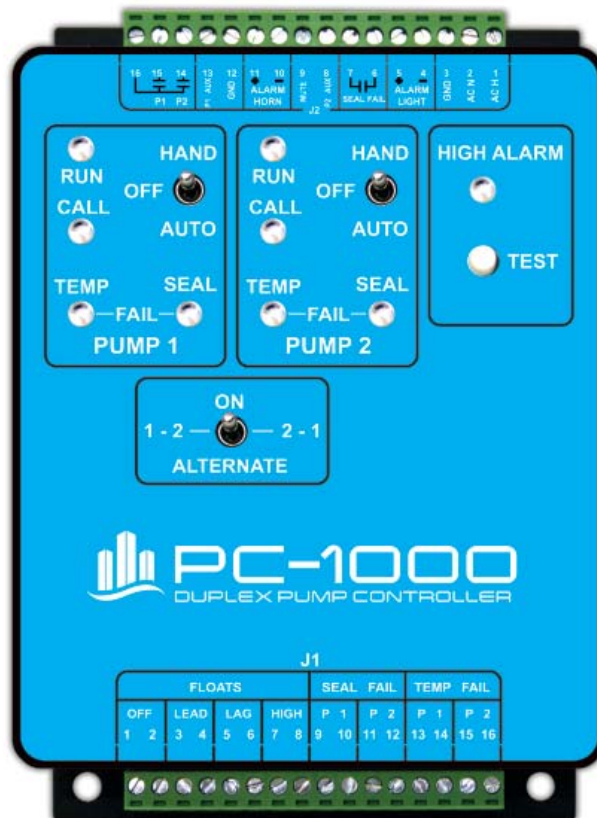


# PC-1000

## DUPLEX PUMP CONTROLLER

### User Manual



## 1.0 INTRODUCTION

The model PC-1000 is a float switch based duplex pump controller intended primarily for wastewater lift station and other pump down applications. It includes sensor inputs for the seal fail and temperature fail sensors for most submersible pumps. It connects to four switches to measure the tank level and has out puts to control two pumps, an alarm horn, a seal fail light, and a high alarm light. It has built in HOA [hand-off-auto] switches, and pump running lights. A lead pump selector switch permits either pump to be selected as lead pump or alternation can be selected causing the pumps to alternate as lead. The PC-1000 uses removable terminal strips to make replacement in the field quick and easy. With the addition of an enclosure, circuit breakers, and motor starters, the PC-1000 makes a complete low cost lift station controller.

## 2.0 OPERATION

The PC-1000 uses four normally open floats as level sensing inputs so when the tank is empty all of the floats are open. On rising water the Off float closes first which causes the controller to take no action. The Lead float will close next as the water rises. The controller will then turn on the lead pump. If this pump causes the water level to fall, the lead pump will be turned off when both the Lead and Off float are out of the water and open. If the lead pump is not sufficient to control the water level then the lag pump will be started when the Lag float closes. The two pumps will not be turned off until the Lag, Lead, and Off floats are out of the water and open, at which time, all pumps will be turned off. The controller has delays built into the software, which will insure that whenever a pump is turned on, the second pump cannot come on for at least 8 seconds. Another delay insures that when a pump is turned off the other one cannot turn off for 4 seconds. These delays help insure smooth pump operation and prevent excessive electrical surges.

The last float input is for the High float. Whenever the high float is under water [closed] then the high alarm condition is set. When a high alarm condition is set the alarm light will flash on and off, and the horn will be activated. The horn can be silenced using an external mute button connected to pin j2-9. Both the alarm light and horn will turn off when the high float input opens. The PC-1000 has an alarm test button on the front panel which can be used to test the alarm horn and light.

The pump controller has two inputs for pump seal fail [leak] sensors [one for each pump]. These inputs measure the resistance between the input and ground. If the resistance is less than 50,000 ohms then the seal fail indicator for that pump will be turned on. This action does not disable the pump, however, it does demote the pump to the lag position in the alternation order.

The pump controller has two inputs for pump temperature sensors. If the controllers detects a short between these inputs and ground then a temperature failure condition does not exist. If the short to ground is removed then a temperature failure condition exists and the pump associated with that input will be disabled and the Temp Fail indicator illuminated. This condition does not latch up and will return to normal if the short to ground is reestablished.

All of the float and sensor inputs are transient protected and filtered to prevent electrical interference from causing improper operation.

The controller has two switches that select what mode the two pumps are in. These HOA switches have the following function:

- H** When in HAND the pump will be constantly called to run.
- O** When in OFF the pump will be off.
- A** When in AUTOMATIC the pumps will be called by the pump controller.

The Hand and Off functions of these switches will operate even if the controller is off or has failed.

The controller has a switch that is used to select the lead pump. When this switch is in the center position [ON] then the two pumps will alternate as lead pump each pump cycle. When in the 1-2 position then pump one is the lead and when in the 2-1 position pump two is the lead.

The controller has two inputs, which should be connected to the auxiliary switches on the two motor starters. These inputs, when shorted, cause the pump running indicators to be illuminated. Using these inputs may eliminate the need for panel-mounted pump running lamps.

### **3.0 SPECIFICATIONS**

#### **3.1 Float and Sensor Input**

There are four float inputs, two leak sensor inputs, and two temperature fail inputs. They use current limiting resistors and a zener diode for transient protection. They also have a resistor/capacitor filter as well as a software filter to avoid electrical interference. They have the following specifications:

Short circuit current	-	less than 2 mA.
Open circuit voltage	-	5.0 VDC

#### **3.2 Aux contact inputs**

There are two sets of inputs for the auxiliary contacts on the motor starters. When these inputs are shorted, the pump running lamps are illuminated. These inputs have the following specifications:

Short circuit current	-	less than 2 mA.
Open circuit voltage	-	12.0 VDC

#### **3.3 Relay outputs**

There are three form A [SPST] relay outputs. Two are to call the pumps and one for the seal fail. They have the following specifications:

Maximum current at 120 VAC	-	5Amps with a resistive load
Maximum voltage	-	140 Volts

#### **3.4 Driver outputs**

There are two 12VDC driver outputs. They are used to drive the alarm light and alarm horn which must be 12VDC devices or 12VDC relays. They can drive a maximum of 100 mA.

### 3.5 Power inputs

The controller is designed to run on 120 VAC control power. It is internally fused and protected with a MOV transient protector. It uses a transformer isolated regulated power system with the following specifications.

Input voltage 120 Volt A.C. + or - 15%, 50 to 70 Hz  
Maximum current 0.25 Amps

### 4.0 CONNECTOR PIN DEFINITIONS

#### CONNECTOR J1

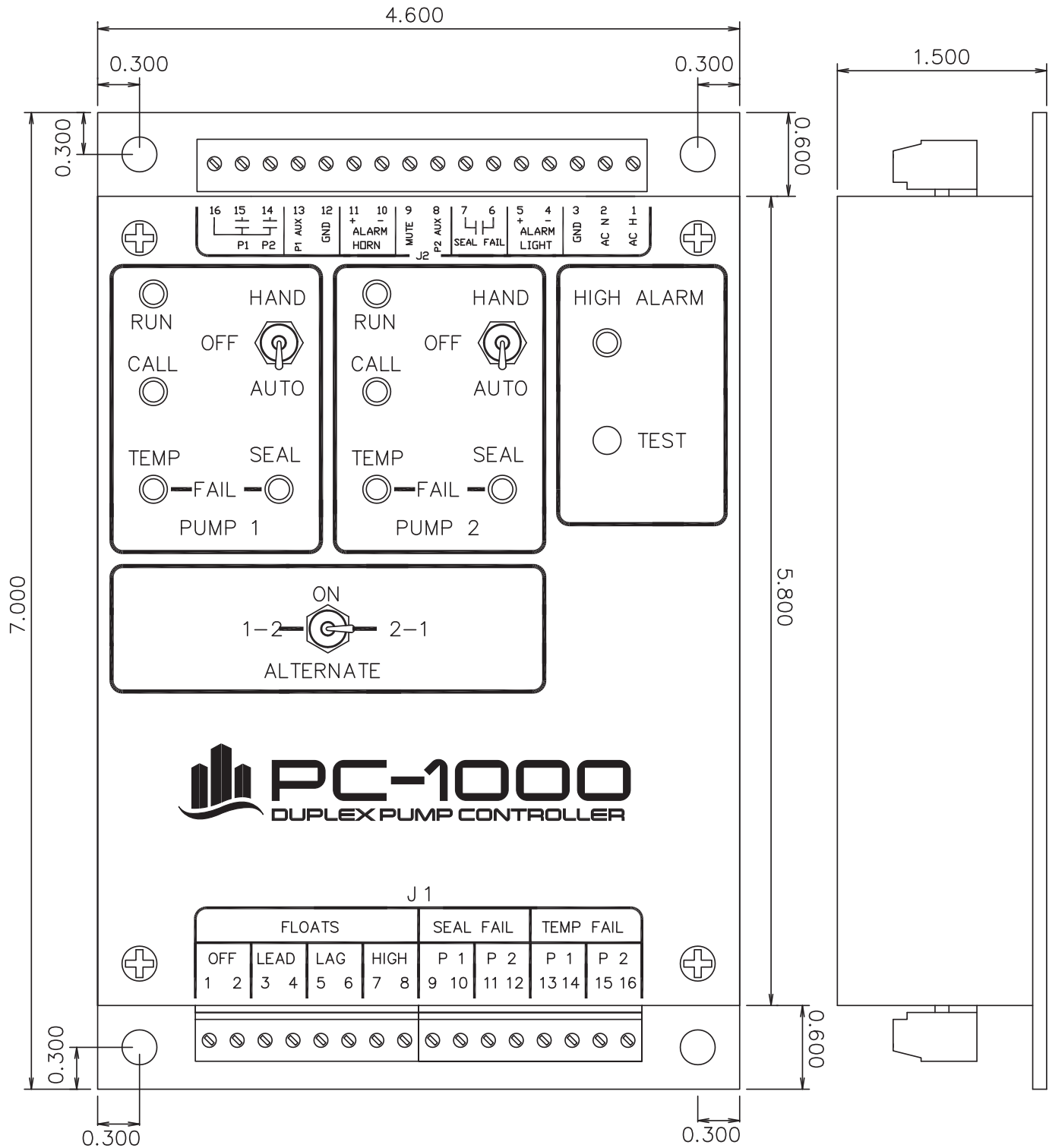
PIN	FUNCTION
1	OFF FLOAT INPUT
2	GROUND
3	LEAD FLOAT INPUT
4	GROUND
5	LAG FLOAT INPUT
6	GROUND
7	HIGH ALARM FLOAT INPUT
8	GROUND
9	PUMP 1 SEAL FAIL SENSOR INPUT
10	GROUND
11	PUMP 2 SEAL FAIL SENSOR INPUT
12	GROUND
13	PUMP 1 TEMPERATURE FAIL SENSOR INPUT
14	GROUND
15	PUMP 2 TEMPERATURE FAIL SENSOR INPUT
16	GROUND

#### CONNECTOR J2

PIN	FUNCTION
1	120 VAC HOT POWER TO CONTROLLER
2	120 VAC NEUTRAL POWER TO CONTROLLER
3	CHASSIS GROUND
4	HIGH ALARM LIGHT NEGATIVE [-] CONTACT
5	HIGH ALARM LIGHT POSITIVE [+] CONTACT
6	SEAL FAIL RELAY CONTACT
7	SEAL FAIL RELAY CONTACT
8	RUN INPUT 2, CONNECT TO AUX CONTACT STARTER 1
9	MUTE SWITCH INPUT
10	ALARM HORN NEGATIVE [-] CONTACT
11	ALARM HORN POSITIVE [+] CONTACT
12	GROUND
13	RUN INPUT 1, CONNECT TO AUX CONTACT STARTER 1
14	POWER TO MOTOR STARTER 2
15	POWER TO MOTOR STARTER 1
16	120 VAC HOT MOTOR STARTER POWER

**Notes:** Header and plugs use copper conductors only.  
Torque requirement for plugs 1.47 Ft. Lbs.  
Unit operates at "Pollution Degree 2".

FIG. 1



# FIG. 2

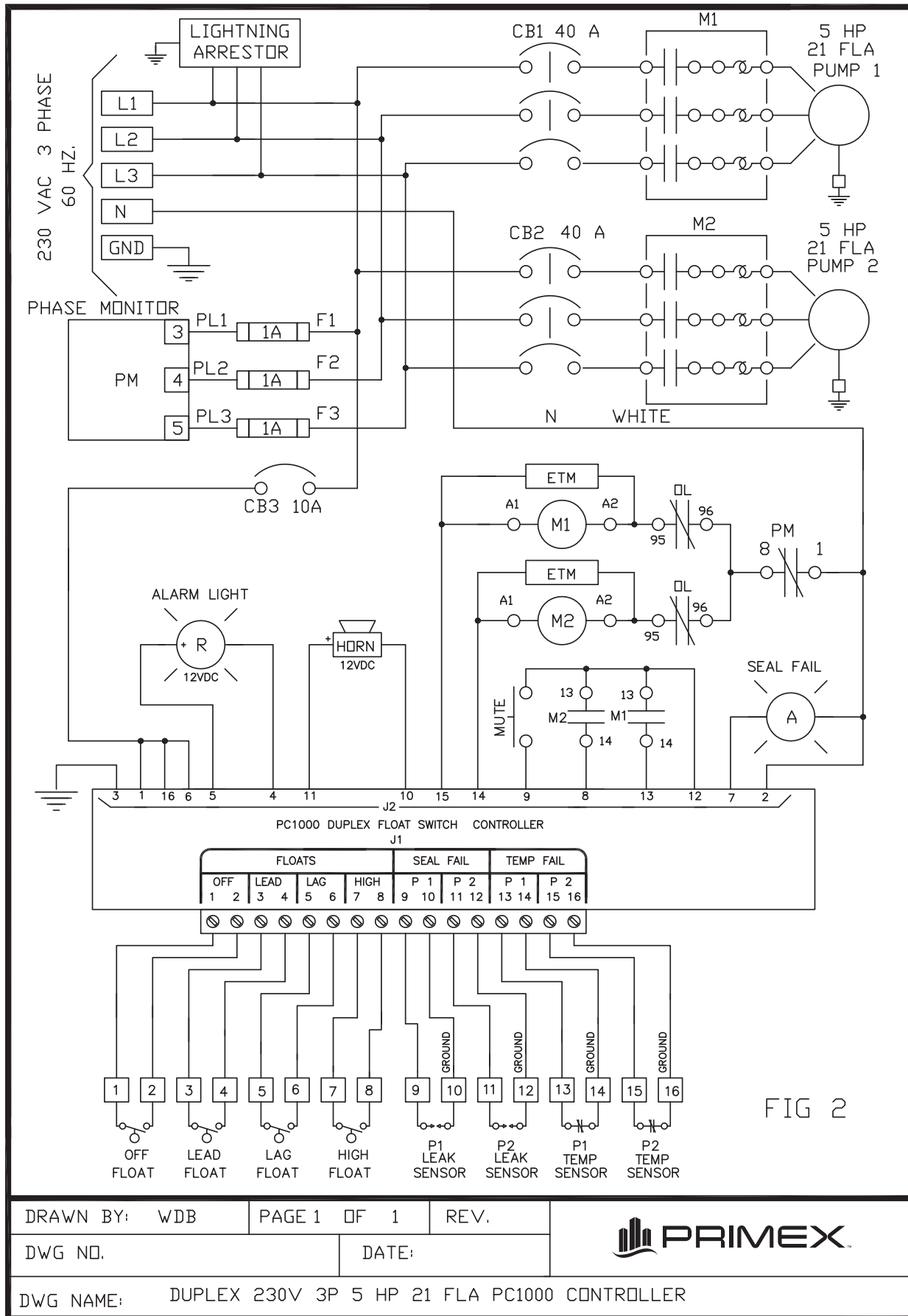


FIG 2

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DWG NO. DATE:

DWG NAME: DUPLEX 230V 3P 5 HP 21 FLA PC1000 CONTROLLER

