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Introduction

Glentek's SMA6520 series linear servo amplifiers provide the optimum solution for applications which require high current loop bandwidth, low radiated electrical noise and zero crossover distortion. These amplifiers incorporate our latest generation ISO-BIAS current sense technology which provide one of the lowest drift linear amplifiers on the market today. These amplifiers are constructed using surface mount technology and incorporate the latest in heat transfer technology which make them one of the most powerful amplifiers for a given form factor.

Typical applications which are ideal for the SMA6520 series amplifiers include low inductance/resistance brushless and brush motors (linear or rotary), high resolution linear brushless motor stages and voice coil motors.

The SMA6520 series is highly configurable and can operate in the following modes:

1. 2-phase sinusoidal commutation (-11 plug-in board) of three-phase brushless servo motors. In this mode, the amplifier accepts two +/- 10V analog inputs as a current command reference for two of the motor phases. The third phase is derived within the amplifier from the two reference phases. This amplifier does not use any feedback devices and is used with controllers that provide the commutation.
2. Trapezoidal commutation (-12 plug-in board) of three-phase brushless servo motors. In this mode, the amplifier accepts a +/- 10V analog input as a current command reference and utilizes the Hall Sensors which are mounted on the motor for commutation of the motor in current (torque) mode.
3. The driving of voice coils or DC brush servo motors (-11 plug-in board) in current (torque) mode. In this mode, the amplifier accepts a +/- 10V analog input as a current command reference.

FEATURES

- Ergonomic Design Easy access to connections, adjustments and test points.
- SMT construction Provides ultra compact size, cost competitive package and high reliability.
- Bandwidth All servo amplifiers have a nominal 10 kHz current loop bandwidth which varies with the motor inductance.
- Linear output stage Provides high bandwidth, low noise and zero crossover distortion.
- Multimode operation The 2-Phase Sinusoidal servo amplifier can drive 3-phase brushless motors, voice coils or DC brush servo motors in current (torque) mode. The Trapezoidal servo amplifier can drive 3-phase brushless motors in current (torque) mode. In addition, the Trapezoidal servo amplifier can close the velocity loop via feedback of a DC tachometer.
- Wide operating voltage Operating voltages range from either +/-20 to +/-75 VDC for standard heatsink Module/large heatsink module w/fan and cover versions and +/-17 to +/-53 VAC for the 2-Axis chassis version.
- Industry std. mounting Available in a standard heatsink Module, large heatsink module w/fan and cover and a 2-Axis chassis version. Optional custom mounting configurations are available to meet virtually any requirement.
- Two basic versions Available in Trapezoidal and 2-Phase/3-Phase Current Mode commutated versions.
- Fault protection Short from output to output, short from output to ground, amplifier RMS over current, amplifier under/over voltage and amplifier over temperature.
- Motor over temp. An input is provided for a motor over temperature switch and will shut down the drive and display a fault.
- Status indicator 7-segment LED display indicates amplifier status and diagnostics.
- Dedicated inputs +/- limits, enable, fault, motor over temperature and reset for Trapezoidal version. Enable, fault, motor over temperature and reset for 2-phase sinusoidal version.
- External fault reset An input is provided to reset the amplifier in the event of a fault.
- Manual reset A push button reset is available to reset a fault.
- Current limit Peak motor current is adjustable.
- CE compliant All servo amplifiers are CE marked.

Technical Specifications

Output Power

- 400 Watts continuous, 2000 Watts peak (heatsink module version @25°C)
- 500 Watts continuous, 2000 Watts peak (heatsink module w/fan and cover version @25°C)
- 5 amps continuous, 25 amps peak

Note 1: Current trip time and peak current is adjustable.

Note 2: Output power ratings based on Glentek or customer supplied airflow.

Input Connections

- Bipolar supply voltage: +/-20 to +/-55VDC (Standard voltage)
- Bipolar supply voltage: +/-25 to +/-75VDC (High voltage)
- Auxiliary bias supply voltage: +/-15VDC regulated, +/- 400 mA
- Command A & B analog signals: +/-20V maximum (differential)
- Fan power for large heatsink module with cover: 24VDC
- Fan power for 2-axis chassis: 120 VAC, single phase
- Manual reset Pushbutton switch
- Reset: Pulled up, Active low
- Enable: Pulled up, Active low
- +/- Limits: Pulled Up, Active low for Trapezoidal version and configurable for active low or active high for Encoder-based version
- Hall sensors: Pulled Up, Active low for Trapezoidal version
- Motor over temperature: Pulled up, Active High (normally closed switch)

Output Connections

- Motor phases A, B and C
- Fault out: Open collector, Pulled Up (5V), Active low (TTL to 24V compatible)

Bandwidth

- 10 kHz maximum and varies with motor inductance

Status Indicator

- 7-segment LED display indicated amplifier status and diagnostics

Mechanical

- Standard heatsink module version (Length: 8.0", Width: 2.5", Height: 7.5")
- Large heatsink module w/fan & cover version (Length: 10.17", Width: 5.31", Height: 7.95")
- 2-axis chassis version (Length: 12.75", Width: 10.25", Height: 8.0")

Environmental

- Operating temperature 0 to 65C
- Storage temperature -40 to 80C
- Humidity 5 – 95% relative (non-condensing)

MODEL NUMBERS

Glentek's SMA6520 series linear servo amplifiers are offered in two module styles; the standard 50HS and the 50HF (which has a cover and a fan). Both modules accept either of the available plug in boards (2 Φ sinusoidal commutation or Hall/Trapezoidal commutation).

A baseplate design with 2 slots available for modules has a bridge rectifier and filter capacitors for the required bipolar DC voltage for the modules along with the +/-15VDC logic supply needed for the bias voltages.

MODULES: First 4 Columns MULTIAXIS BASEPLATES: All Columns						
MODEL NUMBERING					DESCRIPTION	
SMA6520-	-----	---	----	---	-	Linear Amplifier Series, Module & Baseplate Configuration
	50HS					Standard Heatsink Module
	50HF					Large Heatsink Module, w/ Fan & Cover
		11				2 Phase Sinusoidal Current Mode Plug In Board (Personality Board)
		12				Hall Sensor/Trapezoidal Commutation, Current Mode Plug In Board (Personality Board)
		24				Encoder Based Sinusoidal Commuta- tion, Current or Velocity Mode Plug In Board (Personality Board)
			003			Standard Voltage Configuration Power Board, +/-55VDC
			006			High Voltage Configuration Power Board, +/-75VDC
				1		Module or Module w/ Fan & cover
				2A	0	2 Axis Baseplate w/ Fans and Power Supplies, 0 = no modules installed
				2A	1	2 Axis Baseplate w/ Fans and Power Supplies, 1 = 1 module installed
				2A	2	2 Axis Baseplate w/ Fans and Power Supplies, 2 = 2 modules installed

Note: Voice coil and DC brush modes are also available upon request.

STARTUP

Refer to the technical specifications page and the drawings in the appendix for the information needed to supply the correct power and to wire the model you are starting up. When the wiring is completed and verified, the initial pot adjustments can be made. Turn on the bias supply ($\pm 15\text{Vdc}$), it is not necessary to connect the load or turn on the main bipolar supply yet.

2 Phase Sinusoidal Current Mode pot adjustments (Refer to 6520-11 schematic in the appendix):

Current Limit (RV1): The current limit pot sets the peak output current the amplifier can deliver to the load. The range is $\pm 3\text{A}$ to $\pm 25\text{A}$. Set RV1 by adjusting the pot to the desired value by measuring the voltage at TP2, 0 volts is the minimum and 5 volts is the maximum current.

Input Signal Gain: There are two gain pots, one for each phase, the adjustment procedure is the same for both. The pots (RV2 & RV3) scale your input signals to the desired currents you wish to command. Apply a known input signal and adjust the pot to the desired current using a scale factor of 4.5A/V at the test point connected to the pot wiper. Repeat for the second phase. Avoid setting the gain such that the input signals command currents above the current limit. This will prevent your current command signal from being clipped.

Hall Sensor/Trapezoidal Output Current Mode pot adjustments (Schematic 6520-12):

Current Limit (RV2): The current limit pot sets the peak output current the amplifier can deliver to the load. The range is $\pm 0\text{A}$ to $\pm 25\text{A}$. In order to set the current limit, temporarily remove the microshunt at J4. Then adjust RV2 until the measured voltage at TP2 equals the desired peak current (use a scale factor of 4.5A/V). Restore the J4 microshunt to its original (current mode) position.

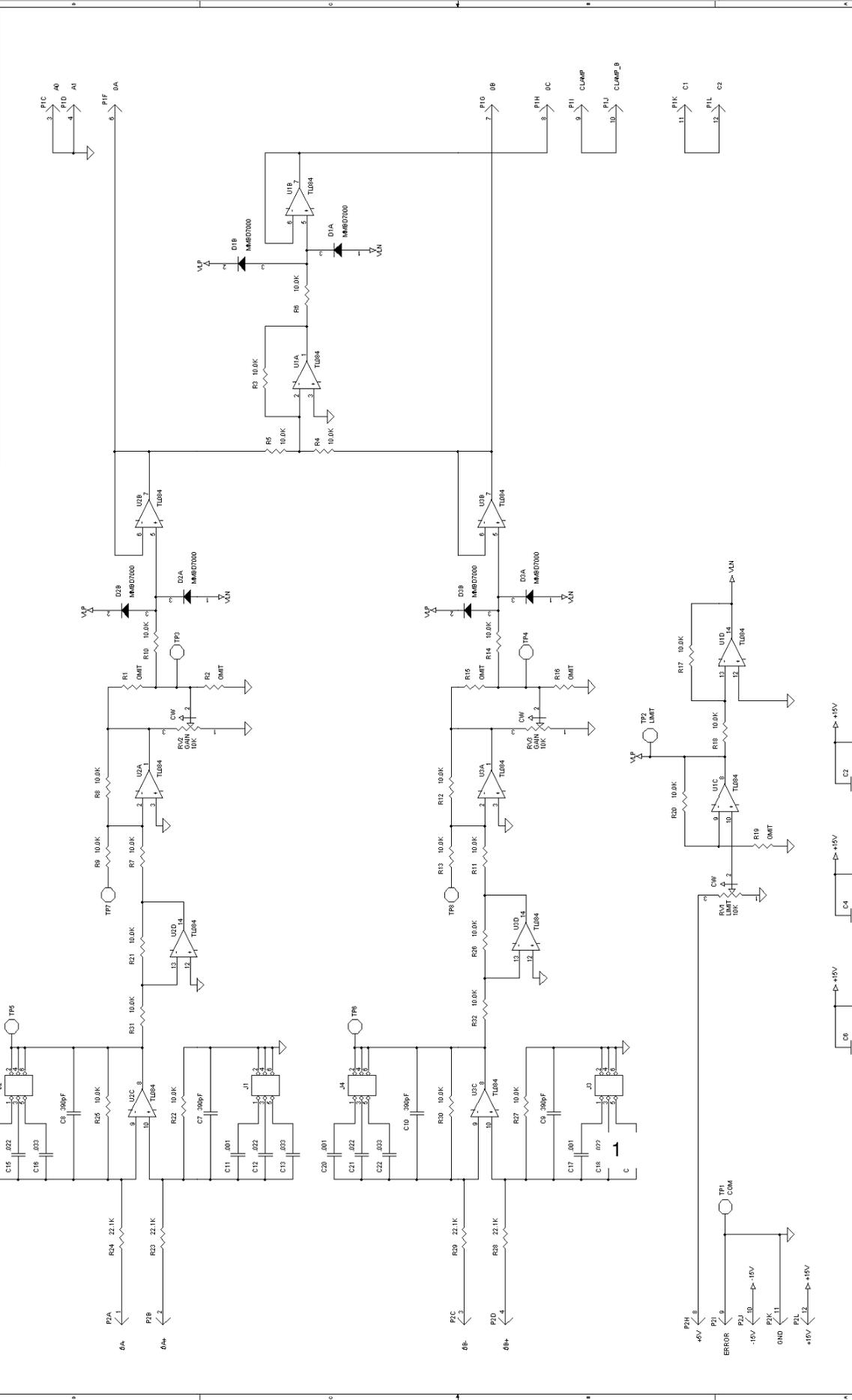
Balance (RV1): The balance pot can be used to deal with offsets in the amplifier and offset in the input signal. A good initial setting is to set the wiper to the midpoint. After the load is up and running final adjustment can be made if needed.

Input Signal Gain (RV5): The signal input gain pot scales your input signal to the current you want to command. Apply a known input signal and adjust RV5 to the desired voltage at TP2 using a scale factor of 4.5A/V . Avoid setting the gain such that the input signal commands current above the current limit. This will prevent your current command signal from being clipped.

These pot adjustments may be all the adjustment needed. Continue with the startup process by connecting the load and applying the main power to the amplifier.

APPENDIX

REV	DESCRIPTION	ECO	DATE	CHG BY	APPD BY
B	REFERENCE ECO	1098	15AUG00	S.A.S.	M.H.
B	REFERENCE ECO CLEANUP NO CHANGE	1485	21JAN02	C.J.	D.B.



HIGHEST REFERENCE DESIGNATOR USER		DESCRIPTION		REV	
C22	D3	J4	P2	P18	R10
U5					
REFERENCE DESIGNATOR USER		MODEL NUMBER		DRAWING NUMBER	
		6520-11		6520-1100-000-B	
DRAWN BY: DATE		ASSY PIN: DATE		TEST PROC. NUMBER: SHEET: 1 OF 1	
M. Hess 9 Aug 2000		6520-1102-000-B		6520-1103-000-B	
CHECK BY: DATE		APPR. BY: DATE		SIZE C	

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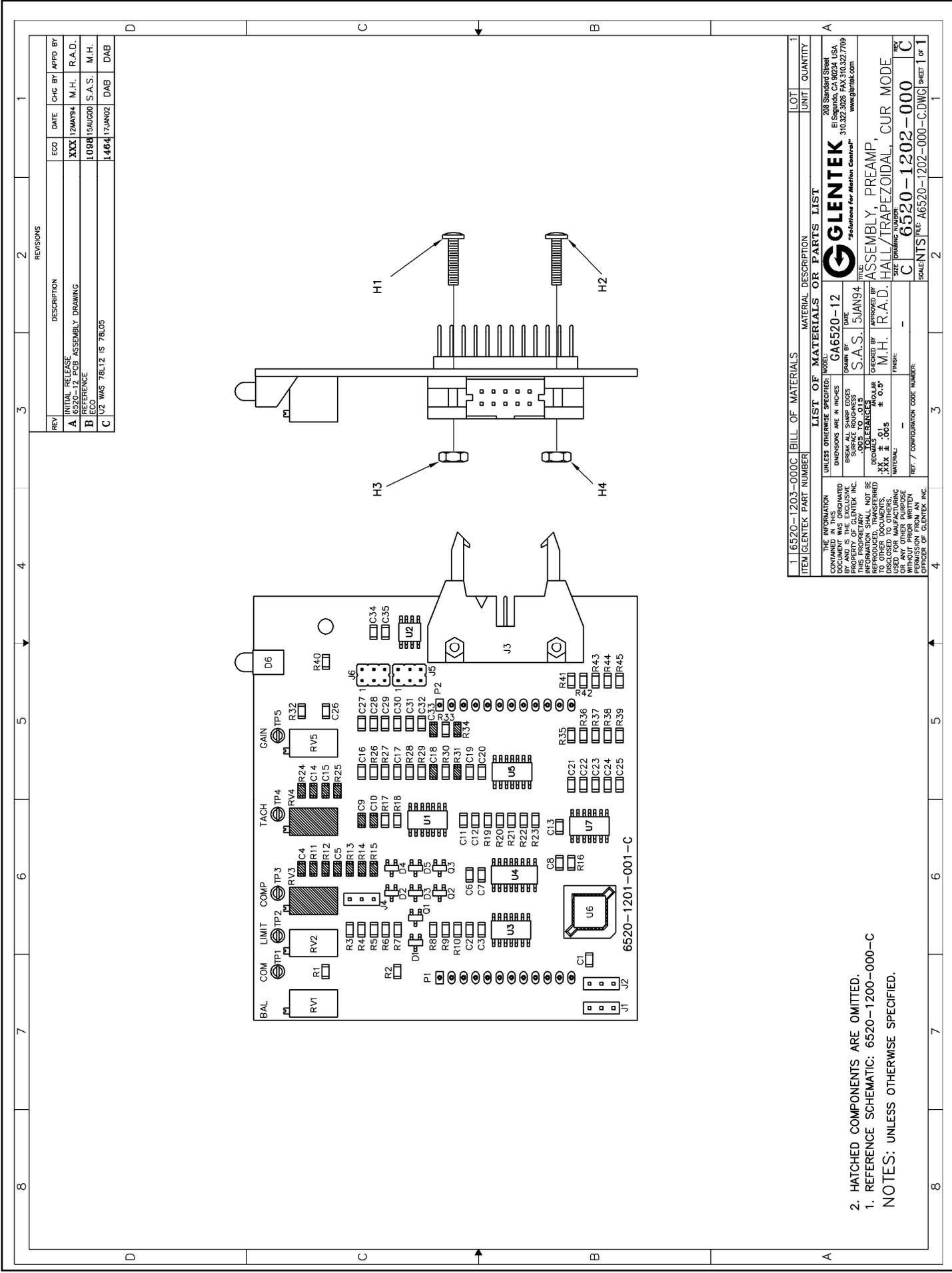
MODIFICATION DATE: Tuesday, January 23, 2002

FCB 6520-1101-001-9

2. CAPACITANCE IS IN MICROFARADS.
1. RESISTANCE IS IN OHMS, 1.8W, 1%.

NOTES: UNLESS OTHERWISE SPECIFIED

SMA6520 SERIES MANUAL



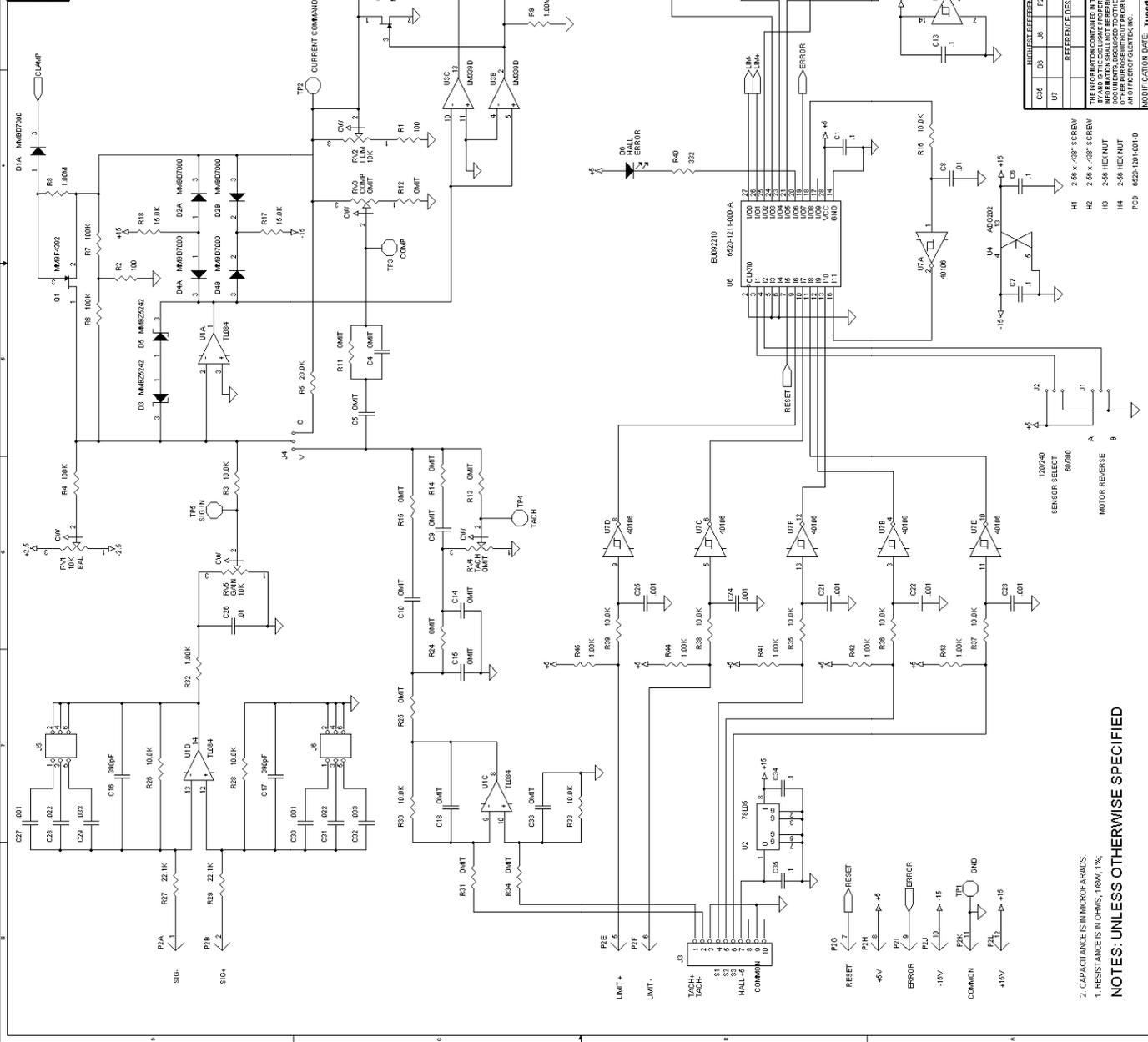
REV	DESCRIPTION	ECD	DATE	CHK BY	APPD BY
INITIAL RELEASE					
A	6520-12 PCB ASSEMBLY DRAWING	XXX	12MAR94	M.H.	R.A.D.
B	REFERENCE	1088	15AUG00	S.A.S.	M.H.
C	U2 WAS 78L12 IS 78L05	1464	17JAN02	DAB	DAB

REVISIONS	
1	
2	
3	
4	
5	
6	
7	
8	

ITEM	GLENTEK PART NUMBER	1. 6520-1203-000C	BILL OF MATERIALS	MATERIAL DESCRIPTION	LOT	UNIT	QUANTITY
<p>UNLESS OTHERWISE SPECIFIED, DIMENSIONS ARE IN INCHES. BREAK ALL SHARP EDGES. SURFACE ROUGHNESS .001. TOLERANCES: ANGULAR ± 0.5°. DIMENSIONS ± .005. FINISH: -</p> <p>REF. 7 CONFIGURATION CODE NUMBER: -</p>							
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<p>LIST OF MATERIALS OR PARTS LIST</p> <p>MODEL: CA6520-12 DATE: 5JAN94 DRAWN BY: S.A.S. CHECKED BY: M.H. APPROVED BY: R.A.D.</p> <p>SCALE: 1:1 DRAWING NUMBER: 6520-1202-000 SHEET 1 OF 1</p>							
<p>GLENTEK "Solutions for Motion Control"</p> <p>208 Standard Street El Segundo, CA 90245 USA 310.322.3026 FAX 310.322.7709 www.glenetek.com</p> <p>ASSEMBLY, PREAMP, HAL/TRAPEZOIDAL, CUR MODE</p>							

2. HATCHED COMPONENTS ARE OMITTED.
 1. REFERENCE SCHEMATIC: 6520-1200-000-C
- NOTES: UNLESS OTHERWISE SPECIFIED.

REV	DESCRIPTION	ECO	DATE	CHK BY	APPR BY
B	REFERENCE ECO	1038	15AUG00	S.A.S	M.H.
C	U2 MGS 12L12 IS 78L05	1484	17JAN02	DAB	DAB



REVISIONS					
ECO	DATE	CHK BY	APPR BY		
1038	15AUG00	S.A.S	M.H.		
1484	17JAN02	DAB	DAB		

REV	DESCRIPTION	ECO	DATE	CHK BY	APPR BY
B	REFERENCE ECO	1038	15AUG00	S.A.S	M.H.
C	U2 MGS 12L12 IS 78L05	1484	17JAN02	DAB	DAB

SCHEMATIC		DRAWN BY: DATE		DRAWING NUMBER	
Top Sch p-board for 6520-xx		M. Hess 9 Aug 2000		6520-1200-000	
MODEL NUMBER: 6520-12		ASSY P/N: 6520-1202-000-C		TEST PROC NUMBER: 6520-1204-000-C	
CHECK BY: DATE		APPR. BY: DATE		SHEET: 1 OF 1	
REFERENCE DESIGNER(S) NAME		MODIFICATION DATE: Tuesday, January 23, 2002		SIZE: C	

HIGHEST REFERENCE DESIGNER(S) NAME: U1, U2, U3, U4, U5, U6, U7, U8, U9, U10, U11, U12, U13, U14, U15, U16, U17, U18, U19, U20, U21, U22, U23, U24, U25, U26, U27, U28, U29, U30, U31, U32, U33, U34, U35, U36, U37, U38, U39, U40

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MODIFICATION DATE: Tuesday, January 23, 2002

SIZE: C

U1 256 x 488 SCR (U7)

U2 256 x 488 SCR (U8)

H1 256 x 488 SCR (U7)

H2 256 x 488 SCR (U8)

H3 256 HED NUT (U8)

H4 256 HED NUT (U8)

F43 6520-1201-01-9

1. RESISTANCE IN OHMS, 100% 1%.

2. CAPACITANCE IN MICROFARADS.

NOTES: UNLESS OTHERWISE SPECIFIED

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Omega Series Digital PWM Brushless Servo Amplifiers

- PWM (Pulse-Width-Modulated) Brushless servo amplifiers to 20KW

Analog Brush Type Servo Amplifiers

- Linear Brush type servo amplifiers to 2.6KW
- PWM (Pulse-Width-Modulated) Brush type servo amplifiers to 28KW

Analog Brushless Servo Amplifiers

- Linear Brushless servo amplifiers to 3.5KW
- PWM (Pulse-Width-Modulated) Brushless servo amplifiers to 51KW

Permanent Magnet DC Brush Type Servo Motors

- Continuous Torques to 335 in. lb.
- Peak Torques to 2100 in. lb.

Permanent Magnet DC Brushless Servo Motors

- Continuous Torques to 1100 in. lb.
- Peak Torques to 2200 in. lb.



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