

Setting up the CR10X as an SDI-12 sensor to be Interfaced with the MICROCOM GTX Modulator.

Author: Richard Schwarz

PRELIMINARY

SUMMARY

The Microcom Model GTX Satellite Transmitter and Data Collector works on GOES, GMS, ARGOS, SCD & METEOSAT systems. The GTX has some data logger functions built into it, including an SDI-12 and counter input. The GTX can be programmed and can be interfaced to external data acquisition systems via its RS-232 port.





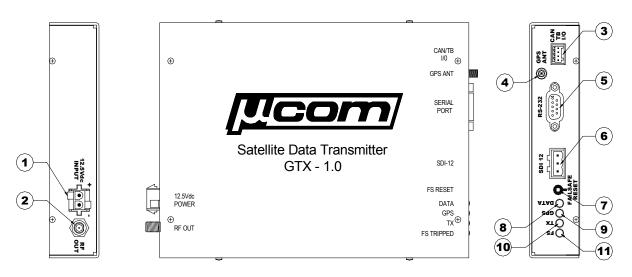
Microcom GTX Satellite Transmitter

Campbell CR10X Programmable Data Logger

For example, the CR10X from Campbell Scientific is an external Data logger / Data Acquisition system which can be interfaced to various sensors to log measurements. The CR10X has its own programming language which allows programs to be written for various application scenarios. By connecting the CR10X to the Microcom Design GTX Modulator, programs can be written on the CR10X can be set up as an SDI-peripheral and logged measurements can then be read via the GTX SDI-12 port and then transmitted via GOES, GMS, ARGOS, SCD and METEOSAT satellite systems.

INTRODUCTION

The Campbell Scientific CR10X is a mature data logger product used in many data acquisition systems world wide. It can interface to dozen's of standard sensors. It also has a industry standard SDI-12 serial interface which can easily be connected to the Microcom GTX Satellite transmitter. The programming of the Campbell Scientific CR10X is powerful, but somewhat cryptic. This application note attempts to cover the programming and hardware aspects of connecting the CR10X to the Microcom GTX transmitter via the SDI-12 interface.



Microcom GTX Transmitter Connections



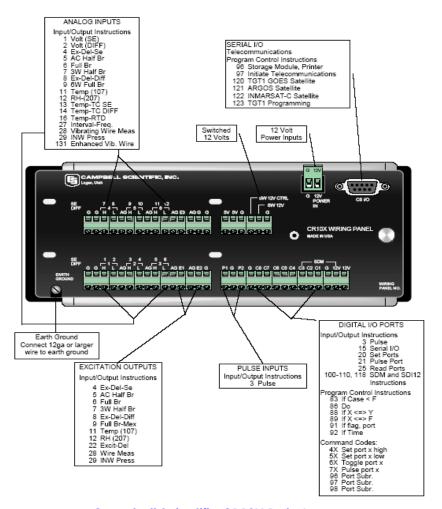
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Provided below is a list of the major end panel components on the GTX

- 1. Main Power Input Connector +12.5 VDC
- 2. RF Output Connector
- 3. CAN (future) and Tipping Bucket Connector
- 4. GPS Antenna Connector
- 5. RS-232 Serial Port Connector
- 6. SDI-12 Interface Connector
- 7. Failsafe Reset Push-Button
- 8. LED4: Data in Transmit Buffer LED (Green)
- 9. LED3: GPS Receive Active LED (Green)
- 10. LED2: RF Transmit Active LED (Green)
- 11. LED1: Failsafe Tripped LED (Red)

The Campbell CR10X interface panel is shown below.



Campbell Scientific CR10X Data Logger

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User's of this application note should be familiar with, or have access to basic coding techniques, user's manuals and software associated with using the GTX and CR1000, including:

- 1) Microcom GTX User's Manual
- 2) Microcom GTX GUI Software
- 3) Campbel Scientific CR10X User's Manual
- 4) Campbell Scientific LoggerNet Software

CR10X **PROGRAMMING**

The CR10X is a popular Data logaer from Campbell Scientific, Campbell has set up a proprietary interpreter for use in the device. The CR10X language is made up of parameter based INSTRUCTIONS (routines) which can be strung together in TABLES (programs). The device allows 3 tables to be stored inside the device. The third table is used for subroutines. The Microcom GTX has an SDI-12 interface. The CR10X can be set up to appear as a standard SDI-12 sensor to the GTX Transmitter. In setting up the CR10X to respond as if it was a SDI-12 sensor, the CR10X uses INSTRUCTION 106 which must be implemented as the first INSTUCTION in SUBROUTINE 98 (located in table 3).

INSTRUCTION 106 DETAILS:

PARAMETER	DATA TYPE	DESCRIPTION
01 SDI-12 Address	4 bytes	SDI-12 address which the CR10X uses when set up as a sensor Valid values are (0-126)
02 TIME/VALUES	4 bytes	ttnn where tt is the time in secs the CR10X requires to complete its sensor routine, and nn is the number (max 63) of values (readings) returned.
03 LOCATION	4 bytes	The starting address location for the nn values to be returned to the recorder. On an M command issued by the SDI-12 controller, the CR10X Starting location = Parameter3 (this parameter) = (n*x) where nn is specified in Parameter2. and x is the number following the M command (M1,M2 etc)

Results of 106 INSTRUCTION: Will return a set of input locations in response to the M or M1-M9 command sequence.

If the SDI-12 issues a V command sequence (status) indicates the status of the CRX-10 sensor. The first and second values are from the *B mode of the CR10X sensor, giving the number of watchdog errors in the CR10X, and the number of table overruns that have occurred. The third is a signature of the sensor CR10X memory. The signature is created by the same technique that INSTRUCTION 19 (signature) uses.

The CR10X can also respond to the I command. The CR10X send the following string back to the I command:

"10CAMPBEL CR10X 001 aaaa" where aaaa is the number from the eighth window of the *B mode.

CONNECTING **UP THE CR10X PROGRAMMING PORT TO A LAPTOP SERIAL PORT**

The CR10X has a D9 port on it which can be used for programming the CR10X. The D9 is NOT A STANDARD SERIAL PINOUT. Rather it has the following pinout:

PIN #	USE	Input or Output	Description
1	5V	OUTPUT	5VDC output
2	GND	=	Ground
3	RING	INPUT	Raised high by peripheral to put the CR10X in the telecommunications mode (TTL levels)
4	RXD	INPUT	Receive data (TTL levels)
5	ME	OUTPUT	Modem Enable signal raised by CR10X in response to the RING signal (TTL Levels)
6	SDE	OUTPUT	Synchronous Device Enable (not used in SDI- 12 mode)
7	CLK/ Handshake	INPUT/ OUTPUT	Not used in SDI-12 mode
8	NC		
9	TXD	OUTPUT	Transmit data (TTL levels)

Since TTL levels are being used we need to use a translator like the MAX 3223 RS232 transceiver chip. Besides the TX and RX data transceiver pair, an additional data transceiver pair is needed for the ME and RING line. The RING and ME lines will be connected to the RTS and CTS lines on a standard RS232 port on our laptop. This allows us to control the RING line and monitor the ME line.

For our testing we will use the APS-V240 FPGA board to handle the interface between the GTX and the CR10X. The APS-V240 has an on board MAX3323 chip with an on board D9 connector (J11) and an FPGA. The V240 board runs the connections through an FPGA which also allows for line switching inverting and for various test patterns to be transmitted if needed. A D9 was connected between the V240 FPGA pins and the CR10X to both control and change the levels of the RS232 lines of the Laptop PC into the required levels of the CR10X. The FPGA design could later be used to do any other simulations or prototyping or testing for the CR10X D9 control port. Figure 1 shows the connections between the PC LAPTOP and the APS-V240 and the CR10X. LEDs on the APS-V240 are also connected to the RING/ME/RX data lines for monitoring purposes. An optical cable is available from Campbell which does the job of level translation and pin swapping.



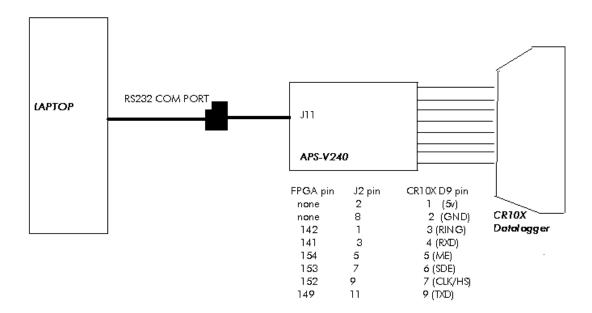


Figure 1 CR10X Programming port connections

The VHDL code for the V240 on board FPGA is shown below:

```
use IEEE.STD_LOGIC_UNSIGNED.ALL;
```

- -- Uncomment the following lines to use the declarations that are
- -- provided for instantiating Xilinx primitive components.
- --library UNISIM;
- --use UNISIM.VComponents.all;

```
entity rs232ttl is
  Port (
                      T_rs232_rx_in : in std_logic;
               T_rs232_tx_out : out std_logic;
               T_rs232_cts_in: in std_logic;
               T_rs232_rts_out : out std_logic;
               T_Osc_I: in STD_LOGIC;
               T_CSIO_RING_o: out std_logic;
               T_CSIO_RXD_o: out std_logic;
               T_CSIO_ME_i: in std_logic;
                       T_CSIO_SDE_i: in std_logic;
                       T_CSIO_CLK_HS_io: inout std_logic;
               T_CS_TXD_i: in std_logic;
              T LED1 o
                                     out STD LOGIC;
               T_LED2_o
                                     out STD_LOGIC
                       T_LED3_o
                                            out STD_LOGIC
       );
```



```
end rs232ttl;
architecture Behavioral of rs232ttl is
SIGNAL S_BufOSC
                              : std_logic;
       component IBUFG
               port (I: in std_logic O: out std_logic);
       end component;
begin
-- Global Buffer Assignments
U3: IBUFG port map (I \Rightarrow T_OSC_i, O \Rightarrow S_BufOsc);
clockout: Process(S_BufOsc) --
 begin
               if (S_BufOsc'event and S_BufOsc = '0') then
                   T_CSIO_RING_o <=
                                             NOT T_rs232_cts_in;
                    T_rs232_rts_out <= T_CSIO_ME_i;
                    if (T_CSIO_ME_i = '1') then
                      T_CSIO_RXD_o <= not T_rs232_rx_in;
                      T_rs232_tx_out <= NOT T_CS_TXD_i;
                    end if:
                    T_LED1_o<= NOT T_rs232_cts_in; --ring
                     T_LED2_o<= T_CSIO_ME_i;
                                                     --me
                     T_LED3_o
                                     <= T_rs232_rx_in;
                                                                    --rxd
               end if:
end process;
end Behavioral;
```

Figure 2 shows the SDI-12 connections between the CR10X and the MICROCOM GTX modulator

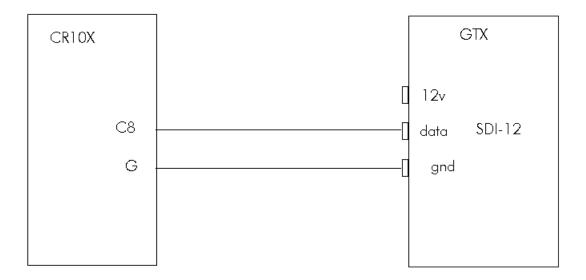
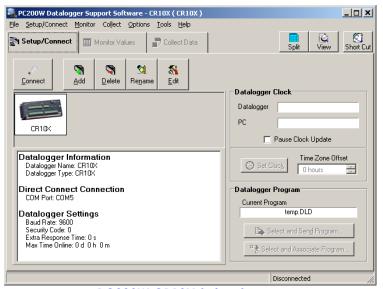
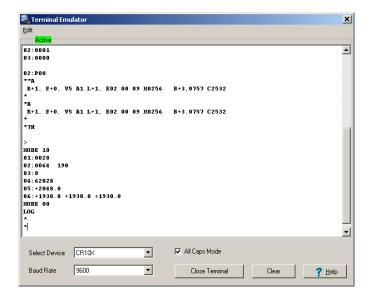


Figure 2 SDI-12 connections

CR10X/GTX USER SOFTWARE The CR10X has user software available which aid in programming the CR10X. The PC200W software will be used in terminal mode to program the CR10X, while the GTX Software will be used in SDI-12 terminal mode to send SDI-12 commands.



PC200W CR10X Setup Screen

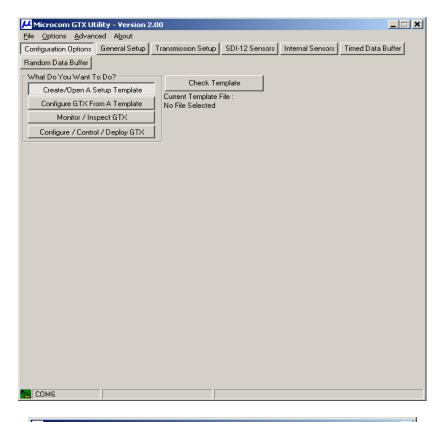


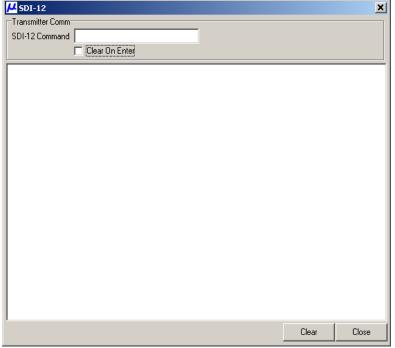
PC200W Control Software Screens

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MICROCOM GTX SOFTWARE SCREENS

Setting up the 106 command on the CR10X:

On the CR10X terminal enter the telecommunications mode by pressing:

7H and FNTFR

you should get this prompt

In order to use INSTRUCTION 106 we have to place it in the dedicated INTERRUPT SUBROUTINE 98 (which will interrupt the program on SDI-12 requests). We will have to create SUBROUTINE 98 in TABLE 3

First we enter table 3 by pressing

*3

At the P00 prompt then press

85

Α

The only parameter is the SUBROUTINE number which is 98

98

Α

Then enter the 106 Instruction

106

Α

Then enter the 106 parameters by typing:

0009

0001

0000

This sets the SDI-12 address of the CR10X to 9 and sets the time required to 0, and the number of parameters to 1, starting at location 0.

then we need to enter the END OF SUBROUTINE INSTRUCTION which is INSTRUCTION 95. 95

Α

So the Pseudo code for our SUBROUTINE written in table 3 is:

I-85 (LABEL INSTRUCTION)

```
P1 – 98 (parameter one is the SUBROUTINE #)
```

```
I-106 ("SET CR10X as SDI-12 SENSOR" INSTRUCTION)
P1-0009 (parameter 1 – SDI-12 address)
P2-0001 (parameter 2-zero time / 1 measurement)
P3-0000 (parameter 3- starting location 0000)
```

I-95 ("END OF SUBROUTINE" INSTRUCTION)

Now one additional thing: The 106 INSTRUCTON requires 182 intermediate locations which means we have to change the default number of intermediate locations available. We do this by using the *A command (mode A).

and then changing the second parameter to a larger number then 182..lets try 200.

Now here is what the terminal IO looked like:

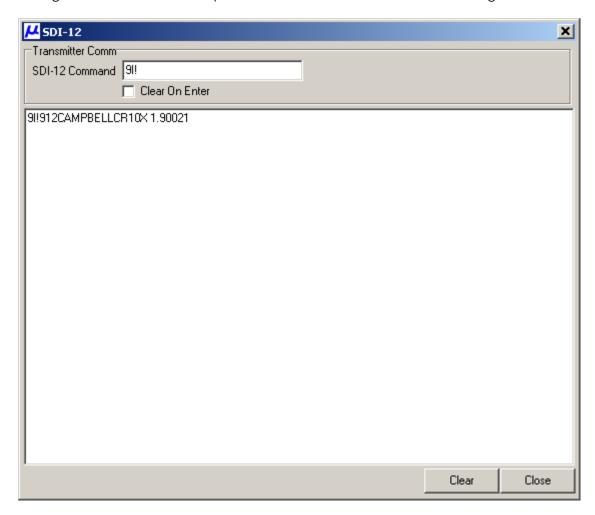
```
// this puts us in telecom mode
*7H
       // hit * here and it changes the > prompt to MODE
MODE 03:0000 //hit 3 to go into 3 mode (subroutine table)
01:P85
          // enter first instruction 85
01:98
          // only parameter is the subroutine number which is 98
02:P00 106
              // enter the next instruction which is the 106 (set to SDI-12 sensor)
01:0000 0009 // enter first parameter
02:0000 0001 // enter second parameter
03:0000 0000 // enter third parameter
03:P00 95 // enter the END of SUBROUTINE instruction (95)
04:P00 // hit * and get MODE prompt
MODE 10 // enter A mode
01:0028 //just hit enter (don't change parameter 1)
02:0064 200 // change parameter 2 (intermediate locations) to 200
              //hit * to get MODE prompt
MODE 00
           //type in 0 to compile program
LOG
*0
```

So we now have set the CR10X up as an SDI-12 sensor with an SDI-12 address of 9.

To test this we will use the Microcom SDI-12 terminal to send an I command an see if the CR10X responds correctly.

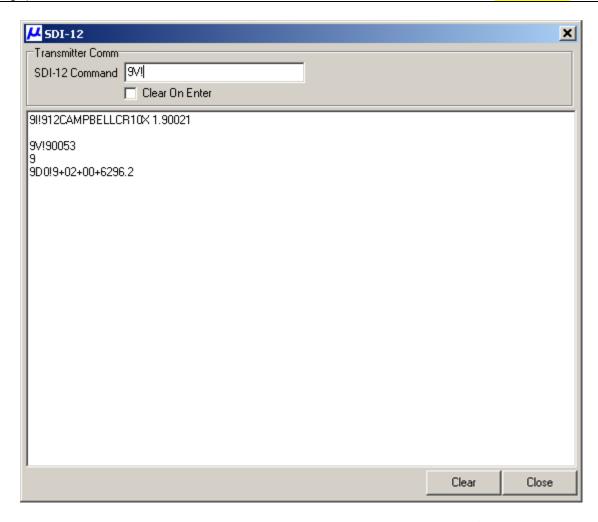
In the terminal we send the all command where a = SDI-12 address or in our case a 9.

The figure below shows the response of the CR10X to the command being sent.



Then we send the 9V! command which will get the status of the CRX10 as shown





Now to set up a real programming example of taking a measurement (we'll use the internal CR10X internal temperature) every 5 seconds and store it in location 1. We will then try and read the measurement from the CR10X from the SDI-12 terminal of the GTX software.

We have to take the measurement using in TABLE 1. So:

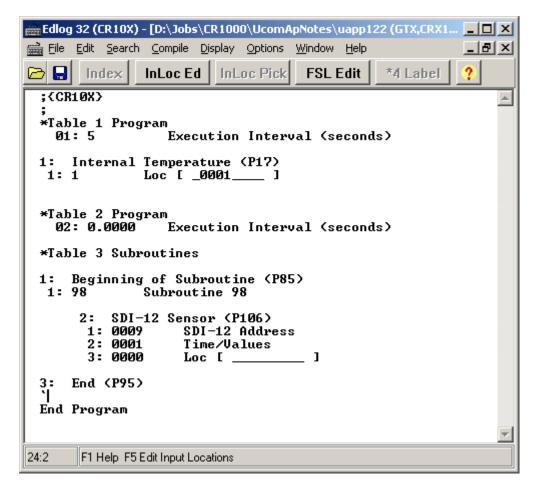
*1

MODE 01:0000 //enter mode 1 SCAN RATE +0.0000 5 //set timing to every 5 seconds 01:P00 17 // enter INSTRUCTION 17 (take internal temp) 01:0000 1 // parameter one stores the temp in location 1 02:P00 // compile the program MODE 00

now lets change the 106 instruction to read from location 1 instead of 0.

```
7H
>
MODE 03:0000
01:P85
01:98
02:P106
01:0009
02:0001
03:0000 1 //change to location 1
03:P95
04:P00
MODE 00
LOG 1
```

If Loggernet software is available, then the following EDLOG code does essentially the same thing:

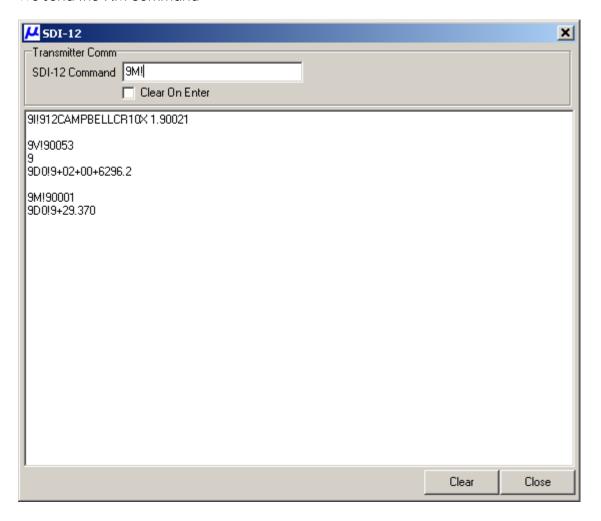


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GTX SDI-12 COMMAND TESTING

Now we need to send an M (measure) command from the SDI-12 terminal on the GTX.

We send the 9!M command



Ok now lets store the programs off into flash

enter the SAVE/Load Mode:

*D then the store command

6

then the program name (number) to save

Now that the terminal program works and shows that the data has come into the GTX, we can set up a program on the GTX. Opening the GTX GUI configuration file called cr10X_SDI12_ex1.txt . In this configuration you can see that SENSORS are enabled on the transmission screen, and that the SDI-12 parameter is read from address 9.

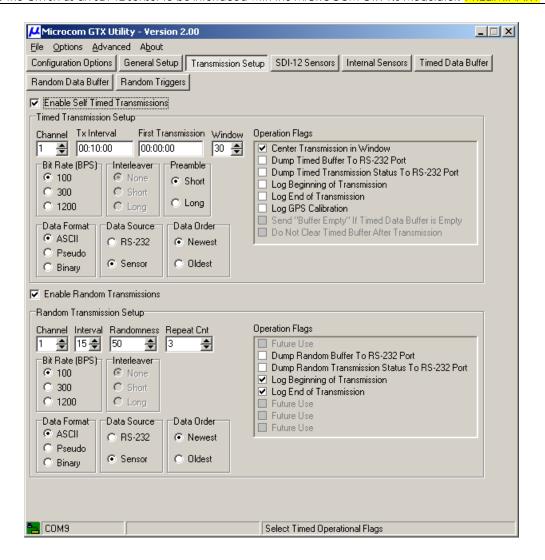
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*D

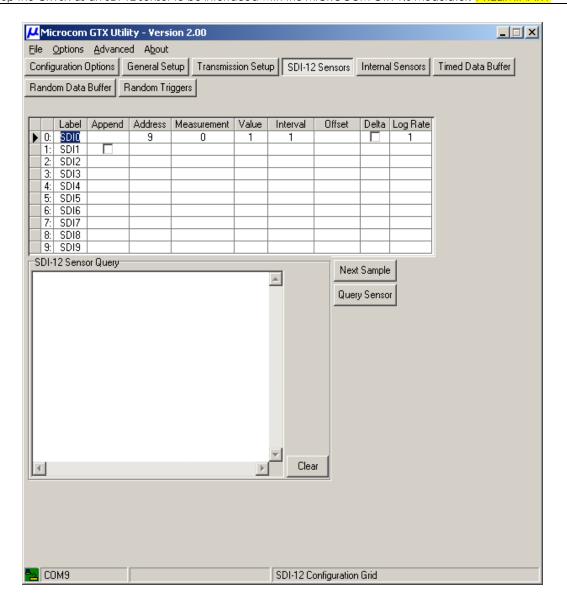
7

1 Α









Interface Cables

Using the APS-V240 board as we did earlier is not practical for field use. Several options exist to replace this interface APS-V240 interface card.

A programming interface cable for the CR10x (to a PC) is available from Campbell (either the SC32B or the SC929).

A Microcom B40 Interface Cable which has a MAX232 chip embedded in the D9 Shroud could also be used

In order to make the cable attach to the DTE (pinned male) PC serial port, a DCE port should be used (female). (NO MODIFICATIONS TO PIN 2 AND 3) should be done to the B40 interface cable.

On the other end of the cable the TX and RX data should be a dual CMOS

inverter (ie a NL27WZU04 from ON Semiconductor) should invert the data from the CR10x and to the CR10x.

Such that:

PC<-> DCE D9—MAX232------cable-----NL27WZU04—DTE D9 <-> CR10X

MAX232CWE pin 11 attaches to green wire which connects to pin 6 of NL27WZU04 (CR10X).

MAX232CWE pin 12 attaches to the white wire which connects to pin 3 of the NL27W...

Pin 1 of NL27 attached to Pin 9 of the DTE D9 at the other end of the cable to be attached to the CR10X programming port

Pin 4 of the DTE D9 CR10X end of the cable gets connected to pin 4 of NL27W..

NL27W pin 2 connects to Pin 2 of D9 DTE connector (GND) NL27W pin 1 connects to Pin 1 of D9 DTE connector (VCC)

short out DTE D9 pin 1 to DTE D9 pin 3 (RING)

This cable should allow the PC to program the CR10X.

A custom cable from Microcom Design may be available which incorporates the changes to the Microcom B40 cable, and makes it a standard product. Check with Microcom Design for the availability of this cable.

Conclusion

The MICROCOM Model GTX Satellite Transmitter and Data collector has internal SDI-12 data logger capability. The CR10X from Campbell Scientific is a data loager which can interface to other sensors and then connect to the Microcom GTX Satellite Transmitter via the GTX's SDI-12 serial interface. Sensor data from the CR10X can then be sent to the GTX making the CR10X appear as a sensor to the GTX, who can then transmit the data over a satellite. This application note covered the connections and programming of the CR10X and GTX.

Revision **History**

Date	Version	Revision
June 10, 2005	1.0	Initial Microcom Preliminary Release

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