

# User Manual

# **BAM & DICE**



## BAM-Shield with DICE-Boards

Version: 1.0en  
Author: Konrad Meyer

Date: 12. Nov. 2014

## Index

1 Important notes.....	3
1.1 Warning notices.....	3
1.2 General precautions.....	4
1.3 Additional notes.....	4
2 Components.....	5
2.1 BAM shield.....	5
2.1.1 Specification.....	5
2.1.2 Connections.....	6
2.2 DICE-STK.....	7
2.2.1 Specification.....	7
2.2.2 Utilization.....	7
2.3 DICE-TMC.....	8
2.3.1 Specification.....	8
2.3.2 Utilization.....	8
2.4 DICE-L6470.....	9
2.4.1 Specification.....	9
2.4.2 Utilization.....	9
2.5 DICE-9555.....	10
2.5.1 Specification.....	10
2.5.2 Utilization.....	10
2.6 DICE-TC.....	11
2.6.1 Specification.....	11
2.6.2 Utilization.....	11
2.7 DICE-VN.....	12
2.7.1 Specification.....	12
2.7.2 Utilization.....	12
3 Applications.....	13

## History

Version	Description	Author	Date
V1.0en	First English version	K. Meyer	12.11.2014

Congratulations on your purchase of the universal BAM Shield from **2PRINTBETA**. Please read the instructions carefully before setting the device in operation. Please also take note of the general safety instructions.

## 1 Important notes

Please observe all instructions given in this manual and read this information carefully before using the product.

### 1.1 Warning notices



#### Safety (Warning / Caution)

- Any operating conditions, such as use in hazardous areas, use in safety-related systems and areas in which the loss of function may present a particular risk to life and limb are prohibited with this product.
- Do not place any objects around the device, which prevent a dissipation of heat.
- Do not place flammable materials and substances in the environment of the device.
- Take care that no metal objects touch the electronics when using the product.
- Use for all interfaces matching plugs and wires.
- Use only components that are within the given specifications.
- Do not expose the device to liquids or corrosive substances.
- Operate the unit in a clean, dry and dust free environment.
- Should the structure be contaminated, disconnect the unit from the mains (remove the power plug and disconnect the PCB from the power supply) and gently clean it.
- Never let the appliance run unattended.
- This kit is designed for self assembly and construction. The finished device can generate and radiate high-frequency signals. The operation of the product may impair or interfere with other electronic devices during operation depending on the type of setup. You are hereby expressly advised of this risk and you should take the necessary measures to prevent this types of interference. Each completed unit must be tested for long-term operation to comply with applicable regulatory limits.
- The responsibility for the security of a constructed machine lies at the builder and operator of the system.

## 1.2 General precautions

### General operating conditions:

- Operate the device only in the final build up of the proposed hardware and with sufficient cooling.
- This device is sensitive to mechanical and physical influences.
- Turn off the power supply and remove the mains plug before making any changes to the installation and wiring of the setup. Not to do so may destroy your electronics and attached equipment.
- The device may be used only for the intended purpose within the limits of the electrical specification.

## 1.3 Additional notes

### Protection against electrostatic discharges



The unit is equipped with electronic components that can easily be destroyed by electrostatic discharges. Use the usual measures to protect the components when you install or use the device.

### Not suitable for children



The device is not suitable for toddlers and children. Make sure that small parts and accessories are kept safe and that the unit is protected against contact when children may be present in the vicinity of the device. Also make sure that your required tools are not in the reach of children and infants.

### Recycling and re-use

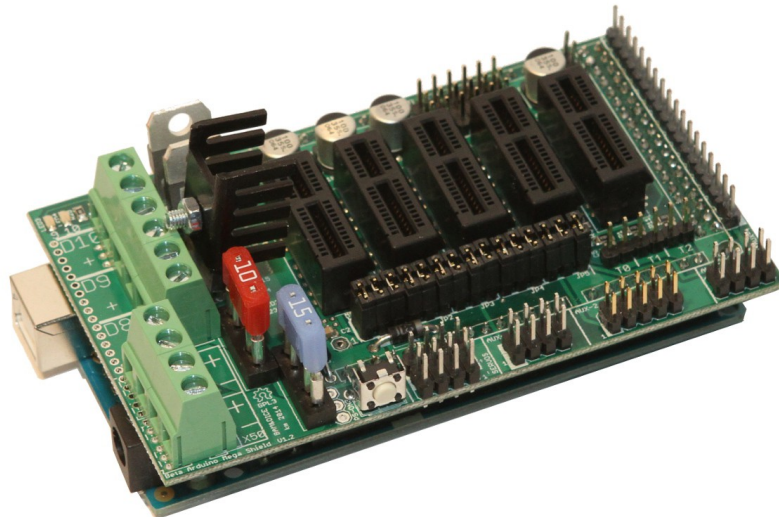


The product contains substances which must not be disposed in household waste (European directive 2002/96/EG). Please give this product to a designated location. Improper handling of components whose components consist of potentially dangerous or harmful substances can cause damage to the environment and can endanger humans, animals and plants. Dispose this product properly and contribute to the effective usage of natural resources. Your dealer will certainly help you. You can also return the device to an authorized collection site for recycling electrical waste and electronic equipment. For information about waste recycling, please contact your city office, the public waste companies or an authorized site for the disposal of electrical and electronic equipment.

## 2 Components

The kit of BAM&DICE includes the BAM shield and additional DICE boards for the individual user dependent applications. For software examples for each module and complete firmwares in specialized setups please visit [www.2printbeta.de](http://www.2printbeta.de).

### 2.1 BAM shield



Picture 1: BAM shield with Arduino, without other components

#### 2.1.1 Specification

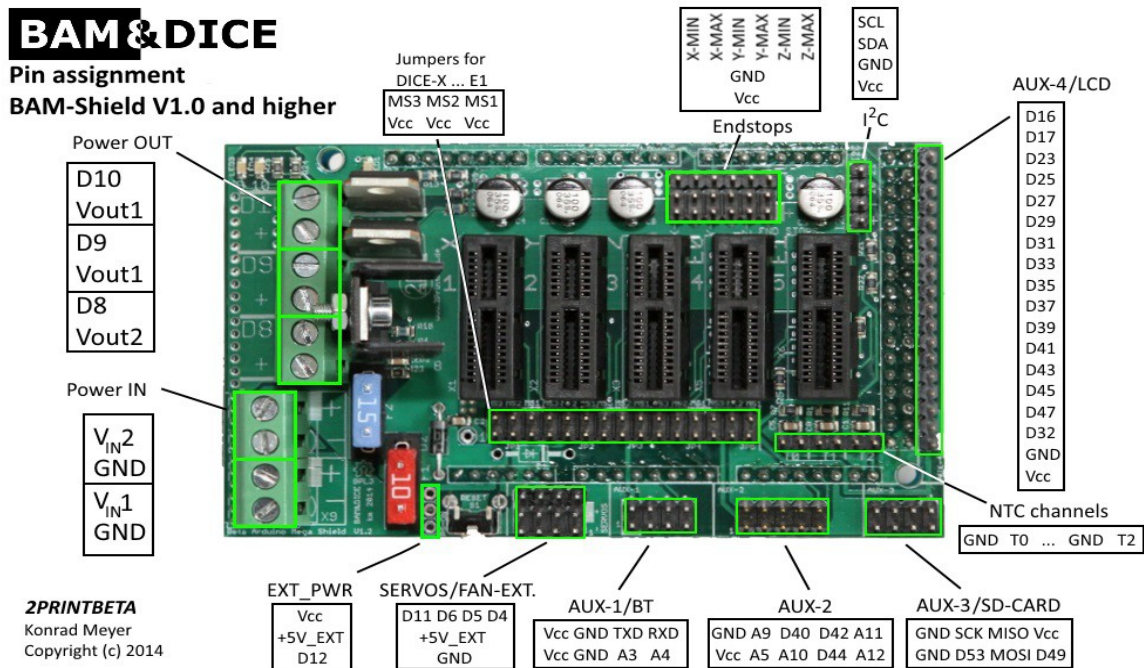
- Input 1:  $I_{max} = 15A^*$   
12V-Variante: +8V .. 18V (without DC/DC converter)  
24V-Variante: +16V .. 32V (with DC/DC converter)
- Input 2:  $I_{max} = 10A^*$   
+8V .. 32V
- Logic voltage: +5V
- Interface for Arduino Mega 1280 and 2560
- Configurable slots with jumpers
- 3 high current switches with up to 10A
- Power connection over screw termination blocks
- Diverse connections for expansions
- Over-current fuses with 10A and 15A
- Everything open source. Schematics, layout and firmware available
- Five DICE board connectors for individual controller extensions

The board is not reverse polarity protected. Always pay attention to the correct polarity!

(\* ) The fuses can also be switched in case of heavy loads at high current switch D8.

When inserting and wiring equipment to the board, be sure that the power supply is switched off.

## 2.1.2 Connections



Picture 2: Pin assignment of the BAM shield

### Pin name

V<sub>IN1</sub>, GND

V<sub>IN2</sub>, GND

Vout1

Vout2

D10, D9, D8

Vcc

+5V\_EXT

D12, D11, D6, D5, D4, TXD, RXD, A3, A4, A5, A9, A10, D40, D44, D42, A12, A11, SCK, MISO, D53, MOSI, D49, D32, D47, D45, D43, D41, D39, D37, D35, D33, D31, D29, D27, D25, D23, D17, D16, SDA, SCL, X-MIN, X-MAX, Y-MIN, Y-MAX, Z-MIN, Z-MAX

MS3, MS2, MS1

### Description

Power input for DICES, Arduino and loads at high current switches D9 and D10

Power input for load at high current switch D8

Power output from V<sub>IN1</sub>, fused

Power output from V<sub>IN2</sub>, fused

High current switches for loads (low side switched)

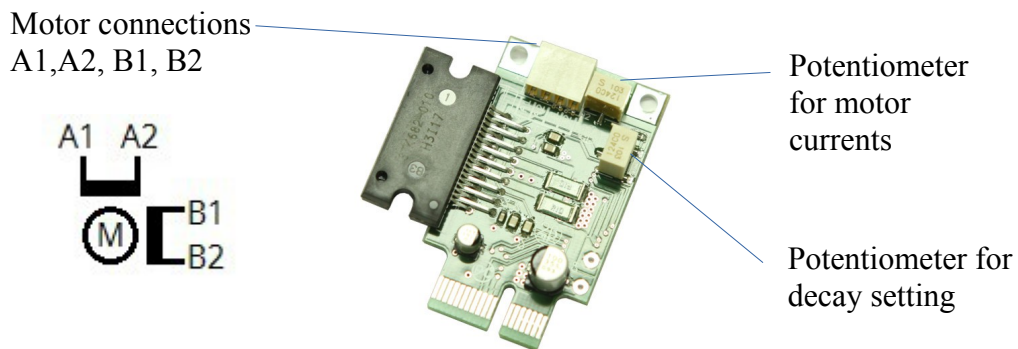
+5V power rail (Arduino generates this voltage)

External 5V power rail for additional servomotors

Digital I/Os of the Arduino

Jumper for microstepping settings and I<sup>2</sup>C addresses (for each DICE slot individually)

## 2.2 DICE-STK



Picture 3: DICE-STK  
Stepper driver

### 2.2.1 Specification

- Logic voltage: 5V
- Power voltage for motor: +9V .. 32V
- Control via STEP/DIR interface
- Without cooling up to 2A (65°C). Up to 2.86A with cooling air flow.
- Substepping: 1, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128
- Two trimmers for phase currents and decay setting
- Size: 51x43mm

### 2.2.2 Utilization

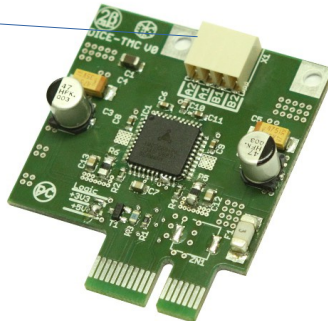
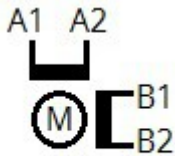
The DICE-STK drivers are controlled by the so-called STEP/DIR interface, i.e. the state (enable/disable), direction (CW, CCW) and step pulses (STEP) are logic signals from the microcontroller. The signals of the MS1..MS3 pins for the respective DICE slot define the microstepping. A '1' in the table defines the plugged jumper.

Jumper setup MS3, MS2, MS1	Substepping	Jumper setup MS3, MS2, MS1	Substepping
0 0 0	No substepping	1 0 0	1/16
0 0 1	1/2	1 0 1	1/32
0 1 0	1/4	1 1 0	1/64
0 1 1	1/8	1 1 1	1/128

## 2.3 DICE-TMC

High precision stepper driver with SPI interface and additional STEP/DIR interface.

Motor connections  
A2, A1, B1, B2



Picture 4: DICE-TMC  
Stepper driver

### 2.3.1 Specification

- Logic voltage: 3,3V / 5V (configurable)
- Supply voltage: +9V .. 30V
- Control via SPI and STEP/DIR interface
- Current: 2.6A RMS (4A max.)
- Substepping: 1, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128, 1/256
- Completely software configurable
- Stall detection
- Size: 51x44mm

### 2.3.2 Utilization

The DICE-TMC drivers are controlled by SPI and feature an additional step- and a direction input (DIR) for the synchronous control with other modules. The signals MS1..MS3 on the BAM shield are not used.

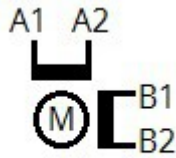
To use the module in a special setup we recommend the pre-configured Arduino library, which you can download with an example program for the first steps on our website.

It is possible to configure the module to lower logic voltages. To do this change the solder jumper on the topside. For more information please use the wiring diagram of the module and the datasheet of TMC2660.



## 2.4 DICE-L6470

Motor connections  
B1, B2, A2, A1



*Picture 5: DICE-L6470  
Stepper driver*

### 2.4.1 Specification

- Logic voltage: +3.3V/ 5V (configurable)
- Supply voltage: +9V .. 35V
- Control via SPI and STEP input
- Up to 3A<sub>RMS</sub>. Up to 7A max.
- Substepping: 1, 1/2, 1/4, 1/8, 1/16, 1/32, 1/64, 1/128
- Completely software configurable
- Sensorless stall detection
- Size: 51x44mm

### 2.4.2 Utilization

The DICE-L6470 drivers are controlled via the SPI and offers an additional step input for synchronous operation. The signals of the MS1..MS3 pins from the BAM shield are not used.

For utilization we recommend to setup the module with an appropriate Arduino library. On your website you can download it and also a suitable code example for the first steps.

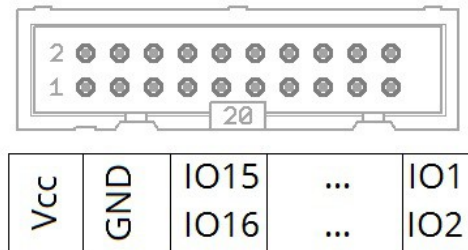
The configuration to lower logic voltages is also possible. For this you have to change the solder jumper on the backside to 3V3 and place a jumper on resistor R7. For further information please refer to the schematics and the datasheet of L6470PD.

## 2.5 DICE-9555

IO port expander with 16 digital signal lines and power output



Picture 6: DICE-9555



Picture 7: DICE-9555 connection

### 2.5.1 Specification

- Logic voltage: +5V, +3V3 (configurable)
- Control via I<sup>2</sup>C-interface (max. 400kHz)
- Up to 50mA per pin and 200mA overall current
- 16 configurable I/O pins
- Interrupt signal for detection of signal changes
- Short circuit protected output voltage (200mA)
- Size: 51x31mm

### 2.5.2 Utilization

The signals MS1..MS3 on the BAM shield are used to define the I<sup>2</sup>C address of the module. The usable address range lies between 32d (100000b) and 39d (100111b).

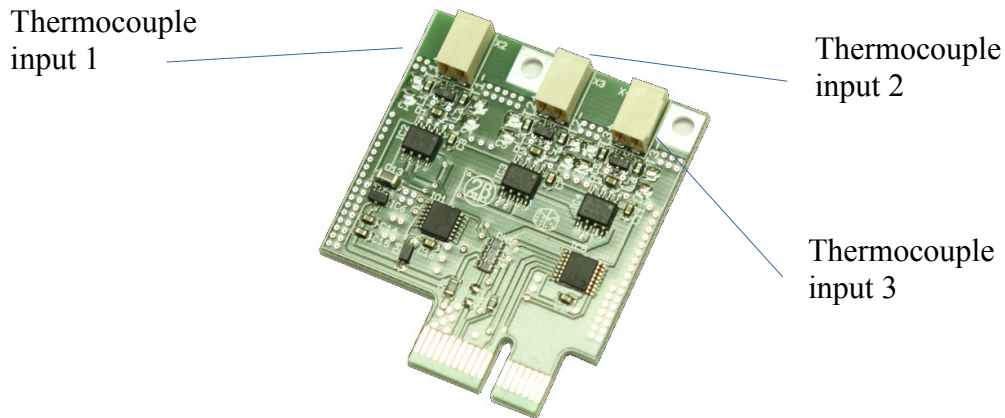
With the first use of this module we recommend the example program from our website.

It is possible to configure the module to lower logic voltages. To do this, change the solder jumper on the top side.

For more information please use the wiring diagram of the module and the datasheet of PCA9555PW.

## 2.6 DICE-TC

Temperature measurement unit for three thermocouples (K type) with SPI interface



Picture 8: DICE-TC

### 2.6.1 Specification

- Logic voltage: +5V, +3V3 (configurable)
- Control via SPI
- 3 channels for thermocouples
- Measurement range: -200°C to 700°C (-328°F to 1292°F)
- Automatic error detection (short, no sensor)
- Size: 51x44mm

### 2.6.2 Utilization

The signals MS1..MS3 on the BAM shield are not used by this module.

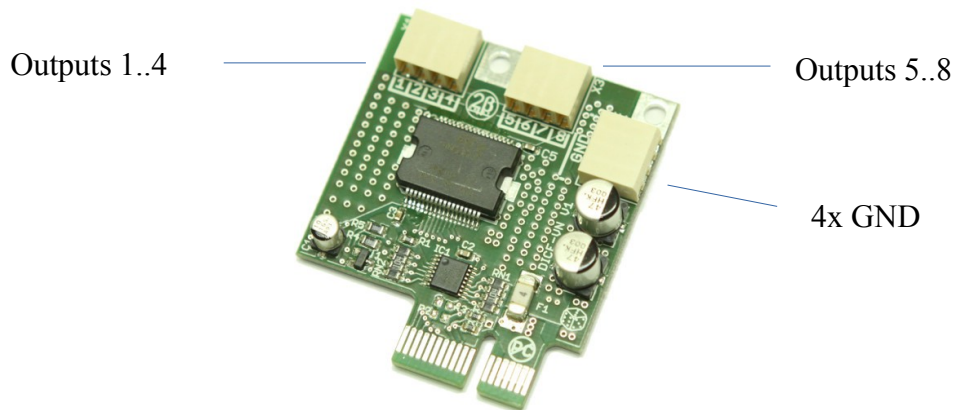
For the reading of each temperature value, the chip select signal of the corresponding channel must be enabled by the corresponding GPIOs. You can find an example and a suitable Arduino library for this module on our website on the product page.

It is possible to configure the board for lower logic voltages. To do this, remove the Zero-Ohm resistor from R3 and place it (or a jumper) on R2.

For more information please use the wiring diagram of the module and the datasheet MAX31855.

## 2.7 DICE-VN

Valve driver with 8 channels for relays and actuators



Picture 9: DICE-VN

### 2.7.1 Specification

- Logic voltage: +5V, +3V3 (configurable)
- Control via I<sup>2</sup>C interface (max. 400kHz)
- Supply voltage: 10,5 - 35V
- Current: 0,7 A per output (4A in sum)
- I<sup>2</sup>C addresses: 112d .. 115d (111000b .. 111011b)
- Size: 51 x 44 mm

### 2.7.2 Utilization

The signals MS1 and MS3 on the BAM-Shield can be used to set the I2C address for the module. After configuring the I2C chip (PCA9538A) in the software, it can set the outputs of the power driver VN808CM-E.

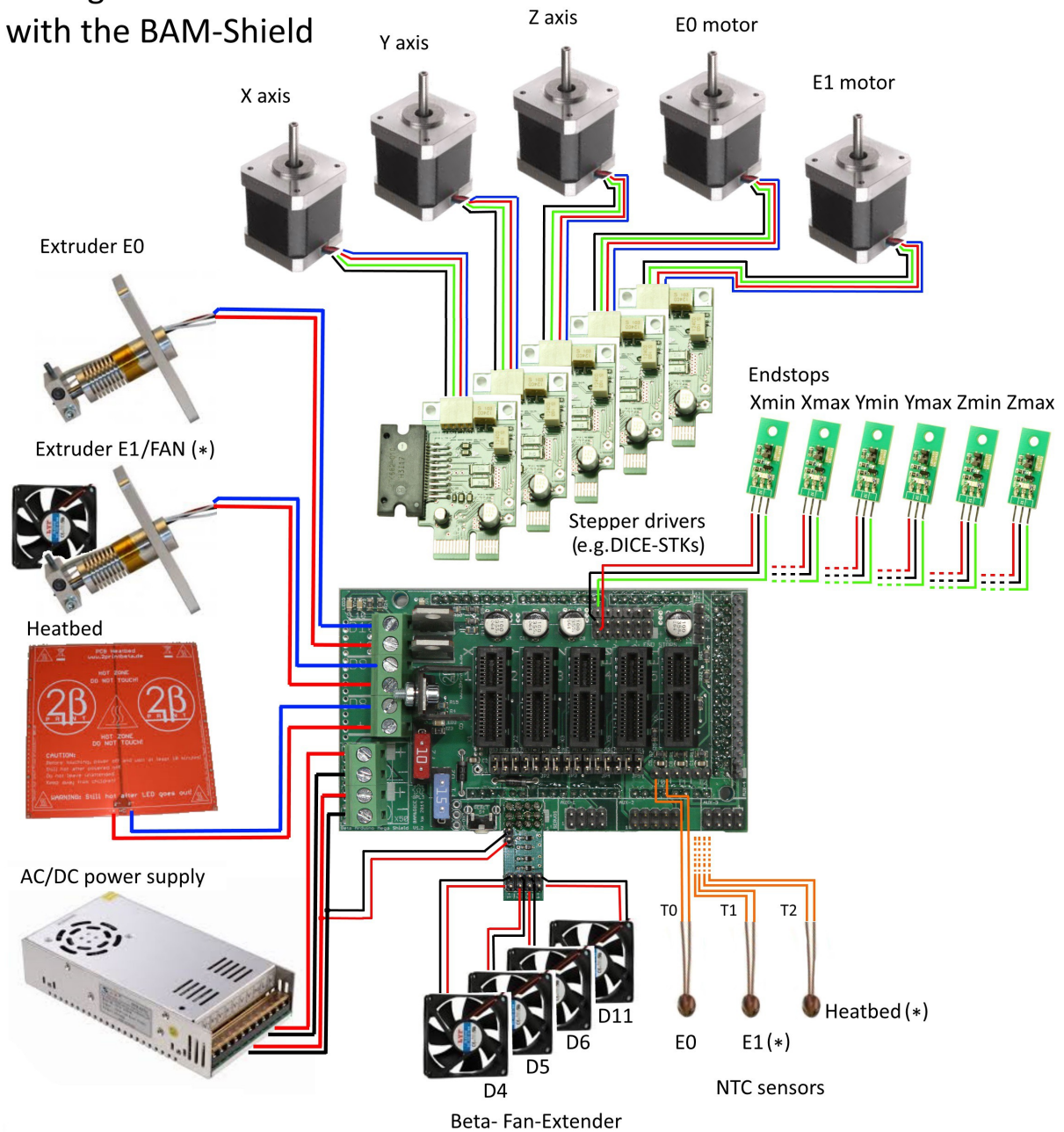
For the first use of this module we recommend the example program from our website.

It is possible to configure this module for lower logic voltages. To do this, change the setting of the solder jumper on the backside. For more information please use the wiring diagram of the module and the datasheets of the components PCA9538A and VN808CM-E.

### 3 Applications

# BAM&DICE

## Wiring of a 3D-Printer with the BAM-Shield



**2PRINTBETA**  
Konrad Meyer  
Copyright (c) 2014

(\*) When used with one extruder, NTC E1 is connected to the heatbed and output E1 is connected to a fan/cooler.

Picture 10: Wiring diagram of BAM&DICE in a 3D printer with the DICE-STK drivers