



**Service Manual** 

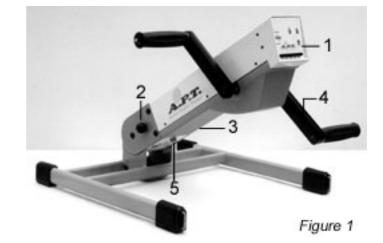
# Table of contents

1.	System components and details	5
2.	General Maintenance and Inspections	6
3.	Spare parts replacement	7
4.	Installation of Stand Assembly	20
5.	Fault finding	21
6.	Spare Parts List	21
7.	List of Tool Types	22

NOTE: Design details may change without notice

## 1. SYSTEM COMPONENTS AND DETAILS

- **1.1.** *APT-1* **unit** (Figure 1)
  - 1. Operator panel
  - 2. Angle release knob
  - 3. Angle securing knob
  - 4. Crank-arm
  - 5. Power input socket



- **1.2. Components** (Figure 2)
  - 1. Power supply unit
  - 2. Straight hand-grips
  - 3. Footrests
  - 4. Finger protection disks
  - 5. Securing straps



#### 2. GENERAL MAINTENANCE AND INSPECTIONS

The rugged design of the **Active Passive Trainer** and the use of selected, modern materials ensure minimal requirements for care and maintenance.

**NOTE:** Improper handling or neglect in the care of the **Active Passive Trainer** may reduce or cancel the coverage of the manufacturer's warranty.

#### 2.1. Regular care

- Inspect Power supply cables and plug for visible damages.
- Check power-input connector for visible damage or insecure fastening.
- On a regular basis check that all screws and components are fastened tightly.
- Ensure that the anti-slip pads under the base are always kept clean.

**CAUTION:** If any damage is detected – do not use *APT-1*. Please contact your authorized dealer. Only authorized personnel may carry out repairs.

#### 2.2. Cleaning instructions

- Disconnect Power Supply and wipe dry with clean cloth.
  CAUTION: For safe disconnection of the *APT-1 always* take the mains plug out of the wall socket *before* removing the connector from the *APT-1* power socket.
- Take care not to allow water to enter the unit. Keep cables and electric components away from water and humidity.

#### 2.3. Storage

• Store Active Passive Trainer between –20 and +40 degrees C and between 10% and 80% humidity

### 3. REPLACEMENT INSTRUCTIONS

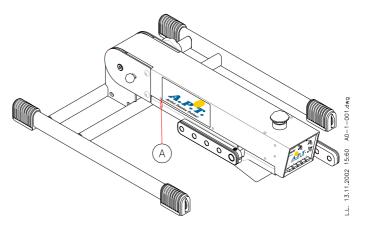
**CAUTION:** Disconnect Power Supply unit before replacement of any part of the *APT-1*. For safe disconnection of the *APT-1* <u>always</u> take the mains plug out of the wall socket before removing the connector from the *APT-1* power socket.

#### 3.1. Body Cover

Kit Number: A0-00-1-001

Tools: Allen Key 2 mm

- Partially unscrew three Screws (3-A) on each side of underbody (no need to remove screws completely)
- 2. Remove cover and replace
- Tighten Screws (3-A)
  NOTE: Do not over-tighten screws



### 3.2. Control Panel

Kit Number: A0-00-1-005

A0-00-1-006 (for remote control)

Tools:

Allen Key 2 mm

- 1. Remove four Screws (4-A) from each side of Control Panel
- Gently pull out Panel and disconnect Flat Cable Connector (4-B) from socket on rear side of Control Panel
- Connect Flat Cable securely to new Control Panel and replace Screws (4-A) NOTE: Do not over-tighten Screws

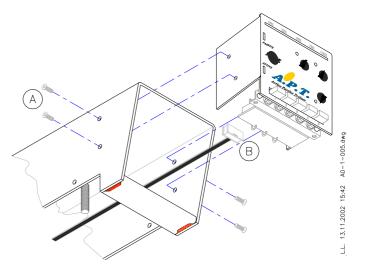


Figure 4

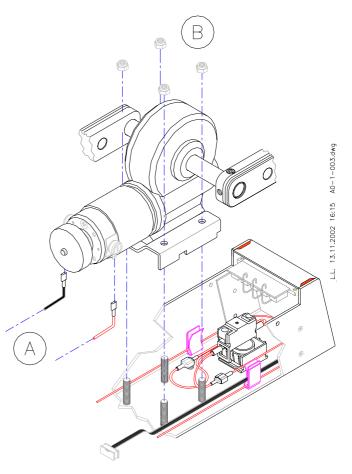
#### 3.3. Gear Motor with crank-arms

### Kit Number: A0-00-1-003

Tools:

Allen Key 2 mm Socket Wrench 10 mm

- 1. Secure **APT-1** in flat position upsidedown on clean table
- 2. Remove Underbody cover, see 3.1
- 3. Disconnect Motor wire spade connectors (5-A) from Motor terminals
- Remove four Nuts (5-B) that secure Gear Motor to *APT-1* body.
- Lift out Gear Motor with crank-arms and replace with new one.
   NOTE: Ensure that Wires do not get 'pinched' under Motor.
- Secure Motor with Nuts (5-B).
  NOTE: Do not overtighten Nuts (B) as this may detach Studs from body or cause paint on top of Body to crack.
- 7. Reassemble Underbody Cover, see 3.1



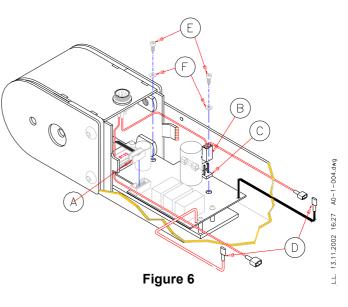
#### 3.4. Controller Circuit Board

#### Kit Number: A0-00-1-004

Tools:

Allen Key 2 mm Allen "T"-Key 2.5 mm Small Flat Blade Screwdriver Silicone Heat-sink Compound

- 1. Secure **APT-1** in flat position upsidedown on clean table.
- 2. Remove Underbody cover, see 3.1
- Carefully disconnect Flat Cable Connector (6-A) from socket on Controller board.
- Disconnect Power Connector (6-B) from Controller Board while releasing tab of Socket (6-C) with screwdriver.
- Disconnect Motor wire Spade Connectors (6-D) from Motor Terminals.
- Remove Screws (6-E) and Washers (6-F) connecting Controller Board to *APT-1* body.
- Lift Controller Board from *APT-1* body with aid of screwdriver. Silicone compound is used between board and *APT-1* body – take care not to get hands or *APT-1* parts dirty.
- 8. Replace with new Controller board. Add Silicone compound if needed.
- Secure Controller Board with Washers (6-F) and Screws (6-E)
- Connect Motor wire Spade Connectors (6-D) to Motor Terminals: red wire to positive/red terminal, black wire to negative/black terminal
- 11. Connect Power Connector (6-B) to Socket (6-C)
- 12. Connect Flat Cable Connector (6-A) to socket on Controller board
- 13. Reassemble Underbody Cover, see 3.1



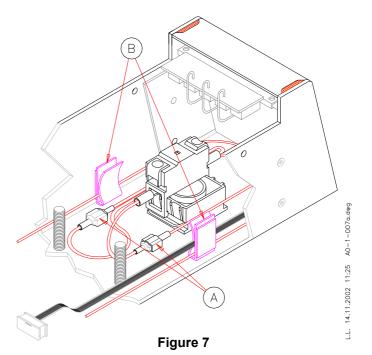
#### 3.5. Power Cable (+ Male Plug)

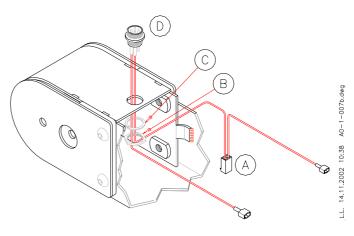
### Kit Number: A0-00-1-007

Tools:

Allen Key 2 mm Small Flat Blade Screwdriver Open End Wrench 19 mm

- 1. Secure **APT-1** in flat position upsidedown on clean table.
- 2. Remove Underbody Cover, see 3.1
- Detach Connectors (7-A) from Stop Switch and remove Wires from Cable Clips (7-B)
- Disconnect Power Connector (8-A) from Controller Board while releasing tab of socket with screwdriver.
- 5. Unscrew Nut (8-B)
- Remove Nut (8-B) and Spring Washer (8-C)
- Remove Plug (8-D) with attached Power Cable and insert new one
- Place Spring Wacher (8-C) and secure Plug (8-D) with Nut (8-B)
- 9. Connect Power Connector (8-A) to Controller Board
- 10. Guide Wires through Cable Clips (7-B)
- 11. Attach Connectors (7-A) to Stop Switch
- 12. Reassemble Underbody Cover, see 3.1







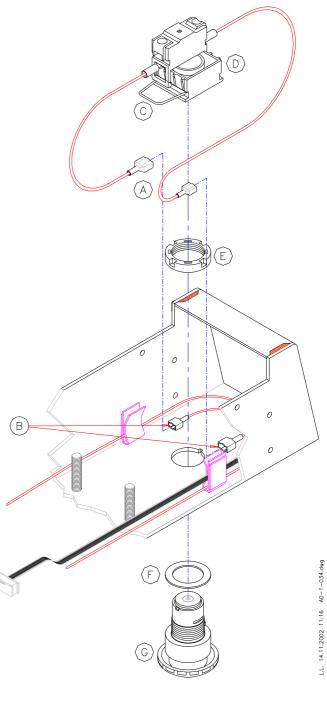
#### 3.6. Stop Switch

Kit Number: A0-00-1-034

Tools:

Allen Key 2 mm Flat Blade Screwdriver Long Nosed Pliers

- 1. Secure **APT-1** in flat position upsidedown on clean table
- 2. Remove Underbody Cover, see 3.1
- 3. Disconnect Wires (9-A) from Power Cable (9-B)
- Open Retaining Spring (9-C) slightly and remove Stop Switch Body NOTE: Be careful not to remove Spring (9-C) from its Housing
- 5. Unscrew Nut (9-E) with Long Nosed Pliers
- 6. Remove Knob (9-G) and Washer (9-F) and insert new one
- 7. Secure Knob (9-G) with Nut (9-E)
- Place Stop Switch Body and secure it with Retaining Spring (9-C)
- Connect Wires (9-A) to Power Cable (9-B)
- 10. Reassemble Underbody Cover, see 3.1



### 3.7. Base Support

*Kit Number: A0-00-1-022 (Rear Base Support) A0-00-1-023 (Front Base Support)* 

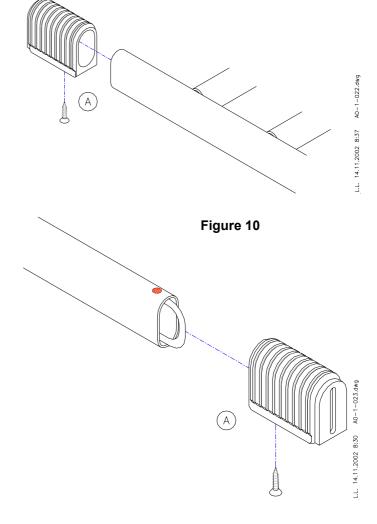
Tools:

Phillips #1 Screwdriver

### Figure 10 shows Rear Base Support, Figure

11 shows Front Base Support

- 1. Remove Screw (10/11-A) from underside of Base Support
- 2. Pull off Support from Base tube
- 3. Replace with new Base Support
- 4. Secure Base Support with Screw (10/11-A)





#### 3.8. Base (incl. Supports)

#### Kit Number: A0-00-1-024

Tools:

Allen Key 2 mm Allen Key 5 mm Open End Wrench 13 mm Loctite Adhesive #242 (1312)

NOTE: These instructions can also be followed to transfer an *APT-1* unit from a base to a stand or the other way round.

- 1. Secure *APT-1* in flat position upsidedown on table
- 2. Remove Underbody cover, see 3.1
- Hold Nylock Nut (12-A) on inner side of Securing Knob (12-B) with wrench
- Remove Securing Knob (12-B) by unscrewing (turning counter-clockwise) from Nut (12-A) and *APT-1* body and remove Washer (12-C)
  NOTE: Keep parts for reassembly.

NOTE: Keep parts for reassembly

- Open Axis Nuts (12-C) on each side of *APT-1* and remove. Base can now be separated from Body
- 6. Assemble new Base on Body
- 7. Secure assembly with Axis Nuts (12-D)
- Place Washer (12-C) on Securing Knob (12-B)
- 9. Hold Nylock Nut (12-A) with wrench and screw Securing Knob (12-B) on Nut
- 10. Reassemble Underbody Cover, see 3.1

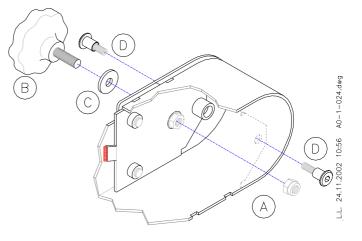


Figure 12

#### 3.9. Body Assembly

### Kit Number: A0-00-1-026

Tools:

Allen Key 2 mm Allen "T"-Key 2.5 mm Allen Key 5 mm Small Flat Blade Screwdriver Socket Wrench 10 mm Open End Wrench 13 mm Silicone Heat-sink Compound Loctite Adhesive #242 (1312)

- 1. Remove following parts as described above:
  - a. Control Panel assembly
  - b. Under-body cover
  - c. Gear Motor with crank-arms
  - d. Controller circuit board
  - e. Base from **APT-1** body
- 2. Assemble components to new body in opposite order.

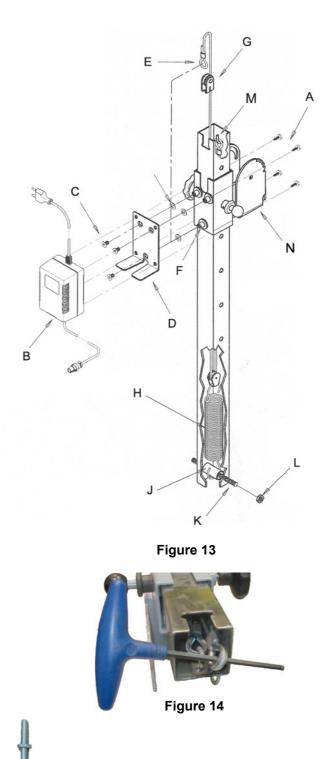
#### 3.10. Cable + Pulley for Stand

Kit Number: A0-00-1-043 – Cable & Pulley Kit Number: A0-00-1-049 – Trolley

#### Tools

Allen Key 5 mm Omnifit M100 Adhesive Rod 130 cm with securing clip Wrench 10 mm Open End Wrench 17 mm

- Remove *APT-1* from Stand, see instruction 3.8
- 2. Open four Screws (13-A) and remove Transformer (13-B)
- Open three Screws (13-C) and remove Transformer Holder (13-D)
- Carefully remove Cable (13-E) from Stud (13-F) and prevent it from being pulled in Stand, see Figure 14
- If necessary, remove Pulley (13-G) and replace by new one NOTE: When Cable does not need be replaced, reassemble Transformer, see instruction 16 and onwards
- Lead Cable (13-E) carefully into Stand CAUTION: The Cable is connected to a powerful Spring (13-H) that will pull it inwards; be careful when releasing Cable into Stand
- Open Nut (13-L) on one side and remove Rod (13-K)
- 8. Remove Cable (13-E) from Hook (13-M)
- 9. Pull out Tube (13-J) and Spring (13-H) with Cable (13-E)
- Attach new Cable (13-E) to Hook (13-M), insert other end with Spring (13-H) in Stand and pull out on other side
- 11. Insert long Rod (15-A) (must be at least130 cm long) with Securing Clip (15-B)in Stand and attach it to Cable





- Gently pull Cable (13-E) in Stand, while Tube (13-J) is inserted in Spring (13-H), see also Fig. 3
- Align Tube (13-J) with hole in Stand insert Rod (13-K) and secure with Nut (13-L)
- 14. Ensure that Trolley (13-N) is in its lowest position (closest to Spring)NOTE: Attaching the Cable to the Trolley when it is in its top position seems easier but will give trouble later during use
- 15. Pull Cable (13-E) out of Stand by using the long rod
- Attach eye of Cable (13-E) to Stud (13-F); ensure that Cable (13-E) runs smoothly over Pulley (13-G) and that the eye of Cable (13-E) sits secure over Stud (13-F)
- 17. Secure Transformer Holder (13-D) to Trolley (13-N) with three Screw (13-C)
- 18. Place Transformer (13-B) on Holder (13-D) and secure with four Screws (13-A)
- 19. Reassemble APT-1 on Stand

### 3.11. Straps for Footrest

### Kit Number: A0-00-1-050

- 1. Remove Straps
- Insert new Straps, see Figure 16
  NOTE: Ensure that the 50 cm strap is in the rear slots and the 40 cm strap in the front slots



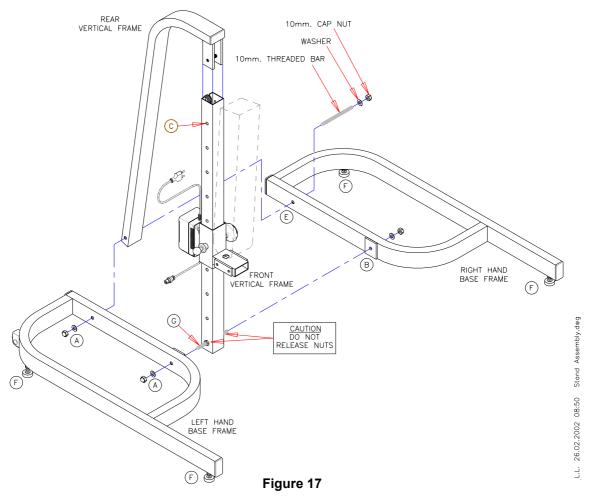
### 4. INSTALLATION OF STAND

Tools:

Allen Key 5 mm Open End Wrench 17 mm (2x)

- 1. Insert the four floor guides (17-F) into the Left and Right Hand Base Frames
- 2. Align the Left and Right Hand Base Frames on either side of the Front Vertical Frame (see Fig. 16)
- 3. Slide the *Threaded Bar* on the *Front Vertical Frame* into the front hole (17-A) of the *Left Hand Base Frame*, place the *Washer* in position and screw on the *Cap Nut* (do not tighten at this stage)
- 4. Repeat this procedure with hole (17-B) on the Right Hand Base Frame
- 5. Align the holes at the bottom of the *Rear Vertical Frame* with rear holes in the *Left and Right Hand Base Frames* (17-D & E)
- 6. Slide the *Threaded Bar* (17-G) through the holes, place the two *Washers* in position on either side and screw on the two *Cap Nuts*
- 7. Tip the *Rear* and *Front Vertical Frames* enough towards the back to slide the two tongues at the top of the *Rear Vertical Frame* into the top of the *Front Vertical Frame*. Straighten both frames
- 8. Tighten the set screw (17-C) with a 5 mm Allen Key by turning it in a clockwise direction
- 9. Ensure that all frame members are aligned correctly and finally tighten all four *Cap Nuts* using two 17 mm open end wrenches
- 10. Adjust the four floor guides (17-F) to level and stabilize the base
- 11. Adjust height of APT by releasing the locking pin on the left hand side; secure positioning by tightening the knob on the right hand side

NOTE: Inside the Vertical Frame is a spring that pulls the APT upwards.



### 5. FAULT FINDING

Tzora Active Systems provides for profound training in Fault Finding to the major distributors of the *APT-1*. Please contact the authorized Tzora Distributor in your country or Tzora for more information.

### 6. SPARE PARTS LIST

	Description		Part Number	Page	
1	Control Panel Assembly		A0-00-1-005	8	
	Control Panel Assembly for Remote Control		A0-00-1-006	0	
2	Body Cover		A0-00-1-001	7	
3	Gear Motor with Crank-arms		A0-00-1-003	9	
4	Controller Circuit Board		A0-00-1-004	10	
5	Rear Base Support		A0-00-1-022	13	
6	Front Base Support		A0-00-1-023	13	
7	Base (including Supports)		A0-00-1-024	14	
8	Body Assembly		A0-00-1-026	15	
9	Power Supply 110V		A0-00-1-016	-	
9a	Power Supply 110V for Stand		A0-00-1-017	-	
10	Stop Switch		A0-00-1-034	12	
11	Remote Control	(not shown)	A0-00-1-018	-	
12	Power Cable (+ male plug)	(not shown)	A0-00-1-007	11	
13	4P Female Plug	(not shown)	A0-00-1-020	-	
14	Finger protection disks	(not shown)	A0-00-1-025	-	
15	Cable + Pulley for Stand	(not shown)	A0-00-1-043	16	
	Trolley for Stand	(not shown)	A0-00-1-049	10	
16	Straps for Footrest (Pair)	(not shown)	A0-00-1-050	18	

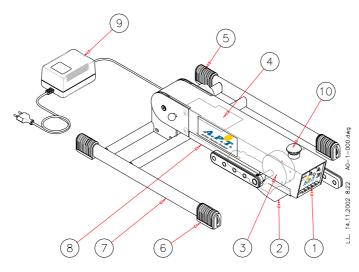


Figure 18

### 7. LIST OF TOOL TYPES

### Screwdrivers:

Phillips #1 Flat Blade Small Flat Blade

### Allen Keys:

2 mm 2.5 mm ("T"-Key) 5 mm

# Wrenches:

Socket Wrench 10 mm Open End Wrench 13 mm Open End Wrench 19 mm

# Other Tools:

Long Nosed Pliers Loctite Adhesive #242 (1312) Silicone Heat-sink Compound For safety and for warranty assurance reasons, any modifications and repair of the *APT-1* or its components must be performed exclusively by authorized personnel and exclusively with original spare parts.

The *APT-1* Active Passive Trainer and its accessories have been designed and manufactured in accordance with the specification of the following:

DIRECTIVE: Medical devices 93/42 EEC (Annex V)





Manufactured by:



Kibbutz Tzora 99803, ISRAEL Web site: www.tzora.com

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