

**Model AD114
CAMAC 16K ADC
Operating and Service Manual**

Advanced Measurement Technology, Inc.

a/k/a/ ORTEC®, a subsidiary of AMETEK®, Inc.

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SAFETY INSTRUCTIONS AND SYMBOLS

This manual contains up to three levels of safety instructions that must be observed in order to avoid personal injury and/or damage to equipment or other property. These are:

DANGER Indicates a hazard that could result in death or serious bodily harm if the safety instruction is not observed.

WARNING Indicates a hazard that could result in bodily harm if the safety instruction is not observed.

CAUTION Indicates a hazard that could result in property damage if the safety instruction is not observed.

Please read all safety instructions carefully and make sure you understand them fully before attempting to use this product.

In addition, the following symbol may appear on the product:



ATTENTION—Refer to Manual



DANGER—High Voltage

Please read all safety instructions carefully and make sure you understand them fully before attempting to use this product.

SAFETY WARNINGS AND CLEANING INSTRUCTIONS

DANGER Opening the cover of this instrument is likely to expose dangerous voltages. Disconnect the instrument from all voltage sources while it is being opened.

WARNING Using this instrument in a manner not specified by the manufacturer may impair the protection provided by the instrument.

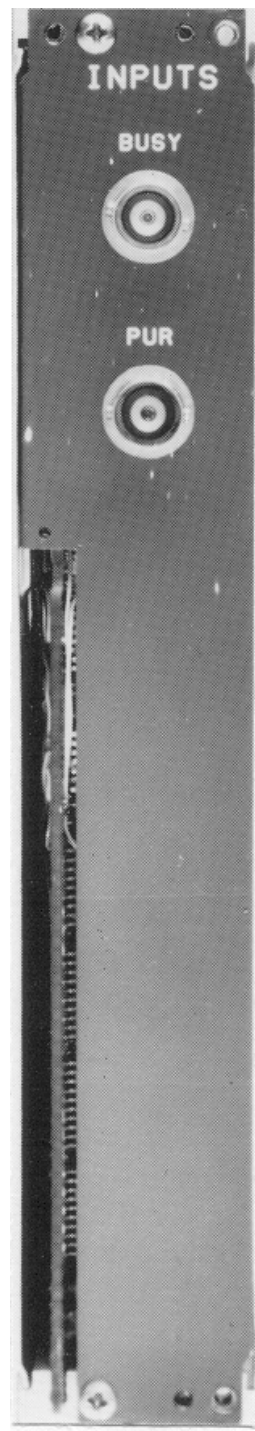
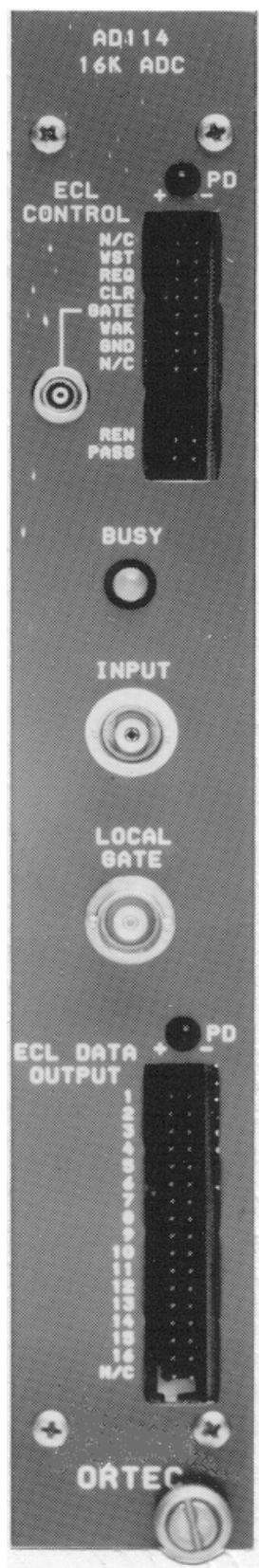
Cleaning Instructions

To clean the instrument exterior:

- Unplug the instrument from the ac power supply.
- Remove loose dust on the outside of the instrument with a lint-free cloth.
- Remove remaining dirt with a lint-free cloth dampened in a general-purpose detergent and water solution. Do not use abrasive cleaners.

CAUTION To prevent moisture inside of the instrument during external cleaning, use only enough liquid to dampen the cloth or applicator.

- Allow the instrument to dry completely before reconnecting it to the power source.



ORTEC MODEL AD114 CAMAC 16K ADC

1. DESCRIPTION

The ORTEC Model AD114 CAMAC 16K ADC is a 14-bit ADC with CAMAC and fast FERAbus readout. It is a very productive solution for high-multiplicity experiments with germanium detectors because it has a conversion time of 5 μ s and a 100-ns-per-word FERAbus readout with the ability to skip ADCs with zero information in 3 ns. This 16128-channel provides excellent peak definition when analyzing wide energy ranges with high-resolution germanium detectors. In fourfold coincidence experiments, a dead time as low as 15% for each detector channel results in a coincidence dead-time loss of 48%. Consequently, the live-time clock included in each Model AD114 is vital for calculating the true coincidence rate. The flexibility of the computer-controlled functions also makes the Model AD114 useful for surface barrier detectors, scintillation detectors, proportional counters, and ionization chambers.

The dc-coupled analog input employs a peak amplitude stretcher, and accepts pulses in the linear range from 0 to +10 V. A 14-bit, successive-approximation ADC with sliding scale linearization provides the conversion to a digital number in 5 μ s. The analog input accepts unipolar and bipolar pulses from standard spectroscopy amplifiers with shaping times from 0.25 to 20 μ s. A differential input is incorporated to suppress ground-loop noise when connected to systems with multiple power supplies and grounds. CAMAC control of the input dc-offset, the lower-level discriminator, and the upper-level discriminator facilitates computer adjustment of the analog operating parameters.

Several types of gating are provided. For coincidence experiments employing the FERAbus readout, the master GATE input is delivered to all ADCs through the ECL CONTROL bus. This gate synchronizes the ADCs on coincident events and forces all ADCs to wait for a common Clear at the end of event readout. In the CAMAC readout mode, the master GATE can be delivered to all ADCs as a TTL input on the front-panel LEMO connector. Using on the master GATE to define coincident events can lead to the random analysis of unrelated events at individual ADC inputs. These unwanted

events can be suppressed by providing a LOCAL GATE input to each ADC only when there is a valid coincident event at the ADC INPUT. The rear-panel PUR input is an anticoincidence gate for use with the pile-up rejector logic pulse from a spectroscopy input. CAMAC commands permit enabling and disabling the module's response to the master GATE or the LOCAL GATE input. This is useful when selecting the coincidence mode or the singles mode for the Model AD114 under CAMAC control.

Additional modes selectable by CAMAC command are: CAMAC or FERAbus readout, zero-suppression or no zero-suppression during readout, overflow-suppression, and singles or coincidence analysis.

Each Model AD114 includes its own live-time clock for correction of dead-time losses. The Gedcke-Hale live-time clock* corrects for the pile-up losses occurring in the spectroscopy amplifier, and for the dead time of the ADC conversion and readout. It provides complete dead-time correction for amplifiers directly presenting their unipolar output pulse, and/or amplifiers providing the appropriate BUSY and PUR logic signals. Via CAMAC commands, the live-time clock can be reset, started, stopped, and read without stopping.

The Model AD114 is compatible with the standard LeCroy FERA control and data output busses. This system can provide very fast readout of the ADCs with non-zero events in a CAMAC crate full of ADCs. For both data acquisition and readout, the control bus synchronizes all ADCs with the experiment's master trigger. This permits identification of all the ADC outputs from the same event and their subsequent assimilation into a common block of data. To the standard FERAbus features, ORTEC has added the ability to select the singles or coincidence analysis mode for any Model AD114. This feature allows checking the

*Ron Jenkins, R.W. Gould, and Dale Gedcke, **Quantitative X-Ray Spectrometry** (New York: Marcel Dekker, Inc.), 1981, pp. 266-267.

functionality of a detector via the singles spectrum at any time during an experiment. The Model AD114 can be mixed with the ORTEC Model AD413A in the same FERAbus readout loop.

Normally, all the ADCs in the crate are connected to a LeCroy Model 4301 FERA Driver for control and readout (Fig. 1 on page 8). The FERA Driver,

in turn, delivers the data to either a LeCroy Model 4302 Dual Port Fast Memory in CAMAC, or a CES Model HSM8170 High Speed Memory in VMEbus. Both memories operate in the list mode to assemble the block of coincident events for further processing by an event builder.

2. SPECIFICATIONS

2.1. PERFORMANCE

ADC ANALOG INPUT Accepts analog input pulses in the range from 0 to +10 V. The peak amplitude of an input pulse is converted to a digital value by a successive-approximation ADC with sliding scale linearization.

RESOLUTION 16,128 channels (0.625 mV/channel).

CONVERSION TIME 5 μ s.

INTEGRAL NONLINEARITY $<\pm 0.025\%$ over the top 99% of the dynamic range.

DIFFERENTIAL NONLINEARITY $<\pm 1\%$ over the top 99% of the dynamic range.

TEMPERATURE SENSITIVITY 0 TO 50°C.

Gain <50 ppm/°C.

Zero Offset <50 ppm of full scale per °C.

LOWER-LEVEL DISCRIMINATOR RANGE CAMAC controlled from 0 to 512 mV (2 mV/bit).

UPPER-LEVEL DISCRIMINATOR CAMAC controlled from 8.5 V to 10.5 V (8 mV/bit).

DC-OFFSET RANGE CAMAC controlled adjustment of input dc-offset from -40 mV to +40 mV (0.312 mV/bit).

LIVE-TIME CLOCK CAMAC controlled Gedcke-Hale Live-Time Clock* with a maximum count of 167772.16 seconds (1.94 days) and a resolution of 10 ms. Readable without interruption.

CAMAC CONTROL OF READOUT MODES Selection of: CAMAC or FERAbus (ECL bus) readout, sequential readout of all ADCs or suppression of ADCs with zeros (zero-suppression mode), overflow-suppression option, and singles or coincidence modes.

READOUT TIME

Zero-Suppressed Readout Mode Two words at 100 ns per word for FERAbus readout, or at 1 μ s per word for CAMAC readout.

Sequential Readout Mode One word at 100 ns per word for FERAbus readout, or at 1 μ s per word for CAMAC readout.

2.2. CONTROLS AND INDICATORS

BUSY Front-panel, multi-color LED, indicates the percent of the time the ADC is busy. LED appears green for 0-40%, yellow for 40-70%, and red for >70% busy.

PD Two front-panel red LEDs, one for the ECL CONTROL connector, and one for the ECL DATA OUTPUT connector. Turned on when the ECL pull-down resistors or termination resistors are installed for the respective connector.

2.3. INPUTS

INPUT Front-panel BNC connector accepts analog pulses for pulse amplitude digitization in the linear range from 0 to +10 V. Input signals can be positive unipolar pulses, positive gated integrator pulses, or bipolar pulses (with the positive lobe leading). Pulse shapes can be semi-Gaussian or triangular, with shaping time constants from 0.25 to 20 μ s, or delay-line-shaped with widths >0.25 μ s. Maximum input is ± 12 V. No internal delay. Center conductor input impedance is 2000 Ω to ground, dc-coupled. The floating BNC connector shield is used with a differential input amplifier to suppress common-mode input noise caused by ground loops. The common-mode rejection ratio is nominally 99:1 with a zero-impedance source, and nominally 22:1 with a 93- Ω signal source.

LOCAL GATE Front-panel BNC connector provides separate gating for the analog input. A low TTL logic level (0 to +0.8 V) prevents analysis of the analog signal at the INPUT connector; a high TTL logic level (+2 to +5 V) permits analysis of the analog signal. Resides in the high state with no input connected. The LOCAL GATE signal must be at the desired logic level prior to the peak amplitude of the analog pulse, and must extend $\geq 0.5 \mu\text{s}$ beyond peak detection. Input impedance is 1000 Ω . Response to the LOCAL GATE connector can be enabled/disabled by CAMAC commands.

GATE Front-panel LEMO connector accepts the master gate signal for coincidence mode operation with CAMAC readout. See ECL GATE for function. A low TTL logic level (0 to +0.8 V) prevents analysis, a high TTL logic level (+2 to +5 V) permits analysis. Resides in the low state with no input connected. Input impedance is 1000 Ω .

PUR Rear-panel BNC connector accepts the pile-up rejector logic signal from the spectroscopy amplifier supplying the analog input pulses. A high TTL logic level (+2 to +5 V) causes rejection of the analog signal; a low TTL logic level (0 to + 0.8 V) permits analysis of the analog signal. Defaults to a low state with no input connected. For required timing, see LOCAL GATE. Input impedance is 1000 Ω .

BUSY Rear-panel BNC connector accepts the Busy output logic signal from the spectroscopy amplifier supplying the analog input pulses. Either a high TTL logic level (+2 to +5 V) at the BUSY input, or the analog input pulse exceeding the ADC lower-level discriminator will cause the live-time clock to start counting backwards. The live-time clock turns off when the stretcher detects peak amplitude on the analog impulse, or when a PUR input occurs. The live-time clock resumes counting forward after BUSY, PUR, and the lower-level discriminator all become inactive, and readout of the conversion has been completed. The BUSY input is inactive at a low TTL logic level (0 to + 0.8 V) when no input is connected. Input impedance is 1000 Ω .

2.4. ECL INPUTS/OUTPUTS

The fast FERAbus readout utilizes the front-panel ECL CONTROL bus and the ECL DATA OUTPUT bus. Differential input impedances are 100 Ω with termination resistors installed. Only one module

should have the termination and pull-down resistors installed (See PD LED and Fig. 1).

ECL LOGIC LEVELS Nominal differential ECL logic levels (into 100- Ω differential load) are:

	Left (+) Pin	Right (-) Pin
Logic 0	-1.8 V	-0.9 V
Logic 1	-0.9 V	-1.8 V

ECL DATA OUTPUT Front-panel 17- by 2-pin connector (AMP 1-103326-7) provides the digitized ADC outputs for connection to the FERA data readout bus. Differential ECL outputs are employed, with bit 1 assigned to the two pins in row 1, and bit 16 occupying the two pins in row 16. Row 17 is not connected. See READOUT FORMAT. Interconnection between ADC modules and the FERA Driver (LeCroy 4301) requires construction of a 34-conductor ribbon cable (3M part number 3365/34) with 17- by 2-pin headers (3M 3414- 6006 or AMP 499498-9) spaced to match the configuration of modules (Fig. 1).

ECL CONTROL BUS Front-panel 8- by 2-pin connector accommodates the control bus for synchronizing data acquisition among multiple ADCs, and for ECL readout. Except where noted otherwise, the inputs to the AD114 are provided from the LeCroy 4301 FERA Driver connected to the bus. A row of two pins is assigned to each differential ECL input or output. Interconnection between ADC modules and the FERA Driver (LeCroy 4301) requires construction of a 16-conductor ribbon cable (3M part number 3365/16) with 8- by 2-pin headers (3M 3452-6006 or AMP 499497-3) spaced to match the configuration of modules (Fig. 1). The logic signals in the ECL CONTROL bus are listed below.

N/C No connection.

WST The Write Strobe output indicates when each output word is valid on the ECL DATA OUTPUT connector. WST is released 15 ns after the Write Acknowledge (WAK) is received.

REQ The Request output indicates that the module has completed its conversions, and is ready to take control of the ECL DATA OUTPUT bus for readout. REQ can be asserted only if FERAbus readout is enabled.

CLR Clears stored data and conversions in progress for all ADCs connected to the ECL CONTROL bus. Required in the coincidence mode

at the end of readout to simultaneously release all ADCs for the next conversion. CLR is not required in the singles mode. Minimum width, 5 ns. Clear can also be initiated from the CAMAC interface. If Clear is asserted during ADC conversion, up to 5 μ s are required to clear the module.

GATE The Gate input simultaneously provides the master gate signal to all ADCs connected to the ECL CONTROL bus for coincidence mode operation. The logic 1 state enables acceptance of the analog input signal for conversion, and forces all ADCs to wait for a common clear (CLR) after analyzing coincident events. With no signal connected, the GATE input remains in the logic 0 state. See LOCAL GATE for required timing. The ECL GATE input is OR'ed with the TTL GATE input from the LEMO connector. Response to the GATE input can be enabled/disabled by CAMAC commands.

WAK The Write Acknowledge input signal indicates through the readout controller (LeCroy 4301) that the associated memory has read the current word and that the next word may be sent. WAK minimum width is 30 ns.

GND Connected to ground.

N/C No connection.

REN The Readout Enable input is a front-panel, 1- by 2-pin connector. It accepts the PASS output from a previous module, or the REO output from the LeCroy 4301, to enable readout of the Model AD114. Interconnection requires construction of a 100- Ω , twisted-pair cable with a 2-pin socket and housing (AMP 1-87756-8 and AMP 5- 87456-3) on each end.

PASS The PASS output is provided on a front-panel, 1- by 2-pin connector. It indicates completion of the module's readout cycle on the ECL bus. The PASS output is normally connected to the REN input on the next module to enable readout of the next module (Fig. 1). In the zero-suppression mode, the Model AD114 generates the PASS signal typically within 3 ns of receiving the REN signal if the Model AD114 has no data to read out. The PASS signal from the last Model AD114 in the readout loop is used to generate the CLR signal via the external master trigger logic for the experiment and/or the LeCroy 4301.

2.5. CAMAC COMMANDS

- Z** Initializes module. Clears the module, sets all bits of control register to zero, sets LLD register to 36 (72 mV), sets ULD register to 255 (10.5 V), sets offset to 128 (0 V), enables the ADC (F(26)-A(0)), and clears the live-time clock.
 - C** Performs the same function as the CLR input.
 - I** Inhibits subsequent conversions and stops the live-time clock when asserted. Conversions and readouts already in progress are not affected. Used to start and stop data acquisition on all ADCs in the CAMAC crate at the same time.
 - X** Generated by the module for all valid functions.
 - Q** Generated by the module if the function can be executed.
 - L** Indicated LAM is set. Occurs after the end of conversion, if there are data to be read (provided CAMAC readout is enabled, and LAM is enabled). See CONTROL REGISTER FORMAT.
-
- F(0)-A(0)** Read Control Register.
 - F(1)-A(0)** Read lower-level discriminator (LLD) setting. The value returned is in units of 2 mV. Only the low 8-bits are valid.
 - F(1)-A(1)** Read upper-level discriminator (ULD) setting. Multiply the low 8-bits of the value read by 8 mV and add 8.5 V to calculate the voltage setting.
 - F(1)-A(2)** Read the input dc-offset setting. Subtract 128 from the lower 8 bits and multiply the resulting 8-bit number by 0.312 mV to calculate the voltage setting.
 - F(2)-A(0)** Read ADC converted digital output. If the zero-suppression mode is disabled (Control Register B9 = 1) and CAMAC readout mode is selected (B10 = 1), the command is issued once to read the ADC data. If zero-suppression is enabled with CAMAC readout mode

(B10 = 1), the command is issued twice, or until Q = 0. Q = 1 for a valid readout.

- F(3)-A(0)** Read low 16-bits of the live-time clock. The value is returned in units of 10 ms. When this command is issued, the highest 8 bits of the live-time clock are simultaneously captured and stored for a subsequent F(3)-A(1) command.
- F(3)-A(1)** Read the higher 8 bits of the live-time clock. This command reports the value of the higher 8 bits captured by the last F(3)-A(0) command.
- F(8)-A(0)** Test LAM. Q = 1 if LAM is present.
- F(9)-A(0)** Clear Module. Performs the same function as the C command, except only for the single module being addressed through CAMAC.
- F(10)-A(0)** Test and clear LAM. Q = 1 if LAM is active.
- F(12)-A(0)** Reset the live-time clock to zero.
- F(16)-A(0)** Write into the Control Register.
- F(17)-A(0)** Write LLD value. See F(1)-A(0) for format.
- F(17)-A(1)** Write ULD value. See F(1)-A(1) for format.
- F(17)-A(2)** Write input dc-offset value. See F(1)-A(2) for format.
- F(24)-A(0)** Disable ADC. Performs the same function as the Inhibit (I) command, but only for the addressed ADC. Stops the live-time clock and prevents conversions from occurring until F(26)-A(0) is issued.
- F(26)-A(0)** Enable the ADC. Enables conversions and starts the live-time clock when the Inhibit (I) command is not active.
- F(27)-A(0)** Test current status of ENABLE/DISABLE flag as set by the F(26)-A(0) and F(24)-A(0) commands. Q = 1 if the ADC enabled.

CONTROL REGISTER FORMAT

Bit	Function
B1 to B8	Virtual Station Number. Index Source for readout with zero-suppression. (Lower eight bits of header word.)
B9	Zero-suppression enable. When B9 = 0, ADCs with zeros for data are skipped during readout.
B10	ECL port enable. When B10 = 0, ECL port readout is enabled. When B10 = 1, CAMAC readout is enabled.
B11	Enable LOCAL GATE (B11 = 0). When B11 = 1, the LOCAL GATE input is ignored and all analog pulses are converted, unless gated by the master GATE or by PUR.
B12	Enable master GATE (B12 = 0) for the coincidence mode. When B12 = 1, the master GATE signal is ignored, and all analog pulses are converted, unless gated by LOCAL GATE or by PUR. B12 = 1 is used only in conjunction with the singles mode (B13 = 1).
B13	Selects the Coincidence mode or the Singles mode. When B13 = 0, the coincidence mode is selected. When B13 = 1, the singles mode is selected. When in the singles mode, the zero-suppression mode must be selected for all ADCs, if the FERAbus readout loop includes more than one ADC.
B14	Not used.
B15	CAMAC LAM enable. When B15 = 1, LAM is enabled.
B16	Overflow-suppression enable. When B16 = 0, overflows are converted to zeros in the ADC output data. Readout will be suppressed only if the zero-suppression mode (B9 = 0) is selected.

2.6. READOUT FORMAT

The readout format of the AD114 is identical in both the CAMAC and the FERAbus ECL readout modes.

WITHOUT ZERO-SUPPRESSION

B16	B15	B14 B1
0	0	DATA

WITH ZERO-SUPPRESSION

When zero-suppression is enabled and valid data are received, two data words are output. The first is always a Header word:

B16	B15	B14	B13 ... B12	B11	B10	B9	B8 ... B1
1	0	0	WRDCNT	0	0	0	VSN

Followed by one data record, with the following format:

B16	B15	B14 B1
0	0	DATA

DEFINITIONS

WRDCNT The word count defines the number of data records that follow the header word. The word count is always 01 for a Model AD114.

VSN The Virtual Station Number (0-255) identifies the module number during zero-suppressed readout. VSN is set via CAMAC command in the lower 8 bits of the Control Register.

DATA Fourteen bits of ADC conversion data. DATA over 16128 indicates overflow.

2.7. ELECTRICAL AND MECHANICAL

POWER REQUIRED The Model AD114 derives its power from a CAMAC crate supplying ± 24 V and ± 6 V. The power required is +24 V at 160 mA, +6 V at 1.4 A, -6 V at 0.9 A, and -24 V at 170 mA.

WEIGHT

Net 1.1 kg (2.5 lb).

Shipping 2.0 kg (4.5 lb).

DIMENSIONS CAMAC-standard double-width module, 3.42 × 22.15 cm (1.35 × 8.72 in.) front panel per IEEE/583-1975.

3. INSTALLATION

3.1. INSTALLATION IN CAMAC CRATE

The AD114 may be placed in any available slot in a CAMAC crate except for the slot which is reserved for the crate controller (usually slot 25). The power to the crate should *ALWAYS* be turned off when inserting and removing modules to prevent problems associated with momentary misalignment of the card edge connections.

With the power to the crate turned off, slide the module into any available slot and tighten the jack screw on the bottom front of the module to force the card edge connector into the CAMAC bus. The AD114 requires two CAMAC slots; however, the module responds only to CAMAC functions issued to the higher number slot. For example, if the AD114 occupies slots 10 and 11, the AD114 responds to commands issued to slot 11, but not slot 10.

3.2. AMPLIFIER CONNECTIONS

In a standard electronics setup, the AD114 has three connections to an associated amplifier. The input, on the front panel of the AD114, is normally connected to the output of the amplifier. The PUR input on the rear panel of the AD114, which is used to reject pulses that are too close together to be properly processed with the selected pulse shaping time, is normally connected to the amplifier pile-up reject output, labeled PUR or INHIBIT. The BUSY input on the rear panel of the AD114, which is used to provide proper live-time correction, is connected to the busy output on the amplifier. The following chart shows the normal connections to various ORTEC amplifiers.

AD114 Amplifier Connections

AMPLIFIER	IN	PUR	BUSY
ORTEC MODEL 572	UNI or BI	INH	BUSY
ORTEC MODEL 671	UNI or BI	PUR	BUSY
ORTEC MODEL 672	UNIPOLAR or BIPOLAR	PUR	BUSY
ORTEC MODEL 673	UNIPOLAR or GI	INHIBIT	BUSY
ORTEC MODEL 973	OUTPUT or GI	PUR	BUSY

If a transistor-reset preamplifier (TRP) is connected to the detector, PUR must be connected differently. If a Model 572 or 673 amplifier is used, connect PUR on the AD114 to the INHIBIT OUTPUT on the Model 132 inhibit generator, and connect INHIBIT on the amplifier to INHIBIT INPUT on the Model 132. If a Model 671, 672, or 973 amplifier is used, connect INHIBIT OUTPUT on Model 132 to INHIBIT INPUT on the amplifier, and connect PUR on the amplifier to PUR on the AD114.

If a Model FG424 fine-gain and offset controller is in the system, the amplifier output connects to the FG424 input and the FG424 output connects to the AD114 input. The PUR and BUSY connections are unchanged. Refer to the specifications in Section 2 for further details concerning the INPUT, PUR, and BUSY inputs.

3.3. ECL BUS (FERAbus) INSTALLATION

If *only* CAMAC readout will be used, and FERAbus readout will *not* be used, then ECL bus installation is not necessary.

An ECL bus interface is provided on the AD114 for high-speed readout of ADC data. The ECL bus is designed to permit multiple ADCs to be connected to the bus in parallel for readout of a large number of channels. A wiring diagram for a multiple ADC system is shown in Figure 1. Across the top of all modules is a control bus, which controls the readout process. The bus is formed from a 16-conductor ribbon cable with an 8- by 2-pin header mounted on it for each ADC. Located across the bottom of the modules is the ECL OUTPUT bus. This bus is formed with a 34-conductor ribbon cable with 17- by 2-pin headers mounted on the cable for each ADC. REN and PASS are normally connected as shown in Fig. 1.

In the first module in the chain, REN is connected to REO on the FERA driver. On the remaining modules, REN is connected to PASS from the previous unit. The PASS output on the final unit is normally connected to the Clear (CLI) input on the LeCroy 4301 FERA driver to clear the ADCs in preparation for the next coincidence event. In experiments with an event master trigger, the PASS output from the final AD114 may be sent through the master trigger logic to generate the Clear input for the FERA driver. The ORTEC Model AD413A can be mixed with the AD114 in the same

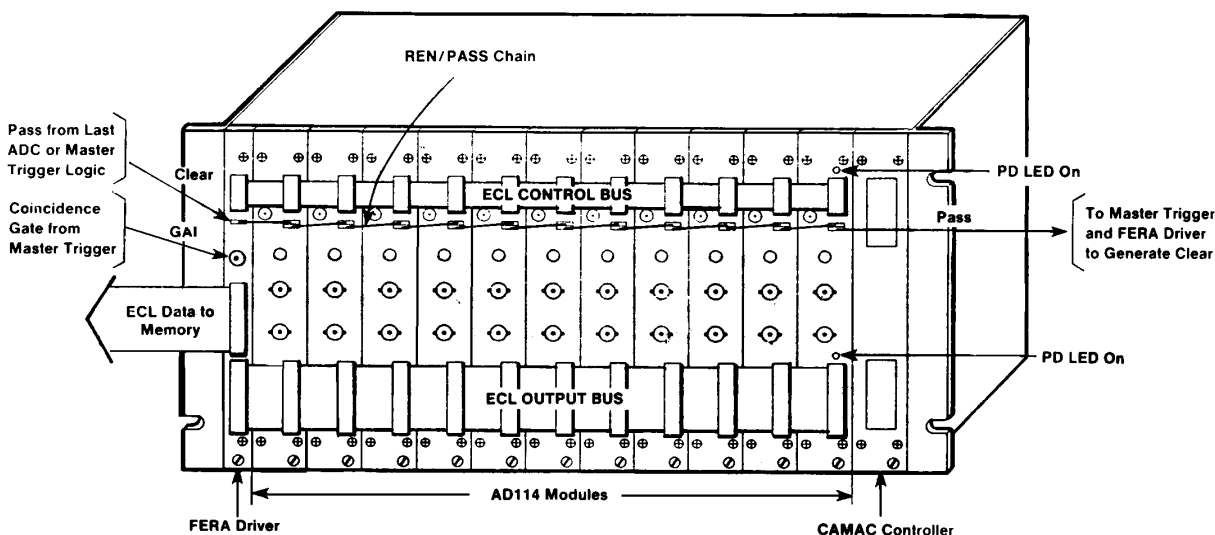


Fig. 1. Interconnection of Multiple Model AD114s and the LeCroy 4301 FERA Driver for FERAbus Readout.

FERAbus readout loop. The connections are the same. See Appendix A for information on cables.

3.3.1. ECL BUS RESISTOR PACKS

If an acquisition system makes use of multiple AD114 modules connected together with an ECL bus, the resistor packs must be removed from all except the last module in the chain of modules. The PD LEDs on the front panel of the AD114 are lit when the resistor packs are installed. Figure 1 indicates which module in a chain of modules should have the packs installed.

To remove the resistor packs from a module do the following:

1. Turn off power to CAMAC crate and remove AD114 module after disconnecting all cables.
2. Slide the left side plate back approximately 4 inches to reveal the components near the front panel of the module.
3. Locate resistor packs labeled RA3, RA4, RA5, RA6, RA7, RA8 and RA9 by referring to the Main Component Assembly Drawing at end of this manual. Remove the resistor packs from their sockets.

4. Store the resistor packs in a safe location, so they can be found and replaced, if necessary.
5. Close the side panel and return the module to the CAMAC crate.

Should it become necessary to replace the resistor packs once they have been removed, refer to Table 3.1 to determine which types belong in each location. Make sure to orient the resistor packs correctly before insertion into the socket. In the Main Component Assembly Drawing, pin 1 is indicated with a bar across the pack and a small "1". On most resistor packs, pin 1 is indicated with a dot.

Table 3.1. Resistor Pack Values.

Resistor Pack	Value (Ω)	No. of Pins
RA3, RA4, RA5, RA6	470	10
RA7	470	6
RA8	56	8
RA9	2200	6

NOTE: When reading values on resistor packs, 470 is often designated 471, 56 is often designated 560, and 2200 is usually designated 222.

4. OPERATION

4.1. LOWER-LEVEL DISCRIMINATOR

The Model AD114 has a programmable lower-level discriminator (LLD) setting. This voltage level determines the minimum amplitude pulse that will be accepted by the ADC. Normally the lower-level is set just above the level of the noise in the system, so time is not wasted converting noise pulses.

The lower level in the AD114 is set with the CAMAC command F(17)-A(0). An 8-bit value is written to the module during this CAMAC command specifying the voltage in units of 2 mV. A value of 50 in the lower-level register sets the voltage to 100 mV. The lower-level setting may be read with the F(1)-A(0) CAMAC command. The returned 8-bit value is also in units of 2 mV. When reading the lower-level setting, only the low 8 bits are valid. Any higher bits should be ignored. The high bits may be cleared by performing an AND function between the returned value and 255 decimal. (e.g., in

BASIC, INFO = INFO AND 255)

The CAMAC commands that change and report the lower level are active only when the ADC is not busy. The ADC is not busy after a clear command and before the peak of the next acceptable pulse after the clear. No Q response is given if the ADC is busy when the commands are issued. To guarantee that the ADC is not busy, set the CAMAC inhibit line (I) and clear the module (C command).

The initial setting of the lower-level voltage on initialization (Z command) is 36, which corresponds to 72 mV.

4.2. UPPER-LEVEL DISCRIMINATOR

The Model AD114 has a programmable upper-level discriminator (ULD) setting. This voltage level determines the maximum amplitude pulse that will be accepted by the ADC. Normally the upper-level is set just above the 10 V level, so time is not wasted converting over-range pulses.

The upper-level in the AD114 is set with the CAMAC command F(17)-A(1). An 8-bit value is written to the module during this CAMAC command specifying the voltage in units of 8 mV with an offset of 8.5 V. A value of 200 in the lower-level register sets the voltage to $8.5 + 0.008 \times 200 = 10.1$ V. The upper-level setting may be read with the F(1)-A(1) CAMAC command. The returned 8-bit value is also in units of 8 mV with an 8.5 V offset. When reading the upper-level setting, only the low 8 bits are valid. Any higher bits should be ignored. The high bits may be cleared by performing an AND function between the returned value and 255 decimal. (e.g., in BASIC, INFO = INFO AND 255).

The CAMAC commands that change and report the upper-level are active only when the ADC is not busy. The ADC is not busy after a clear command and before the peak of the next acceptable pulse after the clear. No Q response is given if the ADC is busy when the commands are issued. To guarantee that the ADC is not busy, set the CAMAC inhibit line (I) and clear the module (C command).

The initial setting of the upper-level voltage on initialization (Z command) is 255, which corresponds to 10.54 V.

4.3. PROGRAMMABLE DC-OFFSET

The Model AD114 has a programmable input dc-offset adjustment. This voltage level is summed with the input signal just before conversion of the signal. Normally the offset is set to 0 V. Setting the offset to a value other than 0 will have the effect of shifting the entire spectrum by the offset value. The offset voltage is set with the CAMAC command F(17)-A(2). An 8-bit value is written to the module during this CAMAC command specifying the voltage in units of 312 μ V with an offset of -40 mV. A value of 200 in the offset register sets the voltage to $-40 + 0.312 \times 200 = 22.4$ mV. The offset setting may be read with the F(1)-A(2) CAMAC command. The returned 8-bit value may be translated to voltage by subtracting 128 and then multiplying by 0.312 mV. When reading the offset setting, only the low 8 bits are valid. Any higher bits should be ignored. The high bits may be cleared by performing an AND function between the returned value and 255 decimal. (e.g., in BASIC, INFO = INFO AND 255).

The CAMAC commands that change and report the offset are active only when the ADC is not busy. The ADC is not busy after a clear command and

before the peak of the next acceptable pulse after the clear. No Q response is given if the ADC is busy when the commands are issued. To guarantee that the ADC is not busy, set the CAMAC inhibit line (I) and clear the module (C command).

The initial setting of the offset voltage upon initialization (Z command) is 128, which corresponds to 0 V.

4.4. LIVE-TIME CLOCK

The Model AD114 is equipped with a Gedcke-Hale Live-Time Clock which is 24-bits in length with a resolution of 10 ms. After the live time reaches 167,772.15 seconds (1 day, 22 hours, 36 minutes and 12.15 seconds), the live time returns to zero and starts over. The live time may be read by issuing the F(3)-A(0) and F(3)-A(1) commands. F(3)-A(0) returns the low 16-bits of the live time and also latches the high byte of the live time. F(3)-A(1) returns the high byte of the live time which was latched by the F(3)-A(0) command. If F(3)-A(1) commands are repetitively issued, they will always return the same value because no new data is being latched by the F(3)-A(0) command. When reading the high byte of the live time, only the low 8 bits of the returned word are valid. Any higher bits should be ignored. The high bits may be cleared by performing an AND function between the returned value and 255 decimal. (e.g., in BASIC, INFO = INFO AND 255).

The live-time clock may be set to zero with the F(12)-A(0) command or by initializing (Z) the CAMAC crate. The live-time clock may be paused by setting the inhibit line (I) in the CAMAC crate or by disabling the ADC (see Section 4.5.).

The CAMAC commands that report the live time are active only when the ADC is not busy. The ADC is not busy after a clear command and before the peak of the next acceptable pulse after the clear. A No-Q response is returned if the ADC is busy when the commands are issued. A No-Q response is also returned if the live-time clock was incremented 1 μ s or less before the F(12)-A(0) command is given. This prevents unstable data from being read. To guarantee a valid read, set the CAMAC inhibit line (I) and clear the module (C command) before reading the live time.

The Gedcke-Hale Live-Time Clock is intended for use with the unmodified, unipolar, analog output pulses from a spectroscopy amplifier. It uses the amplifier pulse shape information, along with the amplifier BUSY and PUR (pile-up reject) signals to

compensate for the dead-time losses caused by pile-up in the spectroscopy amplifier. In order to calculate the effective live time, the dead-time correction for pile-up losses in the amplifier is added to the correction for the AD114 conversion and readout dead time. When the counts in a full-energy peak in the energy spectrum are divided by the live time, the resulting counting rate is an accurate estimate of the true counting rate for that gamma-ray energy at the input to the preamplifier. The live-time clock works with unipolar pulse shapes from gated integrators, Gaussian shaping amplifiers, triangular pulse shaping amplifiers, and single-delay-line shaping amplifiers. Best results are obtained when the BUSY and PUR signals from the amplifier are connected to their respective inputs on the Model AD114.

The Gedcke-Hale Live-Time Clock works as follows. Either the leading edge of the BUSY signal from the amplifier, or the amplifier analog pulse exceeding the Model AD114 lower-level discriminator will cause the live-time clock to start counting backwards. The live-time clock turns off when the stretcher in the Model AD114 detects peak amplitude on the analog input pulse, or when a PUR input occurs. The live-time clock resumes counting forward after BUSY, PUR, and the lower-level discriminator all become inactive, and readout of the conversion has been completed. Turning off the live-time clock compensates for the probability of losing a second pulse after responding to the first pulse. Subtracting live time compensates for the probability of losing both the first and the second pulses from the full-energy peak in the spectrum, as a result of the second pulse piling up and distorting the peak amplitude of the first pulse. Turning off the clock compensates for losing one pulse, while counting backwards provides double weighting and compensates for the loss of two pulses.

The Gedcke-Hale Live-Time Clock will work with bipolar pulses, or with amplifiers that pass only a portion of their signal through a linear gate, if the appropriate signals are supplied to the AD114 BUSY and PUR inputs. The BUSY and PUR signals must accomplish the functions described in the paragraph above. See the ORTEC Model 675 Operating and Service Manual, for example.

4.5. ENABLE/DISABLE COMMANDS

The CAMAC commands F(24)-A(0), F(26)-A(0), and F(27)-A(0) control the DISABLE ADC signal in the AD114. The DISABLE ADC signal performs the

same function as the inhibit (I) signal in the CAMAC crate, but it only affects the addressed AD114. If the inhibit signal is set, all modules in the crate are inhibited. If the DISABLE ADC signal is set, only the AD114 which received the command is inhibited.

To disable the AD114, issue the F(24)-A(0) command. To enable the AD114, issue the F(26)-A(0) command. To determine the current state of the DISABLE ADC signal, issue the F(27)-A(0) command, if the AD114 is enabled, a Q = 1 response is generated; otherwise, no Q is generated.

When the AD114 is disabled, the live-time clock is paused and no pulses are accepted for conversion.

4.6. GATING SIGNALS

Three input signals are available to select which pulses are to be converted by the ADC: PUR, LOCAL GATE, and the master GATE. If any one of the signals indicates that the pulse is to be rejected, the pulse will be rejected. All three inputs are sampled approximately 100 ns after the peak of an input pulse; therefore, the gating signals should arrive before the peak of the pulse and extend at least 500 ns beyond the peak to ensure proper sampling.

PUR or pile-up reject is always active and is normally connected to the pile-up reject output on an amplifier associated with the channel. When the PUR input is high, pulses are not converted. The PUR input assumes a low state when no connection is made to the PUR input. The PUR input can also be used as a general-purpose veto or anticoincidence input.

LOCAL GATE is an individual gate input. The LOCAL GATE can be used in addition to the master GATE to ensure that each ADC accepts only pulses that are judged to be valid for that ADC input. LOCAL GATE may be disabled by setting the appropriate bit in the control word (see Section 4.7). If the LOCAL GATE is enabled, pulses are converted only if the gate signal is high. The GATE input assumes a high state when no connection is made to the GATE input.

The master GATE signal may be supplied via the ECL control bus or the LEMO connector on the front panel. Normally the master GATE is distributed to all ADC modules in a system. The master GATE signal not only provides a gating function, it also determines which pulses are to be grouped together as a coincident event. When the

master GATE is high, pulses are accepted into the AD114. When the master GATE returns low, no pulses are accepted into the ADC until a Clear command is given, even if the master GATE returns high. The master GATE may be disabled in the AD114 by setting bit 12 in the control word (see Section 4.7). Disabling the master GATE is invalid for coincidence experiments, because there is no signal to indicate which pulses belong in the coincident event. Disabling the master GATE is useful only when collecting singles spectra.

4.7. CONTROL REGISTER

The control register in the AD114 determines the various modes of operation. The control register specifies the virtual station number of the module as well as the readout modes, operation modes and which gating signals are to be enabled.

The Control register is loaded with the CAMAC function F(16)·A(0), and is queried with the CAMAC function F(0)·A(0). These CAMAC commands are active only when the ADC is not busy. The ADC is not busy after a clear command and before the peak of the next acceptable pulse after the clear. No Q response is given if the ADC is busy when the commands are issued. To guarantee that the ADC is not busy, set the CAMAC inhibit line (I) and clear the module (C command).

The lower 8 bits of the control register form the virtual station number for the module. The remaining bits in the control register have the following function:

Zero-Suppression Enable (Bit 9) Specifies zero-suppression readout mode as opposed to sequential mode (ECL PORT or CAMAC).

- = 0; Zero-suppression selected.
- = 1; Sequential selected.

ECL Port Enable (Bit 10) Specifies which readout port is to be used; CAMAC or ECL.

- = 0; ECL readout enabled.
- = 1; CAMAC readout enabled.

Enable LOCAL GATE (Bit 11)

- = 0; Front-panel LOCAL GATE enabled.
- = 1; LOCAL GATE disabled.

Enable MASTER GATE (Bit 12)

- = 0; Master GATE is enabled.
- = 1; Master GATE is disabled. This mode should not be selected while in the coincidence mode of operation

because the master GATE determines which pulses belong in an event. This mode should be used only in the singles mode.

Coincidence/Singles Mode Select (Bit 13)

Specifies coincidence mode or singles mode.

- = 0; Coincidence mode selected.
- = 1; Singles mode selected. See Section 4.10.

CAMAC LAM Enable (Bit 15) Specifies if LAM is to be asserted when data is ready to be readout on the CAMAC port.

- = 0; LAM is not asserted.
- = 1; LAM is asserted if CAMAC readout is selected.

Overflow-Suppression Enable (Bit 16) Specifies overflow-suppression mode.

- = 0; Overflow-suppression enabled. When used in conjunction with zero-suppression mode, pulses above the upper-level discriminator are not reported. When not in zero-suppression mode, pulses above the upper-level discriminator are reported as zero.
- = 1; Overflow-suppression disabled. All pulses above the upper-level discriminator are reported with a value between 16128 and 16383.

On power-up, the control registers have an undetermined value. If an initialize (Z) command is issued to the CAMAC crate, all bits of the control registers are set to zero.

4.8. CONVERTER OPERATION TIMING

Figure 2 illustrates the conversion and readout timing when a pulse is accepted into the module. The conversion process begins as soon as a peak detect occurs. The conversion phase then takes 5 μ s for a valid input. If an input is rejected by the upper-level discriminator, Pile-Up Rejector, the LOCAL GATE, or the lower-level discriminator, no time is required during T1 for that channel.

When the conversion phase completes AND the master GATE has returned low, the readout phase begins. The time required to read out depends on the readout method and the mode selected. See Fig. 2 for details.

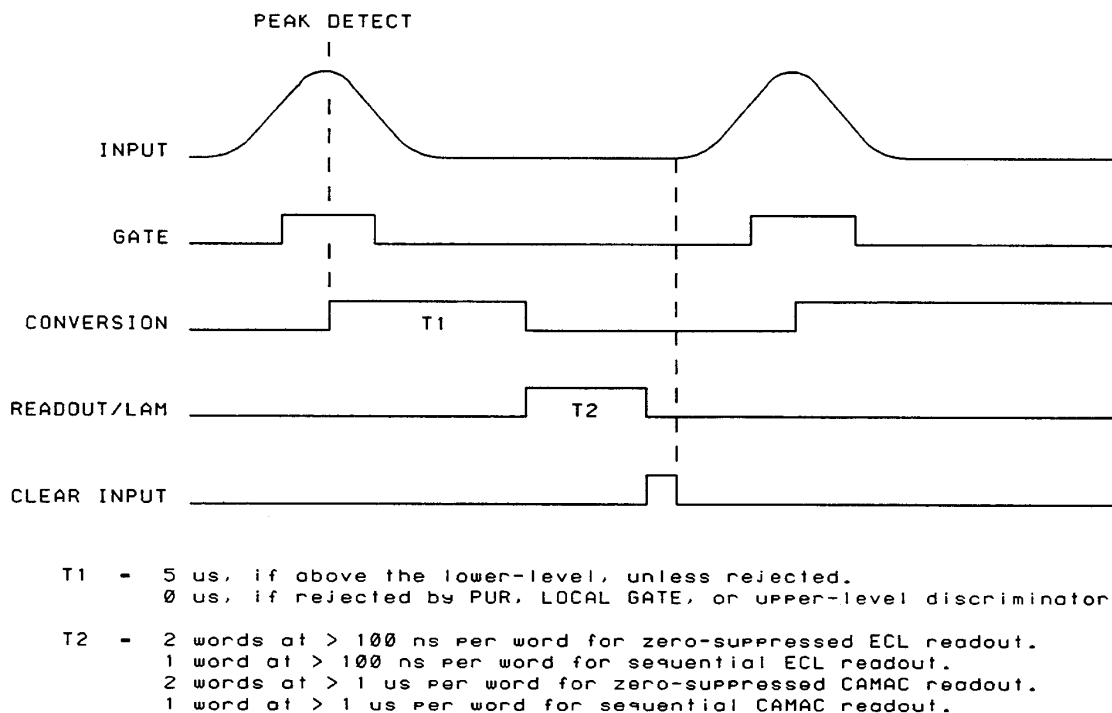


Fig. 2. Conversion Timing Diagram.

Once readout completes, a clear command must be issued by the readout electronics. Once the clear command is given, the ADC is ready for the next pulse.

If the Clear command is issued during a conversion, the conversion process must finish (T1) before the module can accept another input pulse.

4.9. READOUT PORT

Data from the AD114 can be read from either the CAMAC interface or the ECL BUS interface. The ECL BUS interface (FERAbus) is designed for high-speed readout, up to 10 MHz, and is suited for bussing many ADC modules together into a large system. However, additional external hardware (FERA drivers, FIFO memories, cables, etc.) is required to buffer the data and transfer it to permanent storage. When CAMAC readout is utilized, readout occurs at speeds a factor of 10 or more slower; however, performing the readout via CAMAC does not require any extra hardware to get data out of the ADC and into a host computer.

When the AD114 is initialized, the default readout method is the ECL BUS. To select the CAMAC option, bit 10 of the control register should be set high.

4.9.1. CAMAC READOUT

When CAMAC readout is selected, data is read from the ADC via CAMAC operations. Two modes exist for reading data from the module via the CAMAC interface: "zero suppression," and "sequential."

In zero-suppression mode, two data words are available to be read out when a valid pulse is received. The two words are read by issuing the F(2)-A(0) CAMAC command twice. The first output word is the header word that identifies the AD114, which is reporting data. The format of the header word is shown in Section 2.6. The data word follows the header. Issuing the F(2)-A(0) command a third time will result in a NO-Q response. If overflow suppression is enabled, no data is reported for an overflow. If overflow suppression is disabled, a value greater than 16128 is reported. Zero-suppression mode is enabled by setting bit 9 of control register 1 to 0.

When sequential readout mode is selected, there is always 1 data word to be read from the ADC after an event occurs (master GATE goes high, then low). The word is read by issuing the F(2)-A(0) CAMAC command. After the word has been read, Q = 0 occurs if the command is issued again. If no

pulse arrives during the gating time a zero will be reported. If overflow suppression is enabled, zero will be reported for an overflow. If overflow suppression is disabled, a value greater than 16128 is reported. Sequential readout is selected by setting bit 9 of the control register to 1.

Regardless of the readout mode selected, the module must be cleared after readout is completed to permit new conversions, unless singles mode is selected (see Section 4.10). The clear can be initiated with the global CAMAC clear function, or an addressed clear to a single module [F(9)].

If bit 15 in control register 1 is set, a Look-At-Me (LAM) signal is asserted by the module when data is ready to be read. The LAM will be cleared when the last data word is read. The LAM may also be cleared with the F(10)-A(0) command.

4.9.2. ECL PORT (FERAbus) READOUT

When ECL (FERAbus) readout is selected, data is read from the ADC via the front panel ECL DATA port. Multiple AD114 modules may be connected in parallel on the ECL bus for readout of a large number of channels. When multiple ADCs are connected to the ECL bus, a FERA driver module (LeCroy 4301 or CES 1570) is usually required to control the bus. Two readout modes exist for ECL readout: "sequential mode" and "zero suppression mode."

In sequential mode, one data word is available to readout after every event. When this mode is used, every AD114 module in the system will always report one data word when an event occurs (master GATE is asserted). The format of the data word can be found in Section 2.6. If overflow suppression is enabled, a zero is output in place of the overflow. If overflow-suppression is disabled, a value greater than 16128 is output in place of the overflow value. If no pulse occurs during the gating time or the pulse is rejected with the PUR, LOCAL GATE or lower-level discriminator, a zero is output during readout.

In zero-suppression mode, only non-zero data is output on the ECL port. If no non-zero data is available, no data is output onto the ECL bus. If there is data to be read, the module outputs a header word, which contains the virtual station number of the ADC, and then the data word. Therefore, when an ADC module receives non-zero data, two data words are output on the bus; no data is placed on the bus if the data is zero. Zero-

suppression mode is the mode of choice in most experiments, because time is not wasted reading zeros out of modules that did not convert a pulse during the event. The ECL readout passes by an ADC with zeros typically within 3 ns in the zero-suppression mode. If an input pulse is rejected with the LOCAL GATE, PUR, or lower-level discriminator, no data is reported.

Regardless of the readout mode selected, the module must be cleared after readout to permit new conversions, unless the singles mode is used (see Section 4.10). The clear can be initiated with the global CAMAC clear function, an addressed clear to a single module [F(9)], or a clear from the ECL control bus on the front panel.

Five different control signals are used to control ECL PORT readout. A description of each follows, and their relationship can be observed in Fig. 3.

REQ (Output) The readout request signal is asserted by the AD114 as soon as data are ready for readout. REQ is removed when the last datum has been read or a clear command is given.

REN (Input) The readout enable input causes an AD114 to begin readout if it has data ready to be output. Once REN is asserted, it must remain active throughout the entire readout cycle.

PASS (Output) The pass output is asserted by the AD114 when REN is asserted, if the module is not busy converting, and if the module does not have any data to output. The AD114 will not generate a PASS signal as long as it is busy converting new data. This feature allows ADCs with different conversion times to be placed in the same FERA readout loop without additional logic hardware.

WST (Output) The write strobe output is asserted by the AD114 when a data word is available on the ECL port output. The data is stable on the output a minimum of 15 ns before the write strobe occurs, and the write strobe continues to be asserted a minimum of 15 ns after the write acknowledge signal has occurred.

WAK (Input) The write acknowledge input is asserted by the readout controller when the data on the ECL port output has been accepted. WAK should be removed after WST has been released. WST is not reasserted after WAK has been released until 50 ns have elapsed.

4.10. SINGLES MODE

Although this module is designed with coincidence experiments in mind, a mode exists for collection of singles data. When bit 13 is set in the control register (see Section 2.6), the module behaves in a fashion that can be used to collect a singles spectrum. The major distinction of singles mode is that no clear is required to reset the module once readout has completed. The module performs its own clear. This enables one module to be read out and cleared without affecting any other modules in the chain. A second distinction of the singles mode is that data is read out after each conversion completes. In coincidence mode, readout will not occur until the master GATE has returned low;

however, when the singles mode is enabled, the master GATE has no "grouping effect." Data readout is immediately initiated by a module when conversion is complete regardless of the state of the master GATE.

Normally, the master GATE is disabled on units that are placed in the singles mode by setting bit 12 of the control register. Then, if singles data collection is desired in selected modules in a readout chain, the unselected modules can be inhibited by suppressing the gate input to the FERA driver. In a readout chain, either singles mode or coincidence mode should be used in all modules, *not* a combination of modules in singles mode and coincidence mode.

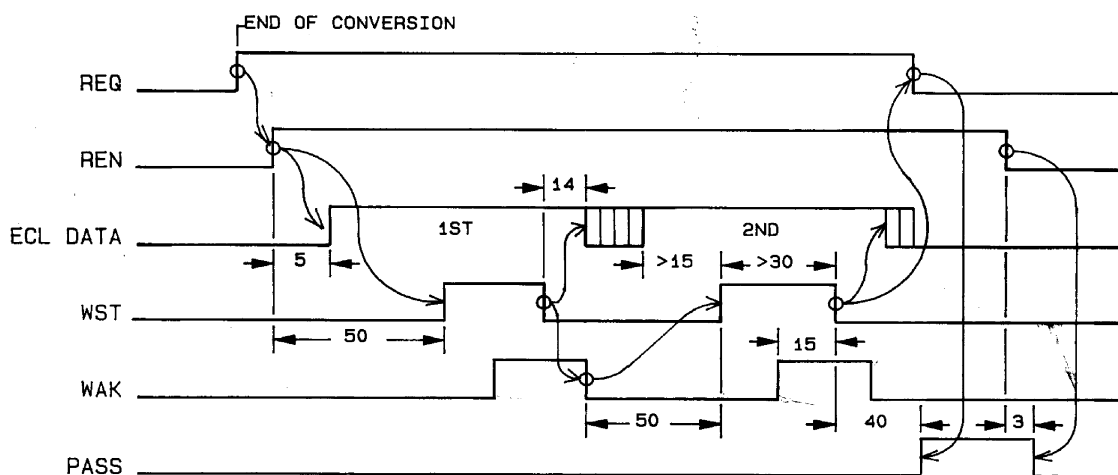


Fig. 3. ECL Port Readout Timing Diagram.

5. TROUBLESHOOTING GUIDE

The following is a list of typical problems which are encountered with suggestions for remedying the problem.

Problem 1: When the lower-level, upper-level or zero offset is polled, a value is returned which is greater than 255 or negative.

Solution: These registers are only 8-bits in length. All higher bits should be ignored. Include a command to clear the high 8-bits of the returned value before reporting the value. (e.g., In BASIC, INFO% = INFO% AND 255).

Problem 2: When the lower-level, upper-level, zero offset or control register is polled, the returned value is different from the value which was written to the register.

Solution: During any CAMAC operation on the AD114, the Q response must be checked. If the AD114 is busy converting or reading out data, a NO-Q response will occur in response to a data transfer CAMAC command. Often when the AD114 is busy, the data which is read will be 0. To guarantee that a CAMAC command will work, set the CAMAC inhibit line and clear the module (F(9)-A(0)).

Problem 3: AD114 does not readout conversions and BUSY light glows bright red.

Solution: Ensure that CAMAC INHIBIT is off. Ensure that the local inhibit in the AD114 is off. Issue F(26)-A(0) command.

Carefully check Control Register setting especially the readout method and singles mode bits (i.e., check CAMAC or FERA bus selection bit and Singles mode bit).

If not using singles mode, ensure that a clear signal is applied to the AD114 after every master GATE whether or not any valid pulses were received by the AD114 during the gating period. If valid data is received, the data should be read before the clear signal is asserted.

Check the lower-level discriminator setting. If the input signal has a positive offset, the baseline of the signal may never be below the lower-level discriminator. The recommended minimum setting for the lower-level discriminator is 70 mV.

Problem 4: AD114 does not readout conversions and BUSY light is not bright red.

Solution: Check master GATE, LOCAL GATE, and PUR signals.

In coincidence mode, the AD114 must be supplied a master GATE to convert any pulses. In singles mode a master GATE must be supplied unless the master GATE is disabled by the appropriate bit in the control register.

A low signal on LOCAL GATE will block all conversions unless the LOCAL GATE is disabled with the control register.

PUR will block conversions if high.

A quick way to determine if the gating signals are the cause of the problem is to set the AD114 as follows:

- Singles Mode
- Zero-suppression disabled
- Overflow-suppression disabled
- Master GATE disabled
- LOCAL GATE disabled
- PUR disconnected

When an input signal is applied to the AD114, it should immediately convert an input pulse and attempt to start a readout cycle. If readout is blocked by disconnecting the REN signal for FERA readout or stopping the CAMAC readout process, the BUSY light on the front panel will glow bright red indicating the AD114 is busy waiting to output data. If the AD114 passes this test, it is likely that one of the gating signals caused the problem. The PUR, LOCAL GATE, and master GATE should be enabled one at a time to determine which is causing the problem.

The master GATE, LOCAL GATE, and PUR signals should be applied before the peak of an input pulse and extend 500ns beyond the peak of the pulse to guarantee correct sampling of the signal.

APPENDIX A: RECOMMENDED CABLE COMPONENTS

Since each experimental system is unique, no attempt is made to supply standard cables to form an ECL bus readout chain. To build the necessary cables, the following will be required:

Control Bus Cable

Parts: 16-conductor ribbon cable with 0.050 inches between conductors.
3M part number = 3365/16

16-position header configured, two rows of 8 sockets.
3M part number = 3452-6006
AMP part number = 499497-3

Construction: Using a ribbon cable construction tool (3M 3698-08), place one header on the cable for each AD114 in the readout chain and one header for the FERA driver on the end. Headers should be positioned such that a minimum of cable separates the AD114s.

Data Output Cable

Parts: 34-conductor ribbon cable with 0.050 inches between conductors.
3M part number = 3365/34

34-position header configured, two rows of 17 sockets.
3M part number = 3414-6006
AMP part number = 499498-9

Construction: Using a ribbon cable construction tool (3M 3698-08) place one header on the cable for each AD114 in the readout chain and one header for the FERA driver on the end. Headers should be positioned such that a minimum of cable separates the AD114s.

Patch Cables (used for REN/PASS readout chain)

Parts: 2-position header for twisted pair cable.
AMP part number = 5-87456-3
Sockets for header.
AMP part number = 1-87756-8

Construction: Using a crimp tool (AMP 90202-2-N), crimp sockets on both ends of individual stranded wire. Take two such wires and tightly twist them to form a twisted pair cable. Plug the sockets into the header to form the cable.