

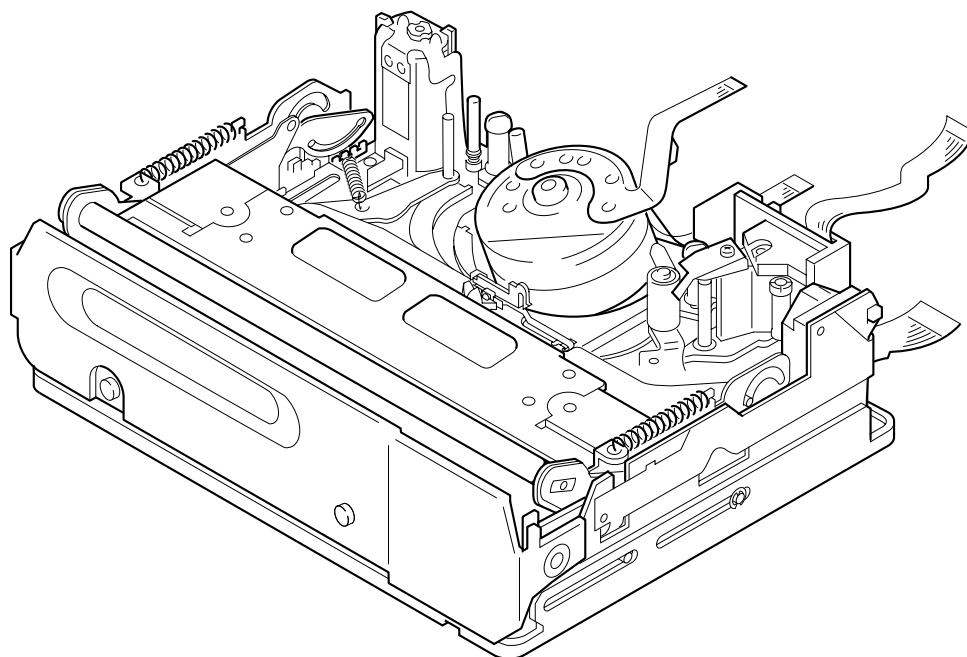
DV MECHANICAL ADJUSTMENT MANUAL VI

Ver 1.0 2000.3

J MECHANISM

Mini DV Digital
Video
Cassette

Please use this manual with the service manual of the respective models.



Digital MECHANISM DECK

SONY®

TABLE OF CONTENTS

<p>1. Preparations for Check, Adjustment and Replacement of Mechanism Block</p> <p>1-1. Cassette Compartment Assy, Damper Assy 3</p> <p>2. Periodic Inspection and Maintenance</p> <p>2-1. Rotary Drum Cleaning 4</p> <p>2-2. Tape Path System Cleaning 4 (Refer to Fig. 2-1.)</p> <p>2-3. Periodic Inspection List 5</p> <p>2-4. Service Jigs and Tools 6</p> <p>2-5. Mode Selector II Operating Procedure 8</p> <p>3. Check, Adjustment and Replacement of Mechanical Parts</p> <p>3-1. Drum 12</p> <p>3-2. L. Motor Holder Block Assy (Loading) and FP-228 Flexible Wiring Board (DEW Sensor) 13</p> <p>3-3. Retainer Plate Assy, LED Retainer 14</p> <p>3-4. Brake-T Block Assy, T-reel Table Assy, Gooseneck Gear Assy 15</p> <p>3-5. TG1 Assy, Tension Coil Spring (Tension Regulator) 16</p> <p>3-6. TG1 FWD Position Adjustment 17</p> <p>3-7. FWD Back-tension Adjustment 18</p> <p>3-8. Reel Torque Check 18</p> <p>3-9. TG3 Guide Zenith Adjustment 18</p> <p>3-10. TG6 Guide Zenith Adjustment 19</p> <p>3-11. LS Cam Plate Position Adjustment 19</p> <p>3-12. LS Chassis Block Assy, LS Guide Retainer 20</p> <p>3-13. LS Cam Plate, Tension Coil Spring (Brake-S), Brake-S, Torsion Coil Spring (Brake Arm), Cassette Position Set-S, Brake-S Driving Arm Assy 21</p> <p>3-14. TG7 Block Assy, Torsion Coil Spring (TG7 Return, Pinch Return), Pinch Arm Assy 22</p> <p>3-15. Layout Diagram of FP-102 Flexible Wiring Board 23</p> <p>3-16. TG1 Cam Slider, LS Arm, LS Roller, Mode Gear Assy, LS Guide Roller 24</p> <p>3-17. Guide Rail 25</p> <p>3-18. Gear Cover B, GL Driving Gear 26</p> <p>3-19. Drum Base Block Assy, Coaster-S Block Assy, Coaster-T Block Assy 27</p> <p>3-20. DC Motor (Capstan), Conversion Gear, Relay Gear 28</p> <p>3-21. Gear Cover C, Pinch Driving Arm Assy, Cam Gear B 29</p> <p>3-22. Gear Cover A, FP-100 Flexible Wiring Board 30</p> <p>3-23. Deceleration Gear, Mode Gear Assy, FP-100 Flexible Wiring Board, Cam Gear A 31</p>	<p>4. Tape Path Adjustment</p> <p>4-1. Adjustment Preparation 32</p> <p>4-2. Tracking Adjustment 33</p> <p>4-3. TG3 Guide Adjustment 33</p> <p>4-4. TG7 Guide Adjustment 34</p> <p>4-5. Check upon Completion of Adjustment 34</p> <p>5. Exploded View</p> <p>5-1. Cassette Compartment Block Assy, Drum Assy Block 36</p> <p>5-2. LS Chassis Block Assy 37</p> <p>5-3. Mechanism Chassis Block Assy 38</p> <p>6. Printed Wiring Boards and Schematic Diagrams 39</p> <p>7. Electrical Parts List 41</p>
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1. Preparations for Check, Adjustment and Replacement of Mechanism Block

- Refer to the “DISASSEMBLY” section of the SERVICE MANUAL of the respective models for details of removing cabinets and printed wiring boards.
- When making any adjustment to a mechanism or replacing mechanical parts, be sure to use the Mode Selector II and select the appropriate status of the mechanical deck such that the mechanical status is suitable for the desired work. Refer to section “2-5. Mode Selector II” for details on how to enter the mode shown in a rectangle mode in subsequent paragraphs of this manual.

1-1. Cassette Compartment Assy, Damper Assy

1. Removal Procedure

- 1) Set the EJ mode.
- 2) When the cassette compartment moves up in the direction of the arrow **(B)**, establish the ULE mode.
- 3) Release the two claws **(1)** and dowel of the damper assy and remove the damper assy.
- 4) Remove the shaft of the holder arm from the damper arm.
- 5) Remove the two screws (M1.4 × 2) **(2)**.
- 6) Lift up the LS frame in the direction of the arrow **(C)**.
- 7) Lift up the cassette compartment block assy in the direction of the arrow **(A)**. While pushing the holder arm in the direction of the inside arrow **(E)**, remove the cassette compartment block assy.

2. Attachment procedure

- 1) Set the ULE mode.
- 2) Attach the holder arm of the cassette compartment block assy to the cassette compartment slide shaft on both sides of the LS chassis block assy from inside.
- 3) Install the LS frame pivot into the groove **(D)** of the LS chassis. Drop down the LS frame in the direction opposite to **(C)**.
- 4) Hook the LS frame T-side bent portion on the LS chassis notch **(F)**.
- 5) Attach the LS frame with two screws (M1.4 × 2) **(2)**. Tightening torque: $0.054 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg \cdot cm).
- 6) While inserting the damper shaft of the cassette compartment block assy into slot of the damper arm, engage the two claws **(1)** with the notch of the LS chassis block assy, and fix the dowel to the corresponding hole of the LS chassis block assy respectively.

Note: Check that the two claws **(1)** and dowel do not come off.

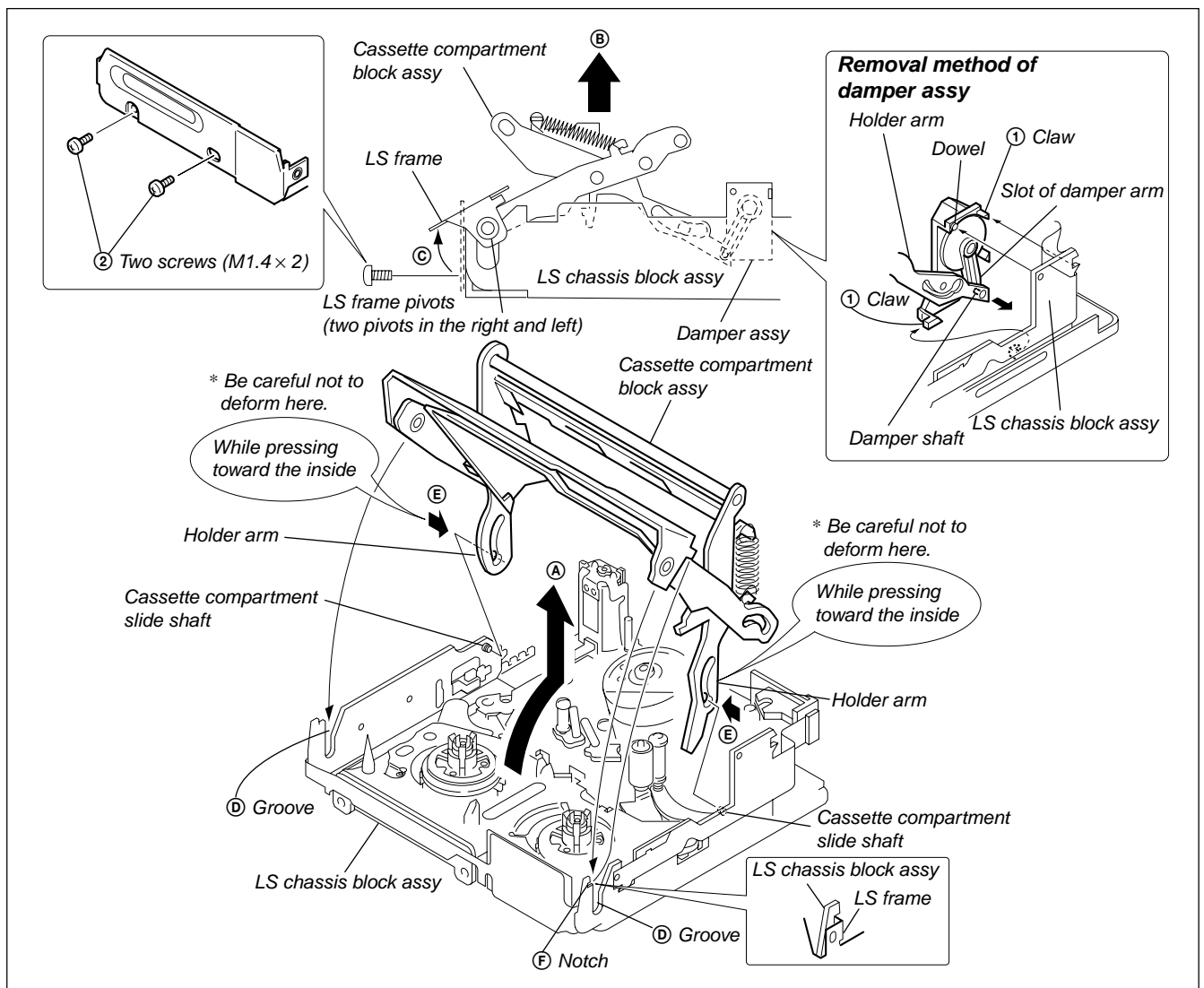


Fig. 1-1

2. Periodic Inspection and Maintenance

- Be sure to perform the following maintenance and inspection so that the machine delivers its full performance and functions, and to protect the machine and tape. Also, perform the following maintenance items after completing the repair work, regardless of the number of hours the machine has been operated by the user.

2-1. Rotary Drum Cleaning

- 1) Press a wiping cloth (Ref. No. J-2) moistened with cleaning fluid (Ref. No. J-1) lightly against the rotary drum. Rotate the upper drum with a super-fine applicator slowly in the counter-clockwise direction to clean the rotary drum.

Caution: Never rotate the rotary drum by turning on the main power of the motor or rotate it in the clockwise direction. Never move the cloth vertically against the head tip, as this will surely damage the video head; the video head must not be cleaned by any other different methods.

2-2. Tape Path System Cleaning (Refer to Fig. 2-1.)

- 1) Set the EJECT state. Clean the tape running path (TG-1, -2, -3, -4, -5, -6 and -7, pinch roller and capstan shaft) and lower drum with a super-fine applicator (Ref. J-3) moistened with cleaning fluid.

Note 1: Be careful not to allow oil or grease of the various link mechanisms to get on the super-fine applicator (Ref. J-3).

Note 2: Once the super-fine applicator has been moistened with alcohol, do not use it to clean other mechanical parts such as the tape guide. However, the pinch roller is cleaned with alcohol.

Note 3: When cleaning the capstan shaft, be careful not to move the oil seal. If the oil seal is moved, oil will leak.

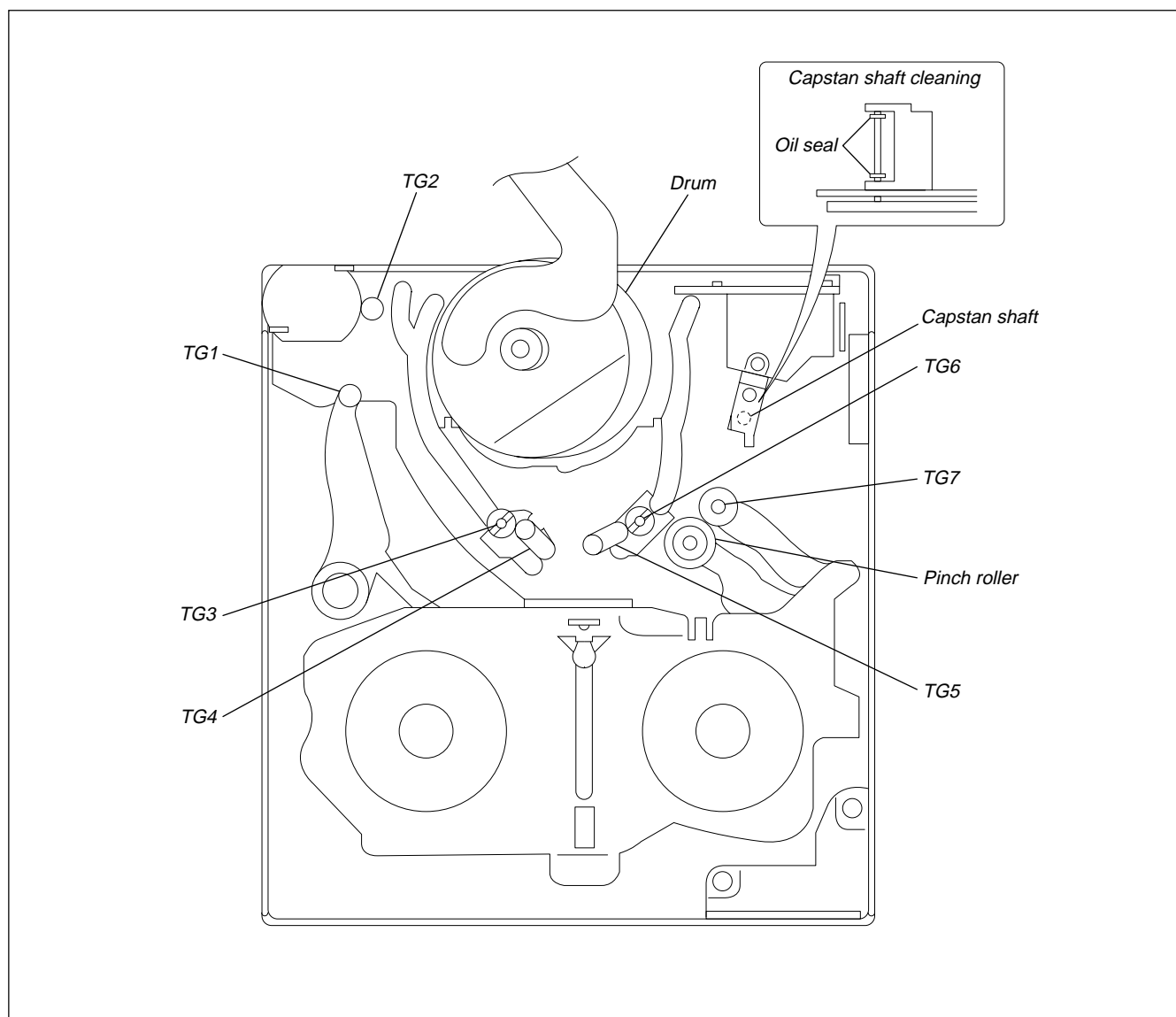


Fig. 2-1

2-3. Periodic Inspection List

Maintenance and inspection item		Operating hours (H)										Remarks
		500	1000	1500	2000	2500	3000	3500	4000	4500	5000	
	Tape running surface cleaning	○	○	○	○	○	○	○	○	○	○	Be careful not to attach oil
	Rotary drum cleaning and degaussing	○	○	○	○	○	○	○	○	○	○	Be careful not to attach oil
Drive mechanism	Capstan bearing	—	☆	—	☆	—	☆	—	☆	—	☆	
	Loading motor	—	☆	—	☆	—	☆	—	☆	—	☆	
Performance check	Abnormal sound	☆	☆	☆	☆	☆	☆	☆	☆	☆	☆	
	Back-tension measurement	—	☆	—	☆	—	☆	—	☆	—	☆	
	Brake system	—	☆	—	☆	—	☆	—	☆	—	☆	
	Brake system	—	☆	—	☆	—	☆	—	☆	—	☆	
	FWD/RVS torque measurement	—	☆	—	☆	—	☆	—	☆	—	☆	

○: Cleaning, ☆: Check

Note 1: When the machine is overhauled, replace the parts referring to the above list.

Note 2: Grease

- Be sure to use the specified grease only. (If grease of different viscosity is used, it can cause various troubles.)
- The grease used for bearings must not contain any dust or other matter, otherwise excessive abrasion and seizure of the bearing could occur.
- A drop of grease means the amount of grease as shown in the illustration, which is the amount that is attracted to the tip of a rod of 2 mm diameter.
- FLOIL grease (SG-941): Part No. 7-662-001-39

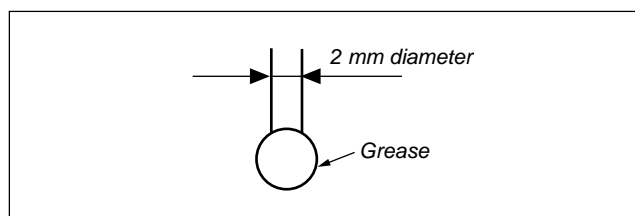


Fig. 2-2

2-4. Service Jigs and Tools

Ref. No.	Name	Part code	Jig inscription	Used for
J-1	Cleaning fluid	Y-2031-001-0		
J-2	Wiping cloth	7-741-900-53		
J-3	Super-fine applicator (made by Nippon Applicator (P752D))	—		
J-4	Mirror (small oval type)	J-6080-840-A	GD-2038	Tape path
J-5	Tracking tape (XH2-1) (NTSC, PAL)	8-967-997-01		Tape path
J-6	Mini DV torque cassette	J-6082-360-A		
J-7	TG1 adjustment jig (FWD position adjustment)	J-6082-492-A		
J-8	TG1 FWD adjustment screwdriver	J-6082-364-A		For TG1 FWD position adjustment
J-9	Dummy drum (for TG36) (J mechanism)	J-6082-490-A		
J-10	TG36 gauge	J-6082-491-A		
J-11	Torque screwdriver	J-9049-330-A		
J-12	Tape path screwdriver	J-6082-026-A		For tape path adjustment
J-13	Adjustment remote commander (RM-95 upgraded) * Note 1	J-6082-053-B		
J-14	Mode Selector II	J-6082-282-B		General adjustment (ROM version 1.7)
J-15	Mode Selector II conversion board (J)	J-6082-493-A		
J-16	Mode Selector II ROM (supporting J mechanism) * Note 2	J-6082-314-E		ROM for Mode Selector II

Other required equipment: Oscilloscope

Note 1: If the microprocessor in the adjustment remote commander is not the new one (UPD7503G-C56-12), the pages cannot be switched. In this case, replace it with the new microprocessor (8-759-148-35).

Note 2: This is the ROM used for upgrading the version of Mode Selector II to enable it to be used for the J mechanism.

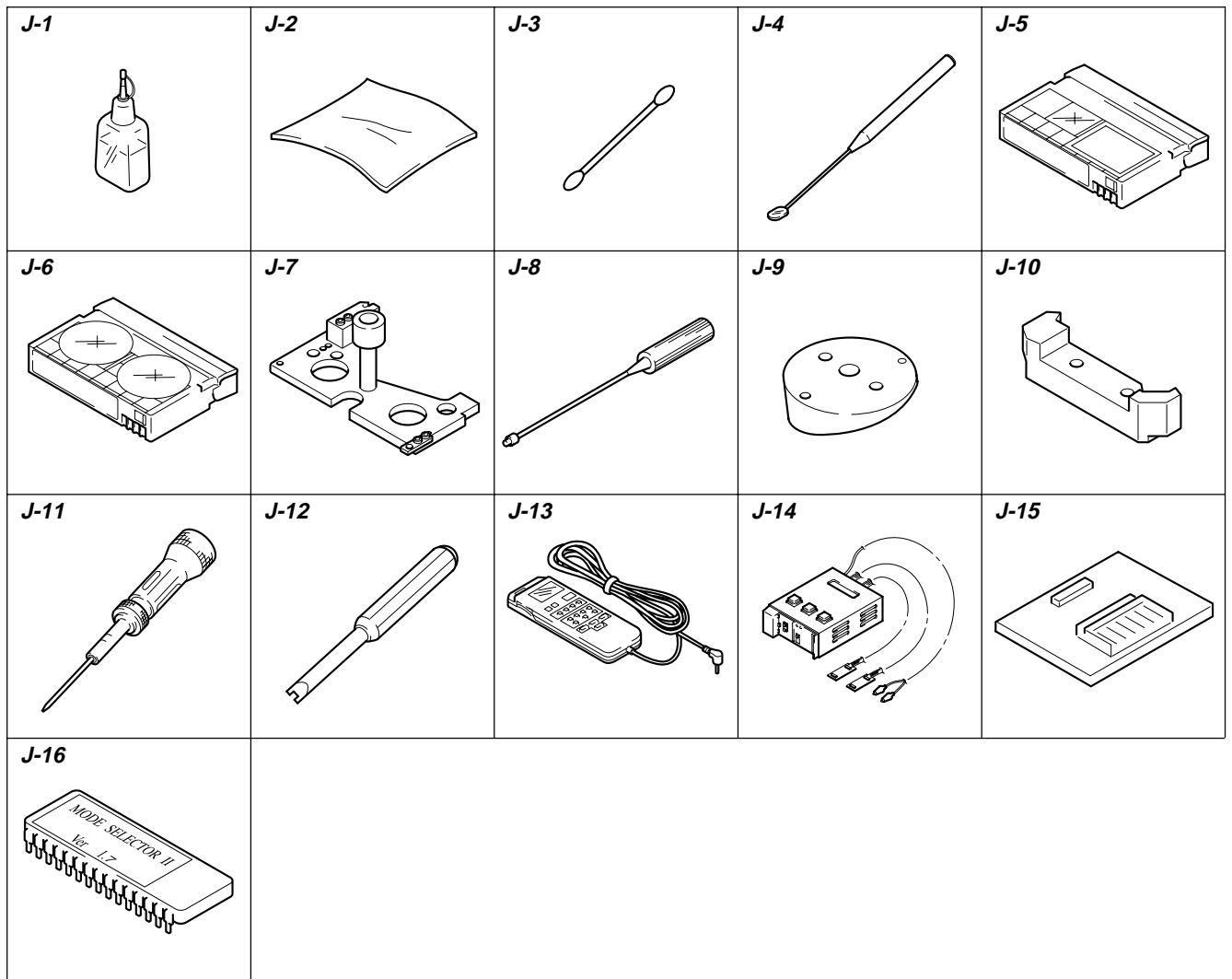


Fig. 2-3

2-5. Mode Selector II Operating Procedure

2-5-1. Introduction

The Mode Selector II is a mechanism drive tool that assists maintenance work of the various mechanism decks. It has the following functions.

1. Manual Test

In this mode, the motor of the mechanism deck is powered only during the period while the switch is turned on manually. Using the Manual Test, the operator can freely control the motor of the mechanism deck.

2. Step Test

In this mode, the motor of the mechanism deck is kept turned on until the mechanical status is changed from the present mechanical status that is obtained from the sensor information. The Step Test is used to confirm a series of movements of the mechanism deck.

3. Auto Test

The Mode Selector II stores the status transition table in its memory as data indicating the respective modes of the mechanism deck. The status transition table can be used to confirm whether a mechanism deck is operating normally or has abnormality from a series of movements of a mechanism deck. If an abnormal status transition is detected during operation, the "NG" indication appears and the mechanism stops moving.

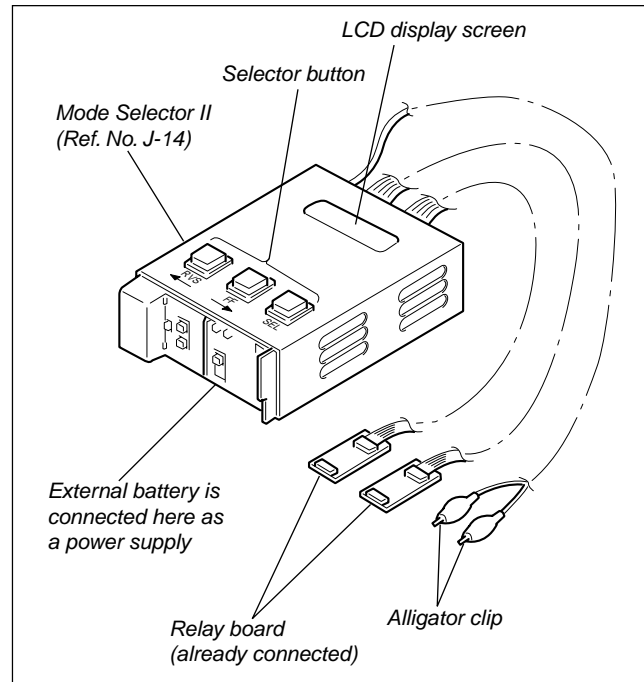


Fig. 2-4

Mode Selector II (J-6082-282-B) connection diagram

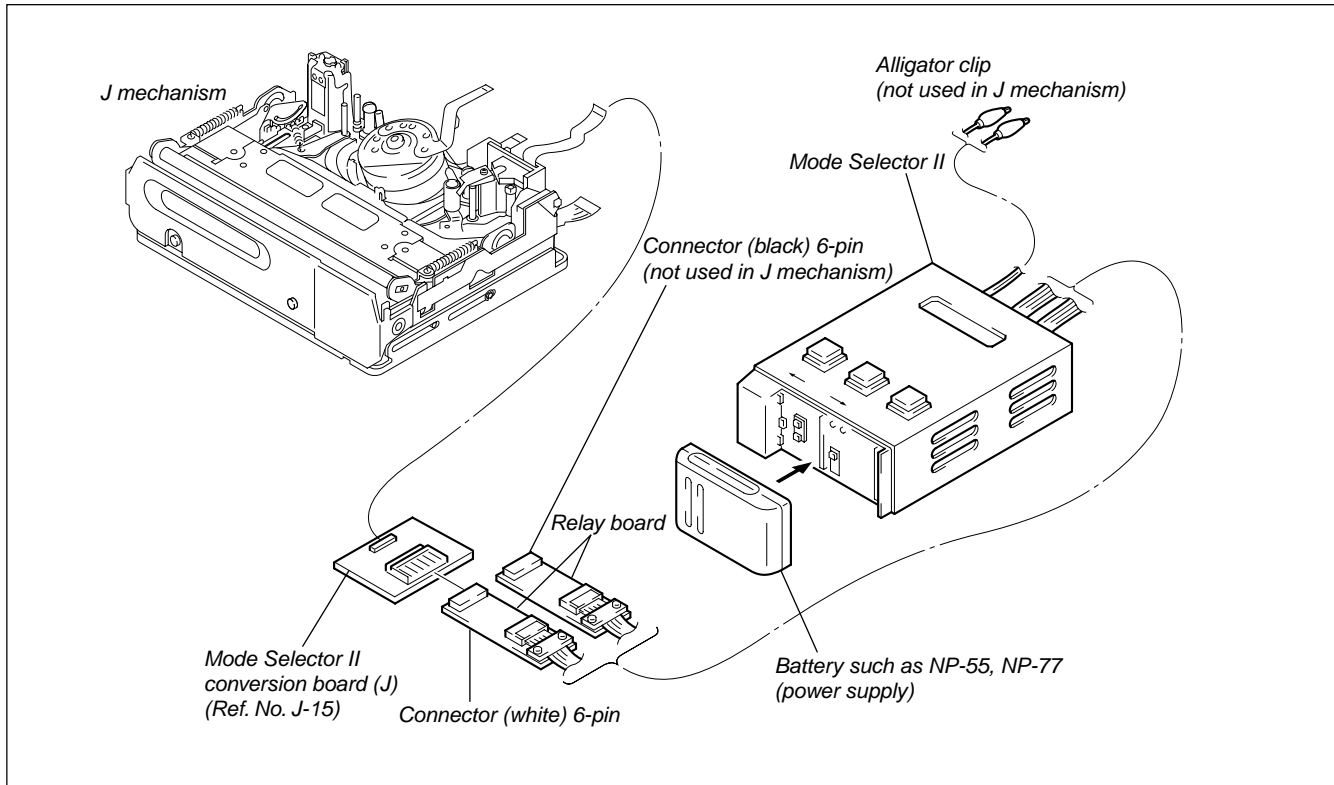
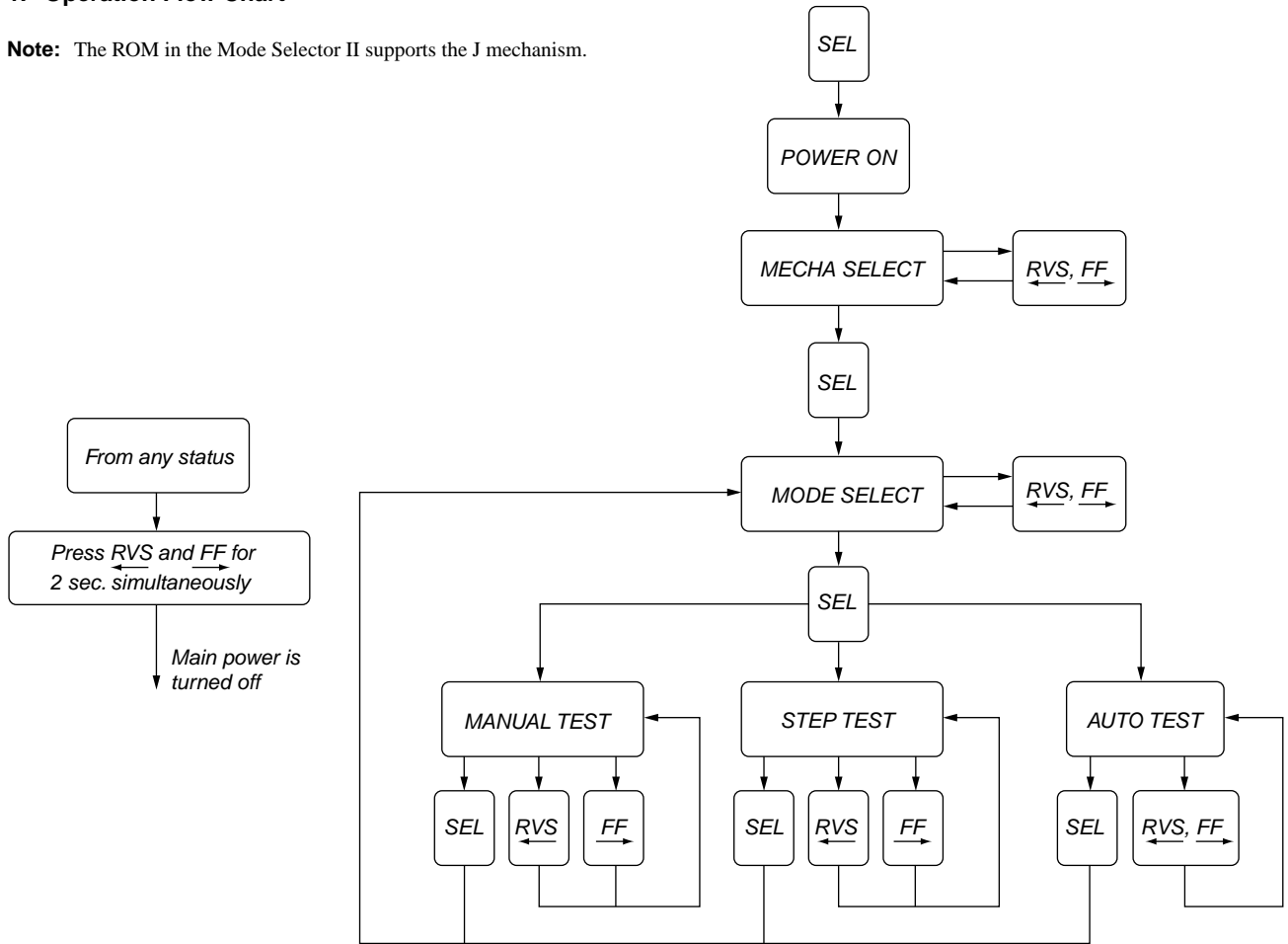


Fig. 2-5

2-5-2. Operation

1. Operation Flow Chart

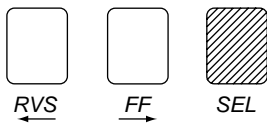
Note: The ROM in the Mode Selector II supports the J mechanism.



2. Mode Selector II Power On

Turn on the main power of the Mode Selector II as follows.

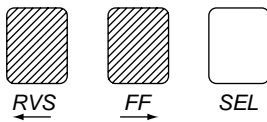
Press the SEL button.



3. Mode Selector II Power Off

Turn off the main power of the Mode Selector II as follows.

Press the RVS and FF buttons at the same time for 2 seconds or longer while the power is on.



4. Mecha Select

When the main power is turned on, the MECHA SELECT display appears on the LCD screen. Select the desired mechanism name using the **RVS** and **FF** buttons. Selection is complete when the **SEL** button is pressed. (Fig. A shows the J mechanism.)

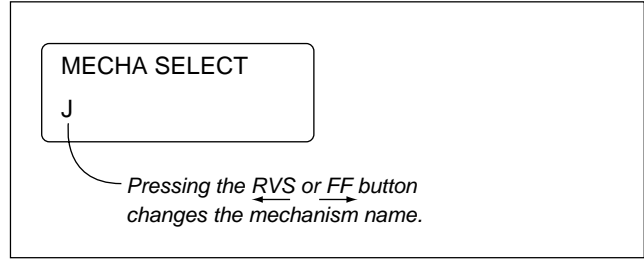


Fig. a

5. Test Type Select

Using the **RVS** and **FF** buttons, select a desired test type from the three types of "MANUAL", "STEP" and "AUTO". Selection is complete when the **SEL** button is pressed.

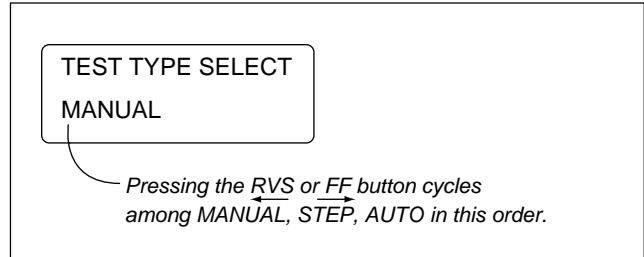


Fig. b

6. Manual Test

In this test, the motor of the mechanism deck is turned on only during the period while the **RVS** or **FF** button is pressed manually.

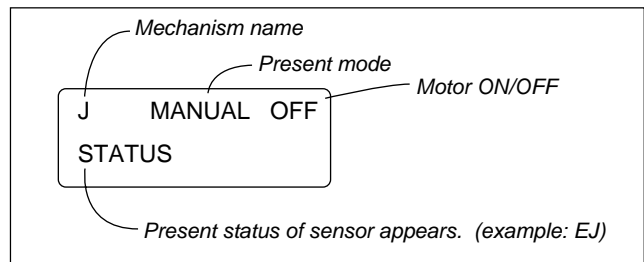


Fig. c

7. Step Test

In this test, the direction of motor movement is determined by the **RVS** and **FF** buttons. The motor of the mechanism deck is kept turned on until the mechanical status is changed from the present mechanical status that is obtained from the sensor information.

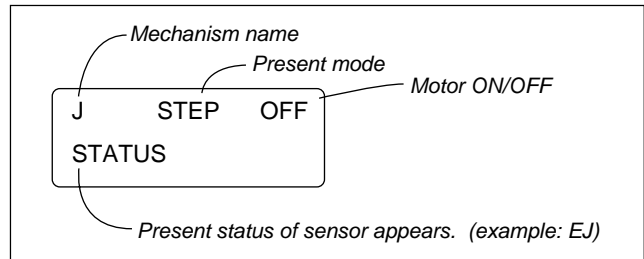


Fig. d

8. Auto Test

In this test, the mechanism deck is tested as to whether it performs a series of movements correctly in accordance with the operation sequence that is memorized earlier for each type of deck, by checking the output signals from sensors with the stored memory. Turning on the **RVS** or **FF** button performs the same operation.

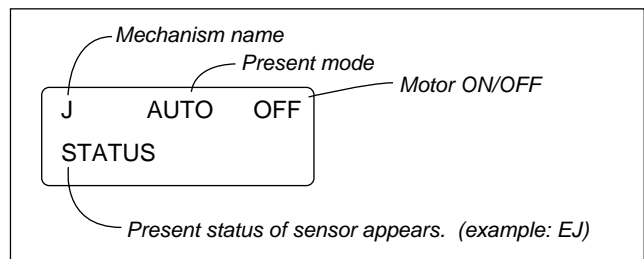


Fig. e

2-5-3. Mechanism Status (Position) Transition Table Using Mode Selector II

After selecting a mechanism deck, select either the MANUAL or STEP test (not AUTO) using the Mode Selector II. The desired mechanism status (position) can be specified by pressing the RVS or FF button. (The selected status appears on STATUS.)
 EJ ↔ ULE ↔ SR ↔ GL ↔ STOP ↔ RP

MD name			J Mechanism	
Code				
A	B	C		
0	0	1	1	EJ
1	0	1	2	ULE
1	0	0	3	SR
1	1	0	4	GL
0	1	0	5	STOP
0	1	1	6	RP

2-5-4. Battery Alarm Indication

When the level of the battery used to supply power to this system decreases, this display appears asynchronously. When this happens, all operations are disabled and the battery must be replaced.

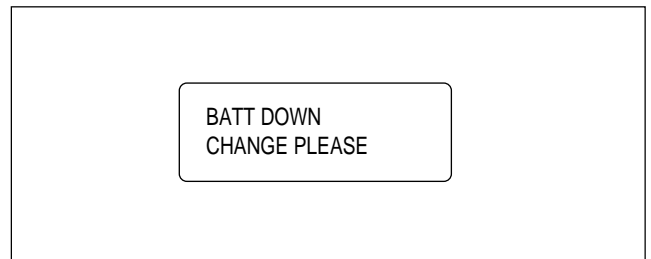


Fig. f

3. Check, Adjustment and Replacement of Mechanical Parts

3-1. Drum

1. Removal procedure

- 1) Loosen the three screws (M1.4 × 2) ① fixing the drum and remove the drum.

2. Attachment procedure

- 1) Align the two reference holes A and B on the rear of the drum with the position setting reference pins A and B of the drum base assy.
- 2) Install the drum with the three screws (M1.4 × 2) ① and tighten the screws in order from ①, then ② and finally ③.
Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg \cdot cm)
- 3) Clean the drum referring to section 2-1.
- 4) Perform the tape path adjustment. (Refer to section 4, "Tape Path Adjustment".)

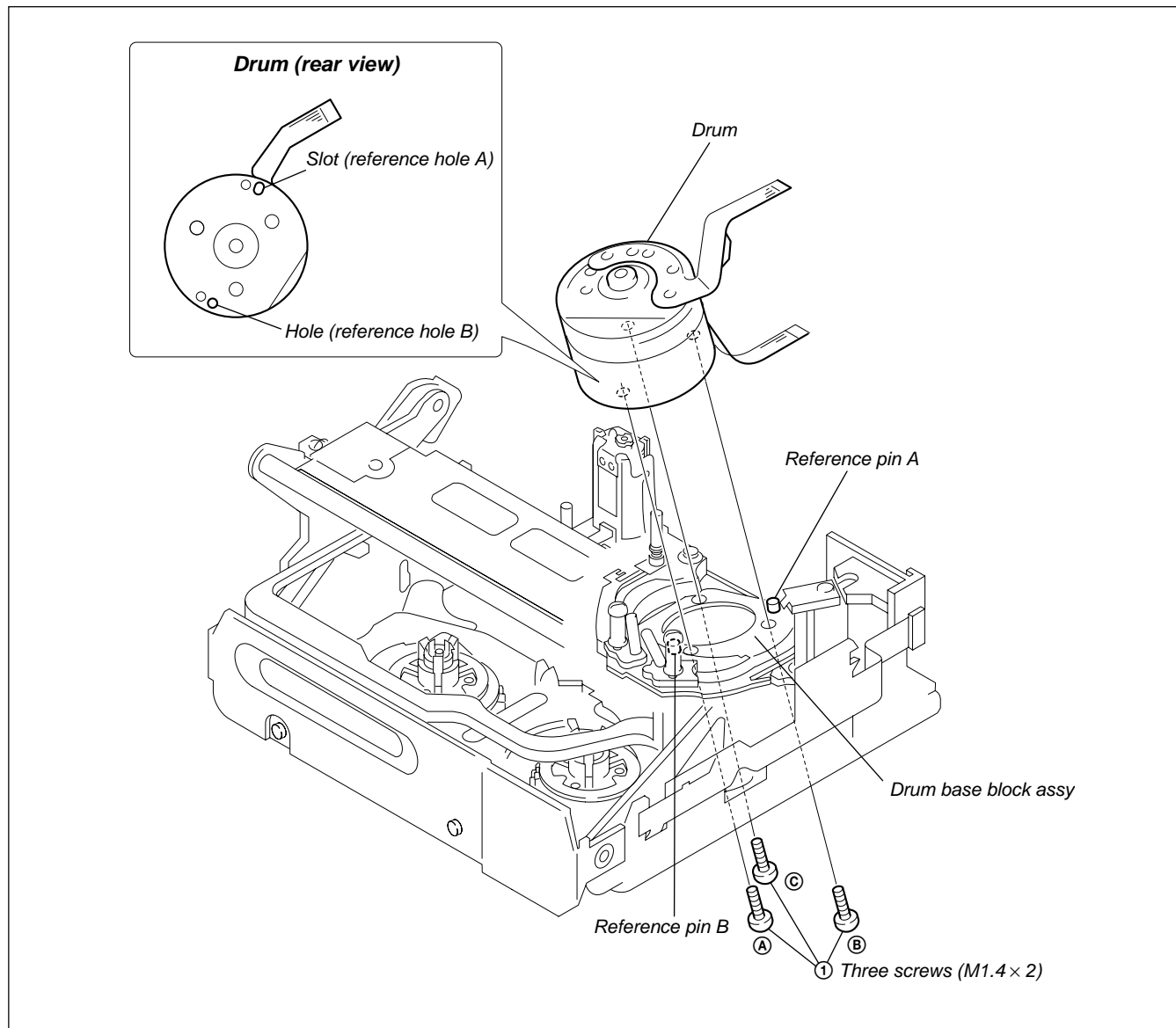


Fig.3-1

3-2. L. Motor Holder Block Assy (Loading) and FP-228 Flexible Wiring Board (DEW Sensor)

1. Removal procedure

- 1) Remove soldering ② from the L motor holder block assy (loading). Remove the FP-100 flexible wiring board.
- 2) Remove soldering ③ from the flexible wiring board FP-100. Remove the FP-228 flexible wiring board (DEW sensor).

Note: Since the FP-228 flexible wiring board (DEW sensor) is attached to the motor shield by adhesive agent, be careful not to break the flexible board when removing soldering.

- 3) Remove the screw (M1.4 × 2.5) ①.
- 4) Remove the L motor holder block assy.
- 5) Unlock the claw ⑤ and remove the worm shaft.
- 6) Remove the motor shield.
- 7) Unlock the two claws ④ of the motor holder. Remove the L motor block assy (loading) in the direction of ⑥.

Note: Be careful not to touch the DEW sensor.

2. Attachment procedure

- 1) Check the direction of the polarity marking ③ of the L motor block assy (loading). Attach the L motor block assy (loading) to the motor holder so that the L motor block assy (loading) faces the worm shaft side.
- 2) While aligning the slot and dowel with the motor shield, attach the motor holder to the motor holder.
- 3) Apply grease (1/2 drop) between the worm shaft gear and gear tooth.
- 4) While the worm gear is engaged with the worm shaft gear, insert the worm shaft tip into the groove ⑦ and fix the worm shaft under the claw ⑤.
- 5) While aligning the chassis's two square holes with the two round holes, attach the motor holder block assy with the screw (M1.4 × 2.5) ①.
Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg•cm)
- 6) Connect FP-228 (DEW sensor) to the FP-100 flexible wiring board by soldering. Attach the DEW sensor to the motor shield.
- 7) Connect the FP-100 flexible wiring board to the motor holder block assy (loading) by soldering.

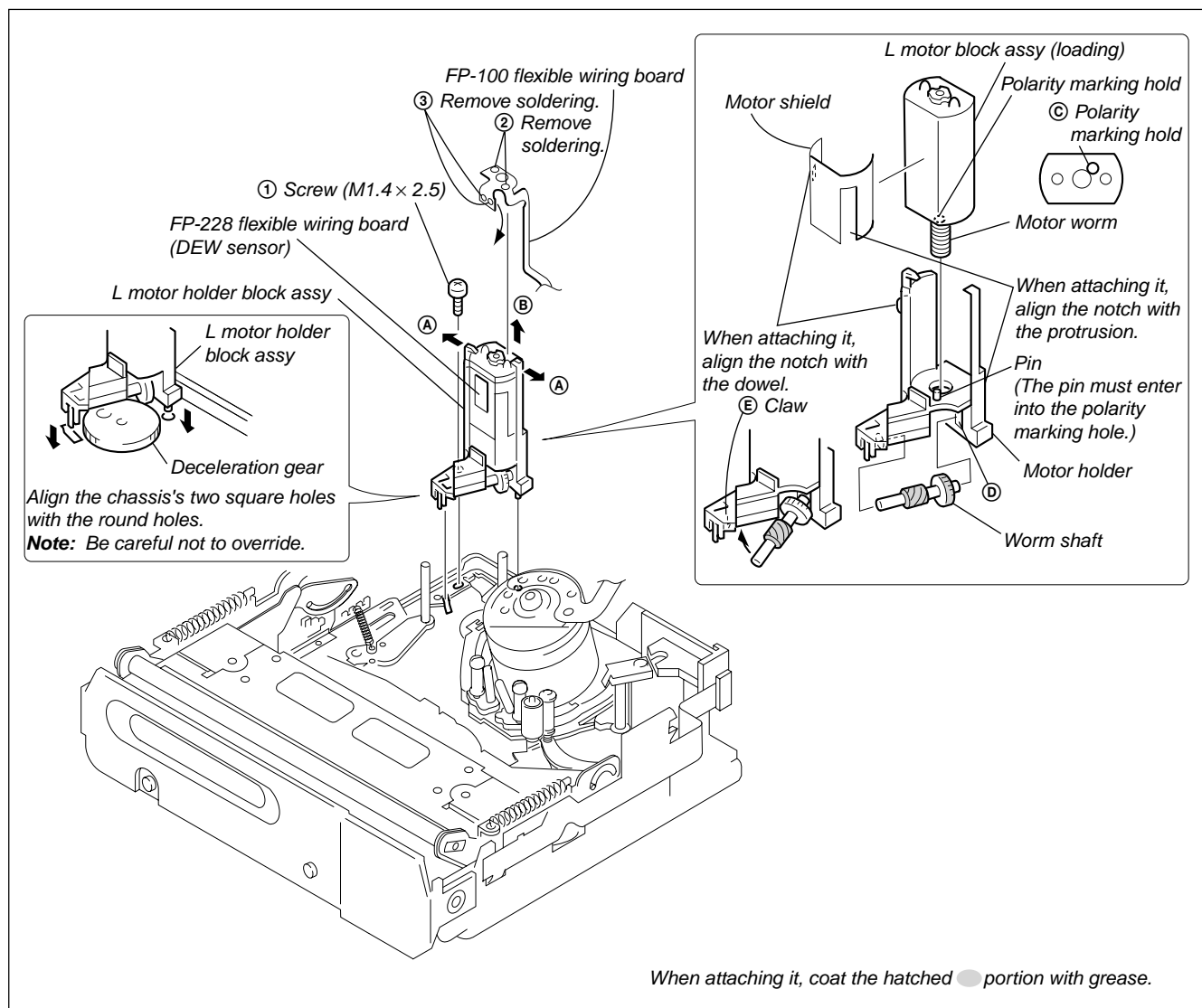


Fig. 3-2

3-3. Retainer Plate Assy, LED Retainer

1. Removal procedure

- 1) While pressing the claw of the LED retainer in the direction of the arrow **(A)**, remove the LED retainer.
- 2) Remove the LED portion **(2)** of the FP-102 flexible wiring board.
- 3) Remove the two screws (M1.4 × 1.4) **(1)**.
- 4) In order to remove the retainer plate assy, because it is hooked with shaft A, shaft B and shaft C, remove the retainer plate assy while moving it in the direction of the arrow **(B)**.

2. Attachment procedure

- 1) Hook shaft A, shaft B and shaft C on notch A, notch B and notch C of the retainer plate assy in this order.
- 2) Attach the retainer plate assy with two screws (M1.4 × 1.4) **(1)**. Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg \cdot cm)
- 3) Route the FP-102 flexible wiring board as shown and install the LED into the prism as shown.
- 4) Hook the LED retainer on **(D)**, attach it to **(E)** and fix them.

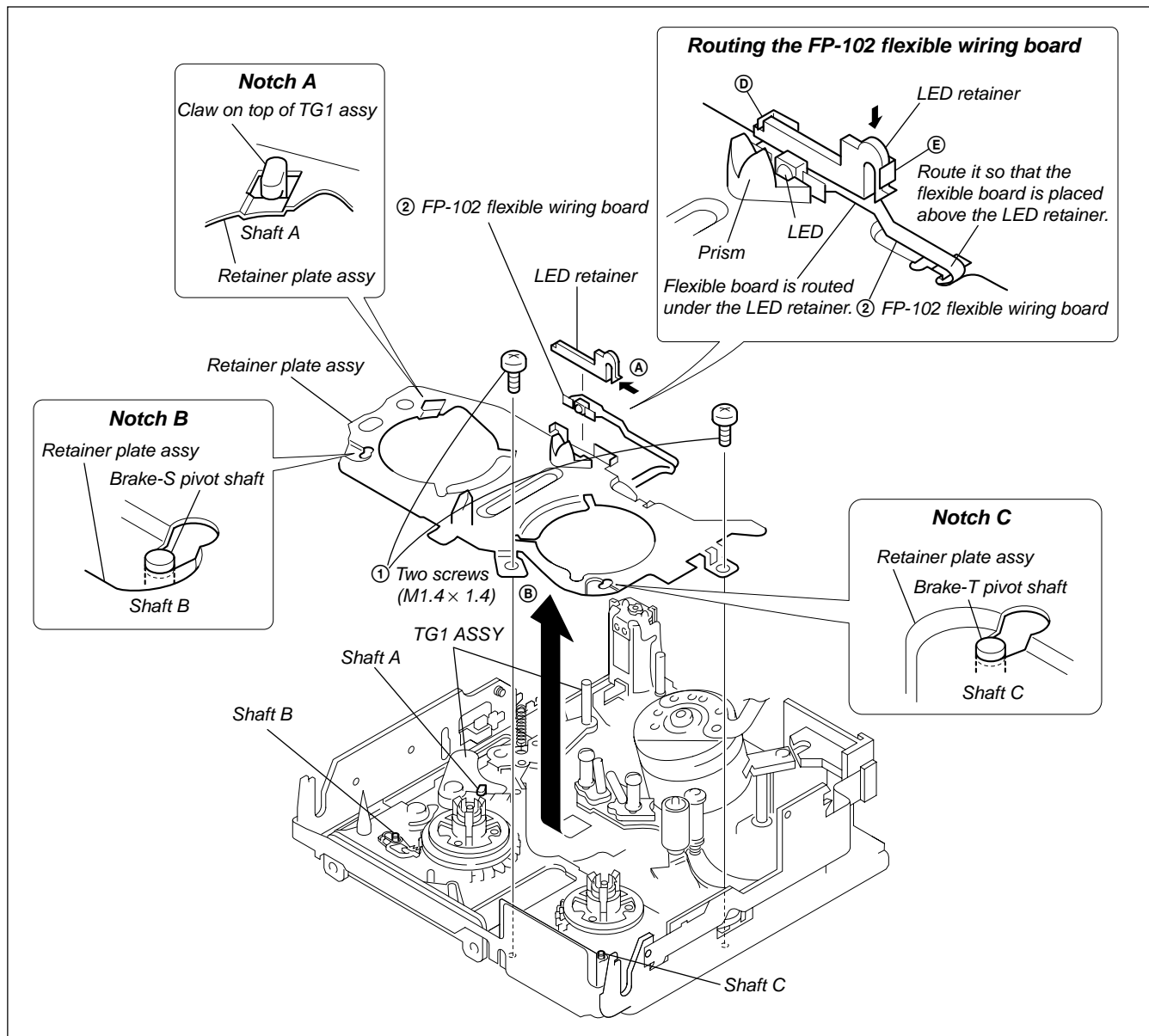


Fig. 3-3

3-4. Brake-T Block Assy, T-reel Table Assy, Gooseneck Gear Assy

1. Removal procedure

- 1) Remove the brake-T block assy from the brake-T pivot shaft.
- 2) While pressing the reel claw retainer (A) of the T-reel table assy down in the direction of (B), remove the reel claw (C).
- 3) Remove the gooseneck assy from the relay gear shaft.

Note: Be careful not to break the reel claw.

2. Attachment procedure

- 1) Insert the gooseneck gear assy into the center hole of the relay gear shaft. Bend the gooseneck gear assy to the S-reel table assy side.
- 2) Attach the brake-T block assy to the brake-T pivot shaft (D).
- 3) Move the brake-T counter-clockwise so that T-brake is freed. While pressing down the reel claw of the T-reel assy, fix the T-reel to the reel shaft-T by rotating the reel.
- 4) Check that the brake spring-T works correctly by rotating the T-reel table assy 30 degrees in the clockwise and counter-clockwise directions.

Note: The retainer on top of the brake spring-T must be hooked on the brake-T pivot shaft (D) and moved down to the groove.

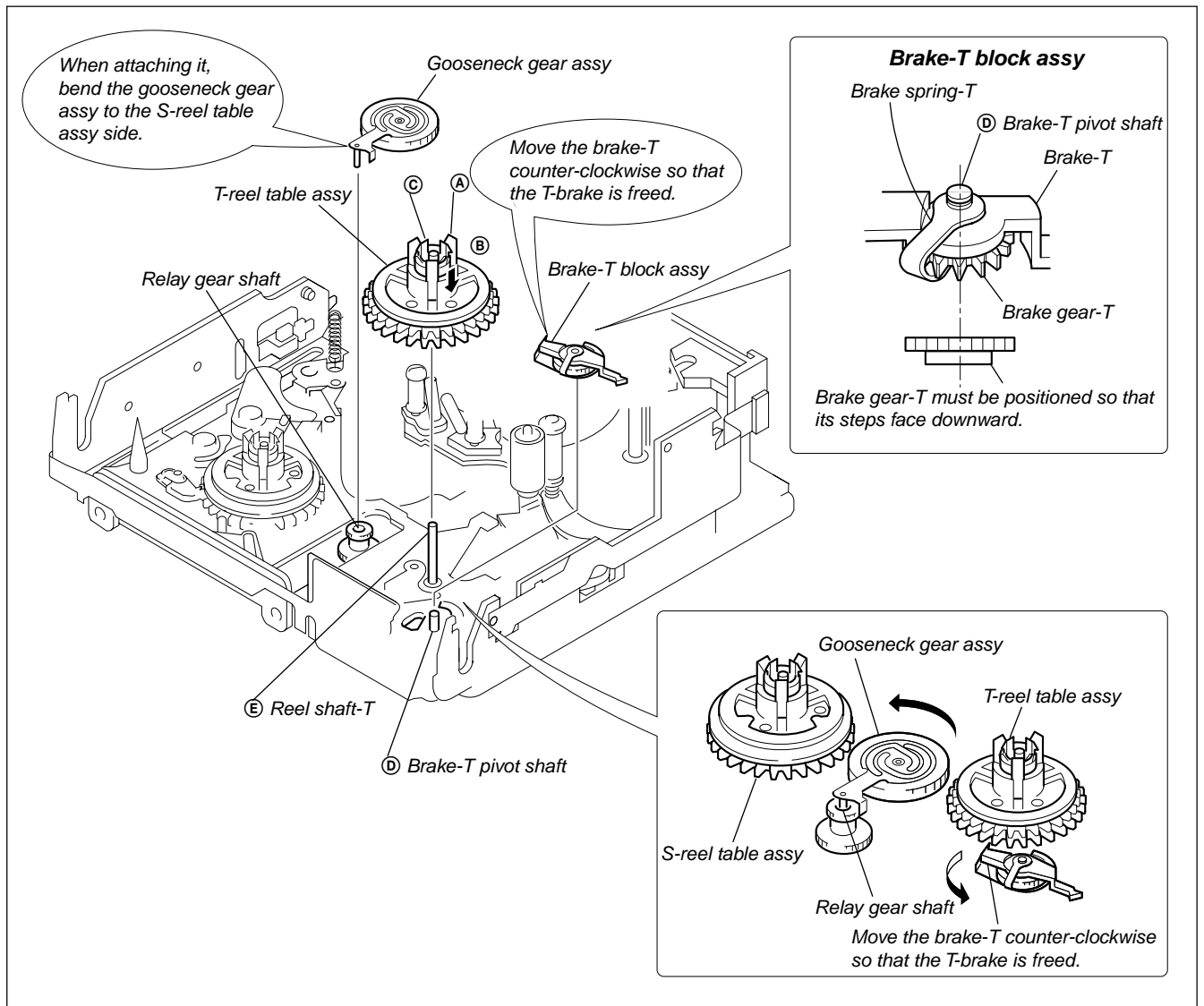


Fig. 3-4

3-5. TG1 Assy, Tension Coil Spring (Tension Regulator)

1. Removal procedure

- 1) Remove the screw (M1.4 × 2.5) ①.
- 2) Remove the tension coil spring.
- 3) Remove the TG1 assy tension regulator band.
- 4) Remove the (FWD) adjustment plate from the S-reel table. Place it between the T-reel table assy and pinch arm assy.
- 5) While pressing down the reel claw retainer ④ of the S-reel table assy in the direction of ⑤, remove the reel claw ③.

Note 1: Be careful not to deform the tension regulator band.

Note 2: Be careful that grease does not attach to the tension regulator band.

2. Attachment procedure

- 1) Coat the root and its surroundings on TG1 pivot shaft ① with grease (1/4 drop). (Strictly observe the coating position and specified amount of grease.)
- 2) Attach the S-reel table assy to the reel shaft-S.
- 3) Attach the TG1 assy to the TG1 pivot shaft ②. Note that the TG1 drive shaft has entered the groove of the LS block assy at this moment.
- 4) Wrap the tension regulator band around the S-reel table assy. Fix it with the screw (M1.4 × 2.5) ③ while ensuring that direction of the (FWD) adjustment plate is correct as shown.
- 5) Hook the tension coil spring ④ on the TG1 assy and on the LS chassis block assy.
- 6) Clean the tip of the TG1 pivot shaft with a super-fine applicator (Ref. J-3) moistened with cleaning fluid.
- 7) Perform the (FWD) position adjustment referring to section 3-6.
- 8) Perform the FWD back-tension adjustment referring to section 3-7.
- 9) Perform the reel torque check referring to section 3-8.

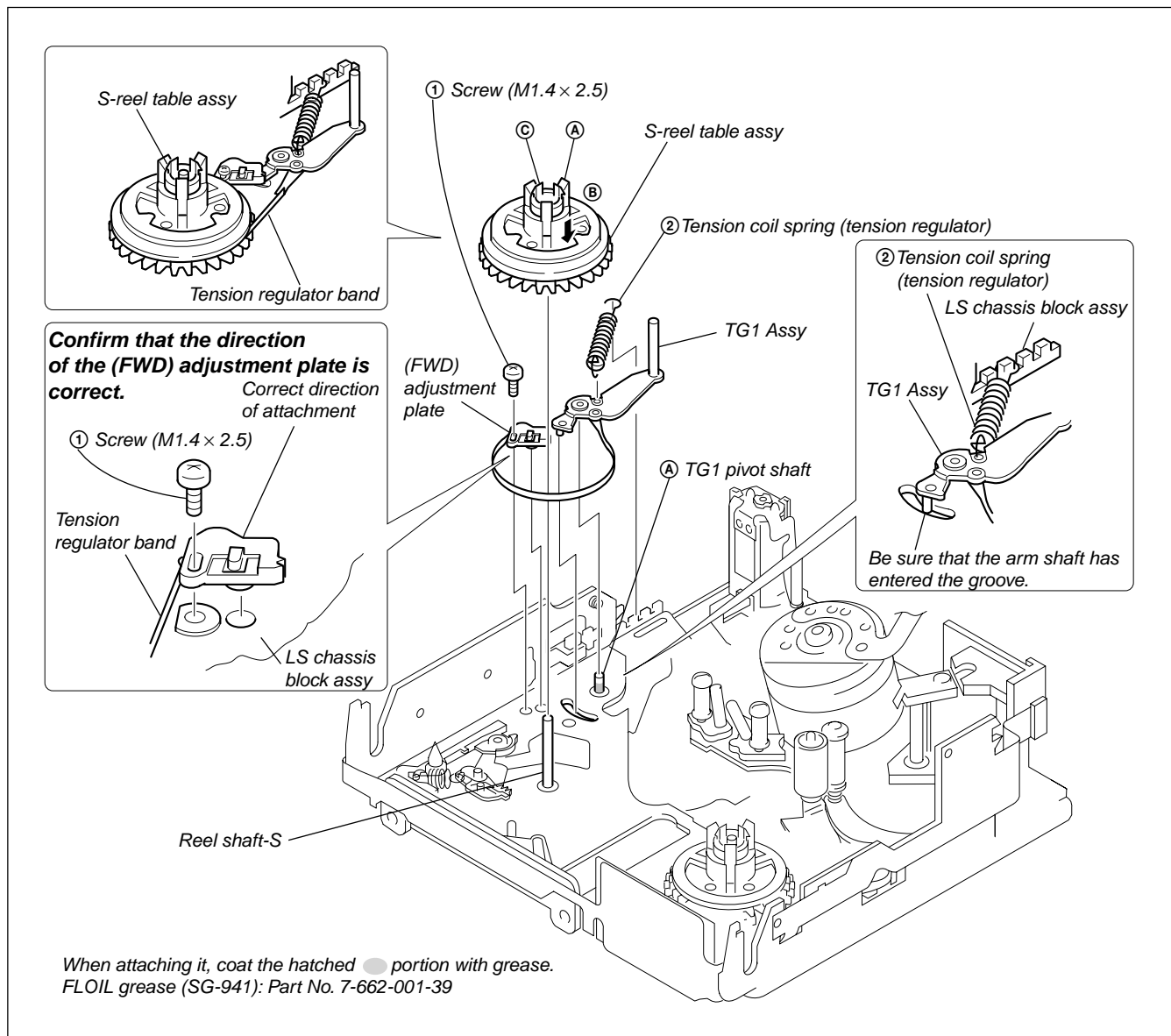


Fig. 3-5

3-6. TG1 FWD Position Adjustment

When the TG1 assy or S-reel table is replaced, or when a part constituting these parts is replaced, perform the following adjustment.

- TG1 FWD Position Adjustment
- FWD Back-tension Adjustment (Refer to section 3-7.)
- Reel table (RVS) torque check (Refer to section 3-8.)

1. Adjustment procedure

- 1) Establish the **[RP]** mode.
- 2) Install the TG1 adjustment jig (Ref. No. J-7) as specified by the S/T position setting.
Note: Be careful not to damage the flexible wiring board.
- 3) Attach the torque screwdriver (Ref. No. J-11) and the TG1 FWD adjustment screwdriver (Ref. No. J-8) to the adjustment screw block.
- 4) While rotating the adjustment screwdriver a little, press it down lightly so that it is aligned with the gear of the (FWD) adjustment plate.
- 5) Loosen the adjustment screw that is tentatively tightened by the torque screwdriver. Perform adjustment so that TG1 comes to the center of the gauge's groove when viewed from directly above the TG1 adjustment jig (Ref. No. J-7). Then tighten the adjustment screw.
Tightening torque: 0.0588 N•m (0.6 kg•cm).
- 6) Check again that the TG1 position remains in the correct position, then remove the jig.

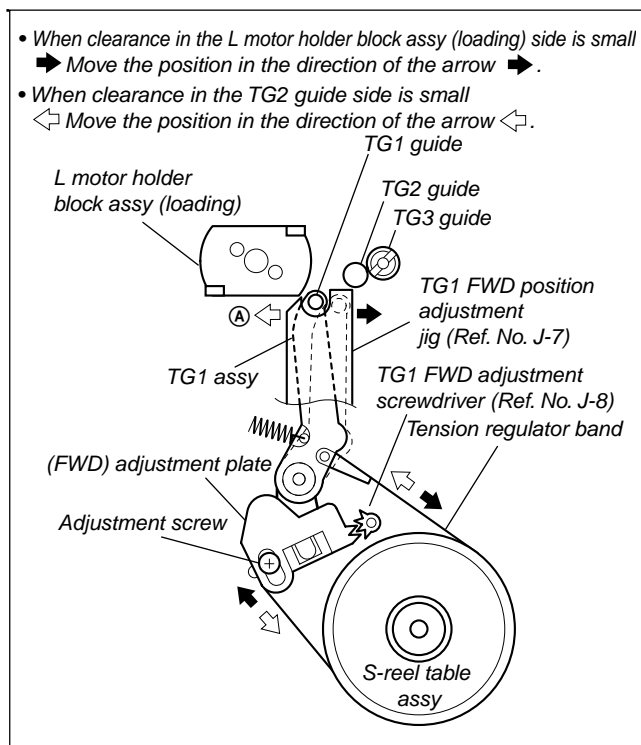


Fig. 3-6

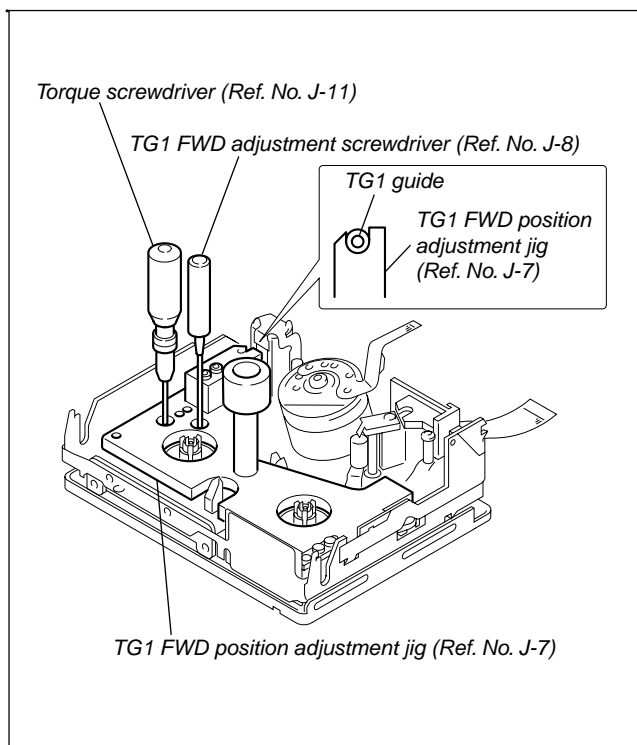


Fig. 3-7

3-7. FWD Back-tension Adjustment

1. Adjustment procedure

- 1) Install the Mini DV torque cassette (Ref. No. J-6).
 - 2) Set the **[RP]** mode. Confirm that the torque reading of the supply side is in the range of 0.45 to 0.55 mN•m (4.5 to 5.6 g•cm) including fluctuation. If the torque reading is outside the specified range, perform the following adjustment.
- If the torque reading value is higher than the specification: (Reduce the spring tension as follows.)
Shift the hook position of the tension coil spring in the direction of **(A)**.
 - If the torque reading value is lower than the specification: (Increase the spring tension as follows.)
Shift the hook position of the tension coil spring in the direction of **(B)**.

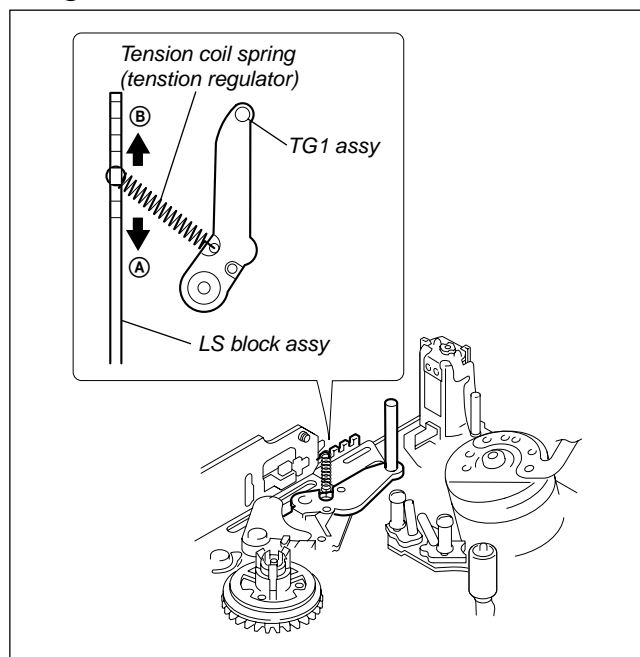


Fig. 3-8

3-8. Reel Torque Check

1. Check procedure

[FWD torque]

- 1) Install the Mini DV torque cassette (Ref. No. J-6).
- 2) Set the FWD mode. Confirm that the center of the T-reel table torque reading value is 0.54 to 1.32 (mN•m) (5.5 to 13.5 g•cm) and the fluctuation value is 0.39 to 0.40 (mN•m) (3.9 to 4.0 g•cm).

[RVS torque]

- 1) Install the Mini DV torque cassette (Ref. No. J-6).
- 2) Set the RVS mode (by using the EDIT SEARCH (-) button of the machine). Confirm that the center of the S-reel table torque reading value is 1.37 to 2.11 (mN•m) (14 to 21.5 g•cm) and the fluctuation value is 0.39 to 0.40 (mN•m) (3.9 to 4.0 g•cm).

If either of the above specifications is not satisfied, check whether the tension regulator band has any abnormality. If it has no abnormality, replace the corresponding reel table.

3-9. TG3 Guide Zenith Adjustment

- 1) Remove the drum referring to section 3-1. Install the dummy drum (Ref. No. J-9).
- 2) Install the TG36 gauge (Ref. No. J-10) on top of the dummy drum. Rotate the slant adjustment zenith screw until the TG3 guide and TG36 gauge (Ref. No. J-10) become parallel.
- 3) Remove all the jigs. Attach the original drum back in its original position referring to section 3-1.
- 4) Clean the TG3 and TG4 guides referring to section 2-2.
- 5) Perform the tape path adjustment. (Refer to section 4, "Tape Path Adjustment".)

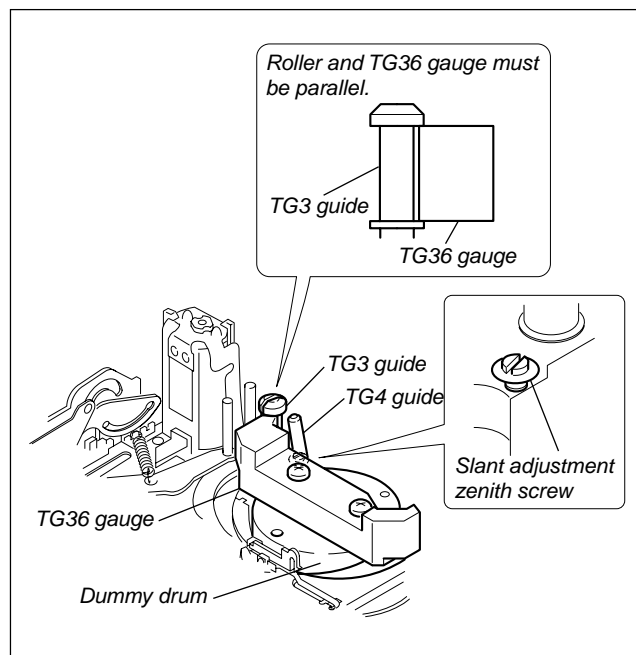


Fig. 3-9

3-10. TG6 Guide Zenith Adjustment

1. Adjustment procedure

- 1) Remove the drum referring to section 3-1. Install the dummy drum (Ref. No. J-9).
- 2) Install the TG36 gauge (Ref. No. J-10) on top of the dummy drum. Adjust the slant of the TG6 guide.
- 3) Rotate the slant adjustment zenith screw until the TG6 guide and TG36 gauge become parallel.
- 4) Remove all the jigs. Attach the original drum back in its original position referring to section 3-1.
- 5) Clean the TG5 and TG6 guides referring to section 2-2.
- 6) Perform tape path adjustment. (Refer to section 4, "Tape Path Adjustment".)

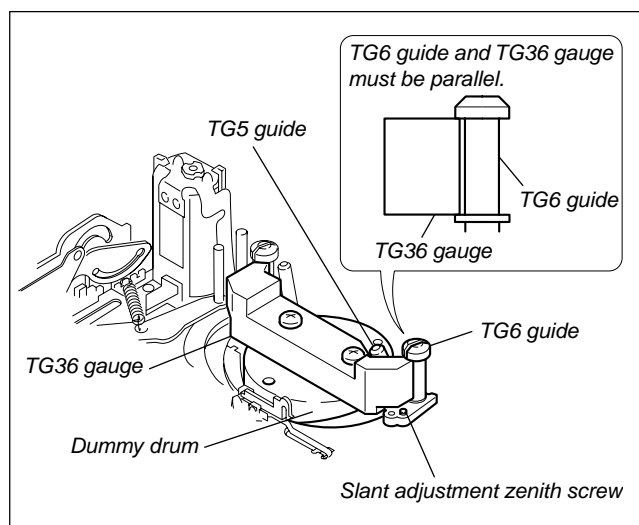


Fig. 3-10

3-11. LS Cam Plate Position Adjustment

1. Adjustment procedure

- 1) Loosen the LS cam fixing screw (M1.4 × 4) ① by 180 degrees.
- 2) Establish the **STOP** mode.
- 3) While pressing down the center of the LS chassis block assy with force of 100 to 200 gf (0.98 to 1.96 N), move the LS cam plate toward the S-reel side and tighten the LS cam plate fixing screw (M1.4 × 4) ① with force of 500 to 1000 gf (4.9 to 9.8 N).

Tightening torque: 0.059 to 0.01 N•m (0.6 kg•cm).

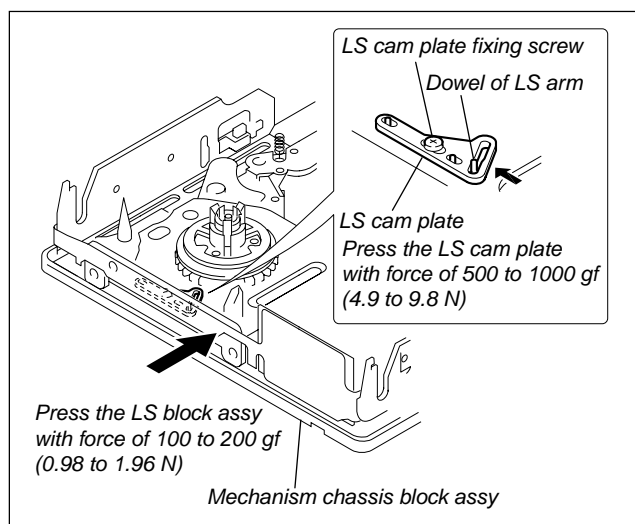


Fig. 3-11

3-12. LS Chassis Block Assy, LS Guide Retainer

1. Removal procedure

- 1) Remove the FP-100 flexible wiring board from the FPC connector on the FP-102 flexible wiring board.
- 2) Remove the screw (M1.4 × 2.5) ②. Remove the FPC holder from DC motor (capstan).
- 3) Remove the two screws (M1.4 × 2) ①.
- 4) Remove the LS guide retainer in the direction of the arrow ④ on the top.
- 5) Remove the E-type stop ring 1.5 ③.
- 6) Remove the LS chassis block assy in the direction of the arrow ⑥.

2. Attachment procedure

- 1) Confirm that the brake-T block assy has been moved in the counter-clockwise direction ③. While pressing the TG7 block in the direction of the arrow ④, insert the LS guide shafts T1 and T2 of the LS chassis block assy into the slots of the mechanism chassis with slanted angle.
- 2) While inserting the LS arm dowel into the LS cam plate groove, insert the LS guide shafts S1 and S2 into the slots of the LS chassis block assy as shown.
- 3) Insert the LS guide retainer from the top, align it with the LS guide shafts S1 and S2 and fix it with the screw (M1.4 × 2) ①. Tightening torque: 0.059 to 0.01 N•m (0.6 kg•cm).
- 4) Confirm that the LS guide retainer has play, is not lifted up, is not installed in opposite direction and has not been deformed.
- 5) Attach the E-type stop ring 1.5 ③ into the LS guide shaft T1.
- 6) Insert the FPC holder into DC motor (capstan) in the direction of the arrow ⑤ and fix it with the screw (M1.4 × 2.5) ②.
- 7) Connect the flexible wiring board coming from the FP-100 flexible wiring board into the FPC connector.

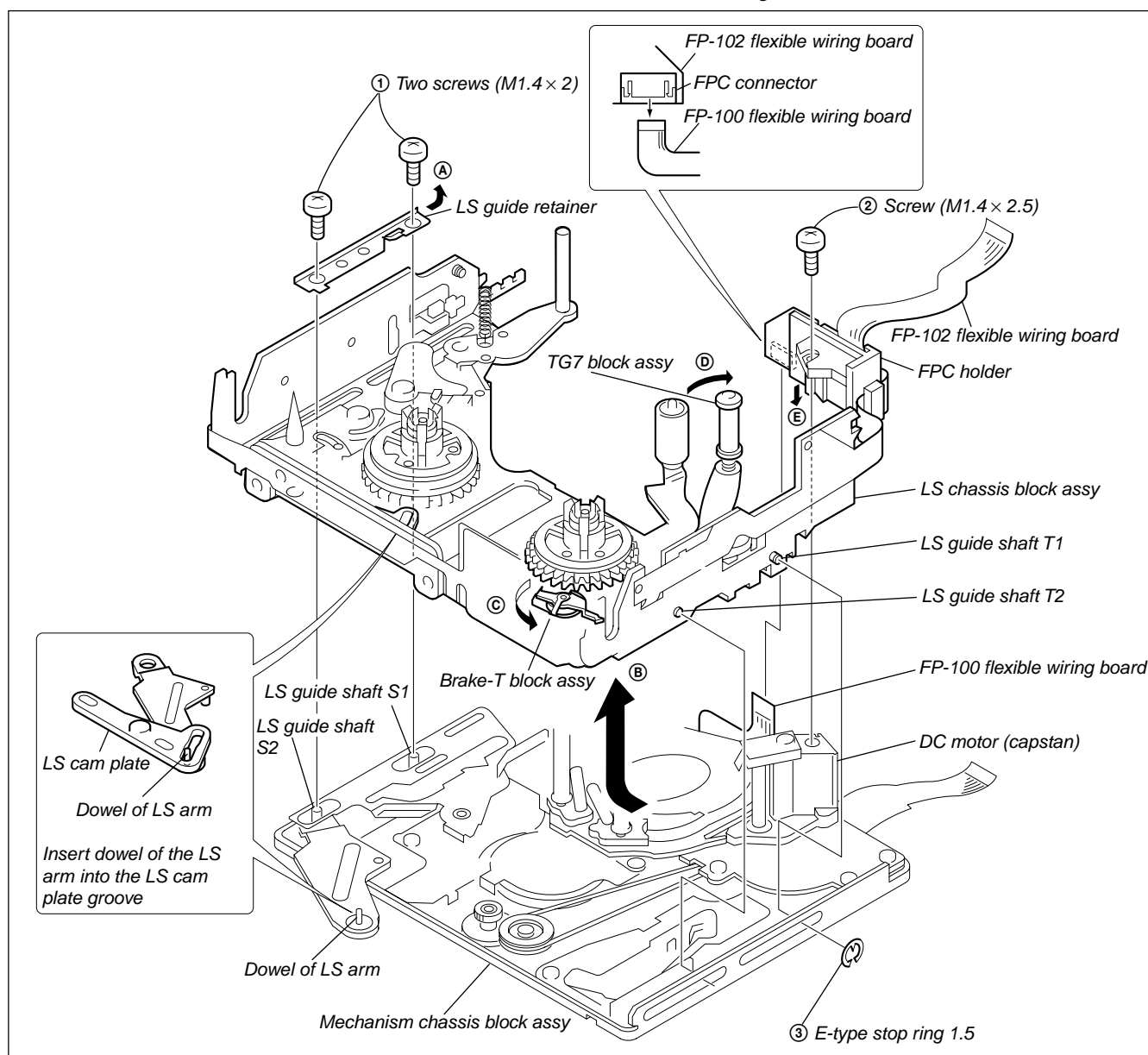


Fig. 3-12

3-13. LS Cam Plate, Tension Coil Spring (Brake-S), Brake-S, Torsion Coil Spring (Brake Arm), Cassette Position Set-S, Brake-S Driving Arm Assy

1. Removal procedure

- 1) Remove the screw (M1.4 × 1.4) ①.
- 2) Remove the LS cam plate.
- 3) Remove the tension coil spring (brake-S).
- 4) Remove the brake-S.
- 5) Remove the screw (M1.4 × 2) ②.
- 6) Remove the torsion coil spring (brake arm).
- 7) Remove the cassette position set-S from groove of the LS block assy in the direction of the arrow ③.
- 8) Remove the brake-S drive arm assy from groove of the LS block assy in the direction of the arrow ④.

2. Attachment procedure

- 1) Insert the brake-S drive arm assy under groove of the LS chassis block assy. Attach the brake-S drive arm assy to the brake-S arm shaft and to the brake-S pivot shaft.
- 2) Insert the cassette position set-S under the groove of the LS chassis block assy. Attach the cassette position set-S to the brake-S arm shaft.
- 3) Attach the torsion coil spring (brake arm).
- 4) Attach the screw (M1.4 × 2) ② to the brake-S arm shaft.
- 5) Attach the brake-S to the brake-S arm bearing and to the brake-S pivot shaft.
- 6) Hook the tension coil spring (brake-S) to the spring stay of the cassette position set-S and the spring stay of the brake-S.
- 7) Align the slot of the LS cam plate with the dowel. Move then in the direction toward the arrow ③ and attach the screw (M1.4 × 1.4) ①.
- 8) Perform the LS cam plate position adjustment referring to section 3-11.

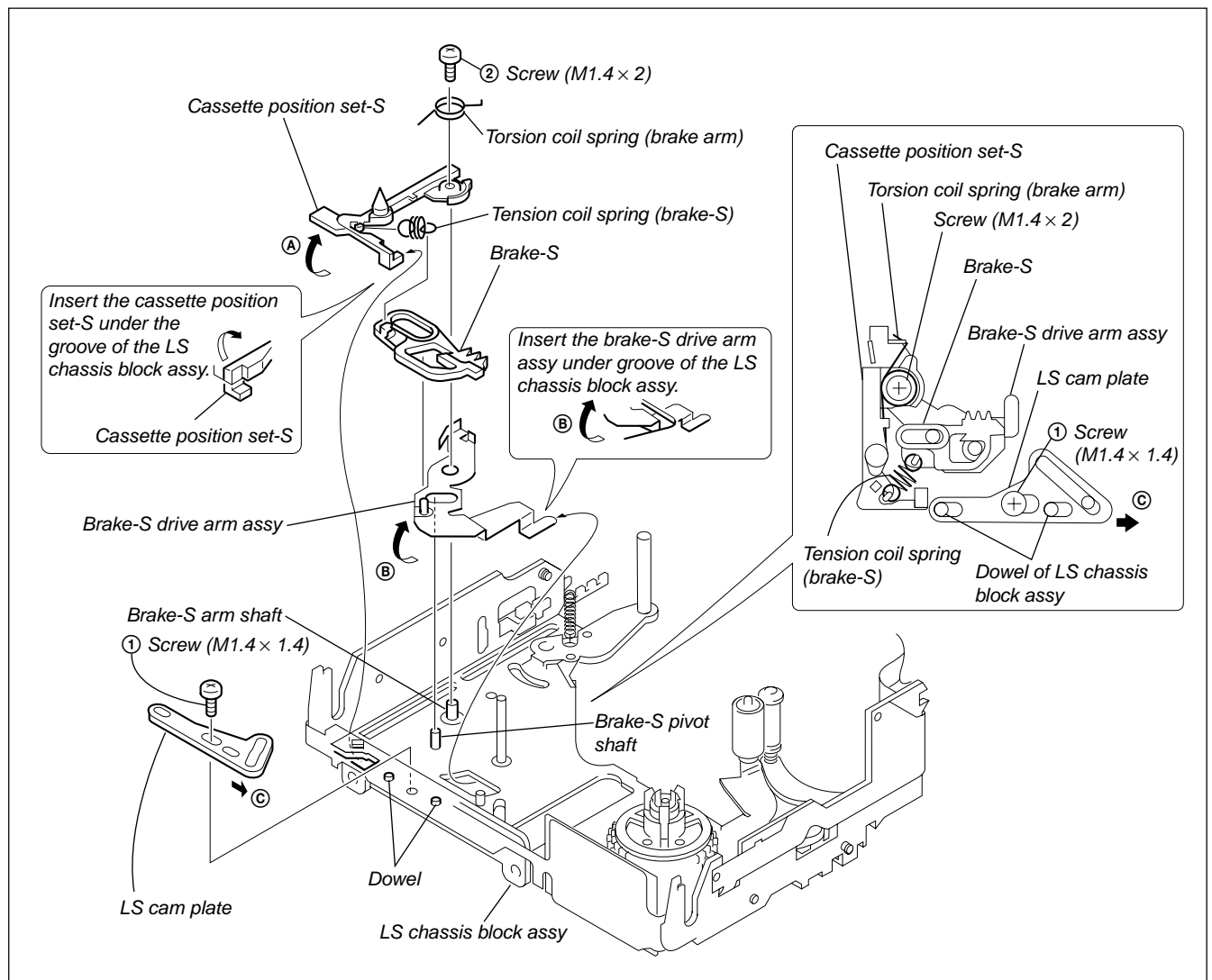


Fig. 3-13

3-14. TG7 Block Assy, Torsion Coil Spring (TG7 Return, Pinch Return), Pinch Arm Assy

1. Removal procedure

- 1) Remove the TG7 block assy in the direction of the arrow **A**.
- 2) Remove the torsion coil spring (TG7 return) **①**.
- 3) Remove the pinch arm assy in the direction of the arrow **B**.
- 4) Remove the torsion coil spring (pinch roller return) **②**.

2. Attachment procedure

- 1) Install the torsion coil spring (pinch roller return) **①**. (Insert the 90-degree-bent portion of the torsion spring into the square hole of the LS chassis block assy.)
- 2) Attach the pinch arm assy to the pinch arm bearing.
- 3) Attach the torsion coil spring (TG7 return) **①**.
- 4) While aligning the TG7 block assy with the groove of the LS chassis block assy, install the TG7 block assy into the TG7 block assy bearing.

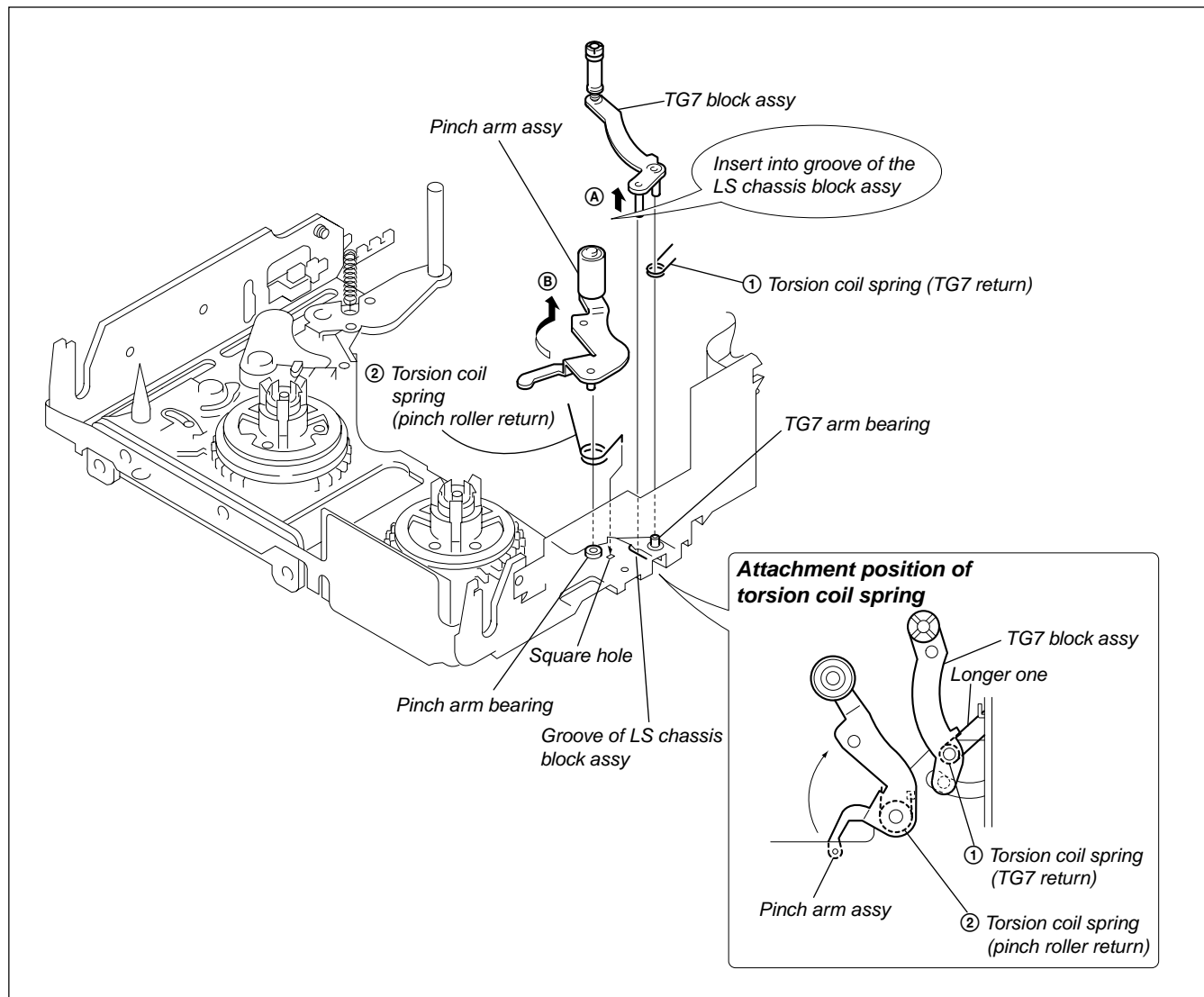


Fig. 3-14

3-15. Layout Diagram of FP-102 Flexible Wiring Board

1. Removal procedure

- 1) Remove the sensor holder-T from groove of the LS chassis block assy in the direction of the arrow **(A)**.
- 2) Remove the cassette holder-S by pushing out the hook under the LS chassis block assy towards the direction of the arrow **(B)**.

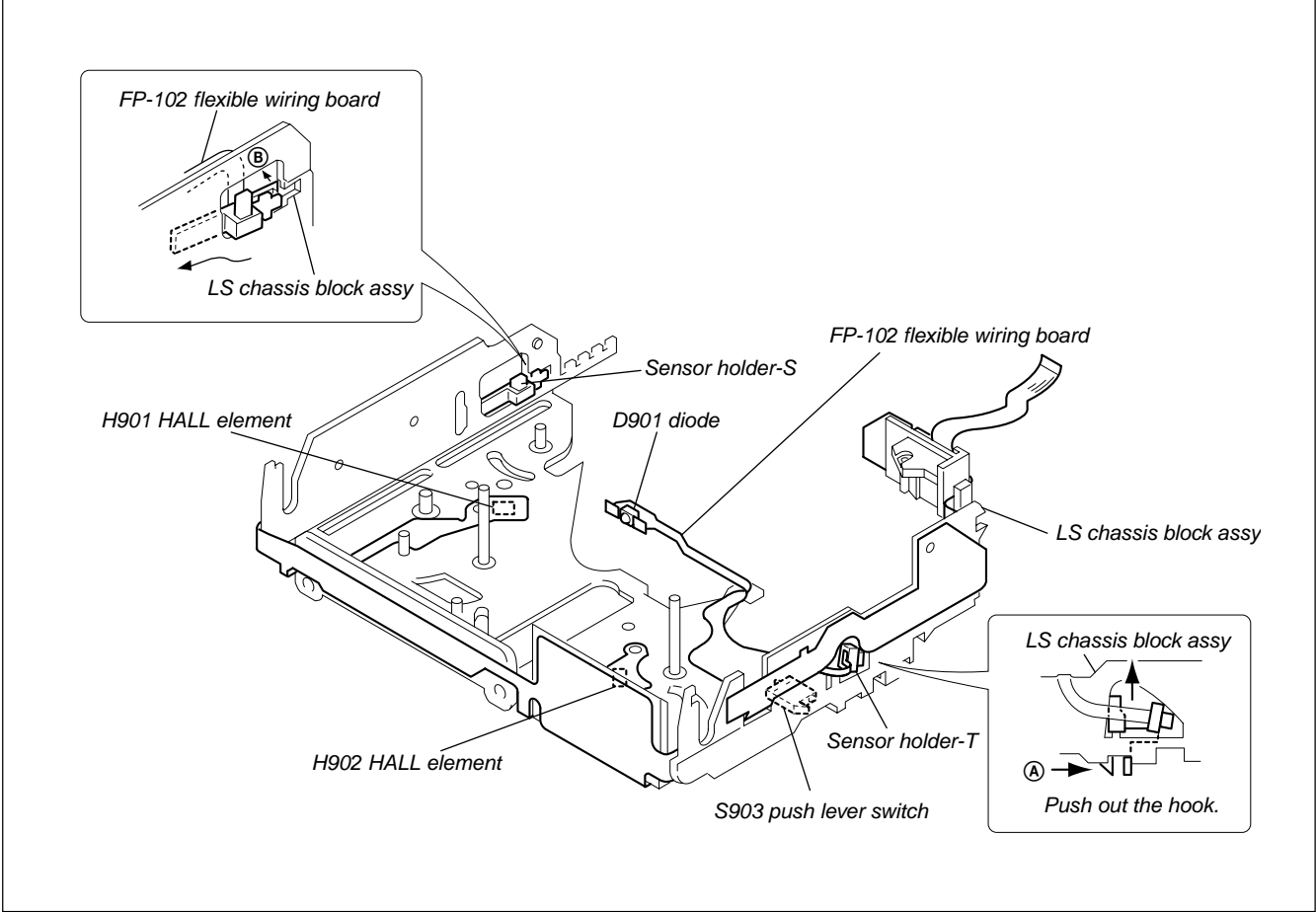


Fig. 3-15

3-16. TG1 Cam Slider, LS Arm, LS Roller, Mode Gear Assy, LS Guide Roller

1. Removal procedure

- 1) Remove the TG1 cam slider.
- 2) Remove the LS arm. (At this moment, be careful that the LS roller can come out of cam gear A groove.)
- 3) Remove the LS roller from the LS arm.
- 4) Remove the LS guide roller.

2. Attachment procedure

- 1) Coat inside the LS guide roller with grease (1/4 drop of grease) and insert it into the LS guide shafts S1 and S2.
- 2) Coat outside the LS guide roller with grease (1/2 drop of grease) at the two points as shown.
- 3) While aligning dowel of the TG1 drive arm with groove of the mode gear assy, insert the TG1 drive arm into the LS guide shaft S1.
- 4) Coat the portion ① of the LS arm with grease (1/4 drop of grease) and insert the LS guide roller.
- 5) Coat both sides of the groove of the cam gear A with grease (1/2 drop of grease). Insert the LS guide roller into groove of the cam gear A and insert the LS arm into the LS guide shaft S2.
- 6) Insert the TG1 cam slider into the three positions of the LS guide shaft S1, S2 and slider guide shaft. Insert dowel of the TG1 cam slider into groove of the cam gear A.
- 7) Be careful that greasing points are correct, amount of grease is correct and the LS arm and the TG1 drive arm are not floating.

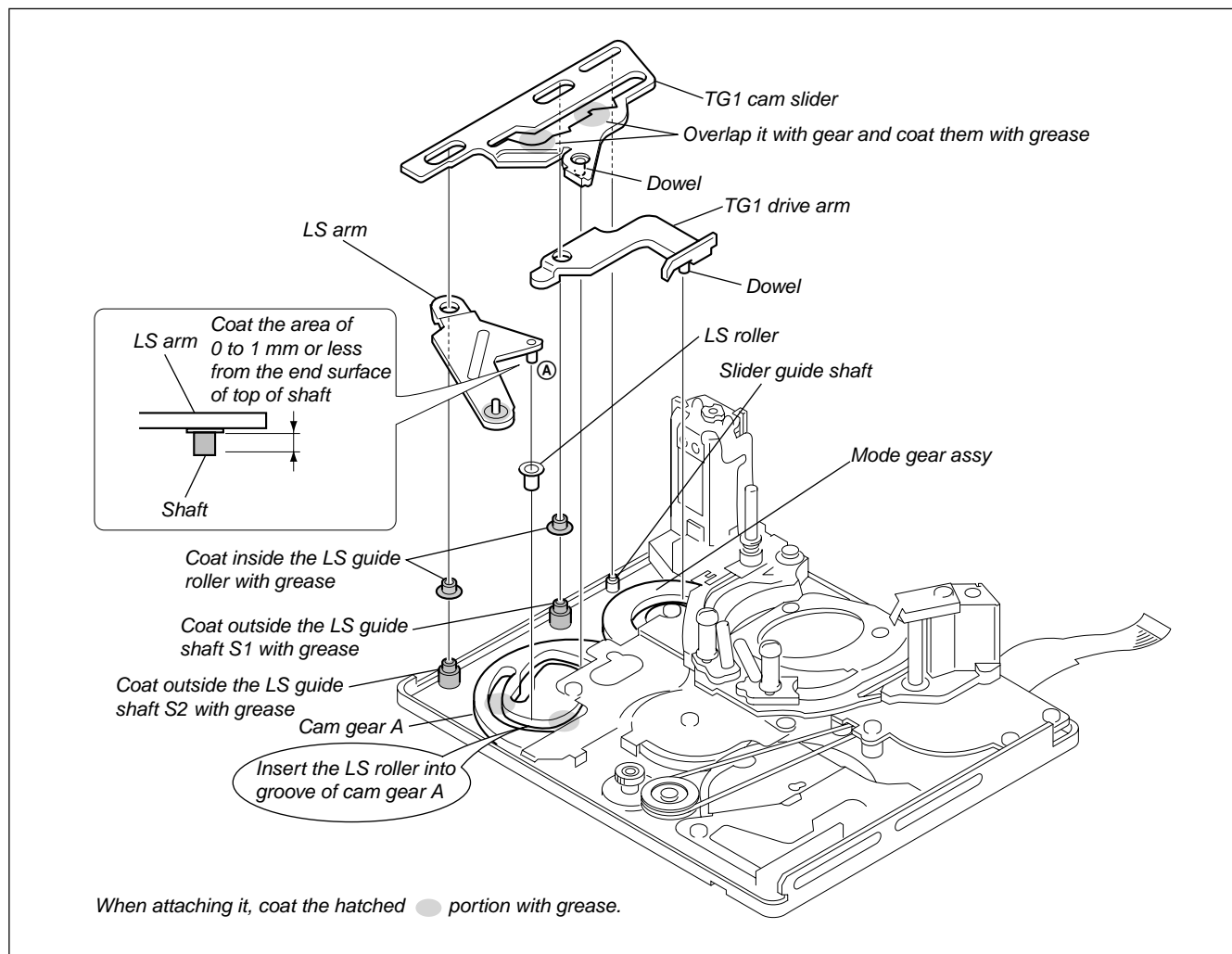


Fig. 3-16

3-17. Guide Rail

1. Removal procedure

- 1) Remove the screw (M1.4 × 2) ①.
- 2) When removing the guide rail, be careful that claws of the drum base block assy are fully released. Remove the S-side rail, T-side rail and rail of DC motor side in this order.

2. Attachment procedure

- 1) Engage the claws of the guide rails with the claws of the drum base block assy starting engaging the claw from the T-side rail and S-side rail.
Note: There must no deformation of guide rail, claws must not be broken, claws must not override, claws must not become white, not be stained or have no play.
- 2) Fix the guide rail with the screw (M1.4 × 2) ①.
Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg•cm)

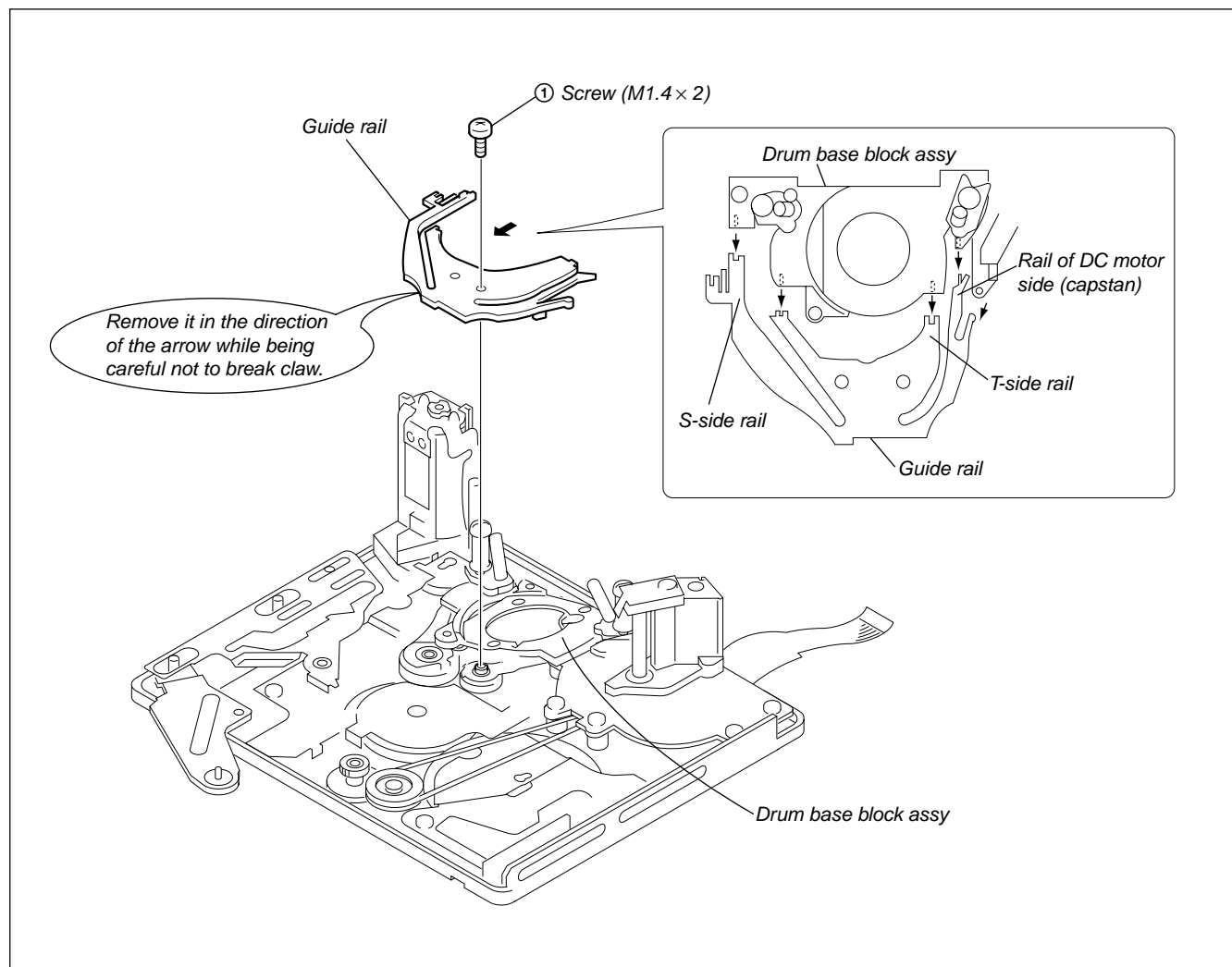


Fig. 3-17

3-18. Gear Cover B, GL Driving Gear

1. Removal procedure

- 1) Remove the screw (M1.4 × 2) ①.
- 2) Remove the gear cover B in the direction of the arrow ②.
- 3) Remove the GL drive gear.

2. Attachment procedure

- 1) Coat the cam gear A and the GL drive gear with grease (1/2 drop). (Refer to Fig. 2.)
- 2) Refer to Fig. 1. While adjusting phase of the GL drive gear as shown, insert the GL drive gear into the GL drive shaft. (Insert it while moving the GL drive gear in the clockwise direction.)
- 3) Insert the two claws of the gear cover B into the square holes of mechanism chassis.
- 4) Fix the GL drive shaft with the screw (M1.4 × 2) ①. Be sure that the gear cover B must not have any play.
Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg \cdot cm)

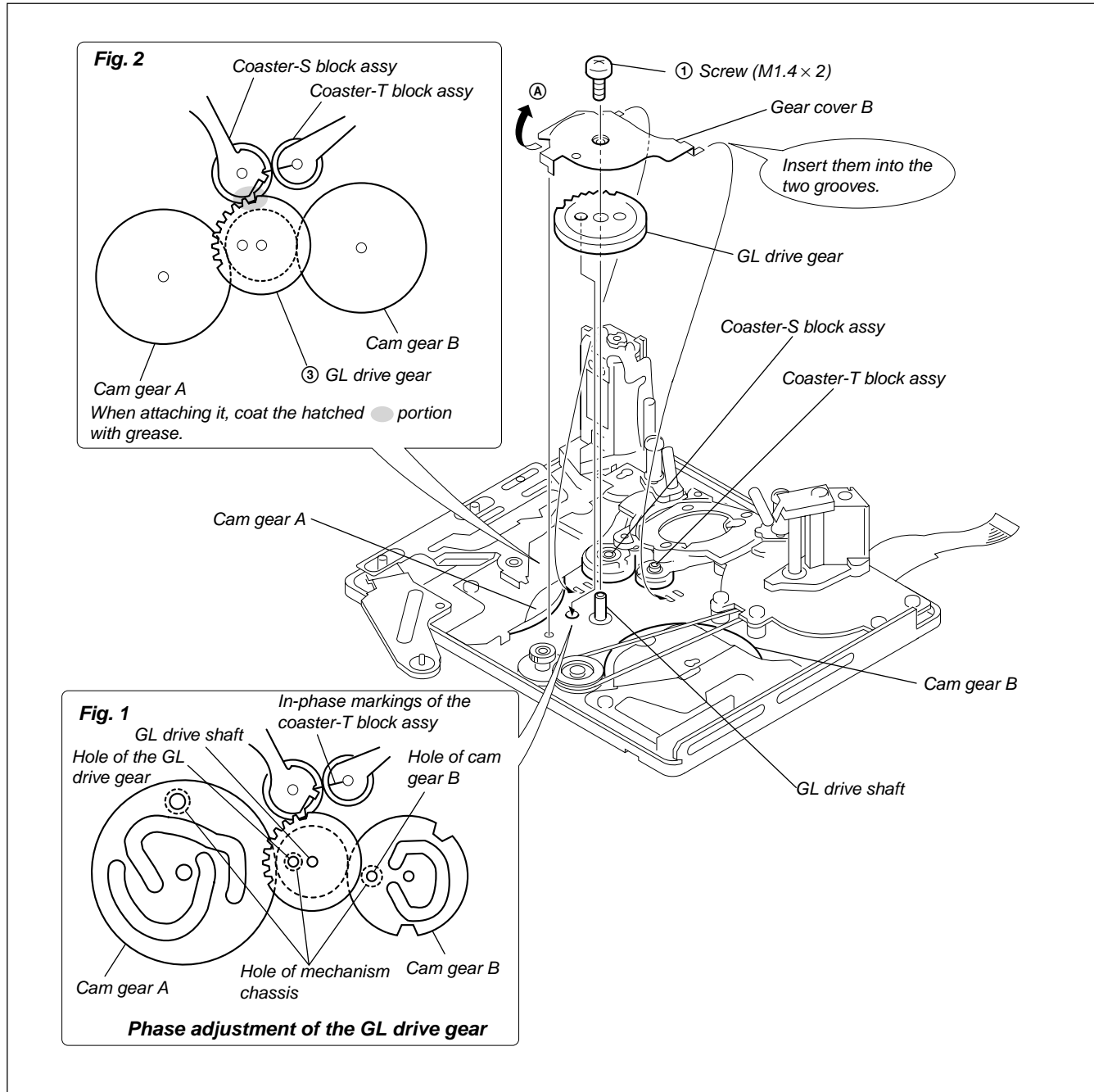


Fig. 3-18

3-19. Drum Base Block Assy, Coaster-S Block Assy, Coaster-T Block Assy

1. Removal procedure

- 1) Remove three screws (M1.4 × 2.5).
- 2) Move the coaster-S block assy and coaster-T block assy out from the drum base groove in the direction of the arrow (A).
- 3) Remove the drum base block assy.
- 4) Remove the coaster-S block assy from the GL gear shaft-S.
- 5) Remove the coaster-T block assy from the GL gear shaft-T.

2. Attachment procedure

- 1) Insert a coaster-S block assy and coaster-T block assy into the drum base groove.
- 2) Place a drum base block assy on top of the mechanism chassis assy. Insert a coaster-T block assy into the GL gear shaft-T.
- 3) Insert a coaster-S block assy in the oblique direction. While adjusting phase so that the spring of coaster-S block assy agrees with the GL gear lever marking of the coaster-T block assy, insert a coaster-S block assy into the GL gear shaft-S.
Note:
 - There must be no phase difference.
 - Do not remove coaster-S block assy and coaster-T block assy from the drum base block assy.
- 4) Determine the exact position of the drum base block assy that has been tentatively placed, on the mechanism chassis assy. Tighten the screws at (A), (B) and (C) in this order.
 Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ ($0.6 \text{ kg}\cdot\text{cm}$)

Note: Be careful that the position setting boss of drum base block assy does not override on the mechanism chassis.

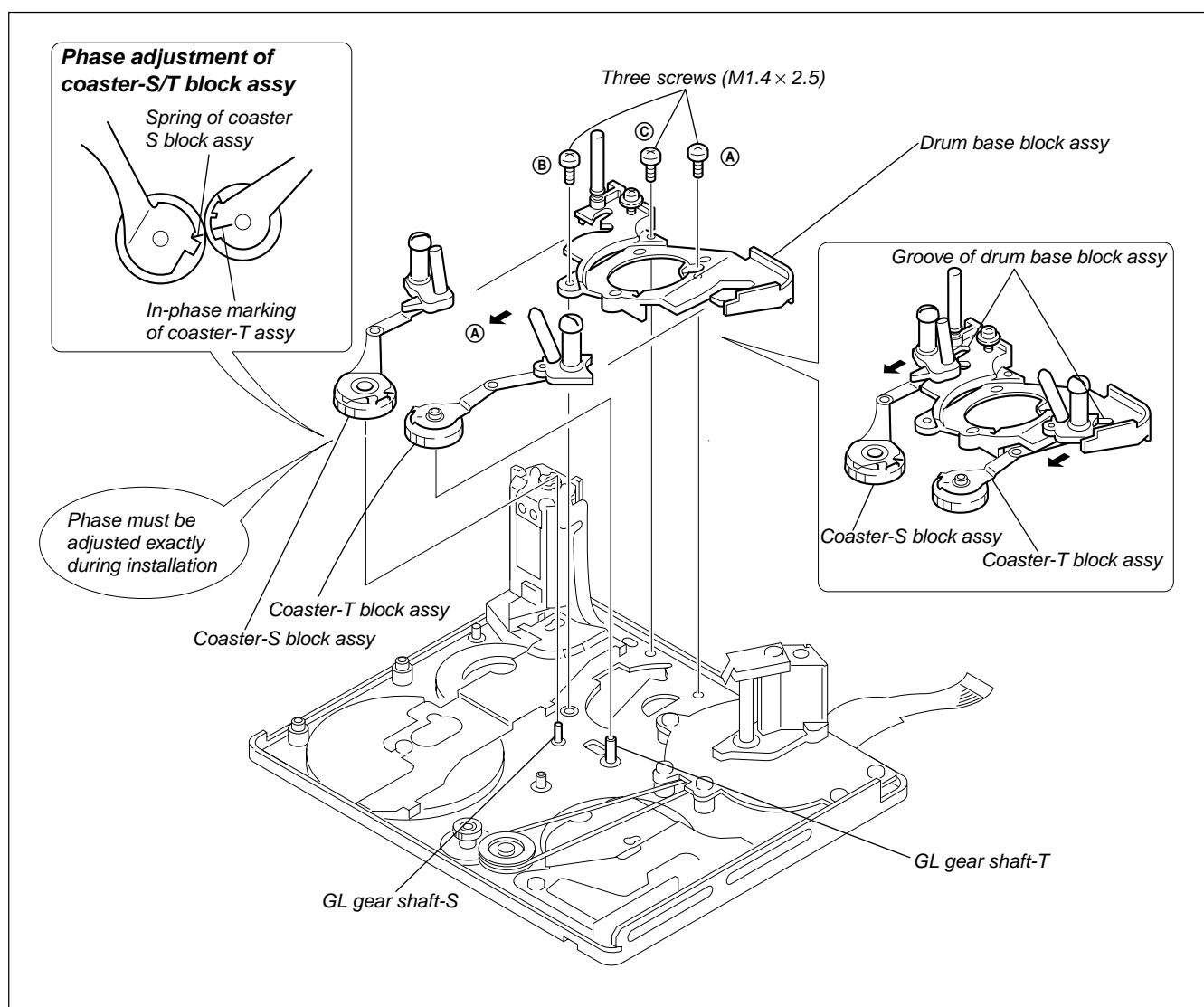


Fig. 3-19

3-20. DC Motor (Capstan), Conversion Gear, Relay Gear

1. Removal procedure

- 1) Remove the three screws (M1.4 × 2) ①.
- 2) Remove DC motor (capstan). Remove belt from the pulley of conversion gear.
- 3) Remove conversion gear.
- 4) Remove relay gear.

2. Attachment procedure

- 1) Coat relay gear shaft and conversion gear shaft with grease (1/8 drop). (Amount of grease must be strictly controlled.)
- 2) With the larger gear of the relay gear positioned down, attach the relay gear to the relay gear shaft.
- 3) With the pulley side of the conversion gear positioned up, engage the conversion gear teeth with the relay gear teeth, and install them.
- 4) Before installing the DC motor (capstan (including belt)), check that belt is not twisted. Hook a belt on the pulley block of conversion gear. Align three shafts with corresponding holes. At this moment, confirm that belt does not override on the shaft.
- 5) Install DC motor (capstan) with three screws (M1.4 × 2) ① in the order of (A), (B) and (C).
① tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg \cdot cm)
② and ③ tightening torque: $0.038 \pm 0.01 \text{ N}\cdot\text{m}$ (0.4 kg \cdot cm)

Note: Be careful that gears and belts are not damaged or dust is not attached.
Be careful also not to splash grease.

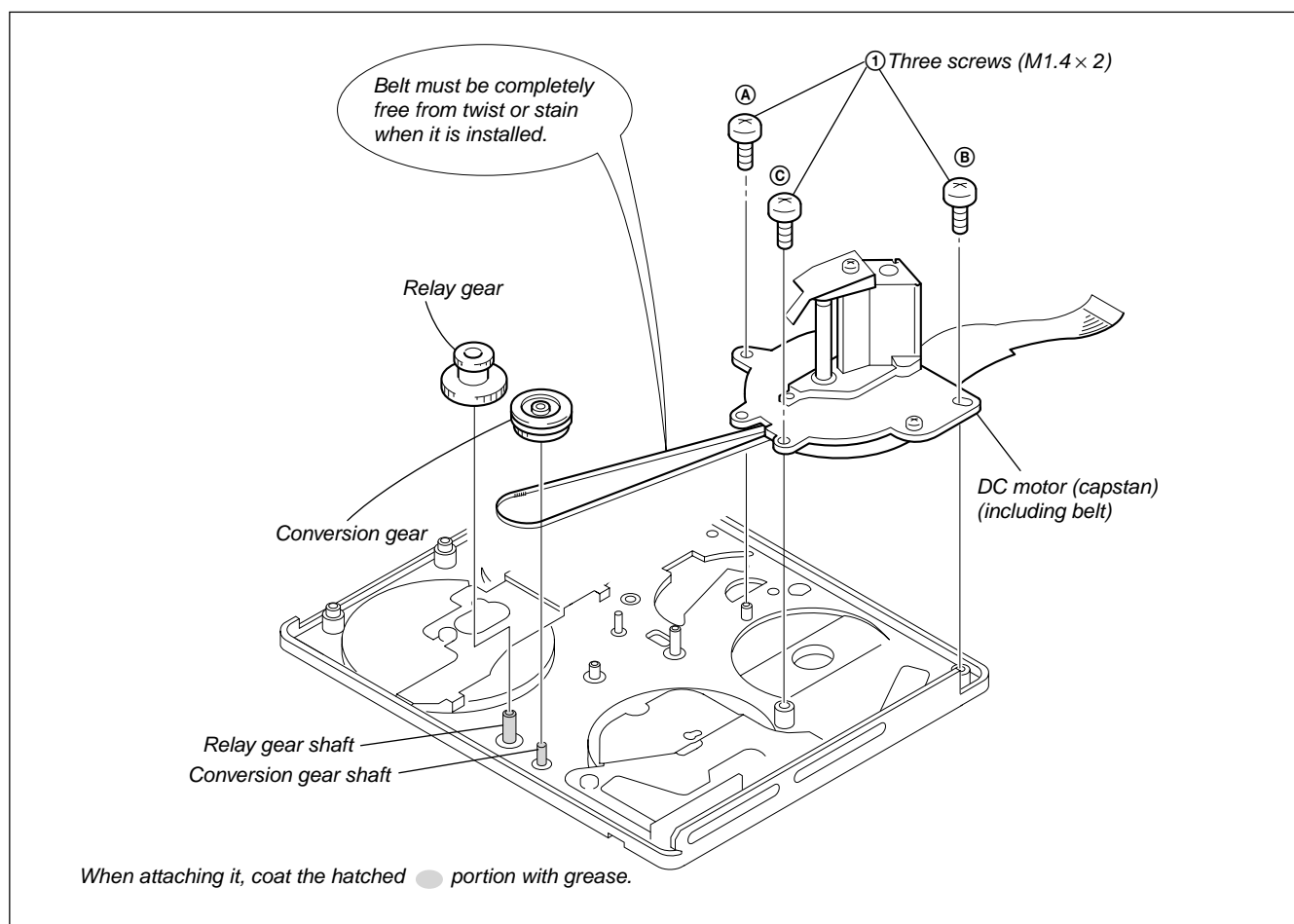


Fig. 3-20

3-21. Gear Cover C, Pinch Driving Arm Assy, Cam Gear B

1. Removal procedure

- 1) Remove the screw (M1.4 × 2) ①.
- 2) Move the key slot of the gear cover C in the direction of the arrow (A) and remove the gear cover C.
- 3) Remove the pinch drive arm assy.
- 4) Remove the cam gear B.

2. Attachment procedure

- 1) Identify the front side and the rear side of a cam gear B. Align the cam gear B shaft, the gear phasing hole and the LS chassis hole. Then attach the cam gear B. coat groove of a cam gear with grease (1/2 drop).
- 2) Align the pinch drive arm assy with the pinch drive pivot shaft. While aligning dowel with the cam groove of the cam gear B, insert the pinch drive arm assy.
- 3) Insert the “one-step bent portion” of gear cover C into notch of the chassis, insert the cam gear B shaft into the key hole of the gear cover C.
- 4) Insert the gear cover C into the pinch drive pivot shaft and fix it with the screw (M1.4 × 2) ①. After tightening the screw (M1.4 × 2) ①, move the gear cover C in order to confirm that there is a little play.
Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg•cm)

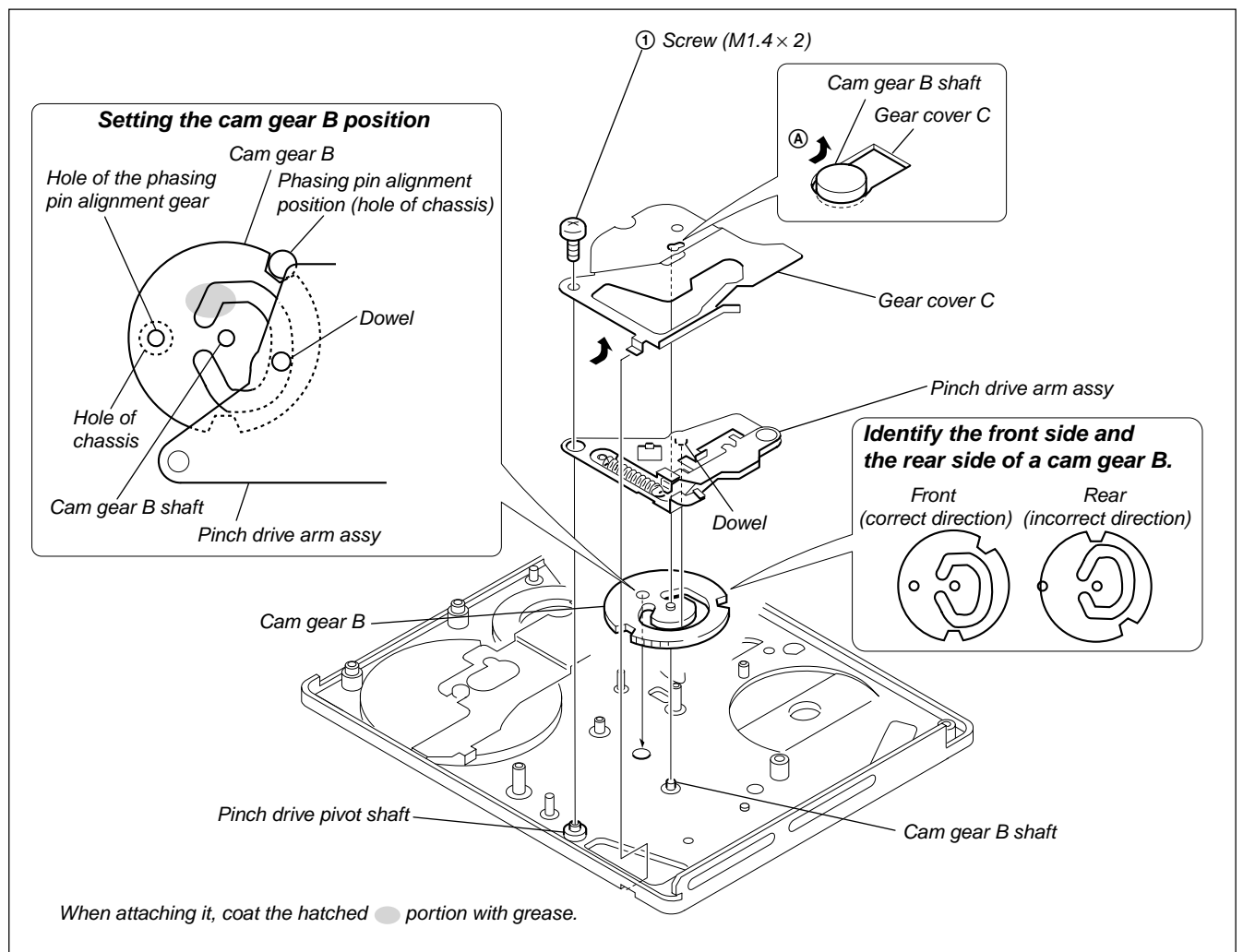


Fig. 3-21

3-22. Gear Cover A, FP-100 Flexible Wiring Board

1. Removal procedure

- 1) Remove the screw (M1.4 × 2) ①.
- 2) Remove the gear cover A in the direction of the arrow (A).
- 3) Remove the screw (M1.4 × 2.5) ②.
- 4) Remove soldering from the motor terminal and FP-228 flexible wiring board (DEW sensor) that are used to connect the FP-100 flexible wiring board with the motor holder block assy.
- 5) Remove the motor holder block assy.

2. Attachment procedure

- 1) Align the motor holder block assy position with the chassis square hole and round hole. The press the motor holder block assy with finger.
Note: Coat the worm shaft with grease (1/2 size of a rice gain).
- 2) Fix the motor holder block assy with the screw (M1.4 × 2.5) ②.
Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg \cdot cm)
- 3) Install the gear cover A as follows: Hook the shaft with the key slot and align the U-groove with the cam gear A shaft. Confirm at this time that there is a play.
- 4) Attach the gear cover A to the cam gear A shaft and fix them with the screw (M1.4 × 2) ①.
Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg \cdot cm)
- 5) Connect the FP-100 flexible wiring board with the motor holder block assy (motor terminal and FP-228 flexible wiring board (DEW sensor)) by soldering.
Note: Do not touch the DEW sensor.

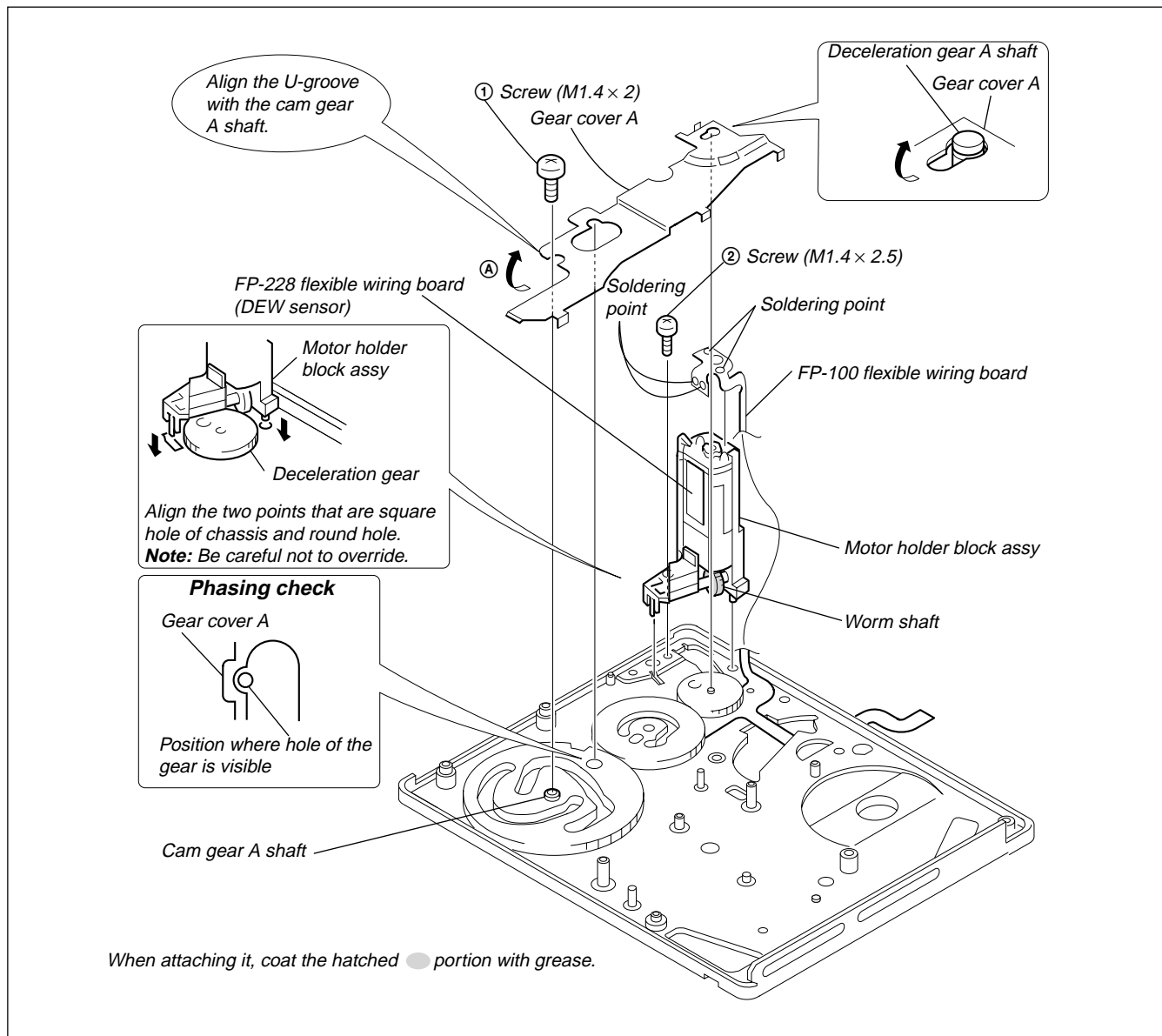


Fig. 3-22

3-23. Deceleration Gear, Mode Gear Assy, FP-100 Flexible Wiring Board, Cam Gear A

1. Removal procedure

- 1) Remove the deceleration gear.
- 2) Remove the screw (M1.4 × 2) ①.
- 3) Remove the cam gear A.
- 4) Remove the mode gear assy.
- 5) Remove the FP-100 flexible wiring board.

Note 1: Do not touch the foil pattern area of the FP-100 flexible wiring board. Any foreign materials must not be adhered.

Note 2: Do not remove the mode gear assy unnecessarily.

2. Attachment procedure

- 1) Install the FP-100 flexible wiring board to the mechanism chassis. Confirm that flexible wiring board is not stained, broken, bent or damaged.
- 2) Coat the entire contact points of the mode pattern area of the FP-100 flexible wiring board with the contact-point grease (equivalent to 1.5 drops). (Any foreign materials must not be mixed in the contact-point grease.)
- 3) Attach the mode gear assy to the mode gear shaft.

- 4) Install the deceleration gear as follows: Position the deceleration gear with its small gear down, and engage the small gear tooth with the mode gear tooth. Rotate the gear tooth until the phasing marking of the mode gear assy arrives at the phasing position of the cam gear A.
- 5) Identify the front and rear sides of the cam gear A. Confirm that the marking of the cam gear A and that of the mode gear assy agree.
- 6) Attach the screw (M1.4 × 2) ① of the mode gear assy. Tightening torque: $0.059 \pm 0.01 \text{ N}\cdot\text{m}$ (0.6 kg•cm)
- 7) Connect the FP-100 flexible wiring board to the motor holder block assy by soldering in accordance with section "3-22 [2. Attachment procedure] step 7.

Note 1: If the FP-100 flexible wiring board is removed, replace it with a new FP-100 board, and do not use the removed FP-100 flexible wiring board.

Note 2: Cautions when attaching the FP-100 flexible wiring board:

- ① It must not override on the mode gear shaft.
- ② It must be aligned with the position setting hole.
- ③ It must no float, must not have stain or must not be broken.
- ④ Never touch the foil pattern area with hand.

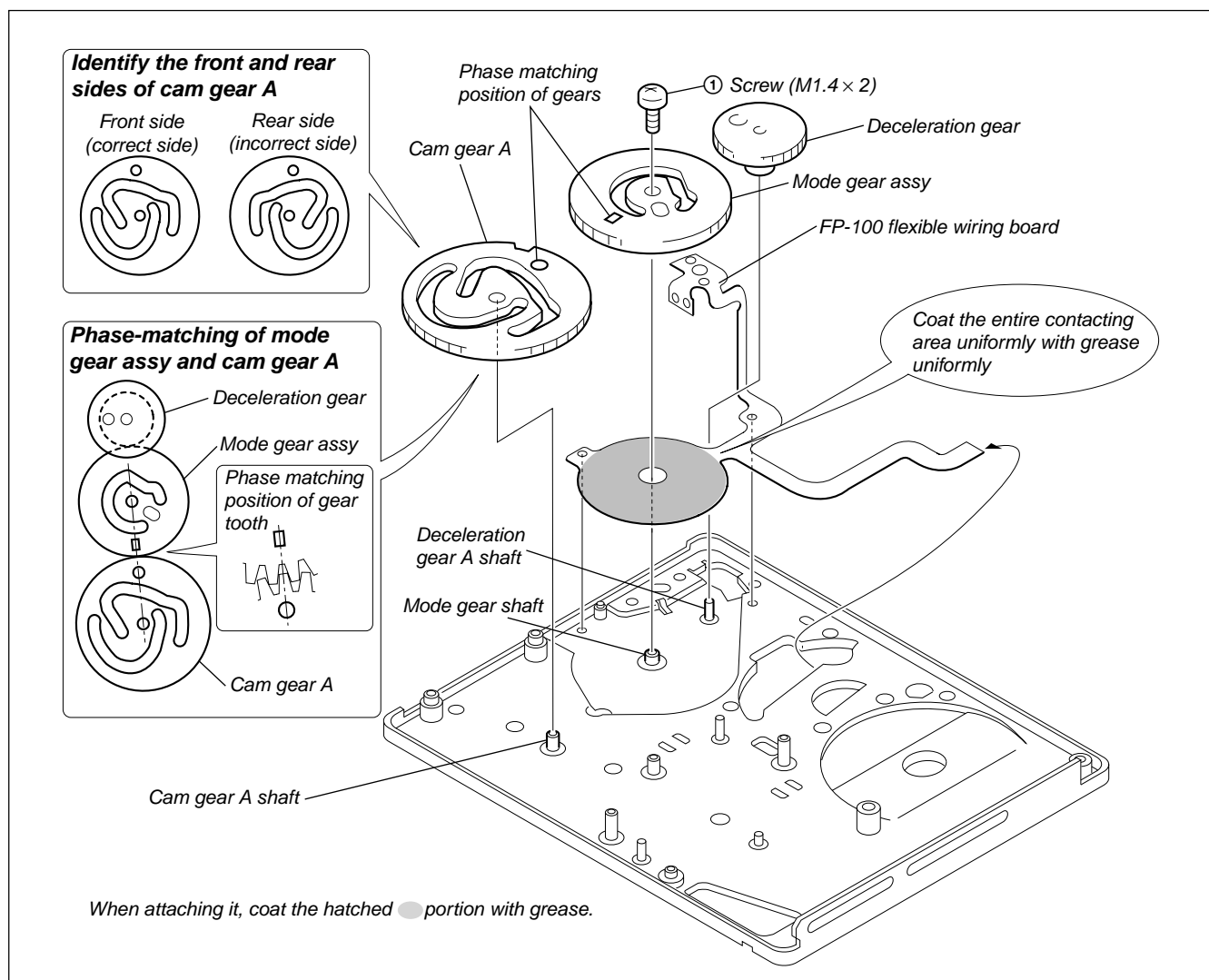


Fig. 3-23

4. Tape Path Adjustment

4-1. Adjustment Preparation

- 1) Clean the tape running surface (tape guides, drum, capstan, pinch roller) referring to Service Manual.
- 2) Connect adjustment remote commander (Ref. No. J-13) to the LANC terminal of the machine. Set the HOLD switch to ON.
- 3) Connect an oscilloscope to the VC-240 board CN009 via the CPC-8 jig (J-082-388-A). (in the case of DCR-TRV20).
Scope channel 1: VC-240 board CN009 pin ⑳ (Note)
External trigger: VC-240 board CN009 pin ⑰ (Note)
Note: Connect CN009 pin ⑳ and pin ⑱ (GND) with 75 Ω resistor (1-247-804-11).
- 4) Play the tracking alignment tape (XH2-1)(Ref. No. J-5) back.
- 5) Select page: 3, address: 33 and data: 08. (Note)
- 6) Select page: 3, address: 26 and data: 31. (Note)
- 7) Confirm that RF waveform on scope is flat in both entrance side and exit side. (Refer to Fig. 4-2 **A**).
If RF waveform is not flat in entrance side and exit side, perform the adjustment of section 4-2. and later. (Refer to Fig. 4-2 **B** and **C**).
- 8) When the required conditions of step 7) are satisfied and adjustment/check are complete, perform [Required work upon completion of adjustment] as described below.

[Required work upon completion of adjustment]

- 1) Connect adjustment remote commander (Ref. No. J-13) to the LANC terminal of the machine. Set the HOLD switch to ON.
- 2) Select page: 3, address: 26 and data: 00. (Note)
- 3) Select page: 3, address: 33 and data: 00. (Note)

Note: Page and address numbers differ depending on each model. Please refer to Service Manual of respective models. Those of DCR-TRV20 are described above.

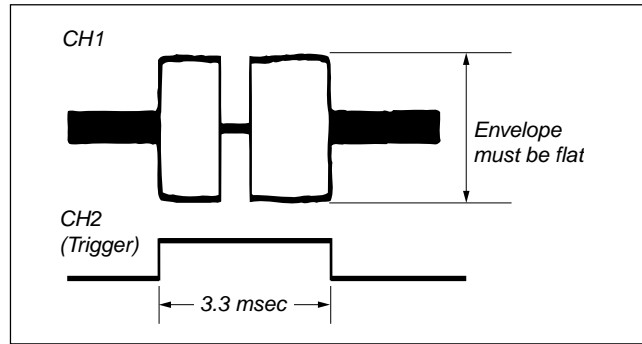


Fig. 4-1

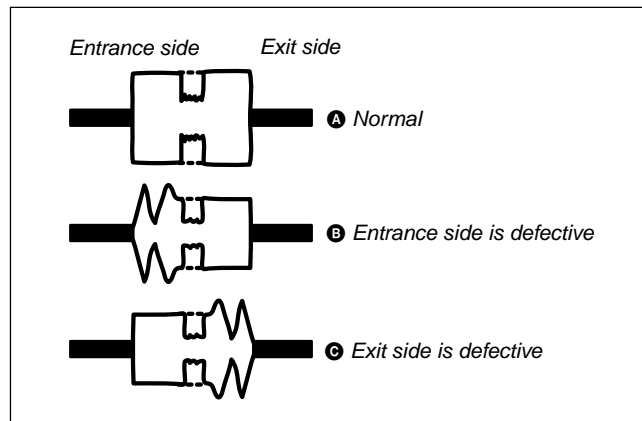


Fig. 4-2

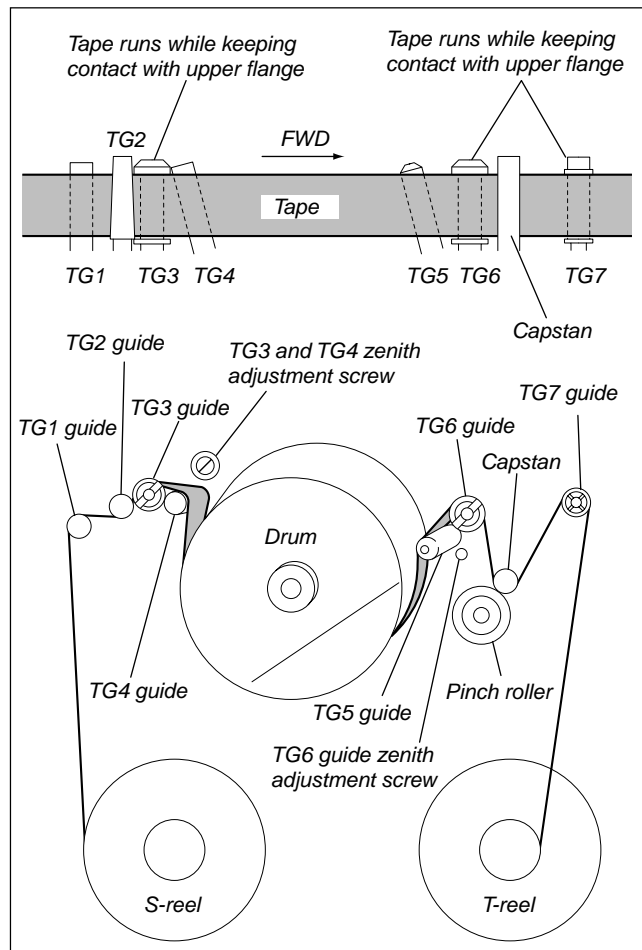


Fig. 4-3

4-2. Tracking Adjustment

- 1) Play the tracking alignment tape (XH2-1) (Ref. No. J-5) back.
- 2) Adjust TG3 guide until the envelope of entrance side waveform becomes flat.
- 3) Adjust TG6 guide until the envelope of exit side waveform becomes flat.

Note: Do not touch or adjust TG3 and TG4 guide zenith adjustment screw.

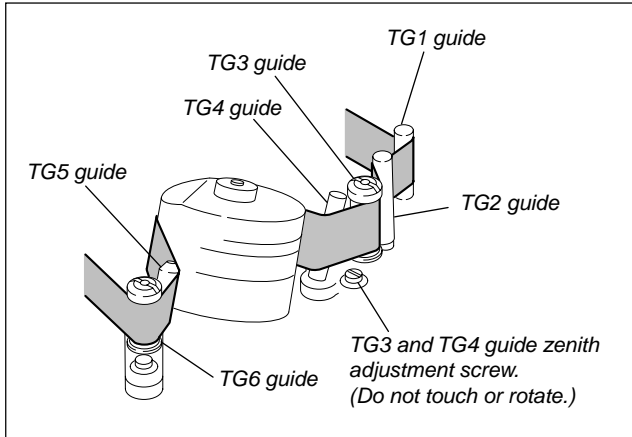


Fig. 4-4

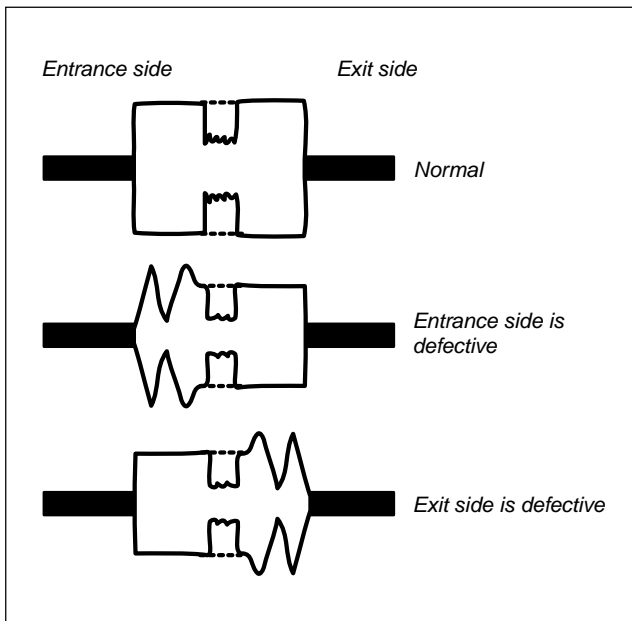


Fig. 4-5

4-3. TG3 Guide Adjustment

- 1) Play the tracking alignment tape (XH2-1) (Ref. No. J-5) back.
- 2) Run the tape in FWD mode. Confirm that tape runs while keeping contact with upper flange of TG3. If any clearance is found between top flange and tape, rotate the adjustment nut in clockwise direction until tape runs while keeping contact with upper flange of TG3.

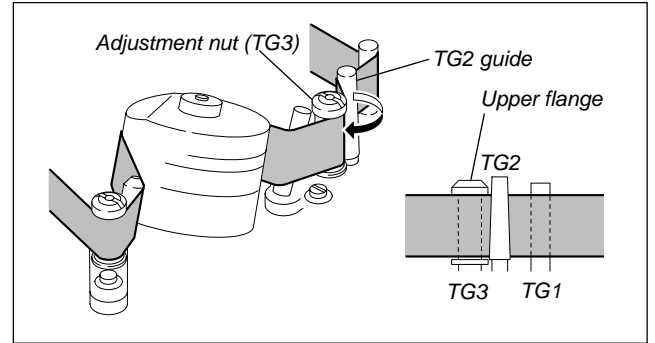


Fig. 4-6

When tape runs while keeping contact with upper flange of TG3, confirm that the tracking waveform does not change. If the tracking waveform has poor amplitude at the entrance side as shown, perform tracking adjustment of entrance side.

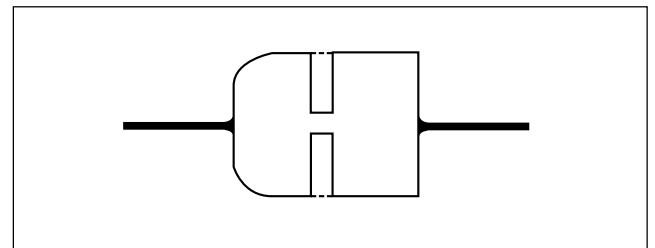


Fig. 4-7

After entrance side is adjusted, establish the RVS mode. Make an attempt to rotate the TG3 adjustment nut by 180 degrees in the counter-clockwise direction in order to confirm that tape rises upward. Upon confirmation, return the TG3 adjustment nut to the original position.

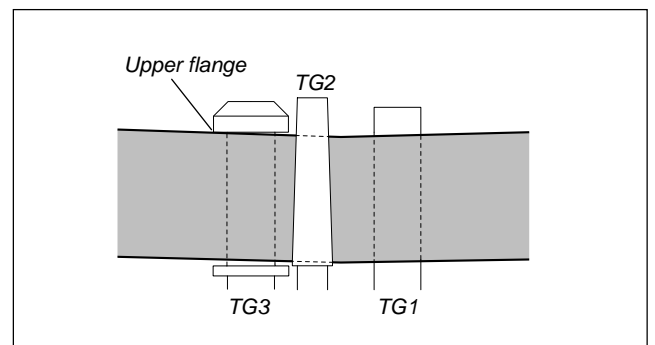


Fig. 4-8

4-4. TG7 Guide Adjustment

- 1) Establish the FWD mode. Confirm that tape slack does not occur in between capstan and TG7 guide. (Specification value: 0.5 mm or less of tape slack) If any tape slack occurs, rotate the TG7 guide to remove the tape slack.
- 2) Establish the REV mode. Confirm that RF waveform at exit side is normal. (Refer to Fig. 4-10.)
- 3) If the RF waveform at exit side has abnormality, rotate the TG7 nut by 90 degrees in counter-clockwise direction. Then perform steps 1) and 2) again.

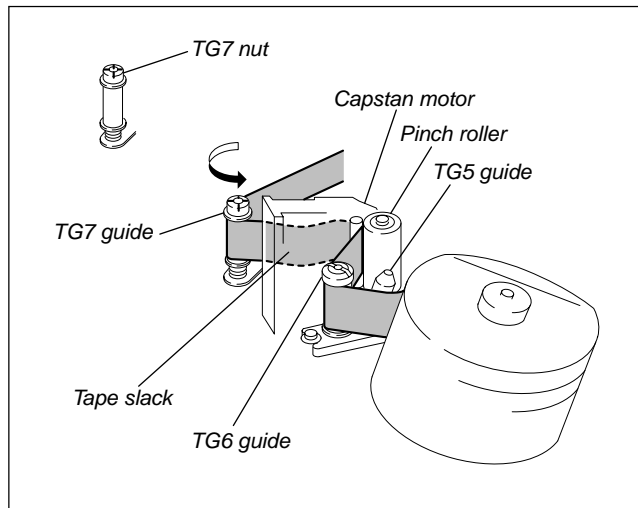


Fig. 4-9

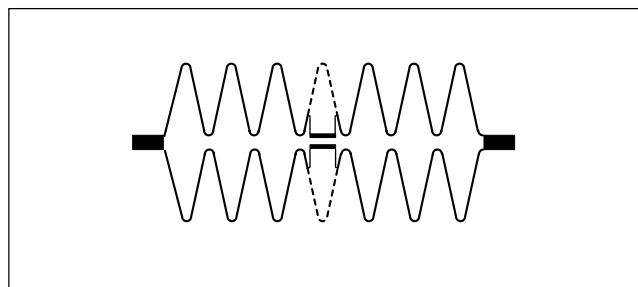


Fig. 4-10

4-5. Check upon Completion of Adjustment

1. Tracking Check

- 1) Play the tracking alignment tape (XH2-1) (Ref. No. J-5) back.
- 2) Confirm that RF waveform has amplitude of about 0.65A (65%) in the FWD mode taking the waveform amplitude during CUE/REV mode as A (= 100%). (Refer to Fig. 4-11.)

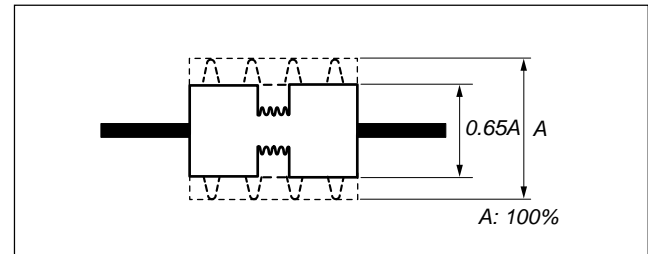


Fig. 4-11

- 3) Confirm that difference between the minimum amplitude (E.min) and the maximum amplitude (E.max) of RF waveform in the FWD mode is 30% or more taking the waveform amplitude during CUE (or REV) mode as A (= 100%).

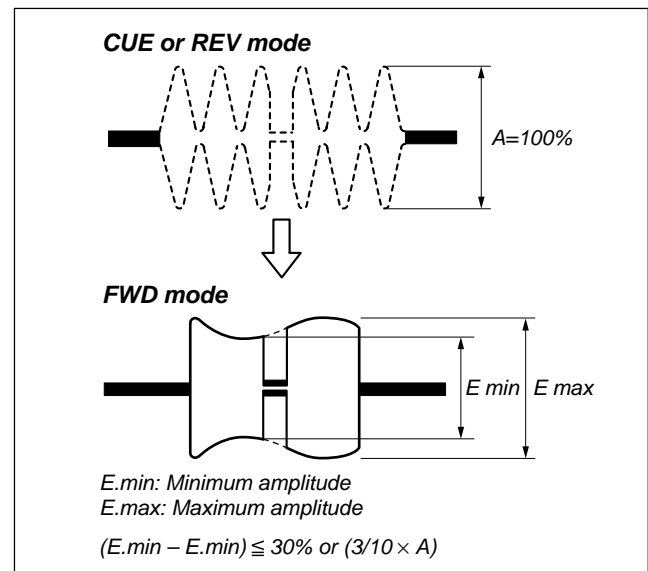


Fig. 4-12

- 4) Confirm that the RF waveform does not have excessive fluctuation.

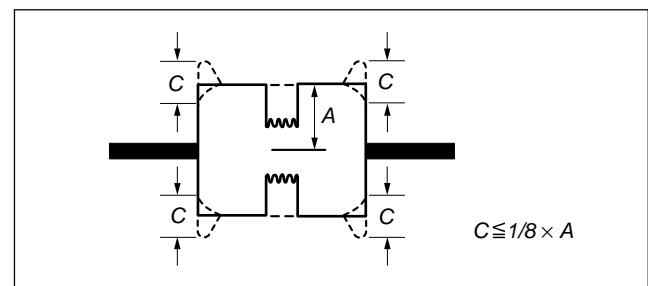


Fig. 4-13

2. CUE/REV Check

- 1) Play the tracking alignment tape (XH2-1) (Ref. No. J-5) back and enter the REV mode. Confirm that pitches between peaks of RF waveform are equally spaced. (Refer to Fig. 4-14.) If pitches between peaks of RF waveform are not equal, perform sections "4-2 Tracking Adjustment" and "4-4. TG7 Guide Adjustment".
- 2) Enter the CUE mode. Confirm that pitches between peaks of RF waveform are equally spaced. (Refer to Fig. 4-14.) If pitches between peaks of RF waveform are not equal, perform sections "4-2 Tracking Adjustment".

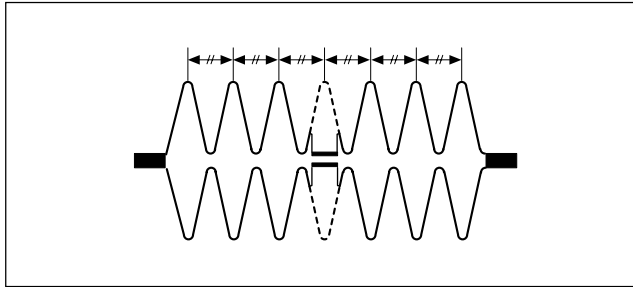


Fig. 4-14

3. Rise-up Check

- 1) Play the tracking alignment tape (XH2-1) (Ref. No. J-5) back.
- 2) Establish the FWD playback mode. Confirm that RF waveform rises up in two seconds or less. Confirm also at this time that tape slack does not occur at around pinch roller.
- 3) Run a tape in CUE/REV mode and FF/REW mode. After that play the tape back and confirm that RF waveform rises up in two seconds or less.
- 4) Repeat steps 2) and 3) repeatedly.

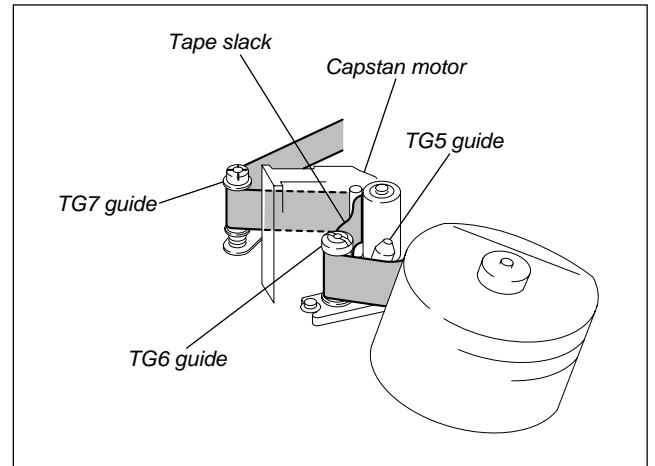


Fig. 4-15

4. Tape Run Check

Run a tape in CUE/REV mode. Confirm to see that major tape curl does not occur at TG2 lower taper, TG3 upper flange, TG6 upper flange and TG7 upper flange during CUE/REV mode.

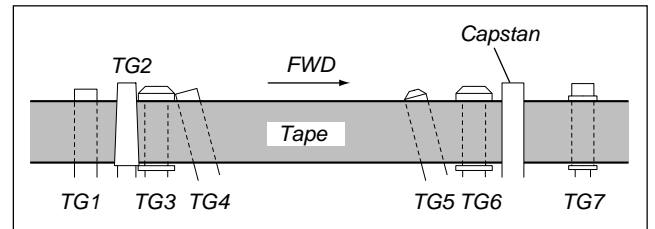
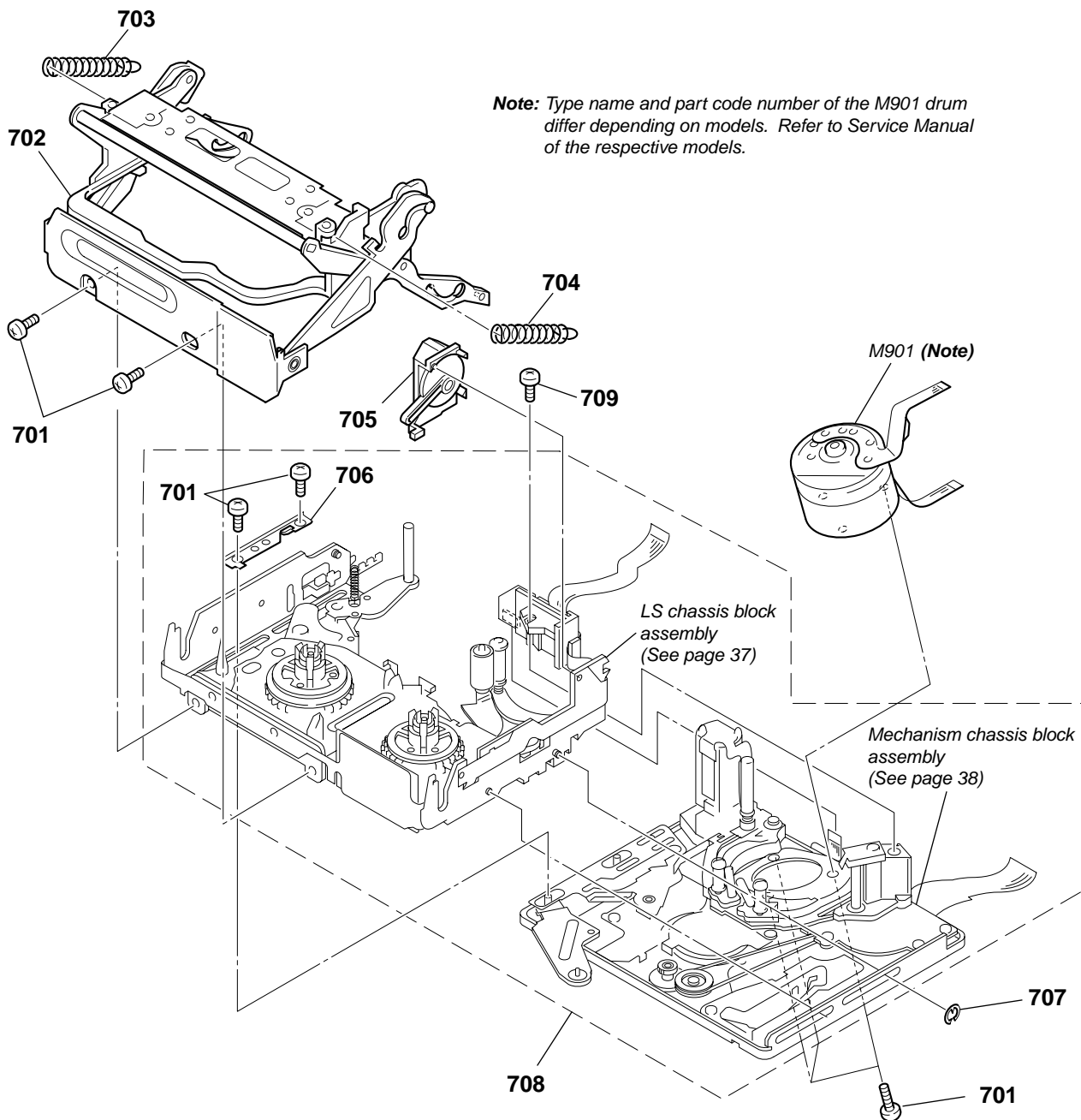


Fig. 4-16

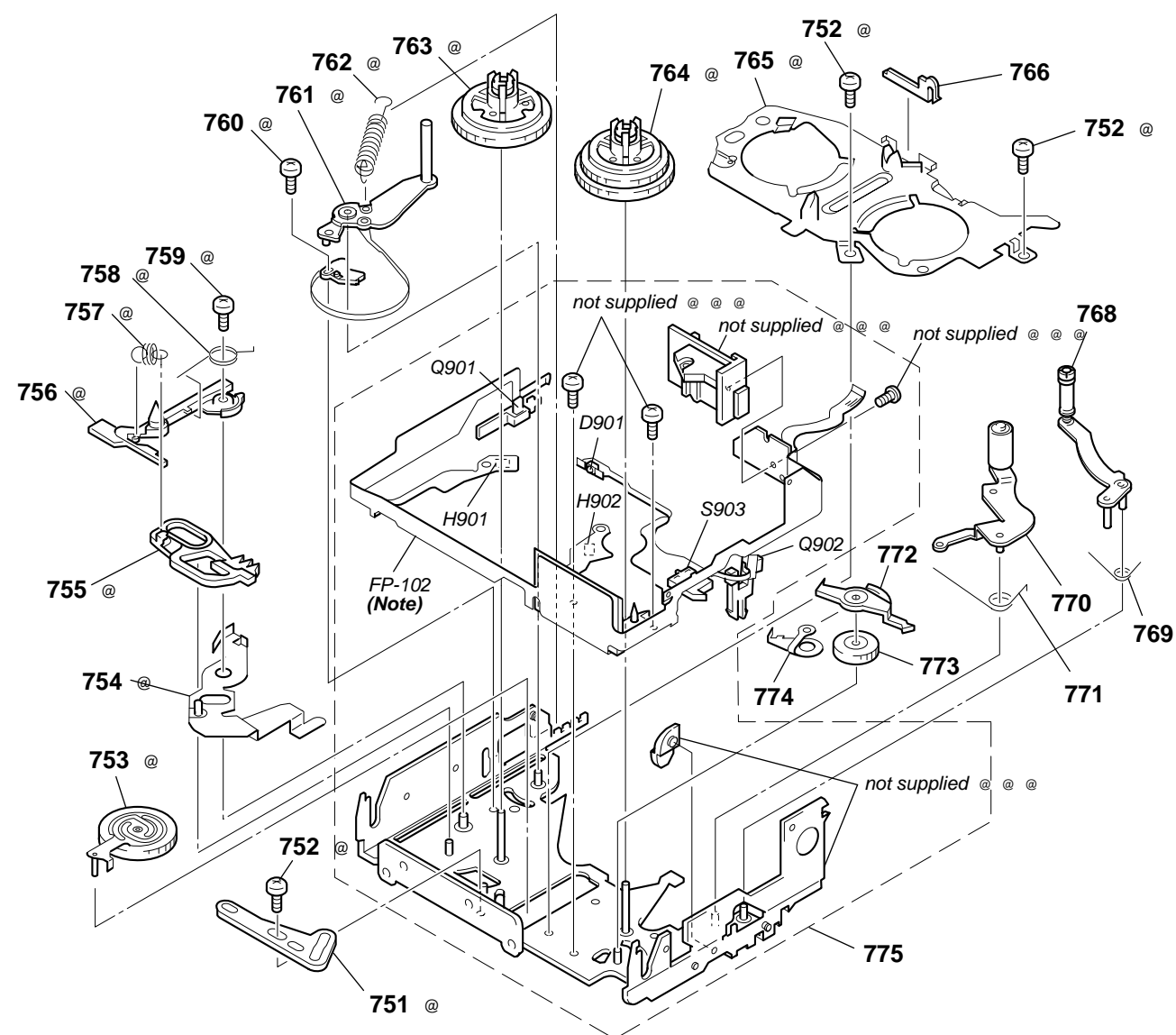
5. Exploded View

5-1. Cassette Compartment Block Assy, Drum Assy Block



Ref. No.	Part No.	Description	Remarks	Ref. No.	Part No.	Description	Remarks
701	3-703-816-14	SCREW (M1.4)		706	3-059-101-01	RETAINER, LS GUIDE	
702	X-3950-369-2	CASSETTE COMPARTMENT ASSY		707	7-624-102-04	STOP RING 1.5, TYPE -E	
703	3-059-082-01	SPRING, TENSION		708	A-7028-133-A	MD(J100) SUB ASSY (Y)	
704	3-059-208-01	SPRING (CASSETTE COMPARTMENT T)		709	3-703-816-41	SCREW (M1.4X2.5), SPECIAL HEAD	
705	X-3950-370-2	DAMPER ASSY		M901	— Note —	DRUM	

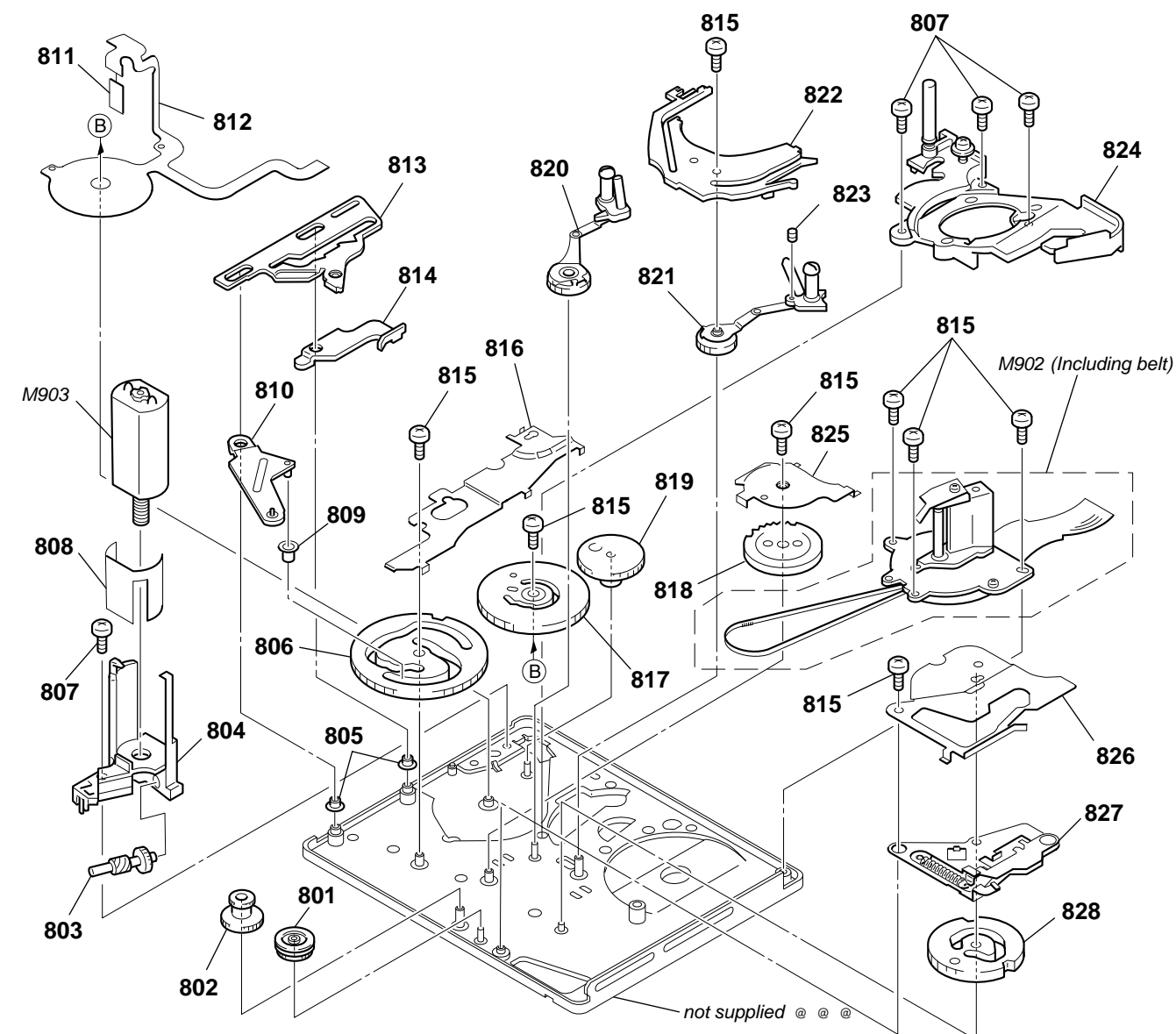
5-2. LS Chassis Block Assy



Note: FP-102 is included in the LS sub assy and is attached to chassis by hot-press.
Because installation of FP-102 requires a very high accuracy, FP-102 is not supplied as an independent service parts.

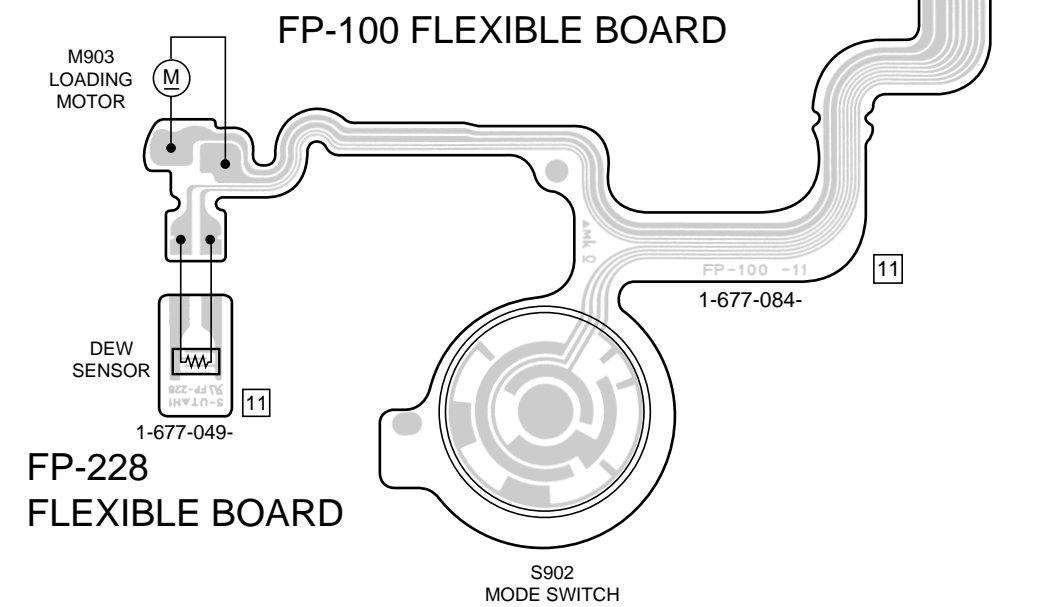
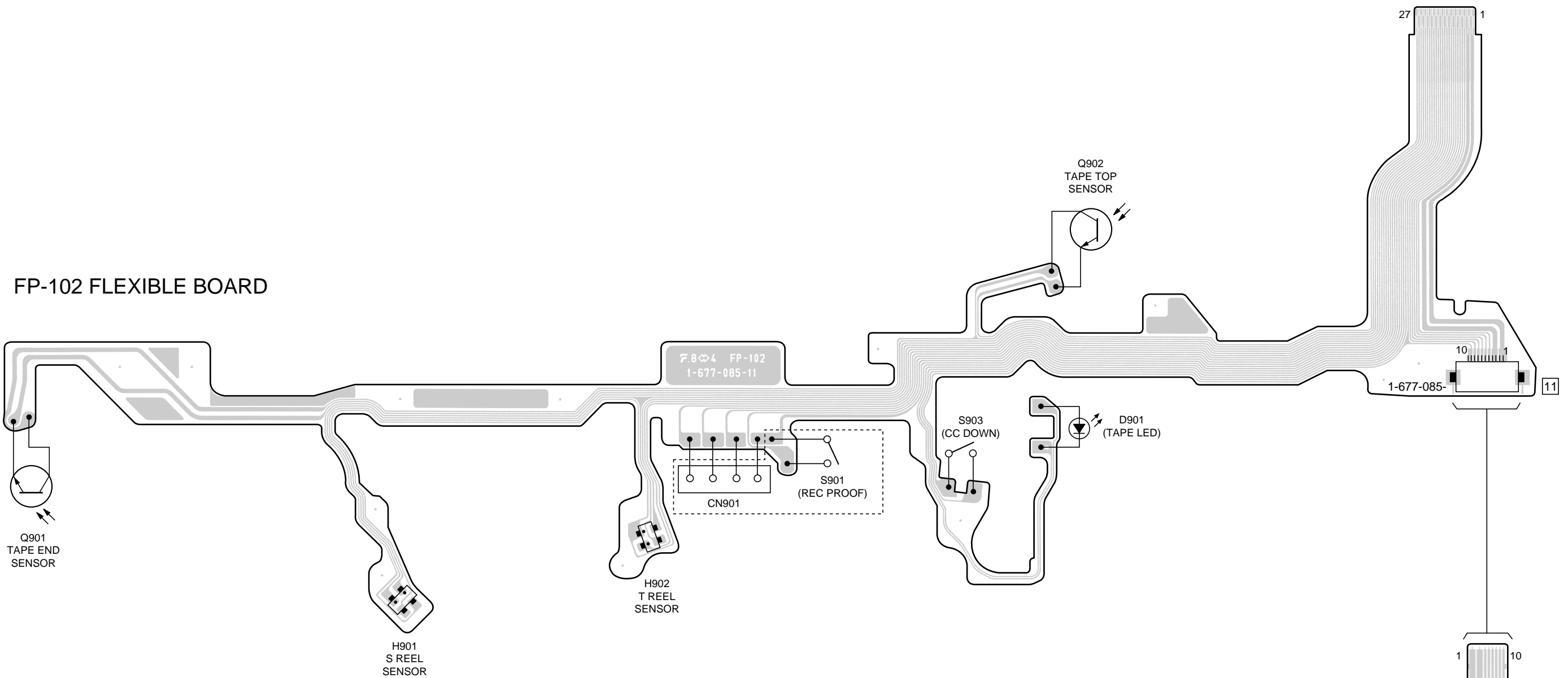
Ref. No.	Part No.	Description	Remarks	Ref. No.	Part No.	Description	Remarks
751	3-059-173-01	PLATE, LS CAM		766	3-059-093-01	RETAINER, LED	
752	3-059-100-01	SCREW (M1.4X1.4), SPECIAL HEAD		768	A-7094-819-A	TG7 BLOCK ASSY	
753	X-3950-364-1	GEAR ASSY, GOOSENECK		769	3-059-165-01	SPRING (TG7 RETURN), TORSION	
754	X-3950-371-1	ARM ASSY, BRAKE (S) DRIVING		770	X-3950-359-1	ARM ASSY, PINCH	
755	3-059-166-01	BRAKE (S)		771	3-059-161-01	SPRING (PINCH RETURN), TORSION	
756	3-059-146-01	POSITIONING (S), CASSETTE		772	3-059-170-01	BRAKE (T)	
757	3-059-167-01	SPRING (BRAKE S), TENSION COIL		773	3-059-171-01	GEAR (T), BRAKE	
758	3-059-169-01	SPRING (BRAKE S ARM), TORSION		774	3-059-172-01	SPRING (T), BRAKE	
759	3-703-816-14	SCREW (M1.4)		775	A-7094-816-A	LS BLOCK ASSY	
760	3-059-090-01	SCREW (M1.4X2.5), SPECIAL HEAD		D901	8-719-078-71	DIODE LA57A,SO (TAPE LED)	
761	X-3950-358-2	TG1 ASSY		H901	8-719-067-74	ELEMENT, HOLE HW-105A-CDE-T (S REEL)	
762	3-059-156-01	SPRING (TENSION REGULATOR)		H902	8-719-067-74	ELEMENT, HOLE HW-105A-CDE-T (T REEL)	
763	X-3950-365-2	TABLE ASSY, S REEL		Q901	8-729-028-71	TRANSISTOR PN 166, SO (TAPE END)	
764	X-3950-366-1	TABLE ASSY, T REEL		Q902	8-729-028-71	TRANSISTOR PN 166, SO (TAPE TOP)	
765	X-3950-361-1	PLATE ASSY, RETAINER		S903	1-771-326-41	SWITCH, PUSH LEVER (1 KEY) (CC DOWN)	

5-3. Mechanism Chassis Block Assy

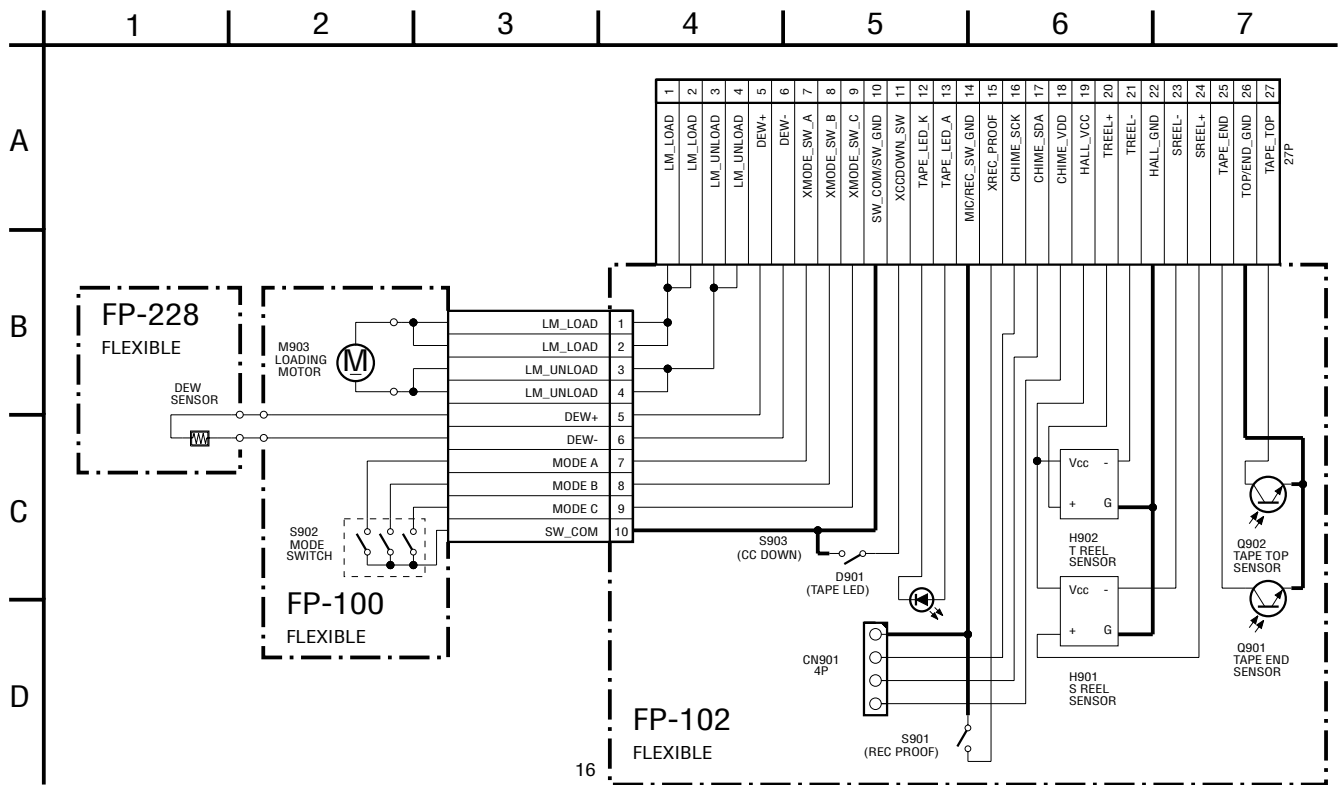


Ref. No.	Part No.	Description	Remarks	Ref. No.	Part No.	Description	Remarks
801	3-059-211-01	GEAR, CONVERSION		816	3-059-117-01	COVER (A), GEAR	
802	3-059-220-01	GEAR, RELAY		817	X-3950-367-1	GEAR ASSY, MODE	
803	3-059-187-01	SHAFT, WORM		818	3-059-139-01	GEAR, GL DRIVING	
804	3-059-186-03	HOLDER, MOTOR		819	3-059-188-01	GEAR, DECELERATION	
805	3-060-002-01	ROLLER, LS GUIDE		820	A-7094-818-A	COASTER (S) BLOCK ASSY	
806	3-059-189-01	GEAR (A), CAM		821	A-7094-817-A	COASTER (T) BLOCK ASSY	
807	3-703-816-41	SCREW (M1.4X2.5), SPECIAL HEAD		822	3-059-126-01	RAIL, GUIDE	
808	3-059-225-01	SHIELD, MOTOR		823	3-962-914-01	SCREW (M1.4X2)	
809	3-059-191-01	ROLLER, LS		824	A-7094-822-A	DRUM BASE BLOCK ASSY	
810	3-059-190-01	ARM, LS		825	3-059-118-01	COVER (B), GEAR	
811	1-677-049-11	PWB, FP-228 FLEXIBLE		826	3-059-083-01	COVER (C), GEAR	
812	1-677-084-11	PWB, FP-100 FLEXIBLE		827	X-3950-368-1	ARM ASSY, PINCH DRIVING	
813	3-059-149-01	SLIDER, TG1 CAM		828	3-059-192-01	GEAR (B), CAM	
814	3-059-148-01	ARM, TG1 DRIVING		M902	8-835-685-01	MOTOR, DC SCD18A/C-NP (INCLUDING BELT)	
815	3-703-816-14	SCREW (M1.4)		M903	A-7094-823-A	MOTOR BLOCK ASSY, L	

6. Printed Wiring Boards and Schematic Diagrams



FP-228 FLEXIBLE BOARD



7. Electrical Parts List

FP-102

Ref. No.	Part No.	Description	Remarks
		FP-102 FLEXIBLE (Not supplied)	

		(Ref.No.:6000Series)	
		< DIODE >	
D901	8-719-078-71	DIODE LN57A.S0	
		< HOLE ELEMENT >	
H901	8-719-067-74	DIODE HW-105A-CDE-T	
H902	8-719-067-74	DIODE HW-105A-CDE-T	
		< TRANSISTOR >	
Q901	8-729-028-71	TRANSISTOR PN166.S0	
Q902	8-729-028-71	TRANSISTOR PN166.S0	
		< SWITCH >	
S903	1-771-326-41	SWITCH, PUSH (1KEY) (CC DOWN)	

