# **Cortex-M3 107 Development Board** User's Manual



### 1, Chapter 1 Hardware Articles

1.1 Golden Dragon STM 32F 107VCT6 development board Introduction Golden Dragon 107 development board embedded with STM 32F
107VC STMicroelectronics, launched new STM32 interconnect type(connectivity) family of microcontrollers in a strong performance, this chip integrates a variety of high-performance industry-standard interface, and STM32 different types of products are perfect in pin and software compatibility, you can easily adapt to more applications. The new STM32 standard peripherals include 10 timers, two 12 M sample / s AD (analog-to-digital converter) (rapidly alternating mode 2M sample / s), two 12-bit DA (digital-to-analog converter), two I 2C interface, five USART interfaces and three SPI ports and high-quality digital audio interface IIS, STM 32F 107 has a full-speed USB (OTG) interface, two CAN2.0B interface, and Ethernet 10/100 MAC modules. This chip can meet the industrial, medical, building automation, home audio and home appliance market a variety of products needs!

1.2 Developer-board resources

STM 32F 107VCT6, ARM Cortex-M3 core, clocked at 72MHz, contains an internal 256K bytes of FLASH and 64K bytes of SRAM

A 10M / 100M Ethernet interface, standard RJ45 interface, support for parallel adaptive crossover cable

One USB 2.0 OTG full-speed interface, as a USB slave, also can be used as USB HOST

A standard 3.2 / 4/5/7 inch TFT LCD interface with touch screen

An I2S audio decoder chip WM8978, music player supports MP3 software solution, high-quality

An FM radio chip TEA5767

2 headphone jack

An SD card interface

A 2.4G wireless communication module interface

An infrared receiver head

A camera interface, optional OV7670 module

A temperature sensor interface, optional DS18B20

Two CAN bus interface

An RS485 interface

An RS232 serial port, DB9 total

A USB to serial chip PL2303 notebook easier to use

An SPI FLASH chip, W25Q16, more convenient storage fonts

An IIC interface EEPROM chip, 24c 02, capacity 2K

1 small speaker

A reset button to control the entire board hardware reset

4 function buttons, including the the WAKEUP wake-up function and Temper invasion of function

A five keys

A power indicator, LD2, red

4 user status indicator, LD1, LD3, LD4, LD5 red

2 startup mode select Configure port

An RTC real time clock backup battery holder

1 standard JTAG / SWD Emulator Debugger download interface

The way potentiometer adjustable resistance analog input, you can do the analog-to-digital conversion experiments

A digital-to-analog converter DAC interface is connected to the terminals

An ADC analog-to-digital conversion interface is connected to the terminals

A PWM interface is connected to the terminals

A DC5V Power Interface

A power switch that controls power to the entire board.

In addition to the the crystal occupied IO pin, all the other IO ports lead to the extended double pin

### 2, Chapter 2 Thematic Explanation

2.1 Theme I: MDK install and download

In Web Search "Red Dragon development board Lecture1"

Note that has several different points:

Red Dragon is 104 pin STM32F103ZE, while Golden Dragon is stm32f 107vc, so there are several differences as following of choosing chip

a. select chip, select STM32F107VC,



b. macro defined (library, if not the library,then it can be ignored), the difference is mainly between the \* \_CL and \* \_HD

Device Target Output Listing Vs	er C/C++ Asm Linker Debu	ıg [Vtilities]
Preprocessor Symbols Define: USE_STDPERIPH_DRIVER Undefine:	R, STM32F10X_CL	
Language / Code Generation		
	Strict ANSI C	<u>W</u> amings:
Optimization: Level 0 (-O0)	Enum <u>C</u> ontainer always int	All Warnings 💌
Coptimize for Time	Plain Char is Signed	Thursda Manda
Split Load and Store Multiple	🔲 Read-Only Position Independent	Thum <u>b</u> Mode
✓ One ELF Section per Function	Read-Write Position Independent	t
Include Paths <u>M</u> isc Controls	iIS\CoreSupport;\Libraries\CMSIS\Device	eSupport;\Libraries\StdPeripl
	ROLIB -g -O0apcs≕interworksplit_sectio port -I\Libraries\CMSIS\DeviceSupport -I	

### c. flash

Debug Trace Flash Downloa Download Function COAD Erase Full Chip Erase Sectors Do not Erase Programming Algorithm	Program	RAM for / Start:	Algorithm Dx20000000 Size: Dx0800
Description	Device Type	Device Size	Address Range
STM32F10x Connectivity Lin	On-chip Flash	256k	08000000H - 0803FFFFH
		Start:	Size:
	Add	Remove	

Flash choose 256k

### 2.2 Theme II: JFLASH use

Tip: If you use this method to download, please try power-off and power-on test again, when comes to the interrupted program it must be repower-on.

2.21: J flash install:

Software in the CD-ROM CD-ROM directory

Golden Dragon 107 development board  $\setminus$  5. Install the Sofware  $\setminus$  JLINK simulation drive

Click .exe file and it can run directly ,next, to the new online version, Baidu and Google can receive



Click j-stuff ARM to open software and interface, similar to the above, as shown

#### 2.22jflash open

JASH SEGGER J-F1	ash AR	V4.41b (	(beta) -	[C:\Program Files\SEGGER\JLinkABM_V441b\Samples\JFlash\Project	IX
<u>F</u> ile <u>E</u> dit <u>V</u> ier	v <u>T</u> arget	<u>O</u> ptions	<u>W</u> indow	Help	
Name Connection Target interface Init JTAG speed JTAG speed TAP number IRPre MCU Endian Check core Id Core Id Use target RAM RAM address RAM size Flash memory Manufacturer Size Flash Id Check flash Id Base address Organization	Value USB [Dev JTAG 200 kHz 12000 kH (not used (not used (not used ST STM3: Little Yes 0x38A004 Yes 0x200000 64 KB	z >> 2F103√E 77 00 0xxE interne		SEGGER	
Application log - J-Flash ARM 1 - JLinkARM.dll Reading flash d - List of flash Reading MCU dev - List of MCU	V4.41b (J- V4.41b () evice list h devices ice list devices ro	DLL compi] t [C:\Prog read succ [C:\Progra ad succes	led Dec 2 gram File cessfully am Files\; ssfully (	c 21 2011 19:08:21) 1 2011 19:07:35) \$\SGGER\JLinkkRM_V441b\ETC\JFlash\Flash.csv] (1028 Devices) \$EGGER\JLinkkRM_V441b\ETC\JFlash\MCU.csv] 1058 Devices) \$ER\JLinkARM_V441b\Samples\JFlash\ProjectFiles\AT91SAM7S64.jflash]	
Ready					

2.2.3jflash configuration1. Select chip: shortcut keys alt-f 7 following interface pops up

roject settings		?)
General Target Interface CPU	Flash Production	
jilink	J-Flash-ARM is a software for J-Link ARM. It requires a license, which can be obtained from SEGGER (www.segger.com). This software is capable of programming the flash memory of several ARM micros, as well as external Flash connected to ARM cores.	
	Connection to J-Link   Cuse Device 1  USB SN  USB SN  Cuse Select  Cuse Contended for the select  Cuse Select	
User interface <u>m</u> ode <u>Engineering</u> (More options, typi	ically used for setup)	
Simplified (Less options, typical	lly used for production)	

Click the label target interface, here, to select SWD or JTAG, if one can not, try the other one, keep the other one default, and then click on the CPU tab, set the following figure

Project settings	2 ×
General Target Interface CPU Flash Production	
Use J-Link script file	
Core     Little endian	
Use target <u>B</u> AM (faster) Addr 20000000 48 KB <	

### And then OK to exit

Then click on target-> Connect, and then output the following prompt, indicating that the connection is successful (the premise is pluging the jlink board power supply, can not be used ulink)



Bottom is the connection success tips

Then click the file to select the file you want to download it, if it is hex file can be downloaded directly, if it is a bin file, according to the project's settings, select the address of the bin file download

Then press f7 it can automatically erase and download the following is the success of the interface, now you can re-power.

J-Flash	ABN ¥4.41b		×
į)	Target erased,	programmed and verified successfully - Completed after 1	.2.569 sec
		<u> </u>	

2.3 Theme III: serial download

Serial download: This method is slow, there may be an error, it is recommended to use jlink

2.3.1 Installing the software

Cortex-M4 107 development board to install the Sofware \ISP Download  $\setminus$  ST original  $\backslash Um0462$ 

Or directory

 $\label{eq:cortex-M4 107 development board \ 5. Install the software-Software \ Flash\_Loader (ST official serial download tools)$ 

Recommended to download new version

Click Install

Click the flash loader demo to open software

	Flash Loader Demonstrator
	STMicroelectronics
	Select the communication port and set settings, then click next to open connection.
	Common for all families
	• UART
	Port Name COM2   Parity Even
1	Baud Rate 14400 💌 Echo Disabled 💌
	Data Bits 8 🔽 Timeout (s 10 💌
	Back Next Cancel Close

The port name you plugged into the development board serial number, baud rate, the best from 115,200 down, keep the default, this time need to set up a development board jumper

B oot1 ,2-3

B oot0 ,1-2

J p10 ,2-3

J p11 ,2-3

9-pin serial port plugged into the development board

Reset the board, click on the next following interface



The development board is not set up correctly, When the following interface, complete.

4	Flash	Loader Demon	strator		
	S	TMicroe	electro	nics	
F					
	<b>*</b>	Carget is reada	ble. Please	click "Next" to	proceed.
	~				
				Remon	ve protection
				ibelli 0 v	e procección
	Flash	256	KB		
		Back	<u>N</u> ext	Cancel	<u>C</u> lose

If you can not get out, you can only download with the serial port 2, set the jumpers JP3 is 2-3, and then plug in the usb cable to the USB-1, and then close the software, and re-open, and then press the reset button (must) software next will appear at the interface, and then click next to the next step, next step has been to the following interface

📌 Flash Loader Demonstrator
STMicroelectronics
C Erase
© All C Selection
Download to device Download from file
💽 Erase necessary pag 🌔 No Erase 🌀 Global Eras
@ 8000000  Jump to the user progr: Optimize (Remove some FFs)  Verify after download
Apply option by
C Upload from device Upload to file
Enable/Disable Flash protection
ENABLE WRITE PROTECTION
C Edit option bytes
Back Eacel Close

Here Download FROM file select the file you want to download and select full chip erase, or erase that need to erase, other default, and then next download After the success

#### 2.4 Theme IV: DFU use

First of all we need to first understand the DFU concept, Baidu search "stm32 DFU" or "DFU"

S TM32 dfu, simple saying, first with jlink or the ulink or serial, the period of application programmed into the flash start address (address) the program begins execution, this code by judge things, determined to run the application, or enter download mode

### 2.4.1 Installing the PC DFU software

Wang Bao-GoldDragon Golden Dragon 107 development board  $\setminus$  5. Install the software-Sofware  $\setminus$  DfuSe, I hope you look the official manual about the use of dfu below

After the software is installed, you will need to download a period equivalent to the bootloader program to the development board (must)Then set jumper jjp10, JP11 to 1-2 do usb

Plug in the mini usb cable to USB2, you need to install the driver, (Reference UM0412\_DFUSe "in the CD-ROM search) 1.3.2 Hardware installation After installation,

Device Manager the STM Device in DFU mode, to prove that the installation was successful (We are into DFU mode by default, you can view)



The line 58 M ain.c file modify

At this point we need to make DFU file First, open the DFU file management software



Select a point ok, go to the next interface

🍄 DFU File ∎anager (v3.0	.2) - Generation
Vendor ID 0x 0483 Product ID 0x 0000 Version 0x 0000	Images         Injection         Target ID:       0         S19 or Hex       Multi BIN         Target Name:       ST         Deletion       Delete selected Image
	<u>G</u> enerate <u>C</u> ancel

Point S19 or hex, you need to determine the execution address can not cover the address of the bootloader, or dfu can only be used once, and the program may not work properly, the compile-time address needs to be set to 0x08003000, because this is the address of the procedures defined at compile time, change addresses need to pay attention to the scale, and settings ect., select compiled hex file Click generated to produce the DFU file, we need to exit the soft Hex file produced using the following method

🔣 Option	as for	Target 'LEI	r i						×
Device	Target	Output Lis	ing User	с/с++   и	lsm I	inker	Debug   Vtili	ties	
STMicro	STMicroelectronics STM32F103VC <u>X</u> tal (MHz): 8.0 Code Generation								
Operatir	ig system:	None		•	🔲 U:	se Cross-I	Module Optimizat	tion	
	Viewer File				🔽 U:	se MicroL	ів Г	Big Endian	
SFD\S	T\STM32	F10xx\STM32F	10xxE.sfr						
Read	/Only Men	iory Areas			_ Read/	Write Men	nory Areas		
default	off-chip	Start	Size	Startup	default	off-chip	Start	Size	Nolnit
	ROM1:					RAM1:			
	ROM2:			0		RAM2:			
	ROM3:			0		RAM3:			
	on-chip					on-chip			
	IROM1:	0x8003000	0×40000	۲		IRAM1:	0x20000000	0xC000	
	IROM2:					IRAM2:			
			OK	Can	cel	De	faults		Help

Set flash start address 0x80003000 Then we open dfu to download software

Supports Download Accelerate	Application Mode:     Vendor ID:     Vendor ID:     Vendor ID:     Vendor ID:     Version:     Version:
Select <u>T</u> arget(s): <u>Target Id</u> Name 00 Internal Fla 01 Option Byte	
Upload Action File: Choose Upload Transferred data size 0 KB(0 Bytes) of 0 KB(0 Bytes) Operation duration 00:00:00	Upgrade or Verify Action File: Vendor ID:Targets in file: Procuct ID: Version: Verify after download Optimize Upgrade duration (Remove some FFs) <u>Choose</u> Upgrade <u>Verify</u>
Abort	

And then select the upgrade or verigy action below choose button, select just the production of dfu file

Upgrade or Verify Actio	on						
File: 1.dfu							
Vendor ID: 0483	Targets in file:						
Procuct ID: 0000	- 00 ST						
Version: 0000							
<ul> <li>Verify after download</li> <li>Optimize Upgrade duration (Remove some FFs)</li> </ul>							
Choose Upgrade Verify							
File correctly loaded	•						

And then click with the upgrade, download the file, following the success interface

参DfuSe Demo (v3.0.2)
Available DFU and compatible HID Devices          STM Device in DFU Mode <ul> <li>Application Mode:</li> <li>Vendor ID:</li> <li>Vendor ID:</li> <li>Vendor ID:</li> <li>Procuct ID:</li> <li>Procuct ID:</li> <li>Version:</li> </ul> DFU Mode:     Vendor ID:     0483     Procuct ID:     DF11     Version:     2200     Version:     2200     Version:     2200     Version:     2200     Version:     200     Version:     Version:     200     Version:     200     Version:     200     Version:     Version: </th
Actions       Select Iarget(s):       Target Id       Name       Available Sectors (Double Click for more)         00       Internal Flash       128 sectors         01       Option Bytes       1 sectors
Upload Action File: <u>Choose</u> Upgrade or Verify Action File: 1.dfu Vendor ID: 0483 Procuct ID: 0000 Version: 0000
1 KB(1232 Bytes) of 1 KB(1232 Bytes)         Operation duration         00:00:02             Choose    Upgrade Verify Verify
Target 00: Upgrade successful !       Abort     Quit

After downloading the program, reset will run the application, if you press and hold the s5 key, you can re-enter the DFU mode, and executes the program download

### 3, Chapter 3 Golden Dragon 107 development board hardware

### **Basics**

3.1 power supply scheme

DC 5V adapter power supply corresponds to CN6 interface

LD2 turned bright when switch SW1 on, 5V voltage power go through 1117to supply power to the board



#### **USB**-powered

Two Mini USB can power the board USB1 act as a serial transfer function, used for serial communication. USB2 can be used for USB communication experiment.

Note; Do not use more than one interface to the board power supply to avoid excessive current burn regulator chip

### 3.2 Boot settings



1	0K	BOOT	0			
Mod	BOOT1	BOOT0	Boot Mode	Explanation		
e						
1	ANY	23	User Mode	Program	to	the
				on-chip Flash,con	nmonly used	
2	23	12	System	Serial downloa	d, run-time	set-back
			Boot	mode 1		

3	12	12	SRAM	Download to SRAM, debugging
			Boot	

Note: BOOT0 connection to MCU boot0 pin (PIN94) boot1 then the PB2 pin 3.3 clock source

For STM 32F 107 provides a two-chip clock, Y2 is a 25MHz system clock, Y3 is 32.768Hz RTC clock.

We start to understand the role of Y2, the system runs the need for coordination, like the rhythmic beating of the human heart. Y2 is a passive 25MHz crystal oscillator, the frequency is too slow for the M3, the MCU's internal increase of PLL frequency multiplier, multiplier to the stability of the system 72MHz, careful not to exceed this frequency, otherwise enter the void HardFault\_Handler (void), it is not strange.

Y3 frequency Why choose 32.768Hz presumably played the MCU people know, behind the RTC routines thereby providing a clock source.

3.4 TFT interface



Golden Dragon 107 LCD interface 34PIN compatible with our launch of the 3.2-inch, 4.3-inch, 7-inch color screen, each color with the corresponding routines, according to the diagram, drawing up this table:

Name	Effect		Name	Effect	
3V3			GND		
DB00	Bi-directional data port PE00		DB01	Bi-directional data port PE01	
DB02	Bi-directional data port PE02		DB03	Bi-directional data port PE03	
DB04	Bi-directional data port PE04		DB05	Bi-directional data port PE05	
DB06	Bi-directional data port		DB07	Bi-directional data port	

	PE06		PE07	
DB08	Bi-directional data port	DB09	Bi-directional data port	
	PE08		PE09	
DB10	Bi-directional data port	DB11	Bi-directional data port	
	PE10		PE11	
DB12	Bi-directional data port	DB13	Bi-directional data port	
	PE12		PE13	
DB14	Bi-directional data port	DB15	Bi-directional data port	
	PE14		PE15	
LCD_CS	Display chip select	LCD_RS	Data / command	
	signals			
LCD_WR	Write Enable	LCD_RD	Read Enable	
RESET	Reset signal	NC	No Connect	
SPI3_MIS	The SPI3 data input	TP_INT	Touch screen interrupt	
0			output	
SPI3_MOS	The SPI3 data output	BLACK	Backlight feet	
Ι				
SPI3_SCK	SPI3synchronous clock	F_CS	Screen contains the Flash	
	signal		chip select	
TP_CS	Touch screen enabled	SD_CS	Screen are set out SD card	
			option	
5V	7-inch screen	GND	7-inch screen	

Note:

1, the liquid crystal DB00 to DB15 are bi-directional, and when the ID is read as an input interface

2,MCU with TFT communication can be divided into two modes of 68,008,080, we use the 8080 parallel mode, which determine the RS WR RD of the definition, and timing.

3,3.2 inch screen Flash, 4.3-inch and 7-inch screen with each the 16M the Flash (W25Q16 of), can be used to store data or font file.

4, the Touchscreen SD card SPI\_Flash, are spent SPI3, the distinction between a chip select signal. Use one-time election, the remaining two-chip should be pulled.

## 4, Chapter 4 The fourth basic experiment Quick Start

The basis of routine class					
Number	Routine name	Jumper settings	Experimental phenomena		
1	C 01 C dragon		LED flashing		
	plate _LED,				
2	[02] Golden Dragon		Keys to control LED light		
	board _EXTI		off		
3	[12] Golden Dragon	JP10	Serial 1/2 transceiver has		
	board _UART	JP11 inserted 2-			
		3			
4	[04] Golden Dragon		Rotation the VR1, print		
	board_ADC		serial 1		
5	C 05 C dragon		Output sine wave, using an		
	plate _DAC,		oscilloscope		
6	[06] Golden Dragon		3.2 'TFT display, there is an		
	plate _internal		error		
	temperature				
7	[07] Golden Dragon				
	board_RTC,				
8	[08] Golden Dragon		Timer delay, LED light off		
	board _TIMER				
9	[ 09 ] the dragon		Simple test print SD card		
	board_SD_Test (board)		information.		
10	[10] the Dragon the		Simple test print SD card		
	board_SD_Test (screen)		information.		
11	[11] Golden Dragon	JP6 plug	Serial port to achieve		
	plate _ 24C 02		human-computer interaction		

	4.1	Golden	Dragon	107	list	of	basic	routines
--	-----	--------	--------	-----	------	----	-------	----------

12	[12] Golden Dragon board_W25Q16		Read and write simple experiment	
13	[13] Golden Dragon board_RS485	The JP3 plug 1 - 2	• Two board communication	
14	[14] Golden Dragon board _CAN	JP13 plug 2 - 3	Two board communication	
15	[15] Golden Dragon plate _ 24L 01	The JP13 plug 1 2	- Two board communication	
16	[16] Golden Dragon board _Camera		3.2 'OV7670 data collection	
17	[17] Golden Dragon board_DS18B20		3.2 'display temperature, optional	
18	[18] Golden Dragon plate _infrared		Infrared remote control, to control the display	
19	[19] Golden Dragon board_USB_Device	JP10 JP11 inserted 1	With three experimental	
20	[20] Golden Dragon board_USB_OTG		With two experiments	
21	[21] Golden Dragon board_ETH_LWIP		Webachievehuman-computer interaction	
22	[22] Golden Dragon board_TEA5767		WM8978 amplifier FMsigna	
23	[23] the Golden Dragon board_MP3 soft solution		With RT-Thread	
		Color class (3.2)		
1	[01] The Golden board _ drawing API (3.2 '	Dragon )	Painted graphics, display in the British character	
2	[02] Golden Dragon pla test (3.2 ')	te _ refresh	Scraper speed test	
3	[03] Golden Dragon boa the test (3.2 ')	rd _ Touch	Calibration and drawing board	
4	[04] Golden plate _ adjustable backligh	Dragon t (3.2 ')	PWM regulator	
5	[05] The the Golden board _ electronic photo fr	Dragon	The SD card is inserted in the back of the screen	
6	[06] of Golden board _HZK16 (3.2 ')	Dragon	SD card is inserted in the board	
7	[07] Golden Dragon board uCGUI (3.2 ')	d_uCOS +		
		Color class (4.3)		
1	[01] The the Golden			

	board _ drawing API (4.3 ')	
2	[02] Golden Dragon plate _ refresh	
-	test (4.3 ')	
3	[03] The the Golden Dragon	
	board _ Touch the test (4.3 ')	
4	[04] Golden Dragon	
	plate _ adjustable backlight (4.3 ')	
5	[05] The Golden Dragon	
	board _ electronic photo frame (4.3 ')	
6	[06] of Golden Dragon	
	board _HZK16 (4.3 ')	
7	[07] Golden Dragon board _uCOS +	
	uCGUI (4.3 ')	
	Color class (7.0)	
1	[01] The Golden Dragon	
	board _ drawing API (7 ')	
2	[02] Golden Dragon board _ scraper	
	test (7)	
3	[03] The Golden Dragon	
	board _ Touch the test (7 ')	
4	[04] Golden Dragon	
	plate _ adjustable backlight (7 ')	
5	[05] The the Golden Dragon	
	board _ electronic photo frame (7 ')	
6	[06] of Golden Dragon	
	board _HZK16 (7 ')	
7	[07] Dragon Cricket _uCOS, +	
	uCGUI (7 ')	

### 5, Chapter 5 Routines

5.1 [01] LED light experiment

Experimental phenomena: the download process, press the reset button S3, the four LED flashing water

Jumper settings:

Hardware: Software analysis:

### 5.2 [02] key external interrupt experimental

Experimental phenomena: the download process, press the reset S3, the LD1 flashing; press S1, LD3 dynamically flashing; press S2, LD4 move State flashes

### Jumper settings:

Hardware:

Software analysis:

the void NVIC\_Configuration (void); / \* interrupt packet, specify the external interrupt preemption priority and sub-priority \* /

void BUTTON\_Configuration (void); / \* configure the interrupt input pin, floating input pull-up input can be \* /

GPIO\_EXTILineConfig (GPIO\_PortSourceGPIOD, GPIO\_PinSource11); GPIO\_EXTILineConfig (GPIO\_PortSourceGPIOD, GPIO\_PinSource12);

/\* To specify the port as an interrupt input mode \* /
the void EXTI\_Configuration (void); / \* external interrupt configuration,
edge-triggered or level-triggered \* /

void EXTI15\_10\_IRQHandler (void) ;/ \* write interrupt function, this function STM 32F 10x\_it.c \* /

5.3 [03] The serial transceiver experiment

Experimental phenomena: serial 1 serial port 2 can print serial, serial port 1 with receiving data to control the LED light off

Jumper settings: set the serial port, JP10 and JP11 plug 2 - 3; set the serial port 2, JP3 plug 2 - 3

Hardware:

Software analysis:

This is an example of a serial transceivers including a serial port 1 and 2, serial 1-DB9 male or USB serial line. Serial 2 direct plugMini USB line corresponding interfaces on the board is the USB-1, the need to install the PL2303 driver, please find on the CD, to determine whether the driver installation was successful, "My Computer -> Device Manager -> Ports (COM & LPT)"

The driver installation OK, remember the serial number, open the serial port debugging assistant - SSCOM3.2 is Niexiao fierce "

Understand the experimental results, let us now to analyze the source code, serial output using printf, subsequent serial debugging using this method, key settings, the use of micro-library, as shown below selecting part

```
Target Output Listing User | C/C++ | Asm | Linker Debug | Utilities |
electronics STM32F107VC
                                        Code Generation
                   Xtal (MHz): 25.0
                                         Use Cross-Module Optimization
ng system: None
                                   •
                                         Use MicroLIB
                                                               E Big Endian
Viewer File (.Sfr):
This is a serial send function, general way,
to void USART2_SendString (uint8_t * ch)
{
        while (* ch! = 0)
        {
                while (! USART_GetFlagStatus (USART2, USART_FLAG_TXE));
                USART_SendData (USART2, * ch);
                ch + +;
        }
}
This function, the serial port of the receiving handler, used to control
the LED changes
void USART1_IRQHandler (void)
{
```

uint8\_t temp1; if (USART\_GetITStatus (USART1, USART\_IT\_RXNE) == SET)

```
{
               USART ClearITPendingBit (USART1, USART IT RXNE);
               temp1 = USART_ReceiveData (USART1);
               switch (temp1)
                ł
                       case 'a': the LED1 ();, LED3 (0); LED4 (0), LED2 (0);;
break:
                       case 'b': LED1 (0); LED2 (1); LED3 (0); LED4 (0); break;
                       case 'C': LED1 (0); the LED2 (0); LED3 (1); LED4 (0);
break;
                       case 'd': LED1 (0); the LED2 (0); LED3 (0); LED4 (1);
break;
                       default:
        break:
               }
        }
}
```

5.4 [04] AD conversion experiments

Experimental phenomena: the use of serial port 1, open the serial port debugging assistant, download the program, press the reset button S3.LD1 starts flashing. The PC collected voltage, rotating VR1 voltage value following the change! Jumper settings: JP10 and JP11 are inserted 1 - 2, use the serial port 1

Hardware:

Software analysis:

5.5 [05] DAC output sine wave experiments

Experimental phenomena: the download process, press the reset button S3, CN3 the DAC output measured with an oscilloscope, you can see the sine Wave, frequency 8.78KHZ.

Jumper settings:

Hardware:

Software analysis:

Modify the trigger time of the timer can be obtained waveforms of different frequencies, the maximum 140kHz. It depends on the waveform generation algorithm.

5.6 [06] internal temperature sensor experimental

Experimental phenomena: the download process, press the reset button S3, LD1 flashes, which means that the program has been running;

Plug 3.2-inch TFT screen displays the internal temperature of the collected values. Jumper settings: Hardware: Software analysis:

5.7 [07] RTC experiment
Experimental phenomena: the initial time through the serial port settings RTC
Jumper settings: JP10, JP11 jump 2 - 3, use the serial port 1
Hardware:
Software analysis:

Follow the prompts, we in turn set every minute, such as 12: 12:12 After setting the time in seconds hex operation, see screenshot.

5.8 [08] timer delay experiments
Experimental phenomena: the download process, press the reset button S3, LD1 flashes fast, LD5 slow flashing
Jumper settings:
Hardware:
Software analysis:
LD1 is a simple delay, LD5 precision delay timer

5.9 [09] SD card testing laboratories (card is inserted in the board) Experimental phenomena: TF card is inserted in development board SD1, open the port serial debugging assistant. Download program, press the reset button S3. TF Card information to PC (the specific content View works information.txt). As used herein, 2G TF card test. JP112 - 3 are inserted, use the serial port 1 Jumper settings: JP10 Hardware: Software analysis:

5.10 [10] SD card testing laboratories (the card is inserted in the back of the screen) Experimental phenomena: the TF card is inserted in the on 3.2/4.3/7 inch deck (in the back of the display), the experimental phenomena Example 5.9. If the test is, however, common problem is poor contact card and transposon! Jumper settings: JP10 JP11 are inserted 2 - 3, use the serial port 1 Hardware: Software analysis:

5.11 [11] IIC EEPORM (24C, 02) testing laboratories

Experimental phenomena: plug in the serial cable, open the serial port debugging assistant, set the baud rate to 57600. Download the program, press the reset Key S3, print a test, follow the prompts; Jumper settings: JP10 and JP11 are inserted 2 - 3, use the serial port 1; the JP6 plug jumper cap, using the 24C 02 Hardware: Software analysis: When the system is running, the the serial printing operation information, in accordance with syntax operation to complete 24C 02 of reading and writing, such as r 50:20 0x20 (32) bytes of data read from address 0x50 w 50:02 44 55 66 77 write 4 bytes of data from address 0x50 (44446677)

#### 5.12 [12] SPI Flash (W25Q16), testing laboratories

Experimental phenomena: Plug the serial cable, open the serial port debugging assistant, a baud rate of 115200, download the program, press the reset button S3 PC side display W25Q16 information, and read and write operations results.

Jumper settings: JP10 and JP11 are inserted 2 - 3, use the serial port 1 Hardware:

Software analysis:

5.13 [13] RS485 communication experiment

Experimental phenomena: the two boards CN9 485 wiring terminals 485 A then A, B, then B.

When received from the machine to the host sends the character 'a', the LD1 start blinking!

Jumper settings: JP3 inserted for 1 - 2 RS485 function

Hardware:

Software analysis:

The following two statements the same project, use a shield Usart\_SendChar (USART2, 'a'); / \* 485 send \* / DAT = Usart GetCahr (USART2); / \* 485 receiver \* /

When the slave receives 'a', LD1 starts flashing, the program is as follows:

```
if (dat == 'a')
{
    while (1)
    {
        LED1 (1);
        DELAY (100);
        LED1 (0);
        DELAY (100);
    }
}
```

5.14 [14] CAN communication experiment

Experimental phenomena: the use of serial debugging assistant USART1 send data to the host, the host passes the data through the CAN1 Passed to the slave; slave receives data through USART1 print to the PC;

Jumper settings: JP13 plug 2 - 3 using the CAN 2 - 3 JP10 and JP11 plug to use the serial port 1, JP3 Hardware: Software analysis: The present experiment spent USART1 and CAN1 CAN1 CAN communication of the two plates, and interactive information board PC USART1

#### 5.15 [15] NRF 24L 01 wireless communication experiment

Experimental phenomena: 24L 01 inserted in two on the board (outward), separately download the program to send and receive, then Received normal LD5 light, while the serial print the received data "abcd" Jumper settings: JP13 plug 1 - 2 NRF 24L 01 JP10 and JP11 plug the 1 - 2 serial Hardware:

Software analysis:

5.16 (16) camera (OV7670) experiments

Experimental phenomena:

Jumper settings:

Hardware:



#### Camera

Name	Function	Name	Function
\ RE	FIFO (AL422B) read enable	\ RRST	Read reset active low
\ The	Write Reset	RCK	Read clock
WRST			
WE	Write Enable		
VSYNC	The OV7670 frame	SCL	OV7670 SCCB Clock Line
	synchronization		
SDA	OV7670 SCCB Data Line	XCLK	The OV7670 system clock
			input
D0	FIFO data output pin D0	D1	FIFO Data Output foot D1
D2	FIFO data output pin D2	D3	FIFO Data Output foot D3

D4	FIFO data output pin D4	D5	FIFO data output pin D5
D6	FIFO data output pin D6	D7	FIFO Data Output foot D7

Software analysis:

5.17 [17] external temperature sensor (DS18B20) experiment

Experimental phenomena: the download process, press the reset key S3 LCD is displayed in the lower-left corner of the "DS18B20 Init OK!"

The middle of the screen shows the collected temperature, hold hands the U6, see temperature rise

Jumper settings:

Hardware:

Software analysis:

5.18 [18] infrared testing laboratories

Experimental phenomena: the download process, press the reset button S3, LCD display infrared test interface with the remote control Control LCD Display Jumper settings: Hardware: Software analysis:

5.19 [19-A] Human Input USB device

Experimental phenomena:

Jumper settings: JP10, JP11 1 - 2 are inserted using a USB communication Hardware:

Software analysis:

Of course, you have to unplug your USB input devices such as a USB mouse and keyboard, that we open test software

🛣 USB HID Demonstrator (v1.0.2)					
USB IIID Device capabilities           Image: Second secon	D. 2) USB HID Target HID-compliant device Buttons Button 1 Report ID (h) 05 Button 2 Report ID (h) 06 Leds Leds Variable Inputs Leds Variable Inputs	00h			
Output mode © Use SET_REPORT © Use SET_FEATURE	✓ Led 2 Report ID (h) 02 ✓ Led 3 Report ID (h) 03 ✓ Led 4 Report ID (h) 04				

The software in the CD-ROM installed, open the interface as shown, first see the USB HID target shows

LEDs Click to check control development board LED light off change

[19-B] virtual serial port of the USB device

Experimental phenomena: the download process, press the reset button S3 PC side prompted STM32 Virtual COM

At this point we see the Device Manager does not recognize the device, install the driver, you can use the serial device. Jumper settings: JP10, JP11 plug the 1 - 2 using a USB Hardware: Software analysis: [19-C] USB device DFU (device firmware update) Experimental phenomena: PC Tips STM32 DFU device, refer to our manual can be DFU download Jumper settings: Hardware: Software analysis:

5.20 [20] Jinlong board \_USB\_OTG

Experimental phenomena: Use the USB adapter cable Mini-side plug USB-2, another paragraph insert U disk, download the program, press the reset button S3, You can see the LCD display U disk information Jumper settings: JP10 JP11 plug 1 - 2

Hardware:

Software analysis:

5.21 [21] Jinlong board \_ETH\_LWIP

Experimental phenomena: the network cable to connect your PC and the development board, set the PC side

Jumper settings: JP9 plug the 2 - 3, the STM32 MCO output synchronous clock Hardware:

Name	Function
ETH_RMII _TX_EN	
(PB11)	
ETH_RMII_TXD0 (PB12)	
ETH_RMII_TXD1 (PB13)	
ETH_RMII_RXD0 (PD9)	
ETH_RMII_RXD1 (PD10)	
ETH_MDC (PC1)	
ETH_MDIO (PA2)	
ETH_RMII_CRSDV (PD8)	
ETH_RMII_REF_CLK	
(PA1)	

MCO (PA8)	
-----------	--

The following is a network chip DP83848 clock source is set, there are two options, one is active crystal, another the MCU clock FootPA8.



Software analysis:

```
C:\Documents and Settings\Administrator>ping 192.168.0.8
Pinging 192.168.0.8 with 32 bytes of data:
Reply from 192.168.0.8: bytes=32 time<1ms TTL=255
Ping statistics for 192.168.0.8:
    Packets: Sent = 4, Received = 4, Lost = 0 (0% loss),
Approximate round trip times in milli-seconds:
    Minimum = 0ms, Maximum = 0ms, Average = 0ms</pre>
```

Ping through, open IE, enter 192.168.0.8 in the address bar hit the Enter key, which is the pop-up test page

We see the body of the page, above three options button to jump to the home page, LED control, ADC conversion

Here briefly earlier, Led control is controlled through a web development board LED lights off

ADC Status bar is the acquisition value of the adjustable resistor VR1 passed to the web display

5.22 [22] Jinlong board \_TEA5767

Experimental phenomena: the the T1 antenna position plug wires, signal enhancement, download the program, press the reset button S3, from small The speaker issued in the received FM signal.

#### Jumper settings:

Hardware: Software analysis:

### 5.23 [23] Jinlong board \_MP3 soft solution

Experimental phenomena: 2G SanDisk card inserted on the board, the project a.mp3 copied to the SD card, download the program, Press the reset button S3, then came the beautiful music from the speaker. You can connect the serial cable to view Print information! Jumper settings: Hardware:

Software analysis:

### 6, Chapter 6, Color Papers

6.1 [01] LCD underlying driver experiment

Experimental phenomena: plug in the 3.2-inch screen, download the program, press the reset button S3, you can see the LCD display characters, Chinese characters, Image (custom), there is a straight line, circle and filled areas.

Jumper settings: Hardware:

Software analysis:

6.2 [02] LCD refresh testing laboratories

Experimental phenomena: Plug in the 3.2-inch screen, press the reset button S3 LCD in different colors scraper

Jumper settings:

Hardware:

Software analysis:

6.3 [03] touch screen testing laboratories

Experimental phenomena: plug in the 3.2-inch screen, press the reset button S3, LCD display calibration point, click for calibration.Calibration into Function, you can use the touch pen drawing.

Jumper settings:

Hardware:

Software analysis:

This is the value of the of four calibration point touch screen collected in accordance with from left to right, from top-down order, these four values is successful calibration, you can observe the characteristics of the data

Name	The position of	Touch value	
	the display		
Point 1	(20, 20)	(0x60, 0x742)	
Point 2	(780, 20)	(0x 79a, 0x 75C)	
Point 3	(20, 460)	(0x51, 0x80)	
Point 4	(780, 460)	(0x76b, 0xA3)	

Note that this function resistive screen there is a difference, you can use the following way of compensation

Draw\_Big\_Point (Pen\_Point.X0, Pen\_Point.Y0-5) ;/ / drawing

6.4 [04] backlight adjustable experiments

Experimental phenomena:

Jumper settings:

Hardware:

Software analysis:

6.5 [05] Digital Photo Frame experiment

Experimental phenomena: the engineering test images are copied to the SD card, then plug it into the back of the screen deck. Download program, press Under the reset button S3, LCD display the picture SD card, which electronic photo frame!

### Jumper settings:

Hardware: Software analysis:

6.6 [06] 16 \* 16 characters programming and display experiment

Experimental phenomena: the sys file in the project folder together with the font file HZK16 copied to the SD card, then the SD card is inserted Into the deck of the development board, and plug in the 3.2-inch screen. Download the program, press the reset button for several seconds, the screen Display Kanji content.

#### Jumper settings:

Hardware:

Software analysis:

if (! SD\_Init ())

{

LCD\_ShowString (0, 280, "SD Init OK!", BLACK, BROWN); / \* SD card initialization OK \* /

}

else LCD\_ShowString (0, 280, "SD Init Failure!", BLACK, BROWN); / \* SD card initialization OK \* /

```
if (! W25Q16_Init ())
```

ι

BROWN);

/

WriteHZ16 (); / \* programming 16 \* 16 font \*
}
else
{
LCD\_ShowString (0, 300, "W25Q16 Init Failure!", BLACK,

LCD ShowString (0, 300, "W25Q16 Init OK!",

BLACK,

BROWN);

Schematics know SD card and W25Q16 are connected in SPI1 the SPI configuration after the end of the SD card is initialized and W25Q16, the initialization results displayed in the bottom left of the screen.

In the write library of function, such a judgment statement, used to mark the character is written to, the customer can use if masked, until the display OK!

```
SPI_Flash_Read (dataflash, 0x 1f 0000,2); / * read flag to determine whether the
font * /
if (DataFlash [0]! = 0xaa | | dataflash [1]! = 0x55)
{
......
}
```

### 6.7 **(**07**)** uCOS + uCGUI test experiment

The experiment phenomenon: plug in the 3.2-inch screen, download the program, press the reset button S3, with uCGUI the system ran up

Jumper settings:

Hardware:

Software analysis: