# SMT365E

# **User Manual**



# **Revision History**

Date	Comments	Engineer	Version
18/07/02	First rev, based on 361	GP	1.0.0
06/01/03	User manual updated, 2 SHBs	YC	1.0.1
16/01/03	Changed flash to 4Mbyte	GP	1.0.2
20/01/03	Added FPGA pin-out	GP	1.0.3
31/01/03	Changed CPLD hdr pin-out.	GP	1.0.4
	Set DSP clk=600, emif clk=100		
24/02/03	No more SDBs clock selection	JPA	1.0.5
17/03/03	Added location of SDBs on the board.	JPA	1.0.6
	Updated FPGA memory mapping.		
24/04/03	Updated Data Sheets (Hyperlinks) section	JPA	1.0.7
19/09/03	Updated Data Sheets (Hyperlinks) section	JPA	1.0.8
	Updated Reprogramming chapter		
09/08/05	Update: the user manual supports the new firmware implementation V3.0 (XC2V6000) and the firmware V1.0 (XC2V8000)	SM	2.0
25/01/06	Errata: Flash ROM access	SM	2.1
16/02/06	Update: the user manual supports the new firmware implementation for 2xSDBs, 32bits V3.12 (XC2V6000)	AL	2.2

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# **Contacting Sundance**

You can contact Sundance for additional information by login onto the <u>Sundance support forum</u>.

#### **Notational Conventions**

#### **DSP**

The terms DSP, C64xx and TMS320C64xx will be used interchangeably throughout this document.

#### SDB

The term SDB will be used throughout this document to refer to the Sundance Digital Bus interface.

#### **SHB**

The term SHB will be used throughout this document to refer to the Sundance Highspeed Bus interface.

#### Register Descriptions

The format of registers is described using diagrams of the following form:

31–24		23–16	15–8	7–0
		OFLAGLEVEL		
R,00000	000	RW,10000000	R,00000000	R,10000000

The digits at the top of the diagram indicate bit positions within the register and the central section names bits or bit fields. The bottom row describes what may be done to the field and its value after reset. Shaded fields are reserved and should only ever be written with zeroes.

R Readable by the CPU
W Writeable by the CPU

RW Readable and writeable by the CPU

Binary digits indicate the value of the field after reset

#### **Outline Description**

The SMT365 is a DSP module, size 2 TIM offering the following features:

- □ TMS320C6416 processor running at 600MHz
- Six comports
- □ 256MB of SDRAM (100MHz)
- □ 4MB of Flash ROM
- Global Bus connector
- 6 SHB connectors for high-speed data transfer

#### **Intended Audience**

There are two existing versions of the firmware for the SMT365e.

For each of the versions of the different firmware is loaded in the FPGA:

- Firmware version 1.1 or
- Firmware version 1.2

This user manual covers the version 1.2 of the firmware for the SMT365e implemented with the model described in the <u>SMT6500 help file</u>.

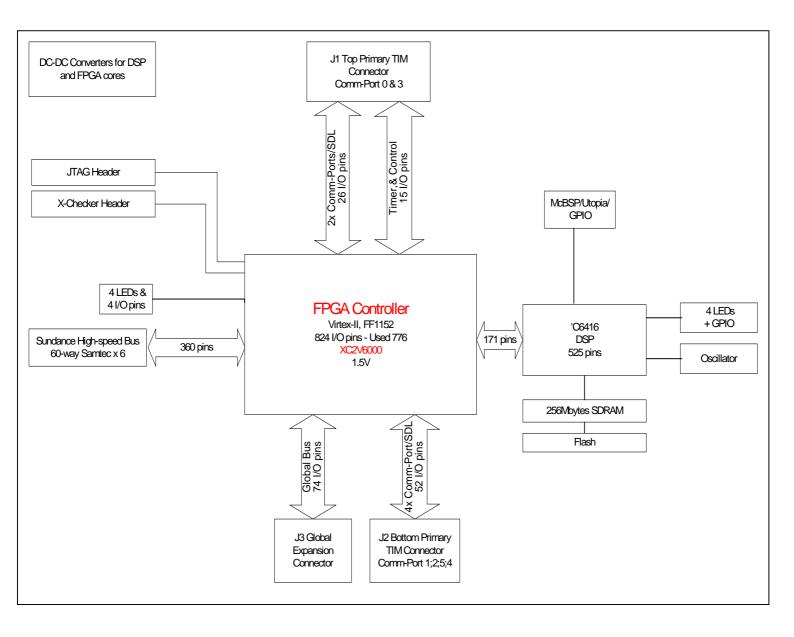
Refer to section Firmware versions.

## **Block Diagram**

The following drawing shows the block diagram of the SMT365e module.

The main components of the SMT365e are:

- A Texas Instruments DSP
- One Xilinx FPGA Virtex-II device
- 256MB of SDRAM



#### **Architecture Description**

#### **DSP**

The Texas Instruments DSP can run at up to 600MHz. The DSP is doted of 256MB of Synchronous DRAM (SDRAM).

The DSP is a TMS320C6416 type.

This is a fixed-point digital signal processor provided by Texas Instruments. The processor will run with zero wait states from internal SRAM. The internal memory is 1MB in size and can be partitioned between normal SRAM and L2 cache.

An on-board crystal oscillator provides the clock used for the DSP which them multiplies this by twelve internally.

#### **Boot Mode**

The DSP is connected to the on-board flash ROM that contains the Sundance bootloader and the FPGA bitstream.

Following reset, the DSP will automatically load the data from the flash ROM into its internal program memory at address 0 and then start executing from there. All this code is the Sundance *bootloader*, and it is made up of two parts: FPGA configuration and processor configuration. FPGA configuration uses data in the ROM to configure the FPGA. A processor configuration sets the processor into a standard state by writing into the DSP internal registers of the EMIF. Then it configures the FPGA from the data held in the flash ROM.

The bootloader is executed. It will continually check the six comports until data appears on one of them. This will next load a program in boot format from this comport. Note that the bootloader will not read data arriving on other comports. Finally the control is passed to the loaded DSP application.

The DSP will take approximately about 46s to configure the FPGA following reset, assuming a 600MHz clock. The external devices implemented in the FPGA (such as comports) must not be used during this configuration.

It is safest to wait for the configuration to complete. Note that comports will appear to be "not ready" until the FPGA has been configured.

The FPGA programming algorithm is not described here. It can be found in the boot code.

#### **EMIF Control Registers**

The DSP has two external memory interfaces (EMIF) which are 64 bits wide and 16 bits wide.

The DSP contains several registers that control the external memory interface (EMIF). A full description of these registers can be found in the <u>DSP C6000</u> Peripherals Reference Guide.

The standard bootstrap will initialise these registers to use the following resources:

Memory space	Resource	Address range		
(EMIFA)				
	Internal program memory (1MB)	0x00000000 - 0x000FFFFF		
CE0	SDRAM	0x80000000 - 0x8FFFFFF		
CE1	Virtex	0x90000000 - 0x9FFFFFF		

Memory space	Resource	Address range		
(EMIFB)				
CE0	Flash paging control	0x60000000 - 0x60000200		
CE1	4MB Flash (1 <sup>st</sup> half)	0x64000000 - 0x640FFFFF		
CE2	4MB Flash (2 <sup>nd</sup> half)	0x68000000 - 0x680FFFFF		
CE3	FPGA Configuration control	0x6C000000 - 0x6C000002		

#### **SDRAM**

Memory space CE0 is used to access 256MB of SDRAM over EMIFA.

The speed of the SDRAM is dependent on the processor variant. Using the C6416, the SDRAM will operate at 133MHz maximum. It operates at one sixth of the core clock speed.

The EMIFA CE0 memory space control register should be programmed with the value 0x000000D0 (64 bits SDRAM).

#### **FLASH**

A 4MB of Flash ROM is connected to the DSP in the EMIFB CE1 & CE2 memory spaces. The ROM holds boot code for the DSP, configuration data for the FPGA, and optional user-defined code.

The EMIFB CE1 and CE2 space control registers should be programmed with the values 0x00000030 and 0xFFFFFE23 respectively.

As the DSP only provides 20 address lines on its EMIFB, both CE1 & CE2 are used to access this device. This in itself allows the direct access to 2MB. A paging mechanism is used to select which half of the 4MB device is visible in this 2MB window.

As the EMIFB CE1 & CE2 memory spaces alias throughout the available range, the **flash device can be accessed** using the address **range 0x67E00000-0x681FFFFF**. This gives a 2MB continuous memory space.

Selecting the visible flash memory page (2 pages of 2MB) involves writing to the following addresses as shown (the data written is irrelevant):

Address	Flash page selected
0x60000000	Page 0
0x60000100	Page 1

The EMIFB CE0 memory space control register should be programmed with the value 0xFFF0C003.

#### **Virtex FPGA**

The FPGA (Field Programmable Gate Array) is a Xilinx Virtex-II device XC2V6000.

It implements the following communication resources:

- Six Comport interfaces
- Four 16-bit Sundance Digital Bus interfaces
- One Global Bus interface

#### Version control

Revision numbers for both the boot code and FPGA firmware are stored in the Flash ROM during programming as zero-terminated ASCII strings.

The <u>SMT6001 utility</u> can be used to display the version numbers of the bootloader and the FPGA data.

#### Firmware versions

The SMT6001 utility includes the latest version of the bootloader and the latest version of the FPGA data that implements the FPGA architecture described in the SMT6500 help file.

Customers who wish to use the old firmware can obtain it from our support web forum.

#### Reprogramming the firmware and boot code

The contents of the flash ROM are managed using the <u>SMT6001 utility</u>. This includes the latest firmware and bootloader along with complete documentation on how to reprogram the ROM. The utility assumes that you have Code Composer Studio installed and that it has been configured correctly for the installed TIMs. The Sundance Wizard can help you with this.

To confirm that the ROM has been programmed correctly, you should run the confidence test in the BoardInfo utility (SMT6300).

#### **Comports**

The DSP has six comports, numbered 0 to 5.

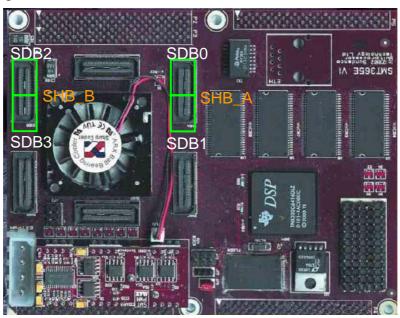
The addresses of the Comport registers are described in the **SMT6400** help file.

#### **SHB**

The SMT365e has six SHB connectors, all of which are connected to the DSP to give 16-bit/32-bit SDB interfaces on two SHB connectors. These interfaces operate with a fixed clock rate of 100MHz.

Note that the four other SHB connectors are not used.

The following figure shows their localisation on the board:



#### Global bus

The SMT365e provides a single global bus interface. This is only accessible from the DSP. The addresses of the global bus registers are shown in the <u>Virtex Memory Map</u>, and are described in the <u>SMT6400 help file</u>.

#### **LED Setting**

The SMT365e has 13 LEDs. One shows the FPGA configuration status and the other 4 are under DSP control.

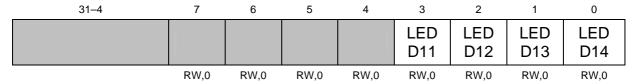
LED D6 always displays the state of the FPGA DONE pin. This LED is off when the FPGA is configured (DONE=1) and on when it is not configured (DONE=0).

This LED should go on when the board is first powered up and go off when the FPGA has been successfully programmed (this is the standard operation of the boot code resident in the flash memory device). If the LED does not light at power-on, check that you have the mounting pillars and screws fitted properly. If it stays on, the DSP is not booting correctly, or is set to boot in a non-standard way.

Four of the remaining LEDs can be controlled with the LED register (D11, D12, D13, D14). Writing 1 will illuminate the LED; writing 0 will turn it off.

Note that the LEDs D7-D10 are not used.

# LED Register (0x900D0000)



The four remaining LEDs (D2-5) are connected to the C60's GPIO pins 12-15.

#### **CONFIG & NMI**

The TIM specification describes the operation of an open-collector type signal CONFIG that is driven low after reset.

This signal, on a standard C4x based TIM, is connected to the processor's IIOF3 pin. On the SMT365, the CONFIG signal is asserted after power on, and can be released by writing the value (1<<6) to the config register. Conversely, CONFIG may be reasserted by writing 0 to this bit. It is not possible for software to read the state of the CONFIG signal.

The NMI signal from the TIM connector can be routed to the DSP NMI pin.

WARNING: Several software components include code sequences that assume setting GIE=0 in the DSP CSR will inhibit all interrupts; NMI violates that assumption. If an NMI occurs during such code sequences it may not be safe to return from the interrupt. This may be particularly significant if you are using the compiler's software pipelining facility.

#### **Config Register**

31–8	7	6	5–0
	NMI	CONFIG	

Field	Des	Description					
CONFIG	0	drive CONFIG low					
CONTIO	1	tri-state CONFIG					
NMI	0	Disconnect NMI from the DSP					
INIVII	1	Connect NMI from TIM to the DSP.					

Config and NMI DSP lines are described in the <u>SMT6400 help file</u>.

#### **Timer**

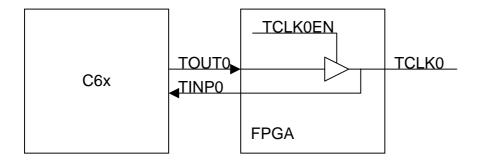
The TIM TCLK0 and TCLK1 signals can be routed to the DSP's TOUT/TINP pins. The signal direction must be specified, together with the routing information in the timer control register.

#### **Timer Control Register**

31–6	5	4	3–0
Reserved	TCLK1	TCLK0	Reserved

Field	Description					
TCLK0	0	TIM TCLK0 is an input				
TOLKU	1	Enable TIM TCLK0 as an output				
TCLK1	0	TIM TCLK1 is an input				
IOLIVI	1	Enable TIM TCLK1 as an output				

If the TIM TCLKx pin is selected as an output, the DSP TOUTx signal will be used to drive it. The TIM TCLKx pin will always drive the DSP TINPx input.



The Timer control register is described in the **SMT6400** help file.

## **IIOF** interrupt

The firmware can generate pulses on the external interrupt lines of the TIM.

Only the interrupt line IIOF1 and IIOF2 are connected from/to the DSP and the HOST.

- IIOF1 is connected from the DSP side to the HOST side: so, the DSP interrupts the HOST
- IIOF2 is connected from the HOST side to the DSP side: so, the HOST interrupts the DSP

The IIOF interrupt lines are described in the **SMT6400** help file.

#### **Code Composer**

This module is fully compatible with the Code Composer Studio debug and development environment. This extends to both the software and JTAG debugging hardware. The driver to use is the *tixds64xx\_11.dvr*. CCS version 3.0 or later is required as the reprogramming utility (SMT6001) requires it.

#### Troubleshooting

Our <u>Knowledge data base</u> and <u>FAQ</u> sections may help you to resolve some known issues.

#### **Application Development**

Depending on the complexity of your application, you can develop code for SMT365 modules in several ways.

#### SMT6400

For simple applications, the Sundance <u>SMT6400 software support package</u> (project examples) and its associated header files (SmtTim.h and ModSup.h) can suffice.

The SMT6400 product is installed by the Sundance Wizard and it is free of charge.

#### 3L Diamond

This module is fully supported by 3L Diamond, which Sundance recommends for all but the simplest of applications. A SMT365e has to be declared as appropriate in configuration files as one processor of type:

#### SMT365E

#### SMT6500

This is the <u>support package for the FPGA</u>. It may be used to develop your application in the FPGA of the module.

#### **Operating Conditions**

#### Safety

The module presents no hazard to the user.

#### **EMC**

The module is designed to operate within an enclosed host system that provides adequate EMC shielding. Operation within the EU EMC guidelines is only guaranteed when the module is installed within an appropriate host system.

The module is protected from damage by fast voltage transients introduced along output cables from outside the host system.

Short-circuiting any output to ground does not cause the host PC system to lock up or reboot.

#### General Requirements

The module must be fixed to a TIM40-compliant carrier board.

The SMT365e TIM is in a range of modules that must be supplied with a 3.3V power source. In addition to the 5V supply specified in the TIM specification, these new generation modules require an additional 3.3V supply to be presented on the two diagonally-opposite TIM mounting holes. The lack of this 3.3V power supply should not damage the module, although it will obviously be inoperable; prolonged operation under these circumstances is not recommended.

The SMT365e is compatible with all Sundance TIM carrier boards. It is a 5V tolerant module, and as such, it may be used in mixed systems with older TIM modules, carrier boards and I/O modules.

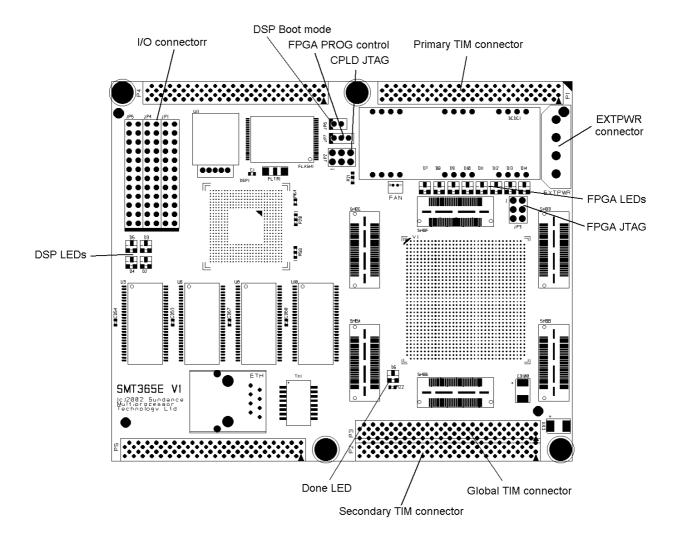
Use of the TIM on SMT327 (cPCI) motherboards may require a firmware upgrade. If LED D6 on the SMT365e remains illuminated once the TIM is plugged in and powered up, the SMT327 needs the upgrade. The latest firmware is supplied with all new boards shipped. Please contact Sundance directly if you have an older board and need the upgrade.

The external ambient temperature must remain between 0°C and 40°C, and the relative humidity must not exceed 95% (non-condensing).

#### **Power Consumption**

The power consumption of this TIM is dependent on the operating conditions in terms of core activity and I/O activity. The maximum power consumption is 10W.

#### **Connector Positions**



#### Serial Ports & Other C60 I/O

The C60 contains various I/O ports. These signals are connected to a 0.1" pitch DIL pin header. The pin-out of this connector is shown here:

Р	DR0	FSR0	DX0	FSX0	CLKR0	CLKX0	CLKS0	CLKS1	CLKX1	CLKR1	URA1	URA0
0								URA3	URA4	URA2		
L	DR2	FSR2	DX2	FSX2	CLKR2	CLKX2	CLKS2	DX1	FSX1	FSR1	DR1	UXA0
Α							GPIO8	UXA4	UXA3	UXA2	UXA1	
R	URD0	URD1	URD2	URD3	URD4	URD5	URD6	URD7	URCLK	URENB	URCLAV	URSOC
I												
S	UXD0	UXD1	UXD2	UXD3	UXD4	UXD5	UXD6	UXD7	UXCLK	UXENB	UXCLAV	UXSOC
Α												
Т	NC	GPIO9	GPIO10	GPIO11	GPIO12	GPIO13	GPIO14	GPIO15	V33	V33	TTL2	TTL3
1												
0	GPIO0	GPIO1	GPIO2	GPIO3	GPIO4	GPIO5	GPIO6	GPIO7	GND	GND	TTL0	TTL1
N												

#### **FPGA and CPLD JTAG**

The following shows the pin-outs for JP2 (CPLD) and JP3 (FPGA) JTAG connectors:

Signal	Pin	Pin	Signal
V33	1	4	TMS
TCK	2	5	TDO
GND	3	6	TDI

# **Virtex Memory Map**

#define	SMT365eCP0	(volatile	unsigned	int	*)0x9000000
#define	SMT365eCP1	(volatile	unsigned	int	*)0x90008000
#define	SMT365eCP2	(volatile	unsigned	int	*)0x90010000
#define	SMT365eCP3	(volatile	unsigned	int	*)0x90018000
#define	SMT365eCP4	(volatile	unsigned	int	*)0x90020000
#define	SMT365eCP5	(volatile	unsigned	int	*)0x90028000
#define	SMT365eCP0_STAT	(volatile	unsigned	int	*)0x90004000
#define	SMT365eCP1_STAT	(volatile	unsigned	int	*)0x9000C000
#define	SMT365eCP2_STAT	(volatile	unsigned	int	*)0x90014000
#define	SMT365eCP3_STAT	(volatile	unsigned	int	*)0x9001C000
#define	SMT365eCP4_STAT	(volatile	unsigned	int	*)0x90024000
#define	SMT365eCP5_STAT	(volatile	unsigned	int	*)0x9002C000
#define	SMT365eGB_STAT	(volatile	unsigned	int	*)0x90034000
#define	SMT365eSDB_STAT	(volatile	unsigned	int	*)0x90038000
#define	SMT365eSTAT	(volatile	unsigned	int	*)0x9003C000
#define	SMT365eSDBA	(volatile	unsigned	int	*)0x90040000
#define	SMT365eSDBB	(volatile	unsigned	int	*)0x90050000
#define	SMT365eSDBC	(volatile	unsigned	int	*)0x90060000
#define	SMT365eSDBD	(volatile	unsigned	int	*)0x90070000
#define	SMT365eSDBA_STAT	(volatile	unsigned	int	*)0x90048000
#define	SMT365eSDBB_STAT	(volatile	unsigned	int	*)0x90058000
#define	SMT365eSDBC_STAT	(volatile	unsigned	int	*)0x90068000
#define	SMT365eSDBD_STAT	(volatile	unsigned	int	*)0x90078000
#define	SMT365eSDBA_INPUTFLAG	(volatile	unsigned	int	*)0x90044000
#define	SMT365eSDBB_INPUTFLAG	(volatile	unsigned	int	*)0x90054000
#define	SMT365eSDBC_INPUTFLAG	(volatile	unsigned	int	*)0x90064000
#define	SMT365eSDBD_INPUTFLAG	(volatile	unsigned	int	*)0x90074000
#define	SMT365eSDBA_OUTPUTFLAG	(volatile	unsigned	int	*)0x9004C000
#define	SMT365eSDBB_OUTPUTFLAG	(volatile	unsigned	int	*)0x9005C000
#define	SMT365eSDBC_OUTPUTFLAG	(volatile	unsigned	int	*)0x9006C000
#define	SMT365eSDBD_OUTPUTFLAG	(volatile	unsigned	int	*)0x9007C000
#define	GLOBAL_BUS	(volatile	unsigned	int	*)0x900A0000
#define	GLOBAL_BUS_CTRL	(volatile	unsigned	int	*)0x90080000
#define	GLOBAL_BUS_START	(volatile	unsigned	int	*)0x90088000
#define	GLOBAL_BUS_LENGTH	(volatile	unsigned	int	*)0x90090000

#define SMT365eTCLK	<pre>(volatile unsigned int *)0x900C0000</pre>
#define SMT365eTIMCONFIG	<pre>(volatile unsigned int *)0x900C8000</pre>
#define SMT365eLED	<pre>(volatile unsigned int *)0x900D0000</pre>
#define SMT365eINTCTRL4	<pre>(volatile unsigned int *)0x900E0000</pre>
#define SMT365eINTCTRL4_EXT	<pre>(volatile unsigned int *)0x900E4000</pre>
#define SMT365eINTCTRL5	<pre>(volatile unsigned int *)0x900E8000</pre>
#define SMT365eINTCTRL5_EXT	<pre>(volatile unsigned int *)0x900EC000</pre>
#define SMT365eINTCTRL6	<pre>(volatile unsigned int *)0x900F0000</pre>
#define SMT365eINTCTRL6_EXT	(volatile unsigned int *)0x900F4000
#define SMT365eINTCTRL7	<pre>(volatile unsigned int *)0x900F8000</pre>
#define SMT365eINTCTRL7_EXT	(volatile unsigned int *)0x900FC000

#### SHB pin-out

#### SHB generic pin-out

	Hw	QSH Pin number	QSH Pin number		Hw
	CLK	1	2		D0
	D1	3	4		D2
	D3	5	6		D4
	D5	7	8	Hw0	D6
	D7	9	10		D8
Hw0	D9	11	12		D10
Í	D11	13	14		D12
	D13	15	16		D14
	D15	17	18		USERDEF0
	USERDEF1	19	20		USERDEF2
	USERDEF3	21	22		WEN
	REQ	23	24		ACK
		25	26		
		27	28		
		29	30		
		31	32		
		33	34		
		35	36		
	CLK	37	38		D0
	D1	39	40		D2
	D3	41	42		D4
	D5	43	44		D6
	D7	45	46		D8
T <sub>W</sub>	D9	47	48	7	D10
Í	D11	49	50	Hw1	D12
	D13	51	52		D14
	D15	53	54		USERDEF0
	USERDEF1	55	56		USERDEF2
	USERDEF3	57	58		WEN
	REQ	59	60		ACK

Note: Hw is a short for Half-word (i.e. 16-bit Word)

This standard is implemented using **SAMTEC QSTRIP** 0.50mm Hi-speed connectors.

# FPGA PROG Pin Control (JP7 connector)

Jumper Position			
1-2	2-3	Out	
PROG asserted continuously	PROG asserted for the duration of RESET.	PROG under control of DSP	
	Can also be controlled by the DSP.		

# DSP Boot Mode Control (JP6 connector)

In	DSP will boot from flash
Out	DSP will be set to boot from HPI

#### **Bibliography**

- 1. Sundance Help file
- 2. SMT6400 help file (DSP support package) and SMT6500 help file (FPGA support package)
- TMS320C6000 Peripherals Reference Guide (literature number SPRU190)
   It describes common peripherals available on the TMS320C6000 digital signal processors. This book includes information on the internal data and program memories, the external memory interface (EMIF), the host port, multichannel-buffered serial ports, direct memory access (DMA), clocking and phase-locked loop (PLL), and the power-down modes.
- 4. <u>TIM-40 MODULE SPECIFICATION</u> Including TMS320C44 Addendum
- 5. SDB Technical Specification
- 6. SHB Technical Specification
- 7. TMS320C4x User's Guide (literature number SPRU063)

  It describes the C4x 32-bit fixed-point processor, developed for digital signal processing as well as parallel processing applications. Covered are its architecture, internal register structure, instruction set, pipeline, specifications, and operation of its six DMA channels and six communication ports. Software and hardware applications are included.
- 8. Xilinx Virtex-II datasheet
- 9. TMSC6416 datasheet

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