Part 2 Chapter 2

Technical Manual

NAVY TYPE ACB

600 FRAME SIZE

AIR CIRCUIT BREAKER

Westinghouse Type DBN-40S **Alternating Current**

WESTINGHOUSE ELECTRIC CORPORATION EAST PITTSBURGH, PENNSYLVANIA, U.S.A.

WESTINGHOUSE TECHNICAL MANUAL 35-224-C17

INDEX

Air Circuit Breaker

Navy Type ACB (Westinghouse Type DBN-40S)
600 Frame Size
10,000 Amp. A-C Interrupting Capacity
Basic Breaker-Westinghouse Electric Corp. Dwg. 48-J-811
BuShips Plan - DD828-S6202-902,366

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AIR CIRCUIT BREAKER NAVY TYPE ACB—WESTINGHOUSE TYPE DBN-40S

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A-2. CIRCUIT BREAKER DIMENSION PLAN

The drawing shown on Page 2 gives the outline dimensions for the Navy type ACB 600 frame size air circuit breaker, Westinghouse Corporation Type DBN-40S alternating current breakers.

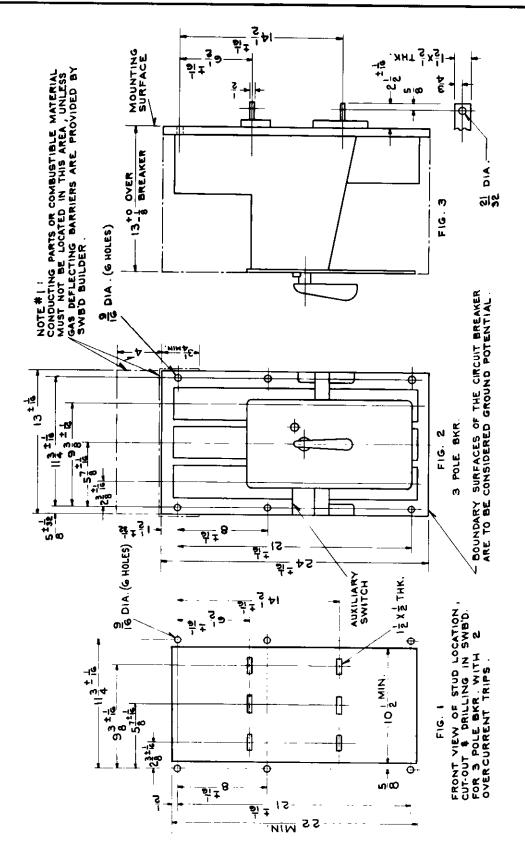


FIG. 1 — Outline Dimensions

SECTION B—GENERAL INFORMATION

B-1. MANUALLY OPERATED CIRCUIT BREAKER

The DBN-40S air circuit breaker is a sturdy compact piece of shipboard electrical equipment consisting of a rigid steel chassis to which are bolted the several sub-assemblies which make up the complete circuit breaker. For example, the mechanism, pole units, arc chutes, over-current trip devices and other attachments are each complete within themselves and are readily interchangeable between breakers. They may be removed intact and replaced if necessary with minimum outage time.

The DBN-40S is a type ACB air circuit breaker of 600 frame size. Its interrupting and continuous current ratings are as outlined in the following table:

INTERRUPTING RATING

10,000 Amperes R.M.S., 1000 Volts, 400 Cycles

CONTINUOUS CURRENT RATING

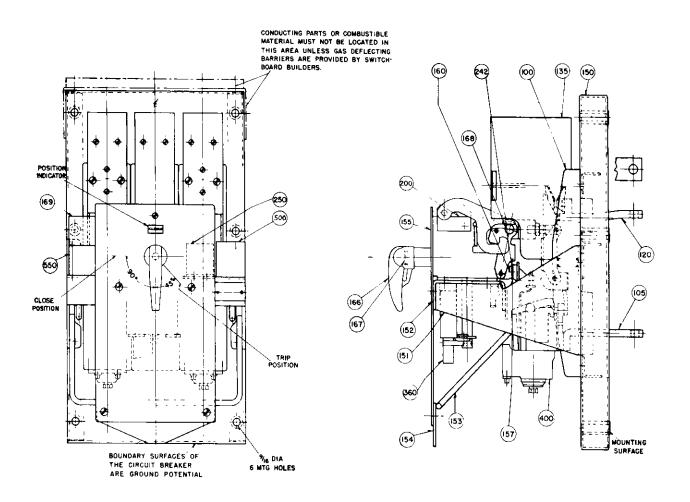
Circuit Breaker Copper Rating Amperes	Overc Trip Coi Amp	_
480	40	250
	50	320
	80	400
	100	480
	160	

The chassis of the breaker consists of a rigid steel panel (150) Fig. 2 on the front of which is bolted a supporting frame consisting of a bracket (151) which in turn supports shelf (152), brace (153), plate (154) and faceplate (155). A separate pole unit (100) is bolted to the steel

panel for each pole. The base of each pole unit is molded from insulating material. When supplied, the series overcurrent trip devices (400) are bolted to the lower part of the pole unit base. The moving contact assembly is pivoted at its lower end on the pole unit base and is connected to the lower stud either directly or through a series overcurrent trip device. The stationary contact assembly is connected directly to the upper stud. The moving contact assembly opens and closes the electric circuit by moving out and in from the stationary contact assembly. An arc chute is mounted above and surrounding each pair of contacts. Its purpose is to stretch and cool the arc drawn when the contacts separate so that it may be readily extinguished.

The operating mechanism (200) is located on the breaker shelf (152) and transmits the force for closing the breaker from the operating handle (166) to the cross bar (168) and thence to the moving contact assembly through insulating links. The mechanism then latches and holds the contacts in the closed position. The circuit breaker is closed manually by depressing handle latch and turning the operating handle (166) 900 clockwise and it may be tripped manually by turning the handle 450 in the opposite direction. Automatic tripping is accomplished by one of the automatic devices which lift the trip bar when suitably energized. These devices consist of the shunt trip (500) and the series overcurrent trip (400) either or both of which may be supplied with an individual circuit breaker.

The main power circuit through the circuit breaker consists of the lower stud, series over-current trip coil (if supplied), shunt, moving contact assembly, stationary contact, and upper stud, all connected in series in the order named.



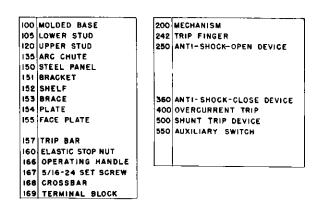


Fig. 2 — General Assembly

SECTION C—OPERATION AND MAINTENANCE

C-1. CAUTION

Before working on a circuit breaker be sure load and control circuits feeding the circuit breaker are thereby de-energized.

Before putting the circuit breaker in regular operation it should be closed and tripped while withdrawn manually several times to see whether all parts are in proper alignment and move freely. Particular care should be taken to make sure the studs have not been forced out of alignment by the bus work. Lift the trip bar by hand with the circuit breaker open to make sure that it does not bind.

C-2. WIRING DIAGRAMS

Figure 3 shows the typical wiring diagrams. For complete details refer to applicable diagram in the Switchboard Instruction Book.

C-3. SHUNT TRIPPING

Shunt trip coils have nominal voltage of 120 volts 60 cycles.

C-4. MAINTENANCE

The frequency of inspection for maintenance will depend upon local conditions but, in general, a complete inspection for preventive maintenance should be made at least once a year. It is recommended that a special inspection be given any breaker that has opened a heavy short-circuit current.

If excessive heating not caused by overcurrent is observed, look for loose or corroded contacts or connections.

When inspecting the circuit breaker, examine the contact surfaces. Rough or high spots should be removed with a clean file or sandpaper. Do not use emery cloth since the dust from this material is a good conductor of electricity and is sure to cause trouble if allowed to settle on insulating surfaces.

More detailed instructions are given later on in the sections on the individual attachments.

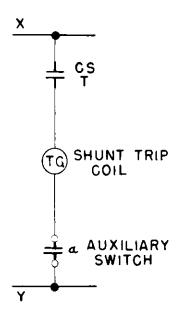


Fig. 3 — Wiring Diagram

SECTION D—COMPONENTS AND ATTACHMENTS

D-1. GENERAL ASSEMBLY (Manually Operated Breaker)

An air circuit breaker for three phase a-c service is normally provided with series over-current trip devices in the two outer poles only. Otherwise, all three poles are identical, each being provided with a stationary and moving contact assembly, and an arc chute.

D-2. ARC CHUTES

Reference Fig. 4

FUNCTION

The arc chute (135) mounted above and surrounding the contact assembly of each pole, has the function of stretching and cooling the arc drawn by the separating contacts so that it may be quickly extinguished and the circuit opened in the least possible time. The arc chutes are an extremely important part of the circuit breaker and the breaker should never be energized without their being mounted in place.

DESCRIPTION

Each arc chute consists of a number of metal plates (138) and (139) and asbestos plates (140) supported in a laminated case (135) and held in place by a clamping plate (136) and insulating tube spacers (146) and two screws (147) through the insulating spacers to the molded base (100). When the arc is drawn by the separating contacts, it moves up into the chute by magnetic and thermal action where it is quickly deionized and extinguished thus opening the circuit.

D-3. CONTACT ASSEMBLY

Reference Fig. 4

FUNCTION

The contact assembly closes and opens the electric circuit through the circuit breaker. The upper stud (120), the stationary contact (121), the series overcurrent trip device (400) (when supplied) and the lower stud (105) are stationary and are mounted rigidly on the molded base (100). The moving contact assembly is hinged on the molded base by pin (127) and is moved in and out by molded insulating link (116) which is pivoted on cross bar (168) Fig. 2.

The moving contact assembly is closed and held in the closed position against the force of the accelerating spring. (131) by the insulating link (116). When the force exerted by the insulating link is released by tripping the breaker, the accelerating spring quickly moves the moving contact assembly to the open position. When the breaker interrupts high short circuit currents, magnetic forces play a large part in the rapid opening of the contacts.

With the circuit breaker in the closed position, main contact surfaces (109) and (121) are held together and carry the load current. When the circuit breaker is tripped, arcing contact surfaces (119) and (123) snap together an instant before main contact surfaces (109) and (121) separate and then the moving contact assembly moves away, drawing the arc between the arcing contacts. This arrangement minimizes arc damage to main current carrying contacts. When the circuit breaker is closed the arcing contact surfaces touch first and then separate as the main contacts touch and the closing operation is completed.

DESCRIPTION

The stationary contact assembly consists of the main contact extruded integral with the upper stud (120) and the arcing contact (123) fastened to the extruded copper section by two screws (124). Contact surfaces (121) and (123) are special arc-resisting silver alloy inserts.

The moving contact assembly consists of a contact base (110) of copper to which is fastened arcing contact (118) by two bolts (112) which are locked with locking clips (113). Main and arcing contact surfaces (109) and (119) are silver alloy inserts welded to their respective Contact base (110) is riveted and soldered to shunt (108) which is bolted at its lower end either to a connector (133) when a series overcurrent trip device is not supplied, or to an overcurrent tripping device. The shunt (108) is a flexible bundle of thin copper strips that carries current from the moving contact assembly to the lower stud. Contact base (110) is connected to contact link (106) with pin (115) and has a limited freedom of rotation about this Contact link (106) is hinged by pin (127) to bracket (125) fastened to molded base (100) by two screws (128). Pin (130) mounted in bracket (125) has the function of restraining shunt (108) when the circuit breaker is tripped.

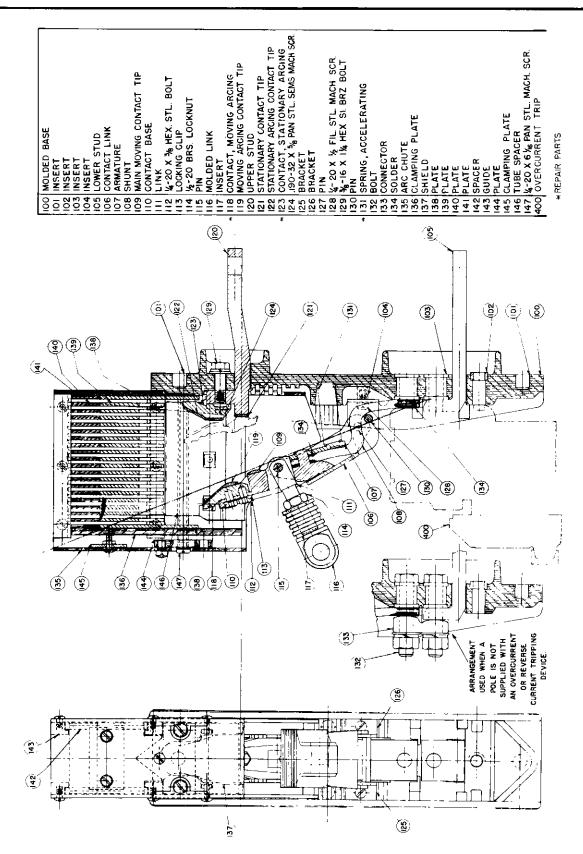


Fig. 4 — Arc Chute and Contact Assembly

The moving contact assembly is attached to the mechanism cross bar (168) Fig. 2 by molded insulating link (116) which is screwed on metal link (111) and locked by nut (114). When the breaker is tripped all force is removed from the cross bar and accelerating spring (131) quickly snaps the moving contact assembly from the closed to the open position.

ADJUSTMENTS

The correct contact pressure of the DBN-40 is about 50 pounds. This pressure is obtained when the arcing contact surfaces are 3/32 inch apart when the breaker is closed. This gap may be adjusted after removing arc chute (135) by removing two screws (147) and cross bar (168). Loosen locknut (114) and turn insulating link counterclockwise if the gap is too small and clockwise if the gap is too large. The locknut should be retightened and the cross bar and arc chutes replaced.

REPLACEMENTS

To replace moving arcing contact (118):

- (a) Remove arc chute (135) by means of screws (147).
- (b) Bend down locking clips (113) and remove bolts (112). When replacing bolts be sure to relock them by bending up corners of clips.

To replace stationary arcing contact (123):

- (a) Remove arc chute (135) by removing screws (147).
- (b) Removing screws (124) frees the contact.

To replace contact arm accelerating spring (131):

- (a) Remove arc chute (135) by removing screws (147).
- (b) End of spring may be slipped off projection on contact arm and replaced.

D-4. MECHANISM

Reference Fig. 5

FUNCTION

The operating mechanism opens and closes the circuit breaker contacts by moving the cross bar (168) Fig. 2 to which the moving contact assemblies are attached by insulating links. The DBN-40 is closed manually by depressing handle latch and turning the operating handle quickly and smoothly as far as it will go (90°) in a clockwise direction. The breaker may be tripped manually by depressing handle latch and turning the handle 45° in a counterclockwise direction. The breaker is tripped automatically by one of the automatic devices described later which rotate trip lever (220) about pin (224).

The mechanism is "trip free", that is, it is not possible to close the breaker if one of the automatic tripping devices moves the trip bar up during the closing stroke or if the trip bar is held in the raised position.

DESCRIPTION

The operating mechanism consists of a group of toggle links, and a latch attached to the operating mechanism frame on fixed pins (214), (226), (241), (216), and (224). The cross bar (168) is held by the closing lever (207). Rotating the operating handle clockwise moves the mechanism linkage from the open position shown to the closed position. This is accomplished when the roller (236) on the end of the operating handle shaft (232) forces the first toggle link (203) upward pushing second toggle link (204). third toggle link (206) and closing lever (207) ahead of it. The motion of the toggle linkages is directed by link (205) which is pivoted at its lower end on pin (217) in latch (208). Latch (208) in turn is restrained from moving by roller latch (210) which is pivoted on pin (214) and engaged trigger (221) on trip lever (220). The linkage is held in the closed position by pawl (209) which latches under pin (227). The handle shaft and lever are returned to the normal position after closing by handle return spring (233).

The mechanism is opened by rotating trip lever (220) counterclockwise. This is accomplished either by rotating handle counterclockwise, in which case the handle shaft lever strikes the extreme left end of trip lever (220) to move it downward; or by forcing push rod "E" of the tripping attachments to strike trip finger screw (243). In either case the counterclockwise rotation of the trip lever (220) moves trigger (221) out of engagement with the lower end of the roller latch (210), which in turn permits the roller latch to rotate counterclockwise out of engagement with latch (208). Latch (208) is then free to rotate in response to the pull of the latch link (205) so that the mechanism assumes the trip free position in which the contacts are open but part of the mechanism levers are in the closed position. In this position pawl (209)

	O MECH, FRAME	-	FIRST TOGGLE	A SECOND TORS E	LINK	۱ ۲	CLOSING LEVER	LATCH	9 8	Œ	2	<u>. </u>	3 SPACER	N.	5 SPRING, L.H. PAWL	2 2 0 1	. 0	 	TRIGG	2 SPRING PLATE STOP	SPRING ROLLER	PIN	S	σ.	NIA	= 0			2 SHAFT	SPRING,	SPRI	LEVER	S KOLLEK 7 NEED: S DEABING	7 K C L	: 8	S	N N		5724 AFT	ANTI- B	LATCH, HANDLE	7 ISPRING, HANDLE LATCH
L	88		36	3 6	9 0	200	207	ន	8	_	_	_	_	_	2 2			 22	2 !	22.5	22	22	22	226	55	Ñ	2 2 2	Ś	23	Ŕ	234	Š i	, k	3 6	100	42	24	24	7 G	245	246	24
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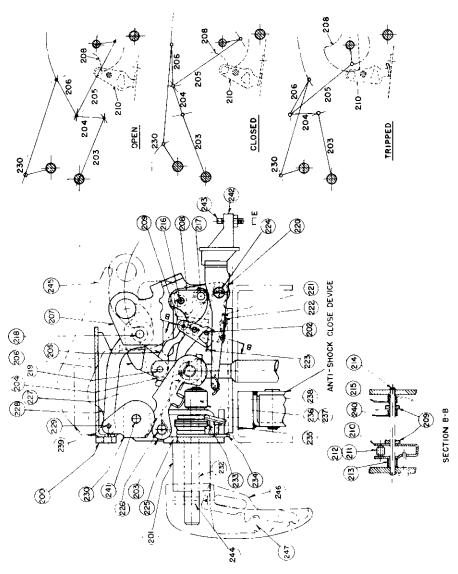


Fig. 5 — Mechanism

is disengaged from pin (227) by a lug on link (204) which pushes it up permitting the linkage to collapse to the open position. Trip spring (234) returns operating handle to the normal vertical position after manual tripping.

ANTI-BOUNCE LATCH

The anti-bounce latch (245) prevents the closing lever (207) from bouncing off its stops and re-closing the circuit when the circuit breaker interrupts maximum short circuit currents. When the circuit breaker interrupts these high currents, the crossbar knocks the latch up, causing the latch to engage the crossbar should it tend to return to the closed position. The latch is pivoted on the side of the mechanism frame.

POSITION INDICATOR

Position indicator (230) is formed from sheet metal and is pivoted on pin (241). It is visible from the front of the circuit breaker through a window in the faceplate and mechanism frame. With the circuit breaker in the open position the yellow face of the indicator shows through the window. The word "OPEN" is stamped on this yellow face. When the breaker closes, pin (218) of the closing lever (207) pulls indicator link (228) to the right, thus rotating the other face of the indicator up into a position visible through the window. This face is painted blue and is stamped with the word "CLOSED".

REPLACEMENTS

To replace roller latch spring (223):

- (a) Prepare to remove mechanism by removing anti-shock-open device (250), and auxiliary switch (550) all of Fig. 2. Avoid removing any more wires than necessary. It will usually be possible to push the devices aside without removing the wiring. Tag any wires which may have to be removed.
- (b) Rotate handle (166) clockwise until pin (277) is visible through a hole in the right side of the mechanism frame. Using a small rod as a pusher, shove this pin part way through the hole until the rod of the anti-shock-close device, in the case of manually operated circuit breakers, or the operating rod of the closing magnet, in the case of electrically operated circuit breakers, drops off. Return the pin (227) to its proper location and allow linkages to fall open. This

frees mechanism from anti-shock-close device or the closing magnet as the case may be.

- (c) Remove handle (166), faceplate (155) and cross bar (168) of Fig. 2.
- (d) Remove the four bolts which hold mechanism to the shelf. This frees mechanism from shelf but frees also either anti-shock-close device (360) of manually operated breakers or closing magnet (340) of electrically operated breakers.

These devices should be temporarily replaced while repairs are being made to the mechanism.

(e) Removal of pin (224) enables trip lever (220) to be removed and spring (223) may then be replaced.

To replace pawl springs (215) and (240):

- (a) Repeat (a) to (e) above.
- (b) Remove pin (214) far enough to release pawl (209). Roller latch (210) and hold-in which are pivoted on the same pin will then remain in place. Replace springs (215) and (240), making sure that their ends are supported correctly.

To replace trip spring (234) or handle return spring (233):

- (a) Repeat operations (a) through (e) under replacement of roller latch spring.
- (b) Remove pin (214) and drop pawl (209) and roller latch (210) out of frame.
- (c) Remove snap ring from handle shaft (232) and push the handle shaft back into frame. Spring (233) or (234) may then be replaced.

To replace retrieve spring (225):

- (a) Repeat operations (a) through (e) under "Replacement of Roller Latch Spring".
- (b) Remove cover (239).
- (c) Remove pins (241) and (226). Retrieve spring (225) may then be replaced.

When replacing mechanism springs, particular attention should be given to the mechanism drawing to see that spring ends are properly placed and that torsion springs are properly oriented to exert torque in the proper direction.

D-5. ANTI-SHOCK-CLOSE DEVICE

Reference Fig. 6

FUNCTION

This device serves to prevent the circuit breaker contacts from closing from shock when open. This is accomplished by an arrangement whereby a mechanical escapement device or "ticker" is operated by the closing of the breaker. Shock blows tending to close the breaker are of such short duration that the mechanical escapement device does not have time

to operate and the device effectively locks the open circuit breaker in the open position under shock conditions.

DESCRIPTION

The anti-shock-close device consists of a ticker case (360) which contains the ticker assembly, bolted to the platform by two bolts (379). A rod and cam pusher assembly (363) is connected at its upper end to pin (227) Fig. 5 of the mechanism. Whenever circuit breaker is closed, rod (363) is pulled up by pin (227) and cam (361) is caused to rotate in a clockwise

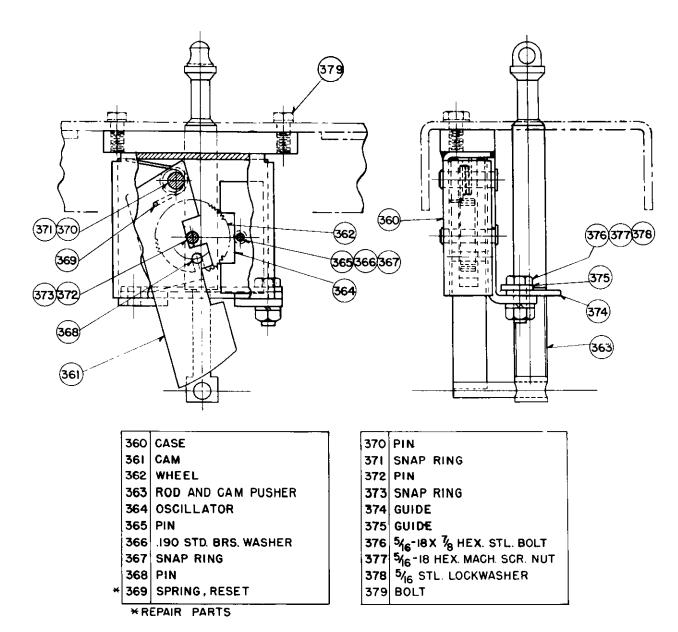


FIG. 6 — Anti-Shock-Close Device

direction around pin (370) against the torsion of return spring (369). As the cam rotates in this manner, oscillator wheel (362) is caused to rotate clockwise around pin (372) by pin (369) mounted in cam (361). The rotation of wheel (362) is regulated by mechanical oscillator (364) which is pivoted on pin (365). This oscillator oscillates due to the engagement of its teeth with the teeth of oscillator wheel (362). When the circuit breaker is tripped, rod (363) drops unimpeded and return spring (369) returns cam and consequently oscillator wheel to the "breaker open" position shown in the figure.

Shock blows tending to close the circuit breaker would have to act in such a way as to raise rod (363). These blows are of such short duration that the cam is restrained long enough by the oscillator to prevent closing of the circuit breaker.

REPLACEMENTS

To replace return spring (369):

- (a) Remove handle and faceplate.
- (b) Remove guide pieces (374) and (375) by removing bolt (376).

- (c) Remove bolts (379) and remove case (360) from shelf.
- (d) Removing snap rings (367), (371) and (373) will allow corresponding pins to be removed. The various parts are then free to be removed and the spring may be replaced.
- (e) After reassembly, be sure that the cam operates freely and that it returns freely to its starting position when pushed over.

D-6. ANTI-SHOCK-OPEN DEVICE

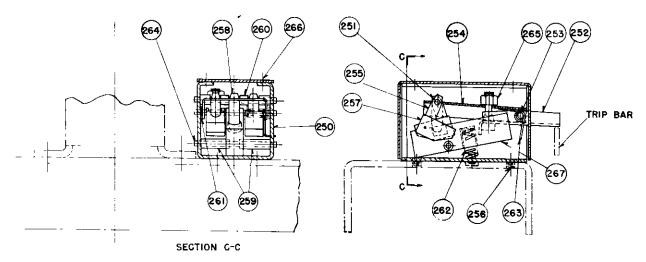
Reference Fig. 7

FUNCTION

This device prevents tripping of the circuit breaker due to rotation of the trip lever caused by shock but allows normal rotation of the trip lever by tripping devices.

DESCRIPTION

The bracket (250) is mounted on the supporting frame shelf to the immediate right of the operating mechanism frame (200) Figure 1



$\overline{}$			
250	ANTI-SHOCK	OPEN	BRACKET
251	PIN		
252	LEVER		
253	PIN		
254	PLATE		
255	STUD		
256	SCREW		
257	WEIGHT		
258	STUD		

	259	SPACER
	260	SPACER
	261	WASHER
×	262	SPRING WEIGHT
₹	263	SPRING PLATE
	264	PIN
	265	4-20 ELASTIC STOP NUT
	266	J64-32 X 4 FIL. HD. STL. MACH. SCR.
	267	WEIGHT

Fig. 7 — Anti-Shock-Open Device

quick reset is desirable. As diaphragm assembly (412) comes down, air is expelled thru port to bottom of long delay valve (416). Pressure moves disc (418) down providing a large opening for the expelled air. Spring (419) returns the disc to the sealed position after reset is completed.

REPLACEMENT

Although repair part springs are supplied, they should be used only in an emergency. The overcurrent trip device should be returned to the factory for calibration.

D-8. AUXILIARY SWITCH

Reference Fig. 9

FUNCTION

The auxiliary switch is used to close or open auxiliary or control circuits. The closed or open positions of its sets of contacts are coordinated with the closed or open position of the main circuit breaker contacts.

DESCRIPTION

The four pole type RC auxiliary switch is mounted on the top of the supporting frame shelf to the left of the operating mechanism. It is operated by shaft (555) and arm (557) which connects to the breaker lever of the operating mechanism. An eight pole auxiliary switch consists of two four pole switches, one mounted above the other.

The contacts are designed to carry 15 amperes continuously or 250 amperes for three seconds.

The interrupting capacities of the auxiliary switch contacts are as follows:

Volts	Non-Inductive Circuit	Inductive Circuit
125 DC	11 Amps.	6.25 Amps.
250 DC	2 Amps.	1.75 Amps.
115 AC	75 Amps.	15.0 Amps.
450 AC	25 Amps.	5.0 Amps.

For the purposes of this table, an "inductive" circuit is considered to be a bell alarm or shunt trip circuit and a "non-inductive" circuit is considered to be a resistance type indicating light or similar circuit.

The auxiliary switch is a shaft-operated, four pole, rotary type having "a" and "b" contacts. An "a" contact is one that is open when the circuit breaker is open, and a "b" contact is one that is closed when the circuit breaker is open.

A square shaft (555) extends through the rotor molds (560) which in turn insulate and support the rotor contacts (562). The rotor assembly is clamped together into a solid unit by screw (564). The rotor contacts are set 60° apart for 60° rotation of shaft (555).

Contact fingers (553) have one end hooked into stem (551) with spring (554) maintaining pressure between the finger contact and stem. The center of the contact finger bears against a stop surface in casing (550) to position the outer end of the contact finger.

ADJUSTMENT

The auxiliary switch is non-adjustable. However, it may be necessary to change from an "a" to a "b" contact or vice versa. This is accomplished as follows:

- (a) Remove switch from the supporting frame shelf as described under "a" and "b" or "Replacements".
- (b) Remove screw (564) and withdraw shaft (555) completely.
- (c) Lift the rotor assembly out of the casing, pull apart slightly at the rotor contact to be changed to disengage the positioning lugs turn the rotor contact 60° to line up with the adjacent contact and push the rotor assembly together to lock in place.
- (d) When replacing shaft (104) during reassembling, be sure that the crank portion is positioned exactly as removed relative to one of the unchanged contacts. This care is necessary as the shaft can also be reassembled when rotated either way 30°.

REPLACEMENT OF AUXILIARY SWITCH

- (a) Remove and tag the terminal connections.
- (b) Disconnect arm (557) from closing lever, remove the two mounting bolts and remove switch.
- (c) Remove link from closing lever and add new switch.

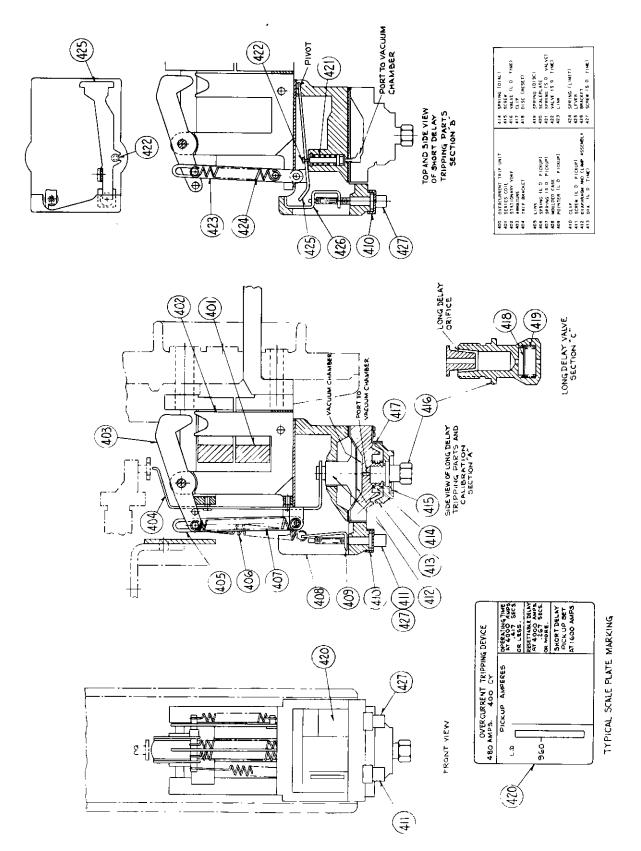


FIG. 8 — Series Overcurrent Trip Device

D-9. SHUNT TRIP DEVICE

Reference Fig. 10

FUNCTION

The shunt trip device serves as a means of tripping the circuit breaker from some remote point by the closing of a control switch or relay contacts at that remote point.

DESCRIPTION

The shunt trip device is mounted on the extreme right end of the supporting frame shelf. It consists of a frame, coil and moving core mounted horizontally. Energizing trip coil (513) causes a magnetic attraction between stationary core (503) and moving core (504) which causes moving core (504) to move to the left rotating trip lever (501) about pin (502). Lever (501) raises trip bar (157) Fig. 2 to trip the circuit breaker. The opening of the circuit breaker de-energizes the shunt trip coil through an "a" contact of the auxiliary switch. Spring (508) returns moving core (504) to its normal position. Non-magnetic washer (510) prevents residual magnetism from holding the cores together when the coil is de-energized.

REPLACEMENTS

To replace coil (513):

- (a) Disconnect the shunt trip leads from the auxiliary switch and cut-off switch.
- (b) Take out the two bolts (515) and remove the shunt trip assembly from the supporting frame.
- (c) Remove pin (502) and screws (509) holding plate (505) in place and drop out the moving core (504), stationary core (503) and sleeve (507). The coil is then free to be replaced.

To replace spring (508):

- (a) Repeat operations (a) and (b) above.
- (b) Remove pin (502) and replace spring (508).

D-10. REPAIR PARTS

Potential coils, springs, arcing contacts, and auxiliary switches are supplied as spare parts. Refer to Fig. 11 for identification.

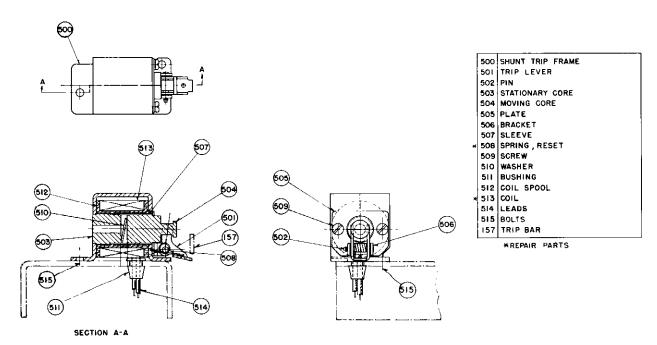


Fig. 10 — Shunt Trip Device

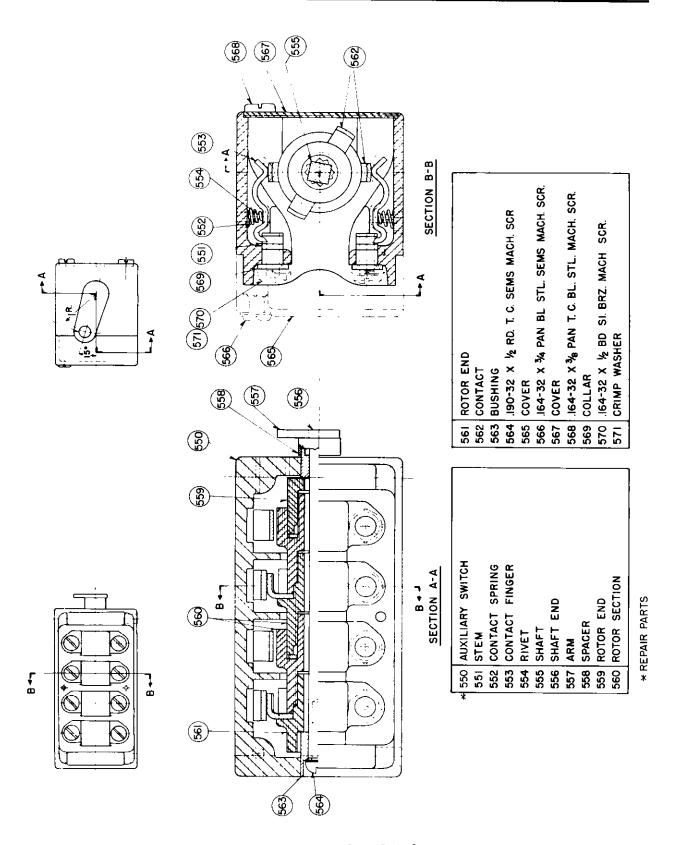


Fig. 9 — Auxiliary Switch

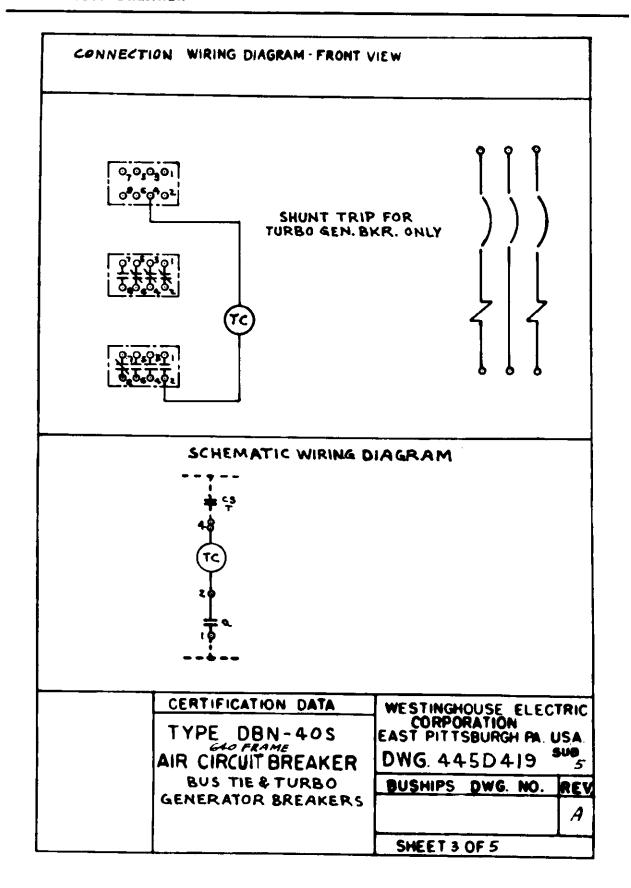
	CERTIFICATION DATA FOR CIR	CUIT BREAKERS
A.	MASTER DRAWING DD828-56202-902	-366 REVISION 1
	MFR'S DRAWING NO. 48 J811	
C.	MASTER DRAWING FIGURES APPLICABLE T	O CONTRACT_1-3-4
	WIRING DIAGRAM SH	FFY 3
D.	APPLICABLE SPECIFICATION _MIL-C-17	7587 OF 27 OCT- 1953
	AND AMENDMENTS NAVY CONTRACT OR SHIPBUILDER'S ORDER	OF
Ε	NAVY CONTRACT OR SHIPBUILDER'S ORDER	NO. SEE SHEET !
F.	MFR'S ORDER NO. SEE SHE	ETI
G.	CIRCUIT BREAKER TYPE AND FRAME SIZE-	
ш		MFR'S. DBN-405
П.	DESCRIPTION OF CIRCUIT BREAKER	C. COME MONUE
	VOLTAGE 1000V. 400 CYCLES MEANS OF NO. OF POLES 3 NO. OF OV	CLOSING MANUAL
	CONNECTIONS BACK MOUNTING	CTATIONARY
	AUXILLIARY SWITCH CIRCUITS 44-	4 b
	OVERCURRENT TRIPPING CURVE MFR	_ ·
I.	COIL RATINGS, PICKUP AND TIME SETTI	
	I. OVERCURRENT COIL BATING-AMPERE	
	2. LONG-TIME DELAY PICKUP SETTING-	
	3. SHORT TIME DELAY PICKUP SETTING-	AMPERES SEE SHEET 5
	4. SHORT TIME DELAY BAND SETTING	SEE SHEET 5
	5. INSTANTANEOUS PICKUP SETTING	SEE SHEET 5
	6. SHUNT TRIP COIL RATING -VOLTS	<u>₩ 120 V - 60 CY.</u>
	7. CLOSE COIL RATING - VOLTS	
	B. CLOSING RELAY COIL RATING-VOLTS	NONE
	9. REVERSE CURRENT TRIP SETTING - A	
	IO. REVERSE CURRENT POTENTIAL COIL-	- VOLTS NONE
K.	NUMBER OF SHIPS INVOLVED	SEE SHEET I
L.	NUMBER OF CIRCUIT BREAKERS PER SH	SEE SHEET 5
	TOTAL NO. OF CIRCUIT BREAKERS INVO	
N.	REPAIR PARTS	SEESHEET NO. 4
	ADDITIONAL DATA, REMARKS, NOTES	
	* SHUNT TRIP ON 35Y9083 (TURBO	
		·
┝一	CERTIFICATION DATA	1
	CERTIFICATION DATA	WESTINGHOUSE ELECTRIC CORPORATION
l	TYPE DBN-40S	EAST PITTSBURGH PA USA
	640 FRAME	DIVID A A ED A LO SUB
	AIR CIRCUIT BREAKER	DWG 445D419 5
	BUS TIE& TURBO	BUSHIPS DWG NO REV.
	GENERATOR BREAKERS	
		SHEET 2 OF 5
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SSN	NAME	ORDER		NOBS	GEN	ORDER	-	POR	DER	
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ACKERMAN	1	CERTI	FICAT	ION DATA		,		SE EL	ECT	RIG
DO ANY SWAN	7-105	CERTI	FICAT	ION DATA		WESTINGO		SE EL		
ACKERMAN	7-105	TYPE	DE 40 FA	ION DATA		WESTIN CO	GHOU RPOR TS BU			
ACKERMAN FREENT FREENT WEGGE 7 ETWORD	7-105 -11-58	TYPE	DE 40 FA	ION DATA BN - 40 S RAME IT BREA		WESTIN CO EAST PIT DWG.	GHOU RPOR TSEU 4-4-51	D41	9 5	UB 5
ACKERMAN	7-105 -11-58	TYPE AIR CI	DE 40 FA RCU	ION DATA BN - 409 KAME TURBO	KER	WESTIN CO	GHOU RPOR TSEU 4-4-51	D41	9 5	
ACKERMAN ENECHT WEARLY 7 ENWORLD 7	7-105 -11-58	TYPE AIR CI	DE 40 FA RCU	ION DATA BN - 40 S RAME IT BREA	KER	WESTIN CO EAST PIT DWG.	GHOU RPOR TSEU 4-4-51	D41	9 5	UB 5

Fig. 11 — Certification Data

					R	EPAIR PART	S LIST				
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ı	_	经	141 ESS		NAME	OF PART	WES	TING	HOUSE	STAND	ARD
	ITEM	33.44	20 OH				STYLE NO.	ITEN	DRAWING NO.	NAVY ST NO.	
	-	 				IOY-ARC.	1574789		18A3894		
ļ	2	*				AT. ARC.	1574797		21A3598		
ŀ	3		_		NG - AC		30D9774H	104	100 150		
ŀ	4	*				PRIEVE-MECH			13D6586		
ŀ	5	*	Ī			LER LATCH			21D7688	•	
ŀ	6	*			AG-PA		1718591		26D2190		
ŀ	7	*				IP-MECH. NDLE RETURN	1491444	+	13D3193	.	-
ŀ	8	**	4			T-A.S.CLOSE		+	13D3193		
ŀ	10	*	⊢÷.			T-A.S.OPEN		+	1806418	 	
ł	 	*				HT-A.S.OPEN		_	9D9236		
ł	12	*				IDLE LATCH			2107417		
	13	*				P-120V.60CY.		+	L-500045		
	14	*			NG - SH		1491282	+	17D1520		
1	15	*			CH-AL		405D2H6	41	7,2,320	 	
ł		*	_			P.UO.C.T.			 	†	
ł	17	*	8			VALVE-O.C.T.		\dashv	27D 3979		
ł	$\overline{}$	*					130A38OH	02	<u> </u>	†	
Ì	19	*	_			OLLOW-O.C.T.		—•—	<u>† </u>		
Ì	20	*	_			L- 0. C.T.			2107417	†	
Ì	21	*				T VALVE -O.C.T.		+	26D2192		·
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						N. BKR. ON 900J229		<u>'</u> Тна	SITEM	1	
					CER	TIFICATION	DATA	WE	STINGHO	USE ELEC	TRIC
					TY	PE DBN-	405	EAS	CORPO T PITTS BI	RATION URGH PA	
1				:	AIR (CIRCUIT B		DV	VG. 445	D419	SUB.
						S TIE & TUI		├ ──	HIPS DW		~ -
					·	RATOR BRE		PO:	DRIFS UN	<u> </u>	RE
					WENE	RAIUK BK	:AVEK?				A
1									SHEET	4 OF 5	Щ

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5HOP		BKKS			ING5 4	PICK	UP5
ORDER	BREAKER	PER SHIP		PELAY	SHORT DELAY PICKUP	BAND No.	INST. PICKUP
35 Y 9 0 8 3	TURBO- GEN. BKR.	2	480	960	1600	3	
35 Y 9 0 84	BUS-TIE BKR	2	480	720	1280	2	<u> </u>
							
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	CERTIFICAT	TION	DATA	Wās	TINGHO!	USE EL	.ECTRIC
				- 1	OKPORF	TION	
				EAST	ORPORA PITTSBO	TION IRGH PA	9.U-5.A.
	TYPE DI	BN-4	105	EAST	OKPORF	TION IRGH PA	9.U-5.A.
	TYPE DI 640 FA AIR CIRCUIT	BN·4 RAME BRE	105 AKER	EAST DWG	PITTSBO 2. 4451	ITION URGH PI D419	9. U-5 .A. 5UB. 5
	TYPE DE 640 FA AIR CIRCUIT BUS-TIE 4	BN·4 BRE TUR	105 AKER BO	EAST DWG	ORPORA PITTSBO	ITION URGH PI D419	9. U-5 .A. 5UB. 5
	TYPE DI 640 FA AIR CIRCUIT	BN·4 BRE TUR	105 AKER BO	EAST DWG	PITTSBO 2. 4451	ITION URGH PI D419	9. U-5 .A. 5UB. 5
	TYPE DE 640 FA AIR CIRCUIT BUS-TIE 4	BN·4 BRE TUR	105 AKER BO	EAST DWG BUSH	PITTSBO 2. 4451	NTION URGH PA D419 VG. NO.	9. U-S .A. SUB. 5