

MCH User Manual

Revision History:

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- Firmware version 2.10

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- Firmware version 2.4: added `get_iaa` and `sysreboot` commands, and Late Boot warning for the `fru` command

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- Updated the Manual for the second generation of Hardware

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1 Description:

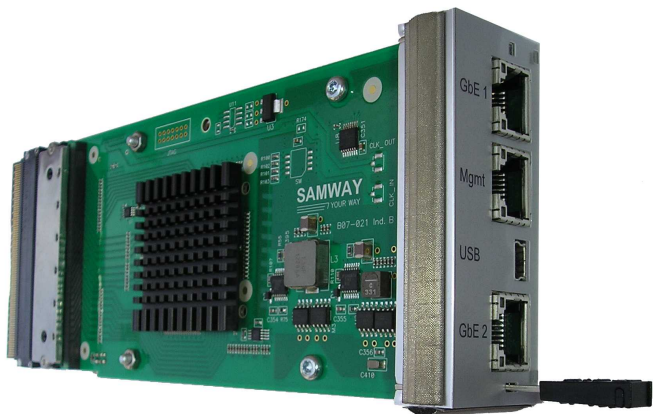


Illustration 1: Samway MCH

Key Features:

- *Compliant to IPMI 1.5.*
- *Compliant to MCTA.0:*
- *Compliant to MCTA.4:*
- *Compliant to HPM.1 firmware upgrade*
- *Redundant Operation*
- *Support for up to 12 AMCs, 12 uRTMs, 2 CUs and 4 PMs*
- *On-board Layer 2 unmanaged GbE Switch*
- *PCIe Gen 3 12 ports Switch*
- *2 Front panel GbE uplink ports*
- *Front panel 10/100Mbps port for management*
- *Front panel USB connector for debug*
- *On-board shelf manager*
- *Own IPMI software*
- *Firmware upgrade via IPMI commands (HPM.1), debug interface or TFTP remote transfer*
- *HTTP, DHCP, RMCP, and Telnet support*

The MicroTCA Carrier Hub (MCH) is the heart of any MicroTCA System. Its main functions include IPMI controlled power management, Electronic keying, Hot-swap of Advanced Mezzanine Cards (AMC), Micro Rear Transition Modules (uRTM), Cooling Units (CU) and Power Modules (PM).

Samway's MCH supports up to 12 AMCs, 12 uRTMs, 2 CUs and 4 PMs, and is compliant to MicroTCA specifications MCTA.0, MCTA.1, MCTA.4.

Firmware upgrade is easily accomplished using the on-board debug interface, IPMI commands (HPM.1) or remote access: TFTP.

MCH Redundancy is supported.

The MCH has been thoroughly tested at the Interoperability Workshops organized by PICMG.

The firmware uses a Samway Proprietary IPMI library and thus can be easily customized for nonstandard MicroTCA solutions.

The product architecture is highly flexible and allows mezzanine add-ons: Clock Distribution Module and PCIe Module.

The starting point of the configuration is the base board that provides the mandatory carrier manager and an unmanaged Layer 2 Gigabit Ethernet switch for Fabric A connectivity. The switch connects to all twelve ports of Fabric A using SERDES links and also to the two front panel up-link ports.

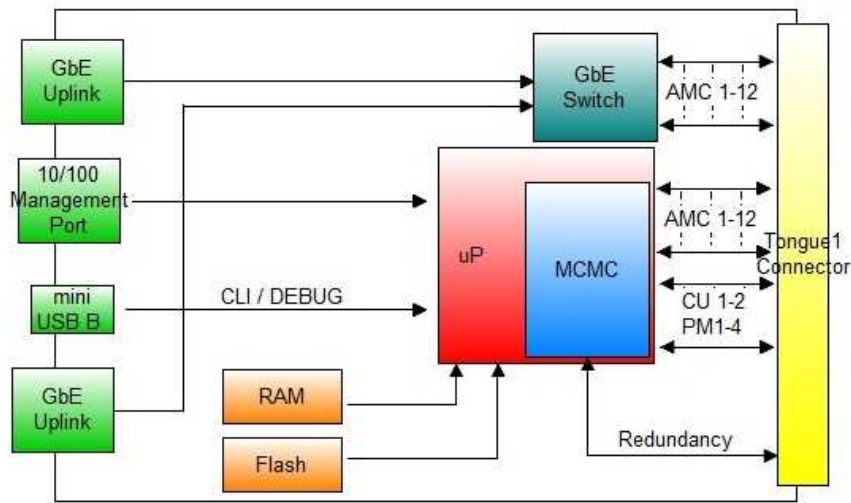


Illustration 2: Tongue 1: Base Board Block Diagram

The Clock Distribution Mezzanine supports CLK3 for PCIe Fabric Clock. The PCIe clock is distributed to all 12 AMCs and can be either a fixed frequency 100 MHz signal or a Spread Spectrum Clock (SSC). The fabric clock distribution circuit is compliant to the timing requirements of PCIe Gen 3 clocks.

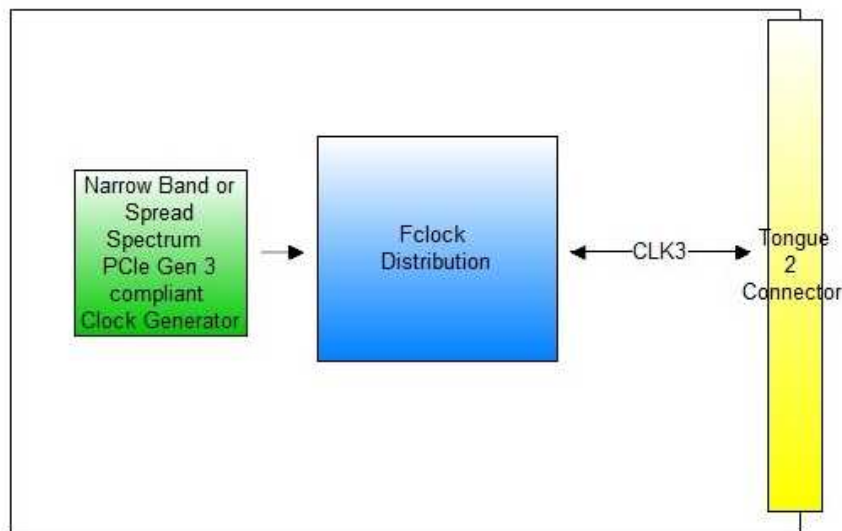


Illustration 3: Tongue 2: Clock Distribution Block Diagram

Upon request a more complex Clock Distribution Module can be developed, specially tailor to fit either the standard Telecom Clock 1 and Clock 2 requirements or custom, user defined ones.

The PCI Express Mezzanine provides a nonblocking PCI Express Gen3 switching architecture that supports up to 12 AMCs and flexible lane configuration of x1,x2,x4,x8 or even x16.

Up to 6 independent Virtual Switches that can split the PCIe domain into separate clusters can be defined. The module operates using the PCIe fabric clock generated by the Clock Mezzanine module.

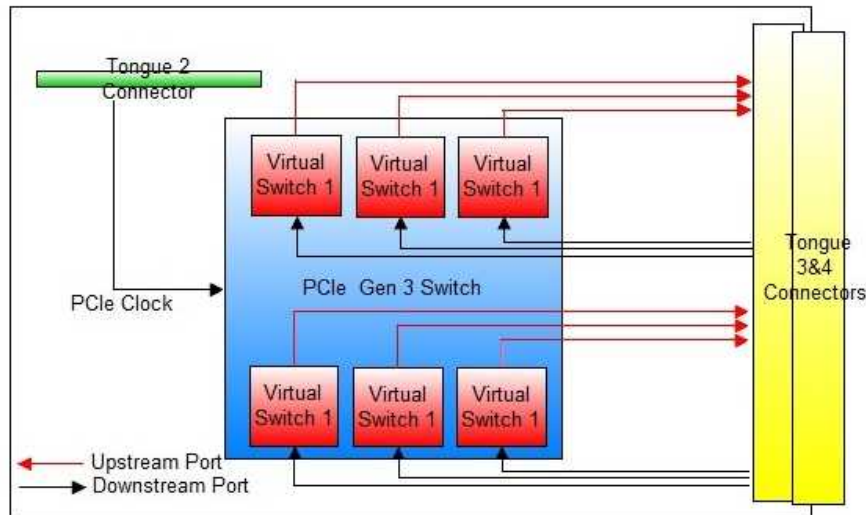


Illustration 4: Tongue 3: PCIe Gen 3 Switch Block Diagram

Each virtual switch configuration is highly flexible and each Virtual Switch has its own PCIe domain with dedicated upstream and downstream ports.

2 Front Panel and Connectivity



Illustration 5: Front Panel

The MCH has 4 Front panel connectors:

- 2 x GbE Uplinks (GbE1,GbE2)– RJ45 connectors directly linked with the 16 ports GbE Switch. The switch provides switching functionality for system Fabric A(1GbE).
- Mgmt – RJ45 connector for 10/100 [Ethernet management interface](#).
- USB – USB mini B connector for the [Serial interface](#) . It provides access to the on board [CLI \(command line interface\)](#)

The Samway-MCH is also equipped with the MicroTCA Hot-swap Handle and the LEDs defined in MicroTCA .

Name	Color	Description
Blue Led	Blue	Hot swap led
Led 1	Red	Status Led: off – Status ok Red – error present
Led 2	Green	On – PP is present

Table 1: MCH LEDs

3 IPMB interface

The MCH was developed based on the IPMI v1.5 specification.

3.1 Supported command list

IPM Device “Global” Commands	NetFn	CMD
Get Device ID	App	01h
Get Self Test Results	App	04h
BMC Device and Messaging Commands	NetFn	CMD
Send Message	App	34h
Get Channel Authentication Capabilities	App	38h
Get Session Challenge	App	39h
Activate Session	App	3Ah
Set Session Privilege Level	App	3Bh
Close Session	App	3Ch
Event Commands	NetFn	CMD
Set Event Receiver	S/E	00h
Get Event Receiver	S/E	01h
Platform Event	S/E	02h
Sensor Device Commands	NetFn	CMD
Get Device SDR Info	S/E	20h
Get Device SDR	S/E	21h
Reserve Device SDR Repository	S/E	22h
Set Sensor Threshold	S/E	26h
Get Sensor Threshold	S/E	27h
Get Sensor Reading	S/E	2Dh
FRU Device Commands	NetFn	CMD
Get FRU Inventory Area Info	Storage	10h
Read FRU Data	Storage	11h
Write FRU Data	Storage	12h
SDR Device Commands	NetFn	CMD
Get SDR Repository Info	Storage	20h
Reserve SDR Repository	Storage	22h
Get SDR	Storage	23h
SEL Device Commands	NetFn	CMD
Get SEL Info	Storage	40h
Reserve SEL	Storage	42h
Get SEL Entry	Storage	43h
Clear SEL	Storage	47h

Get SEL Time	Storage	48h
Set SEL Time	Storage	49h
AdvancedTCA Commands	NetFn	CMD
Get PICMG Properties	PICMG	00h
Get Address Info	PICMG	01h
FRU Control	PICMG	04h
Get FRU LED Properties	PICMG	05h
Get LED Color Capabilities	PICMG	06h
Set FRU LED State	PICMG	07h
Get FRU LED State	PICMG	08h
Set FRU Activation Policy	PICMG	0Ah
Get FRU Activation Policy	PICMG	0Bh
Set FRU Activation	PICMG	0Ch
Set Power Level	PICMG	11h
Get Fan Speed Properties	PICMG	14h
Set Fan Level	PICMG	15h
Get Fan Level	PICMG	16h
AdvancedMC Commands	NetFn	CMD
Set AMC Port State	PICMG	19h
MicroTCA Commands	NetFn	CMD
Power Channel Control	PICMG	24h
Get Power Channel Status	PICMG	25h
PM Reset	PICMG	26h
PM Heartbeat	PICMG	28h

Table 2: Supported Commands List

4 Ethernet Management interface

The integrated 10/100Mbps Ethernet interface allows the MCH to be linked to any existing network. The interface supports DHCP, TFTP, HTTP and TELNET protocols via TCP/IP and UDP.

The user has full access to the commands of the Command Line Interface (CLI) via TELNET, allowing remote control of the MCH.

The use of standard protocols avoids the need for special software or drivers and so achieves platform-independence. The TCP/IP protocol supports 10 simultaneous connections and the maximum packet size is limited to 1k.

- ! The factory default setting for the MCH is DHCP enabled so it negotiates automatically all the necessary addresses. If a fixed IP address is desired, DHCP must be disabled and the address has to be set manually. For all these operations the *lanconfig* command needs to be used.

4.1 WEB

The MCH includes a built in WEB server that provides a simple way to access the management information.

4.1.1 Overview

The WEB page can be designed as a graphical representation of the System Platform, thus providing a very intuitive way of obtaining system / board information.(The illustration bellow exemplifies the web page for a 12 slot system) . The available information includes:

- Board / Carrier /Shelf Field Replaceable Unit (FRU) information file (Manufacturer's Name, Part number, Serial Number, Board Connectivity Records)
- Sensors information: value, name,measuring unit, status,threshold and hysteresis values
- System Event Log (SEL) : sensor events
- MCH attributes: MAC address, Serial number, Firmware version

Blu Two T **1**

2

3

Information

```

INTERNAL USE AREA
Internal Use Area missing

BOARD INFO AREA
Board Manufacturer: Samway
Board Product Name: MCH
Board Part Number: P07-009

PRODUCT INFO AREA
Manufacturer Name: Samway
Product Name: MCH
Model Number: P07-009
Product Version: Rev B

MULTIRECORD AREA

Module Current Requirement
Amp=3.0

AMC P-P Connectivity
On-Carrier Fabric A

ChID:0 Lane0:P0 Lane1: - Lane2: - Lane3: -
ChID:1 Lane0:P1 Lane1: - Lane2: - Lane3: -
ChID:2 Lane0:P2 Lane1: - Lane2: - Lane3: -
ChID:3 Lane0:P3 Lane1: - Lane2: - Lane3: -
ChID:4 Lane0:P4 Lane1: - Lane2: - Lane3: -
ChID:5 Lane0:P5 Lane1: - Lane2: - Lane3: -
ChID:6 Lane0:P6 Lane1: - Lane2: - Lane3: -
ChID:7 Lane0:P7 Lane1: - Lane2: - Lane3: -
ChID:8 Lane0:P8 Lane1: - Lane2: - Lane3: -
ChID:9 Lane0:P9 Lane1: - Lane2: - Lane3: -
ChID:10 Lane0:P10 Lane1: - Lane2: - Lane3: -
ChID:11 Lane0:P11 Lane1: - Lane2: - Lane3: -

Link:0 ChID:0 L0 Eth 1000Base-BX Asym. Match = 0 Gr. Id = 0
Link:1 ChID:1 L0 Eth 1000Base-BX Asym. Match = 0 Gr. Id = 0
                    
```

4

Sensor	Name	Value	Unit	Status
1	Hot Swap	Handle Closed		
2	+3.3V	3.39	V	OK
3	+12V	11.96	V	OK
4	Temp1	39.00	deg C	OK
5	Temp2	39.00	deg C	OK

5

6536. 5/1/1970 6:24:2 Addr: 0x00 LUN: 0 No: 242
6537. 5/1/1970 6:24:2 Addr: 0x00 LUN: 0 No: 243
6543. 5/1/1970 7:32:18 Addr: 0x00 LUN: 0 No: 242
6544. 5/1/1970 7:36:34 Addr: 0x00 LUN: 0 No: 243
6546. 5/1/1970 0:4:18 Addr: 0x00 LUN: 0 No: 242

6

Clear SEL log

Mac Address:	00:50:C2:F2:50:3C
Serial No:	04022014
Host name:	MCH
FirmWare:	2.10

7

8 Uptime: 00:02:06

Illustration 6: Example Web page for a uTCA system

The default Layout for the Web Page is composed of several areas:

1. *Title*: user defined
2. *Logo*: user defined
3. *Dynamic System Platform Representation*:: The images are populated or removed depending on the hot-swap state of the boards. Both system platform and boards are treated as objects and can be selected using a mouse click. The information in panes 4. *FRU info* and 5. *Sensor info* is changed depending on the selected object.

4. *FRU info*: displays the FRU information for the selected object(board or system platform)
5. *Sensor info*: displays the values, names and status for all the sensors of the selected object. All the sensors are considered objects and can be selected using a mouse click.
6. *System Event Log (SEL)*: displays all the sensor events received by the MCH starting from the moment the Web page has been loaded.
7. *Info Area*: displays more details for the selected sensor (threshold and hysteresis values) or, if no sensor is selected, displays MCH attributes: MAC address, Serial number, Firmware version.
8. *Uptime* : displays the amount of time the MCH has been operational. It is reset at each MCH restart.

4.1.2 Architecture

The Web Server uses a Representational State Transfer (REST) based architecture and Extensible Markup Language (XML) files.

REST is an architectural style that abstracts the architectural elements within a distributed hypermedia system. REST ignores the details of component implementation and protocol syntax in order to focus on the roles of components, the constraints upon their interaction with other components, and their interpretation of significant data elements. REST has emerged as a predominant web API design model.

XML is a markup language that defines a set of rules for encoding documents in a format that is both human-readable and machine-readable. The design goals of XML emphasize simplicity,generality, and usability over the Internet.

The MCH WEB page is composed of:

- objects : board and system images; sensors
- information display areas

When an object is selected by a mouse click, the web browser requests predefined XML files using predefined commands. The information contained by the XML files returned by the MCH is parsed in the information display windows.

The XML files could also be requested by an application software in case a custom managing solution is required. The format of the XML files is described in the following chapter.

4.1.3 REST Commands

“/settings”

For this request the MCH returns an XML file containing the following tags:

- <mac_addr>
- <serial_no>
- <host_name>
- <firmware> : firmware version
- <uptime> : the amount of time the MCH has been operational
 - <H>: hours
 - <M>: minutes
 - <S>: seconds

Request: GET /**settings**

IP Address/**settings** (ex: 192.168.16.1/settings)

Response:

```
<?xml version="1.0"?>
<settings>
<mac_addr>0:80:194:242:80:0</mac_addr>
<serial_no>0000000000</serial_no>
<host_name>MCH_2013</host_name>
<firmware>1.6</firmware>
<uptime>
  <H>0</H>
  <M>31</M>
  <S>21</S>
</uptime>
</settings>
```

“/frustatus”

For this request the MCH returns an XML file that contains the following tags:

- **<boot_cnt>**: boot index. The index is incremented at each MCH start-up.
- **<sel_cnt>**: System Event Log (SEL) index. The index is incremented when an event is added to the SEL. This field is used to detect if new events have occurred.
- **<fru_list>**: a list with all the modules(FRUs) present in the system(including the MCH)
- **<fru_addr>**: the IPMB address of the module
- **<fru_id>**: active FRU ID. The Module Management Controller (MMC) is always represented by FRU ID 0 and is always present for active modules. Additional FRU IDs can also be active.

Request: GET /**frustatus**

IP Address/**frustatus** (ex: 192.168.16.1/frustatus)

Response:

```
<?xml version="1.0"?>
<fru_status>
<boot_cnt>315</boot_cnt>
<sel_cnt>9791</sel_cnt>
<fru_list>
  <fru_addr addr="0x00">
    <fru_id>0</fru_id>
  <fru_addr addr="0x82">
    <fru_id>0</fru_id>
  </fru_addr>
  <fru_addr addr="0x84">
    <fru_id>0</fru_id>
  </fru_addr>
  <fru_addr addr="0x86">
    <fru_id>0</fru_id>
  </fru_addr>
  <fru_addr addr="0x10">
    <fru_id>0</fru_id>
  </fru_addr>
</fru_list>
</fru_status>
```

“/sel/start_index/end_index”

This command retrieves multiple SEL event records. The command use two indexes (start,end) to define the desired number of records. The MCH returns an XML file that contains all the event records that

have an index between the start index and the end index. The XML file uses the following tags:

- `<rec id>` : the index of the current record
- `<tmp>` : the time when the event was triggered
- `<addr>`: address of the card that launched the event
- `<lun>`: the LUN on which the sensor resides
- `<no>`: sensor number
- `<name>`: sensor name
- `<type>`: code representing the sensor type
- `<sta>`: sensor state, available only for discrete sensors
- `<ev_type>`: threshold that triggered the event for threshold sensors: UNR (upper non-recoverable), UC(upper critical), UNC(upper non-critical), LNC (lower non-critical), LC(lower critical), LNR(lower non-recoverable)
- `<ev_dir>` Asserted, DeAsserted
- `<val>`: sensor value
- `<thr>`: threshold value

Request: GET `/sel/start_index/end_index`

IP Address/`sel/start_index/end_index` (ex: 192.168.16.1/sel/1/2)

Response:

```
<?xml version="1.0"?>
<sel>
  <rec id="1">
    <tmp>1325376000</tmp>
    <addr>0x72</addr>
    <lun>0</lun>
    <no>97</no>
    <name>MCH Power ON</name>
    <type>192</type>
    <sta>0</sta>
  </rec>
  <rec id="2">
    <tmp>1325376000</tmp>
    <addr>0x72</addr>
    <lun>0</lun>
    <no>2</no>
    <name>V0</name>
    <type>2</type>
    <ev_type>LNC</ev_type>
    <ev_dir>Asserted</ev_dir>
    <val>0.00</val>
    <thr>2.86</thr>
  </rec>
</sel>
```

`"/fruinfo/FRU_Address/FRU_Id"`

This command retrieves a **text file** containing the FRU information for the desired FRU Id on the specified card. The command uses two parameters:

- *FRU_Address*: the IPMB address of the card(hexadecimal value)
- *FRU_Id*: used to distinguish between multiple FRUs located on the same card. The FRU Id for the Module Management Controller (MMC),(the card itself) is 00.

Request: GET `/fruinfo/FRU_Address/FRU_Id`

IP Address/`fruinfo/FRU_Address/FRU_Id`(ex: 192.168.16.1/fruinfo/0x82/0)

Response(text file):

```
INTERNAL USE AREA 0x01 0x02 0x03 0x04 0x05 0x06 0x07 0x08 0x09 0x0A 0x0B 0x0C
0x0D 0x0E 0x0F 0x00 RODUCT INFO AREA Manufacturer Name: SAMWAY Product Name:
Test Board MULTIRECORD AREA Module Current Requirement Amp=1.0
```

“/sensor/FRU_Address/FRU_Id”

This command retrieves all the sensor associated to a FRU Id of a card. The command uses two parameters:

- *FRU_Address*: the IPMB address of the card(hexadecimal value)
- *FRU_Id*: used to distinguish between multiple FRUs located on the same card. The FRU Id for the Module Management Controller (MMC),(the card itself) is 00.

If this parameter is missing the MCH will return the sensors associated to FRU Id 0

The MCH responds to this request using an XML file that contains the following tags:

```
<name>:sensor name
<value>:sensor value
<unit>:sensors unit of measurement
<state>:sensor state (lnr, lc, lnc, unc, uc, unr)
```

Request: GET **/sensor/FRU_Address/FRU_Id**

IP Address/**/sensor/FRU_Address/FRU_Id**(ex: 192.168.16.1/sensor/0x82)

Response:

```
<?xml version="1.0"?>
<sensor_list>
  <sensor no="1">
    <name>Hot Swap</name>
    <value>Handle Open </value>
  </sensor>
  <sensor no="2">
    <name>V0</name>
    <value>0.00</value>
    <unit>V</unit>
    <state>lnr</state>
  </sensor>
</sensor_list>
```

“/sdr/FRU_Address/sensor_No”

This command retrieves additional information for a specific sensor on the desired card. The command uses two parameters:

- *FRU_Address*: the IPMB address of the card(hexadecimal value)
- *sensor_No*: sensor number for the desired sensor

The MCH responds to this request using an XML file that contains the following tags:

- **<name>**
- **<entity_id>** : entity id for the sensor's owner
- **<entity_instance>** :entity instance for the sensor's owner
- **<unr>**: upper non-recoverable threshold value, if the unr threshold is enabled
- **<uc>**: upper critical threshold value, if the uc threshold is enabled
- **<unc>**: upper non-critical threshold value, if the unc threshold is enabled
- **<lnc>**: lower non-critical threshold value, if the lnc threshold is enabled
- **<lc>**: lower critical threshold value, if the lc threshold is enabled
- **<lnr>**: lower non-recoverable threshold value, if the lnr threshold is enabled
- **<hyst_pos>**: positive going hysteresis value

- <hyst_neg>: negative going hysteresis value
- <nominal_reading>
- <normal_maximum>
- <normal_minimum>
- <maximum_reading>
- <minimum_reading>

Request: GET /sdr/FRU_Address/sensor_No

IP Address /sdr/FRU_Address/sensor_No(ex: 192.168.16.1/sensor/0x10/5)

Response:

```
<?xml version="1.0"?>
<sensor no="5">
  <name>V3</name>
  <entity_id>0x01</entity_id>
  <entity_instance>0x61</entity_instance>
  <uc>-11.34</uc>
  <lc>-12.64</lc>
  <hyst_pos>0.07</hyst_pos>
  <hyst_neg>0.07</hyst_neg>
  <nominal_reading>-14.00</nominal_reading>
  <normal_maximum>-14.00</normal_maximum>
  <normal_minimum>-14.00</normal_minimum>
  <maximum_reading>2.58</maximum_reading>
  <minimum_reading> -14.00</minimum_reading>
</sensor>
```

“/picture/FRU_Address”

This command retrieves the pictures for the boards and system platform.

- *FRU_Address*: the IPMB address of the card(hexadecimal value). For the picture of the System platform the request uses FRU_Address = 0.

Request: GET /picture/FRU_Address

IP Address /picture/FRU_Address(192.168.16.1/picture/0x80; 192.168.16.1/picture/0)

Response: picture file

4.1.4 How it all works

The web page has 2 operational states: Initialization and Normal Operation. A functional diagram of the default web page operation can be found bellow.

At start-up, and each time it is re-initialized, the web page is empty. The Web page requests and saves the MCH settings (GET/settings): MAC Address, Serial Number, Firmware Version,Uptime. The page also saves some parameters from the response of the frustatus request: Boot count, SEL count.

Next, the web page request information for the system platform(FRU 0): picture, FRU info, sensors. (GET/picture/0, GET/fruinfo/0/0, GET/sensor/0/0). Once the information is received, the web page displays it.

After the system platform is initialized the init phase ends. By default all boards are considered absent during this phase.

The normal operation phase of the web page is split in two processes:

- A periodical process that check to see if new boards have been inserted, or if boards have been removed
- A mouse click listener that changes the active object

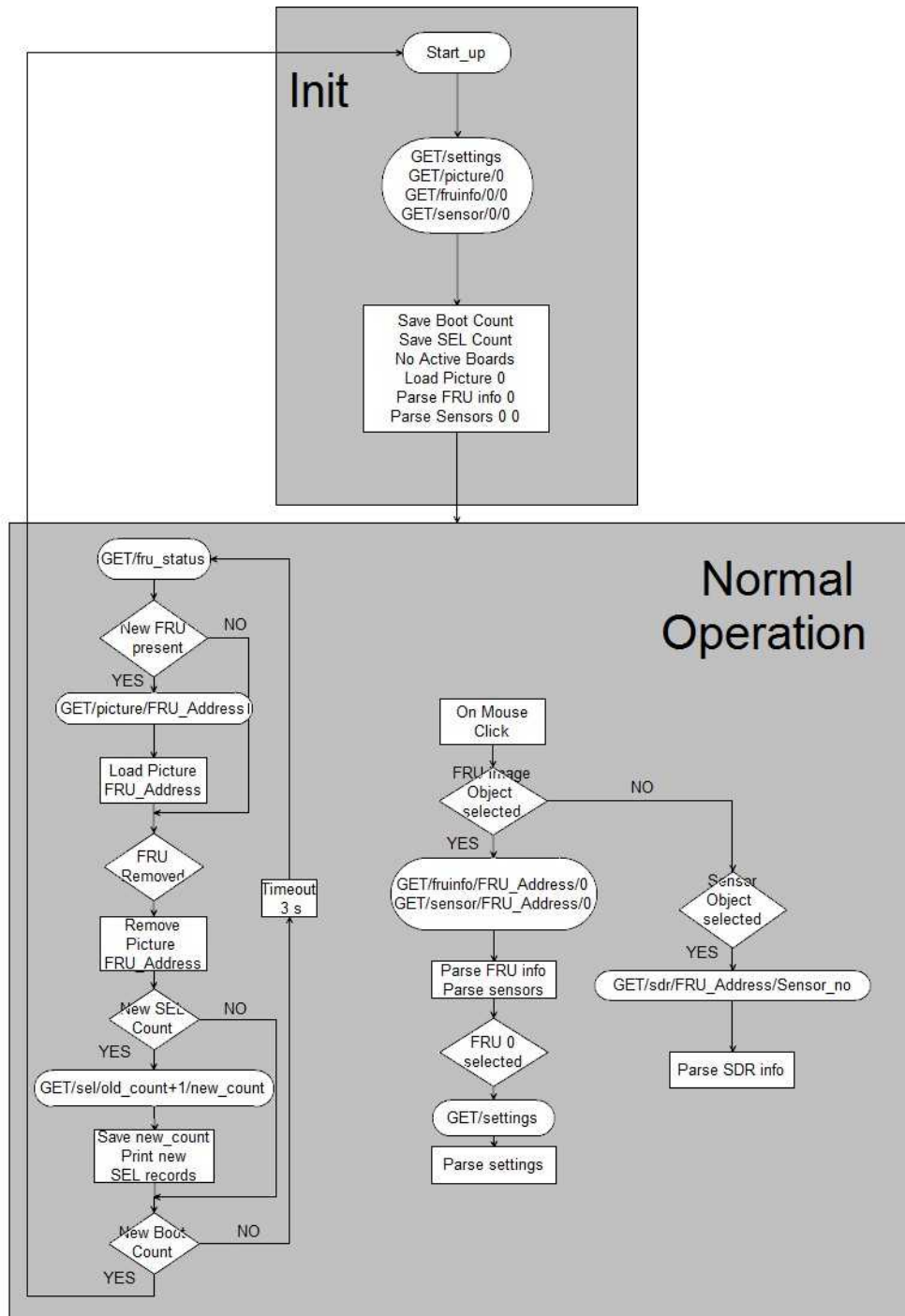


Illustration 7: Representation of Web Page operation

The periodic process issues a **GET/frustatus** request at every 3 seconds. By comparing the FRU list in the response and the FRUs loaded, the page determines if boards have been inserted or removed. For all the new boards the web page sends a **GET/picture/FRU_Address** request and loads the received picture. For all the boards that have been removed, the web page also removes the picture.

Using the response for the **frustatus** request the web page also checks if new SEL events have occurred. If the SEL count from the response is different from the one saved by the page, a **GET/sel/old_count+1/new_count** request is sent. Using the response the web page displays all the new SEL events.

The **frustatus** request is also used to detect restarts of the MCH. If the Boot count in the response is different than the saved one, the WEB page is restarted: all pictures are removed and all the internal

variables are reinitialized.

The WEB page uses a mouse click listener to determine if the current selected object has been changed. The WEB page uses two types of objects:

- FRU images
- FRU sensors

At each mouse click the WEB page determines if the active object has been changed.

If the active FRU image object has been changed, the WEB page request the FRU info and sensors for the new active object: **GET/fruinfo/FRU_Address/0**, **GET/sensor/FRU_Address/0**. Using the responses of the requests, the web page updates the information visible in the *FRU Info* and *Sensor Info* panels. By default, at start-up, the active image object is the system platform (FRU 0).

If the active sensor object has been changed, the WEB page request the detailed information of the new active sensor: **GET/sdr/FRU_Address/Sensor_No**. Using the response for the sdr request, the WEB page updates the information in the *Info Area* panel. By default, at start-up no sensor object is selected and the Info are panel displays MCH parameters: MAC address, Serial No., Firmware version.

After the first sensor object becomes active, the *Info Area* panel will display sensor information. To return to displaying MCH parameters, a click on the system platform image is necessary.

4.2 Telnet

The Telnet interface can be used to gain access to the Command Line Interface (CLI). The CLI is accessible if the operator is logged on as “user” or “admin” profile.

Terminal settings:

- Local echo: *off*
- Local line editing: *off*
- Backspace key: *Control-H*

For the default access settings refer to the CLI chapter.

4.3 RMCP

The MCH supports Remote Management Control Protocol (RMCP). The RMCP connections requires authentication. The supported authentication protocol is MD5. Two user names are accepted for RMCP connections: “user” – with “User” privilege level and “admin” with “Administrator” privilege level. The user names and privilege levels are fixed, they cannot be changed through IPMI commands. The password used are the same passwords configured for the CLI. The default passwords are: “USER” – for “user” profile and “ADMIN” - for admin profile.

4.4 DHCP

The MCH supports Dynamic Host Configuration Protocol (DHCP). With DHCP, the MCH request IP addresses and networking parameters automatically from a DHCP server, reducing the need for a user to configure these settings manually.

4.5 TFTP

The MCH supports Trivial File Transfer Protocol (TFTP) for updating it's firmware or the on-board web page. TFTP is a simple, lock-step, file transfer protocol which allows a client to get a file from a remote

host. TFTP allows remote firmware/ web page update and also significantly reduces the upload time when compared to the RS232 xmodem alternative.

5 Serial interface

The MCH provides a serial interface over which the commands of the Command Line Interface (CLI) can be sent.

The CLI is available via the front panel USB mini B connector.

5.1 Driver

The Samway-MCH uses the [FT232R](#) chip for converting the serial Command Line Interface to USB signals.

! For successfully connecting a PC to the MCH, a Virtual COM port (VCP) driver is required. Usually the appropriate driver is automatically detected and installed by the operating system.

In case the operating system fails to install the correct driver, you can download the latest driver for FT232R from [here](#), and follow the instructions of the [installation guides](#).

5.2 Terminal Program

Once the driver has been successfully installed you can connect to the MCH using any terminal program.

On Windows systems, we recommend the use of “TeraTerm” or “Hyperterminal” as terminal programs.

Terminal settings:

- 19200 bits per second (default baud rate); this baud rate can be changed using “**scispeed**” CLI command
- data bits: 8
- parity: none
- stop bit: 1

In addition, the “**xmodem**” CLI command can be used for file transfer.

6 Redundant Operation

The MCH supports redundant operation. At each start-up primary and redundant status is negotiated by the two MCHs. After the negotiation is done the primary MCH will start to actively manage the Chassis.

The redundant MCH will remain inactive until a switch-over changes its role to primary. The switch-over can be triggered by a CLI command, a reboot, hot-swapping, or a failure of the primary MCH.

7 Field Replaceable Unit (FRU) Management

The MCH manages and controls all FRUs residing in a MicroTCA Carrier (AdvacendMCs, Power Modules, Cooling Units, OEM Modules) through a set of signals controlled by the PMs and its IPMB interfaces.

The communication between the MCH and the other FRUs takes place over the IPMB-L and IPMB-0 interfaces.

The MCH uses I2C buffers to connect to IPMB-A, IPMB-B and all twelve IPMB-L buses, thus being able to disconnect a faulty AMC without losing communication with the other ones.

Regardless of the FRU type, the way it is managed by the MCH is similar and can be described by the following diagram:

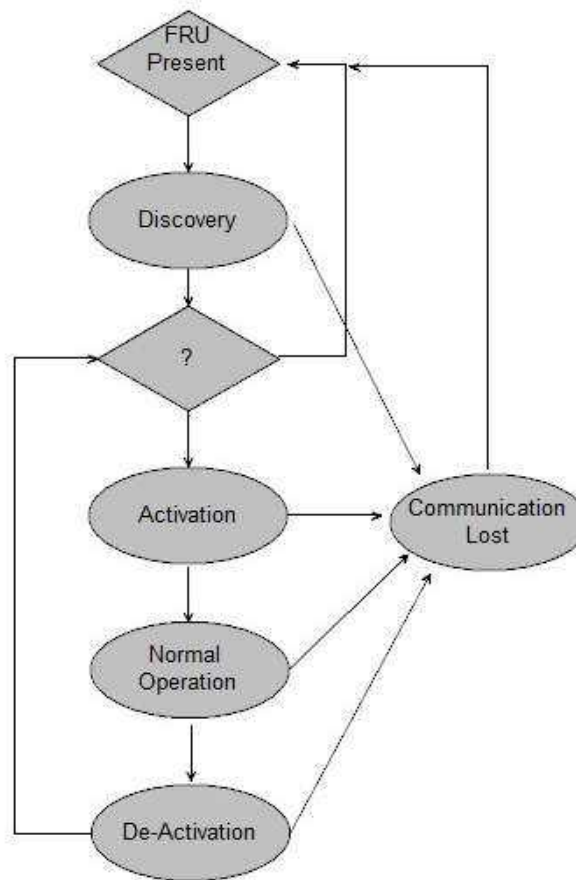


Illustration 8: FRU Management Diagram

The MCH checks operating parameters and decides if it needs to change a FRU's state:

- Presence: for AMCs and CUs, the presence is detected by the PM. The PM presence is detected by issuing a “Get Device Id” request and waiting for the response.
- Activation Criteria Met: Hot swap handle closed or MCH CLI *activate* command
- De-activation Criteria Met: Hot swap handle open or MCH CLI *deactivate* command
- Communication Failure: a number of consecutive IPMB request fail to receive a response

The management diagram is comprised of 5 distinct states:

- Discovery: FRU Information and Sensor data are read
- Activation: Payload Power is enabled and Ekey-ing is done
- Normal Operation: FRU IPMB operational status is checked by issuing an IPMB request from time to time. If a number of consecutive messages fail to receive an answer, the state is changed to Communication Lost.
- De-Activation: Payload Power is disabled

- Communication Lost: IPMB communication status is re-checked from time to time by issuing an IPMB request. If Communication is restore the FRU exists the current state and the process is restarted.

8 Command Line Interface (CLI)

The Command Line Interface (short-form: CLI) is available via the USB interface. The user can read or newly configure and save system parameters via the CLI. Access is divided into 2 profiles and is password-protected.

“user” profile:

System parameters can only be read in this profile – the exception to this write-protect is the **lanconfig** command for setting the IP, subnet and gateway addresses.

“admin” profile:

Full access to all system parameters. All available CLI commands can be executed. To avoid possible damage or malfunctions, the access data for this profile must only be known to trained personnel with appropriate knowledge and competence relating to the system in which the MCH is used!

The profiles can be changed using **logout**.

8.1 Log-in

As soon as you have established a connection, you will be prompted to login.

Default access settings:

login: user
password: USER

login: admin
password: ADMIN



The passwords can be changed using “**passw**”.

8.2 Syntax directory

Syntax Rules:

- *syntax is case sensitive*
- *parameters in [..] are optional*
- *parameters in <.. > are numbers*

8.2.1 activate command

Syntax: activate amc | pm | cu | mcmc <site>

amc_site: 1..12

pm_site: 1..4

cu_site: 1..2

mcmc_site: 1..2

Description: activates the desired FRU.

Example:

```
%>activate amc 1
Done!
```

8.2.2 bpppc command

Syntax: bpppc

Description: back plane point to point connectivity: Displays a summary of the backplane AMC's connectivity. The Columns represent all the AMC's in the system and the rows represent all the ports of those FRUs.

Example:

```
%>bpppc
-----Backplane point to point connectivity-----

*Legend : 3M1A = Port 3 MCH 1 Fabric A
          5A10 = Port 5 AMC 10

AMC   1     2     3     4     5     6     7     8     9     10    11    12
-----
P0    0M1A  1M1A  2M1A  3M1A  4M1A  -     -     -     -     -     -     -
P1    -     -     -     -     -     -     -     -     -     -     -     -
P2    2A3    -     2A1  3A3    3A4    -     -     -     -     -     -     -
P3    -     -     2A4  2A5    -     -     -     -     -     -     -     -
P4    4A3    4A4    4A1  4A2    4M1D  -     -     -     -     -     -     -
P5    5A3    5A4    5A1  5A2    4M1E  -     -     -     -     -     -     -
P6    6A3    6A4    6A1  6A2    4M1F  -     -     -     -     -     -     -
P7    7A3    7A4    7A1  7A2    4M1G  -     -     -     -     -     -     -
P8    -     -     -     -     -     -     -     -     -     -     -     -
P9    -     -     -     -     -     -     -     -     -     -     -     -
P10   -     -     -     -     -     -     -     -     -     -     -     -
P11   -     -     -     -     -     -     -     -     -     -     -     -
P12   -     -     -     -     -     -     -     -     -     -     -     -
P13   -     -     -     -     -     -     -     -     -     -     -     -
P14   -     -     -     -     -     -     -     -     -     -     -     -
P15   -     -     -     -     -     -     -     -     -     -     -     -
P16   -     -     -     -     -     -     -     -     -     -     -     -
P17   -     -     -     -     -     -     -     -     -     -     -     -
P18   -     -     -     -     -     -     -     -     -     -     -     -
P19   -     -     -     -     -     -     -     -     -     -     -     -
P20   -     -     -     -     -     -     -     -     -     -     -     -
```

The highlighted info translates into : AMC 3 port 2 is linked to AMC 1 port 2.

8.2.3 carrieraddr command

Syntax: carrieraddr

Description: Displays the IPMB address of the Carrier.

Example:

```
%>carrieraddr
Carrier Address =0x82
```

8.2.4 channels command

Syntax: channels

Description: Displays information regarding the power status of each FRU in the system: PS1, MP, EN, PP. The command also displays information regarding the PMs in the system: PM's status(redundant,primary,not used), amount of used current, amount of available current.

The info is structured using a table. The lines represent the channels, and each of the columns has a different meaning:

PS1 : present

MP : management power

EN : enable

PP : payload power

Legend: “y” - asserted , “-” -not asserted.

Example:

```
%>channels
```

Channel	Device	Primary PM				Redundant PM				Current AMPs		
		No.	PS1	MP	EN	PP	No.	PS1	MP		EN	PP
1	MCMC 1	1	y	y	y	y	2	y	y	y	y	3.0
3	CU 1	1	y	y	y	y	2	y	y	y	y	2.0
5	AMC 1	-	-	-	-	-	-	-	-	-	-	-
6	AMC 2	1	y	y	y	y	2	y	y	y	y	5.0
7	AMC 3	-	-	-	-	-	-	-	-	-	-	-
8	AMC 4	-	-	-	-	-	-	-	-	-	-	-
9	AMC 5	-	-	-	-	-	-	-	-	-	-	-
10	AMC 6	-	-	-	-	-	-	-	-	-	-	-

PM no.	Status	Current [AMP]				Used			
		Capability	BP	Override	PM1	PM2	PM3	PM4	
1	Primary	25.0		50.0	10.0				
2	Redundant	25.0		50.0	10.0				

In this case channel 2 (CU1), is present (PS1 is asserted), receives management power, is enabled and receives payload power(MP1,EN and PP asserted); has a primary PM and a redundant PM assigned(PM1 -primary, PM2 -redundant), and has a current requirement of 2 Amps.

8.2.5 clock command

Syntax: clock [pcie en|di <amc_site> | all]

Description: Displays information regarding the clocking of the system. The command can enable/disable the clocks.

amc_site= 1..12

Example 1:

```
%>clock
```

```
-----
```

AMC No.	Clock PCIe	Status
1	ON	
2	ON	
3	OFF	
4	OFF	

```
-----
```



```
5 OFF
6 OFF
7 ON
8 ON
9 ON
10 OFF
11 OFF
12 OFF
```

Example 2:

```
%>clock pcie en 3
Done!
```

8.2.6 cu command

Syntax: `cu [<cu_site> (fanlevel shutdown | <level_value>) | (local_control on|off) [rear]]`

cu_site: 1..2

level_value:1..15

Description: Displays or configure the Cooling Units operation. The command displays minimum and maximum fan levels, the normal operating fan level and the current fan level. The command supports front and rear fans according to MTCA.4.

Example1: get cu status

```
%>cu
-----Cooling Status-----
                Local Control          Fan Levels
Device Instance  State   Level  Override Normal Min Max
-----
CU 1              Off     10     3         1    15
```

Example2: set rear fan level in a MTCA.4 chassis

```
%>cu 1 fanlevel 10 rear
Set fan level req sent!
Command acknowledged!
```

8.2.7 date command

Syntax: `date [dd.mm.yyyy]`

Description: Displays or set the RTC Date. The command is available only when the RTC is enabled. (check out the define command)

Example1: get date

```
%>date

Date [dd.mm.yyyy] = 10.12.2014
```

8.2.8 deactivate command

Syntax: `deactivate amc | pm | cu | mcmc <site>`

amc_site: 1..12

pm_site: 1..4

cu_site: 1..2

mcmc_site: 1..2

Description: Deactivates the desired FRU.

Example:

```
%>deactivate amc 5
Done!
```

8.2.9 define command

Syntax: `define` (quiesced timeout [*<t_value>*]) |
 (startup_power_policy [*<sp_value>*]) |
 (unmanaged_channels [*<hex_val>*]) |
 (rtc [en | di]) |
 (upstream_delay [custom | default])

t_value: 0..655 (seconds)

sp_value: 0..1

hex_value: hexadecimal value

Description: Displays or configures various parameters:

- *quiesced timeout*: After sending a **FRU control (Quiesce)** command to a FRU, the MCH waits for the FRU to enter the Quiesced state. After the *quiesced timeout* expires, the MCH proceeds to disabling the Payload Power for the FRU even if the Quiesced state was not reached. The default timeout value is 60 seconds.
- *start-up_power_policy*: this parameter defines the behavior for the MCH power up PM assign process in case the channels that receive autonomous PP (MCH1, MCH2, CU1, CU2) are not powered by the PM specified in the Carrier FRU File. The start-up PM will be changed for those channels and there are 2 options for the switch:
 - 0 – the autonomous channels that were not enabled by the Carrier FRU designated PM are disabled and re-enabled on the required PM
 - 1 – the autonomous channels that were not enabled by the Carrier FRU designated PM are not disabled but they are moved to the same PM that will also provide power for the primary MCH.
- *unmanaged_channels*: this parameter defines a set of channels that will not be managed by the MCH. This means that the MCH will not control MP,EN# and PP signals assertion or deassertion for the respective channel. The *hex_val* parameter is a hexadecimal representation of the power channels with channel x being represented by (0x01 << (x - 1)). The power signals for the unmanaged channels are controlled using the **turn** command.
- RTC : enabled | disabled the real time clock

All parameters changed by this command will be active at the next power on, if the environment changes are saved using the **saveenv** command.

Example1: set the quiesced timeout to 120 seconds

```
%>define quiesced timeout 120
Done! The new value will be active at the next startup if you saveenv!
```

Example2: change the start-up_power_policy

```
%>define startup_power_policy 1
Done! The new value will be active at the next startup if you saveenv!
```

Example3: define AMC 5 – channel 9 as unmanaged

```
%>define unmanaged_channels 0x0100
Done! The new value will be active at the next startup if you saveenv!
Unmanaged Channels: 0x0100
```

8.2.10 devices command

Syntax: `devices`

Description: Displays the string used by the web page to identify board pictures

Example1:

```
%>devices
MCMC1 ID07010SMW02C111
PM4 ID07010P07-003
CU1 ID07010031-088
CU2 ID07010031-088
AMC1 ID03A9813
```

8.2.11 ekey command**Syntax:** ekey**Description:** Displays a summary of the E-Keying process.**Example:**

```
%>ekey
                        Ekeying Summary
-----
AMC  Ports      Partner  Ports      Type
-----
AMC2  0             MCH1    F-A 2      Ethernet 1000Base-BX
AMC2  1             MCH1    F-A 8      Ethernet 1000Base-BX
AMC2  2             AMC4     2         Storage SATA
AMC4  2             AMC2     2         Storage SATA
```

8.2.12 fru command**Syntax:** fru**Description:** Displays the active devices (PMs,AMCs and CUs) and their operational states. The command also displays the FRU's name(if available).

For MCHs equipped with PCIe the command displays a warning for boards that have booted after the CPU (PCIe upstream port) is operational. The Late Boot Warning is marked by a star in the Address column.

Example 1:

```
%>fru
----- FRU Summary -----
Address FRU   Device State Prev Reason      Name
-----
0x10   0x00 MCMC1    M4    M3 Normal Change    MCMC
0xA8   0x00 CU1      M4    M3 Normal Change    Cooling Unit
0xAA   0x00 CU2      M4    M3 Normal Change    Cooling Unit
0x72   0x00 AMC1     M4    M3 Normal Change    A2:AM4011
0x76   0x00 AMC3     M4    M3 Normal Change    AMC-S302-80G
0x80   0x00 AMC8     M4    M3 Normal Change    AMC Test Card
0xC8   0x00 PM4      M4    M3 Normal Change    PDM
```

Example 2: PCIe MCH with AMC8 booting late (booting after the upstream port has become operational)

```
%>fru
----- FRU Summary -----
Address FRU   Device State Prev Reason      Name
-----
0x10   0x00 MCMC1    M4    M3 Normal Change    MCMC
0xA8   0x00 CU1      M4    M3 Normal Change    Cooling Unit
0xAA   0x00 CU2      M4    M3 Normal Change    Cooling Unit
0x72   0x00 AMC1     M4    M3 Normal Change    A2:AM4011
*0x80  0x00 AMC8     M4    M3 Normal Change    AMC Test Card
0xC8   0x00 PM4      M4    M3 Normal Change    PDM
```

8.2.13 frubuffer command

Syntax: frubuffer

Description: Displays the raw fru info for all the FRUs in the system. The FRUs are identified by their IPMB address.

Example:

```
%>frubuffer
Device: 0xFD
FRU ID: 0x00
FRU file Length: 938
Buffer Length: 948
01 00 01 04 11 1C 00 CD 01 03 01 C7 30 33 37 2D
.....
Device: 0xFE
FRU ID: 0x00
FRU file Length: 318
Buffer Length: 328
01 00 01 04 11 1C 00 CD 01 03 01 C7 30 33 37 2D
.....
Device: 0xC2
FRU ID: 0x00
FRU file Length: 20
Buffer Length: 28
01 00 00 00 00 01 00 FE C0 82 07 54 63 5A 31 00
.....
Device: 0x10
FRU ID: 0x00
FRU file Length: 876
Buffer Length: 884
01 00 00 01 05 0A 00 EF 01 04 19 40 6B 81 C6 53
.....
Device: 0xA8
FRU ID: 0x00
FRU file Length: 19
Buffer Length: 28
01 00 00 00 00 01 00 FE C0 82 06 4B 6D 5A 31 00
.....
Device: Free Area
FRU ID: 0xFF
FRU file Length: 48748
Buffer Length: 48756
```

8.2.14 fruinfo command

Syntax: fruinfo (amc|cu|pm|mcmc site) | carrier | shelf | <IPMB Address>

Description: Parses the FRU Information File for the desired device

Example:

```
%>fruinfo amc 2

INTERNAL USE AREA
  Internal Use Area missing

BOARD INFO AREA
  Board Manufacturer: Generic Manufacturer
  Board Product Name: AMC 1
  Board Serial Number: 000999
  Board Part Number:  A9876

PRODUCT INFO AREA
  Manufacturer Name: Generic Manufacturer
```

Product Name: AMC test card
 Model Number: AMC7865
 Product Version: Rev. B
 Product Serial Number: 000999

MULTIRECORD AREA

Module Current Requirement
 Amp=3.0

AMC P-P Connectivity
 AMC Record Type

ChID:0 Lane0:P0 Lane1:- Lane2:- Lane3:-
 ChID:1 Lane0:P4 Lane1:P5 Lane2:P6 Lane3:P7

Link:0	ChID:0	L0		Eth 1000Base-BX	Asym. Match = 0	Gr. Id = 0
Link:1	ChID:1	L0 L1 L2 L3	PCIe Gen2		Asym. Match = 2	Gr. Id = 0
Link:2	ChID:1	L0	PCIe Gen2		Asym. Match = 2	Gr. Id = 0
Link:3	ChID:1	L0 L1 L2 L3	PCIe Gen1		Asym. Match = 2	Gr. Id = 0
Link:4	ChID:1	L0	PCIe Gen1		Asym. Match = 2	Gr. Id = 0

8.2.15 gbe_status command

Syntax: gbe_status

Description: displays the connection status and parameters for all the GbE links connected to the on-board GbE switch.

Example:

```
%>gbe_status
```

```
-----GbE Links Status-----
Link-----State-----Type-----Speed-----Duplex-----
AMC 1      Link Down
AMC 2      Link Up          SerDes      1 Gbs      Full
AMC 3      Link Down
AMC 4      Link Down
AMC 5      Link Down
AMC 6      Link Up          SerDes      1 Gbs      Full
AMC 7      Link Up          SerDes      1 Gbs      Full
AMC 8      Link Down
AMC 9      Link Down
AMC 10     Link Down
AMC 11     Link Down
AMC 12     Link Down
Uplink 1   Link Down
Uplink 2   Link Up          SGMII      100 Mbs    Full
```

8.2.16 get_iua command

Syntax: get_iua amc <site>

site:1..12

Description: reads the Internal Use Area of the FRU file for an AMC

Example:

```
%>get_iua amc 3
```

```
AMC 3 FRU File Internal Use Area
Area length:56 Bytes
```

```
0x01 0x07 0x03 0x04 0x05 0x06 0x07 0x08
```

```
0x09 0x0A 0x0B 0x0C 0x0D 0x0E 0x0F 0x00
0xFF 0xFF 0xFF 0xFF 0xFF 0xFF 0xFF 0xFF
0xFF 0xFF 0xFF 0xFF 0xFF 0xFF 0xFF 0xFF
0xFF 0xFF 0xFF 0xFF 0xFF 0xFF 0xFF 0xFF
0x11 0x11 0x11 0x11 0x11 0x11 0x11 0x11
0x11 0x11 0x11 0x11 0x11 0x11 0x11 0x11
```

8.2.17

8.2.18 help command

Syntax: help [-v]

Description: Displays a list of all the available CLI commands. If the command is used with the verbose parameter (-v), a short description and an example are displayed for each supported CLI command.

8.2.19 info command

Syntax: info amc|pm|cu|mcmc <site>

```
amc site    = 1..12
pm site     = 1..4
cu site     = 1..2
mcmc site   = 1..2
```

Description: Parses the information returned by the response for a Get Device ID request: Device ID, Firmware version, IPMI version, Manufacturer ID, Product ID.

Example:

```
%>info amc 2
```

```
Name: AMC Test Card
Device ID: 0x01
Device provides SDRs
Device Revision: 1
Device Available: Normal Operation
Firmware Revision: 3.0
IPMI Version: 1.5
Additional Device Support:
  IPMB Event Generator
  FRU Inventory Device
  Sensor Device
Manufacturer ID: 28688d = 07010h
Product ID: 0x0100
```

8.2.20 lanconfig - command

Syntax: lanconfig [dhcp [on|off]] | [local [on|off]] |
 [savelocaltofru] | [settings] |
 [ip | mask | gateway [<address>]]

Description: Readout or setup for the network parameters.

- **no parameter used** – the command returns current IP, mask and gateway addresses of the LAN interface
- **settings** – shows the configuration of the LAN interface: the state of all parameters and addresses
- **savelocaltofru** – saves the local addresses in the Carrier Manager IP Link record on the Backplane Carrier FRU EEPROM.
- **dhcp [on|off]** – enables or disables the DHCP. **The local mode has to be turned on in order to use DHCP.**
- **local [on|off]** – enables or disables the local LAN interface settings

- **ip | mask | gateway [address]** – set or print the local addresses

Depending on the state of the *local* and *dhcp* lanconfig parameters one of the 3 LAN parameter sets is used:

- addresses from the Carrier Manager IP Link FRU Record in the Carrier FRU Information File
- local addresses
- dhcp addresses

LAN addresses defined by	<i>local</i>	<i>dhcp</i>
Carrier Manager IP Link Record	off	off
Local addresses	on	off
DHCP	on	on

Table 3: LAN addresses selection table

At startup the MCH checks if the *local* configuration is on or off. If it is off, the LAN addresses are read from the Carrier Manager IP Link FRU record. If this record is missing or the addresses are not specified (value 0.0.0.0) the local set is used.

Depending on the *dhcp* parameter, the local address or the ones obtained using DHCP are used.

! After a parameter is modified, the change must be saved with **saveenv** and the MCH has to be restarted (**reboot** command) before the change becomes effective.

Example1: Readout of current LAN addresses

```
%>lanconfig
DHCP Configuration
  IP=172.16.14.13
  Mask=255.255.255.0
  Gateway=172.16.14.201
```

Example2: Readout of all the lanconfig parameters

```
%>lanconfig settings
FRU Info IP=0.0.0.0
FRU Info Mask=0.0.0.0
FRU Info Gateway=0.0.0.0
DHCP =On
Local Configuration =On
  Local IP=192.168.16.17
  Local Mask=255.255.255.0
  Local Gateway=172.21.35.211
```

Example3: Changing the local IP address

```
%>lanconfig ip 172.16.14.18
Local IP=172.16.14.18
```

Example4: Enabling the local LAN settings

```
%>lanconfig local on
LAN configured by local settings: on
```

8.2.21 links command

Syntax: **links amc <site>**
site : 1..12

Description: Displays a list of all the links defined in the AMC Point to Point Records of the FRU Information File of the desired AMC. For every link the command displays:

- the link type
- the ports it uses
- the link's grouping id field
- the link's asymmetric match field
- the links status: enabled,disabled,waiting enable,waiting disable
- partner

Example:

```
%>links amc 2
```

AMC 2									
No	Link Type	Ports	Gr. Id	As. Match	Status	Partner			
0	Ethernet 1000Base-BX	0	0x00	0x00	Enabled	MCH1	F-A	2	
1	Ethernet 1000Base-BX	1	0x00	0x00	Enabled	MCH1	F-A	8	
2	Storage SATA	2	0x00	0x02	Enabled	AMC4	2		
3	Storage SATA	3	0x00	0x02	Disabled				
4	PCI Express Gen1-SSC	4 5 6 7	0x00	0x02	Disabled				
5	PCI Express Gen1	4 5 6 7	0x00	0x02	Disabled				
6	PCI Express Gen1-SSC	4	0x00	0x02	Disabled				
7	PCI Express Gen1	4	0x00	0x02	Disabled				

In this example AMC 2 has 3 enabled links: two connected to the MCH fabric A port 2 and 8 and one connected to AMC 4 port 2.

8.2.22 logout command

Syntax: logout

Description: Logs out the current user.

Example:

```
%>logout
login:
```

8.2.23 passw command

Syntax: passw

Description: Changes the password for the current user

Examples:

```
%>passw
Enter Old password:****
Enter new password:****
Use saveenv command before reboot for the change to be successful!
```

8.2.24 pcie command

Syntax: pcie [(upstream [vs<x>] [port <p_no>]) |
 (timeout [<time_val>]) |
 (vs<x> <port_list>)]

vs<x>: vs0,vs1..vs5

p_no:0..11

time_val:1..255

port_list: 0,1,2..11

Description: Displays the status of all PCIe links connected to the on-board switch.
 Displays or changes the upstream port for any of the virtual switches.
 Displays or changes the timeout for the start-up of the upstream ports.
 Displays or changes the ports contained by any virtual switch.

Example 1: PCIe link status

```
%>pcie
```

```
-----
```

Link	Virtual Switch	Port	Type	PCIe Links State	Speed	Width	Status	Clock
PORT 0	VS0	Upstream		Link Up	Gen 1	x4		ON
PORT 1	VS0	Downstream		Link Up	Gen 1	x1		ON
PORT 2	VS1	Upstream		Link Down				OFF
PORT 3	VS1	Downstream		Link Down				OFF
PORT 4	VS2	Upstream		Link Up	Gen 3	x4		ON
PORT 5	VS2	Downstream		Link Up	Gen 3	x4		ON
PORT 6	VS3	Upstream		Link Down				OFF
PORT 7	VS3	Downstream		Link Down				OFF
PORT 8	VS3	Downstream		Link Down				OFF
PORT 9	VS3	Downstream		Link Down				OFF
PORT 10	VS3	Downstream		Link Up	Gen 3	x4		ON
PORT 11	VS3	Downstream		Link Down				OFF

Example 2: Set Port 4 as the upstream port for vs0 (by default all ports are in vs0)

```
%>pcie upstream port 4
Operation successful! To validate the change use saveenv!
The Upstream port change will be active at the next power on!
PCIe VS0 Upstream port: 4
```

Example 3: Set Port 6 as the upstream port for vs3(Port 6 belongs to vs3)

```
%>pcie upstream vs3 port 6
Operation successful! To validate the change use saveenv!
The Upstream port change will be active at the next power on!
PCIe VS3 Upstream port: 6
```

Example 4: assign ports 6,7,8,9,10,11 to vs3

```
%>pcie vs3 6 7 8 9 10 11
Operation successful! To validate the change use saveenv!
The Virtual Switch port change will be active at the next power on!
```

Example5: Set 30 seconds upstream port start-up up delay

```
%>pcie timeout 30
Operation successful! To validate the change use saveenv!
PCIe Upstream port bring-up timeout: 30 sec
```

8.2.25 reboot command

Syntax: reboot

Description: Restarts the MCH.

Examples:

```
%>reboot
```

```
Bootloader Version 1.7M
Press x to stop bootloader in: 0 Expired!
Running main program..ÿ
```

8.2.26 reset command

Syntax: reset warm|cold amc|cu <site>
 amc_site:1..12
 cu_site:1..2

Description: Performs a warm or cold reset of the desired AMC or CU.

Example:

```
%>reset warm amc 3
Done!
```

8.2.27 restore command

Syntax: restore

Description: Restores all parameters to the default values. For the restore to be complete a reboot is necessary.

Example:

```
%>restore
Restored to default!
```

8.2.28 saveenv command

Syntax: saveenv

Description: Saves the changes that have been made to the parameters. If the modified parameters aren't saved, they will be lost after reboot.

Examples:

```
%>saveenv
User Settings saved!
```

8.2.29 sel command

Syntax: sel count | print [<start_record> [<end_record>]]

Description: Displays the Sensor Event Log record count, or prints SEL records.

If the *start_record* parameter is used, the command starts to display records starting with this record number, otherwise it starts with the first available record.

If the *end_record* parameter is used, the command stops displaying records when it reaches this record number, otherwise it prints all available records.

Example1: Getting the SEL records count

```
%>sel count
The SEL has 10083 records
```

Example2: Display SEL records

```
%>sel print 10004 10010
```

```
-----
```

Sensor Event Log											
Rec.ID.	Uptime	Owner	Sensor	Name				Dir	Data1	Data2	Data3
			Id	LUN No.	type			St	PrSt	Fru	Id
					0xF0			Dir	Thr	Value	Thr_Value
					Thr						
0x2714	19	0x10	0	1	0xF2	Hot Swap		Handle	Closed		
0x2715	20	0xC2	0	4	0xF3	PDM Events	As	0xA0	0x07	0x1B	
0x2716	21	0xC2	0	4	0xF3	PDM Events	As	0xA1	0x5B	0x01	

```
-----
```

```

0x2717 22          0xC2 0 4          0xF3 PDM Events As 0xA1 0x1B 0x03
0x2718 22          0xC2 0 4          0xF3 PDM Events As 0xA1 0x01 0x06
0x2719 22          0x10 0 1          0xF2 Hot Swap      Handle Closed

```

8.2.30 scispeed command

Syntax: `scispeed 9600 | 19200 | 38400`

Description: Changes the baud rate at which the CLI for the MCH and the bootloader framework operate. For the change to become valid the environment has to be saved using CLI command *saveenv* and the MCH has to be rebooted(*reboot* command)

Example:

```

%>scispeed 38400
Baud rate changed to 38400.Save Environment and reboot.

```

8.2.31 sdr command

Syntax: `sdr amc | pm | cu | mcmc <site>`

```

amc site = 1..12
pm site = 1..4
cu site = 1..2
mcmc site = 1..2

```

Description: Displays the raw sdrs for the requested device. The start of a new sdr if marked with * so it is easier to find a particular record. If you want a parsing of the sdr data you should use the *sensor* command.

Example:

```

%>sdr amc 2
AMC 2 SDRs Number:9
*00 00 51 12 18 00 00 00 29 00 00 00 C1 62 00 CD
41 4D 43 20 54 65 73 74 20 43 61 72 64
*01 00 51 01 33 00 00 01 C1 62 03 42 F2 6F 1F 00
1F 00 1F 00 00 00 00 00 00 00 00 00 00 00 00 00
00 00 00 00 00 00 00 00 00 00 00 00 00 00 C8
48 6F 74 20 53 77 61 70
*02 00 51 01 30 00 00 02 C1 63 03 E8 01 01 00 02
00 22 10 10 00 01 00 00 01 00 EB C0 00 00 00 00
00 00 FF 01 FF 4C 4C 00 00 00 01 01 00 00 00 C5
54 65 6D 70 31
*03 00 51 01 30 00 00 03 C1 63 03 E8 01 01 00 02
00 22 10 10 00 01 00 00 01 00 EB C0 00 00 00 00
00 00 FF 01 FF 4C 4C 00 00 00 01 01 00 00 00 C5
54 65 6D 70 32
*06 00 51 01 2D 00 00 06 C1 62 03 E9 02 01 04 22
04 22 12 00 00 04 00 00 C4 00 00 00 00 C0 00 00
00 00 FF 00 FF BA BA 00 97 97 02 02 00 00 00 C2
4D 50
*07 00 51 01 2D 00 00 07 C1 62 03 E9 02 01 04 22
04 22 12 00 00 04 00 00 41 00 00 00 00 D0 00 00
00 00 FF 00 FF D8 D8 00 9A 9A 02 02 00 00 00 C2
50 50
*08 00 51 01 30 00 00 08 C1 62 03 E9 02 01 04 22
04 22 12 00 00 04 00 00 C4 00 00 00 00 C0 00 00
00 00 FF 00 FF BA BA 00 97 97 02 02 00 00 00 C5
2B 33 2E 33 56
*09 00 51 01 30 00 00 09 C1 62 03 E9 02 01 04 22
04 22 12 00 00 04 00 00 62 00 00 00 00 C0 00 00
00 00 FF 00 FF 85 85 00 71 71 02 02 00 00 00 C5
2B 31 2E 32 56
*0A 00 51 01 39 00 00 0A C1 62 03 E9 02 01 04 22
00 20 12 00 00 00 00 00 27 00 5F 00 00 D3 00 00

```

```
00 00 FF 00 FF 83 83 00 7D 7D 01 01 00 00 00 CE
50 43 49 65 20 43 6C 6F 63 6B 20 4D 48 7A
```

8.2.32 sendipmb command

Syntax: `sendipmb <ipmb_address> <net_Fn/rs_lun> <cmd> [<req_data>]`

Description: Sends a raw IPMI command via the IPMB.

Example1: App req for PM1, Get Device ID

```
%>sendipmb 0xC2 0x18 0x01
Command sent! Waiting for reply!
CC Ok.Response: 0x01 0x82 0x02 0x09 0x51 0x29 0x10 0x70 0x00 0x00 0x06
```

8.2.33 sensor command

Syntax: `sensor <device> [<sensor_no> [-v | (threshold <th_code> <th_value>)]`
device = (amc|cu|pm|mcmc <site>) | carrier | <ipmb_address>
th_code = unr | uc | unc | lnc | lc | lnr

Description: Parses sdr info for all the sensors, or a particular one, of the requested FRU and displays info. The command displays sensor information in a user friendly manner and can also be used to set one of the sensor's thresholds.

Example1: Read sensors for AMC 8

```
%>sensor amc 8
-----Sensor List-----
*legend:
Disc -> discrete
Thr  -> threshold
l    -> lower
u    -> upper
c    -> critical
nc   -> non-critical
nr   -> non-recoverable
-no--Device-----Type---Value--Unit-----State-----Name-----
*1  AMC 8          Disc   H. Closed,      Hot Swap Handle
*2  AMC 8          Thr    3.33   V             Ok      AN0 VCC
*3  AMC 8          Thr    12.10  V             Ok      AN1 +12V
*4  AMC 8          Thr    0.00   V             Ok      AN2
*5  AMC 8          Thr    0.00   V             Ok      AN3
*6  AMC 8          Thr    0.00   V             Ok      AN4
*7  AMC 8          Thr    0.01   V             Ok      AN5
*8  AMC 8          Thr    0.00   V             Ok      AN6
*9  AMC 8          Thr    0.00   V             Ok      AN7
*10 AMC 8          Thr    25.00  deg C        Ok      Temp1
*11 AMC 8          Thr    26.00  deg C        Ok      Temp2
*12 AMC 8          Thr    27.00  deg C        Ok      Temp3 LM86
*32 AMC 8          Disc                    0x0001    GPIO1
*33 AMC 8          Disc                    0x0001    GPIO2
*34 AMC 8          Disc                    0x0001    GPIO3
*35 AMC 8          Disc                    0x0001    GPIO4
```

For every sensor the following info is displayed:

- sensor number
- sensor type: discrete, threshold
- value if it can be parsed (otherwise a raw value will be displayed)
- measuring unit if available
- current status : **Ok**; limit infringement : lower non-critical (**lnc**), lower critical(**lc**), lower non-

recoverable(**lnr**), upper non-critical(**unc**), upper critical(**uc**), upper non-recoverable (**unr**)

- name (if available)

Example2: Change the Upper Non Critical Threshold for sensor 11 of AMC 1

```
%>sensor amc 1 11 threshold unc 38
Set sensor Threshold Request sent!
Request Acknowledged!
Get sensor Thresholds Request sent!
Threshold Change Successful!
New Threshold: 38.00
```

8.2.34 sysreboot command

Syntax: **sysreboot** [*<timeout>*]
timeout: 0..255 (seconds)

Description: Performs a system shutdown, and reboot after the timeout expires.

Example1:

```
%>sysreboot 10
System will reboot...
Reboot Timeout:10 seconds
Waiting for AMCs shutdown..Please Wait..
All AMC have been Turned Off!
System will reboot in: 0
Reboot Complete!
```

8.2.35 tftp command

Syntax: **tftp** firmware|web <ip_address> <file_name>
ip_address : the IP address on which the tftp server resides

Description: Updates the firmware or web page using tftp.

8.2.36 time command

Syntax: **time** [hh:mm:ss]

Description: Displays or set the RTC Time. The command is available only when the RTC is enabled. (check out the define command)

Example 1: get time

```
%>time

Time [hh:mm:ss] = 13:12:45
```

Example 2: set time

```
%>time 14:30:00
Done!
```

8.2.37 turn command

Syntax: **turn** <channel_no> mp|en|pp on|off
channels_no: 1..16

Description: Controls the power signal for unmanaged channels. To define the unmanaged channels use the *define* command.

Example1: define AMC 2 as unmanaged, and turn mp on

```
%>define unmanaged_channels 0x0020
```

```

Done! The new value will be active at the next startup if you saveenv!
Un-Managed Channels: 0x0020
%>saveenv
.....
%>reboot
.....
%>turn 6 mp on
Done!

```

8.2.38 uptime command

Syntax: uptime

Description: Displays the amount of time that has passed since the last reboot.

Example1:

```

%>uptime
Uptime=0 days 02:57:03

```

8.2.39 version command

Syntax: version

Description: Displays information about the MCH hardware and software.

Example1:

```

%>version

Samway MCH
PN: P07-009
Software Version:2.3
MAC Address: 00:50:C2:F2:50:3C
SN: 04022014
Assembly: Base Board
          Clock Distribution Tongue
          PCIe Tongue - PEX 8748
MCH Status : PRIMARY

```

8.2.40 xmodem command

Syntax: xmodem carrierfru | usersettings | fru | sdr | web

Functions:

Receives the FRU Information File for the carrier, the usersettings, the SDR, the FRU information file, or the web page for the MCH. After the command is entered, the MCH goes into data receive mode and waits for the data. At this point you can start the file transfer with your terminal program and select XMODEM as the protocol.



When using "xmodem" in "Hyperterminal" the transfer of the desired file can take up to 10 seconds to start.

Example:

```

%>xmodem sdr
Please upload the file...
%>...Done!

```

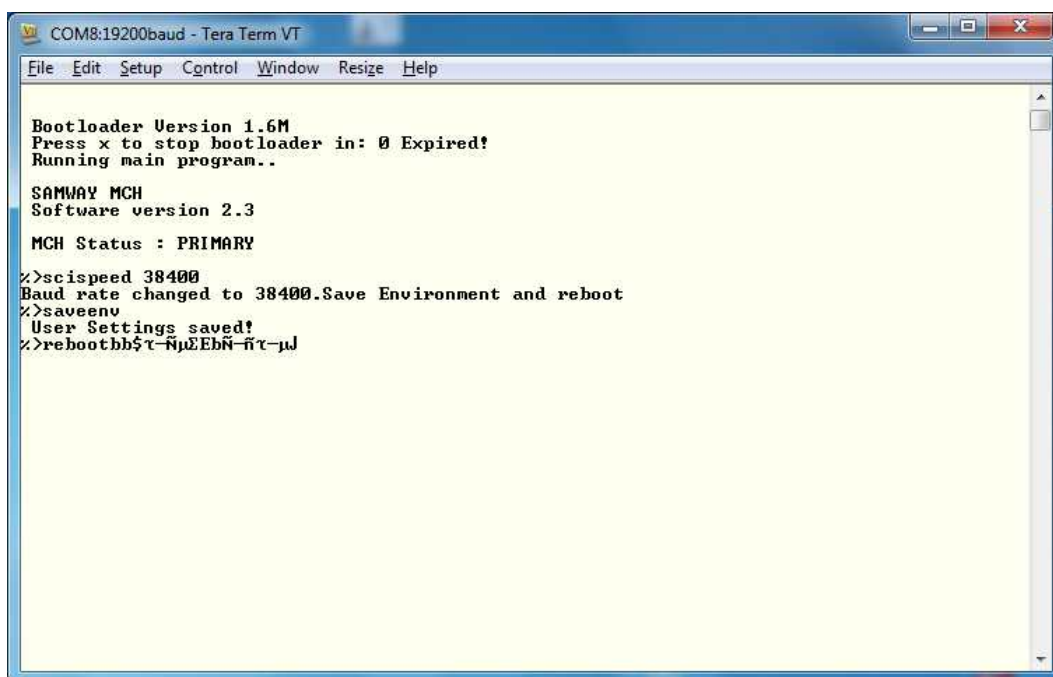

9 Updating the Firmware

The Firmware of the MCH can be updated either locally using an USB cable and the CLI interface, either remotely over LAN using tftp.

9.1 Local Firmware Update

When updating the firmware locally the Xmodem protocol will be used to send over the file. In order to minimize the upload time we suggest to increase the CLI baud rate to the maximum value (38400) before starting the process. This is accomplished using the command **scispeed** with 38400 as a parameter. The baud rate change will become effective at the next restart if the environment is saved using **saveenv**.

The baud rate change is not mandatory, but it will influence the upload time, so we recommend it.



```

COM8:19200baud - Tera Term VT
File Edit Setup Control Window Resize Help

Bootloader Version 1.6M
Press x to stop bootloader in: 0 Expired!
Running main program..

SAMWAY MCH
Software version 2.3

MCH Status : PRIMARY

%>scispeed 38400
Baud rate changed to 38400.Save Environment and reboot
%>saveenv
User Settings saved!
%>reboot

```

Illustration 9: Change CLI Baud Rate using scispeed command

At this point you will have to adapt the baud rate of the terminal software to the new settings of the MCH.

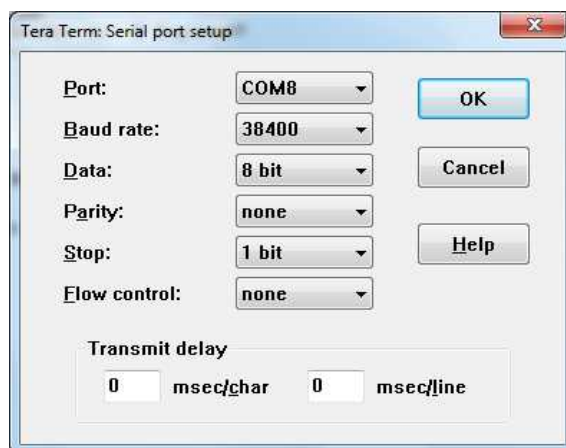


Illustration 10: New Terminal Settings

The firmware is updated using the on-board bootloader. To access the bootloader, “x” must be pressed before the initial timeout of 3 seconds expires.

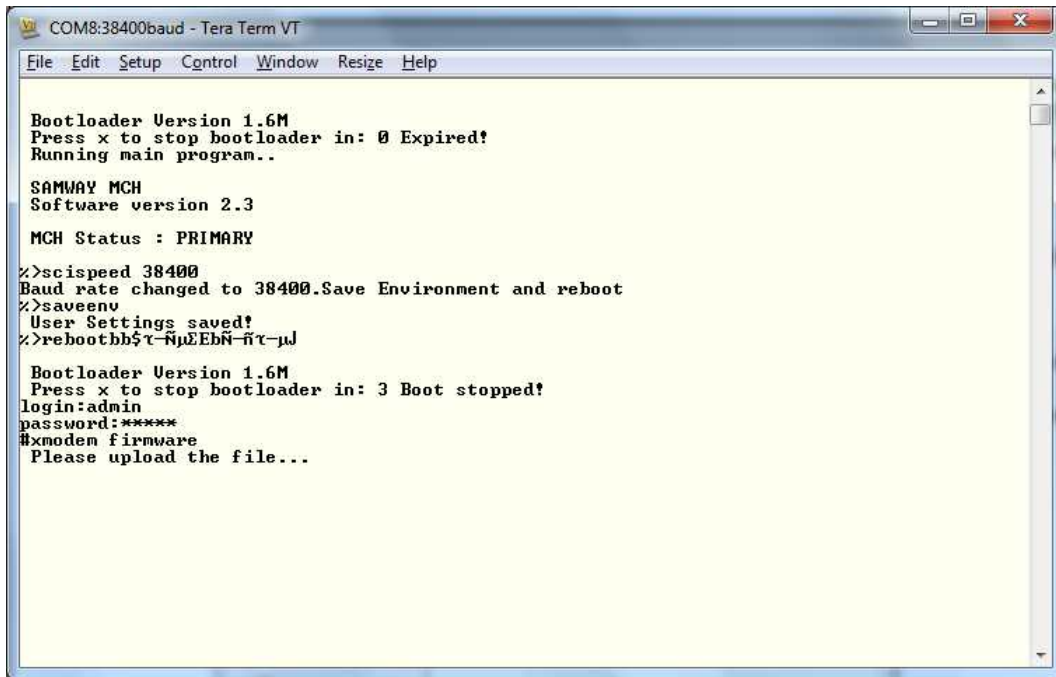
After the bootloader is stopped, an admin login is required. The default credentials for the admin profile are:

login:admin

password: ADMIN

The default password can be changed using the **passw** command, so in order to login successfully you may be required to enter the new password if the default one was changed.

After login the firmware file (*.firm) is uploaded using xmodem. To start the upload process use *xmodem firmware*.



```
COM8:38400baud - Tera Term VT
File Edit Setup Control Window Resize Help

Bootloader Version 1.6M
Press x to stop bootloader in: 0 Expired!
Running main program..

SAMWAY MCH
Software version 2.3

MCH Status : PRIMARY

z>scispeed 38400
Baud rate changed to 38400.Save Environment and reboot
z>saveenv
User Settings saved!
z>rebootbb$τ-NμEbn-ñτ-μ

Bootloader Version 1.6M
Press x to stop bootloader in: 3 Boot stopped!
login:admin
password:*****
#xmodem firmware
Please upload the file...
```

Illustration 11: Local Firmware Update example

At this point you will have to send the firmware file using the terminal software.

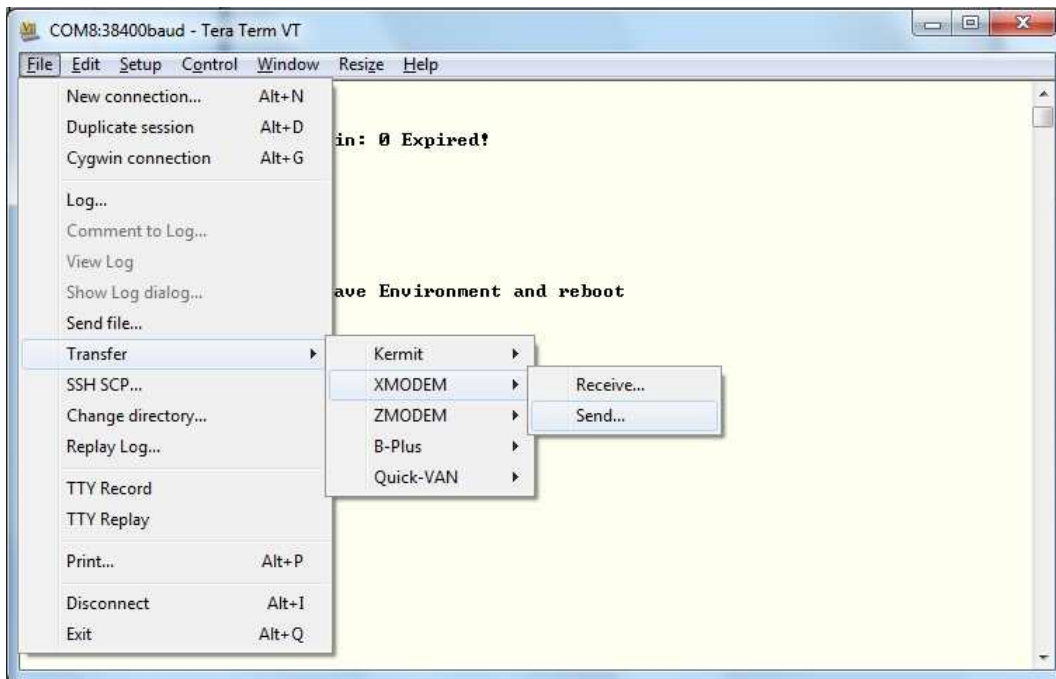


Illustration 12: TeraTerm xmodem send transfer

When the transfer is complete, a confirmation message is displayed. The new firmware can be started using the **run** command.

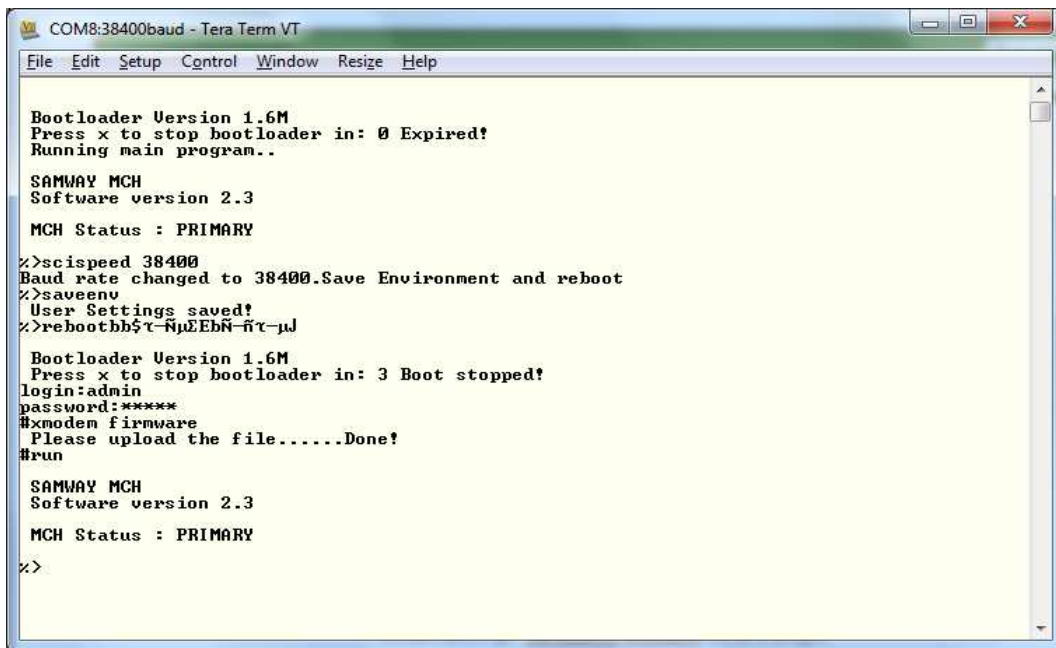


Illustration 13: Firmware Update example

After the update is complete, the baud rate can be changed back to the previous value using **scispeed** and **saveenv**.

10 Restore to factory defaults

Only an admin can perform a system restore. In order to restore all parameters to their default value the following steps need to be followed:

- Login using the admin account (for more details refer to [5. Command Line Interface \(CLI\)](#))
- Use the `restore` command

! When using restore the MCH disregards all the changes applied to the User Settings and uses the default values for all these parameters. These predetermined values are embedded in the firmware.

For Custom MCHs these default firmware parameters may be different then the ones loaded on the MCH when it was shipped out.

To go back to a particular setup you have to use xmodem usersettings, and upload a Configuration file that contains the required setup.