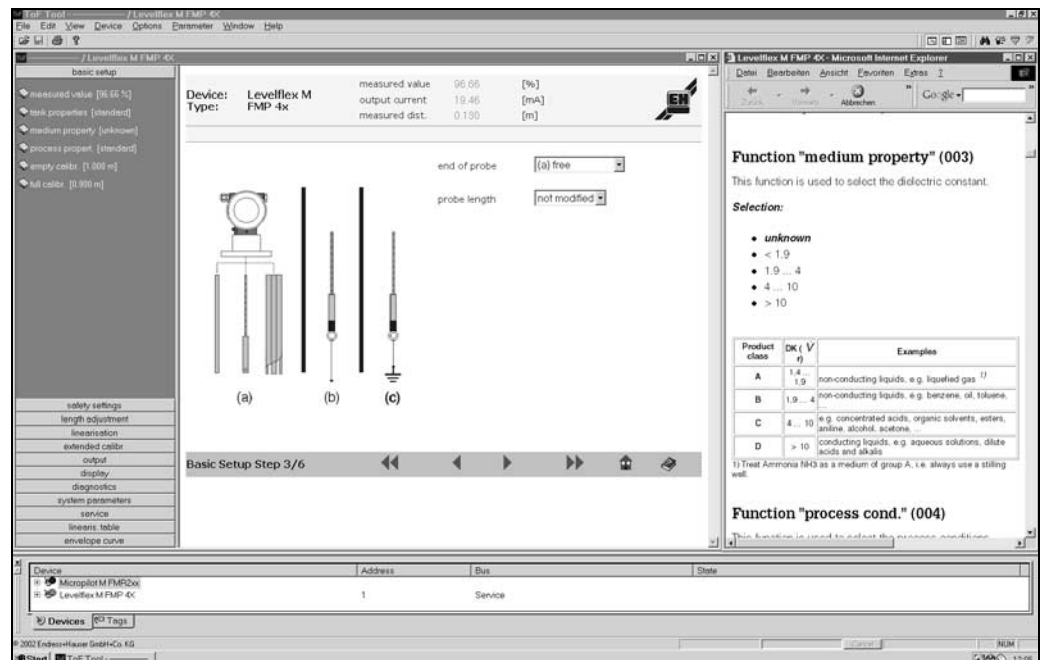
Basic Setup step 2/5:

- Enter the application parameters:
 - tank properties (for a description, see page 60)
 - medium properties (for a description, see page 61)
 - process properties (for a description, see page 62)



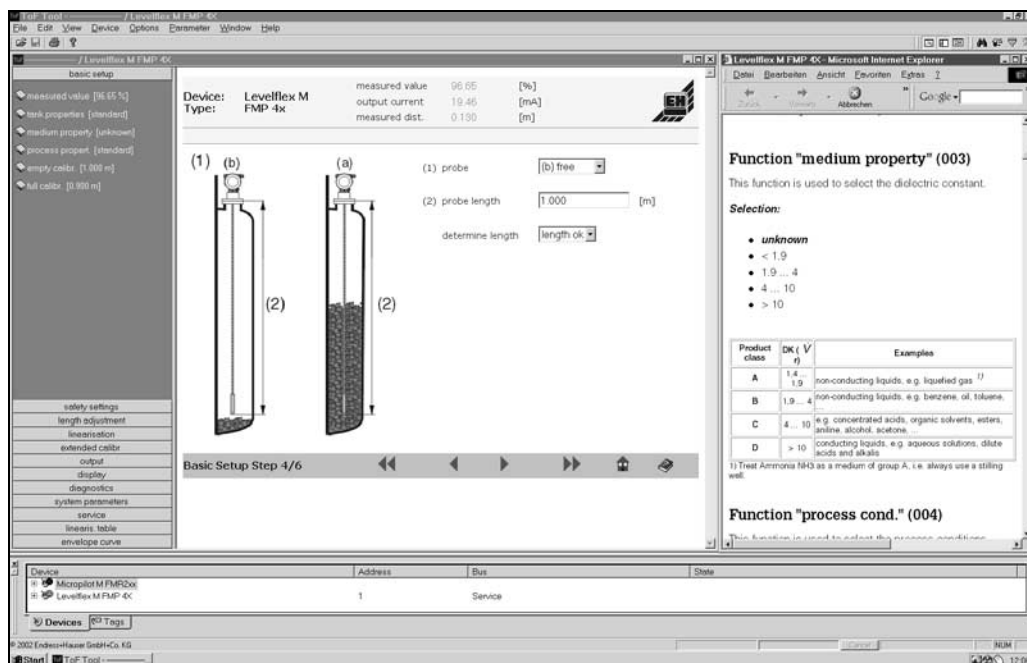
Basic Setup step 3/6:

- Enter the application parameters:
 - end of probe (for a description, see page 62)
 - probe length (for a description, see page 63)

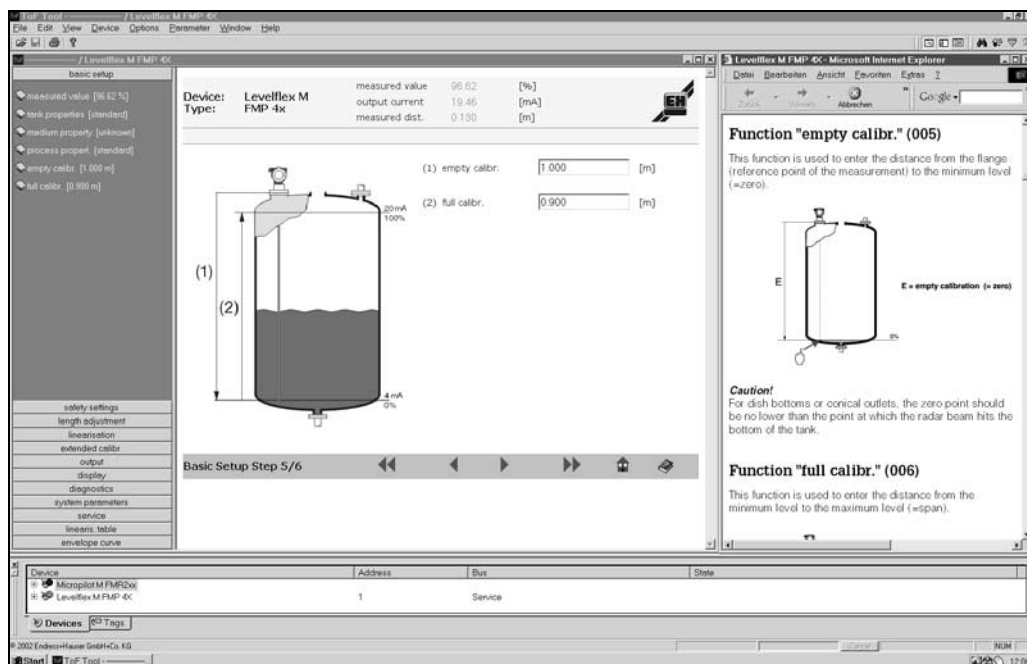


Basic Setup step 4/6:

- Enter the application parameters:
 - probe (for a description, see page 63)
 - probe length (for a description, see page 63)
 - determine length (for a description, see page 63)

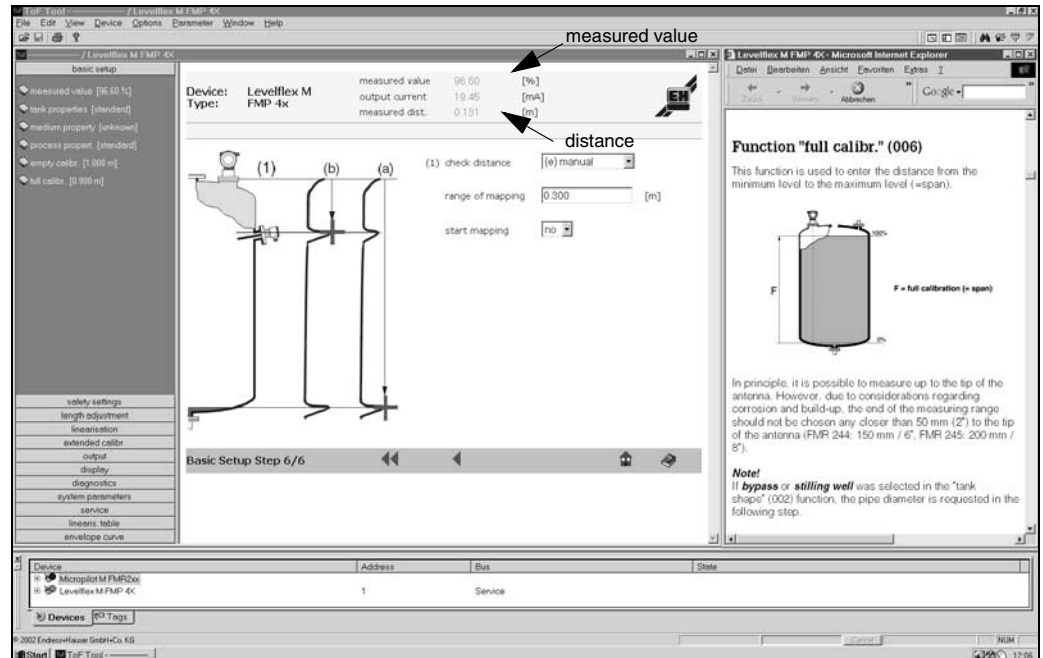
**Basic Setup step 5/6:**

- Enter the application parameters:
 - empty calibration (for a description, see page 64)
 - full calibration (for a description, see page 64)



Basic Setup step 6/6:

- This step starts the tank mapping
- The measured distance and the current measured value are always displayed in the header
- for a description, see page 66



6.8.1 Blocking distance

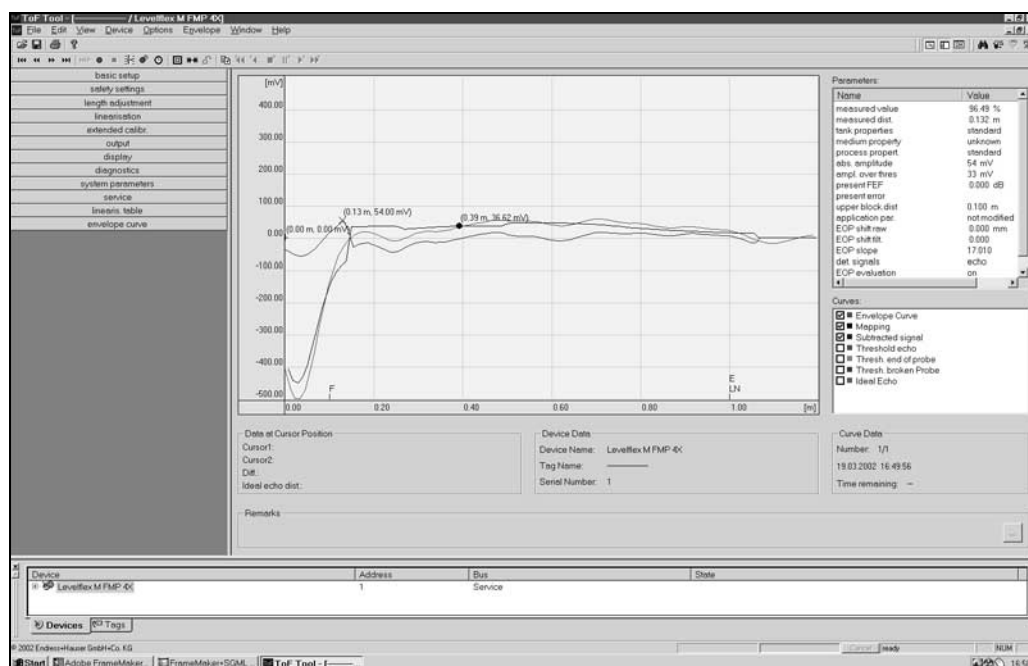


Note!

At installation in high nozzles, please the blocking distance in the function "upper block.dist" (059) newly enter!

6.8.2 Envelope curve with the ToF Tool

After the basic setup, an evaluation of the measurement using the envelope curve is recommended.



Note!

For the optimization of the measurement the installation of the Levelflex in another place can be executed when interference echoes.

6.8.3 User-specific applications (operation)

For details of setting the parameters of user-specific applications, see separate documentation BA 245F/00/en - description of the instrument functions of the Levelflex M.

7 Maintenance

The Levelflex M measuring instrument requires no special maintenance.

Exterior cleaning

When cleaning the Levelflex M, always use cleaning agents that do not attack the surface of the housing and the seals.

Repairs

The Endress+Hauser repair concept assumes that the measuring devices have a modular design and that customers are able to undertake repairs themselves. Spare parts are contained in suitable kits. They contain the related replacement instructions. All the spare parts kits which you can order from Endress+Hauser for repairs to the Levelflex M are listed with their order numbers on pages 87 and 88. sind alle Ersatzteil-Kits mit Bestellnummern aufgeführt, die Sie zur Reparatur des Levelflex M bei Endress+Hauser bestellen können.

Please contact Endress+Hauser Service for further information on service and spare parts.

Repairs to Ex-approved devices

When carrying out repairs to Ex-approved devices, please note the following:

- Repairs to Ex-approved devices may only be carried out by trained personnel or by Endress+Hauser Service.
- Comply with the prevailing standards, national Ex-area regulations, safety instructions (XA) and certificates.
- Only use original spare parts from Endress+Hauser.
- When ordering a spare part, please note the device designation on the nameplate. Only replace parts with identical parts.
- Carry out repairs according to the instructions. On completion of repairs, carry out the specified routine test on the device.
- Only Endress+Hauser Service may convert a certified device into a different certified variant.
- Document all repair work and conversions.

Replacement

After a complete Levelflex M or electronic module has been replaced, the parameters can be downloaded into the instrument again via the communication interface.

Prerequisite to this is that the data were uploaded to the PC beforehand using the ToF Tool / Commuwin II.

Measurement can continue without having to carry out a new setup.

- You may have to activate linearisation (see BA 221F)
- You may need to record the tank map again (see Basic Setup)

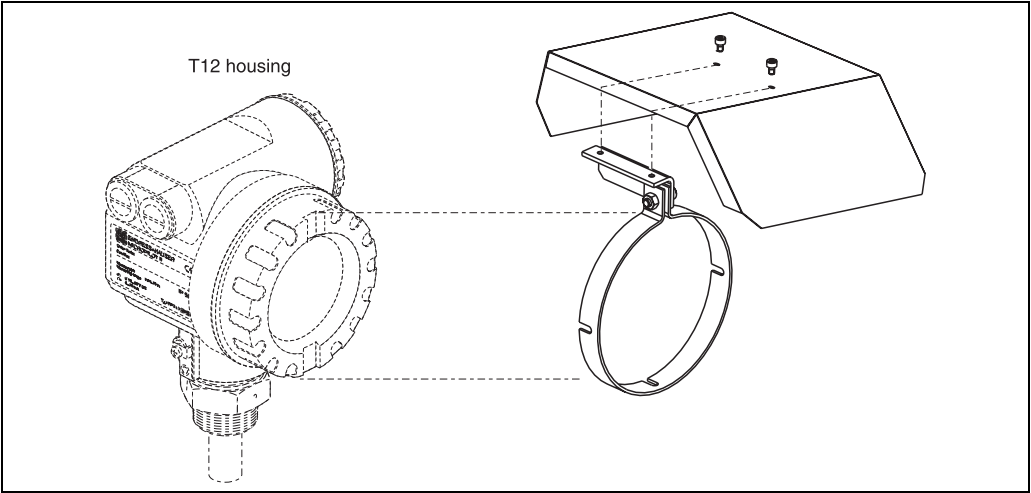
After an probe or electronic has been replaced, a new calibration must be carried out. This is described in the repair instructions.

8 Accessories

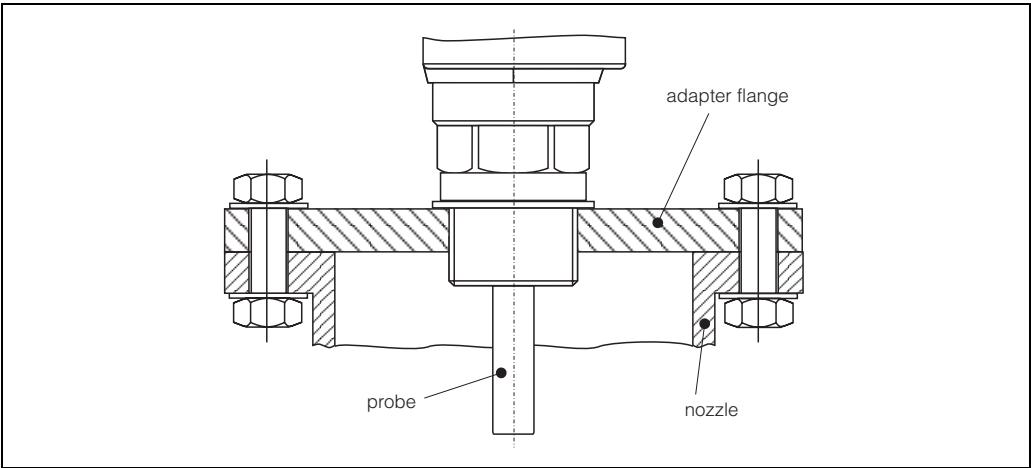
Various accessories, which can be ordered separately from Endress+Hauser, are available for the Levelflex M.

Weather protection cover

A Weather protection cover made of stainless steel is available for outdoor mounting (order code: 543199-0001). The shipment includes the protective cover and tension clamp.



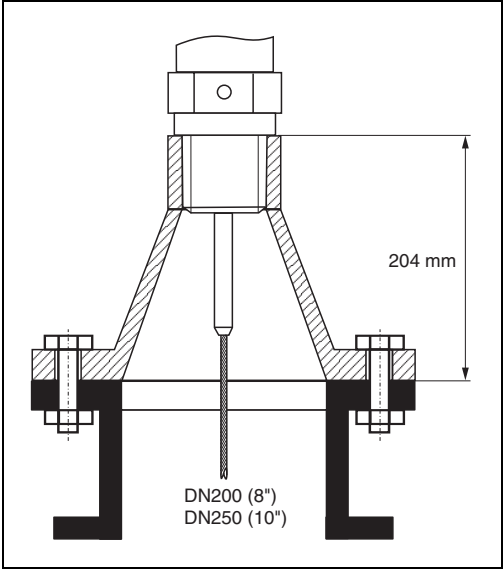
Adapter flange FAU 70 E/FAU 70 A



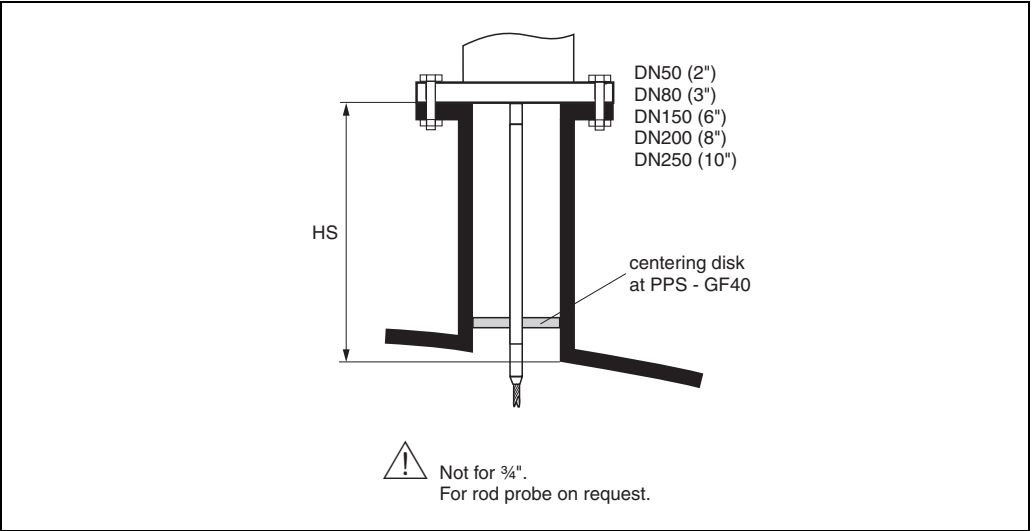
Version				Version			
	12	DN 50 PN 16			12	ANSI 2" 150 psi	
	14	DN 80 PN 16			14	ANSI 3" 150 psi	
	15	DN 100 PN 16			15	ANSI 4" 150 psi	
Thread				thread			
	3	G 1½, ISO 228			3	NPT 1½ - 11,5	
Material				Material			
	2	1.4435			2	1.4435	
FAU 70 E -			Complete product designation	FAU 70 A -			Complete product designation

Flange with horn adapter to adapt on the following nozzles

	Order - No.
G 1 1/2" at DN 200 / PN 16	52014251
G 1 1/2" at DN 250 / PN 16	52014252
NPT 1 1/2" at 8" / 150 psi	52014253
NPT 1 1/2" at 10" / 150 psi	52014254



Extension rod / Centering



Certificate	
A	For non-hazardous areas
2	ATEX II 1D
Extension rod	
1	115mm-rod for nozzle height 150...250mm / 6...10"
2	215mm-rod for nozzle height 250...350mm / 10...14"
3	315mm-rod for nozzle height 350...450mm / 14...18"
4	415mm-rod for nozzle height 450...550mm / 14...22"
9	Special version
Centre disk	
A	without centre disk
B	DN40 / 1 1/2", inside diam. 40-45mm
C	DN50 / 2", inside diam. 50...57mm
D	DN80, inside diam. 80...85mm
E	3", inside diam. 76...78mm
G	DN100 / 4", inside diam. 100...110mm
H	DN150 / 6", inside diam. 152...164mm
J	DN200 / 8", inside diam. 201...215mm
K	DN250 / 10", inside diam. 253...269mm
Y	Special version
HMP40-	complete product designation

Isolated tie down

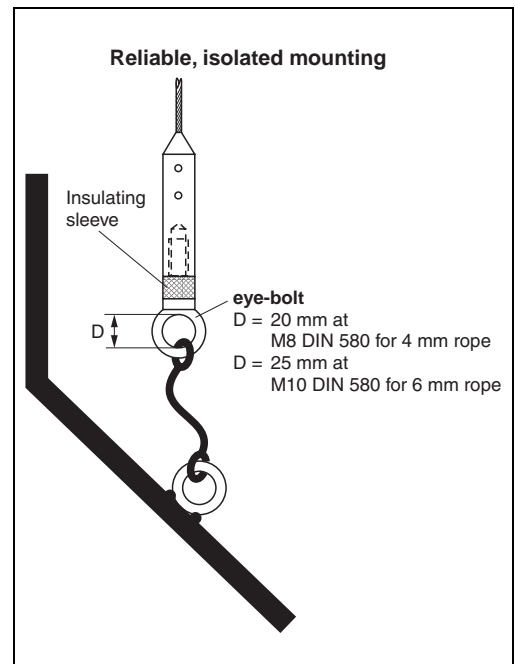
	Order - No.
for 4mm rope probe	52014249
for 6mm rope probe	52014250

If a rope probe has to be fixed and a secure grounded mounting is not possible, we recommend using the insulating sleeve made of PEEK-GF30 with accompanying DIN 580 eye-bolt made of stainless steel.

Max. process temp. 150 °C.

Due to the risk of electrostatic charge, the insulating sleeve is not suitable for use in hazardous areas.

In these cases the fixing must be reliably grounded (see page 23).

**Insulating sleeve**

Insulating sleeve for probe fixation. In preparation.

Service adapter FXA 193

For communication with ToF Tool via the display connector. (Bestell-Nr.: 50095566).

Commuwin II

Operating software for intelligent instruments.

Proficard

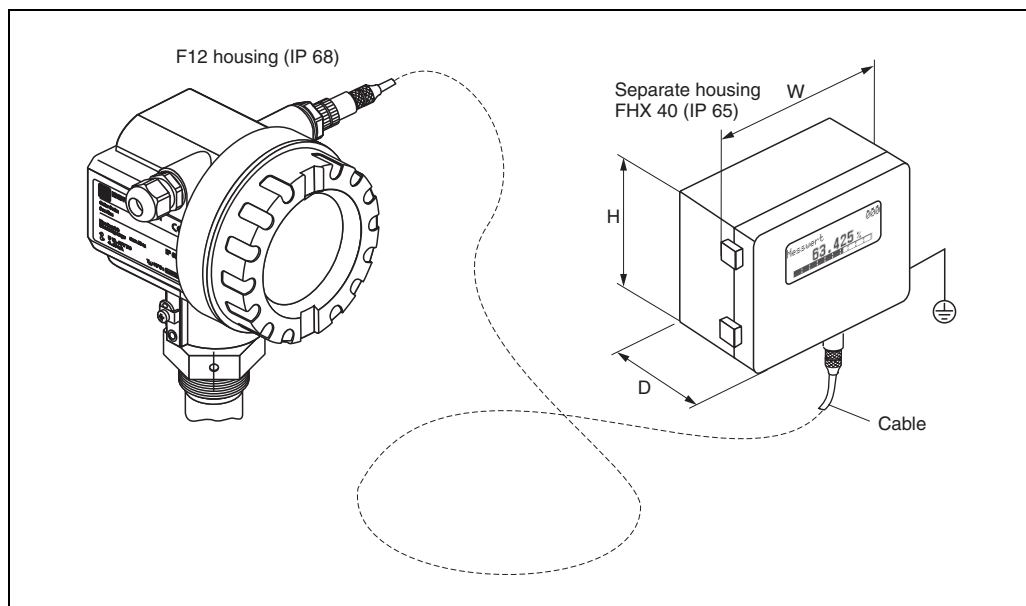
for the connection of a Laptop to PROFIBUS

Profiboard

for the connection of a Personal Computer to PROFIBUS

Remote display FHX 40

Dimensions



Technical data:

Max. cable length: 20 m (67 ft)
 Temperature range: -30 °C...+70 °C (-22 °F...158 °F)

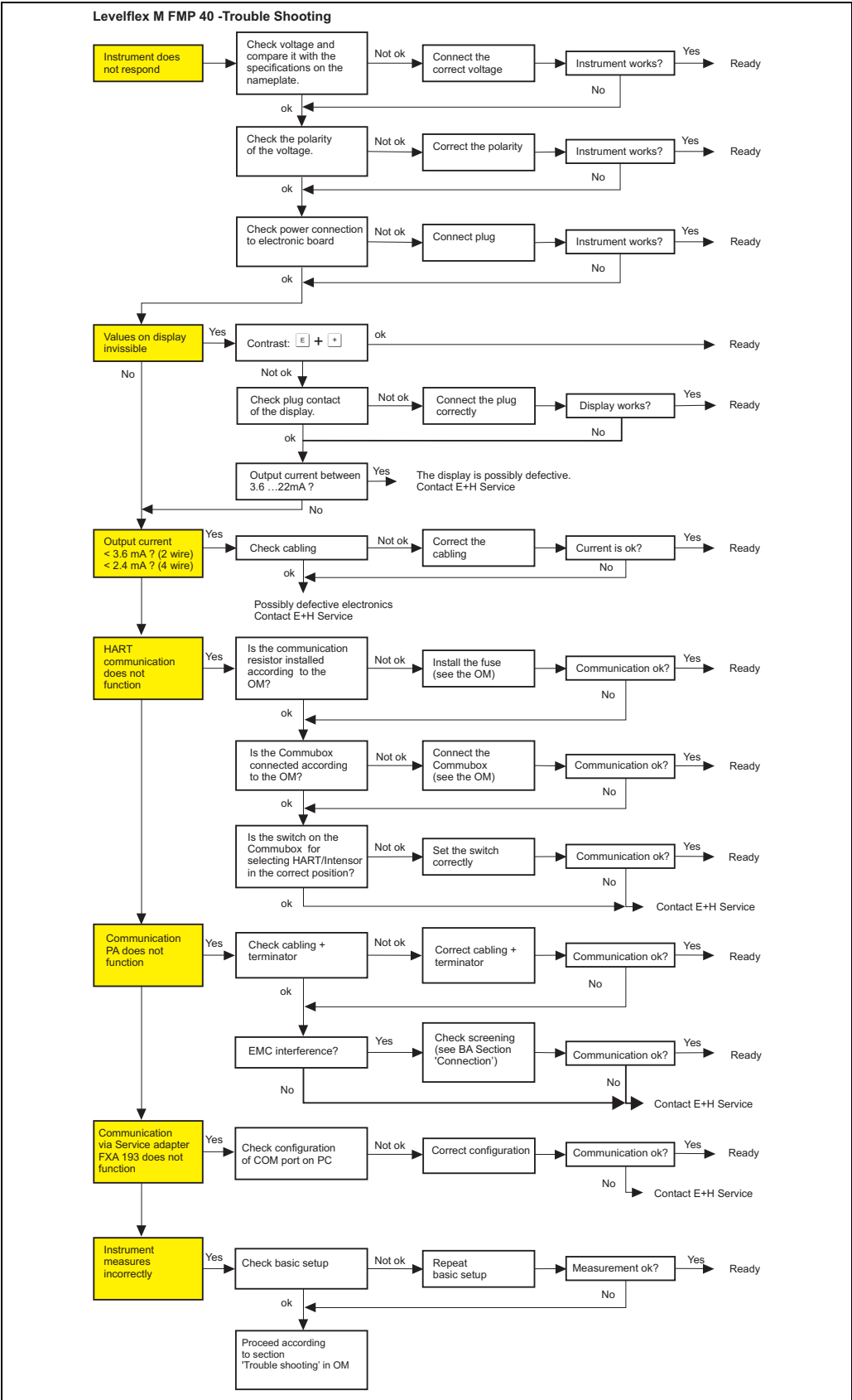
Separate housing:

Degree of protection: IP65 acc. to EN 60529 (NEMA 4)
 Material for housing: Alloy of Aluminium AL Si 12
 Dimensions [mm] / [inch]: 122x150x80 (HxBxT) / 4.8x5.9x3.2
 EMC version with conductive sealing

Also suitable for use in zone 1, in combination with a Levelflex M with ATEX II 1/2 G EEx ia IIC T6 approval.

9 Trouble-shooting

9.1 Trouble-shooting instructions



9.2 System error messages

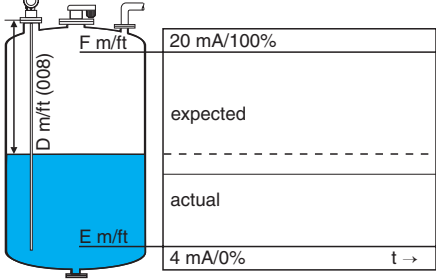
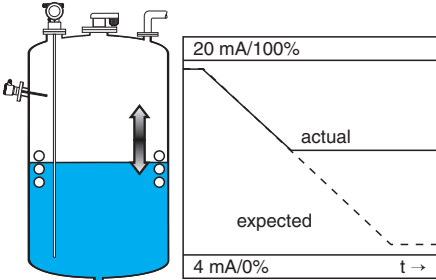
Code	Description	Possible cause	Remedy
A102	checksum error general reset & new calibr.required	device has been powered off before data could be stored; emc problem; E ² PROM defect	reset; avoid emc problem; if alarm prevails after reset, exchange electronics
W103	initialising - please wait	E ² PROM storage not yet finished	wait some seconds; if warning prevails, exchange electronics
A106	downloading please wait	processing data download	wait until warning disappears
A110	checksum error general reset & new calibr.required	device has been powered off before data could be stored; emc problem; E ² PROM defect	reset; avoid emc problem; if alarm prevails after reset, exchange electronics
A111	electronics defect	RAM defective	reset; if alarm prevails after reset, exchange electronics
A113	electronics defect	ROM defective	reset; if alarm prevails after reset, exchange electronics
A114	electronics defect	E2PROM defective	reset; if alarm prevails after reset, exchange electronics
A115	electronics defect	general hardware problem	reset; if alarm prevails after reset, exchange electronics
A116	download error repeat download	checksum of stored data not correct	restart download of data
A121	electronics defect	no factory calibration existant; E ² PROM defective	contact service
W153	initialising - please wait	initialisation of electronics	wait some seconds; if warning prevails, power off device and power on again
A160	checksum error general reset & new calibr.required	device has been powered off before data could be stored; emc problem; E ² PROM defect	reset; avoid emc problem; if alarm prevails after reset, exchange electronics
A164	electronics defect	hardware problem	reset; if alarm prevails after reset, exchange electronics
A171	electronics defect	hardware problem	reset; if alarm prevails after reset, exchange electronics
A221	Probe pulse deviation from average values	HF module or cable between HF module and electronics defective	Check contacts on HF module If fault cannot be eliminated: Replace HF module

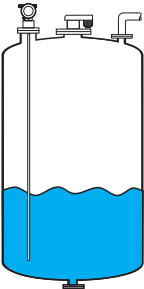
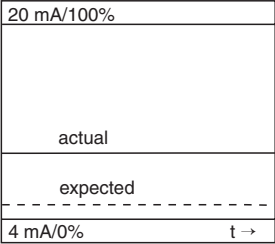
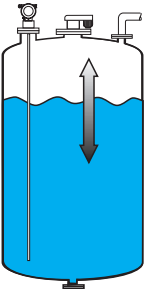
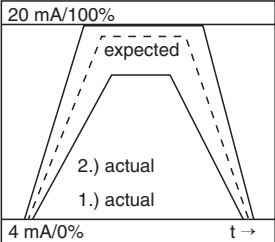
Tab. 3 System error messages

Code	Description	Possible cause	Remedy
A241	Broken probe	Broken probe or value for probe length is too short	Check the probe length in 033, Check the probe itself, if the probe is broken, change the probe, or change to a non contact system
A251	Feedthrough	Lost contact in the process feedthrough	Replace process feedthrough
A261	HF cable defective	HF cable defective or HF connector removed	Check HF connector, replace cable if defective
A275	Offset too high	Temperature at the electronics too high or HF module defective	Check temperature, replace HF module if defective
A512	recording of mapping please wait	mapping active	wait some seconds until alarm disappears
W601	linearisation ch1 curve not monotone	linearization not monotonously increasing	correct linearisation table
W611	less than 2 linearisation points for channel 1	number of entered linearization points < 2	correct linearisation table
W621	simulation ch. 1 on	simulation mode is active	switch off simulation mode
E641	no usable echo channel 1 check calibr.	echo lost due to application conditions of built up on antenna	check installation; clean antenna (cf. Operating Instructions)
W650	Signal/noise ratio too low or no echo	noise on signal too high	eliminate electromagnetic interference
E651	level in safety distance - risk of overspill	level in safety distance	alarm will disappear as soon as level leaves safety distance;
A671	linearisation ch1 not complete, not usable	linearisation table is in edit mode	activate linearisation table
W681	current ch1 out of range	current out of range (3,8 mA ... 21,5 mA)	check calibration and linearisation

Tab. 3 System error messages

9.3 Application errors

Error	Output	Possible cause	Remedy
A warning or alarm has occurred.	Depending on the configuration	See table of error messages (see page 83)	1. See table of error messages (see page 83)
Measured value (00) is incorrect		<p>Measured distance (008) OK?</p> <p>yes →</p> <p>no ↓</p> <p>An interference echo may have been evaluated.</p>	<p>yes →</p> <ol style="list-style-type: none"> 1. Check empty calibr. (005) and full calibr. (006). 2. Check linearisation: <ul style="list-style-type: none"> → level/ullage (040) → max. scale (046) → diameter vessel (047) → Check table <p>yes →</p> <ol style="list-style-type: none"> 1. Carry out tank mapping → basic setup
No change of measured value on filling/emptying		Interference echo from installations, nozzle or extension on the antenna	<ol style="list-style-type: none"> 1. Carry out tank mapping → basic setup 2. If necessary, clean probe. 3. If necessary, select better mounting position
E 641 (loss of echo) after turn on the power supply	If the instrument is configured to Hold by loss of echo the output is set to any value/current.	noise level during the initialisation phase to high.	<p>Repeat once more empty calibr. (005). Caution!</p> <p>Before conformation change with <input type="checkbox"/> or <input type="checkbox"/> to the edit mode.</p>

<p>Device displays a level when the tank is empty.</p>	 	<p>Incorrect probe length</p>	<p>1. Carry out automatic probe length detection when the tank is empty. 2. Carry out mapping over entire probe when the tank is empty (probe free).</p>
<p>Measured value incorrect (slope error in the entire measuring range)</p>	 	<p>Tank properties incorrect.</p> <p>Medium properties incorrect.</p>	<p>LN < 4 m and "Aluminium tank" tank properties selected → Calibration not possible. → Selection → Select standard → Thresholds too high</p> <p>Select lower medium properties.</p>

9.4 Spare parts



Note!

You can order spare parts directly from your E+H service organization by giving the serial number which is printed on the measuring transducer nameplate (see page 6 ff.). The corresponding spare part number also appears on each spare part. Installation instructions are given on the instruction card that is also delivered.

Spare parts Levelflex M FMP 40 with housing F12



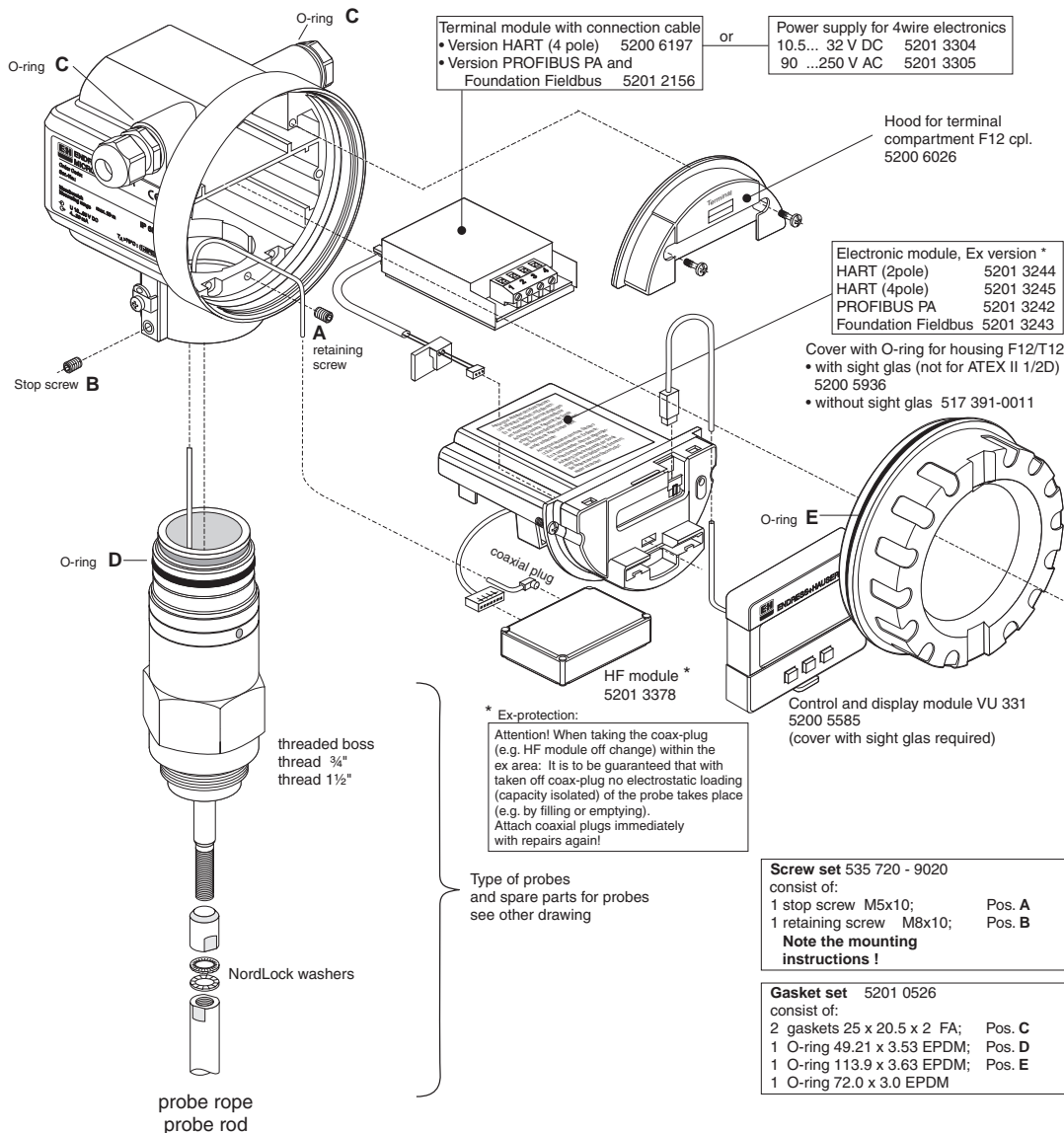
Only identical, original E+H spare parts may be used.

The instrument may only be maintained and repaired by qualified personnel. The device documentation, applicable standards and legal requirements as well as any certificates have to be observed!

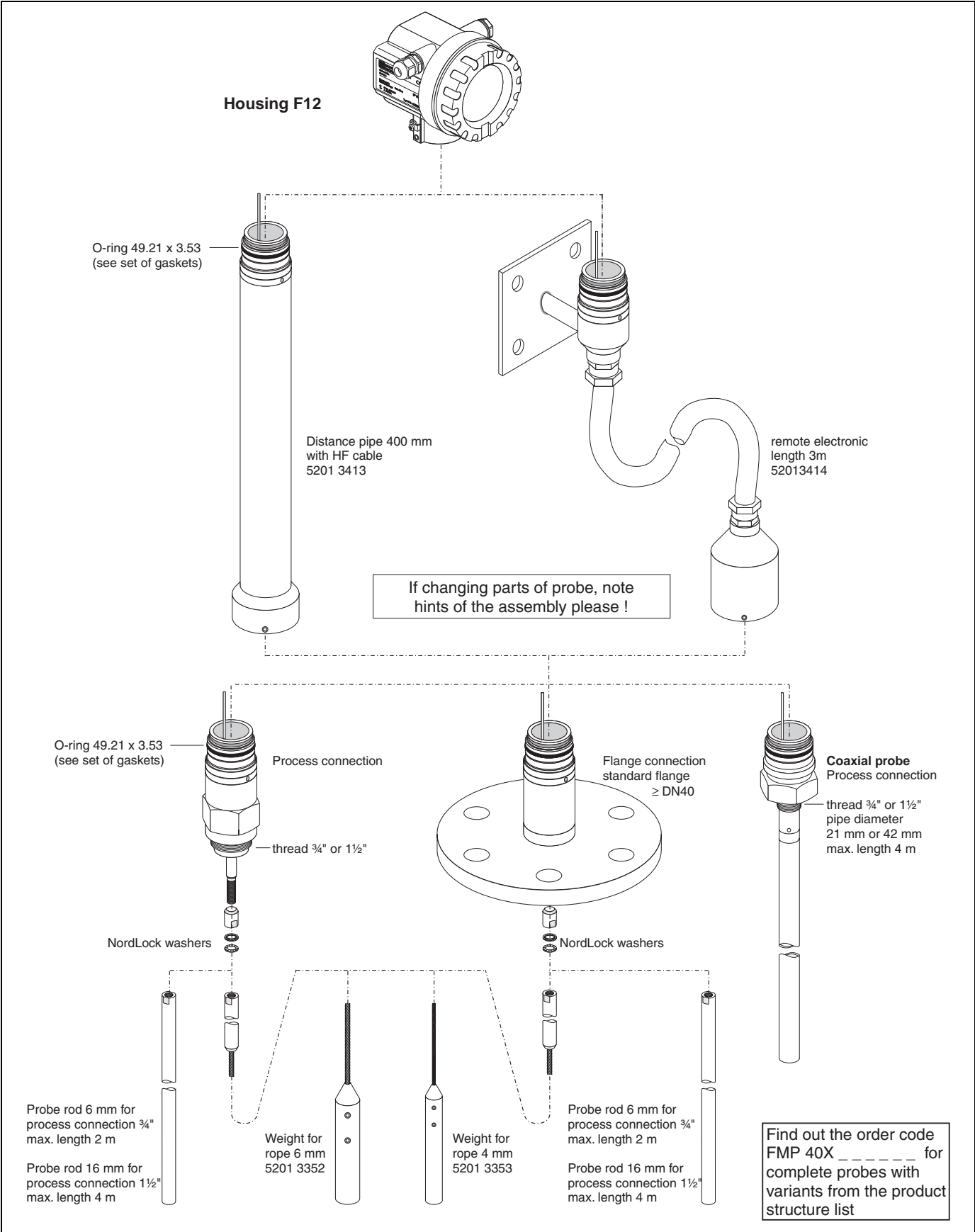
Housing F12: standard, complete pre-mounted, incl. nameplate, cable gland and Teflon filter

543 120 - 0022	G ½" cable gland
543 120 - 0023	NPT ½" cable gland
543 120 - 0024	M20 x 1.5 PA cable gland
5201 3409	M20 x 1.5 metal cable gland (not for lid with sight glass)
5200 1992	M12 PROFIBUS PA plug
5200 8556	7/8 UNC Fieldbus Foundation plug
5201 3348	G ½" cable gland, 4 wire
5201 3349	NPT ½" cable gland, 4 wire
5201 3350	4 wire, M20 x 1.5 PA cable gland
5201 3351	4 wire, M20 x 1.5 metal cable gland (not for lid with sight glass)

The spare parts listed are generally suitable for use in Ex-devices



Spare parts Levelflex M FMP 40 - probes and accessories



9.5 Return

The following procedures must be carried out before a transmitter is sent to Endress+Hauser e.g. for repair or calibration:

- Remove all residue which may be present. Pay special attention to the gasket grooves and crevices where fluid may be present. This is especially important if the fluid is dangerous to health, e.g. corrosive, poisonous, carcinogenic, radioactive, etc.
- Always enclose a duly completed "Declaration of contamination" form (a copy of the "Declaration of contamination" is included at the end of this operating manual). Only then can Endress +Hauser transport, examine and repair a returned device.
- Enclose special handling instructions if necessary, for example a safety data sheet as per EN 91/155/EEC.

Additionally specify:

- An exact description of the application.
- The chemical and physical characteristics of the product.
- A short description of the error that occurred (specify error code if possible)
- If necessary, give the error code.

9.6 Disposal

In case of disposal please separate the different components according to their material consistence.

9.7 Software history

Software version / Date	Software changes	Documentation changes
V 01.02.00 / 04.2002	Original software. Operated via: <ul style="list-style-type: none"> – ToF Tool – Commuwin II (from version 2.05.03) – HART communicator DXR 275 (from OS 4.6) with Rev. 1, DD 1. 	

9.8 Contact addresses of Endress+Hauser

The addresses of Endress+Hauser are given on the back cover of this operating manual. If you have any questions, please do not hesitate to contact your E+H representative.

10 Technical data

10.1 Technical data at a glance

Application	
<i>Application</i>	<p>The Levelflex M performs continuous level measurement of powdery to granular bulk solids and liquids e.g. plastic granulate. Probes are available with threaded process connections from ¾" and flanges from DN40 / 1½":</p> <ul style="list-style-type: none"> • Rope probes, above all for measurement in bulk solids, measuring range up to 35 m/1378" • Rod probes, above all for liquids • Coax probes, for liquids
Function and system design	
<i>Measuring principle</i>	<p>The Levelflex is a "downward-looking" measuring system that functions according to the ToF method (ToF = Time of Flight). The distance from the reference point (process connection of the measuring device see page 12) to the product surface is measured. High-frequency pulses are injected to a probe and led along the probe. The pulses are reflected by the product surface, received by the electronic evaluation unit and converted into level information.</p> <p>This method is also known as TDR (Time Domain Reflectometry).</p>
<i>Equipment architecture</i>	see page 101 ff.
Input	
<i>Measured variable</i>	<p>The measured variable is the distance between the reference point and the product surface.</p> <p>Subject to the input zero point empty distance the level is calculated.</p> <p>Alternatively, the level can be converted by means of linearisation into other variables (volume, mass).</p>
<i>Measuring range</i>	see Technical Information TI 358F
Output	
<i>Output signal</i>	<ul style="list-style-type: none"> • PROFIBUS-PA
<i>Signal on alarm</i>	<p>Error information can be accessed via the following interfaces:</p> <ul style="list-style-type: none"> • Local display: <ul style="list-style-type: none"> – Error symbol (see page 36) – Plain text display • Digital interface
Auxiliary energy	
<i>Electrical connection</i>	<ul style="list-style-type: none"> • Housing F 12 with additionally sealed terminal compartment for standard or EEx ia
<i>Cable entry</i>	see page 31 ff.
<i>Supply voltage</i>	see page 31 ff.
<i>Power consumption</i>	min. 60 mW, max. 900 mW

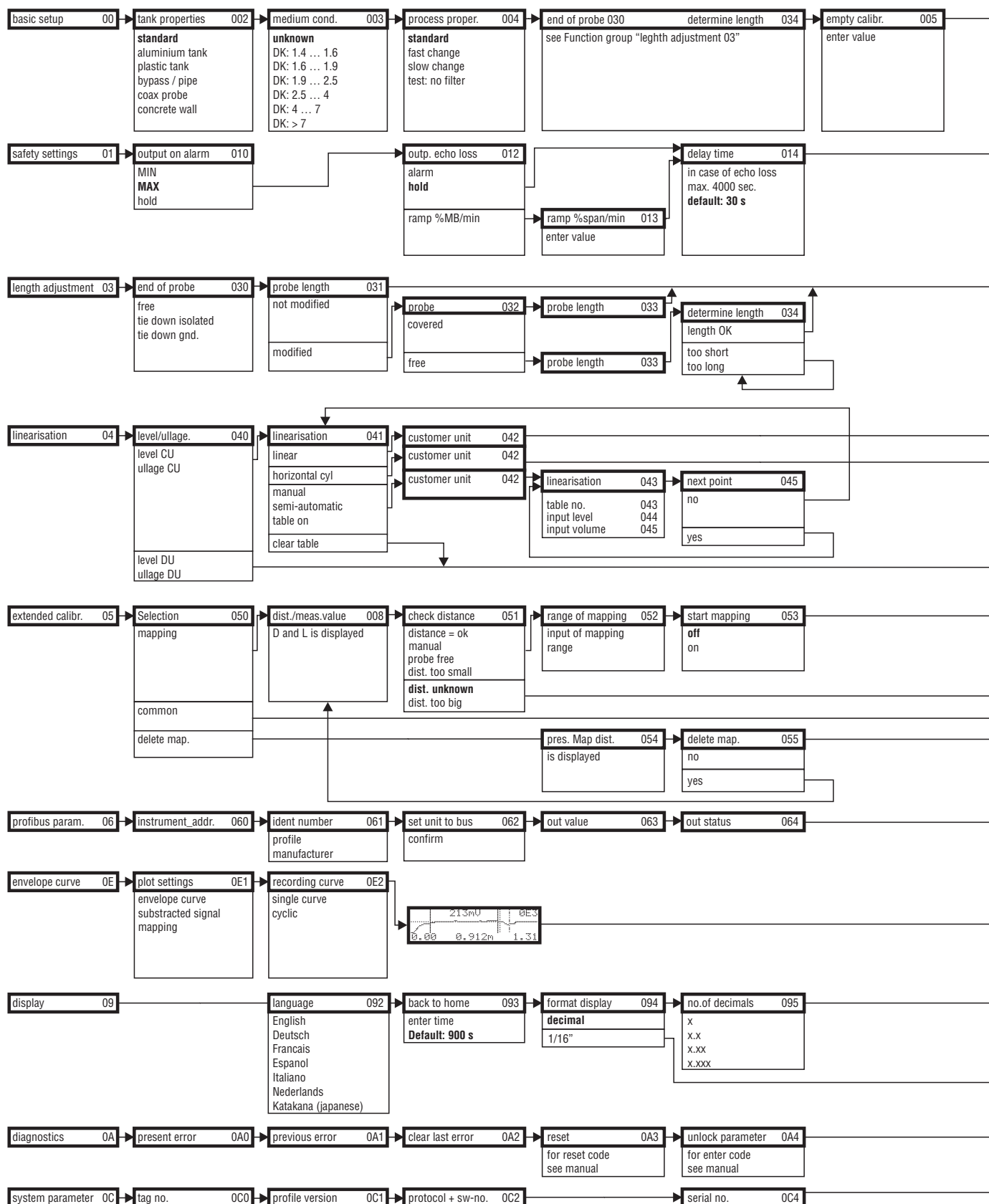
Performance characteristics	
Reference operating conditions	<ul style="list-style-type: none"> temperature = +20 °C (68 °F) ±5 °C (9 °F) pressure = 1013 mbar abs. (14.7 psia) ±20 mbar (0.3 psi) relative humidity (air) = 65 % ± 20% Reflection factor 0.8 (surface of water for coax probe, metal plate for rod and rope probe with min. 1 m Ø) Flange for rod or rope probe ≥ 30 cm Ø Distance to obstructions ≥ 1 m
Maximum measured error	<p>Typical statements for reference conditions, include linearity, repeatability, and hysteresis:</p> <ul style="list-style-type: none"> Linearity: <ul style="list-style-type: none"> up to 10 m/400" measuring range: ±3 mm 10 m/400" to 35 m/1378" measuring range: ± 0,03 % <p>According to IEC 60770-1</p>
Operating conditions	
Operating conditions	
Installation instructions	see page 14 ff.
Environment	
Ambient temperature range	<p>The measurements are carried out in accordance with EN 61298-3:</p> <ul style="list-style-type: none"> digital output (HART, PROFIBUS PA, Foundation Fieldbus): <ul style="list-style-type: none"> FMP 40 average T_K: 0.6 mm/10 K, max. ± 3.5 mm over the entire temperature range -40 °C...+80 °C 2-wire: <ul style="list-style-type: none"> Current output (additional error, in reference to the span of 16 mA): <ul style="list-style-type: none"> Zero point (4 mA) average T_K: 0.032 %/10 K, max. 0.35 % over the entire temperature range -40 °C...+80 °C Span (20 mA) average T_K: 0.05 %/10 K, max. 0.5 % over the entire temperature range -40 °C...+80 °C 4-wire: <ul style="list-style-type: none"> Current output (additional error, in reference to the span of 16 mA): <ul style="list-style-type: none"> Zero point (4 mA) average T_K: 0.02 %/10 K, max. 0.29 % over the entire temperature range -40 °C...+80 °C Span (20 mA) average T_K: 0.06 %/10 K, max. 0.89 % over the entire temperature range -40 °C...+80 °C
Storage temperature	-40 °C ... +80 °C
Climate class	DIN EN 60068-2-38 (test Z/AD)
Degree of protection	<ul style="list-style-type: none"> housing: IP 68, NEMA 4X (open housing: IP20, NEMA 1) probe: IP 68 (NEMA 6P)
Vibration resistance	DIN EN 60068-2-64 / IEC 68-2-64: 20...2000 Hz, 1 (m/s ²)/Hz
Cleaning of the probe	see Technical Information TI 358F

<i>Electromagnetic compatibility</i>	<p>When installing the probes in metal and concrete tanks and when using a coax probe:</p> <ul style="list-style-type: none"> • Interference Emission to EN 61326, Electrical Equipment Class B • Interference Immunity to EN 61326, Annex A (Industrial) <p>When rod and rope probes are installed in plastic and wood silos, the influence of strong electromagnetic fields can have an effect on the measured value. Interference Emission to EN 61326 is in this case: Class A.</p>
Process conditions	
<i>Process temperature range</i>	see Technical Information TI 358F
<i>Process temperature limits</i>	see Technical Information TI 358F
<i>Process pressure limits</i>	see Technical Information TI 358F
<i>Dielectric constant</i>	<ul style="list-style-type: none"> • with coax probe: $\epsilon_r \geq 1,4$ • Rod and rope probe: $\epsilon_r \geq 1,6$
Mechanical construction	
<i>Design, dimensions</i>	see page 12
<i>Weight</i>	see Technical Information TI 358F
<i>Material</i>	see Technical Information TI 358F
<i>Process connection</i>	see Technical Information TI 358F
Human interface	
<i>Operation concept</i>	see page 33
<i>Display</i>	see page 33
Certificates and approvals	
<i>CE approval</i>	The measuring system meets the legal requirements of the EC-guidelines. Endress+Hauser confirms the instrument passing the required tests by attaching the CE-mark.
<i>External standards and guidelines</i>	<p>EN 60529 Protection class of housing (IP-code)</p> <p>EN 61010 Safety regulations for electrical devices for measurement, control, regulation and laboratory use.</p> <p>EN 61326 Emissions (equipment class B), compatibility (appendix A – industrial area)</p> <p>NAMUR Standards committee for measurement and control in the chemical industry</p>
<i>Ex approval</i>	see »Ordering structure Levelflex M FMP 40« on page 6
Ordering Information	
	The E+H service organisation can provide detailed ordering information and information on the order codes on request.
Accessories	
	see page 78

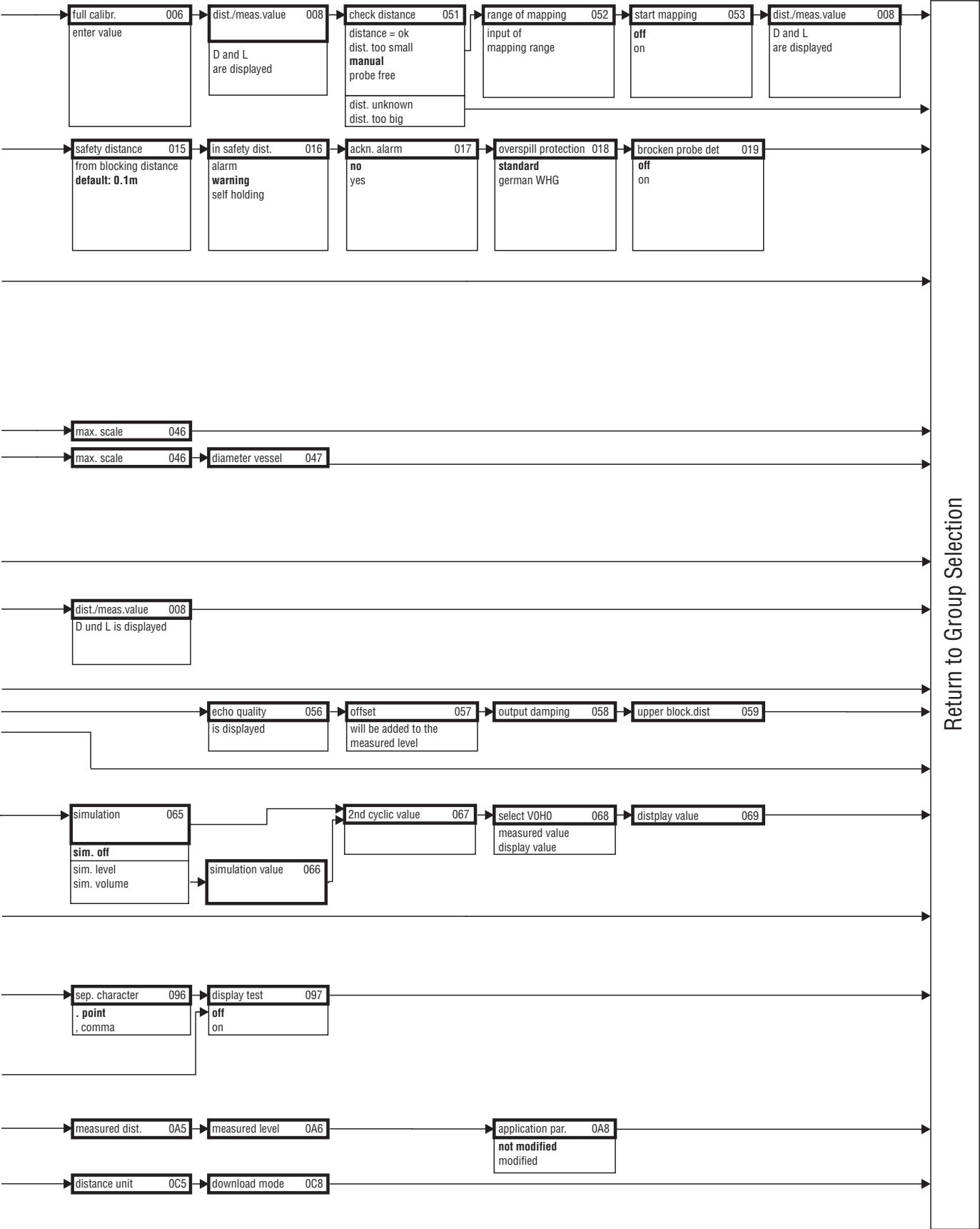
Supplementary Documentation	
Supplementary Documentation	<ul style="list-style-type: none">• System Information Levelflex (SI 030F/00/en)• Technical Information (TI 358F/00/en)• Operating Instructions "Description of instrument functions" (BA 245F/00/en)

11 Appendix

11.1 Operating menu HART (Display modul), ToF Tool



Note! The default values of the parameters are typed in boldface.



11.2 Operating matrix PROFIBUS-PA / Commuwin II

Function Group	V0	H0	H1	H2	H3	H4	H5	H6	H7	H8	H9
basic setup	measured value CU			tank properties 0: unknown 1: aluminium tank 2: plastic tank 3: bypass / pipe 4: coax probe 5: concrete wall	medium cond. 0: unknown 1: 1.4 2: 1.6 3: 1.9 4: 2.5 5: 4.0 6: 7.0	process proper. 0: standard 1: fast change 2: slow change 3: testno filler	empty calibr. Min: -> 0.0m, .ft. Max: -> 100m, .ft. 10m, .ft., .in. DU	full calibr. Min: -> 0.0m, .ft. Max: -> 100m, .ft. 10m, .ft., .in. DU			
safety settings		output on alarm 0: Min 1: MAX 2: hold		outp. echo loss 0: alarm 1: hold 2: ramp %/min	ramp %span/min Min: -> 9999 Max: -> 9999 %/min 0	delay time Min: -> 0 Max: -> 4000 s 30	safety distance Min: -> neg. 100m neg. ft. neg. in, neg. mm Max: -> 100m, .ft., .in., .mm DU 0.1m	in safety dist. 0: alarm 1: warning 2: self holding	ackn. alarm 0: no 1: yes	overspill protection 0: standard 1: german WHG	broken probe det 0: off 1: on
length adjustment		end of probe 0: free 1: tie down isolated 2: tie down grd.	probe length 0: not modified 1: modified	probe 0: covered 1: free	probe length Min: -> 0.0m, .ft. Max: -> 15/35/60m, .ft. in, .mm DU factory calibrated	determine length 0: length ok 1: too short 2: too long					
linearisation		level/ulage 0: level CU 1: level DU 2: ulage CU 3: ulage DU	linearisation 0: linear 1: horizontal cyl 2: manual 3: semi-automatic 4: table on 5: clear table	customer unit 0: % 1: 2hl, 3m³ 4dm³ 5cm³, 6ft³ 7us gal 8: gal, 9kg, 10t, 11lb, 12ton, 13m, 14ft, 15mm, 16inch	table no. Min: -> 1 Max: -> 32 1	input level Min: -> 0.0m, .ft. Max: -> 100m, .ft. in, .mm DU 0.0m, .ft., .in., .mm	input volume Min: -> 99999 Max: -> 99999 CU 0	max. scale Min: -> 99999 Max: -> 99999 CU 1	diameter vessel Min: -> 0.0m, .ft. Max: -> 100m, .ft., .in., .mm 9.0m, 29.528ft, 354.331in, 9000mm DU		
extended calibr.			check distance 0: distance = ok 1: dist. too small 2: dist. too big 3: dist. unknown 4: manual 5: probe free	range of mapping Min: -> 0.3m, .ft., .in., .mm Max: -> 15/35/60m, .ft., .in., .mm DU 0.3m	start mapping 0: off 1: on	pres. Map dist Min: -> - Max: -> - DU	delete map. 0: no 1: yes	echo quality Min: -> - Max: -> - mV	offset Min: -> neg. 100m, neg. ft. neg. in, neg. mm Max: -> 100m, .ft., .in., .mm DU 0.0m	output damping Min: -> 0 Max: -> 255 s 3	upper block dist Min: -> 0.0m, .ft., .in., .mm Max: -> 15/35/60m, .ft., .in., .mm DU probe specific
profibus parameter		instrument addr. Min: -> - Max: -> -	ident number 0: profile 1: manufacturer	set unit to bus 0: confirm	out value Min: -> - Max: -> -	out status Min: -> - Max: -> -	simulation 0: sim. off 1: sim. level 2: sim. volume	simulation value Min: -> -2.0m, .ft. 6.562ft, -78.740in, -2000mm Max: -> 100m, .ft., .in., .mm CU	2nd cyclic value 0: height/dist 1: display value	select V0H0 value 0: measured 1: display value	display value Min: -> - Max: -> -
display				language 0: English 1: German 2: Français	back to home Min: -> 3 Max: -> 9999 s 900	format display 0: decimal 1: 1/16"	no. of decimals 0: x 1: x.x 2: x.xx 3: x.xxx	sep. character 0: - 1: ,			
service											
self check											
diagnostics		present error Min: -> - Max: -> -	previous error Min: -> - Max: -> -	clear last error 0: keep 1: erase	reset Min: -> 0 Max: -> 65535	unlock parameter Min: -> 0 Max: -> 33997 PA: 2457	measured dist. DU	measured level DU	application par. 0: not modified 1: modified		
system parameter		tag no. Min: -> - Max: -> -	profile version Min: -> - Max: -> -	protocol-sw-no. Min: -> - Max: -> -		serial no.	distance unit 0: m 1: ft 2: mm 3: inch		download mode 0: parameter only 1: param+out.ma p 2: only mapping		

11.3 Description of functions

**Note!**

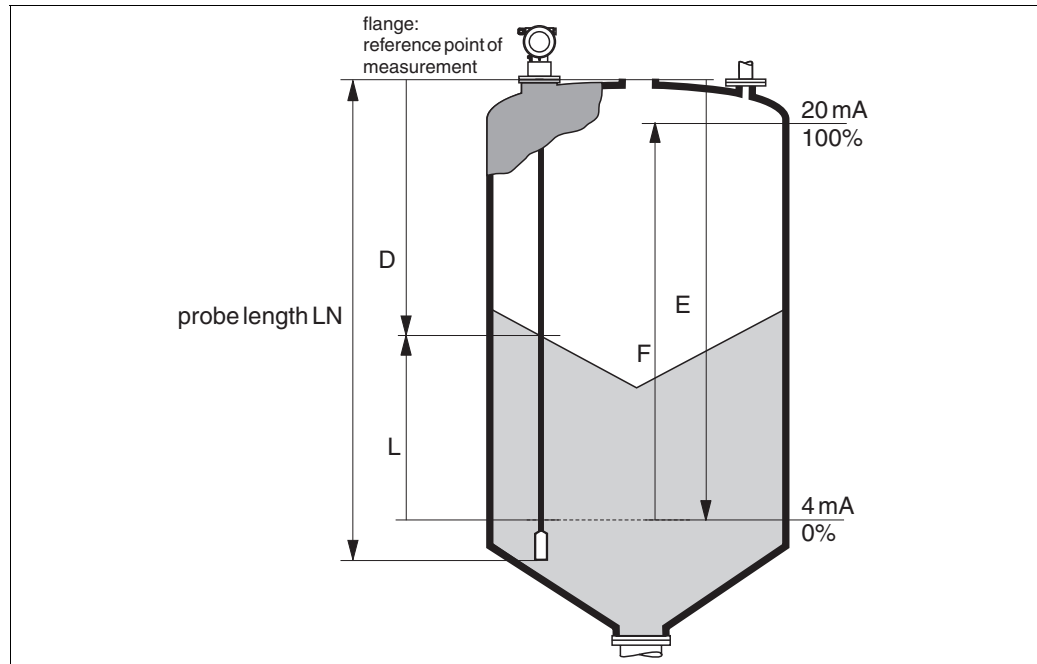
A detailed description of the function groups, functions and parameters is given in the documentation BA 245F/00/en - a description of the instrument functions of the Levelflex M.

11.4 Function and system design

11.4.1 Measuring principle

The Levelflex is a "downward-looking" measuring system that functions according to the ToF method (ToF = Time of Flight). The distance from the reference point (process connection of the measuring device see page 12) to the product surface is measured. High-frequency pulses are injected to a probe and led along the probe. The pulses are reflected by the product surface, received by the electronic evaluation unit and converted into level information.

This method is also known as TDR (Time Domain Reflectometry).



Input

The reflected pulses are transmitted from the probe to the electronics. There, a microprocessor analyses the signals and identifies the level echo, which was generated by the reflection of the high-frequency pulses at the product surface. This clear signal finding benefits from the many years experience with pulse time-of-flight procedures that have been integrated into the development of the PulseMaster® Software.

The distance D to the product surface is proportional to the time of flight t of the impulse:

$$D = c \cdot t/2,$$

with c being the speed of light.

Based on the known empty distance E , the level L is calculated:

$$L = E - D$$

Reference point for "E" see above diagram, Details see page 58.

The Levelflex possesses functions for the interference echo suppression that can be activated by the user. They guarantee that interference echoes from e.g. internals and struts are not interpreted as level echoes.

Output

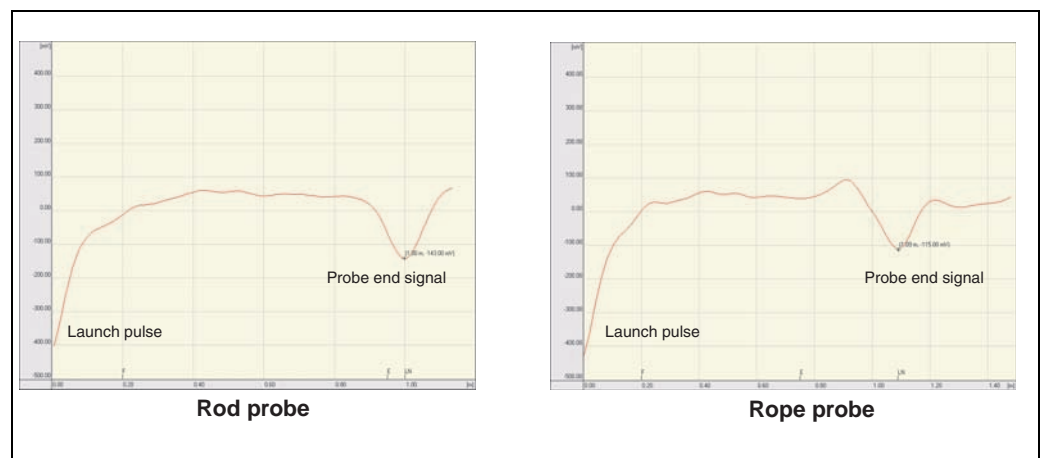
The Levelflex is initially adjusted at the factory to the probe length ordered, so that in most cases only the application parameters, that automatically adapt the device to the measuring conditions, need to be entered. For models with current output, the factory adjustment for zero point and span is F 4 mA and 20 mA, for digital outputs and the display module 0 % and 100 %.

A linearisation function with max. 32 points, that is based on a manually or semi-automatically input table, can be activated on-site or via remote operation. This function enables, for example, the conversion of the level into units of volume or weight.

An evaluation of the measurement with the aid of the envelope curve

Typical curve shape

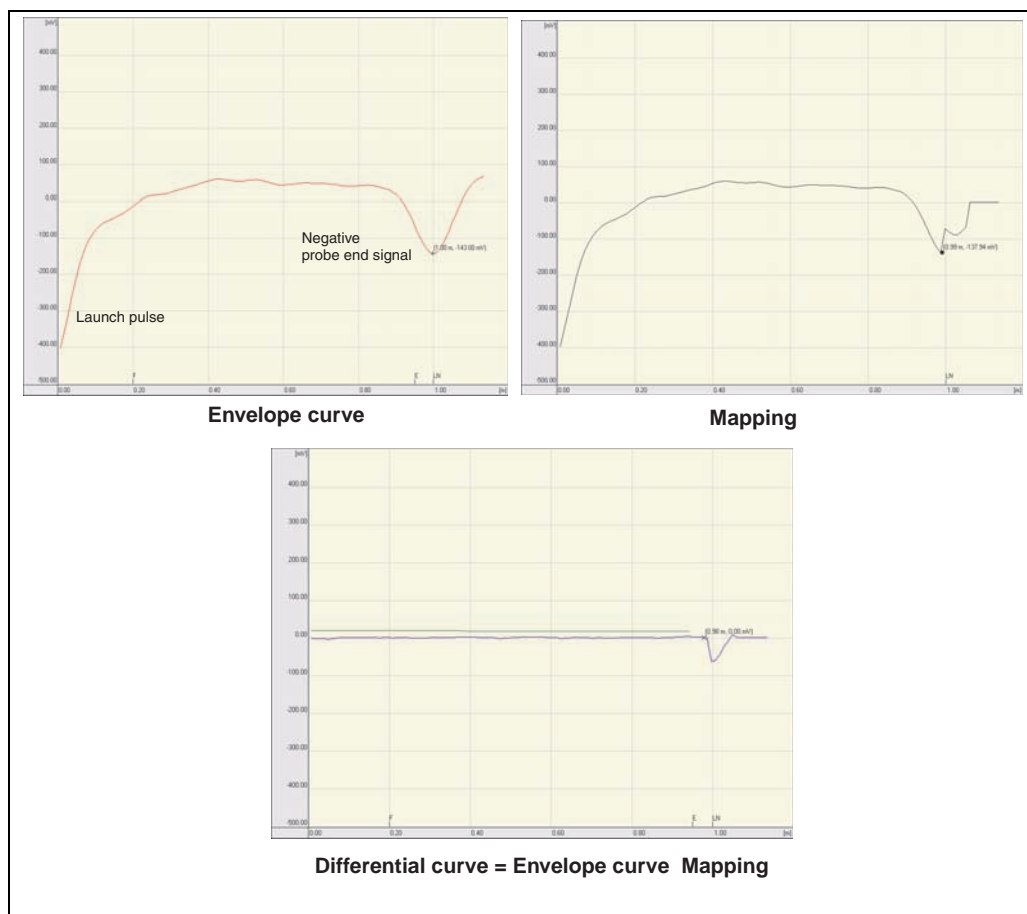
The following examples display typical curve shapes for a rope or rod probe in an empty tank. For all probe types, a negative probe end signal is shown. For rope probes, the end weight causes an additional preliminary positive echo (see rope probe diagram).



Level echoes are detected as positive signals in the envelope curve. Interference echoes can be both positive (e.g. reflections from internals) and negative (e.g. nozzles). The envelope curve, the map and the differential curve are used for the evaluation. Level echoes are searched for in the differential curve.

Evaluation of the measurement:

- The map must correspond to the course of the envelope curve (for rod probes up to approx. 5 cm and for rope probes up to approx. 25 cm before the end of the probe) when the tank is empty.
- Amplitudes in the differential curve should be at a level of 0 mV when the tank is empty and lie within the span that is specified by the probe-specific blocking distances. In order to not detect any interference echoes, there must be no signals that exceed the echo threshold when the tank is empty.
- For partially-filled tanks, the map may only differ from the envelope curve at the position of the level echo. The level signal is then detected unequivocally as a positive signal in the differential curve. For detecting the level echo, the amplitude must lie above the echo threshold.



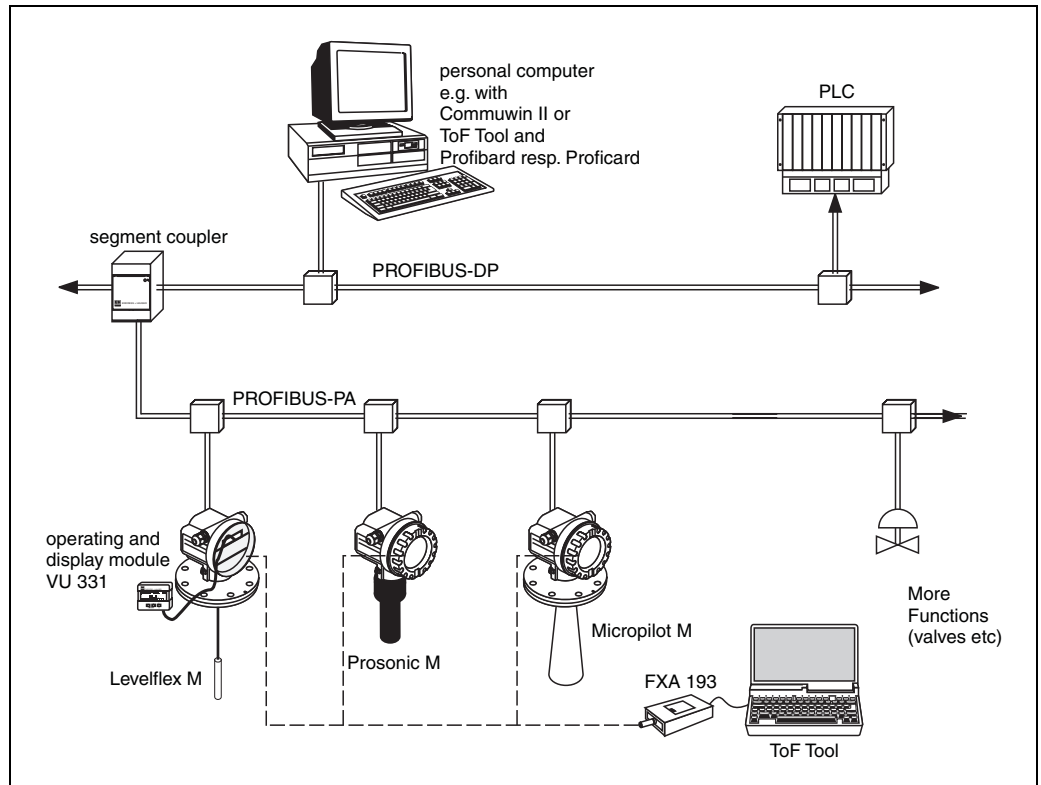
11.4.2 Equipment architecture

Stand-alone

The Levelflex M can be used for measurement in a stilling well / bypass as well as in free space.

System integration via PROFIBUS-PA

The complete measuring system consists of:



On-site operation:

- with display and operating module VU 331,
 - with a Personal Computer, FXA 193 and the operating software ToF Tool.
- The ToF Tool is a graphical operating software for instruments from Endress+Hauser that operate based on the time-of-flight principle (radar, ultrasonic, guided micro-impulse). It assists with commissioning, securing data, signal analysis and documentation of the measuring point.

Remote operation:

with a Personal Computer, Profibard resp. Proficard and the operating software COMMUWIN II respectively ToF Tool.

This product may be protected by at least one of the following patents.
Further patents are pending.

- US 5,345,471 \approx EP 0 694 235 (under Licence)
- US 5,517,198 (under Licence)
- US 5,661,251 \approx EP 0 780 664
- US 5,827,985 \approx EP 0 780 664
- US 5,884,231 \approx EP 0 780 665
- US 5,973,637 \approx EP 0 928 974

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Declaration of contamination

Dear costumer,

Because of legal determinations and for the safety of our employes and operating equipment we need this "Declaration of contamination" with your signature before your order can be handled. Please put the completely filled in declaration to the instrument and to the shipping documents in any case. Add also safety sheets and/or specific handling instructions if necessary.

type of instrument / sensor: _____ serial number: _____

medium / concentration: _____ temperature: _____ pressure: _____

cleaned with: _____ conductivity: _____ viscosity: _____

Warning hints for medium used:

☐

radioactive

☐

explosive

☐

caustic

☐

poisonous

☐

harmful of
health

☐

biological
hazardous

☐

inflammable

☐

safe

Please mark the appropriate warning hints.

Reason for return:

Company data:

company:	_____	contact person:	_____
	_____		_____
	_____	department:	_____
address:	_____	phone number:	_____
	_____	Fax/E-Mail:	_____
	_____	your order no.:	_____

I hereby certify that the returned equipment has been cleaned and decontaminated acc. to good industrial practices and is in compliance with all regulations. This equipment poses no health or safety risks due to contamination.

(Date)

(company stamp and legally binding signature)



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