

# IAI

Quality and Innovation

Network Controller

# ROBO NET

DeviceNet

CC-Link

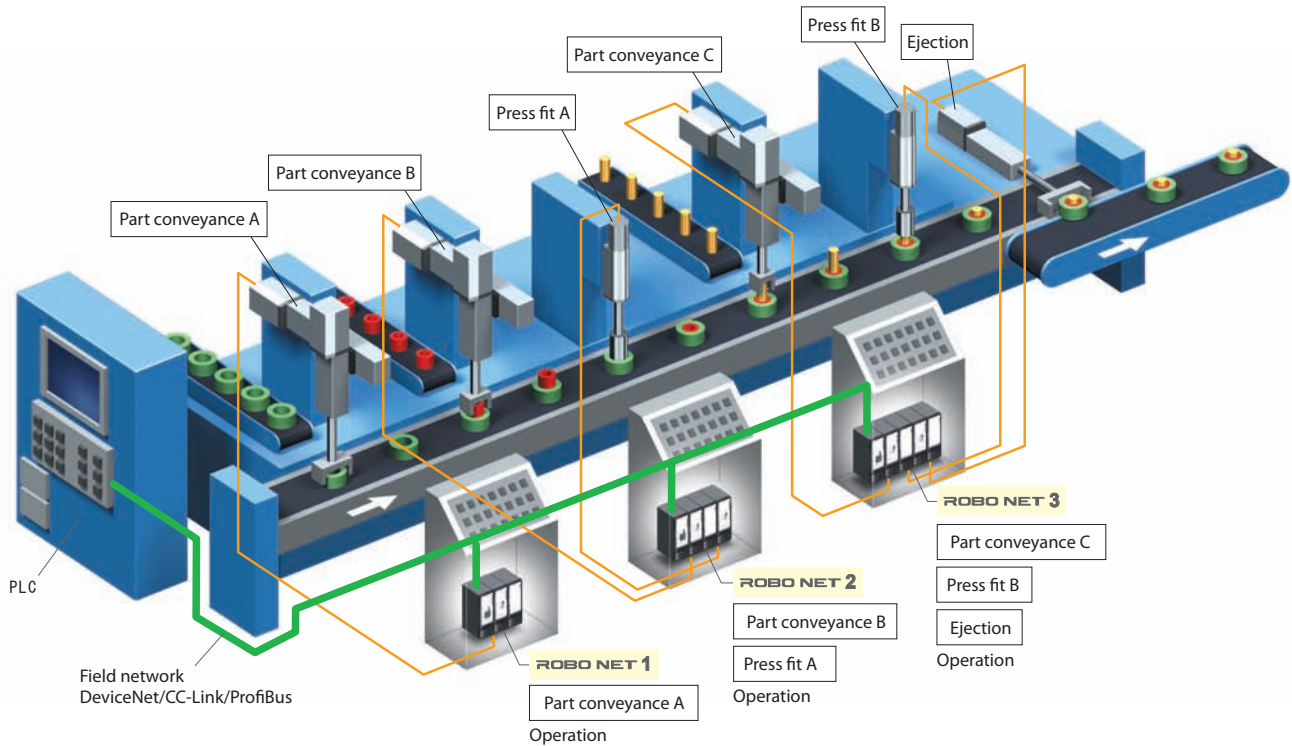
SIO

ProfiBus



# Greatly reduces time and effort of wiring and installation

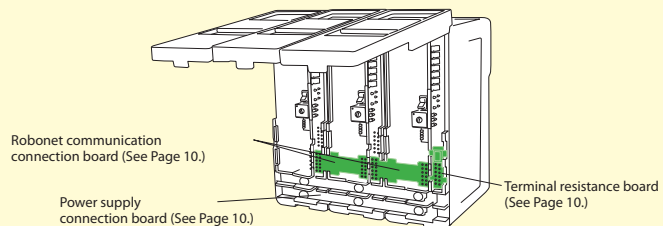
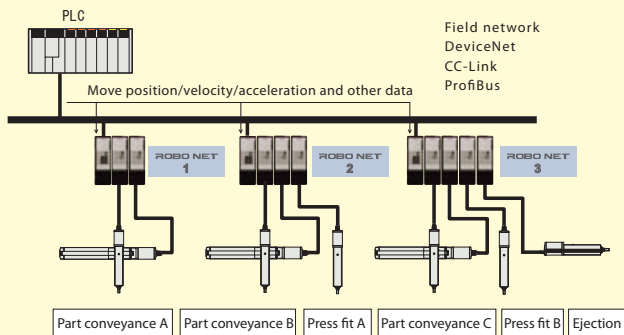
RoboNet is a new type of controller unit that can freely operate robot cylinders via a field network. This makes it possible to greatly reduce the time and effort of wiring installation compared to conventional controllers by reducing wiring, making the controller smaller, and using DIN rail installation.



## 1 Reduced wiring

By connecting each line of the I/O cable to lines wired to the PLC terminals with the field network, wiring processing is completed with one dedicated cable.

Also, since the unit can be coupled by just connecting with the unit connection board, the controller wiring work is greatly simplified.



(Coupling section within RoboNet unit)

# Newly Developed Network Controller

# ROBO NET Arrives!

## 2 The robot can be moved by directly specifying numeric values for the move position/velocity/acceleration and other data.

Besides the conventional method of moving the robot to pre-taught positions it is also possible to operate the robot by sending information as a string of numeric data that contains position, velocity, acceleration, etc. values. This is effective for cases such as when the move position changes with each piece or when one wants to move the robot to an arbitrary position.

	ROBONET controller	Standard controller (ACON/PCON)
Position specification movement	○	○
Direct numeric value specification movement	○	△
Velocity/acceleration specification	○	(Not possible with PIO) (Possible with serial communications)
Current value output	○	

\* RoboNet operates via the field network; the standard controller operates with PIO.

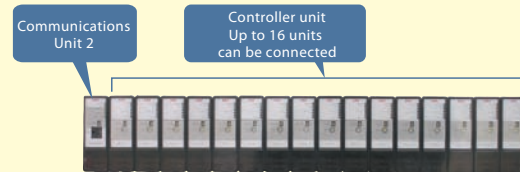
## 3 Ultra-compact

Each unit is an ultra-compact size of 34mm wide by 100mm high x 73 mm deep. Also, since there is no base unit and the main unit is coupled with connectors, the controller takes up little space for installation even if there are many units.



## 4 Can operate up to 16 axes

Up to 16 controller units can be connected to one communications unit (GatewayR unit). One can also freely mix and connect RACON units (RCA controllers) and RPCON units (RCP2 controllers).



## 5 Simple absolute specifications that do not require a return to home position

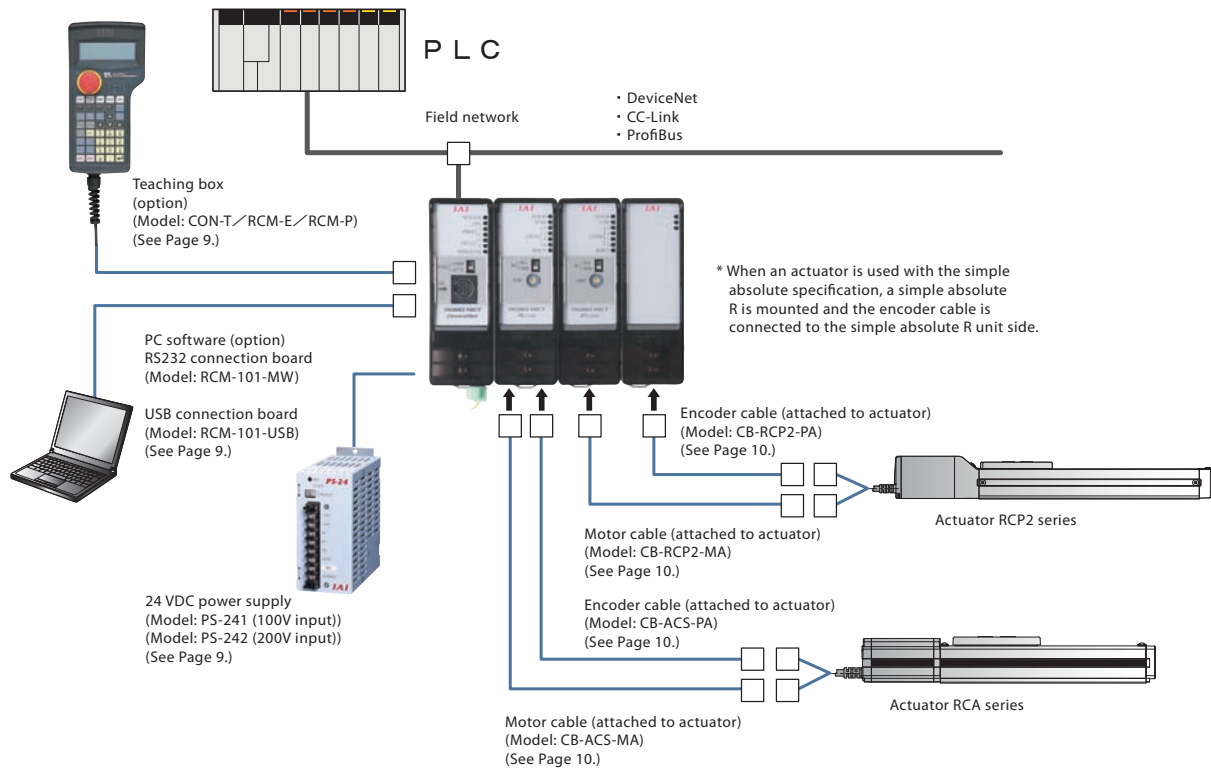
The simple absolute R unit makes it possible to operate incremental specification axes without returning to the home position. By mounting a simple absolute R unit on a RACON unit (RCA controller)/RPCON unit (RCP2 controller), the actuator encoder data is backed up even if the power is cut off.



## 6 DIN rail installation

The controller is installed with DIN rails, so it can be fastened and removed with one touch.

## System configuration



## Component unit/ordering method explanation

For RoboNet, you order the required units individually and use them together freely. Even if you want to add actuators later, you can do so simply by ordering additional RACON/RPCON units.



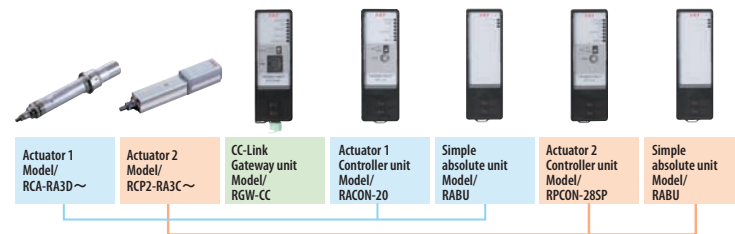
Unit name	Contents	See Page _
Gateway R unit	This unit is for connection to the field network. There are four types to select from: DeviceNet/CC-Link/ProfiBus/SIO. *This unit is a required unit for using RoboNet.	P5 P6
RACON unit	This is the controller unit for operating an RCA actuator. (Each actuator axis requires one unit.) The standard specifications are the incremental specifications, but this unit can be used with the simple absolute specifications by just combining with a simple absolute R unit.	P7
RPCON unit	This is the controller unit for operating an RCP2 actuator. (Each actuator axis requires one unit.) The standard specifications are the incremental specifications, but this unit can be used with the simple absolute specifications by just combining with a simple absolute R unit.	P7
Simple absolute R unit	This is the backup battery unit for holding the actuator encoder data when the power is switched Off.	P8

### User's manual

The RoboNet user's manual comes with the RoboNet not as a printed document, but as a CD-ROM. You can also download the user's manual from our homepage.

**Order method** RoboNet is used by ordering the necessary units one by one and using them together. This means you can add or change units afterwards.

(Order example) Operating the two actuator axes below via CC-Link. The models for operating with absolute specifications are as follows.



## Operating mode explanation

RoboNet operates under instructions received from the PLC via the field network.

It can be used switching among the following three operating modes.

Use the operating mode that best suits the device operation details and control method.

	Name	Contents
1	Positioner mode	This mode operates by specifying the position number. The position data, velocity, acceleration, etc. are input for each position ahead of time. Up to 768 positions can be registered.
2	Simple direct value mode	This mode operates by directly specifying only the position data and specifying other data – velocity, acceleration, position width, electrical current limit for pressing – with the position number. Up to 768 positions can be registered.
3	Direct numeric value specification	This mode operates by directly specifying the numeric values for the position data, velocity, acceleration, position width, and electrical current limit for pressing. There is no limit on the number of position points that can be specified numerically.

## List of Functions by Operating Mode

	Positioner mode	Simple direct value mode	Direct numeric value specification
Number of positions registered	768 points	768 points	—
Movement by specifying position number	○	○	×
Direct specification of position data	×	○	○
Direct specification of velocity and acceleration	×	×	○
Direct specification of positioning width	×	×	○
Pressing operation	○	○	○
Completion position number monitor	○	○	×
Zone output monitor	○	○	○
Position zone output monitor	○	○	×
Teaching functions	○	×	×
Jog operations	○	○	○
Incremental moves	○	○	○
Status signal monitor (*)	○	○	○
Current position monitor (*)	○	○	○
Alarm code monitor (*)	○	○	○
Velocity and electric current monitor (*)	×	×	○
Maximum value for specification of position data	9999.99mm	9999.99mm	9999.99mm
Number of axes that can be connected	16	16	8

\* The status signal monitor, current position monitor, alarm code monitor, and velocity and electric current monitor can monitor by accessing each address of the GatewayR unit from the PLC.

## Component unit explanation

### GatewayR unit (DeviceNet specifications)

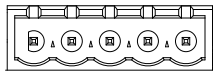


This is the communications unit for operating RoboNet via DeviceNet.  
**Model RGW-DV**  
**Specifications**

Item	Specifications	Item	Specifications	
Power supply	DC24V ±10%	DeviceNet specifications	Communications speed	
Current consumption	600 mA max.		Maximum network length	
Communications standard	Uses DeviceNet 2.0 certified interface module		Maximum branch line length	
	Group 2 only server		Total branch line length	
Communications speed	Insulated node operating with network power supply	Environmental conditions	Usage ambient temperature	
	Master-satellite Connection		Bit strobe	Usage ambient humidity
			Polling	Usage atmosphere
Communications speed	500k/250k/125kpbs (switched with dedicated software)	Number of nodes occupied	1 node	
* 1 For T branch communications, refer to the user's manuals for the master unit and for the PLC used.		Protection rank	IP20	
		Weight	140g	
		Accessories	Terminal resistance board (Model TN-1) Network connector/emergency stop connector	

#### Network connector

Gateway side connector  
 MSTBA2.5/5-G-5.08 ABGY AU  
 (Made by Phoenix Contact)



Cable side connector  
 MSTB2.5/5-ST-5.08 ABGY AU  
 (Made by Phoenix Contact)  
 = Standard accessory



Pin colors	Explanation
Black	Power cable - side
Blue	Communications data Low side
—	Shield
White	Communications data High side
Red	Power cable + side

#### Compatible wire for cable side connector

Item	Contents
Compatible wire diameter	Braided wire AWG24-12 (0.2~2.5 mm <sup>2</sup> )
Peeled wire length	7mm

### GatewayR unit CC-Link specifications



This is the communications unit for operating RoboNet via CC-Link.  
**Model RGW-CC**  
**Specifications**

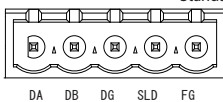
Item	Specifications	Item	Specifications
Power supply	DC24V ±10%	CC-Link specifications	Error control technique
Current consumption	600 mA max.		Number of stations occupied
Communications standard	CC-Link Ver2.0 (※1)	Environmental conditions	Usage ambient temperature
			Usage ambient humidity
Communications speed	10M/5M/2.5M/625k/156kpbs (switched with dedicated software)	CC-Link specifications	Usage atmosphere
Communications technique	Broadcast polling technique		Communication cable
Synchronization technique	Frame synchronization technique	Protection rank	IP20
Encoding technique	NRZ I	Weight	140g
Transmission path format	Bus format (complies with EIA RS485)	Accessories	Terminal resistance board (Model TN-1) Network connector/emergency stop connector Terminal resistance cable (110Ω/130Ω)
Transmission format	Complies with HDLC		

\*1 Certification acquired  
 \*2 For T branch communications, refer to the user's manuals for the master unit and for the PLC used.

#### Network connector

Gateway side connector  
 MSTBA2.5/5-G-5.08 AU  
 (Made by Phoenix Contact)

Cable side connector  
 MSTB2.5/5-ST-5.08 ABGY AU  
 (Made by Phoenix Contact)  
 = Standard accessory



Signal name	Explanation
D A	Communications line A
D B	Communications line B
D G	Ground
S L D	Connect the shield and cable shield to the frame ground and chassis.
F G	Connect the frame ground to the shield and the chassis

#### Compatible wire for cable side connector

Item	Contents
Compatible wire diameter	Braided wire AWG24-12 (0.2~2.5 mm <sup>2</sup> )
Peeled wire length	7mm

## GatewayR unit (Profibus specifications)

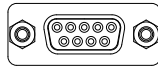


This is the communications unit for operating RoboNet via Profibus.  
**Model RGW-PR**  
**Specifications**

Item	Specifications		Item	Specifications	
Power supply	DC24V ±10%		Environmental conditions	Usage ambient temperature	0~40°C
Current consumption	600 mA max.			Usage ambient humidity	95% RH max. (no condensation allowed)
Profibus specifications	Communications standard	DP satellite		Usage atmosphere	There must be no corrosive gas, combustible gas, oil mist, or dust.
	Communications speed	9.6kbps~12Mbps		Protection rank	IP20
	Communications cable length	9.6kbps	1500m	Weight	140g
		500kbps	400m	Accessories	Terminal resistance board (Model TN-1) Emergency stop connector
		1.5Mbps	200m		
3Mbps		200m			
12Mbps	100m				

### Network connector

Gateway side connector: 5 1  
 D-Sub 9-pin connector  
 Socket side



Pin No.	Signal name	Explanation	Pin No.	Signal name	Explanation
3	B - L i n e	Communications line B (RS485)	6	+5V	+5V output (insulated)
4	RTS	Request to send	8	A - L i n e	Communications line A (RS485)
5	GND	Signal ground (insulated)	Housing	S h i e l d	The cable shield is connected with the chassis.

\* The partner side connector (D-sub 9-pin connector) does not come as an accessory.

\* Pins 1, 2, 7, and 9 are not connected.

## GatewayR unit SIO specifications

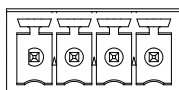


This is the communications unit for operating RoboNet with serial communications from an XSEL controller (\*1) or Modbus communications unit.  
**\*1 A unit with XSEL Gateway functions is scheduled for release soon.**  
**Model RGW-SIO**  
**Specifications**

Item	Specifications		Item	Specifications	
SIO specifications	Power supply	DC24V ±10%	Environmental conditions	Usage ambient temperature	0~40°C
	Current consumption	600 mA max.		Usage ambient humidity	95% RH max. (no condensation allowed)
	Communications format	RS485 compliant (Modbus protocol) 1:1 communication connection		Usage atmosphere	There must be no corrosive gas, combustible gas, oil mist, or dust.
	Communications technique	Stop-start system Half duplex		Protection rank	IP20
	Communications speed	230.4 kbps max.		Weight	140g
	Cable length	100 m max.		Accessories	Terminal resistance board (Model TN-1) Network connector/emergency stop connector
Recommended cable	2-pair twisted pair cable (with shield)				

### Network connector

Gateway side connector  
 MC1.5/4-G-3.5  
 (Made by Phoenix Contact)



Cable side connector:  
 MC1.5/4-ST-3.5  
 (Made by Phoenix Contact)  
 = Standard accessory

Signal name	Explanation	
SA	Communications line A (+ side)	RS485 compliant Terminal resistance board (220 Ω) built in
SB	Communications line B (- side)	
SG	Signal ground	
FG	The frame ground is connected with the chassis.	

### Compatible wire for cable side connector

Item	Contents
Compatible wire diameter	Braided wire AWG28-16 (0.14~1.5 mm <sup>2</sup> )
Peeled wire length	7mm

## Component unit explanation

### RACON unit RCA series controller



This is the controller unit for operating an RCA actuator with RoboNet.

Controller model	Supported actuators
RACON-20	RCA-SA4□ / SS4□ / SA5□ / SS5□ / RA4□-20 / RG□4□-20 / A4R / A5R RCACR-SA4C / SA5□ RCAW-RA4□-20
RACON-20S	RCA-RA3□ / RG□3□ RCAW-RA3□
RACON-30	RCA-SA6□ / SS6□ / RA4□-30 / RG□4□-30 / A6R RCACR-SA6□ RCAW-RA4□-30

#### Specifications

Item	Specifications	Item	Specifications		
General specifications	Power supply	DC24V ±10%	Environmental conditions	Usage ambient temperature	0~50°C
	Power supply capacity	5.1 A max. (depends on actuator)		Usage ambient humidity	95% RH max. (no condensation allowed)
	Operating actuator	RCA series		Usage atmosphere	There must be no corrosive gas, combustible gas, oil mist, or dust.
	Number of positioning points	768 points		Protection rank	IP20
	Backup memory	EEPROM	Weight	200g	
	Position detection technique	Incremental encoder	Accessories	RoboNet communication connection board (JB-1 model)	
	Electromagnetic brake forced release	Brake release switch		Power supply connection board (PP-1 model)	
	Motor cable	Model CB-ACS-MA			
	Encoder cable	Model CB-ACS-PA			

### RPCON unit RCP2 series controller



This is the controller unit for operating an RCP2 actuator with RoboNet.

Controller model	Supported actuators
RPCON-20P	RCP2-RA2C / GRS
RPCON-28P	RCP2-GRM / GR3LS / GR3SS / RTB / RTC
RPCON-28SP	RCP2-RA3C / RGD3C
RPCON-42P	RCP2-SA5□ / SA6□ / SS7□ / BA6□ / BA7□ / RA4C / RG□4C / GR3LM / GR3SM / RCP2CR-SA5C / SA6C / SS7C RCP2W-RA4C
RPCON-56P	RCP2-SA7□ / SS8□ / RA6C / RG□6C / RCP2CR-SA7C / SS8C RCP2W-RA6C

\* This controller can also operate an old-type RCP2 actuator. (Please inquire for details.)

#### Specifications

Item	Specifications	Item	Specifications		
General specifications	Power supply	DC24V ±10%	Environmental conditions	Usage ambient temperature	0~50°C
	Power supply capacity	2 A max.		Usage ambient humidity	95% RH max. (no condensation allowed)
	Operating actuator	RCP2 series		Usage atmosphere	There must be no corrosive gas, combustible gas, oil mist, or dust.
	Number of positioning points	768 points		Protection rank	IP20
	Backup memory	EEPROM	Weight	200g	
	Position detection technique	Incremental encoder	Accessories	RoboNet communication connection board (JB-1 model)	
	Electromagnetic brake forced release	Brake release switch		Power supply connection board (PP-1 model)	
	Motor cable	Model CB-RCP2-MA			
	Encoder cable	Model CB-RCP2-PA			



## Simple absolute R unit



This is a data backup battery unit that is connected to a RACON/RPCON unit to allow incremental specifications actuators to be used as absolute specifications actuators.

\*1 One simple absolute R unit is required for each RACON/RPCON unit.

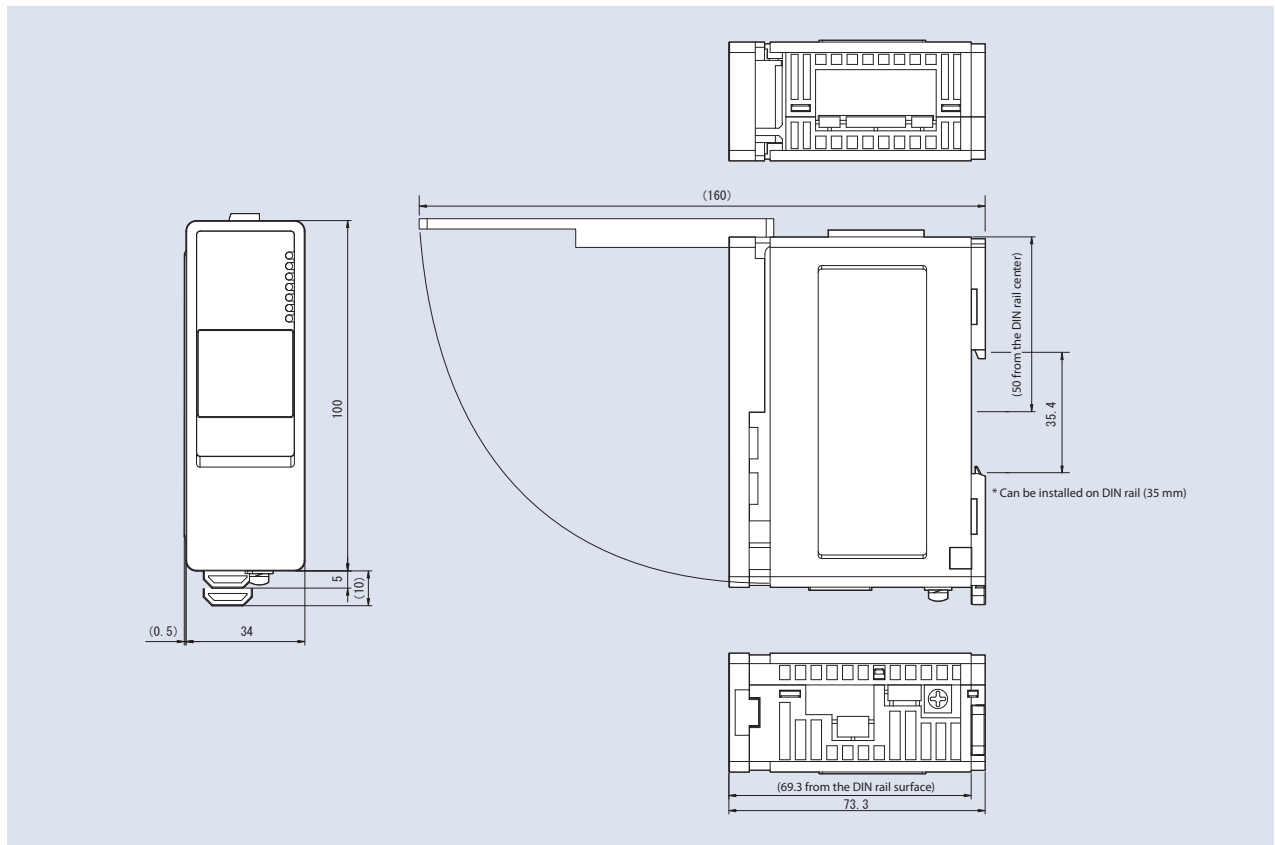
Model **RABU** (Common to RACON/RPCON)

Specifications

Item	Specifications				Item	Specifications		
General specifications	Power supply	DC24V ±10%				Environmental conditions	Usage ambient temperature	0~40°C
	Current consumption	300 mA max.					Usage ambient humidity	95% RH max. (no condensation allowed)
	Battery used	Nickel metal hydride battery (Ni-MH)					Usage atmosphere	There must be no corrosive gas, combustible gas, oil mist, or dust.
	Charge time	About 78 hours				Protection rank	IP20	
	Battery life	3 years				Weight	330g	
Can store absolute data Maximum rotation rate (rpm)	800	400	200	100	Accessories	RoboNet communication connection board (JB-1 model)		
	Absolute data storage time (h)	120	240	360		480	Simple absolute specifications connection board (JB-1 model) Power supply connection board (PP-1 model)	

## External dimensions diagram

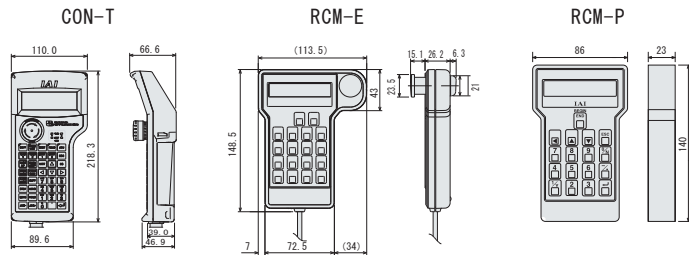
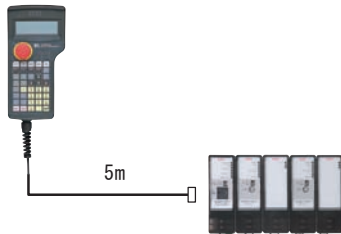
GatewayR unit/RACON unit/RPCON unit/simple absolute R unit all share the same external dimensions.



## Options

### Teaching box

- **Features** This is a teaching device equipped with position input, test run, monitor, and other functions.
- **Model**
  - CON-T (standard type)
  - RCM-E (simple teaching box)
  - RCM-P (data setting unit)
- **Configuration**



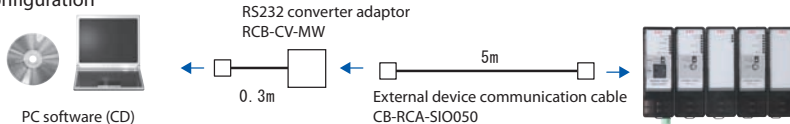
### Specifications

Item	CON-T	RCM-E	RCM-P
Data input	○	○	○
Actuator operation	○	○	×
Usage ambient temperature and humidity	Temperature 0 to 40°C Relative humidity 85% max.		
Usage atmosphere	No corrosive gas allowed Dust must not be particularly bad.		
Protection rank	IP54	—	—
Weight	About 400g	About 400g	About 360g
Cable length	5m		
Display	20-character by 4-line LCD display	16-character by 2-line LCD display	16-character by 2-line LCD display

### PC software (for Windows only)

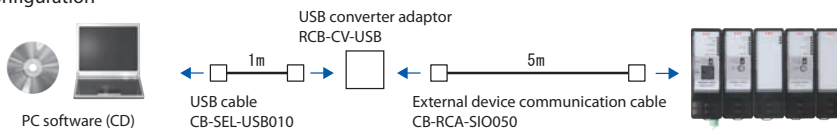
- **Features** This is startup support software equipped with program/position input, test run, monitor, and other functions. It increases functions required for debugging operations and contributes to shortening the start-up time.
- **Model** RCM-101-MW (with external device communications cable + RS232 converter unit)

#### Configuration



- **Model** RCM-101-USB (with external device communications cable + USB cable)

#### Configuration



### 24 VDC power supply

#### Features

This is a 24V power supply for a robocylinder that output an instantaneous maximum of 17 A. Since power supply parallel operation is possible, if one power supply unit has insufficient capacity, up to five units can be added.

#### Model

PS-241

(100V input specifications)

PS-242

(200V input specifications)

Relationship between actuator and power supply current

Control type	Actuator type	Power supply current [A]		PS-24 Number of units that can be connected per unit	
		Rated (=maximum)	2	When the servos come On for all axes at the same time *	When the servos does not come On for all axes at the same time *
RPCON PCON PSEL	RCP2 all models (*)	Rated	1.3	8	8
		Maximum	4.4		
RACON ACON ASEL	SA4, SA5 (20W)	Rated	1.3	3	6
		Maximum	4		
	SA6 (30W)	Rated	1.3	4	6
		Maximum	4		
	RA3 (20W)	Rated	1.7	3	5
		Maximum	5.1		
RA4 (20W)	Rated	1.3	3	6	
	Maximum	4.4			
RA4 (30W)	Rated	1.3	4	6	
	Maximum	4			

\* This indicates the first servo to come On after the power is switched on.  
Note: Except HS8C, HS8R, or RAI0C.



# Maintenance parts

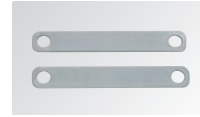
When it is necessary to make arrangements for a replacement cable or the like after product purchase, find the model below.



RoboNet communication connection board (simple absolute connection board) Model JB-1



Terminal resistance board Model TN-1



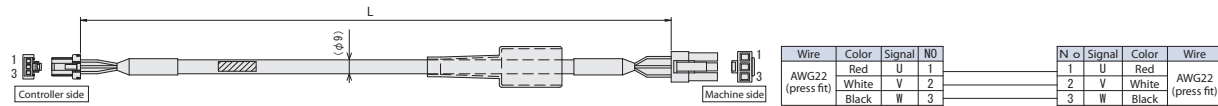
Power supply connection board Model PP-1

## RACON motor cable

## Motor cable

Model CB-ACS-MA□□□

\* For \_\_, enter the cable length (L), up to 20 meters. Example: 080=8 meters

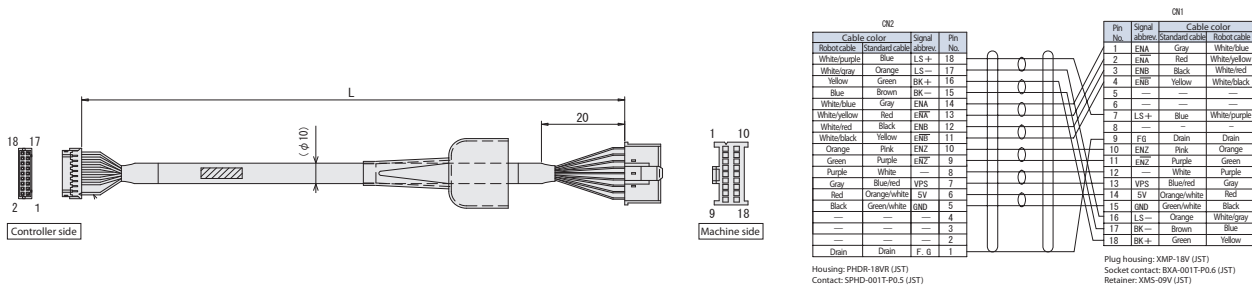


## RACON encoder cable

## Encoder cable/encoder robot cable

Model CB-ACS-PA□□□□/CB-ACS-PA□□□□-RB

\* The standard encoder cable is the normal cable. A robot cable is available as an option.  
\* For \_\_, enter the cable length (L), up to 20 meters. Example: 080=8 meters

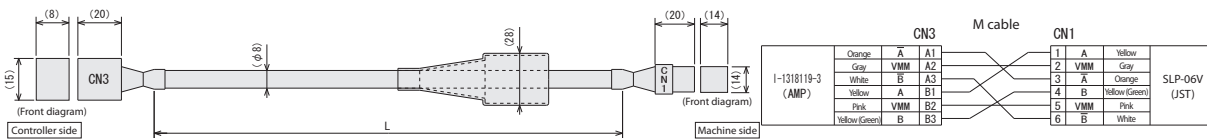


## RPCON motor cable

## Motor cable

Model CB-RCP2-MA□□□□

\* The standard motor cable is a robot cable. Can be selected  
\* For \_\_, enter the cable length (L), up to 20 meters. Example: 080=8 meters

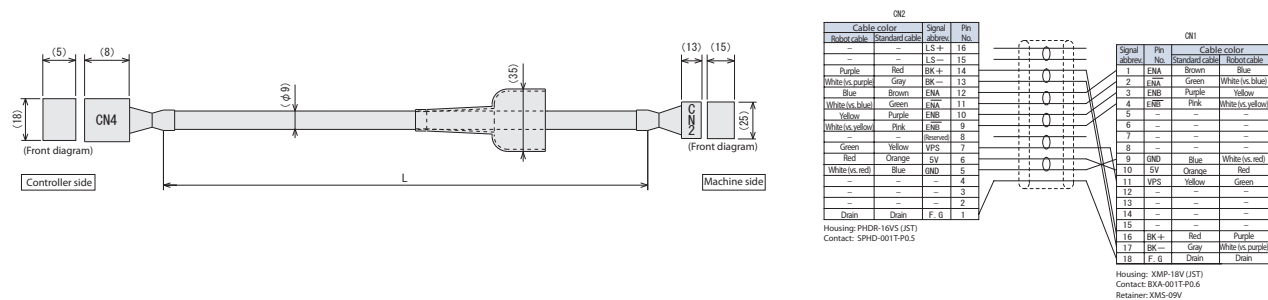


## RPCON encoder cable

## Encoder cable/encoder robot cable

Model CB-RCP2-PA□□□□/CB-RCP2-PA□□□□-RB

\* The standard encoder cable is the normal cable. A robot cable is available as an option.  
\* For \_\_, enter the cable length (L), up to 20 meters. Example: 080=8 meters





**IAI America, Inc.**

Head Office 2690W 237th Street Torrance CA 90505  
Chicago Office 1261 Hamilton Parkway Itasca, IL 60143  
Atlanta Office 1220 Kennestone Circle, Suite E, Marietta, GA 30066

**IAI SHANGHAI CO., LTD**

SHANGHAI JIAHUA BUSINESS CENTER A8404.808  
Hongqiao Rd. shanghai 200030, China

Homepage [www.intelligentactuator.com](http://www.intelligentactuator.com)

The contents of this catalog are subject to change without notice for the sake of product improvement.

**IAI Industrieroboter GmbH**

Ober der R6th 4, D-65824 Schwalbach am Taunus, Germany

