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32-BIT MICROCONTROLLER  
**MB9B618T/S SERIES**

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**ETHERNET BOOTLOADER  
MB9BF618T/S SOFTWARE**

APPLICATION NOTE

## Revision History

Version	Date	Updated by	Approved by	Modifications
0.1.0	2013-3-25	ChamberTeng		Initial version
0.2.0	2013-4-10	ChamberTeng		Add bootloader API functions
0.3.0	2013-4-22	QuinnXu		1. Update 1.1 overview, add update linkage for the Ethernet MAC driver 2. Update setup of HW in 6.3.3 3. Move the API introduction into appendix B 4. Add note in 6.4 5. Add AN number(MCU-AN-510048-E-10) on the coverage
0.4.0	2013-4-23	ChamberTeng		Delete function "Tftp_CalcSquare()" in sector 7

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# 1 Introduction

## 1.1 Overview

This document describes the implementation of an Ethernet boot loader which is based LwIP1.4.0 middleware and Fujitsu Ethernet driver library. Ethernet boot loader can be used to update user applications per Ethernet network.

This solution is designed primarily for Fujitsu microcontroller with existing evaluation boards.

The functions include:

- Supports TCP/IP stack, such as ICMP, ARP, IP, UDP (provided by LwIP1.4.0)
- Supports Ethernet MAC driver (provided by mb9bf61xt\_ethernet\_lwip library, the update can be found from [http://mcu.emea.fujitsu.com/mcu\\_product/mcu\\_all\\_software.htm](http://mcu.emea.fujitsu.com/mcu_product/mcu_all_software.htm))
- Supports static IP address assignment
- Optional flash security function
- Supports configuration of user code area

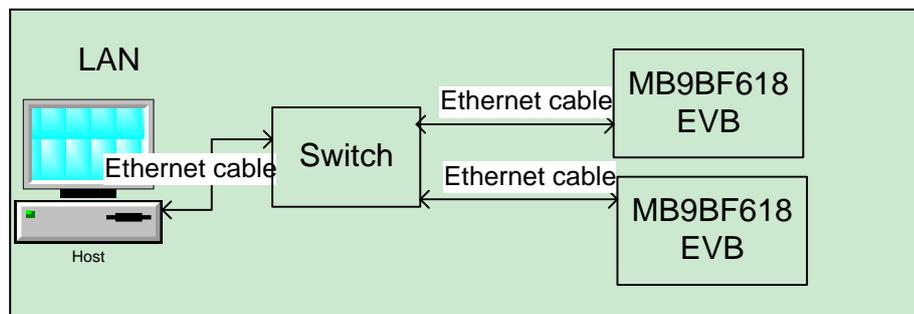


Figure 1 Interconnections

## 1.2 Reference Documents

- [1].MB9Bxxx-MN706-00002-4v0-E.pdf
- [2].MB9BF210T\_610T-MN706-00015-1v0-E.pdf
- [3].Design and Implementation of the LWIP TCP/IP Stack, Feb, 2001, Adam Dunkels.
- [4].MB9Bx10T-MN706-00014-1v0-E.pdf
- [5].MCU-AN-300411-E-V10-fm3\_usb\_host\_masstorage\_bootloader.pdf
- [6].FSS-MB9B618S-EV-Board-User-Manual.pdf

## 2 Hardware Environment

Hardware board

- FSSDC-9B618-EVB v1.0

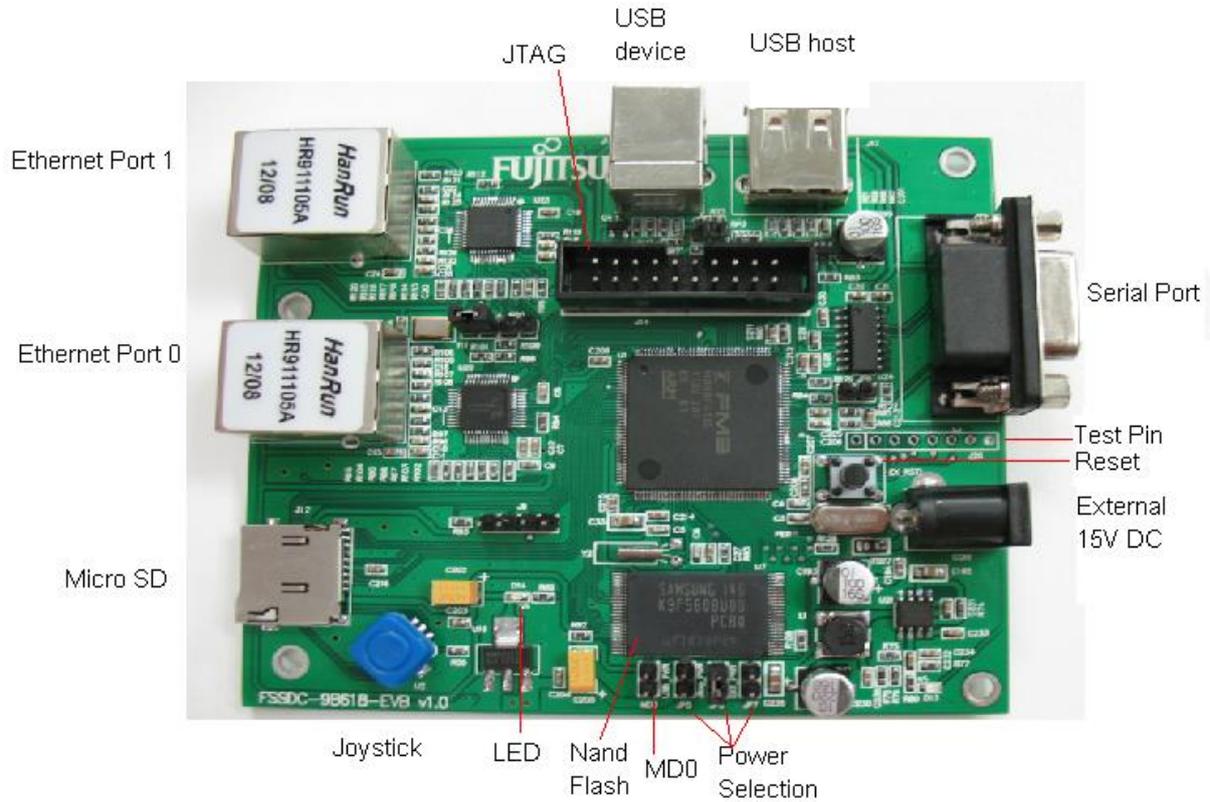


Figure 2 FSSDC-9B618-EVB v1.0

MCU: Fujitsu MB9BF618S

- MCU Frequency: 144MHz
- Ram Space: 128 K bytes
- Code Space: 1 M bytes

### 3 Development Environment

Name	Description	Part Number	Manufacturer	Remark
IAR EWARM	Software Developing IDE	V6.50	IAR	
J-link	MCU Emulator	J-link	IAR	

# 4 Features

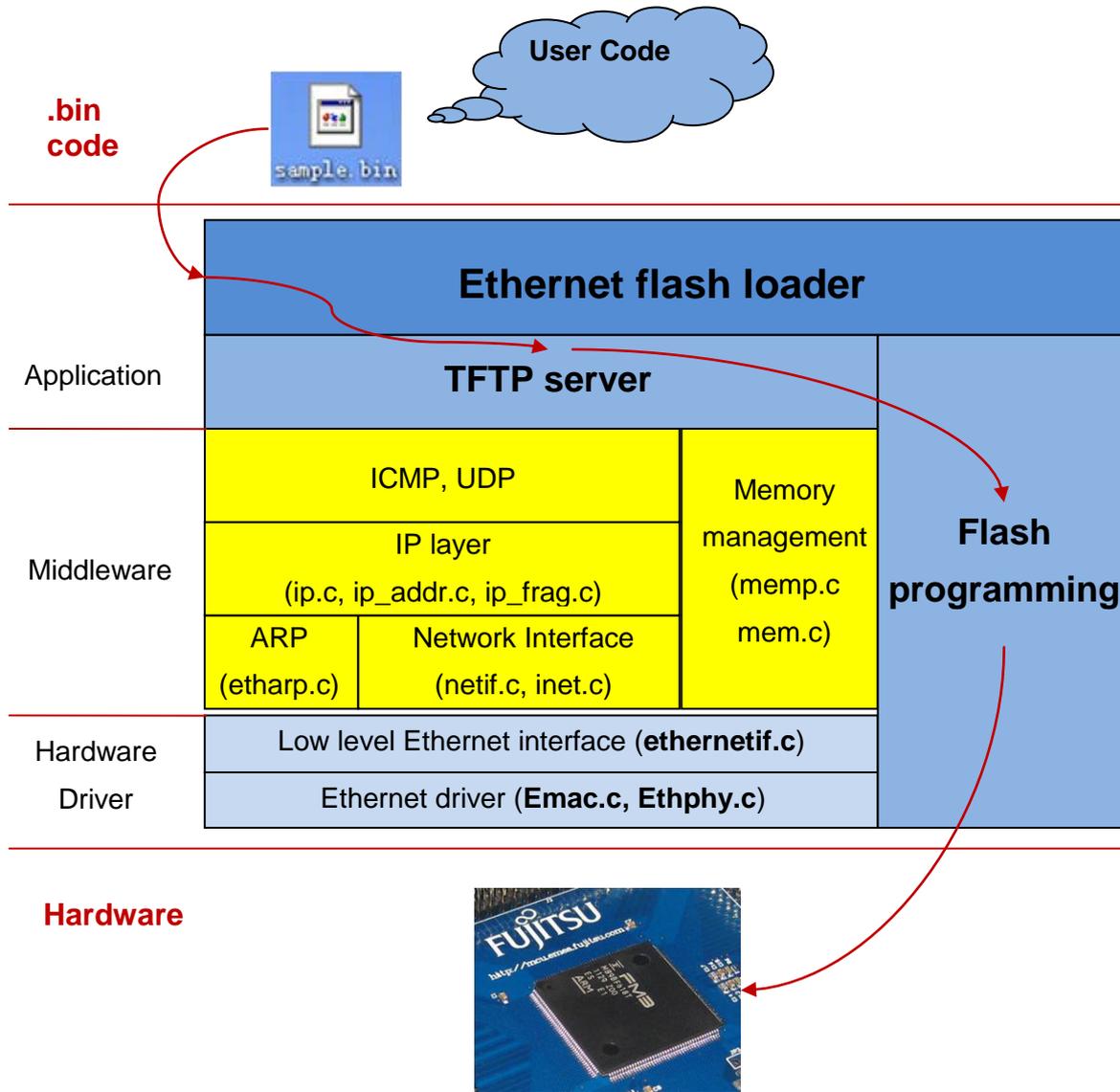


Figure 3 project block diagram

- Hardware Driver— FM3 Ethernet driver
- Middleware— LwIP 1.4.0
- Application— TFTP server
- Flash programming— MCU internal flash
- Ethernet flash loader— contains TFTP server and flash programming driver

## 5 Bootloader operations

### 5.1 Project Structure

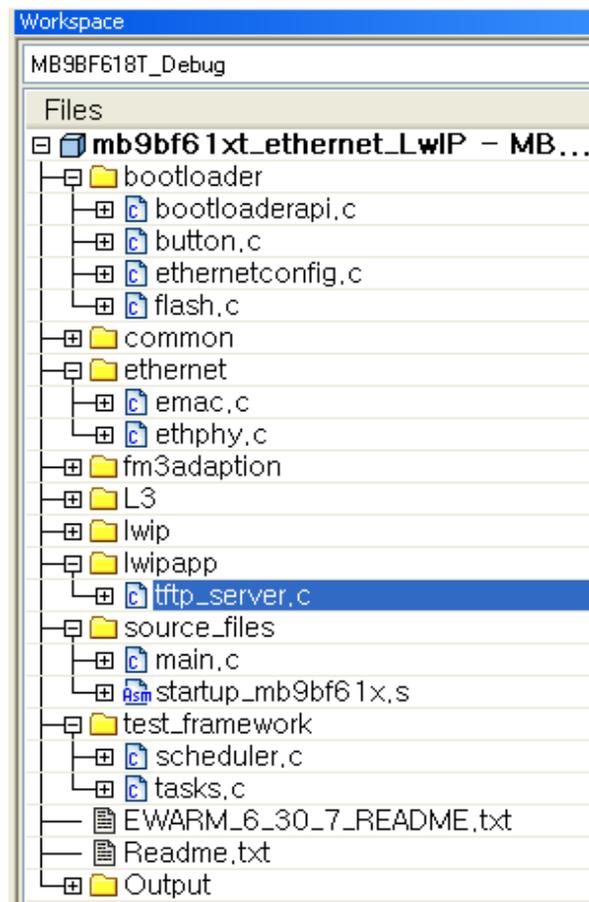


Figure 4 project structure

### 5.2 Main loop

Before initializing boot loader, the main loop checks the following items:

- Specified flash validation
- Start-up key button status

Figure 5 is the software procedure of running mode selection.

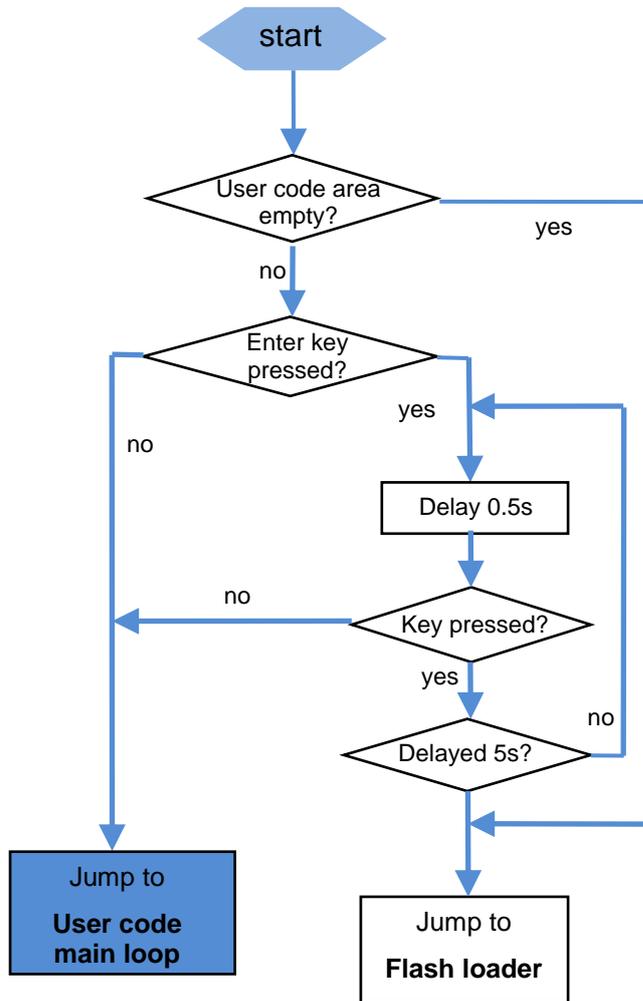


Figure 5 run mode judgement

### 5.3 Memory map

As described in the Technical Reference Manual of ARM for Cortex-M3 core, ARM Cortex M3 microcontrollers have its flash memory starting at 0x0000\_0000, RAM memory starting at 0x2000\_0000 and so on.

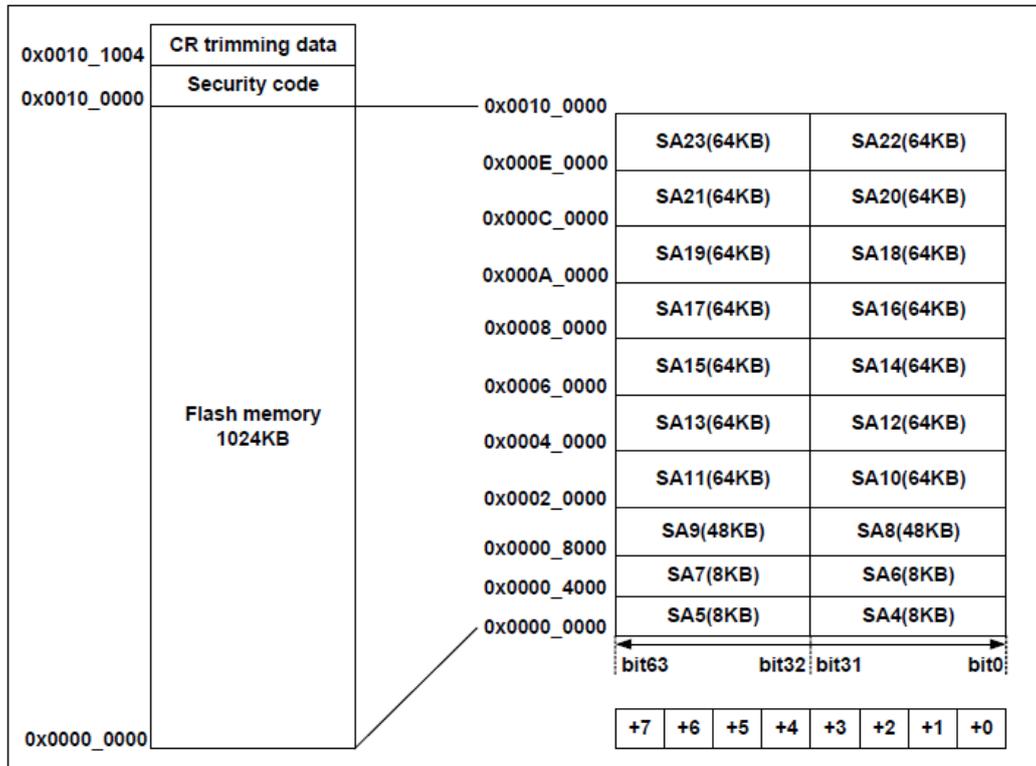


Figure 6 M9BF618S flash memory map

As defined for ARM Cortex-M3 MCUs, the vector table starts with the stack pointer followed by the reset vector and so on.

The vector table of the bootloader is fixed to 0x0000\_0000 and the user code must be linked to upper areas of the flash memories. For Fujitsu Ethernet bootloader, the user code starts from 0x0002\_0000.

The code allocation of this demo as follows:

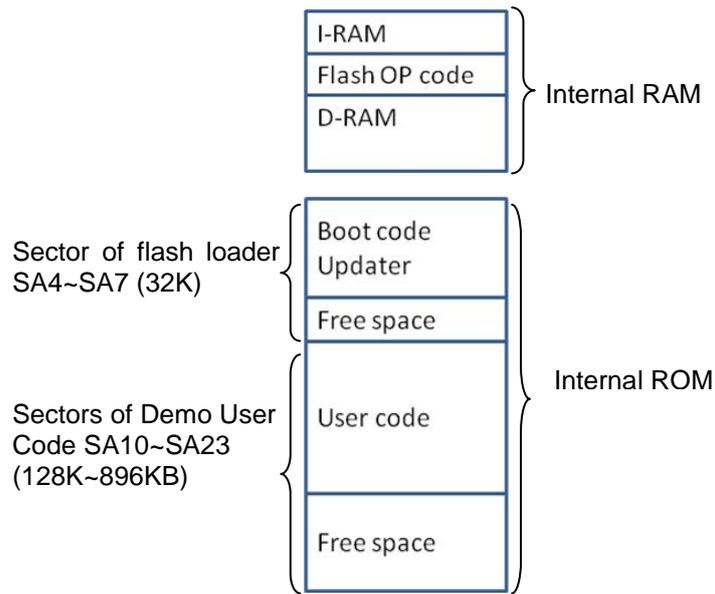


Figure 7 code allocation

The Ethernet loader code of MCU will be allocated at the SA4~SA7.

The user application program will be allocated at SA10~SA23, whose vector table shall be placed at the beginning of the sector.

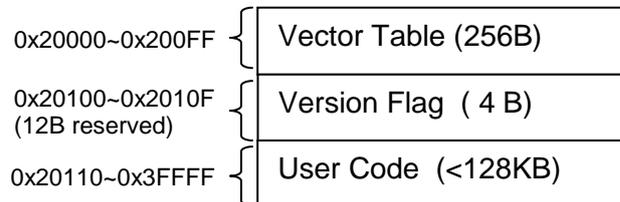


Figure 8 sample memory (Maximum: 128KB)

Maximum code size can be defined by customer, using settings in `bootloader\bootloader.h`. The maximum size can reach up to 896KB.

## 5.4 Jump into user application

To start the user application code, the stack pointer and vector table must be updated. Following procedure is called, to start the user application code, linked to 0x0002\_0000:

```
#define USER_FLASH_START 0x00020000

/**
*****
*****
** \brief Jump to user code application
**
** \param u32Address Address of user code
** \return none
*****
*****/
#ifdef __ICCARM__
void BootloaderAPI_JumpBoot(uint32_t u32Address)
{
    __asm("LDR SP, [R0]"); //Load new stack pointer address
    __asm("LDR PC, [R0, #4]"); //Load new program counter address
}
#elif __CC_ARM
__asm void BootloaderAPI_JumpBoot(uint32_t u32Address)
{
    LDR SP, [R0] ;Load new stack pointer address
    LDR PC, [R0, #4] ;Load new program counter address
}
#else
#error
/**
*****
*****
** \brief Execute main application
**
** \param none
** \return none
*****
*****/
void BootloaderAPI_ExecuteUserApplication(void)
{
    //Change the Vector Table to the USER_FLASH_START
    SCB->VTOR = USER_FLASH_START & 0x1FFFFFF80;
    BootloaderAPI_JumpBoot(USER_FLASH_START);
}

```

## 5.5 Linker settings

For using bootloader, linker settings must be changed, including:

- Bootloader project linker settings  
It is configured in project, no need to change.
- User application project linker settings  
This one must be set in the user application projects.

### 5.5.1 Bootloader linker settings

When writing data into internal flash, flash operations must be copied into RAM to process.

This can be configured in the linker files normally done by the IDE start-up code. The ROM (flash) area should be set to use only 0x0000\_0000 to 0x0000\_7FFF.

To copy Flash erase/programming routines to RAM automatically after start-up and be executed later in RAM, the following lines should be added to the linker file (\*.icf):

```
define symbol __RAM_func_start__ = 0x20000000;
define symbol __RAM_func_end__   = 0x20007FFF;
define region RAM_func_region    = mem:[from __RAM_func_start__
to __RAM_func_end__];
define block RamCode {section .flash_ram_code};
place in RAM_func_region { block RamCode };
```

### 5.5.2 User application code linker settings

To coordinate the application start address in bootloader project, the following lines should be re added in the standard FM3 template linker files (\*.icf):

```
/*-Specials-*/
define symbol __ICFEDIT_intvec_start__ = 0x00020000;
/*-Memory Regions-*/
define symbol __ICFEDIT_region_ROM_start__ = 0x00020000;
```

This can be done also via Project -> Options -> Linker, where .intvec start and ROM start can be specified as well.

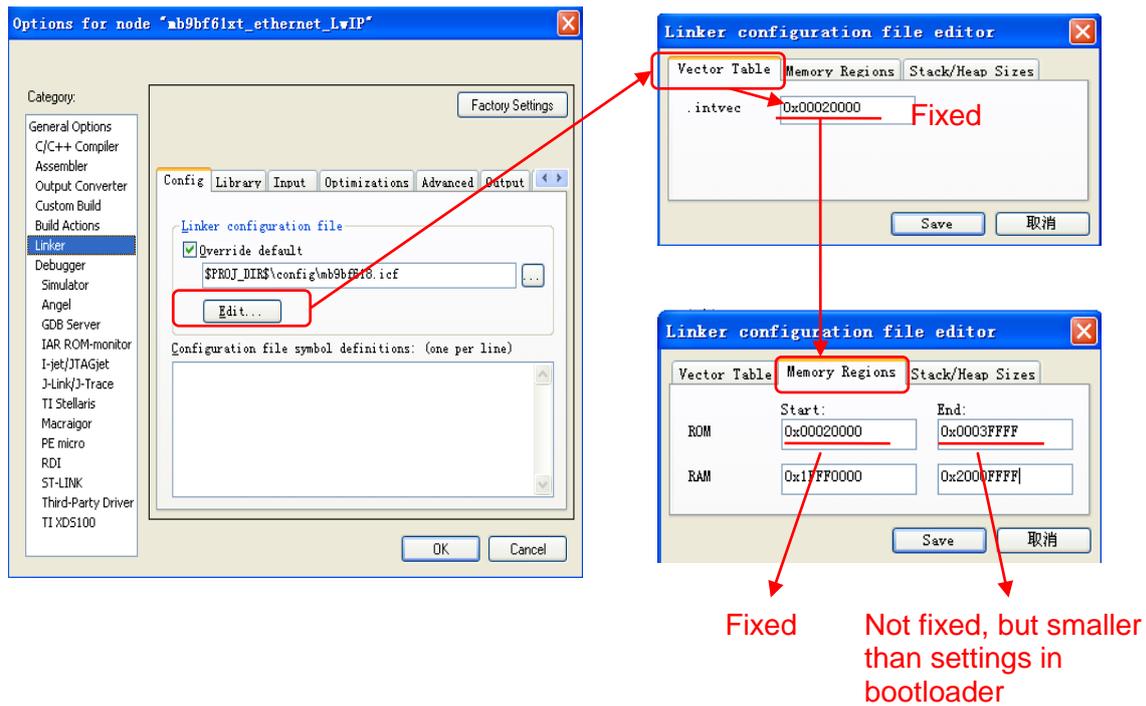


Figure 9 user code project settings

### 5.6 User application code version number settings

Step 1: Define version information array

```
#pragma location = ".INFORSEC" //INFORSEC
const char sVersion[16] = {'V','1','.','0',0,0,0,0,0,0,0,0,0,0,0,0};
```

Step 2: Quote version information array in main() function

```
char *addr = (char *)sVersion;
```

Step 3: Add memory placement command to \*.icf file.

```
place in ROM_region { readonly };
place in RAM_region { readwrite,
    block CSTACK, block HEAP };
place at address mem:0x00020100 { section .INFORSEC};
```

This command is used to locate variables of sVersion to 0x0002\_0100.

## 6 Quick start using FSSDC-9B618-EVB v1.0

### 6.1 Download Bootloader to Flash

To use Ethernet bootloader, customer must download the bootloader code to MCU flash.

Demo board FSSDC-9B618-EVB v1.0 support On-Board Programming via USB. This is convenient to download bootloader code to flash.

#### 6.1.1 Settings for USB On-Board Programming

- Hardware settings below:

Connector	Function	Setting
MD0	Mode setting	short
JP9	USB programming	short

- When connecting with PC via USB cable, the EVB can be identified as a USB device after power on.

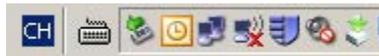


Figure 10 USB device Sign

- Check the COM port for this USB device in the device manager.

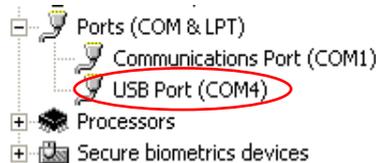


Figure 11 COM Port in Device Manager

- Install the USB programmer: usbdirect-v01i07.zip. (It can be downloaded from Fujitsu official website)
- Run the software and set the parameter as shown in following figures, and select Hex file. Click “**Full Operation**” button.

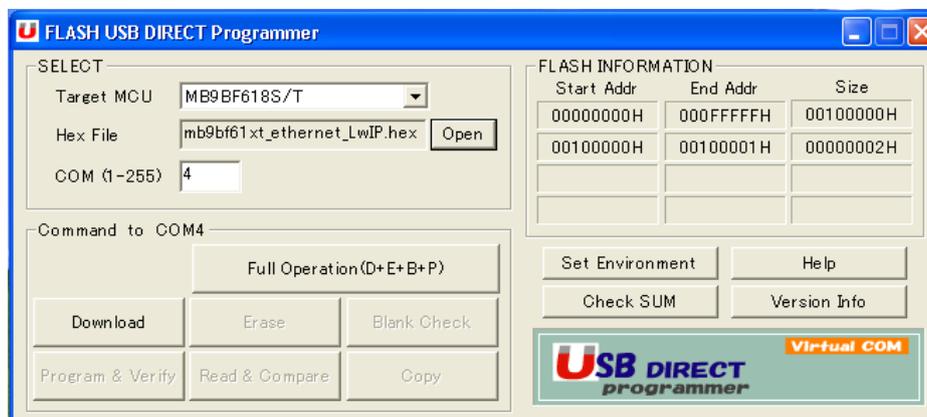


Figure 12 settings of USB programmer

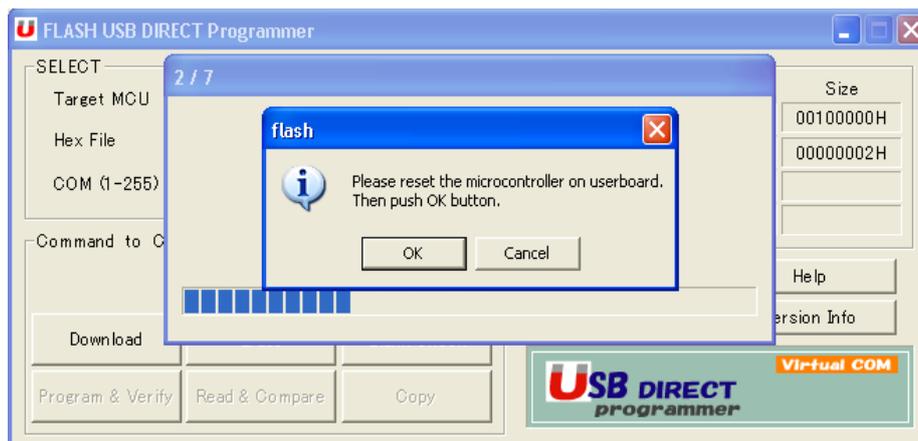


Figure 13 reset message during programming

- Reset EVB first and then press “OK” button in USB programmer

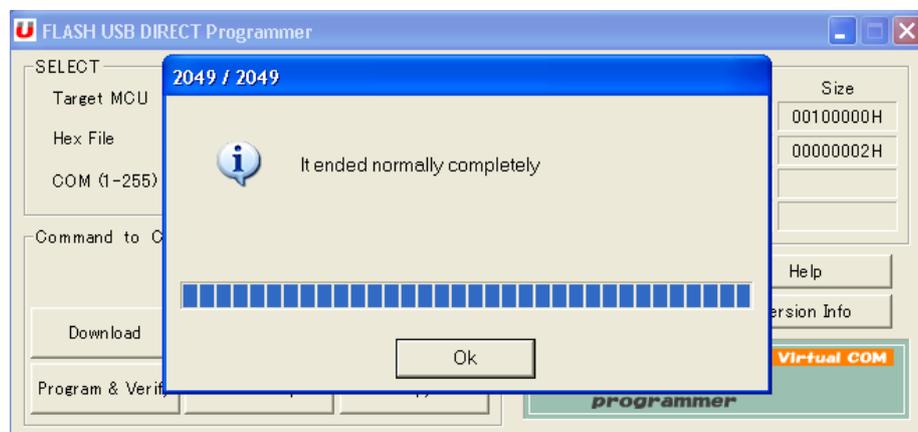


Figure 14 programming complete successfully

Please refer to [FSS-MB9B618S-EV-Board-User-Manual.pdf](#) for the details.

## 6.2 Configure User Application Code

Customer must set user application code as mentioned in sector 5.5.2 and 5.6.

Set user application code linker settings.

- >Vector Start Address: set to 0x0002\_0000
- >Memory Regions: set Rom Start address to 0x0002\_0000
- >Rom End address depends on the code size

Then, configure user code version information as described in sector 5.6 and build the user code into binary file.

## 6.3 Download User Code to Flash

### 6.3.1 Enter Ethernet bootloader mode

If user code flash area is empty (no user code), the MCU will enter bootloader mode directly after power on. And LED “D14” will turn ON when running in bootloader mode.

If user code exists in the specified flash area, MCU may execute user application code directly. At this condition, we have two methods to enter bootloader mode.

Method 1:

Press joystick OK button (middle button of the joystick) without release, then power on the demo board. After 5 seconds, LED “D14” will turn on indicating demo board enters bootloader mode. Then release the button.

Method 2:

When demo board is power on, the existing user application will be executed. Press the joystick OK button without release. Then press reset key (EX\_RST1) to reset MCU. After 5 seconds, the D14 turns on indicating demo board enters bootloader mode. Then release the button. Then release the button.

### 6.3.2 Configure TFTP Client Settings

We need a TFTP client to transmit user application code to internal flash.

For this demo, we choose 3CDaemon.exe to serve as a TFTP client.

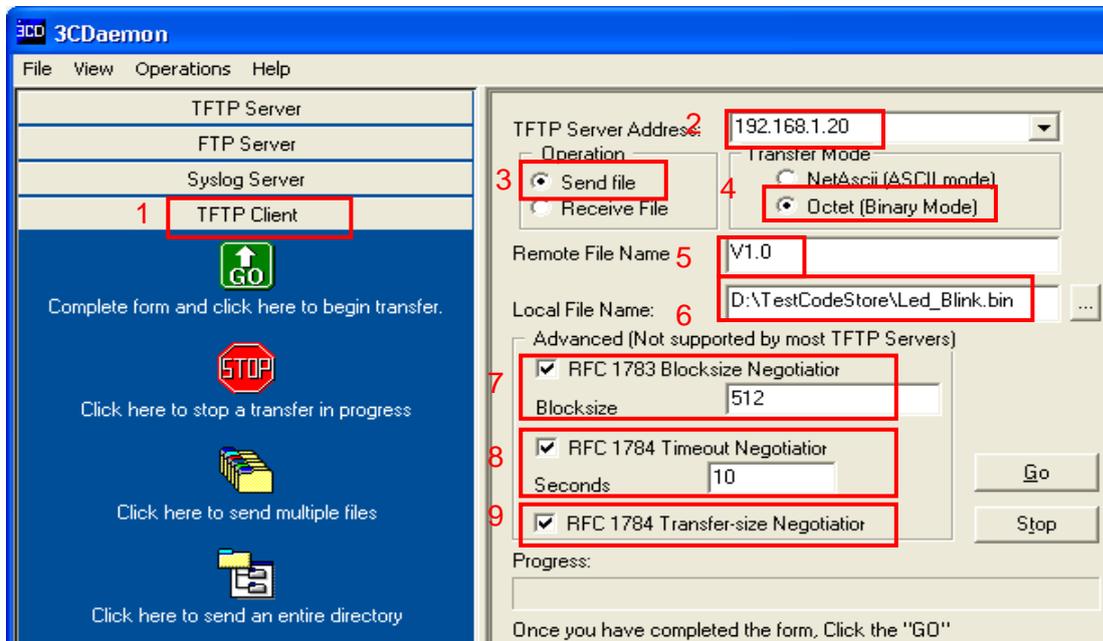


Figure 15 TFTP client settings

1. Set to TFTP client mode
2. Set TFTP Server Address to "192.168.1.20"
3. Set Operation mode:
  - >Write flash: choose Send file
  - >Read flash: choose Receive file
4. Set Transfer Mode to "Octet (Binary Mode)"
5. Fill Remote File Name with version information
  - >Version Format: "Vx.x" (example: V1.0/ V1.1/ V2.0/ V2.3)
  - Please control the version number and format as the examples.
6. Set Local File to the target test code routine, and select the Test\_LED.bin file
7. Select RFC 1783 Blocksize Negotiation
8. Select RFC 1784 Timeout Negotiation and set seconds to 10
9. Select RFC 1784 Transfer-size Negotiation.

### 6.3.3 Flash Empty

To describe execute steps clear, several operations will be shown below.

Before running, customer must confirm user application code project's linker settings and version number settings are correct. Compile and build the binary file (.BIN). Any unclear, please refer to chapter 5.5 and chapter 5.6.

After download bootloader code into internal flash, specified user application code area is default empty.

Power on the demo board, system will enter bootloader mode directly.

1. Configure TFTP client settings as Figure 10
2. Power on the EVB with Ethernet cable plugged into Ethernet Port0 (J1)
3. After PC assigned IP address, press 3C Daemon “Go” button to download user code.

After datagram transferred successfully, demo board will execute the sample code and 3C Daemon will display like below:

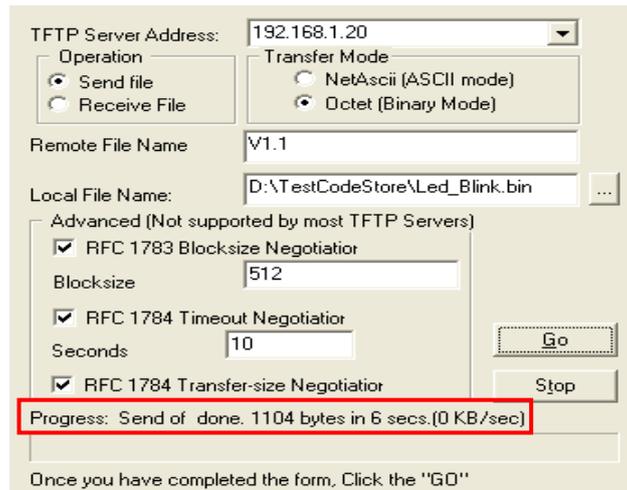


Figure 16 data transferred successfully

### 6.3.4 Flash with User Code

This part will describe the condition when user code is already in flash.

Use the steps in chapter 6.2.1 to enter bootloader mode.

Please confirm typing correct commands in “Remote File Name” of 3C Daemon window.

Version number should be same with the settings in user code project (refer to chapter 5.6).

If version is lower or the same as the code in flash already. TFTP client will display error command as below:

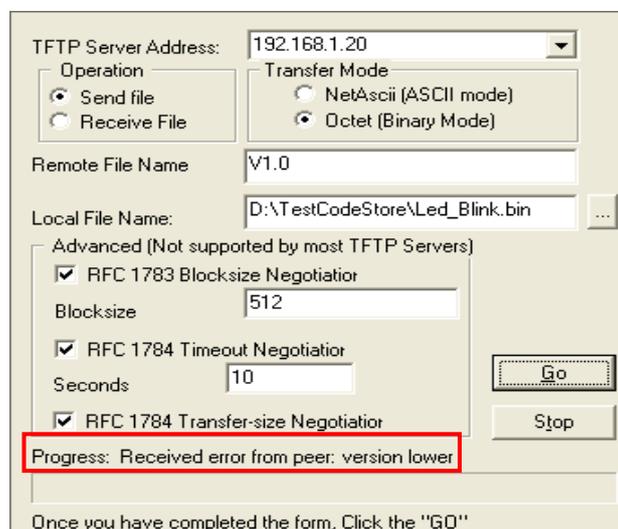


Figure 17 code version number lower

If code size is bigger than the defined size in bootloader, 3CDAemon will display error command “Progress: Received error from peer: code oversize.”

If format of version number is not correct, 3CDAemon will display “Progress: version format error”

## 6.4 Read User Code in Flash

All steps are the same as flash empty section (6.3.3) except changing operation mode to “Receive File” in 3CDAemon.

If Flash is secured (address 0x0010\_0000 is written with “0x0001”) , as well as the macro definition of **ENABLE\_FLASH\_SECURITY** (in bootloader.h) is enabled, the user code can’t be read out. And 3CDAemon will display error message” Progress: Received error from peer: flash security secured, can't be read. ”

### Note:

**The only way to make the use code readable is by erasing the security bit of MCU flash with Fujitsu USB on board program tool (chip erase) and then flash the use code again.**

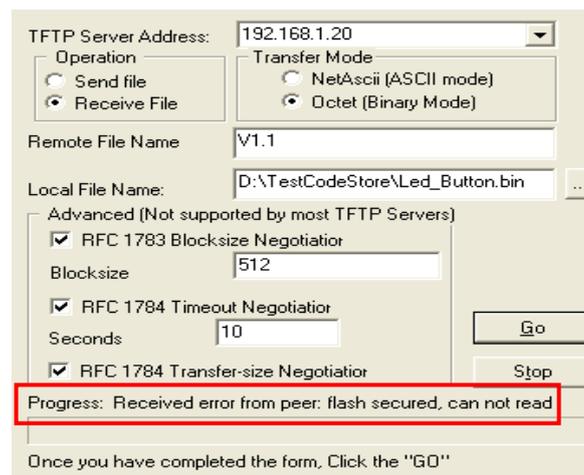


Figure 18 flash secured

## 6.5 Erase User Code in Flash

This demo supports erase user code flash area through using special command. Configure 3CDAemon.exe settings as figure 14.

Type command “Erase” in Remote File Name. Then press “Go” button.

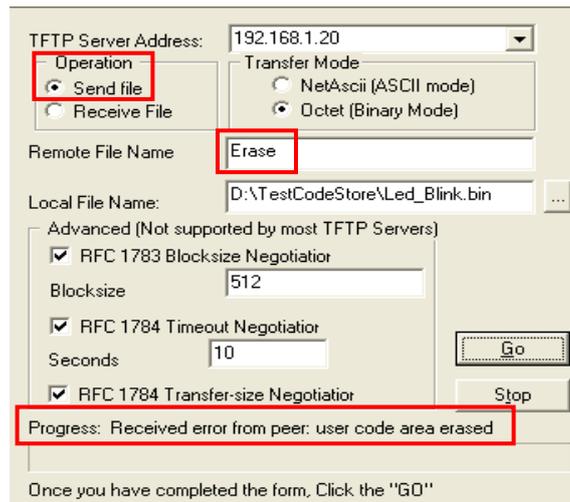


Figure 19 erase user code area

After user code area erased, 3CDaemon will display “Progress: Received error from peer: user code area erased.”

Notes:

***This command will erase all flash sectors of user applications after 0x00020000.***

## 7 Bootloader API functions

Refer to Appendix B for more details:

### 1. Bootloader module

- uint16\_t Bootloader\_ReadFlashSecurityBit(void);
- void Bootloader\_JumpBoot(uint32\_t u32Address);
- void Bootloader\_ExecuteUserApplication(void);
- boolean\_t Bootloader\_UserCodeValid(void);
- boolean\_t Bootloader\_CheckEmpty(void);
- void Bootloader\_EraseChip(void);
- void Bootloader\_ExecuteSoftwareReset(void);
- en\_run\_mode\_t Bootloader\_JudgeRunMode(void);
- static void ConfigureEthernetPins(void);
- int32\_t Bootloader\_EthernetIAPInit(void);
- static void LED\_Init(void);

### 2. Flash module

- int32\_t FlashRomEraseSector(uint32\_t u32SectorEraseAddress);
- int32\_t FlashDataPolling (uint32\_t u32PollAddress, uint16\_t u16PollData);
- int32\_t FlashRomProgram(uint32\_t u32ProgramAddress, uint16\_t u16ProgamData) ;

### 4. Tftp server module

- `uint32_t Tftp-DecompressPktLenth(uint8_t *pu8PktBuf);`
- `static void Tftp-SendBaseMessage( struct udp_pcb *upcb, struct ip_addr *addr,uint16_t port, uint8_t *buf,uint16_t buflen)`
- `void Tftp-SendAckPkt( struct udp_pcb *upcb, struct ip_addr * addr, uint16_t port, uint16_t block)`
- `void Tftp-SendErrorPkt( struct udp_pcb *upcb, struct ip_addr * addr, uint16_t port, uint8_t u8ErrorType)`
- `void Tftp-SendDatagramPkt( struct udp_pcb *upcb, struct ip_addr * addr, uint16_t port, uint16_t block,uint8_t *data,uint16_t datalenth)`
- `void Tftp-RRQRecvedCallback( void *args, struct udp_pcb *upcb, struct pbuf *pkt_buf, struct ip_addr *addr, u16_t port)`
- `void Tftp-WRQRecvedCallback( void *args, struct udp_pcb *upcb, struct pbuf *pkt_buf, struct ip_addr *addr, u16_t port)`
- `void Tftp-WRQRecved(struct udp_pcb *upcb, struct ip_addr *IpAddr, uint16_t port,struct pbuf *pkt_buf)`
- `void Tftp-RRQRecved(struct udp_pcb *upcb, struct ip_addr *IpAddr, uint16_t port, struct pbuf *pkt_buf)`
- `void Tftp-RecvCallback(void *arg, struct udp_pcb *upcb, struct pbuf *pkt_buf, struct ip_addr *addr, u16_t port)`
- `void Tftp_server_init(void)`

## Appendix A    More Information

For more Information on FUJITSU semiconductor products, visit the following websites:

English version address:

<http://www.fujitsu.com/global/services/microelectronics/product/micom/support/sample/fm3.html>

[http://mcu.emea.fujitsu.com/mcu\\_product/mcu\\_all\\_software.htm](http://mcu.emea.fujitsu.com/mcu_product/mcu_all_software.htm)

<http://www.fujitsu.com/cn/fss/mcu/lineup/fm3/>

## Appendix B API List

### Bootloader module

#### Bootloader\_ReadFlashSecurityBit

Read flash security statement

**Prototype:**

uint16\_t Bootloader\_ReadFlashSecurityBit (void);

**Para:**

None

**Return:**

uint16\_t: the stored value of flash security bit

**Describe:**

**Note:**

#### Bootloader\_JumpBoot

Jump to user code application

**Prototype:**

void Bootloader\_JumpBoot(uint32\_t u32Address);

**Parameter:**

u32Address: Address of user code

**Return:**

None

**Describe:**

**Note:**

#### Bootloader\_ExecuteUserApplication

Execute user application code

**Prototype:**

void Bootloader\_ExecuteUserApplication(void);

**Parameter:**

None

**Return:**

None

**Describe:**

**Note:**

### Bootloader\_UserCodeValid

Judge whether the user code is valid

**Prototype:**

```
boolean_t Bootloader_UserCodeValid(void);
```

**Parameter:**

None

**Return:**

*Bootlean\_t:*

*TRUE: user code is valid*

*FALSE : user code is not valid*

**Describe:**

*This function will judge whether the bootloader user code area is empty and user code is valid.*

**Note:**

### Bootloader\_CheckEmpty

Check whether user code area is empty

**Prototype:**

```
boolean_t Bootloader_CheckEmpty(void);
```

**Parameter:**

None

**Return:**

*TRUE : user code area is empty*

*FALSE : user code area is not empty*

**Describe:**

*This function will judge user code area. And return memory statement*

**Note:**

### Bootloader\_EraseChip

Erase user code area flash memory

**Prototype:**

```
void Bootloader_EraseChip(void);
```

**Parameter:**

*None*

**Return:**

*None*

**Describe:**

*This function will erase user code area directly*

**Note:**

### Bootloader\_ExecuteSoftwareReset

Software reset the code

**Prototype:**

```
void Bootloader_ExecuteSoftwareReset (void);
```

**Parameter:**

*None*

**Return:**

*None*

**Describe:**

*Software reset the code*

**Note:**

### Bootloader\_JudgeRunMode

Judge which mode to run

**Prototype:**

```
en_run_mode_t Bootloader_JudgeRunMode(void);
```

**Parameter:**

*None*

**Return:**

en\_run\_mode\_t:

USER\_MODE:

BOOTLOADER\_MODE:

**Describe:**

*Judge which mode to run. If return BOOTLOADER\_MODE, the program will run bootloader code, else run the user application code*

**Note:**

### Bootloader\_ConfigureEthernetPins

Configure general IO ports for Ethernet pins

**Prototype:**

```
void Bootloader_ConfigureEthernetPins(void);
```

**Parameter:**

*None*

**Return:**

*None*

**Describe:**

*Configure the IO ports for Ethernet EMAC0/EMAC1*

**Note:**

### Bootloader\_EthernetIAPInit

Initial Ethernet IAP function

**Prototype:**

```
int32_t Bootloader_EthernetIAPInit(void)
```

**Parameter:**

*None*

**Return:**

*int32\_t*

**Describe:**

*Initial Ethernet IAP*

**Note:**

### LED\_Init

Initial IO ports for LED control

**Prototype:**

```
void LED_Init (void);
```

**Parameter:**

None

**Return:**

None

**Describe:**

Initial IO ports for LED state control

**Note:****Flash module****FlashRomEraseSector**

Initial Ethernet IAP function

**Prototype:**

int32\_t FlashRomEraseSector(uint32\_t u32SectorEraseAddress)

**Parameter:**

*u32SectorEraseAddress* :

*flash sector address need to be erase*

**Return:**

*int32\_t* :

*FLASH\_OK*

*FLASH\_ERROR*

**Describe:**

*Erase one flash sector*

**Note:****FlashDataPolling**

Data Polling alogithm

**Prototype:**

int32\_t FlashDataPolling (uint32\_t u32PollAddress, uint16\_t u16PollData)

**Parameter:**

*u32PollAddress*: *Polling address*

*u16PollData* : *Polling data*

**Return:**

*int32\_t* :

*FLASH\_OK* : *flash polling OK*

*FLASH\_TIMEOUT* : *flash polling error*

**Describe:**

*A flash data polling algorithm*

**Note:****FlashRomProgram**

Write data to specified flash area

**Prototype:**

```
int32_t FlashRomProgram(uint32_t u32ProgramAddress, uint16_t u16ProgamData)
```

**Parameter:**

*u32ProgramAddress: target address*

*u16ProgamData : specified data*

**Return:**

*int32\_t :*

*FLASH\_OK : flash polling OK*

*FLASH\_TIMEOUT : flash polling error*

**Describe:**

*This function is mainly at write data to flash memory*

**Note:**

- 1. It only can write half-word(16 bit) data to flash memory*
- 2. u32ProgramAddress must be even value*

**Tftp server module****Tftp\_DecompressPktLenth**

Decompress total packet length of Tftp trans file

**Prototype:**

```
uint32_t Tftp_DecompressPktLenth(uint8_t *pu8PktBuf)
```

**Parameter:**

*pu8PktBuf: datagram packet buffer*

**Return:**

*uint32\_t: datagram packet total length*

**Describe:**

*This function can decompress total length of file*

**Note:** *This decompress function is only for WRQ request*

## Tftp\_SendBaseMessage

Send basic data packet using UDP protocol

**Prototype:**

```
void Tftp_SendBaseMessage(struct udp_pcb *upcb,  
                          struct ip_addr *addr,  
                          uint16_t port,  
                          uint8_t *buf,  
                          uint16_t buflen))
```

**Parameter:**

*upcb*: udp pcb to be send  
*addr*: ip address  
*port*: port number need to be bind  
*buf*: datagram packet buffer  
*buflen*: datagram packet buffer length

**Return:**

*None*

**Describe:**

**Note:**

## Tftp\_SendAckPkt

Sendback Ack to Tftp client

**Prototype:**

```
void Tftp_SendAckPkt (struct udp_pcb *upcb,  
                     struct ip_addr *addr,  
                     uint16_t port,  
                     uint16_t block)
```

**Parameter:**

*upcb*: udp pcb to be send  
*addr*: ip address  
*port*: port number need to be bind  
*block*: Ack block number

**Return:**

*None*

**Describe:**

*Tftp server send Ack packet to client for feedback*

**Note:**

### Tftp\_SendErrorPkt

Sendback ERROR packet to Tftp client

**Prototype:**

```
void Tftp_SendErrorPkt (struct udp_pcb *upcb,  
                        struct ip_addr *addr,  
                        uint16_t port,  
                        uint8_t u8ErrorType)
```

**Parameter:**

*upcb: udp pcb to be send*

*addr: ip address*

*port: port number need to be bind*

*u8ErrorType:*

```
    ERRORTYPE_SECURITY_ENABLED ;  
    ERRORTYPE_VERSION_LOWER  
    ERRORTYPE_VERSION_NOTSET  
    ERRORTYPE_CODESIZE_OVERFLOW  
    ERRORTYPE_ERASE_CHIP  
    ERRORTYPE_FLASHWRITE_ERROR
```

**Return:**

*None*

**Describe:**

*Tftp server send Error packet to client for feedback*

**Note:**

### Tftp\_SendDatagramPkt

Sendback Ack to Tftp client

**Prototype:**

```
void Tftp_SendDatagramPkt (struct udp_pcb *upcb,  
                            struct ip_addr *addr,  
                            uint16_t port,  
                            uint16_t block,  
                            uint8_t *data,  
                            uint16_t datalenth)
```

**Parameter:**

*upcb*: udp pcb to be send  
*addr*: ip address  
*port*: port number need to be bind  
*block*: Ack block number  
*data* : data buffer  
*datalenth* : length of data buffer

**Return:**

None

**Describe:**

*Tftp server send datagram packet to client, and it can control datagram length*

**Note:**

## Tftp\_RRQRecvedCallback

Callback function when RRQ request received

**Prototype:**

```
void Tftp_RRQRecvedCallback( void *args,  
                             struct udp_pcb *upcb,  
                             struct pbuf *pkt_buf,  
                             struct ip_addr *addr,  
                             uint16_t u16_t port,)
```

**Parameter:**

Args: user supplied argument to match the callback function  
*upcb*: udp pcb to be send  
*pkt\_buf*: buffer stored with data packet  
*port*: port number need to be bind

**Return:**

None

**Describe:**

*This is a callback function when Tftp server received RRQ request*

**Note:**

## Tftp\_WRQRecvedCallback

Callback function when WRQ request received

**Prototype:**

```
void Tftp_WRQRecvedCallback( void *args,
```

```
struct udp_pcb *upcb,  
struct pbuf *pkt_buf,  
struct ip_addr *addr,  
uint16_t u16_t port,)
```

**Parameter:**

*Args: user supplied argument to match the callback function*

*upcb: udp pcb to be send*

*pkt\_buf: buffer stored with data packet*

*port: port number need to be bind*

**Return:**

*None*

**Describe:**

*This is a callback function when Tftp server received WRQ request*

**Note:****Tftp\_WRQRecved**

Callback function when WRQ request received

**Prototype:**

```
void Tftp_WRQRecved ( struct udp_pcb *upcb,  
                     struct ip_addr *IpAddr,  
                     uint16_t port,  
                     struct pbuf *pkt_buf)
```

**Parameter:**

*upcb: udp pcb to be send*

*IpAddr: IP address*

*port: port number need to be bind*

*pkt\_buf: buffer stored with data packet*

**Return:**

*None*

**Describe:**

*Some operations when WRQ request received*

**Note:****Tftp\_RRQRecved**

Callback function when RRQ request received

**Prototype:**

```
void Tftp_RRQRecved ( struct udp_pcb *upcb,  
                    struct ip_addr *IpAddr,  
                    uint16_t port,  
                    struct pbuf *pkt_buf)
```

**Parameter:**

*upcb: udp pcb to be send*

*IpAddr: IP address*

*port: port number need to be bind*

*pkt\_buf: buffer stored with data packet*

**Return:**

*None*

**Describe:**

*Some operations when RRQ request received*

**Note:****Tftp\_RecvCallback**

Callback function when received data through UDP protocol

**Prototype:**

```
void Tftp_RecvCallback ( void *arg,  
                        struct udp_pcb *upcb,  
                        struct pbuf *pkt_buf ,  
                        struct ip_addr *addr  
                        u16_t port)
```

**Parameter:**

*arg: user supplied argument to match the callback function*

*upcb: udp pcb to be send*

*pkt\_buf: buffer stored with data packet*

*addr: IP address*

*port: port number need to be bind*

**Return:**

*None*

**Describe:**

*Some operations when received data through UDP protocol*

**Note:**

## Tftp\_server\_init

Initial tftp server

**Prototype:**

void Tftp\_server\_init (void)

**Parameter:**

*None*

**Return:**

*None*

**Describe:**

*Initial tftp server*

**Note:**