HITACHI PROGRAMMABLE CONTROLLER

EH-150

PROFIBUS-DP MASTER MODULE 2 (EH-RMP2) APPLICATION MANUAL

(SERVICE MANUAL)



O Warranty period and coverage

The warranty period is the shorter period either 18 months from the data of manufacture or 12 months from the date of installation.

However within the warranty period, the warranty will be void if the fault is due to;

- (1) Incorrect use as directed in this manual and the application manual.
- (2) Malfunction or failure of external other devices than this unit.
- (3) Attempted repair by unauthorized personnel.
- (4) Natural disasters.

The warranty is for the PLC only, any damage caused to third party equipment by malfunction of the PLC is not covered by the warranty.

O Repair

Any examination or repair after the warranty period is not covered. And within the warranty period ant repair and examination which results in information showing the fault was caused by ant of the items mentioned above, the repair and examination cost are not covered. If you have ant questions regarding the warranty please contact with your supplier or the local Hitachi Distributor. (Depending on failure part, examination might be impossible.)

O Ordering parts or asking questions

When contacting us for repair, ordering parts or inquiring about other items, please have the following details ready before contacting the place of purchase.

- (1) Model
- (2) Manufacturing number (MFG.No.)
- (3) Details of the malfunction

O Reader of this manual

This manual is described for the following person.

- \cdot Person considering the introduction of PLC
- PLC system engineer
- Person handling PLC
- Manager after installing PLC

Warning

- (1) Reproduction of the contents of this manual, in whole or in part, without written permission of Hitachi-IES, is prohibited.
- (2) The content of this document may be changed without notice.
- (3) While efforts have been made to be accurate, if any wrong or missing information is found, please contact us.

Microsoft[®] and Windows[®] are either registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

PROFIBUS, PROFIBUS-DP are trademarks of PROFIBUS international.

Safety Precautions

Read this manual and related documents thoroughly before installing, operating, performing preventive maintenance or performing inspection, and be sure to use the unit correctly. Use this product after acquiring adequate knowledge of the unit, all safety information, and all cautionary information. Also, make sure this manual enters the possession of the chief person in charge of safety maintenance.

Safety caution items are classifies as "Danger" and "Caution" in this document.



: Identifies information about practice or circumstances, which may lead to personal injury or death, property damage, or economic loss.



: Identifies information about practice or circumstances, which may lead to personal injury, property damage, or economic loss.

However, depending on the circumstances, items marked with



may result in major accidents.

The both marks show important information. Be sure to follow the instructions.

Icons for prohibited items and required items are shown below:



1. Installation

- Use this product in an environment as described in the catalog or this document. If this product is used in an environment subject to high temperature, high humidity, excessive dust, corrosive gases, vibration or shock, it may result in electric shock, fire or malfunction.
- Be sure to install the PLC according to this manual. Failure to do so could result in damage by falling off, failure or malfunction.
- Do not allow foreign objects such as wire chips to enter the unit. They may become the cause of fire, malfunction or failure.

2. Wiring

REQUIRED

• The PLC must be grounded (FE terminal).

Failure to do so could result in injury to personnel or causing it to malfunction.

▲ CAUTION

• Always use the power supply voltage listed in specifications. Using other voltage may damage the equipment or present a risk of fire.

• The wiring operation should be performed by a qualified personnel. Failure to do so could result in fire, damage or electric shock.

3. Precautions when using the unit

DANGER

• Do not touch the terminals while the power is on. There is a risk of electric shock.

• Appropriate emergency stop circuit, interlock circuitry and similar safety measures should be added to the PLC system to ensure safety in the event of incorrect, missing or abnormal signals caused by broken signal lines, momentary power interruptions or other causes. Do not share the power supply of relay output module and interlock circuitry because relay output might not work properly due to switching noise from interlock circuitry.

- When performing program change, forced output, RUN, STOP, etc., while the unit is running, be sure to check system safety carefully. Failure to do so could lead to damage to equipment.
- Supply power according to the power–up order. Failure to do so could lead to damage to equipment or malfunction.

USE POWER SUPPLY UNIT OF EH-PS SERIES FOR SUPPLYING ELECTRIC POWER.

4. Preventive maintenance

DANGER

• Do not connect the _{+/-} of the battery in reverse polarity. Do not recharge, disassemble, heat, place in fire, or short circuit the battery. There is a risk of explosion or fire.

• Do not attempt to disassemble, repair or modify any part of the PLC. Electric shock, malfunction or failure may result.

• Turn off power to the PLC before mounting or dismounting the module Electric shock, malfunction or failure may result.

Revision History

No.	Description of revision	Date of revision	Manual number
1	The first edition	Oct. 2014	NJI-621(X)

Table of Contents

Chapte	er 1 Introduction	1-1 to 1-3
1.1	Before use	1-1
1.2	Item packaged with the module	1-1
1.3	System configurations	1-2
1.4	Difference between EH-RMP2 and EH-RMP	1-3
1.5	Replacement from EH-RMP	1-3

Chapte	er 2 Specifications	2-1 to 2-6
2.1	General Specifications	2-1
2.2	Functional Specifications	2-2
2.3	Name and function of each part	

Chapte	er 3 Installation	3-1 to 3-5
3.1	Mounting module	3-1
3.2	Mountable slots for EH-RMP2	3-2
3.3	Wiring	3-3
	3.3.1 PROFIBUS port	3-3
	3.3.2 Recommened connectors	3-3
	3.3.3 Cable parameters	3-4
	3.3.4 Maximum length of bus segment	3-5

Chapter 4 Operation			
4.1	Start up		4-1
		4.1.1 DIP switch	4-1
		4.1.2 Rotary switch	4-2
		4.1.3 Configuration from configurator	4-3
		4.1.4 Configuration from programming tool	4-12
4.2	Data form	nat	4-14
4.3	Offset ad	ddress	4-15

Chapter 5 Indications		5-1 to 5-9
5.1 LED indications		 5-1
5.1.1 RDY LE	D	
5.1.2 STATU	S LED	
5.1.3 RUN LE	D	
5.1.4 ERR LE	D	
5.2 Link information flag ar	ea	
5.2.1 Get link	information	
5.2.2 Detail o	f each information	

Chapte	r 6 Troubleshooting	6-1 to 6-2
6.1	Error indications of EH-RMP2	6-1
6.2	New entry of slave unit to PROFIBUS	6-2
6.3	Startup time of EH-RMP2	6-2



Chapter 1 Introduction

1.1 Before use

Thank you very much for choosing Hitachi Programmable Controller (hereinafter referred to as PLC), EH-150 series. This manual explains how to use the PROFIBUS-DP master module 2 with the Hitachi EH-150 series Programmable Controller. Read this manual thoroughly and keep for installation operations, maintenance checks and other procedures. The following documentation related to PLC is also available and should be used together with this manual.

Items		Title of document	Manual number
EHV+ series Main system of EHV+		IEC 61131-3 Compliant PLC EHV+ APPLICATION MANUAL	NJI-564*(X)
	Main system of EHV	EH-150 EHV-CPU APPLICATION MANUAL EH-150 EHV-CPU PROGRAMMING MANUAL	NJI-481*(X) NJI-482*(X)
EHV series	Programming software (Standard edition)	EH-150 EHV series Ladder Programming software Control Editor INSTRUCTION MANUAL	NJI-537*(X)
	Programming software (Variable Name Edition)	EH-150 EHV series Ladder Programming software Control Editor INSTRUCTION MANUAL	NJI-486*(X)
	Main system of EH-150	EH-150 APPLICATION MANUAL	NJI-280*(X)
EH-150 series	Programming software	LADDER EDITOR for Windows® INSTRUCTION MANUAL	NJI-206*(X)

* The alphabet between the number and (X) means version (A,B...) and the space means the first edition.

1.2 Item packaged with the module

Great care has been taken in the manufacture of this product, but we advise that the following points are checked immediately after purchase.

- 1. Is the model the same one that you ordered?
- 2. Has the product been damaged in any way?
- 3. Are any of the accessories listed in Table 1.2-1 missing?

Table 1.2-1 List of acces	ssories supplied with the EH-RMP2
---------------------------	-----------------------------------

No.	Product name	Model name	Appearance	Quantity	Remarks
1	PROFIBUS Master module 2	EH-RMP2		1	
2	Instruction manual	NJI-617*(X)		1	
3	Ferrite Core	SFC-10		2	For applying CE marking (EMC direction). Please refer to 3.3 Wiring.

1.3 System configurations

EH-RMP2 is master module on PROFIBUS-DP protocol of industrial network. EH-RMP2 is helpful as master controller of PROFIBUS system. Example of system configuration is shown below.



Figure 1.3-1 Example of system configurations

1.4 Difference between EH-RMP2 and EH-RMP

There are some differences between EH-RMP2 and EH-RMP.

- (1) Configuration tool
 - EH-RMP : Sycon

EH-RMP2 : SYCON.net

(2) Configuration cable

EH-RMP : Exclusive serial cable

EH-RMP2 : USB cable (The cable currently used in EHV series can be used.)

(3) Bus Termination

EH-RMP : Built-in

EH-RMP2 : Not built-in (Please use a connector which has a termination switch.)

EH-RMP2 expands the input and output size to use in PROFIBUS network in comparison with EH-RMP. For this reason, the input data of the PROFIBUS network may be rarely affected under noise environment. As measures method under the noise environment, we recommend the following
measures.(1) PROFIBUS cable and signal cables of various input and output modules must be routed in metal duct separated from power cables.
(2) The shield wire of PROFIBUS cable must be grounded both ends.(3) By increasing the capacity of the power supply for the input and output signals, reduce the voltage
fluctuation due to noise.

1.5 Replacement from EH-RMP

Cautions of replacement from EH-RMP are shown below.

Table 1.5-1 Cautions of replacement from EH-RMP

No.	Item	EH-RMP	EH-RMP2	Action
1	Configuration tool	Sycon	SYCON.net	Configurations file is not compatible between
				EH-RMP and EH-RMP2. Please reconfigure
				with use of SYCON.net.
2	Configuration cable	D-sub 9 pin	Type-B USB cable	Please prepare the type-B USB cable.
		serial connector		Type-B USB cable is same as cable of using
				in EHV / EHV+ series.
3	Link parameter of	Sending data area	Sending data area	Please change parameter
	CPU module	is WLx000 to WLx0FF	is WLx000 to WLx1FF	with use of the programming tool.
4	Terminator	Build-in	Not Build-in	Please use a connector
				which has a termination switch.
5	Rotary switch	-	The input / output sizes	Please set rotary switch to "0".
			of PROFIBUS network	
6	Side DIP switch	Output hol	d selecting	Please set same settings.
7	Start-up time	5 second	10 second	Please change user program.
8	LED indications	RDY, RUN, STATUS,	RDY, RUN, ERR,	Please check each application manual.
		ERR, TOKEN	STATUS, REM	



Chapter 2 Specifications

2.1 General Specifications

General specifications are shown in Table 2.1-1. These specifications are common in EH-150 series.

Item	Specifications
Operating ambient temperature	0 to 55 °C
Storage ambient temperature	−10 to 75 °C
Operating ambient humidity	5 to 95 % RH (no condensation)
Storage ambient humidity	5 to 95 % RH (no condensation)
Vibration resistance	Conforms to IEC 60068-2-6
Noise resistance	 Noise voltage 1,500 Vpp Noise pulse width 100 ns, 1µ (Noise created by the noise simulator is applied across the power supply modules input terminals. This is determined by this company's measuring method.) Based on IEC61131-2 Static noise: 3,000V at metal exposed area
Insulation resistance 20 MΩ or more between the AC external and case ground (FE) terminal (based on 500 V DC)	
Dielectric withstand voltage	1,500 V AC for 1 minute between the AC external terminal and case ground (FE) terminal
Grounding	Class D grounding (ground with power supply module)
Usage environment	No corrosive gases, no excessive dust
Structure	Open, wall-mount type
Cooling	Natural air cooling

Table 2.1-1 Ge	neral specifications
----------------	----------------------

2.2 **Functional Specifications**

Functional specifications are shown in Table 2.2-1.

			Table 2.2-1 Functional specification			
Item			Specific	cations		
	nem	l	EH-RMP2 (This product)	EH-RMP (Existing model)		
Cor	Communication protocol		PROFIBUS-DP V0			
Rar	Range of node address		0 to 125: Setting by	configuration tool		
Ma	ximum I/O	size	Input: 512 words, output: 512 words (Setting by rotary switch)	Input: 256 words, output: 256 words		
Cor	nnector		D-sub	9 pin		
Top	oology		BU	JS		
Se Cor	mmunicatio	on cable	PROFIBU	JS cable		
Communication specifi Wa unu	egment length, 9.6 kbps : 1,200 m 'ransmit speed 19.2 kbps : 1,200 m 93.75 kbps : 1,000 m 500 kbps : 400 m 1500 kbps : 200 m 3 Mbps : 100 m 6 Mbps : 100 m 12 Mbps : 100 m 125 slaves 125 slaves Dutput hold Supported (Clear mode, Freeze mode, Copy mode*1)		: 1,200 m : 1,200 m : 1,000 m : 400 m : 200 m s : 100 m s : 100 m s : 100 m s : 100 m			
Cor	Configuration tool		Not built-inBuilt-inSYCON.netSyCon			
Sup	Support CPU module		EH-CPU316A/516/548, EHV-CPU16/32/64/128, EHV-CPU1025/1102			
SE I/O	assignmen	nt	LINK			
icati	mber of	EH-CPU	2 module	es / CPU		
mo	dules	EHV-CPU	8 module	1		
Functional specifications	Self-check		WDT check	WDT check System memory check		
Erre	Error indication		LED			
تتر Cur	Current consumption		780 mA	600 mA		
Star	ndard com	pliant	CE, C-Tick*2 UL, CE, C-Tick			

Table 2.2-1	Functional	specifications
	i unotionui	opoonnoutionio

*1 When using EH-CPU316A, this mode is effective in case that EH-CPU316A ROM version is 02 or higher. *2 UL is not supported. Contact your local supplier for further information.

2.3 Name and function of each part



Description of Connector

Connector	Symbol	Indication		Details									
PROFIBUS			D-sub 9 pin connector. Terminal layouts are shown below.										
				Pin No.	Details								
		Communication connector		1	NC								
				2	NC								
	PROFIBUS			3	B-Line								
				4	NC								
5 9 ()				5 GND 6 +5 V DO 7 NC	GND								
												6	+5 V DC
						7	NC						
					8	A-Line							
				9	NC								

Description of LED display

LED	LED name	Indication	Details				
			Display EH-RMP2 hardware status.				
			State	Details			
		Hardware status	Off	Hardware error			
	RDY	(Green / Red)		Power supply error			
		(Green / Rea)	Flash in green or red	Initialization			
			Lit in red	Hardware error			
			Lit in green	No error			
			Display the EH-RMP2 sy	ystem status.			
			State	Details			
			Off	Power supply error			
			Flash in red	Internal error			
			Lit in red	WDT error			
	STATUS	System status (Green / Red)	Fifth-flash in green	Side DIP switch setting error			
PROFIBUS EH-RMP2			Forth-flash in green	Link parameter error			
			Triple-flash in green	Configuration data error			
RDY RUN ERR			Double-flash in gree	n CPU module error			
STATUS REM			Single-flash in green	n Initialization			
			Lit in green	No error			
			Display PROFIBUS network status.				
			State	Details			
	RUN	Network status (Green)	Off	No communication established			
		(Green)	Blinking	Under communication establishment			
			On	Communication established			
			Display PROFIBUS error status.				
			State	Details			
	ERR	Error status	Off	No error			
	EKK	(Red)	Blinking	Slave units at least one are not established.			
			On*1	All slave units are not established			
	REM	Operating mode (Green)	No use. It is always off.				



In establishing all slave units, Error status LED is lighting for a moment but it is no problem.

The state of LED is indicated below.



Description of Rotary switch

Rotary switch	Symbol	Meaning	Details of setting																					
			The input /	output sizes of PRFOBU	JS network is set by	rotary switch.																		
			Value	Network size	Input size	Output size																		
			0	0 Variable size 512 words m	512 words max	512 words max																		
				64 words	64 words																			
	MODE Input / Output Sizes			128 words	128 words																			
$\begin{pmatrix} 6 & 7 & 8 \\ \hline & & 9 \end{pmatrix}$		Input / Output Sizes	3	256W / 256W fixed	256 words	256 words																		
$MODE\left(\begin{smallmatrix}5\\4\end{smallmatrix}\right) \stackrel{0}{1}$							~ ^										~ ~ ~			4	4	512W / 512W fixed	512 words	512 words
3 2											5													
[Default setting: 0]									6															
				7	Variable size	512 words max	512 words max																	
			8																					
					9																			

Please set rotary switch to 0 if you use auto addressing function with use of the SYCON.net. If you map each slave I/O address including offset address, please set rotary switch value 1, 2, 3 or 4. When actual input / output sizes exceed setting sizes, EH-RMP2 detects error.

Description of Side DIP switch



No.	Setting description				Details
1	No use	Please kee	p off.		
	[Default setting: OFF]	D1			
2	No use	Please kee	p 011.		
3,4	Output hold selecting	When the	CPU is s	witched from RUN to	o STOP position, it can select output status.
	Output hold selecting	Bit4	Bit3	Position	Output hold function selection
	[Default setting: OFF]	OFF	OFF		Clear mode. When the CPU is switched from RUN to STOP position, EH-RMP2 outputs the zero data to PROFIBUS. But the link area (WL) is not cleared.
		OFF	ON		Freeze mode. When the CPU is switched from RUN to STOP position, EH-RMP2 holds output data that is last data received.
		ON	OFF		Copy mode. When the CPU is switched from RUN to STOP position, EH-RMP2 continues to copy in the link area. When using EH-CPU316A, this mode is effective in case that EH-CPU316A ROM version is 02 or higher.
		ON	ON		Don't care.
					·

Chapter 3 Installation

3.1 Mounting Module

(1) Mounting



Figure 3.1-1 Mounting Module

- 1] Hook the lower part of the module to the hole in the base.
- 2] Press in the upper side of the module until it clicks.
- Note 1: Make sure the module is mounted securely.
- Note 2: Slot position of power supply module is fixed as 1st slot of base unit.
- Note 3: Slot position of CPU module is fixed as 2nd slot of base unit.

Modules can be fixed firmly by M4 \times 10mm screws.

(2) Removing



Figure 3.1-2 Removing Module

- 1] Press the lock button.
- 2] With the lock button pressed, pull the top of the module.
- 3] Pull the unit away from the base unit.
- Note: Press the lock button for a power supply module.

3.2 Mountable slots for EH-RMP2

The mounting position of EH-RMP2 is restricted according to CPU module. EH-RMP2 cannot be on expansion base unit regardless of CPU module.

(1) If you use EHV-CPU16/32/64/128 in CPU module.

Maximum 8 link modules (EH-RMP2) can be on base unit. Mountable slot numbers are 0 to 7 as shown in Figure 3.2-1. Please note that EHV-CPU16/32/64/128 cannot mount on old model base unit (EH-BS3, EH-BS5, EH-BS8).



Figure 3.2-1 Mountable slots for EH-RMP2 (EHV-16/32/64/128)

(2) If you use EHV-CPU1025/1102 in CPU module.

Maximum 8 link modules (EH-RMP2) can be on base unit. Mountable slot numbers are 0 to 7 as shown in Figure 3.2-2. Please note that EHV-CPU1025/1102 cannot mount on old model base units (EH-BS3, EH-BS5, EH-BS8).



Figure 3.2-2 Mountable slots for EH-RMP2 (EHV-CPU1025/1102)

(3) If you use EH-CPU516/548 in CPU module.

Maximum 2 link modules (EH-RMP2) can be on base unit. Mountable slot numbers are 0 to 7 as shown in Figure 3.2-3.



Figure 3.2-3 Mountable slots for EH-RMP2 (EH-CPU516/548)

If base unit is old model base units (EH-BS3, EH-BS5, EH-BS8), mountable slot numbers are 0 to 2.

(4) If you use EH-CPU316A in CPU module.

Maximum 2 link modules (EH-RMP2) can be on base unit. Mountable slot numbers are 0 to 7 as shown in Figure 3.2-4.



Figure 3.2-4 Mountable slots for EH-RMP2 (EH-CPU316A)

3.3 Wiring

For information about installation of the PROFIBUS DP fieldbus, please refer to the document *Installation Guideline for PROFIBUS-DP/FMS* from PNO, Order No. 2.112.

PROFIBUS homepage: http://www.profibus.com

3.3.1 PROFIBUS port

EH-RMP2 has D-sub 9 pin female connector for PROFIBUS port.

Terminal layouts are shown below.

	,
Pin No.	Details
1	NC
2	NC
3	B-Line
4	NC
5	GND
6	+5 V DC
7	NC
8	A-Line
9	NC

Table 3.3.1-1 Terminal layouts of EH-RMP2

+5V DC and GND are used for bus termination. Some devices, like optical transceivers (RS-485 to fiber optics) might require external power supply from these pins. In normal applications, PROFIBUS-DP is only used A-Line and B-Line.

3.3.2 Recommended connectors

Recommended connectors of EH-RMP2 are shown below.

Table 3.3.2-1 Recommended co	connectors of EH-RMP2
------------------------------	-----------------------

Manufacturer	Model name	Description
PHOENIX CONTACT	PROFIB/SC2	Angle type
	PROFIB/AX/SC	Straight type



Figure 3.3.2-1 The connector type for EH-RMP2

3.3.3 Cable parameters

The bus cable is specified in EN 50170 part 8-2 as "Cable Type A", and should comply with the parameters in the table below. Cable type B, which is also described in EN 50170, is outdated and should no longer be used.

Parameter	Cable type A
Characteristic impedance	135 to 165 Ω at a frequency of 3 to 20MHz
Operating capacity	< 30 pF/m
Loop resistance	<= 100 Ω/km
Core diameter	> 0.64 mm
Core cross-section*1	> 0.34mm ²

Table 3.3.3-1 Cable parameters

*1 The cable cross-sections used should be compatible with the mechanical specifications of the bus interface connector.

3.3.4 Maximum length of bus segment

Maximum length of bus segment is shown below.

Table 3.3.4-1	Maximum	cable	lengths	per	segment
10010 0.0.1	maximum	oubio	ionguio	POI	ooginon

	Data transfer rate (kbit/s)								
	9.6	19.2	93.75	187.5	500	1500	3000	6000	12000
Max segment length (m)	1200	1200	1200	1000	400	200	100	100	100





19.0 x 19.0 x 30.0mm

Figure 3.3.4-1 Use ferrite core



Chapter 4 Operation

4.1 Start up

To operation this module normally, the making a setup which is shown in the following figure is necessary.

- 1] Set up the DIP switch. Refer to section 4.1.1.
- 2] Set up the Rotary switch. Refer to section 4.1.2.
- 3] Set up the configuration data from configurator. Refer to section 4.1.3.
- 4] Set up the LINK parameter from the programming tool. Refer to section 4.1.4.

4.1.1 DIP switch

EH-RMP2 can be configured to run in different modes depending on the requirements.

The configuration is accomplished by the switch placed on the left side of EH-RMP2.



Figure 4.1.1-1 Side DIP switch

1] The configurations will affect the behavior of the output area when the CPU is turned
from RUN to STOP. The input area are the same in all modes, the entire input area are always copied.
2] Don't operate this switch while EH-RMP2 is working.

(1) Clear mode

When the CPU is switched from RUN to STOP position, EH-RMP2 outputs the zero data to PROFIBUS. But the link area (WL) is not cleared.

Switch	Position	
1	Don't care	4321
2	Don't care	
3	OFF (default)	Z
4	OFF (default)	

Figure 4.1.1-2 Clear mode

(2) Freeze mode

When the CPU is switched from RUN to STOP position, EH-RMP2 holds output data that is last data received.

Switch	Position	
1	Don't care	4321
2	Don't care	
3	ON	S D
4	OFF	

Figure 4.1.1-3 Freeze mode

When the CPU is switched from RUN to STOP position, EH-RMP2 continues to copy in the link area.

This mode is effective when using the EH-150 EH-CPU 308 / 316 ROM version 02 or later.

Switch	Position	
1	Don't care	432
2	Don't care	
3	OFF	6
4	ON	

Figure 4.1.1-4 Copy mode

4.1.2 Rotary switch

The input / output sizes of PRFOBUS network is set by rotary switch.

Value	Network size	Input size	Output size	
0	Variable size	512 words max	512 words max	
1	64W / 64W fixed	64 words	64 words	
2	128W / 128W fixed	128 words	128 words	
3	256W / 256W fixed	256 words	256 words	
4	512W / 512W fixed	512 words	512 words	
5				
6				
7	Variable size	512 words max	512 words max	
8				
9				

Table 4.1.2-1 The input / output sizes of PRFOBUS network

Please set rotary switch to 0 if you use auto addressing function with use of the SYCON.net. If you map each slave I/O address including offset address, please set rotary switch value 1, 2, 3 or 4. When actual input / output sizes exceed setting sizes, EH-RMP2 detects error. (For the offset address, please refer to "4.3 Offset address".)

4.1.3 Configuration from configurator

The configuration of EH-RMP2 is accomplished by the configurator called SYCON.net.

For general information about the configurator, please refer to the manual for this configurator.

PC (Installed SYCON.net)

Figure 4.1.3-1 Configuration from configurator

Online Configuration

Please set up the I/O assignment from a programming tool before configuration.

(1) Set up as shown in Figure 4.1.3-1, turn on power to the EH-RMP2 and connect the USB cable to config port.

(If a power supply is turned ON, with a USB cable connected, it will be detected as a device unknown at Windows.)

(2) Drag the [Profibus DPV0] - [Master] - [NETX 100DP/DPM] to the gray colored bus.

(When coming to the right position, the mouse pointer will change from \bigotimes to \Bbbk_{+} .)

Double click the "netX".

Hereafter the following figure screen is called as main screen.



(3) Configuration dialog appears. Select the "Driver". Check the "netX Driver" and click the "OK" button.

💦 net Device – Confi	guration M	IETX_100_DP_DPM[NETX 10	00 DP/DPM]<1>(#1)			
IO Device: Vendor:	NETX 100 Hilscher (SmbH			Device ID: Vendor ID:	0x0849 0x011E
Navigation Area		СК		Driver		
lange Settings Settings → Driver		Driver	Vers	ion	ID	
netX Driver		3SGateway Driver for net	X (V3.x) 0.9.	1.2	{787CD3A9-4CF6-4259-8E4D-1	09B6A6BEA91}
Device Assign Firmware Down Licensing		netX Driver	1.10)3.2.7743	{B54C8CC7+F333-4135-8405-6	E12FC88EE62}
Coreirsnig Configuration Bus Parameter Process Data Address Table Station Table Master Settings		@Check				
					3clic	k
↓ Disconnected ∩ C	ata Set				ОК Са	ancel Apply Help
NC Disconnected	ata pet					

(4) Double-click the "netX" in the main screen and select the "Device Assignment" on the same dialog as (3).Wait to complete Scan progress.

Select device selection as "all". Then, device appears. Check the device and click the "OK" button.

🛃 netDevice – Configuratio	on NET	X_100_DP_DPM[I	NETX 100 DP/DPM]<1	>(#1)					
Vendor: Hilsd	(100 DP) her GmbH	⊣ @ vv	ait to complet	e Scan	progres	C -	evice ID: endor ID:	0x0B49 0x011E	For
Navigation Area 🗖	/				Device A				
Settings	Scan p	rogress: 3/3 Device	s (Current device: -)						
netX Driver → Device Assignment Firmware Download	D <u>e</u> vice	selection:		- 3Se	elect "all	"			Scan
Licensing		Device	Hardware Port 0/1/2/3	Slot nu	Serial number	Driver	Channel Protoc	ol	Access path
Configuration Bus Parameters		Device Class (- - - -	n/a	5	netX Driver	PROFIBUS-DP N	4aster	¥COM4_cifX0
Process Data									
Address Table									
Station Table		(4) Check							
Master Settings		Geneek							
							0		
							5 Click	ζ	
	Access	path:	(B54C8CC7-F333-4135-840	5-6E12FC88E	E62}¥COM4 cif	X0 Ch0	1		
							-		
							OK Car	ncel App	ly Help
t]⊳ Disconnected 🕕 Data Set									

(5) Right-click the "netX" in the main screen and click the "Network Scan". Then connected modules are found. Click the "Create Devices" button.

PnetDevice - Scan Response of Device: NETX	100_DP_DPM[NETX 100 DP/DPM]K	1>(#1) Channel: /Profibus	
The following hardware-devices have been found during ne Please check automatic selection of corresponding devices f		es' before creating devices.	
Station Addr Device Type ID Sub Device Ty	pe DTM to Use Device Class	DTM Device	Quality Action
▶ 2 3684 (0×00000e64) n/a	Hilscher generic DT Not Specified	EH-IOCP2	[3] Generic four Add
	Information of hardware devic	- Infor	mation from DTM
Device		EH-IOCP2	
DTM ProgId		GSDDTM.DTMDev.1	
Station Address	2		
Vendor	- 0 (0×00000000)	Hitachi-IES	
	3684 (0×00000e64)	3684 (0×00000e64)	
	n/a	n/a	
DTM to Use		Not Specified	
Generic DTM		Yes	
「			
Creation Mode: Use Hilscher generic DTMs if ava	iable 💌	Creat	e Devices Cancel

(6) The following dialog appears after the network scan, click the "OK" button.

netDevice - Upload EH-	IOCP2[EH-IOCP2]<2>	_ []
Configuration Data:	50 60 00 00 00 00 00 00 00 00 00 00 00 00	0 00 00 00
Vailable Modules:		
Module name	Module Configuration Identifier	
Empty slot	0x00	
16 Digital Input (X16)	0x50	
32 Digital Input (X32)	0x51	
64 Digital Input (X64)	0x53	
16 Digital Output (Y16)	0x60	
32 Digital Output (Y32)	0x61	
64 Digital Output (Y64)	0x63	
Configured Modules:	<u>I</u> nsert	Append
S Module name	Module Configuration Identifier	
1 16 Digital Input (X16)	0x50	
2 16 Digital Output (Y16)	0x60	
3 Empty slot	0x00	
4 Empty slot	0x00	
5 Empty slot	0x00	
6 Empty slot	0x00	
7 Empty slot	0x00	
.ength of input/output data:	4 bytes (max. 416 bytes)	Remove
ength of input data:	2 bytes (max. 244 bytes)	
ength of output data:	2 bytes (max. 244 bytes)	
lumber of modules:	22 (max. 22)	
	OK Cancel Apply	Help

NOTE) If network scan is executed when configration is not executed, slots over mountable position are displayed as "Empty". In addition, since "4 Analog Input (X4W)" is recognized as "64 Digital Input (X64)", remove "64 Digital Input (X64)" and add "4 Analog Input (X4W)". (7) The scanned result is displayed in the main screen.

NETY 100 D	P_DPM[NETX 100 DP/DPM]<1>(#1	2
neb x		
	EH-IOCP2[EH-IOCP2]<2>	

- (8) Right-click the "netX" in the main screen and click the "Download".
- The message that the communication between master and slaves stops appears.

Make sure if it's no problem and click the "Yes" button.



Download of configuration is started to netX.

The following screen appears. When downloading is completed, this dialog disappears.

netDevice
Device: NETX_100_DP_DPM[NETX 100 DP/DPM]<1>(#1)
Download active, device performs initialisation
99 % complete
99%
Cancel

NOTE) Upload function is not supported by EH-RMP2.

_	_	-	
N	ETX_100_DP_DPM[NETX :	1(
п	el y		
	Connect		
-	Disconnect		
	Start Debug Mode		
	Download Upload		This is not supported.

(9) After download is completed, save the project file by choosing [File] - [Save as ...]. Comfiguration is completed.

■Offline Configuration

The offline configuration sets a network scan part of the online configuration by manual operation. Please set up the I/O assignment from a programming tool before configuration.

(1) Drag the [Profibus DPV0] - [Master] - [NETX 100DP/DPM] to the gray colored bus.

(If it becomes a position which can be arranged, a mouse pointer will change from \bigotimes to $\stackrel{\triangleright}{\vdash}$.)

Double click the "netX". Hereafter the following figure screen is called as main screen.

SYCON.net - [Untitled.spj]		
<u> F</u> ile <u>V</u> iew <u>D</u> evice Ne <u>t</u> work E _X	tras <u>H</u> elp	
□ ⊯ ⊑ Q ≝ ≝ ;	1. 💿 🖪 3. 3. 3.	
netProject 🔺 🗴	netDevice	× *
Project: Untitled	NETX_100_DP_DPM[NETX 100 DP/DPM]<1>(#1)	AS-i CANopen CC-Link CompoNet Co-Link CompoNet DeviceNet EtherCAT Modbus RTU POWERLINK POWERLINK OPWERLINK OWERLINK OWERLINK OWERLINK OWERLINK OWERLINK OWERLINK OWERLINK WAster Master Master Master Master Master MASTER OWERLINK NHIST-T100-DP/DPM WHIST-T100-DP/DPM WHIST-T100-DP/DPM WHIST-T100-DP/DPM WHIST-T100-DP/DPM WHIST-T100-DP/DPM WHIST-T100-DP/DPM WHIST-T100-DP/DPM Slave Fieldbus / Vendor DTM Class
	ice /	
Ready		Administrator CAP NUM //

(2) Click the [Vendor] tab and drag the [Hitachi-IES] - [Slave] - [EH-IOCP2] to the pink colored bus.

	PSYCON.net - [Untitled.spj]			
ImetDevice ImetDevice ImetDevice I				
Project: Unitiled Project: Unitiled Image: NETX_100_DP_DPM[Ne Image: NETX_100_DP_DPM[NeTX 100 DP/DPM]<1>(#1) Image: NETX_100_DP_DPM[NETX 100 DP/DPM[NETX 100 DP/DPM]<1>(#1) Image: NETX_100_DP_DPM[NETX 100 DP/DPM]<1 Image: NETX_100_DP				
Image: NETX_100_DP_DPM[NE Image: NETX_100_DP_DPM[NETX_100_DP_DPM[NETX_100_DP/DPM]<1>(#1) Image: NETX_100_DP_DPM[NETX_100_DP/DPM]<1>(#1)		netDevice		X
EH-IOCP2[EH-IOC NETX_100_DP_DPM[NETX 100 DP/DPM]<1>(#1) NETX_100_DP_DPM[NETX 100 DP/DPM]<1>(#1) Image: State of the state of			-	
NETX_100_DP_DPM[NETX 100 DP/DPM]<1>(#1) Hitachi-IES EH-IOCP2[EH-IOCP2]<2> ②Drag				Hilscher Gesellschaft fr Systemautor
EH-IOCP2[EH-IOCP2]<2> ②Drag		NETX_100_DP_DPM[NETX 100 DP/DPM]<	>(#1)	⊞ — Hilscher GmbH
EH-IOCP2[EH-IOCP2]<2> ②Drag		net x 🔸		
		EH-IOCP2[EH-IOCP2]<2>	2 Drag	
(Delick				Delick
Fieldbus Vendor (DTM Class)			•	Fieldbus Vendor / DTM Class / F
X				
t Win	t Win			
SYCON.net / netDevice /	SYCON net /net	Pevice /	T	
Ready Administrator NUM				tor NUM

(3) Double-click the "EH-IOCP2" in the main screen. Configuration dialog appears, click the "Modules". Next, select the modules that are mounted in EH-IOCP2 base from the "Available Modules", and then click the "Insert" button, please add to the "Configured Modules". Click the "OK" button at the end. It is possible to select the 22 modules maximum, select the "Empty slot" in empty slot part.

(The figure below shows an example that slot 0 is 16 points input, slot 1 is 16 points output.)

🅐 net Device – Configurati	ion EH-IOCP2[EH-IOCP2]<2>						
IO Device: EH-	-IOCP2				Device ID:	0x0E64	
	achi-IES	OCalast			Vendor ID:	-	P
ſ	Click	² Select					
	CHCK	/					
Navigation Area				Modules			
Configuration	Available Modules:						
General 🖌	Module	Inputs	Outputs	In/Out		Identifier	
Signal Configuration	📕 Emptyslot	0 0	0		×00		
Parameters		2 0	0		×50		
Groups	I+I 32 Digital Input (X32)	4 0	0		×51		
Extensions	i+i 64 Digital Input (X64)	8 0 0 2	0		×53 ×60		
DPV1	III 16 Digital Output (Y16)	0 2	0		×61		ck
DPV2	I+I 64 Digital Output (Y64)	0 8	0		×63	ĭ	
Redundancy	I+I 16/16 Digital In/Output (B1/	0 0	2		×70		_
🔄 Device Description	1 · · · · · · · · · · · · · · · · · · ·	4 Addit	ion .				
Device	Configured Modules:	Auun	1011			<u>I</u> nsert	Append
GSD	Slot Module	Inputs	Output	s In/Out	t [Identifier	
	▶ I+I 1 16 Digital Input (×16)		0	0	0×50		
	14 2 16 Digital Output (Y1		2	0	0×60		
	I+I 3 Empty slot	0	0	0	0×00		
	I+I 4 Empty slot	0	0	0	0×00		
	I∔I5 Emptyslot I∔I6 Emptyslot	0	0	0	0×00 0×00		
	1+1 7 Empty slot	0	0	0	0×00		
				÷			
	Length of input/output data:	4 bytes (max. 416					<u>R</u> emove
	Length of input data: Length of output data:	2 bytes (max. 244) 2 bytes (max. 244)			5Clicl	7	
	Number of modules:	22 (max. 22)	Jytes)			x	
		22 (110/1 22)					
						1	- I I
					OK	Cancel Apply	Help
🛟 Disconnected 🚺 Data Se	et 🖉						

(4) Set up as shown in Figure 4.1.3-1. After turning on the power of EH-RMP2, connect the USB cable to config port. (If a power supply is turned ON, with a USB cable connected, it will be detected as a device unknown at Windows.)

(5) Double-click the "netX" in the main screen and click the "Driver".

Check the "netX Driver" and click the "OK" button.

PnetDevice - Config	uration NET	X_100_DP_DPM[NETX 100 DP/DPM]<1>	(#1)		_ 🗆 ×
IO Device: Vendor:	NETX 100 DP Hilscher Gmb	/DPM		Device ID: Vendor ID:	0x0849 0x011E
Navigation Area			Drive		
Settings		Driver	Version	ID	
netX Driver		3SGateway Driver for netX (V3.x)	0.9.1.2	{787CD3A9-4CF6-4259-8E4D	109B6A6BEA91}
Device Assignm	ent 🗹	netX Driver	1.103.2.7743	{B54C8CC7-F333-4135-8405-	6E12FC88EE62}
Firmware Downl	oad 💦 🤻				
Licensing		² Check			
Bus Parameters		2 CHECK			
Process Data					
Address Table Station Table					
Master Settings					
				3Clic	C
				— <u> </u>	
					·
				ОК	Cancel Apply Help
📢 Disconnected 🚺 Da	ita Set				

(6) Double-click the "netX" in the main screen and select the "Device Assignment" on the same dialog as (5).

Wait to complete Scan progress.

Select device selection as "all". Then, device appears. Check the device and click the "OK" button.

	ion NETX TX 100 DP/I scher GmbH	OPM 2W	NETX 100 DP/DPM]<1 ait to complet		progres	s.	Device ID: Vendor ID:	0x0B49 0x011E	
Navigation Area Settings Settings Driver netX Driver ⇒ Device Assignment Firmware Download	Scan pr		s (Current device: -)	- 3Se	Device A				Scan
Licensing Configuration Bus Parameters Process Data Address Table Station Table Master Settings		Device Device Class (Check	Hardware Port 0/1/2/3 -/-/-/-	Slot nu	Serial number	Driver netX Driver	Channel Proto		Access path
{β⊳ Disconnected ∩ Data St	Access	path:	(B54C8CC7+F333-4135-840	95-6E12FC88E	E62}¥COM4_cif	X0_Ch0	(5) Clic	K ncel App	ly Help

(7) Right-click the "netX" in the main screen and click the "Download".

The message that the communication between master and slaves stops appears.

Make sure if it's no problem and click the "Yes" button.



Download of configuration is started to netX.

The following screen appears. When downloading is completed, this dialog disappears.

netDevice					
Device: NETX_100_DP_DPM[NETX 100 DP/DPM]<1>(#1)					
Download active, device performs initialisation					
99 % complete					
99%					
Cancel					

NOTE) Upload function is not supported by EH-RMP2.

	_
NETX_100_DP_DPM[NETX]	1
Connect Disconnect	
Start Debug Mode	
Download Upload	— This is not supported.

(8) After download is completed, save the project file by choosing [File] - [Save as ...]. Comfiguration is completed.

1] When EH-RMP2 is power on while connect to PC, PC indicates "unknown USB device".
 When EH-RMP2 is power on while connect to PC, PC indicates "unknown USB device". EH-IOCP can't be supported auto module configuration.

4.1.4 Configuration from programming tool

EH-RMP2 operates in the EH-150 system as a link module. The link area of EH-RMP2 is allocated from one nearer to CPU module.

The output area of EH-RMP2 must be fixed 512 words and the output area start address must be fixed 0.

The link parameter is set by programming tool which is different depending on CPU module.

Operation Parameter	×
Operation Control	Transmission Mode in Error Condition
C Definition of Input(E)	Remote I/O Assign(R): Not Transmit 💌
Input I/O No.(D):	Remote Substation Error(C): Not Transmit 💌
Delay Check Time Setting Value(): 10 X10ms	CPU Link Parameter ✓ No.1 Link(1)
Operation Mode in Error Condition	Top Assign No.(S) WL 0 Last Assign No.(E) WL 1FF
I/O Assign Unmatched(): Not Operate Add Unit Error(U): Not Operate	▼ No.2 Link(2) Top Assign No.(A) WL 1000
Remote Error(M): Not Operate 💌	Last Assign No.(N) WL 11FF
	Execute(X) Cancel

Figure 4.1.4-1 The link parameter setting by LADDER EDITOR

Sending Area Se Send data	From	То	Clear at RUN/STOP
🔽 No.1 Link(<u>1</u>)	WL 0 0	WL 0 1FF	Clear
No.2 Link(<u>2</u>)	WL 1	WL 1	Clear
No.3 Link(<u>3</u>)	WL 2	WL 2	Clear
No.4 Link(4)	WL 3	WL 3	Clear
No.5 Link(5)	WL 4	WL 4	Clear
No.6 Link(6)	WL 5	WL 5	Clear
No.7 Link(<u>7</u>)	WL 6	WL 6	Clear
No.8 Link(<u>8</u>)	WL 7	WL 7	Clear

Figure 4.1.4-2 The link parameter setting by Control Editor

Parameter	Туре	Value	Default Value	Unit	Description
🐡 🖗 LINK area %MW-address	WORD	0	0		LINK memory can be accessed by %M vari
🔷 🖗 Writing area %MW-addre	ss WORD	0	0		Beginning from this address module is acce
🔷 Writing area size	WORD	512	0		Size of module memory which is accessible

Figure 4.1.4-3 The link parameter setting by EHV-CODESYS
Input area and output area are used from 0 to 512 words.



Figure 4.1.4-4 Using area of EH-RMP2 in the link area

4.2 Data format

The data format of EH-RMP2 outputs in PROFIBUS network is shown below.



Figure 4.2-1 Byte data format for byte oriented slave module





netDevice - Configuration NE	ETX_100_DP_DPM[NETX 100 DP/DPM]<				
IO Device: NETX 100 Vendor: Hilscher 0) DP/DPM SmbH		Device ID: Vendor ID:	0x0B49 0x011E	Tda
Navigation Area 🗖		Master Settings			
 Settings Driver netX Driver Device Assignment Firmware Download Configuration Bus Parameters Process Data Address Table Station Table Master Settings 	Start of bus communication Image: Controlled by application Application monitoring Watchdog time: 1000 ms Process image storage format Image: Image Big Endian (MSB first) Image: Uttle Endian (MSB first) Advanced Image: Enable configuration download during net Device status offset	Module Alignment			
	Automatic calculation Static: Starts Urrent offset address is:	tes after last input data			
√▷ Disconnected 0 Data Set			ОК	Cancel App	y Help
Usconnected U Data Set					///

If you want to swap I/O data, change parameter "Process image storage format" with use of the SYCON.net.

Figure 4.2-3 Byte swap

4.3 Offset address

EH-RMP2 can use offset address with use of the SYCON.net.



Figure 4.3-1 Offset address

If you want to include offset address, change address table with use of the SYCON.net.

- Remove the check of Auto addressing
- Change the address in slave

IO Device: NETX 10 Vendor: Hilscher	00 DP/DPM r GmbH			Device ID: Vendor ID:	0x0B49 0x011E		F
Navigation Area 📃			Address Tab	e			
∃ Settings	✓ <u>A</u> uto addressing leputs:		Display mode:	Decimal	•	<u>C</u> SV Exp	ort
netX Driver Device Assignment Firmware Download Configuration Bus Parameters Process Data	Station Add Di 2 EH-IOCP2 2 EH-IOCP2	evice Name EH-IOCP2 EH-IOCP2 I/L300P Inverter Hitachi SJ300		odule T 1 word input IW 2 word input IW 2 word input IW	ype Lengt	th Addr 1 2 2	ess
➡ Address Table Station Table	Outputs:						
Address Table	Station Add Do		lame	Module	Туре	Length A	ddress
Address Table Station Table	Station Add Di	EH-IOCP2		1 word outpu	ut QW	1	ddress
➡ Address Table Station Table	Station Add Di				ut QW	Length A 1 2	ddress

Figure 4.3-2 Address table setting

Chapter 5 Indications

The EH-RMP2 can give indications to the user in two different ways. The first way is via the four indications LED at the top of the module and the second way is via the special internal output of EH-CPU / EHV-CPU or use function block for EHV+, where detailed information about the PROFIBUS-DP network is available for the PLC programmer.

5.1 LED Indications

The LED indications are placed at the top of this module.



Figure 5.1-1 LED indications

5.1.1 RDY LED

The RDY LED will give information about the hardware state of the EH-RMP2

The LED will flash red or green different times depending on the hardware status indicated.

(a) No error.

When the EH-RMP2 is initialized, the RDY LED is constantly lit in green.

Color: Green



(b) Hardware error.

When the EH-RMP2 broke, the RDY LED is constantly lit in red. If hardware error occurred, please change EH-RMP2 to spare module.

Color: Red



(c) Power supply error.

As it is possible that EH-RMP2 is not being supplied power, please check power supply. If EH-EMP2 had been supplied power, EH-RMP2 may be hardware error. Please change EH-RMP2 to spare module. Color: -

5.1.2 STATUS LED

The STATUS LED will give information about the system status of EH-RMP2.

The LED will flash red or green different times depending on the status indicated.

(a) No error.

When the EH-RMP2 is normal operation, the STATUS LED is constantly lit in green.

Color: Green



(b) Initialization.

When EH-RMP2 has not finished initialization, the STATUS LED is single-flash in green. Set the I/O assignment of the CPU module.

Color: Green



(c) CPU module error.

When the CPU module detects errors, the STATUS LED is double-flash in green. Clear errors of the CPU module.

Color: Green



(d) Configuration data error.

When the configuration data of EH-RMP2 is not matched between set data and actual network data, the STATUS LED is triple-flash in green. Configure correct data with use of the SYCON.net.

Color: Green



(e) Link parameter error.

When the CPU module link parameter is not correct, the STATUS LED is forth-flash in green. Set the address in the CPU module link output area to 0 to 512(H00 to H1FF)

Color: Green



(f) Side DIP switch error

When the setting of side DIP switch of EH-RMP2 is wrong, the STATUS LED is fifth-flash in green. Please set EH-RMP2 side DIP switch to correct setting

Color: Green



(g) WDT error.

When EH-RMP2 detects WDT error, the STATUS LED is lit in red. Please change EH-RMP2 to spare module. Color: Red



(h) Internal error.

When EH-RMP2 detects internal error, the STATUS LED is flash in red. Please change EH-RMP2 to spare module.

Color: Red

(i) Power supply error.

As it is possible that EH-RMP2 is not being supplied power, please check power supply. If EH-EMP2 had been supplied power, EH-RMP2 might detect hardware error. Please change EH-RMP2 to spare module. Color: -



Color: Green



(b) Checking PRFOIBUS-DP network.

The RUN LED is blinking during checking PROFIBUS-DP network.

Color: Green



(c) No communication established.

When slave units at least one are not established, the RUN LED is OFF.

Color: Green

5.1.4 ERR LED

(a) No error.

When all slave units are established, the ERR LED is OFF.

Color: Red

(b) Slave units at least one are not established.

When slave units at least one are not established, the ERR LED is blinking.

Color: Red



(c) All slave units are not established.

When all slave units are not established, the ERR LED is lit in red.

Color: Red



5.2 Link information flag area

In the Link information flag area, programming tool can get valuable information about the PROFIBUS-DP fieldbus.

The method to get information is different depending on programming tool.

5.2.1 Get link information

(1) If you use LADDER EDITOR (CPU module is EH-CPU316A/516/548).

The LADDER EDITOR can get the link information with use of special internal output.

OFFSET address (word)

Start address of LINK No.1: WRF0E0

Start address of LINK No.2: WRF140

15	14	13	12	11	10	9	8		6	5	4	3	2	1		\rightarrow
			Rese	erved							Error					+00
							Reserve	ed								+01
							Reserve	ed								+02
							Reserve	ed								+03
		Main	state of		system					0	Global e		ts			+04
Reserved Reserved										+05						
Heavy bus error count									+06							
Number of rejected PROFIBUS telegrams									+07							
							Reserve									+08
							Reserve									+09
							Reserve Reserve									+0A +0B
15		r	1	T	1	Т	Reserve		r –	T	T		Г	1	0	+0B $+0C$
31															16	+0C +0D
47															32	+0D +0E
63				+		1	Slave	Config	I	+			+	+	48	+0E
79							Shave								64	+10
95															80	+11
111															96	+12
-	126														112	+13
15															0	+14
31															16	+15
47															32	+16
63							Slav	e State							48	+17
79															64	+18
95															80	+19
111															96	+1A
-	126														112	+1B
							Reserve									+1C
							Reserve									+1D
							Reserve									+1E
							Reserve									+1F
							Reserve									+20
							Reserve									+21 +22
							Reserve									+22 +23
							Reserve									+23 $+24$
							Reserve									+24 +25
							Reserve									+23 $+26$
			Devic	e error			110301 10				Rese	rved				+20
			Devic				Reserve	ed			Rese	1700				121
					1			max (m	s)							+5D
								min (m								+5E
								now (m								+5F

Table 5.2.1-1 Contents in the LINK information flag area

(2) If you use Control Editor (CPU module is EHV-CPU16/32/64/128).

The Control Editor can get the link information with use of special internal output.

OFFSET address (word) Start address of LINK No.1: WRF0E0 Start address of LINK No.2: WRF140 Start address of LINK No.3: WRF1A0 Start address of LINK No.4: WRF200 Start address of LINK No.5: WRF260 Start address of LINK No.6: WRF2C0 Start address of LINK No.7: WRF320 Start address of LINK No.8: WRF380

Table 5.2.1-2 Contents in the LINK information flag area

				10010	5.Z. I-Z	0011101			mom		ing are	u				
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
			Rese	rved							Error	code				+00
]	Reserve	d								+01
							Reserve									+02
]	Reserve	d								+03
		Main	state of 1		/stem					C	Hobal e		s			+04
			Rese	rved							Rese	rved				+05
Heavy bus error count										+06						
Number of rejected PROFIBUS telegrams										+07						
Reserved										+08						
Reserved										+09						
							Reserve									+0A
			T]	Reserve	d			1				1	+0B
15															0	+0C
31						<u> </u>						ļ	ļ		16	+0D
47			ļ												32	+0E
63							Slave	Config	1						48	+0F
79															64	+10
95						-									80	+11
111	101														96	+12
-	126														112	+13
15															0	+14
31															16	+15
47 63							Classe	Ctata							32 48	+16
63 79							Slave	State	1						48 64	+17 +18
95															64 80	+18 + 19
95															80 96	+19 +1A
	126					-				+		-	-		112	+1A +1B
-	120					<u> </u>	Reserve	d							112	+1D +1C
							Reserve									+1C +1D
							Reserve									+1E
							Reserve									+1F
							Reserve									+20
							Reserve									+21
							Reserve									+22
							Reserve									+23
							Reserve									+24
							Reserve									+25
							Reserve									+26
]	Reserve	d								+27
]	Reserve	d								
					F		ng time		s)							+5D
					I	Refreshi	ng time	min (m	s)							+5E
					F	Refreshi	ng time	now (m	s)							+5F

(3) If you use EHV-CODESYS (CPU module is EHV-CPU1025/1102).

The EHV-CODESYS can get the link information with use of function block "GetProfibusInfo".

	GetProfibusIn	fo
	-byLinkNo BYTE	BOOL xDone
		BOOL xError
	Pro	<i>fibusInfo</i> ProfibusInfo
STRUCT ProfibusInfo:	wErrorCode (WORD)	
	byMainState (BYTE)	
	byGlobalErrorBits(BYTE)	
	byErrorNumber (BYTE) <no use=""></no>	
	byErrorRemoteAddress (BYTE) <no< td=""><td>use></td></no<>	use>
	wHeavyBusErrorCount (WORD)	
	wNumRejectedProfibusTelegrams (W	/ORD)
	wSlaveConfig0_15 (WORD)	
	wSlaveConfig16_31 (WORD)	
	wSlaveConfig32_47 (WORD)	
	wSlaveConfig48_63 (WORD)	
	wSlaveConfig64_79 (WORD)	
	wSlaveConfig80_95 (WORD)	
	wSlaveConfig96_111 (WORD)	
	wSlaveConfig112_127 (WORD)	
	wSlaveState0_15 (WORD)	
	wSlaveState16_31 (WORD)	
	wSlaveState32_47 (WORD)	
	wSlaveState48_63 (WORD)	
	wSlaveState64_79 (WORD)	
	wSlaveState80_95 (WORD)	
	wSlaveState96_111 (WORD)	
	wSlaveState112_127 (WORD)	
	wDeviceError (WORD) <no use=""></no>	
	wRefreshingTimeMax (WORD)	
	wRefreshingTimeMin (WORD)	
	wRefreshingTimeNow (WORD)	

5.2.2 Detail of each information

The following error codes can be present in this register.

Value	Description					
Hex 00	No error					
Hex 01	Failed to initialize PROFIBUS-DP master.					
Hex 02	Start address of link area in the PLC is not zero.					
Hex 03	The link length configured in the PLC is different from 512 words.					
Hex 06	Internal Error on PROFIBUS-DP master.					

⁽a) Error Code.

(b) Main state of master system.

This register contains information about the state of the master system. The following states can be present.

Value	Description
Hex 00	Off-line
Hex 40	Stopped
Hex 80	Clear
Hex C0	Operate

(c) Global error bits.

Details of global error bits are shown below.

Bit number	Description
7-6	Reserved
5	1 = HOST is not ready
5	0 = Normal operation
4	1 =Bus short circuits detected
4	0 = Normal operation
3	1 = Because of heavy bus error, no further bus communication is possible
5	0 = Normal operation
2	1 = At least one slave is not in the data exchange mode or reports fatal error
2	0 = Normal operation
1	1 = The master branched into auto clear mode because of a slave error
1	0 = Normal operation
0	1 = A parameter error occurred
0	0 = Normal operation

Table 5.2.2-3 Global error bits

(d) Heavy bus error count.

This register is incremented if there for example is a short circuit on the bus cable.

(e) Number of rejected PROFIBUS telegrams.

(f) Slave Config.

This 16 bytes bit-field indicates if a node is configured in the master or not. Address bit 0 corresponds to node address zero, bit 1 corresponds to node address 1 and so on. If the bit is 1, the corresponding node is configured otherwise the node is not configured.

(g) Slave State.

This 16 bytes bit-field indicates if a node is active in the data exchange or not. Address bit 0 corresponds to node address zero, bit 1 corresponds to node address 1 and so on. If the bit is 1, the corresponding node is active in the data exchange otherwise the node is not active.



Chapter 6 Troubleshooting

6.1 Error indications of EH-RMP2

Error indications of EH-RMP2 are shown below.

Table 6.1-1	Error	Indications	of	EH-RMP2
-------------	-------	-------------	----	---------

LED	Indicate pattern	Description	Actions
RDY PROFIBUS EH-RMP2 RDY RUN ERR STATUS REM	OFF	Hardware error Power supply error	•Check power of power supply module •Replace EH-RMP2
	Lit in red	Hard ware error	•Replace EH-RMP2
STATUS PROFIBUS EH-RMP2 RDY RUN ERR STATUS REM	OFF	Power supply error	Check power of power supply module
	Flash in red	Internal error	Replace EH-RMP2
	Lit in red	WDT error	Replace EH-RMP2
	Fifth-flash in green	Side DIP switch setting error	Check the side DIP switch.
	Forth-flash in green	Link parameter error	Set CPU module link output area address to 0 to 512
	Triple-flash in green	Configuration data error	 Check the connection of the communication cable Configure correct data with use of the SYCON.net
	Double-flash in green	CPU module error	Clear error of the CPU module
	Single-flash in green	Initialization	Set the I/O assignment of the CPU module.
RUN PROFIBUS EH-RMP2 RDY RUN ERR STATUS REM	OFF	No communication established	 Check the connection of the communication cable Check system and node address and push reset switch of EH-RMP2
ERR PROFIBUS EH-RMP2 RDY RUN ERR STATUS REM	Blinking	Slave units at least one are not established	 Check the connection of the communication cable Check system and node address and push reset switch of EH-RMP2
	Lit	All slave units are not established	 Check the connection of the communication cable Check system and node address and push reset switch of EH-RMP2

6.2 New entry of slave unit to PROFIBUS

New entry of slave unit to PROFIBUS, slave units may fall to enter PROFIBUS communication, when new entry or restarting from communication error.

In this case, reboot the slaves that do not online.

6.3 Startup time of EH-RMP2

It takes approximately 10 seconds until EH-RMP2 starts I/O communication with the slave devices after the initialization since EH-RMP2 can deal with large size input / output data.

Therefore, please not use input / output data of EH-RMP2 until the bits of all using slave state are 1 in the LINK information flag area.