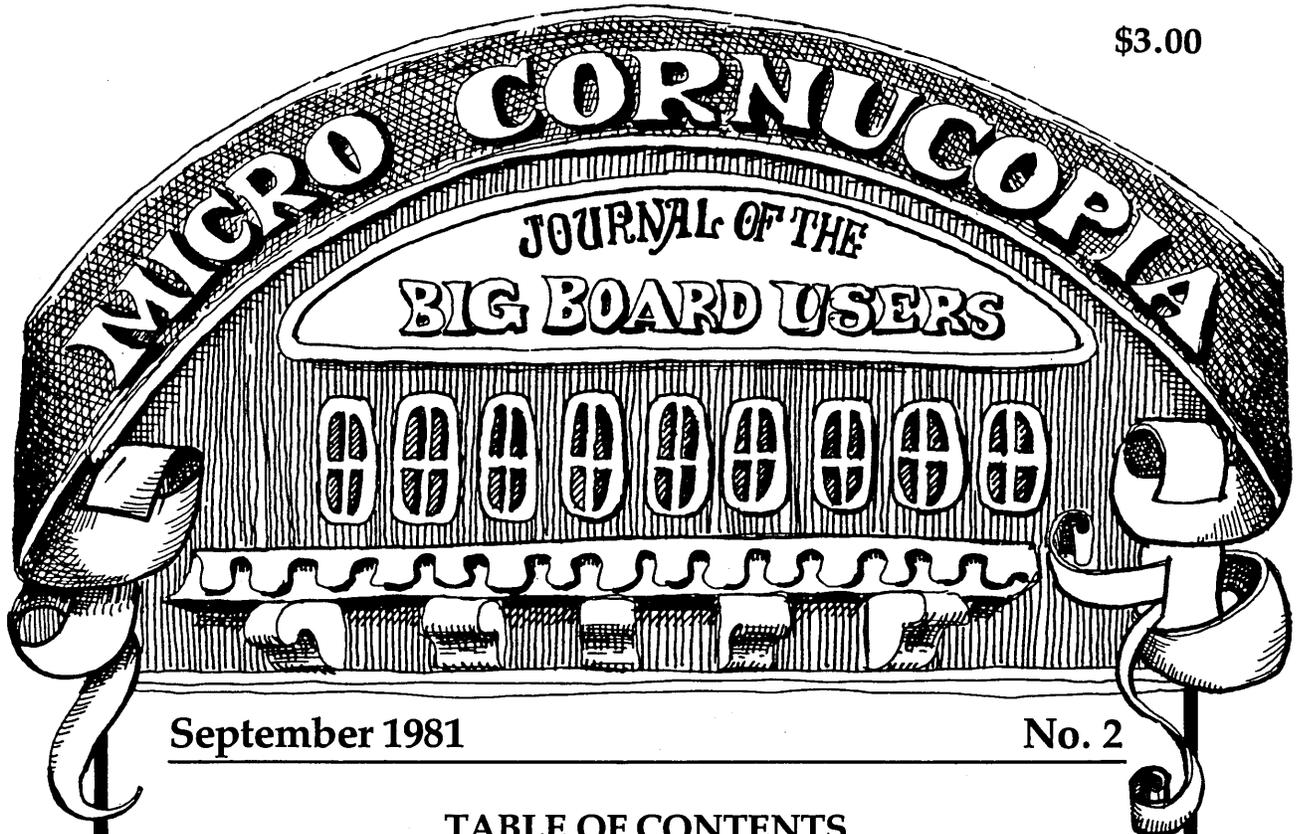


\$3.00



September 1981

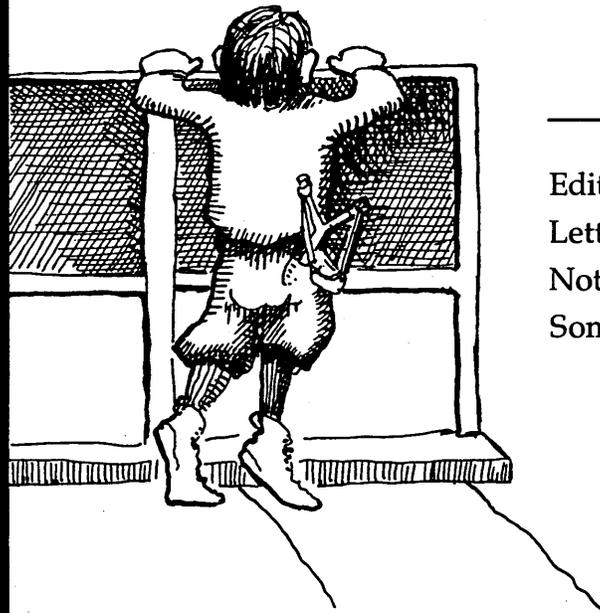
No. 2

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MICRO CORNUCOPIA

Sept. 1981

The Journal of the Big Board Users

No.2

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LETTERS TO THE EDITOR: Please sound off.

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*There once was a
Big Board so brisk.*

*It could eat all the
bits off a disk.*

*It chewed up the bits,
then spit out the pits,
which made feeding it
software a risk.*

Here We Go Again!

Exclusive!

What happens when a Xerox copies a Big Board? Why you get a "Worm", of course! That's right! The Xerox 820 is just a Big Board in disguise.

My informed sources say that last fall Xerox bought non-exclusive rights to manufacture a system based on the Big Board. Xerox re-laid out the board (4 layers) so that it would fit in the cabinet, they dedicated the SIO port B as a printer port, and they set up the disk interface (1771) to handle either 5 or 8 inch. Otherwise, it appears to be all Big Board, right down to the 2.5 MHz clock. The system PIO does the same things on both systems, bit for bit, according to Xerox's documentation.

Xerox had 50,000 orders in hand the day they shipped the first 820, and they expect to recoup all their startup costs by the end of this calendar year. What a market for software and hardware developed around the Big Board. I'll say more about the 820 as information comes in. (I'd give my eye teeth to see a schematic and service manual for the 820.)

Picnic

We had a Saturday noon picnic to celebrate our first issue. It turned out that the Saturday we picked conflicted with every party/birthday/outing/etc. for three states around. But Sandy and I and those who came had six hours of very interesting and mellow conversation.

The knowledge, resources, and excitement among the local group members are terrific. I only wish all of you could have joined us.

The First Issue

Despite the speed of the U.S. Snail, a heartening number of readers have actually received issue no. 1. The responses from these lucky folks have made the daily trip out to our mailbox most enjoyable. The comments have included; 'surprised, happy, delighted'.

Though Micro C is a long way from being a success financially, feedback like this tells us that it is successful in other ways. We like doing it and we really appreciate your response.

Sometimes a dream generates momentum of its own. This one has.

Thanks.

David Thompson
Editor & Publisher

Letters

Dear Sir,

July came and July went by, and my mailbox has completely rusted out due to all that drooling.

Silly me! When I read 'Issue No. 1 will hit the streets during July' I assumed it was July 1981! But now I realize you meant July 1982. I'd better get a stainless steel mailbox or maybe not bother to wait, because the magazine will never get here.

Maybe it went the way of Mitt's Newsletter, the Digital Group Newsletter, and Processor Technology's "Access."

I hope not.

Joe Kish

758 Yucca Ridge Lane
San Marcos, CA 92069

Editor's note:

I called Joe; after all it was the least I could do for his mailbox. And besides, I think it's a great letter! (He did finally receive issue no. 1.)

Sandy and I made a desperate, last ditch effort to get all 500 first issues collated, bound, labeled, sorted and bundled in one afternoon so we could get the first issue in the mail on July 31. We missed the 8 PM deadline at the post office by 15 minutes.

So the magazine was mailed Monday morning, August 3rd. (So much for hitting the streets in July.)

Someday maybe I'll write a book about starting a users group magazine. I could almost write the book about the first issue, and Murphy would certainly be a leading figure. (For those of you who don't know Murphy, he is the one credited with the first voyage of the Titanic.)

Quote from Murphy:

**If there is no way
your plan can fail,
you simply don't have
all the information.**

Dear Editor,

I bought a bare board version and built it up from scratch. I had to buy about \$80.00 worth of parts beyond what I had around. I have it up and running CP/M and am currently working on packaging it in a terminal-type case with a Ball Brothers CRT. The unit is going to be used for text processing and formatting for a friend's photo typesetter. My other computer is an LSI-11 and I also use

(continued next column)

Supporting A Language

By David Thompson

Throughout these early months of Micro Cornucopia, I have been looking at commercial and public versions of various languages with the hope of finding a semiofficial language for this group.

A common high level language would mean we could pass around source code in something other than assembler. But the language would need to be powerful enough for substantial commercial applications and inexpensive enough that most of the people in the group could afford it.

Letters continued

my H19 with the DEC-20 at work. I think the Big Board is an excellent value and very useful.

I agree that Frank Gentges' idea about the parallel ports is excellent. That would take care of most of the board's limitations. I think your publication has already been worth the price and I suspect that an active users group with a publication will enhance the usefulness of the hardware significantly.

Doug Faunt
PO Box 11142A
Palo Alto CA 94306

Dear David,

CONGRATULATIONS!!! FANTASTIC!!! You really made it. It looks great and reads great. You are certainly to be congratulated for undertaking such a task that should be helpful to so many.

I hate to mention that Momma and I are just back from five weeks vacation in the Smokey Mountains in Tennessee. I am about ready to get my feet on the ground again. I hope that I can get back on track to help keep the pipe full of articles for future issues.

Don Retzlaff
6435 Northwood
Dallas TX 75225

Editor's note,

What can I say? Thanks again Don, without you and John Jones and Andrew Beck, and the rest of you who are writing up things for future issues this wouldn't be possible. (As for the five whole weeks in the Smokey Mountains, that's just not fair.)

Plus, it would need to produce fast and compact object code, encourage readable source code, and promote structured programming. (Whew!)

I am looking seriously at three languages: Forth, Pascal, and C. Of these three, C is presently leading. One reason is that all the versions I have seen have been upwardly compatible with Bell Lab's C.

Versions of C that I'm aware of:

Small C (Public)
Small C+ (Public)
Tiny C (\$100)
CW/C (\$75)
BDSC (\$145)
Supersoft C (\$200)
Whitesmith's C (\$600)

(The prices are approximate.)

Whitesmith's C is a full blown version of the language. In fact, sources tell me that it was created by three fellows who worked on C for Bell Labs. They left Bell in order to develop and market C for the business and scientific community.

I've heard that BDSC is a competent enough subset to be an option for someone writing commercial applications. It has its own users group and publication. All this for \$145, such a deal. (Lifeboat is offering discounts on quantity purchases of BDSC.)

CW/C is an expanded version of Small C with lots of nice utilities, but I don't know if it is ready to do commercial work. However, it still looks like quite a bargain at \$75.

Tiny C is the only interpreter in the bunch. It also comes in compiler form for about \$300. The only thing I have heard about Tiny C is that it has an excellent manual (and I heard that fourth or fifth hand).

Supersoft's C is new on the market. The ads say that they support 'most' of version 7 Unix. If that includes floating point and pointer arithmetic, then it would be a very credible piece of software, assuming they have taken time to exorcise bugs.

The standard text on C is:

"The C Programming Language"
by Kernighan and Ritchie
Prentice-Hall

Disk Drive Motor Control

By David Thompson

CP/M patch for serial printer port.

This CP/M modification redirects the list device output to serial port B. The default data rate is 300 baud. This patch does not force the Big Board to poll any of the handshake lines on port B. Thus, it has no way of knowing if the printer buffer is full. (May or may not be a problem.) This modification is for those who ORG at E800.

Enter the characters inside the quotation marks. <CR> = carriage return.

The patch:

1. Power up the Big Board (BB).
2. Place a CP/M disk with SYSGEN on it, in drive A.
3. Boot CP/M.
4. Enter "SYSGEN" "<CR>"
Displays: SYSGEN VER. 2.0
Displays: SOURCE DRIVE NAME...
5. Enter "A"
Displays: SOURCE ON A, THEN TYPE RETURN
6. Enter "<CR>"
Displays: FUNCTION COMPLETE...
7. Hit the BB RESET switch <CR>

NOTE: You now have an image of Boot, CP/M, and Bios in RAM starting at 0900H.

8. Remove the source disk from drive A.
9. Enter "M22C7" "<CR>"
Displays: 22C7 00
10. Enter "79"
11. Enter "C3"
12. Enter "18"
13. Enter "F0"
14. Hit spacebar to return to PFM.
15. Enter "M1F90" "<CR>"
16. Enter "47"
17. Enter "EB"
18. Hit spacebar to return to PFM.
19. Place blank disk in drive A.
20. Enter "G100"
Displays: SYSGEN VER 2.0
21. Enter "<CR>"
Displays: DESTINATION DRIVE...
22. Enter "A"
Displays: DESTINATION ON A...

23. Enter "<CR>"
Displays: FUNCTION COMPLETE...
24. Enter "<CR>"

The disk now contains a CP/M system that supports CONTROL P (and PIP LST:=) for listings. As mentioned above, the output is on serial port B and is 300 baud.

Editor's note:

To change the baud rate, create F.COM as follows:

1. Enter "DDT" "<CR>"
2. Enter "A100" "<CR>"
3. Enter "MVI A,XX" "<CR>"
4. Enter "OUT 0C" "<CR>"
5. Enter "JMP 0" "<CR>"
6. Enter "<CR>"
7. Enter "G00" "<CR>"
8. Enter "SAVE 1 F.COM" "<CR>"

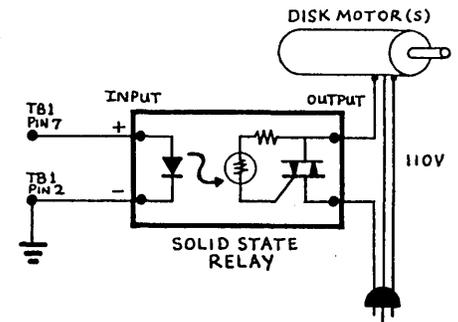
This routine sends a single byte (XX) to the channel B baud rate generator. I am working at 9600 baud so I replace XX with 0E. See the Big Board Theory of Operation for other baud rates.

Once you have completed the baud rate program, simply enter "F" "<CR>" from the CP/M prompt to set the baud rate.

No UPS to a PO Box?

Jim Tanner lists his mailing address as a PO Box but he also has a street address that works for both the post office and United Parcel Service. (The ZIP is different.)

Jim Tanner
Digital Research Computers
2702 Industrial Lane
Suite J2
Garland, Texas 75041
Phone 214-271-3538



Disk AC Control Circuit.

If you're tired of listening to your disk drives grind on hour after hour, here's relief.

The board must have the timer option installed and you must jumper pin 3 to pin 4 and pin 7 to pin 8 on JB2. This supplies the one second interrupt to the Z80. If the Z80 counts all the way to 30 after the most recent disk access then it sends a command to the system PIO to drive the output of U112 pin 2 low.

Terminal 7 on the Big Board power connector is tied to U112 pin 2. This terminal is high (about 4V) when the system is doing a disk access and goes low if there hasn't been an access for 30 seconds.

Simply connect the input of an optically isolated solid state relay between terminal 7 and ground. Then connect the output in series with the AC to the disk drive motors. (But do not connect in series with the drives' DC supply.)

I tried mechanical relays at first, but even the type made to be driven by TTL have problems. Whenever you use mechanical switches to start and stop motors you get interesting transients on the AC line. Interesting transients occasionally cause CPUs to go off picking daisies.

I am now using an ITT solid state relay P6-3DCC-120R5. It has a (P6) package, a 3VDC (3D) input, a 120VAC output with random switching point (120R), and it handles up to (5) amps. It is also small, quiet, and hasn't yet sent the system packing.



Jumpering The Wild Shugart

By David Thompson

Shugart set a new standard for obscurity when they came out with their SA 801 user's manual.

It's not that they don't tell you how to jumper their drives, the only problem is figuring out what they told you. Once you figure it out, don't go back and look at the manual, you'll just get confused again.

So on that note, here's what I figured out.

For drive A, jumper only the following: DC, C, DS1 (Drive Select 1), T2, T3, T4, T5, T6, HL, A, B, T1, 800, Y.

For drive B, change DS1 to DS2. For drive C, change DS1 to DS3, and so on.

For the last 9 months or so, Shugart has been shipping drives with a new circuit board. The new board is completely interchangeable with the old one, but the new one does not use the -5/-15V pin on the DC supply jack (J5). The pin is there but is not connected to anything because the new board does not need -5V.

One way to tell whether you have a new or old style drive is to check the bottom left hand corner on the circuit board. The old drive has a -5V regulator there. On the new one, that corner is pretty empty. Also, the resistance from the -5V pin to ground is infinite on the new boards.

I had one of the new boards but the old documentation so I spent a couple of 'interesting' evenings trying to make sure the -12V I was supplying would be properly turned in-

to -5V on the board. (Oh well, if everyone's documentation were perfect there probably wouldn't be so much need for user groups.)

Note: The following information is from Bill Klevesahl, Shugart's product manager for the SA 800 series.

Test points for both boards.

- 1,2 Amplified read signal
- 5,6,7 Ground
- 10 -Index
- 11 +Head Load
- 12 -Index and Sector Pulses
- 16 +Read Data
- 25 +Write Protect
- 26 +Detect Track 0
- 27 +Step Pulse

Test points on the old board only.

- 3,4 Differential Read Signal (this signal is now hidden inside the new LSI read chip).
- 21,24 -Data Separator Timing (there is no longer a pot to adjust this).

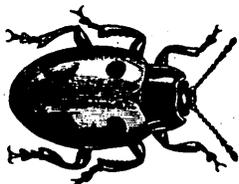
Test points on the new board only.

- 8 +Data Window (for checking FM data separation).

Optional features on the new board.

- Add-trace option TS enables true FM data separation, maintaining synchronization during address marks.
- Add-trace option NFO prevents the head from being forced out past track 0.

BUG



The formatting program listed in issue 1 contains a bug. If the program has a problem accessing a disk in drive B, it reformats the disk in the default drive (A).

Issue 3 will include a revised format program.

Coming Up

Articles you'll be seeing in the future.

- Reverse video cursor
- 5 inch disk interface
- Real time clock routine
- Converting a TV into a real video monitor
- More on the PFM monitor
- Review of 3 assembly language texts
- Bios modifications

Articles we'd love to see.

- Trials and tribulations of bringing up a Big Board
- How you've improved the PFM monitor
- Hard disk interface
- Filling out the second bank with system RAM
- DMA interface
- Double density disk interface
- A graphics display
- A speech generator
- A simple ROM burner
- Interfacing with particular printers etc.
- An in-depth series on CP/M
- Reviews of FIG Forth and Forth 79
- Reviews of BDSC, Whitesmith's C, CW/C and Super-soft's C
- Computer consulting using a Big Board
- Reviews on peripherals, keyboard, video monitor, power supply, cabinet, disks, etc.
- Other software reviews. Even if you are just borrowing a copy to evaluate, please let us know how you like it.
- Book reviews

If you are immersed in any of these projects, please share your experience with all of us.



Direct Input Routine

By Andrew P. Beck

AB Computer Products
PO Box 571
Jackson, NJ 08527

Assembly Listing

```

F800  E5      SUBR    PUSH HL      ;SAVE ADDRESS OF HL%
F801  CD06F0 CALL KBDST ;GET KBD STATUS
F804  B7      OR A      ;IF A=0 DATA AVAILABLE
F805  CA0EF8 JP Z ISDATA ;JP TO DATA SAVE ROUTINE
F808  E1      POP HL     ;GET ADDRESS BACK
F809  3C      INC A      ;A=FF IS NO DATA, MAKE IT 0
F80A  77      LD (HL),A   ;STORE 0 IN HL%
F80B  23      INC HL     ;DO BOTH BYTES
F80C  77      LD (HL),A   ;
F80D  C9      RET        ;RETURN WITH HL% = 0
F80E  CD09F0 ISDATA CALL KBDIN ;GET INPUT CHAR INTO A
F811  E1      POP HL     ;GET ADDRESS OF HL% BACK
F812  77      LD (HL),A   ;STORE DATA, LOW ORDER
F813  23      INC HL     ;
F814  3600   LD (HL),0   ;HIGH ORDER = 0
F816  C9      RET        ;RETURN TO BASIC
    
```

-- Poke the above program into F800+ --

```

500 SUBR = &HF800
510 DATA &HE5, &HCD, &H06, &HF0, &HB7, &HCA, &HOE, &HFB
520 DATA &HE1, &H3C, &H77, &H23, &H77, &HC9, &HCD, &HO9, &HFO
530 DATA &HE1, &H77, &H23, &H36, &H00, &HC9
540 FOR I=0 TO 22
550 READ INST
560 POKE SUBR+I, INST
570 NEXT
    
```

-- Demonstration routine --

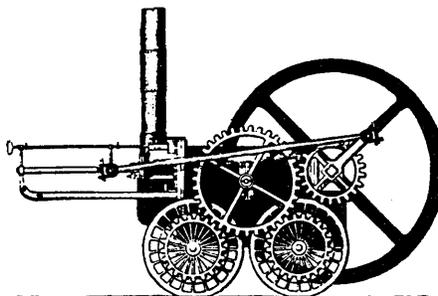
```

580 HL%=0
590 CALL SUBR (HL%)
600 IF HL%=0 GOTO 590
610 IF HL%=3 THEN STOP
620 PRINT CHR$(HL%);
630 GOTO 590
    
```

This routine makes it possible to do direct input with Microsoft basic. First, a machine language subroutine is poked into an unused area of the system monitor.

This subroutine calls the monitor subroutine and the monitor checks to see if an input character is available. If none is available, the HL% is set to zero. If a character is available, it is stored in HL% before a return is executed.

In the demonstration program, a returned character is echoed on the console. If the character is ^C, the demonstration stops.



More Power Supplies

By David Thompson

I just received a catalog from ACDC Electronics and they list a power supply that should power the Big Board and a couple of drives. (Like the Power One, you still have to finagle +12V but that isn't hard, see Issue no. 1.)

Model ETV801 provides:

- +5V at 9 amps
- 12V at 0.8 amps
- +24V at 4.5 amps peak

Price is \$132 (list, single)

They don't mention how they handle over-current protection, but they do indicate that they only have over-voltage protection on the +5V line unless you specify the -1 option. They don't say how much extra you pay for the option.

ACDC Electronics
401 Jones Rd
Oceanside, CA 92054

Power/Mate also has an open frame linear with the same specifications as the ACDC model above, but the PowerMate model ED-132AV lists for \$120 (single).

Power/Mate
514 S River St
Hackensack, NJ 07601



Something New

DataCast
345 Swett Road
Woodside, CA 94062

I just received issue no. 1 of DataCast and I'm impressed, very impressed. This is a bimonthly magazine for 'major micro systems and telecommunications.' 'Major micro systems' means CP/M in a business or OEM environment and 'telecommunications' means networking.

Jim Warren, guiding force behind the West Coast Computer Faire, is behind this magazine and I suspect it will be around for a long while. Subscriptions are \$18 per year (6 issues).

He is starting with a staff of 19 (if you include the mascot, Sir Lick-A-Lot) and it shows. The first issue is

64 pages and about 60 pages of that is copy.

Some first issue articles:

- What is Telidon and Why is AT&T Adopting It?
- Overview of Home Information Services
- A Seminar for Independent CP/M Software Vendors
- Software Documentation Protocols
- An Index to CP/M Software and Vendors

Other Interesting Periodicals

Dr. Dobb's Journal
PO Box E
Menlo Park, CA 94025

Lifelines
1651 Third Ave
New York, NY 10028

Please let us know about your favorite magazines.

Program Storage Above PFM

By Don Retzlaff

6435 Northwood
Dallas, TX 75225

There are numerous times when you want to write a small assembly language program to use as a printer driver or other routine. These small utilities need to reside in high memory so they can operate at the same time as routines which reside in the normal transient program area (starting at 0100H).

Since programs are loaded starting at 0100H, these utilities must load themselves into high memory.

There is a considerable amount of memory available above PFM that is not dedicated to any other use. PFM version 3.3 uses upper memory starting at F000H through F7E6H. The RAM area FF00H through FFC8H is used for data storage. This leaves the memory from F7E7H through FEFFH and FFC9H through FFFFH available for your use. Not all of this space is really available since future releases of PFM could use some of this space.

I recommend that you limit your programs to the following areas: (FA00H through FEFFH and FFE0H through FFFFH).

Moving the program up

In order for your routine to start out as a normal COM file but wind up in upper memory, it has to do a quick shuffle.

1. When the COM file is executed it is loaded into memory starting at 0100H.
2. Execution starts at 0100H.
3. The first few statements (starting at 0100H) must copy the routine into upper memory.
4. An initialization routine may then be executed.
5. Control is then transferred to the routine or back to PFM.

In order to accomplish all of the above it is necessary to do the following:

1. Write your assembly language routine as follows:
 - a. The origin is set at the desired point where your routine is to reside.
 - b. Your program must start with a short move routine.

- c. An initialize routine usually follows that patches (hooks) your routine into the monitor or PFM.
- d. Your routine follows.
- e. The last statement defines the length of the program.

2. Assemble your program.
3. Execute DDT and load your HEX file into memory. Typically this is done as follows:

>A.DDT NAME.HEX

This will load your program into memory at the desired location (example EA00H). The program will not execute.

DDT will print out starting and ending addresses.

NEXT PC/n
FAxx FA00

4. Using DDT, move the program from upper memory to 0100H.
MFA00,FAxx,0100
5. Transfer control back to PFM by typing:
G0
6. Save the program using the SAVE command.

SAVE 1 NAME.COM

You must save the program in 256 byte blocks. Using '1' will save 256 bytes, '2' would save 512 bytes, etc.

7. The program is now ready for execution as a COM file.

The above procedure may seem long and rather involved but after you have done it a few times you will find it very quick and simple.



PFM Monitor Listing (continued from issue no. 1)

F37B	C0	0745	NZ	!ERROR IF > 4 NUMBERS ENTERED	0822	ADD	A, 90H
F37C	C5	0746	BC	!SAVE PARAMETER COUNT	0823	DAA	A, 40H
F37D	CD9FF3	0747	GETHEX	!READ A NUMBER FROM LINE BUFFER	0824	ADC	OUTPUT
F380	C1	0748	BC		0825	DAA	
F381	DB	0749	BC		0826	JP	
F382	DD217CFF	0750	C	!ERROR IF RESULT OVER 16 BITS	0827		
F386	DD09	0751	IX,PARAM1	!POINT TO PARAM STORAGE AREA	0828		
F38B	DD7500	0752	IX,BC	!ADD PARAMETER COUNT IN BC	0829		
F38B	DD7401	0753	(IX+0),L	!STORE DATA RET FROM 'GETHEX'	0830		
F38E	FE20	0754	(IX+1),H		0831		
F390	2BE4	0755	,		0832		
F392	FE2C	0756	,		0833	EGU	04H
F394	2BE0	0757	Z,PARA1-\$!GET ANOTHER ITEM IF SPACE	0834	EGU	0DH
F396	FE0D	0758	Z,PARA1-\$!GET ANOTHER ITEM IF COMMA	0835	EGU	04H
F398	37	0759	CR	!ELSE CHECK FOR CARRIAGE RETURN	0836		
F399	C0	0760	NZ	!AND EXIT WITH CY=1 IF NOT	0837		
F39A	79	0761	A,C		0838	PNEXT:	(SP),HL
					0839	CALL	PMSG
					0840	EX	(SP),HL

```

F39B CB3F 0762 SRL A ;A=COUNT OF NUMBERS ENTERED
F39D 3C 0763 INC A
F39E C9 0764 RET
0765 ;
0766 ;GETHEX CONVERTS ASCII TO BINARY AND DOES
0767 ;HIGH LIMIT CHECKS TO LESS THAN 17 BITS.
0768 ;CARRY SET ON ILLEGAL CONVERSION RESULT
0769 ;TERMINATING CHARACTER RETURNS IN A.
0770 ;HL RETURNS WITH 16 BIT BINARY INTEGER
0771 ;
F39F 210000 0772 GETHEX: LD HL,0
F3A2 180B 0773 JR GNUM3-#
0774
F3A4 0604 0775 GNUM1: LD B,4
F3A6 29 0776 GNUM2: ADD HL,HL ;MULTIPLY RESULT BY 16
F3A7 DB 0777 RET C ;RETURN IF IT OVERFLOWS 16 BITS
F3A8 10FC 0778 DJNZ GNUM2-#
F3AA 5F 0779 LD E,A ;APPEND NEW LOW ORDER DIGIT
F3AB 1600 0780 LD D,0 ;AND GET RESULT BACK INTO DE
F3AD 19 0781 ADD HL,DE
F3AE DB 0782 RET C ;RETURN IF OVERFLOW
F3AF FD7E00 0783 GNUM3: LD A,(IY+0) ;GET A CHAR FROM LINE INPUT
F3B2 FD23 0784 INC IY ; BUFFER @ IY AND BUMP IY
F3B4 4F 0785 LD C,A
F3B5 CDBDF3 0786 CALL ASCHEX ;CONVERT ASCII TO NUMERIC
F3BB 30EA 0787 JR NC,GNUM1-#
F3BA 79 0788 LD A,C
F3BB B7 0789 OR A
F3BC C9 0790 RET
0791 ;
0792 ;
F3BD D630 0793 ASCHEX: SUB '0'
F3BF DB 0794 RET C
F3C0 FE0A 0795 CP 10
F3C2 3F 0796 CCF
F3C3 D0 0797 RET NC
F3C4 D607 0798 SUB 7
F3C6 FE0A 0799 CP 10
F3C8 DB 0800 RET C
F3C9 FE10 0801 CP 16
F3CB 3F 0802 CCF
F3CC C9 0803 RET
0804 ;
0805 ;
0806 ;
F3CD 7C 0807 PUT4HS: LD A,H
F3CE CDDBF3 0808 CALL PUT2HX
F3D1 7D 0809 LD A,L
F3D2 CDDBF3 0810 PUT2HS: CALL PUT2HX
F3D5 C302F4 0811 JP SPACE
0812 ;
0813 ;
F3D8 F5 0814 PUT2HX: PUSH AF
F3D9 1F 0815 RRA
F3DA 1F 0816 RRA
F3DB 1F 0817 RRA
F3DC 1F 0818 RRA
F3DD CDE1F3 0819 CALL PUTNIB
F3E0 F1 0820 PDP AF
F3E1 E60F 0821 PUTNIB: AND 00001111B

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F3F1 C9 0841 RET
0842 ;
F3F2 7E 0843 PMSG: LD A,(HL)
F3F3 23 0844 INC HL
F3F4 FE04 0845 CP EOT
F3F6 C8 0846 RET Z
F3F7 CD15F4 0847 CALL OUTPUT
F3FA 18F6 0848 JR PMSG-#
0849 ;
0850 ;
0851 ;CRLFS OUTPUTS A RETURN-LINEFEED-SPACE
0852 ;TO THE CONSOLE DEVICE
0853 ;
F3FC CDECF3 0854 CRLFS: CALL PNEXT
F3FF 0D0A04 0855 DEFB CR,LF,EOT
F402 3E20 0856 SPACE: LD A,' '
F404 C315F4 0857 JP OUTPUT
0858 ;
0859 ;
0860 ;
0861 ;ECHO INPUTS ONE CHARACTER FROM THE CONSOLE
0862 ;DEVICE, PRINTS IT ON THE CONSOLE OUTPUT AND
0863 ;THEN RETURNS IT IN REGISTER A WITH BIT 7 RESET
0864 ;
0865 ;OUTPUT PRINTS THE CHARACTER IN REGISTER A ON
0866 ;THE CONSOLE OUTPUT DEVICE AND THEN DOES A CHECK
0867 ;FOR CONSOLE INPUT TO FREEZE OR ABORT OUTPUT.
0868 ;
0869 ;
F407 CD09F0 0870 ECHO: CALL CONIN ;INPUT A CHARACTER AND ECHO IT
F40A F5 0871 PUSH AF
F40B CD0CF0 0872 CALL CONOUT
F40E F1 0873 POP AF
F40F FE5B 0874 CP 'Z'+1
F411 DB 0875 RET C
F412 D620 0876 SUB 32 ;CONVERT UPPER CASE TO LOWER
F414 C9 0877 RET
0878 ;
0879 ;
0880 ;
F415 CD0CF0 0881 OUTPUT: CALL CONOUT
F418 CD06F0 0882 CALL CONST ;SEE IF CONSOLE INPUT PENDING
F41B 280F 0883 JR Z,OUTP2-#
F41D CD09F0 0884 CALL CONIN
F420 FE0D 0885 CP CR ;SEE IF <CR> WAS TYPED
F422 2805 0886 JR Z,OUTP1-#
F424 CD09F0 0887 CALL CONIN ;WAIT FOR ANOTHER INPUT CHAR
F427 1803 0888 JR OUTP2-# ; THEN RET TO CALLING ROUTINE
0889 ;
F429 32B4FF 0890 OUTP1: LD (ESCFLG),A ;SET ESC FLAG TO NON-ZERO VALUE
F42C 3A84FF 0891 OUTP2: LD A,(ESCFLG)
F42F B7 0892 OR A ;RETURN CURRENT STATUS OF ESC
F430 C9 0893 RET ; FLAG TO CALLING ROUTINE
0894 ;
0895 ;
0896 ;
0897 INCLUDE INTRSV.ASM

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PFM Monitor Listing (continued)

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0898 ;*****
0899 ;*
0900 ;*      INTERRUPT SERVICE ROUTINES FOR KEYBOARD      *
0901 ;*      INPUT AND REAL-TIME CLOCK FUNCTIONS          *
0902 ;*                      3-Aug-80                      *
0903 ;*
0904 ;*****
0905 ;
0906 ;
0907 ;
0908 ;
F431 3A30FF 0909 KBDST: LD      A,(FIFCNT) ;GET INPUT FIFO BYTECOUNT
F434 B7      0910      OR      A          ;TEST IF EQUAL ZERO
F435 CB      0911      RET     Z          ;EXIT WITH A=0 IF QUEUE EMPTY
F436 3EFF    0912      LD      A,255
F438 C9      0913      RET     ;ELSE A=255 INDICATES DATA RDY
0914 ;
0915 ;
0916 ;
F439 CD31F4 0917 KBDIN: CALL   KBDST
F43C 28FB    0918      JR      Z,KBDIN-$ ;LOOP UNTIL KEYBOARD INPUT RDY
F43E E5      0919      PUSH   HL
F43F CD6DF4 0920      CALL   REMOVE ;GET CHARACTER FROM INPUT QUEUE
F442 E1      0921      POP    HL
F443 C9      0922      RET
0923 ;
0924 ;
0925 ;
0926 ;
0927 ;
F444 2133FF 0928 STASH: LD      HL,LOCK ;POINT TO SHIFT LOCK VARIABLES
F447 BE      0929      CP      (HL) ;TEST IF A=SHIFT LOCK CHARACTER
F448 23      0930      INC    HL ;THEN POINT TO LOCK FLAG
F449 2002    0931      JR      NZ,STASH2-$ ;JUMP IF NOT SHIFT CHARACTER
F44B 34      0932      INC    (HL) ;ELSE COMPLIMENT THE SHIFT LOCK
F44C C9      0933      RET     ;AND EXIT NOW
0934 ;
F44D CB46    0935 STASH2: BIT   0,(HL) ;TEST THE SHIFT LOCK FLAG
F44F 280A    0936      JR      Z,STASH3-$ ;JUMP IF SHIFT LOCK NOT SET
F451 FE40    0937      CP      40H ;ELSE CHECK FOR SHIFTABLE CHAR
F453 3806    0938      JR      C,STASH3-$ ;AND JUMP IF NOT = OR GREATER
F455 FE7F    0939      CP      7FH ;THAN '0' AND LESS THAN RUBOUT
F457 3002    0940      JR      NC,STASH3-$
F459 EE20    0941      XOR    00100000B ;ELSE TOGGLE BIT 5 OF THE CHAR
F45B 4F      0942 STASH3: LD      C,A
F45C 2130FF 0943      LD      HL,FIFCNT ;BUMP INPUT FIFO CHAR COUNT
F45F 7E      0944      LD      A,(HL)
F460 3C      0945      INC    A
F461 FE10    0946      CP      16
F463 D0      0947      RET     NC ;EXIT NOW IF FIFO IS FULL
F464 77      0948      LD      (HL),A ;ELSE INCREMENT FIFO COUNT
F465 2131FF 0949      LD      HL,FIFIN ;POINT HL TO FIFO INPUT OFFSET
F468 CD74F4 0950      CALL   INDEX
F46B 71      0951      LD      (HL),C ;STORE CHARACTER IN FIFO @ HL
F46C C9      0952      RET
0953 ;
0954 ;
0955 ;
0956 ;

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F4C1 CDE7F4 1021 DSPTCH: CALL   CALLHL ;CALL SUBROUTINE ADDRESSED BY H
F4C4 F1      1022      POP    'AF
F4C5 C1      1023      POP    BC
F4C6 D1      1024      POP    DE
F4C7 E1      1025      POP    HL
F4C8 ED7B35FF 1026      LD      SP,(SPSAVE)
F4CC FB      1027      EI      ;RE-ENABLE INTERRUPTS & RETURN
F4CD ED4D    1028      RETI
1029 ;
1030 ;
1031 ;
1032 ;
1033 ;ARRIVE HERE IF RECEIVE INTERRUPT FROM FRAMING, OVERRUN
1034 ;AND PARITY ERRORS. (PARITY CAN BE DISABLED)
1035 ;
F4CF ED7335FF 1036 SIOERR: LD      (SPSAVE),SP ;SAVE USER STACK POINTER AND
F4D3 3157FF 1037      LD      SP,TMPSTK+32 ; SWITCH TO LOCAL STACK
F4D6 F5      1038      PUSH   AF
F4D7 CDF5F4 1039      CALL   SIOIN2 ;CLEAR BAD CHARACTER FROM SIO
F4DA 3E07    1040      LD      A,'G'-64
F4DC CD15F5 1041      CALL   SIOXMT ;OUTPUT A CTL-G AS A WARNING
F4DF F1      1042      POP    AF
F4E0 ED7B35FF 1043      LD      SP,(SPSAVE)
F4E4 FB      1044      EI
F4E5 ED4D    1045      RETI
1046 ;
1047 ;
1048 ;
F4E7 E9      1048 CALLHL: JP      (HL)
1049 ;
1050 ;
1051 ;
1052 ;POLLED MODE I/O ROUTINES FOR SIO CHANEL B
1053 ;
F4E8 DB07    1054 SIOST: IN      A,(SIOCPB) ;GET SIO STATUS REGISTER
F4EA E601    1055      AND    00000001B
F4EC CB      1056      RET     Z ;ACC=0 IF NO DATA AVAILABLE
F4ED 3EFF    1057      LD      A,255
F4EF C9      1058      RET
1059 ;
1060 ;
F4F0 CDE8F4 1061 SIOIN: CALL   SIOST ;TEST CONSOLE STATUS
F4F3 28FB    1062      JR      Z,SIOIN-$ ;LOOP UNTIL DATA IS RECEIVED
F4F5 3E30    1063 SIOIN2: LD      A,00110000B ;RESET STATUS BITS IN SIO FO
F4F7 D307    1064      OUT    (SIOCPB),A ;PARITY/OVERRUN/FRAMING ERRORS,
F4F9 DB05    1065      IN      A,(SIOCPB) ;THEN GET THE INPUT CHARACTER
F4FB E67F    1066      AND    01111111B
F4FD C9      1067      RET
1068 ;
1069 ;
F4FE FE20    1070 SIOOUT: CP      ' ' ;TEST FOR CONTROL CHARACTERS
F500 3013    1071      JR      NC,SIOXMT-$ ;JUMP IF PRINTABLE CHARACTER
F502 CD15F5 1072      CALL   SIOXMT ;ELSE SEND CONTROL CHARACTER
F505 3A79FF 1073      LD      A,(NULLS) ;AND THEN SEND NULLS AS PADDING
F508 3C      1074      INC    A ;GET NULL PAD COUNT AND FIX SO
F509 1806    1075      JR      PAD1-$ ;THAT COUNT=0 SENDS NO NULLS
1076 ;
F50B F5      1077 PAD: PUSH   AF
F50C AF      1078      XOR    A
F50D CD15F5 1079      CALL   SIOXMT ;OUTPUT A NULL TO THE SIO
F510 F1      1080      POP    AF
F511 3D      1081 PAD1: DEC    A
F512 20F7    1082      JR      NZ,PAD-$ ;LOOP SENDING NULLS TO SIO
F514 C9      1083      RET
1084 ;
1085 ;
F515 F5      1086 SIOXMT: PUSH   AF
F516 DB07    1087 SIOX1: IN      A,(SIOCPB)

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F46D 2130FF 0957 REMOVE: LD HL,FIFCNT
F470 35 0958 DEC (HL)
F471 2132FF 0959 LD HL,FIFOUT ;POINT HL TO FIFO OUTPUT OFFSET
F474 7E 0960 INDEX: LD A,(HL)
F475 3C 0961 INC A
F476 E60F 0962 AND 00001111B ;INCREMENT FIFO POINTER
F478 77 0963 LD (HL),A ;MODULO 16 AND REPLACE
F479 2120FF 0964 LD HL,FIFO
F47C 85 0965 ADD A,L ;INDEX INTO FIFO BY OFFSET IN A
F47D 6F 0966 LD L,A
F47E 7E 0967 LD A,(HL)
F47F C9 0968 RET
0969 ;
0970 ;
0971 ;SOFTWARE DISK MOTOR TURN-OFF TIMER ROUTINE
0972 ;
F480 216CFF 0973 DSKTMR: LD HL,MOTOR ;DECREMENT DISK TURN-OFF TIMER
F483 35 0974 DEC (HL)
F484 C0 0975 RET NZ ;EXIT IF NOT TIMED OUT YET
F485 DB1C 0976 IN A,(BITDAT)
F487 F644 0977 OR 01000100B ;DISABLE ALL DRIVE SELECTS AND
F489 D31C 0978 OUT (BITDAT),A ;TURN OFF THE SPINDLE MOTORS
F48B C9 0979 RET
0980 ;
0981 ;
0982 ;-- INTERRUPT SERVICE ROUTINE FOR PARALLEL KEYBOARD --
0983 ;
F48C ED7335FF 0984 KEYSRV: LD (SPSAVE),SP ;SAVE USR STACK POINT AND
F490 3157FF 0985 LD SP,TMPSTK+32;SWITCH TO LOCAL STACK
F493 E5 0986 PUSH HL
F494 D5 0987 PUSH DE
F495 C5 0988 PUSH BC
F496 F5 0989 PUSH AF ;SAVE MACHINE STATE
F497 DB1E 0990 IN A,(KBDDAT) ;READ KEYBOARD INPUT PORT
F499 2F 0991 CFL
F49A 2A59FF 0992 LD HL,(PINVEC);GET KBD INTERRUPT RTN VECTOR
F49D 1822 0993 JR DSPTCH-* ;AND JUMP TO DISPATCH POINT
0994 ;
0995 ;
0996 ;
0997 ;-- INTERRUPT SERVICE ROUTINE FOR ONE SECOND TIMER --
0998 ;
F49F ED7335FF 0999 TIMER: LD (SPSAVE),SP;SAVE USR STACK POINTER AND
F4A3 3157FF 1000 LD SP,TMPSTK+32 ;SWITCH TO LOCAL STACK
F4A6 E5 1001 PUSH HL
F4A7 D5 1002 PUSH DE
F4A8 C5 1003 PUSH BC
F4A9 F5 1004 PUSH AF
F4AA 2A57FF 1005 LD HL,(TIKVEC);GET CLOCK INTERRUPT RTN VECTOR
F4AD 1812 1006 JR DSPTCH-* ;AND JUMP TO DISPATCH POINT
1007 ;
1008 ;
1009 ;
1010 ;-- SERIAL INPUT INTERRUPT SERVICE ROUTINE FOR SID --
1011 ;
F4AF ED7335FF 1012 SIDINT: LD (SPSAVE),SP ;SAVE USER STACK POINTER AND
F4B3 3157FF 1013 LD SP,TMPSTK+32 ; SWITCH TO LOCAL STACK
F4B6 E5 1014 PUSH HL
F4B7 D5 1015 PUSH DE
F4B8 C5 1016 PUSH BC
F4B9 F5 1017 PUSH AF ;SAVE MACHINE STATE
F4BA DB05 1018 IN A,(SIODPB) ;READ SID DATA INPUT PORT
F4BC E67F 1019 AND 01111111B
F4BE 2A5BFF 1020 LD HL,(SINVEC);GET SERIAL INPUT RTN VECTOR

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F51B E604 1088 AND 00000100B ;TEST TBE STATUS BIT
F51A 28FA 1089 JR Z,SIOX1-*
F51C F1 1090 POP AF
F51D D305 1091 OUT (SIODPB),A ;OUTPUT DATA TO SID
F51F C9 1092 RET
1093 ;
1094 ;
1095 ;
1096 ;
1097 ;
1098 ;***** INCLUDE CRTOUT.ASM *****
1099 ;*
1100 ;* MEMORY-MAPPED CRT OUTPUT DRIVER *
1101 ;*
1102 ;* Russell Smith 18-August-1980 *
1103 ;*
1104 ;*****
1105 ;
1106 ;
>0030 1107 CRTBAS EQU CRTMEM.SHR.8 ;START PAGE# OF 3K CRT SPACE
>003C 1108 CRTTOP EQU CRTMEM+3072.SHR.8 ;END PAGE# OF CRT SPACE
1109 ;
1110 ;
F520 E5 1111 CRTOUT: PUSH HL
F521 D5 1112 PUSH DE
F522 C5 1113 PUSH BC
F523 CBBF 1114 RES 7,A
F525 4F 1115 LD C,A
F526 F3 1116 DI ;KEEP WOLVES AWAY FOR A WHILE
F527 ED7335FF 1117 LD (SPSAVE),SP
F52B 3157FF 1118 LD SP,TMPSTK+32 ;POINT SP TO TOP LOCAL STACK
F52E DB1C 1119 IN A,(BITDAT)
F530 CBFF 1120 SET 7,A ;SELECT ROM/CRT MEMORY BANK
F532 D31C 1121 OUT (BITDAT),A
1122 ;
1123 ;FIRST REMOVE THE OLD CURSOR CHARACTER FROM THE SCREEN
1124 ;
F534 2175FF 1125 LD HL,CHRSV ;GET CHAR OVERLAYED BY CURSOR
F537 46 1126 LD B,(HL)
F538 2A73FF 1127 LD HL,(CURSOR);LOAD HL WITH CURSOR POINTER
F53B 7C 1128 LD A,H
F53C E60F 1129 AND 00001111B ;INSURANCE THAT HL CAN'T
F53E F630 1130 OR CRTBAS ;EVER POINT OUTSIDE CRT MEMORY
F540 67 1131 LD H,A
F541 70 1132 LD (HL),B ;RMV CURSOR BY RESTORING CHAR
1133 ;
1134 ;PROCESS CHARACTER PASSED IN C
1135 ;
F542 CD65F5 1136 CALL OUTCH
1137 ;
1138 ;NOW STORE A NEW CURSOR CHARACTER AT THE CURSOR LOCATION
1139 ;
F545 7E 1140 LD A,(HL) ;GET CHAR AT NEW CURSOR LOCAT.
F546 3275FF 1141 LD (CHRSV),A ;SAVE FOR NEXT TIME 'CRTOUT' IS
; CALLED
F549 FE20 1142 CP ' ' ;TEST IF CHARACTER IS A SPACE
F54B CBFF 1143 SET 7,A ;THEN TURN ON BIT 7 TO ENABLE
; BLINK
F54D 2003 1144 JR NZ,CRT2-* ;JUMP IF CHARACTER IS NON-BLANK
F54F 3A76FF 1145 LD A,(CSRCHR) ;ELSE GET CHAR USED FOR CURSOR
F552 77 1146 CRT2: LD (HL),A ;STORE CHAR IN A AS CURSOR MARK
F553 2273FF 1147 LD (CURSOR),HL;SAVE HL AS CURSOR POINTER
1148 ;
F556 ED7B35FF 1149 LD SP,(SPSAVE)
F55A DB1C 1150 IN A,(BITDAT)

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F5A8 E7F5 1209 DEFW RETURN ;CTL-M IS <CR>
F5AA 11F6 1210 DEFW CLREOS ;CTL-Q CLEAR TO END-OF-SCREEN
F5AC 03F6 1211 DEFW CLREOL ;CTL-X IS CLEAR TO END-OF-LINE
F5AE ECF5 1212 DEFW CLRSCN ;CTL-Z IS CLEAR SCREEN
F5B0 B6F5 1213 DEFW ESCAPE ;CTL-[ IS ESCAPE
F5B2 6CF6 1214 DEFW HOMEUP ;CTL-^ IS HOME UP
F5B4 BAF5 1215 DEFW STUFF ;CTL-_ IS DISPLAY CONTROL CHARS
1216
>0027 1217 CTLSIZ EQU $-CTLTAB
1218 ;
1219 ;
F5B6 3E01 1220 ESCAPE: LD A,1
F5B8 12 1221 LD (DE),A ;SET LEAD-IN SEQUENCE STATE
F5B9 C9 1222 RET ;FOR XY CURSOR POSITIONING MODE
1223 ;
1224 ;
F5BA 3E04 1225 STUFF: LD A,4
F5BC 12 1226 LD (DE),A ;SET LEAD-IN SEQUENCE STATE
F5BD C9 1227 RET ;FOR CONTROL CHAR OUTPUT MODE
1228 ;
1229 ;
F5BE 7D 1230 BAKSPC LD A,L ;CHECK FOR LEFT MARGIN
F5BF E67F 1231 AND 01111111B
F5C1 C8 1232 RET Z ;ABORT IF IN LEFTMOST COLUMN
F5C2 2B 1233 DEC HL ;BACK UP CURSOR POINTER
F5C3 C9 1234 RET
1235 ;
1236 ;
F5C4 7D 1237 FORSPC: LD A,L ;CHECK FOR RIGHTMOST COLUMN
F5C5 E67F 1238 AND 01111111B
F5C7 FE4F 1239 CP 79
F5C9 D0 1240 RET NC ;DO NOTHING IF ALREADY THERE
F5CA 23 1241 INC HL
F5CB C9 1242 RET ;ELSE ADVANCE CURSOR POINTER
1243 ;
1244 ;
F5CC 110800 1245 TAB: LD DE,8 ;TABS ARE EVERY 8 COLUMNS
F5CF 7D 1246 LD A,L ;GET COLUMN COMPONENT OF
F5D0 E67B 1247 AND 01111000B ;PREVIOUS TAB POSITION
F5D2 B3 1248 ADD A,E
F5D3 FE50 1249 CP B0 ;EXIT IF NEXT TAB COLUMN WOULD
F5D5 D0 1250 RET NC ;BE PAST THE RIGHT MARGIN
F5D6 7D 1251 LD A,L
F5D7 E6FB 1252 AND 11111000B ;ELSE INCREMENT THE CURSOR
F5D9 6F 1253 LD L,A ;POINTER FOR REAL
F5DA 19 1254 ADD HL,DE
F5DB C9 1255 RET
1256 ;
1257 ;
F5DC DB1C 1258 BELL: IN A,(BITDAT)
F5DE CBEF 1259 SET 5,A ;TOGGLE BIT 5 OF SYSTEM PIO TO
F5E0 D31C 1260 OUT (BITDAT),A ;TRIGGER BELL HARDWARE TO SOUND
F5E2 CBAF 1261 RES 5,A
F5E4 D31C 1262 OUT (BITDAT),A
F5E6 C9 1263 RET
1264 ;
1265 ;
F5E7 7D 1266 RETURN: LD A,L
F5E8 E680 1267 AND 10000000B
F5EA 6F 1268 LD L,A ;MOVE CURSOR POINTER BACK
F5EB C9 1269 RET ;TO START OF LINE
1270 ;
1271 ;
F5EC 210030 1272 CLRSCN: LD HL,CRTMEM

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F645 17 1338 RLA ;EXTRACT ROW# COMPONENT OF HL
F646 E61F 1339 AND 00011111B
F648 4F 1340 LD C,A ;COPY ROW# TO C FOR SCROLL TEST
F649 CD37F6 1341 CALL DNCSR ;MOVE CURSOR TO NEXT ROW DOWN
F64C 3A77FF 1342 LD A,(BASE) ;TEST IF CURSOR ON BOTTOM ROW
F64F B9 1343 CP C ;OF SCREEN BEFORE MOVING DOWN
F650 C0 1344 RET NZ ;EXIT IF NOT AT BOTTOM
1345
F651 E5 1346 PUSH HL ;ELSE PREP TO SCROLL SCREEN UP
F652 CD60F6 1347 CALL CLRRLIN ;FILL NEW BOTTOM LINE WTH SPACES
F655 29 1348 ADD HL,HL
F656 7C 1349 LD A,H ;GET ROW# PART OF HL INTO A
F657 E61F 1350 AND 00011111B
F659 3277FF 1351 LD (BASE),A ;STORE NEW BASE LINE#
F65C D314 1352 OUT (SCROLL),A ;SCROLL UP NEW BLANK BOTTM LINE
F65E E1 1353 POP HL
F65F C9 1354 RET
1355 ;
1356 ;
F660 7D 1357 CLRRLIN: LD A,L
F661 E680 1358 AND 10000000B ;POINT HL TO 1ST COLUMN OF ROW
F663 6F 1359 LD L,A
F664 0650 1360 LD B,B0
F666 3620 1361 CLR: LD (HL),' ' ;STORE ASCII SPACES AT ADDR
; IN HL
F668 23 1362 INC HL ;AND INCREMENT HL
F669 10FB 1363 DJNZ CLR-$ ;REPEAT NUMBER OF TIMES IN B
F66B C9 1364 RET
1365 ;
1366 ;
F66C 0E20 1367 HOMEUP: LD C,' ' ;FAKE-OUT CURSOR ADDR ROUTINE
F66E 1B17 1368 JR SETROW-$ ;TO DO HOMEUP ALMOST FOR FREE
1369 ;
1370 ;
F670 EB 1371 MULTI: EX DE,HL ;UNCONDITIONALLY RESET LEAD-IN
F671 3600 1372 LD (HL),0 ;STATE TO ZERO BEFORE GOING ON
F673 EB 1373 EX DE,HL
F674 FE01 1374 CP 1
F676 200B 1375 JR NZ,M2TST-$
F678 79 1376 SETXY: LD A,C ;GET SECOND CHAR OF SEQUENCE
F679 FE3D 1377 CP '='
F67B C0 1378 RET NZ ;ABORT SEQUENCE IF NOT '='
F67C 3E02 1379 LD A,2
F67E 12 1380 LD (DE),A ;MAKE LEADIN=2 NEXT TIME
F67F C9 1381 RET
1382
F680 FE02 1383 M2TST: CP 2
F682 2019 1384 JR NZ,M3TST-$
F684 3E03 1385 LD A,3
F686 12 1386 LD (DE),A ;MAKE LEADIN=3 NEXT TIME
F687 3A77FF 1387 SETROW: LD A,(BASE) ;ARRIVE HERE ON THIRD CHAR
F68A 81 1388 ADD A,C ;OF ESC, '=',ROW,COL SEQUENCE
F68B D61F 1389 SUB ' '-1
F68D D61B 1390 SETR2: SUB 24
F68F 30FC 1391 JR NC,SETR2-$ ;VERIFY ROW# BETWEEN 0 AND 23
F691 C61B 1392 ADD A,24
F693 F660 1393 OR CRTMEM.SHR.7 ;MERGE IN MSB'S OF CRT MEMORY
F695 67 1394 LD H,A
F696 2E00 1395 LD L,0
F698 CB3C 1396 SRL H
F69A CB1D 1397 RRR L
F69C C9 1398 RET
1399
F69D FE03 1400 M3TST: CP 3
F69F 200C 1401 JR NZ,M4TST-$

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PFM Monitor Listing (continued)

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F6A1 79      1402 SETCOL: LD      A,C      ;ARRIVE HERE ON FOURTH CHAR
F6A2 D620    1403 SUB          ' '      ;OF ESC, '=' ,ROW,COL SEQUENCE
F6A4 D650    1404 SETC2:  SUB      B0      ;
F6A6 30FC    1405 JR          NC,SETC2-# ;MAKE SURE COL# BETWEEN 0 & 79
F6AB C650    1406 ADD      A,B0      ;
F6AA B5      1407 OR          L          ;MERGE IN COL# WITH L
F6AB 6F      1408 LD          L,A      ;
F6AC C9      1409 RET
1410
F6AD CD72F5  1411 M4TST: CALL   DISPLA  ;DISPLAY THE CONTROL CHAR
F6B0 C9      1412 RET          ;PASSED IN C
1413 ;
1414 ;
1415 ;
1416 ;
1417          INCLUDE DISKIO.ASM
1418 ;*****
1419 ;*
1420 ;*   DISK INPUT/OUTPUT DRIVER SUBROUTINE PACKAGE
1421 ;*   FOR WESTERN DIGITAL 1771 DISK CONTROLLER
1422 ;*
1423 ;*   bullet-proof error recovery added 12-APR-80
1424 ;*
1425 ;*****
1426 ;
1427 ;
1428 ;EQUATES FOR DISK CONTROLLER PORTS AND COMMAND CODES
1429 ;
>0010 1430 STSREG EQU      WD1771+0 ;STATUS REGISTER
>0010 1431 CMDREG EQU      WD1771+0 ;COMMAND REGISTER
>0011 1432 TRKREG EQU      WD1771+1 ;TRACK REGISTER
>0012 1433 SECREG EQU      WD1771+2 ;SECTOR REGISTER
>0013 1434 DATREG EQU      WD1771+3 ;DATA REGISTER
1435 ;
>00B8 1436 RDCMD EQU      10001000B ;READ COMMAND
>00AB 1437 WRTCMD EQU      10101000B ;WRITE COMMAND
>001C 1438 SKCMD EQU      00011100B ;SEEK COMMAND
>00D0 1439 FINCMD EQU      11010000B ;FORCE INTR COMMAND
>000C 1440 RSTCMD EQU      00001100B ;RESTORE COMMAND
>0004 1441 HLOAD EQU      00000100B ;RD/WRT HEAD LOAD ENABLE
1442 ;
>00C9 1443 RET EQU      0C9H      ;SUBROUTINE RETURN INSTR OPCODE
>0066 1444 NMIVEC EQU      0066H   ;THE NON-MASKABLE INTERRUPT IS
1445 ;USED FOR DATA SYNC BETWEEN
1446 ;THE Z-80 AND 1771
1447 ;
1448 ;
1449 ;
F6B1 79      1450 SELECT: LD      A,C      ;GET UNIT# PASSED IN C AND
F6B2 FE04    1451 CP          4          ;CHECK FOR MAXIMUM VALID#
F6B4 D0      1452 RET      NC          ;ERROR IF NUMBER > 3
F6B5 CDB8F7  1453 CALL   TURNON ;MAKE SURE DISKS ARE TURNED ON
F6B8 DB1C    1454 IN          A,(BITDAT)
F6BA 47      1455 LD          B,A      ;SAVE CURRENT DRIVE SELECT DATA
F6BB E6F8    1456 AND      11111000B ;MERGE IN NEW DRIVE UNIT# IN C
F6BD B1      1457 OR          C          ;IN PLACE OF THE CURRENT ONE
F6BE D31C    1458 OUT      (BITDAT),A ;TO SELECT THE NEW DISK DRIVE
F6C0 CDAEF7  1459 CALL   FORCE      ;TEST NEW DRIVE'S READY STATUS

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F71F CDABF7  1524 WRITE: CALL   READY  ;CLEAR THE DISK CONTROLLER
F722 C0      1525 RET      NZ          ;EXIT IF DRIVE NOT READY
F723 CB77    1526 BIT      6,A
F725 C0      1527 RET      NZ          ;EXIT IF DISK WRITE-PROTECTED
F726 06AB    1528 LD      B,WRTCMD
F728 1806    1529 JR      RDWRT-#
1530
F72A CDABF7  1531 READ:  CALL   READY  ;CLEAR DISK CONTROLLER
F72D C0      1532 RET      NZ          ;EXIT IF DRIVE NOT READY
F72E 0688    1533 LD      B,RDCMD
F730 2271FF  1534 RDWRT: LD      (IOPTR),HL ;STORE DISK I/O DATA POINTER
F733 216EFF  1535 LD      HL,SECTOR
F736 71      1536 LD      (HL),C      ;STORE SECTOR# FOR READ/WRITE
F737 23      1537 INC     HL
F738 70      1538 LD      (HL),B      ;SAVE READ/WRITE COMMAND BYTE
F739 23      1539 INC     HL
F73A 3602    1540 LD      (HL),2      ;SET DISK RE-TRY COUNT
F73C F3      1541 RW1:  DI          ;NO INTERRUPTS DURING DISK I/O
F73D 216600  1542 LD      HL,NMIVEC  ;SAVE BYTE AT NMI VECTOR LOCAT
F740 56      1543 LD      D,(HL)     ;IN D FOR DURATION OF READ/WRT
F741 36C9    1544 LD      (HL),RET   ;LOOP AND REPLACE IT WITH A RET
F743 216BFF  1545 LD      HL,RECLN
F746 46      1546 LD      B,(HL)     ;B=NUMBER OF BYTES/SECTOR
F747 0E13    1547 LD      C,DATREG   ;C=1771 DATA REGISTER PORT#
F749 2A71FF  1548 LD      HL,(IOPTR) ;HL=DISK R/W DATA POINTER
F74C 3A6EFF  1549 LD      A,(SECTOR) ;GET SECTOR NUMBER
F74F D312    1550 OUT     (SECREG),A ;OUTPUT SECTOR# TO 1771
F751 CDAEF7  1551 CALL   FORCE      ;ISSUE FORCE INTERRUPT COMMAND
F754 CB6F    1552 BIT      5,A      ;TO TEST HEAD LOAD STATUS
F756 3A6FFF  1553 LD      A,(CMDTYP) ;GET READ OR WRITE COMMAND BYTE
F759 2002    1554 JR      NZ,RW2-#   ;JUMP IF HEAD IS ALREADY LOADED
F75B F604    1555 OR      HLOAD     ;ELSE MERGE IN HLD BIT
F75D CDA3F7  1556 RW2:  CALL   CMDOUT   ;START 1771 DOING IT'S THING
F760 CB6F    1557 BIT      5,A      ;TEST IF COMMAND IS A R OR W
F762 200D    1558 JR      NZ,WLOOP-# ;AND JUMP TO THE CORRECT LOOP
F764 76      1559 RLOOP: HALT
F765 EDA2    1560 INI
F767 C26AF7  1561 JP      NZ,RLOOP
F76A CD9CF7  1562 CALL   BUSY      ;LOOP UNTIL 1771 COMES UN-BUSY
F76D E69C    1563 AND     10011100B ;MASK OFF TO READY,NOT FOUND,CRC
F76F 180B    1564 JR      RW3-#    ;AND LOST DATA STATUS BITS
1565
F771 76      1566 WLOOP: HALT
F772 EDA3    1567 OUTI
F774 C271F7  1568 JP      NZ,WLOOP
F777 CD9CF7  1569 CALL   BUSY
F77A E6BC    1570 AND     10111100B ;MASK OFF AS ABOVE + WRT FAULT
F77C 216600  1571 RW3:  LD      HL,NMIVEC
F77F 72      1572 LD      (HL),D    ;RESTORE BYTE @ NMI VECTOR
F780 FB      1573 EI
F781 CB      1574 RET      Z          ;RETURN IF NO DISK I/O ERRORS
F782 2170FF  1575 LD      HL,RETRY
F785 35      1576 DEC     (HL)      ;DECREMENT RE-TRY COUNT AND
F786 2002    1577 JR      NZ,RW4-#   ;EXECUTE COMAND AGAIN IF NOT=0
F788 B7      1578 OR      A
F789 C9      1579 RET
1580
F78A 216DFF  1581 RW4:  LD      HL,TRACK
F78D 4E      1582 LD      C,(HL)    ;GET TRACK# FOR THIS OPERATION
F78E CDFBF6  1583 CALL   SEEK      ;TRY TO RE-CALIBRATE THE HEAD
F791 18A9    1584 JR      RW1-#    ;BEFORE READ OR WRITE AGAIN
1585 ;
1586 ;
1587 ;

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F6C3 2806 1460 JR Z,SEL2-# ;AND CONTINUE IF ITS READY
F6C5 78 1461 LD A,B
F6C6 D31C 1462 OUT (BITDAT),A ;ELSE PUT BACK OLD DRIVE SELECT
F6C8 3E80 1463 LD A,1000000B;AND RETURN DRIVE-NOT-READY
F6CA C9 1464 RET
1465 ;
F6CB 2165FF 1466 SEL2: LD HL,UNIT ;POINT HL TO DRIVE SELECT DATA
F6CE 7E 1467 LD A,(HL) ;LOAD A WITH CURRENT UNIT#
F6CF 71 1468 LD (HL),C ;AND STORE NEW UNIT# FROM C
F6D0 FEFF 1469 CP 255 ;TEST IF NO DRIVE SELECTED
F6D2 2806 1470 JR Z,SEL3-# ;YET & SKIP NEXT SEGMENT IF SO
F6D4 23 1471 INC HL ;POINT TO HEAD POSITION TABLE
F6D5 85 1472 ADD A,L ;AND ADD IN NEW UNIT# AS INDEX
F6D6 6F 1473 LD L,A
F6D7 DB11 1474 IN A,(TRKREG) ;GET CURRENT HEAD POSITION
F6D9 77 1475 LD (HL),A ;AND STORE IN TABLE @ HL
F6DA 2166FF 1476 SEL3: LD HL,TRKTAB
F6DD 7D 1477 LD A,L
F6DE 81 1478 ADD A,C ;INDEX INTO TABLE TO GET
F6DF 6F 1479 LD L,A ;HEAD POSITION OF NEW DRIVE
F6E0 7E 1480 LD A,(HL)
F6E1 FEFF 1481 CP 255 ;TEST IF NEW DRIVE WAS EVER
F6E3 2804 1482 JR Z,HOME-# ;SELECTED AND DO A HOME IF NOT
F6E5 D311 1483 OUT (TRKREG),A ;OUTPUT DRIVE'S CURRENT HEAD
F6E7 AF 1484 XOR A ;POSITION TO THE TRACK REGISTER
F6E8 C9 1485 RET
1486 ;
1487 ;
1488 ;
F6E9 CDABF7 1489 HOME: CALL READY ;CLEAR DISK CONTROLLER
F6EC C0 1490 RET NZ ;EXIT IF DRIVE NOT READY
F6ED AF 1491 XOR A
F6EE 326DFF 1492 LD (TRACK),A ;SET TRACK# IN MEM TO ZERO
F6F1 060C 1493 RESTOR: LD B,RSTCMD ;LOAD B WITH A RESTORE COMMAND
F6F3 CD93F7 1494 CALL STEP ;EXECUTE HEAD MOVING OPERATION
F6F6 EE04 1495 XOR 00000100B ;GET TRUE TRACK 0 STATUS
F6FB E69C 1496 AND 10011100B ;MASK TO ERROR BITS
F6FA C9 1497 RET ;RETURN 1771 STATUS IN A
1498 ;
1499 ;
1500 ;
F6FB CDABF7 1501 SEEK: CALL READY ;CLEAR DISK CONTROLLER
F6FE C0 1502 RET NZ ;EXIT IF DRIVE NOT READY
F6FF 79 1503 LD A,C ;GET TRACK# DATA FROM C AND
F700 FE4D 1504 CP 77 ;CHECK FOR MAXIMUM VALID#
F702 D0 1505 RET NC ;FORGET IT IF TRACK# > 76
F703 326DFF 1506 LD (TRACK),A ;ELSE STORE TRACK# FOR SEEK
F706 D313 1507 OUT (DATREG),A ;OUTPUT TRACK # TO 1771
F708 061C 1508 LD B,SKCMD ;LOAD B WITH A SEEK COMMAND AND
F70A CD93F7 1509 CALL STEP ;GO SEEK WITH PROPER STEP RATE
F70D E698 1510 AND 10011000B ;MASK TO READY,SEEK & CRC ERROR
F70F C8 1511 RET Z ;BITS AND RETURN IF ALL GOOD
1512 ;
F710 CDF1F6 1513 CALL RESTOR ;ELSE TRY TO RE-CALIBRATE HEAD
F713 C0 1514 RET NZ ;ERROR IF WE CAN'T FIND TRACK 0
F714 79 1515 LD A,C
F715 D313 1516 OUT (DATREG),A ;OUTPUT TRACK# TO 1771
F717 061C 1517 LD B,SKCMD
F719 CD93F7 1518 CALL STEP ;TRY TO SEEK THE TRACK AGAIN
F71C E698 1519 AND 10011000B
F71E C9 1520 RET ;RETURN FINAL SEEK STATUS IN A
1521 ;
1522 ;
1523 ;

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F793 3A6AFF 1588 STEP: LD A,(SPEED) ;GET STEP SPEED VARIABLE
F796 E603 1589 AND 00000011B
F798 B0 1590 OR B ;MERGE WTH SEEK/HOME COMND IN B
F799 CDA3F7 1591 CALL CMDOUT ;OUTPUT COMMAND AND DELAY
F79C DB10 1592 BUSY: IN A,(STSREG)
F79E CB47 1593 BIT 0,A ;TEST BUSY BIT FROM
F7A0 20FA 1594 JR NZ,BUSY-# ; 1771 AND LOOP TILL=0
F7A2 C9 1595 RET
1596 ;
1597 ;
1598 ;
F7A3 D310 1599 CMDOUT: OUT (CMDREG),A ;OUTPUT A COMMAND TO THE 1771
F7A5 CDABF7 1600 CALL PAUSE ;WASTE 44 MICROSECONDS
F7A8 E3 1601 PAUSE: EX (SP),HL
F7A9 E3 1602 EX (SP),HL
F7AA C9 1603 RET
1604 ;
1605 ;
1606 ;
F7AB CDB8F7 1607 READY: CALL TURNOFF ;KEEP THOSE DISKS SPINING FOLKS
F7AE 3ED0 1608 FORCE: LD A,FINCMD ;ISSUE FORCE INTERRUPT COMMAND
F7B0 CDA3F7 1609 CALL CMDOUT
F7B3 DB10 1610 IN A,(STSREG) ;READ STATUS REGISTER CONTENTS
F7B5 CB7F 1611 BIT 7,A ;TEST DRIVE NOT READY BIT
F7B7 C9 1612 RET
1613 ;
1614 ;
1615 ;
F7B8 3E1E 1616 TURNOFF: LD A,30
F7BA 326CFF 1617 LD (MOTOR),A ;RE-LOAD MOTOR TURN-OFF TIMER
F7BD CDABF7 1618 CALL PAUSE
F7C0 DB1C 1619 IN A,(BITDAT)
F7C2 CB57 1620 BIT 2,A ;TEST IF MOTORS HAVE STOPPED
F7C4 C8 1621 RET Z ;AND EXIT IF STILL TURNED ON
F7C5 E6BB 1622 AND 10111011B ;ELSE RE-ENABLE DRIVE SELECTS
F7C7 D31C 1623 OUT (BITDAT),A ;AND ACTIVATE THE MOTOR RELAY
F7C9 C5 1624 PUSH BC
F7CA 0600 1625 LD B,0 ;SET READY LOOP MAX TIMEOUT
F7CC CDDCF7 1626 TURN2: CALL WAIT ;WAIT 1/93 SECOND & TEST READY
F7CF 2802 1627 JR Z,TURN3-# ;EXIT LOOP IF DRIVE READY
F7D1 10F9 1628 DJNZ TURN2-# ;ELSE TRY AGAIN UP TO 256 TIMES
F7D3 0609 1629 TURN3: LD B,9
F7D5 CDDCF7 1630 TURN4: CALL WAIT ;GIVE ABT 1/10 SEC MORE DELAY
F7D8 10FB 1631 DJNZ TURN4-#
F7DA C1 1632 POP BC
F7DB C9 1633 RET
1634 ;
1635 ;
F7DC DB1B 1636 WAIT: IN A,(CTC3) ;GET CURRENT CTC3 COUNT VALUE
F7DE 4F 1637 LD C,A
F7DF DB1B 1638 WAIT2: IN A,(CTC3)
F7E1 B9 1639 CP C ;SEE IF CTC3 CHANGED BY 1 COUNT
F7E2 28FB 1640 JR Z,WAIT2-# ;AND LOOP UNTIL IT CHANGES
F7E4 18C8 1641 JR FORCE-# ;THEN TEST DRIVE READY STATUS
1642 ;
1643 ;
1644 ;
1645 ;
1646 ;
F7E6 0000 1647 ROMEND: DEFW 0 ;TAIL OF FREE MEM LINKED LIST
1648 ;
>FF00 1649 ORG RAM
1650 INCLUDE MEMORY.ASM

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PFM Monitor Listing (continued)

```

1651 ;*****
1652 ;*
1653 ;* STORAGE ALLOCATION FOR 256 BYTE SCRATCH RAM *
1654 ;*
1655 ;*****
1656 ;
1657 ;
1658 ;
>FF00 1659 VECTAB EQU $ ;INTERRUPT VECTOR TABLE STARTS
>FF00 1660 SIOVEC: DEFS 16 ;SPACE FOR 8 VECTORS FOR SIO
>FF10 1661 CTCVEC: DEFS 8 ;SPACE FOR 4 VECTORS FOR CTC
>FF18 1662 SYSVEC: DEFS 4 ;SPACE FOR 2 VECTORS FOR SYSTEM
; PIO
>FF1C 1663 GENVEC: DEFS 4 ;SPACE FOR 2 VECTORS FOR
; GENERAL PIO
1664 ;
1665 ;
1666 ;KEYBOARD DATA INPUT FIFO VARIABLES
1667 ;
>FF20 1668 FIFO: DEFS 16 ;CONSOLE INPUT FIFO
>FF30 1669 FIFCNT: DEFS 1 ;FIFO DATA COUNTER
>FF31 1670 FIFIN: DEFS 1 ;FIFI INPUT POINTER
>FF32 1671 FIFOUT: DEFS 1 ;FIFO OUTPUT POINTER
>FF33 1672 LOCK: DEFS 2 ;SHIFT LOCK CHAR+FLAG BYTE
1673 ;
1674 ;
1675 ;STACK POINTER SAVE AND LOCAL STACK FOR INTERRUPT ROUTINES
1676 ;
>FF35 1677 SPSAVE: DEFS 2 ;USER STACK POINTER SAVE AREA
>FF37 1678 TMPSTK: DEFS 32 ;LOCAL STACK FOR INTERRUPTS
1679 ;
1680 ;
1681 ;'SOFTWARE' VECTORS FOR INTERRUPT SERVICE ROUTINES
1682 ;
>FF57 1683 TIKVEC: DEFS 2 ;1 SEC INTERRUPT ROUTINE VECTOR
>FF59 1684 PINVEC: DEFS 2 ;PARALLEL CONSOLE INPUT VECTOR
>FF5B 1685 SINVEC: DEFS 2 ;SERIAL CONSOLE INPUT VECTOR
1686 ;
1687 ;
1688 ;CLOCK-TIMER INTERRUPT VARIABLES
1689 ;
>FF5D 1690 TIKCNT: DEFS 2 ;BINARY CLOCK TICK COUNTER
>FF5F 1691 DAY: DEFS 1 ;CALENDAR DAY
>FF60 1692 MONTH: DEFS 1 ; MONTH
>FF61 1693 YEAR: DEFS 1 ; YEAR
>FF62 1694 HRS: DEFS 1 ;CLOCK HOURS REGISTER
>FF63 1695 MINS: DEFS 1 ; MINUTES RETISTER
>FF64 1696 SECS: DEFS 1 ; SECONDS REGISTER
1697 ;
1698 ;
1699 ;DISK I/O DRIVER VARIABLES
1700 ;
>FF65 1701 UNIT: DEFS 1 ;CURRENTLY SELECTED DISK#
>FF66 1702 TRKTAB: DEFS 4 ;4 DRIVE HEAD POSITION TABLE
>FF6A 1703 SPEED: DEFS 1 ;SEEK SPEED FOR 1771 COMMANDS
>FF6B 1704 RECLN: DEFS 1 ;SECTOR RECORD LENGTH VARIABLE
>FF6C 1705 MOTOR: DEFS 1 ;DRIVE MOTOR TURN-OFF TIMER
>FF6D 1706 TRACK: DEFS 1
>FF6E 1707 SECTOR: DEFS 1

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>FF6F 1708 CMDTYP: DEFS 1 ;COMMAND BYTE FOR READS/WITES
>FF70 1709 RETRY: DEFS 1 ;DISK OPERATION RE-TRY COUNT
>FF71 1710 IOPTR: DEFS 2 ;DISK I/O BUFFER POINTER
1711 ;
1712 ;
1713 ;
1714 ;CRT OUTPUT DRIVER VARIABLES
1715 ;
>FF73 1716 CURSOR: DEFS 2 ;CURSOR POINTER
>FF75 1717 CHRSAV: DEFS 1 ;CHAR OVERLAYED BY CURSOR
>FF76 1718 CSRCHR: DEFS 1 ;CHAR USED FOR A CURSOR
>FF77 1719 BASE: DEFS 1 ;CURRENT CONTENTS OF SCROLL
; REGISTER
>FF78 1720 LEADIN: DEFS 1 ;STATE OF LEAD-IN SEQUENCE
; HANDLER
1721 ;
1722 ;
1723 ;NULL PAD COUNT FOR SERIAL OUTPUT DELAY
1724 ;
>FF79 1725 NULLS: DEFS 1 ;# OF NULLS SENT AFTER CONTROL
; CHARS.
1726 ;
1727 ;
1728 ;LISTHEAD POINTER FOR DYNAMIC MEMORY ALLOCATION SCHEME
1729 ;
>FF7A 1730 FREPTR: DEFS 2
1731 ;
1732 ;
1733 ;CONSOLE MONITOR PROGRAM VARIABLES
1734 ;
>FF7C 1735 PARAM1: DEFS 2 ;STORAGE FOR NUMBERS READ
>FF7E 1736 PARAM2: DEFS 2 ;FROM LINE INPUT BUFFER
>FF80 1737 PARAM3: DEFS 2 ;BY 'PARAMS' SUBROUTINE
>FF82 1738 PARAM4: DEFS 2
>FF84 1739 ESCFLG: DEFS 1 ;CONSOLE ESCAPE FLAG
>FF85 1740 COFLAG: DEFS 1 ;CONSOLE OUTPUT TOGGLE
>FF86 1741 LAST: DEFS 2 ;LAST ADDRESS USED BY 'MEMDMP'
>FF88 1742 LINBUF: DEFS 64 ;CONSOLE LINE INPUT BUFFER
1743 ;
1744 ;
1745 ;
1746 ;
1747 END

```

ERRORS=0000

end



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