Old Company Name in Catalogs and Other Documents

On April 1st, 2010, NEC Electronics Corporation merged with Renesas Technology Corporation, and Renesas Electronics Corporation took over all the business of both companies. Therefore, although the old company name remains in this document, it is a valid Renesas Electronics document. We appreciate your understanding.

Renesas Electronics website: http://www.renesas.com

April 1st, 2010 Renesas Electronics Corporation

Issued by: Renesas Electronics Corporation (http://www.renesas.com)

Send any inquiries to http://www.renesas.com/inquiry.

Notice

- 1. All information included in this document is current as of the date this document is issued. Such information, however, is subject to change without any prior notice. Before purchasing or using any Renesas Electronics products listed herein, please confirm the latest product information with a Renesas Electronics sales office. Also, please pay regular and careful attention to additional and different information to be disclosed by Renesas Electronics such as that disclosed through our website.
- Renesas Electronics does not assume any liability for infringement of patents, copyrights, or other intellectual property rights of third parties by or arising from the use of Renesas Electronics products or technical information described in this document. No license, express, implied or otherwise, is granted hereby under any patents, copyrights or other intellectual property rights of Renesas Electronics or others.
- 3. You should not alter, modify, copy, or otherwise misappropriate any Renesas Electronics product, whether in whole or in part.
- 4. Descriptions of circuits, software and other related information in this document are provided only to illustrate the operation of semiconductor products and application examples. You are fully responsible for the incorporation of these circuits, software, and information in the design of your equipment. Renesas Electronics assumes no responsibility for any losses incurred by you or third parties arising from the use of these circuits, software, or information.
- 5. When exporting the products or technology described in this document, you should comply with the applicable export control laws and regulations and follow the procedures required by such laws and regulations. You should not use Renesas Electronics products or the technology described in this document for any purpose relating to military applications or use by the military, including but not limited to the development of weapons of mass destruction. Renesas Electronics products and technology may not be used for or incorporated into any products or systems whose manufacture, use, or sale is prohibited under any applicable domestic or foreign laws or regulations.
- 6. Renesas Electronics has used reasonable care in preparing the information included in this document, but Renesas Electronics does not warrant that such information is error free. Renesas Electronics assumes no liability whatsoever for any damages incurred by you resulting from errors in or omissions from the information included herein.
- 7. Renesas Electronics products are classified according to the following three quality grades: "Standard", "High Quality", and "Specific". The recommended applications for each Renesas Electronics product depends on the product's quality grade, as indicated below. You must check the quality grade of each Renesas Electronics product before using it in a particular application. You may not use any Renesas Electronics product for any application categorized as "Specific" without the prior written consent of Renesas Electronics. Further, you may not use any Renesas Electronics. Renesas Electronics shall not be in any way liable for any damages or losses incurred by you or third parties arising from the use of any Renesas Electronics product for an application categorized as "Specific" or for which the product is not intended where you have failed to obtain the prior written consent of Renesas Electronics. The quality grade of each Renesas Electronics product is "Standard" unless otherwise expressly specified in a Renesas Electronics data sheets or data books, etc.
 - "Standard": Computers; office equipment; communications equipment; test and measurement equipment; audio and visual equipment; home electronic appliances; machine tools; personal electronic equipment; and industrial robots.
 - "High Quality": Transportation equipment (automobiles, trains, ships, etc.); traffic control systems; anti-disaster systems; anticrime systems; safety equipment; and medical equipment not specifically designed for life support.
 - "Specific": Aircraft; aerospace equipment; submersible repeaters; nuclear reactor control systems; medical equipment or systems for life support (e.g. artificial life support devices or systems), surgical implantations, or healthcare intervention (e.g. excision, etc.), and any other applications or purposes that pose a direct threat to human life.
- 8. You should use the Renesas Electronics products described in this document within the range specified by Renesas Electronics, especially with respect to the maximum rating, operating supply voltage range, movement power voltage range, heat radiation characteristics, installation and other product characteristics. Renesas Electronics shall have no liability for malfunctions or damages arising out of the use of Renesas Electronics products beyond such specified ranges.
- 9. Although Renesas Electronics endeavors to improve the quality and reliability of its products, semiconductor products have specific characteristics such as the occurrence of failure at a certain rate and malfunctions under certain use conditions. Further, Renesas Electronics products are not subject to radiation resistance design. Please be sure to implement safety measures to guard them against the possibility of physical injury, and injury or damage caused by fire in the event of the failure of a Renesas Electronics product, such as safety design for hardware and software including but not limited to redundancy, fire control and malfunction prevention, appropriate treatment for aging degradation or any other appropriate measures. Because the evaluation of microcomputer software alone is very difficult, please evaluate the safety of the final products or system manufactured by you.
- 10. Please contact a Renesas Electronics sales office for details as to environmental matters such as the environmental compatibility of each Renesas Electronics product. Please use Renesas Electronics products in compliance with all applicable laws and regulations that regulate the inclusion or use of controlled substances, including without limitation, the EU RoHS Directive. Renesas Electronics assumes no liability for damages or losses occurring as a result of your noncompliance with applicable laws and regulations.
- 11. This document may not be reproduced or duplicated, in any form, in whole or in part, without prior written consent of Renesas Electronics.
- 12. Please contact a Renesas Electronics sales office if you have any questions regarding the information contained in this document or Renesas Electronics products, or if you have any other inquiries.
- (Note 1) "Renesas Electronics" as used in this document means Renesas Electronics Corporation and also includes its majorityowned subsidiaries.
- (Note 2) "Renesas Electronics product(s)" means any product developed or manufactured by or for Renesas Electronics.





μ**PD750108**

4-bit Single-Chip Microcontrollers

μ**PD750104** μ**PD750106** μ**PD750108** μ**PD75P0116**

Document No. U11330EJ2V1UM00 (2nd edition) Date Published December 1999 J CP(K)

© NEC Corporation 1996 Printed in Japan [MEMO]

① PRECAUTION AGAINST ESD FOR SEMICONDUCTORS

Note:

Strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it once, when it has occurred. Environmental control must be adequate. When it is dry, humidifier should be used. It is recommended to avoid using insulators that easily build static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work bench and floor should be grounded. The operator should be grounded using wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with semiconductor devices on it.

② HANDLING OF UNUSED INPUT PINS FOR CMOS

Note:

No connection for CMOS device inputs can be cause of malfunction. If no connection is provided to the input pins, it is possible that an internal input level may be generated due to noise, etc., hence causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using a pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND with a resistor, if it is considered to have a possibility of being an output pin. All handling related to the unused pins must be judged device by device and related specifications governing the devices.

③ STATUS BEFORE INITIALIZATION OF MOS DEVICES

Note:

Power-on does not necessarily define initial status of MOS device. Production process of MOS does not define the initial operation status of the device. Immediately after the power source is turned ON, the devices with reset function have not yet been initialized. Hence, power-on does not guarantee out-pin levels, I/O settings or contents of registers. Device is not initialized until the reset signal is received. Reset operation must be executed immediately after power-on for devices having reset function.

MS-DOS is a trademark of Microsoft Corporation. IBM DOS, PC/AT, and PC DOS are trademarks of IBM Corporation. The export of this product from Japan is regulated by the Japanese government. To export this product may be prohibited without governmental license, the need for which must be judged by the customer. The export or re-export of this product from a country other than Japan may also be prohibited without a license from that country. Please call an NEC sales representative.

- The information in this document is subject to change without notice. Before using this document, please confirm that this is the latest version.
- Not all devices/types available in every country. Please check with local NEC representative for availability and additional information.
- No part of this document may be copied or reproduced in any form or by any means without the prior written consent of NEC Corporation. NEC Corporation assumes no responsibility for any errors which may appear in this document.
- NEC Corporation does not assume any liability for infringement of patents, copyrights or other intellectual property
 rights of third parties by or arising from use of a device described herein or any other liability arising from use
 of such device. No license, either express, implied or otherwise, is granted under any patents, copyrights or other
 intellectual property rights of NEC Corporation or others.
- Descriptions of circuits, software, and other related information in this document are provided for illustrative purposes in semiconductor product operation and application examples. The incorporation of these circuits, software, and information in the design of the customer's equipment shall be done under the full responsibility of the customer. NEC Corporation assumes no responsibility for any losses incurred by the customer or third parties arising from the use of these circuits, software, and information.
- While NEC Corporation has been making continuous effort to enhance the reliability of its semiconductor devices, the possibility of defects cannot be eliminated entirely. To minimize risks of damage or injury to persons or property arising from a defect in an NEC semiconductor device, customers must incorporate sufficient safety measures in its design, such as redundancy, fire-containment, and anti-failure features.
- NEC devices are classified into the following three quality grades:

"Standard", "Special", and "Specific". The Specific quality grade applies only to devices developed based on a customer designated "quality assurance program" for a specific application. The recommended applications of a device depend on its quality grade, as indicated below. Customers must check the quality grade of each device before using it in a particular application.

- Standard: Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots
- Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)
- Specific: Aircraft, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

The quality grade of NEC devices is "Standard" unless otherwise specified in NEC's Data Sheets or Data Books. If customers intend to use NEC devices for applications other than those specified for Standard quality grade, they should contact an NEC sales representative in advance.

Regional Information

Some information contained in this document may vary from country to country. Before using any NEC product in your application, please contact the NEC office in your country to obtain a list of authorized representatives and distributors. They will verify:

- · Device availability
- Ordering information
- Product release schedule
- · Availability of related technical literature
- Development environment specifications (for example, specifications for third-party tools and components, host computers, power plugs, AC supply voltages, and so forth)
- Network requirements

In addition, trademarks, registered trademarks, export restrictions, and other legal issues may also vary from country to country.

NEC Electronics Inc. (U.S.)

Santa Clara, California Tel: 408-588-6000 800-366-9782 Fax: 408-588-6130 800-729-9288

NEC Electronics (Germany) GmbH

Duesseldorf, Germany Tel: 0211-65 03 02 Fax: 0211-65 03 490

NEC Electronics (UK) Ltd.

Milton Keynes, UK Tel: 01908-691-133 Fax: 01908-670-290

NEC Electronics Italiana s.r.l.

Milano, Italy Tel: 02-66 75 41 Fax: 02-66 75 42 99

NEC Electronics (Germany) GmbH Benelux Office Eindhoven, The Netherlands Tel: 040-2445845 Fax: 040-2444580

NEC Electronics (France) S.A. Velizy-Villacoublay, France Tel: 01-30-67 58 00 Fax: 01-30-67 58 99

NEC Electronics (France) S.A.

Spain Office Madrid, Spain Tel: 91-504-2787 Fax: 91-504-2860

NEC Electronics (Germany) GmbH Scandinavia Office Taeby, Sweden Tel: 08-63 80 820 Fax: 08-63 80 388

NEC Electronics Hong Kong Ltd. Hong Kong Tel: 2886-9318 Fax: 2886-9022/9044

NEC Electronics Hong Kong Ltd. Seoul Branch Seoul, Korea Tel: 02-528-0303 Fax: 02-528-4411

NEC Electronics Singapore Pte. Ltd. United Square, Singapore 1130 Tel: 65-253-8311 Fax: 65-250-3583

NEC Electronics Taiwan Ltd. Taipei, Taiwan Tel: 02-2719-2377 Fax: 02-2719-5951

NEC do Brasil S.A.

Electron Devices Division Rodovia Presidente Dutra, Km 214 07210-902-Guarulhos-SP Brasil Tel: 55-11-6465-6810 Fax: 55-11-6465-6829

J99.1

Major Changes

Page	Description
Throughout	The μPD750104, μPD750106, μPD750108, and μPD75P0116 have already been developed.
	Data bus pins (D0-D7) have been added.
p.21	Section 2.4 has been changed.
pp.234 to 235	Section 9.2 has been changed.
p.236	Section 9.3 has been changed.
p.267	Modification of the instruction list in 11.3 Op code of Each Instruction .
pp.303 to 304	The target for comparison, in the table of Appendix A has been changed from the μ PD75008 to the μ PD750008.
p.325	Appendix F has been added.

The mark * shows major revised points.

PREFACE

Readers This manual is intended for engineers who want to learn the capabilities of the μPD750104, μPD750106, μPD750108, and μPD75P0116 to develop application systems based on them. Purpose The purpose of this manual is to help users understand the hardware capabilities (shown below) of the µPD750104, µPD750106, µPD750108, and µPD75P0116. Configuration This manual is roughly divided as follows: General Pin functions Architecture feature and memory map • Internal CPU functions • Peripheral hardware functions Interrupt and test functions Standby function Reset function Writing to and verifying program memory (PROM) Mask option Instruction set Guidance Readers of this manual should have general knowledge of the electronics, logical circuit, and microcomputer fields. • For users who have used the μPD750008: -> See Appendix A to check for any difference in the functions and read the explanation of those differences. To check the functions of an instruction in detail when the reader knows its mnemonics: -> See the instruction index in Appendix D. To check the functions of specific internal circuits, etc.: -> See Appendix E. To understand the overall functions of the μPD750104, μPD750106, μPD750108, and µPD75P0116: -> Read through all chapters sequentially.

Data bit significance	: Higher-order bits on the left side
	Lower-order bits on the right side
Active low	: xxx (Pin and signal names are overscored.)
Memory map address	: Low-order address on the upper side
	High-order address on the lower side
Note	: Explanation of an indicated part of text
Caution	: Information requesting the user's special attention
Remark	: Supplementary information
Important and emphasized matte	r : Described in bold face
Numeric value	: Binary xxxx or xxxxB
	Decimal xxxx
	Hexadecimal xxxxH

Notation

* **Related documents** Some documents are preliminary editions, but they are not so specified in the tables below.

Documents related to devices

Document name	Document number		
	Japanese	English	
μPD750104, 750106, 750108, 750104(A), 750106(A), 750108(A) Data Sheet	U12301J	U12301E	
μPD75P0116 Data Sheet	U12603J	U12603E	
μPD750108 User's Manual	U11330J	U11330E (This manual)	
μPD750008, 750108 Instruction List	U11456J	_	
75XL Series Selection Guide	U10453J	U10453E	

Documents related to development tools

Document name				Documen	t number
	Doct	Japanese	English		
Hardware	IE-75000-R/IE-75001-R User's Manual			EEU-846	EEU-1416
	IE-75300-R-EM User's Manual			U11354J	U11354E
	EP-75008CU-R Use	r's Manual		EEU-699	EEU-1317
	EP-75008GB-R Use	r's Manual		EEU-698	EEU-1305
	PG-1500 User's Mar	nual		U11940J	EEU-1335
Software	RA75X Assembler P	ackage User's	Operation	EEU-731	EEU-1346
	Manual		Language	EEU-730	EEU-1363
	PG-1500 Controller	PC-9800 Series (MS-DOS TM) Base		EEU-704	EEU-1291
	User's Manual	IBM PC Series (PC DOS TM) Base		EEU-5008	U10540E

Other documents

Document name	Document number		
	Japanese	English	
SEMICONDUCTORS SELECTION GUIDE Products & Packages (CD-ROM)	X13769X		
Semiconductor Device Mounting Technology Manual	C10535J	C10535E	
Quality Grade on NEC Semiconductor Devices	C11531J	C11531E	
NEC Semiconductor Device Reliability and Quality Control System	C10983J	C10983E	
Guide to Prevent Damage for Semiconductor Devices by Electrostatic Discharge (ESD)	C11892J	C11892E	
Microcontroller-Related Products Guide - by third parties	U11416J	_	

Caution The above related documents are subject to change without notice. Be sure to use the latest edition when you design your system.

[MEMO]

CONTENTS

CHAPTER 1	GEN	IERAL		1
	1.1	FUNCT	ION OVERVIEW	2
	1.2	ORDER	ING INFORMATION	3
	1.3	DIFFER	ENCES AMONG μPD750108 SUBSERIES PRODUCTS	4
	1.4	BLOCK	DIAGRAM	5
	1.5	PIN CO	NFIGURATION (TOP VIEW)	6
CHAPTER 2	PIN	FUNCTIO	DNS	9
	2.1	PIN FU	NCTIONS OF THE μ PD750108	9
	2.2	PIN FU	NCTIONS	13
		2.2.1	P00-P03 (PORT0), P10-P13 (PORT1)	13
		2.2.2	P20-P23 (PORT2), P30-P33 (PORT3), P40-P43 (PORT4),	
			P50-P53 (PORT5), P60-P63 (PORT6), P70-P73 (PORT7)	13
		2.2.3	P80, P81 (PORT8)	14
		2.2.4	ТІО	14
		2.2.5	PTO0, PTO1	15
		2.2.6	PCL	15
		2.2.7	BUZ	15
		2.2.8	SCK, SO/SB0, SI/SB1	15
		2.2.9	INT4	15
		2.2.10	INT0, INT1	16
		2.2.11	INT2	16
		2.2.12	KR0-KR3, KR4-KR7	17
		2.2.13	CL1, CL2	17
		2.2.14	XT1, XT2	17
		2.2.15	RESET	18
		2.2.16	VDD	18
		2.2.17	VSS	18
		2.2.18	IC (for the μ PD750104, μ PD750106, and μ PD750108 only)	18
		2.2.19	VPP (for the μ PD75P0116 only)	18
		2.2.20	MD0-MD3 (for the μ PD75P0116 only)	18
		2.2.21	D0-D7 (for the μPD75P0116 only)	18
	2.3	PIN INF	PUT/OUTPUT CIRCUITS	19
	2.4	CONNE	CTION OF UNUSED PINS	21
CHAPTER 3	FEA	TURES (OF THE ARCHITECTURE AND MEMORY MAP	23
	3.1		IEMORY BANK STRUCTURE AND ADDRESSING MODES	23

*

		3.1.1	Data Memory Bank Structure	23
		3.1.2	Data Memory Addressing Modes	25
	3.2	GENEF	RAL REGISTER BANK CONFIGURATION	36
	3.3	MEMO	RY-MAPPED I/O	41
CHAPTER 4	INTE	ERNAL C	PU FUNCTIONS	47
	4.1	Mk I M	ODE/Mk II MODE SWITCH FUNCTIONS	47
		4.1.1	Differences between Mk I Mode and Mk II Mode	47
		4.1.2	Setting of the Stack Bank Selection Register (SBS)	48
	4.2	PROG	RAM COUNTER (PC)	49
	4.3	PROG	RAM MEMORY (ROM)	50
	4.4	DATA I	MEMORY (RAM): 512 WORDS x 4 BITS	55
		4.4.1	Data Memory Configuration	55
		4.4.2	Specification of a Data Memory Bank	56
	4.5	GENEF	RAL REGISTER: 8 x 4 BITS x 4 BANKS	58
	4.6	ACCUN	/ULATOR	59
	4.7	STACK	(POINTER (SP) AND STACK BANK SELECT REGISTER (SBS)	60
	4.8	PROG	RAM STATUS WORD (PSW)	64
	4.9	BANK	SELECT REGISTER (BS)	67
CHAPTER 5	PER	IPHERA	L HARDWARE FUNCTIONS	69
	5.1	DIGITA	L I/O PORTS	69
		5.1.1	Types, Features, and Configurations of Digital I/O Ports	70
		5.1.2	I/O Mode Setting	76
		5.1.3	Digital I/O Port Manipulation Instructions	78
		5.1.4	Digital I/O Port Operation	81
		5.1.5	Specification of Built-In Pull-Up Resistors	83
		5.1.6	I/O Timing of Digital I/O Ports	84
	5.2	CLOCK	GENERATOR	86
		5.2.1	Clock Generator Configuration	86
		5.2.2	Functions and Operations of the Clock Generator	87
		5.2.3	System Clock and CPU Clock Setting	98
		5.2.4	Clock Output Circuit	100
	5.3	BASIC	INTERVAL TIMER/WATCHDOG TIMER	103
		5.3.1	Configuration of the Basic Interval Timer/Watchdog Timer	103
		5.3.2	Basic Interval Timer Mode Register (BTM)	103
		5.3.3	Watchdog Timer Enable Flag (WDTM)	105
		5.3.4	Operation of the Basic Interval Timer	105
		5.3.5	Operation of the Watchdog Timer	106
		5.3.6	Other Functions	107

	5.4	CLOCK	TIMER	108
		5.4.1	Configuration of the Clock Timer	109
		5.4.2	Clock Mode Register	109
	5.5	TIMER/I	EVENT COUNTER	111
		5.5.1	Configuration of Timer/Event Counter	111
		5.5.2	8-Bit Timer/Event Counter Mode Operation	117
		5.5.3	Notes on Timer/Event Counter Applications	123
	5.6	SERIAL	INTERFACE	126
		5.6.1	Serial Interface Functions	126
		5.6.2	Configuration of Serial Interface	127
		5.6.3	Register Functions	130
		5.6.4	Operation Halt Mode	138
		5.6.5	Three-Wire Serial I/O Mode Operations	140
		5.6.6	Two-Wire Serial I/O Mode	147
		5.6.7	SBI Mode Operation	153
		5.6.8	Manipulation of SCK Pin Output	182
	5.7	BIT SEC	QUENTIAL BUFFER	184
CHAPTER 6	INTE	RRUPT	AND TEST FUNCTIONS	187
	6.1	CONFIG	GURATION OF THE INTERRUPT CONTROL CIRCUIT	187
	6.2	TYPES	OF INTERRUPT SOURCES AND VECTOR TABLES	189
	6.3	VARIOL	JS DEVICES TO CONTROL INTERRUPT FUNCTIONS	191
	6.4	INTERR	UPT SEQUENCE	199
	6.5	MULTIP	LE INTERRUPT PROCESSING CONTROL	200
	6.6	PROCE	SSING OF INTERRUPTS SHARING A VECTOR ADDRESS	202
	6.7	MACHIN	NE CYCLES FOR STARTING INTERRUPT PROCESSING	204
	6.8	EFFECT	TIVE USE OF INTERRUPTS	206
	6.9	INTERR	UPT APPLICATIONS	206
	6.10	TEST F	UNCTION	214
		6.10.1	Test Sources	214
		6.10.2	Hardware to Control Test Functions	214
CHAPTER 7	STA	NDBY FL	JNCTION	219
	7.1	SETTIN	G OF STANDBY MODES AND OPERATION STATUS	220
	7.2	RELEAS	SE OF THE STANDBY MODES	221
	7.3	OPERA	TION AFTER A STANDBY MODE IS RELEASED	223
	7.4	SELECT	TION OF A MASK OPTION	223
	7.5	APPLIC	ATIONS OF THE STANDBY MODES	224

CHAPTER 8	RESI	ET FUNC	TION	229
CHAPTER 9	WRIT		AND VERIFYING PROGRAM MEMORY (PROM)	233
	9.1	OPERAT	TING MODES WHEN WRITING TO AND VERIFYING THE PROGRAM	
		MEMOR	Υ	234
	9.2	WRITIN	G TO THE PROGRAM MEMORY	234
	9.3	READIN	G THE PROGRAM MEMORY	236
	9.4	SCREEM	NING OF ONE-TIME PROM	237
CHAPTER 10	MAS	Κ ΟΡΤΙΟ	N	239
	10.1	PIN		239
	10.2	MASK C	PTION OF STANDBY FUNCTION	239
	10.3	MASK C	PTION FOR FEEDBACK RESISTOR OF SUBSYSTEM CLOCK	240
CHAPTER 11	INST	RUCTIO	N SET	241
	11.1	UNIQUE	INSTRUCTIONS	241
		11.1.1	GETI Instruction	241
		11.1.2	Bit Manipulation Instruction	242
		11.1.3	String-Effect Instructions	242
		11.1.4	Number System Conversion Instructions	243
		11.1.5	Skip Instructions and the Number of Machine Cycles Required for	
			a Skip	244
	11.2	INSTRU	CTION SET AND OPERATION	245
	11.3	INSTRU	CTION CODES OF EACH INSTRUCTION	262
	11.4	FUNCTI	ONS AND APPLICATIONS OF THE INSTRUCTIONS	268
		11.4.1	Transfer Instructions	268
		11.4.2	Table Reference Instructions	274
		11.4.3	Bit Transfer Instructions	277
		11.4.4	Arithmetic/Logical Instructions	277
		11.4.5	Accumulator Manipulation Instructions	283
		11.4.6	Increment/Decrement Instructions	283
		11.4.7	Compare Instructions	284
		11.4.8	Carry Flag Manipulation Instructions	285
		11.4.9	Memory Bit Manipulation Instructions	
		11.4.10	Branch Instructions	288
		11.4.11	Subroutine Stack Control Instructions	293
		11.4.12	Interrupt Control Instructions	297
		11.4.13	I/O Instructions	298
		11.4.14	CPU Control Instructions	299
		11.4.15	Special Instructions	299

APPENDIX A	UNCTIONS OF THE μ PD750008, μ PD750108, AND μ PD75P0116				
APPENDIX B	DEVELOPMENT TOOLS	305			
APPENDIX C	MASKED ROM ORDERING PROCEDURE	313			
APPENDIX D	INSTRUCTION INDEX	315			
	D.1 INSTRUCTION INDEX (BY FUNCTION)	315			
	D.2 INSTRUCTION INDEX (ALPHABETICAL ORDER)	318			
APPENDIX E	HARDWARE INDEX	321			
	E.1 HARDWARE INDEX (ALPHABETICAL ORDER WITH RESPECT TO THE				
	HARDWARE NAME)	321			
	E.2 HARDWARE INDEX (ALPHABETICAL ORDER WITH RESPECT TO THE				
	HARDWARE SYMBOL)	323			
APPENDIX F	REVISION HISTORY	325			

*

LIST OF FIGURES (1/4)

Figure No.	Title	Page
2-1	Pin Input/Output Circuits	19
3-1	Use of MBE = 0 Mode and MBE = 1 Mode	24
3-2.	Data Memory Organization and Addressing Range of Each Addressing Mode	26
3-3	Updating Static RAM Addresses	30
3-4.	Example of Register Bank Selection	37
3-5.	General Register Configuration (4-Bit Processing)	39
3-6	General Register Configuration (8-Bit Processing)	40
3-7	μPD750108 I/O Map	42
4-1	Stack Bank Selection Register Format	48
4-2	Program Counter Organization	49
4-3	Program Memory Map (in μPD750104)	51
4-4	Program Memory Map (in μPD750106)	52
4-5	Program Memory Map (in μPD750108)	53
4-6	Program Memory Map (in μPD75P0116)	54
4-7	Data Memory Map	56
4-8	General Register Format	58
4-9	Register Pair Format	59
4-10	Accumulator	59
4-11	Format of Stack Pointer and Stack Bank Select Register	61
4-12	Data Saved to the Stack Memory (Mk I Mode)	62
4-13	Data Restored from the Stack Memory (Mk I Mode)	62
4-14	Data Saved to the Stack Memory (Mk II Mode)	63
4-15	Data Restored from the Stack Memory (Mk II Mode)	63
4-16	Program Status Word Format	64
4-17	Bank Select Register Format	67
5-1	Data Memory Addresses of Digital Ports	69
5-2	Configurations of Ports 0 and 1	71
5-3	Configurations of Ports 2 and 7	72
5-4	Configurations of Ports 3n and 6n (n = 0 to 3)	73
5-5.	Configurations of Ports 4 and 5	74
5-6	Configuration of Port 8	75
5-7	Formats of Port Mode Registers	77
5-8	Pull-Up Resistor Specification Register Format	84

LIST OF FIGURES (2/4)

Figure No.	Title	Page
5-9	I/O Timing Chart of Digital I/O Ports	
5-10	ON Timing Chart of Built-In Pull-Up Resistor Connected by Software	85
5-11	Block Diagram of the Clock Generator	86
5-12	Format of the Processor Clock Control Register	89
5-13	Format of the System Clock Control Register	90
5-14	External Circuit for the Main System Clock Oscillator	91
5-15	External Circuit for the Subsystem Clock Oscillator	91
5-16	Examples of Oscillator Connections Which Should Be Avoided	92
5-17	Subsystem Clock Oscillator	96
5-18	Sub-Oscillator Control Register (SOS) Format	97
5-19	Changing the System Clock and CPU Clock	99
5-20	Configuration of the Clock Output Circuit	100
5-21	Format of the Clock Output Mode Register	101
5-22	Application to Remote Control Waveform Output	102
5-23	Block Diagram of the Basic Interval Timer/Watchdog Timer	103
5-24	Format of the Basic Interval Timer Mode Register	104
5-25	Format of the Watchdog Timer Enable Flag (WDTM)	105
5-26	Block Diagram of the Clock Timer	109
5-27	Clock Mode Register Format	110
5-28	Block Diagram of the Timer/Event Counter (Channel 0)	112
5-29	Block Diagram of the Timer Counter (Channel 1)	113
5-30	Timer/Event Counter Mode Register (channel 0) Format	115
5-31	Timer Counter Mode Register (Channel 1) Format	116
5-32	Timer/Event Counter Output Enable Flag Format	117
5-33	Timer/Event Counter Mode Register Setup	118
5-34	Timer/Event Counter Output Enable Flag Setup	119
5-35	Configuration of Timer/Event Counter	121
5-36	Count Operation Timing	122
5-37	Error at the Start of the Timer	123
5-38	Example of the SBI System Configuration	127
5-39	Block Diagram of the Serial Interface	128
5-40	Format of Serial Operation Mode Register (CSIM)	130
5-41	Format of Serial Bus Interface Control Register (SBIC)	134
5-42	Peripheral Hardware of Shift Register	137
5-43	Example of Three-Wire Serial I/O System Configuration	140
5-44	Timing of Three-Wire Serial I/O Mode	143

LIST OF FIGURES (3/4)

Figure No.	Title	Page
5-45	Operations of RELT and CMDT	144
5-46	Transfer Bit Switching Circuit	144
5-47	Example of Two-Wire Serial I/O System Configuration	147
5-48	Timing of Two-Wire Serial I/O Mode	150
5-49	Operations of RELT and CMDT	151
5-50	Example of SBI System Configuration	153
5-51	Timing of SBI Transfer	155
5-52	Bus Release Signal	156
5-53	Command Signal	156
5-54	Address	156
5-55	Slave Selection Using an Address	157
5-56	Command	157
5-57	Data	157
5-58	Acknowledge Signal	158
5-59	Busy and Ready Signals	159
5-60	Operations of RELT, CMDT, RELD, and CMDD (Master)	164
5-61	Operations of RELT, CMDT, RELD, and CMDD (Slave)	164
5-62	Operation of ACKT	165
5-63	Operation of ACKE	165
5-64	Operation of ACKD	166
5-65	Operation of BSYE	167
5-66	Pin Configuration	170
5-67	Address Transfer Operation from Master Device to Slave Device (WUP = 1)	172
5-68	Command Transfer Operation from Master Device to Slave Device	173
5-69	Data Transfer Operation from Master Device to Slave Device	174
5-70	Data Transfer Operation from Slave Device to Master Device	175
5-71	Example of Serial Bus Configuration	177
5-72	Transfer Format of the READ Command	178
5-73	Transfer Format of the WRITE and END Commands	179
5-74	Transfer Format of the STOP Command	179
5-75	Transfer Format of the STATUS Command	180
5-76	Status Format of the STATUS Command	180
5-77	Transfer Format of the RESET Command	181
5-78	Transfer Format of the CHGMST Command	181
5-79	Master and Slave Operation in Case of Error	182
5-80	SCK/P01 Pin Circuit Configuration	183
5-81	Format of the Bit Sequential Buffer	184

LIST OF FIGURES (4/4)

Figure No.	Title	Page
6-1	Block Diagram of Interrupt Control Circuit	188
6-2	Interrupt Vector Table	189
6-3	Interrupt Priority Specification Register	193
6-4	Configurations of the INT0, INT1, and INT4 Circuits	195
6-5	I/O Timing of a Noise Eliminator	196
6-6	Format of Edge Detection Mode Registers	197
6-7	Interrupt Sequence	199
6-8	Multiple Interrupt Processing by a High-Order Interrupt	200
6-9	Multiple Interrupt Processing by Changing the Interrupt Status Flags	201
6-10	Block Diagram of the INT2 and KR0 to KR7 Circuits	216
6-11	Format of INT2 Edge Detection Mode Register (IM2)	217
7-1	Standby Mode Release Operation	221
8-1	Configuration of Reset Functions	229
8-2	Reset Operation by Generation of RESET Signal	229
B-1	Drawings of the EV-9200G-44 (Reference)	310
B-2	Recommended Pattern on Boards for the EV-9200G-44 (Reference)	311

LIST OF TABLES (1/2)

Table No.	Title	Page
2-1	Digital I/O Port Pins	9
2-2	Non-Port Pin Functions	11
2-3	Connection of Unused Pins	21
3-1	Addressing Modes	27
3-2	Register Bank to Be Selected with the RBE and RBS	36
3-3	Recommended Use of Register Banks with Normal Routines and Interrupt Routi	nes . 36
3-4	Addressing Modes Applicable to Peripheral Hardware Operation	41
4-1	Differences between Mk I Mode and Mk II Mode	47
4-2	Stack Area to Be Selected by the SBS	60
4-3	PSW Flags Saved/Restored in Stack Operation	64
4-4	Carry Flag Manipulation Instructions	65
4-5	Information Indicated by the Interrupt Status Flag	66
4-6	Register Bank to Be Selected with the RBE and RBS	68
5-1	Types and Features of Digital Ports	70
5-2	I/O Pin Manipulation Instructions	80
5-3	Operations by I/O Port Manipulation Instructions	82
5-4	Specification of Built-In Pull-Up Resistors	83
5-5	Maximum Time Required to Change the System Clock and CPU Clock	98
5-6	Resolution and Longest Setup Time	120
5-7	Serial Clock Selection and Application (in the Three-Wire Serial I/O Mode)	143
5-8	Serial Clock Selection and Application (in the Two-Wire Serial I/O Mode)	151
5-9	Serial Clock Selection and Application (in the SBI Mode)	163
5-10	Various Signals Used in the SBI Mode	168
6-1	Interrupt Sources	189
6-2	Set Signals for Interrupt Request Flags	192
6-3	Interrupt Processing Statuses of IST0 and IST1	198
6-4	Identifying Interrupt Sharing Vector Table Address	202
6-5	Test Source	214
6-6	Signals Setting Test Request Flags	214
7-1	Operation Statuses in the Standby Mode	220

LIST OF TABLES (2/2)

Table No.	Title	Page
8-1	Status of the Hardware after a Reset	230
10-1	Selecting Mask Option of Pin	239
11-1	Types of Bit Manipulation Addressing Modes and Specification Range	242

[MEMO]

CHAPTER 1 GENERAL

The μ PD750104, μ PD750106, μ PD750108, and μ PD75P0116 are 75XL series 4-bit single-chip microcontrollers. The 75XL series is a successor of the 75X series consisting of many products. These μ PD750104, μ PD750106, μ PD750108, and μ PD75P0116 are collectively called the μ PD750108 subseries.

The μ PD750108 subseries is produced by replacing the main system clock oscillator of the μ PD750008 subseries with an RC oscillator, enabling operation at the relatively low voltage of 1.8 V.

The 75XL series takes over the CPUs of the 75X series, realizing a wide range of operating voltages. In addition to having upward compatibility with existing products, the 75XL series is best suited for battery-driven applications.

The μ PD750104, μ PD750106, μ PD750108, and μ PD75P0116 have the following features:

- Built-in RC oscillator for main system clock oscillation, enabling the immediate start of processing after the release of standby mode.
- Operable on low voltage: V_{DD} = 1.8 to 5.5 V
- Switchable instruction execution times (useful for power saving)
 - 4, 8, 16, 64 µs (at 1 MHz)
 - 2, 4, 8, 32 µs (at 2 MHz)
 - 122 µs (at 32.768 kHz)
- Enhanced timers: 4 channels
- Easy replacement (The functions and instructions of the μPD750008 are taken over.)

The μ PD75P0116, having the electrically programmable one-time PROM, is pin-compatible with the μ PD750104, μ PD750106, and μ PD750108. It is suitable for small-scale production or prototype production in system development.

Applications

- Camera
- Meter
- Automobile
- Pager
- **Remark** This manual will explain only the μ PD750108 when the μ PD750108, μ PD750104, μ PD750106, and μ PD75P0116 are functionally the same. Users of the μ PD750104, μ PD750106, or μ PD75P0116 should read μ PD750108 as referring to μ PD750104, μ PD750106, or μ PD75P0116.

1.1 FUNCTION OVERVIEW

Item		Function						
Instruction execution time		 4, 8, 16, 64 μs (when the main system clock operates at 1 MHz) 2, 4, 8, 32 μs (when the main system clock operates at 2 MHz) 122 μs (when the subsystem clock operates at 32.768 kHz) 						
Internal memory	ROM	4096	x 8 bi	ts (μPD750104)				
		6144	6144 x 8 bits (μPD750106)					
		8192	x 8 bi	ts (μPD750108)				
		1638	4 x 8 t	oits (μPD75P0116)				
	RAM	512 >	k 4 bits	3				
General register				erating in 4 bits: 8 x 4 banks erating in 8 bits: 4 x 4 banks				
I/O port		34	8	CMOS input pins	Can incorporate 25 pull-up resistors			
			18	CMOS I/O pins Four pins can directly drive the LED.	that are specified with the software.			
			8	N-ch open-drain I/O pins Eight pins can directly drive the LED.	Can withstand 13 V. Can incorporate pull-up resistors that are specified with the mask option. ^{Note}			
Timer		4	 8-bit timer/event counter: 1 channel 8-bit timer counter: 1 channel (clock timer output function is provided) Basic interval timer/watchdog timer: 1 channel Clock timer: 1 channel 					
Serial interface		 Three-wire serial I/O mode (switchable between the start LSB and the start MSB) Two-wire serial I/O mode SBI mode 						
Bit sequential but	ffer	16 bits						
Clock output		 Φ, 125, 62.5, 15.6 kHz (when the main system clock operates at 1 MHz) Φ, 250, 125, 31.3 kHz (when the main system clock operates at 2 MHz) 						
Vectored interrup	ot	External: 3, Internal: 4						
Test input		External: 1, Internal: 1						
System clock oscillator		 RC oscillator for the main system clock (with external resistor and capacitor) Crystal oscillator for the subsystem clock 						
Standby function		STOP/HALT mode						
Operating ambient temperature		$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$						
Supply voltage		V _{DD} :	= 1.8 to	o 5.5 V				
Package				tic shrink DIP (600 mil) tic QFP (10 x 10 mm)				

Note Pull-up resistors, specified with the mask option, are not connected to the μ PD75P0116.

1.2 ORDERING INFORMATION

Part number	Package	On-chip ROM
μPD750104CU-xxx	42-pin plastic shrink DIP (600 mil)	Masked ROM
μPD750104GB-xxx-3BS-MTX	44-pin plastic QFP (10 x 10 mm)	Masked ROM
μPD750106CU-xxx	42-pin plastic shrink DIP (600 mil)	Masked ROM
μPD750106GB-xxx-3BS-MTX	44-pin plastic QFP (10 x 10 mm)	Masked ROM
μPD750108CU-xxx	42-pin plastic shrink DIP (600 mil)	Masked ROM
μPD750108GB-xxx-3BS-MTX	44-pin plastic QFP (10 x 10 mm)	Masked ROM
μPD75P0116CU	42-pin plastic shrink DIP (600 mil)	One-time PROM
μPD75P0116GB-3BS-MTX	44-pin plastic QFP (10 x 10 mm)	One-time PROM

Remark xxx is a ROM code number.

1.3 DIFFERENCES AMONG μ PD750108 SUBSERIES PRODUCTS

Item		μPD750104	μPD750106	μPD750108	μPD75P0116	
Program counter		12 bits	13 bits		14 bits	
ROM (byte)		Masked ROM 4096	Masked ROM 6144	Masked ROM 8192	One-time PROM 16384	
RAM (x 4 b	its)	512				
Mask option Pull-up resistors at ports 4 and 5 Wait time applied when STOP mode is released by an interrupt		Incorporated (Whether to inc be specified.)	corporate pull-up	resistors can	None (Cannot be incorporated.)	
		Available (2 ^{9/} f _{CC} or no wait) ^{Note}			Not available (Fixed to 2 ⁹ /f _{CC} .) Not e	
	Selection to use feedback resistors for subsystem clock	Yes (Whether to use feedback resistors can be specified.)			No (Feedback resistors are used)	
Pin	6-9 (CU)	P33-P30			P33/MD3-P30/MD0	
connection	23-26 (GB)					
	20 (CU)	IC			V _{PP}	
	38 (GB)					
	38-41 (CU)	P43-P40			P43/D3-P40/D0	
	13-16 (GB)					
	34-37 (CU)	P53-P50			P53/D7-P50/D4	
	8-11 (GB)					
Others		Noise immunity layout.	and noise radiat	ion vary with the	circuit scale and mask	

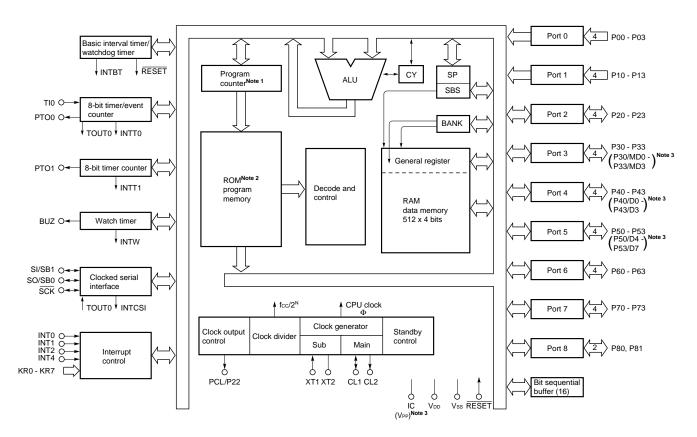
Note $2^{9/f}$ _{CC} (256 µs at 2 MHz, 512 µs at 1 MHz)

Caution The noise immunity and noise radiation of the PROM model differ from those of the mask ROM model. If you replace the PROM model with the ROM model of the course of experimental production to mass production, perform thorough evaluation by using the CS model (not ES model) of the mask ROM model.

*

*

1.4 BLOCK DIAGRAM

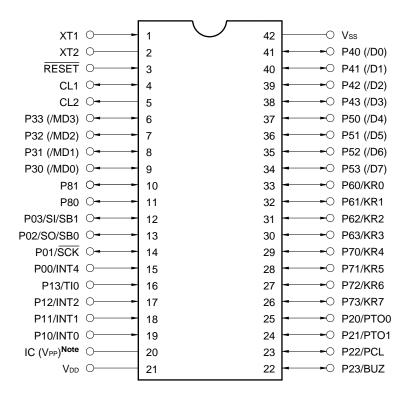


- **Notes 1.** The program counter for the μ PD750104 consists of 12 bits, 13 bits for the μ PD750106 and μ PD750108, and 14 bits for the μ PD75P0116.
 - 2. The ROM capacity depends on the product.
 - **3.** (): μPD75P0116

1.5 PIN CONFIGURATION (TOP VIEW)

(1) 42-pin plastic shrink DIP (600 mil)

μPD750104CU-xxx μPD750106CU-xxx μPD750108CU-xxx μPD75P0116CU

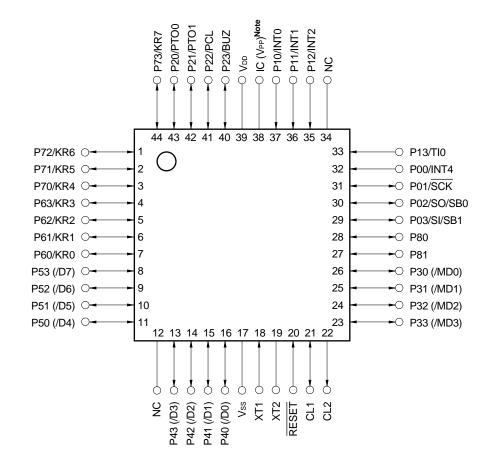


Note Connect IC (V_{PP}) to V_{DD}, keeping the wiring as short as possible.

Remark (): μ PD75P0116.

(2) 44-pin plastic QFP (10 x 10 mm)

μPD750104GB-xxx-3BS-MTX μPD750106GB-xxx-3BS-MTX μPD750108GB-xxx-3BS-MTX μPD75P0116GB-3BS-MTX



Note Connect IC (V_{PP}) to V_{DD}, keeping the wiring as short as possible.

Remark (): μ PD75P0116.

Pin name

P00-P03	: Port 0	TI0	:	Timer input 0
P10-P13	: Port 1	PTO0, 1	:	Programmable timer output 0, 1
P20-P23	: Port 2	BUZ	:	Buzzer clock
P30-P33	: Port 3	PCL	:	Programmable clock
P40-P43	: Port 4	INT0, 1, 4	:	External vectored interrupt 0, 1, 4
P50-P53	: Port 5	INT2	:	External test input 2
P60-P63	: Port 6	CL1, 2	:	RC oscillator
P70-P73	: Port 7	XT1, 2	:	Subsystem clock oscillation 1, 2
P80-P81	: Port 8	NC	:	No connection
KR0-KR7	: Key return 0-7	IC	:	Internally connected
SCK	: Serial clock	V _{DD}	:	Positive power supply
SI	: Serial input	V _{SS}	:	Ground
SO	: Serial output	V _{PP}	:	Programming power supply
SB0, 1	: Serial bus 0, 1	MD0-MD3	:	Mode selection 0-3
RESET	: Reset input	D0-D7	:	Data bus 0-7

CHAPTER 2 PIN FUNCTIONS

2.1 PIN FUNCTIONS OF THE $\mu\text{PD750108}$

Pin	Input/ output	Also used as	Function	8 bit I/O	Upon reset	I/O circuit typeNote 1
P00	Input	INT4	4-bit input port (PORT0).	х	Input	B
P01	I/O	SCK	For P01 to P03, built-in pull-up resistors			F -A
P02	I/O	SO/SB0	can be connected by software in units of			(Е)-В
P03	I/O	SI/SB1	3 bits.			M-C
P10	Input	INT0	4-bit input port (PORT1).	х	Input	B-C
P11		INT1	Built-in pull-up resistors can be connected			
P12		INT2	by software in units of 4 bits.			
P13		ТІО	For P10/INT0, the noise eliminator can be selected.			
P20	I/O	PTO0	4-bit I/O port (PORT2).	х	Input	E-B
P21		PTO1	Built-in pull-up resistors can be connected			
P22		PCL	by software in units of 4 bits.			
P23		BUZ				
P30	I/O	(MD0)Note 2	Programmable 4-bit I/O port (PORT3).	х	Input	E-B
P31		(MD1)Note 2	I/O can be specified bit by bit.			
P32		(MD2)Note 2	Built-in pull-up resistors can be connected			
P33		(MD3)Note 2	by software in units of 4 bits.			

Table 2-1. Digital I/O Port Pins (1/2)

Notes 1. I/O circuits enclosed in circles have a Schmitt-triggered input.

2. (): μPD75P0116

Pin	Input output	Also used as	Function	8 bit I/O	Upon reset	I/O circuit type Note 1
P40Note 2	I/O	(D0)Note 3	N-ch open-drain 4-bit I/O port (PORT4). Withstand voltage is 13 V in open-drain	0	High level (when a pull-up resistor	M-D (M-E)Note
P41Note 2		(D1)Note 3	mode. A pull-up resistor can be provided bit		is provided) or high impedance	
P42Note 2		(D2)Note 3	by bit (mask option) Note 4 . Data input/output pins for writing/			
P43Note 2		(D3)Note 3	verifying (lower 4 bits) of program memory (PROM).			
P50Note 2	I/O	(D4)Note 3	N-ch open-drain 4-bit I/O port (PORT5). Withstand voltage is 13 V in open-drain	0	High level (when a pull-up resistor	M-D (M-E)Note
P51Note 2		(D5)Note 3	mode. A pull-up resistor can be provided bit		is provided) or high impedance	
P52Note 2 (D6)N	(D6)Note 3	by bit (mask option) ^{Note 4} . Data input/output pins for writing/				
P53Note 2		(D7)Note 3	verifying (higher 4 bits) of program memory (PROM).			
P60	I/O	KR0	Programmable 4-bit I/O port (PORT6).	0	Input	F -A
P61		KR1	I/O can be specified bit by bit.			
P62		KR2	Built-in pull-up resistors can be			
P63		KR3	connected by software in units of 4 bits.			
P70	I/O	KR4	4-bit I/O port (PORT7).		Input	F-A
P71		KR5	Built-in pull-up resistors can be			
P72		KR6	connected by software in units of			
P73		KR7	4 bits.			
P80	I/O		2-bit input port (PORT8).	x	Input	E-B
P81		-	Built-in pull-up resistors can be connected by software in units of 2 bits.			

Table 2-1.	Digital I	/O Port	Pins	(2/2)
------------	-----------	---------	------	-------

Notes 1. I/O circuits enclosed in circles have a Schmitt-triggered input.

- 2. When pull-up resistors that can be specified with the mask option are not incorporated (when pins are used as N-ch open-drain input ports), the input leak low current increases when an input instruction or bit operation instruction is executed.
- **3.** (): μPD75P0116
- 4. Pull-up resistors, specified with the mask option, are not connected to the μ PD75P0116.

Table 2-2.	Non-Port Pin F	Functions (1/2)
------------	----------------	-----------------

Pin	Input/ output	Also used as	Function		Upon reset	I/O circuit type Note 1
TI0	Input	P13	Inputs external event pulse to the timer/event counter		Input	B -C
PTO0	Output	P20	Timer/event counter output		Input	E-B
PTO1	-	P21 Timer counter output P22 Clock output			-	
PCL						
BUZ		P23	Arbitrary frequency output			
			(for buzzer or system clock trimming)			
SCK	I/O	O P01 Serial clock I/O		Input	F -A	
SO/SB0		P02	Serial data output or serial data bus I/O			(Е)-В
SI/SB1	-	P03 Serial data input or serial data bus I/O			1	M -C
INT4 Input		P00	Edge detection vectored interrupt input			B
			(Either a rising or falling edge is detected	er a rising or falling edge is detected.)		
INT0	Input	P10	Edge detection vectored interrupt input (The edge to be detected is selectable.) For INT0/P10, the noise eliminator can be selected.	Asynchronous with noise eliminator selectable	Input	B-C
INT1		P11		Asynchronous		
INT2		P12	Rising edge detection testable input	Asynchronous		
KR0-KR3	Input	P60-P63	Falling edge detection testable input		Input	F -A
KR4-KR7	Input	P70-P73	Falling edge detection testable input		Input	F -A
CL1 CL2	I/O Output		Pin for connecting a resistor (R) or capacitor (C) for main system clock oscillation.		_	_
			An external clock cannot be input.			
XT1	Input		Connection pin to a crystal for subsystem clock generation. When an external clock is used, it is input to XT1, and its inverted signal is input to XT2. XT1 can be used as the 1-bit input (test) pin.		_	_
XT2	_					
RESET	Input	_	System reset input (Low-level active)		_	B
CNote 2	2 — — Internally connected.			-	_	
			Connect to V _{DD} , keeping the wiring as short as possible.			
V _{DD}	—	—	Positive power supply		—	
V _{SS}		_	GND potential		_	
V _{PP}			Provided only in the μ PD75P0116. Program voltage application for program memory (PROM) write/verify operation. +12.5 V is applied for PROM write/verify operation. Connect to V _{DD} , keeping the wiring as short as possible.			_

Notes 1. The circuits enclosed in circles have a Schmitt-triggered input.

2. Used as the V_{PP} pin for the $\mu\text{PD75P0116}.$

Pin	Input/ output	Also used as	Function	Upon reset	I/O circuit type Note
MD0- MD3	Input	P30-P33	Provided only in the μPD75P0116. Mode selection for program memory (PROM) write/verify operation.	Input	E-B
D0-D3	I/O	P40-P43	Provided only in the μPD75P0116. Data bus pins for program memory (PROM) write/verify operation.		M-E
D4-D7		P50-P53			
NC	_	_	No connection	_	_

Table 2-2. Non-Port Pin Functions (2/2)

Note The circuits enclosed in circles have a Schmitt-triggered input.

2.2 PIN FUNCTIONS

2.2.1 P00-P03 (PORT0): Input Pins Also Used for INT4, SCK, SO/SB0, and SI/SB1 P10-P13 (PORT1): Input Pins Also Used for INT0-INT2, and TI0

These are 4-bit input ports, which also have the following functions:

 Port 0: Vectored interrupt input (INT4) Serial interface I/O (SCK, SO/SB0, SI/SB1)
 Port 1: Vectored interrupt input (INT0, INT1) Edge detection test input (INT2)

External event pulse input (TI0) for timer/event counter

When the serial interface function is used, the operation mode causes the dual-function pin of P0 to become an output pin.

Schmitt-triggered inputs are used for the pins of port 0 and port 1 to prevent malfunction due to noise. In addition, for P10, the noise eliminator can be selected. (See (3) of Section 6.3 for details.)

Port 0 can be connected with built-in pull-up resistors in units of 3 bits (P01 to P03) by software. Port 1 can be connected with built-in pull-up resistors in units of 4 bits (P10 to P13) by software. This is done by manipulating pull-up resistor specification register group A (POGA).

A RESET signal places these pins in input mode.

2.2.2 P20-P23 (PORT2): I/O Pins Also Used for PTO0, PTO1, PCL, and BUZ

P30-P33 (PORT3): I/O Pins Also Used for MD0-MD3Note

P40-P43 (PORT4): I/O Pins Also Used for D0-D3^{Note}

P50-P53 (PORT5): N-ch Open-Drain Intermediate Withstand Voltage (13 V), I/O Pins Also Used for D4-D7^{Note}

P60-P63 (PORT6): I/O Pins Also Used for KR0-KR3

P70-P73 (PORT7): I/O Pins Also Used for KR4-KR7

These are 4-bit I/O ports with output latches, which also have the following functions:

- (1) Port 2 : Timer/event counter output (PTO0) Timer counter output (PTO1) Clock output (PCL) Arbitrary frequency output (BUZ)
- (2) Port 3 : Mode selection for program memory (PROM) write/verify operation (MD0-MD3)^{Note}
- (3) Ports 4 and 5: Data bus for program memory (PROM) write/verify operation (D0-D3, D4-D7)Note
- (4) Ports 6 and 7: Key interrupt input (KR0-KR3, KR4-KR7)

Note Provided only in the μ PD75P0116.

Ports 4 and 5 are N-ch open-drain intermediate withstand voltage (13 V) ports.

The port mode register specifies I/O mode selection for each port. Ports 2, 4, 5, and 7 can be specified in units of 4 bits. Ports 3 and 6 can be specified bit by bit.

Ports 2, 3, 6, and 7 can be connected with built-in pull-up resistors, in units of 4 bits, by software. This can be done by manipulating pull-up resistor specification register group A (POGA). For ports 4 and 5, the use of built-in pull-up resistors can be specified, bit by bit, with the mask option. However, pull-up resistors, specified with the mask option, are not connected to the μ PD75P0116.

Ports 4 and 5, and ports 6 and 7 can be paired for 8-bit I/O.

A RESET signal places ports 2, 3, 6, and 7 in input mode (high-impedance), and drives ports 4 and 5 high (when a pull-up resistor, specified with the mask option, is incorporated). Or, it causes ports 4 and 5 to enter the high-impedance state.

2.2.3 P80, P81 (PORT8)

These are 2-bit I/O ports with output latches.

Built-in pull-up resistors can be connected to port 8, in units of 2 bits, by software. This can be done by manipulating pull-up resistor specification register group B (POGB).

2.2.4 TI0: Input Pin Also Used for Port 1

This is an external event pulse input pin for programmable timer/event counter 0. To use this pin, select the external event pulse input as the count pulse (CP) in the timer/event counter mode register (TM0). A Schmitt-triggered input is used for the TI0 pin. See (1) of Section 5.5.1 for details.

2.2.5 PTO0, PTO1: Output Pin Also Used for Port 2

These are the output pins of timer/event counter 0 and timer counter 1. Square-wave pulses appear on this pin. To output a signal from the timer/event counter and timer counter, clear the output latch to 0, and set bit 2 for port mode register group B to 1.

The timer start instruction clears the output of TOUT flip-flop to 0. See (3) of Section 5.5.2 for details.

2.2.6 PCL: Output Pin Also Used for Port 2

This is the programmable clock output pin. It is used to supply the clock pulse to a peripheral LSI circuit such as a slave microcontroller or A/D converter.

A RESET signal clears the clock output mode register (CLOM) to 0, disabling clock output, then the pin is placed in the normal mode to function as a normal port. See **Section 5.2.4** for details.

2.2.7 BUZ: Output Pin Also Used for Port 2

An arbitrary frequency (2.048, 4.096, or 32.768 kHz when the subsystem clock operates at 32.768 kHz output on this pin can be used for sounding the buzzer or trimming the system clock frequency. This pin is used also as the P23 pin, and can be used only when bit 7 (WM.7) of the clock mode register (WM) is set to 1.

A RESET signal clears WM.7 to 0, and places this pin in the normal operation mode as a general port. See **Section 5.4.2** for details.

2.2.8 SCK, SO/SB0, SI/SB1: I/O Pins Also Used for Port 0

These are I/O pins for serial interface. They operate according to the setting of the serial operation mode registers (CSIM). When three-wire serial I/O mode is selected, \overline{SCK} functions as CMOS I/O, SO functions as CMOS output, and SI functions as CMOS input. When two-wire serial I/O mode is selected, \overline{SCK} functions as CMOS I/O, and SB1 (SB0) functions as N-ch open-drain I/O.

A RESET signal stops serial interface operation and places these pins in the input port mode.

A Schmitt-triggered input is used for each pin. See Section 5.6 for details.

2.2.9 INT4: Input Pin Also Used for Port 0

INT4 is an external vectored interrupt input pin, which is rising edge active as well as falling edge active. When a signal applied to this pin goes from low to high or from high to low, the interrupt request flag is set.

INT4 is an asynchronous input, and can accept a signal with some high level width or low level width regardless of what the CPU clock is.

The INT4 pin can also be used to release the STOP and HALT modes. A Schmitt-triggered input is used for this pin.

2.2.10 INT0, INT1: Input Pins Also Used for Port 1

These are the edge detection vectored interrupt input pins. For INT0, the noise eliminator can be selected. The edge to be detected can be selected using the edge detection mode registers (IM0, IM1).

(1) INT0 (bits 0 and 1 of IM0)

- (a) Rising edge active
- (b) Falling edge active
- (c) Both rising and falling edges active
- (d) External interrupt signal input disabled

(2) INT1 (bit 0 of IM1)

- (a) Rising edge active
- (b) Falling edge active

INTO and INT1 are asynchronous inputs, and can accept a signal with some high level width regardless of what the CPU clock is. INTO can be provided with the noise eliminator function by software, and change the sampling clock that eliminates the noise at two levels. In this case, the width of the signal received by the CPU operation clock varies.

A RESET input clears IMO and IM1 to 0, selecting rising edge active.

The INT0 and INT1 pins can be used to release STOP and HALT modes. When the noise eliminator is selected, however, the INT0 pin cannot be used to release STOP and HALT modes.

Schmitt-triggered inputs are used for the INT0 and INT1 pins.

2.2.11 INT2: Input Pin Also Used for Port 1

This is a rising edge active, external test input pin. When INT2 is selected with the edge detection mode register (IM2), or when the signal applied to this pin goes high, the internal test flag (IRQ2) is set.

INT2 is an asynchronous input, and can accept a signal with some high level width regardless of the operating clock of the CPU.

A RESET signal clears IM2 to 0. In this case, the test flag (IRQ2) is set by a rising edge on the INT2 pin.

The INT2 pin can also be used to release the STOP and HALT modes. A Schmitt-triggered input is used for this pin.

2.2.12 KR0-KR3: Input Pins Also Used for Port 6 KR4-KR7: Input Pins Also Used for Port 7

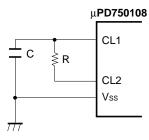
KR0 to KR7 are key interrupt input pins. An interrupt is caused when parallel falling edges are detected on them. An interrupt source can be selected from among KR0-KR7, KR2-KR7, or KR4-KR7 by means of the edge detection mode register (IM2).

A RESET signal places these pins in the port 6 and 7 input modes.

2.2.13 CL1, CL2

These pins are used for connection to a resistor (R) and capacitor (C) for main system clock generation. An external clock cannot be input.

RC oscillation

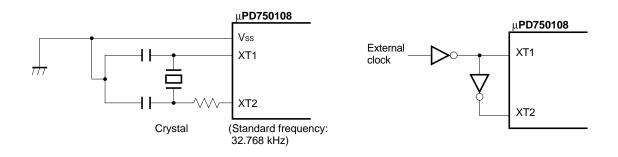


2.2.14 XT1, XT2

These pins are used for connection to a crystal for subsystem clock oscillation. An external clock can also be applied.

(a) Crystal oscillation

```
(b) External clock
```



Remark If the subsystem clock is not to be used, see (6) of Section 5.2.2.

2.2.15 **RESET**

This is the pin for active-low reset input.

The RESET input is asynchronous. When a signal with certain low level width is applied to the pin, a RESET signal is generated to cause a system reset, which has priority over any other operations.

The RESET signal is used for normal CPU initialize/start operation, and is also used to release STOP or HALT mode.

A Schmitt-triggered input is used for the RESET input pin.

2.2.16 V_{DD}

This is the positive power supply pin.

2.2.17 V_{SS}

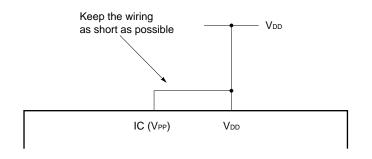
This is the ground pin.

2.2.18 IC (for the μPD750104, μPD750106, and μPD750108 only)

The internally connected (IC) pin is used to set the μ PD750108 to test mode for inspection prior to shipping. In normal operation, connect the IC pin to the V_{DD} pin, keeping the writing as short as possible.

When the wiring between the IC pin and the V_{DD} pin is too long, or noise is generated on the IC pin, a potential difference may occur between the IC pin and the V_{DD} pin. This may cause your program to malfunction.

• Connect the IC pin to the V_{DD} pin, keeping the wiring as short as possible.



2.2.19 V_{PP} (for the μ PD75P0116 only)

This is a program voltage input pin for program memory (one-time PROM) write/verify operation. For normal use, connect this pin to V_{DD} , keeping the wiring as short as possible (shown above). +12.5 V is applied for PROM write/verify operation.

2.2.20 MD0-MD3 (for the μ PD75P0116 only)

MD0 to MD3 select a mode for program memory (one-time PROM) write/verify operation.

* 2.2.21 D0-D7 (for the μPD75P0116 only)

These are the data bus pins for the program memory (one-time PROM) write/verify operation.

2.3 PIN INPUT/OUTPUT CIRCUITS

Figure 2-1 shows schematic diagrams of the I/O circuitry of the μ PD750108.

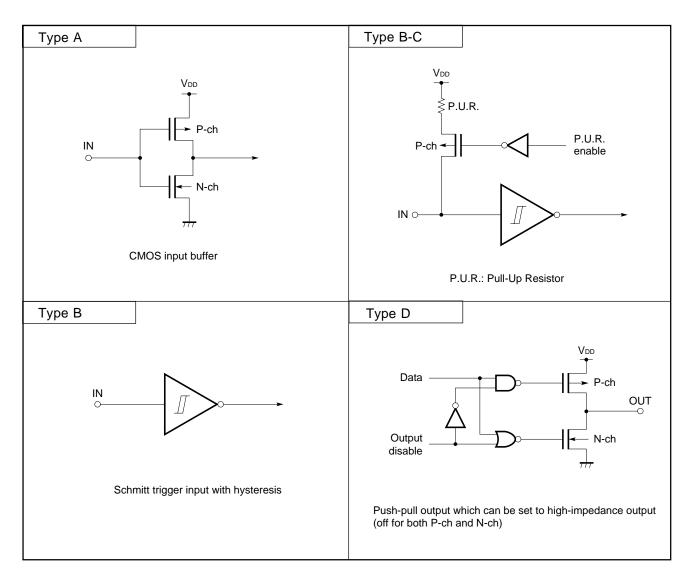
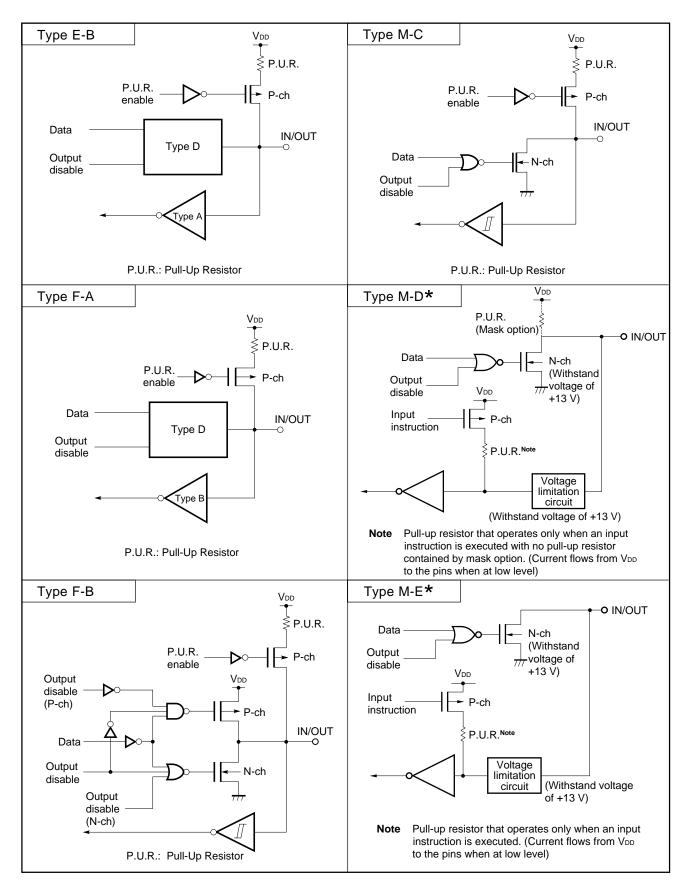


Figure 2-1. Pin Input/Output Circuits (1/2)





* 2.4 CONNECTION OF UNUSED PINS

Pin name	Recommended connection	
P00/INT4	To be connected to $V_{\mbox{\scriptsize SS}}$ or $V_{\mbox{\scriptsize DD}}$	
P01/SCK	To be connected to $V_{\mbox{\scriptsize SS}}$ or $V_{\mbox{\scriptsize DD}}$ through	
P02/SO/SB0	a resistor	
P03/SI/SB1	To be connected to V_{SS}	
P10/INT0-P12/INT2	To be connected to $V_{\mbox{\scriptsize SS}}$ or $V_{\mbox{\scriptsize DD}}$	
P13/TI0		
P20/PTO0	Input state: To be connected to V_{SS} or	
P21/PTO1	V _{DD} through a resistor	
P22/PCL	Output state: To be left open	
P23/BUZ		
P30(/MD0)-P33(/MD3)Note 1		
P40-P43	To be connected to V_{SS} . (A pull-up resistor,	
P50-P53	specified with the mask option, must not be connected.)	
P60/KR0-P63/KR3	Input state: To be connected to V _{SS} or	
P70/KR4-P73/KR7	V _{DD} through a resistor	
P80-P81	Output state: To be left open	
X⊤1Note 2	To be connected to $V_{\mbox{\scriptsize SS}}$ or $V_{\mbox{\scriptsize DD}}$	
XT2Note 2	To be left open	
IC (V _{PP})Note 1	To be always connected directly to V_{DD}	

Table 2-3. Connection of Unused Pins

Notes 1. (): µPD75P0116

2. When the subsystem clock is not to be used, select SOS.0 = 1 (the built-in feedback resistor will not be used).

[MEMO]

CHAPTER 3 FEATURES OF THE ARCHITECTURE AND MEMORY MAP

The 75XL series architecture of the μ PD750108 has the following features:

- Internal RAM of up to 4K words x 4 bits (12-bit address)
- · Peripheral hardware expansibility

To provide these features, the following are used:

- (1) Data memory bank structure
- (2) General register bank structure
- (3) Memory-mapped I/O

This chapter explains these topics.

3.1 DATA MEMORY BANK STRUCTURE AND ADDRESSING MODES

3.1.1 Data Memory Bank Structure

In the μ PD750108, addresses 000H to 1FFH in data memory space are assigned to static RAM (512 words x 4 bits), and addresses F80H to FFFH are assigned to peripheral hardware (such as I/O ports and timers). To address a 12-bit location in this data memory space (4K x 4 bits), the μ PD750108 uses such a memory bank structure that the low-order eight bits are specified with an instruction directly or indirectly, and the high-order four bits are used to specify a memory bank.

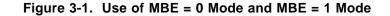
To specify a memory bank (MB), two hardware items are incorporated:

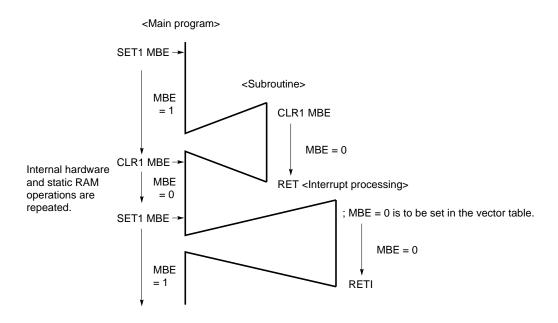
- Memory bank enable flag (MBE)
- Memory bank select register (MBS)

The MBS is a register used to select a memory bank, and the register can be set to 0, 1, or 15. The MBE is a flag used to determine whether the memory bank selected using the MBS is valid. As shown in Figure 3-1, when the MBE is set to 0, a certain memory bank is always selected regardless of the setting of the MBS. When the MBE is set to 1, memory bank selection depends on the setting of the MBS, thus enabling data memory space expansion.

In addressing data memory space, the MBE is usually set to 1 (MBE = 1), and data memory in the memory bank specified in the MBS is operated. However, the MBE = 0 mode or MBE = 1 mode can be selected for each step of processing for more efficient programming.

	Applicable program processing	Effect
MBE = 0 mode	Interrupt processing	MBS save/restoration becomes unnecessary.
	 Processing that repeats internal hardware and static RAM operations 	MBS modification becomes unnecessary.
	Subroutine processing	MBS save/restoration becomes
MBE = 1 mode	Usual program processing	





The contents of the MBE are automatically saved or restored at the time of subroutine processing, so that the MBE can be freely modified during subroutine processing. In interrupt processing, the MBE is automatically saved or restored, and when interrupt processing is started, the contents of the MBE can be specified for the interrupt processing by setting the interrupt vector table. This speeds up interrupt processing.

The setting of the MBS can be modified for subroutine processing or interrupt processing by saving or restoring the MBS with the PUSH or POP instruction.

The MBE is set using the SET1 or CLR1 instruction. The MBS is set using the SEL instruction.

Examples 1. The MBE is cleared, and a fixed memory bank is used. CLR1 MBE : MBE <- 0

2. Memory bank 1 is selected.

SET1	MBE	; MBE <– 1
SEL	MB1	; MBS <– 1

3.1.2 Data Memory Addressing Modes

With the architecture of the μ PD750108, seven addressing modes summarized in Figure 3-2 and Table 3-1 are available to address data memory space efficiently for each bit length of data to be processed. These addressing modes enable more efficient programming.

(1) 1-bit direct addressing (mem.bit)

In this addressing mode, the operand of an instruction can directly specify any bit in the entire data memory space.

A particular memory bank (MB) is always used in this addressing mode. In the MBE = 0 mode, when an address from 00H to 7FH is specified in the operand, memory bank 0 (MB = 0) is always used. When an address from 80H to FFH is specified, memory bank 15 (MB = 15) is always used. Accordingly, both the data area ranging from 000H to 07FH and the peripheral hardware area ranging from F80H to FFFH can be addressed in the MBE = 0 mode.

In the MBE = 1 mode, MB = MBS, and specifiable data memory space can be expanded.

This addressing mode can be applied to four instructions: bit set and reset instructions (SET1 and CLR1), and bit test instructions (SKT and SKF).

Example FLAG1 is set, FLAG2 is reset, and whether FLAG3 is zero is tested.

FLAG1 FLAG2	EQU EQU	03FH.1 087H.2	,	address 3FH address 87H
FLAG3	EQU	0A7H.0	; Bit 0 at	address A7H
	SET1	MBE	; MBE	<– 1
	SEL	MB0	; MBS	<- 0
	SET1	FLAG1	; FLAG1	<- 1
	CLR1	FLAG2	; FLAG2	<- 0
	SKF	FLAG3	; FLAG3	= 0?

	Addressing mode	me men		-	HL nem.bit	@DE @DL	Stack address- ing	fmem.bit	pmem.@L
	Memory bank enable flag	MBE =0	MBE =1	MBE =0	MBE =1	_	Ι	_	—
000H 01FH 020H	Area for general register								
07FH 0FFH	Data area Static RAM (memory bank 0) ↓		MBS =0		MBS =0		SBS =0		
100H	Data area Static RAM (memory bank 1)		MBS =1		MBS =1		SBS =1		
1FFH	Not provided								
F80H FC0H	Peripheral hardware area (memory bank 15)		MBS =15		MBS =15			~~~~~	~~~~~
FFFH									

Figure 3-2. Data Memory Organization and Addressing Range of Each Addressing Mode

Remark -: Don't care

Addressing mode	Representation format	Specified address	
1-bit direct addressing	mem.bit	 Bit specified by bit at the address specified by MB and mem. When MBE = 0 and mem = 00H-7FH, MB = 0 mem = 80H-FFH, MB = 15 When MBE = 1, MB = MBS 	
4-bit direct addressing	mem	Address specified by MB and mem. • When MBE = 0 and mem = 00H-7FH, MB = 0 mem = 80H-FFH, MB = 15 • When MBE = 1, MB = MBS	
8-bit direct addressing		 Address specified by MB and mem (mem: even address). When MBE = 0 and mem = 00H-7FH, MB = 0 mem = 80H-FFH, MB = 15 When MBE = 1, MB = MBS 	
4-bit register indirect addressing	@HL @HL+ @HL–	Address specified by MB and HL. In this case, MB = MBE·MBS HL+ automatically increments the L register after addressing. HL- automatically decrements the L register after addressing.	
	@DE	Address specified by DE in memory bank 0	
	@DL	Address specified by DL in memory bank 0	
8-bit register indirect addressing	@HL	Address specified by MB and HL. (Contents of the L register is an even address.) In this case, MB = MBE·MBS	
Bit manipulation addressing	fmem.bit	Bit specified by bit at the address specified by fmem. In this case, fmem = [FB0H-FBFH (interrupt-related hardware) FF0H-FFFH (I/O ports)	
	pmem.@L	Bit specified by the low-order two bits of the L register at the address specified by the high-order 10 bits of pmem and the high-order two bits of the L register. In this case, pmem = FC0H-FFFH	
	@H+mem.bit	Bit specified by bit at the address specified by MB, H, and the low- order four bits of mem. In this case, MB = MBE·MBS	
Stack addressing	_	Address specified by the SP in memory bank 0 or 1 selected by the SBS	

Table 3-1. Addressing Modes

(2) 4-bit direct addressing (mem)

In this addressing mode, the operand of an instruction directly specifies any area in the data memory space in units of four bits.

As with the 1-bit direct addressing mode, in the MBE = 0 mode, a fixed space consisting of the static RAM area ranging from 000H to 07FH and the peripheral hardware area ranging from F80H to FFFH can be addressed. In the MBE = 1 mode, MB = MBS, and specifiable data memory space can be expanded to the entire space.

This addressing mode can be applied to the MOV, XCH, INCS, IN, and OUT instructions.

Caution Less efficient program processing results if data associated with an I/O port is stored in the static RAM area of bank 1 as in Example 1. The modification of the MBS, as contained in Example 2, becomes unnecessary in the programming if data associated with an I/O port is stored at addresses 00H to 7FH of bank 0.

Examples 1. The data contained in BUFF is output on port 5.

BUFF	EQU	11AH	; BUFF located at address 11AH
	SET1	MBE	; MBE <– 1
	SEL	MB1	; MBS <– 1
	MOV	A,BUFF	; A <– (BUFF)
	SEL	MB15	; MBS <– 15
	OUT	PORT5,A	; PORT5 <– A

2. Data on port 4 is entered, and is saved in DATA1.

DATA1	EQU	5FH	; DATA1 located at address 5FH
	CLR1	MBE	; MBE <- 0
	IN	A,PORT4	; A <– PORT4
	MOV	DATA1,A	; (DATA1) <– A

(3) 8-bit direct addressing (mem)

In this addressing mode, the operand of an instruction directly specifies any area in the data memory space in units of eight bits.

The operand can specify an even address. The 4-bit data at the address specified in the operand and the 4-bit data at the address incremented by 1 are processed as a pair on an 8-bit basis with the 8-bit accumulator (XA register pair).

A memory bank is specified in the same way as the 4-bit direct addressing.

This addressing mode can be applied to the MOV, XCH, IN, and OUT instructions.

Example 1. Eight-bit data from port 4 and port 5 is transferred to addresses 20H and 21H.

DATA	EQU	020H	
	CLR1	MBE	; MBE <- 0
	IN	XA,PORT4	; X <- PORT5 , A <- PORT4
	MOV	DATA,XA	; (21H) <- X, (20H) <- A

Example 2. Eight-bit data is latched into the serial interface shift register (SIO), and the transfer data is set at the same time.

SEL	MB15	; MBS <- 15
ХСН	XA,SIO	; XA <—> (SIO)

(4) 4-bit register indirect addressing (@rpa)

In this addressing mode, the pointer (general register pair) specified in the operand of an instruction indirectly specifies a data memory space in units of four bits.

There are three types of data pointers. One is the HL register pair, which can specify any area in the data memory space when $MB = MBE \cdot MBS$ is specified. The other two are the DE register pair and DL register pair, with which memory bank 0 is always used regardless of how the MBE and MBS are specified. More efficient programming is possible by selecting a data pointer according to a data memory bank to be used. When the HL register pair is specified, the L register can be incremented or decremented by one in the automatic increment or automatic decrement mode each time an instruction is executed, thus simplifying the program step.

Example The data at 50H to 57H is transferred to 110H to 117H.

DATA1	EQU	57H	
DATA2	EQU	117H	
	SET1	MBE	; MBE <– 1
	SEL	MB1	; MBS <– 1
	MOV	D,#DATA1 SHR4	; D <- 5
	MOV	HL,#DATA2 AND 0FFH	; HL <– 17H
LOOP:	MOV	A,@DL	; A <- (DL)
	XCH	A,@HL–	; A <—> (HL), L <- L - 1
	BR	LOOP	

The addressing mode using the HL register pair as the data pointer finds a wide range of operations such as data transfer, operations, comparison, and I/O. The addressing mode using the DE register pair or DL register pair is applied to the MOV and XCH instructions.

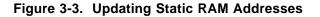
This addressing mode, combined with an increment/decrement instruction for a general register or register pair, enables data memory space addresses to be freely updated as shown in Figure 3-3.

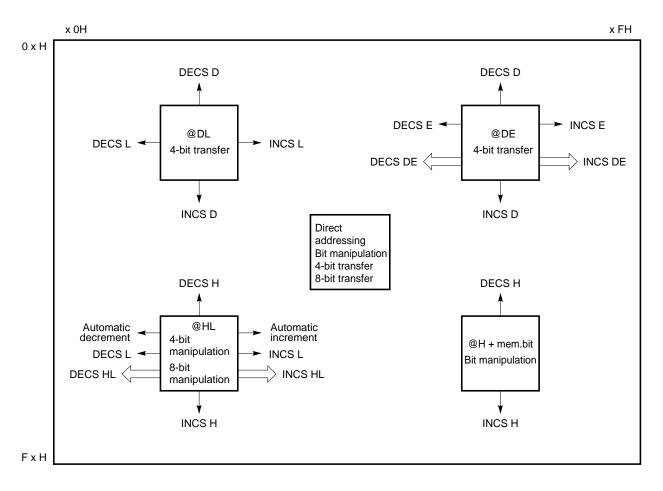
Example 1. The data at 50H to 57H is compared with the data at 110H to 117H.

DATA1	EQU	57H	
DATA2	EQU	117H	
	SET1	MBE	
	SEL	MB1	
	MOV	D,#DATA1	SHR4
	MOV	HL,#DATA	2 AND 0FFH
LOOP:	MOV	A,@DL	
	SKE	A,@HL	; A = (HL)?
	BR	NO	; NO
	DECS	L	; YES, L <- L - 1
	BR	LOOP	

Example 2. The data memory of 00H to FFH is cleared to 0.

	CLR1	RBE	
	CLR1	MBE	
	MOV	XA,#00H	
	MOV	HL,#04H	
LOOP:	MOV	@HL,A	; (HL) <- A
	INCS	HL	; HL <– HL + 1
	BR	LOOP	





(5) 8-bit register indirect addressing (@HL)

DATA

In this addressing mode, the data pointer (HL register pair) indirectly specifies any area in the data memory space in units of eight bits.

The 4-bit data at the address determined with bit 0 of the data pointer (bit 0 of the L register) set to 0 and the 4-bit data at the address incremented by 1 are processed as a pair on an 8-bit basis with the 8-bit accumulator (XA register pair).

A memory bank is specified in the same way as the 4-bit register indirect addressing with the HL register specified. In this case, MB = MBE·MBS.

This addressing mode can be applied to the MOV, XCH, and SKE instructions.

Examples 1. A comparison is made to determine whether the value of the count register (T0) of timer/ event counter 0 is equal to the data at addresses 30H and 31H.

EQU	30H	
CLR1	MBE	
MOV	HL,#DATA	
MOV	XA,T0	; XA <- Count register 0
SKE	XA,@HL	; XA = (HL)?

2. The data memory of 00H to FFH is cleared to 0.

	CLR1	RBE	
	CLR1	MBE	
	MOV	XA,#00H	
	MOV	HL,#04H	
LOOP:	MOV	@HL,XA	; (HL) <- XA
	INCS	HL	
	INCS	HL	
	BR	LOOP	

(6) Bit manipulation addressing

This addressing mode is used to perform bit manipulations (such as Boolean operations and bit transfer) for each bit in the data memory space.

The 1-bit direct addressing mode can be applied only to the set, reset, and test instructions. On the other hand, the bit manipulation addressing enables a wide variety of bit manipulations such as Boolean operations using the AND1, OR1, and XOR1 instructions, bit transfers using the MOV1 instruction, and test and reset operations using the SKTCLR instruction.

There are three types of bit manipulation addressing. The user can choose from these options according to the data memory address used.

(a) Specific address bit direct addressing (fmem.bit)

In this addressing mode, peripheral equipment that frequently performs bit manipulations involving, for example, I/O ports and interrupt flags, can be processed at all times regardless of memory bank setting. Accordingly, the data memory addresses that allow this addressing mode to be used are FF0H to FFFH where I/O ports are mapped, and FB0H to FBFH where interrupt-related hardware is mapped. Hardware mapped to these data memory areas can freely perform bit manipulations in the direct addressing mode at any time regardless of MBS and MBE setting.

Examples 1. Value input to P02 is inverted, and the result is output on P33.

MOV1	CY, PORT0.2
NOT1	CY
MOV1	PORT3.3, CY

2. The timer 0 interrupt request flag (IRQT0) is tested. The request flag, if set, is cleared, and P63 is reset.

SKTCLR	IRQT0	; IRQT0 = 1?
BR	NO	; NO
CLR1	PORT6.3	; YES

3. If both P30 and P41 are set to 1, P53 is reset.

P30

P41 -

MOV1	CY, PORT3.0	; CY <- P30
AND1	CY, PORT4.1	; CY ^ P41
NOT1	CY	; CY <- CY
MOV1	PORT5.3, CY	; P53 <- CY

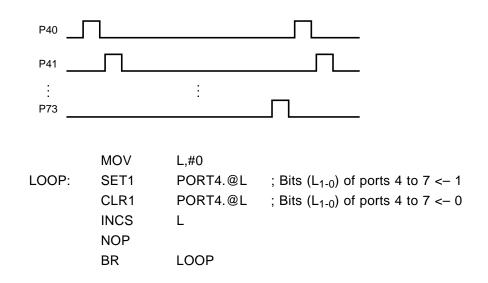
– P53

(b) Specific address bit register indirect addressing (pmem.@L)

In this addressing mode, the bits of peripheral hardware I/O ports are indirectly specified using a register to allow continuous manipulations. This addressing mode can be applied to data memory addresses FC0H to FFFH.

In this addressing mode, the high-order 10 bits of a 12-bit data memory address is directly specified in the operand, and the low-order two bits and bit address are indirectly specified using the L register. Thus the use of the L register enables 16 bits (four ports) to be continuously manipulated. This addressing mode again enables bit manipulation regardless of MBE and MBS setting.

Example Pulses are output on the bits in the order from port 4 to port 7.



(c) Specific 1-bit direct addressing (@H+mem.bit)

This addressing mode enables any bit in the data memory space to be manipulated.

In this addressing mode, the high-order four bits of the data memory address in the memory bank specified by MB = MBE-MBS are indirectly specified using the H register, and the low-order four bits and bit address are directly specified in the operand. This addressing mode enables a wide variety of manipulations for each bit in the entire data memory space.

Example Bit 2 at address 32H (FLAG3) is reset if both bit 3 at address 30H (FLAG1) and bit 0 at address 31H (FLAG2) are set to 0 or 1.



FLAG1	EQU	30H.3	
FLAG2	EQU	31H.0	
FLAG3	EQU	32H.2	
	SEL	MB0	
	MOV	H,#FLAG1 SHR 6	
	MOV1	CY, @H+FLAG1	; CY <– FLAG1
	XOR1	CY, @H+FLAG2	; CY <– CY [∀] FLAG2
	MOV1	@H+FLAG3, CY	; FLAG3 < CY

(7) Stack addressing

This addressing mode is used for save/restoration operation in interrupt processing or subroutine processing.

In this addressing mode, the address indicated by the stack pointer (8 bits) of data memory bank 0 is specified.

This addressing mode can be used for register save/restoration operation using the PUSH or POP instruction as well as save/restoration operation in interrupt and subroutine processing.

Examples 1. A register is saved and restored in subroutine processing.

SUB:	PUSH		XA	
	PUSH		HL	
	PUSH		BS	; Save MBS and RBS
		÷		
	POP		BS	
	POP		HL	
	POP		XA	
	RET			

2. The contents of the HL register pair are transferred to the DE register pair.

PUSH	HL	
POP	DE	; DE <– HL

3. A branch is made to the address indicated by the [XABC] register.

PUSH	BC	
PUSH	XA	
RET		; Branch to address XABC

3.2 GENERAL REGISTER BANK CONFIGURATION

The μPD750108 contains four register banks, each consisting of eight general registers: X, A, B, C, D, E, H, and L. These registers are mapped to addresses 00H to 1FH in memory bank 0 of the data memory (see **Figure 3-5**). To specify a general register bank, a register bank enable flag (RBE) and a register bank select register (RBS) are contained. The RBS is a register used to select a register bank, and the RBE is a flag used to determine whether a register bank selected using the RBS is to be enabled. The register bank (RB) enabled at instruction execution is determined as

 $RB = RBE \cdot RBS$

RBE			Pogistor bank		
	3	2	1	0	Register bank
0	0	0	х	x	Bank 0 is always selected.
1	0	0	0	0	Bank 0 is selected.
			0	1	Bank 1 is selected.
			1	0	Bank 2 is selected.
			1	1	Bank 3 is selected.
		1			
Always 0					

Table 3-2. Register Bank to Be Selected with the RBE and RBS

The contents of the RBE are automatically saved or restored at the beginning or end of subroutine processing, so that the RBE can be freely modified during subroutine processing. In interrupt processing, the RBE is automatically saved or restored, and when interrupt processing is started, the contents of the RBE can be specified for the interrupt processing by setting the interrupt vector table. Therefore, as indicated in Table 3-3, by selecting a register bank depending on whether the processing is normal or interrupt, the general register need not be saved and restored for the level-one interrupt processing, and only the RBS needs to be saved and restored for the level-two interrupt processing, thus speeding up interrupt processing.

Table 3-3. Recommended Use of Register Banks with	Normal Routines and Interrupt Routines
---	--

Normal processing	Use register banks 2 and 3 with $RBE = 1$.
Level-one interrupt processing	Use register bank 0 with $RBE = 0$.
Level-two interrupt processing	Use register bank 1 with RBE = 1. (In this case, the RBS needs to be saved and restored.)
Multiple (triple or more) interrupt processing	Save and restore the registers with PUSH or POP.

Remark x: Don't care

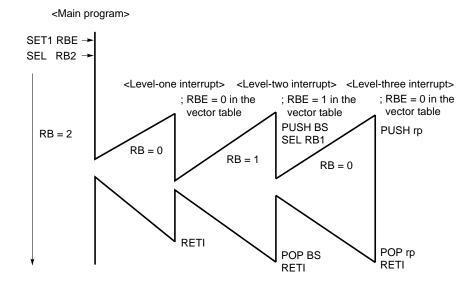


Figure 3-4. Example of Register Bank Selection

The setting of the RBS can be modified for subroutine processing or interrupt processing by saving or restoring the RBS with the PUSH or POP instruction.

The RBE is set using the SET1 or CLR1 instruction. The RBS is set using the SEL instruction.

Example

SET1	RBE	; RBE <-	1
CLR1	RBE	; RBE <-	0
SEL	RB0	; RBS <-	0
SEL	RB3	; RBS <-	3

The general register area of the µPD750108 can be used not only on a 4-bit basis, but also on an 8-bit basis with register pairs. This enables users to perform transfers, arithmetic/logical operations, comparisons, and increments and decrements at a speed comparable to that of an 8-bit microcontroller, and thereby enables to program using mainly general registers.

(1) When used as a 4-bit register

When the general register area is used on a 4-bit basis, eight general registers, the X, A, B, C, D, E, H, and L registers, are available in the register bank specified with RB = RBE·RBS as shown in Figure 3-5. The A register functions as a 4-bit accumulator which performs transfers, arithmetic/logical operations, and comparisons. The other general registers perform transfers, comparisons, and increments/decrements with the accumulator.

(2) When used as an 8-bit register

When the general register area is used on an 8-bit basis, the register pairs in the register bank specified by RBE-RBS can be specified as XA, BC, DE, and HL as shown in Figure 3-6, and the register pairs in the register bank that has the inverted value of bit 0 of the register bank (RB) can be specified as XA', BC', DE', and HL', thus providing up to eight 8-bit registers. The XA register pair functions as an 8-bit accumulator which performs transfers, arithmetic/logical operations, comparisons, and increments/ decrements of 8-bit data. The other register pairs perform transfers, arithmetic/logical operations, comparisons, and increments/decrements with the accumulator. The HL register pair functions mainly as a data pointer, and the DE and DL register pairs function as an auxiliary data pointer.

Examples 1.	INCS	HL	; HL <– HL + 1, skip at HL = 00H
	ADDS	XA,BC	; XA <– XA + BC, skip at carry
	SUBC	DE',XA	; DE' <- DE' - XA - CY
	MOV	XA,XA'	; XA <- XA'
	MOVT	XA,@PCDE	; XA <- (PC ₁₂₋₈ + DE) ROM, reference table
	SKE	XA, BC	; Skip if XA = BC

2. The value of the count register (T0) for timer/event counter 0 is tested until it becomes greater than the value of the BC' register pair.

	CLR1	MBE	,
NO:	MOV	XA,T0	; Read count register
	SUBS	XA,BC'	; XA ≥ BC'?
	BR	YES	; YES
	BR	NO	; NO

[
x	01H	А	00H	Î
н	03H	L	02H	Register bank 0
D	05H	E	04H	(RBE·RBS = 0)
В	07H	С	06H	↓ ↓
х	09H	А	08H	Î
н	0BH	L	0AH	Register bank 1
D	0DH	E	0CH	(RBE·RBS = 1)
В	0FH	С	0EH	¥
x	11H	A	10H	↑
н	13H	L	12H	Register bank 2
D	15H	E	14H	(RBE·RBS = 2)
В	17H	С	16H	L L
х	19H	А	18H	A
н	1BH	L	1AH	Register bank 3
D	1DH	E	1CH	(RBE·RBS = 3)
В	1FH	С	1EH	

Figure 3-5. General Register Configuration (4-Bit Processing)

XA	00H		XA'	00H	Â			
HL	02H		HĽ'	02H				
DE	04H		DE'	04H				
BC	06H	When RBE·RBS = 0				BC'	06H	When RBE-RBS
XA'	08H		XA	08H	= 1			
HL'	0AH			HL	0AH			
DE'	0CH		DE	0CH				
BC'	0EH	¥	BC	0EH				
ХА	10H		XA'	10H				
HL	12H		HĽ'	12H				
DE	14H		DE'	14H				
BC	16H	When RBE-RBS	BC'	16H	When RBE-RBS			
XA'	18H	= 2	XA	18H	= 3			
HĽ'	1AH		HL	1AH				
DE'	1CH		DE	1CH				
BC'	1EH		BC	1EH				

Figure 3-6. General Register Configuration (8-Bit Processing)

3.3 MEMORY-MAPPED I/O

The μPD750108 employs memory-mapped I/O, which maps peripheral hardware such as timers and I/O ports to addresses F80H to FFFH in data memory space as shown in Figure 3-2. This means that there is no particular instruction to control peripheral hardware, but all peripheral hardware is controlled using memory manipulation instructions. (Some mnemonics for hardware control are available to make programs readable.) To manipulate peripheral hardware, the addressing modes listed in Table 3-4 can be used.

	Applicable addressing mode	Applicable hardware
Bit manipulation	Direct addressing mode specifying mem.bit with MBE = 0 (MBE = 1, MBS = 15)	All hardware allowing bit manipulation
	Direct addressing mode specifying fmem.bit regardless of MBE and MBS setting	IST1, IST0, MBE, RBE, IExxx, IRQxxx, PORTn.x
	Indirect addressing mode specifying pmem.@L regardless of MBE and MBS setting	BSBn.x PORTn.x
4-bit manipulation	Direct addressing mode specifying mem with MBE = 0 or (MBE = 1, MBS = 15)	All hardware allowing 4-bit manipulation
	Register indirect addressing mode specifying @HL with (MBE = 1, MBS = 15)	_
8-bit manipulation	Direct addressing mode specifying mem (even address) with MBE = 0 or (MBE = 1, MBS = 15)	All hardware allowing 8-bit manipulation
	Register indirect addressing mode specifying @HL (with the L register containing an even number) with MBE = 1 and MBS = 15	

Table 3-4. Addressing Modes Applicable to Peripheral Hardware Operation

Figure 3-7 summarizes the I/O map of the μ PD750108.

The items in the figure have the following meanings:

- Symbol : Name representing incorporated hardware, which can be coded in the operand field of an instruction
- R/W : Indicates whether the hardware allows read/write operation.
 - R/W : Both read and write operations possible
 - R : Read only
 - W : Write only
- Number of manipulatable bits:

Indicates the number of bits that can be processed at a time in hardware manipulation

- O : Bit manipulation is possible in units of the indicated number of bits (1, 4, or 8 bits).
- Δ : Particular bits can be manipulated. For these bits, see Remarks.
- : Bit manipulation is impossible in units of the indicated number of bits (1, 4, or 8 bits).
- Bit manipulation addressing:

Bit manipulation addressing applicable in hardware bit manipulation

Address	I	Hardware na	ame (symbol)	R/W	Number manipula	of bits tha ated	it can be	Bit manipulation	Remarks
Addless	b3	b2	b1	b0		1 bit	4 bits	8 bits	addressing	Remarks
F80H		(2.5)		-	5.000					Bit 0 is fixed to 0.
	Stack point	er (SP)	R/W	_	-	0	_			
F82H	Register ba	3S)	_	_	0					
F83H	Bank selection register (BS) Memory bank selection register (MBS)					_	0	0	_	Note 1
F84H	Stack bank	selection re	egister (SBS))	R/W	-	0	-	mem.bit	
F85H	Basic interv	val timer mo	de register (l	BTM)	w		0	_	mem.bit	Only bit 3 can be manipulated.
F86H	- Basic interval timer (BT)				R			0		
	Dasic interv)						_	
F8BH	WDTM ^{Note 2}				W	0	_	_	mem.bit	

Figure 3-7. µPD750108 I/O Map (1/5)

F98H	Clock mode register (WM)	R/W	 (R)	_		mem.bit	Only bit 3 can be tested.
		K/ W	-	-	0	-	

Notes 1. Can be manipulated separately as the RBS and MBS in 4-bit units.

Can also be manipulated as the BS in 8-bit units.

Use SEL MBn and SEL RBn instructions to write data to the MBS and RBS respectively. Use a PUSH or POP instruction to write data to the BS.

2. WDTM: Watchdog timer enable flag (W); cannot be cleared by an instruction.

Address	H	Hardware na	ime (symbol)	R/W	Number manipula	of bits tha ated	it can be	Bit manipulation	Remarks
Address	b3	b2	b1	b0		1 bit	4 bits	8 bits	addressing	Remarks
FA0H	Timer/even	it counter mo	R/W	 (₩)	-	(R/W)	mem.bit	Bit write manipu- lation is enabled only for bit 3.		
						-	-	(13/00)	_	
FA2H	TOE0 ^{Note 1}				W	0	-	_	mem.bit	
FA4H	Timer/even	it counter co	unt register	(T0)	R	_	-	0	_	
FA6H	Timer/event counter modulo register (TMOD0)				R/W	_	-	0	_	
FA8H	Timer coun	iter mode reg	gister (TM1)		R/W	 (₩)	-	(R/W)	mem.bit	Bit write manipu- lation is enabled only for bit 3.
						-	-	(10/00)	-	
FAAH	TOE1 ^{Note 2}				W	0	-	_	mem.bit	
FACH	- Timer counter count register (T1)				R	_	_	0	_	
FAEH	Timer coun	iter modulo r	egister (TM	OD1)	R/W	_	_	0	_	

Figure 3-7. µPD750108 I/O Map (2/5)

Notes 1. TOE0: Timer/event counter output enable flag (W)

2. TOE1: Timer counter output enable flag (W)

Address	H	Hardware na	me (symbol)	R/W	Number manipula	of bits that ated	t can be	Bit manipulation	Remarks
Address	b3	b2	b1	b0	10 00	1 bit	4 bits	8 bits	addressing	Kemanos
FB0H	IST1	IST0	MBE	RBE		(R/W)	(R/W)	0		Manipulation in 8-bit units is
	Program st	atus word (F	PSW)		R/W	Neta 2	· · ·	(R)		enabled only
	CY ^{Note 1}	SK2 ^{Note 1}	SK1 ^{Note 1}	SK0 ^{Note 1}		∆ ^{Note 2}	-	(13)	fmem.bit	for reading.
FB2H	Interrupt pr	iority select	register (IPS	;)	R/W	-	0	-	intent.bit	Note 3
FB3H	Processor	clock control	register (PC	CC)	R/W	-	0	-		Note 4
FB4H	INT0 edge	detection mo	ode register	(IM0)	R/W	-	0			
FB5H	INT1 edge	detection mo	ode register	(IM1)	R/W	-	0	-	-	Bits 3, 2, and 1 are fixed to 0.
FB6H	INT2 edge	detection mo	ode register	(IM2)	R/W	-	0			Bits 3 and 2 are fixed to 0.
FB7H	System clo	ck control re	gister (SCC))	R/W	 (R/W)	(R)	_	_	Bits 2 and 1 are fixed to 0.
FB8H	INTA regist IE4	er (INTA) IRQ4	IEBT	IRQBT	R/W	0	0			
FBAH	INTC regist –	er (INTC) -	IEW	IRQW	R/W	0	0	_		
FBCH	INTE regist IET1	er (INTE) IRQT1	IET0	IRQT0	R/W	0	0		fmem.bit	
FBDH	INTF regist	er (INTF) –	IECSI	IRQCSI	R/W	0	0	_	intern.bit	
FBEH	INTG regist	ter (INTG) IRQ1	IE0	IRQ0	R/W	0	0			
FBFH	INTH regist	ter (INTH) –	IE2	IRQ2	R/W	0	0	_		

Figure 3-7. µPD750108 I/O Map (3/5)

FC0H	Bit sequential buffer 0 (BSB0)	R/W	0	0	0		
FC1H	Bit sequential buffer 1 (BSB1)	R/W	0	0		mem.bit	
FC2H	Bit sequential buffer 2 (BSB2)	R/W	0	0		pmem.@L	
FC3H	Bit sequential buffer 3 (BSB3)	R/W	0	0			
FCFH	Sub-oscillator control register (SOS)	R/W		0	-	-	

Notes 1. Not registered as a reserved word.

- 2. Use the CY manipulation operation to write data to the CY.
- 3. Only bit 3 can be manipulated by an EI/DI instruction.
- 4. Bits 3 and 2 can be manipulated bit by bit by a STOP/HALT instruction.

Remarks 1. IExxx : Interrupt enable flag

2. IRQxxx: Interrupt request flag

Address	Hardware name (symbol)				R/W	Number of bits that can be manipulated			Bit manipulation	Remarks
	b3	b2	b1	b0		1 bit	4 bits	8 bits	addressing	Remarks
FD0H	Clock output mode register (CLOM)				R/W	-	0	Ι	-	
FDCH	(PO3) ^{Note 1}	(PO2) ^{Note 1}	(PO1) ^{Note 1}	(PO0) ^{Note 1}						
	Pull-up resistor register group A (POGA)				R/W		-	0	-	
	(PO7) ^{Note 1}	(PO6) ^{Note 1}	-	_						
FDEH	-	-	-	(PO8) ^{Note 1}						
	Pull-up resi	R/W	-	-	0	-				
	_	_	_	_						

Figure 3-7. μ PD750108 I/O Map (4/5)

FE0H	Serial operation	R/W	_	_	0	I	Note 2			
	CSIE	COI	WUP			 (R) (W)	-		mem.bit	Note 2
FE2H	CMDD RELD CMDT RELT SBI control register (SBIC)				R/W	0	_	_	mem.bit	Whether this location is read- or write-
	BSYE	ACKD	ACKE	ACKT						accessible de- pends on the bit.
FE4H	Serial I/O shift register (SIO)				R/W	_	_	0	_	
FE6H	– Slave address register (SVA)					-	_	0	_	
FE8H	(PM33) ^{Note 1} (PM32) ^{Note 1} (PM31) ^{Note 1} (PM30) ^{Note 1} Port mode register group A (PMGA) (PM63) ^{Note 1} (PM62) ^{Note 1} (PM61) ^{Note 1} (PM60) ^{Note 1}				R/W	_	_	0	_	
FECH	- (PM2) ^{Note 1} Port mode register group B (PMGB) (PM7) ^{Note 1} - (PM5) ^{Note 1} (PM4) ^{Note 1}				R/W	_	_	0	_	
FEEH	– Port mode –	– register grou –	– ıp C (PMGC –	(PM8) ^{Note 1}) –	R/W	-	_	0	_	

Notes 1. Not registered as a reserved word.

2. Whether a bit can be read or written depends on the bit.

Address	Hardware name (symbol)				R/W	Number of bits that can be manipulated			Bit manipulation	Remarks
	b3	b2	b1	b0		1 bit	4 bits	8 bits	addressing	Remarks
FF0H	Port 0 (PORT0)				R/W	 (R) (R/W)	⊖ (R)			Note 1
FF1H	Port 1 (PORT1)					0	0		-	
FF2H	Port 2 (PORT2)					0	0	_		
FF3H	Port 3 (PORT3)					0	0			
FF4H	Port 4 (PORT4)					0	0		fmem.bit pmem.@L	
FF5H	Port 5 (PORT5)				R/W	0	0			
FF6H ^{Note 2}	KR3 Port 6 (PC	KR2 DRT6)	KR1	KR0	R/W	0	0			
FF7H ^{Note 2}	KR7 Port 7 (PC	KR6 DRT7)	KR5	KR4	R/W	0	0	0		
FF8H	Port 8 (PORT8)				R/W	0	0	_		

Figure 3-7. µPD750108 I/O Map (5/5)

- **Notes 1.** Bit 1 can be read or written only in serial operation enable mode. It can be read when four-bit manipulation is performed.
 - 2. KR0 to KR7 can be read (R) bit by bit. When inputting 4 bits at a time, specify PORT6 or PORT7.

CHAPTER 4 INTERNAL CPU FUNCTIONS

4.1 Mk I MODE/Mk II MODE SWITCH FUNCTIONS

4.1.1 Differences between Mk I Mode and Mk II Mode

The CPU of the μ PD750108 subseries has two modes (Mk I mode and Mk II mode) and which mode is used is selectable. Bit 3 of the stack bank selection register (SBS) determines the mode.

- Mk I mode: This mode has the upward compatibility with the 75X series. It can be used in the 75XL CPUs having a ROM of up to 16KB.
- Mk II mode: This mode is not compatible with the 75X series. It can be used in all 75XL CPUs, including those having a ROM of 16KB or more.

Table 4-1 shows the differences between Mk I mode and Mk II mode.

	Mk I mode	Mk II mode
Number of stack bytes in a subroutine instruction	2 bytes	3 bytes
BRA !addr1 instruction CALLA !addr1 instruction	Not supported	Supported
CALL laddr instruction	3 machine cycles	4 machine cycles
CALLF !faddr instruction	2 machine cycles	3 machine cycles

Table 4-1. Differences between Mk I Mode and Mk II Mode

* Caution For the 75X and 75XL series, Mk II mode supports a program area of more than 16K bytes. This mode is provided to maintain software compatibility with products requiring a program memory of more than 16K bytes.

When Mk II mode is selected, each use area of the stack byte when the subroutine call instruction is executed will be increased by one byte compared to Mk I mode. When the CALL !addr or CALLF !faddr instruction is used, the machine cycle will need one more machine cycle. Therefore, Mk I mode is recommended for those applications where emphasis is placed on RAM efficiency or speed rather than software compatibility.

4.1.2 Setting of the Stack Bank Selection Register (SBS)

The Mk I mode and Mk II mode are switched by stack bank selection register. Figure 4-1 shows the register configuration.

The stack bank selection register is set with a 4-bit memory operation instruction. To use the CPU in Mk I mode, initialize the register to 100xB^{Note} at the beginning of the program. To use the CPU in Mk II mode, initialize it to 000xB^{Note}.

Note Specify the desired value in x.

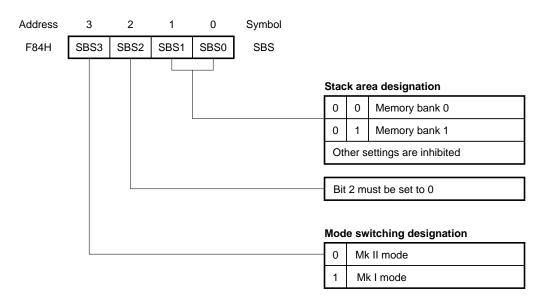


Figure 4-1. Stack Bank Selection Register Format

Caution The CPU operates in Mk I mode after the RESET signal is issued, because bit 3 of SBS is set to 1. Set bit 3 of SBS to 0 (Mk II mode) to use the CPU in Mk II mode.

4.2 PROGRAM COUNTER (PC): 12 BITS (μPD750104) 13 BITS (μPD750106 AND μPD750108) 14 BITS (μPD75P0116)

The program counter is a binary counter which retains the address data of the program memory. The program counter consists of 12 bits in the μ PD750104 (see **Figure 4-2(a)**), 13 bits in the μ PD750106 and μ PD750108 (see **Figure 4-2(b)**), and 14 bits in the μ PD75P0116 (see **Figure 4-2(c)**).

Figure 4-2. Program Counter Organization

(a) µPD750104

PC11	PC10	PC9	PC8	PC7	PC6	PC5	PC4	PC3	PC2	PC1	PC0
------	------	-----	-----	-----	-----	-----	-----	-----	-----	-----	-----

(b) μPD750106 and μPD750108

PC12	PC11	PC10	PC9	PC8	PC7	PC6	PC5	PC4	PC3	PC2	PC1	PC0

(c) µPD75P0116

PC13 PC12 PC11 PC10 PC9 PC8 PC7 PC6 PC5	PC4 PC3 PC2 PC1 PC0
---	---------------------

Usually, each time an instruction is executed, the program counter is automatically incremented according to the number of bytes in the instruction.

When a branch instruction (BR, BRA, BRCB) is executed, immediate data indicating the branch destination and the contents of a register pair are set in all or some bits of the program counter.

When a subroutine call instruction (CALL, CALLA, CALLF) is executed, or a vectored interrupt occurs, the current contents of the program counter (already incremented return address for fetching the next instruction) are saved in the stack memory (data memory indicated by the stack pointer), then the jump destination address is loaded.

When a return instruction (RET, RETS, RETI) is executed, the contents of the stack memory are set in the program counter.

When the RESET signal is issued, the program counter is initialized to the contents of the program memory at addresses 000H and 001H. The program can be started from any address according to the contents.

```
μPD750104 :
PC<sub>11</sub>-PC<sub>8</sub> <- (000H) <sub>3-0</sub>, PC<sub>7</sub>-PC<sub>0</sub> <- (001H) <sub>7-0</sub>
```

```
μPD750106 and μPD750108 :
PC<sub>12</sub>-PC<sub>8</sub> <- (000H) <sub>4-0</sub>, PC<sub>7</sub>-PC<sub>0</sub> <- (001H) <sub>7-0</sub>
```

```
μPD75P0116 :
PC<sub>13</sub>-PC<sub>8</sub> <- (000H) <sub>5-0</sub>, PC<sub>7</sub>-PC<sub>0</sub> <- (001H) <sub>7-0</sub>
```

4.3 PROGRAM MEMORY (ROM):

4096 WORDS x 8 BITS (μPD750104: MASKED ROM) 6144 WORDS x 8 BITS (μPD750106: MASKED ROM) 8192 WORDS x 8 BITS (μPD750108: MASKED ROM) 16384 WORDS x 8 BITS (μPD75P0116: ONE-TIME PROM)

The program memory is used for storing programs, an interrupt vector table, GETI instruction reference table, table data, and so forth. The μ PD750104, μ PD750106, and μ PD750108 are provided with a mask-programmable ROM as the program memory, and the μ PD75P0116 is provided with a one-time PROM.

Figures 4-3 to 4-6 show the program memory maps.

Program memory is addressed by the program counter. Table data can be referenced using the table reference instruction (MOVT).

Figures 4-3 to 4-6 also show the allowable branch address ranges for the branch instructions and subroutine call instructions. The relative branch instruction (BR \$addr) allows a branch to addresses (contents of the PC less 15 to one, or plus two to 16) regardless of block.

The program memory is located at following addresses.

- 0000H to 0FFFH: μPD750104
- 0000H to 17FFH: μPD750106
- 0000H to 1FFFH: μPD750108
- 0000H to 3FFFH: μPD75P0116

The following addresses are assigned to special functions. All areas excluding 0000H and 0001H can be used as normal program memory.

• 0000H to 0001H

Vector address table for holding the RBE and MBE values and program start address when a RESET signal is issued (allowing a reset start at an arbitrary address)

- 0002H to 000DH
 Vector address table for holding the RBE and MBE values and program start address for each vectored interrupt (allowing interrupt processing to be started at an arbitrary address)
- 0020H to 007FH
 Table area referenced by the GETI instruction^{Note}
- **Note** The GETI instruction can represent an arbitrary two-byte or three-byte instruction or two one-byte instructions in one byte and is used to reduce the number of program bytes. (See **Section 11.1.1.**)

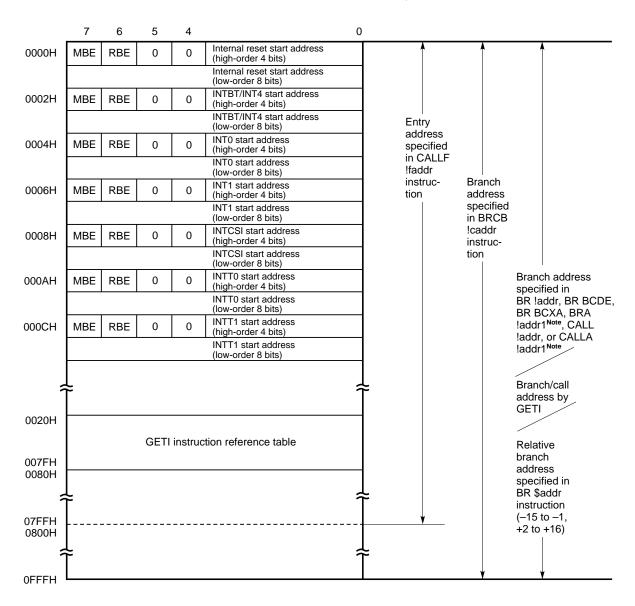


Figure 4-3. Program Memory Map (in µPD750104)

Note Can be used only in the MkII mode.

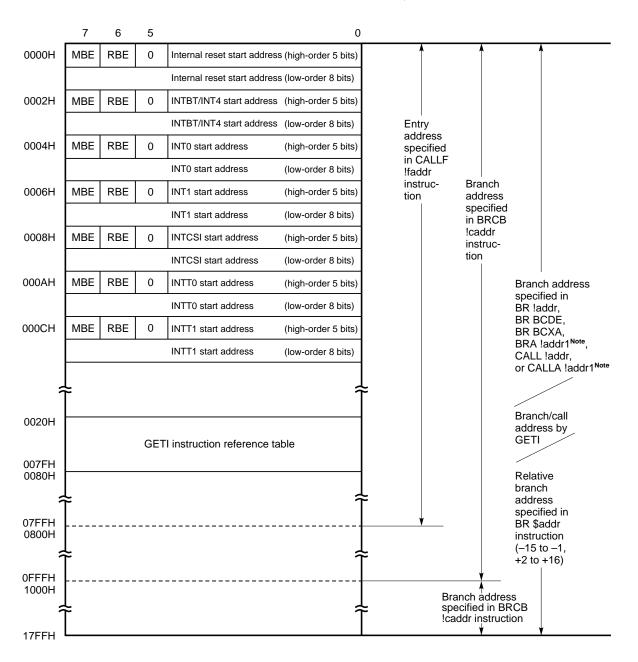


Figure 4-4. Program Memory Map (in µPD750106)

Note Can be used only in the MkII mode.

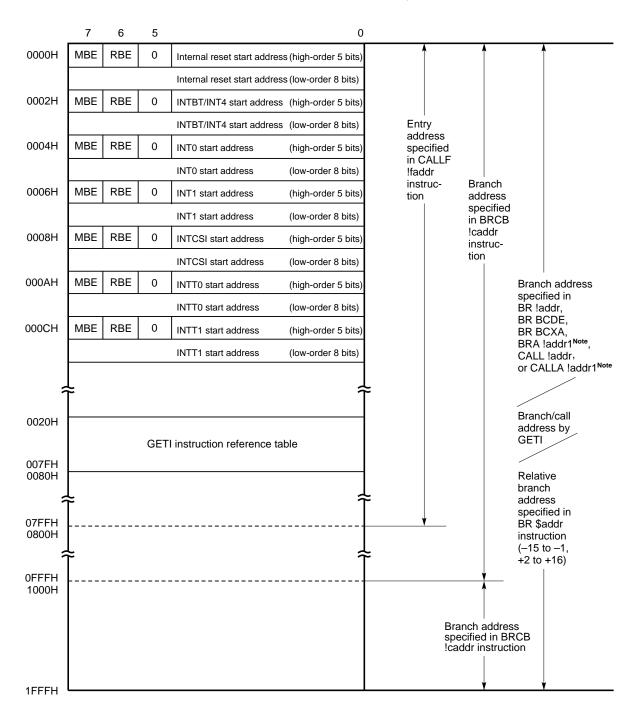


Figure 4-5. Program Memory Map (in µPD750108)

Note Can be used only in the MkII mode.

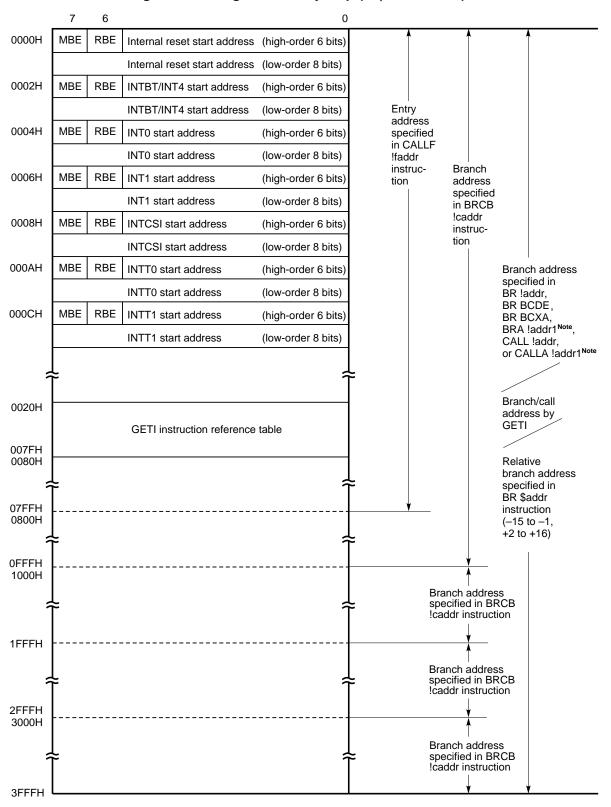
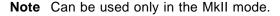


Figure 4-6. Program Memory Map (in µPD75P0116)



4.4 DATA MEMORY (RAM): 512 WORDS x 4 BITS

The data memory consists of a data area and peripheral hardware area as shown in Figure 4-7. The data memory consists of the following memory banks with each bank made of 256 words x 4 bits.

- Memory banks 0 and 1 (data area)
- Memory bank 15 (peripheral hardware area)

4.4.1 Data Memory Configuration

(1) Data area

The data area consists of a static RAM, and is used for storing program data and as stack memory for subroutine and interrupt execution. Battery backup enables the memory to hold data for a long time even if the CPU is stopped in the standby mode. The data area can be manipulated with memory manipulation instructions.

The static RAM is mapped to memory banks 0 and 1, with each made up of 256 words x 4 bits. Bank 0 is used as a data area, but can also be used as a general register area (000H to 01FH) and stack area **Note** (000H to 1FFH).

Whole locations in memory banks 0, 1, 2, and 3 (000H to 3FFH) can be used as a stack area.

The static RAM has a configuration of four bits per address. However, the memory can be manipulated in 8 bit units using an 8-bit memory manipulation instruction, and in bit units using a bit manipulation instruction. Note that an even address must be specified in an 8-bit manipulation instruction.

Note Memory bank 0 or 1 can be selected as the stack area.

General register area

The general register area can be manipulated with either general register manipulation instructions or memory manipulation instructions. Up to eight 4-bit registers are available. Of the 8 general registers, registers not used by the program can be used as a data area or stack area. (See **Section 4.5.**)

Stack memory area

The stack memory area is set by the instruction. This area can be used as a save area for subroutine or interrupt execution. (See **Section 4.7.**)

(2) Peripheral hardware area

The peripheral hardware area is mapped at addresses F80H to FFFH of memory bank 15. Memory manipulation instructions are used to manipulate the peripheral hardware area as well as the static RAM area. Note that, however, the number of bits to be manipulated at a time varies according to the individual addresses. Addresses to which no peripheral hardware is assigned cannot be accessed since such address locations contain no data memory. (See **Figure 3-7**.)

4.4.2 Specification of a Data Memory Bank

If the memory bank enable flag (MBE) enables bank specification (MBE = 1), a memory bank is specified with the 4-bit memory bank select register (MBS = 0, 1, 15). If the MBE disables bank specification (MBE = 0), memory bank 0 or 15 is automatically selected according to the addressing mode. Locations in a bank is addressed by 8-bit immediate data or a register pair.

For details on the selection of a memory bank and addressing, see Section 3.1.

For how to use the particular data memory areas, see the following sections and chapter.

- General register area : Section 4.5
- Stack memory area : Section 4.7
- Peripheral hardware area: Chapter 5

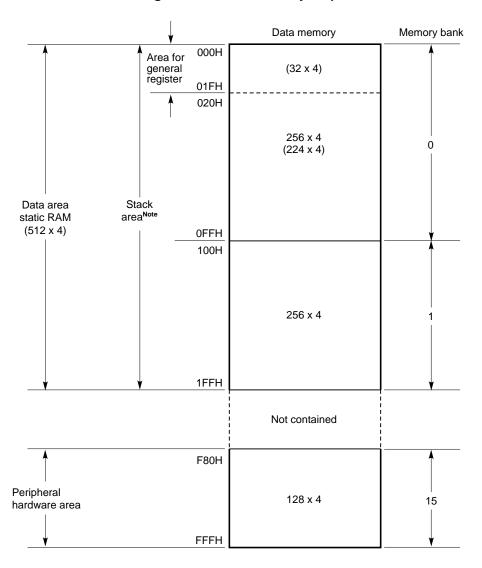


Figure 4-7. Data Memory Map

Note Memory bank 0 or 1 can be selected as the stack area.

Data memory is undefined when it is reset. For this reason, it is to be initialized to zero (RAM clear) usually at the start of a program. Remember to perform this initialization. Otherwise, unexpected bugs may occur.

Example	The following program	clears data at addresses	000H to 1FFH in RAM.
---------	-----------------------	--------------------------	----------------------

	SET1	MBE	
	SEL	MB0	
	MOV	XA,#00H	
	MOV	HL,#04H	
RAMC0:	MOV	@HL,A	; Clear 04H to FFHNote
	INCS	L	; L <- L + 1
	BR	RAMC0	
	INCS	Н	; H <– H + 1
	BR	RAMC0	
	SEL	MB1	
RAMC1:	MOV	@HL,A	; Clear 100H to 1FFH
	INCS	L	; L <- L + 1
	BR	RAMC1	
	INCS	Н	; H <– H + 1
	BR	RAMC1	

Note Data memory locations at 000H to 003H are allocated to general registers XA and HL, so these are not cleared.

4.5 GENERAL REGISTER: 8 x 4 BITS x 4 BANKS

The general registers are mapped to particular addresses in data memory. Four banks of registers are provided, with each bank consisting of eight 4-bit registers (B, C, D, E, H, L, X, and A).

The register bank (RB) to be enabled at the time of instruction execution is determined by:

 $RB = RBE \cdot RBS$: (RBS = 0 to 3)

Each general register allows 4-bit manipulation. In addition, BC, DE, HL, or XA serves as a register pair for 8-bit manipulation. DL also makes a register pair as well as DE and HL. These three register pairs can be used as data pointers.

In 8-bit manipulation, the register pairs in the register banks ($0 \le 1, 2 \le 3$) that have the inverted value of bit 0 of the register bank (RB) address can be specified as BC', DE', HL', and XA' in addition to the register pairs BC, DE, HL, and XA. (See **Section 3.2**.)

A general register area can be addressed and accessed as normal RAM, regardless of whether it is used as a register.

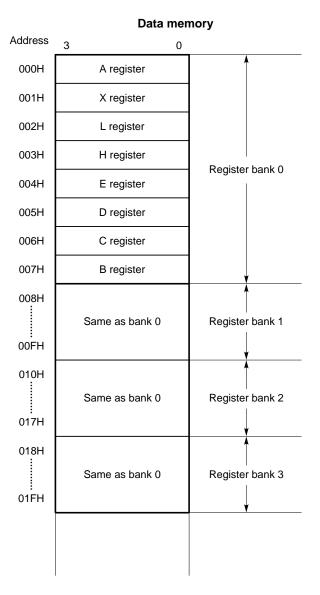


Figure 4-8. General Register Format

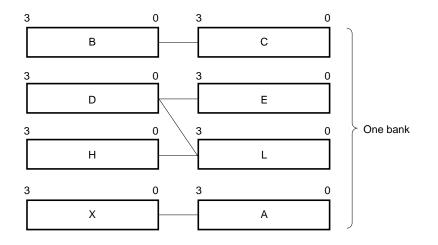
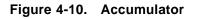


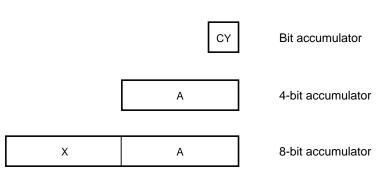
Figure 4-9. Register Pair Format

4.6 ACCUMULATOR

In the μ PD750108, the A register and XA register pair function as accumulators. The A register is mainly used for 4-bit data processing instructions, and the XA register pair is mainly used for 8-bit data processing instructions.

For a bit manipulation instruction, the carry flag (CY) functions as a bit accumulator.





4.7 STACK POINTER (SP) AND STACK BANK SELECT REGISTER (SBS)

The μ PD750108 uses static RAM as stack memory (LIFO scheme), and the 8-bit register holding the start address of the stack area is the stack pointer (SP).

The stack area is located at addresses 000H to 1FFH in memory banks 0 and 1. One memory bank is selected according to the value of the 2-bit SBS. (See **Table 4-2**.)

		1
SE	BS	Stack area
SBS1	SBS0	Stack area
0	0	Memory bank 0
0	1	Memory bank 1
Other than al	bove	Not to be set

Table 4-2. Stack Area to Be Selected by the SBS

The SP is decremented before a write (save) operation to stack memory, and is incremented after a read (restoration) operation from stack memory.

Figures 4-12 to 4-15 show data saved to and restored from stack memory in these stack operations.

To place the stack area at a given location, the SP can be initialized with an 8-bit memory manipulation instruction, and the SBS can be initialized with a 4-bit memory manipulation instruction. Both can be read from as well.

When the SP is initialized to 00H, a stack operation starts at the high-order address (nFFH) of memory bank (n) specified with the SBS.

A stack area must be within the memory bank specified with the SBS. If a stack operation exceeds address n00H, the operation returns to address nFFH in the same bank. Linear stacking beyond memory bank boundaries is enabled only by resetting the SBS.

A RESET signal causes the contents of the SP to be undefined, and causes the contents of the SBS to be 1000B. Remember to initialize the SP and SBS to a desired value at the start of a program.

Remark n = 0, 1

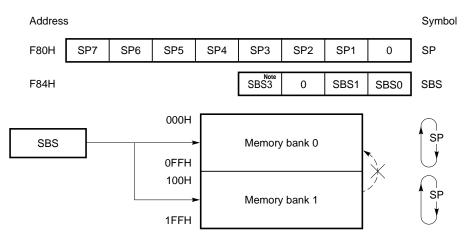


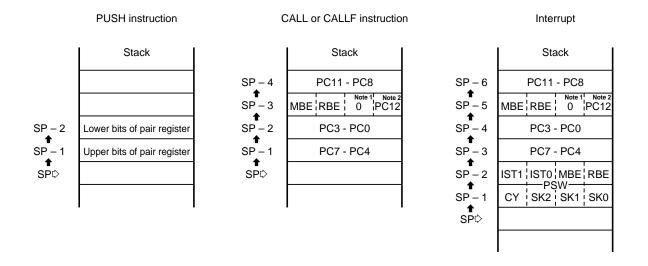
Figure 4-11. Format of Stack Pointer and Stack Bank Select Register

Note The Mk I mode and Mk II mode can be switched by bit 3 of SBS. The stack bank selection function can be used in both Mk I mode and Mk II mode. (See **Section 4.1** for details.)

Example SP initialization

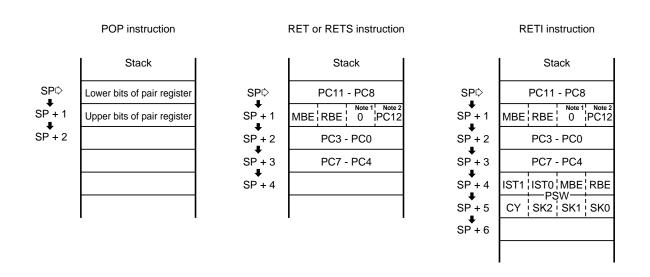
Specify memory bank 1 as a stack area to start stack operation at address 1FFH.

SEL	MB15	; or CLR1 MBE
MOV	A,#1	
MOV	SBS,A	; Specify memory bank 1 as a stack area
MOV	XA,#00H	
MOV	SP,XA	; SP <- 00H









Notes 1. For the μ PD75P0116, PC13 is entered instead of 0.

2. For the μ PD750104, 0 is entered instead of PC12.

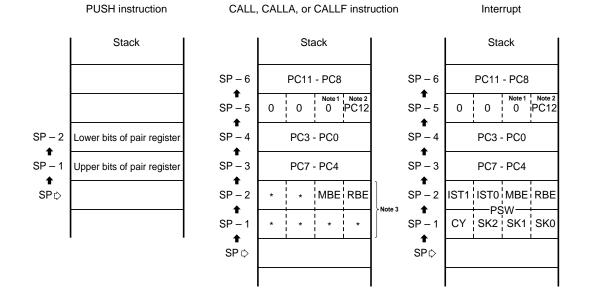
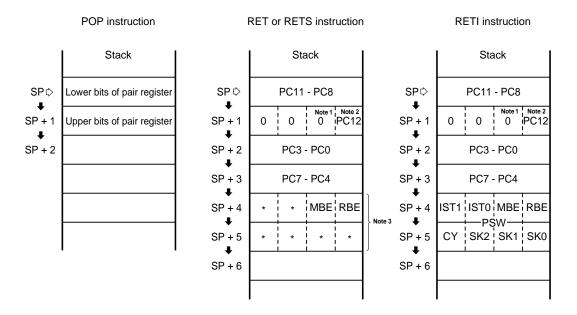


Figure 4-14. Data Saved to the Stack Memory (Mk II Mode)





Notes 1. For the μ PD75P0116, PC13 is entered instead of 0.

- **2.** For the μ PD750104, 0 is entered instead of PC12.
- 3. PSW bits other than MBE and RBE are not saved or restored.

Remark * indicates an undefined bit.

4.8 PROGRAM STATUS WORD (PSW): 8 BITS

The program status word (PSW) consists of various flags closely associated with processor operations. The PSW is mapped to addresses FB0H and FB1H in data memory space. Four bits at address FB0H can be manipulated with a memory manipulation instruction.

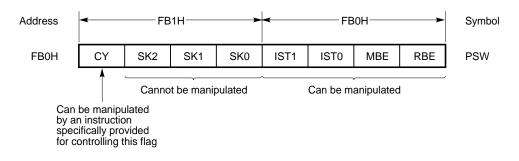


Figure 4-16. Program Status Word Format

Table 4-3. PSW Flags Saved/Restored in Stack Operation

		Saved/restored flag
Save	When a CALL, CALLA, or CALLF instruction is executed	MBE and RBE are saved.
	When a hardware interrupt occurs	All PSW bits are saved.
Restore	When a RET or RETS instruction is executed	MBE and RBE are restored.
	When a RETI is executed	All PSW bits are restored.

(1) Carry flag (CY)

The carry flag is a 1-bit flag used to store information about an overflow or underflow that occurs when an arithmetic operation with a carry (ADDC, SUBC) is executed.

The carry flag functions as a bit accumulator, and therefore can be used to store the result of a Boolean algebra operation performed on the CY and a bit at a specified data memory bit address.

The carry flag is manipulated using special instructions, independently of the other PSW bits.

A RESET signal causes the carry flag to be undefined.

	Instruction (mnemonio	c) Carry flag operation/processing
Instruction dedicated to carry flag manipulation	SET1 CY CLR1 CY NOT1 CY SKT CY	Sets CY to 1. Clears CY to 0. Inverts the state of CY. Skips if CY is 1.
Bit transfer instruction	MOV1 mem*.bit, CY MOV1 CY, mem*.bit	Transfers the state of CY to a specified bit. Transfers the state of a specified bit to CY.
Bit Boolean instruction	AND1 CY, mem*.bit OR1 CY, mem*.bit XOR1 CY, mem*.bit	then sets the result in CY.
Interrupt handling	Interrupt execution	Saves CY and all other PSW bits to stack memory in parallel.
	RETI	Restores CY together with the other PSW bits from stack memory in parallel.

Table 4-4. Carry Flag Manipulation Instructions

Remark mem*.bit represents the following bit addressing:

- fmem.bit
- pmem.@L
- @H+mem.bit

Example Bit 3 at address 3FH is ANDed with P33, then the result is set in P50.

MOV	H,#3H	; Set the high-order 4 bits of the address in H register
MOV1	CY,@H+0FH.3	; CY <– bit 3 at 3FH
AND1	CY,PORT3.3	; CY <- CY ^P33
MOV1	PORT5.0,CY	; P50 <- CY

(2) Skip flags (SK2, SK1, SK0)

The skip flags are used to store skip status, and are automatically set or reset when the CPU executes an instruction.

The user cannot directly manipulate these flags by specifying an operand.

(3) Interrupt status flag (IST1, IST0)

The interrupt status flag is a 2-bit flag used to store the status of processing being performed. See **Table 6-3** for details.

IST1	IST0	Status of processing	Processing and interrupt control being performed
0	0	Status 0	Normal program processing is being performed. Any interrupts are acceptable.
0	1	Status 1	A lower- or higher-priority interrupt is being serviced. Higher-priority interrupts are acceptable.
1	0	Status 2	A higher-priority interrupt is being serviced. No interrupts are acceptable.
1	1	—	Not to be set

Table 4-5. Information Indicated by the Interrupt Status Flag

The interrupt priority control circuit (see Figure 6-1) checks this flag to control multiple interrupts.

The contents of the IST1 and IST0 are saved as part of the PSW to stack memory if an interrupt is accepted, then are automatically set to a one-step higher status. The RETI instruction restores the contents present before an interrupt occurs.

The interrupt status flag can be manipulated using a memory manipulation instruction, and the status of processing being performed can be changed by program control.

Caution The user must always disable interrupts with the DI instruction before manipulating this flag, and must enable interrupts with the EI instruction after manipulating this flag.

(4) Memory bank enable flag (MBE)

The memory bank enable flag is a 1-bit flag used to specify the address information generation mode for the high-order four bits of a 12-bit data memory address.

The MBE can be set or reset any time with a bit manipulation instruction, regardless of memory bank setting.

When the MBE is set to 1, the data memory address space is expanded, allowing all data memory space to be addressed.

When the MBE is reset to 0, the data memory address space is fixed, regardless of MBS setting. (See **Figure 3-2**.)

A RESET signal automatically initializes the MBE by setting the MBE to the content of bit 7 at program memory address 0.

In vectored interrupt processing, the MBE is automatically set to the content of bit 7 in the vector address table for servicing the interrupt.

Usually, the MBE is set to 0 in interrupt processing, and static RAM in memory bank 0 is used.

(5) Register bank enable flag (RBE)

The register bank enable flag is a 1-bit flag used to determine whether to expand the general register bank configuration.

The RBE can be set or reset any time with a bit manipulation instruction, regardless of memory bank setting.

When the RBE is set to 1, a set of general registers can be selected from register banks 0 to 3, depending on the setting of the register bank select register (RBS).

When the RBE is reset to 0, register bank 0 is always selected as general registers, regardless of the setting of the RBS.

A RESET signal automatically initializes the RBE by setting the RBE to the state of bit 6 at program memory address 0.

When a vectored interrupt occurs, the RBE is automatically set to the state of bit 6 in the vector address table for servicing the interrupt. Usually, the RBE is set to 0 in interrupt processing. Register bank 0 is used for 4-bit processing, and register banks 0 and 1 are used for 8-bit processing.

4.9 BANK SELECT REGISTER (BS)

The bank select register (BS) consists of a register bank select register (RBS) and memory bank select register (MBS), which specify a register bank and memory bank to be used, respectively.

The RBS and MBS are set using the SEL RBn instruction and SEL MBn instruction, respectively.

The contents of the BS can be saved to or restored from a stack memory eight bits at a time by using the PUSH BS/POP BS instruction.





(1) Memory bank select register (MBS)

The memory bank select register is a 4-bit register used to store the high-order four bits of a 12-bit data memory address. The contents of this register specify a memory bank to be accessed. The μ PD750108 allows memory banks 0, 1, and 15 only to be specified.

The MBS is set with the SEL MBn instruction (n = 0, 1, 15).

Figure 3-2 shows the range of addressing using MBE and MBS settings.

A RESET signal initializes the MBS to 0.

(2) Register bank select register (RBS)

The register bank select register specifies a register bank to be used as general registers; a register bank can be selected from register banks 0 to 3.

The RBS is set by the SEL RBn instruction (n = 0 to 3).

A RESET signal initializes the RBS to 0.

RBE		RE	BS		Pogistor bank		
RDE	3	2	1	0	Register bank		
0	0	0	х	х	Bank 0 is always selected.		
1	0	0	0	0	Bank 0 is selected.		
			0	1	Bank 1 is selected.		
			1	0	Bank 2 is selected.		
			1	1	Bank 3 is selected.		

Table 4-6. Register Bank to Be Selected with the RBE and RBS

x: Don't care

CHAPTER 5 PERIPHERAL HARDWARE FUNCTIONS

5.1 DIGITAL I/O PORTS

The μ PD750108 employs the memory mapped I/O method. Thus, all input/output ports are mapped on the data memory space.

Address	3	2	1	0	
FF0H	P03	P02	P01	P00	PORT 0
FF1H	P13	P12	P11	P10	PORT 1
FF2H	P23	P22	P21	P20	PORT 2
FF3H	P33	P32	P31	P30	PORT 3
FF4H	P43	P42	P41	P40	PORT 4
FF5H	P53	P52	P51	P50	PORT 5
FF6H	P63	P62	P61	P60	PORT 6
FF7H	P73	P72	P71	P70	PORT 7
FF8H	I	-	P81	P80	PORT 8

Figure 5-1. Data Memory Addresses of Digital Ports

Remark Some I/O parts can be used as static RAM.

Input/output port manipulation instructions are as listed in Table 5-2. Ports 4 to 7 can be manipulated not only in 4-bit units, but also in 8-bit or 1-bit units so that these ports can be controlled in various ways.

Examples 1. To test the condition of P13 and output different values to ports 4 and 5 according to the test

result: SKT PORT1. 3 ; Skips if bit 3 of port 1 is 1 MOV XA, #18H ; XA <- 18H MOV XA, #14H ; XA <- 14H SEL MB15 ; Or CLR1 MBE OUT PORT4, XA ; Port 5, 4 <- XA

2. SET1 PORT4. @L; Sets the bit(s) specified by the L register, in ports 4 to 7, to 1.

5.1.1 Types, Features, and Configurations of Digital I/O Ports

Table 5-1 lists the types of digital I/O ports.

Figures 5-2 to 5-6 show the configurations of the ports.

Port (pin name)	Function	Operation and feat	Remarks			
PORT0 (P00-P03)	4-bit input	When the serial interface fu operation mode causes the to become an output pin.	Also used as INT4, SCK, SO/SB0, and SI/SB1.			
PORT1 (P10-P13)		4-bit input-only port	4-bit input-only port			
PORT2 (P20-P23)	4-bit I/O	Allows input or output mode of 4 bits.	Also used as PTO0, PTO1, PCL, and BUZ.			
PORT3 (P30-P33)		Allows input or output mode bit-by-bit basis.	Also used as MD0-MD3Note 1.			
PORT4 (P40-P43)	4-bit I/O (N-ch open-drain; withstand voltage	Allows input or output mode setting in units of 4 bits. Whether to use pull-up	Ports 4 and 5 can be paired, allowing data I/O	Also used as D0-D3 ^{Note 1} .		
PORT5 (P50-P53)	of 13 V)	resistors can be specified, bit-by-bit, with the mask option ^{Note 2} .	in units of 8 bits.	Also used as D4-D7Note 1.		
PORT6 (P60-P63)	4-bit I/O	Allows input or output mode setting on a bit-by-bit basis.	can be paired,	Also used as KR0-KR3.		
PORT7 (P70-P73)	• 	Allows input or output mode setting in units of 4 bits.	allowing data I/O in units of 8 bits.	Also used as KR4-KR7.		
PORT8 (P80-P81)	2-bit I/O	Allows input or output mode of 2 bits.	setting in units	-		

Table 5-1. Types and Features of Digital Ports

Notes 1. Only for the μ PD75P0116.

2. Pull-up resistors, specified with the mask option, are not connected to the μ PD75P0116.

P10 is also used as an external vectored interrupt input pin. This input is provided with a noise eliminator. (See **Section 6.3** for details.)

When the RESET signal is generated, output latches of ports 2 to 8 are cleared to 0 and the output buffer is turned off so that these ports are in the input mode.

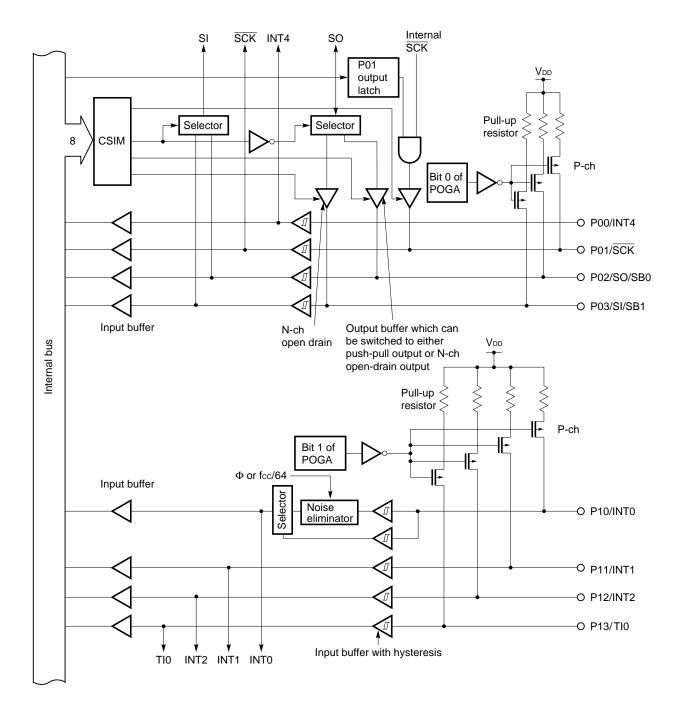
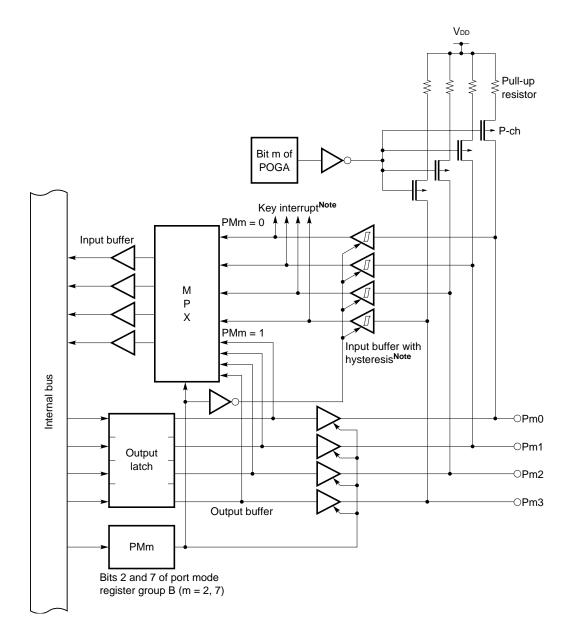
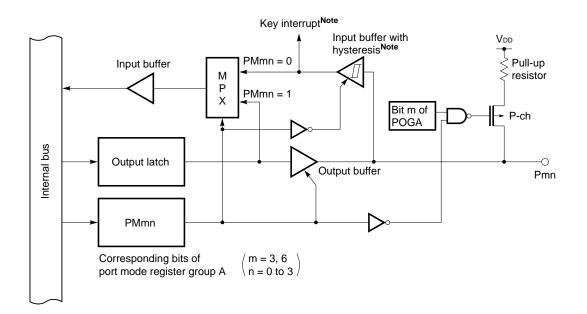


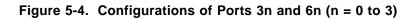
Figure 5-2. Configurations of Ports 0 and 1





Note For port 7 only





Note For port 6n only

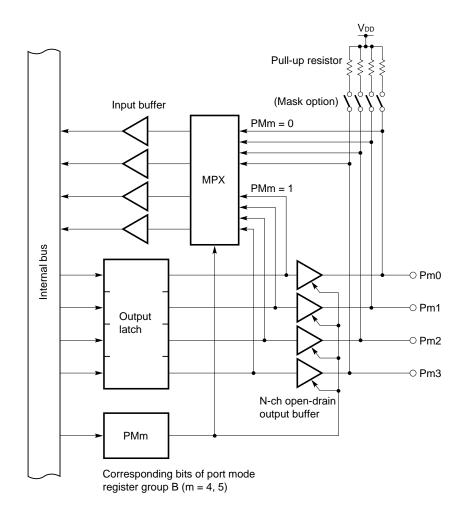
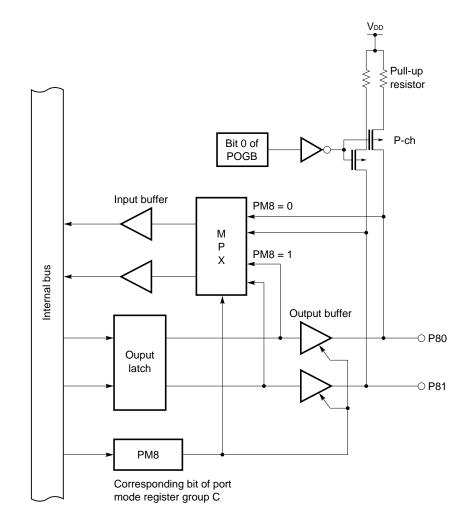


Figure 5-5. Configurations of Ports 4 and 5





5.1.2 I/O Mode Setting

The I/O mode of each I/O port is set by the port mode register as shown in Figure 5-7. The I/O modes of ports 3 and 6 can be set bit by bit by port mode register group A (PMGA). The I/O modes of ports 2, 4, 5, and 7 can be set in units of four bits by port mode register group B (PMGB). The I/O mode of port 8 can be set in units of two bits by port mode register group C (PMGC).

Each port functions as an input port when the corresponding bit of the port mode register is set to 0, and functions as an output port when the same corresponding bit is set to 1.

When the output mode is selected by the port mode register, the contents of the output latch appear on the output pins, and so the contents of the output latch must be changed to a desired value before the output mode is set.

An 8-bit memory manipulation instruction is used to set port mode register group A, B, or C.

A RESET signal clears all bits of each port mode register to 0. This means that the output buffers are set off, and all ports are placed in the input mode.

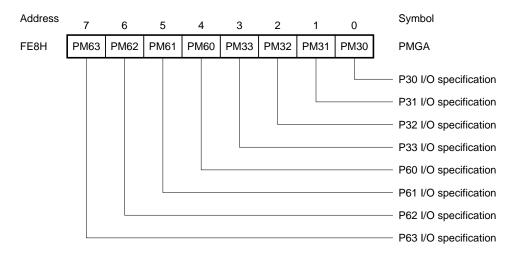
Example P30, P31, P62, and P63 are used as input pins, and P32, P33, P60, and P61 are used as output pins.

CLR1	MBE	; or SEL MB15
MOV	XA,#3CH	
MOV	PMGA,XA	

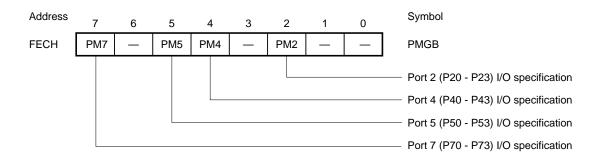
Figure 5-7. Formats of Port Mode Registers

	Contents of specification				
0 Input mode (Output buffer off)					
1 Output mode (Output buffer on)					

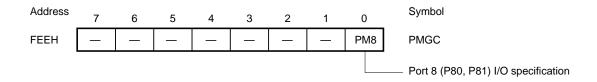
Port mode register group A



Port mode register group B



Port mode register group C



5.1.3 Digital I/O Port Manipulation Instructions

All I/O ports contained in the μ PD750108 are mapped to data memory space, so that all data memory manipulation instructions can be used. Table 5-2 lists the instructions that are particularly useful for I/O pin manipulation and their application ranges.

(1) Bit manipulation instructions

For digital I/O ports PORT0 to PORT8, specific address bit direct addressing (fmem.bit) and specific address bit register indirect addressing (pmem.@L) can be used. This means that bit manipulation can be freely performed for these ports regardless of MBE and MBS settings.

Example P50 is ORed with P41, then the result is output to P61.

	SET1	CY	; CY <– 1
	AND1	CY,PORT5.0	; CY <- CY \land P50
	OR1	CY,PORT4.1	; CY <− CY [∨] P41
	SKT	CY	
	BR	CLRP	
	SET1	PORT6.1	; P61 <– 1
	÷		
	•		
CLRP :	CLR1	PORT6.1	; P61 <– 0

(2) 4-bit manipulation instructions

All 4-bit memory manipulation instructions including the IN, OUT, MOV, XCH, ADDS, and INCS instructions can be used. However, before these instructions can be executed, memory bank 15 must be selected.

Examples 1. The contents of the accumulator are output to port 3.

SEL MB15 ; or CLR1 MBE OUT PORT3.A

2. The value of the accumulator is added to the data output on port 5, then the result is output.

SET1	MBE	
SEL	MB15	
MOV	HL,#PORT5	
ADDS	A,@HL	; A <- A+PORT5
NOP		
MOV	@HL,A	; PORT5 <- A

3. Whether the data on port 4 is greater than the value of the accumulator is tested.

MBE	
MB15	
HL,#PORT4	
A,@HL	; A < PORT4
NO	; NO
	; YES
	MB15 HL,#PORT4 A,@HL

(3) 8-bit manipulation instructions

The MOV, XCH, and SKE instructions as well as the IN and OUT instructions can be used for ports 4 and 5 that allow 8-bit manipulation. As with 4-bit manipulation, memory bank 15 must be selected in advance.

Example The data contained in the BC register pair is output on the output port specified by 8-bit data applied to ports 4 and 5.

	•	
SET1	MBE	
SEL	MB15	
IN	XA,PORT4	; XA <- ports 5,4
MOV	HL,XA	; HL <– XA
MOV	XA,BC	; XA <- BC
MOV	@HL,XA	; Port (L) <- XA

•	÷	•	

Instructi	PORT	PORT 0	PORT 1	PORT 2	PORT 3	PORT 4	PORT 5	PORT 6	PORT 7	PORT 8
IN	A, PORTn Note	1				0				
IN	XA, PORTn Note	1 _			_	()	(Э	_
Ουτ	PORTn, A Note	1 _	_				0			
OUT	PORTn, XA Note	1 _	_	_	_	()	0		_
MOV	A, PORTn Note	1		1		0		I		I
MOV	XA, PORTn Note	1 _	_	_	_		С)		
MOV	PORTn, A Note	1 _	_				0			
MOV	PORTn, XA Note	1 _	_	-	_		С)		
ХСН	A, PORTn Note	1				0				
ХСН	XA, PORTn Note	1 _	_	_	_		С)		_
MOV1	CY, PORTn.bit					0				
MOV1	CY, PORTn.@LNote	2				0				
MOV1	PORTn.bit, CY			0						
MOV1	PORTn.@L, CYNote	2		0						
INCS	PORTn Note	1			0					
SET1	PORTn.bit	-	—		0					
SET1	PORTn.@L Note	2 _	—		0					
CLR1	PORTn.bit	-			0					
CLR1	PORTn.@L Note	2 _			0					
SKT	PORTn.bit			0						
SKT	PORTn.@L Note	2		0						
SKF	PORTn.bit			0						
SKF	PORTn.@L Note	2		0						
SKTCLF	PORTn.bit			0						
SKTCLR PORTn.@L Note 2		2				0				
AND1	CY, PORTn.bit		0							
AND1	CY, PORTn.@LNote	2		0						
OR1	CY, PORTn.bit			0						
OR1	CY, PORTn.@LNote	2		0						
XOR1 CY, PORTn.bit					0					
XOR1	CY, PORTn.@LNote	2				0				

Notes 1. MBE = 0 or (MBE = 1, MBS = 15) must be set before execution.

2. The low-order two bits of an address and bit address are indirectly specified using the L register.

5.1.4 Digital I/O Port Operation

When a data memory manipulation instruction is executed for a digital I/O port, the operation of the port and pins depends on the I/O mode setting (Table 5-3). This is because data taken in on the internal bus is the data input from the pins in the input mode, or the output latch data in the output mode, as obvious from the configurations of I/O ports.

(1) Operation when the input mode is set

Data from each pin is manipulated when a test instruction such as the SKT instruction, a bit input instruction such as MOV1, or an instruction for taking in port data on the internal bus in units of four or eight bits (such as an IN, MOV, arithmetic/logical or comparison instruction) is executed.

When an instruction (the OUT or MOV instruction) is executed to transfer the contents of the accumulator to a port in units of four or eight bits, the data of the accumulator is latched in the output latch, with the output buffers kept off.

When the XCH instruction is executed, the data on each pin is loaded into the accumulator, and the data in the accumulator is latched in the output latch, with the output buffers kept off.

When the INCS instruction is executed, the 4-bit data existing on the pins plus 1 is latched in the output latch, with the output buffers kept off.

When an instruction such as the SET1, CLR1, or SKTCLR instruction is executed to rewrite a data memory bit, the output latch data of the specified bit can be rewritten according to the instruction, but the states of the other output latch bits are undefined.

(2) Operation when the output mode is set

When a test instruction or instruction for taking in port data on the internal bus in units of four or eight bits is executed, output latch data is manipulated.

When an instruction is executed to transfer the contents of the accumulator in units of four or eight bits, the output latch data is rewritten, and is output on the pins.

When the XCH instruction is executed, the output latch data is transferred to the accumulator. The contents of the accumulator are latched in the output latches, and are output on the pins.

When the INCS instruction is executed, the contents of the output latch incremented by 1 are latched in the output latch, and are output on the pins.

When a bit output instruction is executed, the specified bit of the output latch is rewritten, and is output on the pin.

Instruction		Port and pin operation					
	Siruction	Input mode	Output mode				
SKT SKF	<1> <1>	Pin data is tested.	Output latch data is tested.				
MOV1	CY, <1>	Pin data is transferred to CY.	Output latch data is transferred to CY.				
AND1 OR1 XOR1	CY, <1> CY, <1> CY, <1>	An operation is performed on pin data and CY.	An operation is performed on output latch data and CY.				
IN IN MOV MOV MOV	A,PORTn XA,PORTn A,PORTn XA,PORTn A,@HL XA,@HL	Pin data is transferred to the accumulator.	Output latch data is transferred to the accumulator.				
	,	An operation is performed on pin data and the accumulator.	An operation is performed on output latch data and the accumulator.				
SKE SKE	A,@HL XA,@HL	Pin data is compared with the accumulator.	Output latch data is com- pared with the accumulator.				
OUT OUT MOV MOV MOV MOV	PORTn,A PORTn,XA PORTn,A PORTn,XA @HL,A @HL,XA	Accumulator data is transferred to the output latch (with the output buffers kept off).	Accumulator data is transferred to the output latch and is output on the pins.				
XCH XCH XCH XCH	A,PORTn XA,PORTn A,@HL XA,@HL	Pin data is transferred to the accumulator, and accumulator data is transferred to the output latch (with the output buffers kept off).	Data is exchanged between the output latch and accumulator.				
INCS INCS	PORTn @HL	Pin data incremented by 1 is latched in the output latch.	Output latch data is incremented by 1.				
	<1> <1> <1> ,CY .R <1>	The output latch data of a specified bit is rewritten, but the output latch data of the other bits is undefined.	The output pin state is modified according to the instruction.				

Table 5-3. Operations by I/O Port Manipulation Instructions

<1>: Represents an addressing mode PORTn.bit or PORTn.@L.

* *

* *

5.1.5 Specification of Built-In Pull-Up Resistors

A pull-up resistor can be contained at each port pin of the μ PD750108 (except for P00). Whether to use the pull-up resistor can be specified by software (for some pins) or a mask option (for the other pins).

Table 5-4 shows how a built-in pull-up resistor is specified for each port pin. The built-in pull-up resistor is connected by software in the format shown in Figure 5-8.

In input mode, the pull-up resistor can be connected only to the pins of port 3 and 6. When the pins are set in output mode, the pull-up resistor cannot be connected regardless of the setting of POGA.

Port (pin name)	Pull-up resistor incorporation specification method	Specified bit
Port 0 (P01-P03)Note	Connection specification by software in units of 3 bits	POGA.0
Port 1 (P10-P13)	Connection specification by software in units of 4 bits	POGA.1
Port 2 (P20-P23)		POGA.2
Port 3 (P30-P33)		POGA.3
Port 4 (P40-P43)	Connection specification by software, bit-by-bit	-
Port 5 (P50-P53)		
Port 6 (P60-P63)	Connection specification by software in units of 4 bits	POGA.6
Port 7 (P70-P73)		POGA.7
Port 8 (P80, P81)	Connection specification by software in units of 2 bits	POGB.0

Table 5-4. Specification of Built-In Pull-Up Resistors

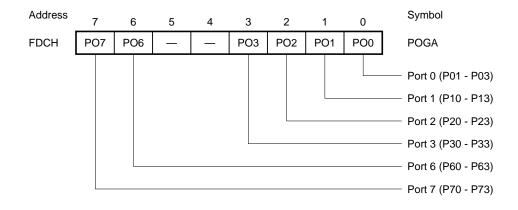
Note The P00 pin cannot specify connection of a built-in pull-up resistor.

Remark Pull-up resistors, specified with the mask option, are not connected to the µPD75P0116.

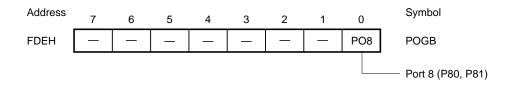
	Specification contents	
0	Built-in pull-up resistor not connected	
1	Built-in pull-up resistor connected	

Figure 5-8. Pull-Up Resistor Specification Register Format

Pull-up resistor specification register group A



Pull-up resistor specification register group B



5.1.6 I/O Timing of Digital I/O Ports

Figure 5-9 shows the timing of data output to an output latch and the timing of taking in pin data or output latch data on the internal bus.

Figure 5-10 shows an ON timing chart when a built-in pull-up resistor is connected to a port pin by software.

Figure 5-9. I/O Timing Chart of Digital I/O Ports (1/2)

(a) When data is input by a 1-machine cycle instruction

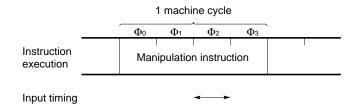
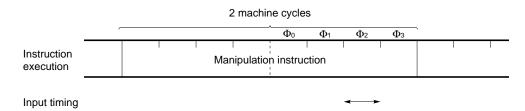
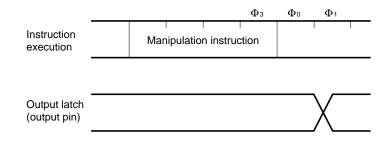


Figure 5-9. I/O Timing Chart of Digital I/O Ports (2/2)

(b) When data is input by a 2-machine cycle instruction



(c) When data is latched by a 1-machine cycle instruction



(d) When data is latched by a 2-machine cycle instruction

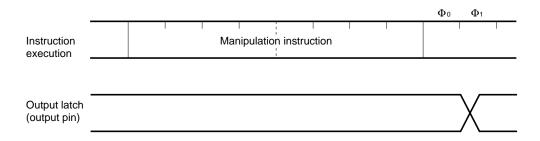
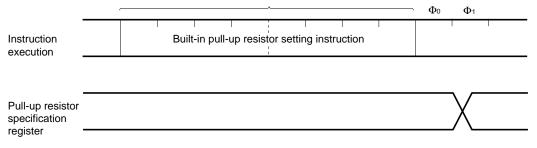


Figure 5-10. ON Timing Chart of Built-In Pull-Up Resistor Connected by Software

2 machine cycles



5.2 CLOCK GENERATOR

The clock generator supplies various clock signals to the CPU and peripheral hardware to control the CPU operation mode.

5.2.1 Clock Generator Configuration

Figure 5-11 shows the configuration of the clock generator.

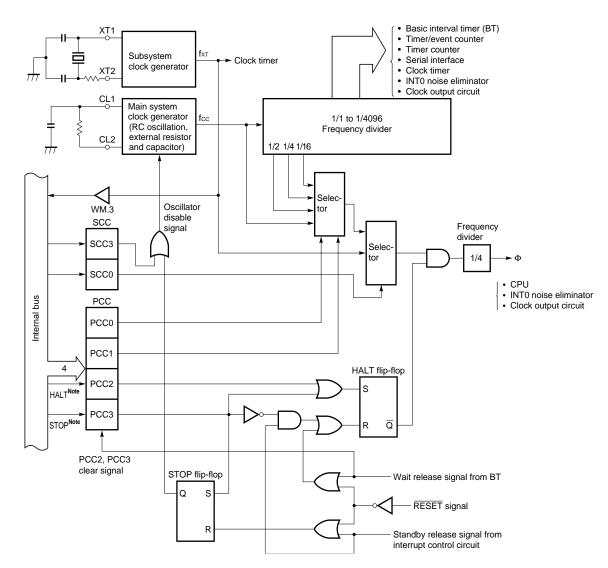


Figure 5-11. Block Diagram of the Clock Generator

Note Instruction execution

Remarks 1. f_{CC}: Main system clock frequency

- 2. f_{XT}: Subsystem clock frequency
- **3.** Φ = CPU clock
- 4. PCC: Processor clock control register
- 5. SCC: System clock control register
- **6.** One clock cycle (t_{CY}) of the CPU clock (Φ) is equal to one machine cycle of an instruction.

5.2.2 Functions and Operations of the Clock Generator

The clock generator generates the following clocks, and controls the CPU operation modes such as the standby mode.

- Main system clock f_{CC}
- Subsystem clock f_{XT}
- CPU clock Φ
- Clock to peripheral hardware

The operation of the clock generator is determined by the processor clock control register (PCC) and system clock control register (SCC). The function and operation of the clock generator are described in (a) to (g) below.

- (a) A RESET signal selects the lowest-speed mode $(32 \,\mu s \,at \, 2 \,MHz)^{Note \, 1}$ for the main system clock (PCC = 0, SCC = 0).
- (b) When the main system clock is selected, the PCC can be set to select one of four CPU clocks (2, 4, 8, and 32 μs at 2 MHz)^{Note 2}.
- (c) When the main system clock is selected, the two standby modes, STOP mode and HALT mode, are available.
- (d) The SCC can be set to select the subsystem clock for very low-speed, low-current operation (122 μ s at 32.768 kHz). The value in the PCC does not affect the CPU clock.
- (e) When the subsystem clock is selected, main system clock generation can be stopped with the SCC. In addition, the HALT mode can be used, but the STOP mode cannot be used. (Subsystem clock generation cannot be stopped.)
- (f) The clock to be supplied to peripheral hardware is produced by frequency-dividing the main system clock signal. The subsystem clock can directly be supplied only to the clock timer. This enables the clock function and the buzzer output function to continue operating even in the standby state.
- (g) When the subsystem clock is selected, the clock timer can continue to operate normally. The serial interface, timer/event counter, and timer counter can continue to operate when the external clock is selected. However, other hardware cannot be used when the main system clock is stopped because they operate with the main system clock.
- **Notes 1.** At $f_{CC} = 1$ MHz: 64 μ s
 - **2.** At f_{CC} = 1 MHz: 4, 8, 16, and 64 μ s

(1) Processor clock control register (PCC)

The PCC is a 4-bit register for selecting a CPU clock Φ with the low-order two bits and for controlling the CPU operation mode with the high-order two bits (see **Figure 5-12**).

When bit 3 or bit 2 is set to 1, the standby mode is set. When the standby mode is released by the standby release signal, these bits are automatically cleared to return to the normal operation mode. (See **Chapter 7** for details.)

A 4-bit memory manipulation instruction is used to set the low-order two bits of the PCC. (The high-order two bits are set to 0.)

Bit 3 and bit 2 are set to 1 using the STOP instruction and HALT instruction, respectively.

The STOP instruction and HALT instruction can always be executed regardless of MBE setting.

The CPU clock can be selected only while the processor is operated by the main system clock. When the processor is operated by the subsystem clock, the low-order 2 bits of the PCC are invalidated, and $f_{XT}/4$ is automatically set. The STOP instruction can be executed only when the processor is operated by the main system clock.

Examples 1. The machine cycle is entered in highest-speed mode (2 μ s at f_{CC} = 2 MHz).

SEL MB15 MOV A,#0011B MOV PCC,A

- 2. The machine cycle is set to 8 μ s (at f_{CC} = 1 MHz). SEL MB15 MOV A,#0010B MOV PCC,A
- The STOP mode is set. (A STOP instruction or HALT instruction must always be followed by an NOP instruction.)
 STOP
 NOP

A $\overline{\text{RESET}}$ signal clears the PCC to 0.

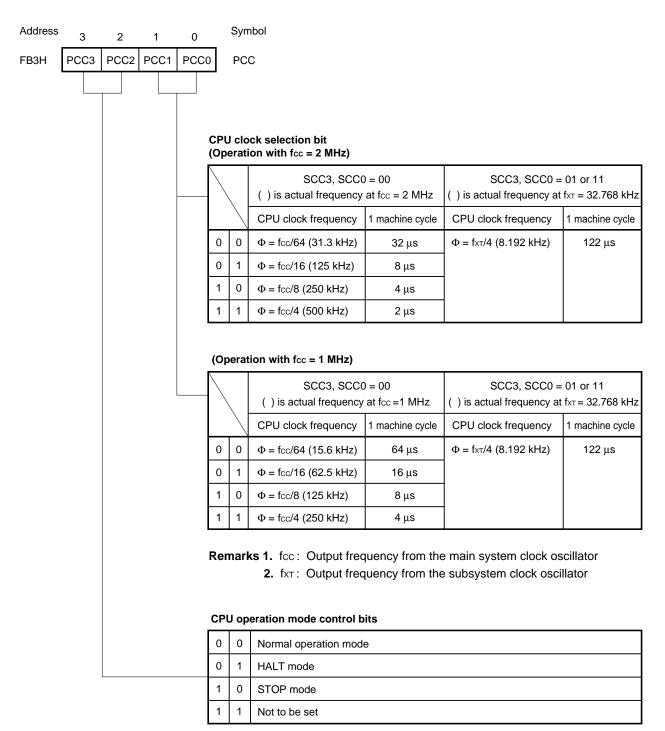


Figure 5-12. Format of the Processor Clock Control Register

(2) System clock control register (SCC)

The SCC is a 4-bit register for selecting CPU clock Φ with the least significant bit and for controlling the termination of main system clock generation with the most significant bit (see **Figure 5-13**).

Bits 0 and 3 of the SCC are located at the same data memory address, but both bits cannot be changed at the same time. Accordingly, bits 0 and 3 of the SCC are set using bit manipulation instructions. Bits 0 and 3 of the SCC can be manipulated regardless of MBE setting.

Main system clock generation can be terminated by setting bit 3 of the SCC only when the subsystem clock is used for operation. The STOP instruction must be used to terminate main system clock generation. A $\overrightarrow{\text{RESET}}$ signal clears the SCC to 0.

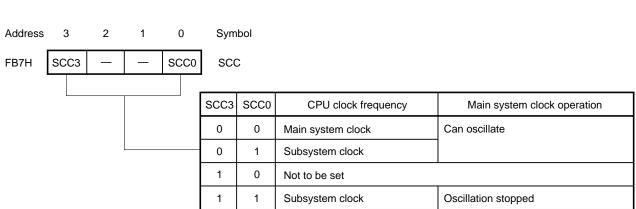


Figure 5-13. Format of the System Clock Control Register

- Cautions 1. A time period of up to 1/f_{XT} is needed to change the system clock. This means that to terminate main system clock generation, bit 3 of the SCC must be set to 1 when the machine cycles indicated in Table 5-4 or more have elapsed after the clock is switched from the main system clock to the subsystem clock.
 - 2. When the main system clock is used for operation, setting bit 3 of the SCC to stop clock generation does not enter the normal STOP mode.

(3) System clock oscillator

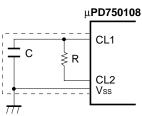
The main system clock oscillator operates with a resistor (R) and capacitor (C) connected to the CL1 and CL2 pins, as shown in Figure 5-14. The external clock cannot be input.

The output frequency (f_{CC}) of the main system clock oscillator is determined from the resistance (R) and capacitance (C), as follows:

 $f_{CC} = \frac{1}{2RC}$

Caution f_{CC} may be subject to a frequency deviation caused by a variation in the supply voltage or temperature.

Figure 5-14. External Circuit for the Main System Clock Oscillator



RC oscillation

The subsystem clock oscillator operates with a crystal resonator (32.768 kHz standard) connected to the XT1 and XT2 pins.

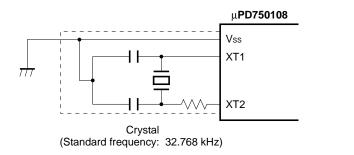
An external clock can also be input. Input the clock signal to the XT1 pin and its inverted signal to the XT2 pin.

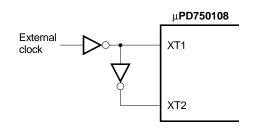
The state of the XT1 pin is tested by bit 3 of the clock mode register (WM).

Figure 5-15. External Circuit for the Subsystem Clock Oscillator

(a) Crystal oscillation

(b) External clock





- Caution When the main system clock or subsystem clock oscillator is used, conform to the following guidelines when wiring enclosed in broken lines of Figures 5-14 and 5-15 to eliminate the influence of the stray capacitance around the wiring.
 - The wiring must be as short as possible.
 - Other signal lines must not run in these areas.

Any line carrying a high pulsating current must be kept away as far as possible.

- The grounding point of the capacitor of the oscillator must have the same potential as that of V_{SS}. It must not be grounded to a grounding pattern carrying a high current.
- No signal must be taken directly from the resonator.

The subsystem clock oscillator has low amplification to minimize current consumption. For this reason, more malfunctions can occur due to noise than the main system clock oscillator. So pay special attention to wiring when using the subsystem clock.

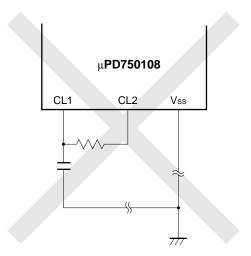
Figure 5-16 gives examples of oscillator connections which should be avoided.

Figure 5-16. Examples of Oscillator Connections Which Should Be Avoided (1/4)

(a) The wiring is too long.

Main system clock

Subsystem clock



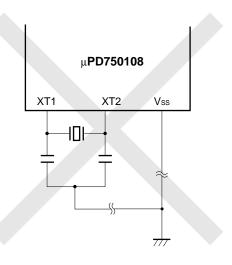
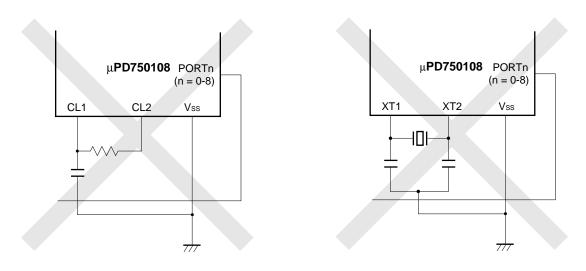


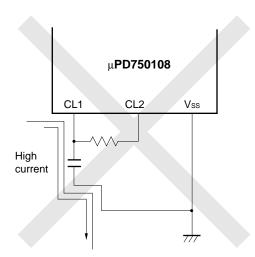
Figure 5-16. Examples of Oscillator Connections Which Should Be Avoided (2/4)

- (b) The signal lines cross.
 - Main system clock

• Subsystem clock



- (c) A high pulsating current is too close to the signal line.
 - Main system clock



Subsystem clock

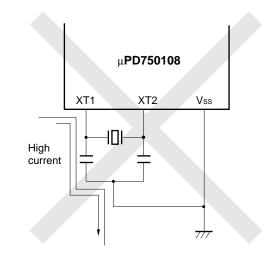
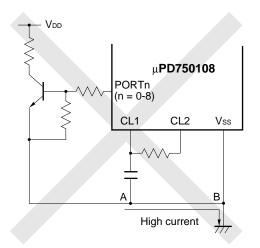
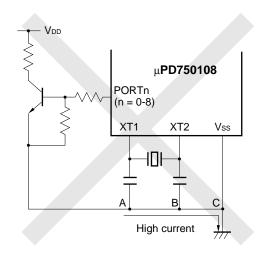


Figure 5-16. Examples of Oscillator Connections Which Should Be Avoided (3/4)

- (d) The current flows through the ground line of the oscillator. (The potential at points A, B, and C fluctuates.)
 - Main system clock

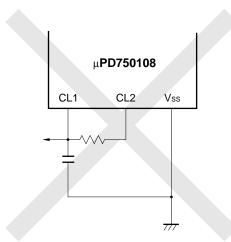
Subsystem clock





- (e) A signal is taken directly from the resonator.
 - Main system clock

Subsystem clock



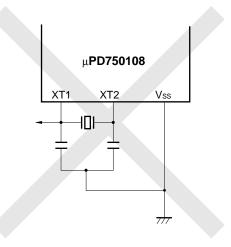
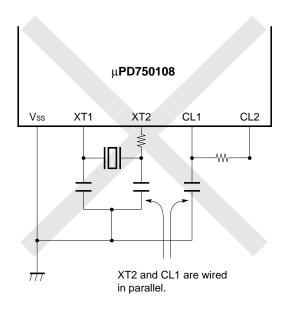


Figure 5-16. Examples of Oscillator Connections Which Should Be Avoided (4/4)

(f) The signal lines of the main system clock and subsystem clock are parallel and adjacent to each other.



(4) Frequency divider

The frequency divider divides the output (f_{CC}) of the main system clock oscillator to generate various clocks.

(5) Control functions of subsystem clock oscillator

The subsystem clock oscillator of the μ PD750108 subseries has two control functions to decrease the supply current.

- The function to select with the software whether to use the built-in feedback resistorNote
- The function to suppress the supply current by reducing the drive current of the built-in inverter when the operating supply voltage is high ($V_{DD} \ge 2.7 \text{ V}$)
- **Note** When the subsystem clock is not to be used, select SOS.0 = 1 by software (the built-in feedback resistor will not be used), connect the XT1 pin to V_{SS} or V_{DD} , and leave the XT2 pin open. This reduces the supply current to the subsystem clock oscillator.

Each function can be used by switching bits 0 and 1 in the sub-oscillator control register (SOS). (See **Figure 5-17**.)

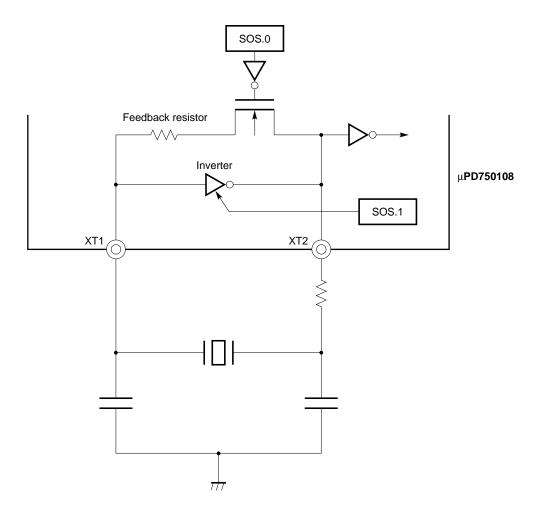


Figure 5-17. Subsystem Clock Oscillator

*

(6) Sub-oscillator control register (SOS)

The SOS register specifies whether to use the built-in feedback resistor and controls the drive current of the built-in inverter. (See **Figure 5-18**.)

Inputting a RESET signal clears all bits of the SOS register. The functions of each flag in the SOS register are described below.

(a) SOS.0 (feedback resistor cut flag)

To use the feedback resistor of the subsystem clock, the mask option setup and switching SOS.0 by software are required. Set SOS.0 to 0 to turn on the feedback circuit.

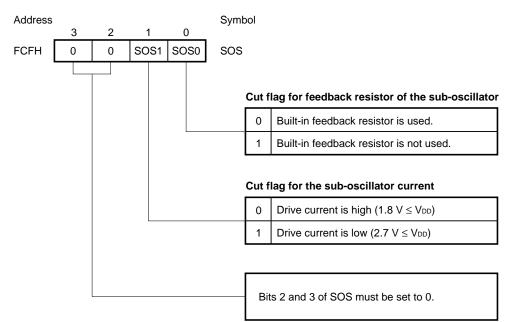
When the resonator is not used, set SOS.0 to 1. The feedback circuit is turned off, reducing the current drain.

To use the resonator, be sure to select "Enable the feedback resistor" upon setting the mask option. Then, set SOS.0 to 0 (feedback circuit is turned on).

(b) SOS.1 (drive capability switch flag)

The built-in inverter in the subsystem clock oscillator of the μ PD750108 subseries has a large drive current because it can be used at low supply voltage (V_{DD} = 1.8 V), so that the supply current becomes too high to use at high supply voltage (V_{DD} \ge 2.7 V). To reduce the supply current, set SOS.1 to 1 so as to reduce the drive current of the inverter.

However, if SOS.1 is set to 1 when V_{DD} is less than 2.7 V, the oscillation may stop for insufficient drive current. Set this flag to 0 when V_{DD} is less than 2.7 V.





Remark If the subsystem clock is not required, the XT1 and XT2 pins and SOS register must be treated as follows:

XT1 : Connected to V_{SS} or V_{DD} . XT2 : Open SOS: 00x1B (x: Don't care)

*

5.2.3 System Clock and CPU Clock Setting

(1) Time required to change the system clock and CPU clock

The system clock and CPU clock can be changed by using the least significant bit of the SCC and the low-order two bits of the PCC. This switching is not performed immediately after the contents of the registers are rewritten, but the system operates with the previous clock for some machine cycles. Accordingly, after this time period, the STOP instruction must be executed to terminate main system clock generation.

*

Table 5-5. Maximum Time Required to Change the System Clock and CPU Clock

	Setting before switching		Setting after switching														
SCC0	PCC1	PCC0	SCC0	PCC1	PCC0	SCC0	PCC1	PCC0	SCC0	PCC1	PCC0	SCC0	PCC1	PCC0	SCC0	PCC1	PCC0
			0	0	0	0	0	1	0	1	0	0	1	1	1	х	х
0	0	0				1 n cyc	nachine cle	9	1 n cyc	nachine cle	9	1 r cyd	nachin cle	e	cycles	lfxt mac s ichine c	
	0	1		machino cles	e					nachine cles	9		nachin cles	e	cycles	ofx⊤ mac s ^{Note} Ichine c	
	1	0		8 machine cycles		8 machine cycles						nachin cles	e	cycles	xt mach s chine cy		
	1	1		machii cles	ne		machir cles	ıe		machir les	ne				cycles	xt mach 3 achine (
1	x	x		machine cle	e		nachine cle ^{Note}	9	1 n cyc	nachine cle	9	1 r cyd	nachin cle	e			

Note Cannot be emulated using the tool.

- **Remarks 1.** Time indicated in parentheses is required when $f_{CC} = 2$ MHz and $f_{XT} = 32.768$ kHz.
 - 2. x: Don't care
 - **3.** CPU clock Φ is supplied to the CPU of the μ PD750108. The reciprocal of this frequency is a minimum instruction time (defined as one machine cycle in this manual).
- Caution The fluctuation of the ambient temperature around an oscillator and the performance of a load capacity change f_{CC} and f_{XT} . In particular, when f_{CC} is higher than the nominal value or f_{XT} is lower than the nominal value, the machine cycles calculated by $f_{CC}/64f_{XT}$, $f_{CC}/16f_{XT}$, $f_{CC}/8f_{XT}$, and $f_{CC}/4f_{XT}$ in Table 5-5 are longer than the machine cycle calculated by the nominal values of f_{CC} and f_{XT} . Therefore, the wait time required to change the system clock and CPU clock should be longer than the machine cycle calculated by the nominal values of f_{CC} and f_{XT} .

(2) Procedure for changing the system clock and CPU clock

The procedure for changing the system clock and CPU clock is explained using Figure 5-19.

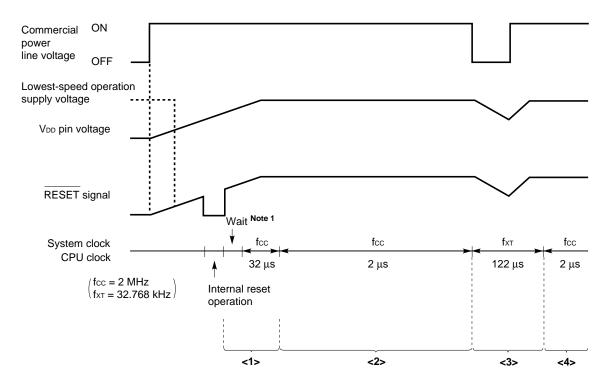


Figure 5-19. Changing the System Clock and CPU Clock

- <1> A RESET signal starts CPU operation at the lowest speed of the main system clock (32 μs at 2 MHz, 64 μs at 1 MHz) after a wait time^{Note 1} for stable oscillation.
- <2> The PCC is rewritten for highest-speed operation after a time elapse which is sufficient for the voltage on the V_{DD} pin to be high enough for highest-speed operation.
- <3> The removal of commercial current is detected using, for example, an interrupt input^{Note 2}, then bit 0 of the SCC is set to 1 to operate with the subsystem clock. (In this case, subsystem clock generation must have been started.) After a time (15 machine cycles) required to switch to the subsystem clock elapses, bit 3 of the SCC is set to 1 to terminate main system clock generation.
- <4> After detecting the input of commercial current by using an interrupt, bit 3 of the SCC is cleared to start main system clock generation. After a time required for stable generation, bit 0 of the SCC is cleared to 0 to operate at the highest speed.
- Notes 1. The wait time is fixed to 56/f_{CC} (28 μs at 2 MHz, 56 μs at 1 MHz)
 - 2. INT4 is useful.

5.2.4 Clock Output Circuit

(1) Configuration of the clock output circuit

Figure 5-20 shows the configuration of the clock output circuit.

(2) Functions of the clock output circuit

The clock output circuit outputs a clock pulse from the P22/PCL pin and is applicable to a remote control waveform output or can be used to supply clock pulses to peripheral LSI devices.

The procedure for outputting a clock pulse signal is as follows:

- (a) Select a clock output frequency, and disable clock output.
- (b) Write a 0 in the P22 output latch.
- (c) Set the output mode for port 2.
- (d) Enable clock output.

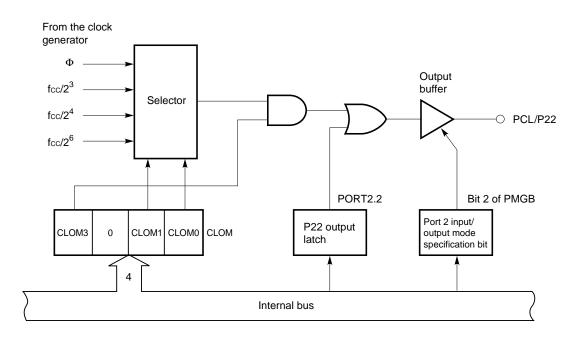


Figure 5-20. Configuration of the Clock Output Circuit

Remark The clock output circuit is designed so that pulses with short widths do not appear in enabling or disabling clock output.

(3) Clock output mode register (CLOM)

The CLOM is a 4-bit register to control clock output. The CLOM is set by a 4-bit memory manipulation instruction.

Example CPU clock Φ is output on the PCL/P22 pin.

SEL	MB15	; or CLR1 MBE
MOV	A,#1000B	
MOV	CLOM,A	

A RESET signal clears the CLOM to 0, disabling clock output.

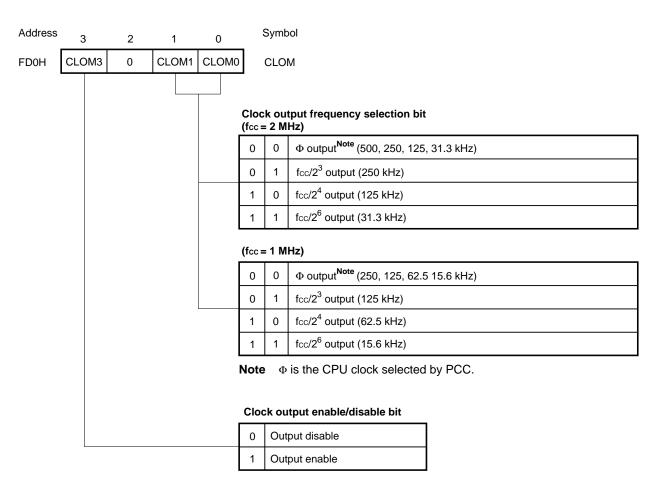


Figure 5-21. Format of the Clock Output Mode Register

Caution Be sure to write a 0 in bit 2 of the CLOM.

(4) Application to remote control waveform output

The clock output function of the μ PD750108 is applicable to remote control waveform output. The frequency of the carrier for remote control waveform output is selected by the clock frequency select bit of the clock output mode register. Pulse output is enabled or disabled by controlling the clock output enable/disable bit by software.

The clock output circuit is designed so that pulses with short widths do not appear in enabling or disabling clock output.

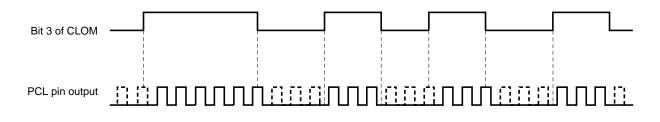


Figure 5-22. Application to Remote Control Waveform Output

5.3 BASIC INTERVAL TIMER/WATCHDOG TIMER

The µPD750108 contains an 8-bit basic interval timer/watchdog timer, which has the following functions:

- (a) Interval timer operation which generates a reference timer interrupt
- (b) Operation as a watchdog timer for detecting program crashes and resetting the CPU
- (c) Reading the count value

5.3.1 Configuration of the Basic Interval Timer/Watchdog Timer

Figure 5-23 shows the configuration of the basic interval timer/watchdog timer.

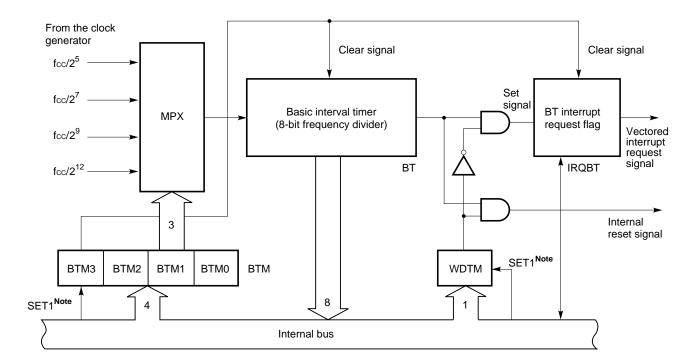


Figure 5-23. Block Diagram of the Basic Interval Timer/Watchdog Timer

Note Instruction execution

5.3.2 Basic Interval Timer Mode Register (BTM)

The BTM is a 4-bit register for controlling operation of the basic interval timer (BT).

A 4-bit memory manipulation instruction is used to set the BTM.

Bit 3 can be independently manipulated using a bit manipulation instruction.

Example The interrupt generation interval is set to 4.10 ms (at 2 MHz).

 SEL
 MB15
 ; or CLR1 MBE

 MOV
 A,#1111B

 MOV
 BTM,A
 ; BTM <- 1111B</td>

When bit 3 is set to 1, the BT is cleared, and the basic interval timer/watchdog timer interrupt request flag (IRQBT) is also cleared (to start the basic interval timer/watchdog timer).

A RESET signal clears the interval timer to 0, and the longest interrupt request signal generation interval time is set.

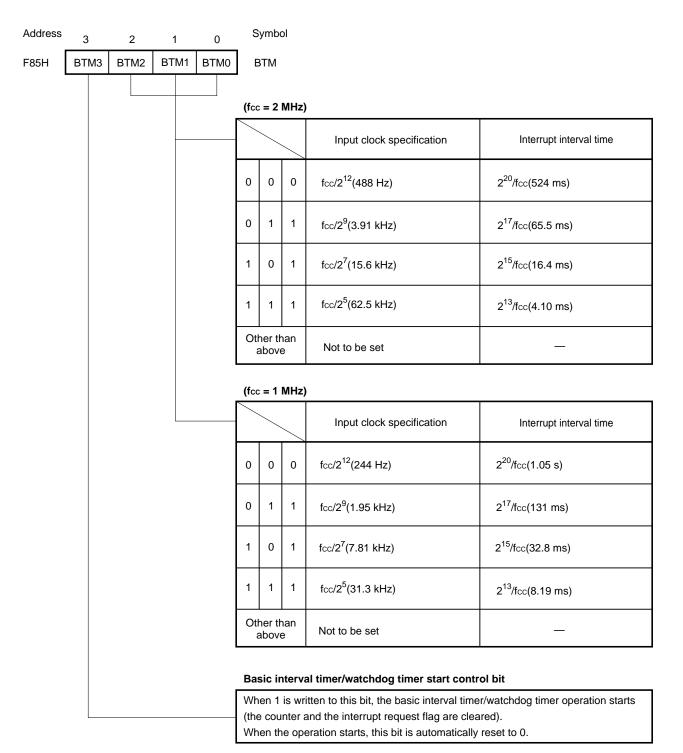


Figure 5-24. Format of the Basic Interval Timer Mode Register

5.3.3 Watchdog Timer Enable Flag (WDTM)

WDTM, when set, is a flag for enabling the generation of the reset signal when the basic interval timer overflows. WDTM is set by a bit manipulation instruction. It cannot be cleared by an instruction.

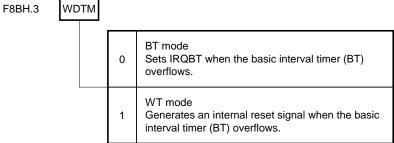
Example Set the watchdog timer function.

SEL	MB15	; or CLR1 MBE
SET1	WDTM	
	:	
	•	
SET1	BTM.3	; Set bit 3 of BTM to 1

The generation of a RESET signal clears WDTM to 0.



Figure 5-25. Format of the Watchdog Timer Enable Flag (WDTM)



5.3.4 Operation of the Basic Interval Timer

When WDTM is set to 0, the basic interval timer (BT) functions as an interval timer. An interrupt request flag (IRQBT) is set when the timer overflows. BT is constantly incremented by the clock supplied from the clock generator. So it is impossible to stop the timer from incrementing.

One of four interrupt generation intervals can be selected by setting BTM. (See Figure 5-24.)

BT and IRQBT can be cleared by setting bit 3 of BTM to 1 (instruction for starting as an interval timer). The count status of BT can be read by an 8-bit manipulation instruction. No data can be loaded to the timer. Perform the timer operation as follows (<1> and <2> can be performed with the same instruction):

<1> Set the interval in BTM.

<2> Set 1 in bit 3 of BTM.

Example Generate an interrupt at intervals of 4.10 ms (at 2 MHz).

SET1	MBE	
SEL	MB15	
MOV	A,#1111B	
MOV	BTM,A	; Set the interval and start processing
EI		; Enable interrupt
EI	IEBT	; Enable BT interrupt

5.3.5 Operation of the Watchdog Timer

When WDTM is set to 1, the basic interval timer/watchdog timer functions as a watchdog timer. An internal reset signal is generated when the basic interval timer (BT) overflows. No reset signal, however, is generated during the oscillation settling time following the STOP instruction has been released (WDTM cannot be cleared without using reset). BT is constantly incremented by the clock supplied from the clock generator. It cannot be stopped from counting.

In the watchdog timer mode, program crashes are detected using the intervals at which BT overflows. The interval can be selected from among four values depending on bits 2 to 0 of BTM (see **Figure 5-24**). Select an interval for detecting crashes according to the user system. A large program should be divided into modules each of which can be executed within the set interval. Include an instruction which clears BT at the end of each module. If execution does not reach the instruction which clears BT within the set interval (in which case a program error leading to a program crash may have occurred), BT overflows and an internal reset signal is generated to forcibly terminate the program. The occurrence of internal reset possibly means that a program crash has occurred. A crash can thus be detected.

Set the watchdog timer as follows (<1> and <2> can be performed with the same instruction):

- <1> Set the interval in BTM.
- <2> Set 1 in bit 3 of BTM. Initial settings

Initial s

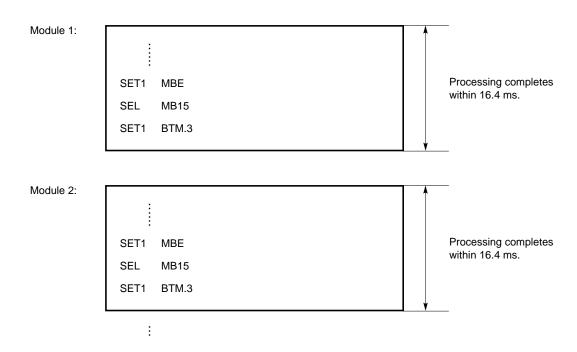
<3> Set 1 in WDTM.

<4> After <1> to <3> are set, set 1 in bit 3 of BTM within each interval.

Example Use the basic interval/watchdog timer as a watchdog timer with 16.4-ms interval (at 2 MHz) A program is divided into several modules each of which can be executed within the interval set in BTM (16.4 ms). BT is cleared at the end of each module. If a program crash occurs, BT overflows and an internal reset signal is generated because BT is not cleared within the set interval.

etting:	SET1	MBE	
	SEL	MB15	
	MOV	A, #1101B	
	MOV	BTM, A	; Specifies a time interval and
			; starts processing.
	SET1	WDTM	; Enables the watchdog timer.
	:		

(From now on, 1 is set in bit 3 of BTM at intervals of 16.4 ms.)



5.3.6 Other Functions

The basic interval timer/watchdog has the following functions regardless of whether it operates as a basic interval timer or watchdog timer:

• Reading the count

The count status of the basic interval timer (BT) can be read by using an 8-bit manipulation instruction. No data can be loaded to the timer.

Caution When reading the count value of BT, execute a read instruction twice so that unstable data which has been counted will not be read. If the two read values are reasonable, use the second one as the result. If the two read values are far apart, retry from the beginning.

Example Read the count value of BT.

	SET1	MBE	
	SEL	MB15	
	MOV	HL, #BT	; Set the BT address in HL
LOOP:	MOV	XA, @HL	; First read
	MOV	BC, XA	
	MOV	XA, @HL	; Second read
	SKE	XA, BC	
	BR	LOOP	

5.4 CLOCK TIMER

The μ PD750108 contains one clock timer, which has the following functions.

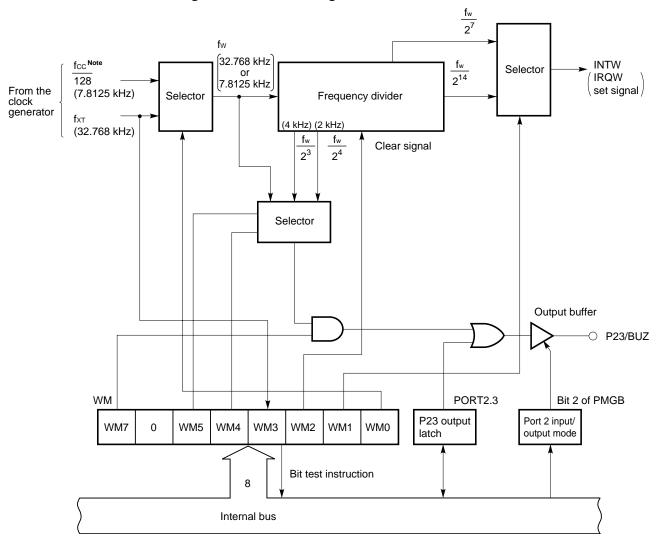
- (a) The clock timer sets the test flag (IRQW) every 0.5 seconds (when WM0 = 1). The IRQW can release the standby mode.
- (b) The subsystem clock (32.768 kHz) can be used to produce 0.5-second intervals.
- (c) The fast-forward mode produces an interval 128 times faster, which is useful for program debugging and testing.
- (d) An arbitrary frequency^{Note} can be output to the P23/BUZ pin, so that it can be used for sounding the buzzer and for system clock frequency trimming.
- (e) The clock can be started from zero seconds by clearing the frequency divider.

Note 0.977, 1.953, or 15.625 kHz (when the main system clock is running at 2 MHz) 0.488, 0.977, or 7.813 kHz (when the main system clock is running at 1 MHz) 2.048, 4.096, or 32.768 kHz (when the subsystem clock is running at 32.768 kHz)

Caution Set WM0 = 1 when using the clock function.

5.4.1 Configuration of the Clock Timer

Figure 5-26 shows the configuration of the clock timer.





Note When a frequency-divided main system clock is used, 32.768 kHz cannot be selected as the source clock.

Remark The values in parentheses are for $f_{CC} = 1$ MHz and $f_{XT} = 32.768$ kHz.

5.4.2 Clock Mode Register

The clock mode register (WM) is an 8-bit register which controls the clock timer. Figure 5-27 shows the format of the clock mode register.

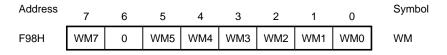
All bits except bit 3 of the clock mode register are controlled by an 8-bit manipulation instruction. Bit 3 is for testing the XT1 pin input level. The input level of the XT1 pin can be tested by bit test operation. No data can be written to this register.

When the RESET signal is generated, all bits except bit 3 of this register are cleared to 0.

Example Time is set using the subsystem clock (32.768 kHz), and buzzer output is enabled:

CLR1 MBE MOV XA, #85H MOV WM, XA ; Sets WM

Figure 5-27. Clock Mode Register Format



BUZ output enable/disable bit

WM7	0	Disables BUZ output
	1	Enables BUZ output

BUZ output frequency selection bit

WM5	WM4	BUZ output frequency
0	0	<u>fw</u> (2.048 kHz)
0	1	$\frac{f_W}{2^3}$ (4.096 kHz)
1	0	Not to be set
1	1	fw (32.768 kHz)

XT1 pin input level (bit test only)

WM3	0	Input to the XT1 pin is low level
	1	Input to the XT1 pin is high level

Clock operation enable/disable bit

WM2	0	Disables clock operation (clears the frequency dividing circuit)
	1	Enables clock operation

Operation mode selection bit

WM1	0	Normal clock mode ($\frac{f_W}{2^{14}}$: sets IRQW at 0.5 s)
	1	Advanced clock mode ($\frac{f_W}{2^7}$: sets IRQW at 3.91 ms)

Count clock (fw) selection bit

WMO	0	Selects divided system clock output: $\frac{f_{CC}}{128}$
	1	Selects subsystem clock: fxt

Remark () for $f_W = 32.768 \text{ kHz}$

5.5 TIMER/EVENT COUNTER

The μPD750108 has one timer/event counter channel (channel 0) and one timer counter channel (channel 1). Figures 5-28 and 5-29 show the configuration of these channels.

In this section, the timer/event counter and timer counters are referred to as "timer/event counters." When you read this section for description of channel 1, take "timer/event counter" as "timer counter."

The timer/event counter has the following functions.

- (a) Programmable interval timer operation
- (b) Square wave output of any frequency to the PTOn pin (n = 0, 1)
- (c) Event counter operation (Channel 0 only)
- (d) Divides the frequency of signal input via the TI0 pin to 1-Nth of the original signal and outputs the divided frequency to the PTO0 pin (frequency divider operation) (Channel 0 only).
- (e) Supplies the shift clock to the serial interface circuit (Channel 0 only).
- (f) Read function for the count value

5.5.1 Configuration of Timer/Event Counter

Figures 5-28 and 5-29 shows the configuration of the timer/event counter.

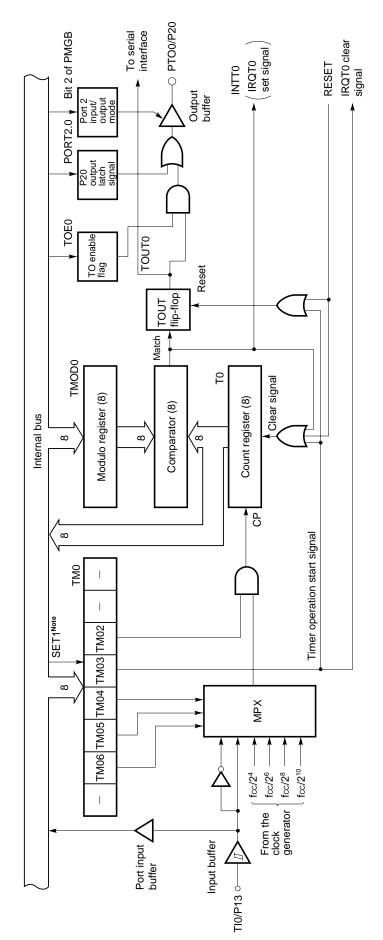
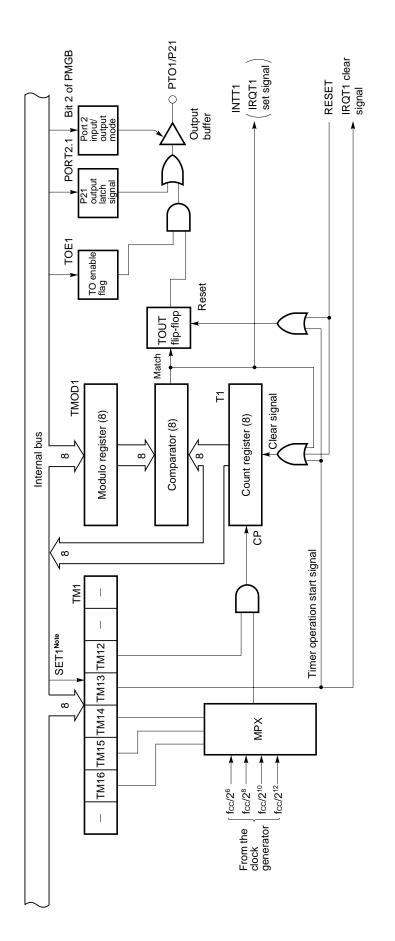




Figure 5-28. Block Diagram of the Timer/Event Counter (Channel 0)





Note Execution of the instruction

(1) Timer/event counter mode register (TM0, TM1)

The timer/event counter mode register (TM0, TM1) is an 8-bit register which controls the timer/event counter.

Its format is shown in Figures 5-30 and 5-31.

The timer/event counter mode register is set by an 8-bit memory manipulation instruction.

Bit 3 is a timer start bit and can be operated bit-wise. It is automatically reset to 0 when the timer operation starts.

All the bits of the timer/event counter mode register are cleared to 0 by a RESET signal generation.

Examples 1. Start the timer in the interval timer mode of CP = 1.95 kHz (during 2 MHz operation).

SEL	MB15	; or CLR1 MBE
MOV	XA, #01001100B	
MOV	TMn, XA	; TMn <- 4CH

2. Restart the timer according to the setting of the timer/event counter mode register.

SEL	MB15	; or CLR1 MBE
SET1	TMn.3	; TMn.bit3 <- 1 (n = 0, 1)

Figure 5-30. Timer/Event Counter Mode Register (Channel 0) Format

Address	7	6	5	4	3	2	1	0	Symbol
FA0H	-	TM06	TM05	TM04	TM03	TM02	_	-	TM0

Count pulse (CP) selection bit

When fcc = 2 MHz

TM06	TM05	TM04	Count pulse (CP)
0	0	0	TI0 rising edge
0	0	1	TI0 falling edge
1	0	0	fcc/2 ¹⁰ (1.95 kHz)
1	0	1	fcc/2 ⁸ (7.81 kHz)
1	1	0	fcc/2 ⁶ (31.3 kHz)
1	1	1	fcc/2 ⁴ (125 kHz)
Othe	Other than above		Not to be set

When fcc = 1 MHz

TM06	TM05	TM04	Count pulse (CP)			
0	0	0	TI0 rising edge			
0	0	1	TI0 falling edge			
1	0	0	fcc/2 ¹⁰ (977 Hz)			
1	0	1	fcc/2 ⁸ (3.91 kHz)			
1	1	0	fcc/2 ⁶ (15.6 kHz)			
1	1	1	fcc/2 ⁴ (62.5 kHz)			
Other than above		bove	Not to be set			

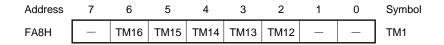
Timer start indication bit

TM03	When 1 is written into the bit, the counter and IRQT0 flag are cleared.
	If bit 2 is set to 1, count operation is started.

Operation mode

TM02	Count operation
0	Stop (retention of count contents)
1	Count operation

Figure 5-31. Timer Counter Mode Register (Channel 1) Format



Count pulse (CP) select bit

When fcc = 2 MHz

TM16	TM15	TM14	Count pulse (CP)
0	0	0	Rising edge of INTW (overflow output for clock timer)
1	0	0	fcc/2 ¹² (488 Hz)
1	0	1	fcc/2 ¹⁰ (1.95 kHz)
1	1	0	fcc/2 ⁸ (7.81 kHz)
1	1	1	fcc/2 ⁶ (31.3 kHz)
Othe	Other than above		Not to be set

When fcc = 1 MHz

TM16	TM15	TM14	Count pulse (CP)
0	0	0	Rising edge of INTW (overflow output for clock timer)
1	0	0	fcc/2 ¹² (244 Hz)
1	0	1	fcc/2 ¹⁰ (977 Hz)
1	1	0	fcc/2 ⁸ (3.91 kHz)
1	1	1	fcc/2 ⁶ (15.6 kHz)
Othe	Other than above		Not to be set

Timer start indication bit

TM13	When 1 is written into the bit, the counter and IRQT1 flag are cleared.
	If bit 2 is set to 1, count operation is started.

Operation mode

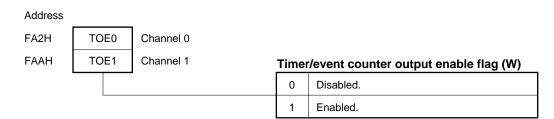
TM12	Count operation
0	Stop (retention of count contents)
1	Count operation

(2) Timer/event counter output enable flag (TOE0, TOE1)

The timer/event counter output enable flag (TOE0, TOE1) controls the output enable/disable to the PTO0 and PTO1 pins in the timer out flip-flop (TOUT flip-flop) status.

The timer out flip-flop is inverted by the match signal sent from the comparator. When bit 3 of the timer/ event counter mode register (TM0, TM1) is set to 1, the timer out flip-flop is cleared to 0. TOE0, TOE1, and timer out flip-flop are cleared to 0 by a RESET signal generation.

Figure 5-32. Timer/Event Counter Output Enable Flag Format



5.5.2 8-Bit Timer/Event Counter Mode Operation

It is used as an 8-bit timer/event counter in this mode. It performs an 8-bit programmable interval timer and event counter operation (channel 0 only).

(1) Register setting

The following three registers and one flag are used in the 8-bit timer/event counter mode.

- Timer/event counter mode register (TMn)
- Timer/event counter count register (Tn)
- Timer/event counter modulo register (TMODn)
- Timer/event counter output enable flag (TOEn)

(a) Timer/event counter mode register (TMn)

When the 8-bit timer/event counter mode is used, TMn must be set as shown in Figure 5-33 (For the format of the TMn, see Figures 5-30 and 5-31).

The TMn is manipulated by an 8-bit manipulation instruction. Bit 3 is a timer start indication bit and can be manipulated bit-wise and is automatically cleared to 0 when the timer starts.

The TMn is cleared to 00H when an internal reset signal is generated.

Remark n = 0, 1

Figure 5-33. Timer/Event Counter Mode Register Setup (1/2)

(a) In the case of timer/event counter (channel 0)

Address	7	6	5	4	3	2	1	0	Symbol
FA0H	_	TM06	TM05	TM04	ТМ03	TM02	—	—	тмо

Count pulse (CP) selection bit

TM06	TM05	TM04	Count pulse (CP)			
0	0	0	TI0 rising edge			
0	0	1	TI0 falling edge			
1	0	0	fcc/2 ¹⁰			
1	0	1	fcc/2 ⁸			
1	1	0	fcc/2 ⁶			
1	1	1	fcc/2 ⁴			
Othe	Other than above		Not to be set			

Timer start indication bit

TM03	When 1 is written into the bit, the counter and IRQT0 flag are cleared.
	If bit 2 is set to 1, count operation is started.

Operation mode

TM02	Count operation				
0	Stop (retention of count contents)				
1	Count operation				

Figure 5-33. Timer/Event Counter Mode Register Setup (2/2)

Address	7	6	5	4	3	2	1	0	Symbol
FA8H		TM16	TM15	TM14	TM13	TM12		_	TM1

(b) In the case of timer counter (channel 1)

Count pulse (CP) selection bit

TM16	TM15	TM14	Count pulse (CP)			
0	0	0	Rising edge of INTW (overflow output for clock timer)			
1	0	0	fcc/2 ¹²			
1	0	1	fcc/2 ¹⁰			
1	1	0	fcc/2 ⁸			
1	1	1	fcc/2 ⁶			
Other than above		oove	Not to be set			

Timer start indication bit

TM13	When 1 is written to the bit, the counter and IRQT1 flag are cleared.
	If bit 2 is set to 1, count operation is started.

Operation mode

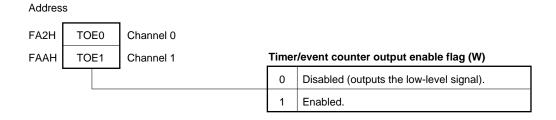
TM12	Count operation				
0	Stop (retention of count contents)				
1	Count operation				

(b) Timer/event counter output enable flag (TOEn)

The TOEn is manipulated by a bit manipulation instruction.

The TOEn is cleared to 0 by an internal reset signal.

Figure 5-34. Timer/Event Counter Output Enable Flag Setup



(2) Timer/event counter time setting

[Timer setup time] (cycle) is found by dividing [modulo register contents + 1] by [count pulse (CP) frequency] selected by setting the mode register.

T (sec) =
$$\frac{n+1}{f_{CP}}$$
 = (n + 1) · (resolution)

T (sec) : Timer setup time (seconds)

f_{CP} (Hz) : Count pulse frequency (Hz)

n : Modulo register content (n \neq 0)

Once the timer is set, interrupt request signal (IRQT0, IRQT1) is generated at the intervals set in the timer. Table 5-6 lists the resolution and longest setup time (time when FFH is set in the modulo register) for each count pulse to the timer/event counter.

Table 5-6. Resolution and Longest Setup Time

Mode register			Д	at 2 MHz	At 1 MHz		
TM06	TM05	TM04	Resolution	Longest setup time	Resolution	Longest setup time	
1	0	0	512 μs	131 ms	1024 μs	262 ms	
1	0	1	128 μs	32.8 ms	256 μs	65.5 ms	
1	1	0	32 µs	8.19 ms	64 μs	16.4 ms	
1	1	1	8 µs	2.05 ms	16 μs	4.10 ms	

(a) When timer/event counter (channel 0)

(b) When timer counter (channel 1)

Mode register			Ą	at 2 MHz	At 1 MHz		
TM16	TM15	TM14	Resolution	Longest setup time	Resolution	Longest setup time	
1	0	0	2048 μs	524 ms	4096 µs	1049 ms	
1	0	1	512 μs	131 ms	1024 μs	262 ms	
1	1	0	128 μs	32.8 ms	256 µs	65.5 ms	
1	1	1	32 µs	8.19 ms	64 μs	16.4 ms	

(3) Timer/event counter operation

The timer/event counter operates as follows. Figure 5-35 shows the configuration of the timer/event counter.

- <1> The count pulse (CP) is selected by setting the timer/event counter mode register (TMn) and is input to the timer/event counter count register (Tn).
- <2> The Tn is compared with the timer/event counter modulo register (TMODn), and if they are equal, a match signal is generated and the interrupt request flag (IRQTn) is set. At the same time, the timer out flip-flop (TOUT flip-flop) is inverted.

Figure 5-36 is a timing chart of the timer/event counter. The timer/event counter normally begins operation in the following procedure.

<1> Set a count in the TMODn.

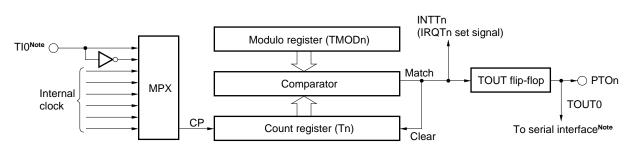
<2> Set the operating mode, count pulse, and start indication in the TMn.

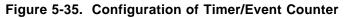
Caution Set a value other than 00H in the modulo register (TMODn).

When using the timer/event counter output pin (PTOn), set the dual function pin P2n as follows.

- <1> Clear the output latch of P2n.
- <2> Set port 2 to the output mode.
- **<3>** Make a status wherein the internal pull-up resistor is not connected in port 2.
- <4> Set the timer/event counter output enable flag (TOEn) to 1.

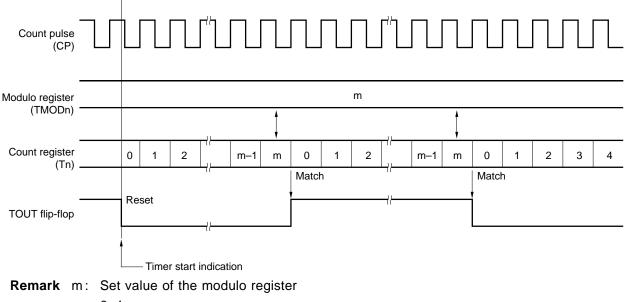
Remark n = 0, 1





Note Channel 0 of the timer/event counter only.





n: 0, 1

(4) Applications of the timer/event counter

(a) Timer/event counter is used as an interval timer that generates interrupts at intervals of 30 ms.

- The high-order four bits of the timer/event counter mode register are set to 0100B to select maximum set time 131 ms (at 2 MHz).
- The low-order four bits of the timer/event counter mode register are set to 1100B.
- The timer/event counter modulo register is set to the following value: 30 ms/512 μs = 58.6 $\,\rightleftharpoons\,$ 3BH

<Sample program>

SEL	MB15	
MOV	XA,#3BH	
MOV	TMOD0,XA	; Set the modulo register
MOV	XA,#01001100B	
MOV	TM0,XA	; Set the mode register and start the timer
EI		; Enable an interrupt
EI	IET0	; Enable a timer interrupt

Remark In this application, the TIO pin can be used as an input pin.

(b) An interrupt is caused when the number of pulses (active high) applied to the TI0 pin reaches 100.

- The high-order four bits of the timer/event counter mode register are set to 0000 to select the rising edge.
- The low-order four bits of the timer/event counter mode register are set to 1100B.
- The timer/event counter modulo register is set to 99 = 100 1.

<Sample program>

SEL	MB15	
MOV	XA,#100 – 1	
MOV	TMOD0,XA	; Set the modulo register
MOV	XA,#00001100B	
MOV	TM0,XA	; Set the mode register
EI		
EI	IET0	; Enable INTT0

5.5.3 Notes on Timer/Event Counter Applications

(1) Time error at the start of the timer

A maximum error of one count pulse (CP) cycle from a value calculated according to **Section 5.5.2 (2)** occurs in a time period from the start of the timer (bit 3 of the TM0 is set) to the generation of a match signal. This is because the count register T0 is cleared not in phase with the CP as shown in Figure 5-37.

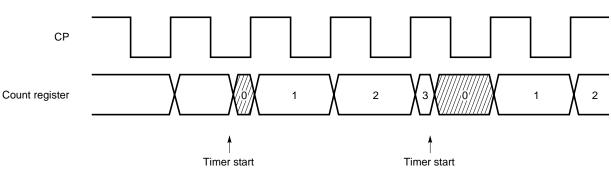


Figure 5-37. Error at the Start of the Timer

(2) Notes on the start of the timer

Usually, when the timer is started (bit 3 of the TM0 is set), the count register T0 and the interrupt request flag (IRQT0) are cleared. However, when the timer is placed in the operation mode, and the setting of IRQT0 and the start of the timer occur at the same time, IRQT0 may not be cleared. This causes no problem if IRQT0 is used for a vectored interrupt. However, if IRQT0 is being tested, a problem arises because IRQT0 is set even if the timer is started. Accordingly, in a situation where the timer is started on such timing that IRQT0 may be set, the timer must be restarted after it is once stopped (bit 2 of the TM0 is cleared to 0), or timer start operation must be performed twice.

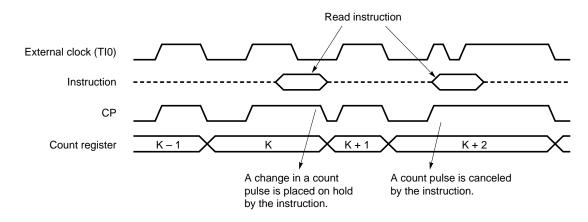
Example The timer is started on such timing that IRQT0 may be set.

SEL	MB15	
MOV	XA,#0	
MOV	TM0,XA	; Stop the timer
MOV	XA,#4CH	
MOV	TM0,XA	; Restart
or		
SEL	MB15	
SET1	TM0.3	
SET1	TM0.3	; Restart

(3) Error in reading the count register

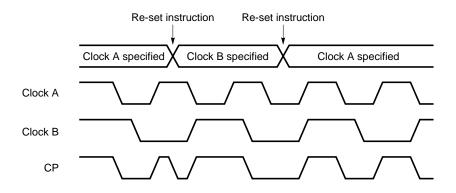
The contents of the count register can be read using an 8-bit data memory manipulation instruction at any time. During operation by such an instruction, all count pulse changes are held not to change the count register. This means that if the count pulse signal source is applied to the TI0 input, as many count pulses as corresponding to the time required to execute the instruction are cut. (When an internal clock is used for the count pulse signal, this problem does not occur because of synchronization with the instruction.)

Accordingly, in an attempt to read the contents of the count register with a count pulse signal applied to TI0, the signal must have a pulse wide enough to avoid incorrect counting even if count pulses are cut. That is, the contents of the count register are held by a read instruction for one machine cycle, so that a signal applied to the TI0 pin must have a pulse wider than that.

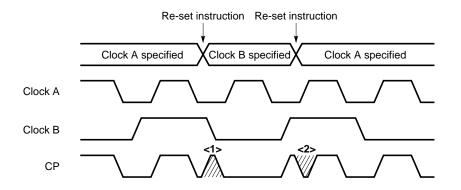


(4) Notes on changing the count pulse

When the count pulse is changed by rewriting the contents of the timer/event counter mode register, this takes effect immediately after the rewrite instruction is executed.

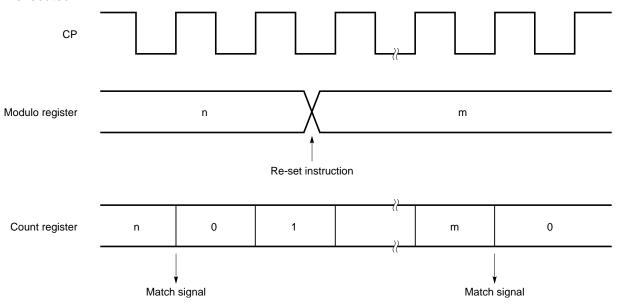


A combination of clocks used for changing count pulse signals can generate a spike (<1> or <2>) count pulse as shown in the figure below. In this case, an incorrect count operation may occur, or the contents of the count register may be destroyed. So when the count pulse is changed, bit 3 of the timer/event counter mode register must be set to 1, and the timer must be restarted at the same time.

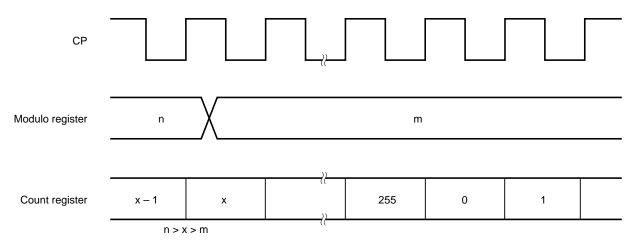


(5) Operation after the modulo register is changed

The contents of the modulo register are changed when an 8-bit data memory manipulation instruction is executed.



If the new value of the modulo register is less than the value of the count register, the count register continues count operation until it overflows, then it restarts count operation from 0. Accordingly, if the new value (m) of the modulo register is less than the value (n) before it is changed, the timer must be restarted after the contents of the modulo register are changed.



5.6 SERIAL INTERFACE

5.6.1 Serial Interface Functions

The μ PD750108 contains a clock synchronous 8-bit serial interface, which has four modes. The functions of the four modes are outlined below.

(1) Operation halt mode

This mode is used when serial transfer is not performed. This mode reduces power consumption.

(2) Three-wire serial I/O mode

In this mode, 8-bit data is transferred through three lines: Serial clock (\overline{SCK}), serial output (SO), and serial input (SI).

The three-wire serial I/O mode allows full-duplex transmission, so data transfer can be performed at higher speed.

The user can choose 8-bit data transfer starting with the MSB or LSB, so devices starting with either the MSB or LSB can be connected.

The three-wire serial I/O mode enables connections to be made with the 75XL series, 78K series, and many other types of peripheral I/O devices.

(3) Two-wire serial I/O mode

In this mode, 8-bit data is transferred through two lines: Serial clock (\overline{SCK}) and serial data bus (SB0 or SB1). By controlling output levels on the two lines by software, communication with multiple devices is enabled.

The output levels of \overline{SCK} and SB0 (or SB1) can be controlled by software, so the user can match an arbitrary transfer format. This means that a line that has been required for handshaking to connect multiple lines can be eliminated for more efficient input/output port utilization.

(4) Serial bus interface (SBI) mode

In this mode, communication with multiple devices can be performed using two lines: Serial clock (SCK) and serial data bus (SB0 or SB1).

This mode conforms to the NEC serial bus format.

In this mode, the transmitter can output, on the serial data bus, an address for selecting a device subject to serial communication, commands directed to the remote device, and data.

The receiver can identify an address, commands, and data from received data by hardware. This function enables more efficient input/output port utilization as in the case of the two-wire serial I/O mode. In addition, this function can simplify the serial interface control portion of an application program.

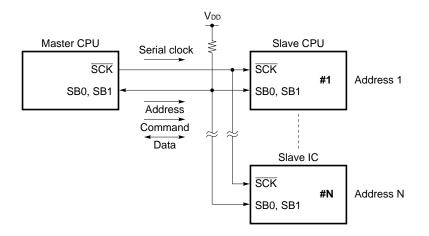


Figure 5-38. Example of the SBI System Configuration

5.6.2 Configuration of Serial Interface

Figure 5-39 shows the block diagram of the serial interface.

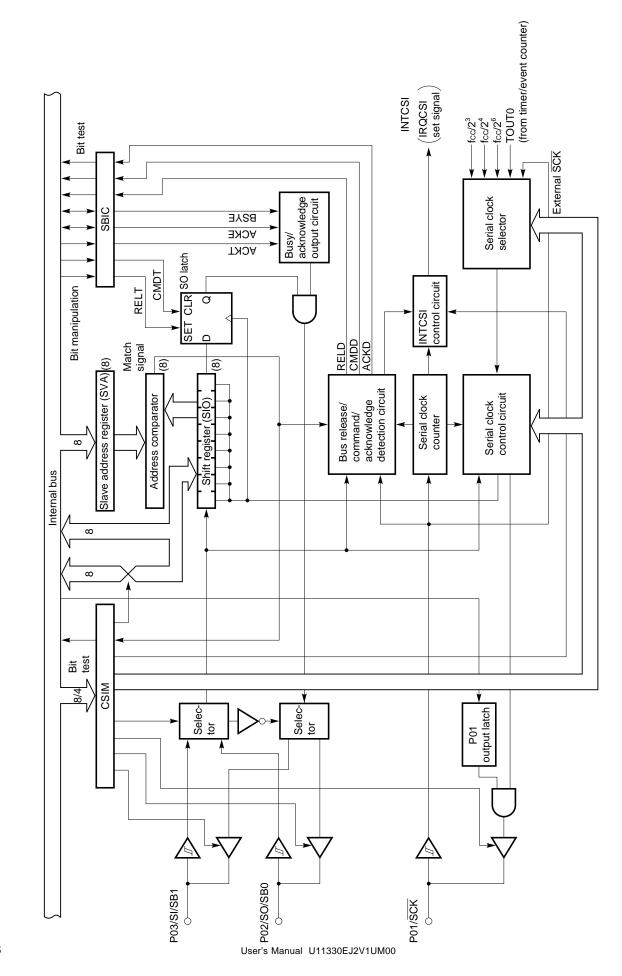


Figure 5-39. Block Diagram of the Serial Interface

(1) Serial operation mode register 0 (CSIM)

CSIM is an 8-bit register which specifies a serial interface operation mode, serial clock, wake-up function, and so forth. (See (1) in Section 5.6.3 for details.)

(2) Serial bus interface control register (SBIC)

SBIC is an 8-bit register consisting of bits for controlling the serial bus and flags for indicating the states of input data from the serial bus. SBIC is used mainly in the SBI mode. (See (2) in Section 5.6.3 for details.)

(3) Shift register (SIO)

SIO is an 8-bit register which converts 8-bit serial data to parallel data, and 8-bit parallel data to serial data. SIO performs transfer (shift) in phase with the serial clock. Transfers operations are controlled by writing data to SIO. (See (3) in Section 5.6.3 for details.)

(4) SO latch

SO is a latch to hold the levels of pins SO and SB0, or SI and SB1, which can be controlled directly by software. In the SBI mode, SO is set when the eighth clock of \overline{SCK} has been output. (See (2) in Section 5.6.3 for details.)

(5) Serial clock selector

The serial clock selector selects the serial clock to be used.

(6) Serial clock counter

The serial clock counter counts the serial clock to be output or input during transfer, and checks whether 8-bit data has been transferred.

(7) Slave address register (SVA) and address comparator

• In the SBI mode

SVA is used when the μ PD750108 is used as a slave device. A slave sets the number assigned to it (slave address) in SVA. The master outputs a slave address to select a particular slave. Two data values (a slave address output from the master and the value of SVA) are compared with each other by the address comparator. If a match is found, the slave is selected.

In the two-wire serial I/O mode or SBI mode
 SVA detects an error when data is transferred with the μPD750108 operating as the master or a slave.
 (See (4) in Section 5.6.3 for details.)

(8) INTCSI control circuit

The INTCSI control circuit controls interrupt request processing. The circuit issues an interrupt request (INTCSI), and set an interrupt request flag (IRQCSI) in the following cases. (See **Figure 6-1**.)

• In the three-wire or two-wire serial I/O mode

An interrupt request is issued whenever eight serial clocks are counted.

In the SBI mode

When WUP7**Note** = 0, an interrupt request is issued whenever eight serial clocks are counted. When WUP = 1, an interrupt request is issued when values of SVA and SIO match after an address is received.

Note WUP: Wake-up function specification bit (bit 5 of CSIM)

(9) Serial clock control circuit

The serial clock control circuit controls the serial clock to be supplied to the shift register, or controls the clock to be output to the \overline{SCK} pin when the internal system clock is used.

(10) Busy/acknowledge output circuit and bus release/command/acknowledge detection circuit

The busy/acknowledge output circuit and bus release/command/acknowledge detection circuit output and detect control signals generated in the SBI mode.

These circuits do not operate in the three-wire or two-wire serial I/O mode.

(11) P01 output latch

The P01 output latch generates serial clock by software after the eighth serial clock has been output. When the $\overrightarrow{\text{RESET}}$ signal is entered, this latch is set to 1.

To select the internal system clock as the serial clock, set the P01 output latch to 1.

5.6.3 Register Functions

(1) Serial operation mode register (CSIM)

Figure 5-40 shows the format of serial operation mode register (CSIM).

CSIM is an 8-bit register which specifies a serial interface operation mode, serial clock, wake-up function, and so forth.

CSIM is manipulated using an 8-bit memory manipulation instruction. The higher three bits can be manipulated bit by bit. Each bit can be manipulated using its name.

Each bit may or may not allow read and/or write operation (see **Figure 5-40**). Bit 6 allows bit test operation only; any data written to this bit is invalid.

When the RESET signal is generated, all bits are cleared to 0.

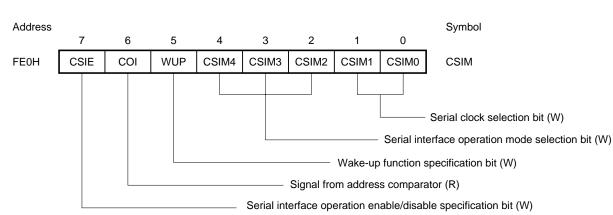


Figure 5-40. Format of Serial Operation Mode Register (CSIM) (1/4)

Remarks 1. (R): Read only 2. (W): Write only

Figure 5-40. Format of Serial Operation Mode Register (CSIM) (2/4)

Serial interface operation enable/disable specification bit (W)

		Shift register operation	Serial clock counter	IRQCSI flag	SO/SB0 and SI/SB1 pins
CSIE	0	Shift operation disabled	Cleared	Held	Used only for port 0
	1	Shift operation enabled	Count operation	Can be set.	Used in each mode as well as for port 0

Signal from address comparator (R)

COINote	Condition for being cleared (COI = 0)	Condition for being set (COI = 1)
	When the data in the slave address register (SVA) does not match the data in the shift register	When the data in the slave address register (SVA) matches the data in the shift register

Note COI can be read only before serial transfer is started or after serial transfer is completed. An undefined value may result during transfer.

COI data written by an 8-bit manipulation instruction is ignored.

Wake-up function specification bit (W)

WUP	0	Sets IRQCSI each time serial transfer is completed in each mode.
	1	Used in the SBI mode only to set IRQCSI only when an address received after bus release matches the data in the slave address register (wake-up state). SB0 or SB1 goes to high-impedance state.

Caution When WUP = 1 is set during BUSY signal output, BUSY is not released. In the SBI mode, the BUSY signal is output until the next falling edge of the serial clock (SCK) appears after release of BUSY is directed. Before setting WUP = 1, be sure to confirm that pin SB0 (or SB1) is high after releasing BUSY.

Figure 5-40. Format of Serial Operation Mode Register (CSIM) (3/4)

Serial interface operation mode selection bit (W)

CSIM4	CSIM3	CSIM2	Operation mode	Bit order of shift register	P02/SO/SB0 pin function	P03/SI/SB1 pin function
x	0	0	3-wire serial I/O mode	SIO ₇₋₀ <—> XA (Transfer starting with MSB)	SO (CMOS output)	SI (CMOS input)
		1		SIO ₀₋₇ <—> XA (Transfer starting with LSB)		
0	1	0	SBI mode	SIO ₇₋₀ <—> XA (Transfer starting with MSB)	SB0 (N-ch open-drain I/O)	P03 (CMOS input)
1					P02 (CMOS input)	SB1 (N-ch open-drain I/O)
0	1	1	2-wire serial	SIO ₇₋₀ <—> XA (Transfer starting	SB0 (N-ch open-drain I/O)	P03 (CMOS input)
1			I/O mode	with MSB)	P02 (CMOS input)	SB1
						(N-ch open-drain I/O)

Remark x: Don't care

Serial clock selection bit (W)

			SCK pin mode		
001111	COMIO	3-wire serial I/O mode	SBI mode	2-wire serial I/O mode	SCK pin mode
0	0	Input clock externally app	Input		
0	1	Timer/event counter output (TOUT0)			Output
1	0	f _{CC} /2 ⁴ (125 kHz: during 2-M 62.5 kHz: during 1-M		f _{CC} /2 ⁶ (31.3 kHz: during 2-MHz	
1	1	f _{CC} /2 ³ (250 kHz: during 2-MHz operation, 125 kHz: during 1-MHz operation)		operation, 15.6 kHz: during 1-MHz operation)	

Remarks 1. Each mode can be selected using CSIE, CSIM3, and CSIM2.

CSIE	CSIM3	CSIM2	Operation mode
0	х	х	Operation halt mode
1	0	х	Three-wire serial I/O mode
1	1	0	SBI mode
1	1	1	Two-wire serial I/O mode

Figure 5-40. Format of Serial Operation Mode Register (CSIM) (4/4)

Remarks 2. The P01/SCK pin assumes any of the following states according to the state of CSIE, CSIM1, and CSIM0:

CSIE	CSIM1	CSIM0	P01/SCK pin state
0	0	0	Input port (P01)
1	0	0	High impedance (SCK input)
0	0	1	High level output
0	1	0	
0	1	1	
1	0	1	Serial clock output (High level output:
1	1	0	Upon completion of serial transfer)
1	1	1	

- 3. When clearing CSIE during serial transfer, use the following procedure:
 - <1> Disable interrupts by clearing the interrupt enable flag (IECSI).
 - <2> Clear CSIE.
 - <3> Clear the interrupt request flag (IRQCSI).
 - **Examples 1.** f_{CC}/2⁴ is selected as the serial clock, serial interrupt IRQCSI, is generated each time serial transfer is completed, and serial transfer is performed in the SBI mode with the SB0 pin used as the serial data bus.
 - SEL
 MB15
 ; or CLR1
 MBE

 MOV
 XA,#10001010B
 ;
 CSIM,XA
 ;
 CSIM <- 10001010B</td>
 - 2. Serial transfer dependent on the contents of CSIM is enabled.
 - SEL MB15 ; or CLR1 MBE
 - SET1 CSIE

(2) Serial bus interface control register (SBIC)

Figure 5-41 shows the format of the serial bus interface control register (SBIC).

SBIC is an 8-bit register consisting of bits for controlling the serial bus and flags for indicating the states of input data from the serial bus. SBIC is used mainly in the SBI mode.

SBIC is manipulated using a bit manipulation instruction. SBIC cannot be manipulated using a 4-bit or 8-bit memory manipulation instruction.

Each bit may or may not allow read and/or write operation (Figure 5-41).

When the RESET signal is generated, all bits are cleared to 0.

Caution Only the following bits can be used in the three-wire and two-wire serial I/O modes:

- Bus release trigger bit (RELT): Sets the SO latch.
- Command trigger bit (CMDT): Clears the SO latch

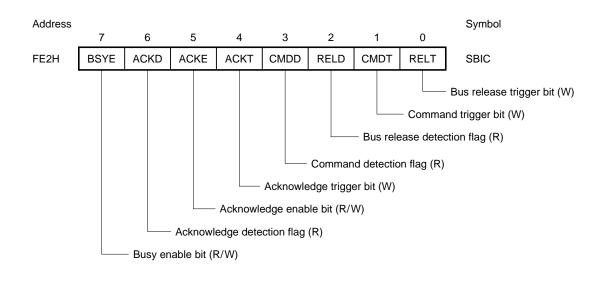
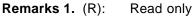


Figure 5-41. Format of Serial Bus Interface Control Register (SBIC) (1/3)



- 2. (W): Write only
- 3. (R/W): Read/write

Figure 5-41. Format of Serial Bus Interface Control Register (SBIC) (2/3)

Busy enable bit (R/W)

BSYE	0	 <1> The busy signal is automatically disabled. <2> Busy signal output is stopped in phase with the falling edge of SCK immediately after clear instruction execution.
	1	The busy signal is output after the acknowledge signal in phase with the falling edge of \overline{SCK} .

Acknowledge detection flag (R)

ACKD	Condition for being cleared (ACKD = 0)	Condition for being set (ACKD = 1)
	 <1> The transfer operation is started. <2> The RESET signal is generated. 	The acknowledge signal (\overline{ACK}) is detected (in phase with the rising edge of \overline{SCK}).

Acknowledge enable bit (R/W)

ACKE	0	Disables automatic output of the acknowledge signal (\overline{ACK}). (Output by ACKT is possible.)				
	1	When set before transfer	efore transfer \overline{ACK} is output in phase with the 9th clock of \overline{SCK} .			
		When set after transfer	\overline{ACK} is output in phase with \overline{SCK} immediately following the set instruction execution.			

Acknowledge trigger bit (W)

ACKT When set after transfer, \overline{ACK} is output in phase with the next \overline{SCK} . After \overline{ACK} signal output, this bit is automatically cleared to 0.

Cautions 1. Never set ACKT before or during serial transfer.

- 2. ACKT cannot be cleared by software.
- 3. Before setting ACKT, set ACKE = 0.

Command detection flag (R)

CMDD	Condition for being cleared (CMDD = 0)	Condition for being set (CMDD = 1)		
	 <1> The transfer start instruction is executed. <2> The <u>bus release</u> signal (REL) <3> The RESET signal is generated. <4> CSIE = 0 (See Figure 5-40.) 	The command signal (CMD) is detected.		

Figure 5-41. Format of Serial Bus Interface Control Register (SBIC) (3/3)

Bus release detection flag (R)

RELD	Condition for being cleared (RELD = 0)	Condition for being set (RELD = 1)
	 <1> The transfer start instruction is executed. <2> The RESET signal is generated. <3> CSIE = 0 (See Figure 5-40.) <4> SVA does not match SIO when an address is received. 	The bus release signal (REL) is detected.

Command trigger bit (W)

CMDT	Control bit for command signal (CMD) trigger output. By setting CMDT = 1, the SO latch is
	cleared. Then the CMDT bit is automatically cleared to 0.

Caution Never clear SB0 (or SB1) during serial transfer. Be sure to clear SB0 (or SB1) before or after serial transfer

Bus release trigger bit (W)

RELT	Control bit for bus release signal (REL) trigger output.
	By setting RELT = 1, the SO latch is set to 1. Then the RELT bit is automatically cleared to 0.

Caution Never clear SB0 (or SB1) during serial transfer. Be sure to clear SB0 (or SB1) before or after serial transfer.

Examples 1. A command signal is output.

SEL MB15 ; or CLR1 MBE SET1 CMDT

 RELD and CMDD are tested to identify the types of received data and the types of processing accordingly. By setting WUP = 1, this interrupt routine is processed only when an address match is found.

SEL	MB15	
SKF	RELD	; RELD test
BR	!ADRS	
SKT	CMDD	; CMDD test
BR	!DATA	
BR	!CMD	
CMD:		; Command analysis
DATA:		; Data processing
ADRS:		; Address decode

(3) Shift register (SIO)

Figure 5-42 shows the configuration of peripheral hardware of shift register. SIO is an 8-bit register which performs parallel-serial conversion and serial transfer (shift) operation in phase with the serial clock. Serial transfer is started by writing data to SIO.

In transmission, data written to SIO is output on the serial output (SO) or serial data bus (SB0 or SB1). In receive operation, data is read from the serial input (SI) or SB0 or SB1 into SIO.

Data can be read from or written to SIO by using an 8-bit manipulation instruction.

When the $\overrightarrow{\mathsf{RESET}}$ signal is generated during operation, the value of SIO is undefined. When the $\overrightarrow{\mathsf{RESET}}$ signal is generated in the standby mode, the value of SIO is preserved.

Shift operation is stopped after 8-bit send or receive operation is completed.

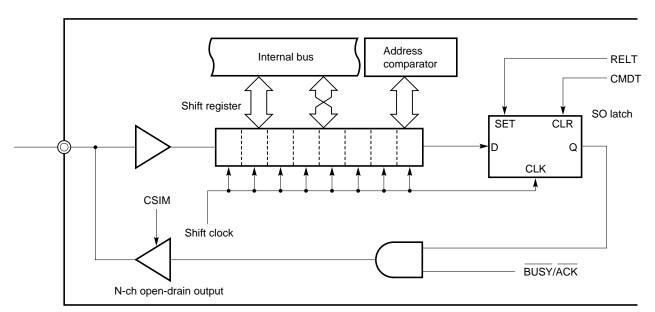


Figure 5-42. Peripheral Hardware of Shift Register

The timing for reading SIO and start of serial transfer (writing to SIO) is as follows:

- When the serial interface operation enable/disable bit (CSIE) = 1. However, the case where CSIE is set to 1 after data is written to the shift register is excluded.
- When the serial clock is masked after 8-bit serial transfer
- SCK is high.

When reading from or writing to SIO, make sure that $\overline{\text{SCK}}$ is high.

In the two-wire serial I/O mode and SBI mode, the pins specified for the data bus are used for both input and output. Because the configuration of output pins is N-ch open-drain, write FFH in SIO for devices that are to receive data.

(4) Slave address register (SVA)

The slave address register (SVA) is an 8-bit register for a slave to set its slave address (number assigned to it).

SVA is manipulated using an 8-bit manipulation instruction.

When the $\overrightarrow{\text{RESET}}$ signal is generated, the value of SVA is undefined. However, the value of SVA is preserved when the $\overrightarrow{\text{RESET}}$ signal is generated in the standby mode.

SVA has the following two functions:

(a) Slave address detection

[In the SBI mode]

SVA is used when the μ PD750108 is connected as a slave device to the serial bus. SVA is an 8bit register for a slave to set its slave address (number assigned to it). The master outputs a slave address to the connected slaves to select a particular slave. Two data values (a slave address output from the master and the value of SVA) are compared with each other by the address comparator. If a match is found, the slave is selected.

At this time, bit 6 (COI) of serial operation mode register (CSIM) is set to 1.

If a match with received address data is not found, the bus release detection flag (RELD) is cleared to 0. When WUP = 1 (wake-up state detection), IRQCSI is set only when a match is found. With this interrupt request, the μ PD750108 can be informed of a communication request transmitted from the master.

(b) Error detection

[In the two-wire serial I/O mode or SBI mode]

SVA detects an error when addresses, commands, or data is transferred with the μ PD750108 operating as the master or when data is transferred with the μ PD750108 operating as a slave. (For details, see **(6)** in **Section 5.6.6** and **(8)** in **Section 5.6.7**.)

5.6.4 Operation Halt Mode

The operation halt mode is used when serial transfer is not performed. This mode reduces power consumption.

The shift register does not perform shift operation in this mode, so the shift register can be used as a normal 8-bit register.

When the RESET signal is entered, the operation halt mode is set. The P02/SO/SB0 pin and P03/SI/SBI pin function as input-only port pins. The P01/SCK pin can be used as an input port pin by setting the serial operation mode register.

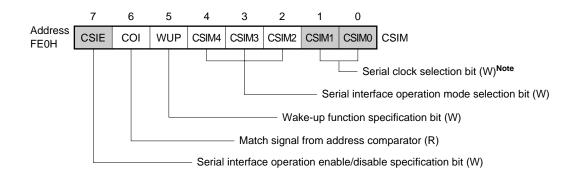
(1) Register setting

To set the operation halt mode, manipulate serial operation mode register (CSIM). (For details on CSIM format, see (1) in Section 5.6.3.)

CSIM is manipulated with an 8-bit manipulation instruction. Only the CSIE bit of CSIM can be independently manipulated. CSIM can also be manipulated using the name of each bit.

When the RESET signal is entered, CSIM is set to 00H.

In the figure below, hatched portions indicate bits used in the operation halt mode.



Note The status of the P01/SCK pin is selectable.

Remark (R): Read only

(W): Write only

Serial interface operation enable/disable specification bit (W)

		Shift register operation	Serial clock counter	IRQCSI flag	SO/SB0 and SI/SB1 pins
CSIE0 0 Shift operat		Shift operation disabled	Cleared	Held	Used only for port 0

Serial clock selection bit (W)

The P01/SCK pin assumes the following state according to the setting of CSIM0 and CSIM1:

CSIM1	CSIM0	P01/SCK pin state
0	0	High impedance
0	1	High level output
1	0	
1	1	

When clearing CSIE during serial transfer, use the following procedure:

<1> Disable interrupts by clearing the interrupt enable flag (IECSI).

<2> Clear CSIE.

<3> Clear the interrupt request flag (IRQCSI).

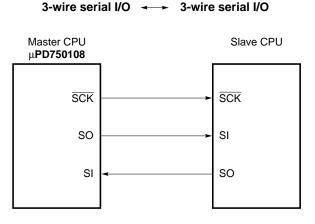
5.6.5 Three-Wire Serial I/O Mode Operations

The three-wire serial I/O mode is compatible with other modes used in the 75XL series, 75X series, μ PD7500 series, and 87AD series.

Communication is performed using three lines:

Serial clock (SCK), serial output (SO), and serial input (SI).

Figure 5-43. Example of Three-Wire Serial I/O System Configuration



Remark The μ PD750108 can also be used as a slave CPU.

(1) Register setting

To set the three-wire serial I/O mode, manipulate the following two registers:

- Serial operation mode register (CSIM)
- Serial bus interface control register (SBIC)

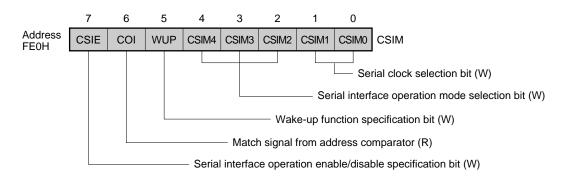
(a) Serial operation mode register (CSIM)

To use the three-wire serial I/O mode, set CSIM as shown below. (For details on CSIM format, see (1) in Section 5.6.3.)

CSIM0 is manipulated using an 8-bit manipulation instruction. Bits 7, 6, and 5 of CSIM can be manipulated bit by bit.

When the $\overline{\text{RESET}}$ signal is input, CSIM is set to 00H.

In the figure below, hatched portions indicate the bits used in the three-wire serial I/O mode.



Remark (R): Read only (W): Write only

Serial interface operation enable/disable specification bit (W)

		Shift register operation	Serial clock counter	IRQCSI flag	SO/SB0 and SI/SB1 pins
CSIE	1	Shift operation enabled	Count operation	Can be set	Used in each mode as well as for port 0

Signal from address comparator (R)

COINote	Condition for being cleared (COI = 0)	Condition for being set (COI = 1)
	When the slave address register (SVA) does not match the data of the shift register	When the slave address register (SVA) matches the data of the shift register

Note COI can be read only before serial transfer is started or after serial transfer is completed. An undefined value may be read during transfer. COI data written by an 8-bit manipulation instruction is ignored.

Wake-up function specification bit (W)

WUP	Sets IRQCSI each time serial transfer is completed.
-----	---

Serial interface operation mode selection bit (W)

CSIM4	CSIM3	CSIM2	Shift register sequence	P02/SO/SB0 pin function	P03/SI/SB1 pin function
x	x 0 0		SIO ₇₋₀ <—> XA (Transfer starting with MSB)	SO (CMOS output)	SI (CMOS input)
		1	SIO ₀₋₇ <—> XA (Transfer starting with LSB)		

Remark x: Don't care

Serial clock selection bit (W)

CSIM1	CSIM0	Serial clock	SCK pin mode
0	0	External clock applied to SCK pin	Input
0	1	Timer/event counter output (TOUT0)	Output
1	0	f _{CC} /2 ⁴ (125 kHz: during 2-MHz operation, 62.5 kHz: during 1-MHz operation)	
1	1	f _{CC} /2 ³ (250 kHz: during 2-MHz operation, 125 kHz: during 1-MHz operation)	

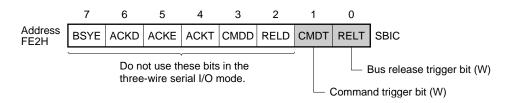
(b) Serial bus interface control register (SBIC)

To use the three-wire serial I/O mode, set SBIC as shown below. (For details on SBIC format, see (2) in Section 5.6.3.)

SBIC is manipulated using a bit memory manipulation instruction.

When the RESET signal is input, SBIC is set to 00H.

In the figure below, hatched portions indicate the bits used in the three-wire serial I/O mode.



Remark (W): Write only

Command trigger bit (W)

CMDT	Control bit for command signal (CMD) trigger output. By setting CMDT = 1, the SO latch is
	cleared. Then the CMDT bit is automatically cleared to 0.

Bus release trigger bit (W)

R	RELT	Control bit for bus release signal (REL) trigger output.
		By setting RELT = 1, the SO latch is set to 1. Then the RELT bit automatically cleared to 0.

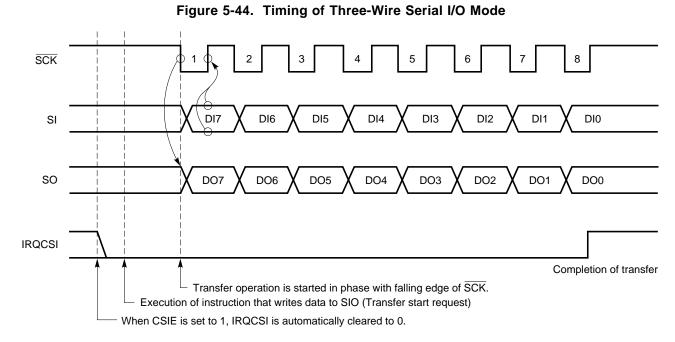
Caution Never use bits other than RELT and CMDT in the three-wire serial I/O mode.

(2) Communication operation

The three-wire serial I/O mode transfers data, with eight bits as one block. Data is transferred bit by bit in phase with the serial clock.

The shift register performs shift operation on the falling edge of the serial clock (\overline{SCK}). Send data is latched on the SO latch, and is output on the SO pin. Receive data applied to the SI pin is latched in the shift register on the rising edge of \overline{SCK} .

When eight bits have been transferred, shift register operation automatically terminates setting the interrupt request flag (IRQCSI).



The SO pin becomes a CMOS output and outputs the state of the SO latch. So the output state of the SO pin can be manipulated by setting the RELT bit and CMDT bit.

However, this manipulation must not be performed during serial transfer.

The output level of the SCK pin can be controlled by manipulating the P01 output latch in the output mode (internal system clock mode). (See **Section 5.6.8**.)

(3) Serial clock selection

To select the serial clock, manipulate bits 0 and 1 of serial operation mode register 0 (CSIM). The serial clock can be selected out of the following four clocks:

Mode r	egister	Se	rial clock	Timing for chift register P/W and	
CSIM 1	CSIM 0	Source	Masking of serial clock	Timing for shift register R/W and start of serial transfer	Application
0	0	External SCK	Automatically masked when	<1> In the operable mode (CSIE = 1)	Slave CPU
0	1	TOUT flip-flop	8-bit data transfer is completed	 <2> When the serial clock is masked after 8-bit transfer <3> When SCK is high 	Half-duplex asyn- chronous transfer (software control)
1	0	f _{CC} /24			Middle-speed serial transfer
1	1	f _{CC} /2 ³			High-speed serial transfer

Table 5-7. Serial Clock Selection and Application (in the Three-Wire Serial I/O Mode)

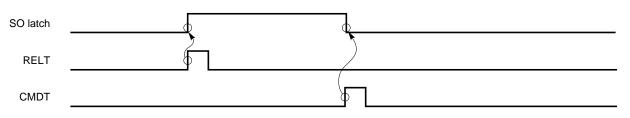
*

*

(4) Signals

Figure 5-45 shows operations of RELT and CMDT.

Figure 5-45. Operations of RELT and CMDT



(5) Switching between MSB and LSB as the first transfer bit

The three-wire serial I/O mode has a function that can switch between the MSB and LSB as the first bit of transfer.

Figure 5-46 shows the configuration of shift register (SIO) and internal bus. As shown in Figure 5-46, read or write operation can be performed by switching between the MSB and LSB.

This switching can be specified using bit 2 of serial operation mode register (CSIM).

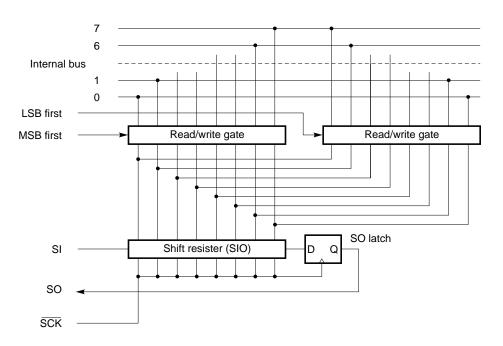


Figure 5-46. Transfer Bit Switching Circuit

The first bit is switched by changing the order of data bits written to shift register (SIO). The shift operation order of SIO is always the same.

Accordingly, the first bit must be switched between the MSB and LSB before writing data to the shift register.

(6) Transfer start

Serial transfer is started by writing transfer data into shift register (SIO), provided that the following two conditions are satisfied:

- The serial interface operation enable/disable specification bit (CSIE) is set to 1.
- The internal serial clock is not operating after 8-bit serial transfer, or SCK is high.

Caution Setting CSIE to 1 after writing data to the shift register does not start transfer.

When eight bits have been transferred, serial transfer automatically terminates setting the interrupt request flag (IRQCSI).

Example To transfer the RAM data specified with the HL register to SIO, load the SIO data to the accumulator and start serial transfer:

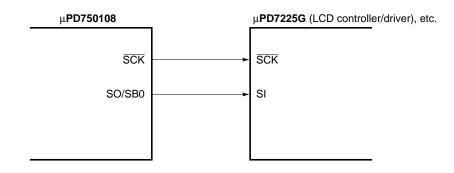
MOV XA,@HL	; Fetch transmit data from RAM
SEL MB15	; or CLR1 MBE
XCH XA,SIO	; Exchange transmit data and receive data, and start transfer

(7) Application of the three-wire serial I/O mode

(a) Data is transferred starting with the MSB on a transfer clock of 62.5 kHz (during 1-MHz operation). (Master operation)

ess
3

Caution A second or subsequent transfer can be started by setting data in SIO (MOV SIO,XA or XCH XA,SIO).

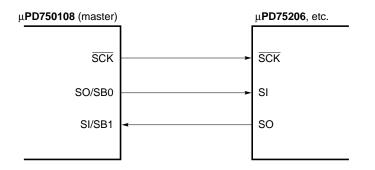


In this case, the SI/SBI pin on the μ PD750108 can be used as an input.

(b) Data is transmitted and received starting with the LSB on an external clock (slave operation). (In this case, the function of inverting the MSB/LSB is used for shift register read/write operation.)

μ ΡD7	50108	Other microcomputers
P	01/SCK <	- SCK
	SI/SB1 🔫	SO
S	;O/SB0,	- SI
<sample program=""></sample>		
Main routine		
CLR1 MBE		
MOV XA,#84H		
MOV CSIM,XA	; Serial operation h	alt, MSB/LSB invert mode, external clock
MOV XA,TDAT	A	
MOV SIO,XA	; Set transfer data,	and start transfer
EI IECSI		
EI		
Interrupt routine (MBE = 0)		
MOV XA,TDAT	A	
XCH XA,SIO	; Start to transfer re	eceive data and transmit data
MOV RDATA,X	A ; Save receive data	à
RETI		

(c) Data is transmitted and received by using a transfer clock of 125 kHz (during 1-MHz operation).

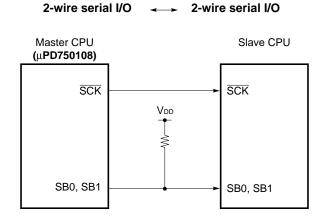


<sample program=""></sample>	(master sid	e):	
	CLR1	MBE	
	MOV	XA,#10000011B	
	MOV	CSIM,XA	; Set transfer mode
	MOV	XA,TDATA	
	MOV	SIO,XA	; Set transfer data, and start transfer
	•		
	•		
LOOP :	SKTCLR BR	IRQCSI LOOP	; Test IRQCSI
	MOV	XA,SIO	; Read in receive data

5.6.6 Two-Wire Serial I/O Mode

The two-wire serial I/O mode can be made compatible with any communication format by programming. In this mode, communication is basically performed using two lines: Serial clock (SCK) and serial data input/ output (SB0 or SB1).





Remark The μ PD750108 can also be used as a slave CPU.

(1) Register setting

To set the two-wire serial I/O mode, manipulate the following two registers:

- Serial operation mode register (CSIM)
- Serial bus interface control register (SBIC)

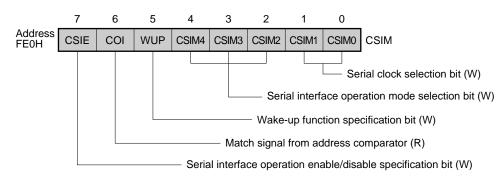
(a) Serial operation mode register (CSIM)

To use the two-wire serial I/O mode, set CSIM as shown below. (For details on CSIM format, see (1) in Section 5.6.3.)

CSIM is manipulated using an 8-bit manipulation instruction. Bits 7, 6, and 5 of CSIM can be manipulated bit by bit.

When the RESET signal is input, CSIM is set to 00H.

In the figure below, hatched portions indicate the bits used in the two-wire serial I/O mode.



Remark (R): Read only (W): Write only

Serial interface operation enable/disable specification bit (W)

		Shift register operation	Serial clock counter	IRQCSI flag	SO/SB0 and SI/SB1 pins
CSIE	1	Shift operation enabled	Count operation	Can be set	Used in each mode as well as for port 0

Signal from address comparator (R)

COINote	Condition for being cleared (COI = 0)	Condition for being set (COI = 1)
	When the slave address register (SVA) does not match the data of the shift register	When the slave address register (SVA) matches the data of the shift register

Note COI can be read only before serial transfer is started or after serial transfer is completed. An undefined value may be read during transfer. COI data written by an 8-bit manipulation instruction is ignored.

Wake-up function specification bit (W)

WUP	0	Sets IRQCSI each time serial transfer is completed.	
-----	---	---	--

Serial interface operation mode selection bit (W)

CSIM4	CSIM3	CSIM2	Shift register sequence	P02/SO/SB0 pin function	P03/SI/SB1 pin function
0	1	1	SIO ₇₋₀ <—> XA (Transfer starting with MSB)	SB0 (N-ch open- drain I/O)	P03 (CMOS input)
1				P02 (CMOS input)	SB1 (N-ch open- drain I/O)

Serial clock selection bit (W)

CSIM1	CSIM0	Serial clock	SCK pin mode
0	0	External clock applied to SCK pin	Input
0	1	Timer/event counter output (TOUT0)	Output
1	0	f _{CC} /2 ⁶ (31.3 kHz: during 2-MHz operation,	
1	1	15.6 kHz : during 1-MHz operation)	

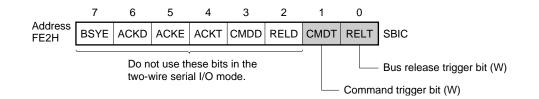
(b) Serial bus interface control register (SBIC)

To use the two-wire serial I/O mode, set SBIC as shown below. (For details on SBIC format, see (2) in Section 5.6.3.)

SBIC is manipulated using a bit manipulation instruction.

When the $\overline{\text{RESET}}$ signal is input, SBIC is set to 00H.

In the figure below, the hatched portions indicate the bits used in the two-wire serial I/O mode.



Remark (W): Write only

Command trigger bit (W)

CMDT Control bit for command signal (CMD) trigger output. By setting CMDT = 1, the SO latch is cleared to 0. Then the CMDT bit is automatically cleared to 0.

Bus release trigger bit (W)

RELT	Control bit for bus release signal (REL) trigger output. By setting RELT = 1, the SO latch is set to 1. Then the RELT bit automatically cleared to 0.
------	--

Caution Never use bits other than RELT and CMDT in the two-wire serial I/O mode.

(2) Communication operation

The two-wire serial I/O mode transfers data, with eight bits as one block. Data is transferred bit by bit in phase with the serial clock.

The shift register performs shift operation on the falling edge of the serial clock (\overline{SCK}). Transmit data is latched on the SO latch, and is output on the SB0/P02 pin or SB1/P03 pin starting with the MSB. Receive data applied to the SB0 pin or SB1 pin is latched in the shift register on the rising edge of \overline{SCK} .

When eight bits have been transferred, shift register operation automatically terminates setting the interrupt request flag (IRQCSI).

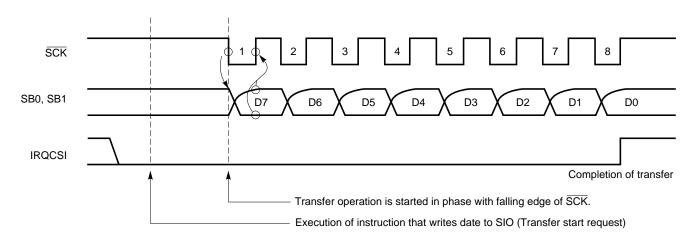


Figure 5-48. Timing of Two-Wire Serial I/O Mode

The SB0 (or SB1) pin becomes an N-ch open-drain I/O when specified as the serial data bus, so the voltage level on that pin must be pulled up externally.

The state of the SO latch is output on the SB0 (or SB1) pin, so the SB0 (or SB1) pin output states can be controlled by setting the RELT or CMDT bit.

However, this operation must not be performed during serial transfer.

The output state of the SCK pin can be controlled by manipulating the P01 output latch in the output mode (internal system clock mode). (See **Section 5.6.8**.)

(3) Serial clock selection

To select the serial clock, manipulate bits 0 and 1 of serial operation mode register (CSIM). The serial clock can be selected out of the following four clocks:

Mode register		Serial clock		Timing for chift register D/W and		
CSIM 1	CSIM 0	Source	Masking of serial clock	Timing for shift register R/W and start of serial transfer	Application	
0	0	External SCK	Automatically masked when	<1> In the operable mode (CSIE = 1)	Slave CPU	
0	1	TOUT flip-flop	8-bit data transfer is completed	 <2> When the serial clock is masked after 8-bit transfer <3> When SCK is high 	Arbitrary-speed serial transfer	
1	0	f _{CC} /26			Low-speed serial transfer	
1	1					

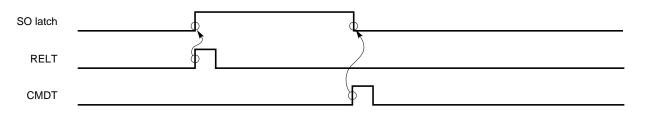
Table 5-8.	Serial Clock	Selection and	Application	(in the	Two-Wire	Serial I/O	Mode)
------------	--------------	---------------	-------------	---------	-----------------	------------	-------

(4) Signals

*

Figure 5-49 shows operations of RELT and CMDT.

Figure 5-49. Operations of RELT and CMDT



(5) Transfer start

Serial transfer starts by writing transfer data into shift register (SIO), provided that the following two conditions are satisfied:

- The serial interface operation enable/disable specification bit (CSIE) is set to 1.
- The internal serial clock is not operating after 8-bit serial transfer, or SCK is high.

Cautions 1. Setting CSIE to 1 after writing data to the shift register does not start transfer.

2. When data is received, the N-ch transistor must be turned off, so FFH must be written to SIO beforehand.

When eight bits have been transferred, serial transfer automatically terminates setting the interrupt request flag (IRQCSI).

(6) Error detection

In the two-wire serial I/O mode, the state of serial bus SB0 or SB1 being used for communication is loaded into the shift register (SIO) of the transmitting device. So a transmission error can be detected by the methods described below.

(a) Comparing SIO data before start of transmission with SIO data after start of transmission With this method, the occurrence of a transmission error is assumed when two SIO values disagree with each other.

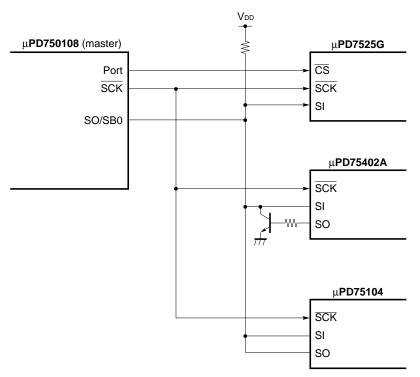
(b) Using the slave address register (SVA)

Transmit data is set in SVA as well before the data is transmitted. On completion of transmission, the COI bit (match signal from the address comparator) of serial operation mode register (CSIM) is tested. If the result is 1, the transmission is regarded as successful. If the result is 0, the occurrence of a transmission error is assumed.

(7) Application of two-wire serial I/O mode

A serial bus is configured, and multiple devices are connected to it.

Example A system is configured with a μ PD750108 as the master to which a μ PD75104, μ PD75402A, and μ PD7225G are connected as slaves.



To configure the bus as shown above, connect the SI pin and SO pin. Then, writes FFH to the shift register to make the SO pin high except when serial data is output, and free the bus by setting off the output buffer. The SO pin of the μ PD75402A cannot go into a high-impedance state, so that a transistor must be connected as shown in the figure to make open collector output appear on the pin. When data is input, 00H must be set beforehand in the shift register to set the transistor off.

The timing of data output by each microcontroller must be predetermined.

The μ PD750108, which is the master microcontroller, outputs a serial clock, and all slave microcontrollers operate with an external clock.

5.6.7 SBI Mode Operation

The SBI (serial bus interface) is a high-speed serial interface that conforms to the NEC serial bus format. To allow communication with multiple devices on a single-master and high-speed serial bus using two signal lines, the SBI has a bus configuration function added to the clock synchronous serial I/O method. So the SBI can reduce ports and wires on boards when multiple microcontrollers and peripheral ICs are used to configure a serial bus.

The master can output, on the serial data bus, an address for selecting a device subject to serial communication, commands directed to the remote device, and data. A slave can identify an address, commands, and data from received data by hardware. This function simplifies the serial interface control portion of an application program.

The SBI function is available with devices such as the 75X series, 75XL series, and 78K series 8-/16-bit single chip microcontrollers.

Figure 5-50 is an example of the SBI system configuration when the CPU with a serial interface conforming to SBI or peripheral ICs are used.

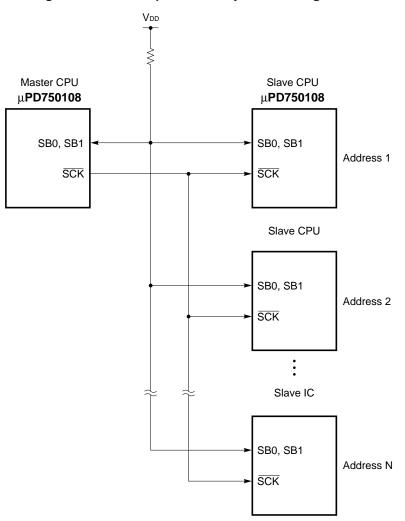


Figure 5-50. Example of SBI System Configuration

- Cautions 1. In the SBI mode, the serial data bus pin SB0 (or SB1) is an open-drain output. So the serial data bus line is placed in the wired OR state. A pull-up resistor is required for the serial data bus line.
 - 2. To switch between the master and slave, a pull-up resistor is required also for the serial clock line (\overline{SCK}) because \overline{SCK} input/output switching is performed between the master and slave asynchronously.

(1) SBI functions

Conventional serial I/O methods provide only data transfer functions. Therefore, many ports and wires are required to identify chip select signals, commands, and data, and to detect busy states, when the serial bus is configured with multiple devices. Also, these processes are too burdensome to be controlled by software.

The SBI method can configure a serial bus with two signal lines: Serial clock \overline{SCK} and serial data bus (SB0 or SB1). For this reason, the number of ports on a microcontroller can be reduced and the wiring on a circuit board can be simplified.

SBI functions are described below.

(a) Address/command/data identification function

Serial data is classified into three types: Address, command, and data.

(b) Address-based chip select function

The master selects a chip for a slave by address transfer.

(c) Wake-up function

A slave can easily check address reception (for chip select identification) with the wake-up function. This function can be set or released by software.

When the wake-up function is set, an interrupt (IRQCSI) is generated when a match address is received. For this reason, in communication with multiple devices, a CPU other than a selected slave can operate independently of serial communication.

(d) Acknowledge signal (ACK) control function

The acknowledge signal, which is used to confirm the reception of serial data, can be controlled.

(e) Busy signal (BUSY) control function

The busy signal, which is used to post the busy state of a slave, can be controlled.

(2) SBI definition

The format of serial data and signal used in the SBI mode are described below. Serial data to be transferred in the SBI mode is classified into three types: Address, command, and data. Serial data forms one frame as shown below.

Figure 5-51 is a timing chart for transferring address, command, and data.

Figure 5-51. Timing of SBI Transfer

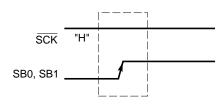
Address transfer **SCK** BUSY SB0. SB1 A7 A0 ACK ! Bus release signal **Command transfer** Command signal SCK 9 CO ACK SB0, SB1 C7 BUSY READY Data transfer SCK DO ACK BUSY READY D7 SB0, SB1

The bus release signal and command signal are output by the master. BUSY is output by a slave. ACK is output by either the master or a slave. (Normally, the device which received 8-bit data outputs \overline{ACK} .) The master continues to output the serial clock from when 8-bit data transfer starts to when \overline{BUSY} is released.

(a) Bus release signal (REL)

When the SCK line is high (the serial clock is not output), the SB0 (or SB1) line changes from low to high. This signal is called the bus release signal, and is output by the master.

Figure 5-52. Bus Release Signal

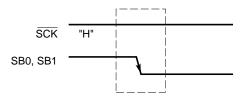


This signal indicates that the master is to send an address to a slave. Slaves contain hardware to detect the bus release signal.

(b) Command signal (CMD)

When the SCK line is high (the serial clock is not output), the SB0 (or SB1) line changes from high to low. This signal is called the command signal, which is output by the master.





Slaves contain hardware to detect the command signal.

(c) Address

An address is 8-bit data and is output by the master to connected slaves to select a particular slave.

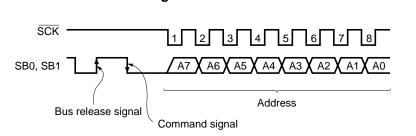
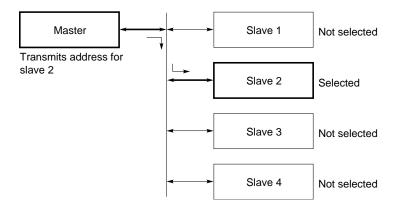


Figure 5-54. Address

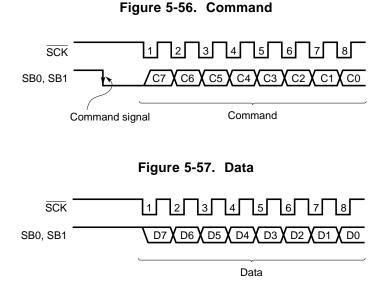
The 8-bit data following the bus release signal or command signal is defined as an address. A slave detects the condition for the addresses by hardware, and checks whether the 8-bit data matches the number assigned to the slave (slave address). If the 8-bit data matches the slave address, that slave is selected. The selected slave continues to communicate with the master until disconnection is directed by the master.

Figure 5-55. Slave Selection Using an Address



(d) Command and data

The master sends commands to the slave selected by sending an address. The master also transfers data to or from the slave.



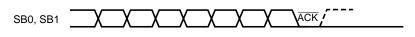
The 8-bit data following the command signal is defined as a command. The 8-bit data without the command signal is defined as data. The usage of commands or data can be selected optionally according to the communication specifications.

(e) Acknowledge signal (ACK)

The acknowledge signal confirms the reception of serial data between the transmitter and the receiver.

Figure 5-58. Acknowledge Signal

[When output in phase with the 11th clock of \overline{SCK}] \overline{SCK} \overline{SCK} \overline{SCK} $\overline{SB0}$, SB1 \overline{SCK} \overline{SCK} [When output in phase with the 9th clock of \overline{SCK}] \overline{SCK} \overline{SCK} \overline{SCK} \overline{SCK}



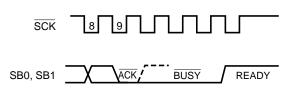
The acknowledge signal is a one-shot pulse output in phase with the falling edge of \overline{SCK} after 8-bit data transfer. This signal may be synchronized with any clock of \overline{SCK} .

The transmitter checks if the receiver returns the acknowledge signal after 8-bit data transfer. If the acknowledge signal is not returned after a specified period of time, the transmitter can assume that the reception failed.

(f) Busy signal (BUSY) and ready signal (READY)

The busy signal informs the master that a slave is getting ready for data transfer. The ready signal informs the master that a slave is ready for data transfer.

Figure 5-59. Busy and Ready Signals



In the SBI mode, a slave notifies the master of the busy state by changing SB0 (or SB1) from high to low.

The busy signal is output following the acknowledge signal output by the master or a slave. The busy signal is set and released in phase with the falling edge of \overline{SCK} . The master automatically terminates output of serial clock \overline{SCK} when the busy signal is released.

The master can transfer the next data when the busy signal is released and a slave enters the state in which the ready signal is to be output.

(3) Register setting

To set the SBI mode, manipulate the following two registers:

- Serial operation mode register (CSIM)
- Serial bus interface control register (SBIC)

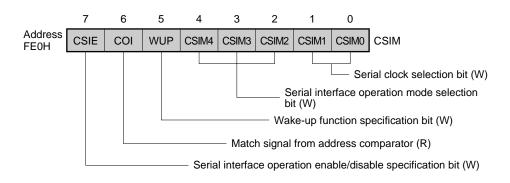
(a) Serial operation mode register (CSIM)

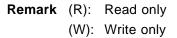
To use the SBI mode, set CSIM as shown below. (For details on CSIM format, see (1) in Section 5.6.3.)

CSIM is manipulated using an 8-bit manipulation instruction. Bits 7, 6, and 5 of CSIM can be manipulated bit by bit.

When the RESET signal is input, CSIM is set to 00H.

In the figure below, hatched portions indicate the bits used in the SBI mode.





Serial interface operation enable/disable specification bit (W)

		Shift register operation	Serial clock counter	IRQCSI flag	SO/SB0 and SI/SB1 pins
CSIE 1		Shift operation enabled	Count operation	Can be set	Used in each mode as well as for port 0

Signal from address comparator (R)

COINote	Condition for being cleared (COI = 0)	Condition for being set (COI = 1)	
	When the slave address register (SVA) does not match the data of the shift register	When the slave address register (SVA) matches the data of the shift register	

Note COI can be read only before serial transfer is started or after serial transfer is completed. An undefined value may be read during transfer.

COI data written by an 8-bit manipulation instruction is ignored.

Wake-up function specification bit (W)

WUP	0	Sets IRQCSI each time serial transfer is completed in each mode.	
	1	Used in the SBI mode only to set IRQCSI only when an address received after bus release matches the data in the slave address register (wake-up state). SB0 or SB1 goes to high-impedance state.	

Caution When WUP = 1 is set during BUSY signal output, BUSY is not released. In the SBI mode, the BUSY signal is output until the next falling edge of the serial clock (SCK) appears after release of BUSY is directed. Before setting WUP = 1, be sure to confirm that the SB0 (or SB1) pin is high after releasing BUSY.

Serial interface operation mode selection bit (W)

CSIM4	CSIM3	CSIM2	Shift register sequence	P02/SO/SB0 pin function	P03/SI/SB1 pin function
0	1	0	SIO ₇₋₀ <—> XA (Transfer starting with MSB)	SB0 (N-ch open- drain I/O)	P03 (CMOS input)
1				P02 (CMOS input)	SB1 (N-ch open- drain I/O)

Serial clock selection bit (W)

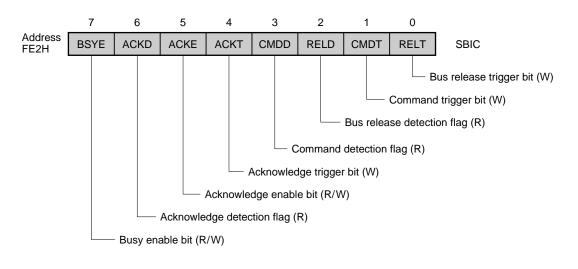
CSIM1	CSIM0	Serial clock	SCK pin mode
0	0	External clock applied to SCK pin	Input
0	1	Timer/event counter output (TOUT0)	Output
1	0	f _{CC} /2 ⁴ (125 kHz: during 2-MHz operation, 62.5 kHz: during 1-MHz operation)	
1	1	f _{CC} /2 ³ (250 kHz: during 2-MHz operation, 125 kHz: during 1-MHz operation)	

(b) Serial bus interface control register (SBIC)

To use the SBI mode, set SBIC as shown below. (For details on SBIC format, see (2) in Section 5.6.3.) SBIC is manipulated using a bit manipulation instruction.

When the RESET signal is input, SBIC is set to 00H.

In the figure below, hatched portions indicate the bits used in the SBI mode.



Remark (R): Read only

(W): Write only

(R/W): Read/write

Busy enable bit (R/W)

BSYE	0	 <1> The busy signal is automatically disabled. <2> Busy signal output is stopped in phase with the falling edge of SCK immediately after clear instruction execution.
	1	The busy signal is output after the acknowledge signal in phase with the falling edge of \overline{SCK} .

Acknowledge detection flag (R)

ACKD	Condition for being cleared (ACKD = 0)	Condition for being set (ACKD = 1)	
	 <1> The transfer operation is started. <2> The RESET signal is entered. 	The acknowledge signal (ACK) is <u>detected</u> (in phase with the rising edge of SCK).	

Acknowledge enable bit (R/W)

ACKE	0	Disables automatic output of the acknowledge signal. (Output by ACKT is possible.)			
	1	When set before transfer	\overline{ACK} is output in phase with the 9th clock of \overline{SCK} .		
		When set after transfer	$\overline{\text{ACK}}$ is output in phase with $\overline{\text{SCK}}$ immediately following the set instruction execution.		

Acknowledge trigger bit (W)

ACKT When set after transfer, \overline{ACK} is output in phase with the next \overline{SCK} . After \overline{ACK} signal output, this bit is automatically cleared to 0.

Cautions 1. Never set ACKT to 1 before or during serial transfer.

- 2. ACKT cannot be cleared by software.
- 3. Before setting ACKT, set ACKE = 0.

Command detection flag (R)

CMDD	Condition for being cleared (CMDD = 0)	Condition for being set (CMDD = 1)	
	 <1> The transfer start instruction is executed. <2> The bus release signal (REL) <3> The RESET signal is entered. <4> CSIE = 0 (Figure 5-40) 	The command signal (CMD) is detected.	

Bus release detection flag (R)

RELD	Condition for being cleared (RELD = 0)	Condition for being set (RELD = 1)
	 <1> The transfer start instruction is executed. <2> The RESET signal is entered. <3> CSIE = 0 (Figure 5-40) <4> SVA does not match SIO when an address is received. 	The bus release signal (REL) is detected.

Command trigger bit (W)

CMDT Control bit for command signal (CMD) trigger output. By setting CMDT = 1, the SO latch is cleared to 0. Then the CMDT bit is automatically cleared to 0.

Caution Never set SB0 (or SB1) during serial transfer. Be sure to set SB0 (or SB1) before or after serial transfer.

Bus release trigger bit (W)

RELT	Control bit for bus release signal (REL) trigger output.
	By setting RELT = 1, the SO latch is set to 1. Then the RELT bit automatically cleared to 0.

Caution Never set SB0 (or SB1) during serial transfer. Be sure to set SB0 (or SB1) before or after serial transfer.

(4) Serial clock selection

To select the serial clock, manipulate bits 0 and 1 of serial operation mode register (CSIM). The serial clock can be selected out of the following four clocks:

Mode r	Mode register		rial clock	Timing for shift register R/W and	
CSIM 1	CSIM 0	Source	Masking of serial clock	start of serial transfer	Application
0	0	External SCK	Automatically masked when	<1> In the operable mode (CSIE = 1)	Slave CPU
0	1	TOUT flip-flop	8-bit data transfer is completed	 <2> When the serial clock is masked after 8-bit transfer <3> When SCK is high 	Arbitrary-speed serial transfer
1	0	f _{CC} /24			Middle-speed serial transfer
1	1	f _{CC} /2 ³			High-speed serial transfer

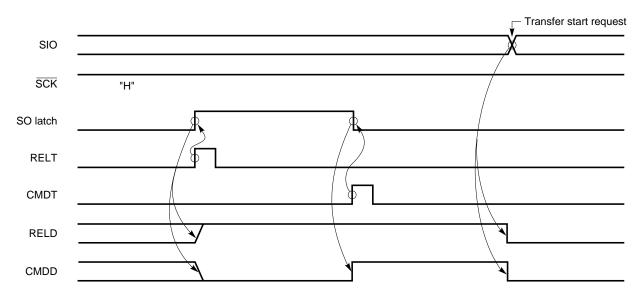
Table 5-9. Serial Clock Selection and Application (in the SBI Mode)

When the internal system clock is selected, \overline{SCK} is internally terminated when the 8th clock has been output, and is externally counted until the slave enters the ready state.

(5) Signals

*

Figures 5-60 to 5-65 show signals to be generated in the SBI mode and flag operations on the SBIC. Table 5-10 lists signals used in the SBI mode.







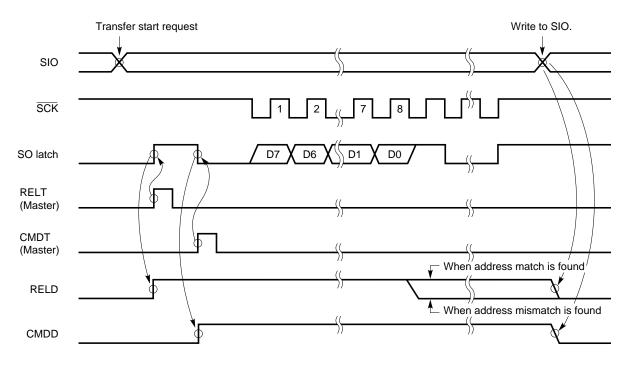
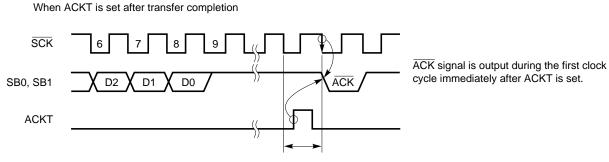


Figure 5-62. Operation of ACKT

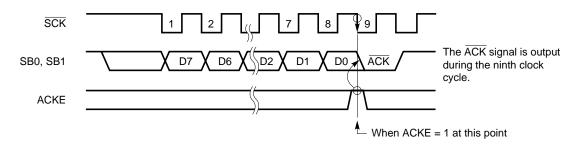


When set during this period

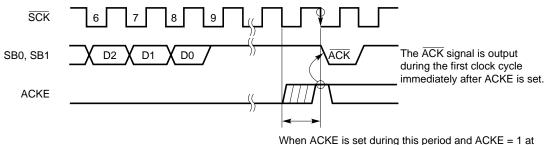
Caution Do not set the ACKT until the transfer is completed.



(a) When ACKE = 1 at time of transfer completion



(b) When ACKE is set after transfer completion



When ACKE is set during this period and ACKE = 1 at the falling edge of the next \overline{SCK}

(c) When ACKE = 0 at time of transfer completion

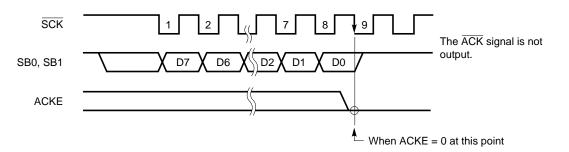
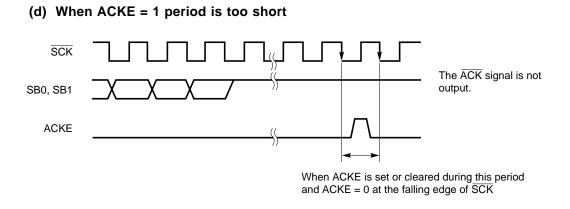
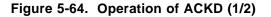
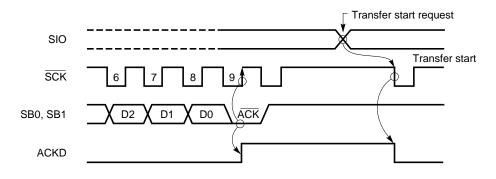


Figure 5-63. Operation of ACKE (2/2)

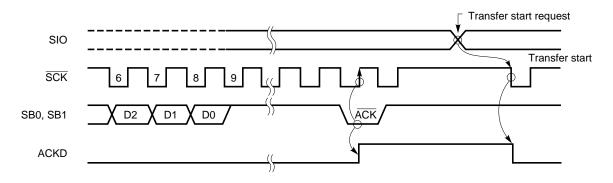




(a) When \overrightarrow{ACK} signal is output during the ninth \overrightarrow{SCK} clock



(b) When \overline{ACK} signal is output after the ninth \overline{SCK} clock



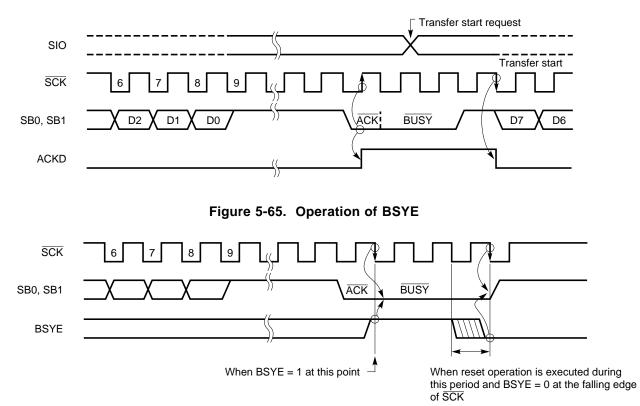


Figure 5-64. Operation of ACKD (2/2)

(c) Clear timing for case where start of transfer is directed during $\overline{\text{BUSY}}$

Meaning of signal	Indicates that CMD signal follows and data transmitted is address data.	 i) Data transmitted after REL signal output is address. ii) Data transmitted, with REL signal not being output, is command. 	Indicates completion of reception.	Indicates that serial reception is disabled because processing is in progress.	Indicates that serial reception is enabled.
Flag operation	 RELD is set. CMDD is cleared. 	CMDD is set.	ACKD is set.		
Condition for output	• RELT is set.	CMDT is set.	<1> ACKE = 1<2> ACKT is set.	• BSYE = 1	 c1> BSYE = 0 c2> Execution of instruction to write data to SIO (Transfer start request)
Timing chart	SCK "H" SB0, SB1	SE0, SB1	[Synchronous <u>BUSY</u> output]		SB0, SB1 D0 (<u>ACK</u> READY
Definition	Rising edge of SB0 or SB1 when <u>SCK</u> = 1	Falling edge of SB0 or SB1 when <u>SCK</u> = 1	Low level signal output on SB0 or SB1 during one <u>SCK</u> clock cycle after serial reception is completed	[Synchronous <u>BUSY</u> signal] Low level signal output on SB0 or SB1 after acknowledge signal	High level signal output on SB0 or SB1 before serial transfer is started or after serial transfer is completed
Output device	Master	Master	Master/ slave	Slave	Slave
Signal name	Bus release signal (REL)	Command signal (CMD)	Acknowledge signal (ACK)	Busy signal (BUSY)	Ready signal (READY)

Meaning of signal	Timing of signal output on serial data bus	Address of slave device on serial bus	Directions and messages to slave device	Numeric processed by slave or master device
Flag operation	IRQCSI is set (on rising edge of 9th clock of <u>SCK</u>) ^{Note 1}			
Condition for output	Execution of instruction to write data to SIO when CSIE = 1 (Serial transfer start request) ^{Note 2}			
Timing chart	sck		SB0,	SER SB0,
Definition	Synchronous clock for outputting address/ command/data, <u>ACK</u> signal, synchronous <u>BUSY</u> signal, and so on. Address/command/data is output during first 8 clock cycles.	8-bit data transferred in phase with <u>SCK</u> after REL signal and CMD signal output	8-bit data transferred in phase with <u>SCK</u> atter only CMD signal is output, with REL signal not being output	8-bit data transferred in phase with <u>SCK</u> , with neither REL signal nor CMD signal being output
Output device	Master	Master	Master	Master/ slave
Signal name	Serial clock (SCK)	Address (A7 - A0)	Command (C7 - C0)	Data (D7 - D0)

Table 5-10. Various Signals Used in the SBI Mode (2/2)

1. When WUP = 0, IRQCSI is always set on the ninth rising edge of the \overline{SCK} signal. Notes

When WUP = 1, IRQCSI is set on the ninth rising edge of SCK only when the received address matches the value held in the slave In the BUSY state, data transfer is initiated after the READY state is set. address register (SVA). ň

(6) Pin configuration

The configurations of serial clock pin SCK and serial data bus pin (SB0 or SB1) are as follows:

- (a) SCK: Pin for serial clock I/O
 - <1> Master: CMOS, push-pull output
 - <2> Slave : Schmitt input
- (b) SB0, SB1: Pin for serial data I/O Output to SB0 or SB1 is an N-ch open-drain output and input is Schmitt input for both the master and a slave.

The serial data bus line must be externally pulled up because it has originally an N-ch open-drain output.

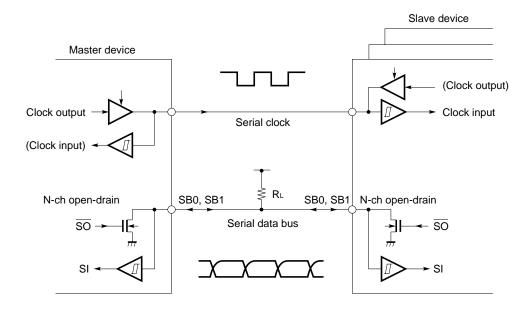


Figure 5-66. Pin Configuration

Caution When data is received, the N-ch transistor must be turned off, so FFH must be written to SIO beforehand. The N-ch open-drain output can be turned off at any time during transfer. However, when the wake-up function specification bit (WUP) is set to 1, the N-ch transistor is always off, so there is no need to write FFH to SIO before reception.

(7) Address match detection method

In the SBI mode, communication starts when the master selects a particular slave device by outputting an address.

An address match is detected by hardware. The slave address register (SVA) is available. In the wakeup state (WUP = 1), IRQCSI is set only when the address transmitted by the master and the value held in SVA match.

- Cautions 1. Whether a slave is selected is determined by detecting a match for a slave address received after bus release (in the state of RELD = 1). An address match is detected usually using an address match interrupt (IRQCSI) generated when WUP is set to 1. So detect selection/nonselection state by slave address when WUP is set to 1.
 - 2. When determining whether a slave is selected without using an interrupt when WUP is 0, do not use the address match detection method. Instead, use transfer of commands set in advance in a program.

(8) Error detection

In the SBI mode, the state of serial bus SB0 (or SB1) being used for communication is loaded into the shift register (SIO) of the transmitting device. So a transmission error can be detected by the methods described below.

(a) Comparing SIO data before start of transmission with SIO data after start of transmission With this method, the occurrence of a transmission error is assumed if two SIO values disagree with each other.

(b) Using the slave address register (SVA)

Transmit data is set in SIO and SVA as well before the data is transmitted. On completion of transmission, the COI bit (match signal from the address comparator) of serial operation mode register (CSIM) is tested. If the result is 1, the transmission is regarded as successful. If the result is 0, the occurrence of a transmission error is assumed.

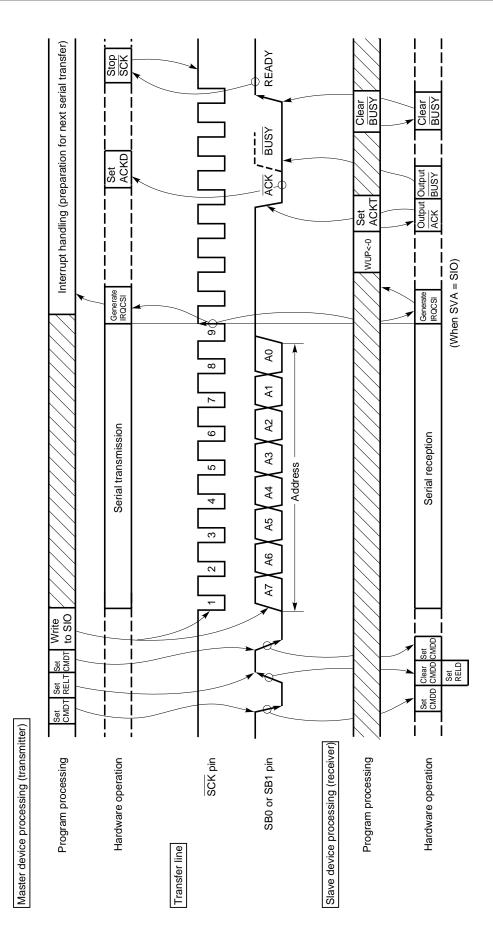
(9) Communication operation

In the SBI mode, the master usually selects a slave device to communicate with from multiple devices by outputting the address of the slave to the serial bus.

After selecting a device to communicate with, the master exchanges commands and data with the slave device, thus establishing serial communication.

Figures 5-67 to 5-70 show the timing charts of data communication operations.

In the SBI mode, the shift register performs shift operation on the falling edge of the serial clock (\overline{SCK}). Transmit data is held on the SO latch, and is output on the SB0/P02 or SB1/P03 pin starting with the MSB. Receive data applied to the SB0 (or SB1) pin is latched in the shift register on the rising edge of \overline{SCK} .





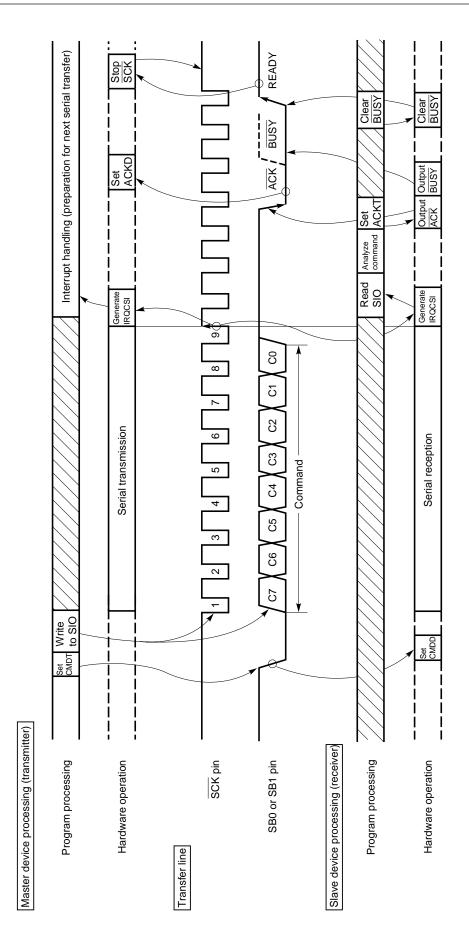


Figure 5-68. Command Transfer Operation from Master Device to Slave Device

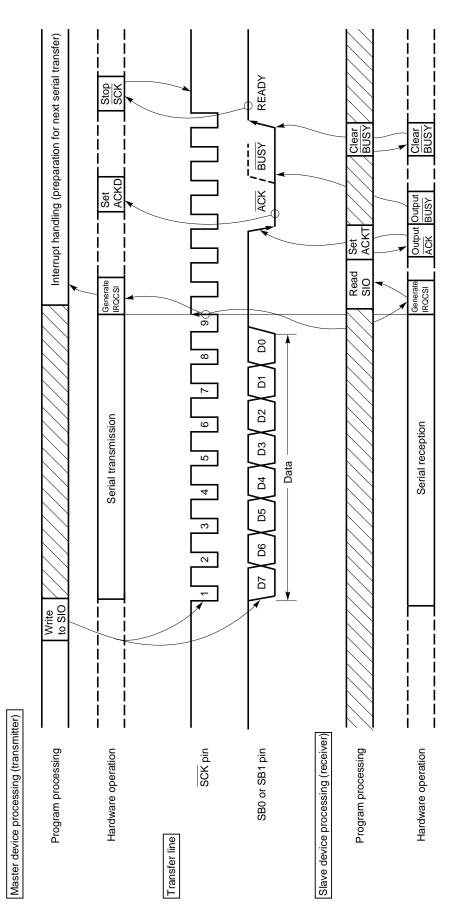
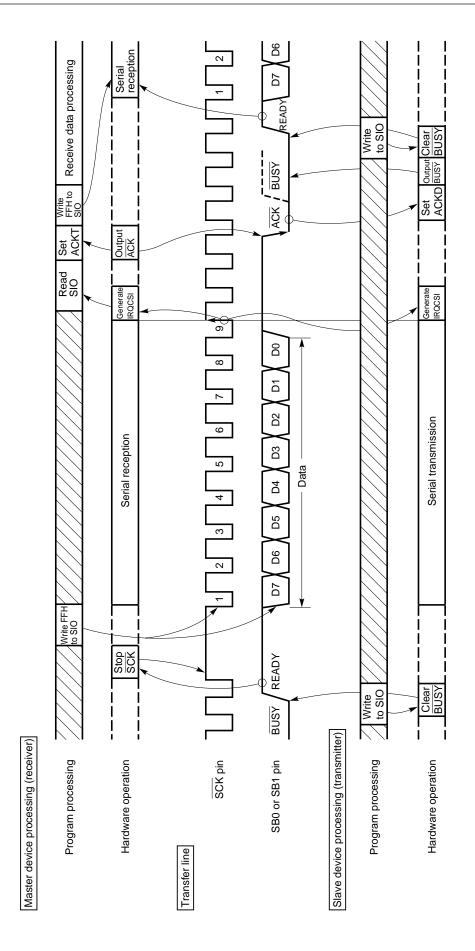


Figure 5-69. Data Transfer Operation from Master Device to Slave Device



175

(10) Transfer start

Serial transfer is started by writing transfer data in shift register (SIO), provided that the following two conditions are satisfied:

- The serial interface operation enable/disable bit (CSIE) is set to 1.
- The internal serial clock is not operating after 8-bit serial transfer, or SCK is high.
- Cautions 1. Transfer cannot be started by setting CSIE to 1 after writing data to the shift register.
 - 2. The N-ch transistor needs to be turned off when data is received. So FFH must be written to SIO beforehand. However, when the wake-up function specification bit (WUP) is set to 1, the N-ch transistor is always off. So FFH need not be written to SIO beforehand for reception.
 - 3. If data is written to SIO when the slave is busy, the data is not lost. Transfer is started when the busy state is released and input to SB0 (or SB1) goes high.

When eight bits have been transferred, serial transfer automatically terminates setting the interrupt request flag (IRQCSI).

Example When RAM data specified by the HL register is transferred to SIO, from which data is loaded into the accumulator at the same time, and serial transfer is started.
 MOV XA,@HL ; Extracts transmit data from RAM
 SEL MB15 ; or CLR1 MBE
 XCH XA,SIO ; Exchanges transmit data with receive data and starts transfer

(11) Notes on the SBI mode

(a) Whether a slave is selected is determined by detecting a match for a slave address received after bus release (in the state of RELD = 1).

An address match is detected usually using, an address match interrupt (IRQCSI) generated when WUP is 1. So detect selection/nonselection state by slave address when WUP is set to 1.

- (b) When determining whether a slave is selected without using an interrupt when WUP = 0, do not use the address match detection method. Instead, use transfer of commands set in advance in a program.
- (c) When WUP is set to 1 during BUSY signal output, BUSY is not released. In the SBI mode, after release of BUSY is directed, the BUSY signal is output until the next falling edge of the serial clock (SCK) appears. Before setting WUP to 1, be sure to confirm that the SB0 (or SB1) pin is high after releasing BUSY.

(12) SBI mode

This section describes an example of application which performs serial data communication in the SBI mode. In the example, the μ PD750108 can be used as either the master CPU or a slave CPU on the serial bus.

The master can be switched to another CPU with a command.

(a) Serial bus configuration

In the serial bus configuration used for the example of this section, a μ PD750108 is connected to the bus line as a device on the serial bus.

Two pins on the μ PD750108 are used: serial data bus SB0 (or SB1) and serial clock SCK (P01). Figure 5-71 shows an example of the serial bus configuration.

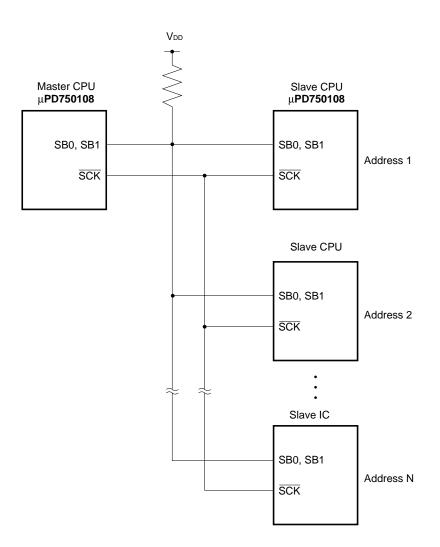


Figure 5-71. Example of Serial Bus Configuration

(b) Explanation of commands

(i) Types of commands

This example uses the following commands:

- <1> READ command : Transfers data from slave to master.
- <2> WRITE command : Transfers data from master to slave.
- <3> END command : Informs slave of WRITE command completion.
- <4> STOP command : Informs slave of WRITE command interruption.
- **<5>** STATUS command : Reads slave status.
- <6> RESET command : Sets currently selected slave as non-selected slave.
- <7> CHGMST command: Passes master authority to slave.

(ii) Protocol

The following protocol is used for communication between the master and slaves.

- <1> The address of a slave with which the master intends to communicate is transmitted to select the slave (chip select). This starts communication. The slave that has received the address returns ACK to engage in communication with the master (The state of the slave is changed from the non-selected state to selected state).
- <2> Commands and data are transferred between the master and the slave selected in <1>. Command and data are transferred between the master and the selected slave on a oneto-one basis, so the other slaves must be placed in the non-selected state.
- <3> Communication is completed when the selected slave is placed in the non-selected state. This state is caused in the following cases:
 - The selected slave is placed in the non-selected state when the slave receives a RESET command from the master.
 - The device that is switched from the master to a slave with a CHGMST command is placed in the non-selected state.

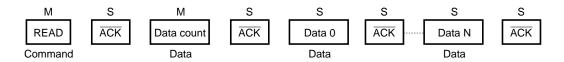
(iii) Command format

The transfer format of each command is described below.

<1> READ command

The READ command reads data from a slave. One to 256 bytes of data can be read. The data length is specified in a parameter by the master. When 00H is specified as the data length, the 256-byte data transfer is assumed.





Remark M: Output by the master S: Output by the slave

When the slave receives a transmission data count, if it has data enough for transmitting the specified number of bytes of data, the slave returns \overrightarrow{ACK} . If the slave does not have enough data for transmission, an error occurs; \overrightarrow{ACK} is not returned in this case. The master sends \overrightarrow{ACK} to the slave each time it receives one byte.

<2> WRITE command, END command, STOP command

These commands write data to a slave. One to 256 bytes of data can be written. The data length is specified in a parameter by the master. When 00H is specified as the data length, the 256-byte data transfer is assumed.

Figure 5-73. Transfer Format of the WRITE and END Commands



Remark M: Output by the master

S: Output by the slave

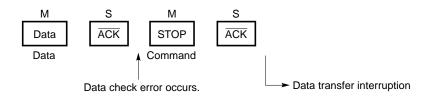
If the slave has an enough area for storing receive data of the specified length, the slave returns \overline{ACK} . If the slave does not have an enough area, an error occurs; \overline{ACK} is not returned in this case.

The master transmits an END command when all data have been transferred. The END command informs the slave that all data have been transferred correctly.

The slave accepts an END command even before data reception is uncompleted. In this case, the data received just before the acceptance of the END command becomes valid.

The master compares the contents of SIO before transfer with the contents of SIO after transfer to check whether the data has been output onto the bus correctly. If the contents of SIO disagree with each other, the master interrupts data transfer by transmitting a STOP command.





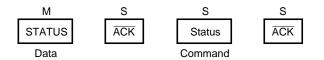
Remark M: Output by the master S: Output by the slave

When the slave receives a STOP command, the slave invalidates the most recently received one byte.

<3> STATUS command

The STATUS command reads the status of the current slave.

Figure 5-75. Transfer Format of the STATUS Command



Remark M: Output by the master

S: Output by the slave

The slave returns the status in the format shown in Figure 5-78.

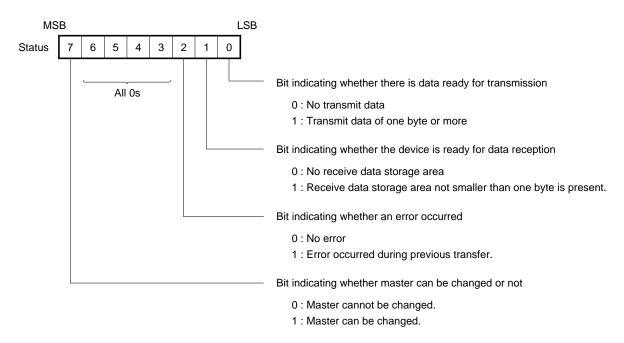


Figure 5-76. Status Format of the STATUS Command

When the master receives a status, it returns ACK to the current slave.

<4> RESET command

The RESET command changes the currently selected slave to a non-selected slave. When a $\overrightarrow{\mathsf{RESET}}$ command is transmitted, any slave can be placed in the non-selected state.

Figure 5-77. Transfer Format of the RESET Command



Remark M: Output by the master

S: Output by the slave

<5> CHGMST command

The CHGMST command passes the master authority to the currently selected slave.

Figure 5-78. Transfer Format of the CHGMST Command



Remark M: Output by the master

S: Output by the slave

When the slave receives a CHGMST command, the slave returns one of the following data to the master after checking whether the slave can receive the master authority:

- 0FFH: Master changeable
- 00H: Master not changeable

The slave compares the contents of SIO before transfer with the contents of SIO after transfer. If the contents of SIO disagree with each other, an error occurs; \overline{ACK} is not returned in this case.

If the master receives 0FFH, the master returns \overline{ACK} to the slave, and starts to operate as a slave. The slave which transmitted 0FFH starts to operate as the master when it receives \overline{ACK} .

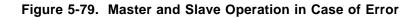
(iv) Error occurrence

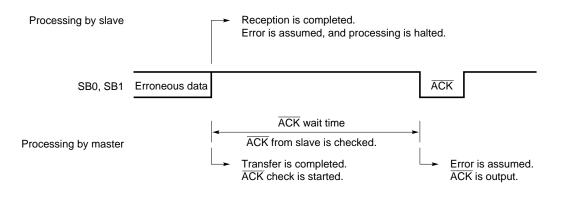
If a communication error occurs, the operation described below is performed.

The slave reports the occurrence of an error by not returning ACK to the master. If an error occurs during reception of data, the slave sets the status bit for indicating error occurrence, and cancels all command processing being performed.

When the transmission of one byte is completed, the master checks for ACK from the slave.

If \overline{ACK} is not returned from the slave within a predetermined period after transmission completion, the occurrence of an error is assumed; the master outputs the \overline{ACK} signal as a dummy.





The following errors may occur:

- · Error that may occur on the slave side
 - <1> Invalid command transfer format
 - <2> Reception of an undefined command
 - <3> Insufficient number of transfer data bytes for a READ command
 - <4> Insufficient area to contain data for a WRITE command
- <5> Change in data during transmission of a READ, STATUS, or CHGMST command
- If any of the above types of errors occurs, ACK is not returned.
- · Error that may occur on the master side

If data transmitted with a WRITE command changes during transmission, the master transmits a STOP command to the slave.

5.6.8 Manipulation of SCK Pin Output

The SCK/P01 pin has a built-in output latch, so that this pin allows static output by software manipulation in addition to normal serial clock output.

The number of SCK pulses can be software-set arbitrarily by manipulating the P01 output latch. (The SO/ SB0/P02 or SI/SB1/P03 pin is controlled by manipulating the RELT and CMDT bits of SBIC.)

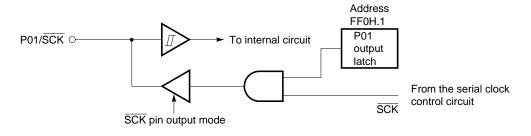
The procedure for manipulating SCK/P01 pin output is explained below.

- <1> Set serial operation mode register (CSIM) (SCK pin: output mode). When serial transfer is halted, SCK from the serial clock control circuit is set to 1.
- <2> Manipulate the P01 output latch by using a bit manipulation instruction.

Example	To output	one SCK/P01	pin clock	cycle by software
---------	-----------	-------------	-----------	-------------------

-	-	
SEL	MB15	; or CLR1 MBE
MOV	XA,#10000011B	; $\overline{\text{SCK}}$ (f _{CC} /2 ³), output mode
MOV	CSIM,XA	
CLR1	0FF0H.1	;
SET1	0FF0H.1	;

Figure 5-80. SCK/P01 Pin Circuit Configuration



The P01 output latch is mapped to bit 1 of address FF0H. A RESET signal sets the P01 output latch to 1.

Cautions 1. During normal serial transfer, the P01 output latch must be set to 1.

The P01 output latch cannot be addressed by specifying PORT0.1 (as described below). The address of the latch (0FF0H.1) must be coded in the operand of an instruction directly. Or, the address must be specified with SCKP. However, MBE = 0 (or MBE = 1, MBS = 15) must be specified before the instruction is executed.

No	t allowed	A	lowed
CLR1	PORT0.1	CLR1	0FF0H.1
SET1	PORT0.1	SET1	0FF0H.1
		CLR1	SCKP
		SET1	SCKP

*

5.7 BIT SEQUENTIAL BUFFER: 16-BIT

The bit sequential buffer (BSB) is special data memory for bit manipulations. In particular, the buffer allows bit manipulations to be performed very easily by sequentially changing address and bit specifications. So the buffer is useful in processing long data bit by bit.

This data memory consists of 16 bits, and allows pmem. @L addressing with a bit manipulation instruction. This addressing uses the L register for indirect bit specification. In this case, only by incrementing or decrementing the L register in a program loop, the bit to be manipulated can be sequentially shifted for continued processing.

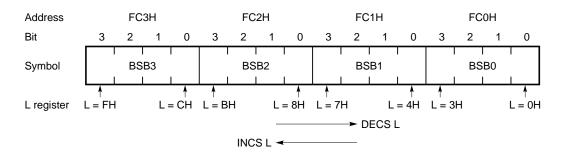


Figure 5-81. Format of the Bit Sequential Buffer

Remarks 1. With pmem.@L addressing, bit specification is shifted according to the L register.2. With pmem.@L addressing, BSB can be manipulated at any time regardless of MBE/MBS specification.

Data can also be manipulated by direct addressing. The buffer can be used for applications such as continuous 1-bit data input or output operations by combining direct 1-bit, 4-bit, and 8-bit addressing with pmem.@L addressing. In 8-bit manipulation, the higher eight bits or lower eight bits are manipulated by specifying BSB0 or BSB2.

Example To output 16-bit data of BUFF1 and BUFF2 serially from bit 0 of port 3:

	CLR1	MBE	
	MOV	XA,BUFF1	
	MOV	BSB0,XA	; Set BSB0 and BSB1
	MOV	XA,BUFF2	
	MOV	BSB2,XA	; Set BSB2 and BSB3
	MOV	L,#0	
LOOP0:	SKT	BSB0, @L	; Tests the specification bit of BSB
	BR	LOOP1	
	NOP		; Dummy (For timing adjustment)
	SET1	PORT3. 0	; Sets bit 0 of port 3
	BR	LOOP2	
LOOP1:	CLR1	PORT3.0	; Clears bit 0 of port 3
	NOP		; Dummy (For timing adjustment)
	NOP		
LOOP2:	INCS	L	; L <- L + 1
	BR	LOOP0	
	RET		

[MEMO]

CHAPTER 6 INTERRUPT AND TEST FUNCTIONS

The μ PD750108 has seven vectored interrupt sources and two test inputs, allowing a wide range of applications.

In addition, the interrupt control circuitry of the μ PD750108 has the following features for very high-speed interrupt processing.

(1) Interrupt functions

- (a) Hardware controlled vectored interrupt function which can control whether or not to accept an interrupt using the interrupt flag (IExxx) and interrupt master enable flag (IME).
- (b) The interrupt start address can be set arbitrarily.
- (c) Multiple interrupt function which can specify the priority by the interrupt priority specification register (IPS)
- (d) Test function of an interrupt request flag (IRQxxx)(The software can confirm that an interrupt occurred.)
- (e) Release of the standby mode (Interrupts released by an interrupt enable flag can be selected.)

(2) Test functions

- (a) Whether test request flags (IRQxxx) are issued can be checked with software.
- (b) Release of the standby mode (A test source to be released can be selected with test enable flags.)

6.1 CONFIGURATION OF THE INTERRUPT CONTROL CIRCUIT

Figure 6-1 shows the configuration of the interrupt control circuit. Each hardware item is mapped to a data memory space.

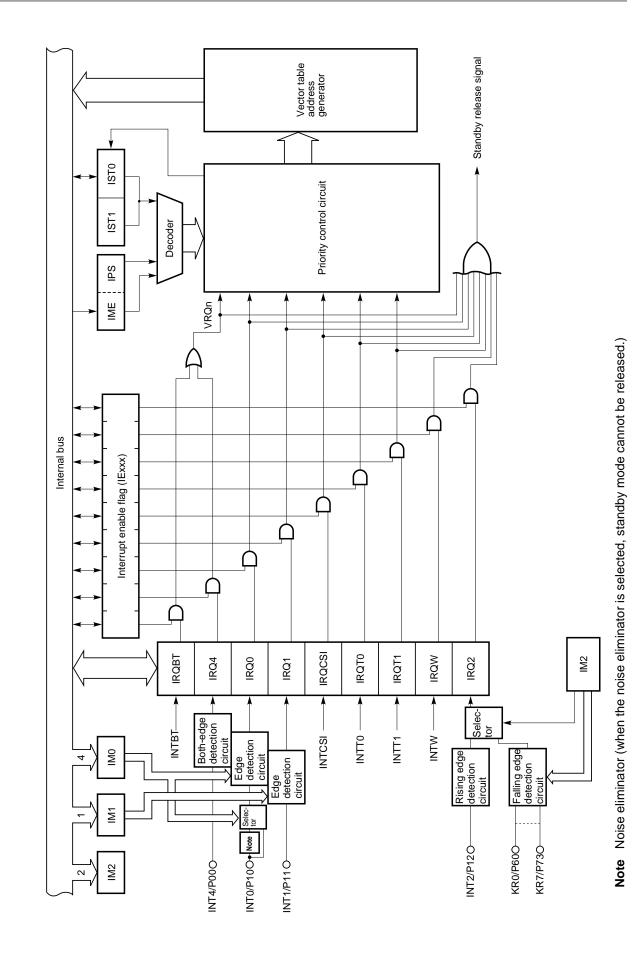


Figure 6-1. Block Diagram of Interrupt Control Circuit

6.2 TYPES OF INTERRUPT SOURCES AND VECTOR TABLES

Table 6-1 lists the types of interrupt sources, and Figure 6-2 shows vector tables.

Table 6-1. Interrupt Source

	Interrupt source signal	In/out	Interrupt priority ^{Note}	Vectored interrupt request (vector table address)
INTBT	Reference time interval signal from basic interval timer/wactchdog timer	In	1	VRQ1 (0002H)
INT4	Detection of both rising and falling	Out		
INT0	┌ Rising/falling edge	Out	2	VRQ2 (0004H)
INT1	_ detection specification_	Out	3	VRQ3 (0006H)
INTCSI	[Serial data transfer completion signal]	In	4	VRQ4 (0008H)
INTT0	Match signal between the count register of timer/event counter 0 and modulo register	In	5	VRQ5 (000AH)
INTT1	│ Match signal between the count │ register of timer counter 1 │ and modulo register │ │	In	6	VRQ6 (000CH)

Note The interrupt priority is used to determine the priority when two or more interrupts are simultaneously generated.

Address				
0000H	MBE	RBE	Internal reset start address	s (high-order 6 bits)
			Internal reset start address	s (low-order 8 bits)
0002H	MBE	RBE	INTBT/INT4 start address	(high-order 6 bits)
			INTBT/INT4 start address	(low-order 8 bits)
0004H	MBE	RBE	INT0 start address	(high-order 6 bits)
			INT0 start address	(low-order 8 bits)
0006H	MBE	RBE	INT1 start address	(high-order 6 bits)
			INT1 start address	(low-order 8 bits)
0008H	MBE	RBE	INTCSI start address	(high-order 6 bits)
			INTCSI start address	(low-order 8 bits)
000AH	MBE	RBE	INTT0 start address	(high-order 6 bits)
			INTT0 start address	(low-order 8 bits)
000CH	MBE	RBE	INTT1 start address	(high-order 6 bits)
			INTT1 start address	(low-order 8 bits)

Figure 6-2. Interrupt Vector Table

The column of interrupt priority in Table 6-1 indicates a priority assigned when multiple interrupt requests occur concurrently or are held.

A vector table contains interrupt processing start addresses and MBE and RBE setting values during interrupt processing. An assembler pseudo instruction (VENTn: n = 1 to 6) is used to set a vector table.

Example A vector table is set for INTBT/INT4.

VENT1 1 Vector table at address 0002

MBE = 0, RBE = 0,^` ۱ MBE-RBE setting value in interrupt service routine

GOTOBT

Symbol for indicating an interrupt service routine start address

Caution The contents (MBE, RBE, and start address) described in the operand of the VENTn (n = 1 to 6) instruction are stored in the vector table address at address 2n.

ExampleVector tables are set for INTBT/INT4 and INTT0.VENT1MBE = 0, RBE = 0, GOTOBT; INTBT/INT4 start addressVENT5MBE = 0, RBE = 1, GOTOT0; INTT0 start address

*

6.3 VARIOUS DEVICES TO CONTROL INTERRUPT FUNCTIONS

(1) Interrupt request flags and interrupt enable flags

The following seven interrupt request flags (IRQxxx) corresponding to the interrupt sources are provided.

INT0 interrupt request flag (IRQ0)	Serial interface interrupt request flag (IRQCSI)
INT1 interrupt request flag (IRQ1)	Timer/event counter interrupt request flag (IRQT0)
INT4 interrupt request flag (IRQ4)	Timer counter interrupt request flag (IRQT1)
BT interrupt request flag (IRQBT)	

An interrupt request flag is set to 1 by an interrupt request, and is automatically cleared to 0 when interrupt processing is performed. However, IRQBT and IRQ4 are cleared in a different way because these flags share a vector address. (See **Section 6.6**.)

The following seven interrupt enable flags (IExxx) corresponding to the interrupt request flags are provided.

INT0 interrupt enable flag (IE0)	Serial interface interrupt enable flag (IECSI)
INT1 interrupt enable flag (IE1)	Timer/event counter interrupt enable flag (IET0)
INT4 interrupt enable flag (IE4)	Timer counter interrupt enable flag (IET1)
BT interrupt enable flag (IEBT)	

An interrupt enable flag set to 1 enables the corresponding interrupt, and an interrupt enable flag set to 0 disables the corresponding interrupt.

When an interrupt request flag and the interrupt enable flag are set to 1, a vectored interrupt request (VRQn: n = 1 to 6) occurs. This condition is also used to release a standby mode.

A bit manipulation instruction or 4-bit memory manipulation instruction is used to manipulate an interrupt request flag and interrupt enable flag. A bit manipulation instruction allows direct manipulation regardless of MBE setting. An interrupt enable flag can be manipulated using an EI IExxx instruction or DI IExxx instruction. The SKTCLR instruction is usually used to test an interrupt request flag.

Example	EI	IE0	; Enable INT0
	DI	IE1	; Disable INT1
	SKTCLR	IRQCSI	; Skip and clear IRQCSI when it is set to 1.

When an interrupt request flag is set using an instruction, even if there is no interrupt request, a vectored interrupt is executed in the same way as when an interrupt is requested.

Inputting a RESET signal clears the interrupt request and interrupt enable flags to 0, disabling all interrupts.

Interrupt request flag	Set signals for interrupt request flags	Interrupt enable flag
IRQBT	Set by a reference time interval signal from the basic interval timer/watchdog timer.	IEBT
IRQ4	Set by a detected rising or falling edge of an INT4/P00 pin input signal.	IE4
IRQ0	Set by a detected edge of an INT0/P10 pin input signal. The detection edge is specified by the INT0 edge detection mode register (IM0).	IE0
IRQ1	Set by a detected edge of an INT1/P11 pin input signal. The detection edge is specified by the INT1 edge detection mode register (IM1).	
IRQCSI	Set by a serial data transfer completion signal for the serial interface.	IECSI
IRQT0	Set by a match signal from timer/event counter 0.	IET0
IRQT1	Set by a match signal from the timer counter. IET1	

Table 6-2.	Set Signals for	Interrupt Request Flags
------------	-----------------	-------------------------

(2) Interrupt priority specification register (IPS)

The interrupt priority specification register selects an interrupt with a higher priority from multiple interrupts using the low-order three bits.

Bit 3, interrupt master enable flag (IME), specifies whether to disable all interrupts.

The IPS is set using a 4-bit memory manipulation instruction. Bit 3 is set by an EI instruction and reset by a DI instruction.

When changing the low-order three bits of the IPS, interrupts must be disabled (IME = 0) beforehand.

 Example
 DI
 ; Disable interrupts

 CLR1
 MBE
 , MOV

 MOV
 A,#1011B
 , Assign a higher priority to INT1, then enable interrupts.

A RESET signal clears all bits to 0.

Caution Disable interrupts before setting the IPS.

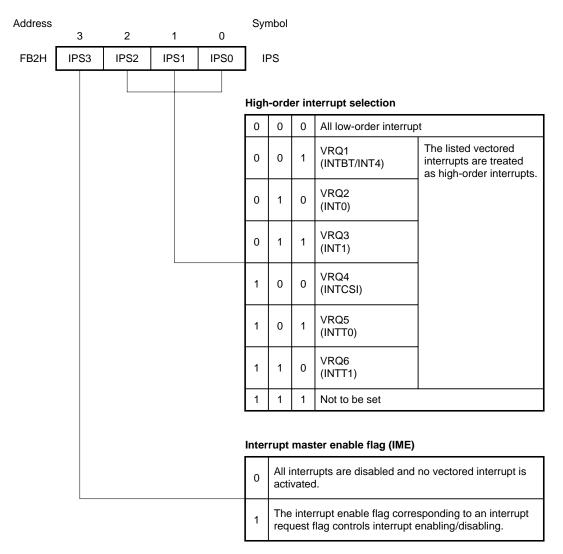


Figure 6-3. Interrupt Priority Specification Register

(3) Configurations of the INT0, INT1, and INT4 circuits

(a) As shown in Figure 6-4 (a), the INT0 circuit accepts an external interrupt at its rising or falling edge. The edge to be detected can be selected.

The INTO circuit has a noise elimination function (see **Figure 6-5**), called a noise eliminator, using a sampling clock, which removes pulses shorter than two sampling clock cycles^{Note} as noise. The INTO circuit may accept pulses which are longer than one sampling clock cycle and shorter than two cycles as interrupts depending on the sampling timing (see **Figure 6-4 (a)**). The circuit is sure to accept pulses equal to or longer than two sampling clock cycles as interrupts.

The INT0 pin is supplied with sampling clock Φ or f_{CC}/64, whichever is selected by bit 3 (IM03) of the INT0 edge detection mode register (IM0).

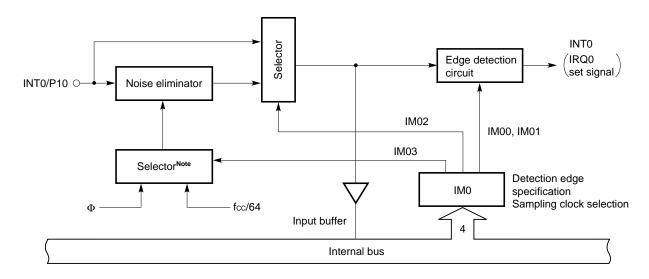
Bit 0 (IM00) and bit 1 (IM01) of the INT0 edge detection mode register (IM0) are used to select a detection edge.

Figure 6-6 (a) shows the format of IM0. A 4-bit memory manipulation instruction is used to set IM0. A $\overrightarrow{\mathsf{RESET}}$ signal clears all bits to 0, and a rising edge is specified to be detected.

- **Note** When the frequency of a sampling clock is Φ , these cycles are equal to $2t_{CY}$. When the frequency of a sampling clock is $f_{CC}/64$, these cycles are equal to $128/f_{CC}$.
- Cautions 1. Input a pulse wider than two sampling clock cycles to the INT0/P10 pin. Otherwise, the pulse is suppressed as noise by a noise eliminator when the pin is used as a port.
 - 2. When the noise eliminator is selected (IM02 is set to 0), INT0 does not operate in standby mode because INT0 requires a clock for sampling (the noise eliminator does not operate unless the CPU clock Φ is supplied). Do not select the noise eliminator when using INT0 to release standby mode (set IM02 to 1).
- (b) As shown in Figure 6-4 (b), the INT1 circuit accepts an external interrupt at its rising or falling edge.
 The INT1 edge detection mode register (IM1) is used to select a detection edge.
 Figure 6-6 (b) shows the format of IM1. A bit manipulation instruction is used to set IM1. A RESET signal clears all bits to 0, and a rising edge is specified to be detected.
- (c) As shown in Figure 6-4 (c), the INT4 circuit accepts an external interrupt at its rising and falling edges.

*

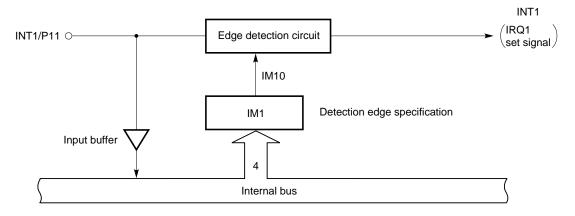




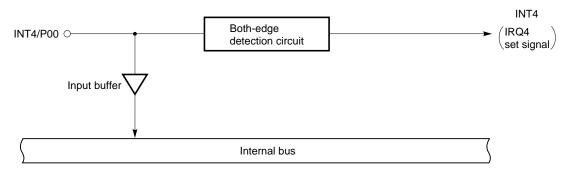
(a) Configuration of the INT0 circuit

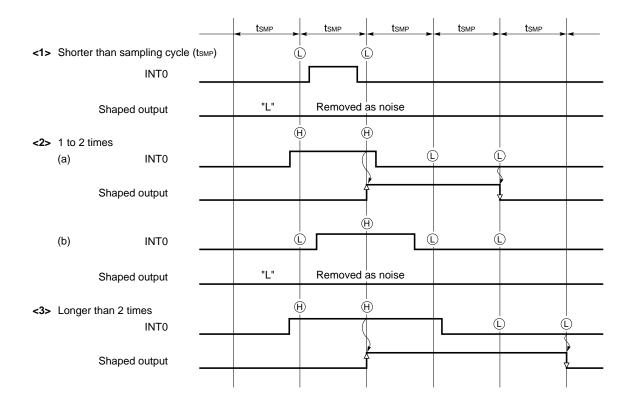
* Note Even if f_{CC}/64 is selected, HALT mode cannot be released by INT0.

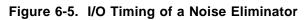
(b) Configuration of the INT1 circuit



(c) Configuration of the INT4 circuit



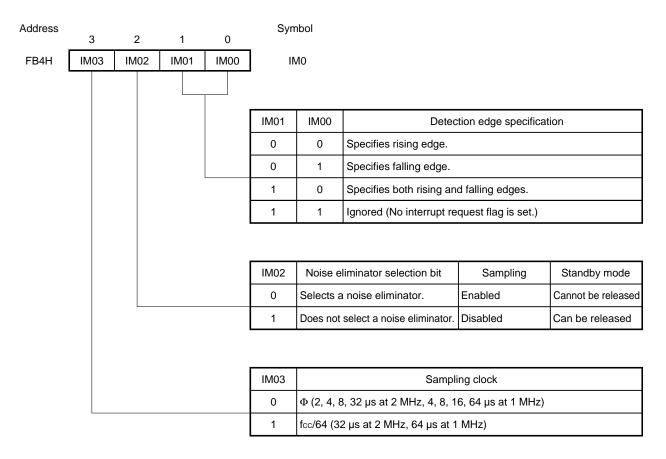




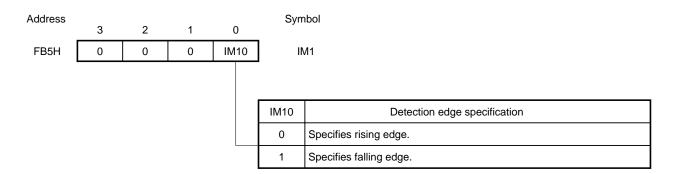
Remark $t_{SMP} = t_{CY} \text{ or } 64/f_{CC}$

Figure 6-6. Format of Edge Detection Mode Registers

(a) INT0 edge detection mode register (IM0)



(b) INT1 edge detection mode register (IM1)



Caution Changing the edge detection mode register may set an interrupt request flag. So, disable the interrupts before changing the edge detection mode register. Then clear the interrupt request flag with a CLR1 instruction and enable the interrupts. When f_{CC}/64 is selected as a sampling clock pulse in changing IM0, wait for 16 machine cycles after changing the mode register and clear the interrupt request flag.

(4) Interrupt status flags

The interrupt status flags (IST0 and IST1), which are contained in the PSW, indicate the status of processing currently executed by the CPU.

By using the content of these flags, the interrupt priority control circuit controls multiple interrupts as indicated in Table 6-3.

A 4-bit manipulation instruction or bit manipulation instruction can be used to set and reset IST0 and IST1, so that multiple interrupts are enabled by changing the current status of execution. IST0 and IST1 can be manipulated on a single-bit basis at any time regardless of MBE setting.

Before IST0 or IST1 is manipulated, the DI instruction must be executed to disable interrupts, then the EI instruction must be executed to enable interrupts.

IST1 and IST0 as well as the other PSW bits are saved in the stack memory when an interrupt is accepted and the status of IST0 and IST1 changes to a status one level higher. When a RETI instruction is executed, the former values of IST1 and IST0 are resumed.

Inputting a $\overline{\text{RESET}}$ signal clears the content of the flag to 0.

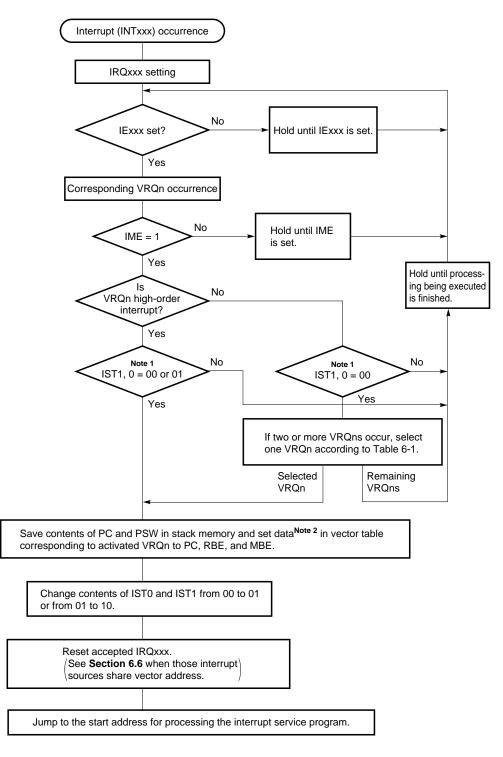
IST1	IST0	Processing	CPUL apprection	Interrupts that	After acceptance	
1311	1310	status	CPU operation	can be accepted	IST1	IST0
0	0	Status 0	Is processing the normal program.	All	0	1
0	1	Status 1	Is processing a low- or high-order interrupt.	Only high-order interrupts	1	0
1	0	Status 2	Is processing a high-order interrupt.	No		—
1	1	Not to be set				

Table 6-3. Interrupt Processing Statuses of IST0 and IST1

6.4 INTERRUPT SEQUENCE

When an interrupt occurs, it is processed using the procedure shown in Figure 6-7.

Figure 6-7. Interrupt Sequence



- Notes 1. IST0 and IST1 are the interrupt status flags (bits 3 and 2 of the PSW). (See Table 6-3.)
 - **2.** An interrupt service program start address and MBE and RBE setting values at the start of interrupt are stored in each vector table.

6.5 MULTIPLE INTERRUPT PROCESSING CONTROL

The μ PD750108 can handle multiple interrupts by either of the following methods.

(1) Multiple interrupt processing by a high-order interrupt

In this method, the μ PD750108 selects an interrupt source among multiple interrupt sources, enabling double interrupt processing.

That is, the high-order interrupt specified by the interrupt priority specification register (IPS) is enabled when the processing status is 0 or 1. Other interrupts (interrupts lower than the specified high-order interrupt) are enabled only when the status is 0. (See **Figure 6-8** and **Table 6-3**.)

When only one interrupt is used as a level-two interrupt, using this method saves the user the trouble of enabling or disabling interrupts during an interrupt processing, and holds down the number of nesting levels to two.

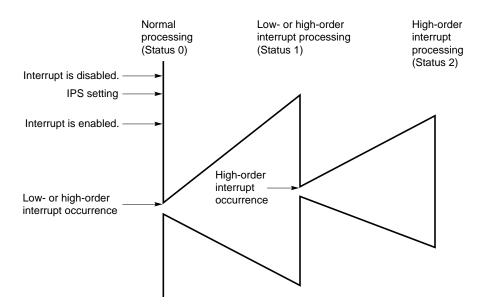


Figure 6-8. Multiple Interrupt Processing by a High-Order Interrupt

(2) Multiple interrupt processing by changing the interrupt status flags

Changing the interrupt status flags with the program causes multiple interrupts to be enabled. That is, when the interrupt processing program changes both IST1 and IST0 to 0 (status 0), multiple interrupt processing is enabled.

This method is used when two or more interrupts are to be enabled at a time or when the processing of three or more interrupts is to be performed.

When changing IST1 and IST0, interrupts must be disabled beforehand with a DI instruction.

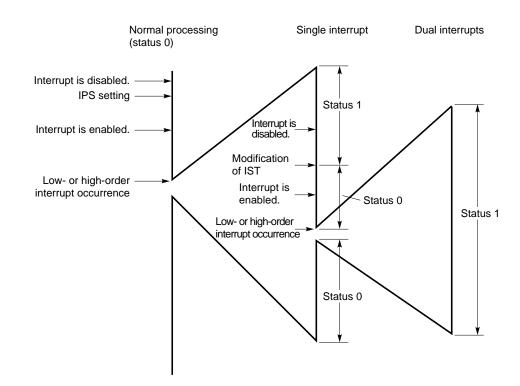


Figure 6-9. Multiple Interrupt Processing by Changing the Interrupt Status Flags

6.6 PROCESSING OF INTERRUPTS SHARING A VECTOR ADDRESS

Interrupt sources INTBT and INT4 share a vector table, so an interrupt source is selected as described below.

(1) Using only one interrupt

The interrupt enable flag for desired one of the two interrupt sources sharing a vector table is set to 1, and the interrupt enable flag for the other is cleared to 0. In this case, the enabled (IExxx = 1) interrupt source causes an interrupt request. When the interrupt request is accepted, the interrupt request flag is reset.

(2) Using both interrupts

The interrupt enable flags corresponding to the two interrupt sources are both set to 1. In this case, the logical sum of the interrupt request flags for the two interrupt sources is used as an interrupt request. In this case, even if an interrupt request or interrupt requests caused by the setting of one or both of the interrupt request flags are accepted, the interrupt request flags or flags are not reset.

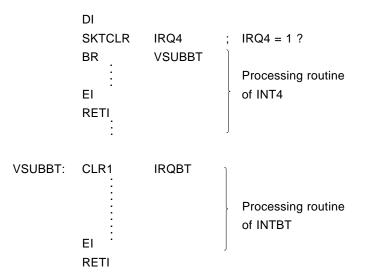
Accordingly, which of the two interrupt sources caused the interrupt needs to be determined using the interrupt service routine. For this determination, the DI instruction is to be executed at the start of the interrupt service routine, and the interrupt request flags are checked with the SKTCLR instruction.

If both the request flags are set when this request flag is tested or cleared, the interrupt request remains even if one of the request flags is cleared. If this interrupt is selected as having the higher priority, nesting processing is started by the remaining interrupt request.

Consequently, the interrupt request not tested is processed first. If the selected interrupt has the lower priority, the remaining interrupt is kept pending and therefore, the interrupt request tested is processed first. Therefore, an interrupt sharing a vector address with another interrupt is identified differently, depending whether it has the higher priority, as shown in Table 6-4.

Table 6-4. Identifying Interrupt Sharing Vector Table Address

With higher priority	Interrupt is disabled and interrupt request flag of interrupt that takes precedence is tested
With lower priority	Interrupt request flag of interrupt that takes precedence is tested



Examples 1. To use both INTBT and INT4 as having the higher priority and give priority to INT4

2. To use both INTBT and INT4 as having the lower priority and give priority to INT4

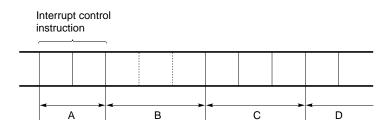
	SKTCLR BR	IRQ4 ; VSUBBT	IRQ4 = 1 ? Processing routine of INT4
	RETI	J	
VSUBBT:	CLR1	IRQBT	Processing routine of INTBT

6.7 MACHINE CYCLES FOR STARTING INTERRUPT PROCESSING

With the μ PD750108 series, the following machine cycles are used to start the execution of the interrupt service routine after an interrupt request flag (IRQxxx) is set.

(1) When IRQxxx is set during execution of an interrupt control instruction

When IRQxxx is set during execution of an interrupt control instruction, an instruction preceded by that instruction is executed, and an interrupt processing of three machine cycles is executed, then the interrupt service routine is started.

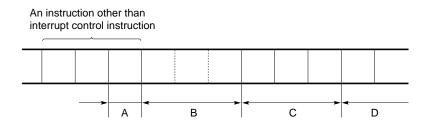


- A: IRQxxx is set.
- B: The next instruction is executed (1 to 3 machine cycles according to the instruction).
- C: Interrupt processing (3 machine cycles)
- D: Interrupt service routine is executed.
- Cautions 1. When interrupt control instructions are contiguous these interrupt control instructions are executed up to the last one. An instruction preceded by the interrupt control instruction executed last is executed, and an interrupt processing of three machine cycles is executed, then the interrupt service routine is started.
 - 2. When a DI instruction is executed in the period during which IRQxxx is set (A in the figure), or in the immediately following period, the interrupt request of the set IRQxxx is held until an EI instruction is executed.
- **Remarks 1.** An interrupt control instruction manipulates hardware (address FBxH in data memory) which handles interrupt processings. There are two types of interrupt control instruction, a DI instruction and an EI instruction.
 - **2.** Three machine cycles required for the interrupt processing include the time to manipulate the stack when an interrupt is accepted.

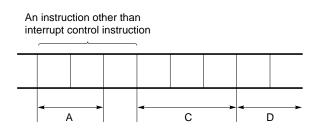
(2) When IRQxxx is set during an instruction other than that described in (1)

(a) When IRQxxx is set at the last machine cycle of the instruction being executed

In this case, an instruction preceded by the instruction being executed is executed, and an interrupt processing of three machine cycles is executed, then the interrupt service routine is started.



- A: IRQxxx is set.
- B: The next instruction is executed (1 to 3 machine cycles to the instruction).
- C: Interrupt processing (3 machine cycles)
- D: Interrupt service routine is executed.
- Caution When one or more interrupt control instructions follow, an instruction preceded by the interrupt control instructions is executed, and an interrupt processing of three machine cycles is executed, then the interrupt service routine is started. When an instruction to be executed after setting IRQxxx is a DI instruction, the interrupt request of the set IRQxxx is held.
- (b) When IRQxxx is set earlier than the last machine cycle of the instruction being executed In this case, after executing the instruction being executed, an interrupt processing of three machine cycles is executed, then the interrupt service routine is started.



- A: IRQxxx is set.
- C: Interrupt processing (3 machine cycles)
- D: Interrupt service routine is executed.

6.8 EFFECTIVE USE OF INTERRUPTS

The interrupt function can be used more effectively in the ways described below.

(1) MBE = 0 is set for the interrupt service routine

By allocating addresses 00H to 7FH as data memory used by the interrupt service routine and specifying MBE = 0 in an interrupt vector table, the user can code a program without being concerned with a memory bank.

If a program must use memory bank 1 for some reason, save the memory bank select register using the PUSH BS instruction before selecting memory bank 1.

(2) Use different register banks for the normal routine and interrupt routine.

The normal routine uses register banks 2 and 3 with RBE = 1 and RBS = 2. If the interrupt routine is for one nested interrupt, use register bank 0 with RBE = 0, so that you do not have to save or restore the registers. When two or more interrupts are nested, set RBE to 1, save the register bank by using the PUSH BS instruction, and set RBS to 1 to select register bank 1.

(3) Use of a software interrupt for debugging

Setting an interrupt request flag using an instruction has the same effect as the occurrence of an interrupt. Debug operation for irregular interrupts or concurrently occurring interrupts can be performed more efficiently by setting the interrupt request flags using an instruction.

6.9 INTERRUPT APPLICATIONS

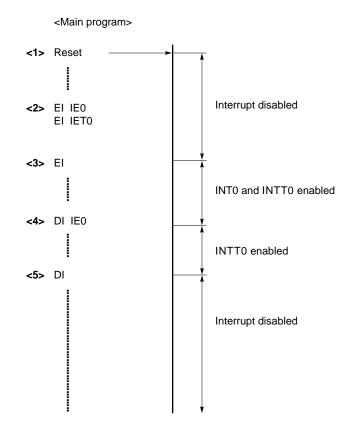
To use the interrupt function, a main program must:

- (a) Set a desired interrupt enable flag (using the EI IExxx instruction)
- (b) Select an active edge when INT0 or INT1 is used (set IM0 or IM1)
- (c) To use nesting (of an interrupt with the higher priority), set IPS (IME can be set at the same time).
- (d) Set the interrupt master enable flag (IME) using the EI instruction

In the interrupt routine, MBE and RBE are set by the vector table. However, when the interrupt specified as having the higher priority is processed, the register bank must be saved and set.

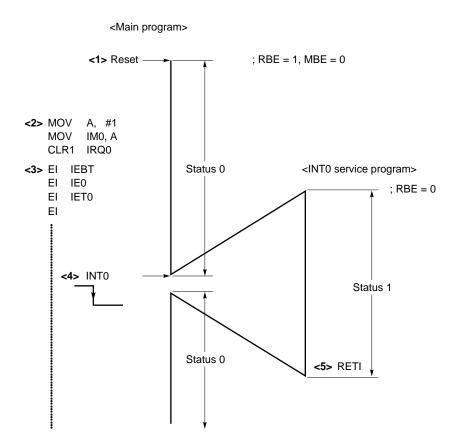
To return from the interrupt routine, use the RETI instruction.

(1) Interrupt enable/disable



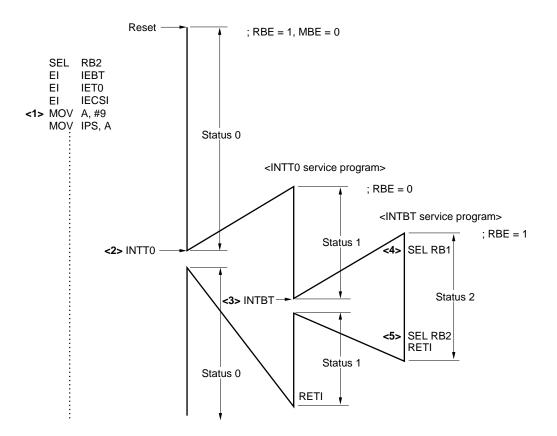
- <1> A RESET signal disables all interrupts.
- <2> Interrupt enable flags are set by the EI IExxx instruction. At this stage, all interrupts are disabled.
- <3> The interrupt master enable flag is set by the EI instruction. At this stage, INTO and INTTO are enabled.
- <4> An interrupt enable flag is cleared by the DI IExxx instruction to disable INT0.
- <5> The DI instruction disables all interrupts.

(2) Example of using INTBT, INTO (falling edge active), and INTTO without multiple interrupt processing



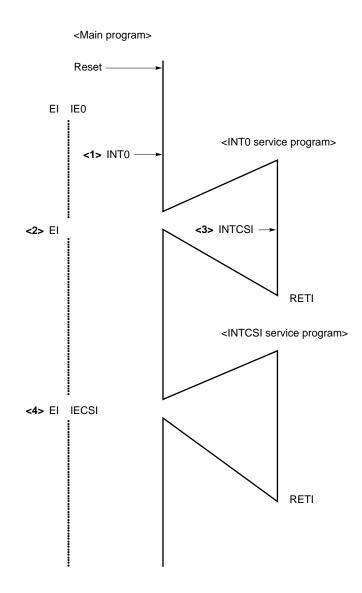
- <1> A RESET signal disables all interrupts, setting status 0.
- <2> INT0 is set to be falling edge active.
- <3> Interrupts are enabled by the EI and EI IExxx instructions.
- <4> On the falling edge of INT0, the INT0 interrupt service program is started, status is set to 1, and all interrupts are disabled.
- <5> Control is returned from the interrupts by the RETI instruction, status 0 is set again, and interrupts are enabled.
- **Remark** If all the interrupts are used as having the lower priority as shown in this example, saving or restoring the register bank is not necessary if RBE = 1 and RBS = 2 for the main program and register banks 2 and 3 are used, and RBE = 0 for the interrupt service program and register banks 0 and 1 are used.

(3) Nesting of interrupts with higher priority (INTBT has higher priority and INTT0 and INTCSI have lower priority)



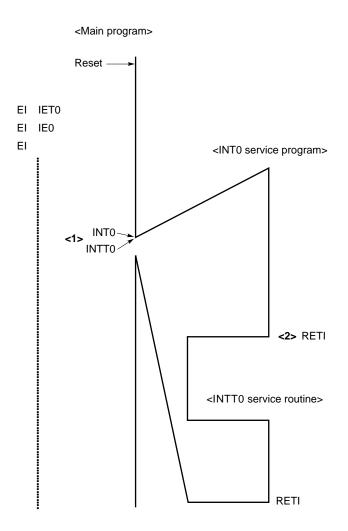
- <1> INTBT is specified as having the higher priority by setting of IPS, and the interrupt is enabled at the same time.
- <2> INTTO service program is started when INTTO with the lower priority occurs. Status 1 is set and the other interrupts with the lower priority are disabled. RBE = 0 to select register bank 0.
- <3> INTBT with the higher priority occurs. The level-two interrupts occurs. The status is changed to 0 and all the interrupts are disabled.
- <4> RBE = 1 and RBS = 1 to select register bank 1 (only the registers used may be saved by the PUSH instruction).
- **<5>** RBS is returned to 2, and execution returns to the main program. The status is returned to 1.





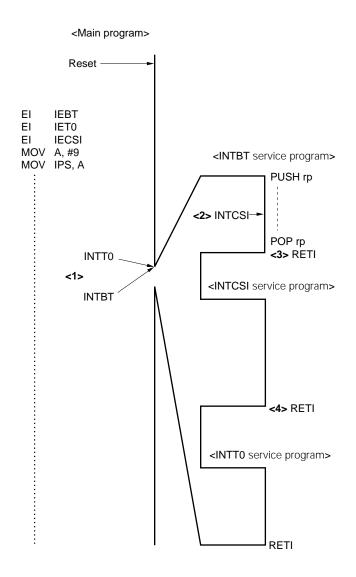
- <1> If INT0 is set when interrupts are disabled, the interrupt request flag is held.
- <2> When the interrupt is enabled by the EI instruction, the INT0 interrupt service program starts.<3> Same as <1>
- <4> When the held INTCSI flag is enabled, the INTCSI interrupt service program starts.

(5) Execution of held interrupts – two interrupts with lower priority occur concurrently –



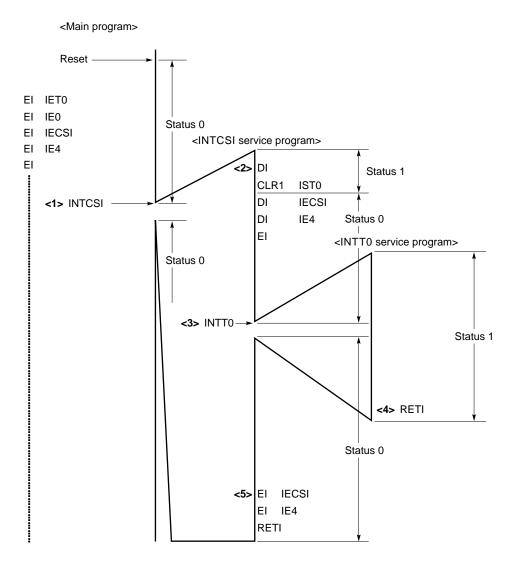
- <1> When INT0 and INTT0 with the lower priority occur concurrently (during execution of the same instruction), INT0, with a higher priority, is executed first. (INTT0 is held.)
- <2> When the INT0 interrupt service program has been executed, the RETI instruction is executed to start the interrupt service program for INTT0, which has been held.

(6) Executing pending interrupt – interrupt occurs during interrupt processing (INTBT has higher priority and INTT0 and INTCSI have lower priority) –



- <1> When INTBT with the higher priority and INTTO with the lower priority occur at the same time, the processing of the interrupt with the higher priority is started (if there is no possibility that an interrupt with the higher priority occurs while another interrupt with the higher priority is processed, DI IExx is not necessary).
- <2> When an interrupt with the lower priority occurs while the interrupt with the higher priority is executed, the interrupt with the lower priority is kept pending.
- <3> When the interrupt with the higher priority has been processed, INTCSI with the higher priority of the pending interrupts is executed.
- <4> When the processing of INTCSI has been completed, the pending INTT0 is processed.

(7) Enabling of level-two interrupts (enabling level-two INTT0 and INT0 interrupts with INTCSI and INT4 handled as level-one interrupts)



- <1> When an INTCSI interrupt not allowed to be a level-two interrupt occurs, the INTCSI service program starts, and status 1 is set.
- <2> Status 0 is set by clearing IST0. INTCSI and INT4 not allowed to be level-two interrupts are disabled.
- <3> When INTT0 allowed to be a level-two interrupt occurs, the level-two interrupt is executed, and status 1 is set to disable all interrupts.
- <4> When INTT0 processing is completed, status 0 is set again.
- <5> INTCSI and INT4 which have been disabled are enabled, then control returns.

6.10 TEST FUNCTION

6.10.1 Test Sources

The µPD750108 has two test sources. INT2 provides two types of edge-detection-test inputs.

Table 6-5. Test Source

	Test source	Internal/external
INT2	(detection of the rising edge of the signal input to the INT2 pin or that of the first falling edge of the signals input to KR0 to KR7)	External
INTW	(signal from clock timer)	Internal

6.10.2 Hardware to Control Test Functions

(1) Test request flags, test enable flags

Test request flags (IRQxxx) are set to 1 when the corresponding test requests (INTxxx) are issued. Clear the test request flags to 0 with the software once the test processing has been executed.

Test enable flags (IExxx) correspond to test request flags. The test enable flags enable the standby release signal when they are set to 1. They disables the standby release signal when they are set to 0. When both a test request flag and the corresponding test enable flag are set to 1, the standby release signal is generated.

Table 6-6 shows the signals which set test request flags.

Table 6-6. Signals Setting Test Request Flags

Test request flag	Signals setting test request flags	Test enable flag	
IRQW	Signal from the clock timer.	IEW	
IRQ2	Detection of the rising edge of INT2/P12 pin input signal or the first falling edge of the signals input to the KR0/P60 to KR7/P73 pins. The detection edge is selected with the INT2 edge detection mode register (IM2).	IE2	

(2) INT2 and key interrupt (KR0 to KR7) hardware

Figure 6-10 shows the configuration of INT2 and KR0 to KR7.

The IRQ2 set signal is output in either of the following edge detection modes, which is selected with the INT2 edge detection mode register (IM2).

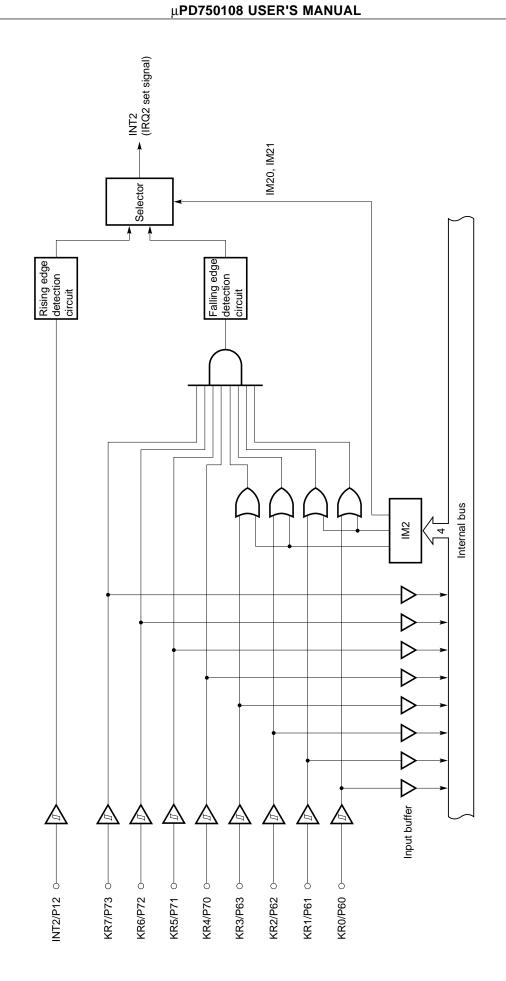
(a) Detection of a rising edge on the INT2 input pin

IRQ2 is set when a rising edge is detected on the INT2 input pin.

(b) Detection of a falling edge on any of the KR0 to KR7 input pins (key interrupt)

One of the pins KR0 to KR7 is selected to be used for interrupt input with the INT2 edge detection mode register (IM2). When a falling edge of one of input signals applied to the selected pin is detected, IRQ2 is set.

Figure 6-11 shows the format of IM2. IM2 is set using a 4-bit manipulation instruction. When the RESET signal is generated, all bits are cleared to 0, and the rising edge on INT2 is specified.



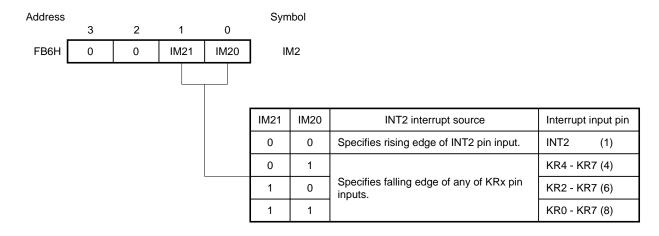


Figure 6-11. Format of INT2 Edge Detection Mode Register (IM2)

- Cautions 1. When the edge detection mode register is modified, test request flags may be set in some cases. So, disable test inputs before modifying the edge detection mode register. Then, clear the test request flags using a CLR1 instruction before enabling test inputs.
 - 2. When a low-level signal is applied to any of the pins subjected to falling edge detection, IRQ2 is not set when a falling edge is detected on another pin.

[MEMO]

CHAPTER 7 STANDBY FUNCTION

The μ PD750108 provides a standby function to reduce the power consumption by the system. The standby function is available in the two modes: the STOP mode and HALT mode.

Differences between these two modes are as follows:

(1) STOP mode

In the STOP mode, the main system clock oscillator is stopped, and the entire system stops. The current used by the CPU is reduced to quite a low level.

In addition, the contents of data memory can be preserved with a low supply voltage of down to V_{DD} = 1.8 V, that is, this mode is effective to retain data memory with a very low current.

The wait time applied when STOP mode is released by an interrupt request can be specified as $2^{9}/f_{CC}$ or no wait, by using a mask option. To start processing immediately upon the detection of an interrupt request, select no wait. The μ PD75P0116, however, does not have a mask option and its wait time is fixed to $2^{9}/f_{CC}$.

If 29/f_{CC} has been selected and processing must be started immediately upon the detection of an interrupt request, select HALT mode.

(2) HALT mode

In the HALT mode, the CPU clock is stopped, but the oscillation of the system clock oscillator continues. In this mode, the system uses more current than in the STOP mode. However, the HALT mode is suitable for starting processing immediately after an interrupt request or for intermittent operations such as watch operation.

In either mode, all contents of the registers, flags, and data memory that are present immediately before the standby mode is set are preserved. In addition, the states of the output latches of the I/O ports and the states of the output buffers are also preserved, so that the states of the I/O ports are to be processed to minimize the power consumption of the entire system.

- Cautions 1. The STOP mode can be used only for the main system clock. (Subsystem clock generation cannot be terminated.) The HALT mode can be used for either the main system clock or the subsystem clock.
 - 2. If the STOP mode is set when main system clock f_{CC} is used for clock timer operation, the clock stops operating. For continued operation, the clock must be changed to subsystem clock f_{XT} before the STOP mode is set.
 - 3. A lower power consumption and lower-voltage operation are enabled by switching standby modes or switching CPU and system clocks. However, a switching time as described in Section 5.2.3 is required before operation is started with a new clock after the clock is selected with the control register. For this reason, when the clock switching function is used together with a standby mode, the standby mode must be set after a time needed for switching elapses.
 - 4. Configure I/O ports for minimum power consumption in the stand by mode. Be sure to connect signals which are high or low to input ports.

7.1 SETTING OF STANDBY MODES AND OPERATION STATUS

Item		STOP mode	HALT mode	
Instruction for setting		STOP instruction	HALT instruction	
System clock for setting		Can be set only when operating on the main system clock	Can be set either with the main system clock or the subsystem clock	
Operation status	Clock oscillator	The main system clock stops its operation	Only the CPU clock Φ stops its operation (oscillation continues)	
	Basic interval timer/watchdog timer	Does not operate	Can operate only at main system clock oscillation. (IRQBT is set at reference time intervals.)	
	Serial interface	Can operate only when the external SCK input is selected for the serial clock	Can operate only when external SCK input is selected as the serial clock or at main system clock oscillation.	
	Timer/event counter	Can operate only when the TI0 pin input is selected for the count clock	Can operate only when TI0 pin input is specified as the count clock or at main system clock oscillation.	
	Timer counter	Does not operate	Can operate ^{Note 1}	
	Clock timer	Can operate when $f_{\mbox{\scriptsize XT}}$ is selected as the count clock	Can operate	
	External interrupt	INT1, INT2, and INT4 can operate. Only INT0 cannot operate. ^{Note 2}		
	CPU	Does not operate		
Release signal		An interrupt request signal from hardware whose operation is enabled by the interrupt enable flag or the generation of a RESET signal		

Table 7-1. Operation Statuses in the Standby Mode

Notes 1. Operation is possible only when the main system clock operates.

 Operation is possible only when the noise eliminator is not selected by bit 2 of the edge detection mode register (IM0) (when IM02 = 1).

A STOP instruction is used to set the STOP mode, and a HALT instruction is used to set the HALT mode. (A STOP instruction sets bit 3 of PCC, and a HALT instruction sets bit 2 of PCC.)

STOP instruction or HALT instruction must always be followed by an NOP instruction.

When changing a CPU operation clock pulse with the low-order two bits of PCC, a time lag may occur from the time when PCC is rewritten as shown in **Table 5-5** to the time when the CPU clock signal is changed. When changing an operation clock pulse before the standby mode or a CPU clock signal after the standby mode is released, it is necessary to rewrite PCC and set the standby mode after as many machine cycles as required to change the CPU clock pulse have elapsed.

In a standby mode, the contents of all registers and data memory that are stopped during the standby mode, including general registers, flags, mode registers, and output latches, are retained.

Caution Reset all the interrupt request flags before setting the standby mode. If an interrupt source whose interrupt request flag and interrupt enable flag are both set exists, the initiated standby mode is released immediately after it is set (see Figure 6-1). When the STOP mode is set, however, the μ PD750108 enters the HALT mode immediately after the STOP instruction is executed, then returns to the operation mode after the specified wait time^{Note} has elapsed.

Note Either of the following can be selected by using a mask option:

- 2⁹/f_{CC} (256 μs at 2 MHz, 512 μs at 1 MHz)
- No wait

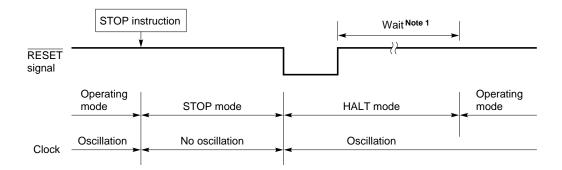
The μ PD75P0116, however, does not have a mask option. Its wait time is fixed to $2^{9}/f_{CC}$.

7.2 RELEASE OF THE STANDBY MODES

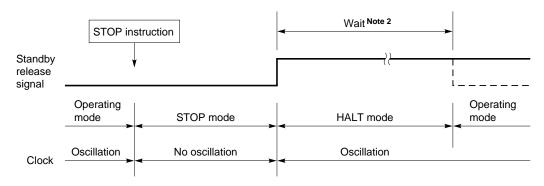
The STOP mode and HALT mode are released by a RESET signal or the generation of an interrupt request signal that is enabled with the interrupt enable flag. Figure 7-1 shows how the STOP and HALT modes are released.

Figure 7-1. Standby Mode Release Operation (1/2)

(a) Release of the STOP mode by RESET signal



(b) Release of the STOP mode by the occurrence of an interrupt



Notes 1. $56/f_{CC}$ (28 µs at 2 MHz, 56 µs at 1 MHz)

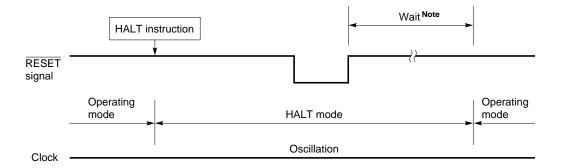
- 2. Either of the following can be selected by using a mask option:
 - 2⁹/f_{CC} (256 μs at 2 MHz, 512 μs at 1 MHz)
 - No wait

The μ PD75P0116, however, does not have a mask option. Its wait time is fixed to 2⁹/f_{CC}.

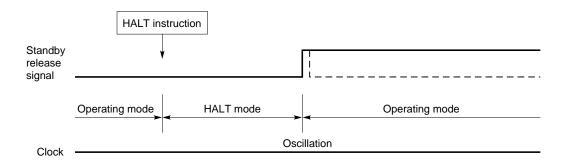
Remark The dashed line indicates the case where the interrupt request that releases the standby mode is accepted.

Figure 7-1. Standby Mode Release Operation (2/2)

(c) Release of the HALT mode by RESET signal



(d) Release of the HALT mode by the occurrence of an interrupt



Note 56/f_{CC} (28 μ s at 2 MHz, 56 μ s at 1 MHz)

Remark The dashed line indicates the case where the interrupt request that releases the standby mode is accepted.

7.3 OPERATION AFTER A STANDBY MODE IS RELEASED

- (1) If a standby mode is released by a RESET signal, normal reset operation is performed.
- (2) If a standby mode is released by the occurrence of an interrupt request, the contents of the interrupt master enable flag (IME) determines whether to perform a vectored interrupt when the CPU resumes instruction execution.

(a) When IME = 0

If a standby mode is released, execution restarts with the instruction immediately following the instruction used to set the standby mode.

The interrupt request flag is held.

(b) When IME = 1

If a standby mode is released, a vectored interrupt is executed after the two instructions are executed. However, if the standby mode is released by INT2 or INTW (testable input), no vectored interrupt occurs, and the same processing as (a) above is performed.

7.4 SELECTION OF A MASK OPTION

For the standby function of the μ PD750108, the wait time applied when STOP mode is released by an interrupt can be set to either of the following by using a mask option:

<1> 29/f_{CC} (256 μs at 2 MHz, 512 μs at 1 MHz)

<2> No wait

The μ PD75P0116, however, does not have a mask option. Its wait time is fixed to 2⁹/f_{CC}.

7.5 APPLICATIONS OF THE STANDBY MODES

When the standby modes are used, the following steps are used.

- <1> Detect a standby mode setting factor such as power removal on an interrupt input or port input. (INT4 is useful for power removal detection.)
- <2> Configure I/O ports for minimum current drain.
- <3> Specify interrupts for releasing a standby mode. (INT4 is useful. All interrupt enable flags not used for release are to be cleared.)
- <4> Specify an operation to be performed after release. (IME is to be manipulated according to whether interrupt processing is performed or not.)
- <5> Specify a CPU clock to be used after release. (If the CPU clock is changed, required machine cycles must elapse before the standby mode is set.)
- **<6>** Select a wait time to be used when a standby mode is released.
- <7> Set a standby mode using a STOP or HALT instruction.

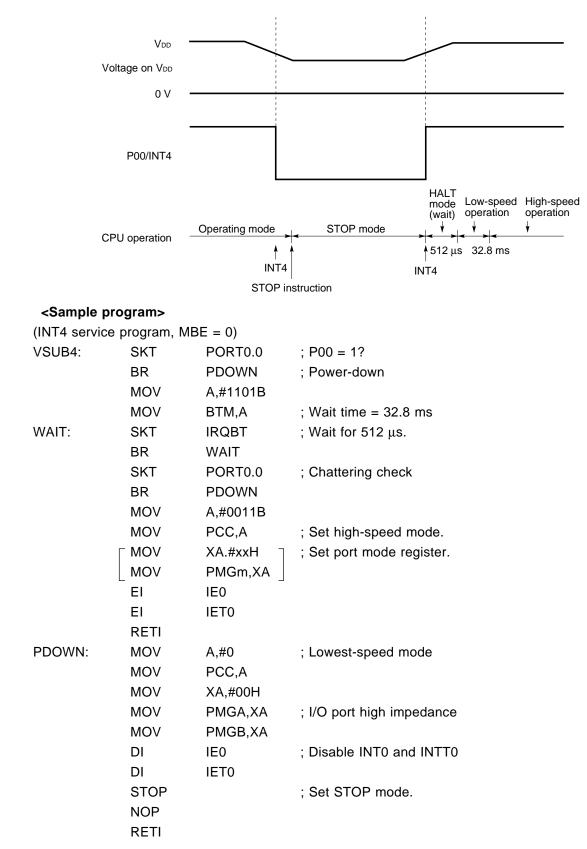
A standby mode when combined with the system clock switch function enables a lower power consumption and lower-voltage operation.

(1) Application of the STOP mode (at $f_{CC} = 1 \text{ MHz}$)

<Use of the STOP mode under the following conditions>

- The STOP mode is set on the falling edge of INT4, and is released on the rising edge of INT4. (INTBT is not used.)
- All I/O ports have a high impedance.
- The INT0 and INTT0 interrupts are used for the program, but are not used to release the STOP mode.
- After the STOP mode is released, interrupts are enabled.
- After the STOP mode is released, operation is started using the lowest-speed CPU clock.
- The wait time applied when the STOP mode is released is set to 512 μ s by using a mask option.
- After the STOP mode is released, another wait time of 32.8 ms is used for stable power supply operation. The P00/INT4 pin is checked twice to remove chattering.

* <Timing chart>

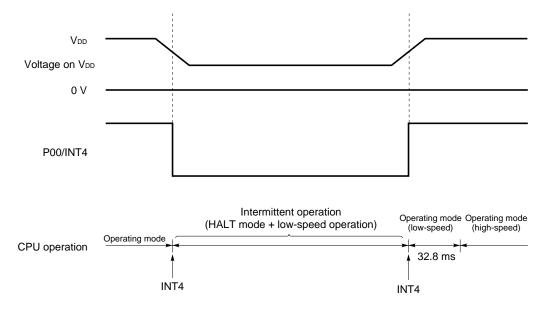


(2) Application of the HALT mode (at $f_{CC} = 1 \text{ MHz}$)

<Intermittent operation under the following conditions>

- The main system clock is switched to the subsystem clock on the falling edge of INT4.
- The oscillation of the main system clock is stopped, and HALT mode is set.
- In the standby mode, intermittent operation is performed at intervals of 0.5 s.
- The subsystem clock is switched back to the main system clock on the rising edge of INT4.
- INTBT is not used.
- After the STOP mode is released, another wait time of 32.8 ms is used for stable power supply operation. The P00/INT4 pin is checked twice to remove chattering.

* <Timing chart>



(Initialization)	9.4		
(MOV	A,#0011B	
	MOV	PCC,A	; High-speed mode
	MOV	XA,#05	
	MOV	WM,XA	; Subsystem clock
	EI	IE4	, ,
	EI	IEW	
	EI		; Enable interrupt
(Main routine)			,
(SKT	PORT0.0	; Power normal?
	HALT		; Power-down mode
	NOP		; Power normal?
	SKTCLR	IRQW	; Flag set for 0.5 second?
	BR	MAIN	; NO
	CALL	WATCH	; Clock subroutine
MAIN:		WATON	
(INT4 service	routine)		
VINT4:	SKT	PORT0.0	; Power normal? MBE = 0
VIII 1.	BR	PDOWN	
	CLR1	SCC.3	; Start main system clock oscillation
	MOV	A,#0DH	
	MOV	BTM,A	
WAIT1:	SKT	IRQBT	; Wait for 32.8 ms
	BR	WAIT1	, wait for 62.0 ms
	SKT	PORT0.0	; Chattering check
	BR	PDOWN	, chatching chock
	CLR1	SCC.0	; Switch to main system clock
	RETI	000.0	, ewiter to main system clock
PDOWN:	SET1	SCC.0	; Switch to subsystem clock
i bown.	MOV	A,#0AH	, Owned to subsystem clock
WAIT2:	INCS	A,#0A11 A	; Wait for 15 machine cycles
vv/\\\ \	BR	WAIT2	
	SET1	SCC.3	; Stop main system clock oscillation
	RETI	000.0	

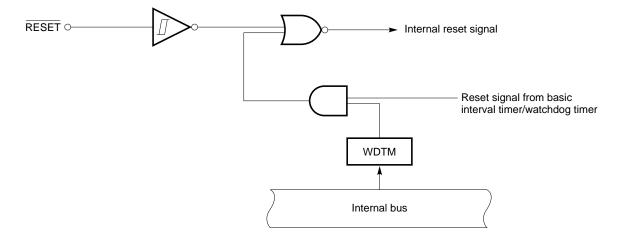
<Sample program>

Caution Before the system clock is changed from the main system clock to the subsystem clock, a wait time sufficient for stable subsystem clock generation is required.

[MEMO]

CHAPTER 8 RESET FUNCTION

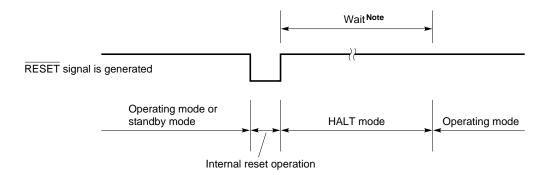
The μ PD750108 is reset with the external reset signal (RESET) or the reset signal received from the basic interval timer/watchdog timer. When either reset signal is input, the internal reset signal is generated. Figure 8-1 shows the configuration of the reset circuit.





When the RESET signal is generated, all hardware is initialized as indicated in Table 8-1. Figure 8-2 shows the reset operation timing.

Figure 8-2. Reset Operation by Generation of RESET Signal



Note $56/f_{CC}$ (28 µs at 2 MHz, 56 µs at 1 MHz).

	Hardware		Generation of a RESET signal in a standby mode	Generation of a RESET signal during operation	
μPD750106, μPD750108			4 low-order bits at address 0000H in program memory are set in PC bits 11 to 8, and the data at address 0001H are set in PC bits 7 to 0.	4 low-order bits at address 0000H in program memory are set in PC bits 11 to 8, and the data at address 0001H are set in PC bits 7 to 0.	
			5 low-order bits at address 0000H in program memory are set in PC bits 12 to 8, and the data at address 0001H are set in PC bits 7 to 0.	5 low-order bits at address 0000H in program memory are set in PC bits 12 to 8, and the data at address 0001H are set in PC bits 7 to 0.	
	μPD75P0116		6 low-order bits at address 0000H in program memory are set in PC bits 13 to 8, and the data at address 0001H are set in PC bits 7 to 0.	6 low-order bits at address 0000H in program memory are set in PC bits 13 to 8, and the data at address 0001H are set in PC bits 7 to 0.	
PSW	Carry flag (CY)		Held	Undefined	
	Skip flags (SK0 t	•	0	0	
	-	lags (IST0, IST1)	0	0	
	Bank enable flag	s (MBE, RBE)	Bit 6 at address 0000H in program memory is set in RBE, and bit 7 is set in MBE.	Bit 6 at address 0000H in program memory is set in RBE, and bit 7 is set in MBE.	
Stack p	pointer (SP)		Undefined	Undefined	
Stack b	pank selection reg	ister (SBS)	1000B	1000B	
Data m	nemory (RAM)		Held	Undefined	
Genera	al registers (X, A,	H, L, D, E, B, C)	Held	Undefined	
Bank s	election register (I	MBS, RBS)	0, 0	0, 0	
Basic	Counter (B	Τ)	Undefined	Undefined	
interva		ter (BTM)	0	0	
timer/w dog tin	Watchdog t	imer enable flag	0	0	
Timer/	Counter (T	0)	0	0	
event		ister (TMOD0)	FFH	FFH	
counte	r Mode regis	ter (TM0)	0	0	
	TOE0, TOL	JT flip-flop	0, 0	0, 0	
Timer	Counter (T	1)	0	0	
counte	r Modulo reg	isters (TMOD1)	FFH	FFH	
	Mode regis	ter (TM1)	0	0	
	TOE1, TOL	JT flip-flop	0, 0	0, 0	
Clock t	imer Mode regis	ter (WM)	0	0	
Serial	Shift registe	er (SIO)	Held	Undefined	
interfac	ce Operation r (CSIM)	node register	0	0	
	SBI control	register (SBIC)	0	0	
	Slave addre	ess register (SVA)	Held	Undefined	

Table 8-1. Status of the Hardware after a Reset (1/2)

	Hardware	Generation of a RESET signal in a standby mode	Generation of a RESET signal during operation
Clock generator,	Processor clock control register (PCC)	0	0
clock output	System clock control register (SCC)	0	0
circuit	Clock output mode register (CLOM)	0	0
Sub-oscillator	control register (SOS)	0	0
Interrupt	Interrupt request flag (IRQxxx)	Reset (0)	Reset (0)
	Interrupt enable flag (IExxx)	0	0
	Priority selection register (IPS)	0	0
	INT0, INT1, and INT2 mode registers (IM0, IM1, IM2)	0, 0, 0	0, 0, 0
Digital	Output buffer	Off	Off
ports	Output latch	Clear (0)	Clear (0)
	I/O mode registers (PMGA, PMGB, PMGC)	0	0
	Pull-up resistor specification register (POGA, POGB)	0	0
Bit sequential	buffers (BSB0 to BSB3)	Held	Undefined

Table 8-1. Statuses of the Hardware after a Reset (2/2)

[MEMO]

CHAPTER 9 WRITING TO AND VERIFYING PROGRAM MEMORY (PROM)

The program memory in the μ PD75P0116 consists of a one-time PROM (16384 x 8 bits).

Writing to and verifying the contents of the one-time PROM is accomplished by using the pins shown in the table below. Note that address inputs are not used; instead, the address is updated using the clock input from the CL1 pin.

Pin name	Function
V _{PP}	Voltage is applied to this pin when writing to the program memory or verifying its contents (normally V_{DD} electric potential).
CL1, CL2	An address update clock, used when writing to program memory or verifying its contents, is input to the CL1 pin. Leave the CL2 pin open.
MD0 to MD3	Operation mode selection pins used when writing to the program memory or verifying its contents.
D0/P40 to D3/P43 (low-order four bits) D4/P50 to D7/P53 (high-order four bits)	I/O pins for 8-bit data used when writing to the program memory or verifying its contents.
V _{DD}	Power voltage is applied to this pin. During normal operation, 1.8 to 5.5 V should be applied; +6 V should be applied when writing to the program memory or verifying its contents.

- Cautions 1. The μ PD75P0116CU/GB does not have an erasure window, so the erasing with ultraviolet radiation cannot be performed.
 - 2. Handle the pins not used for writing to or verifying the program memory, as follows:
 - Pins other than XT2: Connect these pins to V_{SS} through pull-down resistors.
 - XT2 pin: Open

9.1 OPERATING MODES WHEN WRITING TO AND VERIFYING THE PROGRAM MEMORY

If +6 V is applied to the V_{DD} pin and +12.5 V is applied to the V_{PP} pin, the μ PD75P0116 enters program memory write/verify mode. The specific operating mode is then selected by the setting of the MD0 through MD3 pins as listed in the table below.

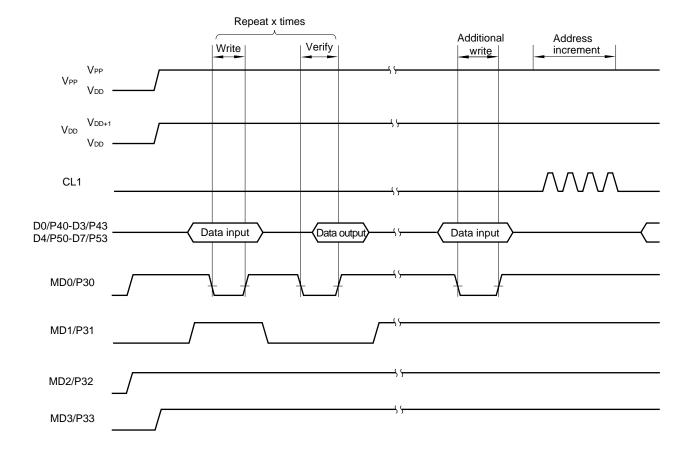
Operating mode specification					Operating mode		
V _{PP}	V _{DD}	MD0	MD1	MD2	MD3		
+12.5 V	+6 V	Н	L	Н	L	Program memory address clear mode	
		L	н	н	Н	Write mode	
		L	L	н	Н	Verify mode	
		Н	Х	Н	Н	Program inhibit mode	

Remark X indicates L or H.

* 9.2 WRITING TO THE PROGRAM MEMORY

The procedure for writing to program memory is described below; high-speed write is possible.

- (1) Pull low all unused pins to $V_{\rm SS}$ by means of resistors. Bring CL1 to low level.
- (2) Apply 5 V to V_{DD} and to V_{PP} .
- (3) Wait 10 µs.
- (4) Select program memory address clear mode.
- (5) Apply 6 V to V_{DD} and 12.5 V to V_{PP} .
- (6) Select write mode for 1 ms duration and write data.
- (7) Select verify mode. If write is successful, proceed to step (8). If write fails, repeat steps (6) and (7).
- (8) Perform additional write for (Number of repetitions of steps (6) and (7)) x 1 ms duration.
- (9) Increment the program memory address by inputting four pulses on the CL1 pin.
- (10) Repeat steps (6) to (9) until the last address is reached.
- (11) Select program memory address clear mode.
- (12) Apply 5 V to V_{DD} and to V_{PP} .
- (13) Turn the power off.



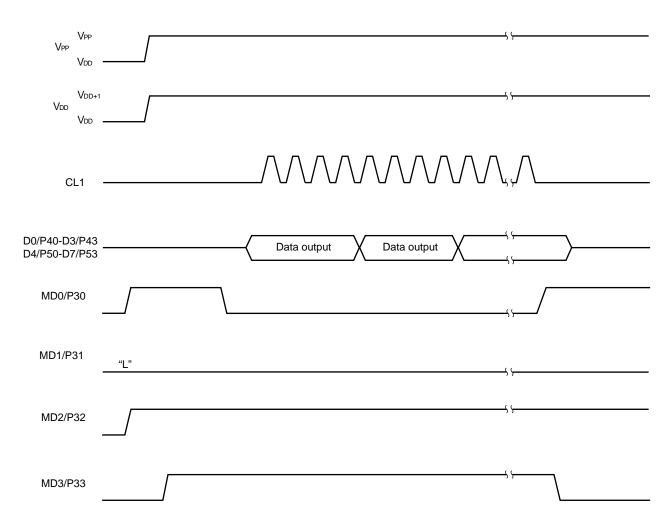
The timing for steps (2) to (9) is shown below.

* 9.3 READING THE PROGRAM MEMORY

The procedure for reading the contents of program memory is described below. The read is performed in the verify mode.

- (1) Pull low all unused pins to V_{SS} by means of resistors. Bring CL1 to low level.
- (2) Apply 5 V to V_{DD} and V_{PP} .
- (3) Wait 10 μs.
- (4) Select program memory address clear mode.
- (5) Apply 6 V to V_{DD} and 12.5 V to V_{PP} .
- (6) Select verify mode. Data is output sequentially one address at a time for each cycle of four clock pulses appearing on the CL1 pin.
- (7) Select program memory address clear mode.
- (8) Apply 5 V to V_{DD} and to V_{PP} .
- (9) Turn the power off.

The timing for steps (2) to (7) is shown below.



9.4 SCREENING OF ONE-TIME PROM

Because of its structure, it is difficult for NEC to completely test the one-time PROM product before shipment. It is therefore recommended that screening be performed to verify the PROM contents after the necessary data has been written to the PROM and the product has been stored under the following conditions.

Storage Temperature	Storage Time
125°C	24 hours

[MEMO]

CHAPTER 10 MASK OPTION

10.1 PIN

The pins of the μ PD750108 have the following mask options:

Pin	Mask Option
P40-P43	Pull-up resistor can be connected in 1-bit units.
P50-P53	

Table 10-1. Selecting Mask Option of Pin

P40 through P43 (port 4) or P50 through P53 (port 5) can be connected with pull-up resistors by mask option. The mask option can be specified in 1-bit units.

If the pull-up resistor is connected by mask option, port 4 or 5 goes high on reset. If the pull-up resistor is not connected, the port goes into a high-impedance state on reset.

Pull-up resistors, specified with the mask option, are not connected to the µPD75P0116.

10.2 MASK OPTION OF STANDBY FUNCTION

The standby function of the μ PD750108 allows you to select wait time by using a mask option. The wait time is required for the CPU to return to the normal operation mode after STOP mode has been released by an interrupt (for details, see **Section 7.2**).

The wait time can be set to either of the following:

<1> 2⁹/f_{CC} (256 μs at 2 MHz, 512 μs at 1 MHz)
 <2> No wait

The μ PD75P0116 does not have a mask option and its wait time is fixed to 29/f_{CC}.

10.3 MASK OPTION FOR FEEDBACK RESISTOR OF SUBSYSTEM CLOCK

For the subsystem clock of the μ PD750108, whether to enable the feedback resistor is selected by the mask option.

<1> Enable the feedback resistor (switches on or off by software).

<2> Disable the feedback resistor (cuts by hardware).

To use the feedback resistor after selecting <1>, turn the feedback resistor on by setting SOS.0 to 0 (for details, see (6) in Section 5.2.2).

Select **<1>** to use the subsystem clock.

For the μ PD75P0116, the mask option need not be set; use of the feedback resistor is factory-set.

CHAPTER 11 INSTRUCTION SET

The instruction set of the μ PD750108 is an improved and extended version of the 75X series instruction set. This instruction set takes over the instruction set of the 75X series, having the following features:

- (1) Bit manipulation instructions allowing a wide variety of applications
- (2) Efficient 4-bit manipulation instructions
- (3) Eight-bit instructions comparable to 8-bit microcontrollers
- (4) GETI instruction for reducing program sizes
- (5) String-effect instructions and number system conversion instructions for increased program efficiency
- (6) Table reference instructions suitable for successive references
- (7) 1-byte relative branch instructions
- (8) NEC standard mnemonics designed for clarity and readability

See **Section 3.2** for the addressing modes applicable to data memory manipulation and register banks used for instruction execution.

11.1 UNIQUE INSTRUCTIONS

This section outlines the unique instructions among the μ PD750108 instruction set.

11.1.1 GETI Instruction

The GETI instruction converts any of the following instructions to a 1-byte instruction:

- (a) Subroutine call instruction for the entire space
- (b) Branch instruction for the entire space
- (c) Arbitrary 2-byte instruction operating with two machine cycles (Except the BRCB and CALLF instructions)
- (d) A combination of two 1-byte instructions

The GETI instruction references the table located at addresses 0020H to 007FH in program memory, and executes referenced 2-byte data as an instruction of (a), (b), (c), or (d) above. This means that 48 instructions consisting of (a) to (d) can be converted to 1-byte instructions.

Thus the GETI instruction can be used to convert frequently used instructions of (a) to (d) to 1-byte instructions to reduce the number of program bytes significantly.

11.1.2 Bit Manipulation Instruction

The μ PD750108 has reinforced bit test, bit transfer, and bit Boolean (AND, OR, and XOR) instruction, in addition to the ordinary bit manipulation (set and clear) instructions.

The bit to be manipulated is specified in the bit manipulation addressing mode. Three types of bit manipulation addressing modes can be used. The bits manipulated in each addressing mode are shown in Table 11-1.

Table 11-1. Types of Bit Manipulation Addressing Modes and Specification Range

Addressing	Peripheral hardware that can be manipulated	Addressing range of bit that can be manipulated
fmem. bit	RBE, MBE, IST1, IST0, SCC, IExxx, IRQxxx	FB0H-FBFH
	PORT0-8	FF0H-FFFH
pmem. @L	BSB0-3, PORT0-8	FC0H-FFFH
@H+mem. bit	All peripheral hardware units that can be manipulated bitwise	All bits of memory bank specified by MB that can be manipulated bitwise

Remarks 1. xxx: 0, 1, 2, 4, BT, T0, T1, W, CSI

2. $MB = MBE \cdot MBS$

11.1.3 String-Effect Instructions

With the μ PD750108, two types of string-effect instructions are available.

- (a) MOV A, #n4 or MOV XA, #n8
- (b) MOV HL,#n8

"String effect" means the locating of these two types of instructions at contiguous addresses.

Example A0: MOV A,#0 A1: MOV A,#1 XA7: MOV XA,#07

When string-effect instructions are arranged as in this example, if execution starts at address A0, the following two instructions are replaced with an NOP instruction. If execution starts at address A1, the following one instruction is replaced with an NOP instruction. That is, only the instruction first executed is valid, and any following instructions are processed as an NOP instruction.

By using string-effect instructions, a constant can be set in an accumulator (the A register or the XA register pair) or data pointer (the HL register pair) more efficiently.

11.1.4 Number System Conversion Instructions

An application may need to convert the result of a 4-bit data addition or subtraction (performed in binary) to a decimal number. A time-related application may require sexagesimal conversion.

For this reason, the instruction set of the μ PD750108 contains number system conversion instructions for converting the result of a 4-bit data addition or subtraction to a number in an arbitrary number system.

(a) Number system conversion for addition

Let m be a desired number system after conversion. The following combination of instructions adds the contents of an accumulator to data in memory (HL), then converts the result of the addition to number system m.

ADDS A,#16 - m ADDC A,@HL ; A, CY <- A + (HL) + CY ADDS A,#m

An overflow is set in the carry flag.

If the execution of the instruction ADDC A, @HL generates a carry, the next instruction ADDS A,#n4 is skipped. If no carry is generated, ADDS A,#n4 is executed. In this case, the skip function of this instruction (ADDS A,#n4) is disabled, so that even if this addition generates a carry, the instruction following this instruction is not skipped. Accordingly, programs can be written after ADDS A,#n4.

Example An accumulator is added to memory data in decimal.

ADDS A,#6 ADDC A,@HL ; A,CY <- A + (HL) + CY ADDS A,#10 .

(b) Number system conversion for subtraction

Let m be a desired number system after conversion. The following combination of instructions subtracts data in memory (HL) from the contents of an accumulator, then converts the result of the subtraction to number system m.

SUBC A,@HL ADDS A,#m

An underflow is set in the carry flag.

If the execution of the instruction SUBC A, @HL generates no borrow, the next instruction ADDS A,#n4 is skipped. If a borrow is generated, the instruction ADDS A, #n4 is executed. In this case, the skip function of this instruction (ADDS A,#n4) is disabled, so that even if this addition generates a carry, the instruction following this instruction is not skipped. Accordingly, programs can be written after ADDS A,#n4.

11.1.5 Skip Instructions and the Number of Machine Cycles Required for a Skip

The instruction set of the μ PD750108 is designed to organize a program by testing a condition with the skip function.

When a skip instruction satisfies the skip condition, the immediately following instruction is skipped to execute the instruction immediately after the skipped instruction.

A skip requires the following number of machine cycles:

- (a) When the instruction (to be skipped) immediately following the skip instruction is a 3-byte instruction (that is, the BR !addr, BRA !addr1, CALL !addr, or CALLA !addr1 instruction): 2 machine cycles
- (b) When the instruction (to be skipped) immediately following the skip instruction is an instruction other than the instructions described in (a) above: 1 machine cycle

11.2 INSTRUCTION SET AND OPERATION

(1) Operand identifier and description

The operand field of an instruction must contain an operand coded according to the description rule for the operand identifier of the instruction. (Refer to **RA75X Assembler Package User's Manual: Language (EEU-1343)** for detailed information.) When there are multiple descriptions for an identifier, one item is to be selected. The uppercase letters and + and – signs are keywords, which must be coded as they appear.

For immediate data, a proper numeric value or label must be coded.

The abbreviations for register flags shown in **Figure 3-7** can be coded as labels in place of mem, fmem, pmem, and bit. (However, not all labels can be coded for the fmem and pmem. For details, see **Table 3-1** and **Figure 3-7**)

Representation format	Description method
reg	X, A, B, C, D, E, H, L
reg1	X, B, C, D, E, H, L
rp	XA, BC, DE, HL
rp1	BC, DE, HL
rp2	BC, DE
rp'	XA, BC, DE, HL, XA', BC', DE', HL'
rp'1	BC, DE, HL, XA', BC', DE', HL'
rpa	HL, HL+, HL–, DE, DL
rpa1	DE,DL
n4	4-bit immediate data or label
n8	8-bit immediate data or label
mem	8-bit immediate data or labelNote
bit	2-bit immediate data or label
fmem	FB0H-FBFH and FF0H-FFFH immediate data or label
pmem	FC0H-FFFH immediate data or label
addr, addr1(for MkII mode only)	0000H-0FFFH immediate data or label (μPD750104) 0000H-17FFH immediate data or label (μPD750106) 0000H-1FFFH immediate data or label (μPD750108) 0000H-3FFFH immediate data or label (μPD75P0116)
caddr	12-bit immediate data or label
faddr	11-bit immediate data or label
taddr	20H-7FH immediate data (bit 0 = 0) or label
PORTn	PORT0-PORT8
IExxx	IEBT, IET0, IET1, IE0-IE2, IE4, IECSI, IEW
RBn	RB0-RB3
MBn	MB0, MB1, MB15

Note For mem, only even addresses can be coded for 8-bit data processing.

(2) Legend

- A: A register; 4-bit accumulator
- B: B register C: C register
- D: D register
- E: E register
- H: H register
- L: L register
- X: X register
- XA: Register pair (XA), 8-bit accumulator
- BC: Register pair (BC)
- DE: Register pair (DE)
- HL: Register pair (HL)
- XA': Extended register pair (XA')
- BC': Extended register pair (BC')
- DE': Extended register pair (DE')
- HL': Extended register pair (HL')
- PC: Program counter
- SP: Stack pointer
- CY: Carry flag, bit accumulator
- PSW: Program status word
- MBE: Memory bank enable flag
- RBE: Register bank enable flag
- PORTn: Port n (n = 0 to 8)
- IME: Interrupt master enable flag
- IPS: Interrupt priority specification register
- IExxx: Interrupt enable flag
- RBS: Register bank select register
- MBS: Memory bank select register
- PCC: Processor clock control register
- .: Address/bit delimiter
- (xx): Contents addressed by xx
- xxH: Hexadecimal data

*1	MB = MBE · ME (MBS = 0, 1, 15		
*2	MB = 0		
*3		= 0 (000H - 07FH) = 15 (F80H - FFFH) = MBS (MBS =0, 1, 15)	Data memory addressing
*4		и = FB0H - FBFH, FF0H - FFFH	
*5	MB = 15, pmen	n = FC0H - FFFH	
*6	μPD750104	addr, addr1 = 0000H - 0FFFH	
	μPD750106	addr, addr1 = 0000H - 17FFH	
	μPD750108	addr, addr1 = 0000H - 1FFFH	
	μPD75P0116	addr, addr1 = 0000H - 3FFFH	
*7		(Current PC) – 15 to (Current PC) – 1 (Current PC) + 2 to (Current PC) + 16	
*8	μPD750104	caddr = 0000H - 0FFFH	
	μPD750106	caddr = 0000H - 0FFFH (PC ₁₂ = 0) or 1000H - 17FFH (PC ₁₂ = 1)	
	μPD750108	caddr = 0000H - 0FFFH (PC ₁₂ = 0) or 1000H - 1FFFH (PC ₁₂ = 1)	Program memory addressing
	μPD75P0116	caddr = 0000H - 0FFFH (PC13, PC12 = 00B) or	
		1000H - 1FFFH (PC ₁₃ , PC ₁₂ = 01B) or	
		2000H - 2FFFH (PC ₁₃ , PC ₁₂ = 10B) or	
		3000H - 3FFFH (PC13, PC12 = 11B)	
*9	faddr = 0000H	- 07FFH	
*10	taddr = 0020H	- 007FH	
*11	For MkII mode	only	
	addr1 = 0000H	- 0FFFH (μPD750104)	
	0000Н	- 17FFH (μPD750106)	
	0000H	- 1FFFH (μPD750108)	
	0000H	- 3FFFH (μPD75P0116)	

(3) Explanation of symbols used for the addressing area column

Remarks 1. MB represents an accessible memory bank.

- **2.** For *2, MB = 0 regardless of the setting of MBE and MBS.
- **3.** For *4 and *5, MB = 15 regardless of the setting of MBE and MBS.
- **4.** Each of *6 to *11 indicates an addressable area.

(4) Explanation of the machine cycle column

S represents the number of machine cycles required when a skip instruction with the skip function performs a skip operation. S assumes one of the following values:

- When no skip operation is performed: S = 0
- When a 1-byte instruction or 2-byte instruction is skipped: S = 1
- When a 3-byte instruction^{Note} is skipped: S = 2

Note 3-byte instruction: BR !addr, BRA !addr1, CALL !addr, and CALLA !addr1 instructions

Caution The GETI instruction is skipped in one machine cycle.

One machine cycle is equal to one cycle (t_{CY}) of the CPU clock (Φ), and four different machine cycles are available for selection according to the PCC setting. (See **Figure 5-12**.)

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	моу	A,#n4	1	1	A <- n4		String-effect A
		reg1,#n4	2	2	reg1 <- n4		
		XA,#n8	2	2	XA <- n8		String-effect A
		HL,#n8	2	2	HL <- n8		String-effect B
		rp2,#n8	2	2	rp2 <- n8		
		A,@HL	1	1	A <- (HL)	∗1	
		A,@HL+	1	2+S	A <- (HL), then L <- L+1	∗1	L=0
		A,@HL-	1	2+S	A <- (HL), then L <- L-1	∗1	L=FH
		A,@rpa1	1	1	A <- (rpa1)	*2	
		XA,@HL	2	2	XA <- (HL)	*1	
		@HL,A	1	1	(HL) <- A	*1	
		@HL,XA	2	2	(HL) <- XA	*1	
		A,mem	2	2	A <- (mem)	*3	
Ē		XA,mem	2	2	XA <- (mem)	*3	
Transfer		mem,A	2	2	(mem) <- A	*3	
		mem,XA	2	2	(mem) <- XA	*3	
		A,reg	2	2	A <- reg		
		XA,rp'	2	2	XA <- rp'		
		reg1,A	2	2	reg1 <- A		
		rp'1,XA	2	2	rp'1 <- XA		
	хсн	A,@HL	1	1	A <-> (HL)	∗1	
		A,@HL+	1	2+S	A <-> (HL), then L <- L+1	∗1	L=0
		A,@HL-	1	2+S	A <-> (HL), then L <- L-1	∗1	L=FH
		A,@rpa1	1	1	A <-> (rpa1)	*2	
		XA,@HL	2	2	XA <-> (HL)	∗1	
		A,mem	2	2	A <-> (mem)	*3	
		XA,mem	2	2	XA <-> (mem)	*3	
		A,reg1	1	1	A <-> reg1		
		XA,rp'	2	2	XA <-> rp'		

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	моут	XA,@PCDE	1	3	• μ PD750104 XA <- (PC ₁₁₋₈ +DE) _{ROM}		
					• μ PD750106, μPD750108 XA <- (PC ₁₂₋₈ +DE) _{ROM}		
uce					• μ PD75P0116 XA <- (PC ₁₃₋₈ +DE) _{ROM}		
Table reference		XA,@PCXA	1	3	• μ PD750104 XA <- (PC ₁₁₋₈ +XA) _{ROM}		
Table					• μ PD750106 , μ PD750108 XA <- (PC ₁₂₋₈ +XA) _{ROM}		
					• μ PD75P0116 XA <- (PC ₁₃₋₈ +XA) _{ROM}	_	
		XA,@BCDE	1	3	XA <- (BCDE) _{ROM} Note	*6	
		XA,@BCXA	1	3	XA <- (BCXA) _{ROM} Note	*6	
	MOV1	CY,fmem.bit	2	2	CY <- (fmem.bit)	*4	
<u> </u>		CY,pmem.@L	2	2	CY <- (pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀))	*5	
Bit transfer		CY,@H+mem.bit	2	2	CY <- (H+mem ₃₋₀ .bit)	*1	
Bit tra		fmem.bit,CY	2	2	(fmem.bit) <- CY	*4	
		pmem.@L,CY	2	2	(pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀)) <- CY	*5	
		@H+mem.bit,CY	2	2	(H+mem ₃₋₀ .bit) <- CY	*1	
	ADDS	A,#n4	1	1+S	A <- A+n4		carry
		XA,#n8	2	2+S	XA <- XA+n8		carry
		A,@HL	1	1+S	A <- A+(HL)	*1	carry
		XA,rp'	2	2+S	XA <- XA+rp'		carry
		rp'1,XA	2	2+S	rp'1 <- rp'1+XA		carry
Arithmetic/logical	ADDC	A,@HL	1	1	A,CY <- A+(HL)+CY	*1	
tic/lo		XA,rp'	2	2	XA,CY <- XA+rp'+CY		
hmet		rp'1,XA	2	2	rp'1,CY <- rp'1+XA+CY		
Aritl	SUBS	A,@HL	1	1+S	A <- A-(HL)	*1	borrow
		XA,rp'	2	2+S	XA <- XA-rp'		borrow
		rp'1,XA	2	2+S	rp'1 <- rp'1-XA		borrow
	SUBC	A,@HL	1	1	A,CY <- A-(HL)-CY	*1	
		XA,rp'	2	2	XA,CY <- XA-rp'-CY		
		rp'1,XA	2	2	rp'1,CY <- rp'1-XA-CY		

Note Set register B to 0 in the μ PD750104. Only the LSB is valid in register B in the μ PD750106 and μ PD750108. Only the low-order two bits are valid in the μ PD75P0116.

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	AND	A,#n4	2	2	A <- A ∧ n4		
		A,@HL	1	1	A <− A ∧ (HL)	*1	
		XA,rp'	2	2	XA <− XA∧rp'		
		rp'1,XA	2	2	rp'1 <− rp'1∧XA		
gical	OR	A,#n4	2	2	A <- A∨n4		
ic/lo		A,@HL	1	1	A <− A∨(HL)	*1	
Arithmetic/logical		XA,rp'	2	2	XA <− XA∨rp'		
Arith		rp'1,XA	2	2	rp'1 <- rp'1∨XA		
	XOR	A,#n4	2	2	A < A∀n4		
		A,@HL	1	1	A <− A ∀ (HL)	*1	
		XA,rp'	2	2	XA <− XA ∀ rp'		
		rp'1,XA	2	2	rp'1 <− rp'1 ∀XA		
Accumulator manipulation	RORC	A	1	1	CY <- A ₀ , A ₃ <- CY, A _{n-1} <- A _n		
Accum manip	NOT	A	2	2	$A < -\overline{A}$		
	INCS	reg	1	1+S	reg <- reg+1		reg=0
Increment/decrement		rp1	1	1+S	rp1 <- rp1+1		rp1=00H
decr		@HL	2	2+S	(HL) <- (HL)+1	*1	(HL)=0
nent/		mem	2	2+S	(mem) <- (mem)+1	*3	(mem)=0
Icren	DECS	reg	1	1+S	reg <- reg-1		reg=FH
-		rp'	2	2+S	rp' <- rp'-1		rp'=FFH
	SKE	reg,#n4	2	2+S	Skip if reg=n4		reg=n4
L.		@HL,#n4	2	2+S	Skip if (HL)=n4	*1	(HL)=n4
Comparison		A,@HL	1	1+S	Skip if A=(HL)	*1	A=(HL)
dwo		XA,@HL	2	2+S	Skip if XA=(HL)	*1	XA=(HL)
		A,reg	2	2+S	Skip if A=reg		A=reg
		XA,rp'	2	2+S	Skip if XA=rp'		XA=rp'
u	SET1	CY	1	1	CY <- 1		
flag ulati	CLR1	CY	1	1	CY <- 0		
Carry flag manipulation	ѕкт	CY	1	1+S	Skip if CY=1		CY=1
	NOT1	CY	1	1	CY <- CY		

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	SET1	mem.bit	2	2	(mem.bit) <- 1	*3	
		fmem.bit	2	2	(fmem.bit) <- 1	*4	
		pmem.@L	2	2	(pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀)) <- 1	∗5	
		@H+mem.bit	2	2	(H+mem ₃₋₀ .bit) <- 1	*1	
	CLR1	mem.bit	2	2	(mem.bit) <- 0	*3	
		fmem.bit	2	2	(fmem.bit) <- 0	*4	
		pmem.@L	2	2	(pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀)) <- 0	∗5	
		@H+mem.bit	2	2	(H+mem ₃₋₀ .bit) <- 0	∗1	
	ѕкт	mem.bit	2	2+S	Skip if (mem.bit)=1	∗3	(mem.bit)=1
		fmem.bit	2	2+S	Skip if (fmem.bit)=1	*4	(fmem.bit)=1
		pmem.@L	2	2+S	Skip if (pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀))=1	∗5	(pmem.@L)=1
		@H+mem.bit	2	2+S	Skip if (H+mem ₃₋₀ .bit)=1	*1	(@H+mem.bit)=1
	SKF	mem.bit	2	2+S	Skip if (mem.bit)=0	*3	(mem.bit)=0
llatio		fmem.bit	2	2+S	Skip if (fmem.bit)=0	*4	(fmem.bit)=0
anipu		pmem.@L	2	2+S	Skip if (pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀))=0	∗5	(pmem.@L)=0
it ma		@H+mem.bit	2	2+S	Skip if (H+mem ₃₋₀ .bit)=0	*1	(@H+mem.bit)=0
ory b	SKTCLR	fmem.bit	2	2+S	Skip if (fmem.bit)=1 and clear	*4	(fmem.bit)=1
Memory bit manipulation		pmem.@L	2	2+S	Skip if (pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀)) =1 and clear	*5	(pmem.@L)=1
		@H+mem.bit	2	2+S	Skip if (H+mem ₃₋₀ .bit)=1 and clear	*1	(@H+mem.bit)=1
	AND1	CY,fmem.bit	2	2	CY <− CY∧ (fmem.bit)	*4	
		CY,pmem.@L	2	2	CY <- CY∧ (pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀))	∗5	
		CY,@H+mem.bit	2	2	CY <− CY∧ (H+mem ₃₋₀ .bit)	∗1	
	OR1	CY,fmem.bit	2	2	CY <− CY∀ (fmem.bit)	*4	
		CY,pmem.@L	2	2	CY <− CY∨ (pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀))	∗5	
		CY,@H+mem.bit	2	2	CY <− CY∀ (H+mem ₃₋₀ .bit)	×1	
	XOR1	CY,fmem.bit	2	2	CY <− CY ∀(fmem.bit)	*4	
		CY,pmem.@L	2	2	CY <- CY ∀ (pmem ₇₋₂ +L ₃₋₂ .bit(L ₁₋₀))	∗5	
		CY,@H+mem.bit	2	2	CY <- CY ∀ (H+mem ₃₋₀ .bit)	*1	

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	BR addr House addr House addr House addr1	addr	_	_	 μPD750104 PC₁₁₋₀ <- addr The assembler selects the most adequate instruction from instructions below. BR !addr BR \$addr BRCB !caddr 	*6	
					 μPD750106, μPD750108 PC₁₂₋₀ <- addr The assembler selects the most adequate instruction from instructions below. BR !addr BRCB !caddr BR \$addr 		
-to					 μPD75P0116 PC₁₃₋₀ <- addr The assembler selects the most adequate instruction from instructions below. BR !addr BRCB !caddr BR \$addr 		
Bran		addr1Note	-		 µPD750104 PC₁₁₋₀ <- addr1 The assembler selects the most adequate instruction from instructions below. BRA !addr1 BR !addr BRCB !caddr BR \$addr1 	*11	
					 μPD750106, μPD750108 PC₁₂₋₀ <- addr1 The assembler selects the most adequate instruction from instructions below. BRA !addr1 BR !addr BRCB !caddr BR \$addr1 		
					 μPD75P0116 PC₁₃₋₀ <- addr1 The assembler selects the most adequate instruction from instructions below. BRA !addr1 BR !addr BRCB !caddr BR \$addr1 		

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	BR	!addr	3	3	•	*6	
					• μ PD750106 , μ PD750108 PC ₁₂₋₀ <– addr		
					• μ PD75P0116 PC ₁₃₋₀ <– addr		
		\$addr	1	2	•	*7	
					• μ PD750106 , μ PD750108 PC ₁₂₋₀ <– addr		
					• μ PD75P0116 PC ₁₃₋₀ <– addr		
		\$addr1	1	2	•	*7	
					•		
					• μ PD75P0116 PC ₁₃₋₀ <– addr1		
Branch		PCDE	2	3	• μ PD750104 PC ₁₁₋₀ <- PC ₁₁₋₈ +DE		
Brai					• μ PD750106 , μ PD750108 PC ₁₂₋₀ <- PC ₁₂₋₈ +DE		
					• μ PD75P0116 PC ₁₃₋₀ <- PC ₁₃₋₈ +DE		
		PCXA	2	3	• μ ΡD750104 PC ₁₁₋₀ <- PC ₁₁₋₈ +XA		
					• μ PD750106 , μ PD750108 PC ₁₂₋₀ <- PC ₁₂₋₈ +XA		
					• μ ΡD75P0116 PC ₁₃₋₀ <- PC ₁₃₋₈ +XA		
		BCDE	2	3	•	*11	
					•		
					•		

Notes 1. Set register B to 0.

- 2. Only the LSB is valid in register B.
- 3. Only the low-order two bits are valid in register B.

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	BR	ВСХА	2	3	• µ PD750104 PC ₁₁₋₀ <- BCXANote 1	*11	
					• μ PD750106 , μ PD750108 PC ₁₂₋₀ <- BCXANote 2		
					•		
	BRA ^{Note 4}	!addr1	3	3	•	*11	
Branch					• μ PD750106 , μ PD750108 PC ₁₂₋₀ <- addr		
					• μ PD75P0116 PC ₁₃₋₀ <- addr1		
	BRCB	!caddr	2	2	• μ PD750104 PC ₁₁₋₀ <– caddr ₁₁₋₀	*8	
					• μ PD750106 , μ PD750108 PC ₁₂₋₀ <– PC ₁₂ +caddr ₁₁₋₀		
					• μ PD75P0116 PC ₁₃₋₀ <- PC _{13, 12} +caddr ₁₁₋₀		
ntrol	CALLANote 4	!addr1	3	3	• μ PD750104 (SP-2) <- x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, 0, 0 PC ₁₁₋₀ <- addr, SP <- SP-6	*11	
Subroutine stack control					• μ PD750106, μ PD750108 (SP-2) <- x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, 0, PC ₁₂ PC ₁₂₋₀ <- addr, SP <- SP-6		
Subr					• μ PD75P0116 (SP-2) <- x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, PC ₁₃ , PC ₁₂ PC ₁₃₋₀ <- addr1, SP <- SP-6		

Notes 1. Set register B to 0.

- 2. Only the LSB is valid in register B.
- 3. Only the low-order two bits are valid in register B.
- **4.** The shaded portion is supported in Mk II mode only. The other portions are supported in Mk I mode only.

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	CALLNote	!addr	3	3	• μ PD750104 (SP-3) <- MBE,RBE, 0, 0 (SP-4)(SP-1)(SP-2) <- PC ₁₁₋₀ PC ₁₁₋₀ <- addr, SP <- SP-4	*6	
					• μ PD750106 , μ PD750108 (SP-3) <- MBE,RBE, 0, PC ₁₂ (SP-4)(SP-1)(SP-2) <- PC ₁₁₋₀ PC ₁₂₋₀ <- addr, SP <- SP-4		
					• μ PD75P0116 (SP-3) <- MBE,RBE, PC ₁₃ , PC ₁₂ (SP-4)(SP-1)(SP-2) <- PC ₁₁₋₀ PC ₁₃₋₀ <- addr1, SP <- SP-4		
ntrol				4	• μ PD750104 (SP-2) <- x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, 0, 0 PC ₁₁₋₀ <- addr, SP <- SP-6		
Subroutine stack control					• μ PD750106 , μ PD750108 (SP-2) <- x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, 0, PC ₁₂ PC ₁₂₋₀ <- addr, SP <- SP-6		
Subro					• μ PD75P0116 (SP-2) <- x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, PC ₁₃ , PC ₁₂ PC ₁₃₋₀ <- addr, SP <- SP-6		
	CALLFNote	!faddr	2	2	• μ PD750104 (SP-3) <- MBE,RBE, 0, 0 (SP-4)(SP-1)(SP-2) <- PC ₁₁₋₀ PC ₁₁₋₀ <- 0+faddr, SP <- SP-4	*9	
					• μ PD750106 , μ PD750108 (SP-3) <- MBE,RBE, 0, PC ₁₂ (SP-4)(SP-1)(SP-2) <- PC ₁₁₋₀ PC ₁₂₋₀ <- 00+faddr, SP <- SP-4		
					• μ PD75P0116 (SP-3) <- MBE,RBE, PC ₁₃ , PC ₁₂ (SP-4)(SP-1)(SP-2) <- PC ₁₁₋₀ PC ₁₃₋₀ <- 000+faddr, SP <- SP-4		

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	CALLF ^{Note}	!faddr	2	3	• μ PD750104 (SP-2) -> x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, 0, 0 PC ₁₁₋₀ <- 0+faddr, SP <- SP-6	*9	
					• μ PD750106, μ PD750108 (SP-2) -> x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, 0, PC ₁₂ PC ₁₂₋₀ <- 00+faddr, SP <- SP-6		
					• μ PD75P0116 (SP-2) <- x, x, MBE,RBE (SP-6)(SP-3)(SP-4) <- PC ₁₁₋₀ (SP-5) <- 0, 0, PC ₁₃ , PC ₁₂ PC ₁₃₋₀ <- 000+faddr, SP <- SP-6		
trol	RET ^{Note}		1	3	• μ PD750104 PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) MBE,RBE, 0, 0 <- (SP+1), SP <- SP+4		
Subroutine stack control					• μ PD750106 , μ PD750108 PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) MBE,RBE, 0, PC ₁₂ <- (SP+1) SP <- SP+4		
Subrouti					• μ PD75P0116 PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) MBE,RBE, PC ₁₃ , PC ₁₂ <- (SP+1) SP <- SP+4		
				3	• μ PD750104 x, x, MBE, RBE <- (SP+4) 0, 0, 0, 0 <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) SP <- SP+6		
					• μ PD750106 , μ PD750108 x, x, MBE, RBE <- (SP+4) MBE,0, 0, PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) SP <- SP+6		
					• µ PD75P0116 x, x, MBE, RBE <- (SP+4) 0,0, PC ₁₃ , PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) SP <- SP+6		

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	RETS ^{Note}		1	3+S	• μ PD750104 MBE, RBE, 0, 0 <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) SP <- SP+4 Then skip unconditionally		Unconditionally
	Subroutine stack control				• μ PD750106 , μ PD750108 MBE, 0, 0, PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) SP <- SP+4 Then skip unconditionally		
					• μ PD75P0116 MBE, RBE, PC ₁₃ , PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) SP <- SP+4 Then skip unconditionally	-	
control			3+S	• μ PD750104 0, 0, 0, 0 <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) x, x, MBE, RBE <- (SP+4) SP <- SP+6 Then skip unconditionally			
Subroutine stack					• μ PD750106 , μ PD750108 0, 0, 0, PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) x, x, MBE, RBE <- (SP+4) SP <- SP+6 Then skip unconditionally		
					• μ PD75P0116 0, 0, PC ₁₃ , PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) x, x, MBE, RBE <- (SP+4) SP <- SP+6 Then skip unconditionally		
	RETI ^{Note}		1	3	• μ PD750104 MBE, RBE, 0, 0 <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) PSW <- (SP+4)(SP+5), SP <- SP+6		
					• μ PD750106 , μ PD750108 MBE, RBE, 0, PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) PSW <- (SP+4)(SP+5), SP <- SP+6		
				• μ PD75P0116 MBE, RBE, PC ₁₃ , PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) PSW <- (SP+4)(SP+5), SP <- SP+6			

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	RETINote 1		1	3	• μ PD750104 0, 0, 0, 0 <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) PSW <- (SP+4)(SP+5), SP <- SP+6		
control					• μ PD750106, μ PD750108 0, 0, 0, PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) PSW <- (SP+4)(SP+5), SP <- SP+6		
Subroutine stack control					• μ PD75P0116 0, 0, PC ₁₃ , PC ₁₂ <- (SP+1) PC ₁₁₋₀ <- (SP)(SP+3)(SP+2) PSW <- (SP+4)(SP+5), SP <- SP+6		
Subre	PUSH	rp	1	1	(SP-1)(SP-2) <- rp, SP <- SP-2		
		BS	2	2	(SP-1) <- MBS, (SP-2) <- RBS, SP <- SP-2		
	РОР	rp	1	1	rp <- (SP+1)(SP), SP <- SP+2		
		BS	2	2	MBS <- (SP+1), RBS <- (SP), SP <- SP+2		
	EI		2	2	IME(IPS.3) <- 1		
Interrupt control		IExxx	2	2	IExxx <- 1		
Intel con	DI		2	2	IME(IPS.3) <- 0		
		IExxx	2	2	IExxx <- 0		
	INNote 2	A,PORT _n	2	2	A <- PORT _n (n=0 - 8)		
0		XA,PORT _n	2	2	$XA \leftarrow PORT_{n+1}, PORT_n (n=4, 6)$		
	OUTNote 2	PORT _n ,A	2	2	PORT _n <- A (n=2 - 8)		
		PORT _n ,XA	2	2	$PORT_{n+1}, PORT_n <- XA (n=4, 6)$		
ntrol	HALT		2	2	Set HALT Mode (PCC.2 <- 1)		
CPU control	STOP		2	2	Set STOP Mode (PCC.3 <- 1)		
CP	NOP		1	1	No Operation		

2. MBE = 0, or MBE = 1 and MBS = 15 must be set when an IN/OUT instruction is executed.

In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	SEL	RBn	2	2	RBS <- n (n=0 - 3)		
		MBn	2	2	MBS <- n (n=0, 1, 15)		
	GETINote	taddr	1	3	• μ PD750104 When the TBR instruction is used PC ₁₁₋₀ <- (taddr) ₃₋₀ +(taddr+1)	*10	
					When the TCALL instruction is used (SP-4)(SP-1)(SP-2) <- PC_{11-0} (SP-3) <- MBE, RBE, 0, 0 PC_{11-0} <- (taddr) ₃₋₀ +(taddr+1) SP <- SP-4	*	
					When an instruction other than the TBR or TCALL instruction is used Execution of (taddr)(taddr+1) instruction		Depends on the referenced instruction
					• μ PD750106 , μ PD750108 When the TBR instruction is used PC ₁₂₋₀ <- (taddr) ₄₋₀ +(taddr+1)		
Special					When the TCALL instruction is used $(SP-4)(SP-1)(SP-2) <- PC_{11-0}$ $(SP-3) <- MBE, RBE, 0, PC_{12}$ $PC_{12-0} <- (taddr)_{4-0}+(taddr+1)$ SP <- SP-4		
					When an instruction other than the TBR or TCALL instruction is used Execution of (taddr)(taddr+1) instruction		Depends on the referenced instruction
					• μ PD75P0116 When the TBR instruction is used PC ₁₃₋₀ <- (taddr) ₅₋₀ +(taddr+1)		
					When the TCALL instruction is used $(SP-4)(SP-1)(SP-2) <- PC_{11-0}$ $(SP-3) <- MBE, RBE, PC_{13}, PC_{12}$ $PC_{13-0} <- (taddr)_{5-0}+(taddr+1)$ SP <- SP-4		
					When an instruction other than the TBR or TCALL instruction is used Execution of (taddr)(taddr+1) instruction		Depends on the referenced instruction

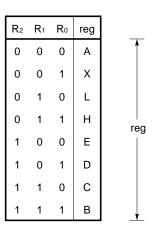
Note The TBR and TCALL instructions are assembler pseudo instructions to define tables used for GETI instructions.

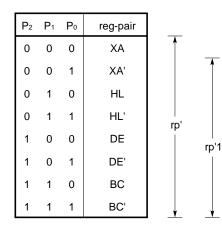
In- struc- tion	Mne- monic	Operand	Number of bytes	Machine cycle	Operation	Address- ing area	Skip condition
	GETINotes1, 2	taddr	1	3	• μ PD750104 When the TBR instruction is used PC ₁₁₋₀ <- (taddr) ₃₋₀ +(taddr+1)	*10	
		4	When the TCALL instruction is used $(SP-6)(SP-3)(SP-4) <- PC_{11-0}$ (SP-5) <- 0, 0, 0, 0 (SP-2) <- x, x, MBE, RBE $PC_{11-0} <- (taddr)_{3-0}+(taddr+1)$ SP <- SP-6				
				3	When an instruction other than the TBR or TCALL instruction is used Execution of (taddr)(taddr+1) instruction		Depends on the referenced instruction
				3	• μ PD750106, μ PD750108 When the TBR instruction is used PC ₁₂₋₀ <- (taddr) ₄₋₀ +(taddr+1)		
Special				4	When the TCALL instruction is used $(SP-6)(SP-3)(SP-4) < -PC_{11-0}$ $(SP-5) < -0, 0, 0, PC_{12}$ (SP-2) < -x, x, MBE, RBE $PC_{12-0} < -(taddr)_{4-0}+(taddr+1)$ SP < -SP-6		
				3	When an instruction other than the TBR or TCALL instruction is used Execution of (taddr)(taddr+1) instruction		Depends on the referenced instruction
			3	• μ PD75P0116 When the TBR instruction is used PC ₁₃₋₀ <- (taddr) ₅₋₀ +(taddr+1)			
				4	When the TCALL instruction is used $(SP-6)(SP-3)(SP-4) < -PC_{11-0}$ $(SP-5) < -0, 0, PC_{13}, PC_{12}$ (SP-2) < -x, x, MBE, RBE $PC_{13-0} < -(taddr)_{5-0}+(taddr+1)$ SP < -SP-6		
				3	When an instruction other than the TBR or TCALL instruction is used Execution of (taddr)(taddr+1) instruction		Depends on the referenced instruction

- **Notes 1.** The shaded portion is supported in Mk II mode only. The other portions are supported in Mk I mode only.
 - **2.** The TBR and TCALL instructions are assembler pseudo instructions to define tables used for GETI instructions.

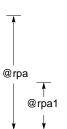
11.3 INSTRUCTION CODES OF EACH INSTRUCTION

(1) Explanations of the symbols for the instruction codes





Q ₂	Q1	Q_0	addressing
0	0	0	@HL
0	1	0	@HL+
0	1	1	@HL-
1	0	0	@DE
1	0	1	@DL



reg1

P ₂	P1	reg-pair			
0	0	ХА		_	,
0	1	HL		Î	r
1	0	DE	∱ rp2	rp1	
1	1	BC	1pz ↓	Ļ	,

N5	N2	N 1	N٥	IExxx
0	0	0	0	IEBT
0	0	1	0	IEW
0	1	0	0	IET0
0	1	0	1	IECSI
0	1	1	0	IE0
0	1	1	1	IE2
1	0	0	0	IE4
1	1	0	0	IET1
1	1	1	0	IE1

- I_n : Immediate data for n4 or n8
- D_n: Immediate data for mem
- B_n: Immediate data for bit
- N_n : Immediate data for n or IExxx
- T_n : Immediate data for taddr x 1/2
- An : Immediate data for the address (2 to 16) relative to branch destination address minus one
- S_n: Immediate data for the one's complement of the address (15 to 1) relative to the branch destination address

(2) Bit manipulation addressing instruction codes

*1 in the operand field indicates that there are three types of bit manipulation addressing, fmem.bit, pmem.@L, and @H+mem.bit.

The table below lists the second byte $\begin{bmatrix} *2 \end{bmatrix}$ of an instruction code corresponding to the above addressing.

*1	S	econ	id by	te of	instr	uctio	n co	de	Accessible bits							
fmem.bit	1	0	В ₁	B ₀	F_3	F_2	F ₁	F_0	FB0H-FBFH manipulatable bits							
	1	1	В ₁	B ₀	F_3	F_2	F ₁	F_0	FF0H-FFFH manipulatable bits							
pmem.@L	0	1	0	0	G_3	G_2	G_1	G_0	FC0H-FFFH manipulatable bits							
@H+mem.bit	0	0	B ₁	B ₀	D_3	D_2	D ₁	D ₀	Manipulatable bits of accessible memory bank							

- B_n: Immediate data for bit
- F_n : Immediate data for fmem (Low-order four bits of address)
- G_n: Immediate data for pmem (Bits 2 to 5 of address)
- D_n: Immediate data for mem (Low-order four bits of address)

Instruction	Mne-	Operand										I	Ins	stru	ucti	on	cod	de				
monic	monic	Operand				E	3 ₁								В	2					Β3	
Transfer MOV	ΜΟΥ	A,#n4	0	1	1	1	I ₃	I_2	I ₁	I ₀												
		reg1,#n4	1	0	0	1	1	0	1	0	I ₃	I ₂	<u>1</u>	1	I ₀	1	R ₂	$_{2} R_{1}$	R ₀			
		rp,#n8	1	0	0	0	1	P ₂	P ₁	1	I ₇	I ₆	; I	5	I_4	I ₃	I_2	I_1	I ₀			
		A,@rpa1	1	1	1	0	0	Q_2	Q1	Q_0												
		XA,@HL	1	0	1	0	1	0	1	0	0	0	()	1	1	0	0	0			
		@HL,A	1	1	1	0	1	0	0	0												
		@HL,XA	1	0	1	0	1	0	1	0	0	0	()	1	0	0	0	0			
		A,mem	1	0	1	0	0	0	1	1	D7	7 D	6 I	D ₅	D ₄	D ₃	D ₂	2 D1	D ₀			
		XA,mem	1	0	1	0	0	0	1	0	D7	7 D	6 [D ₅	D4	D ₃	D ₂	2 D1	0			
		mem,A	1	0	0	1	0	0	1	1	D7	7 D	6 I	D ₅	D ₄	D ₃	D ₂	2 D1	D ₀			
		mem,XA	1	0	0	1	0	0	1	0	D7	7 D	6 [D ₅	D ₄	D ₃	D ₂	2 D1	0			
		A,reg	1	0	0	1	1	0	0	1	0	1		1	1	1	R ₂	2 R1	R ₀			
		XA,rp'	1	0	1	0	1	0	1	0	0	1	()	1	1	P ₂	P ₁	P ₀			
		reg1,A	1	0	0	1	1	0	0	1	0	1		1	1	0	R ₂	2 R1	R ₀			
		rp'1,XA	1	0	1	0	1	0	1	0	0	1	()	1	0	P ₂	P1	P ₀			
	ХСН	A,@rpa1	1	1	1	0	1	Q ₂	2 Q1	Q_0												
		XA,@HL	1	0	1	0	1	0	1	0	0	0	()	1	0	0	0	1			
		A,mem	1	0	1	1	0	0	1	1	D7	7 D	6 [D ₅	D_4	D ₃	D ₂	2 D1	D ₀			
		XA,mem	1	0	1	1	0	0	1	0	D7	7 D	6 [D ₅	D_4	D ₃	D ₂	2 D1	0			
		A,reg1	1	1	0	1	1	R_2	R ₁	R_0												
		XA,rp'	1	0	1	0	1	0	1	0	0	1	()	0	0	P ₂	2 P1	Ρ0			
Table	ΜΟΥΤ	XA,@PCDE	1	1	0	1	0	1	0	0												
reference		XA,@PCXA	1	1	0	1	0	0	0	0												
		XA,@BCXA	1	1	0	1		0	0	1												
		XA,@BCDE	1	1	0	1	0	1	0	1												
Bit	MOV1	CY, 1	1	0	1	1	1	1	0	1					*2	2						
transfer		,CY	1	0	0	1	1	0	1	1					*2							

Instruction	nstruction Mne- Operand			Instruction code																
mstruction	monic	Operand			[3 ₁							E	3 ₂				E	3 ₃	
Arithmetic/	ADDS	A,#n4	0 1	1	0	I ₃	I_2	I ₁	I ₀											
logical		XA,#n8	1 0	1	1	1	0	0	1	I ₇	I_6	I_5	I_4	I ₃	I_2	I ₁	I ₀			
		A,@HL	1 1	0	1	0	0	1	0											
		XA,rp'	1 0	1	0	1	0	1	0	1	1	0	0	1	P ₂	P ₁	P_0			
		rp'1,XA	1 0	1	0	1	0	1	0	1	1	0	0	0	P ₂	P ₁	P_0			
	ADDC	A,@HL	1 0	1	0	1	0	0	1											
		XA,rp'	1 0	1	0	1	0	1	0	1	1	0	1	1	P ₂	P ₁	P_0			
		rp'1,XA	1 0	1	0	1	0	1	0	1	1	0	1	0	P ₂	P ₁	P ₀			
	SUBS	A,@HL	1 0	1	0	1	0	0	0											
		XA,rp'	1 0	1	0	1	0	1	0	1	1	1	0	1	P ₂	P ₁	P_0			
		rp'1,XA	1 0	1	0	1	0	1	0	1	1	1	0	0	P ₂	P ₁	P_0			
	SUBC	A,@HL	1 0	1	1	1	0	0	0											
		XA,rp'	1 0	1	0	1	0	1	0	1	1	1	1	1	P ₂	P ₁	P_0			
		rp'1,XA	1 0	1	0	1	0	1	0	1	1	1	1	0	P ₂	P ₁	P_0			
	AND	A,#n4	1 0	0	1	1	0	0	1	0	0	1	1	I ₃	I_2	I_1	I ₀			
		A,@HL	1 0	0	1	0	0	0	0											
		XA,rp'	1 0	1	0	1	0	1	0	1	0	0	1	1	P ₂	P ₁	P ₀			
		rp'1,XA	1 0	1	0	1	0	1	0	1	0	0	1	0	P ₂	P ₁	P ₀			
	OR	A,#n4	1 0	0	1	1	0	0	1	0	1	0	0	I ₃	I ₂	I ₁	I ₀	-		
		A,@HL	1 0	1	0	0	0	0	0											
		XA,rp'	1 0	1	0	1	0	1	0	1	0	1	0	1	P ₂	P ₁	P ₀	-		
		rp'1,XA	1 0	1	0	1	0	1	0	1	0	1	0	0	P ₂	P ₁	P ₀			
	XOR	A,#n4	1 0	0	1	1	0	0	1	0	1	0	1	I ₃	I_2	I ₁	I ₀			
		A,@HL	1 0	1	1	0	0	0	0											
		XA,rp'	1 0	1	0	1	0	1	0	1	0	1	1	1	P ₂	P ₁	P ₀			
		rp'1,XA	1 0	1	0	1	0	1	0	1	0	1	1	0	P ₂	P ₁	P_0			
Accumulator	RORC	A	1 0	0	1	1	0	0	0											
manipulation	NOT	A	1 0	0	1	1	0	0	1	0	1	0	1	1	1	1	1	-		

Instruction	Mne-	Operand	Instruction code							
Instruction	monic	Operand	B ₁ B ₂	B ₃						
Increment/		reg	1 1 0 0 0 R ₂ R ₁ R ₀							
decrement		rp1	1 0 0 0 1 P ₂ P ₁ 0							
		@HL	1 0 0 1 1 0 0 1 0 0 0 0 0 1 0							
		mem	1 0 0 0 0 0 1 0 D ₇ D ₆ D ₅ D ₄ D ₃ D ₂ D ₁ D ₀							
	DECS	reg	1 1 0 0 1 R ₂ R ₁ R ₀							
		rp'	1 0 1 0 1 0 1 0 0 1 1 0 1 P ₂ P ₁ P ₀							
Comparison	SKE	reg,#n4	1 0 0 1 1 0 1 0 I ₃ I ₂ I ₁ I ₀ 0 R ₂ R ₁ R ₀							
		@HL,#n4	1 0 0 1 1 0 0 1 0 1 1 0 I ₃ I ₂ I ₁ I ₀							
		A,@HL	1 0 0 0 0 0 0 0							
		XA,@HL	1 0 1 0 1 0 1 0 0 0 0 1 1 0 0 1							
		A,reg	1 0 0 1 1 0 0 1 0 0 0 1 R ₂ R ₁ R ₀							
		XA,rp'	1 0 1 0 1 0 1 0 0 1 0 0 1 0 0 1 P ₂ P ₁ P ₀							
Carry flag	SET1	CY	1 1 1 0 0 1 1 1							
manipu- lation	CLR1	CY	1 1 1 0 0 1 1 0							
	ѕкт	СҮ	1 1 0 1 0 1 1 1							
	NOT1	CY	1 1 0 1 0 1 1 0							
Memory	SET1	mem.bit	1 0 B ₁ B ₀ 0 1 0 1 D ₇ D ₆ D ₅ D ₄ D ₃ D ₂ D ₁ D ₀							
bit manipu-		*1	1 0 0 1 1 1 0 1 +2							
lation	CLR1	mem.bit	1 0 B ₁ B ₀ 0 1 0 0 D ₇ D ₆ D ₅ D ₄ D ₃ D ₂ D ₁ D ₀							
		*1	1 0 0 1 1 1 0 0 +2							
	ѕкт	mem.bit	1 0 B ₁ B ₀ 0 1 1 1 D ₇ D ₆ D ₅ D ₄ D ₃ D ₂ D ₁ D ₀							
		*1	1 0 1 1 1 1 1 1 +2							
	SKF	mem.bit	1 0 B ₁ B ₀ 0 1 1 0 D ₇ D ₆ D ₅ D ₄ D ₃ D ₂ D ₁ D ₀							
		*1	1 0 1 1 1 1 0 +2							
	SKTCLR	*1	1 0 0 1 1 1 1 1 +2							
	AND1	CY, 1	1 0 1 0 1 1 0 0 +2							
	OR1	CY, 1	1 0 1 0 1 1 1 0 +2							
	XOR1	CY, 1	1 0 1 1 1 1 0 0 +2							

	Mne-	Onenad										l	nstr	uct	ion	coc	le				
Instruction	monic	Operand				[3 ₁							E	3 ₂					B ₃	
Branch	BR	!addr	1	0	1	0	1	0	1	1	0	0	-						addr —		->
		\$addr1 (+16) to (+2)	0	0	0	0	A ₃	A ₂	A ₁	A ₀											
		(-1) to (-15)	1	1	1	1	S ₃	S ₂	S ₁	S_0											
		PCDE	1	0	0	1	1	0	0	1	0	0	0	0	0	1	0	0			
		PCXA	1	0	0	1	1	0	0	1	0	0	0	0	0	0	0	0			
		BCDE	1	0	0	1	1	0	0	1	0	0	0	0	0	1	0	1			
		BCXA	1	0	0	1	1	0	0	1	0	0	0	0	0	0	0	1			
	BRA	!addr1	1	0	1	1	1	0	1	0	0	-							addr1-		-
	BRCB	!caddr	0	1	0	1	-					ca	ıddr					->			
Sub-	CALL	!addr	1	0	1	0	1	0	1	1	0	1	-						addr —		->
routine stack	CALLA	!addr1	1	0	1	1	1	0	1	1	0	-							addr1-		->
control	CALLF	!faddr	0	1	0	0	0	-				fa	ddr					->			
	RET		1	1	1	0	1	1	1	0											
	RETS		1	1	1	0	0	0	0	0											
	RETI		1	1	1	0	1	1	1	1											
	PUSH	rp	0	1	0	0	1	P ₂	P ₁	1											
		BS	1	0	0	1	1	0	0	1	0	0	0	0	0	1	1	1			
	РОР	rp	0	1	0	0	1	P ₂	P ₁	0											
		BS	1	0	0	1	1	0	0	1	0	0	0	0	0	1	1	0			
I/O	IN	A,PORTn	1	0	1	0	0	0	1	1	1	1	1	1	N ₃	N_2	N ₁	N ₀			
		XA,PORTn	1	0	1	0	0	0	1	0	1	1	1	1	N ₃	N_2	N ₁	N ₀			
	ουτ	PORTn,A	1	0	0	1	0	0	1	1	1	1	1	1	N ₃	N_2	N ₁	N ₀			
		PORTn,XA	1	0	0	1	0	0	1	0	1	1	1	1	N ₃	N_2	N ₁	N ₀			
Interrupt	EI		1	0	0	1	1	1	0	1	1	0	1	1	0	0	1	0			
control		IExxx	1	0	0	1	1	1	0	1	1	0	N ₅	; 1	1	N_2	N ₁	N ₀			
	DI		1	0	0	1	1	1	0	0	1	0	1	1	0	0	1	0			
		IExxx	1	0	0	1	1	1	0	0	1	0	N ₅	; 1	1	N ₂	N ₁	N ₀			
CPU	HALT		1	0	0	1	1	1	0	1	1	0	1	0	0	0	1	1			
control	STOP		1	0	0	1	1	1	0	1	1	0	1	1	0	0	1	1			
	NOP		0	1	1	0	0	0	0	0											
Special	SEL	RBn	1	0	0	1	1	0	0	1	0	0	1	0	0	0	N ₁	N ₀			
		MBn	1	0	0	1	1	0	0	1	0	0	0	1	N ₃	N_2	N ₁	N ₀			
	GETI	taddr	0	0	T ₅	; T2	₁ Τ ₃	Τ2	T₁	T ₀					-						

11.4 FUNCTIONS AND APPLICATIONS OF THE INSTRUCTIONS

This section explains functions and applications of the instructions. For the μ PD750104, μ PD750106, μ PD750108, and μ PD75P0116, usable instructions and their functions in Mk I mode are different from those in Mk II mode. Read the following explanation.

How to read



Ш

) Can be used in both Mk I mode and Mk II mode for the μPD750104, μPD750106, μPD750108, and μPD75P0116

- I) Can be used in only Mk I mode for the μ PD750104, μ PD750106, μ PD750108, and μ PD75P0116
 -) Can be used in only Mk II mode for the μ PD750104, μ PD750106, μ PD750108, and μ PD75P0116
- I/II Can be used in both Mk I mode and Mk II mode for the μPD750104, μPD750106, μPD750108, and μPD75P0116. However, Mk I mode is different from Mk II mode in the functions. Read the explanation of [Mk I mode] for Mk I mode and the explanation of [Mk II mode] for Mk II mode, as required.
- **Remark** "Function" in this section is applicable to the μ PD750106 and μ PD750108 whose program counters consist of 13 bits each. This is also applicable to the μ PD750104 whose program counter consists of 12 bits and the μ PD75P0116 whose program counter consists of 14 bits, however.

11.4.1 Transfer Instructions

MOV A,#n4

Function: A $- n4 n4 = I_{3-0}$: 0-FH

Transfers the 4-bit immediate data n4 to the A register (4-bit accumulator).

The string effect (group A) can be utilized. When MOV A, #n4 and/or MOV XA, #n8 instructions are located contiguously, the string instructions following an executed instruction are processed as NOP instructions.

Examples 1. The data 0BH is set in the accumulator. MOV A,#0BH

2. Data to be output to port 3 is selected from 0 to 2.
A0: MOV A,#0
A1: MOV A,#1
A2: MOV A,#2
OUT PORT3.A

MOV reg1,#n4

Function: reg1 <- n4 $n4 = I_{3-0}$: 0-FH

Transfers the 4-bit immediate data n4 to A register reg1 (X, H, L, D, E, B, C).



Function: $XA \le n8$ $n8 = I_{7-0}$: 00H-FFH

Transfers the 8-bit immediate data n8 to register pair XA. The string effect can be utilized. When two or more of this instruction are executed in succession or when MOV A,#n4 instruction is located continguously, the string instructions following an executed instruction are processed as NOP instructions.



Function: HL \leq n8 = I₇₋₀: 00H-FFH

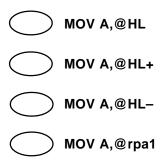
Transfers the 8-bit immediate data n8 to register pair HL. The string effect can be utilized. When two or more of this instruction are executed in succession, the string instructions following an executed instruction are processed as NOP instructions.



MOV rp2,#n8

Function: rp2 <- n8 n8 = I₇₋₀: 00H-FFH

Transfers the 8-bit immediate data n8 to register pair rp2 (BC, DE).



Function: A <- (Register pair specified by the operand) When HL+ is specified for the register pair: Skip if L = 0 When HL- is specified for the register pair: Skip if L = FH

Transfers the data at the data memory location addressed by the specified register pair (HL, HL+, HL-, DE, DL) to the A register.

When HL+ (automatic increment) is specified for the register pair, automatically increments the contents of the L register by one after the data transfer, and continues the operation until the contents are set to 0.

Then skips the immediately following instruction.

When HL– (automatic decrement) is specified for the register pair, automatically decrements the contents of the L register by one after the data transfer, and continues the operation until the contents are set to FH. Then skips the immediately following instruction.

MOV XA,@HL

Function: A <- (HL), X <- (HL+1)

Transfers the data at the data memory location addressed by the HL register pair to the A register, and transfers the data at the next data memory address to the X register.

However, if the contents of the L register are odd- numbered, an address with the low-order bit ignored is specified.

Example The data at addresses 3EH and 3FH are transferred to the XA register pair.

MOV HL, #3EH MOV XA, @HL



Function: (HL) <- A

Transfers the contents of the A register to the data memory location addressed by the HL register pair.

MOV @HL,XA

Function: (HL) <- A, (HL+1) <- X

Transfers the contents of the A register to the data memory location addressed by the HL register pair, and transfers the contents of the X register to the next memory address.

However, if the contents of the L register are odd- numbered, an address with the low-order bit ignored is specified



Function: A <- (mem) mem = D_{7-0} : 00H-FFH

Transfers the data at the data memory location addressed by the 8-bit immediate data mem to the A register.

) MOV XA,mem

Function: A <- (mem), X <- (mem+1) mem = D₇₋₀: 00H-FEH

Transfers the data at the data memory location addressed by the 8-bit immediate data mem to the A register, and transfers the data at the next address to the X register.

An even address can be specified with mem.

Example The data at addresses 40H and 41H are transferred to the XA register pair.

MOV XA,40H



Function: (mem) $\leq A$ mem = D₇₋₀: 00H-FFH

Transfers the contents of the A register to the data memory location addressed by the 8-bit immediate data mem.

MOV mem,XA

Function: (mem) <-A, (mem+1) <-X mem = D₇₋₀: 00H-FEH

Transfers the contents of the A register to the data memory location addressed by the 8-bit immediate data mem, and transfers the contents of the X register to the next memory address.

An even address can be specified with mem.

MOV A,reg

Function: A <- reg

Transfers the contents of register reg (X, A, H, L, D, E, B, C) to the A register.



Function: XA <- rp'

Transfers the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC') to the XA register pair.

Example The contents of the XA' register pair are transferred to the XA register pair.

MOV XA, XA'

) MOV reg1,A

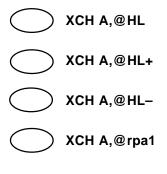
Function: reg1 <- A

Transfers the contents of the A register to register reg1 (X, H, L, D, E, B, C).

MOV rp'1,XA

Function: rp'1 <- XA

Transfers the contents of the XA register pair to register pair rp'1 (HL, DE, BC, XA', HL', DE', BC').



Function: A <-> (Register pair specified by the operand) When HL+ is specified for the register pair: Skip if L = 0 When HL- is specified for the register pair: Skip if L = FH

Exchanges the contents of the A register with the data at the data memory location addressed by the specified register pair (HL, HL+, HL-, DE, DL).

When HL+ (automatic increment) is specified for the register pair, automatically increments the contents of the L register by one after the data exchange, and continues the operation until the contents are set to 0. Then skips the immediately following instruction.

When HL– (automatic decrement) is specified for the register pair, automatically decrements the contents of the L register by one after the data exchange, and continues the operation until the contents are set to FH. Then skips the immediately following instruction.

Example The data at addresses 20H-2FH are exchanged with the data at addresses 30H-3FH.

	SEL	MB0	
	MOV	D,#2	
	MOV	HL,#30H	
LOOP:	XCH	A,@HL	; A <-> (3x)
	XCH	A,@DL	; A <-> (2x)
	XCH	A,@HL+	; A <-> (3x)
	BR	LOOP	

) XCH XA,@HL

Function: A <-> (HL), X <-> (HL+1)

Exchanges the contents of the A register with the data at the data memory location addressed by the HL register pair, and exchanges the contents of the X register with the data at the next memory address.

However, if the contents of the L register are odd- numbered, an address with the low-order bit ignored is specified.



XCH A,mem

Function: A $\langle - \rangle$ (mem) mem = D₇₋₀: 00H-FEH

Exchanges the contents of the A register with the data at the data memory location addressed by the 8bit immediate data mem.

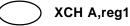


XCH XA,mem

Function: A $\langle - \rangle$ (mem), X $\langle - \rangle$ (mem+1) mem = D₇₋₀: 00H-FEH

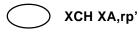
Exchanges the contents of the A register with the data at the data memory location addressed by the 8bit immediate data mem, and exchanges the contents of the X register 1 with the data at the next memory address.

An even address can be specified with mem.



Function: A <-> reg1

Exchanges the contents of the A register with register reg1 (X, H, L, D, E, B, C).



Function: XA <-> rp'

Exchanges the contents of the XA register pair with the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC').

11.4.2 Table Reference Instructions



Function: For the μ PD750106 and μ PD750108

 $XA \leftarrow ROM (PC_{12-8}+DE)$

Transfers the low-order four bits of the table data in program memory to the A register, and the high-order four bits to the X register. The table data is addressed by the program counter (PC) with its low-order eight bits (PC_{7-0}) exchanged with the contents of the DE register pair.

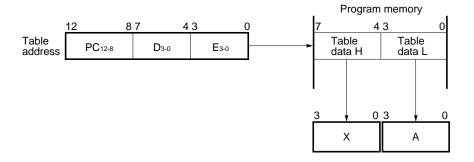
The table address is determined by the contents of the program counter (PC) present when this instruction is executed.

The table area must have necessary data loaded by an assembler pseudo instruction (DB instruction).

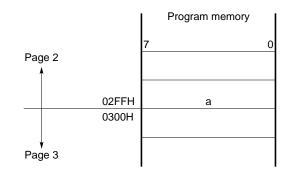
The program counter is not affected by the execution of the pseudo instruction.

This instruction is useful for consecutive table data references.

Example For the μ PD750106 and μ PD750108



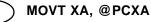
- **Remark** "Function" in this section is applicable to the μ PD750106 and μ PD750108 whose program counters consist of 13 bits each. This is also applicable to the μ PD750104 whose program counter consists of 12 bits and the μ PD75P0116 whose program counter consists of 14 bits, however.
- Caution The MOVT XA, @ PCDE instruction usually references table data in the page containing that instruction. However, when the instruction is located at address xxFFH, table data in the next page is referenced instead of table data in the page containing that instruction.



For example, if MOVT XA,@PCDE is located at a as shown above, the table data in page 3 specified by the contents of the DE register pair is transferred to the XA register pair instead of that in page 2.

Example The 16-byte data at addresses xxF0H-xxFFH in program memory is transferred to addresses 30H-4FH in data memory.

SEL	MB0	
MOV	HL,#30H	; HL <– 30H
MOV	DE,#0F0H	; DE <- F0H
MOVT	XA,@PCDE	; XA <- table data
MOV	@HL, XA	; (HL) <- XA
INCS	HL	; HL <– HL + 2
INCS	HL	
INCS	E	; E <– E + 1
BR	LOOP	
RET		
ORG	xxF0H	
DB	xxH, xxH,	; Table data
	MOV MOV MOVT MOV INCS INCS INCS BR RET ORG	MOV HL,#30H MOV DE,#0F0H MOVT XA,@PCDE MOV @HL, XA INCS HL INCS HL INCS E BR LOOP RET ORG xxF0H



Function: For the μ PD750106 and μ PD750108

XA <- ROM (PC₁₂₋₈+XA)

Transfers the low-order four bits of the table data in program memory to the A register, and the high-order four bits to the X register. The table data is addressed by the program counter (PC) with its low-order eight bits (PC_{7-0}) exchanged with the contents of the XA register pair.

The table address is determined by the contents of the program counter present when this instruction is executed.

The table area must have necessary data loaded by an assembler pseudo instruction (DB instruction). The program counter is not affected by the execution of this instruction.

Caution As with MOVT XA,@PCDE, when the instruction is located at address xxFFH, table data in the next page is transferred.

Remark "Function" in this section is applicable to the μ PD750106 and μ PD750108 whose program counters consist of 13 bits each. This is also applicable to the μ PD750104 whose program counter consists of 12 bits and the μ PD75P0116 whose program counter consists of 14 bits, however.

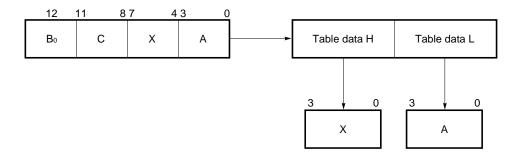
MOVT XA,@BCXA

Function: For the μ PD750106 and μ PD750108

XA <- (BCXA) _{ROM}

Transfers the low-order four bits of the table data (eight bits) in program memory to the A register, and the high-order four bits to the X register. The table data is addressed by the low-order one bit of the B register and the contents of the C, X, and A registers.

The table area must have necessary data loaded by an assembler pseudo instruction (DB instruction). The program counter is not affected by the execution of this instruction.



 \bigcirc

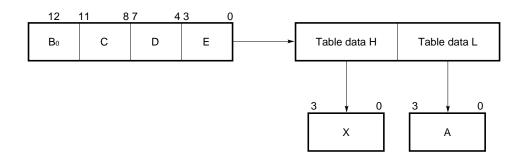
MOVT XA,@BCDE

Function: For the μ PD750106 and μ PD750108

XA <- (BCDE) ROM

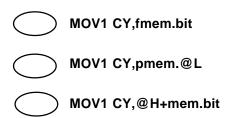
Transfers the low-order four bits of the table data (eight bits) in program memory to the A register, and the high-order four bits to the X register. The table data is addressed by the low-order three bits of the B register and the contents of the C, D, and E registers.

The table area must have necessary data loaded by an assembler pseudo instruction (DB instruction). The program counter is not affected by the execution of this instruction.



Remark "Function" in this section is applicable to the μ PD750106 and μ PD750108 whose program counters consist of 13 bits each. This is also applicable to the μ PD750104 whose program counter consists of 12 bits and the μ PD75P0116 whose program counter consists of 14 bits, however.





Function: CY <- (bit specified in operand)

Transfers the data memory bit specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit) to the carry flag (CY).



MOV1 @H+mem.bit,CY

Function: (bit specified in operand) <- CY

Transfers the carry flag (CY) bit to the data memory bit specified by bit manipulation addressing (fmem.bit, pmem.@L,@H+mem.bit)

Example The flag (bit 3 at address 3FH) in data memory is set in bit 2 of port 3.

FLAG EQU 3FH.3 SEL MB0 MOV H,#FLAG SHR6 ; H <- high-order 4 bits of FLAG MOV1 CY,@H+FLAG ; CY <- FLAG MOV1 PORT3.2,CY ; P32 <- CY

11.4.4 Arithmetic/Logical Instructions

) ADDS A,#n4

Function: A <- A+n4 ; Skip if carry. $n4 = I_{3-0}$: 0-FH

Adds the 4-bit immediate data n4 to the contents of the A register in binary, then skips the next instruction if the addition generates a carry. The carry flag is not affected.

This instruction, when combined with the ADDC A, @HL or SUBC A, @HL instruction, functions as a number system conversion instruction. (See **Section 11.1**.)

ADDS XA,#n8

Function: $XA \le XA + n8$; Skip if carry. $n8 = I_{7-0}$: 00H-FFH

Adds the 8-bit immediate data n8 to the contents of the XA register pair in binary, then skips the next instruction if the addition generates a carry. The carry flag is not affected.



Function: A <- A+(HL) ; Skip if carry.

Adds the data at the data memory location addressed by the HL register pair to the contents of the A register in binary, then skips the next instruction if the addition generates a carry. The carry flag is not affected.

ADDS XA,rp'

Function: XA <- XA+rp'; Skip if carry.

Adds the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC') to the contents of the XA register pair in binary, then skips the next instruction if the addition generates a carry. The carry flag is not affected.

ADDS rp'1,XA

Function: rp' <- rp'1+XA ; Skip if carry.

Adds the contents of the XA register pair to the contents of register pair rp'1 (HL, DE, BC, XA', HL', DE', BC') in binary, then skips the next instruction if the addition generates a carry. The carry flag is not affected.

Example The register pair is left-shifted.

```
MOV XA, rp'1
ADDS rp'1, XA
NOP
```

) ADDC A,@HL

Function: A,CY <- A+(HL)+CY

Adds the data at the data memory location addressed by the HL register pair together with the carry flag to the contents of the A register in binary. If the addition generates a carry, the carry flag is set. If no carry is generated, the carry flag is reset.

If the execution of this instruction generates a carry when this instruction is immediately followed by the ADDS A,#n4 instruction, the ADDS A,#n4 instruction is skipped. If no carry is generated, the ADDS A,#n4 instruction is executed, and the skip function of the ADDS A,#n4 instruction is disabled. Accordingly, a combination of these instructions can be used for number system conversion. (See **Section 11.1**.)



Function: XA, CY <- XA+rp'+CY

Adds the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC') together with the carry flag to the contents of the XA register pair in binary. If the addition generates a carry, the carry flag is set. If no carry is generated, the carry flag is reset.

ADDC rp'1,XA

Function: rp'1, CY <- rp'1+XA+CY

Adds the contents of the XA register pair together with the carry flag to the contents of register pair rp'1 (HL, DE, BC, XA', HL', DE', BC') in binary. If the addition generates a carry, the carry flag is set. If no carry is generated, the carry flag is reset.

) SUBS A,@HL

Function: A <- A-(HL) ; Skip if borrow

Subtracts the data at the data memory location addressed by the HL register pair from the contents of the A register, then sets the result in the A register. If the subtraction generates a borrow, the immediately following instruction is skipped.

The carry flag is not affected.

SUBS XA,rp'

Function: XA <- XA-rp'; Skip if borrow

Subtracts the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC') from the contents of the XA register pair, then sets the result in the XA register pair. If the subtraction generates a borrow, the immediately following instruction is skipped.

The carry flag is not affected.

Example Data memory is compared with register pair rp'.

MOV XA, mem SUBS XA, rp'

; (mem) ≥ rp' ; (mem) < rp'

) SUBS rp'1,XA

Function: rp'1 <- rp'1+XA ; Skip if borrow

Subtracts the contents of the XA register pair from the contents of register pair rp'1 (HL, DE, BC, XA', HL', DE', BC'), then sets the result in register pair rp'1. If the subtraction generates a borrow, the immediately following instruction is skipped.

The carry flag is not affected.

) SUBC A,@HL

Function: A, CY <- A-(HL)-CY

Subtracts the data at the data memory location addressed by the HL register pair together with the carry flag from the contents of the A register, then sets the result in the A register. If the subtraction generates a borrow, the carry flag is set. If no borrow is generated, the carry flag is reset.

If the execution of this instruction generates no borrow when this instruction is followed by the ADDS A, #n4 instruction, the ADDS A, #n4 instruction is skipped. If a borrow is generated, the ADDS A, #n4 instruction is executed, and the skip function of the ADDS A, #n4 instruction is disabled. Accordingly, a combination of these instructions can be used for number system conversion. (See **Section 11.1**.)

SUBC XA,rp'

Function: XA, CY <- XA-rp'-CY

Subtracts the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC') together with the carry flag from the contents of the XA register pair, then sets the result in the XA register pair. If the subtraction generates a borrow, the carry flag is set. If no borrow is generated, the carry flag is reset.

) SUBC rp'1,XA

Function: rp'1, CY <- rp'1-XA-CY

Subtracts the contents of the XA register pair together with the carry flag from the contents of register pair rp'1 (HL, DE, BC, XA', HL', DE', BC'), then sets the result in register pair rp'1. If the subtraction generates a borrow, the carry flag is set. If no borrow is generated, the carry flag is reset.

) AND A,#n4

Function: A $\langle -A \land n4$ $n4 = I_{3-0}$: 0-FH

ANDs the contents of the A register with the 4-bit immediate data n4, then sets the result in the A register.

Example The high-order two bits of an accumulator are set to 0.

AND A,#0011B



Function: $A \leftarrow A \land (HL)$

ANDs the contents of the A register with the data at the data memory location addressed by the HL register pair, then sets the result in the A register.



Function: XA <- XA \lapht rp'

ANDs the contents of the XA register pair with the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC'), then sets the result in the XA register pair.



Function: rp'1 <- rp'1 \ XA

ANDs the contents of register pair rp'1 (HL, DE, BC, XA', HL', DE', BC') with the contents of the XA register pair, then sets the result in the specified register pair.

Function: A $- A \lor 4$ n4 = I₃₋₀: 0-FH

ORs the contents of the A register with the 4-bit immediate data n4, then sets the result in the A register.

Example The low-order three bits of an accumulator are set to 1.

OR A,#0111B

OR A,@HL

Function: $A \leftarrow A \lor (HL)$

ORs the contents of the A register with the data at the data memory location addressed by the HL register pair, then sets the result in the A register.



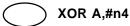
Function: XA <- XA v rp'

ORs the contents of the XA register pair with the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC'), then sets the result in the XA register pair.

OR rp'1,XA

Function: rp'1 <- rp' v XA

ORs the contents of register pair rp'1 (HL, DE, BC, XA', HL', DE', BC') with the contents of the XA register pair, then sets the result in register pair rp'1.



Function: A $- A \lor n4$ n4 = I₃₋₀: 0-FH

Exclusive-ORs the contents of the A register with the 4-bit immediate data n4, then sets the result in the A register.

Example The high-order four bits of an accumulator is inverted.

XOR A,#1000B

XOR A,@HL

Function: A <− A ∀ (HL)

Exclusive-ORs the contents of the A register with the data at the data memory location addressed by the HL register pair, then sets the result in the A register.



Function: XA <- XA v rp'

Exclusive-ORs the contents of the XA register pair with the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC'), then sets the result in the XA register pair.

XOR rp'1,XA

Function: rp'1 <- rp'1 \to XA

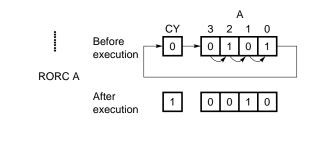
Exclusive-ORs the contents of register pair rp'1 (HL, DE, BC, XA', HL', DE', BC') with the contents of the XA register pair, then sets the result in register pair rp'1.

11.4.5 Accumulator Manipulation Instructions



Function: CY <- A_0 , A_{n-1} <- A_n , A_3 <- CY (n = 1-3)

Rotates the contents of the A register (4-bit accumulator) through the carry flag one bit position to the right.





Function: $A \leftarrow \overline{A}$

Obtains the one's complement of the A register (4-bit accumulator), that is, inverts each bit of the A register.

11.4.6 Increment/Decrement Instructions

INCS reg

Function: reg <- reg+1 ; Skip if reg = 0

Increments the contents of register reg (X, A, H, L, D, E, B, C). If the result of increment produces reg = 0, the immediately following instruction is skipped.

INCS rp1

Function: rp1 <- rp1+1 ; Skip if rp1 = 00H

Increments the contents of register pair rp1 (HL, DE, BC). If the result of increment produces rp1 = 00H, the immediately following instruction is skipped.

) INCS @HL

Function: (HL) \leq (HL)+1 ; Skip if (HL) = 0

Increments the data at the data memory location addressed by the HL register pair. If the result of increment produces data that is 0, the immediately following instruction is skipped.

) INCS mem

Function: (mem) <- (mem)+1 ; Skip if (mem) = 0, mem = D_{7-0} : 00H-FFH

Increments the data at the data memory location addressed by the 8-bit immediate data mem. If the result of increment produces data that is 0, the immediately following instruction is skipped.



Function: reg <- reg-1 ; Skip if reg = FH

Decrements the contents of register reg (X, A, H, L, D, E, B, C). If the result of decrement produces reg = FH, the immediately following instruction is skipped.



Function: rp' <- rp'-1 ; Skip if rp' = FFH

Decrements the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC'). If the result of decrement produces rp' = FFH, the immediately following instruction is skipped.

11.4.7 Compare Instructions

```
SKE SKE
```

SKE reg,#n4

Function: Skip if reg = n4 $n4 = I_{3-0}$: 0-FH

Skips the immediately following instruction if the contents of register reg (X, A, H, L, D, E, B, C) match the 4-bit immediate data n4.

\bigcirc

SKE @HL,#n4

Function: Skip if (HL) = n4 $n4 = I_{3-0}$: 0-FH

Skips the immediately following instruction if the data at the data memory location addressed by the HL register pair match the 4-bit immediate data n4.

SKE A,@HL

Function: Skip if A = (HL)

Skips the immediately following instruction if the contents of the A register match the data at the data memory location addressed by the HL register pair.

) SKE XA,@HL

Function: Skip if A = (HL) and X = (HL+1)

Skips the immediately following instruction if the contents of the A register match the data at the data memory location addressed by the HL register pair, and the contents of the X register match the data at the next address in data memory.

However, if the contents of the L register are odd- numbered, an address with the lowest-order bit ignored is specified.

SKE A,reg

Function: Skip if A = reg

Skips the immediately following instruction if the contents of the A register match the contents of register reg (X, A, H, L, D, E, B, C).

SKE XA,rp'

Function: Skip if XA = rp'

Skips the immediately following instruction if the contents of the XA register pair match the contents of register pair rp' (XA, HL, DE, BC, XA', HL', DE', BC').

11.4.8 Carry Flag Manipulation Instructions

Function: CY <- 1

Sets the carry flag.

Function: CY <- 0

Clears the carry flag.



SKT CY

Function: Skip if CY = 1

Skips the immediately following instruction if the carry flag is set to 1.

Function: $CY < -\overline{CY}$

Inverts the carry flag. If it is 0, it is set to 1, or vice versa.

11.4.9 Memory Bit Manipulation Instructions

SET1 mem.bit

Function: (mem.bit) <-1 mem = D₇₋₀: 00H-FFH, bit = B₁₋₀: 0-3

Sets the bit specified by the 2-bit immediate data bit at the address specified by the 8-bit immediate data mem.



Function: (Bit specified in operand) <- 1

Sets the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit). CLR1 mem.bit



Function: (mem.bit) < -0 mem = D₇₋₀: 00H-FFH, bit = B₁₋₀: 0-3

Clears the bit specified by the 2-bit immediate data bit at the address specified by the 8-bit immediate data mem.

CLR1 fmem.bit CLR1 pmem.@L CLR1 @H+mem.bit

```
Function: (Bit specified in operand) <- 0
```

Clears the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit). SKT mem.bit

SKT mem.bit

Function: Skip if (mem.bit) = 1 mem = D_{7-0} : 00H-FFH, bit = B_{1-0} : 0-3

Skips the immediately following instruction if the bit specified by the 2-bit immediate data bit at the address specified by the 8-bit immediate data mem is 1.



SKT pmem.@L

SKT @H+mem.bit

Function: Skip if (bit specified in operand) = 1

Skips the immediately following instruction if the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit) is set to 1.

SKF mem.bit

Function: Skip if (mem.bit) = 0 mem = D_{7-0} : 00H-FFH, bit = B_{1-0} : 0-3

Skips the immediately following instruction if the bit specified by the 2-bit immediate data bit at the address specified by the 8-bit immediate data mem is 0.

SKF fmem.bit SKF pmem.@L

SKF @H+mem.bit

Function: Skip if (bit specified in operand) = 0

Skips the immediately following instruction if the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit) is 0.

SKTCLR fmem.bit SKTCLR pmem.@L SKTCLR @H+mem.bit

Function: Skip if (bit specified in operand) = 1 then clear

Skips the immediately following instruction if the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit) is 1, then clears the bit to 0.

AND1 CY,fmem.bit

AND1 CY,pmem.@L

AND1 CY,@H+mem.bit

Function: CY <- CY (bit specified in operand)

ANDs the content of the carry flag with the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit), then sets the result in the carry flag.

OR1 CY,fmem.bit

) OR1 CY,pmem.@L

) OR1 CY,@H+mem.bit

Function: CY <- CY v (bit specified in operand)

ORs the content of the carry flag with the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit), then sets the result in the carry flag.

XOR1 CY,fmem.bit

XOR1 CY,@H+mem.bit

Function: CY <- CY v (bit specified in operand)

Exclusive-ORs the content of the carry flag with the bit in data memory specified by bit manipulation addressing (fmem.bit, pmem.@L, @H+mem.bit), then sets the result in the carry flag.

11.4.10 Branch Instructions

) BR addr

Function: For the μ PD750108 PC₁₂₋₀ <- addr addr = 0000H-1FFFH

Branches to the address specified by the immediate data addr.

This instruction is an assembler pseudo instruction, and the assembler automatically replaces this instruction with the BR laddr instruction, BRCB lcaddr instruction, or BR \$addr instruction as required at assembly time.

II) BR addr1

Function: For the μ PD750108 PC₁₂₋₀ <- addr1 addr1 = 0000H-1FFFH

Branches to the address specified by the immediate data addr1.

This instruction is an assembler pseudo instruction, and the assembler automatically replaces this instruction with the BRA !addr1 instruction, BR !addr instruction, BRCB !caddr instruction, or BR \$addr1 instruction as required at assembly time.

Remark "Function" in this section is applicable to the μ PD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH).

However, this is also applicable to the μ PD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μ PD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μ PD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

BRA !addr1

Function: For the µPD750108 PC₁₂₋₀ <- addr1

) BR !addr

```
Function: For the \muPD750108 PC<sub>12-0</sub> <- addr
```

addr = 0000H-1FFFH

Transfers the immediate data addr to the program counter (PC), then branches to the location addressed by the program counter.

BR \$addr

Function: For the μPD750108 PC₁₂₋₀ <- addr addr = (PC-15) to (PC-1), (PC+2) to (PC+16)

Relative branch instruction with branch ranges of (-15 to -1) and (+2 to +16) from the current address. The instruction is not affected by page or block boundaries.

II) BR \$addr1

```
Function: For the μPD750108 PC<sub>12-0</sub> <- addr1
addr = (PC-15) to (PC-1), (PC+2) to (PC+16)
```

Relative branch instruction with branch ranges of (-15 to -1) and (+2 to +16) from the current address. The instruction is not affected by page or block boundaries. **Remark** "Function" in this section is applicable to the μ PD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH).

However, this is also applicable to the μ PD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μ PD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μ PD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

BRCB !caddr

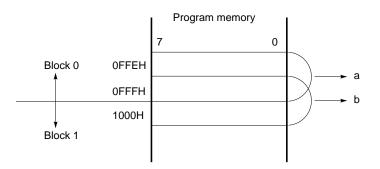
Function: For the μ PD750108 PC₁₂₋₀ <- PC₁₂ + caddr₁₁₋₀ caddr = n000H-nFFFH n = PC₁₂ = 0, 1

Branches to the address specified by the program counter whose low-order 12 bits (PC_{11-0}) have been replaced with the 12-bit immediate data caddr (A_{11-0}) .

Since the program counter of the μ PD750104 consists of 11 bits, this instruction enables a branch to any location in the program memory space.

In the μ PD750106 and μ PD750108, PC₁₂ cannot be changed, so no branch occurs beyond the block. Similarly, in the μ PD75P0116, PC₁₂ and PC₁₃ cannot be changed, so no branch occurs beyond the block.

Caution The BRCB !caddr instruction usually causes a branch within the block containing the instruction. However, if the first byte is located at address 0FFEH or 0FFFH, a branch to block 1 instead of block 0 occurs.



If the BRCB !caddr instruction is located at a or b in the figure above, a branch to block 1 instead of block 0 occurs.

Remark "Function" in this section is applicable to the μ PD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH).

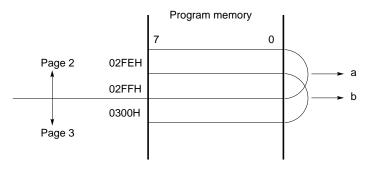
However, this is also applicable to the μ PD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μ PD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μ PD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

BR PCDE

Function: For the μ PD750108 PC₁₂₋₀ <- PC₁₂₋₈ + DE PC₇₋₄ <- D, PC₃₋₀ <- E

Branches to the address specified by the program counter whose low-order 8 bits (PC₇₋₀) have been replaced with the contents of the DE register pair. The high-order bits of the program counter are not affected.

Caution The BR PCDE instruction usually causes a branch within the page containing the instruction. However, if the first byte of the instruction code is located at address xxFEH or xxFFH, a branch to the next page instead of that page occurs.



If the BR PCDE instruction is located at a or b in the figure above, a branch to page 3 instead of page 2 occurs, jumping to the low-order 8 bits of the address specified by the contents of the DE register pair.



Function: For the μ PD750108 PC₁₂₋₀ <- PC₁₂₋₈ + XA PC₇₋₄ <- X, PC₃₋₀ <- A

Branches to the address specified by the program counter whose low-order 8 bits (PC₇₋₀) have been replaced with the contents of the XA register pair. The high-order bits of the program counter are not affected.

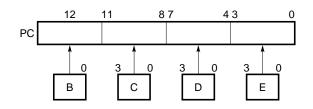
Caution As with the BR PCDE instruction, if the first byte is located at address xxFEH or xxFFH, a branch to the next page instead of the page containing the instruction occurs.

Remark "Function" in this section is applicable to the μPD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH).
 However, this is also applicable to the μPD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μPD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μPD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

) BR BCDE

Function: For the µPD750108 PC₁₂₋₀ <- BCDE

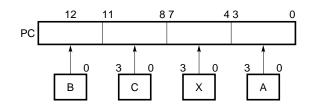
Branches to the address specified by the program counter whose bits have been replaced with the contents of the B_0 , C, D, and E registers.



BR BCXA

Function: For the µPD750108 PC₁₂₋₀ <- BCXA

Branches to the address specified by the program counter whose bits have been replaced with the contents of the B_0 , C, X, and A registers.



TBR addr

Function: Assembler pseudo instruction of the GETI instruction for table definition. This instruction is used to replace a 3-byte BR instruction with a 1-byte GETI instruction. The 12-bit address data must be coded in addr. For detailed information, refer to RA75X Assembler Package User's Manual: Language (EEU-1363).

 Remark "Function" in this section is applicable to the μPD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH). However, this is also applicable to the μPD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μPD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μPD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

11.4.11 Subroutine Stack Control Instructions

II CALLA !addr1

Function: For the μ PD750108 (SP-2) <- x, x, MBE, RBE, (SP-3) <- PC₇₋₄ (SP-4) <- PC₃₋₀, (SP-5) <- 0, 0, 0, PC₁₂ (SP-6) <- PC₁₁₋₈ PC₁₂₋₀ <- addr1, SP <- SP-6

I/II CALL !addr

Function: For the μ PD750108

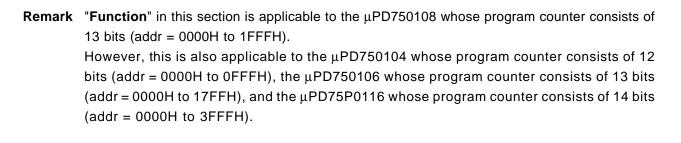
[Mk I mode] (SP-1) <- PC₇₋₄, (SP-2) <- PC₃₋₀ (SP-3) <- MBE, RBE, 0, PC₁₂ (SP-4) <- PC₁₁₋₈, PC₁₂₋₀ <- addr, SP <- SP-4

addr = 0000H - 1FFFH

[Mk II mode] (SP-2) <- x, x, MBE, RBE (SP-3) <- PC₇₋₄, (SP-4) <- PC₃₋₀ (SP-5) <- 0, 0, 0, PC₁₂, (SP-6) <- PC₁₁₋₈ PC₁₂₋₀ <- addr, SP <- SP-6

addr = 0000H - 1FFFH

Saves the contents of the program counter (return address), memory bank enable flag (MBE), and register bank enable flag (RBE) to the data memory location (stack) addressed by the stack pointer (SP), then branches to the location addressed by the 14-bit immediate data addr after decrementing SP.



I/II CALLF !faddr

Function: For the μ PD750108

[Mk I mode] (SP-1) <- PC₇₋₄, (SP-2) <- PC₃₋₀ (SP-3) <- MBE, RBE, 0, PC₁₂ (SP-4) <- PC₁₁₋₈, SP <- SP - 4 PC₁₂₋₀ <- 00 + faddr

faddr = 0000H - 07FFH

[Mk II mode] (SP-2) <- x, x, MBE, RBE (SP-3) <- PC_{7-4} , (SP-4) <- PC_{3-0} (SP-5) <- 0, 0, 0, PC_{12} , (SP-6) <- PC_{11-8} SP <- SP-6 PC_{12-0} <- 00 + faddr

faddr = 0000H - 07FFH

Saves the contents of the program counter (PC; Return address), memory bank enable flag (MBE), and register bank enable flag (RBE) to the data memory location (stack) addressed by the stack pointer (SP), then branches to the location addressed by the 11-bit immediate data faddr after decrementing SP. Only the address range 0000H-07FFH (0-2047) can be called.



TCALL !addr

- Function: Assembler pseudo instruction of the GETI instruction for table definition. This instruction is used to replace a 3-byte CALL laddr instruction with a 1-byte GETI instruction. The 12-bit address data must be coded in addr. For detailed information, refer to RA75X Assembler Package User's Manual: Language (EEU-1363).
- Remark "Function" in this section is applicable to the μPD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH).
 However, this is also applicable to the μPD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μPD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μPD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

(//I) RET

Function: For the µPD750108

[Mk I mode]	PC ₁₁₋₈ <- (SP)
	MBE, RBE, 0, PC ₁₂ <- (SP+1)
	PC ₃₋₀ <- (SP+2)
	PC ₇₋₄ <- (SP+3), SP <- SP+4
[Mk II mode]	PC ₁₁₋₈ <- (SP), x, x, x, PC ₁₂ <- (SP+1)
	PC ₃₋₀ <- (SP+2), PC ₇₋₄ <- (SP+3)
	x, x, MBE, RBE <- (SP+4)
	SP <- SP+6

Restores the program counter (PC), memory bank enable flag (MBE), and register bank enable flag (RBE) with the data at the data memory location (stack) addressed by the stack pointer (SP), then increments the contents of SP.

Caution The program status word (PSW) is not restored except MBE and RBE.

Remark "Function" in this section is applicable to the μ PD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH). However, this is also applicable to the μ PD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μ PD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μ PD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

I/II) RETS

Function: For the μ PD750108

[Mk I mode]	PC ₁₁₋₈ <- (SP)
	MBE, 0, 0, PC ₁₂ <- (SP+1)
	PC ₃₋₀ <- (SP+2), PC ₇₋₄ <- (SP+3), SP <- SP+4
	Then skip unconditionally
[Mk II mode]	PC ₁₁₋₈ <- (SP), 0, 0, 0, PC ₁₂ <- (SP+1)
	PC ₃₋₀ <- (SP+2), PC ₇₋₄ <- (SP+3)
	x, x, MBE, RBE <- (SP+4)
	SP <- SP+6
	Then skip unconditionally

Restores the program counter (PC), memory bank enable flag (MBE), and register bank enable flag (RBE) with the data at the data memory location (stack) addressed by the stack pointer (SP), then skips unconditionally after incrementing the contents of SP.

Caution The program status word (PSW) is not restored except MBE and RBE.

Remark "Function" in this section is applicable to the μ PD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH).

However, this is also applicable to the μ PD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μ PD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μ PD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

I/II) RETI

Function: For the μ PD750108

[Mk I mode]	PC ₁₁₋₈ <- (SP), MBE, RBE, 0, PC ₁₂ <- (SP+1)
	PC ₃₋₀ <- (SP+2)
	PC ₇₋₄ <- (SP+3)
	PSW _L <- (SP+4), PSW _H <- (SP+5)
	SP <- SP+6
[Mk II mode]	PC ₁₁₋₈ <- (SP), 0, 0, 0, PC ₁₂ <- (SP+1)
	PC ₃₋₀ <- (SP+2)
	PC ₇₋₄ <- (SP+3),
	PSW _L <- (SP+4), PSW _H <- (SP+5)
	SP <- SP+6

Restores the program counter (PC) and program status word with the data at the data memory location (stack) addressed by the stack pointer (SP), then increments the contents of SP.

This instruction is used when control is returned from an interrupt service routine.

Remark "Function" in this section is applicable to the μPD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH). However, this is also applicable to the μPD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μPD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μPD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

🔵 🔵 PUSH rp

Function: (SP-1) <- rp_H, (SP-2) <- rp_L, SP <- SP-2

Saves the contents of register pair rp (XA, HL, DE, BC) to the data memory location (stack) addressed by the stack pointer (SP), then decrements SP.

The high-order part of a register pair (rp_H : X, H, D, B) is saved to the stack location addressed by (SP–1), and the low-order part (rp_L : A, L, E, C) is saved to the stack location addressed by (SP–2).

) PUSH BS

Function: (SP-1) <- MBS, (SP-2) <- RBS, SP <- SP-2

Saves the contents of the memory bank select register (MBS) and the register bank select register (RBS) to the data memory location (stack) addressed by the stack pointer (SP), then decrements SP.



Function: rp_L <- (SP), rp_H <- (SP+1), SP <- SP+2

Restores register pair rp (XA, HL, DE, BC) with the data at the data memory location (stack) addressed by the stack pointer (SP), then increments SP.

The low-order part of a register pair (rp_L: A, L, E, C) is restored from the contents of (SP), and the highorder part (rp_H: X, H, D, B) is restored with the contents of (SP+).

POP BS

Function: RBS <- (SP), MBS <- (SP+1), SP <- SP+2

Restores the register bank select register (RBS) and the memory bank select register (MBS) with the data at the data memory location (stack) addressed by the stack pointer (SP), then increments SP.

11.4.12 Interrupt Control Instructions



Function: IME (IPS.3) <- 1

Sets the interrupt master enable flag (bit 3 of the interrupt priority specification register) to 1 to enable interrupts. Whether to accept an interrupt is controlled with the corresponding interrupt enable flag.

🔵 El IExxx

Function: IExxx < -1 $xxx = N_5$, N_{2-0}

Sets an interrupt enable flag (IExxx) to 1 to enable an interrupt. (xxx = BT, CSI, T0, T1, W, 0, 1, 2, 4)

Function: IME (IPS.3) < -0

Resets the interrupt master enable flag (bit 3 of the interrupt priority specification register) to 0 to disable all interrupts regardless of the states of the interrupt enable flags.

Function: IExxx <- 0 $xxx = N_5$, N_{2-0}

Resets an interrupt enable flag (IExxx) to 0 to disable an interrupt. (xxx = BT, CSI, T0, T1, W, 0, 1, 2, 4)

11.4.13 I/O Instructions

IN A,PORTn

Function: $A \leftarrow PORTn$ $n = N_{3-0}$: 0-8

Transfers the contents of the port specified by PORTn (n = 0.8) to the A register.

Caution Before this instruction can be executed, MBE = 0 or (MBE = 1, MBS = 15) must be set. A number from 0 to 8 can be specified as n. Depending on I/O mode specification, output latch data (in the output mode) or pin data (in the input mode) are transferred.

IN XA,PORTn

Function: A <- PORTn, X <- PORT $_{n+1}$ n = N₃₋₀: 4, 6

Transfers the contents of the port specified by PORTn (n = 4 or 6) to the A register, then transfers the contents of the next port to the X register.

Caution Only the number 4 or 6 can be specified as n. Before this instruction can be executed, MBE = 0 or (MBE = 1, MBS = 15) must be set. Depending on I/O mode specification, output latch data (in the output mode) or pin data (in the input mode) are transferred.

) OUT PORTn, A

Function: PORTn -A n = N₃₋₀: 2-8

Transfers the contents of the A register to the output latch of the port specified by PORTn (n = 2-8).

Caution Before this instruction can be executed, MBE = 0 or (MBE = 1, MBS = 15) must be set. A number from 2 to 8 can be specified as n.

) OUT PORTn, XA

Function: PORTn <- A, PORT_{n+1} <- X $n = N_{3-0}$: 4, 6

Transfers the contents of the A register to the output latch of the port specified by PORTn (n = 4, 6), then transfers the contents of the X register to the output latch of the next port.

Caution Before this instruction can be executed, MBE = 0 or (MBE = 1, MBS = 15) must be set. Only 4 or 6 can be specified as n.

11.4.14 CPU Control Instructions

HALT

Function: PCC.2 <- 1

Sets the HALT mode. (This instruction is used to set bit 2 of the processor clock control register.)

Caution The instruction immediately following a HALT instruction must be a NOP instruction.



Function: PCC.3 <- 1

Sets the STOP mode. (This instruction is used to set bit 3 of the processor clock control register.)

Caution The instruction immediately following a STOP instruction must be a NOP instruction.



Function: Uses one machine cycle without performing an action.

11.4.15 Special Instructions

SEL RBn

Function: RBS <-n $n = N_{1-0}$: 0-3

Sets the 2-bit immediate data n in the register bank select register (RBS).

) SEL MBn

Function: MBS <-n $n = N_{3-0}$: 0, 1, 15

Transfers the 4-bit immediate data n to the memory bank select register (MBS). Only 0, 1, or 15 can be specified as n.

I/II GETI taddr

```
Function: taddr = T_{5-0}, 0 : 20H-7FH
```

For the μ PD750108

[Mk I mode]

- When a table defined by the TBR instruction is referenced PC₁₂₋₀ <- (taddr)₄₋₀ + (taddr+1)
- When a table defined by the TCALL instruction is referenced $(SP-1) <- PC_{7-4}, (SP-2) <- PC_{3-0}$ $(SP-3) <- MBE, RBE, 0, PC_{12}$ $(SP-4) <- PC_{11-8}$ $PC_{12-0} <- (taddr)_{4-0} + (taddr+1)$ SP <- SP-4
- When a table defined by an instruction other than the TBR or TCALL instruction is referenced

An instruction using (taddr) (taddr+1) as its operation code is executed.

[Mk II mode]

- When a table defined by the TBR instruction is referenced PC₁₂₋₀ <- (taddr)₄₋₀ + (taddr+1)
- When a table defined by the TCALL instruction is referenced

(SP-2) <- x, x, MBE, RBE

 $(SP-3) < - PC_{7-4}, (SP-4) < - PC_{3-0}$ $(SP-5) < -0, 0, 0, PC_{12}, (SP-6) < - PC_{11-8}$ $PC_{12-0} < - (taddr)_{4-0} + (taddr+1)$

SP <- SP-6

• When a table defined by an instruction other than the TBR or TCALL instruction is referenced

An instruction using (taddr) (taddr+1) as its operation code is executed.

Remark "Function" in this section is applicable to the μ PD750108 whose program counter consists of 13 bits (addr = 0000H to 1FFFH).

However, this is also applicable to the μ PD750104 whose program counter consists of 12 bits (addr = 0000H to 0FFFH), the μ PD750106 whose program counter consists of 13 bits (addr = 0000H to 17FFH), and the μ PD75P0116 whose program counter consists of 14 bits (addr = 0000H to 3FFFH).

The 2-byte data at the program memory addresses specified by (taddr) and (taddr+1) is referenced and executed as an instruction.

Addresses 0020H to 007FH are used as a reference table area. Data must be written to this area beforehand. When a 1-byte instruction or 2-byte instruction is written, its mnemonic can be used directly.

For a 3-byte call instruction or 3-byte branch instruction, an assembler pseudo instruction (TCALL, TBR) is used.

Only an even address can be specified as taddr.

Caution All 2-byte instructions (except the BRCB instruction and CALLF instruction) set in the reference table must be 2-machine-cycle instructions. Pairs of 1-byte instructions can be set as indicated in the table below.

First byte instruction	Second byte instruction
MOV A,@HL MOV @HL,A XCH A,@HL	INCS L DECS L INCS H DECS H INCS HL
MOV A,@DE XCH A,@DE	INCS E DECS E INCS D DECS D INCS DE
MOV A,@DL XCH A,@DL	INCSL DECS INCSD DECS

The PC is not incremented during execution of a GETI instruction, so that after a reference instruction is executed, execution is resumed starting at the address immediately after the GETI instruction.

If the instruction immediately preceding a GETI instruction has the skip function, the GETI instruction is skipped as with other 1-byte instructions. If an instruction referenced with a GETI instruction has the skip function, the instruction immediately following the GETI instruction is skipped.

If a GETI instruction references an instruction having a string effect, the following processing is performed:

- If the instruction immediately preceding the GETI instruction also has the string effect in the same group, the execution of the GETI instruction cancels the string effect, and the referenced instruction is not skipped.
- If the instruction immediately following the GETI instruction also has the string effect of the same group, the string effect of the referenced instruction remains valid, and the next instruction is skipped.

Example			
MOV I			
<		FH are rep	laced with GETI instructions.
CALL			
BR	20B2	ORG	20H
HLOO:		MOV	HL, #00H
XAFF: I			ГП
		TCALL SUB1	
BSUB2:		TBR	SUB2
		:	
		-	
		:	
	GET	T HLOO	; MOV HL,#00H
	÷		
	:		
	:		
	:		
	GET	TI BSUB2	; BR SUB2
	:		
	÷		
	:		
	÷		
	GET	TI CSUB1	; CALL SUB1
	:		
	:		
	÷		
	:		
	GET	TI XAFF	; MOV XA,#FFH
			,

APPENDIX A FUNCTIONS OF THE $\mu\text{PD750008},\,\mu\text{PD750108},\,\text{AND}\,\,\mu\text{PD75P0116}$

				(1/2	
Item		μPD750008	μPD750108	μPD75P0116	
Program memory		Masked ROM 0000H - 1FFFH (8192 x 8 bits)		One-time PROM 0000H - 3FFFH (16384 x 8 bits)	
Data	memory	000H - 1FFH (512 x 4 bits)			
CPU		75XL CPU			
Gene	ral-purpose register	(4 bits x 8 or 8 bits x 4)	x 4 banks		
Main	system clock oscillator	Crystal/ceramic oscillator	RC oscillator (with exte capacitor)	rnal resistor and	
Time	required for start after reset	2 ^{17/f} _X , 2 ^{15/f} _X (selected using a mask option)	Fixed to 56/f _{CC}		
	time applied when STOP is released by an interrupt	$2^{20/f}_{\rm X},~2^{17/f}_{\rm X},~2^{15/f}_{\rm X},~2^{13/f}_{\rm X}$ (selected according to BTM setting)	2 ^{9/f_{CC} or no wait (selected using a mask option)}	Fixed to 2 ⁹ /f _{CC}	
Subsystem clock oscillator		Crystal oscillator			
When selecting the main system clock		 0.95, 1.91, 3.81, 15.3 μs (when operating at 4.19 MHz) 0.67, 1.33, 2.57 10.7 μs (when operating at 6.0 MHz) 	• 2, 4, 8, 32 μs (when operating at 2 MHz)		
Φ	When selecting the subsystem clock	122 μs (when operating at 32.768 kHz)			
	20 (CU)	IC		V _{PP}	
	38 (GB)				
	24 (CU)	P21/PTO1			
ج 42 (GB)					
necti	6-9 (CU)			P33/MD3 - P30/MD0	
Pin connection	23-26 (GB)				
Pin	38-41 (CU)			P43/D3 - P40/D0	
	13-16 (GB)				
	34-37 (CU)	P53 - P50		P53/D7 - P50/D4	
	8-11 (GB)				

(2/2)

	Item	μΡD750008 μΡD750108		μPD75P0116	
	CMOS input	8 (Built-in pull-up resistors that can be connected by software: 7)			
τ	CMOS I/O	18 (Built-in pull-up resisted	18 (Built-in pull-up resistors that can be connected by software)		
I/O port	N-ch open-drain I/O	mask option)	8 (Pull-up resistors that can be incorporated by mask option) Withstand voltage of 13 V		
	Total	34			
Timer		 4 channels 8-bit timer counter: 1 8-bit timer/event counter: 1 Basic interval timer/ watchdog timer: 1 Clock timer: 1 	 8-bit timer counter: 1 8-bit timer counter (clock timer output funct provided): 1 8-bit timer/event counter: 1 		
Serial interface		 3 modes supported Three-wire serial I/O mode: First transferred bit switchable between LSB and MSB Two-wire serial I/O mode SBI mode 			
Clock output (PCL)		 Φ, 524, 262, 65.5 kHz (when the main system clock operates at 4.19 MHz) Φ, 750, 375, 93.8 kHz (when the main system clock operates at 6.0 MHz) 	• Φ , 250, 125, 31.3 kHz (when the main system		
Buzzer output (BUZ)		 2, 4, 32 kHz (when the main system clock operates at 4.19 MHz or the subsystem clock operates at 32.768 kHz) 2.93, 5.86, 46.9 kHz (when the main system clock operates at 6.0 MHz) 	 operates at 32.768 kHz) 0.488, 0.977, 7.813 kHz (when the main system clock operates at 1 MHz) 0.977, 1.953, 15.625 kHz (when the main system clock operates at 2 MHz) 		
Vecto	pred interrupt	External: 3, internal: 4			
Test	input	External: 1, internal: 1			
Supp	ly voltage	V _{DD} = 2.2 to 5.5 V	V _{DD} = 1.8 to 5.5 V		
Oper	ating ambient temperature	$T_{A} = -40$ to +85 °C			
Package		 42-pin plastic shrink DIP (600 mil) 44-pin plastic QFP (10 x 10 mm) 			

APPENDIX B DEVELOPMENT TOOLS

The following development tools are provided for the development of a system which employs the μ PD750108. In the 75XL series, use the common relocatable assembler together with a device file of each model.

RA75X relocatable assembler	Host machine	OS	Distribution media	Part number
	PC-9800 series	MS-DOS / Ver. 3.30	3.5-inch 2HD	μS5A13RA75X
		(to Ver. 6.2 ^{Note})	5.25-inch 2HD	μS5A10RA75X
	IBM PC/AT™	See "OS for IBM	3.5-inch 2HC	μS7B13RA75X
	and compatibles	PC."	5.25-inch 2HC	μS7B10RA75X

Device file	Host machine			Part number
	riost machine	OS	Distribution media	Fait number
	PC-9800 series	MS-DOS	3.5-inch 2HD	μS5A13DF750008
		/ Ver. 3.30		
		(to ──Ver. 6.2 ^{Note})	5.25-inch 2HD	μS5A10DF750008
	IBM PC/AT and	See "OS for IBM	3.5-inch 2HC	μS7B13DF750008
	compatibles	PC."	5.25-inch 2HC	μS7B10DF750008

- **Note** These software products cannot use the task swap function, which is available in MS-DOS Ver. 5.00 or later.
- **Remark** The operations of the assembler and device file are guaranteed only on the above host machines and OSs.

PROM programming tools

Hardware	PG-1500	The PG-1500 PROM programmer is used together with an accessory board and optional program adapter. It allows the user to program a single chip microcomputer containing PROM from a standalone terminal or a host machine. The PG-1500 can be used to program typical 256K-bit to 4M-bit PROMs.			
	PA-75P008CU	P008CU The PA-75P008CU is a PROM programmer adapter provided f μPD75P0116CU/GB. It is used in conjunction with the PG-150			
Software	PG-1500 controller				through the serial and
		Host machine		Part number	
	PC-9800 series		OS	Distribution media	r art number
		MS-DOS / Ver. 3.30	3.5-inch 2HD	μS5A13PG1500	
			(to Ver. 6.2 ^{Note})	5.25-inch 2HD	μS5A10PG1500
		IBM PC/AT and compatibles	See "OS for IBM	3.5-inch 2HD	μS7B13PG1500
			PC."	5.25-inch 2HC	μS7B10PG1500

Note These software products cannot use the task swap function, which is available in MS-DOS Ver. 5.00 or later.

Remark Operation of the PG-1500 controller is guaranteed only on the above host machines and OSs.

Debugging tools

The in-circuit emulators (IE-75000-R and IE-75001-R) are provided to debug programs used for the μ PD750108.

The following system is shown below.

IE-75000-R ^{Note 1}		The IE-75000-R is an in-circuit emulator used to debug hardware and software when developing an application system using the 75X series and 75XL series. Use this emulator together with optional emulation board IE-75300-R-EM and emulation probe to develop application systems of the µPD750108 subseries.				
		For efficient debu PROM programm		emulator to the host	machine and a	
		The IE-75000-R c connected to the		oard IE-75000-R-EN	M. The board is	
IE-75001-R		The IE-75001-R is an in-circuit emulator used to debug hardware and software when developing an application system using the 75X series and 75XL series. Use this emulator together with optional emulation board IE-75300-R-EM and emulation probe.				
Hardware		For efficient debu PROM programm		emulator to the host	machine and a	
Harc	IE-75300-R-EM	The IE-75300-R-EM is an emulation board used to evaluate an application system using the μ PD750108 subseries.				
		Use this board together with the IE-75000-R or IE-75001-R.				
	EP-75008GB-R	The EP-75008GB-R is an emulation probe for the μPD750108GB.				
		Connect this emu 75300-R-EM.	Connect this emulation probe to the IE-75000-R or IE-75001-R, and the IE-75300-R-EM.			
	EV-9200G-44	A 44-pin conversion socket, the EV-9200G-44, supplied with this probe facili- tates the connection of the probe to the target system.				
	EP-75008CU-R	The EP-75008CU-R is an emulation probe for the μPD750108CU.				
		Connect this emulation probe to the IE-75000-R or IE-75001-R, and the IE-75300-R-EM.				
	IE control program	This program enables the host machine to control the IE-75000-R or IE-75001- R through the RS-232-C and Centronics interface.			75000-R or IE-75001-	
are		Host machine	OS	Distribution media	Part number	
Software		PC-9800 series	(MS-DOS	3.5-inch 2HD	μS5A13IE75X	
Ō			Ver. 3.30 to Ver. 6.2 ^{Note 2}	5.25-inch 2HD	μS5A10IE75X	
		IBM PC/AT and		3.5-inch 2HC	μS7B13IE75X	
		compatibles		5.25-inch 2HC	μS7B10IE75X	

Notes 1. Maintenance service only

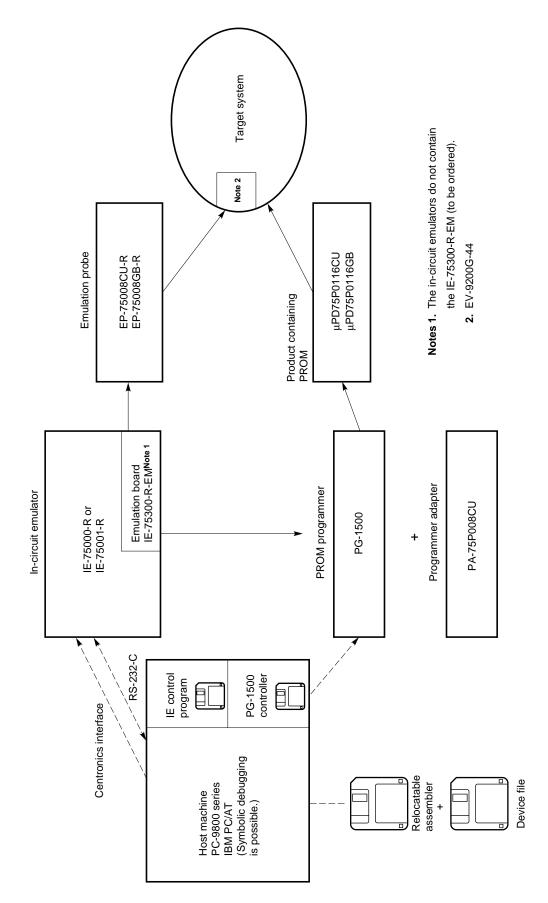
- 2. These software products cannot use the task swap function, which is available in MS DOS Ver. 5.00 or later.
- Remarks 1. Operation of the IE control program is guaranteed only on the above host machines and OSs.
 - **2.** The μ PD750104, μ PD750106, μ PD750108, and μ PD75P0116 are collectively referred to as the μ PD750108 subseries.

OS for IBM PC

The following IBM PC OSs are supported.

OS	Version
PC DOS	Ver. 5.02 to Ver. 6.3 J6.1/V ^{Note} to J6.3/V ^{Note}
MS-DOS	Ver. 5.0 to Ver. 6.22 5.0/VNote to 6.2/VNote
IBM DOS™	J5.02/VNote

- **Note** Only English version is supported.
- Caution These software products cannot use the task swap function, which is available in MS-DOS Ver. 5.00 or later.

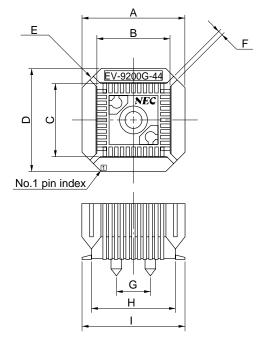


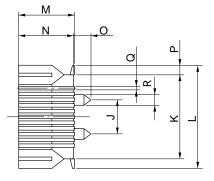
Development Tool Configuration

Drawings of the Conversion Socket (EV-9200G-44) and Recommended Pattern on Boards



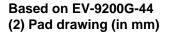
Based on EV-9200G-44 (1) Package drawing (in mm)

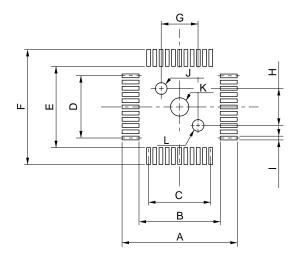




		EV-9200G-44-G0
ITEM	MILLIMETERS	INCHES
А	15.0	0.591
В	10.3	0.406
С	10.3	0.406
D	15.0	0.591
Е	4-C 3.0	4-C 0.118
F	0.8	0.031
G	5.0	0.197
Н	12.0	0.472
I	14.7	0.579
J	5.0	0.197
к	12.0	0.472
L	14.7	0.579
М	8.0	0.315
0	7.8	0.307
Ν	2.0	0.079
Р	1.35	0.053
Q	0.35±0.1	$0.014_{-0.005}^{+0.004}$
R	ø1.5	ø0.059

Figure B-2. Recommended Pattern on Boards for the EV-9200G-44 (Reference)





		EV-9200G-44-P1E
ITEM	MILLIMETERS	INCHES
A	15.7	0.618
В	11.0	0.433
С	$0.8\pm0.02 \times 10=8.0\pm0.05$	$0.031^{+0.002}_{-0.001} \times 0.394 {=} 0.315 ^{+0.002}_{-0.002}$
D	$0.8\pm0.02 \times 10=8.0\pm0.05$	$0.031^{+0.002}_{-0.001} \times 0.394 {=} 0.315 {}^{+0.002}_{-0.002}$
E	11.0	0.433
F	15.7	0.618
G	5.00±0.08	$0.197\substack{+0.003\\-0.004}$
Н	5.00±0.08	$0.197\substack{+0.003\\-0.004}$
I	0.5±0.02	0.02 ^{+0.001} 0.002
J	¢1.57±0.03	Ø0.062 ^{+0.001} 0002
К	φ2.2±0.1	\$\$\$ \$
L	¢1.57±0.03	Ø 0.062 ^{+0.001}

Caution Dimensions of mount pad for EV-9200 and that for target device (QFP) may be different in some parts. For the recommended mount pad dimensions for QFP, refer to "SEMICONDUCTOR DEVICE MOUNTING TECHNOLOGY MANUAL" (C10535E).

Caution Dimensions of mount pad for EV-9200 and that for target device (QFP) may be different in some parts. For the recommended mount pad dimensions for QFP, refer to "SEMICONDUCTOR DEVICE MOUNTING TECHNOLOGY MANUAL" (C10535E).

[MEMO]

APPENDIX C MASKED ROM ORDERING PROCEDURE

After program development is completed, the masked ROM is ordered by the following procedure:

<1> Advance notice of an order for masked ROM

Give advance notice of masked ROM ordering to a special agent or NEC's Sales Department, otherwise the ordered products may be delivered with delay.

<2> Preparation of media for ordering

Masked ROM orders can be placed on the following media types.

• UV-EPROMNote

*

- 3.5-inch IBM format floppy disk (outside Japan only)
- 5.25-inch IBM format floppy disk (outside Japan only)

Note When the UV-EPROM option is selected, prepare three UV-EPROMs each having the same contents. Record the mask option data on the mask option information sheet.

<3> Preparation of the required documents

Prepare the following documents when ordering a masked ROM:

- Masked ROM order sheet
- Masked ROM order check sheet
- Mask option information sheet

<4> Ordering

Send a set of the media created in <2> and the documents created in <3> to a special agent or NEC's Sales Department by the date indicated in the advance notice.

User's Manual U11330EJ2V1UM00

[MEMO]

APPENDIX D INSTRUCTION INDEX

D.1 INSTRUCTION INDEX (BY FUNCTION)

[Transfer instructions]

MOV	A,#n4 249, 268
MOV	reg1,#n4 249, 269
MOV	XA,#n8 249, 269
MOV	HL,#n8 249, 269
MOV	rp2,#n8 249, 269
MOV	A,@HL 249, 269
MOV	A,@HL+ 249, 269
MOV	A,@HL 249, 269
MOV	A,@rpa1 249, 269
MOV	XA,@HL 249, 270
MOV	@HL,A 249, 270
MOV	@HL,XA249, 270
MOV	A,mem 249, 270
MOV	XA,mem 249, 271
MOV	mem,A 249, 271
MOV	mem,XA 249, 271
MOV	A,reg 249, 271
MOV	XA,rp' 249, 271
MOV	reg1,A 249, 272
MOV	rp'1,XA 249, 272
ХСН	A,@HL 249, 272
ХСН	A,@HL+ 249, 272
ХСН	A,@HL 249, 272
ХСН	A,@rpa1 249, 272
ХСН	XA,@HL 249, 273
ХСН	A,mem 249, 273
ХСН	XA,mem 249, 273
ХСН	A,reg1 249, 273
ХСН	XA,rp'249, 273

[Table reference instructions]

MOVT XA,@PCDE ... 250, 274

MOVT	XA,@PCXA 250, 275
MOVT	XA,@BCDE 250, 276
MOVT	XA,@BCXA 250, 276

[Bit transfer instructions]

MOV1	CY,fmem.bit 250, 277
MOV1	CY,pmem.@L 250, 277
MOV1	CY,@H+mem.bit 250, 277
MOV1	fmem.bit,CY 250, 277
MOV1	pmem.@L,CY 250, 277
MOV1	@H+mem.bit,CY 250, 277

[Arithmetic/logical instructions]

ADDS	A,#n4 250, 277
ADDS	XA,#n8 250, 278
ADDS	A,@HL 250, 278
ADDS	XA,rp' 250, 278
ADDS	rp'1,XA 250, 278
ADDC	A,@HL 250, 278
ADDC	XA,rp' 250, 279
ADDC	rp'1,XA 250, 279
SUBS	A,@HL 250, 279
SUBS	XA,rp' 250, 279
SUBS	rp'1,XA 250, 280
SUBC	A,@HL 250, 280
SUBC	XA,rp' 250, 280
SUBC	rp'1,XA 250, 280
AND	A,#n4 251, 280
AND	A,@HL 251, 281
AND	XA,rp'251, 281
AND	rp'1,XA 251, 281
OR	A,#n4 251, 281

OR	A,@HL 251, 281
OR	XA,rp' 251, 281
OR	rp'1,XA 251, 282
XOR	A,#n4 251, 282
XOR	A,@HL 251, 282
XOR	XA,rp' 251, 282
XOR	rp'1,XA 251, 282

[Accumulator manipulation instructions]

RORC A ... 251, 283 NOT A ... 251, 283

[Increment/decrement instructions]

INCS	reg 251, 283
INCS	rp1 251, 283
INCS	@HL 251, 283
INCS	mem 251, 284
DECS	reg 251, 284
DECS	rp' 251, 284

[Compare instructions]

SKE	reg,#n4 251, 284
SKE	@HL,#n4 251, 284
SKE	A,@HL 251, 284
SKE	XA,@HL 251, 285
SKE	A,reg 251, 285
SKE	XA,rp' 251, 285

[Carry flag manipulation instructions]

SET1	CY 251, 285
CLR1	CY 251, 285
SKT	CY 251, 285
NOT1	CY 251, 286

[Memory bit manipulation instructions]

SET1	mem.bit 252, 286
SET1	fmem.bit 252, 286

SET1	pmem.@L 252, 286
SET1	@H+mem.bit 252, 286
CLR1	mem.bit 252, 286
CLR1	fmem.bit 252, 286
CLR1	pmem.@L 252, 286
CLR1	@H+mem.bit 252, 286
SKT	mem.bit 252, 287
SKT	fmem.bit 252, 287
SKT	pmem.@L 252, 287
SKT	@H+mem.bit 252, 287
SKF	mem.bit 252, 287
SKF	fmem.bit 252, 287
SKF	pmem.@L 252, 287
SKF	@H+mem.bit 252, 287
SKF SKTCLR	@H+mem.bit 252, 287 fmem.bit 252, 287
SKTCLR	fmem.bit 252, 287
SKTCLR SKTCLR	fmem.bit 252, 287 pmem.@L 252, 287
SKTCLR SKTCLR SKTCLR	fmem.bit 252, 287 pmem.@L 252, 287 @H+mem.bit 252, 287
SKTCLR SKTCLR SKTCLR AND1	fmem.bit 252, 287 pmem.@L 252, 287 @H+mem.bit 252, 287 CY,fmem.bit 252, 288
SKTCLR SKTCLR SKTCLR AND1 AND1	fmem.bit 252, 287 pmem.@L 252, 287 @H+mem.bit 252, 287 CY,fmem.bit 252, 288 CY,pmem.@L 252, 288
SKTCLR SKTCLR SKTCLR AND1 AND1 AND1	fmem.bit 252, 287 pmem.@L 252, 287 @H+mem.bit 252, 287 CY,fmem.bit 252, 288 CY,pmem.@L 252, 288 CY,@H+mem.bit 252, 288
SKTCLR SKTCLR SKTCLR AND1 AND1 AND1 OR1	fmem.bit 252, 287 pmem.@L 252, 287 @H+mem.bit 252, 287 CY,fmem.bit 252, 288 CY,pmem.@L 252, 288 CY,@H+mem.bit 252, 288 CY,fmem.bit 252, 288
SKTCLR SKTCLR AND1 AND1 AND1 OR1 OR1	fmem.bit 252, 287 pmem.@L 252, 287 @H+mem.bit 252, 287 CY,fmem.bit 252, 288 CY,pmem.@L 252, 288 CY,@H+mem.bit 252, 288 CY,fmem.bit 252, 288 CY,pmem.@L 252, 288
SKTCLR SKTCLR AND1 AND1 AND1 OR1 OR1 OR1	fmem.bit 252, 287 pmem.@L 252, 287 @H+mem.bit 252, 287 CY,fmem.bit 252, 288 CY,pmem.@L 252, 288 CY,@H+mem.bit 252, 288 CY,pmem.@L 252, 288 CY,@H+mem.bit 252, 288

[Branch instructions]

BR	addr 253, 288
BR	addr1 253, 289
BR	!addr 254, 289
BR	\$addr 254, 289
BR	\$addr1 254, 289
BR	PCDE 254, 291
BR	PCXA 254, 291
BR	BCDE 254, 292
BR	BCXA 255, 292

 BRA
 !addr1 ... 255, 289

 BRCB
 !caddr ... 255, 290

 TBR
 addr ... 260, 292

[Subroutine stack control instructions]

CALLA !addr1 ... 255, 293 CALL !addr ... 256, 293 CALLF !faddr ... 256, 294 TCALL !addr ... 260, 294 RET ... 257, 295 RETS ... 258, 295 RETI ... 258, 296 PUSH rp ... 259, 296 PUSH BS ... 259, 297 POP rp ... 259, 297 POP BS ... 259, 297

[Interrupt control instructions]

El ... 259, 297 El IExxx ... 259, 297 Dl ... 259, 297

DI IExxx ... 259, 298

[I/O instructions]

IN	A,PORTn 259, 298
IN	XA,PORTn 259, 298
OUT	PORTn,A 259, 298
OUT	PORTn,XA 259, 298

[CPU control instructions]

HALT ... 259, 299 STOP ... 259, 299 NOP ... 259, 299

[Special instructions]

SEL	RBn 260, 299
SEL	MBn 260, 299
GETI	taddr 260, 300

D.2 INSTRUCTION INDEX (ALPHABETICAL ORDER)

[A]		CLR1	mem.bit 252, 286
ADDC	A,@HL 250, 278	CLR1	pmem.@L 252, 286
ADDC	rp'1,XA 250, 279	CLR1	@H+mem.bit 252, 286
ADDC	XA,rp' 250, 279		C , , , , , ,
ADDS	A,#n4 250, 277	[D]	
ADDS	A,@HL 250, 278	DECS	reg 251, 284
ADDS	rp'1,XA 250, 278	DECS	rp' 251, 284
ADDS	XA,rp' 250, 278	DI 259	, 297
ADDS	XA,#n8 250, 278	DI	IExxx 259, 298
AND	A,#n4 251, 280		
AND	A,@HL 251, 281	[E]	
AND	rp'1,XA 251, 281	El 25	9, 297
AND	XA,rp' 251, 281	EI	IExxx 259, 297
AND1	CY,fmem.bit 252, 288		
AND1	CY,pmem.@L 252, 288	[G]	
AND1	CY,@H+mem.bit 252, 288	GETI	taddr 260, 300
[B]		[H]	
		HAI T	259 299
BR	addr 253, 288	HALT	259, 299
BR BR	addr1 253, 289		259, 299
BR BR BR	addr1 253, 289 BCDE 254, 292	HALT [1] IN	259, 299 A,PORTn 259, 298
BR BR BR BR	addr1 253, 289 BCDE 254, 292 BCXA 255, 292	[1]	
BR BR BR BR	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291	[1] IN	A,PORTn 259, 298
BR BR BR BR BR	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291	[1] IN IN	A,PORTn 259, 298 XA,PORTn 259, 298
BR BR BR BR BR BR	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289	[1] IN IN INCS	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284
BR BR BR BR BR BR BR	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr 254, 289	[I] IN IN INCS INCS	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283
BR BR BR BR BR BR BR BR	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr 254, 289 \$addr1 254, 289	[I] IN IN INCS INCS INCS	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283
BR BR BR BR BR BR BR BRA	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr1 254, 289 !addr1 255, 289	[I] IN IN INCS INCS INCS	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283
BR BR BR BR BR BR BR BR	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr 254, 289 \$addr1 254, 289	[1] IN INCS INCS INCS INCS	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283
BR BR BR BR BR BR BR BRA BRA BRCB	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr1 254, 289 !addr1 255, 289	[I] IN INCS INCS INCS INCS	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283 @HL 251, 283
BR BR BR BR BR BR BRA BRCB	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr 254, 289 \$addr1 254, 289 !addr1 255, 289 !caddr 255, 290	[1] IN INCS INCS INCS INCS [M] MOV	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283 @HL 251, 283 A,mem 249, 270
BR BR BR BR BR BR BR BRA BRCB	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr 254, 289 \$addr1 254, 289 !addr1 255, 289 !caddr 255, 290	[I] IN INCS INCS INCS INCS [M] MOV MOV	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283 @HL 251, 283 A,mem 249, 270 A,reg 249, 271
BR BR BR BR BR BR BRA BRA BRCB	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr1 254, 289 \$addr1 254, 289 !addr1 255, 289 !caddr 255, 290	[I] IN INCS INCS INCS INCS [M] MOV MOV	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283 @HL 251, 283 A,mem 249, 270 A,reg 249, 271 A,#n4 249, 268
BR BR BR BR BR BR BR BRA BRCB [C] CALL CALLA CALLF	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr 254, 289 \$addr1 254, 289 !addr1 255, 289 !caddr 255, 290 !addr 255, 293 !addr1 255, 293 !faddr 256, 294	[I] IN INCS INCS INCS INCS [M] MOV MOV MOV	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283 @HL 251, 283 A,mem 249, 270 A,reg 249, 271 A,#n4 249, 268 A,@HL 249, 269
BR BR BR BR BR BR BRA BRA BRCB	addr1 253, 289 BCDE 254, 292 BCXA 255, 292 PCDE 254, 291 PCXA 254, 291 !addr 254, 289 \$addr 254, 289 \$addr1 254, 289 !addr1 255, 289 !caddr 255, 290	[1] IN INCS INCS INCS INCS [M] MOV MOV MOV MOV	A,PORTn 259, 298 XA,PORTn 259, 298 mem 251, 284 reg 251, 283 rp1 251, 283 @HL 251, 283 A,mem 249, 270 A,reg 249, 271 A,#n4 249, 268 A,@HL 249, 269 A,@HL+ 249, 269

MOV	A,@rpa1 249, 269
MOV	HL,#n8 249, 269
MOV	mem,A 249, 271
MOV	mem,XA 249, 271
MOV	reg1,A 249, 272
MOV	reg1,#n4 249, 269
MOV	rp'1,XA 249, 272
MOV	rp2,#n8 249, 269
MOV	XA,mem 249, 271
MOV	XA,rp' 249, 271
MOV	XA,#n8 249, 269
MOV	XA,@HL 249, 270
MOV	@HL,A 249, 270
MOV	@HL,XA 249, 270
MOVT	XA,@BCDE 250, 276
MOVT	XA,@BCXA 250, 276
MOVT	XA,@PCDE 250, 274
MOVT	XA,@PCXA 250, 275
MOV1	CY,fmem.bit 250, 277
MOV1	CY,pmem.@L 250, 277
MOV1	CY,@H+mem.bit 250, 277
MOV1	fmem.bit,CY 250, 277
MOV1	pmem.@L,CY 250, 277
MOV1	@H+mem.bit,CY 250, 277

[N]

NOP 259, 299		
NOT	A 251, 283	
NOT1	CY 251, 286	

[0]

OR	A,#n4 251, 281
OR	A,@HL 251, 281
OR	rp'1,XA 251, 282
OR	XA,rp' 251, 281
OR1	CY,fmem.bit 252, 288
OR1	CY,pmem.@L 252, 288

 OR1
 CY,@H+mem.bit ... 252, 288

 OUT
 PORTn,A ... 259, 298

 OUT
 PORTn,XA ... 259, 298

[P]

POP	BS 259, 297
POP	rp 259, 297
PUSH	BS 259, 297
PUSH	rp 259, 296

[R]

RET 257	, 295
RETI 258	8, 296
RETS 25	8, 295
RORC	A 251, 283

[S]

r	
SEL	MBn 260, 299
SEL	RBn 260, 299
SET1	CY 251, 285
SET1	fmem.bit 252, 286
SET1	mem.bit 252, 286
SET1	pmem.@L 252, 286
SET1	@H+mem.bit 252, 286
SKE	A,reg 251, 285
SKE	A,@HL 251, 284
SKE	reg,#n4 251, 284
SKE	XA,rp' 251, 285
SKE	XA,@HL 251, 285
SKE	@HL,#n4 251, 284
SKF	fmem.bit 252, 287
SKF	mem.bit 252, 287
SKF	pmem.@L 252, 287
SKF	@H+mem.bit 252, 287
SKT	CY 251, 285
SKT	fmem.bit 252, 287
SKT	mem.bit 252, 287
U.C.	

SKT	pmem.@L 252, 287
••••	pe
SKT	@H+mem.bit 252, 287
SKTCLR	fmem.bit 252, 287
SKTCLR	pmem.@L 252, 287
SKTCLR	@H+mem.bit 252, 287
STOP 25	9, 299
SUBC	A,@HL 250, 280
SUBC	rp'1,XA 250, 280
SUBC	XA,rp' 250, 280

- SUBS
 A,@HL ... 250, 279

 SUBS
 rp'1,XA ... 250, 280
- SUBS XA,rp' ... 250, 279

[T]

TBR	addr 260, 292
TCALL	!addr 260, 294

[X]

XCH	A,mem 249, 273
ХСН	A,reg1 249, 273
ХСН	A,@HL 249, 272
ХСН	A,@HL+ 249, 272
ХСН	A,@HL 249, 272
ХСН	A,@rpa1 249, 272
ХСН	XA,mem 249, 273
ХСН	XA,rp' 249, 273
ХСН	XA,@HL 249, 273
XOR	A,#n4 251, 282
XOR	A,@HL 251, 282
XOR	rp'1,XA 251, 282
XOR	XA,rp' 251, 282
XOR1	CY,fmem.bit 252, 288
XOR1	CY,pmem,@L 252, 288
XOR1	CY,@H+mem.bit 252, 288

APPENDIX E HARDWARE INDEX

E.1 HARDWARE INDEX (ALPHABETICAL ORDER WITH RESPECT TO THE HARDWARE NAME)

[A]

Acknowledge detection flag (ACKD) ... 135 Acknowledge enable bit (ACKE) ... 135 Acknowledge trigger bit (ACKT) ... 135

[B]

Bank select register (BS) ... 67 Basic interval timer (BT) ... 103 Basic interval timer mode register (BTM) ... 103 Bit sequential buffer (BSB0-BSB3) ... 184 BT interrupt enable flag (IEBT) ... 191 BT interrupt request flag (IRQBT) ... 191 Bus release detection flag (RELD) ... 136 Bus release trigger bit (RELT) ... 136 Busy enable bit (BSYE) ... 135

[C]

Carry flag (CY) ... 64 Clock mode register (WM) ... 109 Clock output mode register (CLOM) ... 101 Command detection flag (CMDD) ... 135 Command trigger bit (CMDT) ... 136

[I]

Interrupt enable flag for clock timer (IEW) ... 214 Interrupt master enable flag (IME) ... 193 Interrupt priority specification register (IPS) ... 192 Interrupt request flag for clock timer (IRQW) ... 214 Interrupt status flag (IST0, IST1) ... 65, 198 INT0 edge detection mode register (IM0) ... 197 INT0 interrupt enable flag (IE0) ... 191 INT0 interrupt request flag (IRQ0) ... 191 INT1 edge detection mode register (IM1) ... 197 INT1 interrupt enable flag (IE1) ... 191 INT1 interrupt request flag (IRQ1) ... 191 INT2 edge detection mode register (IM2) ... 217 INT2 interrupt enable flag (IE2) ... 214 INT2 interrupt request flag (IRQ2) ... 214 INT4 interrupt enable flag (IE4) ... 191 INT4 interrupt request flag (IRQ4) ... 191

[K]

Key interrupt input (KR0-KR7) ... 215

[M]

Memory bank enable flag (MBE) ... 23, 66 Memory bank select register (MBS) ... 23, 67

[P]

Port 0 to port 8 (PORT0-PORT8) ... 70
Port mode register group A (PMGA) ... 77
Port mode register group B (PMGB) ... 77
Port mode register group C (PMGC) ... 77
Processor clock control register (PCC) ... 88
Program counter (PC) ... 49
Program status word (PSW) ... 64
Pull-up resistor specification register group A (POGA) ... 84
Pull-up resistor specification register group B (POGB) ... 84

[R]

Register bank enable flag (RBE) ... 36, 66 Register bank select register (RBS) ... 36, 67

[S]

Serial bus interface control register (SBIC) ... 134 Serial interface interrupt enable flag (IECSI) ... 191 Serial interface interrupt request flag (IRQCSI) ... 191 Serial interface operation enable/disable specification bit (CSIE) ... 131 Serial operation mode register (CSIM) ... 130 Shift register (SIO) ... 137 Signal from address comparator (COI) ... 131 Skip flag (SK0-SK2) ... 65 Slave address register (SVA) ... 137 Stack bank select register (SBS) ... 48, 60 Stack pointer (SP) ... 60 Sub-oscillator control register (SOS) ... 97 System clock control register (SCC) ... 90

[T]

Timer counter 1 interrupt enable flag (IET1) ... 191 Timer counter 1 interrupt request flag (IRQT1) ... 191 Timer counter 1 count register (T1) ... 113 Timer/event counter 1 mode register (TM1) ... 114 Timer counter 1 modulo register (TMOD1) ... 113 Timer/event counter 1 output enable flag (TOE1) ... 117 Timer/event counter 0 count register (T0) ... 112 Timer/event counter 0 interrupt enable flag (IET0) ... 191 Timer/event counter 0 interrupt request

flag (IRQT0) ... 191

Timer/event counter 0 mode register (TM0) ... 114 Timer/event counter 0 modulo register (TMOD0) ... 112 Timer/event counter 0 output enable flag (TOE0) ... 117

[W]

Wake-up function specification bit (WUP) ... 131 Watchdog timer enable flag (WDTM) ... 105

E.2 HARDWARE INDEX (ALPHABETICAL ORDER WITH RESPECT TO THE HARDWARE SYMBOL)

[A]	IRQ0 191	
ACKD 135	IRQ1 191	
ACKE 135	IRQ2 214	
ACKT 135	IRQ4 191	
	IRQBT 191	
[B]	IRQCSI 191	
BS 67	IRQT0 191	
BSB0-BSB3 184	IRQT1 191	
BSYE 135	IRQW 214	
BT 103	IST0 65, 198	
BTM 103	IST1 65, 198	
[C]	[K]	
CLOM 101	KR0-KR7 215	
CMDD 135		
CMDT 136	[M]	
COI 131	MBE 23, 66	
CSIE 131	MBS 23, 67	
CSIM 130		
CY 64	[P]	
	PC 49	
[1]	PCC 88	
IE0 191	PMGA 77	
IE1 191	PMGB 77	
IE2 214	PMGC 77	
IE4 191	POGA 84	
IEBT 191	POGB 84	
IECSI 191	PORT0-PORT8 70	
IET0 191	PSW 64	
IET1 191		
IEW 214	[R]	
IM0, IM1 197	RBE 36, 66	
IM2 217	RBS 36, 67	
IME 193	RELD 136	
IPS 192	RELT 136	

[S]

SBIC ... 134 SBS ... 48, 60 SCC ... 90 SIO ... 137 SK0, SK1, SK2 ... 65 SOS ... 97 SP ... 60 SVA ... 137

[T]

T0 ... 112 T1 ... 113 TOE0 ... 117 TOE1 ... 117 TM0 ... 114 TM1 ... 114 TMOD0 ... 112 TMOD1 ... 113

[W]

WDTM ... 105 WM ... 109 WUP ... 131

APPENDIX F REVISION HISTORY

The revision history is shown below. The chapters described in the revised-chapter column indicate those for the corresponding edition.

Edition	Major changes	Revised chapter
Second	The $\mu PD750104,\mu PD750106,\mu PD750108,and\mu PD75P0116$ have already been developed.	Throughout
	The data bus pins (D0-D7) have been added.	
	"CONNECTION OF UNUSED PINS" has been changed.	Chapter 2
	"WRITING TO THE PROGRAM MEMORY" has been changed.	Chapter 9
	"READING THE PROGRAM MEMORY" has been changed.	
	Modification of the instruction list	Chapter 11
	The target to be compared has been changed from the $\mu PD75008$ to $\mu PD750008.$	Appendix A

*

[MEMO]



Facsimile Message

From:		
Name		
Company		
Tel.	FAX	

Address

Although NEC has taken all possible steps to ensure that the documentation supplied to our customers is complete, bug free and up-to-date, we readily accept that errors may occur. Despite all the care and precautions we've taken, you may encounter problems in the documentation. Please complete this form whenever you'd like to report errors or suggest improvements to us.

Thank you for your kind support.

North America Hong Kong, Philippines, Oceania **Asian Nations except Philippines NEC Electronics Inc.** NEC Electronics Hong Kong Ltd. NEC Electronics Singapore Pte. Ltd. Corporate Communications Dept. Fax: +852-2886-9022/9044 Fax: +65-250-3583 Fax: 1-800-729-9288 1-408-588-6130 Korea Japan Europe NEC Electronics Hong Kong Ltd. **NEC Semiconductor Technical Hotline** NEC Electronics (Europe) GmbH Seoul Branch Fax: 044-548-7900 Technical Documentation Dept. Fax: 02-528-4411 Fax: +49-211-6503-274 South America Taiwan NEC do Brasil S.A. NEC Electronics Taiwan Ltd. Fax: +55-11-6465-6829 Fax: 02-2719-5951

I would like to report the following error/make the following suggestion:

Document title:	
Document number:	Page number:

If possible, please fax the referenced page or drawing.

Document Rating	Excellent	Good	Acceptable	Poor
Clarity				
Technical Accuracy				
Organization				