Quick Start



# **Getting Started**

Connected Components Accelerator Toolkit with System Design Assistant





# **Important User Information**

Read this document and the documents listed in the additional resources section about installation, configuration, and operation of this equipment before you install, configure, operate, or maintain this product. Users are required to familiarize themselves with installation and wiring instructions in addition to requirements of all applicable codes, laws, and standards.

Activities including installation, adjustments, putting into service, use, assembly, disassembly, and maintenance are required to be carried out by suitably trained personnel in accordance with applicable code of practice.

If this equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

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Throughout this manual, when necessary, we use notes to make you aware of safety considerations.



**IMPORTANT** Identifies information that is critical for successful application and understanding of the product.

Labels may also be on or inside the equipment to provide specific precautions.





**BURN HAZARD:** Labels may be on or inside the equipment, for example, a drive or motor, to alert people that surfaces may reach dangerous temperatures.



**ARC FLASH HAZARD:** Labels may be on or inside the equipment, for example, a motor control center, to alert people to potential Arc Flash. Arc Flash will cause severe injury or death. Wear proper Personal Protective Equipment (PPE). Follow ALL Regulatory requirements for safe work practices and for Personal Protective Equipment (PPE).

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Follow this path to complete your building block project.



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# **About This Publication**

This quick start is designed to provide a way to implement common control tasks by aiding in the selection of products and providing access to panel and wiring information. Each section is designed with a different task as a standalone machine, or implemented in a larger system.

**IMPORTANT** Use this publication together with other Connected Components Accelerator Toolkit quick starts to aid in building your Micro800<sup>®</sup> based application. Refer to You can view or download publications at <a href="http://www.rockwellautomation.com/literature/">http://www.rockwellautomation.com/literature/</a>. To order paper copies of technical documentation, contact your local Allen-Bradley distributor or Rockwell Automation sales representative. on page <u>9</u> for a listing of quick starts.

To help with the design and installation of your system, application files and other information are provided on the Connected Components Accelerator Toolkit (CCAT). The CCAT provides bills of materials (BOM), CAD drawings for panel layout and wiring, control programs, Human Machine Interface (HMI) screens, and more. With these tools and the built-in best-practices design, you are free to focus on the design of your machine control and not on design overhead tasks.

The CCAT is available on the Connected Components Accelerator Toolkit DVD, publication CC-QR002, or through the Rockwell Automation Software Download and Registration System (SDRS) at <a href="http://www.rockwellautomation.com/rockwellautomation/products-technologies/connected-components/tools/accelerator-toolkit.page">http://www.rockwellautomation.com/rockwellautomation/products-technologies/connected-components/tools/accelerator-toolkit.page</a>.

The beginning of each chapter contains the following information. Read these sections carefully before you begin work in each chapter:

- **Before You Begin** The chapters in this quick start do not have to be completed in the order in which they appear. However, this section defines the minimum amount of preparation that is required before completing the current chapter.
- What You Need This section lists the tools that are required to complete the steps in the current chapter, including, but not limited to, hardware and software.
- Follow These Steps This section illustrates the steps in the current chapter and identifies the steps that are required to complete the examples.

# Terminology

Term (abbreviation)	Definition		
Application Sequence Programs	User-modified programs that work together with the standard state machine logic to control what the machine does while in the abort, clear, reset, run and stop states.		
Auto/manual operation	When the PanelView <sup>™</sup> 800 terminal is in Auto mode, the controller logic controls the machine and monitors machine status. When the PanelView 800 terminal switches to Manual mode, the terminal takes over control. Command buttons and numeric entry fields are available only when the machine is in Manual mode.		
Bill of Materials (BOM)	A list of components that are needed for your system.		
Building block (BB)	Tools for accelerating and simplifying the development of a Micro800 controller-based application. A typical building block includes a starting Bill of Material (BOM), Computer-Aided Design (CAD) drawings, Micro800 controller programs, PanelView 800 terminal applications, and a quick start document.		
Computer-Aided Design (CAD)	A computer-based system that is developed to facilitate design of mechanical parts.		
Connected Components Accelerator Toolkit (CCAT)	Software with application files and other information to speed the design and startup of component-based machines.		
CCAT project	<ul> <li>A project that consists of these items:</li> <li>A ProposalWorks<sup>™</sup>-based bill of materials</li> <li>A set of CAD drawings (dimensions and schematics)</li> <li>A Connected Components Workbench project</li> <li>HMI screens</li> <li>A set of Quick Start documents</li> <li>A project document with information about the project components and links to reference materials</li> </ul>		
Connected Components Workbench™	Software environment for configuring or programming Micro800 controllers, PanelView 800 terminals, PowerFlex® drives, and other component-level products.		
Connected Components Workbench project	<ul> <li>A project consists of one or more of the following:</li> <li>Micro800 controller configuration</li> <li>Up to 256 Micro800 programs, each with program local variables</li> <li>Micro800 global variables</li> <li>PanelView 800 terminal application</li> <li>PowerFlex drive parameter lists</li> </ul>		
Global variables	Project variables that any program can access, including all I/O and system variables.		
State Machine control code	Machine logic for coordinating overall machine operation that is based on states. The state machine broadcasts commands and receives feedback information from each of the building blocks via user-modified application sequence programs.		
System Design Assistant (SDA)	Software with application files and other information to speed the design and start-up of component-based machines.		
Tags	A PanelView 800 term for variables.		
User-defined Function Blocks (UDFBs)	Function block instructions that can be used like standard function block instructions within any Connected Components Workbench programming language. Anyone using Connected Components Workbench software can write these functions blocks. Many UDFBs are posted on the Rockwell Automation sample code website: <u>http://samplecode.rockwellautomation.com/idc/groups/public/documents/webassets/sc_home_page.hcst</u> .		
User-defined Object (UDO)	A collection of PanelView 800 terminal screen objects that can be pasted into a new screen.		

### **Available Connected Components Accelerator Toolkits**

For the most up-to-date listing of available Connected Components Accelerator Toolkits and related quick starts, refer to these resources:

- Rockwell Automation Connected Components Accelerator Toolkit website at <u>http://www.rockwellautomation.com/rockwellautomation/products-technologies/connected-components/tools/</u> <u>accelerator-toolkit.page</u>.
- Connected Components Accelerator Toolkit Building Block Project Descriptions Quick Reference, publication <u>CC-QR003</u>.

# **Additional Resources**

These resources contain information about related products from Rockwell Automation.

Resource	Description
Micro810 <sup>®</sup> Programmable Controllers User Manual, publication 2080-UM001	Provides information to install, wire, and troubleshoot the Micro810 Programmable Controller.
Micro820 <sup>®</sup> Programmable Controllers User Manual, publication 2080-UM005	Provides information to install, wire, and troubleshoot the Micro820 Programmable Controller.
Micro830 <sup>®</sup> and Micro850 <sup>®</sup> Programmable Controllers User Manual, publication <u>2080-UM002</u>	Provides information to install, wire, and troubleshoot the Micro830 and Micro850 Programmable Controller.
PanelView 800 HMI Terminals User Manual, publication 2711R-UM001	Provides information to configure, operate, and troubleshoot the PanelView 800 HMI terminals.

You can view or download publications at <u>http://www.rockwellautomation.com/literature/</u>. To order paper copies of technical documentation, contact your local Allen-Bradley distributor or Rockwell Automation sales representative.

### Notes:

# Using the System Design Assistant (SDA)

This chapter guides you in creating your project and generating a project folder.

### **Before You Begin**

Become familiar with the contents of this Quick Start.

#### What You Need

A Windows-based personal computer with the following software installed:

- Connected Components Accelerator Toolkit (CCAT) with System Design Assistant
- ProposalWorks<sup>™</sup> software
- Connected Components Workbench, version 6.0 (or higher)
- Adobe Acrobat Reader.

### **Follow These Steps**

Complete these steps to design and install your starting Building Block.



# Open the Connected Components Accelerator Toolkit (CCAT)

- 1. From your Windows desktop, choose Start > All Programs > Rockwell Automation > CCAT > Connected Components Accelerator Toolkit.
- 2. Click Connected Components Accelerator Toolkit to launch the software.

The System Design Assistant welcome screen is displayed.

NA Connected Components Accelerator Toolkit	
Ere Tot Took Reb	
<b>Connected Components</b>	
Accelerator Toolkit (CCAT)	
	Recent Projects
Create a new CCAT project Start building a brand new connected components project using the simple pre-physical public provided by the CCAT system design assistant.	
Open a sample CCAT project Create your connected components project by outpointing one of the includes sample projects to it sycuri indicidual needs.	
Learn about using the CCAT bolow the CCAT appalies by vewing the CCAT Getting stanse Guide.	
See the CCAT in action Watch an innocuctory wide showing how to get started developing a connected components project using the CCAT system design assistant.	
Launch ProposalWorks Use the ProposalWorks tool to enhance and expand the Bill of Material, or to received a work.	

3. Choose Create a new CCAT project.

The System Design Assistant workspace is displayed.

AA Connected Components Accelerator Toolkit		0 D -X
Ele Edit Tools Help		
Machine Basics     Motor Control     Sensors     Operator Interface	Machine Basics Jefore us get started, us need to find cut some information. Tell us about your project. Project Name.	
Safety Components Controller Info Machine Build Components	Designet Project Desniption	
System Summary and Generate	Nov. tell us about your system.	
	Feeder Circuit/Disconnect Protection Industry Standards IIE Rotany Oricit Protection Circuit Brailer	
	Central Power: 24V DC .	
	Far mare internation on Line Vallege Cinus Power set the Spower Automation in	1 Protection, and Control oduct Directory Website
Power Voltage: 480 VAC Control Voltag	e: 34V DC Motor Controllers: 0 Digital Input: 0 Digital Output: 0 Analog Input: 0 Analog Output: 0	

# **Review the System Design Assistant Workspace**

Features of the main workspace are described below.



ltem	Description	
Menu Bar	Perform file operations, copy/paste, access ProposalWorks or other software packages and help.	
🔀 Data Incomplete	Required data is missing or incorrect.	
Data Reviewed	Data in this category has been entered/reviewed.	
Project Summary	Provides a summary of the project specifications.	
System Summary and Generate	Provides a complete listing of all products selected in the project and creates the project folder.	
Product/Device Selection	Selects the products/devices used in the project.	
Navigation Arrows	Sequences backward or forward through the SDA screens.	

### **Define the Machine Basics**

1. Choose Machine Basics to enter the basic information about your system.

- 2. Type your project name by using alpha-numeric characters and the underscore (\_) character.
- 3. Type the designer name and project description.
- 4. Enter the basic information for your system by choosing the appropriate items for line voltage, disconnect, and control power.

**IMPORTANT** The line voltage class and control power selections establish the basis of the system. During product selection, only devices compatible with the specified line voltage and control power are displayed.

5. Click the right navigation arrow at the bottom of the screen or choose Motor Control to start selecting devices for your project.

The Motor Control product list is shown.

A Connected Components Accelerator Toolkit	0.0
lie Eat Iools Help	
Machine Basics 🗸	Starter Controlled Motors
Motor Control	Enter the Automatical Charter Constallant Monton Line (unclusify Bigs to add to uncur purpose)
Starter Controlled Motors	
Soft Start Controlled Motors	box
VFD Drive Controlled Motors	
Servo Drive Controlled Motors	
Sensors	
Operator Interface	
Salety Components	
Controller Info	
Machine Build Components	
System Summary and Generate	
	For more information on adding Motor Control, see the <u>Rockwell Automation Product Directory</u> W
ower Voltage 480 VAC Control Voltage 1	10/320 VAC Motor Controllers: 0 Dioital Inout: 0 Dioital Output: 0 Analog Inout: 0 Analog Output: 0

### **Specify Products**

Choose products/devices in your project by going through the items listed on the left.

1. Choose a product by using the pull-down menus and filling in fields.

For example, when choosing VFD Drive Controlled Motors, you must specify the number of controlled motors and the branch circuit protection type. Clicking Add shows a screen similar to the one shown below. The software selects the most logical device according to the basic system information entered earlier.

Default Name	Default Drive	Accessories	Edit
		$\wedge$	
A Connected Components Accelerator polkit			(12 (C)
Eile Edit Iools Help			
Machine Basics	VED Drive Controlled	Motors	
Motor Control	Enter the number of JED drive control	lad motors for each statistics that with to use is your partern	0.*
Starter Controlled Motors	Select a branch circuit destaction tund	Circuit Branker () ISC Surger () NA Surger () None	0.4
Soft Start Controlled Motors	select a branch circuit potection type	S Circuit Breaker Direc Fused O NA Fused O None	
VFD Drive Controlled     Motors	add		
Servo Drive Controlled Motors	VFD1 PowerFlex 523 AC Drive, 480 VAC	, 3 Phase, 2 HP, 1.5 kW Heavy Duty, Frame A, IP20 NEMA / Open	Type, No Filter
Sensors	CM211-NV00218BXZHA		Edit
Operator Interface	CM211 - NEMA Severe Duty I	nverter Motors, 2 HP, 1800 RPM, Foot Mi unted, Frame Size is 14	ST
Safety Components	MPCB, Standard Magnetic Trip	o (Fixed at 13 x le), 4 · 6.3 A. Std. Performance, Frame Size C	Edit
Controller Info			
Machine Build Components			
System Summary and Generate			
	L	For more information on adding Motor Control, see the	Rockwell Automation Product Directory Website
ower Voltage: 480 VAC Control Voltage:	24V DC Motor Controllers: 1 Digital	Input: 0 Digital Output: 0 Analog Input: 0 Analog Out	put: 0

a. If desired, click Edit to customize the product (size, type, and so forth).

This opens the Product Configuration Assistant, enabling custom configuration of the device.

Enter the catalog number 25A-D4P0N104	for the desired PowerFlex 520-Series					
Accept Velicities	Remarke the selections for the product that you need using the interactive selection chart.      Access     Validate     Cancel Reset     Uods     Bedo     Resto					
BASE DRIVE INFORMAT	TON	* Select an attribute to the left to start making				
BulletinNo	PowerFlex 523 AC Drive	selections				
Voltage Class	480 VAC, 3 Phase					
Current / Power Rating	4 Amps 2 HP, 1.5 kW Heavy Duty					
Enclosure Type	IP20 NEMA / Open Type					
Frame Size	Frame A					
Interface Module	Standard					
Emission Class	No Filter					
ACCESSORIES	Marito					
PowerFlex 525 Spare Parts	- NO SELECTION					
Communication, Filter & Option Kits	NO SELECTION					
Additional Details	ومعكاده الالمعاطي ويتوجد بطحمي					
Input	Three Phase 380-480V					

b. Click Accept when finished to update the device information in the SDA.

2. Change the default name of the device to be descriptive of the system; click in the field and type a new name, using alpha-numeric characters and the underscore (\_) character.

The name of the device (VFD1, in this case) is used in a number of places throughout the project folder, including bill of materials, CAD drawing title, program/screen name, screen text, and HMI screens.

- 3. Follow this process for each product in your project.
- 4. Click the right navigation arrow to advance to the next item or choose an item from the list.

#### **Review the System Summary**

When you've completed product selection, review your choices by following these steps.

1. Choose System Summary and Generate.

	Eile Edit Iools Help	
	Machine Basics	V
	Motor Control	V
Suctom Summary	Sensors	<ul> <li>Image: A start of the start of</li></ul>
Dystelli Sullillary	Operator Interface	V
ind Project Folder	Safety Components	<ul> <li>V</li> </ul>
Generation	Controller Info	V
	Machine Build Components	<ul> <li>Image: A start of the start of</li></ul>
	System Summary and Generate	

A summary of the selected devices and associated names is presented. A check in the Default box indicates that the device is using the default configuration.

tem Summary and Generate		🖉 Default? 🔽
VFD Drive Controlled Motors	Total: 1	
PF523 Drive 1	Default? 💽	Device is using the Default
PowerFlex 523 AC Drive, 480 VAC, 3 Phase, 2 HP, 1.5 kW Heavy Duty, Frame A, IP20 NEMA / Open Typ	e, No Filter	Configuration.
CM211-NV00218BXZHA		
CM211 - NEMA Severe Duty Inverter Motors, 2 HP, 1800 RPM, Foot Mounted, Frame Size is 145T	1	
140M-C2E-B63		
MPCB, Standard Magnetic Trip (Fixed at 13 x le), 4 - 6.3 A; Std. Performance, Frame Size C		
HMI	Total: 1	

2. Review the summary and make any necessary changes or additions by double-clicking the product category.

#### **Generate the Project Folder**

- 1. After reviewing the summary and making any necessary changes, click Generate
- 2. A dialog box opens letting you select the desired CAD drawing format.

-IEC Format		NFPA Format	
AutoCAD	EPLAN	AutoCAD	EPLAN
🖾 DWG	E EPLAN	E DWG	E EPLAN
PDF	PDF	E PDF	PDF
Your project files wi	Il be saved in the followin	o location:	

- 3. Verify the default location for the project files and change, if necessary.
- 4. Click Generate.
- 5. The project folder is generated in the location specified.

The folder contains the following:

- Project document
- Bill of materials (BOM) document
- CAD drawings folder
- Literature folder
- Connected Components Workshop project folder

### **Review the Project Folder**

The contents of the project folder are summarized in the following table.

ltem	Description
Project Document	Includes basic system data and links to additional information.
Bill of Material (BOM)	The Bill of Material is produced in ProposalWorks format, the catalog number and proposal generation software from Rockwell Automation. Users can build complete quotes, proposals, and product information for Rockwell Automation and Encompass Partner products.
Literature	Contains literature that provides basic system information and specific product information.
CAD	CAD drawings are provided to speed the design of the CAD documentation of a system. They include example drawings of the system and individual products to let the user easily add their machine-specific wiring.
	The drawings are provided in individual sub-folders for each drawing format selected. Each sub-folder contains system drawings and individual product drawings related to the products selected. The drawings include schematics and 3D modules for panel layout. Schematics are available as individual drawings and circuit library additions.
Programming	The programming sub-folder contains the Connected Components Workbench project for the products and functions selected. The project provides the basic foundation to start your machine design. Use the features and functions of the Connected Components Workbench software to add your individual machine functions and to optimize the machine operation.
	The Connected Components Workbench software provides the programming and configuration functionality needed for controller, HMI, and drives in one project.

# Notes:

# **Customize Your Project**

This chapter helps you customize your BOM, CAD drawing set, and logic, including your HMI screens.

## **Before You Begin**

Create your project file by using the System Design Assistant as described in Chapter 1.

### What You Need

You need a Windows-based personal computer with the CCAT and ProposalWorks software installed. The link to download free ProposalWorks software is listed in "Software and other Internet links" under the Support Tools section of the Connected Components Accelerator Toolkit (CCAT) menu.

## **Follow These Steps**

Complete these steps to customize your project.



#### **Customize Your BOM**

You can modify the default controller and PanelView terminal selection or add more devices to your project BOM by using ProposalWorks software.

#### **Review or Modify Your Controller and HMI Terminal Selections**

- 1. Open your BOM file from the project document.
- 2. Review the Micro800 controller catalog number starting with 2080-L\* and verify that it is the controller model you need.



- 3. If you need to modify the controller or add controller plug-ins or accessories to your system BOM, follow these steps.
  - a. Double-click the controller catalog number to open the Product Configuration Assistant.



- b. Modify controller information and add controller plug-ins or accessories as necessary.
- c. Click Accept to save your modifications or additions.
- 4. Verify that your controller has enough plug-in slots to accommodate your plug-in modules.

If necessary, choose a controller with more I/O points. 10, 16, and 20-point controllers have 2 plug-in slots, 24-point controllers have 3 plug-in slots, and 48-point controllers have 5 plug-in slots.

TIP Each catalog number specifies how many I/O points a controller has. For example, 2080-LC30-16QWB has 16 points.

5. Review the PanelView 800 terminal catalog number starting with 2711R-\* and verify that this is the terminal model you need.



- 6. Modify information as required (refer to step <u>3</u>).
- 7. Review the remaining catalog numbers and quantities listed.
- 8. Modify any catalog numbers or quantities as detailed in step  $\frac{3}{2}$  to meet the requirements of your machine.

#### **Add Devices to the BOM**

Use the RAISE Product Library wizards and configurators to add other devices to the BOM.



### **Customize Your Drawing Set**

Follow these steps to use the drawing library in AutoCAD or EPLAN to create a complete system layout and wiring drawing set.

- 1. Open your drawing software.
- 2. Create and name your new project.
- 3. Find and add to your circuit library the library drawings (.circ) that are in your project folder.
- Edit the drawings to delete any components not used in your project or to edit connections and devices, as necessary. Refer to page <u>22</u> for steps to edit the drawings in AutoCAD Electrical software, and EPLAN Electrical P8 software.

#### For AutoCAD Electrical

a. From the Panel Layout menu, choose Insert Footprint (Icon Menu).

μ	00	<b>G</b> 53 •			<b>₽</b>	•	_		_		AutoC/	ID Electric	al Drawing1.c	lwg		
. F	ie Ec	it Vev	Insert	Format	Tools	Draw	Dimension	Modify	Parametric	Projects	Components	Wires	Panel Layout	Window	Help	Express
DP	0 6		() ×	DOC	150	3.3	- 3 Q	50		も第四	2 08	Layer	Insert Foot	print (Icon M	tenu)	
<u>९</u> २	8, H. 1-1110	2	🖳 🕱 eframe]	8 <del>4</del> : A	*	2+	<b>†</b>	. 7	2 2 2	7 🗞 🏹 :	2 2 2	5 G. 4	Insert Foot	print (Schen print (Manu print (Lists)	natic List) bl)	
/ 🗞													() Insert Foot	print (Manul	facturer M	tenu)

**IMPORTANT ATTENTION:** If you are using an AutoCAD application other than AutoCAD Electrical, choose Insert Block from the Panel Layout menu to browse to the same directory described in the following step.

- b. Browse to the CAD sub-folder in your project folder and find the "FP\_ ... " or "... footprints" drawings.
- c. Select the drawing by part number.

#### For EPLAN Electrical P8 software

a. From the Insert menu, choose Window macro.

Project Page Layout space Edit Yew	Insert Project data End Op	tions Litilities Window Hel
	O Symbol	Insert
	1 Window macro	м
Rer: → Rev:	Symbol mecro Degice Connected functions	Ctri+Insert
Standard  Active	Graphic Dimensioning Special text	:

- b. Browse to the CAD sub-folder in your project folder and find the "AB\_ ..." or "... footprints" drawings.
- c. Select the drawing (macro) by part number.

Look in: 🔯	Component L	ayout Macros (E	ema) 💌 🔾 🌮	💌 🖽	•	Preview
Cert a A A A A A A A A A A A A A A A A A A	6.22* Frame 8.140UE+t21 8.140UE+t21 8.140U-42C 9.1409-A1.6 8.1409-A1.6 8.1492-A1.6 8.1492-FB10 8.1492-FB10 8.1492-FB10 8.1492-FB10 8.1492-FB10 8.1492-FD1 8.1492-FD1 8.1492-FD1 8.1606-012 9.1606-0129	Alema COLEMA COLEMA S-COLEMA S	A 8-1605 91 SONET 4-ema A 4-11605 91 SONET 8-ema A 4-1738 4495017-ema A 4-1738 4495017-ema A 4-1739 4495017-ema A 4-1739 4495017-ema A 4-1270 44957 4-ema A 4-1270 44957 4-ema A 4-1270 44957 4-ema A 4-12000 4-1270 4-ema A 4-2000 4-200 4-ema A 4-2000 4-200 4-ema		A 6.2000 P5120 A 6.2000 P5120 A 6.2000 - SEDLA A 6.2000 - SEDLA A 6.2000 - TC2 en A 6.2000 - TC3 en A 6.2011 C 76T.e	
1 Elen		AR 27 Fran	e6 ema	-	- Breen	2.1.5473
work Files	of type:	Window macr	ro (" ema)	~	Cancel	CCAT Panel Layout Macros
Repre	sent. type:	Pariel layout				
Yorior	t:	Variant A				
				1000		

#### **Customize Your Logic and HMI Screens**

- 1. Open the Connected Components Workbench project file.
- 2. Select and copy the application logic rungs from the example application logic programs that are needed for your application.
- 3. Delete the application logic programs and HMI screens that you do not need for your application.
- 4. Edit the logic and modify the HMI screens as needed for your specific application by following the information provided in the Connected Components Workbench help files and the individual Building Block Quick Starts in your Literature folder.

# **Understanding the CCAT V2 State Machine**

This chapter provides you with an overview of the Connected Components Workbench V2 state machine.

### **Before You Begin**

Create your project file with the System Design Assistant as described in <u>Chapter 1</u>. Customize your project as described in <u>Chapter 2</u>.

### **Follow These Steps**

Complete this chapter in order to understand the state machine included with CCAT V2.



## **Understanding State Machine Logic**

Starting with Connected Components Accelerator Toolkit Version 2.0 (CCAT V2), all Micro800 Building Block projects incorporate state machine logic for coordinating overall machine operation. The state machine broadcasts commands and receives feedback information from each of the building blocks via user-modified application sequence programs (see <u>Chapter 4</u>). Based on the feedback information, the state machine reacts accordingly while in Auto mode. The core of the state machine logic is implemented in the RA\_STATE\_MACHINE User-Defined Function Block documented in <u>Appendix A</u>.

In addition, the state machine provides a high-level interface for an HMI terminal. While in Auto mode, commands such as Start, Stop, and Clear Faults are accepted. The state machine also provides status information (for example, Current State) that can be displayed on the HMI terminal. Refer to Appendix B for a complete list of state machine global variables.



#### **State Machine Diagram**



The state machine uses the transitional states to move between permanent states. Typically, the machine remains in a transitional state for a brief period of time. If an error is detected during a transitional state or if a building block fails to transition within an allotted time (10 seconds by default), the state machine issues an ABORT command. The fail safe transition timer assures that the overall machine does not become locked in a transitional state. This timer also helps to provide diagnostic information to determine which module is not transitioning properly.

The following table provides a brief description for each of the default machine states.

Machine State	State Type	Description
ABORTING	Transitional	<ul> <li>Broadcasts the ABORT command until confirmation that all of the building blocks are aborted. The ABORTING state is triggered based on feedback from the building blocks. The default ABORT conditions that place the machine into ABORTING state include:</li> <li>Power-up detected (in other words, controller first scan</li> <li>Building block or blocks not ready while the machine is in a STARTING and/or RUNNING state</li> <li>Building block or blocks detected a fault condition</li> <li>Building block or blocks failed to RESET</li> <li>Building block or blocks failed to START</li> <li>Building block or blocks failed to STOP</li> <li>Building block or blocks failed to CLEAR</li> </ul>
ABORTED	Permanent	All building blocks are aborted (for example, stopped and disabled). Typically this state indicates a fault condition.
CLEARING	Transitional	Broadcasts the CLEAR command until confirmation that all of the building blocks are OK (for example, all active drives have been cleared) within the allotted time, otherwise an ABORT condition is generated. Once all of the building blocks are OK, the machine is placed into the STOPPED state.
RESETTING	Transitional	Broadcasts the RESET command until confirmation that all of the building blocks are reset within the allotted time, otherwise an ABORT condition is generated.
IDLE	Permanent	All building blocks are reset or ready to run (for example, enabled, homed, and so forth). Typically this is the state that the machine is ready to run and awaits a START command.
STARTING	Transitional	Broadcasts the RESET command until confirmation that all of the building blocks are running within the allotted time, otherwise an ABORT condition is generated.
RUNNING	Permanent	All building blocks are running.
STOPPING	Transitional	Broadcasts the STOP command until confirmation that all of the building blocks are stopped within the allotted time, otherwise an ABORT condition is generated.
STOPPED	Permanent	All building blocks are stopped and ready.

The machine can go from any state in the shaded box to Stopping state.

#### **Machine Overview Screen**

The Machine Overview screen is the main screen for the PanelView 800 applications supplied with CCAT V2. The screen indicates which state the state machine is in and if it is faulted or ready. If the current state is aborted, then the reason the state machine entered the aborted state is indicated.

The following state machine screens are implemented in all CCAT V2 building block PanelView 800 applications.

Х	Mach	nine Overvi	ew		
FAULT	ED		First Scan	Button	Description
Ready	45	ADOITTED	Thist Scart	'X' button	Press to return to the PanelView 800 Configuration
				Stop Machine button	Press to stop machine
				Clear Faults button	Press to clear machine faults (appears when machine is faulted)
				Start Machine button	Press to start machine (appears when machine is not faulted)
				Machine Functions button	Press to go to Machine Functions screen
			Current; Switch To:	Manual/Auto button	Switches machine between Auto and Manual modes
Stop	Clear	Machine	Auto Manual		
macrime	Faults	Functions			
X	Mach	nine Overvi	ew		
ок		STOPPED	77		
Ready	455		-		
Stop	Start	Machine	Current: Switch To:		
Machine	Machine	Functions	Auto Manual		

#### **Machine Functions Screen**

The Machine Functions screen is the starting point for each of the building block specific screens.

	Mach	nine Functi	ons	X	Button	Description
Devic	e: PF5 xx				'X' button	Press to return to the Machine Overview screen
-					Building block button	Press to go to the specific building block overview screen
					Stop Machine button	Press to stop machine
				- 60	Clear Faults button	Press to clear machine faults (appears when machine is faulted)
					Start Machine button	Press to start machine (appears when machine is not faulted)
					Machine Functions button	Press to go to Machine State Diagram screen
			Current:	Switch To:	Manual/Auto button	Switches machine between Auto and Manual modes
Stop Machine	Start Machine	State Diagram	Auto	Manual		

#### **State Diagram Screen**



The State Diagram screen graphically shows which state the machine is in.

Button	Description
'X' button	Press to return to the Machine Functions screen
Stop Machine button	Press to stop machine
Clear Faults button	Press to clear machine faults (appears when machine is faulted)
Start Machine button	Press to start machine (appears when machine is not faulted)
Machine Monitor button	Press to go to Machine Monitor screen
Manual/Auto button	Switches machine between Auto and Manual modes

#### **Machine Monitor Screen**

The Machine Monitor screen shows the current on/off value of individual machine commands, machine status, and application status.



Button	Description
X' button	Press to return to the Machine State Diagram screen
Stop Machine button	Press to stop machine
Clear Faults button	Press to clear machine faults (appears when machine is faulted)
Start Machine button	Press to start machine (appears when machine is not faulted)

# Incorporate Building Block Examples into the Application Sequence Programs

This chapter helps you incorporate building block examples into your application sequence programs.

# **Before You Begin**

Create your project file by using the System Design Assistant as described in <u>Chapter 1</u>. Be familiar with the content presented in <u>Chapter 2</u> and <u>Chapter 3</u>. Complete the integration and validation of each of the individual building blocks included in your project by referring to the individual building block Quick Start manuals.

# **Understanding Application Sequence Programs**

Starting with Connected Components Accelerator Toolkit Version 2.0 (CCAT V2), all Micro800 Building Block projects incorporate the same MC\_StateMachine program and a set of application sequence programs that together control what the machine does while in each machine state.



Each Connected Components Workbench project produced by CCAT V2, as well as each building-block starting project, also includes a set of application sequence example programs specific to the building blocks being implemented. These programs can be used to incorporate the building blocks into the overall machine control. The following figure is an example of the application sequence example programs included with the PowerFlex 520-Series drives building block. Notice that the program names start with the sequence program name they are intended for, followed by "Example," and a short description of their functionality.



If the examples you need are not included in your project, use the Import function to add them.

Each of these example programs begins with a Return instruction in its first rung, which prevents the rest of the example program from ever executing. It is your responsibility to review each example and determine how you want to use the example in the intended sequence program. Following is an example of the process you should go through for each application sequence.

#### App\_Stop\_Seq\_Example\_PF5\_Stop\_Drive Example





1. Compare the provided example against the default App\_Stop\_Seq program.

2. Modify rungs 1 and 2 in the App\_Stop\_Seq program to function like the example rungs 2 and 3, assuming you want the drive to stop when the machine stops.

App_Stop_Seq-POU		
1	Stop Sequence	at Gran Companyon to 900
	La tier your stop sequence coue in this section. When your stop is complete, si	a diop dequerice to 555.
	=	PF5_xx_Cmd_Stop_Auto
	EN ol	
	App_Cfg_Stop_Seq	MOV
	- i1	EN ENO
		10 App Cfg Stop Seg
	12	
2	<u></u>	
2		
		PE5 vy Ste Active
	EN 01	
	App_Cfg_Stop_Seq	20 App_Cfg_Stop_Seq
	+i1	
	10	

- 3. Delete the App\_Stop\_Seq\_Example\_PF5\_Stop\_Drive program, as it is no longer needed.
- 4. Repeat this general procedure to complete the programming for the Abort, Clear, Reset and Run sequence programs as well.

# Notes:

# **State Machine User-defined Function Block**

This appendix describes the state machine user-defined function block and the associated inputs and outputs.

## **RA\_STATE\_MACHINE User-defined Function Block**

This user-defined function block (UDFB) provides a simple state machine for machine control that issues commands (start, stop, reset, clear faults, and abort) to and receives feedback information (running, stopped, reset, ready, OK, and aborted) from each of the building blocks (BBs).

RA_STAT	E_MACHINE
• FBEN	FBENO -
ClearFaults_PB	Cmd_Abort •
• Start_PB	Cmd_ClearFaults •
• Stop_PB	Cmd_Reset -
AutoModeEnabled	Cmd_Start -
• App_Aborted	Cmd_Stop -
• App_Idle	Mach_AbortCode -
• Арр_ОК	Mach_CurrentState •
• App_Ready	Mach_Aborted •
• App_Running	Mach_Aborting •
App_Stopped	Mach_Clearing •
•Clear_Delay	Mach_Idle •
•Reset_Delay	Mach_OK •
• Start_Delay	Mach_Ready •
• Stop_Delay	Mach_Resetting -
	Mach_Running -
	Mach_Starting -
	Mach_Stopped -
	Mach_Stopping -

Input Variable	Data Type	Description
FBEN	BOOL	Set this bit TRUE to enable the function block.
Clear_Faults_PB	BOOL	Pushbutton input to initiate the Clear Faults machine command.
Start_PB	BOOL	Pushbutton input to initiate the Start machine command.
Stop_PB	BOOL	Pushbutton input to initiate the Stop machine command.
AutoModeEnabled	BOOL	Input indicating that Auto mode is enabled.
App_Aborted	BOOL	Input indicating that all building blocks (BBs) are Aborted.
Арр_ОК	BOOL	Input indicating that all BBs are OK.
App_Ready	BOOL	Input indicating that all BBs are Ready.
App_Reset	BOOL	Input indicating that all BBs are Reset.
App_Running	BOOL	Input indicating that all BBs are Running.
App_Stopped	BOOL	Input indicating that all BBs are Stopped.
Clear_Delay	TIME	Maximum time after a Clear Faults command to wait for all BBs to be OK.
Reset_Delay	TIME	Maximum time after a Reset command to wait for all BBs to be Idle.
Start_Delay	TIME	Maximum time after a Start command to wait for all BBs to be Running.
Stop_Delay	TIME	Maximum time after a Stop command to wait for all BBs to be Stopped.

Output Variable	Data Type	Description
FBENO	BOOL	This bit is TRUE when the function block is enabled.
Cmd_Abort	BOOL	Machine command to all BBs to Abort.
Cmd_Reset	BOOL	Machine command to all BBs to Reset.
Cmd_ClearFaults	BOOL	Machine command to all BBs to Clear Faults.
Cmd_Start	BOOL	Machine command to all BBs to Start.
Cmd_Stop	BOOL	Machine command to all BBs to Stop.
Mach_AbortCode	UINT	Code indicating why the machine last aborted.
Mach_CurrentState	UINT	Integer representing the current machine state.
Mach_Aborting	BOOL	Machine state is Aborting when this bit is TRUE.
Mach_Aborted	BOOL	Machine state is Aborted when this bit is TRUE.
Mach_Clearing	BOOL	Machine state is Clearing when this bit is TRUE.
Mach_Idle	BOOL	Machine state is Idle when this bit is TRUE.
Mach_OK	BOOL	Machine state is OK when this bit is TRUE.
Mach_Ready	BOOL	Machine state is Ready when this bit is TRUE.
Mach_Resetting	BOOL	Machine state is Resetting when this bit is TRUE.
Mach_Running	BOOL	Machine state is Running when this bit is TRUE.
Mach_Starting	BOOL	Machine state is Starting when this bit is TRUE.
Mach_Stopped	BOOL	Machine state is Stopped when this bit is TRUE.
Mach_Stopping	BOOL	Machine state is Stopping when this bit is TRUE.

# **State Machine Global Variables**

This appendix provides a listing of the global variables used for program interfacing.

Variable Name
Mach_Cmd_Abort_Auto
Mach_Cmd_ClearFaults_Auto
Mach_Cmd_ClearFaults_PB
Mach_Cmd_Req_OperToAuto
Mach_Cmd_Req_OperToManual
Mach_Cmd_Req_ProgToAuto
Mach_Cmd_Req_ProgToManual
Mach_Cmd_Reset_Auto
Mach_Cmd_Start_Auto
Mach_Cmd_Start_PB
Mach_Cmd_Stop_Auto
Mach_Cmd_Stop_PB
Mach_Sts_AbortCode
Mach_Sts_Aborted
Mach_Sts_Aborting
Mach_Sts_AutoModeEnabled
Mach_Sts_AutoONS
Mach_Sts_Clearing
Mach_Sts_CurrentState
Mach_Sts_Idle
Mach_Sts_ManualModeEnabled
Mach_Sts_ManualONS
Mach_Sts_OK
Mach_Sts_Permissive_AutoToManual
Mach_Sts_Permissive_ManualToAuto
Mach_Sts_Ready
Mach_Sts_Resetting
Mach_Sts_Running
Mach_Sts_Starting
Mach_Sts_Stopped
Mach_Sts_Stopping

# Notes:

## **Rockwell Automation Support**

Rockwell Automation provides technical information on the Web to assist you in using its products. At <u>http://www.rockwellautomation.com/support</u>, you can find technical and application notes, sample code, and links to software service packs. You can also visit our Support Center at <u>https://rockwellautomation.custhelp.com/</u> for software updates, support chats and forums, technical information, FAQs, and to sign up for product notification updates.

In addition, we offer multiple support programs for installation, configuration, and troubleshooting. For more information, contact your local distributor or Rockwell Automation representative, or visit <a href="http://www.rockwellautomation.com/services/online-phone">http://www.rockwellautomation.com/services/online-phone</a>.

#### **Installation Assistance**

If you experience a problem within the first 24 hours of installation, review the information that is contained in this manual. You can contact Customer Support for initial help in getting your product up and running.

United States or Canada	1.440.646.3434
Outside United States or Canada	Use the <u>Worldwide Locator</u> at <u>http://www.rockwellautomation.com/rockwellautomation/support/overview.page</u> , or contact your local Rockwell Automation representative.

#### **New Product Satisfaction Return**

Rockwell Automation tests all of its products to help ensure that they are fully operational when shipped from the manufacturing facility. However, if your product is not functioning and needs to be returned, follow these procedures.

United States	Contact your distributor. You must provide a Customer Support case number (call the phone number above to obtain one) to your distributor to complete the return process.
Outside United States	Please contact your local Rockwell Automation representative for the return procedure.

## **Documentation Feedback**

Your comments will help us serve your documentation needs better. If you have any suggestions on how to improve this document, complete this form, publication <u>RA-DU002</u>, available at <u>http://www.rockwellautomation.com/literature/</u>.

Rockwell Automation maintains current product environmental information on its website at <a href="http://www.rockwellautomation.com/rockwellautomation/about-us/sustainability-ethics/product-environmental-compliance.page">http://www.rockwellautomation.com/rockwellautomation/about-us/sustainability-ethics/product-environmental-compliance.page</a>.

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