

USER MANUAL



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1. CONNECTIONS



RX-/SWITCH HARNESS:

This LRP speed-control is equipped with the new RX-/Switch-Harness for maximum convienence. The regular LRP Multicon receiver wire is used and will easily fit in all ordinary receivers. Install the On/Off micro switch supplied doublesided tape

POWER WIRES:

POWER WIRES: 1.5mm² power wires without any attached connectors are used. There are G3.5 gold connectors included which allow convienent installation with brushless motors such as the Vector Micro 370. The unique solder posts allow easy and convenient replacement of the power wires. Nevertheless some solde-ring skills are required. Avoid soldering longer then 5sec per soldering joint to prevent possible damage to the speed-control due to overheating of the components!

2. INSTALLATION

The *Nexxt 4X* is su t 4X is supplied with 1.5mm² power-wires without attached connectors. There are G3.5 gold connec-ded which allow convienent installation with brushless motors such as the Vector Micro 370. Be careful with the correct wire sequence/colors since an incorrect connection may damage the speed-control! Isolate all connections carefully.

Caution: Avoid soldering longer than 5sec per soldering joint when replacing the power wires on the speed control and motor to prevent possible damage due to overheating of the components!

Attach switch-/RX-wire harness to speedo (be careful with correct polarity)
 Connect the speed-control to the receiver (position: Channel 2)

Brushless Motor • Speedo MOT.A → Motor "A" • Speedo MOT.B → Motor "B" • Speedo MOT.C → Motor "C"	Brushed Motor: • Speedo MOT.A (blue) and MOT.B (yellow) will be the combined "minus" on brushed motor. • Speedo MOT.C (orange) is the "plus" on bruhed motor.
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Doublecheck all connections before connecting the speed-control to a battery. **CAUTION:** If battery is connected with reversed polarity it will destroy your speed-control!

Red nower-wire power-wire

X

→ Speedo "+" to battery "Plus"
 → Speedo "-" to battery "Minus"

The speed-control is now ready to be set-up (see section 5).

3. USAGE TIPS

- Position the speed-control and capacitor where they are protected in the event of a crash and gives you easy access to the connectors and button.
- Make sure there is enough clearance between the speed-control, power-wires, antenna and receiver. Avoid any direct contact between power components, the receiver or the antenna as this can cause interference. If interference occurs, position the components at a different place in the model.
- Mount the speedo and capacitor using the supplied thick/black doubled-sided tape.
- The aerial should be run vertically up and away from the receiver. Avoid contact with any parts made of carbon fibre or metal. If the aerial is too long, don't coil up the excess length. See also the instructions supplied with your radio control system
- Because of the physical principles of brushless technology, the speed-controls do get a little hotter than brushed systems. Therefore it is required to let the speed-control cool down completely after every run.
- Sensorless brushless motors do not have a designated rotating direction and work identically in both direc-tions. If the motor rotates the wrong way for your model, after you have wired up the three phase wires, then you can simply change motor rotation direction by swapping two of the three phase wires (e.g. SpeedoA goes to MotorB and SpeedoB goes to MotorA)!

The crossed-out wheeled bin means that within the European Union the product must be taken to seperate collection at the product end-of-life. Do not dispose of these products as unsorted municipal waste.

Dear Customer

thank you for your trust in this LRP product. By purchasing the LRP NEXXT 4X speed-control, you have chosen one of the most advanced sensorless brushless speed-controls of today. The Nexxt 4X, with all of its high-tech features and specially selected electronic components, is one of the best speed-controls currently available:

- Brushless and Brushed Operation
- Micro Car Specialist
 8 ADPC[™] Power Profiles
 Internal-Temp-Check System 2
 Multi-Protection System
- Small size and lighweight
 AutoCell System (NiMH 4-9 / LiPo 2S + 3S)
 IceDrive Design
 Waterserver
 - Waterproof

Sensorless Design

Please read the following instructions carefully before you start using your LRP Nexxt 4X speed control. This user guide contains important notes for the safety, the use and the maintenance of this product. Thus protecting yourself and avoid damages of the product.

Proceed according to the user guide in order to understand your *LRP Nexxt 4X* speed control better. Please take your time as you will have much more joy with your product if you know it exactly.

This user manual shall be kept in a safe place. If another customer is using this product, this manual has to be handed out together with it

4. SPECIFICATIONS

Brushless + Brushed	yes			B.E.C.	6.0V/2.0A
Sensorless Brushless System	yes			Internal-Temp-Check System 2	yes
Forward / Brake	yes			High Frequency	yes
Forward / Brake / Reverse	yes			Fail-Safe-System	yes
Case Size	28.5 x 40.3mm 20g 4.8 - 11.1V		Multi-Protection-System	yes	
Weight (excl. wires)				Waterproof	yes
Voltage Input				Integrated Solder Posts	yes
	BRUSHLESS	BRUSHED		Power Wires	1.5mm ²
Typ. Voltage Drop* @20A	0.026V / phase	0.019V		3.5mm Gold Connectors	included
Rated Current*	382A / phase	382A		4 adjustable Modes	
Rec. Motor Limit (370/380 size)	none	none		(AutoCell, Motor/Drive-Settings,	yes
Rec. Motor Limit (540 size)	e) over 7.5 turns over 13T		1	ADPC Powerprofiles, Autobrake)	

5. RADIO / SPEED-CONTROL SET-UP

In setup mode the Nexxt 4X stores radio calibrations after completed procedure, all the settings will be stored in the speed-controls memory even if the speed-control will be disconnected from the battery

TRANSMITTER SETTINGS

Setup the following basic functions on your transmitter (if available):							
Description other names in radio Required Setting							
Throttle Travel High ATV, EPA 100%							
Brake Travel Low ATV, EPA, ATL 100%							
Throttle Exponential EXP, EXPO start with 0							
Neutral Trim SUB Trim centre							
Servo Reverse Throttle Reverse any setting, don't change after set-up procedure!							
If your transmitter does	n't offer any of above fund	tions, it's already in "basic setup" mode.					

 Ensure that the speed-control is not connected to the drive battery and is switched off. Remove motor pinion or ensure that the wheels of the model are free to rotate. Switch the transmitter on and set the transmitter throttle stick to neutral.

- Connect the speed-control to the battery (switch in OFF position).

Hold the button pressed and turn the switch on.
 → You entered setup mode and the blue LED flashes (it will flash until the setup is completed).

- Leave transmitter in neutral position and press the button once.
 → Neutral setting is stored , yellow/blue LED flashes and the motor beeps.
- Hold full throttle on transmitter and press the button once → Full-throttle setting is stored, red/blue LED flashes.
- Hold full brake on transmitter and press the button once.
 Brake setting is stored, red and blue LED's glow.
- This completes the setup procedure, stores all settings, and your Nexxt 4X is ready to use.
- If you make a mistake during the setup procedure, don't worry: Disconnect the battery for about 10sec and start again from the first step. again fro
- At the end of each run switch off the car, and then switch off the transmitter.
- At the start of each run switch on the transmitter first, then switch on the car. For storage of the car, disconnect the drive battery at all times!

CHECKING THE FUNCTIONS:

Check the LED's when moving your throttle stick and you will see if everything is setup correctly.

FUNCTION	STATUS	Left LED	Right LED
Neutral (automatic brake inactive)		off	blue
Neutral (automatic brake active)		red	off
Forward	partial throttle	yellow	off
Forward	full throttle	yellow	blue
Brake	partial brake	red	off
Brake	full brake	red	blue

6. SUPPRESSION





ONLY FOR BRUSHED MOTORS! Motors with no capacitors or not enough capacitors may interfe with the speed-control. To avoid this, solder t supplied capacitors to your motor (see picture). the

7. MODE PROGRAMMING

 How to get into "programming the modes"? 	With speedo turned on, press button for 3sec until all 3 LED's flicker twice quickly.
 How to know in which mode you are? 	→ check LED flashing sequence of left LED's.
 How to check the stored values? 	→ Count the number of flashes of the blue LED. (* = value 1 ** = value 2 etc.).
 How to change the value? 	→ Press button to increase value by one step.
 How to get to the next mode? 	→ this is done automatic, the values will be shown 3 times before it jumps to the next Model The "jump" to the next mode is indicated by all 3 LED's flickering twice quickly.
 How to leave the programming mode? 	 simply turn off speedo anytime, the most recent values you had choosen will be stored.
 Table of settings, values and modes: see below 	(grey-shaded values show "default settings").
	nvienence we have incorporated the new DirectAccess func node you would like to change without having to go "the long

• if you have reached the mode you would like to change (as indicated by left LED's), release button.

The DirectAccess works if you start from the beginning of all mode's, but it also works to jump from Mode.1

MODE.O (Internal Temp Check System 2): This new feature allows you to accurately check if all is running well or if you're close to shutdown already. The higher the number of flashes, the hotter the speedo ran and every flash equals to 5°C temperature decrease

L	eft LED's	#1	#2	#3	#4	#5	#6	#7	#8	#9	#10
	OFF	> -45°C > -81°F	-40°C -72°F	-35°C -63°F	-30°C -54°F	-25°C -45°F	-20°C -36°F	-15°C -27°F	-10°C -18°F	-5°C -9°F	Shutdown

MODE.1 (AutoCell System): we recommend using value 2 for 4-6 cells NiMH racing purposes, which disengages the LiPo protection. With value #1, the Nexxt 4X automatically detects if a 2S or 3S LiPo is connected and adjusts cut-off accordingly.

Left LED's	#1	#2
Yellow	LiPo/NiMH Automatic	4-6cell NiMH Racing Mode

MODE.2 (Motor- & Drive Selection): the Nexxt 4X allows you to select from two different drive modes (with or without reverse) and select between brushless and brushed motor operation.

Red Forward/Brake/Reverse Forward/Brake Forward/Brake/Reverse Forward/Brake Brushless Brushless Brushed Brushed	Left LED's	#1	#2	#3	#4
	Red	Forward/Brake/Reverse Brushless			

MODE.3 (ADPC[™] Power Profiles): allows you to adjust the *Nexxt 4X* to your likes. Either you run on mild or powerful motors or on slippery or high-traction surfaces, we have incorporated a profile for you! Higher value means more overall power and more aggressive throttle response. All settings are available for brushless and brushed motors.

- [Left LED's	#1	#2	#3	#4	#5	#6	#7	#8
	Yellow/Red	smooth	smooth	smooth	smooth	linear	linear	progressive	aggressive
	(alternate)	Power: 1X	Power: 2X	Power: 3X	Power: 4X	Power: 4X	Power: 5X	Power: 5X	Power: 6X

MODE.4 (Automatic Brake): allows you to set a slight braking action which is applied in the neutral range. This enables you to simulate the feel of a brushed motor and also hold the throttle on longer when entering a turn. For brushless motors you achieve the same natural slowdown as a brushed motor with no autobrake when you set value 1-2

#3 #4 #5 #6 #7 #8 Left LED's #0 #1 #2 Going from lowest to highest automatic brake setting (value 1 = minimum / value = maximum) Yellow/Red (same time) none

REPAIR PROCEDURES / LIMITED WARRANTY

All products from LRP electronic GmbH (hereinafter called "LRP") are manufactured according to the highest quality standards. LRP guarantees this product to be free from defects in materials or workmanship for 90 days (non-european countris only) from the original date of purchase verified by sales receipt. This limited warranty doesn't cover defects, which are a result of misuse, improper maintenance, outside interference of mechanical damage.

- This applies among other things on: Cut off original power plug or not using reverse polarity protected plugs Receiver wire and/or switch wire damaged Mechanical damage of the case Mechanical damage of electronical components/PCB Soldered on the PCB (except on solder posts) Connected sneed-contcol with eversed polarity"

- Connected speed-control with reversed polarity

To eliminate all other possibilities or improper handling, first check all other components in your model and the trouble shooting guide, if available, before you send in this product for repair. If products are sent in for repair, which do operate perfectly, we have to charge a service fee according to our pricelist.

With sending in this product, the customer has to advise LRP if the product should be repaired in either case. If there is neither a warranty nor guarantee claim, the inspection of the product and the repairs, if necessary, in either case will be charged with a fee at the customers expense according to our price list. A proof of purchase including date of purchase needs to be included. Otherwise, no warranty can be granted. For quick repair- and return service, add your address and detailed description of the malfunction.

If LRP no longer manufactures a returned defective product and we are unable to service it, we shall provide you with a product that has at least the same value from one of the successor series.

The specifications like weight, size and others should be seen as guide values. Due to ongoing technical impro-vements, which are done in the interest of the product, LRP does not take any responsibility for the accuracy of these specs.

LRP-Distributor-Service:

Package your product carefully and include sales receipt and detailed description of malfunction.

- Send parcel to your national LRP distributor.
- Distributor repairs or exchanges the product.
- · Shipment back to you usually by COD (cash on delivery), but this is subject to your national LRP distributor's general policy.

8. SPECIAL FEATURES

Sensorless Brushless Design: Revolutionary LRP software providing sensored driveability even without orless brushless technology

ADPC™ Power Profiles: Advanced Digital Phase Control results in more power and better driveability. Depending on the status of the car (start, acceleration, full speed) the software calculates the perfect motor management by adjusting current limiter, motor timing, throttle curve and more! Higher value means more overall power and aggressive response.

D.E.M.S. Brushed - Power Profiles: The known and world's winning D.E.M.S. Brushed Quantum style power programs have been implemented into the *LRP Nexxt 4X* aswell. Higher value means more overall power and aggressive response.

Internal-Temp-Check System 2: the Nexxt 4X allows you to read-out the maximum internal temperature that the speedo reached. To store it to the memory, briefly apply brakes after the run before you turn the switch off. You can convienently read-out the temperature back in the pits since it remains stored until you turn it on the next time regularly (which will reset the memory). This new feature allows you to accurately check if all is unarrowed to be the short during a feature allows. running well or if you're close to shutdown already. The higher the number of flashes, the hotter the speedo ran. Thermal shutdown would occur at 10 flashes

DirectAccess Function: For maximum convienence we have incorporated a quick DirectAccess function which allows you to jump straight to the mode you would like to change without having to go "the long way" through all the other mode's. See section 7 "Mode Programming" on how to use the DirectAccess function.

Brake Adjustment: A good starting point for the brake setting on your radio is 80% for all classes. Make sure you do the radio-setup with all settings on the radio on 100%!

AutoCell System: Ready for the next battery technology – LiPo batteries! LRP's exclusive and smart Auto-Cell System ensures that LiPo batteries can be used safely without accidentially deep-discharging of the cells. Motor power will be reduced (no shutdown will occur!) if the system recognises very low battery voltage. It is self adjusting to 2S or 3S LiPo batteries!

Waterproof: Due to latest production technologies and use of HighTech materials, it was possible to make these speed-controls fully waterproof! This material also makes the speed-controls more shock resistant then other similar products. It's no longer needed to seal your speed-control when you are driving in the rain/snow! But please make sure you still seal your other electronic components (receiver, servo and motor) since these are normally not waterproof and will get damaged due to the water.

Changing Mode settings without the transmitter: At race events you usually do not have access to your transmitter, but never mind since you can simply disconnect the receiver lead from the receiver and change the MODE settings as described in section 7 "Mode Programming".

Power Capacitor: Never disconnect the power-capacitor! It offers increased punch and additional protection, it must be connected to BAT+ and BAT- solder posts with shortest possible wires.

IceDrive Design: LRP's secret IceDrive Design results in lower speedo temperature under all racing con-ditions and for both brushless + brushed. Sorry, no further details to be disclosed. Simply a step ahead of the competition!

Fail Safe System: Digital protection against radio interference, "The guardian angel". The safety electronic can detect reception of a "false" or incomplete radio signal, e.g due to a low transmitter battery or environmental radio interference which reach the model, or if the model is out of the transmitter range. For protection against damage, the speed-control switches to the neutral position, and the model comes to a stop.

Multi-Protection System, 3-way protection: The perfect protection against short-circuits (motor), overload and overheating. If your speed-control faces overload, the motor function will be shut-off for protection and the blue LED will flash, although the steering function is maintained. Let the speed-control cool down for a few minutes. If you experience frequent shutdowns, check for the following:

- Correct gear ratio (refer to motor manual for gearing recommendations)
 ADPC setting too high (higher value will heat up motor and speed-control excessively)
- Motor is too strong or motor is damaged.

9. TROUBLESHOOTING GUIDE

SYMPTOM	CAUSE	REMEDY	
Servo is working, no motor function.	Speed-control plugged in incorrectly	Plug speed-control in Ch 2	
	Overload protection activated	Allow speed-control to cool down	
	Wiring problem	Check wires and connectors	
	Motor defective	Replace motor	
	Speed-control defective	Send in product for repair	
No servo and no motor function.	Speedo connected to receiver with wrong polarity	Connect speedo with correct polarity	
	RX-/Switch Harness not plugged in correctly	Connect RX-/Switch-Harness correctly	
	Battery defective	Replace with different battery pack	
	Crystal defective	Replace components one by one.	
	Receiver defective	1	
	Transmitter defective	1	
	Speed-control defective	Send in product for repair	
Motor stutters while accelerating	Power Capacitor damaged	replace Power Capacitor	
	Radio Interference	Change location of components	
	Motor defective	Replace motor	
	Speed-control defective	Send in product for repair	
Motor runs in reverse when accele-	Motor connected for reverse operation	Swop two of the 3 phase wires	
rating forward on the transmitter.	BM - Motor connected with reversed polarity	Connect motor correctly	
	Transmitter settings changed after set-up	Repeat set-up procedure	
Insufficient performance.	Motor pinion too big or gear ratio too long.	Use smaller motor pinion/shorter gear ratio	
E.g. poor brake power, topspeed or acceleration	Transmitter settings changed after set-up	Repeat set-up procedure	
	Power Capacitor damaged	Replace Power Capacitor	
	BM - Motor worn out	Maintain motor	
	Motor defective	Replace motor	
	Speed-control defective.	Send in product for repair	
Speed-control switches off	Model used too often without cool-down periods	Let speed-control cool down after every run	
frequently.	Motor stronger than motorlimit or input voltage too high	Use only motors and batteries which are within the specifications of the speed-control	
	Motor pinion too big (e.g. gear ratio too long)	Use smaller motor pinion/shorter gear ratio	
	Stuck drivetrain or ballbearing	Maintain model	
	Motor defective	Replace motor	
Motor never stops, runs at constant slow speed	Transmitter settings changed after set-up	Repeat set-up procedure	
Radio interference	Receiver or antenna too close to power wires, motor, battery or speed-control. Receiver aerial too short or coiled up	See "Installation Tips" and "Installation"	
	Receiver defective, too sensitive; Transmitter defective, transmitter output power too low, servo problem	Replace components one by one Only use original manufacturers crystals	
	Poor battery connection	Check plugs and connecting wires	
	Transmitter batteries empty	Replace / recharge transmitter batteries	

straight to Mode.3 for example (simply keep button pressed to activate DirectAccess again!