

# IN-17 Display Module Tubes & Driver Board

User Manual

October 2013



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# **Revision History**

Date	Authors	Description
2013-10-05	Peter S'heeren	Initial release.



#### **1** Features

- Display module with 2 Russian IN-17 nixie tubes.
- I2C interface, module based on two PCA9865 PWM chips.
- Fully static, no need to multiplex the tubes.
- The brightness of each digit is individually controllable.
- The modules can be fitted into a standard 5.25" drive bay.
- Possibility to mount push button switches on the PCB for user control.
- RGB backlight LEDs for the tubes.
- Backlight is guided to the tubes using light pipes.
- Stacked PCB design using low profile MicroMatch connectors.
- Power supply +5V DC (logic) / +150 170V DC (tubes).
- Small size due to the extensive use of SMD components.
- Multiple modules can be daisy chained (max. 31 pcs. depending on HV power supply).
- The driver board can drive other nixie tubes as well, provided suitable connections are made.

## **2** Technical Specifications

IN-17 Display Module			
Weight	23 g (with IN-17 tubes and mechanical parts)		
Dimensions	32 mm x 43 mm x 38 mm (W x D x H)		

IN-17 Driver Board				
Weight	7 g			
Dimensions	32 mm x 43 mm x 10 mm (W x D x H)			

IN-17 Tubes Board				
Weight	15 g (with IN-17 tubes)			
Dimensions	32 mm x 43 mm x 33 mm (W x D x H)			





### **3** Safety Precautions

#### SAFETY PRECAUTIONS

WHEN THE MODULE IS POWERED ON, DO NOT TOUCH THE DRIVER BOARD OR TUBES BOARD.

THE SCREWS AND STANDOFF BETWEEN THE BOARDS ACT AS A CONDUCTOR FOR THE HIGH VOLTAGE ON THE TUBES. AVOID TOUCHING THE SCREWS AND STANDOFF WHEN THE HIGH VOLTAGE IS TURNED ON.

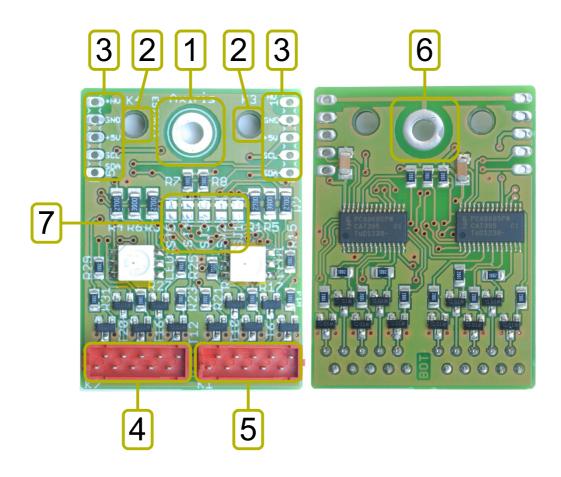
DO NOT EXERT FORCE ON THE TUBES, THEY MAY BREAK.

DO NOT ILLUMINATE MORE THAN TWO DIGITS WITHIN A TUBE. DRIVING MORE DIGITS MAY HEAT UP AND ULTIMATELY DESTROY THE RESISTORS ON THE TUBES BOARD.



## 4 IN-17 Driver Board

#### **Board Overview**

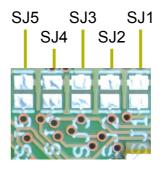


Mark	Label	Description					
1		Screw hole for fitting together the driver board and tubes board					
2	K3, K4	Screw holes for fixing the board to a surface					
3	+HV, GND, +5V, SCL, SDA	Solder pads for connecting and/or chaining the power supply, high voltage, I2C bus, and common ground					
4	K2	Connector for driving the cathodes in the right tube					
5 K1 Connector for driving the cathodes in the left tube							
6	6 Pad for conducting the tube power to the driver board						
7	SJ1, SJ2, SJ3, SJ4, SJ5	Solder jumpers for selecting the I2C addresses of the two PWM controllers					



#### I2C Address Selection (SJ1..SJ5)

Mark	Description
SJ1	A1 selection
SJ2	A2 selection
SJ3	A3 selection
SJ4	A4 selection
SJ5	A5 selection



When a solder jumper is left open ( $\mathbf{O}$ ), the selected address line is logically one. When a solder jumper is closed ( $\mathbf{\bullet}$ ), the selected address line is logically zero.

Use solder wick to open a previously closed solder jump.

Address line A0 is hardwired. For the PWM controller of the left tube, A0 is logically zero, while A0 of the PWM controller of the right tube is logically one.

SJ 5	SJ 4	SJ 3	SJ 2	SJ 1	Address Left Side	Address Right Side	Remarks
•	•	•	•	•	1000 000 b	1000 001 b	
•	۲	۲	•	0	1000 010 b	1000 011 b	
						•	
•	•	•	•	•	•	•	
•	•	•	•	•	•	•	
0	۲	0	0	0	1101 110 b	1101 111 b	
0	0	•	•	•	1110 000 b	1110 001 b	LED ALL CALL address is 1110 000 b. SUBADR1 by default is 1110 001 b.
0	0	•	•	0	1110 010 b	1110 011 b	SUBADR2 by default is 1110 010 b.
0	0	•	0	•	1110 100 b	1110 101 b	SUBADR3 by default is 1110 100 b.
0	0	۲	0	0	1110 110 b	1110 111 b	
0	0	0	٠	•	1111 000 b	1111 001 b	Addresses 1111 0XX b are used for the
0	0	0		0	1111 010 b	1111 011 b	10-bit addressing scheme.
0	0	0	0	•	1111 100 b	1111 101 b	Addresses 1111 1XX b are reserved for
0	0	0	0	0	1111 110 b	1111 111 b	future use.

You can't use the configuration in red. The reason is all PWM controllers will respond to the LED ALL CALL address after power-up.

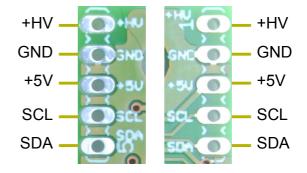
You can use the addresses in green providing there are no other I2C slaves on the bus that use these addresses. If you only connect IN-17 modules to the I2C bus, you can safely apply these addresses.

Refer to the NXP PCA9685 datasheet for more information.



#### **External Bus**

Mark	Description
+HV	High voltage
GND	Ground
+5V	5 V Power supply
SCL	I2C clock line
SDA	I2C data line



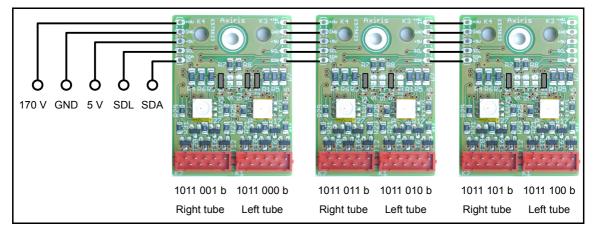
Connect a 170 V power supply to +HV.

SCL and SDA levels are 5 V. Connect these lines to an I2C bus.

The ground line is common for the 5 V and 170 V supplies and the I2C lines.

The external bus is exposed on two sides of the board allowing you to hook up multiple IN-17 display modules. The corresponding solder pads on each side are interconnected hence you're free to choose on which side to connect the various external lines.

Here's an example diagram featuring three IN-17 display modules:



The grey boxes denote closed solder jumpers (see SJ1..SJ5). The resulting I2C addresses for each display module are shown beneath the red connectors.



## 5 IN-17 Tubes Board

#### **Board Overview**

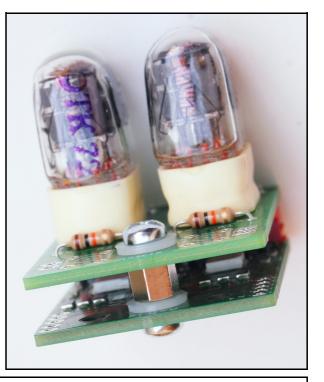


Mark	Label	Description
1		Screw hole for fitting the driver board and tubes board
2	S1, K3, S2, K4	Room for optional buttons



### **6** Setting up the Module

- 1. Close solder jumpers to configure the I2C addresses of the PWM controllers.
- 2. Solder wires on the pads of the external bus, either on one side or both, depending on your intended set up.
- 3. If applicable, fasten the driver board to a surface (screw holes K3 and K4).
- 4. If applicable, solder buttons and wires on the tubes board (S1, K3, S2, K4).
- 5. Fit the light pipe into the holes the tubes.
- 6. Put the tubes board into place on the driver board.
- 7. Bind the central screw holes. The screws and standoff serve as a conductor for the tube power (170 V). As such, the screws, washers and standoff **must be fitted exactly** as shown on the picture to the right.



#### WARNING!

When you put the tubes board into place on the driver board, do not exert force on the tubes, they may start to leak or break under the pressure. You can exert force on the printed circuit board instead.



## 7 Software

#### **Overview**

From a software point-of-view, the IN-17 display module provides two NXP PCA9685 chips on an I2C bus. The configuration of the solder jumpers (SJ1..SJ5) determines the I2C addresses of the PWM controllers.

Refer to the NXP PCA9685 datasheet for more information.

#### Initialization

You've to initialize the PWM controllers before programming the PWM channels. We recommend to program the chip's registers as follows (same for both chips):

MODE	MODE1						
Bit	Bit Name Value Meaning						
7	RESTART	0	Don't clear.				
6	EXCLK	0	Use internal clock.				
5	AI	1	Enable auto-increment.				
4	SLEEP	0	Normal mode (oscillator on).				
3	SUB1	0	Don't respond to I2C subaddress 1.				
2	SUB2	0	Don't respond to I2C subaddress 2.				
1	SUB3	0	Don't respond to I2C subaddress 3.				
0	ALLCALL	1	Respond to I2C address LED All Call.				
MODE	2						
Bit	Name	Value	Meaning				
75	-	000ъ	Reserved.				
4	INVRT	0	Output logic state not inverted.				
3	осн	1	Outputs change on I2C ACK after writing all 4 registers channel. <sup>[1]</sup>				
2	OUTDRV	1	The LED outputs are configured as a totem pole structure.				
10	OUTNE [10]	$10b$ When $\overline{OE}=1$ the LED outputs are high-impedance.					

<sup>[1]</sup> If you set OCH to 0, and you program PWM channels continuously and at great speed, the PWM controller's outputs may become invariant. This happens because the PWM controller needs time to latch new values after it receives the I2C STOP command; if new data comes in too quickly, the PWM controller won't get a chance to start using the values. With OCH set to 1, a PWM channel is programmed directly after I2C ACK and the PWM output changes right away.



#### Driving the Tubes and LEDs

Each PWM controller on the driver board steers one tube's digits and the underlying RGB LED.

Each PWM controller incorporates 16 PWM channels. The corresponding output pins are called LED[0..15]. Each PWM channel as a resolution of 12 bits for a value of 0..4095.

The PWM controller provides a prescaler setting for adjusting the duration of the PWM cycle. The default value is 30 which translates to 196.9 Hz. There's no need to reprogram this value.

The logic of a PWM output is either positive or negative. Positive logic means the target is fully illuminated when the PWM channel is maximally turned on. Negative logic means the target is fully illuminated when the PWM channel is completely turned off.

Output	Logic	Target	Output	Logic	Target
LED0	Positive	Digit 0	LED8	Positive	Digit 2
LED1	Positive	Digit 9	LED9	Positive	Digit 1
LED2	Positive	Digit 8	LED10	Negative	Blue
LED3	Positive	Digit 7	LED11	Negative	Red
LED4	Positive	Digit 6	LED12	Negative	Green
LED5	Positive	Digit 5	LED13	Not connected	
LED6	Positive	Digit 4	LED14	Not connected	
LED7	Positive	Digit 3	LED15	Not connected	

You may illuminate two or more digits and once. However, the more digits you drive, the more current will flow through the resistor next to the tube. If too much current flows through the resistor, it will heat up too much and break. The recommended limit is two fully illuminated digits, or the equivalent spread over more digits.



## 8 Disclaimer

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## **9** Contact Information

Official website: <u>http://www.axiris.be/</u>

