RASS-R - TRACKAN



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Abstract The RASS-R TRACKAN Module User manual describes the TRACKAN module and the software components of which it is built. TRACKAN interfaces with the RASS-R Data Handler Module (DHM) and therefore you should be familiar with that material. This manual supplements the RASS-R Toolbox manual, and assumes that you are familiar with that material. You should also be familiar with the operation of your computer, your computer's operating system and the Intersoft-Electronics specific hardware for Radar Data I/O.					
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TABLE OF CONTENTS

1.	INT	RODUCTION	
	1.1.	BENEFITS AND POSSIBILITIES OF THE SYSTEM	
2.	GEN	NERAL OVERVIEW	9
	2.1.	TRACKAN AS PART OF RASS-R	
	2.2.	TRACKAN PROCESSING UNIT	
	2.3.	TRACKAN CONFIGURATION	
	2.4.	TRACKAN viewers	
	2.5.	NETWORK OPERATION	
3.	INS	TALLATION, VERIFICATION AND STARTUP	
	3.1.	RUNNING THE DHM BACKGROUND SERVER	
	3.2.	RUNNING THE TRACKAN PROCESSING UNIT	
4.	CON	NFIGURATION	
	41	ADD/EDIT PROCESSING THREADS	13
	4.1.1	1. General tab	
	4.1.2	2. Process tab	
	4.1.3	3. Advanced Tab	
	4.1.4	4. Alarm tab	
	4.1.5	5. Radar's Digest tab	
	4.1.6	6. Distribution tab	
	4.2.	SAVE/LOAD CONFIGURATIONS	
5.	RUN	NNING	
	5.1.	RECALCULATION	
	5.2.	ON-LINE HELP	
	5.3.	QUITTING TRACKAN	
6.	SOF	TWARE COMPONENTS	
	6.1.	TRACKAN MAIN GUI	
	6.2.	CONFIGURATION WINDOW	
	6.3.	RECALCULATION WINDOW	
	6.4.	VIEWERS	
	6.4.1	1. TRACKAN Main Viewer	
	6.4.2	2. TRACKAN History Viewer	
	6.4.3	3. TRACKAN Histogram Viewer	
	6.4.4	4. TRACKAN BDS Register Viewer	



- 6 -

TABLE OF FIGURES

Figure 1-1: TRACKAN data flow	
Figure 2-1: RASS-R Structure	9
Figure 3-1: TRACKAN main GUI in compact mode	
Figure 3-2: TRACKAN main GUI in full mode	
Figure 4-1: TRACKAN configuration window.	
Figure 4-2: Menu bar	
Figure 4-3: Preferences - General tab	
Figure 4-4: Preferences - Process tab	
Figure 4-5: Enabled (Bertem) and Disabled (St-Hubert) thread	
Figure 4-6: Different modes	
Figure 4-7: Radar data format	
Figure 4-8: Track Extrapolate=3	
Figure 4-9: Track Extrapolate=5	
Figure 4-10: Late Track initiation	
Figure 4-11: Viewer display options	
Figure 4-12: Preferences - Advanced tab	
Figure 4-13: Viewer display options	
Figure 4-14: Alarm configuration window	
Figure 5-1: Work in progress information.	
Figure 5-2: Work done information	
Figure 5-3: Recalculation window.	
Figure 6-1: TRACKAN Main GUI in action	
Figure 6-2: TRACKAN Configuration window	
Figure 6-3: TRACKAN Recalculation window	
Figure 6-4: Viewer selection drop down menu	
Figure 6-5: TRACKAN History window	
Figure 6-6: Legend and statistics	
Figure 6-7: Detailed PPI view with label and corresponding ASTERIX data	
Figure 6-8: TRACKAN History window	
Figure 6-9: TRACKAN Histogram window	
Figure 6-10: TRACKAN BDS register window	
Figure 6-11: TRACKAN detailed BDS register window	
Figure 6-12: TRACKAN BDS Register Timeline representation	
Figure 6-13: ELS/EHS detail	

TABLE OF TABLES

Table 1: TRACKAN TPC/IP Ports



- 7 -

CONVENTIONS USED IN THIS MANUAL

The following conventions are used in this manual:

Note: This icon to the left of bold italicized text denotes a note, which alerts you to important information.



Caution: This icon to the left of bold italicized text denotes a caution, which alerts you to the possibility of data loss or a system crash.



Warning: This icon to the left of bold italicized text denotes a warning, which alerts you to the possibility of damage to you or your equipment.



1. Introduction

TRACKAN is a 24h/7d real time radar data monitoring and analysis tool. It calculates Pd and accuracy for individual trajectories. It has full Mode S capabilities and therefore can perform BDS register analysis. TRACKAN uses the RASS-R Data Handler Module (DHM) as radar data I/O. All results are stored in format files.



Figure 1-1: TRACKAN data flow

TRACKAN consists out of a central processing unit and several viewers.

1.1. Benefits and possibilities of the system

- 24/7d radar data monitoring and analysis; no snapshot analysis.
- Real time; immediate response to problems.
- Multiple radar data streams may be processed sequentially.
- The same input data may be processed in different ways and be presented in different views.
- Analysis based on individual trajectories; identify problematic transponders.
- Full Mode S capabilities; includes BDS register analysis.
- Client specific demands are easily integrated. (For example: Status reports and alarm signalling via e-mail, pager, mobile phone messages or www.)
- Multiple history windows for long/short term trend analysis.



2.1. TRACKAN as part of RASS-R



Figure 2-1: RASS-R Structure

The radar data that is converted/corrected/modified by the Data Handler Module is redirected to different components of the RASS-R configuration. One of these RASS-R components is TRACKAN. TRACKAN performs radar data quality analysis.

2.2. TRACKAN processing unit

The TRACKAN processing unit also acts as the main GUI to operate the TRACKAN software. All features are accessed using this GUI. TRACKAN configuration is done through one Configuration window. Radar data analysis results can be presented using different viewers.

2.3. TRACKAN configuration

All configuration of TRACKAN is done using the Configuration window. The Configuration window can be accessed through the TRACKAN GUI. The configuration window allows you to create, edit and enable/disable processing threads in TRACKAN. The last used configuration is always stored and used upon start-up. A configuration includes the desktop layout of the different available windows.



2.4. TRACKAN viewers

TRACKAN has several viewers to present the results of the radar data analysis to the user. Each viewer can be opened multiple times to represent the results in different views. TRACKAN viewers communicate with the TRACKAN processing unit via data containers. A data container is a temporary storage place for the most recent results of the radar data analysis.

2.5. Network operation

TRACKAN uses several TCP/IP ports for different purposes, it is important that these ports are free for use on the target system. The following table shows an overview of the ports used by the TRACKAN.

Port Number	Used by	Usage
5570	TRACKAN	Inter-application communication with DHM

Table 1: TRACKAN TPC/IP Ports



- 11 -

3. Installation, verification and startup

3.1. Running the DHM background server

You might need to be logged on as an administrator or a member of the Administrators group in order to perform some tasks.

In case that the TRACKAN performs analysis on real time data, the Data Handling Module background server needs to be running before the TRACKAN software is started. The Data Handling Module background server can be started using the Windows XP services management console. For more details, please consult the DHM user manual. If the TRACKAN performs analysis on data that was already recorded, it is not necessary to have the DHM running.

3.2. Running the TRACKAN Processing unit

The TRACKAN module can be started from the RASS-R toolbox or the Windows Start Menu. The following window (or similar) will appear.



Figure 3-1: TRACKAN main GUI in compact mode

This is the TRACKAN processing unit and main GUI used to operate the TRACKAN tool.

The last used configuration is automatically loaded upon start-up. By clicking the witton (lower right corner) the TRACKAN main GUI is displayed in full mode.

Work File N Prog	riQC Dev V1.3.0	• II IÞ I	Re	eady to Sta	20 art		
Nb.	Thread	Name	Start	End	Samples	Status	

Figure 3-2: TRACKAN main GUI in full mode



4. Configuration

Configuration of the TRACKAN tool is done with the Configuration window which is evoked by clicking the **I** button in the TRACKAN main GUI. The following window appears:

TRACKAN V1.3.4 Preferences					
2 2 4					
Set Up General Process Advanced A Site BERTEM Longitude 04:37:00.01 [H:M:S] Latitude 50:52:25.88 [H:M:S] Altitude 101 [m] Rev. Time 12.00 [s] Min. Elev. 0.1 [deg] Max. Elev. 45.0 [deg] Min. Range 0.2 [Nm] Max. Range 140.0 [Nm] Min. Alt2000 [ft] Max. Alt. 42000 [ft] Data Source	arm Radar's Digest Distribution DTED Uisibility Offset Angle 0.00 D:\CAMPAIGN-56\General\RC\ screening\BERTEM.hrscr SALADT Visibility Offset Angle 0.0 E:\DATA_RASS_R\ArticQ_Demo\ is_dolm.scr SMGET	[deg] ● <th>Threads</th>	Threads		
D:\DATA RASS-R\BERTEM 080124\RMCDE OPS\ 080125_BERTEM_D6	SCF Cluster State		Cancel OK Apply		

Figure 4-1: TRACKAN configuration window.

Only the first time after installation, no processing threads are defined. All other times, the current processing threads are shown in the configuration window.

A processing thread can be considered a set of parameters that will be applied to a radar data stream in order to perform an analysis. Multiple processing threads can be defined, they will be executed sequentially. One radar data stream can be used in different processing threads to obtain different analysis figures.



4.1. Add/Edit processing threads



A new processing thread can be added by clicking the button. Notice that the "new" thread is added to the list at the right hand side of the configuration window. The settings of the last used thread (or default) are automatically used for the new thread. When multiple threads are defined, use the threads list to select the one of interest by clicking on the corresponding item.

Clicking the button deletes the selected processing thread from the list.

Clicking the button copies the selected processing thread into memory.

Clicking the button pastes the previously copied processing thread into the selected processing thread.

Clicking the we button clears all processing threads from the list. Use the four tabs to navigate through the different thread configuration parameters.

4.1.1. General tab

The general tab contains parameters that are typical for a specific radar data stream: site parameters, radar data source path and coverage maps.

4.1.1.1. Site

The name of the site will be used throughout the TRACKAN tool to identify a specific processing thread. It is advised to choose this name so that it can easily be interpreted.

Longitude and latitude are in the following format; °:MM:SS.ssss, east and north being positive, west and south being negative. The altitude is the altitude of the antenna above mean sea level in WGS 84. The revolution time is an important parameter for the trajectory reconstruction and therefore needs to be accurate. (Choose 1 second for ADS-B data analysis) Minimum elevation, maximum elevation, minimum range, maximum range, minimum altitude and maximum altitude are used to define the general coverage volume boundaries. Target reports located outside this coverage volume are not taken into account during the analysis.



4.1.1.2. Data source

The data source defines the path where TRACKAN retrieves the radar data to be processed. This path should contain an archive folder created by the DHM. The format of the archive files should be the .D6 format. For more information on how to create a .D6 format archive, please consult

the DHM user manual. When you click the open button \bigotimes , a dialog to browse follows. Browse to the folder where all the .D6 files are stored.

Please specify	the Data Source	folder for BERTEM.						? 🔀
Save įn:	6 080125_BER	TEM_D6	~	0	ø	Þ	•	
My Recent Documents Desktop My Documents	080125_0000 080125_0100 080125_0200 080125_0300 080125_0400 080125_0500 080125_0500 080125_0700 080125_0700 080125_0800 080125_1000 080125_1100 080125_1200 080125_1400	<pre>080125_1500 080125_1600 080125_1700 080125_1800 080125_1900 080125_2000 080125_2000 080125_2200 080125_2200 080125_2200 080125_2200</pre>						
My Computer	File <u>n</u> ame:	Index.txt				~]	<u>S</u> ave
	Save as type:	All Files (*.*)				~]	Cancel
								Select Cur Dir

Q.

It is important to select a folder or group of folders that contains the .D6 files. You cannot select an individual .D6 file!

When the path to the Data Source is correctly filled in, you should see all the files in the Recalculation Window. (See paragraph 5.1)

4.1.1.3. DTED

DTED screening maps are calculated by the RASS-R Coverage Map Calculator (CMC). They originate from Digital Terrain Elevation Data with a resolution of 3 Arcsec. For more details on how to create DTED screening maps, please consult the corresponding user manual.

Click the button to browse for a DTED screening map. DTED screening files have a .hrscr extension. The default path for the DTED screening maps in RASS-R is: C:\Program Files\Intersoft Electronics\RASS\Maps\DTED

Use the checkbox is to enable/disable the use of the DTED screening map in the TRACKAN tool. The visibility offset angle value is added to the DTED screening map angle to reduce/increase the DTED screening angles.



4.1.1.4. SALADT

SALADT screening files can be imported in the TRACKAN tool. Click the button to browse for a SALADT screening map. SALADT screening files have a .scr extension. Use the checkbox \blacksquare to enable/disable the use of the SALADT screening map in the TRACKAN tool. The visibility offset angle value is added to the SALADT screening map angle to reduce/increase the SALADT screening angles. *Refer to [2] for further details.*

4.1.1.5. SMGET

SMGET cluster maps can be imported in the TRACKAN tool. Click the button to browse for a SMGET cluster map. Use the checkbox \blacksquare to enable/disable the use of the SMGET cluster map in the TRACKAN tool. The value of the SCF cluster state is mandatory in order to use the SMGET cluster maps.

Refer to the "Mode-S System Map Generator and Extractor Tool" on EUROCONTROL website for further details.

4.1.1.6. Blank Zones

Blank zones are areas defined by the user to be excluded from the analysis. Use the checkbox \square to enable/disable the use of the blank zones in the TRACKAN tool. There is no limit on the number of blank zone within a processing thread. A blank zone is defined as a cubical volume (X min, X max, Y min, Y max, Z min and Z max) within the general coverage volume.

4.1.1.7. Local Screening

A local screening file is a tab separated file containing a table of the local screening angle versus azimuth. (For example if you do not have a DTED or SALADT file)

TRACKAN V1.3.4 Preferences			
222+100	Q		
Set Up Advanced Ali Site BERTEM Longitude 04:37:00.01 [H:M:S] Latitude 00:52:25.88 [H:M:S] Latitude 50:52:25.88 [H:M:S] Altitude 101 [m] Rev. Time 12.00 [s] Min. Elev. 0.1 [deg] Max. Elev. 45.0 [deg] Min. Range 0.2 [Vim] Min. Alt. 2000 [ft] Min. Alt. 2000 [ft] Data Source D: 'DATA RASS-R'\BERTEM Dota'Source D: 'DATA RASS-R'\BERTEM 005124'\RMCDE OPS\ OPS\ Data'Source Dota'Source	Image: Barrier Source Barrier Source DTED Image: Distribution Image: Barrier Source Visibility Offset Angle Image: O.00 [deg] Image: Barrier Source D: \CAMPAICN-S6\General\RC\ screening\BERTEM.hrscr Image: Barrier Source SALADT Image: O.00 [deg] Visibility Offset Angle Image: O.00 [deg] Image: O.00 [deg] SALADT Image: O.00 [deg] Visibility Offset Angle Image: O.00 [deg] Image: O.00 [deg] E:\DATA_RASS_R\ArticQ_Demo\ is_dolm.scr Image: O.00 [deg] SMGET Image: O.00 [deg]	Image: Second secon	
	<u></u>		
		Cancel OK	Apply

Finally, the result can be as follows:

Figure 4-3: Preferences - General tab



4.1.2. Process tab

The processing tab contains parameters that are typical for a specific way of processing the radar data: parameters and exclude list.

TRACKAN V1.3.4 Prefere	ences						
2244							
- Set Up							Threads
General Process Advan	iced Alarm	Radar	s Digest	Distribution			O BERTEM
- Parameters				Exclude List			
Thread	Enabl	ed	×	S Address [hex]	Mode A [oct]		
Timing	Time of Re	cording	~				
Mode	Mode S +	MSSR	~				
BDS Register Analysis	Disabl	ed	~			- 11	
Radar Data Format	ASTER	RIX	~				
Combine Files		[#]					
Minimum Track Length	6	[#]				_	
Track Extrapolate	3	[#]				-	
Extrapolation Window	2	[#]					
Late Track Initiation	3	[#]				-	
Early Track Termination	2	[#]				_	
Maximum Code Absence	1	[#]				-	
Mode S Pd Threshold	98.0	[%]					
Mode A/C Pd Threshold	98.0	[%]				-	
Incorrect Mode C Threshold	100	[m]				T	
							Cancel OK Apply

Figure 4-4: Preferences - Process tab

4.1.2.1. Parameters

A processing **Thread** can be enabled/disabled using the processing selector. A disabled processing thread is not executed during the processing, but the processing parameters remain available for later use.



Figure 4-5: Enabled (Bertem) and Disabled (St-Hubert) thread

When available it is advised to select **Time of Detection** for timing purposes. **Time of Recording** includes the processing and transmission delay and can possibly be less accurate for the analysis.

Use the Mode selector to excluded/included specific types of detection during the analysis:

Parameters	
Thread	Mode S Only
meda	MSSR Only
Timing	PSR Only
Mode	✓ Mode S + MSSR
RDS Register Applysis	Mode S + PSR
bbs Register Analysis	MSSR + PSR
Radar Data Format	Mode S + MSSR + PSR

Figure 4-6: Different modes

Detection types that are excluded are not taken into account during the processing and will be categorized as Non Initiated.

The **BDS Register Analysis** can be enabled/disabled individually for each processing thread. Notice that enabling the BDS register analysis will increase the required processing time.



The Radar Data format can be Asterix or Aircat (2 possibilities).



a number of files in order to have a bigger data set for the analysis. The co

Combine a number of files in order to have a bigger data set for the analysis. The combined files will act as a sliding window each time a new file becomes available.

Because the analysis is trajectory based, it is advised to combine a number of files for a period equal to the average time a target spends in the coverage.

Below the **Minimum Track Length**, a trajectory is not used in the processing.

The individual target reports will be marked as not initialized in the TRACKAN Main Viewer. The **Track Extrapolate** parameter defines the number of extrapolated target reports added at the beginning and the end of each trajectory (for the extrapolation on the beginning of a track, you need to combine files. Otherwise the TRACKAN does not know whether the track really started or it is just present in this .D6 file).

This extrapolation is done using the average speed and heading calculated with the last N target reports, N being the **Extrapolation Window** parameter. The extrapolated target reports are checked against the defined coverage volume and each extrapolated target report is marked as in/out coverage.

Extrapolated target reports marked as in coverage are considered as missed by the radar and are taken into account during the analysis. (Red color in Viewer)



Figure 4-8: Track Extrapolate=3





Figure 4-9: Track Extrapolate=5

Trajectories are marked as Late Track Initiation when the number of in coverage extrapolated target reports added at the beginning of a trajectory exceeds the Late Track Initiation value. Similar, trajectories are marked as Early Track Termination when the number of in coverage extrapolated target reports added at the end of a trajectory exceeds the Early Track Termination value.



Figure 4-10: Late Track initiation

The **Maximum Code Absence** parameter is used to flag trajectories with at least the predefined number of consecutive Mode3/A code, mode C code or Mode S address absences.

Mode S/SSR Trajectories with a Pd below the **Mode S/SSR Pd** threshold are marked below Pd, mode S/SSR Trajectories with a Pd above the Mode S/SSR Pd threshold are marked above Pd. **Incorrect Mode C Threshold** [m]: the height difference between the predicted by the C-code reconstruction and actual C-code for flagging incorrect Mode C Code.



Based on several parameters above, the results can be filtered with the Display functionality in the Viewer. (See paragraph 6.4.1)

All
Below Pd Threshold
Above Pd Threshold
Late Initiation
Early Termination
Late Initiation & Early Termination
Mode A/C/S Code Abscence
Mode A Code Change
Track Number Change
Duplicate Mode S
Duplicate Mode A
Duplicate Track Number
Mixed Track
✓ Split Track

Figure 4-11: Viewer display options

4.1.2.2. Exclude list

Use the exclude list to exclude specific trajectories from the analysis. Trajectories can be identified using a Mode S address [hex] or a Mode A code [oct].



TRACKAN V1.3.4 Preferences	
2 4	
- Set Up	_ Threads
General Process Advanced Alarm Radar's Digest Distribution	
Object Correlator	
Maximum Mode AC Gap 👌 5 [#]	
Maximum Mode S Gap 30 [#]	
Origin Approach Range 👌 10.0 [Nm]	
Random Azimuth Error 0.30 [Deg]	
Range Offset 20.0 [Nm]	
Azimuth Error with Range 0.020 [1/Nm]	
Allowed Speed Jitter Factor 2.5 [#]	
Solit Plots	
Delta Azimuth 1.00 [Deg]	
Delta Range 👌 0.50 [Nm]	
Delta Timestamp () 0.30 [s]	
	Cancel OK Apply

4.1.3. Advanced Tab

Figure 4-12: Preferences - Advanced tab

4.1.3.1. Object correlator

The Object Correlator correlates the individual plots and tries to build tracks again, based on the parameters below. These correlated tracks are visible as the Nr. in the Trackan Viewer. In this way, the TRACKAN can be a reference for analysis for different radar sources which were influence of different tracker systems.

Maximum MODE AC Gap: a parameter setting the maximum SSR trajectory gap bridged by the algorithm

Maximum MODE S Gap: a parameter setting the maximum MODES trajectory gap bridged by the algorithm

Origin Approach Range [NM]: the range band where the next plot can be expected to have any azimuth (applicable for the vicinity of the radar origin when a fast moving target may produce azimuth change of about 180 degrees or greater.)

The following three parameters are designed to model the random azimuth error in general using the formula

$$\sigma_{Az} = \sigma_{Az0} + \alpha (R - R_0)$$

Where

- R0 is the **Range Offset** [NM]
- σ_{Az0} is the **Random Azimuth Error** [deg]
- α is the Azimuth Error with Range [NM]

Allowed Speed Jitter Factor:



4.1.3.2. Split Tracks

Three following parameters are dedicated for detection of the split plots:

- Delta Azimuth [deg]
- Delta Range [NM]
- Delta Timestamp [s]

Tracks that are assigned the label "Split Track" can be displayed with the following menu: (See paragraph 6.4.1)



Figure 4-13: Viewer display options



4.1.4. Alarm tab

The alarm tab contains settings to trigger alarms when certain predefined values are exceeded.

🛃 TI	RACKAN V1.3.4 Prefere	ences							
2	e i) (2							
Set	: Up							Threads	
G	eneral Process Advar	nced Alarm	Radar's Dige	est Distribu	tion			BERTEM	
	Parameter	On/Off	Target [#]	Limit [#]	Target [%]	Limit [%]	Allowed [#]		
	Pd All [%]	On	99.5	99.0	99.5	99.0	3		
	Pd Below [%]	Off					0		
	Pd Above [%]	Off					0		
	##############	#######	#######	######	#######	######	######		
	Reported	Off					0		
	Coasted	Off					0		
	Not Init.	Off					0		
	Linked All	Off					0		
	Linked In	Off					0		
	Linked Out	Off					0		
	Missed	Off	5	10			0		
	##############	#######	######	######	######	######	######		
	All TRKs	Off					0		
	Pd Below	Off					0		
	Pd Above	Off					0		
	Late Init.	Off					0		
	Early Term	Off					0		
	LI & ET	Off					0		
	Code Abs	Off					0 🔻		
								Cancel OK	Apply

Figure 4-14: Alarm configuration window

Switch an individual alarm on/off by typing on or off in the corresponding table entry. Every parameter can have a target value and a limit value, the target value being the expected or desired value, the limit value being the alarm trigger value.

When the target value is greater than the limit value, an alarm is triggered whenever the measured value is smaller than the limit value and this for a consecutive number of times equal to the Allowed value plus one.

Explanation of the theoretical example as in the figure above:

- The target of Pd is 99.5%. When the Pd drops to 99.0% or lower for 4 consecutive scans (3+1), it will trigger an alarm
- The target of Missed targets is 5. When the number of missed targets increases till 10 or higher in one scan, it will trigger an alarm.



4.1.5. Radar's Digest tab

This tab allows the user to accumulate a specific set of trajectories over a longer period. Use the filter/category controls to define a specific set of trajectories and check the box to enable the processing. All the trajectories that comply are stored in a separate file called Digest 1. This file has can be used as a data source in an extra processing thread allowing the automatic processing of the accumulated set of trajectories just as any of the other treads.

4.1.6. Distribution tab

The distribution tab contains the information required to distribute the results of the radar data analysis according to the user's needs. In the current version of the TRACKAN tool, the results

can only be saved to disk. All other possibilities are for future developments. Click the button to browse for a destination path. Use the checkbox \blacksquare to enable/disable the saving of the result to disk. All results are stored in file format.

4.2. Save/Load configurations

A complete configuration can be saved to disk by clicking the 🗹 button. Notice that the TRACKAN main GUI also has this save configuration button. A complete configuration can loaded from disk by clicking the 🚰 button. Notice that the TRACKAN main GUI also has this load configuration button.



5. Running

Running TRACKAN is done by pressing the button in the main GUI. TRACKAN will be idle until a file becomes available from the DHM. When a .D6 file is released by the DHM, processing by TRACKAN will start automatically. This process is repeated every time a new file is made available by the DHM. The processing status and progress can be monitored using the work in progress information.

Work in Progress								
File Name	040917_1600.D6	Status	Processing Radar 1					
Progress								

Figure 5-1: Work in progress information.

(and This means that there is a processing delay on the results equal to the period of one file and that there is an update of the results every period of one file.

Stopping TRACKAN is done by pressing the 🔳 button. TRACKAN will always complete the work in progress before the processing is stopped. TRACKAN will resume with the next available file when the button is pressed.

æ

The combination of stop and restart will automatically clear all results from memory. This means that all history is cleared.

Click the III button to pause TRACKAN. TRACKAN will always complete the work in

progress before the processing is paused. By clicking the **I** button, the next and only the next file will be processed when it becomes available.

Whenever a file is processed, an entry is put in the log. The status of the file is changed to done.

LOG							
Nb.	Thread	Name	Start	End	Samples	Status	^
1	Radar 1	040917_1500.D6	15:37:08	15:37:13	13803	Done	
2	Radar 1	040917_1515.D6	15:37:14	15:37:18	14919	Done	
3	Radar 1	040917_1530.D6	15:37:19	15:37:23	12976	Done	
4	Radar 1	040917_1545.D6	15:37:24	15:37:27	12445	Done	
5	Radar 1	040917_1600.D6	15:37:28	15:37:32	15415	Done	
6	Radar 1	040917_1615.D6	15:37:33	15:37:38	16356	Done	
7	Radar 1	040917_1630.D6	15:37:39	15:37:44	17461	Done	
8	Radar 1	040917_1645.D6	15:37:45	15:37:51	18198	Done	
9	Radar 1	040917_1700.D6	15:37:53	15:37:59	18054	Done	
							\mathbf{v}

Figure 5-2: Work done information.

At any time, all results in memory can be cleared by clicking the 🛄 button. This has the same effect as stopping and starting the TRACKAN tool.



5.1. Recalculation

While TRACKAN is running, any file that already has been processed can be re-processed at any time. Click the button to open the Recalculation window. The following window (or similar) will appear.

🔁 ARTiQC Dev V1.1.1 Recald	ulation 📃 🗖 🔀
(2) Thread	Radar 1
ARTIQC Dev V1.1.1 Recald Inread Path C:\CAMPAIGN-S6\SKYGUIDE 040917_1345 [Done] 040917_1400 [Done] 040917_1415 [Done] 040917_1415 [Done] 040917_1430 [Done] 040917_1430 [Done] 040917_1515 [Done] 040917_1515 [Done] 040917_1515 [Done] 040917_1615 [Done] 040917_1615 [Done] 040917_1615 [Done] 040917_1615 [Done] 040917_1630 [Done] 040917_1745 [Done] 040917_1745 [Done] 040917_1800 [Done] 040917_1815 [Done] 040917_1845 [Done] 040917_1945 [Done] 040917_1945 [Done] 040917_1945 [Done] 040917_1945 [Done] 040917_1945 [Done] 040917_1945 [Done] 040917_1945	atlation Image: Change [RESULTS\GV2S Select All Done To Do None Change Change to "Done" Change to "To Do" Update Add Recalculated results to current analysis (history) Count Total 482 [#] Done 482 [#] Selected 0 [#] Selected 0 [#] Selected 0 [#] Done 482 [#] Selected 0 [#]
040917_2030 [Done] 040917_2045 [Done] 040917_2100 [Done] 040917_2115 [Done]	Done 2445.78 [Mb] Selected 0.00 [Mb]
	Cancel OK Apply

Figure 5-3: Recalculation window.

The thread selector can be used to select a specific thread for the recalculation. The path to the archive and a list of the available files is displayed. All files that are already processed are indicated by [Done]. Select the file of interest or shift-click for selecting multiple files. Alternatively, use the row of select buttons to define a specific selection range. Use the Change to "To Do" button to change the status of the selected files from [Done] to [To Do]. Use the Change to "Done" button to change the status of the selected files from [To Do] to [Done].

Uncheck the Update checkbox when the results of the recalculation do not need to be added to the current analysis results (history).



5.2. On-line help

Clicking the button opens the on-line user manual. The on-line user manual is in PDF format.

Clicking the Dutton opens the context help window. Position the cursor over a control to get context help for that control.

5.3. Quitting TRACKAN

Click the D button to quit TRACKAN. The current configuration will automatically be stored and re-used as default configuration next time. All open window will be closed automatically and their layout is saved as part of the configuration.

The layout (position and settings) of all the open TRACKAN windows will be stored as part of a configuration. The content of the windows is NOT part of a configuration.



6. Software components

This chapter provides an overview of all the available software components in TRACKAN. Some of them have already been described in the paragraphs above.

6.1. TRACKAN Main GUI

TRACKAN V1.3.4								
Nb.	Thread	Name	Start	End	Samples	Status	^	
1	BERTEM	080125_0000.D6	07:31:38	07:31:42	15103	Done		
2	BERTEM	080125_0100.D6	07:31:44	07:31:48	14608	Done		
3	BERTEM	080125_0200.D6	07:31:50	07:31:56	16699	Done		
4	BERTEM	080125_0300.D6	07:31:58	07:32:06	23644	Done		
							-	
	<u> </u>						~	

Figure 6-1: TRACKAN Main GUI in action

The use of the TRACKAN main GUI is described in paragraph 5.

6.2. Configuration window

TRACKAN V1.3.4 Preferences				
2244 + 1 68 0	0			
_ Set Up				Threads
General Process Advanced Ala	rm Radar's Digest Distribution			© BERTEM
Site			Blank Zones 🗹	
BERTEM	Visibility Offset Angle	[deg]	+ 🗶 🖻 🛍 🚥	
Longitude 04:37:00.01 [H:M:S] Latitude 50:52:25.88 [H:M:S]	D: \CAMPAIGN-S6\General\RC\ screening\BERTEM.hrscr		X Min () 0.0 [NM]	
Altitude 101 [m]		Pa	X Max 🕘 0.0 [NM]	
Rev. Time 12.00 [s]			Y Min 🖉 0.0 [NM]	
Min. Elev. 0.1 [deg]	SALADT		Y May A 0.0 DMI	
Max. Elev. 45.0 [deg] Min. Range 0.2 [Nm]	Visibility Offset Angle 0.0	[deg]	Z Min () 0 [FT]	
Max. Range 140.0 [Nm]	E:\DATA_RASS_R\ArticQ_Demo\		Z Max / 0 [FT]	
Min. Alt2000 [ft]				
Max. Alt. 42000 [ft]				
Data Source				
D:\DATA RASS-R\BERTEM 080124\RMCDE OPS\ 080125_BERTEM_D6	SCF Cluster State			
ম		R	2	
				Cancel OK Apply

Figure 6-2: TRACKAN Configuration window

The use of the TRACKAN configuration window is described in paragraph 4.



6.3. Recalculation window

TRACKAN V1	.3.4 Recalcu	ulation
Thread		BERTEM
Path D:\DATA RAS 080125_0000 080125_0100 080125_0200 080125_0200 080125_0200 080125_0500 080125_0500 080125_0500 080125_0500 080125_0500 080125_1000 080125_1000 080125_1200 080125_1500 080125_1500 080125_1500 080125_1500 080125_1200 080125_1200 080125_1200 080125_1200 080125_1200	S-R\BERTEM [EM_D6 [Done] [Done] [Done] [Done] [Done] [To D0] [To D0	080124\RMCDE OPS\ Select All Done To Do None Change Change to "Done" Change to "To Do" Update Add Recalculated results to current analysis (history) Count Total 24 [#] To Do 19 [#] Done 5 [#] Selected 0 [#] Size Total 661.24 [Mb] To Do 615.33 [Mb] Done 45.91 [Mb] Selected 0.00 [Mb]
		Cancel OK Apply

Figure 6-3: TRACKAN Recalculation window

The use of the TRACKAN recalculation window is described in paragraph 5.

6.4. Viewers

The last processed set of files for each processing thread is available for real time viewing and analysis. They remain available until the next set of files is processed. This way the latest up-to-date information is always ready for viewing and analysis. Several viewers are at the disposal of the user to monitor and verify these analysis results in real time.

Each type of viewer can be opened multiple times with different settings. This allows the user to represent the results in different ways.

All Viewers can be launched from the TRACKAN Main GUI by using the 🕮 drop down menu.



Figure 6-4: Viewer selection drop down menu

The following paragraphs explain the use of these viewers in more detail.





6.4.1. TRACKAN Main Viewer

The TRACKAN Main Viewer always displays the latest processed data set for a specific processing thread. Whenever a new data set is processed, the TRACKAN Main viewer is updated automatically.

There is an entry in the table for every individual trajectory encountered in the analysis. Individual trajectories can be enabled/disabled by right clicking the trajectory of interest and selecting **Enable/Disable** from the popup menu. The symbol in front of the trajectory will change from \checkmark to \circ when it becomes disabled. Disabled trajectories are not shown in the PPI display.

The content of the table can be customised by the user. The table can be sorted in ascending/descending order by clicking on the corresponding column header in the table. The table can be **filtered** using the Filter function. A specific set of transponders can be selected by using the **Display selector**. The customised table/PPI content can be exported to a .csv/.bmp

formatted file by clicking the 🕮 button and selecting the appropriate menu item.



Figure 6-5: TRACKAN History window



Trackan

The PPI display below the table show the table content in a graphical representation. Only trajectories listed in the table are drawn in the PPI display. The trajectory corresponding with the selected entry of interest in the table is colored blue in the PPI display. The TRACKAN Main Viewer legend is as follows:

- Coasted : coasted target reports (= miss reported by the radar)
- Selected : selected trajectory
- Not Init. : not initialized (meaning assigned by TRACKAN, based on minimum trajectory length not reached)
- Linked : reported target in coverage linked to trajectory (meaning assigned by TRACKAN, based on object correlator parameters)
- Lout: reported target out coverage linked to trajectory (meaning assigned by TRACKAN, based on coverage file)
- Missed : Missed in coverage by the radar and added by the TRACKAN analysis.
- Out Cov.: Missed out coverage by the radar and added by the TRACKAN analysis.

Use the corresponding checkboxes \square to add/deleted specific data sets from the PPI display.

	×* 🗩 +	Hor	ne	+	L	ock		Colo	ur	
<u> </u>	Y 🖉 🗙	Zoo	m	-	Si	ingle	-	Lab	el	
				Coa	sted	⊡[8	94 / 1.	4	
_				Sele	cted	Γ	0/0			
Rep	orted 627	1-∎	Not Init. 🗹				804/1.3			
				Linke	ed	Γ	61	044 / 9	7.3	
			L	- 🗖 🤇	Dut	⊡[71	.34 / 11	.4	
				Miss	ed	⊡[205		
Not Rep	orted 29	59 -		Out	Cov.	₫[2754		
Used	53910	[#]	Va	alid &	Corr.	A	99	.668	[%]	
Pd	99.621	[%]	Valio	d & In	Corr.	A	0.	000	[%]	
Az STD	0.043	[deg]	Va	alid &	Corr.	c	99	.351	[%]	
Ra STD	17.412	[m]	Vali	d & Ir	ncorr.	c	0.	312	[%]	

Figure 6-6: Legend and statistics

Explanation about the different figures:

- The number of reported targets is split in number of coasted, not initiated and linked targets, both expressed in absolute and per cent value: 62742=894+804+61044 or 100%=1.4%+1.3%+97.3%
- 7134 targets or 11.4% from 62742 reported targets are linked but out of coverage.
- 62742-(894+804+7134)=53910 are used for the Pd calculation
- Used-missed=53910-205 gives a Pd of 99.621% from 53910.

If the number of used targets is zero (because for example all targets are assumed as out of coverage) no statistics will be calculated.



Click the Home button to view the full scale PPI.

Click the **Zoom** button to automatically zoom to the selected trajectory +10%, or **+**/- to

zoom stepwise. Click the Single button to display the selected trajectory only. Click the

Lock button to lock the cursor onto the selected trajectory. Click the Colour button to give

each trajectory a different color. Click the Label button to display a label attached to the cursor. Press the space bar to rotate the label content.

Click \times to enable the cursor, click the + button to center the cursor and m to drag the PPI view.

Click Z to enable the view select window. Use the standard Labview menus for scaling, precision, color etc.



Figure 6-7: Detailed PPI view with label and corresponding ASTERIX data





6.4.2. TRACKAN History Viewer

Figure 6-8: TRACKAN History window

The top row selectors allow any parameter from any processing thread to be displayed in the history window. Every set of processed files adds an entry in the histogram window. One history window can display up to three different parameters from on processing thread or one parameter from three different processing threads or any combination of the above. Whenever alarm levels are defined in the configuration window (see paragraph 4) they will be displayed in the history window as a green (target value) and a red (limit value) line.

and

\square Alarm settings are only applicable for the top row selectors. This means that there can only be one alarm setting active for each history window.

When an alarm stage is reached, the history window will turn red and the title bar will flash as long as the alarm stage is maintained. When the alarm stage is released, the window will stay red as an indication that an alarm stage has been encountered. Click the **reset** button to reset the alarm conditions.

The content of the history window can be logged to disk (.csv format) by checking the **Distribution** box. Every increment in the history window is added to log file. This way, the log file is always updated with the latest information. Switching on the log function will allow the user to browse for a destination file.



6.4.3. TRACKAN Histogram Viewer



Figure 6-9: TRACKAN Histogram window

The top row selectors allow any parameter from any processing thread to be displayed in the histogram window. On the right hand side the statistics calculated from the histogram are shown. A cursor can be put on the histogram to query specific values in more detail.

6.4.4. TRACKAN BDS Register Viewer

Whenever Mode S data is available (ASTERIX cat048), the BDS register analysis is automatically enabled. Select the thread of interest with the thread selection menu.

	FRACKAN V1.3	.4 BDS Registe	r												
	Current File(s) D:\DATA RASS-R\BERTEM 080124\RMCDE OPS\080125_BERTEM_D6\080125_0800 <> 080125_0800														
	Thread Display														
	À			A			_				- 11	a ar			
11.	7	BERTEM	_	None	conta	ins						Show	All		
	r. S Address •	Aircraft ID	BDS 10		BDS 17		BDS 1D		ACAS RA		BDS	640	BDS 50	BDS 60	<u>^</u>
1	C00800	TSC410	10 01 00 8	80 E6 00 00	FA 81 01 00 0	00 00 00	00 00 00 00	00 00 00	***		89 (C8 00 30 A4 00 00	90 78 7D 1E 21 C4 76	C6 19 B3 16 FE F	F DE 📄
2	C0054E	ACA846	10 01 00 8	80 F6 00 00	FA 81 03 00 0	00 00 00	00 00 00 00	00 00 00	***		C4 (66 23 30 A8 00 00	84 D5 13 3E E0 44 DE	A7 BA 13 31 20 1	4 00
3	AE145C	RCH6158.	10 01 00 0	00 B6 00 00	10 00 00 00 00	00 00 00	00 00 00 00	00 00 00	***		***		***	***	
4	AE07C3	ESSO75	10 01 00 0	00 A6 00 00	00 00 00 00 00	00 00 00	00 00 00 00	00 00 00	***		***		***	***	
5	AE01B3	HOOK63.0	10 01 00 0	00 A6 00 00	00 00 00 00 00	00 00 00	00 00 00 00	00 00 00	***		***		***	***	
6	ADFE63	ROGUE.32	10 01 00 0	00 B6 00 00	10 00 00 00 00	00 00 00	00 00 00 00	00 00 00	***		***		***	***	
7	AC6C4A	N9UP	10 01 00 1	10 B6 00 00	02 00 00 00 00	00 00 00	00 00 00 00	00 00 00	***		***		***	***	
8	AAA6D3	***	***		***		***		***		***		***	***	
9	AA7D5D	UAL945	10 01 00 8	30 F6 00 00	FB 81 03 00 00	00 00 00	00 00 00 00	00 00 00	***		C6 :	50 00 00 00 00 00	80 3C B5 32 C0 04 EA	E7 1A 2D 34 60 1	401
1	0 AA4860	COA	10 01 00 8	30 E6 00 00	FA 81 03 00 0	00 00 00	00 00 00 00	00 00 00	***		BA 9	9D D4 F0 AA 00 00	FF FD DD 32 7F FC F2	EF AA 7D 34 20	14 03
1	1 A9553B	N700GY	10 00 06 8	30 A0 00 00	02 80 00 00 00	00 00	00 00 00 00	00 00 00	***		00 0	00 00 00 00 00 05	***	***	
1	2 A95169	N7RX	10 01 06 8	30 A6 00 00	0281010000	00 00 00	00 00 00 00	00 00 00	***		AE 8	E5 77 30 A8 00 04	FF FD FF 2F 60 04 D4	F1 0A 5D 2C 60 0	04 00
1	3 A90A17	COA	10 01 00 8	30 F6 00 00	FA 81 03 00 0	00 00 00	00 00 00 00	00 00 00	***		938	BC 9C 70 AA 00 00	FF 73 23 21 BF F4 7F	98 19 89 19 20 0	C 00
1	4 A8CBAC	FYG851E.	10 01 06 8	30 A6 00 00	0281010000	00 00 00	00 00 00 00	00 00 00	***		938	3C 9C 70 A8 00 04	FF 95 3B 32 C0 04 B5	A9 CA 53 24 7E	10 00
1	5 A8B760	COA	10 01 00 8	30 F6 00 00	FA 81 03 00 0	00 00 00	00 00 00 00	00 00 00	***		BA 9	9D D4 F0 AA 00 00	FF DC 71 36 3F FC F3	E5 9A 7D 34 3F F	402
1	6 A7D6B4	00000000	10 01 00 8	30 B6 00 00	20 00 00 00 00	00 00 00	00 00 00 00	00 00 00	***		***	:	***	***	
1	7 A781A4	***	10 01 00 0	00 02 00 00	00 00 00 00 00	00 00	00 00 00 00	00 00 00	***		***		***	***	
1	8 A6C4D3	NWA60	10 01 00 8	80 E6 00 00	FA 81 C1 00 0	00 00 0	00 00 00 00	00 00 00	***		85 E	E0 00 32 36 00 00	80 30 AD 1E E0 04 74	83 99 BF 16 BF 2	FE3
1	9 A698E0	WTA013	10 01 00 8	80 A6 00 00	32 00 00 00 00	00 00	00 00 00 00	00 00 00	***		***		***	***	
2	0 A6906E	8072	10 01 00 8	80 E6 00 00	FA 81 01 00 0	00 00	00 00 00 00	00 00 00	***		CE :	20 00 30 A8 00 00	80 3C B9 32 3F FC E0	E6 29 D7 30 FF F	7 FF
2	1 A62A4F	N497CD	10 00 06 8	30 A0 00 00	028100000	00 00	00 00 00 00	00 00 00	***		00 0	00 00 00 00 00 05	00 1A DD 11 00 00 00	***	<u>×</u>
			649 /	96.72 %	BDS 10	BDS 17	BDS 1D	BDS 40	BDS 50	BDS 60	BDS	Content Error	I048/230 COM Classifica	tion ELS/EHS	
		- BDS 10	650 /	96.87 %	ELS Trans	sponder (Classification		Cour	it [#] / [%]		EHS Transponder	Classification	Count [#] / [%	
		BDS 17	650 /	96.87%	Aircraf	t ID pres	ent		649	/ 96.72 %		O BDS 50 True Tr	ack Angle	526 / 78.39 %	
		000 1/	000 7	50.07 10		present			650	/ 96.87 %		BDS 50 Ground	Speed	530 / 78.99 %	
		BDS 1D	650 /	96.87 %		ACAS R	A available		491	/ 73.17 %		O BDS 50 Track A	ngle Rate	457 / 68.11 %	
N	1ode S 671 -	-		0.15.9/		SI availa	able		634	/ 94.49 %		BDS 60 Magnet	ic Heading	542 / 80.77 %	
		- ACAS RA	1 /	0.15 %	0 BDS 17	present			650	/ 96.87 %			ed Airspeed	542 / 80.77 %	
		- BDS 40	562 /	83.76 %		itatus av	ailable		671	/ 100.00 %		BDS 60 Vertical	Rate	542 / 80.77 %	
		- BDS 50	548 /	81.67 %	Elemen	tary Surv	veillance Com	pliance	473	/ 70.49 %		Enhanced Surv	eillance Compliance	390 / 58.12 %	
		BDS 60	542 /	80.77 %											×

Figure 6-10: TRACKAN BDS register window

There is an entry in the table for every Mode S address encountered in the analysis.



The latest reported aircraft ID, BDS10, BDS17, BDS1D, ACAS RA, BDS40, BDS50 and BDS60 are displayed in the table. This information is only available when it is present in the ASTERIX cat048 radar data stream.

The content of the table can be customised by the user. The table can be sorted in ascending/descending order by mode S address or aircraft ID by clicking the corresponding column header. The table can be filtered using the value of the mode S Address or the content of the aircraft ID using the Filter function. Use a point (.) as wild card for the filter value. Specific set of transponders can be shown or hidden by using the two Display selectors. The customised table content can be exported to a .csv formatted file by clicking the 📾 button.

The detailed content of the BDS registers for a specific transponder (Mode S address) can be displayed by right clicking on the entry of interest. A popup menu appears that allows the user to open a BDS register float window containing the detailed and translated BDS register content for that specific Mode S address.



Figure 6-11: TRACKAN detailed BDS register window

Click one of the 🗈 buttons to view more details of the BDS register content or right click on the window and select "open all" from the popup menu. From the same popup menu, the detailed BDS register content of an individual transponder can be exported to a .csv formatted file.

Use the \mathbb{B} button to lock the window content to a specific transponder. Alternatively, the window content will be updated according to the selection (blue line). Multiple detailed BDS content windows can be opened simultaneously.

By selecting the Timeline presentation, an overview of all the BDS register activity for the selected Mode S address is given in a single window. Use the cursor in the top left graph to select a specific BDS register activity.





Figure 6-12: TRACKAN BDS Register Timeline representation

Below the table a general overview of the BDS register content is displayed. Each time two values are presented: absolute [#] and relative [%]. Use the tabs to get more detailed information for each of the BDS registers and their content.

6.4.4.1. ELS/EHS

This tab calculates the percentage of Elementary Surveillance (ELS) compliant and Enhanced Surveillance compliant (EHS) Mode S transponders. The ELS/EHS criteria are according to the latest EUROCONTROL rules on ELS/EHS.

BDS 10 BDS 17 BDS 1D BDS 40 BDS 50 BDS 60 BDS Content Error I048/230 COM Classification ELS/EHS								
ELS Transponder Classification	Count [#] / [%]	EHS Transponder Classification	Count [#] / [%]					
Aircraft ID present	74 / 56.49 %	🗆 BDS 50 Roll Angle	3 / 2.29 %					
BDS 10 present	126 / 96.18 %	BDS 50 True Track Angle	3 / 2.29 %					
📼 BDS 10 ACAS RA available	115 / 87.79 %	BDS 50 Ground Speed	3 / 2.29 %					
BDS 10 SI available	30 / 22.90 %	BDS 50 Track Angle Rate	3 / 2.29 %					
📼 BDS 17 present	23 / 17.56 %	📼 BDS 60 Magnetic Heading	11 / 8.40 %					
Flight Status available	131 / 100.00 %	BDS 60 Indicated Airspeed	11 / 8.40 %					
_		BDS 60 Vertical Rate	11 / 8.40 %					
Elementary Surveillance Compliance	26 / 19.85 %		_					
		Enhanced Surveillance Compliance	3 2.29% 💌					

Figure 6-13: ELS/EHS detail

These rules can be loosened or tightened by double clicking on the corresponding table entry. Disabled rules are not taken into account for the calculations.



ELECTRONICS

GLOSSARY

Α	ACP ARP Asterix Asterix Data Block Asterix Record	Azimuth Count Pulse. Azimuth Reference or Reset Pulse. All Purpose Structured Eurocontrol Surveillance Information Exchange Unit of information seen by the application as a discrete entity by its contents. A Data block contains one or more Record(s) containing data of the same category. A collection of transmitted Data Fields of the same category.
B	Baud	Unit of signal frequency in signals per second. Not synonymous with bits per second since signals can represent more than one bit. Baud equals bits per second only when the signal represents a single bit.
C	CAT001 CAT002 CAT034 CAT048	Monoradar Data Target Reports, from a Radar Surveillance System to an SDPS (plots and tracks from PSRs, SSRs, MSSRs, excluding Mode S and ground surveillance) Monoradar Service Messages (status, North marker, sector crossing messages) Monoradar Service Messages, next version of CAT002 Monorader Data Target Reports, next version of CAT001
D	Cumulative Distribution D6 Data bits DCE EHS ELS DTE	The probability that a variable takes a value less than or equal to a certain value Intersoft Electronics internal data Radar data format, plot or track based. In data communications, the number of bits used to send each character, not including any added timing or error checking bits Data Communications Equipment. The local and/or remote modem. A DCE is usually connected to a DTE. Enhanced Surveillance Elementary Surveillance Data Terminal Equipment. The computer or terminal, either local (yours), or the remote (the one you're communicating with). A DTE is usually connected to a
Е	DTED	DCE. Digital Terrain Elevation Data
F	EDR EDR V2 Ethernet	Intersoft Electronics internal data format for record based data. Also stands for Extended Data Recorder, a device for generating and capturing serial data. Second version of the EDR format. A network specification developed by DEC, Intel, and Xerox which provides anywhere from 10 megabits to 1000 megabits per second transmission speeds.
г н	Flow control	A method of controlling when information is sent
III	Hex	Hexadecimal. 16 based numbering system ranging from 0 to F
м	I/O	Input/Output. The transfer of data to or from a computer system involving communications channels, operator interface devices, and/or data acquisition and control interfaces.
NI O	MB Mode S	Megabytes of memory. Selective addressing secondary surveillance radar technique
O P	Oct	Octal value. 8 based numbering system ranging 0 to 7
	Path	A path can be described as a file's address on your file system, describing where the file lives: An absolute path gives the complete path, starting at the root directory, or the very top of the filesystem; A relative path looks for a file from the directory you are currently in down.
ĸ	Record RS323, RS422	A collection of data forming a complete message. The Electronics Industry Association (EIA) has produced standards for RS232 and RS422 that deal with data communications.

S		
	SAC	System Area Code, used in Asterix data.
	SALADT	Used by SASS-C Tool for visibility computation
	SASS-C	Surveillance Analysis Support System for ATC-Centre
	SIC	System Identification Code, used in Asterix data.
	SMGET	Mode-S System Map Generator and Extractor Tool
Т		
	Timeout	A timeout occurs when a device has waited too long for another device to send or receive a transmission.
U		
	UAP	User Application Profile, used in Asterix data for assigning Data Items to Data Fields.
	UDP	User Datagram Protocol. A connectionless, unreliable Internet protocol.
	UTC	Coordinated Universal Time.
W		
	WGS-84	World Geodetic System 1984



REFERENCED DOCUMENTS

Reference	Document
[1]	Coverage Map Interface Control Document for POEMS stations
[2]	SASS-C user manual



INDEX

Exclude List15
G
General Overview9 TRACKAN as part of the RASS-R9 TRACKAN Configuration9 TRACKAN Processing Unit9 TRACKAN Viewers9
Glossary28
H
Help18Histogram
I
Installation
L
Label22Legend21Load Configurations16Lock22
0
operation9 Overview See General Overview

Parameters 14	
possibilities	
PPI	
<i>Q</i>	
Quit18	
<i>R</i>	
Recalculation 17	
Running 17	
S	
SALADT 13	
Save Configurations16	
Service 11	
Single22	
Site12	
SMGET 13	
Software components 19	
BDS Register Window 24	
Configuration Window 19	
Histogram Window23	
History Window23	
Main GUI 19	
PPI Window20	
Recalcualtion Window 19	
Viewers	
<i>T</i>	
TRACKAN Processing Unit . 11	
Z	
Zoom 22	



--A--

Add threads	
Alarm	
Limit	
Traget	
B	

background server	11
BDS Register	24
Benefits	8
Blank Zones	13

--*C*--

Color
Configuration12
Alarm 15
Blank Zones 13
Data Source13
Distribution16
DTED13
Exclude List 15
Parameters14
SALADT13
Site
SMGET
CSV Format8, 16, 21, 23, 24, 25
D

Data Source Distribution DTED	13 16 13
<i>E</i>	
Edit threads	12
ELS/EHS	26