

Mobile Rope Tension Measuring System MSM12

henning



Operating Instructions

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Warranty

This description has been drawn up by Henning GmbH to the best of their knowledge. all technical statements have been carefully established and checked. They correspond to the state of the art. Changes and errors excepted. Our application engineering advice - spoken and written - shall support your own work. It is regarded as an indication without obligation - also with regard to possible third party industrial property rights - and does not release you from your own obligation to carry out appropriate testing of the products regarding their suitability for the intended application. Product descriptions do not contain statements about the liability for possible damages. However, should a liability be involved, it would be limited for all damages to the value of the goods supplied and used.

Technical Data

Part Number: 455100 or 455200

Dimensions L x W x H: 7.5 in x 5.4 in x 1.8 in.

Weight: 1.5 lbs. (incl. batteries)

Interfaces: 1 x USB1.1 for the connection to a PC

12 x connections to the rope load sensor LSM

1 x connection for Bluetooth aerial (optional)

Batteries: 4 x AA

Data Transfer: Bluetooth Class 2

Degree of protection: IP 00

Class of protection: SKIII (SELV)

1. Contents of System

1 x Mobile Rope Load meter (MSM12)

1 x External antenna (Optional)

(Part no. 45000404)

1 x Bluetooth USB Adapter class 1 (Optional)

(Including driver and documentation CD)

(Part no. 45000403)

1 x USB-A-B cable 6ft.

4 x LSM sensors or 6 x Mobile Rope Sensors

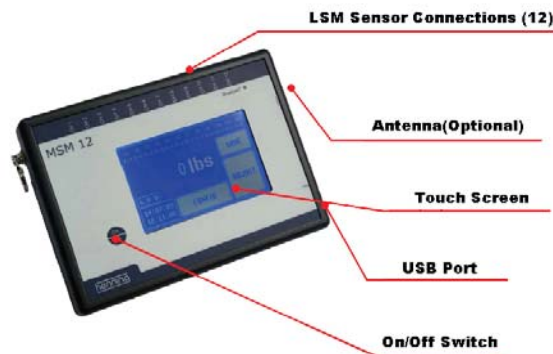
(Part no.: 455100 or 455200)



2. Power Supply

The MSM12 display unit requires 4 x AA batteries. Rechargeable batteries may be used if they have an output of at least 2,000mAh. The MSM12 does NOT charge the batteries; a battery charger must be supplied by the user.

3. MSM12 Description

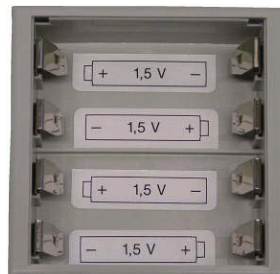


4. Initial Setup

Remove the battery compartment door. Insert the batteries according to the polarity shown on graphic inside the battery compartment. Caution: Improper installation of the batteries may damage the unit! Note: Batteries should be removed from the MSM12 unit if the unit is being stored for an extended period of time.

MSM12 with Bluetooth option:

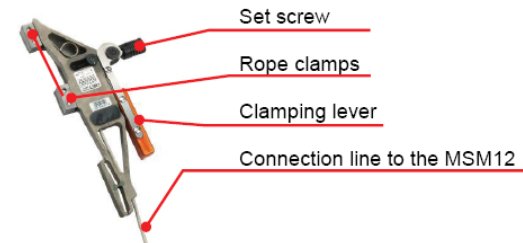
Screw the factory supplied antenna to the connector located on the side of the MSM12 unit. Note: For best signal, it is advised that you point the antenna in an upward direction.



5. Connecting the MSM12 to a PC

The PC software that corresponds with the MSM12 is available for download at www.henning-gmbh.de free of charge.

6. LSM Sensor Description

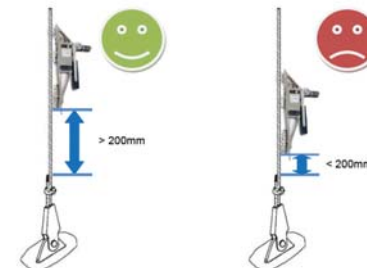


6.1. Mode of Operation

The rope sensor is based on a patented measuring procedure which, for the first time, permits the carrying out of absolute weight measurements without calibration in the rope. Inside the sensor there is a strain gauge the signals of which are conditioned by the integrated electronics and are passed via the USB plug of the sensor to the rope load evaluation unit MSM12. Each rope sensor LSM is individually calibrated.

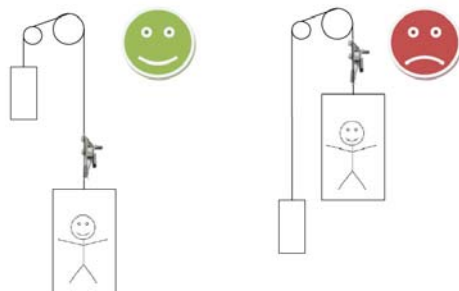
7. Sensor Installation

The sensor must be mounted with a minimum distance of 8 inches from the cable joint. See photo below. Note: Only one sensor per rope should be used, otherwise will result in inaccurate measurement.

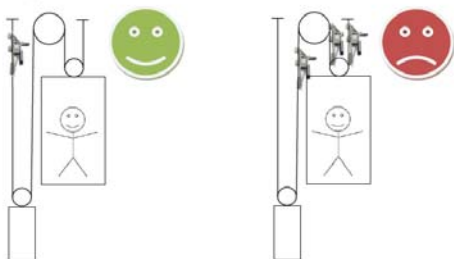


Suspension mounting points

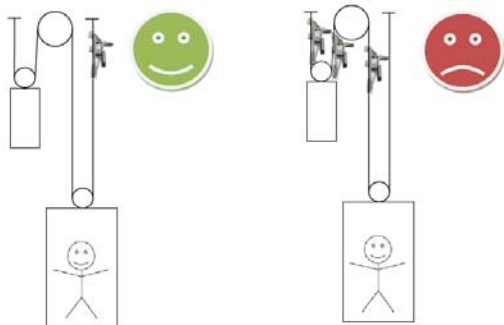
1:1 Suspension



2:1 Suspension



weigh counter weight

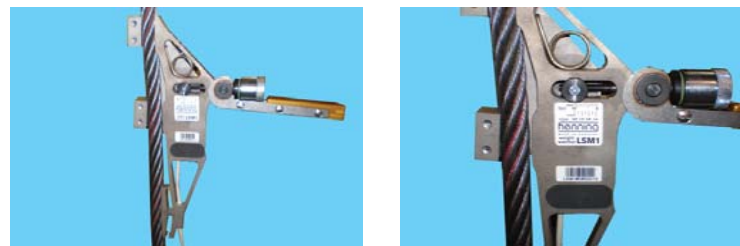


weigh car

7.1 Sensor Installation Continued

Step 1 - With sensor lever open, use the thumb screw to open the sensor as far as needed to fit sensor around the rope.

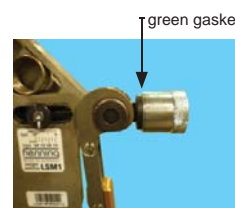
Step 2 - With sensor lever still open. Using the scale, use thumb screw to tighten sensor to the diameter of the rope it is being installed on. See photos below.



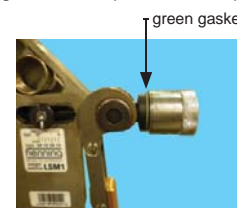
Step 3 - Clamp down the sensor lever. The lever should have some resistant but should be easily clamped by hand. DO NOT use tools to clamp the lever. If the lever cannot be clamped by hand, something is incorrect. See photo below.



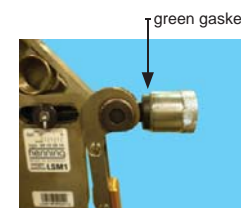
Step 4 - Using the green gasket on the thumb screw as a guide; fine tune the sensor for the most accurate reading. Using an Allen wrench either tighten or loosen the thumb screw until half of the green gasket is exposed. See photos below.



Incorrect - Too Tight!
No green gasket showing



Incorrect - Too Loose!
Too much green gasket showing



Correct!

Step 5 - Repeat for all sensors

7.2 Switching MSM12 display unit on

To turn on the MSM12 display unit, press and hold the “on/off” button for a minimum of 3 seconds. The display should turn on and show the Henning logo. After the logo is displayed it should automatically jump to the main display screen. The MSM12 is now operational and will start to give real time readings of the sensors. Note: If this procedure does not work, the batteries may be too low to run the unit, please replace the batteries and try again.

To turn the MSM12 display unit off, press and hold the “on/off” button for a minimum of 3 seconds until the display turns off.

Spent batteries should be replaced completely and promptly. Do NOT mix spent batteries with fresh batteries. Replace all 4 batteries at once. Note: If the MSM12 is left without power for more than 20 minutes, the MSM12 clock will need to be set again.

7.3 Main Display

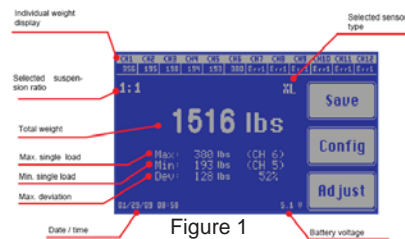


Figure 1

The individual weight display shows the measured load of each connected rope load sensor (LSM). If no sensor is connected to the port or if the sensor is defective, Err1 will be displayed at that port. If a connected sensor is overloaded Err2 will be displayed at that port.

The suspension ratio of the elevator can be selected by the user. The displayed total weight is calculated by this factor. The individual weight of each sensor is not affected by this setting.

Total weight is the sum of all individual readings measured. The total weight will display according to the suspension ratio chosen by the user. For example, if you have a 1:1 ratio, the total weight will be the exact total of each sensor reading. If you have a 2:1 ratio, the rope weights will display actual weight, but a calculation is done to display the correct total weight for a 2:1 system.

The maximum individual rope load displays the highest weight displayed by a given sensor.

The minimum individual rope load displays the lowest weight displayed by a given sensor.

The maximum deviation shows the absolute and percentage of deviation of the rope with the greatest deviation from the mean value of all ropes. The example in figure 1, (page 8), shows the total weight of 1,516 lbs. distributed among 6 ropes. This means that under ideal conditions each rope should carry 252 lbs. corresponding to 52% more load.

The voltage display shows the real time voltage of the battery.

8. Menu System

Figure 2 shows the menu structure of the MSM12.

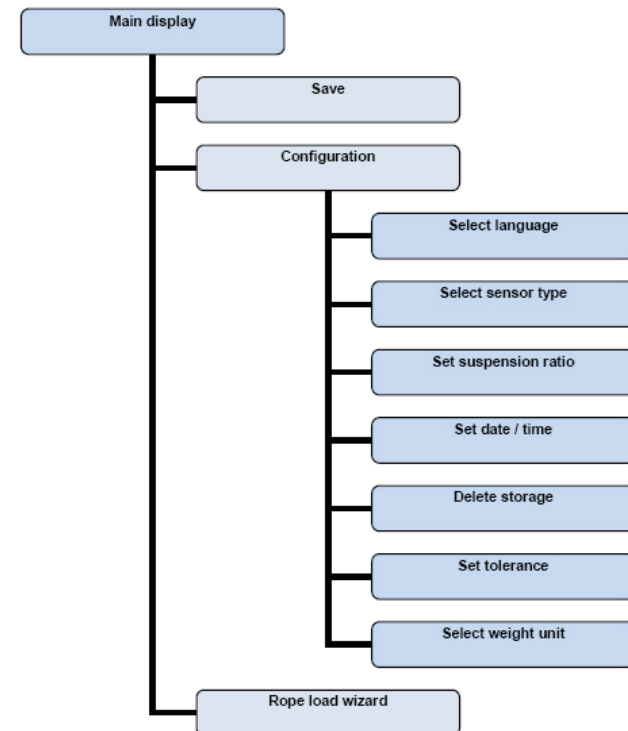


Figure 2

By pressing the CONFIG button you will access the configuration menu. The rope load wizard can be found by pressing the Adjust button and in order to switch to the storage menu, you must press the Save Button.

8.1. Save Current Sensor Readings

By pressing the “Save” button, you can store the current individual rope readings and the total weight in the internal memory of the MSM12.

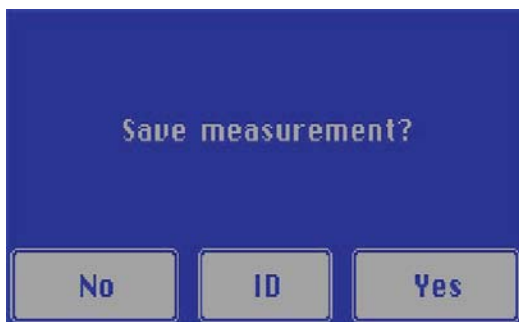


Figure 3: Saving of the rope loads

When you choose “YES” when asked if you’d like to save, the measurements are immediately stored. If you choose “NO” you will exit the menu and the readings will not be saved. It is possible to save a measurement under a specific ID for easier retrieval or archiving. When the ID button is pressed it will take you to a virtual keyboard allowing you to enter your unique ID (up to 16 characters).



Figure 4: Assignment of the measurement ID

8.2. Configuration

The configuration menu is represented in figure 5.



Figure 5: Configuration menu

8.2.1 Select Language

Under the language setting you have the choice of either English or German(Deutsch). Caution: If language is changed; this setting can only be changed again by navigating to the language menu. Resetting the unit does NOT reset the language.



Figure 6: Selection of the language

8.2.2. Sensor Type

The MSM12 has the ability to work with 3 different sensor types, they are as follows:

- LSM1 Diameter 1/4"(6mm) – 5/8"(16mm)
- LSM2 Diameter 1/6"(4mm) – 1/3"(10mm)
- LSM-XL Diameter 5/8"(16mm) – 1"(24mm)

Depending on which sensor is used, it must be selected by the user. The MSM12 unit will NOT automatically detect which sensor type is being used. By default the sensor type selected is LSM1. Note: The sensor setting is stored in memory, restarting the MSM12 unit will NOT change this setting back to default (LSM1).

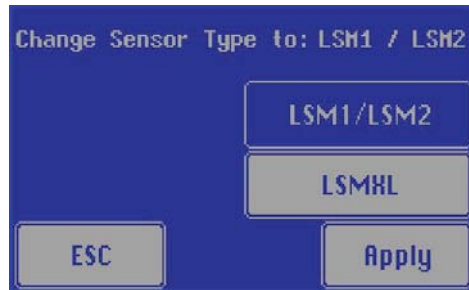


Figure 7: Selection of the sensor type

8.2.3. Suspension Ratio

In this menu section you can choose the suspension ratio of the current elevator. The ratio is displayed on the main display in the upper left corner. Note: This setting is not stored in memory. Once the MSM12 has been switched off, it will default back to 1:1 ratio.



Figure 8: Suspension ratio setting

8.2.4. Time/Date

In this section you can set the internal time clock of the MSM12 unit. You can also set the date in this section. When a load measurement is saved, it is time and date stamped so it is important that the time and date are set correctly. Note: If the MSM12 is without power for more than 20 minutes, the time and date will have to be reset again.



Figure 9: Set data/time

8.2.5 Delete Memory

In this section you can choose to clear out all stored measurement data. If "YES" is pressed, all measurement data is cleared. If "NO" is pressed, all stored measurements remain intact and you will exit from this menu. Note: Clearing memory only deletes stored measurements, all settings will remain unaffected.

CAUTION: Once measurements are deleted they are IRRETRIEVABLE.



Figure 10: Delete Storage

8.2.6 Set Tolerance

Under this section you can set the tolerance of the rope load wizard. This is a user definable percentage of accuracy. If a specific job does not require a great deal of accuracy of rope deviation the tolerance can be set at a higher number to allow a lower percentage of accuracy. 0 would be very accurate, 9 would 9% deviation in either direction allowable.



Figure 11: Set tolerance

8.2.7 Units

This section allows the user to change the displayed units of measure. The user has 3 choices of measurement: Kilograms (kg), Pounds (lbs) in short tons, and Pounds (lbs) in long tons. Note: Short tons should be used in the United States if the user is looking for accurate readings in Pounds (lbs.) Long tons are generally used in Europe and kilograms in other parts of the world.

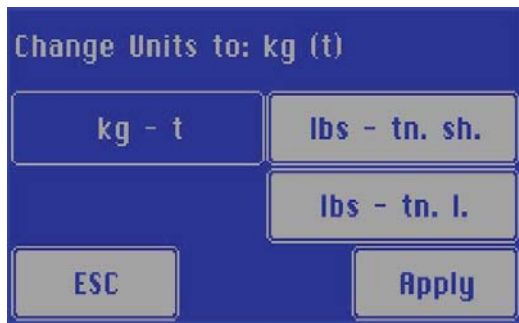


Figure 12: Display unit setting

8.2.8 Rope Load Wizard

The rope load wizard will assist you in the uniform adjustment of the ropes. The wizard uses the current rope loads and calculates a new desired rope load for each rope. The changed rope load distribution is already taken into consideration when re-adjusting a rope. Due to a special calculating algorithm it is possible that after only one adjustment run all ropes bear the same load. In addition, during each adjustment process the wizard searches for a reference rope which does not have to be adjusted. Note: The rope load wizard is only available for use when two or more ropes are present.

In figure 13 you see the connected sensors, in this case six sensors. The MSM12 unit has determined that sensor 2 is the reference rope; this rope will not need adjustment. While adjusting the ropes the goal for each rope is to reduce its shaded area down to the center line.

As soon as all ropes are adjusted, you may exit the rope wizard by pressing "OK".

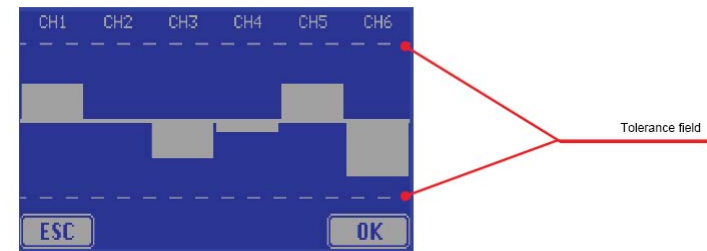


Figure 13: Rope load wizard

After completing the rope adjustment and pressing "OK" the unit will prompt you to save. If you wish to save the measurement press "YES", if you wish to name the measurement with a unique ID and save it, press "ID", and if you wish to not save the measurement, press "NO". Note: The measurement must be saved if you plan to use the PC software to generate a report of maintenance for a particular job.

