T-AXI Blade V1.8 User Manual

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Contents

1	Intr	roduction	3
	1.1	License Information	3
	1.2	Code Overview and Features	3
	1.3	System Requirements	3
	1.4	Installation	3
2	Pro	gram Interface	4
	2.1	Program Initialization and Setup	4
	2.2	Main Program Window	5
	2.3	Program Output Modes	7
3	Bac	kground	11
	3.1	Nomenclature	11
	3.2	Establishing a Coordinate System and Vector Triangles.	12
	3.3	T-AXI Blade Theory of Operation	14
4	Exa	mple Analysis: EEE 3rd Stage Rotor	15
	4.1	Background	15
	4.2	Problem Setup	16
	4.3	Step By Step Procedure	17
5	Bug	g Reporting and Additional Help	20

1 Introduction

1.1 License Information

T-Axi Blade is released under the GNU General Public License Version 3, 29 June 2007. Please see the included file "gpl_license.txt" for information regarding reproduction and distribution.

1.2 Code Overview and Features

T-Axi Blade is a GUI based, free-vortex blade row design and visualization program. The primary purpose of T-Axi Blade is to develop students' physical understanding of key blade design features, with a special emphasis on the relationship between velocity triangles and blade shapes. The specific features of this code are summarized below.

- Support for axial and centrifugal compressor and turbine designs.
- GUI driven design and analysis.
- Detailed data output including vector triangles and values, cascade views for hub, pitch and tip, Smith Charts, and Loading vs. Aspect Ratio charts.
- Formatted output of common turbomachinery equations, solved for the current blade row design.
- Temperature dependant material database.
- Preliminary design stress analysis based on AN^2 values.

1.3 System Requirements

Operating System	Windows 2000 / XP / Vista
Processor	Pentium 3 or faster recommended
Memory	256 MB or greater
Display	$1024 \ge 768$ with 256 colors

1.4 Installation

T-Axi Blade and the related T-Axi Disk codes are available from the University of Cincinnati GTSL website: http://GTSL.ase.uc.edu/T-AXI. Download the file BD_SUITE.zip and extract the entire package to a known location on your hard drive. The unzip process should create all of the necessary files and folders. Input files are contained in the subdirectory named "INPUTS", the material database is located under "MATERIALS", and documentation is located under "HELP". The user should be careful not to change the file structure of T-Axi Disk as it may render the code inoperable. Double clicking on the TAXI_BLADE_V1_8.exe icon will load the T-Axi Blade GUI.

2 Program Interface

2.1 Program Initialization and Setup

Upon execution of T-Axi Blade the user is presented with a splash screen showing copyright and author information. Clicking on the "OK" button brings the user to the blade file loading menu. The user should select a blade input file (*.tri*) from this prompt and then click "Open" to continue. The default blade file is for a first stage axial compressor section, and will load automatically if "Cancel" is pressed. This should be used if a input file has not been created yet.

The "Choose Interface Options" window appears after the selection of a valid blade input file. This windows reads and presents the information from the *.tri* file chosen in the previous step. Figure 1 shows this window. The user should investigate the options carefully before continuing. Any changes to these conditions should be made at this step. Clicking the "OK" will take the user to the main T-Axi Blade window.

Choose Interface Options Exit Help	
Operators HLE Mdot	Configuration Mdot Enabled RPM Enabled 15.000 RPMs Max
Ulep RPM	Default Input
Input Overspeed Fact. 1.2	
Pressure 101325.	Gas Cons. 287.
Temp. 288.15 Zeta IGV .02	Gamma 1.4
Load File	Refresh
ОК	Quit

Figure 1: T-AXI Blade Interface Options Window.

2.2 Main Program Window

Figure 2 shows the main T-Axi Blade window. This window contains all of the controls needed to design and analyze a blade and blade row. A short explanation of the controls marked with the red numbers is shown below.



Figure 2: T-AXI Blade Main Window.

- 1. **Phi** (ϕ): Allows the user to change Phi (angle between the engine axis and the meridional) at the leading edge (ϕ_{Le}) and at the trailing edge (ϕ_{Te}).
- 2. $\mathbf{V}_{m_{le}}$: Meridional velocity(m/s) at the leading edge. The ratio of velocities between the leading and trailing edges is adjusted with the slider to the right.
- 3. **R** Pitch: Radius from engine centerline to the pitch of the blade, leading or trailing edge respectively.
- 4. Mdot (\dot{m}): Sets the mass-flow rate across the stage in kilograms/second.
- 5. **RPM:** Sets the design speed RPM.

- 6. Eta rotor (η_{rot}) : Specifies rotor efficiency.
- 7. Delta TT (ΔT_T): Specifies change in Total Temperature(Kelvin) across the rotor.
- 8. Alpha_mle Pitch (α_{mle}): Specifies the angle(deg) between the velocity(m/s) of the fluid entering the stage, and its meridional component at the leading edge.
- 9. Delta Z: Specifies the engine-axis length of the blade.
- 10. Blade Thickness: Sets the blade thickness at the hub(meters), with the slider to the right setting the thickness at the tip.
- 11. Blades: Specifies the number of blades in the current row.
- 12. Save Inputs: Saves the input conditions to a .tri file.
- 13. View Selector: Changes the view between different options. Options are:
 - Axial View: Displays an axial view of the blade along with relevant data and vector triangles.
 - **Hub View:** Displays a radial view of the hub cross-section of the blade row and all relevant data and vector triangles.
 - Pitch View: Same as Hub View, with data displayed changing to reflect pitch values.
 - **Tip View:** Same as Hub View, with data displayed changing to reflect tip values.
 - Data Printout: Text printout of input values and simulation output.
 - Smith Chart: Smith Chart showing values for the hub, pitch and tip.
 - Loading vs. AR: Loading vs. Aspect Ratio chart.
 - Equations: Shows a formatted equations sheet, solved for the current design.
- 14. Material Menu: Drop-down menu for blade material selection. The menu consists of the material files of the *.dmat* type, stored in the "\MATERIALS" folder. Default options include several alloys such as INCONEL 706, INCONEL 718, and A286 to name a few.
- 15. Save Disk Output: Saves the blade geometry .dsk and flowpath dimensions for use in T-AXI Disk to a .din file.

2.3 Program Output Modes

Figure 3 shows the axial view output from the T-AXI Blade main window. An overview of the displayed data indicated with red numbers is given below.



Figure 3: T-AXI Blade Axial View.

- 1. Meridional Velocity (\mathbf{V}_m) : This is the magnitude of the meridional velocity vector shown in #6.
- 2. Radial Velocity (V_r) : This is the magnitude of the radial velocity vector shown in #6.
- 3. Axial Velocity (V_z) : This is the magnitude of the axial velocity vector shown in #6.
- 4. Phi (ϕ): This is the angle (deg) between the axial velocity vector, and the meridional velocity vector.
- 5. Graphic: This is the graphical representation of the axial view of the blade.
- 6. Vector Triangle: This vector triangle represents the three flow components whose magnitudes are given: axial velocity, radial velocity, and meridional velocity.

Figure 4 shows the pitch view output option from the T-AXI Blade main window. An overview of the data indicated with red numbers is shown below.



Figure 4: T-AXI Blade Pitch View.

- 1. Values Table: Table showing the magnitudes of the vectors and angles from the vector triangles.
 - \mathbf{V}_m : Magnitude of meridional velocity, shown as vector #2.
 - α_m : Angle(deg) between meridional velocity(#2) and absolute velocity(#3).
 - β_m : Angle(deg) between meridional velocity(#2) and relative velocity of the flow as seen by the blade row(#4).
 - V: Magnitude of the absolute velocity, shown as vector #3.
 - W: Magnitude of the relative velocity of the flow as seen by the blade row, shown as vector #4.
 - \mathbf{V}_{θ} : Magnitude of tangential (swirl) velocity, shown as vector #5.
 - \mathbf{W}_{θ} : Magnitude of relative tangential (swirl) velocity of the flow as seen by the blade row, shown as vector #6.
 - U: Magnitude of velocity of the blade row, shown as vector #7.
 - \mathbf{M}_{rel} : Mach number of the flow seen by the blade row, shown as vector #4.
- 2. Meridonal Velocity: Velocity along the m' cutplane.

- 3. True Velocity: Velocity of the flow as seen by an outside observer.
- 4. **Relative Velocity:** Flow velocity as seen by the blade row.
- 5. **Tangential Velocity:** Velocity component of the true velocity in the tangential direction (swirl).
- 6. **Relative Tangential Velocity:** Velocity component of the relative velocity seen by the blade row in the tangential direction.
- 7. Blade Row Velocity: Tangential velocity of the blade row at the radius specified (hub, pitch, or tip).
- 8. Axial View Data: Data from the axial view including meridional, radial, and axial velocity vectors.
- 9. Graphic: Cross-section of the blade row at the radius specified (hub, pitch, or tip).

Several other options are available for displaying the data output from T-AXI Blade. Figure 5 shows the Data Printout option available from the pull-down menu. There is also a Smith chart and a Loading vs. Aspect Ratio chart available. A recent addition to T-Axi Blade is a formatted printout of common turbomachinery equations, solved for the current blade design. This page provides students with an easy way to find and fix mistakes in any hand calculations they are performing in addition to the T-Axi Blade analysis.

			ΤRΙ	Des Re	esults		c	ompress
PTin (Pa)	= 101325.	0 TTin (K)= 288	.15 Rgas	(J/kg*K)=	287.00	γ= 1.400	00
PT_te (Pa)= 170476.	3 TT_te (1	K)= 340	.85 PR =	1.7168	TR = 1	.1829	
A_le (m ²))= 0.282	A_te (m	²)= 0.21	6 Mdot ((kg/s)= 54.	40 Area	$H(cm^{2})=$	2.99
h_le =	0.1699	h_te =	0.12	61 AR =	0.3	6 Area	$T(cm^2)=$	2.20
ф =	0.5112	$\Psi^{=}$	0,44	126				
σ _H =	0.936	$\sigma_P =$	0.58	ο σ ₇ =	0.4	63		
$AN^2 (m^{2*}$	rpm ²)=	202596000	Mat. Al	N ² = 52968	700			
Material =	A 286.dr	nat						
¢ leading=	0.0000	φ trailing=	0.0000	Power (kW	7)= 2879.7	81 Pow	er (hp)=	3858.91
¢ leading= RPM = 1	0.0000	φ trailing= OS RPM =	0.0000	Power (kW $\forall \theta$ tep=	7)= 2879.7 183.90	81 Pow	er (hp)= Vel Rat	3858.91 0.6518
¢ leading= RPM = 1	0.0000 2300.0 Z(m)	φ trailing= OS RPM = Radius (m)	0.0000 14760.0 U (m/s)	Power(kW Vθtep= alpha(deg)	7)= 2879.7 183.90 • beta (deg)	81 Power Rel V Mach	er (hp)= Vel Rat M_rel	3858.91 0.6518
¢ leading= RPM = 1 Le Tip	2 0.0000 12300.0 Z (m) 0.00	φ trailing= OS RPM = Radius (m) 0.35	0.0000 14760.0 U (m/s) 449.47	Power (kW V θ tep= alpha (deg) 7.83	7)= 2879.7 183.90 beta (deg) -65.85	Rel V Rel V Mach 0.60	er (hp)= Vel Rat M_rel 1.41	3858.91 0.6518
¢r leading= RPM = 1 Le Tip Le Pitch	2300.0 2300.0 Z (m) 0.00 0.00	φ trailing= OS RPM = Radius (m) 0.35 0.26	0.0000 14760.0 U (m/s) 449.47 340.05	Power (kW V θ tep= alpha (deg) 7.83 10.30	/)= 2879.7: 183.90 beta (deg) -65.85 -58.15	81 Pow Rel V Mach 0.60 0.59	er (hp)= 7el Rat M_rel 1.41 1.09	3858.91 0.6518
¢ leading= RPM = 1 Le Tip Le Pitch Le Hub	2300.0 Z (m) 0.00 0.00 0.00	φ trailing= OS RPM = Radius (m) 0.35 0.26 0.18	0.0000 14760.0 U (m/s) 449.47 340.05 230.62	Power (kW V Ø tep= alpha (deg) 7.83 10.30 15.00	7)= 2879.7 183.90 beta (deg) -65.85 -58.15 -43.44	81 Pow Rel V Mach 0.60 0.59 0.60	er (hp)= 7el Rat M_rel 1.41 1.09 0.80	3858.91 0.6518
¢ leading= RPM = 1 Le Tip Le Pitch Le Hub Te Tip	2300.0 2300.0 Z (m) 0.00 0.00 0.00 0.00 0.00	φ trailing= OS RPM = Radius (m) 0.35 0.26 0.18 0.34	0.0000 14760.0 U (m/s) 449.47 340.05 230.62 432.85	Power (kW V θ tep= alpha (deg) 7.83 10.30 15.00 42.37	7)= 2879.7 183.90 beta (deg) -65.85 -58.15 -43.44 -59.98	81 Pow Rel V Mach 0.60 0.59 0.60 0.62	er (hp)= 7el Rat M_rel 1.41 1.09 0.80 0.92	3858.91 0.6518
¢ leading= RPM = 1 Le Tip Le Pitch Le Hub Te Tip Te Pitch	2300.0 2300.0 2 (m) 0.00 0.00 0.00 0.00 0.05 0.05	φ trailing= OS RPM = Radius (m) 0.35 0.26 0.18 0.34 0.34 0.27	0.0000 14760.0 U (m/s) 449.47 340.05 230.62 432.85 351.64	Power (kW V θ tep= alpha (deg) 7.83 10.30 15.00 42.37 48.31	7)= 2879.7: 183.90 beta (deg) -65.85 -58.15 -43.44 -59.98 -45.68	Rel V Rel V Mach 0.60 0.59 0.60 0.62 0.68	er (hp)= 7el Rat M_rel 1.41 1.09 0.80 0.92 0.65	3858.91

Figure 5: T-AXI Blade Data Printout View.



Figure 6: T-AXI Blade Equation Printout.



Figure 7: T-AXI Blade Equation Printout.

3 Background

3.1 Nomenclature

T-AXI was created using the nomenclature shown below. There are however, many nomenclature systems in use throughout academia and the industry, with none being especially better than the other. The key is to establish a system and then be consistent. The chosen nomenclature system and one alternative is shown in table 1.

Property	T-Axi Blade	Alternatives
Engine Axis	Z	x
Absolute velocity	V	C
Relative velocity	W	V
Tangential velocity	V_{θ}	C_u
Angular momentum	$rV_{ heta}$	$\frac{UC_u}{\omega}$

Table 1:	TURBOMAC	CHINERY NO	MENCLATUR	E.

NOMENCLATURE	
a	Speed of sound
r	Radius or radial station
A Area	
М	Mach number
N	Rotational Speed (RPM)
Р	Pressure
R	Gas constant
Т	Temperature
U	Rotor wheel speed
V	Absolute flow velocity
W	Rotor relative velocity
GREEK	
α	Absolute flow angle
β	Relative flow angle
γ	Ratio of specific heats
ρ	Density
σ	Stress
ω	Rotor angular velocity
SUBSCRIPTS	
a	Annulus
h	Hub
le	Leading edge
р	Pitch
t	Tip
te	Trailing edge
Z	Axial
Т	Total
θ	Tangential direction

Table 2: General Nomenclature.

3.2 Establishing a Coordinate System and Vector Triangles.

Due to the lack of a standard coordinate system in the realm of turbomachinery, one must clearly define the system before hoping to communicate clearly. The system used by T-AXI Blade is that used by GE Aviation, as it was the most familiar system to the authors. Figure 8 shows the coordinate system.



Figure 8: T-AXIS Blade Coordinate System.

T-AXI Blade is able to handle calculations for both axial and centrifugal configurations. This is attained by following the meridional streamsurfaces shown in figure 9. The blade cross-sections for hub, pitch, and tip are created by cutting along the m' coordinate.



Figure 9: Axial and Centrifugal Streamsurfaces.

The vector triangle notation used in T-AXI Blade is shown in figure 10. The triangle on the right shows the axisymmetric properties of the flow. V_m is the meridional flow, V_z is the axial component of the flow, and V_r is the the radial component of the flow. The triangle on the left

represents the flow as viewed in the cross-sectional plane. The reader may reference table 3 for the meaning of each term.



Figure 10: Vector Triangle Notation.

Table 3: Vector Triangle Nomenclature.					
Term	Definition				
\vec{V}	Absolute velocity of the flow.				
\vec{W}	Relative velocity of the flow as seen by the blade row.				
V_z	Axial component of flow.				
V_r	Radial component of flow.				
\vec{U}	Tangential velocity of blade row at a given radius (hub, pitch, tip).				
α_m	Angle between the meridional and absolute flow vectors.				
β_m	Angle between the meridional and relative flow vectors.				
ϕ	Angle between the axial and meridional flow vectors.				

The governing equations which are used to produce the vector triangle magnitudes are shown as equations 1 - 12. These are standard turbomachinery equations stemming from the geometry of the system, and the coordinate system chosen.

$$\vec{V} = \vec{W} + \vec{U} \tag{1}$$

$$\vec{V} = V_z \hat{k} + V_r \hat{i_r} + V_\theta \hat{i_\theta} \tag{2}$$

$$\vec{W} = W_z \hat{k} + W_r \hat{i_r} + W_\theta \hat{i_\theta} \tag{3}$$

$$W_z = V_z; \ W_r = V_r \tag{4}$$

$$\vec{U} = \vec{\omega} \times \vec{r} = \omega r \hat{i_{\theta}} \tag{5}$$

$$W_{\theta} = V_{\theta} - U = V_{\theta} - \omega r \tag{6}$$

$$\tan\phi = \frac{V_r}{V_z} \tag{7}$$

$$V_m^2 = V_z^2 + V_r^2$$
 (8)

$$\tan \alpha_z = \frac{V_\theta}{V_z} \tag{9}$$

$$\tan \beta_z = \frac{W_\theta}{V_z} \tag{10}$$

$$\tan \alpha_m = \frac{V_\theta}{V_m} \tag{11}$$

$$\tan \beta_m = \frac{W_\theta}{V_m} \tag{12}$$

3.3 T-AXI Blade Theory of Operation

T-AXI Blade solves for blade geometry using straightforward turbomachinery calculations with the free vortex assumption. Several good sources on for students to reference are the introductory texts by Saravanamutto [1] and Mattingly [2]. The free vortex assumption requires a uniform angular momentum distribution, which leads to a clearly defined tangential velocity profile, where r is the radius, and V_{θ} is the tangential velocity.

$$rV_{\theta} = constant \tag{13}$$

ΔT_T	Rotor total temperature change.		
P_{T_o}	Inlet total pressure.		
T_{T_o}	Inlet total temperature.		
$\zeta_{IGV}, \eta_{rotor}$	IGV loss coefficient and rotor efficiency		
r_{le} , ΔZ_{le} , r_{te_p}	Blade geometry values.		
$U_{le}, V_{r_{le}}, V_{Z_{te}}$	Known flow velocities.		
$\alpha_{m_{le}}$	Meridional flow angle at leading edge.		
R , γ	Fluid properties.		
N	Rotational speed (RPM).		

Table 4: T-AXI BLADE INPUTS.

Using the inputs shown in table 4 and assuming an ideal gas, the following general equations hold.

$$a = \sqrt{(\gamma RT)} \tag{14}$$

$$V = Ma \tag{15}$$

$$T = \frac{T_t}{1 + (\frac{\gamma - 1}{2})M^2} \tag{16}$$

$$P = \frac{P_t}{(1 + (\frac{\gamma - 1}{2})M^2)^{\frac{\gamma}{\gamma - 1}}}$$
(17)

$$\rho = \frac{P}{RT} \tag{18}$$

$$C_p = \left(\frac{\gamma}{\gamma - 1}\right)R\tag{19}$$

Mass flow continuity is maintained across the rotor, as shown in equations 20 and 21.

$$\dot{m} = \rho V_m A \tag{20}$$

$$A_{le} = 2\pi r_{le_p} h_{le} \tag{21}$$

Rotor performance is calculated using the rotor efficiency (η_{rotor}) and rotor work is determined from the Euler turbomachinery equations 22 - 24 where ΔH is the change in Entropy across the rotor.

$$\Delta H = \omega([rV_{\theta}]_{te} - [rV_{\theta}]_{le}) \tag{22}$$

$$\Delta H = C_p \Delta T_T \tag{23}$$

$$\dot{W} = \dot{m}\Delta H \tag{24}$$

After solving for all the flow quantities, T-AXI Blade generates a simple blade shape for use in the visualizations and 3D output. This shape is dependent on the relative flow angles for the leading edge and trailing edge, as well as the specified maximum thickness. As can be seen from the vector triangles in figure 4, the camber line at the leading edge is parallel to the relative velocity vector "W", and the camber line at the trailing edge is parallel to the exiting relative velocity "W". This is critical to reduce losses and maximize efficiency. Once T-AXI has found the blade shape, it performs a basic structural analysis in the form of AN^2 . Comparison to theoretical maximum material dependent AN^2 values then determines if the design is feasible. The calculations (eqs. 25 & 26 assume units of $\frac{rad}{s}$ for omega and $m^2 \times RPM^2$ for AN^2 .

$$AN^2 = A_a \omega^2 \left(\frac{30}{\pi}\right)^2 \tag{25}$$

$$AN^2 = \frac{3600}{\pi (1 + \frac{A_t}{A_b})} \frac{\sigma_{sty}}{\rho_{af}}$$
(26)

4 Example Analysis: EEE 3rd Stage Rotor

4.1 Background

The GE Energy Efficient Engine (EEE) high pressure compressor (HPC), shown in Figure 11 below, was designed in the late 1970s. Eventually many features of this design were used in the GE90 turbofan. Many of the documents and designs from this project are publicly available, making the EEE a perfect test case for verifying results from a new program. The third stage rotor and supporting disk have been chosen to demonstrate the capabilities of T-Axi Blade and T-Axi Disk.

4.2 Problem Setup

T-Axi Blade was run first. Table 5 shows the inputs that were used to build the T-Axi Blade input file (*.tri*). The majority of these values were taken or derived from the available EEE documents [3, 4].



Figure 11: EEE 10 STAGE COMPRESSOR CROSS SECTION.

Inlet T_0	394.44 K
Inlet P_0	267563.80 Pa
γ	1.38
ΔT_0	51.12 K
η Rotor	0.91
r_{le} Pitch	0.2898 m
r_{te} Pitch	0.2909 m
ω	12,300 rpm
ϕ_{le}	4.22 Degrees
ϕ_{te}	3.84 Degrees
\dot{m}	54.40 kg/s
α_{mle}	15.80 Degrees
V_m Ratio	0.91
Δ z Tip	0.027 m
Number of Blades	50
Blade Thickness at Hub (% chord)	10.85
Blade Thickness at Tip (% chord)	2.61

Table 5: EEE 3RD STAGE ROTOR INPUTS.

4.3 Step By Step Procedure

- 1. Start T-Axi Blade by running the executable named TAXI_BLADE_V1_8.exe.
- 2. Click "OK" at the splash screen. A file selection prompt should appear.
- 3. Navigate to the "INPUTS" folder and select **EEE_3RD_STAGE.tri**. This file contains all of the relevant input information shown in table 5. The "Choose Interface Options" screen should appear.
- 4. Check over the input values before proceeding. The configuration type should be set to "Large HPC/HPT". Press "Refresh" if the configuration is incorrect. Click "OK" to proceed to the main program interface.
- 5. The main program interface displaying the "Data Printout" tabular output. The input sliders on the left have all be set using the information in the input file. Verify that these are correct. Feel free to modify any of sliders to instantly see the effect on the blade shape and vector triangles. Press "Back" to return to the previous to the previous screen and then reload the correct EEE 3rd Stage inputs.
- 6. Use the Display pull-down selector to cycle through the different outputs.
- 7. View the velocity triangles at the Hub, Pitch and Tip by selecting the appropriate display option. The information shown graphically on these pages is also shown in a tabular form in the "Data Printout" window.
- 8. Select the "Equations" display option to view the equations used to solve for the blade row performance and velocity triangle quantities.
- 9. Press the "Save Disk Output" button to create a file for use in T-Axi Disk.
- 10. Press the "Quit" button to close T-Axi Blade.

The flow relative Mach number (M_{rel}) and the relative flow angle (β) were compared to reference data at the hub, pitch, and tip. Reference data is available at many more locations along the blade. Figure 12 shows this comparison at the blade leading edge and Figure 13 shows this comparison at the trailing edge. The data correlates very well at the mid-span location, but there is a significant amount of deviation at the hub and casing locations. This discrepancy is due to the simplifications included in T-Axi Blade. The reference data was calculated using a proprietary axisymmetric code with empirical loss models. T-Axi Blade uses a free vortex assumption with constant spanwise efficiency. Overall the two results correlate well, but they clearly show the limitations of a low fidelity analysis tool.



Figure 12: BLADE RESULTS COMPARISON - LEADING EDGE.



Figure 13: BLADE RESULTS COMPARISON - TRAILING EDGE.

5 Bug Reporting and Additional Help

Effort has been taken to develop T-Axi Disk into a stable, user-friendly program. However, this software is new and most likely a number of bugs still exist. Please contact the author with any bug reports using the information below. Any questions or comments regarding the current state of T-Axi Disk or ideas for its expansion are also welcome.

Michael Downing University of Cincinnati Department of Aerospace Engineering Email: m_downing@fuse.net Office: 436 ERC

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