

Preliminary



SMT128

User Manual

Revision History

Date	Comments	Engineer	Version
13/6/00	Initial version	AJP	1.0
05/9/00	Second Revision	AJP	1.1
07/01/02	Modifications	AJP	1.2
26/02/02	Several Modifications Made	BM	1.3

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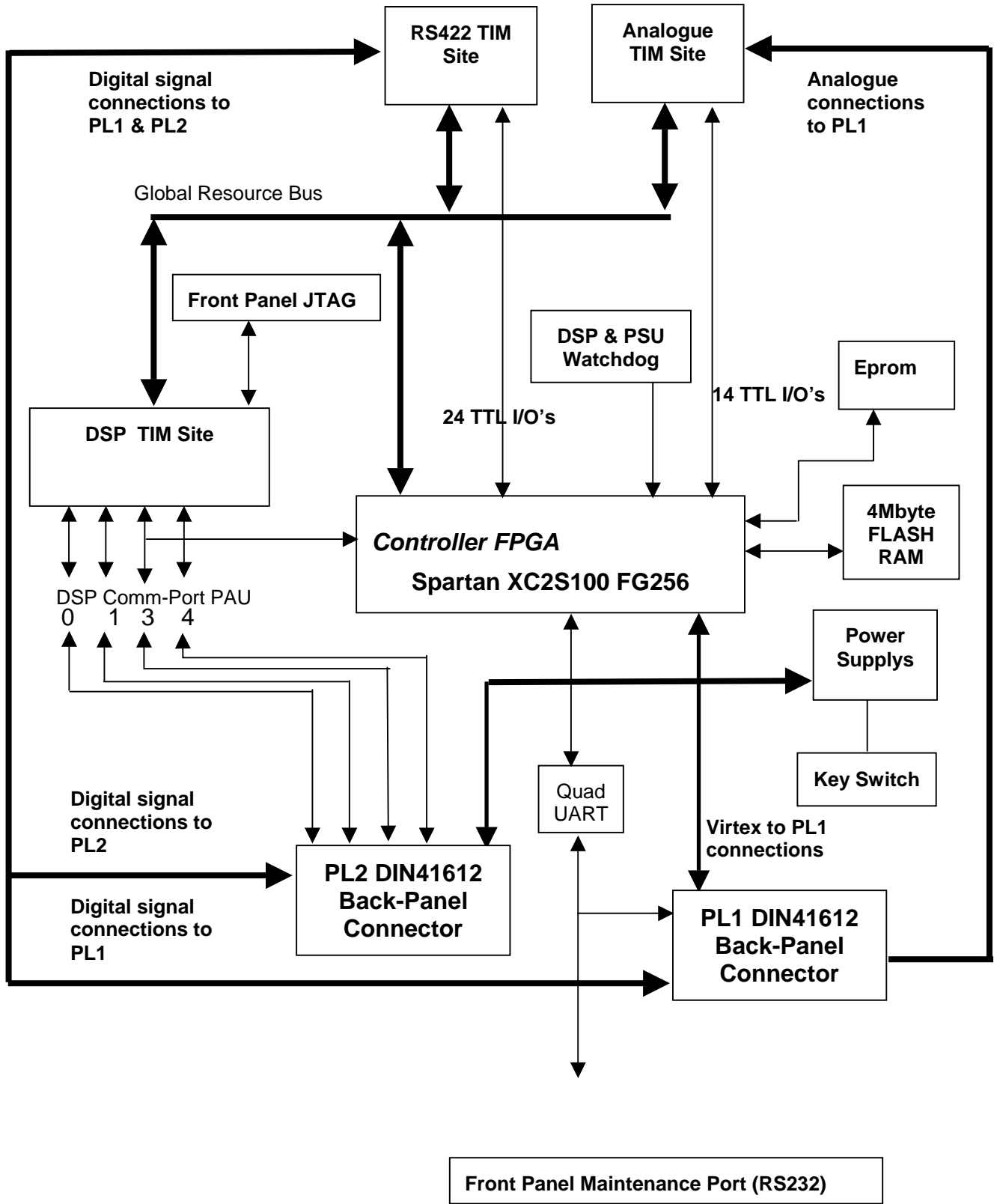
Introduction

The SMT128 is a 3 site TIM carrier card with additional customised features, acting as a supports environment for a DSP TIM and two other peripheral TIM's. The various 'on-board' peripherals available on the motherboard are listed below.

- TIM Site 1: Standard Single width TIM site capable of accepting any TIM compatible card. For the most embedded projects this can be a DSP processing card. It has full COMM-PORT and Global Expansion Bus interconnectivity. The site is also capable of accepting C6x based DSP although only four com-ports are available. These com-ports are routed to the PL2 DIN connector for inter-module communication via com-ports (0,1,3,4) via a buffer CPLD.
- TIM Site 2: Standard Single Width TIM site with additional 26 way and 24 way IDC sockets, see mechanical/electrical information. This is designed to accept the SMT397 12 channel differential ADC/DAC TIM although other peripheral TIM's can be used.
- TIM Site 3: Standard Single Width TIM site with two additional 24 way IDC sockets, see mechanical/electrical information. This is designed to accept the SMT392 4 channel RS422 Transceiver/Digital IO TIM although other peripheral TIM's can be used..
- Motherboard Resources/Peripherals
 - Power Supplies 3.3V, 5V +-15v all generated.
 - Control FPGA
- Digital Inputs/Outputs
- Power Monitor & Watchdog
- 8K bytes of EEprom that can be used to store application parameters.
- JTAG Port
- 4Mbit FLASH ram for application Software
- Quad UART with links to the DIN connectors and also one to an RS232 connector.

The Motherboard has 2 DIN4162 connectors placed at the back of the board which conform with the VME mechanical specifications. The Pin-out out the connectors is given later in this specification. Four of the DSP com-ports are available on the back panel connectors to allow multiple boards to communicate with each other. Each com-port has a control circuitry to allow motherboard in a system to be 'hot swappable'.

Functional Block Diagram



Memory Map

There are four basic motherboard resources, Virtex internal registers, FLASH RAM, EEPROM and UART. Each of these resources is explained in the following sections.

Register	Global Address	Description
FLASH Memory	0xA0000000 -> 0xA003FFFF	FLASH Application/Boot space
EEPROM	0xA8000000 -> 0xA80000FF	8 –bit Non-volatile parameter storage
Virtex Registers	0xB0000000 -> 0xB0000007	See Description below
UART 1	0xB8000000 -> 0xB8000007	ModBus interface
UART 2	0xB8000008 -> 0xB800000F	RS232 interface

Virtex Registers

Register	Global Address	Description
WDOG RST	0xB0000000	Writing to this register resets the watchdog timer.
WDOG ENABLE	0xB0000001	Enables/Disables WDOG timer
DIGIN Register	0xB0000002	Read only, D0..D21 is state of digital I/P's
DIGOUT Register	0xB0000003	Drives the digital O/P signals
VSTATUS	0xB0000004	Virtex Status Register
VCNTRL	0xB0000005	Virtex Control Register

WDOG RST

When the Watchdog timer is enabled (See WDOG ENABLE). This register must be written to with a period of less than 1.6 seconds. If the register is not written to within this period a global reset is initiated and the FAULT LED is activated. The fault LED goes out next time the WDOG RST register is written to.

WDOG ENABLE

When writing to this register the level of the data line D0 selects either an internal oscillator or a WDOG RST signal for the watchdog timer.

D0 -> logic 0 = Watchdog is reset using an internal oscillator.

D0 -> logic 1 = Watchdog is reset using a write to the WDOG RST register.
At reset the value of this signal is '0' i.e. internal oscillator is selected.

DIGIN Register

There are 22 digital input lines connected to the DIN connector PL1.

This is a Read-only register and when read returns the current value on DigIn signals as illustrated below.

D21	D20	D19	D18	D17	D16	D15	D14	D13	D12	D11
DigIn22	DigIn21	DigIn20	DigIn19	DigIn18	DigIn17	DigIn16	DigIn15	DigIn14	DigIn13	DigIn12

D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0
DigIn11	DigIn10	DigIn9	DigIn8	DigIn7	DigIn6	DigIn5	DigIn4	DigIn3	DigIn2	DigIn1

DIGOUT Register

There are 8 digital output lines, which are connected to the DIN connector PL1. Each output can be set to the desired logic level by writing to this register using the Global Bus data bits illustrated below.

D7	D6	D5	D4	D3	D2	D1	D0
DigOut8	DigOut7	DigOut6	DigOut5	DigOut4	DigOut3	DigOut2	DigOut1

VSTATUS Register

When Reading this register the following values are read.

D7	D6	D5	D4	D3	D2	D1	D0
X	X	X	S0INT1	S0INT0	TERMINAL	Addr1	Addr0

Addr0, Addr1 -> Board address, reflects the state of the Addr0 and Addr1 signals on the PL1 connector.

TERMINAL -> When a VT100 terminal, or compatible, is connected to the front panel this bit is logic '1'.

S0INT0 -> A logic '1' when an interrupt occurs on the ModBus.

S0INT1 -> A logic '1' when an interrupt occurs on the RS232 Port.

These interrupt signals must be cleared via the UART Registers.

VCNTRL Register

D7	D6	D5	D4	D3	D2	D1	D0
X	X	X	X	X	MODINTEN	RST UART	RST FLASH

RST UART/RST FLASH: When these bits are high the motherboard UART or FLASH is reset.

RST UART: When logic '1' the UART is in a reset state.

RST FLASH: When logic '0' the FLASH is in a reset state

MODINTEN: When high MODBUS interrupt is enabled on IIOF1 of DSP.

FLASH Memory

The SMT128 has 4Mbit of boot block flash memory. This allows larger application programs to be stored and loaded and run by the DSP.

The motherboard resource is located at the following address locations:

0xA0000000 -> 0xA003FFFF

The FLASH device is a Hyundai HY29F400BT-70. This requires 4 wait states to be set up for the global bus transfer from the DSP. The operation of the FLASH is described in the manufacturers data sheet.

EEPROM

An 8k byte of EEPROM allows program parameters to be stored in a non-volatile media. Data stored is just the lower 8 bits (D0.D7) of the global data lines.

The memory range for the EEPROM is 0xA8000000 -> 0xA80000FF

The EEPROM device is a ATMEL AT28C64E-12SC. This requires 6 wait states to be set up for the global bus transfer from the DSP. The operation of the device is described in the manufacturers data sheet.

UART

The Motherboard UART is a Oxford devices OX16C954 quad device it uses a 40MHz crystal to generate a programmable baud rates. One of the outputs is connected to the front panel via an RS232 driver to allow VT100 terminal communications with the motherboard. A differential receive and transmit signals are connected to the back panel DIN41612 connector, via an ADM1485, at RS422 levels to allow a remote modbus protocol link. The fourth output of the Quad UART is unused. For details on setting up the UART please refer to the Oxford devices data sheet

Com Port Control

Four of the C6x com-ports connect to the DIN connector via a control CPLD. The CPLD acts as a buffer for the Data com-port data lines. This allows multiple SMT128 to communicate in a system via the DSP's com-ports. To allow the state of the com-port to be reset, to their default states after a power-up condition, four registers resources are provided. The table below shows the registers and their Global address values.

Token Reset Control Registers

Com-Port	Address	Operations
Com 0	0xF0000000	Write 0x1 to reset the token for the com-port then write a '0'
Com 1	0xF0000001	Write 0x1 to reset the token for the com-port then write a '0'
Com 3	0xF0000002	Write 0x1 to reset the token for the com-port then write a '0'
Com 4	0xF0000003	Write 0x1 to reset the token for the com-port then write a '0'

Token Reset Software Functions and Method

On power-up the SMT128 com-port directions will be set to either Input or Output depending on their com-port number. The CPLD buffers on the SMT128 will also be reset to their correct state. When connecting multiple SMT128's together in a system there are situation when com-ports may become unsynchronised. To re-synchronise the system it is necessary to do the following.

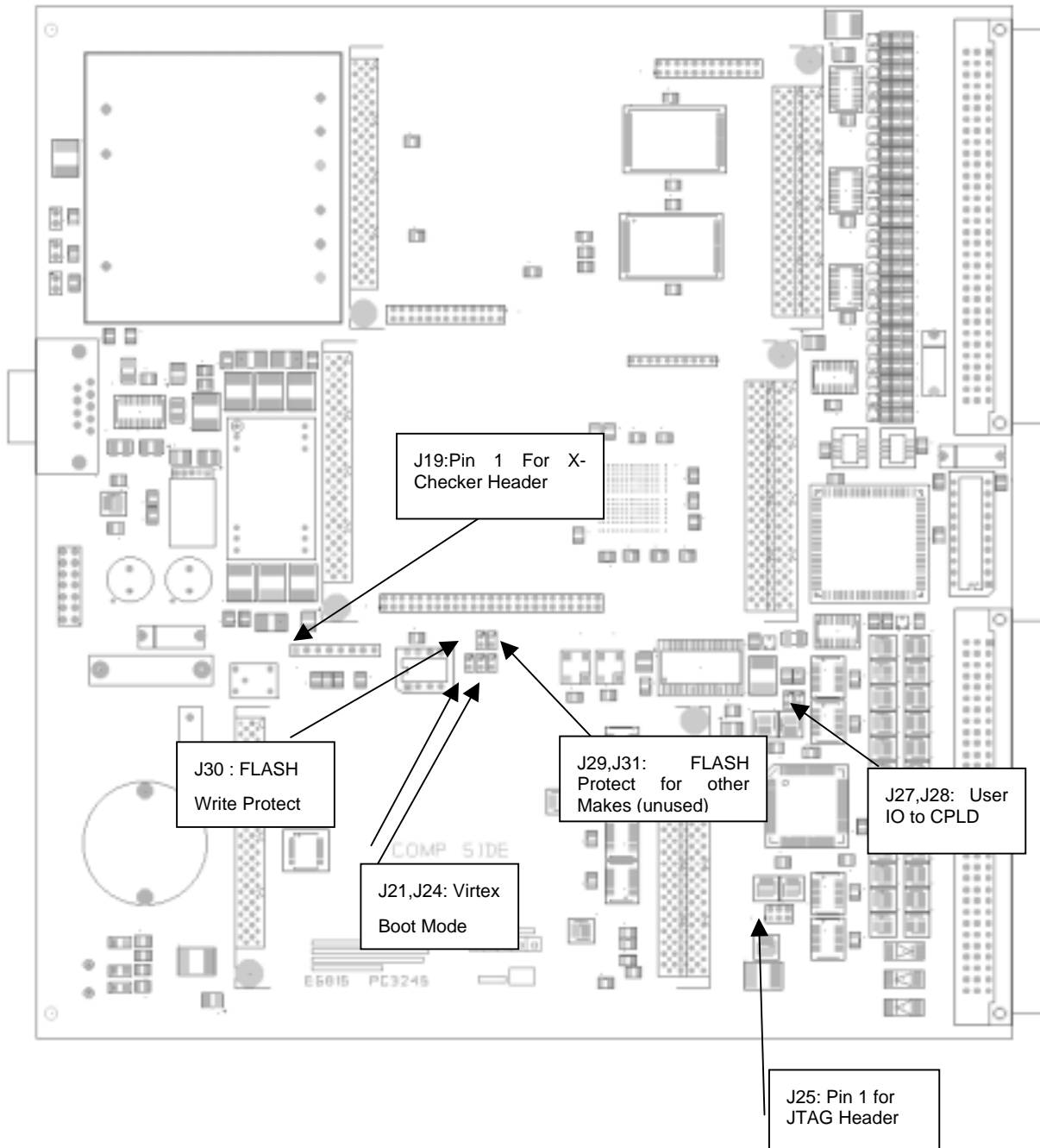
- Reset the com-port in the DSP.
- Reset the Com-port buffer on the SMT128.

To reset the DSP's com-port register a write to the DSP's com-port control register is required (see SMT335 User Guide of details).

The Com-Port buffer on the SMT128 can be reset by writing a '1' followed by a '0' to the corresponding com-port token Reset Control Register in the table above.

Jumper Settings

The diagram below shows the SMT128 with jumper positions labelled.



J21, J24 – Virtex boot mode

With J21 in and J24 out, the SMT128 will boot from a serial prom. When booting from X-checker header remove J21. J24 with reset the serial prom when in and may be fitted when booting from x-checker if the serial prom is still fitted in the IC socket.

J30 – Flash Write Protect

This jumper must be fitted to permit write cycles to be accepted by the SMT128 FLASH memory.

J27, J28 – Com CPLD User I/O

These are connected to the SMT128 com-port CPLD for future expansion.

DIN Connector Pinout

The following tables define the DIN 41612 pin allocation :

DIN PL1

a	Description	b	Description	c	Description
1	ChX/Analogue Input 1+	1	ChX/Analogue Out 1+	1	ChX/Analogue Input 1-
2	ChX/Analogue Input 2+	2	ChX/Analogue Out 1-	2	ChX/Analogue Input 2-
3	ChX/Analogue Input 3+	3	ChX/Analogue Out 2+	3	ChX/Analogue Input 3-
4	ChX/Analogue Input 4+	4	ChX/Analogue Out 2-	4	ChX/Analogue Input 4-
5	ChX/Analogue Input 5+	5	ChX/Analogue Out 3+	5	ChX/Analogue Input 5-
6	ChX/Analogue Input 1+	6	ChX/Analogue Out 3-	6	ChX/Analogue Input 1-
7	ChX/Analogue Input 1+	7	ChX/Analogue Out 4+	7	ChX/Analogue Input 1-
8	ChX/Analogue Input 8+	8	ChX/Analogue Out 4-	8	ChX/Analogue Input 8-
9	ChX/Analogue Input 9+	9	ChX/Pulse In 1+	9	ChX/Analogue Input 9-
10	ChX/Analogue Input 10+	10	ChX/Pulse In 1-	10	ChX/Analogue Input 10-
11	ChX/Analogue Input 11+	11	ChX/Pulse In 2+	11	ChX/Analogue Input 11-
12	ChX/Analogue Input 12+	12	ChX/Pulse In 2-	12	ChX/Analogue Input 12-
13	Sync	13	ChX/Spare 1	13	ChX/Spare 2
14	Digin 1	14	Digin 2	14	Digin 3
15	Digin 4	15	Digin 5	15	Digin 6
16	Digin 7	16	Digin 8	16	Digin 9
17	Digin 10	17	Digin 11	17	Digin 12
18	Digin 13	18	Digin 14	18	Digin 15
19	Digin 16	19	Digin 17	19	Digin 18
20	Digin 19	20	Digin 20	20	Digin 21
21	Addr 0	21	Addr 1	21	Digin 22
22	ChX/Digout 1	22	ChX/Digout 2	22	ChX/Digout 3
23	ChX/Digout 4	23	ChX/Digout 5	23	ChX/Digout 6
24	ChX/Digout 7	24	ChX/Digout 8	24	5V Out
25	Not used	25	Not used	25	Not used
26	ModBus Tx +	26	Not used	26	ModBus Tx -
27	ModBus Rx +	27	ChX/Digout 9	27	ModBus Rx -
28	ChX/Digin 23	28	ChX/Digout 10	28	ChX/Digin 24
29	ChX/Digin 25	29	ChX/Digout 11	29	ChX/Digin 26
30	ChX/Digin 27	30	ChX/Digout 12	30	ChX/Digin 28
31	ChX/Digin 29	31	ChX/Digout 13	31	ChX/Digin 30

32	ChX/Digout 15	32	ChX/Digout 14	32	ChX/Digout 16
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Table 1: PL1 DIN 41612 pin allocation**DIN PL2**

a	Description	b	Description	c	Description
1	ChX/Digout 19	1	Not used	1	ChX/Digout 20
2	ChX/Digout 21	2	ChX/Digout 17	2	ChX/Digout 22
3	ChX/Digout 23	3	ChX/Digout 18	3	ChX/Digout 24
4	ChX/Digout 25	4	ChX/RS485Tx1+	4	ChX/Digout 26
5	ChX/Digout 27	5	ChX/RS485Tx1-	5	ChX/Digout 28
6	ChX/Digout 29	6	ChX/RS485Tx1+	6	ChX/Digout 30
7	ChX/Digout 31	7	ChX/RS485Tx1-	7	ChX/Digout 32
8	ChX/RS422Tx1+	8	ChX/RS485Tx2+	8	ChX/RS422Tx1-
9	ChX/RS422Rx1+	9	ChX/RS485Tx2-	9	ChX/RS422Rx1-
10	ChX/RS422Tx2+	10	ChX/RS485Tx2+	10	ChX/RS422Tx2-
11	ChX/RS422Rx2+	11	ChX/RS485Tx2-	11	ChX/RS422Rx2-
12	Not used	12	Not used	12	Not used
13	D0C0	13	!CREQ	13	D0C3
14	D1C0	14	!C0ACK	14	D1C3
15	D2C0	15	!C0STRB	15	D2C3
16	D3C0	16	!C0RDY	16	D3C3
17	D4C0	17	!C3REQ	17	D4C3
18	D5C0	18	!C3ACK	18	D5C3
19	D6C0	19	!C3STRB	19	D6C3
20	D7C0	20	!C3RDY	20	D7C3
21	D0C1	21	!C1REQ	21	D0C5
22	D1C1	22	!C1ACK	22	D1C5
23	D2C1	23	!C1STRB	23	D2C5
24	D3C1	24	!C1RDY	24	D3C5
25	D4C1	25	!C5REQ	25	D4C5
26	D5C1	26	!C5ACK	26	D5C5
27	D6C1	27	!C5STRB	27	D6C5
28	D7C1	28	!C5RDY	28	D7C5
29	ChX/24V_Out	29	ChX/24V_Out	29	ChX/24V_Out
30	24V A	30	24V A	30	24V A
31	24V B	31	24V B	31	24V B

32	Gnd/0V	32	Gnd/0V	32	Gnd/0V
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Table 2: PL2 DIN 41612 pin allocation