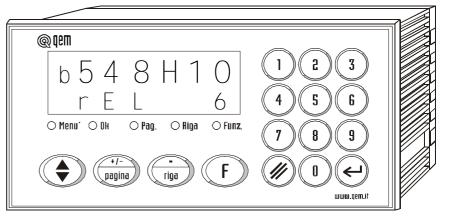
# HB 548.10

User's manual





BI-DIRECTIONAL ON/OFF POSITIONER WITH CLEARANCE RECOVERY AND EXECUTION OF LINES FROM KEYBOARD





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### CHAPTER 1 INTRODUCTION

### 1-1 SUPPLEMENTARY NATURE OF MANUAL

This manual is to be considered as a supplement to the "Installation, maintenance and servicing manual", which contains information on wiring, checking and eliminating faults, start-up and maintenance procedures. This manual gives instructions on the use and correct programming of the instrument.

You are urged, therefore, to read the manual carefully and, if you have any queries, to contact QEM for further explanations by sending the assistance fax contained in the manual.

### 1-2 REFERENCES

The documentation on the instruments designed and sold by QEM has been divided into different booklets for effective and speedy consultation, based on the specific type of information required.

User manual

#### Hardware structure

Explanation of software.

This is this manual, giving all the necessary information for the understanding and use of the instrument described. The manual deals with the instrument software, with information on the understanding, programming, calibration and use of the instrument described.

After installing the instrument, following the instructions in the installation, maintenance and servicing manual, this user manual gives all the necessary instructions on the correct use and programming of the instrument. Basic information on the standard hardware in the series plus customisation possibilities.

This booklet is appended to the user manual and describes the standard hardware configuration for the series of instruments described.

It also gives the standard electrical, technical and mechanical specifications of the series, together with the hardware customisation possibilities in relation to the different software versions.

## Installation, maintenance and servicing manual

All the necessary information for installation, maintenance and servicing.

All the essential details on the correct maintenance and installation.

The aim is to provide you with valid and accurate information for the manufacture of products of recognised quality and reliability. It also gives valid supporting information for servicing applications with QEM instruments installed.



### **1-3 RESPONSIBILITY AND VALIDITY**

### RESPONSIBILITY

QEM declines all responsibility for any injury to persons or damage to objects resulting from the failure to observe the instructions and rules in this manual and the "Installation, maintenance and servicing manual". It is furthermore specified that the customer/purchaser is bound to use the instrument according to the instructions provided by QEM and, if any doubts arise, to send a written query to QEM. Any authorisation for exceptions or substitutions in use, if contested, will be deemed valid by QEM only if in writing.

The reproduction or handing over of all or part of this manual to third parties without the written authorisation of QEM is forbidden. Any transgression will result in a claim for compensation for the damages sustained. All rights deriving from patents or designs are reserved.

QEM reserves the right to make partial or complete modifications to the characteristics of the instruments described or corresponding documentation.

### Objective

The objective of this manual is to give the general rules for the use of the instrument described.

### Conservation of parameters

Write down all the instrument setting and programming parameters and keep them in a safe place, to facilitate any future replacement or servicing operations.

### VALIDITY

This manual is applicable to all instrumentation designed, manufactured and tested by QEM with the same order code. This document is valid in its entirety, barring errors or omissions.

Instrument release	Manual Release	Modifications to manual	Date of modifications
6	0	New Manual	10 / 06 / 04



### **1-4 DESCRIPTION OF OPERATION**

The instrument HB 548.10 is a single-axis ON/OFF bi-directional positioner. The instrument is provided with 99 lines containing the positioning quotas which can be divided into a number of pages at pleasure. It is provided with a series of manual functions (introduction of a value on the count, manual movements, etc...) to facilitate the calibration phases and to allow the operator to intervene on the positioning system. It is allowed the programs execution and work cycles, with or without count by of working executed. There is the possibility to increase the piece counter with an input outward applied an expansion card to the base version. The instrument automatically recalculates the inertia giving very precise positioning even when there are variations in the load, wear, speed, inertia .... It is also provided with a function that allows movements with a delta quota ( $\Delta$ ), useful, for example, when managing a saw, in the movement of the mobile jig during the cut.



### CHAPTER 2 OPERATOR/MACHINE INTERFACE

### 2-1 KEYBOARD DESCRIPTION

Key		Function		
0 ÷ 9	Normal operation: Data input:	pressed after the " <b>F</b> " key, they select the functions available. allows entry of data.		
	Normal operation:	selects the display of the cycle. Impulse pressure selects the successive display. Continuous pressure selects the previous display.		
	Data input:	display. scrolling of the various parameters. Impulse pressure selects the successive parameter. Continuous pressure selects the previous parameter.		
+/- pagina	Normal operation: Data input:	chooses the page to be executed. Inserts or removes the +/- sign. Inserts or removes programme end.		
riga	Normal operation: Data input:	chooses the line to be executed within the selected page. Inserts the decimal point.		
F	Normal operation: Data input:	enables the selection of the functions. During the immediate quota introduction aborted the posizioned.		
	Normal operation: Data input:	in page selection selects the next line without commanding positioning. Reset the piece count (if enabled) deletes the input value and reverts to the old value.		
<b>(</b> -)	Normal operation: Data input:	when enabled, executes the selected line or page. stores the datum entered.		
⊖ Menu'	Lights up when pages are introduced of program.			
⊖ Ok	Lights up if axis is in tolerance.			
⊖ Pag.	Lights up when a page is selected.			
🔿 Aiga	Lights up when a line is selected.			
⊖ Funz.	Lights up when a function is	selected.		



Key	Function
<b>F</b> + <b>0</b>	Access to password-protected functions.
<b>F</b> + <b>1</b>	Introduction of the programme.
<b>F</b> + <b>2</b>	Introduction of a value on the count.
<b>F</b> + <b>3</b>	Display of the last inertia calculated.
<b>F</b> + <b>4</b>	Introduction of blade thickness.
<b>F</b> + <b>S</b>	Manual axis movement.
<b>F</b> + <b>6</b>	Input and output diagnostics.
<b>F</b> + <b>7</b>	Search for preset quota.
<b>F</b> + <b>8</b>	Introduction of minimum quota.
<b>F</b> + <b>9</b>	Introduction of offset on the count.



### 2-2 DESCRIPTION OF INPUTS

### Characteristics of inputs

Refer to the chapter entitled "Electrical characteristics" in the "Hardware structure" booklet appended to this manual.

Terminal bloach	Name	Logical status of activation	Min. time of activation (ms)	Polarization terminal	Description
17	11	ON	50	16	<b>Increase line.</b> Increases at any time the line of the page in progress (change work quota).
18	12	ON	50	16	<b>Start.</b> If input I4 = ON (positioning enabled), commands axis movement energising movement outputs (forward /reverse) in function of the positioning quota and remains the piece count. By selecting the line from the keyboard with the keys line or page, the start can also be activated by confirming with the key ENTER (when enabled in set-up).
19	ß	ON	50	16	<b>Cycle (impulse mode).</b> Restores the execution of the first line of the work programme in use. Acquired on the ascent side. <b>Cycle (continuous mode).</b> When beginning operations, if the input is activated and remains active for the whole duration of operations, the work programme will automatically restart from the first line when the work cycle ends.
20	14	ON	50	16	<b>Enable positioning.</b> Its activation enables the energising of the movement outputs; with input I4=OFF positionings are aborted. It can also be used as an emergency input.
21	15	ON	50	16	<b>Zero impulse enablement.</b> Its specific function depends on the type of preset search programmed in set-up; upon its activation is increased the reading of the zero impulse by the encoder for the loading of the preset quota.
22	16	ON	50	16	<b>Return to zero.</b> When activated, it commands the axis movement to machine zero or to the D quota. If the set-up parameter "F6" is on "0", the activation of this input commands positioning at zero quota. If the set-up parameter "F6" is on "1", positioning is commanded at the selected quota plus the value of "F6". With a successive activation of input I2 (start), the axis returns to the selected quota. With positioning on the selected quota+D, clearance recovery and the inertia band are not enabled. The positionings are in any event enabled/disabled in function of the status of input I4 (positioning enabled).

### Characteristics of expansion of inputs (option E)

Please refer to the chapter "Electric Characteristics" of the leaflet "Hardware Structure" enclosed to this manual.

Terminal bloach	Name	Logical status of activation	aouranon	Polarization terminal	Description
32	17	ON	50	31	Pace Increment. Upon its activation the piece count is increased.



Name	Terminal bloach	Description
1	Vac	Instrument power supply voltage. Alternating voltage as per code in your order. 10% 50 / 60 Hz.
2	Vac	Instrument power supply voltage. Alternating voltage as per code in your order. 10% 50 / 60 Hz.
3	GND	<b>Ground connection.</b> A conductor of $\emptyset$ 4 mm is recommended.
4	+	<b>Transducers positive power supply. P</b> ositive voltage supplied by instrument for instrument and transducers inputs power (12 Vdc - 150 mA, expert different indication).
5	-	Transducers negative power supply. Negative voltage supplied by instrument for instrument and transducers inputs power.

### **COUNT INPUTS**

Terminal bloach	Name	Logical status of activation	Polarization terminal	Description		
13	PHA	N/P	12	Input "phase A" incremental transducer.		
14	PHB	N/P	12	Input "phase B" incremental transducer.		
15	Z	N/P	12	Input "zero impulse" incremental transducer.		
	For details of the count inputs, refer to the chapter entitled "Electrical characteristics" in the "Hardware structure" booklet appended to this manual.					

**Legend** N = Transducer with NPN logic. P = Transducer with PNP logic.



### 2-3 DESCRIPTION OF OUTPUTS

### Characteristics of outputs

Refer to the chapter entitled "Electrical characteristics" in the "Hardware structure" booklet appended to this manual.

Terminal bloach	Name	Logical status of activation	Min. time of activation (ms)	Polarization terminal	Description
7	U1	ON	С	6	<b>Forward.</b> When this output is energised, it commands the forward axis movement (the instrument displays the increasing count).
8	U2	ON	С	6	<b>Reverse.</b> When this output is energised, it commands the reverse axis movement (the instrument displays the decreasing count).
9	U3	ON	С	6	<b>Slow-down.</b> This output reduces the axis speed in proximity of the positioning point, and commands the passage to slow axis speed.
10	U4	ON	С	6	<b>Page end.</b> This is activated when the positioning of the last line of the page in use is concluded (only if I3=off) and is deactivated at restart. If input I3 = on (cycle) it is activated for 300 ms when the positioning of the last page line is concluded.
11	U5	ON	С	6	<b>Jolly</b> . If configurated in set-up as tolerance $(U = 0)$ , it is activated when the axis enters the tolerance range for the quota in use. If configurated as brake enabling $(U = 1)$ , it is activated when the count reaches the inertia range and is disabled by a new positioning 150 ms. before activation of the movement outputs $(U1 - U2)$ . If configurated as brake release $(U = 2)$ , it is deactivated when it reaches the inertia range and is activated by a new positioning 150 ms. before activation of the movement outputs $(U1 - U2)$ .

## CHAPTER 3 SETTING UP FOR OPERATION

### 3-1 SET-UP

As these parameters set the operating mode of the instrument, access is restricted to the installer only. A password must be entered to access the programming, with the following procedure:

Description	Keyboard	Display
Access the set-up programming.	<b>F</b> + <b>0</b>	PASS
Introduce the access code "548" and confirm with <b>ENTER</b> .	5 4 8 ←	$\bigcirc$ Funz. = ON
Exit is possible at any time after introducing the password by pressing the F key.	F	

pressing the F key.

FUNCTION	DISPLAY	DESCRIPTION
Enable input expansion	A E O	<ul> <li>0 = Expansion not enabled.</li> <li>1 = Expansion is enabled and can be used the piece count.</li> </ul>
Display mode	H d O	<ul> <li>0 = Normal display.</li> <li>1 = HDR1 (high definition reading) display</li> <li>2 = HDR2 (high definition reading) display</li> <li>N.B. Refer to the "Installation, maintenance and servicing manual".</li> </ul>
Enable the forcing of count visualization	FC 0	<ul> <li>0 = the visualization force is disabled</li> <li>1 = the count visualization is forced, to the value of the current quota, even if at the end positioning the count is exceded for a bit the value of the position quota.</li> <li>2 = the count visualization is forced to the quota in use when the count of the axis is in the tolerance range</li> </ul>
Decimal figures	FP 0	Select the number of figures after the decimal point (max 3) for the X axis count display (axis position). <b>N.B.</b> Entering the number of decimal figures will affect the DISPLAY of the count; the precision of the positionings depends on the number of impulses supplied by the transducer.
Encoder resolution	FE 400000	This parameter sets what the encoder revolution impulses must be multiplied by to have the length display in the desired unit of quota. Values from 0.00200 to 4.00000 can be entered, bearing in mind that the frequency of the PH phases must not exceed the instrument's maximum count frequency. <b>N.B.</b> Refer to the "Installation, maintenance and servicing manual".
Deceleration Max. 9999	(r L 1234)	This is the distance of the arrival quota at which the axis deceleration output is activated. See relative paragraph. <b>N.B.</b> Refer to the "Installation, maintenance and servicing manual"



FUNCTION	DISPLAY	DESCRIPTION
Negative tolerance Max. 999.9	t n 1234	Axis positioning negative tolerance limit. The tolerance range is set by this parameter and the "Positive tolerance" parameter. This parameter always has one decimal place more than the number of places programmed in the "FP" parameter, to allow for the QPS (QEM POSITIONING SYSTEM) function. <b>N.B.</b> Refer to the "Installation, maintenance and servicing manual"
Positive tolerance Max. 999.9	t P 1234	Axis positioning positive tolerance limit. The tolerance range is set by this parameter and the "Negative tolerance" parameter. This parameter always has one decimal place more than the number of places programmed in the "FP" parameter, to allow for the QPS (QEM POSITIONING SYSTEM) function. <b>N.B.</b> Refer to the "Installation, maintenance and servicing manual".
Deceleration time Max. 9.99	(t L)	Delay time (in seconds) for the activation of the motor forward or reverse output when positioning enters the deceleration range. During this time the axis, because of inertia, must not enter the tolerance range.
Maximum quota Max. 99999	S 12345	This is the maximum quota that the axis can reach; the set value should also be considered as the maximum limit for the introduction of working quotas. If clearance recovery is set on "2", this limit is overcome in the measure set as (quota+overquota).
Enable minimum quota	A N O	<b>0</b> = The value of the minimum quota minima can be introduced in set-up. <b>1</b> = The introduction of the minimum quota is enabled by function keys "F + 8". In this case, the minimum quota in set-up is used by the instrument only to calculate the inertia recalculation ranges (see paragraph "Automatic inertia recalculation").
Minimum quota Min99999	r 12345	This is the minimum quota that the axis can reach; the set value should also be considered as the minimum limit for the introduction of working quotas. If clearance recovery is set on "1", this limit will be exceeded by the measure set as (quota-overquota).
Clearance recovery selection	r A O	<ul> <li>0 = Positioning without clearance recovery.</li> <li>1 = Positioning with forward clearance recovery.</li> <li>2 = Positioning with reverse clearance recovery.</li> <li>N.B.Refer to the "Installation, maintenance and servicing manual".</li> </ul>
D minimum positioning overquota for clearance recovery Min. 1 Max. 9999	0 A 1234	During forward clearance recovery the axis is positioned on: (set quota - over-quota - inertia) and, after the reverse time, on the set quota position. During reverse clearance recovery the axis is first positioned on: (set quota - over-quota - inertia) and, after the reverse time, on the set quota position. If there is no clearance recovery or the position does not require clearance recovery, and the space is less than the over-quota, the instrument will carry out positioning with clearance recovery. <b>N.B.</b> The real clearance recovery quota is calculated by adding the over-quota "OA" to the inertia. If value 0 is introduced, by default the instrument will insert the value 1.



FUNCTION	DISPLAY	DESCRIPTION
Choice of jolly output	J O	<ul> <li>0 = Output U5 behaves as tolerance, being energised if the axis concludes positioning within the tolerance range.</li> <li>1 = Output U5 enables the brake, and is energised when the axis is stopped.</li> <li>2 = Output U5 acts as brake release, and is de-energised when the axis is stopped.</li> </ul>
Enable blade thickness	(AL O)	When wishing to compensate the thickness of material removed during the cut, the introduction of the blade thickness must be enabled. In this case, to set the blade thickness during the instrument's normal functions, press keys "F + 4". <b>0</b> = Blade thickness not enabled. <b>1</b> = Blade thickness enabled.
Load preset	bP O	The preset search procedure is carried out: 0 = Loading the count with the preset quota at input I5 deactivation. 1 = Loading the count with the preset quota at input Z activation, after the axis has reversed direction and input I5 has been deactivated (sensitive to the down front). 2 = Loading the count with the preset quota at input Z activation, after input I5 = ON (impulse). N.B. Refer to the "Installation, maintenance and servicing manual".
Preset quota	P 123480	For the preset search procedure, it is the quota that is loaded on the transducer zero impulse count (according to the method defined by the type of preset search). A preset quota between the maximum and minimum quotas can be introduced. <b>N.B.</b> Refer to the "Installation, maintenance and servicing manual".
Zero impulse logic status		If the encoder generates zero impulse when activating input Z (PNP), set to 0, otherwise if it generates zero impulse when disactivating input Z (NPN) set to 1. If this parameter is programmed correctly, the letter "C" will appear on input diagnostics when there is no zero impulse.
Enable menu programming	n E o	<ul> <li>0 = Access to work quota programming is immediate.</li> <li>1 = Access to work quota programming is conditioned by a password.</li> </ul>
Function key <b>ENTER</b>	E O	<ul> <li>0 = During the choice of the page to be executed, the ENTER key confirms the line chosen without executing it. When introducing the immediate quota, it confirms the value introduced without commanding axis movement.</li> <li>1 = During the choice of the page to be executed, the ENTER key confirms the chosen line and executes it. When introducig the immediate quota, it confirms the value introduced and commands axis movement. In both cases input I4 (enable positioning) must be active.</li> <li>2 =During the choice of the page to be executed, the enter key confirms the line chosen (between the arrow key is possible choices another line) without executing it. Another line between the arrow key can be choice. For to be executed it again, the enter kex must be to press. When immediate quota is executed, it confirms the value introduced and ordered the axis movement. In both cases I4 Input (positioning enable) must be active</li> </ul>



FUNCTION	DISPLAY	DESCRIPTION
Check time input I2 and ENTER key Max. 9.99	(t S 999)	This is the time, expressed in seconds, for activating the start (I2) or the ENTER key, when enabled, to execute the selected line.
Memory configuration Max. 99	cn O	Determines the number of steps composing a programme. A total of 99 steps are available; dividing therefore the number of available steps by the value introduced (number of steps per programme), youo obtain the number of programmes that can be utilised. <b>Example:</b> <b>Cn</b> = 10 <b>N di programmi</b> = 99/10 =9 The steps remaining after the division are added to the last programme which in this case will have a dimension of 19 steps. <b>N.B.</b> Every time the "memory configuration" is modified, the introduced data must be rewritten. With "Cn" $\geq$ 50 "Page" key is not enable.
Enable offset count		<ul> <li>0 = Not enabled.</li> <li>1 = Using keys "F + 9" it is possible to introduce an offset count value; the value introduced will automatically be added to (or subtracted from) all the set work quotas.</li> </ul>
F6 quota (+ / -)	F 6	If "F6" is zero, by activating input I6, the axis moves to zero quota; if "F6" is other than zero, by activating input I6, the axis positions on the selected quota + F6 without utilising clearance recovery.
Reverse time Max. 9,99	t i	In order to avoid possible mechanical stress, caused by excessively rapid axis movement reversal, a reverse delay time, expressed in seconds, can be introduced. This parameter only affects operation in the event of positioning with clearance recovery.
Waith time 1	(t A 1 999)	This is the wait positioning time after I6 input activation. If during the wait time execution, input I6 turns OFF, the procedure is aborted.
Waith time 2	(t A 2 999	This is the wait positioning time on the zero quota or on the delta quota before to return on the program quota. If the time introduced has 9,99 value the return on program quota is not delayed by the tA2 time byt controlled bye the I6 input de-activation. With the time Ta2 sets to 0 the return by the delta quota is not enabled bye the I6 input, but only I2 input or by enter key (if enabled). With tA2 sets to 9,99 or with tA2 sets to 0 the edventually count piece display is enabled during delta quota shifting.
Enable arrow key	A F O	<ul><li>0 = the arrow key is not increases the line executed.</li><li>1 = the arrow key increases the line executed.</li></ul>
Delay time for axis leaving Max. 9.99	(tr 999)	It is the delay time for axis leaving that it is activated to the start. When the time is left the jolly output is deactivated like tolerance.
Enable I1 Input		<ul> <li>0 = the I1 input is always enabled to the reading.</li> <li>1 = the I1 input is not enabled to the reading when it is selected the first program lin and it is not activated the start yet.</li> <li>After the start, I1 input is rehabilitated to the reading.</li> </ul>



FUNCTION	DISPLAY	DESCRIPTION
Choice of memory	sn o	<ul> <li>0= When the instrument is turned off, the automatic working in the process is memorized and proposed again when the instrument is started.</li> <li>1= When the instrument is turned off, the automatic or manual working in the process is memorized and proposed again when the instrument is started.</li> </ul>
When programming of the last function is terminated, the display in use before entering set-up will reappear.		

### 3-2 CALIBRATION

### INTRODUCTION OF A SINGLE FIXED INERTIA VALUE FOR ALL POSITIONINGS.

A) Select manual operation mode. Deactivate input of stop (I4 = OFF). B) Introduce the access code "123" Λ Type in the sequence From the keyboard, introduce the code 123 and confirm with PASS The instrument will display: the enter key 4 E) After confirmation of the code 123, the instrument will display: From the keyboard, introduce the value "0" (exclusion of the eight ranges) and confirm By inserting "0" the axis will be considered 8 F A S C E as a single range; by inserting "1", the axis with the enter key InEr  $\left( \right)$ will be divided into eight equal ranges. F) After confirmation of the value "0", the instrument will display: Introdurre con la tastiera il valore "0" (esclusione del ricalcolo) confermandolo con il By inserting "0" the re-calculation is disabled; CAL by inserting "1", the re-calculation is tasto InEr O enabled, only if the positioning is ended off out of tolerance; by inserting "2" the re-calculation is enabled Press the key even when the positioning is ended off in tolerance. G) After confirmation of the value "0", the instrument will display: 23456 Axis count 123456 Range in use (1) Count relative to the center of the range in At this point the operator can introduce the use inertia value using the numerical keys, and confirming with the enter key H) The instrument will display: 234 Inertia value in use n 1234 Range in use (1) Inertia value introduction Set the tolerance activation delay time. To return to the normal display confirm with the enter key N) After confirmation of the value introduced, the instrument will display: 123 This display relates to the "tolerance activation delay time" setting. 000 tΑ



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AUTOMATIC RE-CALCULATION OF A SINGLE FIXED INERTIA VALUE FOR ALL POSITIONINGS.

- First set the "TA" parameter (tolerance activation delay time).
- To obtain the "TA" display follow the points listed below (A÷G).
- A) Put the instrument in manual mode. Deactivate input (I4 = OFF continuous). B) Introduce the access code "123" Type in the sequence From the keyboard, introduce the code 123 and confirm with Р ASS The instrument will display:  $\bigcirc$ the enter key ASCE 8 C) The instrument will display: Introduce the value "0" and confirm with the enter key nEr ←  $\left( \right)$ А D) The instrument will display: Introduce the value "0" and confirm with the enter key F n  $\cap$ r 3456 2 E) The instrument will display: Press the key 23456 1234 n F) The instrument will display: Introduce the value "0" and confirm with the enter key ( 4 1234 23 Set the tolerance activation delay time. To return to the G) The instrument will display: normal display confirm with the enter key † A 000

- Once the "TA" parameter has been set, the automatic inertia calculation can be performed.

H) Return to the automatic inertia calculation by re-introducing the access code 123.

I) After confirmation of the code 123, the instrument will display:

L) After confirmation of the value "0", the instrument will display:



ICALC

InEr

By inserting "0" the axis will be considered as a single range; by inserting "1", the axis will be divided into eight equal ranges.

By inserting "0" the re-calculation is disabled;

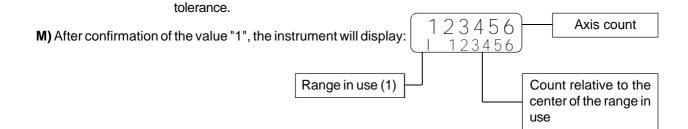
by inserting "1", the re-calculation is enabled;

by inserting "2" the re-calculation is enabled even when the positioning is ended off in From the keyboard, introduce the value "1" (re-calculation enabled) and confirm

From the keyboard, introduce the value "0" (exclusion of the eight ranges) and confirm

with the enter key

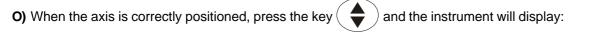
with the enter key

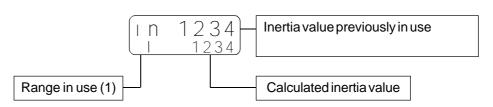






N) Deactivate the stop input (I4 = OFF) and press the "ENTER" key. The axis will move to the central point of the stroke. When positioning has terminated, after the time "TA", the instrument will calculate the inertia value that effects axis movement. Press "ENTER" again; the axis will re-attempt positioning at the central point of the stroke, adopting the inertia calculated at the previous positioning. The axis should terminate positioning inside the tolerance range inserted in set-up. If, after several attempts, the axis fails to position correctly the deceleration, tolerance, tolerance activation delay time values will require modification.





P) After the inertia value is confirmed with "ENTER", the instrument will display the tolerance activation delay time (the installer will choose whether to confirm or modify this value). After the "TA" parameter is confirmed with "ENTER", the instrument will automatically exit from the inertia calculation function.

## ENABLING AUTOMATIC RE-CALCULATION OF EIGHT DIFFERENT INERTIA VALUES RELATIVE TO EIGHT AXIS RANGES.

### To calibrate the axis using the eight range re-calculation, proceed as follows.

First set the "TA" parameter (tolerance activation delay time).

To obtain the "TA" display follow the points listed on the following page ( $A \div H$ ).

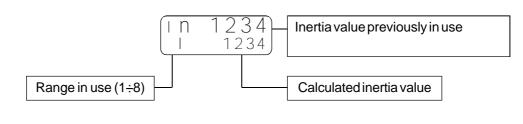
<b>&gt;</b>	Deactivate input ( $I4 = OFF$ continuous).
►	Type in the sequence $F + 0$
►	From the keyboard, introduce the code 123 and confirm with
	the enter key
, ➡	Introduce the value "0" and confirm with the enter key $\overleftarrow{\leftarrow}$
	·
➡	Introduce the value "0" and confirm with the enter key
➡	Press the key
➡	Introduce the value "0" and confirm with the enter key
	t t t t t t t



- H) The instrument will display:
- 123 000
  → Set the tole To return to

←

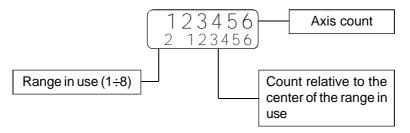
- Set the tolerance activation delay time. To return to the normal display confirm with the enter key
- I) Return to the automatic inertia calculation by re-introducing the access code 123.
- L) After confirmation of the code 123, the instrument will display: From the keyboard, introduce the value "1" (enabling the eight ranges) and confirm By inserting "0" the axis will be considered 8 F A S C E as a single range; by inserting "1", the axis with the enter key InEr 1 will be divided into eight equal ranges. M) After confirmation of the value "0", the instrument will display: From the keyboard, introduce the value "1" (re-calculation enabled) and confirm with By inserting "0" the re-calculation is disabled; ricaic by inserting "1", the re-calculation is enabled; the enter key InEr by inserting "2" the re-calculation is enabled even when the positioning is ended off in tolerance. Axis count 23456 N) After confirmation of the value "1", the instrument will display: 123456 Range in use (1+8) Count relative to the center of the range in use
- O) Deactivate the stop input (I4 = OFF) and press the "ENTER" key. The axis will move to the central point of the first range. When positioning has terminated, after the time "TA", the instrument will calculate the inertia value that effects axis movement within the first range. Press "ENTER" again; the axis will re-attempt positioning at the center of the first range, adopting the inertia calculated at the previous positioning. The axis should terminate positioning inside the tolerance range inserted in set-up. If, after several attempts, the axis fails to position correctly the deceleration, tolerance, tolerance activation delay time values will require modification.
- P) When the axis is correctly positioned, press the key ( -) and the instrument will display:



The installer may modify this value (if considered necessary) or confirm with the  $(\leftarrow)$  key.



**Q)** After the inertia value relative to the first range is confirmed with "ENTER", the instrument will display:



- **R)** After the "**ENTER**" key has been pressed, the instrument positions the axis for the inertia calculation realative to the second range. This is carried out by repeating points M, N, O. Proceed with inertia calculation for all eight ranges.
- S) When the inertia value relative to the eighth range has been confirmed with "ENTER", the instrument will display the tolerance activation delay time. The "TA" may be different from the value set before calibration was started, if the instrument decided that the value required modification in order to provide a more precise inertia calculation. After the "TA" parameter is confirmed with "ENTER", the instrument will automatically exit from the inertia calculation function.



## CHAPTER 4

### 4-1 WORK PROGRAMMES AND AUXILIARY FUNCTIONS

### INTRODUCING THE PAGES

The work programme is composed of a certain number of pages, defined with the set-up parameter "Memory configuration".

For each page it is possible to set a positioning line (preselection) and the number of operations to be made once the set quota has been reached (totaliser).

Description	Keyboard	Display
If programming is protected by a password (see set-up), type in the value "456" and confirm with <b>ENTER</b> . If programming is not protected by a password, no code needs to be introduced.	<b>F</b> + 1	ProGr PAS456 O Menu'= ON
The operator can introduce the page to be programmed and confirm it using the <b>ENTER</b> key.	() ÷ ()	ProGr PAG10
On confirming the page, the upper display will indicate the number of the page. The bottom left display will indicate the number of the line being programmed while the bottom right display will show the quota; the opoerator can introduce the required quota and confirm with the <b>ENTER</b> key.	0 ÷ 9 ←	PAG 10 1 123456
Proposes introduction of page end. If wishing to introduce page end press the " <b>PAGE</b> " key. If wishing to continue programming, confirm with <b>ENTER</b> .	pagina (	- PAG 10 1 123456
Proposes the second line of the selected page; the operator can introduce the quota and confirm with <b>ENTER</b> . Introduction of page end is proposed; programming can continue until completing the steps available.	Û÷ 9	PAG 10 2 1234
By pressing the arrow key, the various lines of the page can be scrolled from the first to the last, or up to the line in which page end has been inserted.		
It is possible to exit page introduction by pressing key "F"; only values confirmed with ENTER will be memorised.	F	⊖ Menu <sup>·</sup> = OFF



### VALUE INTRODUCTION ON THE COUNT

The instrument offers functions for axis manual management and as an aid during calibration phases. The value of the count shown on the instrument (axis position) can be modified by introducing the desired value. This function is particularly useful during installation and calibration procedures.

Description	Keyboard	Display
Access the value introduction on a count function.	<b>F</b> + <b>3</b>	<pre>I nCount 123456</pre> ○ Funz.= ON
The operator may introduce the required count value and confirm with <b>ENTER</b> . The instrument will show the value introduced.	() ÷ ()	
To exit the function press key "F".	F	○ Funz.= OFF

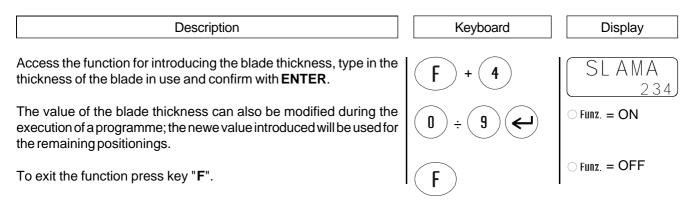
### **RECALCULATED INERTIA DISPLAY**

This way, the last inertia value calculated is displayed (with the last positioning).

Description	Keyboard	Display
Access the display function for the last inertia calculated.	<b>F</b> + <b>3</b>	(In Er 1234)
If not set, the automatic recalculation is displayed.		○ Funz.= ON
To exit the function, press key " <b>F</b> ".	F	○ Funz.= OFF

### INTRODUCING THE BLADE THICKNESS

The quantity of material removed during the cut can be compensated by inserting the thickness of the blade in use. The value introduced will be added to all the positioning quotas so that they are increased by the thickness of the blade.





### MANUAL MOVEMENT OF THE AXIS

The instrument offers functions for the manual management of the axis. The axis can be moved by the keyboard in both directions and at two different speeds. When the manual axis movement function is selected, key 7 allows the axis to be moved "back" (count decreases), while with key 9 it is possible to move the axis "forward" (count increases). Key 8 allows the selection of manual movement speed (slow or fast).

Description	Keyboard	Display
Access the function relative to axis movement.	<b>F</b> + <b>S</b>	$\begin{array}{c} nAn\\ F & 123456 \end{array}$ $\odot$ Funz.= ON
In manual mode, keys 7,8, and 9 are enabled. The bottom left display shows the speed selected with key 8 (L = slow, F = fast). By pressing key 7 the axis moves back and movement stops when the key is released. By pressing key 9 the axis moves foreward and movement stops when the key is released. The bottom right displays show the count (axis position). During manual movements, the set minimum and maximum limits are enabled (set-up).	789	
To exit the function, press key " <b>F</b> ".	F	○ Funz.= OFF

### PRESET QUOTA SEARCH

The instrument offers functions for axis manual management. Preset quota search can also be controlled from the keyboard (for preset quota search see the relative section).

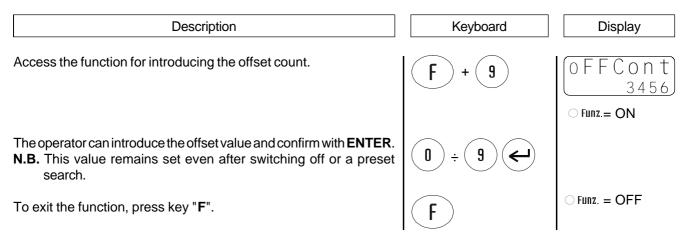
Description	Keyboard	Display
Access the function for the preset quota search. The lower displays will show the count value.	<b>F</b> + <b>7</b>	r Pr ESE t 170
		⊂ Funz. = ON
At start or on pressing the <b>ENTER</b> key (if enabled in set-up) the axis moves in search of the command for loading the preset quota (set- up function) and when activated, the preset quota is loaded. <b>N.B.</b> After carrying out a preset search, this cannot be repeated unless after restarting the instrument.	<b>~</b>	
To exit the function and to abort the procedure if this has not been terminated, press key " $\mathbf{F}$ ".	F	○ Funz. = OFF



### INTRODUCING THE MINIMUM QUOTA

Description	Keyboard	Display
Access the function for the introduction of the minimum quota (if its introduction has been enabled in set-up).	<b>F</b> + <b>B</b>	QnininA 123456
		$\bigcirc$ Funz. = ON
<ul> <li>The operator can introduce the minimum quota value and confirm with ENTER.</li> <li>N.B. The quota introduced must be greater than the minimum quota set in set-up.</li> </ul>	0 ÷ 9 ←	
To exit minimum quota insertion, press key " <b>F</b> ".	F	○ Funz.= OFF

### INTRODUCING OFFSET ON THE COUNT



### POSITIONING AT AN IMMEDIATE QUOTA

The instrument offers functions for manual axis management. The axis can be automatically positioned at a quota other than the work quotas that can be selected from the existing programmes. This function speeds up considerably all those positioning operations differing from normal operations.

Description	Keyboard	Display
Using one of the numerical keys, select the display relative to the introduction of an immediate quota. The upper displays show the count (axis position), while the lower displays show the immediate positioning quota introduced.	0	234567 \$ 123
The operator can introduce the required immediate quota. On confirming the introduced value with <b>ENTER</b> (if in set-up the parameter "E" is on 1), the instrument positions the axis at the quota introduced. If in set-up parameter "E" =0, the axis start will be commanded by the start input.	0 ÷ 9 ←	
To exit without executing the immediate quota, press the <b>"CLEAR"</b> key or the "F" key.	<b>F</b>	



### CHOICE OF THE PAGE TO BE EXECUTED

Using the set-up parameter "Memory configuration" a certain number of work pages have been defined, each containing a series of lines consisting of positioning quotas. To choose the page to be executed, proceed as follows:

Description	Keyboard	Display
Access the function allowing page choice.	+/- pagina	SCELTA PAG 7
Type in the number of the page required, and confirm with <b>ENTER</b> .	0 ÷ 9	○ Pag. = ON
On confirming with <b>ENTER</b> , if the set-up parameter "E" =1, the page will be executed. Use the <b>CLEAR</b> key to select the successive line without commanding positioning. If input I4 = ON, when the <b>ENTER</b> key is pressed, the instrument executes the first line while, when input I4 = OFF, the page is blocked. The arrow key is used to scroll the various lines of the page from the first to the last or up to the line in which page end has been inserted. <b>N.B.</b> The selected lines will be executed if I4 = ON (positioning enabled).		$\begin{array}{c} PAG & 7\\ 1 & 123456 \end{array}$
To exit the function, press the <b>PAGE</b> key.	pagina	⊖ Pag. = OFF



### CHOICE OF THE PAGE TO BE EXECUTED

Description	Keyboard	Display
To select a specific line of the programme, access the line choice function.	- riga	$\begin{array}{c} SCELTA\\ 3 r I GA 9 \end{array}$
Type in the number of the line required within the page selected with the LINE key and confirm with ENTER.	e e e e e e e e e e e e e e e e e e e	○ Aiga = ON
The flashing quota indicates that the value can be modified or executed by the operator using <b>ENTER</b> (when enabled in set-up). On confirming with <b>ENTER</b> the quota stops flashing to show that execution is under way.	Û÷ Û	r I G A 7 3 234567
For the quota to be modified again, press the <b>CLEAR</b> key; the current positioning will be aborted and the quota will flash again. The modified value will not be memorised and a new line display will show once more the value programmed in page programming.		
By pressing the arrow key, the various page lines can be scrolled from first to last or up to the line in which page end was inserted.		
<ul> <li>N.B. The lines selected will be executed if input 14 = ON (positioning enabled).</li> <li>If negative quotas are introduced the maximum programmable value is "-99999".</li> </ul>		
To exit the function, press the <b>LINE</b> key.	riga	○ Riga = OFF

### DISPLAYS

Description	Keyboard	Display
<i>Lower left hand display</i> Number of the selected line. <i>Upper right hand display</i> Count. <i>Lower right hand display</i> Preselection.		123456 11 23467
Parametro di set-up "AE" impostato a "1" e posizionamento in fascia di tolleranza. <i>Upper right hand display</i> Number of quota selected. <i>Lower right hand display</i> Count. <i>Lower right hand display</i> Piece counter.		123456 11 C 1234



### 4-2 OPERATION GRAPHS AND TABLES

### PRESET SEARCH

### "Mode 0" - Loading the preset quota using the zero impulse enabling input.

The preset quota loading command is only provided by the zero impulse enabling input.

Once the preset search procedure has started, the axis moves towards the sensor connected to the zero impulse enabling input; when, during the stroke, the axis activates this input reversing the direction and decelerating.

With the deactivation of the zero impulse enabling input, the preset quota is loaded on the instrument count. With this procedure, the preset quota loading condition is that the enabling input has been activated and then successively deactivated.

## "Mode 1" - Loading the preset quota using the zero impulse and the zero impulse enabling input with inversion.

The preset quota loading command is provided by the transducer zero impulse. When an encoder provides a zero impulse on each revolution, the zone in which the axis acquires the zero impulse must be determined; the zero impulse enabling input is used for this purpose.

Once the preset search procedure has started, the axis moves towards the sensor connected to the zero impulse enabling input; when, during the stroke, the axis activates this input reversing the direction and decelerating. With the deactivation of the enabling input the instrument is ready to acquire the zero impulse: with the first zero impulse provided by the transducer, the preset quota is loaded on the instrument count. With this procedure, the preset quota loading condition is that the enabling input has been activated and then successively deactivated and a zero impulse has been acquired.

## "Mode 2" - Loading the preset quota using the zero impulse and the zero impulse enabling input without inversion.

The preset quota loading command is provided by the transducer zero impulse. When an encoder provides a zero impulse on each revolution, the zone in which the axis acquires the zero impulse must be determined; the zero impulse enabling input is used for this purpose.

Once the preset search procedure has started, the axis moves towards the sensor connected to the zero impulse enabling input; when, during the stroke, the axis activates this input, maintaining the direction and decelerating.

The instrument is ready to acquire the zero impulse: with the first zero impulse provided by the transducer, the preset quota is loaded on the instrument count.

With this procedure, the preset quota loading condition is that the enabling input has been activated and then successively deactivated and a zero impulse has been acquired. In order to avoid errors, the enabling input activation space must be less than the distance covered by the axis during one encoder revolution. If not, the zero impulse can be acquired at two different points.

### "Mode 3" - Loading the preset quota using the input.

With this procedure preset search is not enabled. The preset quota loading command is provided by the activation of the preset search start input.

## CHAPTER 5

### 5-1 INPUT AND OUTPUT TROUBLESHOOTING

The instrument provides troubleshooting for the input and digital output logic status; according to the numbers displayed, it is possible to understand whether an input arrives at the instrument and if an output has been excited. The top line of the display refers to the inputs status; if number 1 is displayed, this means that input 1 has been activated; if number 2 is shown, this means that input 2 has been activated and so on. Input Z (transducer zero impulse) is signalled with an A; if this is shown, there is no zero impulse; if not shown, the zero impulse is supplied to the instrument. The last line of the displays refers to the logic status of the digital outputs. The same correspondence (each number corresponds with its equal output); for example, the presence of the number 4 indicates that the instrument is energising output 4.

Description	Keyboard	Display
Access the troubleshooting function. The input (  ) and output (0) status will be displayed.	<b>F</b> + <b>6</b>	I 123456 01 23457c
		○ <sup>Funz</sup> .= ON
To exit the function, press " <b>F</b> ".	F	

### 5 - 2 HOW TO COMPLETE THE TECHNICAL ASSISTANCE FAX FORM

If we are to provide you with a speedy, efficient and high-quality service, we need your help.

If ever you need the assistance of QEM in dealing with any technical problems that may arise in your applications and, even though all the instructions in the "Installation, maintenance and servicing" manual have been followed, the problem persists, we invite you to fully complete the fax form enclosed with the installation, maintenance and servicing manual and send it to the QEM assistance office.

In this way, our service engineers will have all the essential information for the understanding of your problem (thus avoiding long and costly telephone calls).

In thanking you for co-operation, we wish you all the best in your work.

### NOTE

If ever you have to send an instrument to us for repair, please read the points below carefully.

- If possible, use the original packaging. In any event, the packaging must protect the instrument from knocks during its journey.
- Enclose a detailed description of the problem that has occurred, along with the part of the wiring diagram where the instrument is located, in the package. If the problem involves data storage, enclose the instrument set-up programming (set-up, work quotas, auxiliary parameters ...).
- If necessary, ask us specifically for an estimate on the repairs. If no estimate is requested, the cost will be calculated on completion.
- Our service engineers will give priority to instruments that are sent to in accordance with the instructions in these notes.

### 5-3 WARRANTY

The warranty conditions are as stated in the general conditions of sale.



This product is an electronic instrument and, therefore, should not be considered a machine. As a consequence, it is not subject to the requirements of EEC Directive 89/392 (Machine Directive). For this reason, we affirm that if the QEM instrument is used as a component of a machine, it may not be turned on if the machine does not satisfy the requirements of the Machine Directive.

The instruments marking does not relieve the customer from fulfilling the obligations of the law relative to the finished product.