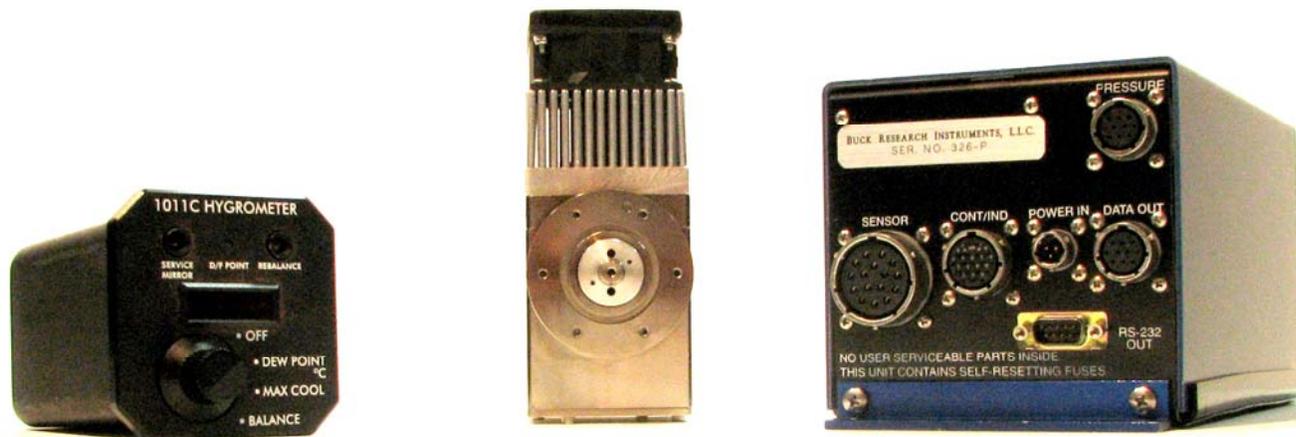


BUCK RESEARCH INSTRUMENTS L.L.C.

MODEL 1011C HYGROMETER

OPERATING MANUAL



December 2009

BUCK RESEARCH INSTRUMENTS, LLC

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SECTION 1. INTRODUCTION

1.1 GENERAL OPERATIONAL INSTRUCTIONS

The 1011C is a high performance condensation type hygrometer designed for airborne measurement of dew and frost point temperatures. The system is capable of measuring dew/frost points between -75°C and $+50^{\circ}\text{C}$, over a wide range of temperatures, pressures, and airspeeds. The 1011C is a complete update of the 1011B hygrometer, incorporating many new features described below.

The instrument operates on the chilled-mirror principle. A mirror is thermoelectrically cooled until it reaches a temperature at which condensation begins to form (the dew or frost point), and is then held at that temperature; the presence of condensation is sensed optically. The signal output is a voltage corresponding to the temperature of the mirror.

The 1011C consists of three distinct units – a Sensor unit, a Power unit and a Control/Indicator unit. The Sensor unit contains a three-stage thermoelectric cooler (TEC) capable of reaching frost points normally encountered at altitudes up to 45,000 feet.

ALL PARTS OF THE 1011C CAN ONLY BE USED WITH THE 1011C. NONE OF THE 1011B COMPONENTS CAN BE INTERCHANGED WITH THE 1011C.

The 1011C features a microcontroller-based Power unit. It features both voltage and 9600 baud RS-232 serial data outputs. Optionally, it includes a power switch and a pressure sensor input.

The Control/Indicator unit features LEDs that indicate mirror cleanliness, an LED display that shows dew/frost point temperature, and a blue LED that indicates whether the instrument is controlling on a dew or a frost point.

The instrument will operate well in most environments, both on and off aircraft. Although the standard configuration is designed for in-flight operation, an optional aspirating kit enables use while the aircraft is on the ground, as well as off the aircraft in a lab or other environment.

Startup and operation are normally very simple. Excluding extreme humidity environments, no in-flight adjustments are required.

Note: An aircraft is an exceedingly difficult platform from which to make humidity measurements, because of the extreme range of environmental conditions which can occur, the abruptness of changes encountered, and various thermodynamic and aerodynamic considerations. While the 1011C is designed using the highest standards in this type of instrument, in-flight situations can be encountered which will tax its limits. To help assure consistently good performance, a number of cautionary factors are discussed in this manual.

1.2 BRIEF PHYSICAL DESCRIPTION

Physically, the system (Figure 1) consists of a sensing unit, a control/indicator unit, a power unit, associated cabling, and a maintenance unit.

The Sensing Unit (A) is the moisture-detecting device. It contains a right or left hand inlet fitting, a mirror, sensing/control optics, a thermistor, a TEC, and associated electronics.

The Control/Indicator Unit (B) is the user interface component, and contains the on/off function switch, balance control, and displays.

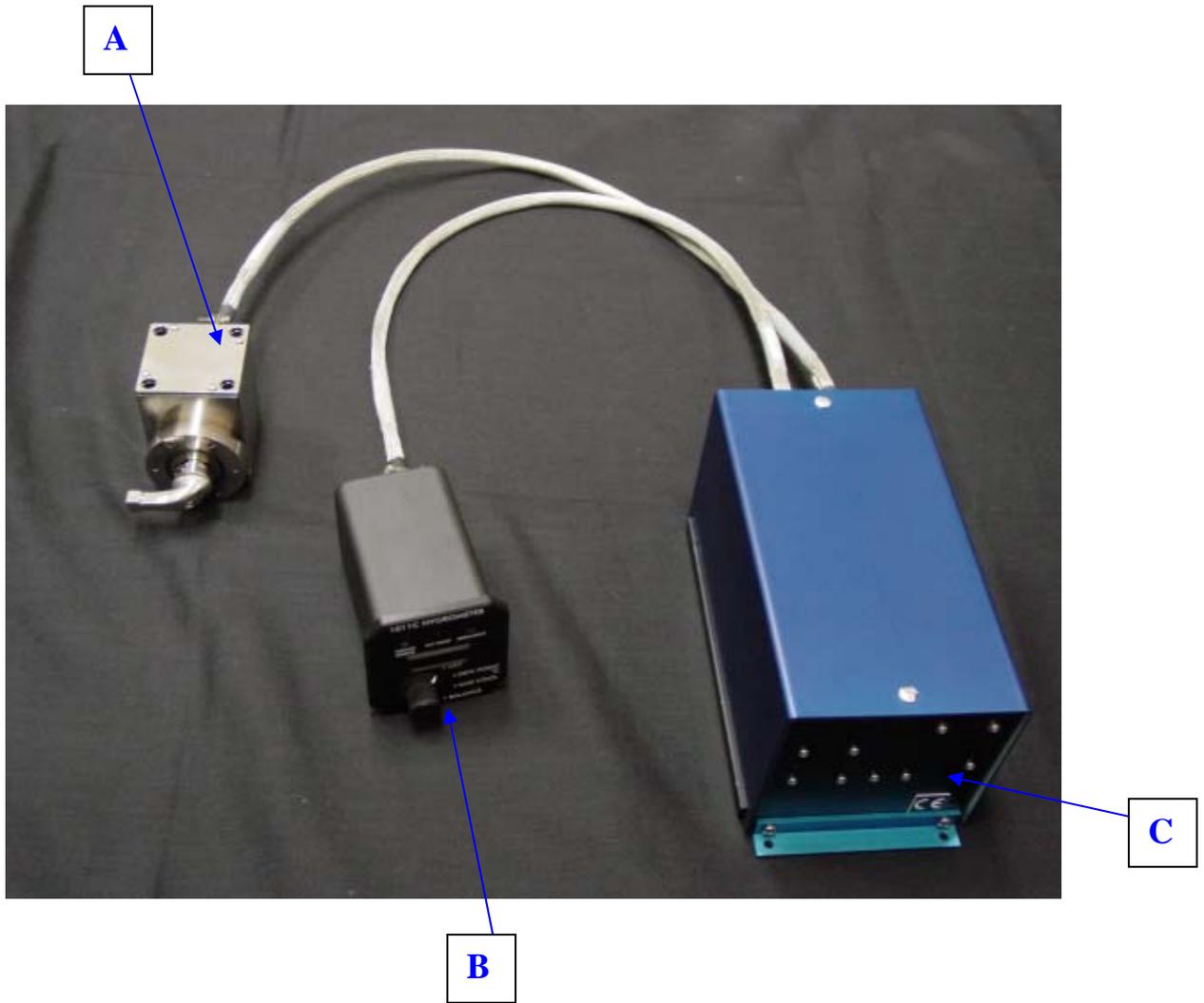
The Power Unit (C) distributes operating power to the system components and contains the circuitry that controls the thermoelectric cooler and converts mirror temperature to a suitable output signal (provided at rear of unit). The unit is equipped with quick-remove shock mount.

The Maintenance kit: Consisting of bottles for water and acetone, cotton swabs and spare gaskets and o-rings. Unlike the 1011B, the 1011C does not come with a calibration plug. This is because the 1011C uses an ultra-stable thermistor instead of an RTD, which improves speed of response and is far less susceptible to drift. Additionally, the temperature is measured with an analog-to-digital converter (ADC) that is calibrated each time the instrument is turned on and is not susceptible to drift like the analog electronics in the old 1011B instrument, and therefore does not need a calibration plug.

Three Cables or six Connectors, a Data Connector, and a Power Connector connect the various system components and provide input power.

Optional Accessories, which further increase versatility and ease of use, are described in Section 2.6.

Note: The 1011B hygrometer was originally developed and produced by General Eastern Instruments. This operating manual originated at General Eastern, and many of the drawings are reproduced by their courtesy.



**Figure 1. Dew Point Hygrometer System
(shown with optional cables)**

1.3 SPECIFICATIONS

Dew point range:	-75 to +50 °C nominal (see also Figure 2)
Accuracy	± 0.1° C RS-232 ± 0.3° C C/I LED display
Response time:	Variable (see Sect. 4.2.1)
Outputs	
Analog:	
Dew point:	0.08 v/°C, 6v = 0°C
Control voltage:	0 – 10 vdc
Minimum load impedance	5 K ohms
Digital display resolution:	0.1 °C
Power Input	28 vdc, 2.5 A max
Operating Limits	
Operating temperature range	
Sensing Unit:	-80 to +60 °C
Control/Indicator Unit:	-40 to +60 °C
Power unit:	-40 to +60 °C
Airspeed (nominal):	450 knots
Altitude (nominal):	45,000 feet
Pressure Limit:	1.5 atmospheres
Dimensions in inches	
Sensing Unit	
Diameter (max):	2.50
Length (with inlet fitting):	4.25
Control/Indicator unit	
Height:	3.26
Width:	3.26
Depth:	5.88
Power unit, including shock mount	
Height:	6.38
Width:	6.06
Depth:	12.0
Weight, lbs.	
Sensor:	1.5 lbs.
Control/Indicator:	1.25 lbs.
Power unit:	3.25 lbs.
Cables:	8.0 oz. per 10 feet

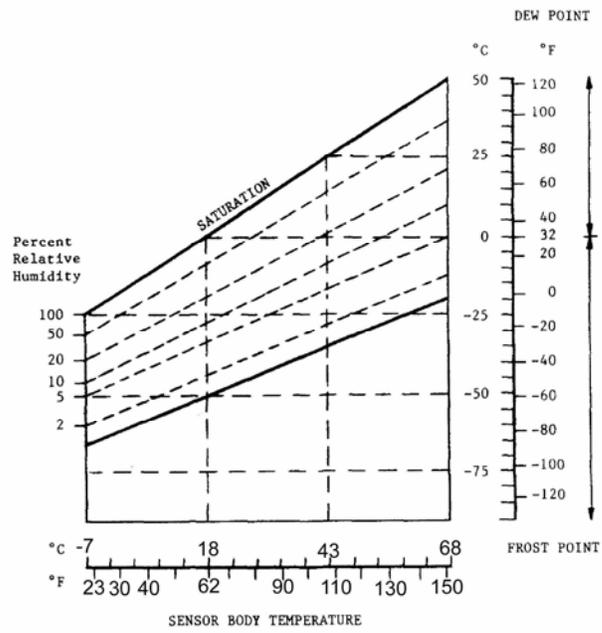


FIGURE 2. Depression Capability

1.4 NOTE TO USERS OF 1011B SYSTEMS

The following is a list of improvements made:

1. 28 VDC operation.
2. RS-232 data output
3. Improved accuracy, ± 0.1 degree C over entire range*
4. Improved servo control, reducing oscillations by a factor of 10.
5. Improved cooling of at least 20 degrees C
6. Faster and more accurate response at low dew points because of nickel-plating
7. Software-upgradeable by end user.
8. Optional pressure sensor input and mixing ratio output
9. Autobalance feature automatically compensates for reduced mirror reflectivity caused by contamination.
10. Service Mirror LED illuminates to indicate mirror contamination is too great and mirror needs to be cleaned.
11. D/F Point LED, which illuminates when a dew or frost point is reached

*RS-232 output only

1.5 ACKNOWLEDGMENT

David M. McFarland at the National Center for Atmospheric Research initially developed the flow test fixture and the aspirating fixture. We acknowledge with appreciation Mr. McFarland's contribution in making these devices available to the user community.

SECTION 2. CONTROLS, CONNECTORS, AND MAJOR COMPONENTS

2.1 SENSING UNIT (Figure 3)

- A. Inlet Fitting - has inlet, exhaust, and water drain ports. Each fitting is designed for use on either the left or the right side of the aircraft, but not for both.
- B. Mounting collar. The mounting collar has 6 holes drilled in it that are ready to be tapped for either 8-32 or M4 screws for mounting. Buck Research Instruments, LLC does not tap these holes unless specifically requested by the customer, as mounting configurations and requirements vary from aircraft to aircraft.
- C. Connector (J6) - for cable leading to power unit.

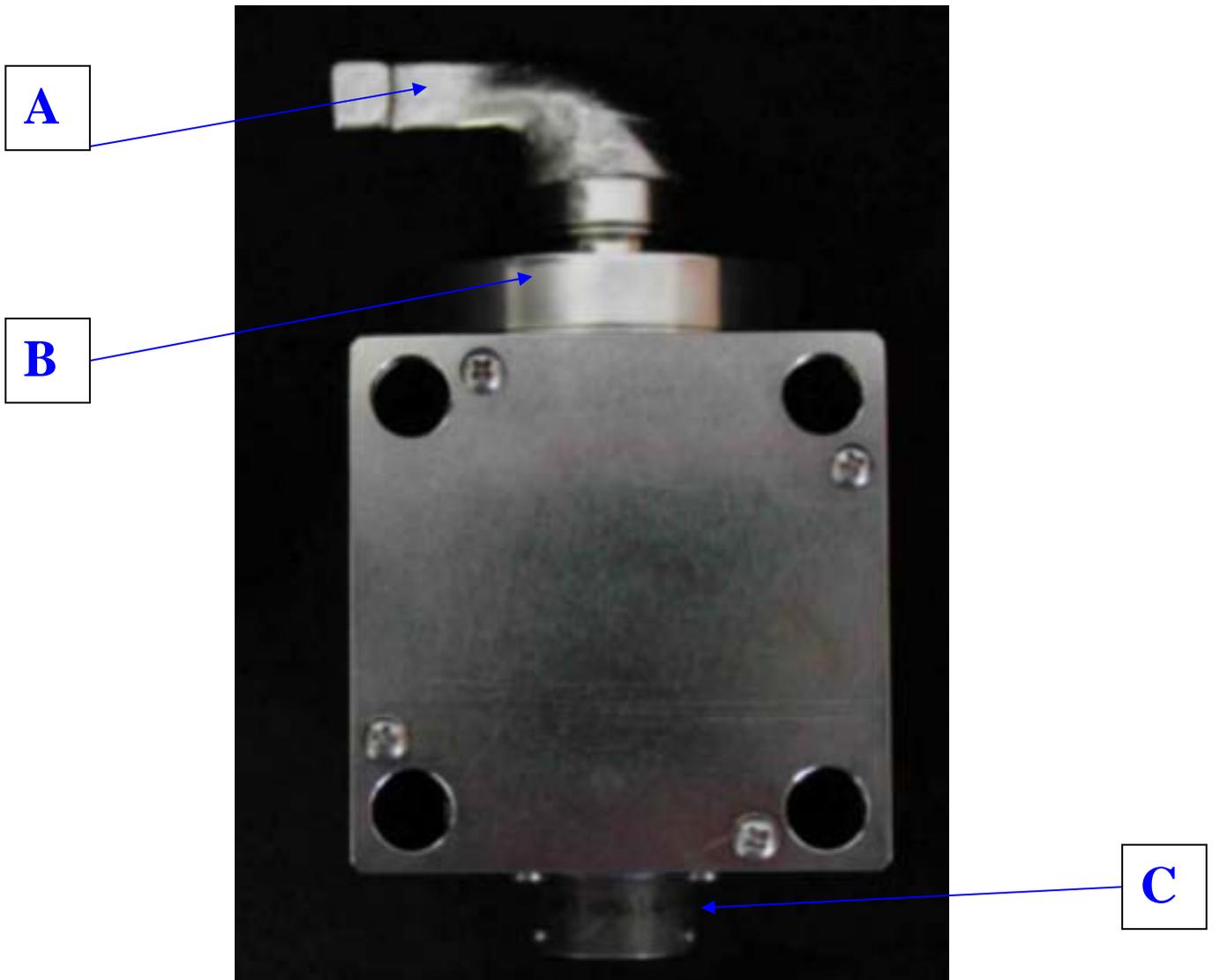


Figure 3. Dew Point Sensing Unit

2.2 CONTROL/INDICATOR UNIT (Figure 4)

- A. Function switch (S1) - applies power to the various system supplies, and provides the following functions:

OFF - no power applied to any circuit.

DEW POINT - normal operating position. Allows system to maintain an equilibrium condensation layer on the mirror. Initiates a balance cycle upon initial power up.

MAX COOL – switch position that applies full cooling current to the thermoelectric cooler. This is used to (1) determine whether there is adequate cooling when the system is operating at very low frost points, and (2) convert any supercooled water deposit to frost.

BALANCE – initiates a balance cycle, which heats the mirror to 40° C to evaporate condensation and allows system to be balanced with a dry mirror. Do not leave in this position once balance routine is initiated or it will repeatedly balance mirror. Switch back to DEW POINT position once REBALANCE LED lights

- B. Digital Panel Meter (M1) – allows direct readout of dew point data.
- C. D/F Point LED - blue LED indicates if unit has stabilized on a dew or frost point.
- D. REBALANCE LED. Lights when a balance routine is performed. If it stays light after balance finishes, this indicates that mirror is becoming contaminated and will need to be cleaned soon.
- E. SERVICE MIRROR LED. This LED flashes to indicate that mirror is too contaminated for proper operation and needs to be cleaned.
- F. Main Connector J8 - for cable leading to control unit.

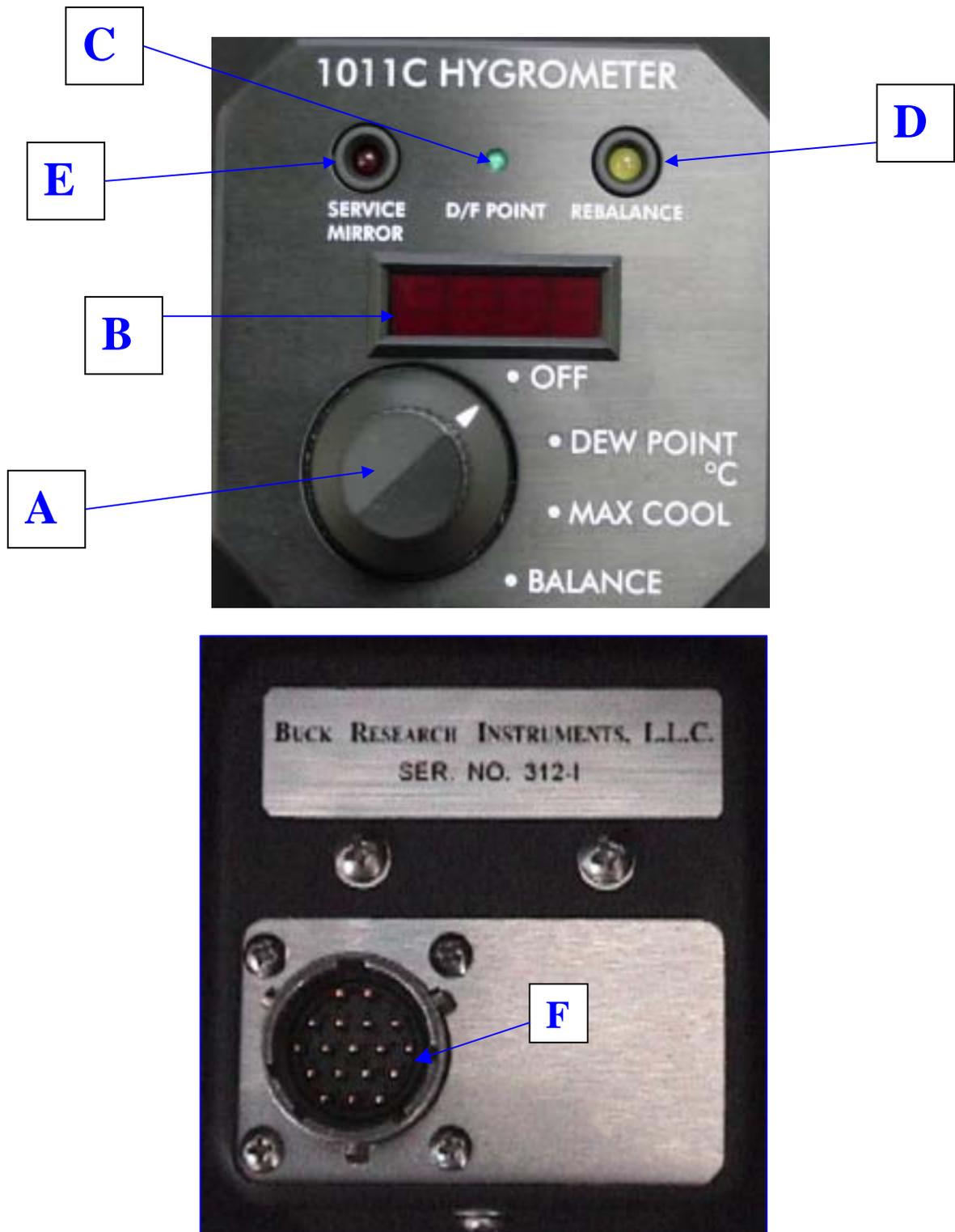


Figure 4. Control/Indicator Unit

2.3 POWER UNIT (Figure 5)

- A. SENSOR Connector (J5) - for cable to sensor.
- B. CONT/IND Connector (J7) - for cable to Control/Indicator.
- C. DATA OUT Connector (J4) - provides analog signal outputs.
- D. POWER IN Connector (J1) - for connecting +28 VDC.
- E. PRESSURE – to connect to optional pressure sensor
- F. RS-232—serial data output (9600 Baud 8-N-1)

The power unit is no longer furnished with a shock-mounted base as we have determined that one should not be required for most aircraft installations. If shock mounts are deemed necessary, they are made by Barry Controls and the part number is Barrymount L44-BA(M)-2. (Use BAM for metric and BA for standard). Install one on each corner of the Power unit using the screw holes on the blue mounting brackets on the bottom. You will need a total of 4 Barrymounts.



Figure 5. Power unit.

2.4 CABLES

Six connectors and wiring diagrams *or* three cables are supplied: power unit to +28 VDC, power unit to sensing unit, and power unit to control/indicator unit. Each connector is unique, so that it is impossible to accidentally connect the cables incorrectly.

2.5 OPTIONAL ACCESSORIES

Aspirating Kit. Provides airflow through the 1011C sensor when it is not exposed to in-flight conditions. It consists of an aspirating fixture which attaches to the sensor, a pump, a floating ball flowmeter with control valve, and a length of non-hygroscopic tubing with fittings.

The fixture attaches itself quickly and allows an operational check of the entire system in the lab or on the aircraft while parked. It also allows use of the system in the lab or other off-aircraft environments, and permits a complete leak check to be performed.

Inlet Fitting. Spare to allow choice of right side or left side operation.

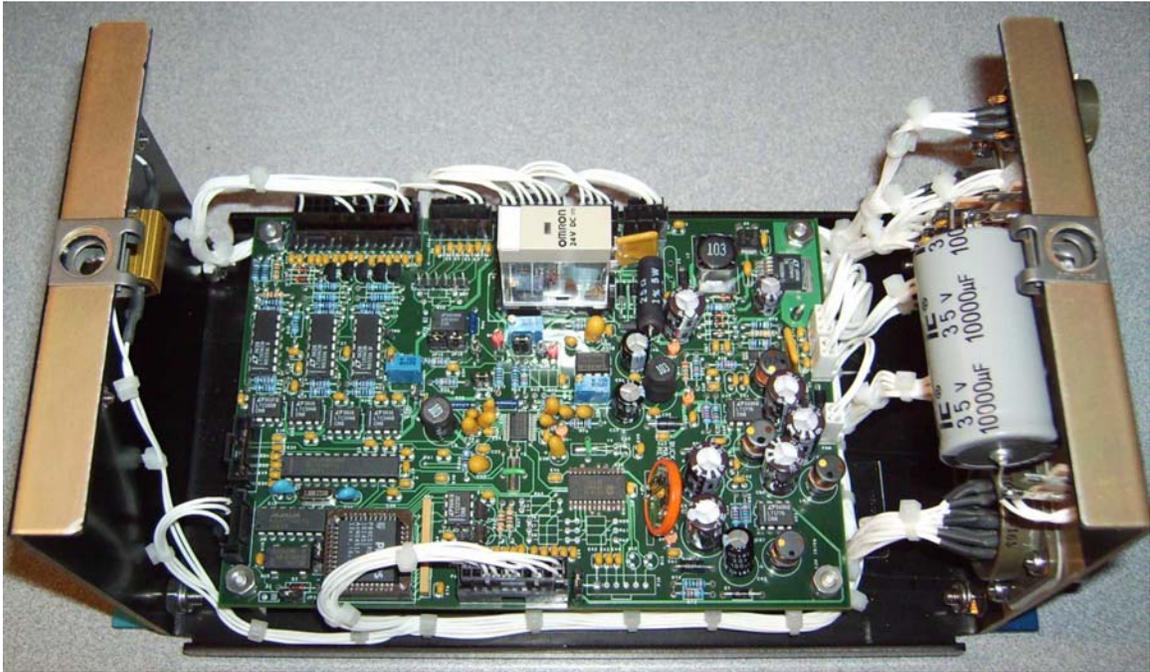


Figure 6. Power Unit, Internal

SECTION 3. INSTALLATION

3.1 UNPACKING PROCEDURE

1. Remove system components from shipping containers and situate near a 28 VDC power source. If possible, save shipping containers for future use.
2. Make sure that all system components are accounted for (Figure 1).
3. Ascertain they are properly matched by serial number, or have been calibrated together.
4. Visually inspect exterior of system components and interconnecting cables for damage. If damage is evident take appropriate action for corrective maintenance and repair, as required.
5. Record serial numbers.

3.2 INITIAL OPERATIONAL CHECK

Before mounting on the aircraft, it is advisable to give the system an initial bench check to verify that it works properly and to become familiar with its operation. See Section 4.3 for operation off the aircraft.

3.3 INSTALLATION ON AIRCRAFT

Sensing unit

The sensor is normally located on the aircraft fuselage, mounted through the exterior skin, with the inlet fitting exposed to the airstream. Other locations, such as a boom, can also be used.

The pressure field along the side of an aircraft in flight varies with location, and may be greater or less than the ambient or static pressure. Attempt to locate the sensor at a point where the pressure is reasonably near static pressure. A side mount is advisable to avoid pressure changes with change of aircraft pitch, and to avoid rain while parked. Avoid prop wash and areas of large local pressure changes, such as wing surfaces, behind radar domes and struts, etc. It is usually safe to mount the sensor near the static instrument ports, as they are located at or near a point of static pressure.

In pressurized aircraft, try to avoid locating immediately downstream of windows or other cabin penetrations that might have slight leaks and thereby affect the air being sampled. A forward location allows a somewhat better penetration of the aircraft boundary layer by the probe, and so is somewhat preferable (although usually not critical).

The inlet fitting is designed for use on either the right or the left side of the aircraft, but not both. The consequence of mounting on the wrong side of the aircraft is: upward pointing inlet and exhaust holes and the likelihood of collecting liquid water in the sensor.

The sensor should be mounted as shown in Figure 7. Initially, orient the sensor so the inlet fitting points downstream, parallel to the airstream, with the inlet and exhaust holes pointed downwards. As soon as practical, adjust for proper flow and pressure change in the cavity, according to Section 3.5.

Power Unit

Wire up cables and connect the proper cables (they are coded to prevent mismatch). +28VDC must be used. Using any other power will damage the unit and void the warranty.

Control/Indicator Unit

If practicable, mount so that the front panel is accessible during flight. Make sure function switch S-1 is in OFF position. Connect cable.

Cable Length

Standard cable lengths may be extended as follows on special order:

Sensing unit to power unit: 3 feet (1m) standard, may go to 50 feet.

Control/Indicator to power unit: 3 feet (1m) standard, may go to 150 feet.

It is essential that cables be identical in quality and configuration to that of original equipment or the cable specified in the drawings. Specifically, that there are 7 pairs of shielded 24 gauge wires and 2 pair of shielded 18 gauge wires contained in the cable used for connecting between the power unit and the control/indicator unit and the cable used for connecting the power unit to the sensor unit. It would also be acceptable to make a cable using 9 separate cables that are shielded, twisted-pair (7 of them 24 gauge and 2 of them 18 gauge) and wrapping them together. Make sure that there is an overall, braided shield surrounding these cables and attached at both ends to the connector. Use of non-standard cable may cause operational problems and make the unit more susceptible to noise and electrostatic discharge.

Sensor Body Temperature

There is a trade-off involved in the degree to which the sensor body is thermally coupled to the outside ambient temperature. If it is held closely to outside temperature, the thermoelectric cooler will have the lightest cooling load, and the instrument will be able to achieve maximum performance at very low frost points (high altitudes); it may, however, become flooded on descent when the cold sensor body suddenly encounters warm moist air. If on the other hand, the sensor body is strongly influenced by the heated cabin, the reverse will be true: better stability on descent, but reduced performance at frost points below -50° C. In practice, normal mounting on

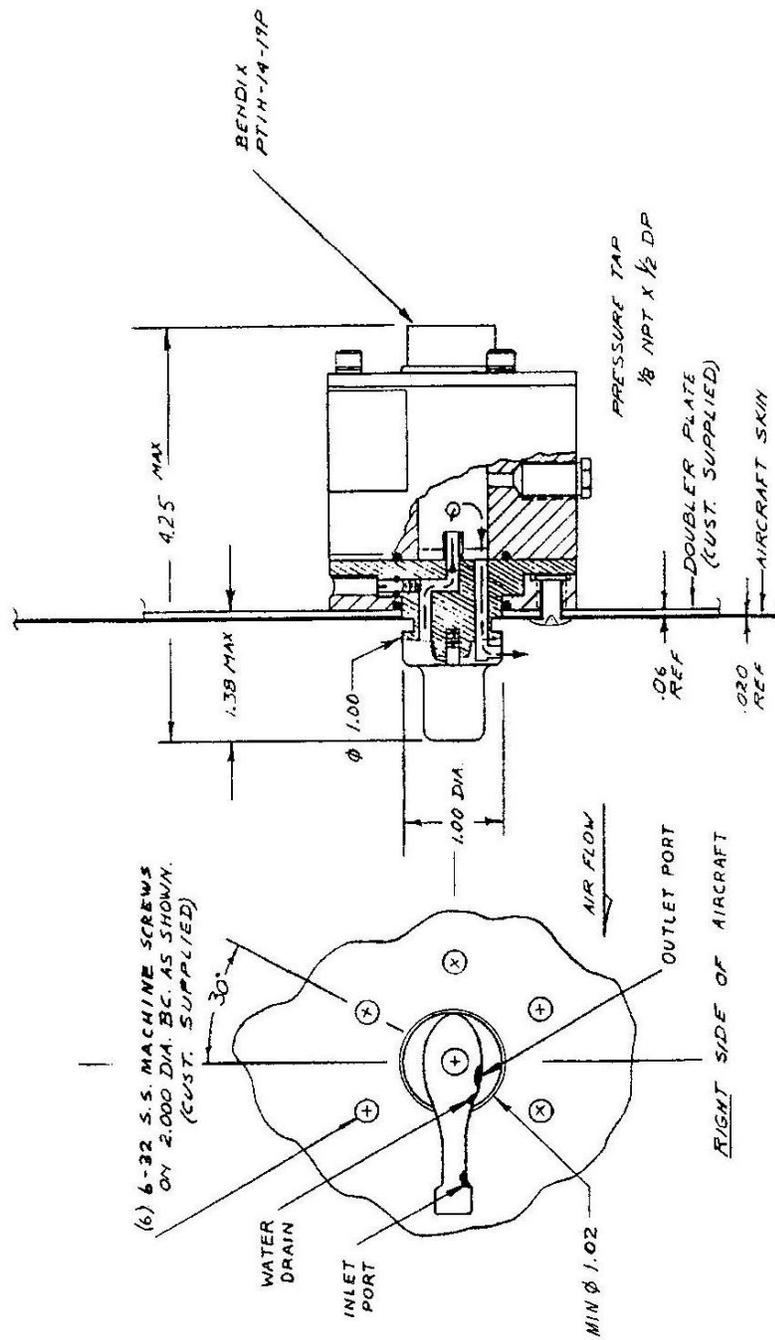


Figure 7. Sensing Unit: Mounting

Note: #6-32 screws go into the mount collar, which has a maximum depth of 0.375". Add this length to the total thickness of the aircraft skin and any plates used to determine screw length.

the aircraft skin usually works well. To achieve a different balance between inside and outside temperatures, insulation and/or heat sinking can be applied as appropriate.

CAUTION--Make sure the sensor has adequate heat sinking when operating in hot environments. Do not operate in environments over 60 °C (140 °F).

3.4 LEAK CHECK

(A) If the optional aspirating kit is available, attach the aspirating fixture in place of the sensor inlet fitting and temporarily seal the inlet holes. Take special care that the gasket is properly oriented to allow free flow through the sensor body. Lower the pressure inside the sensor as much as possible and check for leaks. The flowmeter ball should not move.

(B) If the optional aspirating kit is not available, seal all ports of the inlet fitting, and attach a pump and flowmeter to the pressure tap on the sensor body. Check for leaks as above. (NOTE: To ensure a good seal, use Teflon pipe tape when replacing pressure port plug.)

(C) If a flowmeter is unavailable, the following alternate method can be used: Connect the pump to the sensor by one of the above arrangements, along with a shutoff valve and a pressure gauge. After pumping down the sensor, close the valve to seal it off, and observe its recovery to ambient pressure. If recovery takes 10 seconds or longer, the sensor is adequately sealed from leaks.

If a leak is apparent, locate it using positive pressure and a soap solution or equivalent.

3.5 PRESSURE WITHIN A SENSOR

The 1011C sensor should not be exposed to a pressure differential greater than 1.5 atmosphere across the sensor, as pressure in excess of this can destroy the seals. The sensor is designed to be leak tight when the lower pressure is in the sensor chamber, i.e., pressurized cabin with the sensor chamber at atmosphere pressure.

3.6 CABLING

When cables are supplied with the 1011C and it is desired to use cables of different length than the 3 foot (1m) lengths originally supplied, factory-made cables of different lengths are available from Buck Research Instruments, LLC, on a special-order basis only. Normally, only the connectors are supplied for the 1011C and it is the responsibility of the end user to make cables. This is done because many agencies will not certify cables from outside vendors, such as Buck Research Instruments, LLC, for use aboard their particular aircraft.

Cable length can generally be varied without problem. However, the shielding and grounding arrangement is critical, and the cable used should be identical to that originally supplied or specified in Section 3.3 of the manual and in the wiring diagrams. If you have

any questions or doubts about making your own cable, please contact Buck Research Instruments, LLC and we would be happy to assist you.

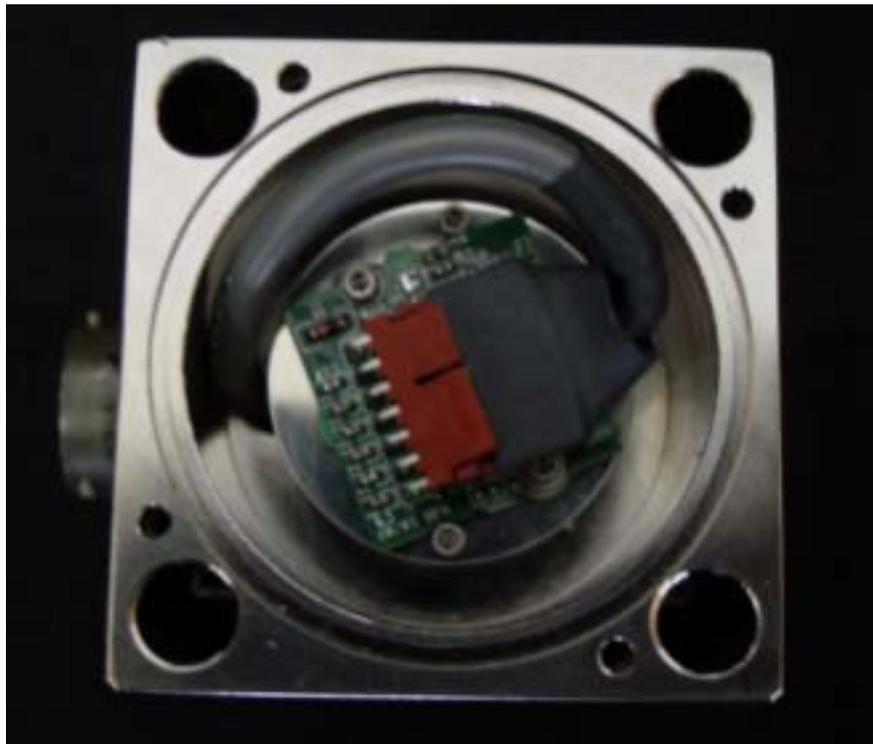


Figure 8. Sensing Unit, Internal

F = Flow Meter
 ΔP = Gauge Pressure Meter
(optional)
ALT = Altimeter (optional)

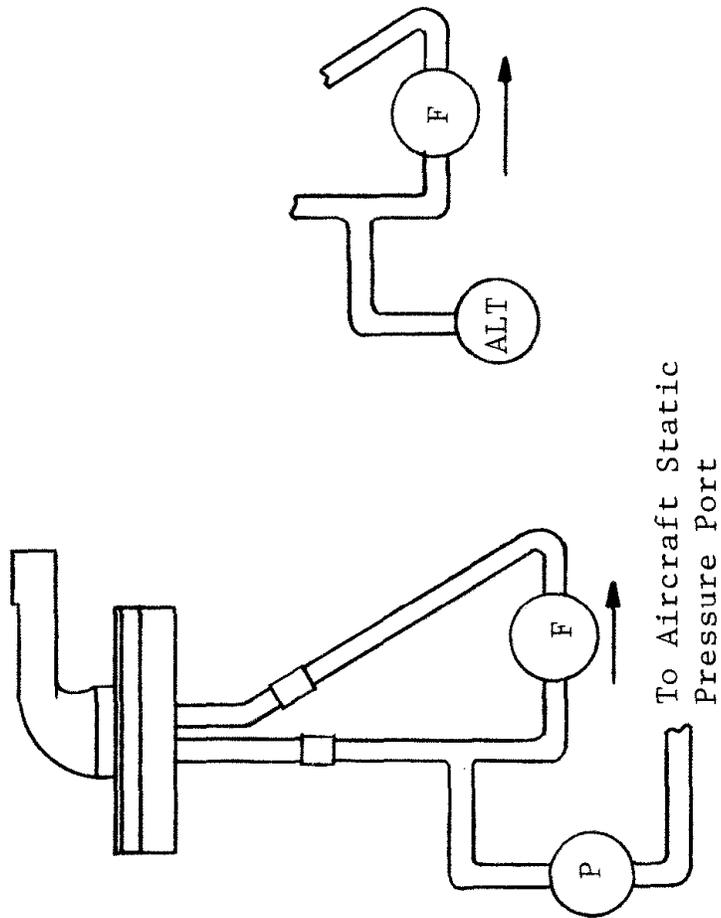


Figure 9. Flow Test Fixture Hookup

SECTION 4. OPERATING INSTRUCTIONS

4.1 INITIAL SETUP

1. Ascertain that function switch S-1 is in OFF position.
2. Connect power unit, sensing unit, and control unit to their appropriate cables, and to 28 VDC (see Figure 13). Also, connect analog or digital recording devices as desired.
3. If instrument is to be operated while not in flight refer to section 4.4.

4.2 SYSTEM OPERATION

Turn the function switch to the DEW POINT position and observe the reading settle to its proper value. The panel meter will read the mirror temperature as it rapidly approaches the correct dew point. When the unit stabilizes, the D/F point LED will illuminate.

At dew points above 0°C, the system stabilizes within a few seconds on the correct dew or frost layer. Take dew/frost point readings after the D/F point LED has illuminated.

If you connect the RS-232 output to a PC running Hyperterminal, there will be a 1 in the third position of the line when the mirror temperature and balance have stabilized enough that dew or frost points are being outputted; otherwise, this will be a zero. Please see page 45 for more details.

4.2.1 Time response

Time response depends on a number of factors: slew rate, dew point, flow rate, and thickness setting. Slew rate is in turn dependent on dew point and depression; at higher dew points and moderate depression, it is typically 1 °C/second. At lower dew points and/or larger depressions (taken as the temperature difference between the mirror and the sensor body), slew rate becomes slower, and can be reduced to tens of minutes at its limit. At low dew points, response is also limited by the reduced availability of water molecules and the resulting slow crystal growth rate. For best response: (1) maximize flow (to increase the rate at which water vapor is supplied or carried off); and (2) make sure the sensor case temperature is kept as close to that of ambient air as possible by proper heat-sinking and insulation. There is, of course, a trade-off between response time, control system stability, and sensitivity to contamination.

4.2.2 Mirror cleanliness

It is not necessary that the mirror be “microscopically clean” and, in fact, best performance will be obtained from a mirror which has been operating for a few hours after cleaning. On an unscratched, freshly cleaned mirror, there are a relatively small number of nucleation sites on which dew or frost deposits can form, and so the time it takes to collect a condensate layer at low frost points is increased. Also, overshoot occurs, which can cause oscillation.

Since proper operation of a condensation hygrometer depends strongly on the condition of the mirror surface, the following discussion of the effects of various types of contaminants may be helpful.

Particulate Contaminants. Particulate matter which is insoluble in water may accumulate on the mirror surface, but usually will not affect the instrument accuracy until the mirror reflectance is reduced substantially, and in many cases, will improve instrument response by providing condensation sites.

Water Soluble Materials. Materials such as naturally occurring salts, which readily dissolve in water, are detrimental to accurate vapor concentration measurement by any condensation method. These materials readily go into solution with the water condensate on the mirror surface, then reduce the vapor pressure in accordance with Raoult's Law. As the concentration increases with time, the saturation vapor pressure of the liquid solution decreases, and the control loop responds by elevating the mirror temperature to maintain a vapor pressure that is in equilibrium with the partial pressure of the water vapor in the atmosphere. The displayed dew point, therefore, drifts upward with respect to the true dew point. Because the measurement error increases gradually, it often goes undetected. This condition is most easily detected by noting the indicated dew point, cleaning the mirror, balancing the detector, then measuring the dew point again. If the new reading is lower than the first reading, there is probably soluble material present in sufficient quantity to cause a measurement error.

Gaseous Contaminants. If a gaseous material were present which had a higher condensation temperature than that of water, even if present in very low concentrations, the system control loop will eventually control on that material rather than on water. The system then displays the condensation temperature of that material, not water. Such material would accumulate on the mirror only while chilled. Fortunately, while such a situation could arise in an industrial environment, it is normally not a problem in the natural atmosphere. An exception might be when flying through emissions from a power plant or industrial smokestacks.

Minimizing Effects of Contaminants. In marine environments, or other situations where contaminant levels are unusually high, one may reduce the rate at which contaminants accumulate on the mirror by reducing flow and/or by increasing condensation thickness.

4.2.3 Supercooled Dew Points

When making measurements in the frost point region of 0 to -40°C , there is the possibility that the mirror is actually controlling on the supercooled dew point, which is 0.1 to 4°C below the actual frost point. (See Appendix 1 for frost point/dew point conversions.) This is a relatively improbable situation, since dew cannot exist indefinitely below 0°C , and will sooner or later transform to ice.

To guarantee that the mirror is controlling on frost rather than supercooled water, switch S-1 to MAX COOL briefly to force cool the mirror several degrees lower than its previous reading. Upon release of the MAX COOL switch, the mirror may attempt to overshoot

above 0°C, causing the deposit to melt. Prevent this by again switching to MAX COOL to hold mirror below 0°C. This will insure that final reading will be in terms of frost point.

4.2.4 Low Frost Points

At very low frost points, it is good practice to allow the instrument to operate continuously, to assure operation in the ice phase.

Performing a rebalance is not recommended, as it could take hours for the frost layer to reform. If a balance check is done or the mirror is otherwise cleared of its frost layer, take a reading just before clearing; allow sufficient time to reform a stable ice layer afterwards.

The MAX COOL switch allows the operator to determine whether there is adequate cooling when the system is operating at very low frost points. Momentarily switch to MAX COOL and observe the dew/frost point display. If the indicated temperature drops, there is reserve cooling capability.

4.2.5 Pressure Effects

The 1011C system will display the Dew/Frost Point at the pressure that the sensor chamber is exposed to. The location of the sensor probe on the aircraft can influence the pressure. Attaching an altimeter and comparing it with the aircraft altimeter is a convenient way of accomplishing this.

The dew point temperature is a function of the sample gas pressure. If the pressure of the gas is increased or reduced from atmospheric pressure, the dew point is correspondingly increased or decreased. It is general practice to assume, unless stated otherwise, that dew point is with respect to atmospheric pressure. To calculate dew point error due to pressure change, refer to Appendix 1.

4.2.6 Typical Response to Humidity Changes

In level flight the system should track the Dew/Frost Points very well. Typical responses to step changes are shown in Figure 9. However, be cautious about readings under the following conditions:

- Icing conditions
- Sudden transition from low to high dew points
 - Particularly with rise in ambient temperature
 - (typical on descent into warm moist air)

Under normal conditions, the 1011C will handle the transition without problem, but under severe transitions the sensing cavity may collect excessive water. Refer to next section.

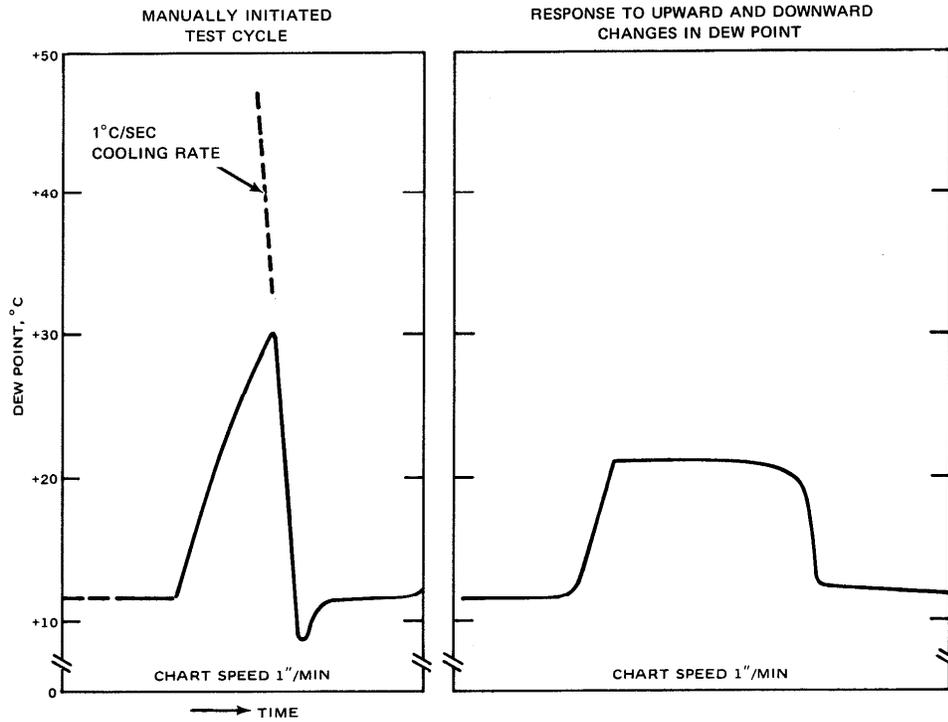
4.2.7 Mirror Flooding

Under conditions of abrupt transition from dry to moist conditions, particularly when accompanied by a transition from cold to warm temperatures, the mirror may accumulate an overload of moisture. It may then take several minutes for the sensor to “dry out”. The process can be speeded by temporarily setting the function switch of the control/indicator unit to the BALance position, thereby heating the mirror.

4.3 OPERATION WHILE PARKED OR OFF THE AIRCRAFT

The system will operate on the ground; however, with the sensing unit closed there will be almost no air exchange within the sensor cavity. To obtain readings of ambient dew point, means for supplying air to the sensor must be provided, either by opening the sensor cavity or by pumping air through. Three options, in order of preference, are:

- (1) If you have the optional aspiration system, connect it to the sensor. Set the flow to about 5 SCFH. (2.5 lpm)
- (2) If a pump and flow meter are available, but no flow test fixture, connect them to the sensor pressure port. Set flow to 5 SCFH. (2.5 lpm)
- (3) Remove the sensor body to expose the sensor cavity, being very careful not to contaminate the cavity with dirt, dust, or fingerprints. While shielding the cavity from extraneous light, allow as much free ventilation as possible



In the manually initiated test cycle shown above, the mirror heats while the function switch S-1 is in the BAL position: In this case, about 30 seconds. Upon returning the switch to operate, the system cools at its 1°C/sec rate, overshoots slightly as the dew layer forms, and then returns to the true dew point temperature.

The above trace shows the system's typical response to upward and downward changes in dew point. Note that overshooting is absent; the response of the system is rapid enough to insure control on the dew layer at all times. As long as the dew layer does not evaporate, overshooting in the response will not occur.

FIGURE 10. System Response Characteristics

SECTION 5. PREVENTIVE MAINTENANCE AND TROUBLESHOOTING

A periodic inspection and preventive maintenance program will significantly improve the performance and longevity of this equipment. The main items of routine maintenance are: periodic inspection, and mirror cleaning. Maintenance of the system is otherwise limited to that associated with troubleshooting the system.

5.1 PERIODIC INSPECTION

GENERAL. Perform periodic inspection of the system annually, or at intervals as required by the service environment and extent of use. Inspection consists of the following steps:

Visually check for damage of system components, with particular attention given to:

- cables and connectors
- O-rings and gaskets
- front panel switches and indicators
- system optics
- mounting hardware

Clean interior and exterior of all components, and tighten loose knobs and hardware, as required.

Clean and lubricate O-rings and gaskets with silicon grease. If necessary, replace any worn or damaged O-rings or gaskets, or other components.

5.2 CLEANING SYSTEM OPTICS.

The cleaning rate for the mirror is a direct function of the contaminant level of the air of the operating environment. In time, the REBALANCE LED will stay lit after balancing. This indicates that the mirror is getting dirty. Eventually it will get dirty enough that the SERVICE MIRROR LED will light and the mirror must be cleaned to restore proper operation. To clean the mirror:

1. Remove the four screws from the top of the sensor and set lid aside.
2. Unscrew two screws holding optics block on using supplied ball driver and lift out optics block, exposing mirror.
3. Clean the mirror using supplied cotton swab moistened with an approved solvent, such as acetone followed by water. A few light swipes is sufficient; use only enough solvent to wet and clean the mirror.
4. Reassemble the sensor by replacing optics block and lid.

APPENDIX 1

1011C PIN OUT:

DATA OUT

A-DEW POINT INDICATION FLAG (5V = dew point)
B-COMMON
C-BALANCE
D-COMMON
E-PRESSURE
F-COMMON
G-TEMPERATURE (Dew Point)
H-COMMON
J-HEATER (**NOT USED**)
K-SHIELD

RS-232

2- Rx
3- Tx
5- Ground

POWER

A-+28 VDC
B-+28V Return
C-Chassis Ground (B and C are wired together on the cable, if supplied)

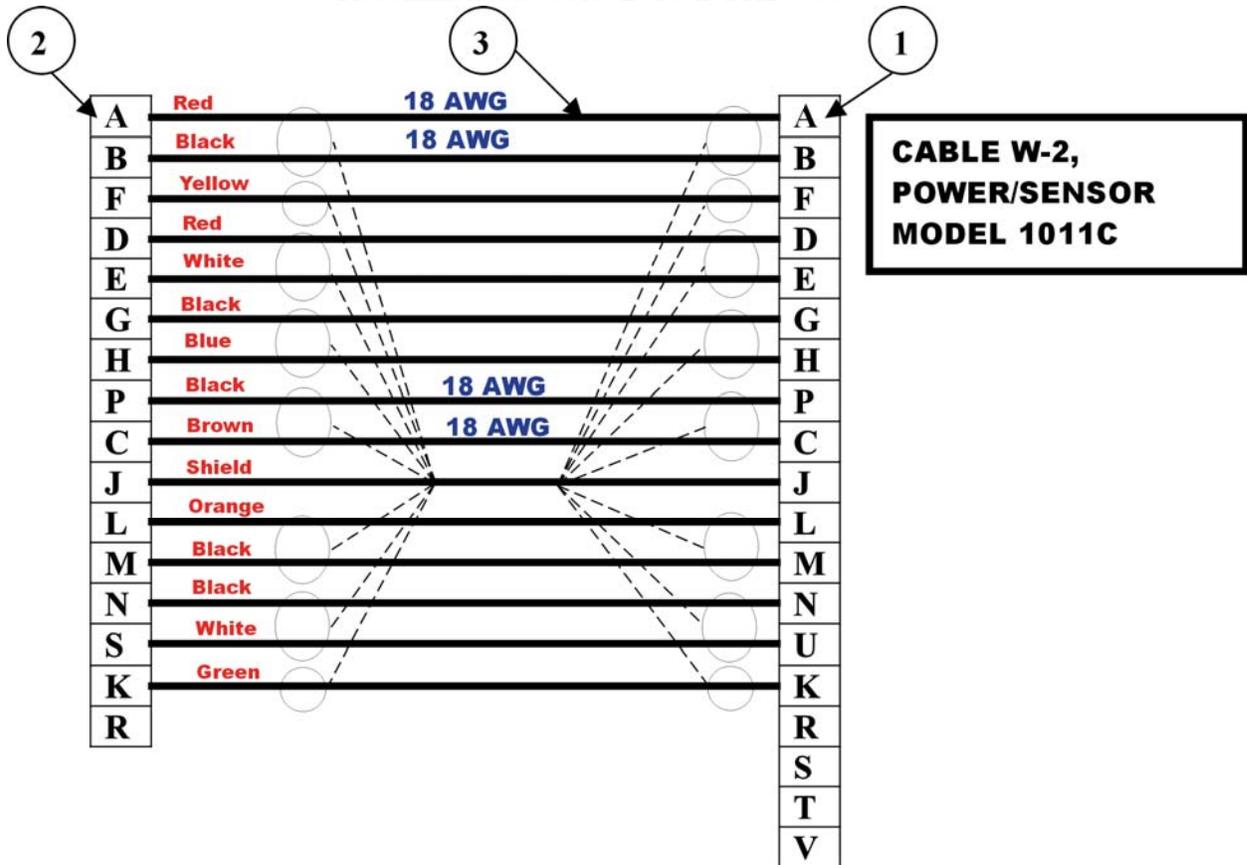
PRESSURE (to connect up an external pressure sensor)

A-Heater Power, +28 VDC (optional)
B-Heater Return (optional)
D-Pressure + (blue wire from 4- 20 mA sensor)
E- Power, +16 VDC (red wire from 4-20 mA sensor)
J- Pressure – (do not use with 4-20 mA sensor)
K-Ground – (do not use with 4-20 mA sensor)

When using a 0-5 or 1-5 VDC sensor, you must use D,E,J and K or the sensor will not work. Calibration instructions are available by request from Buck Research Instruments, LLC.

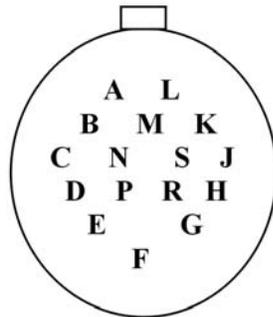
Attach shield of cable to strain relief of connector using spade lug or ring terminal

Recommended cable: Belden YR27540

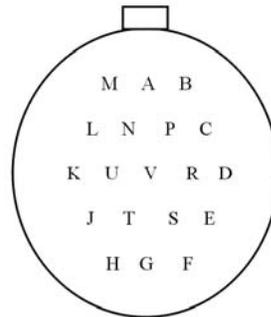


Notes:

1. Cut back wire and shielding on Red/Green pair, also Black wire from both Green/Black and Yellow/Black before stripping and tinning.
2. Tie all shield drain wires together at each end and connect to pin J.
3. If using cable that has Belfoil instead of braided shield, put large braided shield over the outer jacket of entire cable, solder a wire and lug on each end of braid and attach to strain relief screw on connector.



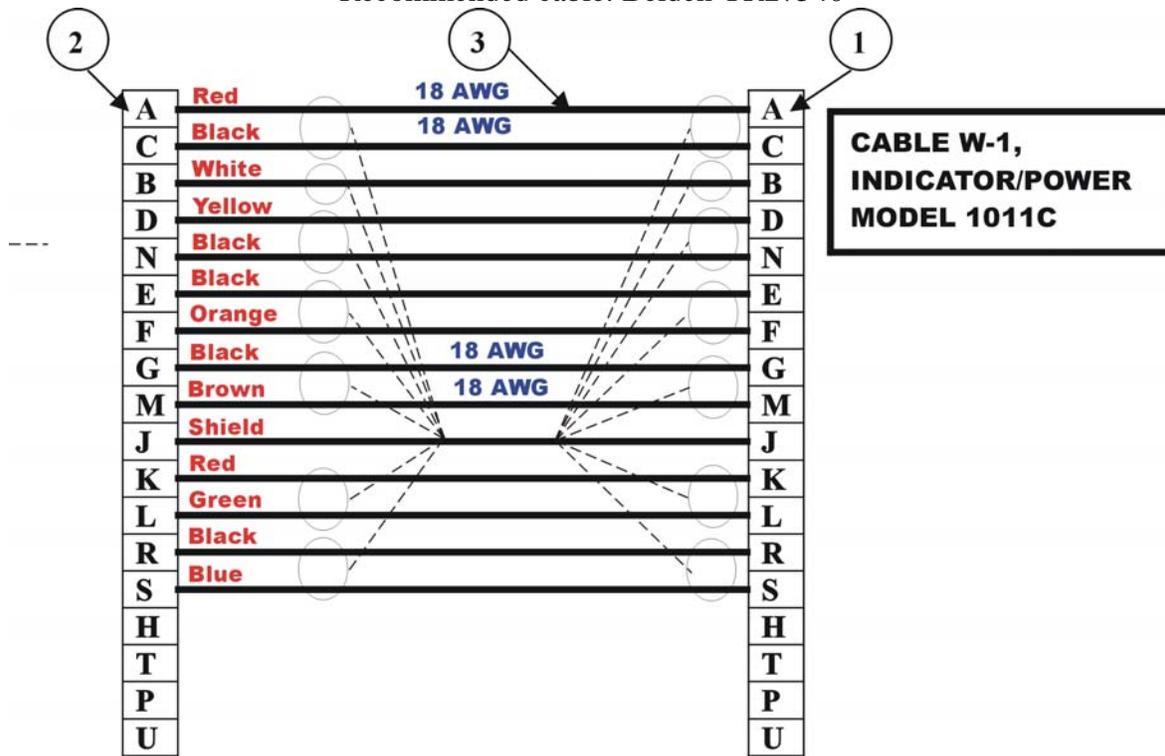
ITEM 1
WIRE SIDE VIEW



ITEM 2
WIRE SIDE VIEW

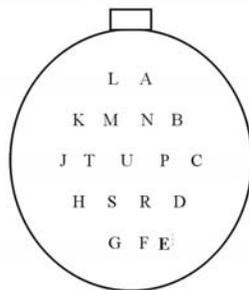
Figure 11. Wiring Diagrams

Recommended cable: Belden YR27540

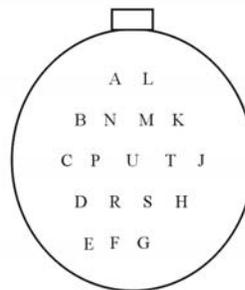


Notes:

1. Cut back wire and shielding on Red/White and Green/Black also Black from White/Black before stripping and tinning.
2. Tie all shield drain wires together at each end and connect to pin J.
3. If using cable that has Belfoil instead of braided shield, put braided shield over the entire cable, solder a wire and lug on each end and attach to strain relief screw on connector.



ITEM 2
WIRE SIDE VIEW



ITEM 1
WIRE SIDE VIEW

Wiring Diagrams Continued

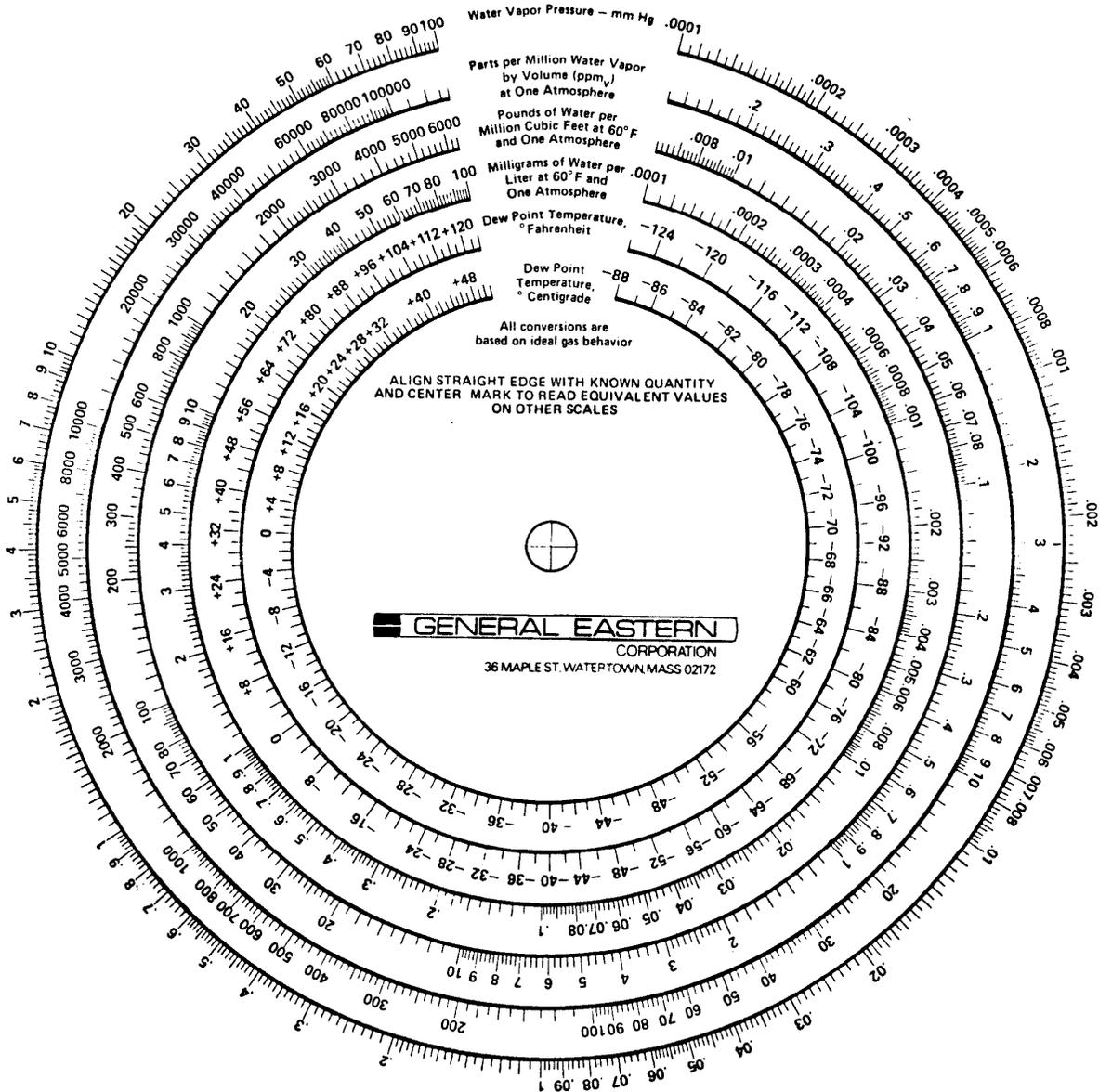


FIGURE 16. WATER VAPOR CONVERSIONS

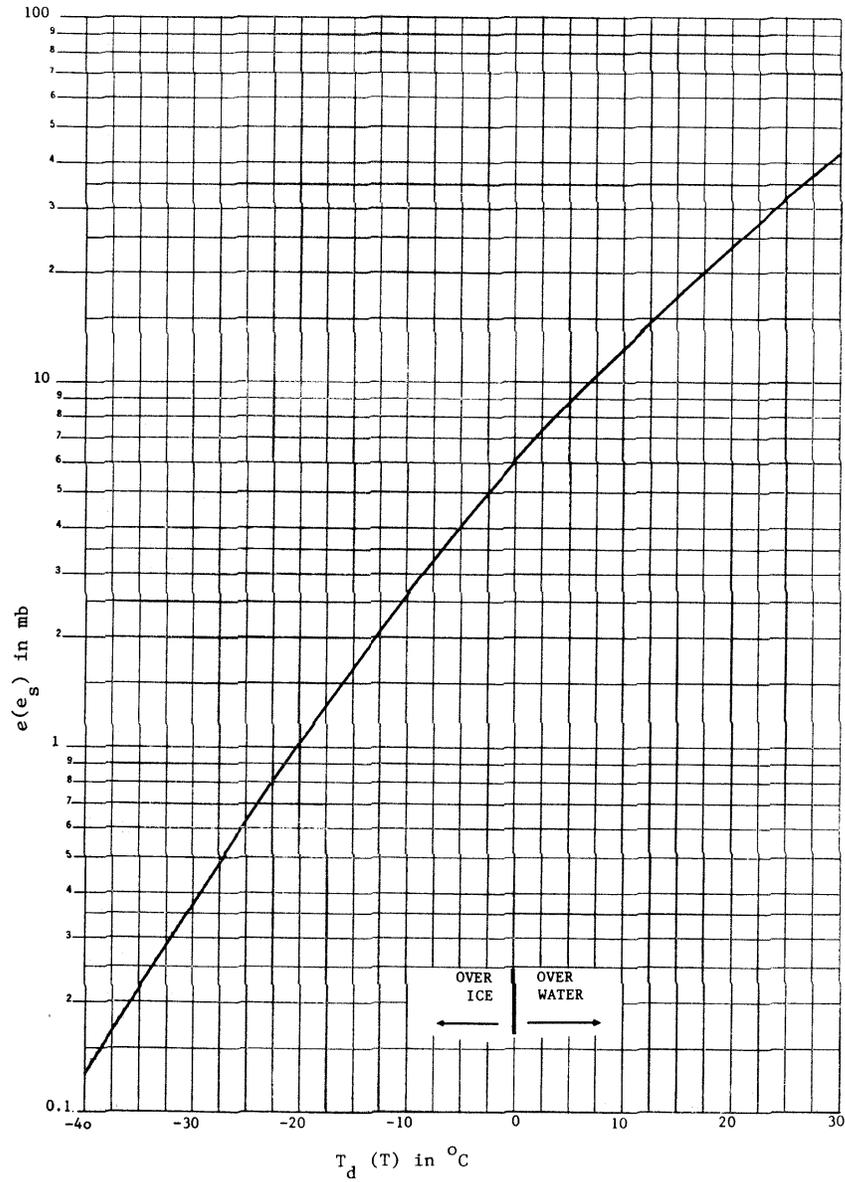


Figure 13. Vapor Pressure e vs. Dew Point T_d or Saturation Vapor Pressure e_s vs. Temperature T

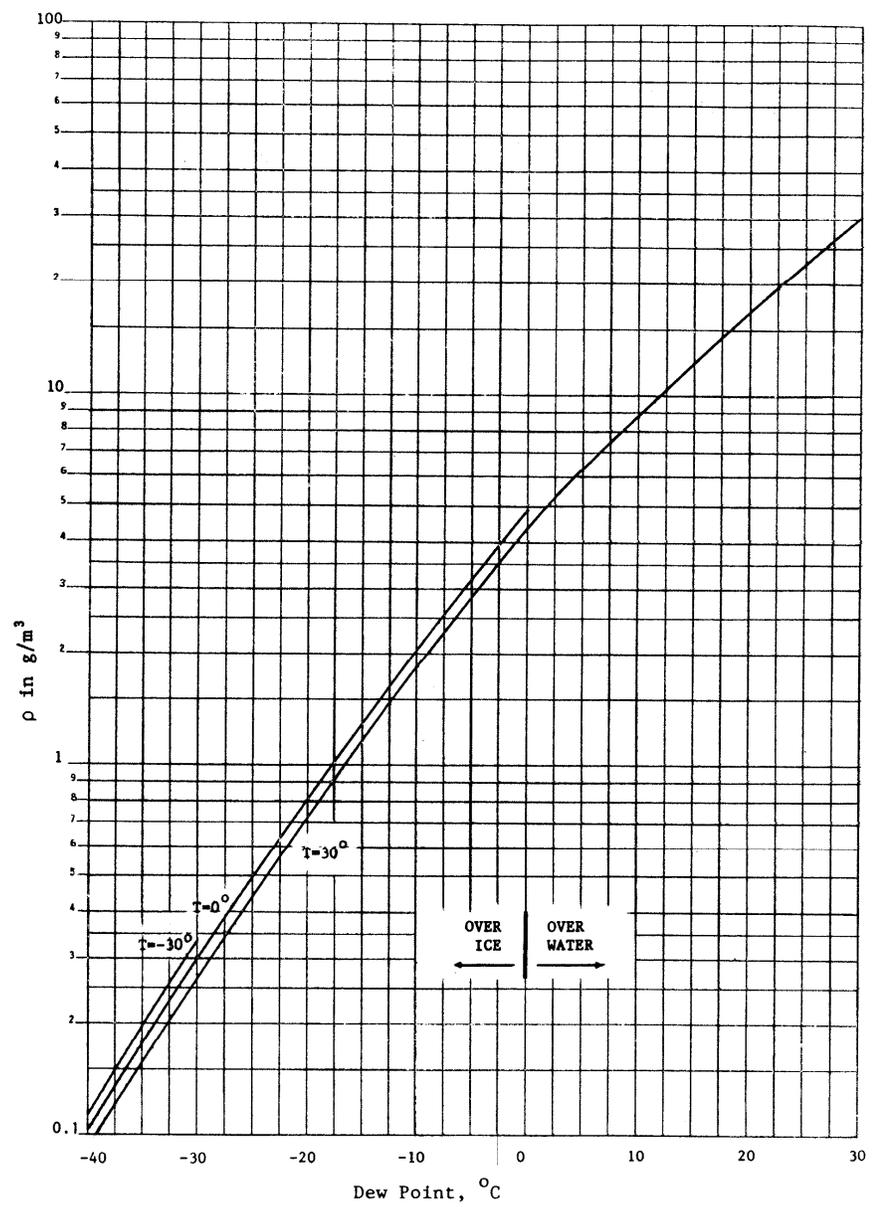


Figure 14. Absolute Humidity vs. Dew Point

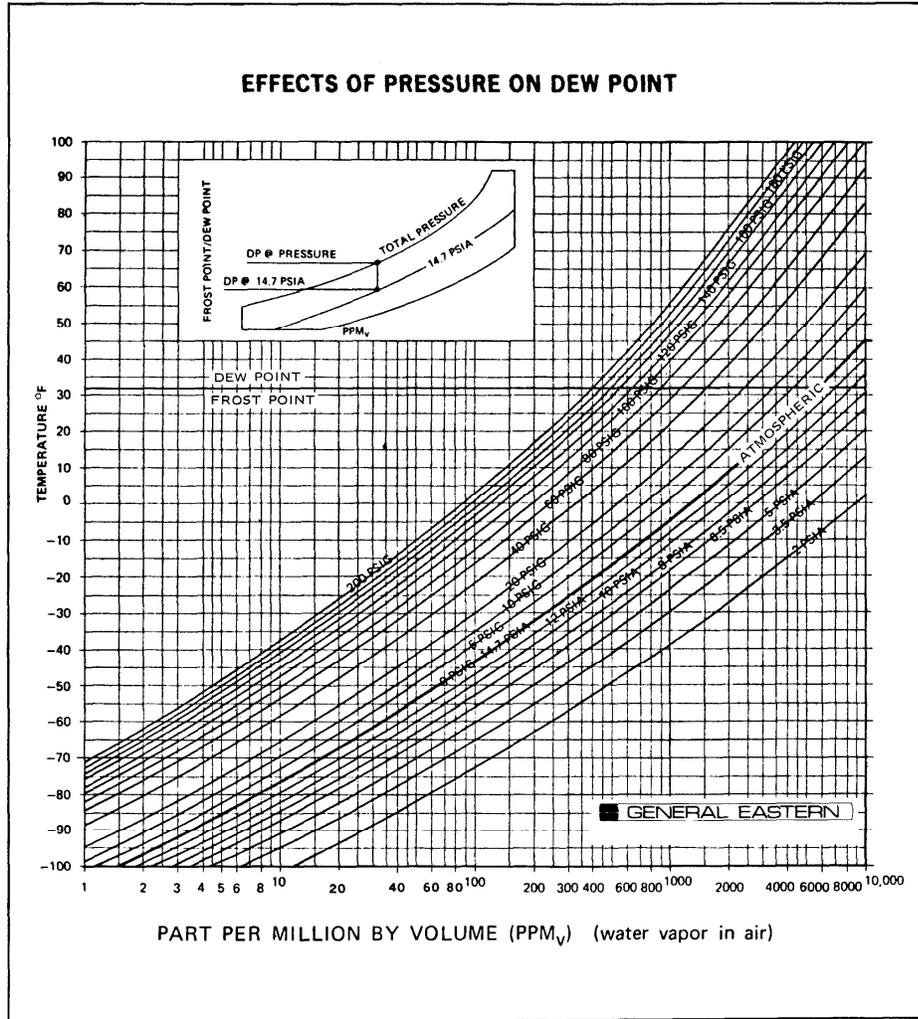


Figure 15.

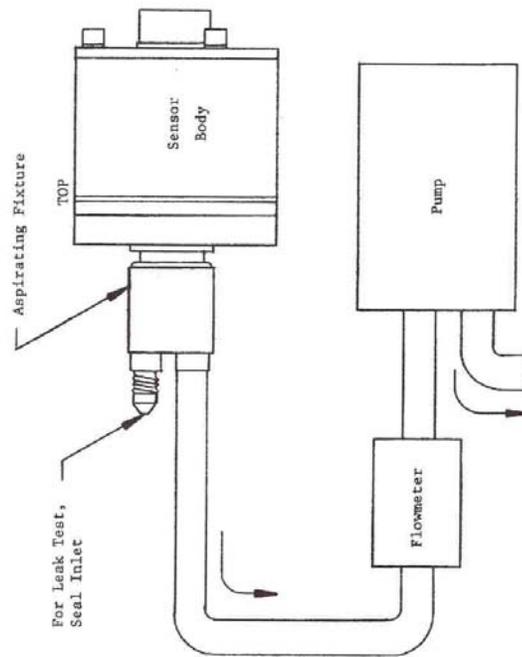


Figure 16. Aspirating Fixture Hookup



Figure 17. 1011C Hygrometer Complete

Table 1. 1011C Connectors

Power Unit	
Power In	PTO2E8 – 3P
Data Out	PTO2E12 – 10S
Sensor	PTO2E20 – 16S
Control Indicator	PTO2E14 – 18S
Serial Out	9 pin D-sub
Control Indicator	
	PTO2E14 – 18P
Cables	
Sensor	PTO6E20 – 16P – SR
	PTO6E14 – 19S – SR
Data	PTO6E12 – 10P – SR
Power	PTO6E8 – 3S – SR
Control Indicator	PTO6E14 – 18P – SR
	PTO6E14 – 18S – SR

Table 2. Dew Point to Frost Point Conversions					
Below 0°C, dew point hygrometers measure the frost point temperature rather than the dew point. The table below permits conversion from dew to frost point. For a more accurate conversion, consult the "Smithsonian Meteorological Tables."					
°C		°C		°C	
FROST POINT	DEW POINT	FROST POINT	DEW POINT	FROST POINT	DEW POINT
0	0	-15.5	-17.3	-31.0	-34.1
- 0.5	- 0.6	-16.0	-17.9	-31.5	-34.7
- 1.0	- 1.1	-16.5	-18.4	-32.0	-35.2
- 1.5	- 1.7	-17.0	-18.9	-32.5	-35.7
- 2.0	- 2.3	-17.5	-19.5	-33.0	-36.3
- 2.5	- 2.8	-18.0	-20.1	-33.5	-36.8
- 3.0	- 3.4	-18.5	-20.6	-34.0	-37.3
- 3.5	- 4.0	-19.0	-21.1	-34.5	-37.9
- 4.0	- 4.5	-19.5	-21.7	-35.0	-38.4
- 4.5	- 5.1	-20.0	-22.2	-35.5	-38.9
- 5.0	- 5.6	-20.5	-22.8	-36.0	-39.5
- 5.5	- 6.2	-21.0	-23.3	-36.5	-40.0
- 6.0	- 6.8	-21.5	-23.9	-37.0	-40.5
- 6.5	- 7.3	-22.0	-24.4	-37.5	-41.0
- 7.0	- 7.9	-22.5	-25.0	-38.0	-41.6
- 7.5	- 8.5	-23.0	-25.5	-38.5	-42.1
- 8.0	- 9.0	-23.5	-26.0	-39.0	-42.6
- 8.5	- 9.6	-24.0	-26.6	-39.5	-43.2
- 9.0	-10.1	-24.5	-27.1	-40.0	-43.7
- 9.5	-10.7	-25.0	-27.7	-40.5	-44.2
-10.0	-11.2	-25.5	-28.2	-41.0	-44.7
-10.5	-11.8	-26.0	-28.7	-41.5	-45.2
-11.0	-12.3	-26.5	-29.3	-42.0	-45.8
-11.5	-12.9	-27.0	-29.8	-42.5	-46.3
-12.0	-13.4	-27.5	-30.4	-43.0	-46.8
-12.5	-14.0	-28.0	-30.9	-43.5	-47.4
-13.0	-14.6	-28.5	-31.4	-44.0	-47.9
-13.5	-15.1	-29.0	-32.0	-44.5	-48.4
-14.0	-15.7	-29.5	-32.5	-45.0	-48.9
-14.5	-16.2	-30.0	-33.1	-45.5	-49.4
-15.0	-16.7	-30.5	-33.6	-46.0	-50.0

Table 3. Dew Point Error due to Pressure Change in Sampling System

dew/frost point degrees C	approx. error oC/psig
-70	0.46
-60	0.51
-50	0.55
-40	0.58
-30	0.65
-20	0.70
-10	0.77
0	0.94
10	1.01
20	1.10

These errors are calculated for sea level pressure. To adjust for actual pressure, multiply above errors by: $P(\text{sea level})/P(\text{actual})$.

altitude, feet	approximate change in psi/thousand feet
10,000	3.9
20,000	2.8
30,000	2.0
40,000	1.32
50,000	0.82
60,000	0.5

(mb/psi = 68.948; meters/ft = 0.3048)

APPENDIX 1: HUMIDITY CONVERSION EQUATIONS

(Revised 7/96)

Computer-efficient algorithms for converting among several humidity units, as used in HCON, are given here. They utilize vapor pressure formulations developed by A. Buck (1981).

DP	= dew or frost point in deg C
e	= vapor pressure in millibars
es	= saturation vapor pressure in millibars
P	= pressure in millibars
r	= mixing ratio by weight in ppm
RH	= relative humidity in percent
rho	= absolute humidity in g/m ³
rhos	= absolute humidity at saturation
T	= temperature in deg C
Tk	= absolute temperature in K

Saturation vapor pressure (es) = f1(T) = e/RH

Dew/frost point (DP) = f2(e) (e)
 = f2[r x P/(622 x 10³ + r)] (r)
 = f2(RH x f1(T)/100) (RH)
 = f2(rho x Tk/216.7) (rho)

Vapor pressure (e) = f1(DP) (DP)
 = r x P/(622 x 10³ + r) (r)
 = RH x f1(T)/100 (RH)
 = rho x Tk/216.7 (rho)

Mixing ratio (r), ppmw = (18.02/ M.W. of gas) x 10⁶ x e/(P-e) (e)
 = (18.02/ M.W. of gas) x 10⁶ x f1(DP)/[P - f1(DP)] (DP)
 = (18.02/ M.W. of gas) x 10⁶ x RH x es/(100 x P - RH x es) (RH)
 = (18.02/ M.W. of gas) x 10⁶ x rho x Tk/(216.7 x P - rho x Tk) (rho)

Relative humidity (RH) = 100 x f1(DP)/f1(T) (DP)
 = 100 x e/es (e)
 = 100 x r x P/[(622x10³ + r) x es] (r)
 = 100 x rho x Tk/(216.7 x es) (rho)

Absolute humidity (rho)= 216.7 x f1(DP)/Tk (DP)
 = 216.7 x e/Tk (e)
 = 0.2167 x r x P/[(622 + .001 x r) x Tk] (r)
 = 216.7 x RH x es/(100 x Tk) (RH)

mixing ratio by volume (ppmv) = mixing ratio by weight (ppmw) x (M.W. of gas)/ 18.02

grains/lb = r x 0.007

Precipitable cm per km = rho/10

NOTE 1: $f_1(DP)$ and $f_2(e)$ are variations on vapor pressure formulations found in Buck, A: J Appl Met 20, pp 1527-1532 (1981). They are given by:

e vs. DP or es vs. T:

$$f_1(DP) = EF \times a_w \times \exp [(b_w - DP/dw) \times DP / (DP + c_w)] \quad (\text{over water})$$

$$= EF \times a_i \times \exp [(b_i - DP/d_i) \times DP / (DP + c_i)] \quad (\text{over ice})$$

DP vs. e or T vs. es:

$$f_2(e) = dw/2 \times [b_w - s - ((b_w - s)^2 - 4 c_w \times s/dw)^{1/2}] \quad (\text{over water})$$

$$= di/2 \times [b_i - s - ((b_i - s)^2 - 4 c_i \times s/d_i)^{1/2}] \quad (\text{over ice})$$

where:

$a_w = 6.1121$	$a_i = 6.1115$
$b_w = 18.678$	$b_i = 23.036$
$c_w = 257.14$	$c_i = 279.82$
$d_w = 234.5$	$d_i = 333.7$

$$s = \ln (e/EF) - \ln (a_w \text{ or } a_i)$$

$$EF_w = 1 + 10^{-4} [7.2 + P (0.0320 + 5.9 \times 10^{-6} T^2)],$$

$$EF_i = 1 + 10^{-4} [2.2 + P (0.0383 + 6.4 \times 10^{-6} T^2)],$$

where P is in millibars and T is in °C.

NOTE 2: RH is defined here using es with respect to ice below freezing. However, RH is also frequently defined using es with respect to water, even below freezing.

NOTE 3: These conversions are intended for use with moist air rather than pure water vapor. They therefore include EF, the enhancement factor, which corrects for the slight departure of the behavior of water in air from that of a pure gas.

NOTE 4: The definitions f_1 and f_2 for ice agree with an extrapolation of NBS values down to -120 deg C, within 0.5%.

APPENDIX 3.

WARRANTY

Manufacturer warrants that the items delivered shall be free from defects (latent and patent) in material and workmanship for a period of one year after acceptance of the specific goods by Buyer, or within 30 days of receipt of the item, whichever comes first. The Buyer's sole and exclusive remedy under this warranty shall be limited to repair or replacement. Defective goods must be returned to the Manufacturer promptly after the discovery of any defect within the above referenced one-year period. Transportation expenses to return unit to Manufacturer shall be borne by the Buyer. Return shipping to Buyer shall be borne by Buyer for valid warranty claims. This warranty shall become inapplicable in instances where the items have been misused or otherwise subjected to negligence by the Buyer

NOTWITHSTANDING ANY OTHER PROVISION OF THIS CONTRACT, NO OTHER WARRANTIES WHETHER STATUTORY OR ARISING BY OPERATION OF LAW, EXPRESSED OR IMPLIED, INCLUDING BUT NOT LIMITED TO THOSE OF MERCHANTABILITY OR FITNESS FOR PARTICULAR PURPOSE, SHALL APPLY TO THE GOODS OR SERVICES PROVIDED HEREUNDER, OTHER THAN THE REPAIR AND REPLACEMENT WARRANTY ABOVE . SELLER SHALL IN NO EVENT BE LIABLE TO BUYER OR ANY THIRD PARTY FOR ANY DAMAGE, INJURY OR LOSS, INCLUDING LOSS OF USE OR ANY DIRECT OR INDIRECT INCIDENTAL OR CONSEQUENTIAL DAMAGES OF ANY KIND.

APPENDIX 4.

RS-232 Data Stream and Pin Out for 1011C Aircraft Hygrometer

Pin Out:

- 2 – Rx (Data In)
- 3 – Tx (Data Out)
- 5 – Ground

9600 baud, 8-N-1 parity. Use included null modem cable to connect to computer running Hyperterminal or similar serial port emulator software.

14354,-14.23,0,0,-56,0, 33.00,05/08/2003, 17:47:08
14060,-13.95,0,0,-54,0, 33.00,05/08/2003, 17:47:09
13721,-13.69,0,0,-52,0, 33.00,05/08/2003, 17:47:10
13342,-13.40,0,0,-50,0, 33.00,05/08/2003, 17:47:11

Balance, mirror temperature, flag, pressure, PWM, mirror, board temp, date, time.

Balance – number that indicates how close the servo is to being balanced and a dew/frost point being measured on the mirror.

Mirror temperature – temperature on the mirror surface.

Flag – Indicates the following:

- 0 – normal operation
- 1 – dew or frost point achieved on mirror
- 2 – balance mode

Pressure – pressure in mb if sensor installed

PWM - - 255 to + 255. Indicates how much heating (+) or cooling (-) being applied to the mirror

Mirror – Indicates the following:

- 0 – mirror normal
- 1 – mirror contaminated and will need cleaning soon

Board temp – temperature on main circuit board

Date – Date in month/day/year

Time – 24 hr time

APPENDIX 5

1011C DATA OUT VOLTAGES AND CONVERSIONS

Data Out Connector Pins:

A-DPI Dew point indication – binary output of 0 V or 5 V.

If 1011C is balanced and controlling, output is 5 V, else output is 0 V. Note: this is listed as RTD in the manual.

C-Balance Vbal (0-10 V range)

Output of signal from optics. 1011C is balanced and controlling on dew or frost when Vbal is close to 5V.

E-PRESSURE for Pressure sensor option. Vpress (0-10V range)

$$\text{Press(mb)} = 100 * (\text{Vpress} - 1.6) / .64$$

G-TEMPERATURE (Dew Point) Vdf (0-10V range), Tdf range (-75 to +50)

$$\text{Tdf} = 12.5 * \text{Vdf} - 75$$

B,D,F,H are all corresponding ground connections for the outputs listed above.

APPENDIX 6

Use of fan/heat sink or heater on sensor.

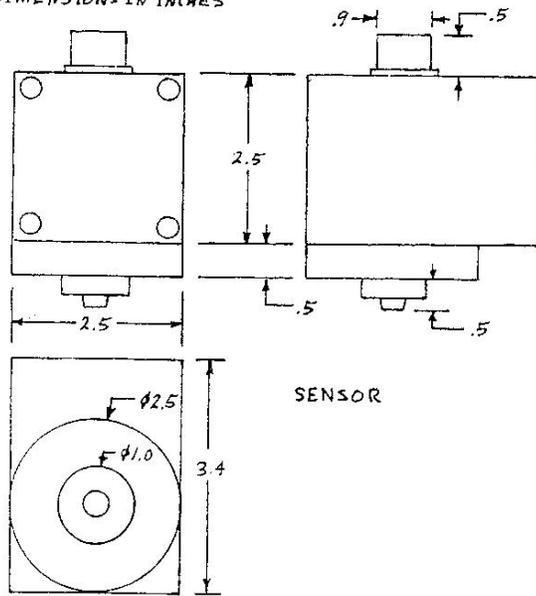
The 1011C sensor has a Molex connector on the sensor that can be used to connect either to the heat sink and fan assembly, or to a heater that is embedded under the white insulation on the side of the sensor. There is also a Molex connector that is attached across a 35 Ohm resistor that is inside the Power unit that needs to be installed or removed, depending upon how the Molex connector on the sensor is connected.

The heat sink and fan are recommended only for use in the laboratory, and not on the aircraft. If the heat sink and fan are attached, make sure that the PTC fuse is not plugged into the Molex connector that is across the 35 Ohm resistor attached to the chassis.

The heater is recommended for use only on the aircraft. When using the heater, the PTC fuse must be installed across the 35 Ohm resistor inside the Power unit.

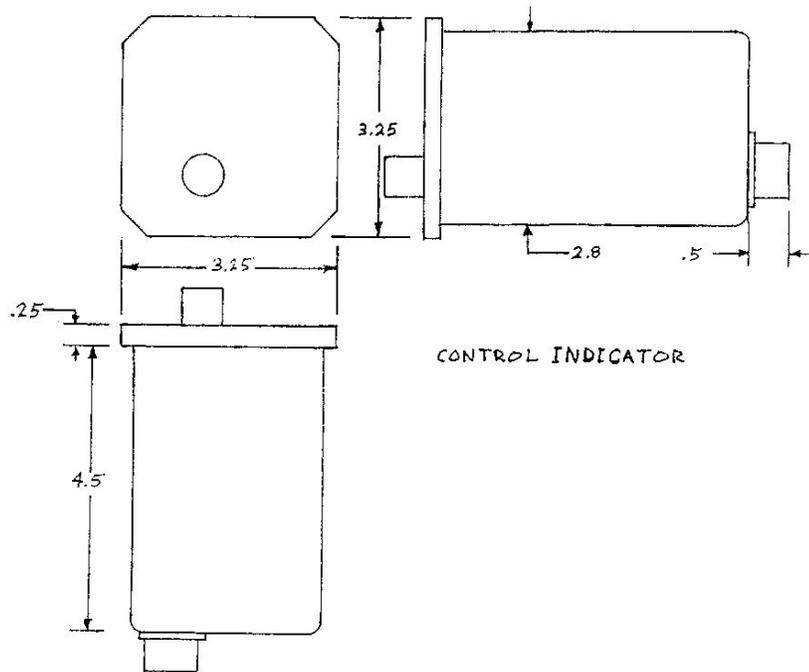
BUCK RESEARCH INSTRUMENTS

ALL DIMENSIONS IN INCHES



DIMENSIONS, IDIC SENSOR
& CONTROL INDICATOR

SENSOR

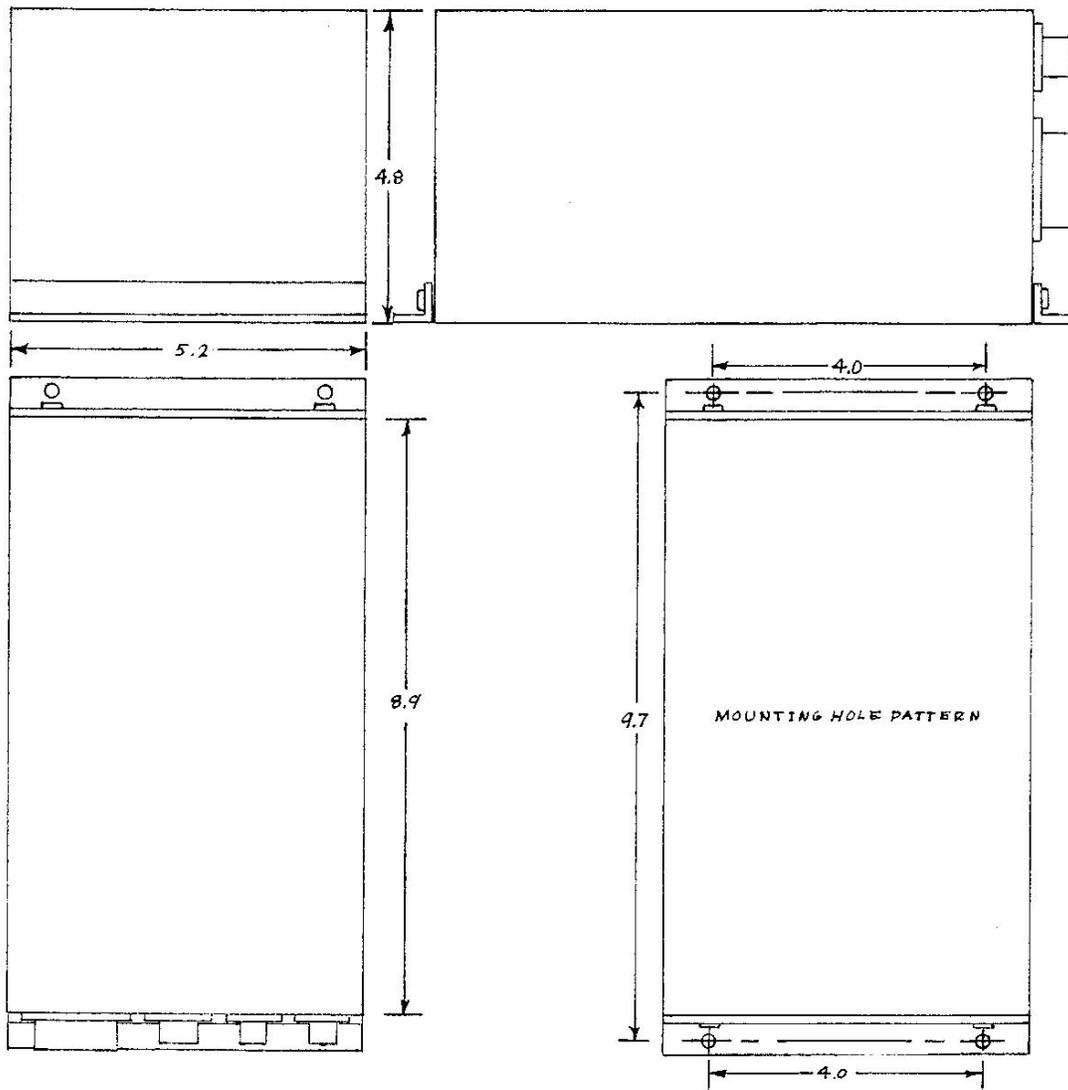


CONTROL INDICATOR

BUCK RESEARCH INSTRUMENTS

DIMENSIONS, 1011C POWER UNIT

ALL DIMENSIONS IN INCHES



Mounting hole diameter: 0.207" x 4 for #10 screws for direct mounting or for optional Barrymounts.