

USER'S MANUAL

MODEL: 5201

MODEL: 5201-MRD-MPS

PROJECTED FIELD ELECTROMAGNET MOTORIZED ROTATING DRIVE

Date Sold: _____

PROPRIETARY

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Section 1
SPECIFICATIONS
Model: 5201 Electromagnet Specifications

Field: (at max current) $B_x = \pm 0.3T$ (3000G)
(X, Y, Z = 0, 0, 4mm)

Projected Field Region (for B_x) X = ± 2 mm
Y = ± 5 mm
Z = 0 to 12mm

Coil:
coil resistance (20°C) 0.85 Ohm
max resistance (hot)* 1.02 Ohm
max power 20A/20V (400W)

Self Inductance:

Cooling: 0.5 Litre/min 1.0 bar [14 psid]

Thermal Interlock: Open circuit above 75° C (167° F)

Dimensions: Drawing 11901860
70.0 mm W x 60.0 mm D x 120 mm H
2.8 inch W x 2.4 inch D x 4.7 inch H

Weight: 4 kg (9 lb)

***CAUTION - The value of maximum coil resistance given should not be exceeded.
At this resistance the coils are at maximum safe temperature for continuous operation.**

SPECIFICATIONS

Table 1. Model 5201-MRD Specifications

Rotation Angle: [from zero point]	+/- 200 deg max
Rotation Repeatability:	+/- 0.2 deg max
Rotation Accuracy:	+/- 0.5 deg max
Mechanical Stops:	approx. +/- 210 deg max
Limit Switches:	approx. +/- 200 deg max
Homing Switch:	0.0deg
Drive System:	
Gear type	Worm/Worm Gear
Mechanical reduction	100:1
Stepper Motor:	
Motor type	VS13B-SFRIO
Motor torque	0.5Nm (73 oz.in)
Motor frame size	17
Stepper Motor Controller:	
Model	Compumotor Zeta 6104
AC Power	115V AC only
Rotation Axis Scaling:	approx. 6944 steps/deg
Dimensions:	Drawing 11901960 200 mm W x 200 mm D x 193 mm H 7.9 inch W x 7.9 inch D x 7.6 inch H
Weight:	4 kg (9 lb)

Section 2

WARNINGS

REFER TO WARNINGS BELOW BEFORE OPERATING ELECTROMAGNET SYSTEM

ELECTROMAGNET

1. Safety

In operation the magnet fringing field in the vicinity of the pole gap is in excess of 0.5mT (5G). This can cause malfunctioning of sensitive electronic and magnetic components. We recommend that warning signs are posted indicating that a magnetic field may be present.

2. Ferromagnetic Objects

During operation the magnet exerts magnetic attraction towards ferromagnetic objects in the near vicinity of its pole gap. Keep ferromagnetic items clear!

3. Arcing

This magnet stores energy in its field during operation. Do not disconnect any current lead while under load or the magnetic field energy will be discharged across the interruption causing arcing and possible damage to electronic circuits.

4. Coil Hot Resistance

Do not exceed the maximum coil hot resistance given in the specifications or coil overheating and possible damage may occur.

5. Watches, Credit Cards, and Magnetic Disks

Do not move magnetically sensitive items into the close vicinity of the magnet pole. Even some anti-magnetic watches can be damaged when placed in close proximity to the pole gaps during operation. Credit cards, and magnetic disks are affected by magnetic fields as low as 0.5mT (5G). Depending on the previous operating field and the pole gap, the remanent field in the gap can be in excess of 0.5mT (5G) with the magnet power supply off or disconnected.

MOTORIZED ROTATIONAL DRIVE

1. Hand Operation

Do not rotate the Motorized Rotating Drive platen by hand. For hand operation the Motor Drive assembly must be removed. See maintenance section for instruction on how to remove the Motor Drive assembly.

2. Obstructions

Keep foreign objects and tools clear of the Motorized Rotation Drive. Ensure the Electromagnet and Motorized Rotation Drive do not contact obstructions during rotation.

Section 3

INSTALLATION HARDWARE

Mounting Position (Refer to drawing 11902050)

The magnet system can be mounting in any orientation, including being completely inverted. The motorized rotating drive can be adjusted for height and also leveled by following the procedure below.

1. Loosen setscrew [item 19]
2. Screw –in/out foot assembly to adjust height and level as required
3. Retighen setcrew [item 19]

Four M5 mounting holes are provided on the bottom of the Motorized Rotating Drive for inverted mounting or securing to test fixture etc.

Electrical Connections

The magnet system comes with integrated wiring for the magnet, and motorized rotating drive. Never connect or remove cables from the magnet system with the AC power energized otherwise damage to the magnet power supply or MRD stepper motor controller may occur. Follow instruction below for making electrical connections.

Power Supply (Refer to drawing 11901950 & 13900420)

1. Plug in the magnet cable plug into the back of Kepco BOP power supply.
2. Secure the connecting plug with the two securing thumbscrews.
3. Connect the three sleeved wires to the output connector block on the rear of the Kepco BOP power supply as detailed below.
 - Black Wire with RED sleeve to Output
 - Black Wire with BLUE sleeve to Common
 - Green wire to Ground
4. Connect GPIB ribbon cable to edge connector on GPIB board.
5. Connect GPIB adaptor into the back of Kepco BOP power supply.
6. Secure GPIB adaptor with the two adaptor securing thumbscrews.
7. Connect GPIB cable to adaptor and secure with GPIB connector thumbscrews.
8. Connect the other end of the GPIB cable to the host computer.
9. Secure GPIB cable with the two GPIB connector securing thumbscrews.
10. Connect Kepco power supply to AC power source with cord set provided.

Motorized Rotating Drive (Refer to drawing 13900350)

1. Plug in the black 9 way plug on the MRD cable into the Motor connector on the Zeta 6104 controller.
2. Plug in the black 4 way plug on the MRD cable into the Limits connector on the Zeta 6104 controller.
3. Plug in the black 4 way plug on the serial communication cable into the Com 1 connector on the Zeta 6104 controller. Connect other end to host computer.
4. Connect Zeta 6104 controller to 115V AC power source with cord set provided.

Section 3

INSTALLATION HARDWARE

Electrical Interlocks

The Model 5201 has two temperature switches, Selco part no 802L-075. They are located on the pole/coil assembly heatsinks and wired in series. The temperature switches are normally closed, opening when the coil heatsink temperature exceeds $75^{\circ}\text{C} +/5^{\circ}\text{C}$.

Water Cooling (Refer to drawing 11901960)

The Model 5201 can be operated to an average coil temperature of 70°C . Assuming an ambient laboratory temperature of 20°C and a temperature coefficient of resistivity for copper of $0.0039/^{\circ}\text{C}$, the hot resistance of the coil should not exceed 20% more than the ambient temperature "cold" resistance. The coil thermostat will open when either pole/coil heatsink temperature exceeds approximately 75°C . If either temperature switch opens then the Magnet power supply circuit breaker will trip to the off position. Clean, cool ($16^{\circ}\text{C} - 20^{\circ}\text{C}$) water at 0.5 l/min at 1.0 bar (14 psid) should be used to cool the 5201 magnet.

The cooling copper tubes are electrically isolated from the coils to avoid electrochemical corrosion. A 50 micron filter should be placed before the input to the magnet to trap particulates and avoid blockage of the cooling circuits.

Water Cooling Connections

The magnet system has two water cooling connections provided on the rear of the motorized rotating drive. Two barbed "push on" hose couplings are provided to suit 6 mm (1/4") ID rubber hose.

- Water Inlet: Connect to a clean water source fitted with a suitable metering valve
(to control water flow).
- Water Outlet: Connect to drain.

Inlet Water Metering Valve Kit.

Metering Valve (brass)

SWAGELOCK Cat No: B-4MG2 (1 required)

Hex Coupling (brass) 1/4" NPT female

SWAGELOCK Cat No: B-4-HGC (2 required)

Hose Connectors (brass) 1/4" NPT to 1/4" Hose

SWAGELOCK Cat No: SB-PB4-PM4

(2 required)

Hose Push On (black) 1/4" ID

SWAGELOCK: Cat No: PB-4-BK (as required)

Section 3

INSTALLATION SOFTWARE

Software Requirements

- An IBM PC 486/Pentium or compatible.
- 8Mb RAM memory.
- SVGA monitor running 1024 x 768 pixels. ^[Note1]
- CD Rom Drive.
- GPIB Board [National Instruments compatible].
- Windows 95/98/ME/XP Operating System software.
- LabVIEW for Windows 95/98/ME/XP. Ver 6.0 or higher.

Motorized Rotating Drive software can also be supplied as an executable file and run directly from the Windows Operating System. In this case LabVIEW for Windows V6.0 is not required. ^[Note 2]

Software Installation

The Motorized Rotating Drive LabVIEW driver and support files are all located in a directory called 5201 Magnet Control.

To install the driver follow the directions given below.

1. Insert CD rom into computer CD ROM drive
2. Copy the complete 5201 Magnet Control directory to the host computers hard drive.
3. Locate the Default.dat file in the Data directory.
4. Right mouse click on the file properties
5. Uncheck the Read Only attribute.

Before running the 5201 Magnet Control software set the Com Port control to match the Com Port being used on the control computer. [Com 1 is the default.] The 5201 Magnet power supply is set to GPIB address 2 and is not changeable from the Setup Panel.

Note:

1. Using screen resolutions other than 1024 x 768 means all items on the LabVIEW front panels will have to be resized by the end user.
2. **The executable program file cannot be altered by the end user.** Consult GMW if the 5201 Magnet Control software is required as a executable file.

Section 4

OPERATION SOFTWARE DESCRIPTION

MAIN CONTROL PANEL

Panel Control: Makes either Setup or Automatic control panels visible.

Control Mode: Selects either Manual or Automatic control mode of operation.

Key Focus Control: When Key Focus is turned on the selected control is controlled by the Up and Down arrows on the computer keyboard. A set value can also be directly entered from the numeral keypad. By default the lowest significant digit is controlled and rolls over to the next highest digit. Roll over occurs between the lowest to the most significant digit.

System Shutdown: Sets zero current on the magnet power supply, and stop rotation on the Motorized Rotating Drive. Finally this LabVIEW application stops running, and a System Shutdown message is displayed.

MAGNET FIELD CONTROL

Setpoint Control: Selects either a current setpoint in Amps or field input in Tesla.

Setpoint Mode Control: Selects either current control or field control of the magnet system..

Excitation File Control: Makes sub panel visible for the creating and loading of open loop characterization files.

Magnet Voltage Indicator: Display voltage from the magnet power supply.

Magnet Current Indicator: Display current from the magnet power supply.

Loaded Excitation File: Displays the current loaded excitation file.

MAGNET ROTATION CONTROL PANEL

Home CW Control: Makes the motorized rotating Drive rotate in a clockwise direction until it finds the homing position at 0.0 deg and resets the current position counter to 0.0 deg.

Home CCW Control: Makes the motorized rotating Drive rotate in a counterclockwise direction until it finds the homing position at 0.0 deg and resets the current position counter to 0.0 deg.

Counter Reset Control: Resets the current position counter to 0.0 deg.

Velocity Control: Sets the velocity of the stepper motor.

Set Position Control: Sets the MRD platen to the desired position.

Immediate Control: Starts the MRD in motion as soon as set position input value is entered.

Go Control: If immediate control is turned off, no motion occurs on the MRD until the Go button is pressed.

Start Motion CCW Control: Starts the motorized rotating drive rotating in a counterclockwise direction until a soft limit is reached, or the **Stop Motion** button is pushed.

Start Motion CW Control: Starts the motorized rotating drive rotating in a clockwise direction until a soft limit is reached, or the **Stop Motion** button is pushed.

Stop Motion Control: Stops the motorized rotating drive rotating at any time.

Emergency Stop Control: Stops the motorized rotating drive rotating INSTANTLY.

FOR EMERGENCY USE ONLY.

Section 4

OPERATION SOFTWARE DESCRIPTION

MAGNET ROTATION CONTROL PANEL (Continued)

CCW Limit Control: Stops the motorized rotation drive from rotating in the counterclockwise direction when the current position counter equals the CCW limit setting. [A red indicator shows when limit is reached.]

CW Limit Control: Stops the motorized rotation drive from rotating in the clockwise direction when the current position counter equals the CW limit setting. [A red indicator shows when limit is reached.]

Current Position Indicator: Shows the motorized rotation drive current position on a digital display. Units are in degrees from the initialized zero position, [normally 0.0 deg.]

Ramp Indicator: Shows velocity ramp up and down as set position is approached.

SETUP PANEL (Visible only when selected with the Panel Control)

Com Port Control: Selects the computer serial port to use to communicate with the stepper motor controller. [Set to Com 1 as default.]

Motor Controls: Sets the acceleration, start of speed ramp down, ramp rate and axis scaling of the stepper motor. Ramp feature can be turn On or Off by the Ramp control switch

Home Motion Controls: Sets the acceleration, deceleration and velocity of the stepper motor when homing to the 0.0 deg position.

Soft Limits Range: Sets the maximum, minimum and increment on the soft limits scale. Soft Limit feature can be turned On or Off by the Soft Limits control switch.

Velocity Chart Indicator: Shows the current acceleration, deceleration and velocity of the stepper motor.

Reset Controller on Start Up: Sends a Reset command to the stepper motor controller. This command is only sent once when the program starts.

AUTOMATIC CONTROL/LOGGING PANEL (Visible only when selected with the Panel Control).

Date Indicator: Shows the data from the computers clock.

Time Indicator: Shows time from the computers clock.

Step in Progress: Shows the current row of data being used for automatic control.

Automatic Control: Turns On and Off the automatic operation from the table setting control.

Logging Control: Turns On and Off logging of system data to log file.

Table Settings Control: The table setting control has five columns of data. Step is the row of Data in use. Current or Field settings are sent to the magnet power supply. Rotation settings are sent to the Motorized Rotating Drive. Time in seconds is the interval between steps.

Step Control: Single steps the table control through steps 1,2,3,4 etc.

Zero Control: Returns the table control to step 1.

Section 4

OPERATION SOFTWARE DESCRIPTION

Auto Log Indicator: Flash's yellow when data is being written to log file.

Data to File Indicator: Shows data that will be written to log file.

Log File Indicator: Reads the data from the current log file.

Log File Name Indicator: Shows the current log file name.

New Data File Control: This control makes the Log File Setup Panel visible.

Open File Control: Reads data from the current log file and displays data in the log file indicator.

Press to Log Control: Logs one line of data to the current log file. Auto log indicator will flash yellow.

CREATE DATA FILE PANEL (Visible only when the new data file control is pressed).

Data File Header Control: Provides inputs for test engineer, magnet model, magnet serial no and test notes.
The computer date is automatically inserted into the data file.

Data File Name Control: Provides input for new file name.

Create New Data File Control: Creates a new data file and writes all the data file header information to the file. Note: If a file with the same name exists a warning will be given. Options are replace the existing file data or cancel the operation. Clicking the replace control will make a new data file with new header information.

Close Panel Control: Closes the create data file panel.

Section 4

OPERATION

To Start the Magnet System Software

Click the LabVIEW **Run** button.

To Stop the Magnet System Software

Click the red System Shutdown button located at the lower LH corner of the screen.

Magnet System Software Default Settings

The Magnet Control System software will open with all parameters set to the default settings. To change the default of a control follow the instructions listed below.

1. First stop the software by clicking on the **SYSTEM SHUTDOWN** button.
2. Then set the control to the desired default value.
3. Right mouse click on the control and select **Data Operation**.
4. Click on the selection **Make Current Value Default**.
5. Restart the Motorized Rotating Drive Software by clicking on the LabVIEW run arrow at the top left screen.

Magnet System Software Help

On screen help is available. To use the on line help use a **CTRL + H** from the keyboard to open the help window, and then move the cursor over the control or indicator on the front panel. A description of the control or indicator function will appear in the help window.

ELECTROMAGNET OPERATION (Current Control)

1. Select current control mode (default).
2. Select Setpoint on the key focus control.
3. Enter desired current from the keyboard and press the enter key.

The setpoint control pointer should move to the desired current and the correct current will be displayed in the magnet current indicator.

ELECTROMAGNET OPERATION (Field Control)

1. Select field control mode.
2. Press the create/load excitation file button.
(The open loop file characterization sub panel will appear).
3. Press the load button.
4. Select the directory where the open characterization files are located.
5. Select the desired file for the correct height above the magnet.
6. (Note for operation 4.0 mm above the magnet the correct file will be 5201-Z04.olc.)
7. Click the done button (The open loop file characterization sub panel will close).
8. The loaded file name will appear in the loaded excitation file indicator.
9. Select Setpoint on the key focus control.
10. Enter desired current from the keyboard and press the enter key.

Section 4

OPERATION

MOTORIZED ROTATING DRIVE

Setup Operation:

1. Firstly power up the Zeta 6104 stepper motor controller.
2. Start the 5201 magnet control software.
3. Click either the CW or CCW home button.
4. After the platen stops at the approximate zero point reduce the velocity setting to 0.1.
5. Use the CW or CCW motion to approach the zero mark.
6. Use the stop motion button when the zero mark is reached.
7. Press the counter reset button to set the position counter to zero.
8. Return the velocity control to the desired setting 0.5 to 2.0.

Note: Do the above operation on power up only. Do not use the home control to go accurately to 0.0 deg, use the set position control as detailed below.

Set Position Operation:

Type in the desired position into the set position control and press the enter key on the keyboard.

Note: If immediate control is turned on, the MRD will start to rotate as soon as new input value has entered and enter key pressed. If immediate control is turned off then press the GO button to start the MRD rotating to the new position.

Soft Limits Operation

1. Set the soft limits control to **enable**.
2. Set the CCW limit by clicking on the blue pointer with the mouse and dragging to the desired location on the status indicator.
3. Set the CW limit by clicking on the blue pointer with the mouse and dragging to the desired location on the status indicator.
4. Click on either the CCW or CW Start Motion button.

The motorized rotating drive will rotate in the desired direction until the soft limit is reached. The soft limit digital control will flash red when the soft limit is reached. Further rotation in the same direction will not occur. Clicking on the opposite direction **Start Motion** button will rotate the motorized rotation drive in the opposite direction until its soft limit is reached.

Hardware Limits

The hardware CCW and CW limit switches operate at approximately -200deg and +200deg respectively. After the limit switch has operated the rotation of the motorized rotating drive will decelerate at the same rate as set by the software acceleration control setting and then stop. A 5 deg overrun has been allowed for before the mechanical stops operate.

Mechanical Stops

The mechanical stops operate at -200 deg and +200 deg stopping any rotation beyond these positions.

Section 5

MAINTANCE

Electromagnet

Electrical Connections on the magnet terminal block should be checked annually. The electrical connections should be clean and tight. Discoloration is a sign that the connection is overheating and must be rectified before further use of the magnet.

Water Hoses should be checked regularly for water leaks. Any leaks should be rectified before further use of the magnet.

Motorized Rotating Drive

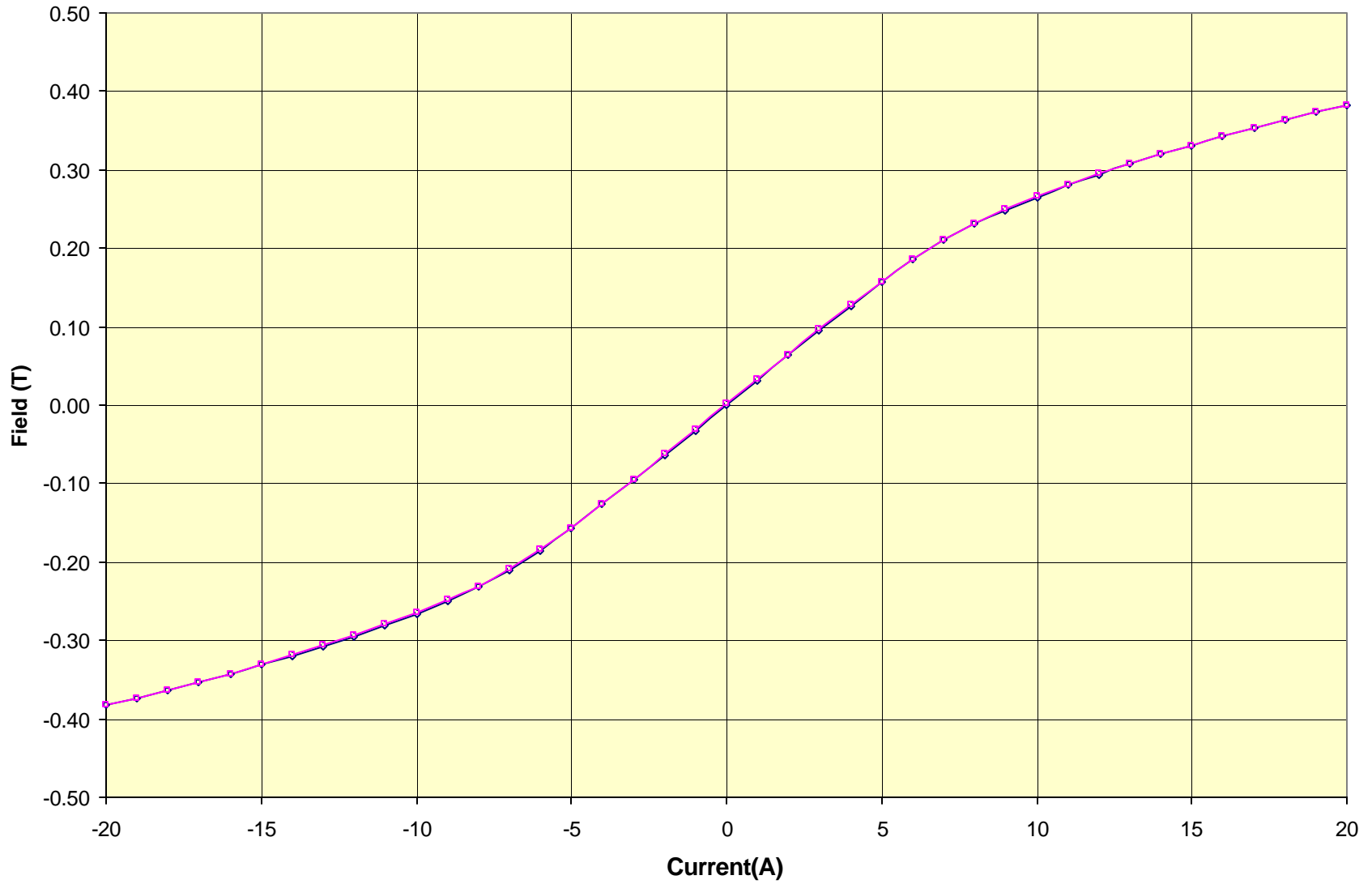
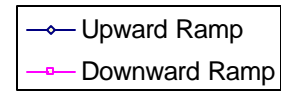
Rotating Platen contains nylon ball bearings and does not require periodic lubrication.

Worm Gear should be lubricated annually by smearing the worm gear with a coating of a graphite based grease.

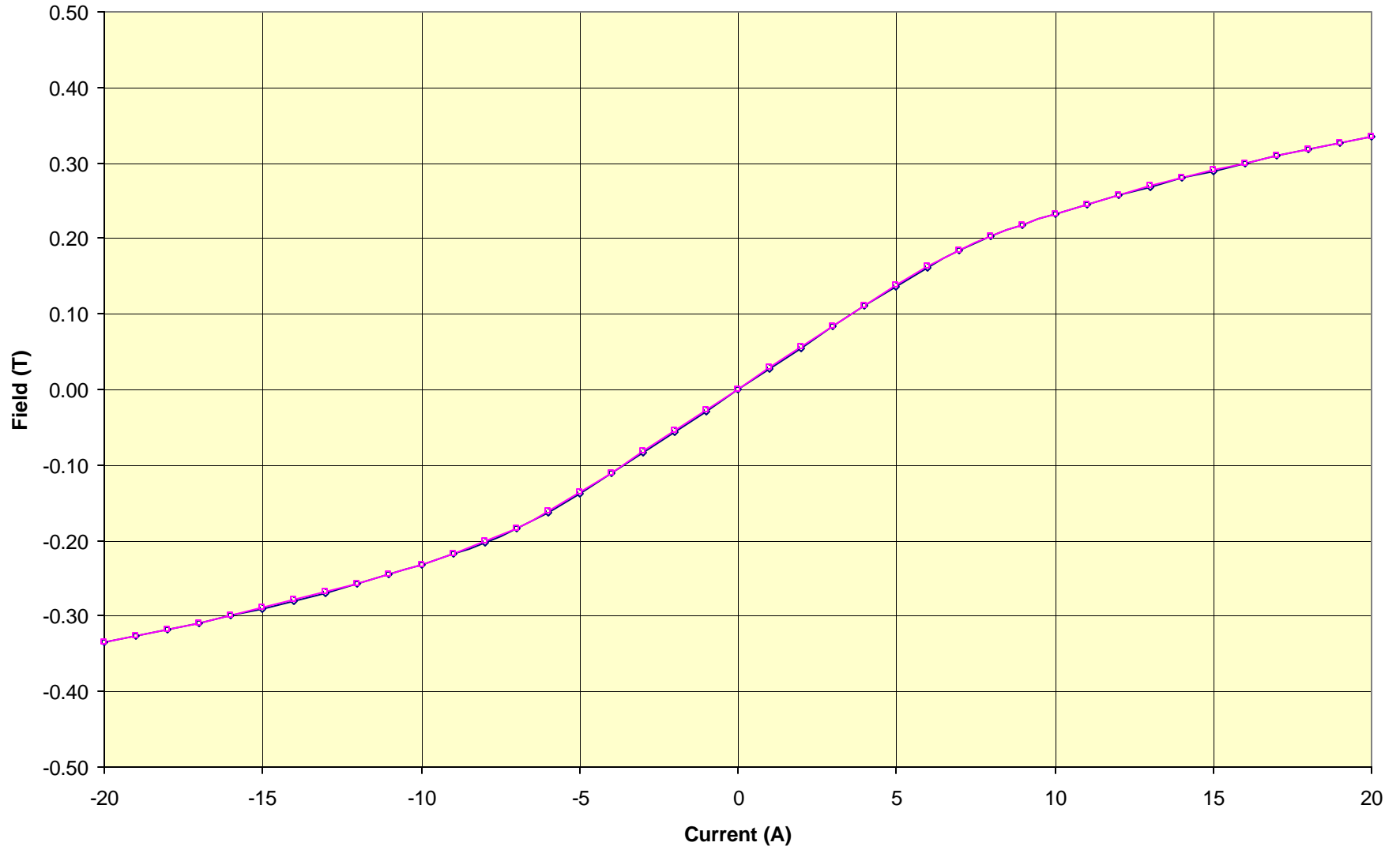
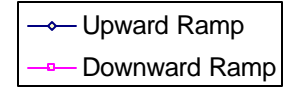
Section 6

EXCITATION CURVES

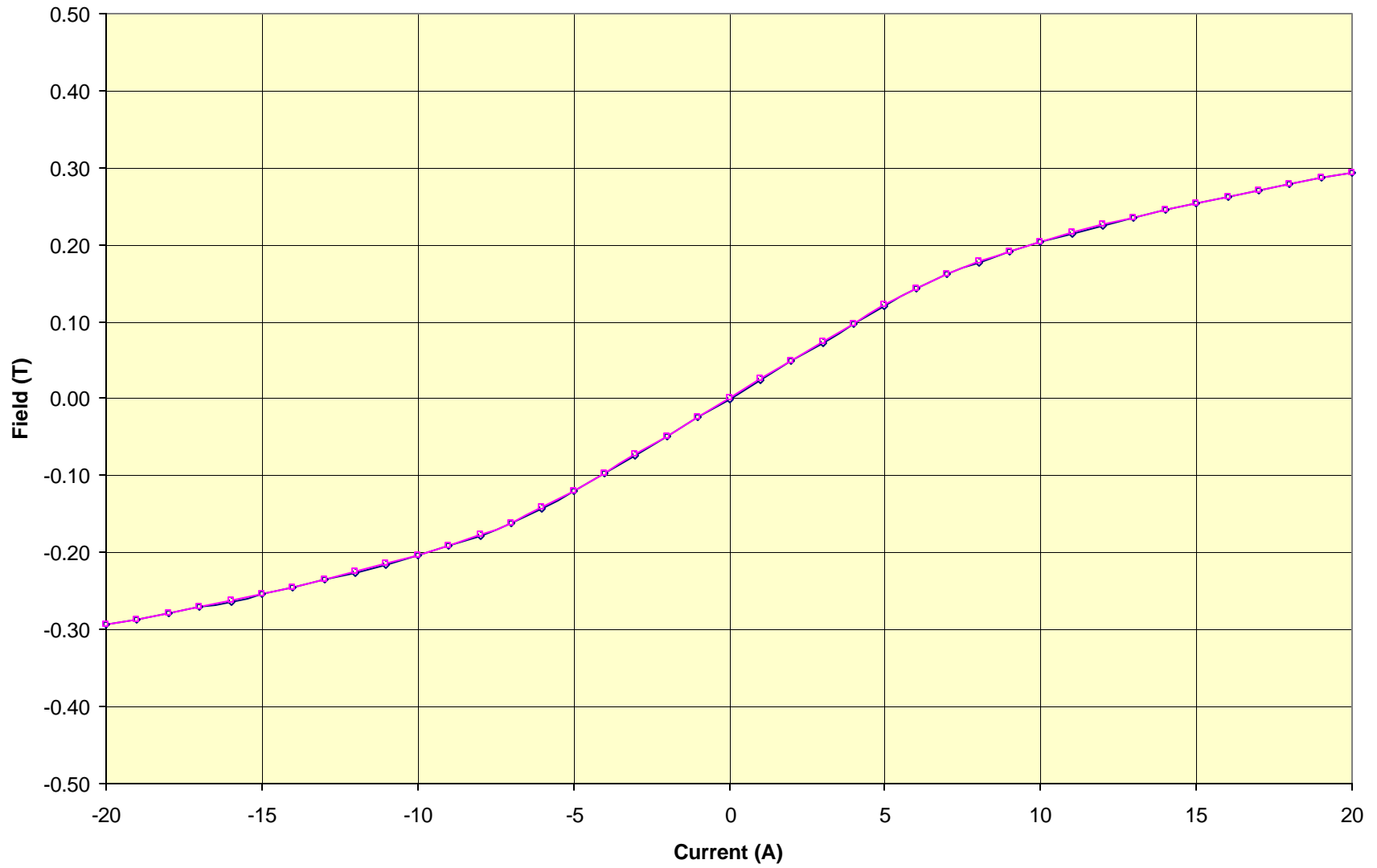
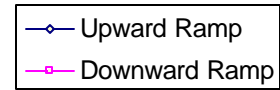
Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=2mm)



Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=3mm)

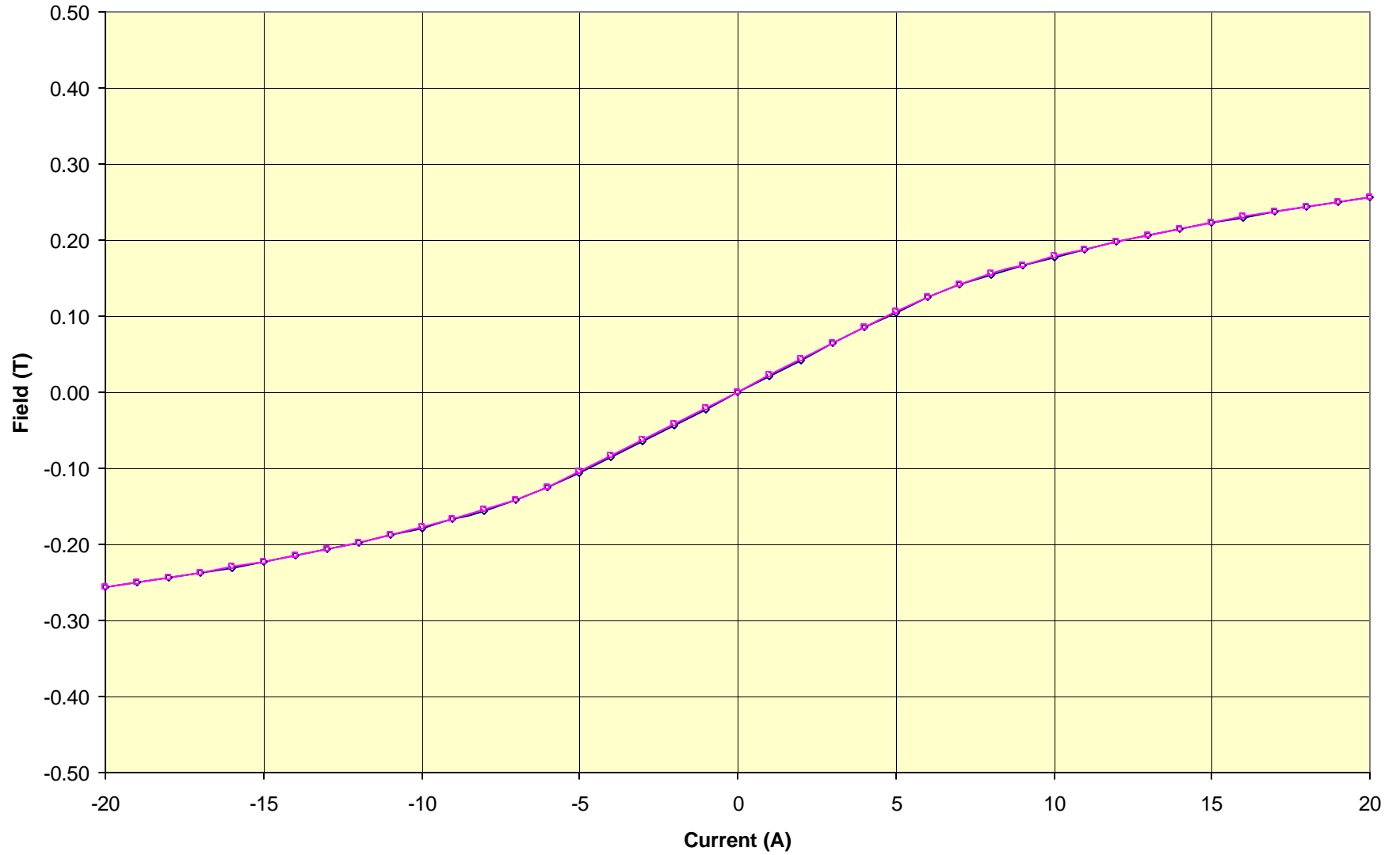


Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=4mm)

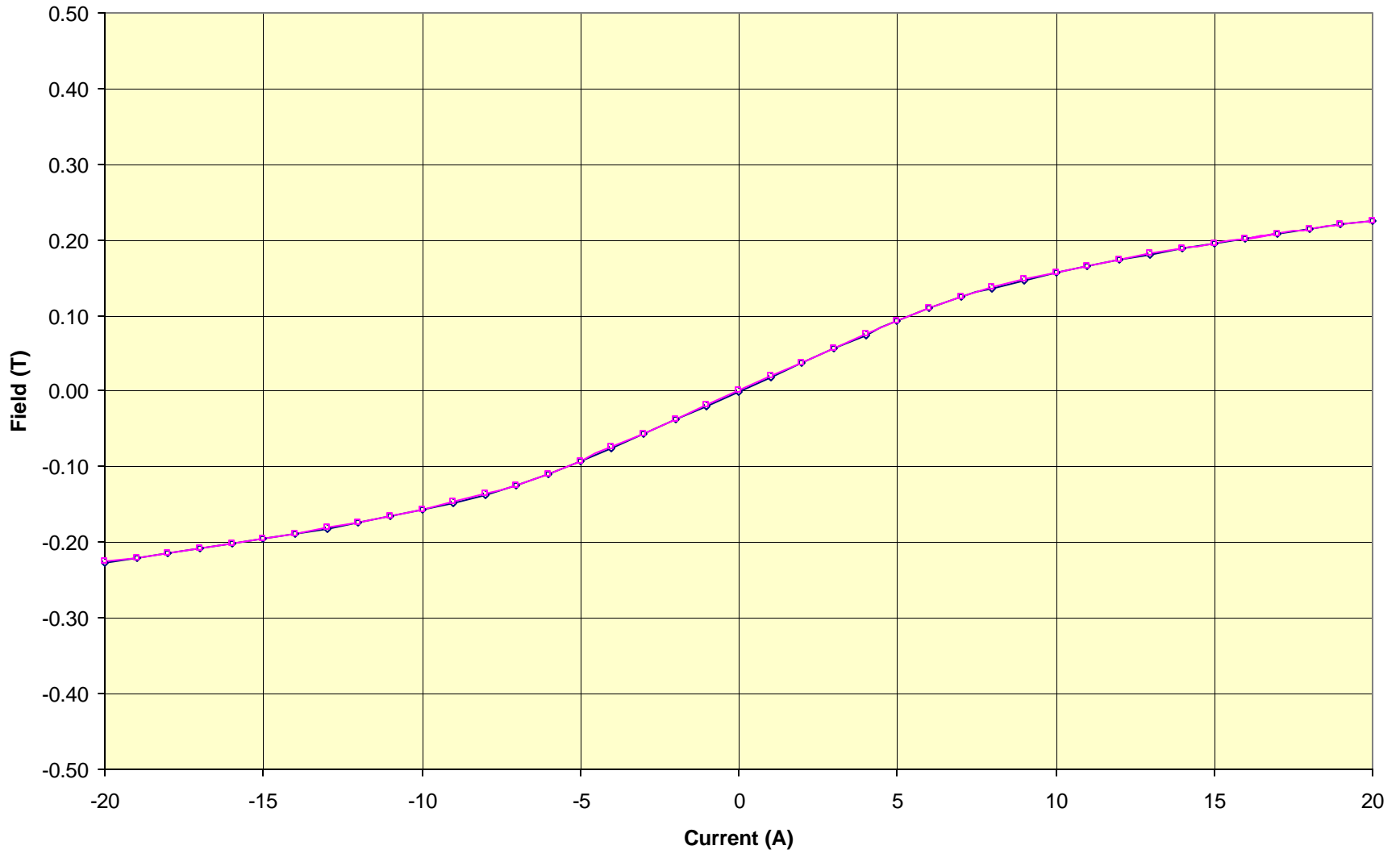
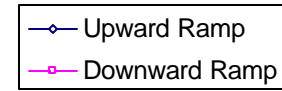


Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=5mm)

Upward Ramp
Downward Ramp

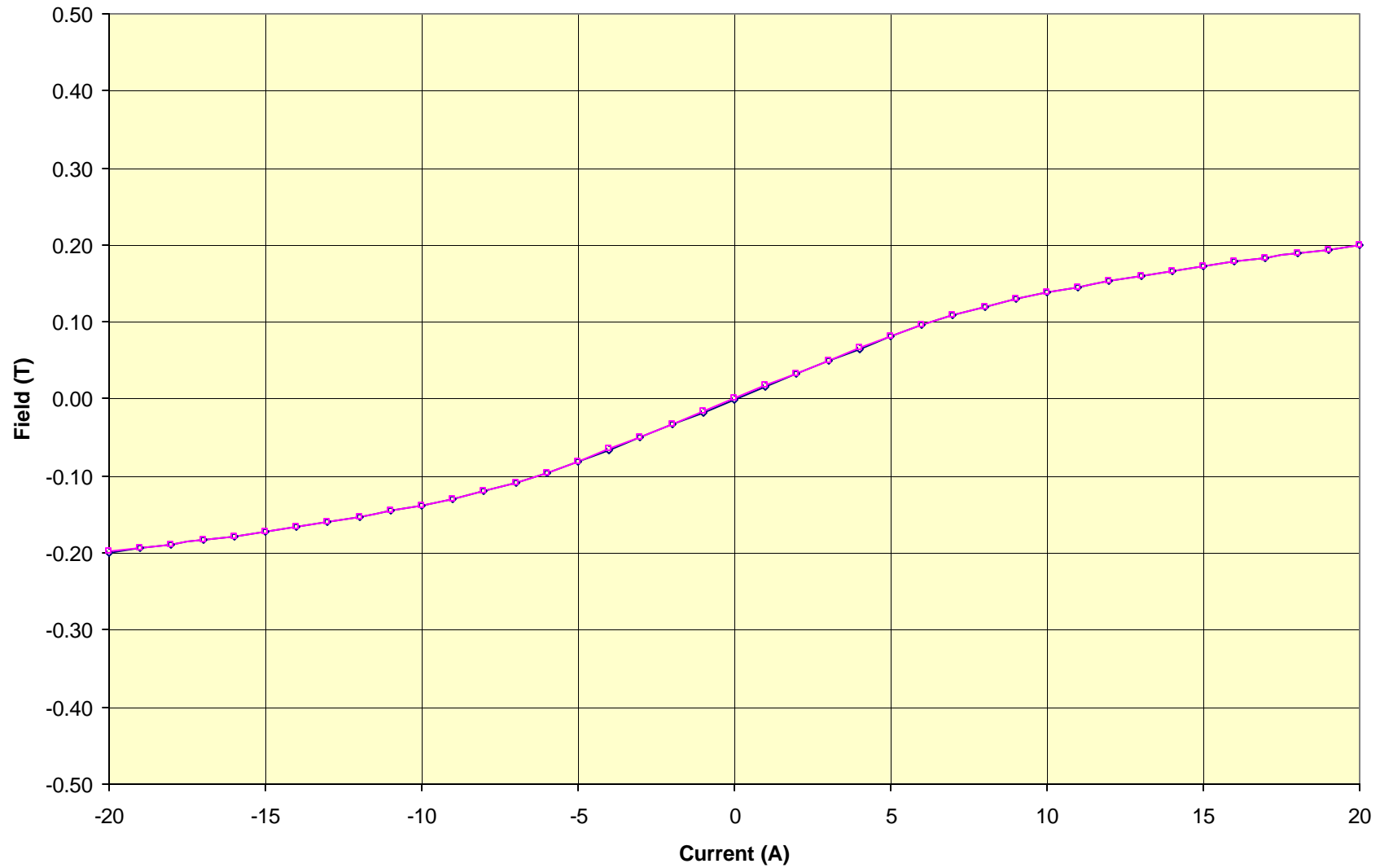


Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=6mm)



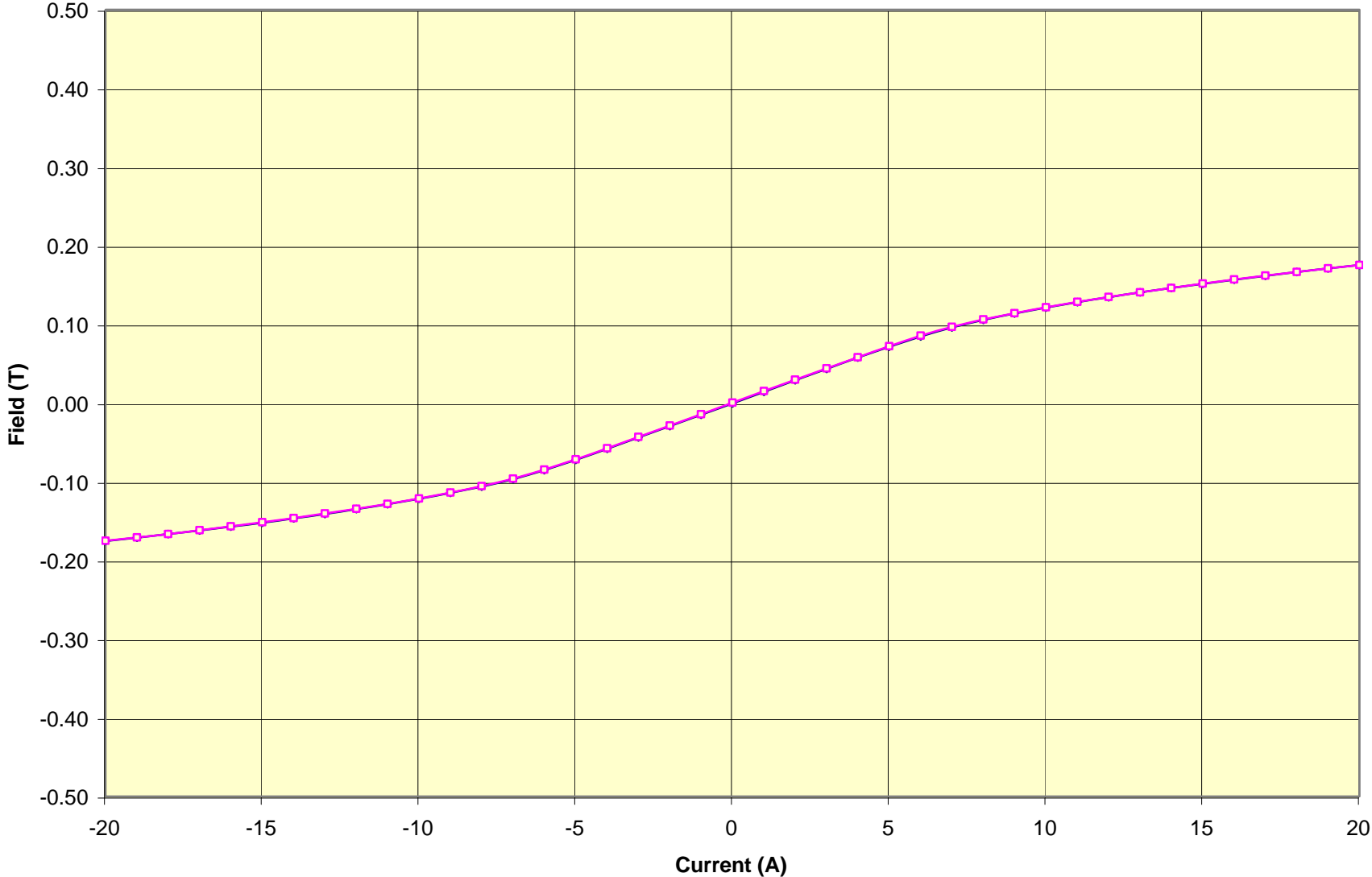
Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=7mm)

Upward Ramp
Downward Ramp

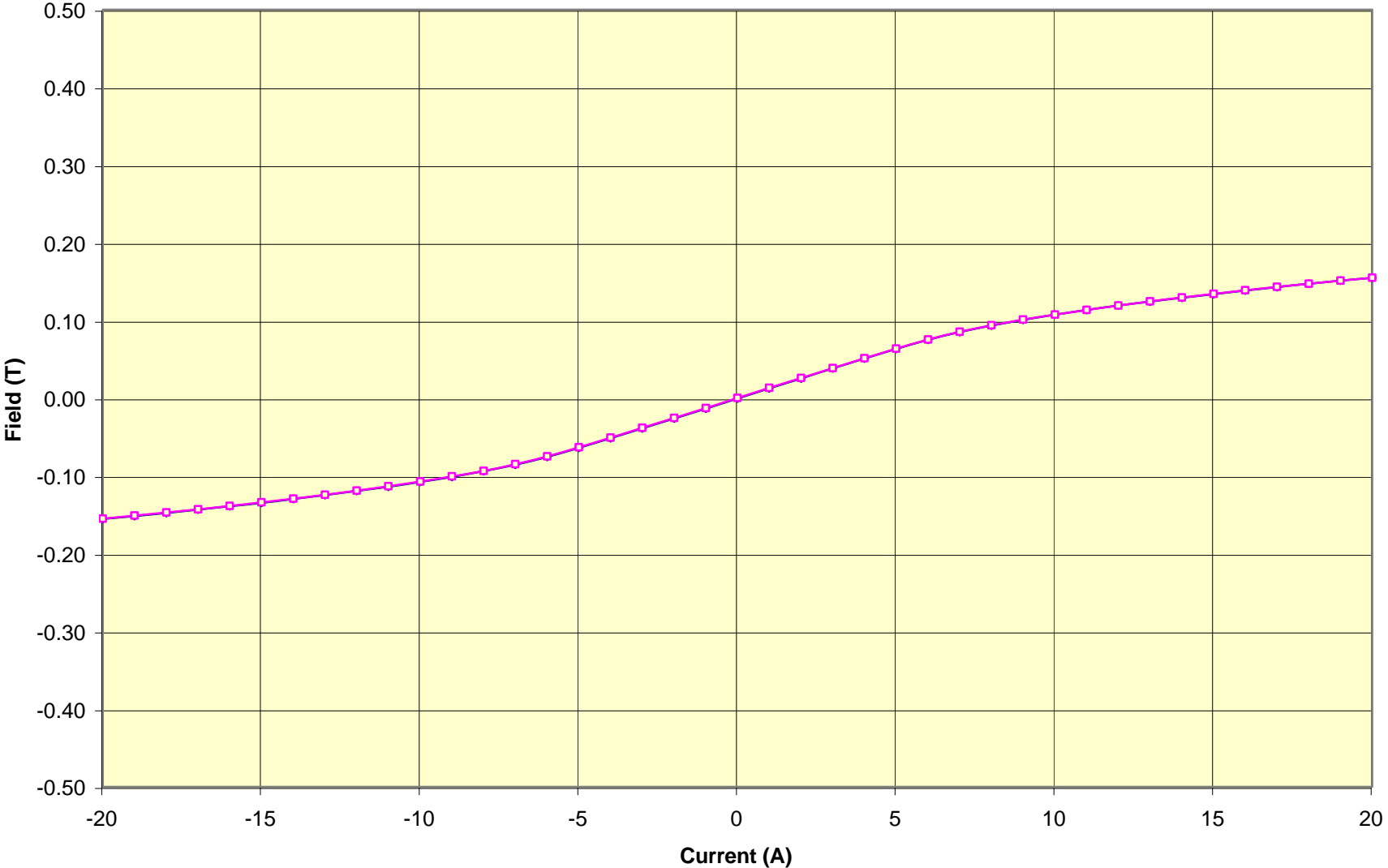
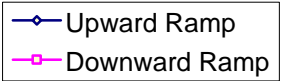


Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=8mm)

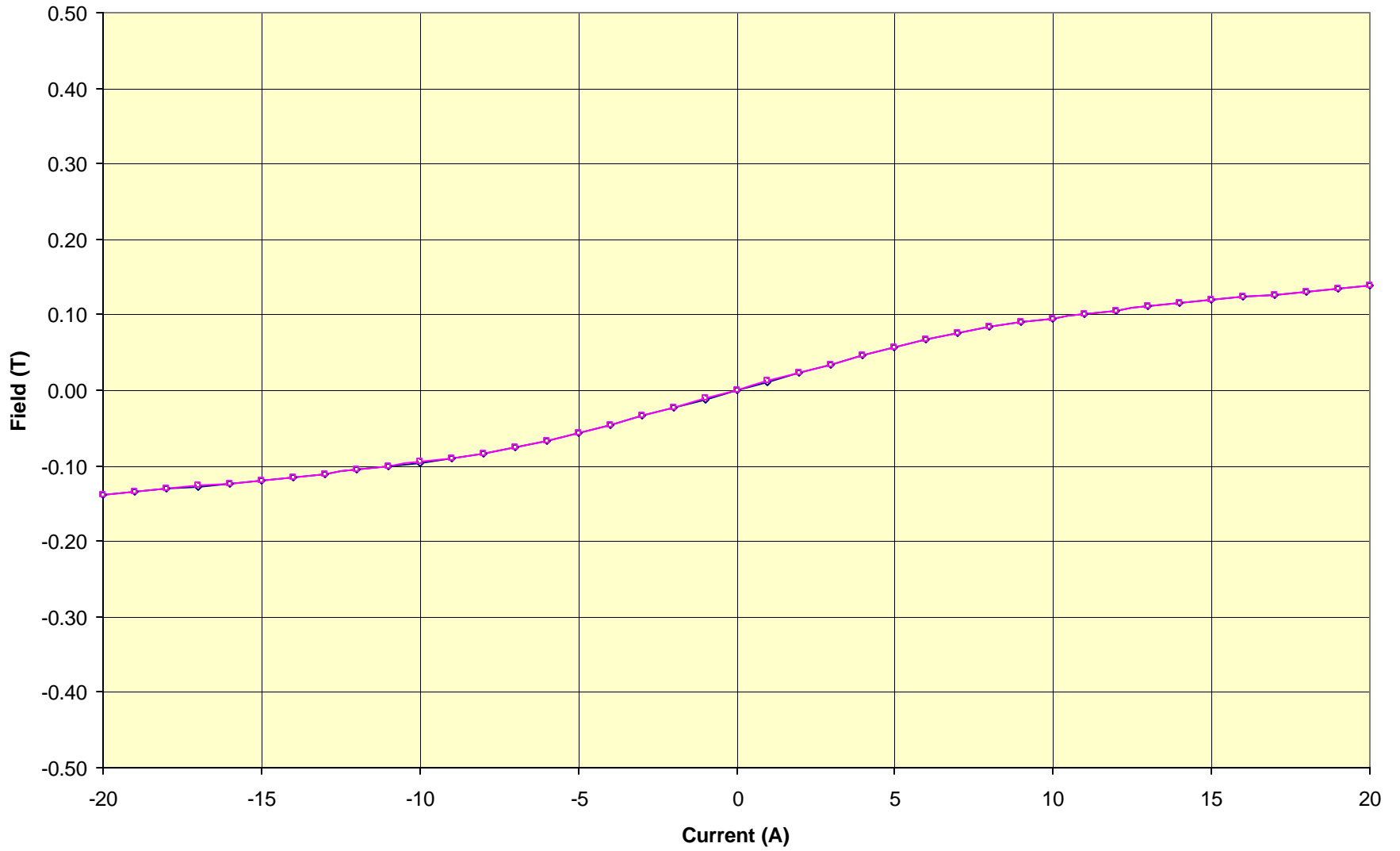
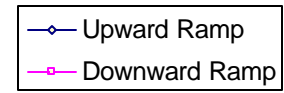
Upward Ramp
Downward Ramp



Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=9mm)



Projected Field Magnet SN:001
Bx vs. Current (X=Y=0mm, Z=10mm)



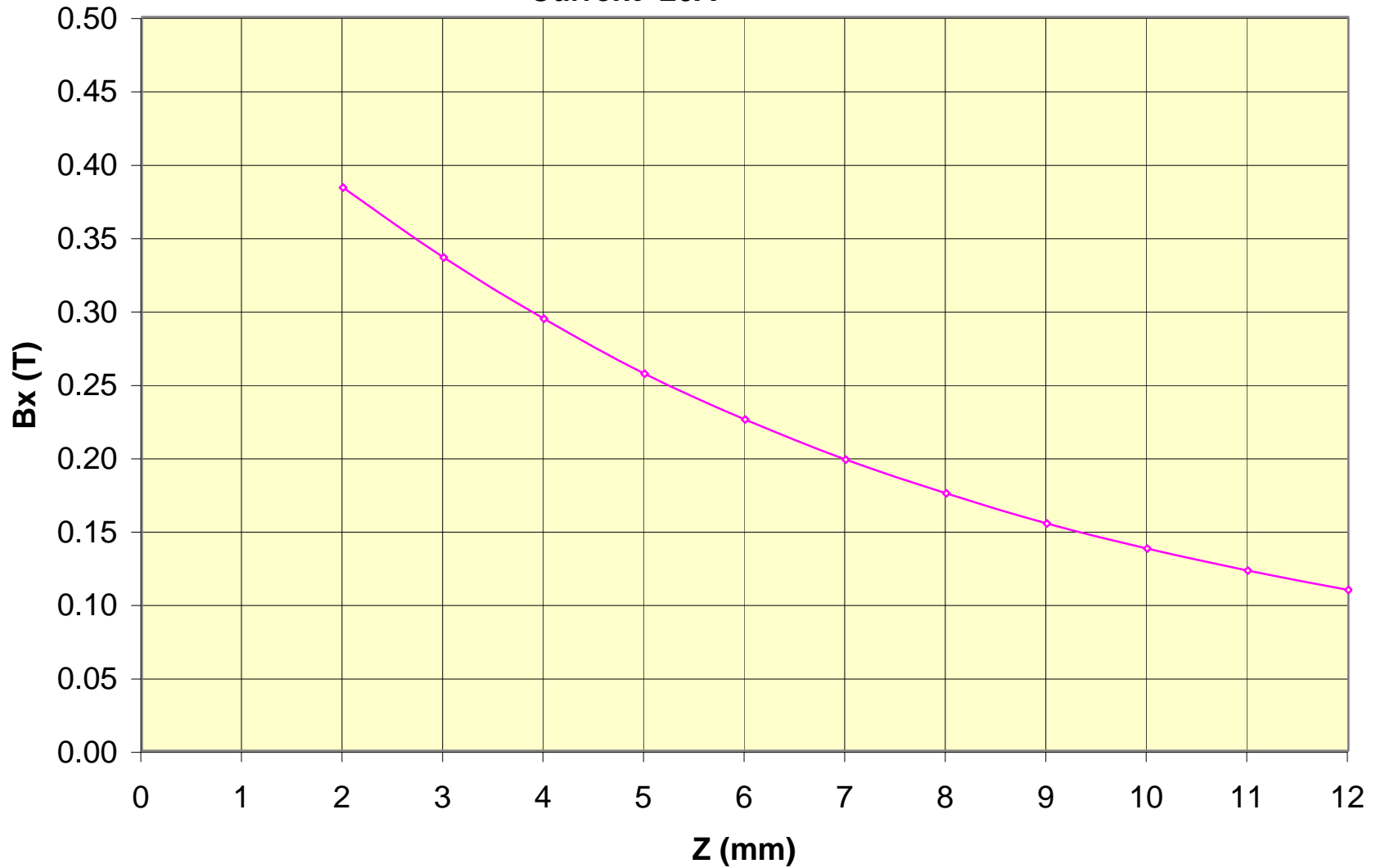
Section 7

TEST DATA

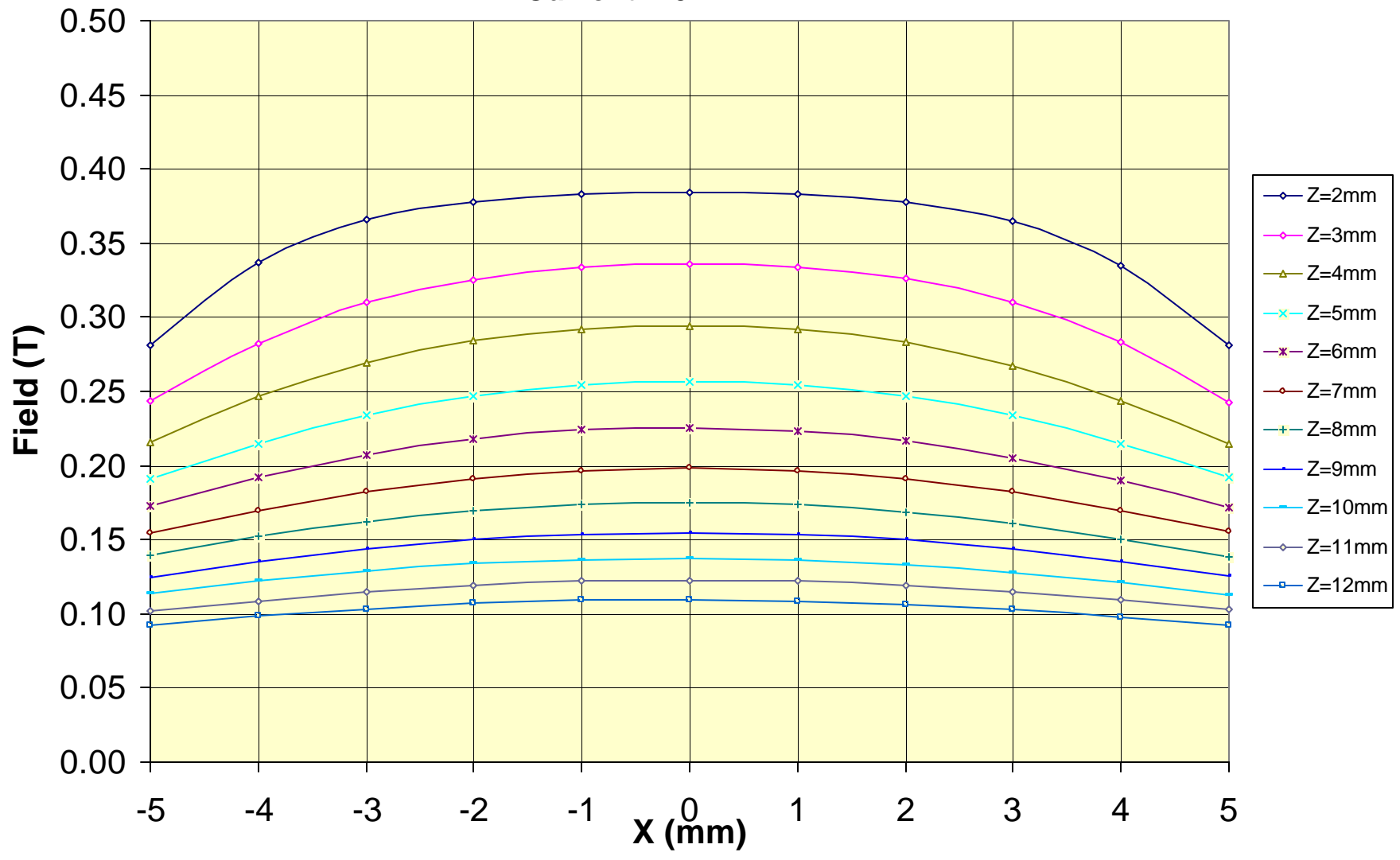
Projected Field Magnet SN:001

Bx vs. Z (X=Y=0mm)

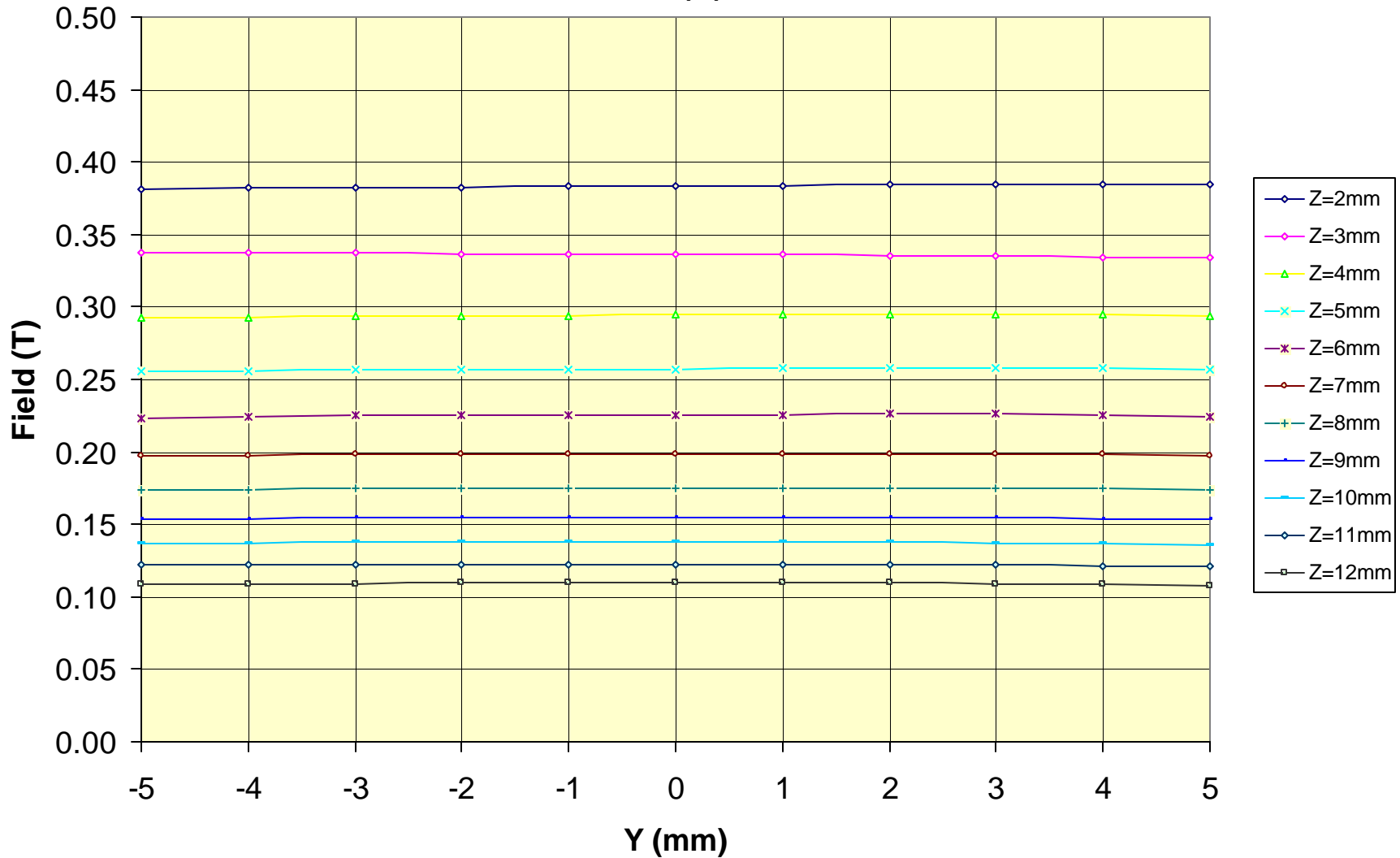
Current=20A



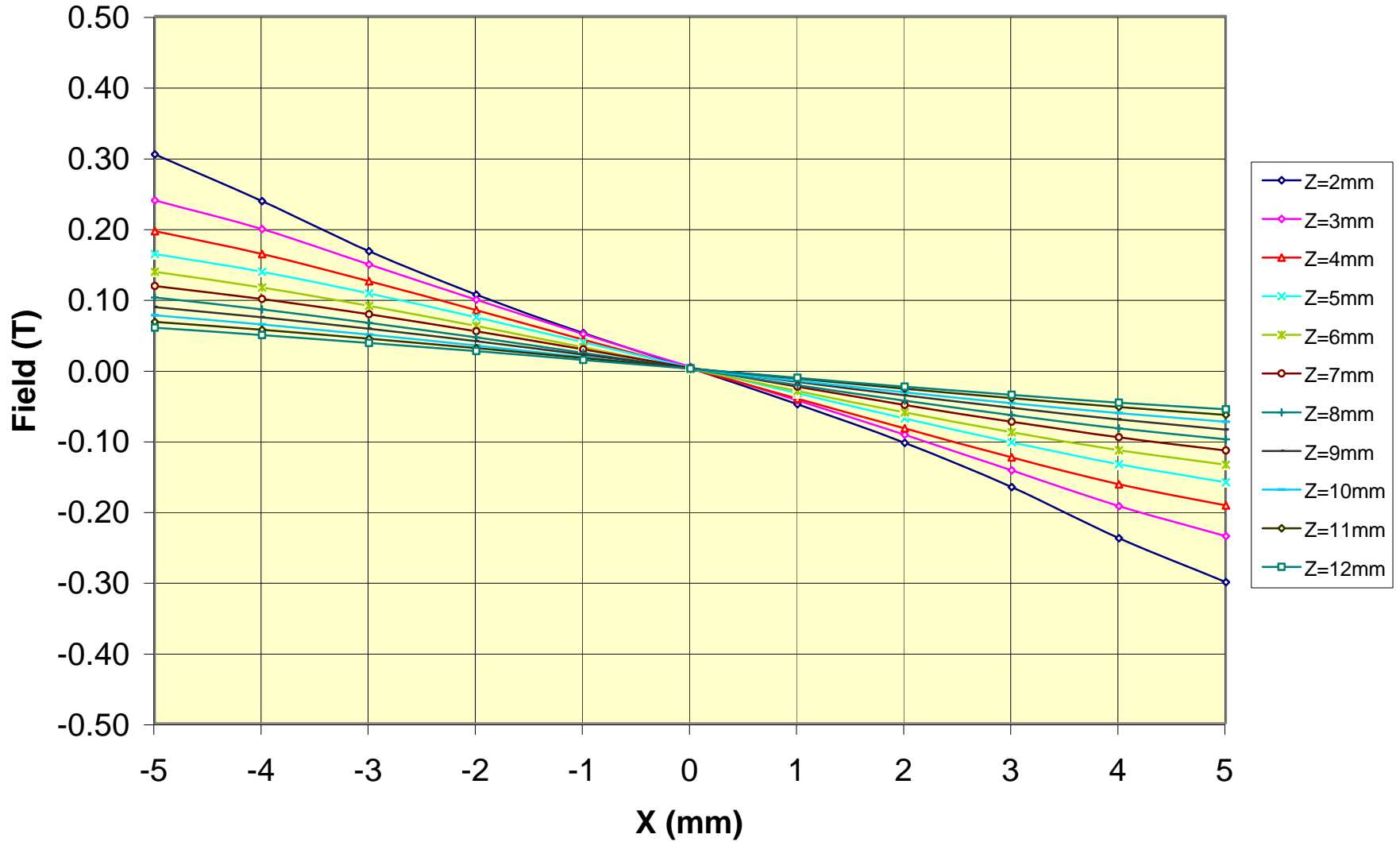
Projected Field Magnet SN:001
Bx vs. X (Y=0mm)
Current=20A



Projected Field Magnet SN:001
Bx vs. Y (X=0mm)
Current =20(A)



Projected Field Magnet SN:001
Bz vs. X (Y=0mm)
Current=20A



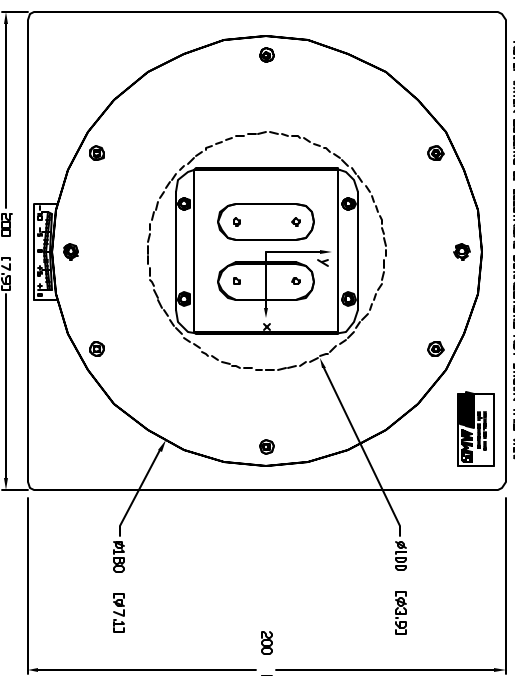
Section 8

DRAWINGS

PROBATIONARY
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NOTE: WATER COOLING & ELECTRICAL CONNECTIONS NOT SHOWN THIS VIEW

TOP VIEW



REV	DESCRIPTION	SHEET	DATE	APPROVED
A	REVISION	1	08/07/01	ES/MS/RS

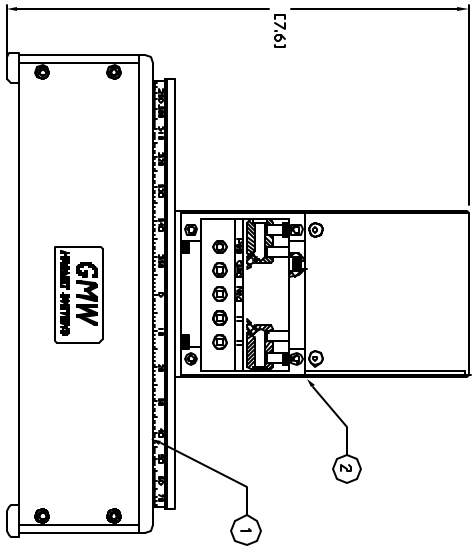
MOTOR SPECIFICATIONS

FIELD (for mech) 0.37 [4 mm above pole face]
 COIL RESISTANCE [20 °C] 0.80 ohm
 RESONANCE [Hz] 1.02 ohm
 MAX POWER 200/20A [400 W]
 COOLING 0.5 ltr/min 1.0 bar [14 psid]
 THERMAL INTERRUPTOR OPEN CIRCUIT ABOVE 75 °C [167 °F]
 MASS 4 kg

ACTORIZED ROTATING DRIVE SPECIFICATIONS

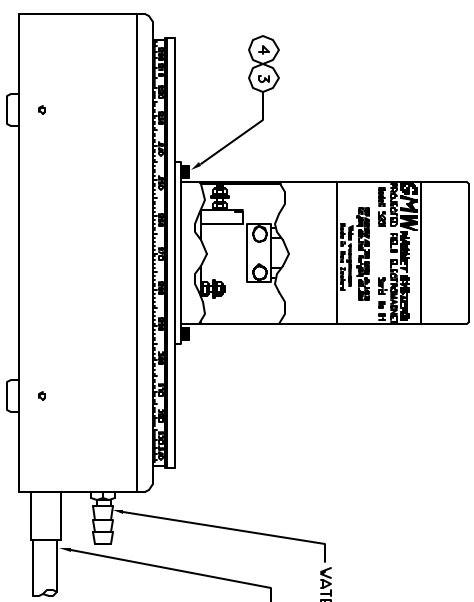
MAXIMUM ROTATION: ± 200 deg
 RESOLUTION: 0.2 deg
 MASS: 4 kg

FRONT VIEW



FRONT VIEW

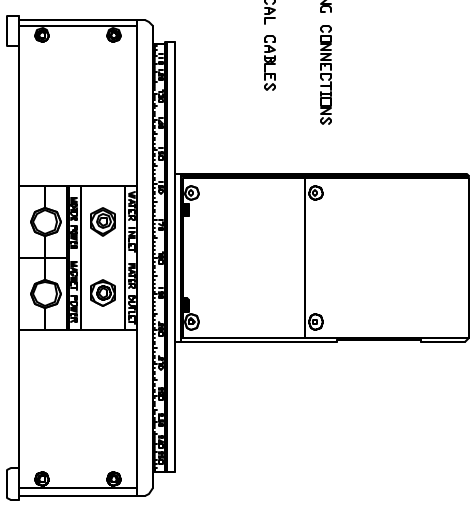
REAR VIEW



REAR VIEW

WATER COOLING CONNECTIONS
 ELECTRICAL CABLES

RIGHT VIEW

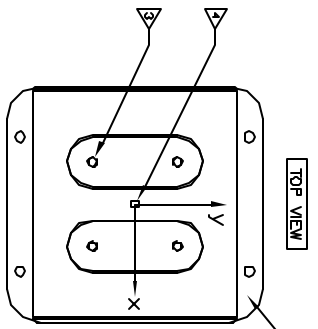


RIGHT VIEW

QTY	PART NUMBER	DESCRIPTION	UNIT
4	11901792	WASHER, LOCK, BOSCHARD	
4	11901812	SHCS, M5 x 10 S/S	
2	11901860	PROTECTED FIELD MAGNET ASSEMBLY	
1	11901850	MINI ROTATING BASE ASSEMBLY	

ITEM	QTY	PART NUMBER	DESCRIPTION	UNIT
1	1	DO NOT SCALE		
2	1	GMW	955 Industrial Rd, San Jose, CA 94705	
3	1	11901960	MAGNET/BASE ASSY	
4	1	MODEL: 5201		
5	1	11901960		
6	1	11901960		
7	1	11901960		
8	1	11901960		
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100	1	11901960		

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IN WITNESS WHEREOF, DATE: 04/10/03



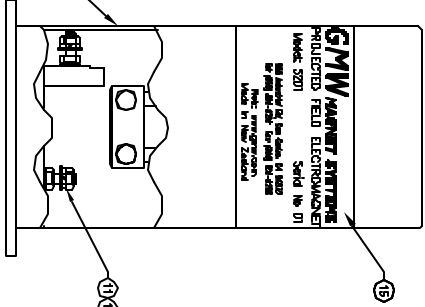
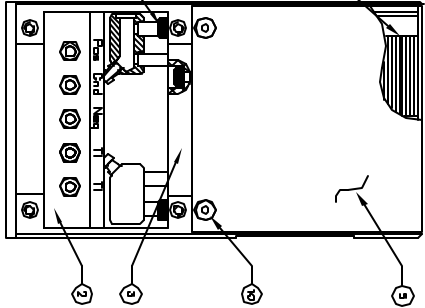
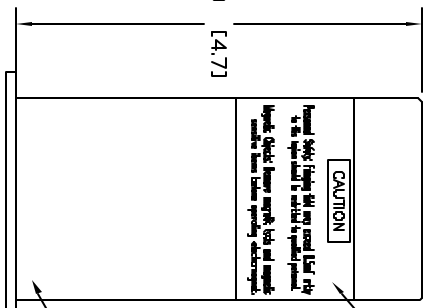
TOP VIEW



FRONT VIEW

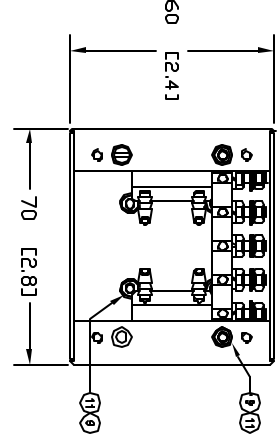
L.H. SIDE VIEW

R.H. SIDE VIEW



BOTTOM COVER (ITEM 6) NOT SHOWN THIS VIEW

MAGNET SCHEMATIC



MAGNET TERMINAL BLOCK

TRANSITION PLATE (ITEM 7) NOT SHOWN THIS VIEW

BOTTOM VIEW

- NOTE
1. SEE DWG NO 11902010 FOR MAGNET WIRING DETAILS.
 2. THIS DRAWING SHOWS MAGNET WITH ROTATING BRUSH MOUNTING. FOR DESKTOP MOUNTING MACHINE, SEE DWG NO: 11901940.
 3. FILL HOLES WITH BLACK COLOURED EPOXY RESIN (4 PLS)
 4. ROI [REGION OF INTEREST]
 5. TEMPERATURE SWITCHES SELECTS BZEL-075

MAGNET SPECIFICATIONS

FIELD (Bx max): 0.3T [4 mm above pole face]

COIL
RESISTANCE (20 °C) 0.85 ohm
RESISTANCE (hot) 1.02 ohm
MAX POWER 20V/20A [400 W]

COOLING:
THERMAL INTERLOCK: 0.5 lbar/min 1.0 bar [1.4 psid]
OPEN CIRCUIT ABOVE 75 °C [167 °F]

MASS: 4 kg

REV	DESCRIPTION	DRAWN	DATE	APPROVED
A	RELEASE		04/10/03	G.DOUGLAS

REVISIONS

ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
1B	1	10900870	LABEL, CAUTION	
1S	1	10900660	LABEL, SPECIFICATION	
14	1	DIN 844	SCREW, M3 X 10 CHEESE HD SLOTTED BRASS	
13	2	DIN 934	NUT, M3 BRASS	
12	1	DIN 433	WASHER, FLAT M3 X 6 X 0.5 BRASS	
11	12	BN 782	WASHER, RIBBED LOCK SPRING/STEEL	
10	8	DIN 7991	SHCS, M3 X 5 FLAT HD S/S	
9	6	DIN 912	SHCS, M3 X 6 S/S	
8	4	DIN 912	SHCS, M3 X 12 S/S	
7	1	17905190	TRANSITION PLATE	
6	2	17905130	COVER, BOTTOM	
5	1	17905120	COVER, TOP	
4	2	17905070	SHIELD POLE	
3	1	17905060	YOKE	
2	1	11901910	TERMINAL BLOCK ASSEMBLY	
1	2	11901870	POLE/COIL ASSEMBLY	

DATE	SCALE	SCALE	SCALE
08/15/02	1:1	1:1	1:1

DO NOT SCALE FROM DRAWING

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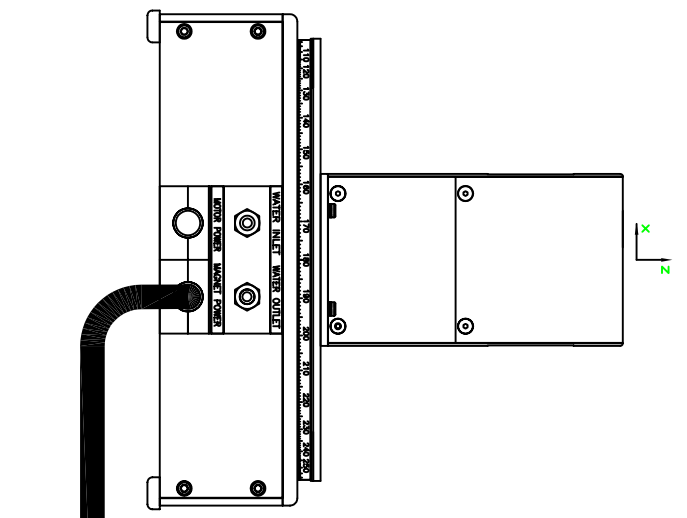
GMW
PROJ FIELD MAGNET
MODEL: 5201

SCALE 1:1 WT kg SHEET 1 OF 1

REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	04/10/03	G.DOUGLAS

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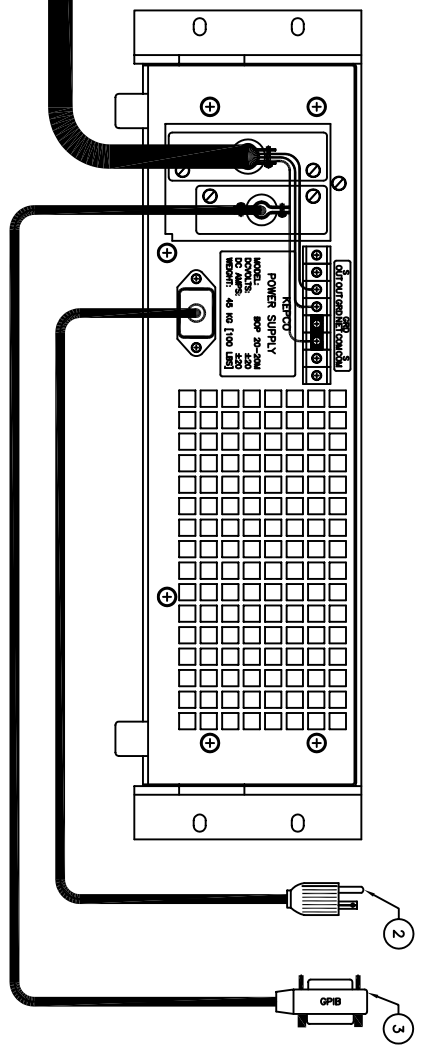
MODEL: 5201 MAGNET



MAGNET REAR VIEW

*** WARNING ***
 CHECK AC POWER VOLTAGE AND FREQUENCY MATCH POWER SUPPLY
 SPECIFIED REQUIREMENTS BEFORE APPLYING AC INPUT POWER

KEPCO MODEL: BOP 20-20M BIPOLAR POWER SUPPLY



POWER SUPPLY REAR VIEW

- NOTE
1. POWER SUPPLY SHOWN WITH 115V AC INPUT
 2. GPIB INTERFACE IS OPTIONAL EQUIPMENT
 3. REFER TO TABLE ON DWG 13900420 FOR AC INPUT RATINGS OTHER THAN 115V AC INPUT

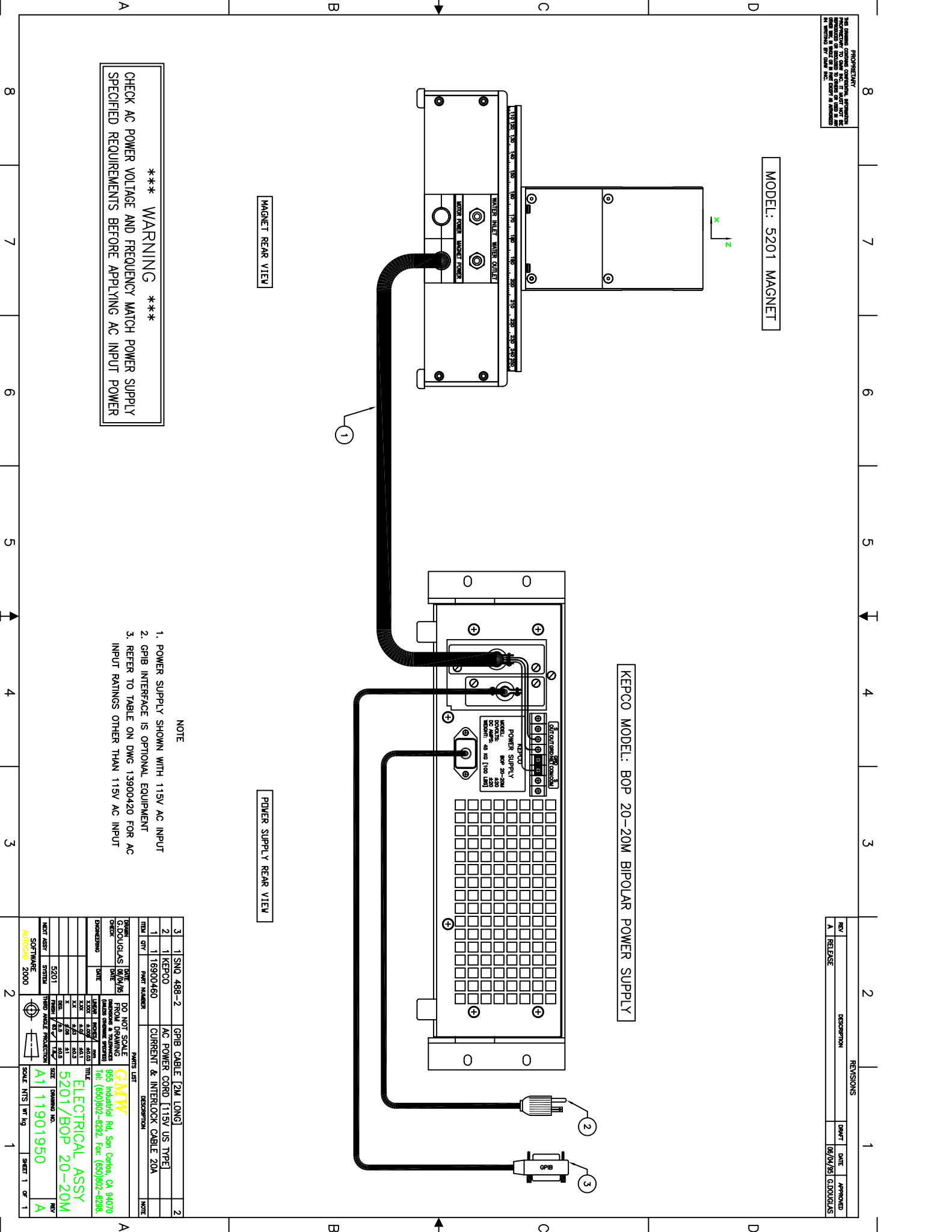
REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	09/09/95	G000UGUS

ITEM	QTY	PART NUMBER	DESCRIPTION
3	1	SN0 488-2	GPIB CABLE [2M LONG]
2	1	KEPCO	AC POWER CORD [115V US TYPE]
1	1	16900460	CURRENT & INTERLOCK CABLE 20A

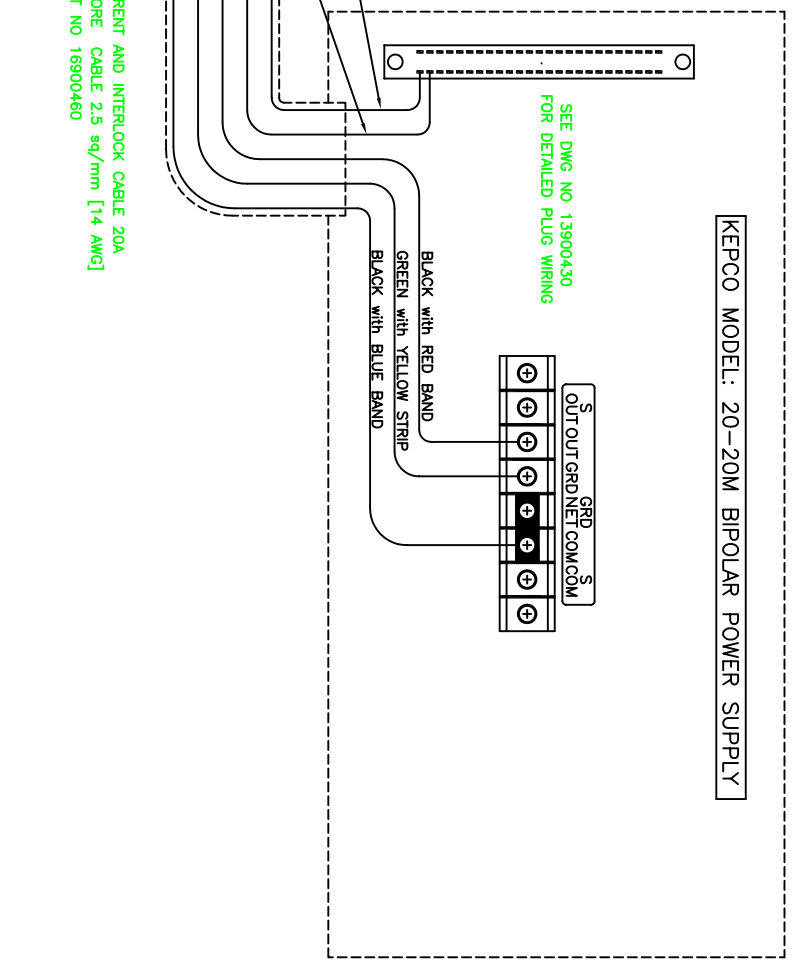
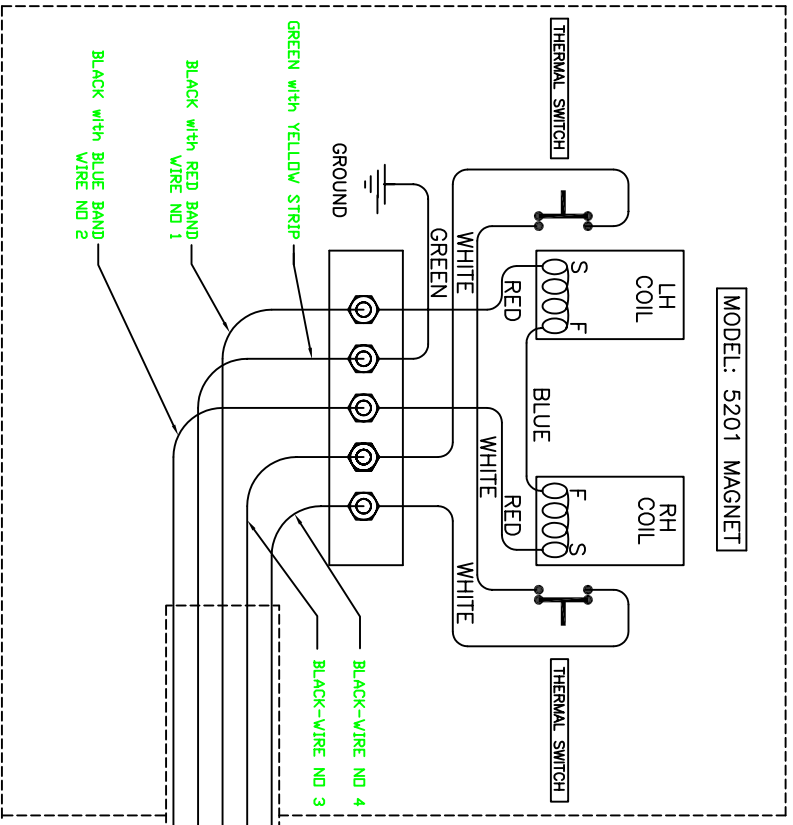
DATE	BY	DESCRIPTION
09/09/95	G000UGUS	RELEASE

REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	09/09/95	G000UGUS

REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	09/09/95	G000UGUS



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AC INPUT POWER	1 PHASE, 50 to 60HZ	115V	208V	230V
AC INPUT FULL LOAD CURRENT	11.0	6.5	6.0	
RECOMMENDED MAIN AC BREAKER	15	10	10	
RECOMMENDED AC POWER OUTLET	5-15R	-	-	
RECOMMENDED AC CABLE SIZE	1.5 SQ./MM	1.0 SQ./MM	1.0 SQ./MM	

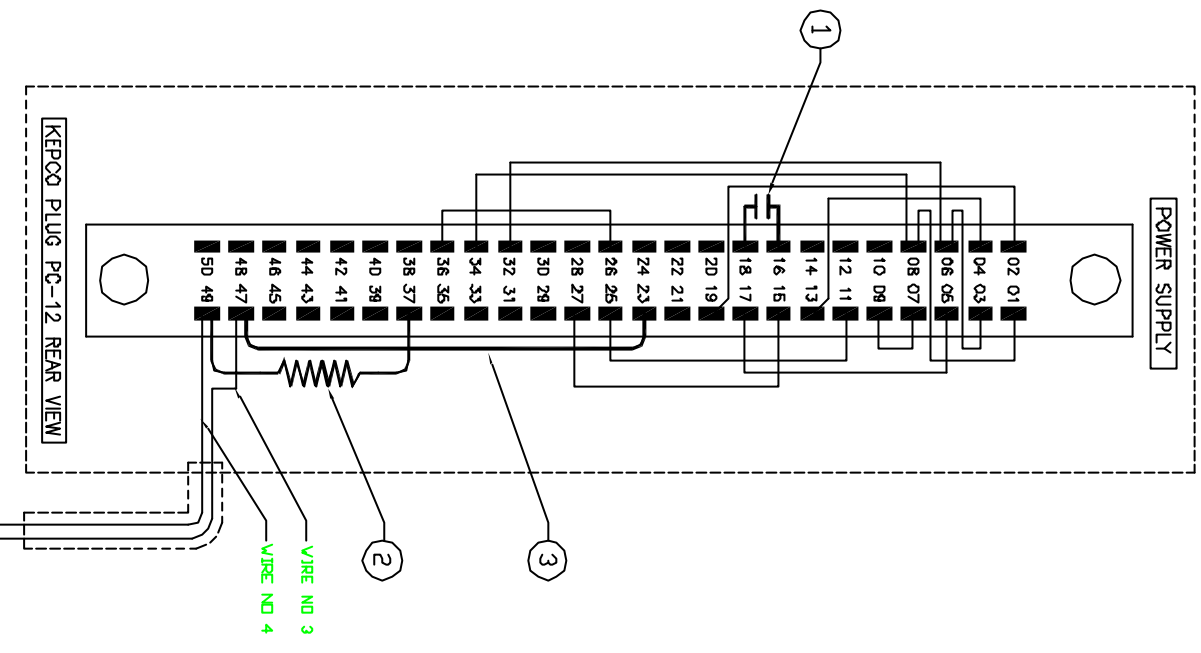
NOTE: DRAWING SHOWS POWER SUPPLY SETUP FOR 1 PHASE 115V AC POWER

REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	04/10/01	G0008US

ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE																				
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995 Industrial Rd, San Carlos, CA 94070
 Tel: (650)802-8292, Fax: (650)802-8298
GUNTER ELECTRIC WIRING
5201/BOP 20-20M
A113900420
 SCALE NTS | WT kg | SHEET 1 OF 1

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REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	04/19/03	CDOLJLAS

REV	DESCRIPTION	DATE	APPROVED
3	1		
2	1		
1	1		

REVISIONS

REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	04/19/03	CDOLJLAS

DESCRIPTION

WIRE LINK, HOOK UP WIRE 0.5 SQ/MM
RESISTOR, 880 OHM/0.25 W
CAPACITOR, MYLAR 0.33UF

DATE

02/01/03

SCALE

1:1

PROJECT

32901

SOFTWARE

AVIAD 2100

DESIGNER

AVIAD 2100

DATE

02/01/03

SCALE

1:1

PROJECT

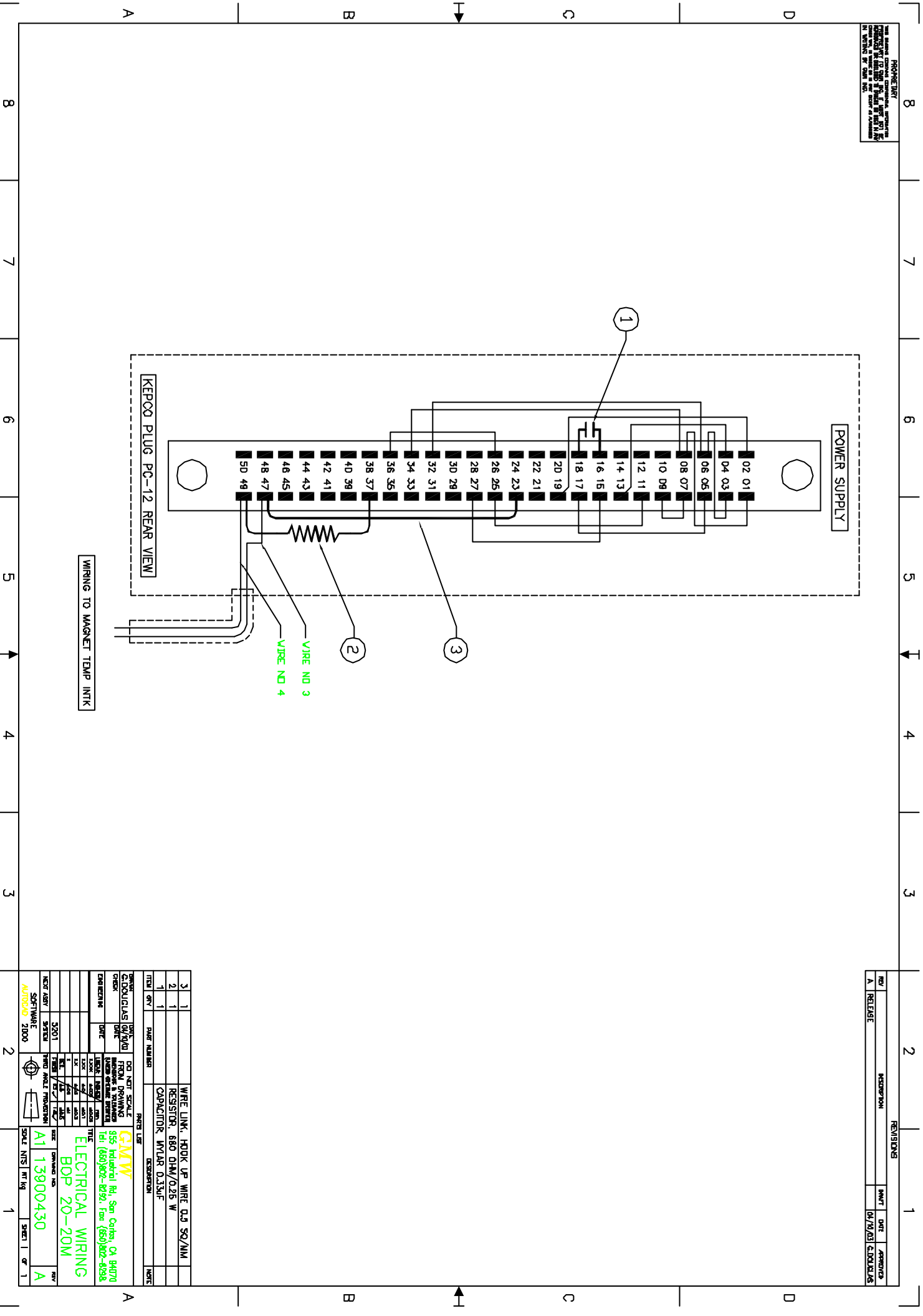
32901

SOFTWARE

AVIAD 2100

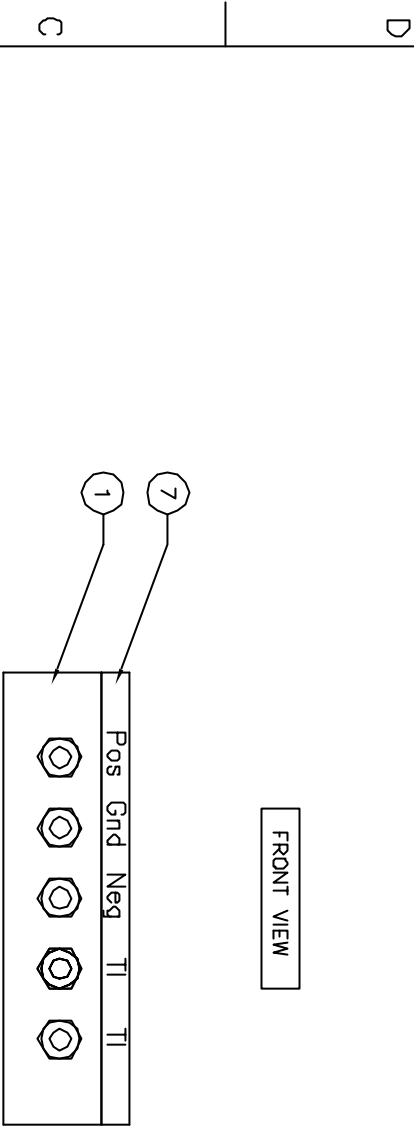
DESIGNER

AVIAD 2100

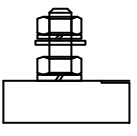


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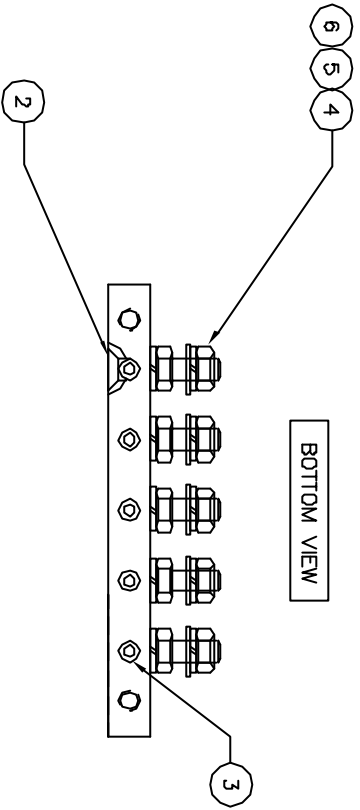
REVISIONS			
REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	10/24/02	G.DOUGLAS



FRONT VIEW



SIDE VIEW



BOTTOM VIEW

NOTE:

1. ASSEMBLE SCREW, NUT, AND LOCKWASHER FIRST [ITEMS 2,4,6]
2. LOCK SCREW [ITEM 2] TO STOP ROTATION WITH SETSCREW [ITEM 3]

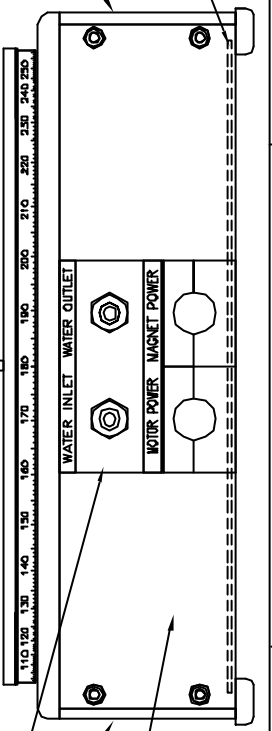
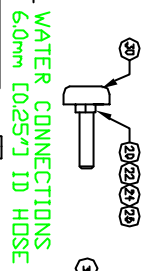
ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
1	1	10900083D	LABEL, TERMINAL BLOCK	
2	5	BN 1401	NUT, M3 HEX JAM BRASS	
3	5	BN 560	WASHER, FLAT M3 x 7 x 0.5 BRASS	
4	10	DIN 7980	WASHER, M3 LOCK S/S	
5	5	DIN 914	SETSCREW, M3 x 5 CONE POINT S/S	
6	5	DIN 963 A	SCREW, M3 x 16 FLAT HD BRASS	
7	1	1790511D	TERMINAL BLOCK	

THROWN G.DOUGLAS	DATE 09/05/02	DO NOT SCALE FROM DRAWING (DIMENSIONS & TOLERANCES UNLESS OTHERWISE SPECIFIED)	DATE 09/05/02	SCALE 2:1	WT Kg	SHEET 1	OF 1
ENGINEERING	DATE	LINEAR DIMEN/ ANGLES/ DIA	DATE	TITLE PROJ FIELD MAGNET TERMINAL BLOCK GA			
11901860	5201	X.XX ±.001		DRAWING NO. A2 11901910			
NEXT ASSY SYSTEM	THIRD ANGLE PROJECTION	X.X ±.05		REV A			
SOFTWARE AUTOCAD 2000		X ±.1					
		Ø ±.05					
		Ø ±.1					
		Ø ±.15					
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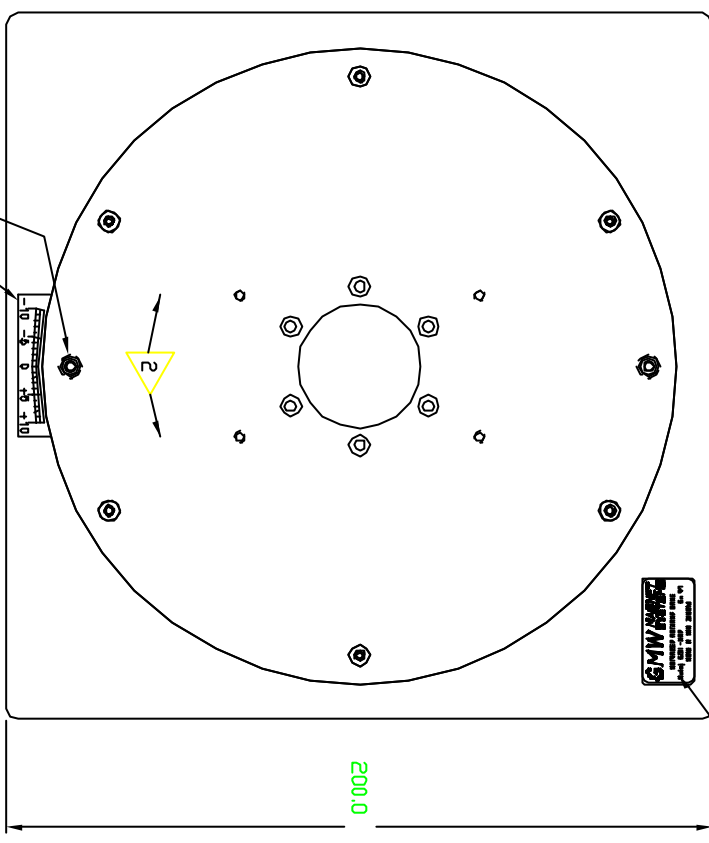
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FOOT DETAIL

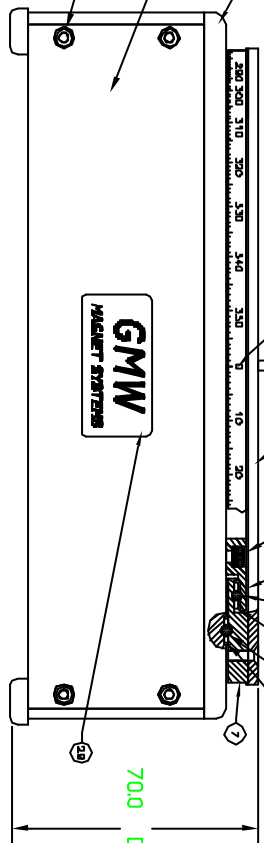


ELECTRICAL & WATER CONNECTIONS NOT SHOWN THIS VIEW



TO ADJUST HEIGHT
SCREW FOOT IN/OUT
AND LOCK IN PLACE
WITH ITEM 19

SEE DRAWING
NO. 11902060 FOR
ROTATING DRIVE WITH
MOTORIZED ROTATING
DRIVE UNIT FITTED.



REV	RELEASE	DESCRIPTION	DRAWN	DATE	APPROVED
A				12/03/02	G.DOUGLAS

- REVISIONS
- ITEM 16 REMOVED, WHEN MOTOR DRIVE UNIT FITTED
 - DO NOT ROTATE PLATTER BY HAND, WHEN MOTOR DRIVE IS FITTED

REV	QTY	PART NUMBER	DESCRIPTION	NOTE
1	1	11902080	SERVICE PANEL ASSEMBLY	
2	1	17905260	TOP PLATE	
3	1	17905260	SIDE PLATE [RH Side]	
4	1	17905270	SIDE PLATE [LH Side]	
5	1	17905280	FRONT COVER	
6	2	17905290	REAR COVER	
7	1	17905330	THRUST BEARING	
8	1	17905340	BEARING RETAINER	
9	1	17905350	BEARING SPACER [Upper]	
10	1	17905360	BEARING SPACER [Lower]	
11	1	17905370	MOUNTING PLATE	
12	1	17905390	CLAMP PAD	
13	1	17905400	BOTTOM COVER	
14	32	3.00 DIA. NYLON	BALL/BEARING, [Plastic/Metal Components Co]	
15	10	DN 912	SHCS, M3 x B S/S	
16	2	DN 912	SHCS, M3 x 12 S/S	
17	8	DN 912	SHCS, M3 x 40 S/S	
18	14	DN 7991	SHCS, M3 x 6 FLUSH HD S/S	
19	4	DN 913 A2	SHSS, M3 x 3 S/S	
20	4	DN 7985A	SCREW, M4 x 20 PAN HD	
21	10	BN 792	WASHER, M3 LOCK, BOSSARD	
22	4	BN 792	WASHER, M4 LOCK, BOSSARD	
23	4	DN 433	WASHER, M3 FLAT S/S	
24	4	DN 433	WASHER, M4 FLAT	
25	4	DN 934	NUT, M4 HEX S/S	
26	1	10901000	LABEL, IDENTIFICATION	
27	1	10901010	LABEL, INDEX	
28	1	10901020	LABEL, VERNIER	
29	1	10901050	LABEL, GDMW MAGNET SYSTEMS	
30	4	H-1736	FEET, RUBBER Ø1.4 x 6.5H DSE	
31	2	DN 1481	ROLL PIN 3.0 x 10.0	

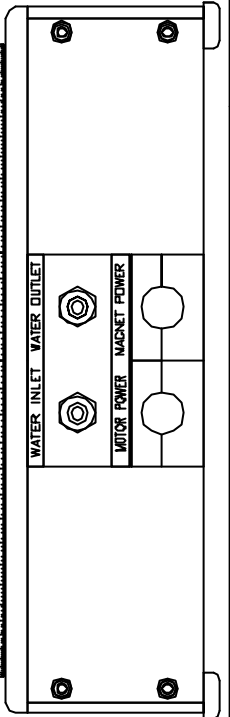
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 Tel: (650)802-8292, Fax: (650)802-8298

ROTATING DRIVE GENERAL ASSEMBLY
 DRAWING NO. **A2 11902050**

SCALE 1:1 WT kg SHEET 1 OF 1

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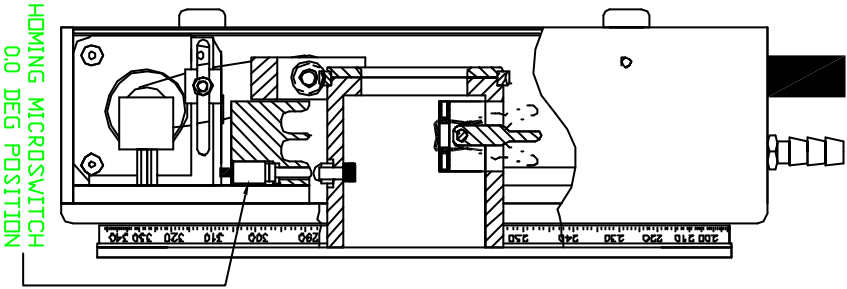
L.H. SIDE VIEW



REAR VIEW



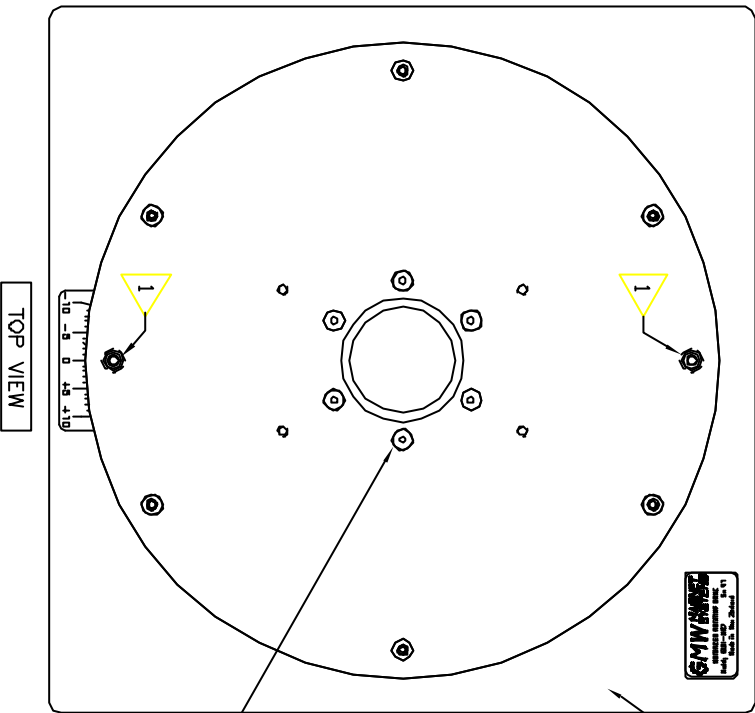
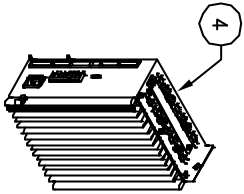
ELECTRICAL & WATER CONNECTIONS NOT SHOWN THIS VIEW



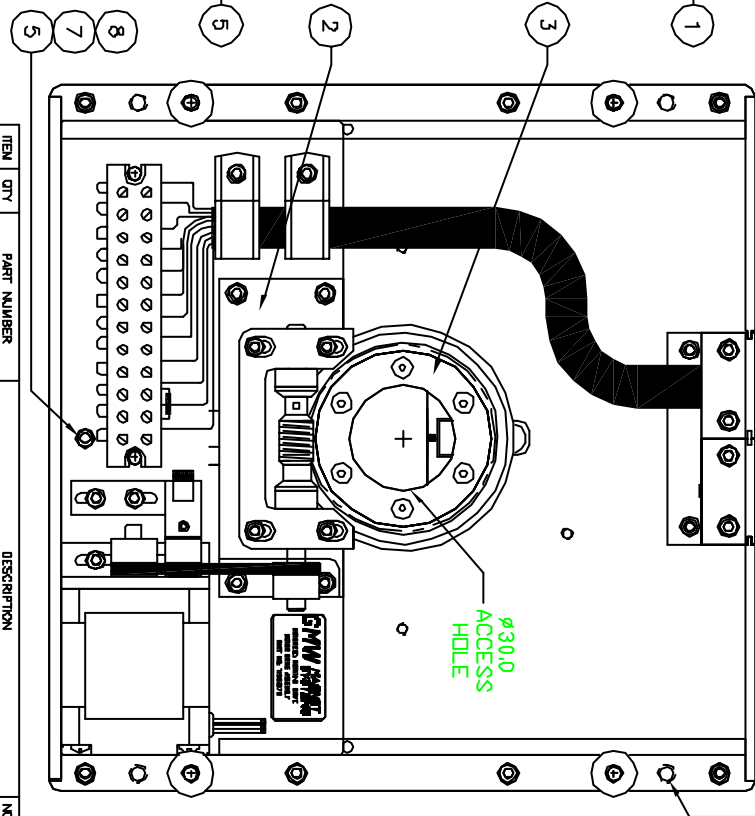
HOMING MICROSWITCH
00 DEG POSITION

FOR DETAILS ON
ROTATING DRIVE ASSEM
SEE DWG NO:11902050

1 REMOVE ROTATION
LOCK SCREWS BEFORE
OPERATING WITH
STEPPER MOTOR



TOP VIEW



UNDERNEATH VIEW

[SHOWN WITH BOTTOM COVER REMOVED]

MS MTG HOLES
[4 PLST]

Ø30.0
ACCESS
HOLE

REVISIONS		DESCRIPTION	DRAWN	DATE	APPROVED
REV	A	RELEASE		11/22/02	G.DOUGLAS

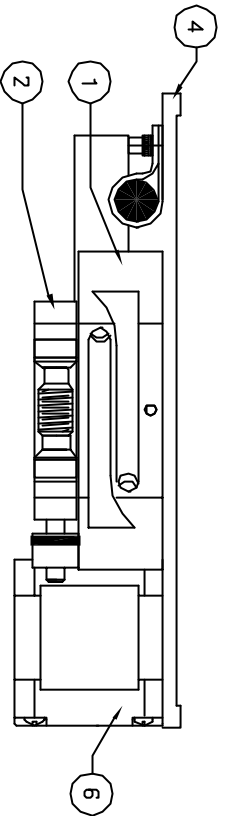
8	1	DIN 433	WASHER, M3 FLAT S/S
7	1	BN 792	WASHER, M3 LOCK, BOSSARD
6	1	DIN 912	SHCS, M3 x 8 S/S
5	6	DIN 7991	SHCS, M3 x 6 FLAT HD S/S
4	1	Z6104	CONTROLLER, STEPPER MOTOR, COMPUMOTOR
3	1	11902090	SPDOL ASSEMBLY
2	1	11902070	MOTOR DRIVE ASSEMBLY
1	1	11902050	ROTATING DRIVE ASSEMBLY

ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
PARTS LIST				
DRWVN		DATE	DO NOT SCALE	
G.DOUGLAS		11/21/02	FROM DRAWING	
CHECK		DATE	DIMENSIONS & TOLERANCES	
ENGINEERING		DATE	(UNLESS OTHERWISE SPECIFIED)	
			LINEAR UNDES/ DIM	
			X.XX ±.007	
			X.X ±.005	
			X ±.003	
			ØS ±.005	
			ØS ±.003	
			FRS ±.007	
			FRS ±.005	
			THIRD ANGLE PROJECTION	
SOFTWARE			SIZE	DRAWING NO.
AUTOCAD Z000			A2	11902060
			SCALE 1:1	WT Kg
			SHEET 1	OF 1

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ROTATING DRIVE
GENERAL ASSEMBLY

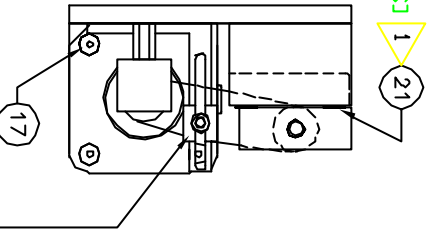
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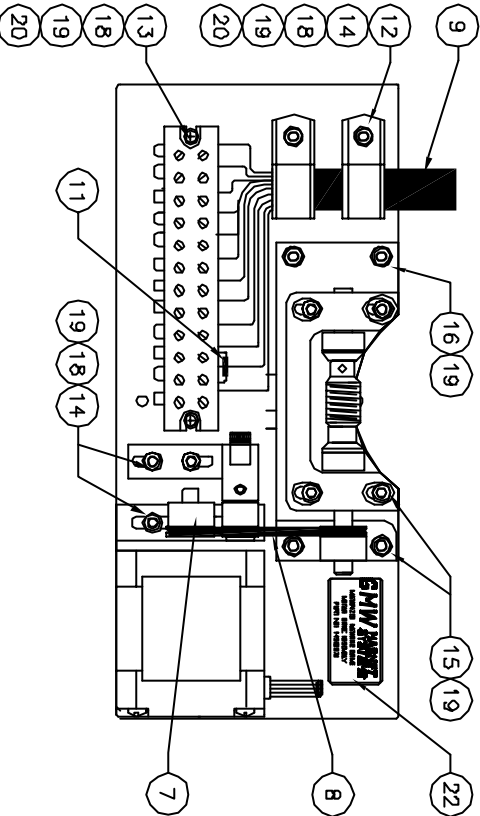
FRONT VIEW

NOTE 1 NOMINAL 5 SHIMS AT EACH POSITION ADD/REMOVE TO ADJUST WORM C/L HEIGHT TO MATCH SPOOL GEAR C/L.

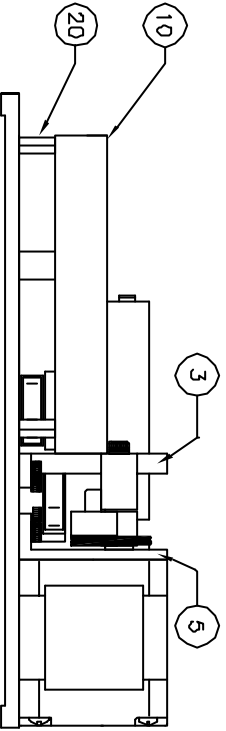
SIDE VIEW



SLIDE BLOCK UP/DN TO TENSION BELT AND LOCK IN PLACE WITH CAP SCREW



TOP VIEW



REAR VIEW

SEE DWG NO 13900350 FOR ELECTRICAL WIRING DETAILS

REVISIONS			
REV	DESCRIPTION	DRAWN	DATE
A	RELEASE		

REV	QTY	PART NUMBER	DESCRIPTION	NOTE
22	1	10901060	LABEL, IDENTIFICATION	
21	20	DIN 988	SHIM RING 3.0 x 6.0 x 0.1 STEEL	
20	2	Z22-480	SPACER, HEX BRASS 10mm LONG R-S	
19	16	DIN 6797	WASHER, INT LOCK M3 X 0.4 S/S	
18	8	DIN 433	WASHER, FLAT M3 X 0.3 S/S	
17	4	DIN 7991	SHCS, M3 x 5 FLAT HD S/S	
16	2	DIN 912	SHCS, M3 x 20 S/S	
15	6	DIN 912	SHCS, M3 x 12 S/S	
14	6	DIN 912	SHCS, M3 x 6 S/S	
13	2	DIN 7985A	SCREW PAN HD, M3 x 25 S/S	
12	2	ECC8	P CLIPS 10mm	
11	1	0.33uF	CAPACITOR	
10	1	2412.6	TERMINAL BLOCK, 12 WAY WEIDMULLER	
9	3M	87/8	CABLE, 6 SHIELDED PAIRS, 22 AWG, BELDEN	
8	1	BTP-104-20	BELT, TIMING, BERG 132mm [5.2"]	
7	1	12900230	PULLEY, TIMING BELT 20 TEETH	
6	1	VS13B-SFR10	MOTOR, STEPPER, COMPUMOTOR	
5	1	17905480	MOTOR MOUNT	
4	1	17906450	BASE PLATE	
3	1	11902100	BELT TENSIONER ASSEMBLY	
2	1	11902120	WORM MOUNT ASSEMBLY	
1	1	11902110	STOP BLOCK ASSEMBLY	

REV	DATE	DESCRIPTION	SCALE	WT Kg	SHEET	OF
1	11/21/02	DO NOT SCALE FROM DRAWING DIMENSIONS & TOLERANCES (UNLESS OTHERWISE SPECIFIED)	1:1		1	1
DRAWN G. DOUGLAS		DATE 11/21/02				
CHECK		DATE				
ENGINEERING		DATE				
SOFTWARE AUTOCAD 2000		DATE				
NEXT ASSY SYSTEM		DATE				
119020501 5201		DATE				
THIRD ANGLE PROJECTION		DATE				
SCALE 1:1		WT Kg				
SHEET 1		OF 1				

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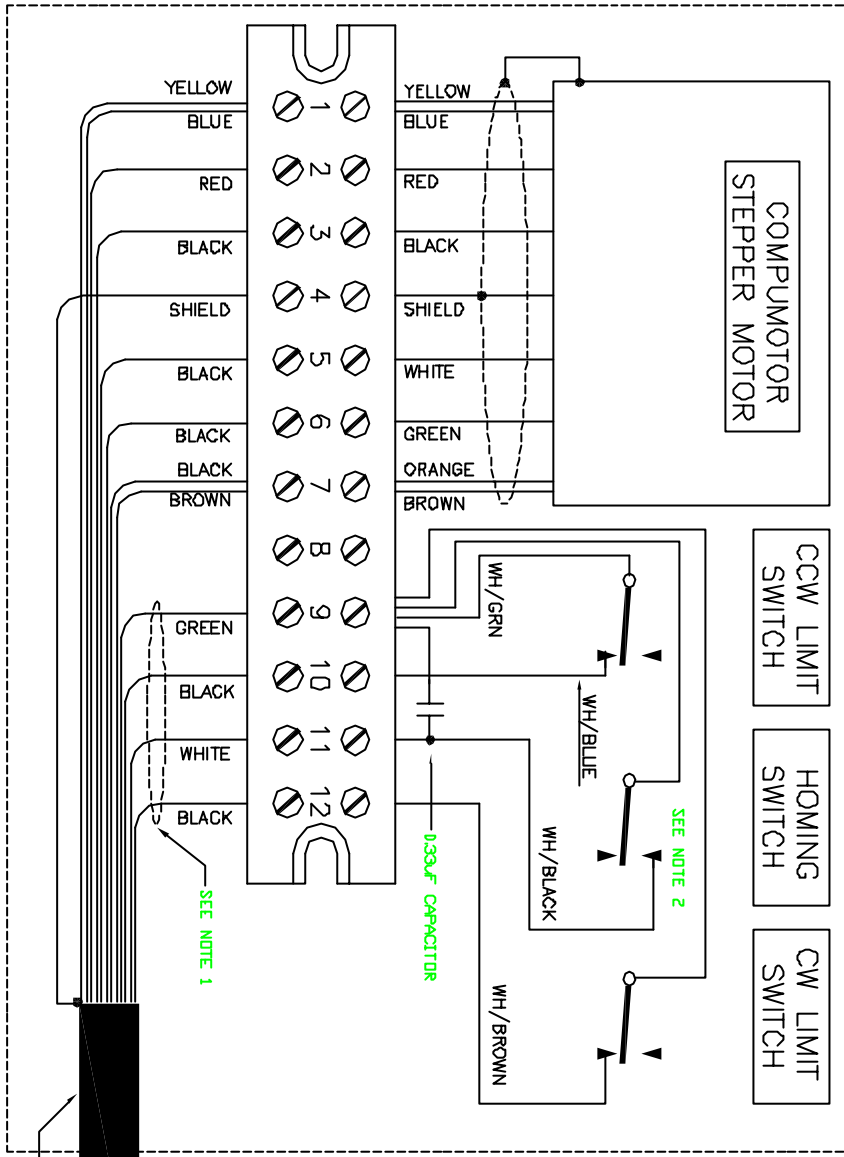
ROTATING DRIVE MOTOR DRIVE ASSEM

Part Number: **A2 11902070**

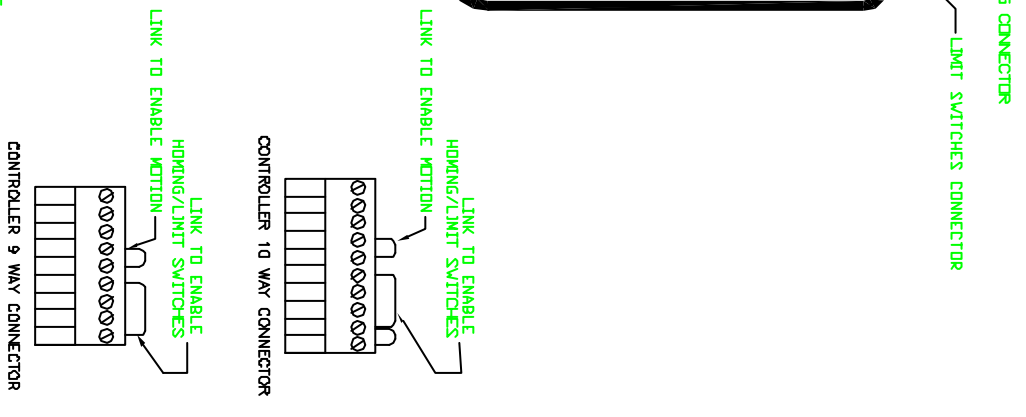
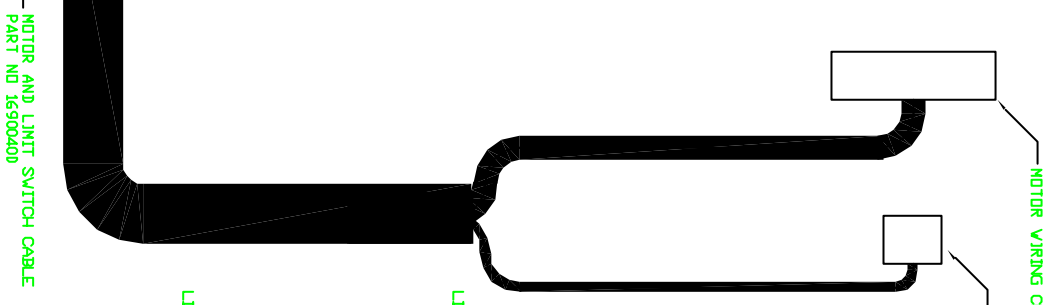
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MOTOR DRIVE ASSEMBLY

MODEL 3474 MRD: SEE DWG NO: 11900810
 MODEL 3473 MRD: SEE DWG NO: 11900800
 MODEL 5201 MRD: SEE DWG NO: 11902070



NOTE:
 1. USE BLACK WIRES FROM GREEN AND WHITE PAIRS. DO NOT MIX WITH BLACK WIRES USED FOR STEPPER MOTOR.
 2. HOMING SWITCH USES NORMALLY OPEN CONTACT. LIMIT SWITCHES USE NORMALLY CLOSED CONTACTS.



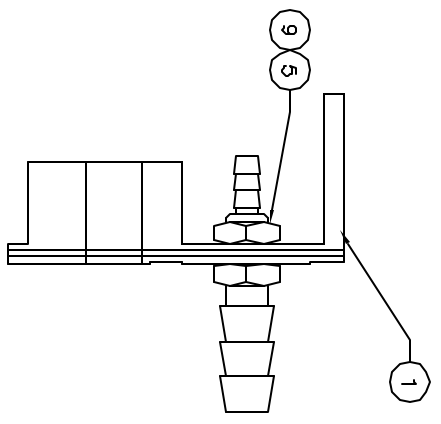
REV.	DESCRIPTION	DATE	APPROVED
A	RELEASE	02/13/01	CSJ003LAB
B	ADD CONTROLLER CONNECTOR LINKING	10/22/01	B20100LAB

REV. A	REV. B	REV. C	REV. D	REV. E	REV. F	REV. G	REV. H	REV. I	REV. J	REV. K	REV. L	REV. M	REV. N	REV. O	REV. P	REV. Q	REV. R	REV. S	REV. T	REV. U	REV. V	REV. W	REV. X	REV. Y	REV. Z
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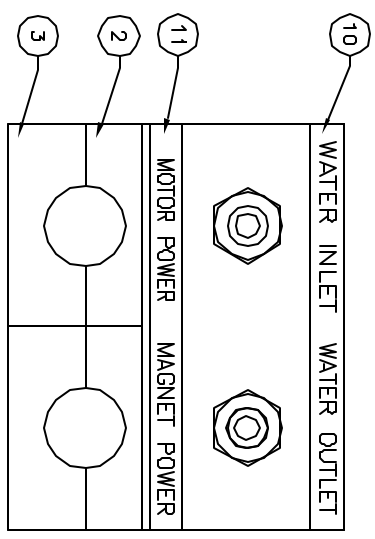
DO NOT SCALE FROM DRAWING
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 925 Industrial Rd San Carlos, CA 94070
 TEL: (650)802-8292 FAX: (650)802-8298

MOTORIZED, ROT DRIVE ELECTRICAL WIRING
 DRAWING NO. A113900350
 SCALE 2:1 1/8" = 1"

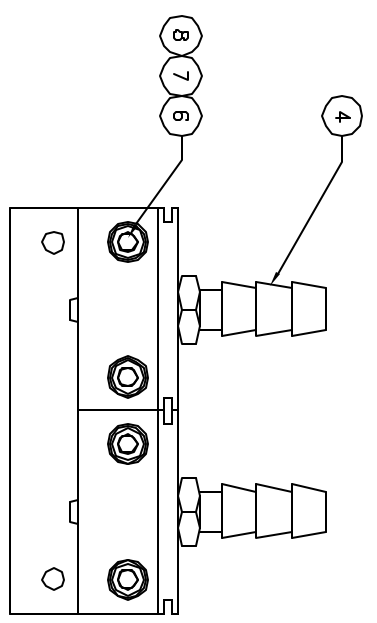
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END VIEW



FRONT VIEW



BOTTOM VIEW

REVISIONS				
REV	DESCRIPTION	DATE	APPROVED	
A	RELEASE	11/08/02	G.DOUGLAS	
B	CORRECT HEIGHT OF ITEM 3	01/29/03	G.DOUGLAS	

ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
11	1	10901040	LABEL, POWER ENTRY	
10	1	10901030	LABEL WATER ENTRY	
9	2	BN 792	WASHER, M6 LOCK SP/S	
8	4	DIN 433	WASHER, M3 FLAT S/S	
7	4	BN 792	WASHER, M3 LOCK SP/S	
6	4	DIN 912	SHCS, M3 x 25 S/S	
5	2	DIN 439 B	NUT, M6 JAM BRASS	
4	2	17905380	HOSE FEEDTHRU	
3	2	17905320	CABLE CLAMP [Lower]	
2	2	17905310	CABLE CLAMP [Top]	
1	1	17905300	SERVICE BRACKET	

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ROTATING DRIVE SERVICE PANEL ASSY

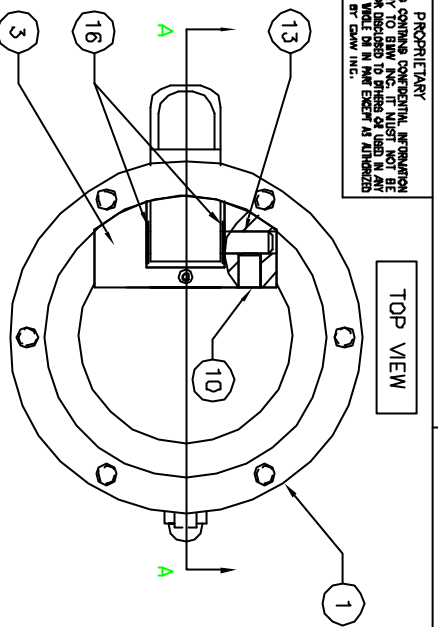
DATE: 11/08/02
 CHECKED: G.DOUGLAS
 ENGINEERING: DATE: 01/29/03

DD NOT SCALE FROM DRAWING DIMENSIONS & TOLERANCES UNLESS OTHERWISE SPECIFIED

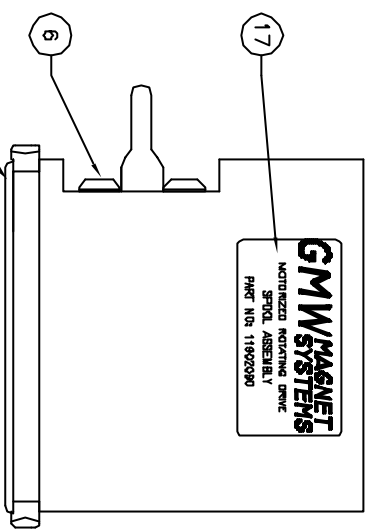
11802050C
 NEXT ASSY: SYSTEM
 SOFTWARE: AUTOCAD 2000

SCALE: 2:1 WT: kg SHEET: 1 OF: 1

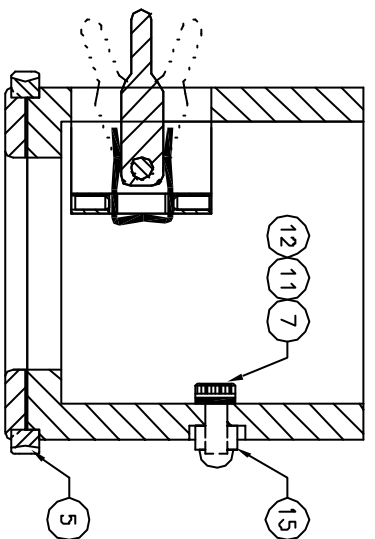
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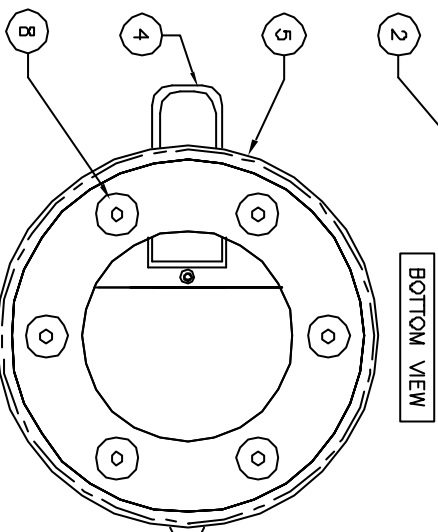
TOP VIEW



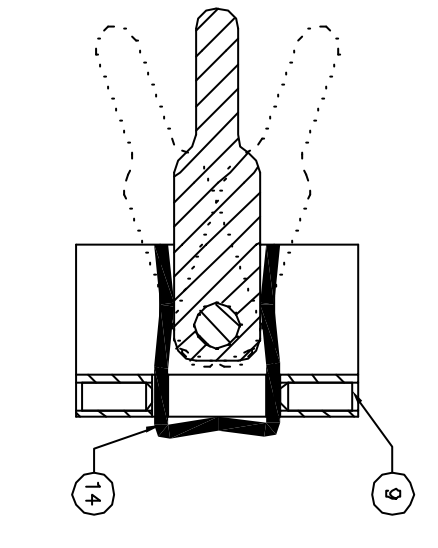
SIDE VIEW



SECTION A-A



BOTTOM VIEW



REVISIONS			
REV	DESCRIPTION	DRAWN	DATE
A	RELEASE		12/04/02

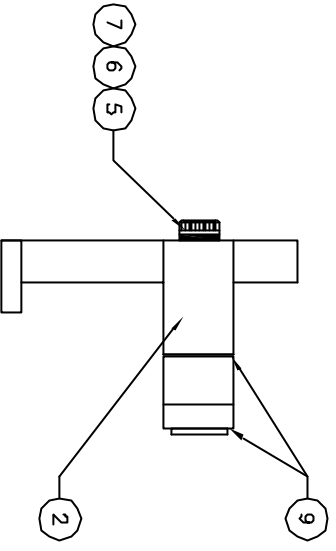
ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
17	1	11090105G	LABEL, IDENTIFICATION	
16	4	DIN 988	SHIM RING 3.0 x 6.0 x 0.1 STEEL	
15	1	DIN 1587	NUT, M3 HEX DOME [ACORN] BRASS	
14 A/R			PLANO WIRE $\phi 1.00$ S/S	
13	1	VSM 12771B	DOWEL PIN $\phi 3.00$ x 24 S/S	
12	1	DIN 433	WASHER, M3 FLAT S/S	
11	1	BN 792	WASHER, M3 LOCK, BOSSARD	
10	2	DIN 913 A2	SHSS, M3 x 5 S/S	
9	2	DIN 913 A2	SHSS, M2 x 5 S/S	
8	6	DIN 7991	SHCS, M3 x 5 FLUSH HD S/S	
7	1	DIN 912	SHCS, M3 x 6 S/S	
6	4	ISO 7380	SHCS, M3 x 10 BUTTON HD S/S	
5	1	12900210	WORM GEAR	
4	1	17905500	STOP BAR	
3	1	17905490	STOP BAR HOUSING	
2	1	17905520	SPOOL CLAMP	
1	1	17905510	SPOOL	

DRAWN		DATE		DO NOT SCALE		PARTS LIST	
G. DOUGLAS	11/8/02	FROM	SCALE				
CHECK	DATE	DRAWING					
ENGINEERING	DATE	DIMENSIONS & TOLERANCES					
		(UNLESS OTHERWISE SPECIFIED)					
		LINEAR	RADII	mm			
		X.XXX	± 0.02	± 0.03			
		X.X	± 0.1	± 0.1			
		X.X	± 0.1	± 0.1			
		X	± 0.06	± 0.1			
		Ø	± 0.06	± 0.1			
		Ø	± 0.3	± 0.3			
		FINISH	RS	1.6			
		THIRD ANGLE PROJECTION					
		SOFTWARE					
		AUTOCAD 2000					
		SIZE	DRAWING NO.				
		A2	11902090				
		SCALE	2:1				
		WT	kg				
		SHEET	1				
		OF	1				

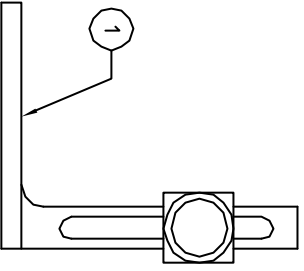
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**ROTATING DRIVE
SPOOL ASSEMBLY**

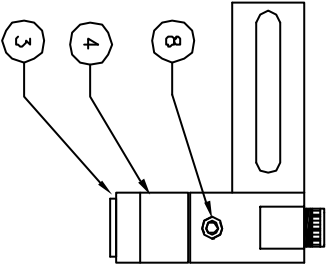
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SIDE VIEW



FRONT VIEW



TOP VIEW

REVISIONS				
REV	DESCRIPTION	DRAFT	DATE	APPROVED
A	RELEASE		12/03/02	C.DOUGLAS

ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
9	2	DIN 988	WASHER, SHIM 4 x 16 x 0.1 THICK	
8	1	DIN 913 A2	SHSS, M3 x 3 S/S	
7	1	DIN 433	WASHER, M3 FLAT S/S	
6	1	BN 792	WASHER, M3 LOCK, BOSSARD	
5	1	DIN 912	SHCS, M3 x 10 S/S	
4	1	87P-104-15	PULLEY, BERG	
3	1	17905550	PULLEY SHAFT	
2	1	17905540	BELT TENSIONER BLOCK	
1	1	17905530	BELT TENSIONER BRACKET	

DRAWN G.DOUGLAS		DATE 11/16/02	DO NOT SCALE FROM DRAWING DIMENSIONS & TOLERANCES (UNLESS OTHERWISE SPECIFIED)	
CHECKED		DATE	TITLE ROTATING DRIVE BELT TENSIONER ASSY	
ENGINEERING		DATE	SIZE DRAWING NO. A2 11902100	
NEXT ASSTY		SHEET	SCALE 2:1	
SOFTWARE AUTOCAD 2000		SHEET 1 OF 1		

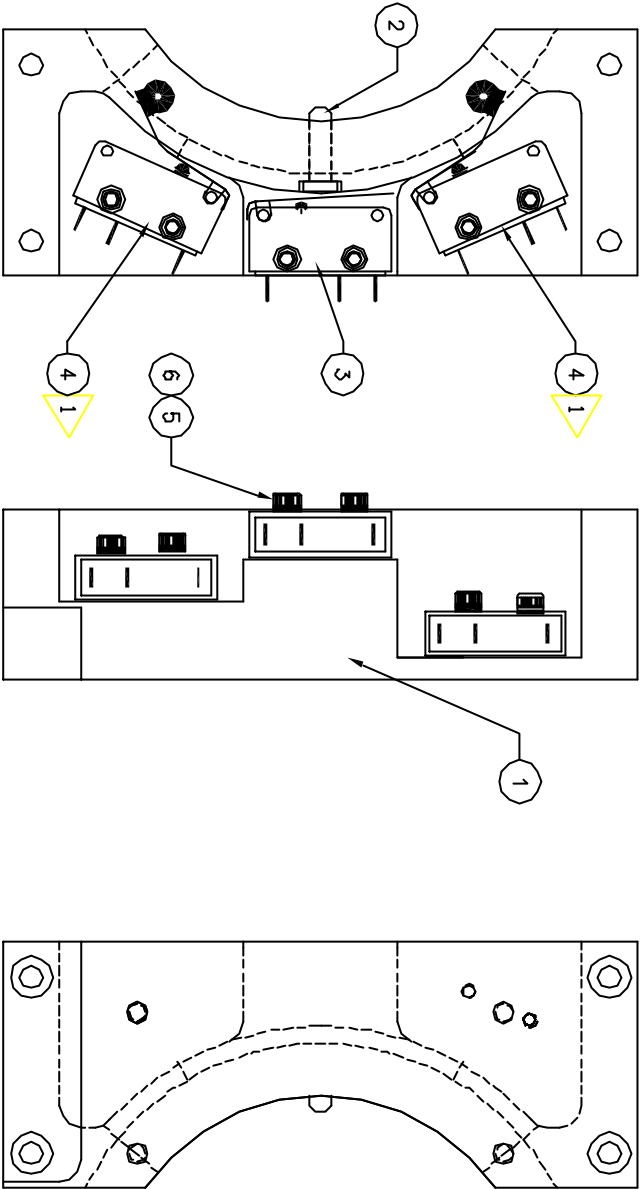
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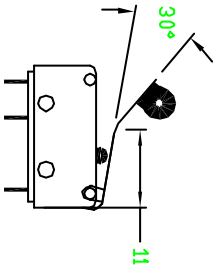
BOTTOM VIEW

REAR VIEW

TOP VIEW



NOTE:
 1 BEND MICROSWITCH ARM AS SHOWN BEFORE ASSEMBLY



REVISIONS			
REV	DESCRIPTION	DATE	APPROVED
A	RELEASE	11/22/02	G.DOUGLAS

ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
6	6	BN 752	WASHER, LOCK SP/S M2 X 0.5 SP/S	
5	6	DN 912	SHCS M2 X 10 S/S	
4	2	V4NT7	MICROSWTCH, BURGESS [travel limit]	
3	1	V4NT9	MICROSWTCH, BURGESS [zero position]	
2	1	1790544D	ZERO SHAFT	
1	1	1790546D	STOP BLOCK	

THIRD ANGLE PROJECTION

DATE: 11/19/02
 G. DOUGLAS
 DATE: 11/19/02
 G. DOUGLAS

ENGINEERING DATE: 11/19/02
 G. DOUGLAS

SOFTWARE: AUTOCAD 2000

SCALE: 2:1 WT: KG SHEET: 1 OF: 1

REV: A

SIZE: DRAWING NO. 11902110

TITLE: ROTATING DRIVE STOP BLOCK ASSY

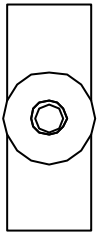
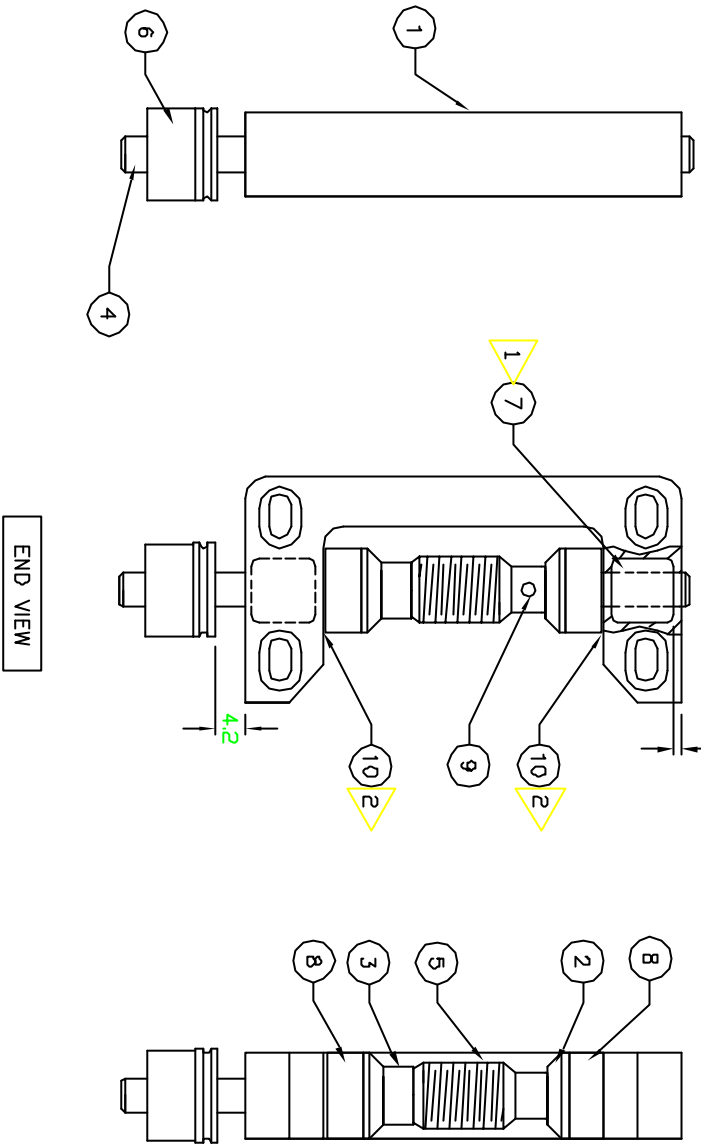
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REAR VIEW

TOP VIEW

FRONT VIEW



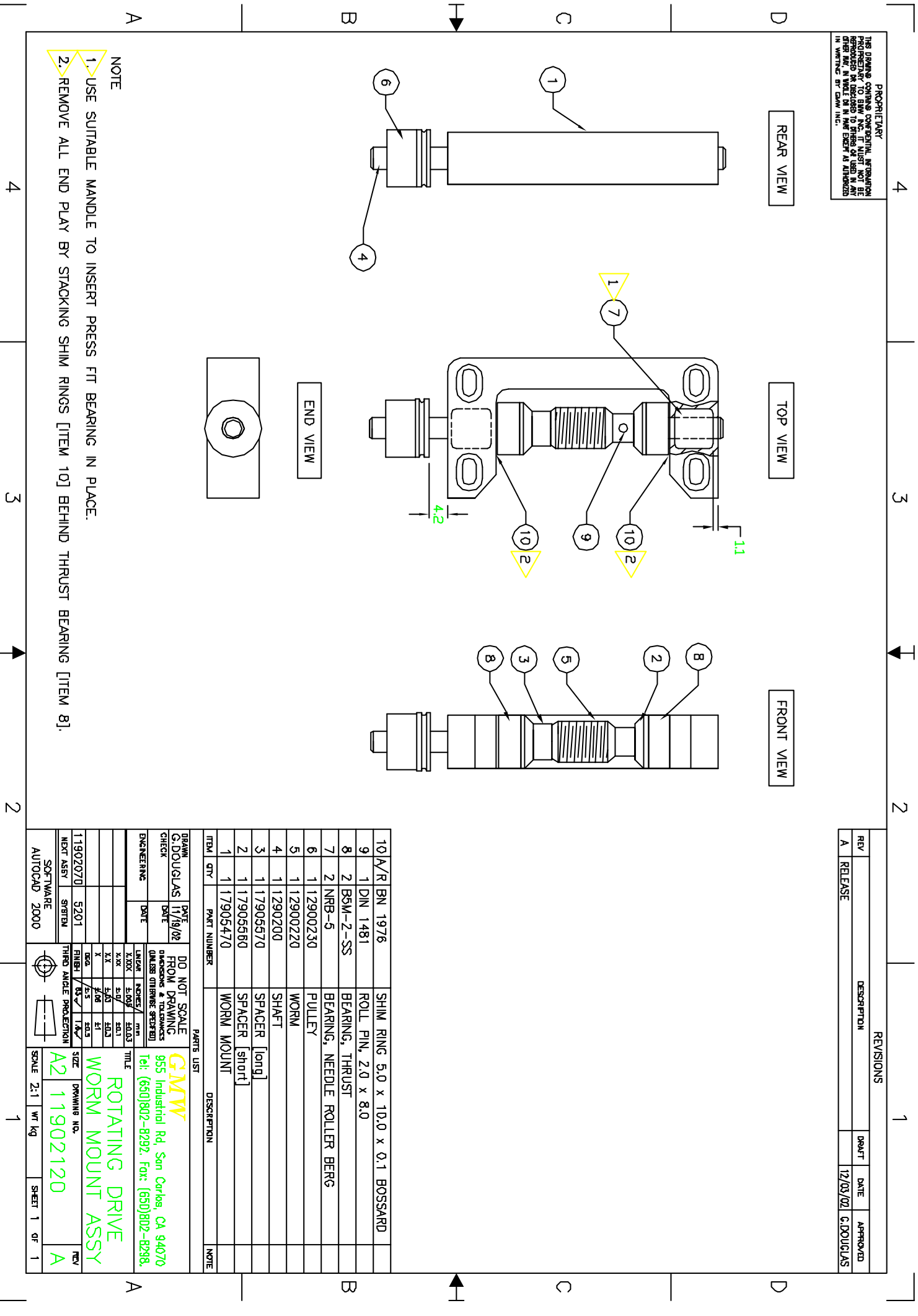
END VIEW

REVISIONS			
REV	DESCRIPTION	DRAFT	DATE
A	RELEASE		12/03/02
			C.DOUGLAS

ITEM	QTY	PART NUMBER	DESCRIPTION	NOTE
10	A/R	BN 1976	SHIM RING 5.0 x 10.0 x 0.1 BOSSARD	
9	1	DN 1481	ROLL PIN, 2.0 x 8.0	
8	2	BSM-2-SS	BEARING, THRUST	
7	2	NRB-5	BEARING, NEEDLE ROLLER BERG	
6	1	12900230	PULLEY	
5	1	12900220	WORM	
4	1	1290200	SHAFT	
3	1	17905570	SPACER [long]	
2	1	17905580	SPACER [short]	
1	1	17905470	WORM MOUNT	

DRAWN G.DOUGLAS		DATE 11/19/02	DO NOT SCALE FROM DRAWING DIMENSIONS & TOLERANCES (UNLESS OTHERWISE SPECIFIED)	
CHECKED		DATE	TITLES	
ENGINEERING		DATE	GMW 955 Industrial Rd, San Carlos, CA 94070 Tel: (650)802-8292, Fax: (650)802-8298.	
SOFTWARE		DATE	ROTATING DRIVE WORM MOUNT ASSY	
AUTOCAD 2000		DATE	SIZE DRAWING NO. A2 11902120	

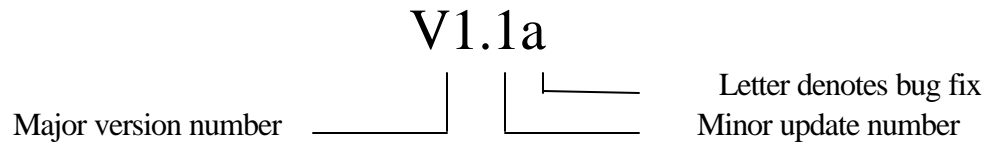
- NOTE
- USE SUITABLE MANDLE TO INSERT PRESS FIT BEARING IN PLACE.
 - REMOVE ALL END PLAY BY STACKING SHIM RINGS [ITEM 10] BEHIND THRUST BEARING [ITEM 8].



Section 9

SOFTWARE REVISION LIST

The Software revision number has the following format.



V1.0 First release April 10, 2003.