



# PN7120

## Full NFC Forum-compliant controller with integrated firmware and NCI interface

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Product data sheet  
COMPANY PUBLIC

## 1. Introduction

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This document describes the functionality and electrical specification of the NFC Controller PN7120.

Additional documents describing the product functionality further are available for design-in support. Refer to the references listed in this document to get access to the full for full documentation provided by NXP.

## 2. General description

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PN7120, the best plug'n play full NFC solution - easy integration into any OS environment, with integrated firmware and NCI interface designed for contactless communication at 13.56 MHz.

It is the ideal solution for rapidly integrating NFC technology in any application, especially those running OS environment like Linux and Android, reducing Bill of Material (BOM) size and cost, thanks to:

- full NFC forum compliancy (see [Ref. 11](#)) with small form factor antenna
- embedded NFC firmware providing all NFC protocols as pre-integrated feature
- direct connection to the main host or microcontroller, by I<sup>2</sup>C-bus physical and NCI protocol
- ultra-low power consumption in polling loop mode
- Highly efficient integrated power management unit (PMU) allowing direct supply from a battery

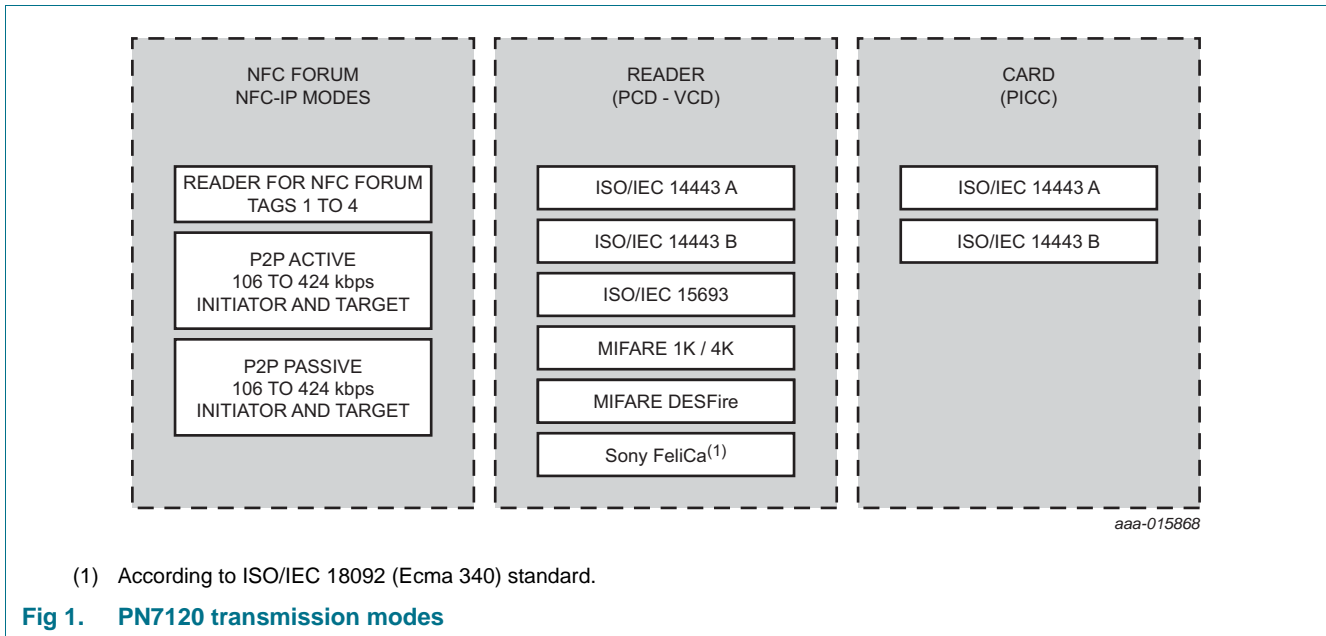
PN7120 embeds a new generation RF contactless front-end supporting various transmission modes according to NFCIP-1 and NFCIP-2, ISO/IEC14443, ISO/IEC 15693, ISO/IEC 18000-3, MIFARE and FeliCa specifications. It embeds an ARM Cortex-M0 microcontroller core loaded with the integrated firmware supporting the NCI 1.0 host communication.

The contactless front-end design brings a major performance step-up with on one hand a higher sensitivity and on the other hand the capability to work in active load modulation communication enabling the support of small antenna form factor

Supported transmission modes are listed in [Figure 1](#). For contactless card functionality, the PN7120 can act autonomously if previously configured by the host in such a manner.



PN7120 integrated firmware provides an easy integration and validation cycle as all the NFC real-time constraints, protocols and device discovery (polling loop) are being taken care internally. In few NCI commands, host SW can configure the PN7120 to notify for card or peer detection and start communicating with them.



### 3. Features and benefits

- Includes NXP ISO/IEC14443-A, Innovatron ISO/IEC14443-B and NXP MIFARE Crypto 1 intellectual property [licensing rights](#)
- ARM Cortex-M0 microcontroller core
- Highly integrated demodulator and decoder
- Buffered output drivers to connect an antenna with minimum number of external components
- Integrated RF level detector
- Integrated Polling Loop for automatic device discovery
- RF protocols supported
  - ◆ NFCIP-1, NFCIP-2 protocol (see [Ref. 7](#) and [Ref. 10](#))
  - ◆ ISO/IEC 14443A, ISO/IEC 14443B PICC mode via host interface (see [Ref. 2](#))
  - ◆ ISO/IEC 14443A, ISO/IEC 14443B PCD designed according to NFC Forum digital protocol T4T platform and ISO-DEP (see [Ref. 11](#))
  - ◆ FeliCa PCD mode
  - ◆ MIFARE PCD encryption mechanism (MIFARE 1K/4K)
  - ◆ NFC Forum tag 1 to 4 (MIFARE Ultralight, Jewel, Open FeliCa tag, DESFire) (see [Ref. 11](#))
  - ◆ ISO/IEC 15693/ICODE VCD mode (see [Ref. 8](#))
- Supported host interfaces
  - ◆ NCI protocol interface according to NFC Forum standardization (see [Ref. 1](#))
  - ◆ I<sup>2</sup>C-bus High-speed mode (see [Ref. 3](#))

- Integrated power management unit
  - ◆ Direct connection to a battery (2.3 V to 5.5 V voltage supply range)
  - ◆ Support different Hard Power-Down/Standby states activated by firmware
  - ◆ Autonomous mode when host is shut down
- Automatic wake-up via RF field, internal timer and I<sup>2</sup>C-bus interface
- Integrated non-volatile memory to store data and executable code for customization

## 4. Applications

- All devices requiring NFC functionality especially those running in an Android or Linux environment
- TVs, set-top boxes, Blu-ray decoders, audio devices
- Home automation, gateways, wireless routers
- Home appliances
- Wearables, remote controls, healthcare, fitness
- Printers, IP phones, gaming consoles, accessories

## 5. Quick reference data

Table 1. Quick reference data

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V <sub>BAT</sub>	battery supply voltage	Card Emulation and Passive Target; V <sub>SS</sub> = 0 V <a href="#">[1]</a> <a href="#">[2]</a>	2.3	-	5.5	V
		Reader, Active Initiator and Active Target; V <sub>SS</sub> = 0 V <a href="#">[1]</a> <a href="#">[2]</a>	2.7	-	5.5	V
V <sub>DD</sub>	supply voltage	internal supply voltage	1.65	1.8	1.95	V
V <sub>DD(PAD)</sub>	V <sub>DD(PAD)</sub> supply voltage	supply voltage for host interface				
		1.8 V host supply; V <sub>SS</sub> = 0 V <a href="#">[1]</a>	1.65	1.8	1.95	V
		3.3 V host supply; V <sub>SS</sub> = 0 V <a href="#">[1]</a>	3.0	-	3.6	V
I <sub>BAT</sub>	battery supply current	in Hard Power Down state; V <sub>BAT</sub> = 3.6 V; T = 25 °C	-	10	12	μA
		in Standby state; V <sub>BAT</sub> = 3.6 V; T = 25 °C	-	-	20	μA
		in Monitor state; V <sub>BAT</sub> = 2.75 V; T = 25 °C	-	-	12	μA
		in low-power polling loop; V <sub>BAT</sub> = 3.6 V; T = 25 °C; loop time = 500 ms	-	150	-	μA
		PCD mode at typical 3 V <a href="#">[3]</a>	-	-	170	mA
I <sub>O(VDDPAD)</sub>	output current on pin V <sub>DD(PAD)</sub>	total current which can be pulled on V <sub>DD(PAD)</sub> referenced outputs	-	-	15	mA

Table 1. Quick reference data ...continued

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{th(lim)}$	current limit threshold current	current limiter on $V_{DD(TX)}$ pin; $V_{DD(TX)} = 3.1\text{ V}$	[3] [4]	180	-	mA
$P_{tot}$	total power dissipation	Reader; $I_{VDD(TX)} = 100\text{ mA}$ ; $V_{BAT} = 5.5\text{ V}$	-	-	0.5	W
$T_{amb}$	ambient temperature	JEDEC PCB-0.5	-30	+25	+85	°C

[1]  $V_{SS}$  represents  $V_{SS}$ ,  $V_{SS1}$ ,  $V_{SS2}$ ,  $V_{SS3}$ ,  $V_{SS4}$ ,  $V_{SS(PAD)}$  and  $V_{SS(TX)}$ .

[2] The antenna should be tuned not to exceed this current limit (the detuning effect when coupling with another device must be taken into account).

[3] The antenna shall be tuned not to exceed the maximum of  $I_{VBAT}$ .

[4] This is the threshold of a built-in protection done to limit the current out of  $V_{DD(TX)}$  in case of any issue at antenna pins to avoid burning the device. It is not allowed in operational mode to have  $I_{VDD(TX)}$  such that  $I_{VBAT}$  maximum value is exceeded.

## 6. Ordering information

Table 2. Ordering information

Type number	Package		
	Name	Description	Version
PN7120A0EV/C1xxxx	VFBGA49	plastic very thin fine-pitch ball grid array package; 49 balls	SOT1320-1

## 7. Marking

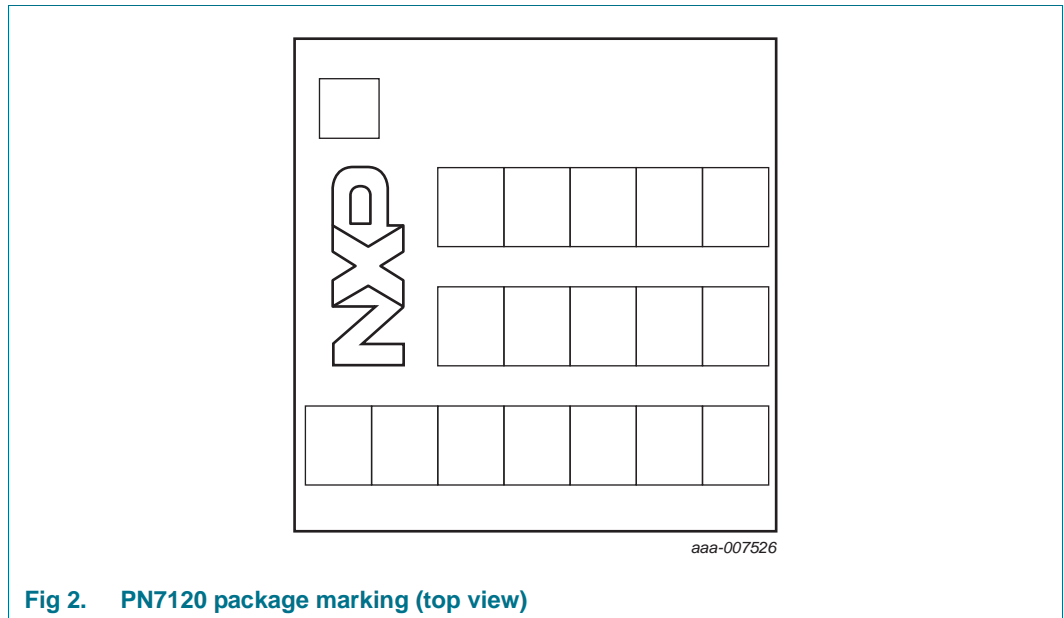


Fig 2. PN7120 package marking (top view)

Table 3. Marking code

Line number	Marking code
Line 1	product version identification
Line 2	diffusion batch sequence number
Line 3	manufacturing code including: <ul style="list-style-type: none"><li>• diffusion center code:<ul style="list-style-type: none"><li>– N: TSMC</li><li>– s: Global Foundry</li></ul></li><li>• assembly center code:<ul style="list-style-type: none"><li>– S: APK</li><li>– X: ASEN</li></ul></li><li>• RoHS compliancy indicator:<ul style="list-style-type: none"><li>– D: Dark Green; fully compliant RoHS and no halogen and antimony</li></ul></li><li>• manufacturing year and week, 3 digits:<ul style="list-style-type: none"><li>– Y: year</li><li>– WW: week code</li></ul></li><li>• product life cycle status code:<ul style="list-style-type: none"><li>– X: means not qualified product</li><li>– nothing means released product</li></ul></li></ul>

### 8. Block diagram

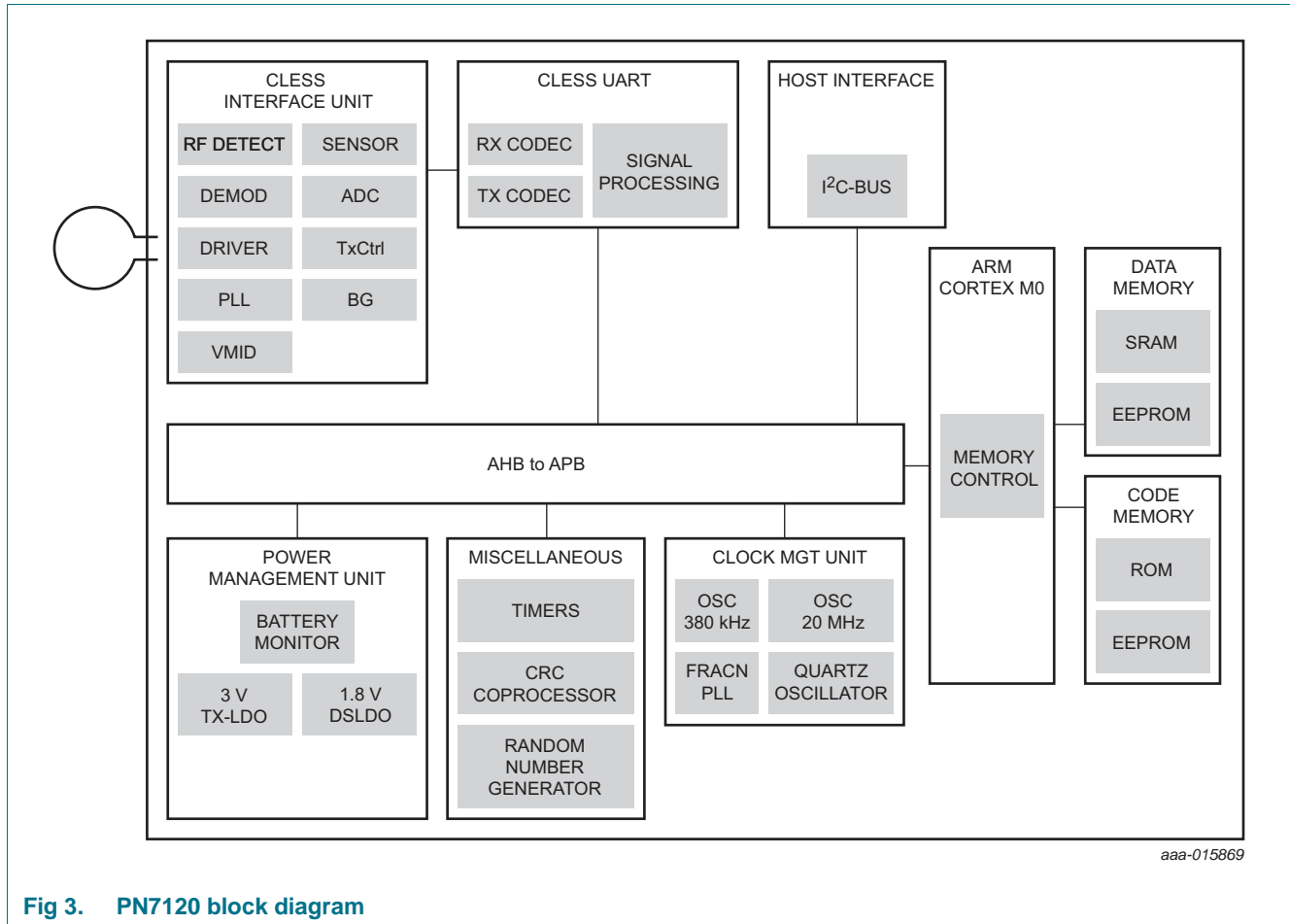


Fig 3. PN7120 block diagram

## 9. Pinning information

### 9.1 Pinning

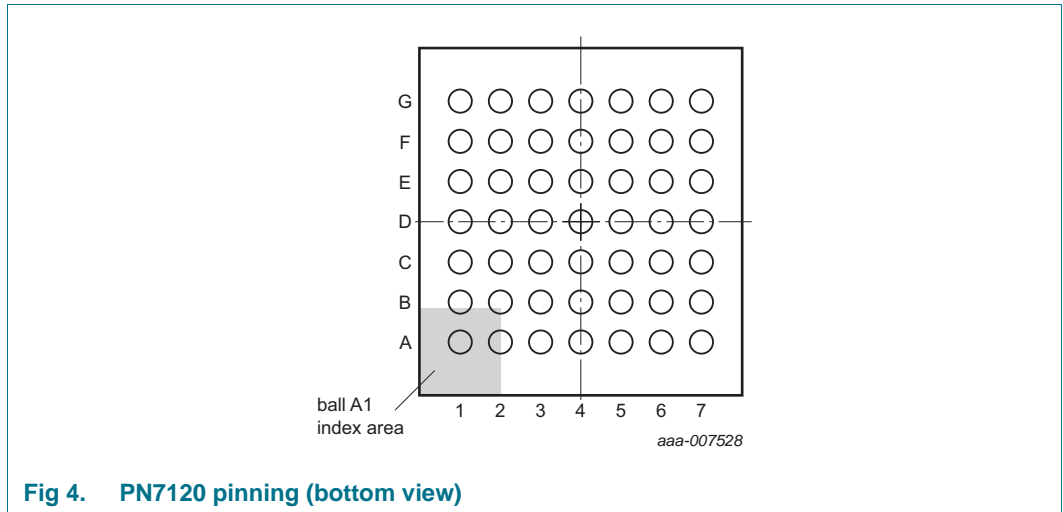


Table 4. PN7120 pin description

Symbol	Pin	Type <sup>[1]</sup>	Refer	Description
i.c.	A1	-	-	internally connected; must be connected to ground
CLK_REQ	A2	O	V <sub>DD(PAD)</sub>	clock request pin
XTAL1	A3	I	V <sub>DD</sub>	PLL clock input. Oscillator input
i.c.	A4	-	-	internally connected; leave open
i.c.	A5	-	-	internally connected; leave open
i.c.	A6	-	-	internally connected; leave open
i.c.	A7	-	-	internally connected; leave open
I2CSCL	B1	I	V <sub>DD(PAD)</sub>	I <sup>2</sup> C-bus serial clock input
I2CADR0	B2	I	V <sub>DD(PAD)</sub>	I <sup>2</sup> C-bus address bit 0 input
i.c.	B3	-	-	internally connected; leave open
i.c.	B4	-	-	internally connected; leave open
i.c.	B5	-	-	internally connected; must be connected to ground
V <sub>SS1</sub>	B6	G	n/a	ground
i.c.	B7	-	-	internally connected; leave open
I2CSDA	C1	I/O	V <sub>DD(PAD)</sub>	I <sup>2</sup> C-bus serial data
V <sub>SS(PAD)</sub>	C2	G	n/a	pad ground
XTAL2	C3	O	V <sub>DD</sub>	oscillator output
V <sub>SS</sub>	C4	G	n/a	ground
n.c.	C5	-	-	not connected
V <sub>DD</sub>	C6	P	n/a	LDO output supply voltage
V <sub>BAT</sub>	C7	P	n/a	battery supply voltage
IRQ	D1	O	V <sub>DD(PAD)</sub>	interrupt request output

Table 4. PN7120 pin description ...continued

Symbol	Pin	Type <sup>[1]</sup>	Refer	Description
BOOST_CTRL	D2	O	V <sub>DD(PAD)</sub>	booster control, see <a href="#">Ref. 5</a>
V <sub>DD(PAD)</sub>	D3	P	n/a	pad supply voltage
V <sub>SS2</sub>	D4	G	n/a	ground
i.c.	D5	-	-	internally connected; leave open
V <sub>SS3</sub>	D6	G	n/a	ground
i.c.	D7	-	-	internally connected; leave open
VEN	E1	I	V <sub>BAT</sub>	reset pin. Set the device in Hard Power Down
V <sub>SS(DC_DC)</sub>	E2	G	n/a	ground
n.c.	E3	-	-	not connected
n.c.	E4	-	-	not connected
n.c.	E5	-	-	not connected
n.c.	E6	-	-	not connected
V <sub>DD(TX)</sub>	E7	P	n/a	contactless transmitter output supply voltage for decoupling
i.c.	F1	-	-	internally connected; leave open
i.c.	F2	-	-	internally connected; leave open
V <sub>SS4</sub>	F3	G	n/a	ground
i.c.	F4	-	-	internally connected; leave open
RXN	F5	I	V <sub>DD</sub>	negative receiver input
RXP	F6	I	V <sub>DD</sub>	positive receiver input
V <sub>DD(MID)</sub>	F7	P	n/a	receiver reference input supply voltage
V <sub>BAT2</sub>	G1	P	n/a	battery supply voltage; must be connected to V <sub>BAT</sub>
V <sub>BAT1</sub>	G2	P	n/a	battery supply voltage; must be connected to V <sub>BAT</sub>
TX1	G3	O	V <sub>DD(TX)</sub>	antenna driver output
V <sub>SS(TX)</sub>	G4	G	n/a	contactless transmitter ground
TX2	G5	O	V <sub>DD(TX)</sub>	antenna driver output
ANT2	G6	P	n/a	antenna connection for Listen mode
ANT1	G7	P	n/a	antenna connection for Listen mode

[1] P = power supply; G = ground; I = input, O = output; I/O = input/output.

## 10. Functional description

PN7120 can be connected on a host controller through I<sup>2</sup>C-bus. The logical interface towards the host baseband is NCI-compliant [Ref. 1](#) with additional command set for NXP-specific product features. This IC is fully user controllable by the firmware interface described in [Ref. 4](#).

Moreover, PN7120 provides flexible and integrated power management unit in order to preserve energy supporting Power Off mode.

In the following chapters you will find also more details about PN7120 with references to very useful application note such as:



- PN7120 User Manual ([Ref. 4](#)):  
User Manual describes the software interfaces (API) based on the NFC forum NCI standard. It does give full description of all the NXP NCI extensions coming in addition to NCI standard ([Ref. 1](#)).
- PN7120 Hardware Design Guide ([Ref. 5](#)):  
Hardware Design Guide provides an overview on the different hardware design options offered by the IC and provides guidelines on how to select the most appropriate ones for a given implementation. In particular, this document highlights the different chip power states and how to operate them in order to minimize the average NFC-related power consumption so to enhance the battery lifetime.
- PN7120 Antenna and Tuning Design Guide ([Ref. 6](#)):  
Antenna and Tuning Design Guide provides some guidelines regarding the way to design an NFC antenna for the PN7120 chip.  
It also explains how to determine the tuning/matching network to place between this antenna and the PN7120.  
Standalone antenna performances evaluation and final RF system validation (PN7120 + tuning/matching network + NFC antenna within its final environment) are also covered by this document.
- PN7120 Low-Power Mode Configuration ([Ref. 9](#)):  
Low-Power Mode Configuration documentation provides guidance on how PN7120 can be configured in order to reduce current consumption by using Low-power polling mode.

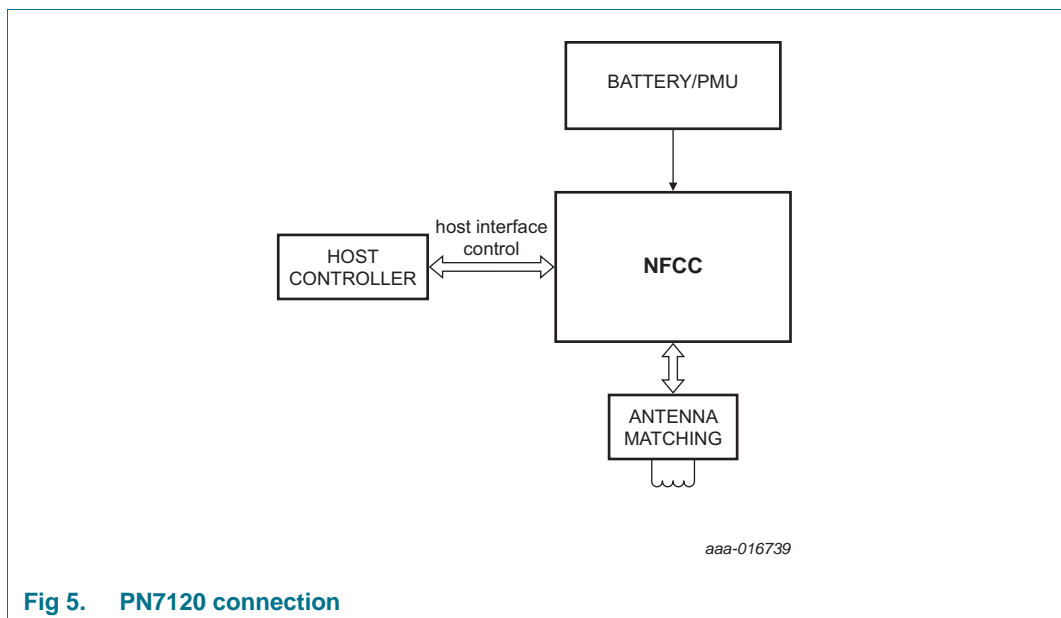


Fig 5. PN7120 connection

## 10.1 System modes

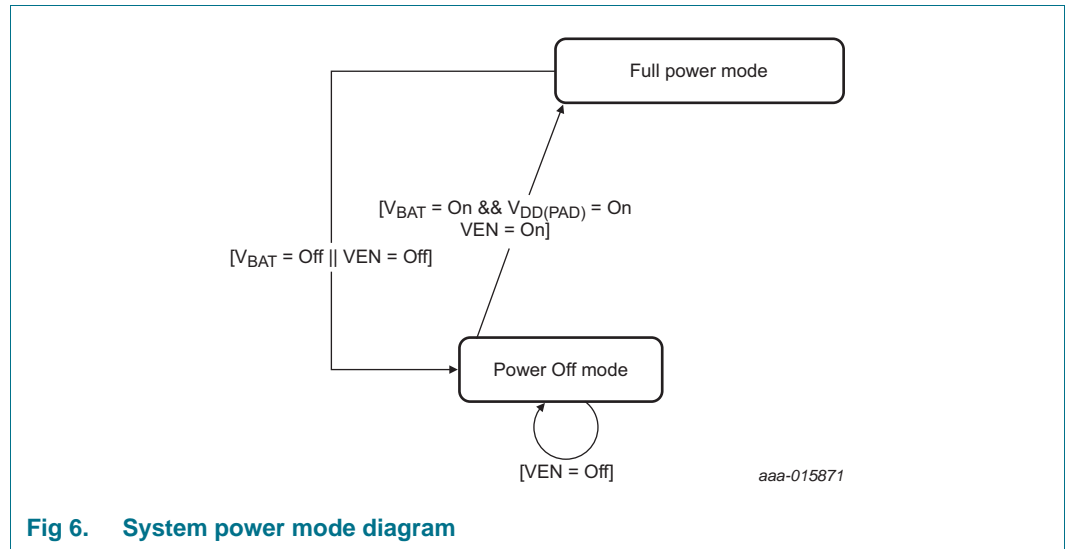
### 10.1.1 System power modes

PN7120 is designed in order to enable the different power modes from the system.

2 power modes are specified: Full power mode and Power Off mode.

**Table 5. System power modes description**

System power mode	Description
Full power mode	the main supply ( $V_{BAT}$ ) as well as the host interface supply ( $V_{DD(PAD)}$ ) is available, all use cases can be executed
Power Off mode	the system is kept Hard Power Down (HPD)



**Fig 6. System power mode diagram**

Table 6 summarizes the system power mode of the PN7120 depending on the status of the external supplies available in the system:

**Table 6. System power modes configuration**

$V_{BAT}$	VEN	Power mode
Off	X	Power Off mode
On	Off	Power Off mode
On	On	Full power mode

Depending on power modes, some application states are limited:

**Table 7. System power modes description**

System power mode	Allowed communication modes
Power Off mode	no communication mode available
Full power mode	Reader/Writer, Card Emulation, P2P modes

### 10.1.2 PN7120 power states

Next to system power modes defined by the status of the power supplies, the power states include the logical status of the system thus extend the power modes.

4 power states are specified: Monitor, Hard Power Down (HPD), Standby, Active.

Table 8. PN7120 power states

Power state name	Description
Monitor	The PN7120 is supplied by $V_{BAT}$ which voltage is below its programmable critical level, VEN voltage > 1.1 V and the Monitor state is enabled. The system power mode is Power Off mode.
Hard Power Down	The PN7120 is supplied by $V_{BAT}$ which voltage is above its programmable critical level when Monitor state is enabled and PN7120 is kept in Hard Power Down (VEN voltage is kept low by host or SW programming) to have the minimum power consumption. The system power mode is in Power Off.
Standby	The PN7120 is supplied by $V_{BAT}$ which voltage is above its programmable critical level when the Monitor state is enabled, VEN voltage is high (by host or SW programming) and minimum part of PN7120 is kept supplied to enable configured wake-up sources which allow to switch to Active state; RF field, Host interface. The system power mode is Full power mode.
Active	The PN7120 is supplied by $V_{BAT}$ which voltage is above its programmable critical level when Monitor state is enabled, VEN voltage is high (by host or SW programming) and the PN7120 internal blocks are supplied. 3 functional modes are defined: Idle, Listener and Poller. The system power mode is Full power mode.

At application level, the PN7120 will continuously switch between different states to optimize the current consumption (polling loop mode). Refer to [Table 1](#) for targeted current consumption in here described states.

The PN7120 is designed to allow the host controller to have full control over its functional states, thus of the power consumption of the PN7120 based NFC solution and possibility to restrict parts of the PN7120 functionality.

#### 10.1.2.1 Monitor state

In Monitor state, the PN7120 will exit it only if the battery voltage recovers over the critical level. Battery voltage monitor thresholds show hysteresis behavior as defined in [Table 26](#).

PN7120 will autonomously shut-down internal PMU supply to protect the battery from deep discharge.

#### 10.1.2.2 Hard Power Down (HPD) state

The Hard Power Down state is entered when  $V_{DD(PAD)}$  and  $V_{BAT}$  are high by setting VEN voltage < 0.4 V. As these signals are under host control, the PN7120 has no influence on entering or exiting this state.

#### 10.1.2.3 Standby state

Active state is PN7120's default state after boot sequence in order to allow a quick configuration of PN7120. It is recommended to change the default state to Standby state after first boot in order to save power. PN7120 can switch to Standby state autonomously (if configured by host).

In this state PN7120 most blocks including CPU are no more supplied. Number of wake-up sources exist to put PN7120 into Active state:

- I<sup>2</sup>C-bus interface wake-up event
- Antenna RF level detector

- Internal timer event when using polling loop (380 kHz Low-power oscillator is enabled)

If wake-up event occurs, PN7120 will switch to Active state. Any further operation depends on software configuration and/or wake-up source.

#### 10.1.2.4 Active state

Within the Active state, the system is acting as an NFC device. The device can be in 3 different functional modes: Idle, Poller and Target.

**Table 9. Functional modes in active state**

Functional modes	Description
Idle	the PN7120 is active and host interface communication is on going. The RF interface is not activated. If Standby state is de-activated PN547/C2 stays in Idle mode even when no host communication.
Listener	the PN7120 is active and is listening to external device. The RF interface is activated.
Poller	the PN7120 is active and is in Poller mode. It polls external device. The RF interface is activated.

**Poller mode:** In this mode, PN547/C2 is acting as Reader/Writer or NFC Initiator, searching for or communicating with passive tags or NFC target. Once RF communication has ended, PN547/C2 will switch to Idle mode or Standby state to save energy. Poller mode shall be used with  $2.7\text{ V} < V_{\text{BAT}} < 5.5\text{ V}$  and VEN voltage  $> 1.1\text{ V}$ . Poller mode shall not be used with  $V_{\text{BAT}} < 2.7\text{ V}$ .  $PV_{\text{DD}}$  is within its operational range (see [Table 1](#)).

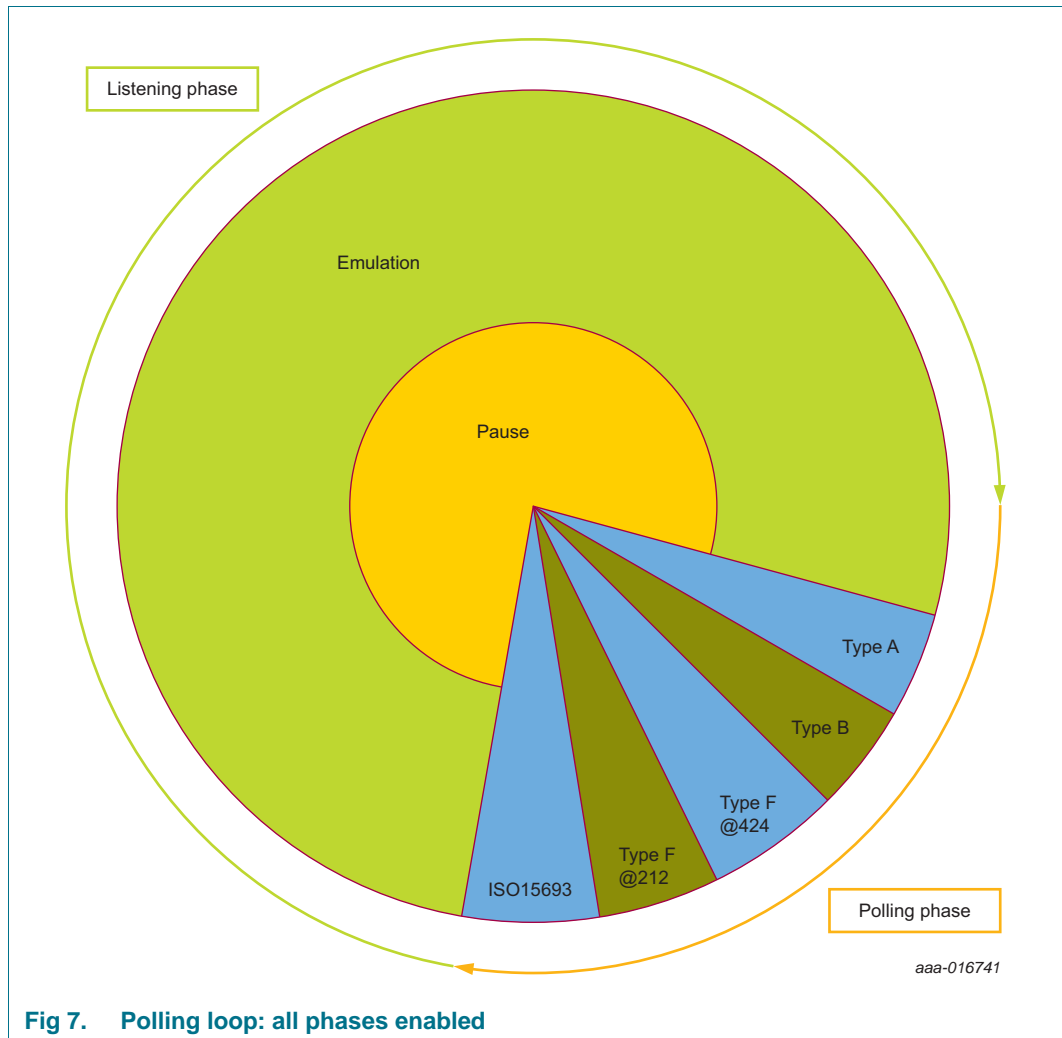
**Listener mode:** In this mode, PN547/C2 is acting as a card or as an NFC Target. Listener mode shall be used with  $2.3\text{ V} < V_{\text{BAT}} < 5.5\text{ V}$  and VEN voltage  $> 1.1\text{ V}$ . Once RF communication has ended, PN547/C2 will switch to Idle mode or Standby state to save energy.

#### 10.1.2.5 Polling loop

The polling loop will sequentially set PN7120 in different power states (Active or Standby). All RF technologies supported by PN7120 can be independently enabled within this polling loop.

There are 2 main phases in the polling loop:

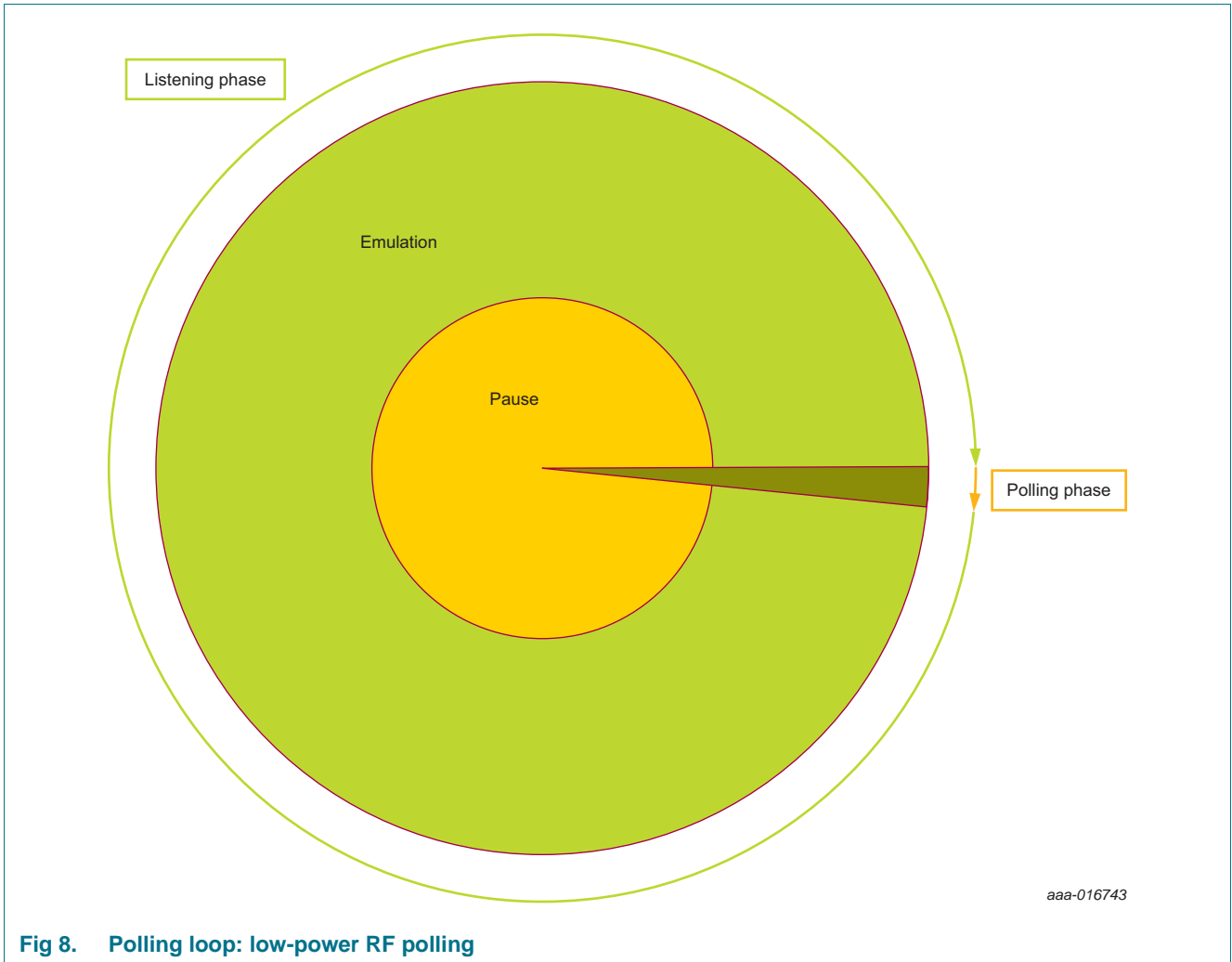
- Listening phase. The PN7120 can be in Standby power state or Listener mode
- Polling phase. The PN7120 is in Poller mode



**Fig 7. Polling loop: all phases enabled**

Listening phase uses Standby power state (when no RF field) and PN7120 goes to Listener mode when RF field is detected. When in Polling phase, PN7120 goes to Poller mode.

To further decrease the power consumption when running the polling loop, PN7120 features a low-power RF polling. When PN7120 is in Polling phase instead of sending regularly RF command PN7120 senses with a short RF field duration if there is any NFC Target or card/tag present. If yes, then it goes back to standard polling loop. With 500 ms (configurable duration, see [Ref. 4](#)) listening phase duration, the average power consumption is around 150  $\mu$ A.



**Fig 8. Polling loop: low-power RF polling**

Detailed description of polling loop configuration options is given in [Ref. 4](#).

### 10.2 Microcontroller

PN7120 is controlled via an embedded ARM Cortex-M0 microcontroller core.

PN7120 features integrated in firmware are referenced in [Ref. 4](#)

### 10.3 Host interfaces

PN7120 provides the support of an I<sup>2</sup>C-bus Slave Interface, up to 3.4 MBaud.

The host interface is waken-up on I<sup>2</sup>C-bus address.

To enable and ensure data flow control between PN7120 and host controller, additionally a dedicated interrupt line IRQ is provided which Active state is programmable. See [Ref. 4](#) for more information.

### 10.3.1 I<sup>2</sup>C-bus interface

The I<sup>2</sup>C-bus interface implements a slave I<sup>2</sup>C-bus interface with integrated shift register, shift timing generation and slave address recognition.

I<sup>2</sup>C-bus Standard mode (100 kHz SCL), Fast mode (400 kHz SCL) and High-speed mode (3.4 MHz SCL) are supported.

The main hardware characteristics of the I<sup>2</sup>C-bus module are:

- Support slave I<sup>2</sup>C-bus
- Standard, Fast and High-speed modes supported
- Wake-up of PN7120 on its address only
- Serial clock synchronization can be used by PN7120 as a handshake mechanism to suspend and resume serial transfer (clock stretching)

The I<sup>2</sup>C-bus interface module meets the I<sup>2</sup>C-bus specification [Ref. 3](#) except General call, 10-bit addressing and Fast mode Plus (Fm+).

#### 10.3.1.1 I<sup>2</sup>C-bus configuration

The I<sup>2</sup>C-bus interface shares four pins with I<sup>2</sup>C-bus interface also supported by PN7120. When I<sup>2</sup>C-bus is configured in EEPROM settings, functionality of interface pins changes to one described in [Table 10](#).

**Table 10. Functionality for I<sup>2</sup>C-bus interface**

Pin name	Functionality
I2CADR0	I <sup>2</sup> C-bus address 0
I2CSDA	I <sup>2</sup> C-bus data line
I2CSCL	I <sup>2</sup> C-bus clock line

PN7120 supports 7-bit addressing mode. Selection of the I<sup>2</sup>C-bus address is done by 2-pin configurations on top of a fixed binary header: 0, 1, 0, 1, 0, 0, I2CADR0, R/W.

**Table 11. I<sup>2</sup>C-bus interface addressing**

I2CADR0	I <sup>2</sup> C-bus address (R/W = 0, write)	I <sup>2</sup> C-bus address (R/W = 1, read)
0	0x50	0x51
1	0x52	0x53

## 10.4 PN7120 clock concept

There are 4 different clock sources in PN7120:

- 27.12 MHz clock coming either/or from:
  - Internal oscillator for 27.12 MHz crystal connection
  - Integrated PLL unit which includes a 1 GHz VCO
- 13.56 MHz RF clock recovered from RF field
- Low-power oscillator 20 MHz
- Low-power oscillator 380 kHz

10.4.1 27.12 MHz quartz oscillator

When enabled, the 27.12 MHz quartz oscillator applied to PN7120 is the time reference for the RF front end when PN7120 is behaving in Reader mode or NFCIP-1 initiator.

Therefore stability of the clock frequency is an important factor for reliable operation. It is recommended to adopt the circuit shown in [Figure 9](#).

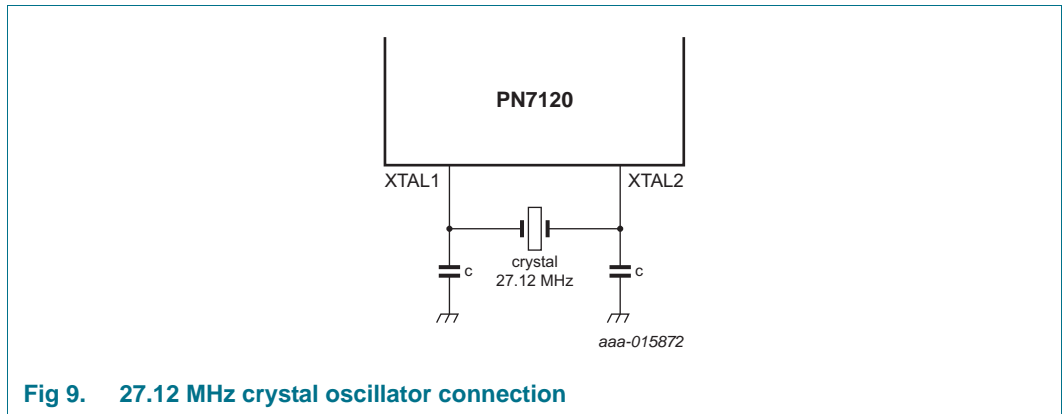


Fig 9. 27.12 MHz crystal oscillator connection

[Table 12](#) describes the levels of accuracy and stability required on the crystal.

Table 12. Crystal requirements

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{xtal}$	crystal frequency	ISO/IEC and FCC compliancy	-	27.12	-	MHz
$\Delta f_{xtal}$	crystal frequency accuracy	full operating range <a href="#">[1]</a>	-100	-	+100	ppm
		all $V_{BAT}$ range; $T = 20\text{ }^{\circ}\text{C}$ <a href="#">[1]</a>	-50	-	+50	ppm
		all temperature range; $V_{BAT} = 3.6\text{ V}$ <a href="#">[1]</a>	-50	-	+50	ppm
ESR	equivalent series resistance		-	50	100	$\Omega$
$C_L$	load capacitance		-	10	-	pF
$P_{o(xtal)}$	crystal output power		-	-	100	$\mu\text{W}$

[1] This requirement is according to FCC regulations requirements. To meet only ISO/IEC 14443 and ISO/IEC 18092, then  $\pm 14\text{ kHz}$  apply.

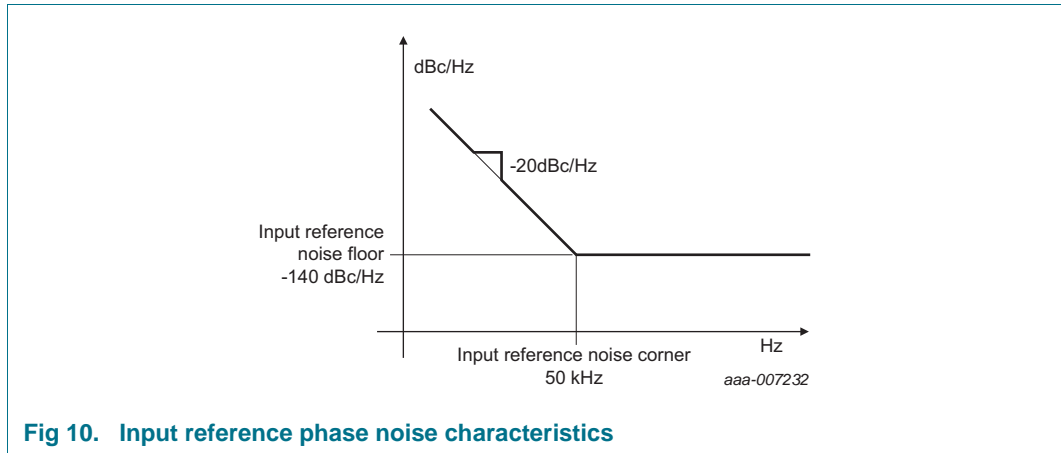
10.4.2 Integrated PLL to make use of external clock

When enabled, the PLL is designed to generate a low noise 27.12 MHz for an input clock 13 MHz, 19.2 MHz, 24 MHz, 26 MHz, 38.4 MHz and 52 MHz.

The 27.12 MHz of the PLL is used as the time reference for the RF front end when PN7120 is behaving in Reader mode or NFC Initiator as well as in NFC Target when configured in Active communication mode.

The input clock on XTAL1 shall comply with the following phase noise requirements for the following input frequency: 13 MHz, 19.2 MHz, 24 MHz, 26 MHz, 38.4 MHz and 52 MHz:





This phase noise is equivalent to an RMS jitter of 6.23 ps from 10 Hz to 1 MHz. For configuration of input frequency, refer to [Ref. 8](#). There are 6 pre programmed and validated frequencies for the PLL: 13 MHz, 19.2 MHz, 24 MHz, 26 MHz, 38.4 MHz and 52 MHz.

**Table 13. PLL input requirements**

*Coupling: single-ended, AC coupling;*

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
f <sub>clk</sub>	clock frequency	ISO/IEC and FCC compliancy	-	13	-	MHz
			-	19.2	-	MHz
			-	24	-	MHz
			-	26	-	MHz
			-	38.4	-	MHz
			-	52	-	MHz
f <sub>i(ref)acc</sub>	reference input frequency accuracy	full operating range; frequencies typical values: 13 MHz, 26 MHz and 52 MHz <sup>[1]</sup>	-25	-	+25	ppm
		full operating range; frequencies typical values: 19.2 MHz, 24 MHz and 38.4 MHz <sup>[1]</sup>	-50	-	+50	ppm
φ <sub>n</sub>	phase noise	input noise floor at 50 kHz	-140	-	-	dB/Hz
<b>Sinusoidal shape</b>						
V <sub>i(p-p)</sub>	peak-to-peak input voltage		0.2	-	1.8	V
V <sub>i(clk)</sub>	clock input voltage		0	-	1.8	V
<b>Square shape</b>						
V <sub>i(clk)</sub>	clock input voltage		0	-	1.8 ± 10 %	V

[1] This requirement is according to FCC regulations requirements. To meet only ISO/IEC 14443 and ISO/IEC 18092, then ± 400 ppm limits apply.

For detailed description of clock request mechanisms, refer to [Ref. 4](#) and [Ref. 5](#).

**10.4.3 Low-power 20 MHz oscillator**

Low-power 20 MHz oscillator is used as system clock of the system.

**10.4.4 Low-power 380 kHz oscillator**

A Low Frequency Oscillator (LFO) is implemented to drive a counter (WUC) waking-up PN7120 from Standby state. This allows implementation of low-power reader polling loop at application level. Moreover, this 380 kHz is used as the reference clock for write access to EEPROM memory.

**10.5 Power concept**

**10.5.1 PMU functional description**

The Power Management Unit of PN7120 generates internal supplies required by PN7120 out of  $V_{BAT}$  input supply voltage:

- $V_{DD}$ : internal supply voltage
- $V_{DD(TX)}$ : output supply voltage for the RF transmitter

The [Figure 11](#) describes the main blocks available in PMU:

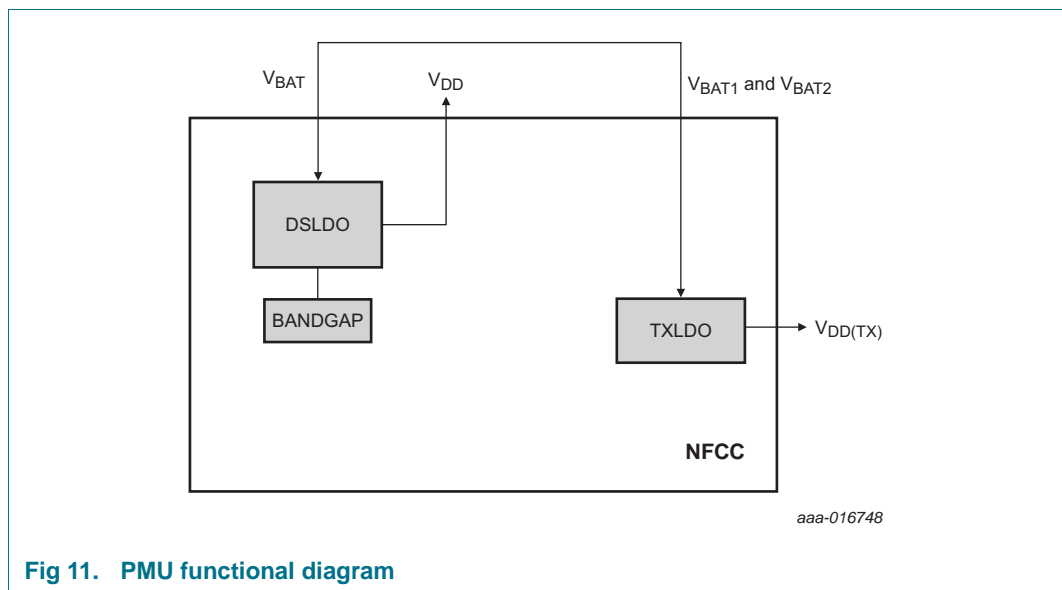


Fig 11. PMU functional diagram

**10.5.2 DSLDO: Dual Supply LDO**

The input pin of the DSLDO is  $V_{BAT}$ .

The Low drop-out regulator provides  $V_{DD}$  required in PN7120.

**10.5.3 TXLDO**

This is the LDO which generates the transmitter voltage.

The value of  $V_{DD(TX)}$  is configured at  $3.1\text{ V} \pm 0.2\text{ V}$ .

$V_{DD(TX)}$  value is given according to the minimum targeted  $V_{BAT}$  value for which Reader mode shall work.

For  $V_{BAT}$  above 3.1 V,  $V_{DD(TX)} = 3.1$  V:

$$V_{BAT} \geq 3.1V \Rightarrow V_{DD(TX)} = 3.1V$$

$$3.1V > V_{BAT} \geq 2.3V \Rightarrow V_{DD(TX)} = V_{BAT}$$

In Standby state,  $V_{DD(TX)}$  is around 2.5 V with some ripples; it toggles between 2.35 V to 2.65 V with a period which depends on the capacitance and load on  $V_{DD(TX)}$ .

Figure 12 shows  $V_{DD(TX)}$  behavior for 3.1 V:

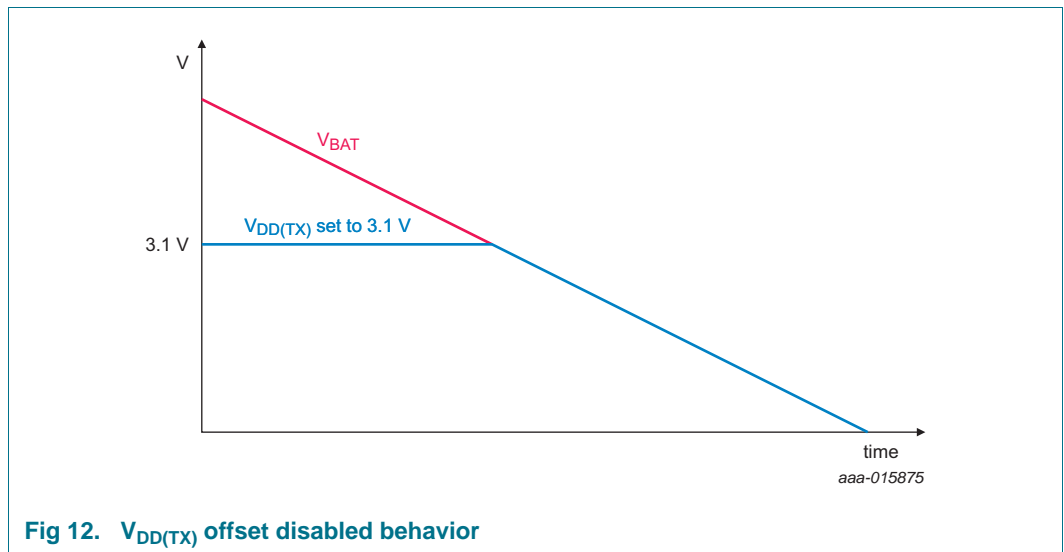


Fig 12.  $V_{DD(TX)}$  offset disabled behavior

Figure 13 shows the case where the PN7120 is in Standby state:

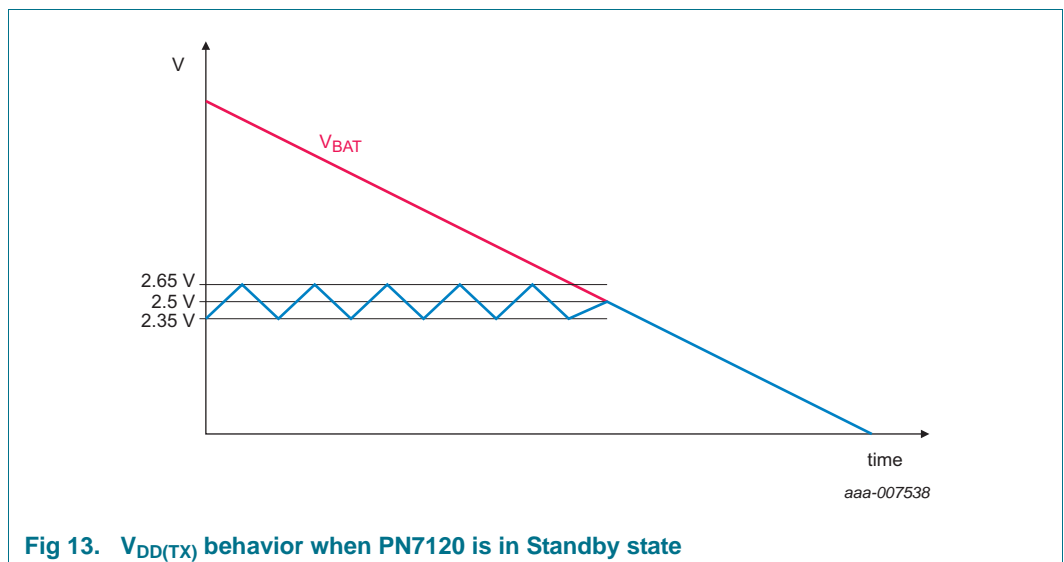


Fig 13.  $V_{DD(TX)}$  behavior when PN7120 is in Standby state

### 10.5.3.1 TXLDO limiter

The TXLDO includes a current limiter to avoid too high current within TX1, TX2 when in reader or initiator modes.

The current limiter block compares an image of the TXLDO output current to a reference. Once the reference is reached, the output current gets limited which is equivalent to a typical output current of 220 mA whatever  $V_{BAT} = 2.7\text{ V}$  and 180 mA for  $V_{BAT} = 3.1\text{ V}$ .

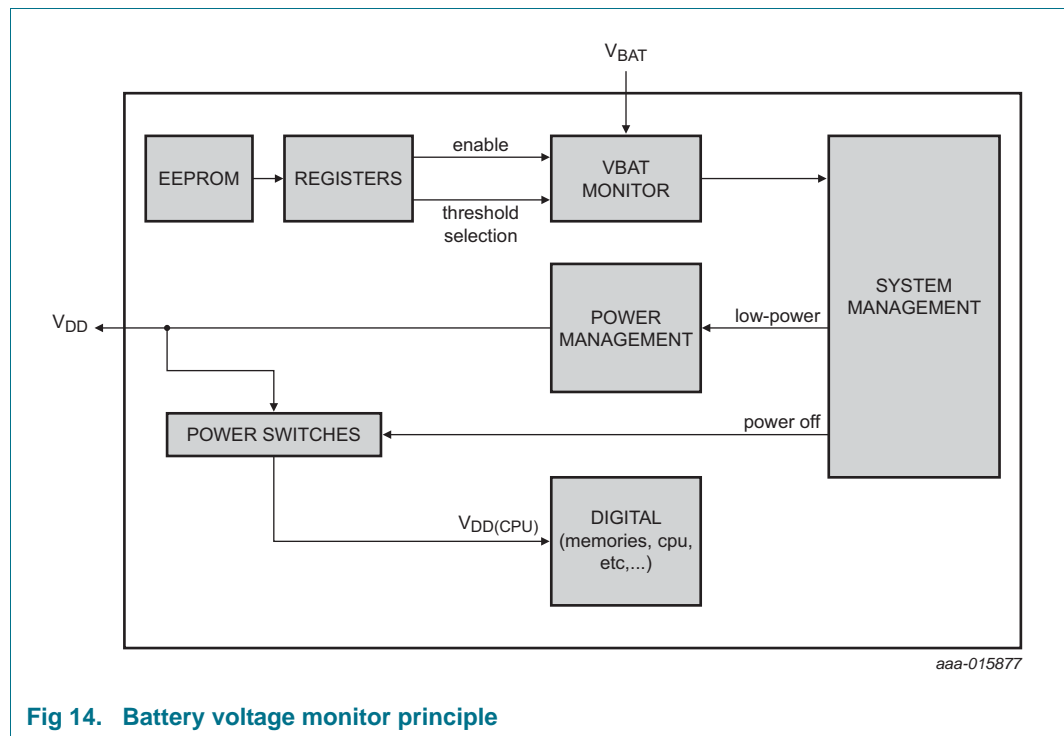
**10.5.4 Battery voltage monitor**

The PN7120 features low-power  $V_{BAT}$  voltage monitor which protects the host device battery from being discharged below critical levels. When  $V_{BAT}$  voltage goes below  $V_{BATcritical}$  threshold, then the PN7120 goes in Monitor state. Refer to [Figure 14](#) for principle schematic of the battery monitor.

The battery voltage monitor is enabled via an EEPROM setting.

The  $V_{BATcritical}$  threshold can be configured to 2.3 V or 2.75 V by an EEPROM setting.

At the first start-up,  $V_{BAT}$  voltage monitor functionality is OFF and then enabled if properly configured in EEPROM. The PN7120 monitors battery voltage continuously.



**Fig 14. Battery voltage monitor principle**

The value of the critical level can be configured to 2.3 V or 2.75 V by an EEPROM setting. This value has a typical hysteresis around 150 mV.

**10.6 Reset concept**

**10.6.1 Resetting PN7120**

To enter reset there are 2 ways:

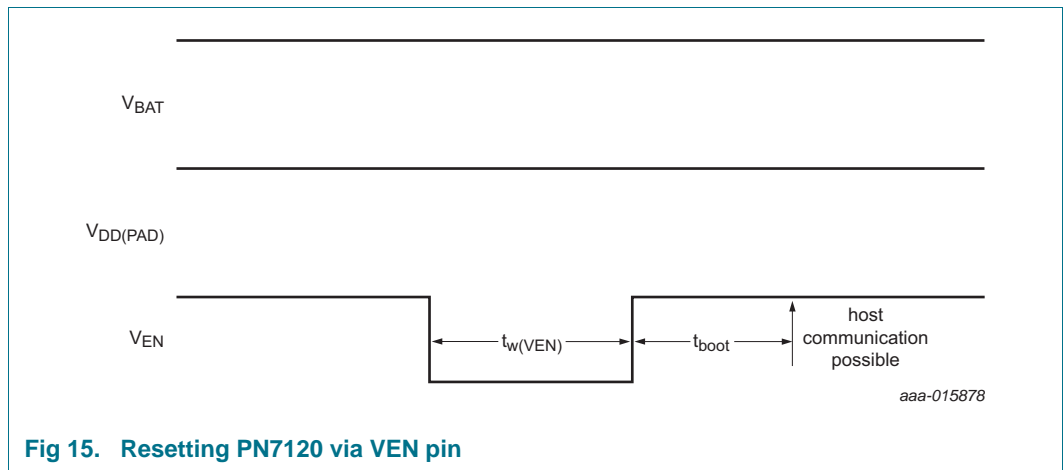
- Pulling VEN voltage low (Hard Power Down state)
- if  $V_{BAT}$  monitor is enabled: lowering  $V_{BAT}$  below the monitor threshold (Monitor state, if VEN voltage is kept above 1.1 V)

Reset means resetting the embedded FW execution and the registers values to their default values. Part of these default values is defined from EEPROM data loaded values, others are hardware defined. See [Ref. 4](#) to know which ones are accessible to tune PN7120 to the application environment.

To get out of reset:

- Pulling VEN voltage high with  $V_{BAT}$  above  $V_{BAT}$  monitor threshold if enabled

[Figure 15](#) shows reset done via VEN pin.



See [Section 15.2.2](#) for the timings values.

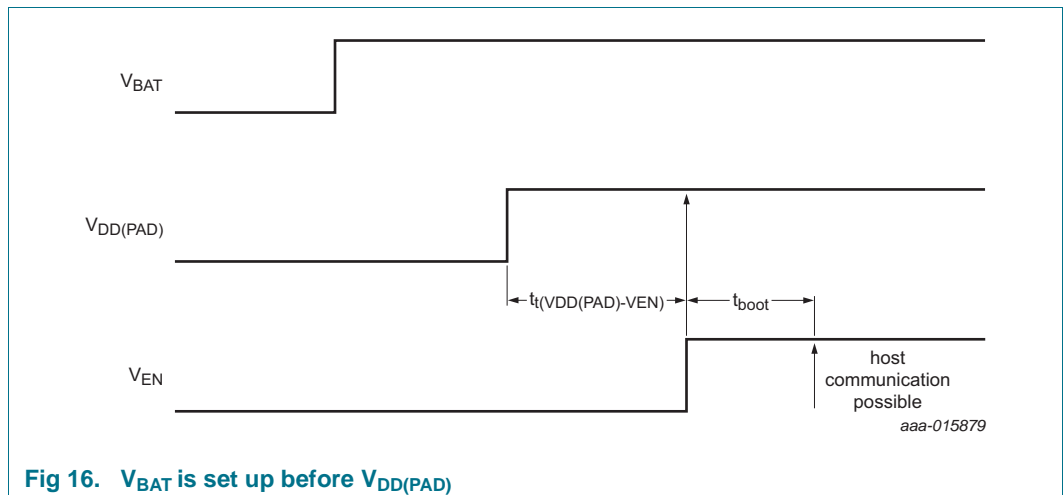
### 10.6.2 Power-up sequences

There are 2 different supplies for PN7120. PN7120 allows these supplies to be set up independently, therefore different power-up sequences have to be considered.

#### 10.6.2.1 $V_{BAT}$ is set up before $V_{DD(PAD)}$

This is at least the case when  $V_{BAT}$  pin is directly connected to the battery and when PN7120  $V_{BAT}$  is always supplied as soon the system is supplied.

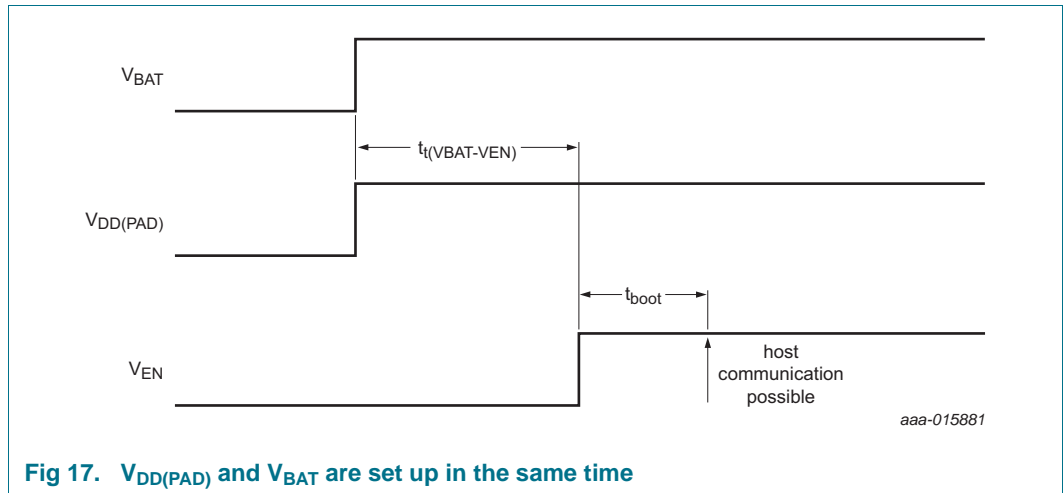
As VEN pin is referred to  $V_{BAT}$  pin, VEN voltage shall go high after  $V_{BAT}$  has been set.



See [Section 15.2.3](#) for the timings values.

**10.6.2.2  $V_{DD(PAD)}$  and  $V_{BAT}$  are set up in the same time**

It is at least the case when  $V_{BAT}$  pin is connected to a PMU/regulator which also supply  $V_{DD(PAD)}$ .



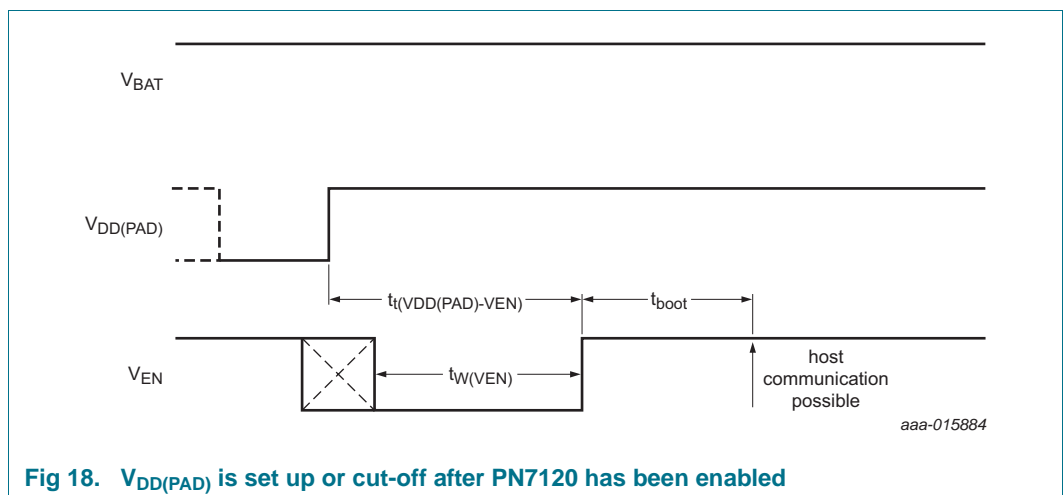
**Fig 17.  $V_{DD(PAD)}$  and  $V_{BAT}$  are set up in the same time**

See [Section 15.2.3](#) for the timings values.

**10.6.2.3 PN7120 has been enabled before  $V_{DD(PAD)}$  is set up or before  $V_{DD(PAD)}$  has been cut off**

This can be the case when  $V_{BAT}$  pin is directly connected to the battery and when  $V_{DD(PAD)}$  is generated from a PMU. When the battery voltage is too low, then the PMU might no more be able to generate  $V_{DD(PAD)}$ . When the device gets charged again, then  $V_{DD(PAD)}$  is set up again.

As the pins to select the interface are biased from  $V_{DD(PAD)}$ , when  $V_{DD(PAD)}$  disappears the pins might not be correctly biased internally and the information might be lost. Therefore it is required to make the IC boot after  $V_{DD(PAD)}$  is set up again.



**Fig 18.  $V_{DD(PAD)}$  is set up or cut-off after PN7120 has been enabled**

See [Section 15.2.3](#) for the timings values.

### 10.6.3 Power-down sequence

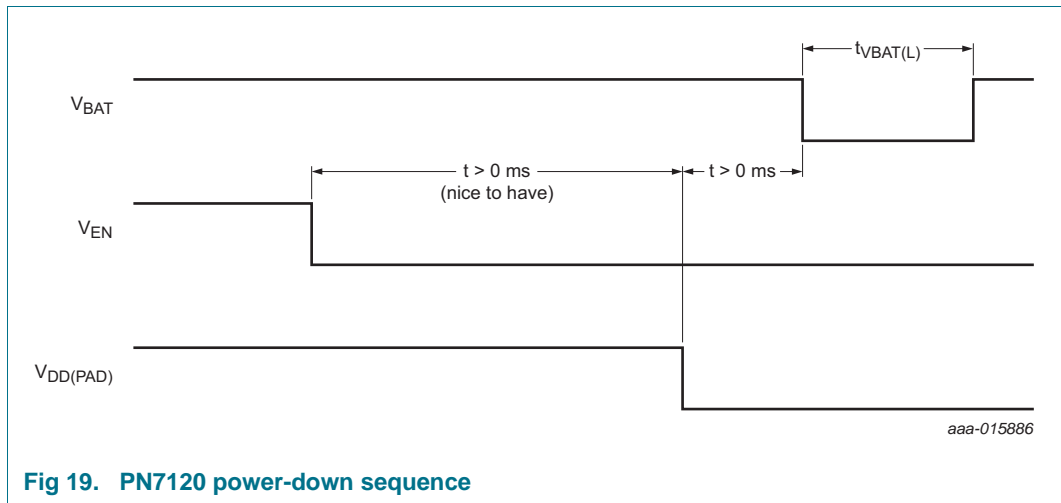


Fig 19. PN7120 power-down sequence

## 10.7 Contactless Interface Unit

PN7120 supports various communication modes at different transfer speeds and modulation schemes. The following chapters give more detailed overview of selected communication modes.

**Remark:** all indicated modulation index and modes in this chapter are system parameters. This means that beside the IC settings a suitable antenna tuning is required to achieve the optimum performance.

### 10.7.1 Reader/Writer communication modes

Generally 5 Reader/Writer communication modes are supported:

- PCD Reader/Writer for ISO/IEC 14443A/MIFARE
- PCD Reader/Writer for Jewel/Topaz tags
- PCD Reader/Writer for FeliCa cards
- PCD Reader/Writer for ISO/IEC 14443B
- VCD Reader/Writer for ISO/IEC 15693/ICODE

#### 10.7.1.1 ISO/IEC 14443A/MIFARE and Jewel/Topaz PCD communication mode

The ISO/IEC 14443A/MIFARE PCD communication mode is the general reader to card communication scheme according to the ISO/IEC 14443A specification. This modulation scheme is as well used for communications with Jewel/Topaz cards.

[Figure 20](#) describes the communication on a physical level, the communication table describes the physical parameters (the numbers take the antenna effect on modulation depth for higher data rates).

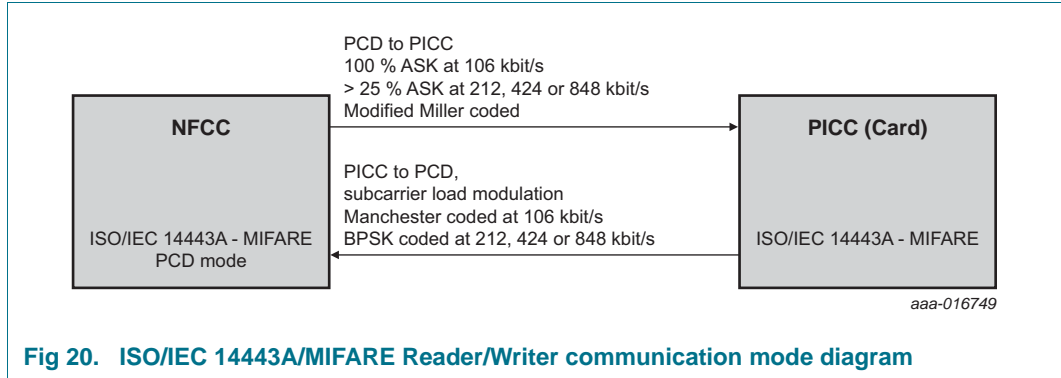


Fig 20. ISO/IEC 14443A/MIFARE Reader/Writer communication mode diagram

Table 14. Overview for ISO/IEC 14443A/MIFARE Reader/Writer communication mode

Communication direction		ISO/IEC 14443A/ MIFARE/ Jewel/ Topaz	ISO/IEC 14443A higher transfer speeds			
		Transfer speed	106 kbit/s	212 kbit/s	424 kbit/s	848 kbit/s
		Bit length	(128/13.56) μs	(64/13.56) μs	(32/13.56) μs	(16/13.56) μs
<b>PN7120 → PICC</b>						
(data sent by PN7120 to a card)	modulation on PN7120 side	100 % ASK	> 25 % ASK	> 25 % ASK	> 25 % ASK	
	bit coding	Modified Miller	Modified Miller	Modified Miller	Modified Miller	
<b>PICC → PN7120</b>						
(data received by PN7120 from a card)	modulation on PICC side	subcarrier load modulation	subcarrier load modulation	subcarrier load modulation	subcarrier load modulation	
	subcarrier frequency	13.56 MHz/16	13.56 MHz/16	13.56 MHz/16	13.56 MHz/16	
	bit coding	Manchester	BPSK	BPSK	BPSK	

The contactless coprocessor and the on-chip CPU of PN7120 handle the complete ISO/IEC 14443A/MIFARE RF-protocol, nevertheless a dedicated external host has to handle the application layer communication.

10.7.1.2 FeliCa PCD communication mode

The FeliCa communication mode is the general Reader/Writer to card communication scheme according to the FeliCa specification. Figure 21 describes the communication on a physical level, the communication overview describes the physical parameters.

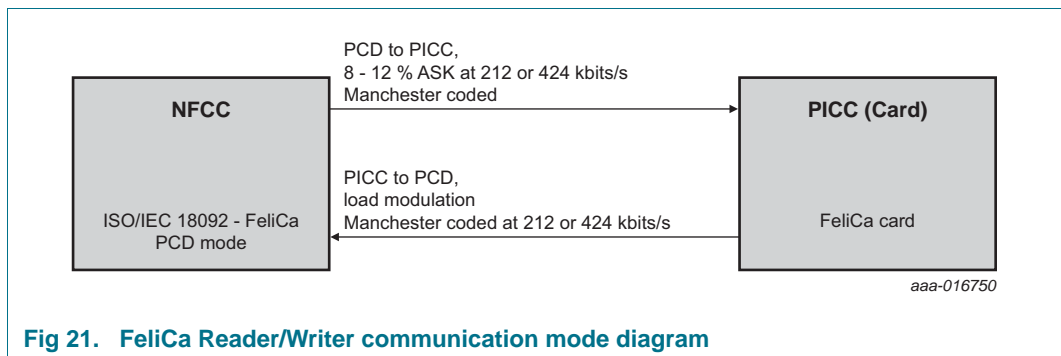


Fig 21. FeliCa Reader/Writer communication mode diagram



Table 15. Overview for FeliCa Reader/Writer communication mode

Communication direction	FeliCa		FeliCa higher transfer speeds	
	Transfer speed	212 kbit/s	424 kbit/s	
	Bit length	(64/13.56) μs	(32/13.56) μs	
<b>PN7120 → PICC</b>				
(data sent by PN7120 to a card)	modulation on PN7120 side	8 % – 12 % ASK	8 % – 12 % ASK	
	bit coding	Manchester	Manchester	
<b>PICC → PN7120</b>				
(data received by PN7120 from a card)	modulation on PICC side	load modulation	load modulation	
	subcarrier frequency	no subcarrier	no subcarrier	
	bit coding	Manchester	Manchester	

The contactless coprocessor of PN7120 and the on-chip CPU handle the FeliCa protocol. Nevertheless a dedicated external host has to handle the application layer communication.

10.7.1.3 ISO/IEC 14443B PCD communication mode

The ISO/IEC 14443B PCD communication mode is the general reader to card communication scheme according to the ISO/IEC 14443B specification. Figure 22 describes the communication on a physical level, the communication table describes the physical parameters.

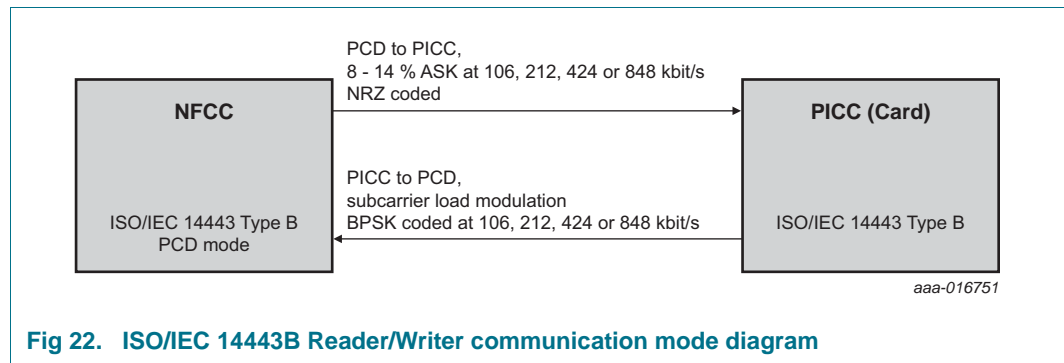


Fig 22. ISO/IEC 14443B Reader/Writer communication mode diagram

Table 16. Overview for ISO/IEC 14443B Reader/Writer communication mode

Communication direction	ISO/IEC 14443B		ISO/IEC 14443B higher transfer speeds		
	Transfer speed	106 kbit/s	212 kbit/s	424 kbit/s	848 kbit/s
	Bit length	(128/13.56) μs	(64/13.56) μs	(32/13.56) μs	(16/13.56) μs
<b>PN7120 → PICC</b>					
(data sent by PN7120 to a card)	modulation on PN7120 side	8 % – 14 % ASK	8 % – 14 % ASK	8 % – 14 % ASK	8 % – 14 % ASK
	bit coding	NRZ	NRZ	NRZ	NRZ
<b>PICC → PN7120</b>					

Table 16. Overview for ISO/IEC 14443B Reader/Writer communication mode ...continued

Communication direction		ISO/IEC 14443B higher transfer speeds			
	Transfer speed	106 kbit/s	212 kbit/s	424 kbit/s	848 kbit/s
	Bit length	(128/13.56) $\mu$ s	(64/13.56) $\mu$ s	(32/13.56) $\mu$ s	(16/13.56) $\mu$ s
(data received by PN7120 from a card)	modulation on PICC side	subcarrier load modulation	subcarrier load modulation	subcarrier load modulation	subcarrier load modulation
	subcarrier frequency	13.56 MHz/16	13.56 MHz/16	13.56 MHz/16	13.56 MHz/16
	bit coding	BPSK	BPSK	BPSK	BPSK

The contactless coprocessor and the on-chip CPU of PN7120 handles the complete ISO/IEC 14443B RF-protocol, nevertheless a dedicated external host has to handle the application layer communication.

10.7.1.4 ISO/IEC 15693 VCD communication mode

The ISO/IEC 15693 VCD Reader/Writer communication mode is the general reader to card communication scheme according to the ISO/IEC 15693 specification. PN7120 will communicate with VICC using only the higher data rates of the VICC (26.48 kbit/s with single subcarrier and 26.69 kbit/s with dual subcarrier).

PN7120 supports the commands as defined by the ETSI HCI (see Ref. 1) and on top offers the inventory of the tags (anticollision sequence) on its own.

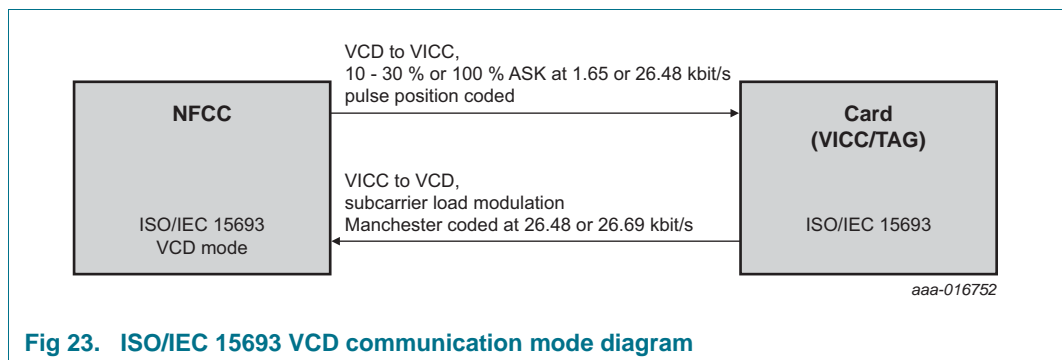


Fig 23. ISO/IEC 15693 VCD communication mode diagram

Figure 23 shows the communication schemes used.

2 communication schemes can be used from card to PN7120 and 2 communication schemes can be used from PN7120 to card.

Thus, 4 communication schemes are possible.

Table 17. Overview for ISO/IEC 15693 VCD communication mode

Communication direction			
<b>PN7120 → VICC</b>			
(data sent by PN7120 to a tag)	transfer speed	1.65 kbit/s	26.48 kbit/s
	bit length	(8192/13.56) $\mu$ s	(512/13.56) $\mu$ s
	modulation on PN7120 side	10 % – 30 % or 100 % ASK	10 % – 30 % or 100 % ASK
	bit coding	pulse position modulation 1 out of 256 mode	pulse position modulation 1 out of 4 mode

Table 17. Overview for ISO/IEC 15693 VCD communication mode ...continued

Communication direction			
<b>VICC → PN7120</b>			
(data received by PN7120 from a tag)	transfer speed	26.48 kbit/s	26.69 kbit/s
	bit length	(512/13.56) μs	(508/13.56) μs
	modulation on VICC side	subcarrier load modulation	subcarrier load modulation
	subcarrier frequency	single subcarrier	dual subcarrier
	bit coding	Manchester	Manchester

**10.7.2 ISO/IEC 18092, Ecma 340 NFCIP-1 communication modes**

An NFCIP-1 communication takes place between 2 devices:

- NFC Initiator: generates RF field at 13.56 MHz and starts the NFCIP-1 communication.
- NFC Target: responds to NFC Initiator command either in a load modulation scheme in Passive communication mode or using a self-generated and self-modulated RF field for Active communication mode.

The NFCIP-1 communication differentiates between Active and Passive communication modes.

- Active communication mode means both the NFC Initiator and the NFC Target are using their own RF field to transmit data
- Passive communication mode means that the NFC Target answers to an NFC Initiator command in a load modulation scheme. The NFC Initiator is active in terms of generating the RF field.

PN7120 supports the Active Target, Active Initiator, Passive Target and Passive Initiator communication modes at the transfer speeds 106 kbit/s, 212 kbit/s and 424 kbit/s as defined in the NFCIP-1 standard.

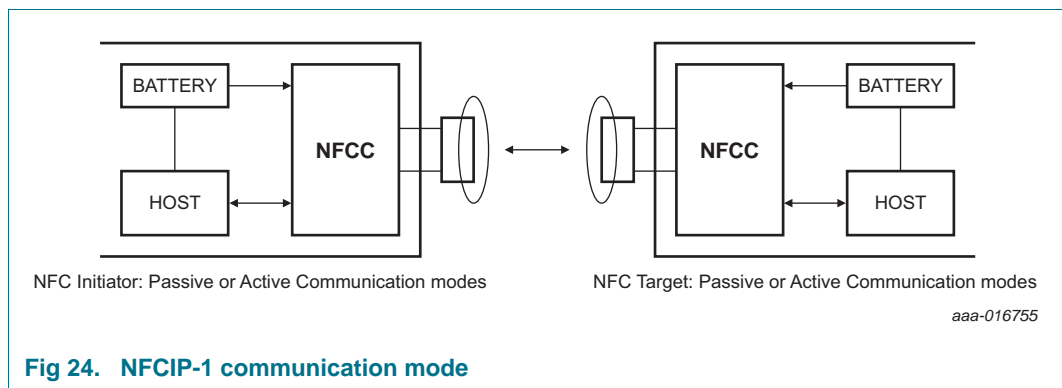


Fig 24. NFCIP-1 communication mode

Nevertheless a dedicated external host has to handle the application layer communication.

**10.7.2.1 ACTIVE communication mode**

Active communication mode means both the NFC Initiator and the NFC Target are using their own RF field to transmit data.

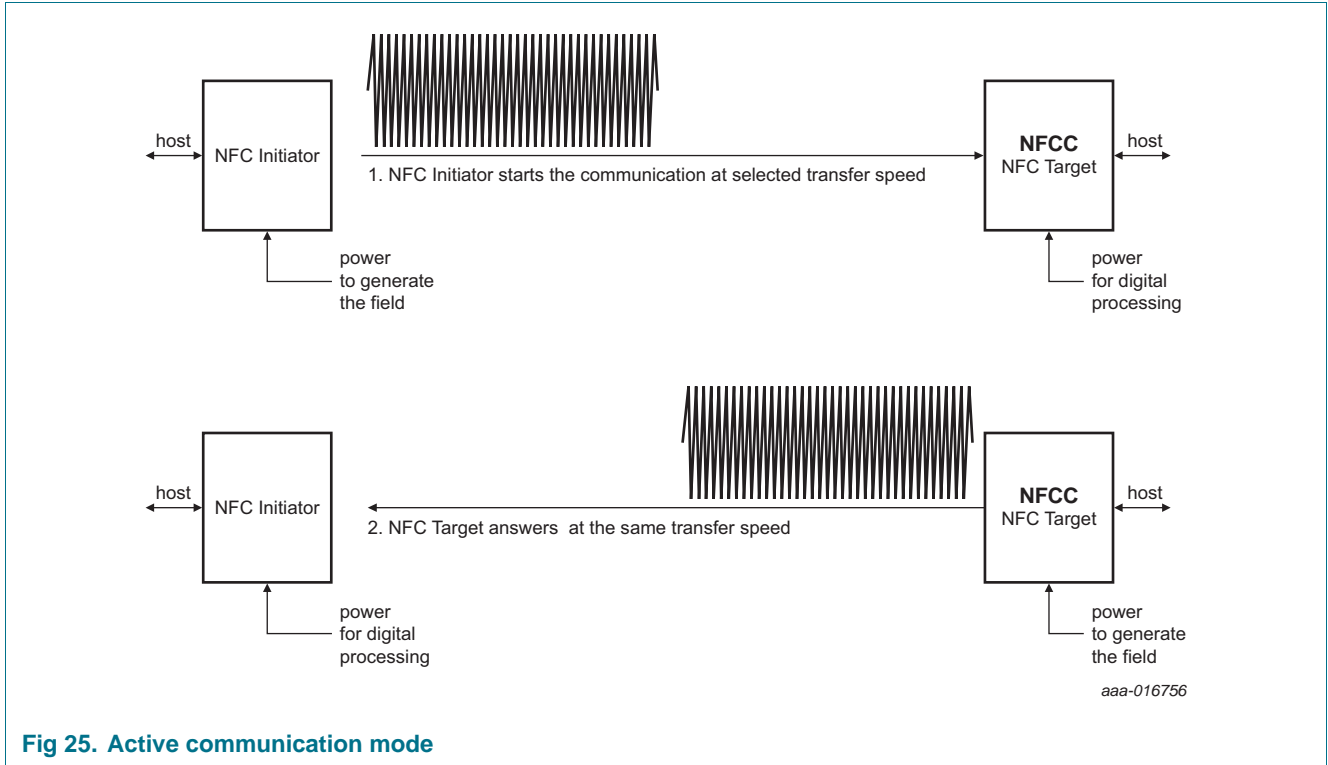


Fig 25. Active communication mode

The following table gives an overview of the Active communication modes:

Table 18. Overview for Active communication mode

Communication direction	ISO/IEC 18092, Ecma 340, NFCIP-1			
	Baud rate	106 kbit/s	212 kbit/s	424 kbit/s
	Bit length	(128/13.56) μs	(64/13.56) μs	(32/13.56) μs
<b>NFC Initiator to NFC Target</b>				
	modulation	100 % ASK	8 % – 30 % ASK <sup>[1]</sup>	8 % – 30 % ASK <sup>[1]</sup>
	bit coding	Modified Miller	Manchester	Manchester
<b>NFC Target to NFC Initiator</b>				
	modulation	100 % ASK	8 % – 30 % ASK <sup>[1]</sup>	8 % – 30 % ASK <sup>[1]</sup>
	bit coding	Miller	Manchester	Manchester

[1] This modulation index range is according to NFCIP-1 standard. It might be that some NFC forum type 3 cards does not withstand the full range as based on FeliCa range which is narrow (8 % to 14 % ASK). To adjust the index, see [Ref. 6](#).

10.7.2.2 Passive communication mode

Passive communication mode means that the NFC Target answers to an NFC Initiator command in a load modulation scheme.

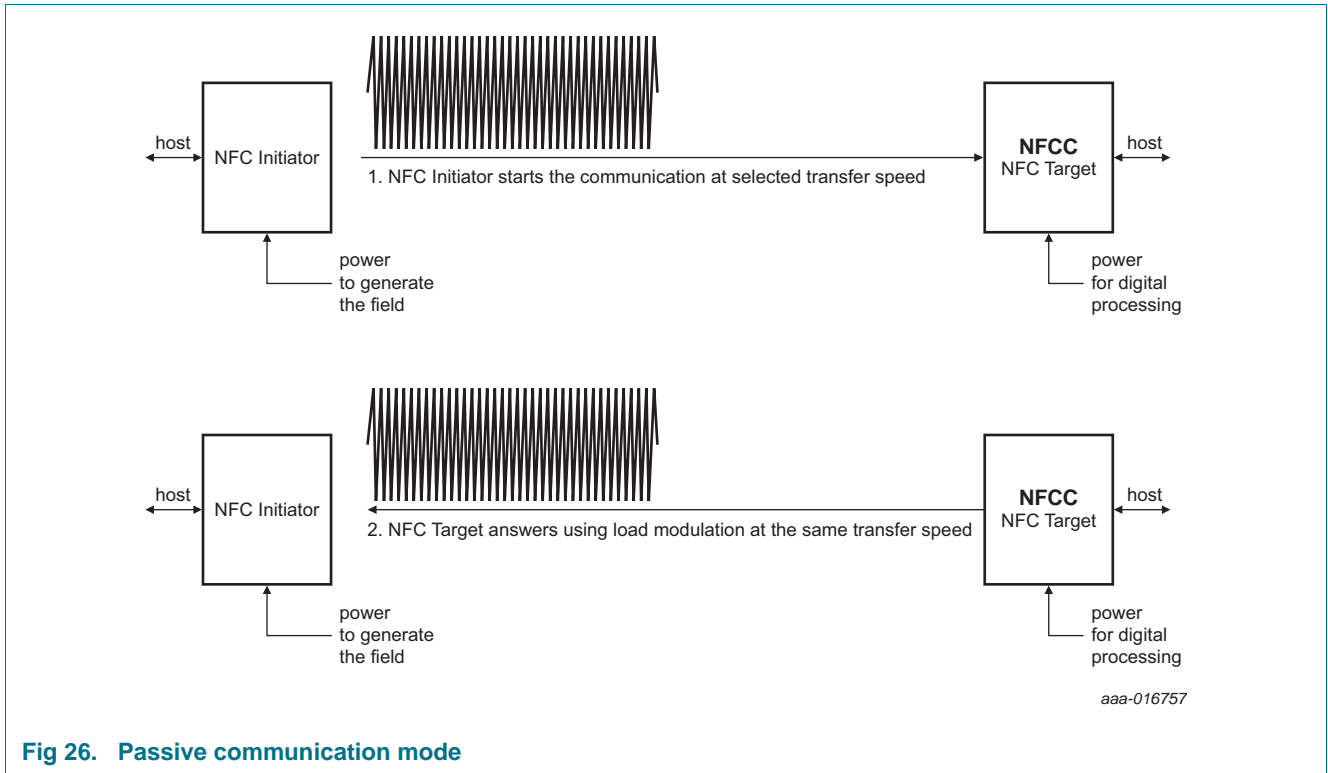


Fig 26. Passive communication mode

Table 19 gives an overview of the Passive communication modes:

Table 19. Overview for Passive communication mode

Communication direction	ISO/IEC 18092, Ecma 340, NFCIP-1			
	Baud rate	106 kbit/s	212 kbit/s	424 kbit/s
	Bit length	(128/13.56) μs	(64/13.56) μs	(32/13.56) μs
<b>NFC Initiator to NFC Target</b>				
	modulation	100 % ASK	8 % – 30 % ASK <sup>[1]</sup>	8 % – 30 % ASK <sup>[1]</sup>
	bit coding	Modified Miller	Manchester	Manchester
<b>NFC Target to NFC Initiator</b>				
	modulation	subcarrier load modulation	load modulation	load modulation
	subcarrier frequency	13.56 MHz/16	no subcarrier	no subcarrier
	bit coding	Manchester	Manchester	Manchester

[1] This modulation index range is according to NFCIP-1 standard. It might be that some NFC forum type 3 cards does not withstand the full range as based on FeliCa range which is narrow (8 % to 14 % ASK). To adjust the index, see Ref. 6.

**10.7.2.3 NFCIP-1 framing and coding**

The NFCIP-1 framing and coding in Active and Passive communication modes are defined in the NFCIP-1 standard: ISO/IEC 18092 or Ecma 340.

**10.7.2.4 NFCIP-1 protocol support**

The NFCIP-1 protocol is not completely described in this document. For detailed explanation of the protocol, refer to the ISO/IEC 18092 or Ecma 340 NFCIP-1 standard. However the datalink layer is according to the following policy:

- Transaction includes initialization, anticollision methods and data transfer. This sequence must not be interrupted by another transaction
- PSL shall be used to change the speed between the target selection and the data transfer, but the speed should not be changed during a data transfer

### 10.7.3 Card communication modes

PN7120 can be addressed as a ISO/IEC 14443A or ISO/IEC 14443B cards. This means that PN7120 can generate an answer in a load modulation scheme according to the ISO/IEC 14443A or ISO/IEC 14443B interface description.

**Remark:** PN7120 does not support a complete card protocol. This has to be handled by the host controller.

[Table 20](#) and [Table 21](#) describe the physical parameters.

#### 10.7.3.1 ISO/IEC 14443A/MIFARE card communication mode

**Table 20. Overview for ISO/IEC 14443A/MIFARE card communication mode**

Communication direction		ISO/IEC 14443A	ISO/IEC 14443A higher transfer speeds	
	Transfer speed	106 kbit/s	212 kbit/s	424 kbit/s
	Bit length	(128/13.56) $\mu$ s	(64/13.56) $\mu$ s	(32/13.56) $\mu$ s
<b>PCD <math>\rightarrow</math> PN7120</b>				
(data received by PN7120 from a card)	modulation on PCD side	100 % ASK	> 25 % ASK	> 25 % ASK
	bit coding	Modified Miller	Modified Miller	Modified Miller
<b>PN7120 <math>\rightarrow</math> PCD</b>				
(data sent by PN7120 to a card)	modulation on PN7120 side	subcarrier load modulation	subcarrier load modulation	subcarrier load modulation
	subcarrier frequency	13.56 MHz/16	13.56 MHz/16	13.56 MHz/16
	bit coding	Manchester	BPSK	BPSK

#### 10.7.3.2 ISO/IEC 14443B card communication mode

**Table 21. Overview for ISO/IEC 14443B card communication mode**

Communication direction		ISO/IEC 14443B	ISO/IEC 14443B higher transfer speeds	
	Transfer speed	106 kbit/s	212 kbit/s	424 kbit/s
	Bit length	(128/13.56) $\mu$ s	(64/13.56) $\mu$ s	(32/13.56) $\mu$ s
<b>PCD <math>\rightarrow</math> PN7120</b>				
(data received by PN7120 from a Reader)	modulation on PCD side	8 % – 14 % ASK	8 % – 14 % ASK	8 % – 14 % ASK
	bit coding	NRZ	NRZ	NRZ
<b>PN7120 <math>\rightarrow</math> PCD</b>				
(data sent by PN7120 to a Reader)	modulation on PN7120 side	subcarrier load modulation	subcarrier load modulation	subcarrier load modulation
	subcarrier frequency	13.56 MHz/16	13.56 MHz/16	13.56 MHz/16
	bit coding	BPSK	BPSK	BPSK

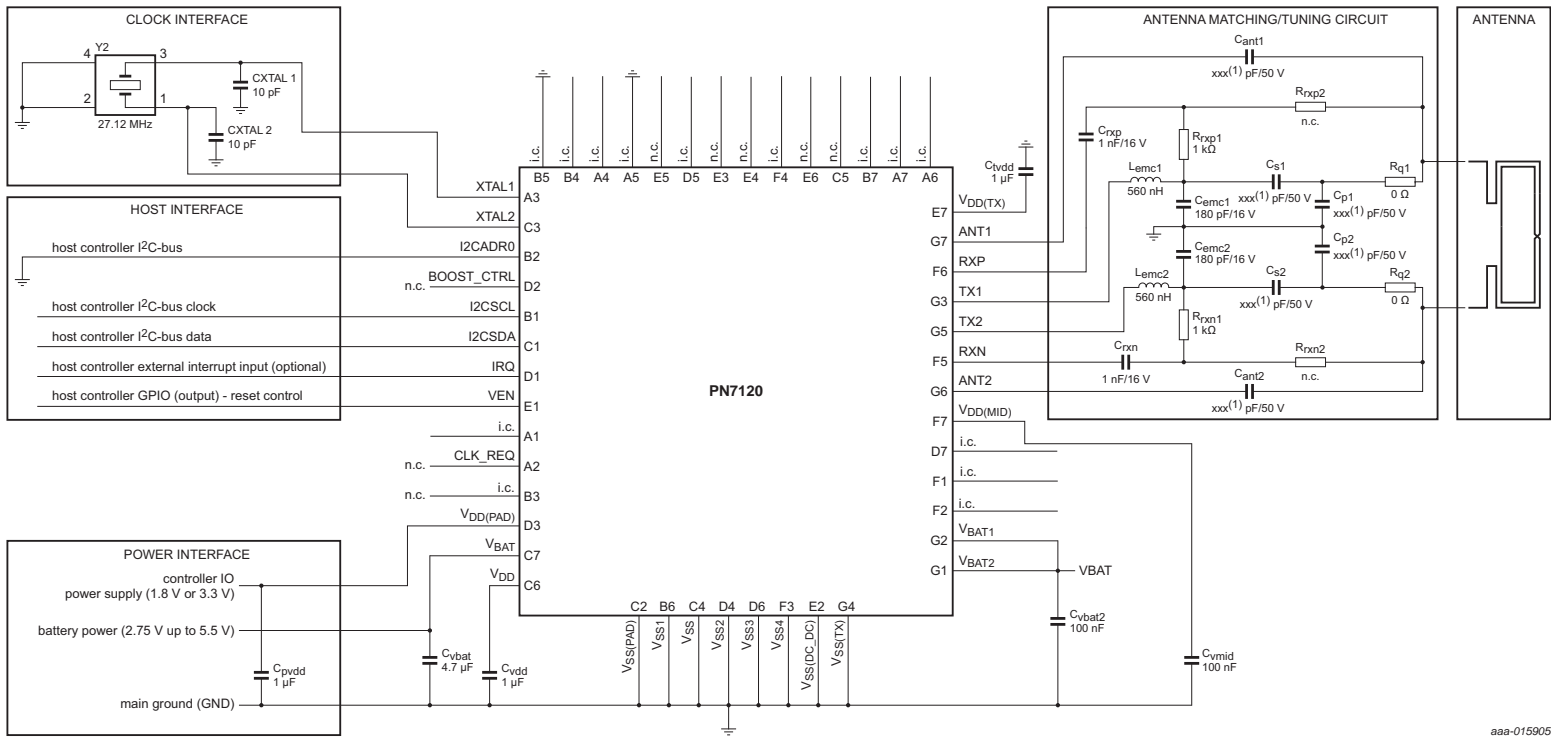
#### 10.7.4 Frequency interoperability

When in communication, PN7120 is generating some RF frequencies. PN7120 is also sensitive to some RF signals as it is looking for data in the field.

In order to avoid interference with other RF communication, it is required to tune the antenna and design the board according to [Ref. 5](#).

Although ISO/IEC 14443 and ISO/IEC 18092/Ecma 340 allows an RF frequency of  $13.56 \text{ MHz} \pm 7 \text{ kHz}$ , FCC regulation does not allow this wide spread and limits the dispersion to  $\pm 50 \text{ ppm}$ , which is in line with PN7120 capability.

# 11. Application design-in information



(1) xxx: customer antenna matching tuning.

Fig 27. Application schematic

aaa-015905



## 12. Limiting values

**Table 22. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD(PAD)</sub>	V <sub>DD(PAD)</sub> supply voltage	supply voltage for host interface	-	4.2	V
V <sub>BAT</sub>	battery supply voltage		-	6	V
V <sub>ESD</sub>	electrostatic discharge voltage	HBM; 1500 Ω, 100 pF; EIA/JESD22-A114-D	-	1.5	kV
		CDM; field induced model; EIA/JESD22-C101-C	-	500	V
T <sub>stg</sub>	storage temperature		-55	+150	°C
P <sub>tot</sub>	total power dissipation	all modes <a href="#">[1]</a>	-	0.55	W
V <sub>RXN(i)</sub>	RXN input voltage		0	2.5	V
V <sub>RXP(i)</sub>	RXP input voltage		0	2.5	V

[1] The design of the solution shall be done so that for the different use cases targeted the power to be dissipated from the field or generated by PN7120 does not exceed this value.

## 13. Recommended operating conditions

**Table 23. Operating conditions**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
T <sub>amb</sub>	ambient temperature	JEDEC PCB-0.5	-30	+25	+85	°C
V <sub>BAT</sub>	battery supply voltage	battery monitor enabled; <a href="#">[1]</a> V <sub>SS</sub> = 0 V	2.3	-	5.5	V
		Card Emulation and Passive Target; <a href="#">[1]</a> <a href="#">[2]</a> V <sub>SS</sub> = 0 V	2.3	-	5.5	V
		Reader, Active Initiator and Active Target; <a href="#">[1]</a> <a href="#">[2]</a> V <sub>SS</sub> = 0 V	2.7	-	5.5	V
V <sub>DD</sub>	supply voltage		1.65	1.8	1.95	V
V <sub>DD(PAD)</sub>	V <sub>DD(PAD)</sub> supply voltage	supply voltage for host interface				
		1.8 V host supply; V <sub>SS</sub> = 0 V <a href="#">[1]</a>	1.65	1.8	1.95	V
		3 V host supply; V <sub>SS</sub> = 0 V <a href="#">[1]</a>	3.0	-	3.6	V
P <sub>tot</sub>	total power dissipation	Reader; I <sub>VDD(TX)</sub> = 100 mA; V <sub>BAT</sub> = 5.5 V	-	-	0.5	W
I <sub>O(VDDTX)</sub>	output current on pin V <sub>DD(TX)</sub>	<a href="#">[2]</a>	-	-	100	mA

Table 23. Operating conditions ...continued

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I <sub>BAT</sub>	battery supply current	in Hard Power Down state; V <sub>BAT</sub> = 3.6 V; T = 25 °C	-	10	12	μA
		in Standby state; V <sub>BAT</sub> = 3.6 V; T = 25 °C	-	-	20	μA
		in Monitor state; V <sub>BAT</sub> = 2.75 V; T = 25 °C	-	-	12	μA
		in low-power polling loop; V <sub>BAT</sub> = 3.6 V; T = 25 °C; loop time = 500 ms	-	150	-	μA
I <sub>VBAT(tot)</sub>	total supply current on V <sub>BAT</sub>	PCD mode at typical 3 V [3]	-	-	170	mA
I <sub>th(lim)</sub>	current limit threshold current	current limiter on V <sub>DD(TX)</sub> pin; V <sub>DD(TX)</sub> = 3.1 V [4]	-	180	-	mA

[1] V<sub>SS</sub> represents V<sub>SS</sub>, V<sub>SS1</sub>, V<sub>SS2</sub>, V<sub>SS3</sub>, V<sub>SS4</sub>, V<sub>SS(PAD)</sub> and V<sub>SS(TX)</sub>.

[2] The antenna should be tuned not to exceed this current limit (the detuning effect when coupling with another device must be taken into account).

[3] The antenna shall be tuned not to exceed the maximum of I<sub>VBAT</sub>.

[4] This is the threshold of a built-in protection done to limit the current out of V<sub>DD(TX)</sub> in case of any issue at antenna pins to avoid burning the device. It is not allowed in operational mode to have I<sub>VDD(TX)</sub> such that I<sub>VBAT</sub> maximum value is exceeded.

## 14. Thermal characteristics

Table 24. Thermal characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
R <sub>th(j-a)</sub>	thermal resistance from junction to ambient	in free air with exposed pad soldered on a 4 layer JEDEC PCB	-	74	-	K/W

## 15. Characteristics

### 15.1 Current consumption characteristics

Table 25. Current consumption characteristics for operating ambient temperature range

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$I_{BAT}$	battery supply current	in Hard Power Down state; $V_{BAT} = 3.6\text{ V}$ ; VEN voltage = 0 V	-	10	18	$\mu\text{A}$
		in Standby state; [1] $V_{BAT} = 3.6\text{ V}$ ; including emulation phase of polling loop	-	20	35	$\mu\text{A}$
		in Idle and Target Active [2] power states; $V_{BAT} = 3.6\text{ V}$	-	6	-	$\text{mA}$
		in Initiator Active power [2] state; $V_{BAT} = 3.6\text{ V}$	-	13	-	$\text{mA}$
		in Monitor state; [3] $V_{BAT} = 2.75\text{ V}$	-	10	18	$\mu\text{A}$
$I_{O(VDDTX)}$	output current on pin $V_{DD(TX)}$	[4] [5]	-	30	100	$\text{mA}$
$I_{O(VDDPAD)}$	output current on pin $V_{DD(PAD)}$	total current which can be pulled on $V_{DD(PAD)}$ referenced outputs	-	-	15	$\text{mA}$

[1] Refer to [Section 10.1.2.4](#) for the description of the power modes.

[2] Refer to [Section 10.1.2.5](#) for the description of the polling loop.

[3] This is the same value for  $V_{BAT} = 2.3\text{ V}$  when the monitor threshold is set to 2.3 V.

[4]  $I_{VDD(TX)}$  depends on  $V_{DD(TX)}$  and on the external circuitry connected to TX1 and TX2.

[5] During operation with a typical circuitry as recommended by NXP in [Ref. 6](#), the overall current is below 100 mA even when loaded by target/card/tag.

### 15.2 Functional block electrical characteristics

#### 15.2.1 Battery voltage monitor characteristics

Table 26. Battery voltage monitor characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{th}$	threshold voltage	set to 2.3 V	2.2	2.3	2.4	V
		set to 2.75 V	2.65	2.75	2.85	V
$V_{hys}$	hysteresis voltage		100	150	200	mV

#### 15.2.2 Reset via VEN

Table 27. Reset timing

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{W(VEN)}$	VEN pulse width	to reset	3	-	-	$\mu\text{s}$
$t_{boot}$	boot time		-	-	2.5	ms

15.2.3 Power-up timings

Table 28. Power-up timings

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{t(VBAT-VEN)}$	transition time from pin $V_{BAT}$ to pin VEN	$V_{BAT}$ , VEN voltage = HIGH	0	-	-	ms
$t_{t(VDDPAD-VEN)}$	transition time from pin $V_{DD(PAD)}$ to pin VEN	$V_{DD(PAD)}$ , VEN voltage = HIGH	0	-	-	ms
$t_{t(VBAT-VDDPAD)}$	transition time from pin $V_{BAT}$ to pin $V_{DD(PAD)}$	$V_{BAT}$ , $V_{DD(PAD)}$ = HIGH	0	-	-	ms

15.2.4 Power-down timings

Table 29. Power-down timings

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_{VBAT(L)}$	time $V_{BAT}$ LOW		20	-	-	ms

15.2.5 Thermal protection

Table 30. Thermal threshold

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$T_{th(act)otp}$	overtemperature protection activation threshold temperature		120	125	130	°C

15.2.6 I<sup>2</sup>C-bus timings

Here below are timings and frequency specifications.

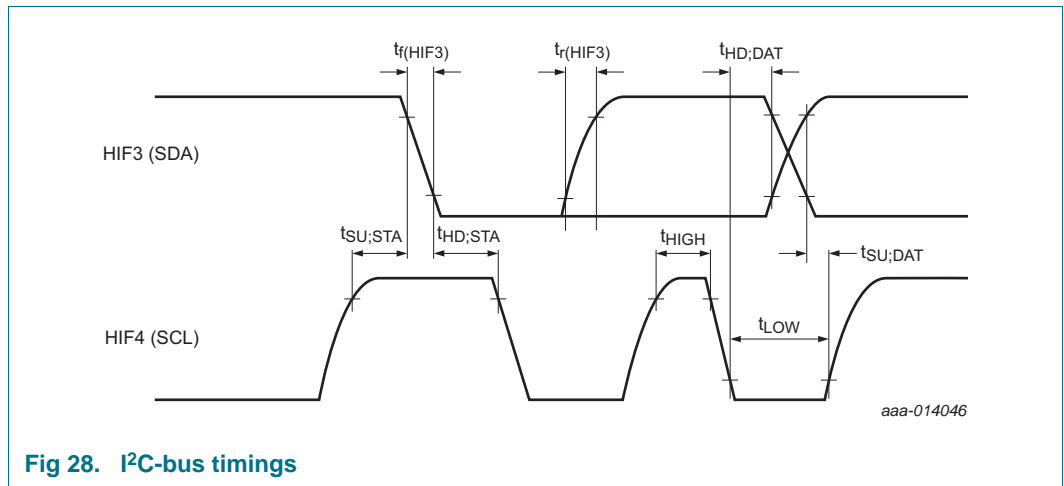


Fig 28. I<sup>2</sup>C-bus timings

Table 31. High-speed mode I<sup>2</sup>C-bus timings specification

Symbol	Parameter	Conditions	Min	Max	Unit
$f_{clk(I2CSCL)}$	clock frequency on pin I2CSCL	I <sup>2</sup> C-bus SCL; $C_b < 100$ pF	0	3.4	MHz
$t_{SU;STA}$	set-up time for a repeated START condition	$C_b < 100$ pF	160	-	ns
$t_{HD;STA}$	hold time (repeated) START condition	$C_b < 100$ pF	160	-	ns

**Table 31. High-speed mode I<sup>2</sup>C-bus timings specification ...continued**

Symbol	Parameter	Conditions	Min	Max	Unit
t <sub>LOW</sub>	LOW period of the SCL clock	C <sub>b</sub> < 100 pF	160	-	ns
t <sub>HIGH</sub>	HIGH period of the SCL clock	C <sub>b</sub> < 100 pF	60	-	ns
t <sub>SU;DAT</sub>	data set-up time	C <sub>b</sub> < 100 pF	10	-	ns
t <sub>HD;DAT</sub>	data hold time	C <sub>b</sub> < 100 pF	0	-	ns
t <sub>r(I2CSDA)</sub>	rise time on pin I2CSDA	I <sup>2</sup> C-bus SDA; C <sub>b</sub> < 100 pF	10	80	ns
t <sub>f(I2CSDA)</sub>	fall time on pin I2CSDA	I <sup>2</sup> C-bus SDA; C <sub>b</sub> < 100 pF	10	80	ns
V <sub>hys</sub>	hysteresis voltage	Schmitt trigger inputs; C <sub>b</sub> < 100 pF	0.1V <sub>DD(PAD)</sub>	-	V

**Table 32. Fast mode I<sup>2</sup>C-bus timings specification**

Symbol	Parameter	Conditions	Min	Max	Unit
f <sub>clk(I2CSCL)</sub>	clock frequency on pin I2CSCL	I <sup>2</sup> C-bus SCL; C <sub>b</sub> < 400 pF	0	400	kHz
t <sub>SU;STA</sub>	set-up time for a repeated START condition	C <sub>b</sub> < 400 pF	600	-	ns
t <sub>HD;STA</sub>	hold time (repeated) START condition	C <sub>b</sub> < 400 pF	600	-	ns
t <sub>LOW</sub>	LOW period of the SCL clock	C <sub>b</sub> < 400 pF	1.3	-	μs
t <sub>HIGH</sub>	HIGH period of the SCL clock	C <sub>b</sub> < 400 pF	600	-	ns
t <sub>SU;DAT</sub>	data set-up time	C <sub>b</sub> < 400 pF	100	-	ns
t <sub>HD;DAT</sub>	data hold time	C <sub>b</sub> < 400 pF	0	900	ns
V <sub>hys</sub>	hysteresis voltage	Schmitt trigger inputs; C <sub>b</sub> < 400 pF	0.1V <sub>DD(PAD)</sub>	-	V

## 15.3 Pin characteristics

### 15.3.1 XTAL1 and XTAL2 pins characteristics

**Table 33. Input clock characteristics on XTAL1 when using PLL**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V <sub>i(p-p)</sub>	peak-to-peak input voltage		0.2	-	1.8	V
δ	duty cycle		35	-	65	%

**Table 34. Pin characteristics for XTAL1 when PLL input**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
I <sub>IH</sub>	HIGH-level input current	V <sub>I</sub> = V <sub>DD</sub>	-	-	1	μA
I <sub>IL</sub>	LOW-level input current	V <sub>I</sub> = 0 V	1	-	-	μA
V <sub>i</sub>	input voltage		-	-	V <sub>DD</sub>	V
V <sub>i(clk)(p-p)</sub>	peak-to-peak clock input voltage		200	-	-	mV
C <sub>i</sub>	input capacitance	all power modes	-	2	-	pF

Table 35. Pin characteristics for 27.12 MHz crystal oscillator

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$C_{i(XTAL1)}$	XTAL1 input capacitance	$V_{DD} = 1.8\text{ V};$ $V_{DC} = 0.65\text{ V};$ $V_{AC} = 0.9\text{ V(p-p)}$	-	2	-	pF
$C_{i(XTAL2)}$	XTAL2 input capacitance		-	2	-	pF

[1] See the [Figure 27](#) for example of appropriate connected components. The layout should ensure minimum distance between the pins and the components.

Table 36. PLL accuracy

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$f_{o(acc)}$	output frequency accuracy	deviation added to XTAL1 frequency on RF frequency generated; worst case whatever input frequency	-50	-	+50	ppm

### 15.3.2 VEN input pin characteristics

Table 37. VEN input pin characteristics

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IH}$	HIGH-level input voltage		1.1	-	$V_{BAT}$	V
$V_{IL}$	LOW-level input voltage		0	-	0.4	V
$I_{IH}$	HIGH-level input current	VEN voltage = $V_{BAT}$	-	-	1	$\mu\text{A}$
$I_{IL}$	LOW-level input current	VEN voltage = 0 V	1	-	-	$\mu\text{A}$
$C_i$	input capacitance		-	5	-	pF

### 15.3.3 Pin characteristics for IRQ, CLK\_REQ and BOOST\_CTRL

Table 38. Pin characteristics for IRQ, CLK\_REQ and BOOST\_CTRL

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{OH}$	HIGH-level output voltage	$I_{OH} < 3\text{ mA}$	$V_{DD(PAD)} - 0.4$	-	$V_{DD(PAD)}$	V
$V_{OL}$	LOW-level output voltage	$I_{OL} < 3\text{ mA}$	0	-	0.4	V
$C_L$	load capacitance		-	-	20	pF
$t_f$	fall time	$C_L = 12\text{ pF max}$				
		high speed	1	-	3.5	ns
		slow speed	2	-	10	ns
$t_r$	rise time	$C_L = 12\text{ pF max}$				
		high speed	1	-	3.5	ns
		slow speed	2	-	10	ns
$R_{pd}$	pull-down resistance	[1]	0.4	-	0.75	$M\Omega$

[1] Activated in HPD and Monitor states.

### 15.3.4 ANT1 and ANT2 pin characteristics

Table 39. Electrical characteristics of ANT1 and ANT2

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$Z_{i(ANT1-ANT2)}$	input impedance between ANT1 and ANT2	low impedance	-	10	17	$\Omega$
$V_{th(ANT1)}$	ANT1 threshold voltage	$I = 10 \text{ mA}$	-	3.3	-	V
$V_{th(ANT2)}$	ANT2 threshold voltage	$I = 10 \text{ mA}$	-	3.3	-	V

### 15.3.5 Input pin characteristics for RXN and RXP

Table 40. Input pin characteristics for RXN and RXP

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{RXN(i)}$	RXN input voltage		0	-	$V_{DD}$	V
$V_{RXP(i)}$	RXP input voltage		0	-	$V_{DD}$	V
$C_{i(RXN)}$	RXN input capacitance		-	12	-	pF
$C_{i(RXP)}$	RXP input capacitance		-	12	-	pF
$Z_{i(RXN-VDDMID)}$	input impedance between RXN and $V_{DD(MID)}$	Reader, Card and P2P modes	0	-	15	$k\Omega$
$Z_{i(RXP-VDDMID)}$	input impedance between RXP and $V_{DD(MID)}$	Reader, Card and P2P modes	0	-	15	$k\Omega$
$V_{i(dyn)(RXN)}$	RXN dynamic input voltage	Miller coded				
		106 kbit/s	-	150	200	mV(p-p)
		212 to 424 kbit/s	-	150	200	mV(p-p)
$V_{i(dyn)(RXP)}$	RXP dynamic input voltage	Miller coded				
		106 kbit/s	-	150	200	mV(p-p)
		212 to 424 kbit/s	-	150	200	mV(p-p)
$V_{i(dyn)(RXN)}$	RXN dynamic input voltage	Manchester, NRZ or BPSK coded; 106 to 848 kbit/s	-	150	200	mV(p-p)
$V_{i(dyn)(RXP)}$	RXP dynamic input voltage	Manchester, NRZ or BPSK coded; 106 to 848 kbit/s	-	150	200	mV(p-p)
$V_{i(dyn)(RXN)}$	RXN dynamic input voltage	All data coding; 106 kbit/s to 848 kbit/s	$V_{DD}$	-	-	V(p-p)
$V_{i(dyn)(RXP)}$	RXP dynamic input voltage	All data coding; 106 kbit/s to 848 kbit/s	$V_{DD}$	-	-	V(p-p)
$V_{i(RF)}$	RF input voltage	RF input voltage detected; Initiator modes		100	-	mV(p-p)

### 15.3.6 Output pin characteristics for TX1 and TX2

Table 41. Output pin characteristics for TX1 and TX2

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{OH}$	HIGH-level output voltage	$V_{DD(TX)} = 3.1\text{ V}$ and $I_{OH} = 30\text{ mA}$ ; PMOS driver fully on	$V_{DD(TX)} - 150$	-	-	mV
$V_{OL}$	LOW-level output voltage	$V_{DD(TX)} = 3.1\text{ V}$ and $I_{OL} = 30\text{ mA}$ ; NMOS driver fully on	-	-	200	mV

Table 42. Output resistance for TX1 and TX2

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$R_{OL}$	LOW-level output resistance	$V_{DD(TX)} - 100\text{ mV}$ ; CWGsN = 01h	-	-	80	$\Omega$
$R_{OL}$	LOW-level output resistance	$V_{DD(TX)} - 100\text{ mV}$ ; CWGsN = 0Fh	-	-	5	$\Omega$
$R_{OH}$	HIGH-level output resistance	$V_{DD(TX)} - 100\text{ mV}$	-	-	4	$\Omega$

### 15.3.7 Input pin characteristics for I2CADR0

Table 43. Input pin characteristics for I2CADR0

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{IH}$	HIGH-level input voltage		$0.65V_{DD(PAD)}$	-	$V_{DD(PAD)}$	V
$V_{IL}$	LOW-level input voltage		0	-	$0.35V_{DD(PAD)}$	V
$I_{IH}$	HIGH-level input current	$V_I = V_{DD(PAD)}$ ; $T = 125\text{ }^\circ\text{C}$	-	-	1	$\mu\text{A}$
$I_{IL}$	LOW-level input current	$V_I = 0\text{ V}$ ; $T = 125\text{ }^\circ\text{C}$	-1	-	-	$\mu\text{A}$
$C_i$	input capacitance		-	5	-	pF

### 15.3.8 Pin characteristics for I2CSDA and I2CSCL

Table 44. Pin characteristics for I2CSDA and I2CSCL

Below values are given for  $V_{DD(PAD)}$  in the range of 1.8 V; unless specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{OL}$	LOW-level output voltage	$I_{OL} < 3\text{ mA}$	0	-	0.4	V
$C_L$	load capacitance		-	-	10	pF



**Table 44. Pin characteristics for I2CSDA and I2CSCL ...continued**  
 Below values are given for  $V_{DD(PAD)}$  in the range of 1.8 V; unless specified.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$t_f$	fall time	$C_L = 100$ pF; Rpull-up = 1.8 k $\Omega$ ; Standard and Fast mode	30	-	250	ns
		$C_L = 100$ pF; $V_{DD(PAD)} = 3.3$ V; Rpull-up = 3.3 k $\Omega$ ; Standard and Fast mode	30	-	250	ns
		$C_L = 100$ pF; Rpull-up = 1 k $\Omega$ ; High-speed mode	80	-	110	ns
$t_r$	rise time	$C_L = 100$ pF; Rpull-up = 1.8 k $\Omega$ ; Standard and Fast mode	30	-	250	ns
		$C_L = 100$ pF; $V_{DD(PAD)} = 3.3$ V; Rpull-up = 3.3 k $\Omega$ ; Standard and Fast mode	30	-	250	ns
		$C_L = 100$ pF; Rpull-up = 1 k $\Omega$ ; High-speed mode	10	-	100	ns
$V_{IH}$	HIGH-level input voltage		$0.7V_{DD(PAD)}$	-	$V_{DD(PAD)}$	V
$V_{IL}$	LOW-level input voltage		0	-	$0.3V_{DD(PAD)}$	V
$I_{IH}$	HIGH-level input current	$V_I = V_{DD(PAD)}$ ; high impedance	-	-	1	$\mu$ A
$I_{IL}$	LOW-level input current	$V_I = 0$ V; high impedance	-1	-	-	$\mu$ A
$C_i$	input capacitance		-	5	-	pF

16. Package outline

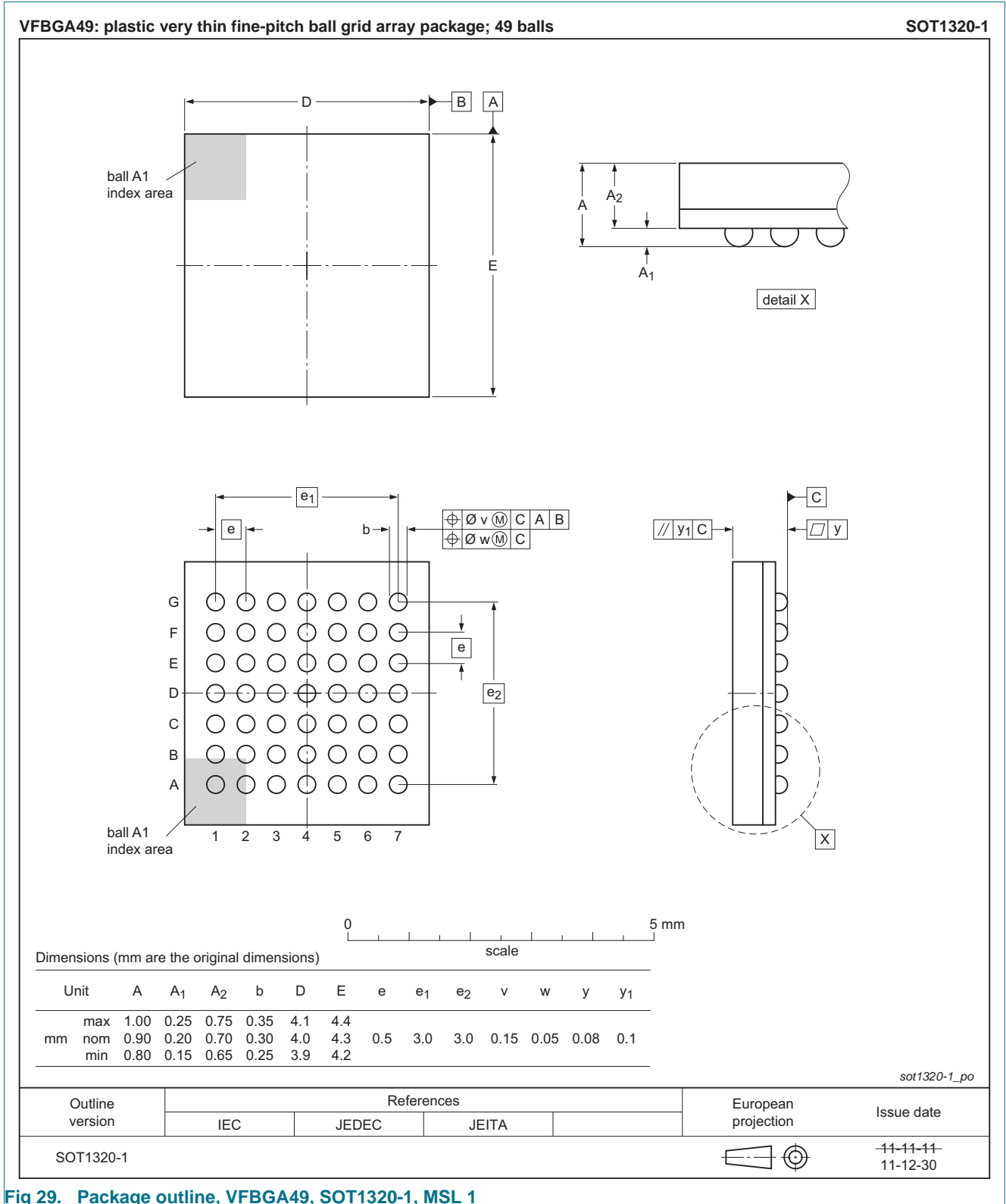


Fig 29. Package outline, VFBGA49, SOT1320-1, MSL 1

## 17. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

### 17.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

### 17.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

### 17.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

### 17.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 30](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 45](#) and [46](#)

**Table 45. SnPb eutectic process (from J-STD-020D)**

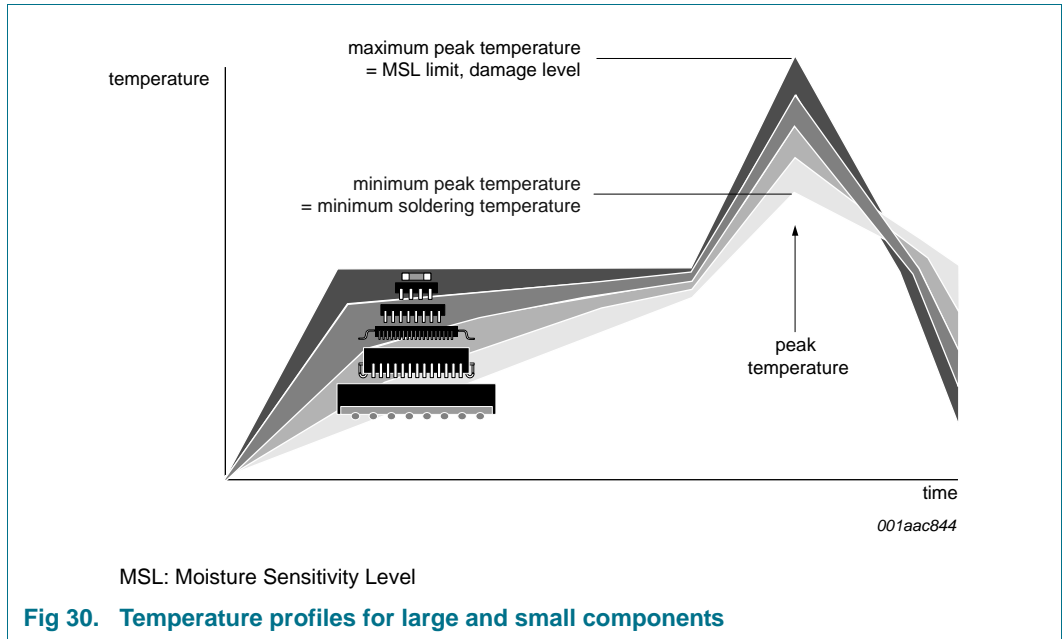
Package thickness (mm)	Package reflow temperature (°C)	
	Volume (mm <sup>3</sup> )	
	< 350	≥ 350
< 2.5	235	220
≥ 2.5	220	220

**Table 46. Lead-free process (from J-STD-020D)**

Package thickness (mm)	Package reflow temperature (°C)		
	Volume (mm <sup>3</sup> )		
	< 350	350 to 2000	> 2000
< 1.6	260	260	260
1.6 to 2.5	260	250	245
> 2.5	250	245	245

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 30](#).



For further information on temperature profiles, refer to Application Note AN10365 “Surface mount reflow soldering description”.

## 18. Abbreviations

Table 47. Abbreviations

Acronym	Description
API	Application Programming Interface
ASK	Amplitude Shift keying
ASK modulation index	The ASK modulation index is defined as the voltage ratio $(V_{max} - V_{min}) / (V_{max} + V_{min}) \times 100 \%$
Automatic device discovery	Detect and recognize any NFC peer devices (initiator or target) like: NFC initiator or target, ISO/IEC 14443-3, -4 Type A&B PICC, MIFARE Standard and Ultralight PICC, ISO/IEC 15693 VICC
BPSK	Bit Phase Shift Keying
Card Emulation	The IC is capable of handling a PICC emulation on the RF interface including part of the protocol management. The application handling is done by the host controller
DEP	Data Exchange Protocol
DSLDO	Dual Supplied LDO
FW	FirmWare
HPD	Hard Power Down
LDO	Low Drop Out
LFO	Low Frequency Oscillator
MOSFET	Metal Oxide Semiconductor Field Effect Transistor
MSL	Moisture Sensitivity Level
NCI	NFC Controller Interface
NFC	Near Field Communication
NFCC	NFC Controller, PN7120 in this data sheet
NFC Initiator	Initiator as defined in ISO/IEC 18092 or ECma 340: NFCIP-1 communication
NFCIP	NFC Interface and Protocol
NFC Target	Target as defined in ISO/IEC 18092 or ECma 340: NFCIP-1 communication
NRZ	Non Return to Zero
P2P	Peer to Peer
PCD	Proximity Coupling Device. Definition for a Card reader/writer device according to the ISO/IEC 14443 specification or MIFARE
PCD -> PICC	Communication flow between a PCD and a PICC according to the ISO/IEC 14443 specification or MIFARE
PICC	Proximity Interface Coupling Card. Definition for a contactless Smart Card according to the ISO/IEC 14443 specification or MIFARE
PICC-> PCD	Communication flow between a PICC and a PCD according to the ISO/IEC 14443 specification or MIFARE
PMOS	P-channel MOSFET
PMU	Power Management Unit
PSL	Parameter SeLection
TXLDO	Transmitter LDO
UM	User Manual

Table 47. Abbreviations ...continued

Acronym	Description
VCD	Vicinity Coupling Device. Definition for a reader/writer device according to the ISO/IEC 15693 specification
VCO	Voltage Controlled Oscillator
VICC	Vicinity Integrated Circuit Card
WUC	Wake-Up Counter

## 19. References

- [1] **NFC Controller Interface (NCI) Technical Specification** — V1.0
- [2] **ISO/IEC 14443** — parts 2: 2001 COR 1 2007 (01/11/2007), part 3: 2001 COR 1 2006 (01/09/2006) and part 4: 2nd edition 2008 (15/07/2008)
- [3] **I<sup>2</sup>C Specification** — I<sup>2</sup>C Specification, UM10204 rev4 (13/02/2012)
- [4] **PN7120 User Manual** — UM10819 PN7120 User Manual
- [5] **PN7120 Hardware Design Guide** — AN11565 PN7120 Hardware Design Guide
- [6] **PN7120 Antenna and Tuning Design Guide** — AN11564 PN7120 Antenna and Tuning Design Guide
- [7] **ISO/IEC 18092 (NFCIP-1)** — edition, 15/032013. This is similar to Ecma 340.
- [8] **ISO/IEC15693** — part 2: 2nd edition (15/12/2006), part 3: 1st edition (01/04/2001)
- [9] **PN7120 Low-Power Mode Configuration** — AN11562 PN7120 Low-Power Mode Configuration
- [10] **ISO/IEC 21481 (NFCIP-2)** — edition, 01/07/2012. This is similar to Ecma 352.
- [11] **NFC Forum Device Requirements** — V1.3
- [12] **ETSI SWP** — TS 102 613; UICC - Contactless Front-end (CLF) Interface; Part 1: Physical and data link layer characteristics (Release 9)
- [13] **ETSI HCI** — TS 102 622; UICC - Contactless Front-end (CLF) Interface; Host Controller Interface (HCI) (Release 9)
- [14] **ETSI UICC** — TS 102 221; UICC - Terminal Interface; Physical and logical characteristics (Release 9)
- [15] **EMVCo** — EMV Contactless Specifications for Payment Systems - Book D - EMV Contactless Communication Protocol Specification”, version 2.3.1, December 2013



## 20. Revision history

Table 48. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
PN7120 v.3.1	20151008	Product data sheet	-	PN7120 v.3.0
Modifications:	<ul style="list-style-type: none"> <li>• <a href="#">Table 4 “PN7120 pin description”</a>: Description of Pin A1 and A5 updated</li> <li>• <a href="#">Figure 27 “Application schematic”</a>: updated</li> </ul>			
PN7120 v.3.0	20150727	Product data sheet	-	PN7120 v.2
Modifications:	<ul style="list-style-type: none"> <li>• Data sheet status changed to “Product data sheet”</li> <li>• <a href="#">Section 2 “General description”</a>: first sentence updated</li> <li>• <a href="#">Section 3 “Features and benefits”</a>: first bullet added</li> <li>• <a href="#">Section 10.1 “System modes”</a>: updated</li> <li>• <a href="#">Section 21.4 “Licenses”</a>: License statement “Purchase of NXP ICs with NFC technology” updated</li> </ul>			
PN7120 v.2	20150611	Preliminary data sheet	-	PN7120 v.1
Modifications:	<ul style="list-style-type: none"> <li>• <a href="#">Table 33</a>: updated</li> </ul>			
PN7120 v.1	20150506	Objective data sheet	-	-

## 21. Legal information

### 21.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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