ATTENTION

Know Your Computer and Be Sure You Are Using the Correct Software

SWTPC has offered, or is now offering, three types of 6809 computers. In order to make SWTPC supplied software work correctly it is necessary to recognize what type of computer you have. Below is a description of each of the three types and some of the characteristics of each. The nomenclature for the motherboard of each type of computer is printed on the motherboard for easy identification.

<u>/09</u>

The /09 computer is any SWTPC 6809 computer which uses an MP-B or MP-B2 motherboard. This computer uses the single port MP-S serial interface and the MP-L and MP-LA parallel interfaces. This computer can have up to 56K of 4K, 8K, 16K and 32K memory boards. Its chassis RESET button is on the right side of the front panel.

69A and 69K

The 69A and 69K computers use the MP-B3 motherboard. The 69A and 69K are identical except that the A is factory.assembled and the K is the kit version. Each interface port in this type computer requires 16 addresses and uses the MP-S2 serial and MP-L2 parallel interface boards. This computer can have up to 56K of 4K, 8K, 16K and 32K memory boards. Its chassis RESET button is on the left side of the front panel.

S/09

The S/09 computer uses the MP-MB motherboard. Each interface port in this computer requires 16 addresses and uses the MP-S2 serial and MP-L2 parallel interfaces. This computer also contains a standard parallel output port and an integral interrupt timer on the MP-ID board. The S/09 can use up to 384K of 128K memory array boards. Its chassis RESET button is on the left side of the front panel.

Be Sure To Use The Correct Software

Although the /09, 69A, 69K and S/09 computers are all basically the same, small differences in I/0 port assignments, speed, features and memory types dictate that certain programs, such as printer drivers, function differently on the various models. After booting the system diskette, FLEX will automatically configure the operating system as completely as it can to certain initial values of speed, CPU type, etc. A special utility (SBOX) has been supplied to examine and change the initial values and computer type. After booting the supplied diskette, this utility should be run to be sure that ALL of the displayed characteristics match EXACTLY with the computer being used. Any necessary changes can be made using the SBOX utility. This will usually be necessary only on 109 computers and 69A/69K computers operating at 2 MHZ.

Product: FLEX 2.6 DOS Date: February 26, 1980

Configuring FLEX 2.6 for Computers with MP-B3 Motherboards (69A, 69K computers, not S/09 Computers)

FLEX 2.6 may incorrectly auto configure on computers with MP-B3 motherboards by indicating the presence of an internal interval timer. This can be checked by running the SBOX utility contained on the FLEX 2.6 disk. If the utility responds with:

-- Interval Timer = Yes

then the SBOX utility must be used to set the Interval Timer response to NO. This must be done even if the system has an optional MP-T interrupt timer plugged on to the system. The timer configurator of the SBOX utility is concerned with the presence of the 6840 type timer which is standard on S/09 computers rather than the optional MP-T timer board. S/09 computers are the only ones at the time of this writing that should respond with "Interval Timer = Yes" response.

To set the Interval Timer response to NO, enter the following:

SBOX, TIMER=NO

The SBOX command will change and confirm that the timer parameter has been properly set.

+++SB0X

SWTPC Configurator -- Version 2.1
-- Memory Size = _K
-- I/O Port Size = 16
-- CPU Clock Rate = 1 MHz
-- Power Line Frequency = _Hz
-- Extended Addressing = No
-- Interval Timer = No
-- Real Time Clock = No
-- Upper Case Only = Yes

If the Interval Timer parameter is not properly set as outlined above the ${\sf P}$ command and printer spooling will not function correctly.

General Notes

Technical Systems Consultants, Inc.

GENERAL NOTES

This section contains suggestions on getting $FLEX^{m}$ 9.0 up on your system and on compatibility with your existing hardware and software. This manual assumes you already have a working disk system and are familiar with the basics of floppy disk systems such as proper disk handling techniques, inserting and removing disks from the drives, etc.

One important point should be made in regard to getting FLEX "up and running". You receive only one disk and it is crucial that you protect this disk with your life. If you take the following steps, you might save yourself a lot of headaches and additional expense:

- 1) Write-protect the FLEX disk before you ever insert it into a drive. Consult your disk system hardware manual or the FLEX User's Manual for details on write-protecting a disk.
- 2) Boot up the FLEX system and once running copy all files from the original FLEX disk to a new disk. Next perform a LINK command to FLEX.SYS on this new disk.
- 3) Now remove the original FLEX disk and store it in a safe place. It should never be used again unless you wipe out all the new FLEX disks you make and need to repeat this procedure. Use the new FLEX disk you have made for all future disk work.

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HARDWARE REQUIREMENTS

This section discusses the hardware requirements for running FLEX 9.0. This version is setup for th6 Southwest Technical Products Corporation's disk systems: the MF-68 or MF-69 5-inch minidiskette, the DMAF1 or DMAF2 8-inch diskette, and the CDS-1 Winchester disk unit.

Memory Requirements

The FLEX disk operating system itself resides in the range of \$C000 to \$DFFF. This means you will need 8K of memory starting at \$C000. You should be certain your particular system can accept memory in this region.

You must also have "User Memory" (RAM) starting at location \$0000 and running continuously up from there. The more user memory you have in your system the better off you will be. This is because you will be able to run larger Programs and because software which works with files that are larger than memory can hold (such as the editor or sort/merge) will operate more efficiently and quickly. Although FLEX resides at \$C000, certain of its commands utilize the lower end of this user RAM space. A minimum of 12K of RAM is required for such purposes.

Monitor ROM

As sold, this version of FLEX requires the S-BUG monitor ROM from SWTPc (or equivalent). FLEX 9.0 has its own internal terminal I/O routines, so S-BUG's are not used. These routines assume an ACIA at location \$E004. S-BUG is required, however, for setting up interrupt vectors.

There are two exceptions to this ROM requirement. The first is that the interrupt vectors need not be set if no program will use interrupts. Note that many programs such as printer spooling, the SWTPc Editors, etc., do make use of interrupts. Thus if you did not require printer spooling or editing you would not require any monitor ROM at all except for booting the system up and to jump to when exiting FLEX. The second exception is to make use of the user adaptable version of FLEX which is supplied on disk along with the standard version. See 'Adapting FLEX to Custom Monitors' for details.

Printer Spooling

FLEX 9.0 Version 2.6 supports printer spooling which allows you to list a file (or files) on a line printer at the same time as you perform other FLEX operations such as editing, assembling, running BASIC, etc. In order to do this, FLEX requires an S/09 computer system, or an MP-T interrupt timer board on I/O port #5 for /09, 69/A and 69/K computer systems.

DISK COMPATIBILITY

Disks created under 6809 FLEX 9.0 are compatible with those created under 6800 FLEX 1.0 on the 8" drives or 6800 FLEX 2.0 on the 5" drives. The reverse is also true, meaning that FLEX 9.0 can read disks created by one of those 6800 FLEX systems. This means that transferring text files will require nothing more than copying with the COPY command. In fact it is not even necessary to put the files on a new disk. As long as a disk is being used for work files only (no disk command files) it may be used interchangeably.

The one place where the disks are different is in the bootstrap loader which the NEWDISK command places on track 0 when a disk is initialized. Obviously the loader must be different for 6800 and 68C9. This simply means that a disk initialized with the 6809 NEWDISK command cannot be used to boot 6800 FLEX and vice versa.

The new double-density system is an exception to all the above. It cannot be used to read disks created by the original 6800 single-density system. Any disks, however, created as single-density with the new double-density version of NEWDISK (done by answering 'N' to the prompt 'Double-Sided Disk?') can be read on either a single or double density system. This is because the new double-density NEWDISK writes FF's in certain gap areas whereas the old single-density NEWDISK wrote 00's. The single-density controller board (which uses the Western Digital 1771) can read either type, but the double-density board (which uses the Western Digital 1791) can only read the type with FF's.

SOFTWARE COMPATIBILITY

6809 object code is NOT at all compatible with 6800 object code. This means you cannot run binary command files from a 6800 system on a 6809 system. Since 6809 FLEX can read a 6800 FLEX disk and vice versa you must be careful not to execute a 6800 command in a 6809 system and again, vice versa.

Where the 6809 and 6800 ARE compatible is in the source code. Thus, if you have the source listing for a 6800 program on disk, it can be reassembled by the 6809 assembler to produce executable 6809 object code. Of course if the program calls any routines from FLEX, these addresses will have to be changed since 6809 FLEX resides at \$C000 (6800 FLEX is at \$A000). This is usually a matter of simply changing all occurrences of 'A' to 'C' and all 'B' to 'D' with the editor.

ADAPTING FLEX

The FLEX 9.0 disk supplied has two copies of the FLEX object code. One is called FLEX.SYS and is ready to boot up with SWTPc disk hardware. The second is called FLEX.COR which represents the CORe or main body of FLEX. It differs from the bootable form of FLEX in that it does not have any terminal or disk I/O routines built in. This allows the user to modify these I/O drivers, if desired, to produce a customized version of FLEX. Note that in order to produce this customized version you must have FLEX up and running so you will need the bootable version (FLEX.SYS). The customized terminal and disk I/O routines are supplied in two packages. We will discuss them separately and then examine how to add them onto FLEX.COR to produce a new, customized, bootable version of FLEX.

The CUSTOM I/O DRIVER PACKAGE

This package allows the user to alter the functioning of the terminal I/O and the functioning of printer spooling. Nine routines and two interrupt vectors are set up in this package. There is a space reserved for these routines beginning at location \$D370 and ending at \$D3E6. The address of these 11 items must be setup in a jump table found at locations \$D3E7 thru \$D3FB. A copy of the Custom I/O Driver Package used to produce FLEX.SYS is included at the end of the General Notes section. Use it as a guide for writing your own.

A description of each routine and vector follows.

INCH

The address of the input character routine should be placed at \$D3FB. This routine should get one input character from the terminal and return it in 'A' with the parity bit cleared. It should also echo the character to the output device. Only 'A' and the condition codes may be modified.

OUTCH

The address of the output character should be placed at \$D3F9. This routine should output the character found in 'A' to the output device. No registers should be modified except condition codes.

STAT

The address of the STAT routine should be placed at \$D3F7. This routine checks the status of the input device. That is to say, it checks to see if a character has been typed on the keyboard. If so, a Not-Equal condition should be returned. If no character has been typed, an Equal to zero condition should be returned. No registers may be modified except condition codes.

TINIT

The address of the terminal initialization routine should be placed at \$D3F5. This routine performs any necessary initialization for terminal I/O to take place. Any register may be modified except 'S'.

MONITR

This is the address to which execution will transfer when FLEX is exited. It is generallly the reentry point of the system's monitor ROM The address should be placed at \$D3F3.

TMINT

The address of the timer initialization routine should be placed at \$D3F1. This routine performs any necessary initialization for the interrupt timer used by the printer spooling process. Any register may be modified except 'S'.

TMON

The address of the timer on routine should be placed at \$D3EF. This routines "turns the timer on" or in other words starts the interval IRQ interrupts. Any registers execpt 'S' may be modified.

TMOFF

The address of the timer off routine should be placed at \$D3ED. This routine "turns the timer off" or in other words stops the interval IRQ interrupts. Any registers except 'S' may be modified.

IRQVEC

The IRQ vector is an address of a two byte location in RAM where FLEX can stuff the address of its IRQ interrupt handler routine. In other words, when an IRQ interrupt occurs control should be transferred to the address stored at the location specified by the IRQ vector. This IRQ vector location (address) should be placed at \$D3EB.

SWIVEC

The SWI3 vector is an address of a two byte location in RAM where FLEX can stuff the address of its SWI3 interrupt handler routine. In other words, when an SWI3 interrupt occurs control should be transferred to the address stored at the location specified by the SWI3 vector. This SWI3 vector location (address) should be placed at \$D3E9.

IHNDLR

The Interrupt Handler routine is the one which will be executed when an IRQ interrupt occurs. If using printer spooling, the routine should first clear the interrupt condtion and then jump to the 'change process' routine of the printer spooler at \$C700. If not using printer spooling. this routine can be setup to do whatever the user desires. If it is desirable to do both printer spooling and have IRQ's from another device (besides the spooler clock), this routine would have to determine which device had caused the interrupt and handle it accordingly. The address of this routine should be placed at \$D3E7.

The CUSTOM DISK DRIVER PACKAGE

This package supplies all the disk functions required by FLEX. There are eight routines in all:

```
READ
         Reads a single sector
WRITE
         Writes a single sector
VERIFY
         Verifys a single sector
RESTORE Restores the head to track O
         Selects the desired drive
DRIVE
CHECK
         Checks a drive for a ready condition
         Same as CHECK but with no delay
OUICK
INIT
         Initializes any necessary values
WARM
         Does any Warm Start initialization
```

These routines and what is required of them are decribed in the Advanced Programmer's Guide in the section titled 'DISK DRIVERS'. There is a jump table which contains the address of all these routines at \$DE00. This table is as follows:

DE00	JMP	READ
DE03	JMP	WRITE
DE06	JMP	VERIF\
DE09	JMP	RESTOR
DE0C	JMP	DRIVE
DE0F	JMP	CHECK
DE12	JMP	QUICK
DE15	JMP	INIT
DE18	JMP	WARM

Immediately following this jump table there is a space for the disk driver routines. In the general case this space would start at \$DE1B and run through \$DFFF. In the SWTPc system with S-BUG installed, that entire space is not available due to the fact that S-BUG uses RAM in the area of \$DFAO to \$DFFF for variables and stack. Thus the driver routine area is limited in this case to \$DE18 through \$DF9F.

The actual source listings for the SWTPc drivers are not included, but a skeletal Custom Disk Driver Package is included at the end of this section which should assist you in writing your own package.

PUTTING THE CUSTOM FLEX TOGETHER

Once you have written and assembled a Custom I/O and Custom Disk Driver packages, you are ready to append them to the core of FLEX (FLEX.COR) to produce a new, bootable version. This is done with the APPEND utility if FLEX, but before we get into that there is a very important point which must be covered.

*** IMPORTANT ***

The copy of FLEX on disk is much like any other standard binary file. IT MUST HAVE A TRANSFER ADDRESS IN ORDER TO WORK! It is also important to note that unlike other binary files FLEX can have ONLY ONE transfer address and it MUST BE THE LAST THING IN THE FILE! The simplest way of getting that transfer address into the file is by use of the END statement in the assembler. We recommend you put a transfer address on the END statement of the Custom I/O Driver Package and make sure it is the last thing in the final FLEX file.

Assuming you have put a transfer address on the Custom I/O Driver Package with an end statement of the form:

END \$CD00

You can now create a new version of FLEX by appending the custom disk drivers and custom I/O drivers onto FLEX.COR. You should use the APPEND command for this purpose as shown:

+++APPEND FLEX.COR DRVRS.BIN CUSTOMIO.BIN NEWFLEX.SYS

This command assumes the object file you created for the Custom Disk Drivers is called DRVRS.BIN and the Custom I/O Drivers are in a file called CUSTOMIO.BIN. The new, custom version of FLEX is called NEWFLEX.SYS. In order to boot up this NEWFLEX.SYS you must link it with the LINK command (see the FLEX User's and Advanced Progammer's Manuals). The command would be of the form:

+++LINK NEWFLEX.SYS

The disk containing your newly made and linked FLEX can now be booted with the normal boot, procedure.

DE18 7E

DE1F

DWARM

JMP

```
* SKELETAL 6809 DISK DRIVER PACKAGE
                   * TECHNICAL SYSTEMS CONSULTANTS, INC.
                  * BOX 2574
                   * WEST LAFAYETTE, INDIANA 47906
                   * THE DRIVER ROUTINES PERFORM THE FOLLOWING
                        READ SINGLE SECTOR - DREAD
                        WRITE SINGLE SECTOR - DWRITE
                        VERIFY WRITE OPERATION - VERIFY
                    3.
                   * 4.
                        RESTORE HEAD TO TRACK 00 - RESTORE
                   * 5.
                        DRIVE SELECTION - DRIVE
                    6.
                        CHECK READY - DCHECK
                  * 7.
                        QUICK CHECK READY - DQUICK
                   * 8.
                        COLD START INITIALIZATION - DINIT
                        WARM START INITIALIZATION - DWARM
                     SYSTEM CONSTANTS
                     THIS SPACE IS WHERE ANY NECESSARY EQUATES MIGHT
                     BE PLACED, SUCH AS DISK CONTROLLER REGISTER
                     LOCATIONS, SECTOR LENGTH, ETC.
                   *****************
DE00
                          ORG
                                  $DE00
                  * JUMP TABLE
DE00 7E
         DE23
                  DREAD
                                  READ
                          JMP
DE03 7E
         DE28
                  DWRITE
                          JMP
                                  WRITE
DE06 7E
         DE2D
                  DVERFY
                          JMP
                                  VERIFY
DE09 7E
         DE31
                  RESTOR
                                  RST
                          JMP
DEOC 7E
         DE35
                  DRIVE
                          JMP
                                  DRV
DEOF 7E
         DE39
                  DCHECK
                          JMP
                                  CHECK
                          JMP
DE12 7E
         DE3F
                  DQUICK
                                  QUICK
DE15 7E
         DE1B
                  DINIT
                                  INIT
                          JMP
```

WARM

WRITES THE SECTOR POINTED

TO BY TRACK IN 'A'

AND SECTOR IN 'B'.

'X' POINTS TO FCB.

DE28 12

DE29 12

DE2A 12

DE2B 12

DE2C 39

WRITE

NOP

NOP

NOP

NOP

RTS

****************** * VARIABLE STORAGE * IF ANY VARIABLES ARE REQUIRED, THEY MIGHT BE PLACED * HERE. THIS MIGHT INCLUDE VARIABLES LIKE CURRENT * DRIVE, CURRENT TRACK FOR EACH DRIVE, OR TEMPORARY * STORAGE LOCATIONS. ************** * INIT * INITIALIZES THE NECESSARY DRIVER VARIABLES. THIS ROUTINE IS CALLED DE1B 12 INIT NOP DE1C 12 NOP DURING FMS INITIALIZATION DE1D 12 AT COLD START NOP **DE1E 39** RTS * WARM * WARM START INITIALIZATION DE1F 12 WARM NOP THIS ROUTINE IS CALLED DE20 12 NOP DURING FMS INITIALIZATION DE21 12 AT WARM START NOP DE22 39 RTS * READ * READ ONE SECTOR DE23 12 READ NOP READS THE SECTOR POINTED DE24 12 NOP TO BY TRACK IN 'A' DE25 12 NOP AND SECTOR IN 'B'. DE26 12 NOP 'X' POINTS TO FCB. DE27 39 RTS * WRITE * WRITE ONE SECTOR

	* VERIFY				
	* VERIF	Y LAST TRACK WRIT	TEN		
DE2D 12 DE2E 12 DE2F 12 DE30 39	VERIFY	NOP NOP NOP RTS	THE SECTOR JUST WRITTEN IS VERIFIED. NO PARAMETERS ARE SUPPLIED.		
	* RST				
	* RST R	ESTORES THE HEAD	ТО 00		
DE31 12 DE32 12 DE33 12 DE34 39	RST	NOP NOP NOP RTS	HEAD RESTORED TO TRACK ZERO ON DRIVE POINTED TO BY FCB AT 'X'.		
	* DRV				
		ELECTS THE DRIVE.			
DE35 12 DE36 12 DE37 12 DE38 39	DRV	NOP NOP NOP RTS	THE DRIVE NUMBER FOUND IN FCB POINTED TO BY 'X' IS SELECTED.		
	* CHECK				
		FOR DRIVE READY			
DE39 12 DE3A 12 DE3B 12 DE3C 12 DE3D 12 DE3E 39	CHECK	NOP NOP NOP NOP NOP RTS	THE DRIVE POINTED TO BY FCB AT 'X' IS CHECKED FOR A READY STATE AFTER DELAYING FOR DRIVES TO COME UP TO SPEED.		
	* QUICK				
		CHECK FOR READY			
DE3F 12 DE40 12 DE41 12 DE42 12 DE43 12 DE44 39	QUICK	NOP NOP NOP NOP NOP RTS	THE DRIVE POINTED TO BY FCB AT 'X' IS CHECKED FOR READY STATE WITHOUT DELAYING FOR DRIVES TO COME UP TO SPEED.		

END

```
* CUSTOM I/O DRIVER PACKAGE
```

* CONTAINS ALL TERMINAL I/O DRIVERS AND INTERRUPT

* SYSTEM EQUATES

C700	CHPR	EQU	\$C700	CHANGE	PROCESS	ROUTINE
------	------	-----	--------	--------	----------------	---------

	*****	*****	*****	*********	k
	*			*	k
	* I/O R	OUTINE	VECTOR	TABLE	k
	* ′			,	k
D3E7		ORG	\$D3E7	TABLE STARTS AT \$D3E7	k
	*		,	· ·	k
DEE7 D3CB	IHNDLR	FDB	IHND	IRQ INTERRUPT HANDLER	k
D3E9 DFC2	SWIVEC	FDB	\$DFC2	SWI3 VECTOR LOCATION	k
D3EB DFC8	IRQVEC	FDB	\$DFC8	IRQ VECTOR LOCATION	k
D3ED D3C4	TMOFF	FDB	T0FF	TIMER OFF ROUTINE	k
D3EF D3BD	TMON	FDB	TON	TIMER ON ROUTINE	k
D3F1 D3A7	TMINT	FDB	TINT	TIMER INITIALIZATION ROUTINE >	k
D3F3 F814	MONITR	FDB	\$F814	MONITOR RETURN ADDRESS	k
D3F5 D370	TINIT	FDB	INIT	TERMINAL INITIALIZATION	k
DEF7 D39C	STAT	FDB	STATUS	S CHECK TERMINAL STATUS	k
DEF9 D38B	OUTCH	FDB	OUTPUT	TERMINAL CHAR OUTPUT	k
D3FB D37D	INCH	FDB	INPUT	TERMINAL CHAR INPUT	k
	*)	k
	*****	****	******	************	k

* ACTUAL ROUTINES START HERE *******

D370	ORG	\$D370

* TERMINAL INITIALIZE ROUTINE

D370 86	13	INIT	LDA	#\$13	RESET ACIA
D372 A7	9F D3E5		STA		[ACIAC]
D376 86	11		LDA	#\$11	CONFIGURE ACIA
D378 A7	9F D3E5		STA		[ACIAC]
D37C 39			RTS		- -

* TERMINAL INPUT CHARACTER ROUTINE

D37D A6 D381 84	9F D3E5 01	INPUT	LDA ANDA	[ACIAC] #\$01	GET STATUS CHARACTER PRESENT?
D383 27	F8		BEQ	INPUT	LOOP IF NOT
D385 A6	9F D3E3		LDÀ	[ACIAD]	GET THE CHARACTER
D389 84	7F		ANDA	#\$7F	STRIP PARITY

* TERMINAL OUTPUT CHARACTER ROUTINE

D38B 34 D38D A6 D391 84 D393 27 D395 35 D397 A7 D39B 39	02 9F D3E5 02 F8 02 9F D3E3	OUTPUT OUTPU2		A [ACIAC] #\$02 OUTPU2 A [ACIAD]	WAIT IF NOT RESTORE CHARACTER
		* TERMI	NAL STA	TUS CHECK	(CHECK FOR CHARACTER HIT)
D39C 34 D39E A6 D3A2 84 D3A4 35 D3A6 39	02 9F D3E5 01 02	STATUS	PSHS LDA ANDA PULS RTS	A [ACIAC] #\$01 A	
		* TIMER	INITIA	LIZE ROUTI	NE
D3A7 BE D3AA 86 D3AC A7 D3AE 86 D3B0 A7 D3B2 86 D3B4 A7 D3B6 A6 D3B8 86 D3BA A7 D3BC 39	D3E1 FF 84 3C 01 8F 84 3D 01	TINT	LDX LDA STA LDA STA LDA STA LDA STA RTS	TMP1A #\$FF 0,X #\$3C 1,X #\$8F 0,X 0,X #\$3D 1,X	GET PIA ADDRESS
		* TIME	R ON RO	UTINE	
D3BD 86 D3BF A7 D3C3 39	04 9F D3E1		LDA STA RTS	#\$04 [TMPIA]	TURN ON TIMER
		* TIME	R OFF R	OUTINE	
D3C4 86 D3C6 A7 D3CA 39	8F 9F D3E1		LDA STA RTS	#\$8F [TMPIA]	TURN OFF TIMER
		* IRQ I	NTERRUP	T HANDLER	ROUTINE
D3CB A6 D3CF 7E	9F D3E1 C700	IHND	STA JMP	[TMPIA] CHPR	RESET INTERRUPTS GO TO SPOOLER

*	ACIA	AND	PIA	ADDRESS	FOR	${\tt SUPPLIED}$	ROUTINES

D3E1		ORG	\$D3E1	
D3E1 E012	TMPIA	FDB	\$E005	TIMER PIA ADDRESS
D3E3 E005	ACIAD	FDB		ACIA DATA REG. ADR.
D3E5 E004	ACIAC	FDB		ACIA CONTROL REG. ADR.

^{*} END STATEMENT HAS FLEX TRANSFER ADDRESS!

END \$CD00