## **Status Letter**

Week 5 - 2/22/15 LFEV

## **Team Milestones:**

### VSCADA:

Last week:

System block diagrams and the GUI designs are drawn and included in the user manual. Able to run python code automatically after the system startup.

This week:

We are going to deliver the user manual. We will set up the logging daemon on the virtualbox. Install Linux on the embedded system once it arrives. Place the order for dashboard and microcontrollers.

### DYNO:

Last Week:

User manual completed and submitted to the website. Temperature sensor for motor selected and ready to order. Dyno software loaded onto computer. Dyno software works with Dyno sensors.

This Week:

Computer controllable throttle input to motor controller for safe and accurate out of room testing. Motor controller programmed using the Curtis software.

#### TSV:

Last week, we completed the schematic for implementing CAN on the BoB. We also completed schematics for a full system reset and the 24V pack indicator, though due to technical difficulties they are not all integrated into the same DxDesigner file. Additionally, we produced a pack wiring diagram for the TSV packs which was conspicuously missing from last year.

For next week, we plan to begin working on the CDR, write the maintainability plan and fix the AMS board schematics. Also we will put out orders for the AMS boards, the new LCD displays and the computers we will be using.

#### **GLV**:

Last week we sketched out all panel interfaces except the Cockpit Panel. We also sketched out the internal layout/circuit diagram sketch of the VCI, TSI, and Side Panel. These sketches were added to our working User Manual.

In the upcoming week, the GLV team plans on purchasing components for the GLV Power and VCI subsystems as well as the connectors for system integration. A new user manual will be submitted.

## **Outstanding Action items:**

Website: Ken has started the process for getting us hosted long term. --Steve Morton Papers

## **Budget:**

Item/Group	Quantity	Price	Total
SCADA			
Embedden Computer System	1	400	400
Dashboard LCD display and controller	1	100	100
Wireless Radio	1	50	50
GPS radio	1	50	50
DC-DC converter	1	35	35
Safety Loop Solid State Relay	2	10	20
Slave Sensor Micro Controller Hardware	4	15	60
		total	715
GLV			0
24V battery	1	185	185
Smart Charger	1	25	25
overvoltage protector - LTC4365	1	2	2
PolySwitch - LVR055	1	2	2
Container	1	150	150
Board	1	40	40
Red LED - McMaster-Carr 2779K7	2	9.62	19.24

29.04	14.52	2	Green LED - McMaster-Carr 2779K2
150	150	1	Wiring and fuses
16.68	16.68	1	Acrylic Frame
220	55	4	Veam Powerlocks
44.6	44.6	1	Tractive System Active Light Lamp
150	150	1	Physical Container
40.79	40.79	1	Circuit Board
37.55	37.55	1	Speaker - BUZZ PIEZO CIRC 42.85MM PANEL
8	8	1	Audio Amplifier
24	6	4	Temperature Sensor
30	15	2	Current Sensor
38	19	2	Voltage Sensor
15	15	1	Rate of Discharge Sesnor
15	15	1	Rate of Charge Sensor
6	6	1	State of Charge Sensor
150	150	1	VCI Container
1397.9	total		
0			DYNO
\$75.00	\$75.00	1	0 AWG (gage) wire - 50ft
\$50.00	\$50.00	1	Wire connector package
\$3.00	\$1.00	3	Temp sensor - LM20CIM7/NOPBCT-ND
\$20.00	\$20	1	4 to 8 pin adapter Motor controller
<b>#140.00</b>	4-4-1		
\$148.00	total		
			TSV
\$512.00	16	32	Advanced Circuits PCD AMS and BOB boards
\$459.00	459	1	parts from Mouser
\$141.70	141.7	1	parts from digikey

8 \$924.00	308	3	Microcontroller
4 \$31.62	10.54	3	Micro SD card 4GB Class 10 industrial
4 \$113.36	28.34	4	Fuse - 200A, Class T, A3A, 300Vac/160VDC
1 \$287.24	71.81	4	Fuse Holder - 200A AC, 300V, a Pole, molder
5 \$163.80	40.95	4	Fans - 119x25 24DC 100CFM 5W 2900RPM 43 dbA
5 \$660.45	94.35	7	AIR - 350A contractor
0 \$280.00	40	7	50A miniTactor
6 \$205.04	51.26	4	Panel Drain, Line 3, Grey
3 \$217.32	54.33	4	Panel Source, Neutral, Blue
5 \$46.00	11.5	4	LCD Character Display Module STN Y/G
2 \$408.00	102	4	Galvanically Isolated Ethernet
0 \$1,600.00	1600	1	Other Parts
\$0.00			
\$0.00			
\$6,049.53	total		

<b>Total Money</b>	5000
Total Requested	8310.43
Remaining Money	-3310.43

# Tasks due within the last 7 days

Printed from Asana

Adam Cornwell	
Adam Cornwell: Finalize system states and define inputs/outputs	due Feb 18
Alex Hytha	
✓ Alex Hytha: <del>Temp Sensor chosen and ordered</del>	due Feb 21
Alex Hytha: TSV Safety Plan TSV safety plan must be written	due Feb 19
☐ Removing AMS PCBs	
☐ Removing Batteries	
☐ Reset AMS PCBs	
□ Reset Pacman	
☐ <del>AIR bypass</del>	
□ <del>voltage/current probing</del>	
☐ High power plugs	
Aloysius Posillico	
✓ Aloysius Posillico: <del>TSI Panel Sketches -AP</del>	due Feb 21
✓ Aloysius Posillico: <del>TSI Circuit Sketches -AP</del>	due Feb 21
Bikram Shrestha	
✓ Bikram Shrestha: Design GUI for 3 modes	due Feb 20
Brendan Malone	
☑ Brendan Malone: <del>User manual</del>	due Feb 19
Daniel Zakzewski	
✓ Daniel Zakzewski: <del>Side Panel BOM -DZ</del>	due Feb 21
☑ Daniel Zakzewski: <del>VCI Circuit Sketches -DZ</del>	due Feb 21
☑ Daniel Zakzewski: <del>Side Panel Internal Layout Sketch -DZ</del>	due Feb 21
✓ Daniel Zakzewski: <del>Side Panel Circuit Sketches -DZ</del>	due Feb 21
Hansen Liang	
_	J - F-1 00
✓ Hansen Liang: Choose new LCD display, interface	due Feb 22

## Jaejoon Yang

✓ Jaejoon Yang: <del>Proposal for 20V indicator design</del>	due Feb 22
John Bloore	
✓ John Bloore: <del>Dyno to computer integration with sensors</del>	due Feb 21
John Gehrig	
☐ John Gehrig: Place the purchase for embedded system	due Feb 23
✓ John Gehrig: Finalize schedule with faculties	due Feb 22
Jordan Blake	
☐ Jordan Blake: Completed pack wiring diagram	due Feb 22
Jordan Frank	
✓ Jordan Frank: TSI Safety loop circuit sketch -JF	due Feb 21
Kai Ottaway	
☐ Kai Ottaway: Rearrange top of box	due Feb 19
Katie Nellis	
✓ Katie Nellis: Proposal for full system reset designs	due Feb 22
Nate Hand	
□ Nate Hand: Motor Controller Cooling system built	due Feb 21
Nick DiNino	
■ Nick DiNino: GLV Battery Circuit Sketches -ND Significant redesign of the circuit used as a power monitor has pushed back sketching of the circuit.	due Feb 21
✓ Nick DiNino: GLV Battery Panel Sketches -ND	due Feb 21
Rameel Sethi	
✓ Rameel Sethi: Simple startup software on Virtualbox	due Feb 20
Sam	
☑ Sam : Software level CAN outline and library design	due Feb 20
Stephen Mazich	
✓ Stephen Mazich: User Manual	due Feb 19

#### William Stathis

William Stathis: Schematic implementation for CAN bus

due Feb 22

### **Yiming Chen**

Yiming Chen: Complete User Manual

due Feb 20

## **Zach Helwig**

Zach Helwig: VCI Panel Sketches -ZH

due Feb 21

Zach Helwig: GLV Hub Panel Sketches -ZH

due Feb 21

✓ Zach Helwig: Side Panel Panel Sketches -ZH

due Feb 21

## **Unassigned**

□ User Manual Update

due Feb 21

☐ ATP submission 2

due Feb 21

#### D011 - Calibration and Accuracy

due Feb 23

Any data acquisition system design or test plan must be accompanied by a Calibration and Error Analysis document that estimates the uncertainties associated with all system measurands. This document must include both analytical estimates of measurement uncertainty, as well as a justified design of acceptance tests to determine the uncertainty achieved in practice. The testing design from this document shall be incorporated into the system ATP.

#### D004 - Acceptance Test Plan

due Feb 23

The Acceptance Test Plan (ATP) is a document that describes how the system as a whole will be tested and demonstrated so as to prove compliance with all requirements and specifications. The ATP should include forms that can be filled out by testers during execution. These filled out forms will be used to create the ATR.

Compliance must be conclusively proved in any of the following three ways:

- Analysis detailed logical analysis can demonstrate compliance by reasoning from known facts (a priori or empirically) similar to the form of a mathematical proof. Analysis can be used cited research results in conjunction with the documented results of subsystem QA testing, along with generally accepted technical principles to prove system level requirements are met. Analysis memos and relevant data are attached to the ATR.
- Test an explicit test, experiment, or demonstration can be used to prove compliance with a certain requirement by acquiring new empirical facts and combining these with analysis as described above. The comprehensive results of any measurements conducted as part of an ATP test is included in the ATR, along with date and time of the test, the pass/fail criteria, uncertainty, statistical confidence, pass/fail result, witness name, and witness signature..
- Inspection –compliance is made evident by directly examining the system. Photographs with detailed annotations or other evidence gathered in an inspection is included in the ATR.

The ATP should be arranged to minimize the work involved in testing. If possible, multiple requirements should be demonstrated by each test. The ATP should include a compliance matrix making it obvious that all requirements have been addressed by the plan.

Numerical specifications shall be considered "passed" if the measured value is demonstrated by empirical statistical trials to meet the specification at a 90% confidence interval.

# **Incomplete Tasks due within the next 7 days**

Printed from Asana

Adam Cornwell	
□ Adam Cornwell: PACMAN Communication Library	due Feb 27
Alex Hytha	
☐ Alex Hytha: Complete and submit ATP Final draft	due Feb 28
Aloysius Posillico	
□ Aloysius Posillico: TSAL Circuit Schematic -AP	due Feb 28
☐ <b>Aloysius Posillico</b> : TSAL Approval and Submission -AP	due Feb 28
□ Aloysius Posillico: TSAL Component Purchase -AP	due Feb 28
Brendan Malone	
☐ Brendan Malone: Model the motor in software	due Feb 28
Daniel Zakzewski	
□ Daniel Zakzewski: Cockpit Panel BOM -DZ	due Feb 28
□ Daniel Zakzewski: Cockpit Panel Panel Sketches -DZ	due Feb 28
☐ Daniel Zakzewski: Cockpit Panel Internal Layout sketch -DZ	due Feb 28
□ Daniel Zakzewski: VCI Internal Layout Sketch -DZ	due Feb 28
□ Daniel Zakzewski: VCI Purchase of Components -DZ	due Feb 28
Hansen Liang	
☐ Hansen Liang: User Interface Demonstrations	due Mar 1
☐ Hansen Liang: Maintainability plan	due Mar 1
Jaejoon Yang	
☐ Jaejoon Yang: Communicate new TSV plan with MechEs	due Mar 1
☐ Jaejoon Yang: Put in order for AMS, LCD, and computers	due Mar 1
John Bloore	
☐ <b>John Bloore:</b> Computer controllable throttle input to motor controller	due Feb 28
John Gehrig	
☐ John Gehrig: Embedded Linux Installation (VAB-820)	due Feb 27

☐ <b>John Gehrig:</b> Place the purchase for embedded system	due Feb 23
☐ <b>John Gehrig:</b> Place the order for dashboard and microcontrollers	due Feb 26
Jordan Blake	
☐ Jordan Blake: Hardware interface control specification	due Mar 1
☐ Jordan Blake: Correct AMS layout errata	due Mar 1
☐ Jordan Blake: Completed pack wiring diagram	due Feb 22
☐ Jordan Blake: AIR failure sensor for main fuse	due Mar 1
Jordan Frank	
☐ Jordan Frank: Connector Inventory -JF	due Feb 28
☐ Jordan Frank: Connector BOM -JF	due Feb 28
☐ Jordan Frank: Connector Order -JF	due Feb 28
Kai Ottaway	
☐ Kai Ottaway: Rearrange top of box	due Feb 19
Katie Nellis	
■ Katie Nellis: Detailed specifications for each subsystem type	due Mar 1
☐ Katie Nellis: Updated system design	due Mar 1
☐ Katie Nellis: Correct BoB board errata	due Mar 1
Nate Hand	
■ Nate Hand: Program the motor controller using the Curtis software	due Feb 28
■ Nate Hand: Motor Controller Cooling system built	due Feb 21
Nick DiNino	
■ Nick DiNino: GLV Battery Circuit Sketches -ND Significant redesign of the circuit used as a power monitor has pushed back sketching of the circuit.	due Feb 21
□ Nick DiNino: GLV Power Internal Layout Sketch -ND	due Feb 28
■ Nick DiNino: GLV Power Purchase of Components -ND	due Feb 28
Rameel Sethi	
☐ Rameel Sethi: System Logging Daemon	due Feb 27
☐ Yiming Chen: System logging Daemon	due Feb 27

☐ Sam : CAN Communication Library Draft	due Feb 27
Stephen Mazich	
□ Stephen Mazich: Complete and submit Calibration and Error Analysis document	due Feb 28
William Stathis	
☐ William Stathis: Enhanced requirements analysis	due Mar 1
☐ William Stathis: Revised WBS	due Mar 1
Yiming Chen	
☐ Yiming Chen: System logging Daemon ⟨ System Logging Daemon	due Feb 27
Zach Helwig	
☐ <b>Zach Helwig:</b> Side Panel Design Approval and Submission -ZH	due Feb 28
☐ Zach Helwig: GLV Hub BOM -ZH	due Feb 28
☐ <b>Zach Helwig:</b> GLV Hub Internal Layout Sketch -ZH	due Feb 28
☐ Zach Helwig: Side Panel Panel Drawing -ZH	due Feb 28
Unassigned	
☐ User Manual Update and Submission 2	due Feb 28
☐ User Manual Update	due Feb 21
☐ ATP submission 2	due Feb 21
☐ A summary of the approved system level Acceptance Test Plan. < D001 - CDR Presentation	due Mar 2
☐ A safety plan per GPR005 if required for the team's subsystem. The plan must be approved by faculty and read and agreed to by all students in all teams. Given the significant addition of a dynamometer, motor, and controller to the design, and the re-engineering of the TSV system, is anticipated that the safety plans from previous years will need revision. < ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐	a t is
☐ An updated system design, comprising the final, detailed, and complete hierarchical subsystem breakdown. This breakdown shall be reflected in all other documentation consistent test plans, ICDs, schedules, etc shall all use the same breakdown. < □001 - □□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□□	
☐ Detailed specifications for each subsystem type, including interface definition, block diagram, state diagram, functional requirements, and QA test plan. < D001 - CDR Presentation	due Mar 2
☐ An enhanced requirements analysis showing that the detailed design and testing meets all requirements and constraints. Operation of critical circuits or systems shall be simulated and pragainst test benches using SPICE, Modelsim, Simulink, or other simulators. Simulation results spresented at CDR. < D001 - CDR Presentation	
$\hfill \square$ A system state demonstration that includes a detailed software simulation of overall system states and state transitions. $\land$ D001 - CDR Presentation	due Mar 2
☐ User interface demonstrations with live computer interactivity that implements as much as possible the final look, feel, and functionality of every user interface. It is desirable that the state demonstration be integrated with the UI demonstration. < ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐	due Mar 2

☐ Communication link demonstration that proves operation of any wireless or wired communication links. < D001 - CDR Presentation	due Mar 2
☐ Hardware interface control specifications captured in an interface control document and System Drawing that documents the exact way subsystem types are instantiated and interinternally, and project wide. Pinouts of all connectors, conductor assignments in cabling shadocumented in the ICD. < D001 - CDR Presentation	connected both
☐ Detailed software API specifications. < D001 - CDR Presentation	due Mar 2
$\square$ A revised cost analysis and detailed program budget that documents costs to date and demonstrates compliance with financial constraints. $\triangleleft$ D001 - CDR Presentation	due Mar 2
☐ A revised program schedule that documents progress to date and identifies the tasks needed to complete the project. The schedule should identify system and software critical complete the project on time. < D001 - CDR Presentation	due Mar 2 path drivers to
☐ Report due a week before < D001 - CDR Presentation	due Mar 2
□ D011 - Calibration and Accuracy Any data acquisition system design or test plan must be accompanied by a Calibration and Error Analy estimates the uncertainties associated with all system measurands. This document must include both a of measurement uncertainty, as well as a justified design of acceptance tests to determine the uncertain practice. The testing design from this document shall be incorporated into the system ATP.	analytical estimates
D012 - Maintainability Plan The Maintainability Plan documents how the team plans to address the general maintainability require GPR007.	due Mar 2 ements given in
Any team that creates or substantially improves software for the project shall deliver a software-specific plan. Others must use the software written for this project over the 5-year life of the system. This deliver how software maintainability will be achieved.	
The software maintainability plan must be delivered in written form and accompanied by an oral prese should answer the following questions:	ntation. The plan
☐ What is the design of the system API and how will this design support ongoing reliab maintenance and expansion?	le operation,
☐ How is system configuration maintained? Will the system auto detect hardware configuration maintenance be required? If the latter, what is the consequence of misconfiguration?	guration changes
☐ What tool chain will be used? Is the tool suite up-to-date and actively supported? Is t mature enough to have stable functionality? Evidence must be provided to support asse	
☐ What third party software will be incorporated into the system? How will this be maint upgraded, or patched during the life of the system.	tained,
☐ How are requirements in GPR007 met?	
□ D004 - Acceptance Test Plan The Acceptance Test Plan (ATP) is a document that describes how the system as a whole will be teste so as to prove compliance with all requirements and specifications. The ATP should include forms that testers during execution. These filled out forms will be used to create the ATR.	
Compliance must be conclusively proved in any of the following three ways:	
<ul> <li>Analysis – detailed logical analysis can demonstrate compliance by reasoning from known facts (a p similar to the form of a mathematical proof. Analysis can be used cited research results in conjunction documented results of subsystem QA testing, along with generally accepted technical principles to pro</li> </ul>	with the

• Test – an explicit test, experiment, or demonstration can be used to prove compliance with a certain requirement by acquiring new empirical facts and combining these with analysis as described above. The comprehensive results of any measurements conducted as part of an ATP test is included in the ATR, along with date and time of the test, the pass/fail

requirements are met. Analysis memos and relevant data are attached to the ATR.

criteria, uncertainty, statistical confidence, pass/fail result, witness name, and witness signature..

Inspection –compliance is made evident by directly examining the system. Photographs with detailed annotations or

other evidence gathered in an inspection is included in the ATR.

The ATP should be arranged to minimize the work involved in testing. If possible, multiple requirements should be demonstrated by each test. The ATP should include a compliance matrix making it obvious that all requirements have been addressed by the plan.

Numerical specifications shall be considered "passed" if the measured value is demonstrated by empirical statistical trials to meet the specification at a 90% confidence interval.