# Q Corresponding Ethernet Interface Module

# **MITSUBISHI**

User's Manual

(Application)



Mitsubishi Programmable Logic Controller



QJ71E71-100 QJ71E71-B5 QJ71E71-B2

## SAFETY PRECAUTIONS •

(Always read before starting use.)

Before using this product, please read this manual introduced in this manual carefully and pay full attention to safety to handle the product correctly.

The instructions given in this manual are concerned with this product. For the safety instructions of the PLC system, please read the user's manual for the CPU module to use.

In this manual, the safety instructions are ranked as "DANGER" and "CAUTION".



Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

Indicates that incorrect handling may cause hazardous conditions, resulting in medium or slight personal injury or physical damage.

Note that the ACAUTION level may lead to a serious consequence according to the circumstances. Always follow the instructions of both levels because they are important to personal safety.

Please store this manual in a safe place and make it accessible when required. Always forward it to the end user.

## [Design Precautions]

## DANGER

- For details on the operating status of each station when a communication abnormality occurs in the data link, see the manual for each data link. Erroneous outputs and malfunctions may lead to accidents.
  - Not doing so can cause an accident due to false output or malfunction.
- To prevent malfunctions of the PLC system that may be caused by illegal e-mails from the outside, take a proper countermeasure (such as virus detection) so that illegal e-mails are not received by the mail server of this module. (Using an anti-virus program, etc.)
- If it is necessary to ensure the security of the PLC system against unauthorized access from external devices via the Internet, appropriate measures must be incorporated by the user.
- Then controlling a running PLC (modifying data) by connecting peripheral devices to the CPU module or connecting a personal computer to the intelligent function module, configure an interlocking circuit in a sequence program so that the safety of the overall system is always maintained. Also, before performing other control operations (program modifications and operation status modifications (status control)) on the running PLC, be sure to read the manual carefully and thoroughly confirm the safety.

Especially in the above mentioned control operations that are performed from an external device to a remote PLC, any problems on the PLC side may not be dealt with promptly due to abnormal data communication. In addition to configuring an interlocking circuit in a sequence program, determine how the system handles data communication abnormalities, etc. between the opposite devices and the PLC CPU.

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## [Design Precautions]

## **DANGER**

• Do not write any data in the "system area" of the buffer memory of the intelligent function module. Also, do not output (turn on) the "use prohibited" signal, which is one of the output signals from the PLC CPU to the intelligent function module. If data is written to the "system area" or the "use prohibited" signal is output, there is a risk that the PLC system may malfunction.

## **↑** CAUTION

- Do not bundle the control wires and the communication cables with the main circuit and the power wires, and do not install them close to each other. They should be installed at least 100 mm (3.94 in.) away from each other. Failure to do so may generate noise that may cause malfunctions.
- When the status control (remote RUN/STOP, etc) of the PLC CPU is performed from the external device, select the "Always wait for OPEN" parameter set by an user in advance. (Select with the initial timing setting in the operational setting.) If "Do not wait for OPEN" is selected the communication line at remote STOP is closed. The communication line cannot be reopened on the PLC CPU side after that, and the remote RUN from the external device cannot start either.

## [Installation Precautions]

## **DANGER**

- Use the PLC in an environment that meets the general specifications listed in the user's manual for the CPU module to use. Using the PLC in any other operating environments may cause electric shocks, fires or malfunctions, or may damage or degrade the module.
- While pressing the installation lever located at the bottom of module, insert the module fixing tab into the fixing hole in the base unit until it stops. Then, securely mount the module with the fixing hole as a supporting point.
  - If the module is not installed properly, it may cause the module to malfunction, fail or fall off. Secure the module with screws especially when it is used in an environment where constant vibrations may occur.
- Be sure to tighten the screws using the specified torque. If the screws loose, it may cause the
  module to short-circuit, malfunction or fall off. If the screws are tightened excessively, it may
  damage the screws and cause the module to short-circuit, malfunction or fall off.
- Before mounting or dismounting the module, make sure to shut off all phases of the external power supply. Failure to do so may damage the module.
- Do not directly touch the conducting parts and electronic parts of the module. This may cause the module to malfunction or fail.

## [Wiring Instructions]

## **↑** CAUTION

- Use crimp-contact, pressure-displacement or soldering to wire the connectors for external
  connections properly using the manufacturer-specified tools.
   If the connection is incomplete, it may cause the module to short circuit, catch fire, or
  malfunction.
- Do not connect the AUI cable when the power to the station in which the module is loaded is on.
- Make sure to place the communication and power cables to be connected to the module in a
  duct or fasten them using a clamp. If the cables are not placed in a duct or fastened with a
  clamp, their positions may be unstable or moved, and they may be pulled inadvertently.
   This may damage the module and the cables or cause the module to malfunction because of
  faulty cable connections.
- Tighten the terminal screws using the specified torque. If the terminal screws are loose, it may cause the module to short-circuit, malfunction or fall off. If the terminal screws are tightened excessively, it may damage the screws and cause the module to short-circuit, malfunction or fall off.
- When disconnecting the communication and power cables from the module, do not pull the cables by hand. When disconnecting a cable with a connector, hold the connector to the module by hand and pull it out to remove the cable. When disconnecting a cable connected to a terminal block, loosen the screws on the terminal block first before removing the cable. If a cable is pulled while being connected to the module, it may cause the module to malfunction or damage the module and the cable.
- Be careful not to let any foreign matter such as wire chips get inside the module. They may cause fire, as well as breakdowns and malfunctions of the module.
- A protective sheet is pasted on the upper part of the module in order to prevent foreign matter such as wire chips to get inside the module while wiring.
   Do not remove this protective sheet during wiring work. However, be sure to remove the protective sheet before operating the module to allow heat radiation during operation.
- Solder the coaxial cable connectors properly. Incomplete soldering may result in malfunctions.

## [Setup and Maintenance Precautions]

## **↑** CAUTION

- Never disassemble or modify the module. This may cause breakdowns, malfunctions, injuries or fire
- Before mounting or dismounting the module, make sure to shut off all phases of the external power supply. Failure to do so may cause the module to breakdown or malfunction.
- Do not mount/remove the module onto/from base unit more than 50 times (IEC61131-2-compliant), after the first use of the product.
  - Failure to do so may cause the module to malfunction due to poor contact of connector.
- Do not touch the terminals while the power is on. Doing so may cause electric shocks or malfunctions.
- Before cleaning the module or retightening the terminal screws and the module mounting screws, make sure to shut off all phases of the external power supply. Failure to do so may cause the module to breakdown or malfunction. If the screws are loose, it may cause the module to short-circuit, malfunction or fall off. If the screws are tightened excessively, it may damage the screws and cause the module to short circuit, malfunction or fall off.
- Always make sure to touch the grounded metal to discharge the electricity charged in the body, etc., before touching the module.
  - Failure to do so may cause a failure or malfunctions of the module.

## [Operating Precautions]

## **A** CAUTION

 Please read the user's manual carefully and confirm the safety thoroughly before proceeding to perform control operations of the PLC (especially, modifications of data, programs and operation status (status control)) that is running by connecting personal computers, etc. to the intelligent function module.

Incorrect modifications of data, programs and operating status may cause system malfunctions, damages to the machines, or accidents.

## [Precautions When Disposing of This Product]

## **⚠** CAUTION

• Dispose of this product as an industrial waste.

#### **REVISIONS**

\* The manual number is given on the bottom left of the back cover.

Print Date	* Manual Number	* The manual number is given on the bottom left of the back cover.  Revision				
Dec., 1999						
Oct., 2000	SH(NA)-080010-A	Reflect the contents of the function version B.				
Oct., 2000	SH(NA)-000010-B	Put Windows® base software products together from Mitsubishi Programmable Logic Controller MELSEC series to Mitsubishi integrated FA software MELSOFT series. Standardize the name from software package (GPP function) to product name (GX Developer).				
		Correction Entire manual (change MELSECNET/10H to MELSECNET/H), Contents About Manuals, About the Generic Terms and Abbreviations, Chapter 1 (entire), Section 1.2 (POINT), Section 2.1, 2.5 (2), 2.6.1, 2.6.2, 2.7.1, 2.7.2, Section 3.2.1 (2). 3.3.3 (4), Section 4.1, 4.3, 4.5.2, Section 5.1.1, 5.2, 5.3, 5.4, 5.5, 5.6.1, 5.6.1 (2) 2), 5.6.2, 5.6.4, Section 6.2 to 6.8, 6.9 (POINT before the function), 6.10 to 6.14				
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		QJ71E71-100				
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Japanese Manual Version SH-080005-J

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#### INTRODUCTION

Thank you for purchasing the MELSEC-Q series PLC.

Before using the equipment, please read this manual carefully to develop full familiarity with the functions and performance of the Q series PLC you have purchased, so as to ensure correct use. Please forward a copy of this manual to the end user.

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#### **About Manuals**

The following manuals are also related to this product.

If necessary, order them by quoting the details in the tables below.

#### Related Manuals

Manual name	Manual number (Model code)
Q Corresponding Ethernet Interface Module User's Manual (Basic)  This manual explains the specifications of the Ethernet module, data communication procedures with external devices, line connections (open/close), fixed buffer communication, random access buffer communication, and troubleshooting.	SH-080009 (13JL88)
Q Corresponding Ethernet Interface Module User's Manual (Web function)  This manual explains how to use the Web function of the Ethernet module. (Sold separately)	SH-080180 (13JR40)
Q Corresponding MELSEC Communication Protocol Reference Manual  This manual explains the communication methods and control procedures through the MC protocol for the external devices to read and write data from/to the PLC CPU using the serial communication module/Ethernet module  (Sold separately)	SH-080008 (13JF89)

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#### The Manual's Use and Structure

#### How to use this manual

In this manual, explanations are given for each special function of the Ethernet modules (QJ71E71-100, QJ71E71-B5 and QJ71E71-B2). Please use this manual using the following key items below as a reference.

#### (1) To learn about an overview of the special functions

 Chapter 1 provides an overview of each of the special functions available for the Ethernet modules.

#### (2) To use the e-mail transmission/reception function and the PLC CPU monitoring function

- Section 2.2 describes the environment in which e-mails can be used.
- Section 2.6 illustrates the screens for parameter settings using GX Developer in order to use the e-mail function.
- Section 2.9 describes the parameter settings in order to monitor the status of the PLC CPU.

## (3) To communicate with PLC CPUs of other stations via the MELSECNET/H, MELSECNET/10 and Ethernet module

- Section 3.2 describes the accessible range and accessible stations when accessing other stations via the Ethernet modules.
- Section 3.3 describes the parameter settings using GX Developer in order to perform data communication with the PLC CPUs of other stations.
- Section 3.3.2 provides an overview of the processing for Station No. <-> IP information conversion.

#### (4) To use the file transfer (FTP) function

- Section 5.3 describes the parameter settings using GX Developer in order to perform the file transfer.
- Section 5.6 describes the FTP operation command on the FTP client (external device) side that is supported by the Ethernet module.

#### **POINT**

To know about the following items, see the Ethernet Interface Module User's Manual (Basic).

- Detailed descriptions of the error codes
   Chapter 11 describes troubleshooting, how to check for errors, and detailed descriptions of error codes for the Ethernet modules.
- (2) Storage locations of the error codes for the Ethernet module Section 11.3 lists the error code storage locations in the buffer memory in the beginning of the section.

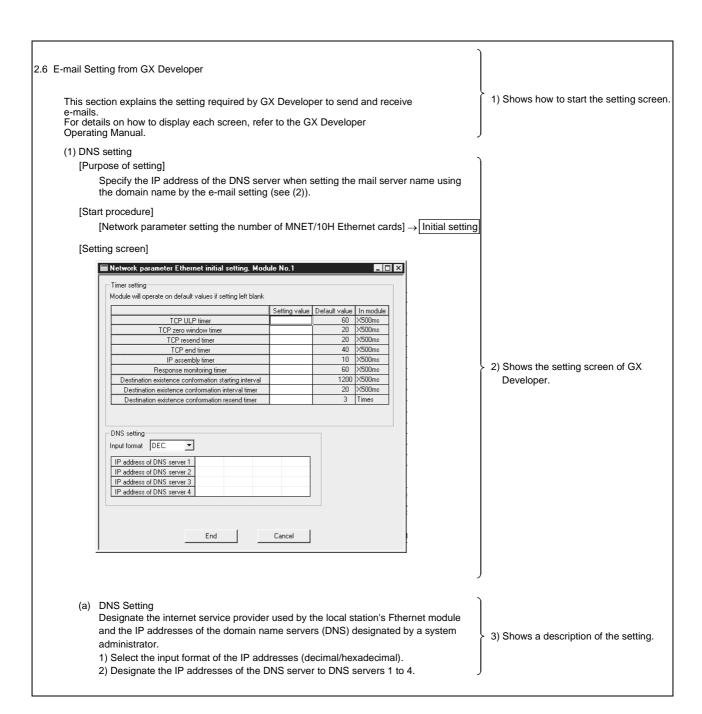
#### Structure of this manual

#### (1) Setting Parameters with GX Developer

- (a) By setting parameters with GX Developer, the sequence programs for communicating with external devices can be simplified in the Ethernet module.
- (b) In this manual, parameter settings using GX Developer are explained in detail for each item displayed on the setting screens.
  - \* For details on the types of the setting screens, objectives of the settings, the setting items and an outline of the setting operation using GX Developer, see Section 4.5 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)
- (c) Set the required parameters by referring to chapters that explain the functions to be used, and load the set parameters to the PLC CPU of the Ethernet module installed station.

### (2) Setting screen of GX Developer

This manual explains the parameter settings with GX Developer in the following format:



\* Depending on the function used, "(Address: \( \pi \pi \pi \pi \pi \pi)\)" may be indicated after some function names. This address indicates the buffer memory address of the Ethernet module in which the setting values from GX Developer are stored. For more details on the buffer memory, see Section 3.8 of the Q Corresponding Ethernet Interface Module User's Manual (Basic).

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#### About the Generic Terms and Abbreviations

This manual uses the following generic terms and abbreviations to describe the Model QJ71E71-100, QJ71E71-B5 and QJ71E71-B2 Ethernet interface modules, unless otherwise specified.

Generic Term/Abbreviation		Description			
ACPU	Generic term for AnNCPU, AnACPU, and AnUCPU.				
AnACPU	Generic term for A2ACPU, A2ACPU-S1, A2ACPUP21/R21, A2ACPUP21/R21-S1, A3ACPU, A3ACPUP21/R21.				
AnNCPU		erm for A1NCPU, A1NCPUP21/R21, A2NCPU, A2NCPU-S1, P21/R21, A2NCPUP21/R21.			
AnUCPU	Generic te	Generic term for A2UCPU, A2UCPU-S1, A2ASCPU, A2ASCPU-S1, A3UCPU, A4UCPU.			
Ethernet Address	Control) a network.	e-specific address that is also referred to as the MAC (Media Access ddress. This is used to identify the addresses of external devices over a The Ethernet address of the Ethernet module can be verified on the MAC mn of the rating plate.			
Ethernet module E71 module		ion for Model QJ71E71-100, QJ71E71-B5 and QJ71E71-B2 Ethernet Modules. (Indicated as the Ethernet module or E71 in the diagrams)			
Ethernet network system	Abbreviati	ion for 10BASE2,10BASE5, 10BASE-T and 100BASE-TX network systems.			
GX Developer	Abbreviati greater)	ion for GX Developer (SWnD5C-GPPW-E). (n in the model name is 4 or			
MELSECNET/10	Abbreviat	ion for the MELSECNET/10 network system.			
MELSECNET/H	Abbreviation for the MELSECNET/H network system.				
Network module (N/W module)	Abbreviation for interface modules compatible with the MELSECNET/H, MELSECNET/10 network system.				
Opossit device External device	Generic term for personal computers, computers, work station (WS) and Ethernet module etc. that are connected by the Ethernet for data communication.				
Personal computer	Generic te	rm for IBM PC/AT (or 100% compatible) personal computer.			
QCPU	Q mode	Generic term for Q00JCPU, Q00CPU, Q01CPU, Q02CPU, Q02HCPU, Q06HCPU, Q12HCPU, Q25HCPU, Q12PHCPU, Q25PHCPU, Q12PRHCPU and Q25PRHCPU.			
QCPU station	Abbreviati	ion for the PLC mounted QCPU.			
QnACPU		erm for Q2ACPU, Q2ACPU-S1, Q2ASCPU, Q2ASCPU-S1, Q2ASHCPU, PU-S1, QA3ACPU, Q4ACPU and Q4ARCPU.			
Q/QnA	Generic term for QCPU and QnACPU.				
Reference Manual	Abbreviation for the Q Corresponding MELSEC Communication Protocol Reference Manual.				
User's Manual (Application)	Abbreviation for the Q Corresponding Ethernet Interface Module User's Manual (Application).				
User's Manual (Basic)	Abbreviation for the Q Corresponding Ethernet Interface Module User's Manual (Basic).				
User's Manual (Web function)	Abbreviati (Web fund	ion for the Q Corresponding Ethernet Interface Module User's Manual ction)			

#### 1 OVERVIEW

This manual provides information on the special functions of the MELSEC-Q Series Ethernet Interface Modules (hereinafter called the Ethernet module).

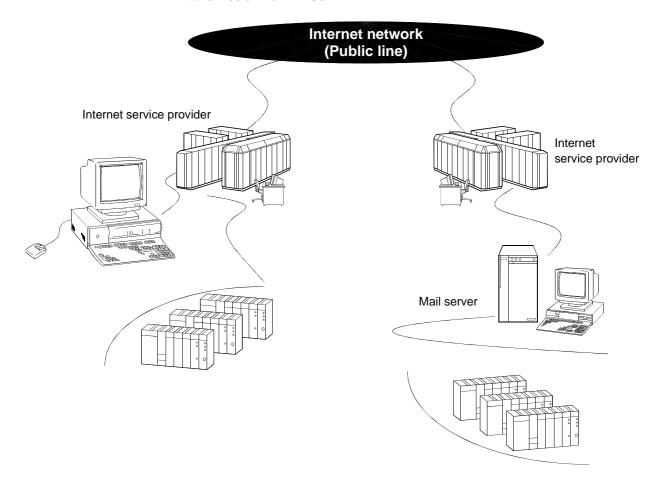
When applying the following program examples to the actual system, make sure to examine the applicability and confirm that it will not cause system control problems. This chapter describes an overview of the special functions that are available for the Ethernet module.

#### 1.1 Overview

### (1) Send/receive e-mails (Details are explained in Chapter 2)

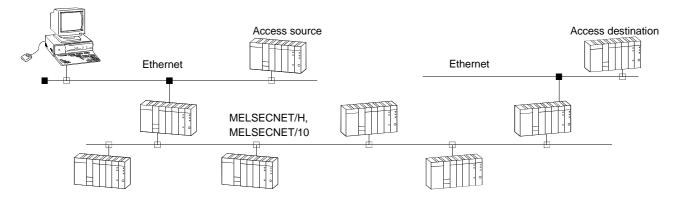
This function allows the transmission and reception of a maximum of 6k words of CPU information as the main text or attached file of e-mail to/from computers and PLC CPUs via the Internet.

Furthermore, by setting the automatic notification, the Ethernet module sends e-mail when the notification conditions set by the user match for the transmission from PLCs.



(2) Communicate with other stations' PLCs via the MELSECNET/H, MELSECNET/10 network system (Details are explained in Chapter 3) This function enables accessing other stations via multiple networks in the network system shown below.

This function is used for multiple relays through a network in which the Ethernet and MELSECNET/H, MELSECNET/10 network systems coexist as well as through a network in which multiple Ethernet network systems are connected. Using this function, another station's PLC can be accessed via the MELSECNET/H, MELSECNET/10 and Ethernet network systems.

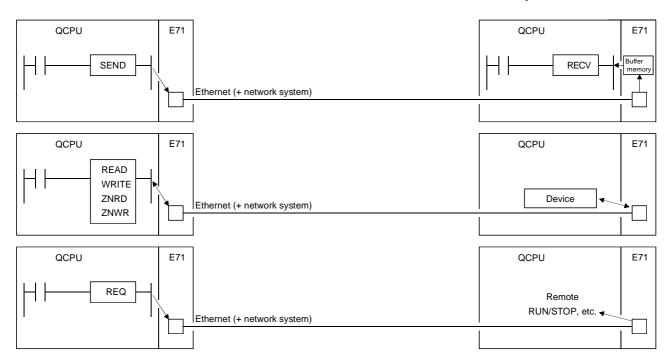


## (3) Perform data communication between PLC CPUs (Details are explained in Chapter 4)

This function sends and receives data to/from another station's PLC CPU via the Ethernet using the data link instructions

(SEND/RECV/READ/WRITE/REQ/ZNRD/ZNWR).

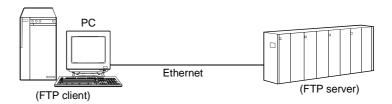
It also sends and receives data to/from another station's PLC CPU via the Ethernet and MELSECNET/H, MELSECNET/10 network systems.



(4) Perform file transfer (FTP) (Details are explained in Chapter 5)

The Ethernet module supports the server function of the TCP/IP standard protocol, FTP (File Transfer Protocol). By using the FTP commands, QCPU files can be read/written in file units.

Because of this, it is possible to manage QCPU files by computers, etc., and to transfer files and browse a file list as needed.



#### 1.2 Additional Functions in Function Version B or Later

The following table lists the functions additionally provided for the Ethernet modules of function version B or later.

For the function version, serial No., software version of the Ethernet modules and related products (i.e. CPU module, GX Developer) supporting the additional functions, refer to the User's Manual (Basic), Section 2.7.

For comparison by function versions of the Ethernet module, refer to the User's Manual (Basic), Appendix 1.1.

#### (1) Functions added for function version B

	Function	Overview	Reference section
	Sending files in CSV format as attachment	Sends a file in CSV format as attachment to e-mail from the Ethernet module.	
When using	Sending main text	Sends main text of up to 960 words from the Ethernet module.	
the e-mail function	Support for encoding/ decoding	<ul> <li>The following encoding/decoding is supported.</li> <li>Encode the Subject using 7 bits encoding and send it from the Ethernet module.</li> <li>Decode and receive an e-mail encoded with Quoted Printable by the Ethernet module.</li> </ul>	Chapter 2
When using the file transfer	Remote password check	Unlocks/locks the remote password of the QCPU. The unlock processing enables access to the QCPU using FTP commands.	Oh saat as 5
(FTP server) function	Support for multiple CPU systems	The QCPU transfers files to the control PLC/non-control PLC of the Ethernet module when a multiple CPU system configuration is used.	Chapter 5

#### (2) Function added for function version D

Function	Overview	Reference section
Specifying target station's CPU type in data link instructions	In the following data link instructions, the target station's CPU type can be specified ((S1)+3). (Specification of control/standby system or system A/B in the redundant system is available.)  • READ/SREAD instruction  • WRITE/SWRITE instruction  • REQ instruction	Chapter 4 Chapter 6

#### 2 USING THE E-MAIL FUNCTION

#### 2.1 E-mail Function

The e-mail function sends and receives CPU information (PLC CPU status and device values) to/from PCs or PLC CPUs in remote locations via the Internet.

The following two methods are available to send/receive e-mail using this function.

Sending/receiving e-mail by the PLC CPU
 Executed by a sequence program using dedicated instructions.

(2) Sending e-mail using the Ethernet module's PLC CPU monitor function

Executed by the Ethernet module according to the Ethernet module parameter setting (notification setting) using GX Developer.

#### 2.1.1 E-mail send and reception by the PLC CPU

(1) Sending/receiving e-mail by the PLC CPU

In sending/receiving e-mail by the PLC CPU, the CPU information of a station in which an Ethernet module is installed is sent to another Ethernet modules or an external device such as a PC as the main text or attached file of e-mail. E-mail sent from other Ethernet modules and PCs can also be received.

			External device			
Sending e-mail by the PLC CPU (MSEND instruction)		Ethernet module (MRECV PC instruction)		Portable terminal (device that cannot handle attached files)	Remark	
	Subject		0	0	_	
A 11 l l	Binary format	0				
Attached file	Binary to ASCII conversion	.,	0	×	Maximum 6k words	
iile	Binary to CSV conversion	×				
Main text Designating using ASCII data		×	0	0	Maximum 960 words.	

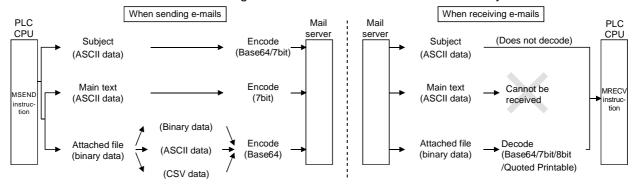
<sup>\*1</sup> The Ethernet module receives the Subject without decoding.

- (a) Sending e-mail by the PLC CPU (MSEND instruction)Data transmission is performed via the main text or attached file of e-mail
  - using the MSEND instruction.

    1) For an attached file, device data and other information is sent by
  - converting into binary/ASCII/CSV data format.2) For the main text, ASCII code data (character string data) created by a sequence program is sent.
- (b) Receiving e-mail by the PLC CPU (MRECV instruction) Receives attached file data of e-mail using the MRECV instruction. The main text data of e-mail cannot be received.

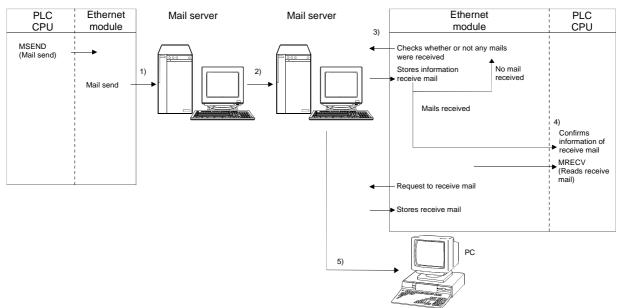
2 - 1 2 - 1

## (2) Data conversion method used by the Ethernet module The following shows the data conversion method used by the Ethernet module.



#### (3) Flow of the e-mail

The following diagram illustrates the flow of e-mail sent by the PLC CPU to its reception by the external device:



- 1) Send an e-mail to the send mail server of the local station's Ethernet module.
- 2) The send mail server of the local station's Ethernet module sends the e-mail to the receive mail server of the send destination device.

[When receiving by the Ethernet module]

- 3) The Ethernet module checks whether or not any mails have arrived at the inquiry interval set with GX Developer, and stores the results to the buffer memory.
- 4) By executing the MRECV instruction, the Ethernet module reads e-mails from the e-mail server to the mail buffer.

The PLC CPU reads one e-mail and stores it in the mail buffer of the PLC CPU's device.

\* By user designation with the MRECV instruction, the Ethernet module reads the number of remaining receive mails on the mail server and stores this number in the buffer memory.

[When receiving by a PC]

5) Mails can be received using applications such as Internet Mail.

#### POINT

The e-mail send/reception function by the PLC CPU and the communication function using the random access buffer cannot be used together. Only one of them can be used at any given time.

### 2.1.2 Sending e-mail using the PLC CPU monitor function

#### (1) Monitor function of the PLC CPU

The monitor function of the PLC CPU is used to regularly monitor the status of the PLC CPU and device values, and send e-mail to the designated external device when they match with the notification conditions (PLC CPU status and device values) set by the user.

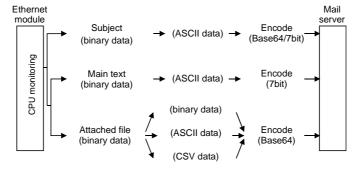
		Exte				
Sending e-mail using the PLC CPU monitor function (notification setting) $(*^1)$		Ethernet module (MRECV instruction)	PC (device that cannot handle		Remark	
	Subject		0	0	_	
	Binary format		0			
	Attached Binary to ASCII conversion			×	Maximum 960 words	
file Binary to CSV conversion		×				
Main text Binary to ASCII conversion		×	0	0	Maximum 960 words.	

- \*1 For the notification of CPU status monitoring, only the Subject (that stores the PLC CPU status) will be sent.
- \*2 The Ethernet module receives the Subject without decoding.
- (a) The PLC CPU in the Ethernet module loaded station is monitored for every CPU inquiry time interval set by the user. The following information can be registered as the notification conditions.
  - 1) Device monitoring of the PLC CPU
    - · Monitoring the numeric values stored in the word device
    - Monitoring the bit device ON/OFF status
  - 2) Monitoring of the PLC CPU status
    - Monitoring the CPU module status (RUN/STOP/PAUSE)
- (b) The device monitoring result of the PLC CPU is sent by either the main text or attached file of e-mail.
  - The attached file is sent by converting the device monitoring data into binary/ASCII/CSV data format.
  - The main text is sent by converting the device monitoring data into ASCII format.
- (c) As for the status monitoring result of the PLC CPU, only the Subject (that stores the PLC CPU status) is sent.
- (d) When more than one send mail address are specified in the notification setting, the smallest numbered address is set in the "To" field of the mail header.

The other addresses are set into the "Cc" field for transmission.

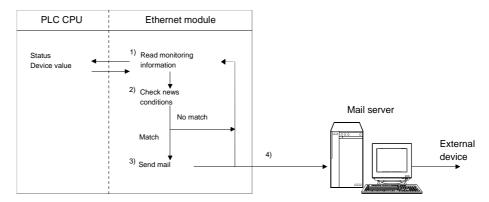
#### (2) Data conversion method used by the Ethernet module

The following shows the data conversion method used by the Ethernet module.



#### (3) Flow of the e-mail

The diagram shown below illustrates the flow of e-mails from the local station's Ethernet module to the external device after the monitor values match with the news conditions.



- Reads the monitoring information (such as status and device values) of the PLC CPU.
- 2) Checks whether the monitoring information read and the news conditions set by the user match. (Checks match/mismatch of the news conditions.)
- 3) Sends an e-mail when the monitored values match with the news conditions.
  - \* Multiple news conditions may be set so that an e-mail can be sent (notified) when any of the conditions matches. (See Section 2.9.1.) Set the CPU inquiry time interval used by the Ethernet module to monitor the PLC CPU, considering the interval of change time in the monitoring target.

After a news condition match occurs, the Ethernet module must confirm the mismatches of other news conditions for the same monitoring target. The next e-mail can be sent only after the Ethernet module confirms the mismatches of these news conditions.

- 4) The Subject of e-mail, which is sent when the notification conditions match, is fixed data. The format of the Subject is as follows (see Section 2.9.2):
  - · When monitoring the CPU status

Subject = "Transmission destination No., CPU model name, Status, Detection time"

· When monitoring the CPU device

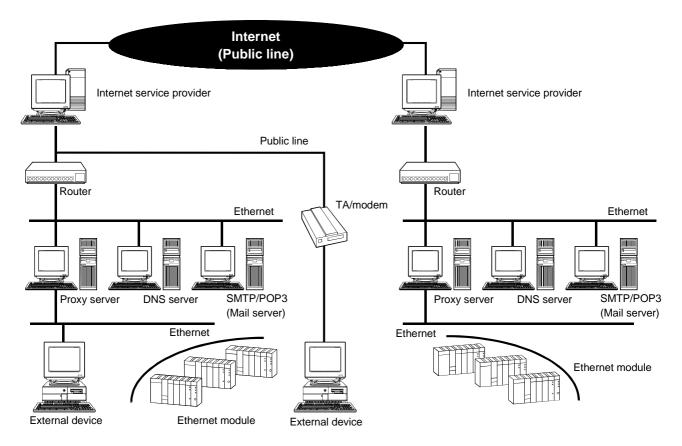
Subject = "Transmission destination No., Matched condition device, Monitoring value, ... "

#### POINT

The e-mail transmission function of the PLC CPU and the communication function using the random access buffer can be used together.

#### 2.2 Configuration and Environment of the Applicable System

This section explains the environment and system configuration for using the e-mail function from the Ethernet module.



- (1) E-mails can be sent and received in an environment where the Internet service is available as shown above.
- (2) Set each Internet mail setting value for the Ethernet module and PC following the directions from the Internet service provider or system administrator.
- (3) Each of the Ethernet module parameters for using the e-mail function is set with GX Developer.

#### 2.3 Precautions for Using the E-mail Function

The following explains precautions when using the e-mail function of the Ethernet module.

#### (1) Precautions regarding the system

- (a) Design the system so that the entire system operates normally at all times when sending/receiving e-mails to/from a running system and controlling the PLC.
- (b) In order to avoid PLC system malfunctions caused by receptions of illegal e-mails from the outside sources, take precautions in preventing illegal e-mails from being received on the mail served on the Ethernet module side (using an anti-virus program, etc).

#### (2) Precautions regarding the external device

- (a) E-mails can be sent to PLC CPU stations in which Q series Ethernet modules are installed.
  - Since the conventional A/QnA series Ethernet modules do not have the email function, e-mails cannot be sent to those PLC CPU stations.
- (b) To send files to the Ethernet module as attachments to e-mail, specify the encoding method (Base 64/7 bits/8 bits/Quoted Printable) of the attached files.

#### (3) Common precautions

- (a) The Ethernet module stores the data of attached files received from the external device in the device specified by the MRECV instruction without converting it from ASCII to binary.
- (b) The maximum sizes of data that can be sent/received by the Ethernet module are as follows:
  - · Data size of attached files: Up to 6k words
  - Data size of main text: Up to 960 words
- (c) Mails that are sent and received do not support encrypted data, compressed data, and data conversion.
- (d) When the external device could not be found in an e-mail sending from the Ethernet module, the error code can be checked through the reception processing with the MRECV instruction.
  - If an external device cannot be found when sending e-mail using the MSEND instruction, failure of e-mail transmission may not be recognized, depending on the operation of the mail server. Be sure to verify the receiver's e-mail address in advance.
  - \* Error codes are stored within the control data of the MRECV instruction. (For details on error codes, refer to the User's Manual (Basic).)
- (e) The e-mail function is supported for the SMTP and POP3 servers.

- (f) When communication errors of e-mails cannot be checked by a dedicated instruction, check the error codes stored in the mail send/reception error log area of the buffer memory.
- (g) If e-mails cannot be received, try one of the following.
  - 1) Execute the MRECV instruction once.
  - 2) Shorten the "Inquiry interval" time in the e-mail settings of GX Developer.
  - 3) Check the number of incoming mails remaining on the mail server. (Can be checked with the buffer memory address 5870H area.)
- (h) When the receive data of an e-mail sent using the MSEND instruction is abnormal (garbled characters, etc.), review the transmission data format (binary/ASCII/CSV) designated with the MSEND instruction.
  - \* The Subject should be designated in ASCII code data. (It is not converted to ASCII format.)
- (i) Confirm with a system administrator regarding the minimum time intervals for accessing the mail server when sending mails, reading receive mails, and inquiring whether or not there are receive mails.
   Depending on the mail server's security setting, frequent access may be prohibited.
- (j) The e-mail send/reception function using the PLC CPU and the communication function using the random access buffer cannot be used together. Only one of them can be used at a time.
  - \* The e-mail send function using PLC CPU monitoring and the communication function using the random access buffer can be used together.
- (k) A Subject that has been sent by the MSEND instruction from an Ethernet module of the following versions, cannot be received normally by the MRECV instruction.
  - Ethernet modules with serial numbers where the first 5 digits are 03101 or less

Different methods are used for converting Subject data at send and reception. (See Section 2.1.1 (2).)

- When sending: Encodes the Subject and then send it.
- When receiving: Receives the Subject without decoding it.

## 2.4 E-mail Specifications

The following table lists the specifications of the e-mail function.

Item			Specification		
	D-1	Attached file	6 k words × 1		
	Data size	Main text	960 words $ imes$ 1		
	Data transfer method		When sending: Sends either a file as attachment or main text (select one).		
			When receiving: Received a file as attachment.		
	Subject		Us-ASCII format or ISO-2022-JP (Base 64)		
	Attached fil	le format	MIME format		
	MIME		Version 1.0		
			Binary/ASCII/CSV can be selected.		
	Data of atta	ached file format	File name: XXXX.bin (binary), XXXX.asc (ASCII), XXXX.csv (CSV)		
			(CSV: Comma Separated Value)		
			Cannot be divided (only one file can be sent/received)		
Transmission	Division of attached file		* If any divided files are received, only the first file will be received and the remaining files		
specifications			will be discarded.		
Transmission	When sending (encode)		Subject: Base 64/7 bits		
and reception			Main text: 7 bits		
data			Attached file: Base 64		
	When receiving (decode)		Subject: (Does not decode)		
			Main text: (Cannot be received)		
			Attached file: Base 64/7 bits/8 bits/Quoted Printable		
			* If e-mail is sent from the external device to the PLC side, specify the encoding method		
			(Base 64/7 bits/8 bits/Quoted Printable) of the attached file.		
	Encryption		No		
	Compressi		No		
		ation with mail	SMTP (sending server) Port number = 25		
	server		POP3 (receiving server) Port number = 110		
	Operation check mailer		Microsoft® Corporation Internet Explorer 5.0 (Outlook Express 5.5/Outlook Express 5)		
			Netscape® Communications Corporation Netscape® 4.05		

## REMARK

Internet mail terminology list:

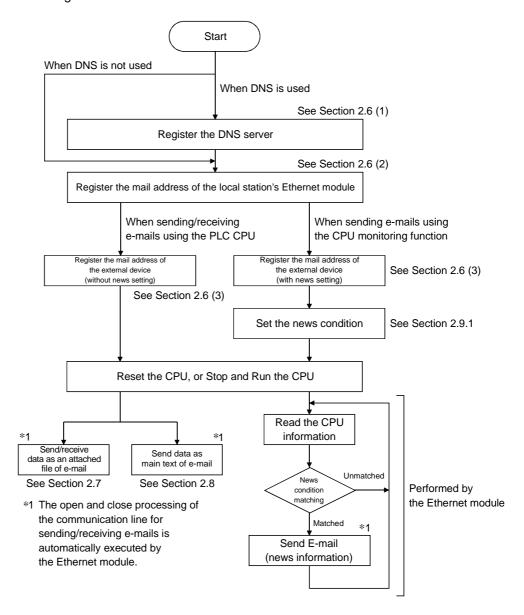
DNS server: Server that manages networks

SMTP server: Server that delivers (transfers) e-mail between mail servers POP3 server: Server that transfers received e-mail addressed to subscribers to

the corresponding subscribers

### 2.5 Processing Procedure of the E-mail Function

The following flowchart illustrates the procedure that is required before sending and receiving e-mails:



## 2.6 E-mail Setting from GX Developer

This section explains the settings required by GX Developer to send and receive e-mails.

For details on how to display each screen, refer to the GX Developer Operating Manual.

#### (1) DNS setting

[Purpose of setting]

Specify the IP address of the DNS server when setting the mail server name using the domain name by the e-mail setting (see (2)).

[Start procedure]

[Network parameter setting the number of MNET/10H Ethernet cards]  $\rightarrow$ 

Initial setting

[Setting screen]

Network parameter Ethernet initial setting. Modu	ile No.1		_ 🗆 ×
Timer setting			
Module will operate on default values if setting left blank			
	Setting value	Default value	In module
TCP ULP timer		60	X500ms
TCP zero window timer		20	X500ms
TCP resend timer		20	X500ms
TCP end timer		40	X500ms
IP assembly timer		10	X500ms
Response monitoring timer		60	X500ms
Destination existence conformation starting interval		1200	X500ms
Destination existence conformation interval timer		20	X500ms
Destination existence conformation resend timer		3	Times
Input format DEC.  IP address of DNS server 1 IP address of DNS server 2 IP address of DNS server 3 IP address of DNS server 4			
End	Cancel		

2 - 10 2 - 10

#### Initial settings

Item name		Description of setting	Setting range/options
	TCP ULP timer	Set the time of packet existence at TCP data send.	2 to 32767
	TCP zero window timer	Set the interval for checking the receive enabled status.	2 to 32767
	TCP resend timer	Set the time to resend at TCP data send.	2 to 32767
	TCP end timer	Set the confirmation wait time at TCP close processing.	2 to 32767
	IP assembly timer	Set the wait time for division data packets.	1 to 32767
Timer setting (*1)	Response monitoring timer	Set the response wait time.	2 to 32767
	Destination existence confirmation starting interval	Set the time to start confirming existence of an external device after communication with it has terminated.	1 to 32767
	Destination existence confirmation interval timer	Set the time interval between reconfirming existence.	1 to 32767
	Destination existence confirmation resend timer	Set the number of times to reconfirm existence when a response to the existence confirmation is not received.	1 to 32767
DNS setting	Input format	Select the input format of the IP addresses of the DNS servers.	decimal/hexadecimal
	IP address of DNS server 1	Set IP address of DNS server 1.	_
	IP address of DNS server 2	Set IP address of DNS server 2.	_
	IP address of DNS server 3	Set IP address of DNS server 3.	_
	IP address of DNS server 4	Set IP address of DNS server 4.	_

<sup>\*1</sup> See Section 5.2 of the User's Manual (Basic)

#### (a) DNS setting

Designate the Internet service provider used by the local station's Ethernet module and the IP addresses of the domain name servers (DNS) designated by a system administrator.

- 1) Select the input format of the IP addresses (decimal/hexadecimal).
- 2) Designate the IP addresses of the DNS servers to DNS servers 1 to 4.

#### **POINT**

- (1) The DNS servers manage networks.
  - DNS settings are required to search for the SMTP server and POP3 server from a domain name.
- (2) Make the DNS setting when the mail server name shown in item (2) is specified with a domain name.
  - No setting is required when it is specified with an IP address.
- (3) When obtaining the IP addresses from a domain name, the DNS servers are searched sequentially starting from the first DNS server.

2 - 11 2 - 11

### (2) E-mail setting

[Purpose of setting]

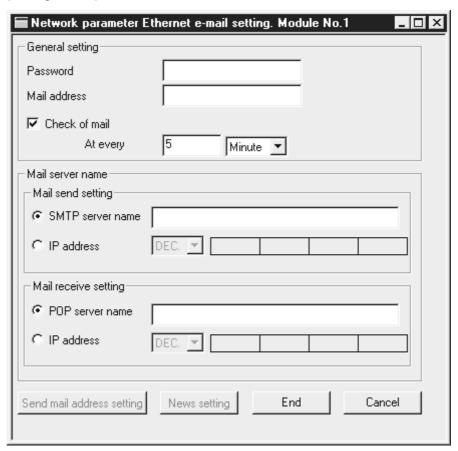
Perform the setting to use the e-mail function.

[Start procedure]

[Network parameter setting the number of MNET/10H Ethernet cards]  $\rightarrow$ 

E-mail setting

#### [Setting screen]



#### [Setting item]

Item name		ne	Description of setting item	Setting range/option
Password			Set the password to the mail server	_
	Mail address		Set the mail address for the Ethernet module	_
General setting	Check of mail		Select whether or not to make inquiries to the incoming mail server regarding the receiving status	Check mark (Inquire)  No check mark (Do not inquire)
	At every		Set the time interval and unit for making inquiries to the incoming mail server	• 30 s to 24 h • h/min/s
Mail server name	Mail send setting	SMTP server name	Set the send mail server name	_
		Input format	Select the input format of the send mail server's IP address	Decimal     Hexadecimal
		IP address	Set the IP address of send mail server	00000001н to FFFFFFEн
	Mail receive setting	POP server name	Set the receive mail server name	_
		Input format	Select the input format of the receive mail server's IP address	Decimal     Hexadecimal
		IP address	Set the IP address of the receive mail server	00000001н to FFFFFFEн

2 - 12 2 - 12

#### (a) General settings

Designate the mail setting values that have been registered with the Internet service provider of the local station's Ethernet module or the mail registration information designated by the system administrator.

#### 1) Password:

Designate the mail password of the local station's Ethernet module.

#### 2) Mail address:

Designate the mail address of the local station's Ethernet module.

#### 3) Check receive mails:

Select whether or not to check if receive mails have arrived and set the checking time interval when incoming mails are checked.

When receive mail check is designated, set the time interval for inquiring the mail server whether or not there are mails addressed to the user.

The following table shows each setting range of the inquiry time intervals for checking receive mails. (30 s to 24 h)

Time units	Setting range (default: 5 min)	
h	1 to 24	
min	1 to 1440	
S	30 to 3600	

#### POINT

If the inquiry time interval from the PLC or other module to the server is short because of the POP3 server specifications, access may be restricted (lock status) on the server side.

Check the POP3 server specifications, and set the inquiry time interval accordingly. (It is recommended to set the setting value of the inquiry time interval to the default (5 minutes) or more.)

#### (b) Mail server name

Set the Internet service provider and the domain name or IP addresses of the mail servers designated by the system administrator, used by the local station's Ethernet module.

- 1) Designate the domain name of the mail server.
- 2) Select the input format (decimal/hexadecimal) of the IP addresses.
- 3) Set the IP address of the outgoing mail server (SMTP).
- 4) Set the IP address of the incoming mail server (POP3).

#### POINT

- The SMTP server delivers (transfers) e-mails between mail servers.
- The POP3 server transfers received e-mails addressed to users to the corresponding users.
- The mail server names must be designated to use the e-mail function. (See POINT of (1).)

2 - 13 2 - 13

#### (3) Send mail address setting

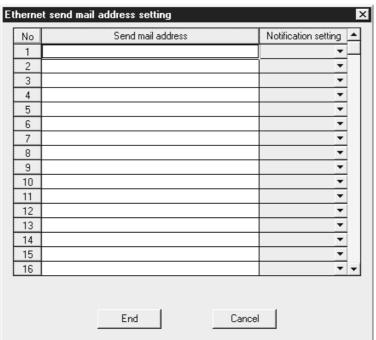
[Purpose of setting]

Register the e-mail address of the external devices where e-mail is to be sent.

[Start procedure]

[E-mail setting] → Send e-mail address setting

[Setting screen]



#### [Setting item]

Item name	Description of setting	Setting range/Selections
Send mail address	Set the mail address of the transmission destination	_
Notification setting	Select whether or not to set news	Execute news     No execute

#### (a) Send mail address

- Designate the mail addresses of a maximum of 16 external devices to which mails are sent from the local station's Ethernet module. (Only one e-mail address can be specified for each area.)
- In the send e-mail address setting, sequentially set up e-mail addresses starting from No. 1.
  To delete an e-mail address with a mid-setting number, specify dummy e-mail addresses before that address. (If it is preceded by any empty e-mail address areas, subsequent setting numbers and areas will
  - move forward to fill in any empty numbers and areas after each setting, so the setting numbers will change.)
    When sending (MSEND instruction) e-mail by the PLC CPU, specify
- these setting numbers (1 through 16) in the control data.
- (b) Notification setting (News designation)

Designate whether or not to send the news information set with the CPU monitoring function.

Item	Explanation	
Notification setting	Execute news	
Notification setting	No execute	

<sup>\*</sup> For more details on the notification settings, see Section 2.9.

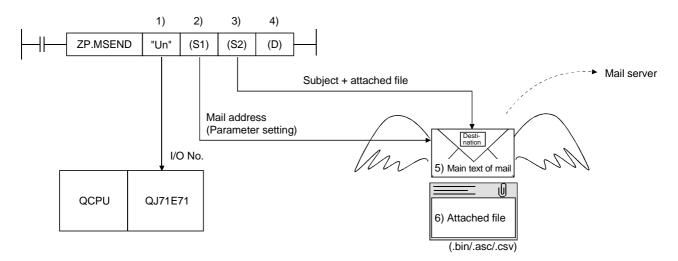
2 - 14 2 - 14

#### 2.7 Sending/Receiving E-mail (Attached Files) by the PLC CPU

This section explains how to send and receive attached files of e-mail using the dedicated instructions (MSEND/MRECV) available for the Ethernet module.

#### 2.7.1 When sending data as an attached file

The following explains the MSEND instruction and program for sending e-mail. The following illustration shows how the MSEND instruction is used to store data in an attached file and send it to an external device.



- 1) I/O number of the Ethernet module
- Control data (such as send mail address)
   This indicates the mail address of the send destination device set on the send mail address settings screen.
- 3) Send mail (subject + attached file) Subject consists of the send destination number and the character data designated by the sequence program. (It is not converted to ASCII format.)
  - \* The Subject should be designated in the sequence program in ASCII characters.
- 4) Complete bit
- 5) Main text of mail

There is no data for the main text of mail.

- \* The send data is included in the attached file.
- 6) Attached file

This indicates the device data designated by the MSEND instruction.

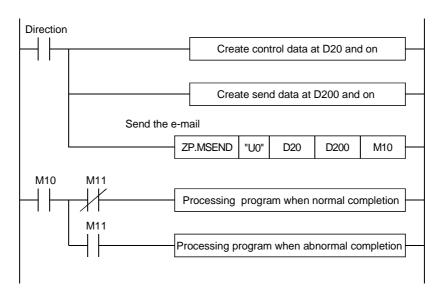
The attached file is sent in either one of binary format, ASCII format or CSV format. The transmission format for attached file is designated in the control data of the MSEND instruction.

(See (3) \*1.)

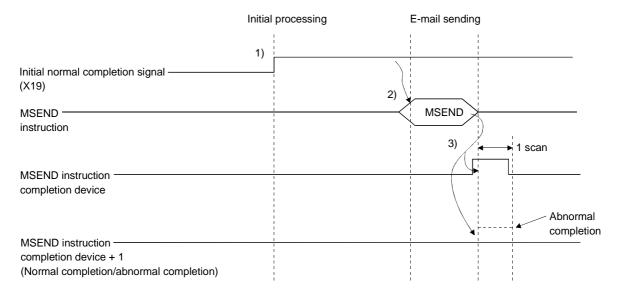
2 - 15 2 - 15

## (1) Send using the sequence program

The following explains how an e-mail is sent by the sequence program. See Chapter 6 MSEND for detail.



## (2) Execution timing of the instruction



- Start the local station PLC.
   The parameters for the e-mail function are stored in the Ethernet module.
- Execute the MSEND instruction.
   The e-mail designated with the MSEND instruction is sent to the mail server.
- 3) When the e-mail sending to the send mail server is completed, the MSEND instruction completion device turns on.
  - When the completion device + 1 (abnormal completion signal) turns on, the error code is stored in the control data completion status ((S1)+1).
  - \* For details on the causes of errors, see "Troubleshooting" in the Q Corresponding Ethernet Interface Module User's Manual (Basic).

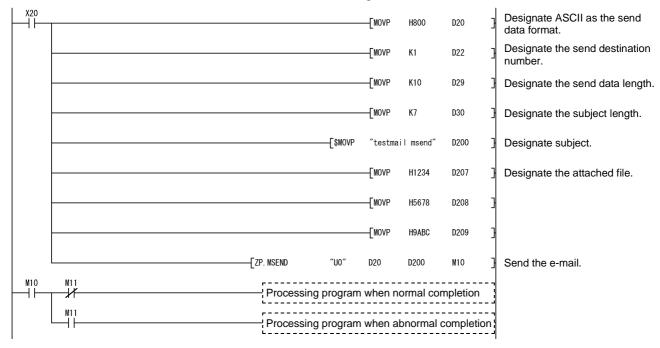
2 - 16 2 - 16

## (3) Sample program

The following shows a sample program for sending e-mails by the PLC CPU. Perform e-mail send processing using the send command (X20).

The contents of the send data are shown in (4).

## When I/O signals of the Ethernet module are X/Y00 to X/Y1F.

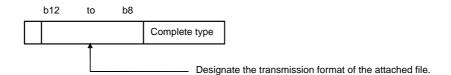


# REMARK

When an error occurs while sending e-mail from the sending mail server to an external device, an error code is stored in the receiving error log area.

2 - 17 2 - 17

- \*1 The following shows the transmission format of the attached file designated in the control data of the MSEND instruction.
  - \* For more details on the binary format/ASCII format/CSV format designation, see the MSEND Instruction in Chapter 6, "Dedicated Instructions."



	_	s for de transm b10	-	ing the format	Format set	Applicable station	Description of processing
0	0	0	0	0	Binary	Ethernet module	Sends the attached file in binary format.  (* * *.bin)
0	1	0	0	0	ASCII	PC/UNIX	Sends the attached file in ASCII format.  The Ethernet module converts the attached file from binary to ASCII. (* * * .asc)
0	1	0	0	1	CSV	PC/UNIX	Sends the attached file in CSV format.  The Ethernet module converts the attached file from binary to CSV. (* * * .csv)

- (a) Designate binary format when communicating between Ethernet modules.
   The attached file of the MSEND instruction will be sent as is.
   The name of the attached file is mmddhhss.bin (system date.bin).
   mm: Month dd: Date hh: Hour ss: minute
- (b) Designate either binary format, ASCII format or CSV format when a PC/UNIX receives e-mail sent from an Ethernet module. The attached file of the MSEND instruction will be sent in the designated format.
  - When binary format is designated The name of the attached file is mmddhhss.bin (system date.bin). mm: month dd: day hh: hour ss: minute
  - When ASCII format is designated The name of the attached file is mmddhhss.asc (system date.asc). mm: month dd: day hh: hour ss: minute
  - 3) When CSV format is designated The name of the attached file is mmddhhss.csv (system date.csv). mm: month dd: day hh: hour ss: minute
    - \* For details on how to receive e-mails, see (4) on page 2-17.
    - \* The system date for the file name is the data managed by the PLC of the station in which the Ethernet module is installed.

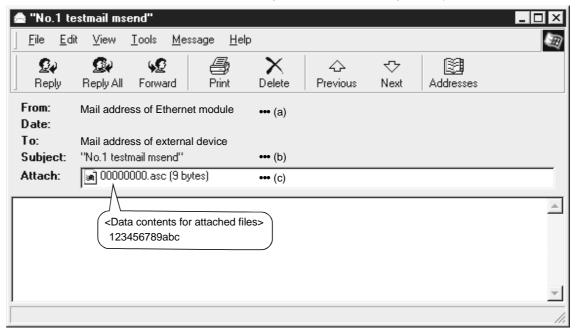
2 - 18 2 - 18

## (4) Receiving by a personal computer

The following explains how a PC/UNIX receives e-mails sent from the Ethernet module.

After setting an environment for using the Internet with application software that processes e-mails, e-mails can be received on a receive message screen as shown below.

(Example) The following shows an example of the reception of e-mail sent using the MSEND instruction (see (3)). (The screen display shows is that of Microsoft<sup>®</sup> Corporation's Outlook Express 5.)



(a) FromDisplays the mail address of the Ethernet module.

# REMARK

By entering the mail addresses of the send destination devices in the address book, the registered names (display names) can be displayed and it makes the management easier.

#### (b) Subject

This indicates the transmission destination No. (\*1) and the Subject written by a sequence program.

\*1 The Ethernet module automatically adds this number sequentially, starting from 1.

(After the maximum number (4294967296) is reached, the number starts again from 0.)

#### (c) Attached file

This indicates the name of the attached file sent by the Ethernet module.

#### POINT

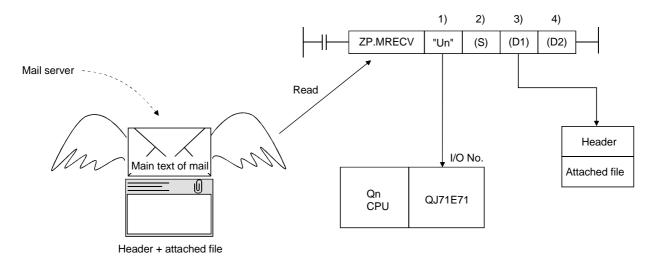
Data in the attached file in CSV format can be read in cell units in Excel, etc., for each 1 word of data.

2 - 19 2 - 19

## 2.7.2 When receiving data in the attached file

This section explains the MRECV instruction and a program to receive e-mails sent from external devices.

The MRECV instruction reads the attached file received.



- 1) I/O number of the Ethernet module
- 2) Control data (such as mail No. to be read)
- 3) Storage device of header + attached file
- 4) Complete bit
- \* Receive mail is temporarily stored in the buffer memory shown below.

Address (hexadecimal)	Item	Description	Remarks
2680н	Received e-mail size	Indicates the size of received e-mail (header + attached file) data.	
2681н	Header size	Indicates the size of the header data.	_
2682н	Mail information	(* <sup>1</sup> )	
2683н	Head address of attached file	Indicates the head address where the attached file data information is stored.	
2684н	Head address of header	Indicates the head address where the header information is stored.	
2685H	From head address	Indicates the head address of this data stored in the header information.	( * <sup>2</sup> )
2686н	Date head address	Indicates the head address of this data stored in the header information.	(*)
2687н	Subject head address	Indicates the head address of this data stored in the header information.	
2688н	Attached file name head address	Indicates the head address of this data stored in the header information.	
2689н	Message ID head address	Indicates the head address of this data stored in the header information.	
268A H	System area	_	
00000000	Header information (maximum of 373 words)	Indicates the content of the header designation items above.	
268Вн to 3FFFн	Attached file (maximum of 6144 words)	Indicates the contents of the attached file data.	
4000н	System area	_	

2 - 20 2 - 20

\*1 In the mail information storage area, the following information related to the receive mail is stored in the corresponding bits.

Mail information storage area address 2682H (9858)

b15	b14 to b5	b4	b3	b2	b1	b0	
7)	6)	5)	4)	3)	2)	1)	I

- 1) Indicates whether the information (maximum of 128 words) in the From head address storage area is valid (1) or invalid (0).
- 2) Indicates whether the information (maximum of 4 words) in the Date head address storage area is valid (1) or invalid (0).
- 3) Indicates whether the information (maximum of 64 words) in the Subject head address storage area is valid (1) or invalid (0).
- 4) Indicates whether or not there is an attached file Yes (1) or No (0). For "Yes", it indicates that the information (maximum of 12 words) stored at addresses starting from the Attached file name head address is valid.
- 5) Indicates whether or not there is information in the Message ID head address storage area Yes (1) or No (0).
- 6) Indicates the system information.
- 7) Indicates whether the receive mail that has not been read to the PLC CPU is stored in the Ethernet module Yes (1) or No (0).
- \*2 The value stored in each head address shown in the table indicates the offset address (0н to nн) from the head address of the buffer memory in which the applicable address is stored (address: 268Вн to 3FFFн).

#### **POINT**

(1) The Ethernet module checks whether or not there are any incoming mails addressed to the local station in the mail server at the time interval set in the inquiry interval in the "Network Parameter Ethernet e-mail setting" screen of GX Developer.

If there are incoming mails addressed to the local station, the reception information is stored in the following areas of the buffer memory.

- Bit 15 is turned on in the mail information storage area (see \*1 above).
- The number of receive mails on the mail server is stored in the receive mail count storage area (address 5870H).
  - \* When more than one receive mails are stored on the mail server, the receive mail information can be stored in the buffer memory in the same way as described above by designating "Inquire" in the MRECV instruction's control data item.

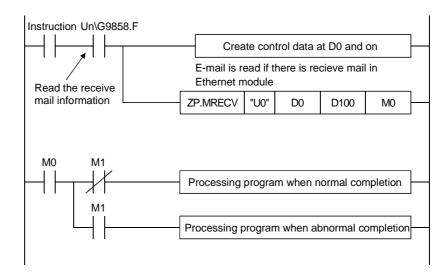
Receive mails can successively be read based on this stored information.

- (2) Read receive mails stored on the mail server using the MRECV instruction. Receive mails will accumulate on the mail server if the MRECV instruction is not executed.
- (3) After executing the MRECV instruction, e-mails that have been read are deleted from the mail server.
  - (Receive mails read will not remain on the mail server.)
- (4) If the Ethernet module has received e-mail longer than the reception data length specified with the MRECV instruction, it stores the data equivalent to the reception data length and ignores the remaining data.

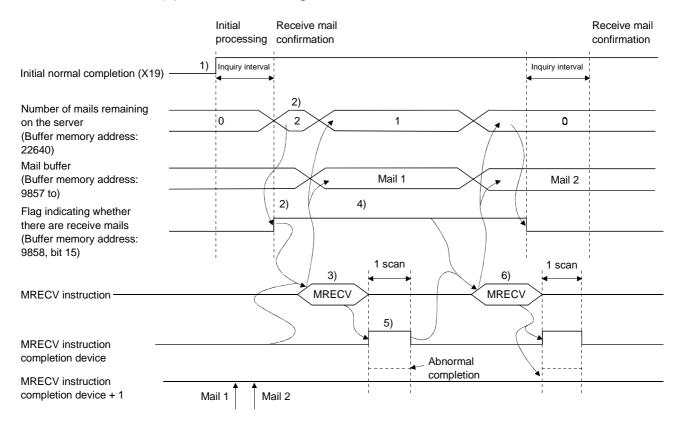
2 - 21 2 - 21

## (1) Reception using the sequence program

The following explains the designation method in a sequence program. For details, see Chapter 6, "MRECV".



## (2) Execution timing of the instruction



- Start up the local station PLC.
   The parameters for the e-mail function are stored in the Ethernet module.
- Check whether or not any received e-mails are stored on the mail server.
   If any receive mail has been stored, the receive mail information is stored in the buffer memory.
- 3) Execute the MRECV instruction.
  - Read e-mails from the server.
  - \* E-mails that have been read will not remain on the mail server.
- 4) The flag indicating whether or not there is a receive mail stays on by designating "Inquire" with MRECV instruction's control data item.
- 5) When reading e-mails is completed, the MRECV instruction completion device turns on.
  - When the completion device + 1 (abnormal completion signal) turns on, the error code is stored in the control data completion status ((S)+1).
  - \* For details on the causes of errors, see "Troubleshooting" in the Q Corresponding Ethernet Interface Module User's Manual (Basic).
- Execute the MRECV instruction.
   Continue to read e-mails remaining on the mail server.

#### **POINT**

- (1) Reading receive mails to the Ethernet module
  - The Ethernet module automatically checks the mail server to see whether or not there are any receive mails at the inquiry interval set with GX Developer. If there are any receive mails addressed to the local station, the reception information is stored in the buffer memory; the MRECV instruction should be executed based on this information.
- (2) When there are two or more receive mails on the mail server By designating "Inquire" in the MRECV instruction's control data, the Ethernet module also reads the information of the remaining receive mails on the mail server and stores it in the buffer memory when the MRECV instruction is executed.

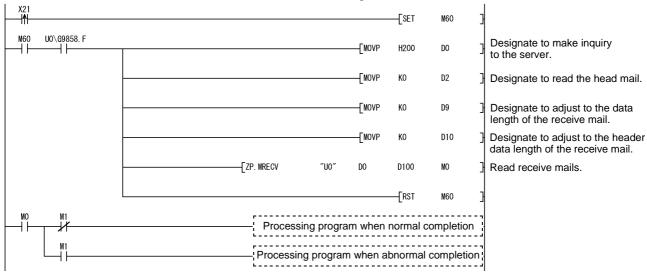
Continue to execute the MRECV instruction based on this information.

2 - 23 2 - 23

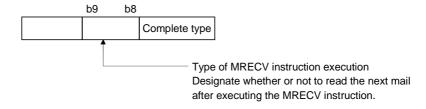
## (3) Sample program

The following is a sample program for receiving e-mail by a PLC CPU. It performs reception processing of e-mail using the receive command (X21).





\* The following explains the types of execution that can be designated in the MRECV instruction's control data. For more details on how to designate the execution types, see Section 6.2 "MRECV Instruction".



designa	value for ating the execution b8	Setting type	Description of processing	Merit	Demerit
0	0	Do not inquire  * Do not read	executed after the time set with a	Inquiries to the mail server can be less frequent.	The next receive mail cannot be read immediately. Mails tend to accumulate on the mail server.
1	0	Inquire * Read	· ·	Mails received by the mail server can be read in succession.	Inquiries to the mail server become more frequent.  More processing in the module affects other internal processing.

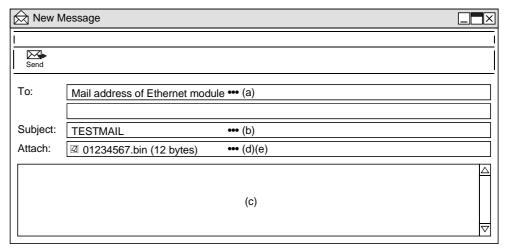
## (4) Sending from a personal computer

This section explains how to send e-mails from a PC/UNIX to the Ethernet module.

Once an environment that is capable of using the Internet through an application program that handles e-mail is set up, e-mail can be created and sent on the New Message screen.

#### POINT

As for an e-mail program that sends e-mail to the Ethernet module, use a program that can designate the encoding method (Base 64/7 bits/8 bits/Quoted Printable) of attached files.



(a) To

Designate the mail address of the Ethernet module.

(b) Subject

Designate the subject of the e-mail to be sent to the Ethernet module in ASCII format.

(c) Main text

Do not designate data (the Ethernet module ignores it.)

(d) Attach file

Data can be sent as an attached file.

Send the attached file data as binary data.

- \* The Ethernet module does not convert the received attached file data from ASCII to binary.
- (e) Attached file name

Designate the name of the attached file using alphanumeric characters. (It is recommended to use the name within eight characters.) Designate either ".bin" or ".asc" for the attached file extension. The stored data will be received as binary data.

# REMARK

Designate a single attached file when sending e-mail to the Ethernet module. If more than one files are attached, the destination Ethernet module will store only the first file and ignore the rest of the attached files.

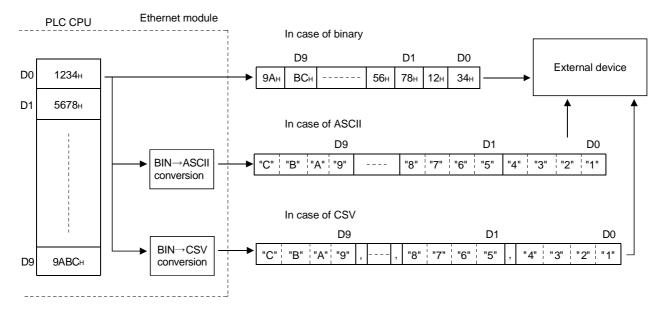
#### 2.7.3 Contents of the attached files

The following explains the contents of the attached file data.

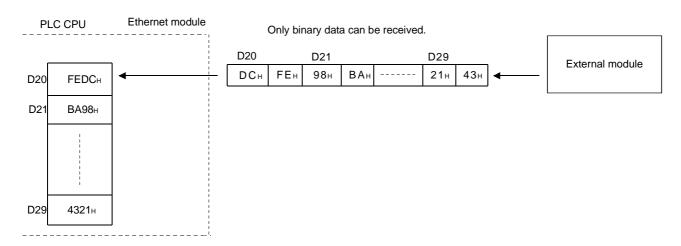
The data format of the attached file is ASCII code (ASCII format, CSV format) or binary code (binary format).

The following example shows the transmission contents for each data format (binary/ASCII/CSV) when the Ethernet module sends the data register value as an attached file.

## (1) When sending from the Ethernet module



#### (2) When receiving by the Ethernet module



# REMARK

(1) For details on the order of data items when sending/receiving bit device data, see the figure shown in Section 2.9.2.

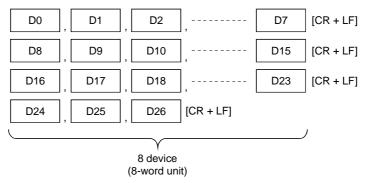
## (2) Data configuration in CSV format

Data in CSV format can be used as control data for the cell units in Excel, etc. Data in CSV format handled by the Ethernet module is the data expressed as follows

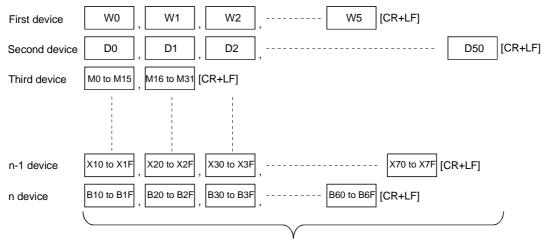
- 1 word (16 bits) binary data is converted to four digit ASCII code when expressed as a hexadecimal. (4 bytes of ASCII code)
- When handling multiple word data, insert comma data between each word (4 bytes of ASCII code).

Data designated by the MSEND instruction or data subject to the news function is sent in the following arrangement.

- (a) Arrangement of data sent by the MSEND instruction
  - In addition to the data conversion and insertion described above, CR (соde: ОDн) and LF (соde: ОАн) are inserted for each 8 words of data.
  - 2) The arrangement of data sent in CSV format is shown below.



- (b) Arrangement of data sent using the news function
  - In addition to the data conversion and insertion of comma data described above, CR (code: 0DH) and LF (code: 0AH) are inserted for each setting device range.
  - A maximum of 16 types of device ranges can be set for news data.\* See Section 2.9 for details.
  - 3) The arrangement of data sent in CSV format is shown below.



Data section can have a maximum of 1920 bytes (total points for the device).

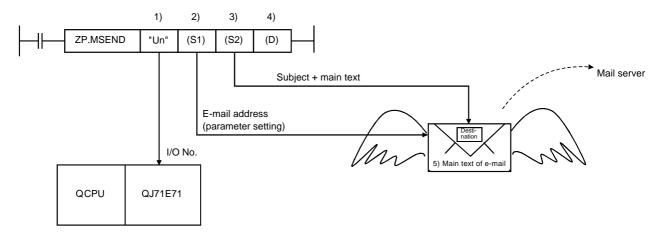
2 - 27 2 - 27

## 2.8 Sending E-mail (Main Text) by the PLC CPU

This section explains how to send the main text of e-mail using the dedicated MSEND instruction available for the Ethernet module.

## 2.8.1 When sending data as main text of e-mail

The following explains the MSEND instruction and program for sending e-mail. The following illustration shows how the MSEND instruction is used to store data in the main text of e-mail and send it to an external device.



- 1) I/O number of the Ethernet module
- Control data (such as sending e-mail address)
   This indicates the e-mail address of the transmission destination device set on the Send E-mail Address Settings screen.
- 3) Sending e-mail (Subject + main text)

The Subject consists of the transmission destination number and the character data specified by a sequence program. (It is not converted to ASCII format.)

- \* Designate text data in ASCII characters in sequence programs.
- 4) Completion bit
- 5) Main text of e-mail

This indicates the character string designated by the MSEND instruction.

It is not converted to ASCII format by the Ethernet module.

- \* Designate the main text in ASCII characters in sequence programs.
- The following binary code data is processed as control codes:
   0D0Aн: Line feed code CR+LF
   00н: End of main text
- \* It is recommended to use 78 characters or less data when writing each line of the main text (sending data). (Be sure to add a line feed code CR+LF (0D0AH) at the end of the main text lines.)

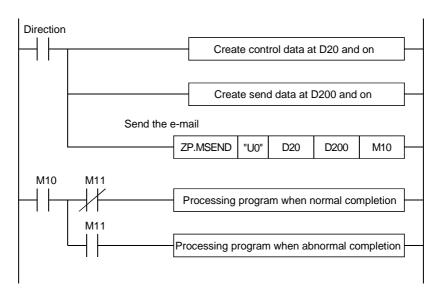
#### 6) Attached file

No attached file can be sent when sending data as the main text of email.

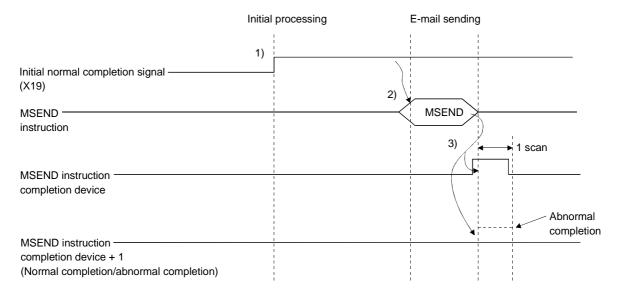
2 - 28 2 - 28

## (1) Send using the sequence program

The following explains how an e-mail is sent by the sequence program. See Chapter 6 MSEND for detail.



## (2) Execution timing of the instruction

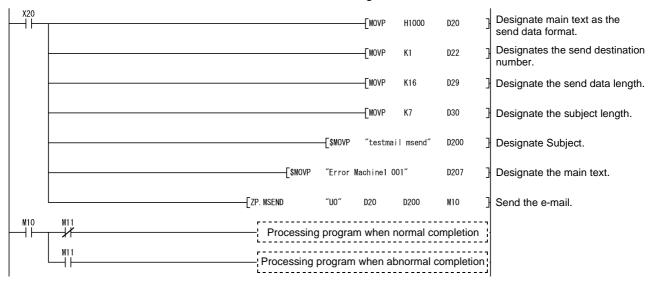


- Start the local station PLC.
   The parameters for the e-mail function are stored in the Ethernet module.
- Execute the MSEND instruction.
   The e-mail designated with the MSEND instruction is sent to the mail server.
- When the e-mail sending to the send mail server is completed, the MSEND instruction completion device turns on.
  - When the completion device + 1 (abnormal completion signal) turns on, the error code is stored in the control data completion status ((S1)+1).
  - \* For details on the causes of errors, see "Troubleshooting" in the Q Corresponding Ethernet Interface Module User's Manual (Basic).

## (3) Sample program

The following shows a sample program for sending e-mail by the PLC CPU. Perform e-mail transmission processing the send command (X20). The contents of the send data are shown in (4).

#### When I/O signals of the Ethernet module are X/Y00 to X/Y1F



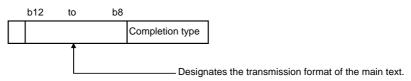
# REMARK

When an error occurs while sending e-mail from the sending mail server to an external device, an error code is stored in the receiving error log area.

\*1 The following shows the transmission format of the main text designated in the control data of the MSEND instruction.

If data is sent as the main text of e-mail, the Ethernet module does not convert the transmission format.

\* Designate the main text data in ASCII characters in sequence programs.



Setting	Setting values for designating the main text data transmission format			ain text	Format set Applicable station	Description of processing	
b12	b11	b10	b9	b8		Station	
1	0	0	0	0	No conversion	PC/UNIX/ portable terminal	Send the main text data.  The Ethernet module does not convert the transmission format.  * Designate the main text data in ASCII characters in sequence programs.

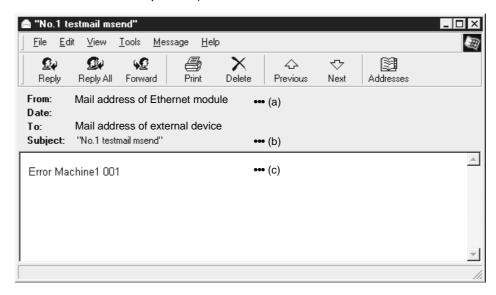
## (4) Receiving by the a personal computer

The following explains how a PC/UNIX/portable terminal receives e-mail sent from the Ethernet module.

After setting an environment for using the Internet with application software that processes e-mails, e-mails can be received on a receive message screen as shown below.

(Example) The following shows an example of the reception of e-mail sent using the MSEND instruction (see (3)).

(The screen display shows is that of Microsoft<sup>®</sup> Corporation's Outlook Express 5.)



#### (a) From

Displays the e-mail address of the Ethernet module.

# REMARK

By entering the mail addresses of the send destination devices in the address book, the registered names (display names) can be displayed and it makes the management easier.

#### (b) Subject

This indicates the transmission destination No. (\*1) and the Subject written by a sequence program.

\*1 The Ethernet module automatically adds this number sequentially, starting from 1.

(After the maximum number (4294967296) is reached, the number starts again from 0.)

#### (c) Main text of e-mail

This indicates the main text of e-mail sent by the Ethernet module.

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## 2.9 Sending E-mails Using the PLC CPU Monitoring Function

When the monitoring information read from the QCPU matches with the news conditions set by the user, the Ethernet module sends an e-mail to the external device.

## 2.9.1 News setting

#### [Purpose of setting]

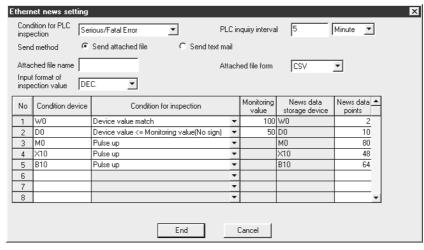
The monitoring conditions (notification conditions) of the PLC CPU can be set on the News setting screen of GX Developer.

The monitoring function of the PLC CPU can be used according to this setting. Both CPU status monitoring and device monitoring can be designated as notification conditions.

[Start procedure]

[E-mail setting] → News setting

#### [Setting screen]



# News settings

		Notification	n condition	
Item name	Description of setting	CPU status monitoring (米1)	Device monitoring	Setting range/option
Condition for PLC inspection	Select the monitoring condition for the CPU	0	×	<ul> <li>No setting</li> <li>Normal STOP</li> <li>Module error/Module system error (Serious/Fatal Error)</li> <li>Module warning STOP (Moderate error STOP)</li> <li>Normal RUN</li> <li>Module warning RUN (Moderate Error STOP)</li> <li>PAUSE</li> </ul>
Send method	Select the data send method.	×	0	Send attached file     Send text mail
Attached file form	Set the data format for the attached file	×	0	Binary format     ASCII format     CSV format
Attached file name	Set the attached file name	×	0	_
PLC inquiry interval	Set time interval between reading the CPU status and device values and the units (h/min/s)	0	0	• 30 s to 24 h
Input format of inspection value	Select the input format of the monitoring data	×	0	Decimal/hexadecimal
Condition device	Set the condition device	×	0	_
Condition for inspection	Set the monitoring condition	×	0	
Monitoring value	Set the monitoring value	×	0	_
Notification data storage device	Notification data storage device value	×	0	_
Notif. data points	Set the notification data points	×	0	_

O: Setting item  $\times$ : Setting not required

## (1) Condition for PLC inspection

Condition for PLC inspection	Description
Normal STOP	Sends an e-mail when the PLC CPU is placed in the STOP status normally.
Module error Module system error	Sends an e-mail when an error that stops the CPU execution has occurred.
Module warning STOP	Sends an e-mail when the PLC CPU is stopped by an external operation, etc. while an error that allows to continue the CPU execution has occurred.
Normal RUN	Sends an e-mail when the PLC CPU is placed in the RUN status normally.
Module warning RUN	Sends an e-mail when an error that does not allow to continue the CPU execution has occurred while the PLC CPU is in the RUN status. (The PLC CPU is in operation.)
PAUSE	Sends an e-mail when the PLC CPU is placed in the PAUSE status.

## (2) Send method

Select the send method of the device monitoring results.

Item	Explanation
Send attached file	Sends data as an attached file in the file format designated in (3).
Send text mail	Sends data as the main text of e-mail in ASCII code format.
Send text mail	It is not necessary to designate items (3) and (4) when this setting is used.

<sup>\*1</sup> When an e-mail is sent with the PLC status inspection, only subject (PLC CPU status is stored) is sent.

## (3) Attached file format

Item	Explanation
	Sends the attached file in binary format.
Pinary format	The Ethernet module sends the attached file as they are with the code
Binary format	currently in use.
	(Binary to ASCII conversion is not performed.)
A C C II fa a t	Sends the attached file in ASCII format.
ASCII format	The Ethernet module converts the attached file from binary to ASCII.
CCV/ forms of	Sends the attached file in CSV format.
CSV format	The Ethernet module converts the attached file from binary to CSV.

#### (4) Attached file name

Designate the name of an attached file. If a file name is not designated, the Ethernet module automatically names it and sends the file named mmddhhss (month, date, hour, minute) (same as for e-mail sending).

## (5) PLC inquiry interval

Designate the interval for the Ethernet module to read the CPU status and device values from the PLC CPU.

The user can designate any inquiry time interval (time) within the ranges shown below.

Time unit	Setting range (default: 5 min)
h	1 to 24
min	1 to 1440
s	30 to 3600

#### (6) Input format of inspection value

Select the input format (decimal/hexadecimal) of the monitoring value.

#### (7) Condition device

Designate the device to be monitored.

#### **POINT**

- (1) A maximum of 16 devices can be monitored.
- (2) It is possible to designate devices that can be accessed for communication using the MC protocol directly as condition devices (see the Reference Manual). In this case, Timer, Retentive timer and Counter should be designated by T, ST,

C.

- The following devices cannot be designated:
- Step relay (S)
- Direct input (DX)
- Direct output (DY)
- Index qualification
- Indirect designation
- (3) After completion of the news setting, the system will rearrange the condition devices in the order; word devices first and then bit devices. Display the news setting screen again to confirm the condition device settings.

## (8) Condition for inspection

Designate the news conditions to monitor the devices of the PLC CPU. The following table lists the comparison conditions for the designated device.

Condition of co	mparison	News condition		
D: 1	Rise	When switching from off to on is detected.		
Bit device	Drop	When switching from on to off is detected.		
	No condition setting	For each monitoring.		
	Device value = monitoring value	When the monitoring device value and the value set by the user are the same.		
	Device value ≠ monitoring value	When the monitoring device value and the value set by the user are different.		
	Device value ≤ monitoring value (unsigned)	When the monitoring device value is equal to or less than the value set by the user.		
	Device value < monitoring value (unsigned)	When the monitoring device value is less than the value set by the user		
Word device	Device value ≧ monitoring value (unsigned)	When the monitoring device value is equal to or greater than the value set by the user.		
	Device value > monitoring value (unsigned)	When the monitoring device value is greater than the value set by the user.		
	Device value ≤ monitoring value (signed)	When the monitoring device value is equal to or less than the value set by the user.		
	Device value < monitoring value (signed)	When the monitoring device value is less than the value set by the user.		
	Device value ≥ monitoring value (signed)	When the monitoring device value is equal to or greater than the value set by the user.		
	Device value > monitoring value (signed)	When the monitoring device value is greater than the value set by the user.		

## (9) Monitoring value

Designate the comparison value of the condition of comparison given in (8) above.

#### (10) Notification data storage device (News data storage device)

The condition device that stores the news data is set when the news condition is satisfied.

When the CPU monitoring condition shown in (1) is "No setting", GX Developer automatically sets the condition device, so the user does not need to set it.

## (11) Notif. data points (News points)

Designate how many devices should be read (number of points read) from the devices designated in (10) above.

(a) The number of device points that can be sent at a time is calculated as follows.

Word device points  $\times$  2 + bit device points  $\div$  8 (round up)  $\leq$  1920

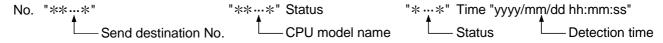
- 1) Designate the settings so that the total number of points satisfies the equation above when multiple news conditions are satisfied when monitoring multiple condition devices.
- 2) When multiple bit devices are to be designated, be aware of following:
  - One device occupies 16 device points.

## 2.9.2 Receiving a news e-mail

The designated external device side can open the news e-mail from the Ethernet module in the same way as opening a mail received from the PLC CPU.

## (1) When monitoring the CPU status

- (a) When the result of the CPU status monitoring matches the monitoring condition, the Subject will be sent. The attached file or main text will not be sent.
- (b) The following shows the contents for the Subject sent.

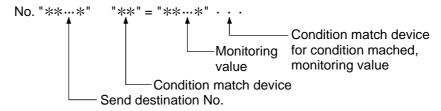


## (Send contents of the parts for the status)

CF	U module status	Send contents
D : DIN	At normal	"Status : RUN"
During RUN	At module warning occurrence	"Status: RUN (Warning)" or "Status: RUN (Slight Abnormal)"
	At normal	"Status: STOP"
D. min a OTOD	At module warning occurrence	"Status : STOP (Warning)" or "Status : STOP (Slight Abnormal)"
During STOP	During the module error or module system error	"Status : STOP (Serious/Fatal Error)" or "Status : STOP (Abnormal)"
During PAUSE	_	"Status : PAUSE"

## (2) When monitoring a device

- (a) Once any of the results of the device monitoring matches the monitoring condition among the devices having the conditions designated on the "Ethernet news setting" screen, the Subject and attached file, or the Subject and main text will be sent.
- (b) The following shows the contents for the Subject sent.



(C) All device values for the number of registered points designated on the "Ethernet news setting" screen are recorded in the attached file or main text.

The size of the data recorded in the attached file or main text is calculated as follows:

Registered points (number of bits)  $\div$  16  $\times$  2 bytes (Round up to a whole number)

Information of word devices:

Registered points (number of devices) × 2 bytes

2 - 36 2 - 36

- (d) The contents of the data recorded are as follows.
  - 1) When sending data as an attached file
    - If the data format is binary, values are recorded from the lower byte
       (L) side.
    - If the data format is ASCII, target values are converted to 4-digit hexadecimal ASCII codes and recorded from the higher byte (H) side of the values.
    - If the data format is CSV, target values are converted to 4-digit hexadecimal ASCII codes and recorded from the higher byte (H) side of the values.

If multiple word data is to be processed, insert a comma between each word (4-byte ASCII code) data.

Insert CR (Code: 0DH) and LF (Code: 0AH) every each setting device range.

(Example) In case of M15 to M0 = 0001  $\mu$ , M31 to M16 = 0002 $\mu$ , ..., W0 = 001A  $\mu$ , W1 = 002B  $\mu$ , ...

## For M15 to M0

M15	5 t	0	M12	2	to		М8		to		M4		to	1	MO
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1

#### For binary

```
Wo(L)Wo(H)W1(L)W1(H) D0(L)D0(H)D1(L)D1(H) - - - - - - D8(L)D8(H) D9(L)D9(H)

1A 00 2B 00 11 00 12 00 - 19 00 1A 00

M0 M8 M16 M24 - - - - - M72 X10X18 X20 - - X38 B10B18 - B40B48

01 00 02 00 03 00 04 00 05 00 60 00 61 00 62 00 30 00 - 33 00
```

#### For ASCII

```
        W0
        W1
        D0
        D1
        D2
        D3
        D4
        D5
        D6
        D7
        D8
        D9

        001A
        002B
        0011
        0012
        0013
        0014
        0015
        0016
        0017
        0018
        0019
        001A

        M0
        M16
        M32
        M48
        M64
        X10
        X20
        X30
        B10
        B20
        B30
        B40

        0001
        0002
        0003
        0004
        0005
        0060
        0061
        0062
        0030
        0031
        0032
        0033
```

## For CSV

```
W1
001A 002B [CR+LF]
   D1
         D2
              D3
                   D4 D5 D6 D7 D8
                                           D9
0011,0012,0013, 0014, 0015,0016,0017,0018, 0019, 001A [CR+LF]
         M32 M48 M64
0001,0002,0003,0004,0005 [CR+LF]
X10 X20
              [CR+LF]
0060 0061 0062
    B20 B30
              B40
0030,0031,0032, 0033 [CR+LF]
```

\* The spaces and lines between device numbers and device values are inserted for the purpose of explanation. They are not recorded in the attached file.

- 2) When sending data as main text
  - Target data values are converted to 4-digit hexadecimal ASCII codes and recorded from the higher byte (H) side of the values.
  - The device name and display device No. are recorded for each setting device.
  - If multiple word data is to be processed, insert a comma between each word (4-byte ASCII code) data.

Insert a CR (code: 0DH) and a LF (code: 0AH) for each setting device range or 8-word data.

(Example) In case of M15 to M0 = 0001H, M31 to M16 = 0002H, ..., W0 = 001AH, W1 = 002BH, ...

#### For M15 to M0

M15	5 t	0	M12	2	to		М8		to		M4		to	1	M0	
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	

#### For the main text of e-mail

```
W0-W1 [CR+LF]
001A,002B [CR+LF]

D0-D9 [CR+LF]
0011,0012,0013, 0014, 0015,0016,0017, 0018 [CR+LF]
0019, 001A [CR+LF]

M0-M79 [CR+LF]
0001,0002,0003,0004, 0005 [CR+LF]

X10-X3F [CR+LF]
0060,0061,0062 [CR+LF]

B10-B4F [CR+LF]
0030,0031,0032, 0033 [CR+LF]
```

\* The dotted boarder lines between device values in the above figure are inserted for the purpose of explanation. They are not recorded in the main text.

#### **POINT**

(1) When e-mail is sent after the result of the device monitoring and the monitoring condition match, the Subject and attached file, or the Subject and main text will be sent.

As a device monitoring result, the data that was read from the PLC CPU by the Ethernet module in order to determine whether or not the conditions match will be sent.

For details on the correspondence between the word device values and the data format of the attached file, see the figure in Section 2.7.3.

The main text will be sent after converting the data read into ASCII code data.

(2) When e-mail is sent after the result of the CPU status monitoring and the monitoring condition match, only the Subject will be sent. The attached file and main text will not be sent.

# 3 WHEN COMMUNICATING WITH MELSECNET/H, MELSECNET/10 RELAY

The Ethernet network system can be in the same class as the MELSECNET/H, MELSECNET/10 network system. External device or Ethernet module installed QCPU station can give access to the other stations via Ethernet networks and MELSECNET/H, MELSECNET/10 within the MELSECNET/H, MELSECNET/10 specification range.

In this chapter, the MELSECNET/H, MELSECNET/10 relay communication functions are described, to perform data communication with other station PLC CPUs via Ethernet module or MELSECNET/H, MELSECNET/10 from the QCPU at external device or Ethernet module installed QCPU station.

## 3.1 MELSECNET/H, MELSECNET/10 Relay Communication

The MELSECNET/H, MELSECNET/10 relay communication is a function to perform the following data communication to the other station PLC via Ethernet or MELSECNET/H, MELSECNET/10 from the external device or Ethernet module installed QCPU station.

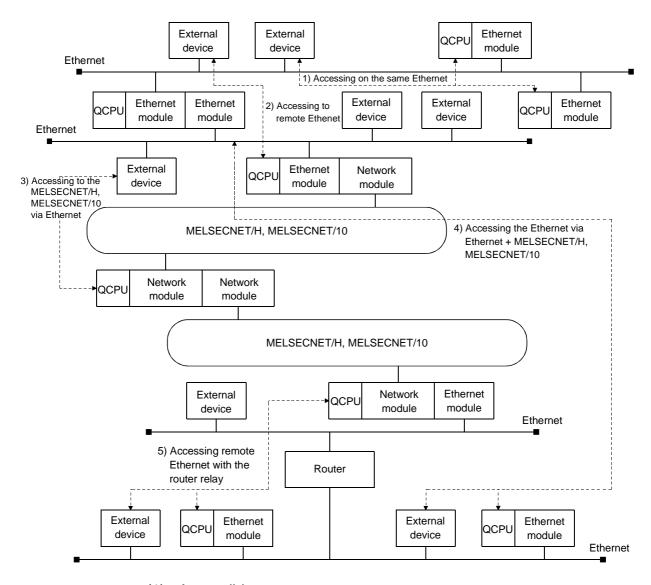
By setting the parameter described in Section 3.3, the other station access becomes possible with the MELSECNET/H, MELSECNET/10 relay communication function.

Function that can be used for communication	Communi When using this function	cation range When not using this function	Communication request source	Function reference section
Communication using the MC protocol	Describle to read/unite date	Only possible to read/write data from/to the PLCs of other	External device	Reference Manual
the data link	from/to other station's PLC, which is the access request destination, from an access source device via multiple MELSECNET/H, MELSECNET/10 and Ethernet network systems.	stations in the same Ethernet or MELSECNET/H, MELSECNET/10 network	Network module installed QCPU station	Chapter 4
Communication with other stations using		system as that of the station in which the Ethernet module is installed. (Example) Only access 1) shown in the diagram in Section 3.2.1 is possible.	GX Developer	GX Developer Manual

## 3.2 Remote Station PLC Accessible Range and Stations

The accessible range and the stations when performing the other station access via Ethernet module using the MELSECNET/H, MELSECNET/10 relay communication function is described.

## 3.2.1 Accessible range and stations



#### (1) Accessible range

- Routing via the Ethernet and MELSECNET/H, MELSECNET/10 network systems is allowed within the range of the MELSECNET/H, MELSECNET/10 specifications.
  - \* Accessing other station is possible between devices indicated by 1) to 5) in the figure on the previous page.
- 2) The only networks that can be routed are the MELSECNET/H, MELSECNET/10 and Ethernet.

# (2) Accessible stations (communication request destination stations) and relay stations (communication relay stations)

This relay communication function allows communication with PLCs of other stations if the communication destination PLCs (communication request destination stations) and all the relay stations to the communication destination stations (communication relay stations) are configured with the modules listed below.

(a) Accessible PLC modules (communication request destination stations: other stations)

#### 1) PLC CPU modules

		Model name						
	PLC CPU	-						
QCPU (Q mode)	Basic model	Q00JCPU, Q00CPU, Q01CPU						
	High performance model	Q02CPU, Q02HCPU, Q06HCPU, Q12HCPU, Q25HCPU						
	Process CPU	Q12PHCPU, Q25PHCPU						
	Redundant CPU	Q12PRHCPU, Q25PRHCPU						
QnACPU	PLC CPU	Q2ACPU, Q2ACPU-S1, Q2ASCPU, Q2ASCPU-S1, Q2ASHCPU, Q2ASHCPU-S1, Q3ACPU, Q4ACPU						
	Redundant CPU	Q4ARCPU						
ACPU QCPU (A mode)		A1NCPU, A2NCPU, A2NCPU-S1, A3NCPU, A2ACPU, A2ACPU-S1, A3ACPU, A2UCPU, A2UCPU-S1, A3UCPU, A4UCPU, A1SCPU, A1SJCPU(-S3), A1SHCPU, A1SJHCPU, A2SCPU, A2SCPU, A2ASCPU-S1, A0J2HCPU, Q02CPU-A, Q02HCPU-A, Q06HCPU-A						

#### 2) Remote I/O station modules

	Model name
MELSECNET/H Remote I/O station	QJ72LP25-25, QJ72LP25GE, QJ72BR15
MELSECNET/10 Remote I/O station	AJ72QLP25, AJ72QBR15, A1SJ72QLP25, A1SJ72QBR15 AJ72LP25(G), AJ72BR15,

<sup>\*1</sup> It is possible to read from and write to the buffer memory of special function modules that are installed in MELSECNET/10 remote I/O stations.

## (b) Modules that can act as relays between networks (communication relay stations)

		Model name
MELSECNET/H		QJ71LP21, QJ71LP21-25, QJ71LP21S-25, QJ71LP21GE, QJ71BR11 (MELSECNET/H mode)
1451 050N5T/10		QJ71LP21, QJ71LP21-25, QJ71LP21S-25, QJ71LP21GE, QJ71BR11 (MELSECNET/10 mode)
MELSECNET/10		AJ71QLP21(S/G), AJ71QBR11, A1SJ71QLP21, A1SJ71QBR11
		AJ71LP21(G), AJ71LR21, AJ71BR11, A1SJ71LP21, A1SJ71BR11
		QJ71E71-100, QJ71E71-B5, QJ71E71-B2, QJ71E71
Ethernet	( * <sup>2</sup> )	AJ71QE71N-T, AJ71QE71N-B5, AJ71QE71N-B2, AJ71QE71N-B5T,
Luiemet	( )	A1SJ71QE71N-T, A1SJ71QE71N-B5, A1SJ71QE71N-B2, A1SJ71QE71N-B5T,
		AJ71QE71, AJ71QE71-B5, A1SJ71QE71-B2, A1SJ71QE71-B5

\*2 QnA series Ethernet interface modules can act as relays between networks if the function version is B or later. Verify the function version with the production date shown in the "Date

column of the rated plate", which is attached to the side of the module. (Manufactured date: Year (last two digits), Month (two digits), function version (one digit))

## 3.3 Settings for Accessing Other Stations

This section explains the parameters and setting items that need to be set with GX Developer to access other stations via the Ethernet using the MELSECNET/H, MELSECNET/10 relay communication function.

- (1) Network parameter, setting the number of MNET/10H Ethernet cards
  - 1) Network No., group number, station number (station No.), etc. for using the Ethernet module are set on this screen.
  - Make sure to set the values by seeing Section 4.6 of the User's Manual (Basic).
- (2) Setting the Ethernet Station No. <-> IP Information (setting the Ethernet MNET/10H routing information)
  - The Ethernet's routing method, correspondences of the Ethernet module's IP address and Network No./station number, etc. for using the MELSECNET/H, MELSECNET/10 relay communication function are set on this screen.
  - 2) Set these values by seeing Section 3.3.1.
- (3) Setting the MNET/10H Ethernet routing information (setting of routing parameters)
  - On this screen, the routing parameters between Ethernet modules for accessing other stations on other MELSECNET/H, MELSECNET/10 networks are set, in the same way as for the routing parameter settings of the MELSECNET/H, MELSECNET/10.
    - \* The Network No. and station number of the first communication relay station as seen from the local station are set.
  - 2) These settings are required for a station in which two or more Ethernet modules or MELSECNET/H, MELSECNET/10 network modules are installed.
  - 3) Set these values by seeing Section 3.3.3.

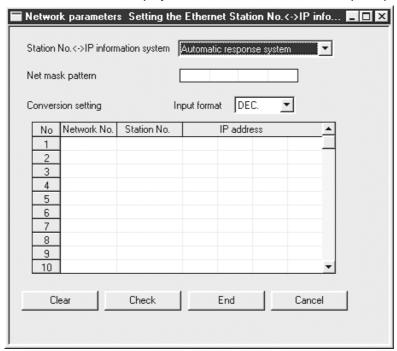
## 3.3.1 Setting the Station No. <-> IP information

The Station No. <-> IP information is used to obtain the IP address of the transmission destination station in order to send an access message to other station designated with the Network No. and station number, from one Ethernet module to the next Ethernet module.

This section explains the Station No. <-> IP information settings that are required to access other stations via the Ethernet module using the MELSECNET/H, MELSECNET/10 relay communication function.

Select [GX Developer] - [Network parameter] to start the [Network parameters Setting the Ethernet Station No. <-> IP information] screen.

For details on how to display this screen, see the GX Developer Operating Manual.



## Setting the Station No. <-> IP information

Item name	Description of setting	Setting range/option
Station No. <-> IP information system	Select the Station No. <-> IP information system (conversion method).	Automatic response system     IP address computation system     Table exchange system     Use-together system
Net mask pattern	<ul> <li>This setting is required when "IP address computation system" or "Use-together system" is selected as the conversion method.</li> <li>Set the mask value used in the logical product with the local station's IP address.</li> </ul>	C0000000н to FFFFFFFн
Input format	Select the input format of "Net mask pattern" and "IP address" .	Decimal     Hexadecimal
Network No.	<ul> <li>This setting is required when "Table computation system" or " Use-together system" is selected as the conversion method.</li> <li>Set the Network No.s of the communication request destination/source stations.</li> </ul>	1 to 239 (designate in decimal)
Station No.	<ul> <li>This setting is required when "Table computation system" or "Use-together system" is selected as the conversion method.</li> <li>Set the station number of the communication request destination/source stations.</li> </ul>	1 to 64 (designate in decimal)
IP address	<ul> <li>This setting is required when "Table computation system" or "Use-together system" is selected as the conversion method.</li> <li>Set the IP address of the communication request destination/source stations.</li> </ul>	Other than 00000000н and FFFFFFFн

- (1) Station No. <-> IP information system (conversion method) (address: 4H ... b7, b6)
  - (a) There are four kinds of Station No. <-> IP information methods as shown below.
  - (b) Select one of them according to Section 3.3.2 and make sure to set the values on this screen using the method selected. (The default conversion method is the Automatic response method.)

## Parameter settings requirement

Conversion method	Net mask pattern	Conversion setting
Automatic response system	×	×
IP address computation system	0	×
Table exchange system	×	0
Use-together system	0	0

O: Setting required X: Setting not required

- (2) Net mask pattern (address: 3A9н)
  - (a) Designate the mask value based on the guidelines given below. This pattern is used in a logical sum with the local station's IP address when calculating the IP address of the opposite device using the IP address computation system.
  - (b) When setting the sub-net mask, designate the target settings of the IP address class, network address, and sub-net address so that all bits are "1" in the mask pattern.
    - \* The mask pattern is designated with a decimal/hexadecimal value obtained by dividing the 32-bit mask value into 8-bit segments.
  - (c) When the sub-net mask is not designated, the mask pattern designation is not necessary.
    - \* When the mask pattern is not designated, the following mask value is used as the mask pattern according to the local station IP Address class.

Class	Mask value used
Class A	FF. 00. 00. 00H
Class B	FF. FF. 00. 00H
Class C	FF. FF. FF. 00H

- (3) Conversion setup (conversion information) (address: 229H to 3A8H)
  - (a) The conversion setting is required to obtain the IP address from the Network No. and station number using the table exchange system.
  - (b) If the local station is an Ethernet module and the next station to which the communication request /response message is passed to access other station is also an Ethernet module, designate the Network No., station number, and IP address of the next station's Ethernet module.
    - \* Designate the values set on "Network parameters, Setting the number of MNET/10H Ethernet cards" screen.
  - (c) Designate the Network No. in the range of 1 to 239 (1H to EFH) and the station number in the range of 1 to 64 (1H to 40H).

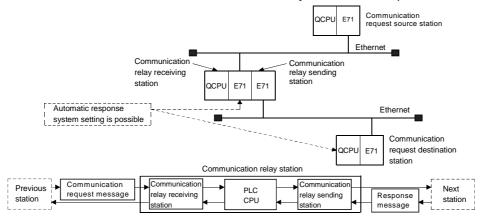
#### **POINT**

- (1) Communication between the Ethernet module and QCPU is performed according to the Network No., and communication between two Ethernet modules are performed according to the IP address and UDP port number. Thus, the Ethernet module must convert the data shown below: Network No. and station number of MELSECNET/H, MELSECNET/10 ↔ IP address and UDP port number of Ethernet.
- (2) The Station No. <-> IP information are required when accessing other stations via other Ethernet network systems and must be registered in all the QCPU stations in which the Ethernet modules are installed.
- (3) The Station No. <-> IP information should be set on the "Setting the Station No. <-> IP information" screen and written in the PLC CPUs of the applicable stations where Ethernet modules are installed.

#### 3.3.2 Convert format between the Network No./station number and IP address/port number

The process overview of the conversion method set by the Station No. <-> IP information screen for performing the other station access via Ethernet module using the MELSECNET/H, MELSECNET/10 relay communication function is explained. Select one of the conversion methods to set.

- Automatic response system (Convert format of Ethernet module default value)
  - (a) Overview of automatic response system
    - The automatic response system differs from the other convert format in that designations can only be made when the Ethernet module installed station is the communication request destination station or communication relay receiving station.
    - The partner station IP Address or port number setting are not necessary with this conversion method, making the MELSECNET/H, MELSECNET/10 relay communication performed easily.

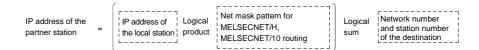


- (b) Convert format of Automatic response system
  - 1) When the Ethernet module receives other station access communication request message (command frame) from the MELSECNET/H, MELSECNET/10 relay communication function, the send source Network No., IP address, and UDP port number in the request message, are stored internally. The response message (response) for the communication request message is returned to the destination IP address and UDP port number calculated from the stored Network No. and station number. Therefore, by receiving the other station access communication request message first, the communication partner stations can be maintained.
  - 2) The maximum number of station information that can be set is 64. When more than 64 other station access communication request message is received, the Ethernet module starts deleting from the oldest data to store the station information in the newly received message communication request message. However, it is ignored if the station information is the same as the station information already stored.
    - \* Information from the same station is not stored twice.

## (2) IP address computation system

(a) Overview of the IP address computation system During calculation, the IP address of the partner station is obtained from the calculation equation below according to the Network No. and station number, and the UDP port number predefined for the Ethernet module system is used as the UDP port number of the destination.

\* For more information about the net mask pattern for MELSECNET/H, MELSECNET/10, see Section 3.3.2.



- (b) Conversion processing of the IP address computation system
  - When a communication request message (command frame) to access other station is received, the IP address is calculated from the Network No. and station number of the destination in the communication request message, and the communication request message is sent to the next station.
    - \*1 The Network No. and station number of the destination in the communication request message are stored in the Ethernet module.
  - The response message (response) for the communication request message is returned based on the return IP address and the stored data above.
- (c) IP address computation example

The logical sum is calculated differently depending on the class of the local station IP address. An IP address is calculated as follows.

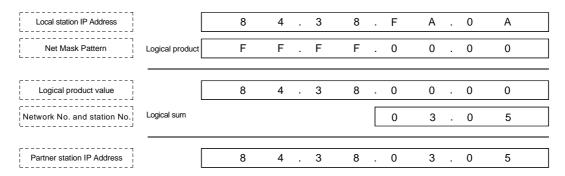
(For class A)

- When the local station IP Address is 79238102H
- When the MELSECNET/H, MELSECNET/10 Routing Net Mask Pattern is FF000000H
- $\bullet$  When the destination Network No. is 03H, and the station number is 05H

Local station IP Address	[	7	9 .	2 3	. 8	1	0	2
Net Mask Pattern	Logical product	F	F.	0 0	. 0	0	0	0
Logical product value	[	7	9 .	0 0	. 0	0	0	0
Network No. and station No.	Logical sum				0	3	0	5
Partner station IP Address		7	9 .	0 0	. 0	3	0	5

(For class B)

- When the local station IP Address is 8438FA0AH
- When the MELSECNET/H, MELSECNET/10 Routing Net Mask Pattern is FFFF0000H
- When the destination Network No. is 03H and station number is 05H



#### (For class C)

- When the local station IP Address is CA65300AH
- When the MELSECNET/H, MELSECNET/10 Routing Net Mask Pattern is FFFFFF00H
- When the destination Network No. is 02H (The Network number is not used.)

Local station IP Address		С	Α.	6	5	. 3	0	0	Α
Net Mask Pattern	Logical product	F	F.	F	F	. F	F	0	0
Logical product value		С	Α.	6	5	. 3	0	0	0
Network No. and station No.	Logical sum							0	2
Partner station IP Address		С	Α.	6	5	. 3	0	0	2

# REMARK

• IP address configuration of class A

31	30 to 24	23 to	16 15	to	0
Class	Network address		Host	address	

• IP address configuration of class B

31	30	29	to	16	15	to	0
Cla	ISS		Network address			Host address	

• IP address configuration of class C

31 to 2928		28 to	8	7	to	0
	Class	Network address		Н	ost addre	ss

## (3) Table exchange system

- (a) Overview of the table exchange system
  - This method uses the Network No., station number, and IP address set in the conversion table of the Station No. <-> IP information, and uses the UDP port number predefined for the Ethernet module system as the UDP port number of the destination.
  - 2) If duplicate network and station numbers are set in the conversion table, the data set with the younger registration number is used.
    - \* If all the required values are not set, communication may not be performed successfully.
- (b) Conversion processing of the table exchange system
  - 1) When a communication request message (command frame) to access other station is received, the same Network No. and station number are searched in the conversion table of the Station No. <-> IP information, and the communication request message is sent to the partner station with the corresponding IP address.
  - 2) The response message (response) for the communication request message is returned based on the return IP address and the data in the conversion table above.
- (c) Designation example
  Shown on the next page.

3 - 11 3 - 11

(Setting example)

Setting

value

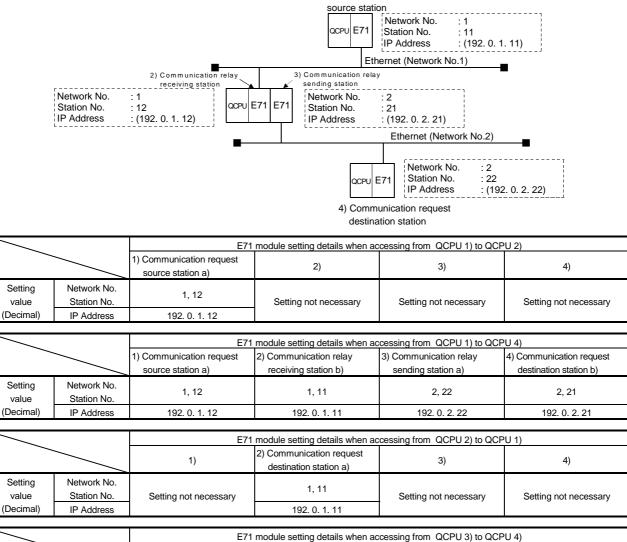
Setting

value

Setting

value

(Decimal)



1) Communication request

		E71 module setting details when accessing from QCPU 3) to QCPU 4)				
		1)	2)	Communication request source station a)	4)	
Setting value	Network No. Station No.	Setting not necessary	Setting not necessary	2, 22	Setting not necessary	
(Decimal)	IP Address	-		192. 0. 2. 22		

		E71 module setting details when accessing from QCPU 4) to QCPU 1)				
		1) Communication request	2) Communication relay	3) Communication relay	4) Communication request	
		source station b)	sending station b)	receiving station b)	destination station a)	
Setting	Network No.	1. 12	1, 11	2, 22	2, 21	
value	Station No.	1, 12				
(Decimal)	IP Address	192. 0. 1. 12	192. 0. 1. 11	192. 0. 2. 22	192. 0. 2. 21	

		E71 module setting details when accessing from QCPU 4) to QCPU 3)				
		1)	2)	3)	Communication request destination station a)	
Setting value	Network No. Station No.	Setting not necessary	Setting not necessary	Setting not necessary	2, 21	
(Decimal) IP Address					192. 0. 2. 21	

<sup>\*</sup> The a) and b) in the E71 station setting details column indicate whether the value is for the communication request message transmission or response message transmission.

3 - 12 3 - 12 a): For communication request message transmission b): For response message transmission

## (4) Use-together system

- (a) Overview of the Use-together system
  - 1) This method uses both the IP address computation system and the table exchange system.
  - 2) This method can be designated when accessing other station with the same Network No., accessing other station in other MELSECNET/H, MELSECNET/10 network system or accessing an Ethernet with different Network No., and relaying from the MELSECNET/H, MELSECNET/10 to the Ethernet network system.
  - 3) The set target Ethernet module can be installed either at a communication request source station, communication relay station, or communication request destination station.
- (b) Conversion processing of the Use-together system
  - 1) When a communication request message (command frame) to access other station is received, the communication request message is sent to the next station obtained by the table exchange system at first.
  - 2) If the IP address of the Ethernet module cannot be obtained by the table exchange system, the IP address is obtained by the IP address computation system in order to send the communication request message.
  - 3) The response message (response) to the communication request message is returned based on the return IP address and the data in the conversion table or the stored data.

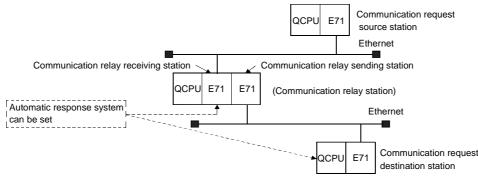
# REMARK

The relationship between the Convert Format and definition of the Ethernet module installed station is as follows.

	Ethernet module installed station definition					
Conversion method	Communication request source station	Communication relay station		Communication request		
method		Relay receiving station	Relay sending station	destination station		
Automatic response system	× ( * <sup>1</sup> )	0	× ( * <sup>1</sup> )	0		
IP Address computation system	0	0	0	0		
Table exchange system	0	0	0	0		
Use-together system	0	0	0	0		

○ : Can be designation × : Cannot be designated

\*1 For the external device that completed the communication, the station can be a communication request source station or a relay sending station.



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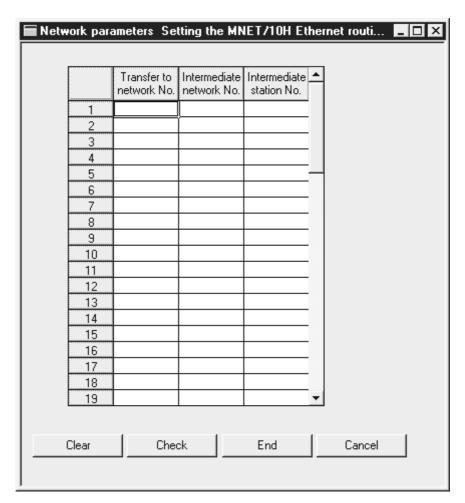
## 3.3.3 Routing parameter settings

The routing parameters contain information of the Ethernet modules passed through when accessing other stations.

This section explains the routing parameters that must be set in order to access other stations via the Ethernet module using the MELSECNET/H, MELSECNET/10 relay communication function.

Select [GX Developer] - [Network parameters] to start the [Setting the MNET/10H Ethernet routing information].

For details on how to display the screen, see the GX Developer Operating Manual.



#### Routing information setting

Item name	Description of setting	Setting range/option
Transfer to Network No.	Set the Network No. of the Ethernet or MELSECNET/H, MELSECNET/10 to which the	
	communication request destination station or the communication request source station is connected	1 to 239
	when sending a communication request message or a response message, respectively.	
	Set the Network No. of the Ethernet or MELSECNET/H, MELSECNET/10 to which the next	
ntermediate network No.	communication relay receive station or the next communication relay send station is connected	1 to 239
	when sending a communication request message or a response message, respectively.	
Intermediate station No.	Set the station number of the target Ethernet module/network module that is used as relay to the	1 to 64
Intermediate station No.	network set by the Intermediate station No	1 to 64

#### (1) Transfer to Network No.

Designate the Network No. of the Ethernet or MELSECNET/H, MELSECNET/10 to which the communication request destination station or the communication request source station is connected when sending a communication request message or a response message, respectively.

### (2) Intermediate Network No.

Designate the Network No. of the Ethernet or MELSECNET/H, MELSECNET/10 to which the next communication relay reception station or the next communication relay transmission station is connected when sending a communication request message or a response message, respectively.

#### (3) Intermediate station No.

Designate the station number of the target Ethernet module/network module that is used as a relay to the network set by the Intermediate station No..

#### **POINT**

The following stations require the routing parameters to be set and registered:

- 1) The PLC CPU of the communication request source station
- 2) The PLC CPU of the stations (relay reception station and relay transmission station) that relay communication request messages.
- 3) The PLC CPU of the stations (relay reception station and relay transmission station) that relay response messages.

## REMARK

- (1) The routing parameters setting is not necessary for the other station access on the same Ethernet network as the external device/local station QCPU.
- (2) The routing parameters are designated in the following manner:

To go to a station on the <u>network No. ○</u>, relay through the <u>station No. □</u>, on the <u>network No. △</u>, which is the first communication relay from the local station.

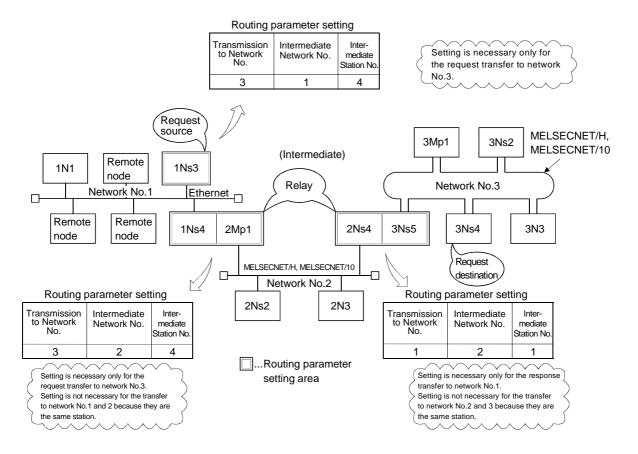
Transfer to Network | Intermediate | Network No. | Station No. | Station

- (3) As an example, to perform other station access from station 1Ns3 to 3Ns4 in the diagram in the next page, the following values are set to the stations which require the routing parameter setting.
  - Communication request source station: Station 1Ns3
  - Communication relay station : Station 1Ns4/2Mp1, and Station

2Ns4/3Ns5

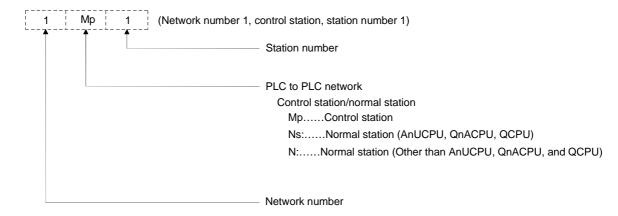
- \* The code used for each station in the diagram indicates the Network No. of the MELSECNET/H, MELSECNET/10 or Ethernet, station type, and station number.
- A maximum of 64 "transfer to Network No." can be set in the QCPU.
   64 types of Network No. can be accessed to other station via local station or can be the request source.

However, the same transfer destination Network No. cannot be set two or more times. (multiple times)



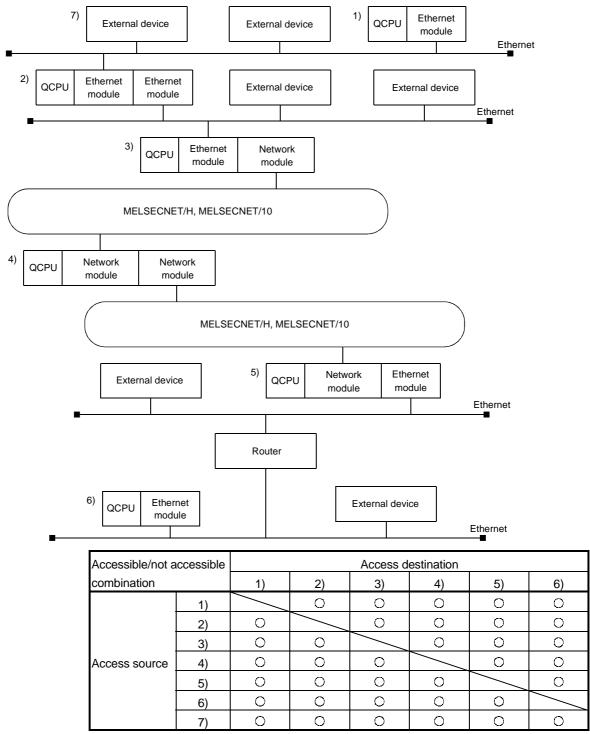
(The meanings of the symbols used for the stations shown in the diagram)

• Network system (MELSECNET/H, MELSECNET/10)



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- (4) Using the example of a system shown below, the accessible stations and the stations that require parameter settings when an opposite device or QCPU access other stations are explained.
  - \* Stations that require the setting of the "setting the Ethernet router relay parameter" as mentioned in Section 5.3 of the User's Manual (Basic) are also shown.



○ : Accessible × : Not accessible

△ : Accessible (The number of access points, etc., is restricted.)

## (1) When performing a remote access from 1) to 2)

Oction without	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H Ethernet cards	•	•	×	×	×	×	×	
Setting the MNET/10H Ethernet routing information	×	×	×	×	×	×	×	
Setting the Ethernet Station No. <-> IP information	•	•	×	×	×	×	×	
Setting the Ethernet router relay parameter	×	×	×	×	×	×	×	

#### (2) When performing a remote access from 1) to 3)

0.45.3	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H Ethernet cards	•	•	•	×	×	×	×	
Setting the MNET/10H Ethernet routing information	•	•	×	×	×	×	×	
Setting the Ethernet Station No. <-> IP information	•	•	•	×	×	×	×	
Setting the Ethernet router relay parameter	×	×	×	×	×	×	×	

#### (3) When performing a remote access from 1) to 5)

Outting titages	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H						×	×	
Ethernet cards						^	^	
Setting the MNET/10H Ethernet					×	×	×	
routing information					^	^		
Setting the Ethernet Station No. <->				×	×	×	×	
IP information				^	^	^	^	
Setting the Ethernet router relay	×	×	×	×	×	×	×	
parameter	^	^	^	^	^	^	^	

## (4) When performing a remote access from 1) to 6)

0 - 11	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H Ethernet cards	•	•	•	•	•	•	×	
Setting the MNET/10H Ethernet routing information	•	•	•	•	•	×	×	
Setting the Ethernet Station No. <-> IP information	•	•	•	×	•	•	×	
Setting the Ethernet router relay parameter	×	×	×	×	•	× (*1)	×	

<sup>\*1</sup> Setting is required when accessing to the PLC of 1) to 5) from the device of 6).

## (5) When performing a remote access from 7) to 1)

Oction without	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H Ethernet cards	•	×	×	×	×	×	×	
Setting the MNET/10H Ethernet routing information	×	×	×	×	×	×	×	
Setting the Ethernet Station No. <-> IP information	•	×	×	×	×	×	×	
Setting the Ethernet router relay parameter	×	×	×	×	×	×	×	

#### (6) When performing a remote access from 7) to 3)

0.445	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H Ethernet cards	×	•	•	×	×	×	×	
Setting the MNET/10H Ethernet routing information	×	•	×	×	×	×	×	
Setting the Ethernet Station No. <-> IP information	×	•	•	×	×	×	×	
Setting the Ethernet router relay parameter	×	×	×	×	×	×	×	

## (7) When performing a remote access from 7) to 4)

Catting items	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H Ethernet cards	×	•	•	•	•	×	×	
Setting the MNET/10H Ethernet routing information	×	•	•	×	×	×	×	
Setting the Ethernet Station No. <-> IP information	×	•	•	×	×	×	×	
Setting the Ethernet router relay parameter	×	×	×	×	×	×	×	

#### (8) When performing a remote access from 7) to 6)

Oction without	Station that does (●)/does not (×) require setting							
Setting item	1)	2)	3)	4)	5)	6)	7)	
Setting the number of MNET/10H Ethernet cards	×	•	•	•	•	•	×	
Setting the MNET/10H Ethernet routing information	×	•	•	•	•	×	×	
Setting the Ethernet Station No. <-> IP information	×	•	•	×	•	•	×	
Setting the Ethernet router relay parameter	×	×	×	×	•	×	×	

#### 3.4 Procedure for Accessing Other Stations

This section explains the procedure for accessing other stations via the Ethernet using the MELSECNET/H, MELSECNET/10 relay communication function as well as the required processing.

(1) Setting the parameters

The parameters shown in Section 3.3 must be set using GX Developer.

(2) Accessing other stations

Access to other stations is performed from an external device/local station QCPU using the MELSECNET/H, MELSECNET/10 relay communication function.

## REMARK

- Access to other stations with the MELSECNET/H, MELSECNET/10 relay communication function is performed using the UDP/IP protocol and data is always communicated in binary code.
- In the data communication, the port number (for the UDP/IP port) for the Ethernet module system is used.
- It is possible to continue accessing other stations while the initial normal completion signal (X19) is on.
   When the initial normal completion signal (X19) is turned off, the Ethernet module forcefully closes the connection although other station is being accessed.

#### (3) End processing of the Ethernet module

When ending access to other station with the MELSECNET/H, MELSECNET/10 relay communication function that has been made using a connection opened by user, execute the close processing of the connection by seeing Section 5.6 of the User's Manual (Basic).

When the following two functions are used to access other station, the close processing is not required.

- · Communication using the data link instructions
- Communication with other stations using GX Developer

#### 3.5 Precautions for Accessing Other Stations

The following describes precautions when accessing other stations via the Ethernet module using the MELSECNET/H, MELSECNET/10 relay communication function.

- (1) The user should make an arrangement so that duplicate Network No.s for the Ethernet network system that have already been assigned to the Ethernet modules are not used.
  - In addition, make sure that the same station numbers for the Ethernet network system as those already assigned to the existing network system mentioned above and other Ethernet are not used.
- (2) Access to other stations using the MELSECNET/H, MELSECNET/10 relay communication function is performed using the UDP/IP protocol and data is always communicated in binary code.

#### POINT

See the manual for the MELSECNET/H, MELSECNET/10 system for the interlock signals and the send/receive processing and processing time of the link data when performing data communication with QCPUs of other stations via the MELSECNET/H, MELSECNET/10 network system.

# 4 WHEN THE QCPU ACCESSES THE OTHER STATION PLC USING THE DATA LINK INSTRUCTION

By using the MELSECNET/H, MELSECNET/10 relay communication function, the Ethernet network system is regarded as the same class as the MELSECNET/H, MELSECNET/10 network system, therefore, the QCPU can perform data communication with the other station PLC CPUs as follows using the data link instructions.

- · PLC CPUs of other stations on the same Ethernet network system
- PLC CPUs on other Ethernet networks accessed via routers (using the router relay function)
- PLC CPUs on other Ethernet or MELSECNET/H, MELSECNET/10 networks accessed via the MELSECNET/H, MELSECNET/10 (using the MELSECNET/H, MELSECNET/10 relay communication function)

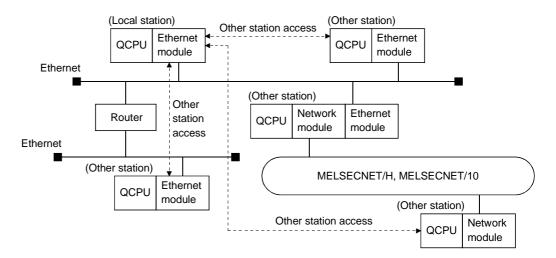
In this chapter, the usage of the data link instructions, etc. are explained when the local station QCPU performs data communication with the other station PLC CPU with the Ethernet module via Ethernet or MELSECNET/H, MELSECNET/10.

#### POINT

When accessing other stations using data link instructions via Ethernet module, set the parameters shown in Chapter 3.

#### 4.1 Other Station Access with the Data Link Instruction

The data link instruction is an instruction to perform data send/receive, read/write of the word device memory, and other station access such as remote RUN/STOP to the other station QCPU connected to the MELSECNET/H, MELSECNET/10 or Ethernet. If the initial processing of the local station, relay station, and access station's Ethernet module is finished correctly, it will be possible to access other stations by the data link instruction.



## 4.2 Precautions for Accessing Other Stations

The following describes precautions when accessing other stations via the Ethernet module using the data link instructions.

# (1) Executing multiple instructions at one time (common to the data link instructions)

- (a) When accessing multiple communication request destination stations (other stations) from the same communication request station at one time, change the target channel number of the communication request source station for each communication request destination station.
- (b) When accessing other stations using the same channel number, access the next station after the last access to other station is completed.
- (c) For mutual accesses between the communication request station and the communication request destination station, change the target channel number of the communication request station for each instruction.
- \* If the access destination stations (communication request destination station) are different, a maximum of eight instructions can be executed at one time as long as the channel numbers (1 to 8) designated in the control data of each instruction do not overlap.

## (2) Setting the arrival monitoring time of the control data storage device

For the arrival monitoring time designation area of the control data storage device, set the monitoring time that is equal to or greater than the TCP resend timer value set with the initial processing parameters.

When the monitoring time is equal to or less than the TCP resend timer value, the TCP resend timer value is set as the arrival monitoring time. (\*1) (When the setting value is less than or equal to the TCP resend timer value, the arrival monitoring timer equals the TCP resend timer value.)

\*1 Although the units of setting values for the TCP resend timer (setting value units: 0.5 s) and the arrival monitoring timer (setting value units: s) are different, the TCP resend timer value is used as is.

#### (3) Checking the execution result of each data link instruction

The execution result (completion status) of each data link instruction is stored in the areas shown as binary values.

After the execution of an instruction is completed, read the execution result from the storage area and verify either normal or abnormal completion.

Stored value at normal completion : 0

Stored value at abnormal completion: Other than 0 (error code)

When an error code that indicates abnormal completion is stored, take an action by seeing the "Troubleshooting" section in the User's Manual (Basic).

Instruction	Storage area of execution result					
SEND						
RECV, RECVS	The completion status storage device of the control data storage					
READ, SREAD						
WRITE, SWRITE	device of the instruction used.					
REQ						
ZNRD	The execution result storage area	Address CF <sub>H</sub> (207)				
ZNWR	in the buffer memory	Address D1н (209)				

- (4) Clock data when each of the data link instructions ends abnormally In the clock data stored as control data at the time that each of the data link instructions ends abnormally (set only when it is something wrong), the year data (upper 2 digits) is stored only when the QCPU is the error detection station. If the error detection station is other than the QCPU, 00H is stored.
- (5) Channels used by the ZNRD and ZNWR instructions

The ZNRD and ZNWR instructions for Ethernet modules are executed using the following channels of the target Ethernet module.

- ZNRD: Channel 1
- ZNWR: Channel 2

Do not use the channels used by the ZNRD and ZNWR instructions listed above for other data link instructions in an Ethernet module mounted station that executes the ZNRD and ZNWR instructions. Also, do not execute data link instructions from other stations on the channels listed above in an Ethernet module mounted station that executes the ZNRD and ZNWR instructions.

#### **POINT**

- (1) See Chapter 3 for details of the following when performing other station access using the data link instructions.
  - The accessible range and accessible stations of the other stations
  - Setting to perform other station access
  - · Other station access procedure
- (2) The communication using the data link instructions on the Ethernet is performed with UDP/IP.
  - When executing each data link instruction except for ZNRD and ZNWR, it is recommended to designate a value greater than "1" to the number of retries setting area of the control data storage device.
- (3) See the MELSECNET/H, MELSECNET/10 Reference Manual regarding the link data send/receive processing and processing time in data communication with the other station PLC CPU via MELSECNET/H, MELSECNET/10.
- (4) For details about data designation methods in the data link instruction, see Chapter 6.

## 4.3 Using the Data Link Instructions

This section explains how to use the data link instructions when accessing other stations via the Ethernet module.

## (1) SEND instruction

- When performing simultaneous other station accesses from multiple communication request source stations to the same communication request destination station, change the channel number of the communication request destination station for each communication request source station.
  - If the channel number is being used at the communication request source station (being accessed from other station using the same channel number) when other station is accessed, the data link instruction ends in error. So, re-execute the instruction.
  - \* If the channel number used is different at the communication request destination station side, simultaneous other station access can be performed from a maximum of eight communication request source stations to the same station.
- 2) When performing other station access from the same communication request source station to the same communication request destination station, change the channel number at the communication request destination station side.
  - When designating the same channel number on the communication request destination station side, perform the second other station access after the first other station access is complete. If the second SEND instruction is executed before the first SEND instruction is completed, the SEND instruction ends in error.

#### (2) Instruction other than the SEND instruction

- When simultaneous other station access is performed to the same communication request destination station from multiple communication request source station, and a busy error (being accessed from other station) occurs, re-execute the instruction.
- 2) When accessing other station from the same communication request source station to the same communication request destination station, execute the second data link command after other station access by the first data link instruction is complete.

#### (3) Broadcast (Simultaneous broadcast)

When FFH is designated as the target station number in the control data when executing SEND/WRITE (SWRITE)/REQ on the Ethernet, the command is sent to all external devices on the network.

(Example) IP address when the command is sent (for class B)

Bit location	31	30 29	to 1	6 15	to	0
			ЕТТЭн		FFFF <sub>H</sub>	
	Cla	iss	Network address	ļ	Host address	

For the external devices on the Ethernet, perform read-dump processing locally for the received commands not related to the local station.

\* The COM. ERR LED indicator of an Ethernet module may turn on and an error code may be stored in the following buffer memory area when a response to a simultaneous broadcast from the Ethernet module is returned from an external device.

Error code/end code area (address: from E5H (229))

- \* These processing are performed automatically with the Ethernet module.
- (4) Interlock when executing the data link instruction
  - (a) Via Ethernet

Execute the data link command when the local station (communication request source station) Ethernet module is at the following I/O signal state.

#### (b) Via MELSECNET/H, MELSECNET/10

Check the status of the local station (communication request source station), communication relay station, and access destination (communication request destination station) using the following devices. Execute the data link instruction if the status is normal.

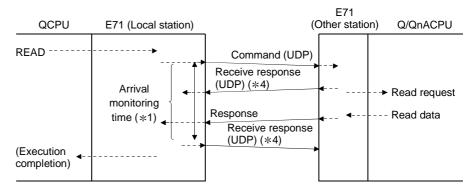
- Link special relay: SB20, SB47, SB70, etc.
- Link special register: SW70 to 73, SW74 to 77, etc.
- \* See the MELSECNET/H, MELSECNET/10 Reference Manual for the interlock signals, link data send/receive processing, and processing time when performing data communication with the other station PLC CPU via MELSECNET/H, MELSECNET/10.
- (5) Number of resend designation of data link instruction

When executing each data link instruction except for ZNRD and ZNWR, it is recommended to designate a value greater than "1" for the number of resend designation area of the control data storage device.

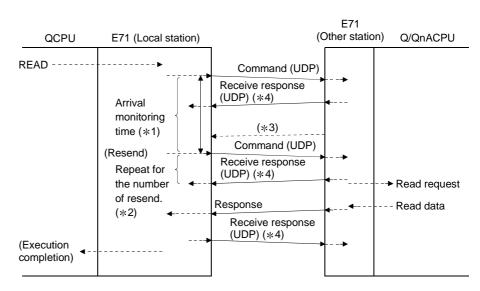
The resend timing when the READ command is executed after designating the number of resend is described below.

(Example) READ instruction execution timing

1) Communication timing when the READ instruction completed successfully (when resend is not performed)



2) Communication timing when the READ instruction completed successfully (when resend is performed)



- \*1 The user designates the arrival monitoring time with the READ instruction control data ((S1)+8).
- \*2 The user designates the number of resend with the READ instruction control data ((S1)+7).
- \*3 Indicates the response not returned within the arrival monitoring time.
  - The Ethernet module performs a resend of the command for the number of resend when this response is not received.
- \*4 The "receive response (UDP)" in the diagram is for the interlock between the Ethernet module, and this is the response to the partner station Ethernet module from the Ethernet module OS.

## 4.4 Data Link Instructions

This section explains the overview of the data send/receive in each data link instruction when accessing via Ethernet Module.

		Instruction execution	Target station		
		station (Local station)	raiget station		
				PLC CF	PU type
Instruction	Details				Other
		Station type	Station type	QCPU	than
				QnACPU	describ-
					ed left * 1
	Data is sent (SEND) and received (RECV)	Ethernet	Ethernet		
	between the Q/QnACPU stations.	Ethernet module	Ethernet module		
		MELSECNET/H, MELSECNET/10	MELSECNET/H, MELSECNET/10		
SEND	Ethernet module/ Ethernet module/ Q/QnACPU N/W module N/W module Q/QnACPU	Control station	Control station		
RECV	channel 1   channel 1   channel 2   channel 2	Normal station	Normal station		\ <u>/</u>
	HI—[SEND] + channel 3 channel 3	Remote master station	Remote master station		×
RECVS	channel 5 Channel 5	Multiple remote master station	Multiple remote master station		
	channel 6 channel 6 channel 7	Parallel remote master station	Parallel remote master station		
	channel 8 channel 8	Multiple remote submaster station	Multiple remote submaster station		
	See Section 4.5.1, 4.5.2	Parallel remote submaster station	Parallel remote submaster station		
	Reads data from other station's word device.	Ethernet	Ethernet		
	(With SREAD, device on target station can	Ethernet module	Ethernet module		
	be turned on.)	MELSECNET/H, MELSECNET/10	MELSECNET/H, MELSECNET/10		
		Control station	Control station		
DEAD	Ethernet module/ Ethernet module/ Q/QnACPU N/W module N/W module Q/QnACPU	Normal station	Normal station		
READ	Chapter 1 Word device	Remote master station	Remote master station		×
SREAD	HI—[READ] Chapter 2 Chapter 3	Multiple remote master station	Multiple remote master station	_	
	Chapter 4   2594   Word device   Chapter 5	Parallel remote master station	Parallel remote master station		
	2594 Chapter 6 Chapter 7	Multiple remote submaster station	Multiple remote submaster station		
	Chapter 8	Parallel remote submaster station	Parallel remote submaster station		
	See Section 4.6				
	Writes data to other station's word device.	Ethernet	Ethernet		
	(With SWRITE, device on target station can	Ethernet module	Ethernet module		
	be turned on.)	MELSECNET/H, MELSECNET/10	MELSECNET/H, MELSECNET/10		
		Control station	Control station		
WRITE	Ethernet module Ethernet module Q/QnACPU N/W module N/W module Q/QnACPU	Normal station	Normal station		
SWRITE	Chapter 1 Word device	Remote master station	Remote master station	0	×
SWITTL	Chapter 3	Multiple remote master station	Multiple remote master station		
	H [WRITE] + Chapter 4 361 Chapter 5	Parallel remote master station	Parallel remote master station		
	Chapter 6 Chapter 7	Multiple remote submaster station	Multiple remote submaster station		
	Chapter 8	Parallel remote submaster station	Parallel remote submaster station		
	See Section 4.6				
	Performs "clock data read and write" for	Ethernet	Ethernet		
	other stations.	Ethernet module	Ethernet module		
	Ethernet module Ethernet module	MELSECNET/H, MELSECNET/10	MELSECNET/H, MELSECNET/10		
	QCPU NW module NW module Q/QnACPU	Control station	Control station		
REQ	Chapter 1 Chapter 2	Normal station	Normal station		×
	Chapter 3 STOP	Remote master station	Remote master station	~	
	Chapter 5 Chapter 6	Multiple remote master station	Multiple remote master station		
	Chapter 7 Chapter 8	Parallel remote master station	Parallel remote master station		
	Li Li	Multiple remote submaster station	Multiple remote submaster station		
	See Section 4.8	Parallel remote submaster station.	Parallel remote submaster station		
	Reads data from other station's word device.	Ethernet	Ethernet		
	Ethernet module Ethernet module	Ethernet module	Ethernet module		
	QCPU N/W module N/W module PLC CPU	MELSECNET/H, MELSECNET/10	MELSECNET/H, MELSECNET/10		
	Channel 1 Word device	Control station	Control station		
ZNRD	2594	Normal station	Normal station		0
	Word device	Remote master station	Remote master station		
		Multiple remote master station	Multiple remote master station		
		Parallel remote master station	Parallel remote master station		
		Multiple remote submaster station	Multiple remote submaster station		
	See Section 4.7	Parallel remote submaster station	Parallel remote submaster station		

		Instruction execution station (Local station)	Target station			
Instruction	Details	Station type	Station type	QCPU QnACPU	Other than described left * 1	
ZNWR	Writes data to other station's word device.  Ethernet module NW module PLC CPU  Word device    H-  ZNWR   3611	Ethernet Ethernet module  MELSECNET/H, MELSECNET/10  Control station Normal station Remote master station Multiple remote master station Parallel remote submaster station Parallel remote submaster station Parallel remote submaster station	Ethernet Ethernet module  MELSECNET/H, MELSECNET/10  Control station  Normal station  Remote master station  Multiple remote master station  Parallel remote submaster station  Parallel remote submaster station  Parallel remote submaster station	0	0	

<sup>\* &</sup>quot;Channels 1 to 8" for the Ethernet module and network module are the OS area for each module in the diagram to store the send/receive data of each data link instruction.

\*1 Access to PLC CPUs other than the QCPU and QnACPU is allowed only to stations connected to the MELSECNET/10.

#### **POINT**

- (1) The MELSECNET/H, MELSECNET/10 network No., group No., and station No., for the Ethernet module in the data link instruction setting data, designate the network No., group No., and station No., assigned to the Ethernet module by the "Setting the number of MNET/10H Ethernet cards" indicated in User's Manual (Basic).
  - \* This is so that the Ethernet network system will be considered to be the same class as the MELSECNET/H, MELSECNET/10 network system, to perform other station accessing processing for the QCPU.
- (2) For details of the data designation method for the data link instruction, see chapter 6.
- (3) A maximum of eight instructions can be performed simultaneously, as long as the channel number (1 to 8) designated in each instruction control data do not overlap with each other when the access destination stations (communication request destination station) are different.

There are no operation differences in the instruction format JP. []] and GP. []], and J. []] and G. []].

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[Precautions for data link instruction]

- (1) In a system where AnUCPU coexist, never execute the following instruction from the Q/QnACPU to other station's AnUCPU. The AnUCPU that has been executed such instruction results in "MAIN CPU DOWN" or "WDT ERROR," and may stop the operation.
  - 1) SEND 2) READ 3) SREAD 4) WRITE 5) SWRITE 6) REQ
- (2) When accessing for all Q/QnACPU stations on the MELSECNET/10 including PLC CPU other than Q/QnACPU, perform the access using the group No. designation.

## 4.5 Data Sending/Receiving

This section explains the arbitrary data sending/receiving function, instruction format and programs using the data send/receive instructions (SEND, RECV and RECVS instructions).

- (1) The SEND, RECV, and RECVS instructions are used for sending and receiving arbitrary data to/from the PLC CPU with which communicate is being performed.
- (2) Data sending is performed using the SEND instruction and data receiving is performed using the RECV or RECVS instruction.
  - The RECV instruction and the RECVS instruction are used differently as follows.
  - (a) The RECV instruction is used in the receiving processing in the main program. The main program reads from the RECV instruction executing request area in the buffer memory and executes the RECV instruction using a switch from off to on of a bit corresponding to the data receiving channel number as a trigger.
  - (b) The RECVS instruction is used in the receiving processing in an interrupt program.
    - An interrupt program is started when data is received from the PLC CPU with which communication is being performed to enable receive data reading to the PLC CPU.
    - In order to start the interrupt program, set the parameters on the following screens of GX Developer.
    - "Network Parameters Ethernet Interrupt Settings" screen
       Set the control number (SI) on the Ethernet module side when an interrupt request is made to the PLC CPU from the Ethernet module.
    - 2) "Intelligent function module interrupt pointer setting" screen Associate the control number (SI) set in the "Ethernet Interrupt Settings" above with the interrupt pointer (Ixx) used in the sequence program.
  - \* The settings on the two screens above are the same as when received data is read by an interrupt program in the fixed buffer communication.

    For details on the settings and setting method on these screens, see Section 7.3.2 of the User's Manual (Basic).

#### **POINT**

- (1) In order to start an interrupt program, the following settings with GX Developer and interrupt enable by the sequence program must be required.
  - "Network parameters Ethernet interrupt settings" and "Intelligent function module interrupt pointer settings" with GX Developer.
  - Create interrupt enable/disable programs in the main program in order to start an interrupt program.
    - Use the EI, DI and IMASK instructions for this.
- (2) In cases where receive data is read on the same channel, the main program for reading receive data and the interrupt program for reading receive data can not be used together. Please use either program to read receive data.
  - \* In order to read receive data with the interrupt program, when the setting corresponds to GX Developer, the main program can not be used to read receive data.

## 4.5.1 Data sending/receiving for receive with the main program (SEND/RECV)

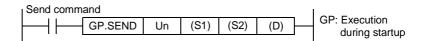
This section explains the format and program examples of the SEND and RECV instructions that are used to send/receive data between the PLC CPUs. For more details, see Sections 6.5 and 6.9.

## (1) Instruction format

(a) SEND instruction [Network number designation]



[Network module/Ethernet module start I/O signal designation]



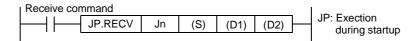
	Setting details	Setting range
Jn	Local station network number	1 to 239: Network number 254: Network designated in the valid module for other station access
Un	Start I/O signal of the local station network module/ Ethernet module  Designate by higher two digits when the I/O signal is expressed by three digits	0 to FEн
(S1)	Control data storage head device  Designate the head device of the local station that stores the control data.	Word device * <sup>2</sup>
(S2)	Send data storage head device  Designate the head device of the local station that stores the send data.	Word device * <sup>2</sup>
(D)	Send completion device  Designate the device to turn on one scan when the send is complete.  (D) OFF: Incomplete ON: Complete  (D) + 1 OFF: Normal ON: Error	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>

\*1: Bit device ...... X, Y, M, L, F, V, B \*2: Word device ..... T, C, D, W, ST, R, ZR

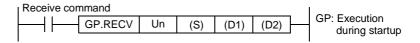
\*3: Word device bit designation ..... [Word device], [Bit number]

4 - 10 4 - 10

(b) RECV instruction (for receive by the main program) [Network number designation]



[Network module/Ethernet module start I/O signal designation]



	Setting details	Setting range
Jn	Local station network number	1 to 239 : Network number 254 : Network designated in the valid module for other station access
Un	Start I/O signal of the local station network module/ Ethernet module  Designate by higher two digits when the I/O signal is expressed by three digits	0 to FEн
(S)	Control data storage head device  Designate the head device of the local station that stores the control data.	Word device * <sup>2</sup>
(D1)	Receive data storage head device  Designate the head device of the local station that stores the receive data.	Word device * <sup>2</sup>
(D2)	Receive completion device  Designate the device to turn on one scan when the receive is complete.  (D2) OFF: Incomplete  (D2) + 1 OFF: Normal  ON: Error	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>

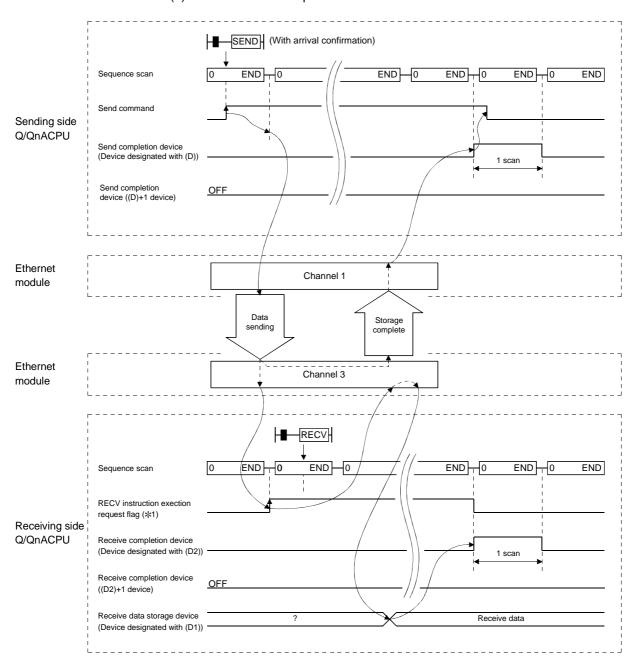
\*1: Bit device ..... X, Y, M, L, F, V, B

\*2: Word device ...... T, C, D, W, ST, R, ZR

\*3: Word device bit designation ····· [Word device], [Bit number]

4 - 11 4 - 11

- (2) Instruction execution timing (for receive processing by the main program)
  - (a) When normal completion



\*1 The RECV instruction execution request flag for Channel 3 used at the receiving side Q/QnACPU is as shown below.

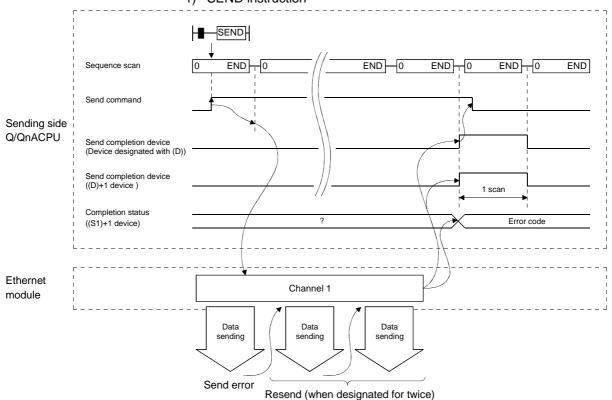
st For Ethernet module : Bit 2 of the RECV instruction execution request area

(address: 205) in the buffer memory

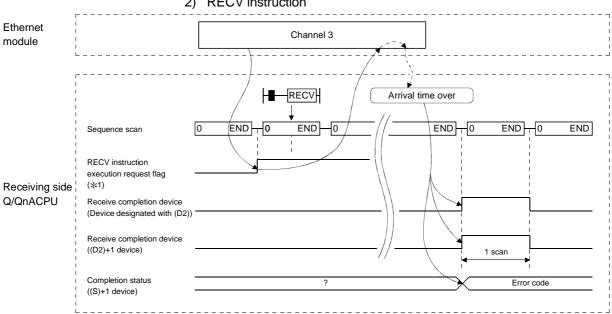
For the N/W module : SBA2 of the link special relay

#### (b) When abnormal completion

#### 1) SEND instruction



## 2) RECV instruction



\*1 The RECV instruction execution request flag for Channel 3 used at the receiving side Q/QnACPU is as shown below.

For Ethernet module: Bit 2 of the RECV instruction execution request area

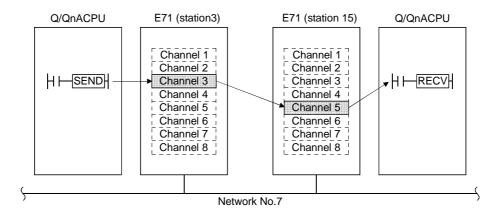
(address: 205) in the buffer memory

For the N/W module: SBA2 of the link special relay

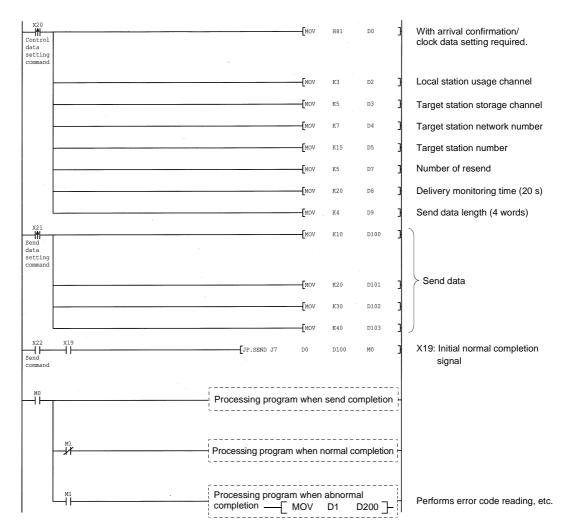
4 - 13 4 - 13

## (3) Program example

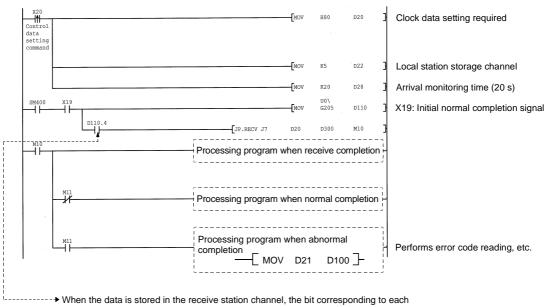
Station 3 uses channel 3 with an SEND instruction, and sends data to station 15 using channel 5. When data is received at station 15, data is read from channel 5.



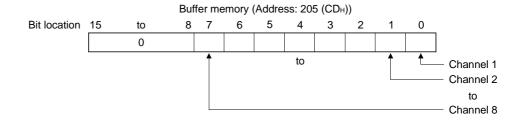
# (a) Station 3 program (SEND instruction) When I/O signals of Ethernet module are X/Y00 to X/Y1F



# (b) Station 15 program (RECV instruction)When I/O signals of the Ethernet module are X/Y00 to X/Y1F



When the data is stored in the receive station channel, the bit corresponding to a channel of buffer memory RECV instruction execution request area turns on. Data can be read automatically bu using this signal for the receive command. The signal turns off shen the RECV instruction is completed.



## 4.5.2 Data sending/receiving for receive with an interrupt program (SEND/RECVS)

This section explains the format and program examples of the RECVS instruction for receive when sending/receiving data between the PLC CPUs.

For details on the instruction format and program examples of the SEND instruction, see Section 4.5.1.

For more details, see Sections 6.5 and 6.9.

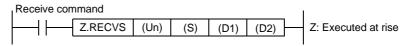
## (1) Instruction format

(a) SEND instruction

Same as the instruction format described in Section 4.5.1.

#### (b) RECVS instruction

[Ethernet module start I/O signal designation]



	Description of setting	Setting range
Un	Start I/O signal of the local station Ethernet module  Designate by higher two digits when the I/O signal is expressed by three digits.	0 to FEн
(S)	Control data storage head device  Designate the head device of the local station that stores the control data.	Word device * <sup>2</sup>
(D1)	Send data storage head device  Designate the head device of the local station that stores the receive data.	Word device * <sup>2</sup>
(D2)	Designate dummy data	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>

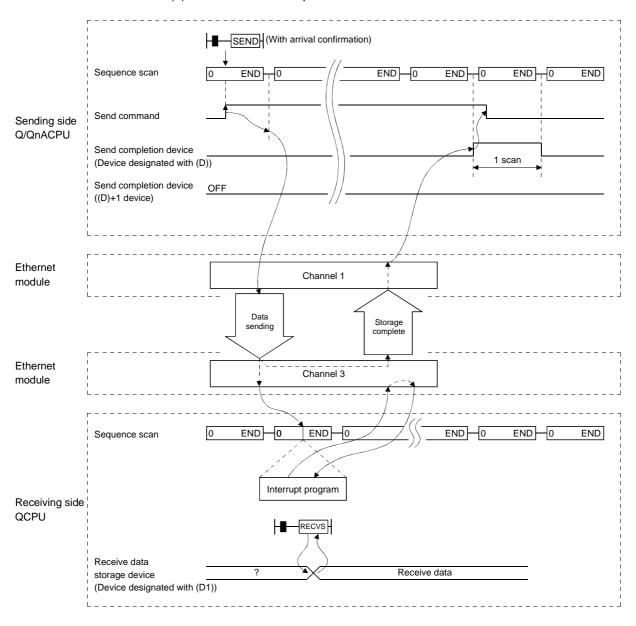
\*1: Bit device ..... X, Y, M, L, F, V, B

\*2: Word device ····· T, C, D, W, ST, R, ZR

\*3: Word device bit designation ..... [Word device]. [Bit number]

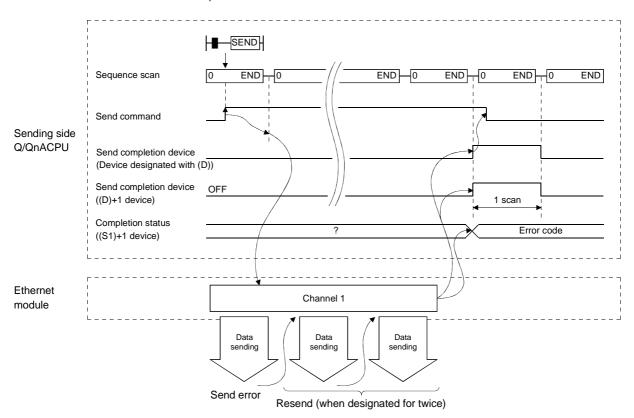
4 - 16 4 - 16

- (2) Execution timing of the instruction (When executing reception processing by an interrupt program)
  - (a) When normal completion

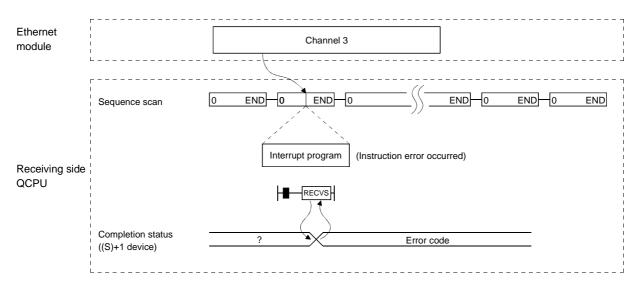


## (b) When abnormal completion

1) In case of the SEND instruction



#### 2) In case of the RECVS instruction

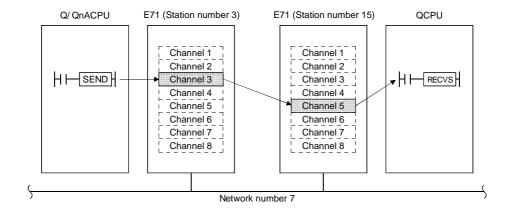


4 - 18 4 - 18

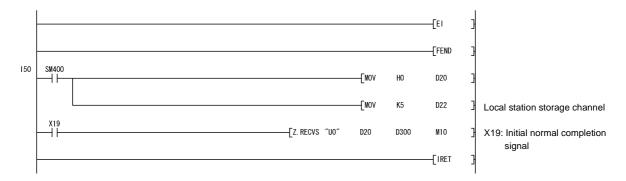
## (3) Program examples

Station 3 uses channel 3 with an SEND instruction and sends data to station 15 using channel 5.

When data is received at station 15, data is read from channel 5.



- (a) Station 3 program (SEND instruction)Same as the program shown in Section 4.5.1.
- (b) Program for station number 15 (RECVS instruction)When the input/output signals of the Ethernet module are X/Y00 to X/Y1F



## REMARK

Create interrupt enable/disable programs in the main program in order to start the interrupt program.

Use the EI, DI and IMASK instructions for this.

To check the descriptions of errors, see the completion status (S1) + 1 indicated in the control data.

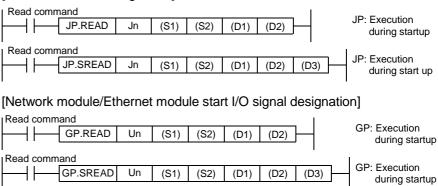
4 - 19 4 - 19

## 4.6 Reading/Writing Word Devices of Other Stations (READ/WRITE)

This section explains the format and program examples of the READ/WRITE instructions that are used to read and write data of word devices of other stations. For details, see Sections 6.4, and 6.10 to 6.12.

### (1) Instruction format

## (a) READ/SREAD instructions [Network number designation]



	Setting details	Setting range
Jn	Local station network number	1 to 239: Network number 254: Network designated in a valid module for other station access.
Un	Start I/O signal of the local station network module/Ethernet module.  Designate by higher two digits when the I/O signal is expressed by three digits.	0 to FEн
(S1)	Control data storage head device  Designate the head device of the local station that stores the control data.	Word device * <sup>2</sup>
(S2)	Read data storage head device (target station)  Designate the head device of the target station that stores the data to read.	Word device * <sup>2</sup>
(D1)	Read data storage head device (local station)  Designate the head device of the local station that stores the data to read.	Word device * <sup>2</sup>
(D2)	Read completion device (local station)  Designate the device of the local station to turn on one scan when the read is complete.  (D2)	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>
(D3)	Read notify device (target station)  Designate the device of the target station to turn on one scan when the read is complete.  (Can recognize data of target station has been read from other station.)  (D3) OFF: Incomplete ON: Complete	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>

\*1: Bit device ...... X, Y, M, L, F, V, B \*2: Word device ..... T, C, D, W, ST, R, ZR

\*3: Word device bit designation ..... [Word device]. [Bit number]

4 - 20 4 - 20

## POINT

- (1) When the target station of the SREAD instruction is the Q00J/Q00/Q01CPU, the read notify device for the target station that is set by an argument (D3) is ignored. The operation of the SREAD instruction is identical to that of the READ instruction.
- (2) The SREAD instruction can be programmed without the argument (D3), while the operation is identical to that of the READ instruction. Depending on whether D3 is omitted or not, the SREAD instruction can be operated differently.
  - (b) WRITE, SWRITE instructions [Network number designation]

L .	_	-					
Write command						. 1	ID. F
JP.WRITE	Jn	(S1)	(S2)	(D1)	(D2)		JP: Execution during startup
			•	•			during startup
Write command							ID. F
JP.SWRITE	Jn	(S1)	(S2)	(D1)	(D2)	(D3)	JP: Execution during startup
''		. , ,					during startup
[Network module/Ethernet module start I/O signal designation]							
Write command						ı	
GP.WRITE	Un	(S1)	(S2)	(D1)	(D2)		GP: Execution during startup
'' -						ļ	during startup
Write command							OD 5 (
GP.SWRITE	Un	(S1)	(S2)	(D1)	(D2)	(D3)	GP: Execution
_ '							during startup

	Setting details	Setting range
Jn	Local station network number	1 to 239: Network number 254: Network designated in a valid module for other station access.
Un	Start I/O signal of the local station network module/Ethernet module.  Designate by higher two digits when the I/O signal is expressed by three digits.	0 to FEн
(S1)	Control data storage head device  Designate the head device of the local station that stores the control data.	Word device * <sup>2</sup>
(S2)	Write data storage head device (local station)  Designate the head device of the local station that stores the data to write.	Word device * <sup>2</sup>
(D1)	Write data storage head device (target station)  Designate the head device of the local station where the data is written.	Word device * <sup>2</sup>
(D2)	Write completion device (local station)  Designate the device of the local station to turn on one scan when the write is complete.  (D2) OFF: Incomplete ON: Complete  (D2) + 1 OFF: Normal ON: Abnormal	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>
(D3)	Write notify device (target station)  Designate the device of the target station to turn on one scan when the write is complete. (Can recognize data of target station has been write from other station.)  (D3) OFF: Incomplete ON: Complete	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>

\*1: Bit device ...... X, Y, M, L, F, V, B \*2: Word device ..... T, C, D, W, ST, R, ZR

\*3: Word device bit designation ...... [Word device] [Bit number]

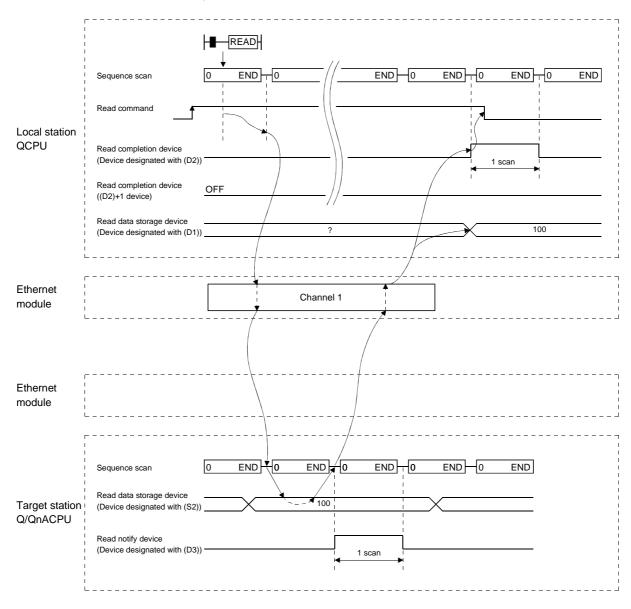
4 - 21 4 - 21

#### **POINT**

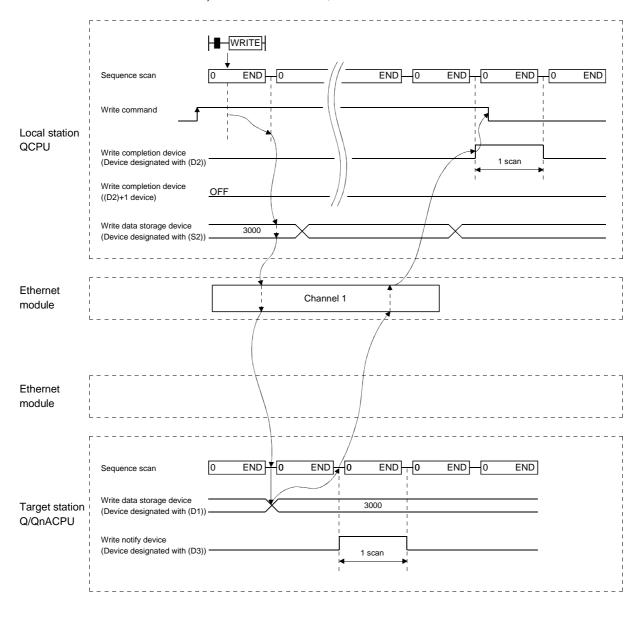
- (1) When the target station of the SWRITE instruction is the Q00J/Q00/Q01CPU, the write notify device for the target station that is set by an argument (D3) is ignored. The operation of the SWRITE instruction is identical to that of the WRITE instruction.
- (2) The SWRITE instruction can be programmed without the argument (D3), while the operation is identical to that of the WRITE instruction. Depending on whether D3 is omitted or not, the SWRITE instruction can be operated differently.

## (2) Instruction execution timing

- (a) When normal completion
  - 1) READ instruction, SREAD instruction

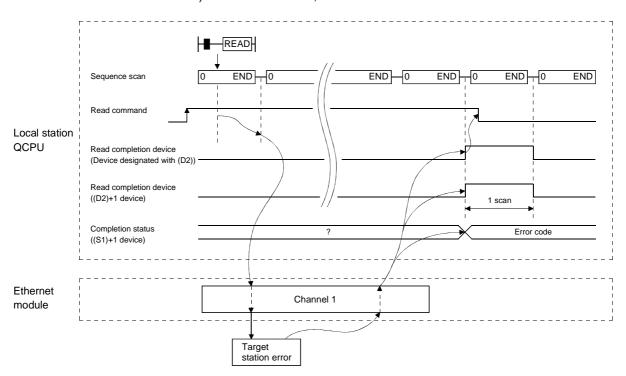


## 2) WRITE instruction, SWRITE instruction

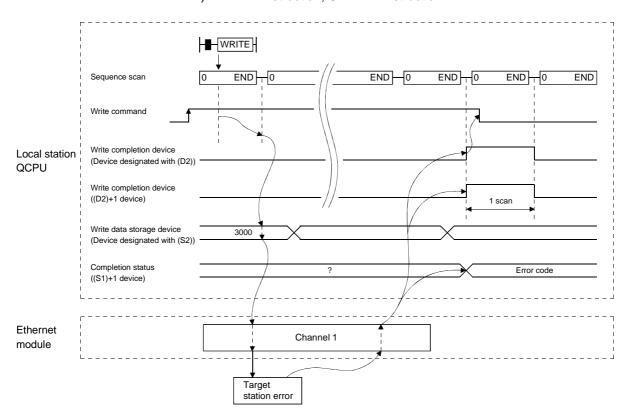


#### (b) When abnormal completion

1) READ instruction, SREAD instruction

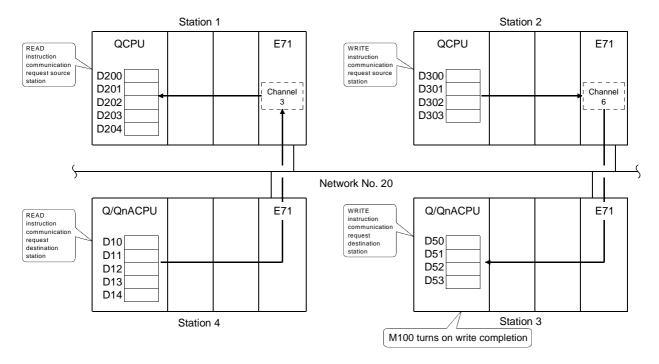


#### 2) WRITE instruction, SWRITE instruction

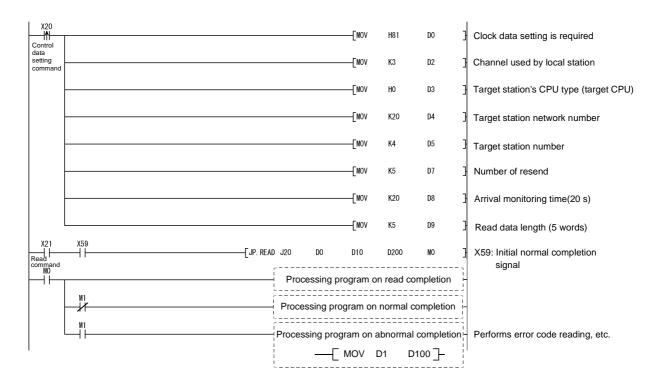


## (3) Program example

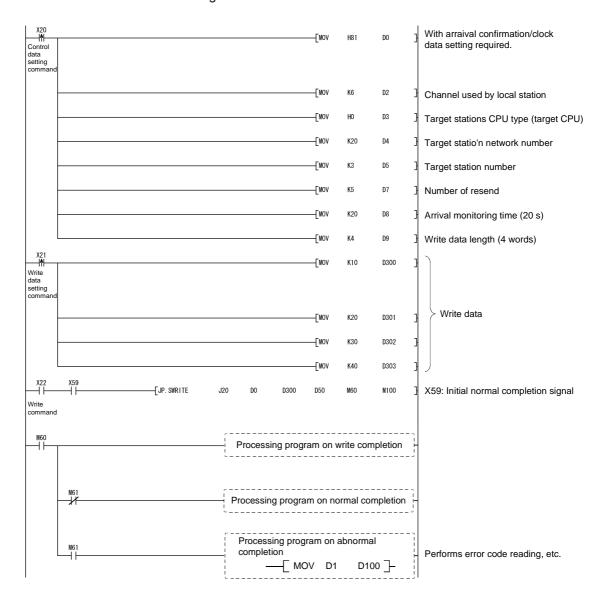
Read data from D10 to 14 of station 4 to D200 to 204 of station 1. Write the data stored in D300 to 303 of station 2 to D50 to 53 of station 3.



(a) Station 1 program (READ instruction)
When I/O signals of Ethernet module are X/Y40 to X/Y5F



# (b) Station 2 programs (SWRITE instruction) When I/O signals of Ethernet module are X/Y40 to X/Y5F



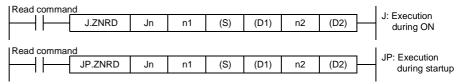
## 4.7 Reading/Writing Word Devices of Other Stations (ZNRD/ZNWR)

This section explains the format and program examples of the ZNRD/ZNWR instructions that are used to read and write data of word devices of other station. For details, see Sections 6.13 and 6.14.

## (1) Instruction format

## (a) ZNRD instruction

[Network number designation]



	Setting details	Setting range
Jn	Target station network number Designate the target station network number.	1 to 239
n1	Target station number  Designate the target station number.	1 to 64 (constant) Bit device digit designation * <sup>2</sup> Word device * <sup>3</sup>
(S)	Read data storage head device (target station)  Designate the head device of the target station that stores the data to read.	T, C, D, W
(D1)	Read data storage head device (local station)  Designate the head device of the local station which will store the data to be read.	Word device * <sup>3</sup>
n2	Read data length  Designate the number of data (words) to read.	When reading from Q/QnACPU  1 to 230 (constant)  When reading from PLC CPU other than Q/QnACPU * 5  1 to 32 (constant)  Bit device digit designation * 2  Word device * 3
(D2)	Read completion device (local station)  Designate the device of the local station to turn on one scan when the read is complete.  (D2) OFF: Incomplete ON: Complete  (D2) + 1 OFF: Normal ON: Abnormal	Bit device * <sup>1</sup> Word device bit designation * <sup>4</sup>

- \*1: Bit device ..... X, Y, M, L, F, V, B
- \*2: Bit device digit designation ..... K Digit number Bit device head number
- \*3: Word device ...... T, C, D, W, ST, R, ZR
- \*4: Word device bit designation ...... [Word device], [Bit number]

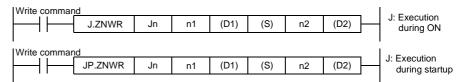
## **POINT**

The normal/abnormal end status when a read is complete is stored in the data link instruction communication completion result (Channel 1) storage area (address: 207) in the buffer memory.

When the read completion device ((D2) + 1) is on due to abnormal end, read the error code (See troubleshooting of User's Manual (Basic).) stored in the area mentioned above, and perform the necessary corrective action.

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## (b) ZNWR instruction [Network number designation]



	Setting details	Setting range	
Jn	Target station network number  Designate the target station network number.	1 to 239	
n1	Target station number Designate the target station number.	1 to 64 (constant): Stations of station number  81H to 89H : All stations of group number  FFH : All stations on the target network number  Bit device digit designation * 2  Word device * 3	
(D1)	Write data storage head device (target station)  Designate the head device of the target station that stores the data to write.	T, C, D, W	
(S)	Write data storage head device (local station)  Designate the head device of the local station which will store the data to write.	Word device * 3	
n2	Write data length Designate the number of data (words) to write.	When writing from Q/QnACPU  1 to 230 (constant)  When writing from PLC CPU other than Q/QnACPU * 5  1 to 32 (constant)  Bit device digit designation * 2  Word device * 3	
(D2)	Write completion device (local station)  Designate the device of the local station to turn on one scan when the write is complete.  (D2) OFF: Incomplete ON: Complete  (D2) + 1 OFF: Normal ON: Abnormal	Bit device * <sup>1</sup> Word device bit designation * <sup>4</sup>	

\*1: Bit device ..... X, Y, M, L, F, V, B

\*2: Bit device digit designation ...... K Digit number Bit device head number

\*3: Word device----- T, C, D, W, ST, R, ZR

\*4: Word device bit designation ...... [Word device]. [Bit number]

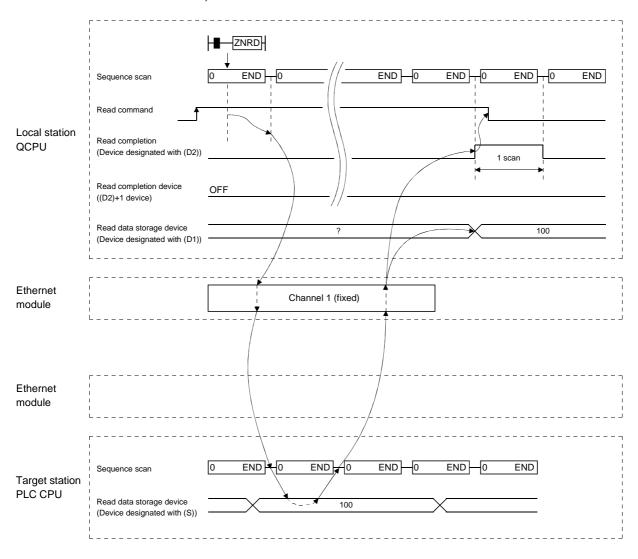
#### **POINT**

The normal/abnormal end status when a write is complete is stored in the data link instruction communication completion result (Channel 2) storage area (address: 209) in the buffer memory.

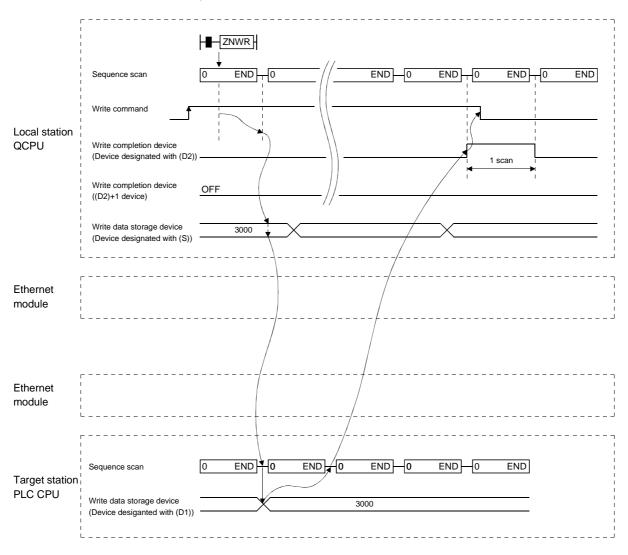
When the write completion device ((D2) + 1) is on due to abnormal end, read the error code (See troubleshooting of User's Manual (Basic).) stored in the area described above, and perform the necessary corrective action.

## (2) Instruction execution timing

- (a) When normal completion
  - 1) ZNRD instruction

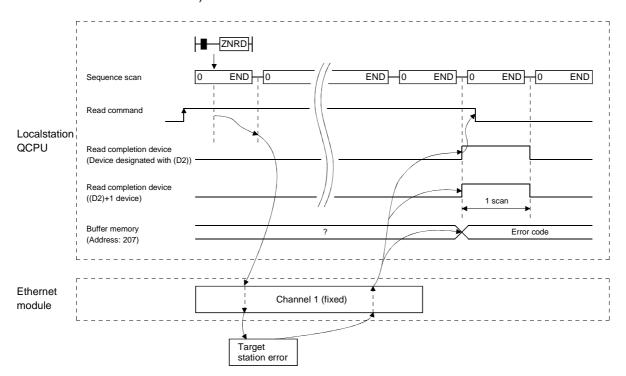


# 2) ZNWR instruction

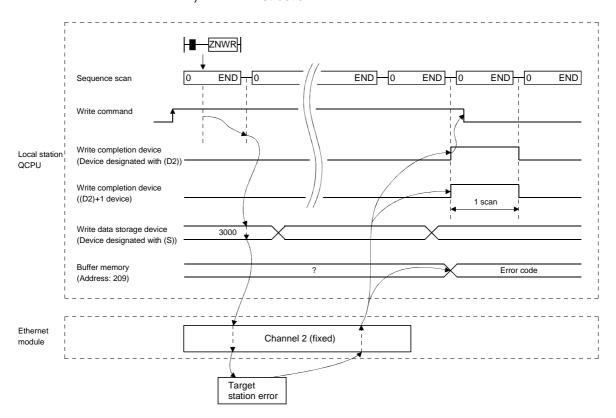


# (b) When abnormal completion

# 1) ZNRD instruction



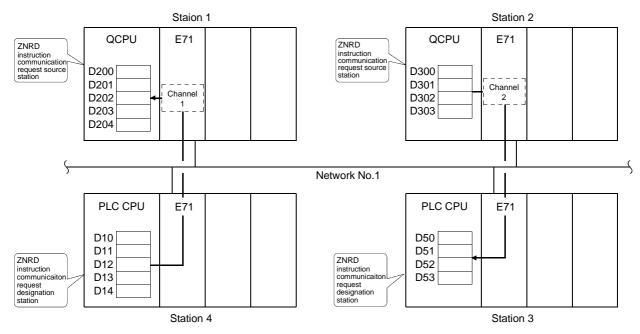
# 2) ZNWR instruction



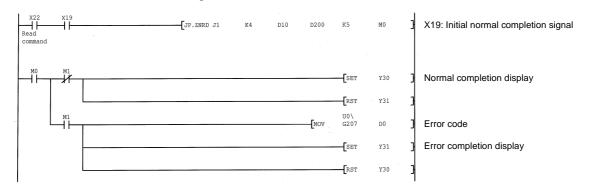
4 - 31 4 - 31

# (3) Program example

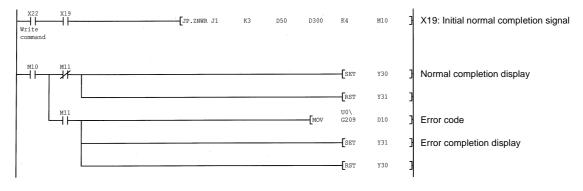
Contents of station 4 D10 to 14 are read to station 1 D200 to 204. Contents of station 2 D300 to 304 are read to station 3 D50 to 53.



# (a) Program of station 1 (ZNRD instruction) When I/O signals of Ethernet module are X/Y00 to X/Y1F



# (b) Program of station 2 (ZNWR instruction)When I/O signals of Ethernet module are X/Y00 to X/Y1F



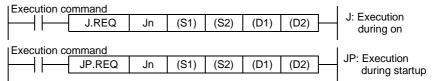
# 4.8 Reading/Writing Clock Data, Remote RUN/Remote STOP (REQ)

This section explains the format and program examples of the REQ instruction that is used to read/write clock data and remote RUN/remote STOP of the Q/QnACPU of other stations.

For details, see Sections 6.7 and 6.8.

# (1) Instruction format

[Network number designation]



# [Network module/Ethernet module start I/O signal designation]

Execution co	ommand						
$\vdash$	G.REQ	Un	(S1)	(S2)	(D1)	(D2)	G: Execution during on
1							during on
Execution co	ommand						05 5 7
$\vdash$	GP.REQ	Un	(S1)	(S2)	(D1)	(D2)	GP: Execution during startup
							aamig otamap

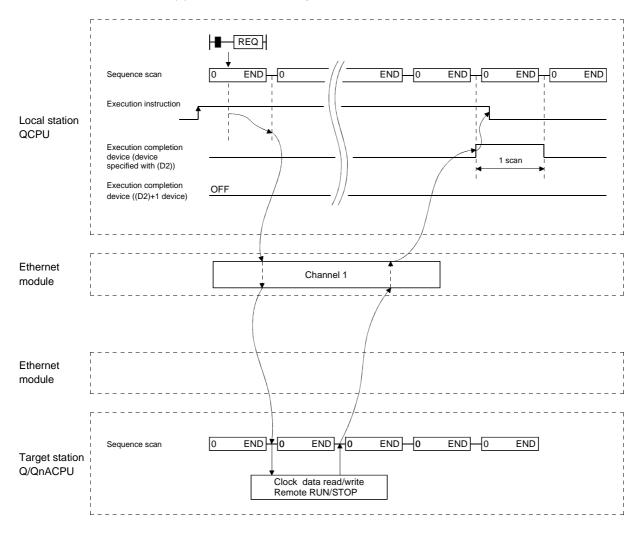
	Setting details	Setting range		
Jn	Local station network number	1 to 239: Network number 254: Network designated in a valid module for other station access.		
Un	Start I/O signal of the local station network module/Ethernet module.  Designate by higher two digits when the I/O signal is expressed by three digits.	0 to FEн		
(S1)	Control data storage head device  Designate the head device of the local station that stores the control data.	Word device * <sup>2</sup>		
(S2)	Request data storage head device (local station)  Designate the head device of the local station that stores the request data.	Word device * <sup>2</sup>		
(D1)	Response data storage head device (local station)  Designate the head device of the local station that stores the response data.	Word device * <sup>2</sup>		
(D2)	Execution completion device (local station)  Designate the device of the local station to turn on one scan when the execution is complete.  (D2)	Bit device * <sup>1</sup> Word device bit designation * <sup>3</sup>		

\*1: Bit device ...... X, Y, M, L, F, V, B \*2: Word device.... T, C, D, W, ST, R, ZR

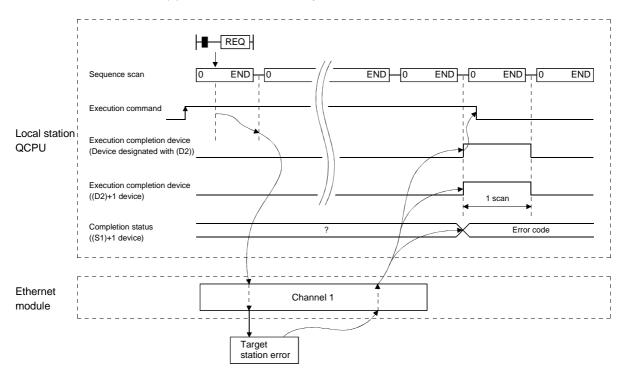
\*3: Word device bit designation ····· [Word device]. [Bit number]

# (2) Instruction execution timing

(a) When normal completion



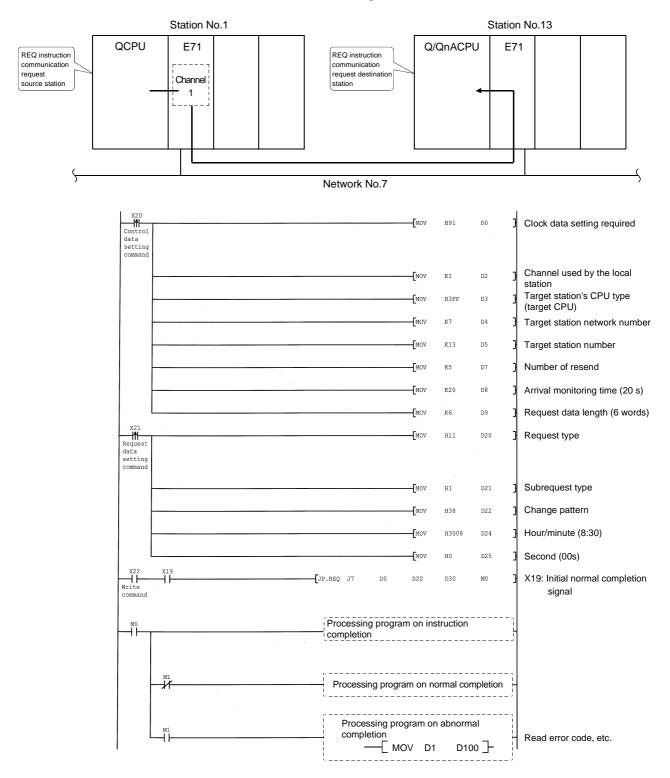
# (b) When abnormal completion



# (3) Instruction examples

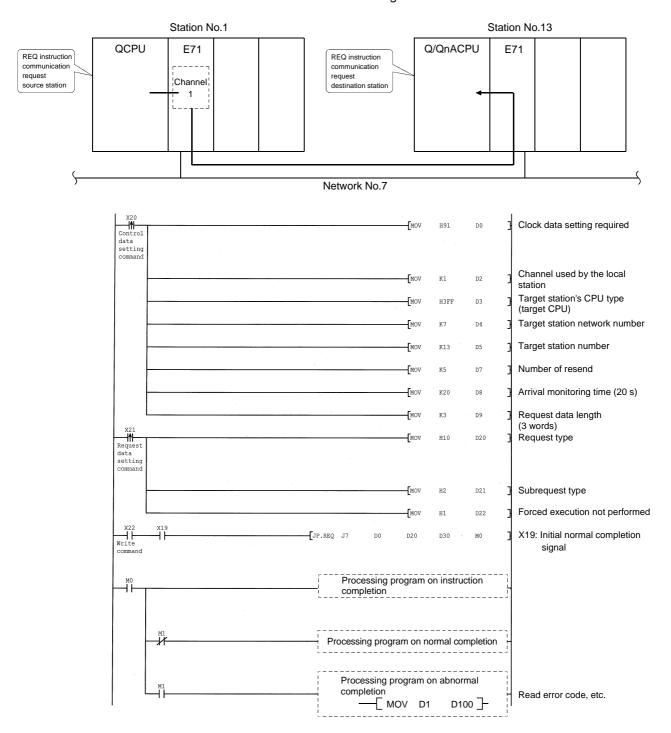
(a) A program that writes the clock data (8:30:00) to the Q/QnACPU of station number 13 using network number 7.

When I/O signals of the Ethernet module are X/Y00 to X/Y1F



(b) This is a program to "Remote STOP" station number 13 on network number 7.

When I/O signals of Ethernet module are X/Y00 to X/Y1F



# 4.9 Error Codes for Data Link Instructions

When the execution results of the data link instruction shown in this chapter end error, the returned error code is the same error code as is shown in the following manual.

Q corresponding Ethernet Interface module Section 11.3.3 of User's Manual (Basic)

The error code for data link instruction is stored in the Ethernet module error log area and the following area:

1) SEND, RECV (RECVS), READ (SREAD),

WRITE (SWRITE), REQ : Control data completion status

((S1) + 1)

2) ZNRD : Buffer memory (Address 207)3) ZNWR : Buffer memory (Address 209)

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# 5 WHEN USING FILE TRANSFER FUNCTIONS (FTP SERVER)

Files in the local station QCPU to which the Ethernet module is installed can be read and written from external device using the Ethernet module file transfer function. In this chapter, how to use (command) the Ethernet module FTP function from external device (personal computer, workstations, etc.) is explained.

# **POINT**

The access destination of files handled using the file transfer function is the local station QCPU in the station to which the Ethernet module is installed. Specify an access target CPU if the local station QCPU is included in a multiple CPU system.

#### 5.1 File Transfer Functions

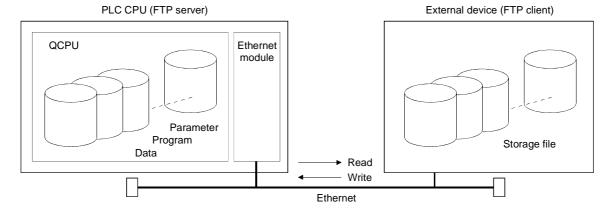
The file transfer functions (hereinafter called FTP server) of the Ethernet module, to perform read/write to the files in the QCPU from a external device side is explained.

The Ethernet module supports the FTP (File Transfer Protocol) server function, which uses the protocol to transfer files between external devices. It functions as the file server for the files in the QCPU.

The FTP commands are used to direct data transfers in file units.

The external device with the FTP client functions, can easily access (read/write) the user-created files in the QCPU directly using the Ethernet module FTP server functions.

- Reading a file from the QCPU (download)
   Reading function for storing the QCPU files in the external device.
- Writing a file to the QCPU (upload)
   Writing function for registering the file in the external device to the QCPU.
- Scanning QCPU files
   Scanning function for checking the files registered in the QCPU, from the external device.
  - \* With these Ethernet module FTP server functions, all user files in the QCPU (parameters, sequence programs, and data files) can be accessed using the FTP commands from the external device.



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# 5.1.1 FTP server support functions of Ethernet module

The FTP commands supported by Ethernet module when it serves as the FTP server are indicated below:

"Write enable setting" and "Write disable setting" shown in the table indicate settings on the GX Developer "Ethernet operation settings" screen. (Set in the item, "Enable writing during RUN.")

The "Remote password" indicates whether the instruction can be executed when the FTP communication port is designated as a port subject to the remote password check in the remote password setting (parameter) for the QCPU of the station to which the Ethernet module is installed.

See Section 5.9 of User's Manual (Basic) for the remote password.

# Client-side user interface command list (supported by Ethernet module)

			PLC CPU statu	S	Remote	password	Remark
Command	Function	D	During	RUN	\A/I=:I=		
Command	Function	During STOP	Write enable setting	Write disable setting	While unlocked	While locked	
binary	Notify to transfer without converting file	0	0	0	0	×	
bye	Disconnect and end the connection with FTP server	0	0	0	0	0	
close	Disconnect the line with FTP server	0	0	0	0	0	
delete	Delete QCPU file	0	O (* 1)	×	0	×	
dir	Display QCPU file information	0	0	0	0	×	
get	Read file from QCPU	0	0	0	0	×	
ls	Display QCPU file names	0	0	0	0	×	
mdelete	Delete QCPU file	0	○ ( * <sup>1</sup> )	×	0	×	
mdir	Store QCPU file information to display file	0	0	0	0	X	_
mget	Read file from QCPU	0	0	0	0	X	
mls	Store QCPU file names to a file	0	0	0	0	×	
mput	Write file to QCPU	0	0	×	0	×	
open	Connect with FTP server	0	0	0	0	0	
put	Write file to QCPU	0	0	×	0	×	
pwd	Display QCPU current directory	0	0	0	0	×	
quit	Disconnect and end the connection with FTP server	0	0	0	0	0	
quote	Send FTP server sub-command	0	0	0	0	0	Can only use Ethernet module dedicated commands ( * 2)
rename	Change QCPU file name	0	0	×	0	×	
user	Enter user name and password for Ethernet module	0	0	0	0	0	_

- \*1 The parameter file and the sequence program file cannot be deleted during RUN.
- \*2 The list of Ethernet module dedicated commands used along with the quote command is described.

When executing the commands from the FTP client, attach the command after the "quote" command.

(Example) When executing the stop command.

Enter the following in the command prompt. quote stop <ret>

			PLC CPU statu	S	Remote	password	
Command	Function	D	During RUN		\A/I=:I=		Remark
Command	Function	During STOP	Write enable setting	Write disable setting	While unlocked	While locked	Remark
status	Display QCPU operation information	0	0	0	0	×	
stop	Set QCPU to STOP state	0	0	0	0	×	
run	Set QCPU to RUN state	0	0	0	0	×	
change	Display/change QCPU file attributes	0	0	×	0	×	
cpuchg	Designates an access target CPU when configurating the multiple CPU system or displays the present access target CPU.	0	0	0	0	×	Ethernet module-FTP server dedicated commands
keyword-set	Set/display/clear QCPU file access keywords	0	0	0	0	×	Commanus
Password- lock	Change status of remote password from unlock to lock	0	0	0	0	×	
	Change status of remote password from lock to unlock	0	0	0	0	0	

# POINT

Some of the commands in the table may not operate as described in this manual depending on the client-side FTP application.

See the manual for the FTP client side (external device), and confirm the functions and operation methods as well.

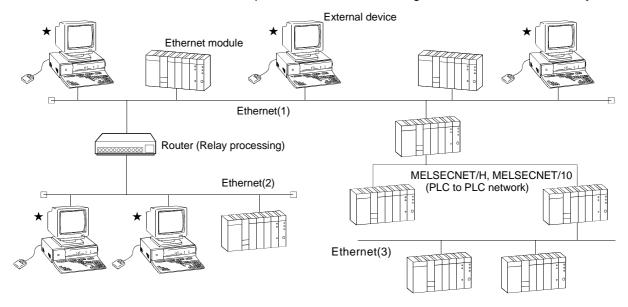
# 5.2 File Transferable Range

The file transferable range from the external device (QCPU with Ethernet module installed station) is explained.

The file transfer operation from the external device using the Ethernet module FTP server function can be performed from any external device with Ethernet module on the Ethernet.

When the router relay function is used, the external device on the Ethernet connected via the designated router can perform FTP functions.

File transfers can be performed from the following external device with the ★ symbol.



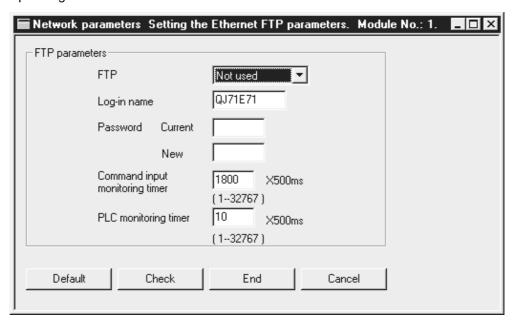
\* File transfers cannot be performed from the external device on the Ethernet (3) which is connected via MELSECNET/H, MELSECNET/10.

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# 5.3 FTP Parameter Settings for File Transfer from GX Developer

This section explains how to set the Ethernet FTP parameters for the file transfer (FTP).

Select [GX Developer] - [Network parameters] to start the [Setting the Ethernet FTP parameters] screen. For details on how to display this screen, see the GX Developer Operating Manual.



# FTP parameter settings

Item name		Description of setting	Setting range/Selections	
FTP		Select whether or not to use the FTP function.	<ul><li>Do not use</li><li>Use</li></ul>	
Log-in name		Set the log-in name when a communication destination requests (log-in) file transfer to the Ethernet module by external device.	"QJ71E71"	
	Current	Set the password when a communication destination requests file transfer to the Ethernet module by external device.	_	
Password New		Set the new password when a communication destination requests file transfer to the Ethernet module by external device.	_	
Command input monitoring timer		Set the monitoring time for the Ethernet module to monitor the command input time from the FTP client.	1 to 32767	
PLC monitoring timer		Set the monitoring time for the Ethernet module to monitor the operation of the local station's CPU.	1 to 32767	

(1) FTP (Address: 4H ... b8, b9); Default value: Do not use the FTP function

Set whether or not to use the FTP function of the Ethernet module.

Item	Explanation
	Use the FTP function.
FTP	Do not use the FTP function.

- (2) Log-in name and password (Address: 3В0н), (3В6н); Default value: QJ71E71
  - (a) Set the log-in name and password for the external device to request (log-in) file transfer to the Ethernet module in order to use the FTP server function of the Ethernet module.
  - (b) If the FTP log-in name is changed and invalid characters are entered, "QJ71E71" is set as the log-in name.
  - (c) If the password is changed and invalid characters are entered, "QJ71E71" is set as the password.
- (3) Command input monitoring timer (address: 3BAн); Default value: 1800 (0708н) (15 min)
  - (a) Set the monitoring time for the Ethernet module to monitor the command input time from the FTP client when it operates as the FTP server.
  - (b) It is recommended to use the default value for this timer value as much as possible.
    - When changing the setting value, determine the command input monitoring timer value upon consulting the administrator of the external device or system.
  - (c) Designate the setting value in the range of <1H to 7FFFH/1 to 32767>. (15 min at the default value of 1800)
    - The FTP connection is disconnected if there is no command input from the FTP client side within the time designated by the command input monitoring timer value after the FTP client log-in.
    - When restarting the file transfer, start over from the log-in operation again.
- (4) PLC monitoring timer (address: 3BBH); Default value: 10 (000AH) (5 s)
  - (a) Set the monitoring time for the Ethernet module to monitor the operation of the local station's QCPU when the Ethernet module is operating as the FTP server.
  - (b) It is recommended to use the default value for this timer value as much as possible.
    - When changing the setting value, determine the CPU monitoring timer value upon consulting the system administrator.
  - (c) Designate the setting value in the range of <1H to 7FFFH/1 to 32767>. The FTP connection is disconnected if an ACPU monitoring error is detected after the FTP client log-in.
    - When restarting the file transfer, make sure that the local station's QCPU is operating normally and then start over from the log-in operation again.

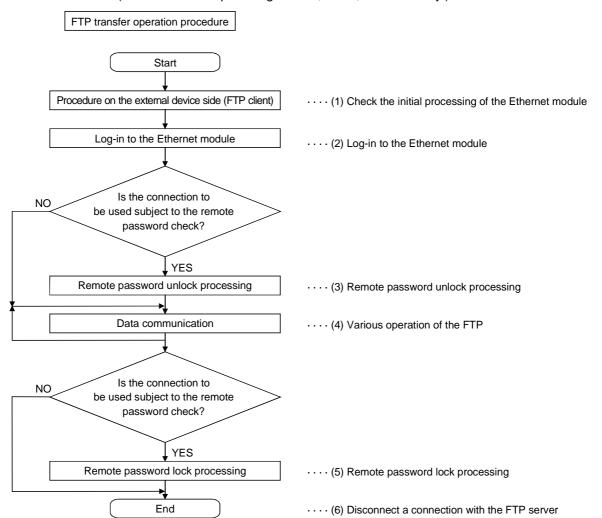
5 - 6 5 - 6

# 5.4 Procedure and Required Processing on the External Device Side (FTP Client)

This section explains the procedure and required processing on the external device side for using the FTP server function of the Ethernet module.

In the explanation, the FTP operation commands and input formats used for the applicable operations are shown.

(<ret> indicates input using the CR, Enter, or Return key.)



# (1) Checking the initial processing of the Ethernet module

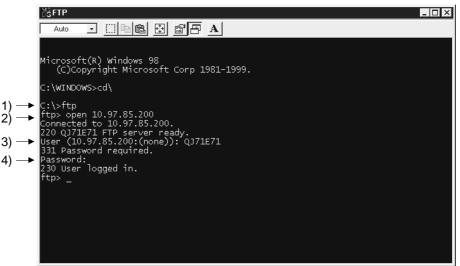
Make sure that the Ethernet module's initial processing has normally completed by checking the LED display/input signal of the Ethernet module.

- LED display: The [INIT] LED on the front of the Ethernet module flashes.
- I/O signal: The initial normal completion signal (X19) turns on.

# (2) Log-in to the Ethernet module

Once the Ethernet module's initial processing has completed normally, log in to the Ethernet module.

(Example) Start FTP from MS-DOS prompt of Microsoft® Windows® 98 Operating System



- Start FTP
- (ftp<ret>).
- 2) Connect with the FTP server (open IP address of the FTP server <ret>).
- Designate the log-in name (log-in name (default value: QJ71E71) <ret>).
   Designate the password (default value: QJ71E71) <ret>).
- \* When logging in, use the FTP log-in name and password set on the "Ethernet FTP parameter settings" screen for setting the log-in name and password. Upon receiving the log-in name and password from the external device (FTP client), the Ethernet module (FTP server) checks whether they match with the FTP log-in name and password set in the FTP parameter setting area of the buffer memory.

File transfer to the Ethernet module is allowed when the log-in name and password match, and not allowed if they do not match.

# (3) Remote password unlock

Changes the status of the remote password from lock to unlock if the FTP communication port has been designated as a port subject to the password check using the remote password setting. (quote password-unlock remote password <ret>)

### POINT

If the FTP communication port has been designated as a port subject to the password check, other commands cannot be used until the remote password status is unlocked.

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# (4) Various operation of the FTP

- Designate an access target CPU if the QCPU is configured as a multiple CPU system.
  - \* The control PLC of the Ethernet module will be the access target CPU after login.

(quote cpuchg access target CPU <ret>)

- Notifies file transfer to a target file without converting the file. (binary <ret>)
- 3) If a password is registered in the QCPU file for file transfer, sets that password in the Ethernet module.

(quote keyword-set password <ret>)

4) Performs the file transfer operation using the FTP commands described in Section 5.6.

# **POINT**

Writing to a parameter file used in the current operation of the QCPU and to a file of the running sequence program that is stored in the QCPU program memory is performed after placing the QCPU in the STOP status.

# 5) Remote password lock

Changes the status of the remote password from unlock to lock if the FTP communication port has been designated as a port subject to the remote password check using the remote password setting. (quote password-lock <ret>)

6) Disconnecting a connection with the FTP server

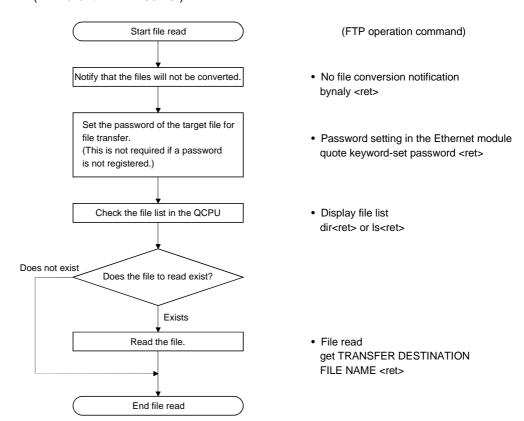
The connection with the FTP server is disconnected and various FTP operations ends. (bye <ret>)

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### File transfer operation procedure example

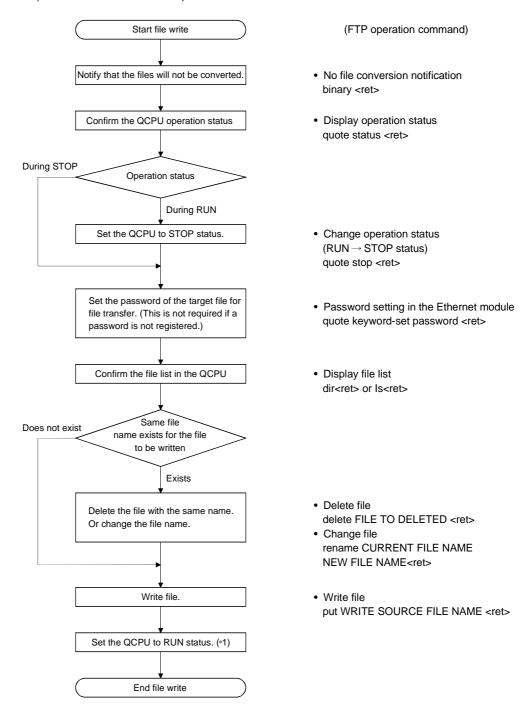
The following two procedures performed between log in and log out are explained as FTP operation examples:

- Read the sequence program file from the QCPU
- · Write the sequence program file to the QCPU
- \* If the FTP communication port has been designated as a port subject to the remote password check, perform the remote password unlock processing/lock processing, in compliance with the FTP transfer operation procedure described in Section 5.4.
- The procedure to read the sequence program file from the QCPU (FTP client ← FTP server)



5 - 10 5 - 10

Procedure to write the sequence program file to QCPU (FTP client → FTP server)



\*1 The QCPU must be set to STOP  $\rightarrow$  RUN  $\rightarrow$  STOP  $\rightarrow$  RUN.

When restarting the QCPU operation after writing a file, it is recommended to set QCPU to RUN with the key switch.

The QCPU can change its status from STOP  $\rightarrow$  RUN from the FTP command, but caution must be taken to the PLC system operations.

5 - 11 5 - 11

# 5.5 Precautions when Using the File Transfer Functions

The precautions when using the Ethernet module FTP server functions are explained.

# Precautions when designing a system which uses file transfer functions

#### (a) For the system

When performing file transfers with the system in operation or controlling the status of the PLC, design the system (such as configuring an interlocking circuit in the sequence program) so that the safety of the overall system is always maintained.

#### (b) For external devices

Some of the FTP operation commands on the FTP client (external devices) supported by the Ethernet module as a FTP server may not operate as described in this manual, depending on the client side FTP application. See the manual on the FTP client (external devices), and confirm the functions and operation methods.

#### (c) For the QCPU

- 1) Only files that can be created/generated by the user with GX Developer can be transferred. (See section 5.6.2.)
- File transfers can only be performed to the local station QCPU with the Ethernet module installed.
   Designate an access target CPU if the local station's QCPU is configured as a multiple CPU system.
- 3) When file read/write is performed by the file transfer functions while QCPU is running, the QCPU's sequence scan time may take longer than when using Ethernet module's other functions, and the file read/write take a few minutes or longer depending on the file size or sequence scan.

The file read/write processing time may take even longer depending on various conditions such as the Ethernet line load (line traffic), number of connections used at the same time (exchange processing which uses another connection), and the system configuration.

(2) Precautions when starting up the Ethernet module
When the QCPU is write-protected (DIP switch 1 is on), file transfers which
perform write (attribute change, file write, etc.) cannot be performed.

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# (3) Precautions common to any usage of the file transfer functions

(a) For external device

When a time-out error occurs during file transfer using the FTP function, the FTP function line is closed (disconnection) regardless of the GX Developer setting.

When restarting the file transfer, perform the log-in operation to the Ethernet module from the FTP client again.

#### (b) For the QCPU

- 1) If a password is registered in the target file for file transfer, transfer that password (set in the Ethernet module) using the FTP operation command, quote keyword-set, after log-in.
  - If a password is registered, that file cannot be accessed unless a
    password of the same character string is designated.
     The password is a character string for file access that the user
    registers in the QCPU and it allows/prohibits access to the target file.
- 2) The QCPU files of target file transfer must be only the files in the root directory for each memory.
- 3) When the QCPU file begin accessed, do not perform any QCPU key switch operations, change operation status with GX Developer (such as RUN → STOP and STOP → RUN), turn off power, reset power, or install/remove the memory card. If any of these operations are performed, the QCPU files will corrupt and the QCPU may not be able to start again.
- 4) Do not perform any file operations (read/write/change file information) from GX Developer, etc. when the FTP function is in operation. When file operations are performed from a peripheral device, etc. while the FTP function is in operation, the FTP function may abnormally end.
- 5) If the FTP communication port is designated as a port subject to the remote password check, perform the file transfer operation after changing the remote password status from lock to unlock. Perform the lock processing for the remote password when the file transfer processing is completed.
  - \* If the FTP communication port is not designated as a port subject to the remote password check, the operation is completed normally when the remote password unlock processing is performed.
  - \* The remote password is a character string registered in the QCPU with the GX Developer by user and data to allow/prohibit access to the QCPU of another station via the QCPU of the station installed Ethernet module.
- (4) Precaution when logging in to the Ethernet module (FTP server)
  Only one external device (FTP client) can log in to the Ethernet module at a time.

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# (5) Precautions when writing a file

- Operation to overwrite an existing file cannot be performed.
   Either delete corresponding file using the file delete command (delete, mdelete), or change the file name using rename command before the file is written.
- 2) The sequence program file set in the parameter file currently used for the QCPU operation cannot be written. Set the QCPU to the stop state, then write in the file.
- 3) File transmission (attributes change, file write, etc.) for file write can only be conducted for the QCPU program memory or the memory card RAM area.
- 4) Check the number of files that can be registered to the drive for the files to be stored. File write cannot be performed to a drive where the number of files has already reached the allowed number of registered files.
  - \* The files are stored in the designated drive's cluster size units.
- 5) Any drives which fit in the size of the continuous unused clusters in the designated drive memory can be written.
- 6) When restarting the QCPU operation after writing a file, it is recommended to set to the run status using the QCPU key switch. The QCPU can be switched from STOP to RUN using the FTP command, but sufficient caution must be taken for the PLC system operations.
- 7) When writing files, the Ethernet module creates temporary work files (FTP\_Ixxx.TMP) in the QCPU.
  - The temporary files are automatically created in the designated drive during the file write (put or mput), and the file name is changed to the designated file name after the operation is completed.
  - The "xxx" in the temporary file name "FTP\_lxxx.TMP" is the upper three digits of the four digits representing the Ethernet module's I/O signals from the QCPU.
  - \* The temporary file is automatically deleted when the file write is successfully completed, line is shut down during transfer, or a file capacity error occurs with the QCPU.
- 8) The temporary work file may remain in the designated drive when the QCPU power is disconnected or reset during the file write.
  When the temporary file remains in the drive, delete the file using the FTP command.
- 9) In the case where file deletion and file writing are repeated while the QCPU is in RUN status, the file size must be fixed in advance. If a file is deleted and then writing of another file larger than the deleted one is attempted, a 402B error will occur disabling the file writing.

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# (6) Precautions when deleting files

- 1) When determining the timing to delete files, consider the system operation as a whole including the functions of QCPU and GX Developer.
- 2) The parameter file and sequence program file can not be deleted during the QCPU is performing "RUN".
  Delete these files after setting the QCPU to the stop status.
- 3) Files with read-only attribute and files that are locked from another device or function cannot be deleted.
  - \* The file attributes can be changed using the FTP operation command, "quote change".
- 4) File deletion can only be conducted for the QCPU program memory or memory card RAM area.
- 5) After deleting a file with the QCPU in RUN status, do not read or write the data of the deleted file by the sequence program. Doing so may result in an operation error detected in the QCPU.

5 - 15 5 - 15

# 5.6 FTP Commands

The FTP operation commands on the FTP client side (external devices) supported by the Ethernet module FTP server are described.

# 5.6.1 File designation method

The file designation method in the FTP operation command from the FTP client side is explained.

# Designation descriptions

- '': The part with the single quotation mark '' indicates one argument.
- ]: The part with the brackets [ ] indicates that it is optional.

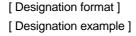
# (1) Password

If a password is registered in the target file for file transfer, the password must be set in the Ethernet module prior to file transfer.

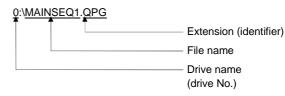
See the "quote keyword-set" command in Section 5.6.4.

# (2) File path

- (a) The QCPU designates the file by differentiating the drive name and file name.
- (b) When designating a file in the QCPU using the FTP functions, designate the file in the following manner:



['drive name': \] 'file name' . 'extension'



#### [ Designation details ]

- 1) Drive name (drive No.)
- Designates the drive name for the memory used for file transfer.
- The relationships between the QCPU memory used and drive name are as follows.

Drive name	Memory used
No designation	Parameter valid drive designated with DIP switches
0	QCPU built-in program memory
1	Memory card (RAM) · · · · · SRAM card
2	Memory card (ROM) · · · · · Flash card, ATA card
3	QCPU built-in standard RAM
4	QCPU built-in standard ROM

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- 2) File name, extension
- The corresponding file for the file transfer is designated.
- The file name must be designated according to the GX Developer file name rules.

Alphabets (uppercase), numbers, symbols, can be used. Alphabets (lowercase) cannot be used.

File name: Max. 8 characters Extension: Max. 3 characters

- For the extension (identifier), the name fixed by the QCPU must be used. The corresponding file extension is designated as seen in section 5.6.2.
- See the GX Developer Operating Manual for the details about the file names and extensions.
- When using a FTP operation command which can designate multiple files, the files (file names and extensions) are designated using wild card symbols,
   "\* /?."
  - \*: Files containing the characters before "\*" and any set of characters (including none) replacing the "\*" are designated.
    - (Example. 1) When designating all files with the "QPG" extension \*.QPG
    - (Example. 2) When designating file names which start with "MAIN" and the extension is "QPG"

      MAIN\*.QPG
  - ?: The files containing the text string designated (including none), replacing? with any character including none. ("?" can be used multiple times.)
    - (Example. 1) The letter after "MAIN" is any character and the extension is "QPG"

MAIN?SEQ.QPG

- (Example. 2) To designate all files whose extension start with "QP" \*.QP?
- (Example. 3) To designate all files whose extension start with "Q" \*.Q??

#### **POINT**

- (1) In the description of the FTP operation commands, the file name indicates both the file name and extension.
- (2) It is recommended to use the following method to treat the file name from the external device.
  - Use the ASCII code characters (upper case for the alphabet letters) for the file to be written to the FTP server.
  - Do not change the file name for the file read from the QCPU.
- (3) Each memory for QCPU does not have any sub-directories. Each file is stored in the root directory.

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# (3) Attributes

The following is designated when changing the attributes of the file stored in the QCPU drive to be transferred:

"r" (Read Only) ↔ "w" (read/write enabled)

See the "quote change" command in section 5.6.4.

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# 5.6.2 QCPU user file list

The user-created files (files that are/can be created by the user with GX Developer) that can be designated for file transfer are described below:

Type	File type	File identifier	Drive that can store the file (See section 5.6.1.)					Remark	
			0	1	2	3	4		
	Parameters	QPA	0	0	0	0	0	1 file/1drive	
For programs	Sequence program (* 1)	000			0	0	0		
	SFC program	QPG	0					_	
	Device comments (* 1)	QCD	0	0	0	0	0	Max. 124 files	
	Device initial values (* 1)	QDI	0	0	0	0	0		
For device	File registers	QDR	×	0	0	0	0		
	Simulation data	QDS	×	0	×	0	×	_	
	Local device	QDL	×	0	×	0	×	1 file/CPU	
	Sampling trace data	QTS						_	
	Status latch data	QTL			\		\		
For debugging	Program trace data	QTP	×		×	0	×		
	SFC trace data	QTR							
For diagnosis	Error log data	QFD	×	0	X	0	×	_	

 $\bigcirc$  :Can be stored  $\times$  : Cannot be stored

\*1 A password can be registered in program files, device comment files and device initial value files of the designated memory (program memory/standard ROM/memory card).

See the QCPU (Q mode) User's Manual (Function Explanation/Program Fundamentals) for details on the password.

# POINT

- Each memory for QCPU does not have any sub-directories. The files are all stored in the root directory.
- (2) See the QCPU User's Manual for the restrictions and details of the QCPU user files.

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# 5.6.3 Response code

For information regarding the response codes that are returned to the external device (FTP client) by the Ethernet module (FTP server), see the manual for the FTP client for the codes except the following 4000H.

Response code	Reference
Other than the following	See the manual for the FTP client.
4000н	
to	See the QCPU User's Manual and correct.
4FFF <sub>H</sub>	
С000н	
to	See Section 11.3.3 of User's Manual (Basic) and correct.
CFFFH	

# REMARK

123

The first two digits of the response code is described below:

- 1 : Response regarding the start of
  - the request processing
    2: Response regarding the successful end of the request processing
  - 3 : Response indicationg the necessity for additional information pertaining to the request processing
  - 4 : Response regarding abnormal end of the request processing
  - 5 : Response regarding abnormal end of the request processing

- 0 : Response regarding a syntax error
- 1 : Response regarding information request, such as status
- 2: Response regarding control or data connection
- 3 : Response regarding log-in processing or account processing
- 4: (Unused)
- 5 : Response regarding the FTP server status

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# 5.6.4 FTP operation command

The FTP operation command functions and usage on the FTP client (external device) side supported by the Ethernet module FTP server are explained.

# **A**CAUTION

 Some of the FTP operation commands on the FTP client (external device) side supported by the Ethernet module may not perform as explained in this manual, depending on the FTP application used on the client side.

See the manual for the FTP client (external device) as well, and confirm the functions and operation methods.

# (1) FTP server support commands

# binary

[Function] Notifies to the FTP server that the file transfer is performed

without converting the file.

The carriage return code and kanji code are not converted,

either.

The Ethernet module is automatically set to this.

[Designation format] binary (Abbreviated as bin)

bye

[Function] Disconnects the FTP server connection, and ends FTP.

[Designation format] bye [Same function] quit

close

[Function] Disconnects the FTP server connection.

[Designation format] close

delete

[Function] Deletes the file stored in the QCPU.

[Designation format] delete FILE PATH

[Designation example] To delete a file stored in the RAM of memory card:

delete 1:\MAINSEQ1. QPG.

[Caution] • See section 5.5 and 5.6.1.

[Similar function] mdelete

dir

[Function] Displays the file names, created dates, and sizes of the files

stored in QCPU.

[Designation format] dir [drive name:\]

[Designation example] To display detailed information of files stored in the RAM of

memory card:

dir 1:\

[Similar function] Is

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get

[Function] Reads the file from the QCPU.

[Designation format] get TRANSFER SOURCE FILE PATH [transfer destination

file path]

[Designation example 1] Reads the file stored in the RAM area of memory card, and

stores using the same file name:

get 1:\MAINSEQ1.QPG

[Designation example 2] To read the file stored in the RAM area of memory card, and

store using a different file name:

get 1:\SEQ1BAK.QPG \SEQ\SEQ1OLD.QPG

[Caution] • When the transfer destination file path (FTP client side) is not

designated, the file is stored in the FTP client side with the same name as the transfer source file name (on the QCPU

side).

The transfer destination is the connected current directory of

the FTP startup connection.

• See sections 5.5 and 5.6.1.

Is

[Function] Displays the file names of the files stored in the QCPU.

[Designation format] Is [drive name:\]

[Designation example] To display the file names of the files stored in the RAM area of

memory card:

ls 1:\

[Similar function] dir

mdelete

[Function] Deletes the file stored in the QCPU.

When deleting the multiple files, the file name and extension are

designated using wild cards ( \* or ?).

[Designation format] mdelete FILE PATH (abbreviated as mdel)

[Designation example] To delete all files with the extension "QPG" in the files stored in

the RAM area of memory card:

mdelete 1:\ \*.QPG

[Caution] • See sections 5.5 and 5.6.1.

[Similar function] delete

#### mdir

[Function] Stores the detailed information (file name, created date, and

size) of the files stored in the QCPU to the FTP client-side file as

log data.

[Designation format] [Designation example]

[Caution]

mdir transfer source drive:\ transfer destination file path To store the detailed information of the files stored in the RAM

area of memory card to \$990901.LOG file:

mdir 1:\ S990901.LOG

• Always designate "\" directly after the drive name of the transfer source.

• When designating the transfer destination file path (FTP client

side), always designate the transfer source drive name.

• When the transfer destination file path is not designated, the file name set by the FTP application on the FTP client side is used to save the file.

· The transfer destination is the connected current directory of the FTP startup connection.

[Similar function] mls

# mget

[Function] Reads a file from QCPU.

When reading multiple files, the file name and extension for the

file path is designated using wild cards (\* or ?).

Receive confirmation is performed for each file transfer.

[Designation format]

mget FILE PATH

[Designation example] To read all files with extension "QPG" from the files stored in the

RAM area of memory card:

mget 1:\ \*.QPG

[Caution] • The files read are stored on the FTP client side with the same

The destination is the connected current directory of the FTP

startup connection.

• See sections 5.5 and 5.6.1.

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#### mls

[Function] Stores file names of the files stored in the QCPU in a file on the

FTP client side as log data.

[Designation format] mls transfer source drive name:\ transfer destination file path

name

[Designation example 1] To store the file names of the files stored in the RAM area of

memory card to the file S990901F.LOG:

mls 1:\ S990901F.LOG

[Designation example 2] To store the file names of the files in the memory where the

parameter file used for the current operation of QCPU is stored

to the file S990901F.LOG: mls \ S990901F.LOG

[Caution] • Always designate "\" directly after the drive name of the

transfer source.

 When designating the transfer destination file path (FTP client side), always designate the transfer source drive name.

 When the transfer destination file path is not designated, the file name set by the FTP application on the FTP client side is

used to store the file.

The transfer destination is the connected current directory of

the FTP startup connection.

[Similar function]

# mput

[Caution]

[Function] Writes a file to the QCPU.

mdir

When writing multiple files, the file name and extension are  $% \left( 1\right) =\left( 1\right) \left( 1\right)$ 

designated using wild cards ( \* or ?).

When writing multiple files, the send confirmation is performed

for each file transfer.

[Designation format] mput TRANSFER source file path [Designation example] When writing all files with extension "QPG":

mput \* .QPG

The transfer destination is the memory where the parameter

file used for the current operation of QCPU is stored.

The destination file name is the same as the file name on the

FTP client side.

See sections 5.5 and 5.6.1.

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#### open

[Function] Connects to the FTP server by designating the host name or IP

address for the FTP server, along with the FTP log-in name and

password.

FTP server host name is displayed while connected to the

server.

[Designation format] open HOST NAME [user name [password]]

open IP ADDRESS [user name [password]]

Host name: Host name, domain name or synonym of the host

name

IP address: IP address for Ethernet module (designated within

brackets [])

User name: FTP log-in name set during Ethernet module initial

processing

Password : Password set during Ethernet module initial

processing

(See section 5.3 for the FTP log-in name and

password)

[Designation example 1] To connect to the FTP server by designating the host name:

open HOST

[Designation example 2] To connect to the FTP server by designating the IP address:

open [192.0.1.254]

[Designation example 3] To connect to the FTP server by designating the host name and

user name:

open HOST QJ71E71

[Designation example 4] To connect to the FTP server by designating the host name,

user name, and password:

open HOST QJ71E71 QJ71E71

 Normally, the connection can be established by designating the FTP server IP address during FTP startup.

> When designating the domain name, the DNS environment must be set using the network parameters on the FTP client
> ...

ho poor

The password entered from the keyboard is not displayed on

the screen.

put

[Function] Writes a file to the QCPU.

[Designation format] put TRANSFER SOURCE FILE PATH [transfer destination

file path name]

[Designation example 1] To write the file MAINSEQ1.QPG to the RAM area of memory

card with same file name:

put MAINSEQ1.QPG 1:\MAINSEQ1.QPG

 $[Designation\ example\ 2] \\ \ \ \ \ To\ write\ the\ file\ MAINSEQ.QPG\ file\ to\ the\ RAM\ area\ of\ memory$ 

card with different file name:

put MAINSEQ.QPG 1:\MAINSEQ1.QPG

 When the directory is not designated for the transfer source file path (FTP client), the file is written to the connected current directory at FTP server startup connection.

 When the transfer destination file path (FTP server side) is not designated, the file is stored to the memory where the parameter file used for the current QCPU operation is stored.

• See sections 5.5 and 5.6.1.

[Caution]

[Caution]

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pwd

[Function] Displays the QCPU current directory.

[Designation format]

[Caution] • The QCPU disks do not have any sub-directories, and the

files are stored in the root directory.

Therefore, "\" is displayed as the execution result of the pwd

command.

quit

[Function] Disconnects the connection to the FTP server, and ends FTP.

[Designation format] quit [Same function] bye

quote

[Function] Sends the FTP server subcommand (Ethernet module

dedicated command).

[Designation format] quote Ethernet module DEDICATED COMMAND

quote status

Ethernet module dedicated command: See (2).

[Designation example]

[Caution]

• Only the Ethernet module dedicated command shown in (2) can be designated directly after the quote command.

rename

[Function] Changes the QCPU file name.

[Designation format] rename FILE PATH BEFORE CHANGE FILE PATH

AFTER CHANGE (abbreviated as ren)

[Designation example] To change the file name of the file stored in the RAM of

memory card:

rename 1:\MAINSEQ1.QPG 1:\SEQ1OLD.QPG

[Caution] • See section Items 5.5 and 5.6.1.

user

[Function] Enter the user name and password for the connected FTP

server.

[Designation format] User : User name [Password]

User name: FTP log-in name set during Ethernet module

"FTP parameter setting"

Password: Password set during Ethernet module "FTP

parameter setting"

(See sections 5.3 for the FTP log-in name and

password.)

[Designation example 1] To designate the user name:

user QJ71E71

[Designation example 2] To designate both user name and password:

user QJ71E71 QJ71E71

[Caution] • The password entry from the keyboard is not displayed.

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#### (2) Ethernet module dedicated commands

The Ethernet module dedicated commands to be attached to the FTP operation command "quote" are explained.

#### change (Ethernet module dedicated command)

[Function] Displays/changes the file attribute for the file stored in the

QCPU.

[Designation format] When displaying the file attribute:

quote change FILE PATH

Either of the following is displayed as the execution result

after a successful completion:

· When the designated file is a read-only file

: "----R"

• When the designated file is a file with read/write enabled

: "-----W"

[Designation format] When changing the file attribute

quote change FILE PATH ATTRIBUTE

Designate either of the following for the attribute:

• To change to read-only file : r

• To change to read/write enabled: w

[Designation example 1] To display the file attribute for the file stored in the RAM area

of memory card:

quote change 1:\MAINSEQ1.QPG

[Designation example 2] To change the file attribute of the file stored in the RAM area

of memory card:

quote change 1:\MAINSEQ1.QPG r

[Caution] • When the PLC CPU is set to RUN, an error occurs when

the following files are designated:

Parameter file

File currently being executed by the program memory

(drive name:0)

• The attribute changing is possible between read-only file

and read/write enabled file.

• See sections 5.5 and 5.6.1.

#### **POINT**

The file attributes designated using the quote change command are explained.

- (1) When changing the attribute of the file for file transfer, designate the attribute after the change.
- (2) The attributes are for changing the file to read-only or read/write enabled file.
- (3) The attribute can be changed to the following for the files stored in the QCPU memory using this command:

"r" (read-only) ↔ "w" (read/write enabled)

(4) An user-created file has the read/write attribute, if it has not been changed.

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#### cpuchg (Ethernet module's dedicated command)

[Function] This command designates an access target CPU with a

multiple CPU system configuration. Alternatively, it displays

the current access target CPU.

[Designation format] quote cpuchg [access target CPU]

Access target CPU: Designate the CPU to which file access is

to be performed.

Command	Description
quote cpuchg	Checks the current access target CPU.
quote cpuchg controlPLC	Designates the control PLC as the access target CPU.
quote cpuchg no1	Designates the PLC No. 1 as the access target CPU.
quote cpuchg no2	Designates the PLC No. 2 as the access target CPU.
quote cpuchg no3	Designates the PLC No. 3 as the access target CPU.
quote cpuchg no4	Designates the PLC No. 4 as the access target CPU.

• When the command is successfully completed, the execution result is displayed as follows:

When setting the access target CPU:

200 Command Okey

When displaying the access target CPU:

200 Target cpu is "access target CPU"

 If the designated access target CPU does not exist, the following message is displayed.

557 Cpu not found

[Designation example 1] When designating the access target CPU as the control PLC

quote cpuchg controlPLC

[Designation example 2] When displaying the currently selected access target CPU

quote cpuchg

[Caution] The control PLC of the Ethernet module will be the access

target CPU after logging in when the OPEN/USER command

is executed to the Ethernet module.

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## keyword-set (Ethernet module dedicated command)

[Function]

Sets the registered password of the target file for file transfer in the Ethernet module.

Or, display/clear the current password set in the Ethernet module.

\* Use this command only if a password is registered in the target file of file transfer.

The Ethernet module performs a password check when the designated file is accessed.

[Designation format]

quote keyword-set [password]

Password: To set a password, designate the password registered in the file of the target QCPU memory.

Designate "\* \* \* \* " to clear a password set in the Ethernet module.

One of the following is displayed as the execution result for a successful completion.

• When setting a password : 200 Command successful

• When displaying a password: 200 keyword is "password"

When clearing a password : 200 Command successful

To set the password (1234) to the Ethernet module:

quote keyword-set 1234

[Designation example 2] To display the password currently set in the Ethernet module: quote keyword-set

quote keyword-set

To clear the password currently set in the Ethernet module: quote keyword-set \*\*\*\*.

 If a password is registered in the target file for file transfer, set the password in the Ethernet module prior to file transfer.

Designating the password registered in the QCPU target file enables QCPU file operation.

- One password can be set in the Ethernet module. If the target file for file transfer changes and a password is registered in the file which is at the changed destination, reset the password for the new target file in the Ethernet module.
- When logging into the Ethernet module from the external device, the password set in the Ethernet module changes to "\* \* \* \* " (clear)

[Designation example 1]

[Designation example 3]

[Caution]

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#### **POINT**

The password designated using the quote keyword-set command is explained.

- (1) If a password is registered in the target file for file transfer, use this command to set the password in the Ethernet module after logging into the Ethernet module prior to file transfer.
- (2) The password is used so that the QCPU can allow/prohibit access to the target file from outside.
- (3) The password for file access to the QCPU is registered with the GX Developer. The password designated by this command is for operations with the Ethernet module.

The user designates the same character string as that registered with the GX Developer to the QCPU designated file.

#### password-unlock (Ethernet module dedicated commands)

[Function]

Designate the remote password set in the QCPU and perform the unlock processing.

\* This command is used when the FTP communication port is designated as a port subject to the remote password check.

[Designation format] quote password-unlock [remote password]

Remote password: Designate the remote password set in the QCPU parameter.

• The following is displayed as the execution result for a successful completion.

200 Command 0key

 The following is displayed if the remote password does not match.

556 Password Error

 The following is displayed if another command is requested before the remote password unlock processing is performed.

555 Password Locked

[Designation example 1]

To designate the remote password (1234) quote password-unlock 1234

[Caution]

- If the FTP communication port is designated as a port subject to the remote password check, the status will be "locked" when the user logs into the Ethernet module from an external device.
- Executing this command and performing the unlock processing prior to various operation of the FTP enables QCPU file operation.
- If the FTP communication port is not designated as a port subject to the remote password check, the operation is completed successfully when the remote password unlock processing is performed.

# password-lock (Ethernet module dedicated commands)

[Function]

Designates the remote password set in the QCPU as unlocked and performs the lock processing.

\* This command is executed if the FTP communication port is designated as a port subject to the remote password check.

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[Designation format] quote password-lock

The following is displayed as the execution result for a

successful completion.

200 Command 0key

[Designation example 1] To designate the remote password (1234)

quote password-lock

#### run (Ethernet module dedicated command)

[Function] Sets the QCPU to the run status (remote run).

Device memory clear can be designated when setting to the run

status.

[Designation format] quote run [mode [clear mode]]

Mode: Designate whether to force a remote run.

0: Normal run (default value)

1: Forced run

Clear mode: Designate whether to clear (initialize) the QCPU

device memory when starting the remote run

operation

0 : Do not clear the device (default value)

 ${\bf 1}$  : Clear everything except for the latch range

 $\ensuremath{\mathbf{2}}$  : Clear everything including the latch range

The following message is displayed as the execution result when completed successfully.

• Displayed message: 200 Command successful

[Designation example 1] To perform a normal remote run with the designation not to

clear the device memory.

quote run

[Designation example 2] To perform a forced remote run with the designation not to clear

device memory.

quote run 1

[Designation example 3] To perform a forced remote run with the designation to clear all

device memory except for the latch range.

quote run 11

[Caution] • The forced execution mode is only used to allow forced remote runs from another device when the QCPU cannot

perform remote runs due to problems in the device which

issued the remote stop for the QCPU.

When a normal run is designated and the system is already set to the stop or pause status by another device, the system

is not set to the run status.

 Designate the clear mode of the device memory during the operation startup depending on the system configurations.
 After the QCPU performs the clear operation, the system runs according to the PLC parameter settings (PLC file setting →

device initial values).

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#### status (Ethernet module dedicated command)

[Function] Displays the QCPU operation information is displayed. This is a

command to check the QCPU operation information before

executing file transfer to the QCPU.

[Designation format] quote status

One of the following is displayed as the execution result for a

successful completion.

When the QCPU is at a run status : "RUN"
 When the QCPU is at a stop status : "STOP"
 When the QCPU is a pause status : "PAUSE"

## stop (Ethernet module dedicated command)

[Function] Set the QCPU to the stop status (remote stop).

[Designation format] quote stop

The following message is displayed as the execution result for

a successful completion.

• Displayed message: 200 Command successful

[Caution] • For the QCPU program file, etc., write this command after the

QCPU is in the stop status.

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# **6 DEDICATED INSTRUCTIONS**

The dedicated instructions are used to simplify programming for using the functions available for the intelligent function module.

This chapter explains the dedicated instructions for the functions that are explained in this manual, among those dedicated commands available for the Ethernet module that can be used by QCPU.

#### 6.1 Dedicated Instruction List

The following table lists the dedicated instructions explained in this chapter.

Appli	cation	Dedicated instruction	Functional description	Reference section
F F '' '' '		MRECV	Reads received e-mails.	Section 6.2
For E-mail sending/re	eceiving	MSEND	Sends e-mails.	Section 6.3
		READ	Reads data from word devices of other station.	Section 6.4
		SREAD	Reads from other station's device (with completion device).	Section 6.10
	For reading/writing	WRITE	Writes to other station's device.	Section 6.12
For communication	device data	SWRITE	Writes to other station's device (with completion device).	Section 6.11
with the PLC CPU of		ZNRD	Reads from other station's device (for ACPU).	Section 6.13
other station		ZNWR	Writes to other station's device (for ACPU).	Section 6.14
		SEND	Sends data to other station.	Section 6.9
* Data link instruction	For message (any data) sending/ receiving	RECV	Reads receive data from other station. (For the main program)	Section 6.6
		RECVS	Reads receive data from other station. (For interrupt programs)	Section 6.6
	For reading/writing clock data	REQ	Issues a remote RUN/STOP request to other station.	Section 6.7
	Remote RUN/STOP		Reads/writes clock data of other station.	Section 6.8

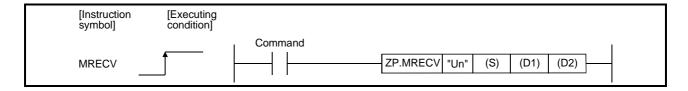
### **POINT**

- (1) The user should not change data (control data, request data, etc.) designated with any of the dedicated instructions until the execution of that instruction is completed.
- (2) Only PLC CPUs of QCPU modules can handle the higher two digits of the year (Gregorian calendar) in the clock data that are processed with dedicated instructions.
  - Thus, when executing dedicated instructions on PLC CPUs other than QCPUs, the data portion of the higher two digits of the year is treated as "00H."
- (3) All dedicated instructions must be executed online.
  If any of the dedicated instructions is executed offline, no error will occur, but the execution of the dedicated instruction will not be completed.

# 6.2 MRECV Instruction

This instruction reads received e-mails.

					Applicat	ole device			
Set data	Internal device File register		MELSECNET/H, MELSECNET/10 Direct J□\□		Special module U□\G□	Index register Zn	Constant K, H, \$	Others	
	Bit	Word		Bit	Word				
(S)			0			_		_	
(D1)			0			_		_	_
(D2)	0		0			_		_	_



#### Set data

Set data	Description	Set by	Data type
"Un"	Start I/O signal of the local station's Ethernet module. (00 to FE: Higher 2 digits of the 3-digit I/O signal)	User	Character string
(S)	Head device of the local station that stores the control data.	User, system	
(D1)	Head device of the local station that stores the contents of the received e-mail (header + attached file).	System	Device name
(D2)	Local station device that is turned on for one scan by the completion of the instruction.  (D2)+1 is turned on if the instruction execution completes abnormally.	System	Bit

The local devices and the file register for each program cannot be used as devices used in setting data.

POINT

The MRECV instruction can be executed only when the local station is a QCPU.

REMARK

The number of steps for the MRECV instruction is 10.

# Control data

Device		Item	Set data	Setting range	Set by ( * <sup>1</sup> )	
(S) + 0	Execution type/complete type		b15 to b10 b9 b8 b7 to b0  0 2) 0 1) 0 0  1) Complete type (bit 7)  Designate whether or not the setting of the clock data is required at abnormal completion.  0: Clock data setting is not required.  The clock data at error occurrence is not set in (S) + 11 to (S) + 15.  1: Clock data setting required.  The clock data at error occurrence is set in (S) + 11 to (S) + 15.  2) Execution type (bit 9) (* 2)  Designate whether or not to inquire if there are more mails on the server after reading receive mails.  0: Do not inquire. (Do not read the receive mail information.)  1: Inquire (Read the receive mail information)	0000н 0080н 0200н 0280н	User	
(S) + 1	Completion	status	Store the status at completion of the instruction.  0: Normal  Other than 0: Abnormal (error code) ( $*$ $^3$ )	1	System	
(S) + 2	Mail number to be read		Designate the mail number to be read when multiple mails are received.  0: Head mail 1 or higher: Designated mail	0 or higher	User	
(S) + 3 to (S) + 8	System area		_		_	
(S) + 9	Receive data length	At instruction execution	Designate the data length (header + attached file) of the e-mail that can be stored in (D1) + 0 to (D1) + n (header: 1 to 373, attached file: 1 to 6144).  0: Adjust to the data length of the received e-mail.  1 to 6517: The number of data that can be stored in (D1 to D1 + n)	0 to 6517 (Words)	User	
			At instruction completion	This stores the data length (header + attached file) of the e-mail stored in (D1) + 0 to (D1) + n.  1 to 6517: The number of received data stored in (D1) + 0 to (D1) + n	* Including the header length described below	System
(S) + 10	Header length	At instruction execution	Designate the data length of the mail's header that can be stored in (D1) + 0 to (D1) + n.  0: Adjust to the header data length of the received mail.  1 to 373: The number of data that will be stored in (D1 to D1 + n).	0 to 373 (Words)	User	
	lengur	At instruction completion	Store the data length of the mail's header that was stored in (D1) + 0 to (D1) + n.  1 to 373: The number of receive data that was stored in (D1 to D1 + n).	(vvoids)	System	
(S) + 11	Clock set flag		Store the valid/invalid status of the clock data in ((S) + 12 to (S) + 15).  0: Invalid 1: Valid	0, 1	System	
(S) + 12	Clock data		Higher 8 bits: month (01 <sub>H</sub> to 12 <sub>H</sub> ), lower 8 bits: last 2 digits of year (00 <sub>H</sub> to 99 <sub>H</sub> )			
(S) + 13			Higher 8 bits: hour (00 <sub>H</sub> to 23 <sub>H</sub> ), lower 8 bits: date (01 <sub>H</sub> to 31 <sub>H</sub> )		C) 10t	
(S) + 14	(set only wh	nen abnormal)	Higher 8 bits: second (00 <sub>H</sub> to 59 <sub>H</sub> ), lower 8 bits: minute (00 <sub>H</sub> to 59 <sub>H</sub> )	_	System	
(S) + 15			Higher 8 bits: first 2 digits of year (00 <sub>H</sub> to 99 <sub>H</sub> ), lower 8 bits: day of the week (00 <sub>H</sub> (Sunday) to 06 <sub>H</sub> (Saturday))			

#### Receive data

Device	Item	Set data	Setting range	Set by ( $^{*}$ $^{1}$ )
(D1) + 1 to (D1) + n	Receive data	This stores the contents (header + attached file) of the received e-mail.	_	System

## **POINT**

The receive data storage device (D1) requires a contiguous free area equal to or greater than the receive data length ((S) + 9) (maximum of 6517 words).

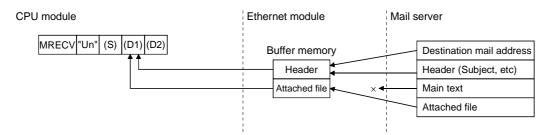
- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 The following shows a description of the processing after the MRECV instruction is executed by selecting the execution type.

Setting option	Description of processing	Merit	Demerit
Do not inquire (Do not read)	<ul> <li>Execute only the read processing of e-mails from the mail server.</li> <li>Inquire (read) about information on receive mails remaining on the mail server after the time set in a GX Developer parameter has elapsed.</li> </ul>	No extra read processing is executed when there are no mails on the mail server.	Even if mails remain on the mail server, they cannot be read immediately.  Mails tend to accumulate on the mail server.
Inquire (Read)	<ul> <li>Execute the read processing of e-mails from the mail server.</li> <li>After executing the MRECV instruction, the inquiry (read) processing of information on receive mails remaining on the mail server is also executed. (Inquire whether or not mails are received immediately.)</li> </ul>	Receive mails stored on the mail server can be read in succession.	Inquiries to the mail server are more frequent.  More processing in the module affects other internal processing.

\*3 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)

#### **Functions**

(1) This instruction reads receive mails from the mail server.



- (2) If a received e-mail contains data exceeding the reception data length ((S) + 9) designated in the control data of the MRECV instruction, only the data equivalent to the designated reception data length will be stored and the remaining data will be ignored.
- (3) Whether or not there are mails on the mail server can be determined by the on (receive mail)/off (no receive mail) of bit 15 of the mail information area (address: 2682H (9858)) in the buffer memory.
  - \* The information in the mail information area is updated when the MRECV instruction execution completes.
- (4) Whether the MRECV instruction is being executed or has been completed normally or abnormally can be checked with the completion device (D2) or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the MRECV instruction is completed, and turns off at the next END processing.
  - completed, and turns off at the next END processing.

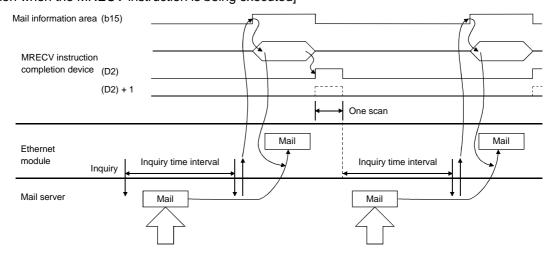
    (b) Status display device at completion ((D2) + 1)

Normal completion : Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the MRECV instruction is completed, and turns off at the next END processing.

Turns on and off depending on the completion status of the MRECV instruction.

## [Operation when the MRECV instruction is being executed]



#### Errors

(1) When a dedicated instruction completes abnormally, the abnormal completion signal (D2)+1 turns on and the error code is stored in the completion status (S)+1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design,

Maintenance and Inspection)

C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

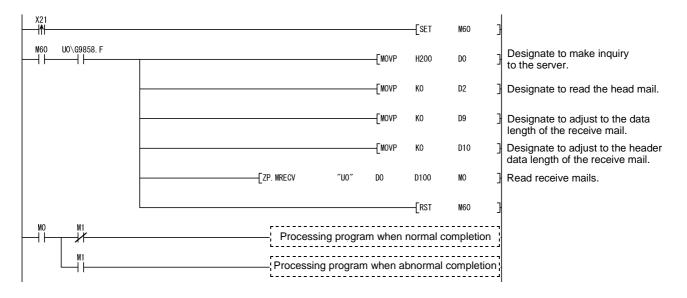
Module User's Manual (Basic)

# Program example

The following example shows a program that receives e-mails.

This program performs e-mail reception processing using the receive command (X21).

# When I/O signals of the Ethernet module are X/Y00 to X/Y1F



# 6.3 MSEND Instruction

This instruction sends e-mails.

		Applicable device							
Set data	Internal	device	File register	MELSEC	CNET/H, CNET/10 J□\□	Special module U□\G□	Index register Zn	Constant K, H, \$	Others
	Bit	Word		Bit	Word				
(S1)			0			_		_	_
(S2)			0			_		_	_
(D)	0		0		•	_		_	_

[Instruction symbol]	[Executing condition]			
MSEND		Command	ZP.MSEND "Un" (S1)	(S2) (D)

# Set data

Set data	Description	Set by	Data type
"Un"	Start I/O signal of the local station's Ethernet module. (00 to FE: The higher 2 digits of the 3-digit I/O signal.)	User	Character string
(S1)	Head device of the local station that stores the control data.	User, system	
(S2)	Head device of the local station that stores the contents of the e-mail to be sent ((Subject + attached file) or (Subject + main text)).	User	Device name
(D)	Local station device that is turned on for one scan by the completion of the instruction.  (D) + 1 is turned on if the instruction execution completes abnormally.	System	Bit

The local devices and the file register for each program cannot be used as devices used in setting data.

POINT

The MSEND instruction can be executed only when the local station is QCPU.

REMARK

The number of steps for the MSEND instruction is 10.

# Control data

Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S1) + 0	Execution/complete type Send data format	b15 to b12 to b8 b7 to b0    O	(As described in the left)	User
(S1) + 1	Completion status	Store the status at completion of the instruction.  0: Normal  Other than 0: Abnormal (error code) ( * <sup>2</sup> )	_	System
(S1) + 2	Send destination number	Designate the opposite device to which the e-mail is sent by the setting number of the "Ethernet send mail address setting" with GX Developer.  1 to 16: The setting number of the destination external device	1 to 16	User
(S1) + 3 to (S1) + 8	System area	_	_	_
(S1) + 9	Send data length	Designate the data length ((Subject + attached file) or (Subject + main text)) of the e-mail stored in (S2) + 0 to (S2) + n.  1) When sending data as an attached file (Subject: 0 to 373, attached file: 1 to 6144)  1 to 6517: The data length of e-mail (words)  2) When sending data as the main text (Subject: 0 to 373, Main text: 1 to 960)  1 to 1333: The data length of e-mail (words)	1 to 6517 or 1 to 1333	User
(S1) + 10	Subject length	Designate the data length of the Subject of the e-mail stored in (S2) + 0 to (S2) + n.  0 to 373: The data length of the Subject (words)	0 to 373	User
(S1) + 11	Clock set flag	This stores the valid/invalid status of the clock data in ((S1) + 12 to (S1) + 15).  0: Invalid 1: Valid	0, 1	System
(S1) + 12		Higher 8 bits: month (01 <sub>H</sub> to 12 <sub>H</sub> ), lower 8 bits: last 2 digits of year (00 <sub>H</sub> to 99 <sub>H</sub> )		
(S1) + 13	Clock data	Higher 8 bits: hour (00H to 23H), lower 8 bits: date (01H to 31H)	_	System
(S1) + 14	(set only when abnormal)			
(S1) + 15				

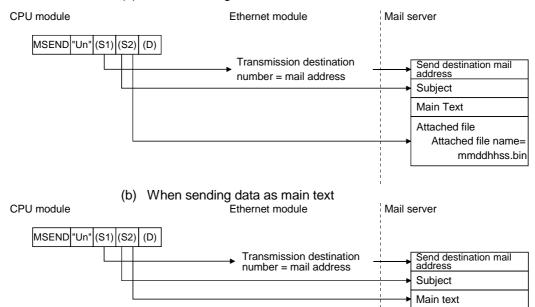
#### Send data

Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S2) + 0 to (S2) + n	Send data	Designate the contents of e-mail ((Subject + attached file) or (Subject + main text)) to be sent.	_	User

- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)

#### **Functions**

- (1) This instruction sends mails to the designated external device.
  - (a) When sending data as an attached file

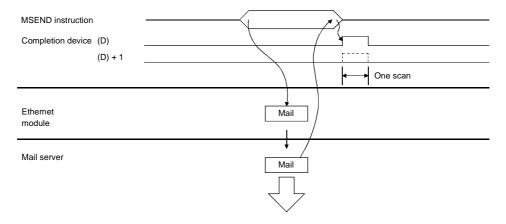


- (2) Whether the MSEND instruction is being executed or has been completed normally or abnormally can be checked with the completion device (D) or completion status display flag ((D) + 1) designated in the set data.
  - (a) Completion device (D)
     Turns on at the END processing of the scan where the MSEND instruction is completed, and turns off at the next END processing.
  - (b) Status display device at completion ((D) + 1)Turns on and off depending on the completion status of the MSEND instruction.

Normal completion: Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the MSEND instruction is completed, and turns off at the next END processing.

# [Operation when the MSEND instruction is being executed]



#### **Errors**

(1) When a dedicated instruction completes abnormally, the abnormal completion signal (D) + 1 turns on and the error code is stored in the completion status (S1)+1. See the following manuals regarding the error codes, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design,

Maintenance and Inspection)

C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's manual (Basic)

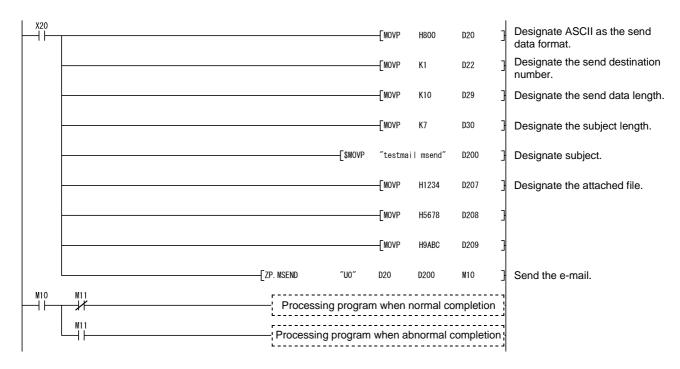
## Program example

The following example shows a program that sends e-mails.

### (1) When sending e-mail as an attached file

This program performs e-mail transmission processing using the send command (X20).

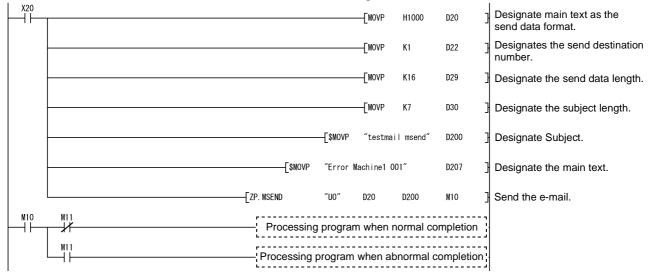
### When I/O signals of the Ethernet module are X/Y00 to X/Y1F



## (2) When sending e-mail as main text

This program performs e-mail transmission processing using the send command (X20).

## When the I/O signals of the Ethernet module are X/Y00 to X/Y1F

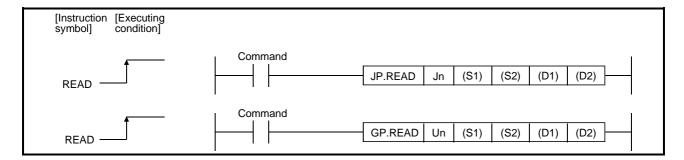


6 - 11 6 - 11

# 6.4 READ Instruction

This instruction	reade data	from word	dovices o	of other etations	
This instruction	reads data	i iromi word	devices (	omer stations.	

	Applicable device								
Set data	Internal	l device	File register	MELSEC	MELSECNET/H, MELSECNET/10 Specia Direct J□\□ UE		Index register Zn	Constant K, H, \$	Others
	Bit	Word		Bit	Word				
(S1)			0			_	_		
(S2)			0			_	_		
(D1)	_		0						
(D2)		0				_	_		



## Set data

Set data	Description	Set by	Data type	
Jn	Network number of the local station (1 to 239, 254) 254: The network designated by the valid module during other station access.	User	Binary 16 bits	
Un	Start I/O signal of the local station's Ethernet module. (00 to FE: The higher 2 digits of a 3-digit I/O signal.)		Character string	
(S1)	Head device of the local station that stores control data. * 1	User, system		
(S2)	Head device of the target station from which data is read.	Haan	Device name	
(D1)	Head device of the local station that stores data read.	User		
(D2)	Local station device that is turned on for one scan by completion of the instruction.  (D2) + 1 turns on if the instruction execution completes abnormally.	System	Bit	

The local devices and the file register for each program cannot be used as devices used in setting data.

## **POINT**

(1) The READ instruction can be executed only when the target station is the Q/QnACPU.

(The READ instruction cannot be executed for an ACPU connected to the MELSECNET/10 or Ethernet network systems.)

Thus, the target station numbers should be limited to Q/QnACPU station numbers.

(2) When reading data from the other station CPU module device with the READ instruction, specify the device within the range applicable to the host station CPU module.

(Head device number to be read in other station CPU module (S2)) + (number of read points -1)

<(last device number of host station CPU module \*)</pre>

\*: Last device number in host station CPU module having the same device name as (S2).

# REMARK

- 1) \*1: At completion of the execution of an instruction, the completion status ((S1) + 1) and the clock data ((S1) + 11 to (S1) + 17) at error occurrence are stored in the control data.
- 2) The number of steps for the READ instruction is 9.

### Control data

Device	Item	Set data	Setting range	Set by ( * 1)
(S1) + 0	Abnormal complete type	b15 to b7 to b0  0 1) 0 1  1) Abnormal complete type (bit 7) Set whether or not the clock data setting is required at abnormal completion. 0: Clock data setting is not requiredClock data is not stored in (S1) + 11 to (S1) + 17 when errors occur. 1: Clock data is stored in (S1) + 11 to (S1) + 17 when errors occur.	0001н 0081н	User
(S1) + 1	Completion status	Store the status at completion of an instruction.  0: Normal  Other than 0: Abnormal (error code) ( * <sup>2</sup> )	_	System
(S1) + 2	Channel used by the local station	Designate the channel used by the local station.  1 to 8 (Channel)	1 to 8	User
(S1) + 3	Target station's CPU type ( * <sup>3</sup> )	Specify the CPU type on the target station.	0000н 03D0н to 03D3н 03FFн	User
(S1) + 4	Target station network No.	Designate the network No. of the target station.  1 to 239: Network No.  254: When 254 is designated in Jn (The network designated by the valid module during other station access)	1 to 239, 254	User

(Continued to the next page)

Device	Item	Set data	Setting range	Set by ( * 1)
(S1) + 5	Target station number	Designate the target station.  1 to 64: The station with the corresponding station number	1 to 64	User
(S1) + 6	_	(Fixed value)	0	User
(S1) + 7	Number of resend	At instruction execution     Set the number of resends when the instruction is not completed within the monitoring time designated by (S1) + 8.     0 to 15 (times)  2) At instruction completion     Store the number of resends executed (result).     0 to 15 (times)	0 to 15	User System
(S1) + 8	Arrival monitoring time	Set the monitoring time until the instruction completion so that it is greater than or equal to the TCP resend timer value.  When the instruction fails to complete within the monitoring time, it is resent for the number of resends designated in (S1) + 7.  0 to TCP resend timer value: The monitoring time is reset to the TCP resend timer value + 1) to 16383:  Monitoring time (unit: s)	1 to 16383 0 to TCP resend timer value	User
(S1) + 9	Read data length	Designate the number of data to be read. 1 to 480 (Words)	1 to 480	User
(S1) + 10	(Not used)	_	_	_
(S1) + 11	Clock set flag	Store the valid/invalid status of the data in ((S1) + 12 to (S1) + 17).  0: Invalid  1: Valid	_	System
(S1) + 12 (S1) + 13 (S1) + 14 (S1) + 15	Clock data (set only when errors occur)	Higher 8 bits: month (01+ to 12+), lower 8 bits: last 2 digits of year (00+ to 99+) Higher 8 bits: hour (00+ to 23+), lower 8 bits: date (01+ to 31+) Higher 8 bits: second (00+ to 59+), lower 8 bits: minute (00+ to 59+) Higher 8 bits: first 2 digits of year (00+ to 99+), lower 8 bits: day of the week (00+ (Sunday) to 06+ (Saturday))	_	System
(S1) + 16	Abnormal detection network No.	Stores the network number of the station that detected an abnormality. ( * <sup>4</sup> ) 1 to 239 (Network No.)	1 to 239	System
(S1) + 17	Abnormal detection station number	Stores the station number of the station that detected an abnormality. ( $st^4$ ) 1 to 64 (Station number)	1 to 64	System

## **POINT**

The data read storage device (D1) requires a contiguous free area equal to or greater than the length of the data read ((S) + 9) (maximum of 480 words).

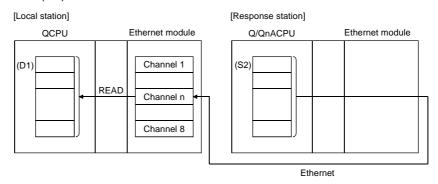
- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)
- \*3 It can be specified when the local station has an Ethernet module of function version D or later. (Not available in any other case. Access to the target CPU is required.)
- \*4 Nothing is stored if the execution source detects an error when receiving an instruction.
- \*5 When the READ instruction is executed to the redundant system with a control system or standby system CPU specified, the instruction may be unsuccessfully completed due to system switching occurred on the target station (error code: 4244н, 4248н).

If this has occurred, execute the READ instruction again.

#### **Functions**

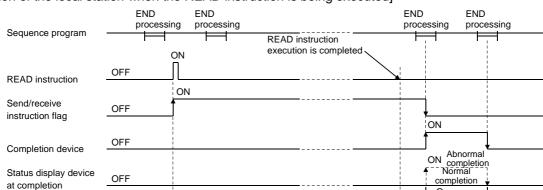
(1) This instruction designates the target network number and target station number of a station connected to an MELSECNET/H, MELSECNET/10 or Ethernet network system in the control data and reads the data of designated word devices of that station.

When reading the device data is completed, the completion device designated by (D2) turns on.



- (2) Device data can be read from stations connected to either the MELSECNET/H, MELSECNET/10 or Ethernet networks having the designated numbers, in addition to stations connected to the local station's network.
- (3) The data link instruction and instructions for the Ethernet network system cannot be executed at two or more locations for the same channel. If the execution conditions are met at two or more locations at the same time, instructions to be executed later have to wait until the channel becomes available because handshaking is automatically performed at the execution of the first instruction.
- (4) Whether the READ instruction is being executed or has been completed normally or abnormally can be checked with the completion device (D2) or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the READ instruction is completed, and turns off at the next END processing.
  - (b) Status display device at completion ((D2) + 1)Turns on and off depending on the completion status of the READ instruction.Normal completion: Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the READ instruction is completed, and turns off at the next END processing.



## [Operation of the local station when the READ instruction is being executed]

(5) When executing the instruction using JP.READ/GP.READ, the read processing is executed only once when the read instruction flag switches from off to on (at rise).

#### Errors

(1) When a dedicated instruction ends with an error, the abnormal completion signal (D2)+1 turns on and the error code is stored in the completion status (S1) + 1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design,

Maintenance and Inspection)

C000н or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

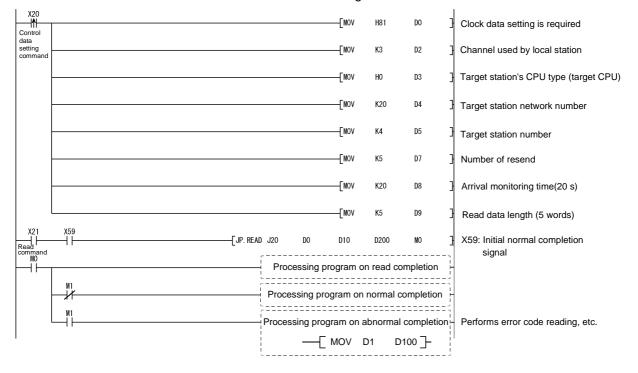
Module User's Manual (Basic)

#### Program example

The following example shows a program that reads data from D10 to 14 of station number 4 to D200 to 204 of station number 1.

When I/O signals of the Ethernet module are X/Y40 to X/Y5F

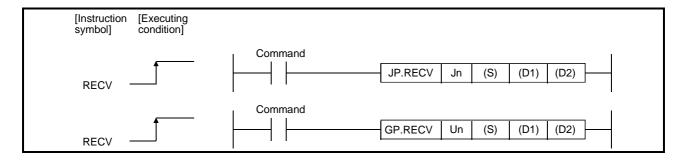
One scan



# 6.5 RECV Instruction (for the Main Program)

Thic	instruction	reade	received	data
111115	шъписион	reaus	received	uala.

					Applicat	ole device			
Set data	I Internal device		File register	MELSEC	MELSECNET/H, MELSECNET/10 Special module Direct J□\□ U□\G□		Index register Zn	Constant K, H	Others
	Bit	Word		Bit	Word				
(S)	_		0			_	_		
(D1)			0	_					
(D2)		0		_					



#### Set data

Set data	Description	Set by	Data type
Jn	Network No. of the local station (1 to 239, 254) 254: The network designated by the valid module during other station access.	User	Binary 16 bits
Un	Start I/O signal of the local station's Ethernet net module. (00 to FE: The higher 2 digits of the 3-digit I/O signal.)		Character string
(S)	Head device of the local station that stores the control data.	User, system	5 .
(D1)	Head device of the local station that stores the reception.		Device name
(D2)	Local station device that is turned on for one scan by the completion of the instruction.  (D2) + 1 is turned on if the instruction execution completes abnormally.	System	Bit

The local devices and the file register for each program cannot be used as devices used in setting data.

POINT

The RECV instruction can be executed only when the local station is a Q/QnACPU.

REMARK

The number of steps for the RECV instruction is 8.

# Control data

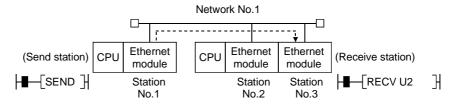
Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S) + 0	Abnormal complete type	b15 to b8 b7 b6 to b0  0 to 0 1) 0 to 0  1) Abnormal complete type (bit 7) Set whether or not the clock data setting is required at abnormal completion.  0: Clock data setting is not required Clock data is not stored in (S) + 11 to (S) + 17 when errors occur.  1: Clock data setting is required Clock data is stored in (S) + 11 to (S) + 17 when errors occur.	0000н 0080н	User
(S) + 1	Completion status	Store the status at completion of an instruction.  0: Normal  Other than 0: Abnormal (error code) ( * <sup>2</sup> )	_	System
(S) + 2	Local station storage channel	Designate the channel to store the data to be read.  1 to 8 (Channel)	1 to 8	User
(S) + 3	Channel used by the transmission station	Store the channel number used by the transmission station.  1 to 8 (Channel)	1 to 8	System
(S) + 4	Transmission station network number	Store the network number of the transmission station.  1 to 239: Network No.	1 to 239	System
(S) + 5	Transmission station number	Stores the station number of the transmission station.  1 to 64: Station number (reception from the station with the corresponding station number)	1 to 64	System
(S) + 6	(Not used)	_	_	_
(S) + 7	(Not used)	_	_	_
(S) + 8	Arrival monitoring time	Set the monitoring time until the instruction completion so that it is greater than or equal to the TCP resend timer value.  When the instruction fails to complete within the monitoring time, abnormal completion occurs.  O to TCP resend timer value: The monitoring time is reset to the TCP resend timer value. (TCP resend timer value + 1) to 16383: Monitoring time (unit: s)	1 to 16383 0 to TCP resend timer value	User
(S) + 9	Reception data length	Stores the word count of the receive data stored in (D1) + 0 to (D1) + n.  0: No receive data  1 to 480: Word count of receive data	0 to 480	System
(S) + 10	(Not used)		_	
(S) + 11	Clock set flag	Store the valid/invalid status of the data in ((S) + 12 to (S) + 17).  0: Invalid  1: Valid	_	System
(S) + 12		Higher 8 bits: month (01н to 12н), lower 8 bits: last 2 digits of year (00н to 99н)		
(S) + 13	Clock data (set only when	Higher 8 bits: hour (00 <sub>H</sub> to 23 <sub>H</sub> ), lower 8 bits: date (01 <sub>H</sub> to 31 <sub>H</sub> )	_	System
(S) + 14	errors occur)	Higher 8 bits: second (00 <sub>H</sub> to 59 <sub>H</sub> ), lower 8 bits: minute (00 <sub>H</sub> to 59 <sub>H</sub> )	_	Сузісііі
(S) + 15		Higher 8 bits: first 2 digits of year (00 <sub>H</sub> to 99 <sub>H</sub> ), lower 8 bits: day of the week (00 <sub>H</sub> (Sunday) to 06 <sub>H</sub> (Saturday))		
(S) + 16	Abnormal detection network number	Stores the network No. of the station that detected an abnormality. (* <sup>3</sup> ) 1 to 239 (Network No.)	1 to 239	Custom
(S) + 17	Abnormal detection station number	Stores the station number of the station that detected an abnormality. ( * <sup>3</sup> )  1 to 64 (Station number)	1 to 64	System

## **POINT**

- (1) The receive data storage device (D1) requires a contiguous free area equal to or greater than the receive data length ((S) + 9) (maximum of 480 words).
- (2) Execute the RECV instruction every time the corresponding channel's bit in the RECV instruction execution request area (address: 205) of the buffer memory turns on (there is receive data).
- (3) When multiple Ethernet modules with the same network No. are installed to a receive station, specify the "Un" to indicate which one is the target of the RECV instruction.

When the "Jn" is specified in the RECV instruction, the PLC CPU will execute the instruction to the module with the smallest starting I/O No..

(Example) To execute the RECV instruction at station No.3 for the SEND instruction from station No.1, specify the "Un" as "U2".



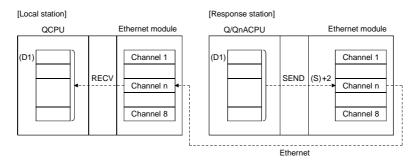
- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)
- \*3 Nothing is stored if the execution source detects an error when receiving an instruction.

#### **Functions**

- (1) This instruction reads, via the Ethernet module of the local station, the data sent from a station connected to an MELSECNET/H, MELSECNET/10 or Ethernet network system, which is designated with the network number and station number in the control data.
  - \* The data is sent using the SEND instruction.

    When data is received from the send station, the receive data is stored in the channel of the local station designated with the send station, and the corresponding bit in the RECV instruction execution request area (address: 205) of the Ethernet module buffer memory turns on. The received data is read from the receive data storage channel using the ON status of the corresponding bit of the RECV instruction execution request area to time the reading operations.

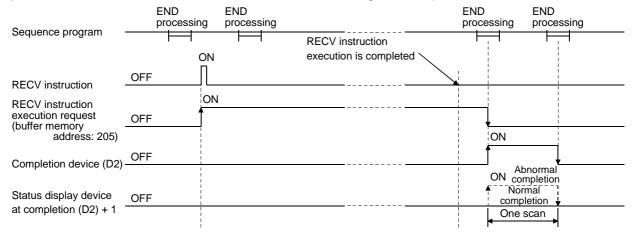
When reading the receive data from the Ethernet module is completed, the completion device designated by (D2) turns on.



- (2) The instructions for Ethernet module cannot be executed to two or more locations for the same channel.
  - If the execution conditions are met at two or more locations at the same time, instructions to be executed later have to wait until the channel becomes available because handshaking is automatically performed at the execution of the first instruction.
- (3) RECVS instruction (for interrupt program) cannot be used with the instruction for data link in cases where the same channel is used to read receive data using the instruction for data link.
- (4) Whether the RECV instruction is being executed or has been completed normally or abnormally can be checked with the completion device (D2) or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the RECV instruction is completed, and turns off at the next END processing.
  - (b) Status display device at completion ((D2) + 1)
     Turns on and off depending on the completion status of the RECV instruction.
     Normal completion: Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the RECV instruction is completed, and turns off at the next END processing.

### [Operation of the local station when the RECV instruction is being executed]



(5) When executing the instruction using JP.RECV/GP.RECV, the read processing is executed only once when the read instruction flag goes from off to on (at rise).

Errors

(1) When a dedicated instruction completes abnormally, the abnormal completion signal (D2) + 1 turns on and the error code is stored in the completion status (S)+1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design,

Maintenance and Inspection)

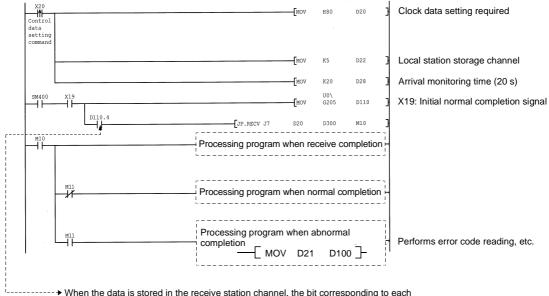
C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's manual (Basic)

# Program example

The following example shows a program that reads receive data from channel 5.

When I/O signals of the Ethernet module are X/Y00 to X/Y1F



➤ When the data is stored in the receive station channel, the bit corresponding to each channel of buffer memory RECV instruction execution request area turns on. Data can be read automatically bu using this signal for the receive command. The signal turns off shen the RECV instruction is completed.

# 6.6 RECVS Instruction (for Interrupt Programs)

This instruction reads received data.

					Applicat	ole device					
Set data	I Internal device		Internal device		File register  MELSECN  MELSECN  Direct J		CNET/10	Special module U⊟\G⊟	Index register Zn	Constant K, H	Others
	Bit	Word		Bit	Word						
(S)	_		0			_	_				
(D1)			0	_							
(D2)		0		_							

[Instruction symbol]	[Executing condition]
RECVS —	Z.RECVS "Un" (S) (D1) (D2)

## Set data

Set data	Description	Set by	Data type	
"Un"	Start I/O signal of the local station's Ethernet net module. (00 to FE: The higher 2 digits of the 3-digit I/O signal.)	User	Character string	
(S)	Head device of the local station that stores the control data.	User, system	Desire	
(D1)	Head device of the local station that stores the receive data.	0	Device name	
(D2)	(Designate as dummy.)	System	Bit	

The local devices and the file register for each program cannot be used as devices used in setting data.

POINT

The RECV instruction can be executed only when the local station is a QCPU.

REMARK

The number of steps for the RECV instruction is 10.

#### Control data

Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S) + 0	Complete type	Designate 0.	0	User
(S) + 1	Completion status	Stores the status at completion of the instruction. 0: Normal Other than 0: Abnormal (error code) ( $^*$ $^2$ )		System
(S) + 2	Local station storage channel	Designate the channel number that stores data to be read.  1 to 8: Channel number	1 1 to 8 1	
(S) + 3	Channel used by send station	Stores the channel number used by the send station.  1 to 8: Channel number	1 to 8	System
(S) + 4	Network number used by send station	Stores the network number of the send station.  1 to 239: Network number	1 to 239	System
(S) + 5	Send station number	Stores the station number of the send station.  1 to 64: Station number (receive from the station with the indicated station number)	1 to 64	System
(S) + 6 to (S) + 8	System area	_	_	_
(S) + 9	Receive data length	Stores the word count of the receive data stored in (D1) + 0 to (D1) + n.  0: No receive data  1 to 480: Word count of receive data	0 to 480	System
(S) + 10	System area	_	_	_

#### Receive data

Device	Item	Set data	Setting range	Set by ( * 1)
(D1) + 0				
to	Receive data	Store the receive data.	_	System
(D1) + n				

## POINT

The receive data storage device (D1) requires a contiguous free area equal to or greater than the receive data length ((S) + 9) (maximum of 480 words).

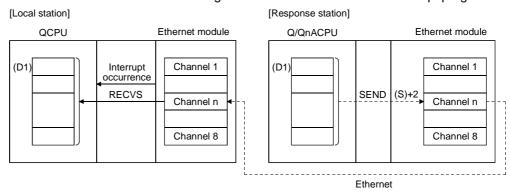
- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)

#### **Functions**

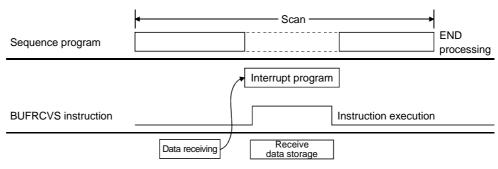
- (1) This instruction reads the data received from other station (a station connected to MELSECNET/H, MELSECNET/10 or Ethernet network system) at the local station storage channel ((S) + 2) designated in the control data.
  - \* Data is sent using the SEND instruction.

    When data is received from the transmission station, the receive data is stored in the channel of the local station designated with the transmission station, and the interrupt program with the interrupt number (Ixx) set with GX Developer is started.

The receive data is read using the RECVS instruction in this interrupt program.



# [Operation when the RECVS instruction is being executed]



- (2) The Z.RECVS instruction is used in the interrupt program and its processing is completed within one scan.
- (3) RECVS instruction (interrupt program-use) can not be used with the instruction for data link in cases where the same channel is used to read received data using the instruction for data link.

#### **Errors**

(1) When a dedicated instruction completes abnormally, the abnormal completion signal (D2)+1 turns on and the error code is stored in the completion status (S)+1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design,

Maintenance and Inspection)

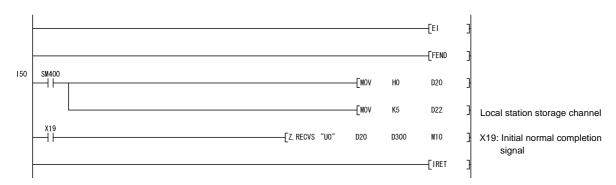
C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's Manual (Basic)

# Program example

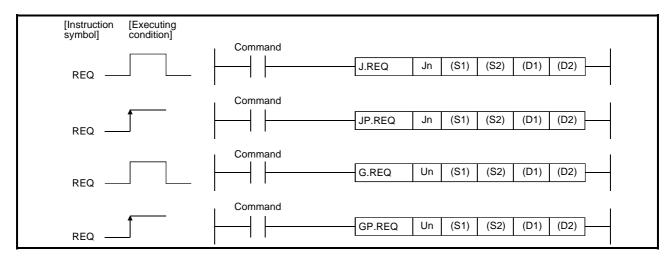
The following example shows an interrupt program that reads the receive data from channel 5.

# When I/O signals of the Ethernet module are X/Y00 to X/Y1F



# 6.7 REQ Instruction (Remote RUN/STOP)

	Applicable device								
Set data	Interna	l device	File register	MELSE	CNET/H, CNET/10	Special module U□\G□	Index register Zn	Constant K, H	Others
	Bit	Word		Bit	Word				
(S1)	_		0			_	_		
(S2)	_		0			_	_		
(D1)	_		0			_	_		
(D2)		0				_	_		



#### Set data

Set data	Description	Set by	Data type
Jn	Network number of the local station (1 to 239, 254) 254: The network designated by the valid module during other station access.	User	Binary 16 bits
Un	Start I/O signal of the local station's Ethernet net module. (00 to FE: The higher 2 digits of the 3-digit I/O signal.)		Character string
(S1)	Head device of the local station that stores the control data.	User, system	
(S2)	Head device of the local station that stores the request data.	User	Device name
(D1)	Head device of the local station that stores the response data.	1	
(D2)	Local station device that is turned on for one scan by the completion of the instruction.  (D2) + 1 is turned on if the instruction execution completes abnormally.	System	Bit

The local devices and the file register for each program cannot be used as devices used in setting data.

## **POINT**

The REQ instruction can be executed only when the target station is a Q/QnACPU. (The REQ instruction cannot be executed to an ACPU connected to an MELSECNET/10 or Ethernet network system.)

# REMARK

The number of basic steps for the REQ instruction is 9.

# Control data

Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S1) + 0	Abnormal complete type	b15 to b7 to b4 to b0  0 1) 0 1 0 1  1) Abnormal complete type (bit 7) Set whether or not the clock data setting is required at abnormal completion. 0: Clock data setting is not requiredClock data is not stored in (S1) + 11 to (S1) + 17 when errors occur. 1: Clock data setting is requiredClock data setting is requiredClock data is stored in (S1) + 11 to (S1) + 17 when errors occur.	0011н 0091н	User
(S1) + 1	Completion status	Store the status at completion of an instruction.  0: Normal  Other than 0: Abnormal (error code) ( * <sup>2</sup> )	_	System
(S1) + 2	Channel used by the local station	Other than 0: Abnormal (error code) ( * 2)  Designate the channel used by the local station.  1 to 8 (channel)	1 to 8	User
(S1) + 3	Target station's CPU type (* 3)	Specify the CPU type on the target station.  Setting value  Description  Single CPU or CPU in the system directly connected to the local station (Same as "03FFH")  03D0H  Control system CPU (* 5)  03D1H  Standby system CPU (* 5)  03D2H  System A CPU  03D3H  System B CPU  03FFH  Single CPU or CPU in the system directly connected to the local station	0000н 03D0н to 03D3н 03FFн	User
(S1) + 4	Target station network number	Designate the network number of the target station.  1 to 239: Network number 254: When 254 is designated in Jn (The network designated by the valid module during other station access)	1 to 239, 254	User
(S1) + 5	Target station number	Designate the target station.  1 to 64: The station with the corresponding station number 81H to A0H: All stations with the indicated group number (only clock data write and remote RUN/STOP are allowed)  FFH: All stations of the target network number (simultaneous broadcast) ··· excluding the local station (only clock data write and remote RUN/STOP are allowed)	1 to 64 81н to А0н FFн	User
(S1) + 6	_	(Fixed value)	0	User
(S1) + 7	Number of resends	1) At instruction execution Set the number of resends when the execution of an instruction did not complete within the monitoring time designated by (S1) + 8.  0 to 15 (times)  2) At instruction completion Store the number of resends executed (result).  0 to 15 (times)	0 to 15	User System
(S1) + 8	Arrival monitoring time	Set the monitoring time until the instruction completion so that it is greater than or equal to the TCP resend timer value. When the instruction fails to complete within the monitoring time, it is resent for the number of resends designated in (S1) + 7.  0 to TCP resend timer value: The monitoring time is reset to the TCP resend timer value.  (TCP resend timer value + 1) to 16383:  The monitoring time is the designated value (unit: s)	1 to 16383 0 to TCP resend timer value	User
(S1) + 9	Request data length	Designate the number of request data (word). (Word count of data stored in the request data storage device (S2)) 4: Remote RUN 3: Remote STOP 2: Clock data read 6: Clock data write	2 to 6	User
(S1) + 10	Response data length	Store the number of response data (word) (Word count of data stored in the response data storage device. 4: Remote RUN 6: Clock data read 2: Clock data write	2, 6	System
(S1) + 11	Clock set flag	Store the valid/invalid status of the data in ((S1) + 12 to (S1) + 17).  0: Invalid  1: Valid	_	System
(S1) + 12	Cleak data (act - Thurst - T	Higher 8 bits: month (01 <sup>H</sup> to 12 <sup>H</sup> ), lower 8 bits: last 2 digits of year (00 <sup>H</sup> to 99 <sup>H</sup> )		
(S1) + 13	Clock data (set only when	Higher 8 bits: hour (00H to 23H), lower 8 bits: date (01H to 31H)		System

(Continued to the next page)

Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S1) + 16	Abnormal detection network number	Stores the network number of the station that detected an abnormality. ( * <sup>4</sup> )  1 to 239 (Network number)	1 to 239	System
(S1) + 17	Abnormal detection station number	Stores the station number of the station that detected an abnormality. ( * <sup>4</sup> )  1 to 64 (Station number)	1 to 64	System

- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)
- \*3 It can be specified when the local station has an Ethernet module of function version D or later. (Fixed to "03FFH" for other than the above. Access to the target CPU is made.)
- \*4 Nothing is stored if the execution source detects an error when receiving an instruction.
- \*5 When the REQ instruction is executed to the redundant system with a control system or standby system CPU specified, the instruction may be unsuccessfully completed due to system switching occurred on the target station (error code: 4244н, 4248н).

If this has occurred, execute the REQ instruction again.

## Request data (All values are set by the user)

Device	Item	Description	Remote RUN	Remote STOP
(S2) + 0	Request type	0010⊮: When station No. is specified in (S1)+5 0030⊮: When all stations or a group is specified in (S1)+5		0
(S2) + 1	Sub-request type	0001н: Remote RUN 0002н: Remote STOP	0	0
(S2) + 2	Mode	Designate whether or not to forcefully execute remote RUN/STOP operations.  0001H: Do not force execution 0003H: Force execution (setting at remote STOP) (The forced execution is a function for forcefully executing remote RUN from other station when the station that executed the remote STOP is no longer able to execute remote RUN.)	0	0
(S2) + 3	Clear mode	Designate the status of the CPU's device memory only when executing remote RUN.  0000 <sub>H</sub> : Do not clear (however, the local device will be cleared)  0001 <sub>H</sub> : Clear (excluding setting and latch range at remote RUN)  0002 <sub>H</sub> : Clear (including setting and latch range at remote RUN)	0	×

### Response data (All values are set by the system)

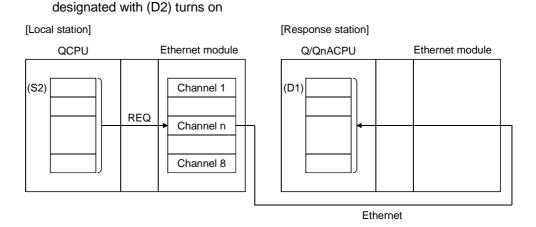
Device	Item	Description	Remote RUN	Remote STOP
(D1)	Request type	0090 <sub>H</sub> : When station No. is specified in (S1)+5 00B0 <sub>H</sub> : When all stations or a group is specified		0
(D1) + 1	Sub-request type	0001н: Remote RUN 0002н: Remote STOP	0	0

### **POINT**

- (1) Remote RUN/STOP becomes valid when the RUN/STOP key switch of the target station's Q/QnACPU is "RUN."
- (2) Remote RUN/STOP cannot be executed when the system protection is activated on the target station's Q/QnACPU (the system protect switch is on).
- (3) When other station has executed a remote STOP/PAUSE operation on the target station, the RUN request cannot be executed if the mode of (S2) + 2 is "Do not force execution (0001H)."
- (4) If the Q/QnACPU of the target station for which a remote RUN/STOP operation has been executed is reset, the information of the remote RUN/STOP is erased.
- (5) The clear mode ((S2) + 3) designates how the clear (initialization) processing of the Q/QnACPU device memory should be performed when the Q/QnACPU starts performing calculations after a remote RUN request has been issued to it. The Q/QnACPU executes the designated clear and then goes into the RUN status according to the parameter settings (PLC file setting → Device initial value).

#### **Functions**

(1) This instruction sends the request data designated by (S2) of the local station to the station connected to an MELSECNET/H, MELSECNET/10 or Ethernet network system, which is designated with the network number and station number in the control data, and makes a service request. When the request to the target station is completed, the completion device



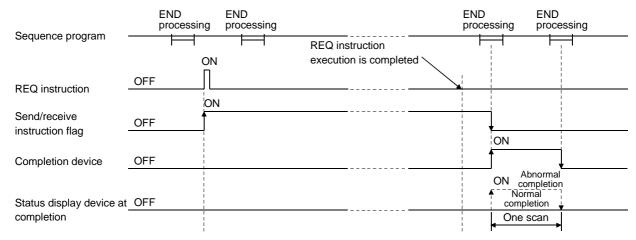
- (2) Device data can be sent from stations connected to either the MELSECNET/H, MELSECNET/10 or Ethernet networks having the designated numbers, in addition to stations connected to the local station's network.
- (3) The data link instruction and instructions for the Ethernet network system cannot be executed at two or more locations for the same channel. If the execution conditions are met at two or more locations at the same time, instructions to be executed later have to wait until the channel becomes available because handshaking is automatically performed at the execution of the first instruction.

- (4) Whether the REQ instruction is being executed or has been completed normally or abnormally can be checked with the complete device (D2) or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the REQ instruction is completed, and turns off at the next END processing.
  - (b) Status display device at completion ((D2) + 1)

Turns on and off depending on the completion status of the REQ instruction. Normal completion: Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the REQ instruction is completed, and turns off at the next END processing.

[Operation of the local station when the REQ instruction is being executed]



(5) When the instruction is executed using J.REQ/G.REQ, the next write processing is executed in succession after one write processing is completed while the write command is on.

When the instruction is executed using JP.REQ/GP.REQ, the write processing is executed only once when the write command switches from off to on (at rise).

#### **Errors**

(1) When a dedicated instruction completes abnormally, the abnormal completion signal (D2) + 1 turns on and the error code is stored in the completion status (S1) + 1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design,

Maintenance and Inspection)

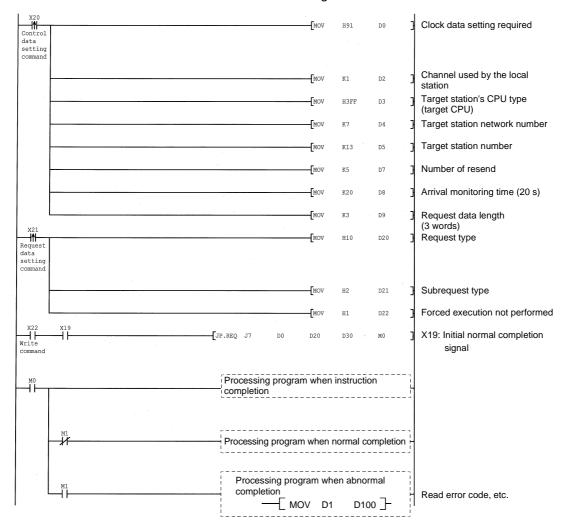
C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's Manual (Basic)

## Program example

The following example shows a program that executes remote STOP on the Q/QnACPU of station number 13 in network number 7.

When I/O signals of the Ethernet module are X/Y00 to X/Y1F



6 - 31 6 - 31

# 6.8 REQ Instruction (Clock Data Read/Write)

This instruction reads/writes clock data from/to other stations.

# POINT

See Section 6.7 for the following information on the REQ instruction for reading/writing clock data from/to other stations.

Since the same explanation as when executing remote RUN/STOP operations using the REQ instruction applies in this case, the explanation of these items is omitted in this section.

- 1) Instruction format
- 2) Devices that can be used with the instruction
- 3) Control data in the setting data
- 4) Functions
- 5) Error

# Request data (All items marked with $\bigcirc$ are set by the user)

Device	Item	Set data	Clock data read	Clock data write
(S2)	Request type	0001н: Clock data read 0011н: Clock data write (When station No. is specified in (S1)+5) 0031н: Clock data write (When all stations or a group is specified in (S1)+5)	0	0
(S2) + 1	Sub-request type	0002н: Clock data read 0001н: Clock data write	0	0
(S2) + 2	Change pattern Year to be changed	1) Change pattern (bits 0 to 7)  Designate which item (s) to write, from the higher byte of (S2) + 2 to (S2) + 5.  0: Do not change  1: Change  2) Year to be changed (bits 8 to 15)  Store year (last two digits of the year in the Gregorian calendar) as BCD code.  b15 to b8 b7 b6 b5 b4 b3 b2 b1 b0  Year (00h to 99h) 0 Year (00h to 99h) 0 Year Hour Hour Hour Hour Hour Second Day of the week	_	0
(S2) + 3		Higher 8 bits: date (01 <sub>H</sub> to 31 <sub>H</sub> ), lower 8 bits: month (01 <sub>H</sub> to 12 <sub>H</sub> )		0
(S2) + 4	Clock data to be changed	Higher 8 bits: minute (00 <sub>H</sub> to 59 <sub>H</sub> ), lower 8 bits: hour (00 <sub>H</sub> to 23 <sub>H</sub> )		0
(S2) + 5	(continued)	Higher 8 bits: day of the week (00н (Sunday) to 06н (Saturday)), lower 8 bits : second (00н to 59н)	_	0

<sup>\*</sup> In this function, the higher two digits of the year data cannot be changed. When it is necessary to change the higher two digits of the year data, use other function (such as GX Developer) to set the clock data.

# Request data (All items marked with $\bigcirc$ are set by the user)

Device	Item	Set data	Clock data read	Clock data write
(D1) + 0	Request type	0081н: Clock data read 0091н: Clock data write (When station No. is specified in (S1)+5) 00В1н: Clock data write (When all stations or a group is specified in (S1)+5)	0	0
(D1) + 1	Sub-request type	0002н: Clock data read 0001н: Clock data write	0	0
(D1) + 2		Higher 8 bits: month (01н to 12н), lower 8 bits : year (00н to 99н) * Year: Lower two digits	0	_
(D1) + 3		Higher 8 bits: hour (00н to 23н), lower 8 bits: date (01н to 31н)	0	_
(D1) + 4	Clock data read	Higher 8 bits: second (00н to 59н), lower 8 bits: minute (00н to 59н)	0	_
(D1) + 5		Higher 8 bits: (00н), lower 8 bits: day of the week (00н (Sunday) to 06н (Saturday)).	0	_

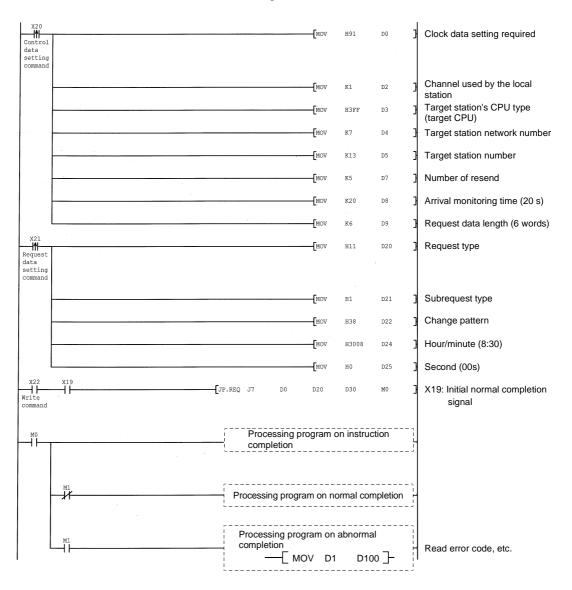
# **POINT**

- (1) The clock data cannot be read/written when the system protection is activated on the target station's Q/QnACPU (the system protect switch is on).
- (2) When the clock data is read, the response data storage device (D1) requires a contiguous free area of six words.

# Program example

The following example shows a program that writes the clock data (8:30:00) to the Q/QnACPU of station number 13 having network number 7.

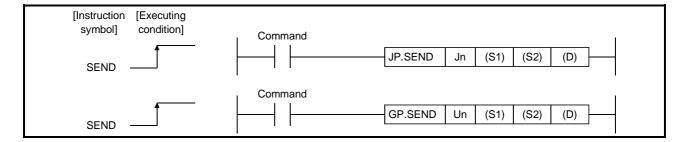
When I/O signals of the Ethernet module are X/Y00 to X/Y1F



# 6.9 SEND Instruction

This instruction se	anda data	to other	atation!a	$O/O_{\infty}ACDII$
This instruction se	mus data	to other	Stations	Q/QNACPU.

	Applicable device								
Set data	I Internal device		rice File register		CNET/H, CNET/10 J□∖□	Special module U⊟\G⊟	Index register Zn	Constant K, H	Others
	Bit	Word		Bit	Word				
(S1)			0			_	_		
(S2)			0	_					
(D)		0		_					



## Setting data

Set data	Description	Set by <sup>(* 1</sup> )	Data type
Jn	Network number of the local station (1 to 239, 254) 254: The network designated by the valid module during other station access.	User	Binary 16 bits
Un	Start I/O signal of the local station's Ethernet module. (00 to FE: The higher 2 digits of the 3-digit I/O signal.)		Character string
(S1)	Head device of the local station that stores the control data. $^{*1}$	User, system	Desire and a
(S2)	Head device of the local station that stores the send data.	User	Device name
(D)	Local station device that is turned on for one scan by the completion of the instruction.  (D) + 1 is turned on if the instruction execution completes abnormally.	System	Bit

The local devices and the file register for each program cannot be used as devices used in setting data.

## POINT

The SEND instruction can be executed only when the target station is a Q/QnACPU. (The SEND instruction cannot be executed for an ACPU connected to an MELSECNET/10 or Ethernet network system.)

# REMARK

- 1) \*1: When the instruction is completed, the completion status ((S1) + 1) and clock data at abnormal occurrence ((S1) + 11 to (S1) + 17) are stored in the control data
- 2) The number of steps for the SEND instruction is 8.

# Control data

Device	Item	Set data	Setting range	Set by ( * 1)
(S1) + 0	Execution/abnormal complete type	b15 to b7 to b0  0 2) 0 1)  1) Execution type (bit 0) 0: No arrival confirmation When the target station is on the same network: Completed when the data is sent from the local station.  When the target station is on other network: Completed when the data arrives at the relay station on the network of the local station.  1: With arrival confirmation Completed when the data is stored in the target station's designated channel.  1: With arrival confirmation Completed when the data is stored in the target station's designated channel.  2) Abnormal complete type (bit 7) Set whether or not the clock data setting is required at abnormal completion. 0: Clock data setting not required: Clock data at error occurrence is not stored in (S1) + 11 to (S1) + 17.  1: Clock data at error occurrence is stored in (S1) + 11 to (S1) + 17.	0000н 0001н 0080н 0081н	User
(S1) + 1	Completion status	Stores the status at the completion of the instruction.  0 : Normal  Other than 0: Abnormal (error code) ( * 2)	-	System
(S1) + 2	Channel used by the local station	Set the channel used by the local station.  1 to 8 (channel)	1 to 8	User
(S1) + 3	Target station storage channel	Designate the target station's channel that stores data.  1 to 8 (channel)	1 to 8	User
(S1) + 4	Target station network number	Designate the network number of the target station.  1 to 239: Network number  254 : When 254 is designated in Jn (The network designated by the valid module during other station access)	1 to 239, 254	User

(Continued to the next page)

Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S1) + 5	Target station number	Designate the target station.  1 to 64 : The station with the corresponding station number  81H to A0H: All the station having the indicated group number (Can be set when the execution type designated in (S1) is "0: No arrival confirmation.")  FFH : All stations having the target network number (simultaneous broadcasting):  Excluding the local station (Can be set when the execution type designated in (S1) is "0: No arrival confirmation.")	1 to 64 81н to АОн FFн	User
(S1) + 6	_	(Fixed value)	0	User
(S1) + 7	Number of resends	Valid when the execution type designated in (S1) is "1: With arrival confirmation."  1) At instruction execution Set the number of resends when the instruction fails to complete within the monitoring time designated by (S1) + 8. 0 to 15 (Time)  2) At instruction completion Store the number of resends executed (result). 0 to 15 (Time)	0 to 15	User System
(S1) + 8	Arrival monitoring time	Valid when the execution type designated in (S1) is "1: With arrival confirmation." Set the monitoring time until the instruction completion equals to or becomes greater than the TCP resend timer value.  When the instruction fails to complete within the monitoring time, it is resent for the number of resends designated in (S1) + 7.  0 to TCP resend timer value:  The monitoring time is reset to the TCP resend timer value.  (TCP resend timer value + 1) to 16383:  Monitoring time (unit: s).	1 to 16383 0 to TCP resend timer value	User
(S1) + 9	Send data length	Designate the number of send data in (S2) to (S2) + n. 1 to 480 (Word)	1 to 480	User
(S1) + 10	(Not used)	_	_	_
(S1) + 11	Clock set flag	Store the valid/invalid status of the clock data in (S1) + 12 to (S1) + 17.  0: Invalid 1:Valid	_	System
(S1) + 12 (S1) + 13 (S1) + 14 (S1) + 15	Clock data (set only when errors occur)	Higher 8 bits: month (01н to 12н), lower 8 bits: last 2 digits of year (00н to 99н) Higher 8 bits: hour (00н to 23н), lower 8 bit: date (01н to 31н) Higher 8 bits: second (00н to 59н), lower 8 bits: minute (00н to 59н) Higher 8 bits: first 2 digits of year (00н to 99н), lower 8 bits: day of the week (00н (Sunday) to 06н (Saturday))	_	System

(Continued to the next page)

Device	Item	Set data	Setting range	Set by <sup>(* 1</sup> )
(S1) + 16	Abnormal detection network number	Stores the network number of the station that detected an abnormality. ( * <sup>3</sup> )  1 to 239 (Network number)	1 to 239	
(S1) + 17	Abnormal dotaction station	Stores the station number of the station that detected an abnormality. ( $*$ $^3$ )  1 to 64 (Station number)	1 to 64	System

- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)
- \*3 Nothing is stored if the execution source detects an error when receiving an instruction.

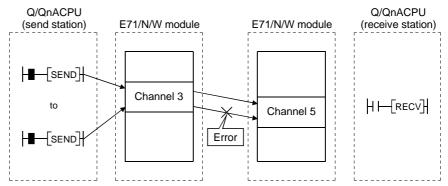
## **POINT**

- (1) The send data storage device (S2) requires a continuous free area equal to or greater than the send data length ((S1) + 9) (maximum of 480 words).
- (2) In order to increase the reliability of the data, it is recommended to execute the instruction by setting the execution type to "With arrival confirmation" when a number from one to 64 is designated for the target station number.

  When 81H to A0H or FFH is designated for the target station number, the instruction should be executed by setting the execution type to "No arrival confirmation."
- (3) When sending data to the same channel of the receive station, do so after the receive station reads data using the RECV instruction.

  If the communication itself is normally completed when the execution type is set to "No arrival confirmation," the send is considered normally completed on the send station even if the contents of the send data are abnormal.

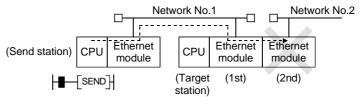
  In addition, even if the contents of the send data are normal, when the instruction is executed to the same station from multiple stations, a timeout error (C083H) will occur on the send station.
- (4) When the execution type is set to "With arrival confirmation," if the send station sends data to the same channel of the receive station before the receive station reads data using the RECV instruction, a buffer full-error will occur on the send station side.



- (5) Designate the target station sending data with the network No. and station No. of the network module or Ethernet module receiving the request from the send station.
  - \* In the diagram below, designate the network No. and station No. of the first Ethernet module.

The SEND instruction cannot be executed if a network module or Ethernet module other than the one receiving the request from the send station is designated.

\* In the diagram below, the SEND instruction cannot be executed if the network No. and station No. of the second Ethernet module is designated.

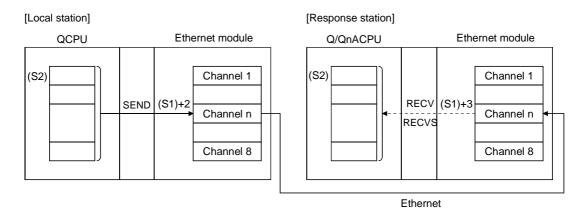


#### **Functions**

(1) This instruction sends data stored in the devices designated with the local station's (S2) to the station designated with the target station network number and target station number in the control data. The target station must be connected to an MELSECNET/H, MELSECNET/10 or Ethernet network system.

The sent data is stored in the channel set with the target station's (S2). Use the RECV/RECVS instruction when reading the data sent on the target station.

When data sending to the target station number is completed, the completion device designated in (D) turns on.



- (2) Data can be sent to stations connected to either the MELSECNET/H, MELSECNET/10 or Ethernet networks having the designated numbers, in addition to stations connected to the local station's network.
- (3) The data link instruction and instructions for the Ethernet network system cannot be executed at two or more locations for the same channel. If the execution conditions are met at two or more locations at the same time, instructions to be executed later have to wait until the channel becomes available because handshaking is automatically performed at the execution of the first instruction.
- (4) Whether the SEND instruction is being executed or has been completed normally or abnormally can be checked with the completion device (D2) or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the SEND instruction is completed, and turns off at the next END processing.
  - (b) Status display device at completion ((D2) + 1)

Turns on and off depending on the completion status of the SEND instruction.

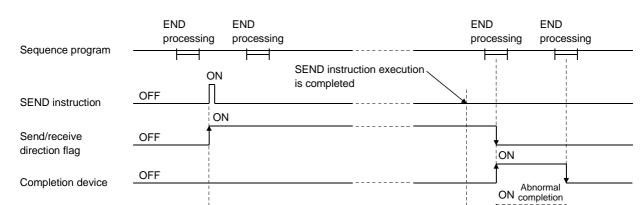
Normal completion : Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the SEND instruction is completed, and turns off at the next END processing.

Normal

completion

One scan



[Operation of the local station when the SEND instruction is being executed]

(5) When the instruction is executed using JP.SEND/GP.SEND, the send processing is executed only once when the send instruction flag switches from off to on (at rise).

#### **Errors**

Status display device

at completion

OFF

 When a dedicated instruction completes abnormally, the abnormal completion signal (D) + 1 turns on and the error code is stored in the completion status (S1) + 1.

See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFF<sub>H</sub> or less : QCPU (Q Mode) User's Manual (Hardware Design, Maintenance

and Inspection)

C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

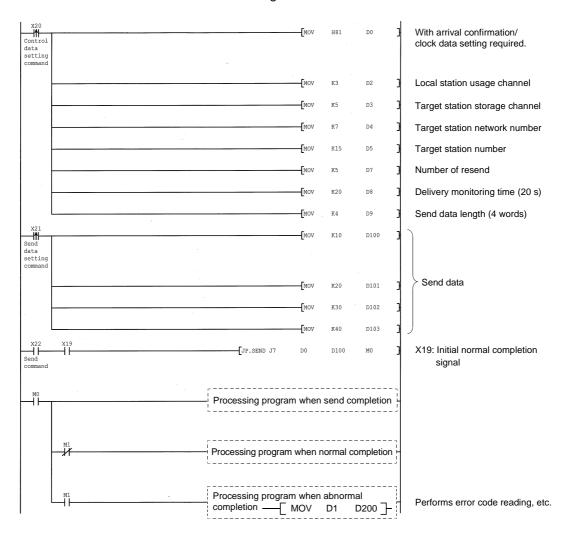
Module User's Manual (Basic)

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# Program example

The following example shows a program that sends data to channel 5 of station number 15.

# When I/O signals of the Ethernet module are X/Y00 to X/Y1F



# 6.10 SREAD Instruction

This instruction	roade de	ata in wor	appiyah h	of other stations.	
I DIS INSTRUCTION	reads da	ata in wor	o devices	or other stations.	

		Applicable device								
Set data	Interna	l device	File register	MELSEC	CNET/H, CNET/10 J□\□	Special module U□\G□	Index register Zn	Constant K, H	Others	
	Bit	Word		Bit	Word					
(S1)			0			_	_			
(S2)			0	<del>_</del>						
(D1)			0			_	_			
(D2)		0				_	_	•		
(D3)	0					_	_			

[Instruction [Executing symbol] condition]	Command	) (D3)
SREAD	GP.SREAD Un (S1) (S2) (D1) (D2	) (D3)

# Setting data

Set data	Description	Set by ( * <sup>1</sup> )	Data type	
Jn	Network number of the local station (1 to 239, 254) 254: The network designated by the valid module during other station access.	User	Binary 16 bits	
Un	Start I/O signal of the local station's Ethernet module. (00 to FE: The higher 2 digits of the 3-digit I/O signal.)	USE!	Character string	
(S1)	Head device of the local station that stores the control data. * 1	User, system		
(S2)	Head device of the target station from which data is read.	User	Device name	
(D1)	Head device of the local station that stores data read.			
(D2)	Local station device that is turned on for one scan by the completion of the instruction.  (D2) + 1 is turned on if the instruction execution completes abnormally.	System	Bit	
(D3)	Device of the target station that is turned on for one scan by completion of the instruction. (Read notification device)			

The local devices and the file register for each program cannot be used as devices used in setting data.

## **POINT**

(1) The SREAD instruction can be executed only when the target station is Q/QnACPU.

(The SREAD instruction cannot be executed for an ACPU connected to the MELSECNET/10 or Ethernet network systems.)

Thus, the target station numbers should be limited to Q/QnACPU station numbers.

(2) When reading data from the other station CPU module device with the SREAD instruction, specify the device within the range applicable to the host station CPU module.

(Head device number to be read in other station CPU module (S2)) + (number of read points -1)

(last device number of host station CPU module \*)

- \*: Last device number in host station CPU module having the same device name as (S2).
- (3) When the target station of the SREAD instruction is the Q00J/Q00/Q01CPU, the read notify device for the target station that is set by an argument (D3) is ignored. The operation of the SREAD instruction is identical to that of the READ instruction.
- (4) The SREAD instruction can be programmed without the argument (D3), while the operation is identical to that of the READ instruction. Depending on whether D3 is omitted or not, the SREAD instruction can be operated differently.

#### Control data

See Section 6.4 for information about how to handle the control data of the SREAD instruction when reading from the word device memory of other station.

The control data should be handled in the same way as when reading the word device memory using the READ instruction. Thus, this section omits its explanation.

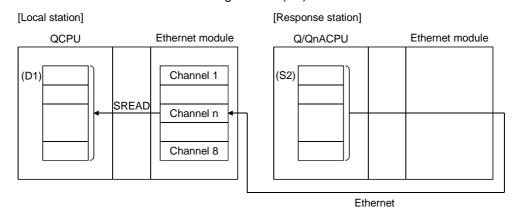
\* The number of steps for the SREAD instruction is 10.

## **Functions**

(1) This instruction reads the designated word device data of the station designated with the target station network number and target station number in the control data. The station must be connected to an MELSECNET/H, MELSECNET/10 or Ethernet network system.

When reading the device data from other station is completed, the completion device designated in (D2) turns on.

Also, when sending the device data designated in (S2) is completed, the device on other station designated in (D3) turns on.



- (2) Device data can be read from stations connected to either the MELSECNET/H, MELSECNET/10 or Ethernet networks having the designated numbers, in addition to stations connected to the local station's network.
- (3) The data link instruction and instructions for the Ethernet network system cannot be executed at two or more locations for the same channel. If the execution conditions are met at two or more locations at the same time, instructions to be executed later have to wait until the channel becomes available because handshaking is automatically performed at the execution of the first instruction.
- (4) Whether the SREAD instruction is being executed or has been completed normally or abnormally can be checked with the send/receive instruction flag corresponding to the channel used, completion device (D2), or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the SREAD instruction is completed, and turns off at the next END processing.
  - (b) Status display device at completion ((D2) + 1) Turns on and off depending on the completion status of the SREAD instruction.

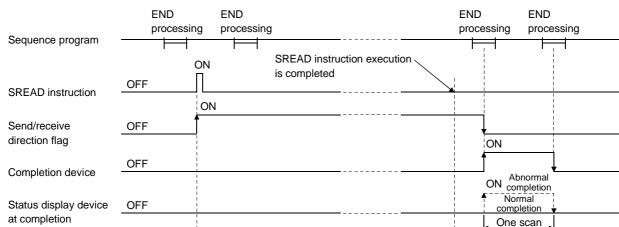
Normal completion : Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where

the SREAD instruction is completed, and turns off at

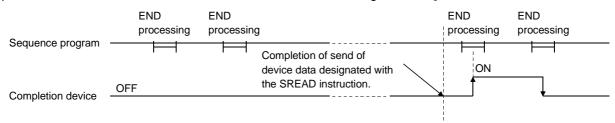
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the next END processing.



# [Operation of the local station when the SREAD instruction is being executed]

## [Operation of the other station when the SREAD instruction is being executed]



(5) When the instruction is executed using J.SREAD/G.SREAD, the next read processing is executed in succession after one read processing is completed while the read command is on.

When the instruction is executed using JP.SREAD/GP.SREAD, the read processing is executed only once when the read command switches from off to on (at rise).

## Errors

(1) When a dedicated instruction ends with an error, the abnormal completion signal (D2) + 1 turns on and the error code is stored in the completion status (S1) + 1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design, Maintenance

and Inspection)

C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's Manual (Basic)

## Program example

See the program example of the READ instruction described in Section 6.4. The SREAD instruction only differs from the READ instruction on one point, namely that the read notification device (D3) is designated at the end of arguments.

# 6.11 SWRITE Instruction

This instr	ruction	writes	data	to word	devices	$\cap$ f $\cap$	ther sta	tions
11113 111311	action	WIILES	uala	to work		OI O	illel sia	แบบเอ.

	Applicable device								
Set data	Interna	l device	File register	MELSEC	CNET/H, CNET/10 J□\□	Special module U□\G□	Index register Zn	Constant K, H	Others
	Bit	Word		Bit	Word				
(S1)			0			_	_		
(S2)			0			_	_		
(D1)			0	_					
(D2)	0			<del>-</del>					
(D3)	0					_	_		

[Instruction [Executing symbol] condition]	Command
SWRITE —	JP.SWRITE Jn (S1) (S2) (D1) (D2) (D3)
SWRITE	Command

# Setting data

Set data	Description	Set by ( * <sup>1</sup> )	Data type
Jn	Network number of the local station (1 to 239, 254) 254: The network designated by the valid module during other station access.	User	Binary 16 bits
Un	Start I/O signal of the local station's Ethernet net module. (00 to FE: The higher 2 digits of the 3-digit I/O signal.)		Character string
(S1)	Head device of the local station that stores the control data. * 1	User, system	
(S2)	Head device of the local station that stores data to be written.	Haan	Device name
(D1)	Head device of the target station to which data is written.	User	
(D2)	Local station device that is turned on for one scan by the completion of the instruction.  (D2) + 1 is turned on if the instruction execution completes abnormally.	System	Bit
(D3)	Device of the target station that is turned on for one scan by the completion of the instruction. (Write notification device)	·	

The local devices and the file register for each program cannot be used as devices used in setting data.

## **POINT**

- (1) The SWRITE instruction can be executed only when the target station is a Q/QnACPU.
  - (The SWRITE instruction cannot be executed for an ACPU connected to the MELSECNET/10 or Ethernet network system.) Thus, the target station number should be limited to the Q/QnACPU station numbers.
- (2) When writing data from the other station CPU module device with the SWRITE instruction, specify the device within the range applicable to the host station CPU module.
  - (Head device number to be write in other station CPU module (S2)) + (number of write points -1)
    - < (last device number of host station CPU module \*)</p>
  - \*: Last device number in host station CPU module having the same device name as (S2).
- (3) When the target station of the SWRITE instruction is the Q00J/Q00/Q01CPU, the write notify device for the target station that is set by an argument (D3) is ignored. The operation of the SWRITE instruction is identical to that of the WRITE instruction.
- (4) The SWRITE instruction can be programmed without the argument (D3), while the operation is identical to that of the WRITE instruction. Depending on whether D3 is omitted or not, the SWRITE instruction can be operated differently.

#### Control data

See Section 6.12 for information about how to handle the control data of the SWRITE instruction when writing to the word device memory of other station.

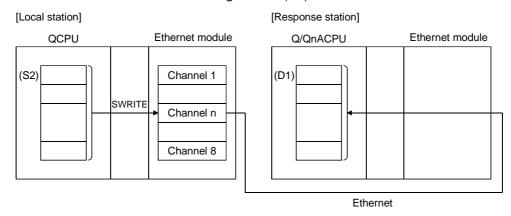
The control data should be handled is the same as when writing to the word device memory using the WRITE instruction. Thus, this section omits its explanation.

\* The number of steps for the SWRITE instruction is 10.

#### **Functions**

(1) This instruction writes data in the device designated in (S2) and succeeding devices of the local station to the word devices of the station, which is connected to either the MELSECNET/H, MELSECNET/10 or Ethernet, that is designated with the target station network number and target station number in the control data. When writing device data from other station number is completed, the completion device designated in (D2) turns on.

Also , when writing the device data designated in (S2) is completed, the device on the other station designated in (D3) turns on.



- (2) Device data can be written to stations connected to either the MELSECNET/H, MELSECNET/10 or Ethernet networks having the designated numbers, in addition to stations connected to the local station's network.
- (3) The data link instruction and instructions for the Ethernet network system cannot be executed at two or more locations for the same channel. If the execution conditions are met at two or more locations at the same time, instructions to be executed later have to wait until the channel becomes available because handshaking is automatically performed at the execution of the first instruction.
- (4) Whether the SWRITE instruction is being executed or has been completed normally or abnormally can be checked with the send/receive instruction flag corresponds to the channel used, completion device (D2), or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the SWRITE instruction is completed, and turns off at the next END processing.

(b) Status display device at completion ((D2) + 1)

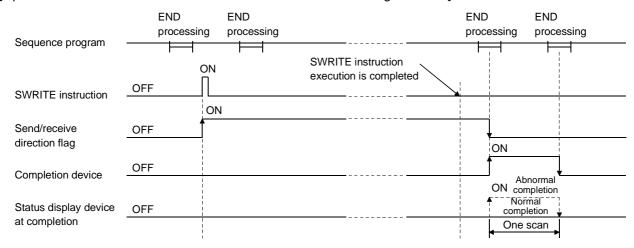
Turns on and off depending on the completion status of the SWRITE instruction.

Normal completion : Stays off and does not change.

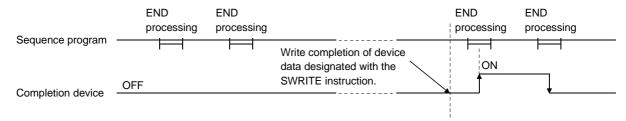
Abnormal completion: Turns on at the END processing of the scan where the SWRITE instruction is completed, and turns off at the next END processing.

·

## [Operation of the local station when the SWRITE instruction is being executed]



## [Operation of the other station when the SWRITE instruction is being executed]



(5) When the instruction is executed using J.SWRITE/G.SWRITE, the next read processing is executed in succession after one read processing is completed while the read command is on.

When the instruction is executed using JP.SWRITE /GP.SWRITE, the read processing is executed only once when the read command switches from off to on (at rise).

## **Errors**

(1) When a dedicated instruction ends with an error, the abnormal completion signal (D2) + 1 turns on and the error code is stored in the completion status (S1) + 1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design, Maintenance

and Inspection)

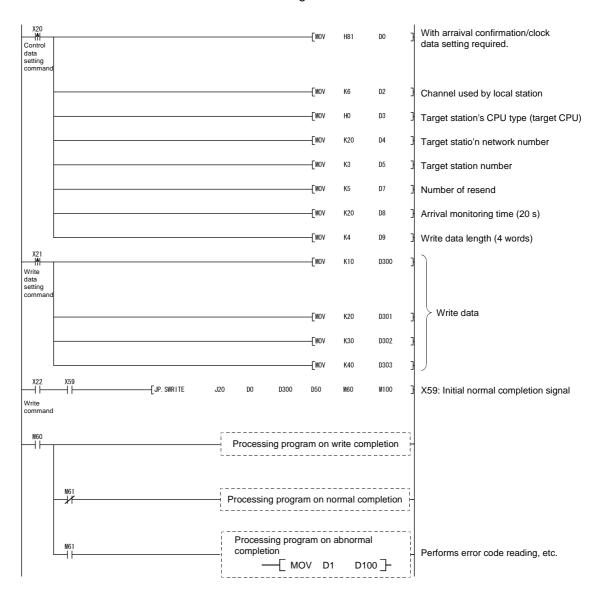
C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's Manual (Basic)

# Program example

The following example shows a program that writes the data stored in D300 to 303 to D50 to 53 of station number 3

When I/O signals of the Ethernet module are X/Y40 to X/Y5F

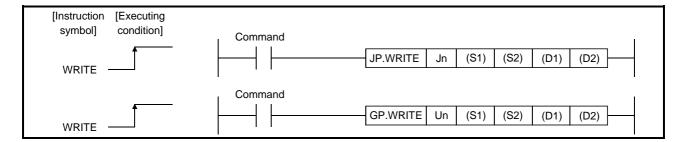


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# 6.12 WRITE Instruction

This instruction	writes	data to	word	devices	of a	other stations
	WILLOS	uata t	WOIG	uc vicco	<b>UI</b> 1	onici stations.

		Applicable device								
Set data	Internal	device	File register	MELSECNET/H, MELSECNET/10 Special module		Special module U□\G□	Index register Zn	Constant K, H	Others	
	Bit	Word		Bit	Word					
(S1)			0			_	_			
(S2)			0			_	_			
(D1)			0	_						
(D2)		0		_						



# Setting data

Set data	Description	Set by ( * <sup>1</sup> )	Data type	
Jn	Network number of the local station (1 to 239, 254) 254: The network designated by the valid module during other station access.	User	Binary 16 bits	
Un	Start I/O signal of the local station's Ethernet module. (00 to FE: The higher 2 digits of the 3-digit I/O signal)		Character string	
(S1)	Head device of the local station that stores the control data. * 1	User, system		
(S2)	Head device of the local station that stores data to be written.	Haan	Device name	
(D1)	Head device of the target station to which data is written.	User		
(D2)	Local station device that is turned on for one scan by the completion of the instruction.  (D2) + 1 is turned on if the instruction execution completes abnormally.	System	Bit	

The local devices and the file register for each program cannot be used as devices used in setting data.

## **POINT**

(1) The WRITE instruction can be executed only when the target station is the Q/QnACPU.

(The WRITE instruction cannot be executed for an ACPU connected to the MELSECNET/10 or Ethernet network systems.)

Thus, the target station numbers should be limited to Q/QnACPU station numbers.

(2) When writing data from the other station CPU module device with the WRITE instruction, specify the device within the range applicable to the host station CPU module.

(Head device number to be write in other station CPU module (S2)) + (number of write points -1)

<(last device number of host station CPU module \*)</pre>

\*: Last device number in host station CPU module having the same device name as (S2).

# REMARK

- \*1: When the instruction is completed, the completion status ((S1) + 1) and the clock data ((S1) + 11 to (S1) + 17) at abnormal occurrence are stored in the control data.
- 2) The number of steps for the WRITE instruction is 10.

# Control data

Device	Item	Set data	Setting range	Set by ( * 1)
(S1) + 0	Execution/abnormal complete type	b15 to b7 to b0  0 2) 0 1)  1) Execution type (bit 0) 0: No arrival confirmation When the target station is on the same network: Completed when the data is sent from the local station.  When the target station is on other network: Completed when the data arrives at the relay station on the network of the local station.  Complete Target station  Target station  1: With arrival confirmation Completed when data is written to the target station.  1: With arrival confirmation Completed when data is written to the target station.  2) Abnormal complete type (bit 7) Designate whether the clock data setting is required or not at abnormal completion. 0: Clock data setting not required: Clock data setting required: Clock data setting required Clock data setting required Clock data at error occurrence is stored in (S1) + 11 to (S1) + 17.	0001н 0081н	User
(S1) + 1	Completion status	Stores the status at the completion of the instruction.  0 : Normal  Other than 0: Abnormal (error code) ( * <sup>2</sup> )	_	System
(S1) + 2	Channel used by the local station	Set the channel used by the local station.  1 to 8 (channel)	1 to 8	User
(S1) + 3	Target station's CPU type (* <sup>3</sup> )	Specify the CPU type on the target station.  Setting value  Single CPU or CPU in the system directly connected to the local station (Same as "03FFH")  03D0H  Control system CPU (* 5)  03D1H  Standby system CPU (* 5)  03D2H  System A CPU  03D3H  System B CPU  03FFH  Single CPU or CPU in the system directly connected to the local station	0000н 03D0н to 03D3н 03FFн	User
(S1) + 4	Target station network number	Designate the network number of the target station.  1 to 239: Network number  254 : When 254 is designated in Jn (The network designated by the valid module during other station access)	1 to 239, 254	User

(Continued to the next page)

Device	Item	Set data	Setting range	Set by ( * <sup>1</sup> )
(S1) + 5	Target station number	Designate the target station.  1 to 64 : The station with the corresponding station number  81H to A0H: All the station with the indicated group number (Can be set when the execution type designated in (S1) is "0: No arrival confirmation".)  FFH : All stations having the target network number (simultaneous broadcast):  Excluding the local station (Can be set when the execution type designated in (S1) is "0: No arrival confirmation".)	1 to 64 81н to A0н FFн	User
(S1) + 6	<u> </u>	(Fixed value)		_
(S1) + 7	Number of resend	Valid when the execution type designated in (S1) is "1: With arrival confirmation."  1) At instruction execution Set the number of resends when the instruction fails to complete within the monitoring time designated by (S1) + 8. 0 to 15 (Time)  2) At instruction completion Store the number of resends executed (result). 0 to 15 (Time)	0 to 15	User system
(S1) + 8	Arrival monitoring time	Valid when the execution type designated in (S1) is "1: With arrival confirmation." Set the monitoring time until the instruction completion equal to the TCP resend timer value or greater.  When the instruction fails to complete within the monitoring time, it is resent for the number of resends designated in (S1) + 7.  0 to TCP resend timer value:  The monitoring time is reset to the TCP resend timer value.  (TCP resend timer value + 1) to 16383:  Monitoring time (units: s).	1 to 16383 0 to TCP resend timer value	User
(S1) + 9	Write data length	Designate the number of write data in (S2) to (S2) + n.  1 to 480 (Word)	1 to 480	User
(S1) + 10	(Not used)	_	_	_
(S1) + 11	Clock set flag	Store the valid/invalid status of the clock data in (S1) + 12 to (S1) + 17.  0: Invalid  1: Valid	_	System
(S1) + 12		Higher 8 bits: month (01н to 12н), lower 8 bits: last 2 digits of year (00н to 99н)		
(S1) + 13	Clock data	Higher 8 bits: hour (00 <sub>H</sub> to 23 <sub>H</sub> ), lower 8 bits: date (01 <sub>H</sub> to 31 <sub>H</sub> )		
(S1) + 14	(set only when errors occur)	Higher 8 bits: second (00н to 59н), lower 8 bits: minute (00н to 59н)	_	System
(S1) + 15		Higher 8 bits: first 2 digits of year (00н to 99н), lower 8 bits: day of the week (00н (Sunday) to 06н (Saturday))		
(S1) + 16	Abnormal detection network number	Stores the network number of the station that detected an abnormality. (* 4)  1 to 239 (Network number)	1 to 239	
(S1) + 17	Abnormal detection station number	Stores the station number of the station that detected an abnormality. (* <sup>4</sup> )  1 to 64 (Station number)	1 to 64	System

## **POINT**

- (1) The data written storage device (D1) requires a contiguous free area equal to or greater than the write data length ((S1) + 9) (maximum of 480 words).
- (2) In order to increase the reliability of the function, it is recommended to execute the instruction by setting the execution type to "With arrival confirmation" when a number from one to 64 is designated for the target station number. When 81H to A0H or FFH is designated for the target station number, the instruction should be executed by setting the execution type to "No arrival confirmation".
- (3) When writing to a device of the same station from multiple stations, make sure that the timings of the write operations do not coincide.

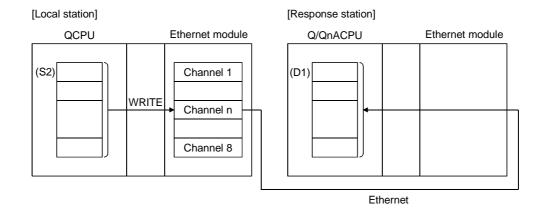
  If the communication itself is normally completed when the execution type is set to "No arrival confirmation," the send is considered normally completed on the write source station even if the contents of the send data are abnormal. In addition, even if the contents of the send data are normal, when the instruction is executed to the same station from multiple stations, a timeout error (C083H) will occur on the write source station.
- \*1 The "Set by" column indicates the following:
  - User: Data is set by the user before executing a dedicated instruction.
  - System: The PLC CPU stores the execution result of a dedicated instruction.
- \*2 For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic)
- \*3 It can be specified when the local station has an Ethernet module of function version D or later. (Not available for any other case. Access to the target CPU is required.)
- \*4 Nothing is stored if the execution source detects an error when receiving an instruction.
- \*5 When the WRITE instruction is executed to the redundant system with a control system or standby system CPU specified, the instruction may be unsuccessfully completed due to system switching occurred on the target station (error code: 4244н, 4248н).

If this has occurred, execute the WRITE instruction again.

#### **Functions**

(1) This instruction writes data for the device designated in (S2) of the local station and succeeding devices to the word devices of the station designated with the target station network number and target station number in the control data. The station must be connected to either an MELSECNET/H, MELSECNET/10 or Ethernet network system.

When writing device data to other station number is completed, the completion device designated in (D2) turns on.

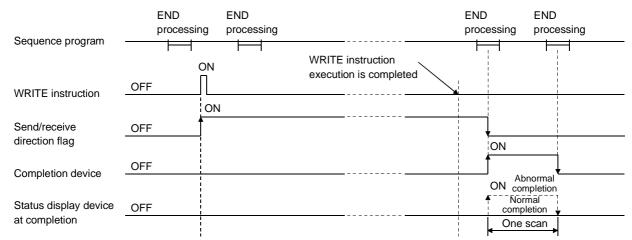


- (2) Data can be written to stations connected to either the MELSECNET/H, MELSECNET/10 or Ethernet networks having the designated numbers, in addition to stations connected to the local station's network.
- (3) The data link instruction and instructions for the Ethernet network system cannot be executed at two or more locations for the same channel. If the execution conditions are met at two or more locations at the same time, instructions to be executed later have to wait until the channel becomes available because handshaking is automatically performed at the execution of the first instruction.
- (4) Whether the WRITE instruction is being executed or has been completed normally or abnormally can be checked with the completion device (D2) or completion status display flag ((D2) + 1) designated in the set data.
  - (a) Completion device (D2)
     Turns on at the END processing of the scan where the WRITE instruction is completed, and turns off at the next END processing.
  - (b) Status display device at completion ((D2) + 1) Turns on and off depending on the completion status of the WRITE instruction.

Normal completion : Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the WRITE instruction is completed, and turns off at

the next END processing.



[Operation of the local station when the WRITE instruction is being executed]

(5) When the instruction is executed using J.WRITE/G.WRITE, the next write processing is executed in succession after one write processing is completed while the write command is on. When the instruction is executed using JP.WRITE/GP.WRITE, the write processing is executed only once when the write command switches from off to on (at rise).

#### Errors

(1) When a dedicated instruction ends with an error, the abnormal completion signal (D2) + 1 turns on and the error code is stored in the completion status (S1) + 1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design, Maintenance

and Inspection)

C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's Manual (Basic)

## Program example

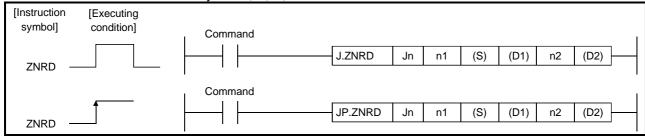
See the program example of the SWRITE instruction described in Section 6.11. The SWRITE instruction only differs from the WRITE instruction on one point, namely that the write notification device (D3) is not designated at the end of arguments.

# 6.13 ZNRD Instruction

This instruction reads	data from word d	devices of other	stations (ACPU).

		Applicable device								
Set data	Interna	l device	File register	MELSEC	CNET/H, CNET/10 J□∖□	Special module U□\G□	Index register Zn	Constant K, H	Others	
	Bit	Word		Bit	Word			·		
n1			0			_		0	_	
(S)		0(*)	_			_			_	
(D1)	1		0			_			_	
n2		0		•		_		0	_	
(D2)		0				_	·		_	

# \*: Can only use T, C, D, W



# Setting data

	Description	Setting range	Set by ( * <sup>1</sup> )	Data type
Jn	Target station network number  Designates the network number of the target station.	1 to 239	Unon	Binary 16 bits
n1	Target station number  Designates the station number of the target station.	1 to 64 (Constant)	User	Character string
(S)	Data read storage head device (target station)  Designates the head device of the target station that stores data to be read.	_		Device name
(D1)	Data read storage head device (local station)  Designates the head device of the local station that stores the data read.	_	_	Device name
n2	Length of data read  Designates the number of data (word count) to be read.	Designates the number of data (word count) to When reading from PLC CPUs		Binary 16 bits
(D2)	Read complete device (local station)  Designate device that is turned on for one scan by the read completion  (D2) off: Incomplete on: Complete  (D2) + 1 off: Normal on: Abnormal	_	System	Bit

The local devices and the file register for each program cannot be used as the device used for the setting data.

## **POINT**

(1) The ZNRD instruction can be executed when the target station is a QCPU or QnACPU.

Access to an AnUCPU is available via MELSECNET/10.

(2) When reading data from the other station CPU module device with the ZNRD instruction, specify the device within the range applicable to the host station CPU module.

(Head device number to be read in other station CPU module (S)) + (number of read points -1)

< (last device number of host station CPU module \*)

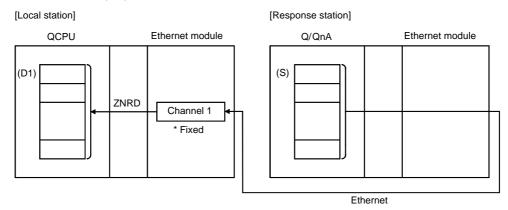
- \*: Last device number in host station CPU module having the same device name as (S).
- (3) The normal/abnormal completion status at read completion is stored in the data link instruction communication completion result (Channel 1) storage area (address: 207) of the buffer memory.

If the read completion device ((D2) + 1) is on due to abnormal end, read the error code stored in the area mentioned above and correct the error accordingly.

#### **Functions**

(1) This instruction reads n2 points of data from the word device of the connected station having the network number designated by Jn/n1 in the Ethernet network system.

When reading the device data is completed, the completion device designated in (D2) turns on



- (2) The ZNRD instruction is executed using channel 1 (fixed).
  - The data link instructions and the Ethernet instructions cannot be executed from two or more stations at the same time on the same channel.
  - If the conditions of more than one instruction to be executed match at the same time, the instruction executed later is made to wait until the channel becomes available since handshaking is performed automatically.
- (3) Whether the ZNRD instruction is currently being executed or has been completed normally or abnormally can be checked with the completion device (D2) designated in the set data.
  - (a) Completion device (D2)

Turns on at the END processing of the scan where the ZNRD instruction is completed, and turns off at the next END processing.

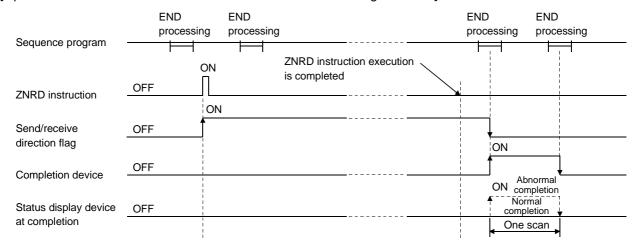
(b) Status display device at completion ((D2) + 1)

Turns on and off depending on the completion status of the ZNRD instruction.

Normal completion : Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the ZNRD instruction is completed, and turns off at the next END processing.

[Operation of the local station when the ZNRD instruction is being executed]



#### Errors

(1) When a dedicated instruction ends with an error, the abnormal completion signal (D2) + 1 turns on and the error code is stored in the completion status (S) + 1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design, Maintenance

and Inspection)

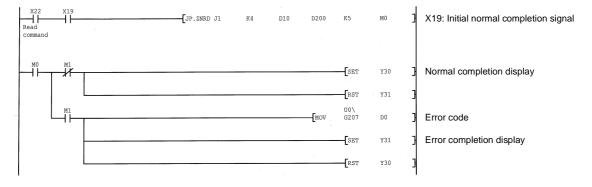
C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's Manual (Basic)

# Program example

A program that reads the contents of D10 to 14 of station number 4 from D200 to 204 of station number 1.

When I/O signals of the Ethernet module are X/Y00 to X/Y1F



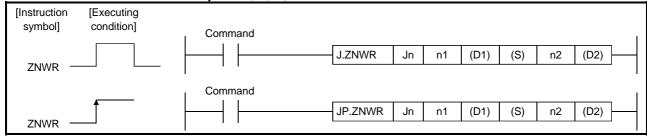
6 - 61 6 - 61

# 6.14 ZNWR Instruction

This instruction writes	data to word device	es of other stations	(ACPU).

	Applicable device								
Set data	Interna	l device	File register	MELSEO MELSEO Direct	CNET/10	Special module U□\G□	Index register Zn	Constant K, H	Others
	Bit	Word		Bit	Word				
n1	1		0			_		0	_
(D1)	1	0(*)	_		_			_	
(S)	1		0			_			_
n2		0			•	_		0	_
(D2)		0				_		_	_

# \*: Can only use T, C, D, W



# Setting data

	Description	Setting range	Set by ( * <sup>1</sup> )	Data type
Jn	Target station network number  Designates the network number of the target station.	1 to 239		Binary 16 bits
n1	Target station number  Designates the station number of the target station.	1 to 64 (Constant): The station with the corresponding station number 81H to 89H: All stations having the designated group number FFH: All stations having the target network number	User	Character string
(D1)	Data written storage head device (target station)  Designate the head device of the target station to which data is written.	_		Device name
(S)	Data written storage head device (local station)  Designate the head device of the local station that stores the data to be written.	_	_	Device Hame
n2	Length of data written Designates the number of data (word count) to be written.	When writing to Q/QnACPU 1 to 230 (Constant) When writing to PLC CPUs other than Q/QnACPU 1 to 32 (Constant)	User	Binary 16 bits
(D2)	Write completion device (local station)  Designate device that is turned on for one scan by the write completion.  (D2) off: Incomplete on: Complete  (D2) + 1 off: Normal on: Abnormal setting range	_	System	Bit

The local devices and the file register for each program cannot be used as the device used for the setting data.

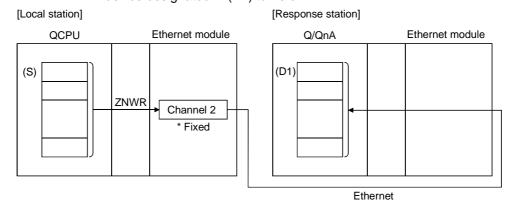
## **POINT**

- The ZNWR instruction can be executed when the target station is a QCPU or QnACPU.
  - Access to an AnUCPU is available via MELSECNET/10.
- (2) When writing data from the other station CPU module device with the ZNWR instruction, specify the device within the range applicable to the host station CPU module.
  - (Head device number to be write in other station CPU module (S)) + (number of write points -1)
    - < (last device number of host station CPU module \*)
  - \*: Last device number in host station CPU module having the same device name as (S).
- (3) The normal/abnormal completion status at write completion is stored in the data link instruction communication completion result (Channel 2) storage area (address: 209) of the buffer memory.

  If the write completion device ((D2) + 1) is on due to abnormal and read the
  - If the write completion device ((D2) + 1) is on due to abnormal end, read the error code stored in the area mentioned above and correct the error accordingly.
- \* For a list of error codes, see Section 11.3.3 of the Q Corresponding Ethernet Interface Module User's Manual (Basic).

#### **Functions**

(1) This instruction write n2 points of data from the word device designated by (S) of the local station to the word device of the connected station having the network number designated by Jn/n1 in the Ethernet network system. When writing the device data to the target station is completed, the completion device designated in (D2) turns on



- (2) The ZNWR instruction is executed using channel 2 (fixed).
  - The data link instructions and the Ethernet instructions cannot be executed from two or more stations at the same time on the same channel.
  - If the conditions of more than one instruction to be executed match at the same time, the instruction executed later is made to wait until the channel becomes available since handshaking is performed automatically.
- (3) Whether the ZNWR instruction is currently being executed or has been completed normally or abnormally can be checked with the completion device (D2) designated in the set data.
  - (a) Completion device (D2)
    - Turns on at the END processing of the scan where the ZNWR instruction is completed, and turns off at the next END processing.

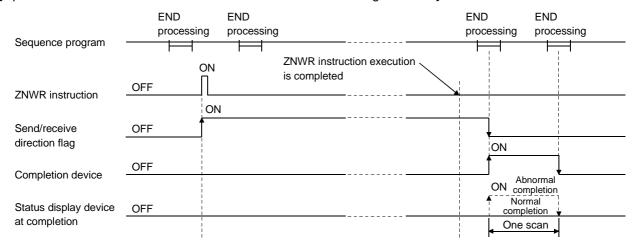
(b) Status display device at completion ((D2) + 1)

Turns on and off depending on the completion status of the ZNWR instruction.

Normal completion : Stays off and does not change.

Abnormal completion: Turns on at the END processing of the scan where the ZNWR instruction is completed, and turns off at the next END processing.

[Operation of the local station when the ZNWR instruction is being executed]



#### Errors

(1) When a dedicated instruction ends with an error, the abnormal completion signal (D2) + 1 turns on and the error code is stored in the completion status (S) + 1. See the following manuals regarding the error code, check the errors and take corrective actions.

<Error codes>

4FFFH or less : QCPU (Q Mode) User's Manual (Hardware Design, Maintenance

and Inspection)

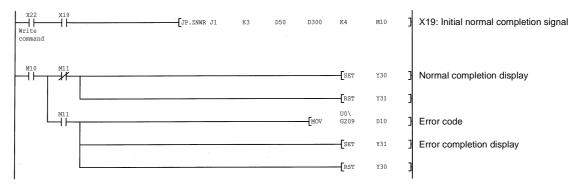
C000H or higher: Section 11.3.3 of the Q Corresponding Ethernet Interface

Module User's Manual (Basic)

# Program example

A program that writes the contents of D300 to 303 of station number 2 to D50 to 53 of station number 3.

When I/O signals of the Ethernet module are X/Y00 to X/Y1F



MEMO		
_		

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# WARRANTY

Please confirm the following product warranty details before using this product.

# 1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company.

However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing onsite that involves replacement of the failed module.

# [Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place.

Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

# [Gratis Warranty Range]

- (1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- (2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
  - 1. Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
  - 2. Failure caused by unapproved modifications, etc., to the product by the user.
  - 3. When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
  - 4. Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
  - 5. Failure caused by external irresistible forces such as fires or abnormal voltages, and Failure caused by force majeure such as earthquakes, lightning, wind and water damage.
  - 6. Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
  - 7. Any other failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

# 2. Onerous repair term after discontinuation of production

- (1) Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued. Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- (2) Product supply (including repair parts) is not available after production is discontinued.

## 3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

## 4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation of damages caused by any cause found not to be the responsibility of Mitsubishi, loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products, replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

#### 5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

# Product application

- (1) In using the Mitsubishi MELSEC programmable logic controller, the usage conditions shall be that the application will not lead to a major accident even if any problem or fault should occur in the programmable logic controller device, and that backup and fail-safe functions are systematically provided outside of the device for any problem or fault.
- (2) The Mitsubishi programmable logic controller has been designed and manufactured for applications in general industries, etc. Thus, applications in which the public could be affected such as in nuclear power plants and other power plants operated by respective power companies, and applications in which a special quality assurance system is required, such as for Railway companies or Public service purposes shall be excluded from the programmable logic controller applications.
  - In addition, applications in which human life or property that could be greatly affected, such as in aircraft, medical applications, incineration and fuel devices, manned transportation, equipment for recreation and amusement, and safety devices, shall also be excluded from the programmable logic controller range of applications.
  - However, in certain cases, some applications may be possible, providing the user consults their local Mitsubishi representative outlining the special requirements of the project, and providing that all parties concerned agree to the special circumstances, solely at the users discretion.

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# Q Corresponding Ethernet Interface Module

User's Manual (Application)

MODEL	QJ71E71-U-OU-E	
MODEL 13JL89		
SH(NA)-080010-G(0406)MEE		



HEAD OFFICE : 1-8-12, OFFICE TOWER Z 14F HARUMI CHUO-KU 104-6212, JAPAN NAGOYA WORKS : 1-14 , YADA-MINAMI 5-CHOME , HIGASHI-KU, NAGOYA , JAPAN

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