

1 INTRODUCTION

Purpose

The ADSP-21160 SHARC DSP Hardware Reference provides architectural information on the ADSP-21160 Super Harvard Architecture (SHARC) Digital Signal Processor (DSP). The architectural descriptions cover functional blocks, busses, and ports, including all features and processes they support. For programming information, see the *ADSP-21160 SHARC DSP Instruction Set Reference*.

Audience

DSP system designers and programmers who are familiar with signal processing concepts are the primary audience for this manual. This manual assumes that the audience has a working knowledge of microcomputer technology and DSP-related mathematics.

DSP system designers and programmers who are unfamiliar with signal processing can use this manual, but should supplement this manual with other texts, describing DSP techniques.

All readers, particularly system designers, should refer to the DSP's data sheet for timing, electrical, and package specifications. For additional suggested reading, see [“For More Information About Analog Products” on page 1-22](#).

Overview—Why Floating-Point DSP?

A digital signal processor's data format determines its ability to handle signals of differing precision, dynamic range, and signal-to-noise ratios. Because floating-point DSP math reduces the need for scaling and probability of overflow, using a floating-point DSP can ease algorithm and software development. The extent to which this is true depends on the floating-point processor's architecture. Consistency with IEEE workstation simulations and the elimination of scaling are two clear ease-of-use advantages. High-level language programmability, large address spaces, and wide dynamic range allow system development time to be spent on algorithms and signal processing concerns, rather than assembly language coding, code paging, and error handling. The ADSP-21160 is a highly integrated, 32-bit floating-point DSP that provides many of these design advantages.

ADSP-21160 Design Advantages

The ADSP-21160 is a high-performance 32-bit DSP for medical imaging, communications, military, audio, test equipment, 3D graphics, speech recognition, motor control, imaging, and other applications. This DSP builds on the ADSP-21000 Family DSP core to form a complete system-on-a-chip, adding a dual-ported on-chip SRAM, integrated I/O peripherals, and an additional processing element for Single-Instruction-Multiple-Data (SIMD) support.

SHARC is an acronym for Super Harvard Architecture. This DSP architecture balances a high performance processor core with high performance buses (PM, DM, IO). In the core, every instruction can execute in a single cycle. The buses and instruction cache provide rapid, unimpeded data flow to the core to maintain the execution rate.

Figure 1-1 shows a detailed block diagram of the processor, illustrating the following architectural features:

- Two Processing Elements (PE_x and PE_y), each containing a 32-Bit IEEE floating-point computation units—multiplier, ALU, Shifter, and data register file
- Program sequencer with related instruction cache, interval timer, and Data Address Generators (DAG1 and DAG2)
- Dual-ported SRAM
- External port for interfacing to off-chip memory, peripherals, hosts, and multiprocessor systems
- Input/Output (IO) processor with integrated DMA controller, serial ports, and link ports for point-to-point multiprocessor communications
- JTAG Test Access Port for emulation

Figure 1-1 also shows the three on-chip buses of the ADSP-21160: the Program Memory (PM) bus, Data Memory (DM) bus, and Input/Output (IO) bus. The PM bus provides access to either instructions or data. During a single cycle, these buses let the processor access two data operands (one from PM and one from DM), access an instruction (from the cache), and perform a DMA transfer.

The buses connect to the ADSP-21160's external port, which provides the processor's interface to external memory, memory-mapped I/O, a host processor, and additional multiprocessing ADSP-21160s. The external port performs bus arbitration and supplies control signals to shared, global memory and I/O devices.

Figure 1-2 illustrates a typical single-processor system. The ADSP-21160 includes extensive support for multiprocessor systems as well. [For more information, see “Multiprocessor \(DSPs\) Interface” on page 7-91.](#)

ADSP-21160 Design Advantages

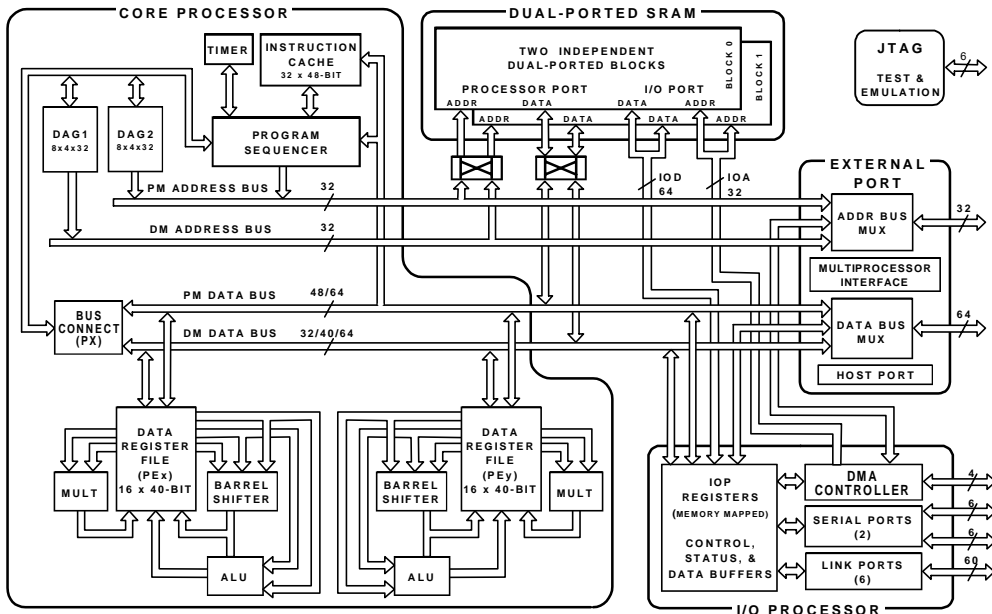


Figure 1-1. ADSP-21160 SHARC Block Diagram

Further, the ADSP-21160 addresses the five central requirements for DSPs:

- Fast, flexible arithmetic computation units
- Unconstrained data flow to and from the computation units
- Extended precision and dynamic range in the computation units
- Dual address generators with circular buffering support
- Efficient program sequencing

Fast, Flexible Arithmetic. The ADSP-21000 Family processors execute all instructions in a single cycle. They provide both fast cycle times and a complete set of arithmetic operations. The DSP is IEEE floating-point

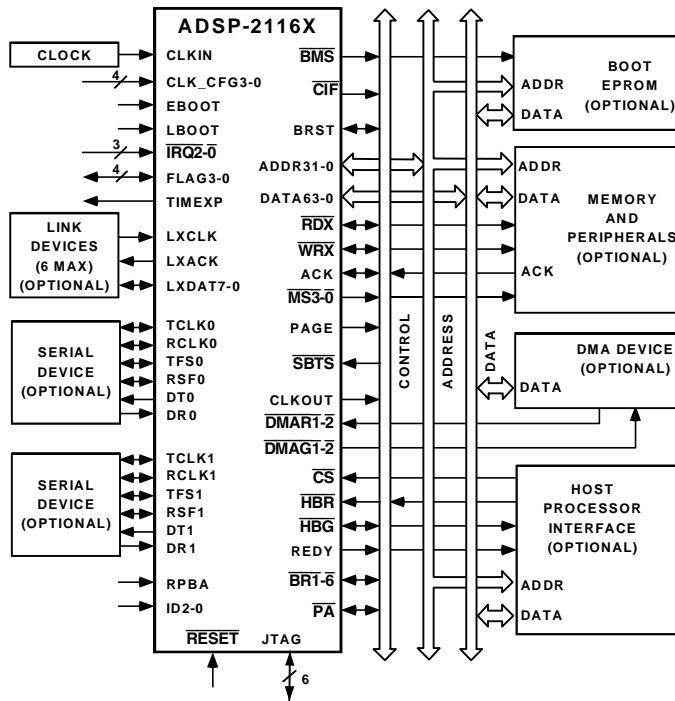


Figure 1-2. ADSP-21160 System

compatible and allows either interrupt on arithmetic exception or latched status exception handling.

Unconstrained Data Flow. The ADSP-21160 has a Super Harvard Architecture combined with a 10-port data register file. In every cycle, the DSP can write or read two operands to or from the register file, supply two operands to the ALU, supply two operands to the multiplier, and receive three results from the ALU and multiplier. The processor’s 48-bit orthogonal instruction word supports parallel data transfers and arithmetic operations in the same instruction.

40-Bit Extended Precision. The DSP handles 32-bit IEEE floating-point format, 32-bit integer and fractional formats (twos-complement and unsigned), and extended-precision 40-bit floating-point format. The pro-

ADSP-21160 Architecture Overview

processors carry extended precision throughout their computation units, limiting intermediate data truncation errors.

Dual Address Generators. The DSP has two data address generators (DAGs) that provide immediate or indirect (pre- and post-modify) addressing. Modulus, bit-reverse, and broadcast operations are supported with no constraints on data buffer placement.

Efficient Program Sequencing. In addition to zero-overhead loops, the DSP supports single-cycle setup and exit for loops. Loops are both nestable (six levels in hardware) and interruptable. The processors support both delayed and non-delayed branches.

ADSP-21160 Architecture Overview

The ADSP-21160 forms a complete system-on-a-chip, integrating a large, high-speed SRAM and I/O peripherals supported by a dedicated I/O bus. The following sections summarize the features of each functional block in the ADSP-21160 SHARC architecture, which appears in [Figure 1-1](#). With each summary, a cross reference points to the sections where the features are described in greater detail.

Processor Core

The processor core of the ADSP-21160 consists of two processing elements (each with three computation units and data register file), a program sequencer, two data address generators, a timer, and an instruction cache. All digital signal processing occurs in the processor core.

Processing Elements

The processor core contains two Processing Elements (PE_x and PE_y). Each element contains a data register file and three independent computation units: an ALU, a multiplier with a fixed-point accumulator, and a

shifter. For meeting a wide variety of processing needs, the computation units process data in three formats: 32-bit fixed-point, 32-bit floating-point and 40-bit floating-point. The floating-point operations are single-precision IEEE-compatible. The 32-bit floating-point format is the standard IEEE format, whereas the 40-bit extended-precision format has eight additional Least Significant Bits (LSBs) of mantissa for greater accuracy.

The ALU performs a set of arithmetic and logic operations on both fixed-point and floating-point formats. The multiplier performs floating-point or fixed-point multiplication and fixed-point multiply/add or multiply/subtract operations. The shifter performs logical and arithmetic shifts, bit manipulation, field deposit and extraction, and exponent derivation operations on 32-bit operands. These computation units perform single-cycle operations; there is no computation pipeline. All units are connected in parallel, rather than serially. The output of any unit may serve as the input of any unit on the next cycle. In a multifunction computation, the ALU and multiplier perform independent, simultaneous operations.

Each processing element has a general-purpose data register file that transfers data between the computation units and the data buses and stores intermediate results. A register file has two sets (primary and alternate) of sixteen registers each, for fast context switching. All of the registers are 40 bits wide. The register file, combined with the core processor's Harvard architecture, allows unconstrained data flow between computation units and internal memory.

Primary Processing Element (PE_x). PE_x processes all computational instructions whether the DSP is in Single-Instruction, Single-Data (SISD) or Single-Instruction, Multiple-Data (SIMD) mode. This element corresponds to the computational units and register file in previous ADSP-21000 family DSPs.

Secondary Processing Element (PE_y). PE_y processes each computational instruction in lock-step with PE_x, but only processes these instructions

ADSP-21160 Architecture Overview

when the DSP is in SIMD mode. Because many operations are influenced by this mode, more information on SIMD is available in multiple locations:

- For information on PEy operations, see [“Processing Elements” on page 2-1](#)
- For information on data addressing in SIMD mode, see [“Addressing in SISD & SIMD Modes” on page 4-17](#)
- For information on data accesses in SIMD mode, see [“SISD, SIMD, and Broadcast Load Modes” on page 5-45](#)
- For information on multiprocessing in SIMD mode, see [“Multiprocessor \(DSPs\) Interface” on page 7-91](#)
- For information on SIMD programming, see the *ADSP-21160 SHARC DSP Instruction Set Reference*.

Program Sequence Control

Internal controls for ADSP-21160 program execution come from four functional blocks: program sequencer, data address generators, timer, and instruction cache. Two dedicated address generators and a program sequencer supply addresses for memory accesses. Together the sequencer and data address generators allow computational operations to execute with maximum efficiency since the computation units can be devoted exclusively to processing data. With its instruction cache, the ADSP-21160 can simultaneously fetch an instruction from the cache and access two data operands from memory. The data address generators implement circular data buffers in hardware.

Program Sequencer. The program sequencer supplies instruction addresses to program memory. It controls loop iterations and evaluates conditional instructions. With an internal loop counter and loop stack, the ADSP-21160 executes looped code with zero overhead. No explicit

jump instructions are required to loop or to decrement and test the counter.

The ADSP-21160 achieves its fast execution rate by means of pipelined fetch, decode and execute cycles. If external memories are used, they are allowed more time to complete an access than if there were no decode cycle.

Data Address Generators. The data address generators (DAGs) provide memory addresses when data is transferred between memory and registers. Dual data address generators enable the processor to output simultaneous addresses for two operand reads or writes. DAG1 supplies 32-bit addresses to data memory. DAG2 supplies 32-bit addresses to program memory for program memory data accesses.

Each DAG keeps track of up to eight address pointers, eight modifiers and eight length values. A pointer used for indirect addressing can be modified by a value in a specified register, either before (pre-modify) or after (post-modify) the access. A length value may be associated with each pointer to perform automatic modulo addressing for circular data buffers; the circular buffers can be located at arbitrary boundaries in memory. Each DAG register has an alternate register that can be activated for fast context switching.

Circular buffers allow efficient implementation of delay lines and other data structures required in digital signal processing, and are commonly used in digital filters and Fourier transforms. The DAGs automatically handle address pointer wraparound, reducing overhead, increasing performance, and simplifying implementation.

Interrupts. The ADSP-21160 has four external hardware interrupts: three general-purpose interrupts, $\overline{\text{IRQ2-0}}$, and a special interrupt for reset. The processor also has internally generated interrupts for the timer, DMA controller operations, circular buffer overflow, stack overflows, arithmetic exceptions, multiprocessor vector interrupts, and user-defined software interrupts.

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For the general-purpose external interrupts and the internal timer interrupt, the ADSP-21160 automatically stacks the arithmetic status and mode (MODE1) registers in parallel with the interrupt servicing, allowing fifteen nesting levels of very fast service for these interrupts.

Context Switch. Many of the processor's registers have alternate registers that can be activated during interrupt servicing for a fast context switch. The data registers in the register file, the DAG registers, and the multiplier result register all have alternates. The Primary Registers are active at reset, while the Alternate (or Secondary) Registers are activated by control bits in a mode control register.

Timer. The programmable interval timer provides periodic interrupt generation. When enabled, the timer decrements a 32-bit count register every cycle. When this count register reaches zero, the ADSP-21160 generates an interrupt and asserts its timer expired output. The count register is automatically reloaded from a 32-bit period register and the count resumes immediately.

Instruction Cache. The program sequencer includes a 32-word instruction cache that enables three-bus operation for fetching an instruction and two data values. The cache is selective—only instructions whose fetches conflict with program memory data accesses are cached. This caching allows full-speed execution of core, looped operations such as digital filter multiply-accumulates and FFT butterfly processing.

Processor Internal Buses

The processor core has six buses: PM address, PM data, DM address, DM data, IO address, and IO data. Due to processor's Harvard Architecture, data memory stores data operands, while program memory can store both instructions and data. This architecture allows dual data fetches, when the instruction is supplied by the cache.

Bus Capacities. The PM address bus and DM address bus transfer the addresses for instructions and data. The PM data bus and DM data bus

transfer the data or instructions from each type of memory. The PM address bus is 32 bits wide allowing access of up to 4 Gwords of mixed instructions and data. The PM data bus is 64 bits wide to accommodate the 48-bit instructions and 64-bit data.

The DM address bus is 32 bits wide allowing direct access of up to 4G words of data. The DM data bus is 64 bits wide. The DM data bus provides a path for the contents of any register in the processor to be transferred to any other register or to any data memory location in a single cycle. The data memory address comes from one of two sources: an absolute value specified in the instruction code (direct addressing) or the output of a data address generator (indirect addressing).

The IO address and IO data buses let the IO processor access internal memory for DMA without delaying the processor core. The IO address bus is 32 bits wide, and the IO data bus is 64 bits wide.

Data Transfers. Nearly every register in the processor core is classified as a Universal Register (UREG). Instructions allow transferring data between any two universal registers or between a universal register and memory. This support includes transfers between control registers, status registers, and data registers in the register file. The PM bus connect (PX) registers permit data to be passed between the 64-bit PM data bus and the 64-bit DM data bus or between the 40-bit register file and the PM data bus. These registers contain hardware to handle the data width difference. [For more information, see “Processing Element Registers” on page A-19.](#)

Processor Peripherals

The term processor peripherals refers to everything outside the processor core. The ADSP-21160's peripherals include internal memory, external port, I/O processor, JTAG port, and any external devices that connect to the DSP.

ADSP-21160 Architecture Overview

Dual-Ported Internal Memory (SRAM)

The ADSP-21160 contains 4 megabits of on-chip SRAM, organized as two blocks of 2 Mbits each, which can be configured for different combinations of code and data storage. Each memory block is dual-ported for single-cycle, independent accesses by the core processor and I/O processor or DMA controller. The dual-ported memory and separate on-chip buses allow two data transfers from the core and one from I/O, all in a single cycle.

All of the memory can be accessed as 16-, 32-, 48-, or 64-bit words. On the ADSP-21160, the memory can be configured as a maximum of 128K words of 32-bit data, 256K words of 16-bit data, 80K words of 48-bit instructions (and 40-bit data), or combinations of different word sizes up to 4 megabits.

The DSP supports a 16-bit floating-point storage format, which effectively doubles the amount of data that may be stored on chip. Conversion between the 32-bit floating-point and 16-bit floating-point formats completes in a single instruction.

While each memory block can store combinations of code and data, accesses are most efficient when one block stores data, using the DM bus for transfers, and the other block stores instructions and data, using the PM bus for transfers. Using the DM bus and PM bus in this way, with one dedicated to each memory block, assures single-cycle execution with two data transfers. In this case, the instruction must be available in the cache. The DSP also maintains single-cycle execution when one of the data operands is transferred to or from off-chip, using the DSP's external port.

External Port

The ADSP-21160's external port provides the processor's interface to off-chip memory and peripherals. The 4-gigaword off-chip address space is included in the ADSP-21160's unified address space. The separate on-chip buses—for PM address, PM data, DM address, DM data, IO

address, and IO data—multiplex at the external port to create an external system bus with a single 32-bit address bus and a single 64-bit data bus. External SRAM can be 16, 32, 48, or 64 bits wide; the ADSP-21160's on-chip DMA controller automatically packs external data into the appropriate word width during transfers.

On-chip decoding of high-order address lines generates memory bank select signals for addressing external memory devices. Separate control lines support simplified addressing of page-mode DRAM. The ADSP-21160 provides programmable memory waitstates and external memory acknowledge controls for interfacing to DRAM and peripherals with variable access, hold, and disable time requirements.

Host Processor Interface. The ADSP-21160's host interface allows easy connection to standard microprocessor buses, both 16-bit and 32-bit, with little additional hardware required. The interface supports asynchronous and synchronous transfers at speeds up to the half the internal clock rate of the ADSP-21160. The host interface operates through the ADSP-21160's external port and maps into the unified address space. Four channels of DMA are available for the host interface; code and data transfers occur with low software overhead. The host can directly read and write the internal memory of the ADSP-21160 and can access the DMA channel setup and mailbox registers. Vector interrupt support provides for efficient execution of host commands.

Multiprocessor System Interface. The ADSP-21160 offers powerful features tailored to multiprocessing DSP systems. The unified address space allows direct interprocessor accesses of each ADSP-21160's internal memory. Distributed bus arbitration logic on the DSP allows simple, glueless connection of systems containing up to six ADSP-21160s and a host processor. Master processor changeover incurs only one cycle of overhead. Bus arbitration handles either fixed or rotating priority. Processor bus lock allows indivisible read-modify-write sequences for semaphores. A vector interrupt capability is provided for interprocessor commands. Broadcast

ADSP-21160 Architecture Overview

writes allow simultaneous transmission of data to all ADSP-21160s and can be used to implement reflective semaphores.

I/O Processor

The ADSP-21160's Input/Output Processor (IOP) includes two serial ports, six link ports, and a DMA controller. One of the I/O processes that the IO processor automates is booting. The DSP can boot from the external port (with data from an 8-bit EPROM or a host processor) or a link port. Alternatively, a no-boot mode lets the DSP start by executing instructions from external memory without booting.

Serial Ports. The ADSP-21160 features two synchronous serial ports that provide an inexpensive interface to a wide variety of digital and mixed-signal peripheral devices. The serial ports can operate at up to half the processor core clock rate. Independent transmit and receive functions provide greater flexibility for serial communications. Serial port data can automatically transfer to and from on-chip memory using DMA. Each of the serial ports offers a TDM multichannel mode and supports μ -law or A-law companding.

The serial ports can operate with little-endian or big-endian transmission formats, with word lengths selectable from 3 to 32 bits. They offer selectable synchronization and transmit modes. Serial port clocks and frame syncs can be internally or externally generated.

Link Ports. The ADSP-21160 features six 10-bit link ports that provide additional I/O capabilities. Link port I/O is especially useful for point-to-point interprocessor communication in multiprocessing systems. The link ports can operate independently and simultaneously. The data packs into 32-bit or 48-bit words, which the processor core can directly read or the IO processor can DMA-transfer to on-chip memory. Clock/acknowledge handshaking controls link port transfers. Transfers are programmable as either transmit or receive.

DMA Controller. The ADSP-21160's on-chip DMA controller allows zero-overhead data transfers without processor intervention. The DMA controller operates independently and invisibly to the processor core, allowing DMA operations to occur while the core is simultaneously executing its program. Both code and data can be downloaded to the ADSP-21160 using DMA transfers.

DMA transfers can occur between the ADSP-21160's internal memory and external memory, external peripherals, or a host processor. DMA transfers can also occur between the ADSP-21160's internal memory and its serial ports or link ports. DMA transfers between external memory and external peripheral devices are another option. External bus packing to 16-, 32-, 48-, or 64-bit words is automatically performed during DMA transfers.

Fourteen channels of DMA are available on the ADSP-21160—six over the link ports, four over the serial ports, and four over the processor's external port. The external port DMA channels serve for host processor, other ADSP-21160s, memory, or I/O transfers.

JTAG Port

The JTAG port on the ADSP-21160 supports the IEEE standard 1149.1 Joint Test Action Group (JTAG) standard for system test. This standard defines a method for serially scanning the I/O status of each component in a system. Emulators use the JTAG port to monitor and control the DSP during emulation. Emulators using this port provide full-speed emulation with access to inspect and modify memory, registers, and processor stacks. JTAG-based emulation is non-intrusive and does not effect target system loading or timing.

Development Tools

The ADSP-21160 is supported by VisualDSP®, an easy-to-use project management environment, comprised of an Integrated Development Environment (IDE) and Debugger. VisualDSP lets you manage projects from start to finish from within a single, integrated interface. Because the project development and debug environments are integrated, you can move easily between editing, building, and debugging activities.

Flexible Project Management. The IDE provides flexible project management for the development of DSP applications. The IDE includes access to all the activities necessary to create and debug DSP projects. You can create or modify source files or view listing or map files with the IDE Editor. This powerful Editor is part of the IDE and includes multiple language syntax highlighting, OLE drag and drop, bookmarks, and standard editing operations such as undo/redo, find/replace, copy/paste/cut, and go to.

Also, the IDE includes access to the SHARC® DSP C Compiler, C Runtime Library, Assembler, Linker, Loader, Simulator, and Splitter. You specify options for these SHARC Tools through Property Page dialogs. Property Page dialogs are easy to use, and make configuring, changing, and managing your projects simple. These options control how the tools process inputs and generate outputs, and have a one-to-one correspondence to the tools' command line switches. You can define these options once, or modify them to meet changing development needs. You can also access the SHARC Tools from the operating system command line if you choose.

Greatly Reduced Debugging Time. The Debugger has an easy-to-use, common interface for all processor simulators and emulators available through Analog Devices and third parties or custom developments. The Debugger has many features that greatly reduce debugging time. You can view C source interspersed with the resulting Assembly code. You can profile execution of a range of instructions in a program; set simulated watch

points on hardware and software registers, program and data memory; and trace instruction execution and memory accesses. These features enable you to correct coding errors, identify bottlenecks, and examine DSP performance. You can use the custom register option to select any combination of registers to view in a single window. The Debugger can also generate inputs, outputs, and interrupts so you can simulate real world application conditions.

SHARC Software Development Tools. SHARC Software Development Tools, which support the SHARC Family, allow you to develop applications that take full advantage of the SHARC architecture, including multiprocessing, shared memory, and memory overlays. SHARC Software Development Tools include C Compiler, C Runtime Library, DSP and Math Libraries, Assembler, Linker, Loader, Simulator, and Splitter.

C Compiler & Assembler. The C Compiler generates efficient code that is optimized for both code density and execution time. The C Compiler allows you to include Assembly language statements inline. Because of this, you can program in C and still use Assembly for time-critical loops. You can also use pretested Math, DSP, and C Runtime Library routines to help shorten your time to market. The SHARC Family Assembly language is based on an algebraic syntax that is easy to learn, program, and debug. The add instruction, for example, is written in the same manner as the actual equation.

Linker & Loader. The Linker provides flexible system definition through Linker Description Files (.LDF). In a single LDF, you can define different types of executables for a single or multiprocessor system. The Linker resolves symbols over multiple executables, maximizes memory use, and easily shares common code among multiple processors. The Loader supports creation of host, link port, and PROM boot images. Along with the Linker, the Loader allows multiprocessor system configuration with smaller code and faster boot time. The Simulator is a cycle-accurate, instruction-level simulator — allowing you to simulate your application in real time.

Differences From Previous SHARC DSPs

3rd-Party Extensible. The VisualDSP environment enables third-party companies to add value using Analog Devices' published set of Application Programming Interfaces (API). Third party products—runtime operating systems, emulators, high-level language compilers, multiprocessor hardware —can interface seamlessly with VisualDSP thereby simplifying the tools integration task. VisualDSP follows the COM API format. Two API tools, Target Wizard and API Tester, are also available for use with the API set. These tools help speed the time-to-market for vendor products. Target Wizard builds the programming shell based on API features the vendor requires. The API tester exercises the individual features independently of VisualDSP. Third parties can use a subset of these APIs that meets their application needs. The interfaces are fully supported and backward compatible.

Further details and ordering information are available in the VisualDSP Development Tools data sheet. This data sheet can be requested from any Analog Devices sales office or distributor.

Differences From Previous SHARC DSPs

This section identifies differences between the ADSP-21160 DSP and previous SHARC DSPs: ADSP-21060, ADSP-21061, and ADSP-21062. The ADSP-21160 preserves much of the ADSP-2106x architecture, while extending performance and functionality. For background information on SHARC and the ADSP-2106x Family DSPs, see the ADSP-2106x SHARC User's Manual.

Processor Core Enhancements

Computational bandwidth on the ADSP-21160 is significantly greater than on the ADSP-2106x DSPs. The increase comes from raising the operational frequency and adding another processing element: ALU, Shifter, Multiplier, and register file. The new processing element lets the DSP process multiple data streams in parallel (SIMD mode).

The program sequencer on the ADSP-21160 differs from the ADSP-2106x family, having several enhancements: new interrupt vector table definitions, SIMD mode stack and conditional execution model, and instruction decodes associated with new instructions. Changes to interrupts include new interrupt vectors for detecting illegal memory accesses and supporting new unshared DMA channels. Link port interrupt control has moved to a new register to support the additional DMA channels. Also, new mode stack and mode mask support has been added to improve context switch time.

Data address generators on the ADSP-21160 differ from the ADSP-2106x in that DAG2 (for the PM bus) has the same addressing capability as DAG1 (for the DM bus). The DAG registers are read/writable in pairs, moving 64-bits/cycle. Additionally, the DAGs support the new memory map and Long Word transfer capability. Circular buffering on the ADSP-21160 can be quickly disabled on interrupts and restored on the return. Data “broadcast”, from one memory location to both data register files, is determined by appropriate index register usage.



Unlike previous SHARCs, the ADSP-21160 has a global circular buffering enable (CBUFEN) bit. Because at reset this bit defaults to disabled, programs that use circular buffering and are being ported from previous SHARCs need to add a line of code to enable circular buffering. [For more information, see “Addressing Circular Buffers” on page 4-12.](#)

Processor Internal Bus Enhancements

The PM, DM, and IO data buses on the ADSP-21160 are much wider than on the ADSP-2106x DSPs, increasing to 64 bits. Additional multiplexing and control logic on the ADSP-21160 enable 16-, 32-, or 64-bit wide moves between both register files and memory. The ADSP-21160 also has the capability of broadcasting a single memory location to each of the register files in parallel. Also, the ADSP-21160 permits register con-

Differences From Previous SHARC DSPs

tents to be exchanged between the two processing elements' register files in a single cycle.

Memory Organization Enhancements

The ADSP-21160 memory map differs from the ADSP-2106x DSPs. The system memory map on the ADSP-21160 supports double-word transfers each cycle, reflects extended internal memory capacity for derivative designs, and works with updated control register for SIMD support.

External Port Enhancements

The ADSP-21160's external port differs from the ADSP-2106x DSPs, greatly extending the external interface. The data bus on the ADSP-21160 is 64 bits wide. The ADSP-21160 has a new synchronous interface that improves local bus switching frequency. Also, burst support on the ADSP-21160 improves bus usage.



Unlike previous SHARCs, the ADSP-21160 sets the buffer hang disable (BHD) bit at reset. Because this bit prevents the processor core from detecting a buffer-related stall condition, programs that use external port, link port, or serial port I/O and are being ported from previous SHARCs need to add a line of code to disable BHD. For more information, see the BHD discussion [on page 6-18](#).

Host Interface Enhancements

The ADSP-21160's host interface differs from the ADSP-2106x DSPs in that this interface can take advantage of the 64-bit data bus width. Though the ADSP-21160 supports the ADSP-2106x's asynchronous host interface protocols, the ADSP-21160 also provides new synchronous interface protocols for maximum throughput.

The host/local bus deadlock resolution function on the ADSP-21160 is extended to the DMA controller. The function allows the host (or bridge)

logic to force the local bus to back off and allow the host to complete its operation first.

Multiprocessor Interface Enhancements

The ADSP-21160's multiprocessor system interface supports greater throughput than the ADSP-2106x DSPs. The throughput between ADSP-21160s in a multiprocessing application increases due to shared data bus width increase to 64-bits, new shared bus transfer protocols, shared bus cycle time improvements due to synchronous interface, and improvements in Link Port throughput. The external port supports glueless multiprocessing, with distributed arbitration for up to six ADSP-21160s.

IO Architecture Enhancements

The IO processor on the ADSP-21160 provides much greater throughput than the ADSP-2106x DSPs. The Link Ports and DMA controller differ on the ADSP-21160.

DMA Controller Enhancements

The ADSP-21160's DMA controller supports 14 channels (versus 10 on the ADSP-2106x DSPs), with no channel sharing. New packing modes support the new 64-bit external/internal busing. To resolve potential deadlock scenarios, the ADSP-21160's DMA controller relinquishes the local bus in a similar fashion to the processor core when host logic asserts both \overline{HBR} and $SBTS$.

Link Port Enhancements

The ADSP-21160's Link ports provide greater throughput than the ADSP-2106x DSPs. The link port data bus width on the ADSP-21160 is 8 bits wide (versus 4 bits on the ADSP-2106x DSPs). Link port clock control on the ADSP-21160 supports a wider frequency range.

For More Information About Analog Products

Instruction Set Enhancements

ADSP-21160 provides source code compatibility with the previous SHARC family members, to the application assembly source code level. All instructions, control registers, and system resources available in the ADSP-2106x core programming model are available in ADSP-21160. New instructions, control registers, or other facilities, required to support the new feature set of ADSP-21160 core are:

- Supersets of the ADSP-2106x programming model
- Reserved facilities in the ADSP-2106x programming model
- Symbol name changes from the ADSP-2106x programming model

These name changes can be managed through re-assembly using the ADSP-21160 development tools to apply the ADSP-21160 symbol definitions header file and linker description file. While these changes have no direct impact on existing core applications, system and I/O processor initialization code and control code do require modifications.

This approach simplifies porting of source code written for the ADSP-2106x family to ADSP-21160. Code changes will be required to take full advantage of the new ADSP-21160 features. For more information, see the *ADSP-21160 SHARC DSP Instruction Set Reference*.

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- Contact your local ADI sales office or an authorized ADI distributor
- Send questions by mail to:
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What's New in This Manual

This is the first edition of the ADSP-21160 SHARC DSP Hardware Reference. Summaries of changes between editions will start with the next edition.

Related Documents

For more information about Analog Devices DSPs and development products, see the following documents:



- *ADSP-21160 SHARC DSP Microcomputer Data Sheet*
- *ADSP-21160 SHARC DSP Instruction Set Reference*
- *Getting Started Guide for VisualDSP & ADSP-21xxx Family DSPs*
- *VisualDSP User's Guide for ADSP-21xxx Family DSPs*
- *C Compiler & Library Manual for ADSP-21xxx Family DSPs*
- *Assembler Manual for ADSP-21xxx Family DSPs*
- *Linker & Utilities Manual for ADSP-21xxx Family DSPs*

All the manuals are included in the software distribution CD-ROM. To access these manuals, use the Help Topics command in the VisualDSP environment's Help menu and select the Online Manuals book. From this Help topic, you can open any of the manuals, which are in Adobe Acrobat PDF format.

Conventions

The following are conventions that apply to all chapters. Note that additional conventions, which apply only to specific chapters, appear throughout this document.

Table 1-1. Notation Conventions

Example	Description
PC, R1, PX	Register names appear in UPPERCASE and keyword font
TIMEXP, $\overline{\text{RESET}}$	Pin names appear in UPPERCASE and keyword font; active low signals appear with an $\overline{\text{OVERBAR}}$.
If, Do/Until	Assembler instructions (mnemonics) appear in initial capitals
	A note, providing information of special interest or identifying a related DSP topic.
	A caution, providing information on critical design or programming issues that influence operation of the DSP.
Click Here	In the online version of this document, a cross reference acts as a hypertext link to the item being referenced. Click on blue references (Table, Figure, or section names) to jump to the location.

Conventions