

# DIMM-MX6 Developer Kit for Android

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User Manual

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## 1 Contents

1	Contents.....	3
2	Definitions.....	4
3	Introduction.....	5
4	The Bootloader .....	6
4.1	Communication settings.....	6
4.2	Dip switch setup.....	6
4.3	Bootloader prompt .....	7
4.3.1	Print/Change environment variables.....	7
4.3.2	Network setup.....	7
4.4	Updating Android Images .....	8
5	Android Application quick start Guide .....	14
5.1	Preparation.....	14
5.2	My Application: an Hello World example.....	14
6	Running Android via NFS.....	17
6.1	Setting up the bootloader:.....	17
6.2	Troubleshooting.....	19
7	Android for advanced user.....	20
7.1	Modifying the Android File System.....	20
7.2	Rebuilding the package.....	20
7.3	Backup .....	21

## 2 Definitions

The table below lists some definitions of terms in this manual.

<b>DIMM-MX6</b>	The target platform
<b>AOSP</b>	Android Open Source Project
<b>VM</b>	Virtual Machine
<b>IDE</b>	integrated development environment
<b>NFS</b>	Network File System
<b>OS</b>	Operating System

### 3 Introduction

Emtrion has designed this Android starter-kit to help you design your Android application quickly and efficiently, and evaluate the Hardware.

By simply running the virtual machine provided, you can start developing your application using the new [Android Studio](#). The SDK is already installed. No download or installation is required to start.

The version of Android OS running on the starter-kit is a custom Android version made by Emtrion. It is compliant with the vanilla Android 4.2.2 named "Jelly Bean" but with some restrictions on specific points. You can find those points below on the section "Available devices/interfaces".

The process of making or rebuilding the Android OS is substantial and requires a lot of knowledge regarding Linux and Android. If you have any requests or particular needs, Emtrion can build a custom Android OS for you. Please contact [sales@emtrion.de](mailto:sales@emtrion.de) for any questions regarding this point.

## 4 The Bootloader

This section gives a brief description of the bootloader used in this Developer Kit. When you are more interested in the function scope of the bootloader, please refer to the detailed description of the bootloader on the homepage of the U-Boot project: <http://www.denx.de/wiki/U-Boot/>

### 4.1 Communication settings

The bootloader's communication settings are:

Baudrate	115200 bps
Data bits	8
Stop bits	1
Parity	none
Handshake	none

### 4.2 Dip switch setup

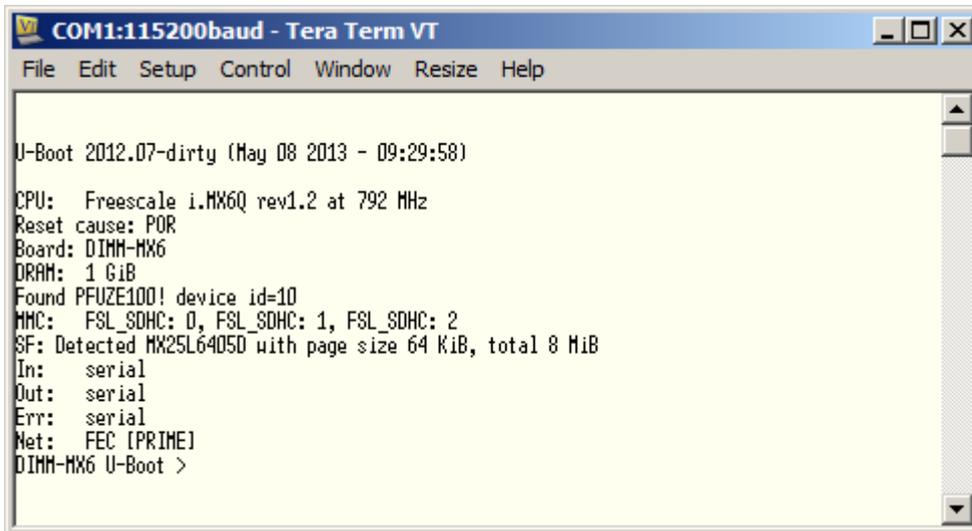
The DIMM-MX6 module carries two dip switches, which have to be setup as follows for a successful start up of the bootloader.

DIP Switch setting for successful start up:

	2	1
off		X
on	X	

### 4.3 Bootloader prompt

The bootloader prompt is reached if you press a key in the console window when the boot delay is counted down. The bootloader prompt allows you to change settings of the bootloader, to update the Android image in flash or boot via NFS.



We are using mainline U-Boot. A detailed description of the bootloader can be found on the homepage of the U-Boot project: <http://www.denx.de/wiki/U-Boot/>.

#### 4.3.1 Print/Change environment variables

The environment variables are handled by using 3 commands: *printenv*, *setenv*, *saveenv*. *Printenv* shows you the current setting of all environment variables. *Setenv <variable> <value>* changes the value of an environment variable. This change is only in RAM and will be lost after reset. The changes can be made permanent by using *saveenv*. The following example shows how the boot command is set up.

```
DIMM-MX6 U-Boot > setenv bootcmd 'mmc read ${loadaddr} 0 0x20000 && bootm'DIMM-MX6 U-Boot > saveenv
```

#### 4.3.2 Network setup

The network setup of the bootloader is also handled by environment variables:

autoload	Set this to "no". This prevents that the use of the "dhcp" command automatically starts a tftp download
ipaddr	IP address of the device. Only effective if dhcp is deactivated
serverip	IP address of the host PC which acts as TFTP server
netmask	Subnet mask of the device
ip-method	Set this to "static" or "dhcp" according to your setup. This is used by the update_uboot script

If you have a DHCP server in your network and want to configure the device via dhcp simple use the command *"dhcp"*:

```
DIMM-MX6 U-Boot > dhcp
BOOTP broadcast 1
BOOTP broadcast 2
BOOTP broadcast 3
DHCP client bound to address 172.26.1.14
```

If there is no DHCP server you have to set the variables *"ipaddr"* and *"netmask"* by hand.

To test your network setting you can ping the host PC from the device running the bootloader. To do so use the command *ping <ip address>*. **Please note, that the device running the bootloader cannot be pinged.**

#### 4.4 Updating Android Images

On the Linux System provided as a Virtual Machine, there is an exported NFS share. For example, for the DIMM-MX6 system:

```
/home/hico/share/dimm-mx6q/
```

With the sub-directory:

```
/home/hico/share/dimm-mx6q/images
```

and

```
/home/hico/share/dimm-mx6q/root/rootfs/boot
```

In the sub-directory „images“, the following files must appear:

```
uImage
android-datafs-dimm_mx6.tar.bz2
android-rootfs-dimm_mx6.tar.bz2
```

In the sub-directory „root/rootfs/boot“, the following files must appear too:

```
emPURS_plat
initramfs-dimm-mx6.igz
uboot_script
uImage
```

Be sure the path of those directories is exported by verifying the file `/etc/exports`. It must be like this:

```
/home/hico/share
0.0.0.0/0.0.0.0(rw,all_squash,anonuid=1000,anongid=1000,no_subtree_
check, sync)
```

You can restart the NFS share by typing on a terminal:

```
~$sudo service nfs-kernel-server restart
```

This is mandatory when you make a change in the file `/etc/exports`.

First of all, your target must have the correct settings, i.e the IP address of the Linux System in the Virtual Machine and the path of the NFS share. See the example in the log below in blue or check the [section 6.1](#).

Then you will be able to update the Android system by only typing:

```
run restore_sys
```

This will flash the Android image automatically and independently. This process takes few minutes to complete and the board must not be powered off.

You can find below, an example of what the board output on the serial during this process.

Note: the highlighted commands in green must be entered to change the settings. With "saveenv", the entries are stored permanently in the boot loader.

```
U-Boot 2013.04-00005-g83a2fe5 (Oct 30 2013 - 14:25:50)

CPU:   Freescale i.MX6Q rev1.2 at 792 MHz
Reset cause: WDOG
Board: DIMM-MX6
DRAM:  1 GiB
PMIC:  PFUZE100 device id=10
MMC:   FSL_SDHC: 0, FSL_SDHC: 1, FSL_SDHC: 2
SF:    Detected MX25L6405D with page size 64 KiB, total 8 MiB
No panel detected: default to UMSH
In:    serial
Out:   serial
Err:   serial
Net:   FEC [PRIME]
Hit any key to stop autoboot:  0
DIMM-MX6 U-Boot > setenv nfsroot /nfsroot/dimm-mx6q/root/rootfs
DIMM-MX6 U-Boot > setenv serverip 172.26.1.3
DIMM-MX6 U-Boot > saveenv
Saving Environment to SPI Flash...
SF:    Detected MX25L6405D with page size 64 KiB, total 8 MiB
Erasing SPI flash...Writing to SPI flash...done
DIMM-MX6 U-Boot > run restore_sys
```



```

+
+ Log from Linux Kernel Starting..
+
+-----+

Executing init script S60 for passing kernel command line
cmdline= console=ttyMX6q,115200n8 serverip=172.26.1.3 empurs_cmd=production
boot_mode=nfs boot_dir=/nfsroot/dimm-mx6q/root/rootfs ip=dhcp
Parsing result SERVERIP=172.26.1.3 EMPURS_CMD=production BOOT_MODE=nfs
BOOT_DIR=/nfsroot/dimm-mx6q/root/rootfs
#####
#####
##### script /usr/sbin/emPURS is executed
#####
#####
#####
##### USAGE: The script requires four parameters.
#####
#####
#####
##### 1st parameter: command(etc. production, update_kernel, update_rfs)
#####
##### 2nd parameter: ipaddress of the server
#####
##### 3rd parameter: boot mode nfs or tftp
#####
##### 4th parameter: boot directory:
#####
##### tftp: path of the tftp subdirectory with the closing slash
#####
##### for example part1/part2/part3/
#####
##### nfs: path of the shared directory
#####
#####
#####
#####
**** SERVERIP ok
**** SERVERIP: 172.26.1.3
#####
##### BOOT_DIR= /nfsroot/dimm-mx6q/root/rootfs #####
#####
#####
##### NFS_SHARE= /nfsroot/dimm-mx6q #####
#####
#### Rescue CMD: production
#### Server IP: 172.26.1.3
#### Boot Mode: nfs
#### Boot Dir: /nfsroot/dimm-mx6q/root/rootfs
#### BOOT_DIR= /nfsroot/dimm-mx6q/root/rootfs
#### NFS_SHARE= /nfsroot/dimm-mx6q
#####
##### Do NOT power off or reset while producing board #####
##### producing without rescue system #####
#####
##### creating partitions on mmc0 #####
#####
*****
***** mmcblk0: INFO= 2095MB SIZE= 2095 UNIT= MB *****
*****
*****
##### detected unit MB #####
##### SIZE of linux partition: 2095 #####

```

```
#####          creating partitions on mmc0          #####
10+0 records in
10+0 records out
**** CREATING_PARTITIONS    ok
Model: SD 2GB (sd/mmc)
Disk /dev/mmcblk0: 2095MB
Sector size (logical/physical): 512B/512B
Partition Table: gpt
Disk Flags:

Number  Start   End     Size    File system  Name  Flags
  1      1049kB  512MB   511MB   ext3         linux
  2      512MB   2095MB 1583MB   ext3         data

#####
#####          formatting root partition          #####
#####
sh: -q: unknown operand
sh: -q: unknown operand
mke2fs 1.42.1 (17-Feb-2012)
Discarding device blocks: done
Filesystem label=
OS type: Linux
Block size=1024 (log=0)
Fragment size=1024 (log=0)
Stride=0 blocks, Stripe width=0 blocks
124928 inodes, 498688 blocks
24934 blocks (5.00%) reserved for the super user
First data block=1
Maximum filesystem blocks=67633152
61 block groups
8192 blocks per group, 8192 fragments per group
2048 inodes per group
Superblock backups stored on blocks:
    8193, 24577, 40961, 57345, 73729, 204801, 221185, 401409

Allocating group tables: done
Writing inode tables: done
Creating journal (8192 blocks): done
Writing superblocks and filesystem accounting information: done

mke2fs 1.42.1 (17-Feb-2012)
Discarding device blocks: done
Filesystem label=
OS type: Linux
Block size=4096 (log=2)
Fragment size=4096 (log=2)
Stride=0 blocks, Stripe width=0 blocks
96768 inodes, 386555 blocks
19327 blocks (5.00%) reserved for the super user
First data block=0
Maximum filesystem blocks=398458880
12 block groups
32768 blocks per group, 32768 fragments per group
8064 inodes per group
Superblock backups stored on blocks:
    32768, 98304, 163840, 229376, 294912

Allocating group tables: done
Writing inode tables: done
Creating journal (8192 blocks): done
Writing superblocks and filesystem accounting information: done

**** BOOT_PARTITION_FORMATED    ok
tune2fs 1.42.1 (17-Feb-2012)
Setting maximal mount count to -1
```

```

Setting interval between checks to 4294880896 seconds
tune2fs 1.42.1 (17-Feb-2012)
Setting maximal mount count to -1
Setting interval between checks to 4294880896 seconds
**** BOOT_PARTITION_TUNING   ok
EXT3-fs: barriers not enabled
kjournald starting. Commit interval 5 seconds
EXT3-fs (mmcblk0p1): warning: checktime reached, running e2fsck is recommended
EXT3-fs (mmcblk0p1): using internal journal
EXT3-fs (mmcblk0p1): mounted filesystem with writeback data mode
EXT3-fs: barriers not enabled
kjournald starting. Commit interval 5 seconds
EXT3-fs (mmcblk0p2): warning: checktime reached, running e2fsck is recommended
EXT3-fs (mmcblk0p2): using internal journal
EXT3-fs (mmcblk0p2): mounted filesystem with writeback data mode
**** MOUNTING_FS            ok
#####
##### preparing and filling rescue system #####
#####
#####
##### Do NOT power off or reset while getting the rfs #####
#####
##### Please wait while updating the root file system #####
##### This can take a few minutes #####
#####
#####
**** REQUESTING_RFS_STARTED   ok
**** INSTALLING_RFS_STARTED  ok
**** RFS_INSTALLED           ok
**** UNMOUNTING_FS           ok
#####
##### setting realtime clock #####
udhcpc (v1.19.4) startedvel: 6
Sending discover...
Sending select for 172.26.1.10...
Lease of 172.26.1.10 obtained, lease time 43200
Stopping syslogd/klogd: no syslogd found; none killed
Deconfiguring network interfaces... done.
Sending all processes the TERM signal...
Sending all processes the KILL signal...
Unmounting remote filesystems...
Deactivating swap...
Unmounting local filesystems...
Rebooting... Restarting system.

```

The system image and data partition are re-programmed and the system can be restarted.

## 5 Android Application quick start Guide

### 5.1 Preparation

First of all, you need the VM to run on your computer. You can use the provided VMware player and the emDroid VM included in the DVD with the starter kit.

The emDroid VM is an Ubuntu 12.04 LTS 32bits Linux machine with everything installed for you to start developing an Android Application.

The login and the password are the same: **hico**

Once you are up and running, you can power up your dim-mx6 development board and connect the USB Device (connector J23 the Cadun baseboard) to your computer.

When the Android operating system is functional on the development board, you can click on the android-studio application icon available on the emDroid VM:

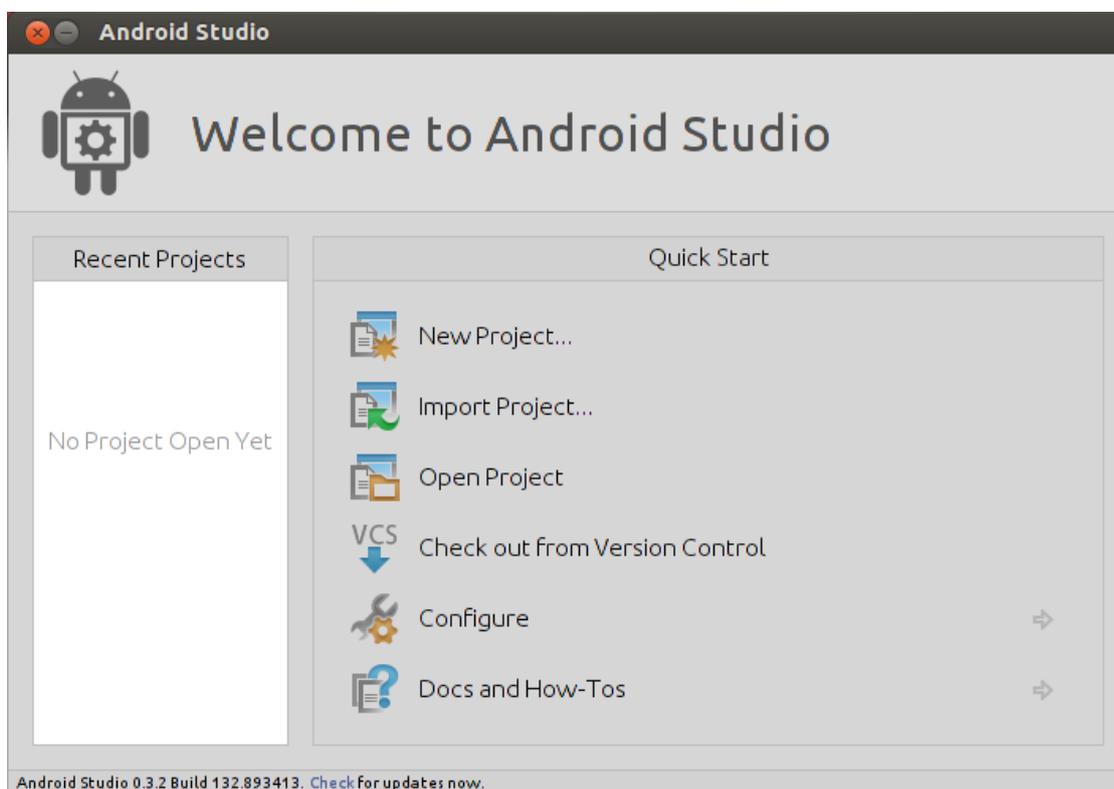


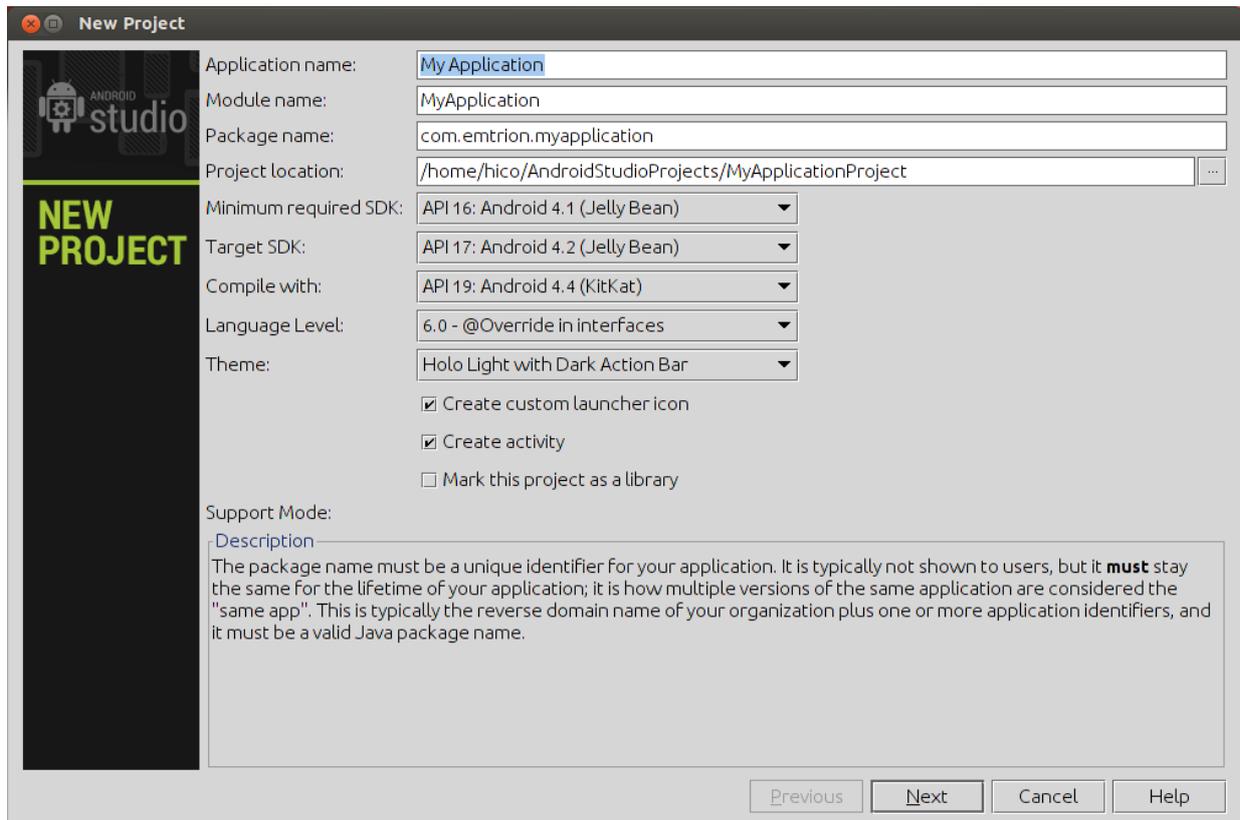
#### **android-studio**

The Android studio application is now starting you are reading to start.

### 5.2 My Application: an Hello World example

You can start by clicking on a new project or use the recent project if available.



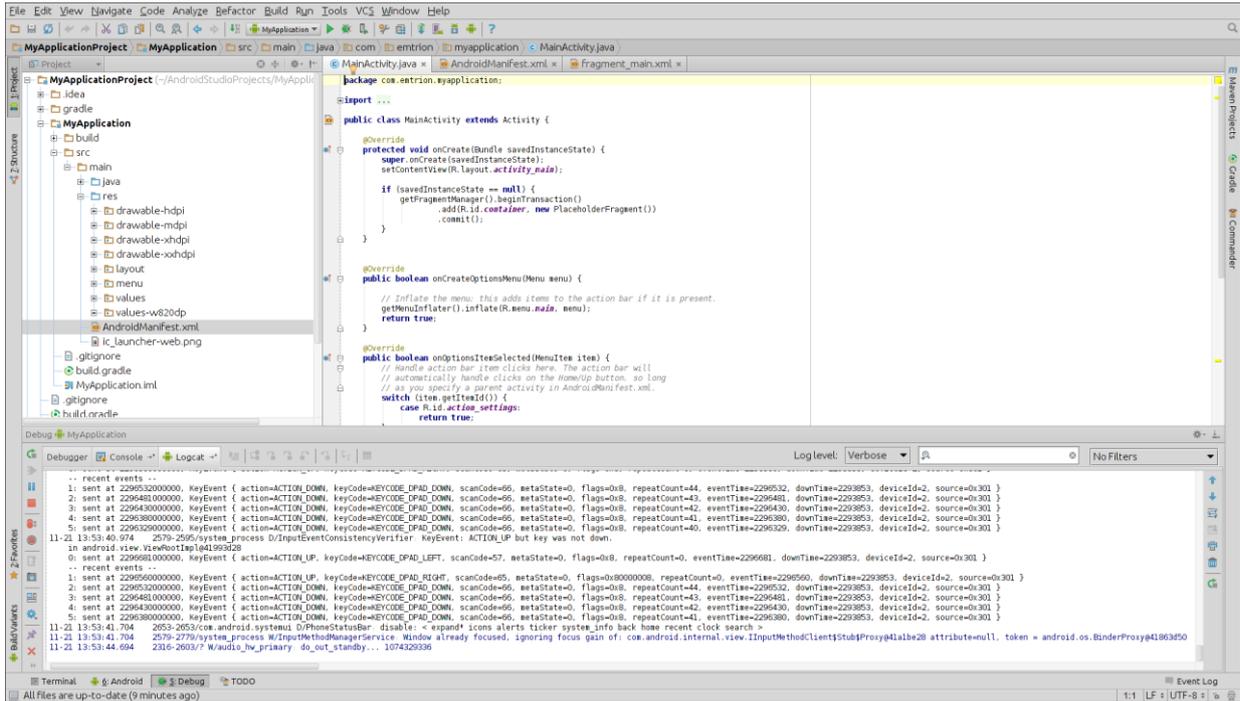


Follow the next instructions:

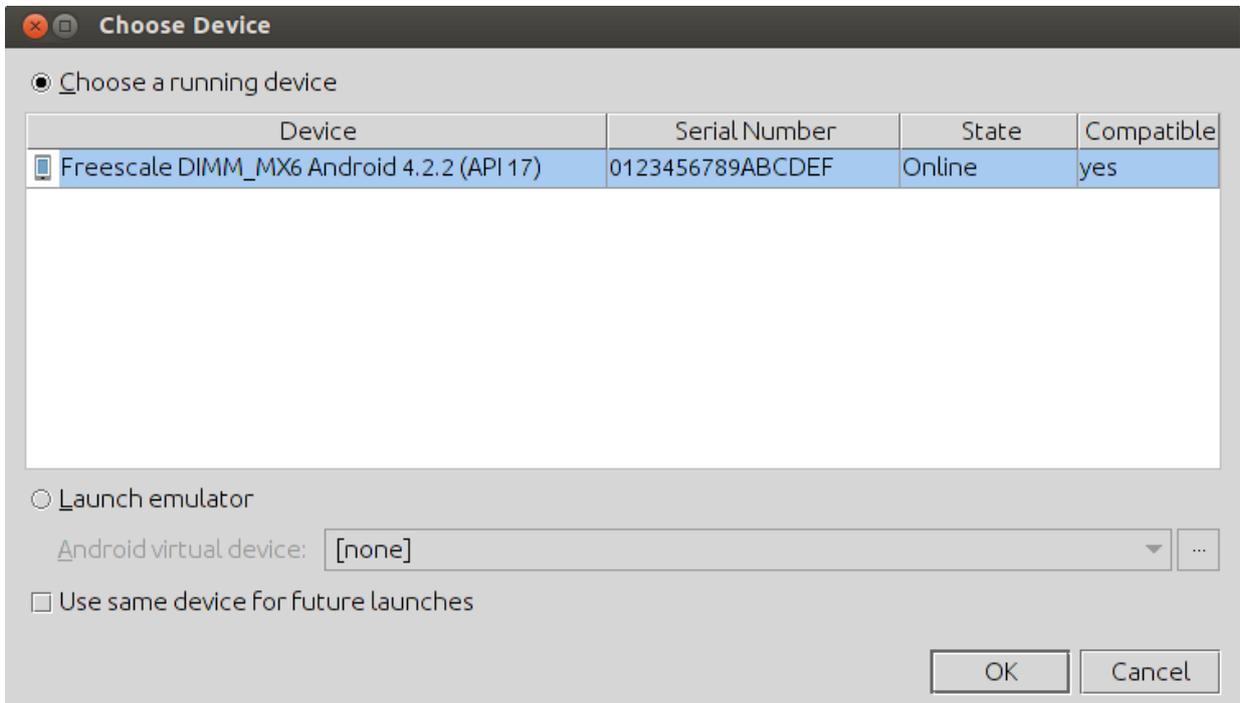
- 1) Name your project (ex: My Application)
- 2) In Package name: change com.example.myapplication (ex: com.emtrion.application)
- 3) Minimum required SDK: API 16 or API 17
- 4) Target SDK: API 17

Now, you click on "Next" until "Finish".

Now the IDE is launching. You are reading to start coding.

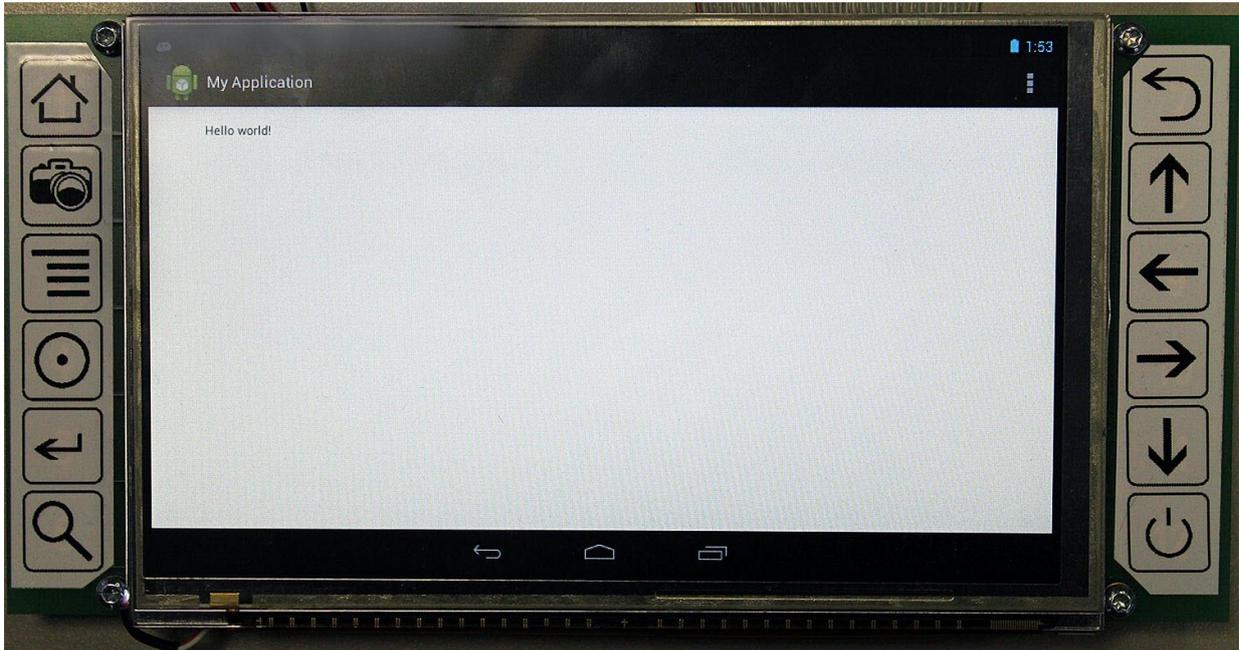


Once you are ready, you can either click on the green triangle run “My Application” to run the application in “release” mode or you can lunch the Debugger (the tiny green bug on the right).



The IDE ask you to choose the device. You normally should see the DIMM\_MX6 Android device.

Once running, you can see your Application on the Development board:

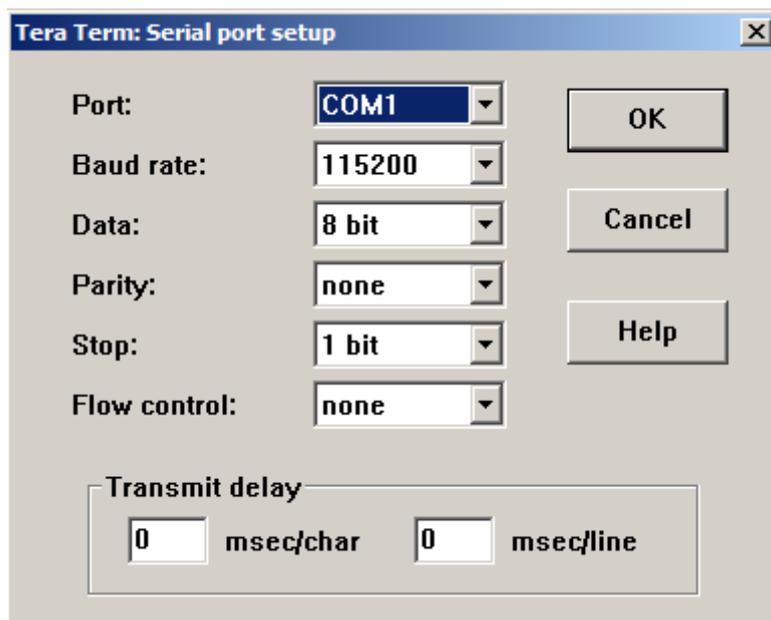


Congratulation you are running your first Android application on the DIMM-MX6!

## 6 Running Android via NFS

### 6.1 Setting up the bootloader:

First of all, connect your board to a serial line with the following parameter:



Then power up your board and hit quickly any keyboard key to stop the auto-boot like this:

```
U-Boot 2013.04-00005-g83a2fe5 (Oct 30 2013 - 14:25:50)
CPU: Freescale i.MX6Q rev1.2 at 792 MHz
Reset cause: WDOG
Board: DIMM-MX6
DRAM: 1 GiB
PMIC: PFUZE100 device id=10
MMC: FSL_SDHC: 0, FSL_SDHC: 1, FSL_SDHC: 2
SF: Detected MX25L64050 with page size 64 KiB, total 8 MiB
No panel detected: default to UMSH
In: serial
Out: serial
Err: serial
Net: FEC [PRIME]
Hit any key to stop autoboot: 0
DIMM-MX6 U-Boot > 
```

Then type the following line and hit enter:

```
set serverip xx.xx.xx.xx
```

with “xx.xx.xx.xx” being the ip address of your VM.

*Tips : You can find your ip address by just typing in a terminal “ifconfig” and you’ll find it on this line: “inet addr: 192.168.1.2”.*

Then type the following line and hit enter:

```
set nfsroot '/home/hico/android_nfs/dimm_mx6_android/root/rootfs'
```

and to finish, type the following line:

```
save
```

Then you can type this line to run the NFS on the target board:

```
run net_boot
```

***Normally, the target board will run Android after ~30 seconds.***

***If you want to run the Android on NFS at startup, type this command line:***

```
set bootcmd 'run net_boot'
```



## 7 Android for advanced user

### 7.1 Modifying the Android File System

Within the VM, you can modify files of the Android File System to modify the behavior. This is only recommended for advanced user as you can broke your NFS.

For example, you can modify the \*.RC files and change the log level of the OS.

Instead of modifying directly the File system here:

```
/home/hico/share/dimm-mx6q/root/rootfs/
```

You must do your change in:

```
/home/hico/dimm_mx6-fs
```

Once ready to test, you can start this script in the folder ~/script :

```
./mx6_prep_nfs.sh
```

The script copies all files from dimm\_mx6-fs folder to the NFS path with the proper files rights.

Now you can test your modification by testing via NFS (See [section 6](#)).

### 7.2 Rebuilding the package

When you are satisfied with your modified file system, you can build packages and flash it into your target.

To do this, simply run the following script in the folder ~/script:

```
./mx6_userland_package.sh
```

It creates the following packages in your Data partition (see [section 7.3](#)):

```
android-datafs-dimm_mx6.tar.bz2  
android-rootfs-dimm_mx6.tar.bz2
```

Then you can replace the packages files by the one in:

```
/home/hico/share/dimm-mx6q/images
```

And launch an update of the Android System (see [section 4.4](#))

### 7.3 Backup

The VM include an extra partition called "Data".

You can find it here:

```
/media/Data
```

Within this extra partition you find backups of your original Android file system and your original Android image. This is also the location of your custom packages build.

Present Archives:

- Images.tar.xz : the content of /home/hico/share/dimm-mx6q/images (i.e original packages system)
- dimm\_mx6-fs.tar.xy : the content of the Android NFS root file system.