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Operation and Service Manual

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PREFACE

IPak Model RP-100 Tray Former are versatile and industry-proven machines with unique mechanical trayforming technology. They are designed and built to withstand the rigors of continuous, heavy-duty, industrial applications.

The RP-100 Tray Former Operation and Service Manual was written to assist you in installing, operating, troubleshooting, maintaining, and repairing the machine properly. This manual describes the standard features that are present in the RP-100 machine. Please read the manual carefully, as it contains the necessary information required to extend the service life of this machine to its fullest.

We recommend that this manual be kept with the tray former for future reference. If any problems are encountered with the procedures contained in this manual, please contact our Service Center before proceeding.

While every effort has been made to ensure the completeness and accuracy of this manual, IPak assumes no responsibility or liability for any losses or damages resulting from the use of the information contained in this document.

Due to technical advances and improvements, some of the information contained in this manual may be changed or modified without prior notice. Also, note that some of the components illustrated in this manual may differ slightly from your machine.

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How to use this manual

Please study carefully the following information about the manual's format.



STOP

This symbol is used to alert you of an important step in operational sequence, to note exceptions to normal machine operation, or when special circumstances must be taken into consideration by the machine operator.

Throughout this manual, you will find the following four special text formats:

• The names of all **buttons**, **keys**, **sensors**, **switches**, **displays**, and **status indicators** are capitalized, boldfaced, and placed in single quotes.

For example, "Press the **'START'** button." "The value in the **'SPEED'** display is not touch sensitive."

• All machine component status terms, operations, functions, display values, and features are capitalized and boldfaced.

For example, "The case separator returns to the UP position."

• When referring to HMI (Human Machine Interface) display screens and windows, we use initial capitals, boldface, and single quotes.

For example, "...return to the **'Main Menu'** screen." "Touching the **'LOGIN**' button will bring up the **'Login'** window."

• When referring to **Sections** in this manual, we italicize the link and use single quotes.

For example, "See Section 6: 'Operating Procedures'."

• If you are using a PDF version of this manual, you may jump directly to the referred section by clicking on the italicized text.

1 SAFETY

MUST BE READ PRIOR TO OPERATING



WARNING

The instructions in this manual are not intended to cover all of the details or variations in equipment, or to provide for every possible contingency to be met in connection with installation, operation, or maintenance. Should further information be desired, or should particular problems arise which are not covered sufficiently for the purchaser's purposes, the matter should be referred directly to IPak.

The RP-100 has safety features to protect you from injury while the machine is operating. Guard doors equipped with interlock switches prevent you from entering the work cell while the case formation is in progress; the machine will not run if one of these doors is open. The control panel access door must also be closed in order for the machine to operate.

The perimeter guarding system surrounds the area known as the restrictive envelope and covers the entire range of possible machine motion. For your safety, you should never try to bypass the perimeter guarding system or enter the restrictive envelope while the machine is in operation.

Pressing an **'EMERGENCY STOP'** button immediately halts all machine operations by cutting off air supply and electrical power. This button should be pushed **IN** to **STOP** the machine in case of an emergency.



WARNING

Any electrical or mechanical modifications to this equipment made without the prior written consent of IPak will void all warranties. Unauthorized modifications can also result in personal injury, death, or destruction of the equipment.

1.1 Safety Considerations

IPak is proud to employ every conceivable precaution in the research and development of our tray formers. We have become a world-class leader in the packaging industry because of our adoption of the following best practices:

- Fully automatic functionality requiring minimal operator interaction
- Advanced safety guarding with keyed electronic interlock switches
- · Lock-out provision on electrical and pneumatic main shut-offs
- Integrated 24-volt DC power supply for safe, low voltage operating controls
- Intuitive cautionary labeling demonstrating electrical and mechanical risks

- 'EMERGENCY STOP' button shutdown with optional extra 'EMERGENCY STOP' buttons
- PLC-operated sequence and timer control

1.2 Safety Standards

IPak observes the following safety standards:

- ANSI B151.1-2000 Safety Standards for Mechanical Power Transmission Apparatus
- CSA C22.2.1-02; 0-M91 Canadian Electrical Code Part I and Part II
- NFPA 79 Electrical Standards for Industrial Machines
- CSA C22.2 No. 14-95 Industrial Control Equipment
- ANSI Z535.4-2002 Product Safety Signs & Labels
- ANSI B155.1-2000 for Packaging Machinery
- CSA Z432-04 (2004) Safeguarding of Machinery
- NEMA 12 UL listed standard electrical control

1.3 General Precautions

Your IPak machine is a rugged piece of industrial machinery. It is equipped with various guards and other safety features, but it must be treated with respect at all times to avoid the possibility of personal injury. The following points are particularly important:

- Do not operate the machine until it is completely set up and installed properly and you are familiar with its operation.
- Do not operate the machine without guards and safety mechanisms in place and functioning.
- Do not attempt to enter the machine for any reason while the air pressure is still ON.
- Do not wear neckties, jewelry, loose clothing, or other items that can get caught in moving parts or mechanisms near the machine.
- Do not operate, troubleshoot, or maintain the machine while under the influence of any type of drug or alcohol.
- Always observe all safety warnings and notices on the machine and in this manual.
- Do not use solvents when cleaning or maintaining the machine.
- All installation wiring must comply with applicable local codes.

1.4 Lock-out Compliance

The RP-100 is lock-out / tag-out-compliant on both the electrical and pneumatic main shut-offs. Both the **'MAIN DISCONNECT'** and the air-regulator assembly can be locked out on our IPak tray formers. Ensure that you lock out the machine prior to performing any repairs or maintenance.



Figure 1-1: Lo cked Out 'MAIN DISCONNECT' Switch and Air-regulator Assembly

1.5 Compressed Air

Compressed air is used to power the movement of many machine components. You must ensure that the machine's main air solenoid valve is shut **OFF** before attempting to clear jams or make minor adjustments which require you to get close to the moving parts of the machine. This air valve shuts **OFF** when the guard doors are opened or when the main power is switched **OFF**.

To safely carry out service or repair work on the machine, a lockable main air shutoff valve is located on all IPak machines upstream of the regulator unit. Padlock this valve in the **OFF** position for absolute safety during service work. Always follow local lock-out/tag-out regulations.

Always exercise caution when switching the compressed air back **ON**. Stay well clear of all moving parts, as they may move quickly when the pressure is reapplied. Ensure that no person is in dangerous location when switching the compressed air **ON**.

1.6 Electrical Power

All IPak machines use electrical power. Switch **OFF** the '**MAIN DISCONNECT**' switch on the control panel, and lock it out before attempting service work outside of the control panel on the machine. Before performing service work inside the control panel, disconnect all electrical power to the machine (customer supplied disconnect).

1.7 Hot Melt Glue System



CAUTION!

Read and understand the safety instructions in the separate Nordson Manual supplied with your new machine.

The Hot Melt glue system operates at temperatures in the range of 350°F (175°C), and contact with the hot glue will cause serious burns. Always wear safety glasses and gloves when refilling the glue tank, and be careful to avoid splashing. Keep the tank lid closed at all times except when refilling the tank.

Remember that the glue applicator is very hot and that the glue is projected with considerable speed when the glue applicator is switched **ON**. Be extremely careful when near Hot Melt material. Even solidified material may still be very hot. Always wear protective clothing which safely covers all exposed parts of the body.



1.8 Outfeed Conveyor

Where used, the outfeed conveyor systems on IPak packaging machines operate at moderate speeds. Be sure to keep fingers well clear of all moving parts, as the gearmotors develop substantial torque and do not stop easily. Do not wear loose clothing or accessories (e.g., neckties) when operating IPak packaging machines.

1.9 Guard Doors

IPak takes your safety seriously, offering the added benefit of safety guarding with interlock guard doors on all of our machines. This guarding prevents operators from reaching into the machine during routine operation and maintenance.

1.10 Safety Interlocks

IPak is an industry leader in the incorporation of advanced integrated safety guarding with keyactivated interlock switches on our IPak tray formers. Opening any of the guard doors on the machine instantly disables all machine functions.



Figure 1-2: Safety Interlock

1.11 Cautionary Labels

IPak provides cautionary labels for workplace hazards. Please pay particular attention to the cautionary labels found on the machine.



Figure 1-3: Warning Labels



2 INSTALLATION

The installation of the RP-100 RPC involves moving the compnents of the machine to an appropriate location, reattaching all of the machine components, connecting electrical power, and supplying air to the machine. The following section shows how to fully install the machine.

2.1 Positioning the Machine

2.1.1 Selecting a Location for the Machine

Select an appropriate location for the machine. Ensure that enough room is provided next to the machine to load tray blanks, access the guard doors and '**EMERGENCY STOP**' buttons, remove formed trays, and make machine adjustments. Also, ensure that there is enough room for the conveyor and that there is enough room to remove trays.

2.1.2 Moving the Machine

The safest way to move the assembled machine is by pushing it with a forklift. When pushing the machine, place a wooden or steel block on the ground across the rear legs. Push against the block with the forklift.

Once the machine components are in the appropriate location, remove the transport skis. To do this, lift the machine, remove the bolts that are connecting the skis to the machine feet, and lower the machine.



Figure 2-1: Pushing a Machine with a Forklift



0.1 Connecting the Electrical Supply

Main power needs to be connected to the control panel when the machine is installed. This machine requires 240V, 3-Phase power, at 60Hz. Power must be wired to the machine before an IPak technician can begin setting up the machine.



Figure 2-1: Ground Connection

Figure 2-2: 3-Phase Power Connection

To connect power to the machine:

- 1. Drill a hole in the side, top or bottom of the control panel, to send the main power wires through. Install a strain relief or any other appropriate fitting, and then send the main power wire into the control panel.
- 2. Connect the ground wire to the grounding terminal block (Figure 2-1).
- 3. Connect the other three wires to the top of the fuse disconnect (see Figure 2-2). If the motor does not turn in the correct direction when the machine is running, the wiring must be changed. To do this, simply reverse any two wires that are connected to the fuse disconnect.

Refer to the electrical schematic provided in the control panel and users manual, for more detail on the electrical wiring.





Figure 2-3: Fittings for FRL Unit & Lubricator

0.2 Connecting The Air Supply

Main air must be supplied to the machine. This can be done either by the client before the service technician arrives to set the machine up, or by the service technician when he or she arrives to set up the machine. The main air supply hose must be ³/₄" ID or larger. See Section 9: 'Engineering Specifications' for other air requirements.

To supply main air to the machine:

Connect the main air hose to the FRL unit (See Figure 2-3). A ³/₄" NPT fitting is required to connect the supply line to the FRL unit. Ensure that the supply line has an inside diameter of at least ³/₄".



Figure 2-4: Air Lubricator

- 2. Ensure that the lubricator is full of oil. If the oil level is below the low level mark, it must be filled with oil. To add oil, pull the tab (Shown in Figure 2-4), twist the oil reservoir clockwise, and then pull it down and off.
- 3. Turn the main air shut off valve to the **SUPPLY** position.



3 THEORY OF OPERATION

The RP-100 Automatic Tray Former and Stacker are automatic machines designed to open and stack RPC trays. When functioning, the machines form and stack the trays at a constant speed, upon demand, without requiring further operator input.

All motions of the RP-100 Automatic Tray Former are controlled by a PLC (Programmable Logic Controller) which is located in the main control panel. Optical proximity sensors are used to detect the position of the machine's components and the trays being formed. Interlock switches are used to ensure that all guarding is secure while the machine is in operation. The buttons and touchscreen on the electrical control panels form the operator interface and provide the input signals to the PLC. The PLC then decides upon the next stage of the machine's operation, and sends electrical signals to the machine's electric motor and the pneumatic and solenoid valves that activate the machine's various components.



3.1 Sequence of Operation

3.1.1 Startup

Because the 'EMERGENCY STOP' buttons and guard doors are wired together in series, all guard doors must be closed and 'EMERGENCY STOP' buttons must be pulled out for the machine to energize when the 'START' button is touched on the machine's HMI.

3.1.2 Hopper Tray Supply

The machine will begin to open trays if the following three conditions are met: 1) the 'OUTFEED JAM' sensor ((Input I: 0.0/12) is clear, indicating that there is not a backup of opened trays on the outfeed converyor, 2) the 'LEFT LANE OF BACK' (Input I: 0.0/3) or the 'RIGHT LANE OF BACK' (Input I: 0.0/4) limit switches detect that the hopper cross pushers are back in position and ready to push a tray stack, and 3) the 'RIGHT LANE RPC DETECT' (Input I: 0.0/7) or 'LEFT LANE RPC DETECT' (Input I: 0.0/5) sensor detects that a conveyor has carried a stack of trays fully forward in one of the hopper lanes.

At this point, a side pusher pushes the stack of trays into the center of the hopper. If there are tray blanks ready to be fed from both of the conveyors, the side pusher of the Duty Lane will push the trays across.

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When trays have been pushed into the center of hopper, the correct positioning of the tray stack is sensed by the **'CENTER RPC DETECT LH'** and **'CENTER RPC DETECT RH'** sensors (Input I: 0.0/0) and (Input I: 0.0/6). This triggers the Center Cross Pusher to push the stack of trays forward into the RPC Hopper. The motion of the Center Cross Pusher is detected by the **'CENTER OF FORWARD'** limit switch (Input I: 0.0/2) which signals when the Center Cross Pusher is at its fully-extended position and the **'CENTER OF BACK'** limit switch (Input I: 0.0/3) which signals that the Center Cross Pusher has returned to its home positon.

The sensors and limit switches described above trigger a series of timers in the PLC which then trigger the following outputs:

- Valve SV0 / Left RPG Lift
- Valve SV1 / Right RPG Lift
- Valve SV2 / Left Side Cross Pusher
- Valve SV3 / Right Side Cross Pusher
- Valve SV4 / Side Swing
- Valve SV5 / Center Cross Pusher

(Output O:2.0/0) (Output O.2:0/1) (Output O.2:0/2) (Output O.2:0/3) (Output O.2:0/4) (Output O.2:0/5)

3.1.3 Tray Positioning for Opening

When the stack of trays is positioned in the RPC Hopper, it is supported by the Front and Rear Hopper Gates. The '**RPC Detect Sensor**' (Input I: 0.0/11) detects the bottom tray in the stack. When this tray is detected, two RPC Clamp Swings jam into holes in the sides of the second tray up in the stack. Two Pick Lifts then grab the bottom tray. The Hopper Gates then open to allow the bottom tray to be lowered and it is lowered down onto two guide rails. The Hopper Gates then close, the RPC Clamp Swings swing out of the holes in the second tray, and it is allowed to fall down onto the Hopper Gates. The two Pick Lifts rise to grab the next tray. Their raised position is signalled by the '**PICK DOWN**' limit switch (Input I: 0.0/8). A '**HOPPER LOW**' sensor (Input I: 0.0/13) is positioned on the side of the RPC Hopper a few inches above the 'RPC Detect Sensor. When this sensor is cleared, another stack of unopened trays is moved by a crosspusher into positon ready to be advanced into the RPC Hopper.

The sensors and limit switches described above trigger a series of timers in the PLC which then trigger the following outputs:

•	Valve SV6 / RPC Pick	(Output 0:2.0/6)
•	Valve SV7 / Grip Swing	(Output 0.2:0/7)

3.1.4 Tray Advance and Opening

As the tray is placed on the guide rails, its presence is detected by the '**OUTFEED JAM**' sensor (Input I: 0.0/12). The RPC Pusher then pushes the tray forward and into position for opening. Two pairs RPC Openers then descend to the bottom of the tray. After reaching the tray bottom, the pairs separate - one pair moving towards the leading end of the tray and the other to the trailing end. The claw-shaped tray openers slide under the folded end panels of the tray, lifting their edges up off of the tray floor. The lifting of the tray ends forces the tray sides to rotate upward into a vertical position. Finally, four RPC Lock Hammers, located near the the tray corners swing outwards to impact the tray's end panels near the tray corners. The tray-opening sequence with the tray openers and hammers is initiated by the '**RPC PUSHER FWD**' limit switch (Input I: 0.0/10). The impact of these hammers forces the four corners of the tray into their locked positions. The tray remains on the guide rails at this location until pushed forward and out of the machine by the advance of the next unopened tray.



The sensors and limit switches described above trigger a series of timers in the PLC which then trigger the following outputs:

- Valve SV11 / RPC Position Lock
- Valve SV12 / Opener Lift
- Valve SV13 / Opener Slide
- Valve SV14 / RPC Lock Hammer

(Output O:2.0/11) (Output O.2:0/12) (Output O.2:0/13) (Output O.2:0/14)

3.1.5 Tray Stacking

As the tray arrives at the the infeed end of the stacker, it is detected by the '**TRAY DETECT**' sensor. If the '**CROSS PUSHER BACK**' limit switch has has signalled that the cross pusher is in its **HOME** position, the lift cylinder activates and the tray is lifted up between two spring-loaded side plates to make way for the arrival of the next tray underneath. It is held at this level while the lift descends to receive the next tray. When the tray stack has reached the number which has been preset in the tray opener's HMI, the cross pusher activates and pushes the stack out of the outfeed end of the stacker.

The sensors and limit switches described above trigger a series of timers in the PLC which then trigger the following outputs:

- Valve SV1 / Cross Pusher Valve
- Valve SV2 / Lift Cylinder Valve
- Valve SV3 / Trapped Guides Valve

(Output O:1.0/1) (Output O.1:0/2) (Output O.1:0/3)





4 CONTROLS

The control station is located on the front of the main control panel. The station consists of the 'HMI' screen, the 'MAIN DISCONNECT' switch, the 'RESET' button, and an 'EMERGENCY STOP' button.

4.1 'MAIN DISCONNECT' Switch

The 'MAIN DISCONNECT' switch turns the main electrical power to the machine ON or OFF. However, no power is applied to any of the machine's electrically or pneumatically powered components. The 'MAIN DISCONNECT' switch can be locked in the OFF position for safety during maintenance operations.

4.2 'RESET' Button

Touch the '**RESET**' button to turn on the control power and provide power to the machine's electrically or pneumatically powered components.

4.3 'EMERGENCY STOP' Button(s)

The 'EMERGENCY STOP' button immediately cuts off electrical and air supply to the machine, and halts all operations regardless of whether a tray is positioned in the tray-erecting process when the button is pushed **IN**.

Power is removed from the main air mechanisms. Restarting the machine after an emergency stop is more complex than with a regular **START**. Most likely, the tray that was being formed will be wasted.

After clearing any tray jams or damaged trays, the **'EMERGENCY STOP'** button should be released (twisted and pulled out) and the **'RESET'** button should be pushed for the machine to operate again.



Figure 4-1: 'MAIN DISCONNECT' Switch



Figure 4-2: 'RESET' Button



Figure 4-3: 'EMERGENCY STOP' Button(s)



4.4 HMI and Chapter Organization

The HMI (Human Machine Interface) touch screen uses a 'Main Control' screen and the 'Jog Control screen' for primary control. The 'Setup Menu' screen has eight subsections for adjusting and monitoring settings. The reference numbers at the top right of the screens indicate chapter section numbers.



Figure 4-4: HMI and Chapter Organization



4.5 'SERVICE CALL' Screen

When the machine is turned on, the opening screen displays a photo of the Wexxar factory and contact information. Touch this screen anywhere to bring up the HMI's '**Main Control**' screen.

You can bring up this screen when the machine is not operating by pressing the '**SETUP**' button located at the lower right corner of any screen. When the '**Setup Menu**' screen appears, press the '**SERVICE CALL**' button to display the screen as shown in *Figure 4-5*.



Figure 4-5: 'SERVICE CALL' Screen

The RP-100 features an Allen Bradley HMI (human-machine interface) touchscreen display instead of mechanical controls. Many of these surfaces, such as the **'START'** button operate as though they were mechanical buttons. They will be referred to as buttons in this manual section.





Figure 4-6: 'Main Control' Screen

4.6 'Main Control' Screen

On the 'Main Control' screen are buttons, toggle switches, and status indicators required for the basic operation of the machine. The interactive controls on this screen include the 'START/STOP' button, the 'TRAY DEMAND DISABLED' button and display and the 'DUTY LANE' toggle switch. This screen also includes buttons which give the operator access to the 'Jog Control' and Setup' screens.

Alarm Sample 1

Figure 4-7: 'MACHINE ALARM' Status Indicator

4.6.1 'MACHINE ALARM' Status Indicator

At the top of many of the HMI screens is the green-text machine **'MACHINE ALARM'** status indicator. This status indicator changes to red during an alarm state. A message in the status indicator indicates which of the machine's fault conditions has triggered the alarm. When the fault condition has been remedied, the alarm message will disappear and the green **NO CURRENT ALARMS** status message will appear.





4.6.2 'MACHINE WARNING' Status Indicator

Below the **'MACHINE ALARM'** status indicator on many of the HMI screens is a green **'MACHINE WARNING'** status indicator. The screen changes to yellow during a warning state. A message in the window indicates which of the machine's fault conditions has triggered the warning. When the fault condition has been remedied, the warning message will disappear, and the green **NO CURRENT WARNINGS** status message will reappear.

4.6.3 'START/STOP' Button

On the left-hand side of the 'Main Control' screen is the 'START' button. Touching this button starts the CYCLE of the machine to erect trays continually. If the 'REMOTE DEMAND' sensor is ON, automatic tray erecting will stop when erected trays block the sensor on the outfeed conveyor and will resume when they move downstream away from the sensor. Once touched, the 'START' button will be replaced with a 'STOP' button. Touching the 'STOP' button stops the automatic machine cycle. If the 'STOP' button is touched while the machine is in the middle of a tray forming cycle, the machine finishes forming the tray, and then halts all further operation, returning the mechanisms to their HOME positions.



Figure 4-9: 'START/STOP' Button

4.6.4 'VALUE' Buttons and Displays

Throughout the remainder of the Controls Section of the manual, the screen images includes '**VALUE**' symbols. Any of these symbols with blue values are touch-sensitive and function as buttons. Any with white numerals are displays and are not touch-sensitive. The function of each will be made clear in the descriptions accompanying them.

4.6.5 'TRAYS per SHIFT' Display

In the upper right area of the 'Main Control' screen is the 'TRAY'S PER SHIFT' button and display. Its value cannot be changed other than being reset to 0. Touch the value in this display to reduce the 'TRAYS PER SHIFT' value to zero.

4.6.6 'TRAYS PER MINUTE' Display

On the right-hand side of the '**Main Control**' screen is the '**TRAYS PER MINUTE**' display. It is not touch-sensitive and cannot be changed by the operator.



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4.6.7 'Numeric Keypad' Window

The numeric keypad is used to change the values of many of the displays on the machine's interactive screens. Touching the numerals of any touch-sensitive value brings up the '**Numeric Keypad**' window. Touch the numerals to set the desired value in the field in the top of the keypad. Touch the '**CLEAR**' button to delete any value entered. Store the new value and close the window by touching the '**ENTER**' button. Touch the '**CANCEL**' button to close the '**Numeric Keypad**' window without making any changes.

4.6.8 'TRAY DEMAND' Toggle Switch and Display

On the right-hand side of the 'Main Control' screen is the 'TRAY DEMAND' toggle switch and display. Touch the gray 'TRAY DEMAND DISABLED' button to enable the tray demand feature which allows the machine to run a set number of trays. Touching the value in the display will bring up a 'Tenkey Keypad' window which will enable the operator to run a set number of trays. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the 'ENTER' button.

4.6.9 'DUTY LANE' Toggle Switch

In the lower right of the 'Main Control' screen is the 'DUTY LANE' toggle switch. Touchng the LH Lane Duty / RH Lane Standby toggle switch will toggle the display from black to green and switch the duty lane from the left lane to the right lane. The display changes to read **Right Lane Duty / Left** Lane Standby and the machine draws the trays from the right hand lane when that lane is not empty. When the right lane becomes empty, trays from the right-hand lane are automatically loaded. Touch the green 'RIGHT LANE DUTY / LEFT LAND STANDBY' toggle switch to switch the duty lane back to the left lane.

4.6.10 'JOG CONTROL' Button

The 'JOG CONTROL' button is located on the 'Main Control' screen at the lower right when the machine is stopped. Touch this button to open the 'Jog Control' screen.



Figure 4-13: 'Numeric Keypad' Window





LH Lane Duty / RH Lane Standby

Right Lane Duty / Left Lane Standby

Figure 4-15: 'DUTY LANE' Toggle Switch

Jog Control





RP100	JOG CONTROL	13:13:32
	Forward F	Reverse
	SENSOR STATUS - (No response with the second seco	hen blinking) 15 15 15 15 10 10 10 10 10 10 10 10 10 10
Main Control		Setup

Figure 4-17: 'Jog Control' Screen

4.7 'Jog Control' Screen

The 'Jog Control' screen contains the '(JOG) REVERSE' and '(JOG) FORWARD' buttons. In the lower area of the 'Jog Control' screen, twelve sensor status indicators show which sensors are activated during each step in the JOG CYCLE.

4.7.1 '(JOG) REVERSE' and '(JOG) FORWARD' Buttons

In the upper right and left of the '**Jog Control**' screen are the '(**JOG**) **REVERSE**' and '(**JOG**) **FORWARD**' buttons. To jog the machne forward, touch the '(**JOG**)' **FORWARD**' button. To jog the machne in reverse, touch the '(**JOG**)' **REVERSE**' button.



Figure 4-18: '(JOG) REVERSE' and '(JOG) FORWARD' Buttons

4.7.2 'SENSOR' Status indicator

The 'SENSOR' status indicators show which sensors are activated at each step as the machine is jogged in forward or reverse. A blinking 'SENSOR' status indicator means that there is no response from a particular sensor. Touching the 'SENSOR' status indicator will bring up the 'Error Identification' screen with a photo of the sensor and its location on the machine. Touching the photo will return the touch screen to the 'Jog Control' screen.

4.7.3 'MAIN CONTROL' Button

The 'MAIN CONTROL' button is located on the bottom lefthand corner of many of the HMI's display screens. Touch the 'MAIN CONTROL' button to return to the 'Main Control' screen..

4.7.4 'SETUP' Button

The **'SETUP'** button appears on the bottom right-hand corner of many of the HMI's display screens. Touch this button to display the **'Setup'** screen. **NOTE:** While the machine is cycling, this button will not display.



Figure 4-19: 'SENSOR' Status indicator



Figure 4-20: 'MAIN CONTROL' Button

Setup

Figure 4-21: 'SETUP' Button





Figure 4-22: 'Setup' Screen

4.8 'Setup' Screen

The '**Setup**'screen provides access to many features related to machine diagnostics and tuning and setting adjustments. It also includes toggle switches for turning the dry cycle and remote demand features **ON** and **OFF**. Touch the '**MAIN CONTROL**' button in the bottom left-hand corner of the screen to return to the '**Main Control**' screen or the '**JOG CONTROL**' button in the bottom right-hand corner to return to the '**JOG CONTROL**' screen.

4.8.1 'DRY CYCLE' Toggle Switch

For the purposes of troubleshooting, machine operators may choose to operate the machine without any try blanks loaded. This function is called the **DRY CYCLE**. To enable the Dry Cycle operation, touch the gray '**DRY CYCLE OFF**' toggle switch located in the lower center of the '**Setup**' screen. The toggle switch will then change to the green '**DRY CYCLE ON**' toggle switch, at which point the machine can operate without any tray blanks loaded.



Figure 4-23: 'DRY CYCLE' Toggle Switch

Controls

4.8.2 'DRY CYCLE ACTIVE' Status Indicator

When the machine is in 'DRY CYCLE' operation, a small 'DRY CYCLE ACTIVE' status indicator appears below the 'DRY CYCLE' toggle switch. It will display in the same location on the 'Main Control' screen.

4.8.3 'REMOTE DEMAND' Toggle Switch

Located in the lower right area of the 'Setup' screen, this toggle switch turns the 'REMOTE DEMAND' sensor ON or OFF. The 'REMOTE DEMAND' sensor is used to halt machine operation if trays are not moving away from the machine on the downstream conveyor, thus avoiding tray jams. It also matches tray forming output to the rate of consumption by downstream processes. To enable the 'REMOTE DEMAND' sensor, touch the gray 'REMOTE DEMAND OFF' toggle switch which will then turn green and display the text 'REMOTE DEMAND ON'.

4.8.4 'REMOTE DEMAND ON' Status Indicator

When the '**REMOTE DEMAND**' sensor has been turned **ON**, a small '**REMOTE DEMAND ON**' status indicator appears below the '**REMOTE DEMAND**' toggle switch. It will display in the same location on the '**Main Control**' screen.

4.8.5 'ALARM HISTORY' Button

Located in the upper left-hand corner of the '**Setup**' screen is the '**ALARM HISTORY**' button. Touch this button to bring up the '**Alarm History**' screen.



Figure 4-24: 'DRY CYCLE ACTIVE' Status Indicator



Figure 4-25: 'REMOTE DEMAND' Toggle Switch



Figure 4-26: 'REMOTE DEMAND ON' Status Indicator



Figure 4-27: 'ALARM HISTORY' Button



RP100 AL	ARM HISTORY	
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	Alarm Message Alarm Message	
Main Control	Clear	Setup

Figure 4-28: 'Alarm History' Screen

4.9 'Alarm History' Screen

The 'Alarm History' screen displays the time, date, and identity of each alarm condition that the machine has experienced. This screen is useful in determining common problems and can assist the operator in troubleshooting or making machine adjustments. Touch the 'SETUP' button in the bottom right-hand corner of the 'Alarm History' screen to bring up the 'Setup' screen, or touch the 'MAIN CONTROL' button in the bottom left-hand corner of the screen to return to the 'Main Control' screen.

4.9.1 'SCROLL' Buttons

The **scroll** buttons, located at the right top and bottom of the screen, are used to move up or down through a alarm history messages. The single arrow scrolls one line at a time while the double arrow scrolls one screen at a time.



Figure 4-29: 'SCROLL' Buttons

4.9.2 'CLEAR' Button

Touch the '**CLEAR**' button, located at the bottom center center of the '**Alarm History**' screen to erase accumulated alarm messages. Authorized users may clear this data upon entering the password on the **Keyboard** that appears. Note that touching this button will bring up a '**Password**' window.

4.9.3 'Password' Window

Touch the blank field in the '**Password**' window to bring up an '**Alphanumeric keypad**' window. Type the required password: 9300. To enter the password into the '**Password**' window, touch the '**ENTER**' key Then touch the '**OK**' button. If you enter an invalid password, an error message will display. Touch '**OK**' to remove the error message and input a valid password. **NOTE:** As soon as the password is entered and the '**OK**' button is touched, the '**Alarm History**' screen will cleared.



Figure 4-30: 'CLEAR' Button

PASSWORD	×
Input password.	
1	
OK Cancel Keyboard	

Figure 4-31: 'Password' Window

Keyboard	
1 2 3 4 5 6 7 8 9 0 · ^	V ESC
qwertyuiop@[CLR BS
asdfghikl;:]	SPACE
z x c v b n m , . /	ENTER
	<· .>

Figure 4-32: 'Alphanumeric Keypad' Window

4.9.4 'Alphanumeric Keypad' Window

Touch the buttons in the '**Alphanumeric Keypad**' window to set the username and the password into the field at the top of the window. Store the username and password and close the window by touching the '**ENTER**' button.

4.9.5 'TRAY RECORD SUMMARY' Button

In the upper left area of the **'Setup'** screen is the **'TRAY RECORD SUMMARY'** button. Touch this button to bring up the **'Tray Record Summary'** screen.

Tray Reco	ord
Summar	'y

Figure 4-33: 'TRAY RECORD SUMMARY' Button

RP100	TRAY RECORD S	SUMMARY	13:18:26
			1
	Total Number Of Trays	0000000000	
	Total Trays / Shift	00000	
	Trays / Minute	00	
L			J
Main Control			Setup

Figure 4-34: 'Tray Record Summary' Screen

4.10 'Tray Record Summary' Screen

The '**Tray Record Summary**' screen is used to check the total number of trays formed by the machine or or the machine's speed in trays per minute or to reset the machine's Total Trays/Shift value. Touch the '**MAIN CONTROL**' button in the bottom left-hand corner of the screen to return to the '**Main Control**' screen or the '**SETUP**' button in the bottom right-hand corner return to the '**Setup**' screen.

Total Number Of Trays	000000000

Figure 4-35: 'TOTAL NUMBER OF TRAYS' Display

4.10.1 'TOTAL NUMBER OF TRAYS' Display

In the top of the '**Tray Record Summary**' screen is the '**TOTAL NUMBER OF TRAYS**' display. This value indicates the total number of trays which the machine has formed. The value changes automatically as each tray is made. The value is not touch-sensitive and cannot be altered or reset.

Total Trays / Shift



Figure 4-36: 'TOTAL TRAYS PER SHIFT' Button and Display

4.10.2 'TOTAL TRAYS PER SHIFT' Button and Display

In the upper center of the '**Tray Record Summary**' screen is the '**TOTAL TRAYS PER SHIFT**' button and display. This value is used to count the number of trays made since the display's value was last reset. Touch the value in the display to reset the value to zero.

② Are You Sure You Want to Reset The Total Trays Per Shift Counter					
Yes(Y) No(N)					

Figure 4-37: 'Total Trays Per Shift' Confirmation Window

4.10.3 'Total Trays Per Shift' Confirmation Window

When the value in the '**Total Trays Per Shift**' button and display is touched, a confirmation window will appear. Touch the '**YES**' button in the confirmation window to reset the Total Trays per Shift value to zero

4.10.4 'TRAYS per MINUTE' Display



Figure 4-38: 'TRAYS per MINUTE' Display

In the center of the '**Tray Record Summary**' screen is the '**TOTAL TRAYS/MINUTE**' display. This value indicates the machine's production speed in trays per minute. This value is not touch-sensitive and cannot be reduced or reset.

4.10.5 'TROUBLESHOOTING (PLC I/O)' Button

The '**TROUBLESHOOTING (PLC I/O)**' button is found on the upper right area of the '**Setup**' screen, to the right of the '**TRAY RECORD SUMMARY**' button. Touch the '**TROUBLESHOOTING**' button to be taken to the '**Troubleshooting**' screen.



Figure 4-39: 'TROUBLESHOOTING (PLC I/O)' Button



RP100	TROUBLESHOOTING	13:15:25
	PLC Inputs (Engineer)	
Main Control		Setup

Figure 4-40: 'Troubleshooting' Screen

4.11 'Troubleshooting' Screen

On the center of the 'Troubleshooting' screen are the 'PLC INPUTS' and the 'PLC OUTPUTS (ENGINEER)' buttons. Touch the 'MAIN CONTROL' button in the bottom left-hand corner of the screen to return to the 'Main Control' screen or the 'SETUP' button in the bottom right-hand corner to bring up the 'Setup' screen.

4.11.1 'PLC INPUTS' Button

In the left center area of the **'Troubleshooting'** screen is the **'PLC INPUTS'** button. Touch this button to access the first **'PLC Inputs'** screen.

PLC Inputs	

Figure 4-41: 'PLC INPUTS' Button



RP100	PLC INPUTS	13:15:07	RP100	PLC INPUTS	13:21:27
1:0/0	E0/1 E0/2 E0/3 E0/4 E0/5	1:0/6	L1/0	E1/1 E1/2 E1/3 E1/4 E1/5 E1/6	k1/7
1:0/8	E0/9 E0/10 E0/11 E0/12 E0/13	:0/14 :0/15	1:1/8	E1/9 E1/10 E1/11 E1/12 E1/13 E1/14	1 1:1/15
1:0/16	E0/17 E0/18 E0/19				
Main Control	Next	Trouble Shooting	Main Control	Next	Trouble Shooting

Figure 4-42: 'PLC Inputs' Screens

4.12 'PLC Inputs' Screens

The 'PLC Inputs' screens display thirty-six machine PLC Inputs status indicators. Touch the 'MAIN CONTROL' button in the bottom left-hand corner of the screen to return to the 'Main Control' screen or the 'TROUBLESHOOTING' button in the bottom right-hand corner to return to the 'Troubleshooting' screen.

4.12.1 'PLC INPUT' Status Indicators

When the machine is jogged through its cycle, as each machine input is triggered, the corresponding '**PLC INPUT**' status indicator will be momentarily change from gray to yellow.

4.12.2 'NEXT' Button

Touch the '**NEXT**' button in the bottom center of the screen to access the next '**PLC Inputs**' screen.

4.12.3 PLC OUTPUTS (ENGINEER)' Button

In the right center area of the **'Troubleshooting'** screen is the **'PLC OUTPUTS (ENGINEER)'** button. Touch this button to access the first **'PLC Outputs'** screen. The password is required to access this screen.

1:0/0

Figure 4-43: 'PLC INPUT' Status Indicators



Figure 4-44: 'NEXT' Button



Figure 4-45: PLC OUTPUTS (ENGINEER)' Button




Figure 4-46: 'PLC Outputs' Screens

4.13 'PLC Outputs' Screens

The '**PLC Outputs**' screens display sixteen buttons. Each of these buttons controls a PLC output directly. Touch the '**MAIN CONTROL**' button in the bottom left-hand corner of the screen to return to the '**Main Control**' screen or the '**TROUBLESHOOTING**' button in the bottom right-hand corner to return to the '**Troubleshooting**' screen.

4.13.1 PLC OUTPUT' Buttons and Status Indicators

To test any of the PLC outputs, **STOP** the machine, and remove any unformed trays from the hopper. Then touch the button for that output. When a button is touched, it will illuminate, and that machine component will function through its cycle. If it does not function, inspect and repair the component.

4.13.2 'SERVICE CALL' Button

In the upper right-hand corner of the '**Troubleshooting**' screen is the '**SERVICE CALL**' button. Touch this button to bring up the '**Service**' screen which contains contact information for the IPak Service Department.

4.13.3 'REMOTE DEMAND' Button

In the upper left area of the '**Setup**' screen is the '**REMOTE DEMAND**' button. Touch this button to bring up the '**Remote Demand Settings**' screen.



Figure 4-47: PLC OUTPUT' Buttons and Status Indicators



Figure 4-48: 'SERVICE CALL' Button



Figure 4-49: 'REMOTE DEMAND' Button



Figure 4-50: 'Remote Demand Settings' Screen

4.14 'Remote Demand Settings' Screen

The 'Remote Demand Settings' screen is used to set the Remote Demand Delay ON and Remote Demand Delay OFF values. Touch the 'MAIN CONTROL' button in the bottom left-hand corner of the screen to return to the 'Main Control' screen or the 'SETUP' button in the bottom right-hand corner to return to the 'Setup' screen.



Figure 4-51: 'REMOTE DEMAND DELAY' Buttons and Displays

4.14.1 'REMOTE DEMAND DELAY' Buttons and Displays

In the top center of the 'Remote Demand Settings' screen is the 'REMOTE DEMAND DELAY ON' buttons and displays. This button and display indicates the amount of time, in milliseconds, that the machine will wait after the 'REMOTE DEMAND' sensor has been blocked before the machine stops. Under the 'REMOTE DEMAND DELAY ON' button and display is the 'REMOTE DEMAND DELAY OFF' button and display. This button and display indicates the amount of time, in milliseconds, after the 'REMOTE DEMAND' sensor has been cleared before the machine will resume cycling. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the 'ENTER (...)' button.

4.14.2 'EXTENDED HOPPER' Button

In the upper left area of the '**Setup**' screen is the '**EXTENDED HOPPER**' button. Touch this button to bring up the first '**Extended Hopper**' screen. Extended Hopper

Figure 4-52: 'EXTENDED HOPPER' Button

RP100	RP100 EXTENDED HOPPER			
	Delay On Time (mSec)			
	Begin Hopper Sequence Delay On Time	0000		
	RPC Lift Delay On Time	0000		
	Side Cross Pusher Delay On Time	0000		
	Cross Pusher Ready Delay On Time	0000		
	Cross Pusher Extended Delay On Time	0000		
	Cross Pusher Home Delay On Time	0000		
Main Contro	Next	Setup		

Figure 4-53: 'Extended Hopper 1' Screen

4.15 'Extended Hopper 1' Screen

The **'Extended Hopper 1'** screen includes the first six of the timings for the machine's extended hopper. Touch the **'MAIN CONTROL'** button in the bottom left-hand corner of the screen to return to the **'Main Control'** screen or the **'SETUP'** button in the bottom right-hand corner to bring up the **'Setup'** screen. Touch the **'NEXT'** button to bring up the **'Extended Hopper 2'** screen.



4.15.1 'BEGIN HOPPER SEQUENCE DELAY ON TIME' Button and Display

The first of the Extended Hopper buttons and displays is the **'BEGIN HOPPER SEQUENCE DELAY ON TIME'** button and display. It indicates, in milliseconds, the delay time after which either of the hopper lanes recognizes that a tray stack is ready for lateral side pushing into the hopper's center lane. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the **'ENTER** (\downarrow)' button.



RPC Lift Delay On Time



Figure 4-55: 'RPC LIFT DELAY ON TIME' Button and Display

4.15.2 'RPC LIFT DELAY ON TIME' Button and Display

The second of the Extended Hopper buttons and displays is the '**RPC LIFT DELAY ON TIME**' button and display. It indicates, in milliseconds, the delay time after the tray stack is ready for lateral side pushing before the stack is lifted in the hopper. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** (\downarrow)' button.



and Display

4.15.3 'SIDE CROSS PUSHER DELAY ON TIME' Button and Display

The third of the Extended Hopper buttons and displays is the '**SIDE CROSS PUSHER DELAY ON TIME**' button and display. It indicates, in milliseconds, the delay time after the tray stack is lifted in the hopper before the stack is cross-pushed laterally into the center of the hopper. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** ($_{\rightarrow}$)' button.

Cross Pusher Ready Delay On Time 👘

8888

Figure 4-57: 'CROSS PUSHER READY DELAY ON TIME' Button and Display

4.15.4 'CROSS PUSHER READY DELAY ON TIME' Button and Display

The fourth of the Extended Hopper buttons and displays is the 'CROSS PUSHER READY DELAY ON TIME' button and display. It indicates, in milliseconds, the delay after the tray stack is moved to the center lane before it is cross-pushed longitudinally towards the tray erecting area. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the 'ENTER (\downarrow)' button.



Cross Pusher Extended Delay On Time

0000

Figure 4-58: 'CROSS PUSHER EXTENDED DELAY ON TIME' Button and Display

4.15.5 'CROSS PUSHER EXTENDED DELAY ON TIME' Button and Display

The fifth of the Extended Hopper buttons and displays is the '**CROSS PUSHER EXTENDED DELAY ON TIME**' button and display. It indicates, in milliseconds, the delay after the tray stack is cross-pushed longitudinally before the cross-pusher retracts to its home position. Touching the numerals of this touchsensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** ($_{-}$)' button.

Cross Pusher Home Delay On Time

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Figure 4-59: 'CROSS PUSHER HOME DELAY ON TIME' Button and Display

4.15.6 'CROSS PUSHER HOME DELAY ON TIME' Button and Display

The sixth of the Extended Hopper buttons and displays is the '**CROSS PUSHER HOME DELAY ON TIME**' button and display. It indicates, in milliseconds, the delay after the longitudinal cross-pusher returns to its home position before it is ready to receive the next stack of closed trays. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** ($_{\rightarrow}$)' button.

RP100		२ 17:23:22
	Delay On Time (mSec)	
	Left Lane Empty Delay On Time	0000
	Right Lane Empty Delay On Time	0000
	Hopper Empty Delay On Time	0000
	Hopper Not Detected Delay On Time	0000
Main Contro	l Next	Setup

Figure 4-60: 'Extended Hopper 2' Screen

4.16 'Extended Hopper 2' Screen

The 'EXTENDED HOPPER 2' screen includes the remaining four timings for the machine's extended hopper. Touch the 'MAIN CONTROL' button in the bottom left-hand corner of the screen to return to the 'Main Control' screen or the 'SETUP' button in the bottom right-hand corner to bring up the 'Setup' screen. Touch the 'NEXT' button to bring up the next 'Extended Hopper 1' screen.

Left Lane Empty Delay On Time	0000
Right Lane Empty Delay On Time	0000

Figure 4-61: 'LEFT LANE (and) RIGHT LANE EMPTY DELAY ON TIME' Buttons and Displays

4.16.1 'LEFT LANE (and) RIGHT LANE EMPTY DELAY ON TIME' Buttons and Displays

The seventh and eighth of the Extended Hopper buttons and displays are the 'LEFT LANE EMPTY DELAY ON TIME' and the 'RIGHT LANE EMPTY DELAY ON TIME' buttons and displays. They indicate, in milliseconds, the delay time after the 'LEFT LANE RPC DETECT' or 'RIGHT LANE RPC DETECT' sensor is cleared before the that lane is recognized as having no trays and trays are taken from the opposite lane. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the 'ENTER (,)' button.

Hopper Empty Delay On Time

0000

Figure 4-62: 'HOPPER EMPTY DELAY ON TIME' Button and Display

4.16.2 'HOPPER EMPTY DELAY ON TIME' Button and Display

The ninth of the Extended Hopper buttons and displays is the **'HOPPER EMPTY DELAY ON TIME**' button and display. It indicates, in milliseconds, the delay time after the **'HOPPER EMPTY'** sensor is cleared before the hopper is recognized as having no trays. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the **'ENTER** (\downarrow)' button.

Hopper Not Detected Delay On Time

Figure 4-63: 'HOPPER NOT DETECTED DELAY ON TIME' Button and Display

4.16.3 'HOPPER NOT DETECTED DELAY ON TIME' Button and Display

The tenth of the Extended Hopper buttons and displays is the **'HOPPER NOT DETECTED DELAY ON TIME'** button and display. It indicates, in milliseconds, the delay time after which the hopper has been empty for a period of time set in the HMI. Touching the numerals of this touch-sensitive value will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the **'ENTER** (,) button.

4.16.4 'HOPPER' Button

In the upper right area of the **'Setup'** screen is the **'HOPPER'** button. Touch this button to bring up the **'Hopper'** screen.



Figure 4-64: 'HOPPER' Button

RP100	HOF		13:16:38	
	Start / Stop	Time (mSec)		_
	Valve	Start	Stop	
	SV4 - Slide Swing	0000	0000	
	SV6 - RPC Pick	0000	0000	
	SV7 - Grip Swing	0000	0000	
	SV8 - Hopper Bottom Gate	0000	0000	
				_
Main Control				Setup

Figure 4-65: 'Hopper' Screen

4.17 'Hopper' Screen

The 'Hopper' screen includes four timings for the machine's hopper. Touch the 'MAIN CONTROL' button in the bottom left-hand corner of the screen to return to the 'Main Control' screen or the 'SETUP' button in the bottom right-hand corner to bring up the 'Setup' screen.



Figure 4-66: 'SLIDE SWING' Buttons and Displays

4.17.1 'SLIDE SWING' Buttons and Displays

The first pair of the Hopper buttons and displays are those of the '**SLIDE SWING**'. They indicate, in milliseconds, the start and stop times for the hopper's Slide Swing. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** (\dashv)' button.



Figure 4-67: 'RPC PICK' Buttons and Displays

4.17.2 'RPC PICK' Buttons and Displays

The second pair of the Hopper buttons and are those of the '**RPC PICK**'. They indicate, in milliseconds, the start and stop times for the hopper's RPC Pick. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** ($_{-}$)' button.



Figure 4-68: 'GRIP SWING' Buttons and Displays

4.17.3 'GRIP SWING' Buttons and Displays

The third pair of the Hopper buttons and are those of the '**GRIP SWING**'. They indicate, in milliseconds, the start and stop times for the hopper's Grip Swing. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** (\downarrow)' button.



Figure 4-69: 'HOPPER BOTTOM GATE' Buttons and Displays

4.17.4 'HOPPER BOTTOM GATE' Buttons and Displays

The fourth pair of the Hopper buttons and are those of the 'HOPPER BOTTOM GATE'. They indicate, in milliseconds, the start and stop times for the Hopper's Bottom Gate. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the 'ENTER (\rightarrow)' button.

4.17.5 'FOLD /LOCK' Button

In the upper right side of the '**Setup**' screen is the '**FOLD** / **LOCK**' button. Touch this button to bring up the first '**Fold** / **Lock**' screen.



Figure 4-70: 'HOPPER' Button

RP100	FOLD / LOCK			13:16:53
	Start / Stop	Time (mSec)		_
	Valve	Start	Stop	
	SV11 - RPC Lock Position	0000	0000	
	SV12 - Opener Lift	0000	0000	
	SV13 - Opener Slide	0000	0000	
	SV14 - RPC Lock Hammer	0000	0000	
				_
Main Control				Setup

Figure 4-71: 'Fold / Lock' Screen

4.18 'Fold / Lock' Screen

4

The **'Fold / Lock**' screen includes four timings for the machine's tray-folding and tray-locking mechanisms. Touch the **'MAIN CONTROL'** button in the bottom left-hand corner of the screen to return to the **'Main Control**' screen or the **'SETUP**' button in the bottom right-hand corner to bring up the **'Setup**' screen.



Figure 4-72: 'RPC LOCK POSITION' Buttons and Displays

4.18.1 'RPC LOCK POSITION' Buttons and Displays

The first pair of Fold / Lock buttons are those of the '**RPC LOCK POSITION**'. They indicate, in milliseconds, the start and stop times for the RPC Lock. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** ($_{-}$)' button.



Figure 4-73: 'OPENER LIFT' Buttons and Displays

4.18.2 'OPENER LIFT' Buttons and Displays

The second pair of Fold / Lock buttons and are those of the '**OPENER LIFT**'. They indicate, in milliseconds, the start and stop times for the Opener Lift. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** ($_{-}$)' button.



Figure 4-74: 'OPENER SLIDE' Buttons and Displays

4.18.3 'OPENER SLIDE' Buttons and Displays

The third pair of Fold / Lock buttons and are those of the '**OPENER SLIDE**'. They indicate, in milliseconds, the start and stop times for the Opener Slide. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** ($_{-}$)' button.



Figure 4-75: 'RPC LOCK HAMMER' Buttons and Displays

4.18.4 'RPC LOCK HAMMER' Buttons and Displays

The fourth pair of Fold / Lock buttons and are those of the '**RPC LOCK HAMMER**' buttons and displays. They indicate, in milliseconds, the start and stop times for the RPC Lock Hammer. Touching the numerals of either of these touch-sensitive values will bring up a ten-key keypad. Touch the numerals of the keypad to set the desired value in the field at the top of the keypad. Store the new value and close the keypad by touching the '**ENTER** (\downarrow)' button.

5 OPERATING PROCEDURES

5.1 General Outline

During normal operation, the operator should maintain an adequate flattened trays. In addition to the above responsibilities, the operator must also be alert to the possible development of malfunctions. An important factor in achieving optimum performance of the RP-100 system is the quality control of the trays The operator should be particularly alert to the condition of these trays.

5.2 Machine Start-Up

Before the machine can start forming trays, it must be powered up. To do this:

- 1. Turn ON the 'MAIN DISCONNECT' switch and turn ON the air to the machine
- 2. Close all guard doors, and ensure that all the 'EMERGENCY STOP' buttons are not pressed
- 3. Press the 'RESET' button on the control panel.

In this mode, the machine will be powered up but will not be able to erect trays.

Before beginning production operation, it is recommended that the operator slowly jog the machine until it has made a few cycles to ensure everything is operating smoothly. To do this, on the HMI:

- 1. Touch the 'JOG' button on the HMI screen.
- 2. Touch the 'START' button on the HMI screen.

The machine will move through the **JOG** cycle only while the **'START'** button is touched. Ensure that all of the shafts and chains are rotating freely. This mode can also be used when troubleshooting problems in the erecting section.

5.3 Loading Totes

Place the totes horizontally onto the extended hopper conveyor. Ensure the stack is even all around and square. The machine is equipped with a 'HOPPER FULL' sensor, and when it becomes clear, the machine will stop.

5.4 Production Operation

5.4.1 Starting the Machine

With the power turned **ON** and a blank hopper full of trays:

- 1. Turn the 'JOG ON/OFF' button on the HMI screen to the OFF position
- 2. Touch the green **'START'** button on the HMI screen.

The machine will now run automatically, continually erecting trays.

If the machine is required to stop and start from a remote area or on demand by a conveyor system, a remote switching device (limit switch, sensor, foot pedal, etc.) is required. This switching device must be wired in the normally **OPEN** position. Refer to the remote demand hookup on the electrical schematic diagram (X100-E0044)

The machine operation does not change when the remote switching device is connected.

5.4.2 Stopping the Machine

The machine will continually run until the machine is manually turned **OFF** by the operator or until the hopper runs out of folded trays. To stop the machine manually, touch the red **'STOP'** button on the HMI or stop the signal from the remote switching device. The machine will run several cycles without picking any more blanks to ensure that all previous trays are cleared from the machine.

5.5 Safaty Systems and Features

If a tote is blocking the **'PH-13'** sensor or if any of the check-timer setting conditions are not met, a safety timer will time out and stop the machine. To restart the machine:

- 1. Depress the 'EMERGENCY STOP' button.
- 2. Remove the tote and any obstructions.
- 3. Disengage the **'EMERGENCY STOP'** button.
- 4. Press the **'RESET'** button on the control _Panel
- 5. Touch the green 'START' button on the HMI screen.

There are five guard doors on the machine and two **'EMERGENCY STOP'** buttons. If any door is opened or an **'EMERGENCY STOP'** button is pressed, the machine will immediately stop. Power will be removed from the PLC and the main air will shut off. To restart the machine:

- 1. Close the guard door and/or turn and pull out the 'EMERGENCY STOP' button.
- 2. Press the '**RESET**' button on the control panel.
- 3. Touch the green **'START'** button on the HMI.

5.6 Features and Instructions

The machine is equipped at the factory with guards to protect the operator from drive units, pinch points and electrical circuitry. It is important to turn the 'MAIN POWER DISCONNECT' switch on the machine to the OFF position before removing any guarding. It is important for all guarding and safety devices, as manufactured and installed at the factory, to be re-installed after maintenance and prior to start-up of the machine. All guarding must always be in place while the machine is operating.



Extreme caution should be taken while making adjustments with the guards off.

5.7 Shutdown Procedure

At the end of each production day, the following shutdown procedures are necessary:

- 1. Clean up the machine and operating area.
- 2. It is suggested that all daily maintenance procedures outlined in Section 7: 'Maintenance' be performed at this time.



6 MACHINE SETUP

The machine comes set up at the factory and should open trays without any problems. However, if the machine fails to open trays properly, the machine setup may need to be adjusted. The areas of the machine that may need adjusting are the guide rails, the lock hammers, and the flap openers. The following procedures outline how to inspect and set up these areas of the machine.

6.1 Guide Rail Adjustment

If blanks are failing to be placed level on the guide rails or are not entering the tray-opening section straight and square, the guide rails may be incorrectly positioned. To correct the positioning of the guide rails, use the following procedure:



Figure 6-1: Infeed-end Side Guide

Figure 6-2: Outfeed-end Side Guide

- 1. Place an open tray on the guide rails and inside the lock hammers (See Figures 6-1 and 6-2).
- 2. Using a 9/16" wrench, loosen the four caphead clamp screws which secure each of the four side guide clamp blocks.
- 3. Adjust the side guides so that there is a 1/16" gap between the inner edges of the two guide rails and the outer edges of the tray. In doing so, take care to ensure that the two guide rails are equidistant from the machine's longitudinal centerline.
- 4. Tighten the sixteen caphead clamp screws.

RP-100 RPC Erector

Machine Setup

6.2 Lock Hammer Lateral Adjustment

- 1. Place a formed tray in the tray-forming section with the RPC lock hammers lowered into the tray.
- 2. Locate the clamp blocks at each end of the RPC lock hammer assembly (See Figure 6-3).
- 3. Using a 9/16" wrench, loosen the four caphead screws which secure the lateral adjustment of the clamp blocks.
- 4. Slide the lock hammer assemblies inward or outward to such a position as that the lock hammers, when fully lowered, straddle the seam lines between the inner edges of the erected tray minor and major flaps.



Figure 6-3: RPC Lock Hammer Clamp Blocks

5. Retighten the clamp blocks.

6.3 Flap Opener Vertical Adjustment

- 1. Place a formed tray in the tray forming section.
- 2. Locate and loosen the two caphead screws which secure the each of the flap opener assemblies in their vertical position (See Figure 6-4) (**NOTE:** Only one caphead screw is shown in the photo.)
- 3. Lower the flap opener assemblies so that the openers, at their lowest point, distort the floor of the RPC tray downward approximately 1/16" from its level position.
- 4. Retighten the four caphead screws.



Figure 6-4: Flap Opener Vertical Adjustment



Machine Setup





Figure 6-5: RPC Pusher

Figure 6-6: Horizontal Adjustment Clamp Block

6.4 Flap Opener Horizontal Adjustment

- 5. Pull the RPC pusher out as far as possible towards the outfeed end of the machine.
- 6. Place an opened tray on the guide rails with its trailing end touching the RPC pusher block (See Figure 6-5).
- 7. Locate the flap opener assembly holding the flap openers which are turned towards the infeed end of the machine. Loosen the four caphead screws which secure it.
- 8. Slide the assembly towards the infeed end of the machine until the flap openers are touching the inner side of the trailing minor flap.
- 9. Tighten the four caphead screws which secure the flap opener clamp block.
- 10. Loosen the caphead screws which secure the second flap opener assembly.
- 11. Slide it away from the first flap opener assembly until it touches the inner side of the leading minor tray flap.
- 12. Secure the caphead screws which secure the second flap opener assembly.



Machine Setup



Figure 6-7: Lock Hammer Assembly

Figure 6-8: Lock Hammer Cylinder and Mount

6.5 Lock Hammer Swing Adjustment

- 1. Locate the four lock hammer cylinders secured to their mounting weldments (See Figure 6-8.)
- 2. Using a 1/2" wrench, loosen the two capscrews which secure each of the four lock hammer cylinders on the mounting weldments.
- 3. Extend each of the four cylinders out to their maximum extension point.
- 4. Slide the each of the cylinders horizontally along the mounting weldments until their positions cause the lock hammers to be swing to exactly 1/2 degree past a vertical angle.
- 5. Tighten the two capscrews on each of the lock hammers. mounting weldments.

6.6 Lock Hammer Longitudinal Adjustment

- 6. Place an opened tray on the side guides with the flap openers fully extended against the inner sides of the tray ends.
- 7. Using a 9/16" wrench, loosen the four caphead screws which secure each of the lock hammer assemblies (See Figure 6-9).
- Slide each of the lock hammer assemblies to positions such that, with the lock hammers swung to their maximum rotation (1/2 degree past the vertical), the edges of the lock hammers are pressed againt the inner edges of the tray's end flaps.
 NOTE: The position of the lock hammer one one side of the machine must be exactly parallel with its match on the other side.
- 9. Tighten the four caphead screws on each of the lock hammer assemblies.



Figure 6-9: Lock Hammer Longitudinal Adjustment



7 MAINTENANCE

Proper maintenance is critical in ensuring long lasting performance from the RP-100. Performing the following procedures will ensure that the machine will continue to run reliably for many years.

7.1 Daily Maintenance

1. Sweep under and around the machine.



3. Inspect the linear shafting for any foreign material that might be attached. Carefully remove any particles, while taking care not to score the shafts.



Maintenance



4. Check the sensors for correct operation. Clear any debris blockage and dust using only a soft cloth to prevent scratching



7.2 Weekly Maintenance

1. Check and refill the air lubricator.



2. Inspect all air cylinders on the machine. They should move freely without binding or restrictions.



7.3 Monthly Maintenance

1. Lubricate all bushings, cylinder pivots and rod ends where applicable.



Maintenance

7.4 Every Three Months

1. Using food grade grease and the two pumps of the grease gun, grease the linear bearings in the vacuum section and the ram assembly. Wipe away the excess grease.



7.5 Annual Maintenance

1. Inspect all air lines for cracks and wear. Replace them as necessary.



2. Change the gearbox oil.







4.

5.

3. Inspect all chains for wear. Replace them if necessary.



7.6 **Guarding Removal**

Grease the bearings.

The machine is equipped at the factory with guards to protect the operator from drive units, pinch points and electrical circuitry.

An 'EMERGENCY STOP' button must be pressed before removing any of the guarding. It is necessary for all guards and safety devices, as manufactured and installed at the factory, to be re-installed after maintenance and prior to STARTUP of the machine. All guarding must always be in place while the machine is operating.





8 TROUBLESHOOTING



NOTE: Prior to referencing the troubleshooting guide, ensure that you have properly read and understand *Section 5: 'Operating Procedures'*

ALL TROUBLESHOOTING STEPS THAT REQUIRE WORKING INSIDE THE ELECTRICAL PANEL OR REMOVING GUARDING SHOULD ONLY BE PERFORMED BY CERTIFIED MAINTAINANCE PERSONNEL!

8.1 Vacuum System

The vacuum system may not operate properly for many reasons. If the vacuum system fails to pick a blank properly, the reasons can be mechanical, pneumatic, or electrical. The following section shows how to trouble shoot the vacuum system. Refer to the vacuum assembly (X21-1348, X21-1377), the electrical diagram (X100-E0034), and the pneumatics diagram.



8.1.1 Vacuum Cups Do Not Move

If the vacuum cups do not move when the 'START' button is pressed:

- 1. Ensure that the vacuum shaft is rotating by slowly jogging the machine.
- 2. If the cam does not rotate, ensure that the chain and taper lock bushings are in place and that the keys and bolts are in the bushings are secured tightly (See Figure 8-1). Tighten any loose fittings.
- 3. If the cam is rotating but the vacuum assembly is not lifting, inspect the vacuum assembly, including the chain, the rod ends, rod end mount, and the cam follower, to insure that all components are properly attached.



Figure 8-3: Vacuum Assemblies

8.1.2 Vacuum Cups Do Not Impact Bottom Of Blank

If the vacuum cups move but do not impact the bottom of the blank:

- 1. Lower the collars on the vacuum cups, so that the vacuum cups lift up higher (See Figure 8-3).
- 2. If the cups still do not impact the blank, adjust the stroke of the vacuum adjustment linkage by moving the vacuum rod end mount further away from the pivot (See Figure 8-2).

8.1.3 Vacuum Does Not Turn ON

If the vacuum cups move properly but there is no suction from the vacuum system:

- 1. Ensure that the limit switch actuator is making contact with the 'VACUUM ON' limit switch. If it is not, adjust the position of the limit switch on the guide mount until the actuator makes contact with the switch (See Figure 8-2).
- 2. Ensure that the **'VACUUM ON'** input (I:0.0/1) light is illuminating when the switch is activated. If the light does not illuminate, then the limit switch may be faulty and should be replaced.
- 3. Ensure that the 'VACUUM VALVE' output (O:3.0/0) is being illuminated, and that the output is sending 24VDC. If it is not, the PLC may be faulty and should be replaced.
- 4. If the output is working properly, check the vacuum valve. If the light on the valve solenoid does not illuminate, check the wiring. If the light does illuminate but the valve does not shift, the valve may be faulty and should be replaced.
- 5. If the valve is shifting, ensure that the airlines are not cracked or clogged. Ensure that they are properly connected, as shown in the pneumatic diagram.

8.1.4 Vacuum Turns ON, But Is Weak

If the blank will not pick, but the vacuum is turning **ON**, and the cups are moving properly, the suction may be too low. The vacuum should be strong enough that it is difficult to remove a blank from the vacuum cups. To correct this problem:

- 1. Check the air pressure at the main regulator to ensure that there is adequate air supply. The machine requires 30 cu. ft. of air per minute at 100 PSI.
- 2. Ensure that the vacuum cups are not damaged or dirty. Clean or replace them as necessary.
- 3. Ensure that the PIAB vacuum filter elements are clean and free of dirt. If they are dirty, clean them out with compressed air or replace them.
- 4. If the problem persists, ensure that the main air filter is clean. If it is dirty, replace it with a new one.
- 5. If the problem still persists, the PIAB vacuum unit may be faulty,. It should be replaced or repaired.

9 ENGINEERING SPECIFICATIONS

9.1 Control Station

The control station is equipped with 'START', 'RESET' and 'EMERGENCY STOP' push buttons, 'CYCLE OFF/ON', 'GLUE OFF/ON' and 'JOG/REV/OFF/FWD' selector switches. The control panel provides an input for a remote demand sensor.

Machine Specifications		
Standard Electrical Features	240 Volt A.C., Three Phases, 60 Hz, 30A	
	Control Circuit: 24 VDC	
Air De suise se este	1 cu. Ft. Per cycle @ 90 PSI	
All Requirements	90 PSI (6.2 bar) at main air regulator	
Machine Speed	Up to 25 trays per minute	
Machina Siza	Weight: 3500 lbs. (approx.)	
	Space Required: 145' length x 62' width x 69' height	

Electrical Specifications		
Power Supply	Allen Bradley, 230 Volt A.C. to 24 Volt D.C., 4.2 ampere power supply	
Limit Switches	Omron Roller Switch	
Sensors	Omron	
Drive Motor	Baldor	
Selector Switches	Allen Bradley, 800 series	
Disconnect	Allen Bradley	
Relays	Omron	
Motor Starter	Allen Bradley Powerflex 40	
PLC	Allen Bradley Compact Logics	

Valves		
SMC	One, NAV4000-5DZ, 3/2 single solenoid, spring return for main air dump	
	Eight, NVFS3120-5DZ-03T, 5/2, single solenoid valves	

Vacuum		
SMC	FRL ASSEMBLY AC 50-DUO 3113	

Cylinders		
Pneumatic	 2 (SMC), NCA1D250-0700-XB5, for opener 2 (SMC), NCA1D250-1800-XB5 for hopper cross pusher 8 (Numatics), UTNN63-025-B for tray grip and tray stack lift 4 (Numatics), 1500DG1-02A for hopper swings 2 (Numatics), 1500DG1.5-02A for hopper gates 2 (Numatics), UTNN050-025-B for tray stop 2 (Numatics), 2000DG3-02A for opener lift 1 (Numatics), P1AK 28A1D-CAAO for center hopper cross pusher 	

10 SPARE PARTS KIT

RPC-100 - Village Farms

ITEM #	QUANTITY	PART #	DESCRIPTION
1	1	02-308	CONTACT,1 N/C
2	1	02-302	CONTACT,1 N/O
3	2	02-999	SENSOR, 18MM OPTICAL, PNP
4	1	Z00-1018	CYL 1.5 x 1 1/2" S, D. ACT, PIVOT CUSH
5	1	Z00-1009	UNIVERSAL CYL, 63mmB x 25mmS
6	1	Z00-1008	Cyl., 2.0B x 3"S, D. Act., Pivt. Cus
7	1	Z00-1405	UNIVERSAL CYL, 50mmBx 25mmS
8	1	Z00-978	VALVE 5/2 3/8" NPT PORTS
9	2	Z01-1227	DOOR SWITCH C/W KEY CAT 3
10	2	Z01-396	LIMIT SWITCH, LOW OF ROLLER LEVER, DC, M12
11	2	Z02-541	BEARING, LINEAR: 1.1/4"
12	1	Z02-550	BEARING,CAM FOLLOWER
13	2	Z02-653	ROD END MALE 5/8 NF
14	1	Z02-749	ROD END FEMALE 7/16" NF, HEAVY DUTY



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					O				DESCRIPTION	QTY.
	(10)					100.1	21-709	\\//	DMT RPC FRAME RH	1
							21-707	١٨/		1
							21-710			1
	(8)			₩.			21-711			1
						4 A	21-712			1
							21-717			1
							21-715			2
				(22)		8 X	21-716			2
			Č 🔍	\sim		9 X	21-717	1		1
		(12)				10 X	21-719		WLDMT, RPC LEG DI	1
			67	III III III III III III III III III II		11 X	21-720	WLDMT, U	PPER FRAME CROSS MEMBER	2
(5)						12 X	21-721	WLDMT, LO	OWER FRAME CROSS MEMBER	2 3
Ŷ		X	<u>Ma</u>		\sim	13 X	21-722	WLDI	MT, RPC DRIVE MOUNT A	1
		× C			(9)	14 X	21-723	WLDI	MT, RPC DRIVE MOUNT B	1
			I S			15 X	21-724	WLDN	MT, RPC DRIVE MOUNT C	1
		29//	×M		ſ.	16 X	21-725	ASSY,	DRIVE CROSS MEMBER A	1
			3			17 X	21-726	ASSY,	DRIVE CROSS MEMBER B	1
		(28)	30			18 X	21-727	ASSY,	DRIVE CROSS MEMBER C	1
			20			19 X	21-730	WLD	MT, CAM LEVER MOUNT	1
		X.				20 X	21-737	WLDM	T, LINEAR SHAFT MOUNT B	2
		\bigcirc				21 X	21-739	WLDMT, RF	PC PUSHER LIN. SHAFT MTG, FR	र 1
						22 X	21-741	WLDMT, RF	PC PUSHER LIN. SHAFT MTG, FR	2
						23 X	21-060	W	eldmt, frame foot	8
		Contraction of the second seco			×.	24 X	11-3155		CAM SHAFT MOUNT	2
			≥ 20		X	25 X	11-3164	OPEN	ER LINEAR SHAFT MOUNT	2
			\mathcal{I}		(23)	26 X	11-3206	PUSH	ER REAR LIN. SHAFT MIG.	1
		× (14)				2/ X	11-3207	וס		1
						28 /	11-3210			4
			\square	23 7		29 A	11-3211			1
		S	X 24			30 A	11-3240	CENTER		1
			\			32 X	11-3248	FLFC		2
	Q.	·	$\overline{4}$			33 X	11-3249	FLEC		2
						34 X	11-3212	CON	/EYOR SHAFT MTG, PLATE	2
		n	(6)			35 X	10-5124		SPACER	4
		\diamond	23	PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF	DIMENSIONS ARE I THIRD ANGLE PRO (3D SOLID DRAWII	IN INCHES JECTION NG)	TOLERANCES OTHERWISE SI DECI	UNLESS PECIFIED: MAL ±.030	WEXXAR Packaging	Inc.
				WEXXAR PACKAGING INC IS PROHIBITED.			DRAWN BY:	ULAR ±1°	ASSY, FRAME RPC	
Rev.	DESCRIPTION	DATE	Ву	FINISH:	DATE : 031	MAR11	APPROVED	BY:	DWG.NO. X21-757 F	REV.

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					4		6				
	$\overline{\mathcal{O}}$					NO. N	NUMBER		DESCRIPTION	N	QTY.
	(1)		a de la	(14)		1 X	21-734	WLDM	T, OPENER CY		2
		$\hat{12}$				2 X	21-735	WLDIV	II, OPENER LIF		2
			/				21-730			MTC DEAD	2
						5 X	11-3186				2
						6 X	11-3192	OPEN	JER LIFT ARM	SHAFT A	4
						7 X	11-3193	OPEN	NER LIFT ARM S	SHAFT B	4
						8 X	11-3194		RPC OPENE	R	4
						9 Z(00-1033	CYL 2"B X	3"S, D. ACT, F	PIVOT, CUSH	2
						10 Z(02-160	ROD	END FEMALE	1/2 NF	2
						11 Z(02-635	SLEEV	E: 3/4ID x 10	D x 1/2"L	16
						12 Z(02-741	ROD E	ND NF - FEMA	ALE - 3/4"	2
						13 Z(00-1449	Cylinder 2	1/2" bore x 18	" stroke - SMC	2
						14 X	21-800	ASSY, O	PENER LINEAR	BEARING/	2
				PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THE SWIMING 'S THE SOLE PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR SA WHOLE WITHOUT THE WRITH PREMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.	DIMENSIONS THIRD ANGL (3D SOLID D	s are in IN E projec Rawing)	NCHES. TOLE CTION	RANCES UNLESS ERWISE SPECIFIED: DECIMAL ±.030 FRACTIONAL ±1/32 ANGULAR ±1	WEXXAI	R Packaging	g Inc . R
				MATERIAL: AS SHOWN			DRA	AWN BY: AYC			
Rev.	DESCRIPTION	DATE	Ву	FINISH: AS SHOWN	DATE :	23MA	AR11 APP	PROVED BY:	DWG.NO.	X21-768	REV.

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		1		14		15		
		- C		ITEN	1 PART	2	DESCRIPTION	QTY.
			(16)	1	X21-728	WI	.DMT, DRIVE ARM	1
				2	X21-072X	WLDMT, ID		1
	DECEMP.		(9)	3	X20-2179	A		1
	TARK			4	X20-2180	ASSY,		1
			5	6	X11-3149	DRIV	F ARM PIVOT SHAFT	1
				7	X11-3150	CO	N ROD A, 49.625"L	1
	Š			8	X11-3151	CC	DN ROD B, 12.25"L	1
	A 400000			9	X11-3153	SPACER, 1	.5"OD X 0.500"L, 3/4" ID	2
STA -		13		10	X11-2600	CRANK	LIMIT SWITCH MT RIGHT	2
			U	11	X11-3334	CRANK		1
A CONTRACT OF				12	702 420			1
				13	702-627	FI ANGE SI	FFVF: 1"ID X 1 3/8 x 3/4" I	2
(3)				15	Z02-653	ROE	D END MALE 5/8 NF	2
				16	Z02-686	ROD	END MALE 3/4 NF	2
				17	Z01-396	LIMIT SWITCH, LO	DW OF ROLLER LEVER, DC, M12	3
			PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF WEXXRE PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF WEXXRE PACKAGING INC IS PROHIBITED.	DIMENSIONS A THIRD ANGLE I (3D SOLID DRA	ARE IN INCHES PROJECTION AWING)	TOLERANCES UNLESS OTHERWISE SPECIFIED: DECIMAL ±030 FRACTIONAL ±1/32 ANGULAR ±1	WEXXAR Packaging II	nc.
Rev DESCRIPTION	DATE	Bv		DATE ·	2MAR11	APPROVED BY:	DWG.NO. X21-767 RE	EV.

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					6				
	6		PROPRIETARY AND CONFIDENTIAL THE INFO STATISTICS THE SOLE	DIMENSIONS ARE	ITEN NO 1 2 3 4 5 6 NINCHES	M PART NUMBER X21-740 X11-3208 X11-3213 X11-3213 X11-3214 X11-3215 Z02-541 IOLEFRANCES UNLESS SPECIEFT	DESCR WLDMT, PUSHE PUSHER LINE PUSHER LINEA PUSHER BLO EARING, LINEAR 1.7	PTION R LINK MOUNT EAR SHAFT R BRG PLATE BLOCK CK MOUNT 1/4" SELF ALIGNIN	QTY. 1 2 1 1 1 1 JG 4
Rev. DESCRIPTION	DATE	Ву	PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PAPET OR AS A WHOLE WITHOUT THE WIRTEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED. MATERIAL: AS SHOWN FINISH: AS SHOWN	DATE : 10	ING)	DECIMAL FRACTIONAL ANGULAR DRAWN BY: APPROVED BY:	±.030 ±1/32 ±1* ASS AYC DWG.NO.	X21-766	REV.
(3) (10) (10) (10) (10) (10) (10) (10) (10	QTY.								
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	H 1								
	+ 1								
(10) I I I I I I I I I I I I I I I I I I I	4								
(4) 4 X11-3209 PICK LINEAR BEARING MO	JNI 4								
5 X11-3225 GRIPPER BLOCK MOUN	4								
	4								
	2								
4 10 702 542 READING LINEAD: 1" SDD 16									
11 702 653 POD END MALE 5/8 NE									
12 700-1009 LINIVERSAL CYL 63mmB x 2	mms 4								
In the Information of the State of the S	ging Inc.								

					2			
		μ (1	6)			PART NUMBER (21-743 WLDM	DESCRIPTION IT, RPC ROTARY MOUNT, RH	QTY.
					2 X	(21-744 WLDN	IT, RPC ROTARY MOUNT, LH	1
					3 x	21-745 W	LDMT, CYL REAR PIVOT	2
						(11-3222 (11-3223 SDACE		8
						(11-3223) SPACE	ΤΑΡΥ ΒΙΟΟΚ ΟΥΙ ΡΙΔΤΕ	2
			0)	r b		(11-3285 R		2
				\times	8 1	(11-3358 ROTA	RY BLOCK BACK PLATE TH	1
			$\left(\begin{array}{c} \\ 3 \end{array} \right)$		9 X	(11-3286 ROT	ARY BEARING BLOCK RH	1
	-		\bigcirc	\checkmark	10 X	(11-3287 RO	ARY BEARING BLOCK LH	1
					11 X	(11-3288	ROTARY BLOCK	1
					12 X	(11-3289 RO	ARY BLOCK BACK PLATE	1
					13 X	(11-3359	ROTARY BLOCK, LH	1
					14 Z	00-1003 CYL1	.5x2"S,D.ACT,PIVOT CUSH	2
					15 Z	00-1008 UNIVERSA	AL CYLINDER, 50mmB x 25mmS	2
					16 Z	02-101 BALL B	EARING, 1/2 ID x 1 1/8 X 3/8	4
					17 Z	202-749 ROD END	FEMALE 7/16" NF, HEAVY DUTY	′ 2
					18 C	06-101 SPRII	NG, HOLD DOWN ROLLER	8
				PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE	DIMENSIONS ARE IN INCHE	S. TOLERANCES UNLESS OTHERWISE SPECIFIED:	WEXXAR Packaging I	Inc.
				IN PART OF WEAKING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.	(3D SOLID DRAWING)	FRACTIONAL ±.030 FRACTIONAL ±1/32 ANGULAR +1°		
				MATERIAL: AS SHOWN	1	DRAWN BY: AYC.	- ASSY, KUTARY FOLDER	К
Rev.	DESCRIPTION	DATE	Ву	FINISH: AS SHOWN	DATE : 01APR11	APPROVED BY:	DWG.NO. X21-764 R	EV.

						2					
			\frown	\frown		ITEM	PART		DESCRIPTIO	ON	QTY.
			(8)	(1)		1 X	21-729	WL	DMT, CAM LI	EVER, LH	1
	•		\sim			2 X	21-738	WL	DMT, CAM LE	VER, RH	1
				\mathbf{x}		3 X	11-013	V	ACUUM CAN	/I ADJ.	2
			6			4 X	11-079		BROWNING	HUB	2
		- @				5 X	10-1652	VAC			2
				0			11-3143	VAC		1AF1, 52.5	1
	10	/	10				10 6004				
	4	/					10 2004				4
		(8)	(11)			10 70	12-228	003I CE		0.048 -	1
	$\begin{pmatrix} 1 \end{pmatrix}$	<u> </u>	\bigcirc	\checkmark		11 70	02-550	BEARING		WER: YCRS 22	2
						12 70	02-545	BEARING. F	LANGE: 1.1/2	2 x 2 Bolt - Nach	i 2
						13 Z	02-607	TA	PER BUSHING	: Q1 X 2	3
				PROPRIETARY AND CONFIDENTIAL INFORMATION CONTAINED IN THE DRAWING IS THE SOLE PROPERTIES AND A DRAWING WITH THE STRAWING PRODUCTION IN PART OR A WHOLE WITHOUT THE WRITEN PERMISSION OF WEXAR PACKAGING INC IS PROHIBITED.	DIMENSIONS ARE THIRD ANGLE PRC (3D SOLID DRAWI	E IN INCHES. OJECTION /ING)	TOLERANCES OTHERWISE SP DECII FRAC ANGI	UNLESS ECIFIED: MAL ±.030 TIONAL ±1/32 JLAR ±1°		Packaging	Inc.
				MATERIAL: AS SHOWN			DRAWN BY:	AYC	,	-	
Rev.	DESCRIPTION	DATE	Ву	FINISH: AS SHOWN	date : 28	BMAR11	APPROVED B	Y: - D	WG.NO.	X21-763	EV.

(9)	Y X @ \ / / 29 -	_					ITÉM PART NO. NUMBER	DESCRIPTION	QTY.
(36) `		1)					1 X22-185	WLDMT, TRAP DR. CYL. MTG	4
		- (<u>32</u>)					2 X21-749	WLDMT, FRONT HOPPER GATE	1
(37)		/ (25)	\sim				3 X21-751	WLDMT, HOPPER PLATE SUPPORT	2
\bigcirc			38 6				4 X21-752		1
(38)		/	/ / 19	5)			6 X21-754	WIDMI, RPC CLAMP SWING, KH	1
/			La Contraction of the second s	-17			7 X21-755	WLDMT, RPC SLIDE SWING, RH	1
$\vec{1}$							8 X21-756	WLDMT, RPC SLIDE SWING, LH	1
				50)			9 X12-1853	TRAP DOOR PIVOT MOUNT	8
) – K				10 X11-3159	RPC SIDE GUIDE, IH	1
		* <	ì				11 X11-3160	RPC SIDE GUIDE, RH	1
		X	\sim				12 X11-3161		1
		1	$\boldsymbol{\succ}$				14 X11-3165	LOWER RPC GUIDE FRONT MOUNT	2
							15 X11-3166	RPC SIDE GUIDE MOUNT A	2
		メト		\cdot \times (23) \times (3)			16 X11-3167	RPC SIDE GUIDE MOUNT B	2
		× / 4	\nearrow				17 X11-3168	RPC SIDE GUIDEJ MOUNT CLAMP A	2
		(40))				18 X11-3169	RPC SIDE GUIDEJ MOUNT CLAMP B	2
					\sim		19 X11-3196	RPC GRIPPER MOUNI	2
	(12)		- 1	(7)	×1		20 X11-3197	SPACER 1" OD X 4 100" L 1/4" TAP	2
	and the second sec	265	÷.				22 X11-3217	HOPPER SIDE PLATE MTG A	2
	(14)		, K		_		23 X11-3245	HOPPER SIDE PLATE MTG CLAMP	4
	<u> </u>	((38)		17	24 X11-3256	FRONT HOPPER GATE SHAFT	1
		C		38			25 X11-3257	REAR CYLINDER CLEVIS	2
			(1)			21	26 X11-3298	HOPPER PLATE, RH	1
			(34			\checkmark	27 X11-3299 28 X11-3200		1
			<u> </u>	(33)		_ (19)	29 X11-3301	HOPPER BACK PLATE, ET	1
					1 20 21 3	19) -	30 X11-3306	REAR HOPPER GATE SHAFT	1
			e /				31 X11-3307	GATE CYL MOUNT CLAMP	2
			V	- (18	3)		32 X11-3308	GATE CYL MOUNT	1
			Ý				33 X11-3309		2
			(TA)				34 X11-3310		2
			4				30 X11-3343 36 X10-6085		2
							37 Z02-749	ROD END FEMALE 7/16" NF, HEAVY DUTY	6
							38 Z00-1002	CYL.1.5x1"S,D.ACT.PIVT.CUS	5
							39 Z00-1008	UNIVERSAL CYLINDER, 50mmB x 25mmS	2
							40 Z02-635	SLEEVE: 3/4ID x 10D x 1/2"L	4
							41 Z00-1002	CYL.1.5x1"S,D.ACT.PIVT.CUS	1
				THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF WEXXAR PACKAGING INC ANY PEPRODUCTION	THIRD ANGLE PRO	DJECTION	IRRWISE SPECIFIED:	WEXXAR Packaging II	nc.
				IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.	(3D SOLID DRAW	'ING)	FRACTIONAL ±1/32		
					1			ASSY, HOPPER RPC	
			1	MATERIAL: AS SHOWN	1	DR	AWN BY: AYC		
Rev.	DESCRIPTION	DATE	Ву	FINISH: AS SHOWN	date : 10	MAR11 AP	PROVED BY:	DWG.NO. X21-762 RE	V.

							13 (13) (13) (14)		
		4)				ITEM NO. I	PART NUMBER	DESCRIPTION	QTY.
						1 >	X10-2606	HINGE SPACER	4
				(14)		2 >	X11-3317	PANEL SIDE GUARD	1
	\bigcirc			\bigcirc		$\frac{3}{4}$	X -33 8 V11 2210		2
						5)	x11-3320	SIDE GUARD R	1
						6)	X11-3321	HOPPER SIDE GUARD	2
						7)	X11-3322	REAR GUARD	1
						8)	X11-3323	LEXAN GUARD	3
						9)	K11-3324 REA	AR LEXAN GUARD DOOR	2
						10 >	X21-718	ASSY, SWITCH MOUNT	1
						11)	X21-784 ASSY,	SWIICH MOUNT SIDE DOO	<u>K 3</u>
						13 7	202-725 704-660 HINGE	S' Heavy Duty - CFA 65 CH	-6 10
						14 7	204-664 HANDLE:	STD DUTY M.643/140 B-5/1	6-18 5
				PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTRIBED IN THE DRAWING IS THE SOLE PROPERTY OF WEXAR PACAGING INC. ANY REPRODUCTION IN THE REPRODUCTION OF WEXAR PACKAGING INC OF PROHIBITED WEXAR PACKAGING INC IS PROHIBITED.	DIMENSIONS ARE THIRD ANGLE PRI (3D SOLID DRAW	IN INCH DJECTIO ING)	IES. TOLERANCES UNLESS OTHERWISE SPECIFIED: DECIMAL ±.03 FRACTIONAL ±1/3 ANGULAR ±1°		ng Inc.
				MATERIAL: AS SHOWN			DRAWN BY: AYC		
Rev.	DESCRIPTION	DATE	Ву	FINISH: AS SHOWN	DATE : 24	MAR1	1 APPROVED BY:	DWG.NO. X21-76	1 REV.

					6)		
			50		J	ITEM PAI NO. NUM	रा BER DESCRIPTION	QTY.
		\gg	\sim			1 X11-3	237 UPPER CENTER PUSHER MOUNT	3
	(19)		///			2 X11-3	290 CENTER PUSHER BRG PLATE BAR	2
	(7)			(15)		3 X11-3	291 CENTER PUSHER LOWER MIG	$-\frac{3}{3}$
		///	Re ex			4 X11-3	293 CENTER CR. PUSHER LIN. SHAFT	$\frac{2}{1}$
			h			5 X11-3	294 PUSHER CYL REAR CLEVIS	
		//		(17)		6 X11-3	295 CENTER CROSS PUPSHER	
			l			7 X12-2	495 CROSS PUSH LIN. BEARING PL.A	
		<hr/>				8 X12-2	496 CROSS PUSH LIN. BEARING PL.B	1
		ι	\cdot			9 A12-2		
		\[\sim			11 12-2		
)				12 X12-2		
				1. P		12 X12-2	514 CROSSTOSTER ROD END MIC	
						14 X12-2	583 SWITCH MOUNT ANGLE	$+$ $\frac{1}{1}$
						15 700-1	451 1 5" B x 28" S Rear Clevis w/Cushion & 1	$+$ $\frac{1}{1}$
				3		16 701 2		12 2
						17 702 5		2 2
						10 702 7	42 BEARING, LINEAR: 1 - SPB TO (INSK)	4
	le l)				10 V12 2		
	*			PROPRIETARY AND CONFIDENTIAL	DIMENSIONS A	ARE IN INCHES		<u> </u>
	(3)			THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.	THIRD ANGLE I (3D SOLID DRA	PROJECTION AWING)	THERWISE SPECIFIED: DECIMAL RRACTIONAL ANGULAR ±1° ASSY CENTER CROSS PUS	nc. Sher
Rev.	DESCRIPTION	DATE	Ву	MATERIAL: AS SHOWN		I	DRAWN BY: AYC	
А	REPLACED Z01-1275 WITH Z01-396	26APR11	AYC	FINISH: AS SHOWN	DATE :	23MAR11	APPROVED BY: DWG.NO. X21-760 RI	ev. A

2		4			8	8			
						ITEM PAI NO. NUM	RT BER	DESCRIPTION	QTY.
		3)			$\begin{pmatrix} 4 \end{pmatrix}$	1 X11-3	271 RPC PL	JSHER LINEAR SHAFT	2
					\bigcirc	2 XII-3	CRUSS P		2
			\cup			3 ATT-3	238 RPC CR		2
						5 X11-3	239 RFC CF		2
			7			6 X11-3	242 RPC CROS	S PUSHER ROD END M	IG 2
						7 X11-3	259 RPC CRC	DSS PUSHER SIDE PLATE	2
	\sim	0	0			8 X11-3	260 CRC	SS PUSHER BRACE	4
	(14)	Ĺ		$\overline{}$		9 X11-3	261 CROSS	PUSHER MOUNT, RH	1
	_		(2)		10 X11-3	292 SPACER, 1	" OD X .938" L, 13/32" I	D 2
						11 Z02-5	41 BEARING, LIN	IEAR 1.1/4" SELF ALIGN	JING 8
						12 Z02-7	41 ROD EN	ND NF - FEMALE - 3/4"	2
						13 X11-3	353 SPACER, 1"	OD X .3.313" L, 13/32"	ID 8
						14 Z00-1	450 Cylinder 2 1/	⁽ 2" bore x 18" stroke - S	MC 2
						15 X11-3	CROSS	PUSHER MOUNT, LH	1
						16 Z01-3	96 LIMIT SWITCH, LC	W OF ROLLER LEVER,	C,M12 2
				PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE	DIMENSION	S ARE IN INCHES	TOLERANCES UNLESS OTHERWISE SPECIFIED:	WEXXAR Packa	ging Inc.
				PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.	(3D SOLID D	RAWING)	DECIMAL ±.030 FRACTIONAL ±1/32 TI		<u></u>
Rev	DESCRIPTION	DATE	Bv					ASSY, SIDE PUS	SHERS
A A	ADDED Z01-396	26APR11	AYC	FINISH: AS SHOWN	DATE :	23MAR11	APPROVED BY: D	WG.NO. X21-7	759 REV. A

						ITEM PART NO. NUMBER 1 X11-3226 2 X11-3227 3 X11-3228	DESCRIPTION CONVEYOR TOP PLATE CONVEYOR TOP PLATE SPACE CONVEYOR CHAIN RAIL	QTY. 2 R 4 4
				18		4 X11-3229 5 X11-3230 6 X11-3231 7 X11-3232 8 X11-3233	CHAIN RAIL SUPPORT BAR INNER INFEED RAIL, LH INNER INFEED RAIL, RH OUTER INFEED RAIL, RH OUTER INFEED RAIL, LH	4 1 1 1 1 1
					22	9 X11-3234 10 X11-3235 11 X11-3236 12 X11-3243 13 X11-3246	CENTER CONVEYOR GUARD CENTER CONV. MOUNT BAR CENTER CONV. CROSS BAR HOPPER SIDE PLATE MTG B INFEED SIDE PLATE, RH	1 2 3 2 1
·C.		·			C,	13 X11-3240 14 X11-3247 15 X11-3250 16 X11-3253 17 X11-3254	INFEED SIDE PLATE, LH INFEED SIDE PLATE MOUNT CROSS FEED PLATE CROSS FEED PLATE SPACER	1 2 1 2
						18 X11-3255 19 X20-2194 20 X20-2195 21 X29-1761	ASSY, DRIVE SHAFT, INFEED CON ASSY, IDLE SHAFT, INFEED CON ASSY, MOTOR 1HP/GEARBOX 30	2 IV. 1 V. 1 D:1 1
)		PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF WEXAR PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF WEXAR PACKAGING INC IS PROHIBIED. MATERIAL: AS SHOWN	DIMENSIONS ARE IN INCHES. THIRD ANGLE PROJECTION (3D SOLID DRAWING)	22 X29-1765 TOLERANCES UNLESS OTHERWISE SPECIFIED: DECIMAL FRACTIONAL ANGULAR DRAWN BY:	ASSY, HOPPER GATE AND CYC WEXXAR Packaging TIME ASSY, INFEED CONVEY AYC	2. 2 1 Inc. 70R
Rev.	DESCRIPTION	DATE	Ву	FINISH: AS SHOWN	date: 23MAR11	APPROVED BY:	DWG.NO. X21-758	REV.

11				15 3 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		-11)				
		(16)	1)		3)	ITEM PA	ART MBER	DESCRIPTION		QTY.
			ر ر (5)		-	1 X80	-1023 SPACER,	0.75" OD X .125" L, 1	13/32" ID MTG	8
			K/	9		3 X21	-732 WLDM	, PRC LOCKER CYL	. MTG,	2
		Sol a	//			4 X11	-3178 LOC	CKER MOUNT PLATE	, RH	2
	(1)		F			5 X11	-3179 LOC	CKER MOUNT PLATE	, LH	2
	А) te				6 X11	-3180		2/22	4
	A A	\checkmark	13			7 X11	-3181 SPACER	, T° OD X 0.063" L, 1	3/32" ID	4
		\searrow	(13)			8 X11	-3182 LO	CKER HAMMER SHA	\FT	4
		(10)				9 X11	-3195 L	OCKER MOUNT BAF	२	2
						10 X11	-3199 LOCK	ER MOUNT BAR PLA	TE, RH	2
						11 X11	-3200 LOCK	ER MOUNT BAR PLA	TE, RH	2
						12 X11	-3201 LOCKER	MOUNT BAR PLATE		4
						13 X11	-3327		711	4
						14 X10	-6139 SPAC	ER,5/80DX15/32ID	K1/4L	4
						15 ZOO-	1018 Cyl. 1.5B x 1	.5S, D.ACT, C/W AD) J CUSHION	4
						16 202-	-551 BEAR	ING, RETAINING RO		8
				PROPRIETARY AND CONFIDENTIAL	DIMENSIONS AR	T / ZO2-	TOLERANCES UNLESS		AVY DUIY	4
				THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF	THIRD ANGLE PE (3D SOLID DRAV	ROJECTION WING)	OTHERWISE SPECIFIED: DECIMAL ±.030 FRACTIONAL ±1/32		CKaging Inc	С.
	DECODIDION	DATE	P				ANGULAR ±1°	ASSY, RPC LO	CK HAMMER	R
A Rev.	REPLACE X80-0779 WITH X80-1023 AND X10-3358 WITH X10-6139	4/4/2011	ву	material: AS SHOWN finish: AS SHOWN	DATE : 0	7MAR11	APPROVED BY:	DWG.NO. X	21-769 REV.	Α

			3.				6		1		
		/		3				ITEM NO.	PART NUMBER	DESCRIPTION Q	TY
								2	X12-2032	SIDE GUARD B	
								3	X12-2634	SIDE GUARD C 4	4
	ν							4	X12-2537	CROSS PUSHER GUARD	1
								5	X12-2636	TOP CONVEYOR GUARD B	1
								6	X12-2635	TOP CONVEYOR GUARD A	1
				PROPRIETARY AND CONTIDENTIAL THE INFORMATION COMPARED IN THE RAWING 6 THE SOLE PROPERTY AT AN COMPARED IN THE RAWING PRODUCTION IN PART OR AS A WHOLE WHITCH THE WRITEN PERMISSION OF WEXAR PACKAGING INC IS PROHIBITED.	DIMENSIONS , THIRD ANGLE (3D SOLID DR	ARE IN INCHES PROJECTION AWING)	TOLERANCES UNLESS OTHERWISE SPECIFIED: DECIMAL FRACTIONAL ANGULAR	±.030 ±1/32 ±1°	WEX TITLE ASS	XAR Packaging Inc.	_
	T			MATERIAL: AS SHOWN	1	4414254	DRAWN BY:	L.L.		-	
Rev.	DESCRIPTION	DATE	Ву	FINISH:	DATE :	11MAR11	APPROVED BY:	-	DWG.NO.	X22-449 REV.	

9				17 31 34 16 30 27 16 19 19 19 19 19 19 19 19 19 19 19 19 19			
						ITEM PART NO. NUMBER 1 X22-299	DESCRIPTION OTY
		$) \qquad \qquad$	24			2 X22-454 3 X22-455	WLDMT, STACKER FRAME, LH 1 WLDMT, STACKER FRAME,RH 1
		(12)	11			4 X22-300 5 X22-402	WLDMT, LOWER CROSS MEM REAR 1 WLDMT, TRAY GUIDE,LH 1
			K		5.	6 X22-403 7 X21-060	WLDMT, TRAY GUIDE,RH 1 WELDMT, FRAME FOOT 4
			Th	(33)		8 X12-352	K GEAR BOX MOUNT 1 SPACER 1"OD X 1" 11/32"ID 4
						10 X12-581	BACK STOP SLIDE 1
			A			11 X12-582 12 X12-605	SENSOR MOUNT ANGLE
	4			J' all a		13 X12-974 14 X12-974	CYL MOUNT CROSS BAR PLATE LH 1 R CYL MOUNT CROSS BAR PLATE RH 1
		11)			HL	15 X12-980	IDLER MOUNT 1 5 STACKER SHAFT, 33"I 3
		(10)				17 X12-161	CROSS GUIDE MOUNT CROSS GUIDE MOUNT CHAIN RAIL MOUNT PAP
						18 X12-251	S CHAIN RAIL MOUNT BAR 2 O CHAIN RAIL MIG. BAR PL.B 2
]	20 X12-252 21 X12-252	2 CHAIN RAIL GUIDE BAR B 2 4 CHAIN RAIL GUIDE B 2
	(1)					22 X11-296/ 23 702-278	A IDLER STANDOFF, 1.75" LONG 1
	\bigcirc					24 Z02-430	SPROCKET - IDLER: HB40C17X5/8 1
						25 Z02-435 26 Z02-548	FLANGE BEARING 3/4
						27 Z02-616 28 Z02-618	TAPER BUSHING: P1 x 1.1/2 5 TAPER BUSHING: H-5/8 1
						29 702-623	TAPER BUSHING: H-1.1/2 2
						30 202-881 31 Z02-882	SPROCKET:H40P32 5 SPROCKET:H40B32 c/w 1-1/2"Bore 1
						32 05-006 33 Z04-661	MOTOR 208/230/460,3,1760,0.33HP 1 RATCHET HANDLE:1/2x1/2NCx1. 1
				PROPRIETARY AND CONFIDENTIAL	DIMENSIONS ARE IN INCHES	34 Z02-675	COLLARS: Split - 1.1/2" (2-pc. black) 2
				THE INFORMATION CONTAINED IN THIS DRAWING IS THE SOLE PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR SA WHOLE WITHOUT THE WRITEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.	(3D SOLID DRAWING)	OTHERWISE SPECIFIED: DECIMAL ±.030 FRACTIONAL ±1/32 ANGULAR ±1*	WEXXAR Packaging Inc.
				MATERIAL: AS SHOWN		DRAWN BY: L.L.	-
Rev.	DESCRIPTION	DATE	Ву	FINISH:	date: 11MAR11	APPROVED BY: -	DWG.NO. X22-448 REV.

		4				
					ITEM PART NO. NUMBER	DESCRIPTION
					1 X12-1594	STACKER LINEAR SHAFT 2
					2 X12-1595	LIFT MOUNT 2
					3 X12-2629	TRAY LIFT CROSSBAR 1
					4 X12-341	BEARING MOUNT BRACKET 1
					5 X12-345	STACKER LINEAR MOUNT SINGLE 1
					6 X12-346	SIACKER LINEAR MOUNT DUAL 1
					/ X12-584	LIFT PLATE MOUNT 1
					δ X12-976	SPACER 4
		(2)			10 V12 070	
	/	\sum			11 112-979	
					12 ¥12-002	
	\leq	_			13 X12-983	STOP PLATE MOUNT ANGLE 4
	\sim	$\overline{0}$			14 X11-727	SLIDE BUMPER 2
	0	\rightarrow			15 Z00-1441	CYL 2" B x 9" S, FLANGE MOUNT 1" ¾-16 1
	~				16 Z02-540	BEARING, LINEAR: 3/4" 3
					17 Z02-300	LOCK COLLAR SPLIT 3/4", ZINC PLATED 2
				DIMENSIONS ARE IN INCHES	TOLERANCES UNLESS	WEXY AD Packaging Inc
			PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF	(3D SOLID DRAWING)	DECIMAL ±.03	
			WEXXAR PACKAGING INC IS PROHIBITED.		ANGULAR ±1°	
			MATERIAL: AS SHOWN		DRAWN BY: L.L	-
DESCRIPTION	DATE	Ву	FINISH:	DATE : 11MAR11	APPROVED BY:	- DWG.NO. X22-447 REV.

Rev.





						<u>(11)</u> (14)				
			8		- ADA		ITEM NO.	PART NUMBER	DESCRIPTION	QTY.
					, 		1	X12-2503	SIDE FRONT TRAP GUIDE, LH	1
					(13)) 🛆	2	X12-2504	SIDE FRONT TRAP GUIDE, RH	1
		Ø			\frown		3	X12-2505	TRAP GUIDE UPPER MOUNT, LH	1
					6		4	X12-2506	TRAP GUIDE UPPER MOUNT, RH	1
		5	\sum		0		5	X12-2507	TRAP GUIDE LOWER MOUNT	2
			Z				6	X12-2508	TRAP GUIDE CYL, REAR MTG AL	1
				12)		7	X12-2509	TRAP GUIDE CYL, REAR MTG AR	1
							8	X12-2510	TRAP GUIDE CYL, REAR MTG BL	1
							9	X12-2511	TRAP GUIDE CYL, REAR MTG BR	1
							10	X12-2512	TRAP GUIDE CYL, FR. MTG, LH	1
							11	X12-2513	TRAP GUIDE CYL, FR. MTG, RH	1
							12	Z04-660	HINGES: Heavy Duty - CFA.65 CH-6	4
							13	Z00-1004	CYL. 1.1/16"BX1"S, D.ACT	2
							14	Z02-153	ROD END FEMALE 5/16" NF	2
				PROPRIETARY AND CONFIDENTIAL THE INFORMATION CONTAINED IN THIS DRAWING TS THE SOLE PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION NUMBER OF A CANADA TO A CONTRACT OF A CANADA TO A CA	DIMENSIONS THIRD ANGL	S ARE IN INCHES	TOLERANCES UNLES OTHERWISE SPECIFIE DECIMAL	S D: ±.030	WEXXAR Packaging In	C.
				IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.			FRACTIONA	L ±1/32 TITI ±1°	ASSY, TRAP GUIDES STACK	ER
Rev.	DESCRIPTION	DATE	Ву	MATERIAL: AS SHOWN	DATE	2700110	DRAWN BY:	RS		Δ
А	REPLACED P/INO.: 200-1097 WITH 200-1004. ECO# 4701	14APRT1	L.L.	FINISH:	DAIL :	2700110	AFPROVED DT:	DV		A

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<u>Jan</u>		25				(15)		
						[ITEM PART NUMB	ER DESCRIPTION QTY.
					\land		1 X22-395	WLDMT, STACKER,CR. PUSHER FR.,LH 1 WLDMT, STACKER,CR. 1
		(20				-	3 X22-399 4 X12-2481 5 X12-2491 6 X12-2492 7 X12-2493	PUSHER FRRH 4 WLDMT, STACKER SIDE GUIDE MTG 4 SIDE GUIDE CLAMP 8 STACKER SIDE GUIDE, LH 1 STACKER SIDE GUIDE, RH 1 CROSS PUSHER MTG BAR A 2
	(18)						8 X12-2494 9 X12-2495	CROSS PUSHER MTG BAR B 4 CROSS PUSH LIN. BEARING PL.A 1
			\bigcirc			-	10 X12-2496 11 X12-2497	CROSS PUSH LIN. BEARING PL.B 1 CROSS PUSH CYL. MOUNT A 1
			6			-	12 X12-2498 13 X12-2499 14 X12 2500	CROSS PUSH CYL. MOUNT B 1 CROSS PUSH CYL. MIG. SPACER 2 CROSS PUSH LIN SHAFT 42 212" LONIC 2
						-	15 X12-2501 16 X12-2502	CROSS PUSH LIN. SHAFT BAR 1 CROSS PUSH LIN. SHAFT BAR 1 CROSS PUSH CYL_SUPPORT 1
				23	4		17 X12-2514 18 X12-2515	CROSS PUSHER ROD END MTG 1 CROSS PUSHER PLATE 1
				XL .	\bigcirc	-	19 X12-2516 20 X12-2517	SIDE BACK GUIDE, LH 1 SIDE BACK GUIDE, RH 1
							21 Z00-1036	CYL 1.5 B x 26"S, D.ACT, CLEVIS, CUSH
							22 Z02-751 23 Z02-542	ALIGNMENT COUPLER 7/16UNF 1 BEARING, LINEAR: 1" - SPB 16 (NSK) 4
							24 Z01-1275 25 X12-2582	LIMIT ROLLER SWITCH, OMRON, 2 SWITCH MOUNT ANGLE 1
					DIMENSIONS ARE I	IN INCHES.	26 X12-2583 TOLERANCES UNLESS	SWITCH MOUNT ANGLE 1
				PROPERTY OF WEXXAR PACKAGING INC. ANY REPRODUCTION IN PART OR AS A WHOLE WITHOUT THE WRITTEN PERMISSION OF WEXXAR PACKAGING INC IS PROHIBITED.	(3D SOLID DRAWIN	NG)	DECIMAL ±.030 FRACTIONAL ±1/32 ANGULAR ±1°	
		1	1	material: AS SHOWN	,		DRAWN BY: RS	
Rev.	DESCRIPTION	DATE	Ву	FINISH:	DATE : 260	OCT10	APPROVED BY:	DWG.NO. X22-406 REV.

