Specifications

Rated input/output

SV iG5A-			055-2	075-2	055-4	075-4	
Motor Note 1		[HP]	7.5	10	7.5	10	
		[kW]	5.5	7.5	5.5	7.5	
Rated output	Capacity	[kVA] Note 2	9.1	12.2	9.1	12.2	
	Current	[A] Note 3	24	32	12	16	
	Frequency		0~400 [Hz] Note 4				
	Voltage [V]		3Phases 200~230V Note 5		3Phases 380~460V Note 5		
Rated input	Voltage [V]		3Phases 200~230 VAC (+10%, -15%)		3Phases 380~460 VAC (+10%, -15%)		
	Frequency		50~60 [Hz] (±5%)				
Cooling type			Forced cooling				
Weight		(kg)	3.86	4.01	3.86	4.01	

Note 1 : The motor capacities were indicated assuming to use 4 poles standard motors.

Note 2 : The rated input voltage for 200V is 220V and 400V is 440V.

Note 3 : Derating is needed when the carrier frequency is setup over 3kHz. Note 4 : The maximum frequency can not be setup up to 300Hz in case of sensorless vector control. Note 5 : The maximum output voltage does not rise over rated input voltage and the output voltage can be freely set up unless it exceeds the input voltage.

Control

Control type	V/F and sensloress vector		
Frequency setup resolution	Digital : 0.01Hz		
rrequency setup resolution	Analog : 0.06Hz (Maximum frequency:60Hz)		
Frequency precision	Digital operation : 0.01% of maximum output frequency		
	Analog operation : 0.1% of maximum output frequency		
V/F pattern	Linear, square, user V/F		
Overload capacity	150%/1Minute		
Torque boost	Manual torque boost and auto torque boost		
Regenerative Maximum brake	20% Note 1		
braking torque Time/	150% with resistor Note 2		

Note 1: 20% torque regenerative refers to the average braking torque of the motor loss which is generated at deceleration stopping. Note 2 : Please refer to the user manual regarding the braking resistor specification.

Operation

Operation type		Selection among loader, terminal, communication, remote loader operations			
Frequency setup		Digital : Loader			
		Analog : 0~10V, -10~+10V, 0~20mA			
Operation function		PID control, up-down operation, 3-wire operation			
		NPN/ PNP selection			
Input		Function : Forward run, reverse run, emergency stop, fault reset, Jog, multi-step frequency-high, middle, low,			
	P1~P8	multi-step deceleration-high, middle, low, DC braking during stop, second motor selection,			
	Multi function	unction frequency increase, frequency decrease, 3-wire run, external trip A/B,			
	terminal (8points)	changing run pattern from PID to normal operation mode			
		Changing run pattern from the option run to main operation mode, analog frequency fix,			
		Selecting during acceleration/decerelation stop			
Output	Multi function open		Below DC 24V 50mA		
	collector terminal	Outputs of the inverter faults			
	Multifunction	or running modes			
	relay terminal		DEIUW I A (N.O, N.O) AOZOUV, DEIUW IA DOOUV		
	Analog output	0~10Vdc (Below 10mA) : Selection among frequency, current, voltage, DC voltage			

Protective feature

Trip	Over voltage, low voltage, over current, ground		
	fault current detection, inverter over-heating,		
	motor over-heating, output overload protection		
	communication error, output phase open, frequency		
	command loss, hardware fault, cooling fan fault		
Alarm	Stall prevention, overload		
	Below 15msec :		
Instant	Runs without stopping yet both input voltage		
power	and output should be within rated value		
failure	Over 15 Msec:		
	Automatic restart		

Exterior structure and Environment

Protection	Open type IP20		
Ambient	100 500		
temperature	-100~500		
Storage			
temperature	-20 0 ~00 0		
Ambient	Polow 00% DH (Non condensing)		
humidity	Delow 30 /8 Hi I (Noi I-coi idensing)		
Altitude, vibration	Below 1000M or 3,300FT . Below 5.9m/sec ² (0.6G)		
Ambient	70, 106 kPa		
atmospheric pressure	10~100 KFa		
Application site	No corrosive gas, combustible gas, oil mist or dust		

Wiring & Dimension

Wiring





Dimension

Inverter	SV055iG5A-2	SV075iG5A-2	SV055iG5A-4	SV075iG5A-4
Capacity [kW]	5.5	7.5	5.5	7.5
W [mm]	180	180	180	180
W1[mm]	170	170	170	170
H [mm]	220	220	220	220
H1 [mm]	210	210	210	210
D [mm]	170	170	170	170
ø [mm]	4.5	4.5	4.5	4.5
A [mm]	5	5	5	5
B [mm]	4.5	4.5	4.5	4.5
Weight [Kg]	3.86	4.01	3.86	4.01

