

UltraLab[®]

ULS Advanced



User Manual

User notes:

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1 GENERAL

1.1 Safety instructions

For your own safety and for the safe operation of the system, please read the following instructions carefully PRIOR to operating the system for the first time.

The *UltraLab*[®] *ULS Advanced* laboratory instrument, as well as the associated ultrasound sensors, represent state-of-the-art technology and comply with the latest safety regulations.

The manufacturer has made every effort to guarantee safe operation. The user must ensure that the instrument is set up and installed in such a way that its safe usage is not impaired.

The instruments are factory tested and were delivered in a safe operational condition.

This User Manual contains information and warnings, which must be observed by the user under all circumstances to ensure safe operation of the instruments.

• The instrument may only be put into operation by authorised persons and only operated by trained personnel. All users working with this instrument must read the User Manual prior to any operation.

• The user may only perform the repair and maintenance work described. Only the specified parts are to be used.

Servicing work may only be carried out by authorised service technicians from GENERAL ACOUSTICS.

• All instruments and additional devices used for this purpose must be properly earthed.

• The earth leads must not be interrupted at any point.

• The *UltraLab*[®] *ULS Advanced* laboratory instrument may only be operated within the specified temperature range of -20 to +70°C. Otherwise measurement inaccuracies and instrument faults or defects may occur.

The temperature stability of connection cables must match the operating temperature of the measurement system.

- The sensor should only be connected to the instrument when it is switched off.
- The sensors are to be treated with care and are only to be screwed in hand-tight; otherwise there is the risk of damage. Sufficient leverage is obtained from the sensor casing itself.
- Avoid electrostatic discharges.
- The UltraLab[®] ULS Advanced instrument must not come into contact with liquids.
- Never operate the instrument at sites where water may get into the instrument.

• Also take care that the instrument is always operated above the water line of experimental reservoirs. Protect the instrument against falling into water.

• Isolate all system devices from the mains before undertaking cleaning. Ensure there is no current. Do not use aggressive cleaning chemicals, liquid cleaners or sprays; only use a damp cloth. Never bring this or any other cloth into contact with parts of the system that will subsequently conduct electricity.

• Never attempt to open instruments with objects or to insert objects into an instrument. The voltages existing in the instruments can lead to short-circuits and electric shocks.

• Ensure adequate ventilation when operating the *UltraLab[®] ULS Advanced*. As the instrument has low power consumption, it requires no additional ventilation under normal conditions. However, the instrument should never be placed on a source of heat (computer monitors, radiators ...).

Only operate the *UltraLab[®] ULS Advanced* at the intended mains voltage of 230 VAC (optionally 110 VAC).

• For safety reasons, the *UltraLab*[®] *ULS Advanced* is provided with a sealed appliance plug with earth contact for its mains power. In this context, only appliance cables and plugs with earth contacts may be used. Operation of the system is prohibited if you do not have this option. Never use an extension cable without an earth contact.

• The instrument is protected from mains voltage by a blowout fuse in the appliance plug. A fine-wire fast-blow fuse (G fuse 5 x 20 mm) compliant with IEC with a nominal value of 0.8(f) A is to be used as a replacement. Only the specified values may be used. Higher tripping values or bridging of fuses is not permissible. If the fuse repeatedly blows, the Service Department of *GENERAL ACOUSTICS* should be informed, as the cause would need to be resolved.

• We recommend protecting the circuit with FI protective switches to ensure safe operation of your complete system.

• Take care that power cables are not worn, abraded or otherwise defective. When routing connecting cables, make certain that the cables do not represent an obstacle or risk of tripping.

• When using extension cables, the total nominal current of all the devices connected must not exceed the allowable maximum current of the cable. The current ratings of all devices connected to a single plug should never exceed 15 A, unless the plug is specifically designed for this purpose. If you are unsure what type of mains power exists in your premises, ask your Safety Officer or an authorised electrician.

It is imperative to isolate instruments from the mains in the following cases:

- If power cables or plugs are worn or damaged.
- If water or any other liquid has found its way into one of the instruments.
- If the instrument is not working correctly despite following the specified operating instructions.
- If one of the instruments has fallen down or the chassis is damaged.
- If the instrument shows any noticeable departure from normal operation.
- If the sensor connections have become wet.

With the exception of the actions explicitly specified in the manual, you should never attempt your own repairs on devices belonging to the *UltraLab*[®] *ULS Advanced* system. Besides the resulting revocation of warranty coverage, you also risk an electric shock or other injury from the components. All maintenance work, unless explicitly described in the manual, should only be carried out by *GENERAL ACOUSTICS*.

2 INTRODUCTION

2.1 Overview

Ultrasound measurement of distances in laboratory measurement technology has become increasingly established in recent years. The advantages gained are quite clear: particularly in small-scale experimental set-ups, it is imperative to avoid any mechanical intervention that may affect the experiment, but at the same time, parameters must be measured and evaluated. This not only applies to laboratory operation and water. As the distance to an object is measured by sound propagation time measurement, and not by intensity measurement, as is the case in optical methods, ultrasound sensors have excellent background suppression. Almost all materials that reflect sound are reliably detected, irrespective of their colour. Even transparent materials and thin foils present no problems for our ultrasound sensors. As a result of their high sensitivity, our sensors are also predestined for the detection of liquid surfaces. The sensors measure in dusty air as well as through fine fog. Even thin deposition on the sensor membrane does not impair the sensor function. These characteristics, combined with extremely slender sound cones (with practically no side lobes), make for completely new laboratory applications.

The easy-to-use *UltraLab[®] ULS Advanced* laboratory instrument excels as a consequence of the diverse functions implemented, making it suitable for use in complex measurement tasks without having to set a series of parameters. The measurement object can be, for example, the water surface as a level or the moving water surface as a wave. This is where the temporally highly resolved distance measurement comes into its own. A complex measurement algorithm ensures high measurement accuracy and resolution, as well as a high degree of data confidence.

The *UltraLab*[®] *ULS Advanced* is dedicated for sound propagation time measurement of very fast moving waves. This device has four independent channels, each one is equipped with up to three sensors of the type USS12-HF. The first (1.1, 2.1, 3.1 and 4.1) of these three sensors - belonging to one measurement unit – are emitting the acoustic ping down to the water surface, whereas the reflected incoming signal can be detected by all of the three independently.

Due to high repetition rate of 100 Hz, every measurement unit detects high dynamic processes in an impressive resolution of 0.36 mm. Thanks to the application of a special reference sensor all fluctuations of the sound velocity will be compensated internally. That means, the data obtained from the measurement device are independent of all the sound velocity interfering parameters, e.g. temperature, air humidity, air pressure, etc.. Nevertheless the last column of the data telegram contains the sound velocity in m/s.

After the switch on of the UltraLab device and a short system test procedure (needs some seconds), the device delivers continuous data.

An opto-isolated trigger input makes a synchronisation with external data acquisition possible.

The *UltraLab[®] ULS Advanced* is equipped wit an Ethernet interface. So it is possible to receive the output data stream at any PC in the local network.

Please, for configuration of the LAN and the software driver on the PC see the respective chapters (chapter 4).

2.2 System components

The *UltraLab[®] ULS Advanced* instrument system consists of the following components:

- 1 UltraLab[®] ULS Advanced controller
- 12 ultrasound sensors of the type USS 12/HF (4x3)
- 1 ultrasound sensor of the type REF-300 for precise sound velocity measurement mounted in a calibrated distance unit
- 12 shielded cables between the sensors and the instrument (4-pin LEMO plug / M12 industry standard)
- 1 cable between the REF sensor and the instrument (3-pin LEMO plug / M12 industry standard)
- 1 Ethernet cable
- 4 mounting plates for USS 12/HF

2.3 Sensor characteristics

Sensor identifier	Measurement frequency	Measurement range	Technical resolution	Accuracy
	[kHz]	[mm]	[mm]	[mm]
USS12/HF	200	200 – 1.200	0.36	+/- 1

The *UltraLab*[®] *ULS Advanced* sensors of the type USS12-HF are based on an ultrasound pulse echo technique. They have been developed for temporally and spatially high-resolution measurement of distances in air. The sensors permit a distance measurement from 200 mm up to 1200 mm. The advantages of the ultrasound sensors made by *GENERAL ACOUSTICS* in comparison to common ultrasound sensors can be described as follows:

- The acoustic beam pattern could be narrowed to a beam cone below 3° and is valid not only for the sending but also for the receiving process. This is important to reduce the area size of the acoustic footprint onto the water surface in order to get only some small sections instead of a full wave or many waves.
- The minor side lobe could quasi be eliminated. This means that there are no disturbances from objects outside the area of interest (e.g. basin walls, etc.).
- The sending power on one hand and the receiving sensibility on the other could be increased.
 This helps much to reduce the number of lost pings immensely, which may occur on very steep flanks of waves.
- The sampling rate is accelerated to 100 Hz. This great achievement allows to measure fast waves in highest accuracy even though a measurement carriage is moving against the wave direction.

3 MEASUREMENT SETUP

The *UltraLab*[®] *ULS Advanced* is equipped with four independent channels. Every channel or measurement unit consists of three sensors. Whereas the first sensor (x.1) is sending the acoustic beam, all three sensors together are active for receiving of the reflected signal. The aim of this combination is to increase the measurement velocity and to detect dynamic processes on the water surface in high resolution.

All three sensors belonging to the same measurement unit are mounted on a matrix plate. For low relative wave speed the triangle arrangement of all three sensors with the sending sensor in front to the incoming waves is recommended, whereas for relative high wave speed to the carriage all sensors should be arranged in a line – oriented 90° towards the incoming wave front- with the sending sensor first. As a matter of relative speed, the reflected beam comes up but the sound emitting sensor has relatively moved further. Therefore, the other sensors (x.2 and x.3) are placed to receive the incoming signal.

As depicted in Figure 1, all twelve sensor cables are connected to the *UltraLab*[®] *ULS Advanced* controller by a 4-pole LEMO socket at the front of the control panel. The reference sensor cable (REF-300) is connected by a 3-pole LEMO socket on the right hand side of the control panel. Right next to it a BNC socket is located (TRIG IN). Here the cable has to be connected coming from the remote PC. It is an opto-isolated TTL type input, which triggers the time stamp to start counting every single data sample (see Data telegram chapter).

At the rear panel the internal power socket including a fuse (0.8 (f) A) is installed. Here, 230 volt has to be connected with. Furher, a Ethernet cable has to be plugged into the LAN socket. The measured data of all four channels will be exported via this LAN. The switch next by is needed for configuration of the data transfer to the remote PC. With its help one can switch between data transfer and LAN configuration. During the data transfer it is not possible to configurate the system. Therefore the data transfer must be switched off before. After the system is configured it is necessary to switch it back to data transfer for normal operation.

Please note:

After switch on of the power supply it needs 20 seconds to send the data via LAN. After 10 seconds of internal tests the system starts the count down from 10. Right after the data telegram is starting.

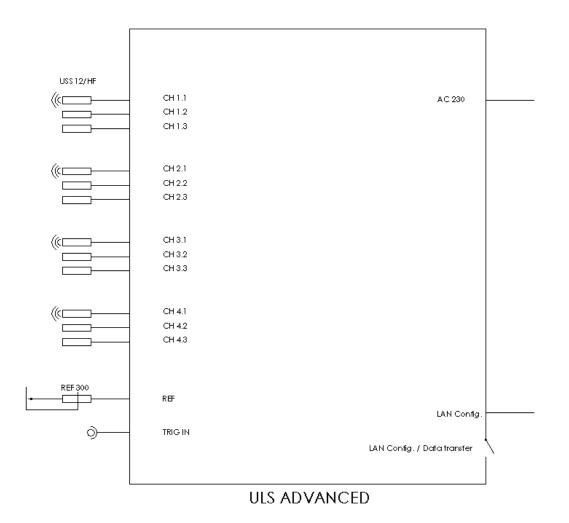


Figure 1: Connection scheme for the UltraLab[®] ULS Advanced

3.1 Compensation using a reference measurement

The most accurate type of compensation is that of a reference measurement. This is necessary for extremely variable conditions or for the purpose of highest accuracy. In the case of density variation or stratification of air masses, through which the ultrasound pulse must penetrate, it is necessary to measure the real speed of sound. The *UltraLab® ULS Advanced* is equipped with a reference sensor REF-300 which has an extremely high accuracy. The reference sensor emits sound along a path of maximum possible length, parallel to the measurement channel, through the same medium/media as the measurement path itself, onto a fixed target at a defined distance. The same influences on the speed of sound are necessarily measured as those on the measuring path itself. Due to data recording of the ultrasound velocity and the internal calibration of the data received from all four channels, the influence of temperature, air pressure, as well as air humidity variations can be excluded. This method can consequently be used for highly accurate compensation of all parameters affecting the sound velocity. The highly precise reference sensor including the reference track (see Figure 2) should be mounted horizontal, upside down nearby the *UltraLab® ULS Advanced* sensors. It should be pointed out

that the reference sensor has to be protected from splashing water and no object has to be between sensor and target, in order to avoid wrong data.

Warning: The reference distance is highly calibrated. The slightest deviation may cause inaccuracy of the measurements.

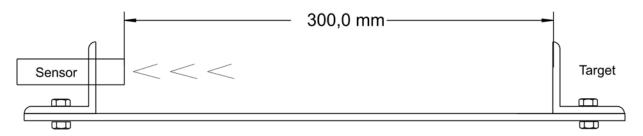


Figure 2: Reference sensor REF-300 mounted on calibrated distance unit

3.2 Data telegram and trigger

With a help of a RS 232/ethernet converter the *UltraLab*[®] *ULS Advanced* transmits ASCII telegrams to a remote PC via Local Area Network (LAN). There, a program like Hyperterminal can be used to view and log the data externally. The telegrams contain six numbers separated by <tab> characters and ending with <CR> <LF>:

- 1 The time stamp
- 2 Measuring channel 1 [in xxxx.xx mm]
- 3 Measuring channel 2 [in xxxx.xx mm]
- 4 Measuring channel 3 [in xxxx.xx mm]
- 5 Measuring channel 4 [in xxxx.xx mm]
- 6 Reference channel with the actual value of the sound velocity [in xxx.xx m/s] (see Figure 3).

A TTL type I/O port triggers the time stamp to start counting the telegrams beginning from 0000000, 0000001, 0000002, ..., up to 9999999 (see first column of Figure 3). Before the time stamp is triggered or after the measurement has stopped the value of the time stamp is –1.

At that moment, the measuring system software program on the PC starts to measure, the rising edge of the time-stamp-reset-signal at the I/O-port – being on high level - switches the count. This situation continues until the measurement is stopped. Then the decreasing edge of the time-stamp-reset-signal provokes a negative value –1 for the telegram column 1.

Nevertheless of the time stamp status the applied sensors are continuously sending measuring data for data preview purposes to the external PC.

The TTL level – trigger input is connected by a BNC socket at the front of the control panel. It is electrically isolated from internal electronics by an opto-coupler.

// Ver. 1.0		ALAB JSTICS 20	005		
// Ver. 1.0	CH1 0362.79 0362.46 0362.79 0362.79 0362.79 0362.79 0362.66		CH3 0204.59 0204.59 0204.76 0204.76 0204.76 0204.76 0204.76 0204.76 0204.76 0204.76 0204.76 0204.76 0204.76 0204.76 0204.59 0204.59 0204.59 0204.59 0204.59 0204.59 0204.59 0204.59 0204.59 0204.59 0204.59 0204.76 0204.76 0204.76	CH4 0622.09 0621.92 0622.26 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.09 0622.26 0622.26 0622.26	C-REF 338.74
0000021 -1 -1 -1	0362.79 0362.79 0363.29 0362.79	0352.96 0352.96 0352.96 0352.96	0204.59 0204.76 0204.76 0204.59	0621.92 0621.92 0621.58 0622.26	338.74 338.74 338.74 338.74
-1	0362.79	0352.96	0204.59	0622.26	338.74

Figure 3: Example of data telegram

Please note:

After switch on of the power supply it needs 20 seconds to send the data via LAN. After 10 seconds of internal tests the system starts the count down from 10. Right after the data telegram is starting.

LAN configuration

3.3 General

For data transmission an internal RS232-to-Ethernet converter that sends the data over the Ethernet is used. The software *Network Enabler Administration* must be installed on the computer/s receiving the data. This software generates a virtual serial port. The data can be logged and evaluated on it. Up to four different PC's on the local network can receive the *UltraLab[®] ULS Advanced* data stream at the same time.

3.4 Moxa interface-converter

For data transmission an interface-converter of the company *Moxa* is used. This packs the output data of *UltraLab[®] ULS Advanced's* internal RS232 interface in IP-packages and sends it over TCP/IP to the desired PC.

Each module must be adapted:

the four most important settings are

- Basic
- Network
- Serial
- Operation Mode

For defining the parameters the software *Network Enabler Administration* is required. This software generates a virtual interface for the real COM mode, needed for *UltraLab[®] ULS Advanced* operation.

3.5 Software installation

Open this folder on the enclosed CD. CD:\Moxa\NEA\ Serial to ethernet standard Version (CD = drive letter) and then start the program setup.exe. Follow the instructions in the installation.

3.6 Configuring the interface

Important:

The module is set and tested by *GENERAL ACOUSTICS* to the parameters desired by the customer. Each change can lead to communication problems between the *UltraLab*[®] *ULS Advanced* and the logging computer and is under your own responsibility.

3.6.1 Preparation

- 1. Turn on the UltraLab[®] ULS Advanced.
- 2. Turn off the data switch on the back side. The data transmission is stopped. This is important because the module cannot be configured during the transmission of data. The module will

not accept the data or only part of them, that can on the other hand lead to the module taking on its default parameters again.

- 3. Connect the twisted paired cable to the LAN-jack.
- 4. Start the program Network Enabler Administration.

3.6.2 Changing the settings

If it happens, that the *Moxa* module has its default values, it is necessary to change the PC IP ADDRESS that contains the following parameters:

- a free IP like 192.168.127.xxx; where xxx can take one value between 2 and 253. The IP 192.168.127.254 is the Default value of the Moxa and therefore already assigned
- the Subnet mask must be 255.255.255.0
 - see also the *Moxa* documentation on the CD

This is only necessary if the *Moxa*-module possesses its default values, otherwise is it already adapted to your network and can be configured.

Warning: Don't try to change settings during data transmission! It may result in loading the default parameters and a new setting of the module is necessary.

3.6.3 Search of a *Moxa* module

1. Broadcast.

By clicking on the first symbol under File a Broadcast will be performed. This operation finds all *Moxa* modules on the network, after that one or several of them can be selected.

2. Direct input of an IP. The module with the entered IP is listed.

X		Network Ena	bler Administrator-Config	juration		0 0 0
<u>File</u> Configuration View <u>H</u>	lelp					
222 2 2 0 A I						
Function		Co	onfiguration - 0 N	etwork Enabl	er Module(s)	
Network Enabler Admit Configuration COM Mapping	No /	Model	MAC Address	IP Address	Status	
Message Log - 0 No Time		Description				
	No	w: 09.03.2005 15	:28:45			

22		Fertivers Environ Automatication-Configuration	0.00	23	Interview Freilies Alternativalia Contignation	0.0.0				
Elle Config	uration View Help			Ele Configuration View	Belo					
221	1 1 0 A			492 294						
	ction	Configuration - 0 Network Enabler		Function	Configuration - 1 Network Enabler Modu	de(s)				
= Netwo	Control Construction Control Construction Control Construction Control Construction Searching tor Network Enables Searching tor Network Enables				No Model MACAddens IPAddens Statu 1 NE-41105 00:90:E8(04:93)04 152:168:67.9					
	Found 1 Networ	k Enabler[s], remain timeout = 2 sec		1 E	Add Network Enabler					
	No. Nodel MAC Addess IIP Addess 1 Mical 105 October Glassifia Historia (75)				Inguz an Network Erobler IP addees 1921 168 87 9 V DK X Cancel					
Message Log				Message Log - 4						
Nó				No Time	Description					
1 2 3	08 03 2005 11 26 03 Found Methods Foulder Module(1 08 03 2005 11 72 Found Methods Foulder Module(1 08 03 2005 11 72 73 Found Methods Foulder Module(1			1 00.03.2005 11:26:03. Found Themark Endels: Nodel():1 2 00.03.2005 11:27:16 Found Themark Endels: Nodel():1 3 08.03.2005 11:27:23 Found Network Endels: Nodel():1 4 08.03.2005 11:27:29 Found Network Endels: Nodel():1						
		Now: 08.03.2005 11.27.28			Now: 00.03 2005 11.20.25					

Figure 4: Search of a *Moxa* module

3.6.4 Parameter readout

Select the module, double click the right mouse key and select Configure, or simply double click the left mouse key on the module. The data are selected.

8			Network E	nable	r Administrator-Configural	tion		0 0	
<u>File</u> Function <u>C</u> o	nfiguration	View <u>H</u> elp)						
222 2 ¥	🧼 🖍								
Function				Con	figuration - 1 Net	work Enable	er Module(s)		
🖃 🔊 Network Enab		No Z	Model		MAC Address	IP Address	Status		
Configure Configure Com Mag Com Mag Configure Monitor Configure Nonitor Si IP Addres	oping tor	1	NE-4110S		Ennisin F&n2433n4 Broadcast Search Specify by IP Address Locate Unlock Qonfigure Upgrade Firmware Export Configuration Import Configuration Assign IP Address	19216867.9			
Message Log - 4 M		0		_	Assign Address	_			
No Time	onitor Log -		Description						
	3.2005 11:26			rk Env	abler Module(s): 1				
2 08.03	3.2005 11:27	7:16	Found Network Enabler Module(s): 1 Found Network Enabler Module(s): 1						
	08.03.2005 11:27:23 08.03.2005 11:27:29		Found Network Enabler Module(s): 1 Found Network Enabler Module(s): 1						
4 08.03	5.2005 TT:27	623	rouna Netwo	K EN	abier module(\$): 1				
		Nov	v: 08.03.2005	11:29	t16				

Figure 5: Parameter readout

3.6.5 Configuration

When configuring it is important to select the Checkbox Modify, because otherwise the parameters could only be seen but not changed.

By pressing OK the data are transmitted to the module.

Important: the module may not receive at this time any data from the *UltraLab[®] ULS Advanced* – press the switch on the back.

Basic

• Device Name

Name of the device connected to the RS-232 Web browser Telnet

Additional access to the module

2 –	0 🥪 🖄 🖷	Confirmation (
F		Configuration
	Information Model NE-4110S	Auto Warning IP Address Report Password Digital IO Basic Network Serial Operating Mode Accessible IPs
	MAC Address 00:90:E8:0A:93:04	Modify Device Name ULS_Advanced
	Serial Number 748	☐ Modify ✓ Enable Web Console
	Firmware Ver. Ver 1.6	Enable Telnet Console
	BIOS Ver. Ver 1.2	Modify
		Time Zone (GMT+01:00) Amsterdam, Berlin, Bern, Rome, Local Date 08.03.2005
-		Local Time 11:29:11
age		Time Server
age		
		Click the "Modify" check box to modify configuration

• Date and time

Figure 6: Configuration

3.6.6 Network

.

Here, the network parameters required by the module to communicate in the network are entered.

- IP address (own)
- Netmask (subnet mask)
- Gateway
- IP Configuration

DNS Server1/2

i.e. here 192.168.67.9 (necessary) i.e. here 255.255.255.0 (necessary)

When the PC is in one of other subnets (IP of the

computer to another subnet) \cdot

Static configuration of the IP addresses. However a dynamic configuration can be selected

IP address of the DNA server (optional)

Configuration Model NE-4110S MAC Address 00:90:E8:0A:33:04 Serial Number 748 Firmware Ver. Ver 1.5 BIOS Ver. Ver 1.2 Mackadaress Configuration BIOS Ver. Ver 1.2 Mackadaress Configuration Contact Con	S File Function Co	nfiguration View <u>H</u>	Network Enabler Administ	rator-Configuration	00
Information Model NE-41105 MAC Address 00:90:E8:0A:33:04 Serial Number 748 Firmware Ver. Ver 1.5 BIOS Ver. Ver 1.2 Modify IP Configuration Static IP Community Name Location Contact		-			
Model Net 4110S MAC Address OU:90:E8:0A:93:04 Serial Number 748 748 ✓ Modify Firmware Ver. Ver 1.6 BIOS Ver. DNS Server 1 Ver 1.2 DNS Server 2 Modify Ver 1.2 Modify Ver 1.2 Modify Ver 1.2	F		Configu	ration	
No Contact	Mac MAA MAA Seri 74 Firm Ve BIO Ve	tet -4110S 2 Address :90:E8:0A:93:04 al Number 8 ware Ver. # 1.6 S Ver.	Basic Network Modify IP Address Modify Netmask Gateway IP Configuration DNS Server 1 DNS Server 2 Modify Community Name	Serial Operating Mode 192.168.67.9	_
4	1 2 3		Contact Click the "Modify" check box	to modify configuration	K X Cancel

Figure 7: Network

3.6.7 Serial

Select Modify. The Settings will be activated. Select Module and then click on Settings.

Sile Fund	tion <u>Config</u> uration View <u>H</u> e		bler Administra	ator-Configuration			000
	- v 🍂 -	r					
F			Configur	ation		6	
	Information Model NE-4110S MAC Address	Auto Warr Basic	ing I Network Iodify	P Address Report Serial	Password Operating Mode	Digital IO Accessible IPs	
	00:90:E8:04:33:04 Serial Number 748 Firmware Ver. Ver 1.6 BIOS Ver. Ver 1.2	Port 1	Alias	Settings 115200,	N,8,1,No flowctrl		
Message No 1 2 3 4		Click the "Modi	íy'' check box	o modify configura	View Settings	Settings	
	No	w: 08.03.2005 11	:33:15				_

Figure 8: Serial

S

The interface parameters are adjusted here. These are not freely eligible, but permanently bound to the *UltraLab[®] ULS Advanced*. A change of the parameters leads to sending no usable data.

•	Baud Ra	ate						115200 b	aud/s
•	Parity							None	
•	Data Bit	ts						8	
•	Stop Bit	S						1	
•	Flow Co	ontrol						None	
•	FIFO	Enable	Enable						
Star From	tion <u>C</u> onfiguration		etwork Enabler A	Administrat	or-Configuration			000	
	non <u>c</u> oninguration	view <u>n</u> eip							
F				Configura	tion			0	
	Information Model NE-4110S	E	Auto Warning Basic Ne	IF etwork	PAddress Report Serial	Password Operating Mode	Digital IO Accessible IP:	s	
	MAC Add			Serial Se	ettings		0		
Message No	00:90:E Serial Nu 748 Firmware Ver 1.6 BIOS Ver Ver 1.2	1 Port(s) Selecte Apply port a Port Alias Baud Rate Parity Data Bits Stop Bits	d. 1st port is Port alias to all selecte 115200 None 8 1		Flow Control FIFO Interface	None Enable RS-232	• • Cancel		
1 2 3 4		Clicł	< the "Modify" ch	ieck box to	o modify configuratio	on 🗸 O	K X Car	ncel	
]		Now: 08.	03.2005 11:34:5	9					

Figure 9: Interface parameters

3.6.8 Operation Mode

Select Modify. Select Module and click on Settings.

° 1			Confi	guration				0
	Information Model NE-4110S MAC Address	Auto War Basic	ning Network Modify	IP Address F Serial		Password perating Mode	Digital IO Accessible IPs	
	00:90:E8:04:93:04 Serial Number 748 Firmware Ver. Ver 1.6 BIOS Ver. Ver 1.2	Port 1	Alias		IP Mode leal COM M	lode		
ssage		Click the "Mod	lífy'' check t	ox to modify co	onfiguration	View Settings	Settings	9

Figure 10: Operation mode

Mode Choice

- Real COM Mode (further Settings)
- TCP Server Mode (further Settings)
- TCP Server Mode (further Settings)
- UDP Mode (further Settings)

Transparent line with up to 4 connections (default) The module is the server and the connections are established by the client (computer) The module is the client and establishes a connection to a server (computer) Improved TCP mode

Fur	nction Configuration Vie	w Help				
	1 Port(s) Selected. 1st	oort is Port 1				0
	Operating Mode	Real COM	Mode	-		
		Real COM TCP Serve	Mode			Digital IO Accessible IPs
	Real COM	TCP Client	Mode			Accessible IPs
		UDP Mode	•			
	Max Connection	2	-			
	Miscellaneous (Opt	onal)				
	TCP Alive Check					
	7		9 min)			
	Data Packing (Opti	onali				
	Delimiter 1	00	(0-ff, Hex)			
	Delimiter 2	00	(0-ff, Hex)			
	Force Tx Timeout	0				
	10.00 111 11.000	0	(0-65535 ms)			Settings
						1
				🗸 OK	🗙 Cancel	X Cancel
			.03.2005 11:36:29			

Figure 11: Mode choice

3.6.9 Real COM Mode

The real COM Mode is adjusted and recommended by *GENERAL ACOUSTICS*. In this mode (transparent connection) four connections to different computers can be established.

	Network Enabler Administrator-Configuration	00
le Function Configuration		
	Operating Mode	0
1 Port(s) Selecte	ed. 1st port is Port 1	0
Operating Mo	ode Real COM Mode -	
2		Digital IO
Real COM		Accessible IPs
Max Connecti	on 2	
	1	
Miscellaneo	us (Optiona 3	
TCP Alive	Check Time 4	
7	(0-99 min)	
Data Packir	o (Optional)	
Delimite		
Delimite	(011, 110A)	
Force Tx T	imeout 0 (0-65535 ms)	Cathian
ssai		Settings
	1.04	
	✓ 0K	X Cancel
	Now: 08.03.2005 11:38:17	

Figure 12: Real COM Mode

3.7 Install a virtual COM Port

3.7.1 COM Mapping

Select Com Mapping. Right mouse click on the COM Mapping and then select Add Target in the context menu.

\$		Network Enab	ler Administrator-CO	M Mapping			000	53	Network Ena	bler Administrator-CO	Mapping			000
Ele COM Mapping View	Help							Ele COM Mapping View	Help					
A & B C G								1 🗞 🕲 🕑 🕲						
Function	ction COM Mapping - 0 COM				Function	COM Mapping - 0 COM								
Network Enabler Admin Configuration	No /	Model	IP Address	Port	CDM Port	Mode	Parameter	Network Enables Adms Configuration Configuration Configuration Configuration Adm		IP Address	Port	COM Port	Mode	Parameter
									more Tecari					
									alda					
								62	W Bellings					
									ply Change					
								🛋 Eg	port COM Mepping					-
 >.	-								port COM Mapping),
Message Log - 1								Message Log - 1						
No Time 1 10.03.2005.07	48:50	Description Found Network E	nabler Module(s) 1					No Time 1 10.03200507	Description 48:50 Found Network	Enabler Module(s) 1				

Figure 13: COM Mapping

Then select again the module and confirm with OK.

First, an entry in the list is chosen for a Com Port, then it can be changed.

Select a Com Port. Right mouse click and select COM Settings.

🗿 🔊 😰 🤌 🙇								
Function								
= 🔊 Network Enabler Admir	No 🛆 Model			IP Address Port		COM Port	Mode	Parameter
Configuration				Add Target Add Target Remove Target Enable Disable QOM Settings Apply Change Discard Change Export COM Mappin			Hi-Perfor	9600, None, 8, 1,
)+	ا		-	Import COM Mappin	• ⊨			
Message Log - 1 No Time 1 10.03.2005 07:-	48:50	Description Found Network	k En	abler Module(s): 1				

Figure 14: COM Settings

COM Settings

Here the same parameters are adjusted, like in the module.

- Basic Settings
- Advanced Settings

- The port to use and the free virtual $\operatorname{Com}\operatorname{Port}$
- Hi-Perfomance and FIFO (Buffer)
- Serial Parameters

Parameters of the serial interface

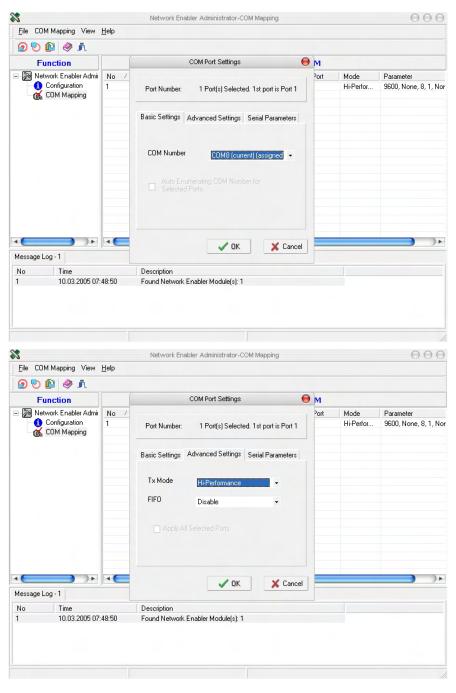


Figure 15: COM Settings. Additional parameters

Serial Parameters

•	Baud Rate	115200 Baud/s
•	Parity	none
•	Data Bits	8
•	Stop Bits	1
•	Flow Control	None

Eile COM Mapping View	<u>H</u> elp	Network Enable	r Administrator-C	OM Mapping			000
ي الأ 🔊 🕲 🔊							
Function		C	OM Port Settings	(● M		
Network Enabler Admin Configuration COM Mapping	<u>No /</u> 1	Port Number:	1 Port(s) Selecte	Port	Mode Hi-Perfor	Parameter 9600, None, 8, 1, Nor	
		Basic Settings Ad Baud Rate Parity Data Bits Stop Bits Flow Control	115200 None 8 1 None	Serial Parameters			
Message Log - 1 No Time 1 10.03.2005 07.48.50		Description	V 0K	X Cancel),
1 10.03.2005 07:	:46:50	Found Network En	adier Module(s): 1				

Figure 16: Serial parameters

After configuring the interface confirm with OK.

3.7.2 Assuming and establishing a COM Port

Activate the context menu of the COM Port and press Apply Change.

Then some messages follow. If it worked, a confirmation that the COM Port was generated is issued.

n 🇞 🗐 🕑 😰								
Function			CO	мм	apping -	- 1 COM		
🗉 🔊 Network Enabler Admii			IP Address				Mode	Para
- Configuration - 🛣 COM Mapping	1	NE-41105	19216867		Add Targ Remove Enable Disable COM Set Apply Ch Discard O Export C	Target tings ange	 Hi-Performance, FIFO Disa 	à 115
	•			-	I <u>m</u> port C	OM Mapping)+
Message Log - 0								
No Time		Description						

Figure 17: Assuming and establishing a COM Port

As a result the COM Port is generated and can then be used by a terminal program or an application to log and analyse data.

Here is not necessary to run the program Network Enabler Admistration .

All this is also described in the *Moxa*-documentation on the CD.

An original parameter file for the module is also included.

4 WARRANTY STATEMENT

(1) Warranty period

GENERAL ACOUSTICS GmbH, as manufacturer, will, itself or through its authorised sales partners, provide end-users with warranty coverage on all *GENERAL ACOUSTICS* products purchased as new and unused for a period of 12 months from the date of sale.

(2) GENERAL ACOUSTICS procedure

Any part, which has been correctly used and is found to be defective as a result of manufacturing and/or material faults within the above-mentioned warranty period, will either be repaired or replaced with a new part by *GENERAL ACOUSTICS* after expert opinion has been sought. Material and/or labour costs arising as a result will not be charged. All exchanged parts become the property of *GENERAL ACOUSTICS*

(3) Conditions for labour rendered under warranty

Instruments delivered must have been operated correctly, unauthorised modifications or repairs must not have taken place and the benchtop instrument must not have been opened.

(4) No warranty claim exists in the following cases

- Parts subject to normal wear

- Damage caused by incorrect maintenance, fitting and addition of non-approved parts and devices, as well as unauthorised modification of components

- Damage caused by electrolysis
- Damage caused by fire or accident, incorrect usage, misuse or negligence
- Damage/rust/corrosion caused by the entry of water

(5) Explicit or tacit guarantees

These guarantees confer special rights to you, and you may also have other rights, which differ from country to country or from province to province. Where these guarantee claims apply, all other explicit or tacit guarantees provided by *GENERAL ACOUSTICS* automatically lose their validity, incl. all market access guarantees or guarantees of fitness for every specific purpose. Conversely, the guarantees thus arising are limited to the period of this warranty. Neither sales partners nor traders are authorised to make any other assurances, representation of facts or warranty offers than those contained in the warranty conditions.

5 CE CONFORMITY STATEMENT



The instrument conforms to the requirements of the EEC directive 89/336/EWG and the revisions through 92/31/EWG and 93/68/EWG Article 5 pertaining to "Electromagnetic Compatibility", as well as 73/23/EWG and the revisions through 93/68/EWG Article 13 pertaining to "Safety".

6 TECHNICAL SPECIFICATIONS

Instrument model	UltraLab [®] ULS Advanced					
Sensors	USS12-HF, IP 65, M30x1.5					
Parameter setting	Virtual com-port via Ethernet (LAN)					
Measuring range	From 200 mm up to 1200 mm					
Technical resolution	Up to +/- 0.36 mm					
Accuracy	+/- 1 mm					
Sample rate	100 Hz					
Data readout	Digital via data telegram					
Electric power	230 VAC, 250 mA (110 VAC optional)					
supply						
Chassis	ca. 330 / 160 / 260 mm width / height / depth IP 50					
Temperature range	-20+70°C					
	UltraLab [®] ULS Advanced instrument, 12 ultrasound sensors USS12_HF, 12					
Delivery package	sensor cable, 1 reference sensor REF-300 including calibrated distance unit, 1					
Delivery package	reference sensor cable, 1 Ethernet cable, 1 power supply cable, 1 User					
	Manual					